Component Mismatches Are a Critical Bottleneck to Fielding AI-Enabled Systems in the Public Sector

AAAI 2019 Fall Symposium Series AI in Government and Public Sector

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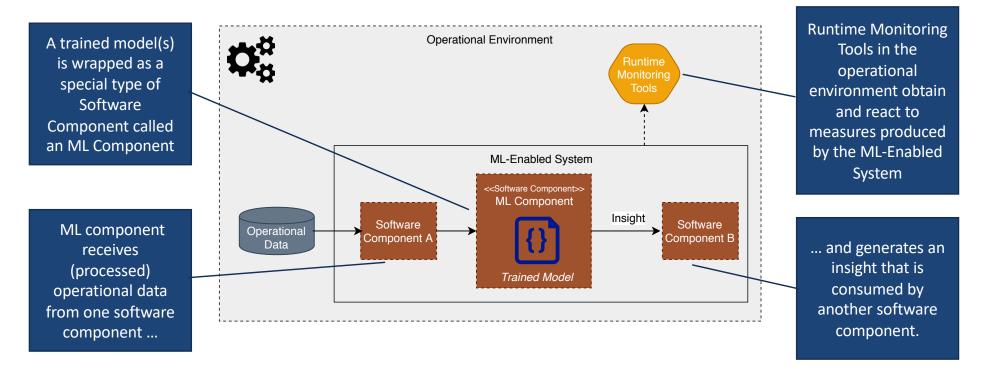
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ML-Enabled System

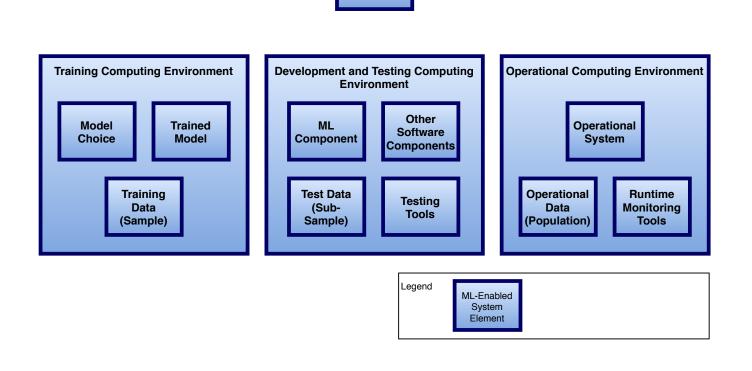
We define an ML-enabled system as a software system that relies on one or more ML software components to provide required capabilities



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Elements of ML-Enabled Systems



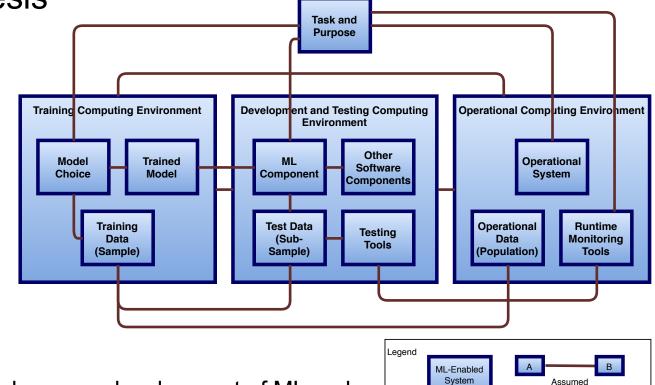
Task and Purpose

We define elements of MLenabled systems as the nonhuman entities involved in the training, integration and operation of MLenabled systems.

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Motivation/Hypothesis

Many of the challenges for deploying MLenabled systems into operational environments is due to mismatch between elements of ML-enabled systems



Very little existing guidance because development of ML and AI capabilities is still mainly a research activity or a standalone project, with the exception of large companies

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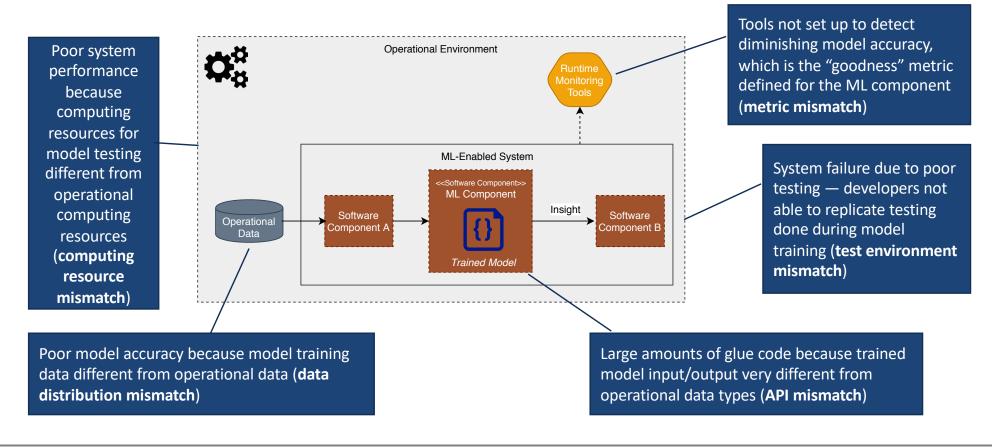
Element

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AAAI FSS 2019 – Mismatch in ML-Enabled Systems © 2019 Carnegie Mellon University Alignment between Elements A and B (not a

complete set)

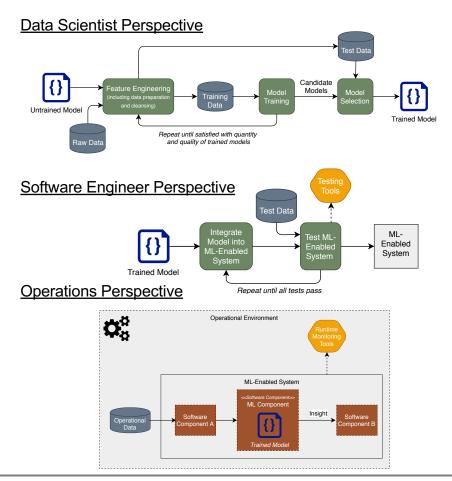
Examples of Mismatch



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Problem: Multiple Perspectives



ML-enabled systems typically involve three different and separate workflows

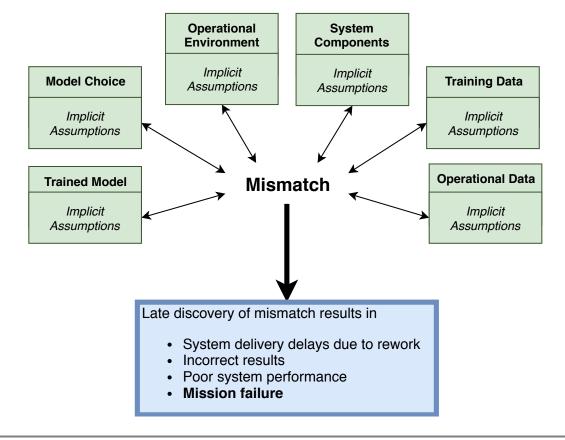
- Model training
- Model integration
- Model operation

... performed by three different sets of stakeholders ...

- Data scientists
- Software engineers
- Operations staff
- ... with three different perspectives

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Problem: Mismatch between Assumptions made by each Perspective



For an operational system to produce appropriate results, all of these elements and assumptions must remained aligned.

As each element evolves independently and at a different rhythm, this increases the risk of unintentional mismatch arising over time.

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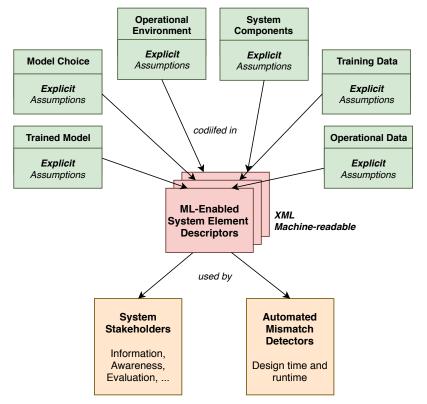
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Solution: Mismatch Detection and Prevention in ML-Enabled Systems

Longer-Term Vision: Codified assumptions and tools exist that allow many types of mismatch to be prevented and/or detected, at design time and runtime

Contribution of this Project: Develop descriptors for elements of ML-enabled systems by

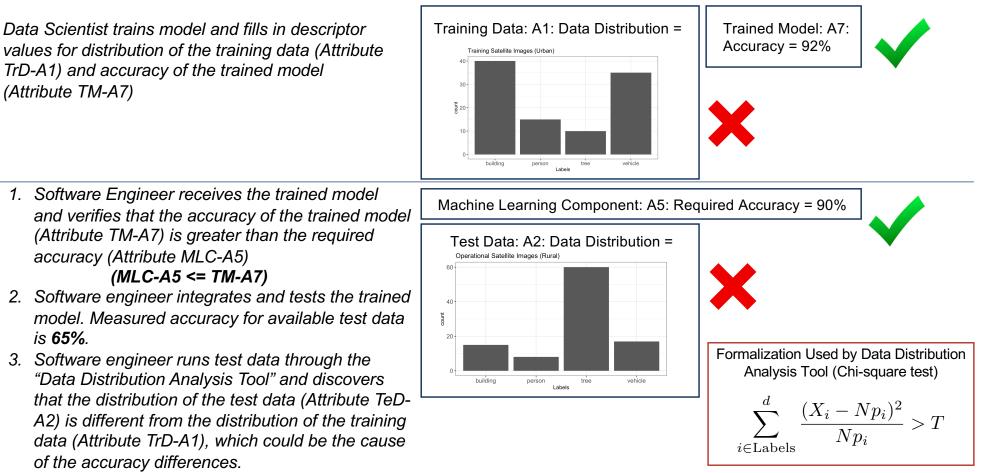
- eliciting examples of mismatch from practitioners
- formalizing definitions of each mismatch in terms of data needed to support detection
- determining sources and validation mechanisms for this data
- identifying potential for using this data for automation of mismatch detection



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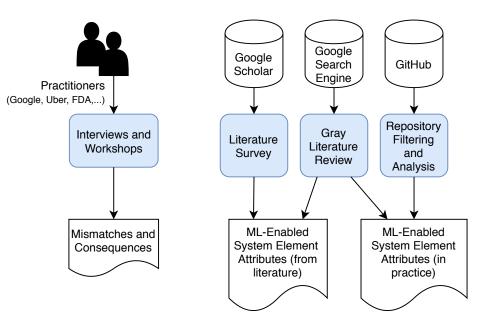
Simple Example Using Descriptors for Mismatch Detection





Technical Approach: Information Gathering

- 1. Identify examples of mismatches and their consequences via interviews, workshops, and other mechanisms
- 2. Identify attributes for describing elements of ML-enabled systems
 - Mining descriptions from GitHub repositories that contain ML models
 - Literature survey
 - Gray literature review



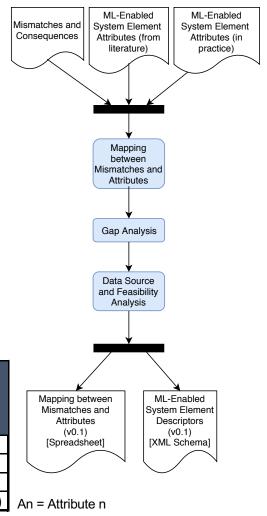
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Technical Approach: Analysis

- 3. Mapping between mismatches and attributes
 - For each mismatch, what is the set of attributes needed for detection, expressed as a predicate over identified attributes
- 4. Gap analysis
 - Which mismatches do not map to any attribute (and vice versa)?
 - · What additional attributes are necessary for detection?
- 5. Data source and feasibility analysis
 - For each attribute, what is the data source, it is feasible to collect, how can it be validated, and is there potential for automation?

			-	-	-	-	-	-	[Descri	ptors	-				-		
	Tra	ined	Tra	ining	Un	trair	ned	5	Syste	em	Ор	eratio	nal	Ope	eratio	nal	Descriptor	Formalization
	Mo	del	D	ata	Ν	Лоde	el	Con	npor	nents	Env	ironm	ent		Data		М	
Mismatch	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13	A14	A15	A16	Am	
Mismatch 1	Х	Х			Х													A1 + A2 > A5
Mismatch 2								Х				Х						A8 = A12
Mismatch N				Х										Х				Chi-Square(A4, A14)

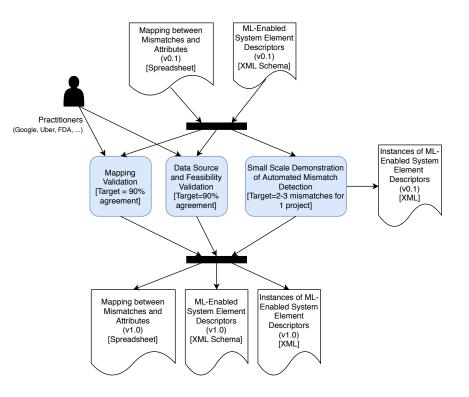


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Technical Approach: Evaluation

- 6. Mapping validation with practitioners
 - Target is 90% agreement on the definition of the mapping between mismatches and sets of attributes
- 7. Data source and feasibility validation with practitioners
 - Target is 90% agreement on data sources and collection feasibility for attributes
- 8. Small Scale Demonstration of Mismatch Detection
 - Target is to identify 2-3 mismatches in a project that can be detected via automation and develop scripts that can detect the mismatch



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Applications of Project Results

- Definitions of mismatch can serve as checklists as ML-enabled systems are developed
- Recommended descriptors provide stakeholders (e.g., program offices) with examples of information to request and/or requirements to impose
- Means identified for validating ML-enabled system element attributes provide ideas for confirming information provided by third-parties
- Identification of attributes for which automated detection is feasible defines new software components that should be part of ML-enabled systems



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14

Points for Discussion

- 1. Is mismatch one of the challenges that you have experienced when deploying MLenabled systems into production settings?
- 2. Do you have examples of mismatch that you can share?

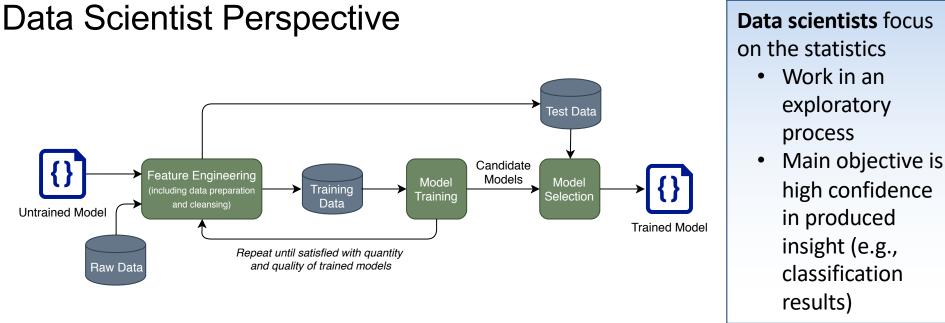


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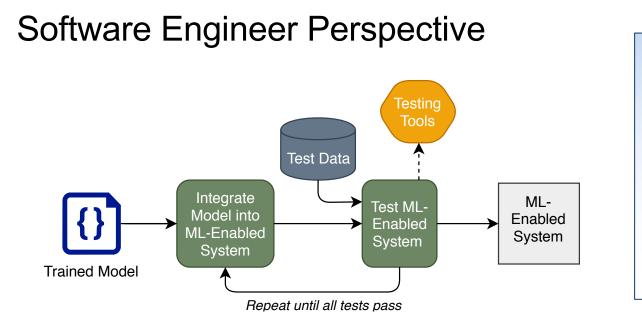


in produced insight (e.g., classification

The goal of the data scientist is to create a *Trained Model* from an *Untrained Model*, plus some collection of *Training Data*.

In the best case, they have some notion of the Operational Data and the requirements and assumptions of the *ML-Enabled System* in which the trained model will be integrated.

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Software engineers focus on getting correct software components integrated to serve mission

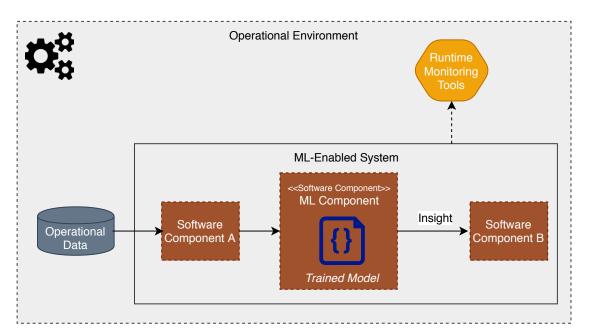
 Focus on typical software concerns: functional correctness + performance, security, maintainability, ...

Software engineers assemble an *ML-Enabled System* from a number of *Software Components*, some of which contain a *Trained Model*.

They generally have some notion of what kind of *Operational Data* they are targeting, but they may not ask the same questions that a data scientist would have looking at the same data.

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Operations Perspective



Operations staff focus on monitoring operational results and failures

- More attuned to crashes and bugs than statistical drift in input as operational conditions change
- Do not have information to determine if an insight produced by the system is correct

Operations staff monitor the performance of the *ML-Enabled System*, but often without deep insight into its structure — *Software Components* (including ML components)

Operations staff also deploy and maintain the Operational Environment and the sources of Operational Data

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Search String	Repos*
"machine learning" + "trained model"	63
"machine learning" + system	1,685
"machine learning" + model	7,994
* Requires additional filtering prior to analysis	

Sample Attributes Extracted from GitHub

Important Notes:

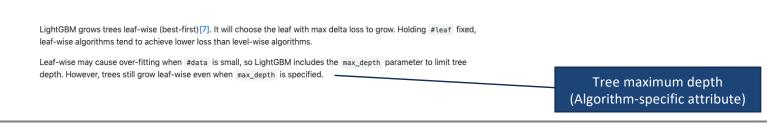
Trained Model: datumbox/datumbox-framework-zoo

• Pre-trained models for Datumbox Machine Learning Framework. <u>http://www.datumbox.com/</u>

The models support only English. The binary files should be loaded using their corresponding Framework version. All the models should be loaded using the InMemory storage engine. Within the folder of each model you will find a stats.txt file which contains the accuracy metrics of the classifier. The metrics were estimated using 10-fold cross validation. All the remaining API methods which are not included here (Readability Assessment, Keyword Extraction, Text Extraction & Document Similarity) are directly powered up by standalone classes of the framework.

Untrained Model: microsoft/LightGBM

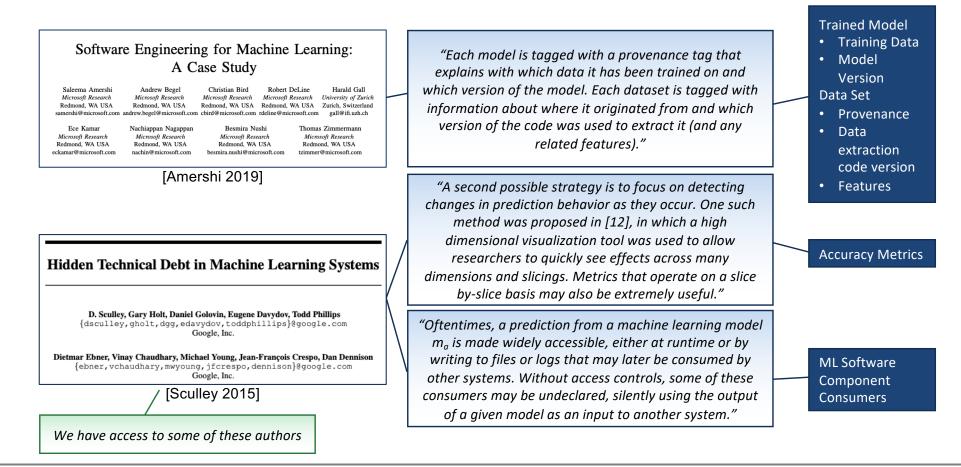
 A fast, distributed, high performance gradient boosting (GBT, GBDT, GBRT, GBM or MART) framework based on decision tree algorithms, used for ranking, classification and other machine learning tasks. It is under the umbrella of the DMTK (http://github.com/microsoft/dmtk) project of Microsoft.



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Sample Attributes Extracted from Literature Survey



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Sample Attributes Extracted from Gray Literature

https://eng.uber.com/tag/michelangelo/

Uber Engineering

Tag: Michelangelo



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Accessible Machine Learning through Data Workflow Management Jaivong Amar - March 18, 2019 Uber engineers offer two common use cases showing how we orthestrate machine learning model training in our data workflow engine.

Manifold: A Model-Agnostic Visual Debugging Tool for Machine Learning at Uber

Uber built Manifold, a model-agnostic visualization tool for ML performance diagnosis and model debugging, to facilitate a more informed and actionable model iteration process.

https://eng.uber.com/machine-learning-data-workflow-management/

- The model training task tells Michelangelo to start training using a predefined project template and the feature dataset generated by the second workflow. Once training completes, Piper attaches a model unique identifier to this training cycle that can be referenced by performance validation, model deploy, and monitoring tasks.
- The performance validation task compares select metrics values such as receiver operating characteristic curve (ROC) and area under curve (AUC) with user-specified thresholds to decide whether a model is accurate enough to deploy.
- 3. If the model is deemed suitable, the model deploy task calls Michelangelo to deploy the model. The model deploy task can also deploy the same model to use different sharding configurations, such as those specific to cities where Uber operates.
- Finally, a monitoring task is typically added to collect serving metrics such as ROC and AUC, comparing them with their training equivalents and continuously monitoring model performances.

Model Unique Identifier

Accuracy Metrics

Search String: trained model "machine learning" description

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Descriptor(s) Example(s)

<?xml version="1.0" encoding="UTF-8"?> <descriptor name="TrainedModel">

<model-details>

<name>Smiling Detection in Images</name>

<developer>Google and the University of Toronto</developer>

<date>2018</date>

<version>v1</version>

<type>Convolutional Neural Net</type>

Sample descriptor created from a text example in [Mitchell 2019]

- Not representative of our research results
- Example in paper is not machine readable (i.e., in XML)

<description>Pre-trained for face recognition then fine-tuned with cross-entropy loss for binary smiling classification</description>

</model-details>

<intended_use>

<primary-intended-uses>

<primary-use>Fun applications, such as creating cartoon smiles on real images</primary-use> <primary-use>Augmentative applications, such as providing details for people who are blind</primary-use> <primary-use>Assisting applications such as automatically finding smiling photos</primary-use>

</primary-intended-uses>

<primary-intended-users>

<user>Younger audiences</user>

</primary-intended-users>

<out-of-scope-uses>

<out-of-scope-use>Emotion detection or determining affect</out-of-scope-use>

<out-of-scope-use>Smiles were annotated based on physical appearance, and not underlying emotions</out-of-scope-use></out-of-scope-uses>

</intended use>

<factors>

<groups>

```
<proup>gender</proup>
<proup>age</proup>
<proup>race</proup>
<proup>race</proup>
<proup>Fitzpatrick skin type</proup>
</proups>
```

</descriptor>

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