



INSTITUTE FOR DEFENSE ANALYSES

**DATAWorks 2020:  
A Notional Case Study of Uncertainty Analysis in Live  
Fire Modeling and Simulation**

Rebecca Medlin, Project Leader

Mark A. Couch  
Thomas A. Johnson  
Heather M. Wojton

March 2020

Approved for Public Release.

IDA Document NS D-13101

Log: H 2020-000076

INSTITUTE FOR DEFENSE ANALYSES  
4850 Mark Center Drive  
Alexandria, Virginia 22311-1882



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#### About This Publication

This work was conducted by the Institute for Defense Analyses (IDA) under contract HQ0034-19-D-0001, Task C9082, "Cross-Divisional Statistics and Data Science Working Group," for the Office of the Director, Operational Test and Evaluation. The views, opinions, and findings should not be construed as representing the official position of either the Department of Defense or the sponsoring organization.

#### Acknowledgments

The IDA Technical Review Committee was chaired by Mr. Robert R. Soule and consisted of Rebecca M. Medlin from the Operational Evaluation Division.

#### For more information:

Rebecca M. Medlin, Project Leader  
rmedlin@ida.org • 703-845-6731

Robert R. Soule, Director, Operational Evaluation Division  
rsoule@ida.org • (703) 845-2482

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## Executive Summary

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A vulnerability assessment, which evaluates the ability of an armored combat vehicle and its crew to withstand the damaging effects of an anti-armor weapon, presents a unique challenge. Since there are many areas that need to be assessed on the vehicle and testing is destructive, this limits the number of full-up, system-level tests to quantities that generally do not support meaningful statistical inference.

The prevailing solution to this problem is to obtain test data that is more affordable from sources that include component-

and subsystem-level testing. This creates a new challenge that forms the premise of this paper: how can we connect lower-level data sources to provide a credible system-level prediction of vehicle vulnerability? This paper presents a notional case study of an approach to this problem that emphasizes the use of fundamental statistical techniques—design of experiments, statistical modeling, and propagation of uncertainty—in the context of a combat scenario that depicts a ground vehicle engaged by indirect artillery.





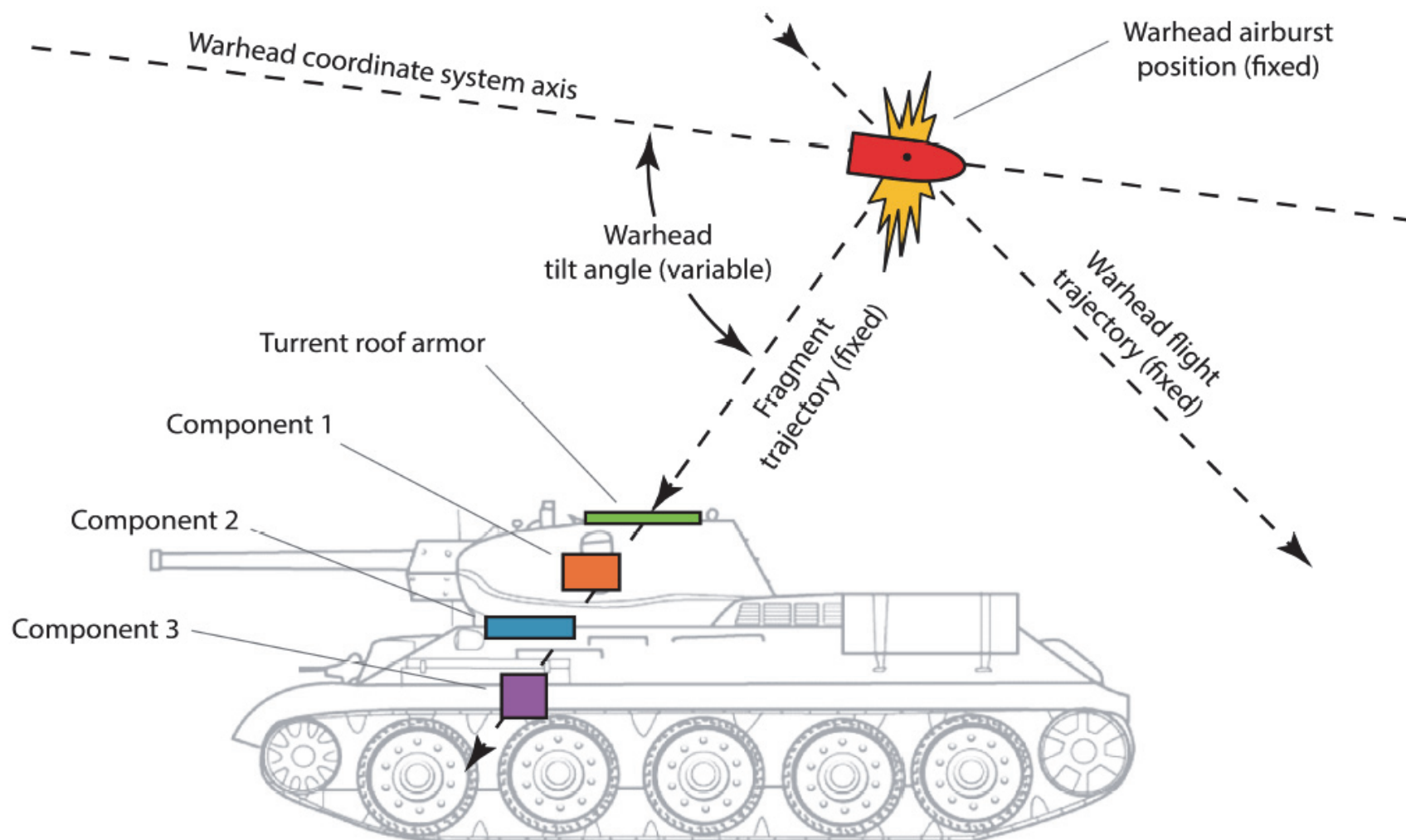
# A Notional Case Study of Uncertainty Analysis in Live Fire Modeling and Simulation

Tom Johnson  
Heather Wojton  
Mark Couch

February 19, 2020

**Institute for Defense Analyses**  
4850 Mark Center Drive • Alexandria, Virginia 22311-1882

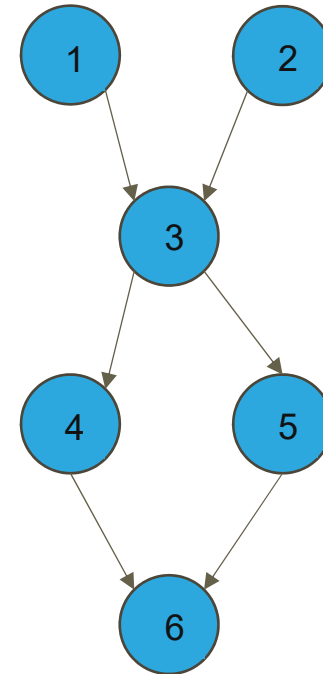
# Case Study Engagement Scenario



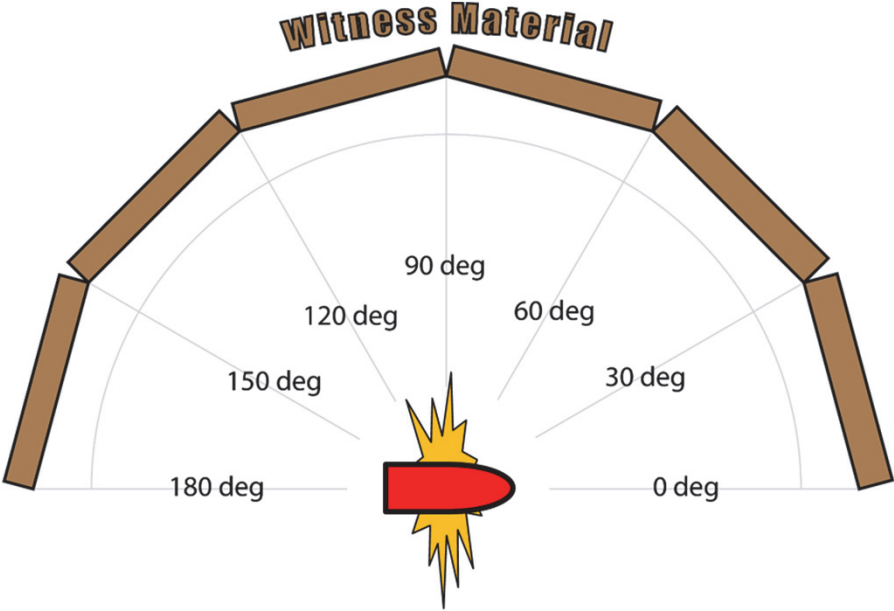
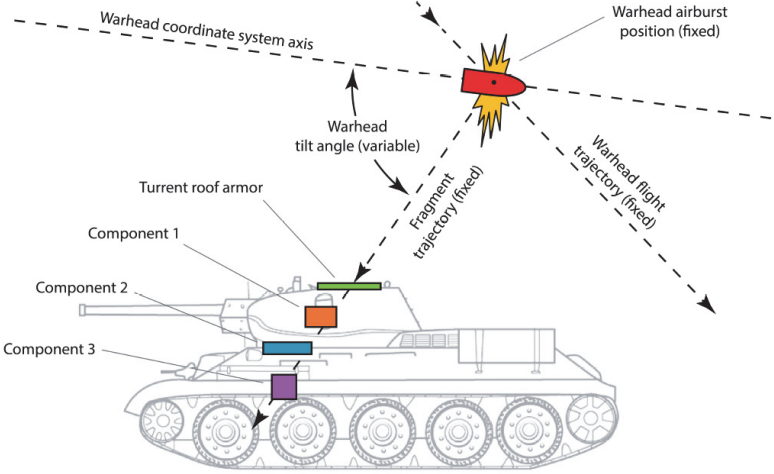


# Three experiments, six models

- Warhead Airburst Experiment
  1. Fragment velocity model
  2. Fragment mass model
- Armor Coupon Experiment
  3. Probability of penetration model
  4. Residual velocity model
  5. Residual mass model
- Component Damage Experiment
  6. Probability of component damage model



# Experiment 1: Warhead Airburst



# Experiment 1: Warhead Airburst

Model 1: Fragment velocity model

Gaussian Process Model – typical formulation

$$y_{ij}^I \sim \text{normal}(f_i^I, \sigma^I) \quad \forall i \in \{1, 2, \dots, 13\} \text{ and } j \in \{1, 2, \dots, n_i^I\}$$

$$f^I \sim \text{multivariate normal}(0, K(x | \alpha^I, \rho^I))$$

$$\alpha^I \sim \text{half normal}(0, .05)$$

$$\rho^I \sim \text{inv gamma}(.05, .05)$$

$$\sigma^I \sim \text{half normal}(0, 1)$$

# Experiment 1: Warhead Airburst

Model 1: Fragment velocity model

Gaussian Process Model – latent variable formulation

$$y_{ij}^I \sim \text{normal}(f_i^I, \sigma^I) \quad \forall i \in \{1, 2, \dots, 13\} \text{ and } j \in \{1, 2, \dots, n_i^I\}$$

$$f^I = L^I \eta^I$$

$$L^I = \text{cholesky decompose}(K(x | \alpha^I, \rho^I))$$

$$\eta_i^I \sim \text{normal}(0, 1) \quad \forall i \in \{1, \dots, 13\}$$

$$\alpha^I \sim \text{half normal}(0, 1)$$

$$\rho^I \sim \text{inv gamma}(.1, .1)$$

$$\sigma^I \sim \text{half normal}(0, 1)$$

# Experiment 1: Warhead Airburst

## Model 2: Fragment mass model

Gaussian Process Model – latent Mott variable formulation

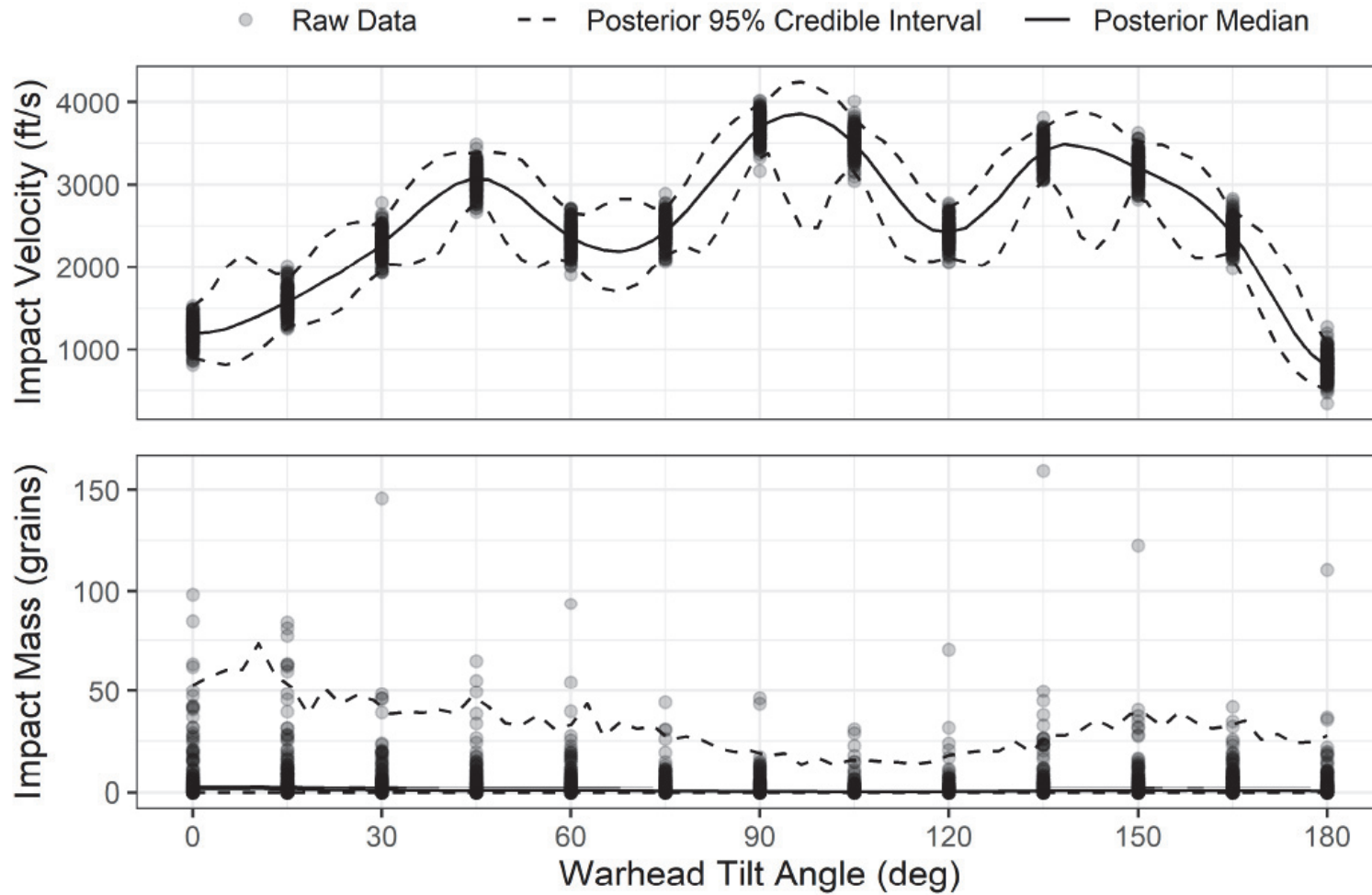
$$y_{ij}^{\text{II}} \sim \text{Mott}(f_i^{\text{II}}) \quad \forall i \in \{1, \dots, 13\} \text{ and } j \in \{1, 2, \dots, n_i^{\text{II}}\}$$
$$\log(f^{\text{II}}) = L^{\text{II}} \eta^{\text{II}}$$
$$L^{\text{II}} = \text{cholesky decompose}(K(x | \alpha^{\text{II}}, \rho^{\text{II}}))$$
$$\eta_i^{\text{II}} \sim \text{normal}(0, 1) \quad \forall i \in \{1, \dots, 13\}$$
$$\alpha^{\text{II}} \sim \text{half normal}(0, 1)$$
$$\rho^{\text{II}} \sim \text{inv gamma}(.1, .1)$$

Mott pdf:

$$p(a | b) = \frac{1}{2b} \left(\frac{a}{b}\right)^{-1/2} e^{-(a/b)^{1/2}}$$

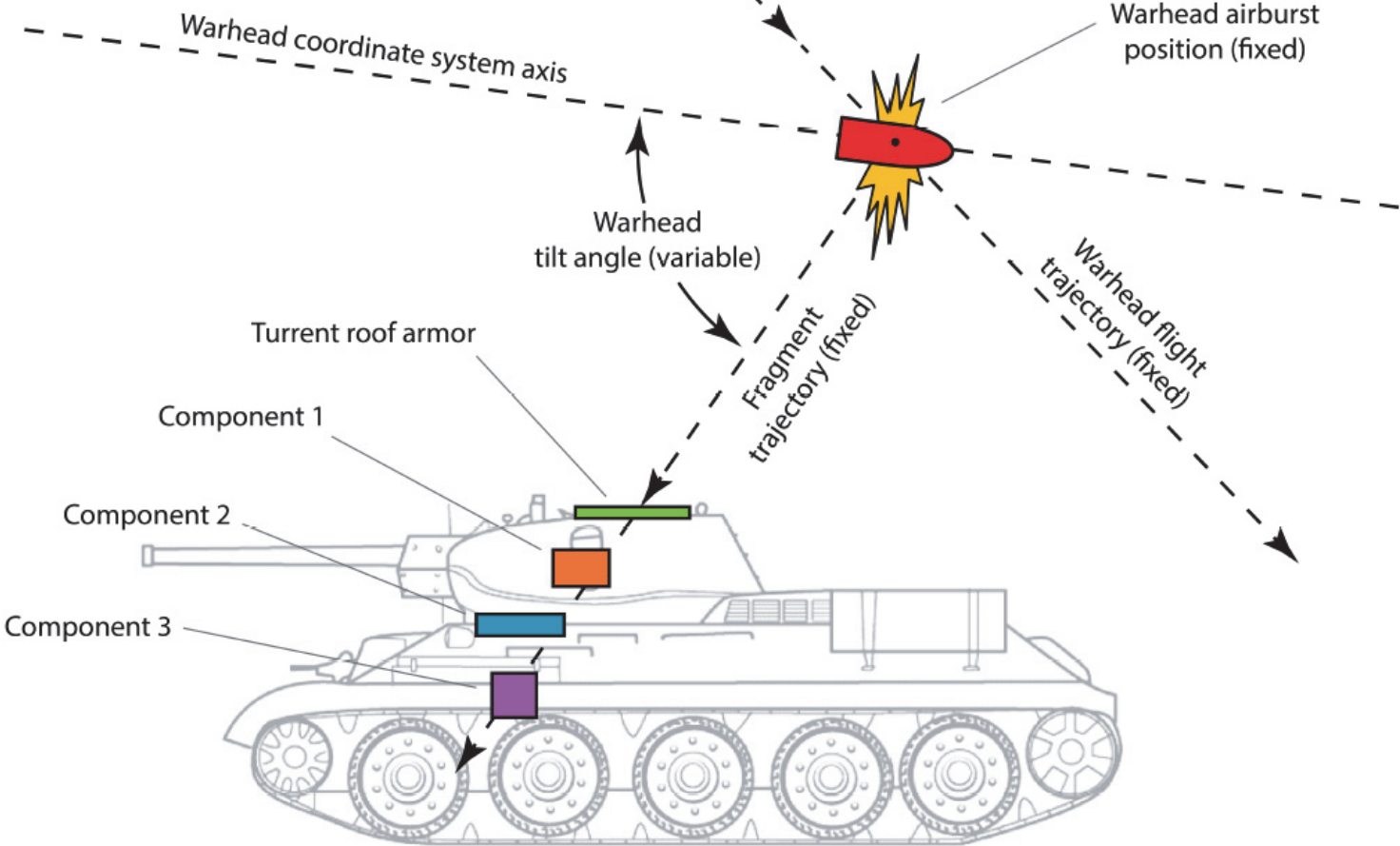
N. Mott, E. Linfoot, A Theory of Fragmentation, in: Fragmentation of Rings and Shells: The Legacy of N.F. Mott, Shock Wave and High Pressure Phenomena, Springer Berlin Heidelberg, Berlin, Heidelberg, 2006, p. 11 (2006).

# Experiment 1: Warhead Airburst



Notional data

# Experiment 2: Armor Coupon Experiment



## Experiment 2: Armor Coupon Experiment

Model 3: Probability of penetration model

$$y_k^{\text{III}} \sim \text{Bernoulli}(\mu_k^{\text{III}}) \quad \forall k \in \{1, 2, \dots, n^{\text{III}}\}$$

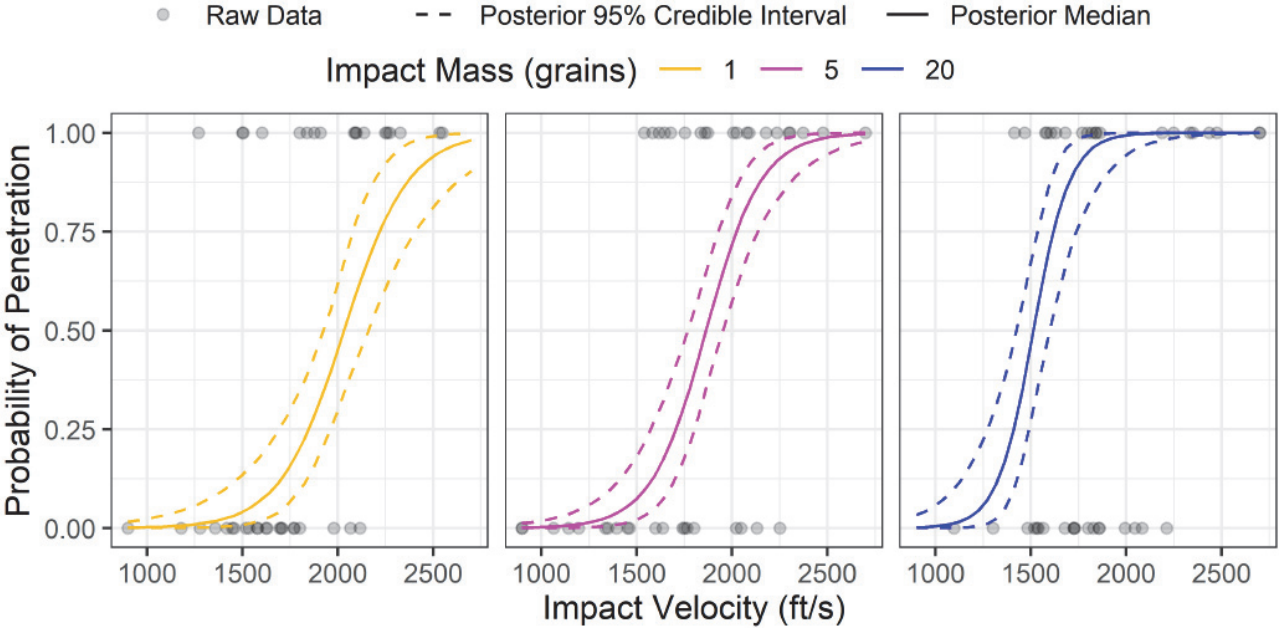
$$\text{logit}(\mu_k^{\text{III}}) = \beta_A^{\text{III}} + \beta_B^{\text{III}} m_k + \beta_C^{\text{III}} v_k + \beta_D^{\text{III}} m_k v_k$$

$$\beta_A^{\text{III}}, \beta_B^{\text{III}}, \beta_C^{\text{III}}, \beta_D^{\text{III}} \sim \text{normal}(0, 10)$$



# Experiment 2: Armor Coupon Experiment

## Model 3: Probability of penetration model



Notional data

## Experiment 2: Armor Coupon Experiment

Model 4: Residual mass model

$$u_j \sim \text{exponential}(\tau_j)$$

$$\log(\tau_j) = \beta_E + \beta_F m_j + \beta_G v_j + \beta_H m_j v_j$$

$$\beta_E, \beta_F, \beta_G, \beta_H \sim \text{normal}(0, 1)$$

## Experiment 2: Armor Coupon Experiment

Model 5: Residual velocity model

$$w_j \sim \text{normal}(\gamma_j, \sigma)$$

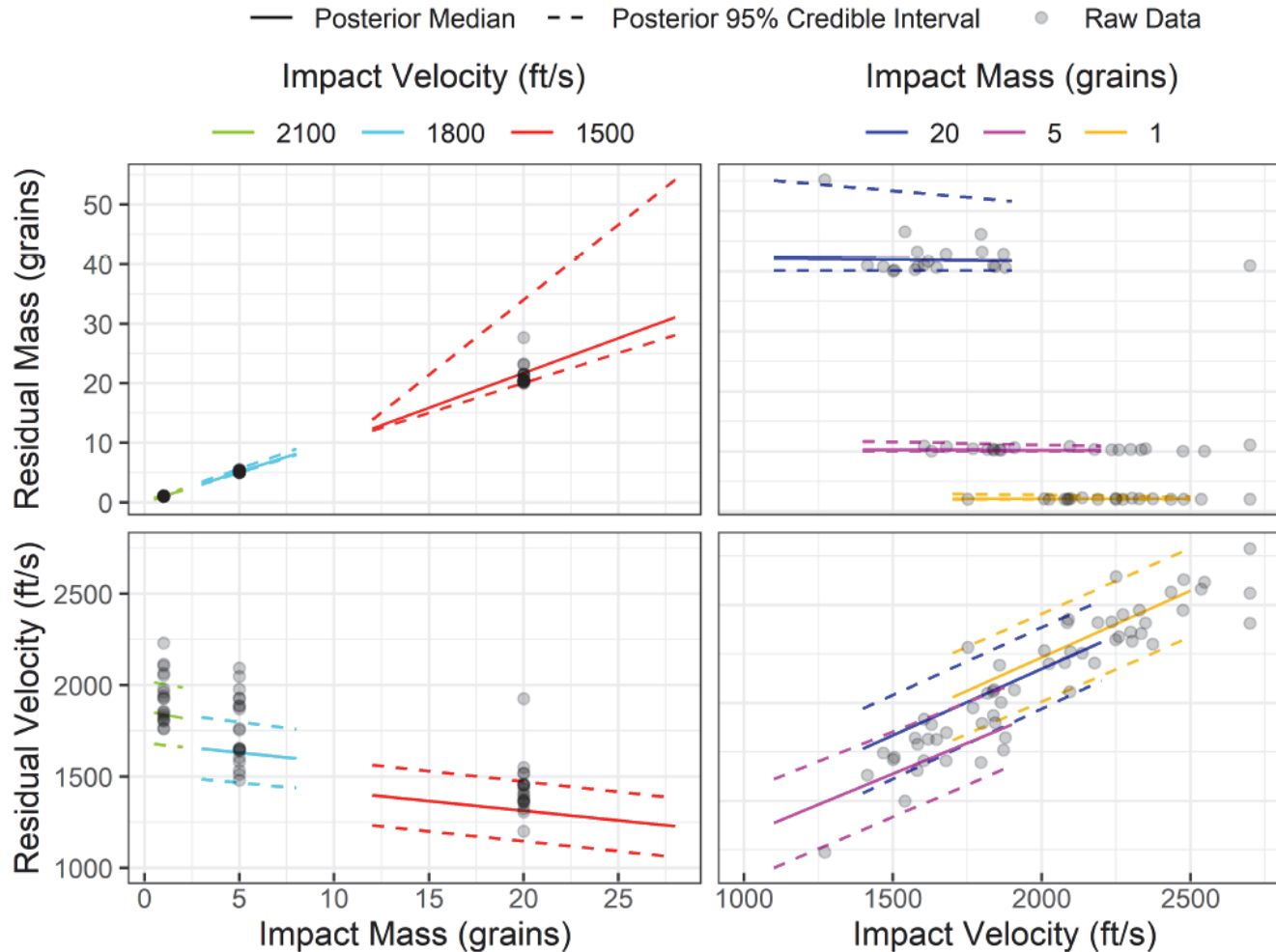
$$\gamma_j = \beta_P + \beta_Q m_j + \beta_R v_j + \beta_S m_j v_j$$

$$\beta_P, \beta_Q, \beta_R, \beta_S \sim \text{normal}(0, 10)$$

$$\sigma \sim \text{normal}(0, 10)$$

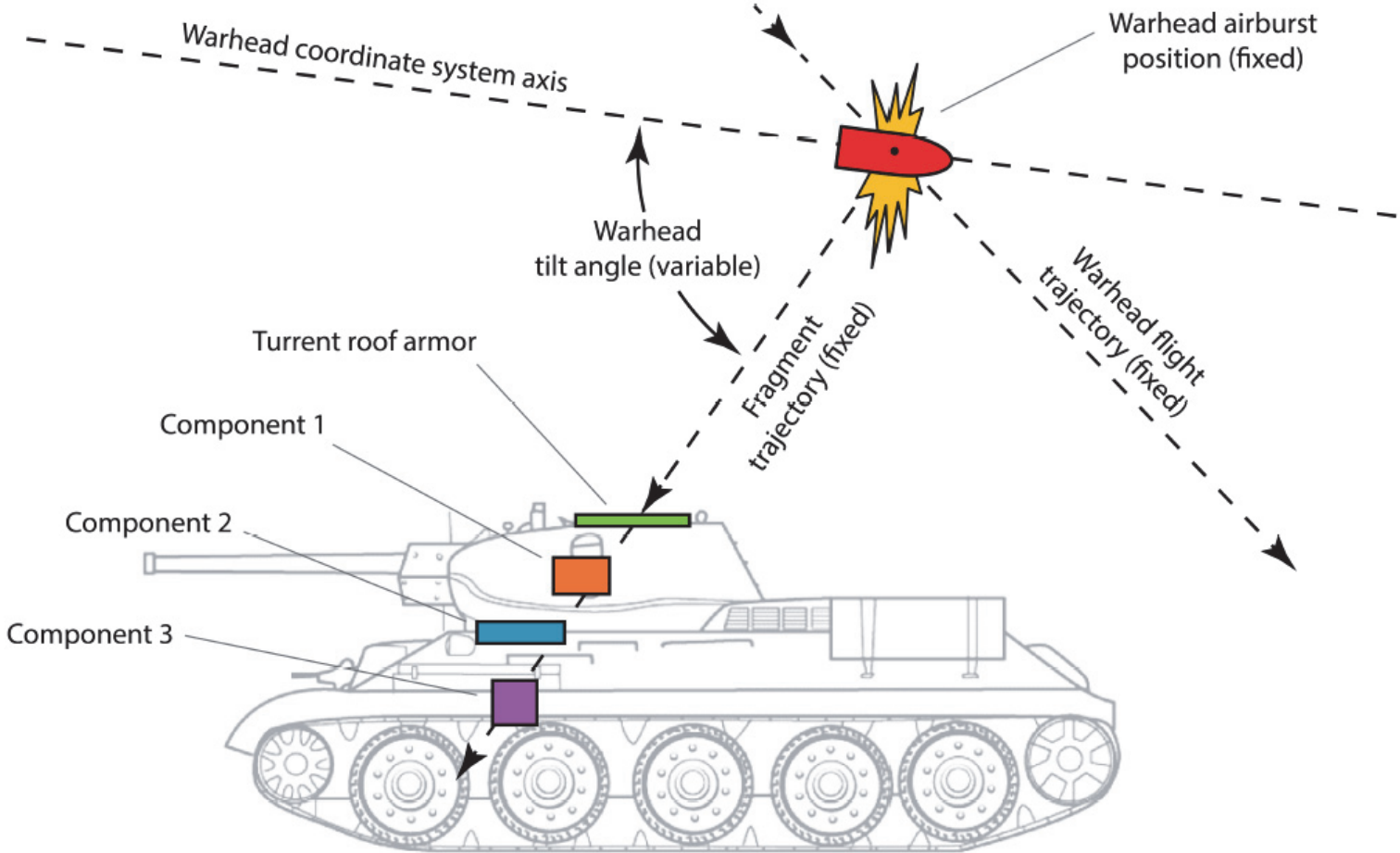
# Experiment 2: Armor Coupon Experiment

## Models 4 and 5: Residual mass and velocity models



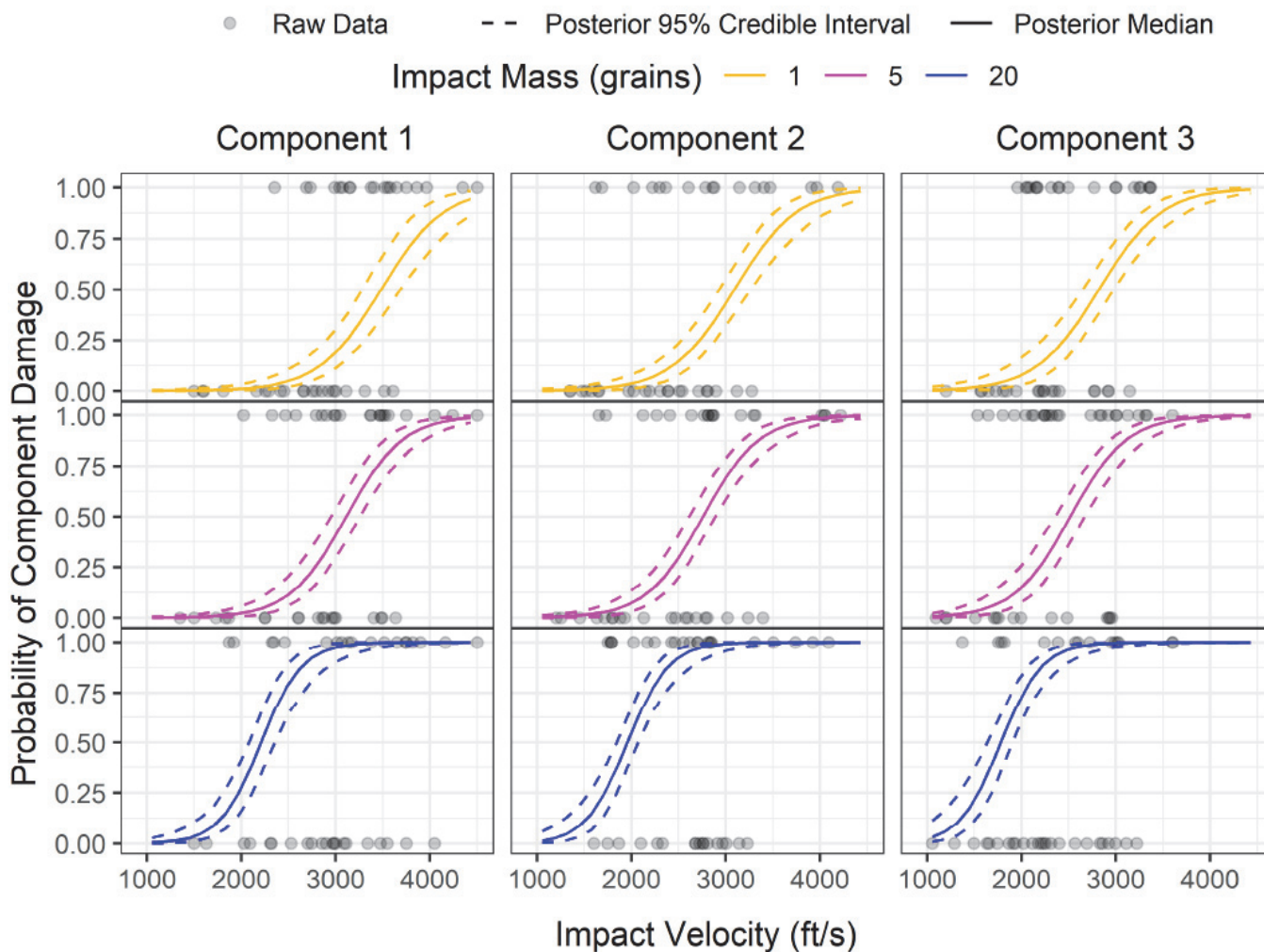
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# Experiment 3: Component Damage Experiment



# Experiment 3: Component Damage Experiment

## Model 6: Probability of component damage model



Notional data

# Propagation of Uncertainty

## First Model

*Inputs (factors and levels)*

Fragment  
Trajectory  
Angle

Warhead  
Airburst  
Model

*Outputs (response variables)*

Impact Mass  
Impact Velocity

## Second Model

*Inputs (factors and levels)*

Impact Mass  
Impact Velocity

Armor  
Coupon  
Model

*Outputs (response variables)*

Probability of Perforation  
Residual Mass  
Residual Velocity

## Propagation of Uncertainty from First to Second Model

*Inputs*

Fragment  
Trajectory  
Angle

Warhead  
Airburst  
Model

Impact Mass  
Impact Velocity

Armor  
Coupon  
Model

*Outputs (response variables)*

Probability of Perforation  
Residual Mass  
Residual Velocity

# Propagation of Uncertainty

We use the following Monte Carlo technique to propagate prediction uncertainty from the impact velocity and impact mass model into the prediction uncertainty in the residual velocity model.

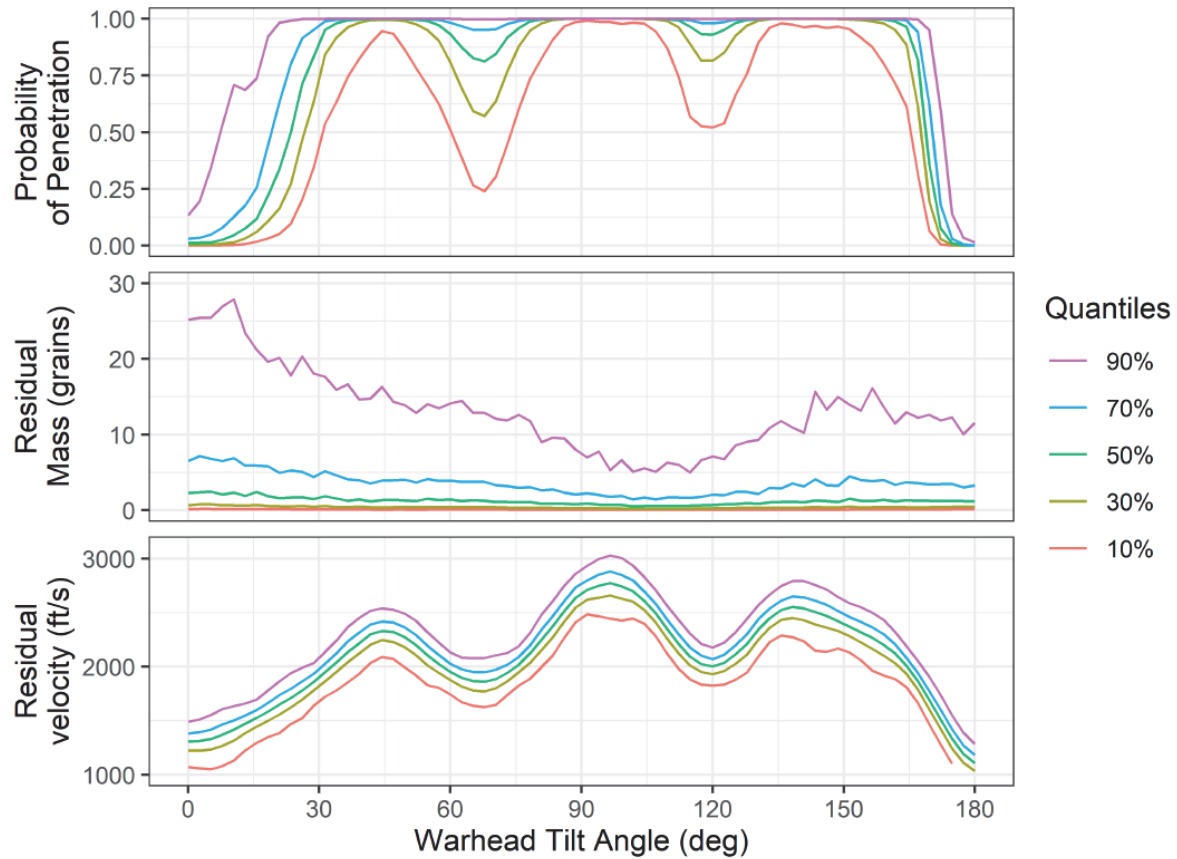
1. For a given tilt angle, draw a single predicted response variable ( $\tilde{v}$ ) from the impact velocity model's posterior predictive distribution.
2. For a given tilt angle, Draw a single predicted response variable ( $\tilde{m}$ ) from the impact mass model's posterior predictive distribution.
3. Draw a vector of model parameters ( $\beta_P, \beta_Q, \beta_R, \beta_S, \sigma$ ) from the joint posterior distribution of the residual velocity model.
4. Simulate a single predicted residual velocity ( $\tilde{w}$ ) from

$$\tilde{w} \sim \text{normal}(\beta_P + \beta_Q \tilde{m} + \beta_R \tilde{v} + \beta_S \tilde{m} \tilde{v}, \sigma) \quad . \quad (7)$$

5. Repeat steps 1-4 to create a distribution of  $\tilde{w}$  for a given tilt angle.
6. Repeat steps 1-5 for each tilt angle.

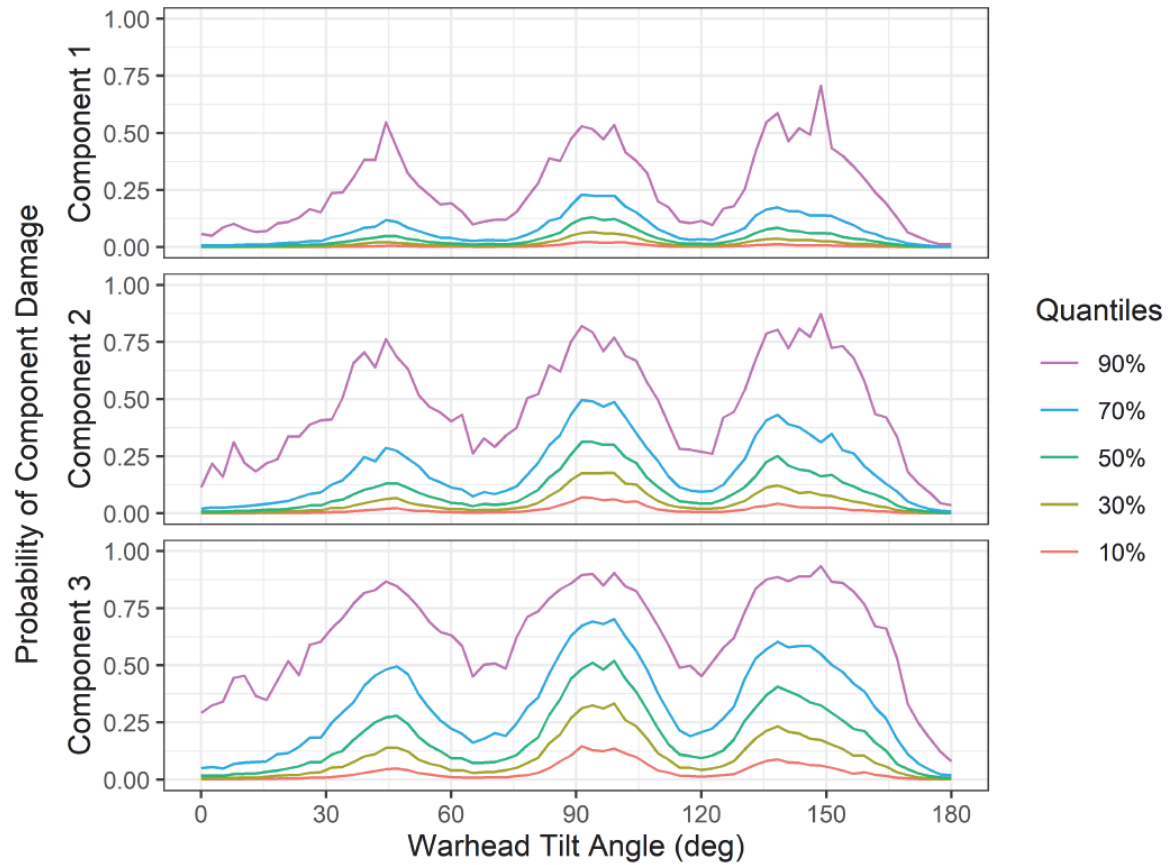


# Propagation of Uncertainty - Stage 1



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# Propagation of Uncertainty – Stage 2



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# Propagation of Uncertainty – Stage 3

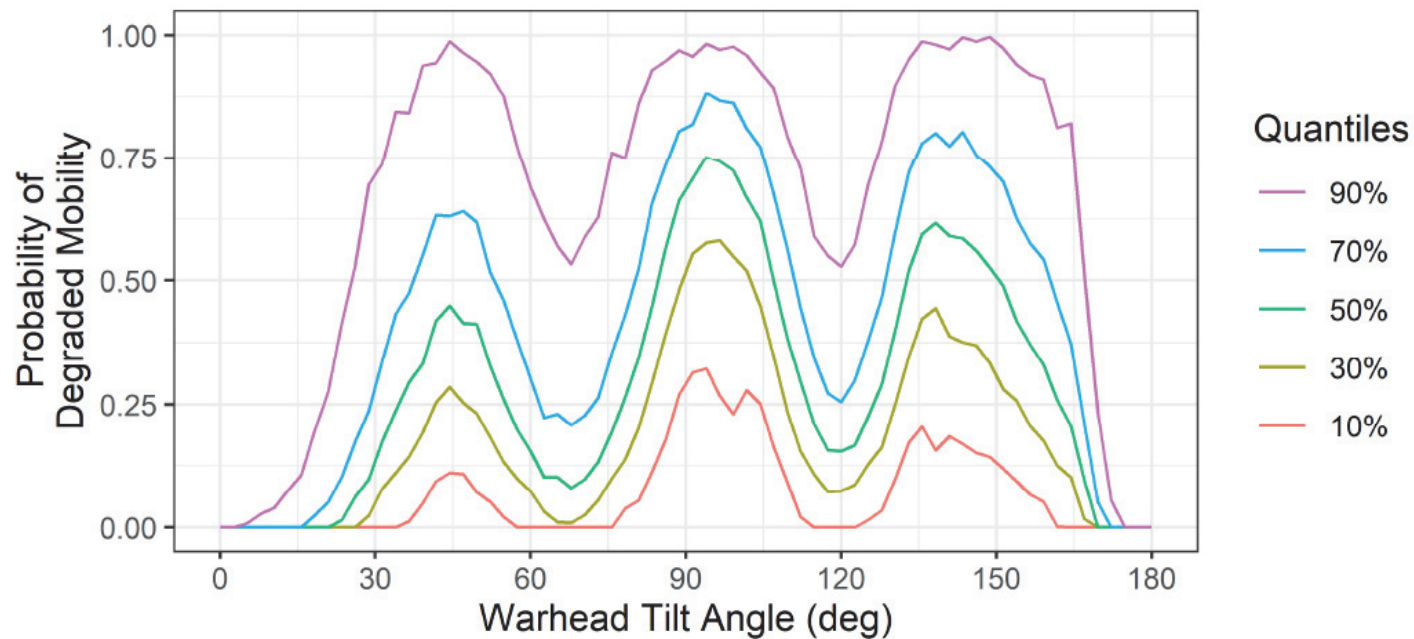
$$p_{m ds/cd} = 1 - (1 - p_{c1d/h})(1 - p_{c2d/h})(1 - p_{c3d/h})$$

Probability of  
mobility degraded  
state  
given prob of  
component damages

Probability of  
component 1  
non-dysfunction

Probability of  
component 2  
non-dysfunction

Probability of  
component 3  
non-dysfunction



Notional data



# REPORT DOCUMENTATION PAGE

Form Approved  
OMB No. 0704-0188

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<b>1. REPORT DATE (DD-MM-YYYY)</b> 10-03-2020		<b>2. REPORT TYPE</b> IDA Publication		<b>3. DATES COVERED (From - To)</b> 1 March 2020 – 31 March 2020	
<b>4. TITLE AND SUBTITLE</b>  DATAWorks 2020: A Notional Case Study of Uncertainty Analysis in Live Fire Modeling and Simulation				<b>5a. CONTRACT NUMBER</b> HQ0034-19-D-0001	
				<b>5b. GRANT NUMBER</b> _____	
				<b>5c. PROGRAM ELEMENT NUMBER</b> _____	
<b>6. AUTHOR(S)</b>  Johnson, Thomas H.; Wojton, Heather M.; Couch, Mark A.				<b>5d. PROJECT NUMBER</b> ER-7-2351	
				<b>5e. TASK NUMBER</b> C9082	
				<b>5f. WORK UNIT NUMBER</b> _____	
<b>7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES)</b> Institute for Defense Analyses 4850 Mark Center Drive Alexandria, Virginia 22311-1882				<b>8. PERFORMING ORGANIZATION REPORT NUMBER</b> NS D-13101  H 2020-000076	
<b>9. SPONSORING / MONITORING AGENCY NAME(S) AND ADDRESS(ES)</b> Institute for Defense Analyses 4850 Mark Center Drive Alexandria, Virginia 22311-1882				<b>10. SPONSOR/MONITOR'S ACRONYM(S)</b> IDA	
				<b>11. SPONSOR/MONITOR'S REPORT NUMBER</b> _____	
<b>12. DISTRIBUTION / AVAILABILITY STATEMENT</b> Approved for Public Release. Distribution Unlimited.					
<b>13. SUPPLEMENTARY NOTES</b> _____					
<b>14. ABSTRACT</b> A vulnerability assessment, which evaluates the ability of an armored combat vehicle and its crew to withstand the damaging effects of an anti-armor weapon, presents a unique challenge because vehicles are expensive and testing is destructive. This limits the number of full-up-system-level tests to quantities that generally do not support meaningful statistical inference. The prevailing solution to this problem is to obtain test data that is more affordable from sources which include component- and subsystem-level testing. This creates a new challenge that forms the premise of this paper: how can lower-level data sources be connected to provide a credible system-level prediction of vehicle vulnerability? This paper presents a case study that demonstrates an approach to this problem that emphasizes the use of fundamental statistical techniques—design of experiments, statistical modeling, and propagation of uncertainty—in the context of a combat scenario that depicts a ground vehicle being engaged by indirect artillery.					
<b>15. SUBJECT TERMS</b> Department of Defense, Live Fire Test and Evaluation, Penetration Mechanics \sep Design of Experiments \sep Computer Simulation, Test and Evaluation, Validation					
<b>16. SECURITY CLASSIFICATION OF:</b>			<b>17. LIMITATION OF ABSTRACT</b>  Unlimited	<b>18. NUMBER OF PAGES</b>  29	<b>19a. NAME OF RESPONSIBLE PERSON</b> Rebecca M. Medlin
<b>a. REPORT</b> Unclassified	<b>b. ABSTRACT</b> Unclassified	<b>c. THIS PAGE</b> Unclassified			<b>19b. TELEPHONE NUMBER (include area code)</b> (703) 845-6731