THE MOST EFFICIENT METHOD TO NUMERICALLY COMPUTE THE SCALAR SOL--ETC(U)

D W REPPERGER

UNCLASSIFIED

AMRL-TR-76-88

END

DATE

7-78

30C
**The Most Efficient Method to Numerically Compute the Solution of the Steady State Riccati Equation**

**Author:** Daniel W. Repperger

**Performing Organization:** Aerospace Medical Research Laboratory, Aerospace Medical Division, Air Force Systems Command, Wright-Patterson Air Force Base, Ohio 45433

**Project/Task/Work Unit Numbers:** 622202F/7222/722209-72220905

**Report Date:** 1976

**Security Classification:** Unclassified

**Distribution Statement:** Approved for public release; distribution unlimited

**Supplementary Notes:**

**Key Words:**
Steady state
Riccati equation
Algorithm

**Abstract:**
(See reverse side)
Abstract

This paper will consider the numerical calculation of the steady state riccati equation utilizing a continued fraction approach. The method considered here has many similarities with the partitioned algorithm approach [1,2] considered by D.C. Layton for the solution of riccati type equations. First the matrix riccati equation in steady state is converted (by a coordinate transformation) into another riccati equation which can be expanded in a matrix continued fraction form. The transformed matrix riccati equation may not be invertible and therefore restrictions are made on the general matrix case to guarantee the proper inversion properties.

The scalar riccati equation is then considered in an effort to give insight into the solution of the matrix equation. A numerical procedure is outlined to iterate on the solution of the scalar steady state equation. Upper and lower bound approximations are obtained for the steady state case based on N terms of the continued fraction expansion. Theorems are proved on the convergence properties of the continued fraction expansion utilizing mathematical induction. By using the continued fraction algorithm, the difference (or error) between the riccati solution and the first N terms of the continued fraction expansion can be bounded from above and below.

A theorem from Number Theory demonstrates that the riccati equation is a quadratic surd and it must exhibit periodicity in its continued fraction expansion. This result was demonstrated in [1] using the partitioned algorithm method. The type of periodicity obtained here is slightly different but has many of the same similarities as obtained in [1].

If the problem of interest were to approximate the numerical solution of the riccati equation using a mathematical approach called "Approximation by Convergents", an investigation is made on this approach of continued fractions in the calculation of an irrational number (such as \( \sqrt{2} \)). By considering the continued fraction expansion of \( \sqrt{2} \) using the largest reciprocals of the difference between \( \sqrt{2} \) and its respective convergences as the elements of the fraction expansion, this method is most efficient. For the case of the riccati equation, the periodic property of the continued fraction coefficients gives convergents which are identical to the periodic terms (hence, most efficient). It is hoped that these results can be extended to the matrix case to obtain the most efficient expansion.

<table>
<thead>
<tr>
<th>ACCESSION for</th>
</tr>
</thead>
<tbody>
<tr>
<td>RTIS White Section ☐</td>
</tr>
<tr>
<td>DOD Buff Section ☐</td>
</tr>
<tr>
<td>UNANNOUNCED ☐</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>BY DISTRIBUTION/AVAILABILITY CODES</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dist. AVAIL. and/or SPECIAL</td>
</tr>
<tr>
<td>☐ A</td>
</tr>
</tbody>
</table>
THE MOST EFFICIENT METHOD TO NUMERICALLY COMPUTE THE SCALAR SOLUTION OF THE STEADY STATE RICCATI EQUATION

DANIEL W. REPPERGER
Wright Patterson Air Force Base
Dayton, Ohio (U.S.A.)

Abstract

This paper will consider the numerical calculation of the steady state riccati equation utilizing a continued fraction approach. The method considered here has many similarities with the partitioned algorithm approach [1,2] considered by D.C. Lainiotis for the solution of riccati type equations. First the matrix riccati equation in steady state is converted (by a coordinate transformation) into another riccati equation which can be expanded in a matrix continued fraction form. The transformed matrix riccati equation may not be invertible and therefore restrictions are made on the general matrix case to guarantee the proper inversion properties.

The scalar riccati equation is then considered in an effort to give insight into the solution of the matrix equation. A numerical procedure is outlined to iterate on the solution of the scalar steady state equation. Upper and lower bound approximations are obtained for the steady state case based on N terms of the continued fraction expansion. Theorems are proved on the convergence properties of the continued fraction expansion utilizing mathematical induction. By using the continued fraction algorithm, the difference (or error) between the riccati solution and the first N terms of the continued fraction expansion can be bounded from above and below.

A theorem from Number Theory demonstrates that the riccati equation is a quadratic surd and it must exhibit periodicity in its continued fraction expansion. This result was demonstrated in [1] using the partitioned algorithm method. The type of periodicity obtained here is slightly different but has many of the same similarities as obtained in [1].

If the problem of interest were to approximate the numerical solution of the riccati equation using a mathematical approach called,"Approximation by Convergents", an investigation is made on this approach of continued fractions in the calculation of an irrational number (such as \( \sqrt{2} \)). By considering the continued fraction expansion of \( \sqrt{2} \) using the largest reciprocals of the difference between \( \sqrt{2} \) and its respective convergences as the elements of the fraction expansion, this method is most efficient. For the case of the riccati equation, the periodic property of the continued fraction coefficients gives convergents which are identical to the periodic terms (hence, most efficient). It is hoped that these results can be extended to the matrix case to obtain the most efficient expansion.

1. Introduction

The riccati equation has been extensively studied. The approach used here will consider a continued fraction method for numerical calculation of the steady state matrix riccati equation. The continued fraction approach has similarities to the partitioned algorithm method [1,2]. By using the continued fraction approach, the main advantage occurs due to the fact that the riccati equation can be approximated by a finite number of terms of the known matrices. If a truncation is made after N terms of the continued fraction expansion, then an upper and lower bound for the difference between the actual riccati solution and the approximation can be obtained for the scalar case. The difference between the two bounds can also be calculated which gives an idea of the ability of this approach to squeeze the true riccati solution between the respective bounds. Some examples are worked to illustrate the advantages of this approach. In order to apply this approach, it is necessary for the development of basic theorems before the continued fraction method can be utilized.

2. Conversion of The Riccati Equation Into The Continued Fraction Form

The problem of interest is the solution of the following matrix equation:

\[
AP + P A^T - PRP + Q = 0 \tag{1}
\]

The unknown matrix P is mxn and the matrices A, R, and Q are all mxn and known. It is initially assumed that R is positive definite; the remaining conditions...
(such as P and Q both symmetric and positive definite, A canonical and stable, and the controllability and observability conditions) will not be stated initially in an effort to derive theorems based on as few assumptions as possible. Theorem 1 illustrates the method to convert the matrix Riccati equation (1) into the form in which the continued fraction approach can be used.

**Theorem 1**: The solution to equation (1) with \( \mathbf{R} \) positive definite can be specified as the solution of the following matrix equation:

\[
\mathbf{W} \mathbf{W} - \mathbf{K} \mathbf{W} - \mathbf{L} = 0
\]

where

\[
\mathbf{P} = \mathbf{W} \mathbf{R}^{-1} + \mathbf{R}^{-1} \mathbf{A}^T
\]

**Proof**: Substitute equation (3) into equation (1) yields:

\[
\mathbf{A} \mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T + \mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T + \mathbf{R}^{-1} \mathbf{A}^T \mathbf{A} \mathbf{W}
\]

\[
-\mathbf{W} \mathbf{R}^{-1} + \mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T \mathbf{R} (\mathbf{W} \mathbf{R}^{-1} + \mathbf{R}^{-1} \mathbf{A}^T \mathbf{A}) + \mathbf{Q} = 0
\]

or

\[
\mathbf{W} \mathbf{R}^{-1} + \mathbf{A} \mathbf{W} \mathbf{R}^{-1} + \mathbf{R}^{-1} \mathbf{A}^T \mathbf{A} \mathbf{W} - \mathbf{W} \mathbf{R}^{-1}
\]

\[
-\mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T \mathbf{R} (\mathbf{W} \mathbf{R}^{-1} + \mathbf{R}^{-1} \mathbf{A}^T \mathbf{A}) + \mathbf{Q} = 0
\]

simplifying yields:

\[
\mathbf{W} \mathbf{W} + [\mathbf{R}^{-1} \mathbf{A}^T \mathbf{R} - \mathbf{A} \mathbf{W} \mathbf{R}^{-1} \mathbf{A}] + [-\mathbf{A} \mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T \mathbf{R} - \mathbf{Q} \mathbf{R}] = 0
\]

Hence, if the choice is made of the form:

\[
\mathbf{K} = -\mathbf{R}^{-1} \mathbf{A}^T \mathbf{R} + \mathbf{A}
\]

\[
\mathbf{L} = \mathbf{Q} \mathbf{R} + \mathbf{A} \mathbf{W} \mathbf{R}^{-1} \mathbf{A}^T \mathbf{R}
\]

then equation (2) will follow.

It is noted that the matrix \( \mathbf{K} \) may be singular if \( \mathbf{R} \) is symmetric, \( \mathbf{Q} \) positive definite and symmetric, then the matrix \( \mathbf{L} \) will be positive definite. To conclude the study on the matrix Riccati equation, the continued fraction approach (for the matrix case) will be investigated using equation (2) in lieu of equation (1). The next theorem demonstrates the advantage of expressing equation (1) in the form of equation (2) for matrix continued fractions.

**Theorem 2**

If \( \mathbf{W}^{-1} \) exists and \( \mathbf{K} \neq 0 \), then

\[
\mathbf{W} = \mathbf{K} + \mathbf{L}
\]

\[
\mathbf{K} + \mathbf{L}
\]

\[
\mathbf{W} = \mathbf{K} + \mathbf{L}
\]

\[
\mathbf{W} = \mathbf{K} + \mathbf{L}
\]

\[
\mathbf{W} = \mathbf{K} + \mathbf{L}
\]

\[
\mathbf{W} = \mathbf{K} + \mathbf{L}
\]

Thus equation (5) follows; if \( \mathbf{K} = 0 \), then \( \mathbf{W} = \mathbf{L} \) as indicated above.

The scalar Riccati equation will now be considered in an effort to study the numerical algorithm presented here and to gain incite into the solution of the matrix case.

3. The Scalar Riccati Equation

Consider the following equation:

\[
\mathbf{a} \mathbf{P} + \mathbf{P} \mathbf{A}^T = \mathbf{Q}
\]

with \( \mathbf{r} > 0, \mathbf{q} > 0 \), and \( \mathbf{a} < 0 \) equations (4a-b) now become:

\[
\mathbf{a} \mathbf{K} = 0
\]

\[
\mathbf{L} = \mathbf{q} \mathbf{r} + \mathbf{a}^2
\]

which has a solution specified by:

\[
\mathbf{W} = \mathbf{q} \mathbf{r} + \mathbf{a}^2
\]

It is easily seen that \( \mathbf{W} \) always has one positive root because:

\[
\mathbf{q} \mathbf{r} + \mathbf{a}^2 > 0
\]

\[
\mathbf{P} \text{ is specified by:}
\]

\[
\mathbf{P} = \mathbf{W} + \mathbf{a} \mathbf{r}
\]

\[
\mathbf{Q} = \mathbf{W} - \mathbf{a} \mathbf{r}
\]

\[
\mathbf{L} = \mathbf{W} - \mathbf{a} \mathbf{r}
\]

Note that under the standard assumptions, if \( \mathbf{W} > 0 \), simplifying yields:

\[
\mathbf{W} \mathbf{K} = \mathbf{L}
\]

\[
\mathbf{W} = \mathbf{W} \mathbf{K} + \mathbf{W} \mathbf{L}
\]

The continued fraction expansion for \( \mathbf{W} \) is trivial in this case. In order to investigate the scalar Riccati equation in greater detail, convergence theorems will be proven based on Euclid's Algorithm [3] with the proper notation used in continued fraction expansions.

4. Convergence Theorems on The Continued Fraction Expression For The Riccati Equation

Consider the scalar continued fraction expansion of the form:

\[
\mathbf{W} = \mathbf{a}_0 + \frac{1}{\mathbf{a}_1 + \frac{1}{\mathbf{a}_2 + \frac{1}{\mathbf{a}_3 + \ldots}}}
\]

The continued fraction notation of equation (7) will be specified by:

\[
\mathbf{W} = \langle \mathbf{a}_0, \mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3, \ldots \rangle
\]

The following definition is essential to discuss convergence properties of continued fraction expansions.

**Definition**: Let \( \mathbf{a}_0, \mathbf{a}_1, \mathbf{a}_2, \ldots \) be an infinite sequence of integers, all positive except perhaps \( \mathbf{a}_0 \). Define two sequences of integers \( \langle \mathbf{h}_0, \mathbf{h}_1, \ldots \rangle \) and \( \langle \mathbf{k}_0, \mathbf{k}_1, \ldots \rangle \) inductively as follows:

\[
\mathbf{h}_2 = 0, \mathbf{h}_1 = 1, \mathbf{h}_0 = \mathbf{a}_0 \mathbf{h}_1 + \mathbf{k}_1 \mathbf{h}_2
\]

\[
\mathbf{k}_2 = 1, \mathbf{k}_1 = 0, \mathbf{k}_0 = \mathbf{a}_0 \mathbf{k}_1 + \mathbf{k}_2
\]

for \( \mathbf{n} \geq 0 \)
continued fraction expansion from the calculation of an upper and a lower bound.

Theorem 5

As a lower bound
\[ r_j < r_{j+1} < r_{j+2} < \cdots \]
for j even forms an increasing sequence, i.e.
\[ r_0 < r_2 < r_4 < r_6 < \cdots \]

As an upper bound
\[ r_j > r_{j+1} > r_{j+2} > \cdots \]
and \( \lim_{N \to \infty} r_j \) exists and for every \( j \geq 0 \)
\[ r_j < r_{j+1} \]

i.e.
\[ r_0 < r_2 < r_4 < \cdots < \lim_{N \to \infty} r_N < \cdots < r_2 < r_0 \]

In order to prove theorem 5, the following two lemmas must be shown:

**Lemma (1):** The following equations hold for \( i \geq 1 \)
\[ h_{i-1} - h_{i-2} K_1 = (-1)^{i-1} \]

which implies
\[ r_{i-1} - r_{i-2} = (-1)^i a_i \]

**Lemma (2):** for \( i \geq 2 \)
\[ h_{i-1} - h_{i-2} K_1 = (-1)^i \]

which implies:
\[ r_{i-1} - r_{i-2} = (-1)^i a_i \]

First to prove (10a-b). Using equations (8a–b), the proof will follow by mathematical induction:

For \( i = 1 \), it is easily shown that:
\[ h_1 - h_0 K_1 = -1 \]

Also using equations (8a–b), the following result holds for \( i = 0 \):
\[ h_0 K_1 - h_0 K_1 = -1 \]

Now assume:
\[ h_{i-1} K_{i-2} - h_{i-2} K_{i-1} = (-1)^{i-2} \]

using equations (8a–b) implies:
\[ h_{i-1} K_{i-1} - h_{i-2} K_{i-1} = (a_i h_{i-1} + h_{i-2}) K_{i-1} \]
\[ - (h_{i-1}) (a_i K_{i-1} + K_{i-2}) \]
\[ = a_i h_{i-1} K_{i-1} + h_{i-2} K_{i-1} - a_i K_{i-1} h_{i-1} - h_{i-1} K_{i-2} \]
\[ = - (h_{i-1} K_{i-2} - h_{i-2} K_{i-1}) = (-1)^{i-1} \]

since \( h_1 K_2 - h_1 K_1 = (-1)^i \)
this implies:
\[ \frac{h_i}{K_i} - \frac{h_{i-1}}{K_{i-1}} = \frac{(-1)^{i-1}}{K_{i-1} K_i} = r_i r_{i-1} \]
Hence lemma 1 is shown. To prove lemma (2), it is observed that:

\[ h_0 K_{-2} - h_{-2} K_0 = a_0 \]

and equation (11a) holds for the case \( i=1 \) (which is easily verified). Proceeding as before:

\[ h_1 K_{-2} - h_{-2} K_1 = (a_1 h_1 - h_{-2}) K_{-2} \]

\[ = a_1 h_{1-1} K_{-2} + h_{1-2} K_{-2} - a_1 h_{1-2} K_{1-1} - h_{1-2} K_1 \]

\[ = a_1 [h_1 K_{1-2} - h_{1-2} K_{1-1}] = a_1 \left( (-1)^0 a_1 \right) \]

which implies:

\[ h_1 K_{-2} - h_{-2} K_1 = (-1)^i a_1 \]

or

\[ \frac{h_1}{K_1} - \frac{h_{-2}}{K_{-2}} = (-1)^i a_1 \]

or

\[ r_1 - r_{-2} = \frac{(-1)^i a_1}{K_1 K_{-2}} \]

(13)

Hence the results of lemma 2 hold. Now the proof of theorem 5 will be demonstrated:

Since each \( K_i > 0 \), \( a_i > 0 \) and we know

\[ r_i - r_{i-1} = \frac{(-1)^i a_i}{K_i K_{i-1}} \text{ and } \frac{(-1)^i a_i}{K_i K_{i-1}} \]

It follows for \( j \) an integer:

\[ r_{2j} < r_{2j+2} \]

From equations (12,13), we know for \( a_i > 0 \) and \( j \) an integer:

\[ r_{2j-1} \rightarrow r_{2j+1} \text{ and } r_{2j} \rightarrow r_{2j-1} \]

Therefore:

\[ r_0 < r_2 < r_4 < \ldots \text{ and } r_1 > r_3 > r_5 > \ldots \]

It remains to show that:

\[ r_{2n} < r_{2n+2} < r_{2n+2j-1} < r_{2j-1} \]

The sequence \( r_0, r_2, r_4, \ldots \) is monotonically increasing and is bounded above by \( r_1 \) and since all \( r_i > 0 \), it has a limit \( [L] \). In a similar manner the sequence \( r_1, r_3, r_5, \ldots \) is monotonically decreasing and is bounded below by \( r_0 \) and thus has a limit. The two limits are equal because:

\[ \lim_{i \to \infty} \left( r_i - r_{i-1} \right) = (-1)^i a_i \]

\[ K_i K_{i-1} \rightarrow 0 \]

Since each \( K_i > K_{i-1} \), the proof of theorem 3 is complete.

Before examples are worked it is necessary to consider the periodicity of the riccati equation in the coefficients of the continued fraction expansion.

Theorem 6

The continued fraction which represents a quadratic surd is periodic. The term quadratic surd from number theory means a quadratic equation similar to the riccati type.

Proof:

If \( x = \left( a_0, a_1, a_2, \ldots \right) \) implies

\[ x = \frac{x_{n+1} + h_{n-1}}{x_{n+2}} \]

or \( x \) satisfies an equation of the form:

\[ x^2 + A x + c = 0 \]

because each \( K_i > 0 \). The converse of this theorem can also be shown but the proof is more difficult.

5. A Scalar Example

Example 1:

Consider the solution to the following riccati equation by the continued fraction approach:

\[ x = \frac{x_{n+1} + h_{n-1}}{x_{n+2}} \]

or

\[ x^2 + p x + c = 0 \]

which has roots

\[ \rho = -\frac{1}{2} \pm \frac{\sqrt{A}}{2} \]

The positive root can be written \( \rho = .366 \ldots \)

Now using the continued fraction approach, we know \( p \) satisfies the following equation:

\[ p = -\frac{1}{2} \pm \frac{\sqrt{A}}{2} \]

and \( w \) satisfies:

\[ w^2 = qr + a^2 \]

\[ w = 1 + (\sqrt{3} - 1) \]

or

\[ \sqrt{w} = qr + a^2 \]

To illustrate the applicability of this approach, if

\[ w = qr + a^2 \]

or

\[ w = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]

\[ = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]

\[ = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]

\[ = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]

\[ = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]

\[ = 1 + \frac{1}{2 \left[ \sqrt{3} + 1 \right]} \]
Since $\sqrt{2} = 1.7320508-----$
Then the continued fraction of interest is:

$$1.732 = \frac{1}{1 + \frac{1}{1 + \frac{1}{2 + \frac{1}{1 + \frac{1}{1 + \frac{1}{2 + \cdots}}}}}}$$

(16)

Now it is necessary to calculate the $h_i$ and $K_i$ terms.
Table I illustrates this calculation. Now the concept of "best possible approximations" will be considered for the scalar riccati equation and for any irrational number.

<table>
<thead>
<tr>
<th>$h_i$</th>
<th>$K_i$</th>
<th>$r_n$</th>
<th>$r_{i-1}$</th>
<th>$r_{i-2}$</th>
<th>$a_i$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h_{-2} = 0$</td>
<td>$K_{-2} = 1$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h_{-1} = 1$</td>
<td>$K_{-1} = 0$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h_0 = 1$</td>
<td>$K_0 = 1$</td>
<td>1.0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h_1 = 2$</td>
<td>$K_1 = 1$</td>
<td>2.0</td>
<td>1.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h_2 = 5$</td>
<td>$K_2 = 3$</td>
<td>1.667</td>
<td>.333</td>
<td>.6667</td>
<td>$a_2 = 2$</td>
</tr>
<tr>
<td>$h_3 = 7$</td>
<td>$K_3 = 4$</td>
<td>1.750</td>
<td>.08333</td>
<td>-.2500</td>
<td>$a_3 = 1$</td>
</tr>
<tr>
<td>$h_4 = 19$</td>
<td>$K_4 = 11$</td>
<td>1.7272</td>
<td>-.0227</td>
<td>.06060606</td>
<td>$a_4 = 2$</td>
</tr>
<tr>
<td>$h_5 = 26$</td>
<td>$K_5 = 15$</td>
<td>1.7333</td>
<td>.0066066</td>
<td></td>
<td>$a_5 = 1$</td>
</tr>
<tr>
<td>$h_6 = 71$</td>
<td>$K_6 = 41$</td>
<td>1.7317</td>
<td>-.001626</td>
<td>.0043589</td>
<td>$a_6 = 2$</td>
</tr>
<tr>
<td>$h_7 = 97$</td>
<td>$K_7 = 56$</td>
<td>1.73214</td>
<td>.000439</td>
<td>-.0011905</td>
<td>$a_7 = 2$</td>
</tr>
<tr>
<td>$h_8 = 265$</td>
<td>$K_8 = 153$</td>
<td>1.732026</td>
<td>-.0001167</td>
<td>.000318267</td>
<td>$a_8 = 2$</td>
</tr>
<tr>
<td>$h_9 = 362$</td>
<td>$K_9 = 209$</td>
<td>1.732057</td>
<td>.00003127</td>
<td></td>
<td>$a_9 = 2$</td>
</tr>
<tr>
<td>$h_{10} = 989$</td>
<td>$K_{10} = 571$</td>
<td>1.732049</td>
<td>-.0000083795</td>
<td>.000022893</td>
<td>$a_{10} = 2$</td>
</tr>
</tbody>
</table>

### Example 2
Let $\xi$ be the irrational number, i.e.

$$\xi = 3.14159$$

Hence $a_0 = [\xi_0] = 3$. To calculate $a_1$, compute

$$f_1 = \frac{1}{\xi - a_0}$$

Using

$$r_n = \frac{h_n}{K_n}$$

for $n \geq 0$

$$r_i - r_{i-2} = \frac{(-1)^{i-1}}{K_i K_{i-1}}$$

$$r_i - r_{i-2}^2 = \frac{(-1)^i}{K_i K_{i-2}}$$

Now compute $a_i = [\xi_i] = 7$. In this manner we calculate (using double precision (29 digits) on a CDC 6600 computer) the following numerical results:

$$\xi_0 = 3.141592653589793238462643383279$$

Using

$$\xi = \frac{h_n}{K_n}$$

for $n \geq 0$

$$r_i = r_{i-2} - (-1)^{i-1}$$

$$r_i - r_{i-2}^2 = \frac{(-1)^i}{K_i K_{i-2}}$$

Inductively it follows that

$$\xi_{i+1} = \frac{1}{\xi_i - a_i}$$

and

$$a_i = [\xi_i]$$

An example will now be worked with the irrational number $\xi$ to illustrate this approach.

6. The "Best Possible Approximation"

Given an irrational number $\xi$, the following continued fraction expansion is "best possible" \[5\] for numerical computation of $\xi$:

**Procedure:**

1. Using the notation $a_0 = [\xi_0]$ where $a_0$ denotes the nearest integer smaller than the irrational number $\xi$,
2. let $\xi_1 = \frac{1}{\xi_0 - a_0}$ and $a_1 = [\xi_1]$
3. inductively it follows that

$$\xi_{i+1} = \frac{1}{\xi_i - a_i}$$

and

$$a_i = [\xi_i]$$

An example will now be worked with the irrational number $\xi$ to illustrate this approach.
It is noted that this expansion is identical to the one given in equation (16). This result occurs due to the following identity:
\[ 1 + \sqrt{3} = \frac{1}{\sqrt{3} - 1} \]
which results in:
\[ \sqrt{j} = \sqrt{j+2} \]
for all \( j \)
with \( a_1 = 1 \) (i odd)
\( a_{i+1} = 2 \) (i odd)

Since the square root of 3 is an irrational number (as the solution of any quadratic equation may be), the "most efficient" method to numerically compute the solution to this riccati equation has been demonstrated by equation (16). This technique is numerically illustrated here in an effort to develop an algorithm for the matrix case and when the solution to equation (2) is not known apriori.

7. Conclusions

A continued fraction approach is used to investigate the solution to the steady state riccati equation. Theorems are proven to demonstrate an algorithm which converges for the steady state scalar case. Some examples are worked to demonstrate the "most efficient" method to compute the solution to the riccati equation.

References


