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**MODIFICATION TO MATH MODEL FOR SMALL
INDEPENDENT ACTION FORCES (SIAF)**

TRW Systems Group

Prepared for:

**Advanced Research Projects Agency
Army Missile Command**

15 December 1973

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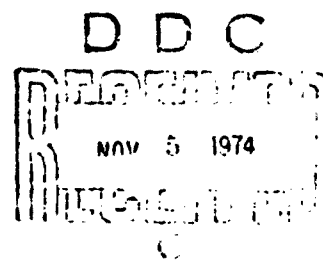
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MODIFICATION TO MATH MODEL FOR
SMALL INDEPENDENT ACTION FORCES (SI AF)
FINAL REPORT

15 December 1973
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MODIFICATION TO MATH MODEL FOR SMALL INDEPENDENT ACTION FORCES (SIAF) FINAL REPORT

INTRODUCTION

This document, prepared by TRW Systems Group, One Space Park, Redondo Beach, California, constitutes the final technical report on the "Modification to Math Model for SIAF" program. This program was conducted under ARPA/AMICOM Contract Number DAAH01-73-C-0914 during the period 25 May 1973 to 31 December 1973. The original study sponsor was the USACDC Systems Analysis Group. Shortly after the start of the work, cognizance was transferred to the U. S. Army Infantry School. The principal product of this program was a revision to a computerized simulation model of a SIAF operating in both reconnaissances and combat modes developed by TRW under previous ARPA contracts.

The SIAF simulation model is provided as computer software installed on the CDC 6500 computer at Fort Leavenworth, Kansas, and additions to and replacements for a six-volume User's Manual as follows:

Volume I-Model Description and Programming Guide (This Final Report serves as a forward to Volume I)

Volume II-Model Subroutines (Terrain, Weather, Targets)

Volume III-Model Subroutines (SIAF Function and Ancillary Routines)

Volume IV-Model Program Listing

Volume V-Combat Initialization Subroutines

Volume VI-Combat Execution Subroutines

These six volumes are to be considered as part of the final report.

This final report provides a background to the SIAF program, a brief description of the features of the integrated SIAF model, and a summary of the tasks performed during the current contract.

Section 2 of Volume I provides a more complete overview of the SIAF model. Full details of the individual submodels are provided in Volumes II through VI.

BACKGROUND

In recognition of the increasing importance and complexity of small military patrols in low intensity guerilla warfare, ARPA activated the Small Independent Action Forces (SIAF) program in 1968. This continued project has as its ultimate objective the improvement of the operational effectiveness of SIAF units. One aspect of this objective has been the need to develop a rapid and economical means of measuring patrol effectiveness to permit the effects of postulated improvements or changes to be evaluated. Namely, a capability is required to

- ° Study effects of changes in equipment
- ° Establish tradeoffs for organization/equipment mixes
- ° Expose alternative doctrine options

In furtherance of this objective, ARPA has sponsored several types of research and development programs. These have included the collection of extensive field data on the various aspects of patrol operations in Southeast Asia, equipment development programs, field test programs, and a SIAF computer model simulation program by TRW Systems. The model is the subject of this report.

The SIAF simulation model has been developed by TRW Systems under seven successive programs. The first, under ARPA/AMICOM Contract DAAH01-70-C-0141 running from August 1969 to June 1970, was to determine the feasibility of structuring a SIAF model for use as an evaluation tool. The second, under ARPA/AMICOM Contract DAAH01-71-C-0100 running from August 1970 to August 1971 was to develop a computerized simulation of a SIAF patrol in a reconnaissance role. The primary effort was formulation and programming of the model itself. Volumes II and III of the SIAF Users Manual describe primarily the results of that effort.

The third TRW SIAF program was the SIAF External Fire Support Study, under ARPA/AMICOM Contract DAAH01-71-C-1115 running from May 1971 to May 1972. An output of that study was an External Fire Support Submodel that was incorporated into the SIAF Reconnaissance Model.

The fourth SIAF model development program provided for the development and programming of a fully computerized stochastic combat submodel

which provided dynamic deployment logic as well as fully simulated small arms fire. This work was performed under ARPA/AMICOM Contract DAAH01-72-C-0305 running from November 1971 to December 1972. The results were fully integrated with the previous SIAF Reconnaissance Model.

Two subsequent contracts, DAAH01-73-C-0222 and DAAH01-73-C-0257 which were performed in December 1972 and from March 1973 to July 1973, respectively, were used to reprogram the SIAF model to run on the CDC 6500 computer.

The final SIAF model development contract was used to modify the SIAF Model. This has been performed under Contract DAAH01-73-C-0914 from June 1973 to December 1973. The work performed is the subject of this report.

MODEL SUMMARY

The Small Independent Action Forces (SIAF) Model is a computer simulation intended for use in evaluating the effectiveness of alternative SIAF concepts. The model essentially accepts as input a military operations plan, such as would be prepared by a military commander in the field for an actual patrol operation, and simulates this operation on a computer. It considers both reconnaissance and combat missions. The SIAF Model simulates the interactions of the operations plan with the terrain, weather, and enemy situation. It considers a total mission from beginning to end. The output of the model is the effectiveness of the particular operation under consideration. During the simulation of activities and events which occur during SIAF operations, the model calculates statistics pertaining to movement, navigation, surveillance and detection, fire support, supply maintenance, human maintenance, communications, and casualties.

The model is checked out and is ready for use. It can be applied to a variety of problems involving the effectiveness of SIAF operations, such as the effects of postulated improvements and determination of performance capabilities of these type units. It can also be used to study the sensitivities with respect to numerous input variables.

Listed below are some of the features of the SIAF model compared to other models which might be used for the same purpose:

- 1) It simulates the entire mission from start to finish and is capable of considering up to 10-day missions. This differs from many existing models of patrol operation which consider only a partial mission segment. The functions of movement, navigation, surveillance and detection, fire support, supply maintenance, human maintenance and external communications and their interactions are explicitly considered in the model.
- 2) It includes a detailed and realistic treatment of terrain considering relief, vegetation, obstacles, cultural features and surface material. This differs from other existing models in that for this model relief is represented by a continuous surface, and vegetation is represented throughout the entire area of operations instead of just locally.
- 3) It has an explicit detailed treatment of visual detection considering instantaneous locations of each SIAF and target individual as well as light level, reflectivity and background.
- 4) It includes dynamic movement of the patrol and detailed target movement. The patrols can advance toward targets or can be made to move around them.
- 5) The suppressive effect of incoming fire is considered for both movement and outgoing fire.

The combat model has the following detailed features:

- 1) It considers the events and conditions just prior to entering combat as well as the combat itself. Thus allowing study of the effect of pre-combat conditions and of entry into and exit from combat.
- 2) It considers ambush, attack, defense and meeting engagements.
- 3) It is stochastic and considers the attributes of each man on both sides. It considers individual fire-target combinations.

- 4) It relates the progress and the outcome of combat operations to environmental variables such as terrain, weather, etc., as well as to the combat power on each side.
- 5) It allows a study of combat alone or combat in combination with reconnaissance and/or in combination with the complete SIAF mission.
- 6) It considers EFS and organic weapon combat.
- 7) It allows user-input to many of the variables and decision factors so as to study the effect of variations of these.

SUMMARY OF ACTIVITY

Technical Objective

The objective of Contract DAAH01-73-C-0914 "Modification to Math Model for Small Independent Action Forces", is to improve the capability and utility of the previously developed SIAF model.

Technical Requirements

This section discusses each of the requirements specified in Technical Requirement Number 1816, which is an attachment to the contract.

1.0 Digital Elevation Data - The SIAF model now has the capability to use digital elevation data from tapes provided by the Defense Mapping Agency. Using subroutines created by the Systems Analyses Group of USACDC, a TOPOCOM tape is unpacked and a disk file is created for the area of operations. This disk file contains elevation data at the maximum resolution. When the SIAF model is run, the elevation data is read from the disk at the desired resolution. Changes were made to the storage sequence for elevation data such that the area of operations can be of any dimensions. The USACDC supplied subroutines are described in Volume III, Sections 10.5 to 10.7 (MAPGEN, CONVERT, ROTATE).

1.1 Tape Supplied - The SIAF sample case was run using a TOPOCOM tape containing elevations from the northern half of map sheet 1755I. This area is part of the Hunter-Liggett Military Reservation near King City, California. The maximum resolution of the data is 12.7 meters.

1.2 Variable Terrain Resolution - The capability is provided for varying the terrain resolution when changing from a reconnaissance mode to a combat mode and vice versa. At the start of the model the elevation data is read from the disk according to reconnaissance resolution by Subroutine RCREAD (See Volume III, Section 10.9). When a combat decision is made, the reconnaissance data is saved on a temporary file while Subroutine CMREAD obtains from the original disk file the elevation data at combat resolution (See Volume III, Section 10.8). Due to the requirement for more storage at greater resolution, the area considered during combat is smaller than the entire area of operations. The center of the combat area is determined dynamically by considering the SIAF position, target position, projected deployment point, and projected engagement point. The best shaped rectangle for containing these points is selected. In case the boundary of this area is crossed during combat the combat area is shifted. This is done by Subroutine OUTSID (See Volume III, Section 10.10). When the simulation returns to a reconnaissance mode, the old elevation data is retrieved by Subroutine CONMIS (See Volume VI, Section 3.14)

2.0 Vegetation, Microrelief, and Soil Shapes - The Terrain Submodel has been reprogrammed to consider vegetation, microrelief, and surface features as polygons. These polygons are input as rectangles, circles, or triangles. Dominant classes are used to describe the area not covered by a polygon. (See Volume II, Section 2.1)

3.0 Antipersonnel Mines - Capability has been added to allow a pre-planned Claymore mine ambush. In the reconnaissance mode the SIAF moves to the mine deployment area and hand emplaces the mines. When a target comes within detection range, control is shifted to the Combat Submodel to consider detailed detection, movement, and lethality of the mines. (See Subroutine MINES in Volume VI, Section 3.18).

4.0 Dynamic Action/Reaction - Provisions have been made to allow dynamic actions and reactions of the two opposing forces in combat. The action is taken following detection of the adversary. When the target detects the attacker, it can either

- withdraw
- deploy in place
- open fire
- ignore the detection
- rotate the formation
- move to best deployment position

The desired option is a user input. If the attacker detects a change in the original status of the target, it can withdraw, change its deployment point, or exchange roles between the maneuver unit and the base of fire. The target then gets to react one more time to a subsequent detection of a change in the attacker's intent. This capability is described in Subroutines REACT and CREAT (See Volume VI, Sections 3.16 and 3.17).

5.0 Internal Communications - An internal communications submodel has been added to the SIAF Combat Model to introduce delay times for communications between maneuver units. Three messages were incorporated for use requiring internal communications. These are "break contact" "change deployment point", and "exchange roles between the base of fire and the moving maneuver unit". For each message an heirarchy of preferred communications means is input. These are selected from visual hand signals, aural communication, radio, smoke grenades, and sending a messenger. Additional messages could be easily added to this list. Internal communications are controlled by Subroutine IC (See Volume III, Section 8.2).

6.0 Hand Grenades - Hand grenades have been added as an alternative weapon for a firefight. Logic was developed such that hand grenades are used at short ranges when the firer is highly suppressed. Existing routines in the Fire Control and Lethality Submodel were expanded to cover the employment decision and the simulation of the lethality of hand grenades. (See Volume VI, Section 2)

7.0 External Fire Support - An extensive effort was undertaken to provide a stochastic, dynamic model of external fire support during combat. Subroutines EFSTIM (See Volume III, Section 5.3) computes the times of arrival of either artillery shells or bombs. This is based on the tactical situation and the input delay times associated with requesting fire

support. Subroutine EFS1 (See Volume III, Section 5.2) stochastically computes the effects of each burst. This is based on input range and deflection errors, ballistic dispersion errors, and lethality data. Provisions are included to adjust firing between volleys when an observer is present.

8.0 Model Demonstration and Validation - This requirement calls for the performance of test runs on the USACDC 6500 computer at Fort Leavenworth, Kansas. These test runs are to be selected from historical examples, field tests, or other appropriate sources. They are to be used to verify the predictive capabilities of the integrated reconnaissance and combat SIAF model. Considerable effort was undertaken to discover appropriate data sources to use for a test case. The SIAF model requires very specific inputs in terms of a detailed operations plan, a tape containing the elevation and vegetation data for the area of operations, the weather, and detailed information on the locations of the targets. In the Combat Model, the SIAF makes decisions based on input decision criteria. Although extensive data was collected by The Vertex Group of the Research Management Corporation on historical SIAF operations, the data requirements for a simulation were not met. In the area of field tests, it was found that the only appropriate field test was the reconnaissance test performed at Hunter-Liggett in 1971. This was previously simulated and the results are presented in Volume I, Section 6. It does not include any of the combat model.

The approach taken by TRW to satisfy this task was in two parts. The first is a detailed validation through an experimental field test of the line-of-sight prediction portion of the model. This was felt important because it is a key driver of the events in the model. For this purpose an experiment was performed at the Hunter-Liggett Military Reservation where line of sight distances were measured from known locations at various headings. This test was simulated using the appropriate portions of the SIAF model with the elevation data tape from the Defense Mapping Agency. Resolution was varied from 12.7, 25.4 and 50.8 meters between elevation points. Results were found to be very close for rolling terrain at the 12.7 meter resolution, with a fast decline in accuracy as resolu-

tion was lowered. The simulation was also performed using the ASARS technique of modelling relief. It was found that the SIAF technique was slightly more accurate at 12.7 meter resolution and that the ASARS technique did not give credible results at lesser resolutions. This test is described in Volume I, Section 8.

The second step in model verification is to present a detailed examination of a sample case. This case is to be demonstrated at the SIAF Executive Overview Meeting on 18 January 1974 at Fort Benning, Georgia. The presentation will show the decisions, events, actions, and results of the SIAF simulation for a typical scenario. A qualitative assessment is to be made by experienced SIAF personnel. The sample case is also presented in Volume I, Section 6.

9.0 Documentation - The documentation for the current contract is provided as augmentation to the documentation from previous contracts. The most recent version was published in December 1972. All routines that were added or modified are to be replaced or added as specified in the augmentation instructions. The result is an integrated whole.

10.0 Train Government Personnel - A training class is scheduled for the week of 14 January 1974 at Fort Benning, Georgia. This class will teach analysts and programmers to understand, use, and modify the SIAF model. The class sessions are to be videotaped and placed in the videotape library at the U.S. Army Infantry School.

11.0 Stop/Restart - Capability has been added to the model to allow several stop points. At the point in the model that the stop point is reached, all of the common blocks are copied onto a disk. The model can then be restarted from that point for later use. This allows playing the combat portion separately and running it many times without repeating the earlier portions of the mission. This is performed by Subroutine RESTRT (See Volume III, Section 10.4).

12.0 Integrated, Debugged Model - The additions to the SIAF Model have been fully integrated with the previous version. The model has been debugged and is operational. At the time of this writing, it is scheduled to be installed on the CDC 6500 computer at Fort Leavenworth, Kansas

within a few days. Since the previous version is currently installed, no difficulties are foreseen.

13.0 Model and Documentation Requirements - Standards for the model and the documentation have been fully followed from USACDC supplement 1 to AR-18-7 Appendix M.

This document, prepared under ARPA Contract DAAH01-73-C-0914, contains changes and additions to Volume I, of the SIAF System Model User's Manual, 15 December 1972; hence, these pages replace or augment appropriate pages of the above referenced document. Table I provides instructions for accomplishing these changes to Volume I. (The pages in this document appear in the order in which they are referenced in Table I. As shown in Table I, for example, Pages i through ix of this document replace Pages i through xiii of Volume I of the User's Manual dated 15 December 1972.

Table I. Instructions for Changing and Augmenting Volume I, SIAF System Model User's Manual, 15 December 1972 (Sheet 1)

Page or Section	Replacement	Augmentation
Pages 1 through 12		Go in front of Volume I
Pages i through ix	Replace Pages i through xiii	
Page 1-1	Replaces Page 1-1	
Pages 2-1 through 2-84	Replaces Pages 2-1 through 2-80	
Pages 3-1 through 3-57	Replaces Pages 3-1 through 3-37	
Pages 4-1 through 4-17	Replaces Pages 4-1 through 4-15	
Pages 5-1 through 5-12	Replaces Pages 5-1 through 5-10	
Pages 6-137 through 6-221	Replaces 6-137 through 6-204	
Pages 8-1 through 8-30	Replaces Page 8-1	
Page 9-1		Goes behind Page 8-30

VOLUME I - USER'S MANUAL

TABLE OF CONTENTS

	<u>Page</u>
1.0 INTRODUCTION	1-1
2.0 PROGRAM DESCRIPTION	2-1
2.1 SIAF MEASURES OF EFFECTIVENESS	2-1
2.2 MODEL APPROACH AND REQUIREMENTS	2-3
2.3 THE EXECUTIVE ROUTINE	2-7
2.4 SIAF SUBMODELS AND SUBROUTINES	2-12
2.4.1 SIAF Terrain Submodel	2-12
2.4.2 SIAF Weather Model	2-30
2.4.3 Enemy Situation	2-33
2.4.4 Movement	2-33
2.4.5 Navigation	2-38
2.4.6 Surveillance/Detection	2-40
2.4.7 Fire Support	2-45
2.4.8 Supply Maintenance	2-45
2.4.9 Human Maintenance	2-45
2.4.10 External Communications	2-49
2.4.11 Command and Control	2-49
2.5 SIAF COMBAT SUBROUTINES	2-51
2.5.1 Combat Decision Logic and Optimization Logic	2-51
2.5.2 Combat Executive	2-54
2.5.3 Data Structure and Manipulation	2-60
2.5.4 Calculation of Movement Event Times	2-62
2.5.5 Calculation of Detection Event Times	2-64
2.5.6 Calculation of Firing Event Times	2-64
2.5.7 Calculation of Internal Communication Event Times	2-67
2.5.8 Calculation of External Fire Support Event Times	2-69
2.5.9 Ammunition Update	2-69
2.5.10 Weapon Substitution	2-73
2.5.11 Firing Options	2-77
2.5.12 Mines	2-80

20660-6002-R0-00

Page iii

Revised December 1973

	<u>Page</u>
2.5.13 Break Contact	2-80
2.5.14 Withdraw	2-80
2.5.15 Continue the Mission	2-83
2.5.16 Summary of Attacker and Defender Options	2-84
2.5.17 Summary of Model Capacities	2-84
3.0 MODEL INPUT	3-1
4.0 MODEL OUTPUTS	4-1
4.1 RECONNAISSANCE MODEL OUTPUTS	4-1
4.2 COMBAT MODEL OUTPUTS	4-1
5.0 SUBROUTINES	5-1
6.0 SAMPLE CASE	6-1
6.1 QUALITATIVE DESCRIPTION OF THE TEST PROGRAM	6-1
6.2 GENERATION OF BINARY TAPE 8	6-3
6.3 USER INPUT AND DATA BASE	6-24
6.4 MODEL OUTPUTS	6-42
6.5 USER INPUT FOR THE COMBAT MODEL SAMPLE CASE	6-137
6.6 OUTPUTS FOR THE COMBAT MODEL SAMPLE CASE	6-137
7.0 OPERATING PROCEDURES	7-1
7.1 HARDWARE REQUIREMENTS	7-1
7.2 SOFTWARE REQUIREMENTS	7-1
7.3 OVERLAY STRUCTURE	7-2
7.4 DECK SETUP	7-2
8.0 SIAF RELIEF MODEL VALIDATION	8-1
8.1 PURPOSE	
8.2 HUNTER-LIGGETT FIELD EXPERIMENT	8-1
8.2.1 Purpose	8-1
8.2.2 Equipment	8-1
8.2.3 Methodology	8-1
8.2.4 Field Measurement Errors	8-4

	<u>Page</u>
8.3 ELEMENTS OF SIAF MODEL USED IN VALIDATION	8-7
8.3.1 Mathematical Representation at Macro- Relief in SIAF Model	8-7
8.3.2 SIAF Subroutines Used	8-9
8.4 COMPUTER SIMULATION OF FIELD TEST	8-10
8.4.1 Simulation Methodology	8-10
8.4.2 A Measure for Evaluating Validity	8-12
8.4.3 Error Adjustments	8-12
8.4.4 Overall Measure of Validity	8-16
8.4.5 Simulation Using Different Resolutions	8-16
8.5 ANALYSIS OF SIMULATION RESULTS	8-17
8.6 SUMMARY	8-21
8.7 COMPARISON WITH ASARS BATTLE MODEL	8-23
8.7.1 ASARS Methodologh	8-24
8.7.2 Comparison	8-29
9.0 REFERENCES	9-1
APPENDICES	
Appendix A - Block Data Generator Program (BLKGEN)	A-1
Appendix B - Specification Statement Punch Program (SPECPN)	B-1

VOLUME I - USER'S MANUAL
LIST OF ILLUSTRATIONS

<u>Figure</u>		<u>Page</u>
2.1	Typical SIAF Measures of Effectiveness	2-2
2.2	SIAF Model Overview	2-5
2.3	SIAF Model Elements	2-6
2.4	Patrol Route	2-8
2.5	Generation of a Distance Segment	2-10
2.6	Illustration of Mini-Segments	2-11
2.7	Terrain Model - Relief and Vegetation Summary	2-14
2.8	Photograph of an Iconic Model of the SIAF Mathematical Terrain Model	2-15
2.9	Comparison of 100-Meter Resolution Digitized Data with Map Contours	2-16
2.10	Comparison of 50-Meter Resolution Manual Data with Map Contours	2-17
2.11	Representative Area of HLMR Vegetation	2-19
2.12	Class 5 Vegetation: Light Forest with Brush	2-20
2.13	Class 3 Vegetation: Moderate Brush	2-21
2.14	Effect of Polygon Overlay on Vegetation Representation	2-23
2.15	Terrain Model - Additional Factors Considered	2-24
2.16	Micro-Relief Features	2-26
2.17	General Line-of-Sight Situation "Top View"	2-27
2.18	General Line-of-Sight Situation "Profile View"	2-28
2.19	Terrain Concealment Subroutine (TERCON)	2-29
2.20	Weather Subroutine (WETHR) Variables	2-31
2.21	Example Weather Input Values	2-32
2.22	SIAF Model Threat Options	2-34

<u>Figure</u>		<u>Page</u>
2.23	Movement Subroutine (MVRATE)	2-35
2.24	Movement Command and Control Subroutine (CCMOV)	2-37
2.25	Navigation Subroutine (NAV)	2-39
2.26	Aural Detection Subroutine (AURAL)	2-41
2.27	Visual Detection Subroutine (VISUAL)	2-42
2.28	Detection Subroutine (DETECT)	2-44
2.29	External Fire Support Subroutine (EFS)	2-46
2.30	Supply Maintenance Subroutine (LOGIS)	2-47
2.31	Human Maintenance Subroutine (HUMAN)	2-48
3.32	External Communications Subroutine (EXCOM)	2-50
2.33	Movement to Contact and Deployment Logic	2-53
2.34	Alternative 1 to the Combat Executive	2-55
2.35	Alternative 2 to the Combat Executive	2-57
2.36	Comparison of Executive Alternatives	2-59
2.37	Attributes of Attacker and Defender	2-61
2.38	Calculation of Movement Event Times	2-63
2.39	Calculation of Detection Events	2-65
2.40	Calculation of Firing Events	2-66
2.41	Ammunition Update Subroutine (AMMOUP)	2-68
2.42	Weapon Substitution Subroutine (WSUBS)	2-70
2.43	Firing Option Subroutine (FIREOP)	2-74
.44	Logic for Continuing Reconnaissance After Combat	2-76
2.45	Illustration of Withdrawal Model	2-78
2.46	Continue the Mission Subroutine	2-79
6.1	SIAF Area of Operations Showing Patrol Checkpoints	6-2
6.2	Namelist Printout of Sample Case Elevation (Z) and Vegetation (V) Data	6-4

<u>Figure</u>	<u>Page</u>
6.3 Namelist Printout of Sample Case User Input	6-25
6.4 Detailed Computer Output	6-44
6.5 SIAF Surveillance Statistics Hunter-Liggett Scenario 1, 5 Replications	6-79
6.6 SIAF and Target Positions in Vicinity of Star Cluster Turn	6-135
6.7 Timeline Diagram for Selected Portion of the Scenario	6-136
6.8 Combat Sample Case Namelist Inputs	6-140
6.9 Sample Case Diagram	6-151
6.10 Sample Case Output	6-152
6.11 EFS Sample Case Diagram	6-193
6.12 EFS Sample Case Output	6-194
6.13 Claymore Mines Sample Case Diagram	6-216
6.14 Combat Outputs for Claymore Mines Sample Case	6-217
7.1 Master Common Listing	7-3
7.2 Overlay Structure	7-50
7.3 Deck Setup for the IBM 360/65	7-51
8.1 Hunter-Liggett Test Area	8-2
8.2 LOS Experimental Procedure	8-3
8.3 Distinction Between True Range and Surface Distance	8-5
8.4 Field Data (Hunter-Liggett)	8-6
8.5 Surface Within j, k^{th} Rectangle	8-8
8.6 Estimation of Surface Distance	8-13
8.7 Grid or Observer Location	8-15
8.8 Root Mean Square Error at Different Resolutions	8-18
8.9 Detailed Simulation Results (Sheet 1)	8-19

20660-6002-R0-00

Page viii

Revised December 1973

Figure

Page

8.10	LOS Verdict Using Different Resolutions	8-22
8.11	SIAF and ASARS Simulation Results (Sheet 1)	8-25
8.12	ASARS Line-of-Sight Calculation	8-27
8.13	Non-Unique Terrain Surface Representation	8-29

VOLUME I - USER'S MANUAL
LIST OF TABLES

<u>Table</u>		<u>Page</u>
2-1	Firing Options	2-71
2-2	Firing Options for the Base of Fire and the Maneuver Unit	2-72
2-3	Logic for Breaking Contact	2-75
3-1	User Input Namelist Input	3-2
3-2	Alphabetical Cross-Reference for Namelist Input Variables	3-54
3-3	Combat User Input - DLOGIC	OBSOLETE
3-4	Combat User Input - Combat Execution	OBSOLETE
3-5	Combat User Input - Lethality	OBSOLETE
4-1	Model Output Variables	4-2
4-2	Combat Outputs	4-11
5-1	SIAF Models and Associated Subroutines	5-2
5-2	SIAF Subroutines and Their Function	5-4
5-3	SIAF Elevation Data Handling (Sheet 1)	5-12
5-4	SIAF Combat Subroutines and Their Function	OBSOLETE
6-1	Target Number System	6-133

1.0 INTRODUCTION

The Small Independent Action Forces (SIAF) System Model User's Manual consists of six volumes. Volume I provides the information necessary to actually operate the model on the computer while Volumes II, III, V and VI provide the more detailed analysis and discussion of the subroutines.

Volumes II and III contain the reconnaissance routines developed under ARPA Contract DAAH01-71-C-0100 while Volumes V and VI are the combat routines developed under Contract DAAH01-72-C-0305. All of the volumes have been modified under Contract DAAH01-73-C-0914.

These volumes are as follows:

- Volume I - Model Description and Programming Guide
- Volume II - Reconnaissance Subroutines (Terrain, Weather, Targets)
- Volume III - Reconnaissance Subroutines (SIAF Functions and Ancillary Routines)
- Volume IV - Model Program Listing
- Volume V - Combat Initialization Subroutines
- Volume VI - Combat Execution Subroutines

The first volume contains general information concerning the use of the model. The first section contains a qualitative description of the model and associated subroutines. This is followed by sections which present alphabetical lists of the model input and output variables. Next, the model subroutines are presented and summarized (details of each subroutine are contained in Volumes II, III, V and VI). Finally, a sample case consisting in part of the simulation of a test conducted at Hunter Liggett Military Reservation and computer operating procedures are included.

2.0 PROGRAM DESCRIPTION

The SIAF system model is a computer simulation intended for use in evaluating the effectiveness of alternative SIAF concepts. This model essentially accepts as input a military operations plan, such as would be prepared by the military commander for an actual patrol operation, and simulates this operation in a computer environment. It considers a small independent action force which follows this operations plan, and considers both reconnaissance and combat missions. The SIAF model simulates the interaction of the operations plan with the terrain, weather, and enemy situation and considers a total mission from beginning to end. The output of the model is the effectiveness of the particular operation under consideration. During the simulation of the activities and events which occur during SIAF operations, the model calculates statistics pertaining to movement, navigation, surveillance and detection, fire support, supply maintenance, human maintenance, and communications. The specific objectives of this modeling effort were as follows:

- 1) Develop a methodology for modeling a SIAF patrol and implement the methodology.
- 2) Quantitatively measure the reconnaissance and combat effectiveness of alternative SIAF concepts.
- 3) Identify those variables which have the greatest impact on the overall effectiveness of SIAF.

2.1 SIAF MEASURES OF EFFECTIVENESS

In order to satisfy the objectives stated above, one of the first tasks that had to be performed was that of defining appropriate measures of effectiveness for SIAF since these are essentially the outputs of the model. For this purpose, experienced patrol leaders representing various military organizations were interviewed. Based upon these discussions, a list of measures of effectiveness was identified. Some of these measures are shown in Figure 2.1.

As an example of how these measures are applied to a SIAF problem, consider a situation where the user desires to compare the relative merits of two sensor systems, one of which is bulkier and requires a larger crew but is very reliable, versus less reliable equipment which is lighter and

- MOVEMENT MOE'S
 - INSERTION SUCCESSES/ATTEMPTS
 - PATROL DURATION
 - DISTANCE TRAVELED
- NAVIGATION MOE'S
 - NAVIGATION ACCURACY
 - TARGET LOCATION ERROR
- SURVEILLANCE MOE'S
 - NUMBER OF TARGETS DETECTED
 - NUMBER OF TARGETS IDENTIFIED
 - NUMBER OF TIMES SIAF IS DETECTED
- FIRE SUPPORT MOE'S
 - NUMBER OF SIAF CASUALTIES
 - NUMBER OF ENEMY CASUALTIES
 - NUMBER OF TIMES ENEMY IS HIT BY FIRE
- SUPPLY MAINTENANCE
 - PATROL WEIGHT
 - PERCENT SUPPLIES CONSUMED
 - PERCENT AMMUNITION EXPENDED
- HUMAN MAINTENANCE
 - HUMAN PERFORMANCE DEGRADATION
- COMMUNICATION MOE'S
 - COMMUNICATION SUCCESSES/COMMUNICATION ATTEMPTS

Figure 2.1, Typical SIAF Measures of Effectiveness

requires a smaller crew. For this purpose, measures such as detection per detection opportunity and man days per detection might be selected as being fundamental. Given such data, trade-offs are readily obtained providing useful guidance for research and development decision making. For examining and answering questions pertaining to engagement, the classical measures: casualties, exchange ratio (enemy casualties/SIAF casualties), and survivor ratio (SIAF survivors/enemy survivors) are computed. These measures are often used in the evaluation of competing patrol weapons mixes. Another possibility is that one might not be interested in casualties, per se, but in the number of times SIAF is able to direct fire on the enemy. This measure is also calculated by the model.

Ancillary statistics are intended to be of value for elucidation of cause and effect relationships. As a simple example in the use of these statistics, suppose that it is consistently found that battery life is a principal cause of communication failures. Given typical patrol durations and communication frequencies, a clear justification is available for a development effort aimed at extending power source endurance.

In summary, because of the requirement for the model to apply to general SIAF problems, a large number of measures and ancillary statistics are calculated and provided by the model. Application of the model requires that the user select from these data those statistics which pertain to the particular problem of interest. (Details of the model outputs are provided in Section 4.0 of this volume.)

2.2 MODEL APPROACH AND REQUIREMENTS

The approaches considered for the SIAF model included an analytical model, war gaming, and computer simulation. During this evaluation, a purely analytic model was discarded since it does not have the generality necessary to meet project requirements. War gaming is too slow and unwieldy for most SIAF purposes and is usually valuable only if copious resources and time are available. Field exercises and combat testing were also considered but were ruled out since, at times, conceptual systems must be studied by the decision maker. Simulation using analytical submodels was judged to combine the necessary generality and flexibility with acceptable speed and economy. The

computer simulation method allows for comparing alternative concepts (i. e., different mixes of personnel, material, and procedures) within a scenario of fixed conditions and assumptions. For the SIAF project, it constituted a clear first choice.

Once simulation was selected for developing the SIAF mathematical model, the next task was to prepare specifications for developing this model. The purpose of these specifications was to identify required model inputs, outputs, and submodels. To this end, it was recognized that the measures of effectiveness illustrated in Figure 2.1 depend upon five basic factors which are the terrain, weather, enemy situation, friendly situation in terms of units which support SIAF operations, and the specific SIAF operations plan being considered. Since the basic purpose of the model is to estimate the effectiveness of SIAF operations as a function of changes in these factors, they were essentially identified as inputs to the model. This is illustrated in Figure 2.2.

In identifying the submodel areas, a vigorous effort was made to develop a model which is as realistic as possible. To this end, it was recognized that in the real world a patrol leader prepares an operations plan before he starts the mission. In this operations plan, he considers the functions of movement, navigation, surveillance and detection, fire support, supply maintenance, human maintenance, communications, and command and control. In addition, these are the essential functions the patrol performs during the execution of the plan. Hence, these areas, in addition to terrain, weather, and enemy, were identified as the major areas for submodel development. (See Figure 2.3.)

Although submodels in each of these areas could conceivably be independently developed, a realistic simulation of patrol operation must also consider the interactions of the functions shown in Figure 2.3 with each other and the weather, terrain, and enemy situation. For example, the movement rate a patrol selects will be a function of the terrain and weather, pack weight, and fatigue of the patrol members. This will have an impact on the patrol duration, distance traveled, the visual detection capability of the patrol, and the possibility that the patrol is detected. That is, if the patrol moves rapidly over rough terrain, the patrol surveillance capability is decreased since more attention must be devoted to

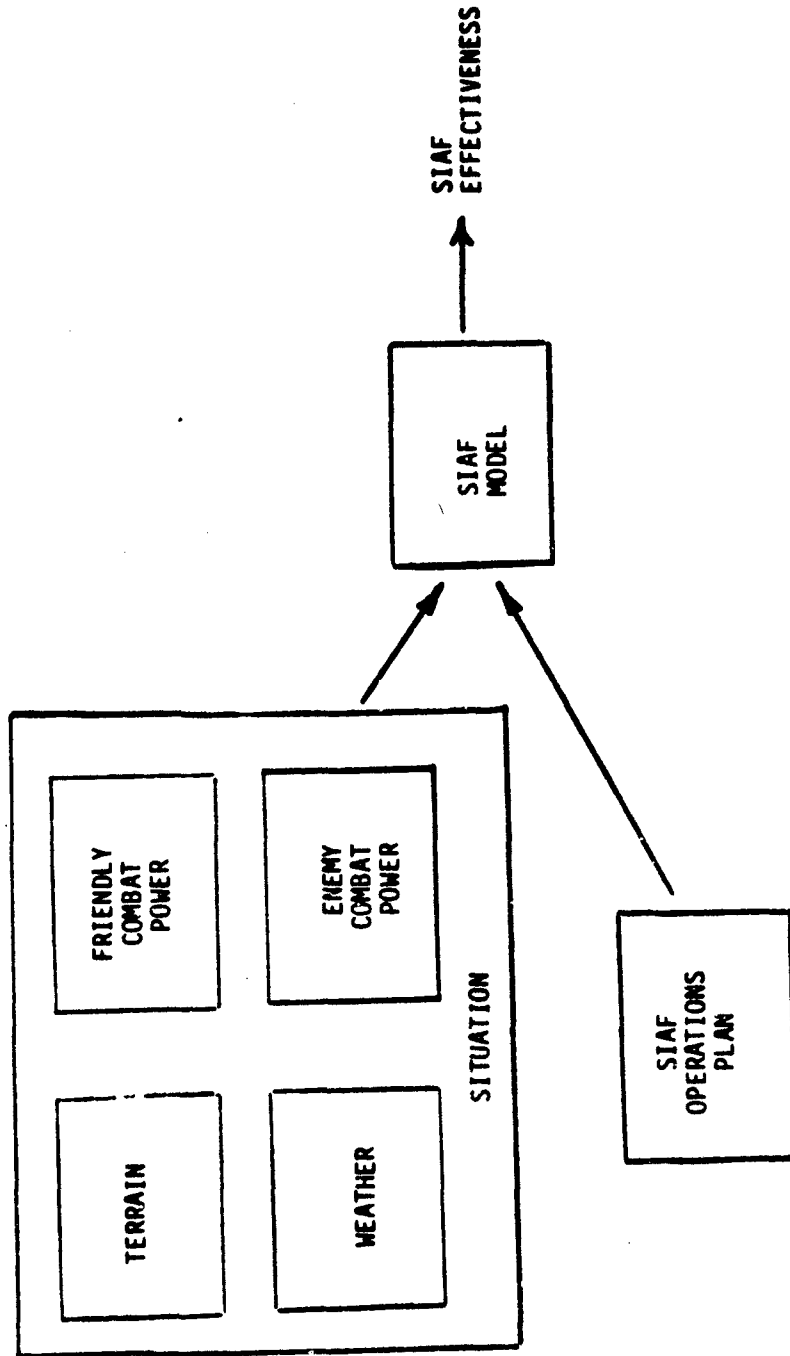


Figure 2.2, SIAF Model Overview

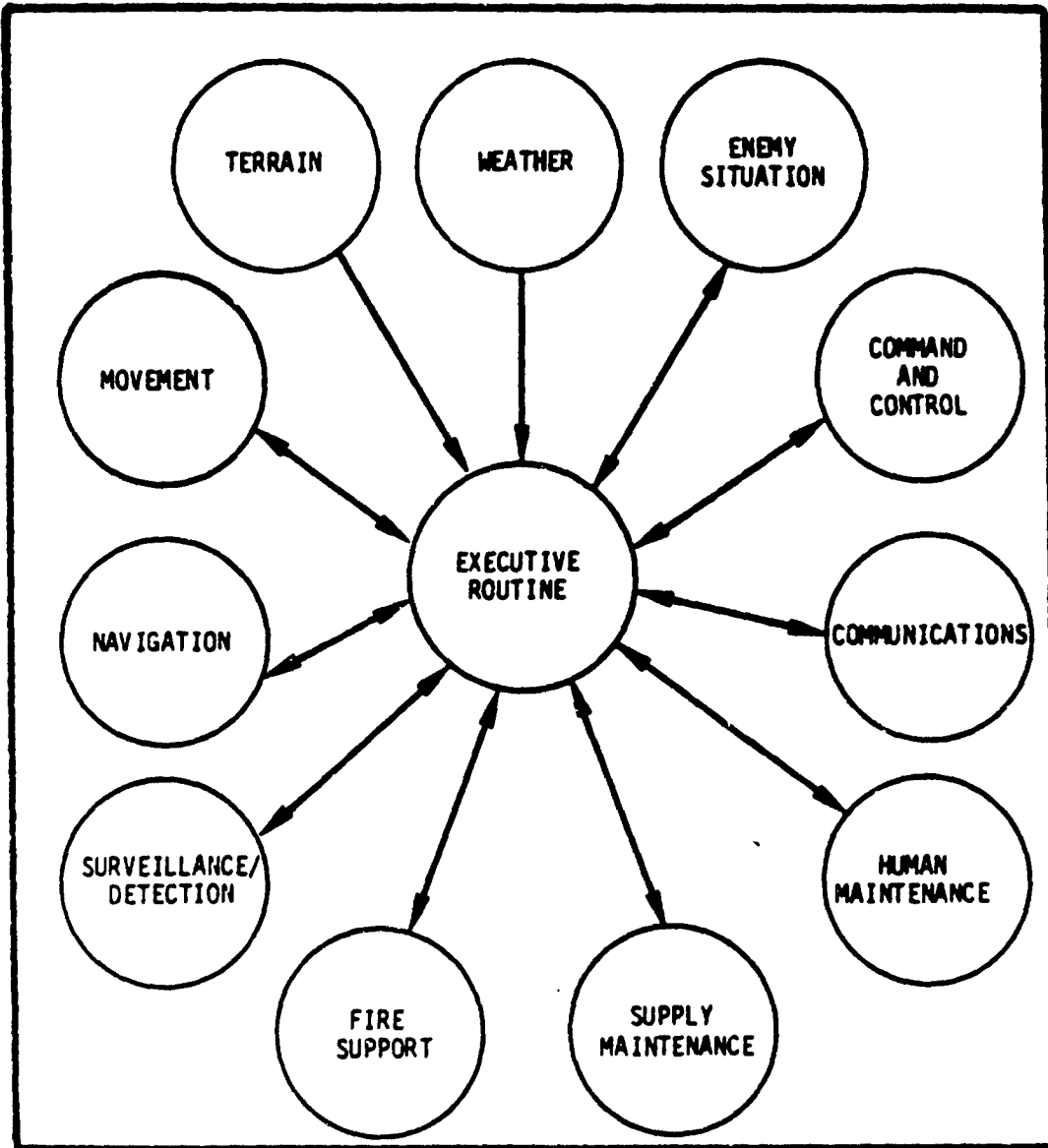


Figure 2.3, SIAF Model Elements

movement and, consequently, less can be devoted to surveillance. In addition, movement is a cue for visual detection and, hence, increases the possibility of detection by the enemy. This patrol movement rate also influences the energy expenditure rate of the patrol and the food and water requirements which are functions of the temperature and humidity and which, in turn, influence subsequent patrol movement rates. These are examples of the complex interactions which are considered in this model. These interactions are extremely important since equipments and tactics which lead to improvements in some areas could possibly result in a decrease in effectiveness in other areas (see Figure 2.1).

2.3 THE EXECUTIVE ROUTINE

The performance of many of the functions identified previously depend upon physical environment parameters of terrain and weather; as such, these subroutines use this information as input data. The problem here is that the physical environment parameters change with the location of the patrol on a route such as that shown in Figure 2.4; however, the subroutines are constrained to accept only a single value for a particular variable. A simple solution to the problem is to time step the patrol through the route using small time intervals. The idea, of course, is that if the time intervals are sufficiently small, one can assume that the appropriate physical environment parameters are constant during this interval. This approach, however, was not selected since it was felt that this would result in excessive model running time. A time step of 30 seconds, for example, would result in 28,800 time intervals for a patrol with a 10-day mission. Also, visual detection probability changes drastically as a function of light level; hence, it is desirable to examine events on a shorter time interval basis during periods of sunrise and sunset.

The possibility of using a purely distance driven simulation was also considered. However, this approach is complicated by the fact that the patrol may conduct stationary reconnaissance operations for long periods of time and normally reports its position and status to the base on a periodic basis (a function of time). Also, some targets are of such a nature that they may enter and leave the simulation as a function of time,

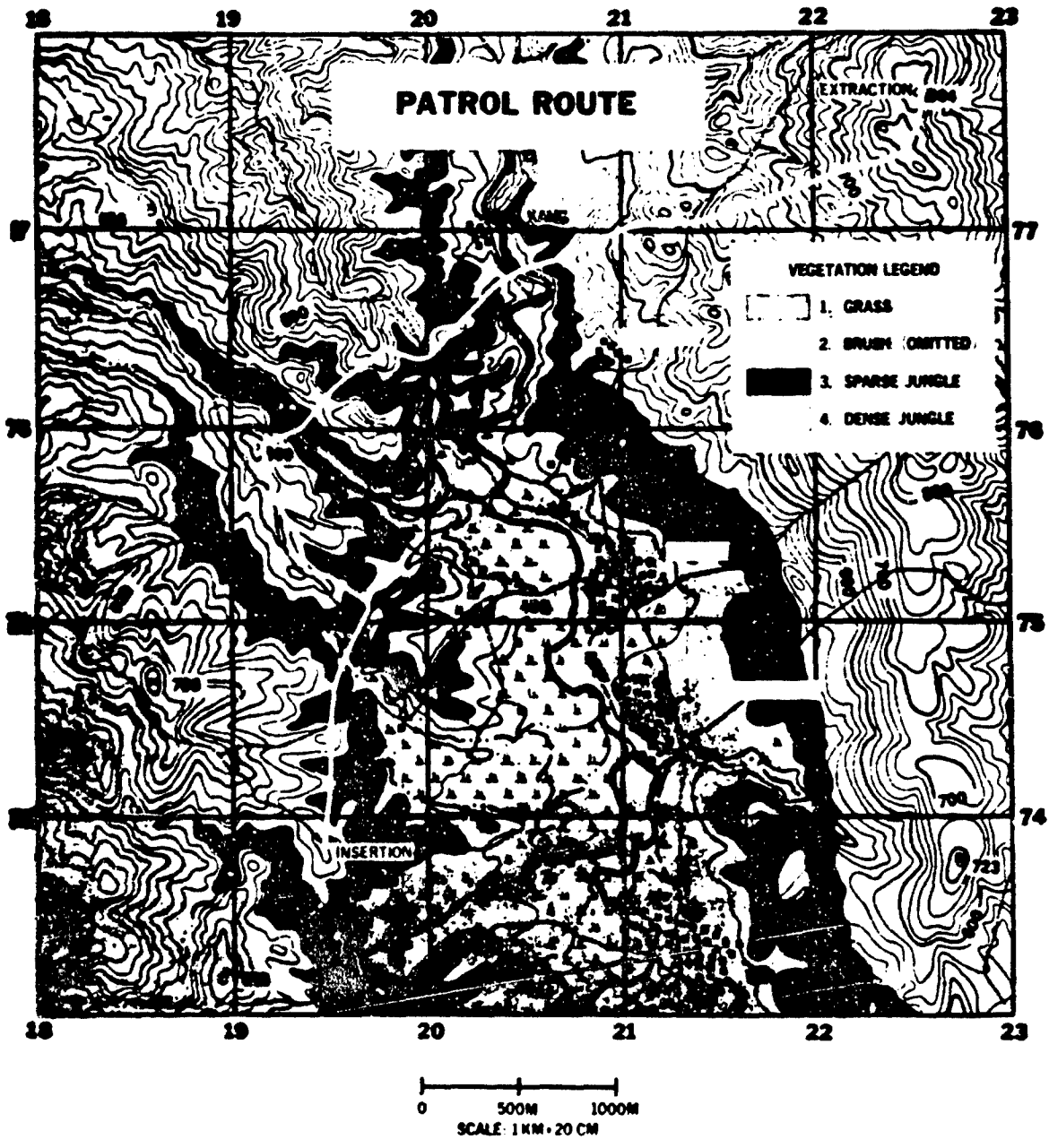


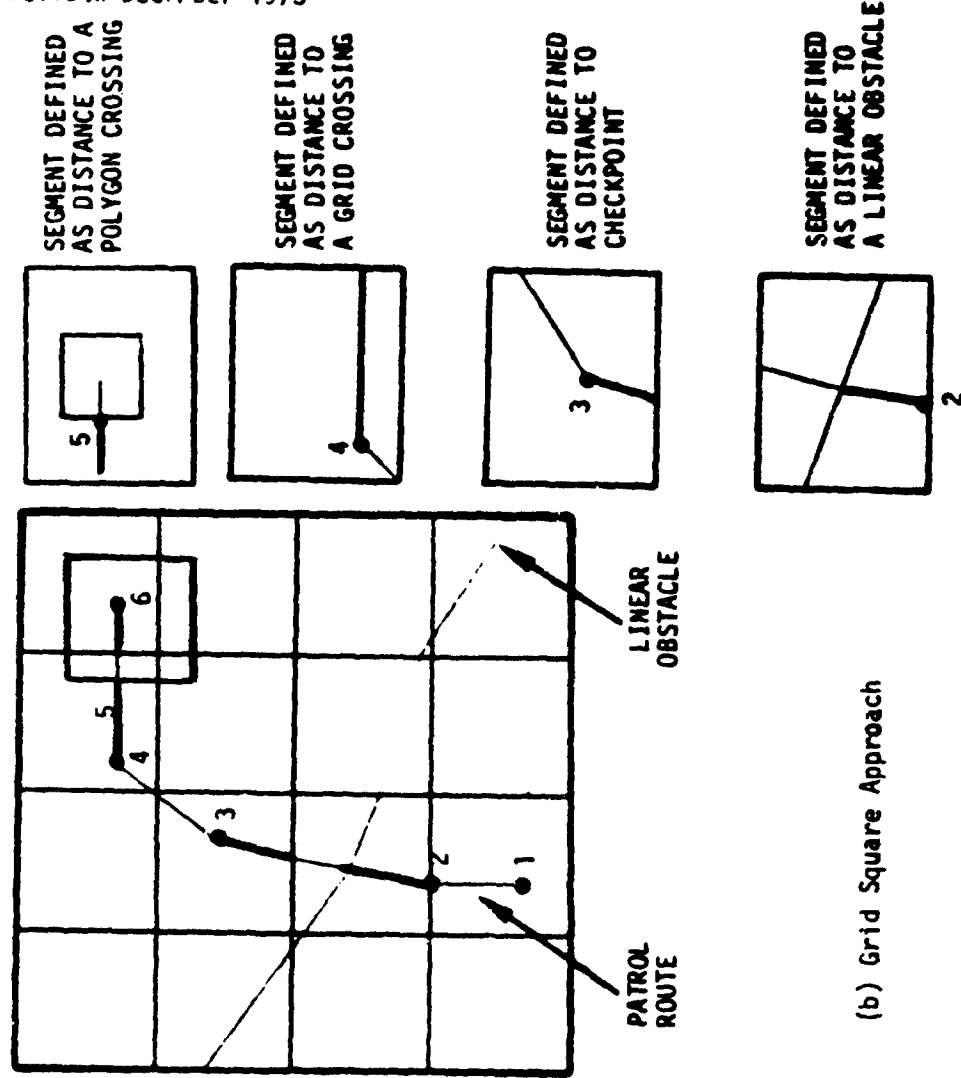
Figure 2.4, Patrol Route

further complicating the manner in which the model is driven. Likewise, a purely event driven simulation was discarded since events such as movement and surveillance and detection are continuously occurring in patrol operations.

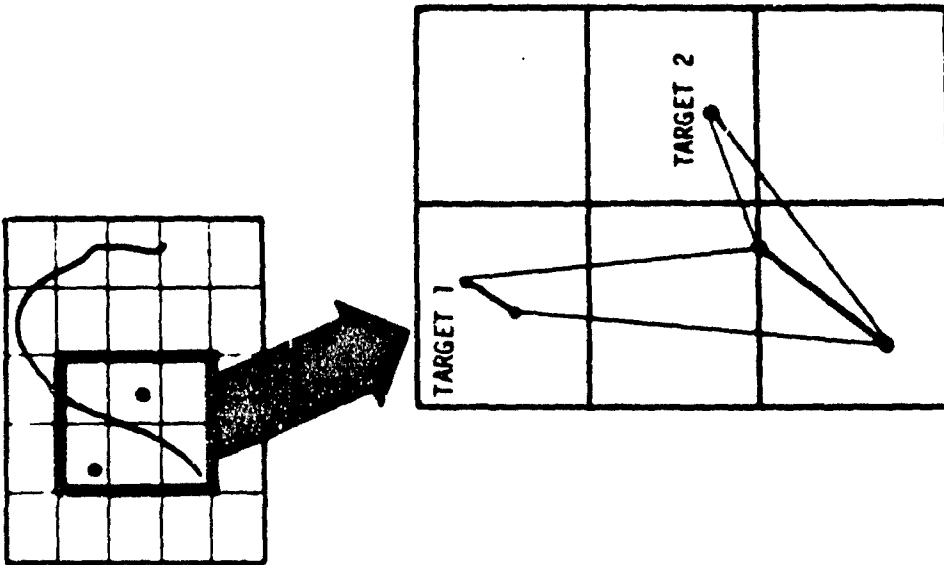
The resulting executive routine essentially consists of a marriage of these ideas. The basis of the concept is a grid square approach for inputting digitized terrain data and is illustrated in Figure 2.5. With this approach, a map of the area of operations is divided into grid squares whose resolution is user input. The total area is assigned a vegetation class with exceptions to this as subareas (polygons), in the form of rectangles, circles, and triangles (user input) assigned to the total (see Volume II for discussion of the terrain model). Based upon the axis of advance of the patrol, a segment, defined as the distance of the first grid crossing, checkpoint, obstacle, or polygon crossing, whichever is smaller, is first generated as shown in Figure 2.5(b). The movement rate over this segment is next calculated and a segment time is computed. This segment time is then checked to see if any target movement or communication events are to occur within the segment. If so, the segment is redefined as the distance the patrol moves to the time that particular event is scheduled to occur. Once a segment is defined, statistics pertaining to the functions shown in Figure 2.3 are calculated and accumulated for the segment. After these calculations, another segment is generated and the process is continued until the last checkpoint is reached.

If the SIAF patrol is stationary, a time driver subroutine drives the model and uses criteria of light level and target movement for determining the time step. During periods where the light level is relatively constant and targets are beyond feasible detection ranges, the time interval selected is large. When light level changes rapidly the time step is automatically reduced to account for the change in visual detection capability which occurs in this situation. Again, statistics pertaining to the functions shown in Figure 2.3 are accumulated for each time segment.

In addition to the distance and time segments defined previously, a subset of these called mini-segments are also generated when detections are feasible. Figure 2.6 illustrates this concept which operates as follows: During a simulation of the mission, many of the targets in the area of operations are not feasible of being detected because of the distance between them and the SIAF patrol. For each segment, feasibility of



(b) Grid Square Approach



(a) Area of Operations

Figure 2.5, Generation of a Distance Segment

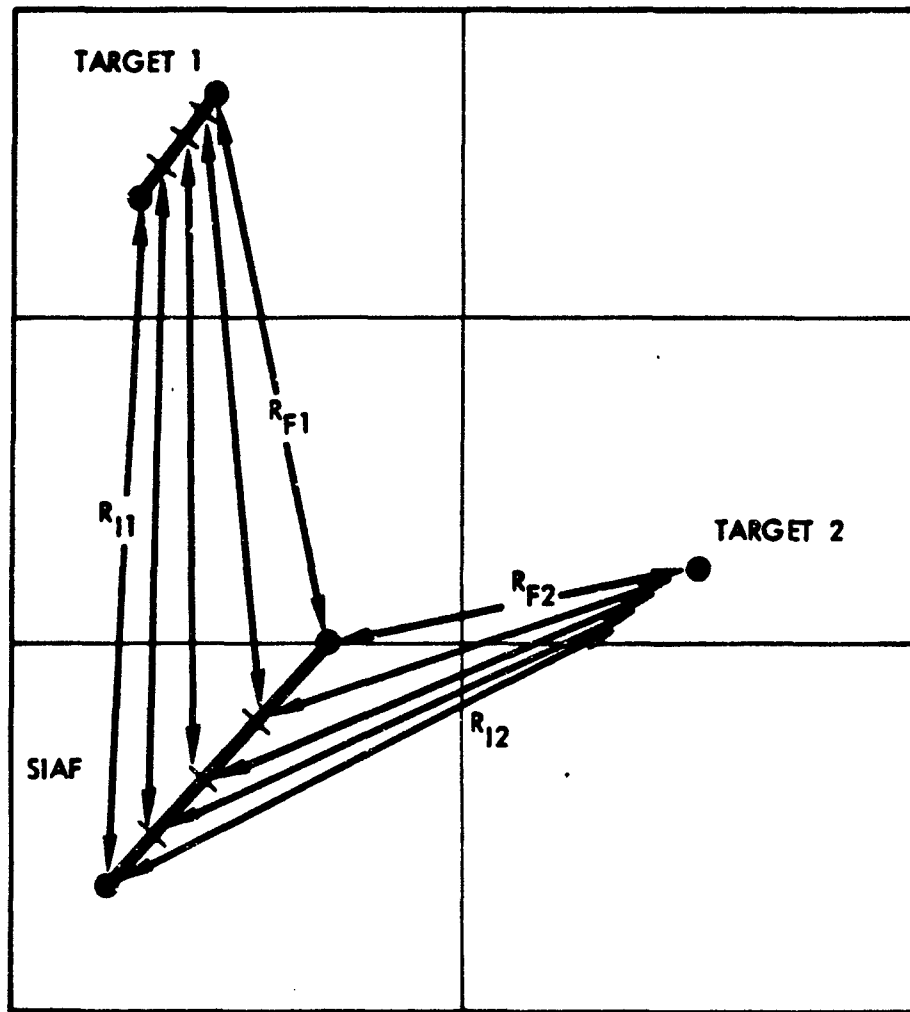


Figure 2.6, Illustration of Mini-Segments

target detection is checked at the minimum range point and, if not feasible, the target is not considered during the next series of calculations. If feasible, on the other hand, the line of sight between SIAF and the target could change as a function of their relative positions in the segments. In this situation, both SIAF and target segments are divided into mini-segments. The length of the mini-segments are user input. In this situation, the program advances SIAF and each feasible target, a mini-segment at a time, and determines a detection verdict for each mini-segment. For this calculation two options are available: In the first of these, the centroid of the patrol and each target are examined to determine if line of sight exists. If so, then it is assumed that line of sight exists between all members of each group. The user also has the option of treating man-to-man intervisibility in which he can consider the relative location of each individual in both the patrol and target formations (see the Surveillance/Detection Submodel, Volume III, Section 4.0, for the details). This option accounts for the fact that some of the individuals in a particular group may not be visible by all members of the other group. Thus, the user can consider the patrol as one point or consider individuals as desired. These options essentially serve to automatically increase the resolution of the model when required and use less detail resolution when this is appropriate. All of these features serve to minimize the running time of the model and provide the user the option of selecting the resolution he desires.

2.4 SIAF SUBMODELS AND SUBROUTINES

In this section, each of the submodels shown in Figure 2.3 is summarized and the interactions among them are described. The subroutines described herein are listed in Section 5.0 of this volume for ease in referencing. Volumes II, III, V and VI contain detailed information concerning these submodels and subroutines.

2.4.1 SIAF Terrain Submodel

The purpose of the SIAF Terrain Submodel is to provide a representation of the terrain for use in line-of-sight and slope calculations,

and for considering factors such as the vegetation at various points in the area of operations as required by the other subroutines. This submodel considers the following factors:

- Relief
- Vegetation
- Obstacles and Cultural Features
- Micro-Relief
- Surface Materials

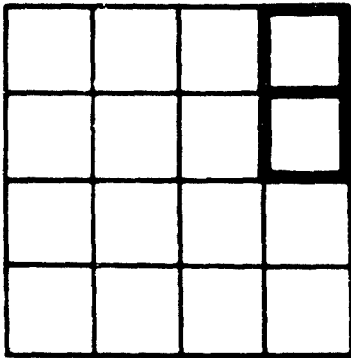
The manner in which these factors are treated in this submodel is summarized below.

Relief

The basic approach for treating relief is to divide the map into grids, whose size is a user input. The grid elevation data is obtained from a military "TOPOCOM" tape of the area of operations. The tape contains digitized elevation data of various areas and is of a high resolution. Thus, the elevation data represents the elevation at each corner of the grid square. Based upon these data, the model generates a hyperbolic surface between the points for each grid square. Figure 2.7 illustrates this surface for two grid squares. In order to explain and illustrate the results which are obtained with this approach, an ionic model of four grid squares was developed. Figure 2.8 is a photograph of this model. It illustrates the curved surface which is obtained from the four-corner input data.

As an example of the impact of various resolutions on the accuracy of the relief representation, a study was made using Army map sheet 1755 IV NE, Alder Peak California, 1:25,000. Figure 2.9 shows actual contours and the contours which result from this model using 100-meter resolution. These 100-meter data were obtained from a listing of an Army digitized terrain tape of the area. The Figure illustrates how much of the section of road can be observed from the observation post for both sets of contours; there is considerable error in the results obtained from the model when the 100-meter resolution is used. Figure 2.10 shows the same situation for 50-meter resolution. These illustrations show that accuracy

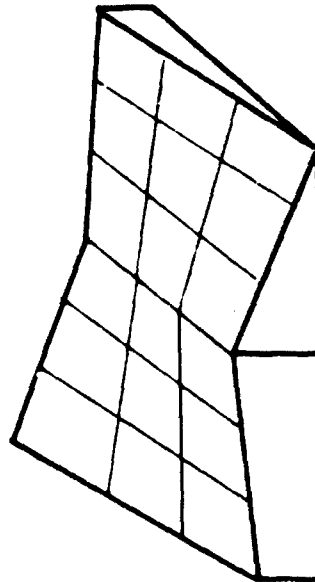
TERRAIN DATA INPUT SCHEME



VEGETATION CLASSIFICATION SCHEME

- 1 NO VEGETATION
- 2 SPARSE GRASS OR BRUSH
- 3 MODERATE GRASS OR BRUSH
- 4 DENSE GRASSLAND
- 5 LIGHT FOREST WITH BRUSH
- 6 SPARSE FOREST
- 7 MODERATE FOREST
- 8 HEAVY FOREST
- 9 DENSE BRUSH WITH TREES
- 10 SPARSE JUNGLE
- 11 MODERATE JUNGLE
- 12 HEAVY JUNGLE

RELIEF REPRESENTATION



GENERALLY EACH VEGETATION CLASS CONTAINS

- GRASS
- BRUSH
- TREE TRUNKS
- TREE CROWNS

Figure 2.7, Terrain Model - Relief and Vegetation Summary

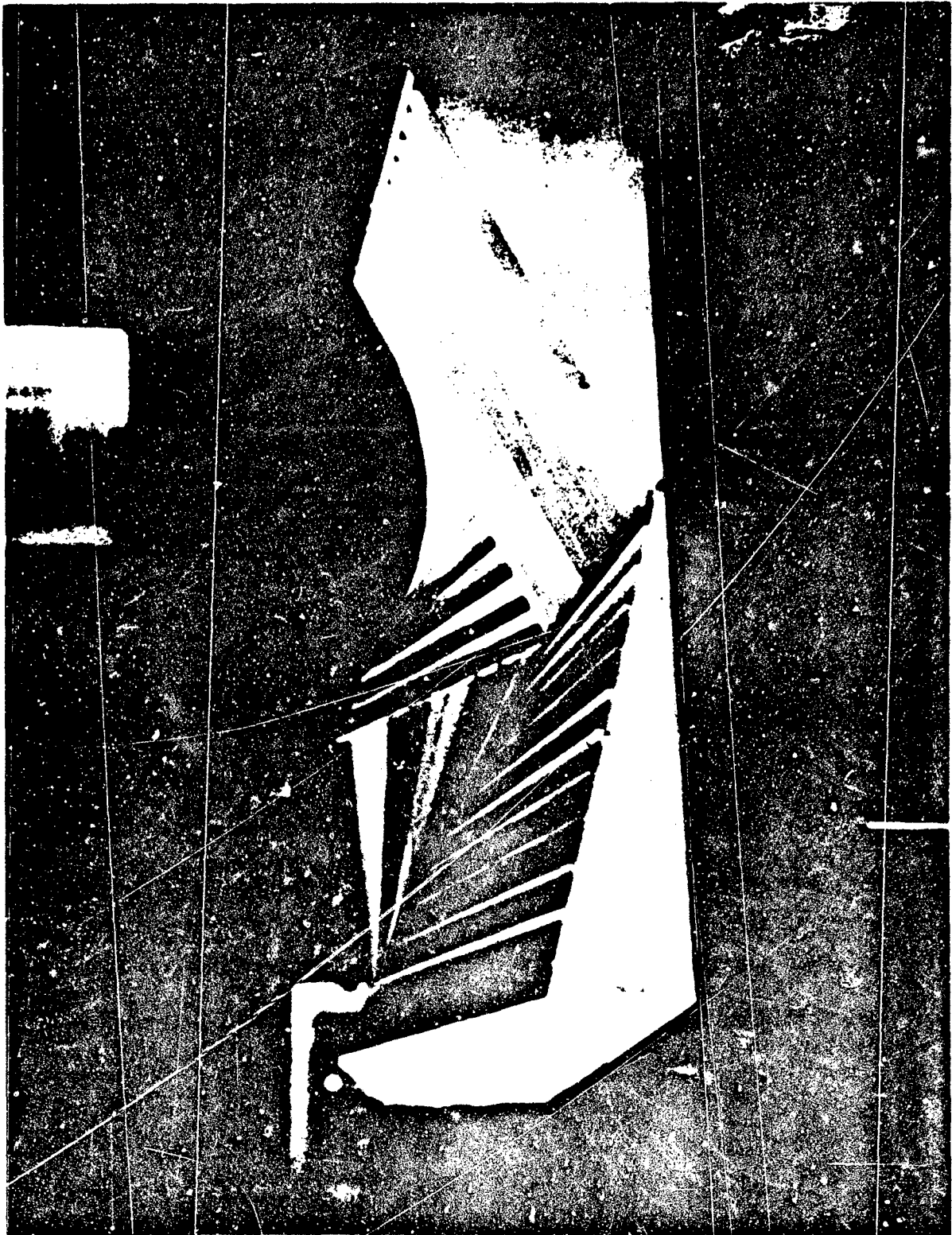


Figure 2.8, Photograph of an Iconic Model of the
CIAF Mathematical Terrain Model

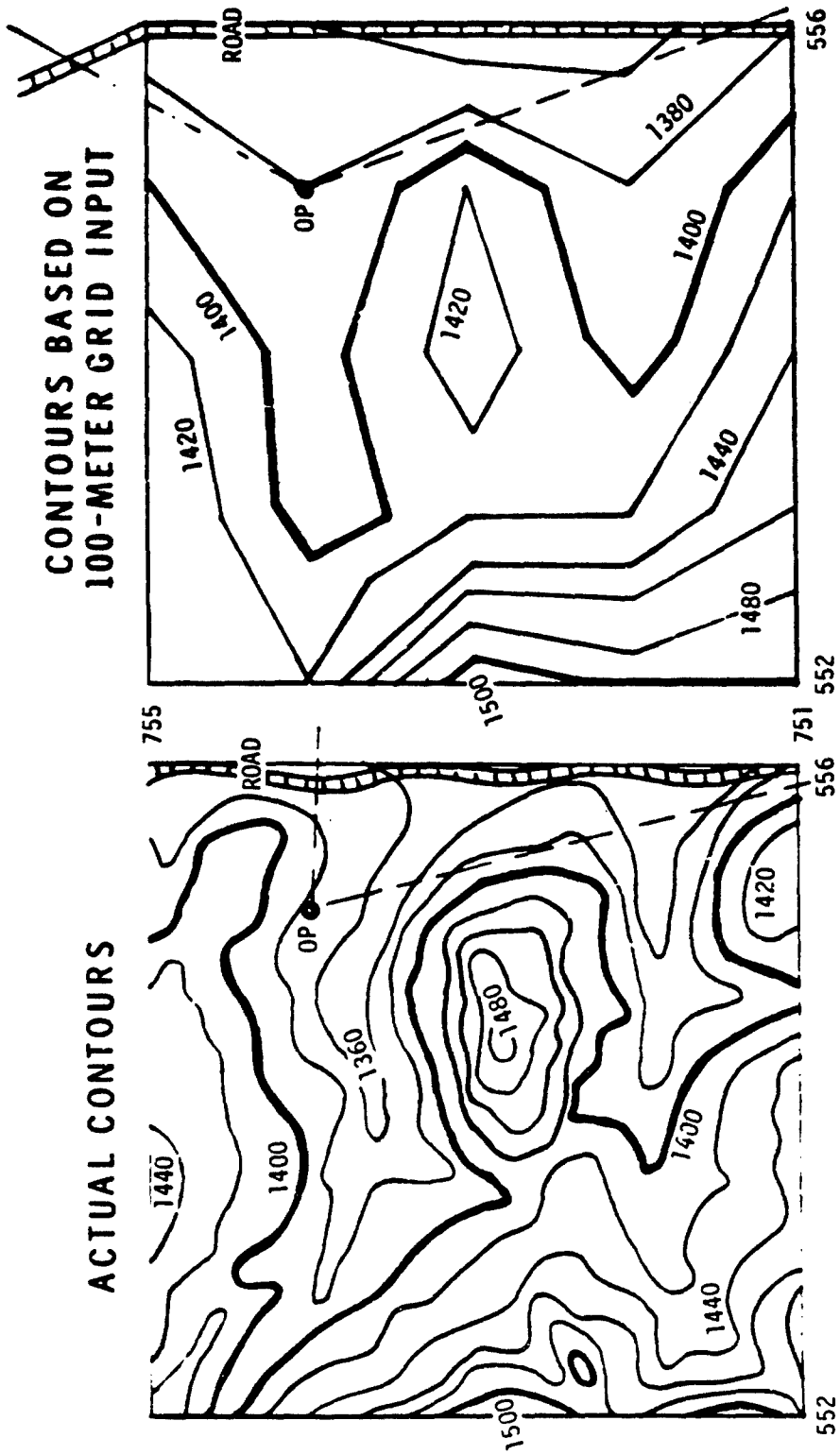
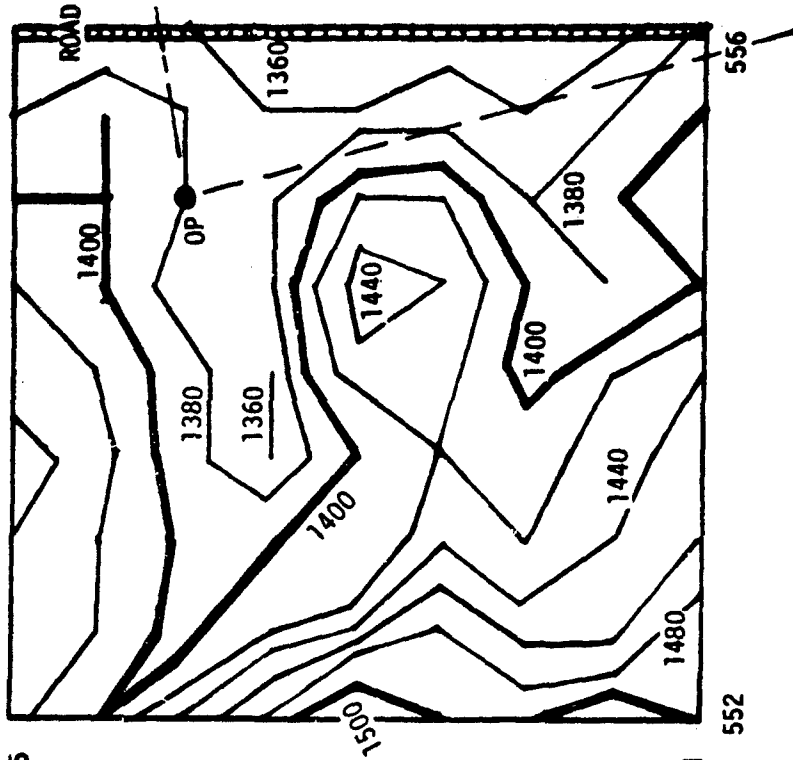


Figure 2.9, Comparison of 100-Meter Resolution Digitized Data with Map Contours

**CONTOURS BASED ON
50-METER GRID INPUT**



ACTUAL CONTOURS

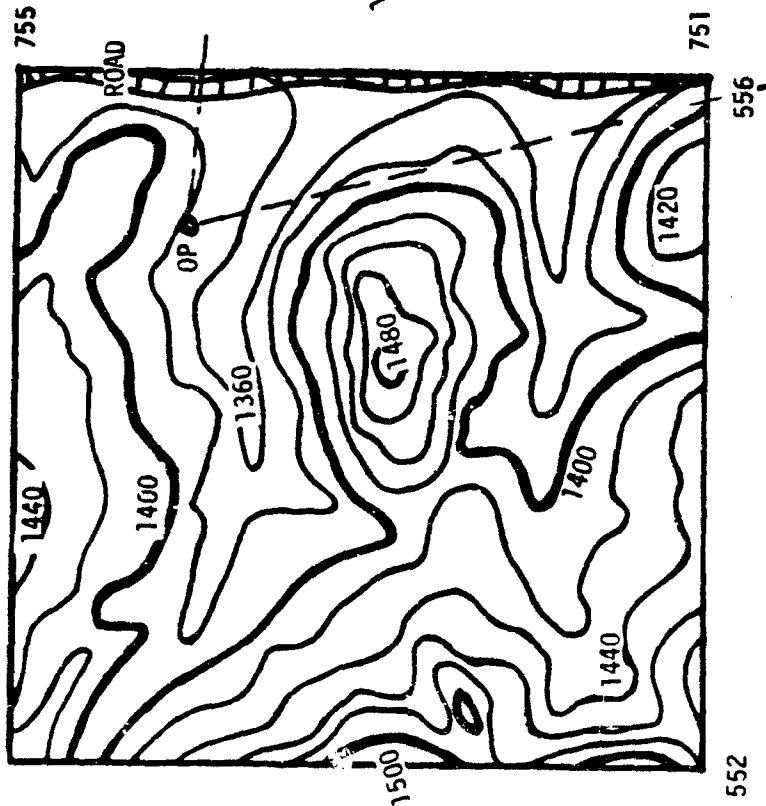


Figure 2.10, Comparison of 50-Meter Resolution Manual Data with Map Contours

of relief representation is considerably better with 50-meter resolution. It is interesting to note that the terrain for which this comparison was made is fairly rugged. Hence, the preceding analysis probably represents a worst-case situation.

Further comparison of the relief part of this model to field experiments is presented in Section 8.0 of this model.

Vegetation

The problem of appropriately modeling the vegetation factor of terrain for SIAF was approached in two steps. First, it was necessary to develop an appropriate vegetation classification scheme. Second, it was necessary to determine the manner in which this scheme could best be used, in conjunction with the relief portion of the Terrain Submodel.

The vegetation classes considered in this submodel are summarized in Figure 2.7. As shown in the figure, each class of vegetation consists of a certain amount of grass, brush, and trees. The features within each class are assumed to be distributed at random. To the total area for which elevation is input is assigned one number from 1 to 12 to represent the class (dominant) of vegetation to be found within the area. Exceptions to this are inputted as subareas in the form of triangles, circles, and rectangles and are also assigned a number from 1 to 12 and are used to represent subareas of vegetation other than the dominant within the total area.

In developing this classification scheme, an attempt was made to include consideration of the types of vegetation which might be found in various parts of the world. In addition, an attempt was also made to gather realistic data concerning the density and size of the vegetation features within each class. To this end, various references (indicated in Volume II) were studied. The data in these references were augmented by a field trip to Hunter Liggett Military Reservation where aerial photographs of the area were obtained and a ground survey was conducted.





Figure 2.12, Class 5 Vegetation: Light Forest with Brush



Figure 2.13, Class 3 Vegetation: Moderate Brush

Figure 2.11 presents one of these aerial photographs while Figure 2.12 provides a closeup view of the vegetation in the square of Figure 2.11. Figure 2.13 is a view of the vegetation in the area of the circle of Figure 2.11. The vegetation shown in the photograph of Figure 2.12 was subsequently defined as class 5, light forest with brush. Results of the ground survey indicated that there were approximately 63 features of brush per 50- by 50-meter square, each feature being approximately 2 meters wide and 3 meters high. In addition, the 42 trees in this area were judged to be an average of 10 meters high with 3-meter wide crowns. The vegetation shown in Figure 2.13 was found to be considerably different as might be expected from an inspection of Figure 2.11. This area was defined as class 3, moderate grass or brush, and was found to consist of 500 features of brush per 50-meter square. Each feature was judged to be a sphere with a diameter of approximately 1.5 meters.

As an example of the impact of the polygon (triangles, rectangles, and circles) overlay method of vegetation representation, Figure 2.14 shows the accuracy of realism that can be obtained through this method. As can be observed, considerable accuracy can be obtained.

Obstacles and Cultural Features

For the purposes of modeling, cultural features and obstacles are treated in the same manner as vegetation in that a polygon configuration resembling the feature or obstacle is overlaid on the area and is assigned a number which indicates the type of area obstacle. Cultural features such as roads, on the other hand, are input by means of straight line segments. Figure 2.15 summarizes obstacles and cultural features considered in this submodel and presents an example which illustrates the input procedure described above.

Surface Materials

The surface materials or soil classifications considered in this submodel are summarized in Figure 2.15. In preparing the inputs to the submodel, a dominant soil classification is assigned to the area of operations. Thus, if the area is considered to consist mainly of sand, then the number 2 would be associated with the area. Exceptions to this are input by a means of subareas in the form of circles, rectangles, and triangles illustrated in Figure 2.15. Thus, for example the shown, the cross-hatched area would consist of high plasticity silt (class 0) while the remainder of the area would have the dominant soil class (class 2).

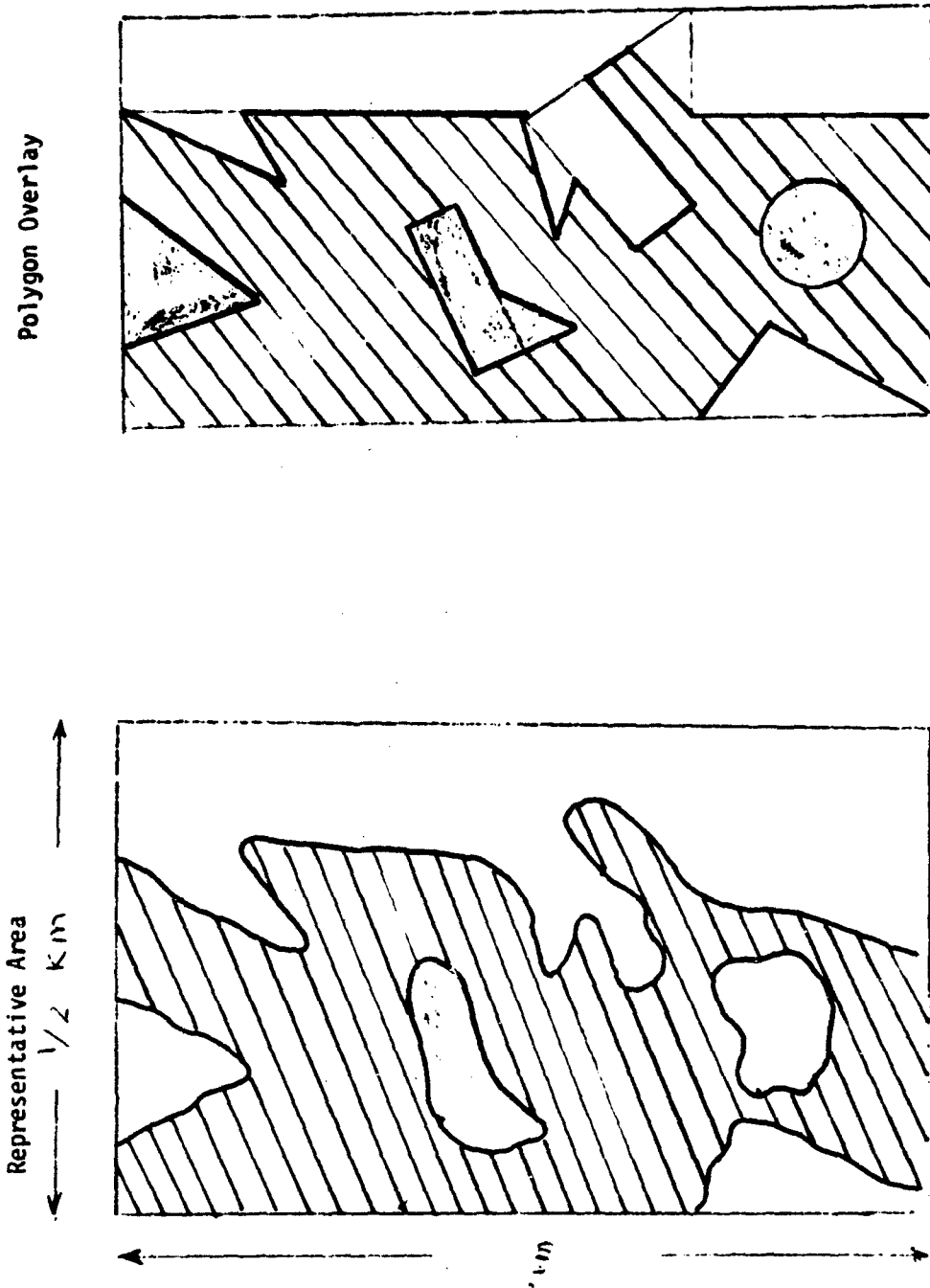
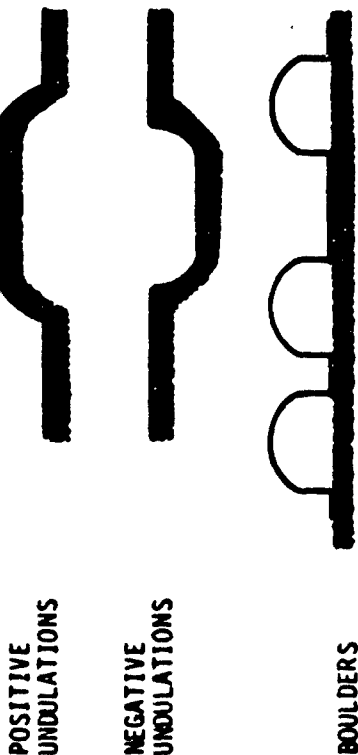


Figure 2.14. Effect of Polygon Overlay on Vegetation Representation

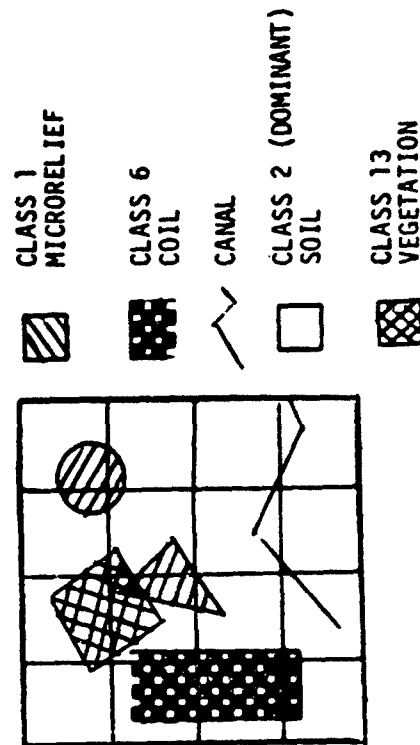
MICRO RELIEF (5 CLASSES)



OBSTACLES AND CULTURAL FEATURES

- AREA
- LINEAR
- SWAMPS
- RIVER
- CULTIVATED LAND
- STREAM
- VILLAGES
- RAVINE
- DIKE
- CANAL
- CLIFF
- ROAD
- TRAIL
- LAKE
- BOUNDARIES

POLYGON BY EXCEPTION METHOD OF INPUTTING SOIL, MICRORELIEF AND VEGETATION



SOIL CLASSIFICATION

- 1 GRAVEL
- 2 SAND
- 3 CLAY - LOW PLASTICITY
- 4 CLAY - HIGH PLASTICITY
- 5 SILT - LOW PLASTICITY
- 6 SILT - HIGH PLASTICITY
- 7 PLOWED EARTH (SOFT)
- 8 FROZEN GROUND

Figure 2.15. Terrain Model - Additional Factors Considered

Micro-Relief

In addition to the factors considered in the foregoing discussion, certain terrain irregularities must now be considered. Figure 2.16 photographically illustrates some of these irregularities that exist at the Hunter Liggett Military Reservation. These irregularities are called micro-relief for this model. Here, positive undulations, negative undulations, and boulders are considered. Each class of micro-relief consists of a combination of these features of varying densities and sizes. These features are assumed to be distributed randomly within an area; they are input by means of circles, rectangles and triangles as illustrated in Figure 2.15. Thus, the cross-hatched region, as shown in Figure 2.15, would consist of that class of micro-relief desired by the user while the remainder of the area of operations would consist of a dominant micro-relief class.

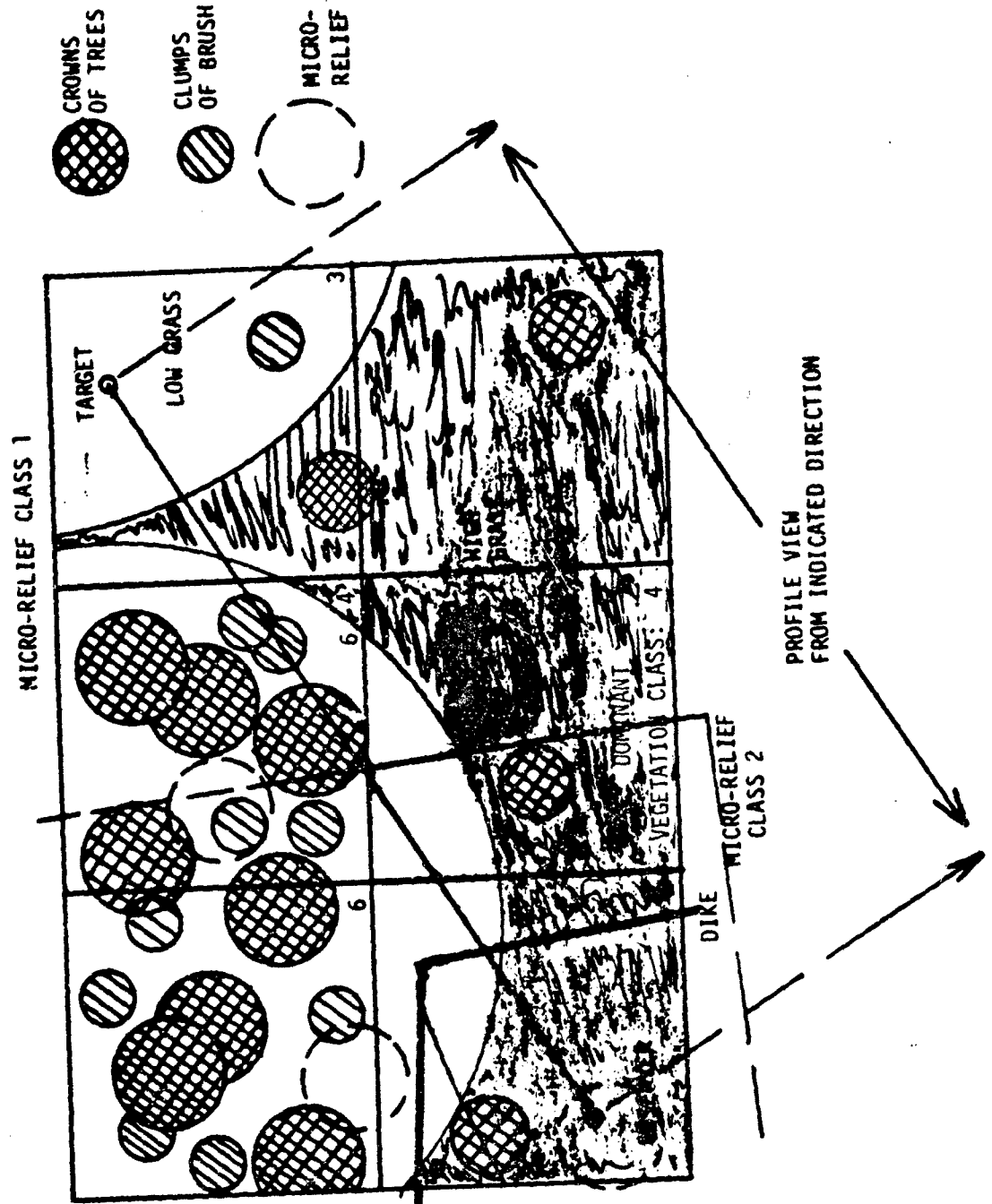
Summary

To illustrate how these factors of terrain are combined in the model, Figure 2.17, which presents a top view of six grid squares, was developed. A profile view of this situation is shown in Figure 2.18. A study of Figure 2.17 and 2.18 indicates that line of sight could be obstructed for a variety of reasons. For example, line of sight could be obstructed by relief, an obstacle, features of brush, crowns of trees, or trunks of trees. The relief and obstacle line-of-sight decision is essentially a deterministic one which is based upon the geometry of the situation while the line-of-sight verdict due to vegetation and micro-relief is a probabilistic one. Furthermore, this probabilistic verdict depends upon the relative location of the vegetation features and the micro-relief features with respect to the observer and the target. For example, features close to the observer tend to have a greater impact on concealment probability than do those further away. See Sections 2.5, 2.10, and 2.11 in Volume II for concealment analysis and description of equations.

This total line-of-sight decision calculation is made by Subroutine TERCON which in turn calls eight other terrain subroutines as illustrated in Figure 2.19. Here, Subroutines MICSOL and MITFEA essentially determine if a target is on a micro-relief feature or on an obstacle such as a swamp. Both of these factors are used to adjust the height of the target



Figure 2.16, Micro-Relief Features



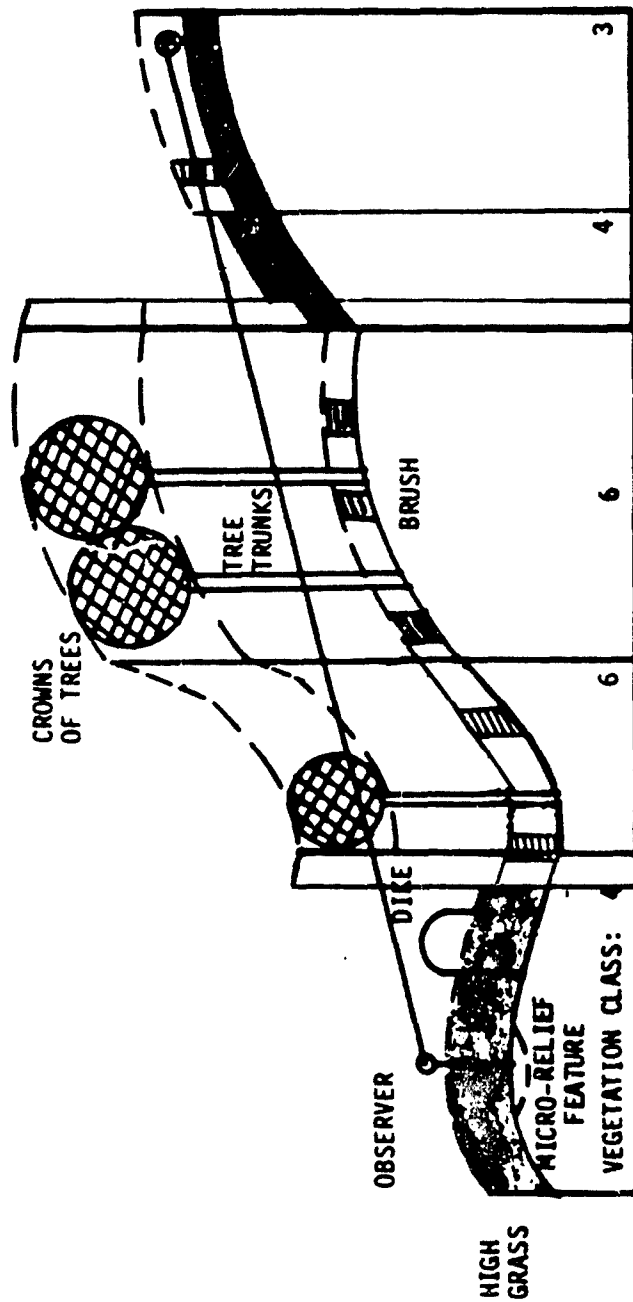


Figure 2.18, General Line-of-Sight Situation "Profile View"

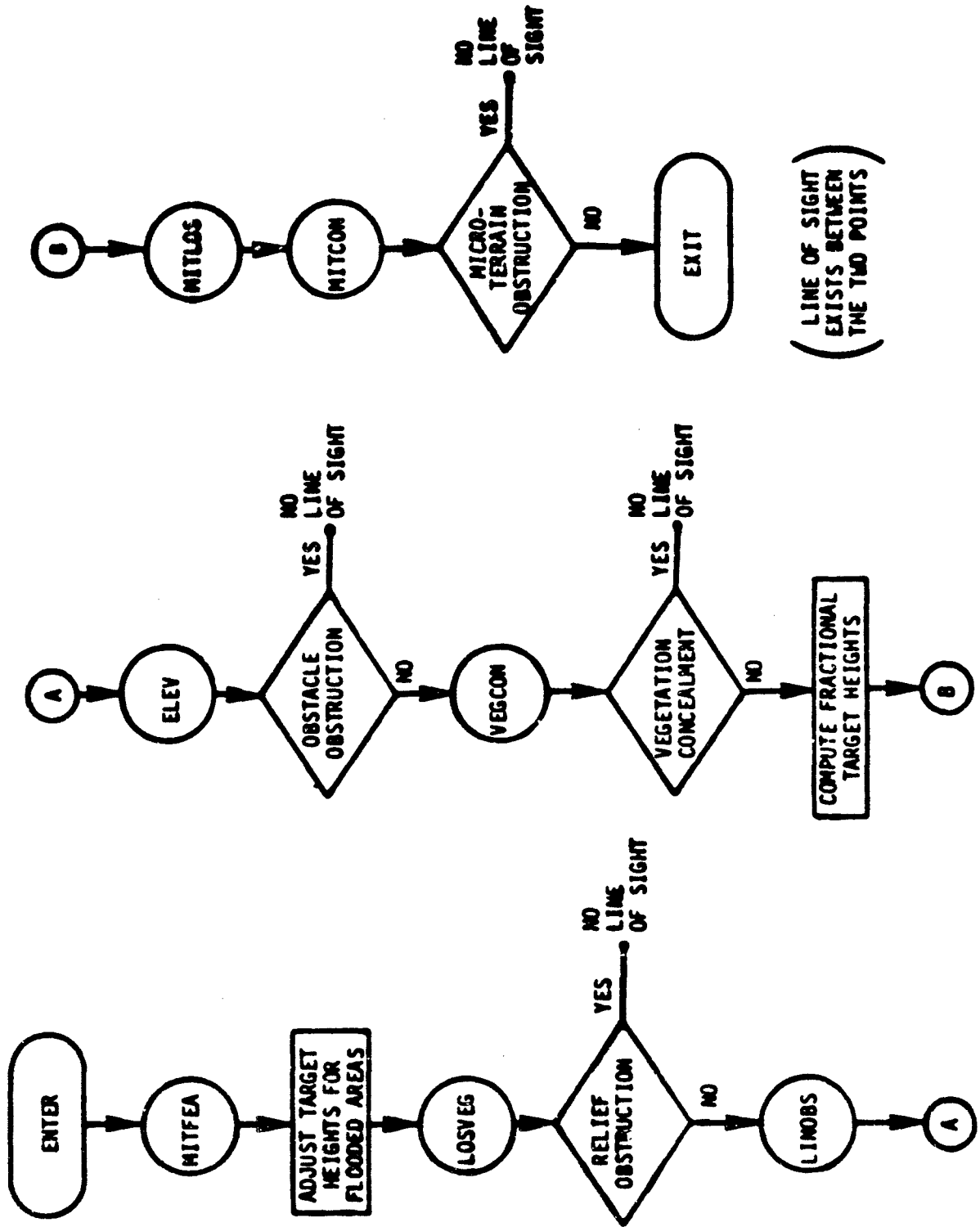


Figure 2.19, Terrain Concealment Subroutine (TERCON)

appropriately. Next, Subroutine LOSVEG is called and determines if there is a relief intercept between the two points of interest. If so, a no-line-of-sight verdict is returned by the subroutine. If there is not a relief obstruction, Subroutines LINOBS and ELEV are next called. These subroutines essentially determine if there is an obstacle between the two points of interest and determine the elevation of the obstacle. Based upon these calculations, a check is made for an obstacle obstruction and a line-of-sight/no-line-of-sight verdict is again made as shown in Figure 2.19. If line of sight exists, then Subroutine VEGCON is called to check the vegetation concealment. As part of this calculation it could turn out that a target is partially concealed because of vegetation. If so, the area of the target visible is calculated. The final two subroutines, called MITLOS and MITCON, determine if there is a micro-relief obstruction between the two points of interest.

In summary, Subroutine TERCON determines if there is line of sight between any two points in the area of operations. The line-of-sight verdict is based upon an examination of relief, obstacles and cultural features, vegetation, and micro-relief which exists between the two points under consideration.

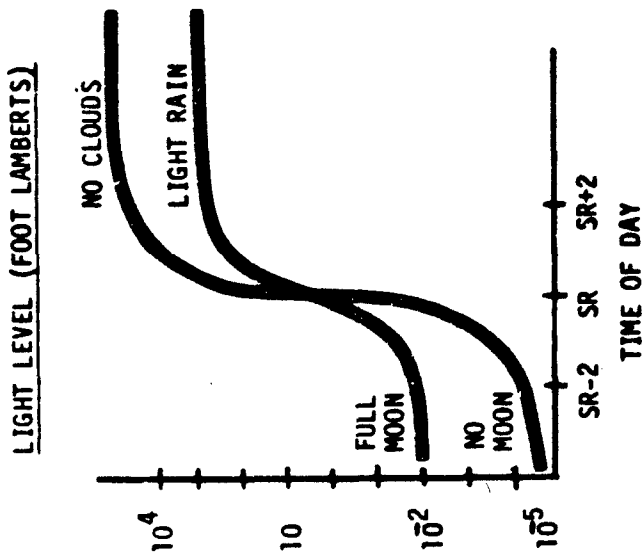
2.4.2 SIAF Weather Model

Figure 2.20 shows Weather Subroutine variables for weather classification, light level, temperature, and wind velocity. In the model, these variables are functions of time. When a subroutine needs a particular weather variable, the model simply examines the weather variables at the time in question and selects the appropriate values. The 11 classes of weather which vary from clear to heavy fog are input by the user as a function of time. Figure 2.21 is an example of the procedure to input variables for the Weather Subroutine.

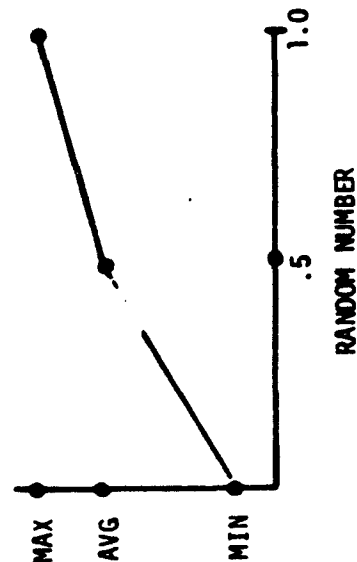
The light level data of Figure 2.20 (foot lamberts versus time) were obtained from Reference 1 and, as shown, varies rapidly near sunrise (SR) and sunset (SS). (Only sunrise is illustrated in the Figure since sunset is essentially the reverse of this.) The model also considers the interaction of these basic light level data with the weather in that the light level is degraded appropriately depending upon the weather conditions which exist at the time the light level is sampled.

WEATHER CLASSIFICATION SCHEME

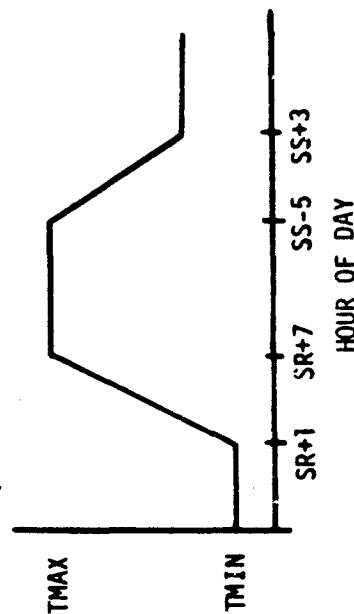
- 1 VERY CLEAR
- 2 CLEAR
- 3 LIGHT OVERCAST
- 4 HEAVY OVERCAST
- 5 HAZE
- 6 LIGHT RAIN
- 7 MODERATE RAIN
- 8 HEAVY RAIN
- 9 LIGHT FOG/DUST
- 10 MODERATE FOG/DUST
- 11 HEAVY FOG/DUST



WIND VELOCITY



TEMPERATURE
(TYPICAL CHARACTERISTIC)*



*Use local data for time scale.

DAY	MOON		MOON TYPE	TEMPERATURE		RELATIVE HUMIDITY		WIND VELOCITY (KNOTS)			WIND DIRECTION
	RISE	SET		MAX	MIN	MAX	MIN	MIN	AVG	MAX	
01	1148	0156	1st Q.	78°F	30°F	98%	24%	0	2	7	360
02	1249	0235	"	84	32	98	16	0	0.25	2	330
03	1349	0307	"	78	32	99	18	0	0	0	0
04	1446	0335	"	60	41	99	45	0	1	8	320
05	1542	0400	"	59	32	99	46	0	2	8	060
06	1638	0423	"	68	26	99	27	0	3	12	090
07	1733	0446	"	66	32	98	32	0	5	18	250

Figure 2.21. Example Weather Input Values

The temperature curve was derived empirically from data collected at Los Angeles Civic Center and Hunter Liggett Military Reservation. Examination of these data revealed that the temperature begins to increase approximately one hour after sunrise (SR) and reaches its maximum value about seven hours after sunrise. Then it stays relatively constant with time, starts decreasing approximately five hours before sunset (SS), and reaches its minimum value at three hours after sunset. Based upon these observations, the temperature model shown in Figure 2.20 was constructed. The maximum and minimum temperatures and the time scale for any locality for each day of the operation would be input by the user; then the model will generate a curve as shown in the Figure. Relative humidity (not shown) is treated in a similar manner, but it decreases as temperature increases.

Finally, the maximum, average, and minimum wind velocity is input by the user, and a random number is drawn to determine the appropriate velocity. Wind direction is input as constant. This sample procedure essentially accounts for gusts. If a constant wind scenario is desired, the user can simulate this by equating the minimum, average, and maximum velocities.

2.4.3 Enemy Situation

Three options are provided in the model for treating the enemy. These are illustrated in Figure 2.22. As shown in the Figure, the user can have fixed enemy positions, can simulate an enemy movement in a random manner within a circular area of operations, or can simulate the enemy moving on a pre-planned path. For the random movement within a circle on the fixed targets, the user can either pre-select the initial positions of these targets or can have the computer select these positions at random. Targets such as trucks, personnel, and enemy caches are simulated by inputting appropriate target characteristics. Analyses and discussion of target movement are contained in Sections 4.1 and 4.3 of Volume II.

Subroutines pertaining to the SI&F functions are described next. These subroutines are exercised for each segment as discussed in Section 2.3.

2.4.4 Movement

This subroutine calculates the movement rate of the patrol to be consistent with maintaining good surveillance and detection capability. Figure 2.23 presents a simplified flow diagram of how this movement rate,

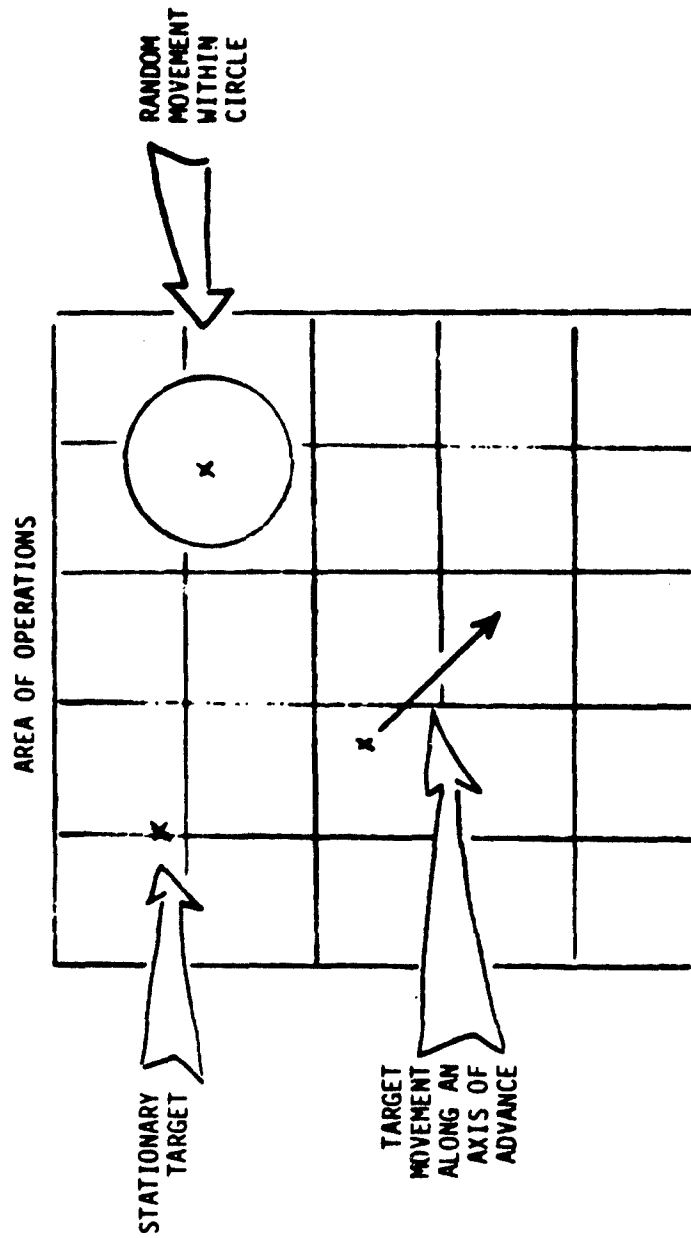
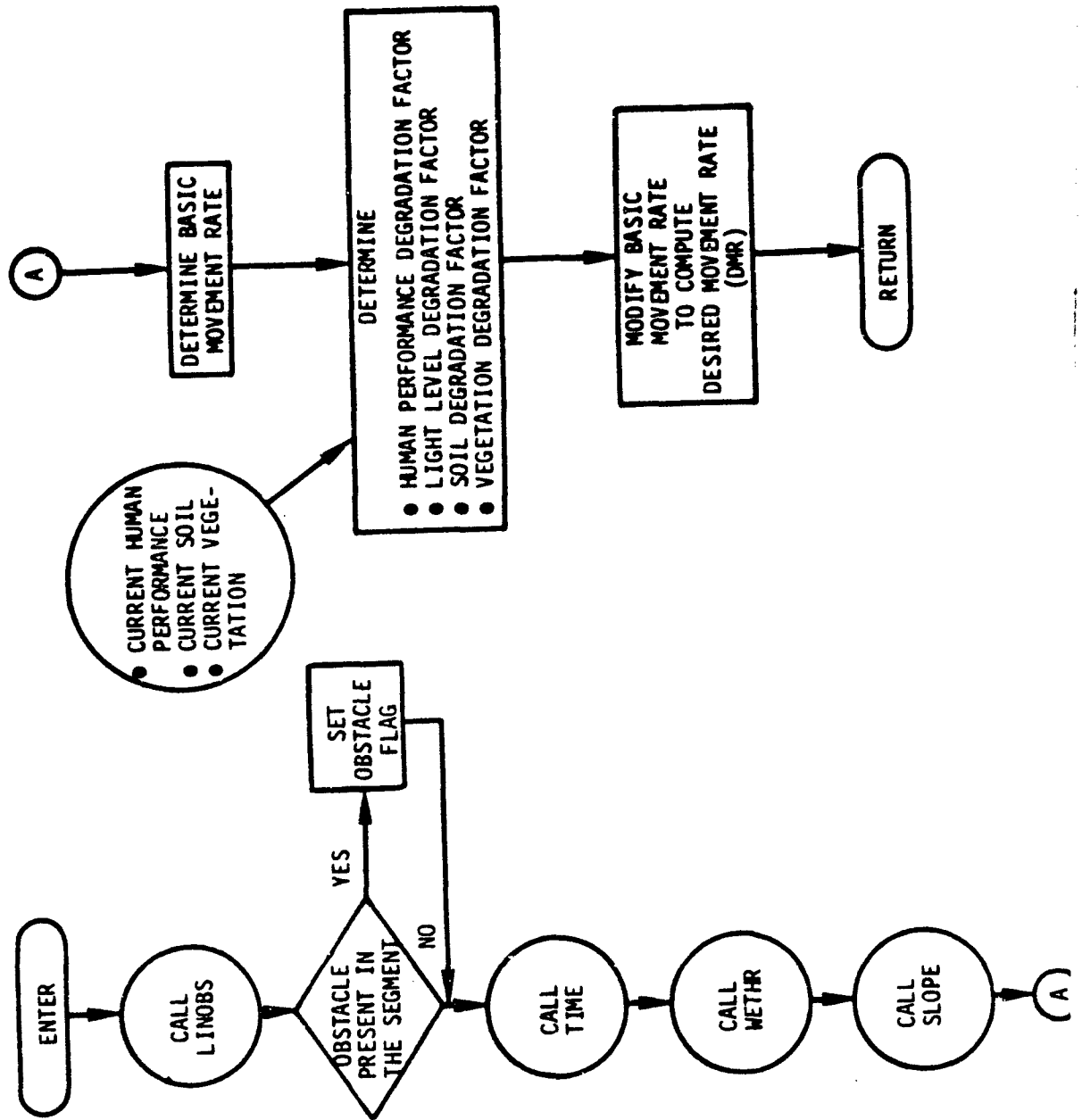


Figure 2.22, SIAF Model Threat Options



called desired movement rate, is calculated. Upon entering this subroutine, a distance segment (see Figure 2.5), based upon the minimum of the distance to a checkpoint, terrain polygon crossing, or grid crossing, has already been calculated by a segment generator subroutine (see Volume III). The first check made in this subroutine is one to determine if the segment intersects a linear obstacle. For this purpose, Subroutine LINOBS is called and an appropriate flag is set if required. After this calculation, Subroutines Time, Weather, and Slope are called as shown in Figure 2.23, and a basic patrol movement rate is determined by means of a table look-up procedure. This movement rate is then modified to account for the current human performance level of the patrol, and the current soil and vegetation the patrol is moving through (these interactions among subroutines are illustrated by means of circles in Figure 2.23). The output of this subroutine is called the desired movement rate and is defined as that movement rate consistent with good surveillance and detection capability.

Although a desired patrol movement rate has been determined in the previous subroutine, it could turn out that time contingencies require that the patrol move faster than this rate. In order to determine an actual patrol movement rate, a movement command and control subroutine, illustrated in Figure 2.24, is used. As shown in the Figure, the checkpoints from the present patrol position to the end of the patrol route are first checked to determine if there is an arrival time constraint associated with any of them. If not, the actual movement rate is set equal to the desired movement rate. If a checkpoint has an associated arrival time, then the required movement rate, based upon the distance from the patrol to the checkpoint, and the remaining time is calculated. These calculations essentially simulate the commander's estimate of his required movement rate which he would obtain in a similar manner.

Since it is possible that this required movement rate could exceed certain human and physical, environmentally constrained limits, both critical and marginal movement rate limits are next calculated. This marginal movement rate limit is defined as the minimum of the desired movement rate and a 10 percent margin associated with a movement rate consistent with zero body heat storage. The critical movement rate is defined as the minimum of three times the desired movement rate (which is

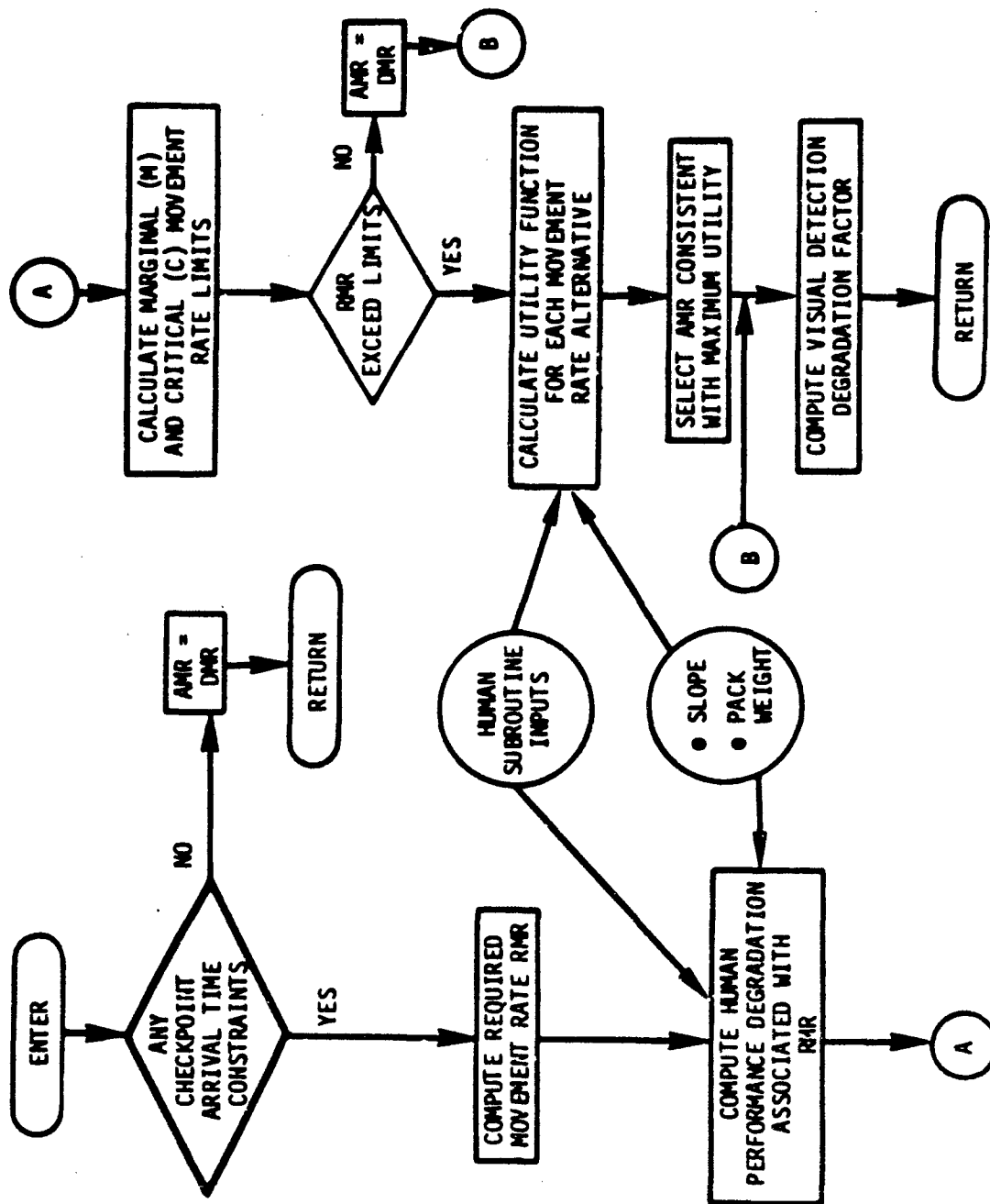


Figure 2.24. Movement Command and Control Subroutine (CCMOV)

estimated to be the nominal movement rate due to the terrain and weather) and that movement rate at which the body just maintains thermal equilibrium. As shown in Figure 2.24, these factors are functions of the current status of the patrol which is available in the communication block of the program. If the required movement rate is less than these limits, then the actual movement rate is set equal to the desired movement rate. If the required rate exceeds these limits, then the patrol leader must trade off his surveillance capability and time. For this purpose, weighting factors for each of these performance variables are provided as input, thus allowing the user the capability to consider alternative movement rate tactics. Based upon these input weighting factors, an actual patrol movement rate is selected and the visual performance degradation factor associated with this movement rate (used by the Visual Detection Subroutine) is calculated.

2.4.5 Navigation

The purpose of this subroutine is to determine the CEP of the patrol location. During the conduct of a mission, the patrol normally determines its location at the various checkpoints and reports its position to the base. However, if a target is detected or another contingency develops, the patrol may need to know its location at positions in between checkpoints. This location error is a function of the distance the patrol has traveled since it last updated its position. Figure 2.25 summarizes the calculations made in this subroutine which starts by computing the range and azimuth errors associated with navigation from the last checkpoint. These dead-reckoning errors are then combined with map, base, and recording errors, and a basic patrol CEP is calculated. Next, the user has the option of adjusting this calculated CEP in accordance with the specifications provided in Reference 2. Independent of these specifications, the patrol could improve its initial estimate of its location by map terrain association if the light level is favorable. This essentially adjusts the location estimate to account for readily identifiable terrain features which the patrol leader could use to more accurately determine his position. Finally, the user has the option of specifying certain patrol location equipment which aids the patrol in determining its position. If this equipment is specified, then the patrol location is adjusted, based upon the amount of

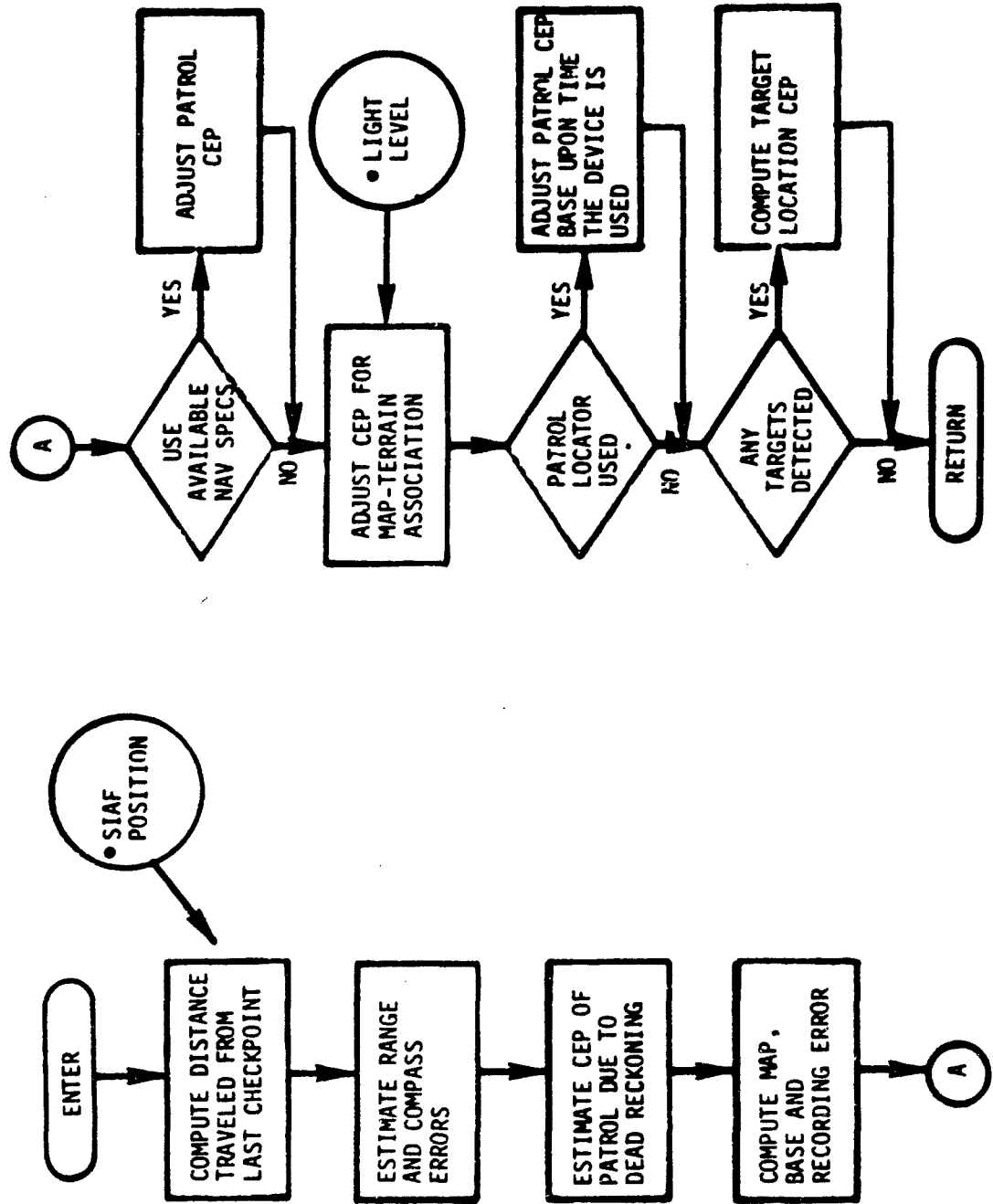


Figure 2.25, Navigation Subroutine (NAV)

time this equipment is used. These steps serve to determine a CEP of the patrol location. As shown in Figure 2.25, if a target is detected, this subroutine also calculates the CEP of the location of the target with respect to the patrol. This calculation is based upon considerations similar to those previously described.

2.4.6 Surveillance/Detection

Aural Detection

The purpose of this subroutine is to determine an aural detection verdict for SIAF against the targets in the area of operations and for the targets against SIAF. The aural detection capability of an individual depends upon the local background sound level and the sound level being made by the individual. The first calculation made in this subroutine, shown in Figure 2.26, is to determine the local aural background level for SIAF and for the targets. This background level is a function of the vegetation, time of day, and weather. Next, the source noise level for SIAF and the targets is computed. This source noise level depends upon the number of men in the unit, their disposition, and their present activity. If, for example, the patrol is moving through heavy vegetation, then its source noise level is considerably higher than it would be if the patrol were conducting a stationary reconnaissance. Based upon these two calculations, the sound level arriving at the listener is computed (considering range and vegetation attenuation) and is compared with the hearing threshold and the local background noise. If the threshold is exceeded, then the appropriate detection opportunity is stored in a vector for subsequent analysis by the Detect and Decision Subroutines.

Visual Detection

The Visual Detection Subroutine is illustrated in Figure 2.27. The purpose of this subroutine is to calculate probability of making a single glimpse, visual detection of targets that are feasible of being detected by SIAF, and for targets to detect SIAF. In this calculation, line of sight between SIAF and the targets is assumed. Hence, the calculation mainly considers light level for the detection computation. As shown in Figure 2.27, the first calculation is to determine the target reflectance, background reflectance, the light level at the target, and the light level

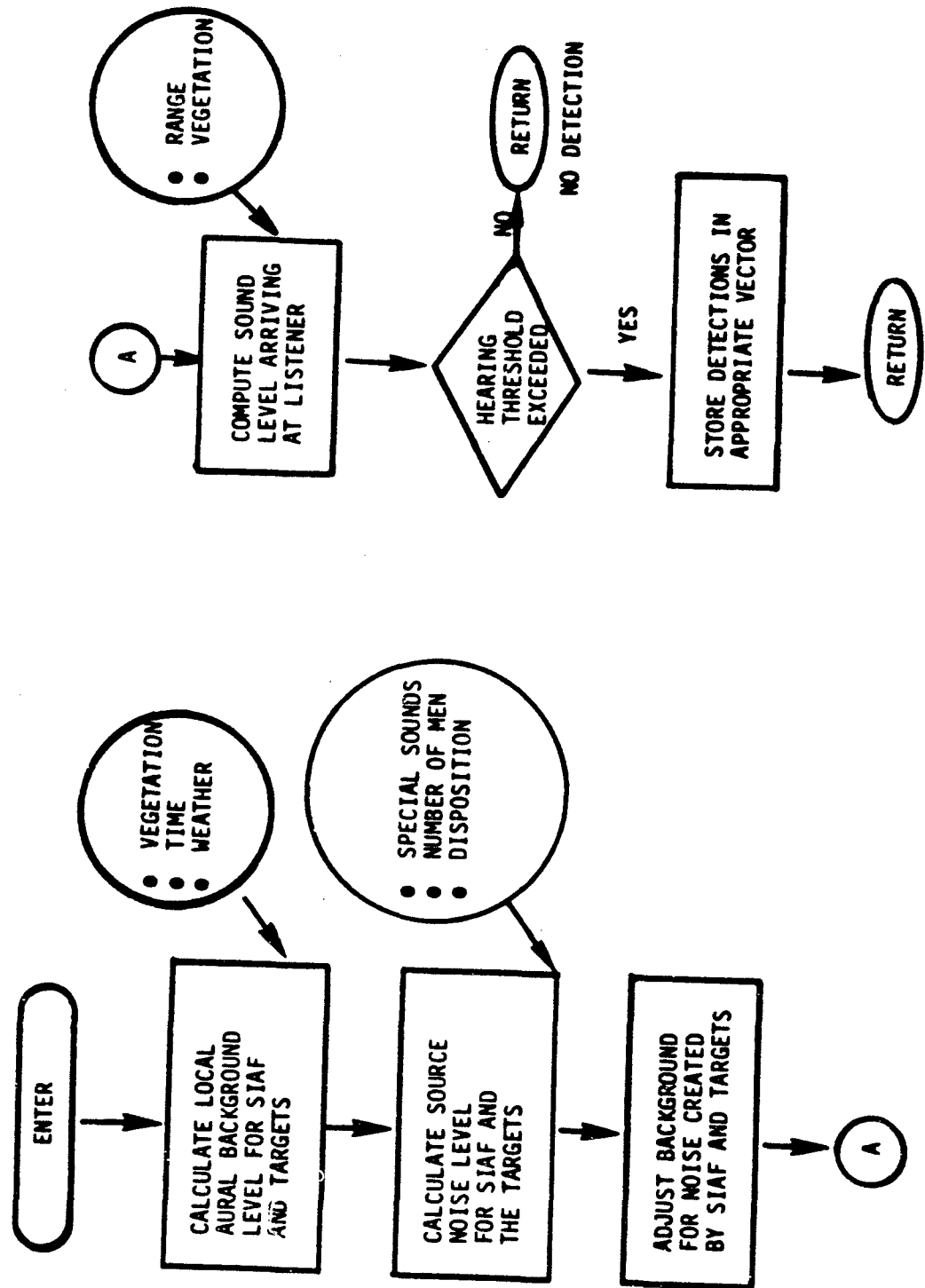


Figure 2.26, Aural Detection Subroutine (AURAL)

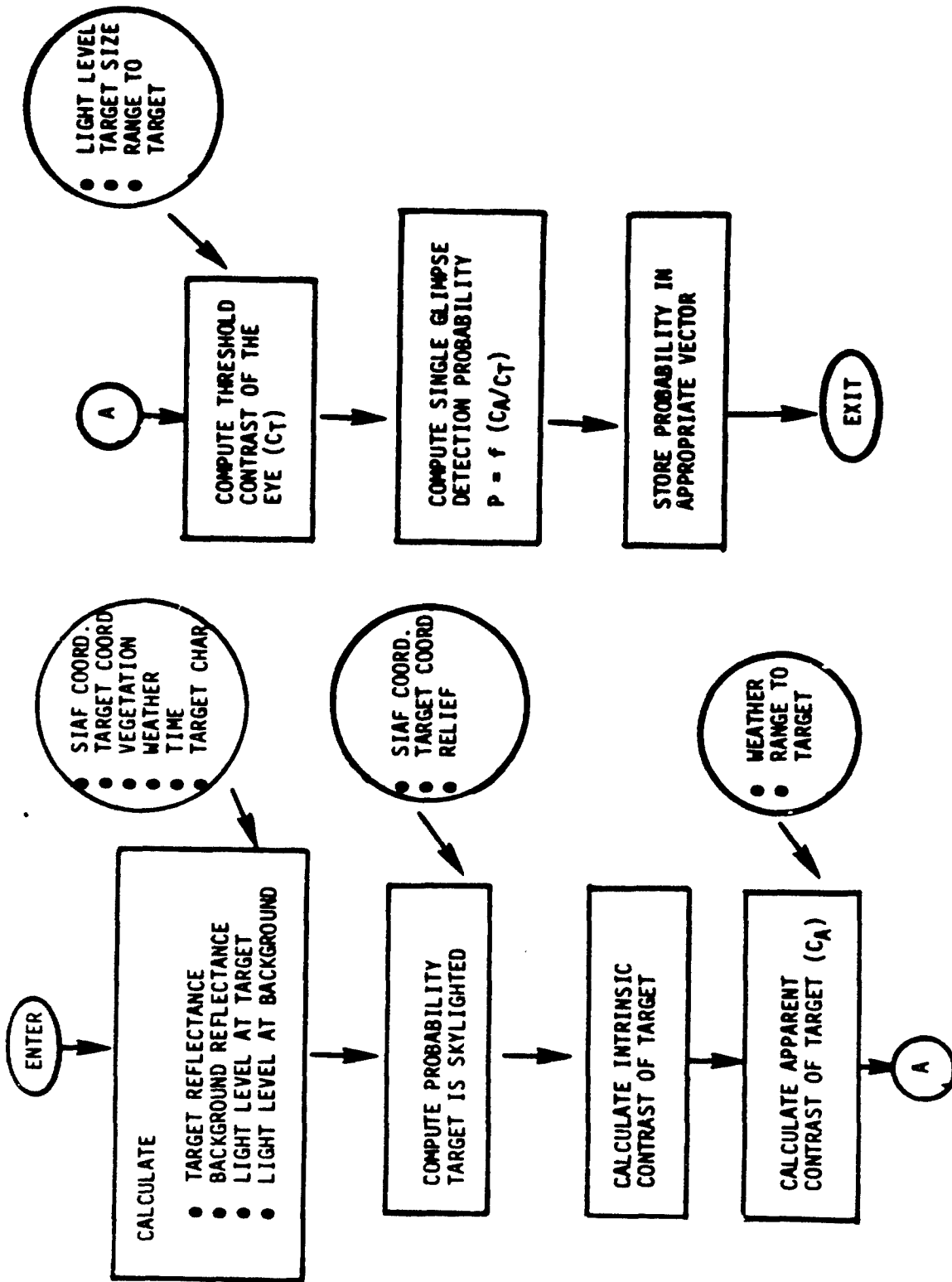


Figure 2.27. Visual Detection Subroutine (VISUAL)

of the background. Depending upon the location of SIAF and the particular target under consideration, there is a possibility that the target may be skylighted. The next calculation is then made using the Terrain Concealment Subroutine to determine background conditions, including skylighting. Based upon this information, the intrinsic contrast of the target is computed. This intrinsic contrast is essentially the ratio of the brightness of the target to the brightness of the background. Depending upon the range between SIAF and the target and the weather conditions, the contrast of the target as observed by the eye differs from the intrinsic contrast. This is called apparent contrast and is next calculated considering the factors mentioned above. The third contrast calculated in this subroutine is threshold contrast of the eye. As indicated in Figure 2.27, this threshold contrast is a function of the light level, target size, and the range to the target. The ratio of apparent contrast to threshold contrast is then used to determine a single glimpse detection probability. This probability is then stored in an appropriate vector as further indicated in Figure 2.27.

Detect

The described calculations serve to determine detection opportunities and are independent of line of sight. Subroutine Detect, illustrated in Figure 2.28, combines these calculations with the relief and vegetation and considers the physical location of SIAF and the target. As mentioned previously in Section 2.3, this detection calculation is made once for each mini-segment and can consider man-to-man detection if desired by the user. The first calculation made is to determine which patrol members are looking in the correct sector to potentially see the target. If, for example, no patrol members are viewing any targets, then detection is not feasible. For all feasible targets, Subroutines TERCON, AURAL, and VISUAL are next called. These subroutines essentially examine line of sight between SIAF and the target, sound levels made by SIAF and the target, and light level to determine whether detection or several detections can possibly occur in the mini-segment. Based upon this information and the time available, detection verdicts are calculated in a Monte Carlo fashion for SIAF and all detectable targets. The order and interval between detections is created to identify who sees who first and later is used in the decision model to determine simultaneous detection/counterdetection situations.

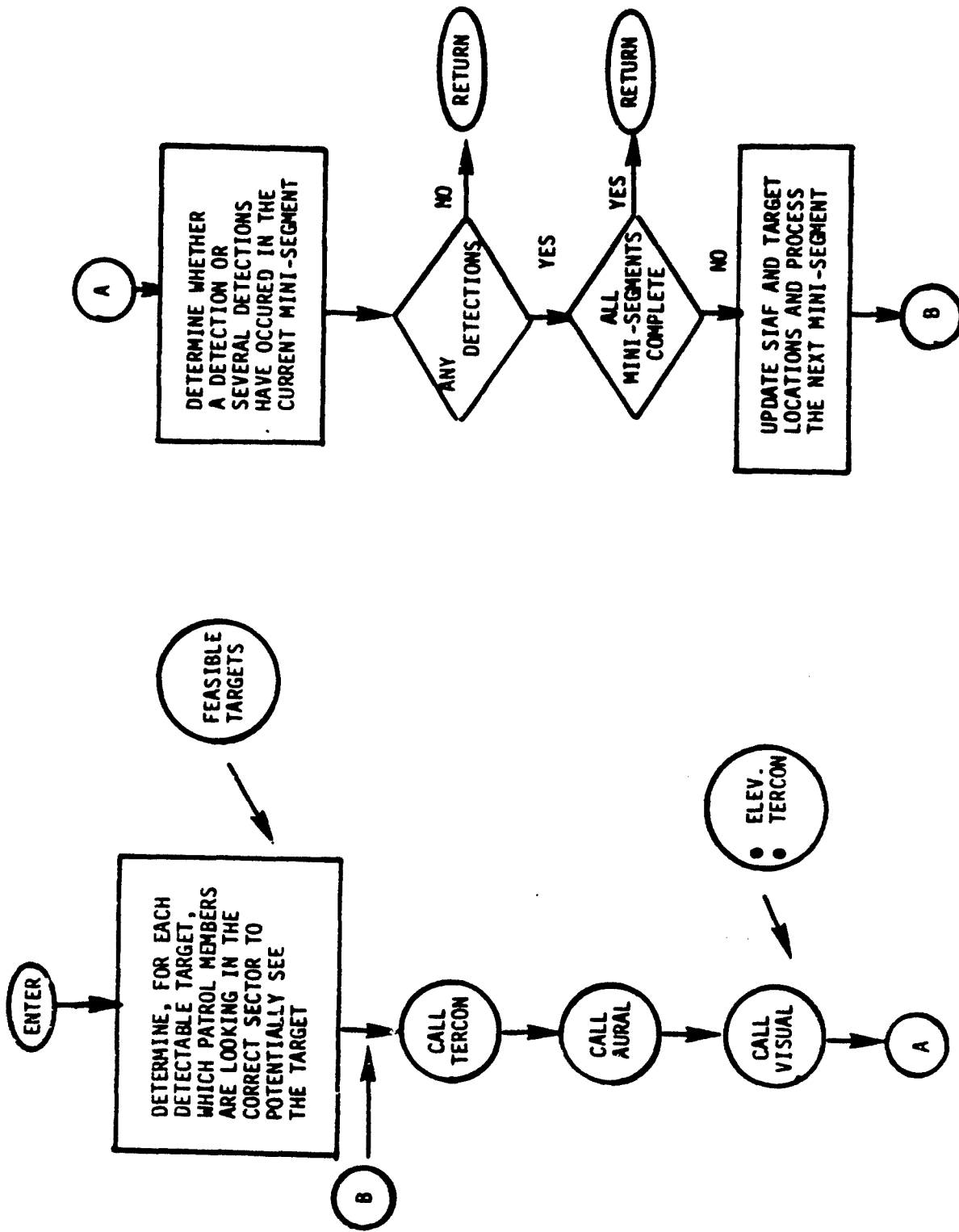


Figure 2.28, Detection Subroutine (DETECT)

2.4.7 Fire Support

If a patrol detects a target, it may elect to direct fire on the target, without engaging in a firefight depending upon the mission and the situation at the time of detection. For this purpose, an external fire support subroutine (EPS) is called by the Executive Routine. As shown in Figure 2.29, the user can select air, artillery, or manual gunfire for analysis. If air is selected, then the assumption is made that the target movement provides negligible error in ordnance delivery CEP. Because of the response time of artillery and naval guns, a moving target could introduce decreased accuracy in delivery CEP; hence, the user can examine this situation if desired. As shown in Figure 2.29, factors such as surprise and adjusted fire, target reaction to the first round hit, and the interactions of the effectiveness of the fire support mission with the patrol and target location errors are considered. If preliminary fire support is to be used prior to attacking a target, a detailed simulation of external fire support effectiveness is used. This is discussed in the Combat Submodel description.

2.4.8 Supply Maintenance

The Supply Maintenance Subroutine illustrated in Figure 2.30 is essentially a booking subroutine which increments and/or decrements the supply status of the patrol during each segment. As shown in the Figure, food, water, ammunition, and pack weight are incremented if the patrol was resupplied during the last segment and decremented for combat operation and for normal food and water consumption. The normal food and water consumption requirements are calculated in the Human Maintenance Subroutine which follows.

2.4.9 Human Maintenance

This subroutine computes food and water requirements for the patrol and calculates the current human performance degradation of the patrol. As illustrated in Figure 2.31, the current energy expenditure rate of the patrol members is first determined. This is based on the current patrol activity which includes rest, sleep, stationary reconnaissance activities, or movement. During movement, the energy expenditure rate is a function of the slope, pack weight, and movement rate, for which values are available to this subroutine via the communication block of the program. Once the energy expenditure rate is determined, the value of the segment time is used

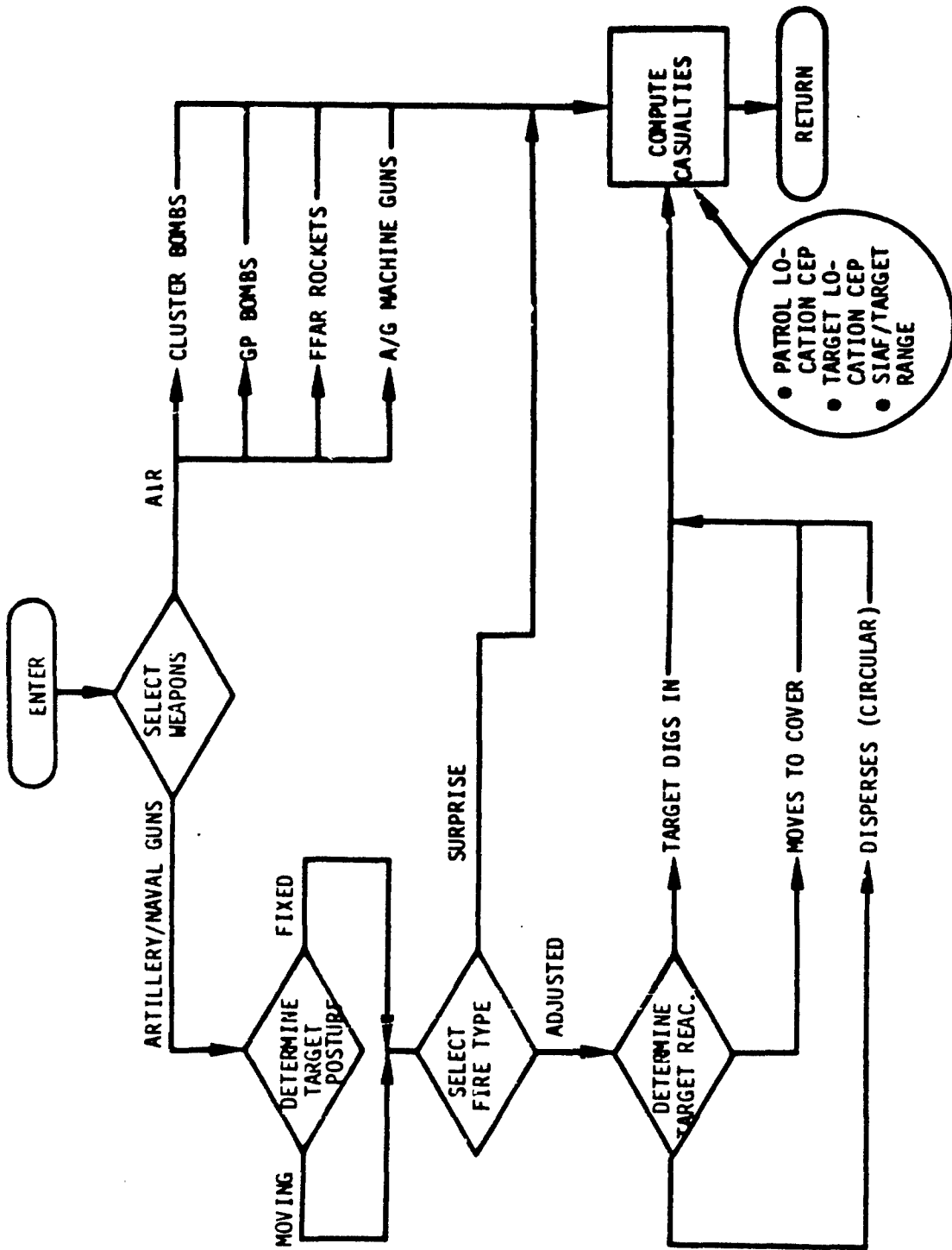


Figure 2.29, External Fire Support Subroutine (EFS)

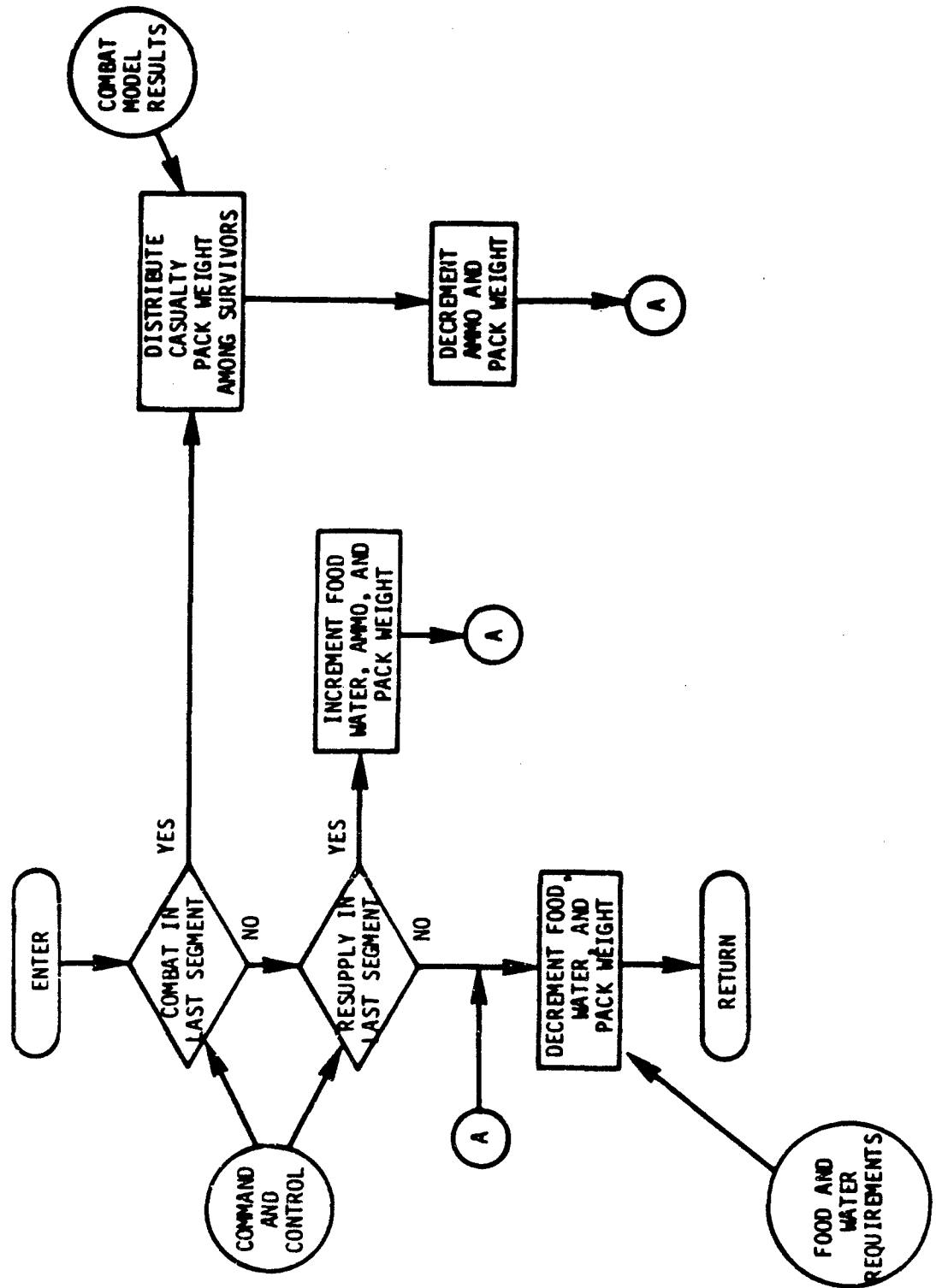


Figure 2.30. Supply Maintenance Subroutine (LOGIS)

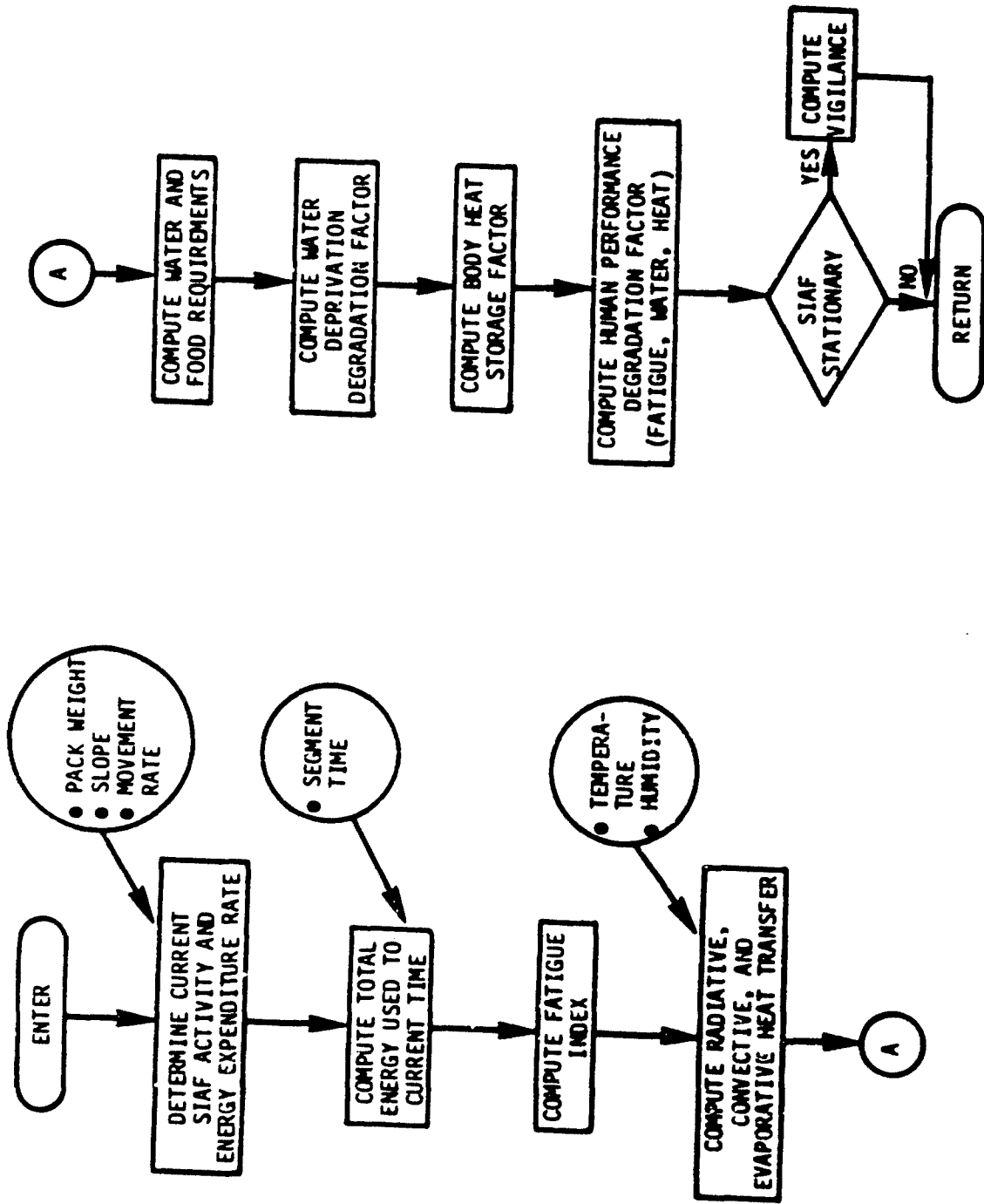


Figure 2.31, Human Maintenance Subroutine (HUMAN)

to compute energy expenditure and an associated fatigue index as shown in Figure 2.31. This energy expenditure is then used to compute the body heat lost through radiation, convection and evaporation. From this, food and water requirements and body heat storage are calculated. These factors are then combined and a human performance degradation factor is computed. This human performance degradation factor is the amount in percent by which the performance of patrol functions such as visual detection are degraded due to fatigue, body heat storage, and water deprivation. In addition, visual detection performance is influenced by a factor called vigilance which accounts for the decrease in the alertness of patrol members as a function of the time they have been conducting stationary reconnaissance operations. If the patrol is stationary, this calculation is also made as shown in Figure 2.31.

2.4.10 External Communications

The External Communications Subroutine shown in Figure 2.32 calculates an external communication verdict for the patrol on each communication attempt. First, the total ampere hours currently available to the patrol are computed to determine if the battery life is expended. If so, a no-communication verdict is returned by the subroutine. If power is available, then a power budget analysis is conducted; and vegetation, defraction, and space losses are computed. These calculations depend upon the current distance from the patrol to the base and the terrain between SIAF and the base. The results of this power budget are used to compute the signal-to-noise ratio at the receiver. This signal-to-noise ratio is then used to compute message intelligibility. As shown in Figure 2.32, the model simulates the actions of the patrol repeating the message until the intelligibility criteria (a user input) is satisfied. If the intelligibility criteria is not satisfied with N trials (N is a user input), then a no-communications verdict is returned by the subroutine. If the criteria is satisfied, then the communication is said to be successful.

2.4.11 Command and Control

The current SIAF command and control model consists of a movement command and control subroutine (described in Section 9.1) and a post detection decision subroutine (Section 9.2).

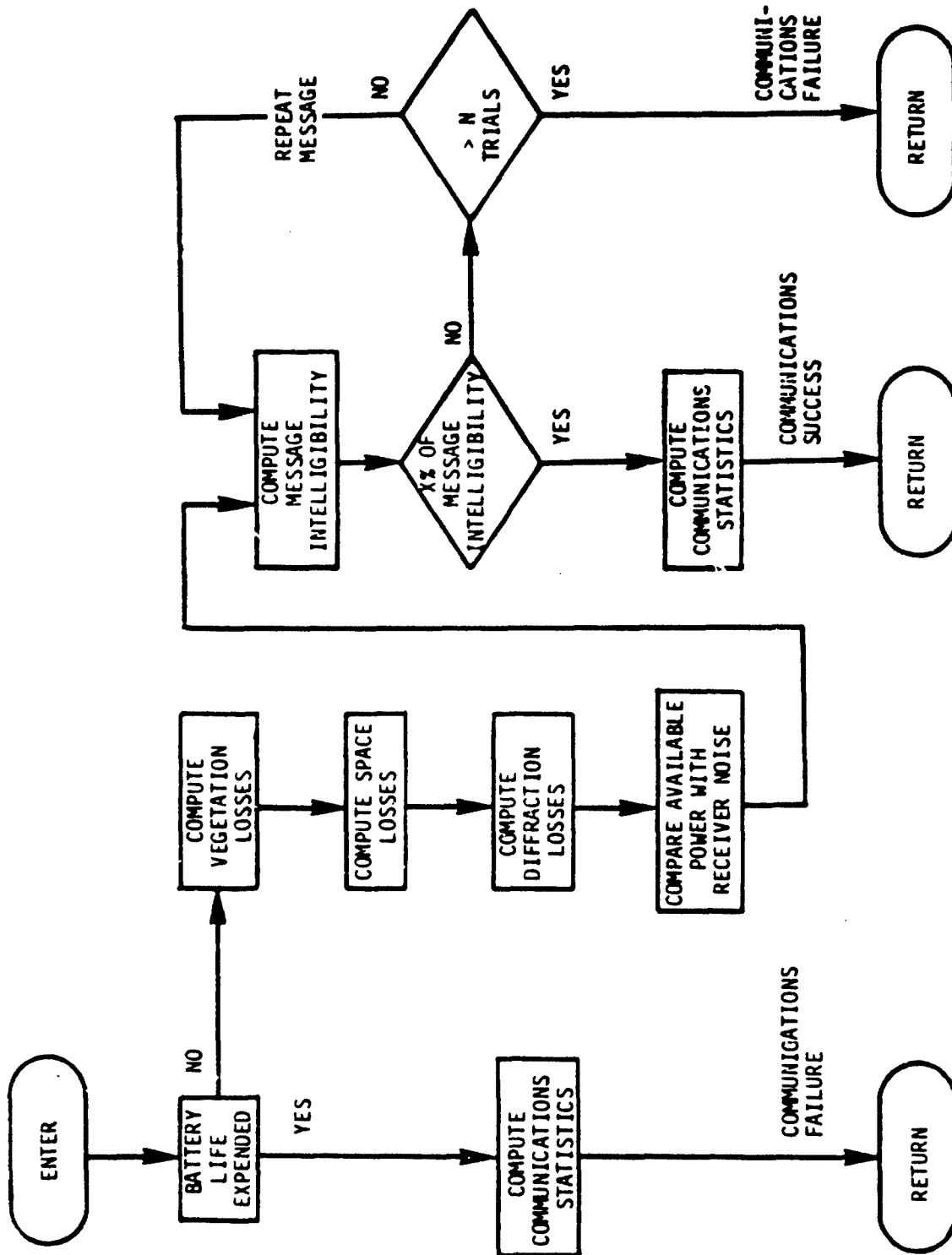


Figure 2.32, External Communications Subroutine (EXCOM)

With respect to patrol movement, the required movement rate which a patrol must sustain in order to arrive at a next checkpoint on time is compared with a desired movement rate that is consistent with being able to maintain good surveillance. If the required rate exceeds the desired rate, trade-offs are made between time and detection performance to select the most satisfactory movement rate for the patrol. The trade-off results can be controlled by adjusting input weighting factors.

In the post detection subroutine of Section 9.2, alternatives are provided which cause the patrol to move along a dynamic route toward the target to identify it or to move around the target to avoid it. Logic is also provided for calling external fire support on targets. Input variables are provided which allow the user the capability of exercising these model options (see Section 9.0 for details).

2.5 SIAF COMBAT SUBROUTINES

Thus far an overview of the reconnaissance model has been presented in previous sections. Once the SIAF patrol detects a target, however, it may decide to combat the target, and once the combat is completed the patrol may decide to continue the reconnaissance mission. The SIAF model considers these possibilities. In the following section an overview of the combat decision and execution subroutines are presented. (Details of these routines are described in Volumes V and VI.) Included is a description of the decision logic and decision optimization routines, and a discussion of the combat executive routine. Finally an overview of the withdrawal and the continue mission routine which allows the patrol to continue on its reconnaissance mission once the combat operating is completed, is presented.

2.5.1 Combat Decision Logic and Optimization Logic

In the SIAF reconnaissance model many detection and identification possibilities exist. For example, the SIAF patrol could possibly identify two targets simultaneously or several targets could identify and detect SIAF at the same time. Because of the complications involved in developing logic to model these situations, combat operations where more than one target is involved are not considered in the model. Instead if it turns out that several targets detect SIAF or SIAF has detected and identified several targets then a no combat decision is made and the SIAF patrol avoids the

targets. Considering the fact that SIAF normally operates as an independent force this is probably a reasonable simulation of what they would in fact do. That is, should they detect and identify more than one target they would probably avoid the target area.

Now consider the case in the simulation model where SIAF detects and identifies a single target. In this case if its mission is combat, the patrol must decide what kind of combat action to initiate. Here decision logic is necessary since it is impossible to determine exactly where the patrol will be and exactly what and where the target is when the detection occurs during the simulation. Hence this logic dynamically examines the current tactical situation and selects a course of action. The movement to contact and deployment decision logic shown in Figure 2.33 indicates that five courses of action are possible. The first course of action is that the patrol could call in external fire support on the target. The second alternative is that the patrol could deploy for ambush. This alternative, for example, would probably be selected if the target were moving toward the SIAF patrol. On the other hand the target may be moving in a direction away from the patrol or may be out of range of the patrol. In this case the SIAF patrol could decide to move to a deployment position and call for external fire support if available, before initiating the fire fight. Another alternative, even before a detection occurs, is to move to an ambush area to deploy Claymore mines. The fifth alternative, of course, is a no combat decision. The decision logic subroutines examine the current tactical situation and select one of these alternatives based on the following decision variables.

- 1) Mission (ambush, attack, or deploy Claymore mines)
- 2) Force ratio (i.e., the relative size of the target vs the size of the SIAF)
- 3) SIAF-target range
- 4) Direction of travel of the target
- 5) The terrain between the SIAF patrol and the target as to its effects on cover, concealment, and observability.

The decision logic is constructed so that the user can adjust the input data and choose different criteria for selecting a course of action. Thus the decision variables are examined, the tactical situation determined by the model and a combat option is dynamically selected.

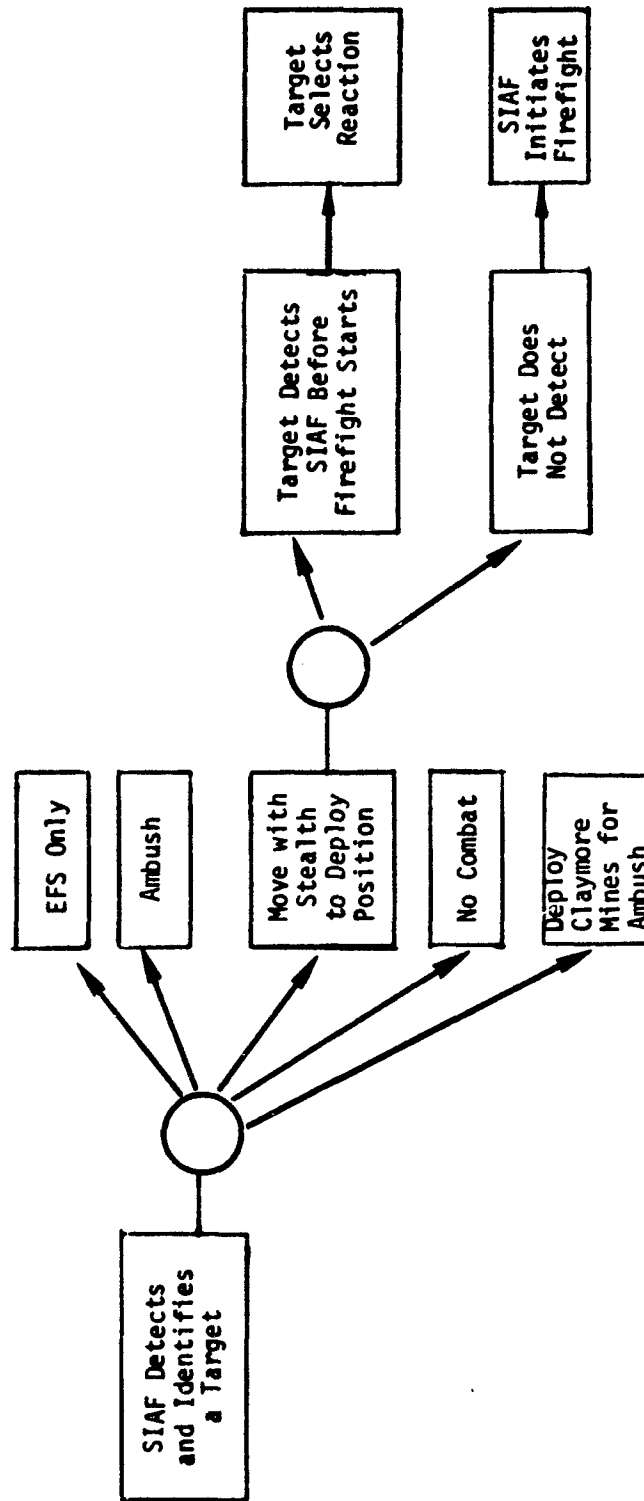


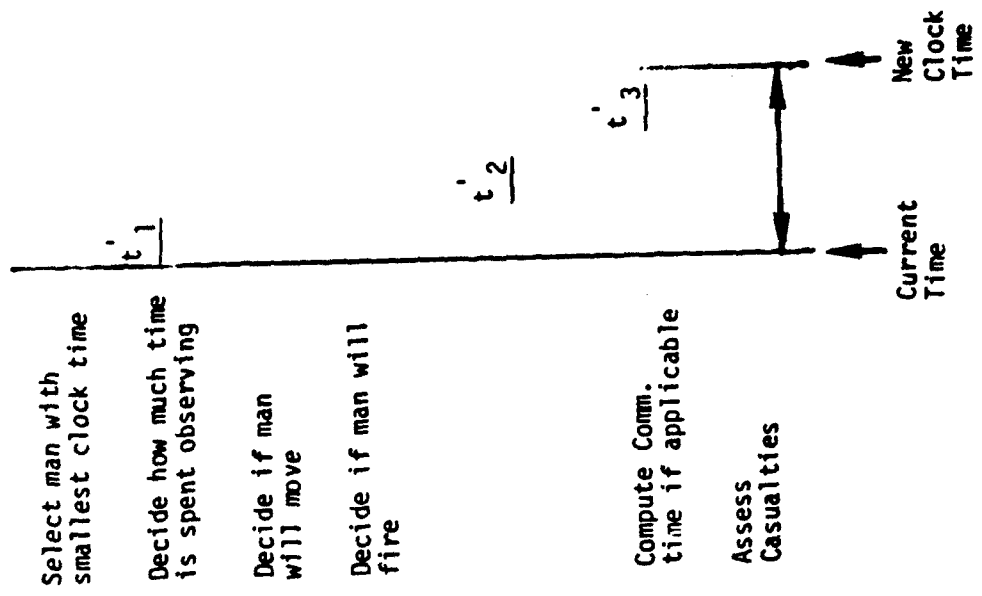
Figure 2.33, Movement to Contact and Deployment Logic

In the case of external fire support only the external fire support (EFS) subroutine is then called, external fire support simulated, and the patrol then makes a "continue the mission" decision and would probably, in this case, decide to return to continue the reconnaissance patrol. In the case where deployment is selected, optimization logic optimally selects the exact deployment position of each maneuver unit in the terrain. The most complicated situation evolves when the patrol decides to move to a deployment position. In this case the dynamic route selector routine (DROUTE) selects movement points based upon different movement criteria which again are user input. As shown in Figure 2.33 when the patrol is involved in this type of a movement the target could possibly detect the patrol before the fire fight occurs. In this event the target could react by moving, deploying, or opening fire. If, on the other hand, the target does not detect the patrol in movement to the deployment position, SIAF initiates the fire fight. If the target should move toward a better defensive position, the SIAF may reselect its deployment points or exchange roles between maneuver units and and the base of fire. Thus, the combat decision and optimization logic provide a mechanism for the user to select various combat alternatives based upon the current tactical situation.

2.5.2 Combat Executive

In Section 2.3 the executive routine used to drive a reconnaissance model was described. In this section an overview of the executive routine used to drive the combat model is presented. In this regard two approaches for driving the combat executive routine were examined. The following section describes and compares these two approaches.

The first alternative shown in Figure 2.34 indicates that each man in this situation has a clock time, initial values of which are selected to be different based upon user input. The model selects the man with the smallest clock time and decides how much time is to be spent observing in an intelligence routine, and computes this amount of time (t_1 in the figure). Then movement and fire controller models decide if the man will move or fire. If he is to fire, for example, the fire controller model decides at whom he will fire and computes the firing time (t_2 in the figure). If communications are to occur the time required for communications are also computed. Finally casualty assessments are made. After these calculations are made the clock time for this particular individual examined



Man	Clock Time
Man 1	t_1
Man 2	t_2
.	.
Man n	t_n

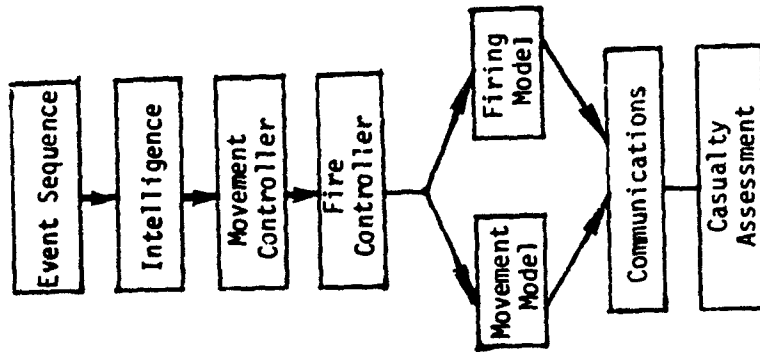


Figure 2.34, Alternative 1 to the Combat Executive

is advanced by the amount $t'_1 + t'_2 + t'_3$ and he is given a new clock time. The model then scans the list of men and clock times, picks out the minimum, and repeats the procedure. Thus, in alternative one, each man is individually cycled through functions that he is required to perform during combat and time is advanced in the fashion described above. This is the approach that is used in models such as DYNTACS and ASARS.

An alternative to this approach is presented in Figure 2.35. Here, instead of individually selecting each man and having a clock time associated with each man, only one clock time exists in the model. The event times in this case are movement, detection, casualty, EFS burst, and internal message reception. The executive routine computes the movement and detection event times for each individual for both the attacker and defender, and the casualty times of each individual for both the attacker and defender. It then scans this list of times together with any scheduled arrival of EFS and any scheduled reception of a message between maneuver units. It then selects the minimum time, and defines the corresponding event as the event which occurs in this particular segment of the model. Figure 2.35, for example, illustrates what would happen if the event were movement. In this case, all moving individuals would be moved an appropriate amount of ammunition, the clock time and the status of each man would be updated, and calculations would be repeated. Thus, instead of cycling through each man, this particular method examines the next event to occur for all men, advances the clock time based upon the minimum of these times, and updates the attributes of each man to what they would be at this time.

A comparison of these two approaches is shown in Figure 2.36 and here, three attributes were defined: running time, event accuracy, and capability to handle cumulative interactions. The comparison indicates that alternative one probably has a faster running time in most cases. However, arguments that alternative two could be faster are also possible to evolve. As far as event accuracy is concerned, alternative one could possibly neglect events which occur to other individuals during a given loop through the logic. The reason for this can be seen through a further examination of Figure 2.34 which shows that an individual could possibly become a casualty during the advance of his clock time. Thus, unless a time step variable is set to adjust the advance of

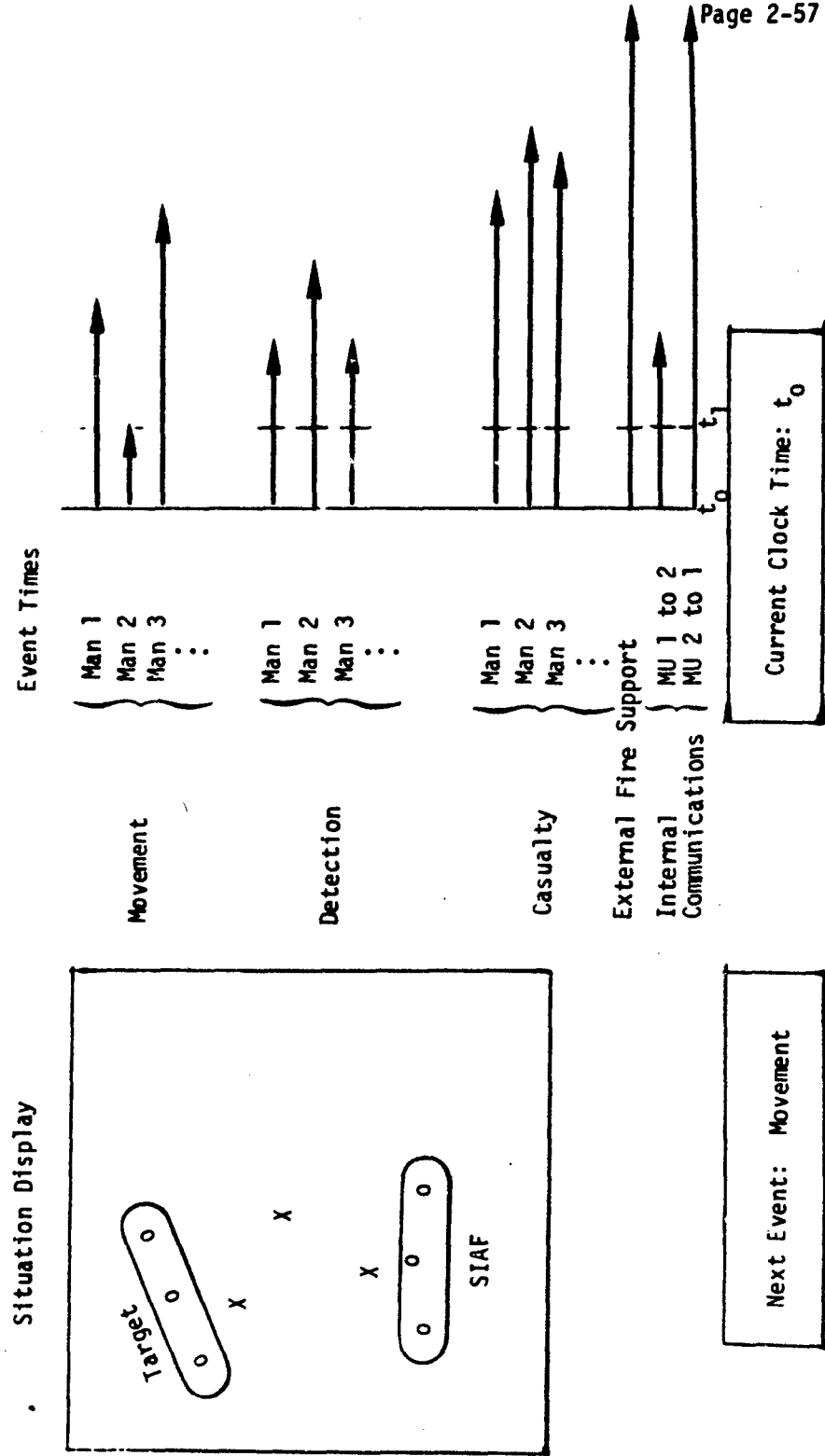
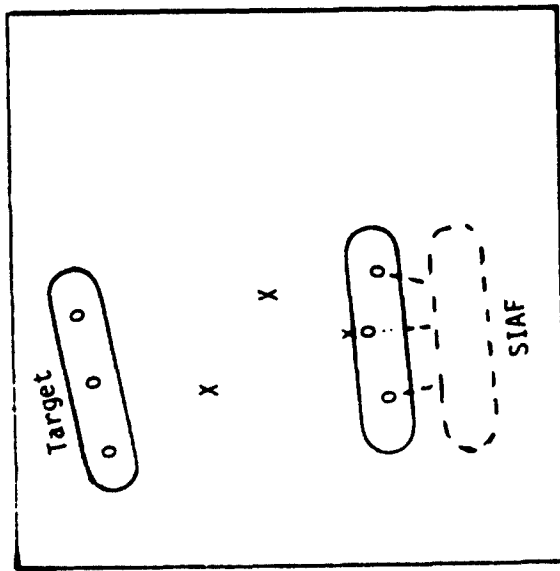
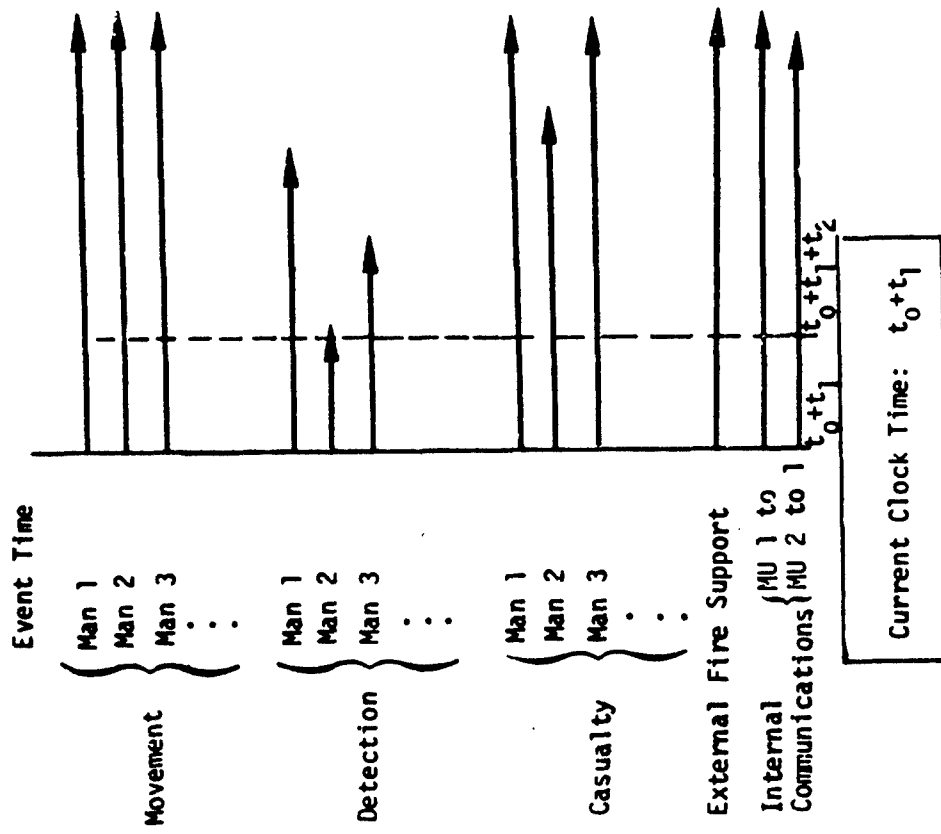


Figure 2.35, Alternative 2 to the Combat Executive (Sheet 1)



Next Event: detection

Figure 2.35, Alternative 2 to the Combat Executive (Sheet 2)

Attribute	Alternative 1	Alternative 2 SIAF Technique
Running time	Faster running time in most cases	Will normally run longer but could run faster than Alt. 1
Event Accuracy	Could neglect events which occur to other individuals during a given loop through the logic	Such events are not neglected since everyone is updated during each advance of the clock
Capacity to handle cumulative interaction	Suppression only considers one man firing at one and neglects simultaneous firing	Suppression includes the effect of many individuals firing at one (cumulative P _k table)

Figure 2.36. Comparison of Executive Alternatives

the clock, these types of events, which would tend to bias the results, could occur. With alternative two, such events are not neglected since the time of the first event for all individuals is first calculated and time is advanced in a fashion previously described. With respect to cumulative effects, alternative one neglects the fact that the suppression of an individual may be greater because three individuals may be firing at him rather than just one. Alternative two, on the other hand, can include these types of cumulative effects. As far as implementation goes, it is not clear that alternative one is superior to alternative two. Different logic is required for both alternatives, and a comparison is very difficult to make. Based upon the manner in which the reconnaissance model currently runs and an examination of these alternatives, alternative two was selected as the technique to be used for the SIAF combat model.

In summary, two executive routines are provided with the SIAF model. The first is the reconnaissance executive which operates in the manner described in Section 2.3. Once the detection and identification occurs the decision logic determines whether a combat action will occur. If a combat is to occur then the combat executive described above simulates this part of the mission. Once a combat mission is concluded and a decision is made to return to the reconnaissance operation, the reconnaissance executive routine described in Section 2.3 takes over and continues driving the model.

2.5.3 Data Structure and Manipulation

The SIAF combat model consists of a series of subroutines and an executive routine. The executive routine advances time in the manner previously described and calls individual subroutines to make various calculations. Interactions are considered and modeled by the subroutines which essentially update the attribute list of the target and SIAF shown in Figure 2.37. For example, ATT(1,1,1) is the fire team number of the first man in the attacker patrol. ATT(3,2,2) contains a value of the number of rounds remaining for man number 2 in the defender unit. The attribute matrix is a 25 x 20 x 2 matrix, and the attributes of each individual are changed by various subroutines depending upon the situation. For example, should movement occur then the current X and Y coordinates, attributes 7 and 8, of each individual involved in the movement are updated by the appropriate routine. Should a patrol member assume a different posture, then the height of the patrol member is

ATT(X,Y,Z)

Z is the Patrol Identifier

- 1: Attacker
- 2: Defender

Y is the Patrol Member

- 1
- 2
- 3
- .
- .
- .
- 20

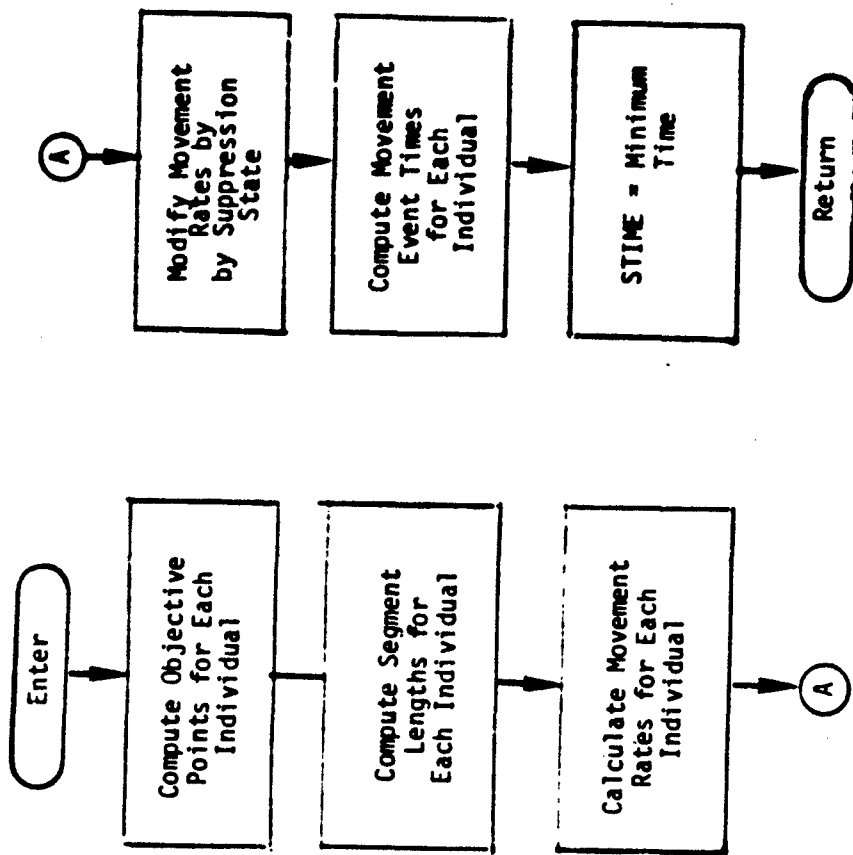
X is the Attribute of the Patrol Member

- 1: Team Number
- 2: Weapon Number
- 3: Current Ammunition Supply (Rounds)
- 4: Casualty Status
- 5: Firing Status
- 6: Current Suppression State
- 7: Current x Coordinate (Meters)
- 8: Current y Coordinate (Meters)
- 9: Next x Coordinate (Meters)
- 10: Next y Coordinate (Meters)
- 11: Height (Meters)
- 12: Width (Meters)
- 13: Current Posture
- 14: Moving Element
- 15: Maneuver Unit to Which the Element Belongs
- 16: Number of Rounds Remaining in Magazine
- 17: Function in Patrol
- 18: Movement Rate of Each Individual
- 19: Individual's Assignment
- 20: Initial Ammunition Supply
- 21: Weapon Type
- 22: Position in Fire Team
- 23: Secondary Weapon Number
- 24: Hand Grenade Supply
- 25: Signal Grenade Supply

adjusted, attribute No. 11. Should his movement status change, for example, should he be in a suppression state where movement is not allowed, then the movement status attribute is changed. Attribute changes by one routine in turn effect other routines. For example, should the movement status change, the firing status would probably be different to allow the advancing unit to start moving again. Hence, the interactions between routines are essentially communicated to each of the routines through the attribute matrix. Naturally this is an oversimplification of the exact details of the model and is intended to be an overview to aid in understanding the details presented in Volumes V and VI.

2.5.4 Calculation of Movement Event Times

As previously described in Section 2.5.2 five events are defined in the executive: movement times, detection times, casualty times, communication arrival times, and EFS burst event times. This section describes the calculation of movement event times. Figure 2.38 illustrates this calculation and shows the SIAF team in a line formation moving from one objective point to the next objective point which in this case is the point generated by a dynamic route subroutine. The model starts by computing the objective point for each individual based upon its formation of the unit. For a line formation the objective points would be as shown in the figure. If the formation were a "V" or a wedge then subroutine FORMST would compute the appropriate objective points for each individual and load these values into the ATT matrix. Specifically, these values would be located in ATT 9 and 10, the next movement coordinates. Next, based upon the present location of each individual, this subroutine calculates segment lengths for each individual. As shown in the figure, the segment lengths for each individual could be different and the path each individual takes could be over different terrain; hence, the movement rate model described previously in the reconnaissance section is called and the movement rate of each individual over each segment is calculated. Next these movement rates are modified by the current suppression state which is stored in the ATT matrix. Finally, the segment lengths are divided by movement rates to compute the time at which each individual would reach its next objective point. Then the minimum of all these times is calculated and stored in a variable called STIME.



(X) Next Dynamic Route Point

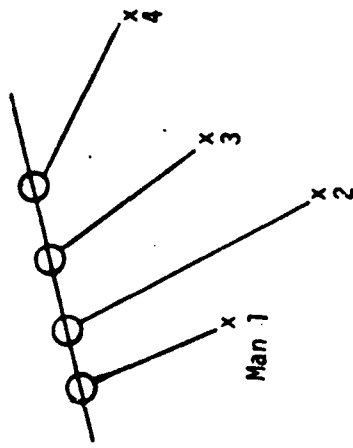


Figure 2.38, Calculation of Movement Event Times

2.5.5 Calculation of Detection Event Times

The previous section described how movement event times are calculated. In this section the calculation of detection event times is described and illustrated in Figure 2.39. First a specific SIAF and target individual are selected. Here detection times are based upon individual detections on individuals, that is, if there are 20 members in a SIAF patrol and 20 members in a target then there are 400 calculations made. After a SIAF individual and target individual are selected the terrain routines are entered and calculations made to determine if line-of-sight exists. If line-of-sight does not exist a no-detection verdict is entered. If line-of-sight does exist and the target is firing then the target is declared detected and time of detection is stored in the array DTIME as shown in the figure. Here the value of DTIME is the current time plus the reaction time which is the time it takes the individual to react to the detection and either change his posture, firing option, movement rate, or change another of his attributes based upon this detection. As shown in the figure, if line-of-sight exists but the target is not firing then a visual detection subroutine is entered to calculate the visual detection time TT. This routine is similar to the routine used in the reconnaissance model described in Volume III. Based upon this calculation the matrix DTIME is again loaded. Finally, the DTIME plus a maximum time are compared with the current time to allow for considering the fact that an individual might have detected another individual 5 seconds ago and the detection may still be valid. As shown in the figure the variable MDET is set equal to TRUE or FALSE which indicates whether the detection did or did not occur. The model proceeds in this fashion until all individuals in the SIAF patrol and all individuals in the target have been examined for detection.

2.5.6 Calculation of Casualty Event Times

Figure 2.40 describes this calculation which starts with computing the assigned area of responsibility of each individual. From this information the next calculation essentially determines a figure of merit and determines firing assignments which will maximize this figure of merit. Thus, this calculation determines the optimum strategy for the

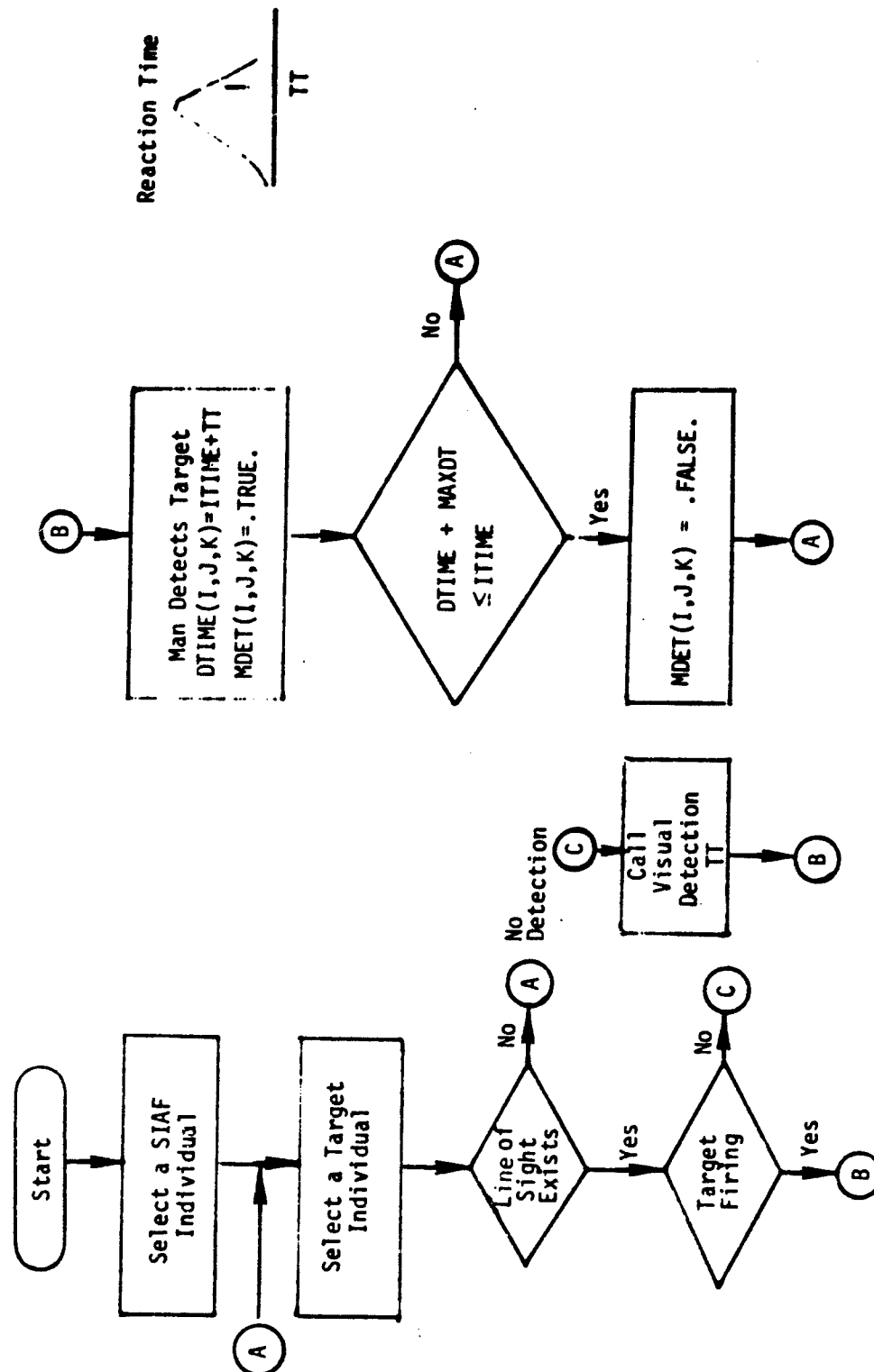


Figure 2.39. Calculation of Detection Events

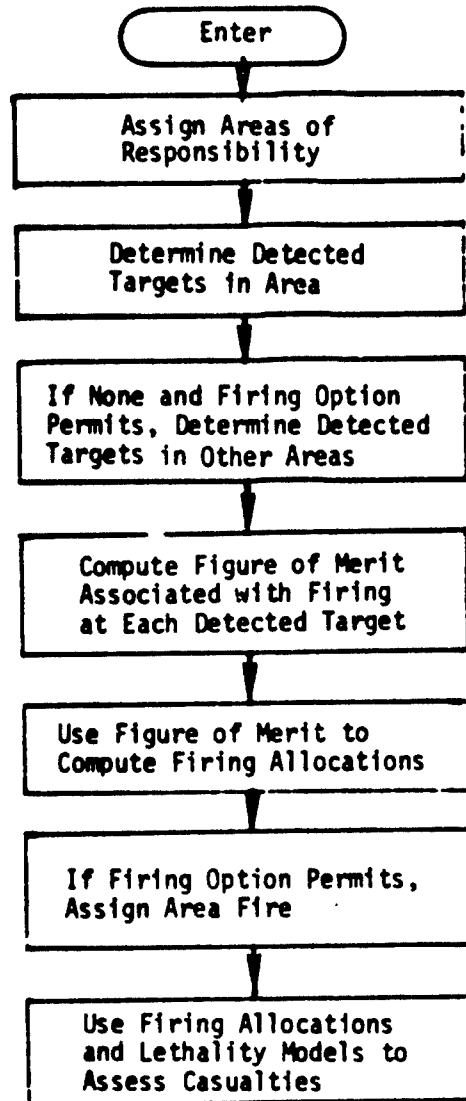


Figure 2.40, Calculation of Firing Events

target and SIAF patrol to use in firing. Based upon this optimum strategy, firing allocation and lethality models are entered to compute casualty times.

2.5.7 Calculation of Internal Communication Event Times

One of the events considered is the reception of a communication from another maneuver unit within the patrol. This would occur after deployment when units are divided into moving maneuver units and a base of fire. In this case it may be necessary to communicate decisions such as break contact, change deployment points, or exchange roles between the moving units and the base of fire. The latter two would be in response to a reaction of the target such as a change in its route or deployment. Several options are available to provide communications. These are by visual hand signals, aural commands, radio, smoke grenades and by sending a messenger. For each type of message, the model has a preference order for attempting communication. These are dependent on the tactical situation. The internal communications routines, called by IC, determine whether or not the communication will be successfully received and interpreted, and they determine the delay time until the message can be implemented. The delay time becomes an event time because the result affects further progress of the combat, including firing, detection and movement status.

2.5.8 Calculation of External Fire Support Event Times

The fifth event considered is an External Fire Support (EFS) event. This is defined as the arrival of a burst, either a volley of artillery or the weapons dropped in a single pass of a close air support aircraft. EFS is a scheduled event but its execution depends on the tactical situation. It is used preparatory to an attack mission. Upon identification of the target, the aimpoint is communicated and a schedule of arrivals is determined. If the target has not counterdetected the SIAF, then the arrivals are scheduled such that they are finished at the same time that the target reaches the minimum safe distance from the target. If this is the case, but the target subsequently counterdetects the SIAF, an immediate open fire command is sent and the schedule of arrivals is adjusted

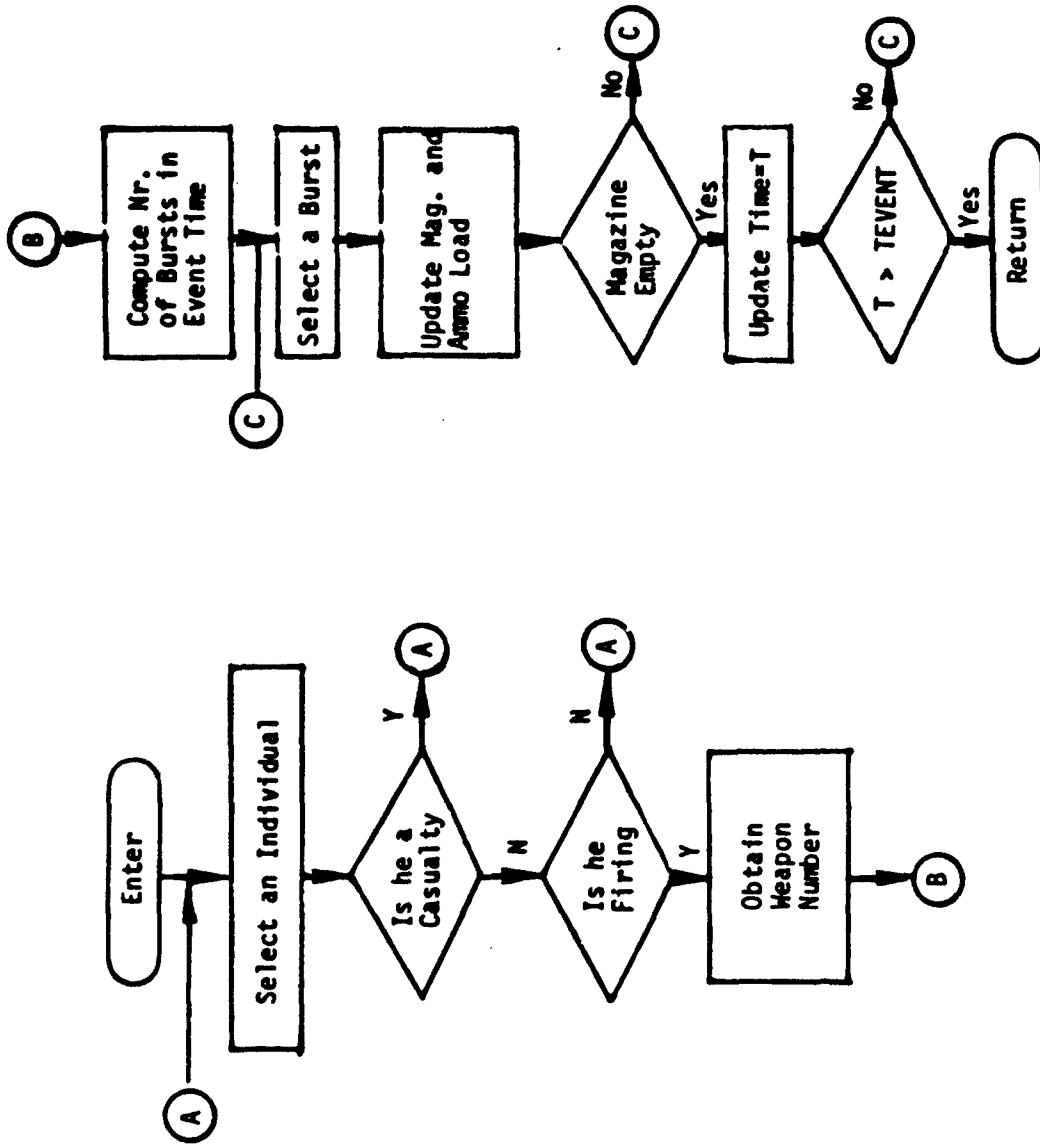


Figure 2.41, Ammunition Update Subroutine (AMMUP)

to start after a delay due to communications and time of flight. If the target has counterdetected the SIAF at the time of the original request, the delay time also includes time to make aiming calculations and to aim the weapons.

If external fire support is the next event, then Subroutine EFS1 is entered to compute the casualties due to each bomb or shell. This is done by considering aim point errors due to the inability of the SIAF to exactly determine the grid coordinates of the target. This includes both navigation errors and target location estimation errors. Also considered is the ballistic dispersion error. Once the aimpoint is determined (stochastically), the distance of each individual is determined and compared to the lethality data for the weapon. The attribute table is updated to account for any casualties.

Once these times are calculated the next event to occur be it movement, detection, casualty, EFS, or internal communication can be computed. If, for example, it is a movement event then the individuals are moved by updating the ATT matrix. If the next event is a detection event the corresponding logic is entered which will modify the movement rates and firing options based upon these detections. If, on the other hand, the next event was a casualty event then the appropriate element in the ATT matrix are updated to indicate that the individual has become a casualty. After these series of calculations are made the ammunition update, weapon substitution, break contact, and withdrawal routines are entered as appropriate. These routines are described in the next sections.

2.5.9 Ammunition Update

The purpose of this subroutine is to update the ammunition of each individual based upon the current elapsed time and the firing scheme. This routine is described in Figure 2.41 which shows that the first calculation is to select an individual. Next, the question is asked, "is he a casualty?" If so, his ammunition is not updated since he could not have been firing. Hence, another individual is selected and the calculations proceed. If he is not a casualty and if he is firing then his weapon number is obtained from the ATT matrix and the number of bursts in the current event time are computed for this particular weapon and particular

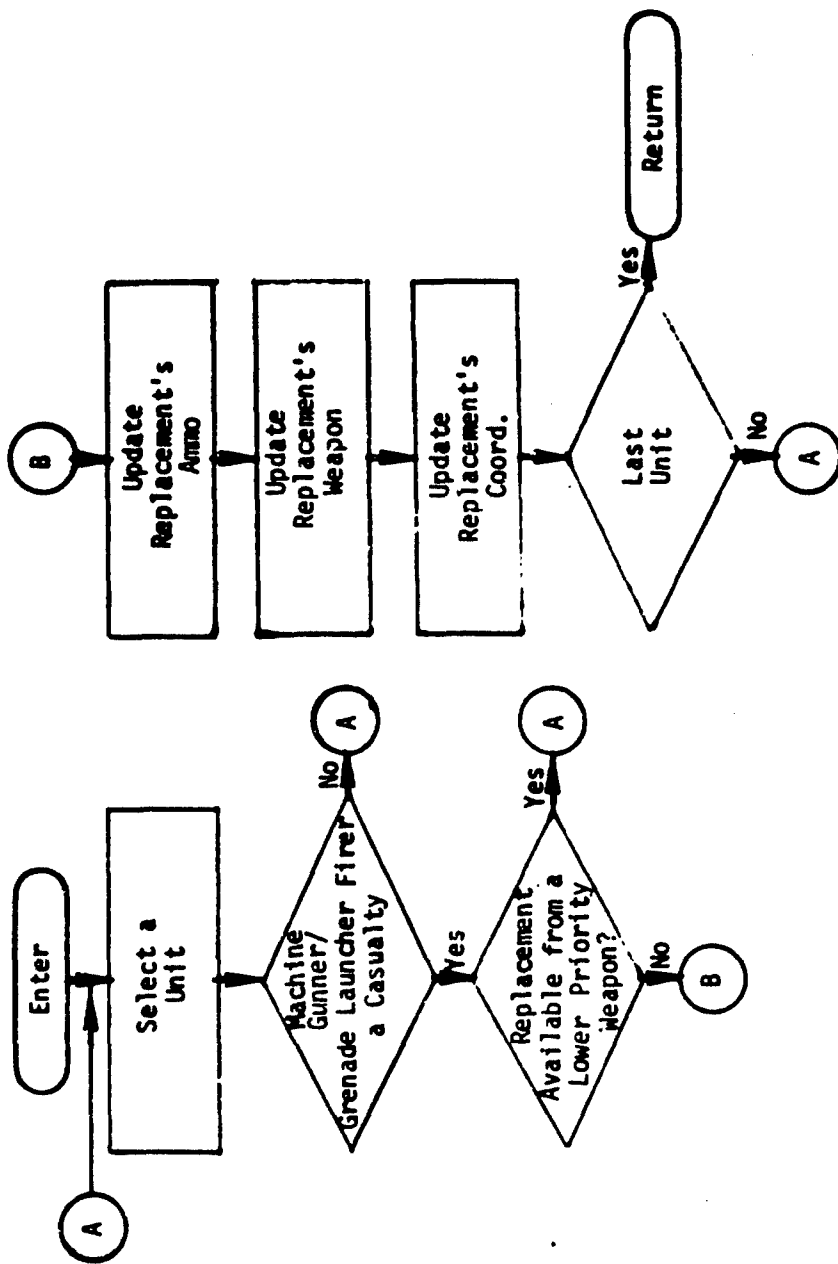


Figure 2.42, Weapon Substitution Subroutine (WSUBS)

Table 2-1. Firing Options

	Firing Options				
	0	1	2	3	4
Fire at detected targets in area of responsibility		X	X	X	X
If none, fire at any detected targets				X	X
If none, conduct area fire into area of responsibility			X		X
Don't fire	X	X		X	

Table 2-2, Firing Options for the Base of Fire and the Maneuver Unit

Base of Fire

SSMU	0	1	2	3	4	5	6
SSBF	0	1	1	1	1	1	1
0	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1
2	1	1	1	1	1	1	1
3	1	1	1	1	1	1	1
4	1	1	1	1	1	1	1
5	2	2	2	2	2	2	2
6	2	2	2	2	2	2	2

Maneuver Unit

SSMU	0	1	2	3	4	5	6
Firing Option	0	0	0	0	2	2	2

SSBF = Suppression State for the Base of Fire
 SSMU = Suppression State for the Maneuver Unit

firing rate of the individual. It could turn out that during the event time the magazine of the weapon became empty. Hence, the next series of calculations determines whether this occurred. If the magazine does become empty reloading time is entered into the calculation and modifies the number of rounds that the individual expended during the last event. If the magazine did not become empty, then number of rounds are computed based upon the event time and firing rate of the weapon. These calculations are done for each individual and the subroutine returns when all individuals have been examined.

2.5.10 Weapon Substitution

If an individual becomes a casualty (major wound or death) in a particular event, it could turn out that the patrol operations plan is to have another individual take over his weapon. This normally occurs in a case of team weapons like grenade launchers, and machine guns. If the machine gunner is hit a patrol member who fires a rifle or grenade launcher will take over his weapon. An attempt to replace him with a rifleman is made first. If the man who is hit fires a grenade launcher an attempt is made to replace him with a rifleman only. Subroutine WSUBS provides the logic implementing this strategy. Figure 2.42 illustrates the calculations made. First, a unit is selected and here the assumption is that intra-unit weapon substitution is not allowed. That is, weapon substitution is only allowed within a particular unit. After a unit is selected the question is asked if the gunner who is a casualty fires a machine gun or a grenade launcher. If not, another unit is selected and this unit selection process continues until the number of units in a patrol and target are exhausted. If the patrol member under consideration is a casualty and is either a machine gunner or fires a grenade launcher and an appropriate replacement can be found then the ammunition of the replacement is updated, his weapon is switched and his next movement coordinates are changed. These calculations continue until all units have been examined for weapon substitution. (Note: If the user does not desire to play weapon substitution, this subroutine can be bypassed by appropriately adjusting the input variables. This is described further in Volume VI, Subroutine WSUBS.)

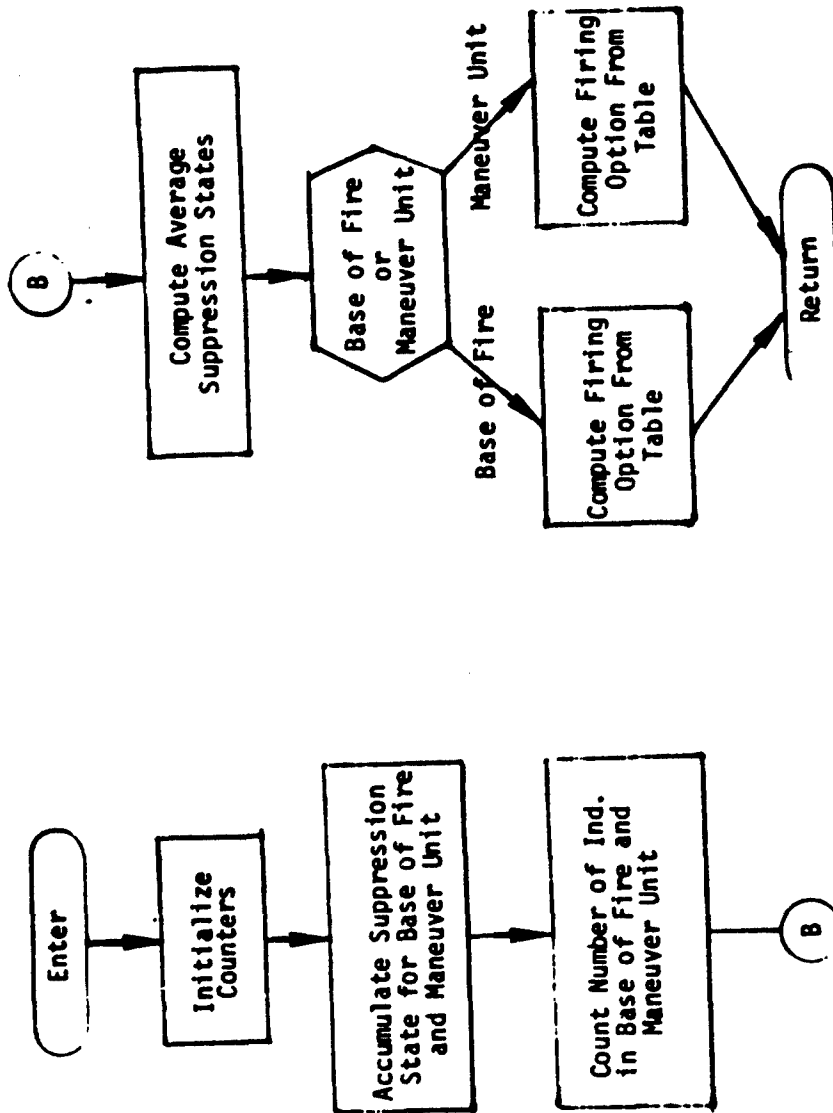


Figure 2.43. Firing Option Subroutine (FIREOP)

Table 2-3, Logic for Breaking Contact

Break Variable	Definition	Criteria
Firepower	$FP = \frac{\text{Firepower of Target}}{\text{Firepower of SIAF}}$	Break if $FP > FP_{Max}$
Casualty Fraction	$CF = \frac{\text{SIAF Casualties}}{\text{SIAF Force Size}}$	Break if $CF > CF_{Ma}$
Time	T = Elapsed time of the firefight	Break if $T > T_{lim}$
Loss of Key Personnel	$L_i = 1$ if the PL is hit $L_i = 2$ if the PL and APL are hit	Break if $L_i = j$ ($j = 1$ or 2)
SIAF - Target Range	R = Minimum Distance Between SIAF and Target	Break if $R < R_{lim}$
Ammunition	A = Average Number of Rounds Remaining (per troop)	Break if $A < A_{lim}$

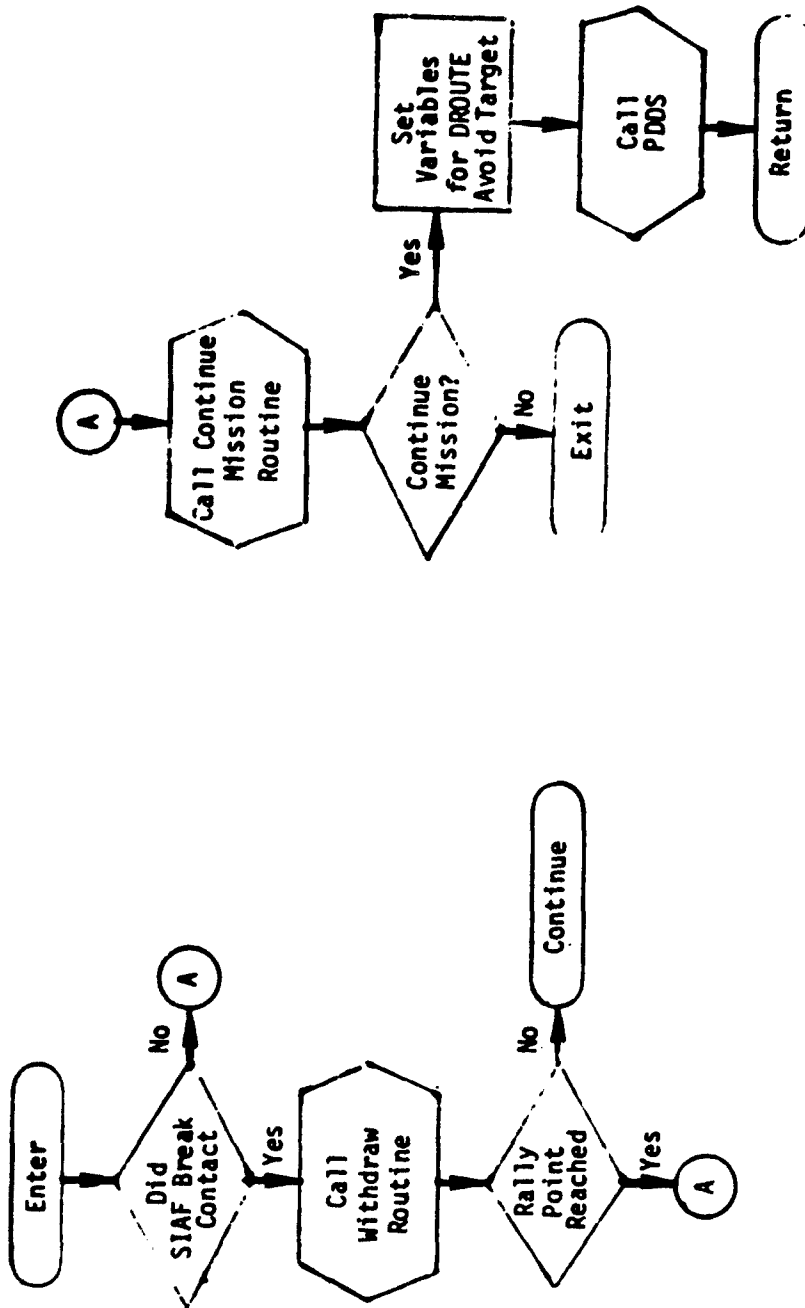


Figure 2.44, Logic For Continuing Reconnaissance After Combat

2.5.11 Firing Options

This particular section describes and presents an overview of how firing options are changed dynamically throughout the conduct of the simulation. Table 2-1 shows the firing options considered in the model. For example, Firing Option 0 is simply "don't fire". Firing Option 1 says, "fire if targets are in your area of responsibility. If none, then don't fire". Option 2 says "fire if detected targets are in area of responsibility. If none, then conduct area fire in area of responsibility." Options 3 and 4 are similar and can be examined by studying Table 2-1. Table 2-2 shows the firing options of both the base of fire and maneuver unit and here the numbers correspond to the options previously described in Table 2-1. For the base of fire, the firing option is a function of their own suppression state and the suppression state of the maneuver unit since their mission is to support the advance of the maneuver unit. The firing options of the maneuver unit on the other hand is a function of their own suppression state only. As an example, Table 2-2 shows that if the maneuver unit in suppression state 0 through 3 their firing option is 0, that is "don't fire". If they are in suppression state 4, 5, or 6, however, their firing option is firing option 2 which states fire at detected targets in area of responsibility. Hence, the firing options can be changed for the base of fire and the maneuver unit by user input data depending upon which particular strategy the user wishes to simulate.

Figure 2.43 shows how this logic is implemented in subroutine FIREOP. When the subroutine is entered counters are initialized and the suppression state for all individuals in the base of fire and maneuver unit is accumulated. Next the number of individuals in the base of fire and maneuver units are counted and the average suppression state of each of these units is computed. Table 2-2 is entered and the appropriate firing option computed by means of table look-up. In this fashion the firing options of both the base of fire and maneuver unit are dynamically adjusted throughout the execution of the combat mission.

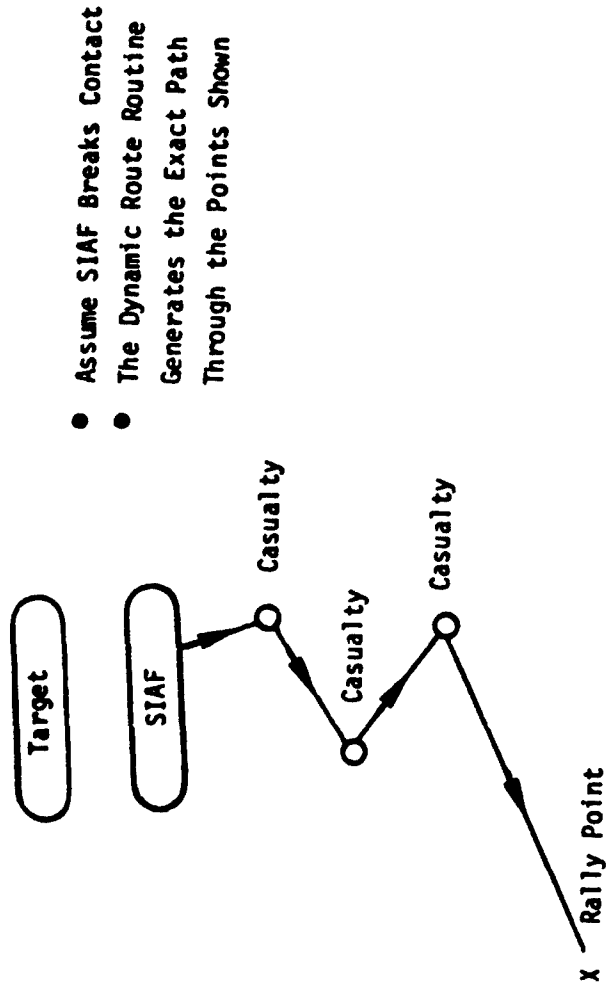


Figure 2.45, Illustration of Withdrawal Model

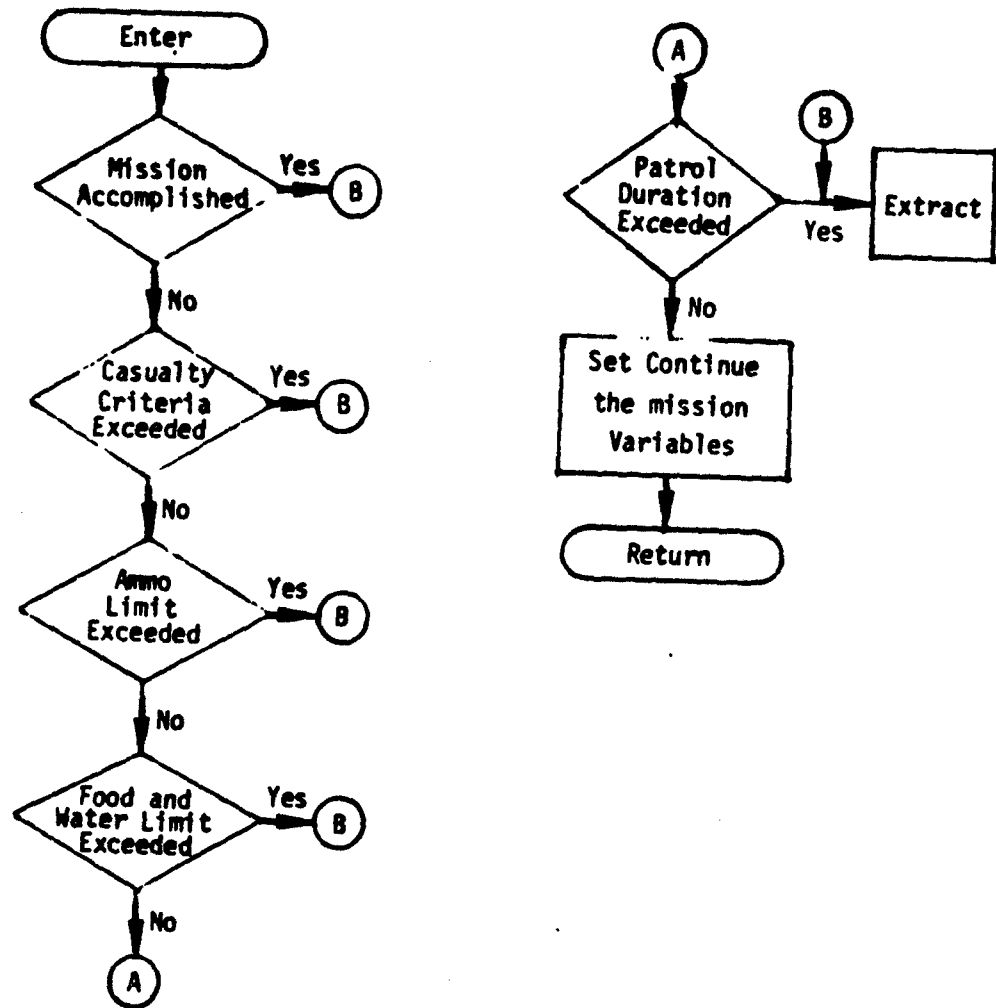


Figure 2.46, Continue The Mission Subroutine

This firer also has the option of firing his normally assigned weapon or throwing a handgrenade. Dependent upon the figure of merit calculated for both his normally assigned weapon and a handgrenade, for the situation that the firer under consideration is in, a decision is made as to which weapon to utilize. The handgrenade is basically used at short ranges under high suppression.

2.5.12 Mines

A SIAF patrol has the capability of Claymore mine ambush. Figure 2.46A depicts a typical mine field deployment. The user specifies a Claymore mine ambush intent by inputting the required inputs, and upon the enemy patrol reaching the most lethal point in the field (middlemost) the mines are detonated. The cumulative probability of kill of all mines in the field upon each target element is computed and the cumulative probability is Monte Carloed for each target individually to determine if the target suffered a minor wound (hit), major wound, or death. Figure 2-46-B shows how this logic is implemented in Subroutine MINES.

2.5.13 Break Contract

In each loop of the simulation, logic for breaking contact is entered if a break contact event is to occur and if so, a determination is made as to which side breaks contact. The break variables described in Table 2-3 are fire power, casualty fraction, time, loss of key personnel, SIAF-target range and ammunition. The criteria for breaking contact are adjusted by means of user input for both the SIAF patrol and for the target. For example, if the user wishes to implement a strategy whereby the SIAF patrol breaks contact after their ammunition reaches 30% of the initial load they implement this strategy by appropriately adjusting the ammunition limit variable shown in the table. The other criteria shown in the table are used in a similar manner. The break contact logic implements a break contact decision if any of the criteria are satisfied.

2.5.14 Withdraw

Figures 2.44 through 2.46 describe how we model a situation where SIAF returns to its reconnaissance mission after the combat operation has been completed. As seen from Figure 2.44, this routine is entered once the proper break contact variable has been set. The first question asked

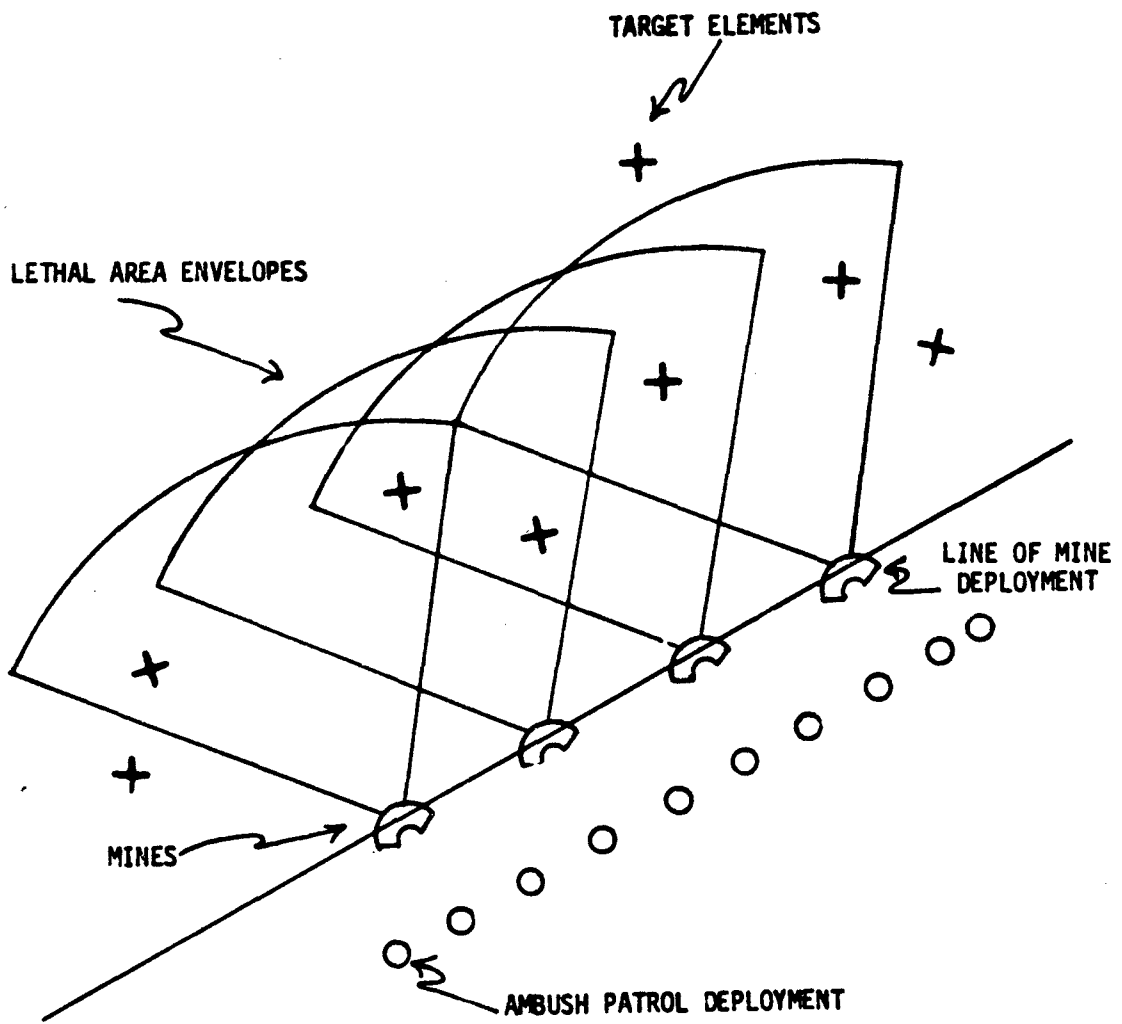


Figure 2.46A Typical Minefield Deployment

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Page 2-82

Revised December 1973

USER INPUT:

NUMBER OF MINES
LENGTH OF FIELD
ANGLE OF DEPLOYMENT
CENTER OF FIELD

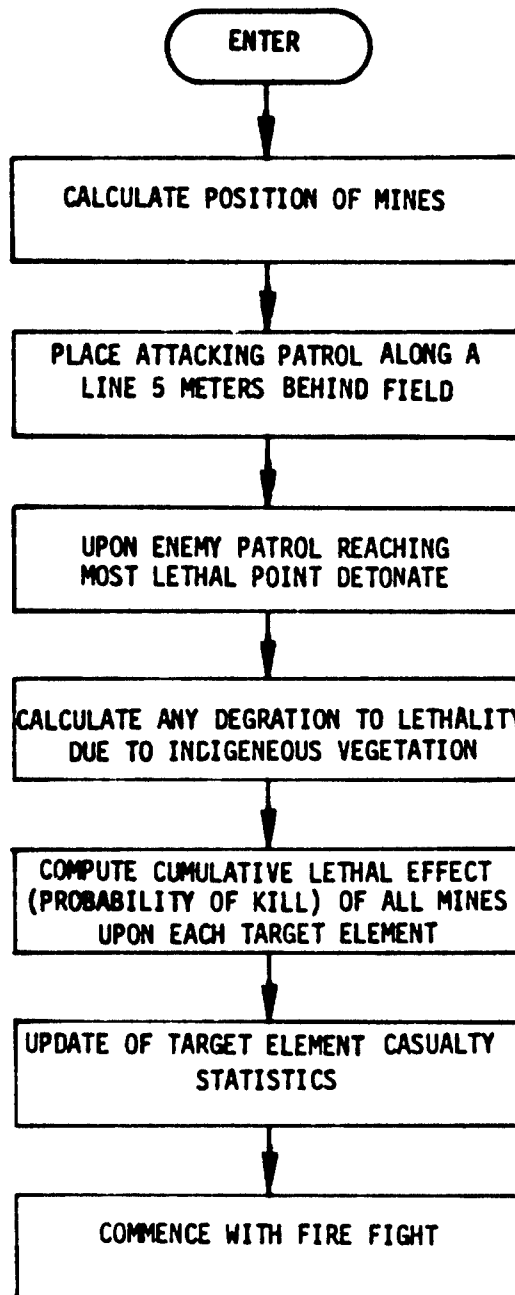


Figure 2.46B, Logic Diagram (MINES)

is, "did SIAF break contact?". If not, then no withdrawal is required for the SIAF unit and the continue-the-mission subroutine described in Figure 2-46 is entered. If SIAF did decide to break contact, then a withdrawal routine is entered. This withdrawal routine calculates the major withdrawal objective points for the patrol. Next, the withdrawal is simulated until the rally point is reached. Once the rally point is reached, the continue-the-mission decision subroutine is entered and if the decision is to continue the mission, then dynamic route variables are set up to avoid the target and get the patrol back to the planned route.

Figure 2.45 illustrates the withdrawal model which forces the patrol to pass through points where a casualty has occurred to the rally point. As indicated in Figure 2.45 the dynamic route subroutine is called to generate the exact route through the casualty locations to the rally point.

2.5.15 Continue the Mission

Once the rally point is reached, the continue-the-mission subroutine shown in Figure 2.46 simulates the patrol leader's decision to extract or go back to the planned route. This decision is based upon the variables shown which are mission objective, casualty criteria, ammunition limits, food and water limits, and patrol duration limits. By adjusting these limits which are user input values, the user can select the criteria he wishes to use in simulating the decision to continue the mission or extract. If a continue-the-mission decision is reached, dynamic route variables are set and subroutine PDDS (see Volume III) is called to generate the route back to the planned path. If the decision is to extract then the model terminates and variables are initiated for the next replication.

2.5.16 Summary of Attacker and Defender Options

Prior to a detection occurring, the SIAF Reconnaissance Model simulates the SIAF mission as discussed in Section 2.4. Once a detection and identification is made (either by SIAF or by the target), the party making the detection and identification becomes the attacker and the other party becomes the defender.

As discussed in Section 2.5.1, the attacker will select one of five options, viz, 1) EES only, 2) ambush, 3) move with stealth to attack, 4) deploy for ambush with mines, 5) no combat. Meanwhile, the defender, having not yet detected, continues to move along his preplanned route. If the attacker selects options 2 or 3, a deployment point is computed and the dynamic route routine generates the attacker's route between his present position and the deployment point. If the defender detects the attacker before the attacker initiates the firefight, then the defender initiates the firefight or selects an alternative course of action to protect its position.

Once the firefight commences, the defender remains stationary unless he decides to break contact. If the target decides to break contact, the engagement is considered complete and SIAF decides whether to continue its mission. However, if SIAF decides to break contact, the withdrawal is simulated until the rally point is reached, at which point SIAF decides whether to continue its mission, in which case the SIAF Reconnaissance Model is again employed to simulate the remainder of the mission.

2.5.17 Summary of Model Capacities

This section summarizes the current capacities of the model. A summary of computer requirements is given in Sections 7.1 and 7.2 of this volume.

- Maximum number of men on each side = 20
- Maximum number of different weapons = 20
- Maximum number of different grenade launches = 10
- Maximum grid of terrain elevation points = 1366
- Maximum number of targets = 20
- Maximum number of preplanned route points for each target = 20
- Maximum number of preplanned SIAF route points = 100
- Maximum number of helicopter landing points = 5
- Maximum number of weather changes = 100
- Maximum length of simulated patrol = 10 days

3.0 MODEL INPUT

The model input data consists of users inputs, data base, and elevation data. The elevation data is taken directly from digital TOPOCOM tapes from the Defense Mapping Agency. When a particular area of operations is desired, a set of subroutines is used to generate a file of elevation data which can be permanently stored. This file can then be accessed at the start of each run as long as the area of operations remains the same. This file contains elevation data at the maximum resolution (or minimum separation). The model then reads from this file to obtain data for the required resolution. The maximum elevation points at any one time is 8196.

The remaining data inputs are read via NAMELIST card input. In general, the namelist card input has been organized into categories of data base (NAML1), user input (NAML2), target oriented user inputs, (NAML3), and combat oriented user inputs (NAML4). Table 3.1 contains a complete list and definition of all of the required input variables. This table is organized by first presenting user inputs, (those variables specific to a situation) and then presenting the data base. (Variables whose values are unlikely to change from run to run). Within these categories the data is organized by categories according to the use of the variables. For example, all of the required inputs to describe the targets are found together.

The variables in the data base are further described by default values which are current best estimates. These need only be changed if better data become available.

Table 3.2 contains a cross reference to Table 3.1. Here all variables from the namelists are presented in alphabetical order with the sheet number of the corresponding location in Table 3.1. It is felt that this method of presentation allows the user to better understand the meaning of a variable because he is able to see its definition in the context of other variables with which it is associated.

USER INPUT

SET UP

JSTART Starting point within run if RESTRT feature is used (See Volume III, Section 10.4)

JSTOP Termination point within run if STOP feature is to be used for later RESTRT.

NCOPY Number of copies of summary output desired

MAXCAS Number of cases

MAXREP Number of replications

ICOMBF Bypass combat flag

= 0 reconnaissance only
= 1 combat model included

IX1, IX2 Initial Random numbers (see Subroutine MAIN).

TERRAIN

THEATA Angle between the X axis SIAF computer coordinate system and military grids degrees

VH X coordinate of origin of SIAF computer coordinate system in the military grid system 4-digit military grid

VK Y coordinate of origin of SIAF computer coordinate system in the military grid system 4-digit military grid

Table 3-1. Namelist Inputs (Sheet 1)

TERRAIN (Continued)

COMRES	Combat resolution for elevation array (Distance between grid lines)	meters (12.7)
REGRES	Reconnaissance resolution for elevation array (Distance between grid lines)	meters (50.8)
RESMAX	Maximum resolution available for elevation array	meters (12.7)
IXMAT	Number of scan lines in input Z matrix (output from MAPGEN) (See Vol. III, Section 10.5)	-
IYMAT	Number of elevation points per scan line	
IDOMST	Dominant soil type	
DOMMT	Dominant class of micro-relief	
DOMV	Dominant class of vegetation	
NOB	Total number of linear obstacles	
NRVP	Total number of vegetation polygons	
NRMT	Total number of micro-relief polygons	
NRST	Total number of soil polygons	
LNRI	The integer number designating the first linear obstacle	
VEGI	The integer number designating the first vegetation polygon	
SOIL1	The integer number designating the first micro-relief polygon	

Table 3-1, Namelist Inputs (Sheet 2)

IERRAII (Continued)

MICR1 The integer number designating the first soil polygon

IOB(L) Linear obstacle type; for L=1,2,3,...,NOB where IOB(L) =

- 1 if linear obstacle L is a river
- 2 if linear obstacle L is a stream
- 3 if linear obstacle L is a ravine
- 4 if linear obstacle L is a dike
- 5 if linear obstacle L is a canal
- 6 if linear obstacle L is a cliff
- 7 if linear obstacle L is a road
- 8 if linear obstacle L is a trail
- 9 if linear obstacle L is a lake or reservoir

ITRC(L) Geometry of Lth polygon, where

- 1 if Lth polygon is a triangle
- 2 if Lth polygon is a rectangle
- 3 if Lth polygon is a circle

for L=1,2,3,..., NRVP+NRMP+NRSOIL

(XOB(I,L); YOB(I,L)) Coordinates of start point of segment I of obstacle L, for L=1,2,...,NOB, and I=1,2,... (NCO(L)+1) or coordinates describing the geometry of the Lth polygon

NCO(L) Number of line segments comprising linear obstacle L, for L=1,2,3,...,NOB

ICL(L) Class of the Lth polygon, for L=1,2,...,NRVP+NRMP+NRSOIL

Table 3-1, Namelist Inputs (Sheet 3)

NAVIGATION DEVICES

PPLS Portable Position Location System. If such a device is carried by SIAF, PPLS=1, if not carried by SIAF, set PPLS=0.

TBUR Set TBUR=0 if it is impracticable to use PPLS or if sufficient time is not available. TBUR=1 if sufficient time is available only for a "quick" navigation fix. (2 min. after aircraft arrival, CEP=150.) TBUR=2 if sufficient time (15 min.) is available for an accurate navigational fix (CEP=60 meters).

SCALE Map Scale

SPEC Special Case. Allows override of HumRRO SIAF navigation specs. Input revised limit on standard deviation of distance between actual SIAF location and believed SIAF location. (HumRRO nav. specs. are used if SPEC is input as zero.)

SIAF INPUTS

DESCRIPTION

SC(1) Average height of a SIAF element - meters

SC(2) Average width of a SIAF element - meters

SC(4) Number of men in the SIAF patrol

SC(5) Average visual reflectivity of a SIAF element

SC(6) Hearing threshold for a SIAF member - dB

IFS { 0 if a vegetation class dependent formation is to be used for SIAF
 1 if specific formation number 1 is to be used for SIAF
 2 if specific formation number 2 is to be used for SIAF
 5 if specific formation number 5 is to be used for SIAF

For Reconnaissance
(See DETECT)

(See FORMATIONS)

OPERATIONS PLAN

XBASE X coordinate of base. - 4-digit military grid

YBASE Y coordinate of base - 4-digit military grid

ITZERO Time mission starts from base. - days, hrs, min, sec.

Table 3-1, Namelist Inputs (Sheet 5)

SIAF INPUTS (Continued)

ITMAX - days, hrs, min, sec.
Limiting value on patrol time duration
(used as temporary checkout input)

INSERTION

MODE Insertion vehicle description (1 = helo,
2 = truck, 3 = boat, 4 = fixed wing).

TDEBK(MODE) Average time to debark, for M = insertion
travel mode. - days, hrs, min, sec.

VELM(MODE) Average velocity of the insertion travel
mode over the terrain from base to insertion
point. - meters/sec

TPREP Time necessary to complete prep firing (i.e., - seconds
time enemy has to move toward primary landing
zone).

NLZ Number of landing zones

XLZ(I) X coordinate of the Ith landing zone. - 4-digit
military grid

YLZ(I) Y coordinate of the Ith landing zone - 4-digit
military grid

PLZ(IZ) Radius of landing zone IZ - meters

NDECOY Number of alternate landing zones (sequentially
numbered) that are used for deceptive landings
in addition to the actual landing zone attempt
at the primary site. This dilutes the enemy in
the area of actual landing. This number must
be less than or equal to (NLZ-1).

Table 3-1, Jamelist Inputs (Sheet 6)

SIAF INPUTS (Continued)

ISEN	<p>0 if LZ sensors are not used before landing attempt 1 if LZ sensors are used before landing attempt</p>	-	seconds
ISENLZ	Number of LZ's seeded with sensors (seeding proceeds sequentially starting with the primary LZ)	-	seconds
HLZ	Time before landing that sensors are monitored.	-	seconds
NSENS	Number of sensors in each LZ (each individual LZ has the same number of sensors)	-	meters
ENRNG	Range within which the enemy may engage the SIAF upon attempting insertion	-	meters
<u>ROUTE</u>			
NPLAN(IZ)	Number of coordinate points for the planned route for insertion IZ	-	4-digit military grid
XPLAN(IP, IZ)	X axis of the IP th checkpoint of the planned route when the insertion is made at point IZ.	-	4-digit military grid
YPLAN(IP, IZ)	Y axis of the IP th checkpoint of the planned route when the insertion is made at point IZ.	-	4-digit military grid
ITARIV(IP, IZ)	Planned arrival time at checkpoint IP when insertion is made at point IZ (equals zero if this time is not pertinent).	-	days, hrs, min, sec.
ITSTAY(IP, IZ)	Mission elapsed time to remain at non-movement point of IP th checkpoint for insertion point IZ.	-	days, hrs, min, sec.

Table 3-1. .iamelist Inputs (Sheet 7)

SIAF INPUTS (Continued)

ISTAY(IP, IZ) { 0 if route checkpoint IP for insertion point IZ is not a non-movement point
 1 if route checkpoint IP for insertion point IZ is a non-movement point

ITMOV(IP, IZ) Planned departure time from checkpoint IP - days, hrs, min, sec.
 for insertion point IZ.

TARGET INPUTS

NTAR Total number of targets

NFIX Number of targets located specifically by user.
 (Others located randomly)

ITST(IT) Time when target IT is created in the model. - days, hrs, min, sec.

ITSTOP(IT) Time when target IT is eliminated from the model.
 - days, hrs, min, sec.

IDET(IT) { 1 if target IT is to be considered on an element-to-element basis
 0 otherwise

MOVEMENT

IMV(IT) { 1 target IT is fixed
 2 target IT moves at random
 3 target IT moves according to a time and checkpoint plan

Table 3-1, Namelist Inputs (Sheet 8)

TARGET INPUTS (Continued)

Movement (Cont'd.)

For IMV = 2 or 3 supply =

FRCMVD(IT)	Fraction of the time target IT is moving during the day
FRCMVN(IT)	Fraction of the time target IT is moving during the night
RAINMAX(IT)	Maximum range target IT can travel. (Random only) - meters
TVEL(IT)	Velocity of the IT th target. (0 if not a manned target) - meters/sec.

IF IMV = 3 also add

IMP(IT)	Number of movement periods for target IT.
ITIMS(IL,IT)	The time that target IT initiates movement - days, hrs, min, sec.
GOALTX(IL,IT)	The X coordinate of the goal point for movement period IL of target IT. } 4-digit military coordinates
GOALTY(IL,IT)	The Y coordinate of the goal point for movement period IL of target IT. } 4-digit military coordinates
TC(1,IT)	The X starting coordinate for the IT th target (0 if random).
TC(2,IT)	The Y starting coordinate for the IT th target (0 if random).

Table 3-1, Jamelist Inputs (Sheet 9)

For Reconnaissance
(See JTECT)

TARGET INPUTS (Continued)

	<u>CHARACTERISTICS</u>	
TC(3.IT)	The average height of an element of target IT.	- meters
TC(4.IT)	The average width of an element of target IT.	- meters
TC(5.IT)	The number of fire teams making up target IT.	
TC(6.IT)	The number of elements making up target IT.	
TC(7.IT)	The average visual reflectivity of an element of target IT.	
TC(8. IT)	The average 1.06 micron reflectivity of an element of target IT (for laser designation).	
TC(9.IT)	The hearing threshold for a member of target IT.	- dB

FORMATION

IFT(IT)	0 if a vegetation class dependent formation is to be used 1 if a specific formation for target IT is to be used (e.g., a fixed set of buildings)
FORMT(I,J,IT)	The locations within a target for a special formation of each of the J elements for target IT

Table 3-1, NameList Inputs (Sheet 10)

For Reconnaissance
 (See UTECT)

TARGET INPUTS (Continued)
 Formation (Cont'd)

Where: I = 1 is the X location of element J relative to the J = 1 element
 I = 2 is the Y location of element J relative to the J = 1 element
 (only used if IFT(IT) = 1)

SOUND TRACK

NSTP(IT)	Number of special sound track periods of target IT	
ISSOFF(IK,IT)	The time when the IK th sound period stops operating for target IT	- days, hrs, min, sec.
ISSON(IK,IT)	The time when the IF th sound period starts to operate for target IT	- days, hrs, min, sec.
SOUNDT(IK,IT)	Sound level for IK th sound period for target IT.	- dB

Table 3-1. Jamelist Inputs (Sheet 11)

TARGET INPUTS (Continued)

DETECTION

RCMAX(IT)

The range between a target IT and SIAF which describes the distance beyond which detailed detection computations are not desired.

- meters

RCMIN(IT)

The range between a target IT and SIAF that always requires detailed detection computations without first checking feasibility.

- meters

(See TARGET)

POST DETECTION

KREC(IT)

0 if target IT is to be eliminated upon detection

1 if SIAF should proceed toward target IT in order to identify the target given that it cannot be identified at detection

2 if SIAF should call external fire support against target IT after advancing for identification

3 if SIAF should avoid target IT upon first detection of target IT.

(See PDDS)

TARGET INPUTS (Continued) EXTERNAL FIRE SUPPORT (This Section For EFS Only Attack)

IFSUP(IT) { 0 no external fire support available
 { 1 artillery support available - Also used for combat
 { 2 air support available

Artillery

IFADJ(IT) { 0 if fire without adjustment
 { 1 if fire with adjustment

ITACT(IT) { 1 if target digs in in-place
 { 2 if target expands circularly (if IFADJ(IT) = 1)
 { 3 if target moves to cover

Close Air Support

IAMG(IT) { 1 if air/ground machine guns are used
 { 0 if air/ground machine guns are not used

ICBOM(IT) { 1 if cluster bombs are used
 { 0 if CBU's are not used

IGBOM(IT) { 1 if general purpose bombs are used
 { 0 if general purpose bombs are not used

IFAR(IT) { 1 if folding fin A/C rockets are used
 { 0 if FFAR's are not used

Table 3-1, Namelist Inputs (Sheet 13)

TARGET INPUTS (Continued)

FMCB1(IT)	<u>If Using Cluster Bombs</u> Lethal area of CBU bomblet versus first pass personnel posture - square
FMCB2(IT)	Lethal area of CBU bomblet versus second and subsequent pass personnel posture - square
NCB(IT)	Number of ordnance delivering passes, CBU
FMGPB(IT)	<u>If Using General Purpose Bombs</u> Mean area effectiveness (GP) - personnel posture
FMA1(IT)	<u>If Using Rockets</u> Lethal area of rockets versus second and subsequent passes personnel posture - square meters
FMA2(IT)	Lethal area of rockets versus second and subsequent passes personnel posture - square meters
NGF(IT)	<u>If Using Machine Guns</u> Number of rounds of machine gun fire
VAX(IT)	Personnel vulnerable area to MG projectiles. - square meters

Table 3-1. Namelist Inputs (Sheet 14)

WEATHER INFORMATION

TSR	Time of sunrise	days, hrs, min, sec
TSS	Time of sunset	days, hrs, min, sec
NWCL(I,1)	Time at which weather class changes	days, hrs, min, sec
NWCL(I,2)	New weather class commencing at time NWCL(I,1)	-
WDAY(I,J)	Daily weather information	
	I: Day of the patrol.	
	J: 1 = time of moonrise	hrs, min
	2 = time of moonset	hrs, min
	3 = type of moon	
	Type 0 = New Moon	
	Type 1 = 1/4 Moon	
	Type 2 = 1/2 Moon	
	Type 3 = Full moon	
	4 = Maximum temperature	°F
	5 = Minimum temperature	°F
	6 = Maximum relative humidity	%
	7 = Minimum relative humidity	%
	8 = Minimum wind velocity	kts
	9 = Average wind velocity	kts
	10 = Maximum wind velocity	kts
	11 = Direction wind is coming from	Compass bearing
		0 - 360°

Table 3-1, Namelist Inputs (Sheet 15)

COMBAT INPUTSHUMAN

XMU	Mean human reaction time to detection	Seconds
SSIG	Standard deviation of human reaction time to detections	Seconds
UNKCON	Factor to compute area of uncertainty of target position as a function of the elapsed time since the target was last seen.	
VELNOM (I,K)	Nominal velocity, moving normally $I = 1$, or moving at top speed $I = 2$, where $K = 1$ for attackers, $K = 2$ for defenders.	Meters/Seconds
FHCR	Fraction of height below which subject is said to be not standing	
FHPR	Fraction of height below which subject is said to be prone.	
XMAXDT	Elapsed time from last detection after which target position becomes unknown.	Seconds
MAXDT	Maximum time after which previous detections lose their value	Seconds

FIRING

DELTA	Increment by which firing allocations are varied in the point fire allocation model (See FALØC)	
AIMMX (K)	Contains maximum aiming time; $K = 1$ attacker, $K = 2$ defender	Seconds
FTAPB (K)	Contains fraction of time between bursts spent aiming; $K = 1$ attacker, $K = 2$ defender	Seconds
DTEFS	Maximum probable delay of EFS after EFS is called	Seconds
HFR	Height above terrain cutoff for firing	Meters

Table 3-1, NameList Inputs (Sheet 16)

Firing (Cont'd)		
DF(I,J)	Firing rate degradation factor when the fraction of ammunition remaining is of index I; J - 1 for point-fire weapons, J - 2 for area-fire weapons	
	<u>FORMATIONS</u> (For Combat Only; See FORMST)	
IPERM(J,M)	Contains the positions of a fire team. J indicates the fire team number and M indicates the particular permutation of fire team positions within their maneuver unit. (M = 1, 2, 3, 4, or 5).	Meters
IFORFT (J)	The formation type to be used by the individual within a fire team. Examples: = 1 column, = 2 wedge, = 3 vee, = 5 echelon right, = 6 echelon left; where J, - 1 for stealth, J = 2 for fire and movement, J = 3 for assault, J = 4 for pursuit, J = 5 for withdrawal, J = 6 for stopped.	
IFORMT(J)	The formation type for fire teams within maneuver units (same as for IFORFT).	
FORFTX (K,J)	The relative X location of the Kth position within fire team formation J	
FORFTY (K,J)	The relative Y location of the Kth position within fire team formation J	
FORMUX(I,J)	The relative X location of the Ith fire team in maneuver unit formation J	
FORMUY(I,J)	The relative Y location of the Ith fire team in maneuver unit formation J	
FORSFX(J)	The relative spacing in the X direction of the patrol element from the fire team leader of fire team formation type J	

Table 3-1, Namelist Inputs (Sheet 17)

Formations (Cont'd)		Meters
FORSFY(J)	The relative spacing in the Y direction of the patrol element from the fire team leader of fire team formation type J	
FORSMX(J)	The relative spacing in the X direction of the fire team in position from the leader of the maneuver unit in formation	
FORSMY(J)	The relative spacing in the Y direction of the fire team in position from the leader of the maneuver unit in formation type J	
<u>FIRING ALLOCATION</u>		
COLMIN(K)	Contains minimum fraction of fire power directed against each detected target; K = 1 defender, K - 2 attacker	
WPWT(I,J)	Contains weapon weighting factor for firing allocation	
	J = 1 - attacker applies to defender's weapons 2 - defender applies to attacker's weapons	
	I = 1 - semi-automatic weapon 2 - automatic weapon 3 - grenade launcher	
ARSMV(K)	Contains minimum length of each man's area of responsibility; K = 1 attacker, K - 2 defender	
ARSPI(K)	Contains fractional overlap of each man's area of responsibility; 1 attacker, 2 defender	
FDGFAC(K)	Contains lateral distance on each side of right-most and left-most targets for defending total area of responsibility; K = 1 defender, K - 2 attacker	

Table 3-1, Iamelist Inputs (Sheet 18)

DEPLOYMENT CRITERIA (See DLOGIC)

RAMB	Ambush range between deployment point and engagement point	Meters
RAWIN	Minimum admissible value of RA (see subroutine DLOG5)	Meters
RATT	Attack range between deployment point and engagement point	Meters
REFS	Minimum admissible distance between the subject patrol and object patrol for calling EFS.	Meters
ROBS	Maximum admissible distance between the subject patrol and the engagement point to use detailed terrain information (See DLOG7)	Meters
RSP	Approximate distance desired between trial deployment points	Meters
RZ	Maximum admissible ratio of line-of-sight cut-off distance to range to observed target for adequate cover due to line-of-sight obstruction	
IOIREC	1 - SIAF to be the subject patrol 2 - target to be the subject patrol	In case of standoff only.
IPURSU(J)	= 0 if the maneuver unit is not to pursue the defender in the withdrawal mode past the last attacker objective point (presently not used).	
GSAPRR	Approximate spacing desired between rows and between columns of predeployment movement area array. (See DLOG8)	Meters
NSECT	Number of angular increments (through pi radians) subtended by the circular array of trial deployment points about a stationary object patrol	

Table 3-1, Namelist Inputs (Sheet 19)

Deployment Criteria (Cont'd)

CADM	Minimum admissible value of ADM, where ADM is the average merit value of trial points set in predeployment movement area ($0 \leq \text{CADM} \leq 1$). (See DLOGIC)	
FRAMB	Minimum admissible force ratio for ambush	
FRATT	Minimum admissible force ratio for attack	
GMAX	Maximum admissible slope from deployment point to engagement point for engagement	
CC1	Percentage thresholds, to be used jointly, with PP1, . . . , PP5, for determining adequate cover, concealment, and observation (see subroutine CCO).	
CC2		
CC3		
CLASS(J,K)	0 if micro-relief Class J and vegetation Class K are deemed jointly admissible for a deployment point (See DLOG7). 1 if micro-relief Class J and vegetation Class K are deemed joint conditionally admissible 2 if micro-relief Class J and vegetation Class K are deemed joint inadmissible	
DTDAMB	Minimum deployment time required for ambush	Seconds
DTDATT	Minimum deployment time required for attack	Seconds
DTENGM	Maximum admissible time for object patrol to move to engagement point	Seconds
DTPURM	Maximum admissible time for subject patrol to move to deployment point.	Seconds

Table 3-1. Hamelist Inputs (Sheet 20)

Deployment Criteria (Cont'd)

PP1
PP2
PP3
PP4
PP5

Probability thresholds, to be used jointly with CC2, CC3, for determining adequate cover, concealment and observation (see subroutine CCO).

Q1
Q2
Q3

Coefficients, non-negative and summing to 1, used to determine the merit value of a point in the movement area (See subroutine CCO).

FIRING OPTIONS (See FIREOP)

FOTB(I,J,K)

Firing options for the base of fire where I - the average suppression state of the base of fire, J - the average suppression state of the unit they are supporting, and K - 1 for attackers, K - 2 for defenders.

FOTM(J,K)

Firing options for the unit being supported by the base of fire where J is the average suppression state of the unit and K - 1 for attackers, K - 2 for defenders

SUPPRESSION

DSUST (J,K)

Defines suppression state J as a function of P_{HIT} per minute; K - 1 defender, K - 2 attacker (See SUPN)

SUFAC(I,J)

Contains degradation factors J each suppression state (I); J - 1 firing rate; J - 2 aiming accuracy; J = 3 moving; J = 4 hand grenades

WITHDRAWAL

NSECTR

Number of angular increments (through a half arc of 60°) between middle trial point and extreme trial point (use to select a rally point). (See RPT)

Table 3-1, Itemlist Inputs (Sheet 21)

Withdrawal (Cont'd)

DWDR Radius of circular array of trial points for withdrawing to rally point

CARFR Maximum allowable value of the ratio:

$$\frac{\text{number of casualties carried}}{\text{number of members carrying}}$$

C1 Maximum admissible ratio of current food per man to initial food for extraction

C2 Maximum admissible ratio of current water per man to initial water per man for extraction

LDAYS Minimum admissible number of days elapsed for extraction

DEFENDER REACTION (See Subroutine REACT)

KDEFOP Defender option index (after detecting attacker)

- 1 Withdraw at top speed
- 2 Deploy in place
- 3 Start firing in place
- 4 Ignore detection
- 5 Rotate formation and stop
- 6 Deploy with stealth to new point

XATT(I,J,K)

ATTRIBUTES

Personnel attributes I for each man J, K = 1 for attackers
 K = IT + 1 for defenders, where IT is the target number 1-4

- I: is the attribute of the Patrol Member
 - 1 Team number
 - 2 Weapon number (See WTS in Weapon Supply DATA BASE)
 - 3 Current ammunition supply (rounds)
 - 4 Casualty status: 0 = not a casualty
 - 1 = minor wound
 - 2 = major wound
 - 3 = dead
 - 5 Firing status: 0 = not firing
 - 1 = area fire
 - 2 = point fire
 - 6 Current suppression state
 - 7 Current X coordinate (meters)
 - 8 Current Y coordinate (meters)
 - 9 Next X coordinate (meters)
 - 10 Next Y coordinate (meters)
 - 11 Height (meters)
 - 12 Width (meters)
 - 13 Current posture: 1 = standing
 - 2 = crouching
 - 3 = prone
 - 14 Moving Status (0 = stopped, 1 = moving normally, 2 = moving at top speed)
 - 15 Maneuver unit to which the element belongs
 - 16 Number of rounds remaining in magazine
 - 17 Function in Patrol: 1 = Patrol Leader
 - 2 = Asst. Patrol Leader
 - 3 = Machine Gunner
 - 4 = Grenade Launcher
 - 5 = Rifleman
 - 18 Movement rate of each individual

Table 3-1, Namelist Inputs (Sheet 23)

Attributes (Cont'd)

- 19 Individual's assignment: 1 = if in base of fire
2 = if in maneuver unit
- 20 Initial ammunition supply
- 21 Weapon type: 1 = point fire
2 = area fire
- 22 Position in fire team
- 23 Secondary Weapon Carried: 13 = Hand Grenade
0 = None
- 24 Hand Grenade Supply
- 25 Smoke Grenade Supply

YATT(I,J,K)

Maneuver unit attributes I for each maneuver unit J, K = 1 for attackers, K = IT + 1 for defenders, where IT is the target number 1-4

- I: 1 = Movement type, loads MOVYTP
- 2 = Number of fire teams in the maneuver unit
- 3 = Index M used to specify which of the particular permutations used to assign fire teams to their positions within their maneuver unit
- 4 = Number of patrol member acting as leader of the maneuver unit. Loads KPEN
- 5 = Maneuver Unit assignment, Loads IBF
1 = base of fire
0 = moving

ATTRIBUTES (continued)

ZATT(1,K)

Attacker defender attribute I, K = 1 for SIAI, K = IT + 1 for target IT, where IT is the target number 1-4

- I: 1 = Number of maneuver units in the patrol
 2 = Patrol mission. Loads MISS
 3 = Availability of external fire support to patrol;
 0 = not available
 1 = available. Loads EFSA
 4 = Patrol member number of patrol leader. Loads NPL
 5 = Patrol member number of assistant patrol leader.
 Loads NAPL
 6 = Relative weight factor assigned to semi-automatic
 weapons in defining firepower for the attacking
 patrol. Loads SCEMI(1)
 7 = Relative weight factor assigned to semi-automatic
 weapons in defining firepower for the defending
 patrol. Loads CSEMI(2)
 8 = Relative weight factor assigned to automatic
 weapons in defining firepower for the attacking
 patrol. Loads CAUTO(1)
 9 = Relative weight factor assigned to automatic
 weapons in defining firepower for the defending
 patrol. Loads CAUTO(2)
 10 = Relative weight factor assigned to grenades in
 defining firepower for the attacking patrol.
 Loads CGREN(1)
 11 = Relative weight factor assigned to grenades in
 defining firepower for the defending patrol.
 Loads CGREN(2)
 12 = Firepower ratio which if exceeded will result in a
 break contact decision for defenders. Loads FPMAX(1)
 13 = Firepower ratio which if exceeded will result in a
 break contact decision for attackers. Loads FPMAX(2)

Table 3-1, NameList Inputs (Sheet 25)

ATTRIBUTES (CONTINUED)

- 14 = Maximum number of rounds per man which will result in a break contact decision for attacking patrol. Loads RLIM (1)
- 15 = Maximum number of rounds per man which will result in a break contact decision for defending patrol. Loads RLIM (2)
- 16 = Casualty fraction which it exceeded will result in a break contact decision for attacking patrol. Loads CFMAX(1).
- 17 = Casualty fraction which if exceeded will result in a break contact decision for defending patrol. Loads CFMAX(2).
- 18 = Value of the loss of key personnel (see definition of L(K)) which will result in a break contact decision for attackers. Load LKP(1)
- 19 = Value of the loss of key personnel (see definition of L(K)) which will result in a break contact decision for defenders. Load LKP(2)
- 20 = Elapsed engagement time which will result in a break contact decision for attacking patrol. Loads TLIM(1)
- 21 = Elapsed engagement time which will result in a break contact decision for defending patrol. Loads TLIM(2)
- 22 = Range between units which will result in a break by defending patrol. Loads DISTL
- 23 = Orientation angle of patrol configuration if stationary, as required by subroutine FORMST

Table 3-1, Namelist Inputs (Sheet 26)

XLAAM(I,J)	WEAPON
1 = 1	Contains lethal areas for grenade Type J
2	Lethal area for minor wound - target position 1 = standing
3	Lethal area for minor wound - target position 2 = crouching
4	Lethal area for minor wound - target position 3 = prone
5	Lethal area for major wound - target position 1 = standing
6	Lethal area for major wound - target position 2 = crouching
7	Lethal area for major wound - target position 3 = prone
8	Lethal area for death wound - target position 1 = standing
9	Lethal area for death wound - target position 2 = crouching
	Lethal area for death wound - target position 3 = prone

Table 3-1, NameList Inputs (Sheet 27)

WEAPONS (Continued)

WCHAR(I,J)	Weapon characteristics I for each weapon number J.
1	Maximum range (meters)
2	Minimum range (meters)
3	Rounds per trigger pull - point fire
4	Actual firing rate - point fire (trigger pulls/min)
5	Rounds per trigger pull - area fire
6	Actual firing rate-area fire (trigger pulls/min)
7	P given hit indicator (or value)
8	Air error indicator
9	$\sigma X1$ (mils) used if aim error indicator
10	$\sigma Y1$ (mils) is zero
11	$\sigma X2$ (mils)
12	$\sigma Y2$ (mils)
13	$\mu X3$ (mils)
14	$\mu Y3$ (mils)
15	$\sigma X3$ (mils)
16	$\sigma Y3$ (mils)
17	Distance between aimpoints - area fire (meters)
18	Maximum number of aimpoints in area of responsibility - area fire
19	Minimum number of aimpoints in area of responsibility - area fire
20	Vertical aimpoint above ground level for area fire (meters)
21	Lethal area indicator (= 0 except for grenades)
22	Weapon type for area assignment (1 = semi-automatic, 2 = automatic, 3 = grenades)
23	Weapon type for firing allocating weight factors (1 = semi-automatic, 2 = automatic, 3 = grenades)
24	Weapon magazine capacity (rounds)
25	Loading time (Seconds)

Table 3-1, NameList Inputs (Sheet 28)

MINES

NBR	=	Number of mines deployed by Subject Patrol
LGTH	=	Length of mine field (meters)
XCENT YCEN	=	Coordinates of the centroid of the mine field deployment line segment. (line along which mines are deployed). (Map Coordinates)
TAK	=	Angle that the mine field deployment lines makes with the X-axis. Positive counterclockwise
XLAAM (I,LAIC)	=	Lethal area for mines. See table XLAAM, Volume IV
LAIC	=	Lethal area indication for mines. Points to appropriate lethal area column for mines in table XLAAM
XENGA YENGA	=	Coordinates of engagement point (Map Coordinates)
<u>EXTERNAL FIRE SUPPORT (For Combat Model)</u>		
T1	=	The time to make a request for EFS plus aiming calculation time, and time for flight of the shells
T2	=	The time to communicate open fire request plus the time of the flight of the shells given that attack has been previously planned
T3	=	The time delay between each volley of shells
SAFDIS	=	The safe-distance radius between the SIAF and target for an EFS attack

Table 3-1, Hamelist Inputs (Sheet 29)

External Fire Support (Cont'd)

- NVOLLEY** = The total number of volleys in the EFS attack
- SIGMDIS** = The error due to ballistic dispersion expressed as the standard deviation.
- JARTL** = Variable whose value (1, 2, 3, 4, 5, 6) specifies which type of artillery or air support is used:
 1 = 4.2 inch mortar
 2 = 155 MM Howitzer
 3 = 105 MM Howitzer
 4 = 175 MM Gun
 5 = 8 inch Howitzer
 6 = Air support

MAEE (Z,J) Lethal radius of selected ammo against Posture (Z) for kill level J
 J=1 death, J=2 major wound, J=3 minor wound.

NSUPP = Suppression state assigned to enemy patrol after completion of the first volley of EFS

DATA BASE
SET UP

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
IPOS	Total number of different personnel postures in set		
SEGMIN	Minimum segment length for which a segment is considered negligibly small	meters	0.1
DSTEP	The maximum step size to be used in a mini-segment. The highest velocity moving feasible target will define the time step size to use for detailed	meters	10.

Table 3-1, iame11st Inputs (Sheet 30)

Data Base Set Up (Cont'd)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
MAXDIS	detection to assure, at most, a step size of DSTEP for any target or for SIAF (the value must be > 0) Maximum distance patrol can move in any event time	Meters	
FORMS(I,J,IFS)	<u>FORMATION</u> (Reconnaissance Only) The location within a SIAF patrol for each of the elements J for each type of special formation IFS (used by Subroutine DETECT when man-to-man detection is desired) where: I = 1 is the X location of element J relative to the J = 1 element I = 2 is the Y location of element J relative to the J = 1 element	meters	
BSAREA	<u>HUMAN MAINTENANCE</u> Body surface area	square ft	20.
CONCAP	Convective capacity content	BTU/lb ^o F	0.0735
CPRAT (L)	Energy expenditure rate for type L check point (rest, recon, sleep, etc. - subroutine HUMAN)	meters	See Subroutine HUMAN

Table 3-1, Namelist Inputs (Sheet 31)

Human Maintenance (Cont'd)

SIGFFR	Heat transfer constant: $\sigma * F_{ae} + f_r$ where	$\frac{\text{BTU/ft}^2}{\text{hr (}^{\circ}\text{R)}^4}$	0.1103 x 10 ⁸
	σ = Stephen-Boltzman constant F_{ae} = Shape emissivity factor f_r = Radiation area factor		
RHOH	Air density	lbs/cu ft	0.075
P	Barometric pressure	mm Hg	760.
To	Base film temperature, absolute	F	536.
Po	Standard pressure	mm Hg	760.
RPE	Vapor resistance, air	in. of air	0.24
RPG	Vapor resistance, garments	in. of air	0.50
XMMAX	Maximum SIAF personnel energy expenditure rate (BTU/hr)		

Table 3-1, Namelist Inputs (Sheet 32)

HUMAN MAINTENANCE (cont.)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
FHRAT(L)	Food consumption energy expenditure rate for type L checkpoint (rest, recon, sleep, etc. - see Subroutine HUMAN).	BTU/hr	See Subroutine LOGIS
LAMDAE	Heat of vaporization	BTU/lb	1080.
STS	Skin temperature	°F	95.
PS	Vapor Pressure at skin	in. Hg	42.
<u>TERRAIN</u>			
SL1	Limiting value on terrain surface quadratic coefficient - a value close to zero indicates the terrain surface is approximately linear		5×10^4
SL2	Limiting value of slope differences		0.05
DMT(I,K)	Density of micro-relief feature of type K (positive undulations, negative undulations, boulders) in micro-relief class I (I=1,...,5).	number/acre	See Subroutine MICROT
RHOI(II,U)	Density of vegetation features type U (1=grass, 2=brush, 3=tree trunk, 4=tree crown) in vegetation class II.	number/acre	See Subroutine VEGCOM
RMAX(II,U)	Range at which a target has unity probability of being completely concealed by vegetation features of type U in class II.	meters	See NAMELIST

Table 3-1, Namelist Inputs (Sheet 33)

TERRAIN (Cont.)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
PMTMAX(I,L)	Range at which a target has unity probability of being completely concealed by micro-relief features of type L (1=positive undulations, 2=negative undulations, 3=boulders) in micro-relief class I (see Subroutine MICROT).	meters	See Subroutine MICROT
W(I,U)	Width of vegetation features of type U (1=grass, 2=brush, 3=tree trunks, 4=tree crowns) in vegetation class I (see Subroutine VEGCON).	meters	See Subroutine VEGCON
WMT(L,K)	Width of micro-relief feature of type K (1=positive undulations, 2=negative undulations, 3=boulders) in micro-relief class L (see Subroutine MICROT)	meters	See Subroutine MITFEA
DSW11	Water depth in vegetation class 13 - sparse swamp.	meters	1.0
DSW12	Water depth in vegetation class 14 - dense swamp.	meters	1.0
DRICE	Water depth in vegetation class 16 - rice field	meters	0.3
H(I,U)	Height above surface of vegetation features (1=grass, 2=brush, 3=tree trunks, 4=crowns of trees) for vegetation class I (1=1,...,16).	meters	See Subroutine VEGCON

20660-6002-R0-00

Page 3-35

Revised December 1973

Table 3-1, Iamelist Inputs (Sheet 34)

TERRAIN (cont.)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
HB(J)	Height of obstacle of type J for J=1,....,9 (see Subroutine TERCON).	meters	See Subroutine TERCON
HMT(I,K)	Height of a micro-relief feature of type K (positive undulations, negative undulations, boulders) in micro-relief class I (I=1,....,5).	meters	See Subroutine MICROT
AQXMAX	The maximum X coordinate at the boundary of the area of operations.	meters	7200.
AQYMAX	The maximum Y coordinate at the boundary of the area of operations.	meters	2400.
REF(II,J)	The effective background reflectance for vegetation class II where 1 is with a downward look angle 2 is with a nearly parallel look angle 3 is with an upward look angle		See Subroutine VISUAL
XLP(II)	The fractional light penetration of vegetation class II		See Light Penetration Subroutine (Volume II, Section 3.2)
VEGC(3,II)	The formation type for moving in the vegetation class II (1-file; 2-column; 3-diamond) (Reconnaissance Only)	meters	See DETECT
VEGC(1,II)	The formation spacing parameter for the vegetation class II (Reconnaissance Only)	meters	See DETECT

Table 3-1. Namelist Inputs (Sheet 35)

<u>NAVIGATION</u>		(See NAV Subroutine)	
<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
SGMTAB	Sigma, Map Terrain Association, Best. For the area of SIAF operation this value represents the standard deviation of the best (minimum) distances within which SIAF can determine its location at any point on its route (except a check-point) by Map Terrain Association, provided that <u>visibility</u> and <u>light level</u> are adequate (i.e., ALL = ALLB, VISM = VISMB).	meters	50.
SGMTAW	Sigma, Map Terrain Association, Worst. Analogous to SGMTAB, but for poor visibility (VISM = VISMW, ALL = ALLW). This term represents the limit on position location by map terrain association.	meters	200.
VISMB	Meteorological Visibility, Best. Visibility (VISM) at which the surrounding terrain features can be seen and identified in sufficient detail to allow the SIAF location to be determined (by Map Terrain Association) to approximately the distance given by the one sigma value of SGMTAB.	meters	13.
VISMW	Meteorological Visibility, Worst. Similar to VISMB described above, but for the "worst" visibility. If VISM = VISMW then SGMTA = SGMTAW. If VISM < VISMW then SIAF location cannot be determined by Map Terrain Association.	meters	300.

NAVIGATION (cont.)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
ALLW	The "worst" value of Ambient Light Level (ALL) for Map Terrain Association. If ALL > ALLW then SIAF location cannot be determined by Map Terrain Association.	ft lamberts	4×10^3
ITAC05	Average time necessary to get an air craft on-site if PPLS 15 is to be used	seconds	900.
ALLB	The "best" value of Ambient Light Level (ALL) for map-terrain-association (i.e., that value of ALL at which SIAF location can be determined to approximately SGMTAB provided that visibility is good). If ALL > ALLB then it is assumed that ALL > ALLB.	ft lamberts	5×10^3
PMC	Point-on-map Error (Constant Component). Error associated with putting the believed SIAF location on the map as a point (25 meters suggested for 1:50,000 map; other map scales are automatically converted internally).	meters	25.
PMR	Point-on-map Error (component that increases with range traveled). (25 meters for 1:50,000 map; other values converted internally).	meters	25.
RC	Range Error Constant. Average error associated with estimating range traveled (by pace count), expressed as % of distance traveled since last check-point.		4.

Table 3-1, Namelist Inputs (Sheet 37)

NAVIGATION (cont.)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
RCTAR	Range Error Constant Target Estimate. Average error (σ) associated with visual estimation of the range to a sighted target, expressed as % of estimated range.		10.
BE	Base Error. (σ_{BE}). Average distance between SIAF location and exact center of checkpoint location when SIAF believes it is at checkpoint.	meters	25.
AA	Average compass reading error (assume more than one compass reading is taken for mission leg).	degrees	1.85
AEQ	Effect of special equipment on estimating average compass reading error.	degrees	0.
ATTAR	Angle error, target estimate. Average compass reading error of bearing to target.	degrees	4.
GR	Grid Reading Error. Introduced by translating the point on the map into eight-digit grid readings (25 meters for 1:50,000 map; other values converted).	meters	25.
ATER	Effect of terrain on estimating average compass reading error.	degrees	0.

Table 3-1, iamelist Inputs (Sheet 38)

NAVIGATION (cont).

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
RTER	Effect of terrain on estimating range traveled.		0.
REQ	Effect of special equipment on estimating range traveled.		0.
ITDRPM	Average time for SIAF to determine its position by dead reckoning, put point on map, and read eight digit grid coordinates.	seconds	60.
ITHMTA	Average time necessary to attempt position location by map-terrain association with good light and visibility, given general area by dead reckoning.	seconds	120.
INTAR	Average time necessary to estimate range and bearing of target visually detected.	seconds	30.
ITPLSA	Average time for an accurate (CEP = 50 meters) navigational fix by PPLS once A/C is on site.	seconds	120.
ITPLSQ	Average time for a "quick" navigational fix (CEP = 150 meters) by PPLS once A/C is on site.	seconds	900.
<u>MOVEMENT RATE</u>			
VTYP	Typical SIAF movement rate. (See Subroutine MVRATE)		.3 meters per second
TMR(I,J)	Movement rates for night (J=1) and day (J=2) over terrain slopes satisfying for various slope values I	km/hr	See Subroutine MVRATE

Table 3-1, Hamelist Inputs (Sheet 39)

MOVEMENT RATE (Cont'd)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
TMR(I,3)	Slope limits defining movement rate as a step function		See Subroutine MVRATE
VEGF(I)	Movement rate degradation factor for vegetation class I (I = 1, ..., 16).		See Subroutine MVRATE
SOILF(I,J)	Movement rate degradation factor for soil type J (see Subroutine SOIL) for wet conditions (I=1) and dry conditions (I=2).		See Subroutine MVRATE
ALIM(I,J)	Night and day limits of ambient light level for a movement rate degradation (lower limit I=1, upper limit I=2, night J=1, day J=2).	ft lamberts	See Subroutine MVRATE
ALLF(I,J)	Movement rate degradation factor for night (J=1) and day (J=2) for various values (I=1,2,3; see Subroutine MVRATE) of ambient light level.		See Subroutine MVRATE
VEGC(2,I1)	The speed adjustment factor for the vegetation class I1 (integer). (Used by target Only)		See MOVET

20660-6002-R0-00

Page 3-41

Revised December 1973

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
Movement Rate (Cont'd)			
WDC	Weighting factor associated with detection for critical movement problem		
WDM	Weighting factor associated with detection for marginal movement problem		
WTC	Weighting factor associated with time for critical movement problem		
WTM	Weighting factor associated with time for marginal movement problem		
<u>AURAL DETECTION</u>			
ATTEN(J)	The attenuation coefficient for sound passing through solid growth of feature type J. This will be modified by growth density in the subroutine (1=grass, 2=brush, 3=tree trunk, 4=tree crown).	dB/meter	See Subroutine AURAL
VEGC(4,II)	The background noise level for vegetation class II in the daytime.	dB	See Subroutine AURAL
VEGC(5,II)	The background noise for vegetation class II in the nighttime.	dB	See Subroutine AURAL
VEGC(6,II)	The noise generated by one man moving in vegetation class II.	dB	See Subroutine AURAL
VEGC(7,II)	The noise generated by one man not MOVING IN VEGETATION class II.	dB	See Subroutine AURAL
VEGC(8,II)	The incremental wind background noise for vegetation class II.	dB/knot	See Subroutine AURAL

Table 3-1, Hamelist Inputs (Sheet 41)

DETECTION (See Subroutine DETECT)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
ANGID	Angular subtense required for identification of a target	minutes of arc	12.
CRECOG	Contrast ratio required for recognition of a target.		1.
DBACK	Distance behind target considered for background calculations.	meters	50.
TDMIN	Time interval in which detections can be considered simultaneous.	seconds	
WR	Fractional target width required to be visible for target recognition.		0.5
SECT (I, IND, 1)	Sector of scan for the case of both patrols moving or both patrols stopped, where I=1 for the angular left bound for the sector of responsibility for the current sector index IND (IND=1,2,3,4), and I=2 is the angular right bound.		See DETECT
SECT (I, IND, 2)	Sector of scan for the case of stationary observer and moving target where I and IND are as above. This variable is an adjustment to the scan sector due to peripheral vision being able to pick up targets at a much wider angle from forward than is nominal for a fixed target (see Subroutine DETECT).		See DETECT

<u>Symbol</u>	<u>DEFLECTION</u> (See Subroutine DETECT)	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
ANGID		Angular subtense required for identification of a target	minutes of arc	12.
CRECOG		Contrast ratio required for recognition of a target.		1.
DBACK		Distance behind target considered for background calculations.	meters	50.
TDMIN		Time interval in which detections can be considered simultaneous.	seconds	
WR		Fractional target width required to be visible for target recognition.		0.5
SECT (I, IND, 1)		Sector of scan for the case of both patrols moving or both patrols stopped, where I=1 for the angular left bound for the sector of responsibility for the current sector index IND (IND=1,2,3,4), and I=2 is the angular right bound.		See DETECT
SECT (I, IND, 2)		Sector of scan for the case of stationary observer and moving target where I and IND are as above. This variable is an adjustment to the scan sector due to peripheral vision being able to pick up targets at a much wider angle from forward than is nominal for a fixed target (see Subroutine DETECT).		See DETECT

Table 3-1, NameList Inputs (Sheet 42)

Detection (Cont'd)	<u>Symbol</u>	<u>Definition</u>	<u>Units</u>	<u>Default Value</u>
	ISECT(J)	Sector of primary surveillance responsibility for member J of a patrol (forward sector=1, left side=2, right side=3, rear sect-r=4).		1, 2, 3, 4, 1, 2
	IDTIM	<u>WEATHER</u> Time interval preceding current time during which rain is considered to cause a current wet soil condition	hours	1.0
	VISLUM(I,1)	Meteorological visibility at sea level for weather class I (see Subroutine WETHR).	meters	See Subroutine WETHR
	VISLUM(I,J)	Illumination of the sky for weather class I, where J=2 for daylight; J=3 for sunrise; 4: sunset; 5: night, no moon; 6: night, quarter moon; 7: night, half moon; 8: night, full moon.	ft lamberts	See Subroutine WETHR

Table 3-1. Name11st Inputs (Sheet 43)

AMWTAB(K)	<u>SUPPLY</u>	Weight of ammunition for type K weapon	lbs/round
	<u>K WEAPON</u>		
	1. M-14(SA6)		.080
	2. M-14A1		.080
	3. M-60MG		.080
	4. M-16(SA)		.040
	5. M-16(A)		.040
	6. Stoner MG		.040
	7. M-79 GL		.600
	8. XM-148 RGL		.600
	9. AK-47		.070
	10. AK-47(A)		.070
	11. RPD Lt. MG		.070
	12. SGM Hvy. MG		.070
	13. M26 A1		1.0
	14. M18 A1		3.5
	15. Stoner MG 1:14		.040
	16. AAI SPIW(SA)		.029
	17. AAI SPIW(A)		.029
	18. AAI SPIW MG		.033
	19. 17. with 11.2 Gr Flechette		.032
	20. 0.17 Cal(A)		.037

Table 3-1. Flamelist Inputs (Sheet 44)

FOOD SUPPLY

PEQUIP	Total weight of patrol equipment carried	pounds
EQUIP	Initial weight of equipment carried per man	pounds
H2O	Initial amount of water carried per man	pounds
RH2O	Total weight of resupply water	pounds
FOOD	Initial amount of food carried per man	pounds
RF00D	Total weight of resupply food	pounds

WEAPON SUPPLY

SAMU(K)	Number of rounds of ammo carried by SIAF for weapon type K.
RAMU(K)	Total number of resupply ammo rounds for weapon type K.
RMINES	Number of resupply mines.
NMINES	Total number of mines carried by SIAF
RHANDG	Number of resupply hand grenades.
NHANDG	Total number of hand grenades carried by SIAF
NSWT	Number of SIAF weapon types
WTS(K)	K th SIAF weapon type

Table 3-1. Namelist Inputs (Sheet 45)

WEAPON SUPPLY (cont.)

- 1 - M-14(SA6)
- 2 - M-14A1
- 3 - M-60MG
- 4 - M-16(SA)
- 5 - M-16(A)
- 6 - Stoner MG
- 7 - M-79 GL
- 8 - XM-148 RGL
- 9 - AK-47
- 10 - AK-47(A)
- 11 - RPD Lt. MG
- 12 - SGM Hvy. MG
- 13 - M26 A1
- 14 - M18 A1
- 15 - Stoner MG 1:14
- 16 - AAI SPIW(SA)
- 17 - AAI SPIW(A)
- 18 - AAI SPIW MG
- 19 - 17. with 11.2 Gr Flechette
- 20 - 0.17 Cal(A)

Table 3-1, Namelist Inputs (Sheet 46)

COMMUNICATION

TUSE	Average external communication message duration	minutes
XDBINS	Sound level increase during attempt of external communication	dB
ICPER	Length of communications period	hours
FREQ	Transmitter frequency of the patrol radio	-
PT	Transmitter output power	mw
TPOWER	Transmission power requirements	amps
RPOWER	Reception power requirements	amps
RNF	Receiver noise figure	dB
BETA	Receiver bandwidth	Kilocycles
BLIFE	Battery life for single radio (assuming a 9:1 ratio of receiving time to transmitting time)	Hours
NBAT	Number of batteries carried per radio.	
NRAD	Total number of radios carried by SIAF	

Table 3-1, Namelist Inputs (Sheet 47)

DYNAMIC ROUTE (See Subroutine DROUTE)

IDELE	0 if point A, B, C, D, or E is to be deleted 1 if point A, B, C, D, or E is not deleted	
RAVOID	Radial distance from XAVOID, YAVOID with which all grid points are to be deleted (enter 0 if no such position).	meters
XAVOID	X coordinate of position for deletion of grid points	
YAVOID	Y coordinate of position for deletion of grid points	
RAVODD	Radial distance from XAVODD, YAVODD within which all grid points are to be deleted (enter 0 if no such position - second position).	meters
XAVODD	X coordinate of second position for deletion of grid points	
YAVODD	Y coordinate of second position for deletion of grid points	
GSAPRX	Approximate desired grid points spacing	meters
GSAPYX	Approximate desired spacing for second stage grid (LFLOBJ = 1, I.GRID = 1)	meters

Table 3-1, Namelist Inputs (Sheet 48)

Dynamic Route (Cont'd)		
DSA	First significant range from enemy position XPPT, YPPT; enter only if DYWT (9,MI) ≠ 0	-
DSAA	First significant range from position XPPTT, YPPTT; enter only if DYWT (8,MI) ≠ 0	-
DMOR	Second significant range from enemy position XPPT, YPPT, enter only if DYWT (9,MI) ≠ 0	-
DMORR	Second significant range from position XPPTT, YPPTT; enter only if DYWT (8,MI) ≠ 0	-
RFSAA	Risk factor associated with DSAA.	-
RFMOR	Risk factor associated with DMOR	-
RFMORR	Risk or benefit factor associated with DMORR	-
RFSAA	Risk factor associated with DSA	-
NPAR	Number of parameters considered in the determination of path utility	9

DYWT(IPAR,MI) Weight Factors for Assumed Missions; relative importance of parameter IPAR

MI: Mission Situation

- 1 = Reconnaissance - detect and identify suspected enemy but avoid encounter
- 2 = Reconnaissance - avoid enemy and proceed as fast as possible
- 3 = Combat - avoid detection and identification by the enemy

Table 3-1, Namelist Inputs (Sheet 49)

Dynamic Route (Cont'd)

IPAR:

- 1 = Movement Time
- 2 = SIAF Detects Enemy
- 3 = SIAF identifies enemy
- 4 = Enemy detects SIAF
- 5 = Enemy identifies SIAF
- 6 = SIAF cover
- 7 = SIAF Concealment
- 8 = Distance from Enemy (2)**
- 9 = Distance from Enemy (1)**

** The enemy locations can be used; however, the ninth parameter calculation refers to the same enemy position as the calculation of detection, identification, cover, and concealment.

CBDYWT (IPAR, ICB) The weight associated with parameter IPAR while movement type ICB is in progress (Same definition as DYWT above; used for combat)

EXTERNAL FIRE SUPPORT (for EFS Only Mission)

JNF	Total number of firings	
AIRC	1 - If FFAR's are helicopter launched 0 - If FFAR's are fixed wing aircraft launched	
IPREP	0 Don't use prep fire 1 Use LZ prep fire (prep fire assumed only on the primary LZ)	
PL	CBU bomblet pattern length	meters
PW	CBU bomblet pattern width	meters
MLANGL	Mean launch angle of MG firing	degrees
MLRANG	Mean launch range of MG firing	meters
LANGLE	Launch angle of FFAR salvo	degrees
L RANGE	Launch range of FFAR salvo	meters
MAE(i)	Lethal area of selected ammo versus personnel in posture (i)	square meters
F(i,j)	Fraction of personnel in posture (i) for each firing	
TBISTR	System delay time before first round or volley is delivered after fire request	sec
TBRNDS	System delay time between subsequent rounds/volleys	sec

Table 3-1. Namelist Inputs (Sheet 51)

EXTERNAL FIRE SUPPORT (cont.)

NN(J)	Number of rounds in each firing	
NROP	Number of ordnance delivery passes, GP	
NRS1P	Number of rockets launched - first pass	
NRS2P	Number of rockets launched - second and subsequent passes	
NCB1P	Number of CBU bomblets delivered, first pass	
NCB2P	Number of CBU bomblets delivered, second and all subsequent passes	
NGPB	Number of GP bombs delivered	
RPA	Artillery range probable error (also used for combat)	meters
RPECBU	CBU delivery error - range	meters
RPEGPB	GP delivery error - range	meters
DPE	Artillery deflection probable error (also used for combat)	meters
DPECBU	CBU delivery error - deflection	meters
DPEGPB	GP delivery error - deflection	meters

Table 3-1, Hamelist Inputs (Sheet 52)

Table 3.2, Alphabetical Cross Reference
for Namelist Input Variables

Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.
AA	38	CONCAP	31	ENRNG	7
AEQ	38	CPRAT	31	EQUIP	45
AIMMX	16	CRECOG	42	F	51
AIRC	51	C1	22	FDGFAC	18
ALIM	40	C2	22	FHCR	16
ALLB	37	DBACK	42	FHPR	16
ALLF	40	DELTA	16	FMA1	14
ALLW	37	DF	17	FMA2	14
AMWTAB	44	DMOR	49	FMCB1	14
ANGID	42	DMORR	49	FMCB2	14
ARSMN	18	DMT	33	FMGPB	14
ARSPI	18	DOMMT	2	FOOD	45
AOXMAX	35	DOMV	2	FORFTX	17
AOYMAX	35	DPE	52	FORFTY	17
ATER	38	DPECBU	52	FORMS	31
ATTAR	38	DPEGPB	52	FORMT	10
ATTEN	41	DRICE	34	FORMUX	17
BE	38	DSA	49	FORMUY	17
BETA	47	DSAA	49	FORSFX	17
BLIFE	47	DSTEP	30	FORSFY	18
BSAREA	31	DSUST	21	FORSMX	18
CADM	20	DSW11	34	FORSMY	18
CARFP	22	DSW12	34	FOTB	21
CBDYWT	50	DTDAMB	20	FOTM	21
CC1	20	DTDATT	20	FRAMB	20
CC2	20	DTEFS	16	FRATT	20
CC3	20	DTENGM	20	FRCMVD	9
CLASS	20	DTPURM	20	FRCMVN	9
COLMIN	18	DWDR	22	FREQ	47
COMRES	2	DYWT	49	FTAPB	16

Table 3.2, Alphabetical Cross Reference
for Namelist Input Variables (cont.)

Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.
FWRAT	33	IFORMT	17	ITSTOP	8
GMAX	20	IFS	5	ITZERO	5
GOALTX	9	IFSUP	13	IXMAT	2
GOALTY	9	IFT	10	IX1	1
GR	38	IGBOM	13	IX2	1
GSAPRR	19	IMV	8	IYMAT	2
GSAPRX	48	IOB	3	JARTL	30
GSAPXX	48	IPERM	17	JNF	51
H	34	IPOS	30	JSTART	1
HB	35	IPREP	51	JSTOP	1
HFR	16	IPURSU	19	KDEFOP	22
HMT	35	ISECT	43	KREC	12
HLZ	7	ISEN	7	LAMDAE	33
H2O	45	ISENLZ	7	LANGLE	51
IAMG	13	ISSOFF	11	LDAYS	22
ICBOM	13	ISSON	11	LGTH	29
ICL	3	ISTAY	8	LNRT	2
ICOMBF	1	ITACOS	37	LRANGE	51
ICPER	47	ITACT	13	MAE	51
IDELA	48	ITARIV	7	MAEE	30
IDELB	48	ITDRPM	39	MAXCAS	1
IDELC	48	ITIMS	9	MAXDIS	31
IDELD	48	ITMAX	6	MAXDT	16
IGELE	48	ITMOV	8	MAXREP	1
IDET	8	ITNMTA	39	MICR1	3
IDTIM	43	ITNTAR	39	MLANGL	51
IDIREC	19	ITPLSA	39	MLRANG	51
IDOMST	2	ITPLSQ	39	MODE	6
IFADJ	13	ITRC	3	NBAT	47
IFAR	13	ITST	8	NBR	29
IFORFT	17	ITSTAY	7	NCB	14

Table 3.2, Alphabetical Cross Reference
for Namelist Input Variables (cont.)

Variable	Sheet 3.1 Sheet No.	Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.
NCB1P	52	NWCL	15	REF	35
NCB2P	52	P	32	REFS	19
NCO	3	PEQUIP	45	REQ	39
NCOPY	1	PL	51	RESMAX	2
NDECOY	6	PMC	37	RFMOR	49
NFIX	8	PMR	37	RFMORR	49
NGF	14	PO	32	RFOOD	45
NGPB	52	PPLS	4	RFSA	49
NHANDG	45	PP1	21	RFSAA	49
NLZ	6	PP2	21	RHANDG	45
NMINES	45	PP3	21	RHOH	32
NMP	9	PP4	21	RHOI	33
NN	52	PP5	21	RH20	45
NOB	2	PS	33	RLZ	6
NPAR	48	PT	47	RMAX	33
NPLAN	7	PW	51	RMINES	45
NRAD	47	Q1	21	RMTMAX	34
NRMT	2	Q2	21	RNF	47
NROP	52	Q3	21	ROBS	19
NRST	2	RAMB	19	RPA	52
NRS1P	52	RAMU	45	RPE	32
NRS2P	52	RAMIN	19	RPECBU	52
NRVP	2	RANMAX	9	RPEGPB	52
NSECT	19	RATT	19	RPG	32
NSECTR	21	RAVODD	48	RPOWR	47
NSENS	7	RAVOID	48	RSP	19
NSTP	11	RC	37	RTER	39
NSUPP	30	RCTAR	38	RZ	19
NSWT	45	RCMAX	12	SAFDIS	29
NTAR	8	RCMIN	12	SAMU	45
NVOLLEY	30	RECRES	2	SC	5

Table 3.2, Alphabetical Cross Reference
for Namelist Input Variables (cont.)

Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.	Variable	Table 3.1 Sheet No.
SCALE	4	TO	32	XBASE	5
SECT	42	T1	29	XCENT	29
SEGMIN	30	T2	29	XDBINS	47
SGMTAB	36	T3	29	XENGA	29
SGMTAW	36	UNKCON	16	XLAAW	27
SIGFFR	32	VAX	14	XLP	35
SIGMDIS	30	VEGC	35,40,41	XLZ	6
SL1	33	VEGF	40	XMAXDT	16
SL2	33	VEG1	2	XMMAX	32
SOILF	40	VELM	6	XMU	16
SOIL1	2	VELNOM	16	XOB	3
SOUNDT	11	VH	1	XPLAN	7
SPEC	4	VISLUM	43	YATT	24
SSIG	16	VISMB	36	YAVODD	48
STS	33	VISMW	36	YAVOID	48
SUFAC	21	VK	1	YBASE	5
TAK	29	VTYP	39	YCENT	29
TBRNDS	51	W	34	YENGA	29
TBUR	4	WCHAR	28	YLZ	6
TB1STR	51	WDAY	15	YOB	3
TC	9	WDC	41	YPLAN	7
TDEBK	6	WDM	41	ZATT	25
TDMIN	42	WMT	34		
THEATA	1	WPWT	18		
TMR	39	WR	42		
TPOWR	47	WTC	41		
TPREP	6	WTM	41		
TSR	15	WTS	45		
TSS	15	XATT	23		
TUSE	47	XAVODD	48		
TVEL	9	XAVOID	48		

4.0 MODEL OUTPUTS

4.1 RECONNAISSANCE MODEL OUTPUTS

The reconnaissance model output variables are defined in Table 4-1, and are listed according to the order in which they appear in the model output format. The method used to calculate these variables is described in subroutines SISTAT and SIWRT of Volume IV.

4.2 COMBAT MODEL OUTPUTS

The combat model output variables are defined in Table 4-2. In the model, these variables are printed out during each even time thus giving the user a time history of the events which took place during the combat operation.

Table 4-1, Model Output Variables (Sheet 1)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
IVOR(IT,1)	The number of visual detections of target IT by SIAF.	
SDEISR(IT,1)	The visual detection success ratio of target IT by SIAF.	
SSTVDR(IT,1)	The mean visual detection range of target IT by SIAF.	meters
SSSTVD(IT,1)	The standard deviation of the visual detection range of target IT by SIAF.	meters
SISTVD(IT,1)	Mean time of detection of target IT by SIAF.	days,hrs,min
SSISTV(IT,1)	Standard deviation of the time of detection of target IT by SIAF.	days,hrs,min
IAOR(IT)	Number of aural detection cues associated with the visual detection of target IT.	
IIVOR(IT,1)	Number of identifications of target IT by SIAF.	
SIDSR(IT,1)	Identification success ratio of target IT by SIAF.	
SSTRR(IT,1)	Mean identification range of target IT by SIAF.	meters
SSSTRR(IT,1)	Standard deviation of the identification range of target IT by SIAF.	meters
SISTR(IT,1)	Mean time of identification of target IT by SIAF	days,hrs,min
SSISTR(IT,1)	Standard deviation of the time of identification of target IT by SIAF.	days,hrs,min
IIAOR(IT,1)	Number of aural detections of target IT by SIAF.	

Table 4-1. Model Output Variables (Sheet 2)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SAURSR(IT,1)	Aural detection success ratio of target IT by SIAF.	
SSTADR(IT,1)	Mean aural detection range of target IT by SIAF.	meters
SSSTAD(IT,1)	Standard deviation of the aural detection range of target IT by SIAF.	meters
SISTAD(IT,1)	Mean time of an aural detection of target IT by SIAF.	days,hrs,min
SSISTA(IT,1)	Standard deviation of the time of an aural detection of target IT by SIAF.	days,hrs,min
SCEPTA(IT)	The mean target location CEP of target IT.	meters
SSCEPT(IT)	Standard deviation of the target location CEP of target IT.	meters
IVOR(IT,2)	The number of visual detections of SIAF by target IT.	
SDETSR(IT,2)	Visual detection success ratio of SIAF by target IT.	
SSTVDR(IT,2)	Mean visual detection range of SIAF by target IT.	meters
SSSTVD(IT,2)	Standard deviation of the visual detection range of SIAF by target IT.	meters
SISTVD(IT,2)	Mean time of detection of SIAF by target IT.	days,hrs,min
SSISTV(IT,2)	Standard deviation of the time of detection of SIAF by target IT.	days,hrs,min
IIVOR(IT,2)	Number of identifications of SIAF by target IT.	

Table 4-1, Model Output Variables (Sheet 3)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SIDSR(IT,2)	Identification success ratio of SIAF by target IT.	
SSTRR(IT,2)	Mean identification range of SIAF by target IT.	meters
SSSTRR(IT,2)	Standard deviation of the identification range of SIAF by target IT.	meters
SISTRI(IT,2)	Mean time of identification of SIAF by target IT.	days,hrs,min
SSISTR(IT,2)	Standard deviation of the time of identification of SIAF by target IT.	days,hrs,min
IIAOR(IT,2)	Number of aural detections of SIAF by target IT.	
SAURSR(IT,2)	Aural detection success ratio of SIAF by target IT.	
SSTADR(IT,2)	Mean aural detection range of SIAF by target IT.	meters
SSSTAD(IT,2)	Standard deviation of the aural detection range of SIAF by target IT.	meters
SISTAD(IT,2)	Mean time of an aural detection of SIAF by target IT.	days,hrs,min
SSISTA(IT,2)	Standard deviation of the time of an aural detection of SIAF by target IT.	days,hrs,min
SLOSRI(IT,1)	Percent of the time target IT is not detected by SIAF due to a relief intercept.	
SLOSVI(IT,1)	Percent of the time target IT is not detected by SIAF due to a vegetation intercept.	

Table 4-1. Model Output Variables (Sheet 4)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SLOSD(IT,1)	Percent of the time target IT is not detected by SIAF due to insufficient range or light.	
SLOST(IT,1)	Percent of the time target IT is not detected by SIAF due to insufficient time.	
SLOSRI(IT,2)	Percent of the time SIAF is not detected by target IT due to a relief intercept.	
SLOSV(IT,2)	Percent of the time SIAF is not detected by target IT due to a vegetation intercept.	
SLOSD(IT,2)	Percent of the time SIAF is not detected by target IT due to insufficient range or light.	
SLOST(IT,2)	Percent of the time SIAF is not detected by target IT due to insufficient time.	
SMVEL	Mean movement rate of the SIAF patrol.	km/hr
SSVEL	Standard deviation of the movement rate of the SIAF patrol.	km/hr
STIME	Mean patrol duration.	days,hrs,min
SSIYIM	Standard deviation of the patrol duration.	days,hrs,min
SPATDI	Mean distance traveled by the SIAF patrol.	km
SSPATD	Standard deviation of the distance traveled by the SIAF patrol.	km
SVEL(I)	Patrol velocity histogram. This vector consists of 12 elements. In each element, the percent of time the patrol is moving is stored in increments of 0.2 of a kilometer per hour.	

Table 4-1, Model Output Variables (Sheet 5)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SCEPPM	The mean patrol location CEP at checkpoints.	meters
SSDCEP	Standard deviation of the patrol location CEP at checkpoints.	meters
SITNAV	Mean time for the patrol to determine its location.	minutes
SSDIT	Standard deviation of the time for the patrol to determine its location.	minutes
SATTEM	Mean number of communication attempts.	
SSATTE	Standard deviation of the number of communication attempts.	
SSUCRA	Mean communication success ratio of the patrol.	
SSSUCR	Standard deviation of the communication success ratio of the patrol.	
SAPCAD	The percent of the communication power loss due to relief for communication failures.	
SAPCAF	The percent of the communication power loss due to vegetation for communication failures.	
SAPCAS	The percent of the communication power loss due to range for communication failures.	
STTIE	The mean time the communication receiver of the patrol is on.	days,hrs,min
SSTIM	Standard deviation of the time the communication receiver of the patrol is on.	days,hrs,min
STTUSE	The mean time the transmitter of the patrol communication equipment was on.	days,hrs,min

Table 4-1, Model Output Variables (Sheet 6)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SSTUS	Standard deviation of the time the transmitter of the patrol communication equipment was on.	days,hrs,min
AWPHR	Ampere hours available at the beginning of the patrol.	amp hrs
SAMPHR	Mean ampere hours used by the communication equipment during the patrol.	amp hrs
SSAMPH	Standard deviation of the ampere hours used by the communication equipment during the patrol.	amp hrs
FOOD	Amount of food carried per patrol member at the beginning of the mission.	lbs/man
H2O	Amount of water carried per patrol member at the beginning of the mission.	lbs/man
XP2	Amount of ammunition carried per patrol member at the beginning of the mission.	lbs/man
XP3	Amount of ordnance other than ammunition carried per patrol member at the beginning of the mission.	lbs/man
SF00DA	Mean amount of food carried by each patrol member at the end of the patrol.	lbs/man
SSF00D	Standard deviation of the amount of food carried by each patrol member at the end of the patrol.	lbs/man
SH20A	Mean amount of water carried by each patrol member at the end of the patrol.	lbs/man
SSH20A	Standard deviation of the amount of water carried by each patrol member at the end of the patrol.	lbs/man

Table 4-1, Model Output Variables (Sheet 7)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SPAK2	Mean amount of ammunition carried by each patrol member at the end of the patrol.	lbs/man
SSPAK2	Standard deviation of the amount of ammunition carried by each patrol member at the end of the patrol.	lbs/man
SPAK3	Mean amount of ordnance other than ammunition carried by each patrol member at the end of the patrol.	lbs/man
SSPAK3	Standard deviation of amount of ordnance other than ammunition carried by each patrol member at the end of the patrol.	lbs/man
SPDEGL	The mean human performance degradation at the end of the patrol.	
SSPDEG	Standard deviation of human performance degradation at the end of the patrol.	
SPDMAX	The mean of the maximum human performance degradation experienced by the patrol during the mission.	
SSPDMA	The standard deviation of the maximum human performance degradation experienced by the patrol during the mission.	
SPDMIN	The mean of the minimum human performance degradation experienced by the patrol during the mission.	
SSPDMI	The standard deviation of the minimum human performance degradation experienced by the patrol during the mission.	
SPDAVG	The mean of the average human performance degradation experienced by the patrol during the mission.	

Table 4-1, Model Output Variables (Sheet 8)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
SSPDAV	The standard deviation of the average human performance degradation experienced by the patrol during the mission.	
SSIGEN	The mean of the energy expended per patrol member at the end of the patrol.	BTU
SSIGE	The standard deviation of energy expended per patrol member at the end of the patrol.	BTU
SSGMAX	The mean of the maximum energy expended per patrol member during the mission.	BTU
SSSGMA	The standard deviation of the maximum energy expended per patrol member during the mission.	BTU
SSGMIN	The mean of the minimum energy expended per patrol member during the mission.	BTU
SSGMI	The standard deviation of the minimum energy expended per patrol member during the mission.	BTU
SSGAVG	The mean of the average energy expended per patrol member during the mission.	BTU
SSSGAV	The standard deviation of the average energy expended per patrol member during the mission.	BTU
PDPL0T(1)	A vector in which is stored a time history of human performance degradation for the mission.	

Table 4-1, Model Output Variables (Sheet 9)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
HTPLOT(I)	A vector of times associated with the human performance values in PDPLOT.	
JJTIME(I)	A vector in which is stored the arrival time of SIAF at the checkpoints.	
AAALL(I)	The vector in which is stored a time history of the light level.	
KKTIME(I)	A vector of times associated with the light level data.	

Table 4-2, Combat Outputs (Sheet 1)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
ATT(1,J,K)	Fire team number of man J; K = 1 for attackers and K = 2 for defenders.	-
ATT(2,J,K)	Weapon number of man J; K = 1 for attackers and K = 2 for defenders.	-
ATT(3,J,K)	Current ammunition supply of man J; K = 1 for attackers and K = 2 for defenders.	rounds
ATT(4,J,K)	Casualty status of man J; K = 1 for attackers and K = 2 for defenders. 0 = not a casualty; 1 = minor wound; 2 = major wound; 3 = dead.	-
ATT(5,J,K)	Firing status of man J; K = 1 for attackers and K = 2 for defenders. 0 = not firing; 1 = area fire; 2 = point fire.	-
ATT(6,J,K)	Current suppression state of man J; K = 1 for attackers and K = 2 for defenders.	-
ATT(7,J,K)	Current X coordinate of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(8,J,K)	Current Y coordinate of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(9,J,K)	Next X coordinate of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(10,J,K)	Next Y coordinate of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(11,J,K)	Height of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(12,J,K)	Width of man J; K = 1 for attackers and K = 2 for defenders.	meters

Table 4-2. Combat Outputs (Sheet 2)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
ATT(13,J,K)	Current posture of man J; K = 1 for attackers and K = 2 for defenders.	meters
ATT(14,J,K)	Moving status of man J; K = 1 for attackers and K = 2 for defenders. 0 = stopped; 1 = moving normally; 2 = moving at top speed.	
ATT(15,J,K)	Maneuver unit of man J; K = 1 for attackers and K = 2 for defenders.	
ATT(16,J,K)	Number of rounds remaining in magazine of the weapon of man J; K = 1 for attackers and K = 2 for defenders.	
ATT(17,J,K)	Function of man J in the patrol; K = 1 for attackers and K = 2 for defenders. 1 = patrol leader; 2 = assistant patrol leader; 3 = machine gunner; 4 = grenadier; 5 = rifleman.	
ATT(18,J,K)	Movement rate of man J; K = 1 for attackers and K = 2 for defenders.	meters/ seconds
ATT(19,J,K)	Man J's maneuver unit; K = 1 for attackers and K = 2 for defenders.	
ATT(20,J,K)	Initial ammunition supply of man J; K = 1 for attackers and K = 2 for defenders.	
ATT(21,J,K)	Man J's weapon type; K = 1 for attackers and K = 2 for defenders. 1 = point fire; 2 = area fire.	
ATT(22,J,K)	Position of man J in fire team; K = 1 for attackers and K = 2 for defenders.	
ATT(23,J,K)	Weapon number of secondary weapon carried by man J; K = 1 for attackers and K = 2 for defenders. 0 = none; 13 = hand grenade.	
ATT(24,J,K)	Supply of hand grenades for man J; K = 1 for attackers and K = 2 for defenders.	
ATT(25,J,K)	Supply of signal grenades carried by man J; K = 1 for attackers and K = 2 for defenders.	

Table 4-2, Combat Outputs (Sheet 3)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
ALPHA(J)	Orientation angle SIAF member J moves to the next point during the current time event.	radians
TIMCAS	Time of the next casualty event.	seconds
TIMDET(K)	Time of the next detection event, K = 1 for attackers, K = 2 for defenders.	seconds
IBRK(K)	0 if patrol K does not break contact; 1 if patrol K breaks contact. K = 1 for attackers and K = 2 for defenders.	
IBVAR(J,K)	K = 1 for attackers and K = 2 for defenders. J = 1,2,...,6 (defined below).	
IBVAR(1,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to lack of adequate firepower.	
IBVAR(2,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to lack of adequate ammunition.	
IBVAR(3,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to the high casualty fraction.	
IBVAR(4,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to the loss of key personnel.	
IBVAR(5,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to excessive elapsed time of the fire fight.	
IBVAR(6,K)	0 if the decision is to continue the fire fight; 1 if the decision is to break contact due to the excessively close range of the fire fight.	
IBVAR(6,1)	IBVAR(6,1) is always zero.	

Table 4-2. Combat Outputs (Sheet 4)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
IEXTR(1)	{ = 0 Continue. = 1 Extract: all targets have been recognized.	
IEXTR(2)	{ = 0 Continue. = 1 Extract: lack of adequate firepower.	
IEXTR(3)	{ = 0 Continue. = 1 Extract: lack of adequate ammunition.	
IEXTR(4)	{ = 0 Continue. = 1 Extract: high casualty fraction.	
IEXTR(5)	{ = 0 Continue. = 1 Extract: inadequate food.	
IEXTR(6)	{ = 0 Continue. = 1 Extract: inadequate water.	
IEXTR(7)	{ = 0 Continue. = 1 Extract: time duration exceeded.	
INDCAS	Side that sustains next casualty.	
JEXTR	{ = 0 Continue the mission. = 1 Extract.	
JGO	{ = 0 Combat decision is to avoid engagement. = 1 To conduct an EFS operation. = 2 Decision is to ambush. = 3 Decision is to attack. = 4 Decision is to deploy Claymore mines for ambush.	

Table 4-2, Combat Outputs (Sheet 5)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
JSP	= 1 if SIAF is the subject patrol (attackers). = 2 if the target is the subject patrol.	
STIME	Time to the next movement event.	seconds
NTYPC	Type of casualty sustained.	
NUMCAS	Number of the man sustaining the next casualty.	
SLENG(J)	Length traveled by SIAF man J during the current time event.	
TIMEFF	Elapsed time of the fight.	seconds
XYBRK	X-Y coordinates of the break point.	meters
XYDEPL	X-Y coordinates of the deployment point.	meters
XYENG	X-Y coordinates of the engagement point.	meters
XYRALY	X-Y coordinates of the rally point.	meters

Table 4-2. Combat Outputs (Sheet 6)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
EFSTIME(L)	Time vector containing times of scheduled arrivals of external fire support burst events.	seconds
AIMPTXY	X-Y coordinates of external fire support bursts.	meters
XYMINES(M)	X-Y coordinates of the deployment of the M th mine in a Claymore minefield.	meters
TMINES	Time until target arrives in Claymore minefield.	seconds
TAKOP	Target's direction of movement.	radians
ICOMFT	1 if firing is being conducted; 0 before and after firing	
MOVINF(IUN)	Movement information flag maneuver unit IUN. 0 = if a new check point is needed. 1 = if the current check point is still in effect.	
IGA(IUN)	Current check point for maneuver unit IUN.	
NGA(IUN)	Total check points for maneuver unit IUN until the next objective point.	
XYGA(I,IUN)	X-Y coordinates of check point I for maneuver unit IUN	meters
INRPA(IUN)		
IMPA(IUN)	Current objective point for maneuver unit IUN.	

Table 4-2. Combat Outputs (Sheet 7)

<u>Symbol</u>	<u>Definition</u>	<u>Units</u>
NARP(IUN)	Total number of objective points for maneuver unit IUN.	
XYARP(N,IUN)	X-Y coordinates of N th objective point for maneuver unit IUN.	meters
KKK	Maneuver unit that last arrived at a check point.	

20660-6002-R0-00

Page 5-1

Revised December 1973

5.0 SUBROUTINES

The SIAF model subroutines are presented in Table 5-1 and a brief summary of their function is presented in Table 5-2. The elevation data handling subroutines are presented in Table 5-3. This information is provided as an overview of the SIAF model subroutines. Details concerning the purpose, description, inputs, outputs, flow chart, and programming information are presented in Volumes II, III, V, and VI.

Table 5-1, SIAF Models and Associated Subroutines (Sheet 1)

<u>TERRAIN (RECON)</u>	<u>TARGET</u>	<u>NAVIGATION</u>	<u>COMMUNICATIONS</u>
LOSVEG	TARMOV	NAV	EXCOM
VEGCON	TARGEN		IC
MICSOL	MOVET	<u>SURVEILLANCE/ DETECTION</u>	ICGRE
MITFEA			ICMSG
MITLOS		TARGET	ICLOS
MITCON	<u>ANCILLARY AND DATA HANDLING</u>	AURAL	ICRAD
ELEV	MAIN	STRACK	ICAU
SLOPE	CASEIN	VISUAL	
LINOB	REPIN	DETECT	<u>COMMAND AND CONTROL</u>
TERCON	RESTART		PDDS
		<u>SUPPLY MAINTENANCE</u>	
<u>WEATHER</u>	<u>MOVEMENT</u>	LOGIS	<u>ELEVATION DATA HANDLING</u>
WETHR	INSERT		MAPGEN
	SEGGEN	<u>HUMAN MAINTENANCE</u>	CONVERT
<u>SUPPLY MAINTENANCE</u>	TMDRVR	HUMAN	ROTATE
LOGIS	MVRATE		CMREAD
	DROUTE		REREAD

Table 5-1, SIAF Models and Associated Subroutines (Sheet 2)

<u>DECISION LOGIC</u>	<u>OPTIMIZATION LOGIC</u>	<u>FIRE CONTROL/LETHALITY</u>	<u>COMBAT FUNCTIONS AND C²</u>
MISGEN	OLOGIC	KTL	CHAIN
CCO	OLOG4	LGTH	MOVPLN
DLOGIC	OLOG6	ARAS	MOVDRV
DLOG1	OLOG7	PKBRP	FORMST
DLOG2	OLOG8	FALOC	POSTURE
DLOG3	OLOG9	PTPTPK	DTBCFR
DLOG4	OLOG10	ARPTPK	FIRATE
DLOG5		ARPTI	AMMOUP
DLOG6	<u>TERRAIN (COMBAT)</u>	SI	FIREOP
DLOG7	DETERR	PKH	WSUBS
DLOG8	PCOVER	SUPH	BREAK
DLOG9	PCOKCL	NEXTC	RPT
DLOG10	PEQTN		WDR
DLOG11	EFCAS		COMMS
		<u>ETERNAL FIRE SUPPORT</u>	REPT
		EFS	REACT
		EFSI	CREACT
		EFSTIM	MINES
			FIRINT
			EFSMIN

Table 5-2, SIAF Subroutines and Their Function (Sheet 1)

TERRAIN

LOSVEG	-	Computes line-of-sight limit due to vegetation and relief
VEGCON	-	Computes vegetation concealment
MITFEA	-	Determines if a target is on a micro-relief feature
MITLOS	-	Computes line-of-sight limit due to micro-relief
MITCON	-	Computes micro-relief concealment
ELEV	-	Calculates elevation of a particular terrain coordinate
SLOPE	-	Calculates slope between two points in the AO
LINOBS	-	Determines if there is an obstacle, or vegetation, micro-relief, or soil polygons between two points
TERCON	-	Integrates terrain subroutines into one package
MICSOL	-	Determines micro-relief, vegetation, and soil type about a particular terrain coordinate

WEATHER

WETHR	-	Computes ambient light level, meteorological visibility, temperature, humidity, wind velocity, and rain/no rain verdict
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TARGET

TARMOV	-	Moves targets during the insertion operation
TARGEN	-	Places targets on the map
MOVET	-	Moves targets in accordance with the scenario during non-insertion operations

Table 5-2, SIAF Subroutines and Their Function (Sheet 2)

ANCILLARY AND DATA HANDLING

- MAIN - Provides logic to drive the SIAF model
- CASEIN - Converts military coordinates to computer coordinates and converts all times to seconds
- REPIN - Initializes subroutine variables to proper values at the start of a new replication
- RESTART - Provides for model execution to start and stop at preset points

MOVEMENT

- INSERT - Simulates an insertion operation
- SEGGEN - Generates SIAF movement segment
- TMDRVR - Computes time interval for driving the model if the segment length is zero
- MVRATE - Computes nominal patrol velocity and actual velocity based upon mission and time constraints
- DROUTE - Computes check points for dynamic movement

NAVIGATION

- NAV - Computes patrol location CEP and target location CEP if detection(s) have occurred

Table 5-2, SIAF Subroutines and Their Function (Sheet 3)

SURVEILANCE/DETECTION

- TARGEL - Eliminates infeasible targets from detection calculations
- AURAL - Determines aural detection verdict
- STRACK - Simulates special sound effects such as truck tailgate noise
- VISUAL - Determines visual detection verdict
- DETECT - Integrates detection subroutines into one package

EXTERNAL FIRE SUPPORT (EFS)

- EFS - Computes results of external fire support when EFS only mode is used
- EF51 - Simulates the effects of external fire support in combat mode
- EFSTIM - Computes the event times for external fire support bursts
- EFCAS - Determines which members sustained casualties from external fire support

SUPPLY MAINTENANCE

- LOGIS - Updates available patrol food, water, and ammunition

HUMAN MAINTENANCE

- HUMAN - Computes required food and water depending upon work performed and computes human performance degradation due to fatigue, body water loss, and body heat storage

Table 5-2, SIAF Subroutines and Their Function (Sheet 4)

OPTIMIZATION LOGIC

- OLOGIC - Provides an optimum array of objective points for attacking maneuver unit routes for ambush or attack
- OLOG4 - Assigns the nominal attack configuration based upon the tactical situation and patrol mission
- OLOG6 - Determines whether the observed patrol configuration is linear or perimeter and - in case of linear - the axes of maximum and minimum dispersion of position
- OLOG7 - Sets an array of trial points over which to search for an optimum deployment point for the case in which the defenders are moving to within engagement range
- OLOG8 - Sets an array of trial points over which to search for an optimum deployment point for the case in which the defenders are moving and the attackers must move to within engagement range of the line of movement of the defenders
- OLOG9 - Sets an array of trial points over which to search for an optimum deployment point for the case in which the defenders are stationary
- OLOG10 - Selects an optimum deployment point from an array of trial points set by OLOG7, 8, or 9

COMMUNICATIONS

- EXCOM - Calculates external communications statistics and updates battery supply
- IC - Integrates the fire IC subroutines and decides whether internal communications is available between maneuver units
- ICGRE - Checks and updates the maneuver leaders supply of signal grenades
- ICMSG - Selects a messenger

Table 5-2, SIAF Subroutines and Their Function (Sheet 5)

COMMUNICATIONS (cont.)

- ICLOS - Determines whether line-of-sight exists between two maneuver unit leaders
- ICRAD - Determines whether two maneuver units can communicate using radios
- ICAUR - Determines whether a receiver can detect an aural message

COMMAND AND CONTROL

- PDDS - Determines detection verdict(s) from the possible detection possibilities

Table 5-2, SIAF Subroutines and Their Function (Sheet 6)

<u>TERRAIN (COMBAT)</u>	
JETERR -	Determines whether the line of sight from the observer to the observed is obstructed by macro-relief, and if it is not, computes probabilities of cover and concealment (head to head, head to foot, foot to head, and foot to foot).
PCOVER -	Computes the probabilities of no cover and of complete cover for observer-target and target-observer.
PCONCL -	Computes the probabilities of no concealment and of complete concealment for observer-target and target-observer.
PEQTN -	Computes the probabilities of complete obstruction of observer and target and the probabilities of no obstruction of observer and target.
<u>DECISION LOGIC</u>	
MISGEN -	Coordinates combat initialization and combat execution.
CCO -	Evaluates cover, concealment, and observation of an observer's position with respect to the observed's position.
DLOGIC -	Simulates engagement-avoid decision and defines General Combat.
DLOG1 -	Reads detection and identification statistics and specifies two patrols--one to be a potential attacker and the other a potential defender.
DLOG2 -	Determines whether a patrol is sufficiently remote from an enemy patrol to call for external fire support.
DLOG3 -	Determines whether the latest possible deployment time would occur before sunrise or the earliest after sunset.
DLOG4 -	Determines whether the relative movement of the two patrols would allow adequate time for the attacking patrol to move to deployment and then to deploy. Determines all reachable deployment points.
DLOG5 -	Searches for the nearest admissible deployment point for the case of a moving enemy patrol where the enemy patrol's line of movement is not within engagement range of the attacking patrol.

Table 5-2, SIAF Subroutines and Their Function (Sheet 7)

DECISION LOGIC (Cont'd)

- DLOG6 - Searches for the nearest admissible deployment point for the case of a moving enemy patrol where the enemy patrol's line of movement is within engagement range of the attacking patrol
- DLOG7 - Tests a trial deployment point for terrain admissibility
- DLOG8 - Tests a pre-deployment movement area for sufficient protectiveness
- DLOG9 - Evaluates protectiveness for movement at a trial point in an array over a pre-deployment movement area
- DLOG10 - Searches for the nearest admissible deployment point for the case of a stationary enemy patrol
- DLOG11 - Computes the SIAF velocity vector for SIAF on either a planned route or a dynamic route for the case in which SIAF is a potential defender

FIRE CONTROL/LETHALITY

- KILL - Controls the operation of the remaining fire control/lethality subroutines
- LETH - Allocates point fire weapons, assigns area fire as appropriate, assigns hand grenades as appropriate
- ARAS - Computes the area of responsibility for each firer and computes which targets are in each area of responsibility
- PKBRP - Computes a figure of merit for alternative firing strategies
- FALOC - Computes the optimum point fire allocations for all firers in the point fire mode
- NEXTC - Computes casualty data for the next attacker and defender casualty
- PTPTPK - Computes kill probability for each firer using a rifle or machine gun
- ARPTPK - Computes kill probability for each firer using a grenade launcher
- S1 - Computes the total single shot delivery error for each weapon type
- PKH - Computes the probability of kill given a hit
- SUPH - Computes individual suppression states

Table 5-2, SIAF Subroutines and Their Function (Sheet 8)

COMBAT FUNCTIONS AND C²

CHAIN	-	Provides logic to drive the combat model.
MOVPLN	-	Generates dynamic route points between unit movement objective points.
MOVDRV	-	Computes movement rates and movement event times.
FORMST	-	Computes coordinates of individuals for various formations.
POSTURE	-	Computes the posture of each individual.
FIRATE	-	Computes firing rate of each individual based upon the ammunition remaining.
AMMOUP	-	Updates ammunition in the magazine and total ammunition remaining for each individual.
FIREOP	-	Computes the firing option of each unit based upon the current suppression state of the unit.
WSUBS	-	Provides logic for weapon substitution.
BREAK	-	Provides logic for breaking contact.
RPT	-	Computes withdrawal points for defending unit.
WDR	-	Computes withdrawal points for attacking unit.
COMMIS	-	Computes a continue the mission decision for SIAF after the combat operation has been completed.
REACT	-	Provides six defender reaction options after detection but before fire-fight
CREACT	-	Permits attacking unit to revise its plan before attack is initiated
MINES	-	Provides for a Claymore Mine ambush
FIRIHT	-	Initiates fire-fight between an attacking and a defending unit
EFMIN	-	Updates the EFS event times

Table 5-3, SIAF Elevation Data Handling (Sheet 1)

ELEVATION DATA HANDLING

- CONVERT - Produces FORTRAN - compatible tapes from Defense Mapping Agency (TOPOCOM) Digital Topographic Tapes
- MAPGEN - Selects and/or thins terrain elevation data for the area of operation
- ROTATES - Provides for rotation and change of interval distance between elevation points at a map area output from MAPGEN
- CMREAD - Loads a selected section of the available map area into computer memory
- REREAD - Condenses the input area elevations in computer memory

6.0 SAMPLE CASE

Sections 6.1 through 6.4 describe a test case which illustrates the use of the reconnaissance model while Sections 6.5 and 6.6 present a combat model test case.

As part of the SIAF program, a model verification plan was developed and a test using actual patrols was conducted. Concurrent with the test, the SIAF System Model was exercised for the purpose of simulating this test and providing data for comparison purposes. This section presents a sample case based upon the test scenario. Included is a qualitative description of the test, a description of the model input data consisting of terrain, weather, the SIAF operations plan, and the enemy situation, and a description of the outputs of the model.

6.1 QUALITATIVE DESCRIPTION OF THE TEST PROGRAM

The field test was conducted at the Hunter Liggett Military Reservation located near King City, California, a facility of the Combat Developments Command Experimentation Command headquartered at Fort Ord, California (Monterey). The test exercise was conducted in a relatively rugged and remote valley which is also a part of Los Padres National Forest. Figure 6.1 is a photograph of a map of the area of operations which represents a geographic area of approximately 17 square kilometers. The patrol mission-scenario (including an aggressor scenario) was developed by the test conductor employing inputs from the test team members. The mission was basically one of reconnaissance which consisted of surveillance of a road suspected of being an enemy supply route, by a SIAF patrol moving primarily at night along the high ground on one side of the valley. Combat was not entered or simulated and live ammunition was not carried.

As shown by Figure 6.1, the distance between the projected insertion and extraction points is approximately 6-1/4 kilometers; however, the route between checkpoints and projected patrol bases is not a straight line nor did the patrols follow a simple point-to-point route. The actual route traveled by each patrol was approximately 9 kilometers long.

Each patrol spent two days in an objective area near the center of the route. This area contained several OP's and bases among which the patrol moved. Aggressor activity existed in the area, some of which was along the roads. For experimental purposes, this area was instrumented to determine exact positions and ranges of detection between the SIAF patrols and the aggressor.



Figure 6.1, SIAF Area of Operations
Showing Patrol Checkpoints

The 5 1/2 day mission was performed by each of 20 patrol teams provided by the 3 participating services:

Army Special Forces	10 teams
U. S. Marine Corps	5 teams
U. S. Navy Seals	5 teams

Each six-man SIAF patrol team was given the same mission, checkpoints, and basing areas, and was exposed to the same aggressor scenario. Patrols moved primarily at night. During the day the patrols established bases from which they monitored the primary road or conducted related reconnaissance and surveillance activities. The sample case described herein (referenced as scenario 1) treats only the first of these patrol missions.

6.2 GENERATION OF BINARY TAPE 8

As described in Section 3.0, Binary Tape 8 is generated from card input. Because of the requirement to duplicate the test situation as closely as possible, detailed terrain and vegetation data were first gathered. This section describes that task.

As previously described in Section 2 4.1, the terrain resolution study for the Hunter Liggett area indicated a substantial increase in accuracy with 50-meter resolution as compared with that obtained for 100-meter resolution. Since the objective of the Hunter Liggett test was to validate the SIAF model, it was considered necessary to use 50-meter resolution. Since the only available digitized data were 100-meter resolution, a decision was made to input the elevation data for the area of operations shown in Figure 6.1 by hand. For this purpose, the map shown in Figure 6.1 was enlarged and a 50-meter grid was overlaid on the map. Then elevation data associated with each corner point of the grid were recorded on computer input sheets. The resulting 7,105 points took approximately two weeks to record. A namelist printout of these resulting data is shown in Figure 6.2. These data, which were used to generate Binary Tape 8, are in feet since the map used for this purpose (Reference 3) contained elevation information in these units. Data were subsequently converted to meters in the computer program.

It should be pointed out that Army digitized terrain tapes of various areas of the world exist. These tapes obviate the necessity of inputting

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
and Vegetation (Y) Data (Sheet 2)

1201, 207, 1, 7, 200, 401, 300, 1, 205, 201,
1101, 207, 1, 7, 200, 401, 300, 1, 205, 201,
201, 500, 201, 207, 300, 401, 5, 201, 205, 201,
701, 207, 1, 7, 200, 401, 300, 1, 205, 201, 1001,
201, 700, 701, 207, 300, 401, 5, 201, 205, 1001,
201, 600, 701, 207, 300, 401, 5, 201, 205, 1001,
201, 500, 501, 300, 401, 5, 1, 5, 1, 400, 1901,
201, 700, 401, 200, 7, 1, 5, 1, 400, 1901,
201, 500, 401, 200, 7, 1, 5, 1, 400, 2001,
201, 500, 301, 200, 7, 1, 400, 2201,
1201, 205, 201, 205, 0, 1, 505, 2101,
1201, 400, 1, 1, 5, 5, 1, 1, 205, 2101,
501, 500, 201, 300, 1, 203, 206, 5, 1, 605, 2001,
401, 700, 201, 3, 303, 5, 3, 6, 1, 405, 1, 305, 1901,
301, 800, 501, 3, 301, 405, 1, 305, 2001,
201, 1000, 401, 305, 1, 405, 401, 405, 1201,
201, 1000, 401, 5, 1, 205, 1, 205, 2101,
201, 1000, 201, 5, 1, 5, 1, 5, 1, 205, 1, 305, 1801,
201, 600, 301, 6, 601, 5, 1, 5, 1, 5, 501, 205, 1401,
201, 200, 401, 6, 1, 5, 1, 205, 401, 205, 301, 305, 1401,
201, 0, 1, 0, 1, 0, 1, 0, 201, 201, 305, 200, 305, 1401,
201, 1, 400, 5, 1, 5, 1, 3, 6, 5, 1, 5, 1, 5, 5, 1, 201, 305, 1501,
201, 300, 201, 6, 501, 5, 1, 205, 1, 5, 1, 205, 1501,
201, 201, 1, 5, 1, 5, 1, 0, 1, 5, 1, 205, 1, 205, 1501,
201, 1, 400, 1, 1, 3, 1, 0, 1, 5, 1, 205, 1, 205, 201, 205, 1501,
201, 400, 1, 0, 5, 1, 0, 200, 205, 1, 5, 1, 205, 701, 305, 1401,
201, 9, 400, 0, 1, 5, 1, 5, 6, 5, 1, 205, 1, 5, 301, 5, 401, 205, 1501,
701, 303, 201, 3, 201, 205, 1, 5, 1, 5, 401, 205, 2101,
201, 400, 300, 1, 205, 1, 5, 301, 3, 201, 205, 2201,
201, 200, 400, 401, 5, 1, 205, 1, 5, 1, 5, 5, 2301,
201, 200, 1, 9, 401, 7, 5, 601, 200, 701, 5, 1001,
201, 801, 207, 401, 5, 1, 5, 1, 701, 5, 1601,
1901, 207, 1, 5, 601, 1, 501, 205, 1601,
1401, 307, 1, 3, 301, 5, 1, 5, 501, 205, 1601,
1401, 307, 5, 301, 5, 201, 5, 501, 205, 1601,
1501, 207, 5, 1, 5, 301, 5, 5, 501, 205, 1601,
1001, 207, 401, 7, 501, 205, 601, 205, 1601,
1001, 207, 207, 1601, 205, 1601,
1101, 7, 207, 301, 200, 1101, 205, 1601,
1201, 307, 1, 305, 201, 205, 701, 205, 1601,
1201, 401, 205, 301, 205, 501, 400, 1601,
1201, 400, 405, 1, 205, 6, 401, 405, 1601,

Figure 6.2. Namelist Printout of Sample Case Elevation (Z)
and Vegetation (V) Data (Sheet 9)

1530,	1540,	1520,	1440,	1460,	1340,	1320,	1260,	1210,	1200,
1100,	1150,	1180,	1140,	1140,	1150,	1180,	1140,	1130,	4+1120,
			1130,	1140,	1250,	1350,	1400,	1480,	1380,
1300,	1330,	1340,	1340,	1320,	1330,	1320,	1260,	1200,	
1060,	1900,	1920,	1380,	1630,	1780,	1730,	1710,	1640,	1500,
1520,	1530,	1480,	1450,	1420,	1390,	1310,	1200,	1200,	1180,
1170,	1150,	1220,	1200,	1140,	1160,	1150,	1140,	1130,	1120,
1150,	1150,	1140,	1140,	1170,	1210,	1300,	1400,	1400,	1390,
1380,	1300,	1360,	1360,	1330,	1310,	1300,	1260,	1220,	
1920,	1920,	1920,	1320,	1830,	1730,	1710,	1680,	1630,	1570,
1520,	1460,	1450,	1400,	1370,	1330,	1280,	1220,	1180,	1180,
1170,	1180,	1180,	1150,	1160,	1200,	1150,	1140,	1140,	1150,
1160,	1140,	1140,	1160,	1180,	1230,	1330,	1400,	1380,	1380,
1380,	1400,	1360,	1340,	1320,	1310,	1260,	1240,	1240,	
1960,	1940,	1920,	1910,	1870,	1810,	1750,	1700,	1640,	1600,
1580,	1520,	1450,	1410,	1360,	1300,	1260,	1230,	1220,	1200,
2+1200,			1180,	1160,	1200,	1150,	1140,	1140,	1150,
1160,	1160,	1160,	1170,	1180,	1200,	1240,	1340,	1380,	1380,
1360,	1400,	1400,	1400,	1300,	1290,	1290,	1270,	1260,	
1980,	1920,	1880,	1850,	1800,	1700,	1650,	1620,	1560,	1530,
1490,	1430,	1400,	1340,	1260,	1215,	1200,	1250,	1250,	1250,
1270,	1180,	1180,	1160,	1160,	1170,	1140,	1140,	1140,	1140,
1140,	1160,	1180,	1200,	1240,	1360,	1380,	1390,	1400,	1400,
1400,	1400,	1320,	1280,	1280,	1260,	1260,	1260,	1260,	
1980,	1920,	1870,	1815,	1770,	1760,	1700,	1630,	1550,	1510,
1440,	1400,	1360,	1300,	1230,	1210,	1200,	1250,	1250,	1250,
1190,	1160,	1160,	1170,	1160,	1160,	1140,	1140,	1140,	1150,
1140,	1160,	1180,	1200,	1230,	1250,	1400,	1420,	1400,	1400,
1420,	1400,	1380,	1340,	1290,	1240,	1200,	1200,	1240,	
1930,	1880,	1840,	1790,	1740,	1680,	1660,	1620,	1550,	1490,
1430,	1350,	1320,	1270,	1230,	1220,	1210,	1250,	1250,	1250,
1160,	1180,	1160,	1160,	1160,	1140,	1140,	1140,	1140,	1150,
1160,	1170,	1150,	1200,	1260,	1330,	1420,	1420,	1400,	1400,
1400,	1400,	1400,	1360,	1300,	1300,	1230,	1180,	1200,	
1900,	1850,	1810,	1750,	1700,	1650,	1620,	1570,	1540,	1480,
1400,	1340,	1300,	1240,	1240,	1220,	1200,	1230,	1250,	1160,
1170,	1200,	1190,	1160,	1160,	1140,	1150,	1140,	1140,	1140,
1160,	1170,	1180,	1200,	1280,	1350,	1440,	1440,	1420,	1400,
1400,	1400,	1400,	1320,	1320,	1300,	1220,	1180,	1160,	
1900,	1830,	1780,	1730,	1680,	1620,	1580,	1540,	1470,	1430,
1360,	1320,	1270,	1260,	1200,	1200,	1200,	1170,	1180,	1180,
1200,	1200,	1180,	1160,	1150,	1140,	1140,	1140,	1140,	1140,

Figure 6.2. Namelist Printout of Sample Case Elevation (Z)
and Vegetation (V) Data (Sheet 10)

1140.	1160.	1180.	1210.	1300.	1350.	1450.	1450.	1400.	1380.
1580.	1400.	1500.	1300.	1300.	1220.	1170.	1150.	1150.	1400.
1880.	1840.	1720.	1670.	1620.	1600.	1600.	1520.	1460.	1400.
1350.	1280.	1230.	1230.	1210.	1190.	1180.	1140.	1190.	1200.
1200.	1190.	1160.	1150.	1150.	1160.	1140.	1140.	1140.	1140.
1150.	1160.	1150.	1220.	1300.	1300.	1420.	1440.	1410.	1370.
1360.	1400.	1400.	1400.	1400.	1300.	1300.	1280.	1260.	1400.
1860.	1780.	1760.	1720.	1680.	1630.	1550.	1510.	1450.	1400.
1360.	1320.	1300.	1200.	1200.	1200.	1200.	1180.	1220.	1220.
1180.	1180.	1160.	1150.	1140.	1140.	1140.	1140.	1140.	1140.
1140.	1160.	1180.	1220.	1300.	1360.	1400.	1400.	1380.	1360.
1360.	1380.	1400.	1400.	1400.	1300.	1260.	1220.	1270.	1340.
1840.	1780.	1720.	1670.	1650.	1600.	1540.	1480.	1440.	1380.
1390.	1360.	1320.	1200.	1200.	1200.	1200.	1240.	1280.	1260.
1210.	1100.	1160.	1160.	1140.	1140.	1140.	1140.	1140.	1140.
1140.	1160.	1180.	1200.	1300.	1350.	1380.	1360.	1360.	1340.
1350.	1360.	1400.	1400.	1400.	1320.	1300.	1220.	1170.	1410.
1780.	1720.	1700.	1640.	1600.	1570.	1530.	1500.	1440.	1410.
1400.	1360.	1340.	1270.	1200.	1200.	1180.	1200.	1220.	1200.
1180.	1200.	1160.	1140.	1160.	1160.	1160.	1160.	1150.	1140.
1140.	1160.	1180.	1200.	1300.	1340.	1390.	1380.	1340.	1320.
1340.	1360.	1380.	1400.	1380.	1300.	1250.	1200.	1160.	1400.
1710.	1780.	1730.	1650.	1600.	1570.	1520.	1490.	1430.	1400.
1380.	1360.	1320.	1280.	1240.	1200.	1200.	1240.	1220.	1240.
1210.	1160.	1160.	1140.	1160.	1160.	1140.	1140.	1140.	1140.
1140.	1140.	1180.	1220.	1280.	1350.	1380.	1360.	1340.	1320.
1350.	1370.	1400.	1400.	1400.	1310.	1240.	1200.	1140.	1300.
1680.	1720.	1740.	1660.	1600.	1560.	1500.	1460.	1400.	1390.
1400.	1400.	1370.	1340.	1290.	1230.	1200.	1240.	1240.	1240.
1220.	1160.	1160.	1170.	1160.	1160.	1160.	1160.	1160.	1160.
1160.	1160.	1200.	1230.	1300.	1320.	1350.	1360.	1320.	1300.
1320.	1340.	1360.	1400.	1360.	1300.	1230.	1200.	1120.	1420.
1720.	1700.	1660.	1640.	1600.	1540.	1480.	1440.	1400.	1420.
1440.	1400.	1380.	1370.	1290.	1220.	1200.	1230.	1260.	1260.
1220.	1170.	1190.	1200.	1160.	1160.	1160.	1160.	1160.	1160.
1160.	1180.	1200.	1240.	1280.	1320.	1360.	1340.	1300.	1300.
1320.	1340.	1360.	1400.	1300.	1250.	1180.	1150.	1100.	1440.
1680.	1700.	1660.	1600.	1560.	1500.	1450.	1430.	1420.	1440.
1460.	1420.	1370.	1350.	1290.	1240.	1200.	1240.	1260.	1240.
1220.	1210.	1180.	1200.	1180.	1180.	1160.	1160.	1160.	1160.
1170.	1180.	1200.	1230.	1280.	1340.	1340.	1320.	1300.	1310.
1320.	1340.	1360.	1400.	1300.	1240.	1180.	1140.	1100.	1440.

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
and Vegetation (Y) Data (Sheet 11)

1650,	1650,	1620,	1500,	1260,	1570,	1470,	1450,	1440,	1440,
1490,	1440,	1380,	1300,	1230,	1240,	1220,	1250,	1260,	1220,
1200,	1200,	1180,	1180,	1180,	1180,	1100,	1170,	1180,	1140,
1150,	1150,	1200,	1240,	1200,	1330,	1270,	1250,	1260,	1300,
1520,	1350,	1340,	1360,	1320,	1250,	1190,	1160,	1100,	
1520,	1610,	1560,	1510,	1500,	1460,	1430,	1410,	1430,	1420,
1440,	1420,	1380,	1320,	1260,	1260,	1240,	1260,	1260,	1230,
1200,	1200,	1180,	1200,	1190,	1230,	1170,	1170,	1180,	1180,
1180,	1180,	1180,	1200,	1220,	1230,	1210,	1240,	1250,	1280,
1280,	1260,	1260,	1220,	1300,	1250,	1170,	1100,	1100,	
1600,	1550,	1500,	1450,	1400,	1360,	1360,	1350,	1360,	1360,
1380,	1360,	1340,	1200,	1280,	1240,	1240,	1250,	1260,	1230,
1200,	1200,	1210,	1200,	1200,	1190,	1175,	1170,	1165,	1160,
1155,	1170,	1160,	1230,	1220,	1200,	1240,	1280,	1260,	1270,
1520,	1500,	1440,	1310,	1260,	1150,	1130,	1080,	1080,	1350,
1500,	1450,	1400,	1400,	1400,	1450,	1380,	1420,	1400,	1240,
1300,	1300,	1310,	1280,	1260,	1260,	1260,	1240,	1230,	1240,
1250,	1210,	1220,	1210,	1200,	1150,	1180,	1170,	1160,	1160,
1160,	1175,	1160,	1170,	1160,	1210,	1250,	1300,	1300,	1280,
1300,	1360,	1330,	1300,	1200,	1150,	1100,	1080,	1120,	
1500,	1450,	1400,	1400,	1500,	1470,	1410,	1460,	1460,	1440,
1390,	1320,	1300,	1260,	1270,	1300,	1250,	1240,	1240,	1240,
1250,	1220,	1200,	1180,	1230,	1155,	1175,	1180,	1160,	1160,
1160,	1185,	1200,	1210,	1200,	1250,	1260,	1280,	1310,	1300,
1300,	1340,	1300,	1280,	1200,	1130,	1080,	1090,	1120,	
1560,	1540,	1560,	1510,	1550,	1550,	1470,	1440,	1510,	1460,
1400,	1370,	1320,	1290,	1280,	1270,	1240,	1230,	1220,	1220,
1200,	1220,	1205,	1190,	1190,	1175,	1170,	1160,	1160,	1175,
1175,	1160,	1200,	1200,	1200,	1260,	1300,	1310,	1315,	1325,
1300,	1330,	1320,	1260,	1150,	1140,	1080,	1060,	1120,	
1550,	1580,	1570,	1580,	1610,	1600,	1530,	1470,	1520,	1470,
1440,	1380,	1320,	1280,	1260,	1260,	1240,	1240,	1220,	1210,
1220,	1220,	1200,	1190,	1175,	1170,	1160,	1160,	1160,	1180,
1200,	1200,	1240,	1260,	1220,	1240,	1260,	1320,	1340,	1340,
1300,	1320,	1320,	1260,	1210,	1170,	1110,	1130,	1120,	
1640,	1660,	1650,	1660,	1640,	1630,	1580,	1520,	1530,	1500,
1430,	1370,	1320,	1280,	1280,	1270,	1240,	1240,	1220,	1200,
1200,	1210,	1210,	1180,	3*1160,			1170,	1180,	1200,
1210,	1270,	1320,	1300,	1300,	1240,	1320,	1360,	1350,	
1300,	1320,	1330,	1260,	1210,	1160,	1130,	1115,	1120,	
1600,	1670,	1740,	1770,	1720,	1660,	1620,	1600,	1540,	1470,
1380,	1320,	1300,	1280,	1280,	1280,	1260,	1250,	1220,	1200,

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 12)

1200.	1150.	1170.	1155.	1160.	1160.	1180.	1200.
1210.	1400.	1320.	1250.	1340.	1320.	1330.	1360.
1320.	1330.	1210.	1170.	1150.	1120.	1100.	
1420.	1710.	1740.	1710.	1590.	1630.	1540.	1460.
1400.	1300.	1280.	1270.	1250.	1240.	1220.	1200.
1220.	1210.	1190.	1170.	1160.	1160.	1185.	1200.
1225.	1300.	1330.	1320.	1340.	1350.	1375.	1350.
1340.	1330.	1240.	1150.	1160.	1140.	1110.	
1640.	1710.	1760.	1740.	1700.	1610.	1550.	1460.
1440.	1400.	1330.	1240.	1250.	1220.	1215.	1210.
1230.	1240.	1190.	1130.	1170.	1160.	1195.	1195.
1220.	1300.	1330.	1330.	1370.	1380.	1400.	1380.
1360.	1380.	1340.	1210.	1170.	1140.	1150.	
1600.	1700.	1730.	1740.	1650.	1600.	1540.	
1510.	1450.	1330.	2*1300.	1260.	1260.	1230.	1220.
1260.	1240.	1220.	1200.	1175.	1160.	1180.	1195.
1225.	1300.	1400.	1350.	1380.	1430.	1430.	1390.
1380.	1380.	1310.	1250.	1150.	1140.	1170.	
1620.	1630.	1740.	1700.	1620.	1570.	1520.	1470.
1400.	1300.	1330.	1235.	1255.	1230.	1220.	1250.
1265.	1230.	1215.	1210.	2*1200.	2*1180.	1200.	1200.
1240.	1300.	1410.	1360.	1450.	1460.	1440.	1405.
1370.	1370.	1320.	1280.	1130.	1140.	1150.	1200.
1620.	1710.	1780.	1830.	1730.	1540.	1525.	1500.
1450.	1420.	1360.	1320.	1370.	1250.	1230.	1260.
1260.	1240.	1240.	1215.	1235.	1190.	1200.	1215.
1250.	1340.	1420.	1350.	1450.	1510.	1450.	1390.
1325.	1340.	1300.	1340.	1160.	1180.	1240.	
1600.	1650.	1750.	1840.	1660.	1640.	1600.	1570.
1510.	1360.	1350.	1330.	1270.	2*1240.	1260.	1260.
1240.	1230.	1220.	1215.	1220.	1200.	1205.	1220.
1245.	1310.	1340.	1340.	1450.	1520.	1430.	1360.
1310.	1320.	1280.	1330.	1280.	1200.	1240.	
1600.	1620.	1720.	1790.	1730.	1660.	1580.	1510.
1450.	1420.	1365.	1330.	1400.	2*1260.	1265.	1250.
1240.	1230.	1225.	2*1220.	1240.	1200.	1180.	1200.
1235.	1300.	1315.	1280.	1410.	1490.	1520.	1400.
1300.	1310.	1340.	1310.	1160.	1200.	1260.	1500.
1700.	1630.	1670.	1760.	1770.	1690.	1640.	1580.
1460.	1430.	1350.	1320.	1250.	1270.	1250.	1260.
1240.	1230.	1230.	1225.	1220.	2*1200.	1240.	1200.
1230.	1260.	1300.	1375.	1500.	1490.	1400.	1340.

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 15)

1330	1250	1320	1370	1430	1410	1420	1450	1460	1520
1510	1420	1460	1480	1340	1250	1130	1160	1230	
2000	2000	2020	2050	2080	2100	2030	2010		2040
1970	1900	1750	1710	1650	1550	1450	1420		1395
1340	1320	1300	1320	1250	1260	1140	1420	1480	1460
1360	1300	1340	1400	1460	1450	1480	1470	1500	1510
1520	1410	1400	1440	1340	1220	1120	1160	1220	
2050	2000	2020	2070	2160	2100	2020	2030	2070	2000
1950	1900	1800	1700	1630	1560	1530	1480	1420	1390
1350	1330	1330	1350	1300	1200	1340	1400	1480	1460
1360	1300	1360	1420	1500	1500	1520	1480	1540	1530
1500	1400	1320	1350	1300	1200	1120	1140	1200	
2020	2000	2010	2050	2120	2100	2000	2030	2050	1980
1930	1850	1750	1670	1640	1610	1550	1480	1420	1400
1390	1350	1360	1370	1300	1200	1330	1400	1500	1460
1370	1300	1340	1420	1500	1510	1540	1510	1540	1520
1460	1390	1320	1260	1230	1180	1120	1140	1220	
2040	2000	2030	2020	2080	2050	2010	2060	2050	1970
1900	1820	1740	1660	1630	1600	1540	1480	1430	1390
1380	1380	1370	1380	1300	1260	1330	1420	1480	1450
1370	1300	1340	1420	1470	1460	1500	1500	1500	1510
1450	1380	1300	1250	1200	1130	1120	1150	1200	
2040	1970	1960	1980	2020	1960	2000	2080	2000	1930
1850	1760	1700	1670	1660	1620	1550	1500	1440	1400
1390	1360	1380	1390	1310	1250	1350	1420	1470	1420
1360	1320	1340	1350	1420	1440	1460	1500	1450	1430
1390	1380	1290	1220	1170	1120	1130	1150	1200	
2040	1960	1960	1980	1960	2*2000	2080	1990	1930	
1870	1820	1800	1730	1660	1600	1570	1500	1450	1410
1400	1380	1390	1380	1320	1270	1350	1420	1480	1420
1380	1330	1320	1390	1440	1470	2*1500	1450	1400	
1350	1320	1300	1250	1200	1130	1140	1160	1160	
1970	1960	1940	1940	1960	2000	2010	2070	2080	1980
1920	1880	1750	1720	1680	1650	1600	1520	1440	1430
1410	1400	1410	1350	1320	1270	1330	1420	2*1500	
1410	1360	1320	1380	1420	1440	2*1500	1460	1420	
1400	1370	1340	1290	1220	1160	1160	1220	1220	
1940	1960	1960	1960	2000	1980	2020	2060	2100	2050
2000	1920	1840	1780	1730	1660	1620	1500	1450	1425
1420	1425	1420	1380	1310	1280	1350	1410	1490	1500
1430	1360	1330	1370	1430	1490	1480	1490	1480	1420
1380	1320	1300	1280	1220	1120	1200	1280	1300	

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 16)

34200J	1955	2020	2010	2030	2040	2110	2040
1970	1620	1730	1610	1540	1500	1660	1440
1450	1340	1430	1280	1340	1400	1420	1400
1420	1300	1450	1400	1500	1500	1480	1420
1370	1260	1170	1140	1210	1270	1330	
2000	2040	2000	2040	2010	2080	2160	2060
1960	1830	1760	1640	1640	1540	1480	1460
1500	1460	1330	201300	1340	1340	1380	
1400	1360	1320	1480	1520	1480	1470	1410
1350	1250	1210	1140	1170	1210	1270	1320
2040	2060	2020	2000	2050	2020	2100	2070
2000	1850	1800	1750	1580	1610	1550	1480
1500	1450	1380	1330	1350	1280	1290	1340
1400	1350	1370	1470	1520	1540	1500	1410
1370	1300	1260	1150	1170	1230	1270	1320
2100	2060	2080	2010	2070	2050	2070	2160
2030	1860	1600	1740	1660	1560	1520	1500
1420	1350	1320	1360	1380	1320	201300	1340
1350	1300	1340	1480	1510	1560	1510	1450
2060	2100	2110	2050	2140	1180	1230	1280
1950	1860	1750	1650	1640	1570	1570	1450
1400	1360	1340	1380	1420	1380	201300	1380
1420	1360	1340	1400	1500	1530	1550	1520
1350	1300	1250	1200	1160	1140	1180	1230
2100	2120	2130	2050	2030	2090	2070	2100
2000	1930	1870	1800	1730	1650	1580	1520
1450	1400	1380	201400	1350	1350	1300	1400
1440	1380	1350	1400	1500	1580	1600	1400
1320	1270	1220	1200	1150	1140	1200	
2150	2120	2120	2080	2050	2070	2100	2120
2040	1960	1900	1800	1730	1660	1590	1540
1470	1430	1450	1420	1370	1320	1310	1400
1490	1400	1350	1400	1500	1580	1600	1440
1350	1320	1260	1210	1190	1150	1140	1160
2160	2140	2160	2120	2070	2080	2050	2100
2070	1960	1900	1800	1740	1680	1600	1560
1500	1420	1420	1410	1360	1360	1340	1420
1500	1450	1360	1380	1450	1500	1600	1460
1400	1360	1300	1270	1230	1170	1140	1180
2160	2170	2160	2140	2110	2080	2060	2100
2070	1970	1900	1800	1730	1680	1600	1520

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 17)

1450	1420	1400	1360	1370	1360	1340	1360	1360	1420
1500	1460	1360	1300	1430	1440	1570	1560	1500	1430
1370	1350	1320	1300	1300	1220	1120	1160	1180	
2080	2120	2140	2100	2160	2120	2070	2080	2090	2130
2020	1950	1800	1770	1670	1640	1630	1550	1500	1460
1435	1410	1370	1360	1390	1360	1340	1340	1350	1400
1500	1450	1360	1500	1440	1500	1600	1560	1480	1420
1420	1350	1340	1250	1230	1160	1150	2*1200		
2080	2100	2140	2150	2200	2120	2100	2120	2120	2120
2000	1900	1800	1750	1600	1500	1530	2*1500	1450	
1420	2*1400	2*1440		1360	1360	1350	1360	1360	1380
1460	1460	1380	1360	1440	1500	1600	1580	1500	1440
1430	1400	1340	1300	1100	1140	1170	1220	1200	
2080	2100	2120	2140	2180	2140	2120	2160	2170	2100
2000	1900	1800	1700	1650	1600	1590	1550	1480	1430
1420	1430	1430	1430	1440	1360	1370	1360	1360	1370
1430	1430	1350	1580	1410	1470	1580	1580	1500	1400
1370	1340	1300	1240	1180	1120	1180	1240	1260	
2020	2030	2060	3*2100			2110	2160	2170	2070
1970	1870	1780	1710	1680	1640	1540	1620	1520	1470
1450	1420	1400	1350	1370	1360	1390	1400	1370	1370
1430	1460	1400	1380	1400	1440	1540	1580	1500	1400
1340	1320	1300	1260	1220	1140	1170	1230	1300	
2080	2100	2*2080		2*2100	2110	2110	2120	2130	2100
1900	1820	1760	1700	1700	1640	1640	1540	1500	1460
1420	1380	1360	1350	1400	1400	1410	1380	1370	1440
1500	1410	1380	1350	1430	1500	1600	1500	1400	
1330	1260	1260	1260	1180	1140	1160	1200	1250	
2020	2050	2100	2130	2130	2120	2100	2110	2140	2000
2020	1920	1840	1760	1770	1700	1720	1660	1570	1540
1500	1420	1380	1400	1410	2*1420	1410	1380	1370	
1440	1520	1440	1400	1400	1370	1390	1470	1500	1400
1320	1260	1240	1200	1160	1150	1140	1180	1220	
2060	2060	2100	2130	2130	2120	2110	2120	2130	2070
2000	1900	1840	1820	1800	1760	1720	1650	1560	1560
1500	2*1400	1420	2*1440			1430	1420	1370	1380
1440	1500	1450	1410	1400	1430	1490	1550	1500	1400
1300	1250	1200	1200	1170	1150	1140	1160	1190	
2100	2140	2160	2200	2180	2130	2110	2120	2140	2060
1480	1920	1670	1630	2*1800		1700	1600	1500	1540
1500	1400	1420	1440	1460	1480	1460	1420	1380	1350
1400	1500	1460	1430	1410	1420	1480	1520	1500	1380

Figure 6.2, Namelist Printout of Sample Case Elevation (Z)
and Vegetation (V) Data (Sheet 18)

1300,	1450,	1260,	1220,	1190,	1150,	1140,	1150,	1180,
2100,	2150,	2200,	2240,	2130,	2070,	2140,	2120,	2080,
1580,	1520,	1900,	1330,	1840,	1750,	1670,	1600,	1530,
1440,	1420,	1450,	1430,	1500,	1500,	1500,	1450,	1330,
1370,	1450,	1500,	1450,	1410,	1420,	1400,	1530,	1480,
1350,	1330,	1250,	1220,	1180,	1160,	1150,	1150,	1160,
2130,	2150,	2160,	2240,	2230,	2160,	2140,	2120,	2060,
1950,	1920,	1940,	1900,	1750,	1710,	1620,	1580,	1520,
1500,	1480,	1450,	1500,	1540,	1510,	1510,	1460,	1390,
1350,	1400,	1480,	1460,	1420,	1420,	1450,	1520,	1500,
1400,	1350,	1320,	1260,	201200,	1160,	1160,	1160,	1150,
2150,	42200,			2160,	2120,	2080,	2060,	2010,
1960,	1970,	1940,	1850,	1780,	1740,	1700,	1600,	1540,
1550,	1540,	1530,	1540,	1580,	1560,	1500,	1430,	1380,
1340,	1370,	1440,	1480,	1440,	1420,	1440,	1490,	1520,
1420,	1400,	1360,	1300,	1240,	1230,	1220,	1170,	1150,
2190,	2220,	2240,	2200,	2160,	302120,			2070,
2010,	2010,	1970,	1820,	1900,	1740,	1680,	1600,	1530,
1620,	1600,	1580,	1580,	1530,	1520,	1500,	1440,	1370,
1320,	1340,	1410,	1470,	1440,	201440,		1475,	1500,
1480,	1460,	1420,	1340,	1300,	1280,	1260,	1220,	1170,
2200,	2150,	2200,	2150,	2125,	2100,	2060,	2060,	2050,
2050,	2020,	1950,	1800,	1750,	1640,	1620,	1600,	1610,
1680,	1610,	1575,	1540,	1480,	1480,	1440,	1380,	1350,
1300,	1320,	1400,	1480,	1460,	1460,	1450,	1480,	1480,
1440,	1430,	1410,	201400,	1350,	1300,	1250,	1190,	
2100,	2120,	202100,		2160,	2240,	2220,	2150,	2080,
2040,	1920,	1880,	1480,	1830,	1750,	301650,		1700,
1660,	1580,	1560,	1540,	1510,	1420,	201400,	1360,	1290,
1290,	1320,	1350,	1480,	301480,		1530,	1600,	1530,
1500,	1440,	1450,	1440,	1400,	1360,	1280,	1230,	1200,
2050,	2020,		2070,	2140,	2200,	2260,	2200,	2120,
2020,	1920,	1830,	1780,	1800,	1700,	1650,	1680,	1660,
1600,	1550,	1500,	401450,		1440,	1410,	1350,	1280,
1300,	1370,	1460,	1520,	1580,	1530,	1590,	1610,	1550,
1480,	1480,	1500,	1420,	1350,	1320,	1250,	201250,	
302000,		2040,	2040,	2090,	2160,	2220,	2180,	2100,
1980,	1670,	1820,	1720,	1700,	1630,	1650,	1600,	1570,
1460,	1470,	1500,	1570,	1540,	1480,	1510,	1480,	1420,
1280,	1320,	1400,	1470,	1530,	1580,	1610,	1620,	1620,
1520,	1500,	1500,	1450,	1420,	1370,	1300,	1290,	1250,
302000,			2040,	2080,	2150,	2200,	2150,	2050,

Figure 6.2. Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 19)

1700, 1650,	1750,	1700,	1720,	1700,	1580,	1560,	2*1580,
2*1530,	1640,	1620,	1530,	1500,	1550,	1430,	1350,
1265, 1290,	1380,	1440,	1500,	1500,	1600,	1620,	2*1600,
1560, 1540,	1510,	1450,	1380,	1340,	2*1300,	1200,	
3*2120,	2150,	2100,	2100,	2220,	2140,	2050,	1980,
1380, 1810,	1770,	1680,	1630,	1500,	1620,	1600,	1630,
4*1660,	1640,	2*1600,	1640,	2*1600,	1520,	1410,	1330,
1275, 1260,	1340,	1420,	1450,	1340,	1560,	1530,	1450,
2*1550,	1500,	1420,	1340,	1270,	1240,	1170,	
3*2150,	2*2100,	2*2100,	2200,	2240,	2140,	2040,	1960,
1880, 1820,	1770,	1750,	1650,	1620,	1540,	1660,	1680,
4*1720,	1740,	1720,	1680,	1630,	1580,	1510,	1420,
1280, 1250,	1330,	1380,	1300,	1460,	1500,	1400,	1480,
1480, 1520,	1450,	1380,	1320,	1260,	1200,	1180,	1160,
2*2150,	2100,	2150,	2160,	2260,	2220,	2100,	2040,
1850, 1840,	1810,	1770,	1680,	1620,	1690,	1700,	1730,
3*1800,	1750,	1680,	1680,	1600,	1550,	1490,	1400,
1280, 1240,	2*1300,	1350,	1350,	1430,	1400,	1440,	1470,
1440, 1460,	1400,	1330,	1230,	1240,	1180,	1160,	1140,
2*2100,	2140,	2200,	2230,	2260,	2220,	2100,	2020,
1940, 1870,	1800,	1770,	1720,	1680,	1700,	1760,	1780,
1820, 1840,	1815,	1755,	1670,	1600,	1520,	1460,	1400,
1300, 1240,	1240,	1250,	1360,	1420,	1380,	1300,	1370,
2*1400,	1330,	1260,	1240,	1220,	1200,	1160,	1140,
3*2140,	2220,	2*2260,	2180,	2100,	2020,	1970,	
1980, 1900,	1860,	1820,	1810,	1730,	1700,	1790,	2*1840,
1880, 1840,	1800,	1720,	1680,	1570,	1520,	1470,	1400,
1290, 1260,	1240,	1290,	2*1320,	1350,	1280,	1300,	1330,
1340, 1340,	1320,	2*1760,	1230,	1190,	1160,	1140,	
3*2160,	2210,	2240,	2260,	2160,	2060,	2000,	1960,
1900, 1880,	1850,	1830,	1810,	1740,	1780,	1840,	1900,
1820, 1770,	1700,	1640,	1520,	1540,	1460,	1380,	1330,
1260, 1220,	1270,	1300,	1240,	1260,	1240,	2*1260,	
1280, 3*1300,	1240,	1180,	1160,	1160,	1170,	1170,	1170,
4*2200,	2260,	2200,	2160,	2050,	1980,	1940,	
1940, 1900,	1840,	3*1600,	1860,	1900,	1940,	1900,	
2*1800,	1760,	1690,	1580,	1500,	1400,	1360,	1300,
1280, 1265,	1240,	4*1200,	1200,	1180,	1160,	2*1170,	
1260, 3*1300,	1280,	2220,	2100,	2040,	2000,	2000,	
4*2240,	2000,	1950,	1860,	1820,	1960,	1940,	1880,
1760, 1460,	2*1700,	1600,	1530,	1450,	1400,	1380,	1340,

Figure 6.2. Namelist Printout of Sample Case Elevation (Z)
 and Vegetation (V) Data (Sheet 20)

1300, 1250, 1200, 1250, 1200, 1240, 1240, 1220, 1220,
 1230, 1240, 1250, 1200, 1180, 1180, 1180, 1180,
 5*2200, 2240, 2140, 2060, 2*2000, 1180,
 2030, 1900, 2*1900, 2*1900, 2*1900, 2060, 2*2000, 1900,
 1750, 1600, 1500, 1500, 1500, 1520, 1460, 1400, 1360, 1340,
 1305, 1250, 1300, 1200, 1200, 2*1240, 3*1200,
 3*1200, 1180, 1160, 4*1160,
 2150, 3*2100, 2200, 2250, 2150, 2*2100, 2150,
 2000, 1970, 1930, 1960, 3*2020, 1980, 1920, 1840,
 1600, 1650, 1610, 1550, 1500, 1400, 1420, 1380, 1360, 1320,
 1300, 1275, 1275, 1300, 1280, 1260, 4*1200,
 3*1180, 5*1160, 1180,
 2*2100, 2*2300, 2250, 2180, 2*2160,
 2060, 2000, 1970, 1930, 2060, 2080, 2030, 1950, 1900, 1850,
 1800, 1700, 1640, 1580, 1500, 1460, 1410, 1360, 1320, 1310,
 1270, 1260, 1270, 1340, 1300, 1240, 4*1200,
 3*1220, 1200, 3*1160, 2*1160,
 2120, 2150, 2200, 2250, 2*2300, 2150, 3*2150,
 2100, 2050, 2*2000, 2*2050, 2000, 1900, 1830, 1760,
 1700, 1650, 1630, 1500, 2*1500, 1420, 1350, 1340, 1295,
 1290, 1200, 1200, 1250, 1300, 1250, 1200, 1220, 1220, 1230,
 1250, 2*1200, 1200, 3*1180, 2*1160,
 3*2200, 2250, 2*2200, 2*2150, 2*2100,
 2100, 2060, 2000, 2060, 2020, 1980, 1900, 1850, 1800,
 1700, 1620, 1530, 1500, 1530, 1500, 1380, 1320, 2*1280,
 1270, 1240, 1230, 2*1240, 2*1200, 3*1240,
 1280, 1320, 1260, 1190, 5*1170, 2120, 2*2080, 2060,
 2100, 2150, 4*2200, 1980, 1900, 1840, 1820,
 2050, 2080, 2060, 2020, 2000, 1950, 1970, 1310, 1270, 1250,
 1750, 1630, 1550, 1460, 1440, 1470, 1230, 1250, 1300,
 1240, 1270, 1210, 1205, 2*1200,
 2*1300, 1200, 1260, 5*1160, 2120, 2060, 2*2040,
 6*2100, 2020, 2040, 2020, 2000, 1900, 1900, 1820, 1780,
 1720, 1640, 1550, 1490, 2*1400, 1380, 1330, 1300, 1265,
 1235, 4*1200, 1240, 1260, 2*1300,
 1300, 1240, 1200, 6*1180, 2120, 2060, 2*2040,
 2200, 2150, 2200, 2240, 2200, 2150, 2100, 2020, 2000, 2*1580,
 2*2000, 1920, 3*1870, 2*1820, 1760,
 1700, 1630, 1550, 1480, 1420, 1400, 1300, 1280, 1260,
 1220, 3*1200, 1220, 1260, 3*1300, 1260,
 1240, 3*1160, 5*1160,

Figure 6.2. Namelist Printout of Sample Case Elevation (Z)
and Vegetation (V) Data (Sheet 21).

3*2200, 2150, 2*2100, 2050, 2020, 2000, 1960,
1950, 1800, 1940, 1920, 2*1800, 5*1780, 1770,
1700, 1610, 1520, 2*1400, 1420, 1350, 2*1260, 1240,
4*1220, 1250, 1350, 2*1320, 1250, 1200,
1200, 1160, 1170, 1180, 1180, 1170, 1160, 1180, 2020,
2200, 2160, 2140, 2100, 2060, 3*2040,
1960, 1900, 2*1830, 1600, 2*1750, 1700, 2*1780,
1600, 1600, 1520, 2*1400, 1400, 1300, 1240, 1250, 1220,
1220, 1220, 1230, 1230, 2*1340, 1280, 1220, 1180,
5*1180,
3*2200, 2100, 3*2100, 2060, 2050, 2020,
2000, 1920, 1840, 1780, 1750, 3*1700, 1760, 1750,
1660, 1500, 1480, 3*1410, 1300, 1240, 3*1220,
1240, 1240, 1240, 1280, 1350, 1310, 1220, 2*1180,
1180, 2*1160, 2*1160, 1190, 3*1180, 2080, 2020,
2*2200, 3*2100, 2140, 2*2100, 2080, 2020,
1960, 1900, 1850, 1780, 1700, 1680, 1660, 1720, 1700,
1650, 1550, 1450, 1350, 1340, 1280, 1240, 2*1240,
3*1240, 1200, 1275, 1300, 1220, 3*1180,
3*1160, 2*1180, 2*1300, 2*1180,
2200, 2150, 2*2100, 3*2150, 2100, 2080, 2000,
1950, 1880, 1820, 1730, 1710, 1690, 1640, 1680, 1650,
1600, 1510, 1410, 1340, 1310, 1270, 2*1240, 1260, 1260,
1240, 1250, 1260, 1215, 1225, 1200, 4*1180, 2*1180,
4*1180, 3*1200,

terrain data by hand as was done for this sample case, and normal use of the model for various SIAF studies would probably not require as extensive an effort as was undertaken for this project.

As with relief, considerably more effort than normally required was taken to input vegetation data since the objective of the simulation was to duplicate as best as possible the test situation. As described in Section 2.4.1, a vegetation survey of the Hunter Liggett area was conducted for the purpose of obtaining input data for this simulation. During this survey, aerial photographs of the area were obtained, a ground survey was conducted, and the vegetation in the area was categorized according to the classification scheme shown in Figure 2.7. From this information, the vegetation data for the 50-meter grid square resolution were recorded on computer input sheets. The last part of Figure 6.2 shows namelist printout of these data from which Tape 8 was generated. Because of the difficulties of correlating the aerial photograph with the map, this exercise took approximately three weeks; however, normal use of the model would require a far less extensive effort. In fact, with the aid of the namelist input the vegetation of the entire area could be input with one card if the user desired to specify a constant vegetation class for the area.

6.3 USER INPUT AND DATA BASE

Values corresponding to the variables of Tables 3-1 and 3-2 are presented in Figure 6.3. The data base in NAML1 consists of the first three pages of this Figure. The user inputs with the exception of the target data are in NAML2 which starts on the third page of Figure 6.3, while the target data (NAML3) starts on the seventh page of Figure 6.3. The user input for the sample case has been organized alphabetically so there is a one-to-one correspondence between this sample case and the inputs described in Section 3.0.

In order to exercise the dynamic route and external fire support options of the model, this sample case was organized as follows: For targets 1 and 2, the decision rule used was for SIAF to move toward these targets in an attempt to identify them. Once targets were identified, external fire support was to be called on the targets. For targets 3 and 4, the decision rule was to avoid these targets, if detected, by moving around them. For


```

VEUC = 15.00 1.00 3.00 35.00 30.00 25.00 3.00 0.50 10.00 0.05 3.00 33.00 20.00
20.00 31.00 0.50
4.00 0.70 3.00 31.00 20.00 27.00 32.00 0.20 2.00 0.40 2.00 30.00 25.00 50.00
35.00 0.50
5.00 0.30 3.00 27.00 27.00 27.00 3.00 3.45 15.00 0.00 3.00 20.00
23.00 27.00 27.00 27.00
7.50 0.70 2.00 27.00 27.00 27.00 32.00 0.35 7.50 0.65 2.00 25.00
20.00 55.00 30.00 0.30
1.00 0.20 2.00 25.00 24.00 20.00 34.00 0.20 2.00 0.40 2.00 20.00
23.00 50.00 32.00 0.30
1.50 0.30 1.00 27.00 22.00 50.00 33.00 0.25 1.00 0.20 1.00 25.00
20.00 27.00 24.00 0.20
2.00 0.30 1.00 30.00 25.00 22.00 32.00 0.50 1.00 0.20 1.00 20.00 23.00
63.00 35.00 0.40
4.00 0.90 3.00 40.00 35.00 37.00 32.00 0.40 10.00 0.20 3.00 40.00
35.00 0.10 34.00 0.50
VEUF = 1.00 0.95 0.70 0.40 0.20 0.10 0.70 0.60 0.20 0.40 0.30 0.20
0.30 0.20 0.20 0.20
VISLUM = 4000.00 1500.00 1300.00 1000.00 2000.00 500.00 300.00 50.00
1000.00 500.00 1000.00 100.00 100.00 500.00 500.00 100.00 10.00
240.00 10.00 10.00 10.00 10.00 10.00 24.00 1.00 0.50 0.10 0.01
240.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
240.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
240.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
240.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
VISMJ = 13.00
VISM = 20.00
VIPT = 0.00
W = 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00
4.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00
4.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00 3.00
MAT = 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
ALP = 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00
LENU
LIML2 = 40.00
BETA = 100.00
BLIFE = 0.00
DMUR = 0.00
DMUR2 = 0.00

```

Figure 6.3, Namelist Printout of Sample Case User Input (Sheet 3)


```

KHAJUS = 1.0
KALZ = 50.0
KALGZ = 2.0
KAP = 10.0
KAPR = 25.0
KPCOR = 0.0
SAMJ = 40.0
SC(1) = 1.7
SC(2) = 0.5
SC(3) = 1.0
SC(4) = 0.0
SC(5) = 0.04
SC(6) = 32.0
SCALE = 50000.0
SPEC = 0.0
TOLSTR = 60.0
TOLRUS = 30.0
TOLUR = 0.0
TOLUN = 40.0
TOLIN = 10.0
THEATA = 30.0
TPCOR = 1.0
TPREP = 0.0
ISR = 255.0
TSS = 182.0
TUSE = 0.5
VELM = 4000.0
VH = 577.0
VK = 7020.0
MAY = 63.0
2310.0 2350.0 2014.0 0110.0 4150.0 500.0 501.0 75.0 79.0 69.0 63.0
72.0 75.0 470.0 51.0 50.0 51.0 47.0 48.0 5052.0 90.0 97.0 98.0 85.0
98.0 94.0 420.0 20.0 23.0 40.0 22.0 20.0 20.0 4224.0 1000.0 2.0 1.0
3.0 4.0 2.0 501.0 3.0 5.0 2.0 15.0 0.0 506.0 30300.0 030.0 190.0
5305.0
MUL = 0.0
MDM = 0.0
MTC = 1.0
MTH = 1.0
MIS = 4.0
XAVGJD=0.0
AAVULJ=J.0
XBASE = 5600.0
XULINS = 40.0
XAL = 5032.0

```

Figure 6.3, Namelist Printout of Sample Case User Input (Sheet 6)

targets 5 through 51, no dynamic movement was used. Instead, once detected, these targets were removed from the simulation and subsequent identification was not attempted.

6.4 MODEL OUTPUTS

The outputs of the model consist of detail and summary printout. Detail printout presented in Figure 6.4 begins with some target transformations and then shows the X and Y coordinates of the SIAF location, the target currently being considered under the dynamic route option, and the current time in seconds. The second page of Figure 6.4, for example, indicates that IDTAR equals zero. Thus, there are no targets currently being considered for the dynamic route option at the simulation time shown. The third page of Figure 6.4 indicates that the dynamic route option was taken by the patrol at the time shown. Subsequent printout reveals that the patrol was moving toward the first target in an attempt to identify it. Finally, the fifth page of Figure 6.4 shows the result of an external fire support mission which was called on target number 2 and later on target number 1. This detail printout continues and presents a time history of a portion of the operation by showing when a dynamic route is used, the results of the external fire support missions, and the location of the patrol throughout the entire mission.

Summary printout of the simulation of the mission for all 51 targets is presented in Figure 6.5. Table 6-1 presents a brief description of these targets. For this summary printout, the dynamic route option described above was not used; hence, KREC(IT) was set equal to zero for all targets.

Included in Figure 6.5 are statistics pertaining to visual detection, target identification, aural detection, target location, movement, navigation, communications, supply maintenance, and human maintenance. As an example of the correlation of these results with the physical situation, Figures 6.6 and 6.7 are presented. Figure 6.6 shows the first six targets in the vicinity of the star cluster turn while Figure 6.7 shows the time line diagram associated with these targets.

A study of these Figures and Page 1 of the output data of Figure 6.5 reveals that for 5 replications, targets 1 through 3 were never visually detected by SIAF while targets 4 through 6 were always detected. Page 37

of the output reveals that the reasons for no detection on target 1 were primarily due to vegetation while targets 2 and 3 were always masked by relief. The aural detection statistics of Page 10 of Figure 6.5 indicate that targets 1, 2, and 5 were always detected by SIAF while target 4 (8 personnel) was not. Aural detection of target 3 and 6 was not feasible.

With respect to detections of SIAF, Page 19 of Figure 6.5 indicates that target 4 (8 personnel) visually detected SIAF once in 5 replications while Page 28 reveals no aural detections of SIAF by the enemy.

REPLICATION NUMBER	TASK NUMBER	ELAPSED TIME OF EXECUTION	NUMBER OF CASUALTIES ILLICITED BY AIRCRAFT	NUMBER OF CASUALTIES ILLICITED BY U.S. NAVY	NUMBER OF CASUALTIES ILLICITED BY U.S. MARINE CORPS	NUMBER OF CASUALTIES ILLICITED BY U.S. ARMY	NUMBER OF CASUALTIES ILLICITED BY U.S. AIR FORCE	NUMBER OF CASUALTIES ILLICITED BY U.S. COAST GUARD	NUMBER OF CASUALTIES ILLICITED BY U.S. NAVY (REPEATED)
XUYA, YUYA	1730.22382	1400.11447	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1720.55339	1370.91271	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1701.40315	1350.73342	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1692.51824	1403.15203	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1680.42407	1420.55273	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1670.95164	1430.05277	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1671.83229	1422.41020	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1663.74033	1470.55330	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1650.45402	1490.23469	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1643.53170	1507.23732	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1641.46923	1520.34492	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1633.97687	1542.45104	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1620.68431	1523.32131	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1610.91699	1577.26013	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1611.49926	1597.07334	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1604.23032	1616.55332	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1596.51434	1624.48734	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1589.32172	1600.89431	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1581.52929	1604.23173	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1571.44402	1604.23172	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1601.55331	1714.13114	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XUYA, YUYA	1730.223	1400.114	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1730.223	1400.114	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1720.553	1370.913	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1701.403	1350.733	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1692.518	1403.152	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1680.424	1420.553	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1670.952	1430.053	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1671.832	1422.410	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1663.740	1470.553	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1650.454	1490.234	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1643.532	1507.237	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1641.469	1520.345	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1633.977	1542.451	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1620.684	1523.321	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1610.917	1577.260	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1611.499	1597.073	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1604.230	1616.553	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1596.514	1624.487	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1589.322	1600.894	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1581.529	1604.231	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1571.444	1604.231	0.0	0.0	0.0	0.0	0.0	0.0	0.0
XSIAP, YSIAP	1601.553	1714.131	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Figure 6.4. Detailed Computer Output (Sheet 6)

XSIAP, VSIAP, IUIAP, ITIME	1354.474	1618.437	4	194589
XSIAP, VSIAP, IUIAK, ITIME	1367.408	1625.007	4	194782
XSIAP, VSIAP, IUIAK, ITIME	1368.417	1627.442	4	194909
XSIAP, VSIAP, IUIAK, ITIME	1372.003	1630.333	4	194919
XSIAP, VSIAP, IUIAK, ITIME	1374.033	1633.733	4	194969
XSIAP, VSIAP, IUIAK, ITIME	1378.033	1639.177	4	194968
XSIAP, VSIAP, IUIAK, ITIME	1377.033	1635.706	4	194120
XSIAP, VSIAP, IUIAK, ITIME	1378.301	1638.353	4	194131
XSIAP, VSIAP, IUIAK, ITIME	1381.125	1642.232	4	194193
XSIAP, VSIAP, IUIAK, ITIME	1383.333	1645.333	4	194254
XSIAP, VSIAP, IUIAK, ITIME	1387.033	1648.733	4	194263
XSIAP, VSIAP, IUIAK, ITIME	1387.544	1649.233	4	194310
XSIAP, VSIAP, IUIAK, ITIME	1391.544	1654.233	0	194401
XSIAP, VSIAP, IUIAK, ITIME	1407.244	1680.233	0	194434
XSIAP, VSIAP, IUIAK, ITIME	1412.033	1685.233	0	194530
XSIAP, VSIAP, IUIAK, ITIME	1408.377	1680.273	0	194625
XSIAP, VSIAP, IUIAK, ITIME	1407.302	1681.705	0	194640
XSIAP, VSIAP, IUIAK, ITIME	1407.802	1682.705	0	194717
XSIAP, VSIAP, IUIAK, ITIME	1437.002	1689.705	0	194767
XSIAP, VSIAP, IUIAK, ITIME	1434.001	1688.700	0	194793
XSIAP, VSIAP, IUIAK, ITIME	1433.345	1687.203	0	194821
XSIAP, VSIAP, IUIAK, ITIME	1434.771	1688.077	0	195032
XSIAP, VSIAP, IUIAK, ITIME	1437.430	1691.430	0	195017
XSIAP, VSIAP, IUIAK, ITIME	1437.036	1690.337	0	195114
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.988	0	195162
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.488	0	195253
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1675.988	0	195254
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1675.488	0	196455
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1675.403	0	197050
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1675.403	0	197057
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.488	0	199001
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.488	0	199032
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.483	0	198033
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	199234
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	199835
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	200436
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.400	0	201037
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.433	0	201601
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	201662
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	203463
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.433	0	203201
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.438	0	205232
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.433	0	207033
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.433	0	203801
XSIAP, VSIAP, IUIAK, ITIME	1427.075	1676.433	0	209022

Figure 6.4, Detailed Computer Output (Sheet 9)

XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	270000
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	270001
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	272654
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	280043
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	280051
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	280062
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	280081
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	281091
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	281099
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	282131
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	282140
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	282799
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	282901
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	283501
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	283711
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	283801
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	284441
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	284452
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	285033
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	285634
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	285235
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	286830
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	287431
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	288031
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	288032
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	287633
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	287673
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	289923
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	289902
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	289990
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291054
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291049
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291074
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291084
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291375
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291421
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291601
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291632
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	291654
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	292059
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	292601
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	292811
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	292801
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	295202
XSIAF,YSIAF,LOIAK,LTIME	090.707	200.0449	0	295003

Figure 6.4, Detailed Computer Output (Sheet 13)

XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	325030
XSIAP, YSIAP, IDIAP, IITIME	890.707	2800.449	0	325137
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	325234
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	325739
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	327040
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	327341
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	327601
XSIAP, YSIAP, IDIAP, IITIME	890.707	2800.449	0	327751
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328018
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328057
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328303
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328390
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328014
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328704
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	328879
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329021
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329177
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329312
XSIAP, YSIAP, IDIAP, IITIME	890.707	2800.449	0	329350
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329381
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329471
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329554
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329620
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329750
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329760
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329890
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329900
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329920
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	329974
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330042
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330103
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330201
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330291
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330312
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330351
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330370
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330426
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330470
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330527
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330538
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330581
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330632
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330680
XSIAP, YSIAP, IUTAP, IITIME	890.707	2800.449	0	330717

Figure 6.4, Detailed Computer Output (Sheet 15)

XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33770
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33760
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33777
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33810
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33805
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33873
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33923
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33940
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33954
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33962
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33915
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33916
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33921
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33970
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33801
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33707
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33709
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33701
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33701
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33707
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	338013
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330060
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	33372
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	333094
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	333132
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330101
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330235
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330310
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330401
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330476
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330437
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330521
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330535
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	330566
XSIAF, VSIAF, IUTAK, ITIME	700.313	3502.044	0	333551
XSIAF, VSIAF, IUTAK, ITIME	700.313	3507.370	0	333570
XSIAF, VSIAF, IUTAK, ITIME	700.490	3591.130	0	330200
XSIAF, VSIAF, IUTAK, ITIME	700.013	3592.020	0	330583
XSIAF, VSIAF, IUTAK, ITIME	000.000	3597.301	0	333613
XSIAF, VSIAF, IUTAK, ITIME	000.470	3227.200	0	330614
XSIAF, VSIAF, IUTAK, ITIME	000.077	3297.300	0	330705
XSIAF, VSIAF, IUTAK, ITIME	009.900	3590.214	0	333724
XSIAF, VSIAF, IUTAK, ITIME	310.000	3270.394	0	333754
XSIAF, VSIAF, IUTAK, ITIME	021.900	3227.231	0	333700
XSIAF, VSIAF, IUTAK, ITIME	000.000	3500.017	0	330604
XSIAF, VSIAF, IUTAK, ITIME	000.070	3227.300	0	333617

Figure 6.4. Detailed Computer Output (Sheet 16)

XSIAP,YSIAP, IUTAK,ITIME	450.047	3223.200	0	331500
XSIAP,YSIAP, IUTAK,ITIME	450.000	3224.900	0	330000
XSIAP,YSIAP, IUTAK,ITIME	451.212	3217.830	0	331004
XSIAP,YSIAP, IUTAK,ITIME	450.000	3217.041	0	331954
XSIAP,YSIAP, IUTAK,ITIME	450.000	3219.079	0	331900
XSIAP,YSIAP, IUTAK,ITIME	457.747	3220.770	0	331972
XSIAP,YSIAP, IUTAK,ITIME	415.310	3219.100	0	331901
XSIAP,YSIAP, IUTAK,ITIME	415.000	3210.900	0	331904
XSIAP,YSIAP, IUTAK,ITIME	421.722	3205.770	0	331021
XSIAP,YSIAP, IUTAK,ITIME	420.000	3200.000	0	331032
XSIAP,YSIAP, IUTAK,ITIME	437.550	3210.000	0	331074
XSIAP,YSIAP, IUTAK,ITIME	434.000	3207.210	0	331072
XSIAP,YSIAP, IUTAK,ITIME	440.000	3207.000	0	331111
XSIAP,YSIAP, IUTAK,ITIME	450.000	3204.720	0	331129
XSIAP,YSIAP, IUTAK,ITIME	422.879	3223.200	0	331155
XSIAP,YSIAP, IUTAK,ITIME	407.174	3249.270	0	331154
XSIAP,YSIAP, IUTAK,ITIME	407.710	3250.000	0	331101
XSIAP,YSIAP, IUTAK,ITIME	413.020	3258.100	0	331178
XSIAP,YSIAP, IUTAK,ITIME	400.501	3402.379	0	33201
XSIAP,YSIAP, IUTAK,ITIME	494.601	3401.500	0	33215
XSIAP,YSIAP, IUTAK,ITIME	1202.200	3455.010	0	33228
XSIAP,YSIAP, IUTAK,ITIME	1202.200	3455.000	0	33234
XSIAP,YSIAP, IUTAK,ITIME	1204.000	3450.000	0	33241
XSIAP,YSIAP, IUTAK,ITIME	1200.420	3442.070	0	33250
XSIAP,YSIAP, IUTAK,ITIME	1021.270	3442.121	0	33276
XSIAP,YSIAP, IUTAK,ITIME	1035.914	3426.212	0	33310
XSIAP,YSIAP, IUTAK,ITIME	1225.220	3429.870	0	33329
XSIAP,YSIAP, IUTAK,ITIME	1050.000	3420.000	0	33341
XSIAP,YSIAP, IUTAK,ITIME	1050.000	3403.200	0	33365
XSIAP,YSIAP, IUTAK,ITIME	1226.820	3402.000	0	33381
XSIAP,YSIAP, IUTAK,ITIME	1056.700	3399.020	0	33383
XSIAP,YSIAP, IUTAK,ITIME	1070.355	3371.860	0	33383
XSIAP,YSIAP, IUTAK,ITIME	1002.000	3361.000	0	33350
XSIAP,YSIAP, IUTAK,ITIME	1074.027	3353.100	0	33367
XSIAP,YSIAP, IUTAK,ITIME	1071.714	3350.000	0	33374
XSIAP,YSIAP, IUTAK,ITIME	1003.100	3345.000	0	33385
XSIAP,YSIAP, IUTAK,ITIME	1050.000	3343.100	0	33374
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	33361
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	33364
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34142
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34201
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34203
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34383
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34501
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	34562

Figure 6.4. Detailed Computer Output (Sheet 17)

XSIAP,YSIAP, IUTAP,ITIME	1042.001	3342.413	0	35000
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	35000
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	350654
XSIAP,YSIAP, IUTAP,ITIME	1042.001	3342.410	0	350002
XSIAP,YSIAP, IUTAP,ITIME	1042.001	3342.410	0	350712
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	350724
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	350740
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.413	0	350700
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.413	0	350797
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.413	0	350590
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	360001
XSIAP,YSIAP, IUTAK,ITIME	1042.001	3342.410	0	360091
XSIAP,YSIAP, IUTAK,ITIME	1020.034	3350.000	0	360169
XSIAP,YSIAP, IUTAK,ITIME	1020.030	3301.029	0	360291
XSIAP,YSIAP, IUTAK,ITIME	910.035	3304.200	0	360497
XSIAP,YSIAP, IUTAK,ITIME	910.030	3400.000	0	360650
XSIAP,YSIAP, IUTAK,ITIME	820.000	3407.000	0	360721
XSIAP,YSIAP, IUTAK,ITIME	820.000	3423.000	0	360909
XSIAP,YSIAP, IUTAK,ITIME	805.000	3400.000	0	361227
XSIAP,YSIAP, IUTAK,ITIME	800.000	3452.507	0	361257
XSIAP,YSIAP, IUTAK,ITIME	750.000	3475.215	0	361494
XSIAP,YSIAP, IUTAK,ITIME	690.000	3497.392	0	361096
XSIAP,YSIAP, IUTAK,ITIME	690.000	3500.000	0	361721
XSIAP,YSIAP, IUTAK,ITIME	620.000	3523.370	0	361965
XSIAP,YSIAP, IUTAK,ITIME	600.000	3543.247	0	362190
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.765	0	362245
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	362270
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	362577
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	362870
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	363179
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	363480
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	363601
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	363662
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	363903
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	364204
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	364265
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	364806
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	365167
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	365468
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	365769
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	366070
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	366371
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	366672
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	366973
XSIAP,YSIAP, IUTAK,ITIME	590.039	3547.760	0	367274

Figure 6.4, Detailed Computer Output (Sheet 19)

XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367006
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367129
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367176
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367200
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367220
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367251
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367266
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367275
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367375
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367501
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367661
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367751
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367790
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367840
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367887
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367926
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367968
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	367986
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	368587
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	368168
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	368789
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	370390
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	370801
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	370922
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	371523
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	372124
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	372725
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	373326
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	373927
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	374401
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	374932
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	376293
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	378001
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	378632
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	378833
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	381601
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	381722
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	383523
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	385201
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	385252
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	387033
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	388001
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	388832
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	390633
XSIAF,YSIAF,IUTAK,ITIME	590.039	3547.700	0	392401

Figure 6.4. Detailed Computer Output (Sheet 20)

XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372402
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372521
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372501
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372602
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372649
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372699
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372736
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372746
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372821
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372828
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372901
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372929
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372937
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372978
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	373010
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	372926
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	373029
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	373051
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	373032
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	401433
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	401251
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	403362
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	403923
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	404524
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	403165
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	405726
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	405327
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	405801
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	405532
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	407433
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	408034
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	408635
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	409236
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	409837
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	410438
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	410432
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	411033
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	411634
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	411935
XSIAP,YSIAP,LOIAP,ITIME	590.039	3547.700	412536

Figure 6.4, Detailed Computer Output (Sheet 21)

XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	412537
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	412030
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	413139
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	413440
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	413741
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	414001
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	414632
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	414333
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	414034
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	414935
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	415236
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	415537
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	415838
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	416031
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	417002
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	417403
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	421201
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	421632
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422000
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422117
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422157
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422178
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422245
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422249
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422334
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422341
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422352
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422415
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422454
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422504
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422520
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422521
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422592
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422609
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422690
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	422921
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	423705
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	423678
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	423915
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	423955
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	423990
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	424043
XSIAP,YSIAF, IUTAF,ITIME	590.039	3547.700	424093

Figure 6.4, Detailed Computer Output (Sheet 22)

XSIAP,YSIAP, IUTAK,ITIME	597.034	3547.100	424100
XSIAP,YSIAP, IUTAK,ITIME	590.034	3547.100	424200
XSIAP,YSIAP, IUTAK,ITIME	241.255	3543.034	424200
XSIAP,YSIAP, IUTAK,ITIME	570.530	3546.034	424214
XSIAP,YSIAP, IUTAK,ITIME	593.034	3547.140	424220
XSIAP,YSIAP, IUTAK,ITIME	592.030	3547.034	424224
XSIAP,YSIAP, IUTAK,ITIME	595.122	3550.700	424225
XSIAP,YSIAP, IUTAK,ITIME	597.759	3551.293	424229
XSIAP,YSIAP, IUTAK,ITIME	594.293	3552.290	424272
XSIAP,YSIAP, IUTAK,ITIME	522.775	3549.134	424274
XSIAP,YSIAP, IUTAK,ITIME	595.260	3554.034	424350
XSIAP,YSIAP, IUTAK,ITIME	592.977	3552.322	424314
XSIAP,YSIAP, IUTAK,ITIME	593.127	3559.323	424364
XSIAP,YSIAP, IUTAK,ITIME	593.034	3559.030	424375
XSIAP,YSIAP, IUTAK,ITIME	593.744	3560.920	424350
XSIAP,YSIAP, IUTAK,ITIME	595.347	3562.071	424422
XSIAP,YSIAP, IUTAK,ITIME	570.422	3565.034	424650
XSIAP,YSIAP, IUTAK,ITIME	593.010	3569.000	424909
XSIAP,YSIAP, IUTAK,ITIME	597.100	3567.370	424461
XSIAP,YSIAP, IUTAK,ITIME	594.938	3565.042	424503
XSIAP,YSIAP, IUTAK,ITIME	593.313	3569.713	424505
XSIAP,YSIAP, IUTAK,ITIME	729.030	3507.040	424914
XSIAP,YSIAP, IUTAK,ITIME	718.324	3571.332	424543
XSIAP,YSIAP, IUTAK,ITIME	723.341	3574.077	424542
XSIAP,YSIAP, IUTAK,ITIME	744.209	3570.420	424046
XSIAP,YSIAP, IUTAK,ITIME	750.030	3579.037	424663
XSIAP,YSIAP, IUTAK,ITIME	766.212	3582.344	424709
XSIAP,YSIAP, IUTAK,ITIME	760.315	3582.034	424721
XSIAP,YSIAP, IUTAK,ITIME	760.315	3582.034	424740
XSIAP,YSIAP, IUTAK,ITIME	760.215	3582.044	424811
XSIAP,YSIAP, IUTAK,ITIME	760.313	3582.344	424876
XSIAP,YSIAP, IUTAK,ITIME	760.313	3582.344	424897
XSIAP,YSIAP, IUTAK,ITIME	766.213	3582.344	424921
XSIAP,YSIAP, IUTAK,ITIME	760.313	3582.344	424935
XSIAP,YSIAP, IUTAK,ITIME	760.313	3582.034	424946
XSIAP,YSIAP, IUTAK,ITIME	756.313	3582.344	424964
XSIAP,YSIAP, IUTAK,ITIME	760.313	3582.034	424981
XSIAP,YSIAP, IUTAK,ITIME	763.777	3583.030	424980
XSIAP,YSIAP, IUTAK,ITIME	737.912	3592.132	425021
XSIAP,YSIAP, IUTAK,ITIME	533.030	3597.031	425043
XSIAP,YSIAP, IUTAK,ITIME	533.030	3597.030	425044
XSIAP,YSIAP, IUTAK,ITIME	533.077	3597.030	425105
XSIAP,YSIAP, IUTAK,ITIME	539.938	3591.914	425184
XSIAP,YSIAP, IUTAK,ITIME	515.030	3570.034	425214
XSIAP,YSIAP, IUTAK,ITIME	524.934	3557.031	425268

Figure 6.4, Detailed Computer Output (Sheet 23)

1000-1000-1000
7 7 7

KSIAF,YSIAF,LUFAK,TIME	3550.617	031.025	3550.617	031.025	C	423264
KSIAF,YSIAF,LUFAK,TIME	3550.630	334.074	3550.630	334.074	C	423271
KSIAF,YSIAF,LUFAK,TIME	3550.650	349.247	3550.650	349.247	C	423280
KSIAF,YSIAF,LUFAK,TIME	3549.722	059.033	3549.722	059.033	C	423320
KSIAF,YSIAF,LUFAK,TIME	3517.030	057.013	3517.030	057.013	C	423344
KSIAF,YSIAF,LUFAK,TIME	3519.041	425.003	3519.041	425.003	C	425414
KSIAF,YSIAF,LUFAK,TIME	3513.074	425.932	3513.074	425.932	C	425416
KSIAF,YSIAF,LUFAK,TIME	3525.773	427.747	3525.773	427.747	C	425432
KSIAF,YSIAF,LUFAK,TIME	3519.125	913.012	3519.125	913.012	C	425449
KSIAF,YSIAF,LUFAK,TIME	3510.000	913.007	3510.000	913.007	C	425464
KSIAF,YSIAF,LUFAK,TIME	3503.773	421.743	3503.773	421.743	C	425461
KSIAF,YSIAF,LUFAK,TIME	3500.000	425.000	3500.000	425.000	C	425492
KSIAF,YSIAF,LUFAK,TIME	3478.049	437.031	3478.049	437.031	C	425534
KSIAF,YSIAF,LUFAK,TIME	3407.013	434.075	3407.013	434.075	C	425552
KSIAF,YSIAF,LUFAK,TIME	3457.027	340.027	3457.027	340.027	C	425571
KSIAF,YSIAF,LUFAK,TIME	3424.722	423.020	3424.722	423.020	C	425585
KSIAF,YSIAF,LUFAK,TIME	3450.000	424.070	3450.000	424.070	C	425619
KSIAF,YSIAF,LUFAK,TIME	3490.179	407.179	3490.179	407.179	C	425621
KSIAF,YSIAF,LUFAK,TIME	3450.000	423.000	3450.000	423.000	C	425638
KSIAF,YSIAF,LUFAK,TIME	3402.039	420.039	3402.039	420.039	C	425692
KSIAF,YSIAF,LUFAK,TIME	3402.039	400.031	3402.039	400.031	C	425701
KSIAF,YSIAF,LUFAK,TIME	3402.039	900.031	3402.039	900.031	C	425815
KSIAF,YSIAF,LUFAK,TIME	3402.039	420.039	3402.039	420.039	C	425826
KSIAF,YSIAF,LUFAK,TIME	3402.039	480.031	3402.039	480.031	C	425861
KSIAF,YSIAF,LUFAK,TIME	3402.039	400.031	3402.039	400.031	C	425880
KSIAF,YSIAF,LUFAK,TIME	3402.039	900.031	3402.039	900.031	C	420541
KSIAF,YSIAF,LUFAK,TIME	3402.039	400.031	3402.039	400.031	C	420601
KSIAF,YSIAF,LUFAK,TIME	3401.000	1007.000	3401.000	1007.000	C	420604
KSIAF,YSIAF,LUFAK,TIME	3423.039	1002.029	3423.039	1002.029	C	420679
KSIAF,YSIAF,LUFAK,TIME	3423.039	1004.007	3423.039	1004.007	C	420694
KSIAF,YSIAF,LUFAK,TIME	3422.073	1000.420	3422.073	1000.420	C	420713
KSIAF,YSIAF,LUFAK,TIME	3444.029	1010.007	3444.029	1010.007	C	420724
KSIAF,YSIAF,LUFAK,TIME	3440.021	1021.023	3440.021	1021.023	C	425770
KSIAF,YSIAF,LUFAK,TIME	3432.079	1020.030	3432.079	1020.030	C	425814
KSIAF,YSIAF,LUFAK,TIME	3423.012	1029.714	3423.012	1029.714	C	420850
KSIAF,YSIAF,LUFAK,TIME	3420.070	1045.420	3420.070	1045.420	C	425880
KSIAF,YSIAF,LUFAK,TIME	3420.000	1050.000	3420.000	1050.000	C	420919
KSIAF,YSIAF,LUFAK,TIME	3420.000	1050.000	3420.000	1050.000	C	420983
KSIAF,YSIAF,LUFAK,TIME	3397.023	1050.000	3397.023	1050.000	C	427054
KSIAF,YSIAF,LUFAK,TIME	3374.044	1070.000	3374.044	1070.000	C	427101
KSIAF,YSIAF,LUFAK,TIME	3301.000	1059.000	3301.000	1059.000	C	427231
KSIAF,YSIAF,LUFAK,TIME	3223.102	1070.000	3223.102	1070.000	C	427260

Figure 6.4, Detailed Computer Output (Sheet 24)

XSIAF,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453448
XSIAF,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453448
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453529
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453576
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453600
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453601
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453722
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	453981
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	454562
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	455163
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	455764
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	455985
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	456201
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	456322
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	457923
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	458224
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	459125
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	459726
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	460327
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	460801
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	460922
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	462633
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	463401
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	464632
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	465233
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	468001
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	468032
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	468123
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	468601
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	468922
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	469223
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	469701
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	469822
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	469923
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	469985
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	470001
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	470322
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	470833
XSLAE,YSIAF,IUTAK,ITIME	883,203	3907,076	0	470901

Figure 6.4, Detailed Computer Output (Sheet 27)

XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	495636
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	498937
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499236
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499534
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499833
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499836
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499837
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499838
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499839
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	499840
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	500161
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	500401
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	500581
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	500794
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	500903
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501020
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501236
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501357
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501363
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501608
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501836
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501927
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501957
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	501975
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502198
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502321
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502352
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502442
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502514
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502754
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502801
XSIAP,YSIAP,UTAK,ITIME	883.203	3907.078	502900

Figure 6.4, Detailed Computer Output (Sheet 28)

Code	Label	Value	Value	Value
XSIAP	YsIAP	670.335	403.443	22201
XSIAP	YsIAP	070.550	401.442	22202
XSIAP	YsIAP	473.472	404.372	22203
XSIAP	YsIAP	673.155	404.932	22204
XSIAP	YsIAP	072.520	404.231	22205
XSIAP	YsIAP	072.130	402.222	22206
XSIAP	YsIAP	371.574	603.905	22207
XSIAP	YsIAP	073.124	400.259	22011
XSIAP	YsIAP	073.122	404.272	22019
XSIAP	YsIAP	073.711	473.131	22220
XSIAP	YsIAP	307.222	473.733	22221
XSIAP	YsIAP	227.112	473.247	22224
XSIAP	YsIAP	069.131	473.692	22227
XSIAP	YsIAP	209.142	472.703	22307
XSIAP	YsIAP	099.141	473.713	22308
XSIAP	YsIAP	095.131	473.713	22309
XSIAP	YsIAP	300.174	473.702	22320
XSIAP	YsIAP	205.141	473.713	22321
XSIAP	YsIAP	069.141	473.703	22322
XSIAP	YsIAP	300.141	473.703	22323
XSIAP	YsIAP	300.141	473.703	22324
XSIAP	YsIAP	065.141	473.703	22325
XSIAP	YsIAP	309.141	473.703	22326
XSIAP	YsIAP	069.141	473.703	22327
XSIAP	YsIAP	069.141	473.703	22328
XSIAP	YsIAP	069.141	473.703	22329
XSIAP	YsIAP	069.141	473.703	22330
XSIAP	YsIAP	069.141	473.703	22331
XSIAP	YsIAP	069.141	473.703	22332
XSIAP	YsIAP	069.141	473.703	22333
XSIAP	YsIAP	069.141	473.703	22334
XSIAP	YsIAP	069.141	473.703	22335
XSIAP	YsIAP	069.141	473.703	22336
XSIAP	YsIAP	069.141	473.703	22337
XSIAP	YsIAP	069.141	473.703	22338
XSIAP	YsIAP	069.141	473.703	22339
XSIAP	YsIAP	069.141	473.703	22340
XSIAP	YsIAP	069.141	473.703	22341
XSIAP	YsIAP	069.141	473.703	22342
XSIAP	YsIAP	069.141	473.703	22343
XSIAP	YsIAP	069.141	473.703	22344
XSIAP	YsIAP	069.141	473.703	22345
XSIAP	YsIAP	069.141	473.703	22346
XSIAP	YsIAP	069.141	473.703	22347
XSIAP	YsIAP	069.141	473.703	22348
XSIAP	YsIAP	069.141	473.703	22349
XSIAP	YsIAP	069.141	473.703	22350
XSIAP	YsIAP	069.141	473.703	22351
XSIAP	YsIAP	069.141	473.703	22352
XSIAP	YsIAP	069.141	473.703	22353
XSIAP	YsIAP	069.141	473.703	22354
XSIAP	YsIAP	069.141	473.703	22355

Figure 6.4, Detailed Computer Output (Sheet 30)

XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	513337
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	502030
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503529
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	502247
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503541
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503051
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503922
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503223
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	507254
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	517025
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	500126
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503427
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503728
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503401
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503432
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	502233
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503031
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503536
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	507051
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	507232
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503433
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503431
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	503432
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	610233
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	610233
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	610232
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	613033
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	615631
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	615032
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	617433
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	619231
XSIAF,YSIAF,UTAF,ITIME	1109.307	5454.303	0	519232

Figure 6.4, Detailed Computer Output (Sheet 33)

KSIAF, YSLAF, LULAF, LULAF, LULAF	023711	023711	023711
KSIAF, YSLAF, LULAF, LULAF, LULAF	023712	023712	023712
KSIAF, YSLAF, LULAF, LULAF, LULAF	023713	023713	023713
KSIAF, YSLAF, LULAF, LULAF, LULAF	023714	023714	023714
KSIAF, YSLAF, LULAF, LULAF, LULAF	023715	023715	023715
KSIAF, YSLAF, LULAF, LULAF, LULAF	023716	023716	023716
KSIAF, YSLAF, LULAF, LULAF, LULAF	023717	023717	023717
KSIAF, YSLAF, LULAF, LULAF, LULAF	023718	023718	023718
KSIAF, YSLAF, LULAF, LULAF, LULAF	023719	023719	023719
KSIAF, YSLAF, LULAF, LULAF, LULAF	023720	023720	023720
KSIAF, YSLAF, LULAF, LULAF, LULAF	023721	023721	023721
KSIAF, YSLAF, LULAF, LULAF, LULAF	023722	023722	023722
KSIAF, YSLAF, LULAF, LULAF, LULAF	023723	023723	023723
KSIAF, YSLAF, LULAF, LULAF, LULAF	023724	023724	023724
KSIAF, YSLAF, LULAF, LULAF, LULAF	023725	023725	023725
KSIAF, YSLAF, LULAF, LULAF, LULAF	023726	023726	023726
KSIAF, YSLAF, LULAF, LULAF, LULAF	023727	023727	023727
KSIAF, YSLAF, LULAF, LULAF, LULAF	023728	023728	023728
KSIAF, YSLAF, LULAF, LULAF, LULAF	023729	023729	023729
KSIAF, YSLAF, LULAF, LULAF, LULAF	023730	023730	023730
KSIAF, YSLAF, LULAF, LULAF, LULAF	023731	023731	023731
KSIAF, YSLAF, LULAF, LULAF, LULAF	023732	023732	023732
KSIAF, YSLAF, LULAF, LULAF, LULAF	023733	023733	023733
KSIAF, YSLAF, LULAF, LULAF, LULAF	023734	023734	023734
KSIAF, YSLAF, LULAF, LULAF, LULAF	023735	023735	023735
KSIAF, YSLAF, LULAF, LULAF, LULAF	023736	023736	023736
KSIAF, YSLAF, LULAF, LULAF, LULAF	023737	023737	023737
KSIAF, YSLAF, LULAF, LULAF, LULAF	023738	023738	023738
KSIAF, YSLAF, LULAF, LULAF, LULAF	023739	023739	023739
KSIAF, YSLAF, LULAF, LULAF, LULAF	023740	023740	023740
KSIAF, YSLAF, LULAF, LULAF, LULAF	023741	023741	023741
KSIAF, YSLAF, LULAF, LULAF, LULAF	023742	023742	023742
KSIAF, YSLAF, LULAF, LULAF, LULAF	023743	023743	023743
KSIAF, YSLAF, LULAF, LULAF, LULAF	023744	023744	023744
KSIAF, YSLAF, LULAF, LULAF, LULAF	023745	023745	023745
KSIAF, YSLAF, LULAF, LULAF, LULAF	023746	023746	023746
KSIAF, YSLAF, LULAF, LULAF, LULAF	023747	023747	023747
KSIAF, YSLAF, LULAF, LULAF, LULAF	023748	023748	023748
KSIAF, YSLAF, LULAF, LULAF, LULAF	023749	023749	023749
KSIAF, YSLAF, LULAF, LULAF, LULAF	023750	023750	023750

Figure 6.4, Detailed Computer Output (Sheet 35)

Figure 6.5. SLAF SURVEILLANCE STATISTICS (PAGE 1)
 HUNTER LIGHTS SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY SLAF

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF DETECTIONS	0	0	0	5	5	5
DETECTION SUCCESS RATIO	0.0	0.0	0.0	1.000	1.000	1.000
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	172.910	152.475	65.213
STANDARD DEVIATION	0.0	0.0	0.0	0.321	2.370	0.767
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	020517	022237	022206
STANDARD DEVIATION	00000	00000	00000	000000	000000	000000
DETECTION CUPS						
AURAL	5	5	0	0	5	0
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY SLAF

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF IDENTIFICATIONS	0	0	0	0	3	3
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.600	1.000
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	152.079	65.213
STANDARD DEVIATION	0.0	0.0	0.0	0.0	2.195	0.007
IDENTIFICATION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	022237	022206
STANDARD DEVIATION	00000	00000	00000	00000	000000	000000

Figure 4.5. STAF Surveillance Statistics (Page 2)
 Hunter Legend Scenario 1
 6 Replications

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	7	8	9	10	11	12
NUMBER OF DETECTIONS	0	0	0	5	0	1
DETECTION SUCCESS RATIO	0.0	0.0	0.0	1.000	0.0	0.250
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	515.212	0.0	1030.190
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	00000	00000	00000	00000	00000	030904
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000
DETECTION CUES	5	0	0	0	5	0
AURAL SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	7	8	9	10	11	12
NUMBER OF IDENTIFICATIONS	0	0	0	5	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	1.000	0.0	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	515.212	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	00000	00000	00000	00000	00000	000000
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000

00000-0000-00-00

Figure 6.5. SIAF SURVEILLANCE STATISTICS (PAGE 31)
 HUNTER LIGHTY SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF DETECTIONS	0	0	3	0	0	4
DETECTION SUCCESS RATIO	0.0	0.0	0.600	0.0	0.0	0.800
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	1039.449	0.0	0.0	41.912
STANDARD DEVIATION	0.0	0.0	0.629	0.0	0.0	0.923
DETECTION TIME (DAYS,HRS,MINS)						
MEAN	00000	00000	031721	00000	00000	032203
STANDARD DEVIATION	00000	00000	000023	00000	00000	000000
DETECTION CUES	0	5	0	0	5	0
AURAL						
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	4
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	1.000
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	41.912
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.923
IDENTIFICATION TIME (DAYS,HRS,MINS)						
MEAN	00000	00000	00000	00000	00000	032203
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000

1000-600-10-0

Figure 10. Visual Detection Statistics (Case 4)
 Number of Targets 1
 4 Replications

UNBIASED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF DETECTIONS	0	3	0	1	3	1
DETECTION SUCCESS RATIO	0.0	0.670	0.0	0.200	0.600	0.200
DETECTION RANGE (METERS)						
MEAN	0.0	35.446	0.0	31.159	44.014	501.217
STANDARD DEVIATION	0.0	11.659	0.0	0.0	3.151	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	040054	00000	040117	040356	040408
STANDARD DEVIATION	00000	000000	00000	000000	000000	000000
DETECTION CUES						
AURAL	1	2	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF IDENTIFICATIONS	0	3	0	1	3	0
IDENTIFICATION SUCCESS RATIO	0.0	1.000	0.0	1.000	1.000	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	35.665	0.0	31.159	44.018	0.0
STANDARD DEVIATION	0.0	11.659	0.0	0.0	3.151	0.0
IDENTIFICATION TIME (DAYS, HRS, MINS)						
MEAN	00000	040054	00000	040117	040306	000000
STANDARD DEVIATION	00000	000000	00000	000000	000000	000000

Figure 6.5. STAF SURVEILLANCE STATISTICS (PAGE 5)
 HUNTER TARGET SCENARIO
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	25	26	27	28	29	30
NUMBER OF DETECTIONS	C	1	0	5	1	0
DETECTION SUCCESS RATIO	0.0	0.200	0.00	1.000	0.200	0.00
DETECTION RANGE (METERS)						
MEAN	0.0	153.085	0.0	198.758	45.842	0.0
STANDARD DEVIATION	0.0	0.0	0.0	190.660	0.0	0.0
DETECTION TIME (DAYS.HRS.MINS)						
MEAN	00000	041334	00000	042213	042204	000000
STANDARD DEVIATION	00000	000000	000000	000011	000000	000000
DETECTION CUES						
AURAL	C	0	C	4	C	0
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	25	26	27	28	29	30
NUMBER OF IDENTIFICATIONS	C	0	0	3	1	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.00	0.600	1.000	0.00
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	47.808	45.842	0.0
STANDARD DEVIATION	0.0	0.0	0.0	3.313	0.0	0.0
IDENTIFICATION TIME (DAYS.HRS.MINS)						
MEAN	00000	000000	000000	042219	042204	000000
STANDARD DEVIATION	00000	000000	000000	000007	000000	000000

16005-6000-10-00

FIGURE 1. UNASSISTED VISUAL DETECTION STATISTICS (PAGE 6)
 JUNIER LIGHT SCENARIO I
 5 REPLICATIONS

UNASSISTED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	31	32	33	34	35	36
NUMBER OF DETECTIONS	5	0	3	5	5	3
DETECTION SUCCESS RATIO	1.000	0.0	0.600	1.000	1.000	0.600
DETECTION RANGE (METERS)						
MEAN	31.555	0.0	31.159	39.950	216.416	259.432
STANDARD DEVIATION	9.772	0.0	5.0	1.813	3.400	55.929
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	050054	000000	050110	050306	050600	052132
STANDARD DEVIATION	000000	000000	000000	000000	000000	000001
DETECTION CUES						
AURAL	4	0	0	0	5	5
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	31	32	33	34	35	36
NUMBER OF IDENTIFICATIONS	5	0	3	5	2	0
IDENTIFICATION SUCCESS RATIO	1.000	0.0	1.000	1.000	0.400	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	31.555	0.0	31.159	39.950	215.522	200
STANDARD DEVIATION	9.772	0.0	5.0	1.813	3.765	0.0
IDENTIFICATION TIME (DAYS, HRS, MINS)						
MEAN	050054	000000	050110	050306	050600	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

16905-6000-20-00

Figure 6.5. STAFF SURVEILLANCE STATISTICS (PAGE 7)
 HUNTER LIGHTLY SCENARIO
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY STAFF

TARGET NUMBER	37	38	39	40	41	42
NUMBER OF DETECTIONS	0	6	0	0	0	5
DETECTION SUCCESS RATIO	0.0	0.667	0.0	0.0	0.0	1.000
DETECTION RANGE (METERS)						
MEAN	0.0	136.657	0.0	0.0	0.0	258.208
STANDARD DEVIATION	0.0	0.147	0.0	0.0	0.0	0.999
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	00000	051355	000000	000000	000000	060215
STANDARD DEVIATION	00000	000001	000000	000000	000000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY STAFF

TARGET NUMBER	37	38	39	40	41	42
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	1.000
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	258.208
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.999
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	00000	000000	000000	000000	000000	060215
STANDARD DEVIATION	00000	000000	000000	000000	000000	000000

16885-6888-10-00
 7 8

Figure 400, SIAF Surveillance Statistics (Page 4)
 Hunter Liberty Scenario 1
 5 Replications

UNAIDED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF DETECTIONS	5	5	5	5	5	5
DETECTION SUCCESS RATIO	1.000	1.000	1.000	1.000	1.000	1.000
DETECTION RANGE (METERS)						
MEAN	256.214	1330.246	334.893	334.967	334.634	335.173
STANDARD DEVIATION	1.374	0.0	0.767	0.752	0.782	0.824
DETECTION TIME (DAYS,MRS,MIPS)						
MEAN	060845	051500	061643	062113	070013	070555
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUPS	5	5	5	5	5	5
AURAL						
SENSOR						

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF IDENTIFICATIONS	5	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	1.000	0.000	0.000	0.000	0.000	0.000
IDENTIFICATION RANGE (METERS)						
MEAN	256.214	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	1.374	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS,MRS,MIPS)						
MEAN	060845	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

16905-6008-20-00
 Page 4 of 8

Figure 6.5. SIAF SURVEILLANCE STATISTICS (PAGE 9)
 MONTPELIER SCENARIO 1
 5 REPLICATIONS

UNASSISTED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	49	50	51
NUMBER OF DETECTIONS	5	5	3
DETECTION SUCCESS RATIO	1.000	1.000	0.600
DETECTION RANGE (METERS)			
MEAN	119.722	736.549	736.549
STANDARD DEVIATION	3.669	3.347	0.017
DETECTION TIME (DAYS.HRS.MINS)			
MEAN	070640	070643	070643
STANDARD DEVIATION	000000	000000	000000
DETECTION CUES			
AURAL	0	0	0
SENSOR			

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	49	50	51
NUMBER OF IDENTIFICATIONS	5	3	0
IDENTIFICATION SUCCESS RATIO	1.000	0.000	0.000
IDENTIFICATION RANGE (METERS)			
MEAN	119.722	3.000	0.000
STANDARD DEVIATION	3.669	0.000	0.000
IDENTIFICATION TIME (DAYS.HRS.MINS)			
MEAN	070640	000000	000000
STANDARD DEVIATION	000000	000000	000000

FIGURE 10. AIR-TO-AIR DETECTION STATISTICS (PAGE 10)
 MONITOR LIGHT SCENARIO 1
 5 REPLICATIONS

AIR-TO-AIR DETECTION STATISTICS OF THE TARGETS BY SIATF

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF DETECTIONS	5	5	0	0	5	0
DETECTION SUCCESS RATIO	1.000	1.000	0.000	0.000	1.000	0.000
DETECTION RANGE (METERS)						
MEAN	344.191	240.831	0.000	0.000	311.824	0.000
STANDARD DEVIATION	0.000	0.000	0.000	0.000	0.000	0.000
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	012157	012200	000000	000000	022139	000700
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	1	2	3	4	5	6
TARGET LOCATION CEP (METERS)						
MEAN	0.000	0.000	0.000	24.861	21.923	9.376
STANDARD DEVIATION	0.000	0.000	0.000	0.046	0.337	0.010

FIGURE 6-5. SIA - SURVEILLANCE STATISTICS (PART 1)
 NUMBER OF TARGETS DETECTED
 4 REPERCUSSIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY STAFF

TARGET NUMBER	7	8	9	10	11	12
NUMBER OF DETECTIONS	5	5	6	9	5	0
DETECTION SUCCESS RATIO	1.000	1.000	0.667	1.000	1.000	0.000
DETECTION RANGE (METERS)						
MEAN	423.070	3.000	0.000	0.000	392.990	0.000
STANDARD DEVIATION	3.000	0.000	0.000	0.000	0.000	0.000
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	030221	030000	000000	000000	030851	000000
STANDARD DEVIATION	030000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	7	8	9	10	11	12
TARGET LOCATION CEP (METERS)						
MEAN	3.000	3.000	0.000	74.077	0.000	149.272
STANDARD DEVIATION	0.000	0.000	0.000	0.000	0.000	0.000

16905-6008-RO-00
 AIRCRAFT TARGET SUBSYSTEM
 PUBLICATION

AIRAL DETECTION SUBSYSTEM DETECTION STATISTICS BY DATE

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF DETECTIONS	0	5	0	0	5	0
DETECTION SUCCESS RATE	0.0	1.000	0.0	0.0	1.000	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	382.900	0.0	0.0	330.202	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	000000	031651	000000	000000	032120	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	13	14	15	16	17	18
TARGET LOCATION CEP (METERS)						
MEAN	0.0	0.0	149.452	0.0	0.0	6.026
STANDARD DEVIATION	0.0	0.0	0.090	0.0	0.0	1.283

1. SUMMARY OF SURVEILLANCE STATISTICS (PAGE 12)
 MONTHLY SCENARIOS
 5 REPLICATIONS

ANNUAL DETECTION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF DETECTIONS	0	2	0	0	0	0
DETECTION SUCCESS RATIO	0.0	0.400	0.0	0.0	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	27.900	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS:HRS:MIN)						
MEAN	000000	040054	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	19	20	21	22	23	24
TARGET LOCATION CEP (METERS)						
MEAN	0.0	5.095	0.0	4.487	6.329	72.065
STANDARD DEVIATION	0.0	1.533	0.0	0.0	0.453	0.0

PERFORMANCE STATISTICS (PAGE 11)
 TARGET SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	25	26	27	28	29	30
NUMBER OF DETECTIONS	0	0	0	4	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.800	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	446.869	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.559	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	042218	00000	00000
STANDARD DEVIATION	00000	00000	00000	00000	00000	00000

TARGET LOCATION STATISTICS

TARGET NUMBER	25	26	27	28	29	30
TARGET LOCATION CEP (METERS)						
MEAN	0.0	22.011	0.0	29.577	6.591	0.0
STANDARD DEVIATION	0.0	0.0	0.0	27.384	0.0	0.0

Figure 6.5, SIAF SURVEILLANCE STATISTICS (PAGE 15)
 HUNTER LIGGITT SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	31	32	33	34	35	36
NUMBER OF DETECTIONS	4	0	0	0	5	5
DETECTION SUCCESS RATIO	0.800	0.0	0.0	0.0	1.000	1.000
DETECTION RANGE (METERS)						
MEAN	27.909	0.0	0.0	0.0	301.201	263.412
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS,HRS,MINS)						
MEAN	050054	000000	000000	000000	050600	052131
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	31	32	33	34	35	36
TARGET LOCATION CEP (METERS)						
MEAN	4.537	0.0	4.480	5.744	31.116	36.430
STANDARD DEVIATION	1.261	0.0	0.0	0.261	0.489	0.041

FIGURE 6-94. SURVEILLANCE STATISTICS (PAGE 16)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	37	39	39	40	41	42
NUMBER OF DETECTIONS	0	0	0	0	0	5
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	1.000
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	369.330
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	34.196
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	00000	060215
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	37	38	39	40	41	42
TARGET LOCATION CEP (METERS)						
MEAN	0.0	19.649	0.0	0.0	0.0	37.125
STANDARD DEVIATION	0.0	0.021	0.0	0.0	0.0	0.144

Figure 6.5. SIAF SURVEILLANCE STATISTICS (PAGE 17)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF DETECTIONS	5	0	5	5	5	5
DETECTION SUCCESS RATIO	1.000	0.0	1.000	1.000	1.000	1.000
DETECTION RANGE (METERS)						
MEAN	374.015	0.0	394.064	466.798	470.139	410.854
STANDARD DEVIATION	22.622	0.0	8.192	41.378	34.697	56.359
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	060845	000000	061643	062112	070012	070554
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

TARGET LOCATION STATISTICS

TARGET NUMBER	43	44	45	46	47	48
TARGET LOCATION CEP (METERS)						
MEAN	36.810	192.413	48.151	48.161	48.114	48.191
STANDARD DEVIATION	0.198	0.0	0.110	0.115	0.112	0.110

Figure 6.5. STAF SURVEILLANCE STATISTICS (PAGE 18)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

AIRAL DETECTION STATISTICS OF THE TARGETS BY STAF

TARGET NUMBER	49	50	51
NUMBER OF DETECTIONS	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0
DETECTION RANGE (METERS)			
MEAN	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)			
MEAN	00000	00000	00000
STANDARD DEVIATION	00000	00000	00000

TARGET LOCATION STATISTICS

TARGET NUMBER	49	50	51
TARGET LOCATION CEP (METERS)			
MEAN	17.214	105.901	105.904
STANDARD DEVIATION	0.096	0.007	0.072

Figure 6.5, TARGET SURVEILLANCE STATISTICS (PAGE 19)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF DETECTIONS	0	0	0	1	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.200	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	172.470	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	000000	000000	000000	020517	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	000000	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

Figure 3.3, TARGET SURVEILLANCE STATISTICS (PAGE 20)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	7	8	9	10	11	12
NUMBER OF DETECTIONS	0	0	0	0	0	3
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.600
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	1036.898
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	2.447
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	00000	030904
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	7	8	9	10	11	12
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	00000	000000
STANDARD DEVIATION	00000	00000	00000	00000	00000	000000

PERFORMANCE EVALUATION STATISTICS (PAGE 21)
 MURPHY LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF DETECTIONS	0	0	2	0	0	3
DETECTION SUCCESS RATIO	0.0	0.0	0.400	0.0	0.0	0.600
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	1037.702	0.0	0.0	38.502
STANDARD DEVIATION	0.0	0.0	1.049	0.0	0.0	8.201
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	00000	00000	031704	00000	00000	032203
STANDARD DEVIATION	00000	00000	00000	00000	00000	00000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	3
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	1.000
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	38.502
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	8.201
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	00000	00000	00000	00000	00000	032203
STANDARD DEVIATION	00000	00000	00000	00000	00000	00000

FIGURE 6-5. TABLE 7. SURVEILLANCE STATISTICS (PAGE 22)
 HUNTER TARGET SCENARIO 1
 5 REPLICATIONS

UNALIGNED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF DETECTIONS	0	3	0	0	2	0
DETECTION SUCCESS RATIO	0.0	0.600	0.0	0.0	0.400	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	40.622	0.0	0.0	38.502	0.0
STANDARD DEVIATION	0.0	9.309	0.0	0.0	0.963	0.0
DETECTION TIME (DAYS,HRS.,MINS)						
MEAN	000000	040054	000000	000000	040306	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF IDENTIFICATIONS	0	4	0	0	2	0
IDENTIFICATION SUCCESS RATIO	0.0	1.333	0.0	0.0	1.000	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	30.466	0.0	0.0	38.502	0.0
STANDARD DEVIATION	0.0	19.349	0.0	0.0	0.963	0.0
IDENTIFICATION TIME (DAYS,HRS.,MINS)						
MEAN	000000	030040	000000	000000	040306	000000
STANDARD DEVIATION	000000	011757	000000	000000	000000	000000

EXPERIMENTAL TARGET SURVEILLANCE STATISTICS (DATE 23)
 MOUNTED TARGET SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	25	26	27	28	29	30
NUMBER OF DETECTIONS	0	4	0	0	4	0
DETECTION SUCCESS RATIO	0.0	0.909	0.0	0.0	0.800	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	172.107	0.0	0.0	43.600	0.0
STANDARD DEVIATION	0.0	85.050	0.0	0.0	6.904	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	000000	041333	000000	000000	042205	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	25	26	27	28	29	30
NUMBER OF IDENTIFICATIONS	0	0	0	0	4	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	1.000	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	43.600	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	6.904	0.0
IDENTIFICATION TIME (DAYS, HRS, MINS)						
MEAN	000000	000000	000000	000000	042205	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

Figure 6.5. TARGET SURVEILLANCE STATISTICS (PAGE 24)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	31	32	33	34	35	36
NUMBER OF DETECTIONS	1	0	0	0	0	0
DETECTION SUCCESS RATIO	0.200	0.00	0.00	0.00	0.00	0.00
DETECTION RANGE (METERS)						
MEAN	25.087	0.00	0.00	0.00	0.00	0.00
STANDARD DEVIATION	0.00	0.00	0.00	0.00	0.00	0.00
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	050054	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION GUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	31	32	33	34	35	36
NUMBER OF IDENTIFICATIONS	1	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	1.000	0.00	0.00	0.00	0.00	0.00
IDENTIFICATION RANGE (METERS)						
MEAN	25.087	0.00	0.00	0.00	0.00	0.00
STANDARD DEVIATION	0.00	0.00	0.00	0.00	0.00	0.00
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	050054	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

Figure 6.5. TARGET SURVEILLANCE STATISTICS (PAGE 25)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	37	38	39	40	41	42
NUMBER OF DETECTIONS	0	0	0	0	0	1
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.200
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	259.003
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	000000	000000	000000	000000	000000	060215
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUES	0	0	0	0	0	0
AURAL						
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	37	38	39	40	41	42
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	000000	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

Figure 6.5, TARGET SURVEILLANCE STATISTICS (PAGE 26)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF DETECTIONS	3	0	0	0	0	1
DETECTION SUCCESS RATIO	0.600	0.0	0.0	0.0	0.0	0.200
DETECTION RANGE (METERS)						
MEAN	255.577	0.0	0.0	0.0	0.0	335.355
STANDARD DEVIATION	1.525	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS,HRS,MIN)						
MEAN	060845	000000	000000	000000	000000	070555
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000
DETECTION CUES						
AURAL	0	0	0	0	0	0
SENSOR						

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF IDENTIFICATIONS	0	0	0	0	0	0
IDENTIFICATION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
IDENTIFICATION TIME (DAYS,HRS,MIN)						
MEAN	000000	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

Figure 6.5, TARGET SURVEILLANCE ST. STICS (PAGE 27)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

UNAIDED VISUAL DETECTION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	49	50	51
NUMBER OF DETECTIONS	5	5	5
DETECTION SUCCESS RATIO	1.000	1.000	1.000
DETECTION RANGE (METERS)			
MEAN	119.722	736.548	736.548
STANDARD DEVIATION	0.669	0.047	0.047
DETECTION TIME (DAYS,HRS,MIN)			
MEAN	070640	070643	070643
STANDARD DEVIATION	000000	000000	000000
DETECTION CUES	0	0	0
AURAL			
SENSOR			

IDENTIFICATION STATISTICS OF SIAF BY THE TARGETS

TARGET NUMBER	49	50	51
NUMBER OF IDENTIFICATIONS	5	0	0
IDENTIFICATION SUCCESS RATIO	1.000	0.000	0.000
IDENTIFICATION RANGE (METERS)			
MEAN	119.722	0.000	0.000
STANDARD DEVIATION	0.669	0.000	0.000
IDENTIFICATION TIME (DAYS,HRS,MIN)			
MEAN	070640	000000	000000
STANDARD DEVIATION	000000	000000	000000

FIGURE 6-5. TARGET SURVEILLANCE STATISTICS (PAGE 23)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF STAFF BY THE TARGETS

TARGET NUMBER	1	2	3	4	5	6
NUMBER OF DETECTIONS	0	0	0	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	00000	00000
STANDARD DEVIATION	00000	00000	00000	00000	00000	00000

5 REPLICATIONS

AURAL DETECTION STATISTICS OF SIAP BY THE TARGETS

TARGET NUMBER	13	14	15	16	17	18
NUMBER OF DETECTIONS	0	0	0	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS:HRS.:MINS)						
MEAN	000000	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

FIGURE 6.10. TARGET SURVEILLANCE STATISTICS (PAGE 31)
 MASTER LIGHT SCENARIO 1
 5 REPLICATIONS

AJUAL DETECTION STATISTICS OF SIAE BY THE TARGET

TARGET NUMBER	19	20	21	22	23	24
NUMBER OF DETECTIONS	0	0	0	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	00000	00000	00000	00000	00000	00000
STANDARD DEVIATION	00000	00000	00000	00000	00000	00000

Figure 6.5. TARGET SURVEILLANCE STATISTICS (PAGE 35)
 HUNTER LIGGETT SCENARIO 1
 5 REPLICATIONS

AURAL DETECTION STATISTICS OF SIAP BY THE TARGETS

TARGET NUMBER	43	44	45	46	47	48
NUMBER OF DETECTIONS	0	0	0	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION RANGE (METERS)						
MEAN	0.0	0.0	0.0	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0	0.0	0.0	0.0
DETECTION TIME (DAYS, HRS, MINS)						
MEAN	000000	000000	000000	000000	000000	000000
STANDARD DEVIATION	000000	000000	000000	000000	000000	000000

FIGURE 6-5. TARGET PERFORMANCE STATISTICS (PAGE 3a)
 MOUNTED LIGHTS BY SCENARIO 1
 5 REPLICATIONS

ADJAL DETECTION STATISTICS OF SIAP BY THE TARGETS

TARGET NUMBER	49	50	51
NUMBER OF DETECTIONS	0	0	0
DETECTION SUCCESS RATIO	0.0	0.0	0.0
DETECTION RANGE (METERS)			
MEAN	0.0	0.0	0.0
STANDARD DEVIATION	0.0	0.0	0.0
DETECTION TIME (DAYS.HRS.MINS)			
MEAN	00000	00000	00000
STANDARD DEVIATION	00000	00000	00000

STATISTICS OF CAUSES OF NO DETECTION FOR TARGETS (PAGE 17)
 NUMBER OF TARGET SCENARIOS
 & REPLICATIONS

CAUSES OF NO DETECTION FOR STAF (PERCENT)

TARGET NUMBER	1	2	3	4	5	6
MASKING BY RELIEF	9.746	100.000	100.000	16.667	42.962	0.0
MASKING BY VEGETATION	90.256	0.0	0.0	72.917	55.666	0.0
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	7.813	0.0	0.0
INSUFFICIENT TIME	0.0	0.0	0.0	2.694	1.392	0.0

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	1	2	3	4	5	6
MASKING BY RELIEF	9.340	100.000	100.000	16.000	42.520	0.0
MASKING BY VEGETATION	85.700	0.0	0.0	70.000	55.118	0.0
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	10.000	2.362	100.000
INSUFFICIENT TIME	0.0	0.0	0.0	6.000	0.0	0.0

EMERGENCY SITUATION UNDER SURVEILLANCE STATISTICS (PAGE 3A)
 MOVE-1 LIBERTY SCENARIO 1
 REPLICATIONS

CAUSES OF NO DETECTION FOR STAF (PERCENT)

TARGET NUMBER	7	8	9	10	11	12
MASKING BY RELIEF	19.032	100.000	40.404	0.0	33.384	17.978
MASKING BY VEGETATION	80.968	0.0	59.596	0.0	64.350	65.169
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	0.0	1.007	0.562
INSUFFICIENT TIME	0.0	0.0	0.0	0.0	1.259	16.292

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	7	8	9	10	11	12
MASKING BY RELIEF	19.032	100.000	40.404	0.0	33.384	18.182
MASKING BY VEGETATION	80.968	0.0	59.596	0.0	64.350	65.909
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	100.000	2.266	5.682
INSUFFICIENT TIME	0.0	0.0	0.0	0.0	0.0	10.227

Figure 6.5. SIAF/TARGET SURVEILLANCE STATISTICS (PAGE 39)
 MUNTIS LIGHT SCREEN 1
 5 REPLICATIONS

CAUSES OF NO DETECTION FOR SIAF (PERCENT)		13	14	15	16	17	18
TARGET NUMBER							
MASKING BY RELIEF	0.0	33.969	14.167	0.0	78.750	61.431	
MASKING BY VEGETATION	0.0	63.262	66.667	0.0	21.250	36.392	
RANGE AND LIGHT LEVEL	0.0	0.0	2.500	0.0	0.0	1.089	
INSUFFICIENT TIME	0.0	2.769	16.667	0.0	0.0	1.089	

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)		13	14	15	16	17	18
TARGET NUMBER							
MASKING BY RELIEF	0.0	33.969	14.050	0.0	74.118	61.335	
MASKING BY VEGETATION	0.0	63.262	66.116	0.0	20.000	36.335	
RANGE AND LIGHT LEVEL	0.0	2.769	4.959	0.0	5.882	1.087	
INSUFFICIENT TIME	0.0	0.0	14.876	0.0	0.0	1.242	

Figure 6.5, STAF/TARGET SURVEILLANCE STATISTICS (PAGE 4J)
 HUNTER LIGGETT SCENARIO I
 5 REPLICATIONS

CAUSES OF NO DETECTION FOR STAF (PERCENT)		19	20	21	22	23	24
TARGET NUMBER		0.0	52.795	0.0	0.0	90.278	18.576
MASKING BY RELIEF		100.000	40.373	0.0	0.0	0.0	74.305
MASKING BY VEGETATION		0.0	0.0	0.0	0.0	0.0	0.0
RANGE AND LIGHT LEVEL		0.0	5.832	0.0	100.000	9.722	7.119
INSUFFICIENT TIME							
CAUSES OF NO DETECTION FOR TARGETS (PERCENT)		19	20	21	22	23	24
TARGET NUMBER		0.0	53.125	0.0	0.0	69.041	10.556
MASKING BY RELIEF		90.196	40.625	0.0	0.0	0.0	74.222
MASKING BY VEGETATION		9.804	3.125	0.0	100.000	0.0	4.111
RANGE AND LIGHT LEVEL		0.0	3.125	0.0	0.0	10.959	3.111
INSUFFICIENT TIME							

Figure 6.5. STAF/TARGET SURVEILLANCE STATISTICS (PAGE 61)
 HUNTER LIGHT SCENARIO 1
 5 REPLICATIONS

CAUSES OF NO DETECTION FROM STAF (PERCENT)	25	26	27	28	29	30
TARGET NUMBER	23.136	46.154	35.484	37.122	0.0	10.102
MASKING BY RELIEF	71.722	27.473	59.355	50.204	90.933	10.102
MASKING BY VEGETATION	0.0	0.0	0.0	0.409	2.332	27.273
RANGE AND LIGHT LEVEL	5.141	26.374	5.161	12.265	6.736	36.364
INSUFFICIENT TIME						

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)	25	26	27	28	29	30
TARGET NUMBER	23.136	47.727	32.164	32.946	0.0	10.102
MASKING BY RELIEF	71.722	28.409	53.801	44.557	91.645	10.102
MASKING BY VEGETATION	6.499	0.0	14.035	22.279	2.350	27.273
RANGE AND LIGHT LEVEL	0.643	23.864	6.0	0.218	6.005	36.364
INSUFFICIENT TIME						

Figure 6.5. SIAF/TARGET SURVEILLANCE STATISTICS (PAGE 42)
 HUNTER TARGET SCENARIO 1
 5 REPLICATIONS

CAUSES OF NO DETECTION FOR SIAF (PERCENT)

TARGET NUMBER	31	32	33	34	35	36
MASKING BY RELIEF	52.147	0.0	0.0	91.549	89.286	11.607
MASKING BY VEGETATION	39.877	0.0	0.0	0.0	7.143	83.482
RANGE AND LIGHT LEVEL	3.067	0.0	0.0	0.0	0.0	0.0
INSUFFICIENT TIME	4.908	0.0	100.000	0.451	3.571	4.911

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	31	32	33	34	35	36
MASKING BY RELIEF	50.595	0.0	0.0	85.526	87.549	11.314
MASKING BY VEGETATION	38.690	0.0	0.0	0.0	7.004	81.375
RANGE AND LIGHT LEVEL	2.976	0.0	100.000	0.0	5.447	7.311
INSUFFICIENT TIME	7.738	0.0	0.0	14.474	0.0	0.0

Figure 6.5, STAF/TARGET SURVEILLANCE STATISTICS (PAGE 43)
 HUNTER LIGHT SCENARIO 1
 5 REPLICATIONS

CAUSES OF NO DETECTION FOR STAF (PERCENT)

TARGET NUMBER	37	38	39	40	41	42
MASKING BY RELIEF	0.0	9.563	2.489	0.0	100.000	96.270
MASKING BY VEGETATION	100.000	99.617	97.511	100.000	0.0	3.722
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	0.0	0.0	0.0
INSUFFICIENT TIME	0.0	0.020	0.0	0.0	0.0	0.0

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	37	38	39	40	41	42
MASKING BY RELIEF	0.0	9.150	2.489	0.0	100.000	93.046
MASKING BY VEGETATION	100.000	85.752	97.511	100.000	0.0	3.597
RANGE AND LIGHT LEVEL	0.0	5.098	0.0	0.0	0.0	2.398
INSUFFICIENT TIME	0.0	0.0	0.0	0.0	0.0	0.959

Figure 6.5. STAF/TARGET SURVEILLANCE STATISTICS (PAGE 44)
 WINTER LIGHT SCENARIO 1
 5 REPLICATIONS

CAUSES OF NO DETECTION FOR STAF (PERCENT)						
TARGET NUMBER	43	44	45	46	47	48
MASKING BY RELIEF	56.875	0.0	100.000	100.000	100.000	100.000
MASKING BY VEGETATION	3.125	0.0	0.0	0.0	0.0	0.0
RANGE AND LIGHT LEVEL	0.0	0.0	0.0	0.0	0.0	0.0
INSUFFICIENT TIME	0.0	0.0	0.0	0.0	0.0	0.0
CAUSES OF NO DETECTION FOR TARGETS (PERCENT)						
TARGET NUMBER	43	44	45	46	47	48
MASKING BY RELIEF	96.673	0.0	98.000	98.000	98.000	98.394
MASKING BY VEGETATION	3.112	0.0	0.0	0.0	0.0	0.0
RANGE AND LIGHT LEVEL	0.0	100.000	0.0	2.000	2.000	0.0
INSUFFICIENT TIME	0.415	0.0	2.000	0.0	0.0	1.606

FIGURE 6-10. SIZE/TARGET COMPLIANCE STATISTICS (PAGE 45)
 NUMBER OF NO DETECTION
 & REPLICATIONS

CAUSES OF NO DETECTION FOR SIZE (PERCENT)

TARGET NUMBER	40	50	51
MASKING BY RELIEF	0.0	0.0	0.0
MASKING BY VEGETATION	0.0	0.0	0.0
RANGE AND LIGHT LEVEL	0.0	0.0	43.233
INSUFFICIENT TIME	0.0	0.0	16.047

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	49	50	51
MASKING BY RELIEF	0.0	0.0	0.0
MASKING BY VEGETATION	0.0	0.0	0.0
RANGE AND LIGHT LEVEL	0.0	0.0	0.0
INSUFFICIENT TIME	0.0	0.0	0.0

MOVEMENT RATE STATISTICS (PAGES 56)
MOUNTAIN LIGHT SCENARIO 1
5 REPLICATES

MOVEMENT RATE (KM/HR)
MEAN 6.964
STANDARD DEVIATION 0.324

PATROL DURATION (DAYS, HRS, MINS)
MEAN 071000
STANDARD DEVIATION 000000

DISTANCE TRAVELLED (KM)
MEAN 9.022
STANDARD DEVIATION 0.000

MOVEMENT RATE HISTOGRAM (KM/HR)

PERCENT TIME BETWEEN 0.0 - 0.200 KM/HR =	0.004
PERCENT TIME BETWEEN 0.200 - 0.400 KM/HR =	0.0
PERCENT TIME BETWEEN 0.400 - 0.600 KM/HR =	0.009
PERCENT TIME BETWEEN 0.600 - 0.800 KM/HR =	0.310
PERCENT TIME BETWEEN 0.800 - 1.000 KM/HR =	0.457
PERCENT TIME BETWEEN 1.000 - 1.200 KM/HR =	0.001
PERCENT TIME BETWEEN 1.200 - 1.400 KM/HR =	0.038
PERCENT TIME BETWEEN 1.400 - 1.600 KM/HR =	0.137
PERCENT TIME BETWEEN 1.600 - 1.800 KM/HR =	0.004
PERCENT TIME BETWEEN 1.800 - 2.000 KM/HR =	0.030
PERCENT TIME BETWEEN 2.000 - 2.200 KM/HR =	0.002
PERCENT TIME BETWEEN 2.200 - 2.400 KM/HR =	0.001

FIGURE 6.5. STAF NAVIGATION STATISTICS (PAGE 47)
WINTER LEGGETT SCENARIO 1
5 REPLICATIONS

PATROL CEP AT CHECKPOINTS (METERS)
MEAN 31.621
STANDARD DEVIATION 8.442

TIME TO DETERMINE LOCATION (MIN)
MEAN 0.830
STANDARD DEVIATION 0.0

STAF INSERTION STATISTICS

INSERTION ATTEMPTS
NUMBER OF SUCCESSFUL INSERTIONS
NUMBER OF INSERTIONS AT PRIMARY LZ
NUMBER OF INSERTIONS AT SEC. LZ
INSERTION TIME (DAYS,HRS,MIN) 011700

EXTERNAL COMMUNICATIONS

ATTEMPTS	
MEAN	176.000
STANDARD DEVIATION	0.0
COMMUNICATION SUCCESS RATIO	
MEAN	0.827
STANDARD DEVIATION	0.034
AVERAGE POWER LOSSES FOR COMM FAILURES (PERCENT)	
ATTENUATION DUE TO RELIEF	10.952
ATTENUATION DUE TO VEGETATION	1.019
ATTENUATION DUE TO RANGE	88.037
TOTAL TIME RECEIVING (DAYS,HRS,MIN)	
MEAN	051700
STANDARD DEVIATION	000000
TOTAL TIME TRANSMITTING (DAYS,HRS,MIN)	
MEAN	000300
STANDARD DEVIATION	000010
AMPERE HRS AVAILABLE	138.000
AMPERE HRS USED	
MEAN	79.817
STANDARD DEVIATION	0.099

STANDARD DEVIATION
 SUPPLY MAINTENANCE
 END

	BEGINNING	END
TOTAL WEIGHT CARRIED (LBS/MAN)		
MEAN	65.051	50.518
STANDARD DEVIATION	0.0	0.000
FOOD (LBS/MAN)		
MEAN	6.520	0.0
STANDARD DEVIATION	0.0	0.0
WATER (LBS/MAN)		
MEAN	8.017	0.0
STANDARD DEVIATION	0.0	0.0
AMMO (LBS/MAN)		
MEAN	0.0	0.0
STANDARD DEVIATION	0.0	0.0
OTHER ORDNANCE (LBS/MAN)		
MEAN	2-250	2-250
STANDARD DEVIATION	0.0	0.0

MEAN 0.0 0.0 0.0 0.0 0.0
 STANDARD DEVIATION 0.000 0.000 0.000 0.000 0.000 0.000

ENERGY EXPENDITURE (BTU)
 MEAN 2722.044 5131.193 1318.590
 STANDARD DEVIATION 1.489 33.000 6.130

TIME HISTORY IN NORMAL DECOMMISSION DEGRADATION (FIRST REPLICATION ONLY)

TIME	011722	012022	012303	020231	020532	020920
PERF. DEG.	0.000	0.010	0.021	0.011	0.002	0.0
TIME	021201	021512	021831	022132		
PERF. DEG.	0.0	0.0	0.0	0.009		

UNITED STATES DEPARTMENT OF THE ARMY
 HEADQUARTERS, 1000 AVENUE OF THE STARS
 WASHINGTON, D.C. 20315

NUMBER OF SECTIONS: 61

STAFF ARRIVAL TIME BY CHECKPOINTS (DAYS:HR:MM:SS)

CHECKPOINT ARRIVAL TIME	1	2	3	4	5
	000000	011721	011731	011745	012241
CHECKPOINT ARRIVAL TIME	7	8	9	10	11
	012314	021925	021937	021954	022217
CHECKPOINT ARRIVAL TIME	13	14	15	16	17
	022304	031434	032009	032030	032203
CHECKPOINT ARRIVAL TIME	19	20	21	22	23
	033000	040000	040000	040000	040000
CHECKPOINT ARRIVAL TIME	25	26	27	28	29
	040000	040000	040000	040000	040000
CHECKPOINT ARRIVAL TIME	31	32	33	34	35
	040000	040000	040000	040000	040000
CHECKPOINT ARRIVAL TIME	37	38	39	40	41
	040000	040000	040000	040000	040000
CHECKPOINT ARRIVAL TIME	43	44	45	46	47
	040000	040000	040000	040000	042219
CHECKPOINT ARRIVAL TIME	49	50	51	52	53
	042204	042207	040000	040000	040000
CHECKPOINT ARRIVAL TIME	55	56	57	58	59
	040000	040000	040000	040000	040000
CHECKPOINT ARRIVAL TIME	61	62	63	64	65
	040000	040000	040000	040000	040000

MOBILE STATISTICS (PART 2)
 DIFF LIGHTY SOFTWARE
 APPLICATIONS

CHECKPOINT ARRIVAL TIME	80 042216	81 000000	82 000000	83 000000	84 000000	85 000000	86 000000	87 000000	88 000000	89 000000	90 000000
CHECKPOINT ARRIVAL TIME	73 000000	74 000000	75 000000	76 000000	77 000000	78 000000	79 000000	80 000000	81 000000	82 000000	83 000000
CHECKPOINT ARRIVAL TIME	79 000000	80 042240	81 050447	82 050453	83 051914	84 051924	85 051924	86 051924	87 051924	88 051924	89 051924
CHECKPOINT ARRIVAL TIME	95 051933	96 051947	97 052040	98 060214	99 061113	90 061123	91 061137	92 070643	93 070643	94 070643	95 070643

LIGHT LEVEL (FT LAMPERTS) AND SAMPLE TIME (DAYS, HRS, MINS)

LIGHT LEVEL SAMPLE TIME	2.89E 02 011721	1.69E 02 011731	6.93E 01 011745	3.83E 01 011800	1.91E-01 011900	1.00E-03 012000	1.00E-03 012000	1.00E-03 012000	1.00E-03 012000	1.00E-03 012000	1.00E-03 012000
LIGHT LEVEL SAMPLE TIME	1.00E-03 012100	1.00E-03 012200	1.00E-03 012241	1.00E-03 012251	1.00E-03 012300	1.00E-03 012314	1.00E-03 012314	1.00E-03 012314	1.00E-03 012314	1.00E-03 012314	1.00E-03 012314
LIGHT LEVEL SAMPLE TIME	1.00E-03 020000	1.00E-03 020100	1.00E-03 020200	1.00E-03 020300	1.00E-03 020400	1.00E-03 020500	1.00E-03 020500	1.00E-03 020500	1.00E-03 020500	1.00E-03 020500	1.00E-03 020500
LIGHT LEVEL SAMPLE TIME	6.64E 01 020600	1.71E 02 020700	1.00E 03 020800	1.00E 03 020900	1.00E 04 021000	1.00E 04 021100	1.00E 04 021100	1.00E 04 021100	1.00E 04 021100	1.00E 04 021100	1.00E 04 021100
LIGHT LEVEL SAMPLE TIME	1.00E 04 021200	1.00E 04 021300	1.00E 04 021400	1.00E 04 021500	1.00E 04 021600	1.00E-03 021700	1.00E-03 021700	1.00E-03 021700	1.00E-03 021700	1.00E-03 021700	1.00E-03 021700
LIGHT LEVEL SAMPLE TIME	5.15E 01 021800	9.57E-02 021900	1.00E-03 021925	1.00E-03 021937	1.00E-03 021954	1.00E-03 022000	1.00E-03 022000	1.00E-03 022000	1.00E-03 022000	1.00E-03 022000	1.00E-03 022000
LIGHT LEVEL SAMPLE TIME	1.00E-03 022100	1.00E-03 022200	1.00E-03 022217	1.00E-03 022236	1.00E-03 022300	1.00E-03 022323	1.00E-03 022323	1.00E-03 022323	1.00E-03 022323	1.00E-03 022323	1.00E-03 022323

WINTER LIGHT SCENARIO 1
5 REPLICATIONS

LIGHT LEVEL SAMPLE TIME	1.00E-03 030000	1.00E-03 030200	1.00E-03 030300	1.00E-04 030400	6.92E-04 030500
LIGHT LEVEL SAMPLE TIME	6.64E 01 030600	1.00E 02 030700	1.00E 03 030800	1.00E 04 030900	1.00E 04 031000
LIGHT LEVEL SAMPLE TIME	1.00E 04 031200	1.00E 04 031400	1.00E 04 031500	1.00E 04 031600	1.20E 03 031700
LIGHT LEVEL SAMPLE TIME	3.83E 01 031800	9.57E-02 031900	1.00E-03 032000	1.00E-03 032009	1.00E-03 032030
LIGHT LEVEL SAMPLE TIME	1.00E-03 032100	1.00E-03 032200	1.00E-03 032219	1.00E-03 032300	1.00E-03 040000
LIGHT LEVEL SAMPLE TIME	1.00E-03 040100	8.00E-04 040200	8.00E-05 040400	8.00E-05 040439	5.66E-04 040500
LIGHT LEVEL SAMPLE TIME	1.65E 01 040600	1.31E 02 040700	1.00E 03 040800	1.00E 03 041000	1.00E 03 041100
LIGHT LEVEL SAMPLE TIME	1.00E 03 041200	1.00E 03 041300	1.00E 03 041500	1.00E 03 041600	3.76E 02 041700
LIGHT LEVEL SAMPLE TIME	5.94E 00 041800	3.97E-02 041900	5.00E-04 042000	8.00E-04 042200	8.00E-04 042204
LIGHT LEVEL SAMPLE TIME	8.00E-04 042207	9.00E-04 042216	9.00E-04 042300	8.00E-04 050000	8.00E-04 050100
LIGHT LEVEL SAMPLE TIME	8.00E-04 050200	8.00E-04 050300	9.73E-05 050447	3.15E-04 050453	1.02E-03 050500
LIGHT LEVEL SAMPLE TIME	1.65E 01 050600	1.47E 02 050700	1.00E 03 050900	1.00E 03 051000	1.00E 03 051100
LIGHT LEVEL SAMPLE TIME	1.00E 03 051200	1.00E 03 051300	1.00E 03 051500	1.00E 03 051600	3.35E 02 051700
LIGHT LEVEL SAMPLE TIME	1.06E 01 051800	4.04E-02 051900	7.65E-03 051914	9.01E-04 051933	8.00E-04 051947

HUNTER LIGGETT SCENARIO 1
5 REPLICATIONS

LIGHT LEVEL SAMPLE TIME	8.00E-04 052000	1.00E-04 052040	8.00E-04 052100	9.00E-04 052200	8.00E-04 052300	8.00E-04 060000
LIGHT LEVEL SAMPLE TIME	8.00E-04 060100	1.00E-03 060200	1.00E-03 060214	1.00E-03 060300	1.00E-03 060400	1.06E-03 060500
LIGHT LEVEL SAMPLE TIME	4.70E 01 060600	1.21E 02 060700	1.07E 03 060800	1.07E 03 060900	1.00E 04 061000	1.00E 04 061100
LIGHT LEVEL SAMPLE TIME	1.00E 04 061113	1.00E 04 061123	1.00E 04 061137	1.00E 04 061200	1.00E 04 061300	1.00E 04 061400
LIGHT LEVEL SAMPLE TIME	1.00E 04 061500	1.00E 04 061600	1.62E 03 061700	5.15E 01 061800	1.91E-01 061900	1.00E-03 062000
LIGHT LEVEL SAMPLE TIME	1.00E-03 062100	1.00E-03 062200	1.00E-03 062300	1.00E-03 070000	1.00E-03 070100	1.00E-03 070200
LIGHT LEVEL SAMPLE TIME	1.00E-03 070300	1.00E-03 070400	6.92E-04 070500	7.62E 01 070600	8.58E 01 070643	1.31E 02 070700
LIGHT LEVEL SAMPLE TIME	1.00E 03 070800	1.00E 03 070900				



Table 6-1, Target Number System (Sheet 1)

- WATER CAN EVENT - DAY 01
 - 1 - TRUCK (ROUND TRIP)
 - 2 - MEN + WATER CANS
 - 3 - LIT CIGARETTES
- AMMO CARRIERS - DAY 02
 - 4 - MEN
- STAR CLUSTER EVENT - DAY 02
 - 5 - TRUCK (ROUND TRIP)
 - 6 - FLARE (COLUMN)
- TRUCK/AMMO EVENT - DAY 03
 - 7 - TRUCK + TAILGATE BANGING
 - 8 - LIT CIGARETTES
- SMOKE AT SUNRISE EVENT - DAY 03
 - 9 - MEN
 - 10 - SMOKE COLUMN
- RADAR ANTENNA DISASSEMBLY - DAY 03
 - 11 - TRUCK (ROUND TRIP)
 - 12 - MEN
 - 13 - CIGARETTE SMOKE (COLUMN)
- RADAR ANTENNA ASSEMBLY - DAY 03
 - 14 - TRUCK (ROUND TRIP)
 - 15 - MEN
 - 16 - CIGARETTE SMOKE (COLUMN)
- SECURITY PATROL (A-LOOPS) - DAY 03
 - 17 - TRUCK (DELIVERY)
 - 18 - PATROL THROUGH LOOPS
- MOODLE CARRIERS - DAY 04
 - 19 - TRUCK (DELIVERY)
 - 20 - PATROL THROUGH LOOPS (C-TRAIL)
 - 21 - TWO PATROLS LEAVING AGGRESSOR TENT
 - 22 - LIT CIGARETTE
 - 23 - CROW'S NEST PATROL (A74)
 - 24 - TWO TRUCKS (PICK-UP)

Table 6-1, Target numbering system (Sheet 2)

- EXOTIC WEAPON EVENTS - DAY 04
- 25 - TRUCK (DELIVERY)
- 26 - PATROL
- SECURITY PATROL (A-LOOPS) - DAY 04
- 27 - TRUCK (DELIVERY)
- 29 - PATROL (A-1 TO A-41)
- 30 - PATROL (A-49 TO A-62)
- * ● WATER CAN EVENT - DAY 04
- 28 - TRUCK (ROUND TRIP)
- NOODLE CARRIERS - DAY 05
- 31 - PATROL (C-LOOPS)
- 32 - TWO PATROLS LEAVING AGGRESSOR TENT
- 33 - LIT CIGARETTE
- 34 - CROW'S NEST PATROL
- 35 - TWO TRUCKS (PICK-UP)
- * ● STAR CLUSTER EVENT - DAY 05
- 36 - TRUCK (ROUND TRIP)
- 37 - FLARE
- HELIPAD EVENT - DAY 06
- 38 - TRUCK (ROUND TRIP)
- 39 - MEN
- 40 - STROBE LIGHT
- 41 - LANDING LIGHTS
- * ● PASSING TRUCKS - DAY 06
- 42 - AMMO TRUCK
- 43 - RADAR DISASSEMBLY TRUCK
- LASER EXERCISE - DAY 06
- 44 - BEACON
- * ● PASSING TRUCKS - DAY 06 AND 07
- 45 - RADAR ASSEMBLY TRUCK
- 46 - LOOP PATROL TRUCK
- 47 - NOODLE CARRIER TRUCK
- 48 - TWO TRUCKS FOR PICK-UP
- ROAD PATROL EVENT - DAY 07
- 49 - TRUCK (ONE-WAY)
- 50 - PATROL
- 51 - CIGARETTE SMOKE (COLUMN)

* EVENTS PLANNED FOR A SECOND PATROL IN THE TEST, THAT PRESENT DETECTION OPPORTUNITIES FOR THE FIRST PATROL.

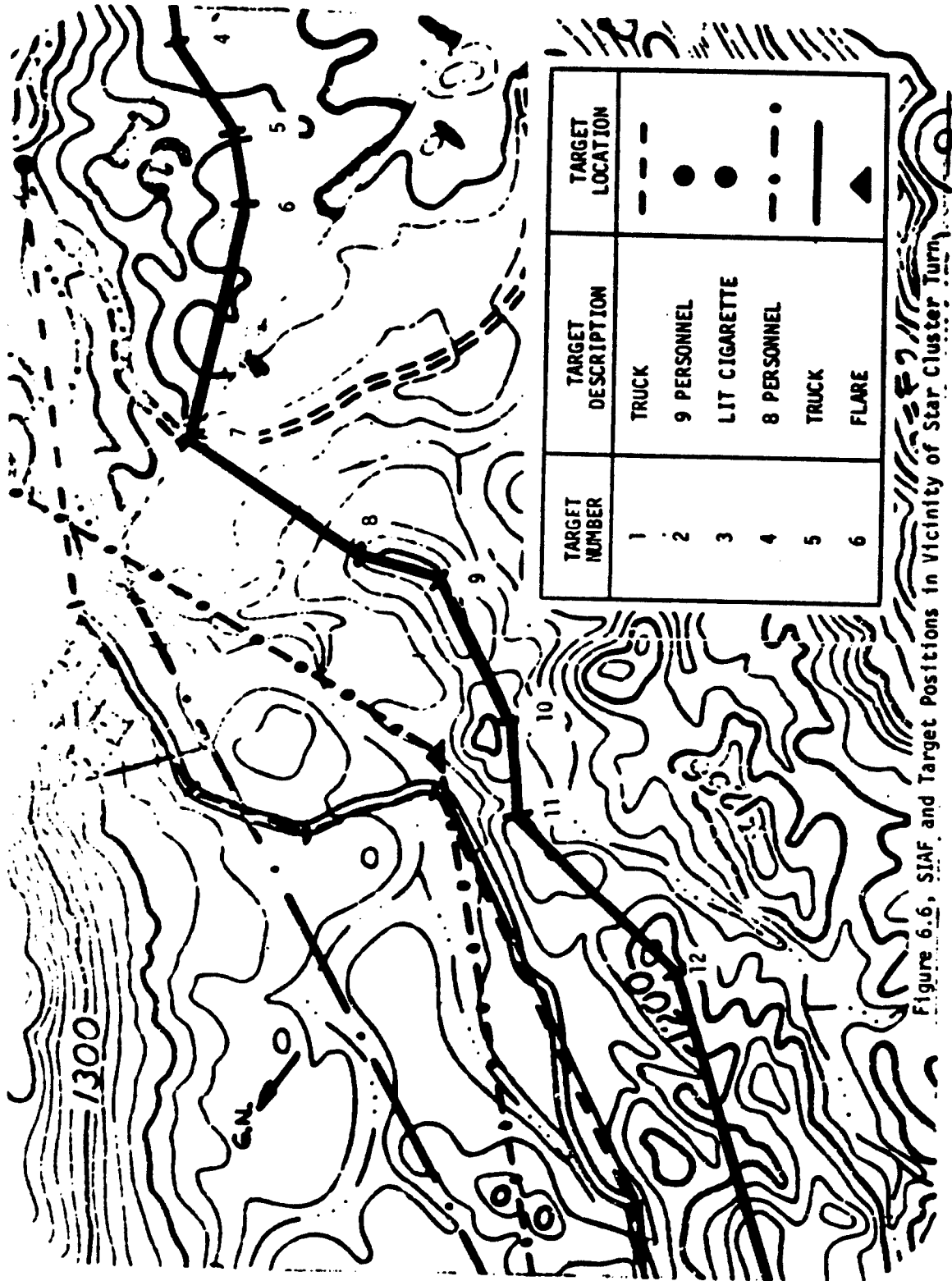
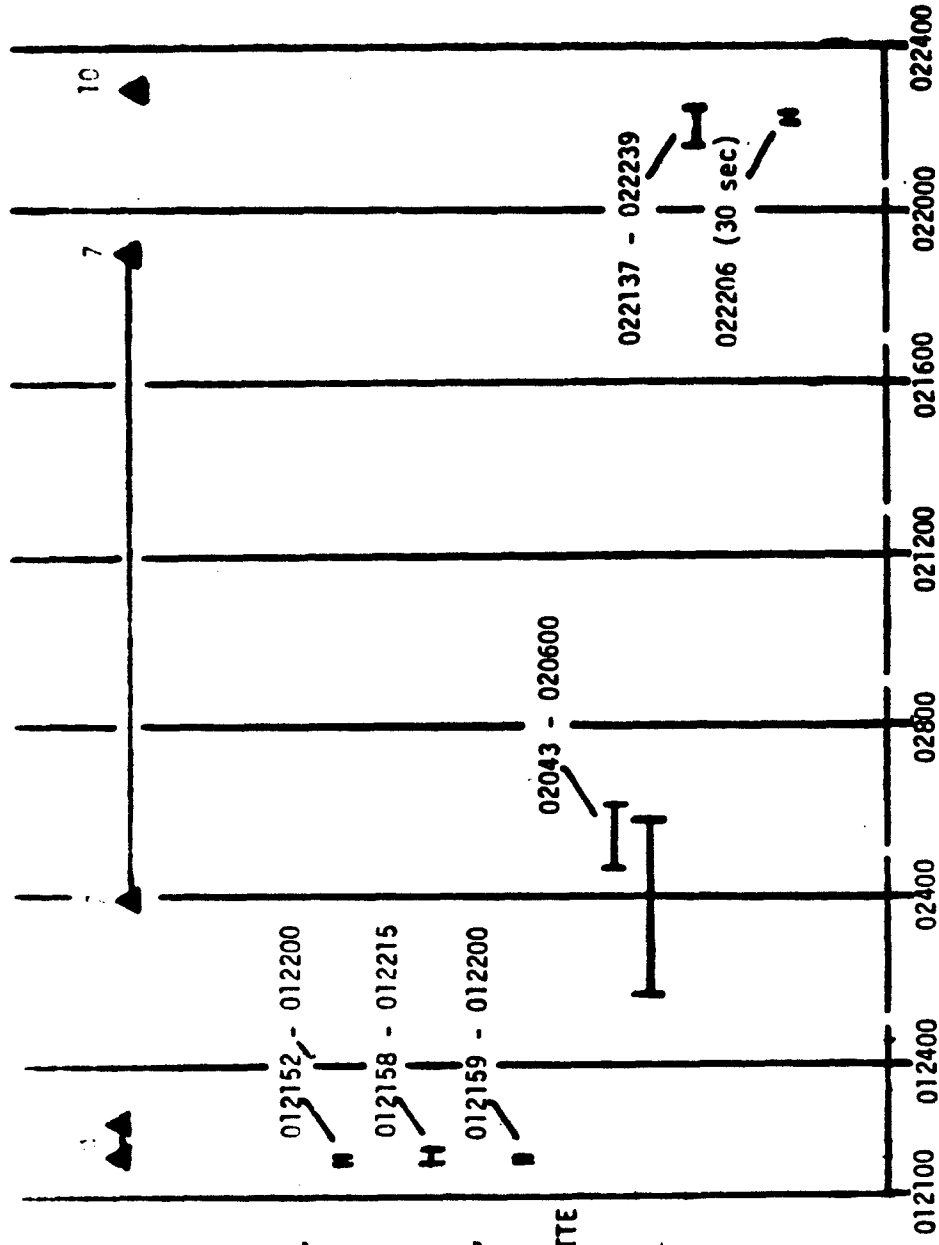


Figure 6.6, SIAF and Target Positions in Vicinity of Star Cluster Turn



SIDE CHECKPOINTS

TARGETS

TARGET #	DESCRIPTION
1	TRUCK
2	9 PERSONNEL
3	LIT CIGARETTE
4	8 PERSONNEL
5	TRUCK
6	FLARE

Figure 6.7, Timeline Diagram for Selected Portion of the Scenario

6.5 USER INPUT FOR THE COMBAT MODEL SAMPLE CASE

As an example of the operation of the integrated reconnaissance and combat model including the additions made in the modification contract, the following case is presented. Figure 6.8 shows the namelist input used for this case. The area of operations is taken from the Hunter Liggett Military Reservation. The scenario calls for a SIAF patrol of eight men on an ambush mission. They are moving in the dry El Piojo Creek bed at 0800. The scenario is diagrammed in Figure 6.9. The target starts on the other side of an 80 foot hill approximately 600 meters away. The target is a six-man patrol and is heading on a collision course with the SIAF.

6.6 OUTPUTS FOR THE COMBAT MODEL SAMPLE CASE

The outputs of the model, shown in Figure 6.10, consist of detail and summary printout. The detailed printout begins with the location of the target and of the SIAF. Two lines of printout are generated by the Reconnaissance model at the end of each segment. This gives the positions, a detection verdict, the time, and the reason for no line of sight.

At 17 minutes into the mission, the SIAF detects the target. This is shown by point 1 on Figure 6.9. It is in an area of both vegetation and microrelief. The output then shows the generation of a dynamic route to seek recognition of the target. The grid plot shows the selected grid points for the dynamic route. One minute later, the SIAF identifies the target. The range is 264 meters. This is shown by point 2 on Figure 6.9 for both the SIAF and target. At this point, a dynamic route is generated to return to the original route should that be the decision of the SIAF.

The action selected by the decision logic submodel is to continue to ambush. A preliminary deployment point and engagement point is selected which is the first admissible point. The optimization logic then selects deployment points for both a base of fire and a moving maneuver unit. These are shown by the pair of points labelled number 3 at the edge of the wooded area. The projected engagement point for the target is also shown. The optimization logic also determines an assault point close to the target.

At this point in the simulation, the terrain resolution is shifted from 50.8 meters to 12.7 meters for greater accuracy in the line of sight calculations. The individual attributes are then printed for both patrols

at the start of combat. The next computation is the generation of dynamic routes for the attacker maneuver units to the deployment points.

The combat model through its executive routine, CMAIN, then assumes control of the simulation. This is driven by the first occurrence of a detection, arrival at the checkpoint (generated by dynamic route routine), casualty, or 20 seconds if nothing else happens. For other missions, it considers also the arrival of an external fire support burst and the detonation of Claymore mines. For this case, the first few events are individual detections by SIAF members of target members. More detections could be occurring, but only one is printed per patrol at each event interval. Here the locations of the maneuver unit leaders are also printed. The next two events are arrivals at the intermediate dynamic route points. This process continues until both maneuver units have arrived at their deployment points. At this time, they stop. A dynamic route is generated for the moving maneuver unit to get to the assault point, but movement does not begin on this leg for an ambush until the firefight has begun. The model continues to print detection events for the attacker of the defender while the defender is moving to the engagement point.

When the defender arrives at the engagement point, the SIAF opens fire and a casualty event occurs within 2 seconds. As shown in the print-out, the casualty is defender number 5 who sustains a minor wound. The next event is another casualty. This time defender 2 sustains a major wound. The elapsed time of the firefight is 3.3 seconds. The attribute tables for both patrols are then printed as they are after either a major wound or death. At this time, the defender decides to withdraw and selects a direction 180° opposite to which it was moving. The break decision was due to the high number of casualties.

At the five second point, defender number 3 is killed. The break decision printout is repeated for information purposes, but no new action is taken. The next event is a major wound for defender 1 at 6.2 seconds. At 7.8 seconds, defender 6 is killed and at 9.7 seconds, defender 4 is killed. At this point all defenders have been killed or wounded. The SIAF stops firing and the moving maneuver unit reaches the first checkpoint on its assault route.

At 30 seconds, however, the SIAF decides to break due to an elapsed time criterion. A rally point is selected on the opposite side of the hill and the SIAF begins moving. After arriving at the rally point, the patrol decides to continue the reconnaissance mission. The final attributes are printed and control is returned to the Reconnaissance Model. At this time, the elevation data at the 50.8 meter resolution is retrieved. The SIAF then completes its operations plan and is extracted. Summary statistics for the mission are then printed.

6.7 EXAMPLE USING EXTERNAL FIRE SUPPORT

The same case was run using external fire support in preparation for the firefight. The same inputs were used except the mission was changed to attack. The same deployment and engagement points were selected, but this time a volley of artillery shells arrived soon after the request. Figure 6.12 shows the detailed output from there on. First the burst points are printed and then the attributes after the burst. The next event is a casualty inflicted by the SIAF who open fire after the first volley. The next events are arrivals of more volleys of artillery. Again the target decides to break in the opposite direction. The attacker decides to break due to the elapsed time criterion.

6.8 EXAMPLE USING CLAYMORE MINES

For this case, the mission was switched to an ambush using Claymore mines. As shown in Figure 6.13, the mines were deployed just inside the edge of the wooded area. The SIAF was deployed in the woods and was not detected by the target. When the target reached the most vulnerable area with respect to the mines, they were detonated and all of the target personnel were killed. Control then returned to the Reconnaissance model after the withdrawal. The detailed output is shown in Figure 6.14.

SNAM1
 AA = 1.85.
 AEO = 0..
 ALIM = .0001, .001, .1, .100..
 ALLB = 500..
 ALLF = .75, 2.1, .075, 2.1..
 ALLW = .0004.
 ANGIO = 12..
 AOXMAX = 2400..
 AOYMAX = 7200..
 ANMTAB = 3.0, 0.8, 3.0, 0.4, 2.0, 0.6, 4.0, 0.7, 1.0, 3.5, 0.04, 2.0, 0.029,
 0.033, 0.032, 2* 0.037,
 ATER = 0..
 ATTAR = 4..
 ATTEN = 0.03, 0.09, 0.15, 0.12.
 BE = 25..
 BSAREA = 20..
 COMRES=15..
 CONCAP = 0.0735.
 CPRAT = -1700., -700., 600., -1200., -550., -50., -600..
 CRFCOG = 1..
 DBACK =150..
 DMT = 0., 25., 75., 25., 20., 25., 75., 50., 1000., 600..
 DRICE = 0.3.
 DSTEP =20..
 DSM11 = 1..
 DSM12=1..
 DYMT=-1.1, .3, .3, -1.1, .0, .0, -1.0, .0, .2, -2.1, .1, .5, 0., 2, -3.4, 1.
 FWRAT =300., 500., 600., 400., 450., 550., 467..
 GR = 25..
 H = 0., 1., 1.5, 3., 4.0, 0.5, 2.0, 0.7,
 4.0, 3., 2.1, 0., 2.5, 3.3, 2.2, 4., 0..
 4.0, 2., 3., 5., 4., 1., 7.5, 11., 14., 0., 3., 2.0..
 4.0, 10., 12., 15., 20., 15., 18., 24., 30., 0., 5., 2.0..
 HR = -1., -0.5, -4., 1.8, -0.8, 4., 2., 2.0..
 HMT = 0., -0.25, 2*-0.5, 2.0., 0.25, 0.5, 5.0, 0.25, 1..
 IDTIM = 1.
 ISECT(1)=1, 2, 3, 4, 1, 2, 3, 1, 4, 1, 2, 1, 3, 1, 2, 3, 4, 1, 2, 3,
 ITACOS = 900,
 ITRPM = 60,
 ITNMTA = 120,
 ITNTAR = 30.

Figure 6.8, Combat Sample Case Nasal1st Inputs

IYMAT = 301.
 IYMAT = 350.
 IYMAT = 1080.
 MPAR = 9.
 P = 760.
 PNC = 25.
 PNR = 25.
 PO = 760.
 PS = 42.
 RC = 4.
 RCTAR = 10.
 RECRES = 50.
 REF = 0.3, 0.3, 0.13, 0.13, 4*0.3, 4*0.09, 0.17, 0.15, 2*0.2,
 2*0.3, 2*0.13, 3*0.35, 0.3, 4*0.09, 0.17, 0.15, 2*0.2,
 3*1., 2*0.13, 0.06, 0.03, 5*0.02, 1., 0.04, 0.2, 1.
 REQ = 0.
 RESMAX = 12.7.
 RHOM = 0.075.
 RHOMI = 0., 50., 667., 120., 450., 18., 2*0., 5.,
 40., 135., 250., 500., 0., 1200., 250., 500., 1000., 20., 1300.,
 50., 0., 4*0., 70., 140., 300., 600., 30., 200., 350., 400., 0.,
 100., 2*0., 4*0., 70., 140., 300., 600., 30., 200., 350., 400., 0.,
 100., 2*0.,
 RMAX = 1000., 36., 20., 10., 8*1000., 10., 2*1000., 15.,
 4*1000., 75., 72., 36., 1000., 10., 32., 16., 10., 50., 2*10.,
 21*1000., 75., 30., 12., 10., 120., 18., 10., 10., 1000., 80.,
 2*1000.,
 RMTMAX = 200., 100., 50., 100., 2*200., 100., 50., 5*200., 150., 50.,
 RPE = 0.24.
 RPG = 0.5.
 RTFR = 0.
 SECT = 5.49, 0.745, 0.745, 2.35, 1.93, 5.49, 2.35, 1.93,
 4.72, 1.57, 0., 2*1.14, 0., 1.57, 4.72.
 SEGMIN = 1.
 SGMTAB = 50.
 SGMTAM = 20.
 SIGFFR = J-00000001103.
 SL1 = 0.00J5.
 SL2 = 0.05.
 SOILF = .8, .45, .8, .75, .7, .65, .6, .5, .4, 3*1., 4*0.9.

SIS = 95.
TO = 536.

TMR = .1. .25. .5. .75. 1. 1.25. 1.5. 1.75. 2. 2.25. 2.5. 2.75. 3. 3.25. 3.5.
1.5. .05. 36.25. 2. .5. 1. 1.5. 2. 2.5. 3. 3.5. 2.3.
1.6. 1. .7. .3. 1. 36.5. -1.6. -1.4. -1.2. -1. .8.
-0.6. -0.4. -0.2. 0. .2. .4. .6. .8. 1. 1.2. 1.4. 1.6. 1.8.
VEGC = 19. 1. 3. 35. 30. 55. 30. 0.5. 10. 0.85. 3. 33. 28.
56. 31. 0.5.
4. 0.7. 3. 31. 26. 57. 32. 0.5. 2. 0.60. 2. 30. 25. 58.
33. 0.5.

5. 0.85. 3. 29. 24. 59. 33. 0.65. 15. 0.80. 3. 28.
23. 59. 33. 0.4.
7.5. 0.7. 2. 27. 22. 57. 32. 0.35. 7.5. 0.65. 2. 25.
20. 55. 30. 0.3.
1. J.20. 2. 25. 20. 60. 34. J.2. 2. 0.4J. 2. 28.
23. 56. 32. 0.3.

1.5. 0.30. 1. 27. 22. 58. 33. 0.25. 1. 0.2. 1. 25.
20. 60. 34. 0.2.
2. 0.3. 1. 30. 25. 62. 35. 0.5. 1. J.2. 1. 28. 23.
63. 35. J.4.
2. .9. 3. 40. 35. 57. 32. 0.4. 10. J.2. J. 40.
35. 61. 34. 0.5.

VEGF = 1. .85. 7. 4. .85. .8. .7. .65. .2. .4. .3. .2.
.3. .2. .9. .2.
VISLUM = 4000. 15000. 13000. 10000. 2000. 500. 300. 50.
1000. 500. 100. 100. 500. 100. 10.
240. 10. 1. 1J. 5. 1. 0.1. 24. 1. 0.1. 1. 0.5. 0.1. 0.1.
240.001. J.0008. 0.0002. 0.0008. 0.0005. J.0002. 0.0001.
240.001. 0.0008. 0.0002. 0.0008. 0.0005. 0.0002. 0.0001.
240.004. 0.003. 0.008. 0.003. 0.002. 0.008. 0.004.
240.01. 0.008. 0.002. 0.008. 0.005. 0.002. 0.001.

VISM = 13.
VISMM = 300.
VTYP=3.
M = 0. 1. 1.5. 10. 40. 20. 20. 50.
40. 2. 201. 0. 42. 1. 2. 10. J.
40. 340.3. 0.45. 0.2. 20.3. J.45. 0. J.5. 240.
40. 3. 3.5. 4. 4.5. 24. 4.5. 5. 0. 2. 240.
= 0. 5. 4. 5. 240. 5. 4. 50. 0.5. 1.
= 0.5.

XLP = 341. 0.95. 0.9. 0.5. J.15. 0.01. 0.9. 0.5. J.25. 0.1. 1. 0.75.
0.95. 1.

8

SNAMLZ
BEYA = 40..
BLIFE =100..
DMOR=0..
DMORB=0..
DOMAT = 2.
DOMV = 1.
DPE =10..
DSA=0..
DSAA=0..
EQUIP = 0..
ENRNG = 0..
F(1,1) =1..
FOOD =13.47.
FORMS=200*0..
FORMT=800*0..
FREQ = 50..
GSAPRX=20..
GSAPXX=20..
MLZ=3600..
MZO =6.96.
ICL(1)=5.3.5.
ICPER = 3600.
IDELA=1.
IDELB=1.
IDELC=1.
IDELD=1.
IDELE=1.
IOMST = 3.
IFADJ =20*0.
IFS=0.
IFSUP =20*0.
IFSUP(1)=1.
IOR=5*0.
IFT=20*0.
IPNS =1.
IPREP = 0.
ISEN = J.
ISENLZ=0.
ISTAY(1,1)=3*0.1.
ITARI(1,1)=4*0.

ITACT = 1, 3, 2, 1, 6, 1,
ITMAX = 0100000,
ITMOV(1,1) = 3, 0, 01003700,
ITRC(1,1) = 1, 2, 1
IVSTAV(1,1) = 3, 0, 00002000,
ITZERO = 01000000,
IX1 = 334432395,
IX2 = 363975447,
JSTART=0,
JSTOP=0,
JMP = 1,
LNRI=0,
KNRC(1)=3+1,
MAE(1) = 600.,
MAXCAS = 1,
MAXREP = 1,
MICRI=1,
MODE = 1,
NRAT = 2,
NCO(1)=3, 4, 3,
NOCOPY = 1,
NDECOY = 0,
NFIK= 1,
NHANDG = 0,
NLZ
NNINES = 0,
NN (1) = 36,
NOB = 0,
NPLAN(1)=7. ←
NRAD = 1,
NRMT = 2,
NRST = 0,
NRVP=1,
NSENS=0,
NSWT = 1,
NTAR=1,
NWCL(1,1) = 010800, 012000, 020630, 020900, 021000, 022000, 030400, 042400,
050630, 050900, 051600, 052000, 060630, 060900, 061600, 062000,
070630, 070900, 100000,
NWCL(1,2) = 2, 1, 5, 1, 2, 1, 3, 1, 5, 1, 2, 1, 5, 1, 2, 1, 4, 1, 2, 1, 1,
PEQUIP = 313.46,
PPLS = 0.

PLS SYSTEMS
 RAMU = 4*0.
 RAV000=0.
 RAV010=0.
 RFM000=5.
 RFM000=3.
 RF000 = 0.
 RFSAP=5.
 RFSAP=5.
 RM20 = 0.
 RM200 = 1.
 RL211 =50.
 RMINES = 0.
 RMF = 10.
 RPA =25.
 RPOWR = 0.6.
 SAMU =4*0.
 SC(1) = 1.7.
 SC(2) = 0.5.
 SC(3) = 1.
 SC(4) = 8.
 SC(5) = 0.04.
 SC(6) = 32.
 SCALE = 50000.
 SOIL1 =0.
 SPEC = 0.
 YB1STR =60.
 YBRNDS =30.
 YBUR = 0.
 YDERK = 4*0.
 YDMIN = 10.
 YHEATA=0.
 YPOMR = 1.5.
 YPREP = 0.
 YTSR =0554.
 YISS =1829.
 YTUSE = 0.5.
 YVEGI =3.
 YVELM =4*100.
 YVH = 6302.
 YVK = 7146.
 YMDAY = 0038.. 0716.. 0760.. 0049.. 0946.. 1346.. 4*1148.. 2045.. 2159.

2310.. 2350.. 0014.. 0110.. 4*156.. 5*0.. 5*1.. 73.. 79.. 69.. 63..
 72.. 4*78.. 51.. 56.. 51.. 47.. 48.. 5*52.. 98.. 97.. 98.. 85..
 98.. 99.. 4*98.. 20.. 23.. 40.. 22.. 20.. 26.. 4*24.. 10*0.. 2.. 1..
 3.. 4.. 2.. 5*1.. 8.. 5.. 12.. 15.. 8.. 5*0.. 3*300.. 030.. 190..
 5*360..

MDC = 0..
 MDM = 0..
 WTC = 1..
 WTM = 1..
 MTS = 4.. 3*0.

XAV000=0..
 XAV010=0..
 XBASE =6345..
 XLZ(1) = 6455..
 XOBINS = 40..
 XMMAX = 6000..

YOB(1,1)=6419.56424.5.6419.5.
 YOB(1,2)=6417.6417.50..
 YOB(1,3)=6419.56424.5.6419.5.
 YPLAN(1,1)=6451.6447.6427.6418.6.6427.6447.6451..
 YAV000=0..
 YAV010=0..

YBASE =7240..
 YLZ(1) = 7284..
 YOB(1,1)=7306.7318.5.7318.5.
 YOB(1,2)=7318.5.7321..
 YOB(1,3)=7306.7318.5.7318.5.
 YPLAN(1,1)=7296.7311.7319.7319.0.7319.7311.7296..

\$NAML3
 IDET =20*0.
 IVEL=20*0..SOUND1=100*0..NMP=2*0..NSTP=20*0.
 IMV(1)= 5. RANMAX(1)= 4000.. FRCMVD(1)= 1.. FRCMVN(1)= 1..
 IVEL(1)= 0.3 . NMP(1)= 1. IFS(1)= 01080000. IYSTOP(1)= 02080000.
 ITIMS(1,1)= 01081600.01092000.
 GOALTX(1,1)=6442..
 GOALTY(1,1)=7341..

IC(1,1)=6392..7301..1.7..5.1..6..04.0..32..
 NSTP(1)= 1. ISSUM(1,1)= 01080000. 01221500.
 ISSOFF(1,1)= 02080000. 01222100. SOUND1(1,1)= 90.. 93..
 RCNINI(1)= 200.. RCNMAX(1)= 1500..

SWT	..4.
CADA	..5.
CARFR	..3.
CI	..3.
CC1	..90..
CC2	..50..
CC3	..50..
CLASS	2.2.1.1.1, 2.2.1.1.1, 1.1.1.1.1, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 0.0.0.0.0, 2.2.2.2.2, 2.2.2.2.2, 2.2.2.2.2, 2.2.2.2.2, 2.2.2.2.2,
OTDAMB	=150..
OTDATT	=120..
OTDFS	=300..
OTENGM	=3600..
OTPURM	=3600..
DMOR	=300..
FRAMB	..7.
FRATT	..9.
GMAX	..3.
GSAPRR	=50..
TOTREC	=1.
IPERM(1,1)	=1.
LDAYS	=4.
NSECT	=6.
NSECTR	=3.
PPI	=1.
PP2	..1.
PP3	..3.
PP4	..5.
PP5	..95.
O1	..33.
O2	..33.
O3	..34.
RAMB	=100..
RAMIN	..6.
RATT	=100..
RFFS	=500..
RURS	=600..
RSP	=10..
RZ	..5.

(4)

SAFDIS=15.
JARTL=1.
MAE(1)=14..12..6..11..5..12..6..11..3..9..8..8..
NSUPP=1.
SIGMDIS=15..
KDEFOP=4.
8

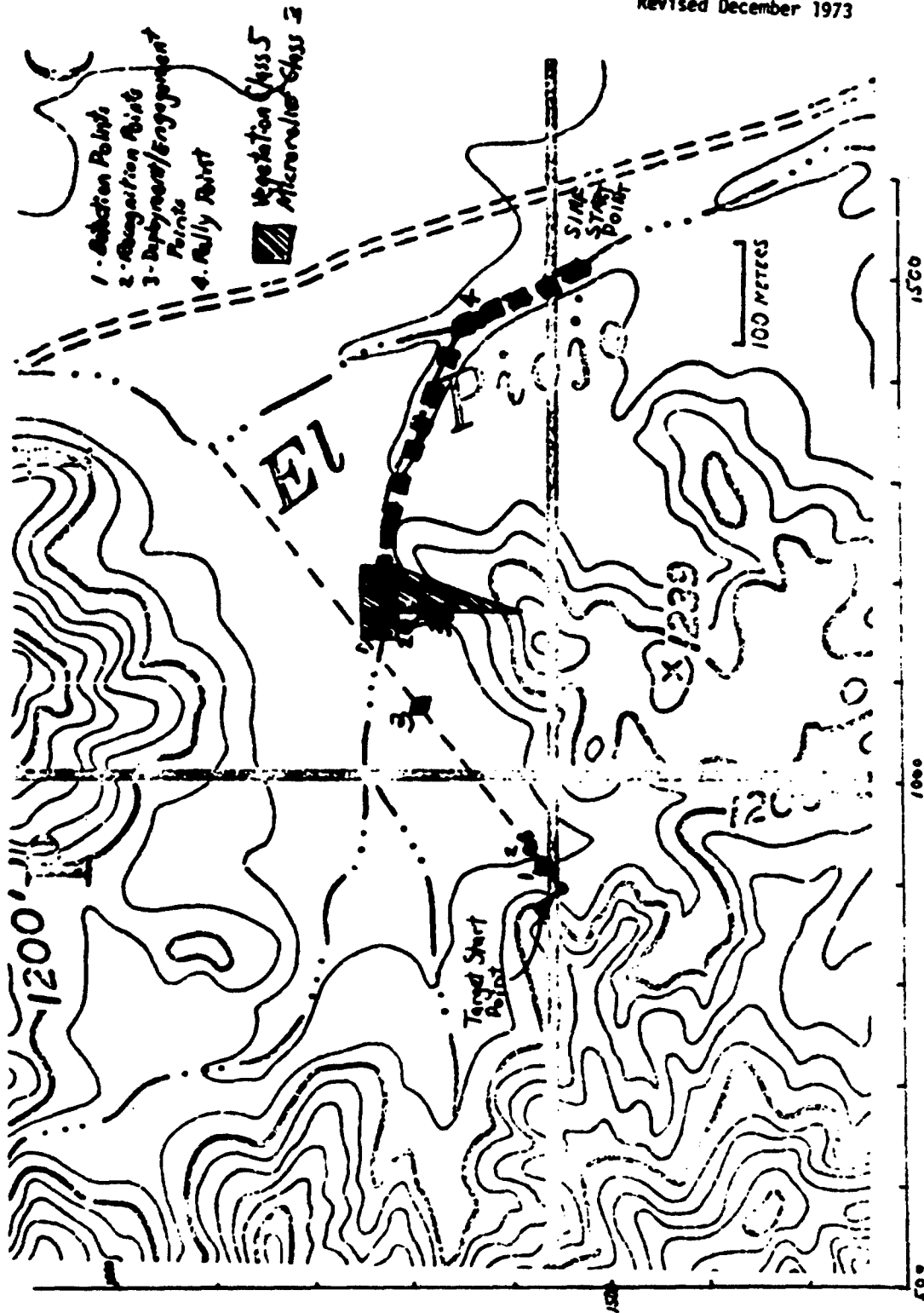


Figure 6.9, Sample Case Diagram

STARTING WITH PERFORMANCE RESOLUTION OF 50.8 METERS

INITIAL TARGET POSITION FOR TARGET NUMBER	I	X	Y	V	TARGET DETECTED:	TIME:	DAYS	HOURS	MINUTES
STAF POSITION: X- 1483.00 Y- 1524.00 XTAR = 900 VTAR = 1550	2					1550.00	01	08	01
STAF POSITION: X- 1473.70 Y- 1553.00 XTAR = 900 VTAR = 1550	2						01	08	02
STAF POSITION: X- 1470.00 Y- 1574.00 XTAR = 500 VTAR = 1550	2						01	08	03
STAF POSITION: X- 1456.51 Y- 1625.00 XTAR = 900 VTAR = 1550	2						01	08	05
STAF POSITION: X- 1450.00 Y- 1650.00 XTAR = 500 VTAR = 1550	2						01	08	06
STAF POSITION: X- 1422.40 Y- 1661.00 XTAR = 500 VTAR = 1550	2						01	08	07
STAF POSITION: X- 1384.00 Y- 1676.00 XTAR = 900 VTAR = 1550	2						01	08	09
STAF POSITION: X- 1371.60 Y- 1681.00 XTAR = 900 VTAR = 1550	2						01	08	09
STAF POSITION: X- 1320.30 Y- 1701.60 XTAR = 900 VTAR = 1550	2						01	08	11
STAF POSITION: X- 1273.00 Y- 1727.00 XTAR = 900 VTAR = 1550	2						01	08	14
STAF POSITION: X- 1257.00 Y- 1727.00 XTAR = 900 VTAR = 1550	2						01	08	14
STAF POSITION: X- 1250.00 Y- 1730.00 XTAR = 900 VTAR = 1550	2						01	08	14
STAF POSITION: X- 1227.00 Y- 1730.00 XTAR = 900 VTAR = 1550	2						01	08	16
STAF POSITION: X- 1209.30 Y- 1730.00 XTAR = 900 VTAR = 1550	2						01	08	16
STAF POSITION: X- 1169.40 Y- 1730.00 XTAR = 517 VTAR = 1504	3						01	08	17
STAF POSITION: X- 1169.40 Y- 1730.00 XTAR = 917 VTAR = 1504	3						01	08	17
STAF POSITION: X- 1169.40 Y- 1730.00 XTAR = 917 VTAR = 1504	1						01	08	17

Figure 6.10. Sample Case Output

TARGET DETECTED DYNAMIC ROUTE TO BEEN RECOGNITION
 X,Y COORDINATES ON EACH MOVEMENT FOR THE LEAD-UP OF THIS MU.
 RELATIVE GRID PLUT

XOYN	YDYN	
1168.39	1733.00	.
1163.08	1703.92	.
1147.39	1693.54	.
1131.69	1683.16	.
1126.39	1657.08	.
1100.31	1662.39	.
1084.62	1652.00	.
1068.93	1641.62	.
1053.24	1631.24	.
1037.54	1620.85	.
1021.85	1610.47	.
1006.16	1600.08	.
990.47	1589.70	.
974.78	1579.31	.
959.09	1568.93	.
943.39	1558.55	.
917.32	1563.85	.

STATISTICS ON ARRIVE DYNAMIC ROUTE
 NUMBER OF POINTS IN THE ROUTE : 17

SIAP POSITION: X- 1167.82 Y- 1727.20 TARGET DETECTED: YES TIME: DAYS-01 HOURS-08 MINUTES-17

X/YAR = 919 Y/YAR = 1565 LOS = 1

SIAP DETECTS TARGET NO. 1 VISUALLY

SIAP POSITION: X- 1163.08 Y- 1703.92 TARGET DETECTED: YES TIME: DAYS-01 HOURS-08 MINUTES-18

X/YAR = 932 Y/YAR = 1576 LOS = 1

SIAP DETECTS TARGET NO. 1 VISUALLY

SIAP RECOGNIZED TARGET NO. 1 AT X- 1163.08 Y- 1703.92 THE RECOGNITION RANGE IS 263.88

DYNAMIC ROUTE TO RETURN TO NEXT CHECK PT IF ORIGINAL ROUTE IS DESIRED
 X,Y COORDINATES ON EACH MOVEMENT FOR THE LEADER OF THIS MU.

XCYN	YCYN	RELATIVE GRID PLOT
1162.08	1703.92	.
1165.04	1705.22	.
1167.00	1706.52	.
1168.96	1707.82	.
1170.92	1709.12	.
1171.26	1710.75	.
1171.59	1712.38	.
1171.92	1714.01	.
1172.25	1715.64	.
1172.58	1717.26	.
1172.91	1718.89	.
1173.25	1720.52	.
1173.58	1722.15	.
1172.28	1724.12	.
1170.98	1726.08	.
1165.68	1728.04	.
1168.39	1730.00	.

STATISTICS ON ABOVE DYNAMIC ROUTE : 17
 NUMBER OF POINTS IN THE ROUTE :

MISSION IS -- AMBUSH OR AVOID

THE COURSE OF ACTION FOR STAFF TO TAKE :

STAFF DECIDES TO COMMIT JN TO AMBUSH

STAFF IS TO BE THE SUBJECT PATROL

DEPLOYMENT POINT X = 1177.1333 Y = 1702.2624

ENGAGEMENT POINT X = 1077.6529 Y = 1592.1268

FOR MANEUVER UNIT NUMBER 1, LOGIC COMPUTES APPROACH PATH

1164 1173 1390

1691 1663 1677

FOR MANEUVER UNIT NUMBER 2, LOGIC COMPUTES APPROACH PATH

1160 1177

1710 1682

ENGAGEMENT POINT 1077.65 1592.13

A 128 BY 64 RECTANGLE HAS BEEN FITTED AT X= 228.60Y= 1591.60

RESOLUTION HAS BEEN CHANGED TO COMBAT LEVEL OF 12.7 METERS

PATROL MEMBER STATISTICS BEFORE COMBAT

ATTACKER PATROL:	PATROL MEMBER								
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(A)	M-79 GL	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	100	100	100	100	0	100	100	100	0
CASUALTY STATUS	NO	NO	MI	NO	M	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1160.48	1163.89	1163.10	1157.86	1195.72	1155.26	1166.12	1161.65	0.00
CURRENT Y (METER)	1716.14	1651.76	1711.84	1720.42	1737.62	1724.66	1686.44	1695.93	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	0.00
MANEUVER UNIT	1	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	0	20	20	20	20	20	20	20	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	G.I.V.M.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0.00
MOVEMENT RATE (P/SEI)	.41	.41	.41	.41	.41	.41	.41	.41	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	0
WEAPON TYPE	APFA	APFA	AREA	AREA	AREA	AREA	AREA	AREA	0
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	1	0
SECONDARY WEAPON AVI	M. GREN.	M. GREN.	M. GREN.	P. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	3	0	3	3	3	3	0

DEFENDER PATROL:

PATROL MEMBER

	1	2	3	4	5	6	7	8	9
WEAPON NUMBER	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47			
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47			
CURRENT AMMO SUPPLY	100	100	100	100	100	100			
CASUALTY STATUS	IC	IC	NI	NI	NI	NI			
FIRING STATUS	ACT	ACT	ACT	ACT	ACT	ACT			
SUPPRESSION STATE	0	0	0	0	0	0			
CURRENT X (METER)	932.55	927.23	939.47	926.10	938.63	929.23			
CURRENT Y (METER)	1575.88	1577.78	1571.97	1583.69	1568.27	1579.78			
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00			
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00			
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70			
WIDTH (METER)	0.50	0.50	0.50	0.50	0.50	0.50			
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND			
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL			
MANEUVER UNIT	1	1	1	1	1	1			
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20			
FUNCTION IN PATROL	P.O.	P.O.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN			
MOVEMENT RATE (M/S)	0.0	0.0	0.0	0.0	0.0	0.0			
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.			
INITIAL AMMO SUPPLY	100	100	100	100	100	100			
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA			
POSIT. IN FILE TEAM	1	2	3	4	5	6			
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE			
NO. OF PAVO GRENADE	0	0	0	0	0	0			
NO. OF SMOKE GRENADE	0	0	0	0	0	0			

DYNAMIC ROUTE FOR ATTACKER M1
X,Y COORDINATES ON EACH MOVEMENT FOR THE LEADER OF THIS MU.

XCYN	YDYN
1163.89	1691.46
1168.58	1677.16
1173.28	1662.86

STATISTICS ON ABOVE DYNAMIC ROUTE
NUMBER OF POINTS IN THE ROUTE : 3

DYNAMIC ROUTE FOR ATTACKER M2
X,Y COORDINATES ON EACH MOVEMENT FOR THE LEADER OF THIS MU.

XCYN	YDYN
1160.48	1715.14
1168.83	1699.29
1177.19	1682.44

STATISTICS ON ABOVE DYNAMIC ROUTE
NUMBER OF POINTS IN THE ROUTE : 3

Task
 SECURITY EXECUTION: F.P.
 TIME MRS. MIN. SEC. POSITION(ATTACKER) EVENT

TIME	MRS.	MIN.	SEC.	POSITION(ATTACKER)	EVENT
1	8	18	31	1164.79	DETECTION
				1588.72	DETECTION
				1688.77	DETECTION
				1712.42	DETECTION
				1577.75	DETECTION
				1685.97	DETECTION
				1709.83	DETECTION
				1579.63	DETECTION
				1685.97	DETECTION
				1683.23	DETECTION
				1707.24	DETECTION
				1581.50	DETECTION
				1583.23	DETECTION
				1683.48	DETECTION
				1704.65	DETECTION
				1583.38	DETECTION
				1680.48	DETECTION
				1679.05	DETECTION
				1703.30	DETECTION
				1584.36	DETECTION
				1679.35	MOVEMENT
				1703.30	MOVEMENT
				1677.19	MOVEMENT
				1701.55	MOVEMENT
				1585.62	MOVEMENT
				1677.19	MOVEMENT
				1701.55	MOVEMENT
				1674.44	MOVEMENT
				1698.96	MOVEMENT
				1587.50	MOVEMENT
				1674.44	MOVEMENT
				1671.7C	MOVEMENT
				1695.77	MOVEMENT

ATTACKER MEMBER: 4 DETECTS DEFENDER MEMBER: 2
 ATTACKER MEMBER: 7 DETECTS DEFENDER MEMBER: 1
 ATTACKER MEMBER: 4 DETECTS DEFENDER MEMBER: 6
 ATTACKER MEMBER: 8 DETECTS DEFENDER MEMBER: 6
 ATTACKER MU 1 WILL MOVE 1.51 METERS AT AN ANGLE OF -71
 ATTACKER MU 2 WILL MOVE 1.51 METERS AT AN ANGLE OF -63
 ATTACKER MU 1 WILL MOVE 1.96 METERS AT AN ANGLE OF -71
 ATTACKER MU 2 WILL MOVE 1.96 METERS AT AN ANGLE OF -63
 ATTACKER MEMBER: 5 DETECTS DEFENDER MEMBER: 5

1	8	19	1170.38	X	949.22	Y	1599.27		
		32	1671.70					DETECTION	
			1171.28	Y	1668.95				ATTACKER MEMBER: 6 DETECTS DEFENDER MEMBER: 4
			1171.56	Y	1693.78				
			951.56	Y	1591.23				
		42	1171.28	Y	1668.95			DETECTION	
			1172.18	Y	1666.21				ATTACKER MEMBER: 3 DETECTS DEFENDER MEMBER: 1
			1172.85	Y	1691.20				
			953.90	Y	1593.12				
		52	1172.18	Y	1666.21			DETECTION	
			1173.08	Y	1663.47				ATTACKER MEMBER: 7 DETECTS DEFENDER MEMBER: 4
			1174.13	Y	1688.61				
			956.24	Y	1594.99				
		2	1173.08	Y	1663.47			DETECTION	
			1173.15	Y	1663.31				ATTACKER MEMBER: 4 DETECTS DEFENDER MEMBER: 5
			1174.20	Y	1688.46				
			956.32	Y	1595.06				
		2	1173.13	Y	1663.31			MOVEMENT	
			1174.20	Y	1688.46				ATTACKER MU 1 WILL MOVE .16 METERS AT AN ANGLE OF -7:
									ATTACKER MU 2 WILL MOVE .16 METERS AT AN ANGLE OF -6:

T
DYNAMIC ROUTE FOR ATTACKER MU 1
X,Y COORDINATES ON EACH MOVEMENT FOR THE LEADER OF THIS MU.

XOYN	YDYN
1173.13	1663.31
1156.54	1665.95
1139.94	1668.59
1125.98	1667.83
1109.39	1690.47
1090.15	1676.51

STATISTICS ON ABOVE DYNAMIC ROUTE
NUMBER OF POINTS IN THE ROUTE : 6

POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1175.49 Y- 1685.87
 POSITION OF DEFENDER MU 1 X- 958.67 Y- 1596.93

1 8 20 12 1173.13 1663.31 DETECTION ATTACKER MEMBER: 6 DETECTS DEFENDER MEMBER: 6
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 960.68 Y- 1598.54

1 8 20 20 1173.13 1663.31 MOVEMENT ATTACKER MU 1 WILL MOVE 0.00 METERS AT AN ANGLE OF -71
 1 8 20 20 1177.04 1682.74 MOVEMENT ATTACKER MU 2 WILL MOVE 3.49 METERS AT AN ANGLE OF -6:
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 963.02 Y- 1600.42

1 8 20 30 1173.13 1663.31 DETECTION ATTACKER MEMBER: 7 DETECTS DEFENDER MEMBER: 3
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 965.36 Y- 1602.29

1 8 20 40 1173.13 1663.31 DETECTION ATTACKER MEMBER: 4 DETECTS DEFENDER MEMBER: 6
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 967.71 Y- 1604.17

1 8 20 50 1173.13 1663.31 DETECTION ATTACKER MEMBER: 1 DETECTS DEFENDER MEMBER: 6
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 970.05 Y- 1606.04

1 8 21 0 1173.13 1663.31 DETECTION ATTACKER MEMBER: 1 DETECTS DEFENDER MEMBER: 6
 POSITION OF ATTACKER MU 1 X- 1173.13 Y- 1663.31
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 972.39 Y- 1607.91

1 8 21 10 1173.13 1663.31 DETECTION ATTACKER MEMBER: 7 DETECTS DEFENDER MEMBER: 2

POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	974.73	Y-	1607.74				
	1	20	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 5 DETECTS DEFENDER MEMBER: 5
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	977.08	Y-	1611.66				
	1	30	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 5 DETECTS DEFENDER MEMBER: 1
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	979.42	Y-	1613.54				
	1	40	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 5 DETECTS DEFENDER MEMBER: 6
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	981.76	Y-	1615.41				
	1	50	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 7 DETECTS DEFENDER MEMBER: 4
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	984.10	Y-	1617.28				
	1	60	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 8 DETECTS DEFENDER MEMBER: 5
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	986.45	Y-	1619.16				
	1	70	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 3 DETECTS DEFENDER MEMBER: 5
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	984.74	Y-	1621.03				
	1	80	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 8 DETECTS DEFENDER MEMBER: 1
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	991.13	Y-	1624.91				
	1	90	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 8 DETECTS DEFENDER MEMBER: 6
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	993.43	Y-	1624.74				
	1	100	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 5 DETECTS DEFENDER MEMBER: 4
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	995.01	Y-	1624.86				
	1	110	1173.13	1663.31	DEFLECTION				ATTACKER MEMBER: 4 DETECTS DEFENDER MEMBER: 1
POSITION OF ATTACKER	MU 1	X-	1173.13	Y-	1603.31				
POSITION OF ATTACKER	MU 2	X-	1177.04	Y-	1682.74				
POSITION OF DEFENDER	MU 1	X-	997.01	Y-	1624.91				
	1	120	1173.13	1663.31	DEFLECTION				

POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	
POSITION OF ATTACKER MU 2	X-1177.04	V-1682.74	
POSITION OF DEFENDER MU 1	X-1024.87	V-1649.89	
1	8	24	54
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	25	6
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1029.55	V-1631.64	
1	8	25	14
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	25	24
POSITION OF ATTACKER MU 1	X-1031.89	V-1655.52	
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	
POSITION OF ATTACKER MU 2	X-1177.04	V-1682.74	
POSITION OF DEFENDER MU 1	X-1034.24	V-1657.39	
1	8	25	34
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	25	46
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	25	56
POSITION OF ATTACKER MU 1	X-1039.39	V-1661.51	
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	
POSITION OF ATTACKER MU 2	X-1177.04	V-1682.74	
POSITION OF DEFENDER MU 1	X-1041.73	V-1643.39	
1	8	25	6
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	26	16
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1044.08	V-1685.26	
1	8	26	26
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	
POSITION OF DEFENDER MU 2	X-1177.04	V-1682.74	
1	8	26	26
POSITION OF ATTACKER MU 1	X-1045.42	V-1667.12	
POSITION OF DEFENDER MU 1	X-1173.13	V-1663.31	DETECTION
POSITION OF ATTACKER MU 1	X-1173.13	V-1663.31	
POSITION OF ATTACKER MU 2	X-1177.04	V-1682.74	

ATTACKER MEMBERS: 2 DETECTS OFFENDER MEMBERS: 4

ATTACKER MEMBERS: 5 DETECTS DEFENDER MEMBERS: 3

ATTACKER MEMBERS: 3 DETECTS DEFENDER MEMBERS: 4

ATTACKER MEMBERS: 5 DETECTS DEFENDER MEMBERS: 4

ATTACKER MEMBERS: 7 DETECTS DEFENDER MEMBERS: 4

ATTACKER MEMBERS: 1 DETECTS DEFENDER MEMBERS: 4

ATTACKER MEMBERS: 3 DETECTS DEFENDER MEMBERS: 6

ATTACKER MEMBERS: 5 DETECTS DEFENDER MEMBERS: 5

ATTACKER MEMBERS: 4 DETECTS DEFENDER MEMBERS: 3

ATTACKER MEMBERS: 1 DETECTS DEFENDER MEMBERS: 4

1	0	26	30	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 3	DETECTS DEFENDER MEMBER: 3
				1173.13	1663.31	DETECTION		
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1051.10	1670.88	DETECTION		
1	0	26	46	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 3	DETECTS DEFENDER MEMBER: 4
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1053.45	1672.76	DETECTION		
1	0	26	56	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 6	DETECTS DEFENDER MEMBER: 5
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1055.79	1674.63	DETECTION		
1	0	27	6	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 4	DETECTS DEFENDER MEMBER: 6
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1058.13	1676.91	DETECTION		
1	0	27	16	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 7	DETECTS DEFENDER MEMBER: 6
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1060.47	1678.38	DETECTION		
1	0	27	26	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 1	DETECTS DEFENDER MEMBER: 5
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1063.82	1680.23	DETECTION		
1	0	27	36	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 1	DETECTS DEFENDER MEMBER: 6
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1065.16	1682.13	DETECTION		
1	0	27	46	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 6	DETECTS DEFENDER MEMBER: 3
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1067.50	1684.00	DETECTION		
1	0	27	56	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 3	DETECTS DEFENDER MEMBER: 5
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1069.84	1685.88	DETECTION		
1	0	28	5	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 6	DETECTS DEFENDER MEMBER: 1
				1173.13	1663.31	DETECTION		
				1177.04	1682.74	DETECTION		
				1072.19	1687.75	DETECTION		
1	0	28	15	1173.13	1663.31	DETECTION	ATTACKER MEMBER: 7	DETECTS DEFENDER MEMBER: 5

POSITION OF ATTACKER MU 1 A- 1173.12 V- 1663.31
POSITION OF ATTACKER MU 2 A- 1177.04 V- 1682.74
POSITION OF DEFENDER MU 1 V- 1074.97 V- 1689.57
1 8 28 29 1173.13 1663.31 DIRECTION
POSITION OF ATTACKER MU 1 A- 1173.13 V- 1663.31
POSITION OF DEFENDER MU 2 A- 1177.04 V- 1682.74
POSITION OF DEFENDER MU 1 A- 1074.97 V- 1689.57

ATTACKER MEMBERS & DETECTS. DEFENDER MEMBERS &

1 6 28 27 CASUALTY EVENT
DEFENDER PATROL SUSTAINS THE NEXT CASUALTY
THE NUMBER OF THE CASUALTY MEMBER IS : 5
THE TYPE OF CASUALTY IS : MIA, WOUND
TIME(SEC) THAT COMBAT OPERATION WAS BEEN UNDERWAY: 1.8720
POSITION OF ATTACKER M1 X- 1175.13 Y- 1663.31
POSITION OF ATTACKER M1 X- 1172.37 Y- 1663.43
POSITION OF ATTACKER M1 X- 1177.04 Y- 1682.74
POSITION OF DEFENDER M1 X- 1075.30 Y- 1690.24

1 8 28 29 CASUALTY EVENT
DEFENDER PATROL SUSTAINS THE NEXT CASUALTY
THE NUMBER OF THE CASUALTY MEMBER IS : 2
THE TYPE OF CASUALTY IS : MIA, WOUND
TIME(SEC) THAT COMBAT OPERATION WAS BEEN UNDERWAY: 3.2854
POSITION : X- 1172.37 Y- 1663.43

DEFENDER PATRIOT

	1	2	3	4	5	6	7	8	9
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY	100	100	100	100	100	100	100	100	100
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1078.42	1078.18	1078.42	1078.42	1078.42	1078.42	1078.42	1078.42	1078.42
CURRENT Y (METER)	1694.14	1694.14	1694.14	1694.14	1694.14	1694.14	1694.14	1694.14	1694.14
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50
CURRENT POSTURE	STAND	PRONE	STAND	STAND	STAND	STAND	STAND	STAND	STAND
MOVING STATUS	NORMAL	STOPPED	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL
MANEUVER UNIT	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (M50)	20	20	20	20	20	20	20	20	20
FUNCTION IN PATROL	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
MOVEMENT RATE (M/S)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSIT. IN FIRE TEAM	1	2	3	4	5	6	7	8	9
SECONDARY WEAPON AVI	0	0	0	0	0	0	0	0	0
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMORE GRENADE	0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION
 DEFENDER SPEAKS. WITHDRAWAL ANGLE = 3.0163
 POSITION OF ATTACKER : A- 1171.53 Y- 1663.56
 POSITION OF ATTACKER : A- 1177.00 Y- 1642.74
 POSITION OF DEFENDER : A- 1078.42 Y- 1694.14

1 29 29 CASUALTY EVENT
DEFENDER PATROL SUSTAINS THE NEXT CASUALTY
THE NUMBER OF THE CASUALTY MEMBER IS 3
THE TYPE OF CASUALTY IS : DEATH
TIME(SEC) THAT COMBAT OPERATION HAS BEEN UNDERWAY 0.0025
POSITION : X- 1171.53 Y- 1603.56

ATTRIBUTE TABLE (ATT) CASUALTY SUSTAINED

ATTACKER DETAILS:

	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	2	3	4	5	6	7	8	9
WEAPON TYPE	4-10(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	97	97	97	97	97	97	97	97	97
CASUALTY STATUS	AL	NJ	NJ	NJ	NJ	NJ	NJ	NJ	NJ
FIRING STATUS	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT
SUPPRESSION STATUS	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1177.07	1171.53	1170.36	1177.57	1175.73	1175.10	1170.24	1172.93	0.00
CURRENT Y (METER)	1665.74	1663.56	1670.64	1687.56	1674.72	1692.39	1658.64	1669.22	0.00
NEXT X (METER)	1177.19	1155.54	1170.70	1177.67	1175.22	1175.10	1158.20	1154.87	0.00
NEXT Y (METER)	1682.44	1653.35	1677.65	1687.41	1672.43	1692.39	1661.24	1670.66	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	0.00
MANEUVER UNIT	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	0.00
ROUNDS REMAIN (MIG.)	17	17	17	17	17	17	17	17	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	P.GUNNER	GR.LNCP.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
MOVEMENT RATE (M/SEC)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	C
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	C
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	H. GREN.	H. GREN.	F. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER PATROL:	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
WEAPON TYPE	99	100	100	99	100	100	100	100	100
CURRENT AMMO SUPPLY	NO MA	BOUND	DEAD	NU	MI	MI	MI	MI	MI
CASUALTY STATUS	100%	100%	100%	100%	100%	100%	100%	100%	100%
FIRING STATUS	100%	100%	100%	100%	100%	100%	100%	100%	100%
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METERS)	1074.93	1072.18	1070.25	1068.68	1061.18	1071.81	1071.81	1071.81	1071.81
CURRENT Y (METERS)	1659.94	1694.14	1696.04	1697.75	1682.14	1693.05	1693.05	1693.05	1693.05
NEXT X (METERS)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METERS)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METERS)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METERS)	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50
CURRENT POSTURE	STAND	PRONE	PRONE	STAND	STAND	STAND	STAND	STAND	STAND
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT	1	1	1	1	1	1	1	1	1
ROUNDS REPAIR (MAG.)	19	20	23	19	20	20	20	20	20
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSIT. IN FIRE TEAM	1	2	3	4	5	6	7	8	9
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0

AREAS DECISION: DEFENSE - BREAKS CONTACT DUE TO HIGH CASUALTY FRAGMENT
 POSITION OF ATTACK: X=1170.82 Y=1651.68
 POSITION OF ATTACK: X=1177.00 Y=1682.74
 POSITION OF DEFENSE: X=1074.93 Y=1659.94

20660-6002-R0-00

Page 6-172

Revised December 1973

1. THE NUMBER OF CASUALTY REPORTS
DEFENSE PATROL REPORTS TO STATE CASUALTY
THE NUMBER OF THE CASUALTY REPORTS IS : 1
THE TYPE OF CASUALTY IS : ROAD BLOCK
TIMES-OF THAT CASUALTY HAS BEEN JACKETED : 0.1054
POSITION : X-117.00 Y-1001.03

ATTRIBUTIVE TABLE AFTER CASUALTY SUSTAINED

ATTACKER	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(A)	M-79	GL M-16(SA)	M-16(SA)	M-16(SA)	
CURRENT AMMO SUPPLY	96	96	96	89	2	2	96	96	0
CASUALTY STATUS	NC	NC	NC	NO	NO	NO	NC	NO	0
FIRING STATUS	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT	0
SUPPRESSION STATE	0	0	0	0	0	5	0	0	0
CURRENT X (METER)	1177.04	1170.82	1176.36	1177.57	1175.73	1178.16	1169.54	1172.22	0.00
CURRENT Y (METER)	1682.74	1663.68	1678.44	1687.58	1676.72	1692.39	1658.60	1668.31	0.00
NEXT X (METER)	1177.19	1156.54	1176.73	1177.67	1176.22	1178.16	1158.23	1154.87	0.00
NEXT Y (METER)	1682.44	1665.95	1677.46	1687.41	1672.48	1692.39	1661.24	1670.60	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	
MOVING STATUS	STOPPED	NORMAL	STOPPED	STOPPED	STOPPED	STOPPED	NORMAL	NORMAL	
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (%G.)	16	16	16	8	16	16	16	16	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GA.L.N.C.H.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
MOVEMENT RATE (M/SEC)	0.00	.54	0.00	0.00	0.00	0.00	.54	.54	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT BASE FR.	JASE FR.	JASE FR.	JASE FR.	JASE FR.	P. UNIT	M. UNIT	
INITIAL AMMO SUPPLY	130	100	100	100	6	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	M. GREN.	M. GREN.	M. GREN.	P. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	0
NO. OF P.M.C. GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER	PATROL	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER		1	2	3	4	5	6	7	8	9
WEAPON TYPE		AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY		100	100	100	100	100	100	100	100	100
CASUALTY STATUS		0	0	0	0	0	0	0	0	0
FIRING STATUS		0	0	0	0	0	0	0	0	0
SUPPRESSION STATE		0	0	0	0	0	0	0	0	0
CURRENT X (METERS)		1074.52	1072.16	1074.05	1063.37	1083.87	1071.50	1071.50	1071.50	1071.50
CURRENT Y (METERS)		1689.70	1694.14	1686.04	1697.50	1681.89	1693.00	1693.00	1693.00	1693.00
NEXT X (METERS)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METERS)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METERS)		1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METERS)		0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50
CURRENT POSTURE		PRUNE	PRUNE	PRUNE	STAND	STAND	STAND	STAND	STAND	STAND
MOVING STATUS		STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT		1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (MAG.)		19	20	20	18	20	20	20	20	20
FUNCTION IN PATROL		P-1	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)		0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30
INDIV. ASSIGNMENT		BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY		100	100	100	100	100	100	100	100	100
WEAPON TYPE		AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSIT. IN FIRE TEAM		1	2	3	4	5	6	6	6	6
SECONDARY WEAPON AVAIL		0	0	0	0	0	0	0	0	0
NO. OF PANC GRENADE		0	0	0	0	0	0	0	0	0
NO. OF SPOKE GRENADE		0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION

POSITION OF ATTACKER YU 1 X- 1109.97 Y- 1663.81

POSITION OF ATTACKER YU 2 X- 1177.05 Y- 1682.74

POSITION OF DEFENDER YU 1 X- 1074.63 Y- 1689.70

1. H 2A 21 CASUALTY EVENT
DEFENDER PATROL SUSPENS THE NEXT CASUALTY
THE NUMBER OF THE CASUALTY NUMBER IS : 6
THE TYPE OF CASUALTY IS : DEATH
TIMESPEC THAT CASUALTY OPERATION HAS BEEN UNDERWAY : 7.7777
POSITION : X- 1197.97 Y- 1663.81

ATTACHED TO THE UNIT'S CASUALTY SCHEDULE

ATTACKER PATRIOT	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	75	95	95	45	45	95	95	95	95
CASUALTY STATUS	NO	NO	NI	NI	NI	NO	NI	NI	NI
FIPING STATUS	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT
SUPPRESSION STA-	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1177.04	1167.97	1176.35	1177.57	1175.72	1178.16	1168.70	1171.26	0.00
CURRENT Y (METER)	1092.74	1061.81	1075.44	1067.70	1074.72	1092.39	1098.80	1098.43	0.00
NEXT X (METER)	1177.19	1175.54	1176.70	1177.07	1175.22	1178.15	1158.20	1157.87	0.00
NEXT Y (METER)	1092.64	1067.95	1077.66	1077.01	1072.48	1092.39	1061.24	1073.65	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAFF	STAND	STAND	STAND	STAND	STAND	STAND	STAND	
MOVING STATUS	STOPPED	NORMAL	STOPPED	STOPPED	STOPPED	STOPPED	NORMAL	NORMAL	
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	15	15	15	5	15	15	15	15	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	QU. LNC.	RIFLEMAN	RIFLEMAN	RIFLEMAN	
MOVEMENT RATE (M/SEC)	0.00	.54	0.00	0.00	0.00	0.00	.24	.54	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POST. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

OFFENSE PATROL	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY	100	100	100	100	100	100	100	100	100
CASUALTY STATUS	MA. BOUND	MA. BOUND	DEAD	DEAD	MI. WOUND	DEAD	DEAD	DEAD	DEAD
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1074.62	1072.18	1070.05	1068.00	1060.47	1071.12	1071.12	1071.12	1071.12
CURRENT Y (METER)	1689.70	1696.14	1686.04	1697.21	1581.50	1693.30	1693.30	1693.30	1693.30
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	STAND	STAND	PRONE	PRONE	PRONE
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	TOP SP.	TOP SP.	STOPPED	STOPPED	STOPPED
MANEUVER UNIT	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (450.)	10	20	20	18	20	20	20	20	20
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/S)	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSIT. IN FIRE TEAM	1	2	3	4	5	6	7	8	9
SECONDARY WEAPON AVI	PRONE	PRONE	NCNE	NCNE	NCNE	NCNE	NCNE	NCNE	NCNE
NO. OF PAVE GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0

BREAK DECISION : OFFENSE BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : OFFENSE BREAKS CONTACT DUE TO HIGH CASUALTY RATIO

POSITION OF ATTACK : U : 1074.62 Y : 1689.70

POSITION OF ATTACK : U : 1072.18 Y : 1696.14

POSITION OF ATTACK : U : 1070.05 Y : 1686.04

POSITION OF ATTACK : U : 1068.00 Y : 1697.21

POSITION OF ATTACK : U : 1060.47 Y : 1581.50

POSITION OF ATTACK : U : 1071.12 Y : 1693.30

POSITION OF ATTACK : U : 1071.12 Y : 1693.30

POSITION OF ATTACK : U : 1071.12 Y : 1693.30

POSITION OF ATTACK : U : 1071.12 Y : 1693.30

20660-6002-R0-00

Page 6-178

Revised December 1973

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100

DEFENSE PAYROLL SUSTAINS THE BATT CASUALTY
THE NUMBER OF THE CASUALTY NUMBER IS 4
THE TYPE OF CASUALTY IS 2 DEATH
TIME(S) THAT COMBAT OPERATION HAS BEEN UNDERWAY
POSITION: X- 1103.30 Y- 1003.57

9.6705

ATTRIBUTABLE TABLE AFTER CASUALTY SUSTAINED

	ATTACKER PATROL:				PATROL MEMBER				
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	
CURRENT AMMO SUPPLY	94	94	94	82	0	94	94	94	0
CASUALTY STATUS	NC	NO	NO	NO	NO	NO	NO	NO	
FIRING STATUS	POINT	POINT	POINT	POINT	POINT	POINT	POINT	POINT	
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1177.04	1168.96	1176.36	1177.57	1179.73	1178.16	1167.70	1170.35	0.00
CURRENT Y (METER)	1682.74	1663.97	1676.44	1687.56	1676.72	1692.39	1659.03	1688.57	0.00
NEXT X (METER)	1177.19	1150.54	1176.70	1177.67	1176.22	1176.16	1158.20	1154.87	0.00
NEXT Y (METER)	1682.44	1665.95	1677.46	1687.61	1672.68	1692.39	1661.24	1670.66	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	
MOVING STATUS	STOPPED	NORMAL	STOPPED	STOPPED	STOPPED	STOPPED	NORMAL	NORMAL	
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REPAIR (43.G.)	14	14	14	2	0	14	14	14	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.L.M.C.	RIFLEMAN	RIFLEMAN	RIFLEMAN	
MOVEMENT RATE (M/SEC)	0.00	.54	0.00	0.00	0.00	0.00	.54	.54	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	
INITIAL AMMO SUPPLY	100	100	100	100	4	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON	M. GREN.	M. GREN.	H. GREN.	F. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER	PATROL	1	2	3	4	5	6	7	8	9
PATROL MEMBERS										
FIRE TEAM NUMBER		1	1	1	1	1	1	1	1	1
WEAPON TYPE		AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY		94	100	100	100	100	100	100	100	100
CASUALTY STATUS		WOUND	WOUND	DEAD	DEAD	WOUND	DEAD	DEAD	DEAD	DEAD
FIRING STATUS		NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE		0	0	0	0	0	0	0	0	0
CURRENT X (METER)		1074.62	1072.18	1078.05	1067.56	1080.05	1071.12	0.00	0.00	0.00
CURRENT Y (METER)		1689.70	1694.14	1686.04	1696.85	1681.23	1693.30	0.00	0.00	0.00
NEXT X (METER)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)		1.70	1.70	1.70	1.70	1.70	1.70	0.00	0.00	0.00
WIDTH (METER)		.50	.50	.50	.50	.50	.50	0.00	0.00	0.00
CURRENT PCSTURE		STOPPED	PRONE	STOPPED	PRONE	STOPPED	PRONE	STOPPED	PRONE	STOPPED
MOVING STATUS		1	1	1	1	1	1	1	1	1
MANEUVER UNIT		19	20	20	18	20	20	20	20	20
ROUNDS REMAIN (MAJ.)		P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
FUNCTION IN PATROL		.30	.30	.30	.30	.30	.30	.30	.30	.30
MOVEMENT RATE (M/SEC)		BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
TMOTV. ASSIGNMENT		100	100	100	100	100	100	100	100	100
INITIAL AMMO SUPPLY		AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
WEAPON TYPE		1	2	3	4	5	6	6	6	6
POSTY. IN FIRE TEAM		NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
SECONDARY WEAPON AVI		0	0	0	0	0	0	0	0	0
NO. OF P-AND GRENADE		0	0	0	0	0	0	0	0	0
NO. OF SCORE GRENADE		0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION
 POSITION OF ATTACKER MU 1 X- 1159.33 Y- 1665.50
 POSITION OF ATTACKER MU 2 X- 1177.04 Y- 1682.74
 POSITION OF DEFENDER MU 1 X- 1074.62 Y- 1689.70
 1 8 24 49 1159.33 1665.53 MOVEMENT ATTACKER MU 1 WILL MOVE 9.75 METERS AT AN ANGLE OF 171
 1 8 28 49 1177.04 1682.74 MOVEMENT ATTACKER MU 2 WILL MOVE 3.00 METERS AT AN ANGLE OF -63

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION

POSITION OF ATTACKER MU 1 X- 1159.33 Y- 1665.50

POSITION OF DEFENDER MU 1 X- 1074.62 Y- 1689.70

POSITION OF DEFENDER MU 3 X- 1072.18 Y- 1696.14

1 0 29 9 NO EVENTS IN 20 SECONDS.

BREAK DECISION : ATTACKER BREAKS CONTACT DUE TO EXCESSIVE ELAPSED TIME(FIGHT)

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION

IC FOR BREAK CONTACT-AVAILABLE

STAFF RALLY POINT 1466.2427 1626.8864

ATTACKER WITHDRAWAL ROUTES

1159.33 1466.24

1665.50 1626.89

1177.04 1466.74

1682.74 1626.89

POSITION OF ATTACKER MU 1 X- 1180.83 Y- 1682.80

POSITION OF ATTACKER MU 2 X- 1195.12 Y- 1679.25

POSITION OF DEFENDER MU 1 X- 1074.62 Y- 1689.70

1 4 33 46 1451.55 1628.73 MOVEMENT ATTACKER MU 1 WILL MOVE 19.36 METERS AT AN ANGLE OF -11

1 5 31 42 1405.22 1576.19 MOVEMENT ATTACKER MU 2 WILL MOVE 19.36 METERS AT AN ANGLE UP -11

RESOLUTION HAS BEEN ENTERED BACK TO THE RECONNAISSANCE LEVEL OF 5000 METERS

DECISION ON CONTINUITY OF RECONNAISSANCE MISSION AFTER CONTACT OPERATION IS COMPLETED :

MISSION DECISION : CONTINUE

CURRENT AMOUNT OF FUEL AVAILABLE FOR THIS MISSION : 13.6442

CURRENT AMOUNT OF WATER AVAILABLE FOR MISSION : 0.3354

PATROL DURATION (DAYS) :

PATROL MEMBER STATISTICS AFTER COMBAT

ATTACKER PATROL:

	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-79	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	94	94	94	94	0	94	94	94	0
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1466.22	1451.55	1465.41	1466.79	1449.55	1467.40	1453.58	1452.97	0
CURRENT Y (METER)	1626.89	1628.73	1621.96	1631.87	1617.03	1636.84	1623.47	1633.57	0.00
NEXT X (METER)	1466.24	1466.24	1465.41	1467.07	1464.54	1467.90	1465.41	1467.07	0.00
NEXT Y (METER)	1626.89	1626.89	1621.96	1631.82	1617.02	1636.75	1621.96	1631.82	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
MOVING STATUS	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND
MANEUVER UNIT	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.
ROUNDS REMAIN (MAG.)	2	1	2	2	2	2	2	2	2
FUNCTION IN PATROL	14	14	14	14	0	14	14	14	0
MOVEMENT RATE (M/SEC)	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.LMCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
INDIV. ASSIGNMENT	1.08	1.08	1.08	1.08	1.08	1.08	1.08	1.08	0.00
INITIAL AMMO SUPPLY	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	0.00
WEAPON TYPE	100	100	100	100	6	100	100	100	0
POSIT. IN FIRE TEAM	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	0
SECONDARY WEAPON AVI	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	1	0	0	0	0	0	0	0

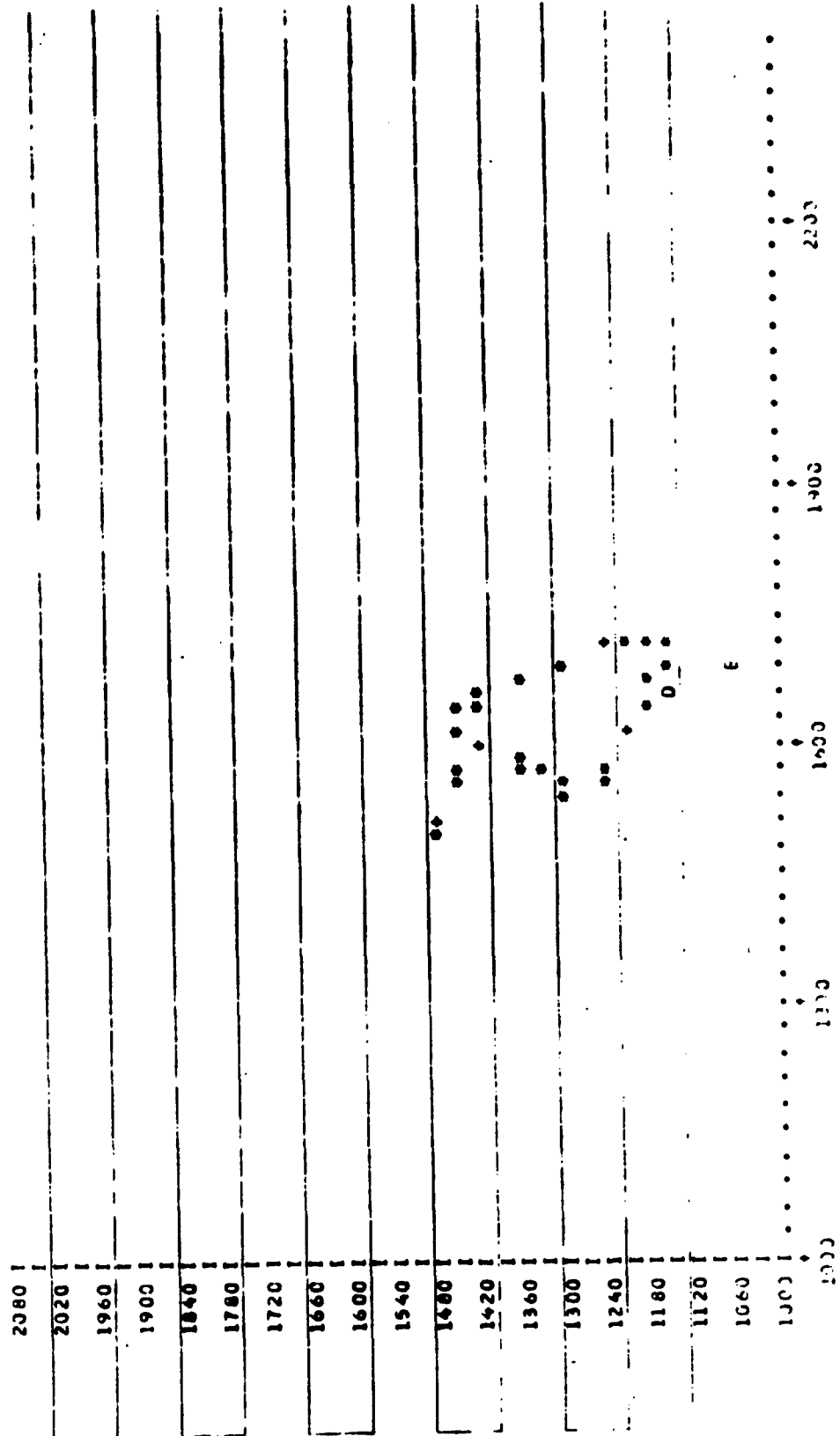
DEFENDER PATROL: PATROL MEMBER

	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	0
CURRENT AMMO SUPPLY	94	100	100	98	100	100	100	100	0
CASUALTY STATUS	MA.WOUND	MA.WOUND	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD	0
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	0
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1074.62	1072.16	1078.05	1067.36	1066.05	1071.12	1071.12	1071.12	0.00
CURRENT Y (METER)	1669.70	1694.14	1686.04	1696.89	1622.04	1693.30	1693.30	1693.30	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	STAND	PRONE	PRONE	PRONE	0.00
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	TOP SP.	STOPPED	STOPPED	STOPPED	0
MANEUVER UNIT	1	1	1	1	1	1	1	1	0
ROUNDS REMAIN (MAG.)	19	20	20	18	20	20	20	20	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
MOVEMENT RATE (M/SEC)	.50	.30	.30	.30	.30	.30	.30	.30	0.00
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	0.00
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	0
POSTY. IN FIRE TEAM	1	2	3	4	5	6	6	6	0
SECONDARY WEAPON AVI	NONE	NONE	NCME	NCME	NONE	NONE	NONE	NONE	0
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0

STAF POSITION: X- 1456.51 Y- 1625.5J TARGET DETECTED: NO TIME: DAYS-01 HOURS-09 MINUTES-01
YVAR = 932 YVAR = 1576 LOS = 1
STAF DETECTS TARGET NO. 1 VISUALLY
STAF POSITION: X- 1470.05 Y- 1574.80 TARGET DETECTED: NO TIME: DAYS-01 HOURS-09 MINUTES-03
YVAR = 932 YVAR = 1576 LOS = 1
STAF DETECTS TARGET NO. 1 VISUALLY
STAF POSITION: X- 1473.20 Y- 1563.00 TARGET DETECTED: NO TIME: DAYS-01 HOURS-09 MINUTES-03
YVAR = 932 YVAR = 1576 LOS = 1

STAF POSITION: X- 1483.60 Y- 1524.00 TARGET DETECTED: NO TIME: DAYS-01 HOURS-09 MINUTES-09
YVAR = 932 YVAR = 1576 LOS = 1
STAF DETECTS TARGET NO. 1 VISUALLY
STAF POSITION: X- 1490.00 Y- 1500.00 TARGET DETECTED: NO TIME: DAYS-01 HOURS-09 MINUTES-06
YVAR = 932 YVAR = 1576 LOS = 1

TIME MOVEMENT PLOT FOR SIAP



SIAF SURVEILLANCE STATISTICS (PAGE 1)
HUNTER LEGGETT SCENARIO I
1 REPLICATIONS

UNATED VISUAL DETECTION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER 1

NUMBER OF DETECTIONS 1

DETECTION SUCCESS RATIO 1.000

DETECTION RANGE (METERS)
MEAN 301.064
STANDARD DEVIATION 0.000

DETECTION TIME (DAYS, HRS, MINS)
MEAN 010817
STANDARD DEVIATION 000000

DETECTION CUES
AURAL 0
SENSOR

IDENTIFICATION STATISTICS OF THE TARGETS BY SIAF

TARGET NUMBER 1

NUMBER OF IDENTIFICATIONS 1

IDENTIFICATION SUCCESS RATIO 1.000

IDENTIFICATION RANGE (METERS)
MEAN 263.076
STANDARD DEVIATION 0.000

IDENTIFICATION TIME (DAYS, HRS, MINS)
MEAN 010818
STANDARD DEVIATION 000000

SIAP SURVEILLANCE STATISTICS (PAGE 2)
HUKTER LIGGETT SCENARIO 1
1 REPLICATIONS

AURAL DETECTION STATISTICS OF THE TARGETS BY SIAP

TARGET NUMBER 1
NUMBER OF DETECTIONS 0
DETECTION SUCCESS RATIO 0.000

DETECTION RANGE (METERS)
MEAN 0.000
STANDARD DEVIATION 0.000

DETECTION TIME (DAYS, HRS, MINS)
MEAN 000000
STANDARD DEVIATION 000000

TARGET LOCATION STATISTICS

TARGET NUMBER 1
TARGET LOCATION (SP (METERS))
MEAN 43.287
STANDARD DEVIATION 0.000

SLAF/TARGET SURVEILLANCE STATISTICS (PAGE 5)
HUNTER LIGHT SCENARIO I
1 REPLICATIONS

CAUSES OF NO DETECTION FOR SLAF (PERCENT)

TARGET NUMBER	1
MASKING BY RELIEF	90.000
MASKING BY VEGETATION	10.000
RANGE AND LIGHT LEVEL	0.000
INSUFFICIENT TIME	0.000

CAUSES OF NO DETECTION FOR TARGETS (PERCENT)

TARGET NUMBER	1
MASKING BY RELIEF	90.000
MASKING BY VEGETATION	10.000
RANGE AND LIGHT LEVEL	0.000
INSUFFICIENT TIME	0.000

SIAF MOVEMENT STATISTICS (PAGE 6)
 MONTE CARLO SCENARIO I
 1 REPLICATIONS

MOVEMENT RATE (KM/HR)

MEAN 1.645
 STANDARD DEVIATION .184

PATROL DURATION (DAYS:HR:MIN)

MEAN 010906
 STANDARD DEVIATION 000000

DISTANCE TRAVELLED (KM)

MEAN 1.356
 STANDARD DEVIATION 0.000

MOVEMENT RATE HISTOGRAM (KM/HR)

PERCENT TIME BETWEEN 0.000 - 0.200 KM/HR =	0.000
PERCENT TIME BETWEEN 0.200 - 0.400 KM/HR =	0.000
PERCENT TIME BETWEEN 0.400 - 0.600 KM/HR =	0.000
PERCENT TIME BETWEEN 0.600 - 0.800 KM/HR =	0.000
PERCENT TIME BETWEEN 0.800 - 1.000 KM/HR =	0.000
PERCENT TIME BETWEEN 1.000 - 1.200 KM/HR =	0.000
PERCENT TIME BETWEEN 1.200 - 1.400 KM/HR =	0.000
PERCENT TIME BETWEEN 1.400 - 1.600 KM/HR =	.596
PERCENT TIME BETWEEN 1.600 - 1.800 KM/HR =	.081
PERCENT TIME BETWEEN 1.800 - 2.000 KM/HR =	.323
PERCENT TIME BETWEEN 2.000 - 2.200 KM/HR =	0.000
PERCENT TIME BETWEEN 2.200 - 2.400 KM/HR =	0.000

SIAF NAVIGATION STATISTICS (PAGE 7)
HUNTER LIGGETT SCENARIO 1
1 REPLICATIONS

PATROL CEP AT CHECKPOINTS (METERS)

MEAN 41.515
STANDARD DEVIATION 12.050

TIME TO DETERMINE LOCATION (MIN)

MEAN .750
STANDARD DEVIATION 0.000

SIAF INSERTION STATISTICS

INSERTION ATTEMPTS 1

NUMBER OF SUCCESSFUL INSERTIONS 1

NUMBER OF INSERTIONS AT PRIMARY LZ 1

NUMBER OF INSERTIONS AT SEC. LZS 0

INSERTION TIME (DAYS, HRS, MINS) 010000

STEP COMMUNICATION STATISTICS (PAGE 4)
 HUNTER LIGGETT SCENARIO 1
 1 REPLICATIONS

EXTERNAL COMMUNICATIONS

ATTEMPTS
 MEAN 1.300
 STANDARD DEVIATION 0.000

COMMUNICATION SUCCESS RATIO
 MEAN 1.000
 STANDARD DEVIATION 0.300

AVERAGE POWER LOSSES FOR COMMO FAILURES (PERCENT)
 ATTENUATION DUE TO RELIEF 0.300
 ATTENUATION DUE TO VEGETATION 0.300
 ATTENUATION DUE TO RANGE 0.000

TOTAL TIME RECEIVING (DAYS.HRS.MINS)
 MEAN 000050
 STANDARD DEVIATION 000300

TOTAL TIME TRANSMITTING (DAYS.HRS.MINS)
 MEAN 000001
 STANDARD DEVIATION 000300

AMPERE HRS AVAILABLE 130.000

AMPERE HRS USED
 MEAN .510
 STANDARD DEVIATION 0.300

SIAF HUMAN MAINTENANCE STATISTICS (PAGE 10)
MUNTA LIGGETT SCENARIO
1 REPLICATIONS

	BEGINNING	END	MAX	MIN	AVERAGE
HUMAN PERFORMANCE DEGRADATION					
MEAN	0.0	0.004	0.004	0.000	0.002
STANDARD DEVIATION	0.0	0.000	0.000	0.000	0.000
ENERGY EXPENDED (RTU)					
MEAN	0.0	846.215	846.215	0.000	442.342
STANDARD DEVIATION	0.0	0.000	0.000	0.000	0.000
TIME HISTORY OF HUMAN PERFORMANCE DEGRADATION (FIRST REPLICATION ONLY)					
TIME	010801				
PERF. DEG.	0.000				

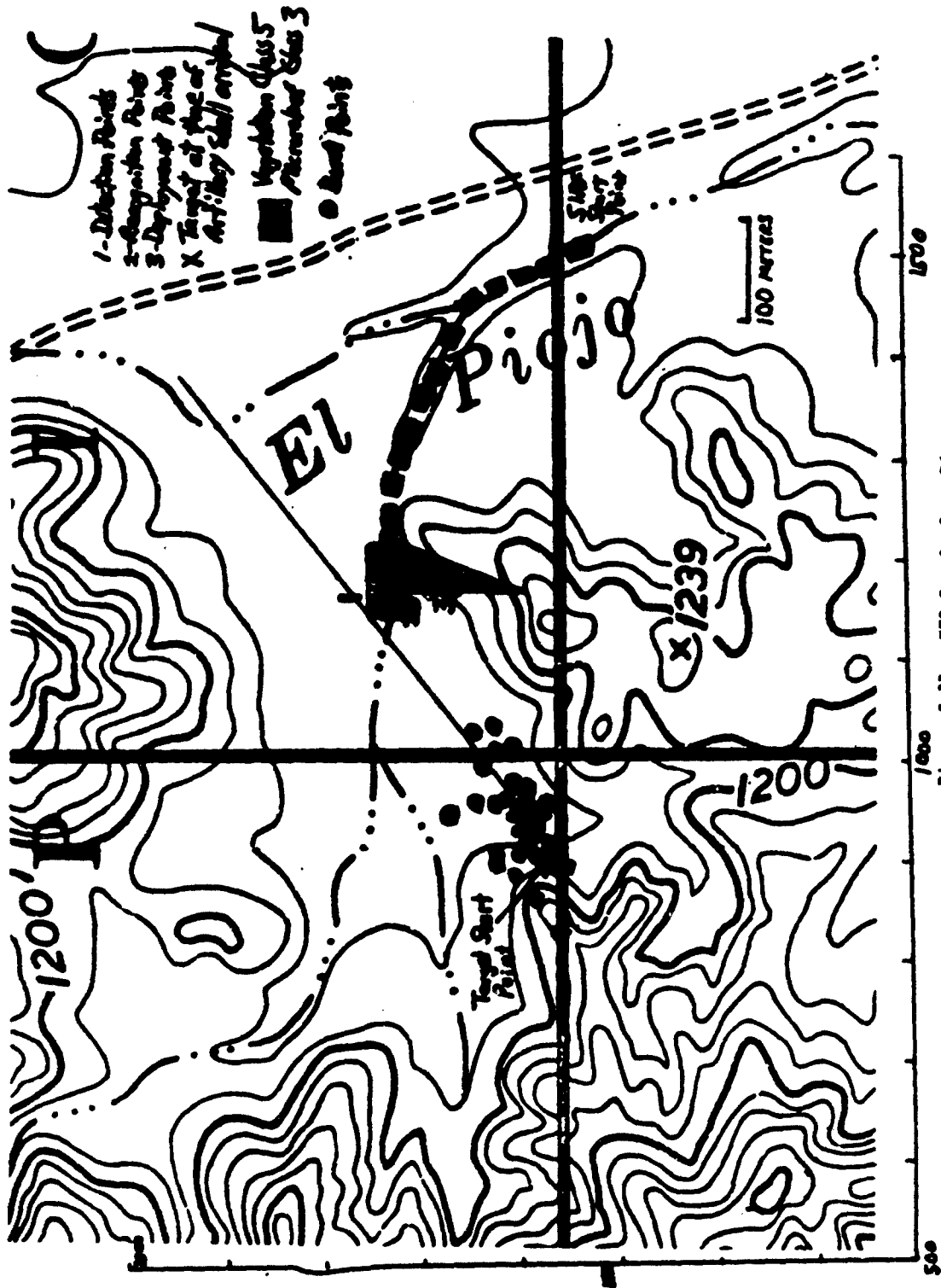


Figure 6.11. EFS Sample Case Diagram

X-Y COORDINATES OF EXTERNAL LIFE SUPPORT BURST PRINTS

X = 826.57 V = 1555.07
X = 831.63 V = 1600.41
X = 897.87 V = 1554.90
X = 947.97 V = 1598.93

POSITION OF ATTACKER MU 1 X- 1169.28 V- 1674.72

POSITION OF ATTACKER MU 2 X- 1168.87 V- 1699.22

POSITION OF DEFENDER MU 1 X- 946.64 V- 1587.31

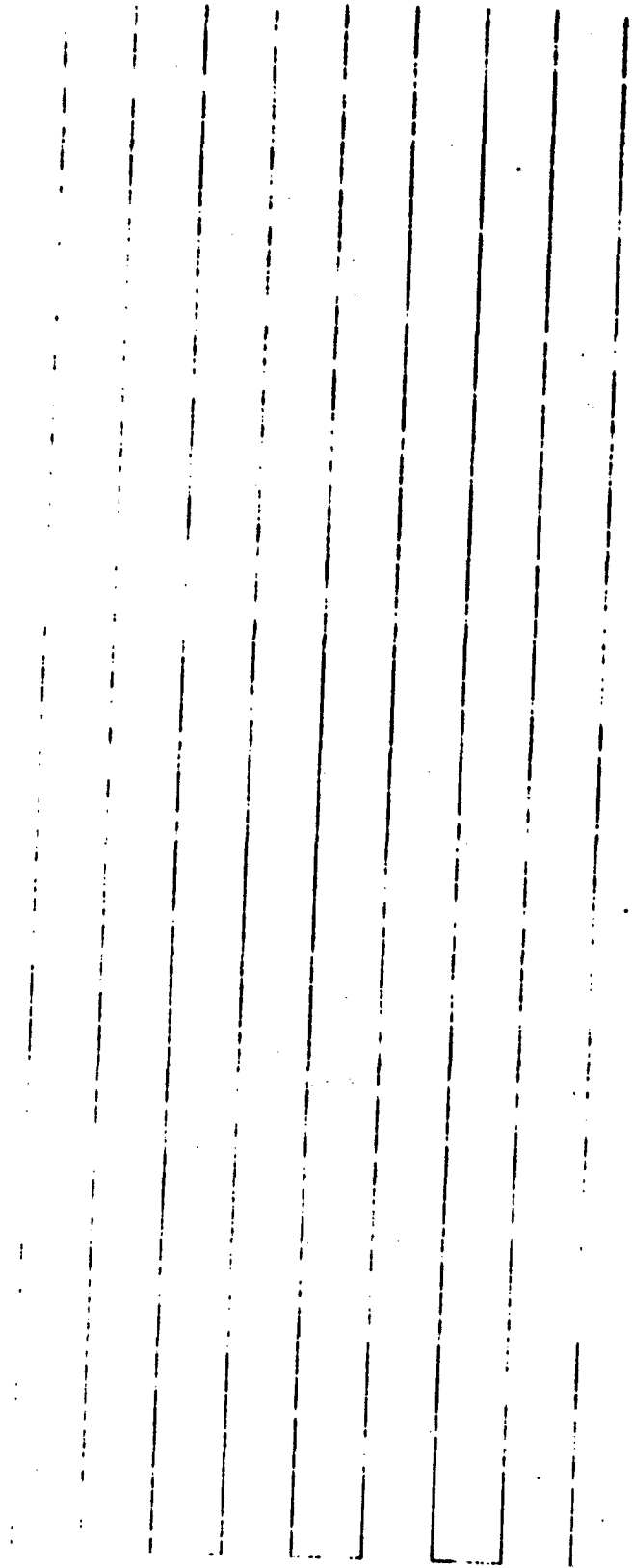


Figure 6.12. EFS Sample Case Output

ATTIRUTES AFTER EFS MUST

ATTACKER PATROL:

PATROL MEMBER

1 2 3 4 5 6 7 8 9

FIRE TEAM NUMBER	1	2	3	4	5	6	7	8	9
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-79 GL	M-16(SA)	M-16(SA)	M-16(SA)	0
CURRENT AMMO SUPPLY	100	100	100	100	6	100	100	100	0
CASUALTY STATUS	VU	NO	NO	NO	NO	NO	NO	NO	0
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	0
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1168.87	1169.38	1170.21	1168.16	1172.06	1167.23	1170.76	1167.91	0.00
CURRENT Y (METER)	1699.22	1676.72	1695.77	1701.65	1691.26	1704.76	1670.04	1679.50	0.00
NEXT X (METER)	1177.19	1175.28	1176.70	1177.67	1176.22	1178.16	1171.82	1174.74	0.00
NEXT Y (METER)	1682.44	1662.86	1677.46	1687.41	1672.48	1692.39	1658.08	1667.64	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	0.00
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	20	20	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
MOVEMENT RATE (M/SEC)	.29	.29	.29	.29	.29	.29	.29	.29	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	6	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	0
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER PATROL:	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	0	0	0
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47			
CURRENT AMMO SUPPLY	100	100	100	100	100	100	0	0	0
CASUALTY STATUS	HI. WOUND	MA. WOUND	MU	DEAD	NO MA. WOUND	MA. WOUND			
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT			
SUPPRESSION STATE	1	1	1	1	1	1	0	0	0
CURRENT X (METER)	946.64	941.41	949.76	938.28	952.89	941.41	0.00	0.00	0.00
CURRENT Y (METER)	1587.31	1589.53	1583.41	1593.43	1579.50	1589.53	0.00	0.00	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	0.00	0.00	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	0.00	0.00	0.00
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	0.00	0.00	0.00
MOVING STATUS	NORMAL	STOPPED	NORMAL	STOPPED	NORMAL	STOPPED			
HANDOVER UNIT	1	1	1	1	1	1	0	0	0
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	0	0	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN			
MOVEMENT RATE (M/SEC)	.30	.30	.30	.30	.30	.30	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.			
INITIAL AMMO SUPPLY	100	100	100	100	100	100	0	0	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA			
POSTY. IN FIRE TEAM	1	2	3	4	5	6	0	0	0
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE			
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION

DEFENDER BREAKS, WITHDRAWAL ANGLE = 3-2163
 POSITION OF ATTACKER MU 1 X- 1169.45 Y- 1674.52
 POSITION OF ATTACKER MU 2 X- 1168.96 Y- 1699.03
 POSITION OF DEFENDER MU 1 X- 945.47 Y- 1587.17

1 4 19 21 CASUALTY EVENT
DEFENSE PATROL SUSTAINS THE HEAVY CASUALTY
THE NUMBER OF THE CASUALTY MEMBER IS : 5
THE TYPE OF CASUALTY IS : MAJ. WOUND
TIME(SEC) THAT COMBAT OPERATION HAS BEEN UNDERWAY : 9.7322
POSITION : X- 1169.45 Y- 1674.52

	DEFENDER PATROL								
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY	100	100	100	100	100	100	100	100	100
CASUALTY STATUS	PI-WOUND	MA-WOUND	NO	DEAD	MA-WOUND	MA-WOUND	MA-WOUND	MA-WOUND	MA-WOUND
FIGHTING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	946.47	941.41	949.59	938.28	952.71	941.41	941.41	941.41	941.41
CURRENT Y (METER)	1587.17	1589.53	1583.27	1593.43	1579.37	1589.53	1589.53	1589.53	1589.53
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	.50
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE
MOVING STATUS	TOP SP.	STOPPED	TOP SP.	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	20	20	20
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)	.30	.30	.30	.30	.30	.30	.30	.30	.30
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POST. IN FIRE TEAM	1	2	3	4	5	6	7	8	9
SECONDARY WEAPON (M)	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER
 BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY PROJECTION

X-Y COORDINATES OF EXTERNAL FIRE SUPPORT BURST POINTS

X = 965.92 Y = 1612.21
X = 1014.78 Y = 1647.15
X = 1034.45 Y = 1621.09
X = 1082.17 Y = 1649.00

POSITION OF ATTACKER MU 1 X- 1170.35 Y- 1671.77

POSITION OF ATTACKER MU 2 X- 1170.26 Y- 1696.44

POSITION OF DEFENDER MU 1 X- 944.12 Y- 1585.30

1 8 19 31

ATTRIBUTES AFTER EFS BURST

	ATTACKER PATROL:								
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-79 GL	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	99	99	99	97	5	99	99	99	99
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1170.24	1170.35	1171.24	1169.89	1172.73	1169.28	1171.03	1169.46	0.00
CURRENT Y (METER)	1696.44	1671.77	1692.85	1699.07	1688.23	1702.42	1666.95	1676.82	0.00
NEXT X (METER)	1177.19	1173.28	1176.70	1177.67	1176.22	1176.16	1171.82	1174.74	0.00
NEXT Y (METER)	1682.44	1662.86	1677.46	1687.41	1672.48	1692.39	1698.08	1667.64	0.00
WEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	0.00
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	19	19	19	17	19	19	19	19	0
FUNCTION IN PATROL	P.L.	A.P.L.	PIFLEMAN	M.GUNNER	GR.LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0
MOVEMENT RATE (M/SEC)	.29	.29	.29	.29	.29	.29	.29	.29	0.00
INDIV. ASSIGNMENT	BASE FR.	K. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	0
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER PATROL:	1	2	3	4	5	6	7	8	9	1
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1	1
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY	100	100	100	100	100	100	100	100	100	100
CASUALTY STATUS	MI. WOUND	MA. WOUND	MI. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE	1	1	1	1	1	1	1	1	1	1
CURRENT X (METER)	944.12	941.41	947.25	938.28	952.71	941.41	941.41	941.41	941.41	941.41
CURRENT Y (METER)	1585.30	1589.53	1581.40	1593.43	1579.37	1589.53	1589.53	1589.53	1589.53	1589.53
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	.50	.50
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE
MOVING STATUS	TOP SP.	STOPPED	TOP SP.	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT	1	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	20	20	20	20
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)	.30	.30	.30	.30	.30	.30	.30	.30	.30	.30
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POST. IN FIRE TEAM	1	2	3	4	5	6	6	6	6	6
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION

X-Y COORDINATES OF INTERVAL FIRE SUPPORT BATTERY POINTS

X = 800.46 Y = 1575.04
X = 933.84 Y = 1610.04
X = 949.04 Y = 1571.41
X = 993.72 Y = 1619.40

POSITION OF ATTACKER MU 1 X- 1171.25 Y- 1609.03

POSITION OF ATTACKER MU 2 X- 1171.53 Y- 1693.85

POSITION OF DEFENDER MU 1 X- 941.78 Y- 1583.43

DEFENDER	PATROL	MEMBER	1	2	3	4	5	6	7	8	9	10
FIRE TEAM NUMBER			1	2	3	4	5	6	7	8	9	10
WEAPON TYPE			AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY			100	100	100	100	100	100	100	100	100	100
CASUALTY STATUS			MI. WOUND	MA. WOUND	MI. WOUND	MA. WOUND	MI. WOUND	MA. WOUND	MI. WOUND	MA. WOUND	MI. WOUND	MA. WOUND
FIRING STATUS			NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE			1	1	1	1	1	1	1	1	1	1
CURRENT X (METER)			941.61	944.91	938.28	932.71	941.41	941.41	941.41	941.41	941.41	941.41
CURRENT Y (METER)			1583.63	1579.52	1593.43	1579.37	1589.53	1589.53	1589.53	1589.53	1589.53	1589.53
NEXT X (METER)			0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)			0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)			1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)			0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50
CURRENT POSTURE			PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE
MOVING STATUS			STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT			1	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (MAG.)			20	20	20	20	20	20	20	20	20	20
FUNCTION IN PATROL			P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)			0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30	0.30
INDIV. ASSIGNMENT			BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY			100	100	100	100	100	100	100	100	100	100
WEAPON TYPE			AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POST. IN FIRE TEAM			1	2	3	4	5	6	7	8	9	10
SECONDARY WEAPON AVI			NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
NO. OF HAND GRENADE			0	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE			0	0	0	0	0	0	0	0	0	0

BREAK DECISION : DEFENDER MAKES CONTACT DUE TO LACK OF ADEQUATE FIREPOWER
 BREAK DECISION : DEFENDER MAKES CONTACT DUE TO HIGH CASUALTY RATE

X-Y COORDINATES OF INTERNAL FIRE SUPPORT BURST POINTS

X = 888.01 Y = 1567.50
X = 934.91 Y = 1603.22
X = 959.04 Y = 1565.42
X = 1004.12 Y = 1602.83

POSITION OF ATTACKER MU 1 X- 1172.15 Y- 1666.28

POSITION OF ATTACKER MU 2 X- 1172.81 Y- 1691.27

POSITION OF DEFENDER MU 1 X- 939.44 Y- 1581.55

1 P 19 51

ATTRIBUTES AFTER EFS MUST

ATTACKER PATROL:

	1	2	3	4	5	6	7	8	9	1
	PATROL MEMBER									
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	1	1
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-79 GL	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)
CURRENT AMMO SUPPLY	99	99	99	97	3	99	99	99	99	99
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	MUT	MUT	MUT	MUT	MUT	MUT
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1172.81	1172.15	1173.17	1173.09	1173.98	1173.11	1171.54	1172.34	1172.34	1172.34
CURRENT Y (METER)	1691.27	1666.28	1687.41	1694.27	1682.59	1698.09	1681.19	1671.81	1671.81	1671.81
NEXT X (METER)	1177.19	1175.28	1176.70	1177.67	1176.22	1178.16	1171.82	1174.74	1174.74	1174.74
NEXT Y (METER)	1682.44	1662.86	1677.46	1687.41	1672.48	1692.39	1658.88	1667.64	1667.64	1667.64
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
CURRENT PCSTURE	.50	.50	.50	.50	.50	.50	.50	.50	.50	.50
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL
MANEUVER UNIT	2	1	2	2	2	2	1	1	1	1
ROUNDS REMAIN (MAG.)	19	19	19	17	19	19	19	19	19	19
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	P-GUNNER	GR-LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN
MOVEMENT RATE (M/SEC)	.29	.29	.29	.29	.29	.29	.29	.29	.29	.29
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	M. UNIT	M. UNIT
INITIAL AMMO SUPPLY	100	100	100	100	100	100	100	100	100	100
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	2	3	3
SECONDARY WEAPON AVI	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.	M. GREN.
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	4	4
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0	0

DEFENDER	PATROL	1	2	3	4	5	6	7	8	9	1
FIRE TEAM NUMBER		1	1	1	1	1	1	1	1	1	1
WEAPON TYPE		AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47
CURRENT AMMO SUPPLY		100	100	100	100	100	100	100	100	100	100
CASUALTY STATUS		MI. WOUND	MA. WOUND	MI. WOUND	DEAD	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND
FIRING STATUS		NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT
SUPPRESSION STATE		1	1	1	1	1	1	1	1	1	1
CURRENT X (METER)		939.64	941.41	942.56	938.28	952.71	941.41	941.41	941.41	941.41	941.41
CURRENT Y (METER)		1581.55	1589.53	1577.65	1593.43	1579.37	1589.53	1589.53	1589.53	1589.53	1589.53
NEXT X (METER)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)		0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)		1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70
WIDTH (METER)		.50	.50	.50	.50	.50	.50	.50	.50	.50	.50
CURRENT POSTURE		PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE
MOVING STATUS		TOP SP.	STOPPED	TOP SP.	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED
MANEUVER UNIT		1	1	1	1	1	1	1	1	1	1
ROUNDS REMAIN (MAG.)		20	20	20	20	20	20	20	20	20	20
FUNCTION IN PATROL		P.L.	A.P.L.	P.L.	P.L.	P.L.	P.L.	P.L.	P.L.	P.L.	P.L.
MOVEMENT RATE (M/SEC)		.30	.30	.30	.30	.30	.30	.30	.30	.30	.30
INDIV. ASSIGNMENT		BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.
INITIAL AMMO SUPPLY		100	100	100	100	100	100	100	100	100	100
WEAPON TYPE		AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA
POSTY. IN FIRE TEAM		1	2	3	4	5	6	6	6	6	6
SECONDARY WEAPON AVI		NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE	NONE
NO. OF HAND GRENADE		0	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE		0	0	0	0	0	0	0	0	0	0

BREAK DECISION : ATTACKER BREAKS CONTACT DUE TO EXCESSIVE ELAPSED TIME (FIGHT)

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO HIGH CASUALTY FRACTION
 IC FOR BREAK CONTACT-AVAILABLE
 STAFF RALLY POINT 1470.9600 Y644.5567
 ATTACKER WITHDRAWAL RUTTS

1172.15 1470.96
1666.28 1648.06
ATTACKER WITHDRAWAL POINTS
1172.81 1470.96
1651.27 1648.66

X-Y COORDINATES OF EXTERNAL FIRE SUPPORT BUST POINTS

X = 895.52 Y = 1616.8c
X = 945.79 Y = 1646.09
X = 959.63 Y = 1609.11
X = 1020.95 Y = 1659.39

POSITION OF ATTACKER MU 1 X- 1182.97 Y- 1665.65
POSITION OF ATTACKER MU 2 X- 1183.54 Y- 1669.72
POSITION OF DEFENDER MU 1 X- 937.10 Y- 1576.68

DEFENDER	PATROL	MEMBER	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER			1	1	1	1	1	1	1	0	0
WEAPON TYPE			AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47	0	0
CURRENT AMMO SUPPLY			100	100	100	100	100	100	100	0	0
CASUALTY STATUS			MI. FOUND	MA. WOUND	MI. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	MA. WOUND	0	0
FIGHTING STATUS			WY	WY	WY	WY	WY	WY	WY	0	0
SUPPRESSION STATE			1	1	1	1	1	1	1	0	0
CURRENT X (METER)			937.10	941.41	940.22	938.28	952.71	941.41	941.41	0.00	0.00
CURRENT Y (METER)			1579.68	1589.53	1575.77	1593.43	1579.37	1589.53	1589.53	0.00	0.00
NEXT X (METER)			0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)			0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)			1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00	0.00
WIDTH (METER)			.50	.50	.50	.50	.50	.50	.50	0.00	0.00
CURRENT POSTURE			PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE	0.00	0.00
MOVING STATUS			T.P. SP.	STOPPED	T.P. SP.	STOPPED	STOPPED	STOPPED	STOPPED	0	0
MANEUVER UNIT			1	1	1	1	1	1	1	0	0
ROUNDS REMAIN (MAG.)			20	20	20	20	20	20	20	0	0
FUNCTION IN PATROL			P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN	0	0
MOVEMENT RATE (M/SEC)			.30	.30	.30	.30	.30	.30	.30	0.00	0.00
INDIV. ASSIGNMENT			BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	0	0
INITIAL AMMO SUPPLY			100	100	100	100	100	100	100	0	0
WEAPON TYPE			AREA	AREA	AREA	AREA	AREA	AREA	AREA	0	0
POSIT. IN FIRE TEAM			1	2	3	4	5	6	6	0	0
SECONDARY WEAPON AVI			NONE	VUNF	NONE	NONE	NONE	NONE	NONE	0	0
NO. OF HAND GRENADE			0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE			0	0	0	0	0	0	0	0	0

POSITION OF ATTACKER MU 1 X- 1201.35 Y- 1664.56

POSITION OF ATTACKER MU 2 X- 1201.77 Y- 1687.13

POSITION OF DEFENDER MU 1 X- 932.41 Y- 1575.93

1 8 20 21 NO EVFATS IN 20 SECONDS.

POSITION OF ATTACKER MU 1 X- 1222.99 Y- 1663.29

POSITION OF ATTACKER MU 2 X- 1220.00 Y- 1684.52

POSITION OF DEFENDER MU 1 X- 927.73 Y- 1572.18

1 8 20 41 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1244.61 Y- 1664.01
 POSITION OF ATTACKER MU 2 X- 1241.45 Y- 1681.46
 POSITION OF DEFENDER MU 1 X- 923.04 Y- 1568.43

1 8 21 1 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1266.24 Y- 1440.73
 POSITION OF ATTACKER MU 2 X- 1262.90 Y- 1678.39
 POSITION OF DEFENDER MU 1 X- 918.30 Y- 1564.68

1 8 21 21 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1287.87 Y- 1659.46
 POSITION OF ATTACKER MU 2 X- 1264.34 Y- 1675.33
 POSITION OF DEFENDER MU 1 X- 913.67 Y- 1560.94

1 8 21 41 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1309.50 Y- 1658.18
 POSITION OF ATTACKER MU 2 X- 1305.79 Y- 1672.26
 POSITION OF DEFENDER MU 1 X- 908.99 Y- 1557.19

1 8 22 1 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1331.13 Y- 1656.91
 POSITION OF ATTACKER MU 2 X- 1327.24 Y- 1669.20
 POSITION OF DEFENDER MU 1 X- 904.30 Y- 1553.44

1 8 22 21 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1352.76 Y- 1655.63
 POSITION OF ATTACKER MU 2 X- 1348.69 Y- 1666.13
 POSITION OF DEFENDER MU 1 X- 899.62 Y- 1549.69

1 8 22 41 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1374.39 Y- 1654.35
 POSITION OF ATTACKER MU 2 X- 1370.14 Y- 1663.06
 POSITION OF DEFENDER MU 1 X- 894.93 Y- 1545.94

1 8 23 1 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1396.01 Y- 1653.08
 POSITION OF ATTACKER MU 2 X- 1391.59 Y- 1660.00
 POSITION OF DEFENDER MU 1 X- 890.24 Y- 1542.20

1 8 23 21 NO EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1417.64 Y- 1651.8C

POSITION OF ATTACKER MU 2 X- 1413.04 Y- 1656.93
 POSITION OF DEFENDER MU 1 X- 805.96 Y- 1538.45

1 8 23 41 NUMBER OF EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1439.27 Y- 1650.53
 POSITION OF ATTACKER MU 2 X- 1434.49 Y- 1653.87
 POSITION OF DEFENDER MU 1 X- 880.87 Y- 1534.70

1 8 24 1 NUMBER OF EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1460.90 Y- 1649.25
 POSITION OF ATTACKER MU 2 X- 1455.93 Y- 1650.80
 POSITION OF DEFENDER MU 1 X- 876.19 Y- 1530.95

1 8 24 21 NUMBER OF EVENTS IN 20 SECONDS.
 POSITION OF ATTACKER MU 1 X- 1470.96 Y- 1646.66
 POSITION OF ATTACKER MU 2 X- 1465.51 Y- 1649.38
 POSITION OF DEFENDER MU 1 X- 874.01 Y- 1529.21

1 8 24 30 1470.96 1648.66 MOVEMENT ATTACKER MU 1 WILL MOVE 10.08 METERS AT AN ANGLE OF --
 1 8 24 30 1465.91 1649.38 MOVEMENT ATTACKER MU 2 WILL MOVE 10.08 METERS AT AN ANGLE OF --
 RESOLUTION HAS BEEN CHANGED BACK TO THE RECONNAISSANCE LEVEL OF 50.8 METERS

DECISION ON CONTINUATION OF RECONNAISSANCE MISSION AFTER COMBAT OPERATION IS COMPLETED :

MISSION DECISION : CONTINUE

CURRENT AMOUNT OF FOOD REMAINING PER MAN(LB.) : 13.4442

CURRENT AMOUNT OF WATER REMAINING PER MAN(LB.) : 6.9334

PATROL DURATION (DAYS) : 1

STAF DETECTS TARGET NO. 1 VISUALLY

STAF RECOGNIZED TARGET NO. 1 AT X- 1470.96 Y- 1648.66 THE RECOGNITION RANGE IS 543.21

PATROL MEMBER STATISTICS AFTER COMBAT

ATTACKER PATROL:	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-101A)	M-79	M-15(SA)	M-16(SA)	M-16(SA)	
CURRENT AMMO SUPPLY	99	99	99	97	5	99	99	99	0
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	0
FIGHTING STATUS	NOT	NOT	NOT	NOT	NCT	NOT	NOT	NOT	
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1465.51	1470.96	1460.10	1406.96	1466.86	1466.63	1470.35	1467.87	0.00
CURRENT Y (METER)	1549.58	1648.66	1644.32	1654.31	1639.16	1659.31	1643.69	1651.85	0.00
NEXT X (METER)	1470.96	1470.96	1470.41	1471.51	1469.86	1472.06	1470.41	1471.51	0.00
NEXT Y (METER)	1648.66	1648.00	1643.69	1653.03	1638.72	1658.60	1643.69	1653.63	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	TOP SP.	TCP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	TOP SP.	
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	19	19	19	17	19	19	19	19	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	
MOVEMENT RATE (M/SEC)	1.08	1.08	1.08	1.08	1.08	1.08	1.08	1.08	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	6	100	100	100	0
WEAPON TYPE	AKA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON (AVI)	M. GREN.	M. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	1	0	0	0	0	0	0	0

DEFENDER PATROL: PATROL MEMBER

	1	2	3	4	5	6	7	8	9	1
FIRE TEAM NUMBER	1	1	1	1	1	1	0	0	0	0
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47				
CURRENT AMMO SUPPLY	100	100	100	100	100	100	0	0	0	0
CASUALTY STATUS	MI. WOUND	MI. WOUND	MI. WOUND	DEAD	MA. WOUND	MA. WOUND				
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT				
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	374.01	941.41	877.13	338.28	952.71	941.41	0.00	0.00	0.00	0.00
CURRENT Y (METER)	1529.21	1589.53	1525.30	1593.43	1579.37	1589.53	0.00	0.00	0.00	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	0.00	0.00	0.00	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	0.00	0.00	0.00	0.00
CURRENT POSTURE	PRONE	PRONE	PRONE	PRONE	PRONE	PRONE				
MOVING STATUS	TOP SP.	STOPPED	TOP SP.	STOPPED	STOPPED	STOPPED				
MANEUVER UNIT	1	1	1	1	1	1	0	0	0	0
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	0	0	0	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN				
MOVEMENT RATE (M/SEC)	.30	.30	.30	.30	.30	.30	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.				
INITIAL AMMO SUPPLY	100	100	100	100	100	100	0	0	0	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA				
POST. IN FIRE TEAM	1	2	3	4	5	6	0	0	0	0
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE				
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0	0

SIAF POSITION: X- 1430.95 Y- 1625.60 TARGET DETECTED: YES TIME: DAYS-01 HOURS-08 MINUTES-26
 XTAR = 932 YIAR = 1576 LOS = 1
 SIAF DETECTS TARGET NO. 1 VISUALLY
 SIAF POSITION: X- 1422.40 Y- 1620.67 TARGET DETECTED: YES TIME: DAYS-01 HOURS-03 MINUTES-27
 XTAR = 932 YIAR = 1575 LOS = 1
 SIAF DETECTS TARGET NO. 1 VISUALLY
 SIAF POSITION: X- 1371.60 Y- 1591.40 TARGET DETECTED: YES TIME: DAYS-01 HOURS-08 MINUTES-29
 XTAR = 932 YIAR = 1576 LOS = 1
 SIAF DETECTS TARGET NO. 1 VISUALLY

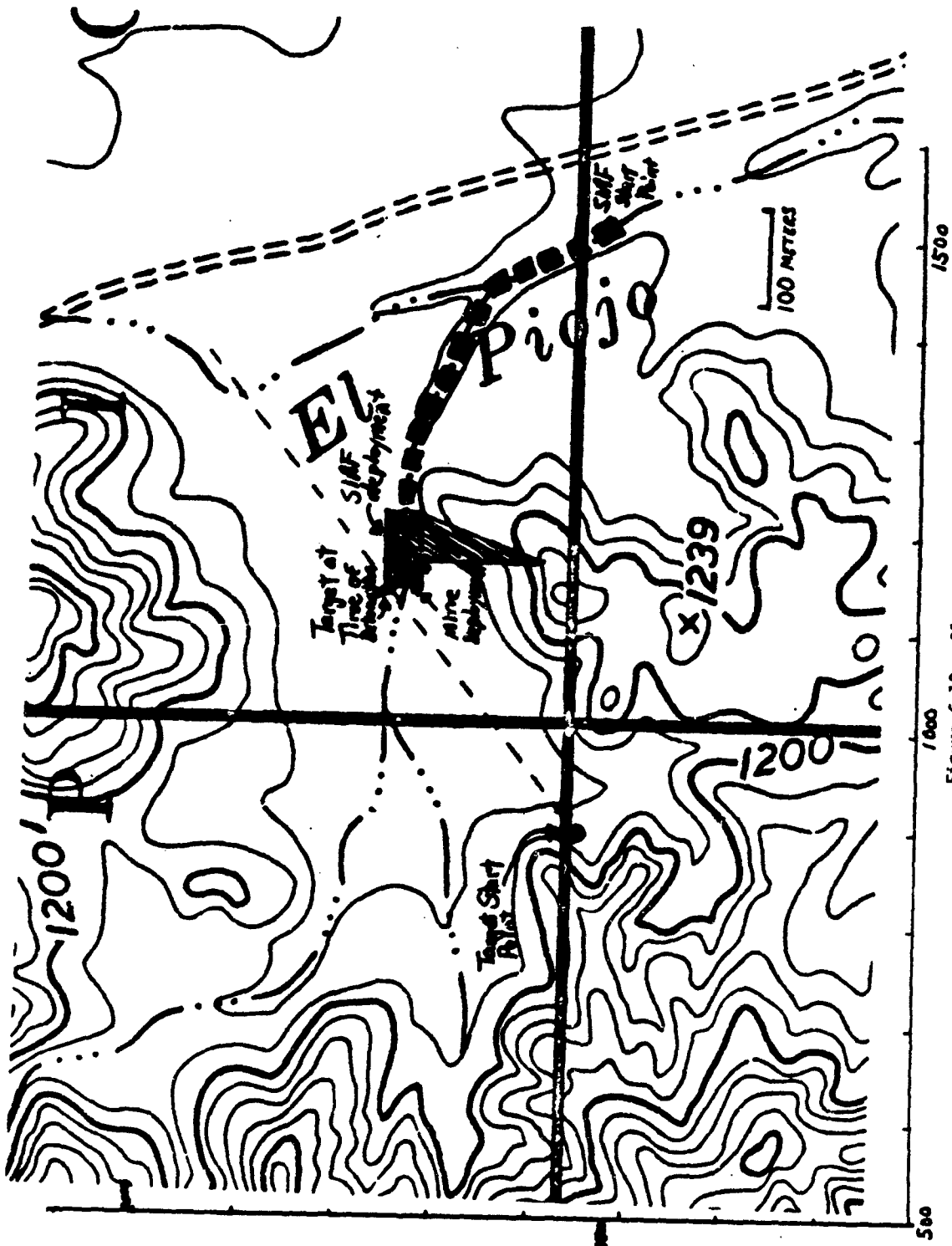


Figure 6.13. Claymore Mines Sample Case Diagram

ATTRIBUTES AFTER DEPLOYMENT OF CLAYMORE MINES

	ATTACKER PATROL:				PATROL MEMBER				
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-16(SA)	M-16(SA)	M-16(SA)	M-16(A)	M-16(SA)	M-16(SA)	M-16(SA)	M-16(SA)	
CURRENT AMMO SUPPLY	100	100	100	100	6	100	100	100	0
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1157.41	1160.53	1163.64	1164.78	1169.90	1173.03	1176.15	1179.27	0.00
CURRENT Y (METER)	1716.73	1719.22	1721.72	1724.22	1726.72	1729.22	1731.72	1734.22	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	CROUCH	CROUCH	CROUCH	CROUCH	CROUCH	CROUCH	CROUCH	CROUCH	0.00
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	0.00
NAME/COVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	20	20	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	0.00
MOVEMENT RATE(M/SEC)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	6	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POSIT. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	0
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

Figure 6-14. Combat Outputs for Claymore Mines Sample Case

DEPLOYMENT OF CLAYMORE MINES
X MINE = 1154.29 Y MINE = 1720.63
X MINE = 1166.00 Y MINE = 1730.00
X MINE = 1177.71 Y MINE = 1739.37

ATTRIBUTES AFTER DETONATION OF MINES

	ATTACKER PATROL:								
	1	2	3	4	5	6	7	8	9
FIRE TEAM NUMBER	1	1	1	1	1	1	1	1	0
WEAPON TYPE	M-161SA1	M-161SA1	M-161SA1	M-161SA1	M-79 CL	M-161SA1	M-161SA1	M-161SA1	
CURRENT AMMO SUPPLY	100	100	100	100	6	100	100	100	0
CASUALTY STATUS	NO	NO	NO	NO	NO	NO	NO	NO	NO
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT	NOT	NOT	
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1197.41	1160.53	1163.66	1166.78	1169.90	1173.03	1176.15	1179.27	0.00
CURRENT Y (METER)	1716.73	1719.22	1721.72	1724.22	1726.72	1729.22	1731.72	1734.22	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	1.70	1.70	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	.50	.50	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND	STAND	STAND	0.00
MOVING STATUS	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	STOPPED	0.00
MANEUVER UNIT	2	1	2	2	2	2	1	1	0
ROUNDS REMAIN (MAG.)	20	20	20	20	20	20	20	20	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	M.GUNNER	GR.LNCH.	RIFLEMAN	RIFLEMAN	RIFLEMAN	
MOVEMENT RATE (M/SEC)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	M. UNIT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	M. UNIT	M. UNIT	0.00
INITIAL AMMO SUPPLY	100	100	100	100	6	100	100	100	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA	AREA	AREA	
POST. IN FIRE TEAM	1	1	2	3	4	5	2	3	0
SECONDARY WEAPON AVI	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	H. GREN.	
NO. OF HAND GRENADE	4	4	4	4	4	4	4	4	0
NO. OF SMOKE GRENADE	2	2	0	0	0	0	0	0	0

DEFENDER PATROL:	1	2	3	4	5	6	7	8	9	1
FIRE TEAM NUMBER	1	1	1	1	1	1	0	0	0	0
WEAPON TYPE	AK-47	AK-47	AK-47	AK-47	AK-47	AK-47				
CURRENT AMMO SUPPLY	100	100	100	100	100	100	0	0	0	0
CASUALTY STATUS	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD				
FIRING STATUS	NOT	NOT	NOT	NOT	NOT	NOT				
SUPPRESSION STATE	0	0	0	0	0	0	0	0	0	0
CURRENT X (METER)	1150.00	1166.88	1133.12	1143.75	1136.25	1146.88	0.00	0.00	0.00	0.00
CURRENT Y (METER)	1753.00	1733.90	1746.10	1757.81	1742.19	1753.90	0.00	0.00	0.00	0.00
NEXT X (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
NEXT Y (METER)	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
HEIGHT (METER)	1.70	1.70	1.70	1.70	1.70	1.70	0.00	0.00	0.00	0.00
WIDTH (METER)	.50	.50	.50	.50	.50	.50	0.00	0.00	0.00	0.00
CURRENT POSTURE	STAND	STAND	STAND	STAND	STAND	STAND				
MOVING STATUS	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL	NORMAL				
MANEUVER UNIT	1	1	1	1	1	1	0	0	0	0
ROUNDS REMAIN (MAG.1)	20	20	20	20	20	20	0	0	0	0
FUNCTION IN PATROL	P.L.	A.P.L.	RIFLEMAN	RIFLEMAN	RIFLEMAN	RIFLEMAN				
MOVEMENT RATE(M/SEC)	.30	.30	.30	.30	.30	.30	0.00	0.00	0.00	0.00
INDIV. ASSIGNMENT	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.	BASE FR.				
INITIAL AMMO SUPPLY	100	100	100	100	100	100	0	0	0	0
WEAPON TYPE	AREA	AREA	AREA	AREA	AREA	AREA				
POST. IN FIRE TEAM	1	2	3	4	5	6	0	0	0	0
SECONDARY WEAPON AVI	NONE	NONE	NONE	NONE	NONE	NONE				
NO. OF HAND GRENADE	0	0	0	0	0	0	0	0	0	0
NO. OF SMOKE GRENADE	0	0	0	0	0	0	0	0	0	0

POSITION OF ATTACKER MU 1 X- 1162.53 Y- 1719.22
 POSITION OF ATTACKER MU 2 X- 1157.41 Y- 1716.73
 POSITION OF DEFENDER MU 1 X- 1150.00 Y- 1750.00

1 10 17 51 TIME OF MINFS DETONATION

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE FIREPOWER

BREAK DECISION : DEFENDER BREAKS CONTACT DUE TO LACK OF ADEQUATE AMMUNITION

7.0 OPERATING PROCEDURES

This section describes the operating procedures in terms of hardware requirements, software requirements, overlay structure of the model, and sample deck setup.

7.1 HARDWARE REQUIREMENTS

- CDC 6000 series digital computer
- SCOPE operating system
- FORTRAN EXTENDED source program compiler (FTN)
- COMPASS assembler
- Tape drive for input of topocon tape
- 232K of octal 60-bit words central memory
- Temporary and short-term storage devices (i.e., disk or tape)
- Standard system file configuration for input data and object program modules.

7.2 SOFTWARE REQUIREMENTS

- FORTRAN unit 1 is used for reading namelist input data. This data consists of NAML1, NAML2, NAML3, and NAML4. File NLINP is referenced to this unit.
- FORTRAN unit 2 is used for temporary storage. At the beginning of the model the packed reconnaissance elevations are stored here. After the return of a combat operation this unit is read to restore reconnaissance elevation data. File PAKZ is referenced to this unit.
- FORTRAN unit 5 is used for standard input. File INPUT is referenced to this unit.
- FORTRAN unit 6 is used for standard output. File OUTPUT is referenced to this unit.
- FORTRAN unit 7 is used for temporary storage. When a start/stop point is reached, the common blocks are dumped or read from this unit, so that the model can be started or stopped at specific points. File START is referenced to this unit.
- FORTRAN unit 8 is used for reading elevation input data. This file is a direct output of topocon programs, MAPGEN or ROTATE. File ZINP is referenced to this unit.

- FORTRAN unit 9 is used for intermediate storage. The common block **STATS** is updated on this unit for each replication of the model. File **STATS** is referenced to this unit.
- Most of the **COMMON** blocks used by the **SIAF** program are defined in the following computer pages 1 through 47 of Figure 7.1. These blocks were generated by the **BLKGEN** program described in Appendix A of this volume. Using these **COMMON** blocks the **SPECP** program defined in Appendix B of this volume, punched out the **DIMENSION** and **EQUIVALENCE** statements for all subroutines requiring any variable pertaining to the **COMMON** blocks.
- To facilitate finding a location of a common variable, Figure 7.2 gives an alphabetical list of all variables in these commons. Furthermore, their location in that block and the block name are given along with its dimension if the variable is an array.

7.3 OVERLAY STRUCTURE

- Figure 7.3 is a chart overview of the overlay structure organization. Within each overlay block the overlay level is given and the subroutine and programs are listed alphabetically, along with the size of the model with that overlay.

7.4 SAMPLE DECK SET-UPS

- Figures 7.4 - 7.6 are listings of card decks that would be required to create the model from tape starting from scratch and end up with an execution of the sample case.
- Figure 7.4, when submitted, will create or copy from the **SIAF** tape, all source cards and store them on permanent disk files.
- Now, execution of Figure 7.5 will compile all these source cards and create the object modules required for loading. These also are stored on permanent disk files.
- Figure 7.6 takes the generated object modules along with the required input files and executes the sample case.

20660-6002-R0-00

Page 7-2A

Revised December 1973

7.5 INSTALLATION

- The SIAF program as described above was installed and runs on a CDC 6500 digital computer at the USACDC Data Processing Installation, at Fort Leavenworth, Kansas.

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/DATABR/DATABR(625)
CURRENT BLOCK IS DATABR (624)

PAGE 1

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
-----	-----	-----	-----	-----
ATTEN	4	1		
DSM11		5		
DSM12		6		
DRICE		7		
DMT	5.3	8		
H	16.4	23		
HD	3	47		
HMT	5.3	36		
I SECT	20	111		
RHO	16.4	131		
QMTMAX	5.3	195		
RMAX	16.4	210		
REF	16.3	274		
SECT	2.4.2	322		
VEGC	1.16	338		
VISLUM	8.9	466		
W	16.4	530		
WMT	5.3	594		
XLP	16	609		

Figure 7.1. Master Common Listings (Sheet 1)

PAGE

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/DATAB2/DATAB2(100)
CURRENT BLOCK IS DATAB2 (90)

PAGE 2

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ALIN	2,2	1		
ALLF	3,2	5		
SL1		11		
SL2		12		
SOILF	2,6	13		
TMR	10,3	29		
VEGF	16	83		

Figure 7.1, Master Common Listings (Sheet 2)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/DLOGRL/DLOGBL(100)

CURRENT BLOCK IS DLOGBL (100)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ADM		1		
ALPHA		2		
ALPHA1		3		
ALPHA2		4		
BETA		5		
DSOROP		6		
DSENG		7		
DSPUR		8		
DTOEPL		9		
DTENG		10		
DTPUR		11		
DTHATT		12		
ICOUNT		13		
IDARK		14		
IFLAG		15		
IPOSE		16		
ISET		17		
ISTOFF		18		
ISUIT		19		
ITAREN		20		
JGO		21		
JSP		22		
JTACT		23		
KTACT		24		
MENOP		25		

Figure 7.1, Master Common Listings (Sheet 3)

MASTER COMMON LISTING

CURRENT BLOCK IS DLOGBL (100)

PAGE

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
MENSP		26		
NGS		27		
NHRMIN		28		
PHI		29		
PURVEL		30		
R		31		
KADV1		32		
RADV2		33		
RC		34		
RS		35		
SF		36		
SVA74		37		
TACKOP		38		
VADM		39		
VCEAL		40		
VCOV		41		
VELOP		42		
VOBS		43		
W1		44		
W2		45		
WA		46		
WB		47		
XDEPL		48		
XICIR		49		
XOP		50		
XSP		51		
YDEPL		52		
YICIR		53		
YOP		54		
YSP		55		
ZENG		56		
ZENG		57		

Figure 7.1, Master Common Listings (Sheet 4)

CURRENT BLOCK IS DLOGBL (100) MASTER COMMON LISTING PAGE 5

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ZOEPL		58		
ZENG		59		
ZETA		60		
IR		61		
MGS		62		
GS		63		
OLXDEP		64		
OLYDEP		65		
OLVULX		66		
OLVULY		67		
OLDVEL		68		
OLTACK		69		
ISTU		70		
BLANK1		71		
IMAN		72		
JMAN		73		
IFFSID		74		
KDEFOP		75		
ISTART		76		
XDEFOP		77		
YDEFOP		78		
TARV		79		
IFFF		80		
ISTALL		81		

Figure 7.1, Master Common Listings (Sheet 5)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/DLOGIN/DLOGIN(150)

CURRENT BLOCK IS DLOGIN (150)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
CADM		1		
CC1		2		
CC2		3		
CC3		4		
CLASS	5,16	5		
DTDAMB		85		
DTDATT		86		
DTEFS		87		
DTENGM		88		
DTPURM		89		
EFSA		90		
FRAMB		91		
FRATT		92		
GMAX		93		
IDIREC		94		
IDUM1		95		
IDUM2		96		
MISS		97		
NSECT		98		
PP1		99		
PP2		100		
PP3		101		
PP4		102		
Q1		103		
Q2		104		

Figure 7.1, Master Common Listings (Sheet 6)

MASTER COMMON LISTING

CURRENT BLOCK IS DLOGIN (150)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
Q3		105		
RAMB		106		
RAMIN		107		
RATT		108		
REFS		109		
ROBS		110		
RSP		111		
RZ		112		
P5		113		
GSAPRR		114		

Figure 7.1, Master Common Listings (Sheet 7)

MASTER COMMON LISTING
PAGE 8

CURRENT COMMON IS --
COMMON/COMMONA/COMMONB(900)
CURRENT BLOCK IS COMMONA (916)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
A	4.204	1		

Figure 7.1. Master Common Listings (Sheet 8)

MASTER COMMON LISTING

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
AC	16.4	1		
ALL		65		
ATAR		66		
ASIAP		67		
CC		68		
CT		69		
CR		70		
CLL		71		
CR2		72		
D	2.2	76		
DRINS		250		
DRINT		251		
DBSPEC	20	292		
EOUT	204	302		
FTMREL		506		
F0HREL		507		
G1OUT	204	508		

Figure 7.1, Master Common Listings (Sheet 9)

MASTER COMMON LISTING

CURRENT COMMON IS ---

COMMON/COMMB2/COMMB2 (645) ,CHTAR1 (320)

CURRENT BLOCK IS COMMB2 (642)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
G2OUT	204	1		
G3OUT	264	205		
HS		409		
HT		410		
IDE		411		
ISAD		412		
ITAD		413		
IDAY		414		
IISIRI		415		
IZ		416		
ITIME		417		
ILZAVL	5	418		
ITVEG	20	423		
IGEN	20	443		
IMP	20	463		
IFIRST	20	483		
ISVD		503		
ITVO		504		
IAT		505		
IAS		506		
IWC		507		
IDEYS	20	508		
IFYPE	20	528		
IT		548		
ITGRID		549		

Figure 7.1, Master Common Listings (Sheet 10)

CURRENT BLOCK IS COMB2 (642) MASTER COMMON LISTING

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
IP		550		
IDVOL		551		
ISIP	20	552		
JIT		572		
KEY		573		
LZTAR	20	574		
LFLAG	20	574		
MNO	5	614		
MS		619		
MT		620		
NUI		621		
NOCH	20	622		
NDAV		642		

Figure 7.1. Master Common Listings (Sheet 11)

CURRENT BLOCK IS GMTARI (320) MASTER COMMON LISTING PAGE 14

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ITARG	20,5	1		
IAOR	20,2	101		
IVOR	20,2	141		
ICH	20	181		
ISA	20	291		
ISV	20	221		
ITA	20	241		
ITV	20	261		
IRECOG	20,2	281		

Figure 7.1. Master Common Listings (Sheet 12)

MASTER COMMON LISTING

PAGE 13

CURRENT COMMON IS --

COMMON/COMMB3/COMMB3(485).CNTAR2(100)

CURRENT BLOCK IS COMMBY (481)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
NDETEC		1		
NSEC		2		
PAIR		3		
PALL		4		
PALLB		5		
PMONE		6		
PMONEB		7		
PSKY	2	8		
PSGSKY	2	10		
PSGP	2	12		
POEGL		14		
R	16.4	15		
RLOSS		79		
RS		90		
RT		91		
RN		92		
RH		93		
SNUM		94		
SEGL	20	95		
SEGLGT		105		
SIME		106		
SGENDX		107		
SGENDY		108		
STSTRT		109		
TZ		110		

Figure 7.1. Master Common Listings (Sheet 13)

MASTER COMMON LISTING

CURRENT BLOCK IS COMB3 (681)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
TARVEL		111		
TNUM		112		
TNS		113		
THT		114		
TSTART		115		
THETA	20	116		
TH		136		
TEMP		137		
TOETS	20	138		
TSAVE	20,2	158		
VISH		198		
VIGLEV		199		
VOEG		200		
WV		201		
WS		202		
WT		203		
WD		204		
XB	5,20	205		
XLZ	5	305		
XS		310		
XT		311		
XTAR	20	312		
XZ		332		
XOYNOL	10	333		
YB	5,20	343		
YLZ	5	443		
YS		448		
YT		449		
YTAR	20	450		
YZ		470		
YOYNOL	10	471		
ZZ		481		

Figure 7.1.1. Master Common Listings (Sheet 14)

MASTER COMMON LISTING

CURRENT BLOCK IS CNTAR2 (100)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
RAMLZ	20.5	1		

Figure 7.1. Master Common Listings (Sheet 15)

63

MASTER COMMON LISTING

CURRENT COMMON IS --
 COMMON/COMMON4/COMMON4(295)
 CURRENT BLOCK IS COMMON4 (292)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ISTATT	20,2	1		
ISTR	20,2	41		
ISTVDI	20,2	91		
STADR	20,2	121		
STRR	20,2	161		
STVD?	20,2	201		
SC4		241		
TC6	20	242		
CEPPAT		262		
CEPTAR	20	263		
CEPPH		293		
CEPPSS		284		
CEPPS		295		
ITNAV		286		
ITNAVS		297		
ITNVSS		288		
ITNAVH		299		
NNAV		290		
SDCEPP		291		
SDITNV		232		

Figure 7.1, Master Common Listings (Sheet 16)

CURRENT COMMON IS -- MASTER COMMON LISTING
 COMMON/COMM85/COMM95(50), COMM95(500), COMM95(500), COMM95(100)
 CURRENT BLOCK IS COMM85 (50) COMM95(500)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
AMR		1		
CS	2	2		
FM1		4		
FM2		5		
IOBST		6		
IST		7		
VBAR		8		
VEL	12	9		
XAMR		21		
NOCOM		22		
NREP		23		
PCINT		24		
SUCRAT		25		
TAMPNR		26		
TPCAD		27		
TPCAF		28		
TPCAS		29		
TTIME		30		
TTUSE		31		
APCAD		32		
APCAF		33		
APCAS		34		
ATTEMP		35		
DF1		36		
DF2		37		

Figure 7.1, Master Common Listings (Sheet 17)

CURRENT BLOCK IS COMB5 (50) MASTER COMMON LISTING PAGE 10

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
F		38		
IBDEAD		39		
ICOM		40		
IPOWR		41		
IICOM		42		
COMMO		43		
IPOVRT		44		
ICPER		45		
IXST		46		
HM		47		
PATJIS		48		
D1		49		
D2		50		

Figure 7.1, Master Common Listings (Sheet 18)

PAGE 19

MASTER COMMON LISTING

CURRENT BLOCK IS COMING (500)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
AAALL	500	1		

Figure 7.1. Master Common Listings (Sheet 19)

63

63

CURRENT BLOCK IS COMMS (5J0) MASTER COMMON LISTING

PAGE 28

VARIABLE POSITION TYPE DESCRIPTION
DIMENSION 500
KKTIME 1

Figure 7.1. Master Common Listings (Sheet 20)

PAGE 7

MASTER COMMON LISTING

CURRENT BLOCK IS COMNES (500)

DESCRIPTION

TYPE

POSITION

DIMENSION

VARIABLE

1

100

JJTIME

Figure 7.1, Master Common Listings (Sheet 21)

MASTER COMMON LISTING

CURRENT COMMON IS ---
 COMMON/LINSIG/LINSIG(1403)
 CURRENT BLOCK IS LINSIG (3403)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
LLMY		1		
DOMV		2		
ETA		3		
FLAMDA		4		
SAM	3,20	5		
ICL	50	65		
II	204,5	115		
IG7		1135		
IFRO		1136		
KND	50	1196		
LNRI		1187		
LSVJ		1198		
MICRI		1189		
HK2		1190		
NRSOIL		1191		
NRVVP		1192		
NUMVFG	204	1193		
SOIL		1194		
VEGC		1398		
VEG2		1399		
XBAR		1400		
XOB	1000	1401		
YBAR		1402		
VOR	1000	2402		
		2403		

Figure 7.1, Master Common Listings (Sheet 22)

MASTER COMMON LISTING

CURRENT COMMON IS --
 COMMON/MISC01/MISC01J001
 CURRENT BLOCK IS MISC01 (243)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
AMPHRA		1		
AMUN	4	2		
AMVTAB	21	6		
BSAREA		27		
CLAYMH		28		
CONCAP		29		
CPRAT	7	38		
EQUIP		37		
EXOEGT		38		
FINDEX		39		
FOOD		40		
FOODA		41		
FOODD		42		
FOODU		43		
FWRAT	7	44		
H20		51		
H20A		52		
H20D		53		
H20TD		54		
H20U		55		
HANDGM		56		
HTPLOT	58	57		
ICNT		107		
ICOMB		108		
IOVFL		109		

Figure 7.1, Master Common Listings (Sheet 23)

MASTER COMMON LISTING

CURRENT BLOCK IS MISC81 (243)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
INREP		110		
INREP1		111		
INREP2		112		
IREONE		113		
IRESUP		114		
ISCEN	7	115		
ITHULA		122		
ITIMPR		123		
KK		124		
LAMDAE		125		
MAXREO		126		
MMAX		127		
NCOPY		128		
NHANDG		129		
NHGA		130		
NHU		131		
NLFLAG		132		
NMA		133		
NMINES		134		
NNHJ		135		
NSWT		136		
P		137		
PO		138		
PAKWT		139		
PAKWT2		140		
PAKWT3		141		
PAKWT4		142		
PATROW		143		
PDAVG		144		
PDMAX		145		
POMIN		146		
PDPL0T	50	147		

Figure 7.1, Master Common Listings (Sheet 24)

CASE 21

MASTER COMMON LISTING

CURRENT BLOCK IS MISC81 (243)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
POTOT		137		
PEQUIP		198		
RAMU	4	199		
RFOOD		203		
RH20		204		
RHANDG		205		
RMOH		206		
RMINES		207		
RPE		208		
RPG		209		
RIIME		210		
SAMU	4	211		
SAMUTE	4	215		
SGAVG		219		
SGMAX		220		
SGMIN		221		
SGTOT		222		
SIGENG		223		
SIGGR		224		
SIGFFR		225		
STS		226		
T		227		
TO		228		
TAMUN		229		
TEQUIP		230		
THEETS		231		
WT	4	232		
WYS	4	236		
XP2		240		
XPJ		241		
XPAKWT		242		
PS		243		

Figure 7.1, Master Common Listings (Sheet 25)

Best Available Copy

MASTER COMMON LISTING

CURRENT COMMON IS --
 COMMON/OBSTAB/OBSTAB(55)
 CURRENT BLOCK IS OBSTAB (53)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
MSIG		1		
HTAU		2		
PSL		3		
MSIG		4		
WTAU		5		
XSIG		6		
XTAU		7		
XTAR2	20	8		
XSIAF		28		
YSIG		29		
VTAU		30		
VTAR2	20	31		
VSIAF		51		
ZSIG		52		
ZTAU		53		

Figure 7.1, Master Common Listings (Sheet 26)

MASTER COMMON LISTING

CURRENT COMMON IS --
 COMMON/OUTST1/OUTST1(120)
 CURRENT BLOCK IS QUIS1 J 1201

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
LOSD	20,2	1		
LOSR	20	41		
LOST	20,2	61		
LOSV	20	101		

Figure 7.1. Master Common Listings (Sheet 27)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/TARINT/TARINT(205)

CURRENT BLOCK IS TARINT (201)

PAGE 20

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
XGOAL	20	1		
YGOAL	20	21		
ISTART	20	41		
WCHNG	20	61		
ISAA	20	81		
ITAA	20	101		
ISVV	20	121		
ITVV	20	141		
IANCHS	20	161		
IANCHT	20	181		

Figure 7.1. Master Common Listings (Sheet 28)

CURRENT COMMON IS -- MASTER COMMON LISTING PAGE 29

COMMON/MISC82/MISC02(1500)
 CURRENT BLOCK IS MISC82 (597)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
DMOR		1		
DMORR		2		
JSA		3		
OSAA		4		
DYMT	9,3	5		
IDELA		32		
IDELB		33		
IDELC		34		
IDELD		35		
IDELE		36		
IDV		37		
ICE/BK		38		
IGRTO		39		
JCOMAX		40		
JCOMXX		41		
JCS		42		
JCSS		43		
JROMAX		44		
JROMXX		45		
JRS		46		
JRSS		47		
KREC	20	48		
LFLOJ		58		
MI		59		
MII		70		

Figure 7.1. Master Common Listing (Sheet 29)

CURRENT BLOCK IS MISCH2 (497) MASTER COMMON LISTING

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
NIDY		71		
NPAR		72		
RAV000		73		
RAVOID		74		
RFMR		75		
RFHRR		76		
RFSA		77		
RFSAA		78		
VTYP		79		
XAV000		80		
XAV010		81		
XOYN	200	82		
XE		292		
XEE		283		
XPPT		284		
XPPTT		295		
XSV		286		
YAV000		297		
YAV010		288		
YOYN	200	299		
YE		439		
YEE		490		
YPPT		431		
YPPTT		432		
YSV		433		
GSAPRX		494		
GSAPXX		435		
ITSTC		496		
NC04		437		

Figure 7.1, Master Common Listings (Sheet 30)

MASIER COMMON LISTING

CURRENT COMMON IS --

COMMON/USIB01/USIB01(110), USTAR1(200)

PAGE

CURRENT BLOCK IS USIB01 1 1001

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ANGID		1		
ADYMAX		2		
ADYMAX		3		
CMT	20	4		
GRECOG		24		
DBACK		25		
DOMHT		26		
ORMT	20	27		
OSTEP		47		
DRSY	20	48		
EMRNG		58		
FRCMVO	20	59		
FRCNVN	20	89		

Figure 7.1. Master Common Listings (Sheet 31)

MASTER COMMON LISTING

CURRENT BLOCK IS USTAR1 (200)

VARIABLE DIMENSION POSITION TYPE DESCRIPTION

GOALTX 10,20 1

Figure 7.1. Master Common Listings (Sheet 32)

CURRENT COMMON IS --
 COMMON/USIB02/USIB02(550).USTAR2(200)
 CURRENT BLOCK IS USIB02 (550)

MASTER COMMON LISTING

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
HLZ		1		
IOB		2		
ISEN	5	7		
ISENLZ		8		
IPREP		9		
IMOV	20	10		
ITMOV	20	30		
IIMAX	100.5	50		
		550		

Figure 7.1. Master Common Listings (Sheet 33)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/JSIB03/USIB03(265),USTAR3(200)
CURRENT BLOCK IS USIB03 (261)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
IDEV	20	1		
ISSOFF	5,20	21		
ISSON	5,20	121		
ITST	20	221		
ITSTOP	20	241		
ITZERO		261		

Figure 7.1. Master Common Listings (Sheet 35)

CURRENT BLOCK IS USTAR3 (200) MASTER COMMON LISTING

PAGE 36

VARIABLE DIMENSION POSITION TYPE DESCRIPTION

ITIMS 10.20 1

10000-000-00-00
Page 7-38

Figure 7.1, Master Common Listings (Sheet 36)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/USIB04/USIB04(500)

CURRENT BLOCK IS USIB04 (500)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ISTAY	100.5	1		

Figure 7.1. Master Common Listings (Sheet 37)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/USI005/USI005(500)

CURRENT BLOCK IS USI005 (500)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ITSTAY	100,5	1		

Figure 7.1. Master Common Listings (Sheet 38)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/USI806/USI806(500)

CURRENT BLOCK IS USI806 (500)

VARIABLE DIMENSION POSITION TYPE DESCRIPTION

ITARIV 100.5 1

Figure 7.1. Master Common Listings (Sheet 39)

(3)

MASTER COMMON LISTING

PAGE 40

CURRENT COMMON IS --

COMMON/USI007/USI007(400).USTAR4(300)

CURRENT BLOCK IS USI007 (478)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
IDONST		1		
KREGOL		2		
MODE		3		
NOB		4		
MCO	5	5		
NRMT		10		
NSENS		11		
NLZ		12		
NDECOV		13		
NTAR		14		
NFIX		15		
NMP	20	16		
NSTP	20	36		
NMCL	100,2	56		
NPLAN	5	256		
NRST		261		
RANMAX	20	262		
RSEN		282		
RLZ	5	283		
RCMIN	20	288		
RCMAX	20	308		
SC	6	328		
SEGMIN		334		
TZERO		335		
TDEBK	4	336		

16905-6008-R0-00
Page 7-42

Figure 7.1. Master Common Listings (Sheet 40)

MASTER COMMON LISTING

CURRENT BLOCK IS US1007 (478)

PAGE 41

18905-6005-R0-00

Page 7-43

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
TPREP				
TVEL	20	340		
TOMIN		341		
TSR		361		
TSS		362		
VELM		363		
MDAY	10.11	364		
MR		368		
		478		

Figure 7.1. Master Common Listings (Sheet 41)

MASTER COMMON LISTING

PAGE 42

CURRENT BLOCK IS USTAR4 (300)

VARIABLE DIMENSION POSITION TYPE DESCRIPTION

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
TC	10.20	1		
SOUND1	5.20	201		

16805-6008-R0-00

Page 7-44

Figure 7.1. Master Common Listings (Sheet 42)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
XBASE		1		
YBASE		2		
X1FREN		3		
X2FREN		4		
Y1FREN		5		
Y2FREN		6		

Figure 7.1, Master Common Listings (Sheet 43)

CURRENT BLOCK IS USTAR5 (1000) MASTER COMMON LISTING PAGE 44

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
XPLAN	100,5	1		
YPLAN	100,5	501		

Figure 7.1. Master Common Listings (Sheet 44)

MASTER COMMON LISTING

CURRENT COMMON IS --

COMMON/USIB10/USIB10(200)

CURRENT BLOCK IS USIB10 (31)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
ALLB		1		
ALLH		2		
ATTAR		3		
AA		4		
ATER		5		
AEG		6		
BE		7		
GR		8		
ITDRPH		9		
ITMNTA		10		
ITMTAR		11		
ITAGOS		12		
ITPLSQ		13		
ITPLSA		14		
PMC		15		
PMR		16		
PPLS		17		
RC		18		
RCTAR		19		
RTER		20		
REQ		21		
SCALE		22		
SPEC		23		
SGNTAB		24		
SGNTAM		25		

Figure 7.1, Master Common Listings (Sheet 45)

CURRENT BLOCK IS US1010 (311) MASTER COMMON LISTING PAGE 04

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
TBUR		26		
TMEATA		27		
VH		28		
VK		29		
VISMW		30		
VISM8		31		

Figure 7.1. Master Common Listings (Sheet 46)

CURRENT COMMON IS --

COMMON/USIB11/USIB11(20)

CURRENT BLOCK IS USIB11 (17)

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
IDENT		1		
MDC		2		
MDM		3		
NYC		4		
WTM		5		
MAXREP		6		
NBAY		7		
NRAD		8		
PT		9		
RNF		10		
RPOWR		11		
TPOWR		12		
TUSE		13		
XOBINS		14		
BETA		15		
BLIFE		16		
FREQ		17		

Figure 7.1. Master Common Listings (Sheet 47)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSM	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
CEPTAR	263	20			COMMB4
CLASS	5	5,16			LOGGIN
CLAYM	20				MISCB1
CLL	71				COMMB1
CLMT	1				LIMS16
CMT	4	20			USIB01
COMMO	43				COMMB3
CONCAP	29				MISCB1
CPRAT	30	7			MISCB1
CREGOG	24				USIB01
CR2	72	2,2			COMMB1
CR	70				COMMB1
CS	2	2			COMMB3
CT	69				COMMB1
DBACK	25				USIB01
DBINS	280				COMMB1
DBINT	281				COMMB1
DBSPEC	282	20			COMMB1
DF1	36				COMMB3
DF2	37				COMMB3
DMORR	2				MISCB2
DMOR	1				MISCB2
DMT	8	5,3			DATABB
DMMT	26				USIB01
DMV	2				LIMS16
DSAA	4				MISCB2
OSA	3				MISCB2
OSOROP	6				DLOGBL
DRICE	7				DATABB
DSENG	7				DLOGBL
DRMT	27	20			USIB01
DTDAMB	85				DLOGIN
DTDATT	86				DLOGIN
DTDEPL	9				DLOGBL
DRST	58	20			USIB01
DTFTS	87				DLOGIN
DTENGH	88				DLOGIN

Figure 7-2. Cross-reference of Common Variables (Sheet 2)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSM	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
BTENG	10				DLOGBL
BSPUR	8				DLOGBL
DSTEP	47				USIB01
DSM11	5				DATABB
DSM12	6				DATABB
DIPURH	89				DLOGIN
DIPUR	11				DLOGBL
DIMAIT	12				DLOGBL
DYMT	5	9.3			MISC02
D1	49				COMMB5
D2	50				COMMB5
D	76	204			COMMB1
EFSA	90				DLOGIN
ENRNG	68				USIB01
EOUT	302		204		COMMB1
ETA	3				LINSIG
EQUIP	37				MISC01
EXDEGT	38				MISC01
FLAMDA	4				LINSIG
FINDEX	39				MISC01
FM1	4				COMMB5
FM2	5				COMMB5
FRAMB	91				DLOGIN
FRATT	92				DLOGIN
FOODA	41				MISC01
FOODD	42				MISC01
FOODU	43				MISC01
FOOD	40				MISC01
FRCHVD	69	20			USIB01
FRCHVN	89	20			USIB01
FTHREL	506		7		COMMB1
FWRAT	44				MISC01
F0HREL	507				COMMB1
F	38				COMMB5
GAM	5	3.20			LINSIG
GMAX	93				DLOGIN
GOALTX	1	10.20			USTARI

Figure 7-2. Cross-reference of Common Variables (Sheet 3)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSM	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
GOALTY	1	10.20			USTRZ
GSAPRR	114				DLOGIM
GSAPRX	494				MISCB2
GSAPXX	495				MISCB2
GS	63				DLOGBL
G1OUT	500		204		COMMB1
G2OUT	1		204		COMMB2
G3OUT	205		204		COMMB2
HANDGM	56				MISCB1
HB	87		9		DATABB
NH	47				COMMB5
HLZ	1				USI002
HMT	96		5.3		DATABB
H1TAU	2				OBSTAB
HSIG	1				OBSTAB
H1PLOT	57		50		MISCB1
HS	409				COMMB2
HT	410				COMMB2
H20A	52				MISCB1
H20D	53				MISCB1
H20TD	54				MISCB1
H20U	55				MISCB1
H20	51				MISCB1
H	23		16.4		DATABB
IDDEAD	39				COMMB5
IDARK	14				DLOGBL
IDAY	414				COMMB2
IANGMS	161		20		TARINT
IANCHT	181		20		TARINT
IAOR	101		20,2		CHYAR1
IAS	506				COMMB2
IAT	505				COMMB2
ICH	181		20		CHYAR1
IDELA	32				COMMB2
IDELB	33				MISCB2
IDELC	34				MISCB2
IDELD	35				MISCB2

Figure 7-2. Cross-reference of Common Variables (Sheet 4)

3

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
IDELE	36				MISC82
IDEITS	508	20			COMB82
IDET	1	20			USI803
IDE	411				COMB82
ICL	65		5		LINSIG
ICMT	107				MISC81
ICOMB	108				MISC81
ICON	40				COMB85
ICOUNT	13				DLOG8L
ICPER	45				COMB85
IDIREC	94				JLOGIM
IDMST	1				USI807
IDUM1	95				DLOGIM
IDUM2	96				DLOGIM
IFFF	80				DLOG8L
IDYFL	109				MISC81
IFFSTO	74				DLOG8L
IDYOL	551				COMB82
IDV	37				MISC82
IFIRST	483	20			COMB82
IGEN	443	20			COMB82
IGETBK	38				MISC82
IFLAG	15				DLOG8L
IGRID	39				MISC82
IMAN	72				DLOG8L
II	115	204.5			DLOG8L
IOBST	6				LINSIG
IOB	2	5			COMB85
ILZAVL	418	5			USI802
IMOV	10	20			COMB82
IMP	463	20			COMB82
IMV	30	20			USI8C2
INREP1	111				MISC81
INREP2	112				MISC81
INREP	110				MISC81
ISAA	81				IARINT
ISAO	412				COMB82

Figure 7-2. Cross-reference of Common Variables (Sheet 5)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
ISA	201		20		CNTAR1
IPOSE	16				DLOGBL
IPOVRT	44				COMB2
IPOVR	41				COMB5
ITAA	101		20		TARINT
ITAD	413				COMB2
IPREP	9				USI002
IRECOC	201		20.2		CNTAR1
ITAREM	20				DLOGBL
ITARG	1		20.5		CNTAR1
ITARIV	1		100.5		USI006
IROME	113				MISC01
IRESUP	114				MISC01
ISGEN	115		7		MISC01
ITA	241		20		CNTAR1
ISECT	111		20		DATA00
IENLZ	0				USI002
ISEN	7				USI002
ISET	17				DLOGBL
IP	550				COMB2
ITCOM	42				COMB5
ITGRIO	549				COMB2
ITMULA	122				MISC01
ITIME	417				COMB2
ITIMPR	123				MISC01
ITIMS	1		10.20		USTAR3
ISSOFF	21		5.20		USI003
ISSON	121		5.20		USI003
ISTADI	1		20.2		COMB4
ISTALL	01				DLOGBL
ISTART	76				DLOGBL
ISTART	41		20		TARINT
ISTAY	1		100.5		USI004
ISTUPE	16				DLOGBL
ISTP	552		20		COMB2
ISTRV	41		20.2		COMB4
ISTU	70				DLOGBL

Figure 7-2. Cross-reference of Common Variables (Sheet 6)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
IBTVDY	01	20,2			COMMB4
IBY	7				COMMB5
IBY	1135				LINSIG
ISUIT	19				DLOGBL
ISVD	503				COMMB2
ISVV	121	20			TARINT
ISV	221	20			CMTAR1
IR	61				DLOGBL
ITMAX	550				USIB02
ITNOV	50	100,5			USIB02
ITHAVM	289				COMMB4
ITHAVS	287				COMMB4
ITHAV	286				COMMB4
ITNVSS	288				COMMB4
ITRC	1136		50		LINSIG
ITSTAY	1	100,5			USIB05
ITSTC	496				MISC02
ITSTOP	241	20			USIB03
ITSIRT	415				COMMB2
ITST	221	20			USIB03
ITVD	504				COMMB2
ITVEG	423	20			COMMB2
ITVV	141	20			TARINT
ITV	261	20			CMTAR1
ITYPE	528	20			COMMB2
ITZERO	261				USIB03
IMC	507				COMMB2
IV	548				COMMB2
IV02	141	20,2			CMTAR1
IXST	46				COMMB5
IZ	416				COMMB2
JCOMAX	40				MISC02
JCOMXX	41				MISC02
JCSS	43				MISC02
JCS	42				MISC02
J60	21				DLOGBL
JMAN	73				DLOGBL

Figure 7-2. Cross-reference of Common Variables (Sheet 7)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
JIT	572				COMMB2
JJTIME	1	100			COMMB2
JTACT	23				OLOGBL
JROMAX	44				MISC02
JROMIX	45				MISC02
JRSS	47				MISC02
JRS	46				MISC02
JSP	22				OLOGBL
KDEFOP	75				OLOGBL
KEY	573				COMMB2
KKTIME	1	500			COMMB2
KMD	1186				LINSIG
KK	124				MISC01
KTACT	24				OLOGBL
KREGOL	2				USIB07
KREC	48	20			MISC02
LAMDAE	125				MISC01
LFLAG	594	20			COMMB2
LFLAGJ	60				MISC02
LMRI	1187				LINSIG
LOSD	1	20.2			OUTST1
LOSR	41	20			OUTST1
LOST	61	20.2			OUTST1
LOSV	101	20			OUTST1
LSVS	1188				LINSIG
LZTAR	574	20			COMMB2
MAXREO	126				MISC01
RENOP	25				OLOGBL
MENSP	26				OLOGBL
MICRI	1189				LINSIG
MGS	62				OLOGAL
MI	70				MISC02
MISS	97				OLOGIM
MMAX	127				MISC01
MHB	614	5			COMMB2
MI	69				MISC02
MODE	3				USIB07

Figure 7-2. Cross-reference of Common Variables (Sheet 8)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
NS	619				COMMB2
NT	620				COMMB2
NDAY	642				COMMB2
NBI	621				COMMB2
NDECOY	13				USI007
NDETEC	1				COMMB3
NCON	497				MISCB2
NCOPY	120				MISCB1
NGO	5		5		USI007
NHANDG	129				MISCB1
NFIX	15				USI007
NHGA	130				MISCB1
NIDY	71				MISCB2
NGS	27				DLOGBL
NHRMIN	20				DLOGBL
NHU	131				MISCB1
NMA	133				MISCB1
NMAY	290				COMMB4
NFLAG	132				MISCB1
NMINES	134				MISCB1
NPAR	72				MISC32
NOB	4				USIA07
NOCH	622		20		COMMB2
NOCOM	22				COMMB5
NLZ	12				USI007
NNHU	135				MISCB1
NMP	16		20		USI007
NPLAN	256		5		USI007
NTAR	14				USIA07
NREP	23				COMMB5
NSECT	98				DLOGIM
NSEC	2				COMMB3
NSENS	11				USIA07
NRMP	1191				LINSIG
NRMT	10				USI007
NRSOIL	1192				LINSIG
NRST	261				USI007

Figure 7-2. Cross-reference of Common Variables (Sheet 9)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
NRVP	1193				LIMSIG
NSTP	36		20		USI007
NSMT	136				MISC01
MMCL	56				USI007
MUMVEG	1194		100, 2		LIMSIG
OLOVEL	68		204		DLOGBL
OLYACK	69				DLOGBL
OLVULX	66				DLOGBL
OLVULY	67				DLOGBL
OLXOEP	64				DLOGBL
OLYDEP	65				DLOGBL
PAIR	3				COMM03
PDAVG	164				MISC01
PAKNT2	160				MISC01
PAKNT3	141				MISC01
PAKNT4	142				MISC01
PAKNT	139				MISC01
PALLO	5				COMM03
PALL	6				COMM03
PATDIS	48				COMM05
PATROM	163				MISC01
PCINT	24				COMM05
PDEGL	14				COMM03
PDMAX	145				MISC01
PDIM	166				MISC01
POPLOT	167		50		MISC01
PDIOI	197				MISC01
PEQUIP	198				MISC01
PHI	29				DLOGBL
PNOMER	7				COMM03
PNONE	6				COMM03
PP1	99				DLOGIN
PP2	100				DLOGIN
PP3	101				DLOGIN
PP4	102				DLOGIN
PSGP	12		2		COMM03
PSGSKY	10		2		COMM03

Figure 7-2. Cross-reference of Common Variables (Sheet 10)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	DEFINITION	BLOCK NAME
PSKY	8	2		COMM83
PSL	3			OBSTAB
PS	243			MISC81
PURVEL	30			DLOG8L
P8	138			MISC81
P5	113			DLOGIN
P	137			MISC81
Q1	103			DLOGIN
Q2	104			DLOGIN
Q3	105			DLOGIN
RAOV1	32			DLOG8L
RADY2	33			DLOG8L
RAM8	106			DLOGIN
RAMIN	107			DLOGIN
RAMU	199	4		MISC81
RANLZ	1	20,5		CMTAR2
RANMAX	262	20		USIB07
RATI	108			DLOGIN
RAVODD	73			MISC82
RAVOID	74			MISC82
RCMAX	306	20		USIB07
RCMIN	289	20		USIB07
REFS	109			DLOGIN
REF	274	16,3		DATAB8
RHANDG	205			MISC81
RC	34			DLOG8L
RFHORR	76			MISC82
RFHOR	75			MISC82
RFOOD	203			MISC81
RFSAA	74			MISC82
RFSA	77			MISC82
RHOH	206			MISC31
RHO	131	16,4		DATAB8
RH20	204			MISC81
RMAX	210	16,4		DATAB8
RH	83			COMM83
RLOSS	79			COMM83

Figure 7-2. Cross-reference of Common Variables (Sheet 11)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
RHINES	207				MISC81
ROBS	110				DLOGIN
RLZ	203		5		USIB07
RMTHAX	195		5,3		DATAB8
RPE	206				MISC81
RPG	209				MISC81
RM	82				COMMB3
RSEN	202				USIB07
RSP	111				DLOGIN
RTIME	210				MISC81
RS	35				DLOG8L
RS	80				COMMB3
RT	81				COMMB3
RZ	112				DLOGIN
R	15	16,4			COMMB3
K	31				DLOG8L
SANUTE	215		4		MISC81
SAMU	211		4		MISC81
SOCEPP	291				COMMB4
SECT	322	2,4,2			DATAB8
SDITMV	292				COMMB4
SGAVG	219				MISC81
SEGLGT	105				COMMB3
SEGL	85		20		COMMB3
SEGMIN	334				USIB07
SC4	241				COMMR4
SC	328		6		USIB07
SGENDX	107				COMMB3
SGENDY	108				COMMB3
SGMAX	220				MISC81
SGMIN	221				MISC81
SGTOT	222				MISC81
SF	36				DLOG9L
SIGENG	223				MISC81
SIGFFR	225				MISC81
SIGGR	224				MISC81
SL1	11				DATAB2

Figure 7-2. Cross-reference of Common Variables (Sheet 12)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
SL2	12				DATA82
SOILF	13	2,0			DATA82
SOIL	1390				LIMSIG
SNUN	84				COMB83
SOUND	201	5,20			USTAR4
STADR	121	20,2			COMB84
SVADM	37				DLOG8L
SUGRAT	25				COMB85
STIME	106				COMB83
STRR	161				COMB84
STSTRT	109	20,2			COMB83
STS	226				MISC81
STVDR	201	20,2			COMB84
TACKOP	38				DLOG8L
TAMPHR	26				COMB85
TANUN	229				MISC81
TARVEL	111				COMB83
TARY	79				DLOG8L
TDEBK	336		4		USIB07
TOETS	138	20			COMB83
TDMIN	361				USIB07
TC6	242		20		COMB84
TC	1	10,20			USTAR4
TEMP	137				COMB83
TEQUIP	230				COMB81
THETA	116		20		COMB83
THETS	231				MISC81
THS	113				COMB83
THT	114				COMB83
TH	136				COMB81
THR	29		10,3		DATA82
TPCAD	27				COMB85
TPCAF	28				COMB85
TPCAS	29				COMB85
TNUM	112				COMB83
TSAVE	158		20,2		COMB83
TPREP	340				USIB07

Figure 7-2. Cross-reference of Common Variables (Sheet 13)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
TYTIME	30				COMMB5
TSR	362				US1807
TS	363				US1807
TSTART	115				COMMB3
TVEL	341		20		US1807
TTUSE	31				COMMB5
TZERO	335				US1807
TZ	110				COMMB3
TO	226				MISC81
T	227				MISC81
VBAR	8				COMMR5
VADM	39				DLOGBL
VCEAL	40				DLOGBL
VCHNG	61		20		TARINT
VDEG	200				COMMB3
VCOV	41				DLOGBL
VEGC	338		0.16		COMMB3
VEGC	1399				DLOGBL
VEGF	83		16		DATA8
VEG1	1400				LIMSIG
VELM	364		4		US1807
VELOP	42				DLOGBL
VEL	9		12		COMMB5
VIGLEV	199				COMMB3
VISLUM	466		0.8		DATA8
VISM	198				COMMB3
VOBS	43				DLOGBL
VTYP	79				MISC82
WDAY	368		10,11		US1807
WA	46				DLOGBL
WB	47				DLOGBL
WD	204				COMMB3
WMT	594		5,3		DATA8
WTAU	5				OBSTAR
WSIG	4				OBSTAR
WR	478				US1807
WYS	236				MISC81

Figure 7-2. Cross-reference of Common Variables (Sheet 14)

SIAF,T100,MT1.
TASK,TN=SIAF,TA=13954,OS=ATDSOPF,TR=TS.
REQUEST,SIAF00,*AM.
REQUEST,SIAF01,*AM.
REQUEST,SIAF02,*AM.
REQUEST,SIAF03,*AM.
REQUEST,SIAF04,*AM.
REQUEST,SIAF05,*AM.
REQUEST,SIAF06,*AM.
REQUEST,SIAF07,*AM.
REQUEST,SIAF08,*AM.
REQUEST,BTPKS,*AM.
REQUEST,NLINP,*AM.
REQUEST,ZINP,*AM.
REQUEST,CONVRT,*AM.
REQUEST,MAPGEN,*AM.
REQUEST,ROTATE,*AM.
VSN,SIAF=0000.
REQUEST,SIAF,*HY.
COPYBR,SIAF,SIAF00.
COPYBR,SIAF,BTPKS
COPYBR,SIAF,SIAF01.
COPYBR,SIAF,SIAF02.
COPYBR,SIAF,SIAF03.
COPYBR,SIAF,SIAF04.
COPYBR,SIAF,SIAF05.
COPYBR,SIAF,SIAF06.
COPYBR,SIAF,SIAF07.
COPYER,SIAF,SIAF08.

Figure 7.4, Creation of Source Files (Sheet 1)

SKIPF,SIAF,9.
COPYBR,SIAF,NLINP.
COPYBR,SIAF,ZINP.
COPYBR,SIAF,CONVRT.
COPYBR,SIAF,MAPGEN.
COPYBR,SIAF,ROTATE.
CATALOG,SIAF00,SIAF00,ID=SIAF,RP=100,CY=1.
CATALOG,BTPKS,BTPKS,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF01,SIAF01,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF02,SIAF02,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF03,SIAF03,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF04,SIAF04,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF05,SIAF05,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF06,SIAF06,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF07,SIAF07,ID=SIAF,RP=100,CY=1.
CATALOG,SIAF08,SIAF08,ID=SIAF,RP=100,CY=1.
CATALOG,NLINP,NLINP,ID=SIAF,RP=100,CY=1.
CATALOG,ZINP,ZINP,ID=SIAF,RP=100,CY=1.
CATALOG,CONVRT,CONVRT,ID=SIAF,RP=100,CY=1.
CATALOG,MAPGEN,MAPGEN,ID=SIAF,RP=100,CY=1.
CATALOG,ROTATE,ROTATE,ID=SIAF,RP=100,CY=1.
EOR
EOI

Figure 7.4, Creation of Source Files (Sheet 2)

SIAF,T400.
TASK,TN=SIAF,TA=13954,OS=ATDSDPF,TR=TS.
REQUEST,NVBFT0,*AM.
REQUEST,NVBFT1,*AM.
REQUEST,NVBFT2,*AM.
REQUEST,NVBFT3,*AM.
REQUEST,NVBFT4,*AM.
REQUEST,NVBFT5,*AM.
REQUEST,NVBFT6,*AM.
REQUEST,NVBFT7,*AM.
REQUEST,NVBFT8,*AM.
ATTACH,SIAF00,SIAF00,ID=SIAF.
ATTACH,BTPKS,BTPKS,ID=SIAF.
ATTACH,SIAF01,SIAF01,ID=SIAF.
ATTACH,SIAF02,SIAF02,ID=SIAF.
ATTACH,SIAF03,SIAF03,ID=SIAF.
ATTACH,SIAF04,SIAF04,ID=SIAF.
ATTACH,SIAF05,SIAF05,ID=SIAF.
ATTACH,SIAF06,SIAF06,ID=SIAF.
ATTACH,SIAF07,SIAF07,ID=SIAF.
ATTACH,SIAF08,SIAF08,ID=SIAF.
FTN,I=SIAF00,B=NVBFT0.
COMPASS,I=BTPKS,B=NVBFT0.

Figure 7.5, Creation of Object Files (Sheet 1)

FTN,I=SIAF01,B=NVBFT1.
FTN,I=SIAF02,B=NVBFT2.
FTN,I=SIAF03,B=NVBFT3.
FTN,I=SIAF04,B=NVBFT4.
FTN,I=SIAF05,B=NVBFT5.
FTN,I=SIAF06,B=NVBFT6.
FTN,I=SIAF07,B=NVBFT7.
FTN,I=SIAF08,B=NVBFT8.
CATALOG,NVBFT0,NVBFT0,ID=SIAF,CY=1.
CATALOG,NVBFT1,NVBFT1,ID=SIAF,CY=1.
CATALOG,NVBFT2,NVBFT2,ID=SIAF,CY=1.
CATALOG,NVBFT3,NVBFT3,ID=SIAF,CY=1.
CATALOG,NVBFT4,NVBFT4,ID=SIAF,CY=1.
CATALOG,NVBFT5,NVBFT5,ID=SIAF,CY=1.
CATALOG,NVBFT6,NVBFT6,ID=SIAF,CY=1.
CATALOG,NVBFT7,NVBFT7,ID=SIAF,CY=1.
CATALOG,NVBFT8,NVBFT8,ID=SIAF,CY=1.
EOR
EOI

Figure 7.5, Creation of Object Files (Sheet 2)

SIAF,T700.
TASK,TN=SIAF,TA=13954,OS=ATDSDPF,TR=TS.
ATTACH,NVBFT0,NVBFT0,ID=SIAF.
ATTACH,NVBFT1,NVBFT1,ID=SIAF.
ATTACH,NVBFT2,NVBFT2,ID=SIAF.
ATTACH,NVBFT3,NVBFT3,ID=SIAF.
ATTACH,NVBFT4,NVBFT4,ID=SIAF.
ATTACH,NVBFT5,NVBFT5,ID=SIAF.
ATTACH,NVBFT6,NVBFT6,ID=SIAF.
ATTACH,NVBFT7,NVBFT7,ID=SIAF.
ATTACH,NVBFT8,NVBFT8,ID=SIAF.
ATTACH,MLINP,MLINP,ID=SIAF.
ATTACH,ZINP,ZINP,ID=SIAF.
RFL,150000.
LOAD,NVBFT0.
LOAD,NVBFT1.
LOAD,NVBFT2.
LOAD,NVBFT3.
LOAD,NVBFT4.
LOAD,NVBFT5.
LOAD,NVBFT6.
LOAD,NVBFT7.
LOAD,NVBFT8.

Figure 7.6, Execution of Model (Sheet 1)


```
NOGO  
RFL,232000.  
MNALPH.  
EXIT.  
DMP,232000.  
EOR  
$NAML1  
      (REVISIONS TO NAMELIST NAML1)  
SEND  
$NAML2  
      (REVISIONS TO NAMELIST NAML2)  
SEND  
$NAML3  
      (REVISIONS TO NAMELIST NAML3)  
SEND  
$NAML4  
      (REVISIONS TO NAMELIST NAML4)  
SEND  
EOR  
EOI
```

Figure 7.6, Execution of Model (Sheet 2)

8.0 SIAF RELIEF MODEL VALIDATION

8.1 PURPOSE

The purpose of this discussion is to describe the method and results of simulating line of sight experiments to demonstrate the validity of: 1) the line of sight calculations; and 2) the mathematical concept of macro-relief representation in the SIAF Terrain Submodel. The raw data used in the simulation was taken from field measurements at nine different locations in the Hunter-Liggett Military Reservation. The experiment measures line of sight data with respect to macro-relief only; the effects due to vegetation and micro-relief features are neglected.

8.2 HUNTER-LIGGETT FIELD EXPERIMENT

8.2.1 Purpose

The primary purpose of the field experiment was to gather actual line of sight data concerning terrain macro-relief. The line of sight experiments were conducted at nine locations within the map section shown in Figure 8.1.

8.2.2 Equipment

The experiments required three pieces of equipment. A compass was used to determine direction, a one-hundred meter rope, graduated in five meter intervals was used to measure surface distance, and a pair of walkie-talkies was used to relay information.

8.2.3 Methodology:

The typical procedure undertaken is depicted in Figure 8.2. An observer would stand at an easily identifiable point (i.e., landmarks, roads, peaks, saddlepoints, etc.) with a compass and walkie-talkie. One end of the hundred-meter rope is held by the observer. Another individual, designated as the "target", moves away from the observer holding the other end of the rope. The target is also equipped with a walkie-talkie. The target continues to walk away from the stationary observer, until only the target's head is visible (to the observer) due to the interruption of the line of sight by the ground. The observer and target are in radio communication, so that the location of the target at the time of line of sight interruption is established accurately.

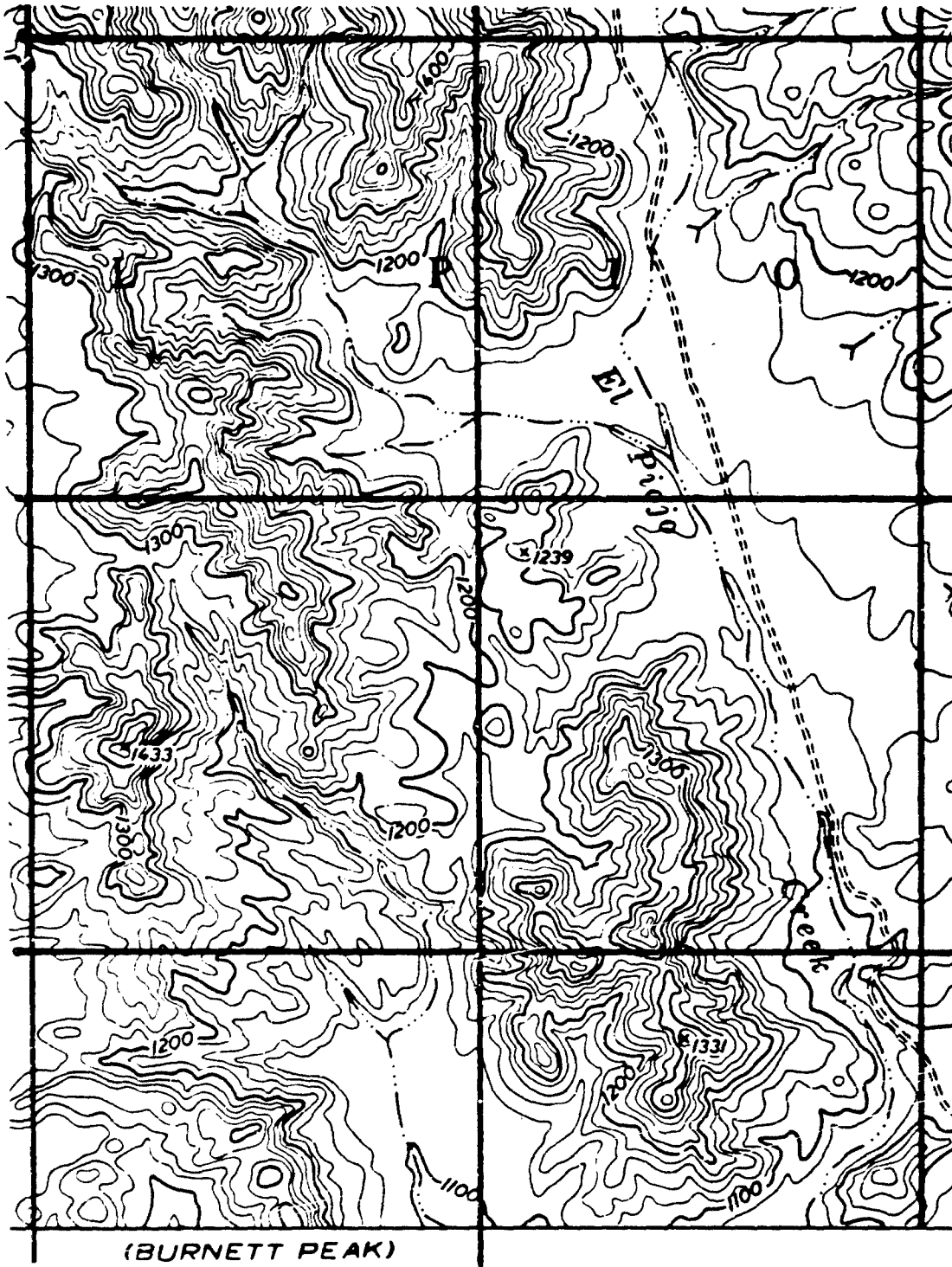


Figure 8.1, Hunter-Liggett Test Area



Figure 8.2, LOS Experimental Procedure

The procedure was repeated at approximately every fifteen degrees of arc, at which time a third individual would record the heading, and the "surface distance" between the observer and target. By "surface distance" we mean the distance traced out by the rope over the curvature of the ground. This is to be distinguished from the "range distance," which is the distance between observer and target when the line of sight is projected onto the grid plane of zero altitude. See Figure 8.3 for the distinction. This procedure continued over a three hundred and sixty degree sweep about the observer, whenever the terrain permitted.

Line of sight data was collected at nine different locations. At each site, several direction headings and the corresponding surface distances were recorded. The nine locations are shown in Figure 8.1, and the experimental data is displayed in Figure 8.4.

8.2.4 Field Measurement Errors

In conducting an experiment of this type, four sources of error are inherent and must be taken into consideration using the data for validation purposes.

- Location Error: Exact determination of the observer's position (grid coordinates) is impossible. Minimizing the effects of this type of error was achieved basically by choosing observer positions near relief landmarks such as roads, peaks, saddle-points, and intersections.
- Compass Error: Compass readings are subject to errors due to alignment, sighting, and reading errors. An additional error source is in the estimation of magnetic north with respect to grid north. It is estimated that the combined effects of such errors amounts to $\pm 2^{\circ}$ error.
- Linear Measurement Error: All distances recorded on a map are given for a grid plane (of zero altitude) normal to any given elevation. The experiment, however, was conducted around sloping, hilly areas. Thus, the measured distance between the observer and target is the sloping surface ("slant") distance, and will be in error as a function of the distance and the difference in elevation between them. An approximation

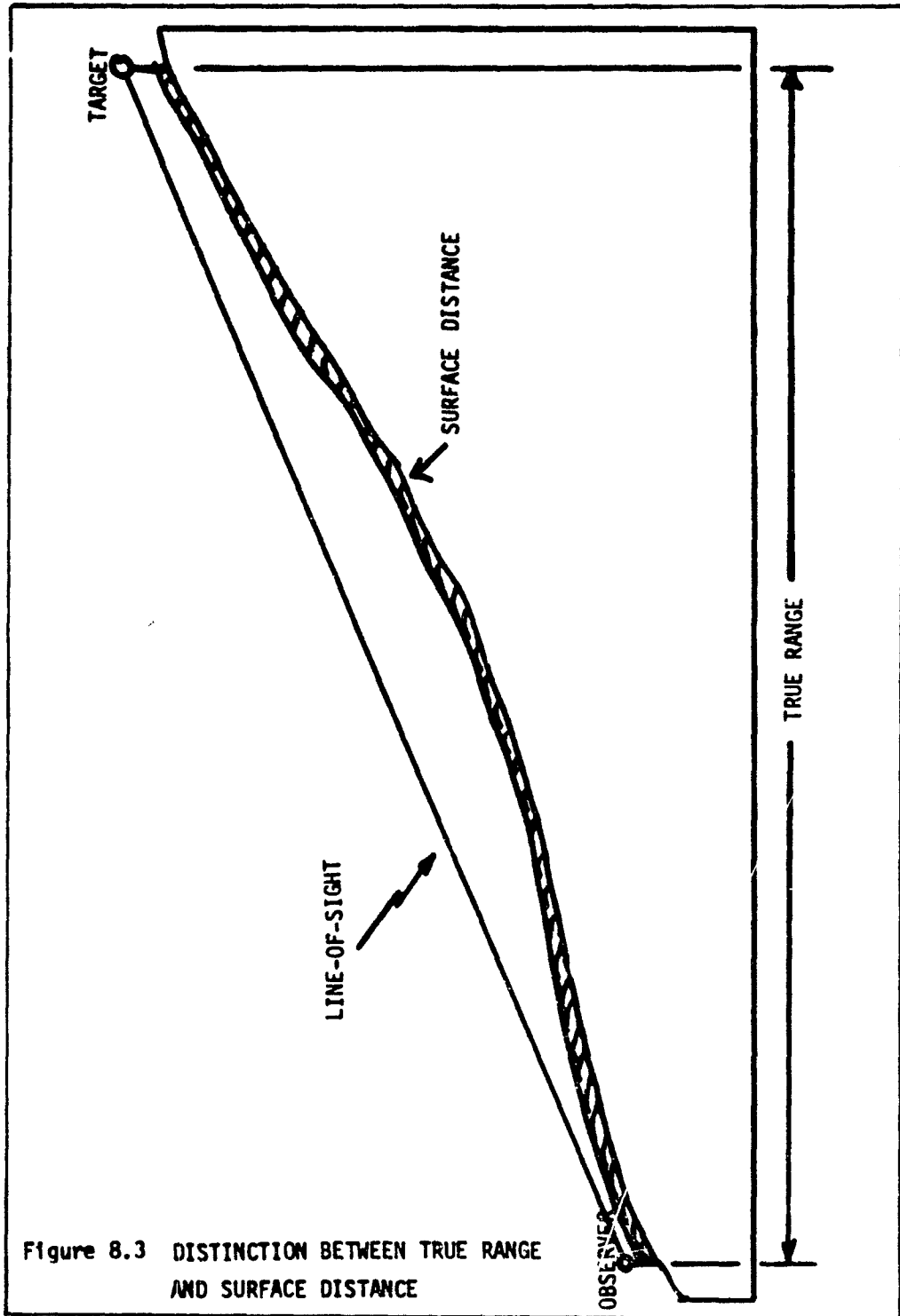


Figure 8.3 DISTINCTION BETWEEN TRUE RANGE AND SURFACE DISTANCE

	POINT 1	POINT 2	POINT 3	POINT 4	POINT 5	POINT 6	POINT 7	POINT 8	POINT 9
MEAS 1	25m, 40°	71m, 85°	26m, 0°	31m, 5°	27m, 30°	60m, 115°	175m, 216°	65m, 100°	139m, 51°
MEAS 2	71m, 115°	65m, 265°	29m, 40°	31m, 15°	29m, 68°	63m, 125°	145m, 223°	60m, 115°	108m, 817
MEAS 3	50m, 300°	23m, 355°	28m, 55°	35m, 30°	28m, 108°	61m, 148°	172m, 229°	67m, 136°	108m, 94°
MEAS 4			18m, 98°	35m, 40°	24m, 147°	68m, 150°	198m, 234°	88m, 182°	109m, 116°
MEAS 5			36m, 122°	66m, 70°	42m, 190°	78m, 158°		81m, 162°	110m, 126°
MEAS 6			47m, 132°	79m, 82°	18m, 171°	65m, 165°		67m, 174°	118m, 147°
MEAS 7			35m, 180°	86m, 90°	30m, 252°	49m, 188°		57m, 185°	249m, 166°
MEAS 8			33m, 217°	63m, 106°	60m, 271°	55m, 190°		57m, 205°	388m, 176°
MEAS 9			44m, 247°	37m, 125°	89m, 350°				281m, 188°
MEAS 10			90m, 290°	29m, 152°					137m, 203°
MEAS 11			63m, 295°	28m, 170°					169m, 215°
MEAS 12			38m, 313°	47m, 240°					104m, 229°
MEAS 13			30m, 345°	35m, 270°					113m, 250°
MEAS 14				32m, 290°					106m, 270°
MEAS 15				35m, 322°					125m, 279°
MEAS 16				35m, 350°					150m, 289°
MEAS 17									176m, 295°

Figure 8.4, Field Data (Hunter Liggett)

of this type of error is given by $D_E = D_M - D_M \cos(\theta)$, where D_E is the error in the distance measurement, D_M is the actual measured distance, and θ is the angle of elevation between observer and the target.

- **Vegetation:** As stated earlier, the intent of the experiment was to validate the SIAF model using line of sight verdicts with respect to macro-relief only. The effects of vegetation on line of sight were ignored. However, the presence of grass, sometimes several feet in height, could have introduced error into the measurements. This type of error is dependent on the density and height of the grass. The distance at which the line of sight is lost tends to be less in the presence of grass than otherwise. The effect of this error was minimized by choosing observer locations having very little vegetation (grass having negligible height) whenever possible.

8.3 ELEMENTS OF SIAF MODEL USED IN VALIDATION

8.3.1 Mathematical Representation at Macro-Relief in SIAF Model

The SIAF model utilizes a grid concept to describe macro-relief. Within each grid square a continuous surface is mathematically represented by a quadratic surface weighting all four corner elevation points. A region under consideration is assumed to be sufficiently small, so that effects due to earth's curvature are neglected, (i.e., a flat earth assumption is made, allowing use to use surface altitudes given by topographical maps). At each grid point, the earth's surface is specified by its altitude. Altitude data is available for grid resolutions as fine as 12.7 meters. The surface at nongrid points are determined as a weighted average of the four altitudes at the corner points of the grid square in which the point lies.

Consider Figure 8.5. Grid lines are defined by

$$\begin{aligned}x_j &= (j-1)\Delta x \\ y_k &= (k-1)\Delta y\end{aligned}$$

where Δx and Δy are grid square dimensions. The j, k^{th} rectangle is bounded by the grid lines ($x=x_j, y=y_k, x=x_{j+1}, y=y_{k+1}$). The surface within the j, k^{th} grid square, as shown in Figure 8.5, is determined in the following manner where $z_{j,k}, z_{j,k+1}, z_{j+1,k}$ and $z_{j+1,k+1}$ are the input

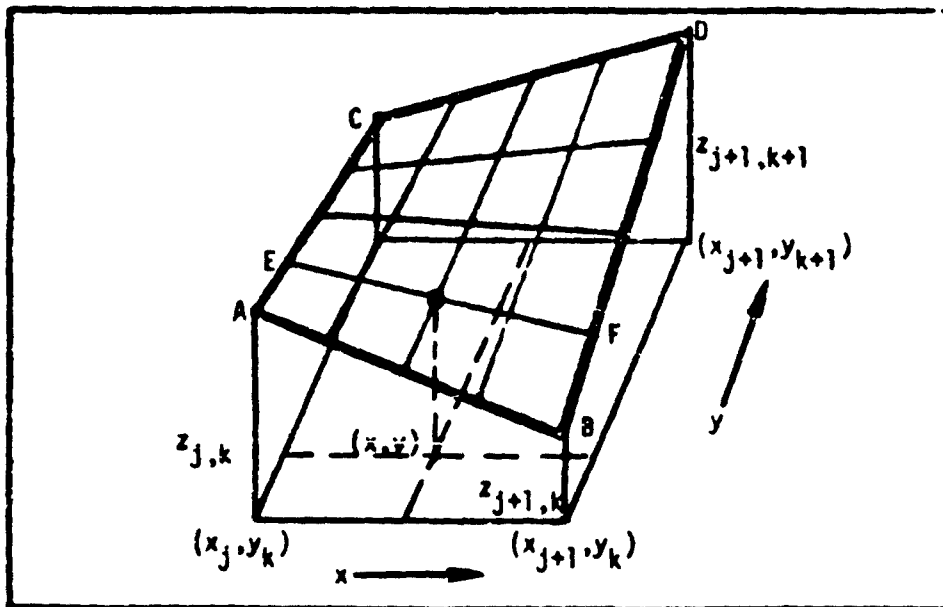


Figure 8.5, Surface Within j, k^{th} Rectangle

altitudes of the four corner points:

$$\text{Altitude on Line AB: } z_k(x) = \left[z_{j,k} + \frac{x-x_j}{x_{j+1}-x_j} (z_{j+1,k} - z_{j,k}) \right]$$

$$\text{Altitude on Line CD: } z_{k+1}(x) = \left[z_{j,k+1} + \frac{x-x_j}{x_{j+1}-x_j} (z_{j+1,k+1} - z_{j,k+1}) \right]$$

Altitude on Line EF (weighted average):

$$z(x,y) = \left\{ z_k(x) + \frac{y-y_k}{y_{k+1}-y_k} [z_{k+1}(x) - z_k(x)] \right\}$$

8.3.2 SI AF Subroutines Used

The subroutine LOSVEG is responsible for the line of sight calculations in the SI AF model. This subroutine is called by the subroutine DETERR. DETERR calculates intervisibility between any pair of points on the terrain for prone and upright positions of both the observer and the target. This intervisibility is characterized in terms of line of sight obstructions and various probabilities of cover and concealment. Cover and concealment are provided by micro-relief features and vegetation. Since the purpose of the field experiment was to consider macro-relief only, the line of sight experiments were performed in areas characterized by little or negligible amounts of micro-relief objects and vegetation. Thus the effects of cover and concealment on intervisibility are neglected in the simulation, and DETERR was modified to do this. Furthermore, for each pair of points on the terrain locating the observer and target, four lines of sight are considered by the subroutine DETERR.

- 1) "Head to head", i.e., observer and observed both upright.
- 2) "Head to foot", i.e., observer upright and observed prone.
- 3) "Foot to head", i.e., observer prone and observed upright.
- 4) "Foot to foot", i.e., observer and observed both prone.

Since the field experiments considered only "head to head" lines of sight, DETERR was modified such that the simulation considered only that case.

The primary purpose of LOSVEG is to determine if the line of sight between an observer and target is obstructed by the intervening land surface (macro-relief). It accomplishes this by projecting the line of sight onto a grid plane (of zero altitude). Every intersection of the line of sight with horizontal and vertical grid crossings partitions the line of sight into segments. The subroutine checks for line of sight interruptions within or at the end-point of a given segment. This is done segment by segment, beginning with the segment containing the observer's position, until the line of sight is interrupted. If no interruption occurs the fraction of target height and the fraction of observer height covered by macro-relief is calculated; the routine continues on to compute cumulative distance through vegetation. It checks to see whether the cumulative distances through certain vegetation feature types is great enough to cause concealment of the target. This cumulative vegetation check, however, is of no concern to this test.

Detailed documentation and flow charts of LOSVEG and DETERR can be found in Volumes II and V respectively of the SIAF Users Manual.

8.4 COMPUTER SIMULATION OF FIELD TEST

The subroutines discussed above were modified and inserted into a program designed to simulate the line of sight experiments conducted at Hunter Liggett. The program considers only macro-relief features; it also takes into account several of the error sources which were inherent in the field experiments.

8.4.1 Simulation Methodology

The basic simulation procedure tries to model the actual experimental procedure conducted in the field. A given observer's position (grid coordinates on a topographic map) is determined as accurately as possible. Based on this determination, the program reads in all the elevation data in a square area centered about this point. The area is 444.5 grid points (using 12.7 meter resolution).

As in the actual experiments, the target is programmed to move away from the observer in a fixed direction. The target steps off increments of 3.175 meters away from observer. Every step increment initiates a call to subroutine DETERR, which in turn, calls LOSVEG to determine if a "head-to-head" line of sight exists. If it does the target takes another step of 3.175 meters away from the observer. The line of sight routine is called again. The procedure is repeated as long as the line of sight exists. This continues until either the line of sight no longer exists due to macro-relief obstruction, or the target has stepped off so many increments away from the observer that elevation data is no longer available for line of sight calculations. In the latter case, the distance between the observer and the target for which line of sight remains uninterrupted by macro-relief is considered to be unlimited.

Once the line of sight is obstructed, the target is programmed to move towards the observer. The step increment is reduced by half to 1.5875 meters. Again, each step increment initiates a call to the appropriate subroutines giving a line of sight verdict. The target is programmed to continue the inward movement until an uninterrupted line of sight is established again. As soon as the line of sight has been re-established, the target begins moving away from the observer once more. Now the step increments are made smaller ($1.5875 \div 2$). As before, each step gives rise to a line of sight verdict. The target continues moving away from the observer until the line of sight is interrupted by macro-relief again. At this instance, the range between the observer and target is recorded. In addition, the ranges between the observer and the line of sight intersections with grid crossings are recorded. These distances are needed to form an approximation of the actual surface between the observer and target. In short the simulation obtains data to approximate the surface distance by pinpointing the target's exact location (in a forward and backward manner) at the instant of line of sight obstruction.

The surface distance approximation is required because LOSVEG projects all lines of sight onto a grid plane of zero altitude, and computes all distances on this plane. Naturally, for extremely undulating relief, the linear range computed would be a poor approximation of the actual surface

distance measured at Hunter Liggett. Figure 8.6 illustrates the estimation procedure. The distance between two successive grid crossings is computed. This is done for the C^{th} grid line by subtracting $D(C)$ from $D(C+1)$. The elevations at points where the line of sight intersect the two grid crossings are computed also ($ZZZ(C+1)$, and $ZZZ(C)$). The difference in elevation at these two points can be computed by subtracting $ZZZ(C)$ from $ZZZ(C+1)$. The surface distance from the C^{th} line is the length of the hypotenuse of the right triangle having sides $|D(C+1)-D(C)|$ and $|ZZZ(C+1)-ZZZ(C)|$. The estimation procedure is repeated for all grid squares having intersections with the line of sight; the results are summed to produce the surface distance from observer to target.

8.4.2 A Measure for Evaluating Validity

A comparison is made between the actual surface distance measured in the field and the estimated surface distance produced by the simulation. The absolute value of the difference between the actual and simulated surface distances is computed. This difference provides a measure for evaluating the credibility of:

- 1) the line of sight calculations and
- 2) the mathematical representation of macro-relief.

Specifically, a difference that approaches zero indicates that the simulation is producing reasonable results. However, a very small difference, or a difference of zero should not be interpreted as evidence of complete validity. It merely reflects that the line of sight algorithm, and the mathematical model for relief give reasonable estimates of the true situation.

8.4.3 Error Adjustments

Recall that the raw data from the field experiments was subject to four basic types of error. One such error involved inaccuracies in pin-pointing the exact location of the observer on a topographical map. A pencil point on a map of scale 1:50000, can be in error by as much as 20 meters. Furthermore, the exact location of the target is in doubt, not only due to the uncertainties in the observer's location, but due to

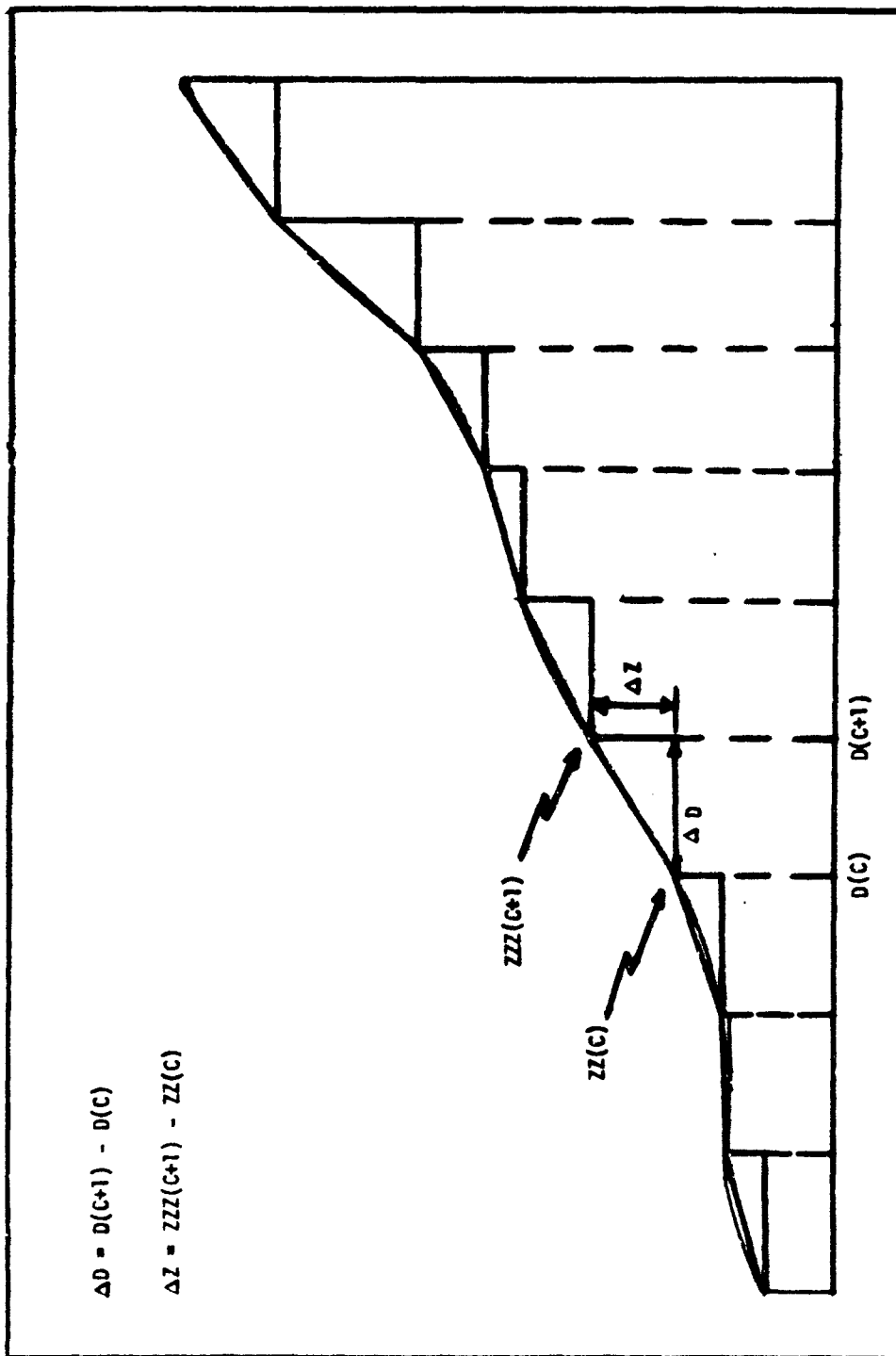


Figure 8.6 ESTIMATION OF SURFACE DISTANCE

compass errors. The computer simulation attempts to correct such errors by:

- 1) considering a set of observer locations; and
- 2) slightly perturbing the angle of direction which locates the target relative to the observer.

Instead of investigating one possible observer location, the simulation considers a set of possible locations. Thirty-six equally spaced points within a 12.7 by 12.7 square area are analyzed. Each point is 2.54 meters apart. Thus, the input for "observer location" is not given by a pair of coordinates denoting a single point; it is given by a small grid area enclosing the most likely observer location. See Figure 8.7. This technique removes the guesswork involved with measuring map coordinates (by hand with a ruler), and places more emphasis on locating the observer's position relative to his immediate macro-relief environment.

At every observer location at Hunter Liggett, line of sight data was gathered in several different directions. The recorded angle (relative to magnetic north), for a given direction will be designated the "base angle." This angle contains small uncertainties due to compass reading errors. The simulation attempts to eliminate these uncertainties by perturbing the base angle slightly ($\pm 1^\circ$ and $\pm 2^\circ$). Thus, five different line of sight determinations are performed for a given direction:

- 1) the base angle determination;
- 2) base angle $+2^\circ$;
- 3) base angle $+1^\circ$;
- 4) base angle -1° ; and
- 5) base angle -2° .

In each case, the absolute value of the difference between actual and simulated surface distance is computed. The angle resulting in the smallest difference is chosen as the new "base angle" for that given direction. The same procedure is applied to each of the several other directions recorded at the experiment site.

In most instances, the simulation examined only three recorded directions at each experiment site. These three directions were chosen arbitrarily, but remained the same for each of the thirty-six points at

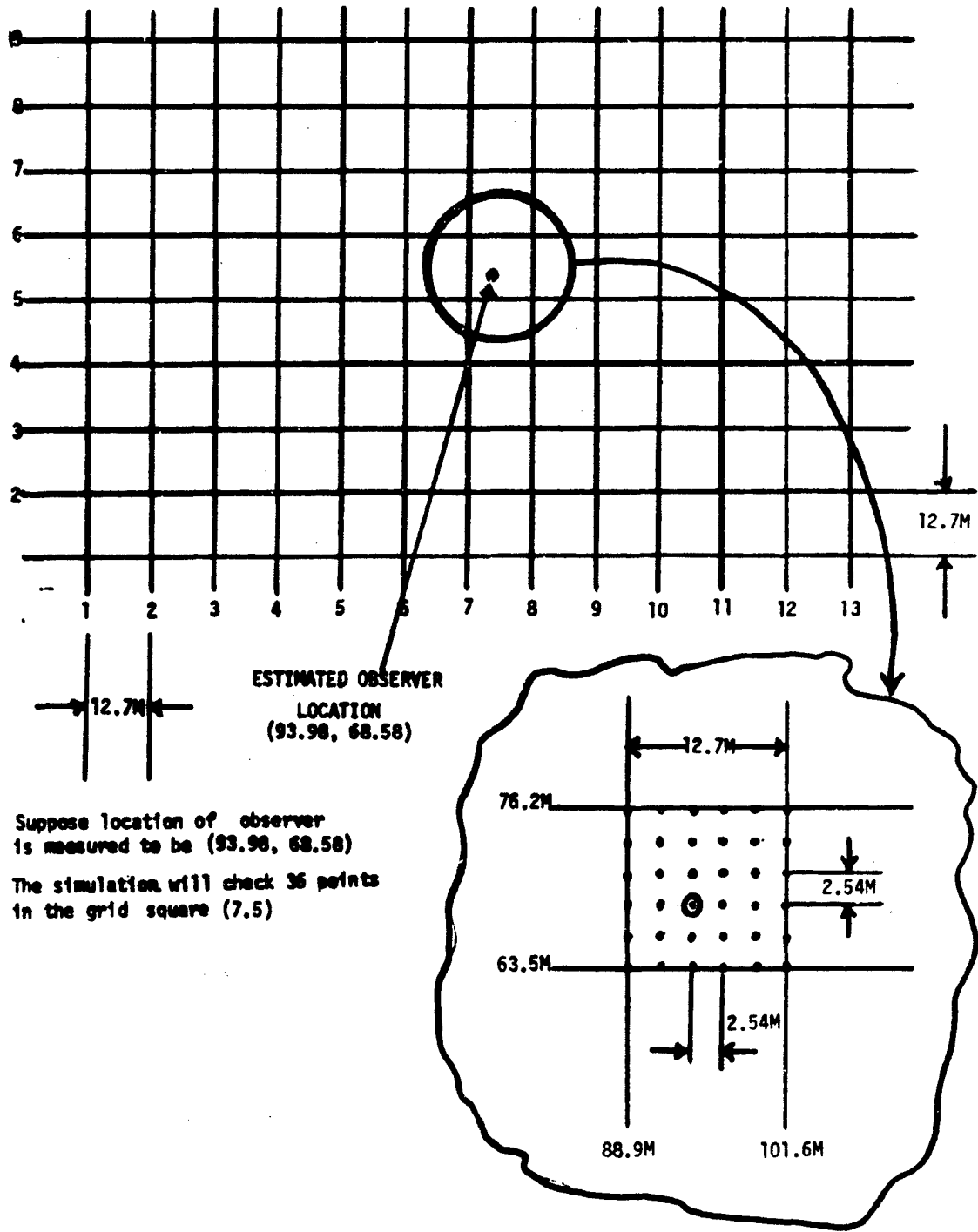


Figure 8.7 GRID OR OBSERVER LOCATION

a given location. Computer costs involved with examining more than three directions were prohibitive: the simulation considers thirty-six points. If three directions are examined, then fifteen line of sight experiments are performed (3x5). Thus there are 36x15=360 line of sight experiments performed for one location at Hunter Liggett.

8.4.4 Overall Measure of Validity

Recall that the absolute difference provided a measure of validity for a line of sight experiment conducted in one direction. But for each point, three different directions were analyzed. Thus a summary statistic, measuring the accuracy of line of sight calculations for all three directions, was needed.

The root mean square of the difference in each direction was chosen to measure the accuracy of all line of sight calculations at a given point. Specifically, the quantity measuring overall validity for line of sight calculations in all directions is given by:

$$\sqrt{\frac{\sum_{I=1}^N \{D_A(I) - D_C(I)\}^2}{N}}, \text{ where } D_A(I) \text{ is the actual}$$

surface distance in the I^{th} direction, $D_C(I)$ is calculated surface distance in the I^{th} direction, and N is the number of directions analyzed ($N=3$ in this simulation). Thus every one of the thirty-six possible points under consideration has associated with it, a root mean square difference. This number reflects the accuracy of the simulation experiments at each of these points. The location of the point having the least root mean square difference is chosen to represent the actual position of the observer in the field experiment.

8.4.5 Simulation Using Different Resolutions

The simulations were conducted using three grid size resolutions. The initial simulation was done with elevation data available at grid points 12.7 meters apart. This was the finest resolution of elevation data available; hence this resolution was used to locate the actual

positions of the observer at the experiment sites. Having established these locations, the simulation was performed using coarser resolution: elevation data points 25.4 and 50.8 meters apart respectively. The simulation procedure using cruder resolution is exactly the same as described above, except that it no longer examines the set of thirty-six possible points for an actual location (it uses the actual locations derived from the initial simulation, thus avoiding a great deal of processing).

8.5 ANALYSIS OF SIMULATION RESULTS.

The root mean square (of differences between actual and simulated surface distance in all line of sight directions examined for a given experiment site at Hunter Liggett) provides a measure for evaluating the validity of the line of sight routines and macro-relief representation. Figure 8.8 gives these measures for all nine Hunter Liggett experiment sites, at the various resolutions used in the simulation. Figure 8.9 presents the simulation results broken down into individual line of sight experiments. The overall root mean square difference is given on this figure also.

As Figure 8.8 indicates, the simulation performed under 12.7 meter resolution produce very credible results. The results using 25.4 and 50.8 meter resolution are credible, but not as sharp. The reason for this is that the line of sight interruption distances measured are relatively short (i.e., with respect to the length of the side of the grid squares). Many of the line of sight obstruction distances measured at Hunter Liggett were less than 100 meters in length. These short distances do not affect the simulation when the resolution is very fine (i.e., 12.7 meter resolution), but as the resolution becomes coarser, the simulation results are more inaccurate. It must be stressed that this happens only when simulation is attempted over very short lines of sight using very coarse resolution. The inaccuracies appear in the form of large root mean square differences. Coarse resolution should be used in line of sight determinations when the observer and target are over 200 meters away.

SITE	12.7 METERS RESOLUTION		25.4 METERS RESOLUTION		50.8 METERS RESOLUTION	
	ROOT MEAN SQUARE	PERCENT	ROOT MEAN SQUARE	PERCENT	ROOT MEAN SQUARE	PERCENT
1	5.9M	10.6	8.2M	42.7	67.8M	107.0
2	1.7M	3.3	18.6M	50.0	11.5M	43.0
3	1.6M	4.0	4.7M	40.6	*	100.
4	0.3M	0.5	4.7M	12.3	39.0M	107.2
5	2.1M	5.0	24.6M	82.8	38.9M	105.9
6	2.7M	4.6	10.0M	13.7	31.0M	52.8
7	8.1M	4.9	40.1M	25.9	67.7M	62.9
8	9.1M	9.7	16.0M	19.7	39.6M	71.8
9	3.0M	1.7	22.6M	12.1	48.1M	52.3

* UNLIMITED LINE OF SIGHT (i.e., TARGET HAS STEPPED OFF SO MANY INCREMENTS FROM OBSERVER THAT ELEVATION DATA IS NO LONGER AVAILABLE FOR LOS CALCULATIONS). FIGURE 8.10 ILLUSTRATES HOW THIS CAN HAPPEN.

FIGURE 8.8 ROOT MEAN SQUARE ERROR AT DIFFERENT RESOLUTIONS

SITE	RESOLUTION	DIRECTION 1		DIRECTION 2		DIRECTION 3		ROOT MEAN SQUARE
		MEASURED DISTANCE	ERROR	MEASURED DISTANCE	ERROR	MEASURED DISTANCE	ERROR	
1	12.7	25.	1.8	71.	6.3	50.	7.8	5.9
	25.4		•		6.8		9.3	8.2
	50.8		•		25.3		92.	67.8
2	12.7	71.	1.9	68.	2.2	23.	-.9	1.7
	25.4		-8.2		25.		•	18.6
	50.8		-15.6		4.5		•	11.5
3	12.7	26.	.9	29.	-.4	36.	-2.6	1.6
	25.4		•		1.1		6.5	4.7
	50.8		•		•		•	•
4	12.7	36.	.0	29.	-.3	47.	.3	0.3
	25.4		-6.8		3.2		-3.0	4.7
	50.8		•		50.1		-23.0	39.0
5	12.7	27.	-3.6	28.	.0	42.5	.7	2.1
	25.4		•		30.6		-16.6	24.6
	50.8		•		55.		9.0	38.9

*Unlimited Line of Sight (i.e., target has stepped off so many increments from observer that elevation data is no longer available for LOS calculations).
 Figure 8.10 illustrates how this can happen.

Error = $D_C(I) - D_A(I)$ where $D_C(I)$ is the calculated surface distance in the I^{th} direction and $D_A(I)$ is the actual measured surface distance in the I^{th} direction.

Figure 8.9, Detailed Simulation Results (Sheet 1)
 (ALL MEASUREMENTS IN METERS)

SITE	RESOLUTION	DIRECTION 1		DIRECTION 2		DIRECTION 3		ROOT MEAN SQUARE
		MEASURED DISTANCE	ERROR	MEASURED DISTANCE	ERROR	MEASURED DISTANCE	ERROR	
6	12.7	61.	-1.8	61.	-3.7	49.	-2.4	2.7
	25.4		-14.5		-9.3		1.0	10.0
	50.8		-33.5		-35.8		-21.9	31.0
7	12.7	145.	11.8	145.	5.3	172.	-5.2	8.1
	25.4		20.0		50.8		27.0	40.1
	50.8		43.3		85.4		*	67.7
8	12.7	67.	-10.5	88.	-11.8	57.	.0	9.1
	25.4		-10.1		-24.0		9.5	16.0
	50.8		*		38.0		41.2	39.6
9	12.7	130.	.6	118.	5.1	152.	.5	3.0
	25.4		-12.9		-1.1		40.	22.6
	50.8		-67.4		9.8		*	48.1

*Unlimited line of sight (i.e., target has stepped off so many increments from observer that elevation data is no longer available for LOS calculations).
Figure 8.10 illustrates how this can happen.

Error = $D_C(I) - D_A(I)$ where $D_C(I)$ is the calculated surface distance in the I^{th} direction and $D_A(I)$ is the actual measured surface distance in the I^{th} direction.

Figure 8.9, Detailed Simulation Results (Sheet 2)

(ALL MEASUREMENTS IN METERS)

Figure 8.10 demonstrates what can happen when line of sight calculations are conducted over a short distance using various resolutions. An observer and target, both of height 1.8 meters, stand 12 meters apart. Macro-relief described with 12.7 meter resolution indicates a line of sight interruption at approximately 6.7 meters from the observer. However, no such line of sight interruption occurs when describing macro-relief with 25.4 or 50.8 meter resolution. The figure shows that the hump at about 6.7 meters from the observer is not modeled when describing macro-relief using the cruder resolutions. This explains why some of the root mean square differences are so large when the simulation was run using 25.4 and 50.8 resolution (recall that the target keeps moving away from the observer until a verdict of obstruction is given).

The simulation results particularly those obtained when using the 12.7 meter resolution demonstrate that the SIAF line of sight routine and the SIAF representation of macro-relief are "reasonable". Furthermore, line of sight calculations are sensitive to resolution when the distance between observer and target is small (i.e., less than 100 meters). For the reason, the SIAF concept of switching resolution (using less resolution in the Reconnaissance Mode when long distances are involved; and finer resolution in the Combat Mode when shorter distances are involved, and more detailed computation are required) appears well founded.

8.6 SUMMARY

Line of sight data was collected at nine different locations at the Hunter Liggett Military Reservation. At each location, line of sight experiments were conducted in several different directions. Inherent errors in compass reading and in locating positions on a topographical map required the simulation to consider a set of possible locations and to vary the directions between observer and target. The initial simulation examines a set of thirty-six equally spaced (2.54 meters apart) points enclosed in a 12.7 by 12.7 meter grid square. Each of the thirty-six points are analyzed as follows. Three arbitrary experimental directions were chosen. Each direction is perturbed by $\pm 1^\circ$ and $\pm 2^\circ$, so that five line of sight verdicts are obtained. The verdict which offers the minimum

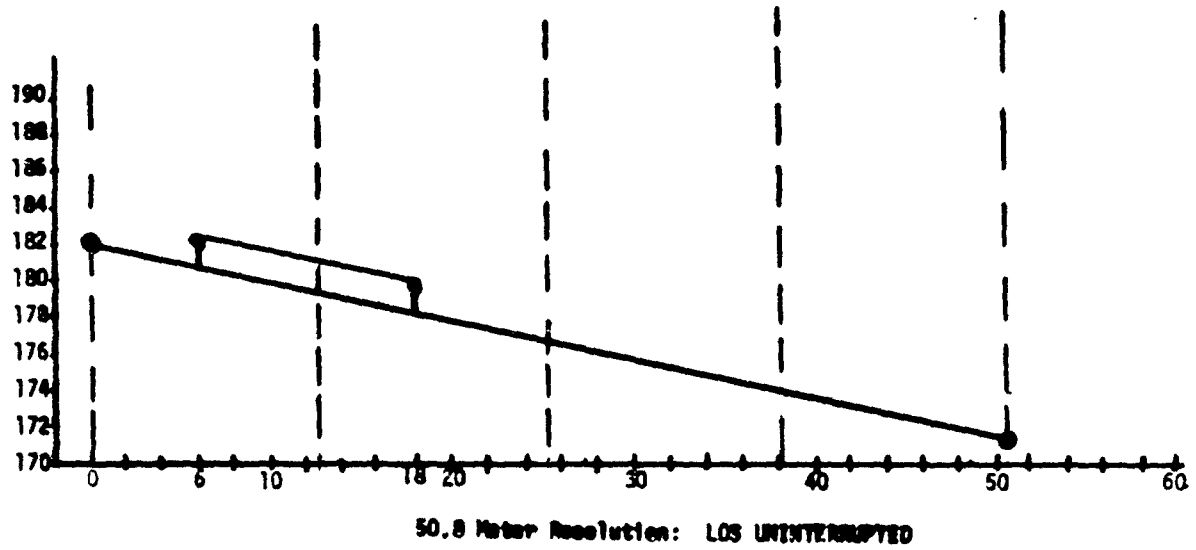
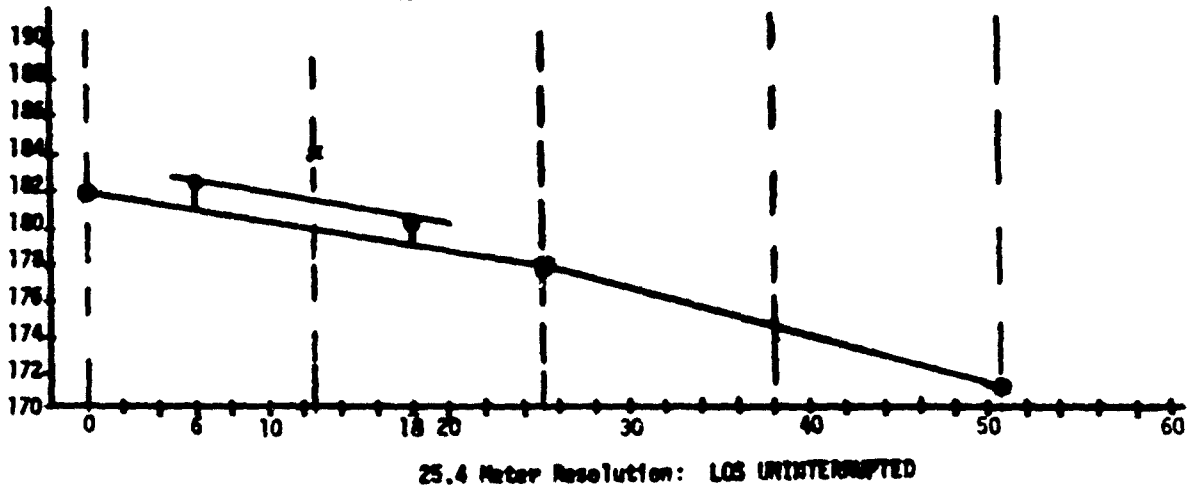
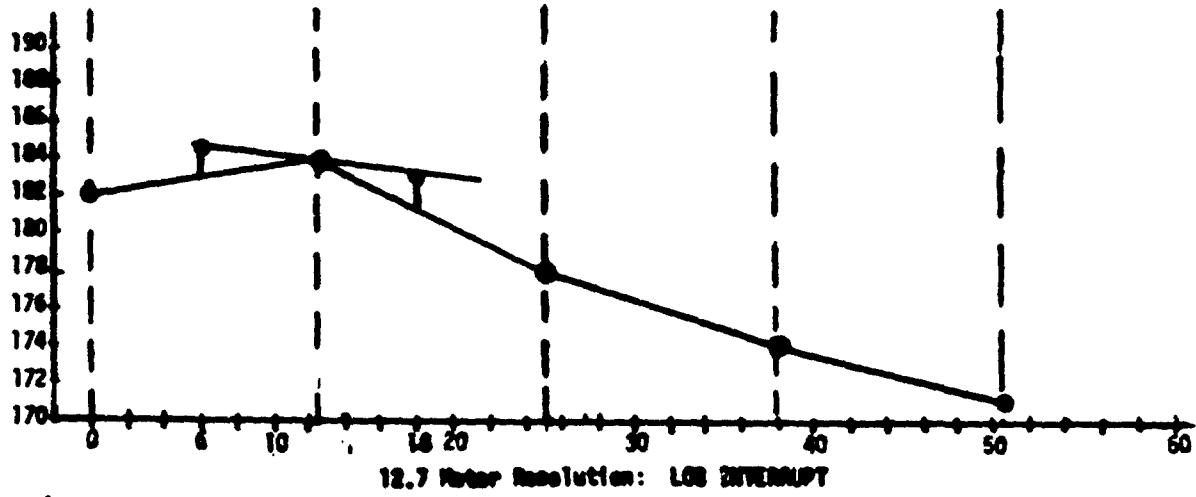


Figure 8.10 LOS VERDICT USING DIFFERENT RESOLUTIONS

difference between actual and computed surface distance determines the base angle for that direction. Thus each direction has associated with it, a measure of how accurate the simulation was. The root mean square of these individual differences gives an over measure of how accurate the simulation of the field experiment was at that point. The root mean square difference is given by:

$$\sqrt{\frac{\sum_{I=1}^N \{D_A(I) - D_C(I)\}^2}{N}}$$

where $D_A(I)$ is the actual surface distance, $D_C(I)$ is the computed surface distance, and N is the number of directions analyzed.

The initial simulation examines thirty-six possible points for a given experiment location, thus producing thirty-six root mean square differences. The location of the point having smallest root mean square is considered the site where the line of sight experiment actually took place. All nine experiment sites at Hunter Liggett were determined by the above procedure.

The simulation was repeated using resolutions of 25.4 and 50.8 meters. The same procedure was applied, except the observer positions are inputted (from initial simulation) instead of calculated.

The results of the simulation demonstrate that the SIAF line of sight calculations and the SIAF model of macro-relief are valid. Also, when the distance between observer and target is small (i.e., less than 100 meters), the line of sight calculations are dependent on resolution.

8.7 COMPARISON WITH ASARS BATTLE MODEL

Macro-relief models usually employ a grid square concept in which elevation data is known at four corners of each grid. The elevation at points lying between these data points are represented by an interpolated value using the known data points. Different methods are used to obtain these interpolated values. As mentioned before, the STAF model uses a continuous

surface representation within a grid square based on the four surrounding grid points. A less complex method uses two intersecting triangular planes within a grid square to obtain interpolated values. This scheme is used in the ASARS model. The simulation experiment was done utilizing both representations of macro-relief; the results were compared.

8.7.1 ASARS Methodology

ASARS macro-relief is modeled by specifying two triangular planes within a grid square. The planes are defined by specifying a diagonal within the grid square (a positive diagonal if it connects the lower left corner with the upper right corner; a negative diagonal if it connects the upper left corner with the lower right corner). The orientation of the diagonal is the same for all grid squares under consideration. Positive diagonals were used in the simulation.

The line of sight subroutine in the ASARS model is basically a series of comparisons. The line of sight between the observer and the target is projected onto a grid plane (of zero altitude) and partitioned into a set of segments. The endpoints of these segments are defined by the intersection of the line of sight with horizontal and vertical grid crossings and with diagonals. Initially, the horizontal distance between observer and target, and the vertical difference in elevation between the top of the observer and the top of the target are computed. These quantities are used to compute the tangent of the angle subtended by the line of sight and a horizontal line parallel to the grid plane at the top of the observer. This tangent value is designated "TANLIM".

The line of sight routine proceeds as follows: the elevation of the ground surface at an endpoint of a segment is referenced. The horizontal range from the observer to the endpoint is computed. These quantities are used to compute the tangent of the angle subtended by the line extending from the top of the observer to the ground surface at that endpoint, and the horizontal line parallel to the grid plane at the observer's height. Call this quantity "TAN". Figure 8.12 illustrates the above procedure. A comparison is made between TANLIM and TAN, to determine the line of sight verdict: If TAN is greater than or equal to TANLIM, the line of sight is interrupted at that endpoint. Otherwise, the line of sight exists and the

SITE	RESOLUTION	DIRECTION 1			DIRECTION 2			DIRECTION 3				
		MEAS. DIST.	SIAP ERROR	ASARS ERROR	MEAS. DIST.	SIAP ERROR	ASARS ERROR	MEAS. DIST.	SIAP ERROR	ASARS ERROR	SIAP R.M.S.	ASARS R.M.S.
1	12.7		1.8	1.4		6.3	5.3		7.8	*	5.9	3.9
	25.4	25.	*	*	71.	6.8	*	50.	9.3	94.9	8.2	94.9
	50.8		*	*		26.3	*		92.	189.2	67.8	189.2
2	12.7		1.9	.9		2.2	-2.7		-9	1.6	1.7	1.9
	25.4	71.	-8.2	-3.0	65.	25.	-172.0	23.	*	*	18.6	121.8
	50.8		-15.6	175.3		4.5	171.0		*	*	11.5	173.2
3	12.7		.9	15.		-.4	5.8		-2.6	9.8	1.6	10.9
	25.4	26.	*	131.6	29.	1.1	*	36.	6.5	*	4.7	131.6
	50.8		*	69.7		*	*		*	*	*	69.7
4	12.7		.0	7.0		-.3	-6.1		.3	.5	.3	5.4
	25.4	35.	-6.8	182.7	29.	3.2	201.4	47.	-3.0	179.1	4.7	188.0
	50.8		*	*		50.1	201.5		-23.0	178.4	39.0	190.3
5	12.7		-3.6	-2.4		.0	-4.7		.7	-10.2	2.1	6.6
	25.4	27.	*	*	28.	30.6	*	42.5	-16.6	*	24.6	131.6
	50.8		*	*		55.	104.8		9.0	170.7	38.9	141.6

* UNLIMITED LINE OF SIGHT (i.e., TARGET HAS STEPPED OFF SO MANY INCREMENTS FROM OBSERVER THAT ELEVATION DATA IS NO LONGER AVAILABLE FOR LOS CALCULATIONS). FIGURE 8.10 ILLUSTRATES HOW THIS CAN HAPPEN.

ERROR = $D_C(I) - D_A(I)$ WHERE $D_C(I)$ IS THE CALCULATED SURFACE DISTANCE IN THE I^{TH} DIRECTION AND $D_A(I)$ IS THE ACTUAL MEASURED SURFACE DISTANCE IN THE I^{TH} DIRECTION.

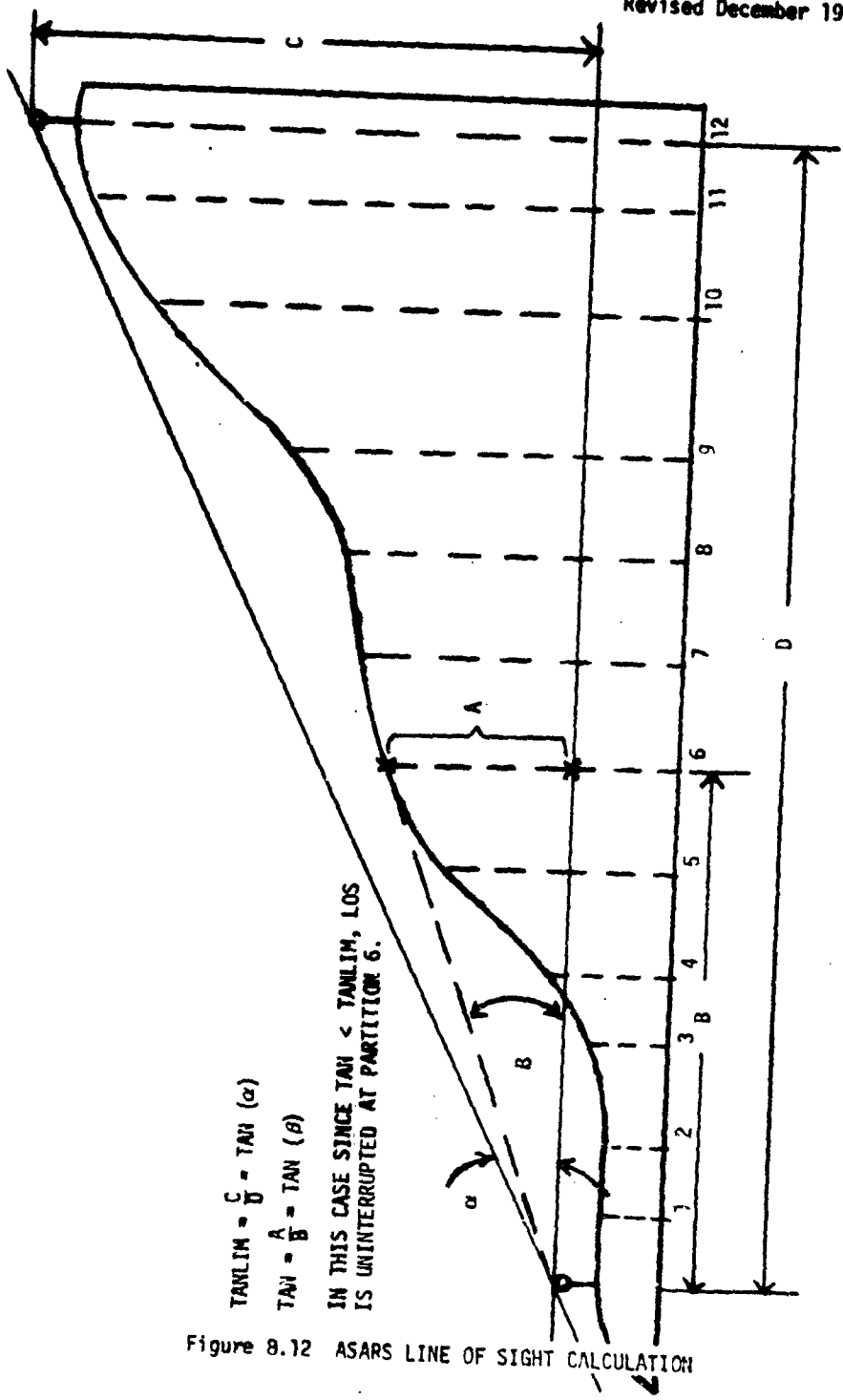
FIGURE 8.11 SIAP AND ASARS SIMULATION RESULTS (SHEET 1)
(ALL MEASUREMENTS IN METERS)

SITE	RESOLUTION	DIRECTION 1			DIRECTION 2			DIRECTION 3			SIAP R.M.S.	ASARS R.M.S.
		MEAS. DIST.	SIAP ERROR	ASARS ERROR	MEAS. DIST.	SIAP ERROR	ASARS ERROR	MEAS. DIST.	SIAP ERROR	ASARS ERROR		
6	12.7		-1.0	-0.7		-3.7	25.6		-2.0	-23.0	2.7	20.6
	25.4	61.	-14.5	32.5	61.	-9.3	31.1	40.	1.0	98.9	10.0	62.7
	50.8		-33.5	80.3		-35.8	160.7		-21.9	*	31.0	130.
7	12.7		11.0	-35.7		5.3	-37.3		-5.2	*	8.1	35.5
	25.4	148.	39.0	112.9	148.	80.0	20.9	172.	27.0	26.7	40.1	68.1
	50.8		43.3	85.2		85.4	66.4		*	29.2	67.7	65.0
8	12.7		-10.5	2.5		-11.8	15.5		.0	*	9.1	11.1
	25.4	67.	-10.1	21.9	80.	-24.0	.9	57.	9.5	64.2	16.0	39.2
	50.8		*	45.1		38.0	80.0		41.2	122.7	39.6	120.
9	12.7		.6	60.		5.1	*		.5	-81.0	3.0	55.7
	25.4	139.	-12.9	130.3	118.	-1.1	143.0	152.	40.	*	22.6	137.0
	50.8		-67.4	212.		9.8	144.3		*	*	40.1	181.3

* UNLIMITED LINE OF SIGHT (I.E., TARGET HAS STEPPED OFF SO MANY INCREMENTS FROM OBSERVER THAT ELEVATION DATA IS NO LONGER AVAILABLE FOR LOS CALCULATIONS). FIGURE 8.10 ILLUSTRATES HOW THIS CAN HAPPEN.

ERROR = $D_C(U) - D_A(I)$ WHERE $D_C(I)$ IS THE CALCULATED SURFACE DISTANCE IN THE I^{TH} DIRECTION AND $D_A(I)$ IS THE ACTUAL MEASURED SURFACE DISTANCE IN THE I^{TH} DIRECTION

FIGURE 8.11 SIAP AND ASARS SIMULATION RESULTS (SHEET 2)
 (ALL MEASUREMENTS IN METERS)



$$\text{TAN LIM} = \frac{C}{D} = \text{TAN}(\alpha)$$

$$\text{TAN} = \frac{A}{B} = \text{TAN}(\beta)$$

IN THIS CASE SINCE $\text{TAN} < \text{TAN LIM}$, LOS IS UNINTERRUPTED AT PARTITION 6.

Figure 8.12 ASARS LINE OF SIGHT CALCULATION

procedure is repeated at the next endpoint.

The above procedure starts at the observer position and continues toward the target, until line of sight interruption occurs. If no interruption occurs, the fraction of target height covered by intervening macro-relief is computed.

The ASARS method of representing macro-relief along with the ASARS line of sight routine were inserted into the simulation program. Appropriate minor modifications in the simulation program were made to accommodate the change. Otherwise, the exact methodology used in the SIAF macro-relief simulation was followed for the ASARS simulation.

8.7.2 Comparison

The simulation results using the ASARS macro-relief model did not compare as well as those of the SIAF simulation. The ASARS simulation produced credible results at 12.7 meters resolution. As figure 8.11 indicates, the SIAF results at this resolution were generally better than those returned by the ASARS method (though in some instances the ASARS method gave better approximations). At coarser resolutions (25.4 and 50.8 meters), the SIAF results were significantly better. In almost every instance, the SIAF simulation gave smaller errors, and thus smaller root mean square differences. Also, the ASARS simulation produced more instances where erroneous "unlimited" lines of sight were given (see figure 8.10 for explanation).

The large root mean square differences at the coarser resolutions may be attributed to the less accurate scheme for approximating macro-relief. Interpolated values in the SIAF model use data from all four surrounding grid points, whereas the ASARS model use only three of the four data points available. In addition, the ASARS relief model has the disadvantage that the choice of which grid square diagonal to use in forming the two triangular planes must be held constant throughout the entire gridded area under consideration. This disadvantage results in a loss of realism (this method does not give a unique representation of relief). A situation depicted in figure 8.13 illustrates this disadvantage. In both case 1 and case 2, the same set of four data points is input. Suppose case 2 is the desired approximation (ridge), but because positive diagonals (lower left corner to upper right corner) was the established choice of diagonal orientation, we

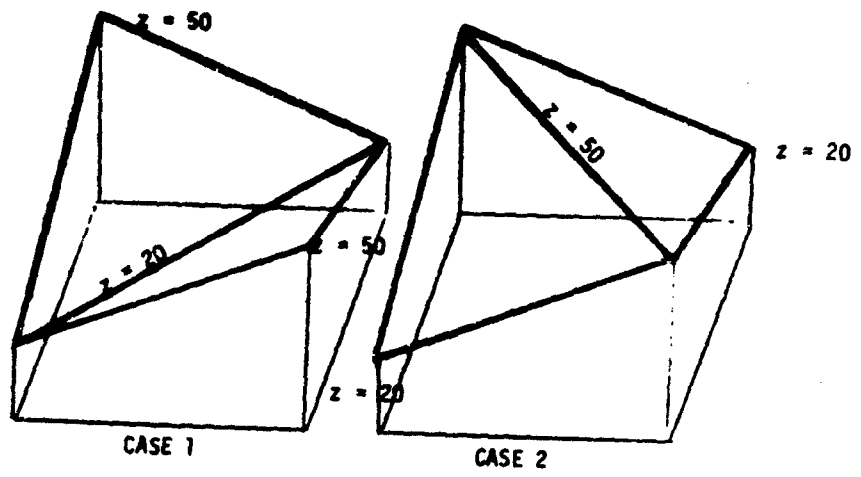


Figure 8.13 Non-Unique Terrain Surface Representation

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Page 8-30

Revised December 1973

obtained an inaccurate representation (ravine). Clearly, the two surfaces resulting are quite different depending on the choice of diagonals. Thus, in comparison, it appears that the two-triangular-plane method of ASARS requires a smaller grid size to represent macro-relief to the same resolution as the four-point continuous surface scheme of SIAF.

Best Available Copy

9.0 REFERENCES

1. S. Q. Duntley, et al, "Visibility," Applied Optics, Volume 3, Number 5, May 1964.
2. "Training for SIAF, Program Description Number 1: Land Navigation," HumRRO Division 4.
3. Army Map Sheets, Numbers 1755 IV NE, 1755 I NW, 1755 IV SE, and 1755 I SW, for Alder Peak, California, 1:25,000.
4. TRW Systems Group, "SIAF Model Development, Validation, and Implementation Final Report," 16905-6012-R0-00.

APPENDICES

Included herein are Appendix A, Block Data Generator Program and Appendix B, Specification Statement Punch Program (SPECPN) User's Guide.

These Appendices describe two computer programs which were originally written for the IBM 7094. These programs have recently been modified to run on the IBM 360, and in the process an additional change has been made.

The main external difference in the programs is that BLKGEN no longer punches a BLOCK DATA subprogram which must be input to SPECPN. The necessary information is written on tape and is read back directly into the necessary COMMON blocks for SPECPN. This eliminates the need for two separate passes through the machine, since the two programs can be run as one single program. They can, however, be run as separate phases if necessary, using a previously generated tape as input to SPECPN.

The conversion to the 360 was handled in this manner for several reasons:

1. It eliminated the need for unnecessary card handling associated with a punched BLOCK DATA.
2. It eliminated the need for two separate passes through the machine, since there is no need to compile a BLOCK DATA subprogram, and thus improved turnaround.
3. It improved the running time of the program by eliminating the punching of the BLOCK DATA.

The inputs to both BLKGEN and SPECPN remain unchanged from those described in Appendix A and Appendix B. The 360 version can thus be run using existing decks with no modifications. However, since the programs have been combined utilizing a short driver, an additional control card is necessary to specify whether BLKGEN, SPECPN, or both are to be executed. This control card must precede all other data. Card column 1 is punched non-zero if it is desired to execute BLKGEN; card column 2 is punched non-zero if it is desired to execute SPECPN.

The appropriate column is punched zero or left blank if it is desired to skip execution of either program. The standard input decks follow this card, with no separation between BLKGEN and SPECN inputs, if both are being run. The output will be identical to that of the 7094 version, with the exception of a punched BLOCK DATA.

2

APPENDIX A
BLOCK DATA GENERATOR PROGRAM
(BLKGEN)
User's Guide

I. History:

Because many large programs use COMMON quite extensively, it has become a common practice to set up all the variables of a program, equate them to blocks, and put all the blocks in a COMMON array. In order to use the variables in a subroutine, one would have to write COMMON, DIMENSION, and EQUIVALENCE cards for each variable. It soon became apparent that it would be desirable to be able to generate these COMMON, DIMENSION, and EQUIVALENCE statements by some external means. The Specification Statement Punch Program (SPECPN)¹ fulfills this desirability, but it requires a rather complicated BLOCK DATA sub-program to be written by the user to describe all the variables in COMMON.

The BLKGEN program was written to generate this BLOCK DATA sub-program from input cards which are easily written and changed. The combination of the BLKGEN and SPECPN programs allow an easy way to create and update a master COMMON of blocks and variables. By using these two programs, it should be fairly easy for one to generate the COMMON, DIMENSION, and EQUIVALENCE cards for each subroutine.

II. Usage:

For a picture of the organization and the usage of the BLKGEN and SPECN programs, look at Section V. It can be seen that the usage of the two programs requires two passes on the computer. On the first pass, the master input cards are input to the BLKGEN program. The output of the BLKGEN program is the BLOCK DATA sub-program punched on cards. The BLOCK DATA sub-program is input with the variable names for each subroutine to the SPECN program on the second pass. The second pass output are the COMMON, DIMENSION, and EQUIVALENCE cards which are directly placed into the respective subroutines.

Since the specific usage of the SPECN program is given in the SPECN User's Guide, the only additional required information is the format of the input cards to the BLKGEN program. There are nine different cards accepted as input to the BLKGEN program, and each is described below:

1. IDENT Card:

The IDENT card is always the first card input to a run. The word IDENT starts in c.c. 1 and the number of cards that are to follow the IDENT card to describe the job is punched in c.c. 30. If c.c. 30 contains a 3, then there are three cards which contain information describing a run.

Example:

c.c. 1

IDENT

c.c. 30

1

*10
30 for number of cards*

THIS IS A SAMPLE RUN

The information punched on the card(s) following IDENT appears as comments in the BLOCK DATA program generated by BLKGEN. Columns 1 - 71 may be used for the comments cards.

2. PROGRAMMER Card:

The PROGRAMMER card simply contains identification information concerning the programmer, and it is always the second control card in a run following IDENT and the comment cards specified by IDENT. The word PROGRAMMER starts in c.c. 1, and the programmer's name follows immediately after (one space is skipped). Up to 24 characters may be used for the PROGRAMMER name.

Example:

c.c. 1	c.c. 12
PROGRAMMER	J. Gerry Purdy

3. DATE Card:

The DATE card must always be the third control card in any run. The word DATE starts in c.c. 1, followed by a blank, followed by the date.

Example:

c.c. 1	c.c. 6
DATE	November, 1966

Following the IDENT, PROGRAMMER, and DATE control cards are the cards which actually describe the COMMON blocks of the user's program. Each COMMON block is described separately in the following way:

- a) The actual cards which define the COMMON block of interest are presented to BLKGEN.
- b) Each master variable name of interest from the above defined COMMON block is denoted followed by a series of control cards identifying the variables within the master variable, their dimension, and their relative position within the block.
- c) After all master variables have been described a signal is given (ENDCOM) and the next COMMON block is defined. Following the last COMMON block definition a signal is given (ENDJOB) terminating the job. Each control card will now be described.

4. COMMON Card:

The COMMON control card must be the first card of each COMMON set. The number of cards that are to follow is placed in c.c. 30. What follows is the card or cards which define the COMMON block exactly as they would be punched for the user's program.

Example:

c.c. 1	c.c. 30
COMMON	2

COMMON/VSTR/BLK(50), B(6), ~~30(36)~~
1 c.c.

In this example, 3 cards are used to define the COMMON block VSTR. BLKGEN constructs a card image of these COMMON statements and places it in the FMT array in the output BLOCK DATA cards for processing by SPEC PN.

Only 1 COMMON block name (e.g. VSTR) may be defined per use of COMMON. Subsequent COMMON entries would be used if the user has more than 1 COMMON block in his program. Blank or labeled COMMON blocks are acceptable. A maximum of 9 cards may be used for each COMMON block definition.

5. M Card:

The M card identifies the block name under the current COMMON. The M is placed in c.c. 1, the block name (up to 6 characters) starts in c.c. 10, and the description of the block (up to 24 characters) starts in c.c. 40.

Example:

c.c. 1	c.c. 10	c.c. 40
M	BLK1	FLOATING CONSTANTS

Sets of M and subsequent V cards may be repeated for each block in the current COMMON. The order in which the blocks are processed from the COMMON cards is arbitrary and the descriptions given starting in c.c. 40 are optional.

6. V Card:

The V card is the variable card and contains information about the variable which is contained within the current block. The V is in c.c. 1, the variable name (up to 6 characters) starts in c.c. 10, the dimension, if any, ends in c.c. 30, and the description of the variable (up to 24 characters) starts in c.c. 40, (optional). Singly dimensioned variables are indicated by placing a "1" or blank in c.c. 30.

Example:

c.c. 1	c.c. 10	c.c. 30	c.c. 40
V	CGMR	↓ 10	GM RATIO OF E, M, S, V, M, S, J, TO EARTH.

7. JUMP Card:

The JUMP card allows spaces to be skipped in the current block for perhaps future expansion. The word JUMP begins in c.c. 1 and the number of spaces to be skipped ends in c.c. 30.

Example:

c.c. 1	c.c. 30
JUMP	↓ 20

The above card would cause a "hole" of 20 cells to be made in the current COMMON block.

8. ENDCOM Card:

The ENDCOM Card is simply a signal to the program that the current COMMON block is finished. The ENDCOM starts in c.c. 1.

Example:

c.c. 1
ENDCOM

Following the ENDCOM card is either a new COMMON card or the ENDJOB card.

9. ENDJOB Card:

The ENDJOB card is simply a signal to the program that the inputs are finished. It is always the last card in a job.

Example:

c.c. 1
ENDJOB

III. Sample Inputs:

On the following pages is a listing of a sample set of input cards to the BLKGEN program. No labeled COMMON was used in this case, although both labeled and blank COMMON will work.

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
MS	202				COMB3
MT	232		4		MISC81
WT	203				COMB3
WV	201				COMB3
W1	44				DLOG8L
W2	45				DLOG8L
W	530	16,4			DLOG8L
XBAR	1401				DATA80
XBASE	1				LINSIG
XAMR	21				USI808
XAVODD	80				COMB3
XAVOID	81				MISC82
XDEFOP	77				MISC82
XDEPL	48				DLOG8L
XEE	203				DLOG8L
X8	205	5,20			MISC82
XDYNOL	333	17			COMB3
XDVN	82	200			COMB3
XENG	56				MISC82
XE	282				DLOG8L
XICIR	49				MISC82
XGOAL	1		20		DLOG8L
XLP	609		16		TARINT
XPAKMT	242				DAY80
XOB	1402	1000			MISC81
XLZ	305	5			LINSIG
XOP	50				COMB3
XPLAN	1	100,5			DLOG8L
XPPTT	285				USTARS
XPPT	284				MISC82
XTAR2	8				MISC82
XTAR	312		20		OBSTAB
XTAU	7		20		COMB3
XP2	240				OBSTAB
XP3	241				MISC81
XSIAF	28				MISC81
XST6	6				OBSTAB

Figure 7-2. Cross-reference of Common Variables (Sheet 15)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
XSP	51				DLOGBL
XSV	206				MISC82
XS	310				COMMB3
XT	311				COMMB3
X1FREN	3				USIB00
XZ	332				COMMB3
X2FREN	4				USIB00
YBAR	2402				LINSIG
YBASE	2				USIB00
YAV000	207				MISC82
YAV010	200				MISC82
YDEFOP	70				DLOGBL
YDEPL	52				DLOGBL
YB	343	5.20			COMM93
YEE	490				MISC82
YOYNOL	471	10			COMMB3
YDYN	209	200			MISC82
YENG	57				DLOGBL
YE	489				MISC82
VICIR	53				DLOGBL
VGOAL	21	20			TARINT
YOB	2403	1000			LINSIG
VLZ	443	5			COMMB3
YOP	54				DLOGBL
VPPT	492				MISC82
VPPT	491				MISC82
YRAR2	31	20			OBSTAB
VTAR	450	20			COMMB3
YTAU	30				OBSTAB
YSIAF	51				78STAB
YSIG	29				OBSTAB
VSP	55				DLOGBL
YSV	493				MISC82
YS	448				COMMB3
YT	449				COMMB3
Y1FREN	5				USIR00
YZ	470				COMMB3

Figure 7-2. Cross-reference of Common Variables (Sheet 16)

COMMON VARIABLES IN ALPHABETICAL ORDER

VARIABLE NAME	COMMON PSN	DIMENSION SIZE	T	DEFINITION	BLOCK NAME
V2FREN	6				US1800
ZDEPL	58				OL06BL
ZENG	59				OL06BL
ZETA	60				OL06BL
ZTAU	53				OBSTAB
ZSIG	52				OBSTAB
ZZ	401				COMMB3

Figure 7-2. Cross-reference of Common Variables (Sheet 17)

THIS IS THE MAIN PROGRAM TO GENERATE COMMON,
 COMMON AND COMMON FOR THE ISP PROGRAM.

PROGRAMMER J. GERRY RUDY
 DATE NOVEMBER, 1966
 COMMON

- COMMON
- 1. BLK5 (50), BLK2 (50), BLK3 (100), BLK4 (50)
- 2. BLK10(200), BLK7 (200), BLK8 (500), BLK9 (75)
- 3. BLK15(300), BLK12(50), BLK13(50), BLK14(200)

M	BLK1	(125)	BLK2	(50)	BLK3	(100)	BLK4	(50)
V	BLK5	(50)	BLK6	(200)	BLK7	(200)	BLK8	(500)
V	BLK10	(200)	BLK11	(200)	BLK12	(50)	BLK13	(50)
V	BLK15	(300)						
V	CGMR							
V	RCB							
V	CERAU							
V	CFTER							
V	CIN1							
V	CIN2							
V	COUT1							
V	COUT2							
V	CLIGHT							
V	CNMER							
V	CKMER							
V	CSOLC							
V	CDAYMN							
V	CDEG							
V	CJD50							
V	CPI2							
V	CPI							
V	C2PI							
V	CHMAX							
V	CHMIN							
V	CYMIN							
V	CTRM1							
V	CTRM2							
V	CER							
V	RASHE							

FLOATING POINT CONSTANTS
 EQUATORIAL RADIUS OF EARTH
 POLAR RADIUS OF EARTH
 ELLIPTICITY OF EARTH
 GRAVITATION CONSTANT OF EARTH
 ROTATIONAL RATE OF EARTH
 GM RATIO OF E.M.S.V.M.J.S TO EARTH
 RADIUS OF E.M.S.V.M.J.S TO EARTH
 EARTH RADII PER ASTRONOMICAL UNIT
 FEET PER EARTH RADII
 INITIAL CONDITION INPUT PER EARTH RADII
 INITIAL CONDITION TIME PER MINUTE
 TERMINAL CONDITION OUTPUT PER EARTH RADII
 TERM. COND. OUTPUT TIME PER MINUTE
 SPEED OF LIGHT
 NAUTICAL MILES PER EARTH RADII
 KILOMETERS PER EARTH RADII
 SOLAR CONSTANT (WATTS/METER SQ.)
 DAYS PER MONTH IN NON-LEAP YEAR
 DEGREES PER RADIAN
 JULIAN DATE OF JANUARY 1, 1950
 PI/2
 PI
 2*PI
 MAXIMUM STEPSIZE FOR TRAJ
 MINIMUM STEPSIZE FOR TRAJ
 AUXILIARY PARAMETER FOR TRAJ
 TERM USED TO CAL. RADIUS OF EARTH
 TERM USED TO CAL. RADIUS OF EARTH
 ERROR BOUND FOR TRAJ
 IMPACT PARAMETER FOR TRAJ

10
 10

12

V	CRDRM	MIN. TEST ALTITUDE FOR TRAJ	
V	CRCT	(1.-CELLIP)	
V	CEACT2	(1.-CELLIP)**2	
V	ACRACY	DESIRED ACCURACY IN TOF	
M	BLK2	FIXED POINT CONSTANTS	
V	KQUI	SYSTEM OUTPUT UNIT	
V	KIN	SYSTEM INPUT UNIT	
V	KTRAJ	UNIT FOR TRAJECTORY OUTPUT	
V	KIPEIN	UNIT FOR INPUT TAPE	
V	KEPHEM	UNIT FOR EPHEMERIS TAPE	
V	KERNO	FOR INTRZ	
V	IBFGEM	MASTER BODY FLAGS FOR E.M CENTER	10
V	IBFGS	MASTER BODY FLAGS FOR SUN CENTER	10
V	IBFGOB	MASTER BODY FLAGS FOR OTHER BODY CENTER	10
M	BLK3	FLOAT. PT. INPUTS	
V	TEPOCH	EPOCH TIME (MIN. FROM 0 HOURS)	
V	TJDATE	JULIAN DATE OF 0 HOURS EPOCH DAY	
V	TALFAG	RT. ASCEN. OF GREEN. @ MR. EPOCH DAY	
V	DYEAR	EPOCH YEAR MINUS 1900	
V	DMONTH	EPOCH MONTH NUMBER	
V	DDAY	EPOCH DAY NUMBER	
V	DHOUR	EPOCH HOUR	
V	DMIN	EPOCH MINUTE	
V	DSEC	EPOCH SECONDS AND FRACTIONS	
V	DTYPE	TYPE OF INITIAL CONDITIONS INPUT	
V	DBASE	DAYS SINCE JAN. 1, 1950 TO EPOCH DAY	
V	INOMX	CARTESIAN POS. AND VEL. AT EPOCH	6
V	INOMP	POLAR POS. AND VEL. AT EPOCH	6
V	TICOND	INITIAL CONDITIONS INPUT	10
V	RANGLE	RT. ASS. OF ICONDS X AXIS	
V	CDAD2M	CDA/2M (FT.**2/SLUG)	
V	CK	DRAG VARIATION	
V	CKSLCT	TYPE DRAG VAR. (P1 PER.**2 SECULAR)	
V	CDRAGM	DRAG ATROS. MODEL	
V	DAREA	AREA OF CRAFT FOR RAD. PRESSURE (INP2)	
V	DMASS	MAS. OF CRAFT FOR RAD. PRESS. (KILO.)	
V	TSTEP	INITIAL STEP SIZE FOR INTEGRATION	
V	COVAR	INPUT COVARIANCE MATRIX	21
V	POWFLT	POWERED FLIGHT INPUTS (ASPOF)	10
V	TRACE	FLAG TO SET UP TRACING THRU EXECUTION	
V	BPRIM	FACTOR TO MULT. TOF FOR NEW ESTIMATE	

V	PL	PLACED POINT INPUTS	
V	EQIN	EQUINOX OF INPUT ICONDS	
V	EQOUT	EQUINOX OF OUTPUT TRAJECTORY PRINT	
V	ICB	INITIAL CENTRAL BODY	
V	NI	MAXIMUM NO. OF ITERATIONS	
V	NDPR	NO. OF VARIATIONAL EQUATIONS	
M	BLK5	MASTER POINTERS AND FLAGS	
V	ISRCH	SEARCH FLAG, .NE. 0 IF SEARCH IS ON	
V	IOVRID	OVER-RIDE FLAG, .NE. 0 TO PRINT ON SRCH	
V	IFIRST	FLAG SET IN SEG IN FOR 1ST TIME THRU SLECT	
M	BLK6	WORKING STORAGE	
V	CMUC	CURRENT MU	
V	RCCB	RADIUS OF CURRENT CENTRAL BODY	
V	TEMP	TEMPORARY STORAGE	50
V	RTCB	RADIUS OF TARGET CENTRAL BODY	
V	DCAOUT	OUTPUT VECTOR FROM TDCA	6
V	TNOWJD	VALUE OF JULIAN DATE FOR CURRENT TIME	
V	VEPOCH	INIT. VAR. EQ., MEAN OF 50	36
V	TG	TIME TO INTEGRATE TO IN TRAJ	
M	BLK7	TRAJECTORY STORAGE	
V	TR	RADIUS FROM CENTRAL BODY TO PROBE	
V	TR2		TR**2
V	TR3		TR**3
V	TR5		TR**5
V	TR7		TR**7
V	COLA	COSINE LAMDA (CURRENT VEH. LAT.)	
V	SILA	SINE LAMDA (CURRENT VEH. LAT.)	
V	TV	VELOCITY OF PROBE REL. TO ROT. EARTH	
V	TVA	MAGNITUDE OF TV	
V	TDOO	COEFF. IN DIURNAL DRAG VARIATION	
V	CRSHB	SEMI-MINOR AXIS OF CURRENT CERAL BODY	
V	TPOT	PERT. ACEL. DUE TO POTEN. OF CCB.	3
V	TBPRT	PERT. ACEL. DUE TO OTHER BODIES	3
V	TRPRES	PERT. ACEL. DUE TO RAD. PRESSURE	3
V	ATHRST	PERT. ACEL. DUE TO THRUST	3
V	TDRAG	PERT. ACEL. DUE TO ATMOSPHERIC DRAG	3
V	PMAT	POST. EFFECTS TO CAL. 2ND DER. OF V. EQ.	9
V	VMAT	VEL. EFFECTS TO CAL. 2ND DER. OF V. EQ.	9
V	FLVE	FLAG, #0 TO NOT CAL. V EQ.	
V	TCRASH	FLAG, .NE. 0 WHEN CCB IMPACTED IN TRAJ	
V	PRALT	ESTIMATE PERIGEE ALT. FOR TRAJ	

V	SKIP	FLAG, .EQ. 0 TO EVAL. V. EQ. PRED. ONLY
V	SCALE	VALUE OF K IN K-R EVAL. FOR TDCA
V	TCRT	ICONDS, CARTESIAN, MEAN QF 50
V	PSENUM	CURRENT PHASE NUMBER
V	BSETME	BASE TIME FOR PHASE DELTA T, T S
V	TALFA	FLAG, NON-ZERO FOR RAD. PRS. CAL.
V	XN	EPHEMERIS POSITIONS
V	XNDOT	EPHEMERIS VELOCITIES
V	TEMP TG	TEMPORARY VALUE OF IG IN SELECT
V	TLASTM	LAST T IN MASTER DELTA T, T LIST
V	STORTG	STORAGE OF TEMP TG
V	TLASTP	LAST T IN PHASE DELTA T, T LIST
V	TSEC	FOR INTPL, SEC. FROM 1990 (PSEUDO D.P.)
V	COLA	COS(CURRENT VEH. LONGITUDE)
V	SILA	SIN(CURRENT VEH. LONGITUDE)
V	GOPH	COS(CURRENT VEH. LATITUDE)
V	SIPH	SIN(CURRENT VEH. LATITUDE)
V	CSALF	COS(CURRENT VEH. RIGHT ASCENSION)
V	SNALF	SIN(CURRENT VEH. RIGHT ASCENSION)
V	TRJPRT	FLAG, NON-ZERO FOR PRINT. IN TRAJ
M	BLK8	INTEGRATION INPUT
V	TLIST	INTEGRATION INPUT LIST
M	BLK9	INTEGRATION OUTPUT
V	TRAJX	INTEGRATION OUTPUT LIST
M	BLK10	EARTH-MOON HARMONICS
V	CEJ	EARTH ZONAL HARMONICS J1,J2.....J12
V	CEC	EARTH SECTORAL-TESSERAL HAR. C11...C66
V	CES	EARTH SECTORAL-TESSERAL HAR. S11...S66
V	CMJ	MOON ZONAL HARMONICS J1,J2.....J12
V	CHC	MOON SECTORAL-TESSERAL HAR. C11...C66
V	CMS	MOON SECTORAL-TESSERAL HAR. S11...S66
V	FJ	CURRENT ZONALS BEING USED IN GPRT
V	C	CURRENT SECT.-TESS. BEING USED IN GPRT
V	S	CURRENT SECT.-TESS. BEING USED IN GPRT
M	BLK11	TIMES FOR
V	TIMES	ALL PROCESS TIMES
M	BLK12	FIXED WORKING STORAGE
V	ICCB	CURRENT CENTRAL BODY
V	IOCB	PREVIOUS CENTRAL BODY
V	INCB	NEW CENTRAL BODY
V	NEOP	STARTING POST. OF PHASE SHIFT T IN TIMES

V	START. POST. OF TSP IN TIMES	
V	STARTING POST. OF MID-COURSE T S IN TIMES	
V	START. POST. OF JULIAN DATE I S IN TIMES	
V	START. POST. OF MASTER D T S IN TIMES	
V	START. POST. OF SPECIAL PRT. T S IN TIMES	
V	START. POST. OF PHASE D I S IN TIMES	
V	VALUE OF TARGET CENTRAL BODY FOR TDCA	
V	START. PSN. OF CURRENT PHASE IN LIST	
V	START. PSN. OF NEXT PHASE	
V	PSN. OF PHASE NO. IN CURRENT PHASE	
V	PSN. OF PHASE TYPE IN CURRENT PHASE	
V	PSN. OF FINAL CONDITION IN CURRENT PHASE	
V	PSN. OF TARGET CENT. BODY IN CURR. PHASE	
V	PSN. OF CURRENT CENT. BODY IN CURR. PHASE	
V	PSN. OF RAD. PRES. FLAG IN CURR. PHASE	
V	PSN. OF DELTA T FLAG IN CURRENT PHASE	
M	FIXED TRAJECTORY STORAGE	
V	DEGREE OF HIGHEST ZONAL HARMONICS	
V	DEGREE OF HIGHEST SECTORAL HARMONICS	
V	DEGREE OF HIGHEST TESSERAL HARMONICS	
V	OPTION FLAG FOR ROTAT	2
V	FLAG, .NE. 0 FOR FIRST PRE-EPOCH TIME	
V	FLAG, .NE. 0 1ST TIME THRU PHASE	
V	FLAG, .NE. 0 WHEN ALL TIMES PROCESSED	
V	FLAG, .NE. 0 TO PRINT AFTER INTEG.	
V	TYPE OF TIME RETURNED FROM SELECT	
V	FLAGS FOR BODIES EFFECTS THIS PHASE	
V	FLAG FOR DESIRED QUADRANT IN TDCA	
V	FLAG FOR 1ST TIME LESS THAN ACCRACY	
V	MAXIMUM LOOPS THRU TDCA	
V	FLAG FOR SELECT SET IN PHASE	
V	FLAG SET IN PHASE FOR SELECT	
V	FLAG SET IN PHASE FOR WORK TO CALL TDCA	
V	FLAG RETURNED FROM INTR2 FOR ERRORS	
V	FLAG FOR INTPL. INTR3. .1.P.A.V.=0.P ONLY	
V	FLAG, NON-ZERO FOR FXD. STP. R-K IN TRAJ	
V	PHASE LIST STORAGE	
V	CONTAINS ALL PHASES TO BE PROCESSED	
V	INPJT STORAGE BUFFER	200
V	INITIAL CONDITIONS	10
V	COORD. TYPE OF ICONDS	1
V	ITYPE	
V	ITMNU5	
V	IPHSE	
V	IQUIT	
V	IPRTFG	
V	ITYPTM	
V	IBFLGS	10
V	IQUAD	
V	IBPRIM	
V	IMAX	
V	ISLECT	
V	IRUNOT	
V	IWKFLG	
V	INTRX	
V	NVEL	
V	MRRR	
M	BLK14	
V	PHASES	
M	BLK15	
V	ICOND	
V	ITYPE	

V	SPRINT	10	PRINT
V	SPECIAL PRINT TIMES	25	
V	MIDCOURSE TIMES	25	
V	JULIAN DATE TIMES	25	
V	SEARCH VARIABLES	10	
V	TARGET BODY FOR SEARCH	1	
V	TERM CONDITIONS FOR SEARCH	10	
V	BOUNDS FOR TERMINAL CONDITIONS	10	
V	BOUNDS FOR SEARCH VARIABLES	10	
V	PHASE I. D. NUMBER (.LT. 99999.1)	1	
V	PHASE TYPE	1	
V	PHASE FINAL CONDITIONS	5	
V	PHASE TARGET CENTRAL BODY	1	
V	CURRENT CENTRAL BODY	1	
V	FLAG FOR RADIATION PRESSURE	1	
V	PHASE DELTA T. T LIST	50	
V	END JOB FLAG	1	
	ENDCOM		
	ENDJOB		

IV. Sample Output:

On the following pages is a listing of the outputs of the BLKGEN program.

PAGE

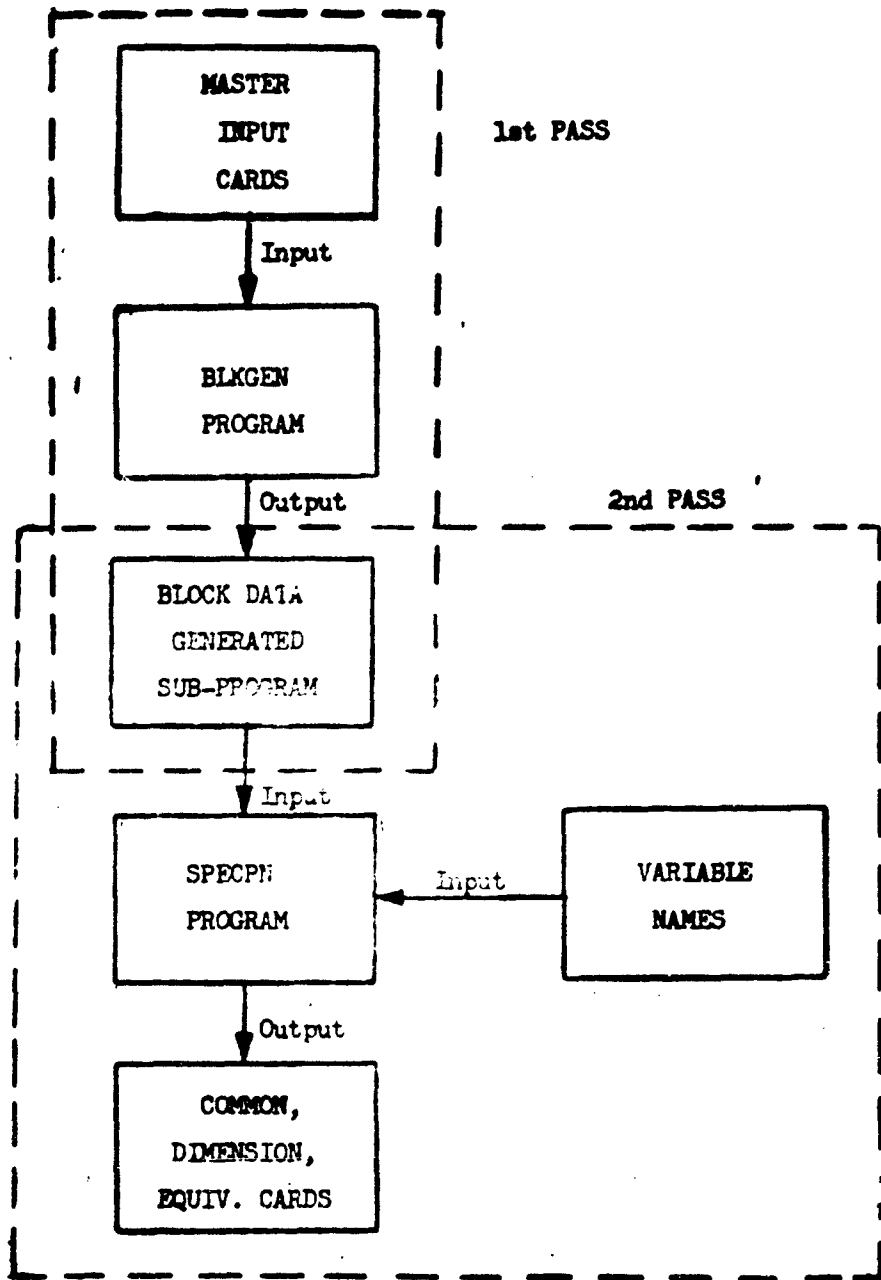
MASTER COMMON LISTING

CURRENT COMMON IS --
 COMMON
 1, BLK5 (50), BLK2 (50), BLK3 (100), BLK4 (50)
 2, BLK20 (200), BLK7 (200), BLK8 (500), BLK9 (75)
 3, BLK15 (300), BLK11 (200), BLK12 (50), BLK13 (50), BLK14 (200)

CURRENT BLOCK IS BLK1 (0) FLOATING POINT CONSTANTS

VARIABLE	DIMENSION	POSITION	TYPE	DESCRIPTION
LAE		1		EQUATORIAL RADIUS OF EARTH
COE		2		PULAN RADIUS OF EARTH
CEELIP		3		ELLIPTICITY OF EARTH
CMU		4		GRAVITATION CONSTANT OF EARTH
CWE		5		ROTATIONAL RATE OF EARTH
CGMR	10	6		GA RATIO OF E.M.S.V.M.J.S TO EARTH
KOB	10	16		RADIUS OF E.M.S.V.M.J.S TO EARTH
CERAU		25		EARTH RADIUS PER ASTRONOMICAL UNIT
CFTEK		27		FEET PER EARTH RADIUS
CINIR		28		INITIAL CONDITION PER EARTH RADIUS
CINZR		29		INITIAL CONDITION TIME PER MINUTE
COUTI		30		TERMINAL CONDITION OUTPUT PER EARTH RADIUS
COUIT2		31		TERM. COND. OUTPUT TIME PER MINUTE
CLIGHT		32		SPEED OF LIGHT
CNMEK		33		NAUTICAL MILES PER EARTH RADIUS
CKMEK		34		KILOMETERS PER EARTH RADIUS
CSJLC		35		SOLAR CONSTANT (WATTS/METER SQ)
CDAYMN		36		DAYS PER MONTH IN NON-LEAP YEAR
CDEG		48		DEGREES PER RADIAN

V. Organization and Usage of BLKGEN and SPECN Flow Chart:



VI. References:

1. Specification Statement Punch Program (SPECPN) User's Guide, A. J. DeSalvio and J. Rau, September 15, 1966, CDC Report Number 3127.21-01.

16905-6008-R0-00

Page B-1

APPENDIX B
SPECIFICATION STATEMENT PUNCH PROGRAM
(SPECPN)
User's Guide

SPECN USERS GUIDE

The SPECN (SPECification statement Pulch) program was written to aid the FORTRAN programmer in his preparation of COMMON, DIMENSION, and EQUIVALENCE statements. It was designed primarily for programs which use the philosophy of master COMMON blocks and EQUIVALENCE variables e.g.

```
COMMON/COMMON/BLK1 (100), BLK2 (5000)
EQUIVALENCE (BLK1 (26), VAR1), (BLK2 (63), VAR2)
```

In this example only the variables VAR1, VAR2 are needed from the 100 cell block BLK1 and the 5000 cell block BLK2. Using EQUIVALENCE statements to identify only those variables actually used in a subroutine significantly reduces the card volume for a subroutine and the size of the symbol table necessary at compile time. This technique is opposed to the standard one of stringing out the actual COMMON variable names in the COMMON statement e.g.

```
COMMON/COMMON/ A, B, C(3), D, E, F(16), G(2), VAR1
```

To use SPECN one must supply input in two forms. First, a BLOCK DATA subprogram must be prepared containing a map of the master COMMON blocks including a complete map of each variable in COMMON, EQUIVALENCE numbers, and DIMENSION. This BLOCK DATA subprogram is then compiled and submitted as part of the SPECN job. Unless the COMMON map changes, the BLOCK DATA subprogram will never be altered again. The second input to SPECN is data cards specifying by subroutine those variables defined in COMMON. These variables may be in blank COMMON or any of the labeled COMMON blocks defined in the BLOCK DATA subprogram. The output from SPECN is the COMMON, DIMENSION, and EQUIVALENCE statements necessary for each subroutine.

The advantages of using SPECPR are several:

- a) The format of the punched cards is uniform. This makes the program listing neat and easy to read.
- b) Once the BLOCK DATA subprogram has been verified for accuracy, the worry of mis-equivalencing a COMMON variable is ended.
- c) If significant changes are made in the COMMON map of a large scale program such that the equivalence numbers are disturbed, only the BLOCK DATA subprogram need be re-keypunched. The data cards used with the old COMMON may be re-submitted with SPECPR to recover all the COMMON, DIMENSION, and EQUIVALENCE statements for the new COMMON map.

BLOCK DATA Input to SPECPR

The BLOCK DATA subprogram must contain the following four labeled COMMON blocks:

```
COMMON/ISIZE/ISIZE
COMMON/BLK /BLK(I)
COMMON/FMT /FMT(J)
COMMON/XMCOM/XMCOM(ISIZE)
```

COMMON/ISIZE/ISIZE

ISIZE is an integer which defines the size of XMCOM. ISIZE will be $3 * N$, where N is the total number of COMMON variables defined in the users program.

COMMON/BLK /BLK(I)

BLK is a dimensioned array which contains the name of each master COMMON block in BCD. The order of the names within BLK is arbitrary.

If the following COMMON statements appeared in the user's program:

```
COMMON/ / BLK1(100), BLK2(5000)
COMMON/COMA/ABLK1(50), ABLK2(25), ABLK3(500)
```

the master COMMON block names BLK1, BLK2, ABLK1, ABLK2, ABLK3 must appear in BLK, left adjusted, in BCD. For example:

```
COMMON /BLK/BLK(5)
DATA (BLK(I),I= 1,5) /6HABLK2 ,6HBLK1 ,6HABLK3 ,
16HBLK2 ,6HABLK1 /
```

could be used to define /BLK/ for this program. The labeled COMMON block names, i.e. COMA, are not specified within BLK.

COMMON / FMT / FMT(J)

FMT is a dimensioned array defining the COMMON statements that appear in the user's program. All the information in FMT is in BCD. Since the format of a COMMON statement is so arbitrary (is it blank COMMON, or labeled COMMON; how many variables etc.) and the elements of the card so variable, the user is required to store in FMT the actual FORMAT statement that would cause the COMMON statements defined in the users program to be punched. For example; the COMMON card

```
COMMON /COMNAM / BLK1(100), BLK2(5000)
```

could be punched with the following statements

```
WRITE (12, 901)
```

```
901  FORMAT(6X,34HCOMMON/COMNAM/BLK1(100),BLK2(5000))
```

What goes into the array FMT is exactly what the compiler would generate in core at location 001: the BCD equivalent of what follows the word FORMAT, each character from " (" to the terminating ")" inclusive. In this example:

```
COMMON /FMT/FMT(7)
DATA (FMT(1),1=1,7)  /6H(6X,34,6HCOMMON,
16HN/COMN,6HAM/BLK,6H(100),6H,BLK2(,6H5000)) /
```

would be used to load the array FMT. Each COMMON statement is specified in the above manner, in any order within FMT. If the final BCD word for a given format is not a full 6 characters, fill out the word with blanks following the ") " since each "FORMAT" must begin in a new word within FMT.

COMMON/XMCOM/XMCOM(1024)

XMCOM is an N x 3 array stored singly subscripted by rows. (N is the total number of COMMON variables in the user's program). In column 1 of XMCOM is placed the name of each COMMON variable, left adjusted, in BCD. Column 2 of XMCOM contains integer code words of the form I * 10000 + J. I is the entry in BLK which identifies the master COMMON block name appropriate for this variable. J is the equivalence number of the given variable within the master COMMON block. Column 3 of XMCOM contains integer code words of the form

$K = 10000 + L$. L is the dimension of the given variable. (Non-dimensional variables are indicated with $L = 1$) K is the entry in **FMT** of the first word of the "FORMAT" statement which identifies the **COMMON** statement containing the given master **COMMON** block name. A sample **XMCOM** will now be constructed from the following **COMMON** map:

```
COMMON//BLK1(24)
COMMON/COMA/ABLK1(50)
EQUIVALENCE          (BLK1 ( 1),CAE  ),(BLK1 ( 2),TEMP  )
1,(BLK1 ( 12),CBE  ),(BLK1 ( 13),CDAYMN)
DIMENSION TEMP(10),CDAYMN(12)
EQUIVALENCE          (ABLK1 ( 1),NPR  ),(ABLK1 ( 2),NDPR  )
1,(ABLK1 ( 3),MATRIX)
DIMENSION MATRIX(48)
```

To compute **ISIZE**, we simply count the number of **COMMON** variables:

CAE, TEMP, CBE, CDAYMN, NPR, NDPR, MATRIX... 7

ISIZE: $3 * 7 = 21$

COMMON/ISIZE/ISIZE

DATA ISIZE /21/

The entries in **BLK** will be the master **COMMON** block names:

BLK1, ABLK1

COMMON / BLK / BLK(2)

DATA (BLK(I), I = 2) / 6HBLK1 , 6HABLK1 /

The **FMT** array would be constructed from the following **FORMAT** statements:

```
FORMAT(6X,16,6HCOMMON//BLK1(24))
FORMAT(6X,16,6HCOMMON/COMA/ABLK1(50))
COMMON/FMT/FMT(2)
DATA (FMT(I), I=1,4) /
16H(6X,16,6HCOMMON,6HN//BLK,6H1(24)) /
DATA (FMT(I), I=5,9) /
16H(6X,21,6HCOMMON,6HN/COMA,6H/ABLK1,6H(50)) /
```

XMCOM would look as follows:

```
COMMON/XMCOM/XMCOM(21,
EQUIVALENCE (XMCOM,IXMCOM)
DIMENSION IXMCOM(21)
DATA (XMCOM(I),I= 1,21) /
16HCAE   , 10001, 10001,
26HTEMP  , 10002, 10010,
36HCBE   , 10012, 10001,
46HCDAYMN, 10013, 10012,
56HNPR   , 20001, 50001,
66HNDPR  , 20002, 50002,
76HMATRIX, 20003, 50048/
```

- ① VARIABLE NAME
- ② BLK ENTRY
- ③ EQUIVALENCE NO.
- ④ FMT ENTRY
- ⑤ CONNECTION

For compatibility with the G.E. computer, XMCOM should be set

up as follows:

```
DATA (XMCOM(I),I= 1,21,3) /6HCAE   ,6HTEMP  ,6HCBE   ,6HCDAYMN
1,6HNPR   ,6HNDPR  ,6HMATRIX/
DATA ((IXMCOM(I),IXMCOM(I-1)),I= 2,20,3) /
1 10001, 10001,
2 10002, 10010,
3 10012, 10001,
4 10013, 10012,
5 20001, 50001,

6 20002, 50002,
7 20003, 50048/
```

DATA CARD Input to SPECN

The BLOCK DATA subprogram described above contains the complete definition of each COMMON block in the users program. The remaining inputs to SPECN are a series of fixed format data cards describing the individual COMMON variables defined in each subroutine in the users program. The data cards have the following format:

For each subroutine:

Card 1 Contains the subroutine name in columns 1 - 6.
This card serves to identify the routine which the punched and printed output from SPECN belongs. The name punched in cc 1 - 6 may be any combination of alphanumeric characters except ENDSUB or ENDJOB.

Cards 2-(N - 1) Contains the COMMON variable names, punched up to 12 per card, in columns 1 - 6, 7 - 12, 13 - 18, etc. The variable names must be left adjusted in each field.

Card N Contains ENDSUB in columns 1 - 6. The entry ENDSUB indicates to SPECN that all the variables for this subroutine have been entered. Columns 7 - 72 of this card are ignored.

The above series of cards are repeated for as many subroutines as desired. Following the final ENDSUB card must be placed a card with ENDJOB to indicate the end of the input data. See figure 1 and appendix for an example of the deck set-up and data card samples.

Output from SPECN

SPECN delivers both printed and punched output. The first block of printed output will be the XMCOM array after having been algebraically sorted about column 1. For each subroutine name card in the data deck, a message is printed stating:

THE FOLLOWING CARDS ARE FOR SUBROUTINE XXXXXX

This card is also punched. Next will be the EQUIVALENCE, DIMENSION, and COMMON cards, in that order. Continuation cards are indicated with an E in column 6 for EQUIVALENCE and a D in column 6 for DIMENSION. A card image is printed and punched. In the event that a variable is requested in the data deck that does not appear in XMCOM, the following error message is printed only:

ERROR - XXXXXX NOT IN XMCOM.

Operating Notes

One point that should be noted is the flexibility which results from the use of the FMT array in the BLOCK DATA subprogram. As was explained above, SPECN simply executes a WRITE (12, FMT(I)) in order to punch the Ith COMMON statement. In theory then, the user can direct

SPECFN to punch any card, in any arbitrary format for any arbitrary subroutine. For instance the user could place in **FMT** the necessary control characters to cause comments cards to be punched before or after **COMMON** statements, which define the variables in that **COMMON** block. Another use of **FMT** might be to include **DIMENSION** card images for those variables which are multi-dimensioned in the user's program since there is no provision in **XMCOM** for indicating such.

This could be accomplished as follows:

- a) Place in **FMT(J)** the **FORMAT** statement that would cause the desired **DIMENSION** statement to be punched.
- b) In the appropriate column 3 entry in **XMCOM**, set the dimension of the multi-dimensioned variable to 1.
- c) Instead of pointing to the **COMMON** card image in **FMT** for this variable, point to the **DIMENSION** card image, **J**.
- d) Be sure that another variable in the subroutine list does point to the proper **COMMON** card image.

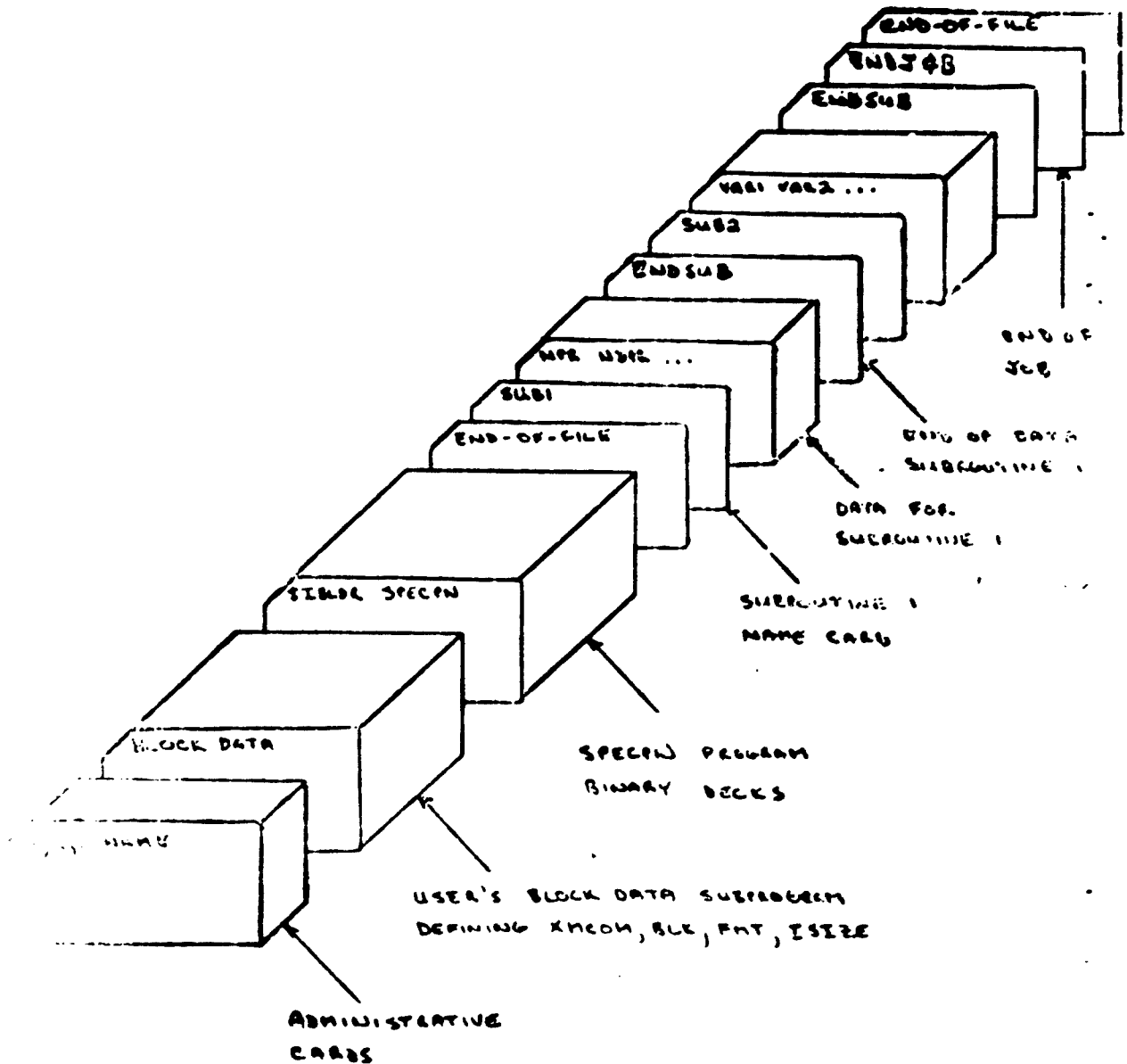
Setting the dimension to 1 will suppress the punching of a standard **DIMENSION** card.

To aid the spot checking of **EQUIVALENCE** variables it is a good practice to list the variables in ascending **EQUIVALENCE** order on the data cards for each subroutine. If it is desired to obtain **EQUIVALENCE** cards by master **COMMON** block, that is, have **SPECFN** start with a new **EQUIVALENCE** card for each new master **COMMON** block, it is only necessary to back up the variables by **COMMON** block within a subroutine and submit each set under the name of the same subroutine. The fact that the subroutine name is repeated within the data deck is immaterial since it is used only for identification of the output.

The following restrictions should be observed when running **SPECFN**:

- a) The total size of **XMCOM** + **BLK** + **FMT** must not exceed $22,753_{10}$ cells. This is based on the **SPECFN** version currently in use on the 7094.

- b) Do not use a subroutine card with ENDSUB or ENDJOB in columns 1 - 6. These variables may appear on a data card providing they are not placed in columns 1 - 6.
- c) No variable name may be repeated in XMCOM.
- d) When operating on the 7094, a PUNCH card should be included in the administrative cards if more than 500 punched cards are expected or if it is desired to have the punched cards listed and/or interpreted.



SPECN DECK SETUP - FIGURE 1

The following page is an example of the data card
input to SPECPR

FIRST	ACT	DIP	KLT	FADK	ZOT	NPR	BUM	NON	ONK	MP	TNS
CAE			THUMP								KKK
KNT			DOG	DRV	KUFK	INT	UMP		ORB		CK
ONTL	NOUNT	DNR	HLT	BLKK							LO
MNN	GGGG	DGN	UVM	KZY	FLY	FADK	ZXA	LAVA			CDM
KNOLH	AROUSEUV		SPOT				AAAD				
ENDSUB	ANT										
SECOND											
CDAYNAB	BAB	DNK	SPOT	KLT	INT	FADK	ZOT	FLY	NON	MP	BLKK
CBE	DALP	CAT	UMP	XOLT	KZY	DRV	NDR	OPT	FDP	AHLT	JOB
KJJ	DNR	CK	TORB	DIP	AAAD	RTS	OKL	AGGG	LAVA	ZXA	KNT
DOT	ACT	KKK	BBFK	ORB	CNTP	PCNOM	WV	NPP	BUM	DOG	DAB
XUFK	ER	ZMPT	MOUSE	CELLIP	ABAD	COO	CAEM	CKK	KLRSS	NIN	SNK
OINK	XUFK	DGN	BOND	TNS	DDDD	RTS	SYGL	LLAE	RZMPT	WTHUMP	THUMP
XOLT	KOO	ONK	BLKK	FLY	EGT	HLT	JOT	EGND	OPT	NPR	DEE
CK	MP	KKK	BMFK	ACT	WV	LOT	CDM	NPP	AEAB	WYHNTNS	
ENDSUB											
THIRD											
CELLIFC	DAYM	KKK	FLY				LAND				
ENDSUB											
FOURTH											
ACT	JOB										
ENDSUB											
FIFTH											
CAT											
ENDSUB											
SIXTH											
ENDSUB											
SIX											
KOO	FLY	DOT	DIP	ABAD	DNK	ZOT	KKK	DRV			
ENDSUB											
ENDJOB											

CELLIP

KUFK

The following pages illustrate the punch card
output from SPECPR

E.(DOPLR (9),BOND (1),TRAJ (3),DNC (3),ZOT (4),FLY (7),RIS (2)
 DIMENSION ABAB (2),KJJ (2),DIP (6),AAAU (3)
 D.CAT (6),DRV (6),CGNOM (6),UWV (8),XUFX (6),ABAB (3)
 D.DOT (3),KGG (2),XUFX (6)
 D.KGG (2),XUFX (6)
 EQUIVALENCE (COLB (23),SIGL (1),BLK3 (24),IHUMP (1)
 E.(BLK6 (2),XULT (1),COLB (17),KOC (1),COLB (4),UNK (1)
 E.(BLK7 (1),BLK (1),DOPLR (1),FLY (1),DOPLR (1),DGN (1)
 E.(DOPLR (2),HLT (1),BLK3 (1),DOT (1),DOPLR (2),BOND (2)
 E.(BLK2 (1),NPR (1),MZA (4),DIP (4),BLK6 (17),CK (1)
 E.(TRAJ (6),MP (1),BLK6 (1),KKK (1),BLK6 (3),BNFK (1)
 E.(BLK3 (23),ACT (1),BLK3 (25),DUMP (1),BLK3 (13),LOT (1)
 E.(BLK3 (1),CDM (1),MZA (1),NPP (1),BLK2 (6),ABAB (1)
 E.(BLK1 (10),CDAYMN),(TRAJ (1),TNS (1)
 DIMENSION KGG (2),FLY (2),DOT (3),DIP (6)
 D.KKK (6),LOT (10),ABAB (3)
 COMMON //BLK1(10),BLK2(8),TJA(2)
 COMMON/BLAH/MZA(26),BLK3(9),BLK4(1),BLK5(2),BLK6(19),COLB(26)
 1,BLK7(1)
 COMMON /HIPPO/TRAJ(6),DOPLR(12)
 C THE FOLLOWING CARDS ARE FOR SUBROUTINE THIRD
 EQUIVALENCE (BLK1 (3),CELLIP),(BLK1 (10),CDAYMN)
 E.(BLK6 (11),KKK (1),DOPLR (11),FLY (1),DOPLR (10),LAND (1)
 DIMENSION KKK (6),FLY (2)
 COMMON //BLK1(10),BLK2(8),TJA(2)
 COMMON/BLAH/MZA(26),BLK3(9),BLK4(1),BLK5(2),BLK6(19),COLB(26)
 1,BLK7(1)
 COMMON /HIPPO/TRAJ(6),DOPLR(12)
 C THE FOLLOWING CARDS ARE FOR SUBROUTINE FOURTH
 EQUIVALENCE (BLK3 (23),ACT (2),DOPLR (3),JOB (1)
 COMMON/BLAH/MZA(26),BLK3(9),BLK4(1),BLK5(2),BLK6(19),COLB(26)
 1,BLK7(1)
 COMMON /HIPPO/TRAJ(6),DOPLR(12)
 C THE FOLLOWING CARDS ARE FOR SUBROUTINE FIFTH
 EQUIVALENCE (BLK4 (2),CAT (1)
 DIMENSION CAT (6)
 COMMON/BLAH/MZA(26),BLK3(9),BLK4(1),BLK5(2),BLK6(19),COLB(26)
 1,BLK7(1)
 C THE FOLLOWING CARDS ARE FOR SUBROUTINE SIXTH
 EQUIVALENCE (BLK6 (5),RUPK (1),DLKI (3),CELLIP)
 DIMENSION KUFK (6)

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1, BLK7(1)

COMMON //BLK1(10),BLK2(18),TJA(2)

C THE FOLLOWING CARDS ARE FOR SUBROUTINE SIX

EQUIVALENCE

E, (BLK3 (10), DOT (17), K00 (1), DOPLR (11), FLY (6))

E, (MZA (10), DNK (3), ZOT (4), DIP (6), ABAB (6), ABAB (6))

E, (MZA (10), DNK (3), ZOT (4), DIP (6), ABAB (6), ABAB (6))

DIMENSION K00 (2), FLY (2), DOT (2), DIP (3), DIP (6)

D, ABAB (3), DNK (3), ZOT (4), KKK (6), DRV (2)

COMMON/BLAH/MZA(26),BLK3(9),BLK4(1),BLK5(2),BLK6(15),COLB(26)

1, BLK7(1)

COMMON /HIPPO/TRAJ(6),DOPLR(12)

COMMON //BLK1(10),BLK2(18),TJA(2)