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EARTH PENETRATOR DESIGN STUDY PROGRAM SUBSCALE BALLISTIC PENETRATION TESTS

Avco Corporation
Avco Systems Division
201 Lowell Street
Wilmington, Massachusetts 01887

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| 20. ABSTRACT (Continue on reverse side if necessary and identify by block number) A series of 24 penetration tests were performed at various combinations of angle of attack and obliquity using three different models. Ogive, single stepped tier and conical tipped scale models were used to penetrate through concrete into a sand media. All tests were performed at 1000 ft/s. Copper balls were used to measure the peak deceleration for each test. Grids were used to monitor the penetrator trajectory and change of velocity through the sand media. | | |

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20. ABSTRACT (Continued)

△ Test results including velocity, angle of attack, obliquity, crater size, copper ball deformation, trajectory and change of velocity in sand media are reported. Variations in performance as a function of tip configurations are discussed. The results provide an extensive and significant addition to the understanding of the interaction between earth penetrators and representative target media. ↗

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PREFACE

A series of 24 subscale penetration tests were performed to investigate the variation of performance as a function of tip configuration. Ogive, single stepped tier and conical tipped subscale projectiles were fired through a concrete target into a sand media at various angles of attack and obliquity. The results of these successful tests may be used to refine predictive techniques concerning the performance of earth penetrators in typical target media.

The Program was conducted under Contract DNA001-C-76-0057-P00001 for the Defense Nuclear Agency. This work was administered under the direction of Lt. R. Nibe.

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1.0 INTRODUCTION

A major factor in earth penetrator (EP) performance is the tip configuration. A program was initiated to determine the relative penetration performance of three different tip configurations. Full scale earth penetrators were designed with ogive, single stepped tier (SST) and conical tips. The total weight, c.g. location, and tip geometry was defined for each configuration. One twelfth scale models were designed to duplicate each of the important design parameters as closely as possible. These subscale model designs included provisions for a copper ball passive accelerometer.

Subscale EP models were fabricated and tested. A total of 24 tests were performed at various combinations of angle of attack and obliquity for each of the three model configurations. Tests were conducted at 1000 ft/s impact velocity through concrete into a sand media. EP model performance was monitored and compared.

The primary purpose of these tests was to determine relative "g" loads and trajectory performance for three realistic design configurations under typical operational conditions. It was further intended that the test results should provide a data base which could be used to predict future EP performance with regard to "g" loading and trajectory performance. This type of information is needed to ensure that EP designs can be evolved which can be realistically expected to achieve program objectives.

This report documents the subscale EP model test hardware, instrumentation, procedures, results and data trends. Detailed analysis of the data to develop and refine predictive computer trajectory codes is beyond the scope of this activity. However, it is recommended that detailed analysis of the test data be undertaken as a part of a future program to maximize data utility and to increase understanding of earth penetrator phenomenology.

2.0 TEST HARDWARE

Tests were conducted with subscale EP models fabricated to the three configurations shown in Figures 1 through 3. These represent 1/12 scale models of full scale penetrator design. Full scale designs were developed for each of the three candidate configurations; ogive, SST and conical tip designs. Each design realistically considered EP geometry, internal components, mass and c.g. The models were developed by scaling the total mass of the full scale design and the relative c.g. location into the models in a representative fashion. The design included the passive copper ball accelerometers. The three EP models are shown in Figure 4 together with the passive accelerometer assembly. An exploded detail of the passive accelerometer assembly is shown in Figure 5. The test model weights and c.g.'s are compared with the theoretical 1/12 scale model values in Table 1. As may be seen the models were very close to the desired values in all cases.

The test models were machined from maraging steel and heat treated to a hardness of approximately 50 on the Rockwell C scale. This is equivalent to an ultimate strength in excess of 255,000 lb/in².

The copper ball passive accelerometer design was based on work performed as reported in References 1 and 2. These reports were prepared by Mr. Val DeVost of the Naval Ordnance Laboratory, White Oak, Maryland. Mr. DeVost was of great assistance during this program, providing insight into the design and fabrication of these devices. He further identified a source and quality assurance procedure for the copper balls. NOL copper ball passive accelerometers (MOD 10-200,000 g) were used in all tests. The passive accelerometer assemblies including the copper balls were obtained from Halpro, Inc., Rockville, Maryland. These assemblies were made in accordance with Halpro Drawing No. 2425615. Copper balls were 0.1553 inch in diameter and were quality controlled to a tolerance of plus 0.0002 inch minus zero inches.

Heat treat: 900° - 925°F - 3 hrs - air cool

1/4 - 20 N.C.

1.602 dia

1.39 dia

1.20 dia

1 7/16 - 40 thd

0.453 dia

1/4 r

2.939 r

0.95 dia

1.166 dia

4.50

6.332

1.424

0.587

0.275

0.25

0.083

9

Figure 1 SUBSCALE PROJECTILE DESIGN – OGIVE

Technical drawing of a mechanical part, likely a valve or fitting, showing a cross-section with various dimensions and a detail 'A'.

Material and Heat Treatment:
 Malt: Grade 300 maraging steel
 Heat treat: 900° - 925°F - 3 hrs - air cool

Dimensions and Features:

- Overall Length:** 5.146
- Internal Bore Diameter:** 1.23 dia
- Internal Step Diameter:** 1.03 dia
- Internal Step Diameter:** 1.09 dia
- Internal Step Diameter:** 1.03 dia
- Internal Step Diameter:** 1.3125 r
- Internal Step Diameter:** 1/8 r
- Internal Step Diameter:** 1/4 - 20 N.C.
- Internal Step Diameter:** 0.416 dia
- Internal Step Diameter:** 0.955 dia
- Internal Step Diameter:** 0.167
- Internal Step Diameter:** 0.275
- Internal Step Diameter:** 0.537
- Internal Step Diameter:** 0.750
- Internal Step Diameter:** 0.10
- Internal Step Diameter:** 0.25
- Internal Step Diameter:** 0.10
- Internal Step Diameter:** 2.20
- Internal Step Diameter:** 4.396
- Internal Step Diameter:** 0.750
- Internal Step Diameter:** 5.146

Detail 'A': A detail view of the top of the part, showing a 0.05 r fillet and a 0.269 dimension.

Figure 2 SUBSCALE PROJECTILE DESIGN – SST

Matl: Grade 300 maraging steel
Heat treat: 900° - 925°F - 3 hrs - air cool

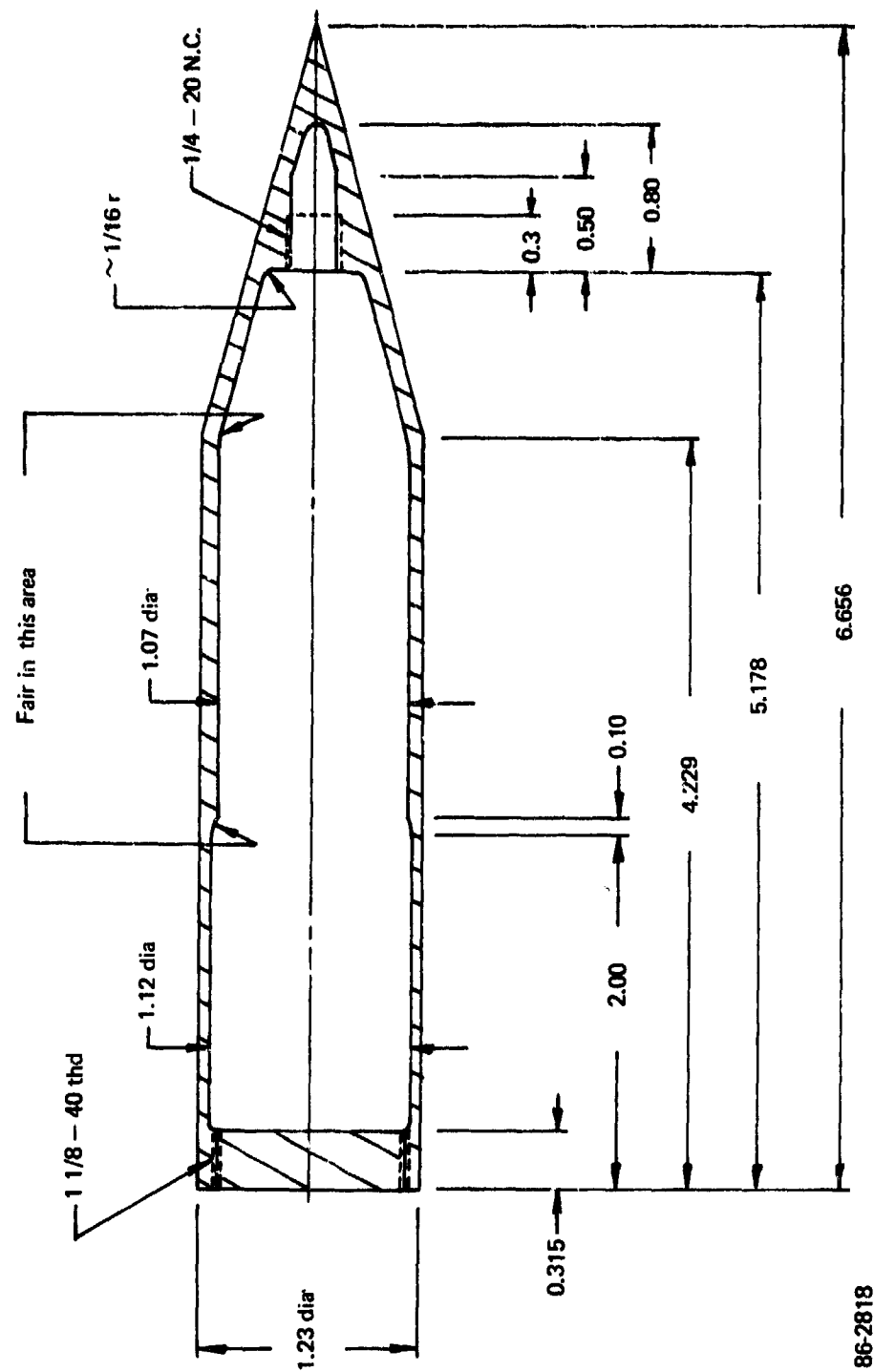


Figure 3 SUBSCALE PROJECTILE DESIGN - CONICAL

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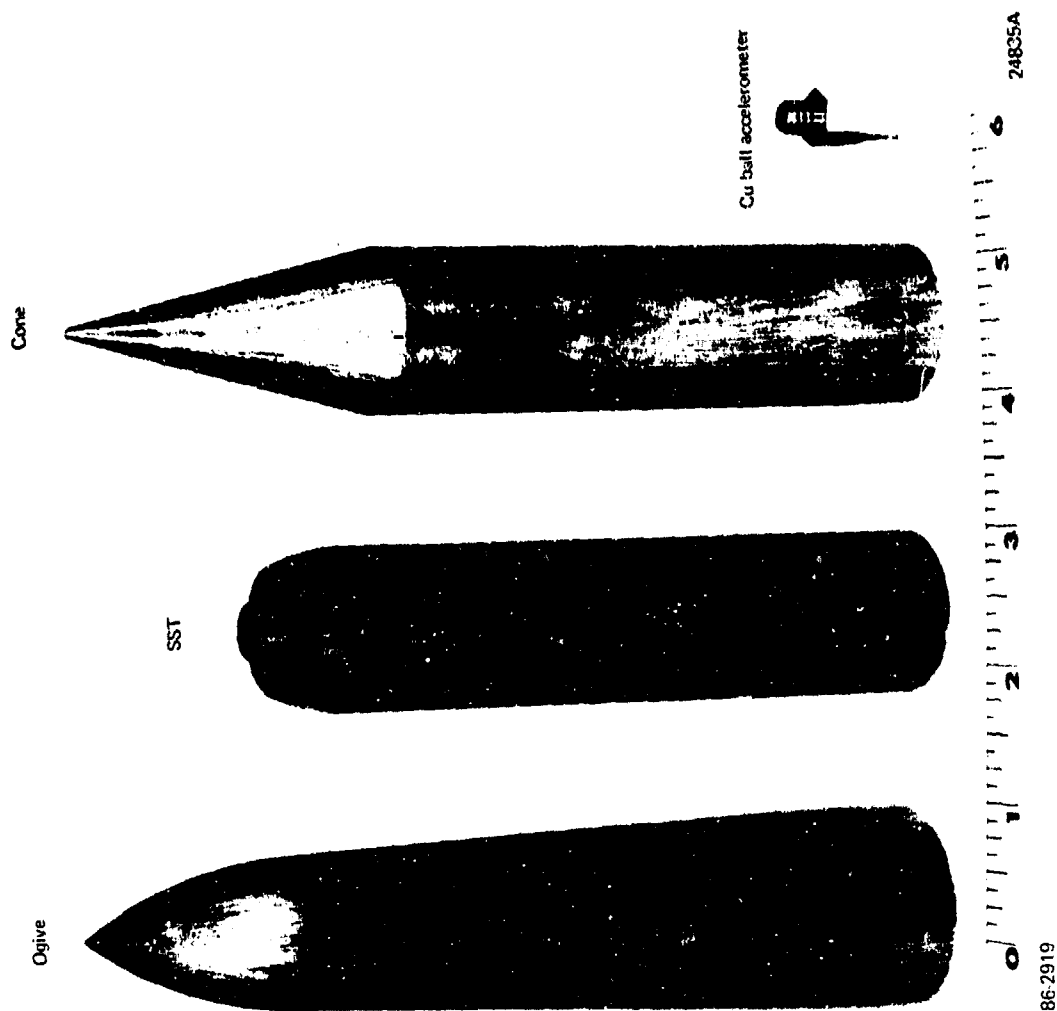
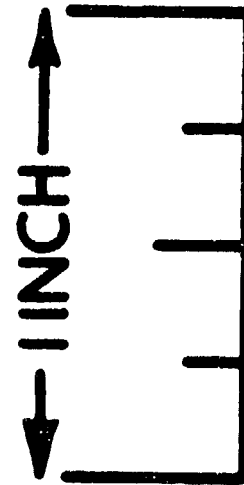
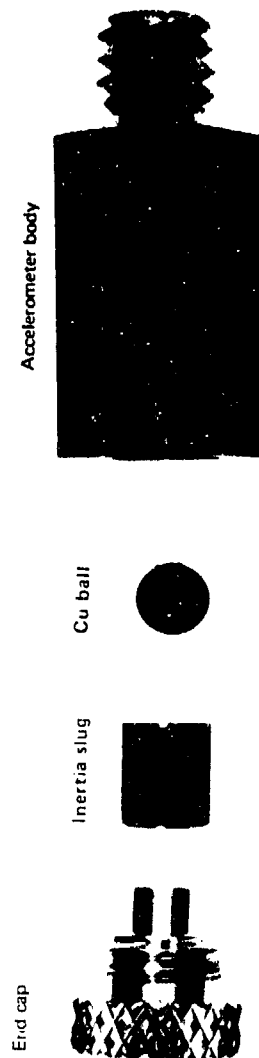


Figure 4 PROJECTILES AND ACCELEROMETER



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Figure 5 PASSIVE ACCELEROMETER PARTS

TABLE 1. COMPARISON OF TEST MODEL WEIGHTS AND C.G.'S WITH DESIRED VALUES

| | Ogive | | SST | | Cone | |
|----------------------------------|-----------------|--------------------|-----------------|--------------------|-----------------|--------------------|
| | Weight (gms) | C.G. % from tip | Weight (gms) | C.G. % from tip | Weight (gms) | C.G. % from tip |
| Actual test models | 243 | 55 | 274 | 45.6 | 377 | 57.9 |
| Theoretical 1/12 scale models | 247 | 57.28 | 276 | 45 | 358 | 57.95 |
| Ratio actual to theoretical % | 98.4 | 96.0 | 99.3 | 101.3 | 105.3 | 99.9 |

All tests were performed using a 2.9 inch diameter smooth bore launcher to accelerate the EP scale model to a nominal 1000 ft/s velocity. It was necessary to use sabots to support the projectiles to accommodate the difference between the EP diameters and the launcher diameter and to provide for angle of attack orientation where necessary. A sabot drawing is shown in Figure 6. The sabot and disc were fabricated from a 3-inch diameter polyethelene rod. The disc and base support configuration were varied to accommodate the desired angles of attack (i.e., 0, 2-1/2 or 5 degrees).

Figure 7 shows a typical sabot with an SST model installed. The saw cuts, 90 degrees apart, are typical for all sabots and are needed to accommodate separation of the EP model from the sabot after launch.

The target consisted of a three-foot square concrete slab backed by a box full of sand. The concrete had a nominal thickness of one inch which represented a 12-inch thick full scale concrete slab. The concrete was made with a sand aggregate. The concrete had a compressive strength of approximately 5000 lb/in² seven days after pouring using a high early strength cement.

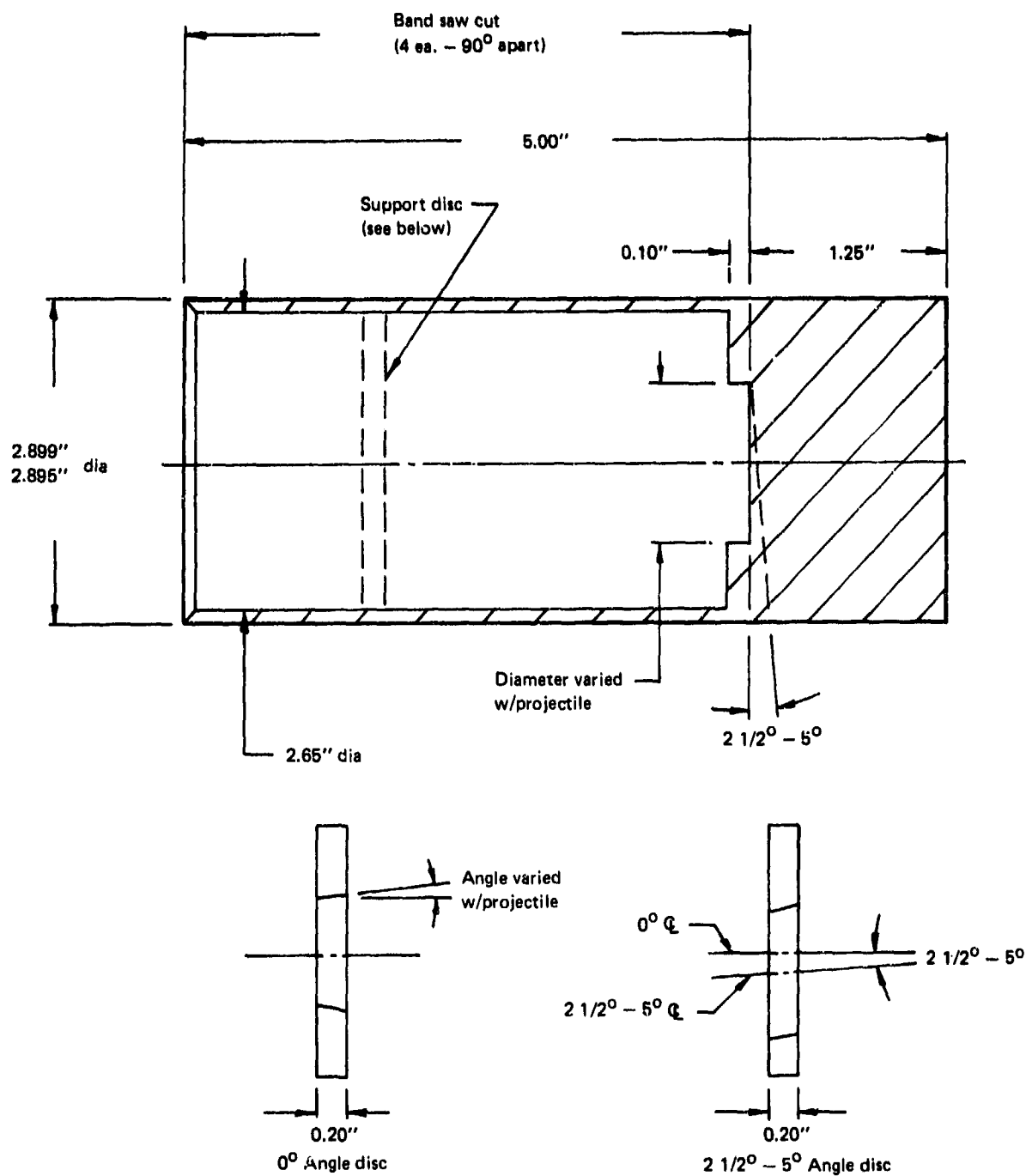


Figure 6 PROJECTILE SABOTS AND SUPPORT DISCS

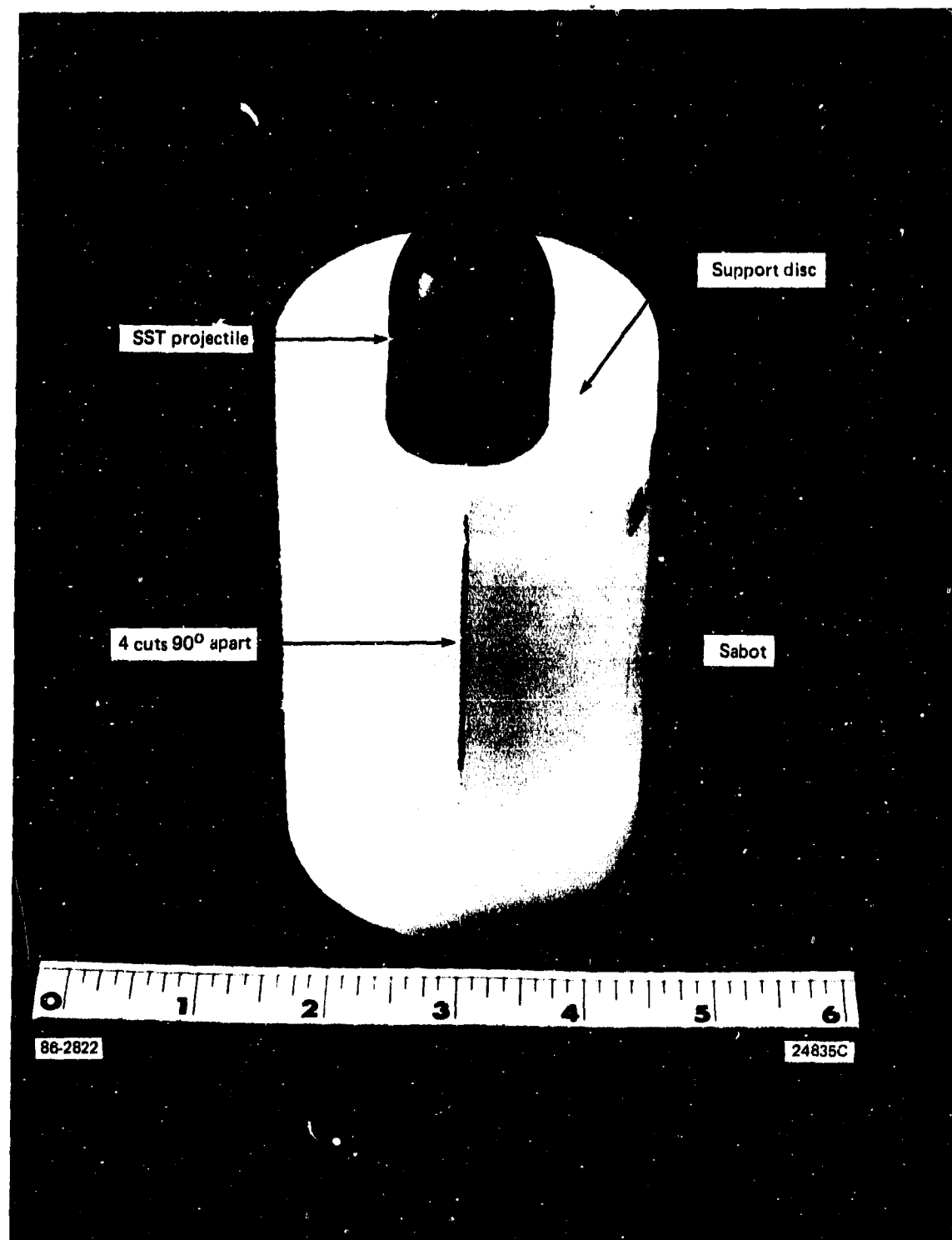


Figure 7 SST PROJECTILE IN SABOT

3.0 INSTRUMENTATION

The instrumentation used on all 24 tests consisted of high speed cameras to observe the projectile flight up to and including hitting the concrete slab and "make circuit" velocity grids to monitor velocity through the sand media. The passive accelerometers described under test hardware were used on each test to measure peak deceleration "g's". One mil of copper ball deformation equals approximately 22,600 g's up to 200,000 g's according to the Reference 1 data.

Two high speed Fastax cameras were located 90 degrees apart to observe the free flight of the EP model from a side view and from a top view. The cameras were operated at approximately 6000 frames per second and were used to measure EP model angle of attack and velocity. All sabots were oriented so that the angle of attack could be observed by the side view camera with EP nosetip up/tail down orientation. However, due to slight sabot roll during launch it was possible to observe some angle of attack orientation in the top camera.

The actual test angle of attack was of course the resultant of the angles observed in the top and side cameras. It was possible to measure angles to within ± 0.5 degree using the Fastax camera filming technique. Velocity at impact into the concrete was also determined by analyzing the Fastax film data. The velocity data is accurate to within 5 percent or approximately plus or minus 50 ft/s.

EP model trajectory and velocity after concrete target penetration was determined with make-circuit velocity grids on the face of the concrete target and in the sand media behind the target. Three make-circuit grids were located in the sand media for each test. Each make-circuit in the sand consisted of two layers of aluminum screen (1 x 1 ft square) insulated with posterboard material. The concrete target face make-circuit (T_0) consisted of two layers of aluminum foil insulated with a layer of 5 mil mylar. EP model trajectory was

determined from the location of the holes in the grids and velocity was determined from the time interval and distance between grids. All grid circuit closing times were recorded on magnetic tape and playback was onto an oscilloscope.

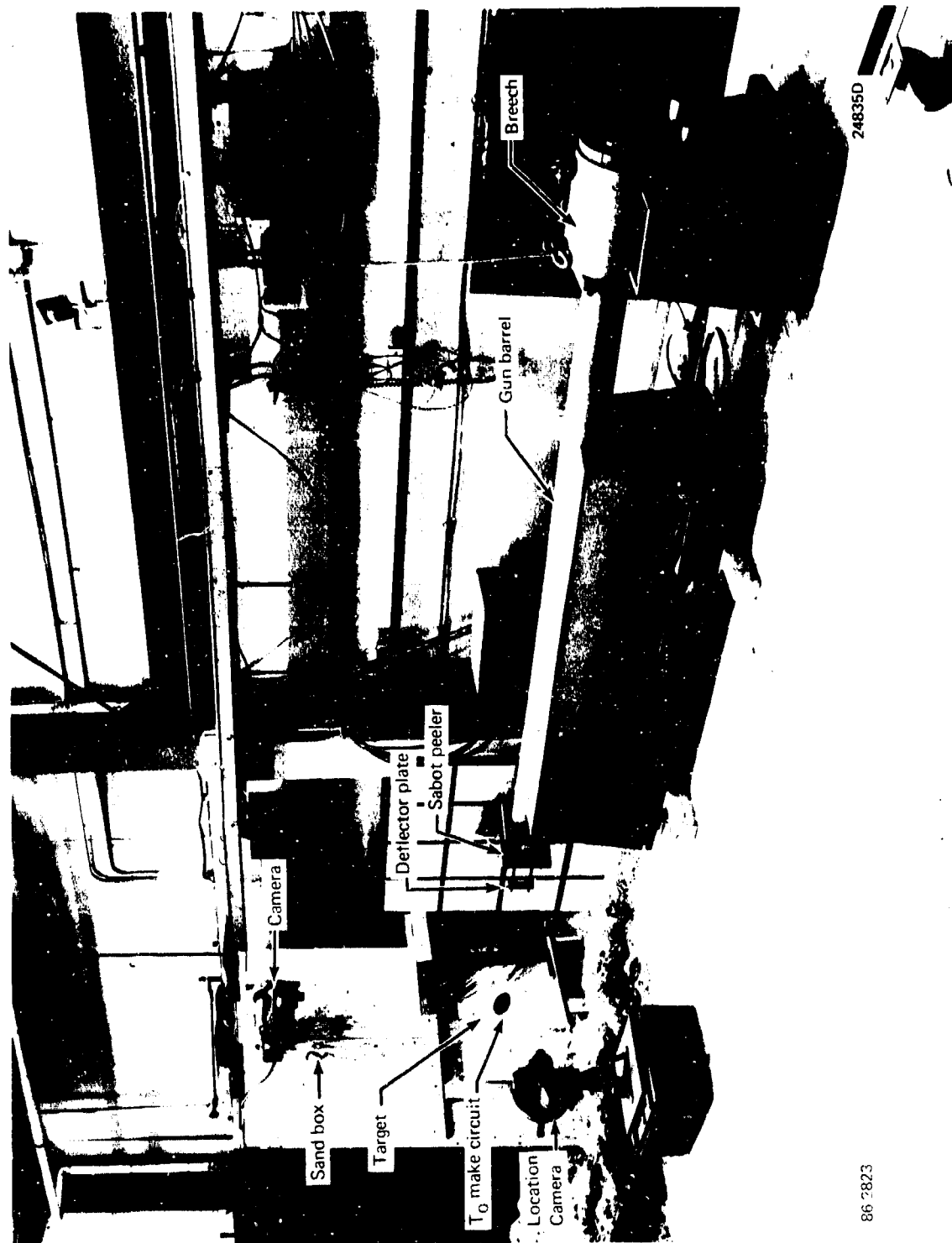
4.0 TEST PROCEDURE

The test setup used for each of the 24 tests is shown in Figure 8. Each test was performed in the same manner as described below.

Make-circuits were positioned in the sand box as shown in Figure 9. Sand was put into the box to the depth shown in Figure 9. A concrete target was located in front of the sand box positioned to the obliquity desired for the particular test. A make-circuit was placed on the front surface of the concrete target to act as a T_0 circuit. All make-circuits were connected to a magnetic tape recorder. Sabot peeler and deflection plates were located at the front of the EP model launcher (gun barrel). The hole in the peeler plate was smaller than the sabot, but, larger than the EP model. The peeler plate would retard the sabot while permitting the EP model to pass through. However, the sabot was still in line with the model such that it would impact the concrete target immediately after the EP model, making it impossible to evaluate model cratering effects. Therefore, a deflector plate was used to kick the peeled sabot to one side causing it to impact a steel plate located to the right of the concrete target.

The passive accelerometer was assembled after selecting and measuring a copper ball. The passive accelerometer was assembled into the EP model and the aft model cover screwed in place. The EP model was then placed in a sabot selected to produce the desired angle of attack. The sabot EP assembly was located so the aft end of the sabot was flush with the aft end of the gun barrel. The EP model tip was oriented upward such that the angle would be seen in the side view camera for all angle of attack tests. A powder charge of 10 grams FFG black powder and 90 grams 4895 powder, as determined by calibration tests, was placed in the breech along with a S-94 electric squib. The breech was assembled to the gun barrel.

The two fastax cameras were loaded with film and the firing circuit connected.



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Figure 8 S/S PENETRATION TEST SETUP

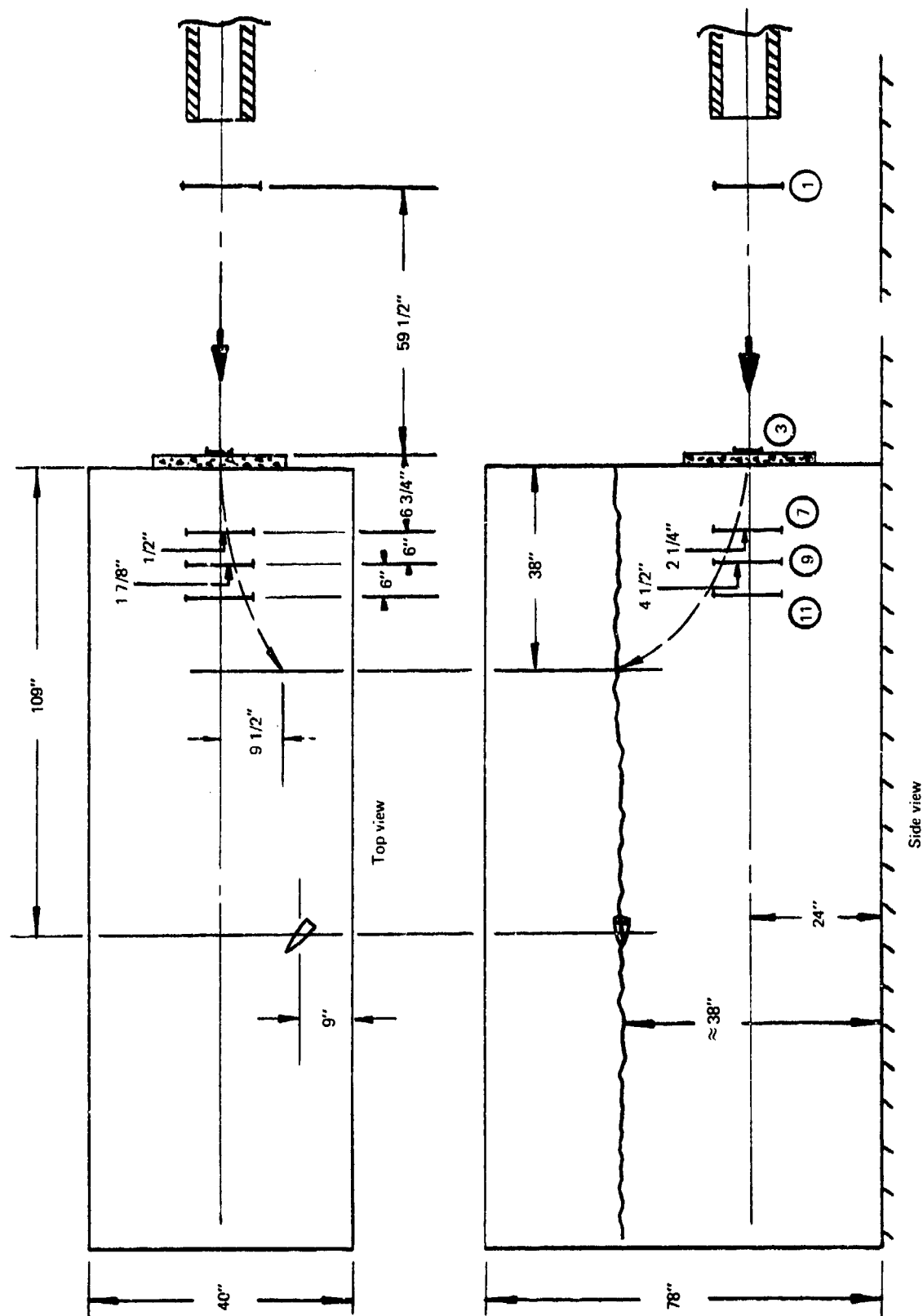


Figure 9 SUBSCALE OGIVE PENETRATION TEST 1, $\gamma = 0^\circ$, $\alpha = 5^\circ$

The cameras were started prior to firing the EP model so that the desired film speed of 6000 frames per second could be achieved. The tape recorders were started and the S-94 squib initiated causing the EP model to be launched. The gun to concrete target distance varied from prior test to test because of different target obliquities, but was nominally 52 inches.

At the conclusion of testing the EP model was recovered from the sand box with the final location noted. The location of holes in the velocity grids were used to provide trajectory data through the sand media. The tape recorder velocity grid data was played back through oscilloscopes to provide a measure of elapsed time from penetration of one grid to the next. Knowing the distance between grids permitted the calculation of EP model velocity through the sand media.

The Fastax film data was recovered, developed and analyzed to provide EP model velocity and angle of attack data. The concrete target crater was measured in detail for each test.

5.0 TEST RESULTS AND DISCUSSION

The test results are summarized in Table 2. Details of the EP model trajectory in the sand media and the target crater characteristics are presented for each test in Figures 9 through 52.

Table 2 shows the order in which the tests were performed, the EP model used for each test, the angle at which the concrete target media was set for each test, and the desired angle of attack. The measured angles of attack as observed from analysis of the side and top located Fastax camera films are listed. The resultant angle of attack was calculated from the side and top values. The resultant angle of attack is the angle of attack of the EP model when it hit the concrete target. The EP models were located nose up in the launcher so that angle of attack could be observed in the side camera. It is obvious from the data that the sabots rotated somewhat during transit of the launcher. The actual (resultant) angle of attack compares quite well with the desired angle of attack for all but Tests 19 and 21. The average difference between the desired and actual angle of attack was approximately one degree for the 22 tests, excluding Tests 19 and 21. The maximum deviation range for the 22 tests was -2.5 degrees and +3.0 degrees. If Tests 19 and 21 are included the average deviation per test increases to 1.4 degrees and the maximum difference increases to 6 degrees. The results of Tests 19 through 21 seem to be more representative of five degree angle of attack data than zero degree data and is not completely understood. It seems evident that sabot machining and assembly is very critical to achieving the desired angle of attack and must be carefully controlled for each test.

The impact velocity data shown in Table 2 was obtained from analysis of the film data. The average velocity for the 24 tests was 977 ft/s with maximum deviations of +160 ft/s and -122 ft/s. The average velocity is quite close to the desired velocity of 1000 ft/s. The average velocities achieved for the ogive, SST and cone tip models

TABLE 2. SUMMARY OF EP MODEL PENETRATION TEST DATA

| Test no. | EP model type | Target angle of attack (deg) | Desired angle of attack (deg) | Resultant angle of attack (deg) | Side view angle of attack (deg) | Top view angle of attack (deg) | V ₁ impact velocity (ft/s) | V ₂ velocity (ft/s) | V ₃ velocity (ft/s) | V ₄ velocity (ft/s) | Cu ball(4) deformation (mil) | Trajectory path | Target crater data |
|----------|---------------|------------------------------|-------------------------------|---------------------------------|---------------------------------|--------------------------------|---------------------------------------|--------------------------------|--------------------------------|--------------------------------|------------------------------|-----------------|--------------------|
| 1 | Ogive | 0 | 5.0 | 7.6 | 6.5 | 4.0 | 933 | 672 | 462 | (2) | 4.7 | See Fig. 9 | (5) |
| 2A | Ogive | 0 | 0.0 | 1.3 | 1.3 | (1) | 926 | 707 | 520 | 438 | 0.9 | See Fig. 10 | See Fig. 11 |
| 3 | SST | 0 | 0.0 | 1.4 | 1.0 | 1.0 | 913 | 636 | 341 | 123 | 21.5 | See Fig. 12 | See Fig. 13 |
| 4 | SST | 0 | 5.0 | 5.9 | 5.0 | 0.0 | 900 | 617 | 301 | 143 | 16.3 | See Fig. 14 | See Fig. 15 |
| 5 | Cone | 0 | 0.0 | 0.0 | (1) | 0.0 | 990 | 725 | 430 | 248 | 1.3 | See Fig. 16 | See Fig. 17 |
| 6 | Cone | 0 | 5.0 | 7.7 | 6.3 | 4.5 | 926 | 650 | (2) | (2) | 1.8 | See Fig. 18 | See Fig. 19 |
| 7 | Ogive | 45 | 5.0 | 5.9 | 2.5 | 5.3 | 878 | 542 | (2) | (2) | 2.7 | See Fig. 20 | See Fig. 21 |
| 8 | Ogive | 45 | 0.0 | 9.0 | 0.0 | 0.0 | 898 | 629 | (2) | (2) | 4.6 | See Fig. 22 | See Fig. 23 |
| 9 | SST | 45 | 5.0 | 3.8 | 3.8 | 0.0 | 911 | 357 | 57 | (2) | 7.6 | See Fig. 24 | See Fig. 25 |
| 10 | SST | 45 | 0.0 | 0.5 | 0.0 | 0.5 | 947 | 375 | 70 | (2) | (3) | See Fig. 26 | See Fig. 27 |
| 11 | Cone | 45 | 5.0 | 2.5 | 1.5 | 2.0 | 935 | 653 | (2) | (2) | 5.8 | See Fig. 28 | (5) |
| 12 | Cone | 45 | 0.0 | 1.3 | 1.0 | 0.8 | 900 | 518 | (2) | (2) | 5.1 | See Fig. 29 | See Fig. 30 |
| 13 | Ogive | 22.5 | 5.0 | 4.5 | 4.5 | 0.0 | 1033 | 714 | 286 | (2) | 4.1 | See Fig. 31 | See Fig. 32 |
| 14 | Cone | 22.5 | 5.0 | 5.0 | 5.0 | 0.0 | 1114 | (2) | (2) | (2) | 4.9 | See Fig. 33 | See Fig. 34 |
| 15 | SST | 22.5 | 5.0 | 8.0 | 0.0 | 8.0 | 978 | (2) | (2) | (2) | 8.1 | See Fig. 35 | See Fig. 36 |
| 16 | Ogive | 22.5 | 2.5 | 2.1 | 0.5 | 2.0 | 921 | 773 | 286 | 176 | 2.7 | See Fig. 37 | See Fig. 38 |
| 17 | SST | 22.5 | 2.5 | 2.3 | 2.3 | 0.0 | 1065 | (3) | (2) | (2) | 24.5 | See Fig. 39 | See Fig. 40 |
| 18 | Cone | 22.5 | 2.5 | 1.8 | 1.8 | 0.0 | 1060 | (2) | (2) | (2) | 4.6 | See Fig. 41 | See Fig. 42 |
| 19 | Ogive | 22.5 | 0.0 | 4.5 | 0.0 | 4.5 | 1160 | 677 | 375 | (2) | 3.8 | See Fig. 43 | See Fig. 44 |
| 20A | SST | 22.5 | 0.0 | 2.5 | 2.0 | 1.5 | 960 | 333 | 84 | (2) | 12.8 | See Fig. 45 | See Fig. 46 |
| 21 | Cone | 22.5 | 0.0 | 6.0 | 1.0 | 6.0 | 955 | (2) | (2) | (2) | 2.9 | See Fig. 47 | See Fig. 48 |
| 22 | Ogive | 45 | 2.5 | 2.3 | 2.3 | 0.0 | 1052 | 779 | 510 | 361 | 4.5 | See Fig. 49 | See Fig. 50 |
| 23 | SST | 45 | 2.5 | 2.0 | 0.0 | 2.0 | 1124 | 523 | 89 | (2) | 11.9 | See Fig. 51 | (5) |
| 24 | Cone | 45 | 2.5 | 2.0 | 2.0 | 0.0 | 970 | (2) | (2) | (2) | 4.3 | See Fig. 52 | (5) |

- Notes:
- (1) Camera malfunctioned, no data.
 - (2) Projectile missed make-circuit grid due to trajectory through sand media.
 - (3) No data.
 - (4) Cu ball calibration - one mil deformation = 22,600 g's
Linear up to 200,000 g's.
 - (5) No crater data, concrete target broke up on removal from setup.

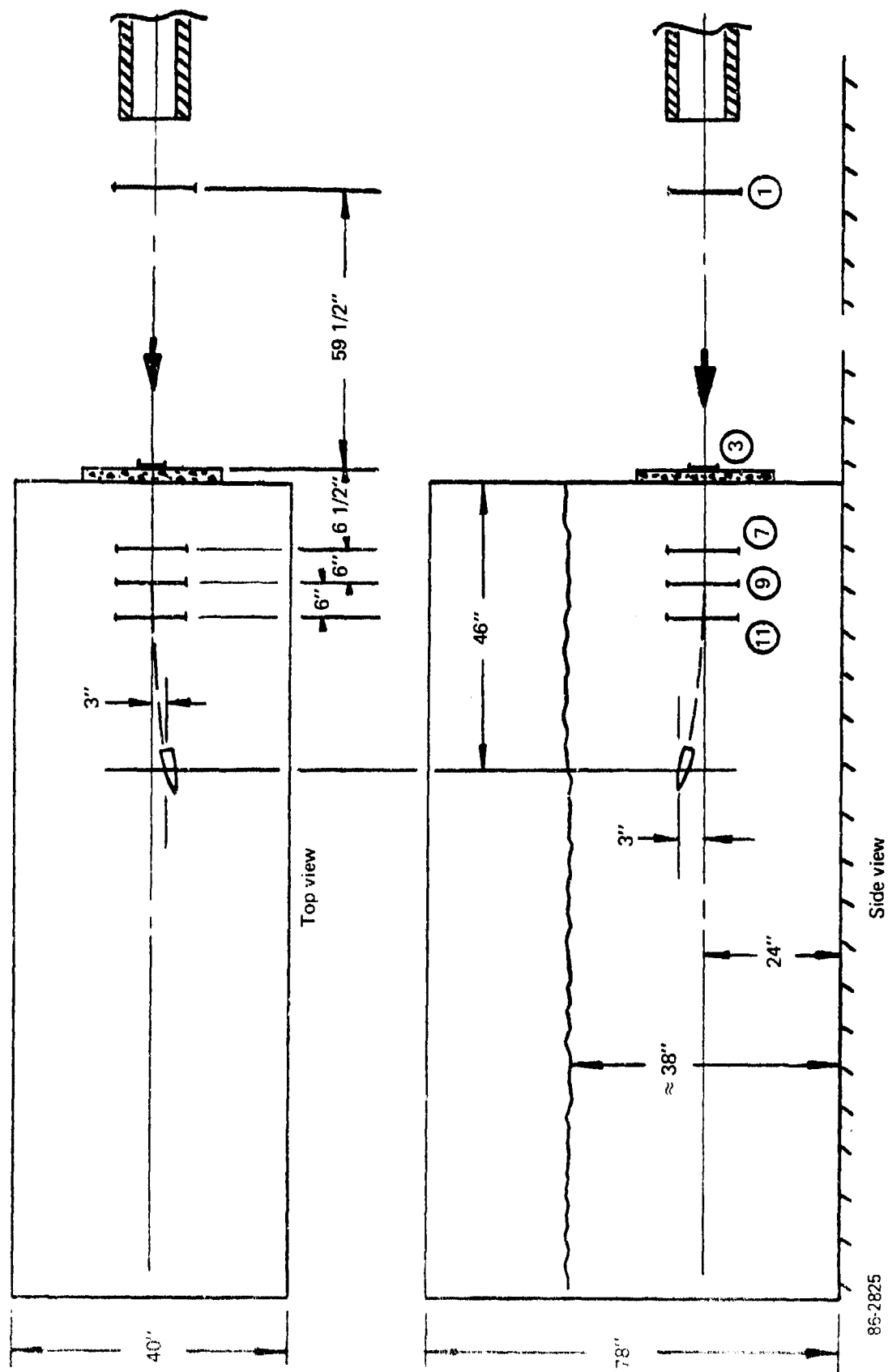
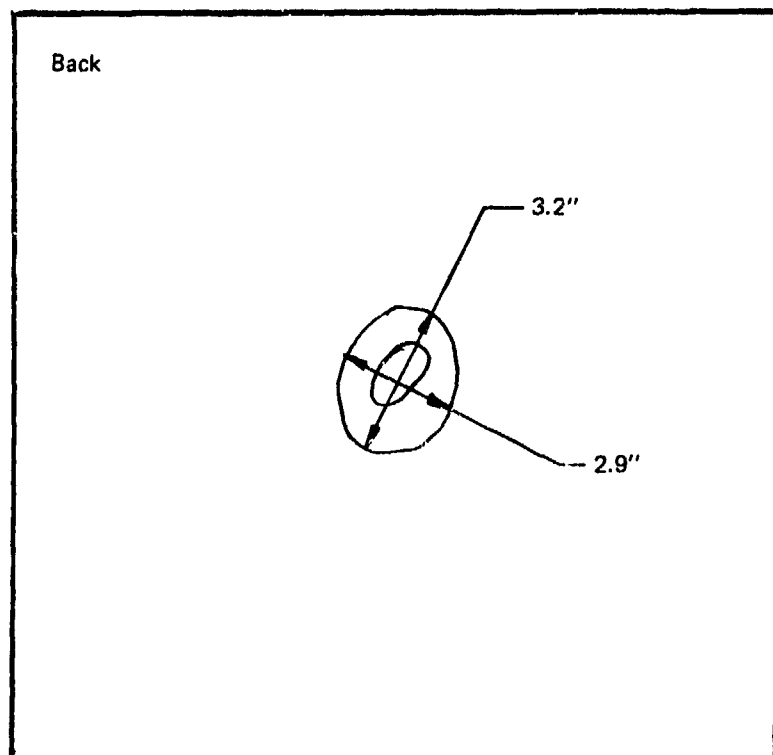
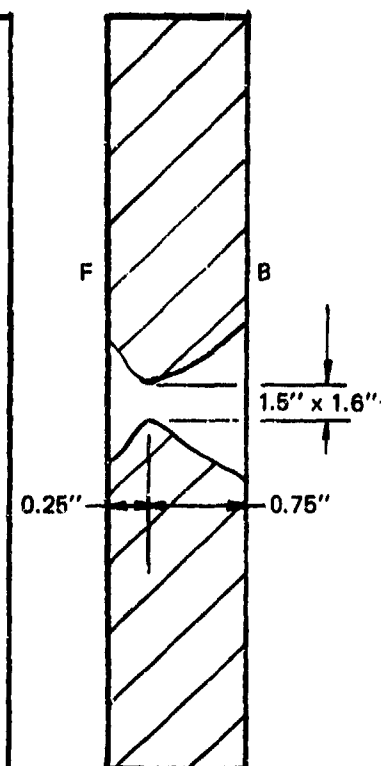
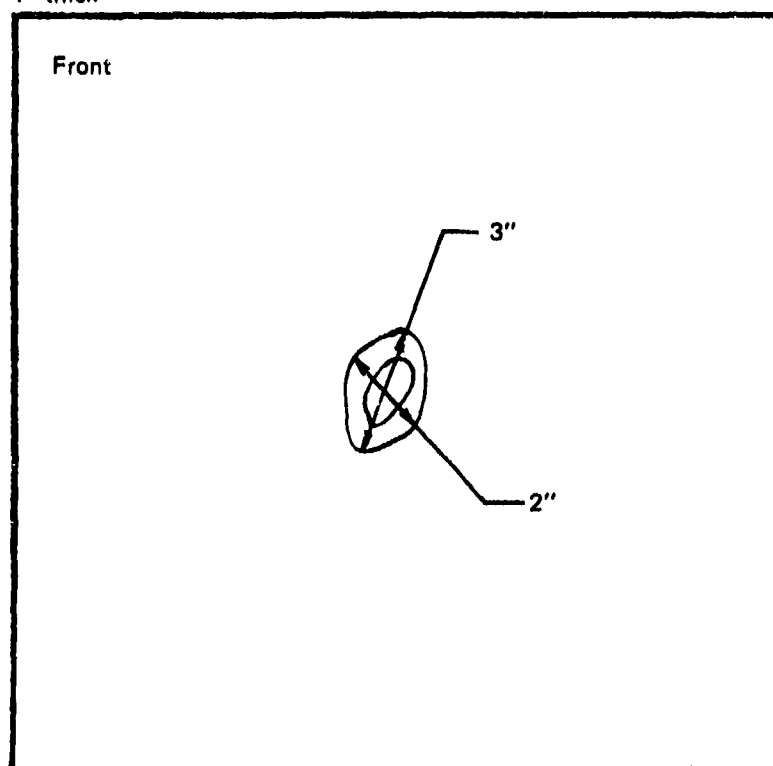


Figure 10 SUBSCALE OGIVE PENETRATION TEST 2A, $\gamma = 0^\circ$, $\alpha = 0^\circ$

86-2825

Target no. 2A
1" thick



$$\gamma = 0^\circ$$

$$\alpha = 0^\circ$$

86-2826

Figure 11 TEST 2A TARGET DATA — OGIVE PROJECTILE

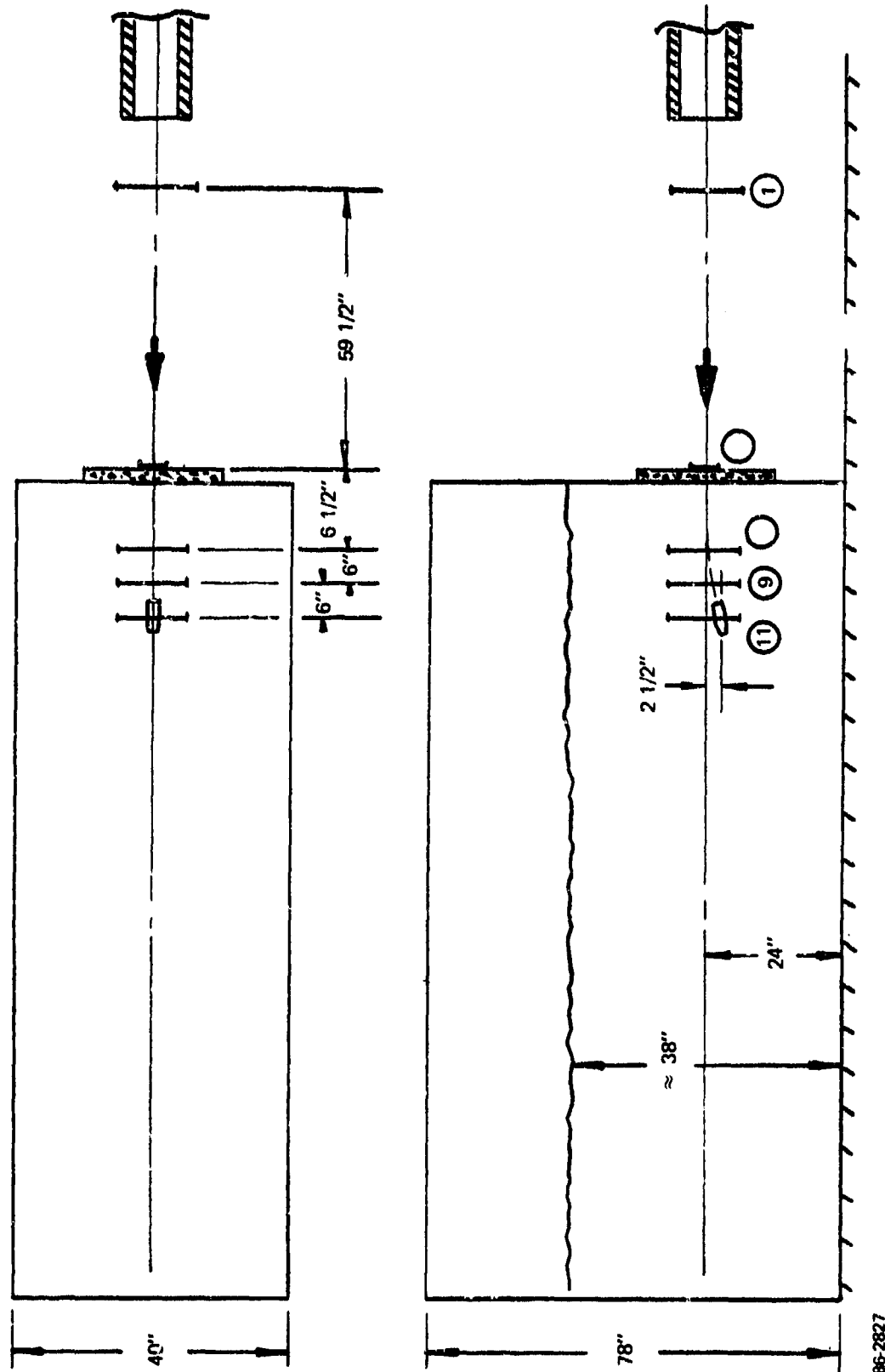
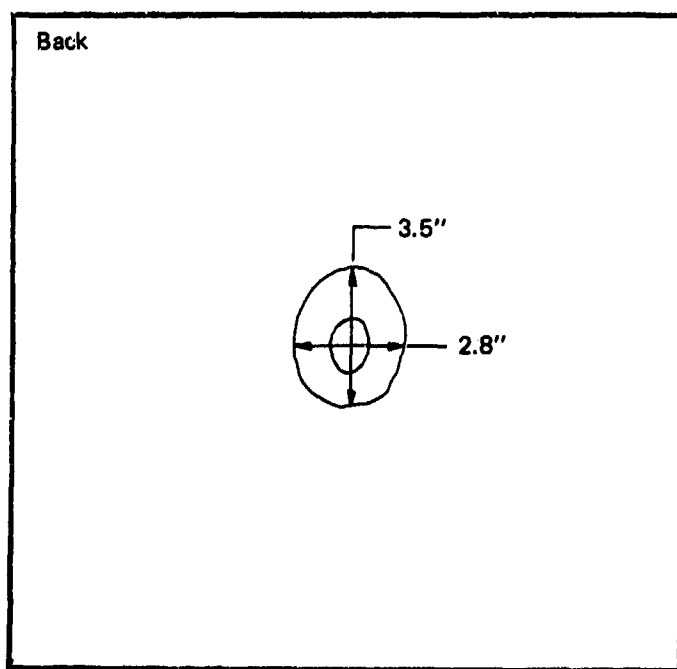
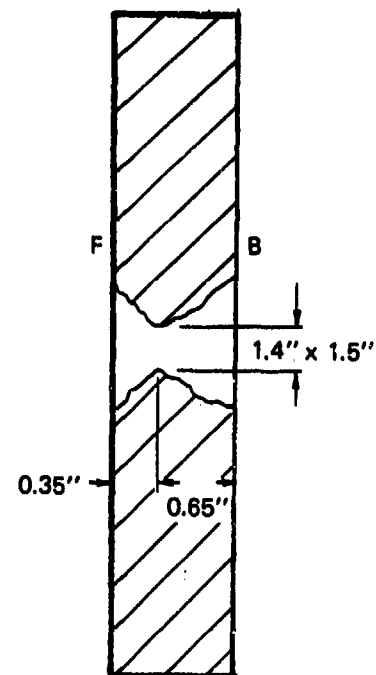
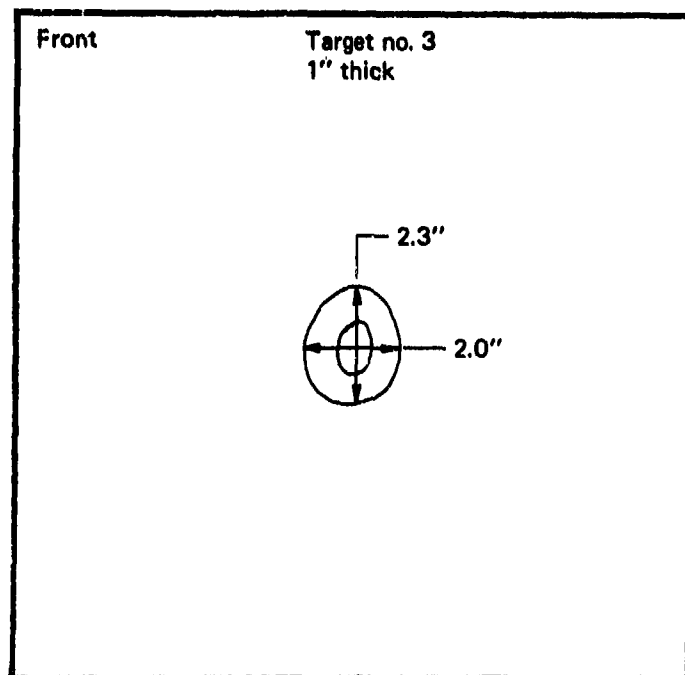


Figure 12 SUBSCALE SST PENETRATION TEST 3, $\gamma = 0^\circ$, $\alpha = 0^\circ$

86-2827



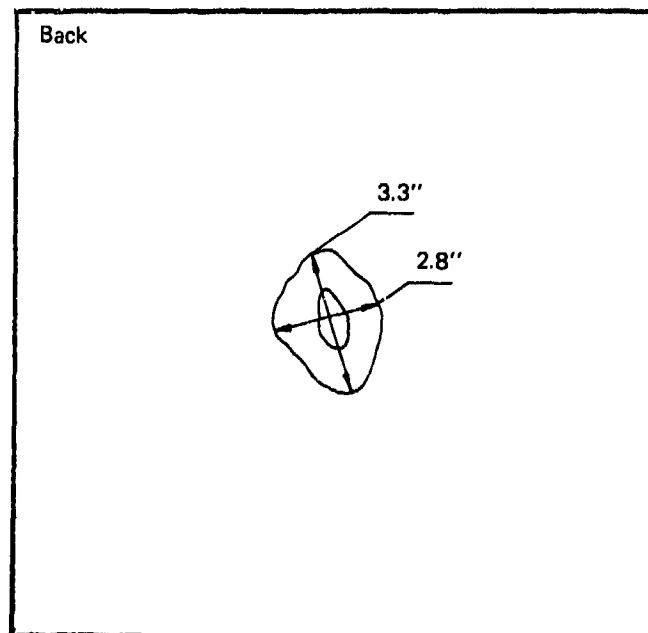
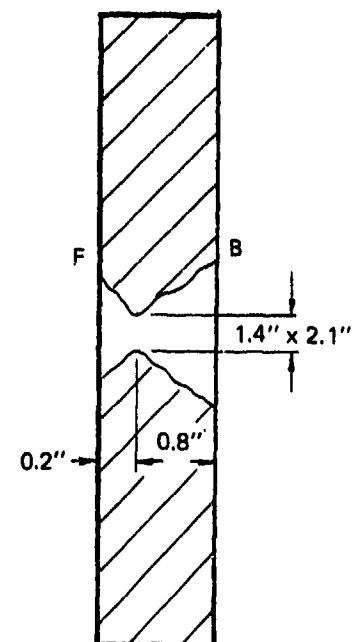
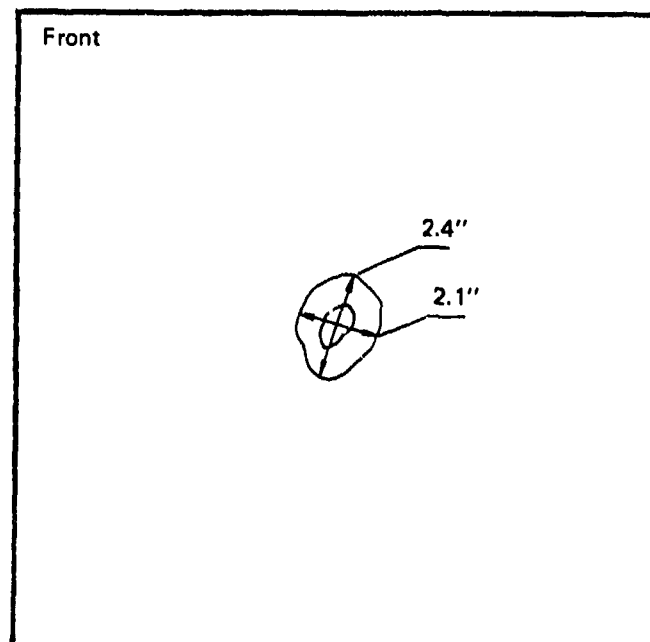
$$\gamma = 0^\circ$$

$$\alpha = 0^\circ$$

98-2828

Figure 13 TEST 3 TARGET DATA – SST PROJECTILE

Target no. 4
1" thick - (1 3/32)



$\gamma = 0^\circ$
 $\alpha = 0^\circ$

86-2830

Figure 15 TEST 4 TARGET DATA - SST PROJECTILE

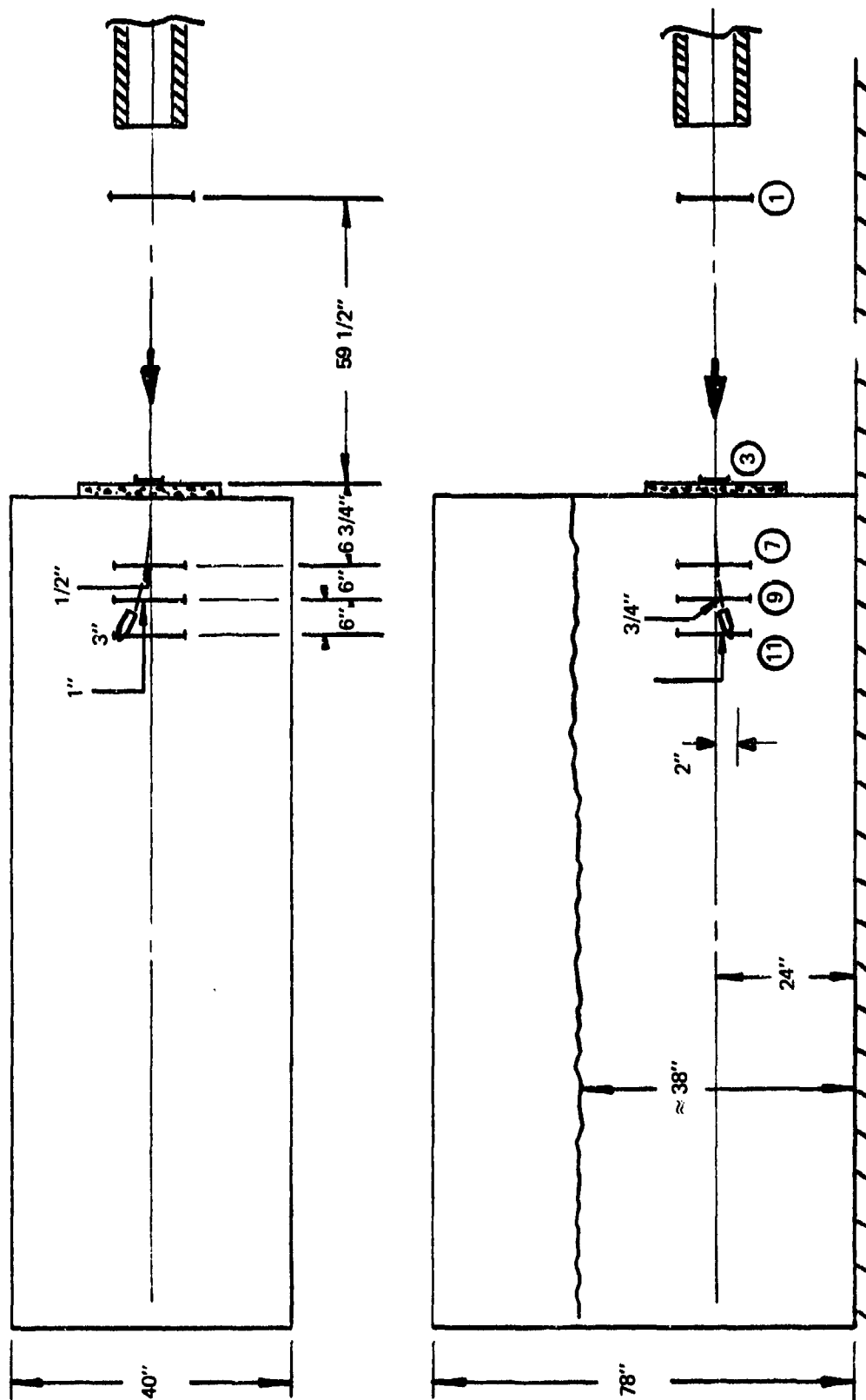
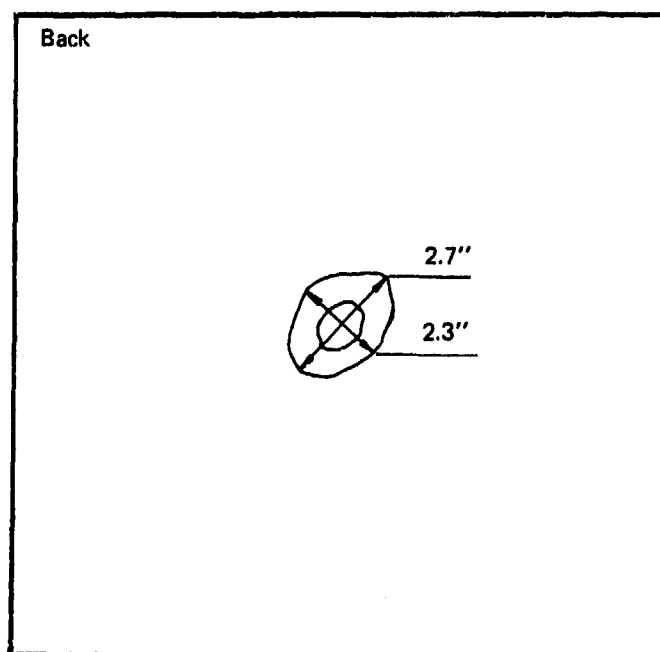
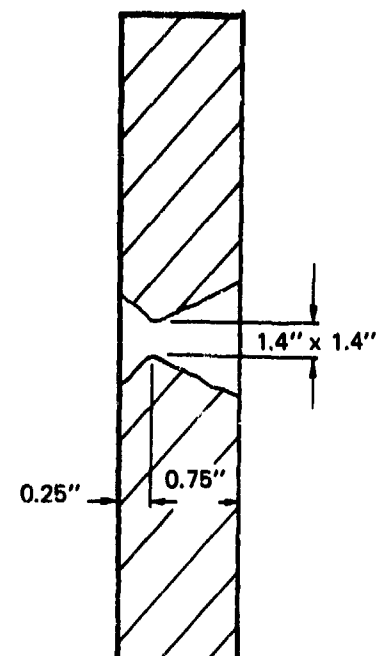
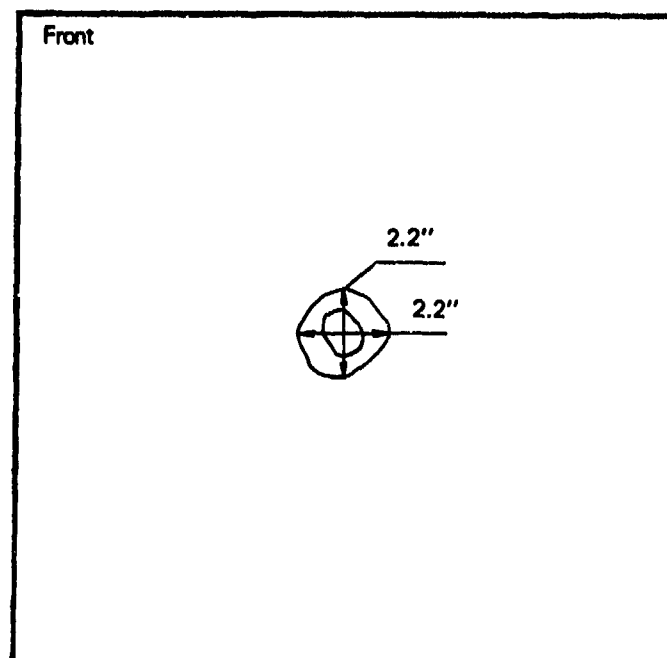


Figure 16 SUBSCALE CONE PENETRATION TEST 5, $\gamma = 0^\circ$, $\alpha = 0^\circ$

Target no. 5
1" thick



$$\gamma = 0^\circ$$

$$\alpha = 0^\circ$$

86-2832

Figure 17 TEST 5 TARGET DATA - CONE PROJECTILE

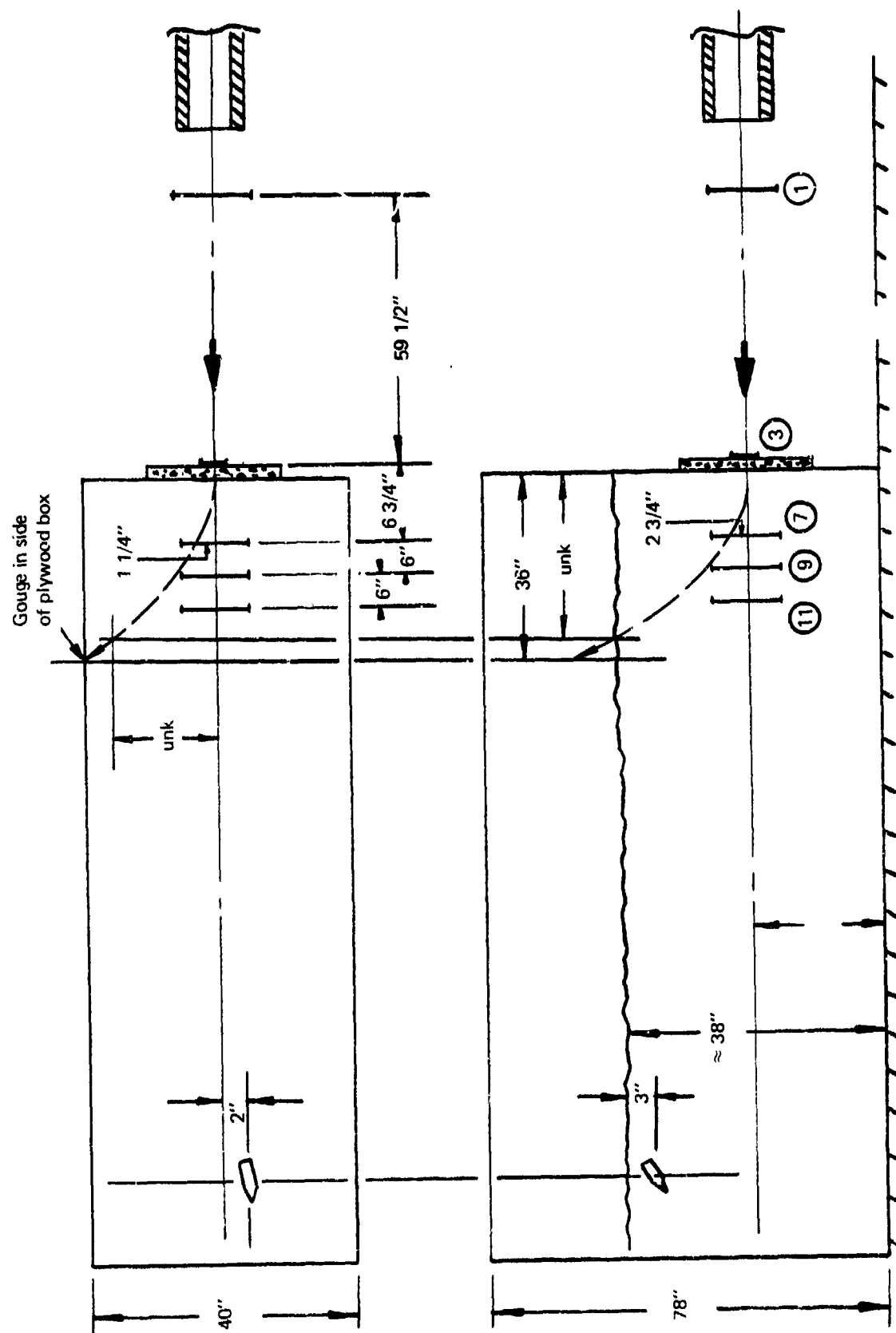
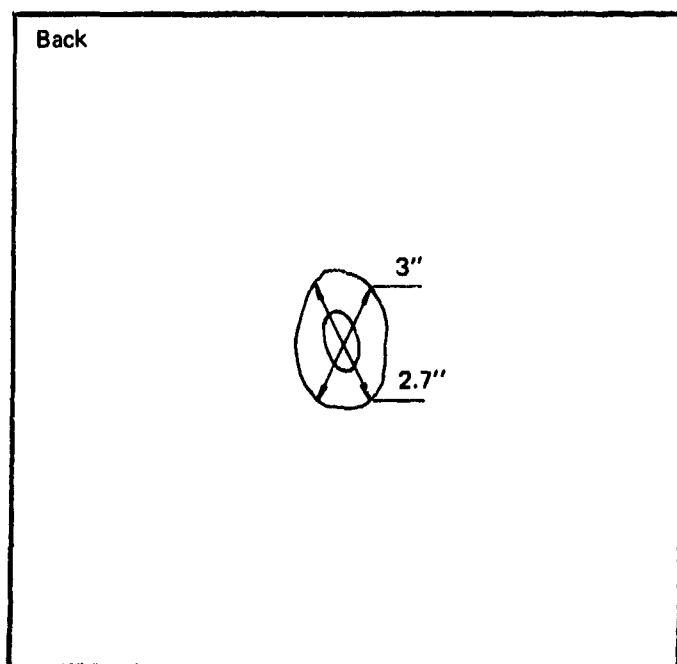
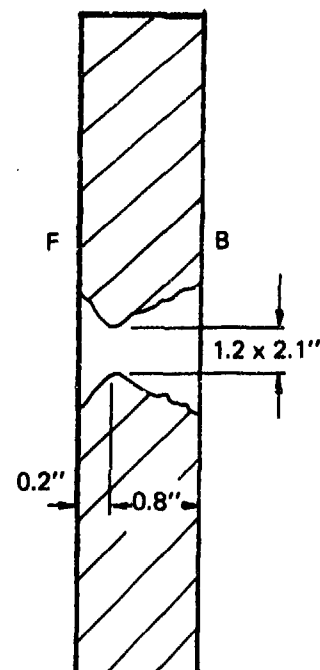
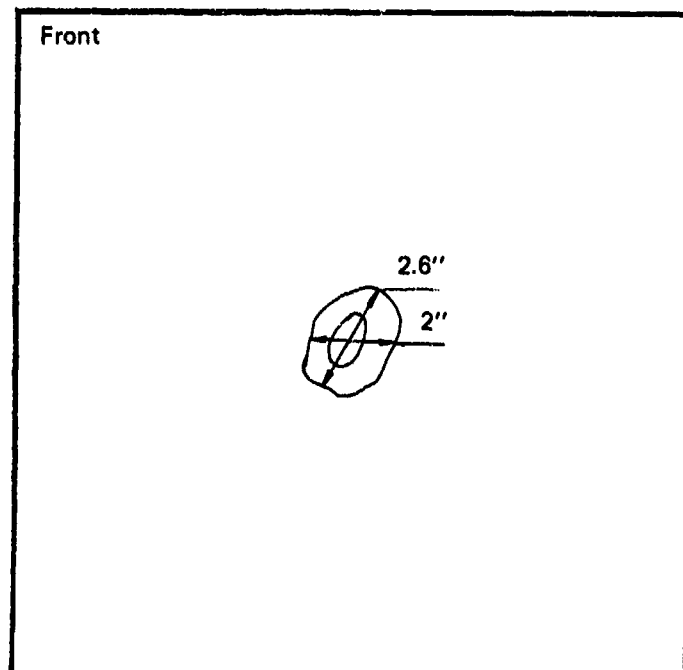


Figure 18 SUBSCALE CONE PENETRATION TEST 6, $\gamma = 0^\circ$, $\alpha = 5^\circ$

86-2833

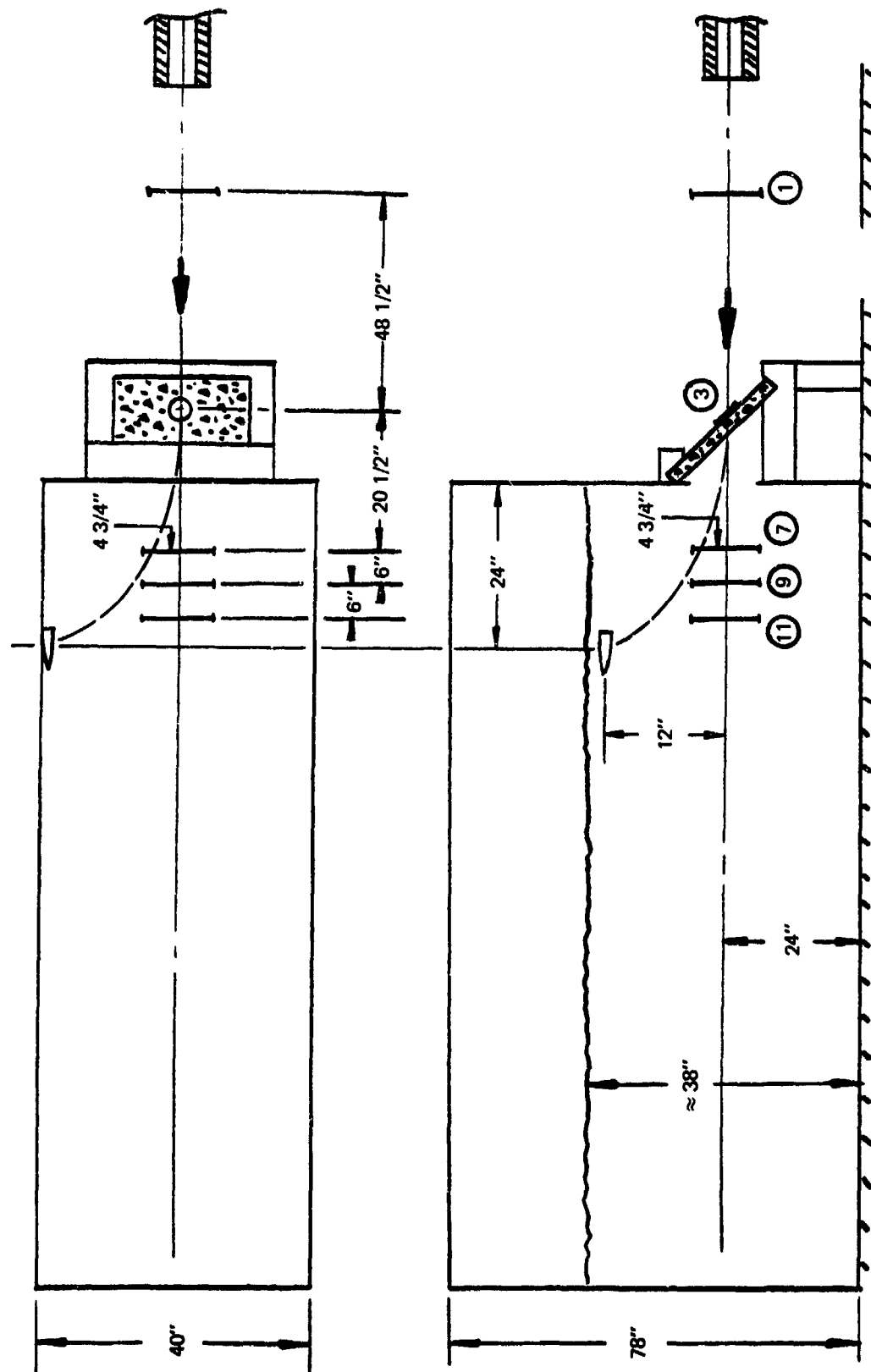
Target no. 6
1" thick



$\gamma = 0^\circ$
 $\alpha = 5^\circ$

86-2834

Figure 19 TEST 6 TARGET DATA – CONE PROJECTILE

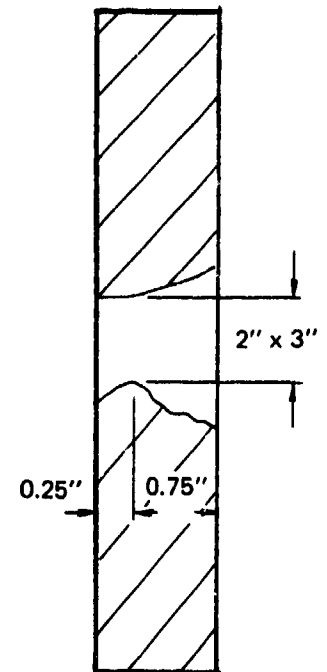
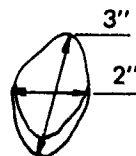


86-2835

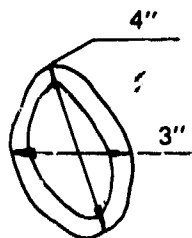
Figure 20 SUBSCALE OGIVE PENETRATION TEST 7, $\gamma = 45^\circ$, $\alpha = 5^\circ$

Target no. 7
1" thick

Front



Back



$\gamma = 0^\circ$
 $\alpha = 5^\circ$

86-2836

Figure 21 TEST 7 TARGET DATA – OGIVE PROJECTILE

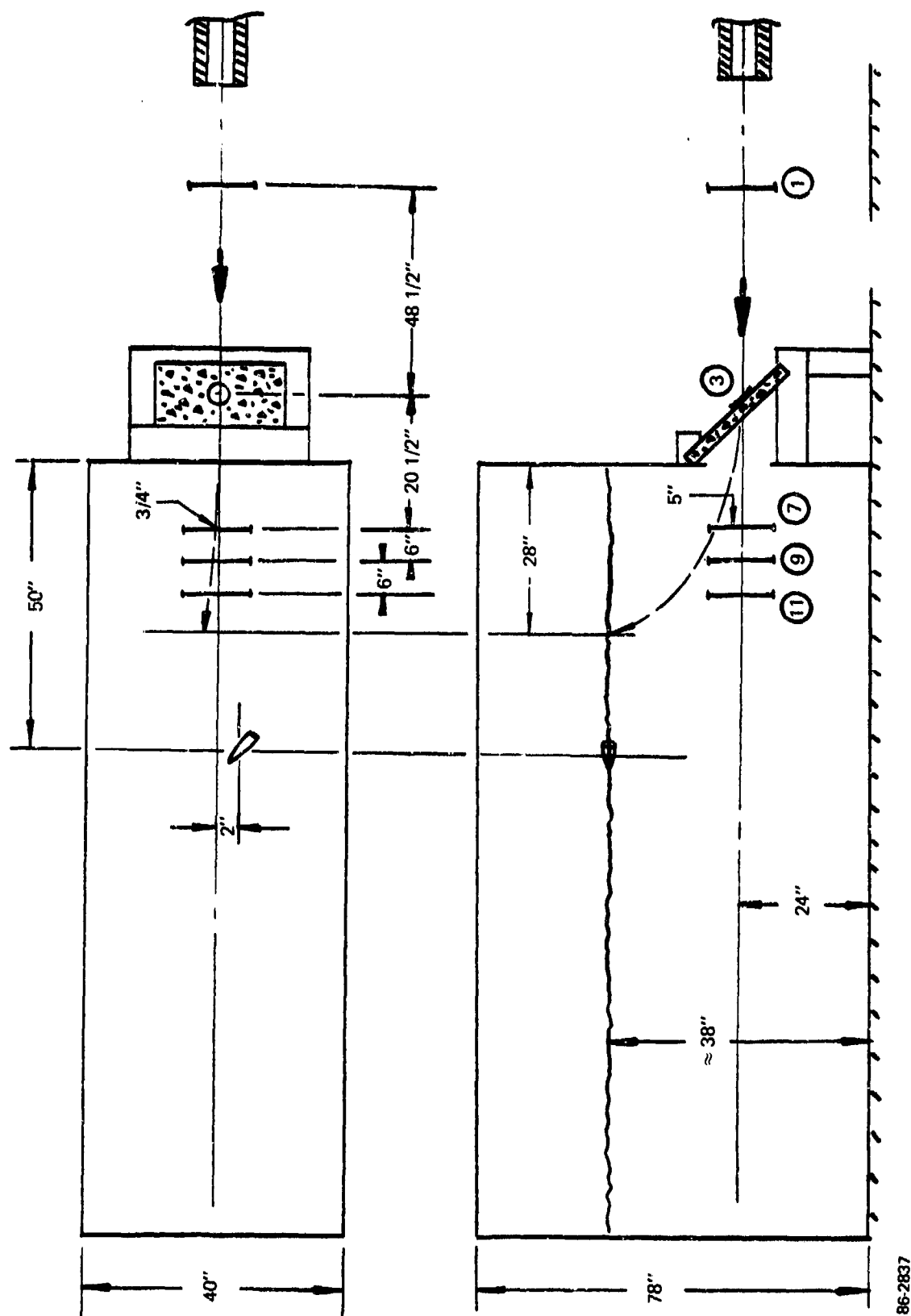
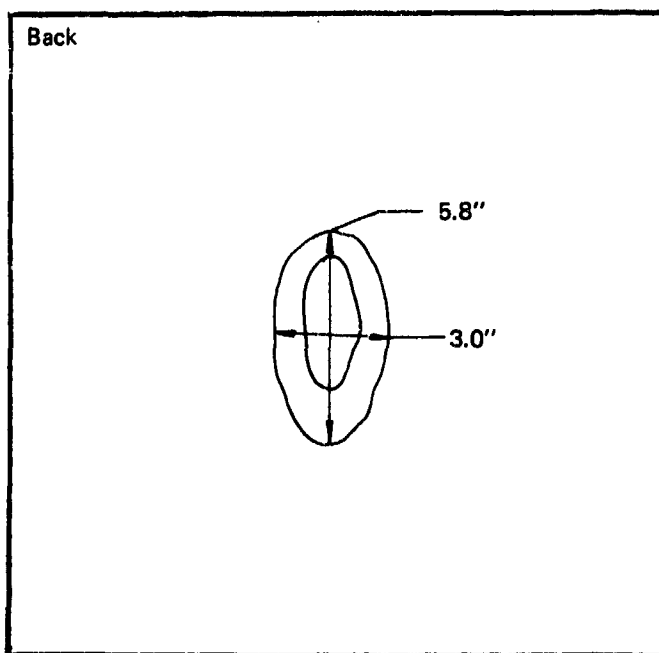
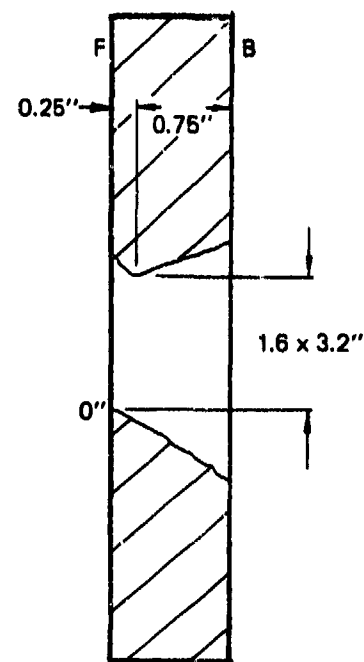
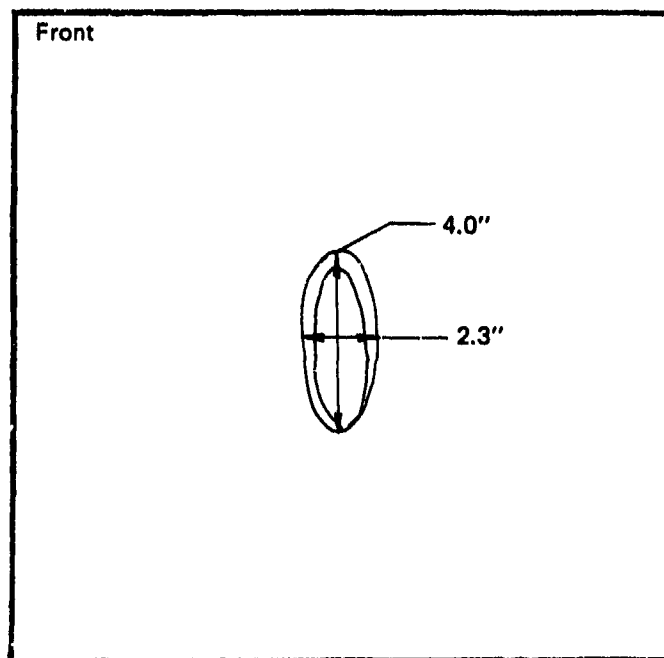


Figure 22 SUBSCALE OGIVE PENETRATION TEST 8, $\gamma = 45^\circ$, $\alpha = 0^\circ$

Target no. 8
1" thick



$$\gamma = 45^\circ$$

$$\alpha = 0^\circ$$

86-2838

Figure 23 TEST 8 TARGET DATA – OGIVE PROJECTILE

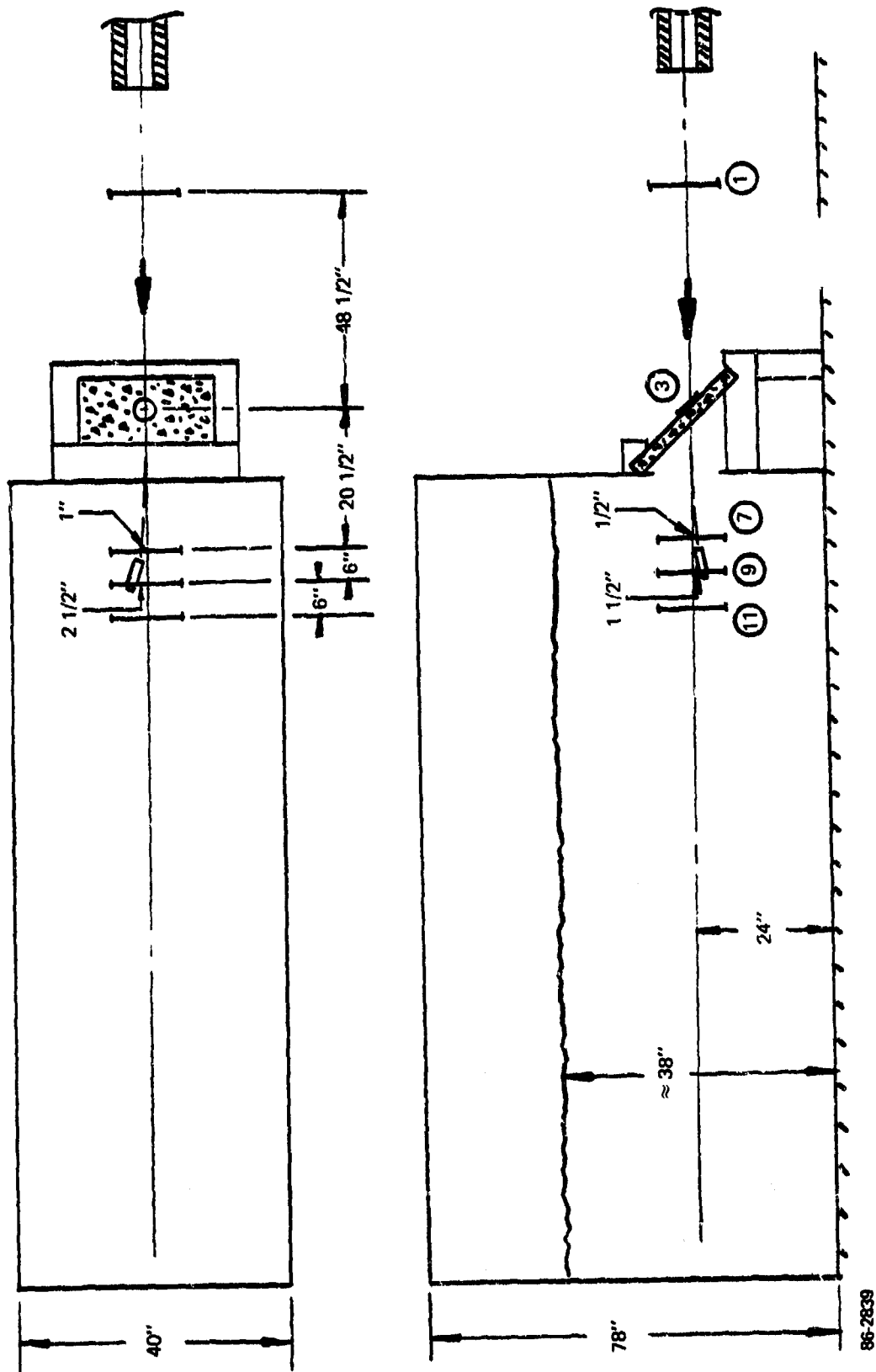
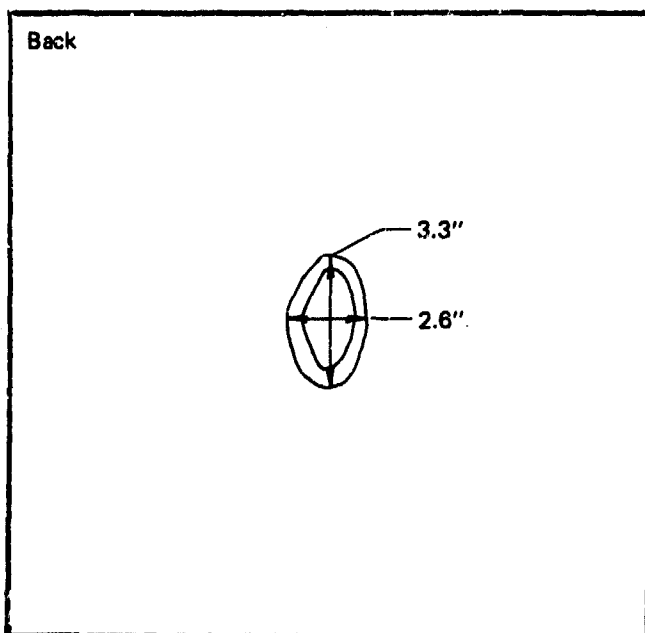
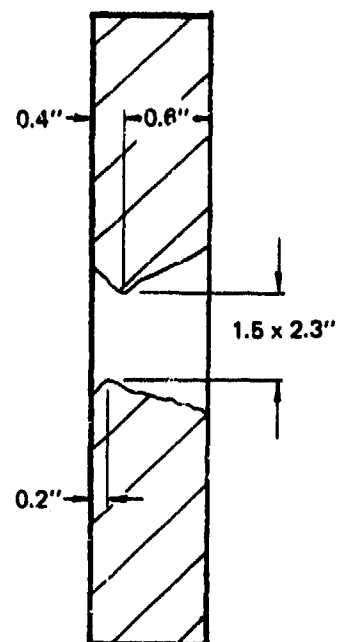
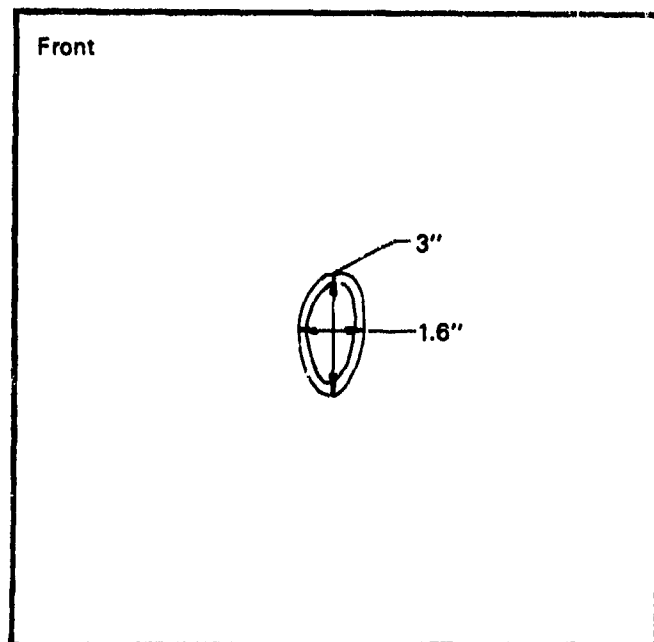


Figure 24 SUBSCALE SST PENETRATION TEST 9, $\gamma = 45^\circ$, $\alpha = 5^\circ$

Target no. 9
1" thick



$\gamma = 45^\circ$
 $\alpha = 5^\circ$

86-2840

Figure 25 TEST 9 TARGET DATA – SST PROJECTILE

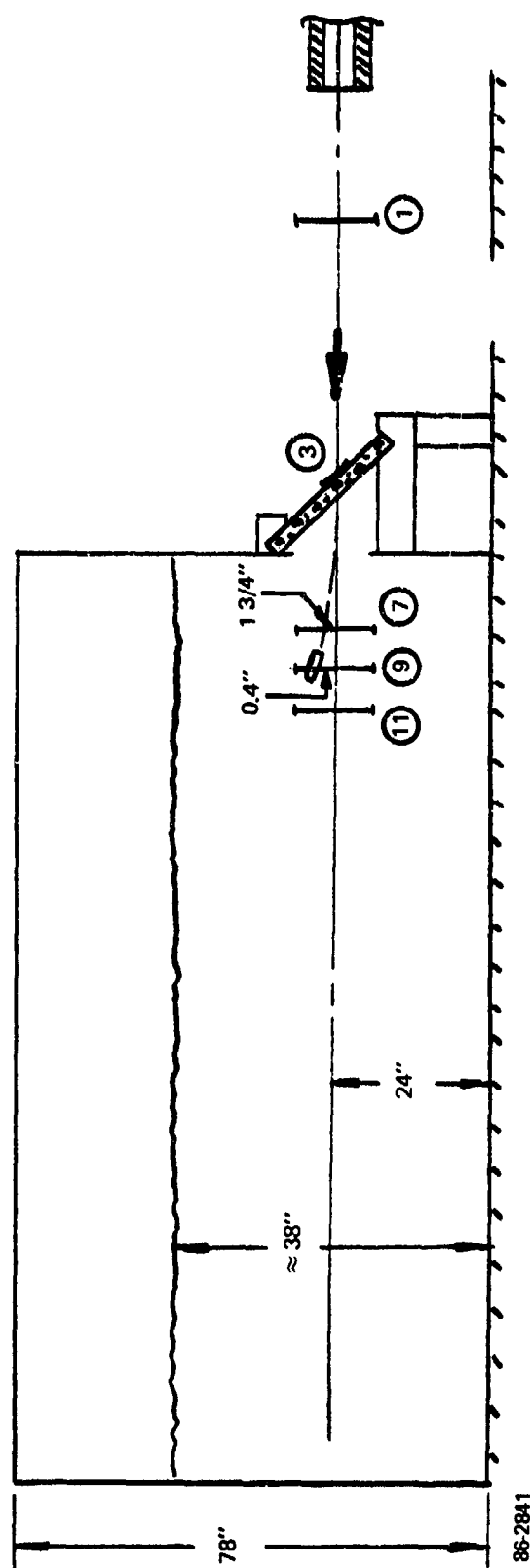
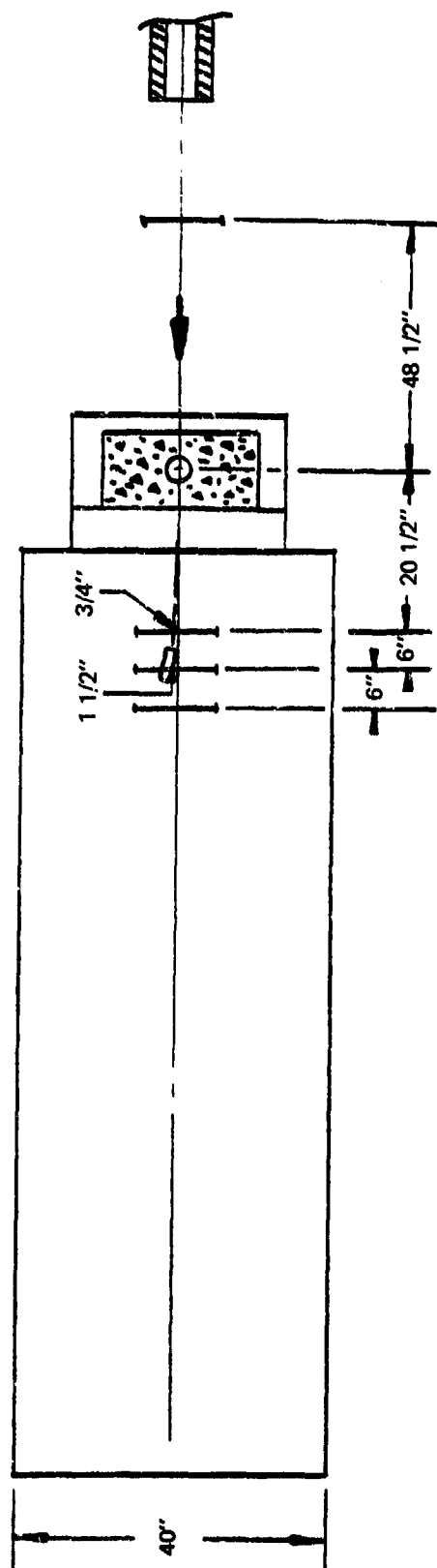
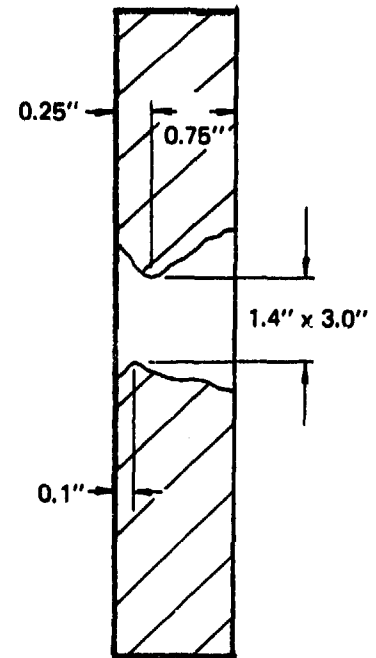
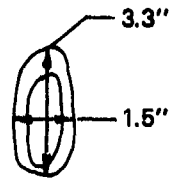


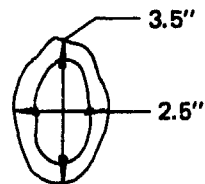
Figure 26 SUBSCALE SST PENETRATION TEST 10, $\gamma = 45^\circ$, $\alpha = 0^\circ$

Target no. 10
1" thick

Front



Back



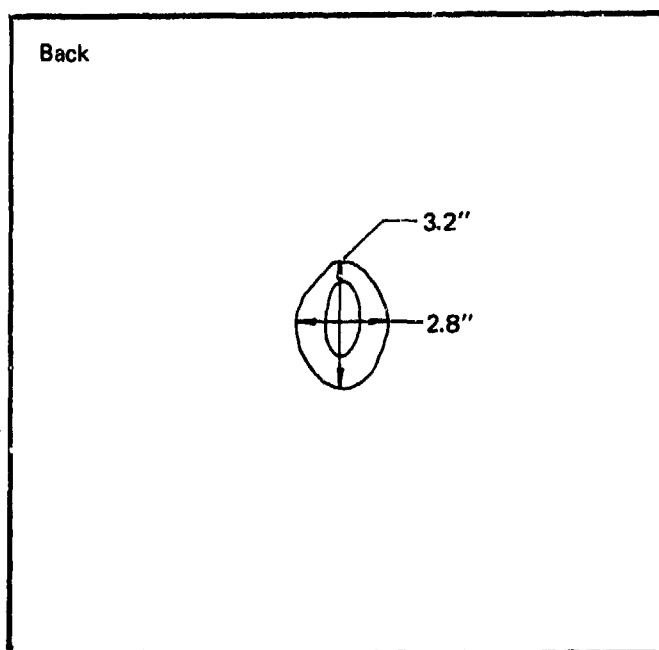
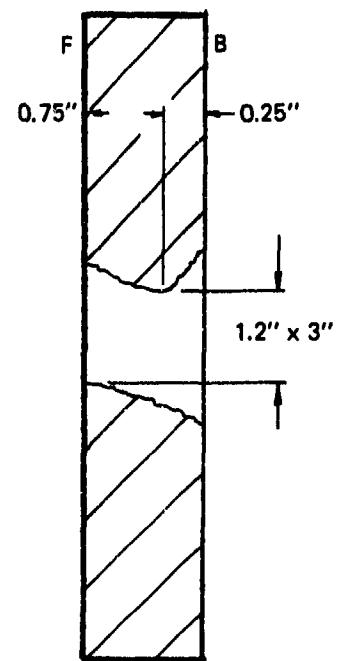
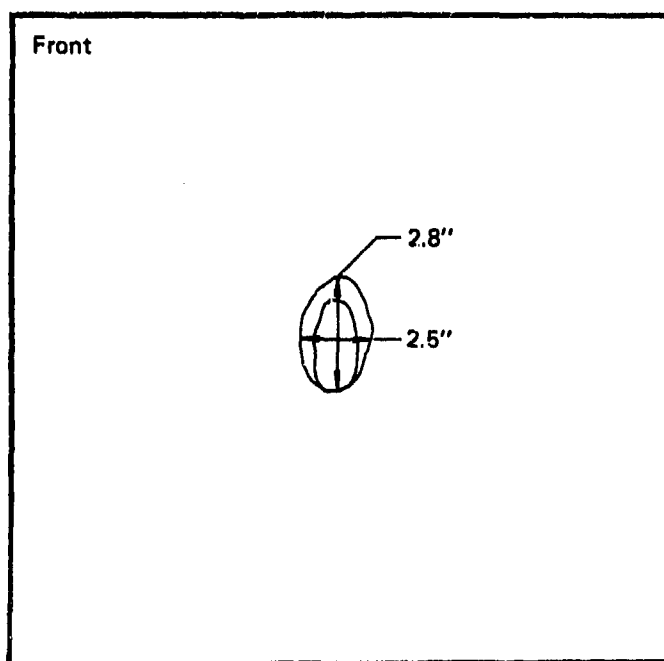
$$\gamma = 45^\circ$$

$$\alpha = 0^\circ$$

86-2842

Figure 27 TEST 10 TARGET DATA – SST PROJECTILE

Target no. 12
1" thick



$$\gamma = 45^{\circ}$$

$$\alpha = 0^{\circ}$$

86-2845

Figure 30 TEST 12 TARGET DATA – CONE PROJECTILE

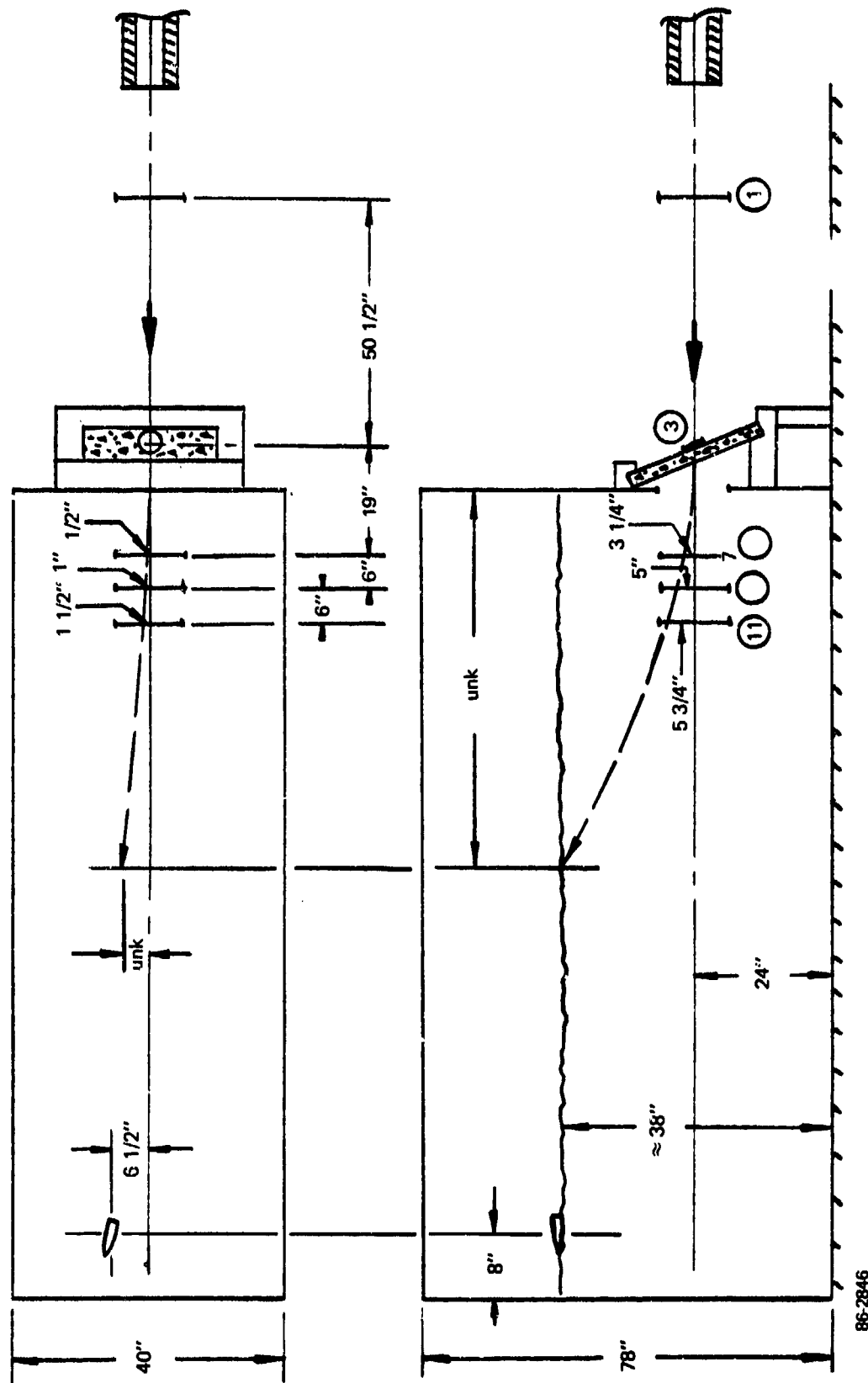
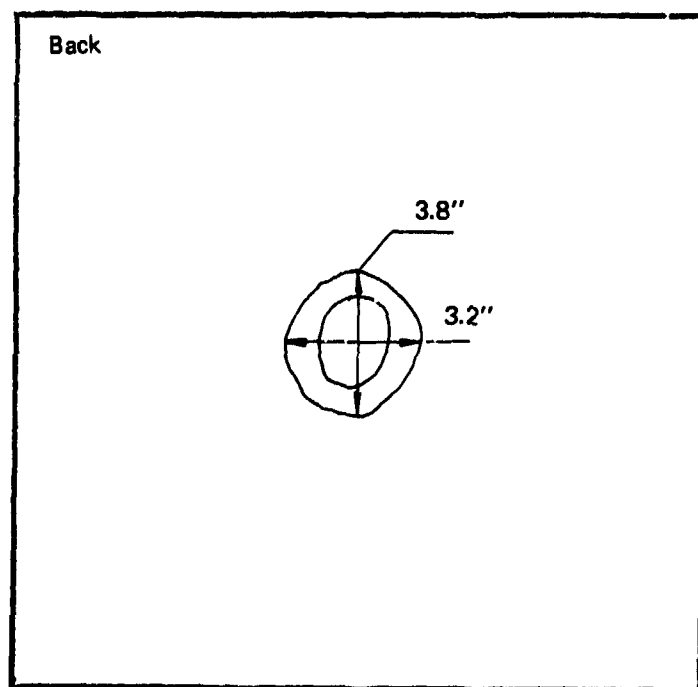
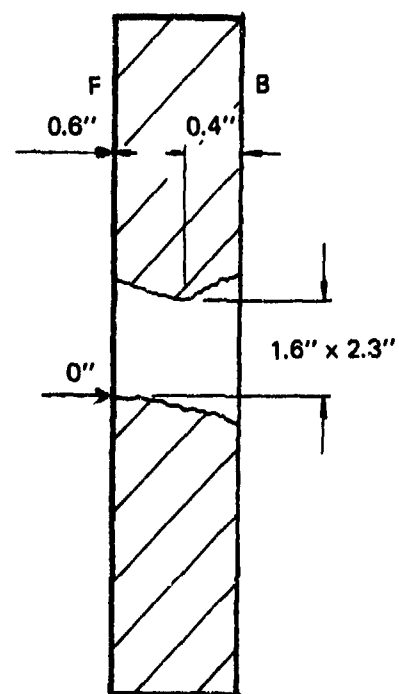
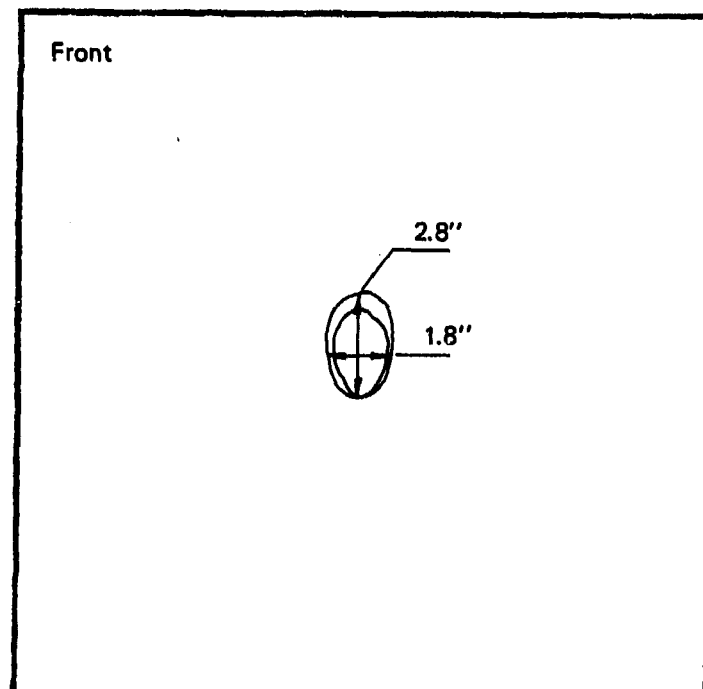


Figure 31 SUBSCALE OGIVE PENETRATION TEST 13, $\gamma = 22-1/2^\circ$, $\alpha = 5^\circ$

86-2846

Target no. 13
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 5^{\circ}$$

86-2847

Figure 32 TEST 13 TARGET DATA

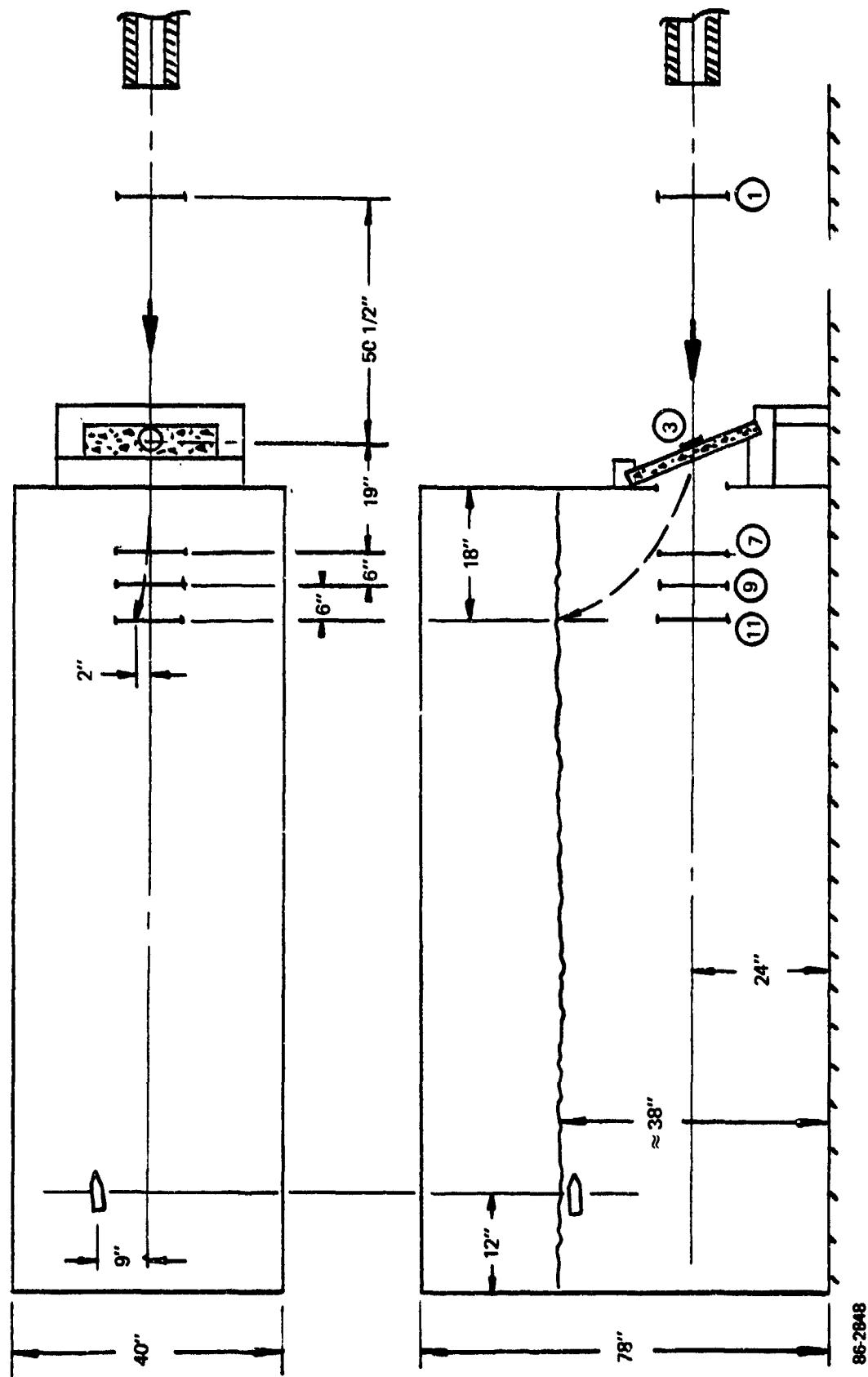
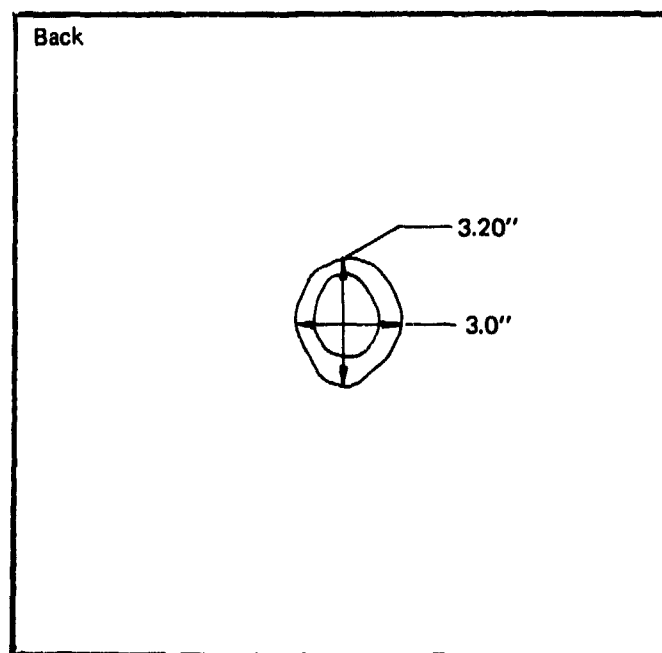
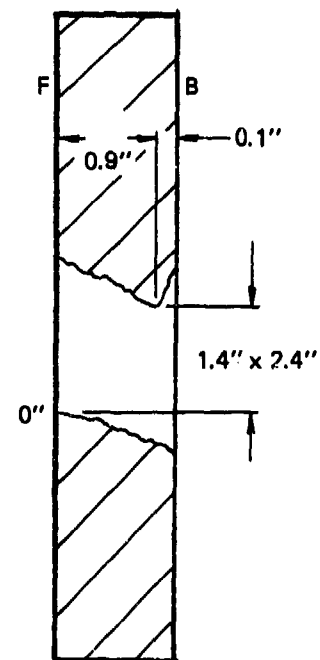
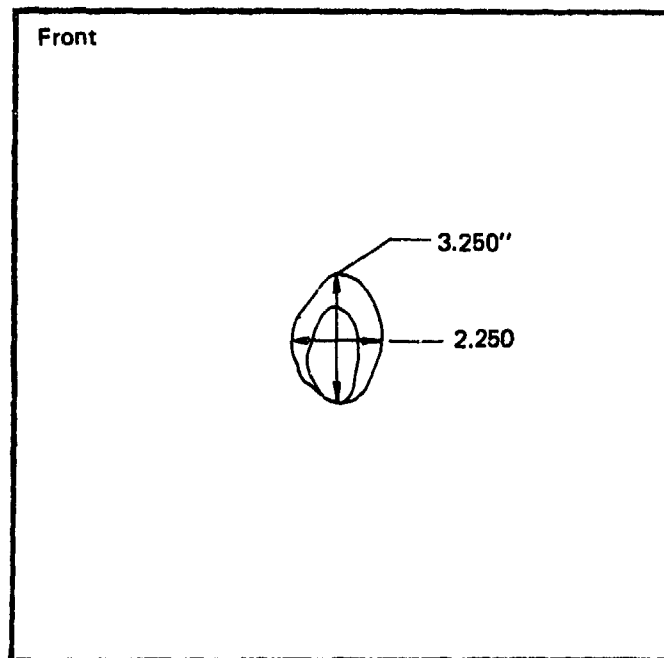


Figure 33 SUBSCALE CONE PENETRATION TEST 14, $\gamma = 22.1/2^\circ$, $\alpha = 5^\circ$

86-2848

Target no. 14
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$a = 5^{\circ}$$

86-2849

Figure 34 TEST 14 TARGET DATA – CONE PROJECTILE

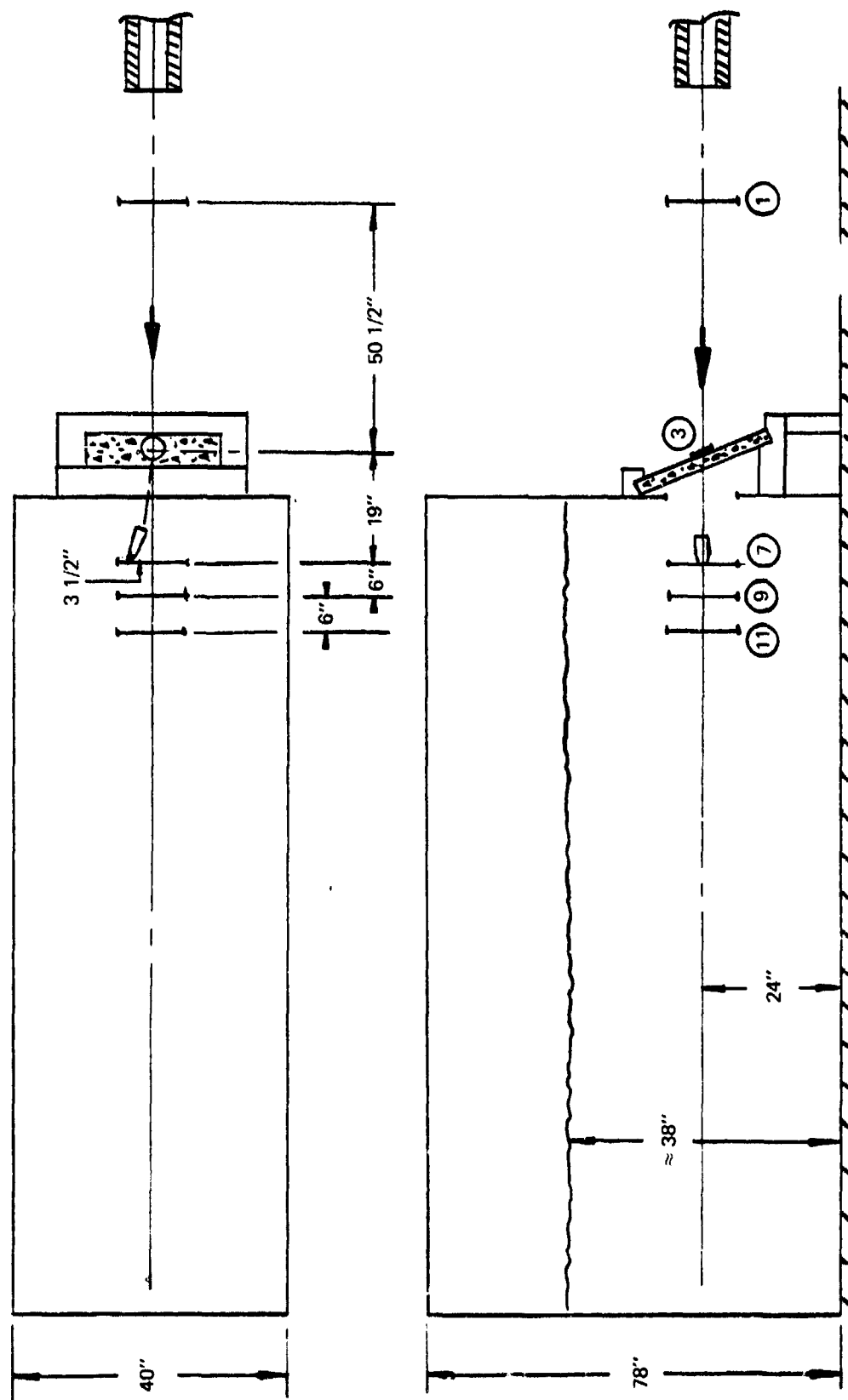
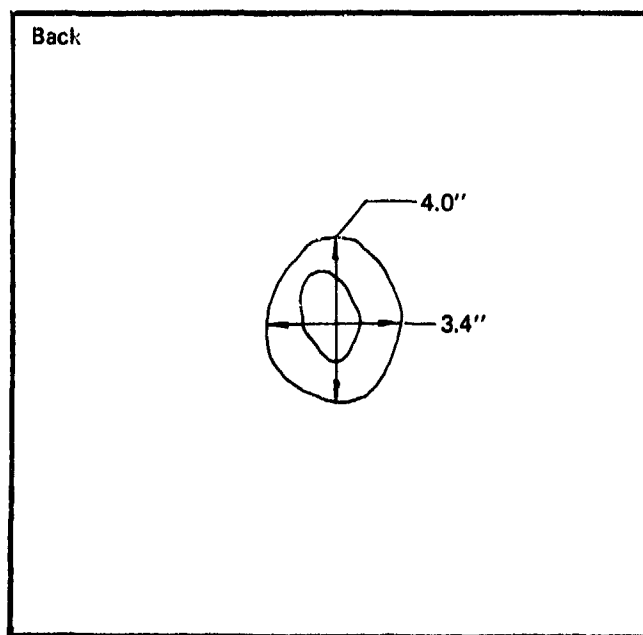
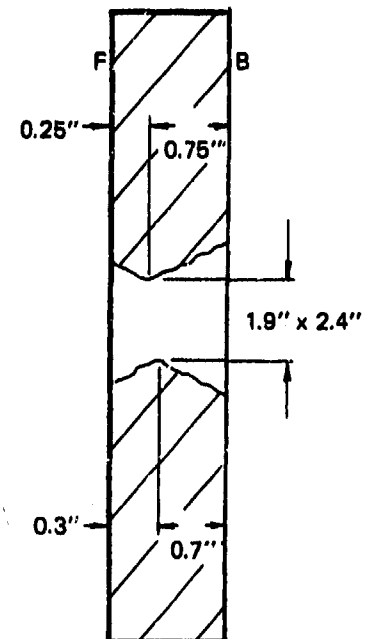
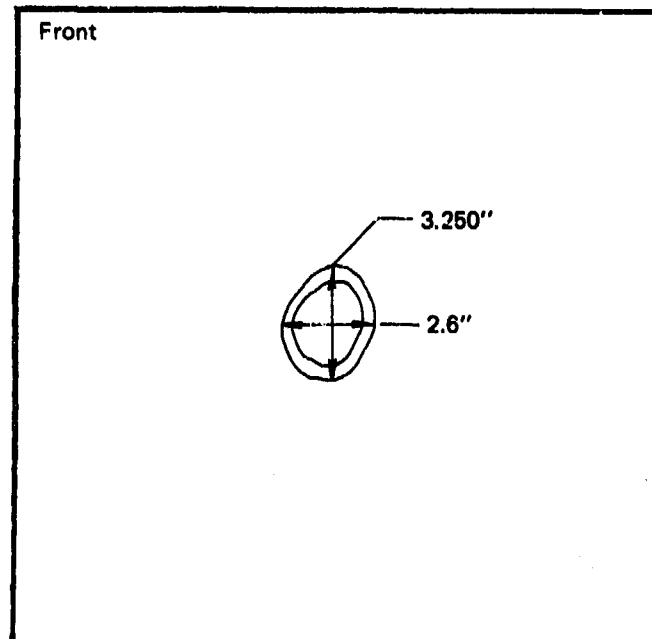


Figure 35 SUBSCALE SST PENETRATION TEST 15, $\gamma = 22\frac{1}{2}^\circ$, $\alpha = 5^\circ$

86-2850

Target no. 15
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 5^{\circ}$$

86-2851

Figure 36 TEST 15 TARGET DATA – SST PROJECTILE

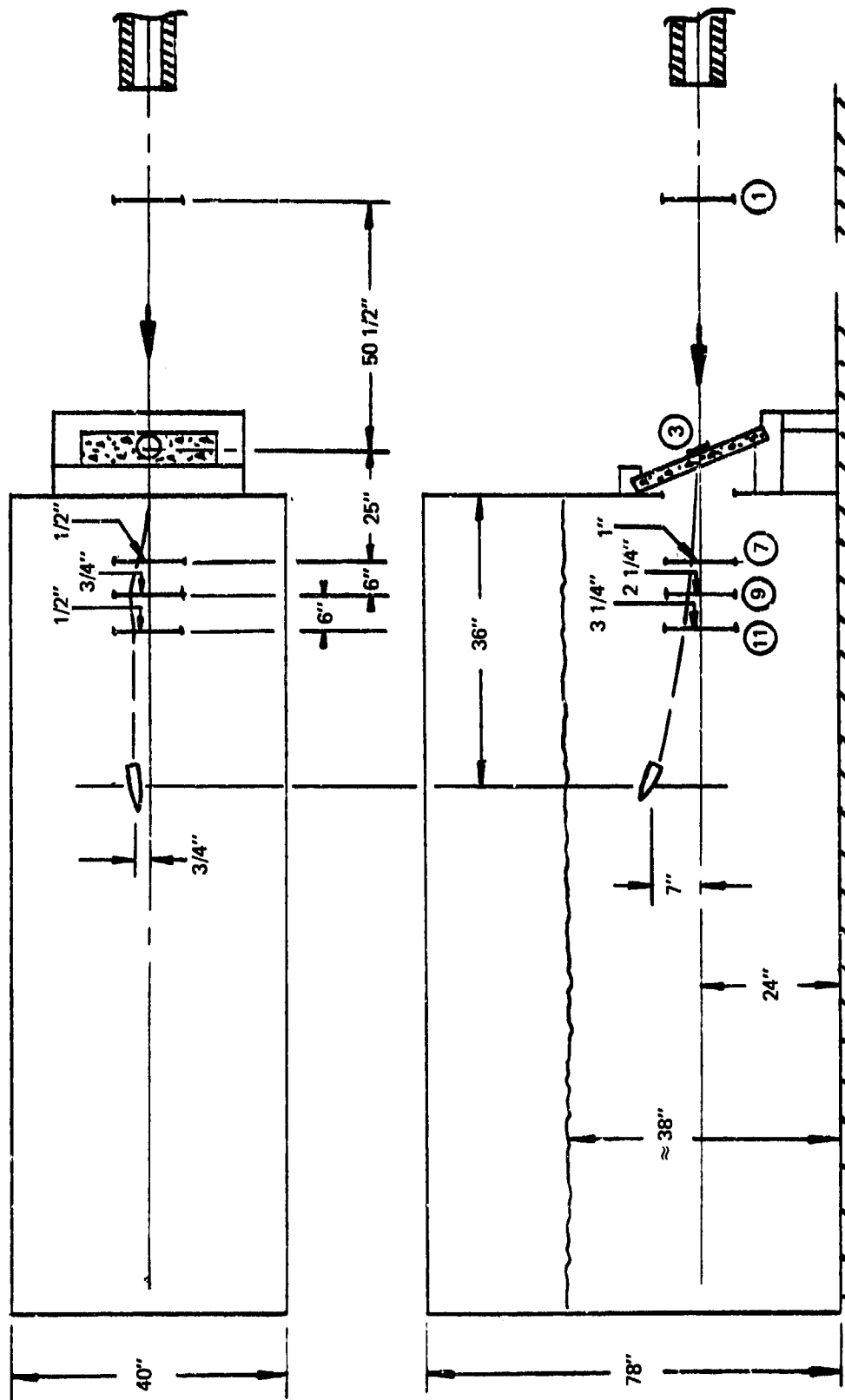
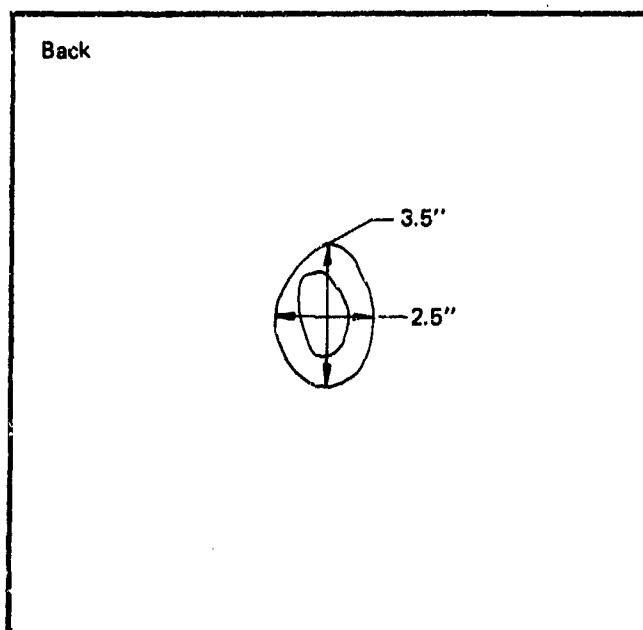
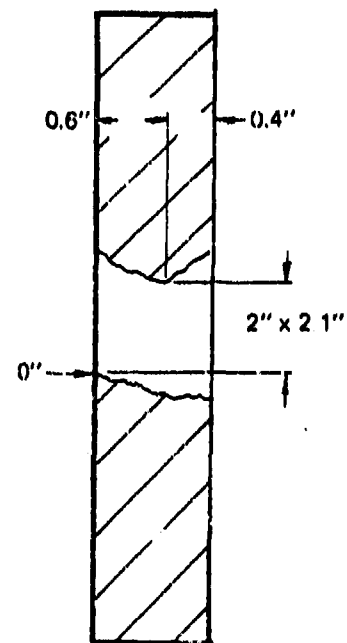
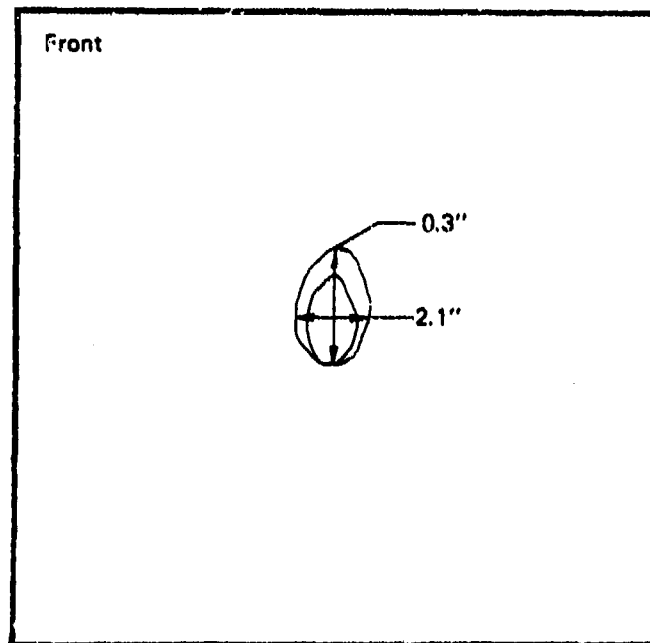


Figure 37 SUBSCALE OGIVE PENETRATION TEST 16, $\gamma = 22.17^\circ$, $\alpha = 2.17^\circ$

86-2852

Target no. 16
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 2 \frac{1}{2}^{\circ}$$

86-2853

Figure 38 TEST 16 TARGET DATA – OGIVE PROJECTILE

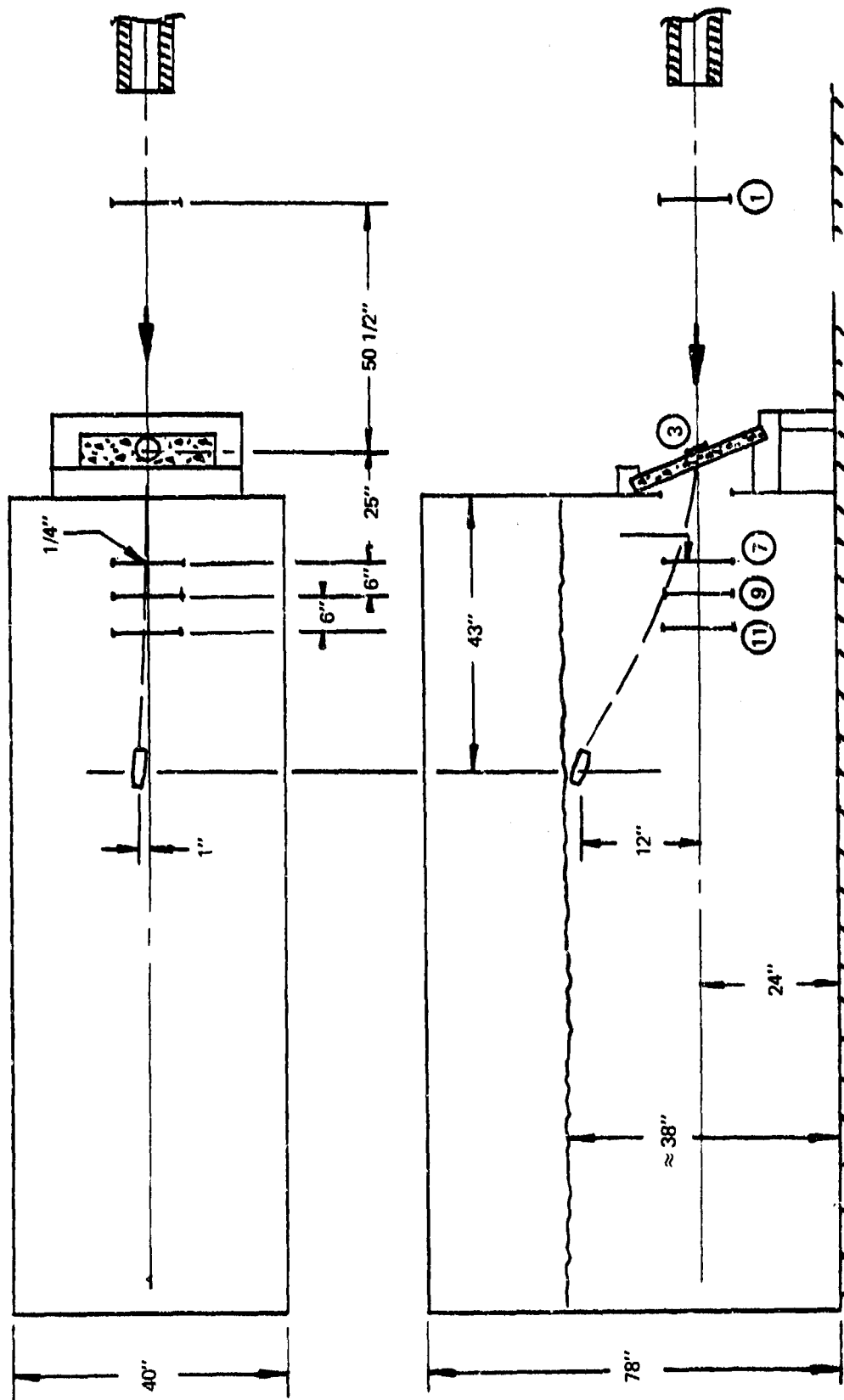
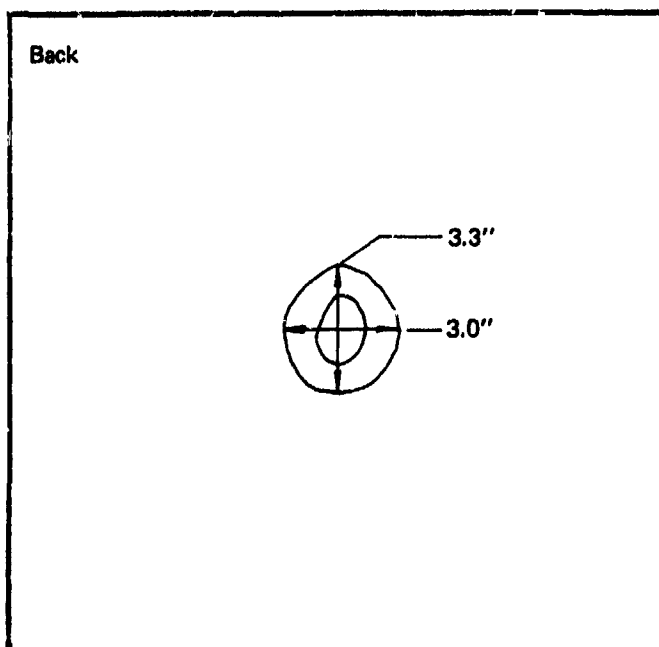
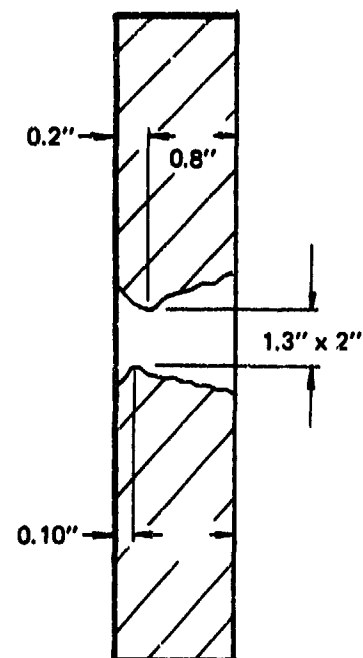
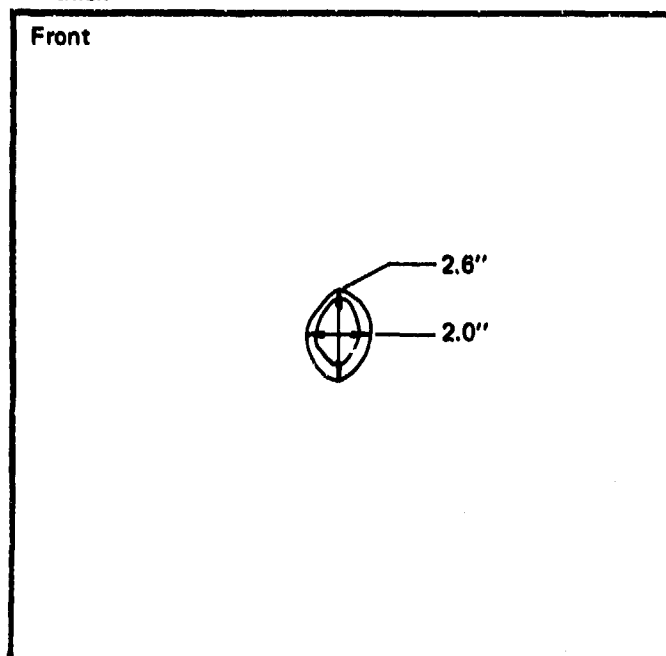


Figure 39 SUBSCALE SST PENETRATION TEST 17, $\gamma = 22.1/2^\circ$, $\alpha = 2.1/2^\circ$

86-2854

Target no. 17
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 2 \frac{1}{2}^{\circ}$$

88-2855

Figure 40 TEST 17 TARGET DATA – SST PROJECTILE

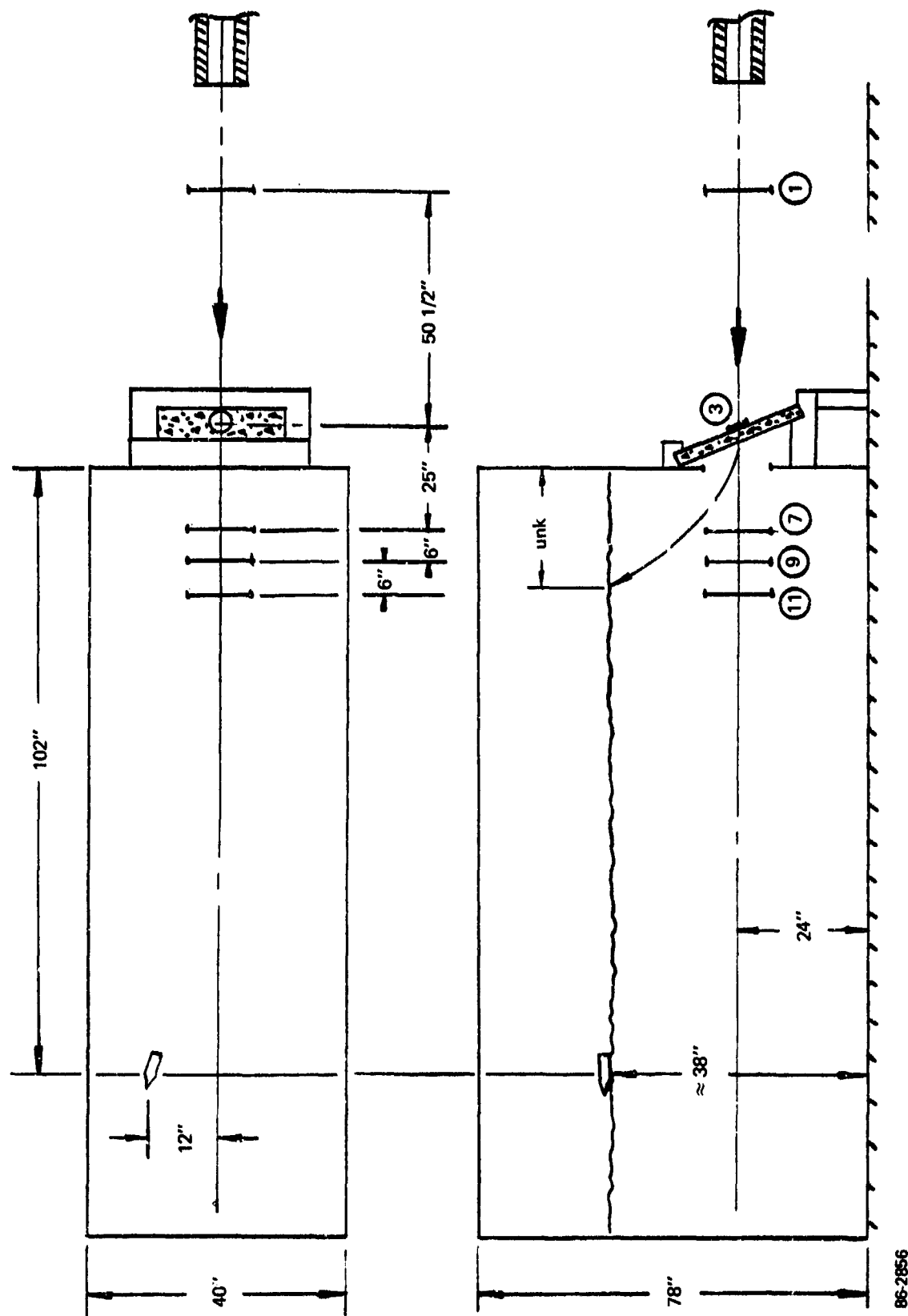
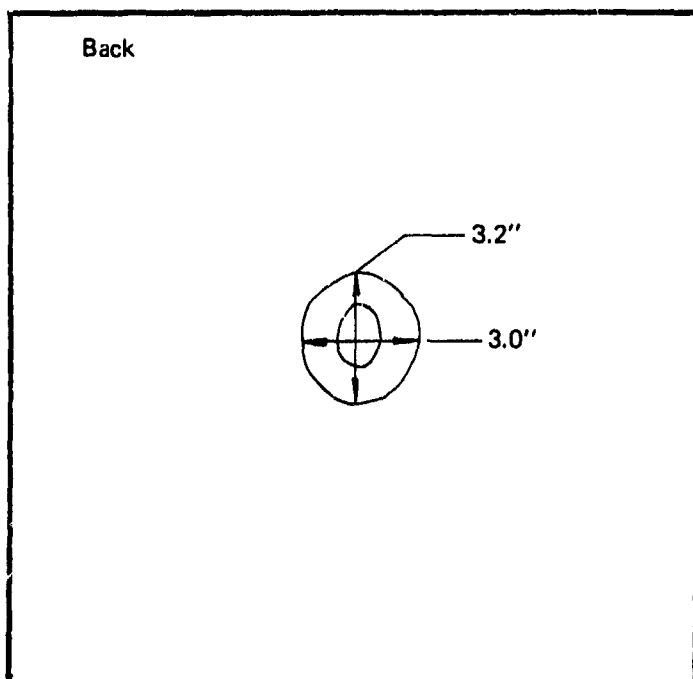
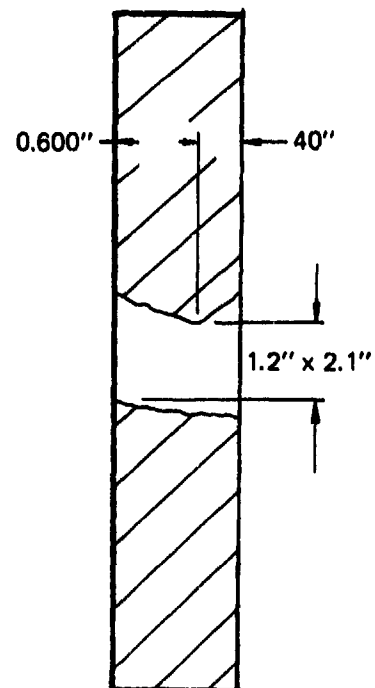
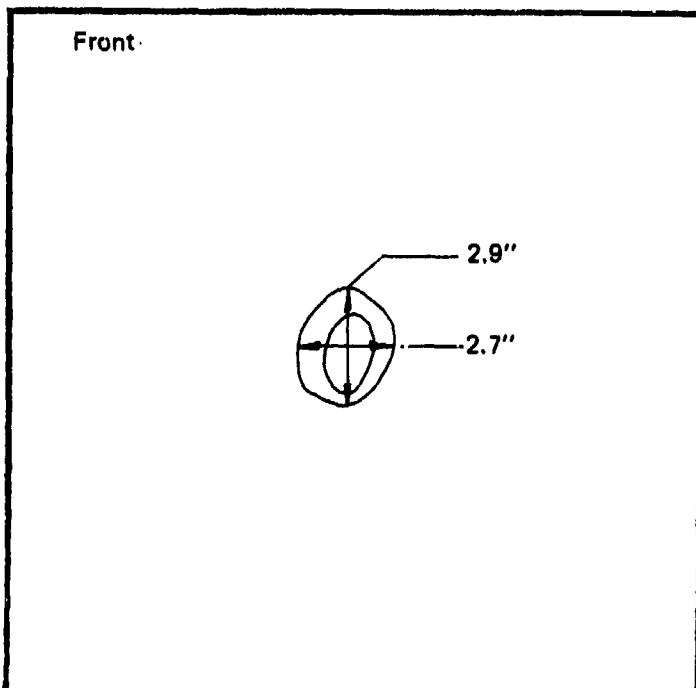


Figure 41 SUBSCALE CONE PENETRATION TEST 18, $\gamma = 22.1/2^\circ$, $\alpha = 2.1/2^\circ$

86-2856

Target no. 18
1" thick



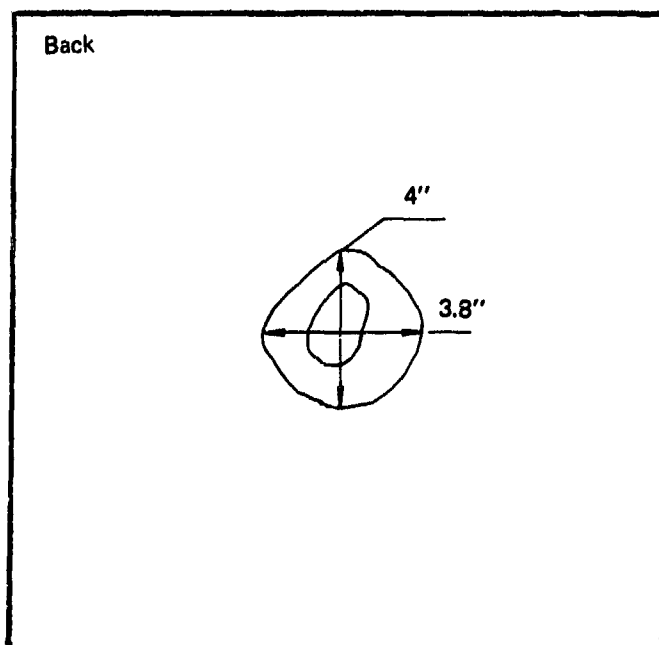
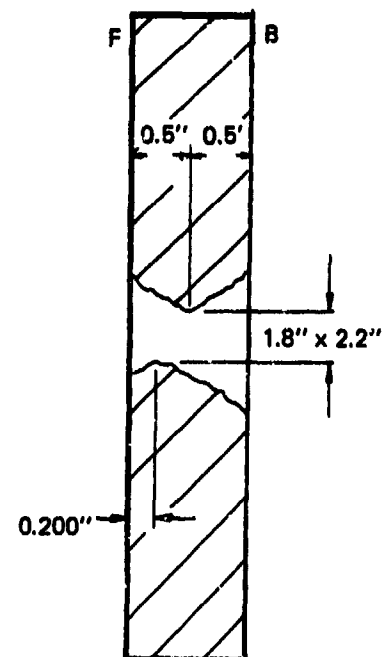
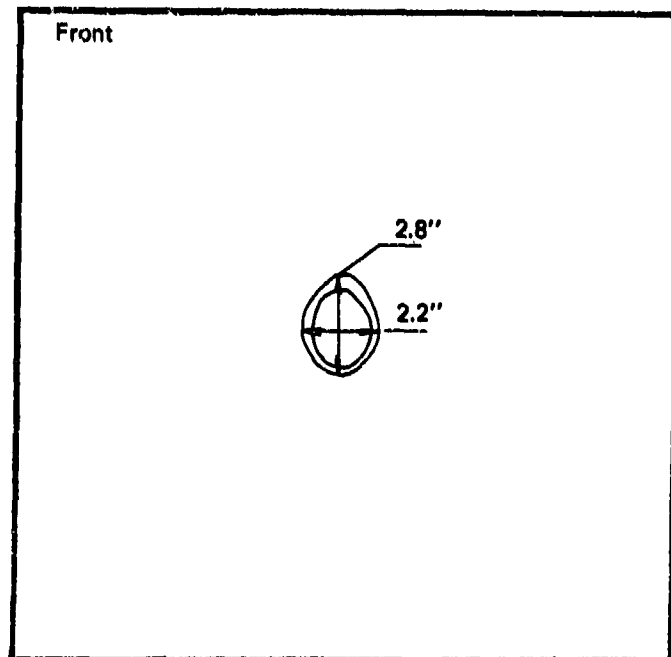
$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 2 \frac{1}{2}^{\circ}$$

86-2842

Figure 42 TEST 18 TARGET DATA – CONE PENETRATION

Target no. 19
1" thick



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 0^{\circ}$$

Figure 44 TEST 19 TARGET DATA – OGIVE PROJECTILE

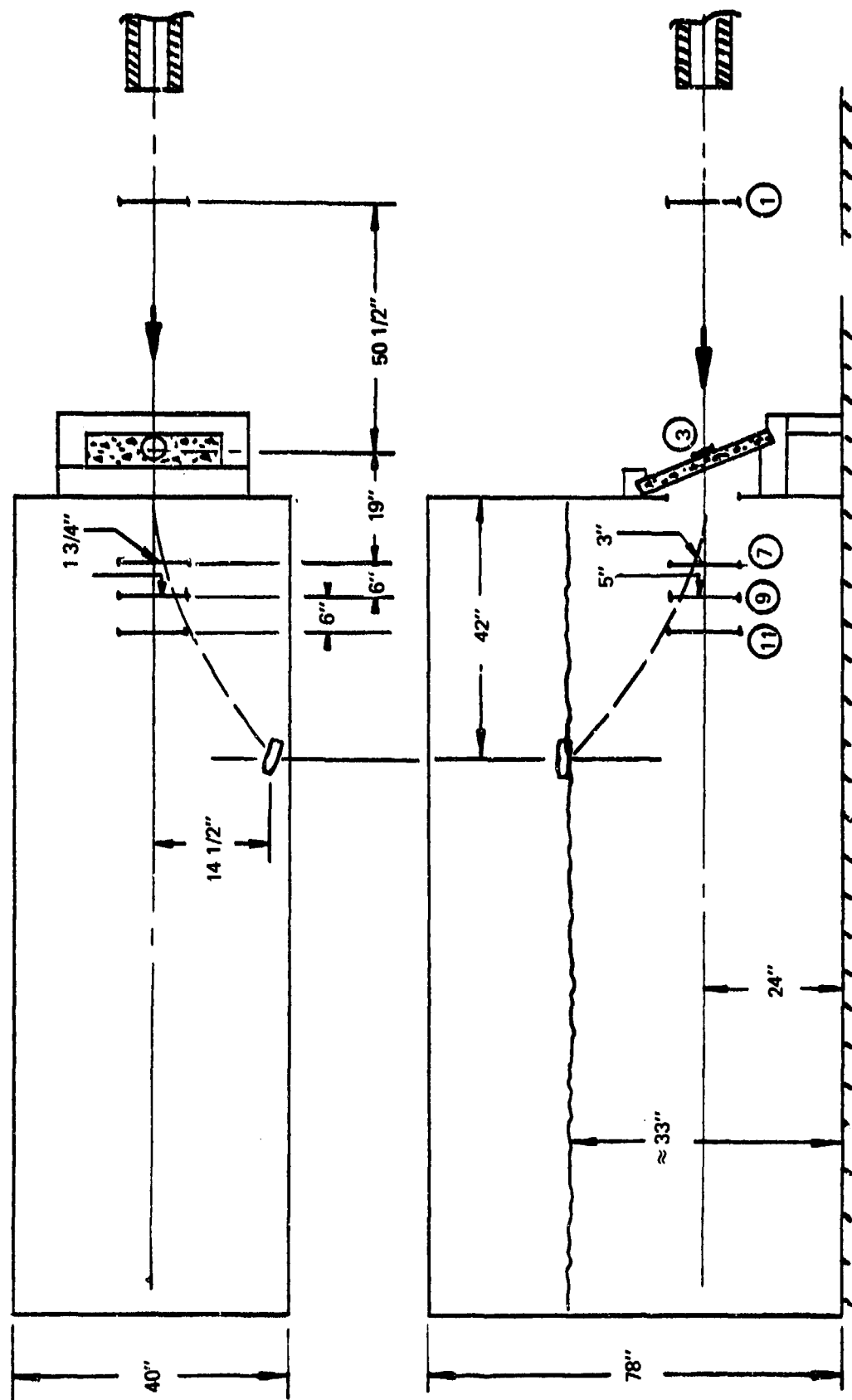
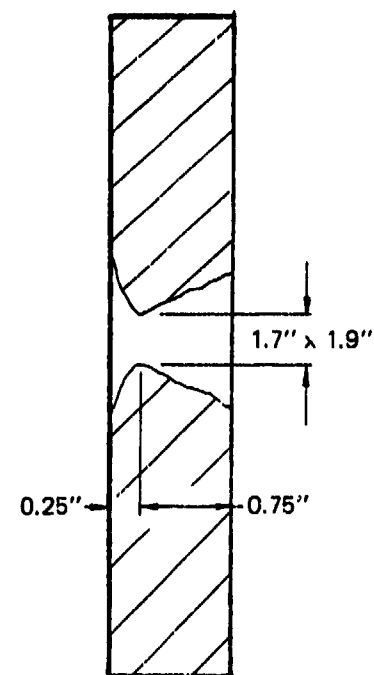
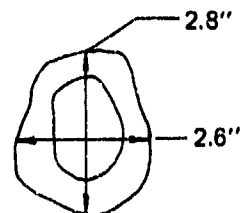


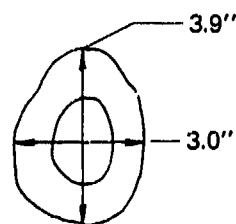
Figure 45 SUBSCALE SST PENETRATION TEST 20A, $\gamma = 22-1/2^\circ$, $\alpha = 0^\circ$

Target no. 20A
1" thick

Front



Back



$$\gamma = 22 \frac{1}{2}^{\circ}$$

$$\alpha = 0^{\circ}$$

86-2861

Figure 46 TEST 20A TARGET DATA – SST PROJECTILE

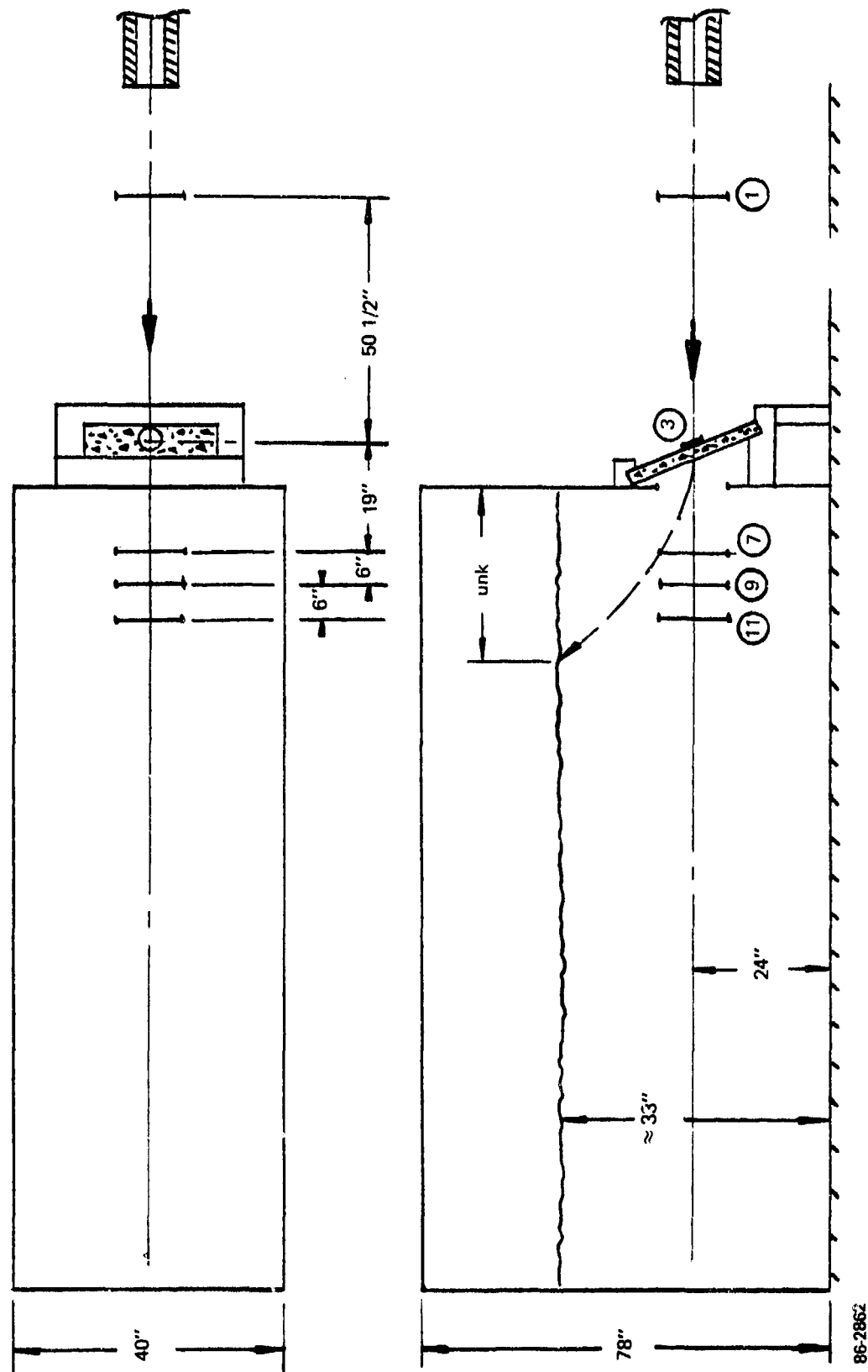
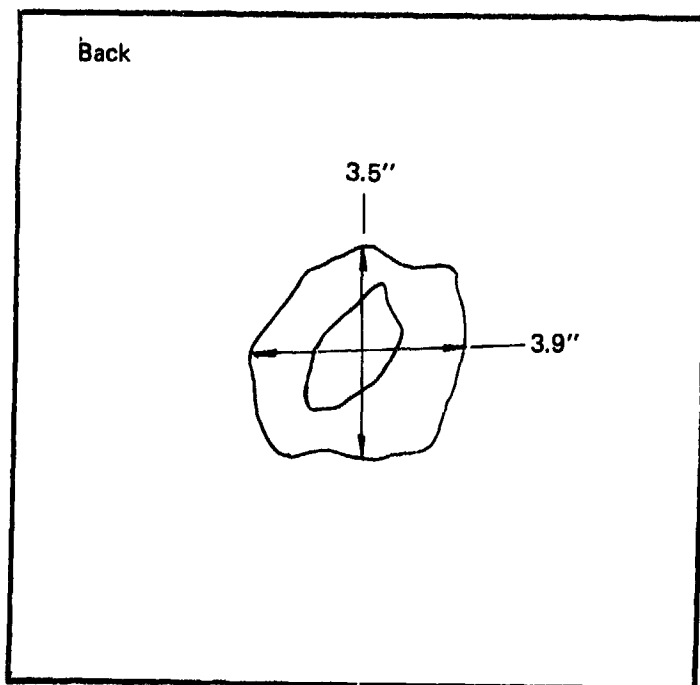
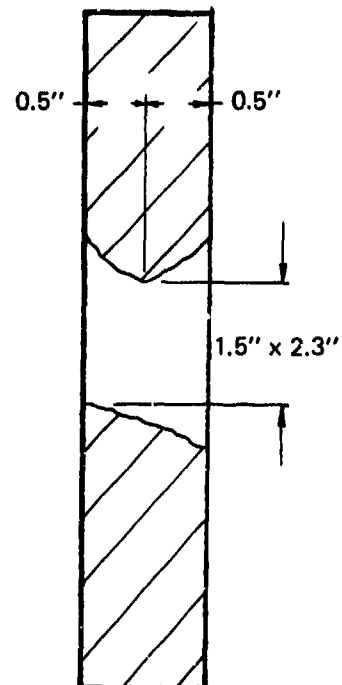
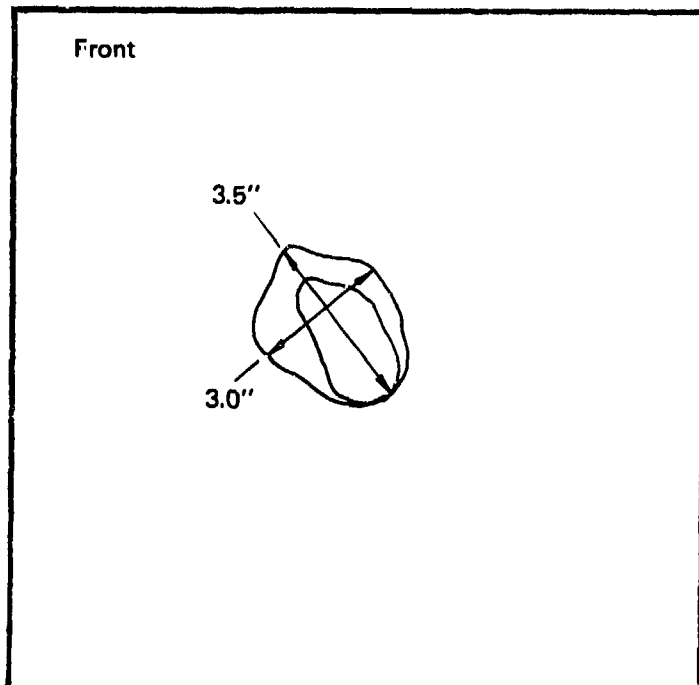


Figure 47 SUBSCALE CONE PENETRATION TEST 21, $\gamma = 22.1/2^\circ$, $\alpha = 0^\circ$

86-2862

Target no. 21
1" thick



$\gamma = 22 \frac{1}{2}^{\circ}$
 $\alpha = 0^{\circ}$

86-2863

Figure 48 TEST 21 TARGET DATA — CONE PROJECTILE

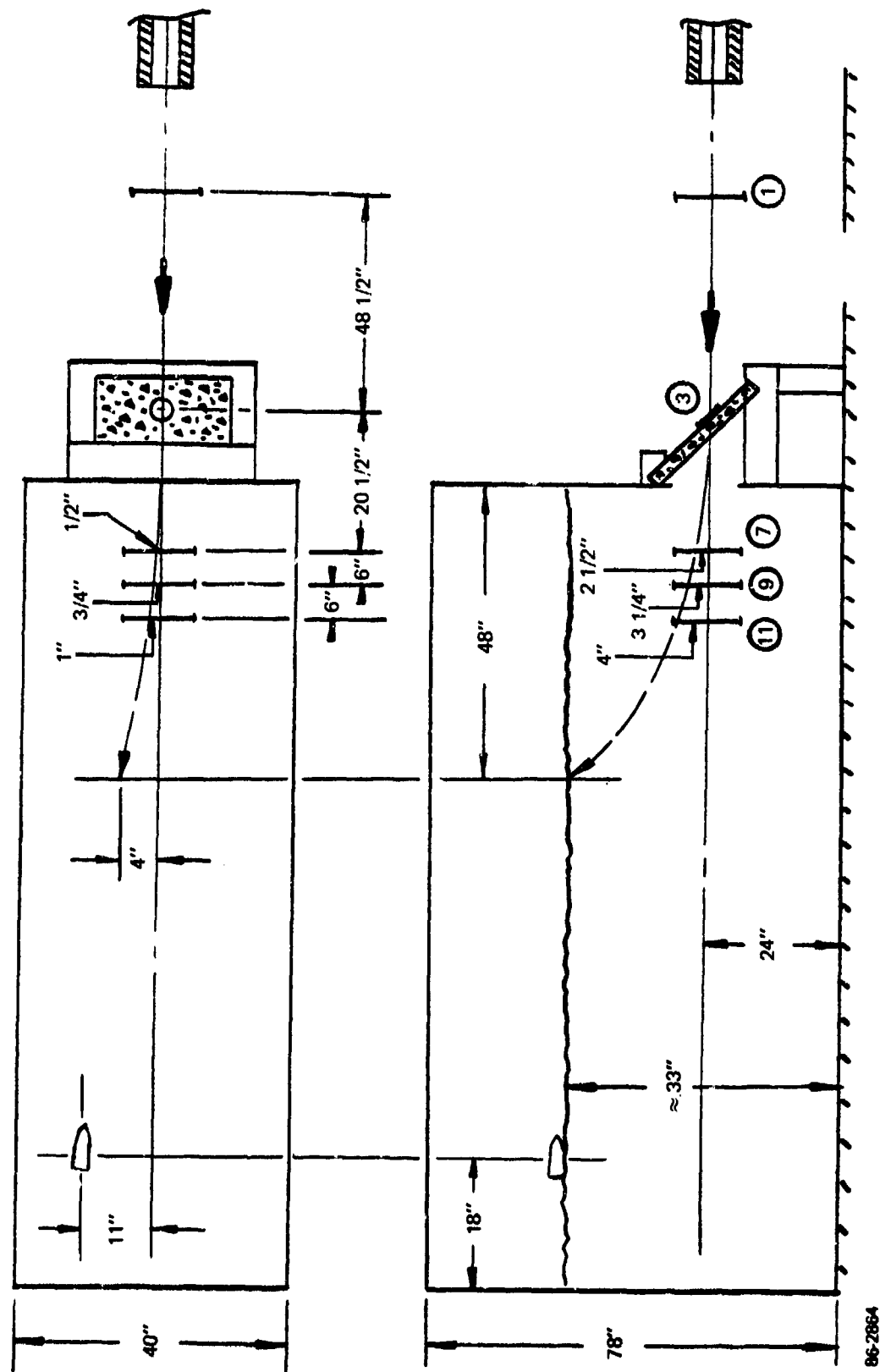
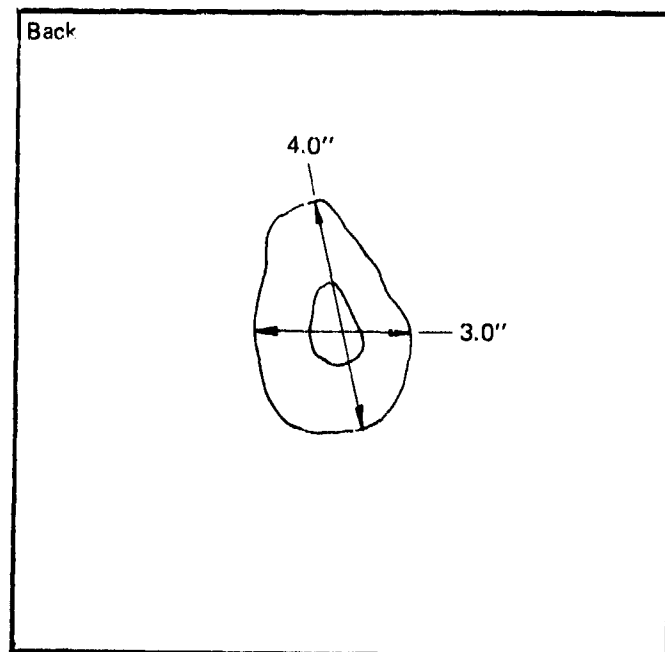
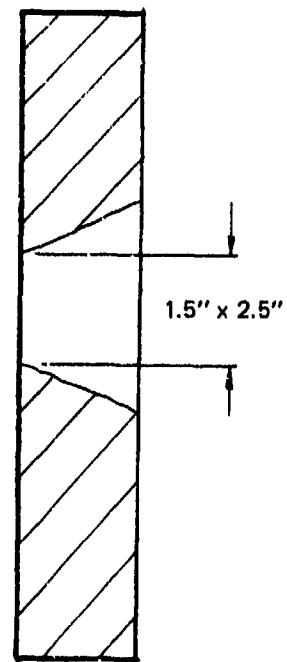
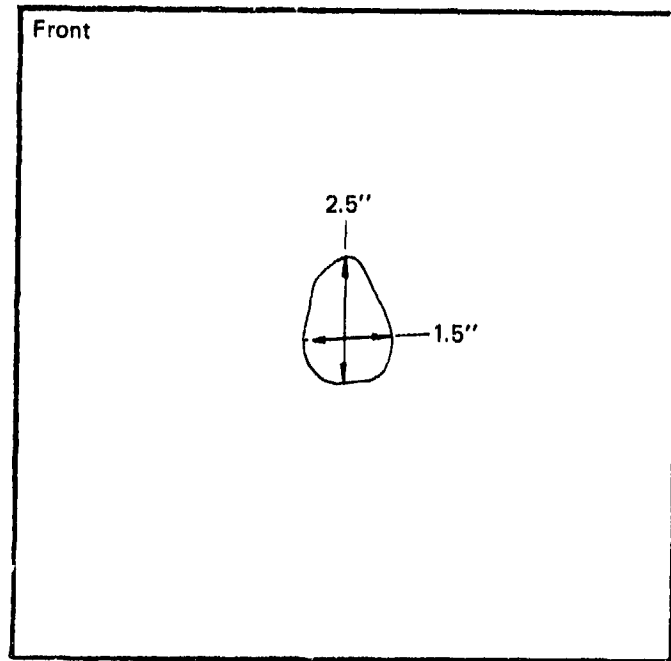


Figure 49 SUBSCALE OGIVE PENETRATION TEST 22, $\gamma = 45^\circ$, $\alpha = 2.1/2^\circ$

86-2864

Target no. 22
1" thick



$$\gamma = 45^\circ$$

$$a = 2 \frac{1}{2}"$$

86-2865

Figure 50 TEST 22 TARGET DATA – OGIVE PROJECTILE

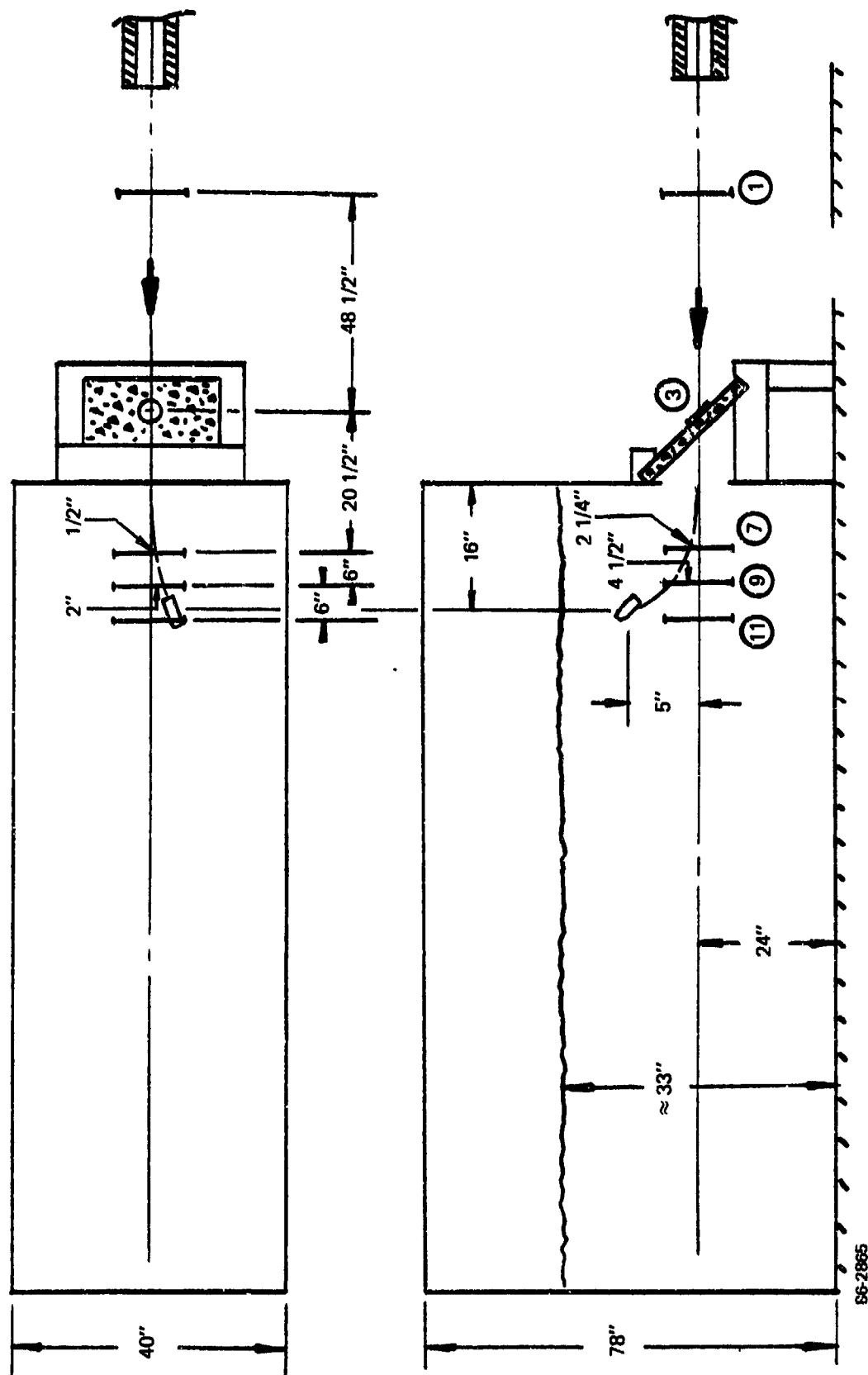


Figure 51 SUBSCALE SST PENETRATION TEST 23, $\gamma = 45^\circ$, $a = 2-1/2^\circ$

86-2865

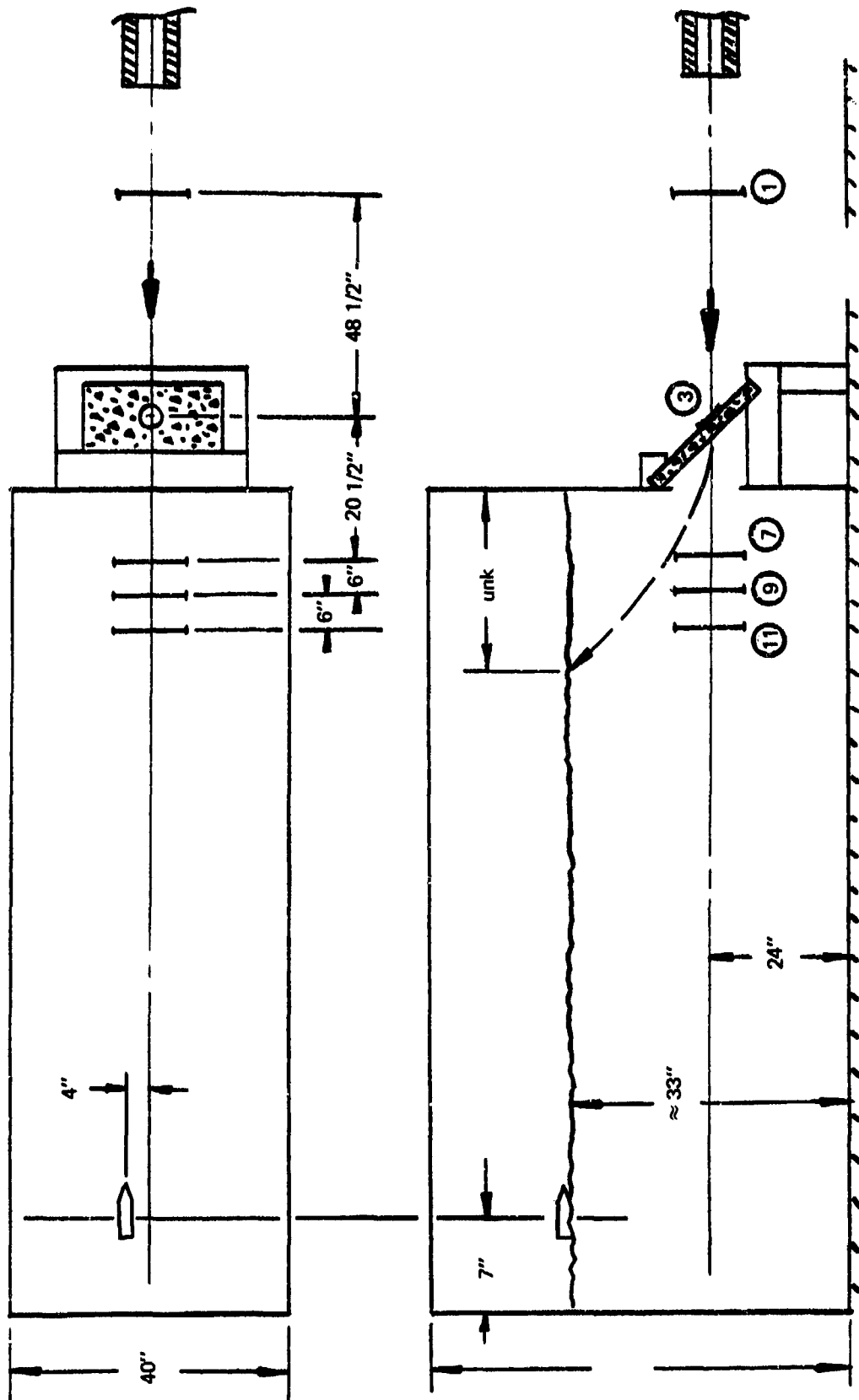


Figure 52 SUBSCALE CONE PENETRATION TEST 24, $\gamma = 45^\circ$, $\alpha = 2.1/2^\circ$

86-2866

were 975, 974 and 981 ft/s, respectively. Thus, slight differences in launch weight due to the different configurations had little influence on launch velocity. The primary factor influencing launch velocity was probably the tolerances between the sabot and launcher barrel.

The copper ball deformation is listed for each test. These values are more indicative of relative performance than actual g measurement since many of the measurements are outside the linear range of the copper ball. Trajectory estimates through the sand media were made for each EP model. Concrete crater measurements were made on each concrete target except for four targets which broke up during removal from the test setup. These data are presented in Figures 9 through 52. Typical craters are shown in Figures 53 and 54. Because of the difficulty in comparing the many test variables and referring to a large number of figures, an attempt has been made to summarize the test results in tabular form. This summary is presented in Table 3.

The data in Table 3 is grouped by EP tip configuration, obliquity and angle of attack for ease of review. Test number, measured angle of attack and, copper ball deformation are taken from Table 2. Velocity loss is calculated by taking representative velocity values from Table 2 and dividing the change in velocity in the sand media by the distance over which the change of velocity occurred. This is done for changes in velocity over distances of 6.5 and 18.5 inches for the zero obliquity tests and for approximately 20 inches for the 22.5 degree and 45 degree obliquity cases. The stability factor shown in Table 3 is an attempt to quantify and simplify the trajectory data. Basically, the value is obtained by dividing the distance traveled in the sand media by the total deviation from the normal path. For Test 1, the EP traveled 38 inches in the sand and deviated a total of 23.5 inches before leaving the sand. The result of dividing 38 by 23.5 is 1.6, the stability factor. The higher the stability factor the more stable the trajectory. The fact that the Test 1 EP left the sand means that the stability factor was probably less than the 1.6 value shown. That is, had there been

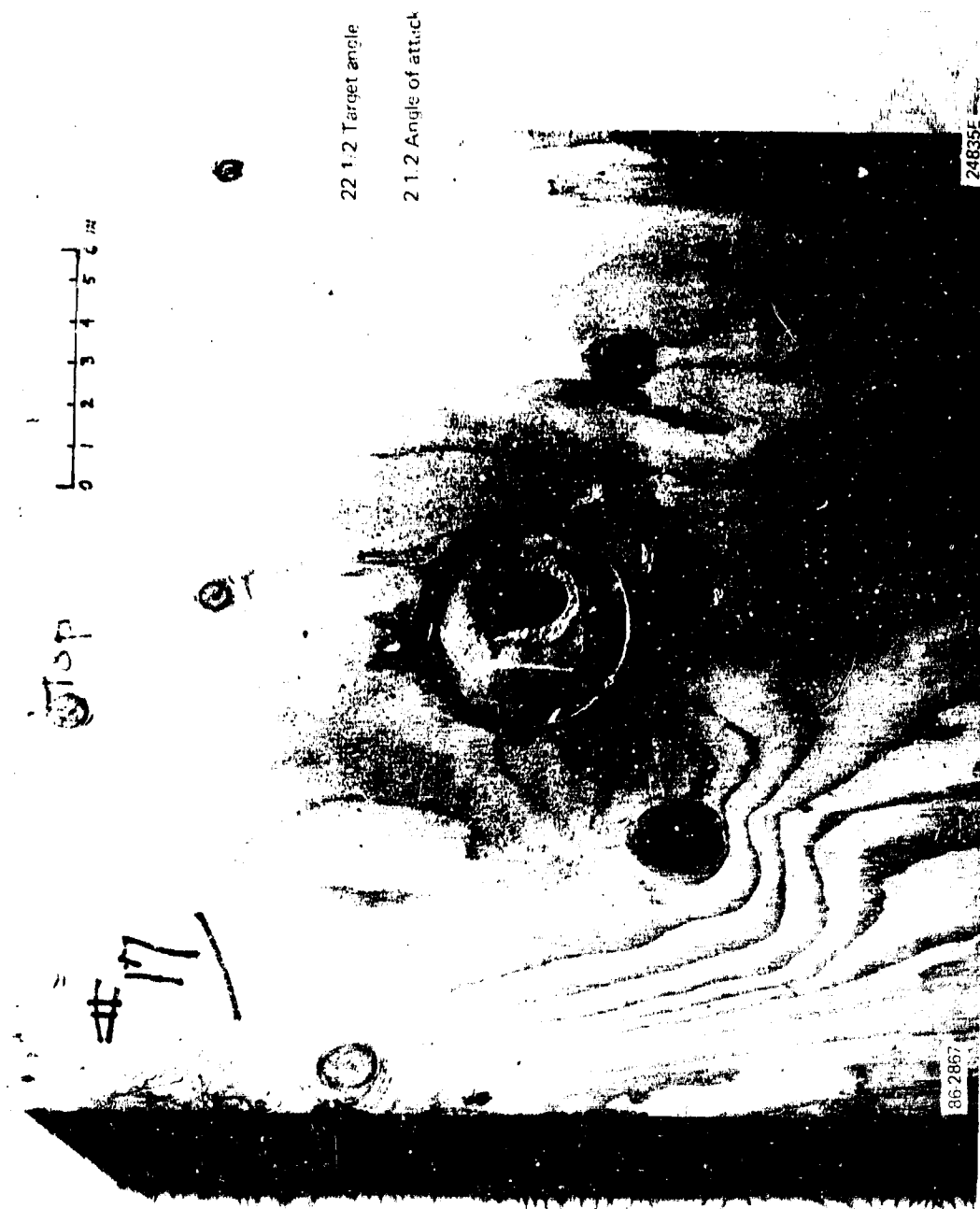


Figure 53 CONCRETE TARGET, FRONT FACE



Figure 54 CONCRETE TARGET, BACK FACE

TABLE 3. DATA SUMMARY EP MODEL TEST RESULTS

| | | Ugive | | | | | SST | | | | | Cone | | | | | | | | | | | | | | | | |
|---------------------------|---|-------------|--|--------------------------|-----------------------------|---------------------------|-------------------------------|---|------|--------|-------------|--|--------------------------|-----------------------------|---------------------------|-------------------------------|---|------|--------|-------------|--|--------------------------|-----------------------------|---------------------------|-------------------------------|---|------|--------|
| Target angle (degrees) | Desired angle of attack (degrees) | Test number | Angle of attack measured (degrees) | Passive accel. (ml/s) | Velocity loss (ft/s/in.) | | Stability factor ² | Crater size max. dimension (inches) | | | Test number | Angle of attack measured (degrees) | Passive accel. (ml/s) | Velocity loss (ft/s/in.) | | Stability factor ³ | Crater size max. dimension (inches) | | | Test number | Angle of attack measured (degrees) | Passive accel. (ml/s) | Velocity loss (ft/s/in.) | | Stability factor ⁴ | Crater size max. dimension (inches) | | |
| | | | | | At 6.5 inch depth | At 18 to 20 inch depth | | Entrance | Exit | Throat | | | | At 6.5 inch depth | At 18 to 20 inch depth | | Entrance | Exit | Throat | | | | At 6.5 inch depth | At 18 to 20 inch depth | | Entrance | Exit | Throat |
| 0 | 0.0 | 2 | 1.3 | 0.9 | 24.7 | 23.2 | 7.7 | 3.0 | 3.2 | 1.6 | 3 | 1.4 | 21.5 | 39.8 | 41.7 | 7.4 | 2.3 | 3.5 | 1.5 | 5 | 0.0 | 1.3 | 39.3 | 39.6 | 3.8 | 2.2 | 2.7 | 1.4 |
| 0 | 5.0 | 1 | 7.5 | 4.7 | 38.6 | 36.9 | 1.64 | - | - | - | 4 | 5.0 | 16.5 | 43.5 | 40.4 | 2.1 | 2.4 | 3.3 | 2.1 | 6 | 7.7 | 1.8 | 40.9 | - | 1.14 | 2.6 | 3.0 | 2.1 |
| 22.5 | 0.0 | 19 | 4.5 | 3.8 | - | 19.3 ¹ | 3.0 | 2.7 | 4.0 | 2.2 | 20A | 2.5 | 12.8 | - | 33.0 | 2.1 | 2.8 | 3.9 | 1.9 | 21 | 6.0 | 2.5 | - | - | (5) | 3.5 | 3.9 | 2.3 |
| 22.5 | 2.5 | 16 | 2.1 | 2.7 | - | 20.5 ² | 5.5 | 3.0 | 3.5 | 2.1 | 17 | 2.3 | 24.5 | - | - | 3.8 | 2.6 | 3.3 | 2.0 | 18 | 1.8 | 4.6 | - | - | (5) | 2.9 | 3.2 | 2.1 |
| 22.5 | 5.0 | 13 | 4.5 | 4.1 | - | 16.8 | 4.3 | 2.8 | 3.8 | 2.3 | 15 | 8.0 | 8.1 | - | - | 5.4 | 3.2 | 4.0 | 2.4 | 14 | 5.0 | 4.9 | - | - | 1.9 | 3.2 | 3.2 | 2.4 |
| 45 | 0.0 | 8 | 0.0 | 4.6 | - | 13.1 | 2.5 ⁴ | 4.0 | 5.8 | 4.2 | 10 | 0.5 | - | - | 27.9 | 4.8 | 3.3 | 3.5 | 3.0 | 12 | 1.25 | 5.1 | - | 18.6 | 1.8 | 2.7 | 3.2 | 3.0 |
| 45 | 2.5 | 22 | 2.3 | 4.5 | - | 13.3 | 4.64 | 2.5 | 4.0 | 2.5 | 22 | 2.0 | 11.9 | - | 29.3 | 4.0 | - | - | - | 24 | 2.0 | 4.3 | - | - | (5) | - | - | - |
| 45 | 5.0 | 7 | 5.9 | 2.7 | - | 15.7 | 1.1 | 3.0 | 4.0 | 4.0 | 9 | 3.8 | 7.6 | - | 27.0 | 6.6 | 3.0 | 3.3 | 2.3 | 11 | 2.5 | 5.8 | - | 13.8 | 4.3 | - | - | - |

NOTES:

- 1) Measured over 25 inches.
- 2) Measured over 31 inches.
- 3) Stability factor equals depth of penetration in sand media divided by total deviation from normal path.
- 4) Came out of catcher, actual stability factor lower than shown.
- 5) Missed first velocity grid.

more sand in the box the projectile probably would have deviated more. Finally, the maximum crater dimensions are presented for the entrance hole, the throat and the exit hole for each test for which this data was obtained.

A perusal of Table 3 provides insights into the significance of the test data. The copper ball deformation is equatable to peak deceleration "g's". For the ogive shape tip these forces are relatively independent of obliquity or angle of attack except for the zero-zero case. Conversely, the SST loads are highest for the zero-zero case and appear to be somewhat alleviated by obliquity and angle of attack. In all instances the SST loads are higher than the ogive loads for the same test conditions. The conical tip loads tend to increase somewhat with obliquity, to be independent of angle of attack, to be less than the SST values for all tests and comparable to the ogive values for most tests.

The velocity loss factor seems to be independent of depth for the data available. As might be expected, the higher loaded SST configuration loses velocity fastest. Obliquity seems to reduce velocity loss for all three configurations. The SST trajectory is the most stable and the cone the least stable. The conical tip EP model deviated so much from the normal path on Tests 18, 21 and 24 that the first velocity grid in the sand media was missed and no in-depth velocity data obtained. The conical stability factors are lower than the SST values in all cases and comparable to the ogive values. It should be noted, however, that no ogive EP model deviated so much as to miss the in-depth velocity grids completely.

The crater data showed the following trends. The entrance hole was generally smaller than the exit hole with the throat diameter generally smaller than both. The crater size tended to increase with obliquity. The ogive crater sizes were generally equal to or larger than the SST or cone EP model produced craters.

In summary, it can be stated that the SST EP models experienced the highest peak deceleration loads and the highest velocity loss rates through the sand media while exhibiting the most stable trajectory performance. The cone tip EP models exhibited the least stable trajectory performance. Both the ogive and cone peak deceleration "g" loads were comparable and substantially lower than the SST loads.

It is recommended that the test results be used to refine currently available EP trajectory predictive techniques both as a method of further explaining the observed EP model performance and increasing the ability of predicting the performance of future EP designs.

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