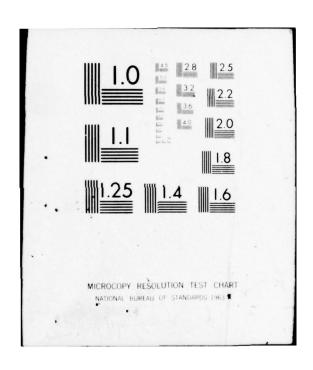
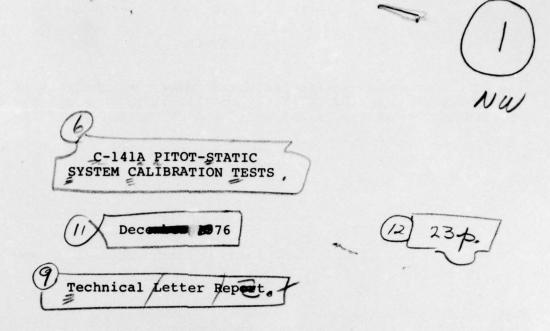
AIR FORCE FLIGHT TEST CENTER EDWARDS AFB CALIF C-141A PITOT-STATIC SYSTEM CALIBRATION TESTS.(U) DEC 76 R K POMEROY, H KLEIN, J A GUTHRIE AD-A036 241 F/6 14/2 UNCLASSIFIED NL OF AD A036241 END DATE 3-77





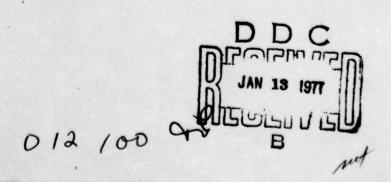
Ronald K. / Pomeroy,

Herbert / Klein,

Joseph A. / Guthrie, In.

Thomas P. / Stafford

AIR FORCE FLIGHT TEST CENTER EDWARDS AIR FORCE BASE, CALIFORNIA



## FOREWORD

These tests were conducted under the authority of AFFTC Program Directive 71-41, 28 October 1976. The program Job Order Number was 921NUI and the AFFTC priority was 41.

Foreign announcement and dissemination by the Defense Documentation Center are not authorized because of technology restrictions of the U.S. Export Controls Acts as implemented by AFR 400-10.

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## INTRODUCTION

This report presents the results of a six flight C-141A pitot-static system evaluation performed at Edwards AFB, California, between 1 and 16 November 1976. Twenty hours of C-141A ground systems tests, along with 11.4 hours of C-141A and 8.8 hours of T-38A flight time (table 1) were used to complete the pitot-static systems evaluation.

During the "Stretch C-141" baseline testing on a standard fleet configured C-141A (AF S/N 66-0186), it was discovered that the ship's production airspeed (Vc) did not agree with , the corrected flight test kiel-trailing cone airspeed (Vc). To investigate this discrepancy, an additional airspeed calibration was conducted on the baseline C-141 using an AFFTC calibrated T-38 pacer. The resulting analysis of the pacer data confirmed the validity of the flight test kiel-trailing cone pitot-static system data and verified that there was a difference between the baseline C-141A and the 1966 Category II pitot-static system's calibration data (reference 1). The magnitude of the baseline C-141 airspeed error was significant enough to perhaps explain, in part, the C-141 "Fly Heavy" problem (Reference 2). Since the "Stretch C-141" program involved only one aircraft, more testing was required to determine whether this error was unique to one test aircraft or an indication of a larger fleet wide problem.

The objective of the test program was to predict the pitot-static system errors for the C-141A fleet. To predict these errors the pilot and copilot airspeed, altitude, and Mach system vertical scale instrument (VSI) errors of six standard fleet configured C-141A's from the 63rd Military Airlift Wing (MAC), Norton AFB, California, were spot checked. The in-flight VSI errors were a summation of the pitot-static probe errors and the central air data computer (CADC) - VSI electromechanical system errors. For this test program no modifications to the existing C-141A pitot-static system were made.

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<sup>1</sup> See figure B2 for a C-141 Airspeed System Schematic.

Table 1

C-141A PITOT-STATIC SYSTEM CALIBRATION FLIGHT LOG

C-14lA C-14lA C-14l D T-38 Pace <sup>C</sup> Test <sup>a</sup> S/N Flt Time (hr) Configuration Flt Time (hr)	Pace 66-6172 1.6 1, 2, 3 1.5	Pace 66-7952 2.8 1, 2, 3 1.5	Tower Fly-by 1, 2, 3	Pace 65-9402 1.9 1, 2, 3 1.6	Pace 63-8084 1.8 1, 2, 3 1.5	Pace 67-0011 2.0 1 1.4	Pace 64-0652 1.3 1, 2, 3 1.3	Total 11.4 Total 8.8
			F F					
Date	1 NCV 76	4 Nov 76		8 Nov 76	10 Nov 76	12 Nov 76	16 Nov 76	

aFor all flights takeoff gross weight = 220,000 lb.

bc-141A Configurations: 1 - Cruise

1 - Cruise
2 - Takeoff - gear up, flaps -75 pct
3 - Landing - gear down, flaps - 100 pct

CT-38 S/N 67-4954 was used for all pace flights.

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## TEST AND EVALUATION

The flight test program consisted of six C-141A/T-38A pacer flights. On flight 2, a series of tower fly-by points were also accomplished. Prior to each flight a ground calibration of the aircraft's pitot-static systems was performed (Appendix B). Each of the six pacer flights consisted of 30,000 and 20,000 feet (MSL), cruise configuration and 10,000 feet (MSL) takeoff and landing configuration points. On flight 5, adverse weather conditions prohibited flight operations at 10,000 feet. The T-38A pacer position and alignment, detailed in figure Al, enabled the pacer pilot to perceive small airspeed and altitude changes, while maintaining a position outside the C-141A pressure wave.

The flight test data (figure A2) from the six aircraft tested in the cruise regime were small and within MIL-P-26292C tolerances. The mean in-flight Mach number error was 0.0022, and at the 95 percent confidence level the in-flight arithmetic mean of any C-141A fleet system should range from 0.0006 to 0.0038 Mach above the VSI Mach number. At typical cruise conditions (0.74 Mach and 35,000 feet), this correlates to from 0.1 to 0.9 knots or from 11 to 75 feet above the VSI airspeed and These small in-flight errors would have little effect on cruise performance and would not explain the C-141A fleet "Fly Heavy" problem (reference 2). The in-flight mean Mach number error encountered in the "Stretch C-141" program fell outside the C-141A fleet 95 percent confidence interval. This indicates that the in-flight pitot-static system errors measured on the baseline C-141A were not representative of the C-141A fleet. No differences between the pilot and copilot systems were noted on any of the aircraft tested. The in-flight VSI errors compared well with the ground calibration data (Appendix B) and indicate the majority of the in-flight errors were in the CADC - VSI system, rather than in the pitot-static probes.

The results of the cruise configuration pacer flight tests indicate that the predicted C-141A fleet VSI errors in the cruise regime are small and present no flight safety hazards.

The 10,000 feet (MSL) takeoff and landing configuration flight test data (figure A3) indicated the in-flight errors were larger than in the cruise configuration and outside allowable MIL-P-26292C tolerances. For the five aircraft tested in takeoff and landing configuration the mean in-flight Mach number error was 0.004, and at the 95 percent confidence level the in-flight arithmetic mean of any C-141A fleet system should range from 0.00025 to 0.00775 Mach above the VSI Mach number. At typical approach conditions (140 knots and 5,000 feet), this correlates to from 0.2 to 4.6 knots or from 3 to 73 feet above the VSI airspeed and altitude. The direction of the airspeed and altitude errors provided a greater

stall margin and altitude clearance than was actually displayed on the C-141A VSI's. The in-flight VSI errors compared well with the ground calibration data (Appendix B) and indicate the majority of the in-flight errors were in the CADC-VSI system, rather than in the pitot-static probes. No differences between the pilot and copilot system were noted. Configuration changes did not appear to effect the data.

The results of the takeoff and landing configuration pacer flight tests indicate that the magnitude and direction of the predicted C-141A fleet VSI errors do not present any hazards to flight safety.

## CONCLUSIONS

The airspeed errors encountered during the "Stretch C-141" program on the baseline C-141A were found to be outside the predicted 95 percent confidence interval for the C-141A fleet. This indicates the baseline C-141A airspeed problems were not representative of the C-141A fleet. In the cruise regime the flight test data indicated that the pilot and copilot in-flight VSI system errors were small and within MIL-P-26292C tolerances. These small in-flight errors would have little effect on the C-141A fleet "Fly Heavy" problem. In the takeoff and landing configuration the pilot and copilot in-flight VSI errors were larger than those in the cruise regime and exceeded the allowable MIL-P-26292C tolerances. Typical in-flight corrections required to correct the VSI to calibrated airspeed and altitude are shown in table 2.

Table 2
C-141A FLEET VSI CORRECTIONS

	Typica Flight Cond		VSI Correction <sup>a</sup>		
Configuration	Airspeed (kt)	Altitude (ft)	Airspeed <sub>b</sub>	Altitude <sub>b</sub>	
Cruise	250 (0.74 Mach)	35,000	0.1 to 0.9	11 to 75	
Takeoff and Landing	140	10,000	0.2 to 4.6	3 to 73	

<sup>&</sup>lt;sup>a</sup>Correction be added to VSI reading.

The magnitude and direction of the predicted C-141A fleet VSI errors do not present any flight safety hazards.

For all flight conditions tested no differences were noted between the pilot and copilot system, nor were any configuration change effects present. The flight test data was in good agreement with the ground calibration results and indicated that the majority of the in-flight errors were in the CADC-VSI system, rather than in the pitot-static probes.

bC-141A fleet 95 percent confidence interval.

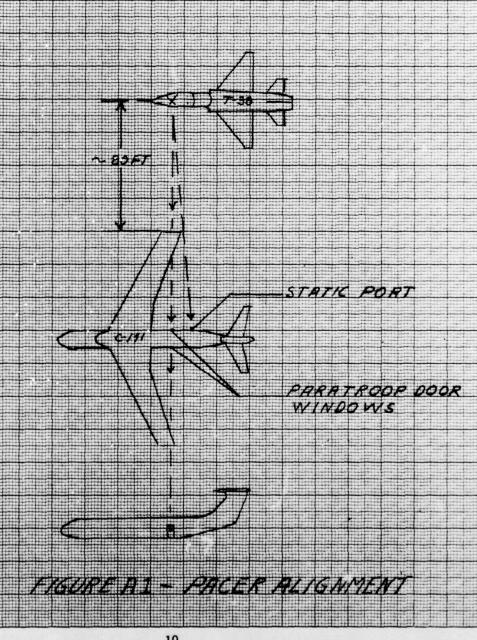
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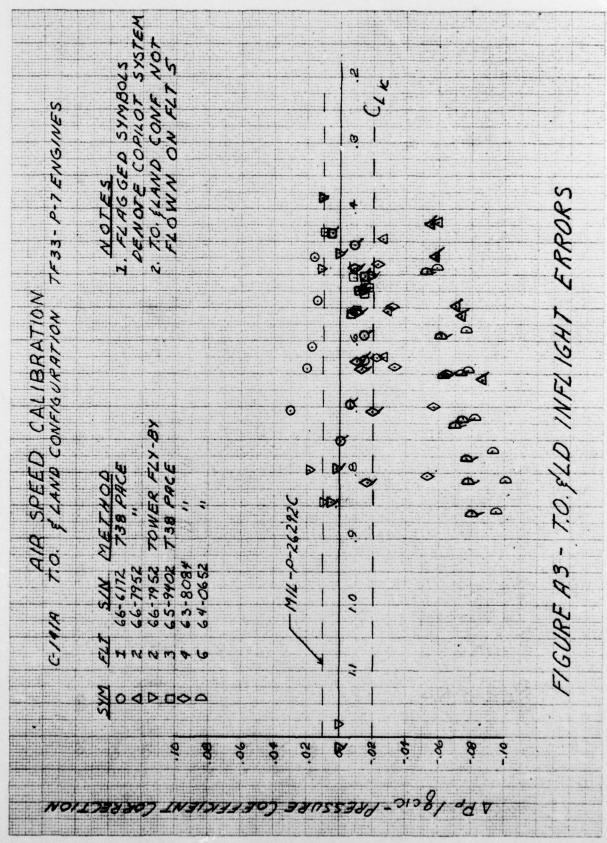
APPENDIX A FIGURES

## Figure Al

The T-38 paper horizonal and vertical placement was accomplishment by positioning the T-38 to align the C-141A paratroop door windows. Pacer lateral displacement was accomplished by aligning the C-141A wingtip with the C-141A aft fuselage static port. This alignment enabled the pacer to perceive very small airspeed and altitude changes, while maintaining a position outside of the C-141A bow wave.



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APPENDIX B

GROUND CALIBRATIONS

## Appendix B

#### GROUND CALIBRATIONS

### GROUND TESTS

Prior to each test aircraft's arrival at the AFFTC, A pitot-static system leak check was performed in accordance with T.O. 1C-141A-2-6-JG-1 by the 63rd Avionic Maintenance Squadron, Norton AFB, California. Once at the AFFTC a CADC ground calibration was performed from 10,000 feet to 40,000 feet altitude and from 150 to 375 knots. The calibration was performed by plumbing a TTU-205 (figure B1) into the C-141A's pitot-static system (figure B2) at the pitot-static system drain caps (figure B3). From this arrangement the CADC corrections to the input TTU-205 pressures could be determined from the differences in the C-141A VSI's and the corrected TTU-205 readings. To insure the accuracy of the total and static pressure, the TTU-205 was calibrated prior to and at the conclusion of the test program. No changes in the TTU-205 calibration were found.

The results of the pilot and copilot system ground calibration are shown in figures B4 through B9. In general, airspeed and Mach number errors in the pilot and copilot systems were within CADC manufacturing tolerances (reference 3). However, this was not true for the CADC altitudes errors. Using standard statistical methods (reference 4) the range of the CADC altitude deviation was predicted for the C-141A fleet.

In the cruise regime, the arithmetic mean of the altitude deviation for the systems of the six test aircraft was  $\pm$  30 feet. This was within the allowable manufacturing tolerance of  $\pm$  80 feet altitude. At the 95 percent confidence level the mean of any C-141A fleet aircraft's system should range from 4 feet below to 64 feet above the VSI altitude.

In the approach and landing flight regime, (below 0.4 Mach) the arithmetic mean of the altitude deviation for the systems of the six test aircraft was  $\pm$  46 feet. This exceeded the CADC manufacturing tolerances of  $\pm$  35 feet by 11 feet. At the 95 percent confidence level, the mean of any one C-141A fleet aircraft's system should range from 8 to 84 feet above the VSI altitude.

Altitude Deviation = Altitude System Error (ΔHsys) - CADC
Altitude Design Curve (See figure B3)

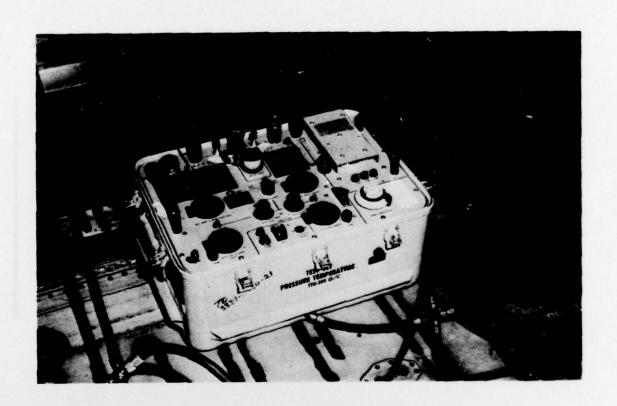
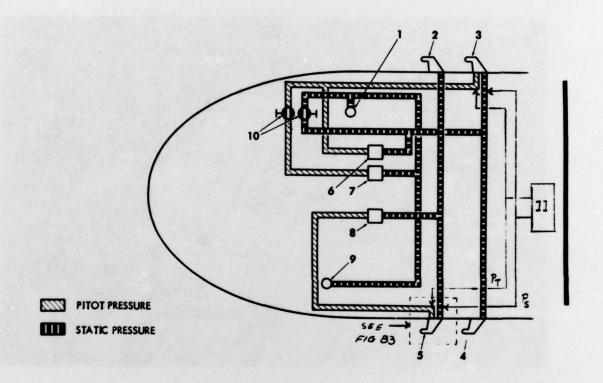


Figure Bl

# PITOT STATIC SYSTEM



- 1. FLIGHT ENGINEER'S ALTIMETER
  2. PILOT'S PITOT-STATIC TUBE (UPPER LOCATION)
  3. COPILOT'S PITOT-STATIC TUBE (LOWER LOCATION)
  4. COPILOT'S PITOT-STATIC TUBE (UPPER LOCATION)
  5. PILOT'S PITOT-STATIC TUBE (LOWER LOCATION)
  6. COPILOT'S CENTRAL AIR DATA COMPUTER

- 7. FLIGHT DATA RECORDER
  8. PILOT'S CENTRAL AIR DATA COMPUTER
  9. NAVIGATOR'S ALTIMETER
- 10. MANUAL SHUTOFF VALVES
- 11 TTU-205 (GEOUNS TEST ONLY)

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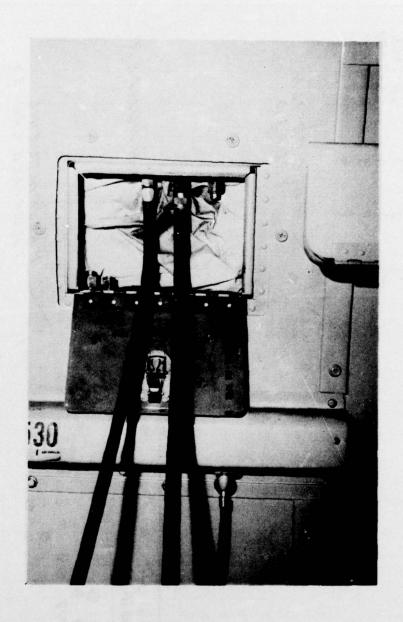


Figure B3 Pitot-Static System Drain Caps

