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Confidence Intervals for an Exponential Parameter from a Two Stage Life Test

by

Kenneth B. Fairbanks

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Confidence Intervals for an Exponential Parameter from a Two Stage Life Test

by

Kenneth B. Fairbanks*
University of Missouri - Columbia

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Confidence Intervals for an Exponential Parameter from a Two Stage Life Test

Abstract

Theta

The two stage life test of Bulgren and Hewett (1973) for the mean lifetime, θ , of an exponentially distributed lifetime is essentially a two stage version of type II censoring. Since the test decision only determines whether θ is above or below θ_{\emptyset} , it may be of interest to estimate θ following the decision using the test data. Epstein (1960a) found confidence intervals for under type II censoring. This report shows that Epstein's intervals may be modified slightly and used to provide confidence intervals for θ following the two stage test. The resulting confidence intervals are shown to be conservative.

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Theta

Confidence Intervals for an Exponential

Parameter from a Two Stage Life Test

I. Introduction.

In the theory of reliability and life testing, a lifetime τ is often assumed to have an exponential distribution. Thus the probability density function of τ may be expressed as

$$f(\tau;\theta) = \begin{cases} \frac{1}{\theta} e^{-\tau/\theta} & \text{if } \tau \ge 0 \\ 0 & \text{elsewhere} \end{cases}$$
 (1.1)

where $\theta > 0$ is the expected lifetime.

In a life test with type II censoring, n items are placed on test and observed for failures until the $r_0^{\ th}$ failure occurs. Properties of this test were given by Epstein and Sobel (1953). Bulgren and Hewett (1973) developed a two stage version of a life test with type II censoring to test $H_0\colon\theta\geq\theta_0$ vs. $H_1\colon\theta<\theta_0$. In the test n items are placed on test and two integer values, r_1 and r_2 are chosen such that $r_1+r_2\leq n$. In the first stage, testing proceeds (with or without the replacement of failed items) until r_1 failures occur. At this time a decision is made to accept or reject H_0 , or to continue on to the second stage where r_2 additional failures are

observed and a final decision is made. The decisions are based on the values of T_r and T_r , the total times on test at the times of the r_1^{th} and r_3^{th} failures repectively, with $r_3 = r_1 + r_2$. The test is depicted in figure 1.1.

It is possible that additional information about the true value of θ may be needed following the test decision. Thus it may be of interest to estimate θ using the data from the life test. In this report we derive confidence intervals for θ using data from the two stage life test.

Stage 1 reject
$$H_0$$
 continue to stage 2 accept H_0 $\xrightarrow{2T_1}$ θ_0

Figure 1.1. The two stage life test.

II. A Two Sided Confidence Interval for θ

Confidence intervals for $\,\theta\,$ using type II censoring were given by Epstein (1960a) and Epstein (1960b). A two

sided interval with confidence coefficient $(1 - \alpha)$ is

$$\begin{bmatrix} \frac{2T_r}{\chi^2_{\frac{\alpha}{2}}, 2r} & , & \frac{2T_r}{\chi^2_{1-\frac{\alpha}{2}}, 2r} \end{bmatrix}$$
 (2.1)

where T_r is the total time on test at the r^{th} failure. If t_1, t_2, \ldots, t_n represent the ordered failure times, then

$$T_{r} = \begin{cases} r \\ \sum_{i=1}^{r} t_{i} + (n-r)t_{r} \\ nt_{r} \end{cases}$$
 (without replacement)

A two sided confidence interval for type II censoring in a single stage is given by (2.1). This suggests the possibility that the single stage interval could be used at either stage of the two-stage test. More formally, we conjecture that the following rule provides a $100(1-\alpha')$ percent confidence interval for θ .

When the decision is made at stage 1, use

$$\begin{bmatrix} \frac{2^{T}r_{1}}{x_{\alpha'}^{2}, 2r_{1}}, \frac{2^{T}r_{1}}{x_{1-\frac{\alpha'}{2}, 2r_{1}}^{2}} \end{bmatrix}.$$

When the decision is made at stage 2, use

$$\begin{bmatrix} \frac{2T_{r_3}}{\chi^2_{\alpha',2r_3}}, \frac{2T_{r_3}}{\chi^2_{1-\frac{\alpha'}{2},2r_3}} \end{bmatrix}.$$

We shall refer to the first interval in (2.2) as I_1 and the second interval as I_2 . In general we will refer to the single interval generated by rule (2.2) as I. To establish that I is a confidence interval for θ with a coefficient at least $1-\alpha'$, we would have to show that $P(\theta \epsilon I) \geq 1-\alpha'$. Unfortunately, it will be shown that $P(\theta \epsilon I) < 1-\alpha'$ for some θ . However, we will also show that, for a suitably chosen α' , the confidence interval given by (2.1) will have a confidence coefficient no less than $1-\alpha$.

First, define event D \equiv (the test decision is made at stage 1). Then \bar{D} will represent continuation to stage 2. We may then write

$$P(\theta \epsilon I) = P(D, \theta \epsilon I_1) + P(\overline{D}, \theta \epsilon I_2) = p_1 + p_2$$
, say.

If we recall that $2T_{r_1}/\theta \sim \chi^2_{2r_1}$, it is seen that $P(\theta \epsilon I_1) = 1 - \alpha'$. Also, $P(\theta \epsilon I_1) = P(D, \theta \epsilon I_1) + P(\overline{D}, \theta \epsilon I_1) = P_1 + P(\overline{D}, \theta \epsilon I_1)$. Combining these results gives

$$P(\theta \epsilon I) = 1 - \alpha' - (P(\overline{D}, \theta \epsilon I_1) - P(\overline{D}, \theta \epsilon I_2))$$
$$= 1 - \alpha' - p^*, \text{ say.}$$

To establish the validity of the interval in (2.1) it would be necessary that $p^* = P(\overline{D}, \theta \epsilon I_1) - P(\overline{D}, \theta \epsilon I_2) \leq 0$. That this is not always the case will be shown later. We first introduce some notational definitions which should make subsequent material more readable.

Define the transformations Y = $2T_{r_1}/\theta$ and Z = $2T_{r_3}/\theta$ so that Y $\sim \chi^2_{2r_1}$ and Z $\sim \chi^2_{2r_3}$. Under these transformations, p* is equal to

$$P\left[\frac{\theta_0^{d_1}}{\theta} \leq Y \leq \frac{\theta_0^{d_2}}{\theta}, \chi^2_{1-\frac{\alpha'}{2},2r_3} \leq Z \leq \chi^2_{\frac{\alpha'}{2},2r_3}\right].$$

Now define

$$R_{1} = \begin{bmatrix} \chi_{1-\frac{\alpha'}{2},2r_{1}}^{2}, \chi_{\frac{\alpha'}{2},2r_{1}}^{2} \end{bmatrix}$$

$$R_{2} = \begin{bmatrix} \frac{\theta_{0}d_{1}}{\theta}, \frac{\theta_{0}d_{2}}{\theta} \end{bmatrix}, \text{ and}$$

$$R_3 = \left[\chi^2_{1-\frac{\alpha'}{2},2r_3}, \chi^2_{\frac{\alpha'}{2},2r_3}\right]$$

Thus, under the transformations, R_1 , R_2 and R_3 correspond to I_1 , the continuation region, and I_3 respectively. This permits us to write p* simply as $P(Y \in R_2, Y \in R_1) - P(Y \in R_2, Z \in R_3)$.

Making use of the endpoints of intervals R_1 , R_2 and R_3 , we can make some general observations about $P(\theta \epsilon I)$. We consider those intervals designated by numbers in parentheses in Figure 2.1.

Figure 2.1. A partition of the parameter space.

In interval (1):

$$\theta < \frac{\theta_0 d_1}{\chi_{\alpha'}^2, 2r_3}$$

In this interval,

$$\frac{\theta_0 d_1}{\theta} > \chi^2_{\underline{\alpha}, 2r_3} > \chi^2_{\underline{\alpha}, 2r_1},$$

which implies that $P(Y \in R_2, Z \in R_3) = P(Y \in R_2, Y \in R_1) = 0$. Thus, in interval (1) we have $P(\theta \in I) = 1 - \alpha'$.

In interval (2):

$$\frac{\theta_0 d_1}{\chi_{\alpha_1,2r_3}^2} \leq \theta < \frac{\theta_0 d_1}{\chi_{\alpha_1,2r_1}^2}$$

Since

$$\frac{\theta_0^{d_1}}{\theta} \rightarrow \chi^2_{\underline{\alpha'},2r_1}$$

in this interval, we have $P(Y \in R_2, Y \in R_1) = 0$. This gives the result that $P(\theta \in I) \ge 1 - \alpha'$ for all θ in interval (2).

In interval (3):

$$\theta \geq \frac{\theta_0 d_2}{x_{1-\frac{\alpha'}{2},2r_1}}$$

Here

$$\frac{\theta_0^{d_2}}{\theta} \leq \chi^2_{1-\frac{\alpha'}{2},2r_1}$$

implies $P(Y \in R_2, Y \in R_1) = 0$. So again, for θ in the interval (3), $P(\theta \in I) \ge 1 - \alpha'$.

In interval (4):

$$\frac{\theta_0 d_2}{\frac{\chi_{\alpha'}}{2}, 2r_1} \leq \theta \leq \frac{\theta_0 d_1}{\chi_{1-\frac{\alpha'}{2}, 2r_1}^2}$$

We note that, if

$$(d_2/d_1) \geq (\chi_{\alpha}^2, 2r_1/\chi_{1-\frac{\alpha}{2}, 2r_1}^2),$$

the sense of the inequalities will be reversed and interval (4) will be empty. When it is non-empty we have $R_2 \subseteq R_1$ and

$$\begin{split} \mathtt{P}(\theta \in I) &= 1 - \alpha' - \mathtt{P}(\mathtt{Y} \in \mathtt{R}_2) + \mathtt{P}(\mathtt{Y} \in \mathtt{R}_2, \mathtt{Z} \in \mathtt{R}_3) \\ &= 1 - \alpha' - \mathtt{P}(\mathtt{Y} \in \mathtt{R}_2) \left(1 - \mathtt{P}(\mathtt{Z} \in \mathtt{R}_3 \big| \mathtt{Y} \in \mathtt{R}_2) \right) \\ &= 1 - \alpha' - \mathtt{P}(\overline{\mathtt{D}}) \left(1 - \mathtt{P}(\theta \in I_2 \big| \overline{\mathtt{D}}) \right). \end{split}$$

Since $P(\overline{D}) > 0$ and $P(\theta \epsilon I_2 | \overline{D}) < 1$, it follows that $P(\theta \epsilon I) < 1 - \alpha'$ for θ in interval (4) when it is non-empty. This shows that the confidence interval proposed by (2.1) is invalid in the sense that, for some θ , $P(\theta \epsilon I) < 1 - \alpha'$.

For those regions not included in these four intervals a general pattern of the behavior of $P(\theta \epsilon I)$ as a function of θ was observed by computing $P(\theta \epsilon I)$ on the computer for various test parameters given by Bulgren and

Hewett (1973). The general pattern which was observed is depicted in Figure 2.2. It can be seen from Figure 2.2 that if α' were chosen sufficiently small, it would be possible to keep $P(\theta\epsilon I) \geq 1-\alpha$, where $1-\alpha$ is the desired confidence coefficient. An appropriate value of α' can be found if we find an upper bound on p* which can be solved for α' . Recall that p* is just $F(Y\epsilon R_2, Y\epsilon R_1)-P(Y\epsilon R_2, Z\epsilon R_3)$. The difficulty in finding a bound on p* is finding a closed expression for $P(Y\epsilon R_2, Z\epsilon R_3)$ which is also simple enough to permit the solution for α' . Bulgren and Hewett (1973) give the joint density of Y and Z as

$$f(y,z) = \begin{cases} \frac{(z-y)^{r_{2}-1} r_{1}^{-1} - z/2}{y^{r_{1}+r_{2}} r_{1}^{-1} r_{2}^{-1}} & 0 < y < z \quad 0 < z < \infty \\ 0 & \text{elsewhere.} \end{cases}$$

Then

$$P(Y \in \mathbb{R}_{2}, Z \in \mathbb{R}_{3}) = \int_{0}^{\frac{\theta_{0}d_{2}}{\theta}} \frac{\chi_{\alpha'}^{2}}{2}, 2r_{3}$$

$$\int_{0}^{\frac{\theta_{0}d_{1}}{\theta}} \chi_{1-\frac{\alpha'}{2}, 2r_{3}}^{2}$$

$$f(y, z) dzdy,$$

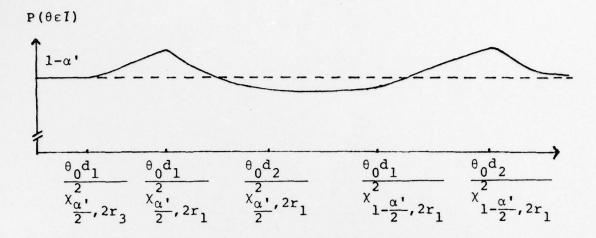


Figure 2.2. Behavior of $P(\theta \epsilon I)$ when I is from (2.1)

and it is apparent that the closed, simple expression we seek is not possible. In lieu of evaluating this joint probability directly, we will simplify it using a Bonferroni bound. A lower bound on $P(Y \in \mathbb{R}_2, Z \in \mathbb{R}_3)$, using the Bonferroni inequality, is

$$P(Y \in R_2, Z \in R_3) \ge P(Y \in R_2) + P(Z \in R_3) - 1$$

$$= P(Y \in R_2) + (1 - \alpha^*) - 1$$

$$= P(Y \in R_2) - \alpha^*.$$

Thus

$$p^* \leq P(Y \in R_1, Y \in R_2) - P(Y \in R_2) + \alpha'.$$
 (2.3)

This upper bound on p* may be further simplified with some observations about the relationship of R_1 to R_2 . With respect to θ , interval R_1 is fixed. On the other hand, R_2 increases in both size and location as θ decreases. When $\theta = \infty$, R_2 is the single point $\{0\}$. When θ is such that $\theta_0 d_1/\theta$ coincides with

$$2T_{r_1}/\chi^2_{1-\frac{\alpha}{2},2r_1}$$

it could be that $R_2 \subseteq R_1$. If this occurs, the upper bound in (2.3) achieves its maximum value α' . Since $P(\theta \epsilon I) = 1 - \alpha' - p^*$, the Bonferroni inequality gives $P(\theta \epsilon I) \geq 1 - 2\alpha'$. Obviously, if we want $P(\theta \epsilon I) \geq 1 - \alpha$, α' is given the value $\alpha/2$. This establishes the following result.

Theorem 2.1. Let r_1 and r_2 be the number of failures required for each stage of the two-stage exponential life test, where $r_3 = r_1 + r_2$. If T_{r_1} and T_{r_3} represent the total time on test at the r_1 and r_3 failures respectively, then the following rule gives a two-sided confidence interval for the exponential mean θ , with a confidence coefficient at least $1 - \alpha$, at the time of decision for the two-stage test. If a decision is made at the first stage, use

$$\begin{bmatrix} \frac{2^{T}r_{1}}{\chi_{\frac{\alpha}{4},2r_{1}}^{2}}, \frac{2^{T}r_{1}}{\chi_{1-\frac{\alpha}{4},2r_{1}}^{2}} \end{bmatrix}.$$

If a decision is made at the second stage, use

$$\begin{bmatrix} \frac{2T_{r_3}}{x_3^2}, \frac{2T_{r_3}}{x_{1-\frac{\alpha}{4}, 2r_3}^2} \end{bmatrix}.$$

The wide applicability of the Bonferroni inequality suggests that the bound in (2.3) may be quite crude, leading to overly conservative confidence intervals. An alternative approach will be employed in searching for a less conservative confidence interval. We also will admit the possibility that $P(\theta \epsilon I) < 1 - \alpha$, for some θ , if the difference $(1-\alpha)-P(\theta \epsilon I)$ can be shown to be small. This would result in approximate confidence intervals.

Let

$$\Delta = P(Y \in R_2) P(Z \in R_3) - P(Y \in R_2, Z \in R_3)$$
.

Then

$$p^* = P(Y \in R_1, Y \in R_2) - P(Y \in R_2) P(Z \in R_3) + \Delta$$

$$= P(Y \in R_1, Y \in R_2) - P(Y \in R_2) (1-\alpha') + \Delta. \qquad (2.4)$$

If $\Delta=0$ (this would be true if Y and Z were independent) p^* could be bounded above without use of the Bonferroni inequality. The penalty for assuming $\Delta=0$, when, in fact, $\Delta\neq 0$ could be a confidence interval where $P(\theta \epsilon I) < 1-\alpha$ for some θ . The difference $(1-\alpha)-P(\theta \epsilon I)$ would be at most Δ , and the Bonferroni inequality can provide an upper bound on Δ .

$$P(Y \in R_1, Z \in R_3) \ge P(Y \in R_2) + P(Z \in R_3) - 1$$

= $P(Y \in R_2) - \alpha'$.

Thus

$$\Delta \leq P(Y \in R_2) (1-\alpha') - P(Y \in R_2) + \alpha'$$

$$= \alpha' (1-P(Y \in R_2))$$

$$= \alpha' P(Decision at stage 1). \tag{2.5}$$

Since this Bonferroni bound may also be overly conservative, and since α' will be less than α , it is apparent that Δ will be small if it is positive. If Δ is negative the resulting confidence interval would be less conservative than under the assumption $\Delta = 0$. Thus, if we assume $\Delta = 0$ and then bound p* under this assumption, the resulting confidence interval will be such that $P(\theta \in I) \geq 1 - \alpha - \Delta$, where Δ is bounded above by (2.5). We proceed with the assumption that $\Delta = 0$.

The expression (2.4) for p* now becomes

$$p^* = P(Y \in R_1, Y \in R_2) - P(Y \in R_2) (1-\alpha^*).$$
 (2.6)

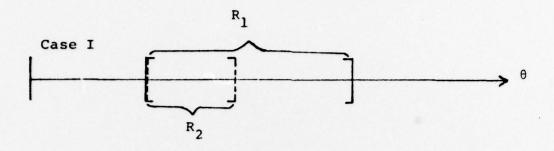
To establish an upper bound on (2.6) we again consider the relationship of R_1 with R_2 as θ changes. Our observations will pivot on the relationship of R_1 with R_2 when θ is such that

$$\theta_0 d_1/\theta = \chi^2_{1-\frac{\alpha'}{2},2r_1}$$

i.e., when the left endpoints of R_1 and R_2 coincide. Here either $R_2 \subseteq R_1$ or $R_1 \subseteq R_2$. We will designate the situation $R_2 \subseteq R_1$ as Case I, and Case II will correspond to $R_1 \subseteq R_2$. Case I and Case II are depicted in Figure 2.3. In a specific application, whether Case I or Case II applies will depend on the test parameters involved and the value of α' . Each case is considered separately.

Case I: $R_2 \subseteq R_1$ when their left endpoints coincide. We examine the nature of the relationship of R_1 with R_2 for different θ and its effect on the problem of placing a bound on p^* .

I.a) θ is such that $R_1 \cap R_2 = \emptyset$. Referring to (2.6) it is clear that $p^* \le 0$ for these values of θ .



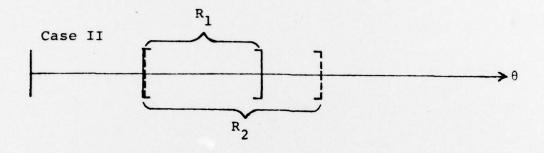


Figure 2.3. Relationship of R with R when θ is such that their left endpoints coincide.

I.b) θ is such that $R_1 \cap R_2 \neq \emptyset$ and $\overline{R}_1 \cap R_2 \neq \emptyset$. Let $R_1 \cap R_2 \equiv R_5$ and $\overline{R}_1 \cap R_2 \equiv R_4$. With this notation we have

$$P^* = P(Y \in R_1, Y \in R_2) - (1-\alpha') P(Y \in R_2)$$

$$= P(Y \in R_5) - (1-\alpha') [P(Y \in R_4) + P(Y \in R_5)]$$

$$= \alpha' P(Y \in R_5) - (1-\alpha') P(Y \in R_4). \qquad (2.7)$$

Expression (2.7) is maximum when $R_{\underline{q}} = \emptyset$ or, equivalently $R_{\underline{2}} \subseteq R_{\underline{1}}$.

It is clear that, to establish an upper bound on p* for Case I, it suffices to consider only those θ for which $R_2 \subseteq R_1$. If $R_2 \subseteq R_1$ expression (2.6) reduces to p* = $\alpha' P(Y \in R_2)$. Note first that if $R_2 \subseteq R_1$, then $P(Y \in R) \le P(Y \in R_1) = 1 - \alpha'$. So, one bound on p* under Case I is $\alpha'(1-\alpha')$. A smaller bound may be found if we determine the maximum value of $P(Y \in R_2)$, subject to $R_2 \subseteq R_1$.

For that purpose, we find the value of θ , say θ^* , for which $P(Y \in R_2)$ is maximum for given θ_0 , d_1 and d_2 . Since $Y \sim \chi^2_{2r_1}$ we can write

$$P(Y \in \mathbb{R}_2 | \theta) = \int_{\ell(\theta)}^{\ell(\theta)} f(t) dt, \text{ where } \ell(\theta) = \theta_0 d_1 / \theta,$$

$$u(\theta) = \theta_0 d_2/\theta$$
, and $f(t) = \frac{t^{-1} - t/2}{t^{-1}}$.

Then

$$\frac{\partial P(Y \in \mathbb{R}_2 \mid \theta)}{\partial \theta} = f(u(\theta)) \frac{\partial u(\theta)}{\partial \theta} - f(\ell(\theta)) \frac{\partial \ell(\theta)}{\partial \theta}.$$

Setting

$$\frac{\partial P(Y \varepsilon R_2 \mid \theta)}{\partial \theta} = 0$$

and making the appropriate substitutions, we obtain

$$d_{2}\left[\frac{\theta_{0}d_{2}}{\theta}\right]^{r_{1}-1} = e^{-\frac{\theta_{0}d_{2}}{2\theta}} = d_{1}\left[\frac{\theta_{0}d_{1}}{\theta}\right]^{r_{1}-1} = e^{-\frac{\theta_{0}d_{1}}{2\theta}},$$

or

$$\left\{ \frac{d_2}{d_1} \right\}^{r_1} e^{\frac{\theta_0}{2\theta} (d_1 - d_2)} = 1.$$

Finally

$$\theta^* = \frac{\theta_0 (d_2 - d_1)}{2r_1 (\ln d_2 - \ln d_1)}.$$

So, P(YER $_2\mid \vartheta)$ increases to a maximum at $\theta \star$ and then decreases. Now let

$$R_2^* = \begin{bmatrix} \frac{\theta_0^d 1}{\theta^*}, \frac{\theta_0^d 2}{\theta^*} \end{bmatrix}$$
.

If $R_2^* \subseteq R_1$, an upper bound on p^* is clearly $\alpha' P(Y \in R_2^*)$ under Case I.

Since

$$R_1 = \left[\chi^2_{1-\frac{\alpha'}{2},2r_1}, \chi^2_{\frac{\alpha'}{2},2r_1} \right]$$

and α' is as yet unknown, it appears that it is not possible to determine if $R_2*\subseteq R_1$. We note however that $\alpha'\le \alpha$ and consequently

$$R_{2}^{*} \subseteq \left[\chi_{1-\frac{\alpha}{2},2r_{1}}^{2}, \chi_{\frac{\alpha}{2},2r_{1}}^{2} \right]$$

implies that

$$R_2^* \subseteq \left[\chi^2_{1-\frac{\alpha'}{2},2r_1}, \chi^2_{\frac{\alpha'}{2},2r_1}\right].$$

Thus in most cases, using the desired $1-\alpha$ coefficient, it can be determined if $R_2^*\subseteq R_1$. When this relationship exists we find that $P(\theta \epsilon I) \geq 1-\alpha'-\alpha'P(Y\epsilon R_2^*)$. So, if $\alpha'=\alpha/[1+P(Y\epsilon R_2^*)]$, we have $P(\theta \epsilon I) \geq 1-\alpha$. We also note that

$$\frac{\alpha}{1 + P(Y \in R_2^*)} > \frac{\alpha}{2}$$

insures that the interval with $\alpha' = \alpha/[1+P(Y \in R_2^*)]$ will be less conservative than the original intervals in Theorem 2.1 using $\alpha' = \alpha/2$.

Computations using actual test parameters given by Bulgren and Hewett (1973) suggest that R_2^* is quite commonly contained in R_1 for smaller values of α , say

 $\alpha \leq .2$. The improvement over the intervals of Theorem 2.1 will be discussed later in this section.

If $R_2^* \not \subseteq R_1$, the problem becomes more complex. Here $P(Y \in R_2 \mid \theta)$, subject to the constraint $R_2 \subseteq R_1$, reaches its maximum value when the left endpoints of R_1 and R_2 coincide, or when the right endpoints coincide, depending on the location of R_2^* with respect to R_1 . Specifically, when $R_1 \supseteq R_2$,

$$\max_{\mathbf{P}(\mathbf{Y} \in \mathbf{R}_{2} | \theta)} = \begin{cases} \frac{d_{2}}{d_{1}} & \chi_{1-\frac{\alpha'}{2},2r_{1}}^{2} \\ \int_{\chi_{1-\frac{\alpha'}{2},2r_{1}}^{2}}^{f(t) dt, \text{ if } \frac{\theta_{0}d_{1}}{\theta^{*}}} < \chi_{1-\frac{\alpha'}{2},2r_{1}}^{2} \\ \chi_{\frac{\alpha'}{2},2r_{1}}^{2} \\ \int_{\frac{d_{1}}{d_{2}}}^{\chi_{\frac{\alpha'}{2},2r_{1}}^{2}}^{f(t) dt, \text{ if } \frac{\theta_{0}d_{1}}{\theta^{*}}} \geq \chi_{1-\frac{\alpha'}{2},2r_{1}}^{2} \end{cases}$$

We need to solve the equation

$$\alpha = \alpha' + \alpha' (\max P(Y \in R_2 | \theta))$$

for α' . The difficulty involved is the manner in which α' appears in the limits of integration in max $P(Y \in R_2 | \theta)$. Consequently, if it is found that $R_2 * \subseteq R_1$ cannot be established, the use of $\alpha'(1-\alpha')$ as an upper bound on p^* is advised. We next treat the corresponding problem under Case II.

Case II: When θ is such that the left endpoints of R_1 and R_2 coincide, $R_1 \subseteq R_2$. By arguments essentially the same as those used for Case I, it suffices to consider only the set of θ for which $R_1 \subseteq R_2$, in finding an upper bound on p^* .

If
$$R_1 \subseteq R_2$$
,

$$p^* = P(Y \in R_2, Y \in R_1) - (1-\alpha') P(Y \in R_2)$$

$$= P(Y \in R_1) - (1-\alpha') P(Y \in R_2)$$

$$= (1-\alpha') - (1-\alpha') P(Y \in R_2)$$

$$= (1-\alpha') [1-P(Y \in R_2)].$$

Now, since $P(Y \in R_2) \ge P(Y \in R_1) = 1 - \alpha'$, we again find, as we did in Case I, that $p^* \le \alpha'(1-\alpha')$. This bound is achieved by p^* if $R_1 = R_2$.

We have shown that, under the assumption $\Delta=0$, an upper bound on p* is $\alpha'(1-\alpha')$, and $P(\theta \epsilon I) \geq 1-\alpha'-\alpha'(1-\alpha')$. If we want $P(\theta \epsilon I) \geq 1-\alpha$, then set $\alpha'=1-(1-\alpha)^{1/2}$. In Theorem 2.1 we used $\alpha'=\alpha/2$ which is

greater than $1-(1-\alpha)^{1/2}$. However, for small α , $\alpha/2 \approx 1-(1-\alpha)^{1/2}$. Thus, the improvement over the results in Theorem 2.1 is slight. A further improvement s possible when $R_2^* \subseteq R_1$. Then we have $\alpha' = \alpha/[1+P(Y \in R_2^*)]$. The degree of improvement in this situation over the intervals of Theorem 2.1 depends on the value of $P(Y \in R_2^*)$.

To get some idea of how conservative the interval in Theorem 2.1 is, some computer studies were carried out using specific two-stage test parameters given by Bulgren and Hewett (1973). For each test used, the interval

$$\begin{bmatrix} \frac{\theta_0 d_1}{x_{\alpha',2r_1}^2}, \frac{\theta_0 d_2}{x_{1-\frac{\alpha'}{2},2r_1}^2} \\ \end{bmatrix}$$

(see Figure 2.2) was divided by twenty points. Using $\alpha' = \frac{\alpha}{2}, \ P(\theta \epsilon I) \ was \ computed \ at \ each \ of \ the \ twenty \ points.$ Numerical integration techniques were used to find $P(Y \epsilon R_2, Z \epsilon R_3). \quad \text{Table 2.1 gives the minimum and}$ $\max \text{maximum values of } P(\theta \epsilon I) \ \text{over the twenty points.} \quad \text{Many}$ other tests were included in this study but, since results on those were nearly the same as for the tests given in Table 2.1 , their results have not been included in the Table.

Table 2.2 reflects the improvement which is possible if it happens that $R_2^*\subseteq R_1$ and the value used for α' is $\alpha/1+P(Y\epsilon R_2^*)$ rather than $1-(1-\alpha)^{1/2}$. The desired confidence coefficient in Table 2.2 is .90. As in Table 2.1 the minimum and maximum observed values of $P(\theta\epsilon I)$ are given, first using $\alpha'=1-(1-\alpha)^{1/2}$, and then using $\alpha'=\alpha/1+P(Y\epsilon R_2^*)$. The confidence intervals using the latter expression for α' are less conservative, but the improvement is hardly dramatic. We do not sacrifice much by using the simpler intervals of Theorem 2.1.

III. A One-Sided Confidence Interval

If a one-sided confidence interval for θ is desired following the two-stage test, the same approach as used in Section II will yield analogous results. The confidence interval is found according to the following rule.

When the test decision is made at stage one, use

$$\left[\frac{2T_{r_1}}{\chi_{\alpha',2r_1}^2}, \infty\right] = I_1, \text{ say.}$$

When the test decision comes at stage two, use (3.1)

$$\left[\frac{2T_{r_3}}{\chi^2_{\alpha',2r_3}}, \infty\right] = I_2, \text{ say.}$$

.05	.9973	.9855	.9692	.9328
.05				• • • • • • • • • • • • • • • • • • • •
		.9630	.9285	.8497
0.5	.9973	.9856	.9693	.9328
.05 .05	.9931	.9648	.9278	.8466
.05	.9974	.9863	.9710	.9365
	.05	.9931	.9931 .9648 .9974 .9863	.05 .9931 .9648 .9278 .9974 .9863 .9710

Note: The first entry in each cell is the maximum observed $P(\theta \epsilon 1)$ over the twenty points used.

The second entry is the minimum observed $P(\theta \epsilon I)$.

$\frac{\text{Test}}{\theta_0/\theta_1}$	Paramete α	β	α'	Minimum $P(\theta \in I)$	Maximum P(θεΙ)
5			.0513	.9272	.9698
5/2	.05	.05	.0592	.9143	.9642
3	.05	.05	.0513	.9278	.9636
			.0595	.9152	.9690
2	.10	.10	.0513	.9290	.9690
			.0608	.9166	.9634
<u>5</u>	.10	.10	.0513	.9257	.9701
2			.0583	.9125	.9646
3	.10 .	.10	.0513	.9241	.9702
			.0566	.9105	.9647

Note: The first entry in a cell corresponds to $\alpha' = 1 - (1-\alpha)^{1/2}$.

The second entry corresponds to $\alpha' = \alpha/[1+P(Y \in R_2^*)]$.

Again, $P(\theta \in I) = 1 - \alpha' - p^*$, where

$$p^* = P[\overline{D}, \theta \epsilon I_1] - P[\overline{D}, \theta \epsilon I_2].$$

We use the transformations

$$Y = \frac{2T_{r_1}}{\theta}$$
 and $Z = \frac{2T_{r_3}}{\theta}$,

and also define

$$R_{1} = [0, \chi_{\alpha}^{2}, 2r_{1}],$$

$$R_{2} = \left[\frac{\theta_{0}d_{1}}{\theta}, \frac{\theta_{0}d_{2}}{\theta}\right], \text{ and}$$

$$R_{3} = [0, \chi_{\alpha}^{2}, 2r_{3}].$$

Now we may write

$$p^* = P(Y \in R_2, Y \in R_1) - P(Y \in R_2, Z \in R_3)$$
.

As with the two-sided intervals, we can make some general observations about $P(\theta \epsilon \mathbf{1})$.

i) If

$$\theta < \frac{\theta_0 d_1}{\chi_{\alpha',2r_3}^2},$$

then

$$\frac{\theta_0^{d_1}}{\theta} > \chi_{\alpha',2r_3}^2 > \chi_{\alpha',2r_1}^2$$

Here $P(Y \in R_2, Y \in R_1) = P(Y \in R_2, Z \in R_3) = 0$, and $P(\theta \in I) = 1 - \alpha'$. ii) If

$$\frac{\theta_0 d_1}{\chi_{\alpha',2r_3}^2} \leq \theta \leq \frac{\theta_0 d_1}{\chi_{\alpha',2r_1}^2},$$

then

$$\frac{\theta_0 d_1}{\theta} \geq \chi_{\alpha',2r_1}^2$$

and

$$R_1 \cap R_2 = \emptyset$$
.

Since $P(Y \in R_1, Y \in R_2) = 0$, $P(\theta \in I) \ge 1 - \alpha'$. iii) If

$$\theta \geq \frac{\theta_0 d_2}{\chi_{\alpha',2r_1}^2} ,$$

then

$$\frac{\theta_0^{d_2}}{\theta} \leq x_{\alpha',2r_1}^2$$

and

$$R_2 \subseteq R_1$$
.

Furthermore,

$$R(\theta \epsilon I) = 1 - \alpha' - P(Y \epsilon R_2) + P(Y \epsilon R_2, Z \epsilon R_3)$$

$$= 1 - \alpha' - P(Y \epsilon R_2) (1 - P(Z \epsilon R_3 | Y \epsilon R_2))$$

$$< 1 - \alpha'.$$

We can utilize the same approaches to finding an upper bound on p* that were used in the previous section on two-sided intervals. One bound on p* is found using the Bonferroni inequality, and the result is again $p^* \leq \alpha'$. Consequently we would set $\alpha' = \frac{\alpha}{2}$ in the intervals (3.1) to ensure that $P(\theta \epsilon I) \geq 1 - \alpha$ for all θ .

The other approach is to set

$$\Delta = P(Y \in R_2) P(Z \in R_3) - P(Y \in R_2, Z \in R_3) = 0.$$

Then p* becomes $P(Y \in R_2, Y \in R_1) - (1-\alpha') P(Y \in R_2)$. By arguments similar to those used in Section II, it can be shown that p^* takes its maximum value when $R_2 \subseteq R_1$. If $R_2 \subseteq R_1$, then $p^* = \alpha' P(Y \in R_2) \leq \alpha' (1-\alpha')$. Or, we may again define

$$R_2^* = \left[\frac{\theta_0^d_1}{\theta^*}, \frac{\theta_0^d_2}{\theta^*}\right],$$

where θ^* is that value of θ for which $P(Y \in R_2 | \theta)$ is maximum. So, we obtain $p^* \leq \alpha' P(Y \in R_2^*)$ when $R_2^* \subseteq R_1$. We arrive at the same terminus as in Section II. We may use $\alpha' = 1 - (1-\alpha)^{1/2}$, which is nearly $\alpha/2$, or $\alpha/[1+P(Y \in R_2^*)]$ if $R_2^* \subseteq R_1$ and a less conservative one-sided interval is desired.

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