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Optimal Runge-Kutta Schemes for High-order Spatial and Temporal Discretizations



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> 2015 AIAA SciTech June 23, 2015

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Introduction

Governing Equations

- Spatial Discretizations
- Temporal Discretizations
- Von Neumann Analysis (VNA)

Computational Results

- One-dimensional Wave
- Three-dimensional Vortex

Conclusions and Future Work



Introduction



- High-order in space is now commonplace
- High-order in time... not so much...
- Is this sufficient? Is high-order in time needed?
- <u>Limiting Fact</u>: There are no A-stable backward-difference formula (BDF) methods with > 2nd -order accuracy
- Thus, multistage methods, like Runge-Kutta (RK) methods, must be used for 3rd- and higher-order
- Explicit RK methods are not amenable to stiff problems

Objective: To find optimal diagonally-implicit Runge-Kutta time integrators for use with high-order spatial discretizations







Dual Time Stepping:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \frac{\partial \mathbf{F}_i}{\partial x_i} = \frac{\partial \mathbf{V}_i}{\partial x_i} + \mathbf{H} \qquad \mathbf{Q} = \begin{bmatrix} \rho & \rho u_i & \rho e_0 \end{bmatrix}^T$$

 $\mathbf{F}_i = \begin{bmatrix} \rho u_i & \rho u_i u_j + p \delta_{ij} & u_i \rho h_0 \end{bmatrix}^T \text{ where } h_0 = e_0 + \frac{p}{\rho}$

• Quasi-linear Form:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \underline{\mathbf{A}} \frac{\partial \mathbf{Q}}{\partial x_i} = \frac{\partial \mathbf{V}_i}{\partial x_i} + \mathbf{H} \qquad \underline{\mathbf{A}} = \frac{\partial \mathbf{F}_i}{\partial \mathbf{Q}} = \underline{\mathbf{M}} \mathbf{\Lambda} \underline{\mathbf{M}}^{-1}$$
$$\underline{\mathbf{\Lambda}} = diag \left\{ u_i + c, u_i, u_i - c \right\}$$

Residual Form:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \mathbf{R}_{s} \left(\mathbf{Q} \right) = 0 \quad where \quad \mathbf{R}_{s} = \frac{\partial \mathbf{F}_{i}}{\partial x_{i}} - \frac{\partial \mathbf{V}_{i}}{\partial x_{i}} - \mathbf{H}$$



- Central Differences with added artificial dissipation
- Central differences:

Inces:
$$\frac{\partial \Upsilon_{j}}{\partial x_{i}}\Big|_{II} = \frac{\Upsilon_{j+1} - \Upsilon_{j-1}}{2\Delta x_{i}}$$
$$\frac{\partial \Upsilon_{j}}{\partial x_{i}}\Big|_{IV} = \frac{-\Upsilon_{j+2} + 8\Upsilon_{j+1} - 8\Upsilon_{j-1} + \Upsilon_{j-2}}{12\Delta x_{i}}$$
$$\frac{\partial \Upsilon_{j}}{\partial x_{i}}\Big|_{VI} = \frac{\Upsilon_{j+3} - 9\Upsilon_{j+2} + 45\Upsilon_{j+1} - 45\Upsilon_{j-1} + 9\Upsilon_{j-2} - \Upsilon_{j-3}}{60\Delta x_{i}}$$

where Υ could be \mathbf{F}_i or \mathbf{Q} depending on the form of the equations

• Scalar artificial dissipation:

$$\mathbf{R}_{s} = \frac{\partial \mathbf{F}_{i}}{\partial x_{i}} - \varepsilon_{\eta} \parallel \lambda \parallel \frac{\partial^{\eta} \mathbf{Q}}{\partial x_{i}^{\eta}} - \frac{\partial \mathbf{V}_{i}}{\partial x_{i}} - \mathbf{H}$$

where η is even and one more than the order of accuracy

$$\|\lambda\| = |u_i| + c$$
 $\varepsilon_{II} = \frac{\Delta x_i}{2}, \quad \varepsilon_{IV} = -\frac{\Delta x_i^3}{12}, \quad \varepsilon_{VI} = \frac{\Delta x_i^5}{60}.$

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Runge-Kutta Methods:

	c_1	a_{11}	a_{12}	a_{13}	•••	$a_{1(s-1)}$	a_{1s}	
	c_2	a_{21}	a_{22}	a_{23}	•••	$a_{2(s-1)}$	a_{2s}	
	c_3	a_{31}	a_{32}	a_{33}	•••	$a_{3(s-1)}$	a_{3s}	
	•	• •	• •	•	•••	• •	:	
	c_{s-1}	$a_{(s-1)1}$	$a_{(s-1)2}$	$a_{(s-1)3}$	•••	$a_{(s-1)(s-1)}$	$a_{(s-1)s}$	
	c_s	a_{s1}	a_{s2}	$a_s 3$	• • •	$a_{s(s-1)}$	a_{ss}	
		b_1	b_2	b_3	•••	b_{s-1}	b_s	
		\hat{b}_1	\hat{b}_2	\hat{b}_3	•••	\hat{b}_{s-1}	\hat{b}_{s}	
$t^k = t^n + c_k \Delta t$ $\mathbf{Q}^k = \mathbf{Q}^n - \Delta t \sum_{j=1}^s a_{kj} \mathbf{R}_s^j(\mathbf{Q}^j)$ $k = 1, 2, \dots, s$								
$\mathbf{Q}^{n+1} = \mathbf{Q}^n - \Delta t \sum_{j=1}^s b_j \mathbf{R}_s^j(\mathbf{Q}^j) \qquad \hat{\mathbf{Q}}^{n+1} = \mathbf{Q}^n - \Delta t \sum_{j=1}^s \hat{b}_j \mathbf{R}_s^j(\mathbf{Q}^j)$								
$\epsilon^{n+1} = \mathbf{Q}^{n+1} - \hat{\mathbf{Q}}^{n+1}$								





- <u>Explicit first stage Singly-Diagonally</u>
 <u>Implicit Runge-Kutta</u>
 - Stiffly accurate
 - Second-order stage accuracy
 - FSAL <u>First is the Same As Last</u>



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ESDIRK3 and 4



	0		0	0	0	1	(0
$\frac{17677322059}{20278366411}$	$\frac{03}{18}$	$\frac{17677322059}{405567328222}$	$\frac{17677}{36}$ $\frac{17677}{40556}$	$\frac{732205903}{573282236}$	0)	(0
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		Implie	cit, Third	-order ES	DIRK3			
0		0	0	0	0	0	0	
$\frac{1}{2}$		$\frac{1}{4}$	$\frac{1}{4}$	0	0	0	0	
$\frac{83}{250}$		$\frac{8611}{62500}$	$-rac{1743}{31250}$	$\frac{1}{4}$	0	0	0	
$\frac{31}{50}$		$rac{5012029}{34652500}$	$-rac{654441}{2922500}$	$\frac{174375}{388108}$	$\frac{1}{4}$	0	0	
$\frac{17}{20}$	$\frac{1}{15}$	$\frac{5267082809}{5376265600}$	$-rac{71443401}{120774400}$	$\frac{730878875}{902184768}$	$\frac{2285395}{8070912}$	$\frac{1}{4}$	0	
1		$\frac{82889}{524892}$	0	$\frac{15625}{83664}$	$\frac{69875}{102672}$ -	$-\frac{2260}{8211}$	$\frac{1}{4}$	
		$\frac{82889}{524892}$	0	$\frac{15625}{83664}$	$\frac{69875}{102672}$	$-\frac{2260}{8211}$	$\frac{1}{4}$	
		T 14	• • • •					

Implicit, Fourth-order ESDIRK4

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ESDIRK5









- Often used to study stability of schemes
- Von Neumann analysis is used to compare schemes for accuracy
 - Dissipation error
 - Dispersion error
- Assumes linear, periodic problems
- VNA theory and more results are in the associated paper





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• Unperturbed Mach number of 0.5

$$\rho_{\infty} = 8.7077 \times 10^{-1} \frac{kg}{m^3}$$

$$\rho u_{\infty} = 1.7458 \times 10^2 \frac{kg}{m^2 \cdot s}$$

$$T_{\infty} = 400K$$

$$R_{\infty} = 2.871 \times 10^2 \frac{J}{kg \cdot K}$$

$$\gamma = 1.4$$

• Perturbation wave - 20 points per wave resolution

$$Q_o = Q_\infty + M\delta \hat{Q}_{u,u\pm c}$$
$$\delta \hat{Q}_{u,u\pm c} = \hat{\delta} \cdot \cos(kx)$$
where $\hat{\delta} = 0.01$

More results in the paper







	Dissipati	on Error	Dispersion Error		
Scheme	VNA	Simulation	VNA	Simulation	
Crank-N-colson	3.05×10^{-3}	1.00×10^{-2}	8.11×10^{-2}	8.11×10^{-2}	
ESDIRK3	5.02×10^{-2}	5.02×10^{-2}	1.51×10^{-3}	1.53×10^{-3}	
ESDIRK4	3.13×10^{-3}	3.13×10^{-3}	1.50×10^{-4}	1.58×10^{-4}	
ESDIRK5	3.14×10^{-3}	3.14×10^{-3}	6.78×10^{-5}	6.90×10^{-5}	



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	Dissipati	on Error	Dispersion Error	
Scheme	VNA Simulation		VNA	Simulation
Crank-Nicolson	9.02×10^{-5}	2.44×10^{-3}	3.61×10^{-1}	3.61×10^{-1}
ESDIRK3	4.99×10^{-1}	4.90×10^{-1}	1.92×10^{-1}	1.92×10^{-1}
ESDIRK4	7.22×10^{-3}	7.25×10^{-3}	4.90×10^{-2}	4.90×10^{-2}
ESDIRK5	5.10×10^{-2}	5.46×10^{-2}	1.38×10^{-2}	1.39×10^{-2}



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	Dissipati	on Error	Dispersion Error		
Scheme	VNA	Simulation	VNA	Simulation	
Crank-Nicolson	2.63×10^{-1}	2.65×10^{-1}	8.11×10^{0}	8.10×10^{0}	
ESDIRK3	9.94×10^{-1}	9.94×10^{-1}	1.51×10^{-1}	1.00×10^{-1}	
ESDIRK4	2.69×10^{-1}	1.95×10^{-1}	1.50×10^{-2}	3.00×10^{-2}	
ESDIRK5	2.70×10^{-1}	2.01×10^{-1}	6.78×10^{-3}	2.50×10^{-2}	



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• Free-stream Mach number of 0.5

 $\rho_{\infty} = 1.0 \frac{kg}{m^3}, \quad \rho u_{\infty} = 200.0 \frac{kg}{m^2 \cdot s}, \quad \rho v_{\infty} = 0.0 \frac{kg}{m^2 \cdot s}, \quad \rho w_{\infty} = 0.0 \frac{kg}{m^2 \cdot s}, \quad \rho e_{0,\infty} = 305714.3 \frac{kg}{m \cdot s^2}$ $R_{\infty} = 287.11 \frac{J}{kg \cdot K} \text{ and } \gamma = 1.4$

Perturbation - 11 points across the vortex

$$\delta u = -\sqrt{R_{\infty}T_{\infty}} \frac{\alpha}{2\pi} (y - y_0) e^{\phi(1 - r^2)} \qquad \alpha = 4 \text{ and } \phi = 1$$

$$\delta v = \sqrt{R_{\infty}T_{\infty}} \frac{\alpha}{2\pi} (x - x_0) e^{\phi(1 - r^2)} \qquad \text{Vortex center: } (x_0, y_0)$$

$$\delta T = T_{\infty} \frac{\alpha^2 (\gamma - 1)}{16\phi\gamma\pi^2} e^{2\phi(1 - r^2)} \qquad r = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

More results in the paper





3-D, *CFL* = 1.0, 40 Lengths, 11 Points Across the Vortex





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3-D, *CFL* = 1.0 Different Resolutions







3-D, *CFL* = *8.0*, 40 Lengths, 11 Points Across the Vortex





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Sneak Peak: Filtering





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Conclusions



2nd- and 3rd-order time integrators for 5th-order spatial schemes are inadequate

- The same order of spatial and temporal discretizations is preferable
- However, ESDIRK5 is not much better than ESDIRK4
 - 7 implicit stages vs. 5 implicit stages

• Higher-order time integrators:

- Do not show significant improvement on coarse grids at CFL of one
- Are better at high CFL number
- Are better on highly refined grids
- Spatial error usually dominates for typical CFL numbers and grid resolutions
 - Central difference plus artificial dissipation schemes are inadequate





- Implement more accurate spatial schemes of the same orders of accuracy
 - Compact-difference schemes
 - Filtering schemes
- Derive better ESDIRK schemes tailored to the desired dissipation and dispersion properties
- Add preconditioning to take maximum advantage of the ESDIRK time integrators for stiff problems
 - Improved convergence efficiency
 - Improved solution accuracy









Extra Slides



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3-D, *CFL* = *8.0* Different Resolutions





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