



ABSTRACT. Given $n \times n$ complex matrices $A, B$, the $C$-numerical radius of $A$ is the nonnegative quantity

$$
r_{C}(A) \equiv \max \left\{\left|\operatorname{tr}\left(C U^{*} A U\right)\right|: U \text { unitary }\right\} .
$$

For $C=\operatorname{diag}(1,0, \ldots, 0)$ it reduces to the classical numerical radius $r(A)=\max \left\{\left|x^{*} A x\right|: x^{*} x=1\right\}$. We show that $r_{C}$ is a generalized matrix norm if and only if $C$ is nonscalar and $\operatorname{tr} C \neq 0$. Next, we consider an arbitrary generalized matrix norm and characterize all constants $v>0$ for which $v N$ is multiplicative. A technique to obtain such $v$ is then applied to C-numerical radii with Hermitian C. In particular we find that $v r$ is a matrix norm if and only if $v \geq 4$.

## CESTRTEOTION STATMALANTX

 Approved for mable release; Distribution UnlimitedAIR FORCE OFFICE OF SCIENTIFIC RESEARCH (AFC) NOTICE OF TREMSMITMEL 20 DOC This technical 1 :
approved :or

A. D. CLOSE

Technical Information officer

AMS (MOS) subject classification (1970). 15A60, 65F35
Key words and phrases. Numerical radius, semi-norms, generalized matrix norms, matrix norm, multiplicativity factors.
*The research of the first author was sponsored in part by the Air Force Office of Scientific Research, Air Force System Command, USAF, under Grant No. AFOSR-76-3646, The work of the second author was supported in part NSF MPS 71-2884

## 1. Introduction

Let $C_{n \times n}$ be the algebra of $n \times n$ complex matrices and let $u_{h}$ be its unitary group. Given $A, C \in C_{n \times n}$, the $C$-numerical range of $A$ is the compact set

$$
W_{C}(A)=\left\{\operatorname{tr}\left(C U^{*} A U\right): U \in u_{h}\right\} .
$$

This definition together with some properties of $W_{C}(A)$ were presented by the authors in [2].

It is not hard to see (compare [2], Lemma 9), that $W_{C}(A)$ is invariant under unitary similarities of $A$ or $C$. Hence, if $C$ is normal with eigenvalues $\gamma_{j}$, we easily find that
(1.1) $W_{C}(A)=W_{\operatorname{diag}}\left(\gamma_{1}, \ldots, \gamma_{n}\right)(A)=\left\{\sum_{j=1}^{n} \gamma_{j} x_{j}^{*} A x_{j}:\left\{x_{j}\right\} \in \Lambda_{n}\right\}$,
$\Lambda_{n}$ being the set of orthonormal bases for $C_{n}$. In particular, for $C=\operatorname{diag}(1,0, \ldots, 0)$, we obtain the classical range

$$
W(A)=\left\{x^{*} A x: x^{*} x=1\right\} .
$$

Associated with the classical range is the numerical radius

$$
r(A)=\max \{|z|: z \in W(A)\} .
$$

Similarly, we define the C-numerical radius to be

$$
r_{C}(A)=\max \left\{|z|: z \in W_{C}(A)\right\} .
$$

The main purpose of this work is to study the norm properties of $r_{C}$. The situation is trivial for $n=1$, so without further reference? we assume troughout the paper that $n \geq 2$.

We use the following standard definitions.
(i) A mapping $A \rightarrow N(A)$ is a semi-norm on $C_{n \times n}$, if for any $A, C \in C_{n \times n}$ and $\alpha \in E$

Dist. AVail. and /a specint

$$
\begin{aligned}
& \mathbb{N}(A) \geq 0 ; \\
& \mathbb{N}(\alpha A)=|\alpha| \mathbb{N}(A) ; \\
& \mathbb{N}(A+B) \leq \mathbb{N}(A)+\mathbb{N}(B) .
\end{aligned}
$$

(ii) A semi-norm is a generalized matrix norm if it is positive definite, that is,

$$
N(A)>0 \text { for } A \neq 0
$$

(iii) A generalized matrix norm is a matrix norm if it is (sub-) multiplicative, i.e., for all A, B,

$$
N(A B) \leq N(A) N(B)
$$

Without difficulty we obtain

THEOREM 1. For any $C, r_{C}$ is a semi-norm.

The questions of definiteness and multiplicativity are much more complicated.

In Section 2 we characterize those $C$ for which $r_{C}$ is positive definite. We show that $r_{C}$ is a generalized matrix norm if and only if $C$ is not scalar and tr $C \neq 0$. This result agrees with the well known fact that the classical radius $r$ is a generalized matrix norm.

The classical radius is not multiplicative, [4]. Hence, in general, a. C-radius cannot be expected to be a matrix norm.

In Section 3 we consider arbitrary generalized matrix norms, and characterize all positive constants $v$ for which $\boldsymbol{N N}$ is multiplicative. A technique of finding such multiplicativity factors is given by a theorem of Gastinel [1].

The above technique (aided by some combinatorial inequalities
-3-
obtained in Section 4) is applied in Section 5 to find multiplicativity factors for C-numerical radii with Hermitian C. In particular we find that $v r$ is a matrix norm if and only if $v \geq 4$.

Thanks are due to Alston Householder and to Robert Steinberg for helpful discussions.

## 2. Norm Characterization of C-radit.

## THEOREM 2. $r_{C}$ is a generalized matrix norm if and only if

$$
\begin{equation*}
C \text { is nonscalar and } \operatorname{tr} C \neq 0 . \tag{2.1}
\end{equation*}
$$

In the proof we use the following three lemmas in which A, C are given $n \times n$ matrices.

LEMMA 1. Let $m$ be an integer with $1 \leq m<n$. If $C$ leaves invariant all m-dimensional subspaces of $\mathbb{C}^{n}$, then $C$ is scalar.

Proof. Since $m<n$, then each one-dimensional subspace of $\mathcal{C}^{n}$ is an intersection of subspaces of dimension $m$, which by hypothesis, are fixed by C. This implies that $C$ fixes all one-dimensional subspaces of $\mathrm{C}_{\mathrm{n}}$.

Now let $\left\{e_{j}\right\}_{j=1}^{n}$ be the standard basis of ${\underset{\sim}{c}}^{n}$. By the preceding argument, there exist scalars $\lambda_{1}, \ldots, \lambda_{n}, \mu$, such that

$$
C e_{j}=\lambda_{j} e_{j}, \quad 1 \leq \mathrm{l} \leq \mathrm{n},
$$

and

$$
\text { c } \sum_{j=1}^{n} e_{j}=\mu \sum_{j=1}^{n} e_{j}
$$

Hence, $\quad \mathcal{\Sigma} e_{j}=\Sigma \lambda_{j} e_{j}$, and we conclude that $\lambda_{j}=\mu, 1 \leq j \leq n$. Therefore,

$$
C e_{j}=\mu e_{j}, \quad 1 \leq j \leq n ;
$$

i.e., $C=\mu I$, and the lemma follows.

LEMMA 2. If

$$
C U^{*} A U=U^{*} A U C \quad \forall U \in u_{\mathrm{h}},
$$

then either $A$ or $C$ are scalar.

Proof. Suppose A is not scalar and let us prove that C is. Let $\lambda$ be an eigenvalue of $A$ with corresponding eigenspace $X_{\lambda}$ of dimension $m$. Since $A$ is not scalar, then

$$
1 \leq m=\operatorname{dim}\left(\chi_{\lambda}\right)<\operatorname{dim}\left(c^{n}\right)=n .
$$

Now, for arbitrary $U \in u_{h}, U^{*} A U$ also has $\lambda$ as eigenvalue with corresponding eigenspace $U^{*} X_{\lambda^{\prime}}$. Thus, for every vector $v \in U^{*} X_{\lambda^{\prime}}$,

$$
U^{*} A U(C v)=C\left(U^{*} A U v\right)=C(\lambda v)=\lambda(C v)
$$

It follows that

$$
C v \in U^{*} X_{\lambda} \quad \forall v \in U^{*} X_{\lambda},
$$

that is, $C$ leaves $U^{*} X_{\lambda}$ invariant. Since $\operatorname{dim}\left(X_{\lambda}\right)=m$ and $U^{*}$ is arbitrary, we find that $C$ leaves invariant all m-dimensional subspaces of $C^{n}$. Hence, by Lemma 1, C is scalar and the proof is complete.

LEMMA 3. If

$$
\operatorname{tr}\left(C U^{*} A U\right)=\text { constant } \quad \forall U \in U_{\mathrm{h}},
$$

then

$$
C U^{*} A U=U^{*} A U C \quad \forall U \in u_{\mathrm{h}} \text {. }
$$

Proof. Let $S$ be skew-Hermitian; then $e^{\theta S}$ is unitary for all real $\theta$, and so is $U e^{\theta S}$. By hypothesis therefore,

$$
f(\theta) \equiv \operatorname{tr}\left[C\left(U e^{\theta S}\right) * A\left(U e^{\theta S}\right)\right]=\text { constant }, \quad \theta \in R ;
$$

and consequently,

$$
\begin{gathered}
\frac{d}{d \theta} f(\theta)=\frac{d}{d \theta} \operatorname{tr}\left(C e^{-\theta S} U^{*} A U e^{\theta S}\right)= \\
=\operatorname{tr}\left(\mathrm{Ce}^{-\theta S} U^{*} A S e^{\theta S}-\mathrm{CSe}^{-\theta S} U^{*} A U e^{\theta S}\right)=0 .
\end{gathered}
$$

Evaluating the derivative at $\theta=0$ we obtain

$$
\operatorname{tr}\left(C U^{*} A U S-\operatorname{CSU}^{*} A U\right)=0 ;
$$

hence for all skew-Hermitian $S$ (and all unitary U),

$$
\operatorname{tr}\left[\left(C U^{*} A U-U^{*} A U C\right) S\right]=0
$$

Since every matrix B is a linear combination of skew-Hermitians*, the last identity implies

$$
\operatorname{tr}\left[\left(C U^{*} A U-U^{*} A U C\right) B\right]=0 \quad \forall B \in C_{n \times \infty} .
$$

Thus,

$$
C U^{*} A U-U^{*} A U C=0,
$$

and the lemma is proven.

Proof of Theorem 2. By Theorem 1, it suffices to show that (2.1) holds if and only if $r_{C}$ is positive definite.

If $C$ is scalar, namely $C=\lambda I$, then any $A \neq 0$ with $\operatorname{tr} A=0$ gives

$$
r_{C}(A)=|\lambda \operatorname{tr} A|=0
$$

*For example, $B=S_{1}-1 S_{2}$ with $S_{1}=\frac{1}{2}\left(B-B^{*}\right), S_{2}=\frac{1}{2}\left(B+B^{*}\right)$.

Also, if $\operatorname{tr} C=0$, then

$$
r_{C}(I)=|\operatorname{tr} C|=0
$$

Thus, violation of (2.1) implies the indefiniteness of $r_{C}(\cdot)$.
Conversely, let (2.1) hold. If $r_{C}(A)=0$, then by definition

$$
\operatorname{tr}\left(C U^{*} A U^{*}\right)=0 \quad \forall U \in u_{n} ;
$$

so by Lemma 3,

$$
C U^{*} A U=U^{*} A U C \quad \forall U \in u_{h} .
$$

By Lemma 2, therefore, either C or A are scalar, and since $C$ is not, $A$ is. Setting $A=\mu I$ we have

$$
r_{C}(A)=|\mu \operatorname{tr} C|=0,
$$

and since $\operatorname{tr} C \neq 0$, then $\mu$ must vanish and the proof is established.

EXAMPLE 1. The $k$-numerical range, $1 \leq k \leq n$, was defined by Halmos $[3, \S 167]$ to be

$$
W_{k}(A)=\{\operatorname{tr}(P A): P \text { orthonormal projection of rank } k\} \text {. }
$$

We easily verify that

$$
W_{k}(A)=W_{C_{k}}(A) \text { where } C_{k}=I_{k} \oplus O_{n-k}
$$

Thus, the $k$-numerical radius

$$
r_{k}(A)=\max \left\{|z|: z \in W_{k}(A)\right\},
$$

is a generalized matrix norm if and only if $1 \leq k \leq n-1$. In particular $r(A)=r_{1}(A)$ is a generalized norm while $r_{n}(A)=|\operatorname{tr} A|$ is not.

## 3. Multiplicatixity Factors and Gastinel's Theorem

Given a semi-norm $N$ on $C_{\text {non }}$ and a constant $v>0$, then obviously

$$
\mathbf{N}_{v} \equiv v \mathbf{N}
$$

is a semi-norm too. Similarly, $N$ is definite if and only if $N_{v}$ is. In any case the new norm may or may not be multiplicative. If it is, we say that $v$ is a multiplicativity factor of $N$.

A characterization of multiplicativity factors for generalized matrix norms is given in Theorem 4. We first prove, however, that indefinite nontrivial semi-norms have no multiplicativity factors.

THEOREM 3. An indefinite semi-norm $\dot{N}$ on $C_{n \times n}$ is multiplicative if and only if $N \equiv 0$.

Proof. The trivial semi-norm is certainly multiplicative. So let N be indefinite and multiplicative, and let us show that $\mathrm{N} \equiv 0$.

Since $N$ is indefinite, then $N(A)=0$ for some $A \neq 0$. Let $\alpha_{\ell k}$ be a nonvanishing entry of $A$, and denote by $E_{i j}$ the matrix whose $(i, j)$ element is 1 and the others are zero. Since

$$
E_{i \ell} A E_{k j}=\alpha_{\ell k} E_{i j}
$$

then by multiplicativity,

$$
\left|\alpha_{\ell k}\right| N\left(E_{i j}\right)=N\left(\alpha_{\ell k} E_{i j}\right) \leq N\left(E_{i \ell}\right) N(A) N\left(E_{k j}\right)=0 .
$$

We conclude that

$$
N\left(E_{i j}\right)=0 \quad \forall l \leq i, j \leq n ;
$$

thus for any $B=\left(\beta_{i j}\right) \in C_{n \times n}$,

$$
N(B)=N\left(\sum_{i, j} \beta_{i j} E_{i j}\right) \leq \sum_{i, j}\left|\beta_{i j}\right| N\left(E_{i j}\right)=0,
$$

and the theorem follows.

THEOREM 4. If $N$ is a generalized matrix norm, then $v$ is a maltiplicativity factor of $N$ (i.e., $N_{v}$ is a matrix norm) if and only if

$$
v \geq v_{N} \equiv \max _{A, B \neq 0} \frac{N(A B)}{N(A) N(B)}
$$

Proof. We write $v_{N}$ in the form

$$
v_{N}=\max \{N(A B): N(A)=N(B)=1\},
$$

and use a compactness argument to conclude that $v_{N}$ is well defined.
It is clear then that $v_{N}>0$.
Now, if $v \geq v_{N}$, then

$$
N_{v}(A B)=\nu \mathbb{N}(A B) \leq \nu v_{N} N(A) N(B) \leq v^{2} N(A) N(B)=N_{v}(A) N_{v}(B) ;
$$

hence $N$ is multiplicative.
Conversely, if $v$ satisfies $0<v<\nu_{N}$, we can find matrices $A, B$ such that $\sim N(A) N(B)<N(A B)$. Thus we have

$$
N_{v}(A B)=\nu N(A B)>v^{2} N(A) N(B)=N_{v}(A) N_{v}(B),
$$

and the proof is complete.

As an immediate consequence we have established

COROLIARY 1. A generalized matrix norm $N_{v}$ is a matrix norm if and only if $v_{N} \leq 1$.

In practice, Theorem 4 offers limited help since in general, $v_{N}$ is
not easily evaluated. In the case of C-numerical radii, we were unable to find the optimal factor except for the classical radius.

An alternative way of finding multiplicativity factors is suggested by the following, somewhat stronger version of a theorem by Gastinel, [1].

THEOREM 5. Let $N$ be a semi-norm, $M$ a matrix norm, and $\eta \geq \xi>0$ constants such that

$$
\begin{equation*}
\xi M(A) \leq N(A) \leq \eta M(A) \quad \forall A \in C_{n \times n} . \tag{3.1}
\end{equation*}
$$

Then,
(i) N is a generalized matrix norm.
(ii) For any $v \geq \eta / \xi^{2}, N_{v}$ is a matrix norm.
(iii) If $\eta / \xi^{2} \leq 1$, then $N$ is a matrix norm.

Proof. Part (i) is trivial, and for part (ii) we should merely note that

$$
\begin{aligned}
& \mathbb{N}_{v}(A B)=\nu N(A B) \leq \nu \eta M(A B) \leq \nu \eta M(A) M(B) \\
& \leq \frac{\nu \eta}{\xi} N(A) N(B) \leq \nu \geqslant N(A) N(B)=N_{v}(A) N_{v}(B)
\end{aligned}
$$

Part (iii) then follows.

We recall, of course, that any two norms on $C_{n \times n}$ are equivalent. Thus if $\mathbf{N}$ of Theorem 5 is known to be a matrix norm, then (3.1) always holds for suitable constants $\eta \geq \boldsymbol{\xi}>0$.

In Section 5 we use Theorem 5 to obtain multiplicativity factors for C-numerical radii with Hermitian $C$.
4. Some Combinatorial Inecualities

Let $\alpha_{j}, \gamma_{j}, 1 \leq j \leq n$, be scalars and consider the set

$$
g_{\gamma}(\alpha)=\left\{\sum_{j=1}^{n} \gamma_{j} \alpha_{\sigma(j)}: \sigma \in S_{n}\right\}
$$

$S_{n}$ being the symmetric group. In this section we study bounds for the radius of $\varepsilon_{\gamma}(\alpha)$,

$$
R_{\gamma}(\alpha)=\max \left\{|z|: z \in \varepsilon_{\gamma}(\alpha)\right\}
$$

A general remark is that all the involved quantities are invariant under rearrangements of the $\alpha_{i}$ and the $\gamma_{j}$, and under rotations of the form

$$
\left(\alpha_{1}, \ldots, \alpha_{n}\right) \rightarrow e^{i \varphi}\left(\alpha_{1}, \ldots, \alpha_{n}\right),\left(\gamma_{1}, \ldots, \gamma_{n}\right) \rightarrow e^{i \psi}\left(\gamma_{1}, \ldots, \gamma_{n}\right)
$$

which include, of course, change of sign. This fact will be repeatedly used in the proof of the following results.

LEMMA 4. For any $\alpha_{j}, \gamma_{j} \in \mathbb{C}$

$$
R_{\gamma}(\alpha) \geq \frac{1}{n}\left|\sum_{j=1}^{n} \alpha_{j}\right|\left|\sum_{j=1}^{n} \gamma_{i}\right|
$$

Proof. Let $\tau^{1}, i=1,2, \ldots, n$, be the powers of a nontrivial cyclic permatation in $S_{n}$. Since

$$
\sum_{j=1}^{n} \gamma_{j}^{\alpha} \tau_{\tau^{i}(j)} \in \&_{\gamma}(\alpha), \quad 1 \leq i \leq n
$$

then

$$
\begin{aligned}
R_{\gamma}(\alpha) & \geq\left|\frac{1}{n} \sum_{i=1}^{n}\left(\sum_{j=1}^{n} \gamma_{j} \alpha_{\tau^{i}(j)}\right)\right| \\
& =\left|\frac{1}{n} \sum_{j} \gamma_{j} \sum_{i} \alpha_{\tau^{i}(j)}\right|=\left|\frac{1}{n} \sum_{j} \gamma_{j} \sum_{i} \alpha_{i}\right|
\end{aligned}
$$

-11-
and the lemma holds.

LEMMA 5. If $\alpha_{i} \in R, \gamma_{j} \in \mathbb{C}, 1 \leq j \leq n$, then

$$
R_{\gamma}(\alpha) \geq \frac{1}{2} \max _{i, j}\left|\alpha_{i}-\alpha_{j}\right| \max _{i, j}\left|\gamma_{i}-\gamma_{j}\right|
$$

Proof. Setting

$$
\gamma_{j}=\lambda_{j}+i \mu_{j}, \quad \lambda_{j}, \mu_{j} \in \underset{\sim}{R}
$$

we have

$$
\begin{aligned}
R_{\gamma}(\alpha) & =\max _{\sigma \in S_{n}}\left|\sum_{j} \lambda_{j} \alpha_{\sigma(j)}+i \sum_{j} \mu_{j} \alpha_{\sigma(j)}\right| \\
& \geq \max _{\sigma \in S_{n}}\left|\sum_{j} \lambda_{j} \alpha_{\sigma(j)}\right|=R_{\lambda}(\alpha)
\end{aligned}
$$

Now, if the $\gamma_{j}$-are equal, then the result is trivial; so by rotating and rearanging the $\gamma_{j}$, we may assume that

$$
\max \left|\gamma_{i}-\gamma_{j}\right|=\gamma_{1}-\gamma_{n}>0
$$

It follows that

$$
\lambda_{1}-\lambda_{n}=\gamma_{1}-\gamma_{n}=\max _{i, j}\left|\gamma_{i}-\gamma_{j}\right| \geq \max _{i, j}\left|\lambda_{i}-\lambda_{j}\right| .
$$

Thus

$$
\lambda_{1} \geq \lambda_{j} \geq \lambda_{n}, \quad 2 \leq j \leq n-1
$$

'so we may assume that

$$
\lambda_{1} \geq \lambda_{2} \geq \cdots \geq \lambda_{n} .
$$

We may also assume that

$$
\alpha_{1} \geq \alpha_{2} \geq \cdots \geq \alpha_{n}
$$

Hence, observing that

$$
s_{1}=\sum \lambda_{j} \alpha_{j}, \quad s_{2}=\sum \lambda_{j} \alpha_{n-j}
$$

are two points in $g_{\gamma}(\alpha)$, we have
$R_{\lambda}(\alpha) \geq \frac{1}{2}\left|s_{1}-s_{2}\right|=\frac{1}{2}\left|\lambda_{1}\left(\alpha_{1}-\alpha_{n}\right)+\lambda_{2}\left(\alpha_{2}-\alpha_{n-1}\right)+\cdots+\lambda_{n}\left(\alpha_{n}-\alpha_{1}\right)\right|$
$=\frac{1}{2}\left|\left(\lambda_{1}-\lambda_{n}\right)\left(\alpha_{1}-\alpha_{n}\right)+\left(\lambda_{2}-\lambda_{n-1}\right)\left(\alpha_{2}-\alpha_{n-1}\right)+\ldots+\left(\lambda\left[\frac{n}{2}\right]^{-\lambda}\left[\frac{n}{2}\right]+1\right)\left(\alpha_{1}\left[\frac{n}{2}\right]^{-\alpha^{2}}\left[\frac{n}{2}\right]+1\right)\right|$
$\geq \frac{1}{2}\left(\lambda_{1}-\lambda_{n}\right)\left(\alpha_{1}-\alpha_{n}\right)=\frac{1}{2} \max \left|\gamma_{i}-\gamma_{j}\right| \max \left|\alpha_{i}-\alpha_{j}\right|$,
and the lemma follows.
We are interested now in obtaining constants $K_{\gamma}$, which may depend on the $\gamma_{j}$ but not on the $\alpha_{j}$, such that

$$
\begin{equation*}
M_{\gamma}(\alpha) \geq K_{\gamma} \max \left|\alpha_{j}\right| \quad \forall \alpha_{1}, \ldots, \alpha_{n} \in R . \tag{4.1}
\end{equation*}
$$

THEOREM 6. For given $\gamma_{j} \in \mathbb{C}, 1 \leq \mathrm{j} \leq \mathrm{n}$, there exists a constant $K_{\gamma}>0$ which satisfies (4.1) if and only if

$$
\begin{equation*}
\gamma_{j} \text { are not all equal and } \sum_{j} \gamma_{j} \neq 0 \tag{4.2}
\end{equation*}
$$

If (4.2) holds, then (4.1) is satisfied by the positive constant

$$
\begin{equation*}
K_{\gamma}=\frac{\left|\sum_{j} \gamma_{j}\right| \cdot \max \left|\gamma_{i}-\gamma_{j}\right|}{2\left|\sum_{j} \gamma_{j}\right|+\underset{i, j}{\max \left|\gamma_{i}-\gamma_{j}\right|}} \tag{4.3}
\end{equation*}
$$

Proof. Suppose (4.2) is violated. If the $\gamma_{j}$ are equal, we choose $\alpha_{j}$ not all equal, with $\Sigma \alpha_{j}=0$; if $\Sigma \gamma_{j}=0$, we take $\alpha_{j}=1$, $1 \leq \mathrm{j} \leq \mathrm{n}$. In both cases $\mathrm{R}_{\gamma}(\alpha)=0$ but $\max \left|\alpha_{j}\right|>0$; hence no positive $K_{\gamma}$ satisfies (4.1).

Conversely, let (4.2) hold, and let $K_{\gamma}$ be the constant specified
in (4.3). We may assume that

$$
\alpha_{1} \geq \cdots \geq \alpha_{n},
$$

where in fact, by change of sign if necessary, it suffices to consider the cases

$$
\begin{equation*}
\alpha_{1} \geq \cdots \geq \alpha_{n} \geq 0 \tag{4.4a}
\end{equation*}
$$

and
(4.4b) $\quad \alpha_{1} \geq \cdots \geq \alpha_{k} \geq 0>\alpha_{k+1} \geq \cdots \geq \alpha_{n}$ with $\max \left|\alpha_{j}\right|=\alpha_{1}$.

In case (4.4a) we write $\alpha_{n}=\theta \alpha_{1}, 0 \leq \theta \leq 1$, and use Lemmas 4 and 5 to obtain, respectively,

$$
R_{\gamma}(\alpha) \geq \frac{1}{n}\left|\Sigma \alpha_{j}\right|\left|\Sigma \gamma_{j}\right|>\alpha_{n}\left|\Sigma \gamma_{j}\right|=\theta \alpha_{1}\left|\Sigma \alpha_{j}\right|=\theta\left|\Sigma \gamma_{j}\right| \max \left|\alpha_{j}\right|
$$

and

$$
\begin{aligned}
R_{\gamma}(\alpha) & \geq \frac{1}{2} \max \left|\alpha_{i}-\alpha_{j}\right| \max \left|\gamma_{i}-\gamma_{j}\right|=\frac{1}{2}\left(\alpha_{1}-\alpha_{n}\right) \max \left|\gamma_{i}-\gamma_{j}\right| \\
& \geq \frac{1}{2}(1-\theta) \max \left|\gamma_{i}-\gamma_{j}\right| \max \left|\alpha_{j}\right|
\end{aligned}
$$

We thus find that

$$
R_{\gamma}(\alpha) \geq \max \left\{\theta\left|\Sigma \gamma_{j}\right|, \frac{1}{2}(1-\theta) \max \left|\gamma_{i}-\gamma_{j}\right|\right\} \cdot \max \left|\alpha_{j}\right| \cdot
$$

The expressions in the above braces are functions of $\theta$ which describe straight lines with opposite slopes and intersection value $K_{\gamma}$. Hence, for any $\theta$

$$
\max \left\{\theta\left|\Sigma \gamma_{j}\right|, \frac{1}{2}(1-\theta) \max \left|\gamma_{i}-\gamma_{j}\right|\right\} \geq K_{\gamma}
$$

and (4.1) follows.
In case (4.4b) we use Lemma 5 to find that

$$
R_{\gamma}(\alpha) \geq \frac{1}{2}\left(\alpha_{1}-\alpha_{n}\right) \max \left|\gamma_{1}-\gamma_{n}\right|>\frac{1}{2} \max \left|\gamma_{i}-\gamma_{j}\right| \max \left|\alpha_{j}\right| .
$$

Since

$$
\frac{1}{2} \max \left|\gamma_{i}-\gamma_{j}\right|>K_{\gamma}
$$

then (4.1) holds again, and the theorem is proven.

The above result can be improved for certain classes of $\gamma_{j}$.

THEOREM 7. If $\gamma_{j}, l \leq j \leq n$, are complex scalars of the same argument, then (4.1) holds with

$$
\begin{equation*}
K_{\gamma}=\frac{1}{2} \frac{\max }{i, j}\left|\gamma_{i}-\gamma_{j}\right| \tag{4.5}
\end{equation*}
$$

Proof. By change of argument and rearangement we may assume that

$$
\gamma_{1} \geq \cdots \geq \gamma_{n} \geq 0,
$$

and that the $\alpha_{j}$ satisfy (4.4a) or (4.4b).
For (4.4a) we have

$$
R_{\gamma}(\alpha)=\sum \gamma_{j} \alpha_{j} \geq \gamma_{1} \alpha_{1} \geq \frac{1}{2}\left(\gamma_{1}-\gamma_{n}\right) \alpha_{1}
$$

and for (4.4b), Lemma 5 yeilds

$$
\mathrm{R}_{\gamma}(\alpha) \geq \frac{1}{2}\left(\gamma_{1}-\gamma_{n}\right)\left(\alpha_{1}-\alpha_{n}\right)>\frac{1}{2}\left(\gamma_{1}-\gamma_{n}\right) \alpha_{1}
$$

Thus,

$$
\mathrm{R}_{\gamma}(\alpha) \geq \frac{1}{2} \max \left|\gamma_{i}-\gamma_{j}\right| \max \left|\alpha_{j}\right|,
$$

and the proof is complete.
Indeed, comparing $K_{\gamma}$ of (4.5) with $K_{\gamma}$ of (4.3), we realize that for the relevant $\gamma_{j}$, Theorem 6 provides a tighter lower bound for ${ }^{R_{\gamma}}(\alpha)$ than Theorem 5.

## 5. Multiplicatixe Hermitian Radit

As indicated previously, the purpose of this section is to obtain multiplicativity factors for C-numerical radii with Hermitian
C.

LEMMA 6. Let $A, C$ be normal matrices with eigenvalues $\alpha_{j}$ and $\gamma_{j}$, respectively. Then

$$
r_{C}(A)=R_{\gamma}(\alpha)
$$

Proof. Obviously, it suffices to show that

$$
\operatorname{conv} W_{C}(A)=\operatorname{conv} g_{\gamma}(\alpha)
$$

Since $W_{C}(A)$ is invariant under unitary similarities of $A$ and $C$, and since $A$ and $C$ are normal, then by (1.1),

$$
W_{C}(A)=\left\{\sum_{j=1}^{n} \gamma_{j} x_{j}^{*} \operatorname{diag}\left(\alpha_{1}, \ldots, \alpha_{n}\right) x_{j}:\left\{x_{j}\right\} \in \Lambda_{n}\right\} .
$$

Thus, using the standard basis $\left\{e_{j}\right\}$, we find that every point in $g_{\gamma}(\alpha)$ satisfies

$$
\sum_{j} \gamma_{j} \alpha_{\sigma(j)}=\sum \gamma_{j} e_{\sigma(j)}^{*} \operatorname{diag}\left(\alpha_{1}, \ldots, \alpha_{n}\right) e_{\sigma(j)} \in W_{C}(A),
$$

which gives us

$$
g_{\gamma}(\alpha) \subseteq W_{C}(A)
$$

Conversely, take an arbitrary point,

$$
\sum_{j} \gamma_{j} x_{j}^{*} \text { diag }\left(\alpha_{l}, \ldots, \alpha_{n}\right) x_{j} \in W_{C}(A) .
$$

Since $x_{j}=\left(x_{j 1}, \ldots, x_{j n}\right)^{T}, 1 \leq j \leq n$, is an orthonormal basis, then $X \equiv\left[\left|x_{j k}\right|^{2}\right]$ is a doubly stochastic matrix. Doubly stochastic matrices are convex combinations of permutation matrices $P_{\sigma}$. Thus writing $X=\sum_{\sigma} \lambda_{\sigma} p_{\sigma} \quad$ and

$$
a \equiv\left(\alpha_{1}, \ldots, \alpha_{n}\right)^{T}, \quad c \equiv\left(\gamma_{1}, \ldots, \gamma_{n}\right)^{T}
$$

we have

$$
\begin{aligned}
& \sum_{j} \gamma_{j} x_{j}^{*} \operatorname{diag}\left(\alpha_{1}, \ldots, \alpha_{n}\right) x_{j}=\sum_{j, k} \gamma_{j}\left|x_{j k}\right|^{2} \alpha_{k}=c^{T} X_{a}= \\
&= c^{T}\left[\sum_{\sigma \in S_{n}} \lambda \alpha_{\sigma} P_{\sigma}\right] a=\sum_{\sigma} \lambda_{\sigma}\left(c^{T} P_{\sigma} a\right)=\sum_{\sigma} \lambda_{\sigma}\left[\sum_{j} \gamma_{j} \alpha_{\sigma(j)}\right] \in \operatorname{conv} g_{\gamma}(\alpha) .
\end{aligned}
$$

This yields

$$
W_{C}(A) \subseteq \operatorname{conv} g_{\gamma}(\alpha)
$$

and the lemma follows.

LEMMA 7. Let $C$ be normal with eigenvalues $\gamma_{j}$, let $K_{\gamma}$ satisfy (4.1), and let

$$
\|A\|_{2} \equiv \max \left\{\left(x^{*} A A^{*} A x\right)^{1 / 2}: x^{*} x=1\right\}
$$

denote the spectral norm of $A$. Then

$$
\mathbf{r}_{C}(A) \geq K_{\gamma}\|H\|_{2} \quad \forall \text { Hermitian } H \in C_{n \times n}
$$

Proof. For Hermitian $H$ with eigenvalues $\alpha_{j}$, we know that

$$
\|H\|_{2}=\max \left|\alpha_{j}\right|
$$

Since the $\alpha_{j}$ are real, we may use (4.1), and by Lemma 6

$$
r_{C}(A)=R_{\gamma}(\alpha) \geq K_{\gamma} \max \left|\alpha_{j}\right|=K_{\gamma}\|A\|_{2}
$$

LMMMA 8. If $C$ is Hermitian, then $r_{C}(A)=r_{C}\left(A^{*}\right)$.

Proof.

$$
r_{C}(A)=\max _{U}\left|\operatorname{tr}\left(C U^{*} A U\right)\right|=\max _{U}\left|\operatorname{tr}\left(C U^{*} A U\right)^{*}\right|=\max _{U}\left|\operatorname{tr}\left(U^{*} A^{*} U C\right)\right|=r_{C}\left(A^{*}\right) .
$$

LEMMA 9. If $C$ is Hermitian with eigenvalues $\gamma_{j}$, and if $K_{\gamma}$
satisfies (4.1), then

$$
r_{C}(A) \geq \frac{1}{2} K_{\gamma}\|A\|_{2} \quad \forall A \in C_{n \times n}
$$

Proof. We write $A=\frac{1}{2}\left(H_{1}-1 H_{2}\right)$, where

$$
H_{1}=A+A^{*}, \quad H_{2}=i\left(A-A^{*}\right)
$$

are Hermitian. By Lemmas 7 and 8 , and by Theorem 1,

$$
\begin{aligned}
& \frac{1}{2} K_{\gamma}\|A\|_{2}=\frac{1}{4} K_{\gamma}\left\|H_{1}-i H_{2}\right\|_{2} \leq \frac{1}{4} K_{\gamma}\left[\left\|_{1}\right\|_{2}+\left\|H_{2}\right\|_{2}\right] \leq \frac{1}{4}\left[r_{C}\left(H_{1}\right)+r_{C}\left(H_{2}\right)\right] \\
& =\frac{1}{4}\left[r_{C}\left(A+A^{*}\right)+r_{C}\left(A-i A^{*}\right)\right] \leq \frac{1}{2}\left[r_{C}(A)+r_{C}\left(A^{*}\right)\right]=r_{C}(A),
\end{aligned}
$$

and the proof is complete.

LEMA 10. If $C$ is normal with eigenvalues $\gamma_{j}$, then

$$
r_{C}(A) \leq \sum_{j}\left|\gamma_{j}\right|\|A\|_{2} \quad \forall A \in C_{n \times n_{n}}
$$

Proof. By (1.1) we have

$$
r_{C}(A)=\max \left\{\left|\sum_{j} \gamma_{j} x_{j}^{*} A x_{j}\right|:\left\{x_{j}\right\} \in \Lambda_{n}\right\} ;
$$

and since $\left|x^{*} A x\right| \leq\|A\|_{2}$ for any unit vector $x$, the lemma follows.
THEOREM 8. Let $C$ be Hermitian, nonscalar, with $\operatorname{tr} \mathcal{C} 0$ and
eigenvalues $\gamma_{j}$. Then, for any $v$ with

$$
v \geq 4 \sum_{j}\left|\gamma_{j}\right|\left[\frac{2\left|\sum_{j} \gamma_{j}\right|+\max _{i, j}\left|\gamma_{i}-\gamma_{j}\right|}{\left|\sum_{j} \gamma_{j}\right| \cdot \frac{\max \left|\gamma_{i}-\gamma_{j}\right|}{2}}\right]^{2}
$$

the (Hermitian) numerical radius $\quad \nu r_{C} \equiv r_{\nu C}$ is a matrix norm.
Proof. Since $C$ is nonscalar, the $\gamma_{j}$ are not all equal; and since $\operatorname{tr} C \neq 0$, then $\sum \gamma_{j} \neq 0$. Thus, by Theorem 6 , the inequality in (4.1) is satisflied by the positive constant $K_{\gamma}$ of (4.3). By Lemmas 9 and 10 we have therefore,

$$
\frac{1}{2} \frac{\left|\Sigma \gamma_{j}\right|+\max \left|\gamma_{i}-\gamma_{j}\right|}{2\left|\Sigma \gamma_{j}\right|+\max \left|\gamma_{i}-\gamma_{j}\right|}\|A\|_{2} \leq r_{C}(A) \leq \Sigma\left|\gamma_{j}\right|\|A\|_{2} \quad \forall A \in \mathbb{C}_{n \times n}
$$

and Theorem 5 completes the proof.

For Hermitian definite $C$, we improve Theorem 6 as follows.

THEOREM 9. Let $C$ be Hermitian nonnegative (nonpositive) definite.
If $C$ is nonscalar with eigenvalues $\gamma_{j}$, then for every $v$ with $v \geq \frac{16 \sum_{i}\left|\gamma_{j}\right|}{\max \mid \gamma_{i}-\gamma_{j}}$,
$v r_{C} \equiv r_{v C}$ is a matrix norm.
Proof. Since $C$ is Hermitian definite, the $\gamma_{j}$ are of the same sign and by Theorem 7, $K_{\gamma}$ of (4.5) satisfles (4.1). Lemmas 9 and 10 yield now,
(5.1) $\quad \frac{1}{4} \max \left|\gamma_{i}-\gamma_{j}\right|\|A\|_{2} \leq r_{C}(A) \leq \Sigma\left|\gamma_{j}\right|\|A\|_{2} \quad \forall A \in C_{n \times n}$.

Since $C$ is nonscalar, the $\gamma_{j}$ are not all equal; so $\max \left|\gamma_{i}-\gamma_{j}\right|>0$, and Theorem 5 completes the proof.

EXAMPLE 2. We recall the definition of the $k$-numerical radius $r_{k}$. By Theorem 7, we find that $v_{k}, 1 \leq k \leq n-1$, is a matrix norm if $v \geq 16 k$.

Ecample 2 implies that $v \geq 16$ is a miltiplicativity factor for the classical radius $r$. The optimal factor, $v_{r}$, is given in the following result.

THEOREM 10. $v r$ is a matrix norm if and only if $v \geq 4$; that is $v_{r}=4$.

Proof. It is well known, [3, §162], that

$$
\frac{1}{2}\|\mathrm{~A}\|_{2} \leq r(\mathrm{~A}) \leq\|\mathrm{A}\|_{2} \quad \forall \mathrm{~A} \in \mathrm{C}_{\mathrm{n} \times \mathrm{n}} .
$$

Thus, by Theorem 5, $v \geq 4$ is a multiplicativity factor for $r$, and by Theorem 4, $v_{r} \leq 4$.

To show that $v_{r} \geq 4$, consider the matrices

$$
A=\left(\begin{array}{ll}
0 & 1 \\
0 & 0
\end{array}\right) \oplus I_{n-2}, \quad B=\left(\begin{array}{ll}
0 & 0 \\
1 & 0
\end{array}\right) \oplus I_{n-2}
$$

A simple calculation shows that

$$
\mathbf{r}(A)=r(B)=\frac{1}{2}, \quad r(A B)=1
$$

Hence

$$
r_{v}(\mathrm{AB}) \leq r_{v}(\mathrm{~A}) r_{v}(\mathrm{~B})
$$

if and only if $v \geq 4$, and the theorem follows.

## RGFERENCES

1. N. Gastinel, Linear Numerical Analysis, Academic Press, 1970.
2. M. Goldberg and E. G. Straus, Elementary inclusion relations for generalized numerical ranges, Linear Algebra Appl., Vol. 18 (1977) 1-24.
3. P. R. Halmos, A Hilbert Space Problem Book, Van Nostrand, 1967.
4. C. Pearcy, An elementary proof for the power inequality for numerical radius, Mich. Math. J., Vol. 13 (1966) 289-291.


SECURITY CLASSIFICATION OF THIS PAGE(When Dath Enterod)

```
    (con't) 20. Abstract
    r(A)}=\operatorname{max}{|\mp@subsup{x}{}{*}Ax|:\mp@subsup{x}{}{*}x=1}\mathrm{ . We show that }\mp@subsup{r}{C}{}\mathrm{ is a generalized matrix norm
    if and only if C is nonscalar and tr C }\not=0\mathrm{ . Next, we consider an arbitrary
    generalized matrix norm and characterize all constants v>0 for which UN
    is multiplicative. A technique to obtain such v}\mathrm{ is then applied to
    C-numerical radii with Hemitian C. In particular we find that vr is a
    matrix norm if and only if v}\geq4
```

