1.0

4.5
5.0
5.6
6.3

2.8

2.5

1.1

3.2

3.6

4.0

2.2

2.0

1.8

1.25

1.4

1.6

MICROCOPY RESOLUTION TEST CHART
NATIONAL BUREAU OF STANDARDS-1963-A

LEVEL Ⅱ

AD-E300 408

DNA 4351T-1A

A PREFERRED CONCEPT FOR T-COR COMMO

The BDM Corporation
7915 Jones Branch Drive
McLean, Virginia 22101

15 May 1978

Topical Report for Period for 24 March 1977— 14 August 1977

CONTRACT No. DNA 001-76-C-0371

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Prepared for
Director
DEFENSE NUCLEAR AGENCY
Washington, D. C. 20305

REPORT DOCUMENTATION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM

1. REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
DNA 4351T-1A		

4. TITLE (and Subtitle)	5. TYPE OF REPORT & PERIOD COVERED
A PREFERRED CONCEPT FOR T-COR COMMO	Topical Report, for Period 24 Mar 77 —14 Aug 77.
	6. PERFORMING ORG. REPORT NUMBER
	BDM/W-77-402-TR

7. AUTHOR(s)	8. CONTRACT OR GRANT NUMBER(s)
Ralph H. Schmidt William E. Sweeney, Jr. Ronald L. Rothrock Patrick H. Riedl	DNA 001-76-C-0371

9. PERFORMING ORGANIZATION NAME AND ADDRESS	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS
The BDM Corporation 7915 Jones Branch Drive McLean, Virginia 22101	NWED Subtask 099QAXCA107-10

11. CONTROLLING OFFICE NAME AND ADDRESS	12. REPORT DATE
Director Defense Nuclear Agency Washington, D.C. 20305	15 May 1978
	13. NUMBER OF PAGES
	76

14. MONITORING AGENCY NAME & ADDRESS(if different from Controlling Office)	15. SECURITY CLASS (of this report)
	UNCLASSIFIED
	15a. DECLASSIFICATION DOWNGRADING SCHEDULE

16. DISTRIBUTION STATEMENT (of this Report)

Approved for public release; distribution unlimited.

17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)

19. KEY WORDS (Continue on reverse side if necessary and identify by block number)

T-COR	Nuclear Weapons Effects
Communications Modeling	Weapons Effects
War Games	

20. ABSTRACT (Continue on reverse side if necessary and identify by block number)

This report elucidates a preliminary concept for a T-COR theater combat communications module which, when exercised with other T-COR modules, will provide a capability for improved assessment of the impact of communications on combat effectiveness.

DD FORM 1473   EDITION OF 1 NOV 65 IS OBSOLETE   UNCLASSIFIED

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PREFACE

This final report is submitted to the Defense Nuclear Agency, ATTN: Captain Frank Eisenbarth, (VLIS), Washington, D.C. 20305, as a deliverable under the terms of contract number DNA001-76-C-0371-P00002.

This report was prepared by Ralph H. Schmidt, Ronald L. Rothrock and William E. Sweeney, Jr., under Program Manager Patrick H. Riedl of The BDM Corporation.

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CHAPTER 1

OVERVIEW

CHAPTER I

OVERVIEW

1.1   Summary

This report provides a preliminary concept for
a T-COR theater combat communications module
which, when exercised with other T-COR modules,
will provide a capability for improved assessment
of the impact of communications on combat
effectiveness.

The specific objectives of this conceptual design effort are summarized in the figure. The principal study effort was oriented toward defining an architectural framework for a T-COR module to permit communications assessment.

In order to provide a communications assessment tool for incorporation into T-COR, it was first necessary to identify those requirements placed on the communications model by T-COR itself and by the communications systems and processes that must be modeled. Discussion of these requirements is provided in Chapter II.

A series of basic concepts for the T-COR COMMO module were developed and compared with the requirements. For each fundamental approach it was necessary to define the basic interactions between T-COR and T-COR COMMO as well as the response of T-COR COMMO to the combat environment. For the preferred concept it was necessary to address the levels of detail both conceivable and desirable. This allows the development of a basic T-COR COMMO module which preserves the speed of the basic T-COR model. Additional levels of detail allow for increased sophistication of the module as deemed appropriate from initial exercising of the module. In developing the preliminary concept, careful consideration of the software currently in T-COR was necessary to identify any implementation problems inherent in various design approach alternatives and to assist in the selection process and definition of data requirements. Detailed discussion of the T-COR COMMO module prefered concept is provided in Chapter III.

Finally, an implementation plan for the basic T-COR COMMO module is outlined in Chapter IV.

- **IDENTIFY T-COR REQUIREMENTS**
- **DETERMINE T-COR COMMO CONCEPT**
  - Fundamental Approach
  - Interactions with T-COR
  - Combat Environment Interactions
  - Levels of Detail
  - Modeling Problems
  - Data Requirements
- **IMPLEMENTATION**

Figure 1.1. Summary

1.2   Why T-COR COMMO?

The contribution of communications to combat effectiveness can not be determined by direct analysis; therefore representation of communications in a player centered combat simulation such as T-COR is necessary to obtain force multiplier quantification.

Command, Control, Communications and information flow processes are vital to the conduct of military operations; however, actual measurements of the contribution of the processes to combat effectiveness are difficult. An advanced theater combat model called T-COR-II is under development for the Defense Nuclear Agency. T-COR-II will simulate combat dynamics in the Corps area under both nuclear and non-nuclear situations. The design and incorporation of a communications model in T-COR-II will serve as a valuable computational tool in determining the value of communications to the Corps and Division commander as well as quantifying the impact of vulnerabilities and degradation effects induced into the network by nuclear events. The contribution of communications can be determined in terms of measures of effectiveness (MOE) relating to such factors as personnel casualties, equipment attrition, and unit movement.

The T-COR COMMO module discussed herein will be capable of simulating the characteristics of any foreseeable communications system from Corps to the maneuver companies and calculating delays in message flow/information transfer caused by communications handling procedures, transmission, hostile countermeasures, and other environmental effects. These delays will affect the time of receipt of operations orders and internally generated messages thus influencing artillery targeting, unit reinforcement, unit movement and other combat factors. The end result will be to impact the above mentioned measures of effectiveness.

The communications networks simulated by the COMMO module will transmit messages after a delay time commensurate with the available communications capability and the level of jamming or firepower attacks against elements of the communications system. Alternate routings and message expiration times are also considered. Each of the communications nodes within a network can be attacked and sustain varying levels of damage. In addition, communications status can be extracted from the module to serve as a decision aid in the T-COR model.

Development of T-COR COMMO will provide a valuable measure of the impact of loss and/or degraded communications on tactical combat that is not available in current communications models such as ETC[3] (European Theater Command, Control and Communications). Hence T-COR COMMO will serve as the critical link between the detailed communications degradation analysis conducted in the INCA (Integrated Nuclear Communications Assessment) program using ETC[3] and the combat effectiveness measures which result from the T-COR simulation.

1-4
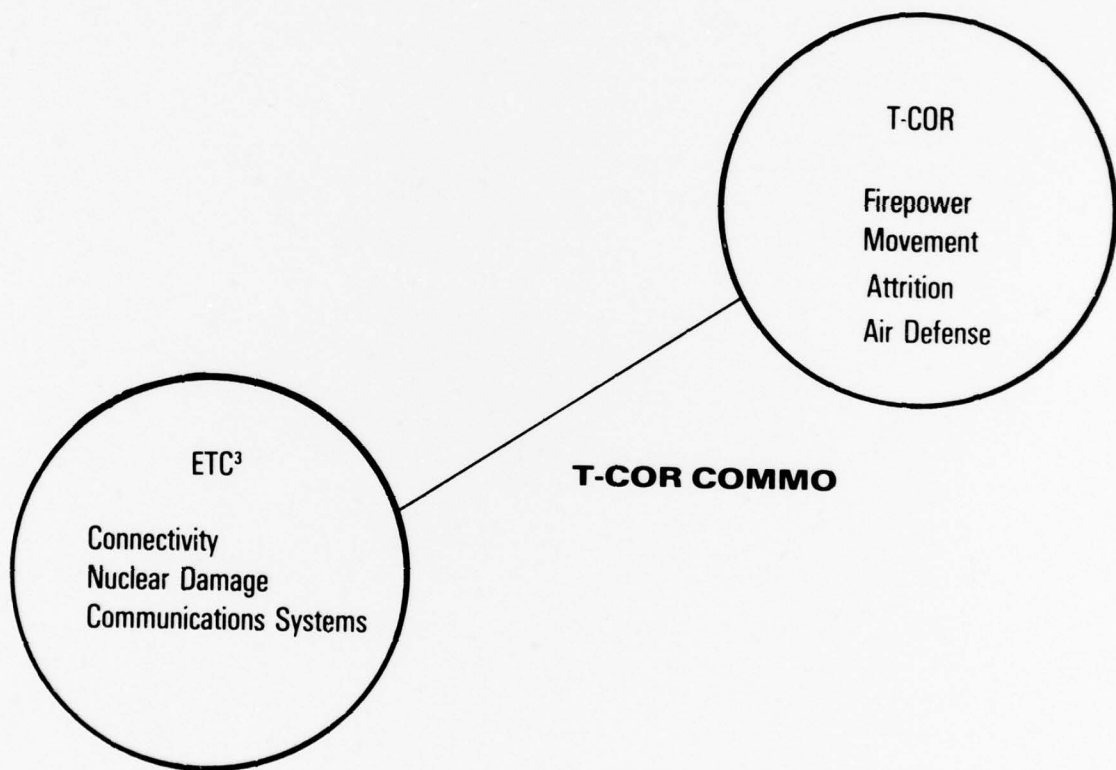
Figure 1.2.   Why T-COR COMMO ?

1.3   Scope

The scope of the T-COR communications module
is bounded by the characteristics of T-COR.

The general relationship of T-COR COMMO with other T-COR
elements is shown in the figure. Essentially, T-COR COMMO accepts
messages generated by C^2 nodes and delivers then to the addressee after
an appropriate time delay. The time delay is affected by system
perturbations due to the combat environment. Thus the scope of the analyses
that can be conducted using T-COR COMMO are bounded by the level of detail
contained within the T-COR C^2 node and combat modules utilized. For example,
the impact of the loss of communications to a engineer support element can
not be evaluated if that element is not explicitly represented in T-COR,
no matter what level of detail is contained within T-COR COMMO.

The scope of the conceptual T-COR COMMO module is also shown in
the figure. This module considers players from Corps to line company
echelons and their associated communications systems. The messages generated
by the C^2 modules are of variable description (i.e., they may specify any
or all of the following attributes: address, precedence, length,
classification, transmission system). The combat environments represented
include nuclear, EW, and conventional. All three primary types of
communications used at Corps and below are represented. Radio communications
include satellite links and multi-channel terrestrial links as well as
single channel nets.

Although not explicitly stated, the model can represent
communications between Air Force units located in the Corps area of
operations and between Army and Air Force units.

```
┌ ─ ─ ─ ─ ─ ─ ─ ─ ─ ┐
  ILLUSTRATIVE
│                   │
  T-COR ELEMENTS
│  ┌─────────┐      │        ┌─────────┐        ┌─────────┐
      C²                       COMMO              C²
│  │ NODE    │ ─MESSAGE─→  │ │ MODULE  │ ─────→  │ NODE    │ │
      #N                                          #M
│  └─────────┘      │        └─────────┘        └─────────┘
                              ↑
└ ─ ─ ─ ─ ─ ─ ─ ─ ─ ┘  ┌──────────────────┐
                       │ COMBAT ENVIRONMENT │
                       └──────────────────┘
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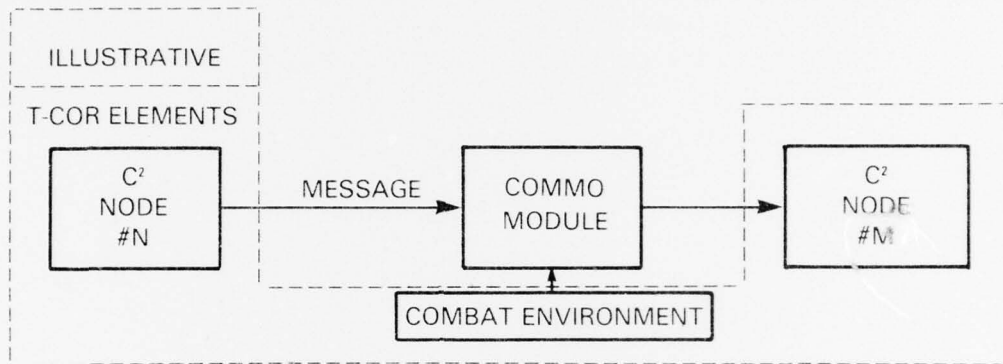
SCOPE

COMMAND ECHELON: Corps ⟶ Line Company

MESSAGE CHARACTERISTICS: Variable, function of level of detail of C^2 node representation

COMBAT ENVIRONMENT: Nuclear, EW, and Conventional

TYPE COMMUNICATIONS: Radio, Wire, Messenger

Figure 1.3.   Scope

CHAPTER II

T-COR COMMO REQUIREMENTS

CHAPTER II

T-COR COMMO REQUIREMENTS

2.1   Introduction

The T-COR COMMO module must be responsive to
the communications systems which are found at
CORPS and below, the C^2 functions played in
T-COR, the combat environment, and the basic
T-COR architecture and computer coding.

The fundamental concept for the T-COR COMMO module must be
designed to accomodate a broad spectrum of communications capabilities and
systems. The basic types of systems will vary from single user dedicated
circuits to multichannel, multiuser systems. Transmission media include
radio, wire and messenger. The types of messages include voice, data, hard
copy, and graphics. The T-COR COMMO concept is fully capable of handling
all of these systems, media, and messages.

T-COR generates specific information requirements related to
the issuance and receipt of high priority messages which effect the play of
the game. T-COR COMMO must provide a rapid technique that efficiently supports
the main game played by T-COR. Additionally, the T-COR COMMO module will
be developed so as to enhance the capabilities of T-COR by providing a
more realistic impact of communications processes on the conduct of the battle.

In addition to improving the T-COR main game, the T-COR COMMO
module will provide initial answers to the important question of the impact
of communications losses on the conduct of the battle. To achieve this goal,
T-COR COMMO must be sensitive to the combat situation. The T-COR COMMO
concept includes direct interaction with the nuclear, EW, and conventional combat
environments. Specific combat events will cause T-COR COMMO to assess the
impact on communications capabilities and provide the data to the main T-COR
routine.

Finally, the efficient design of T-COR COMMO requires that the
module be structured to fit into the basic T-COR software. In particular,
T-COR COMMO will access the T-COR Automated Data Base for information and
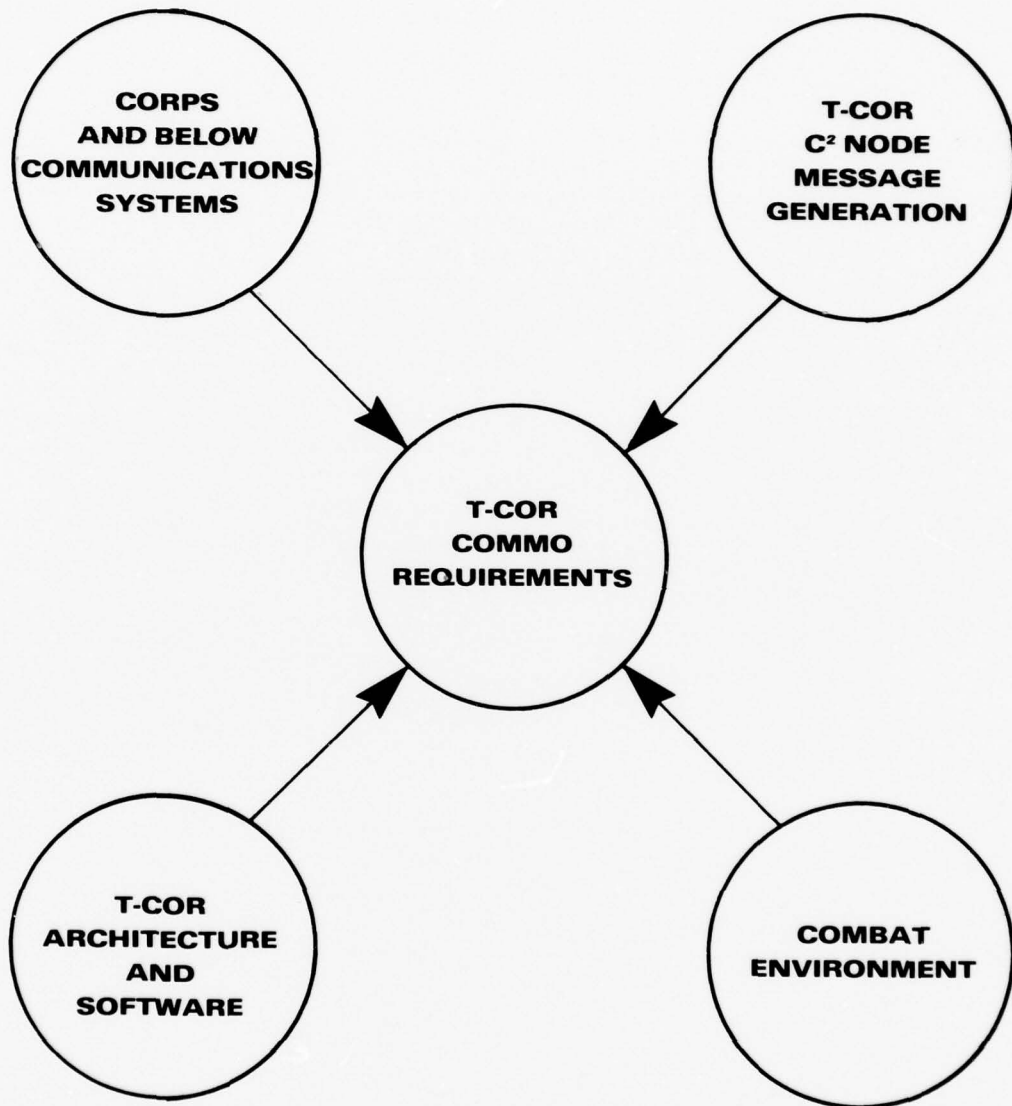be fully integrated into the Simulation Control Software.

Figure 2.1.   T-COR COMMO Requirements

2.2 Tactical Communications Types

Tactical communications from the Corps to
the line companies is diverse in communications
systems, transmission media, and types of messages
transmitted.

The principal means of communications at Corps and below is via
radio. The major radio systems include single channel voice nets, single
channel radioteletype nets and both low and medium capacity multichannel systems.
The multichannel systems carry both sole user and common user voice circuits
as well as data circuits. The T-COR COMMO module must be designed to model
the communications processes over systems as widly diverse as single channel
radioteletype and multichannel common user voice.

The transmission media used at Corps and below for the radio systems
include LOS microwave, tropospheric scatter, satellite, HF (groundwave and
skywave), VHF FM and UHF AM (Air-Ground). T-COR COMMO will include combat
environment interaction routines that will be sensitive to the type of
equipment and type of transmission media used. The nuclear effects and
electronic warfare effects routines must provide information to T-COR which
accounts for the transmission media used.

T-COR COMMO must also have the ability to model information
transfer for messages of varying lengths with a variety of different
preparation and handling. For instance, the time delay associated with
voice messages may consist only of the time necessary to establish a voice
link connection whereas the preparation time for a radioteletype message
may play a significant role in the overall message transmission time.

Finally, Corps and below communications includes an overlay of
both special and scheduled messenger capability. This capability can play
a significant roll in the transfer of long messages and map related
information. Messenger capability includes motor, air, and foot delivery
and is highly dependent on enemy action, weather, terrain, and physical
locations of the involved units.

2-4

RADIO/WIRE
SINGLE CHANNEL/MULTICHANNEL
VOICE/DATA/FACSIMILE/RATT
LOS/GROUNDWAVE/TROPO/
　　　SATELLITE/SKYWAVE
MESSENGER
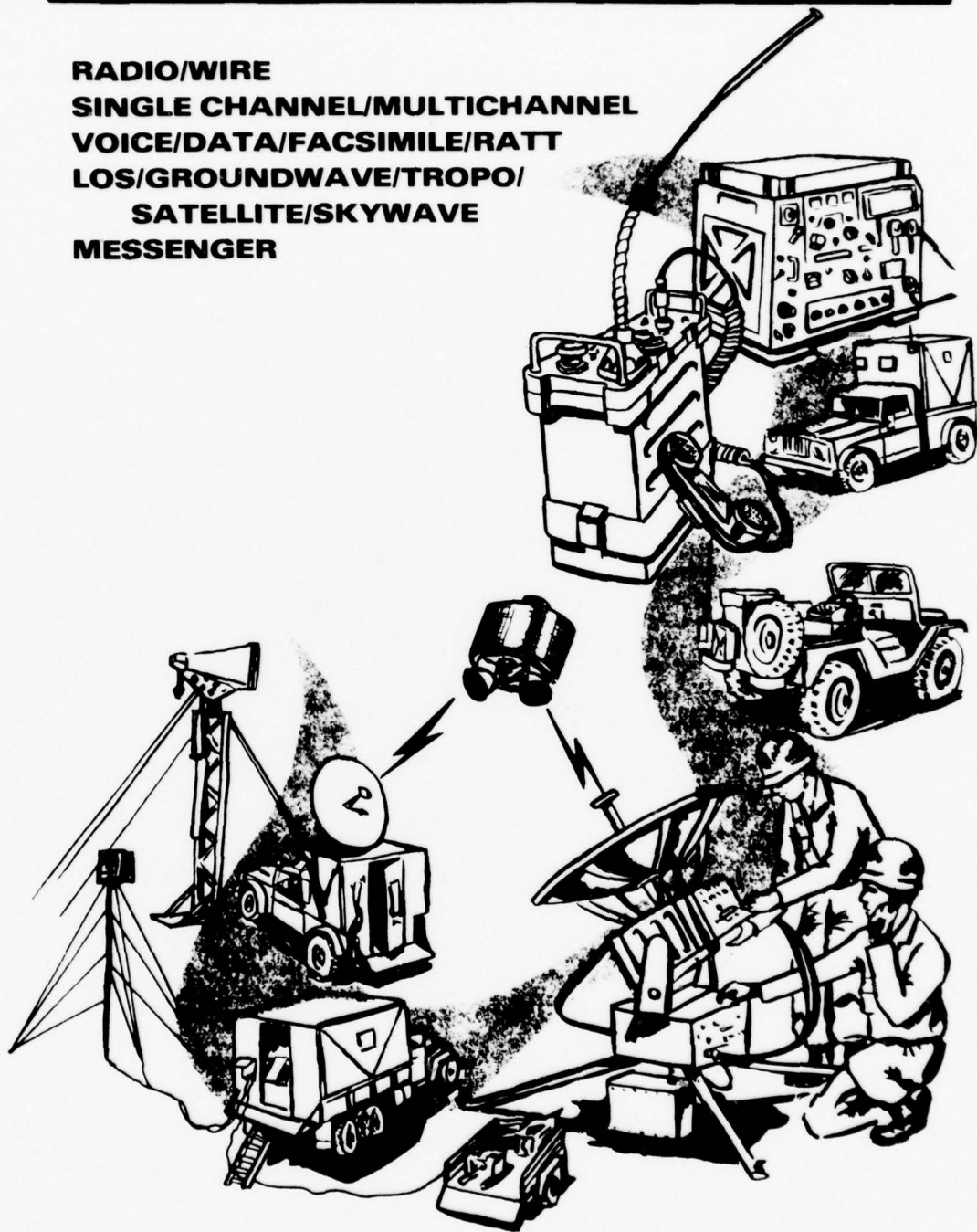
Figure 2.2.　Tactical Communications Types

2.3   Corps Command Communications

        The Corps command communications system is composed
        of a broad spectrum of capabilities and equipments
        in order to meet the communications requirements
        from Corps to the maneuver units.

        A typical distribution of Corps command communications is shown
in the figure. As one proceeds from Corps to the maneuver units, the available
communications connectivities become less redundant with much lower
capacity. Single channel FM capability is observed to be present at all
echelons of command whereas multichannel capability is observed only at
the higher echelons.

        T-COR COMMO models all of the communication means shown in the
figure to at least a first-order level of detail. The inclusion of
messenger-type communication (physical delivery by aircraft, vehicle or foot
soldier) in T-COR COMMO is deemed necessary for completeness and logical
because of interplay with electronic means.

        Though not explicit in this figure, both voice and record data
systems throughout the Corps can be played in T-COR COMMO.
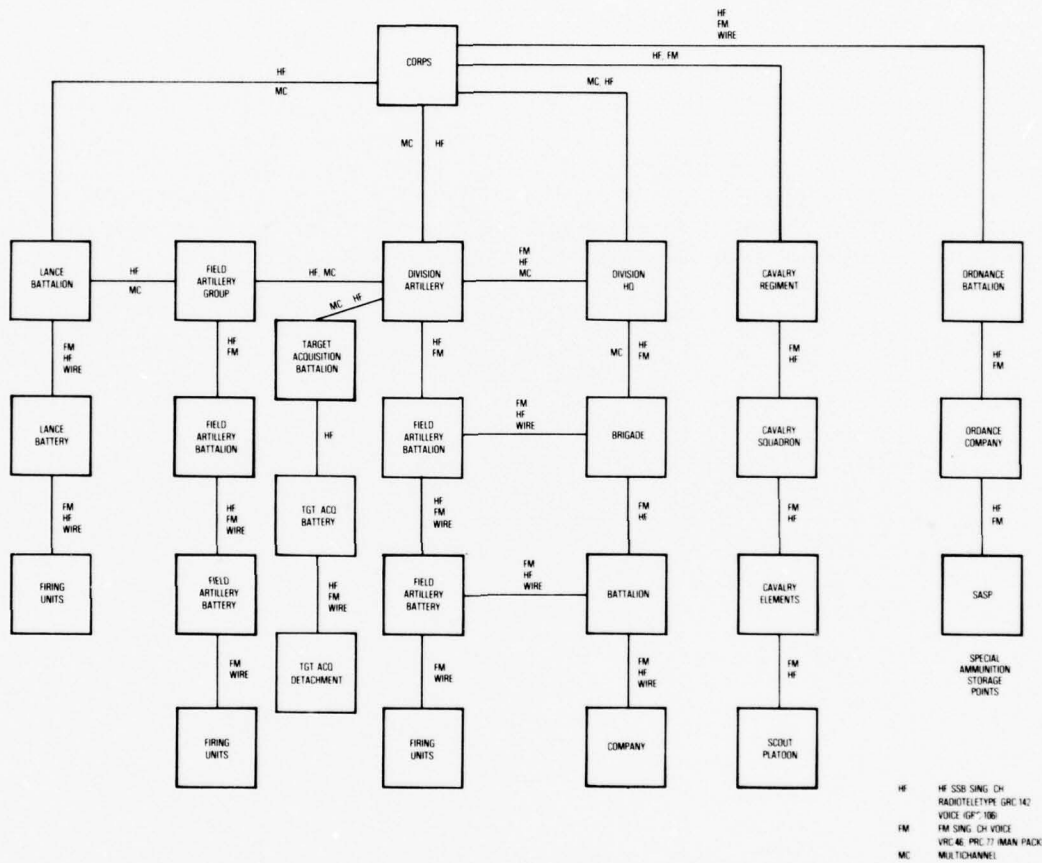
Figure 2.3. Corps Command Communications

2.4   Multichannel Systems (Command and Area)

Corps and Division Multichannel systems provide command and control links and additional area communications capability which is available for command utilization.

In addition to the command communications systems discussed previously, there are extensive multichannel communications capabilities available in both the command and area systems established in the Corps/ Division area. Although established primarily to service administrative and logistics traffic as well as attached units, the Corps area system provides additional capability for command/control utilization.

A stylized configuration of the command multichannel (light lines) and Corps area systems (dark lines) is shown in the figure. Internetting provides the capability of utilizing the Corps area system for command/ control traffic.

T-COR COMMO will be designed to model the current multichannel systems, and via expansion of the basic approach, additional systems such as TRITAC.

2-8

TYPE DEPLOYMENT
TACTICAL FIELD RADIO RELAY SYSTEMS
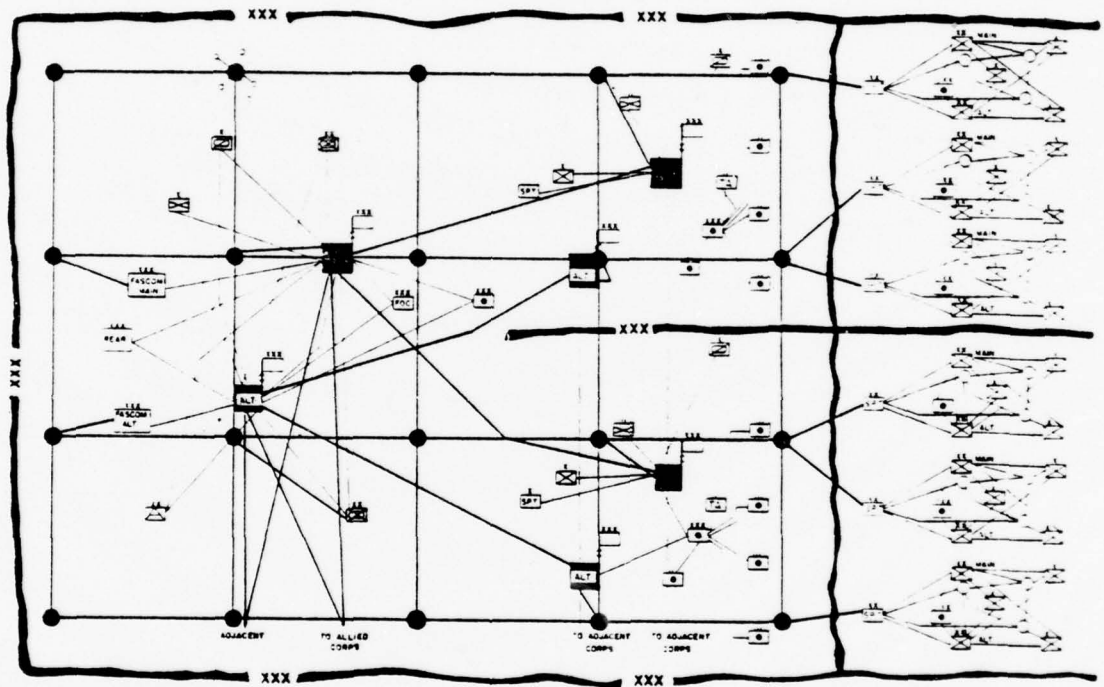
Figure 2.4. Multichannel Systems (Command and Area)

2.5   Tactical Operations Center

A typical tactical operations center, e.g. a division tactical
operations center (DTOC), generates a high volume of messages.

Typical elements of a DTOC and their communications connectivities
are shown in the figure. A high volume of message traffic flows within
the DTOC and to both higher and lower echelons. In addition to voice
traffic, substantial quantities of record traffic, data, maps, overlays,
photographs, etc is transmitted within and external to the TOC. Similar
functions are performed at a Corps TOC and within the command/staff
elements at Division and below.

T-COR COMMO will not model in detail the full operation of a tactical
operations center but rather will address the critical messages and functions
which impact on the play of the T-COR model.

T-COR COMMO will reflect the internal communications of a TOC by
impacting on the quality and timeliness of messages that are received or
transmitted by the TOC.

DTOC

MESSAGES GENERATED

TYPE	ROUTING
Voice	Sole User Telephone
	Common User Telephone
	Radio
Text Message	Point to Point TTY
	RATT
	TTY Relay
	Messenger
Map, Overlay, etc	Facsimile
	Messenger
Data	Data Circuit
	Messenger

G2 G3 Higher HQ ◄—— **G2CM&D G3 OP** ——► Div TAC CP
SWO Higher HQ ◄—— ——► S2 S3 Subordinate HQ
——► CI ELEMENTS

◄—— **FSE** ——► Div TAC CP
FSC ◄—— ——► DIVARTY
◄——

DASC ◄—— **TASE** ——► TACP
——►

Higher HQ ADA ◄—— **AME** ——► Subordinate ADA HQ
FOC ◄—— ——► Airfield
FCC ◄——

USASA ◄—— **ATSE G2A&P** ——► EW Units
Higher HQ SSO ◄—— ——►
Other Special-circuits ◄—— ——► II Unit

Higher HQ G1 G4 ◄—— **G1 G4** ——► Division Rear
FASTS ◄—— ——► DISCOM
——► CSS Element
(Div TAC CP)

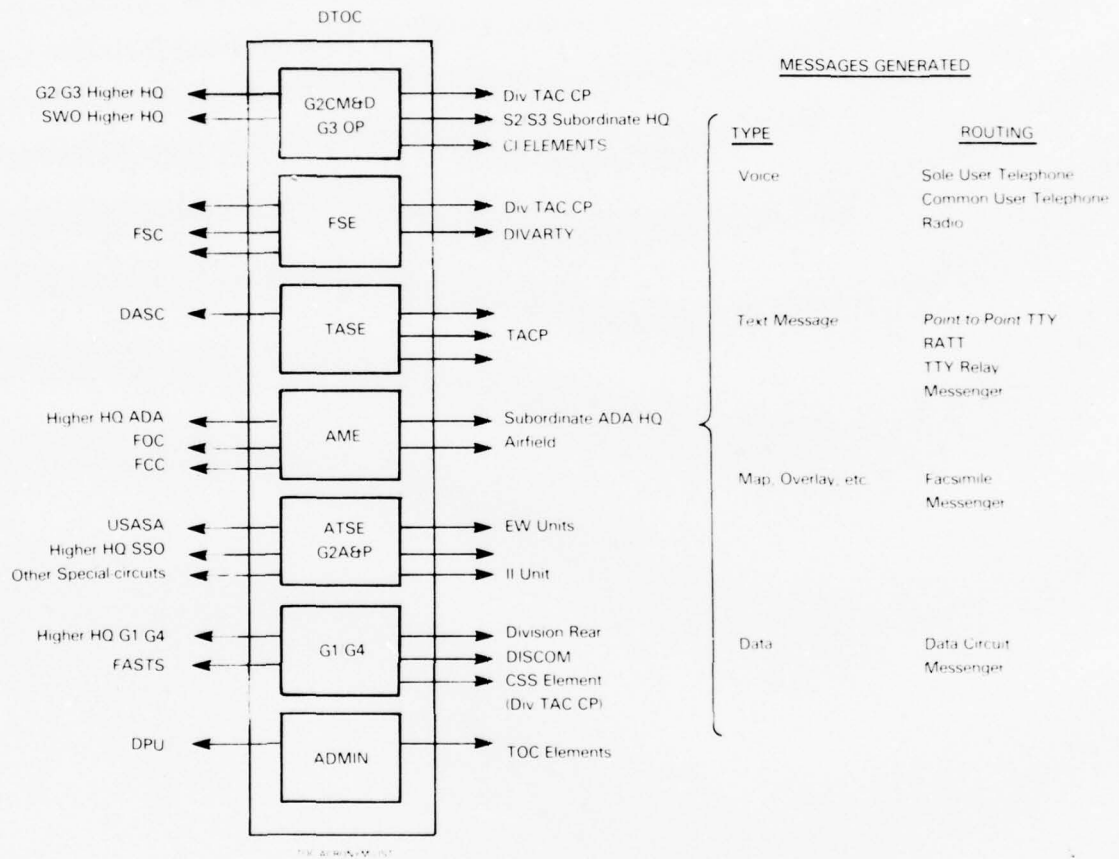DPU ◄—— **ADMIN** ——► TOC Elements

Figure 2.5. Tactical Operations Center

2.6   T-COR Phase II Messages

        The T-COR Phase II command and control modules
        aggregate all TOC elements into one entity and
        limit message generation to operations orders,
        status reports and intelligence reports.

        Within the T-COR model, tactical operations centers are considered
to be a single entity with respect to location and function. Interaction
with other C^2 elements is restricted to critical messages which have
significant impact on the conduct of the battle. These critical messages
include operations orders, status reports, and intelligence reports.

        T-COR COMMO will account for the additional traffic that is known
to exist within and between C^3 nodes but will not explicitly model the
information transfer associated with the background traffic. However
the background traffic, implicit in the T-COR COMMO model, will effect the
handling, routing, and transmission of the critical messages.
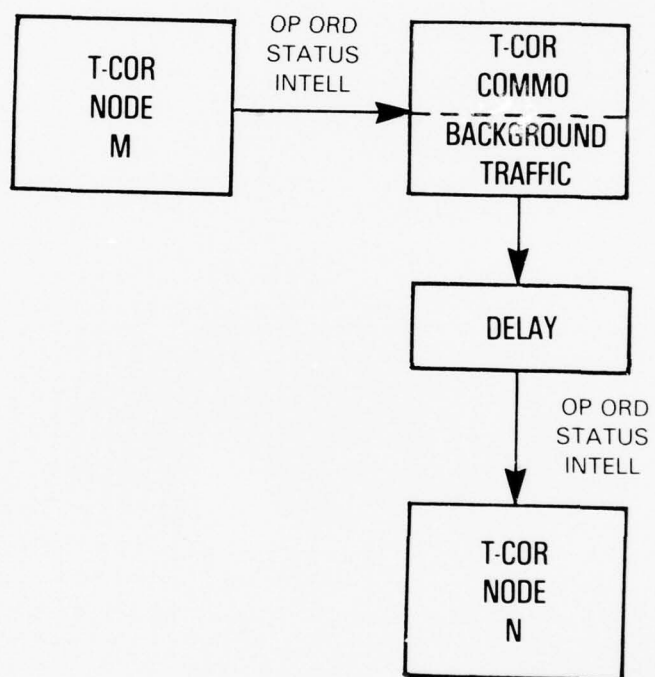
Figure 2.6.   T-COR Phase II Messages

2.7   T-COR COMMO Functions

T-COR COMMO will support the efficient play
of T-COR, provide communications degradation
information to impact the course of the battle,
and provide communications status information
for automatic or interactive play.

At the broad conceptual level there are three primary
interactions between T-COR and T-COR COMMO. During the play of the T-COR
main game, critical messages are generated at C^2 nodes for delivery to
other C^2 nodes. Upon receipt of instructions that T-COR desires to
transmit a message from one node to another, T-COR COMMO determines the
availability of the primary or alternate delivery capabilities, determines
the delay associated with the message and provides that information to
T-COR. T-COR then continues with the play of the main game.

A second function of T-COR COMMO is to quantify the effects on
communications of a variety of combat related events. For simplicity only
enemy and friendly action have been shown, although this interaction is
capable of addressing other environmental or operational effects such as
weather and increased traffic levels. In this type of interaction T-COR provides
to T-COR COMMO specific information relating to the conduct of the battle
(e.g., a series of nuclear detonations). T-COR COMMO then assesses the
impact of these battle actions and modifies, as appropriate, message time
delays for subsequent use in the main game.

The third type of interaction is the provision of communications
status from T-COR COMMO to T-COR. This interaction is the equivalent of
a commander asking his communications officer to report on the communications
status with respect to the capability to interact with subordinate and
higher commands. The status as reported by T-COR COMMO (the communications
officer) can then be used by T-COR (the commander) as a basis for decisions.
Within T-COR the decision process can be made automatically by the software
or via the man-in-the-loop when operating T-COR interactivity.

MAIN GAME

| T-COR | → MESSAGE → | T-COR COMMO |
| CONTINUE | ← DELAY ← | DETERMINE DELAY |

COMBAT ENVIRONMENTAL EFFECTS

| T-COR | → ENEMY ACTION / FRIENDLY ACTION → | T-COR COMMO |
| | | MODIFY DELAYS |

COMMUNICATIONS STATUS

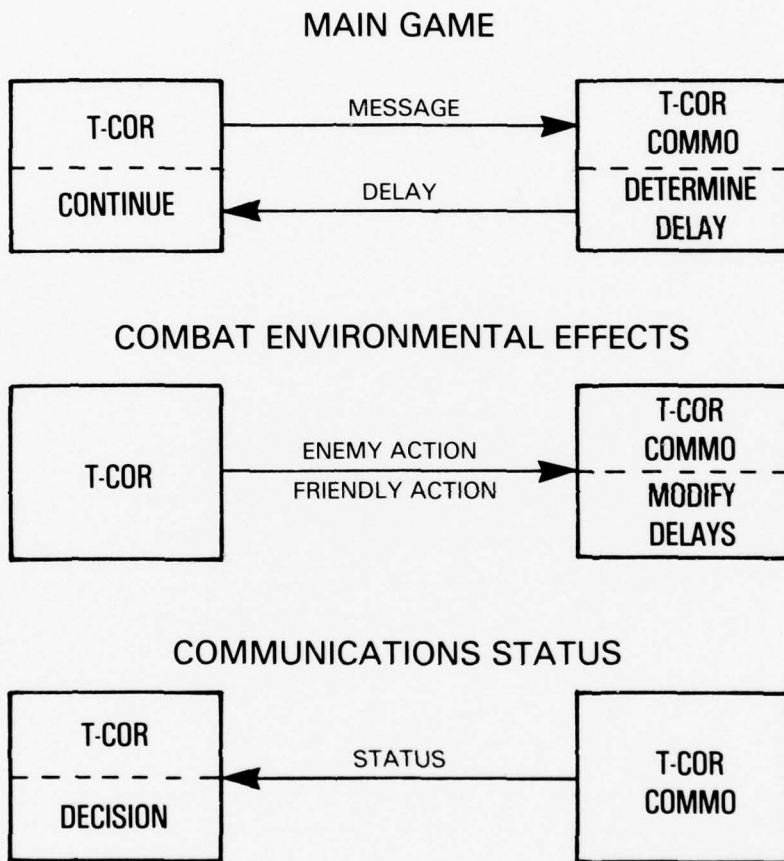| T-COR | ← STATUS ← | T-COR COMMO |
| DECISION | | |

Figure 2.7.   T-COR COMMO Functions

2.8 Combat Environment

A major design feature of T-COR COMMO is the incorporation of a methodology for representing the impact of combat dynamics on communications.

A principal objective of the T-COR COMMO module is to provide the tool by which the impact of communications capability can be measured in terms of force combat effectiveness. In order to accomplish this objective, it is necessary that T-COR COMMO model the status of communications as a function of the state of the battle as modeled in T-COR. This will require not only close interaction with the T-COR main game but also special routines which translate T-COR combat actions into communications gains and losses.

The nature of the combat environment representations in T-COR COMMO will be determined to a large extent by the combat representions in T-COR. The location of communications nodes is governed in part by the hexagonal grid coordinate system employed in T-COR. The minimum hex size for the Corps area model is 1.35 km (center-to-center). Hence C^3 elements will be located within this grid system. T-COR allocates conventional weapons on an area basis and calculates damage as a percentage loss to all units in the area. T-COR COMMO will translate conventional losses as provided by T-COR into changes in communications capability.

For nuclear bursts, T-COR will provide a hex grid identification, and required weapon burst parameters such as yield, height of burst, time of burst. T-COR COMMO combat effects subroutines will convert this information into communications losses. The basic data to support the nuclear combat effects subroutines will be derived from the detailed results of the tactical assessments conducted under the INCA program.

Electronic warfare can also cause significant degradations in communications capability. The T-COR COMMO module will also include jamming subroutines as part of the combat environments capability. Finally, the movement of combat units impacts not only on their combat effectiveness but also on their communications capability. Hence, data on unit movement provided by T-COR can be used to update communications status to reflect loss of capability during movement. Further discussion of the concepts for the combat environment modules is found in Chapter III.

CONVENTIONAL
    Equipment Loss
    Personnel Loss
NUCLEAR
    Personnel Loss
    Blast
    Nuclear Radiation
    EMP
    Blackout
ELECTRONIC WARFARE
    Jamming
    Destruction of Jammers
UNIT MOVEMENT

Figure 2.8. Combat Environment

2.9   T-COR II Architecture

        T-COR COMMO must fit within the basic T-COR
        Phase II architecture.

        The key architectural features of T-COR*which influence T-COR
COMMO design are the use of a common simulation control structure, process
modules without hard coded data, a used oriented input language, and a
flexible data structure.

        Input is achieved by means of a user oriented input language (UOIL)
using subject, verb and object phrases. The Red and Blue sides are identified
by an introduction line followed by the unit identification, location and
command structure. Other input data such as terrain and communication network
descriptions, for example, would be described in similar form.

        The Scenario Selection Processor (SSP) is the interface for the
user to initialize the execution of T-COR. The user identifies the
data in the Automated Data Base (ADB) that is to be used and specifies any
additions or modifications required for the specific scenario. The Input
Processor (IP) locates the appropriate data, merges the ADB and SSP Infor-
mation and creates the initial Simulation Data Structure (SDS).

        The input data is stored in a dynamically-allocated data space which
grows, shrinks and is reused depending on the actual requirements for
space during input or execution. This is accomplished by use of list pro-
cessing techniques and eliminates the requirement to edit and change modules
when additional data types are required. The major data elements include the
scoreboard perceptions, communications net characteristics, and event lists.
The scoreboard contains all of the real attributes of each unit that are
in the simulation. The perceptions list contains the data that a unit uses
to understand its battle conditions. The Discrete Event List (DEL) contains
all of the currently scheduled events that are to occur at a future <u>instant</u>
in time. The Continuous Event List (CEL) contains all of the currently
scheduled events that are to occur during a <u>period</u> of time.

        The number and complexity of the process modules vary widely depending
on the degree of detail required and the scope of the simulation. There are
sets of modules that differ by combat unit size and function. In addition,
there are alternative modules that provide for decisions by employing man-in-
the-loop techniques as opposed to being totally automated, if this capability
is desired.

        The time at which each event occurs may be stored for post simu-
lation query. This query is done using a post processor which provides the
capability to trace the impact on unit status of each event to its source.
In addition, combat reports are produced by the Report Processor.

*For more Information on T-COR see, "The T-COR II-A Model" BDM/W-77-427-TR,
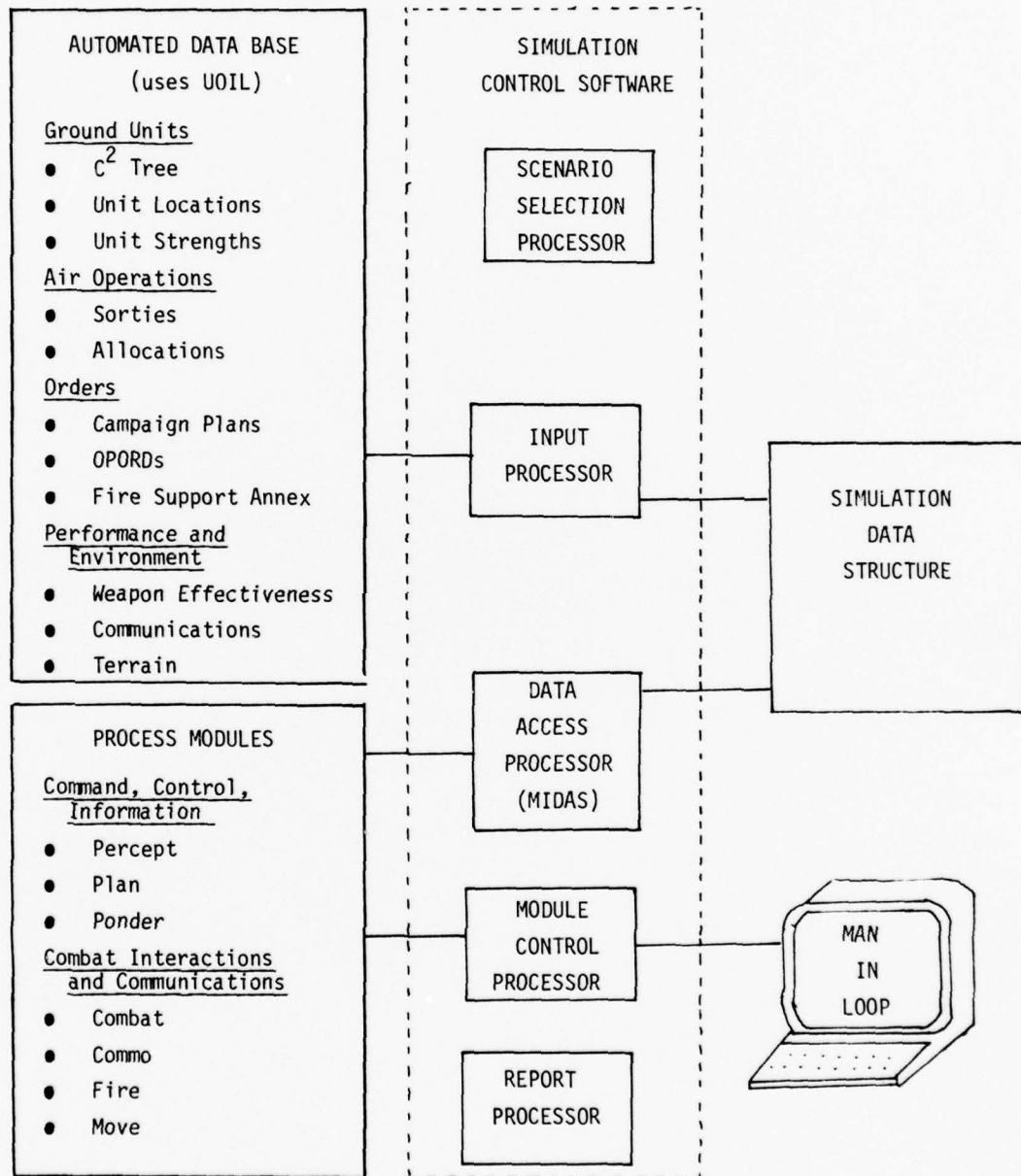 9 November 1977.

Figure 2.9. T-COR II Architecture

CHAPTER III

T-COR COMMO PREFERRED CONCEPT

CHAPTER III

T-COR COMMO PREFERRED CONCEPT

3.1   Fundamental Architecture

The T-COR COMMO preferred design concept and
its fundamental architecture embodies a high
degree of modularity in conjunction with a
top-down modeling approach.

There are several key advantages associated with the foregoing
such as:

(1)   The development and implementation of the T-COR COMMO model is
      greatly facilitated.

(2)   Subsequent code enhancement/modification is easier to implement.

(3)   Execution efficiency can be increased, particularly when varing
      levels of model detail are employed.

(4)   A large degree of flexibility is provided in virtually all
      aspects of model development, implementation and utilization.

The figure presents the high-level structure of T-COR COMMO
in addition to its major functional processing modules. The totality of
elements within the dashed rectangle comprises the COMMO simulation model
which executes concurrently with T-COR. A basic premise of T-COR COMMO is
that the communications simulation model is not an end in itself but rather
is completely responsive and consistent with the requirements of T-COR.
To achieve this objective, T-COR "communicates" with the COMMO module
through T-COR's System Control Software (SCS) which controls and executes
T-COR COMMO.

The basic elements of T-COR COMMO are the Service Matrix, the
Environmental Effects Program, the COMMO Status File and special
calculations and subroutines.

The Service Matrix is the heart of the T-COR COMMO module and
contains the basic communications data for use by T-COR. The Service
Matrix also provides access to special calculations and subroutines to
generate message processing data not contained directly in the matrix.

The Environmental Effects Program contains all the subroutines
which translate combat actions into changes in communications capability.

The COMMO Status File maintains communications status summary data for use by T-COR in the selection of alternative communications handling and to aid either T-COR or the interactive players in making decisions.

Finally T-COR contains critical elements such as the Automated Data Base and the Simulation Data Structure which provide data for input into T-COR COMMO.
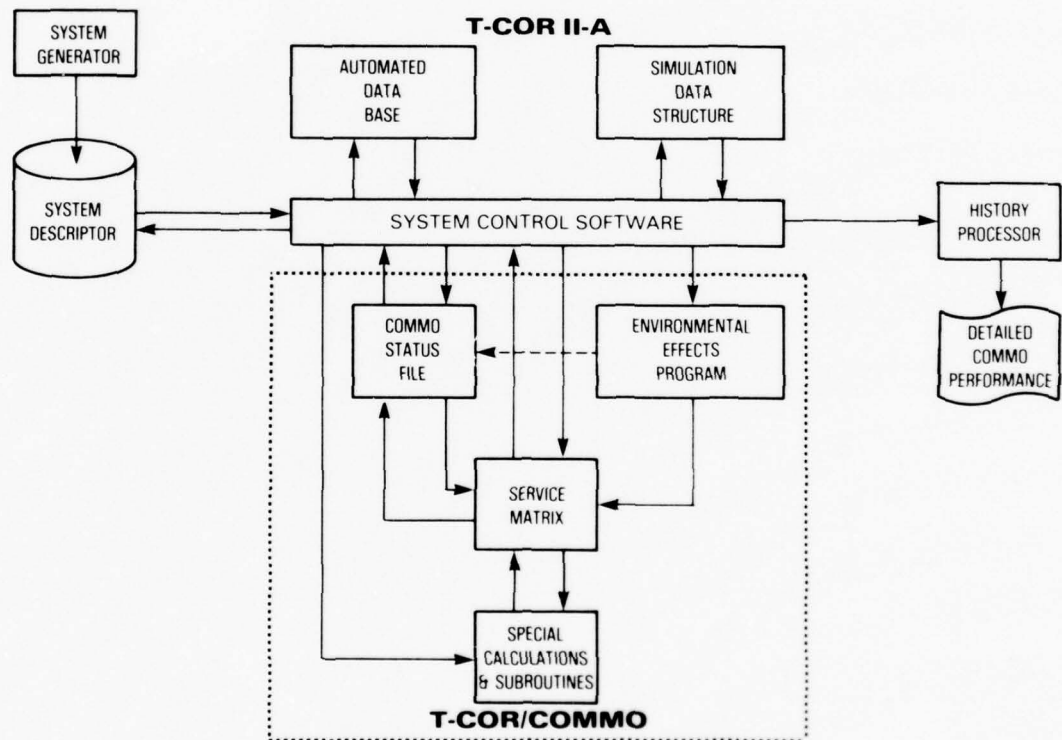

Figure 3.1. Fundamental Architecture

3.2   The Service Matrix

The heart of the perferred approach to the
T-COR COMMO module can be conceptualized as
a three dimensional matrix with communications
processing time entries with subscripts for the
sending mode, the transmission system used,
and the receiving mode.

This conceptual matrix is referred to as the Service Matrix.   In
general, when the T-COR COMMO model is exercised by T-COR the desired
result is total communications processing delay time between a specific
pair of nodes or users.   In many cases, this number may reside in the Service
Matrix and a direct result can be returned to T-COR quickly and efficiently
As the combat situation changes such that this particular communications
path (or any other for that matter) is affected, another module of T-COR
COMMO assures that the appropriate modification(s) is applied to the
Service Matrix.

There will be other cases, however, where the communications service
delay time must be computed.   In these cases, the Service Matrix provides
addresses of the appropriate subroutine codes to calculate those times.
An example of the use of subroutines would be the requirement to process a
message through an interswitched network, should such networks become
available in the Corps area.   For a given message transmission a combination
of direct and computed delay is not an unusual situation.

The Service Matrix is only conceptually a matrix because in
practice the information will be highly compressed into a set of lists
and pointers so as to minimize computer memory space demands.

Summarizing, the Service Matrix is the single processor of
communications traffic and is designed to minimize computer simulation time
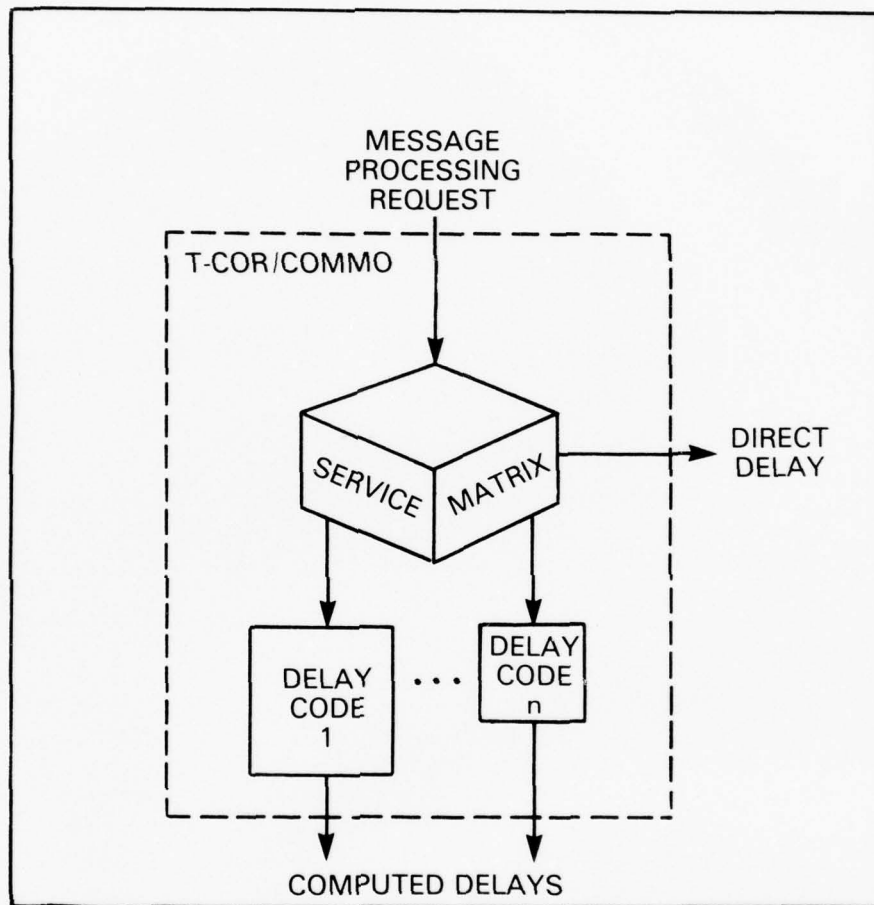required to service messages.

Figure 3.2.   The Service Matrix

3.3   Request/Directives

The range of T-COR instructions to the T-COR
COMMO module varys between a completely defined
request to a very loosely defined request in steps
as fine as detail requires.

T-COR exercises the T-COR COMMO module through a Request/
Directive (R/D) command which is coordinated by the system control software
and which falls into one of the following three generic categories.

(1)   Communications Service Request (CSR) indicates to T-COR COMMO
       that communications processing is required and expects disposition
       of that request as output.

(2)   Communications System Operability/Capability Assessment and
       Modification (CSOCAM) indicates that a combat event has occured
       which may alter the operability/capability of the communications
       system elements. CSOCAM instructions would be directed to the
       Environmental Effects Package of T-COR COMMO.

(3)   Communications System Status (CSS) reports to T-COR parameters
       indicating the status of the communications systems that have
       potential bearing on decisions made in T-COR.

Each R/D has associated with it a list of processing options that
are selected by T-COR. Concentrating on the Communications Service Request
(item one above), a range of actions occur in T-COR COMMO depending on the
options selected by T-COR. For example, one qualified R/D might specify
that a given message is to be transmitted between two specific users over
a named communications system. We call this a well-defined R/D and expect
as output from COMMO, a total delay time to complete this message trans-
mission. A possible result, of course, is an infinite delay time response
if the specified transmission system is incapable of successfully transmit-
ting the message.

At the opposite end of the spectrum we have the "loosely" defined
request. As an example, suppose T-COR issues an R/D which states: here is
a user-pair between which communications is needed - what are the current
means available and how are they performing? For each communications system-
type between the specified pair, T-COR COMMO responds with their current
availability and an indication of their performance caliber. The figure
shows that several levels of R/D complexity exist between a completely
defined R/D (no returned alternatives) and a loosely defined R/D resulting
in essentially a status report of communication capabilities at the current
time. A typical example of an intermediate R/D might be the following:
T-COR indicates that message communications are needed between a specific
user-pair, the information to be transmitted is record data and to use the
fastest available system (including messenger) to transmit it. T-COR COMMO
processes the request and reports to T-COR what systems was used and the
expected time delay before successful transmission is completed.

COMPLETELY
DEFINED
REQUEST

REQUESTS WITH
INTERMEDIATE
LEVELS OF
DEFINITION

LOOSELY
DEFINED
REQUEST

T-COR/COMMO

TIME
DELAY

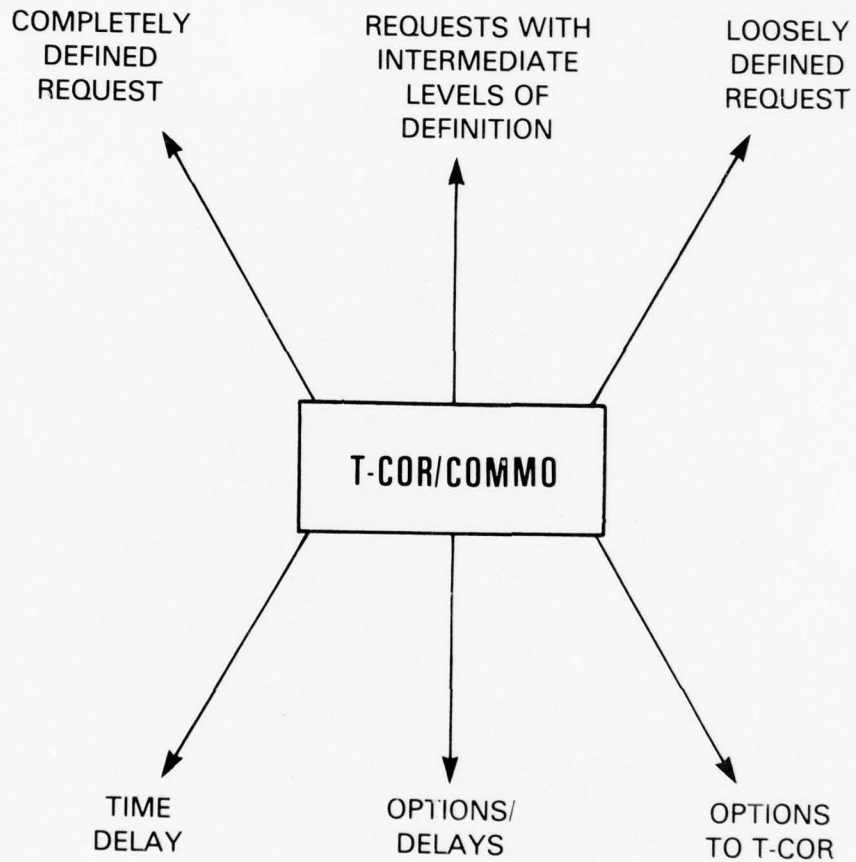OPTIONS/
DELAYS

OPTIONS
TO T-COR

Figure 3.3.   Request/Directives

3.4   Environmental Effects Program

The Environmental Effects Program assesses the
effects on the operability/capability of the
communications systems components at affected
nodes for certain T-COR simulation generated
and scheduled events and applies the appropriate
modifications to the Service Matrix.

Combat and other environmental events generated by the T-COR
simulation gaming and other scheduled events cause the system control
software to trigger the Environmental Effects Program to assess possible
changes in the operability/capability of communications components located
at various nodes. Examples of simulation generated events which might
effect the operability/capability of communication components are a nuclear
burst, destruction of an enemy jammer, movement of a node or significant
equipment/personnel losses due to conventional attrition. An example of a
scheduled event would be restoration of a communications component that had
failed at an earlier time. The nodes affected can be specified by T-COR,
as in the case of movement of a node, or assessed by the Environmental
Effects Program, as in the case of a nuclear burst at a location and yield
that are defined by the T-COR gaming. If a high detail model is used which
incorporates message queuing, message transmission completion times would
be handled as scheduled events by T-COR and reported to T-COR COMMO for
appropriate updating when they occur.

The Environmental Effects Program applies the appropriate
changes, if any, to the Service Matrix elements. If the Service Matrix is
changed it can be searched by routines in the COMMO Status File to update
the connectivity file. Alternately the COMMO Status File can be left
unchanged at these event times and only update when status report requests
are made directly to the COMMO Status File by T-COR.

Computationally, the Environmental Effects Program would depend
extensively on extant techniques and methodologies as applicable at the
T-COR COMMO level of detail. A key source of both techniques and method-
ologies is the ETC^3 wherein subroutines from ETC^3 may be integrated
directly into the Environmental Effects Program of T-COR COMMO. Further-
more, in the interests of computational efficiency, effects data resulting
from the DNA sponsored INCA effort could be incorporated in T-COR COMMO
through curve fit and/or data lookup table techniques.
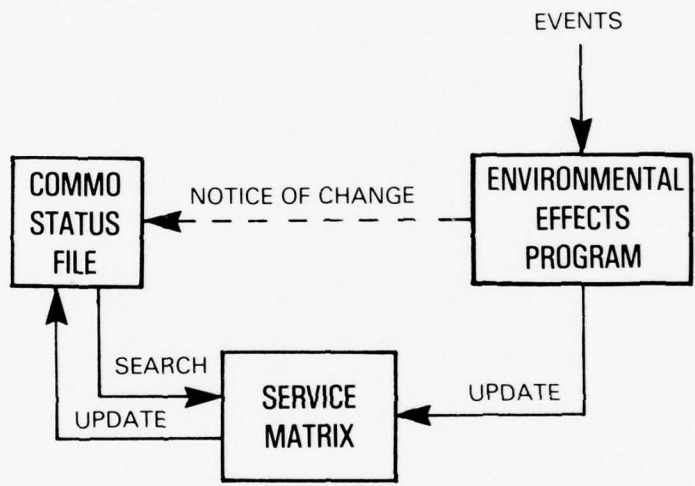
Figure 3.4. Environmental Effects Program

3.5   T-COR Net Structure

Each unit used in T-COR from Corps Rear to
the maneuver units represent nodes in the System
Description and associated with each of these
nodes, as a message transmitter, is a two
dimensional slice of the Service Matrix.

In the System Description, and conceptually in the T-COR COMMO
Module, each unit in the detail portion of the T-COR game represents a
communication network node. There are several communications networks
identified by the type of communication transmission system, for example
the FM/Secure Voice Command Net or the Microwave Multichannel LOS net.
These networks are automatically interfaced at the appropriate nodes by
the System Generator during the data input process.

If a node, N_k, is thought of as a sender or transmitter of
messages then associated conceptually with that node is a two dimensional
slice of the Service Matrix, with rows indexed by communication networks
and columns indexed by nodes in the T-COR game. In this conceptualization
if node N_k does not have an access to a particular communication network
then all the entries in that row would indicate that no communication is
possible, or equivalently that message time delays on that network are
infinite. Likewise, in this conceptualization, if N_k cannot communicate
with node N_j by some network which N_k has access to, then this entry in
the matrix indicates that no communication is possible.

EXAMPLE:

N_1 CORPS REAR
$\vdots$
N_4 CORPS TACT OPS CNTR (CTOC)
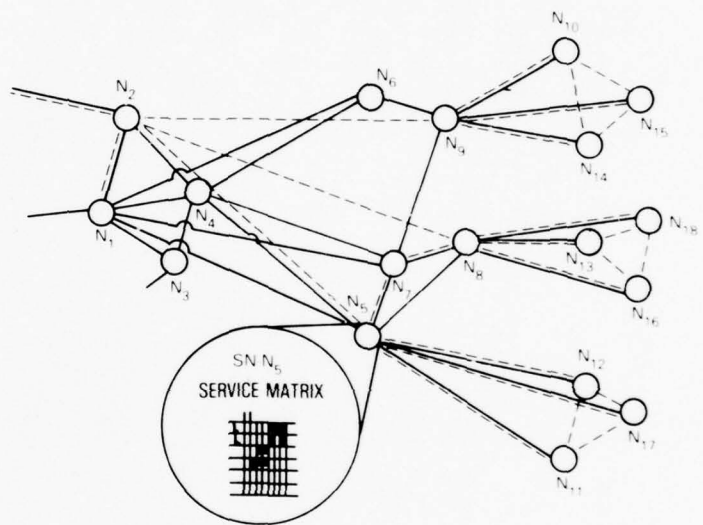N_5 DIV TACT OPS CNTR (DTOC)
$\vdots$
N_I

Figure 3.5.   T-COR Net Structure

3.6 Service Matrix Structure

Request/directives from T-COR are processed by
the T-COR COMMO Module by checking one or several
entries in the send node slice of the Service
Matrix, depending on the level of definition of the
R/D.

Recall that the row indices of the send node slice of the
Service Matrix correspond to communications networks and the columns to
receive nodes (units) in the T-COR game. In practice only communications
networks to which the send node ever has access are of interest. Referring
to the figure which shows a detail of the send node slice of the Service
Matrix, it is seen that there may be several means of communications
between a given send and receive node. For organization and accessing
reasons the communication network indices are grouped into two major classes;
voice and text/record systems. Messenger type communications are classed
as text/record and can be listed at the end of the text/record group. In
practice message communication will be handled in a separate list structure
to permit more compression of the Service Matrix.

A communications service Request/Directive (R/D) is issued from T-COR
and processed by the T-COR COMMO Control Module by consulting the Service
Matrix. The addressed element (send node, receive node, voice/text indicator
and system) contains the processing delay or procedure for its determination
as the output from T-COR COMMO for this R/D. If the specific voice or text
system is not specified, then a downward search is conducted to find the
first available system which can service the R/D.

A large degree of flexibility is allowed with respect to the
definition or qualification level of an R/D. It can be fully qualified
specifiying a particular voice or text system, partially qualified
specifying voice or text class and a subset of allowable systems, partially
qualified specifying voice or text class and no system which invokes a top-
down sequential search or unqualified such that a list of all available
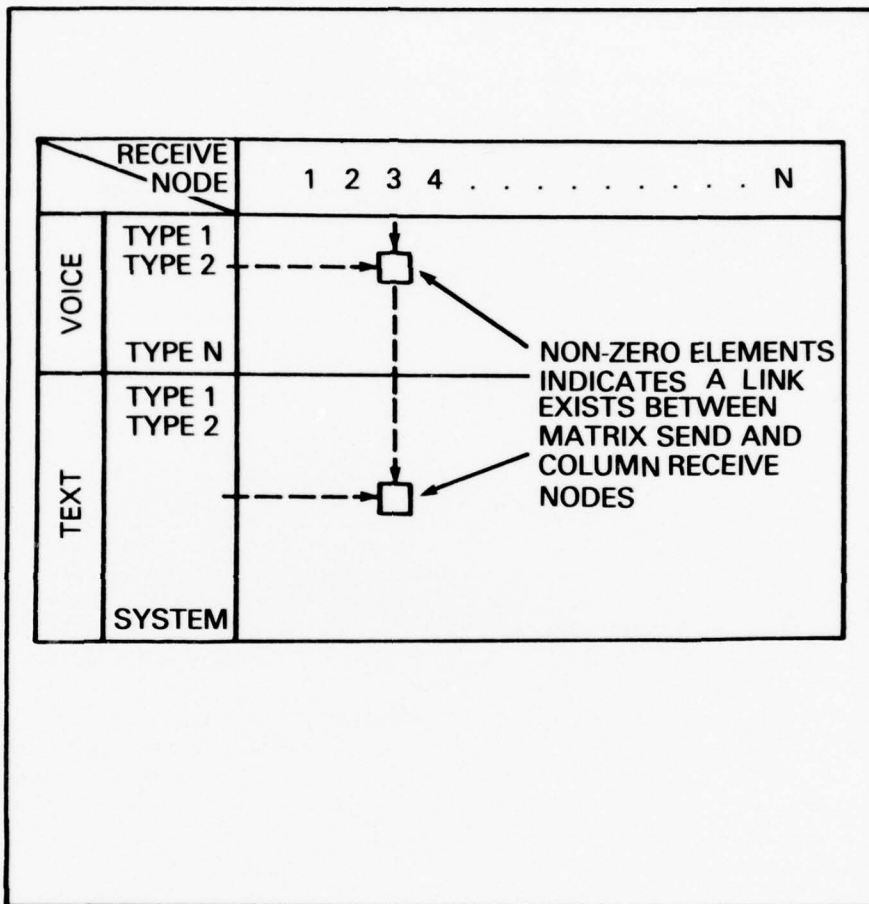communications systems are determined.

Figure 3.6.   Service Matrix Structure

3.7   Service Matrix Elements

Each entry in the Service Matrix, referred to as
an element, contains one or more communications
processing parameters from which processing times
can be determined consistent with the level of detail
required.

Generally speaking, any communications event will consist of three
distinct phases; preparation for transmission of the message, actual
conveyance of the message between sender and receiver locations and receipt
actions following the transmission phase. There is substantial variation
in the size and content of these three phases among the communications systems
employed at Corps and below.

Consistent with this concept, each element of the Service Matrix pro-
vides for the existance of these three communications processing phases for
any message type. The total message transmission delay time is then given
by the sum of these three delay time contributions.

The message processing delay time can be direct or computed depending
on several factors including the T-COR COMMO user's required level of detail.
In the interest of T-COR execution speed, T-COR COMMO may provide three
techniques for the determination of communications processing delay time
for each phase of processing as follows:

(1) Time Delay Form - This is the simplest and fastest technique.
     A processing delay time factor is pre-computed and stored as
     elements of the Service Matrix that are appropriate for the
     communication system type and status. A typical example might be
     record data transmission system where the transmission delay would
     be given by the product of this factor and the message length.

(2) Computational Procedure - The computational procedure is provided
     for those communications systems, communication processing phases,
     or volatile situations that are highly dependent on dynamic factors
     in the T-COR game. In this case the element of the Service Matrix
     points to the appropriate special computations contained or
     addressed in the T-COR COMMO Module.

(3) Distributional Time Delay Form - In this form an element of the
     Service Matrix would contain the parameters that characterize the
     probability distribution of the processing delay times. Either
     T-COR COMMO or T-COR itself would then be responsible for the
     appropriate utilization of these distribution parameters. While
     this technique would seem to represent more realistically the

3-14

actual delay process, the validity of the parameters to be
used would be highly dependent on the quality and quantity
of statistical data available to determine the distributional
forms and parameters characterizing those distributional forms.

It should be noted that combinations of the above three techniques for
the three phases of the communication event are possible if the level of
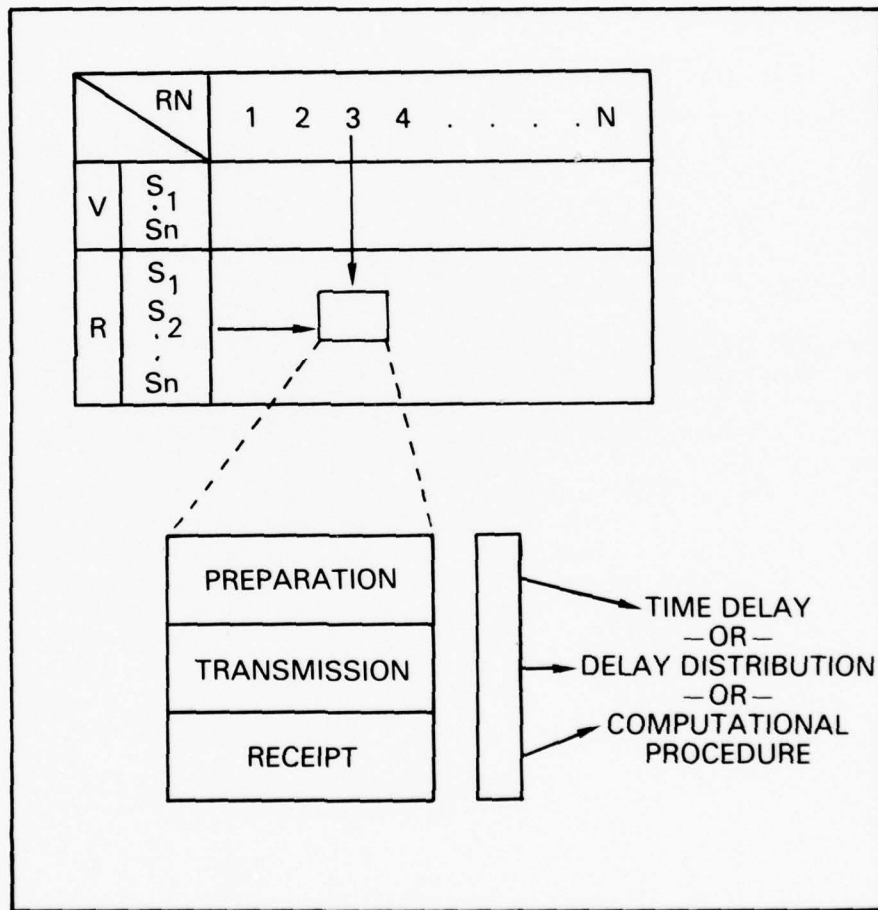detail requirements so dictate.

Figure 3.7.   Service Matrix Elements

3.8   Message Delays for Record/Data

Record-data type communication systems typically
encompass message handling processes which have
considerably larger time delays associated with
them than the transmission itself.

At an originating node, the start of the communications system pro-
cessing usually begins with the receipt of the message at a message or
communications center and is called the time-of-file (TOF) for that message.
Following TOF, the message must be physically handled by message center
personnel in preparation for electrical transmission which often includes
punching and verification of a paper tape.

When the message is physically entered into the electrical transmission
system or a queue for electrical transmission, this is marked by the start-
send segment of the end-to-end message communications process. The duration
of this segment is determined by such factors as message length, message
precedence, transmission speed, error rate, queing and alternate routing.
Note that, if the electrical transmission system is not available for access
or is inoperative, the transmission time is infinite.

When the electrical transmission to the receiving node is complete and
acknowledged, the transmission segment is complete and we enter the receiver
handling segment. Included in this final segment might be hard copy
generation of the message and, in all cases, actual delivery of the message
to the named addressee (s). Performance of the latter action is designated
the time-of-delivery (TOD) of the message.

In many record data communication systems, the TOF to TOD time span
will include one or more intermediate nodes where personnel actions are
required such as, for example, in torn-tape relay. These cases are
accommodated in T-COR COMMO by recognition of intermediate node status which
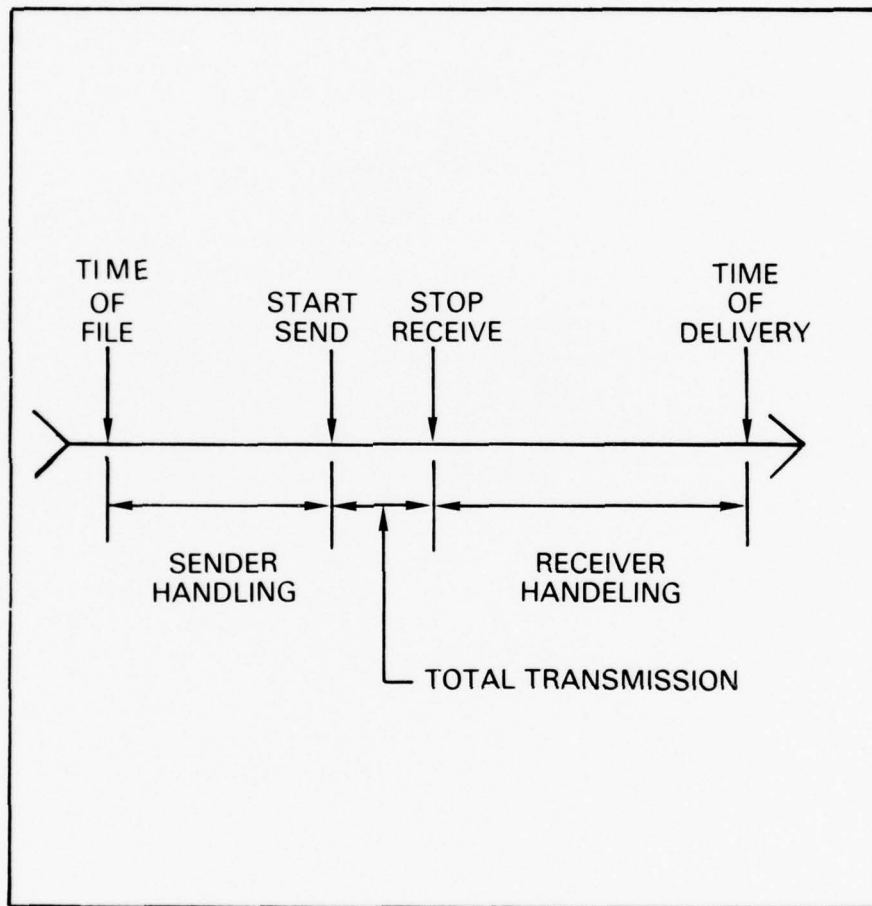modifies the derivation of the total processing time.

Figure 3.8. Message Delays for Record/Data

3.9 Intermediate Processing

Communication system nodes serving message traffic
on an intermediary basis can automatically select
and forward messages to the final destination.

Communications in the combat theater are typified by a collection of
several different system-types interfacing at the various command echelon
headquarters. The size, sophistication and complexity of these interface
nodes tends to increase as we progress from the forward (company level) to
the rear area (Corps headquarters).

The relaying of message traffic through these nodes is a normal part
of tactical communications and hence is represented in T-COR COMMO.
Frequently, human actions are required in the processing and relaying of
traffic through these intermediate nodes as, for example, in torn-tape-relay
A statistical characterization of communications operations personnel actions
representing the process is employed in the COMMO model and is sensitive to
such parameters as number of personnel, traffic activity, message precedence
and message quality.

In many cases, the choice of message forwarding means is simple in
that only one means is (or ever was) available to get to the destination
subscriber (excluding messenger) and may or may not involve a transmission
system-type change. However, in some cases there will be more than one
means available to forward messages and a selection process must be invoked.
Control of this selection process is provided by a doctrine table which
specifies the permissible interfaces, their preference of selection and
any special considerations which must be applied.

It is important to note that T-COR always has the capability to over-
ride the communications node doctrinal interface processing by simply using
the node as a destination for the initial message leg and as an origin for the
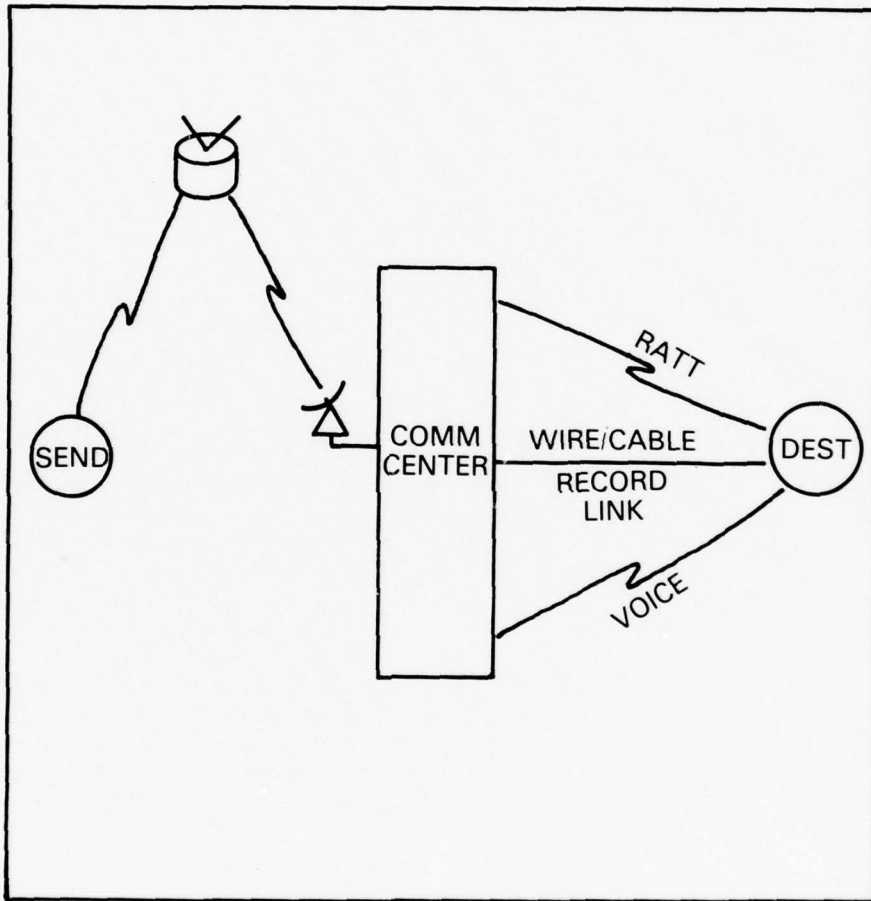second or final leg of the end-to-end path.

Figure 3.9.   Intermediate Processing

3.10   Message Integrity

Variability in operational capability as well as
hostile or friendly combat events can impact message
clarity and integrity.

The existance of a nominal communications link between two nodes
does not guarantee that sufficiently accurate messages can be passed over
that link. Message clarity is generally related to average intelligibility
for voice messages and character error rate or bit error rate for text/
record and digital messages, respectively.

A number of environmental effects, combat and non-combat related,
can impact on message integrity. Non-combat factors that can impact on
voice intelligibility include range of transmission, weather effects such as
rain, and both gross and local terrain features. Similarily, combat effects
such as jamming, RF interference, and loss of power or high gain antennas can
adversely effect voice intelligibility without completely eliminating the
communications link.

Record/data and digital links are also subject to variability in the
quality of transmission due to combat and non-combat related effects. An
important example is the possible large increase in bit-error rate for satellite
communications links that may result following a high altitude nuclear burst.

The impact of reduction in average voice intelligibility and increase
in character or bit-error rate is highly dependent on the type of message
being transmitted and the available procedures for retransmission and message
piecing. Clearly for most voice messages repetition can be used to assure
message integrity. For critical record/data or digital messages repeated
transmission may also be used to insure message integrity. However, in the
absence of retransmission procedures, faulty data may be passed undetected due
to increases in error rate.

T-COR COMMO does not propose to calculate directly message integrity,
however, the impact of selected combat and non-combat effects on message
integrity can be included in the T-COR COMMO model. The special delay codes
subordinate to the Service Matrix can be used to calculate message integrity
effects for selected critical cases. Additionally, the distributional form
for the Service Matrix delays would be an excellent vehicle for inclusion of
abnormal delays due to reductions in voice intelligibility.

EFFECTS:

        VOICE INTELLIGIBILITY
        CHARACTER ERROR RATE
        BIT ERROR RATE

CAUSES:

        TERRAIN
        WEATHER
        NUCLEAR WEAPONS
        PHYSICAL DISPOSITIONS

MODELS:

        SPECIAL DELAY CODES
        DISTRIBUTIONAL PARAMETERS

Figure 3.10. Message Integrity

3.11   Messenger Service

Messenger-type communications delays are determined
as a function of transmission mode, sender-receiver
separation and terrain/weather conditions.

The fundamental messenger-type communications modes allowed in
T-COR COMMO include air (helicopter), ground vehicle (jeep) and foot. Each
mode or system type is initially assigned a nominal average speed-of-service.
When a messenger system is selected by T-COR (or T-COR COMMO when permitted),
the line-of-sight distance between the centers of the sender hex and receiver
hex is determined. Then the nominal message delivery time is simply the
quotient of this distance and the nominal mode velocity.

To correct the nominal delivery time delay for terrain and weather
conditions, a terrain traversal difficulty factor for each hex in the
delivery route for the selected messenger node and the prevailing weather
factor can be applied. That is, the product of the terrain factor for each
hex, the weather factor and the nominal delivery time gives the corrected
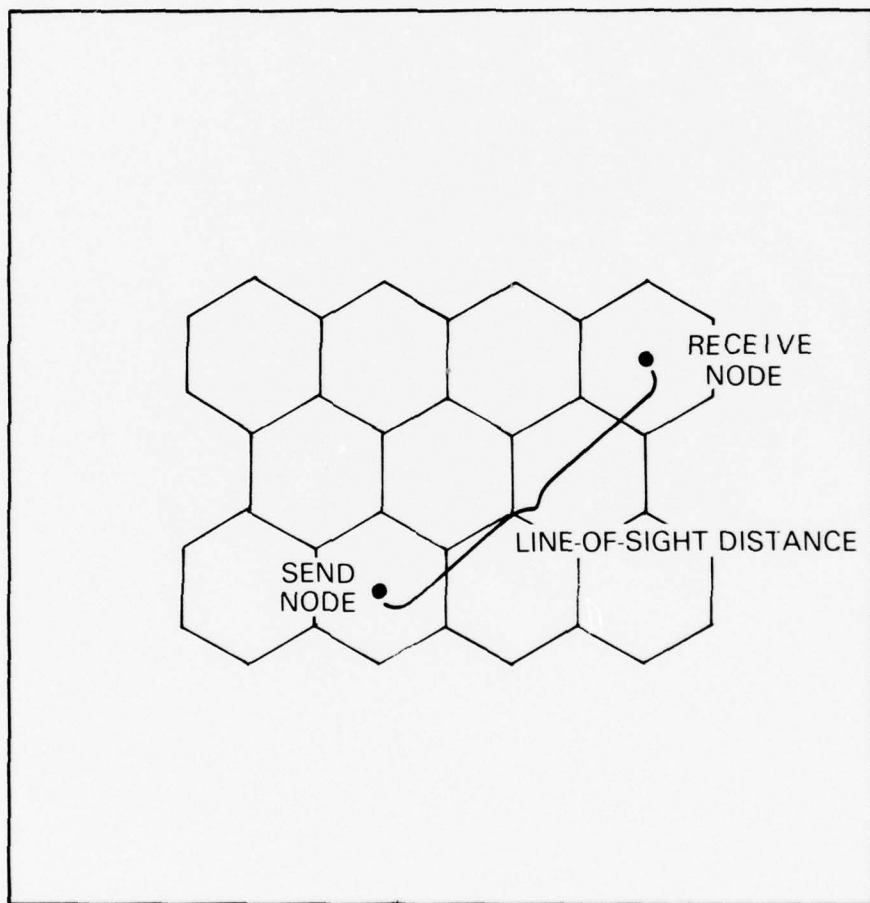delivery time.

Figure 3.11. Messenger Service

3.12   Combat Environmental Effects

The primary combat and environmental effects
that influence the operability/capability of the
communications components at the nodes are
electromagnetic jamming, damage from conventional
and nuclear weapons, and movement of nodes.

As mentioned earlier, T-COR sends notice to T-COR COMMO of the
occurance of events which could potentially cause a change in the operability/
capability of communications components located at the various nodes. The
Environmental Effects Program module in T-COR COMMO then evaluates the event
and makes the appropriate updates to the Service Matrix. The most important
types of events which can impact on communication operability/capability are
changes in electromagnetic jamming, conventional firepower, nuclear weapons
detonations, and movement of nodes.

Electromagnetic jamming can cause communications systems such as FM
nets to be completely jammed, partially jammed, or not jammed. The effect
of increased jamming is to increase the message transmission time until at
some threshold the transmission time becomes infinite, corresponding to no
communication capability on the affected communication system at the node.

Conventional and nuclear detonations cause gross inoperabilities
or in some cases decreases in the capability of communications components.
An example of a decrease in capability would be the loss of a major portion
of the communications personnel at a particular node resulting in large
increases in message handling times.

Movement of nodes causes the temporary loss of communications
capability in nearly all networks except FM nets and messengers while the
node is preparing to move, while moving, and for a period of time after the
node has reached a new location. Additionally, relocation may cause loss of
some node-to-node radio communication because of range limitations, while
making feasible other node-to-node communication that was previously infeasible.

In addition to the important effects mentioned above, high detail
models are possible which incorporate other effects such as weather and message
queuing. Also many types of communications systems which have been damaged
due to detonations can be reconstituted in relatively short periods of time
(relative to the game time). Consistent with the level of detail required
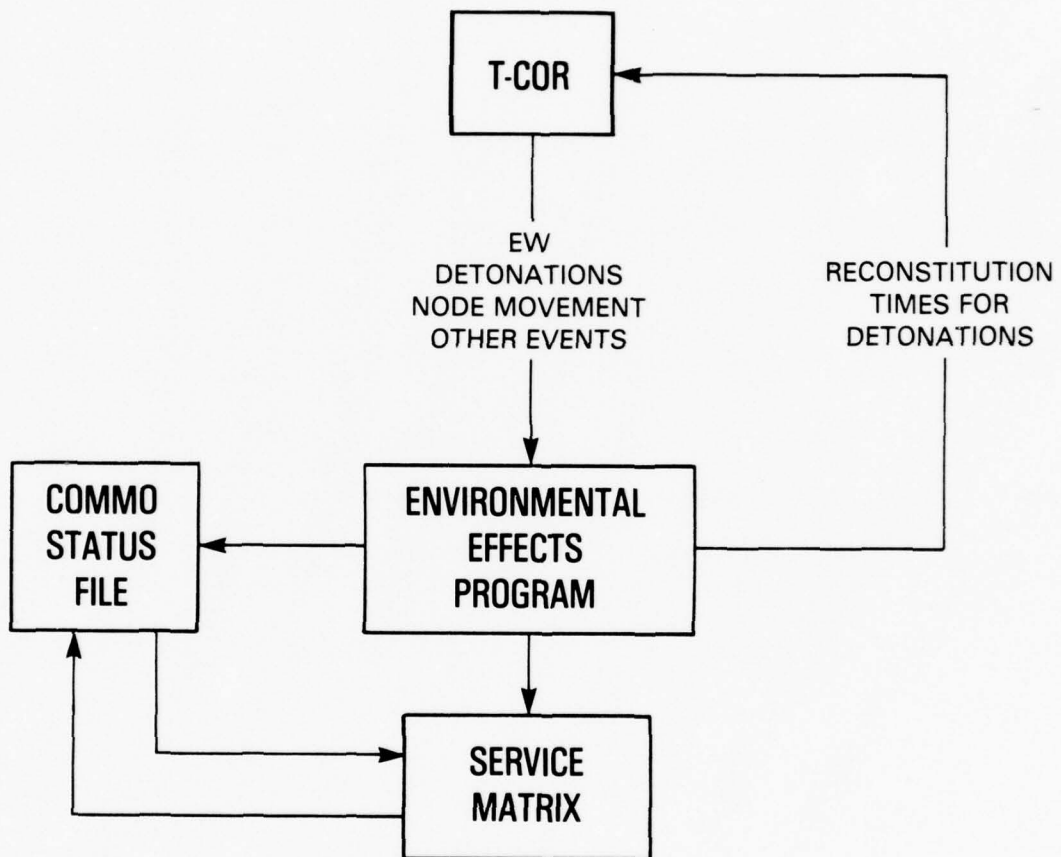such reconstitution events should be fed back to T-COR to be scheduled.

Figure 3.12.   Combat Environmental Effects

3.13   Electronic Warfare

Electronic Warfare (EW) is a significant threat to
communications in the theater and is,
therefore, included in T-COR COMMO by a first-order
model addressing radio links.

The scope and sophistication of radio communications jamming
alone (as a subset of EW) is extensive and complex. The effectiveness of
a particular jammer against a particular radio link (receivers) is a function
of a very large number of parameters characterizing the jammer, receiver(s)
and the physical/electrical environment between them.

T-COR COMMO can address the jamming of radio links
with a very straightforward first-order model. Each jammer played has a
maximum effective jamming radius associated with it. Any receiver located
in a hex that is totally within the effective jamming radius is considered
totally jammed and ineffective for both transmit and receive operation. For
those receivers located within hex's through which the line of effective
jamming radius passes, either total jamming or no jamming will be assessed
according to the toss of a coin.

Each jammer also has a "type" designator associated with it and
each receiver node may be marked as susceptible or not susceptible to any
subset of the jammer types. Using this capability, a first-order
approximation can be made to account for such variables as jammer type, power,
directivity and receiver frequency, antenna characteristics (gain, direction,
etc) as a few examples.

While more representative models of jamming are fairly easily
obtained, the preceding approach should prove initially adequate, is consistent
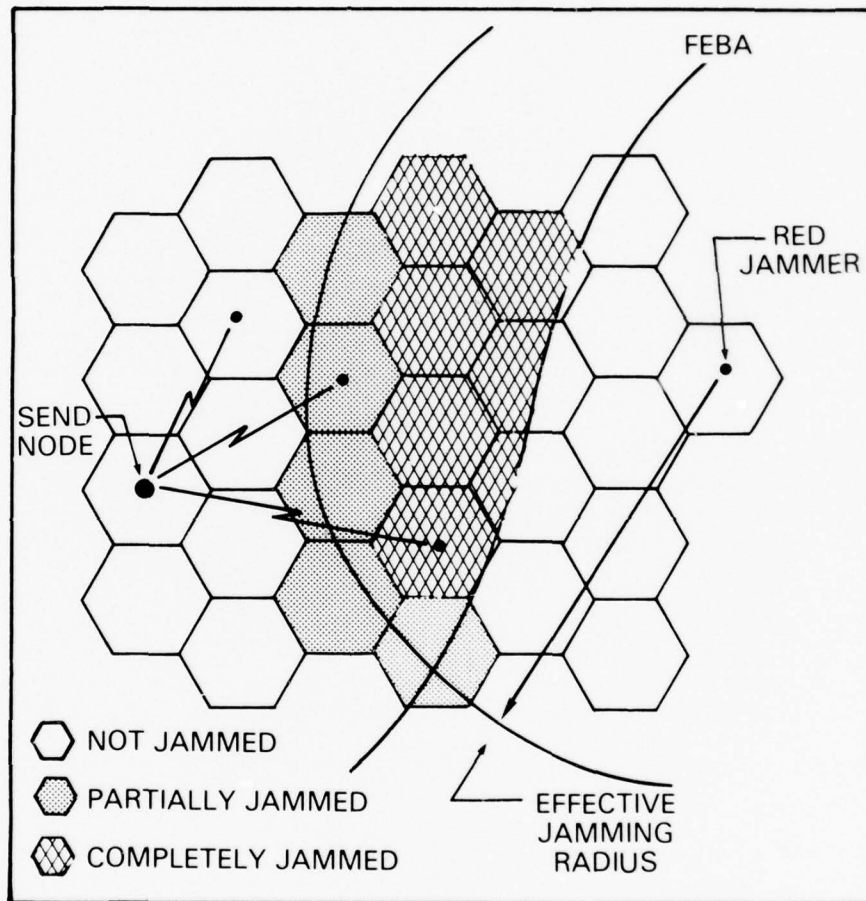with T-COR COMMO level-of-detail, and is easily refined.

Figure 3.13.   Electronic Warfare

3.14   Conventional Weapons Effects

Conventional weapon detonations affect communications
by producing gross inoperabilities in communication
components and by reducing capability through personnel
losses.

There are three major considerations in assessing the conventional
weapon damage to communication system components: (1) destructive capability
of the weapon or weapons, (2) vulnerability of the components, and (3) distance
from the detonation to the communication components. Since T-COR allocates
conventional weapons on an area basis, a conventional detonation event reads
as one or more detonations of a specified destructive capability occurring in a
specified hex. Since hexes are at minimum 1.35 km center to center, it is a good
first order approximation to examine only nodes located in the specified hex
for changes in operability/capability due to the given event. Consideration
(3) then becomes one of weapons coverage.

Within the hex specified by the detonation events, gross component
inoperabilities and personnel losses are probabilistic events. The probabilities
associated with these communication events are produced as outputs of a weapons
coverage subroutine to which the parameters; number of detonations, destruction
capability per detonation, communication component vulnerability, and number
of communication personnel assigned is passed. With these probabilities
either T-COR or the T-COR COMMO itself makes random draws to determine the
specific communication components damaged and number of personnel lost.
These losses are then translated into changes in communications capability and
the new status is entered in the Service Matrix. Consistent with the level
of detail required, the weapons coverage subroutine will be developed as a
fast running computation which is condensation of results already treated
in T-COR.

As noted earlier in this chapter some types of communication systems
losses which have occured because of component failures can be reconsitituted
in a time that are short by comparison to the T-COR game. Consistent with the
level of detail required, system loss events due to this category of failures
should generate a mean or random reconsititution time which is sent to T-COR
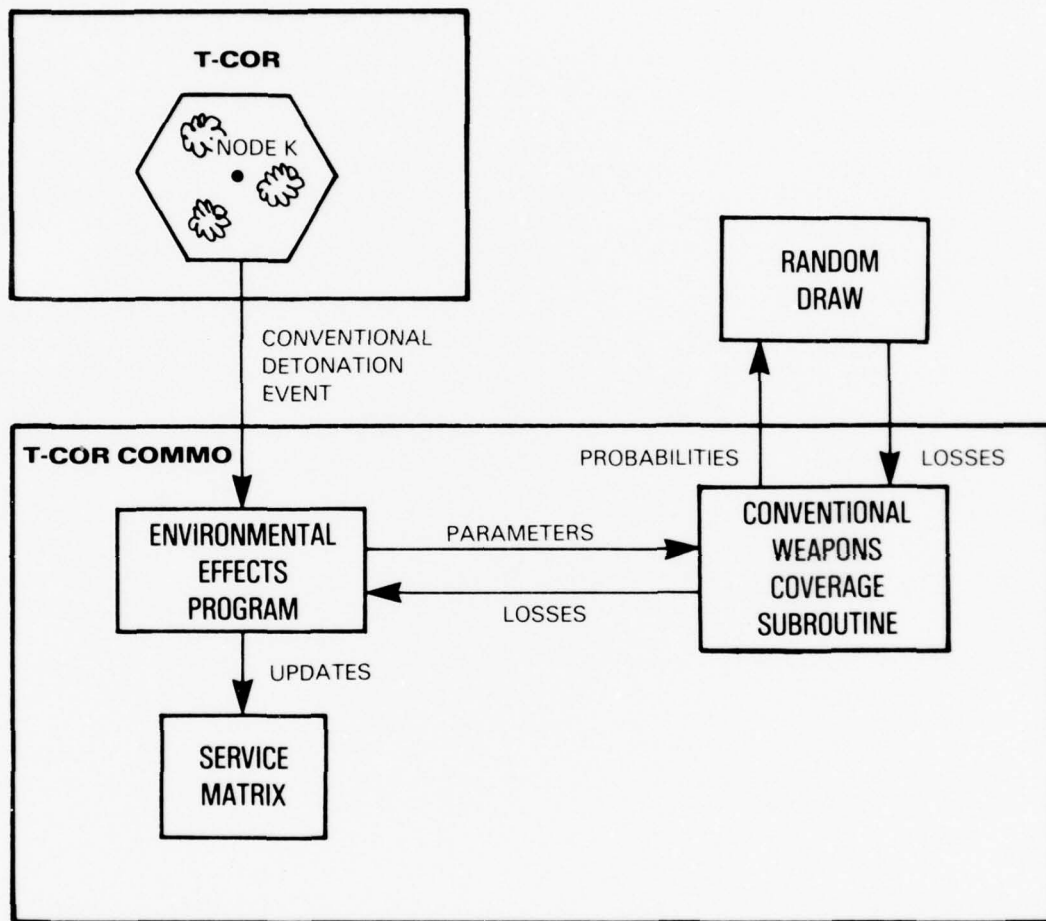for scheduling.

Figure 3.14. Conventional Weapons Effects
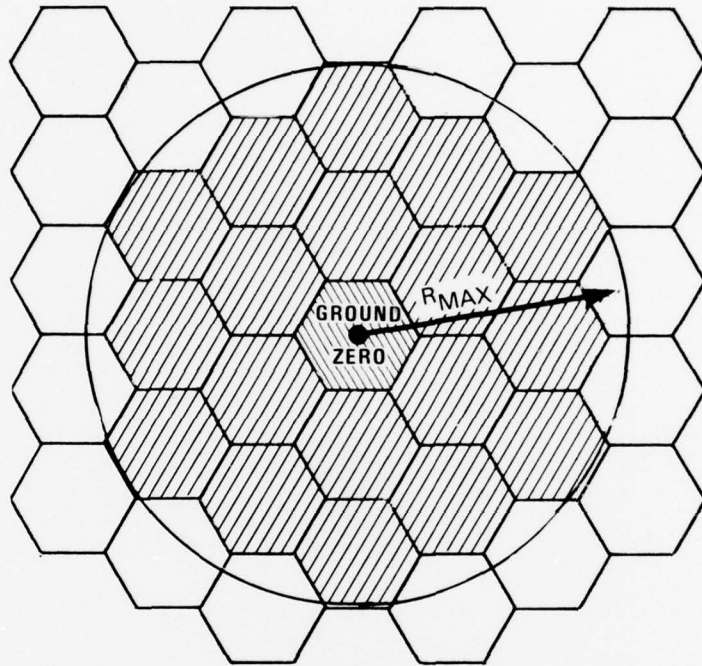
3.15   Nuclear Weapons Effects

Nuclear weapons detonations impact communication
system operabilities/capabilities at all nodes
within hexes which have centers less than a radius
R_{MAX} from the center of the hex in which the detonation
occured, where R_{MAX} is a function of the weapon yield.

Unlike conventional weapons, nuclear weapons can cause communication
system losses at large distances and by several destructive effects.   Thus
it is not a valid approximation to look only at the hex in which the
detonation occurs or even to include only the hexes adjacent to the
detonation hex.

For all typical low altitude tactical yields at typical heights of
burst, loss of all personnel is essentially certain within 0.7 kilometers of
the weapon ground zero. Since electronic component losses due to neutrons
are similar to personnel losses, all communications systems located in the hex
where the detonation occured are considered completely destroyed with no
possibility of reconstitution.

Along with the ground zero location of nuclear bursts T-COR will
supply the nuclear weapon yield and height of burst. From this information
T-COR COMMO will compute the radius R_{MAX}, a function of yield and height of
burst, which corresponds to the maximum radius where nuclear weapons effects
are considered significant; for example the 99 percentile radius for damage to
a soft communications system. For each node located in a hex with a center
located in a circle of radius R_{MAX} about the center of the detonation hex,
the Environmental Effects Program will access communication system nuclear
vulnerability subroutines which will produce probabilities associated with
gross inoperability and/or levels of capability of the communication system
at that node.   T-COR or T-COR COMMO itself will then conduct random draws
to define the damage to specific communication systems, the damage will be
translated to changes in message delays and entered in the Service Matrix.
As in the case of conventional detonations, reconstitution capabilities can
be included if the level of detail dictates.

At the heart of the nuclear detonation damage calculations are the
nuclear vulnerability routines. These routines will be fast running out-
growths, probably curve fits, of the nuclear survivability/vulnerability
models that BDM is developing under INCA for the communications systems of
Corps and lower echelon units.

```
▨▨▨  TOTAL DESTRUCTION
▨▨▨  SUBROUTINE COMPUTED LOSSES
☐    NOT VULNERABLE
```

Figure 3.15.   Nuclear Weapons Effects

3.16   Additional Levels of Detail

Requirements for high level detail will introduce
complexity which will increase both the run times
and computer memory requirements in T-COR and T-COR
COMMO.

While the introduction of weather, message queuing, random non-
enemy action caused malfunctions of communications components, and communication
system reconstitution capability will be expected to increase the realism
of T-COR, the data structure needed to model these features will increase
complexity and run time of T-COR significantly.

Weather affects radio transmission reliability and hence will
affect transmission times. Queuing of messages at busy nodes can result in
increased message times. Random malfunctions of communication components can
cause loss of the affected system until the malfunction is corrected. Other
features can be identified that will affect message times, but all will result
in an increase in the data structure complexity. Many of the above features
not only require additional computations and branching, but also require
maintenance of a comprehensive history record. For example, consider the case
where a communication component malfunction event occurs and a time of repair
or reconstitution is scheduled, and subsequent to this event but before the
reconstitution event this communication system is subject to combat effects
which would have destroyed the system. Unless some memory exists as to the
tentative status of the communication system, no additional destruction on
the system will be recorded and when the scheduled reconstitution time
arrives the system will be made operable again. When overlapping periods
of reconstitution are considered the number of troublesome scenarios increases.
In order to avoid an error, comprehensive histories on all system (and
maybe even system components) must be maintained and searched at most events
that affect that system. This requirement results in significant degradation
of the T-COR COMMO Module efficiency.

While comprehensive models of message queuing are in concept the
same type of history problem mentioned above, in practice they result in
very large increases in run time and memory requirements because of the
number of messages involved and the frequency with which they must be processed.

A well reasoned balance between the need for detail and efficient
run times is required for development of T-COR COMMO. Clearly no detail
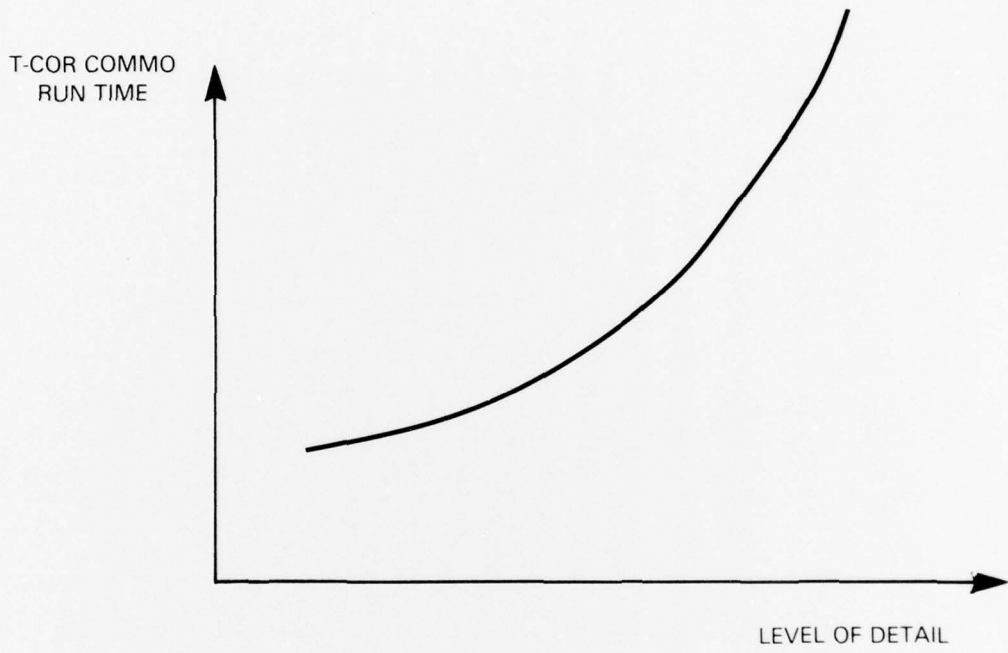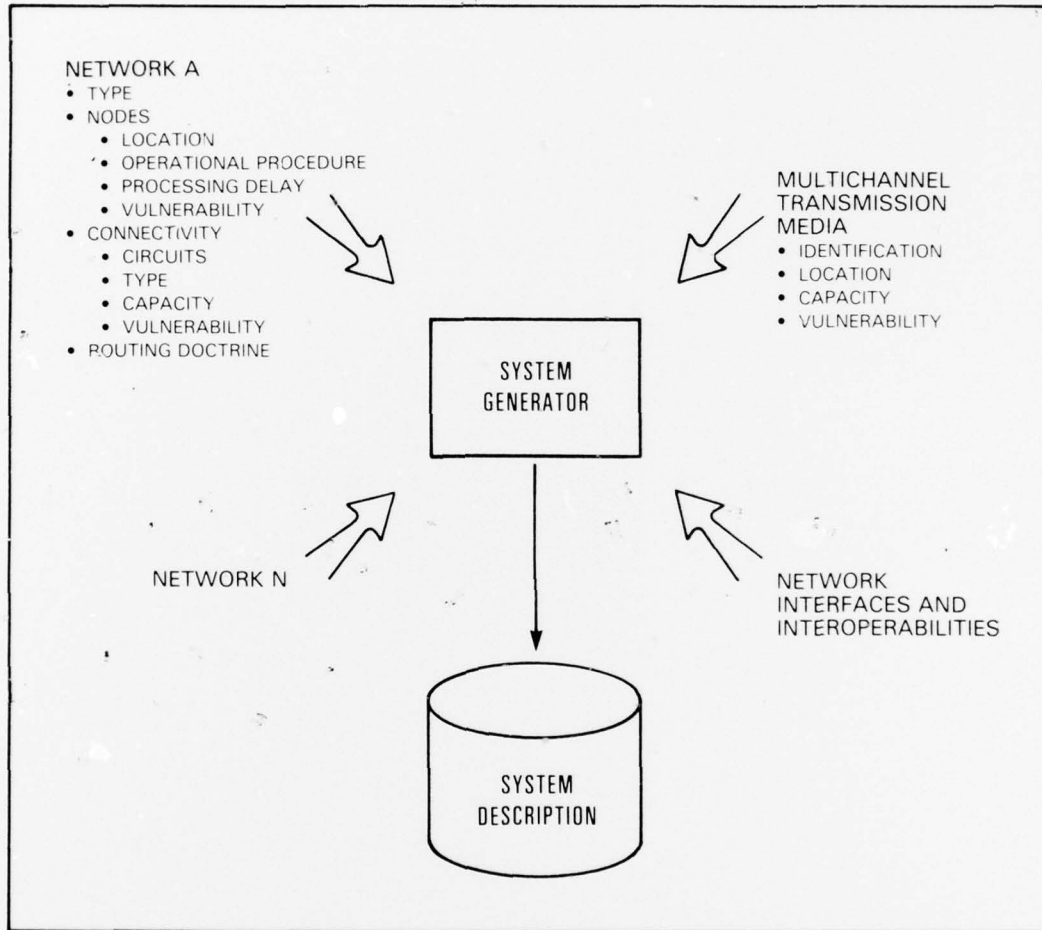finer then that inherent to T-COR itself is justified.

T-COR COMMO
RUN TIME

LEVEL OF DETAIL

Figure 3.16.   Additional Levels of Detail

3-33

3.17 Communications Systems Data Base

The communications system is defined, organized and stored in an offline data base using a stand-alone program dedicated to this function.

All of the requisite parameters characterizing a total communication system for T-COR COMMO are input to a System Generator program which produces a System Description data base. This data base is then subsequently read as input to T-COR COMMO via the T-COR SCS at run initialization time. As part of this initialization process, a limited but comprehensive set of data base modification directives may be optionally specified and applied to the external data base resulting in a derivative internal communication system configuration/characterization. An example of such a modification would be changes to the communications system to input to model random, combat independent equipment failures. Such a case would also require the generation and storage in T-COR's event list of the restoration times for those pieces of equipment.

The figure identifies the fundamental data inputs to the System Generator which are appropriately processed, formatted and entered into the System Description data base. Three distinct data-type categories are identified as well as their key characterization parameters. Since the theater communications system is typically composed of several independent networks, a separate category of Network Interfaces and Interoperabilities is established. For the most part these interfaces would be either automatic at the common nodes or at least well-characterized (including any human action/interaction). T-COR itself always retains the capability to evaluate and select among alternatives at any communications network interface node. Finally, we recognize that multichannel transmission media are employed from which more than one independent network may derive part of its connectivity. Because the loss or reduction in capacity of these transmission systems potentially affects a number of networks, their definition and characterization is maintained in a separate region of the System Description data base.

NETWORK A
- TYPE
- NODES
  - LOCATION
  - OPERATIONAL PROCEDURE
  - PROCESSING DELAY
  - VULNERABILITY
- CONNECTIVITY
  - CIRCUITS
  - TYPE
  - CAPACITY
  - VULNERABILITY
- ROUTING DOCTRINE

MULTICHANNEL
TRANSMISSION
MEDIA
- IDENTIFICATION
- LOCATION
- CAPACITY
- VULNERABILITY

SYSTEM
GENERATOR

NETWORK N

NETWORK
INTERFACES AND
INTEROPERABILITIES

SYSTEM
DESCRIPTION

CHAPTER IV

IMPLEMENTATION

CHAPTER IV

IMPLEMENTATION

4.1   Implementation Outline

The approach to implementing T-COR COMMO stresses
early identification of critical data and subroutines
through sensitivity analysis.

The T-COR COMMO conceptual design discussed above has the need
for flexibility and the capability to include varying levels of detail. The
approach to the detailed design, coding, and check out of T-COR COMMO will
be to build a relatively simple baseline model with a limited data base and,
through sensitivity analysis, to determine those portions of the model with
the greatest impact on T-COR.

The initial T-COR COMMO model will include, as a minimum, the
Service Matrix, Environmental Effects routines, and the modification of
the T-COR control software to provide the necessary interaction with T-COR
COMMO. Initial entries to the Service Matrix will be provided using primarily
operational experience with a minimum of detailed analysis. The form of the
environmental effects subroutines will be established and existing data used
to code the algorithms.

With the establishment of a working basic T-COR COMMO module,
sensitivity analyses will be conducted using T-COR to determine the impact of
the new T-COR COMMO module on the T-COR main game. These sensitivity studies
will be of two types: (1) Simple variations of Service Matrix elements and
environmental effects parameters and (2) substitution of higher level-of-
detail submodels. The objective of the sensitivity studies is to determine
which submodels and which parameters have the greatest effect on T-COR and
hence should be developed most fully.

Documentation of the initial implementation will consist of a
users guide which explains the basic workings of T-COR COMMO and the data
that is incorporated into the model. Additional documentation will define
the data requirements to make T-COR COMMO fully operational as well as those
improvements deemed necessary as a result of the sensitivity analyses.

IMPLEMENTATION

- CODE THE BASIC T-COR COMMO
    SERVICE MATRIX
    ENVIRONMENTAL EFFECTS
    T-COR SOFTWARE
- PROVIDE INITIAL DATA BASE
    SERVICE MATRIX ELEMENTS
    EFFECTS SUBROUTINES
- SENSITIVITY ANALYSIS
    VARY PARAMETERS
    INCLUDE TEST MODIFICATIONS
    DETERMINE T-COR IMPACT
- DOCUMENTATION
    USERS GUIDE
    DATA REQUIREMENTS
    NEEDED IMPROVEMENTS

Figure 4.1.   Implementation

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