AFWL-TR-68-46

0

AD 84051

AFWL-TR-68-46

ACT.

90

1

1

# EXPONENTIALLY DECAYING PRESSURE PULSE MOVING WITH SUPERSEISMIC VELOCITY ON THE SURFACE OF A HALF SPACE OF VON MISES ELASTO-PLASTIC MATERIAL

Hans H. Bleich

Alva Matthews

Paul Weidlinger, Consulting Engineer New York, New York 10017

Contract F29601-67-C-0091

TECHNICAL REPORT NO. AFWL-TR-68-46

August 1968

AIR FORCE WEAPONS LABORATORY Research and Technology Division Air Force Systems Command Kirtland Air Force Base New Mexico

This document is subject to special export controls and each transmittal to foreign governments, or foreign nationals may be made only with prior approval of AFWL (WLDC), Kirtland AFB, NM, 87117.

AFWL-TR-68-46

Ø

иÌ

EXPONENTIALLY DECAYING PRESSURE PULSE MOVING WITH SUPERSEISMIC VELOCITY ON THE SURFACE OF A HALF SPACE OF VON MISES ELASTO-PLASTIC MATERIAL Hans H. Bleich Alva Matthews Paul Weidlinger, Consulting Engineer New York, New York 10017

Contract F29601-67-C-0091

TECHNICAL REPORT NO. AFWL-TR-68-46

This document is subject to special export controls and each transmittal to foreign governments or foreign nationals may be made only with prior approval of AFWL (WLDC), Kirtland AFB, NMex 87117. Distribution is limited because of the technology discussed in the report.

#### FOREWORD

This report was prepared by Paul Weidlinger, Consulting Engineer, New York, N. Y. under Contract F29601-67-C-0091. The research was performed under Program Element 6.16.46.01.41, Project 5710, Subtask RSS2144, and was funded by the Defense Atomic Support Agency (DASA).

Inclusive dates of research were October 1967 to May 1968. The report was submitted 18 June 1968 by the AFWL Project Officer, Dr. Henry F. Cooper, Jr. (WLDC).

This report has been reviewed and is approved.

Hin

DR. HENRY F. COOPER, JR. Project Officer

ROBERT E. CRAWFOR Lt Col USAF Chief, Civil Engineering Branch

GEORGE C. DARBY JR Colonel USAF Chief, Development Division

t

#### ABSTRACT

(Distribution Limitation Statement 2)

An approximate solution is given for the effect of an exponentially decaying pressure pulse traveling with superseismic velocity on the surface of a half-space. The halfspace is an elastic-plastic material of the von Mises type. The effect of a step wave for this geometry and medium was treated previously. For that case, the peak pressures do not decrease with increase in depth, while such a decrease is obtained for a decaying surface load. The prime purpose of this investigation is to determine the magnitude of this attenuation. The approximate solutions obtained are valid for a limited distance behind the wave front, and are tabulated for different sets of parameters pertaining to the material and velocity. The tabulated results show that the peak pressures in the case of the decaying surface load do decrease with depth, but that the decrease is less than one might intuitively expect. On the other hand the attenuation is in general larger than that encountered in the similar problem of an elasto-plastic material of the Coulomb type.

AFWL-TR-68-46

This page intentionally left blank.

4

ív

# CONTENTS

•

Section

Ľ

A second s

۲

I	Introduction	1
II	Formulation of the Approximate Analysis	15
III	Solution of the Differential Equations by Taylor Series	24
IV	Numerical Results and Discussion	31
	l. Discussion of Typical Results	32
	2. Range of Depth for which Results Apply.	72
v	Conclusions	74
APPENDIX I	Special Case, m = 0	75
APPENDIX II	Elastic Solutions	77
DISTRIBUTION .		79

Page

•

#### LIST OF ILLUSTRATIONS

Figure

1

2

3

4

5

6

7

8

9

# Step Pressure moving over Half-Space 2 Decaying Pressure moving over Half-Space 2 Configuration for Step Pressure $p_0 > p_L$ 5 Parameters for which Tables are given in Section IV 7 Range I Solutions, $p_E < p_o < p_L$ 8 Sange II Solutions, $p_E < p_o < p_L$ 8 Configuration of Elastic Solutions Q, Configuration for Approximate Solution 12 (v > 1/8)Yield Violation at the Surface for a 34 Step Wave

10 through 18	Principal stresses $\sigma_1^{}/k$ at $ar{\Phi}$ for	
	different values of $v$ and V/c <sub>p</sub>	36

Page

# LIST OF TABLES

•

Ia	Exact Stresses for $p_0/k = 4.41$	35
Ib	Approximate Stresses for $p_0/k = 4.41$	35
II through XXVIII	Results for selected values of $v$ ,	
	V/c <sub>p</sub> , p <sub>o</sub> /k	37

\* \*

.

•

.

# LIST OF SYMBOLS

<sup>a</sup> i, <sup>b</sup> i, <sup>c</sup> i	Coefficients of Tavlor series expansion.
c <sub>p</sub> , c <sub>s</sub> , <del>c</del>	Velocity of propagation of elastic P-waves,
	S-waves, and inelastic shock fronts,
	respectively.
f <sub>i</sub> , g <sub>i</sub>	Arbitrary functions of x or y.
G	Shear modulus.
J <sub>1</sub> , J <sub>2</sub>	Invariants, Eqs. (51) and (2).
k	Material parameter related to yield stress
	in shear.
$M = \frac{V}{c_p}$ , $M_S = \frac{V}{c_S}$	
n	Ratio defined by Eq. (11).
N <sub>1</sub> ,, N <sub>10</sub>	Functions defined by Eqs. (82).
p(x - Vt)	Surface pressure.
р <sub>о</sub>	Initial value of the surface pressure.
t	Time.
u, v, ů, ř	Particle displacements and velocities in
	x and y directions, respectively.
ů <sub>N</sub> ,ů <sub>T</sub>	Particle velocities normal and tangential,
	respectively to fronts of discontinuity.
V	Velocity of surface pressure.
х, у	Cartesian coordinates.
Δσ. Δύ. Δτ	Increments of σ, ů, τ, etc., at a front.

viii

ε <sub>i</sub>	Strain rates.
$\xi = x - Vt$	Coordinate.
θ	Angle between direction of principal stress
	$\sigma_{l}$ and x-axis.
μ	Decay constant of surface pressure, Eq. (46).
ν	Poisson's ratio.
ρ	Mass density of medium.
σ <sub>i</sub> , τ	Normal and shear stresses, respectively.
σ <sub>1</sub> , σ <sub>2</sub> , σ <sub>3</sub>	Principal stresses.
σ <sub>N</sub> , τ <sub>N</sub> , σ <sub>T</sub>	Stresses, respectively in the plane, and
	perpendicular to the plane of a shock front.
φ	Position angle of element, Fig. 8.
$\phi_{\rm P}$ , $\phi_{\rm S}$ , $\overline{\phi}$	Position angle of elastic P- and S- and
	inelastic shock fronts, respectively.
Φ, Ψ, Ψ, Ψ	Potential functions.

ix

AFWL-TR-68-46

٥

j

Ì.

This page intentionally left blank.

×

#### SECTION I

#### INTRODUCTION

In a preceding analysis, Refs. [1] and [2]<sup>\*</sup>, the effect of a step pressure, Fig. 1, progressing with a superseismic velocity V on the surface of a half-space has been studied for an elastic-plastic material subject to the von Mises yield condition

$$J_2 - k^2 = 0$$
 (1)

where k is the yield stress in shear and  $J_2$  is the invariant

$$J_{2} = \frac{1}{2} s_{ij} s_{ij}$$
 (2)

The present report considers the more general problem of a decaying pressure pul p(x - Vt), Fig. 2, moving with a superseismic, constant velocity V. The problem under study here is more realistic than the one treated in Refs. [1] and [2], but it is also considerably more complex. Because of the complexity only an approximate solution will be derived, which is valid for a limited distance from the moving front.

·······

<sup>[1]</sup> Bleich, H.H. and Matthews, A.T., "Step Load Moving with Superseismic Velocity on the Surface of an Elastic-Plastic Half-Space", Int. J. Solids and Structures, 3, 819-852, 1967. (Also Office of Naval Research, Tech. Rpt. 38, Contract Nonr-266(86), December 1965.)

<sup>[2]</sup> Matthews, A.T. and Bleich, H.H., "Stresses in an Elastic-Plastic Half-Space Due to a Superseismic Step Load", TBL, Ballistics Research Laboratory, Aberdeen, Md., Tech. Rpt. 4, Contract DA-30-069-AMC-8(R), March 1966.





Step Pressure moving over Half-Space





Decaying Pressure moving over Half-Space

2

.

The approximation employed is somewhat similar to the one utilized and discussed in Ref.  $[3]^{*}$  for a material subject to a different yield condition.

Because the velocity V of the load is constant, the resulting stress and velocity fields remain unchanged if considered in a coordinate system moving with velocity V. In other words, Refs. [1], [2] and [3] and the present paper consider steady-state solutions, which may be used as approximations to actual situations when the velocity V varies gradually.

It was found in Refs. [1] and [2] that the response to the step pressure changes in character depending on the range in which the values of Poisson ratio v, of the velocity ratio  $V/c_p$ , and of the intensity of the surface step load  $p_o$  are situated. As introduction to the problem with a decay of pressure, some aspects of the results of the analysis for the step pressure are restated in the following.

Defining the location of a field point by the polar coordinates  $\phi$  and r, Fig. 1, where the origin of the coordinate system lies at and moves with the front of the surface load, it was found that the stresses and velocities are functions of the angle  $\phi$  only. For a step pressure there is

<sup>[3]</sup> Bleich, H.H. and Matthews, A.T., "Exponentially Decaying Pressure Pulse Moving with Superseismic Velocity on the Surface of a Half-Space of Granular Material", Tech. Rpt. AFWL-TR-67-21, Contract AF29(601)-7082, July 1967.

therefore no dependence of stresses or velocities on the radius r, so that there is no attenuation with depth. It was found, further, that for sufficiently large values of the surface load,  $p_0 > p_L$ , the solution has the character of Fig. 3, where the value of  $p_L$  depends on the parameters v and  $V/c_p$ .

The configuration shown in Fig. 3 shows two discontinuities, a P-front and an S-front, moving with the velocities of elastic P- and S-waves

$$c_{\rm P}^2 = \frac{2(1-\nu)}{1-2\nu} \frac{G}{\rho}$$
(3)

$$c_{\rm S}^2 = \frac{G}{\rho} \tag{4}$$

respectively. The locations of the fronts are defined by the related angles

$$\phi_{p} = \pi - \sin^{-1} \left[ \frac{1}{v} \sqrt{\frac{2(1-v)G}{(1-2v)\rho}} \right]$$
(5)

$$\Phi_{\rm S} = \pi - \sin^{-1} \left[ \frac{1}{V} \sqrt{\frac{G}{\rho}} \right] \tag{6}$$

The changes in stress and velocity at these fronts are entirely elastic. There are four "neutral" regions of uniform stress (and uniform velocity), i.e., regions where the yield condition, Eq. (1), is just satisfied, but no yield occurs at the particular instant. There are two plastic regions,  $\phi_1$  to  $\phi_2$ , and from  $\phi_3$  to  $\phi_4$ , where plastic deformations occur at the particular instant, and where the stresses



NEUTRAL REGIONS OF UNIFORM STRESS SATISFYING EQ.I

.

CONFIGURATION FOR STEP PRESSURES P. > PL

FIG.3

5

(and velocities) vary as functions of the location  $\phi$ . One of the plastic regions is always located between the P- and S-fronts, and one between the S-front and the surface.

If the surface load lies below the limit  $p_L$ , but above another value  $p_E < p_L$ , so that

$$p_{E} < p_{O} < p_{L}$$
(7)

only one of the two plastic regions occurs, which one occurs depends on the parameters v and  $V/c_p$ . If these parameters lie in Range I or II of Fig. 4, the configurations of Fig. 5 or 6 apply, respectively. In these cases two of the neutral regions shown in Fig. 3 coalesce and become a region of uniform stress below yield as noted in Figs. 5 and 6. The demarkation line between Ranges I and II in Fig. 4 is given by the relation

$$V/c_{p} = \frac{(1-2\nu)^{2}}{(1-\nu)(1-3\nu)}$$
 (8)

If, finally,  $p_0 \leq p_E$ , the solution becomes entirely elastic, Fig. 7.

One detail obtained in Ref. [1] for the step pressure is crucial for the present purpose. If  $p_0$  is not only larger, but very much larger than  $p_L$ , it was found that one of the two plastic regions in Fig. 3 is of much greater importance than the other. This means that the energy dissipated and the changes in stress and velocity in the "important" region



• PARAMETERS FOR WHICH TABLES ARE GIVEN IN SECTION IV.

FIG. 4



1

.



.

~

# CONFIGURATION OF ELASTIC SOLUTIONS

FIG. 7

5. 11

•

are very much larger than in the other plastic region. In the "important" region the bulk of energy dissipation and of the changes in stress and velocity occur for values of  $\phi$  very close to a critical angle  $\overline{\phi}$  for which the basic differential equations are capable of a singular, discontinuous solution. The critical angle is connected with the fact, that in the von Mises material considered, plastic shock fronts may exist, having a velocity

$$\overline{c}^2 = \frac{2(1+\nu)}{3(1-2\nu)} \frac{G}{\rho}$$
(9)

As discussed in Ref. [1], at such shock fronts the state of stress ahead and behind the front must be at yield, but - in addition - the major principal stress must be at a right angle to the front and the other two principal stresses must be equal. It is shown in Ref. [1] that at such a plastic shock front all three principal stresses change by the same amount  $\overline{\Delta\sigma}$ , while the component of the velocity normal to the front changes as required by conservation of momentum.

In the present steady-state problem the angle  $\bar{\phi}$  may be obtained from the value for  $\bar{c}$ ,

$$\overline{\phi} = \sin^{-1} \left[ \frac{1}{V} \sqrt{\frac{2(1+v)}{3(1-2v)}} \frac{G}{\rho} \right]$$
(10)

The location of this front depends on the value of Poisson's ratio  $\nu.$  If  $\nu$  > 1/8 the critical angle  $\bar{\phi}$  lies between  $\phi_p$  and  $\phi_S$  .

While in the actual problem the above stated conditions for a discontinuity are not exactly satisfied and no shock front occurs, the conditions are nearly satisfied when  $p_o >> p_L$ . As a result, very rapid changes were found in Ref. [1] in an extremely narrow range of the angle  $\phi$  near  $\overline{\phi}$ when  $p_o$  exceeds about 5. (See the tables in Ref. [2].)

The fact that for large values of p the plastic effects are nearly a "shock front" at  $\phi = \overline{\phi}$ , suggests that approximate solutions could be obtained by compressing (approximately) all plastic effects into a discontinuity in normal pressure and velocity at  $ar{\phi},$  and treating the material elsewhere (approximately) as entirely elastic, even if the yield condition is slightly violated. For the case of a step pressure  $p_0 > p_L$ , this approximate solution for  $\nu > 1/8$  would have the configuration shown in Fig. 8. In addition to the elastic discontinuities at  $\boldsymbol{\varphi}_S$  and  $\boldsymbol{\varphi}_P$  , there is an assumed discontinuity at  $ar{\phi}$ , consisting of a change of all three principal stresses by an amount  $\overline{\Delta\sigma}$  and an appropriate change of normal velocity. In the region between these fronts the stresses and velocities are uniform, but the yield condition in one or two of the regions will be violated. Such violation is considered acceptable provided it is not too severe.

In view of the fact that correct solutions for the step pressure are available, there is no need to consider this case further, but the equivalent approximations can be made, and will be made below for the case of a decaying surface load.



(√ >1/8)

FIG. 8

تستخلبها ألمأكم فيرجر

•

12

ŧ.

Assuming the discontinuities stated above, at  $\phi_p$ ,  $\phi_s$  and  $\bar{\phi}$ , it will be assumed that the elastic differential equations apply in each of the three wedge shaped regions shown in Fig. 8. Solving the boundary value problem posed by the prescribed surface load and by momentum or continuity considerations, approximate solutions are obtained. After finding the solutions the degree of violation of the yield condition can be checked by computing the ratio,

$$n = \frac{\left| \sqrt{J_2} \right|}{k} \tag{11}$$

starting near the leading edge of the load. If the solution in this location and within some distance  $\bar{r}$  from the wave front is acceptable, the hyperbolic nature of the problem bermits one to accept the solution in the range  $r < \bar{r}$ , even if serious violations of the yield condition occur elsewhere for  $r > \bar{r}$ . A further restraint on the range of validity,  $\bar{r}$ , is the fact that the compressive stress at the shock front  $\phi = \bar{\phi}$  must inherently 'ncrease and the solution can only be accepted within a radius  $\bar{r}$  where this requirement holds.

In the numerical solution obtained later the ratios n indicating compliance or violation of the yield condition are stated for each point where stresses are given. For engineering purposes values up to n = 1.2 were considered, but a reader may elect not to use the full range of the solution given if smaller values of n appear appropriate. It is found that the range of applicability shrinks as V/cp becomes smaller and approaches unity.

The formulation of the problem given below applies only for values  $\nu \ge 1/8$ . Therefore the tables given contain only values  $V/c_p \ge 1.5$  and  $\nu > 1/8$ .

.

#### SECTION II

#### FORMULATION OF THE APPROXIMATE ANALYSIS

Based on the reasoning outlined in Section I, approximate solutions for the case of the decaying shock wave, Fig. 2, will be formulated. Only the case v > 1/8 is considered so that  $\phi_S > \overline{\phi}$ . In accordance with the discussion in the Introduction, it is assumed (approximately) that plastic deformations occur in any element only at the time of passing of the plastic shock front indicated in Fig. 8, while stress changes thereafter are elastic. The applicable elastic relations between stress rates and strain rates for the present case of plain strain are

$$\dot{\varepsilon}_{x} \equiv \frac{\partial \dot{u}}{\partial x} = \frac{1}{E} \left[ \dot{\sigma}_{x} - \nu \dot{\sigma}_{y} - \nu \dot{\sigma}_{z} \right] = \left( \frac{1 - \nu^{2}}{E} \right) \left[ \dot{\sigma}_{x} - \frac{\nu}{1 - \nu} \dot{\sigma}_{y} \right]$$
(12)

$$\dot{\varepsilon}_{y} \equiv \frac{\partial \dot{v}}{\partial y} = \frac{1}{E} \left[ -\nu \dot{\sigma}_{x} + \dot{\sigma}_{y} - \nu \dot{\sigma}_{z} \right] = \left( \frac{1 - \nu^{2}}{E} \right) \left[ -\frac{\nu}{1 - \nu} \dot{\sigma}_{x} + \dot{\sigma}_{y} \right]$$
(13)

$$\dot{\varepsilon}_{z} \equiv 0 = \frac{1}{E} \left[ -\nu \dot{\sigma}_{x} - \nu \dot{\sigma}_{y} + \dot{\sigma}_{z} \right]$$
(14)

$$\dot{\varepsilon}_{xy} \equiv \frac{1}{2} \left[ \frac{\partial \dot{u}}{\partial y} + \frac{\partial \dot{v}}{\partial x} \right] = \frac{1}{2G} \dot{\tau}$$
(15)

where  $\sigma_x$ ,  $\sigma_y$ ,  $\sigma_z$ ,  $\tau$  are the stresses, while u, v, are the displacements in the x and y directions, respectively. In addition, the equation of motion

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau}{\partial y} = \rho \frac{\partial \dot{u}}{\partial t}$$
(16)

$$\frac{\partial \tau}{\partial x} + \frac{\partial \sigma}{\partial y} = \rho \frac{\partial \dot{v}}{\partial t}$$
(17)

must be satisfied. Equations (12, 13, 15) may be integrated with respect to time, requiring the addition of arbitrary functions  $f_i(x,y)$  of x and y,

$$\frac{\partial u}{\partial x} = \frac{1 - v^2}{E} \left[ \sigma_x - \frac{v}{1 - v} \sigma_y \right] + f_1(x, y)$$
(18)

$$\frac{\partial v}{\partial y} = \frac{1-v^2}{E} \left[ -\frac{v}{1-v} \sigma_x + \sigma_y \right] + f_2(x,y)$$
(19)

$$\frac{1}{2} \left[ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right] = \frac{1}{2G} \tau + f_3(x, y)$$
(20)

while Eq. (14) after integration may be written

$$\sigma_{z} = \nu(\sigma_{x} + \sigma_{y}) + f_{o}(x, y)$$
(21)

The last equation is the only relation containing  $\sigma_z$ , and simply defines this quantity. It is noted that the arbitrary functions  $f_1$ ,  $f_2$  and  $f_3$  are not entirely "arbitrary", but are related by a compatibility relation, as may be seen by eliminating u and v from Eqs. (18), (19) and (20).

The solution to the differential equations (16-20) may be expressed in terms of potentials  $\Phi$  and  $\Psi$  which satisfy the wave equations

$$\Phi_{xx} + \Phi_{yy} = \frac{1}{c_p^2} \Phi_{tt}$$
(22)

$$\Psi_{xx} + \Psi_{yy} = \frac{1}{c_{S}^{2}} \Psi_{tt}$$
 (23)

Subscripts on potentials indicate derivatives. In terms of these potentials and of two arbitrary functions  $g_1$  and  $g_2$  of x and y, the displacements become

$$u = \Phi_{x} - \Psi_{y} + g_{1}(x, y)$$
(24)

$$v = \Phi_{y} + \Psi_{x} + g_{2}(x, y)$$
 (25)

while the velocities  $\dot{\textbf{u}}$  and  $\dot{\textbf{v}}$  are

$$\dot{u} = \dot{\Phi}_{x} - \dot{\Psi}_{y}$$
(26)

$$\dot{v} = \dot{\Phi}_{y} + \dot{\Psi}_{x}$$
(27)

The stresses are

$$\sigma_{x} = 2G \left[ \frac{1-\nu}{1-2\nu} \Phi_{xx} + \frac{\nu}{1-2\nu} \Phi_{yy} - \Psi_{xy} \right]$$
(28)

$$\sigma_{y} = 2G \left[ \frac{\nu}{1-2\nu} \Phi_{xx} + \frac{1-\nu}{1-2\nu} \Phi_{yy} + \Psi_{xy} \right]$$
(29)

$$\tau = 2G \left[ \Phi_{xy} + \frac{1}{2} \left( \Psi_{xx} - \Psi_{yy} \right) \right]$$
(30)

with  $\sigma_z$  given by Eq. (21).

Substitution of Eqs. (24-25) and (28-30) into Eqs. (18-20) furnishes relations between the three "arbitrary" functions  $f_1$ ,  $f_2$  and  $f_3$ , and the two functions  $g_1$  and  $g_2$ , i.e.,

$$f_1 = \frac{\partial g_1}{\partial x}$$
,  $f_2 = \frac{\partial g_2}{\partial y}$ ,  $f_3 = \frac{1}{2} \left( \frac{\partial g_1}{\partial y} + \frac{\partial g_2}{\partial x} \right)$  (31)

These three relations and the Eqs. (28-30) satisfy compatibility indentically, leaving the two functions  $g_1(x,y)$  and  $g_2(x,y)$  as arbitrary functions in lieu of the related functions  $f_1$ ,  $f_2$  and  $f_3$ .

It is now noted that the velocities  $\dot{u}$  and  $\dot{v}$ , and the stresses  $\sigma_x$ ,  $\sigma_y$  and  $\tau$  in terms of the potentials  $\Phi$  and  $\Psi$  have exactly the same form as in an elastic plane problem and these quantities will therefore have the same values as in an entirely elastic problem with the same boundary conditions. The plastic deformations at the shock front lead, however, to different expressions for u, v and  $\sigma_z$  because the functions  $g_1$ ,  $g_2$  and  $f_0$  now occur. As will be seen later, these three arbitrary functions follow from conditions at the P-front and at the plastic front.

Due to the fact that the steady-state problem is considered, the surface pressure is solely a function of

$$\xi = x - Vt \tag{32}$$

and the solutions are only functions of  $\xi$  and y. The wave equations for the potentials then become

$$\Phi_{yy} = (M^2 - 1) \Phi_{\xi\xi}$$

$$\Psi_{yy} = (M_S^2 - 1) \Psi_{\xi\xi}$$
(33)

where

$$M = \frac{V}{c_p} ; M_s = \frac{V}{c_s}$$
(34)

Noting that the open functions  $f_0$ ,  $g_1$  and  $g_2$ , which are not functions of t, can in the steady-state not depend on x either, the expressions for displacements and stresses become

$$u = \Phi_{\xi} - \Psi_{y} + g_{1}(y)$$
 (35)

$$v = \Phi_{y} + \Psi_{\xi} + g_{2}(y)$$
 (36)

$$\sigma_{x} = G[2(1 + \frac{\nu M^{2}}{1 - 2\nu}) \Phi_{\xi\xi} - 2\Psi_{\xiy}]$$
(37)

$$\sigma_{y} = G[(M_{S}^{2} - 2) \phi_{\xi\xi} + 2\Psi_{\xi y}]$$
(38)

$$\tau = G[2\Phi_{\xi y} - (M_S^2 - 2) \Psi_{\xi \xi}]$$
(39)

$$\sigma_{z} = v(\sigma_{x} + \sigma_{y}) + f_{o}(y)$$
(40)

To formulate the boundary conditions, expressions will be required for the normal and tangential velocities  $\dot{u}_N$ ,  $\dot{u}_T$ and the normal, tangential and shear stresses  $\sigma_N$ ,  $\sigma_T$ ,  $\tau_N$ for planes inclined at any angle  $\phi$  (see Fig. 1)

$$\frac{\dot{u}_{N}}{V} = i - \phi \Phi_{\xi\xi} - \cos \phi \Phi_{\xiy} - \cos \phi \Psi_{\xi\xi} - \sin \phi \Psi_{\xiy}$$
(41)  

$$\frac{\dot{u}_{T}}{V} = -\cos \phi \Phi_{\xi\xi} - \sin \phi \Phi_{\xiy} - \sin \phi \Psi_{\xi\xi} + \cos \phi \Psi_{\xiy}$$
(42)  

$$\frac{\sigma_{N}}{G} = [M_{S}^{2} (1 - \frac{1 - 2\nu}{1 - \nu} \sin^{2}\phi) - 2 \cos 2\phi] \Phi_{\xi\xi} -$$

$$- 2 \sin 2\phi \Phi_{\xiy} + 2 \cos 2\phi \Psi_{\xiy} + (M_{S}^{2} - 2) \sin 2\phi \Psi_{\xi\xi}$$
(43)

$$\frac{\sigma_{\rm T}}{G} = [M_{\rm S}^2 (1 - \frac{1-2\nu}{1-\nu} \cos^2 \phi) + 2 \cos 2\phi] \phi_{\xi\xi} + + 2 \sin 2\phi \phi_{\xiy} - 2 \cos 2\phi \Psi_{\xiy} - (M_{\rm S}^2 - 2) \sin 2\phi \Psi_{\zeta\xi} (44) \frac{\tau_{\rm N}}{G} = (M^2 - 2) \sin 2\phi \phi_{\xi\xi} + 2 \cos 2\phi \phi_{\xiy} + + 2 \sin 2\phi \Psi_{\xiy} - (M_{\rm S}^2 - 2) \cos 2\phi \Psi_{\xi\xi} (45)$$

To state the boundary conditions of the problem properly, and to be able to make statements on the character of the solutions, the differential equations for  $\Phi$  and  $\Psi$  must be discussed. While both differential equations are hyperbolic, the characteristics for  $\Phi$  are steeper than the boundary  $\overline{\Phi}$ defining the plastic front,  $\phi_p < \overline{\Phi}$ . The solution for  $\Phi$  in the region of interest,  $\overline{\Phi} < \phi < \pi$ , Fig. 8, is therefore defined by statements on the boundaries  $\phi = \overline{\Phi}$  and  $\phi = \pi$ .  $\Phi$  will be a continuous function if the prescribed conditions at the boundaries are continuous. This being the case, it will be possible to use for  $\Phi$  an expansion in a Taylor series in  $\xi$  and y for a region near the origin  $\xi = y = 0$ .

On the other hand, the characteristic directions for the differential equation on  $\Psi$  are flatter than the boundary,  $\phi_S > \tilde{\phi}$ . The differential equation does therefore not apply at  $\phi = \phi_S$ , and the solutions  $\overline{\Psi}$  for  $\phi > \phi_S$ , and  $\overline{\overline{\Psi}}$  for  $\overline{\phi} < \phi < \phi_S$  are not fully defined by prescriptions on  $\phi = \pi$  and  $\phi = \overline{\phi}$ . The two functions  $\overline{\Psi}$  and  $\overline{\Psi}$  must, however, lead to

values of stress and velocities which satisfy momentum considerations at  $\phi = \phi_S$ , which furnish additional conditions for their determination. While at least some of the derivatives of  $\overline{\Psi}$  and  $\overline{\overline{\Psi}}$  at  $\phi = \overline{\phi}_S$  will not be continuous, each of these potentials in its region will be continuous, and each of the potentials  $\overline{\Psi}$  and  $\overline{\overline{\Psi}}$  can again be expanded in a Taylor series.

The functions  $\Phi$ ,  $\overline{\Psi}$  and  $\overline{\overline{\Psi}}$  are therefore subject to the conditions listed below. On the surface the normal and tangential stresses are prescribed. Thus, for an exponentially decaying surface load, the stresses are

 $at y = 0, \xi < 0$ 

$$\frac{\sigma_{y}}{k} = -\frac{P_{o}}{k} e^{\mu\xi} \qquad (\mu > 0)$$
 (46)

$$\frac{\tau}{k} = 0 \tag{47}$$

At the plastic front  $\phi = \overline{\phi}$  conservation of momentum requires

 $at \phi = \tilde{\phi}$ 

$$\frac{\Delta J_1}{k} = \frac{3\rho \bar{c}}{k} \Delta \dot{u}_N \tag{48}$$

$$\frac{\Delta \tau}{k} = 0 \tag{49}$$

$$\Delta \sigma_{\rm N} = \Delta \sigma_{\rm T} = \Delta \sigma_{\rm z} = \overline{\Delta \sigma} = \frac{1}{3} \Delta J_{\rm 1}$$
 (50)

where  $J_1$  is the invariant

$$J_1 = \sigma_x + \sigma_y + \sigma_z \tag{51}$$

and where the symbol  $\Delta$  indicates the jump in stress, or velocity at a front of discontinuity and where  $\overline{c}$  and  $\overline{\phi}$  are given by Eqs. (9) and (10), respectively. Moreover, energy considerations require that the signs of  $\overline{\Delta\sigma}$  and of the total normal stress  $\sigma_N$  at  $\overline{\phi}$  are equal.

Due to the fact that different expressions  $\overline{\Psi}$  and  $\overline{\overline{\Psi}}$  for the solution of the second of Eqs. (33) will be used, it is necessary to consider conditions at the location  $\phi = \phi_S$ . Momentum considerations require that discontinuities in the shear stress  $\tau_N$  and the tangential component of the velocity  $\dot{u}_T$  are proportional

at  $\phi = \phi_S$ 

$$\Delta \tau_{\rm N} = \rho \, c_{\rm S} \, \Delta \dot{u}_{\rm T} \tag{52}$$

while all the normal and tangential stresses and the normal velocity at  $\phi = \phi_S$  must be continuous

at  $\phi = \phi_S$ 

$$\Delta \sigma_{\rm N} = 0 \tag{53}$$

$$\Delta \sigma_{\tau} = 0 \tag{54}$$

$$\Delta \sigma_{-} = 0 \tag{55}$$

$$\Delta \dot{u}_{y} = 0 \tag{56}$$

In the assumed approximate solution, the plastic shock propagates into a region which has been previously stressed by the passage of the P-front. In this region,  $\phi_{\rm F} < \phi < \bar{\phi}$ , the stresses are uniform and just at the yield limit. Their values are:

for  $\phi_P < \phi < \overline{\phi}$ 

$$\frac{\sigma_{\rm x}}{k} = \frac{-\sqrt{3} (1-\nu)}{1-2\nu} \left[1 - 2 \sin^2 \phi_{\rm S} \cot^2 \phi_{\rm P}\right]$$
(57)

$$\frac{\sigma_{y}}{k} = \frac{-\sqrt{3} (1-\nu)}{1-2\nu} \cos 2\phi_{s}$$
 (58)

$$\frac{\tau_{xy}}{k} = \frac{2\sqrt{3} (1-\nu)}{1-2\nu} \sin^2 \phi_S \cot \phi_P$$
 (59)

$$\frac{\sigma_z}{k} = \frac{-\sqrt{3}}{2} \sin 2\phi_p \tag{60}$$

The above equations complete the available conditions for the determination of the potentials  $\Phi$ ,  $\overline{\Psi}$  and  $\overline{\Psi}$ . After the potentials are obtained the arbitrary function  $f_0(y)$ appearing in Eq. (40) can be obtained from Eq. (50). The arbitrary functions  $g_1(y)$  and  $g_2(y)$  in Eqs. (35) and (36) are defined by the fact that displacements at the plastic front may be computed from the velocities in the region between  $\phi_p$  and  $\overline{\phi}$ , using the relations:

for 
$$\phi_p < \phi < \overline{\phi}$$

$$u = -\frac{\dot{u}}{v} \left(\xi + y \cot \phi_{p}\right) \tag{61}$$

$$v = -\frac{\dot{v}}{v} (\xi + y \cot \phi_p)$$
 (62)

## SECTION III

## SOLUTION OF THE DIFFERENTIAL EQUATIONS BY TAYLOR SERIES

The differential equations for the potentials to be solved are

.

$$\Phi_{yy} - (M^2 - 1) \Phi_{\xi\zeta} = 0$$
 (63)

$$\overline{\Psi}_{yy} - (M_{S}^{2} - 1) \overline{\Psi}_{\xi\xi} = 0$$

$$\overline{\Psi}_{yy} - (M_{S}^{2} - 1) \overline{\Psi}_{\xi\xi} = 0$$

$$(64)$$

(67)

The boundary conditions, Eqs. (46-47) on the surface give

$$(M_{S}^{2} - 2) \Phi_{\xi\xi} + 2\overline{\Psi}_{\xiy} = -\frac{P_{o}}{G} e^{\mu\xi}$$
(65)  
$$2\Phi_{\xiy} - (M_{S}^{2} - 2) \overline{\Psi}_{\xi\xi} = 0$$
(66)

While the conditions, Eqs. (48-50) at the plastic front give three equations

$$\frac{\text{at } y = \xi \ \text{tan } \overline{\phi}}{\frac{G}{k} \left\{ (M^2 - 1) \ \phi_{\xi\xi} + \cot \ \overline{\phi} \ [\psi_{\xi y} + \overline{\Psi}_{\xi\xi}] + \overline{\Psi}_{\xi y} \right\} = \\ = -\frac{\sqrt{3}}{2} + \frac{1}{2} \ \sqrt{\frac{1-\nu}{1+\nu}} \cos \ (\overline{\phi} - \phi_p)$$

$$\frac{G}{k} \{ (M^2 - 2) \sin 2\bar{\phi} \, \phi_{\xi\xi} + 2 \cos 2\bar{\phi} \, \phi_{\xiy} + 2 \sin 2\bar{\phi} \, \bar{\Psi}_{\xiy} - (M_S^2 - 2) \cos 2\bar{\phi} \, \bar{\Psi}_{\xi\xi} \} = 0$$
(68)

$$\frac{G}{k} \left\{ (M^2 - 2) \cos 2\overline{\phi} \, \phi_{\xi\xi} - 2 \sin 2\overline{\phi} \, \phi_{\xiy} + 2 \cos 2\overline{\phi} \, \overline{\Psi}_{\xiy} + \right\}$$

+ 
$$(M_{S}^{2} - 2) \sin 2\bar{\phi} \bar{\Psi}_{\xi\xi}$$
 =  $-\frac{\sqrt{3}}{2} \cos 2(\bar{\phi} - \phi_{p})$  (69)

Finally, the five conditions, Eqs. (52-56) at the S-front lead to only one condition on  $\overline{\Psi}$  and  $\widetilde{\widetilde{\Psi}}$ 

at  $y = \xi \tan \phi_S$ 

$$(\bar{\Psi}_{\xi\xi} - \bar{\Psi}_{\xi\xi}) + \tan \phi_{S}(\bar{\Psi}_{\xiy} - \bar{\Psi}_{\xiy}) = 0$$
 (70)

The surface load is expanded in a series in  $\boldsymbol{\xi}$ 

$$p_{o} e^{\mu\xi} = p_{o} \sum_{m=0}^{\infty} \frac{1}{m!} \mu^{m} \xi^{m}$$
 (71)

applicable for  $\xi$  < 0, while the potentials  $\Phi,~\bar{\Psi}$  and  $\bar{\bar{\Psi}}$  are expanded in double series

$$\frac{G}{k} \begin{bmatrix} \phi \\ \overline{\Psi} \\ \overline{\Psi} \end{bmatrix} = \sum_{i,j} \begin{bmatrix} a_{i,\ell} \\ b_{i,\ell} \\ c_{i,\ell} \end{bmatrix} \xi^{i} y^{\ell}$$
(72)

The differential equations and the conditions, Eqs. (46-56) are homogeneous, i.e., they contain consistently only second derivatives of  $\Phi$ ,  $\overline{\Psi}$  and  $\overline{\overline{\Psi}}$  with respect to  $\xi$  and y.
Substitution of Eqs. (72) into Eqs. (63), (64) and (66-70) results therefore in linear equations for the values  $a_{i,\ell}$ ,  $b_{i,\ell}$ ,  $c_{i,\ell}$  which couple only those terms with indices  $m = i+\ell-2$ . The potentials can therefore be conveniently written as a series of polynomials. Each set of polynomials of class m can be determined independently from the polynomials for a different value of m.

$$\frac{G\Phi}{k} = \sum_{m=0}^{\infty} \Phi^{(m)} \qquad \Phi^{(m)} = \sum_{i=0}^{m+2} a_i^{(m)} \xi^i y^{m+2-i}$$
(73)

$$\frac{G\overline{\Psi}}{k} = \sum_{m=0}^{\infty} \overline{\Psi}^{(m)} \qquad \qquad \overline{\Psi}^{(m)} = \sum_{i=0}^{m+2} b_i^{(m)} \xi^i y^{m+2-i} \qquad (74)$$

The case m = 0 corresponds to the step load and, while quite simple, is treated differently, see Appendix I. For each value  $m \ge 1$  there are (3m + 9) unknown coefficients  $a_{1}^{(m)}, h_{1}^{(m)}, c_{1}^{(m)}$ . Substituting the second derivatives of Eqs. (73-75) into the conditions on the boundaries of the regions, Eqs. (65-70), yields six equations for each value  $m \ge 1$ :

$$(M_{S}^{2} - 2)(m + 2)(m + 1) a_{m+2} + 2(m + 1) c_{m+1} = -\frac{p_{o} \mu^{m}}{k m!}$$
 (76)

$$2(m + 1) a_{m+1} - (M_S^2 - 2)(m + 2)(m + 1) c_{m+2} = 0$$
(77)

$$\sum_{i=1}^{m+2} (b_{j} - c_{j}) j (\tan \phi_{s})^{m+2-j} = 0$$
 (78)

The superscripts used in Eqs. (73-75) have been omitted for simplicity.

$$(m + 1)(m + 2)[(M2 - 1) a_{m+2} + \cot \bar{\phi} b_{m+2}] + + (m + 1)(\tan \bar{\phi})^{m} [\cot \bar{\phi} a_{1} + b_{1}] + + \sum_{j=2}^{m+1} (m + 3 - j)(\tan \bar{\phi})^{j-1} [[(m + 2 - j)(M2 - 1) + + (j - 1) \cot^{2} \bar{\phi}] a_{m+3-j} + [(m + 2 - j) \cot \bar{\phi} + + (j - 1) \cot \bar{\phi}] b_{m+3-j}] = 0$$
(79)

$$(m + 2)(m + 1)[N_{5}a_{m+2} + N_{8}b_{m+2}] + (m + 1)(\tan \bar{\phi})^{m}[N_{6}a_{1} \div N_{7}b_{1}] + + \sum_{j=2}^{m+1}(m + 3 - j)(\tan \bar{\phi})^{j-1} \{[(m + 2 - j) N_{5} + + (j - 1) \cot \bar{\phi} N_{6}]a_{m+3-j} + [(m + 2 - j) N_{8} + + (j - 1) \cot \bar{\phi} N_{7}]b_{m+3-j}\} = 0$$
(80)

$$(m + 2)(m + 1)[N_{9}a_{m+2} + N_{10}b_{m+2}] + (m + 1)(\tan \bar{\phi})^{m}[N_{7}a_{1} - N_{6}b_{1}] + + \sum_{j=2}^{m+1}(m + 3 - j)(\tan \bar{\phi})^{j-1} \{[(m + 2 - j) N_{9} + + (j - 1) N_{7} \cot \bar{\phi}] a_{m+3-j} + [(m + 2 - j) N_{10} - . - (j - 1) N_{6} \cot \bar{\phi}] b_{m+3-j}\} = 0$$
(81)

where

÷,

$$N_{1} = N_{S}^{2} - 2 + \sin^{2}\bar{\phi} (4 - 2N^{2} - M_{S}^{2})$$

$$N_{2} = -(\frac{M_{S}^{2} - 4}{2}) \sin 2\bar{\phi}$$

$$N_{3} = 2 + (M_{S}^{2} - 4) \sin^{2}\bar{\phi}$$

$$N_{4} = (\frac{3N_{S}^{2} - 4}{2}) \sin 2\bar{\phi}$$

$$N_{5} = (M^{2} - 2) \sin 2\bar{\phi}$$

$$N_{6} = 2 \cos 2\bar{\phi}$$

$$N_{7} = 2 \sin 2\bar{\phi}$$

$$N_{8} = -(M_{S}^{2} - 2) \cos 2\bar{\phi}$$

$$N_{9} = 2[\cos 2\bar{\phi} + (M_{S}^{2} - M^{2})(\frac{1 + 2\alpha\sqrt{3}}{2 + \alpha\sqrt{3}}) - \frac{1}{2}M_{S}^{2} + M^{2} \sin^{2}\bar{\phi}]$$

$$N_{10} = -(M_{S}^{2} - 2) \sin 2\bar{\phi}$$
(82)

Substituting Eqs. (73-75) into the wave equations, Eqs. (63-64), and equating coefficients of like powers of  $\xi$  and y, yields (3m + 3) recurrence equations

28

t

$$a_{m-2q+2} = (M^{2} - 1)^{q} a_{m+2} \prod_{\ell=1}^{q} P_{m,\ell}$$

$$a_{m-2q+1} = (M^{2} - 1)^{q} a_{m+1} \delta_{2q-2,m} \prod_{\ell=1}^{q} \bar{P}_{m,\ell}$$

$$b_{m-2q+2} = (M_{S}^{2} - 1)^{q} b_{m+2} \prod_{\ell=1}^{q} P_{m,\ell}$$

$$b_{m-2q+1} = (M_{S}^{2} - 1)^{q} b_{m+1} \delta_{2q-2,m} \prod_{\ell=1}^{q} \bar{P}_{m,\ell}$$

$$c_{m-2q+2} = (M_{S}^{2} - 1)^{q} c_{m+2} \prod_{\ell=1}^{q} P_{m,\ell}$$

$$c_{m-2q+1} = (M_{S}^{2} - 1)^{q} c_{m+1} \delta_{2q-2,m} \prod_{\ell=1}^{q} \bar{P}_{m,\ell}$$
(83)

where

$$P_{m,\ell} = \frac{(m + 3 - 2\ell)(m + 4 - 2\ell)}{2\ell(2\ell - 1)}$$

$$\vec{P}_{m,\ell} = \frac{(m + 2 - 2\ell)(m + 3 - 2\ell)}{2\ell(2\ell + 1)}$$

$$\delta_{2q-2,m} = \frac{1 \text{ if } 2q - 2 \neq m}{0 \text{ if } 2q - 2 = m}$$

$$1 \leq q \leq \frac{2m + 3 + (-1)^{m}}{4}$$
(84)

Equations (76-81) and Eqs. (83) give the required number of (3m + 9) equations for the (3m + 9) unknown coefficients  $a_i$ ,  $b_i$  and  $c_i$ .

29

.

Substitution of Eqs. (83) into Eqs. (76) to (81) reduces the system to a set of six linear, nonhomogeneous, simultaneous equations, involving only the unknowns  $a_{m+2}$ ,  $a_{m+1}$ ,  $b_{m+2}$ ,  $b_{m+1}$ ,  $c_{m+2}$ .  $c_{m+1}$ . After solving for these values, the stresses, velocities and displacements for each of the m components of the surface load may be computed at any location ( $\xi$ ,y) behind the front at  $\overline{\phi}$ .

t

#### SECTION IV

#### NUMERICAL RESULTS AND DISCUSSION

Numerical results from the relations derived in the previous section were obtained on a digital computer, truncating the series solution by retaining terms up to and including m = 7. Retention of terms m > 7 would have required the use of double precision, in spite of the fact that the computer employed carries 14 digits. The stresses found are presented in Tables II to XXVIII and in the ac-companying figures, for all combinations of the velocity ratios  $V/c_p = 1.5$ , 2.0, 4.0 and of Poisson's ratio v = 0.15, 0.25, 0.35, and for three peak values of surface loading. The values of  $P_0/k$  are selected to permit interpolation and extrapolation.

The approximation employed restricts the applicability of the approximate solutions to distances from the front of the applied load where the ratio n, Eq. (11), exceeds unity only moderately. To check this matter, the Tables indicate the value n for all points where stresses are listed. Truncation of the series further limits the validity of the results to points where  $|\mu\xi| < 1.7$  and only such points are listed. Finally, the range of applicability of the present solution is limited by the fact that the approximate results can only be accepted as a reasonable approximation in the

range where the shock is compressive. The tables have been restricted in range such that this requirement is never seriously violated.

For each set of values v and V/c<sub>p</sub> considered, results for three levels of the load  $p_0/k$  are given. For values of  $p_0/k$  below the minimum considered, the elastic solution presented in Appendix II may be used, because this will generally result only in a very slight violation of the yield condition. For values  $p_0/k$  between the lowest and highest values given in the tables, interpolation between the three values given can be used without serious error, except at point (1<sup>\*</sup>). For values  $p_0/k$  which exceed the highest value, max( $p_0/k$ ) considered, the principal stresses at all points, except at point (1<sup>\*</sup>) can be obtained by using the results  $\sigma_i$  for the respective highest value of  $p_0/k$ , and adding the increment

$$\sigma_{i}^{(in)} = \max(p_{o}/k) - p_{o}/k$$
(85)

to each value  $\sigma_i$  in the table applicable for the value  $\max(p_o/k)$ . The increment  $\sigma_i^{(in)}$  is inherently negative, i.e., compressive. Stresses at point (1<sup>\*</sup>) are always those shown in the tables for all values  $p_o/k$  above the minimum considered.

### 1. Discussion of typical results

The results for  $V/c_p = 2.0$ , v = 0.25 for the three loads  $p_0/k = 4.0$ , 6.0 and 10.0 are discussed as typical.

The principal stresses  $\sigma_1/k$ ,  $\sigma_2/k$ ,  $\sigma_3/k$ , the angle  $\theta$ between the direction of  $\sigma_1$  and the  $\zeta$ -axis, and the values of n indicating violation of the yield condition are tabulated at fourteen points on a rectangular grid in the  $\xi$ -y plane. The results for these cases are given in Tables XIV - XVI. In every table point I has three sets of stresses because the stress field there has a directional singularity, i.e., the values depend on the direction of approach  $\phi$ , and the results differ depending on whether  $\phi_{\rm p}$  <  $\phi$  <  $\bar{\phi}$ ,  $\bar{\phi}$  <  $\phi$  <  $\phi_{\rm S}$  or  $\phi_c < \phi < \pi$ . The three sets of values at point 1 immediately behind the front of the applied load are equal to those due to a step load without decay. In each of these three tables the yield violation at point 1 is the same, n = 1.056. The yield violations for a step wave, for a range of the parameters  $V/c_r$ , v and p /k are shown in Fig. 9. For each combination of  $V/c_p$  and v there is a limiting load, above which the degree of violation, n, remains constant. This is due to the fact that the effect of any higher value of p\_/k results only in a jump in the stress invariant  $J_1$  at  $\phi = \overline{\phi}$ , a matter which does not affect the von Mises yield condition.

In order to judge the seriousness of the yield violation at point 1, n = 1.056, Table I gives the exact values of the stresses  $\sigma_i/k$  and of the angle  $\theta$ , for a load of  $p_0/k = 4.41$ , as obtained in Ref. [1].





34

t

TABLE	Ia	<b>v</b> :	=	0.25,	V/c <sub>p</sub>	-	2.0,	<sup>p</sup> o	8	4.41k
		(E)	хa	et Str	esses	:)				

Location	-σ <sub>1</sub> /k	- 7 <sub>2</sub> /k	$-\sigma_3/k$	θ
$\phi_{p} < \phi < \phi_{1}$ $\phi_{2} < \phi < \phi_{S}$ $\phi_{S} < \phi < \phi_{3}$ $\phi_{3} < \phi < \pi$	2.598	0.866	0.866	60.00 <sup>0</sup>
	4.20	2.47	2.47	67.46 <sup>0</sup>
	4.20	2.47	2.47	78.98 <sup>0</sup>
	4.41	2.63	2.73	90.00 <sup>0</sup>

The comparable stresses in the approximate solution for  $p_0 = 4.41k$  are

TABLE Ib

v = 0.25,  $V/c_p = 2.0$ ,  $p_o = 4.41k$ (Approximate Stresses)

Location	-σ <sub>1</sub> /k	$-\sigma_2/k$	- <sub>3</sub> /k	θ
$\phi_{p} < \phi < \overline{\phi}$ $\overline{\phi} < \phi < \phi_{S}$ $\phi_{S} < \phi < \phi$	2.598	0.866	0.866	60.00°
	4.345	2.613	2.613	60.00°
	4.41	2.549	2.549	90.00°

The differences in the principal stresses in the two tables are not large, the maximum being 7%. While the values  $\theta$  listed in Table Ia agree with those in Table Ib, it is noted that in the exact case the value  $\theta$  varies between  $\phi_1 < \phi < \phi_2$  from  $60.00^\circ$  to  $67.46^\circ$  and between  $\phi_3 < \phi < \phi_4$  from  $78.98^\circ$  to  $90.00^\circ$ . In the approximate



PRINCIPAL STRESS  $\frac{61}{k}$  AT  $\overline{\phi}$ FOR  $\sqrt{4}$  0.15  $\frac{\sqrt{6}}{c_{p}}$ = 1.50 FIG. 10



TABLE II

RESULTS FOR v = 0.150 V/c<sub>p</sub> = 1.5 p<sub>o</sub> = 4.0k

37

-1.580

-1.395

-1.249

-0.576

-1.580

-1.718

-1.591

~1.351

48.195

89.200

88.846

90.000

1.000

1.269

1.278

0.390

Δτ = 1.357 k

At

φ<sup>+</sup>s

-0.299

-0.199

-0.299

-1.500

For  $\phi_{\mathbf{p}} < \phi < \dot{\phi}$ 

For  $\overline{\phi} < \phi < \phi_S$ 

For  $\phi_S < \phi \leq \pi$ 

0.150

0.094

0.141

0.000

-3.313

-3.737

-3.615

-J.890

8 9 1C 11\*\*\*\* 12\*\*\* 13

## TABLE III

RESULTS FOR v = 0.150,  $V/c_p = 1.5$ ,  $p_o = 6.0k$ 



Pt.	μξ	μу	σ <sub>l</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ°	n
1*	0.000	0.000	-2.103	-0.371	-0.371	48.189	1.000
1**	0.000	0.000	-5.720	-3.987	-3.987	48.189	1.000
<u>1***</u>	0.000	0.000	-6.000	-3.707	-3.987	90:000	1.250
2	-0.059	0.000	-5.651	-3.622	-3.922	90.000	1.094
3	-0.119	0.000	-5.321	-3.538	-3.860	90.000	0.950
4	-0.179	0.000	-5.012	-3•456	-3.802	90.000	0.817
5	-r 059	0.030	-5.591	-3.859	-3.859	48.189	1.000
6	-0.119	0.030	-5.547	-3.479	-3.796	89.630	1.113
7	-0.179	0.030	-5,223	-3.401	-3.735	89.668	0.970
8	-0.119	0.060	-5.456	-3.733	-3.733	48.199	1.000
9	-0.179	0.060	-5.447	-3.340	-3.671	89.278	1.132
10	-0.179	0.090	-5•344	-3.611	-3.611	48•198	1.000
11****	<b>~0</b> •119	0.056	-5.759	-3.421	-3.741	89.262	1.267
12****	-0.179	0.085	-5.644	-3.284	-3.622	88.923	1.276
13	-1.500	0.000	-2.010	-1.335	-3.033	90.000	0.855

\* For 
$$\phi_{p} < \phi < \overline{\phi}$$
  
\*\* For  $\overline{\phi} < \phi < \phi_{S}$   
\*\*\* For  $\phi_{S} < \phi \leq \pi$   
\*\*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 1.357k$ 

ł



Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θο	n
1*	0.000	0.000	-2.103	-0.371	-0.371	48•189	1.000
1**	0.000	0.000	-9.720	-7.987	-7.987	48.189	1.000
1***	0.000	0.000	-10.000	-7.707	-7.987	90.000	1.250
2	-0.039	0.000	-9.608	-7.612	-7.914	90.000	1.075
3	-0.080	0.000	-9.231	-7.518	-7.844	90.000	0.909
4	-0.119	0.000	-8.869	-7.425	-7.776	90.000	0.753
5	-0.039	0.020	-9.576	-7.844	-7.844	48.189	1.000
6	-0.080	0.020	-9.490	-7.451	-7.772	89.552	1.096
7	-0.119	0.020	-9.118	-7.361	-7.703	89.550	0.931
8	-0.080	0.040	-9.436	-7.702	-7.702	48.205	1.001
9	-0.119	0.040	-9.375	-7.292	-7-632	89.126	1.117
10	-0.119	0.060	-9.298	-7.564	-7.564	48.205	1.000
11****	-0.080	0.037	-9.729	-7.387	-7.711	89.173	1.269
12****	-0.119	0.056	-9.599	-7.230	-7.576	88.787	1.279

¥	For	$\phi_{\mathbf{P}}$	<	φ	<	φ
**	For	$\overline{\Phi}$	<	φ	<	φs
***	For	<sup>φ</sup> s	<	φ	<u>&lt;</u>	π
****	At	φ <sup>+</sup> s				

 $\Delta \tau = 1.357k$ 

TABLE IV

RESULTS FOR v = 0.150,  $V/c_{P} = 1.5$ ,  $p_{o} = 10.0k$ 







Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ°	n
1*	0.000	0.000	-2.103	-0.371	-0.371	60 000	1 000
1**	0.000	0.000	-2-859	=1.127	-1.107	60.000	1.000
1***	0.000	0.000	-3.000		-1+127	60.000	1.000
2	-0.281	0.000	-2.000		-1+12/	60.000	1.124
2		0.000	-2.266	-0.783	-0•986	90.000	0.804
5	-0+561	000+0	-1.712	-0.605	-0.877	90.000	0.577
4	-0.842	0.000	-1.293	-0.448	-0.790	90.000	0.0011
:	-0.281	0.100	-2.600	-()-868	-0.969		0.425
6	-0.561	0.100	=2.048	-0.576	~0.000	60.000	1.000
7	=0.842	0.100	-1 640	-0.576	-0.742	91+690	0.806
8	-0.541	0.100	-1.940	-0.425	-0.643	92.970	0.591
0	-0.561	0.200	-2.367	-0.635	-0.635	60.000	1.000
>	-0.842	0•200	-1.855	-0.387	-0.521	93.180	0.912
10	<del>~</del> 0•842	0.300	-2.157	-0.425	-0.425	50 000	0.012
11****	-0.561	0.190	-2.430	-0.521		00.000	1.000
12****	-0.842	0.285	-2.100	-0.991	-0∙044	91.330	1.065
		V # 2 0 9	2 4 1 90	-0.337	-0.438	922000	1.060

\* For 
$$\phi_{P} < \phi < \overline{\phi}$$
  
\*\* For  $\overline{\phi} < \phi < \phi_{S}$   
\*\*\* For  $\phi_{S} < \phi \leq \pi$   
\*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 0.944 \text{ k}$ 

.

TABLE VI

RESULTS FOR v = 0.150,  $V/c_p = 2.0$ ,  $p_o = 6.0k$ 



Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ°	n
1*	0.000	0.000	-2.103	-0.371	-0.371	60.000	1.000
1**	0.000	0.000	-5.859	-4.127	-4.127	60.000	1.000
1***	0.000	0.000	-6.000	-3.986	-4.127	90.000	1.124
2	-1.122	0.000	-1.953	-2.630	-3.317	90.000	0.682
3	-1.403	0.000	-1.474	-2.377	-3.201	90.000	0.867
4	=1.683	0.000	-1.107	-2.148	-3+117	90.000	1 006
5	=1.122	0.400	-4.078	-2.345	-2.345	60.000	1.000
6	-1.403	0.400	-3.118	-2.071	-2.160	106.660	6.580
7	-1.683	0.400	-2.516	-1.707	-2.016	127.046	0.408
8	-1.403	0.500	-3.736	-2.005	-2.005	60.000	1.000
Q	-1.683	0.500	-2.865	-1.766	-1.838	108.970	0.615
ió	m1.683	0.600	-3.430	-1.698	-1.698	60.000	1.000
114444	-1-403	0.475	-3.584	-2.010	-2.040	97.520	0.900
12****	-1.683	0.570	-3.249	-1.720	-1.736	99.080	0.879

\* For 
$$\phi_{P} < \phi < \overline{\phi}$$
  
\*\* For  $\overline{\phi} < \phi < \phi_{S}$   
\*\*\* For  $\phi_{S} < \phi \leq \pi$   
\*\*\* At  $\phi_{S}^{+}$   
 $\Delta T = 0.944 k$ 

42

ï



TABLE VII

*	For	Φ <sub>P</sub>	<	φ	<	φ
**	For	φ	<	φ	<	¢s
***	For	φ <sub>s</sub>	<	ф	<u>&lt;</u>	π
***	At	φ <sup>+</sup> s				

∆t = 0.944k



PRINCIPAL STRESS  $\frac{6}{k}$  AT  $\overline{\phi}$ FOR  $\sqrt{2} = 0.15$   $\frac{1}{2}$   $\frac{1}{2}$  FIG. 12



TALLE VIII

\* For  $\phi_P < \phi < \overline{\phi}$ \*\* For  $\overline{\phi} < \phi < \phi_S$ \*\*\* For  $\phi_S < \phi < \phi_S$ \*\*\* At  $\phi_S^+$ 

 $\Delta \tau = 0.442k$ 



TABLE IX

**	For	₽	<	φ	<	¢s
4 <del>4</del> <del>4</del>	For	φ <sub>s</sub>	<	ф	<u>&lt;</u>	π
****	At	¢ <sup>+</sup> s				

 $\Delta \tau = 0.442k$ 

46

A : 116



TABLE X RESULTS FOR v = v.150 V/c<sub>p</sub> = 4.0 p<sub>o</sub> = 10.0k

1*	0.000	0.000	-2.103	-0.371	-0.371	75•52U	1.000
1**	0.000	0.000	-9.968	-8.236	-8.236	90.000	1.000
<u>1***</u>	0.000	0.000	-13.000	-8.204	-8.236	90.000	1.028
2	-0.117	0.000	-0,092	-7.883	-8.022	90.000	0.547
3	-0.235	0.000	-/.906	-7.584	-7.829	90±000	L.16H
4	-0.352	0.000	-1.305	-7.030	-7.656	90.000	، ا د س
5	-0.117	0.020	-9.626	-7.894	-7.894	75.520	1.000
6	-0.235	0:020	-8.586	-7.558	-7.688	107.500	U.56U
7	-0.352	C.020	-7.765	-7.145	-7.503	126.460	0.311
8	-0.235	0.040	<b>~9</b> •292	-7.568	-7.568	75.520	1.000
9	-0.352	0.040	-8.441	-7.099	-7.370	119.720	0.710
10	-0.352	0.060	-8.976	-7.252	-7.252	75.520	1.000
11****	-0.235	0.038	-9.269	-7.523	~7.575	109.480	1.004
12****	-0.352	0.057	-9.058	-7.072	-7.264	117,250	1.095
13	-0.650	0.000	-6.675	-5.220	-7.290	90,000	1.061

 $\Delta \tau = 0.442 \, k$ 



PRINCIPAL STRESS K AT \$ FOR V=0.25 V/Cp= 1.5

FIG. 13

48



\* For  $\phi_{P} < \phi < \overline{\phi}$ \*\* For  $\overline{\phi} < \phi < \phi_{S}$ \*\*\* For  $\phi_{S} < \phi \leq \pi$ \*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 1.223 k$ 

# TABLE XII

RESULTS FOR v = 0.250,  $V/c_p = 1.5$ ,  $p_o = 6.0k$ 



Pt.	μξ	μу	σ <sub>1</sub> /k	$\sigma_2/k$	$\sigma_3/k$	θ°	n
1*	0.000	0.000	-2.598	-0.866	-0.866	48•189	1.000
<u>1**</u>	0.000	0.000	-5.900	-4.168	-4.168	48.189	1.000
<u>1***</u>	0.000	0.000	-6.000	-4.069	-4.168	90.000	1.087
2	-0.174	0.000	-5.038	-3.669	-3.828	90.000	0.748
3	-0.349	0,000	-4.230	-3.316	-3.538	90.000	0.476
4	-0.524	00000	-3.552	-3.005	-3.290	90.000	0.273
5	-0:174	0.100	-5.565	-3.833	-3.833	48.189	1.000
6	-0.349	0.100	-4.867	-3.251	-3.513	86.467	0.867
7	-0.524	0.100	-4.077	-2.952	-3.241	86.432	0.584
8	-0.349	0.200	-5.251	-3.518	-3.518	48.189	1.000
9	-0.524	0.200	-4.731	-2.836	-3.218	83.742	1.002
10	-0.524	0.300	-4.955	-3.223	-3.223	48 189	1.000
11****	-0.349	0.145	-5.208	~3.198	-3.512	85.145	1.081
12****	-0.524	0.218	-4.868	-2.806	-3.217	83.299	1.091
13****	-1.200	0.500	-3.817	-1.542	-2.248	78.788	1.164
14	-1.200	0.000	-2.085	=1.806	-2.624	90.000	0.416

*	For	$\phi_{\mathbf{P}}$	<	ф	<	φ
**	For	φ	<	¢	<	φ <sub>s</sub>
***	For	φ <sub>s</sub>	<	ф	<u>&lt;</u>	π
****	At	φ <mark>+</mark> s				

 $\Delta \tau = 1.223k$ 



 $\Delta \tau = 1.223k$ 

ALL LUCION

4

ŝ



.

RESULTS FOR v = 0.250,  $V/c_p = 2.0$ ,  $p_o = 4.0k$ 

IABLE XIV



Pt.	μξ	џу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θο	n
1*	0.000	0.000	-2.598	-0.866	-0.866	60.000	3.000
- 1**	0.000	0.000	-3.936	2.203	-2.203	60.000	1.000
1***	0.000	0.000	-4.000	-2.139	-2.203	90.000	1.056
2	-0.996	0.000	-1.477	-1.026	-1.294	90.000	0.227
2	-1.245	0.000	-1.151	-0.847	-1.168	90.000	0.181
4	-1.494	0.000	-0.896	-0.693	-1.066	90.000	0.187
5	-0.996	0.400	=2.960	-1.228	-1.228	60.000	1.000
5	-1.245	0.400	=2.502	-0.769	-0.999	54.610	0.941
7	-1,494	0.400	-1.871	-0.574	-0.817	89.640	0.654
, 8	-1.245	0.500	-2.758	-1.026	-1.026	60.000	1.000
0	-1.494	0.500	-2.334	-0.603	-0.814	55.000	0.944
10	-1.494	0.600	-2.572	-0.840	-0.840	60.000	1.000
114444	-1.245	0.375	-2.329	~0.831	-0.997	87.040	0.821
104444	-1.494	0.450	-2.093	-0.640	-0.812	86.950	0.794
12****		0.513	=1.916	-0.496	-0.671	86.990	0.774
14	~1.700	0.000	-0.725	-0.579	-0.995	90.000	0.211

\* For  $\phi_{p} < \phi < \overline{\phi}$ \*\* For  $\overline{\phi} < \phi < \phi_{S}$ \*\*\* For  $\phi_{S} < \phi \leq \pi$ \*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 0.900k$ 



\* For 
$$\phi_{P} < \phi < \overline{\phi}$$
  
\*\* For  $\overline{\phi} < \phi < \phi_{S}$   
\*\*\* For  $\phi_{S} < \phi \leq \pi$   
\*\*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 0.900 k$ 



RESULTS FOR v = 0.250,  $v/c_p = 2.0$ ,  $p_o = 10.0k$ 



Pt.	μξ	μу	$\sigma_1/k$	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ <sup>ο</sup>	n
1*	0.000	0.000	-2.598	-0.866	-0.866	60.000	1.000
1**	0.000	0.000	-9.935	-8.203	-8.203	60.000	1.000
1***	0.000	0.000	-10.000	-8+139	<b>~8</b> •203	90.000	1.056
2	-0.249	0.000	-7.795	-7.241	-7.428	90.000	0.281
3	-0.498	0.000	-6.499	-6.075	-6.812	90.000	0.369
4	-0.747	0.000	-5.879	-4.737	-6.322	90.000	U•817
5	∞0.249	0.100	-9.254	-7.522	-7.522	60.000	1.000
6	-0+498	0.100	-7.301	-6.599	-6.803	86.970	0.361
7	-0.747	0.100	-5.959	5.661	-6.233	84•499	0.286
8	-0.498	0.200	-8.622	-6.890	-6.890	59.992	1.000
9	-0.747	0.200	<del>~</del> 6•869	-5.979	-6.224	83.656	じ・インタ
10	-0.747	0.300	-8.037	-6+305	-6.305	59.993	1.000
11****	-0.498	0.150	-8.048	-6.622	-6.834	84•925	0.769
12****	-0.747	0.225	-7.231	-5.967	-6.236	82•589	0.666
13***	-1.000	0.301	-6.491	-5.365	-5•680	80•473	0.580
14	-1.000	0.000	-5.347	-3.678	-5.925	90.000	1.166

 $\Delta \tau = 0.900 \, k$ 



×



 $\Delta \tau = 0.043 \, k$ 

.

## TABLE XVIII

RESULTS FOR v = 0.250,  $V/c_p = 4.0$ ,  $p_o = 6.0k$ 



Pt.	μξ	μу	$\sigma_1/k$	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ°	ŋ
1*	0.000	0.000	-2.598	-0.866	-0.866	75.522	1.000
<u>1**</u>	0.000	0.000	-5.983	-4.251	-4.251	75.622	1,000
<u>1***</u>	0.000	0.000	-6.000	-4.234	-4.251	90.000	1.014
2	-0.527	0.000	-3.541	-3.203	-3,378	90.000	1.169
3	-1.054	0.000	-2.510	-2.089	-2.842	89,949	0,377
4	-1.581	0.000	-2.024	-1.225	-2.506	90,000	0.645
5	-0.527	0.100	-5.237	-3.505	-3.505	75.522	1.000
6	-1.054	0:100	-3.383	-2.326	-2.747	129.020	0.532
7	-1.581	0+100	-2.516	-1.334	~2.282	56.390	0.625
8	-1.054	0.200	-4.588	-2.857	-2.857	75.526	0,000
9	-1.581	0.200	-3.358	-1.455	-2.199	133,128	0.959
10	-1.581	0.300	-4.026	-2.294	-2.294	75.525	0.000
11****	-1.054	0.153	-4.071	-2.479	-2.777	121.415	0.846
12****	-1.581	0.230	-3.646	-1.563	-2.207	129.772	1.066
13****	-1.700	0.248	-3.575	-1.364	-2.092	130.937	1,124
14	-1.700	0.000	-1.934	-1.087	-2.448	90.000	1.687

÷	For	ψ <sub>₽</sub>	<	ψ	<	ψ
**	For	φ	<	ф	<	φ <sub>s</sub>
***	For	φ <sub>s</sub>	<	φ	<u>&lt;</u>	π
****	At	$\phi_{S}^{+}$				

 $\Delta \tau = 0.043k$ 

•

I



 $\Delta \tau = 0.043k$ 





RESULTS FOR v = 0.350,  $V/c_p = 1.5$ ,  $p_o = 4.0k$ 

TABLE XX

\* For  $\phi_{P} < \phi < \phi$ \*\* For  $\overline{\phi} < \phi < \phi_{S}$ \*\*\* For  $\phi_{S} < \phi \leq \pi$ \*\*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 1.082k$ 

<u>.</u> (


TABLE XXI

 $\Delta \tau = 1.082k$ 

X

ţ

ò

1,

۶

10

2

6

1

62

t



RESULTS FOR v = 0.350,  $V/c_p = 1.5$ ,  $p_o = 10.0k$ 

TABLE XXII

Pt.	μξ	μу	$\sigma_1/k$	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ <sup>0</sup>	n
1*	0.000	0.000	-3.752	-2.020	-2.020	48•189	1.000
1**	0.000	0.000	-10.112	-8.380	-8.380	48.189	1.000
1***	0.000	0.000	-10.000	-8.493	-8.380	90.000	0.904
2	-0.075	0.000	-9.277	-8.035	-7.967	90.000	0.737
3	-0.150	0.000	-8.606	-7.601	-7.582	90.000	0.583
4	-Ue225	0.000	-7.984	-7.208	-7.225	90.000	0.443
5	-0.075	0.050	<b>~9</b> •920	-8.187	-8.187	48.189	1.000
6	-0.150	0.050	-9.234	-7.713	-7.782	84.016	0.858
7	-0.2.5	0.050	-8.565	-7.305	-7.405	83.435	0.700
8	-0.150	0.100	-9.730	-7.997	-7.991	48.188	1.000
9	-0.225	0.100	-9.320	-7.271	-7.600	47.540	1.100
10	-0.225	0.150	-9.544	-7.812	-7.812	48.188	1.000
11****	-0.150	0.050	-9.243	-7.715	-7.785	83.952	0.863
12****	-0.225	0.076	-8.902	-7.339	-7.505	81.298	0.858
13****	-0.300	0.101	-8.580	-6.974	-7.236	78•915	0.851
14	-0.3(1)	0.000	-7.447	-6-825	-6-802	90.000	0 214

\* For  $\phi_{p} < \phi < \overline{\phi}$ \*\* For  $\overline{\phi} < \phi < \phi_{S}$ \*\*\* For  $\phi_{S} < \phi \leq \pi$ \*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 1.082k$ 



PRINCIPAL STRESS  $\frac{6}{1/3}$  AT  $\overline{\phi}$ FOR  $\sqrt{1} = 0.35$   $\sqrt{1}$  Cp = 2.0 FIG. 17

64

I

RESULTS FOR v = 0.350,  $V/c_p = 2.00$ ,  $p_o = 4.0k$ 

TABLE XXIII

•



Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	A O	n
1*	0.000	0.000	-3.752	-2.020	-2.020	60.000	1.000
1**	0.000	0.000	-4.037	-2.305	-2.305	60.000	1.000
<u>1***</u>	0.000	0.000	-4.000	-2.343	-2.305	90.000	U•967
2	-0.109	0.000	-3.585	-2.096	-2.074	90.000	U•866
3	-0.218	0.000	-3.214	-1.874	-1.866	90.000	v•776
4	-0.299	0.000	-2.964	-1.723	-1.726	90.000	0.715
5	-0.109	0.050	-3.944	-2.212	-2.212	60.000	1.000
6	-0.218	0.050	-3.530	-1.980	-1.986	88.108	0.893
7	-0.299	0.050	-3.254	-1.820	-1.833	88.213	0.823
8	-0.218	0.100	-3.852	-2.120	-2.120	59.997	1.000
9	-0.299	0.100	-3.638	-1.861	-1.954	58.253	1.000
10	-0.299	0.137	-3.786	-2.054	-2.054	59.517	1.000
11****	-0.218	0.054	-3.557	-1.988	-1.996	87.938	J.903
12****	-0-299	0.074	-3.408	-1.866	-1.890	87.218	0.883
13****	-1.50Ŭ	0.371	-1.836	-0.522	-0.717	79.975	0.708
14	-1,500	0.000	-0.890	-0.401	-0.537	90.000	0.252



 $\Delta \tau = 0.847 \text{ k}$ 

I





ь,





TABLE XXVI

Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	θ	n
1*	0.000	0.000	-3.752	-2.020	-2.020	75.522	1.000
1**	0.000	0.000	-5.005	-3.273	-3.273	75.522	1.000
1444	0.000	0.000	-5.000	-3.278	-3.273	90.000	0.995
2000	-0.470	0.000	-3-124	-2.189	-2.235	90.000	0.526
2	-0.940	0.000	-1.952	-1.483	-1.578	90.000	0.247
2	-1.410	0.000	-1-218	-1.016	-1.158	90.000	0.103
4		0.100	-4.583	-2.851	-2:851	75.522	1.000
5	<b>⊷</b> 0•470	0.100		-1.859	-1.897	98.950	0.553
6	-0.940	0.100	-20040	-1,180	-1.294	110.612	0.332
7	-1.410	0.100	-1.004	-2 463	-2-463	75-521	6.995
8	-0.940	0.200	-43194	-2.405	-2.403	72.550	(1.537
9	-1.410	0.200	-2.534	-1.020		75.571	0.009
10	-1.410	0.300	-3.838	-2.105	-2.100	100 276	0 603
11****	-0.940	0.113	-2.993	-1.938	-1.958	70.310	0 614
12****	-1.410	0.170	-2.339	-1+418	<b>-1</b> ≉481	100+198	00274

\* For  $\phi_{P} < \phi < \overline{\phi}$ \*\* For  $\overline{\phi} < \phi < \phi_{S}$ \*\*\* For  $\phi_{S} < \phi \leq \pi$ \*\*\* At  $\phi_{S}^{+}$  $\Delta \tau = 0.431k$ 

# TABLE XXVII

RESULTS FOR v = 0.350,  $v/c_p = 4.0$ ,  $p_o = 7.0k$ 



Pt.	μξ	μу	σ <sub>1</sub> /k	σ <sub>2</sub> /k	σ <sub>3</sub> /k	6 °	n
1*	0.000	0.000	-3.752	-2.020	-2.020	75.522	1.000
144	0.000	0.000	-7.005	-5.273	-5.273	75.522	1.000
1444	0.000	0.000	-7.000	-5.278	-5.273	90.000	0.995
2	000470	0.000	-4.374	-3.754	-3.820	90.000	0.340
2		0.000	=2.765	-2.732	-2.900	89•999	0.088
5	-1-410	0.000	-2.112	-1.705	-2.311	89•999	0:309
4 c	-10,470	0.100	-6.414	-4.682	-4.682	75.522	1.000
2	-0+470	0.100	-4.009	-3.273	-3.347	107.300	0.405
5	-0.940	03100	-7.722	-2.145	-2.502	46.569	0.290
7	-1.410	0.100	-6 070	-20242	-4.139	75.521	0.999
8	-0.940	0.200	-2.870			71.232	0.354
9	-1.410	0.200	-3.54/	-2.958	•2•722	110626	0 000
10	<b>-1</b> •410	0.300	-5.371	-3.639	-3.639	12+221	0 170
11****	-0.940	0.113	-4.217	-3.376	-3.433	105+202	0.410
12****	-1.410	0.170	-3.373	-2•575	<b>-2</b> •764	119.950	0.417

\* For 
$$\phi_{p} < \phi < \overline{\phi}$$
  
\*\* For  $\overline{\phi} < \phi < \phi_{S}$   
\*\*\* For  $\phi_{S} < \phi \leq \pi$   
\*\*\*\* At  $\phi_{S}^{+}$ 

 $\Delta \tau = 0.431 k$ 

t



 $\Delta \tau = 0.431 k$ 

case the value  $\theta$  stays at 60.00° for  $\phi_{\rm p}$  <  $\phi$  <  $\phi_{\rm S}$  and at 90.00° for  $\phi_{\rm S}$  <  $\phi$  <  $\pi$  .

Looking at results for other grid points it is seen that at point 10 in Table XIV the plastic shock has reached a small tensile value, indicating that the requirement of compressive shocks is violated from there on.

For the higher loads  $p_0/k = 6.0$  and 10.0, Tables XV, XVI, the shock remains compressive in the entire range of the tables. Table XV for  $p_0/k = 6.0$  is limited only by the condition  $\mu\xi \ge -1.7$  due to the truncation of the expansions. For the highest load  $p_0/k = 10.0$ , the validity is limited to  $\mu\xi \ge -1.0$ because the yield condition on the surface, beyond point 14 would be violated excessively.

For other values of v and  $V/c_p$  the situation is generally similar. Violation of the yield condition for low values of  $p_o/k$  occurs first on the S-front, while for higher values of  $p_o/k$  the violation appears first on the surface.

### 2. Range of depth for which results apply

The previous discussions considered the validity of results with respect to a nondimensional depth  $\mu y$ . It is appropriate to consider values of  $\mu$  of physical interest to find out for what actual depth y results have been obtained.

Let  $t_o = 0.2 \text{ sec}$ , V = 4000 ft/sec, then  $\frac{1}{\mu} = Vt_o = 800 \text{ ft}$ . For the typical values v = 0.25 and  $V/c_p = 2.0$  discussed above, information on peak pressures for values of the surface load  $p_o = 4.0k$  and 6.0k are contained in Tables XIV and XV up to about  $\mu y = 0.6$  or for a depth of 480 feet. A time history can be plotted using interpolation for the depths  $\mu y = 0.5$  or 400 feet. For the same values of v and  $V/c_p$ , but  $p_o/k = 10.0$ , the limit of applicability is  $\mu y = 0.3$ , or about 240 feet.

In general, for larger values of  $V/c_p$  and for larger values of  $p_o/k$  the depth for which the results apply decreases.

#### SECTION V

#### CONCLUSIONS

An analytical approach has been presented to describe the effect of a decaying pressure moving with superseismic velocity  $V \ge 1.5 c_p$  on the surface of a half-space of an elastic-plastic material subject to the von Mises yield condition. Numerical results have been obtained for a wide range of surface pressure and material properties. Due to simplifications in the analysis the results obtained are approximate and restricted to target points of limited depth, as discussed in Section IV.

Information on the stress field for exponential decay of the applied load is contained in Tables II - XXVIII and in the accompanying figures. Comparing the effects of step loads given in Ref. [1] with the new results for decaying loads, it is found that in the latter case the peak and subsequent pressures decrease with depth, which is not the case for a step load. However, the decrease found at any depth y is smaller than the decrease of the applied pressure at the point on the surface directly above the target point, i.e., at a distance equal to  $(-y/tg \bar{\phi})$  behind the shock front. This is graphically shown in Figs. 10 to 18. While the attenuation is therefore less important than one might expect, it is still greater than found in a similar analysis, Ref. [3], for an elastic-plastic material of the Coulomb type.

# <u>APPENDIX I - Special Case, m = 0</u>

Although an approach analogous to that used in the text for m > 0 may be used for m = 0, it is considerably simpler to derive expressions for a step pressure using the simple configuration shown in Fig. 8, consisting of three shock fronts only.

# For $\phi_p \leq \phi < \overline{\phi}$

$$\frac{\sigma_1}{k} = \frac{\Delta \sigma^P}{k}$$
(86)

$$\frac{\sigma_2}{k} = \frac{\sigma_3}{k} = \frac{\nu}{1-\nu} \frac{\Delta \sigma^P}{k}$$
(87)

where

$$\frac{\Delta \sigma^{\rm P}}{\rm k} = -\frac{\sqrt{3}'(1-\nu)}{1-2\nu}$$
(88)

For  $\overline{\phi} < \phi < \phi_S$ 

$$\frac{\sigma_1}{k} = \frac{\Delta \sigma^P}{k} + \frac{\overline{\Delta \sigma}}{k}$$
(39)

$$\frac{\sigma_2}{k} = \frac{\sigma_3}{k} = \frac{\Delta \sigma^P}{k} \left(\frac{\nu}{1-\nu}\right) + \frac{\overline{\Delta \sigma}}{k}$$
(90)

where

$$\frac{\overline{\Delta\sigma}}{k} = -\frac{p_{o}}{k} + \frac{\sqrt{3}}{2} \left[ \frac{2(1-\nu)}{1-2\nu} \cos 2\phi_{S} + \frac{\sin 2\phi_{P} \sin 2\phi_{S}}{\cos 2\phi_{S}} \right]$$
(91)

$$\frac{\sigma_1}{k} = -\frac{p_0}{k}$$

$$\frac{\sigma_2}{k} = -\sqrt{3} \left[\cos^2 \phi_p + \left(\frac{1-\nu}{1-2\nu}\right)\right] + \sqrt{3} \frac{\tan 2\phi_s \sin 2\phi_p}{2\cos 2\phi_s} + \frac{\overline{\Delta \sigma}}{k}$$

$$\frac{\sigma_3}{k} = \frac{\sqrt{3}}{2} \left(\frac{\nu}{1-2\nu}\right) + \frac{\overline{\Delta \sigma}}{k}$$
(92)
$$(92)$$

.

1

.

# APPENDIX II - Elastic Solutions

The expressions for the stresses in a purely elastic material subjected to a step pressure may be found in Ref. [1]. The equivalent expressions for a decaying surface pressure are:

For 
$$\phi_P \leq \phi < \phi_S$$

$$\frac{\sigma_{y}}{k} = \frac{\Delta \sigma^{P}}{k} \cos 2\phi_{S} e^{\mu(\xi - \xi_{P})}$$
(95)

$$\frac{\sigma_x}{k} = \frac{\Delta \sigma}{k} \left[1 - 2 \sin^2 \phi_s \cot^2 \phi_p\right] e^{\mu(\xi - \xi_p)}$$
(96)

$$\frac{\sigma_z}{k} = \frac{\Delta \sigma^P}{k} \left[ \frac{1}{2} \left( \frac{1-2\nu}{1-\nu} \right) \sin 2\phi_P \right] e^{\mu (\xi - \xi_P)}$$
(97)

$$\frac{\tau}{k} = -\frac{\Delta\sigma^{P}}{k} \left[2 \sin^{2}\phi_{S} \cot \phi_{P}\right] e^{\mu(\xi-\xi_{P})}$$
(98)

$$\frac{\Delta\sigma^{P}}{k} = -\frac{p_{o}}{k} \frac{(1-\nu) \cos 2\phi_{S}}{[\cos^{2}\phi_{S} + (1-2\nu) \cos^{2}(\phi_{S} - \phi_{P}) - (1-\nu)]}$$
(99)

$$\xi_{\rm p} = \frac{y \cos \phi_{\rm p}}{\sin \phi_{\rm p}} \tag{100}$$

$$\frac{For \phi_{S} < \phi < \pi}{\frac{\sigma_{y}}{k} = -\frac{P_{o}}{k} e^{\mu\xi}}$$
(101)

$$\frac{\sigma_x}{k} = \frac{\Delta \sigma^P}{k} \left[1 - 2 \sin^2 \phi_S \cot^2 \phi_P\right] e^{\mu(\xi - \xi_P)} - \frac{\Delta \tau^S}{k} \sin 2\phi_S e^{\mu(\xi - \xi_S)}$$
(102)

$$\frac{\sigma_z}{k} = \frac{\Delta \sigma^P}{k} \frac{(1-2\nu)}{2(1-\nu)} \sin 2\phi_P e^{\mu(\xi-\xi_P)}$$
(103)

$$\frac{\tau}{k} = -\frac{\Delta\sigma^{P}}{k} \left[2 \sin^{2}\phi_{S} \cot \phi_{P}\right] e^{\mu(\xi-\xi_{P})} + \frac{\Delta\tau^{S}}{k} \cos 2\phi_{S} e^{\mu(\xi-\xi_{S})}$$
(104)

$$\frac{\Delta \tau^{S}}{k} = \frac{1-2\nu}{2(1-\nu)} \frac{\sin 2\phi_{P}}{\cos 2\phi_{S}} \frac{\Delta \sigma^{P}}{k}$$
(105)

$$\xi_{\rm S} = \frac{y \cos \phi_{\rm S}}{\sin \phi_{\rm S}} \tag{106}$$

UNCLASSIFIED

.

1

Ł

신문

Security Classification			
DOCUMENT CONT	ROL DATA - R &	L D	
Security classification of title body of abstract and indexing.	annotation must be a	ntered when the	overall report in classified)
Paul Weidlinger, Consulting Engineer		UNCI ASST	TER
Now York New York 10017		25. GROUP	<u>r140</u>
New fork, New fork 1001/		- <u></u>	
EXPONENTIALLY DECAYING PRESSURE PULSE MON		DEFTENTC	
VELOCITY ON THE SURFACE OF A HALZ-SPACE O	F VON MISES I	ELASTO-PLA	STIC MATERIAL
4 DESCRIPTIVE NOIES (Type of report and inclusive dates)			
October 1967 to May 1968		·	
Bleich, Hans H.			
Matthews, Alva			
		· · · · · · · · · · · · · · · · · · ·	
August 1968	78. TOTAL NO. OF	PAGES	7b. NO. OF REFS
88. CONTRACT OR GRANT NO	90. OBIGINATOR'S	REPORT NUMP	5 (F R(5)
F29601-67-C-0091			
b. PROJECT NO 5710	AFWL-TR-68-46 9b. OTHER REPORT NO(5) (Any other numbers that may be assign this report) s subject to special export controls and each		
- Subtack No RSS2144			
COULASK NO NOSZI44	9b. OTHER REPOR this report)	T NO(5) (Any of	her numbers that may be assigned
d.			
10 DISTRIBUTION STATEMENT This document is subject	ct to special	export c	ontrols and each
transmittal to foreign governments or for	eign national	ls may be n	made only with prior
approval of AFWL (WLDC), Kirtland AFB, NM	ex 87117. I	)istributi	on is limited
DECAUSE OF THE TECHNOLOGY discussed in the	12. SPONSORING M	LITARY ACTIN	VITY
	DASA	١	
		•	
13 ABSTRACT			
(Distribution Limitation Stat	tement No. 2)	) 	alla de conduce
pressure pulse traveling with superseismi	c velocity or	the surf.	arly decaying ace of a balf-
space. The half-space is an elastic-plas	tic material	of the vo	n Mises type.
The effect of a step wave for this geomet	ry and medium	n was trea	ted previously.
For that case, the peak pressures do not	decrease with	n increase	in depth,
while such a decrease is obtained for a decrease is obtained for a decrease of this investigation is to determ	ecaying surra	ace load.	The prime
The approximate solutions obtained are va	lid for a lin	nited dist	ance behind the
wave front, and are tabulated for different	nt sets of pa	rameters	pertaining to
the material and velocity. The tabulated	results show	that the	peak pressures
in the case of the decaying surface load of decrease is loss that are marked in the second state of the se	do decrease v	ith depth	, but that the
attenuation is in general larger than the	ty expect. (	m the other other in the state	imilar problem
of an elasto-plastic material of the Could	omb type.	uite 0.	
-			
	,		
DD FORM 1473	UN	CLASSIFIE	D
		Security	Classification

v

IA. KEY WORDS		LINK A		КВ	LINK C	
		WT	ROLE	ΨT	ROLE	W
lastic-Plastic			[ ]		[	
lave Propagation						
ave reopugation						{
round Motion						}
bagying Processo Dulca						Į
ecaying riessure ruise						
					ļ	ļ
						ļ
					ĺ	
			}		ļ	
	1					
	Í					
			1		1	
	ļ					
				i		
			[			[
					Ì	[
						[
	ļ					
			••••••••••••••••••••••••••••••••••••••	ريبي ككنوني م		
	<u> </u>	NCLASS	IFIED			

į