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THE MOTION OF A PLANE-PARALLEL HEAVY LIQUID IN A CHANNEL WITH A BOTTOM WHICH HAS A STEP

By

G. Abduvaliyev, Ch. Dzhanybekov





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*ye initially, after vowels, and after ъ, ъ; e elsewhere. When written as ë in Russian, transliterate as yë or ë. The use of diacritical marks is preferred, but such marks may be omitted when expediency dictates.

GREEK ALPHABET

Alpha	А	α			Nu	Ν	ν	
Beta	В	β			Xi	Ξ	ξ	
Gamma	Г	γ			Omicron	0	0	
Delta	Δ	δ			Pi	Π	π	
Epsilon	E	ε	e		Rho	P	ρ	
Zeta	Z	ζ			Sigma	Σ	σ	s
Eta	Н	η			Tau	т	τ	
Theta	Θ	θ	\$		Upsilon	Т	υ	
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Mu	М	μ			Omega	Ω	ω	

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	sin			sin	
	cos			cos	
	tg			tan	1.00
	ctg			cot	
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	sh			sinh	
	ch			cosh	
	th			tanh	
	cth			coth	
	sch			sech	
	csch	n		csch	
	arc	sin		sin ⁻¹	
	arc	cos		cos ⁻¹	
	arc	tg		tan ⁻¹	
	arc	ctg		cot ⁻¹	
	arc	sec		sec ⁻¹	
	arc	cosed		csc ⁻¹	
	arc	sh		sinh ⁻¹	
	arc	ch		cosh ⁻¹	
	arc	th		tanh ⁻¹	
	arc	cth		coth ⁻¹	
	arc	sch		sech ⁻¹	
	arc	csch		csch ⁻¹	
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RUSSIAN AND ENGLISH TRIGONOMETRIC FUNCTIONS

rot	curl
lg	log

GRAPHICS DISCLAIMER

All figures, graphics, tables, equations, etc. merged into this translation were extracted from the best quality copy available.

1.2

THE MOTION OF A PLANE-PARALLEL HEAVY LIQUID IN A CHANNEL WITH A BOTTOM WHICH HAS A STEP

G. Abduvaliyev, Ch. Dzhanybekov

The problem of motion of heavy liquid in a channel with a bottom which has a step is examined. Such a problem was first studied by N. E. Kochin [1] in a linear setup and was resolved for the case of a step of negligible height.



Fig. 1.

Assume that a heavy incompressible liquid moves at a speed of V_a (Fig. 1). The presence of the step at the bottom results in a disturbance of the liquid. Our objective is to determine the form of free surface EF in the region near the step.

1

Employing the theory of functions of a complex variable, we formulate a system of integral-differential equations, the solution of which will determine the form of free surface EF.

Let us assume that in the case of a weightless liquid we have a complex potential of $w = \psi + i\psi$ and a Zhukovskiy function of

F. = ln Vedz = 10.+ ln Ve.

For determining function $W \cdot \varphi \cdot i \varphi$ let us plot a band of width q on plane W onto the upper half plane of plane $i \cdot \mathbf{F} + i \gamma$. At the same time the solid walls FABE and free surface EF are plotted onto half lines FA, ABE and segment EF of the true axis, respectively (Fig. 2).



Fig. 2.

It is not difficult to verify that this representation is given by the function

$$W(t) = \frac{q}{3} ln \frac{t-t}{t-1} + tq.$$
 (1)

where q is the flow of the liquid per second.

The function

$$\Phi(t) = \frac{F(t) - F_{t}(t)}{\sqrt{t-t^{*}}},$$

4. 3

(2)

comes into consideration

Fit)-ln Vedz. Fo(t)=ln Vedz dW.

(2.1)

is the Zhukovskiy function for weighable and weightless liquid of the scheme being considered, V_4 is the speed of the weighable liquid at infinity upstream. The limiting values for determining functions $\Phi^{(t)}$ and $F_{i}(t):\sqrt{t-t^{2}}$ are given in Table 1.

Table 1.						
t=y	$F_{o}(t):\sqrt{1-t^{2}}$	ф(е)				
	$Re[f_{\bullet}(\underline{x});\sqrt{1-\underline{x}^2}] = \frac{\underline{x}\overline{x}}{\sqrt{\underline{y}}^{-1}}$	$Rech(\mathbf{E})=0$				
-8<3<-1	$\frac{1}{1} \operatorname{Re}[F_{o}(\mathbf{y}): \sqrt{1 - \mathbf{y}^{2}}] = 0$	$Re (D \mathbf{y}) = ln \frac{V_{\mathbf{x}}}{V} \cdot \sqrt{1-\mathbf{y}^{\mathbf{x}}}$				
-1<買<1	Re[F_(y):√2-y=]=0	Re Ф(5) = 0				
1<3~~~	R[F_(E): \-=]=0	Reф(;;)=0				

According to the limiting values given in Table 1, based on the Schwarz integral, for $\Im_m t \ge 0$ we have:

 $\frac{F(t)}{\sqrt{1-t^*}} = \frac{1}{\pi t} \int \frac{Re[F_t(\mathbf{y}):\sqrt{t-\mathbf{y}^*}]d\mathbf{y}}{\mathbf{y}-t} =$ $=\frac{4}{\pi i}\left[\int \frac{\ln V_i hr}{\sqrt{1-g^2}} \frac{dg}{g-t} - \int \frac{dg}{\sqrt{g-t}} \frac{dg}{g-t}\right],$ $\Phi(t) = \frac{1}{\pi i} \int \frac{Re}{y-t} dy = \frac{1}{\pi i} \int \frac{\ln V_0/V}{\sqrt{t-y^2}} dy$

Here the unessential constants equate to zero. Considering the constancy of the speed magnitude vector on the free surface ($V_c = V$) and function (2), from the last equalities we have:

where

3

4. 2

$$F_{o}(t) = x \ln \frac{(+Bt - \sqrt{t^{2} - i}\sqrt{t^{2} - i})}{(B-t)(t - \sqrt{t^{2} - i})} \quad (\Im m t > 0), \quad (3)$$

$$F(t) = F_0(t) + \frac{\sqrt{1-t^2}}{\pi t} \int \frac{e_n V_0/V}{\sqrt{1-s^2}} \frac{ds}{s-t}$$
(4)

It is possible to determine that equalities (3) and (4) satisfy the boundary conditions of Table 1 and give the desired Zhukovskiy functions in the case of weightless liquid and also with & V/V given for weighable liquid.

On the free surface the function $ln v_{-}/v$, which is part of the expression under the integral sign from formula (4), satisfies the Bernoulli equation. Thus from

$$V^2 + 2gy = V_a^4 + 2gy_a$$

we find

$$l_{h} = -\frac{1}{2} l_{h} [1 + \epsilon (y_{*} - y):h].$$
 (5)

Here

$$\mathcal{E} = \frac{1}{F} = \frac{299}{V_{*}^{*}}$$

of the Froude reciprocal, v_{\bullet} . v_{\bullet} are the speed vector magnitudes of weighable liquid at points with ordinates y_{\bullet} and y respectively, g is the acceleration of gravity, h is the height of the free surface from the bottom at infinity upstream. From equality (4). proceeding to the limit with $t \rightarrow \phi$ (first designating the variable of integration by ϕ_{\bullet} , with 7mt > 0, and equating the imaginary parts, we obtain

$$\theta = \theta_{+} + \frac{\sqrt{1-\mu^{*}}}{\sqrt{1-\mu^{*}}} \int \frac{\ln[1+E(y_{h}-y):h]}{\sqrt{1-\mu^{*}}} d\varphi_{+}, \qquad (6)$$

4.

where

B.= zarcty F15-1/11-

with -i < y < i, 6 is constant (6>1). From the first equation of system (2.1) we have

exp F(t) = Ve e'= vdz

or with top, considering that 2=x+iy and equality

dw 29 .

we obtain

$$\frac{dz}{dz} = \frac{29}{3(y^2-1)} \frac{e^{i\theta}}{V},$$

from which we have finally

$$\frac{dx}{dy} = -\frac{29}{3(t-y^2)} \cdot \frac{\cos\theta}{V} \cdot \frac{dy}{dy} = -\frac{29}{3(t-y^2)} \cdot \frac{\sin\theta}{V} \cdot \frac{\sin\theta}{V} \cdot \frac{\cos\theta}{V} \cdot \frac{\cos\theta}{V} \cdot \frac{\sin\theta}{V} \cdot \frac{\cos\theta}{V} \cdot \frac{$$

The parametric equation of the free surface and thereby its form are determined from set of equations (6) and (7) with -1 < y < 1.

In order to solve the obtained set of nonlinear singular kernel integral-differential equations (6) and (7) we employ the Newton-Kantorovich method [2]. As the initial approximation of $x \cdot x \cdot (x)$ and $y \cdot y \cdot (x)$ let us take the solution of the corresponding problem for weightless liquid and for arriving at the first approximation let us proceed as follows.

Assuming the zero approximation is known, in the vicinity of point (*A.Y.*) let us replace the nonlinear terms from expressions (6) and (7) with the linear terms relative to unknowns *A.Y.*:

$$\frac{\sin\theta}{\sqrt{7}\sqrt{6}} \int_{0}^{0} \frac{1}{(1+\varepsilon(y_{0}-y_{0});h)^{4}h} \left[\sin\theta_{0} + (\theta_{0}-\theta_{0})\cos\theta_{0} + \frac{\varepsilon}{2} \frac{\sin\theta_{0}}{h+\varepsilon(y_{0}-y_{0})} (y_{1}-y_{0}) - \frac{\varepsilon\cos\theta_{0}\sqrt{1-\mu^{2}}}{2\pi} \right]$$

$$= \int_{0}^{1} \frac{cl}{[1+\varepsilon(y_{0}-y_{0});h](y_{0}-y_{0})\sqrt{1-y^{2}}} (y_{0}-y_{0}) \int_{0}^{1} \frac{cl}{2\pi} \left[\frac{\varepsilon}{2} \frac{cl}{2\pi} \right]$$
(8)

1. A.

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$$ln[1+\epsilon(y_{-}y):h]_{y_{1}} = ln[1+\epsilon(y_{-}y_{0}):h] - \frac{\epsilon(y_{0}-y_{0})}{h\cdot\epsilon(y_{0}-y_{0})}.$$
 (9)

Then on the basis of equation (9), formula (6) is presented as

$$\theta_{z} - \theta_{z} = F_{z}(y) - \frac{\varepsilon \sqrt{t - y^{2}}}{2\pi h} \int \frac{[y_{z}(y_{z}) - y_{z}(y_{z})] dy_{z}}{\sqrt{t - y^{2}} [y_{z} - y_{z}][t + \varepsilon (y_{z} - y_{z});h]}$$
(10)

here

$$F_{o}(\boldsymbol{z}) = \frac{\sqrt{t-\boldsymbol{y}^{*}}}{2\boldsymbol{x}} \int_{-t}^{t} \frac{\ln\left[t+\boldsymbol{\varepsilon}\left(\boldsymbol{y}_{o}-\boldsymbol{y}_{o}\right);h\right]}{\sqrt{t-\boldsymbol{z}_{i}^{*}}\left(\boldsymbol{z}_{o}-\boldsymbol{z}_{i}\right)} d\boldsymbol{z}_{i}.$$

From the second equation of set (7), in conformance with formulas (8) and (9), we obtain

$$\frac{dy_{i}}{d\xi} = -\frac{2h}{\xi(i-\xi^{2})[i+\xi(y_{0}-y_{0}):h]^{i/2}} \left\{ Sin \theta_{i} + Cos \theta_{i} \left\{ F_{i}(\xi) - \frac{\xi(y_{0}-y_{0})}{\xi(i-\xi^{2})[i+\xi(y_{0}-y_{0}):h]} d\xi \right\} + \frac{\xi}{2\pi h} \int_{-1}^{4} \frac{y_{i}(\xi) - y_{0}(\xi)}{f(\xi-\xi^{2})[\xi+\xi(y_{0}-y_{0}):h]} d\xi \right] + \frac{\xi}{2} \left[\frac{Sin \theta_{0}}{1+\xi(y_{0}-y_{0}):h} - \frac{\cos \theta_{0} \left\{ 1-\xi^{2} \right\}}{\pi} \int_{-1}^{4} \frac{d\xi_{i}}{(\xi+\xi u_{0})(\xi-\xi)\sqrt{t-\xi^{2}}} \right] (y_{i}-y_{0}) \right\}$$

or

$$\frac{d\tilde{u}_{\bullet}}{d\tilde{\sharp}} + \frac{\varepsilon}{\mathcal{J}(1-\tilde{\sharp}^{4})(1+\varepsilon u_{0})^{4/2}} \left[\frac{S_{in}\theta_{\bullet}}{1+\varepsilon u_{\bullet}} - \frac{\cos\theta_{\bullet}\sqrt{1-\tilde{\sharp}}}{\tilde{s}} \right]_{\bullet}^{\bullet} + \frac{\varepsilon}{\mathfrak{J}(1-\tilde{\sharp}^{4})(1+\varepsilon u_{0})^{4/2}} \left[\tilde{u}_{\bullet} = R(\tilde{\sharp}) + \frac{\varepsilon}{\mathfrak{J}\sqrt{1-\tilde{\sharp}^{4}}(1+\varepsilon u_{0})^{4/2}} \right]_{\bullet}^{\bullet}$$

$$= \frac{1}{\tilde{s}} \int_{-\frac{1}{2}}^{\frac{1}{2}} \frac{\widetilde{u}_{\bullet}(\tilde{\sharp}_{\star})d\tilde{s}_{\star}}{\sqrt{t-\tilde{\sharp}^{4}}(\tilde{\sharp}_{\star}-\tilde{\sharp})(1+\varepsilon u_{0})} , \qquad (11)$$

where

$$R(\overline{\mathbf{y}}) = -\frac{2}{\mathfrak{F}(t-\overline{\mathbf{y}}^*)(1+\varepsilon U_0)^{4} \mathfrak{g}} \left[\operatorname{Sin} \theta_0 + \operatorname{Cos} \theta_0 (\theta_0 - \theta_1 + \frac{\sqrt{t-\overline{\mathbf{y}}^*}}{\mathfrak{g}} \int_{\sqrt{t-\overline{\mathbf{y}}^*}}^{t} (\theta_1 - \varepsilon U_0(\overline{\mathbf{y}}_1)) d(\overline{\mathbf{y}}_1) \right] - \frac{d \mathcal{Y}_0(\varepsilon)}{h d\overline{\mathbf{y}}}.$$

Let us introduce the notation

$$\frac{\widetilde{U}_{\bullet}(\mathbf{E})}{\mathbf{E}^{\prime}+\mathbf{E}U_{\bullet}(\mathbf{E})}=V_{\bullet}(\mathbf{E}). \tag{12}$$

in a

Then equation (11) has the form

$$(1 - \mathbf{F}^{0}) \frac{dV_{e}}{dE} + \mathcal{A}_{e}(\mathbf{F}) V_{e}(\mathbf{E}) + \frac{\mathcal{B}_{e}(\mathbf{E})}{3} \int \frac{V_{e}(\mathbf{F}_{e}) d\mathbf{F}_{e}}{\sqrt{1 - \mathbf{F}_{e}^{2}} (\mathbf{E}_{e} - \mathbf{F})} = f(\mathbf{F}),$$
(13)

Here

$$\mathcal{A}_{\bullet}(\mathbf{E}) = \frac{\varepsilon}{\mathfrak{F}(t+\varepsilon u_{\bullet})^{T_{\bullet}}} \left[\frac{S_{in} \mathcal{Q}_{\bullet}}{t+\varepsilon u_{\bullet}} - \frac{C_{ob} \mathcal{Q}_{\bullet} \sqrt{t-\mathbf{E}^{\bullet}}}{\mathfrak{F}} \right]$$

$$* \int_{1}^{t} \frac{d\mathbf{E}_{t}}{(t+\varepsilon u_{\bullet}) / |\mathbf{E}_{t}-\mathbf{E}| \sqrt{t-\mathbf{E}^{\bullet}}} - \frac{\varepsilon (t-\mathbf{E}^{\bullet})}{t+\varepsilon u_{\bullet}} \frac{d\mathcal{Y}_{\bullet}}{hd\mathbf{E}^{\bullet}}$$

$$(13,1)$$

 $B_{\bullet}(\mathbf{x}) = -\frac{\varepsilon}{\pi} \frac{\cos \theta_{\bullet} \sqrt{1 - \varepsilon^{2}}}{(1 + \varepsilon u_{\bullet}(\mathbf{x}))^{3/2}}, \qquad (13.2)$

$$f_{o}(\overline{p}) = -\frac{2}{g(1+\varepsilon u_{0})^{3/2}} \left[\sin \theta_{0} + \cos \theta_{0} (\theta_{0} - \theta_{1} + \frac{1}{\sqrt{1-p^{2}}} (\theta_{1} - \theta_{1})^{3/2} \right] - \frac{1-\overline{p^{2}}}{1+\varepsilon u_{0}(\overline{p})} \cdot \frac{d y_{0}}{h d \overline{p}} \cdot (13.3)$$

The obtained linear singular kernel integral-differential equation is solved under the secondary condition

$$V_{\bullet}(1-\delta) = 0 \tag{14}$$

at interval (-1.3,1-3), . ($\delta > o$ is a fairly small number).

Solving equation (13) taking condition (14) into account, we find $V_{(f)}$ and $V_{(f)}$ is determined in conformance with formula (12)

$$\frac{y_{*}(\mathbf{F})}{h} = \frac{y_{*}(\mathbf{F})}{h} + \left[1 + \varepsilon \, \mathcal{U}_{*}(\mathbf{F})\right] V_{*}(\mathbf{F}), \qquad (15)$$

 $\theta_{n}(\mathbf{s})$ is found from expression (10) by means of the computation of singular integrals

$$\Theta_{\epsilon}(\boldsymbol{F}) = \Theta_{\epsilon}(\boldsymbol{F}) + F_{\epsilon}^{*}(\boldsymbol{F}) - \frac{\varepsilon \sqrt{t-\boldsymbol{F}^{*}}}{2\sigma} \int \frac{V_{\epsilon}(\boldsymbol{F}_{\epsilon})}{\sqrt{t-\boldsymbol{F}^{*}_{\epsilon}}} \frac{d \boldsymbol{F}_{\epsilon}}{\boldsymbol{F}_{\epsilon}-\boldsymbol{F}} \qquad (10.1)$$

After obtaining $\theta_{i}(p)$ and $y_{i}(p)$ the unknown $x_{i}(p)$ is computed, according to the first equation from (7), using the simple quadrature

$$\frac{dx_{t}}{hd\xi} = -\frac{2}{\mathcal{F}(t-\xi')} \frac{\cos\theta_{t}}{(t+\varepsilon t_{t})^{4/2}}$$
(16)

under the secondary condition

$$x_{\ell}(t-\delta) = x_{n} \tag{17}$$

Here

$$x_{n} = -\frac{2B_{i}h}{3} \int_{0}^{t} \left[\frac{\pi (\pi + B_{i}B - \sqrt{B_{i}^{2} - \Xi^{2}} \sqrt{B^{2} - I})}{(B_{E} + B_{i})(B_{i} - \sqrt{B_{i}^{2} - \Xi^{2}})} \right]^{t/2} \frac{d\pi}{B_{i}^{2} - \Xi^{2}},$$

 $\beta, \beta_i > 1$ are the abscissae of point B and the point which lies between A and F on plane t, respectively. Calculation is made with B = 5 and $\beta_i = 1, 01$.

Let us look for the solution of the problem in question (13)-(14) in terms of

$$V_{o}(\varepsilon) = \sum_{m=0}^{N} a_{m} T_{m}(\varepsilon), \qquad (19)$$

where $T_m(\mathbf{s})$ are Chebyshev polynomials of the first kind, α_m are the coefficients still unknown.

We find

$$\frac{dV_0}{dE} = \sum_{m=0}^{N} a_m T_m'(E) = \sum_{m=0}^{N} a_m m \mathcal{U}_{m-1}(E), \qquad (20)$$

where $u_{m,l}(\mathbf{E})$ are the Chebyshev polynomials of the second kind.

Substituting the relationships (19) and (20) into equation (13), considering the following equality [3]

$$\mathcal{U}_{m-s}(\mathbf{E}) = \frac{1}{g} \int \frac{T_m(y)}{\sqrt{t-y^2}} \frac{dy}{y-\mathbf{E}},$$

we obtain the transcendental equation

$$\sum_{m=0}^{N} \alpha_m [m(1-\Xi^2)\mathcal{U}_{m-s}(\Xi) + A_0(\Xi)T_m(\Xi) + B_0(\Xi)\mathcal{U}_{m-s}(\Xi)] = f_0(\Xi),$$

from which for determining the coefficients a_m , substituting $\mathbf{5}$ - \mathbf{F}_i ($\mathbf{F}_i = -Cos \frac{\mathbf{F}_i}{N}$ are the colocation points), we arrive at the algebraic system

$$\sum_{m=0}^{N} a_m C_{nm} = \delta_n \, . \quad (n = 0, 1, 2, \dots, N-1), \tag{21}$$

where

$$C_{nm} = A_0(F_n)T_m(F_n) + [m(1 - F_n) + B(F_n)]u_{m,1}(F_n),$$

$$B_n = f_0(F_n). \qquad (22)$$

Here $u_{i}(f)=0$, $u_{-i}(f)=0$, $\overline{T_{i}(f)}=1$. The coefficients $V_{i}(f)$ are determined from the set of algebraic equations (21).

The Newton-Kantorovich method used has a quadratic convergence, the convergence of the process depending essentially on how well the initial approximation has been selected. The solution of a specific problem for a weightless liquid was taken as the initial approximation, which is considered most appropriate. Calculations were conducted on a "Minsk-22" computer for $\mathcal{E}=0,01$, $\mathcal{E}=0,2$ with x=4:2 and for $\mathcal{E}=0,04$; $\mathcal{E}=0,2$;

Numerical calculation shows that in the case x=4:2 iteration converges for $\xi=0.4$ in the third approximation, and for $\xi=0.2$ in the fourth approximation. But if x=4:4, then the iteration converges for $\xi=0.4$ in the third approximation and for $\xi=0.2$ in the fifth approximation.

In our calculations we were guided by the following: the process of iteration was terminated when the following conditions had been met

> 1 acre - scil ≤ 2.10", 1 yere - yel = 7.10", i=0,1.2,...

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