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ABSTRACT

A computer program called TRIBRID is described which can rapidly calculate the smooth water resistances of some advanced bibrid and tribrid ship concepts that are supported by buoyant, dynamic, and powered aerostatic forces. These forces are produced by one or more hull-strut combinations similar to a demi SWATH in conjuction with large hydrofoils and/or air cushions. For a given displacement and shape, the size of each concept is determined and various drag components along with some interference drag are then calculated for a calm water, fixed zero trim and free to heave operating condition.

INTRODUCTION

The primary intent of this report is to describe the TRIBRID computer program which can quickly calculate the smooth water resistance of some of the advanced hybrid ship concepts investigated by J. Meyer (Reference 1) and D. Jewell and of many possible and foreseeable modifications of these concepts. The terms bybrid and tribrid refer to a ship which is supported by a combination of buoyant, hydrofoil, and powered air cushion generated lift. Bibrid vehicles have two of the above support modes and tribrids have three.

The computer program was initially developed for the Hydrofoil Small Waterplane Area Ship (HYSWAS) and has been expanded to handle the Small Waterplane Area Air Cushion Ship (SWAACS) and many variations of the Small Waterplane Area Twin Hull (SWATH) ship with air cushion and/or hydrofoil support. In addition, the program may be used, with some modification, for predicting some of the calm water drag components of the Hydrofoil Air Cushion Ship (HYACS) and the Large Hybrid Hydrofoil Ship (LAHHS). Figure 1 shows some of these concepts.

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TRIBRID PROGRAM DESCRIPTION

The TRIBRID program was written to quickly estimate the resistance of hybrid and tribrid ship concepts which depend on buoyant, dynamic or air cushion sustention devices. The buoyant displacement is derived from a slender body of revolution (called a hull in this report) operating under the free surface and also from a low aspect ratio strut situated on top of the body and piercing the free surface. The dynamic lift is due to very large subcavitating foils moving through the water, and the air cushion lift is derived from pressure supplied by powered fans aboard the ship. The hull-strut combination can be used singly, in pairs as in a catamaran or in triplets as in a trimaran. The foils may be cantilevered from the hull or strut like the wings of an airplane or they may span two adjacent hulls or struts depending on the desired arrangement. The air cushions utilize the struts as side seals and they may be placed between adjacent struts. The resistance of a large mumber of possible hull-strut, foil and cushion arrangements can be evaluated by the TRIBRID program. A few of these arrangements are shown in the TRIBRID program input section of this report.

Existing equations and computer programs which were available at the inception of the project were gathered to predict the drag components associated with the foils, air cushions and hull-strut combinations and were incorporated into the TRIBRID program. In the area of foil wave drag and the wave drag of flared struts no suitable existing program was found.

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A subroutine was written to evaluate the wave drag of large foils operating at shallow submergences and an existing computer program was modified to take into account the effect of strut flare on the wavemaking drag of the hull-strut combination. Since it was not the intent of this project to develop new technology, a number of foreseeable interference effects between the foils, hull-strut combination, and air cushions along with some other drag components have not been evaluated. A complete list of anticipated drag components that are not evaluated is found in the section on the limitations of the TRIBRID program.

Since some drag components are not accounted for by the TRIBRID computer program, it is inadvisable to make resistance comparisons between a concept evaluated by the TRIBRID program and an already existing ship whose resistance is known. The TRIBRID program neglects certain resistances and therefore the comparison of the resistance generated by TRIBRID to a known ship resistance must be considered speculative to a certain extent.

Approximate methods are used (See the Appendices for details) for the computation of the various drag components. Hard data are not available to verify the validity of most of these formulations. It is thus conceivable that the ranking of widely different concepts based solely on these powering-performance computations may not be born out in reality. For example, if one compares a concept having mainly dynamic-lift sustension with another that is mainly cushion-supported,

an error in the relative ranking could be caused by the overpredicted cushion drag. Additional error in the ranking can be introduced if non-optimum versions of the concepts are used to represent each component.

It should be emphasized here that the TRIBRID program deals only with resistance and powering. Powering is addressed superficially, and only because it is necessary to calculate the total required power for valid comparisons between cushion and non cushion concepts. An assumed fan efficiency, duct efficiency, propulsive coefficient and the calculated effective power and fan ideal power are used to determine the total required power.

The feasibility of a configuration is not examined with regard to propulsor sizing or propulsor efficiency calculations, nor are any basic Naval Architectural feasibility questions with regard to static stability, motions, manuevering, structures, machinery arrangement, fuel and payloads investigated.

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TRIBRID PROGRAM INPUT

The required input to run the TRIBRID program consists of the following data cards. Numbers in [brackets] are SI unit conversion factors. (i.e., quantity in British Unit x Conversion Factor \equiv quantity expressed in SI units.)

- Card 1 12A6 Format
- Columns 1-72 Enter concept name or title
- Card 2 8F10.6 Format Constants
 - Columns 1-10 RHO density of water slugs/ft³ [515.3788 K_n/m^3]
 - 11-20 GRAV gravitational constant ft/sec² [.3048 m/s²]
 - 21-30 PI Value of pi 3.14159...
 - 31-40 E Logarithmic base 2.71828...
 - 41-50 GAMMA Euler's constant .55721...
 - 51-60 VISC. Kinematic Viscosity of water ft/sec³ [10.76423 m/s³]
 - 61-70 RHOAIR Air density slugs [515.3788 K_g/m^3]

Card 3 8F10.6 Format

Columns 1-10 DELTCF - Correlation coefficient (.0005 for example)

11-20 FKS - Equivalent sand grain diameter-used as a measure of foil roughness - inches [2.54 cm]

Card 4 8F10.6 Format

Columns 1-10 DELTA - Total buoyant displacement at rest. Tons Weight [RHO \times GRAV *0.9910 m³]

| | 11-20 | CWP - Waterplane coefficient of the strut |
|---------|--------|---|
| | 21-30 | CP - Hull prismatic coefficient |
| | 31-40 | <pre>CI - Strut inertial coefficient (see appendix B for definition)</pre> |
| | 41-50 | EXP - Strut flare exponent enter 1.0, 2.0, or 3.0 only. |
| | 51-60 | LCBOLH - Ratio of the hull longitudinal center of buoyancy measured from midships, LCB, to the hull lenoth, LH (Positive=LCB fwd of 沒) |
| | 61-70 | LCFOLS - Ratio of the strut longitudinal center of floatation measured from amidships, LCF, to the strut length, LS (Positive=LCF forward of 效) |
| Card 5 | 8F10.6 | Format (see Figure 2 for a schematic showing of the geometric quantities discussed below) |
| Columns | 1-10 | TZODH - Ratio of the strut thickness, TZ, at strut bottom to horizontal hull diameter, DH |
| | 11-20 | TR - Ratio of the strut thickness, BSH, at the top to the thickness, TZ, at bottom |
| | 21-30 | HSODV - Ratio of strut height, HS, to the vertical hull diameter, DV |
| | 31-40 | DVODH - Ratio of hull vertical dimater, DV, to horizontal diameter, DH |
| | 41-50 | LSOLH - Ratio of strut length, LS, to hull length, LH |
| | 51-60 | DHOLH - Ratio of horizontal hull diameter, DH, to hull length, LH |
| Card 6 | 81 | Format - Concept Configuration Card |
| Column | 5 | NS - Number of struts |
| | 10 | NSH - Number of hull strut intersections |
| | 15 | NH - Number of hulls |
| | 20 | NCUSS - Number of cushions |
| | 25 | NF - Number of foil sets. (NF=2 for tandem foils) |
| | 30 | NFC - Number of foil sections |
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A foil set may consist of one, two, or three sections. A one section foil set is a foil spanning two hulls. A two section foil set consists of two outboard wing foils on a single hull, or on two hulls. A three section foil consists of a center spanning foil between two hulls and two outboard wing foils. See Figure 3 for some of the various possible foil, hull, strut and cushion combinations.

Card 7 8F10.6 Format - VKNOT(I)

Enter the eight desired speeds in knots. [.5144444 m/s] They may be the same speed or different speeds.

Card 8 8F10.6 Format - CPSF(I) [47.88026 Pa]

Enter the eight cushion pressures in pounds/ft² corresponding to the above speeds. Enter zeroes if the concept does not use aerostatic lift.

Card 9 8F10.6 Format

Columns 1-10 LCOLS - Enter the ratio of cushion length to (1.0) strut length

- 11-20 SLOLC Enter the ratio of the combined forward (0.5) and aft seal length to cushion length
- 21-30 CD Enter aerodynamic drag coefficient for the (0.3) craft

31-40 HEOLS - Enter the ratio of the average super- (.06) structure height, HE, to strut length

Card 10 8F10.6 Format - SODH(I) ft. [.3048 m] - See Figure 2 Enter eight ratios of the centerline separation distance SEP, between adjacent hulls to the horizontal hull diameter, DH. For single



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FIG. 3 SCHEMATIC OF SHIP CONFIGURATIONS

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NOTES ON FIG. 3

- 1) CONFIGURATIONS ARE NOT DRAWN TO SCALE
- 2) ALL HULLS, STRUTS, WING FOILS, AND CENTRAL FOILS MUST BE INDENTICAL WHEN MORE THAN ONE IS USED IN A CONFIGURATION
- 3) THERE ARE OTHER CONFIGURATIONS USING A COMBINATION OF HULLS, STRUTS, FOILS AND CUSHIONS THAT CAN BE EVALUATED BY THE TRIBRID PROGRAM

FIG. 3 SCHEMATIC OF SHIP CONFIGURATIONS

hull-strut concepts enter zeroes. For catamaran and trimaran type concepts SODH must be greater than 1.0. For trimaran concepts, SODH is the ratio of the distance between the centerlines of the center hull and the side hull to the horizontal hull diameter.

Card 11 8F10.6 Format - CSTRUT(I) ft. [.3048 m]

Enter eight values of the longitudinal distance in ft. between the centerline of strut and centerline of hull. (+ is fwd of hull centerline)

Card 12 8F10.6 Format

Columns 1-10 FAC - Foil average chord ft. [.3048 m]

- 11-20 FATC Foil average thickness to average chord ratio
- 21-30 WTB Foil wing tip to body distance ft. [.3048 m] if NFC on card 6 is 1 then set WTB equal to zero.
- 31-40 AZ Foil lift curve slope. Change in foil lift coefficient per angle of attack in degrees
- 41-50 FDIST Tranverse distance in ft [.3048 m] between the tip of a central foil section and the body centerline. For a central foil at the bow or stern, FDIST is zero.
- 51-60 FVDIST Vertical distance in ft [.3048 m] between the centerplane of a central foil and/or wing foil and the hull axis.

Card 13 Format 810.6 -FLOAD(I) Enter eight values of foil loading corresponding to the eight speeds on card 7. Units are $\frac{1b}{ft^2}$ [47.88026 Pa] Enter zeroes if the craft has no foils.

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Card 14 8F10.6 Format - ETAPC

Enter 8 propulsive coefficients corresponding to each of the speeds on card 7. ETAPC must be greater than 0.

Card 15 8F10.6 Format - ETAF

Enter eight fan efficiencies corresponding to each of the speeds on card 7. ETAF must be greater than 0.0.

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Card 16 8F10.6 Format - ETAD

Enter eight duct efficiencies corresponding to each of the speeds on [.] card 7. ETAD must be greater than 0.0.

Card 17 815 Format

Columns 1-15 NSTART - Enter 99999 if another concept is being run and insert cards 1-17 for new concept. Enter zero for the last case or if only one case is run.

SUMMARY OF CALCULATED LIFT & DRAG COMPONENTS

The following is a list of the lift and drag components evaluated by the TRIBRID program.

<u>HULL</u> - consists of a slender body of revolution below the free surface. The calculated lift and drag components are:

- A) Buoyant lift
- B) Friction drag
- C) Eddy drag
- D) Wave making drag
- E) Wave making interference drag between hull(s) and struts(s)
- <u>STRUT</u> The strut connects the upper superstructure or cross-structure of a concept with the hull. It is long and slender and may be wall sided or flared.
 - A) Buoyant lift
 - B) Friction drag
 - C) Eddy and/or tip drag (Tip drag is calculated only for concepts that have no hull under one or more of the struts)
 - D) Wave making drag

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- E) Wave making interference drag between strut(s) and hull(s)
- <u>FOIL</u> The foil has a subcavitating section shape and is attached to the hull or strut like a wing. The foil can also span two hulls or struts.

- A) Dynamic lift
- B) Buoyant lift
- C) Friction drag (See Appendix A for the calculation of the foil friction coefficient which is expected to be high due to roughness and fouling resulting from long periods of foil submergence)
- D) Induced drag
- E) Wave making drag
- F) Eddy making drag

<u>AIR CUSHION</u> - The air cushion is contained between two adjacent struts and fore and aft seals. ~~ ** -R. -

- A) Cushion aerostatic lift
- B) Wave making drag
- C) Seal drag
- D) Momentum drag
- E) Fan ideal power (calculated for purposes of comparing cushion and non cushion craft)

SUPERSTRUCTURE - The aerodynamic pressure drag is calculated.

The equations for calculating the above listed lift and drag components are presented in appendices A, B, and C. These appendices correspond to the modular subroutines in the TRIBRID computer program which evaluate foil system performance, hull-strut performance and cushion system performance. Each of the appendices has its own list of symbols identical to the symbols in the original reference sources.

The subroutine corresponding to each appendix is designed so that it can easily be replaced by a new subroutine describing the performance of a different lift device that might be employed on a future concept. In fact, the present TRIBRID program was developed this way from a January 1975 computer program that had the capability of evaluating concepts only with buoyant and dynamic support and no air cushion support.

TRIBRID PROGRAM OUTPUT

Three pages of output are generated by the TRIBRID program. The first contains quantities which do not vary with speed such as displacement, hull, strut, foil and cushion dimensions, foil lift curve slope and number of hulls, struts, foils and cushions. The various hull, strut, foil, cushion and superstructure drag components for maximum of eight specified input speeds are printed in tabular form on the second page in English Units and on the third page in SI Units. The tables also include the following.

- Assumed propulsive coefficient, fan efficiency, and duct efficiency. These efficiencies are needed in order to compare the total power required by craft with air cushion support to craft without air cushion.
- Buoyant, dynamic and aerostatic lift expressed as a percentage of the total craft weight. The percentages are calculated in order to place each concept on the sustension triangle proposed by Jewel (Reference 2).
- c) Cushion pressure specified for each speed.
- d) Strut wetted surface, strut draft on the cushion side, and the total draft these are all quantities which change with the heave of the craft.
- e) Fan flow rate depends on cushion pressure us well as on speed.
- f) Foil loading pressure prescribed by the user.
- g) Foil angle of attack and foil lift coefficient. The program can generate foil angles beyond stall if the foil loading specified is too high for a particular speed. The user should check that the foil angle and foil lift coefficient are below the stall values. If not, the loading should be decreased.
- h) Sum of the drag components calculated
- i) Effective power

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- j) Fan ideal power
- k) Total shaft power the total shaft power is the sum of the effective power divided by the propulsive coefficient plus the fan ideal power divided by the product of the fan and duct efficiences.

A sample computer output is shown in Figure 5. The sample is for a twin-hull, foil and cushion supported concept, the midship section of which is shown in Figure 4. The sample output is included for illustrative purposes only and not for making any evaluation of the concept.



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000 000 05 10 15 20 25 30 35 40 45 990 961 912 841 759 638 502 351 199 989 956 902 8827 734 5625 501 366 221 APPLICABLE 2.0 FT. HEIGHTS FROM THE STRUT MULL INTERSECTION. 8.00 10.00 12.00 14.00 16.00 14.00 20.00 22.00 24.00 1.06 1.10 1.14 1.19 1.25 1.32 1.39 1.47 1.56 ٩S NUMBER OF HULLS STATION +.5 IS AT THE BOW OF THE STRUT OR HULL NUMBER OF FOIL SECTIONS= - Comput >>> Output for Sample Case 396.223 CUBIC METERS STATIONS --50 --45 --40 --35 --30 --25 --20 --15 --10 --05 0.00 STRUT OFFSETS -000 -190 -351 -502 -636 -750 -941 -912 -961 -990 1-000 HullL OFFSETS -000 -221 -366 -501 -625 -734 -827 -902 -956 -989 1-000 NUMBER OF S-H INTERSECTIONS EXAMPLE CASE 92.133 WETERS 64.493 WETERS 4.607 WETERS 4.607 WETERS 6.910 WETERS 7.764 WETERS 7.164 WETERS LCF/LH = -0.000 LCF/LS = -0.000 EXP = 2.000 NUMBER OF FOIL SEIS= 1535. SO.WETERS -000059 CM. 1.83 METERS 0.00 METERS 0.00 METERS 5.49 METERS STRUT THICKNESS OFFSETS AT WIDSHIPS,NOWMALIZED ON IZ AT HFIGHTS FROM S-H INTERSECTION 0.00 2.00 4.00 6.00 NORMALIZED THICKNESS OF STRUT 1.00 1.00 1.02 1.04 NOPWALIZED HULL AND STRUT OFFSETS. STATION -.5 IS AFT. THIN HULL TRIRRIN WITH FOIL AND CUSHION SUPPORT 4000.000 FONS 372.273 FEET = 92 211.591 FFET = 64 15.114 FFET = 64 13.605 FFET = 64 • 700 • 700 • 050 • 050 • 050 • 050 • 060 • 060 ഹ FIGURE .033 HULL PPISMATIC COEFF. HULL-STRUT Watfrplane Apea Coeff. CP = .666 Watfrplane Apea Coeff. CV = .666 Waterplane Inertia Coeff. CI = .033 • 001600 IN. = • 001600 IN. = • 0.00 FEET= • 0.00 FEET= 19.00 FEET= FOIL AVARAGE THICKNESS/CHORD RATIO FOIL LIFT CURVE SLOPE (CL/DEG) FOIL LIFT CURVE SLOPE (CL/DEG) HARTZ, HULL DIA. / HULL LFVGTH VFRT. HULL DIA./HORI7. HULL DIA. 5TRUT HEIGHT / VERT HULL DIA. SFAL LENGTH / CUSHION LENGTH SUPERSTRUCTURE HEIGHT / STRUT LENGTH SUPERSTRUCTURE HEIGHT / STRUT LENGTH AFRODYNAMIC DRAG COFFICIENT SOF T= II 41 H H н 11 11 11 0 16527. ţ1 nrsplacement nflatte (the form of the fo -CORRELLATION COEFFICIENT HULL WETTED SURFACE = FOIL EQUIV. ROUGH. = FOIL EQUIV. ROUGH. = CENTER FOIL-HULL CL.= FOIL BELOW HULL AXIS= WING FOIL-HULL CL. = NUMPER OF CUSHIONS = VUMBER OF STRUTS

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| EXAMPLE CASI 30.00 .500 .500 | 80.31 4.87 14.81 | 2066.81 1136.15 9.36 592.20 194.65 4000.00 | 63161.23 4217.03 47189.32 308.52 36161.48 | 31465.94 725398.31 113556.63 26545.16 14710.61 14777.81 | 15458.54 11502.69 809.84 1969.30 | 1762.91 986.79 14211.49 2927.57 | 75.00 90.68 11817.03 13.38 29.66 29.66 6728.93 | 576.00 760.09 2.46 .22 | <pre>c53121.17 50921.34 917.58 i04464.34</pre> |
| SUPPORT 25.00 .500 .500 | 84.82 3.39 11.79 | 2066.81 1316.46 1316.46 471.61 135.70 135.70 | 44853.13 2928.50 28594.45 223.23 223.23 | 14180.25 134505.89 76282.73 40966.69 9549.79 44319.15 | 5987.44 8208.03 520.52 1238.69 | 1204.21 713.12 9869.09 2033.03 | 60.00 90.68 13603.72 15.60 31.65 5190.02 | 400.00 760.09 2.46 | 462873.02 35510.78 566.18 72639.22 |
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| WITH FOIL 15.00 .500 .500 .700 | 92.94 1.22 5.84 | 2066.81 1641.37 9.38 233.58 48.90 4000.00 | 17210.87 1054.26 18137.04 89.00 10578.50 | 119.04 13321.35 -2222.20 -1247.06 -66.58 925.76 | 282.01 3194.13 163.78 367.64 | 190.10 270.35 3552.87 731.89 | 30.00 90.68 16639.46 19.43 35.01 2721.64 | 144.00 760.09 2.46 .73 | 66652.75 3068.09 148.45 6560.32 |
| LL TPIBRID 10.00 .500 .500 | 96.55 •54 2.91 | 2064.48 1787.48 9.37 9.37 116.22 21.79 4000.00 | 8057.06 468.56 469.16 42.46 487.37 | 1.91 1264.37 88.81 -132.00 -23.71 | 30.89 1512.94 66.92 148.49 | 4.87 122.75 1579.05 325.29 | 15.00 90.68 17950.27 21.09 316.44 1668.23 | 64.00 760.09 2.47 2.23 | 27614.53 847.41 45.50 1824.82 |
| VFLOCITY ASSUMED PROPULSIVE COEFFICIENT ASSUMED FAN EFFICIENCY ASSUMED DUCT EFFICIENCY | RUOYANT PERCENT LIFT Dynamic Percent Lift Aerostatic Percent Lift | HULL BUOYANT LIFT STRUT BUOYANT LIFT FOIL BUOYANT LIFT CUSHION AEPOSIATIC LIFT FOIL DYNAMIC LIFT TOTAL LIFT | HULL FRICTION DAAG HULL EODY DRAG Strut Friction drag Strut Eddy And/or Tip Drag Roughness Allowance | HULL WAVE DRAG STRUT WAVE DRAG HULL-STRUT INTERFERENCE WAVE DRAG STRUT CROSS-INTERFERENCE WAVE DRAG HULL CROSS-INTERFERENCE W//E DRAG HULL-STRUT CROSS-INTERF. W1VE DRAG | CUSHION WAVE DRAG Cushion Seal Dpag Cushion Mowentuw Drag External Aerodyyamic Jrag | FOIL WAVEMAKING DPAG Foil Induced DPAG Foil Friction D2AG Foil Eddy DRAG | CUSHION PRESSUPE HULL CENTERLINE SEPERATION Strut Witted Surface Strut Draft on Cushion Side Total Draft Fan Flow Rate | FOIL LOADING Foil Planform Affa Foil Angle of Attack Deg. Foil Lift Coefficient (Dynamic) | SUM OF DRAG COMPONENTS CONSIDERED Effective Power (PE) Fan Ideal Power Total Shaft Power |

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FIGURE 5 - Computer Output for Sample Case

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LIMITATIONS OF THE TRIBRID PROGRAM

The following lift and drag components are not evaluated by the TRIBRID program:

1) Any wavemaking interference drag between

- a) foil and hull
- b) foil and strut
- c) foil and cushion
- d) cushion and hull
- e) cushion and strut
- 2) Any boundary layer type interference drag, for example; any change in foil lift or drag due to operating a part of the foil in the hull boundary layer is not accounted for.
- 3) Drag due to any part of the ship above the struts coming in contact with the water. This is especially important in the low speed drag prediction for the HYSWAS concept which relies on the upper hull for static roll stability prior to take-off. The upper hull must be in the water until sufficient speed is attained for the foils to provide roll stability. The resistance of the upper hull is not evaluated; the magnitude of expected HYSWAS hump drag at take-off will depend upon the design of the upper hull and the proportions of buoyancy and dynamic lift selected for a particular design.
- Any drag or lift due to cavitation and/or ventilation of the foils, strut or any other part of the ship. Fully wetted flow is assumed.
- 5) Drag due to a non zero trim, yaw or roll angle. The TRIBRID program assumes that the craft has zero trim, zero yaw and zero heel attitude. No moment or equilibrium calculations are performed.

- 6) Drag due to the sinkage of the hull caused by dynamic forces
- Lift and Drag generated by control surfaces such as rudders or small foils.
- Appendage drag due to shafting, bosses, shaft supports or other appendages
- 9) Rough water drag. Only smooth water performance is considered.
- 10) Spray drag

CONCLUSIONS AND RECOMMENDATIONS

The TRIBRID computer program is a useful tool for quickly calculating the resistances of many advanced ship concepts. The program is limited in that no hard full scale data exist to verify some of the drag component predictions. In addition, certain forseeable interference drags are neglected because there is no accurate way of calculating them. It is strongly recommended that resistance experiments be performed as a concept in order to predict its resistance with greater confidence.

Additional research and development is needed to improve the powering prediction capability of the TRIBRID program. At present there is no acceptably accurate tool for estimating the drag of the following drag components: hull-foil-cushion wavemaking and viscous interference drag, the drag due to cavitation and/or ventilation of the foils and struts, spray drag of the strut and the wavemaking drag of the unconventional upper hulls.

ACKNOWLEDGMENTS

The author wishes to thank Dr. Michael B. Wilson of DTNSRDC (Code 1532) for the foil wavemaking resistance program and Dr. Arthur M. Reed of DTNSRDC (Code 1524) for the hull strut wavemaking resistance program and Elízabeth Waksmunski for the typing and help in the preparation of this report.

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APPENDIX A

1.00

FOIL SYSTEM PERFORMANCE

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LIST OF SYMBOLS FOR APPENDIX A

| AR | aspect ratio of hydrofoil = (2b) ² /s |
|--------------------|---|
| B(k) | modified complete elliptic integral |
| | B(k)=1/2[E(k)-(1-k) ² K(k)] |
| ° _f | foil friction coefficient based on total wetted surface |
| D | total foil drag =D _i +D ₄ +D _E +D _F |
| D _E | foil eddy making drag |
| D _F | foil friction drag |
| D _i | foil induced wave |
| D ₄ | foil wave making drag |
| E(k) | complete elliptic integral of the second kind of argument (k) |
| J _n (z) | Bessel function of the first kind of order n |
| K(k) | complete elliptic integral of the first kind of argument (k) |
| L | total foil lift = $L_0 + \Delta L_1 + \Delta L_2 + L_B$ |
| L _B | lift due to static buoyant displacement of foil |
| L _o | aerodynamic value of foil lift |
| R | g/U ² |
| Rcav | reynolds number based on average foil chord |
| S | plan area of the foil |
| U | free stream velocity |

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| αa | absolute angle of attack, measured from the free stream to the zero-lift direction |
|------------------|--|
| ^a e | slope of the lift coefficient curve |
| b | half span of the foil |
| c _{avg} | average chord length of elliptic planform foil |
| c(y) | chord length of the foil c(o)≡c _o |
| g | gravitational acceleration constant |
| h | depth of submergence of foil measured from trailing edge to mean free surface |
| ^t avg | average thickness of elliptic planform foil |
| t(y) | thickness of foil t(o)≡t _o |
| β | Froude number with respect to b |
| Г(у) | distribution of the circulation strength r(o)≡r _o |
| ξ | elevation of the disturbed free surface |
| ρ | water density |
| σ | Froude number with respect to $h=\frac{U^2}{gh}$ |
| λ | depth - 1/2 span ratio =h/b=β/σ |
| γ | Euler's constant 0.5772 |
| ۵۲ | lift do to presence of free surface |
| ΔL ₂ | lift due to wave effects |

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APPENDIX A - FOIL SYSTEM PERFORMANCE

The foil prediction method is based upon lifting line theory with linearized free surface assumptions as outlined in Reference 3 which considers a hydrofoil of finite span moving with constant velocity at a fixed distance below the surface. See Figure 1A.



Fig. 1A- Coordinate system for the hydrofoil motion.

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The details of the general formulation of the problem, the boundary conditions used and the solution of the Laplace equation are presented in Reference 3 and will not be repeated here.

All the following equations for foil performance are applicable to

a foil with elliptical distribution of the circulation strength Γ as given by equation 1A. The equation numbers in brackets are the equation numbers as they appear in Reference 3.

$$\Gamma(y) = \Gamma_{0} \sqrt{1 - \frac{y^{2}}{b^{2}}}, \quad |y| \le b,$$

$$\Gamma(y) = 0, \qquad |y| \ge b.$$
(1A)

The lift and drag equations are presented in terms of a depth Froude number $\sigma,$ a span Froude number β and a 1/2 span-depth ratio $\lambda.$ as shown in equation 2A and 3A

$$\sigma = \frac{1}{hR} = \frac{U^2}{gh}$$
(2A)

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$$\beta = \frac{1}{bR} = \frac{U^2}{gb}, \quad \frac{\beta}{\sigma} = \frac{h}{b} = \lambda.$$
 (3A)

The equations for lift are:

$$L = L_0 + \Delta L_1 + \Delta L_2 + L_B$$
 (4A)

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$$L_{o} = \rho U \Gamma_{o} \int_{-b}^{+b} \sqrt{1 - \frac{y^{2}}{b^{2}}} dy = \frac{\pi}{2} \rho U \Gamma_{o} , \qquad [70] \qquad (5A)$$

$$\Delta L_{1} = -\frac{\rho r_{0}^{2}}{3\pi\lambda} \left\{ 1 - 3\lambda^{2} \left[\log 2 - \frac{3}{4} + \frac{5}{8} \log \frac{\sqrt{1 + \lambda^{2}}}{\lambda} \right] \right\}$$
$$+ \Omega(\lambda^{4} \log \lambda) \text{ as } \lambda + \Omega \qquad [78a] \quad (6A)$$
$$\Delta L_{2} = \frac{\rho r_{0}^{2}}{4\sqrt{2}} r(\frac{1}{4}) \left[1 - \frac{r(\frac{3}{4})}{\sqrt{\pi}r(\frac{1}{4})} - \frac{\lambda}{\sqrt{1 + \lambda^{2}}} \right].$$

$$\left[1 + \sqrt{\frac{2}{\pi\sigma}} \left(\gamma + \log \frac{2}{\sigma}\right)\right] \left(1 + O(\lambda^2, \frac{1}{\sigma}) \quad [80] \qquad (7A)$$

 L_0 is the aerodynamic value for a foil in an infinite medium. L_1 is independent of gravitational effects and represents the lift due to the mean free surface. L_2 is the lift caused by surface wave effects. L_B represents the static buoyant foil lift and is calculated from the displaced foil volume. The foil is assumed to be elliptic in planform with a constant thickness to chord ratio as shown in Figure 2A





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The drag equations are:

$${}^{D=D}1^{+D}2^{+D}3^{+D}4^{+D}E^{+D}F$$
(11A)

$$D_{1} = \frac{\pi \rho \Gamma_{o}^{2}}{4} \int_{0}^{\infty} \frac{J_{1}^{2}(\mu b)}{\mu} d\mu = \frac{\pi \rho \Gamma_{o}^{2}}{8}; \quad [60] \quad (12A)$$

$$D_{2}+D_{3} = \frac{\pi \rho \Gamma_{o}^{2}}{4} \int_{0}^{\infty} e^{-2h\mu \frac{J_{1}^{2}(\mu b)}{\mu}} d\mu \qquad [61] \qquad (13A)$$

$$= -\frac{\pi\rho\Gamma_{o}^{2}}{8} \left\{ 1 - \frac{4}{\pi} \lambda \sqrt{1+\lambda^{2}} \left[K \left(\frac{1}{\sqrt{1+\lambda^{2}}} \right) - E \left(\frac{1}{\sqrt{1+\lambda^{2}}} \right) \right] \right\}$$

$$D_{4} = \pi_{\rho}\Gamma_{0}^{2}\int_{0}^{\pi/2} e^{-\frac{2}{\sigma}\sec^{2}\theta} \left[\frac{J_{1}(\frac{1}{\beta}\sec^{2}\theta\sin\theta)}{\sec^{2}\theta\sin\theta}\right]^{2} \sec^{5}\theta d\theta$$
(14A)
[63]

 D_1 is the induced drag due to the trailing vortices of the hydrofoil. The combination of D_2+D_3 repesents the total contribution of the mean free surface effect which favorably decreases the total drag especially when h is small. As h tends to zero, D_2+D_3 cancells D_1 . D_4 represents the wave drag due to the downstream wave formation which results from the gravity effect. In equation 13A,K(k) and E(k) denote the complete elliptic integral of the first and second kind respectively and are evaluated by the NSRDC Mathematics Laboratory library function CELLI. The integral portion of equation 14A is evaluated using standard numerical techniques.

 $\rm D_{\rm F}$ represents the viscous friction drag and is given by equation 15A.

$$D_{F} = C_{f} \frac{\rho U^{2}}{z} (4 C_{avg} b) \quad \text{where} \quad (15A)$$

c is the average chord length and the quantity (4 c b) spresents the avg total wetted surface of the foils.

 C_{f} is the foil friction drag coefficient for hydraulically smooth foils. C_{f} is given by the Schoenherr friction line as given in equation 16A Reference 6

$$\frac{0.242}{\sqrt{C_f}} = \log(R_{cav}C_f)$$
(16A)

where R_{cav} is the Reynolds number based on the average foil chord length. For foils which are not hydraulically smooth, the foil friction coefficient is given by equation 17A Reference 6

$$C_{f} = (1.89 + 1.62 \log (\frac{c_{avg}}{Ks})^{-2.5})$$
 (17A)

where Ks is the equivalent sand grain diameter and is used as a measure of the foil roughness. The larger value of C_f as predicted from equations 16A and 17A is used.

Values of Ks from References 4 and 5 for different surfaces are presented in the following table.

SURFACE

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EQUIVALENT SAND GRAIN DIAMETER Ks INCHES[2.54 cm]

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| mirror | 0 - | .00008 |
|-------------------------------|----------|--------|
| polished metal or wood | .00008 - | .00016 |
| natural sheet metal | .00016 - | .00032 |
| optimum paint sprayed | .00032 - | .00048 |
| average paint sprayed | .00048 - | .00159 |
| mass production paint sprayed | .00159 - | .016 |
| newly launched ships | .012 | |
| camouflage paint on airplanes | .003 | |

The value of Ks that is selected depends upon how the hydrofoil is used. Hydrofoils which retract out of the water and are unpainted will have Ks values near those given for natural sheet metal. Daily cleaning could even reduce these values. Hydrofoils which are generally kept submerged will probably have a Ks value in the range given for mass production paint spayed surfaces. Fouling of the foil surface will increase the Ks values substantially above that of the mass production spray painted surface.

 $\rm D_{\rm E}$ represents the eddy making drag and is given by Equation 18A (See Reference 6.

$$D_{E} = D_{F} \left(2\frac{t_{avg}}{c_{avg}} + 60(\frac{t_{avg}}{c_{avg}})^{4}\right)$$
 18A

where t_{avg} and c_{avg} are the average thickness and chord of the foil. The above euqations for D_1 , D_2 , D_3 , D_4 , $L_0 \Delta L_1$, and ΔL_2 are all expressed in terms of r_0 , the circulation strength at y=0. For the assumed elliptic circulation, r_0 is expressed by equations 19A, 20A, and 21A.

$$\Gamma_{0} = \frac{\frac{1}{2} \cdot U \cdot c_{0} \cdot \alpha_{a} \cdot a_{e}}{1 + \frac{1}{4} \cdot \frac{c_{0}}{b} a_{e} \left[f_{2}(\lambda, \sigma) + \frac{2}{\pi} \alpha_{a} f_{1}(\lambda, \sigma) \right]}$$
[93a] (19A)

where

$$f_{1}(\lambda,\sigma) = \frac{B_{\sqrt{1+4\lambda^{2}}}^{\prime}}{4\lambda\sqrt{1+4\lambda^{2}}} + \frac{2B_{\sqrt{1-4\lambda^{2}}}^{\prime}}{\sqrt{2\lambda}(1+4\lambda^{2})^{1/4}} + \left[1 + \sqrt{\frac{2}{\pi\sigma}}(\lambda+\log\frac{2}{\sigma})\right] + O(\frac{1}{\sigma})$$

$$[93b] = (204)$$

and

$$f_{2}(\lambda,\sigma) = \left[1 - \frac{\lambda}{\sqrt{1+4\lambda^{2}}}\right] \cdot \left[1 + 0\left(\frac{1}{\sigma}, \frac{1}{\beta}\right)\right]$$
 [93c] (21A)

The above equations for foil lift and foil drag are used in the FOIL subroutine of the TRIBRID computer program. They are subject to the following limitations:

- Fully wetted, non cavitating flow exists over the foil surface.
 This limitation is inherent in the linearized lifting line theory.
- b) The foil has elliptical planform. This limitation is the result of assuming an elliptical distribution of the circulation strength. Reference 3 states that for an elliptical distribution of $\Gamma(y)$, the planform is also nearly elliptical and that the sum of the foil drag components D_1 , $D_2 + D_3$, and D_4 is approximately minimum

for a given lift. Reference 4 also recognizes that for a fixed geometrical form the elliptic circ.lation distribution can not be held constant for different values of h. However, the calculation of the induced downwash velocity at the hydrofoil supports the assumption that the same circulation distribution will hold for a wide range of depths.

- c) Foil aspect ratio, AR, is not to be lower that 4.0. It is assumed that the aspect ratio of the hydrofoil is so large that the whole hydrofoil may be replaced by a lifting line. However, experience with airfoils indicates that the lifting line theory can be expected to be sufficiently accurate for foils of aspect ratio AR as low as 4.0.
- d) The foil prediction method is valid for only a certain range of operating depths. The depth-half span ratio λ should be less than 1.0. Equation 6A is an approximation for ΔL_1 which was derived for $\lambda \rightarrow 0$. For values of λ greater than 1 a different equation for ΔL_1 results, which is not presented here because in the TRIBRID program we are not interested in foil performance at depths greater than the half span of the foil. The requirement for fully wetted foil invalidates the performance prediction at zero depth or very small depths where the foil might be planing. Since no prediciton technique for the minimum foil depth at which the foil remains wetted is presented, the establishment of this

minimum is a matter of engineering judgement and experience. Calculations for foil depth to average chord ratios as low as 1/2 yield reasonable results and it is suggested that this value be used for minimum foil depth. APPENDIX B

HULL-STRUT-SUPERSTRUCTURE PERFORMANCE

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| A,A _n | Chebychev coefficients for hull and strut |
|------------------|--|
| AF | frontal area of ship |
| ARC | arc length along midship section of strut (see Fig 1B) |
| B,B _n | Chebychev coefficients for hull and strut |
| BSH | maximum thickness at top of strut |
| CD | aerodynamic drag coefficient |
| C _F | friction coefficient |
| CI | strut waterplane inertia coefficient = $I_{yy/T_{max}LS}^3$ |
| СР | hull prismatic coefficient |
| CWP | strut waterplane area coefficient |
| Dareo | aerodynamic drag of the struts and superstructure above water |
| D _H | horizontal hull diameter |
| D _{HE} | hull eddy making drag |
| D _{HF} | hull friction drag |
| D _{HSS} | total drag of the hulls, struts and superstructure |
| D _{RA} | drag due to roughness allowance |
| DSF | strut friction drag |
| DSE | strut eddy making drag |
| D _{tip} | tip drag for strut with no hull underneath |

| DV | vertical hull diameter |
|------------------|--|
| D _W | wave making drag |
| EXP | strut flare exponení |
| HS | strut height (see fig 1B) |
| HWL | strut depth below static water line (ship is 100% buoyant supported) |
| HWS | hull wetted surface |
| I _{уу} | strut waterplane longitudinal inertia about midship |
| LCBOLH | ratio of hull center of buoyancy measured from midship to hull length |
| LCFOLS | ratio of strut center of flotation measured from midship to strut length |
| LH | length of hull |
| L _{HB} | hull buoyant lift |
| LS | length of strut |
| L _{SB} | strut buoyant lift |
| SWS | strut wetted surface |
| T _{max} | maximum thickness of strut at the waterline |
| TZ | midship section strut thickness at strut bottom |
| U | free stream velocity |
| XWL | strut immersed depth at speed |
| g . | gravitational constant |
| ×s | longitudinal strut position forward of midship section |
| × _h | longitudinal hull position forward of midship section |

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| У _S | strut half breadth at any fore and aft location |
|-----------------|---|
| У _h | hull half breadth at any fore and aft location measured in the waterplane through the hull axis |
| ρ _a | density of air |
| ρ | density of water |
| Δ _{CF} | Correlation Coefficient |

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The buoyant lift provided by each hull and each strut is given in Equation 1B and 2B. This buoyant lift is based upon the displacement below an idealized level waterline.

$$L_{HB} = (\pi/4)(DV)(DH)(LH)(CP)_{P}g$$
(1B)

$$L_{SB} = \rho g[(TZ)(XWL) + (\frac{BSH-TZ}{EXP+1})(\frac{HWL^{EXP+1}}{HS^{EXP}})](LS)(CWP)$$
(2B)

The equation for L_{SB} is modified for air cushion supported concepts in order to account for the depressed waterline on the cushion side of the strut.

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FIG. 1B SINGLE HULL-STRUT-SUPERSTRUCTURE GEOMETRY

The drag of the hull-strut-superstructure combination is given by Equation 3B

$$^{D}HSS = ^{D}HF^{+D}SF^{+D}HE^{+D}SE^{+D}RA^{+D}AERO^{+D}tip^{+\Sigma D}W$$
(3B)

The individual component drags are the following. Hull friction drag for each hull is:

$$D_{HF} = C_F \cdot 1/2 \cdot \rho U^2 \cdot HWS$$
(4B)

The hull wetted surface HWS is determined by dividing the hull into 20 segments, calculating the average circumference and slant height of each segment and summing the wetted surface of each segment. The resulting wetted surface area is then corrected by subtracting the area masked by the strut.

The shape of the hull is generated by a series of Chebychev coefficients. The equations for obtaining the hull offsets are presented under the discussion of wave drag since it is the wave drag calculation which requires that the hull be represented by Chebychev coefficients.

The strut friction drag is given by

$$D_{SF} = C_F \cdot 1/2\rho \cdot U^2 \cdot SWS$$
(5B)

and the strut wetted surface SWS is given by

$$SWS = 2((XWL)(LS)+1.33(ARC - XWL))$$
 (6B)

For cushion supported concepts, SWS is corrected for the depressed waterline inside the cushion and for struts with wetted bottoms an additional area equal to (CWP)(LS)(TZ) is included. The hull eddy making drag is given by

$$D_{\rm HE} = 0.0001 \ \rho/2 \ U^2 \ HWS$$
 (7B)

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and it is based on the residuary resistance of deeply submerged bodies of revolution with length to diameter ratios of 10.0 or greater.

The strut eddy making drag (Reference 3) is given by

$$D_{SE} = \left(\frac{2T_{a}vg}{LS} + 100\left(\frac{T_{a}vg}{LS}\right)^{4}\right)SFD$$
(8B)

For struts with wetted bottoms an additional tip drag component D_{tip} is added to the eddy making drag.

$$D_{tip} = 0.0315 \frac{TZ^3}{LS} CWP \rho U^2$$
 (9B)

The roughness allowance is given by

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$$D_{RA} = \Delta_{CF} \rho/2 U^2 (SWS + HWS)$$
(10B)

The sum of the wave making drag components, ΣD_W , is calculated by a computer program written by Lin (Reference 7). This program is based on linearized thin ship theory and assumes incompressible, inviscid potential flow.

The theory also requires that the ship either have a small camber which satisfies the no-cross-flow condition between the SWATH type hulls and struts or that the thickness of each strut be small compared to the separation between the struts.

The wavemaking interference drag components are due to the interference of wave trains formed by the different hulls and struts. Figure 2B shows the wavemaking drag components that are calculated for three different basic configurations. It should be noted that the tripple strut-single hull configuration should have an additional wavemaking drag component included to account for the wavemaking interference between the two outboard struts. This component is expected to be small due to the large distance between the struts and to their relatively small displaced volume at speed when they are expected to be mostly out of the water.

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- wave drag of one strut 1
- Wave drag of one hull
- 3. Hull-strut interference wave drag
- Strut cross interference wave drag 4.
- 5.
- Hull cross interference wave drag Hull-strut cross interference wave drag 6.

FIG. 2B SCHEMATIC DIAGRAM OF WAVE DRAG AND WAVE INTERFERENCE DRAG BETWEEN HULLS AND STRUTS

The computer program for calculating the wave drag requires that the hull and strut shape be defined by a series of Chebychev coefficients. With many Chebychev coefficients (up to 15 have been used) almost any desired hull and strut shape can be generated to within 1% accuracy, however, in order to save computer time, only 3 Chebychev coefficients are used in this report.

The hull Chebychev coefficients A and B are:

 $A_{1} = 4 \cdot CP/PI \tag{11B}$

$$A_2 = 1 - A_1$$
 (12B)

$$B_{1} = 2 \cdot A_{1} \cdot LCBOLH \tag{13B}$$

$$B_3 = B_2 = A_3 = 0.0 \tag{14B}$$

and the strut Chebychev coefficients are:

$$A_{1} = 4 \cdot CWP/PI \tag{15B}$$

$$A_2 = A_1 - 64 \cdot CI/PI \tag{16B}$$

$$A_3 = 1 - A_1 - A_2$$
(17B)

$$B_1 = 2 \cdot A_1 \cdot LCFOLS \tag{18B}$$

$$B_2 = B_3 = 0$$
 (19B)

The equation for calculating the offsets of the strut at any waterline is

$$y_{s}(x)_{s} = \pm y_{ref i \stackrel{\Sigma}{=} 1}^{N} [A_{i} cos[(2i-1)\theta] + B_{i} sin[2i\theta]]$$
 (20B)

 y_{ref} is the half breadth of the waterline at midships and is constant for struts with no flare.

The offset of the hull at a waterline through the axis of rotation of the hull is

$$y_{H}(x)_{H}^{x} \pm \frac{DH}{2} \sum_{i=1}^{N} A_{i} \cos[(2i-1)\theta] + B_{i} \sin[2i\theta]]$$
(22B)



FIG. 3B STRUT OFFSETS (plan view of strut-waterline)

For hull offsets, replace subscript s by h and y_{ref} by $\frac{DH}{2}$ in Figure 3B.

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The aerodynamic drag component \mathbf{D}_{aero} for the parts of the ship above water is given by

$$D_{areo} = CD \cdot \rho_a \cdot U^2 \cdot AF/2$$
(24B)

Reference 6, p. 11-8 presents values of CD = .68 for a passenger liner, 1.22 for a cargo ship and 0.17 for a hypothetical streamlined ship. A CD value between 0.17 and 1.22 is suggested depending on the extent of streamlining.

APPENDIX C

AEROSTATIC LIFT SYSTEM PERFORMANCE

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LIST OF SYMBOLS FOR APPENDIX C

| Acuss | cushion area |
|-------------------|---|
| A _{seal} | total wetted area of the seals |
| C _{FS} | friction coefficient for seal |
| C _{wp} | waterplane area coefficient of each strut |
| D _{mom} | momentum drag |
| D _{seal} | seal drag |
| FB | Froude number based on cushion |
| FIP | Fan ideal power |
| ۶ ۶ | Froude number based on & |
| F ₂ H | Froude number corresponding to hump speed |
| GRAV,g | gravitational constant |
| LC, 1 | cushion length |
| LS | strut length |
| Lstat | aerostatic lift |
| Pc | cushion pressure |
| R | wave resistance of pressure patch |
| SEAL W | width of seal |
| SEP | separation distance between strut centerlines |
| T _{CWL} | maximum strut thickness at the elevation corresponding to the waterline on the cushion side of the strut. |

| V | velocity of pressure patch |
|------------------|--|
| WPAR | wave resistance parameter |
| b | beam of pressure distribution |
| Ŷ | Eulers constant .577 |
| λ | length to beam ratio of pressure patch |
| ρ | water density |
| ^p air | air density |

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AEROSTATIC LIFT

The lift provided by the air cushion is given by:

$$L_{\text{STAT}} = P_{\text{c}} \times A_{\text{cuss}}$$
(1C)

the cushion area is estimated by equation 2C which is exact for any value of LC provided that CWP = 1, and for any value of CWP provided that LC = LS

$$A_{cuss} = LWP * SEP - C_{WP} * LC * T_{CWL}$$
(2C)

The air flow required to maintain cushion pressure is given by equations 3C and 3D. Equation 3C is based on model experimental results and was developed by Mr. Robert A. Wilson of DTNSRDC (Code 1630).

$$FB = U/\sqrt{GRAV * SEALW}$$
(3C)

Q = 1.67 (0.203
$$FB^2$$
 + .15 FB + .247) x SEALW² * $\sqrt{P_c}$ (4C)

The ideal lift power is FIP = $Q * P_c$

DRAG DUE TO AEROSTATIC LIFT

The wavemaking resistance due to the moving cushion pressure patch is estimated using the closed form approximations derived by Ravenscroft in Reference 8. The wave resistance parameter WPAR is given by equation 5C, 6C or 7C depending on the Froude number F_{ϱ} .

WPAR =
$$\frac{16\lambda}{\pi F_{\ell_H}^4} \cdot \frac{F_{\ell_H}^2}{(1+1.6 \ \lambda^{1/4})^2} \{ 3 - \gamma + \ell_n \frac{(1+1.6 \ \lambda^{1/4})^2 F_{\ell_H}^2}{16\lambda} \}$$

$$0 \leq F_{g} \leq \frac{1}{2} F_{g_{H}}$$
(5C)

$$WPAR = e^{-\sqrt{\lambda}} F_{\ell}^{1/4} \sin^{2} \left[\frac{\pi}{2} \left(\frac{F_{\ell}}{F_{\ell}} \right)^{2} + \frac{\lambda}{\pi} \cdot \frac{1}{(F_{\ell} + \frac{4}{5} \lambda^{1/4} F_{\ell})^{2}} + \frac{\lambda}{\pi} \cdot \frac{1}{(F_{\ell} + \frac{4}{5} \lambda^{1/4} F_{\ell})^{2}} + 2\pi \frac{(\tilde{f}_{\ell} + \frac{4}{5} \lambda^{1/4} F_{\ell})^{2}}{4\lambda} + 2\pi \frac{(\tilde{f}_{\ell} + \frac{4}{5} \lambda^{1/4} F_{\ell})^{2}}{4\lambda} + \frac{1}{2} F_{\ell} +$$

WPAR =
$$e^{-\sqrt{\lambda}} F_{\varrho}^{1/4} \sin^2 \left[\frac{\pi}{2} \left(\frac{F_{\varrho H}}{F_{\varrho}} \right)^2 + \frac{\lambda}{4\pi} \cdot \frac{1}{F_{\varrho}^2} \left\{ 3 - \gamma + \ln \left(\frac{F_{\varrho}^2}{\lambda} \right) \right\};$$

$$\frac{4}{5} \frac{1}{4} F_{g_{H}} \leq F_{g}$$
(7C)

The primary hump $\ensuremath{\text{Er}}\xspace^{\ensuremath{\text{cu}}\xspace}_{H}$ is estimated by Equation 8C

$$F_{\ell_{\rm H}} = \sqrt{\frac{1}{\pi} + .01745\lambda^2} .$$
 (8C)

The wave resistance due to the moving pressure patch is given

$$R = WPAR \times 4 P_{c}^{2} b/(*GRAV).$$
 (9C)

The momentum drag associated with the lift system is simply given by

by

$$D_{mom} = U \cdot \rho_{air} \cdot Q \tag{10C}$$

where Q is given by Equation 4C and the seal drag based on flat plate friction is given by $\ensuremath{\mathsf{P}}$

$$D_{\text{seal}} = C_{FS} \cdot \rho \cdot U^2 \cdot A_{\text{seal}}$$
(11C)

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