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68th Annual Gaseous Electronics Conference

LASER DIAGNOSTICS FOR SPACECRAFT PROPULSION

GEC15-2015-000599 Tuesday, October 13, 2015

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- Motivation
- Monopropellant thrusters
 - Diode Laser Absorption Spectroscopy (DLAS)
 - Wavelength Modulation Spectroscopy (WMS)
- Arcjets
- Hall thrusters/lon engines
 - Laser Induced Fluorescence (LIF)
 - Time resolved LIF Methods
- Recent results from Time-Synchronized LIF
 - Time-Sync Method
 - BHT-600 Results
- Summary
- References





- Many satellite propulsion technologies were developed in the 1960s
 - Didn't have the diagnostics to fully understand how/why they worked
 - Aging workforce causing us to lose knowledge of how the systems were made, recipes for materials, trade secrets, etc.
 - Now having to go back and characterize old systems to lay groundwork for advancements in technologies
- Tunable diode lasers developed in the 1960s
 - Diagnostic techniques have been developed alongside propulsion technologies
 - Simulation of space environment, rarefied gases facility effects become important
 - Laser diagnostics non intrusive, can survive harsh environments of combustion, plasmas
- New methods of laser diagnostics
 - Provide insight into dynamics of thruster operation
 - Are linked to thruster performance metrics
 - Are critical to validating numerical simulations



Monopropellant Thrusters





Aerojet MR-106 Propellant: Hydrazine Thrust: 22 N Isp: 235 sec

Operation

- Monopropellant flows over catalyst bed to initiate exothermic decomposition
- Propellant is expanded and accelerated out of a nozzle
- Developed in 60s, having to now go back and figure out how they work

Diagnostics

- Destructive testing the current standard
 - Intrusive, post-test
 - Cut open thruster to examine catalyst
- Diode Laser Absorption Spectroscopy
 - Non-intrusive, in-situ measurements
 - Temperature, species concentrations
 - Wavelength Modulation Spectroscopy (WMS)
- Other methods such as FTIR, PLIF, emission spectroscopy on combustion/propellants, not on thrusters in operation

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Beer-Lambert Law

 $I_{v}(L) = I_{v}^{\theta} exp(-k_{v}L)$

- $I_v(L)$ Transmitted spectral intensity after traveling through a distance, L, through the medium [W/cm²s⁻¹]
- Initial spectral intensity of the laser per unit frequency [W/cm²s⁻¹]

 k_v Spectral absorption coefficient [cm⁻¹]



Hydrazine Thruster

Ramp input to laser

- Modulates intensity and wavelength (modulation frequency up to 1 MHz)
- Baseline fit + Beer-Lambert Law gives absorbance of spectral feature

Species Identification

- $k_{\nu} \text{ can be related to number densities, partial pressures to detect concentrations of combustion products such as NH_3$
- Presence of different species indicates catalyst health

Temperature

- FWHM of transition indicates temperature (if no pressure broadening)
- Ratio of two nearby transition intensities indicates temperature (pressure independent)
- Lowering temperature indicates degradation of catalyst



Wavelength Modulation Spectroscopy (WMS)



<u> 1f-normalized WMS-2f</u>

- Diode laser modulated in wavelength and intensity via:
 - Current injection at frequency = 1f
 - Ramp voltage
- Detector output sent through two lock-in amplifiers
 - Reference frequencies = 1f and 2f
 - Comparison of 2f signal ("WMS-2f") to model of absorption feature indicates temperature and gas concentration

Improved sensitivity and noise-rejection over direct absorption (2 to 100x better SNR)



2f signal is related to the original absorption feature by a mathematical transform

$$I_{\nu}(L) = I_{\nu}^{0}H_{n}(\overline{\nu})L$$

$$(\sum 2^{1-n} d^{n}\alpha(\nu))$$

$$H_{n}(\overline{\nu}) = \frac{2^{1-n}}{n!} \alpha_{n} \frac{d^{n} \alpha(\nu)}{d\nu^{n}} \bigg|_{\nu=1}$$

- H_n^v = nth Fourier component of modulated absorption coefficient (n=2 for WMS-2f)
- $\alpha(v)$ = absorption coefficient (modeled by Gaussian, Lorentzian, Voigt)
- v = mean modulation frequency
- Normalization of 2f signal by 1f signal eliminates effects of laser intensity drift, scattering, etc.

$$\frac{2f}{lf} = \frac{H_2}{i_0} = \frac{S(T) \cdot P \cdot x_i \cdot L}{i_0 \cdot \pi} \int_{-\pi}^{\pi} \phi \Big(\overline{v}_{peak} + a \cos \theta \Big) \cos 2\theta d\theta$$

- S(T) = Linestrength at temperature = T
- x_i = species concentration
- i₀ = incident laser intensity
- φ = linseshape function (Gaussian, Lorentzian, Voigt)
- a = amplitude of frequency modulation







• Electrothermal thruster

- Heats a gaseous propellant (hydrazine, NH₃, H₂)via electrical arc
- Propellant is expanded and accelerated out of a nozzle similar to chemical thrusters

Diagnostics

- Laser Induced Fluorescence
 - Velocity, temperature measurements
 - Development of LIF techniques
 - Hydrogen plasma
- Raman spectroscopy





Propellant: Hydrazine

lsp: 585 sec

Thrust: 250 mN

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Ion Engines & Hall Thrusters





Operation

Ion engines and Hall thrusters are electrostatic propulsion devices

Ion Engines

- Propellant is ionized via electron bombardment and then accelerated by high voltage grids
- Thrust, Isp, Propellant: Xenon

Hall thrusters

- Hall thrusters are gridless electrostatic thrusters
- Propellant ionized by electrons trapped in magnetic field
- lons accelerated by an electric field between anode and electron cloud
- Thrust, Isp, Propellant: Xenon, Krypton

Diagnostics

- Laser Induced Fluorescence
 - Velocity, temperature measurements
- Diode Laser Absorption Spectroscopy
 - Metastable neutrals

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Xe⁺

834.72 nm

5d[4]_{7/2}

Laser Induced Fluorescence



- Laser beam tuned across electronic transition in Xe ions
 - 5d[4]_{7/2}-6p[3]_{5/2} at 834.72 nm
- lons spontaneously emit photons ۲ resulting in their relaxation from its excited state to a lower state (fluorescence)
 - 6s[2]_{3/2} -6p[3]_{5/2} at 541.92 nm



- **Convolution of ion velocity** distribution function (VDF), transition lineshape (inc. hfs, etc.)
- Shape (broadening/shift) dominated by Doppler effect:





Laser Induced Fluorescence Velocimetry







Lineshape of the 834.68 nm Xe transition compared to widths of a pulsed laser and a CW laser. Hyperfine structure (HFS) shown as reference.

- Measurement of time-averaged velocity vectors
 - Non-intrusive measurements in channel and near field plume
 - High spatial resolution (~1mm)
 - High spectral resolution can resolve multiple velocity populations
 - Temporal resolution eliminated by need for long integration times (>100 ms)
- Necessary to develop time-resolved LIF velocity measurements
 - Resolve oscillatory behavior of thrusters
 - Inform M&S for S/C interactions
- CW diode lasers required to take time resolved LIF measurements
 - Typical linewidth of pulsed laser is larger than desired
 - CW Diode Laser: < 300 kHz
 - Pulsed Nd:Yag Dye Laser: > 1.5 GHz
 - Doppler width of transition: < 2 GHz



- New Focus Vortex TLB-6917 tunable diode laser used to seed a TA-7600 VAMP tapered amplifier
 - 60 mW output power
 - Xenon ion (Xe II) transition at 834.72 nm probed (5d[4]_{7/2}-6p[3]_{5/2})
 - Non-resonant fluorescence collected at 541.92 nm (6s[2]_{3/2} -6p[3]_{5/2})
- Stationary xenon neutral (Xe I) reference
 - 9.03 GHz distant 6p'[3/2]₁-8s'[3/2]₁
- Parallelized sample-hold method of timesynchronization
 - 6 time points taken simultaneously
- 9x improvement in data acquisition efficiency
 - Better signal-to-noise
 - Faster data acquisition





1. Take simultaneous measurements of AC discharge current, emission + fluorescence



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BHT-600 Specifications





- BHT-600
 - 600 W annular Hall thruster
 - Manufactured by Busek Co.
- Tested in Chamber 6 at AFRL
 - Background pressure 1.2x10⁻⁵ Torr



b) BHT-600 Operating on Xenon

Nominal Operating Conditions

Anode Flow	2.45 mg/s Xe		
	(20.5 sccm)		
Cathode Flow	$197 \ \mu g/s Xe$		
	(1.5 sccm)		
Anode Potential	300 V		
Anode Current	2.05 A		
Magnet 1 Current	2.0 A		
Magnet 2 Current	2.0 A		

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ion population

Peak lineshape intensity

In phase with current

- Most probable ion velocity
 - 90° phase lag relative to current

Intensity increases w/ growth of

Max velocity after point of peak



Velocity and Intensity Trends

0

25

20

15

Velocity (km/s)

100

200

300

400

500



30

24

18

Frequency (GHz)

600



Channel IVDFs



- Minimal radial variations in channel
- Z = -8 mm (near anode)
 - Slight negative velocity
 - Gradient-driven field reversal
- Z = -6 mm
 - Accelerating potential begins
 - Broader IVDFs
- Z = -4 mm
 - Significant broadening of IVDFs
 - Large temporal variations (5-13 km/s)
 - Spatial extent of propellant ionization and local potential drop fluctuate
- Z = -2 mm, Z = 0 mm
 - IVDFs narrow
 - More even acceleration in time



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Near-Field Plume Measurements

5

10

16

Upcoming radial IVDF measurements

- Elucidate fluctuations in plume divergence
- lon velocity vectors compared to numerical models in HPHall, emission data

Secondary ion velocity population Appears near centerline of thruster

- Low velocity dominates at current minimum
- Primarily caused by geometric effects
- Other causes:

•

- Charge exchange collisions w/ neutrals
- Residual ionization downstream of main potential drop







15

20

25

Axial ion velocity distributions vs. time at Z = 15 mm, R = 0 mm.





30







- Laser diagnostic techniques have been developed alongside propulsion technologies
- Allow us to better understand propulsion technologies that were previously 'black boxes'
- In-situ, time-resolved diagnostics are becoming more important for understanding spacecraft interactions, pushing towards predictive modeling & simulation efforts







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Chris Young, Dr. Andrea Lucca-Fabris, Prof. Mark Cappelli – Stanford University

Amanda Makowiecki , Torrey Hayden, Prof. Greg Rieker – U. of Colorado, Boulder



