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SOLUTIONS AND SIMPLE PROGRAMS TO PERFORM ACCURATE CALCULATIONS BASED ON RICE DISTRIBUTION

by

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ABSTRACT. The Rice distribution arises in bombing problems where it is referred to as the "offset circle probability function." It occurs in radar as a basic relationship involving probability of elarm (PFA), probability of detection (P_d), and signal-power-to-notise-power (S/N) ratio. Evaluation of P_d when PFA and S/N are known, or of S/N when PFA and P_d are known, is of usefulness frequently, but available means in the form of curves, approximations, and tables are not very satisfying. This report presents the solution of the integral in a form that is interesting and easily programmable. Programs in BASIC and for the Hewlett Packard 9100A desk calculator are also included.



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FOREWORD

This report derives solutions to the Rice distribution and contains simple computer programs for solving the integral for the defined dependent variable. This work was accomplished under AirTask A30-303/2161/WII74-000-01.

The report has been reviewed for technical content by J. S. Dinsmore, Jr. and R. B. Seeley.

Released by N. E. WARD, Head Aviation Crdnance Dept. 8 September 1970 Under authority of H. G. WILSON Technical Director

NWC Technical Publication 4999

Published by	Aviation Ordnance Department
Manuscript	35/MS-291
Supersedes	. Inside Distribution Publication 2979
Collation Cover, I	3 leaves, DD Form 1473, abstract cards
First printing	
Security classification	UNCLASSIFIED

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INTRODUCTION

The Rice distribution arises in bombing problems where it is referred to as the "offset circle probability function." It also occurs in radar as a basic relationship involving probability of false alarm (PFA), probability of detection (P_d), and signal-power-to-noise-power (S/N) ratio. Evaluation of P_d when PFA and S/N are known, or of S/N when PFA and P_d are known, is of usefulness frequently, but within the writer's knowledge, available means, in the form of curves, approximations, and tables are not very satisfying. The solution of the integral in a form that is interesting and easily programmable is presented herein. Programs in BASIC and for the newly available Hewlett Packard 9100A desk calculator are also included.

DISCUSSION OF INTEGRAL VARIATIONS

The integral that concerns us appears with numerous minor variations in several references. Six of these variations are as follows:

Equation I is the offset circle probability function.

$$P(a,v) = \int_{0}^{v} xe^{-(a^2 + x^2)/2} i_{o} (ax) dx$$
 (1)

Reference I on page 15, Eq. 1.5 gives

$$P_{d} = (1/\psi_{o}) \int_{E_{+}}^{\infty} \exp\left(\frac{-E_{n}^{2} - E_{s}^{2}}{2\psi_{o}}\right) i_{o}\left(\frac{E_{n}E_{s}}{\psi_{o}}\right) dEn$$
 (2)

Reference 2 on page 407, substituting Eq. 7-144 into Eq. 7-143 gives

$$P_{sb} = \int_{b}^{\infty} \frac{e^{-s^{2}} re^{-r^{2}/2N}}{N} I_{o} (rs \sqrt{2/N}) dr$$
 (3)

Reference 3 on page 170, Eq. 33.43 gives

$$D = \int_{\varepsilon_{*}}^{\frac{\varepsilon}{\sigma^{2}}} e^{-\left[(\bar{\phi})^{2} + \varepsilon^{2}\right]/2\sigma^{2}} |_{o} \left(\frac{\bar{\phi}\varepsilon}{\sigma^{2}}\right) d\varepsilon \qquad (4)$$

Reference 4 on page 126, Eq. 1-35 gives

$$P_{sb} = \int_{\sqrt{-\log_e P_{nb}}}^{\infty} e^{-(y^2 + s^2)} I_o(2sy) dy$$
 (5)

Reference 5 on page 33, Eq. 2.28 gives the following, which is also the form used by Rice in his original work.

$$P_{d} = \int_{V_{+}}^{\infty} \exp \left(-\frac{R^{2} + A^{2}}{2\psi_{o}}\right) I_{o}\left(\frac{RA}{\psi_{o}}\right) dR$$
 (6)

Herein, we will start with Eq. 7 which, except for using P_d in place of P_{sb} , is the same as Eq. 3. The choice is just happenstance.

$$P_{d} = \int_{h}^{\infty} \frac{e^{-s^{2}} re^{-r^{2}/2N}}{N} I_{o}(rs\sqrt{2/N}) dr$$
 (7)

Equations 1-6 are related to Eq. 7 as follows:

In Eq. 1

$$P(a,v) = I - P_{d}$$

$$x = r/\sqrt{N}, dx = dr/\sqrt{N}, v = b/\sqrt{N}$$

$$a^{2}/2 = S^{2}, a = \sqrt{2} S$$

In Eq. 2

$$E_n = r$$
, $dE_n = dr$

$$E_{\dagger} = b$$
, $P_{d} = P_{d}$

$$\psi_0 = N$$
, $E_s^2/2\psi_0 = S^2$

In Eq. 3

$$P_{sb} = P_{d}$$

In Eq. 4

$$\varepsilon = r, \varepsilon_* = b$$

$$\sigma^2 = N$$
, $\bar{\phi} = S\sqrt{2N}$, $D = P_d$

In Eq. 5

$$\sqrt{-\log_e P_{nb}} = \frac{b}{\sqrt{2N}}$$

$$y^2 = r^2/2N$$
, $y = r/\sqrt{2N}$, $dy = dr/\sqrt{2N}$

In Eq. 6 (essentially the same as 2)

$$R = r, V_T = b$$

$$\psi_{0} = N, A^{2}/2\psi_{0} = S^{2}$$

In Eq. 1-7, the modified Bessel function of the first kind and zero order $I_0(Z)$ appears, and its expansion in series form, as found in handbooks or in Ref. 1-5, is given as follows:

$$I_0(Z) = \sum_{n=0}^{\infty} \frac{Z^{2n}}{2^{2n}(n!)^2}$$
 (8)

Substituting Eq. 8 into Eq. 7 and replacing Z with rs $\sqrt{2/N}$ gives

$$P_{d} = \int_{b}^{\infty} \frac{e^{-s^{2}} r e^{-r^{2}/2N}}{N} \sum_{n=0}^{\infty} \frac{(r s \sqrt{2/N})^{2n}}{2^{2n} (n!)^{2}} dr$$
 (9)

In Eq. 9, since we are integrating with respect to r, and summing with respect to n, we can take e^{-s^2}/N outside the integral and take $re^{-r^2}/2N$ inside the summation to give the following:

$$P_{d} = \frac{e^{-s^{2}}}{N} \int_{n=0}^{\infty} \frac{(s\sqrt{2/N})^{2n} e^{-r^{2}/2N} r^{2n+1}}{2^{2n} (n!)^{2}} dr$$
 (10)

In Eq. 10, the s and r functions that appear inside the summation sign have also been separated.

The integration and summation in Eq. 10 can be interchanged in order and, since we are integrating with respect to r, we can write the following.

$$P_{d} = \frac{e^{-s^{2}}}{N} \sum_{n=0}^{\infty} \left[\frac{(s\sqrt{2/N})^{2n}}{(2)^{2n}(n!)^{2}} \int_{b}^{\infty} e^{-r^{2}/2N} r^{2n+1} dr \right]$$
 (11)

In Eq. II consider the integral

$$\int_{b}^{\infty} e^{-r^{2}/2N} r^{2n+1} dr$$
 (12)

Let

$$y = -r^2/2N \text{ or } r^2 = -2Ny$$

Then

$$dy = -\frac{r}{N} dr$$

or

$$dr = -\frac{N}{r} dy$$

By making these substitutions into Eq. 12 we get Eq. 13.

$$-N \int_{r=b}^{r=\infty} e^{y} (-2Ny)^{n} dy$$
 (13)

Expressing Eq. 13 operationally we get

$$\left[-N \frac{1}{D} e^{y} (-2Ny)^{n}\right]_{r=b}^{r=\infty}$$
(14)

$$= \left[-N e^{y} \frac{1}{D+1} \left(-2Ny \right)^{n} \right]_{r=b}^{r=\infty}$$
 (15)

$$= \left[-N e^{y} (1 - D + D^{2} - D^{3} + D^{4} - D^{5} - --) (-2Ny)^{n} \right]_{r=b}^{r=\infty}$$
 (16)

$$= \left[-N e^{y} \left\{ (-2Ny)^{n} - n(-2N)(-2Ny)^{n-1} \right\} \right]$$
 (17)

$$+(n)(n-1)(-2N)^{2}(-2Ny)^{n-2}$$
 = $r=b$

$$= \left[-Ne^{y} \sum_{k=0}^{n} (-1)^{k} \frac{n!}{(n-k)!} (-2N)^{k} (-2Ny)^{n-k} \right]^{r=\infty}$$
(18)

$$= \begin{bmatrix} -Ne^{-\frac{r^2}{2N}} & n \\ k=0 \end{bmatrix} (2N)^k \frac{n!}{(n-k)!} (r^2)^{n-k}$$
 r=b (19)

$$= Ne^{-\frac{b^2}{2N}} \sum_{k=0}^{n} (2N)^k \frac{n!}{(n-k)!} (b^2)^{n-k}$$
 (20)

Substituting Eq. 20 for the integral in Eq. II we get the following.

$$P_{d} = e^{-s^{2}} e^{-\frac{b^{2}}{2N}} \sum_{n=0}^{\infty} \left[\frac{(s\sqrt{2/N})^{2n}}{2^{2n}(n!)^{2}} \sum_{k=0}^{n} (2N)^{k} \frac{n!}{(n-k)!} (b^{2})^{n-k} \right] (21)$$

or

$$P_{d} = e^{-s^{2}} e^{-\frac{b^{2}}{2N}} \sum_{n=0}^{\infty} S^{2n} \sum_{k=0}^{n} \frac{2^{n} 2^{k} N^{k} (b^{2})^{n-k}}{N^{n} (2)^{2n} n! (n-k)!}$$
(22)

ог

$$P_{d} = \sum_{n=0}^{\infty} \frac{(S^{2})^{n}}{e^{S^{2}} n!} \sum_{k=0}^{n} \frac{(b^{2}/2N)^{n-k}}{e^{b^{2}/2N} (n-k)!}$$
(23)

In Eq. 23, S^2 is the signal-power-to-noise-power ratio, and $e^{-b^2/2N}$ is the PFA. Using R for the signal-to-noise ratio in place of S^2 and T in place of $b^2/2N$, we get the following:

$$P_d' = \sum_{n=0}^{\infty} \frac{R^n}{e^n n!} \sum_{k=0}^{n} \frac{T^{n-k}}{e^T (n-k)!}$$
 (24)

The form of Eq. 24 is noteworthy in that for each value of n, the second summation is the ratio of the sum of the first n terms of the e^T series divided by the entire e^T series, and the term between the summation signs acting as a factor is the ratio of the n^{th} term of the e^R series divided by the entire e^R series.

In programming Eq. 24, it will help to write out the development of P_d for the first few values of n.

n	k	Partial Sums
0	0	(1/e ^R)(1/e ^T)
ı	0, 1	$(R/e^R) \{ (1 + T)/e^T \}$
2	0, 1, 2	${R^2/(e^R 2!)}$ {(1 + T + T ² /2!)/ e^T }
	•	•
•	•	•
•	•	•
n	0, i,n	${R^{n}/(e^{R_{n}!})}{(1 + T + T^{2}/2! + T^{n}/n!)/e^{T}}$

We are to find P_d with the following given:

(S/N) in db =
$$10 \log_{10} R$$

PFA = i/e^{T}

We define and use the following calculations where n takes integral values starting with zero.

FI =
$$R^{n}/(e^{R}n!)$$

F0 = $T^{n}/(e^{T}n!)$
F2 = (I + T + $T^{2}/2!$ + ---- $T^{n}/n!$)/ e^{T}
 δ = (FI)(F2)

Each of the partial sums above is made up of two factors: the factor involving R and the factor involving T. We call the R factor "FI" and the T factor "F2." Succeeding FI factors are obtained by multiplying the preceding FI factor by R/n. Succeeding F2 factors are obtained by adding a new term to the preceding F2 factor; we call this additive increment "F0." Succeeding F0 increments are obtained by multiplying the preceding F0 increment by T/n.

In the program, we call the partial sums " δ " because they are additive increments to the previous sum to get the next approximation to P_d . These δ terms can be very small for initial values of n and therefore we cannot use a simple comparison of a newly calculated δ with a small number as a test for stopping the calculation. We compare each δ with the previous δ and continue as long as δ s are increasing. When the δ s start decreasing we terminate when we reach a $\delta \leq 10^{-11}$ value, which goes beyond needed accuracy and can be altered if desired, although the required number of executions will not be greatly reduced.

A program for Eq. 24 in BASIC is as follows:

```
[where PO=PFA, R4=(S/N) in db; both given]
10
       READ PO. R4
       LET T= -LOG(PO) [where LOG is to base e]
20
       LET R=10+(.1*R4)
                   [where P4=P<sub>d</sub>; to be calculated]
40
       LET P4=0
                   [where Di=6; see D2 below]
50
       LET
            D1=0
       LET M=0
                   [where M=n]
60
80
       LET FI=EXP(-R)
       LET F2=0
100
120
       LET F0=P0
       LET F2=F2 + F0
160
180
       LET D2=F1*F2
                      [where D2=\delta, D1 and D2 are succeeding values of \delta]
       LET P4=P4 + D2
20υ
220
       LET M=M + I
       LET FI=(R/M)*FI
240
       LET FO=(T/M)*FO
260
       1F
            D2>D1 THEN 340
280
            D2>1E-11 THEN 340
300
       1F
320
       GO TO 380
       LET DI=D2
340
       GO TO 160
360
       PRINT "PFA= "; PO, "S/N= "; R4, "PD= "; P4
380
400
       GO to 10
```

Finding (S/N) = R when PFA = $1/e^{T}$ and P_d are given can be done as follows:

Let

999

END

$$f(R) = \sum_{n=0}^{\infty} \frac{R^n}{e^R} \sum_{n=0}^{n} \frac{T^{n-k}}{e^T[(n-k)!]} - P_d$$

$$= P_d(R) - P_d$$
(25)

We wish to find the value of R that makes f(R) = 0 in Eq. 25. Taking P_d and T as constants we get:

$$\frac{df(R)}{dR} = \sum_{n=0}^{\infty} \frac{n R^{n}}{e^{R} R n!} \sum_{k=0}^{n} \frac{T^{n-k}}{e^{T} [(n-k)!]} - P_{d}(R)$$

$$= I/e^{R} I/e^{T} [0+I(T+I)+R(T^{2}/2!+T/I!+I)$$

$$+ R^{2}/2!(T^{3}/3!+T^{2}/2!+T/I!+I) ----]$$

$$- I/e^{R} I/e^{T} [1+R(T+I)+R^{2}/2!(T^{2}/2!+T/I!+I)$$

$$+ R^{3}/3!(T^{3}/3!+T^{2}/2!+T/I!+I) ----]$$
(26)

or

$$\frac{df(R)}{dR} = I/e^{R} I/e^{T} \left[T + \frac{R}{1!} \frac{T^{2}}{2!} + \frac{R^{2}}{2!} \frac{T^{3}}{3!} + \frac{R^{3}}{3!} \frac{T^{4}}{4!} - \cdots \right]$$
 (27)

If we make an initial estimate of $R=R_1$, we can use the Newton-Raphson iterative procedure (Eq. 28) to get succeeding approximations.

$$R_2 = R_1 - f(R_1)/f^1(R_1)$$
 (28)

Equation 24 programmed for the H.P. 9100A follows:

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The function f(R) plotted as the ordinate with R as the abscissa lies between $f(R) = PFA - P_d$ and an upper asymptote $f(R) = I - P_d$; at R = 0, f(R) = PFA - Pd with a slope T/e^{T} (where $I/e^{T} = PFA$) and rises, changing from concave upward to concave downward, toward its upper asymptote. Because of this shape, the repetitive use of Eq. 28 will converge only when the initial R_1 has suitable values. Two programs, one in BASIC and one for the H.P. 9100A, are presented below. In the BASIC program, a rough initial estimate of R is generated. In the H.P. 9100A program, a value for R₁ must be entered and changed if necessary to secure convergence. The BASIC program, as written, finds S/N in db to the nearest 0.01 db. The H.P. 9100A program presents the result following each iteration showing R_1 and R_2 for comparison; pressing "CONTINUE" proceeds to the next approximation so that the full accuracy of the calculator is attainable. When the two values are adequately alike, setting the flag and pressing "CONTINUE" gives a display of S/N in decibels. A separate program for the H.P. 9100A is given also to generate an initial value for R₁. The BASIC program, as given, has been run on the GE Mark I time-sharing system for a wide range of PFA and Pd values, but it operates for only a limited range of values on the GE Mark II time-sharing system on which it produces underflows that sometimes lead to divisions by zero.

CALCULATION OF S/N WHEN PFA AND $\mathbf{P_d}$ ARE GIVEN

All alpha registers and register 9 are used for storage. If new estimate R_2 diverges, insert an intermediate estimate in the y register before pressing "CONTINUE" at program step 71 (not necessary to preserve x and z displays). If R_2 is negative, zero can be used as a new R_2 .

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APPROXIMATION TO S/N WHEN PROBABILITY OF FALSE ALARM AND PROBABILITY OF DETECTION ARE GIVEN

This is intended only for use as a first estimate of R in Eq. 28. APPROXIMATE R = \sqrt{T} (\sqrt{T} + $2\sqrt{2}(2P_d - 1)$) + 8 $P_d(P_d - 1)$ + 1.5

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```
PRINT "PFA," "PD," "(S/N), DB"
10
15
       FRINT
20
       READ PO, F4
25
       IF PO = P4 THEN 365
30
       IF PO > P4 THEN 378
35
       LET T = -LOG(PO)
       LET_RI = T + SQR (8*T)*(2 P4 - 1) + 8* P4*(P4 - 1) + 1.5
40
49
       LET R2 = R1
50
       IF RI > 0 THEN 70
60
       LET RI = (P4/P0 - I)/T
70
       LET N = I
75
       LET F = 0
80
       LET FO = PO
90
       LET FI = EXP(-RI)
100
       LET S = 0
110
       LET DI = 0
120
       LET D = F1*P0
130
       LET P = D
140
       LET FO = (T/N)*FO
150
       LET SO = FI*FO
160
       LET S = S + SO
170
       LET D = (RI/N)*(SO + D)
180
       IF DI < D THEN 210
190
      IF IE-II < D THEN 210
200
       LET F = I
210
       LET DI = D
220
       LET P = P + D
230
      LET FI = (RI/N)*FI
240
     LET N = N + I
250
     IF F = 1 THEN 265
```

A program in BASIC for Eq. 28 is as follows:

260

GO TO 140

```
265
       LET R0 = (P4 - P)/S
280
       IF ABS(RO) < 10 THEN 300
290
       LET R0 = 10*(R0/ABS(R0))
300
       LET R = RI + R0
310
       IF R > 0 THEN 330
320
       LET RI = RI/2
325
       GO TO 70
330
       IF ABS (LOG(R/RI)) < = .00115 THEN 360
340
       LET RI = R
350
       GO TO 70
       PRINT PO, P4, INT(1000 * (LOG(R)/LOG(10)) + .5)/100
360
361
       PRINT R2, R
362
       GO TO 15
365
       PRINT
       PRINT PO, P4, "NO SIGNAL"
370
375
       GO TO 15
378
       PRINT
       PRINT PO, P4, "PD < PFA"
380
385
       GO TO 15
500
       DATA PFA, Pd, ---- PFA, Pd, ETC.
999
       END
```

CONCLUSIONS

These programs have proven useful in evaluating radar data acquired using pulse height analysis.

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DOCUMENT CONTROL DATA - R & D (Security classification of titie, body of abstract and indexing annotation must be entered when the overall report ix classified)									
1. ORIGINATING ACTIVITY (Corporate author)		20. REPORT SE	CURITY CLASSIFICATION						
Naval Weapons Center China Lake, California 93555		UNCLASSIF [ED							
SOLUTIONS AND SIMPLE PROGRAMS TO PERFORM ACCURATE CALCULATIONS BASED ON RICE DISTRIBUTION									
4. DESCRIPTIVE HOTES (Type of report and inclusive dates)									
S. AUTHORIS) (Fliet name, middle initial, last name) Jerome P. Madden									
September 1970	74. TOTAL NO. 01	75. NO. OF REFS							
SE. CONTRACT OR GRANT NO.	Se. ORIGINATOR'S	REPORT NUMB	ER(\$)						
A. PROJECT NO. AirTask A30-303/2161/W1174-000-01	NWC TP 4999								
с.	Sb. OTHER REPOR	RT NO(S) (Any of	her numbers that may be assigned						
4. 10. DISTRIBUTION STATEMENT									
EACH TRANSMITTAL OF THIS DOCUMENT OUTSIDE THE AGENCIES OF THE U.S. GOVERNMENT MUST HAVE PRIOR APPROVAL OF THE NAVAL WEAPONS CENTER.									
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		terial Co on, D.C.							
The Rice distribution arises in bombing problems where it is referred to as the "offset circle probability function." It also occurs in radar as a basic relationship involving probability of false alarm (PFA), probability of detection (Pg), and signal-power-to-noise-power (S/N) ratio. Evaluation of Pg when PFA and S/N are known, or of S/N when PFA and Pg are known, is of usefulness frequently, but available means in the form of curves, approximations, and tables are not very satisfying. This report presents the solution of the integral in a form that is interesting and easily programmable. Programs in BASIC and for the Hewlett Packard 9100A desk calculator are also included.									

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**. KEY WORDS		Security Classification						
	LIN	4 A	LINK D		LINKC			
	ROLE	WT	ROLE	WT	ROLE	WT		
Rice Distribution Modified Rayleigh Distribution Offset Circle Probability Function Solution of Integrals Probability of Detection Probability of False Alarm Signal-to-Noise Ratio Computer Programs			·					

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