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DEVELOPING C-17A CONTROL LAWS IN-FLIGHT

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14. ABSTRACT The C-17A was known for Level 2 handling qualities during aerial-refueling and extensive turbofan time delay during both aerial-refueling and powered-lift configuration landing. This increased the pilot compensation required for aerial-refueling and decreased safety margins for adverse wind condition landings. The Aerial-Refueling Handling Qualities Improvement (ARHQI) was a three-axis control law designed to improve HQ with a vertical-speed feedback loop. Additionally, ARHQI implemented flap and spoiler bias with elevator feedback to create a throttle-controlled drag differential, with zero net pitching moment, to augment relative fore-aft control and reduce time delay. Robust Flight Path Control was a control law designed to reduce time delay by mixing flap, spoiler, and elevator with throttle movement to increase powered-lift control. These two control laws were developed in a risk-reduction program including control law first-flight, safety build-up, in-flight control law tuning, offset landings, tanker contacts, and lessons learned for future flight control developmental testing.					
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Developing C-17A Control Laws In-Flight

3-AXIS AERIAL-REFUELING & ROBUST FLIGHT PATH



C-17A Legacy Control Laws

- *Air-refueling*

- *Thrust axis: computer controlled engines*
- *Pitch rate command*
- *Roll rate command*

- *Approach & landing*

- *Pitch attitude command*
- *Augmented powered lift*



New Control Law Requirement: Air-Refueling

HQR Air-Refueling Pilot Comments During Full Scale Engineering & Development

- “Training would not significantly improve pilot’s ability to compensate”
- “Engine throttle response was marginal. Small throttle changes resulted in large thrust changes...increasing pilot workload”
- “Delay between throttle movement and thrust response contributed to throttle sensitivity deficiency...lag time unavoidable with high bypass turbofan engines”
- “Lack of predictability in pitch...tendency toward moderate, periodic, pitch excursions or bobbles increased workload”
- “Aircraft moved rapidly around envelope...nearly impossible to stabilize without constant correction”



New Control Law Requirement: Landing

HQR Approach Pilot Comments During Full Scale Engineering & Development

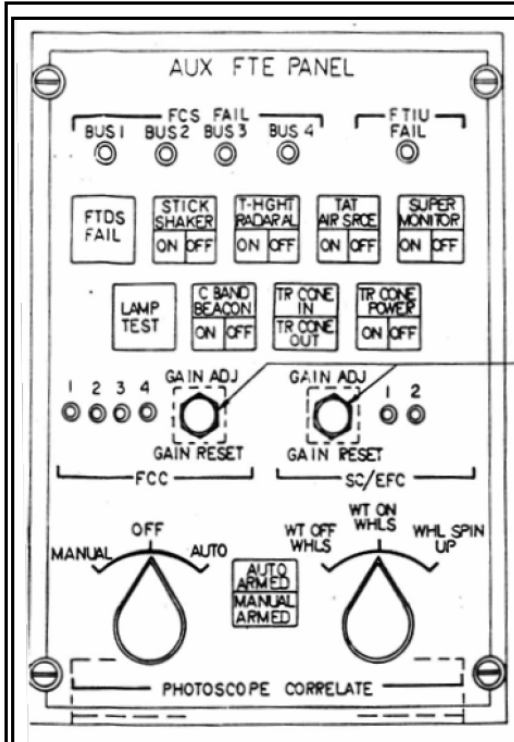
- “Moderate workload in thrust axis”
- “Workload tolerable, compensation moderate, struggle to match [Flight Path Vector] response”
- “Thrust is difficult to control”
- “Gusty winds/thermals make stabilization on final difficult”
- “Crosswind landing: thrust axis hard to control, workload high for task with gusty winds”
- “Throttles are unpredictable”
- “[Flight Path Vector] control sluggish”
- “Lots of throttle, drives up workload – concentrated more on throttle than lateral or pitch”



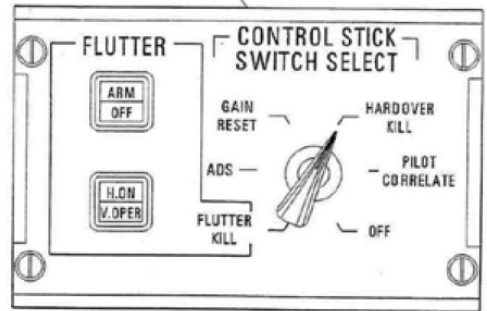
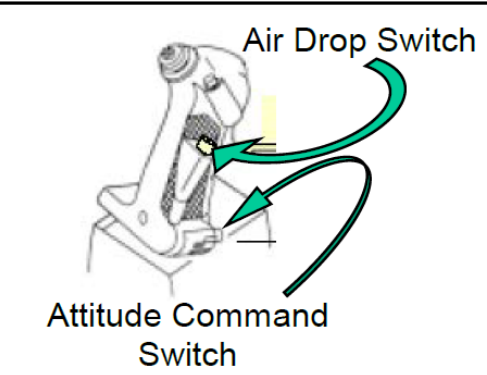
New Design: 3-Axis AR & Robust Flight Path

- *Air-refueling: thrust axis*
 - *Spoiler, flap & elevator augmentation*
- *Air-refueling: pitch rate command*
 - *Short input: attitude command*
 - *Sustained input: rate command*
 - *Vertical speed feedback*
- *Air-refueling: roll rate command*
 - *Precision azimuth tracking*
- *Approach: pitch attitude command & augmented powered lift*
 - *Closed loop system*
 - *Flap augmentation*

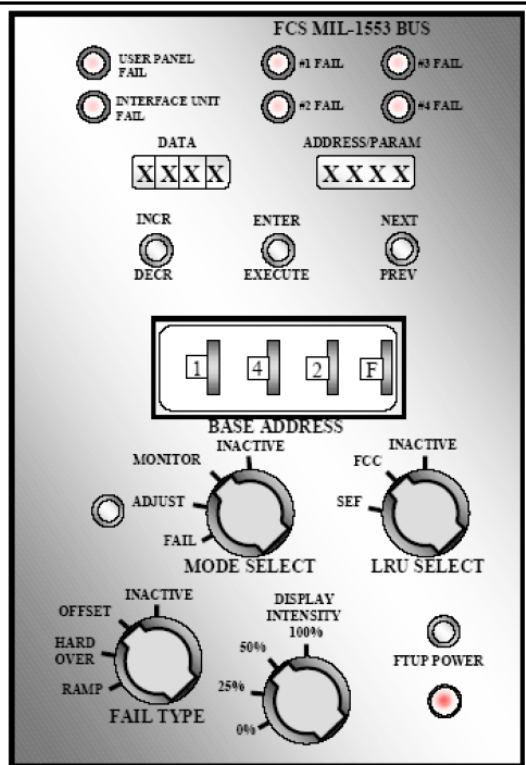




Aux FTE Panel



Center Console Control Switch Select Panel



Flight Test User's Panel

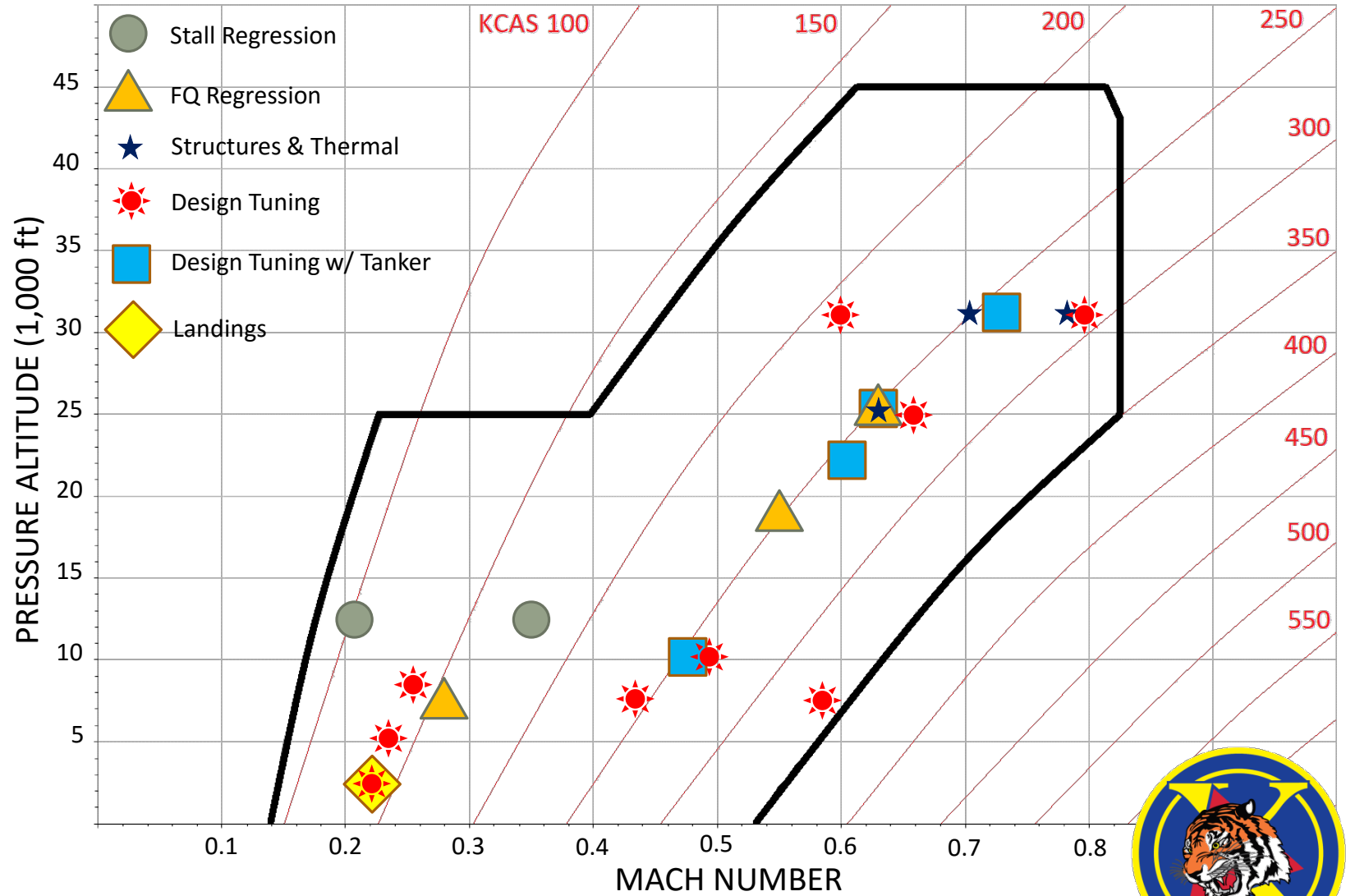
Change-A-Gain System

Test Unique Hardware



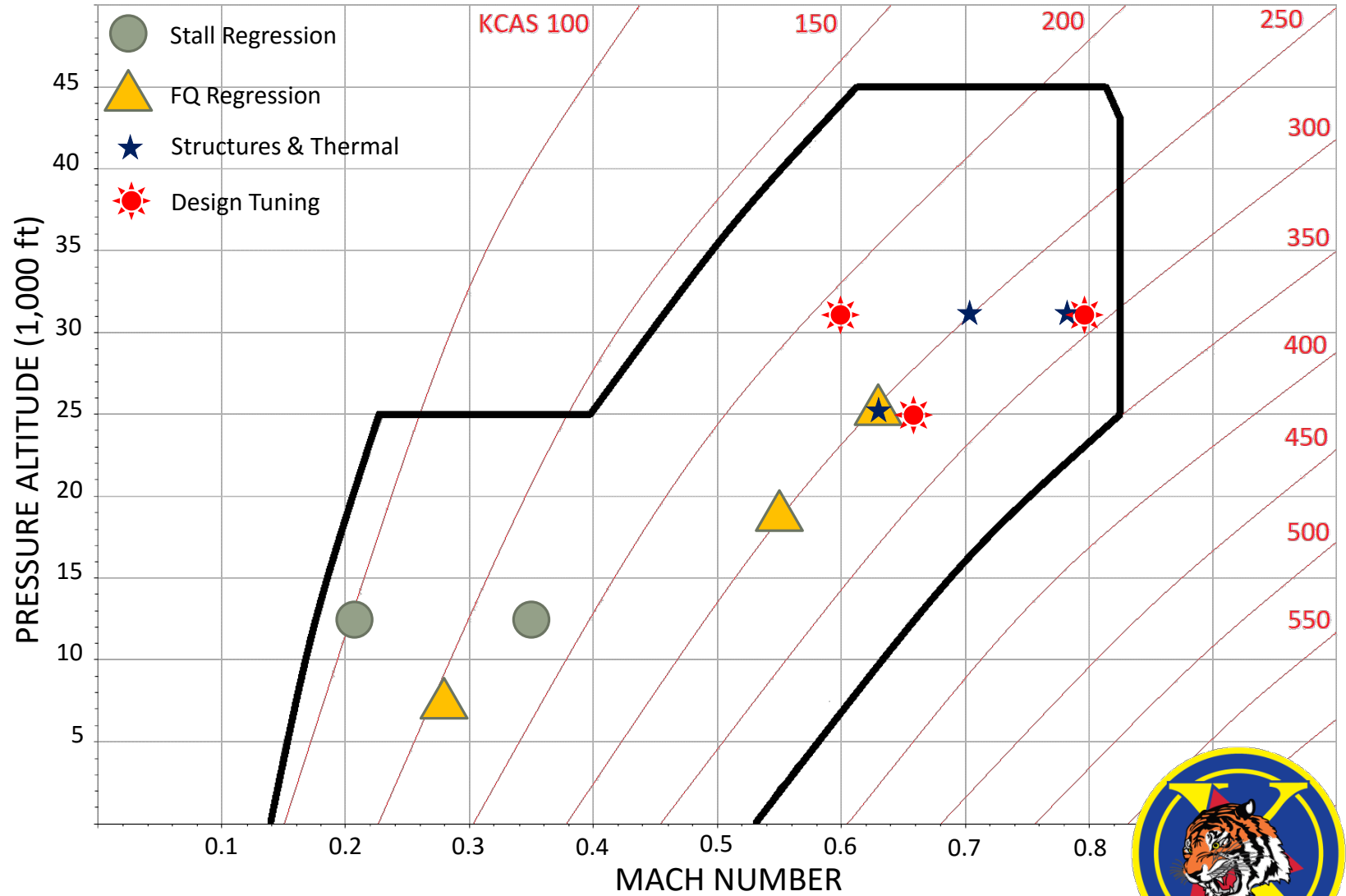
Test Methodology

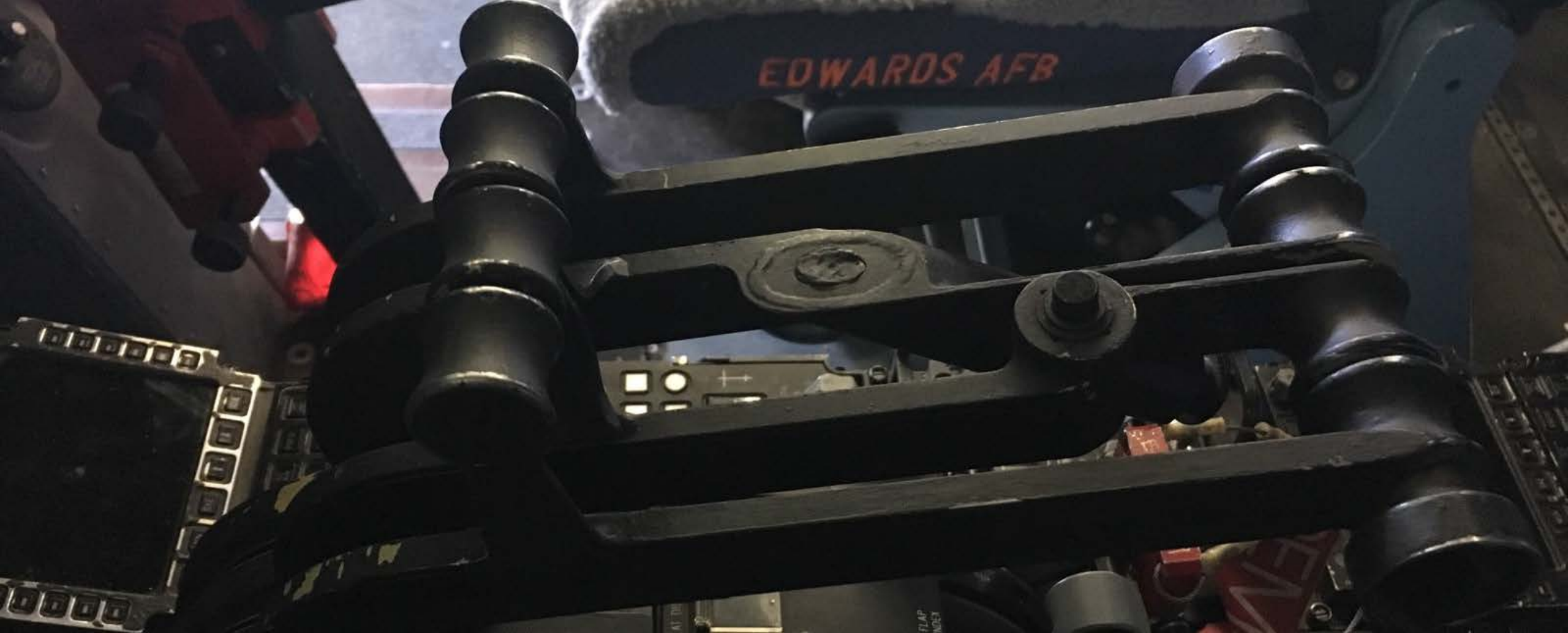
- *Single Ship*
- *Tanker/Receiver Formation*
- *Robust Flight Path Landings*



Test Methodology

- *Single Ship*
 - *Safety Buildup*
 - *FQ Data Collection*
- *Tanker/Receiver Formation*
- *Robust Flight Path Landings*





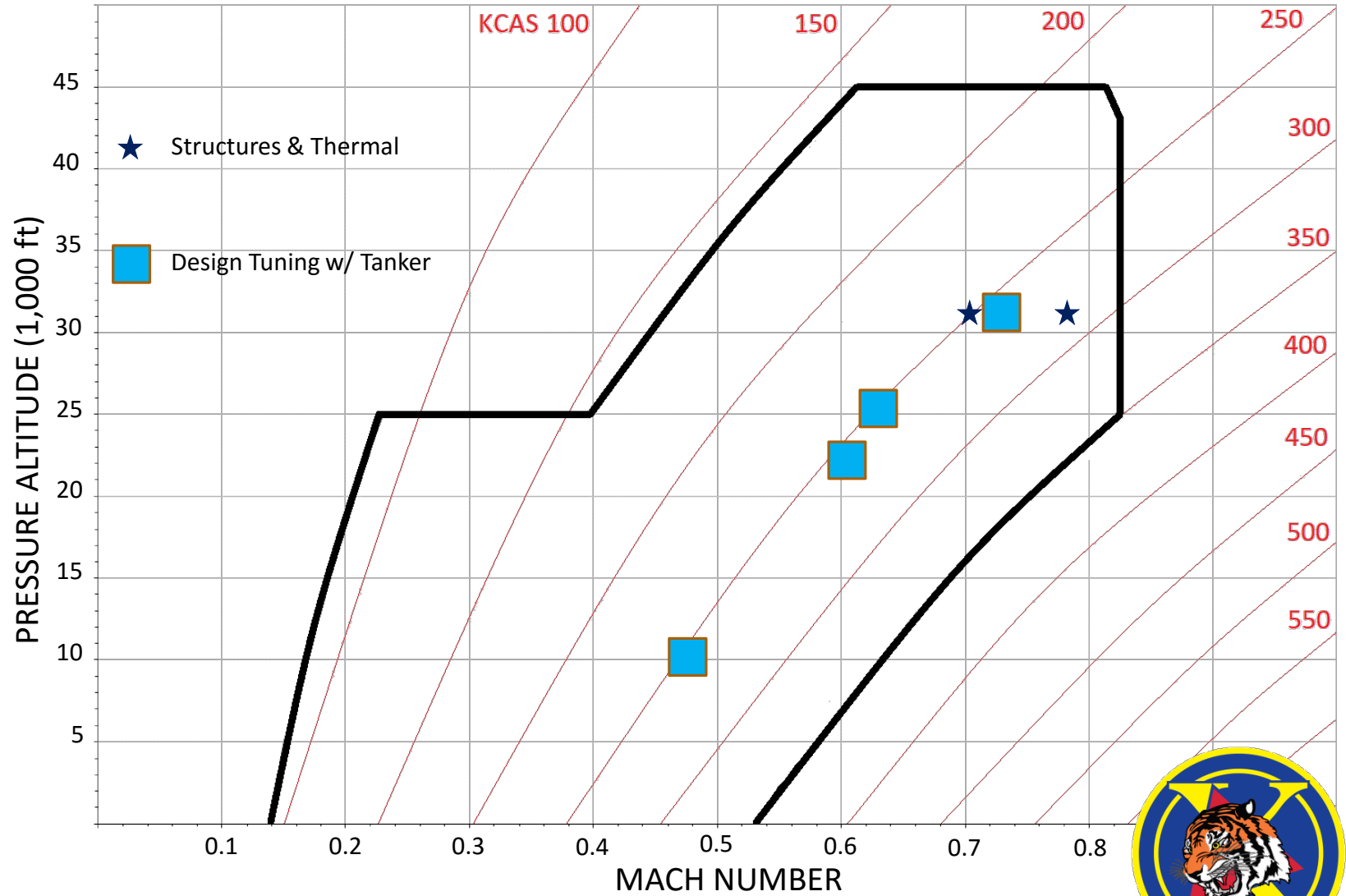
FTT: Throttle Frequency Sweeps

0.1 – 5 Hz ½ INCH AMPLITUDE



Test Methodology

- *Single Ship*
- *Tanker/Receiver Formation*
 - *Safety Buildup*
 - *HQ Evaluation*
- *Landings*





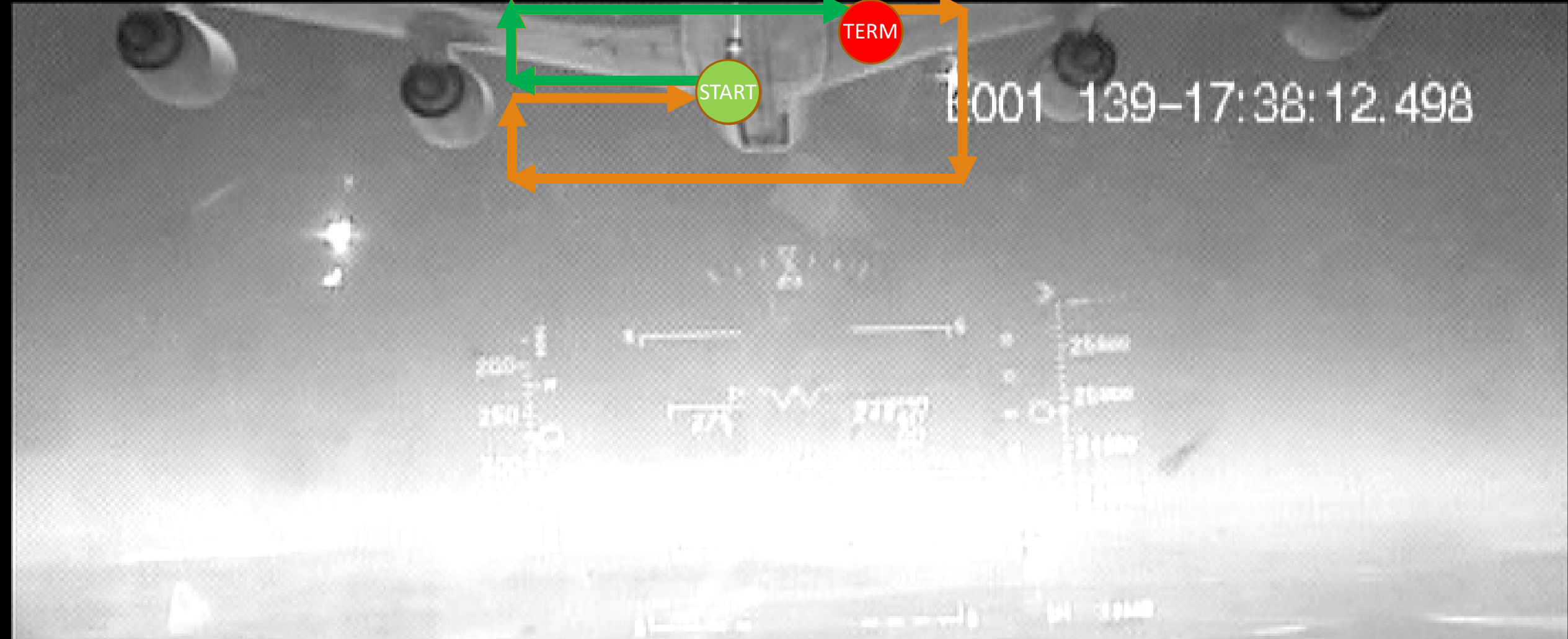
Air-Refueling Control Law Engagement

Initial control law engagement in one nautical mile trail

Qualitative evaluation with target

Rejoin in stages





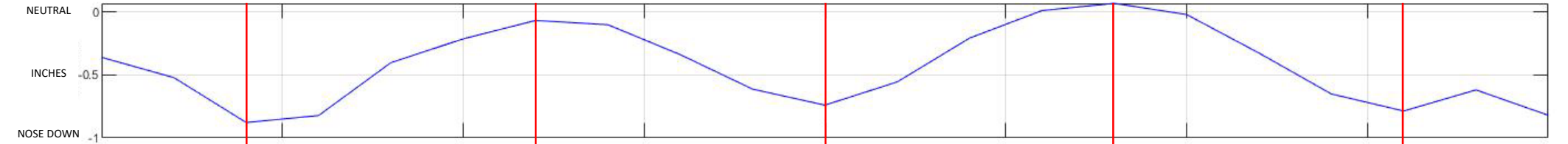
FTT: Boom Tracking

Safety buildup at 50 feet separation (Pre-Contact)

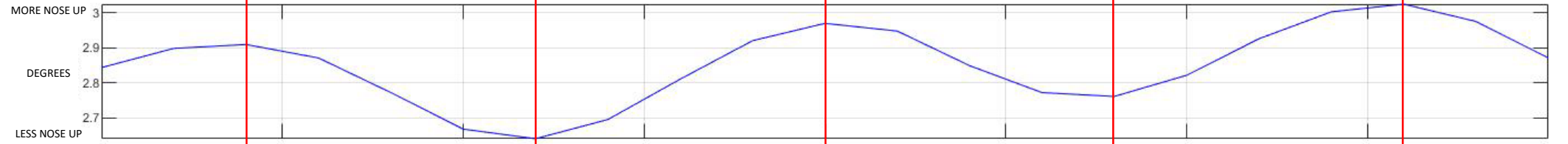
Performed at two rates



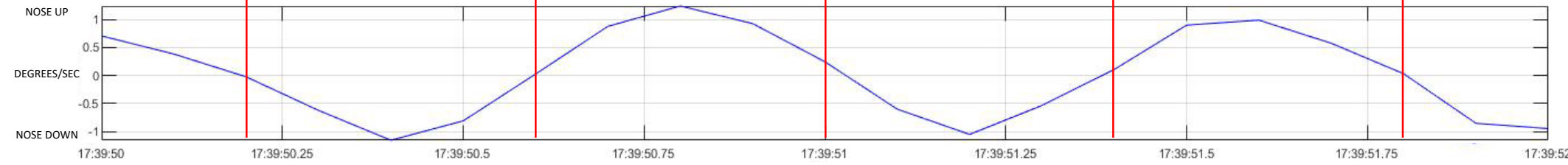
Stick Position



Pitch Angle, θ



Pitch Rate, $\dot{\theta}$



Boom Tracking Strip Charts

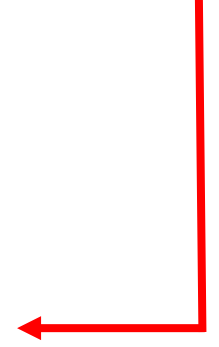
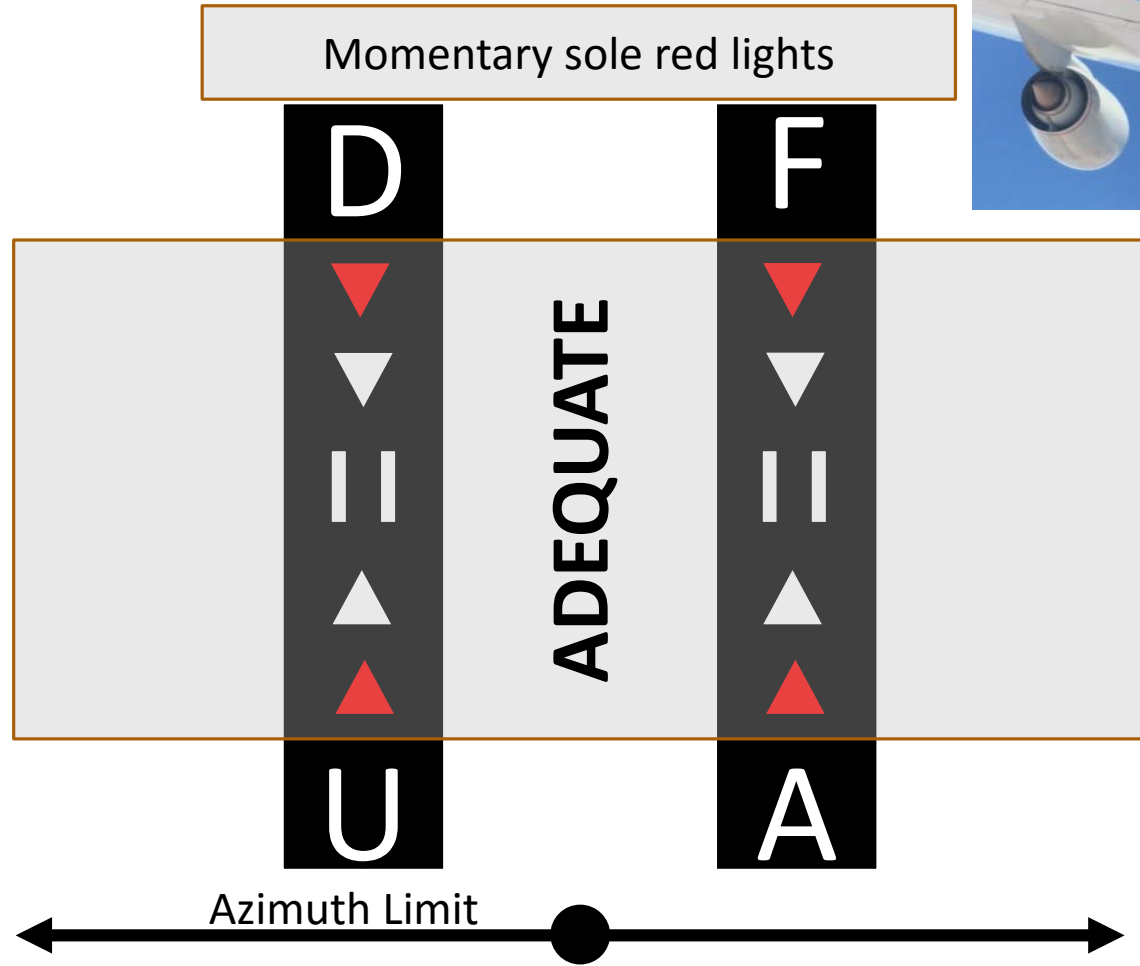
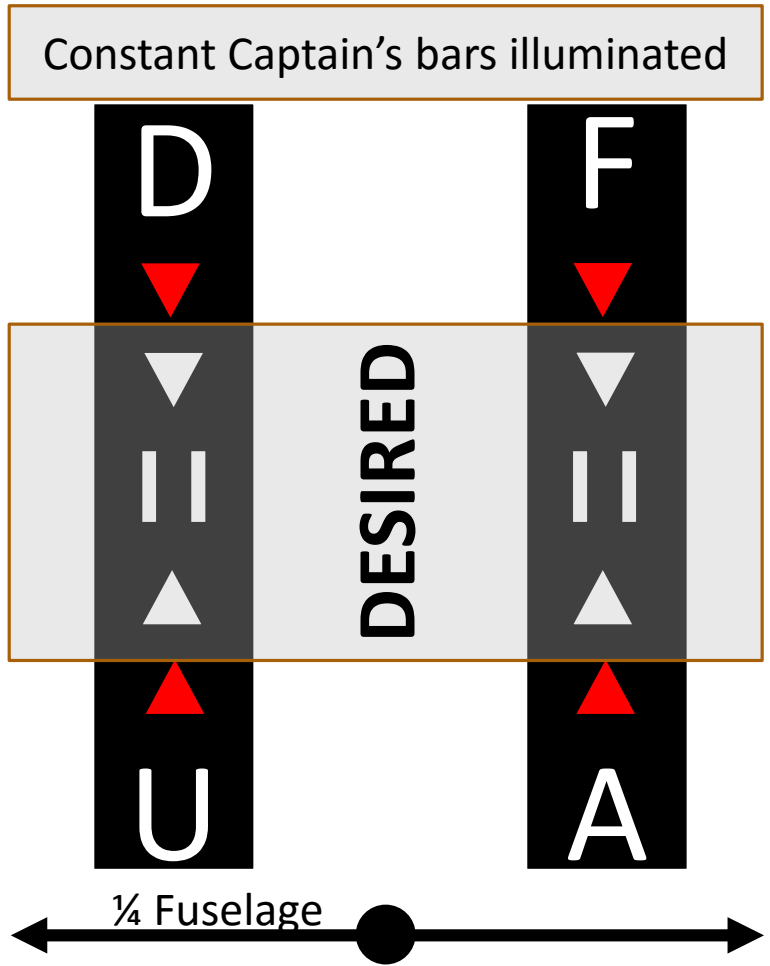
1.25 Hz oscillation



The case for a lesson learned...

- Six month break for data review & design update
- Test methodology review & re-prioritization
- ***Design the right flight test: identify and pursue the knowledge test point***





FTT: Sustained Contact HQ Evaluation

Task Criteria
 Two minutes straight & level
 180 degree turn



Three Axis Control Law



Legacy Control Law



FTT: Sustained Contact HQ Evaluation

Control Laws Side-by-side



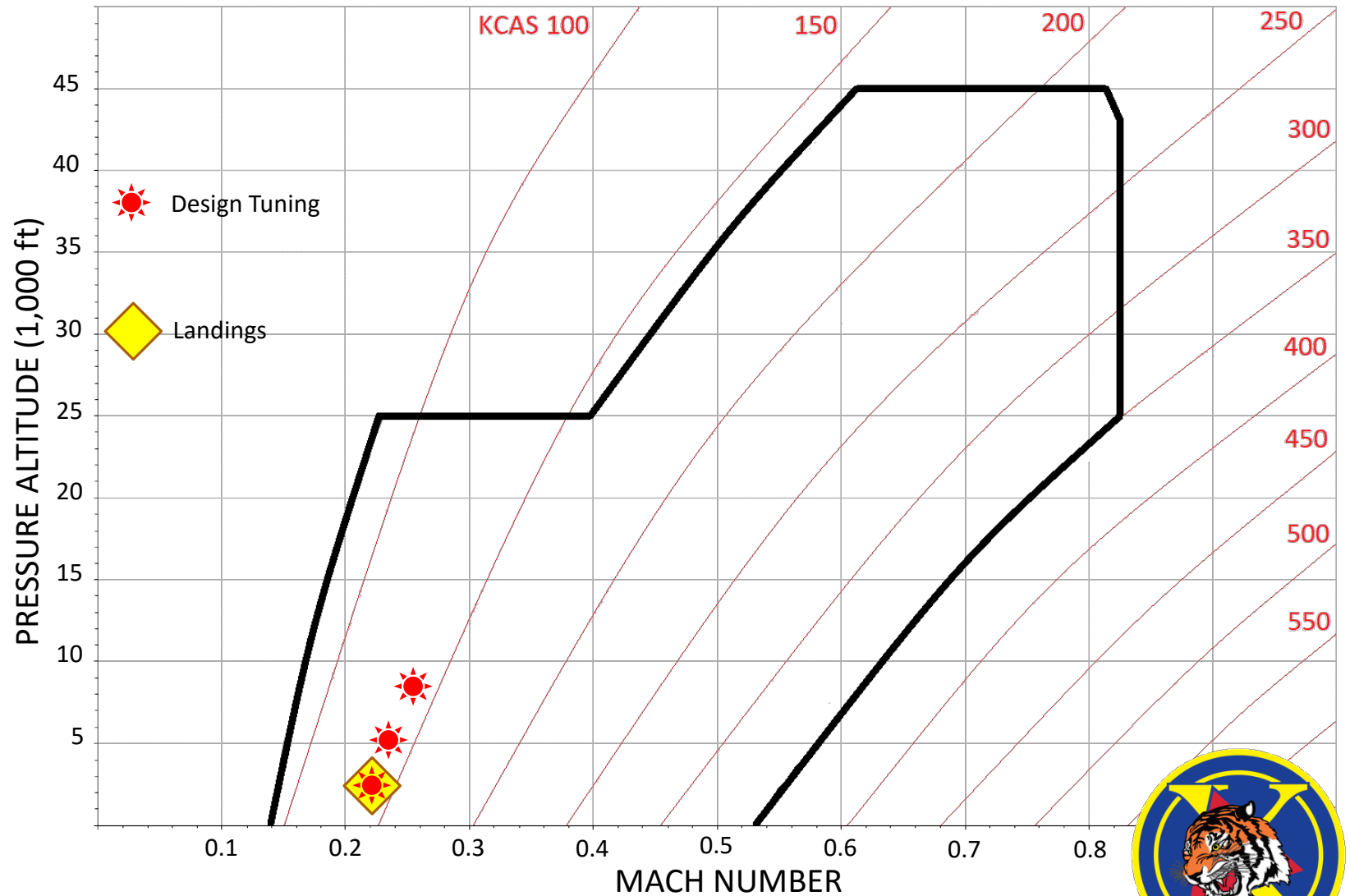
The case for a lesson learned...

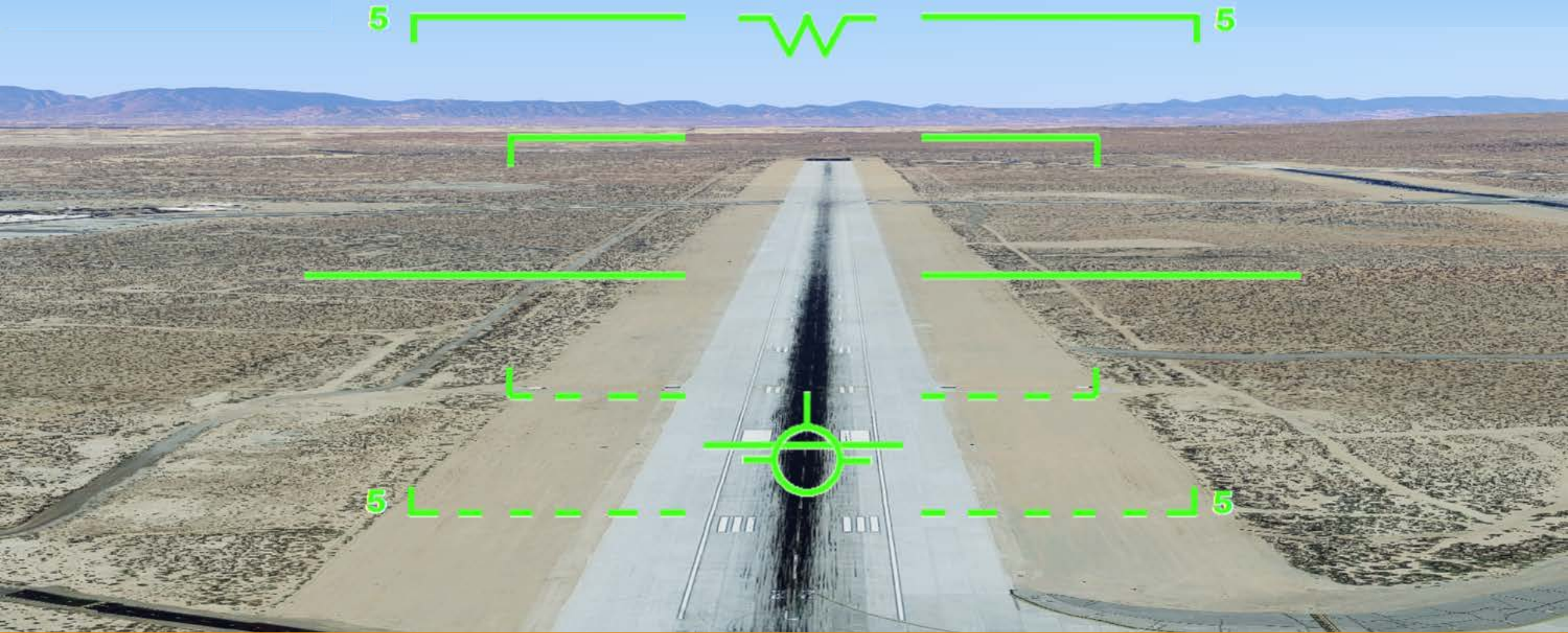
- Test pilots with 1,000s of hours in one platform have inherent bias
- “I used to fly AR just fine, I don’t know how to compensate now, give me back the legacy control law so I know what to do”
- ***Defeat mature aircraft bias: calibrate the test pilot on the ground and in the air***



Test Methodology & Buildup

- *Single Ship*
- *Tanker/Receiver Formation*
- *Robust Flight Path Landings*
 - *Safety Buildup*
 - *Flight Path Performance*
 - *HQ Evaluation*





FTT: Vertical Offset Recovery

Stress control law
Increase pilot gain



Robust Flight Path



Legacy Control Law



FTT: Vertical Offset Recovery

Side by side video





Rating	FPV at T/D (°)	A/S at T/D (kt)	T/D from Aim (ft)	Centerline Dev (ft)
Desired	-0.5 to -1.5	+/- 5	+580 / -20	+/- 15
Adequate	0.0 to -2.0	+10 / -5	+880 / -320	+/- 25

FTT: Normal Landing HQ Evaluation





Rating	FPV at T/D (°)	A/S at T/D (kt)	T/D from Aim (ft)	Centerline Dev (ft)
Desired	-1.0 to -2.0	+/- 5	+/- 150	+/- 15
Adequate	0.0 to -2.0	+10 / -5	+/- 250	+/- 25

FTT: Assault Landing HQ Evaluation





FTT: Assault Landing HQ Evaluation

Side by side control law



The case for a lesson learned...

- Test pilots with 1,000s of hours in one platform have inherent bias
- “I used to land just fine, I don’t know how to compensate now, give me back the legacy control law so I know what to do”
- ***Defeat mature aircraft bias: calibrate the test pilot on the ground and in the air***



Lessons Learned Wrap-up

- ***Design the right flight test: identify and pursue the knowledge test point***
- ***Defeat mature aircraft bias: calibrate the test pilot on the ground and in the air***



A special thanks to:

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For helping us gather data and
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