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AFFDL-TR-67-192 VCLUME II

## ESTABLISHMENT OF AN UNSYMMETRICAL WAKE TEST CAPABILITY FOR AERODYNAMIC DECELERATORS

1949 - 19 13

VOLUME II. ANALYSIS OF HIGH-SPEED AXISYMMETRIC WAKES AND PARASONIC PARACHUTE PERFORMANCE

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Goodyerr Aerospace Corporation

TECHNICAL REPORT AFFDL-TR-67-192, VOLUME II

**AUGUST 1968** 

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AIR FORCE FLIGHT DYNAMICS LABORATORY AIR FORCE SYSTEMS COMMAND WRIGHT-PATTERSON AIR FORCE BASE, OHIO

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### FOREWORD

The work described in this report was performed by Goodyear Aerospace Corporation (GAC), Akron, Ohio, under USAF Contract AF33(615)-3595. The contract was initiated under Project 6065, "Performance and Design of Deployable Aerodynamic Decelerators," Task 606507, "A. rodynamic Decelerator Free-Flight Performance at High Mach Numbers." The program was administered by the Air Force Flight Dynamics Laboratory, Air Force Systems Command, Wright-Patterson Air Force Base, Ohio Mr. W. R. Pinnell and Mr. C. A. Babish III, (FDFR), were project engineers.

The work covered in this report was initiated on 1 March 1966 and completed on 15 January 1968. The report was submitted in March 1968.

This volume does not cover all the program's primary objectives. Volume 1 of this report presents analyses and preliminary design efforts to determine feasibility of reconfiguring a free flight decelerator test vehicle by means of an inflatable appendage in order to simulate the wake of a lifting body. Volume III contains a tabulation of wake survey and body surface pressure data obtained from wind-tunnel tests conducted during this program.

The contractor's report number is GER-13528.

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Special acknowledgment is made of conscientious support of Dr. R. M. Nerem of Ohio State University who, in his activities as a consultant, added technical assistance to the boundary layer and wake analyses.

This technical report his been reviewed and is approved.

GEORGE A. SOLT, Jr. Chief, Recovery & Crew Station Branch Vehicle Equipment Division AF Flight Dynamics Laboratory

### ABSTRACT

Methods were developed to predict the boundary layer and wake characteristics of symmetric bodies manifely at supersonic speeds. The methods developed for predicting boundary layer characteristics are applicable to both laminar and turbulent flow over axisymmetric or two dimensional bodies and can be used as an approximation for the flow over quasisymmetric bodies. The wake predictive methods were developed for axisymmetric flow and are applicable to both laminar and turbulent wakes. The aforementioned methods were combined and programmed such that wake profiles may be determined based only on inputs of forebody geometry and free stream conditions. Also presented is a method for calculating the drag of PATASONIC<sup>T</sup> parachutes using the flow field immediately ahead of the parachute as the free stream conditions. An analysis of the effects of various geometric and free stream parameters on PARASONIC parachute performance was conducted and trends determined.

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### **LIST OF SYMBOLS**

### BOUNDARY LAYER ANALYSIS (SECTION II AND APPENDIXES I AND III)

- a = speed of sound or semi-minor axis of ellipse
- B = Equation 36
- b = semi-major axis of ellipse
- D = forebody base diameter
- $G_1 = Equation 34$ 
  - h = enthalpy
  - $h = h_w / h_{aw}$
  - k = exponent from Equation 24
- M = Mach number or boundary layer integrated momentum defect

M\* = wake integrated momentum defect

P = pressure

Pr = Prandtl number

- R = base radius for axisymmetric body, or hydraulic base radius for non-axisymmetric body
- Re = Reynolds number

 $R_T$  = transition Reynolds number

 $R_1 = gas constant$ 

- r = radial coordinate
- s = distance from stagnation point measured along surface
- $\tilde{s}$  = circumferential coordinate
- T = temperature

 $\Gamma_{r,1} = Equation 38$ 

u = velocity

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U'/U =free stream turbulence

V = velocity

x = axial coordinate of forebody

 $\beta$  = pressure gradient parameter, Equation 24

y = ratio of specific heat capacities

 $\theta$  = boundary layer momentum thickness

 $\theta_{tr}$  = transformed boundary layer momentum thickness

- $\mu = viscosity$
- v = kinematic viscosity
- $\xi$  = Equation 24
- $\xi^*$  = Equation 27

 $\xi_{\rm T}^{*}$  = Equation 41

- $\rho$  = gas density
- symmetry
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### Subscripts

- a = adiabatic
- e = edge of body boundary layer
- s = nose stagnation conditions
- w = body wall conditions
- t = stagnation conditions
- $x_{tr} = value of x at transition$
- co = free stream conditions

θ critical = momentum thickness at which the boundary layer becomes unstable to small disturbances

 $\theta_{tr}$  = momentum thickness at transition

### WAKE ANALYSIS (SECTION III AND APPENDIX IV)

- a = velocity of sound
- a; = coefficients in velocity profile, i.e., Equation 5
- $a_{1, 2, \ldots}$  = enthalpy constants determined from boundary conditions

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- c<sub>D</sub> = heat capacity at constant pressure
- D = forebody base diameter
- h = enthalpy
- K = turbulence constant in Equation 6
- $K_1, K_2, K_3 = constants$  in Equations 16 and 17
  - $\overline{M}_1$  = effective Mach number. Equation 17
    - M = Mach number
    - m = exponent in Equation 6
    - n = transformed coordinate, Equation 57; exponent, Equation 6
    - P = pressure
  - Pr = Prandtl number
    - p = exponent in Equation 6
  - p<sub>+</sub> = total pressure
  - R = universal gas constant
  - Re = Reynolds number
  - Rs = shock radius

 $R_T$  = Townsend Reynolds number

- r = radial coordinate
- r\* = half-width at half-depth; see Equation 8
- T = temperature

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u = x-direction velocity component

 $V_{\infty}$  = free stream velocity

- v = radial direction velocity component
- X = downstream distance from forebody base
- $\mathbf{x}_{0}$  = rear stagnation point location
- Y = vertical distance from forebody centerline (+ above and - below)
- Z = horizontal distance from forebody centerline (+ right and - left, looking upstream)
- $\gamma$  = ratio of specific heat capacities
- $\Delta =$  transformed wake radius or thickness
- $\delta$  = wake radius or thickness

 $\delta_{\rm D}$  = wake diameter,  $\delta_{\rm D}$  = 26

- $\delta^*$  = wake displacement thickness
  - $\eta$  = nondimensional transformed radial coordinate
  - $\theta$  = momentum thickness
- $\theta_{T}$  = enthalpy thickness
  - H = viscosity
  - $\xi$  = wake form parameter in Equation 63
  - P = gas density

### Subscripts

- B = forebody base where boundary layer separates
- D = forebody diameter
- L = local conditions
- t = total condition
- s = forebody surface condition
- TR = transition condition

w = wall condition

- x = distance from rear stagnation point
- $\infty$  = freestream condition

 $\delta_{D_{TR}}$  = wake diameter at transition

- $\theta$  = momentum thickness
- 0 = wake centerline conditions
- 1 = viscous wake edge condition

### DRAG PREDICTION (SECTION V); PARASONIC PARACHUTE PERFORM-ANCE (SECTION IV); WIND-TUNNEL TESTING AND DATA REDUCTION (APPENDIX V)

- A = area
- a = camber
- b = chord for linear downwash
- $C_D = drag$  coefficient

 $C_{D_{p}} =$ pressure drag coefficient

 $C_n = pressure coefficient$ 

- D = forebody base diameter; drag; parachute diameter
- Di = inlet diameter of parachute
- D<sub>open</sub> = porous area equivalent diameter
  - DR = roof cap diameter
    - f = frequency
    - $l_{g}$  = suspension line length

M = Mach number

- NG = number of gores
- NS = number of suspension lines
  - n = number of annular rings

- P = pressure
- q = dynamic pressure
- R = maximum radius of parachute
- Re = Reynolds number
  - r = radius of ring of differential width ds
- $\mathbf{r}_i = \text{inlet radius of ring of constant pressure differential}$
- $\mathbf{r}_{0}$  = exit radius of ring of constant pressure differential
- WR = width of radials
  - X = downstream distance from forebody base
  - Y = vertical distance from forebody centerline (+ above and - below
  - Z = horizontal distance from forebody centerline (+ right and - left, looking upstream)

 $a_c$  = angle between chord and skirt axis

$$\beta = \sqrt{M^2 - 1}$$

 $\lambda_{a} = geometry porosity$ 

 $\lambda_{\rm T}$  = total porosity

s = angle between a line tangent to parachute canopy and parachute centerline

### Subscripts

- b = forebody base or breathing
- c = constructed or canopy
- e = mesh opening
- f = drag oscillation
- i = inlet
- L = iocal conditions
- o = stagnation conditions

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- p = projected
- t = total conditions
- exp = experimental
- ext = external
- int = internal
  - $\alpha$  = canopy oscillation angle
  - 1 = conditions forward of shock wave
  - 2 =conditions aft of shock wave
  - $\infty$  = free stream conditions

### FOREBODY FLOW FIELD PROGRAM (APPENDIX II)

- i = axial indexing parameter
- M = Mach number
- p = pressure
- R = average base radius
- r = radial coordinate normal to body centerline
- $\gamma$  = ratio of specific heats
  - $\theta$  = angle of the forebody surface with the body axis in each  $\phi$  plane
- $\theta_c$  = critical cone angle for attached shock
  - $\phi$  = Reference plane passing through body centerline

#### Subscripts

- e = Conditions at boundary layer edge
- o = local stagnation conditions
- s = nose stagnation conditions
- $\infty =$ free stream conditions

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#### SECTION I

#### INTRODUCTION

As a portion of the Establishment of an Unsymmetrical Wake Test Capability for Aerodynamic Decelerators (EUREKA) program sponsored by the Air Force Flight Dynamics Laboratory (AFFDL), a study was performed to analyze performance characteristics of supersonic parachutes operating in the wakes of both axisymmetric and asymmetric forebodies and to develop the capability to analytically predict the performance of a parachute operating in the wake of an axisymmetric forebody. The results of that study are presented in this volume.

In order to predict the parachute performance, the properties of the wake flow field in which the parachutes operate and the forebody flow field properties that establish the development of the wake flow field had to be determined. The three basic tasks performed were:

- 1. Analysis of the flow field and boundary layer characteristics of the axisymmetric forebodies
- 2. Determination of the viscous and inviscid wake flow field characteristics behind these forebodies
- 3. Prediction of the drag performance characteristics of the parachute operating in the wake of such forebodies

Presented in Section II is a method for determining the flow properties over the forebody and the boundane layer momentum thickness and momentum defect on the body. The invision is we properties necessary for the boundary layer analysis are computed using Newtonian and tangent cone theories, where the tangent cone theory is based on the Taylor-Maccoll conical flow solution. The laminar compressible boundary layer characteristics are determined by using a local similarity solution, and the turbulent boundary layer is analyzed by using an integral method. An approximate criterion for the boundary layer transition point also is given.

Presented in Section III is a momentum integral solution for laminar and turbulent viscous wake characteristics and a mass flow balance solution for the inviscid wake characteristics. The viscous wake theory is based on the assumption that the details of the base flow and free shear layer regions may be largely ignored, thus allowing the wake momentum defect to be equated to the forebod, momentum defect. Boundary layer type equations then can be applied to the wake flow region downstream of the wake rear stagnation point. Also presented in Section III is a method for determining inviscid wake characteristics by a mass flow balance that is performed with the forebody bow shock shape.

Based on the viscous and inviscid wake solutions along with the computed forebody characteristics, comparison of predicted wake profiles has been made with experimental wake profile data obtained from EUREKA windtunnel tests behind an Arapaho C with nose cone forebody. These correlations

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indicate that excellent agreement between wake theory and experiment can be obtained using the methods presented in this volume. The wake methods of solution, as well as the forebody methods of solution, have been programmed in FORTRAN IV for use on the IBM 360, Model 40, and IBM 7094 computers. This computer program was used in making all the wake comparisons shown.

Section IV contains an analysis of the effects of Mach number, Reynolds number, forebody shape, canopy location, and canopy size on PARASONIC<sup>1</sup> parachute performance.

Section V presents a method for calculating the pressure drag coefficient of a PARASONIC parachute operating in the wake of an axisymmetric forebody. Comparisons of calculated and experimentally determined drag coefficients are presented also and show good agreement.

Other sections of this volume contain conclusions, recommendations for future work, and appendixes giving the details of the flow field analyses and wind tunnel tests.

This report does not cover all primary program objectives. Volume I presents analyses and preliminary design efforts to determine feasibility of reconfiguring a free flight decelerator test vehicle with inflatable appendage in order to simulate the walks of a lifting body.

Volume III contains a tabulation of wake survey and body surface pressure data obtained from wind tunnel tests conducted during the EUREKA program.

<sup>1</sup>TM, Goodyear Aerospace Corporation, Akron, Ohio.

### SECTION II

### BOUNDARY LAYER ANALYSIS

### 1. BOUNDARY LAYER CHARACTERISTICS

In investigating the various characteristics of the viscous wake trailing a typical aerodynamic body, one of the dominant features is integrated momentum defect. The wake momentum defect, M , can be expressed as

 $M^* = \int_0^\infty \int_0^{2\pi} \rho u(u_1 - u) r d\phi dr$ ,

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and for a wake in which there is little or no static pressure gradient, the momentum defect remains invariant as the wake develops in the downstream direction. Furthermore, by neglecting the details of the base flow ad shear layer regions and assuming that no external work is done on the wake fluid in these regions, the wake momentum defect,  $M^*$ , may be evaluated by equating it to the integrated boundary later momentum defect, M, at the trailing edge of the forebody. The equation at momentum defects provides a direct link between the viscous wake properties and the forebody configuration, and any attempt to predict the properties of the viscous wake behind a body must begin with some knowledge of the forebody trailing edge boundary layer momentum defect.

This section describes the development of a method for calculating the growth of the boundary layer momentum thickness and momentum defect over an aerodynamic body of arbitrary shape. In doing this, an extensive literature survey was made of the available literature on compressible boundary layer flow. The method finally chosen for use on the program is representative of the state of the art of present boundary layer theory. The resultant procedures developed yield solutions for twodimensional or axisymmetric flow and are good approximations for quasitwo-dimensional or quasi-symmetric flows. The method of analysis as developed for laminar and turbulent flow has been programmed for use on high speed digital computers and has been utilized to determine the momentum defect and momentum thickness on the Arapaho Cvehicle with nose cone and on a blunted elliptical cone configuration.

### 2. BOUNDARY LAYER CALCULATION METHODS

#### a. Laminar Boundary Layer

Kemp, Rose, and Detra (Reference 1) have studied the compressible laminar boundary layer, including effects due to pressure gradient and due to chemical dissociation. The former effect has been investigated through the study of similar solutions that may be obtained for cases in which the boundary layer pressure gradient parameter,  $\beta$ , is constant with respect to surface distance. Although for most cases of interest  $\beta$  is not constant over the entire surface of a body, it has been generally accepted that the results of such calculations still may be applied in

engineering calculations if the local value of the pressure gradient parameter,  $\beta$ , is used (References 2 and 3). This application is called the concept of "local similarity." Lees in Reference 4 has shown that for highly cooled boundary inversible effect of the parameter  $\beta$  is small and may even be neglected entirely for heat transfer calculations. However, for skin friction calculations and for cases where the wall temperature is comparable to the free stream total temperature,  $\beta$  still can have an important effect. Within the assumption of local similarity, however, this influence may be accounted for by using the local value of  $\beta$ .

As was indicated, Kemp, Rose, and Detra also have included effects due to dissociation by using the binary model of Fay and Riddell in Reference 5. The results obtained indicate no important effects for catalytic or near catalytic surfaces; and thus, for the analysis described herein the gas is treated as thermally and calorically perfect.

Stetson in Reference 6 has presented an empirical correlation of the results of the numerical solution for momentum thickness,  $\theta$ , of Kemp, Rose, and Detra which is given by Equation 24 (Appendix I). This equation applies to two-dimensional or axisymmetric flows and can be used with reasonable accuracy for quasi-symmetric flows such as that over elliptical cones. Knowing the equation for the momentum thickness,  $\theta$ , and knowing the inviscid flow properties at the edge of the boundary layer (from Item 3 below), the momentum thickness and the momentum defect

 $M = \int_{circumference} \rho_e u_e^2 \theta d\tilde{s}$ 

can be evaluated. The details of this development are given in Appendix I.

### b. Turbulent Boundary Layer

The state of knowledge of turbulent boundary layers is not as well developed as that of the laminar case. Although there have been many approximate treatments of turbulent flow, most of which can be supported to one degree or another by some of the existing experimental data, there are no "exact" theoretical solutions such as that of Kemp, Rose, and Detra for laminar flow.

One approximate solution, the results of which lend themselves to the present problem, is that of Reshotko and Tucker (Reference 7). This solution uses the momentum integral and moment-of-momentum equations and is simplified by using Stewartson's transformation from Reference 8. In order to solve these two equations, a skin friction relation must be used. Reshotko and Tucker chose the Ludwieg-Tillman relation (Reference 9) in a form suitable for compressible flow with heat transfer through application of the reference enthalpy concept. The above equations were further simplified through the use of an approximate shear stress distribution and the power law velocity profile.

The moment-of-momentum equation is needed in order to account for pressure gradient effects on the boundary layer velocity profile. The

method o: Reshotko and Tucker, as applied to insulated surfaces, is quite well founded. However, for noninsulated or nonadiabatic wall cases, the method (though qualitatively correct) is based on some speculative assumptions. It is still anticipated, however, that for such cases the method will yield reasonable quantitative results. The method certainly is representative of the best solution that can be obtained within the present status of turbulent flow theory.

Reshotko and Tucker have presented their results in terms of a transformed momentum thickness,  $\theta_{tr}$ , given by the equation

$$\theta = \theta_{tr} (1 + \frac{\gamma - 1}{2} M_e^2)^3$$

If the boundary layer is turbulent over the entire body, the solution begins at the stagnation point. However, if the boundary layer is initially laminar, the calculation must begin at the transition point. The transition point can be specified either in terms of a location or a transition Reynolds number,  $Re_{\theta}$ , or it can be determined from the transition criterion developed in Item 3, b. This criterion has been programmed along with the turbulent boundary layer solution. The details of the solution for boundary layer momentum thickness and momentum defect are given in Appendix I along with the basic elements of the programmed boundary layer solution.

#### 3. SUPPORTING ANALYSES

#### a. Forebody Inviscid Flow Field

In order to evaluate the boundary layer momentum thickness and momentum defect, the inviscid flow field characteristics at the edge of the boundary layer must be determined. In particular, for the programmed boundarw layer analysis, the following flow properties must be evaluated along the forebody: (1)  $P_e/P_o$ , (2)  $P_o/P_s$ , and (3)  $M_e$ . A general computation procedure was developed to calculate the flow properties along the forebody based only on inputs of free stream conditions and forebody geometry.

The procedure is applicable for a wide range of free stream conditions and is suitable for quasi-symmetric geometries as well as for axisymmetric and two-dimensional bodies. A tangent cone method of solution was used to obtain the flow properties for sharp-nosed bodies and a combination of New\*onian and tangent cone methods was used for a bluntnosed configuration. To this end, a Taylor-Maccoll conical flow solution was programmed along with a logic procedure for the application of the tangent cone and Newtonian methods to quasi-symmetric forebody geometries. The logic procedure is shown in Appendix II.

The use of Newtonian theory and tangent cone theory is sufficient to yield solutions for pressure and Mach number within 10 to 20 percent accuracy, which is quite sufficient for engineering purposes. Since the momentum defect varies as the square root of the pressure, a 20-percent error in pressure would cause less than a 10-percent error in

momentum defect. Note also that the effects of boundary layer separation on the pressure are not considered in this analysis.

### b. Boundary Layer Transition

In order to make use of the turbulent boundary layer analysis, it is necessary to determine the location at which transition occurs. As a part of the computer program developed to predict boundary layer momentum defect, three choices exist for determining transition:

- 1. Input the transition point location
- 2. Input the transition Reynolds number,  $Re_{\theta_{tr}}$
- 3. Compute  $\operatorname{Re}_{\theta_{tr}}$  based on a programmed transition criterion

The criterion developed to predict transition was based on a correlation by Dr. R. Nerem, consultant, of the form

$$Re_{\rho} \approx 1.000 (1 - 0.12 \text{ M}^2 + 0.023 \text{ M}^3)^{1/2}$$

$$(-2.29 + 17.38 \text{ F} - 18 \text{ F}^2 + 3.91 \text{ F}^3)^{1/2}, \qquad (1)$$

where

$$\overline{\mathbf{h}} = \mathbf{h}_{\mathbf{w}} / \mathbf{h}_{\mathbf{a}\mathbf{w}}$$
.

For regions of adverse pressure gradients, such as in the vicinity of a compression surface, the  $Re_{\theta tr}$  is replaced with the critical Reynolds number given by

These equations have been programmed as part of the boundary layer calculation procedure and are used if transition location or transition  $Re_{\theta}$  is not specified. The evolution of the above equations and a general discussion of boundary layer transition may be found in Appendix III.

#### SECTION III

### WAKE ANALYSIS

#### 1. WAKE REGIONS

Analysis of the characteristics of high-speed wakes begins by examining the various regions that comprise the conventional high-speed wake. The five distinct regions of the high-speed wake shown in Figure 1 are: 「「「「「「「「」」」」

- 1. Recirculating base flow
- 2. Free shear layer
- 3. Rear stagnation point and the neck region
- 4. Inner viscous wake (downstream of the neck)
- 5. Outer inviscid wake

Each of these regions has its own peculiar characteristics. The recirculating base flow region, for example, is boundary layer fluid entrained due to the adverse pressure gradient associated with the deflection of fluid at the axis of symmetry back into the streamwise direction. The free shear layer is also boundary layer fluid; this fluid initiates the development of the neck region, which is characterized by steep gradients due to the presence of the recompression shock.

Aft of the neck region, the viscous wake develops in a rather orderly and well-behaved manner. This viscous wake is the subject of Item 3 of this section in which the conventional boundary layer equations, including the various integral relations, are applied to the viscous wake and a momentum integral method is used in obtaining a solution.

The outer inviscid wake also is shown in Figure 1. It surrounds the viscous wake and reflects the nature of the forebody inviscid flow field and, in particular, the curvature of the forebody bow shock wave and the entropy gradient there produced. The inviscid wake is discussed in detail in Item 4 of this section.

#### 2. VISCOUS WAKE MODELS

Considering the viscous wake in more detail and the velocity profiles shown schematically in Figure 1 in particular, it may be seen that for the conventional high-speed wake, the centerline X-direction velocity,  $\gamma_0$ , increases with increasing distance hownstream of the rear stagnation point. In the far wake (X/D >> 1), the centerline velocity actually approaches asymptotically to the logil free-stream velocity. For this problem, the radial velocity gradient is zero at the centerline for all of X, as are also the gradients in temperature, density, and the other fluid properties. On the other hand, the outer edge of this viscous wake, at least where the viscous and inviscid wakes are clearly separated from one another, is defined in the usual manner for boundary layer



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type flows. Here the properties are equal to their inviscid values, and the gradients in these properties are zero. Furthermore, for the case where viscous and inviscid wakes are clearly separated from one another and in the absence of any pressure gradient, the momentum defect will remain constant as the wake develops in the downstream direction. When a decelerator is attached to a forebody by a cable and is positioned in such a conventional high-speed wake, consideration must be given to the extent to which the wake characteristics are altered due to the interaction of the forebody wake, the decelerator, and the tow cable that links these two bodies. If the decelerator was located in the immediate neighborhood of the base of the forebody, a conventional high-speed wake would not have the opportunity to develop. In this case even the base flow and free-shear layer would be completely altered (see, for example, Figures 13 and 14 of Reference 10), and the proximity of the decelerator to the base of the forebody might result in the presence of a strong adverse pressure gradient in the largely subsonic cavity region separating the two bodies. In this case, the wake growth is explosive and the decelerator, being immersed in a subsonic cavity type of flow, produces a low drag coefficient.

If, however, the decelerator was located far downstream of the base of the forebody, then very little alteration of the wake flow would be expected  $d_{L^2}$  to the interaction of the decelerator with the wake itself. In this case the only alteration to the wake (except in the immediate vicinity of the decelerator) is due to the presence of the tow cable or riser line.

If it is assumed for the limiting case described above that the cab'e diameter is very small compared with the wake diameter, then the amount of work done on the wake due to skin friction on the cable is negligible. For this case, in the absence of any pressure gradient, both the wake momentum defect and momentum thickness are constant in the axial direction, exactly as in the conventional high-speed wake. However, at least for laminar flow here, the similarity between these wakes ends because in the present case, i.e. for the wake with a trailing decelerator in it, the tow cable forces the wake centerline velocity to be zero. Assurning further that the wake profiles are similar at all axia' stations, then the ratio of the wake momentum thickness to the wake diameter is the same at all axial stations, and the conclusion is that the wake diameter is constant with axial position. In other words, for this particular case there is no wake growth such as is present in the conventional highspeed wake. The wake is cylindrically shaped and does not change characteristics in the axial direction. This is illustrated in Figure 2.

For the turbulent viscous wake, however, this cylindrical wake model is not applicable. The turbulent wake in the presence of a tow cable or riser line must include both a laminar sublayer and an outer turbulent mixing layer. In this case, the effects of the tow cable are solely limited to the sublayer region. This region, though not present in the conventional wake, is such that it allows the no-slip condition to be satisfied at the wall, <u>i.e.</u> the cable surface. At this region's outer edge, the velocity is equal to that of the turbulent outer layer. This outer layer, on the other hand, not being constrained by the no-slip condition at the centerline, grows as in the case for the conventional turbulent wake.



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> For the condition of a contant viscous wake momentum defect (the assumption of negligible work due to cable skin friction is still inade here), the velocity at the inner edge of the turbulent layer increases just as the centerline velocity increases for the conventional turbulent wake.

During the first series of wake survey tests (WT-IIA) conducted under the EUREKA program, wake profile measurements were obtained behind an axisymmetric cone-cylinder-flare-cylinder forebody with and without a simulated riser line. These measurements are summarized in Figures 3 and 4 where impact pressure, rofiles at four different X/D stations are presented for Mach numbers of 2 and 5. There is virtually no difference between the properties of these two kinds of wakes. Furthermore, there is an obvious wake growth and the centerline region velocity may be show, to increase with X/D for both cases. The turbulent wake in the presence of a riser line is illustrated in Figure 5. 「「「「「「「「」」」」

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The discussions presented here concerning the nature of both laminar and turbulent wakes in the presence of a tow cable or riser line are based on only the preceding arguments and an extremely limited amount of experimental data. In spite of this, these models should prove useful in engineering calculations. They do appear to be applicable for a wide range of conditions in terms of Reynolds number, Mach number, etc. They are, however, limited to the case where the radius of the tow cable or riser line is much less than the wake momentum thickness and to X/D > 3, avoiding the "strong interaction region."

3. VISCOUS WAKE ANALYSIS

### a. Wake Flow Assumptions

An integral method of solution was applied to the problem of determining the properties of both laminar and turbulent viscous wakes with particular attention to the problem of the wake flow preceding a trailing aerodynamic decelerator. In the paragraphs that follow, the theory will be summarized for the different types of wake flows. The important assumptions contained in the theory are as follows:

- The fluid is thermally and calorically perfect, and there are no chemical reactions or other real gas phenomena.
- 2. The Prandtl number is unity (Pr = 1).
- 3. Prandtl's concept of viscous flow phenomena is valid for the high-speed compressible wake such that gradients in the streamwise or axial direction are much smaller than those normal to the wake axis and boundary layer type equations may be used.
- 4. The details of the base flow and free shear layer regions may be largely ignored. Thus, the region of validity for the present analysis must be considered to extend from somewhere in the vicinity

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Figure 5 - Turbulent Wake in Presence of Riser Line

> of the wake neck or further downstream and on down into the far wake.

5. Effects due to the existence of an external pressure gradient are negligible.

Note that this last assumption is not intended to restrict the solution to flows with zero pressure gradient. The assumption only implies that local acceleration in the inner wake itself is much more important than acceleration due to an external pressure gradient. This assumption allows the momentum integral equation to be simply written as

$$\rho_1 u_1^2 (\pi \theta_1^2) = 2\pi \int_0^0 \rho u (u_1 - u) r dr$$
 (3)

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constant with respect to X.

Here  $\theta$  is the momentum thickness and Equation 3 is simply a statement to the effect that the wake momentum defect is constant in the axial direction. Since the pressure gradient has been assumed to be negligible, then there is no external work being done on the wake, and the momentum defect must be constant.

As a check on the validity of the assumption of constant wake momentum defect, experimental wake momentum defect values were calculated from wake survey data obtained during wind tunnel tests conducted under this program. In looking at the viscous wake, it was found that the width of the wake decreased with increasing Mach number. For this reason, the viscous wake momentum defect comparisons were conducted at Mach 2. The comparisons were made for an axisymmetric spherical nose cone-cylinder-fiare forebody at a Mach number of 2 and a Reynolds number of 0.369  $\times 10^6$ /in. The wake momentum defects were computed at several wake stations using a data reduction program, which reduced wake survey pressure and temperature data to local velocities. The data reduction program used a linear variation between experimental data points in computing momentum defects. The edge of the viscous wake was determined by using the criterion that at the edge of the viscous wake, the total pressure would be equal to the total pressure immediately behind a normal forebody bow shock. The data reduction program chose the data point having a total pressure closest to this pressure. The spacing of the experimental data points was equal to one-tenth of the forebody base diameter. The experimental wake momentum defects also were compared with forebody momentum defect calculated using the method described in Section II. The results of the comparison are shown in Table I.

The tabulated values indicate that the method used for predicting the edge of the viscous wake is not accurate enough to produce accurate experimental wake momentum defect results. The X/D = 3 data are too near the wake neck to be a useful profile for this study. The general decrease in the momentum defect values from X/D = 5 to X/D = 11 is the result of the inaccuracy in selection of the nearest experimental data point as the

M <sub>∞</sub>	Re <sub>co/in</sub> .	X/D	Momentum defect in Y plane (lb)	Wake radius, Y/D	Momentum defect in Z plane (lb)	Wake radius, Z/D	Ferebody momentum defect (lb)
2	$0.369 \times 10^{6}$	3	5.68	0.5	2.98	U.5	1.203
2	$0.369 \times 10^{6}$	5	4.46	0.5	1.65	0.5	1.203
2	$0.369 \times 10^{6}$	7	4.10	0.5	1.02	0.4	1.203
2	0.369 × 10 <sup>6</sup>	9	2.29	0.5	0.964	0.4	1.203
2	$0.369 \times 10^{6}$	l n	1.73	υ.5	0.786	0.4	1.203

### TABLE I - VISCOUS WAKE MOMENTUM DEFECT COMPARISON

viscous wake edge. Since the wake is growing, the value of the momentum defect within a given circle will decrease with increasing X/D. The experimental data also may contain errors induced by the forebody mourting strut that spanned the wind tunnel in the Z plane. Within the limits of the accuracy of the experimental data and the computation method, the momentum defect is assumed to be constant. In an attempt to improve the method for computing the momentum defect in the wake, a polynomial curve fit technique was used to smooth the experimental data and therefore improve the accuracy of the calculation. Using the curve fit technique in the wake momentum defect calculations did not have an appreciable effect on the results.

Assumption 5 listed above thus does not limit the solution to wake flows with zero pressure gradient. However, the validity of the solution certainly does decrease with increasing pressure gradient. For blunt bodies with strong pressure gradients, the solution should be considered as being highly approximate.

By ignoring the details of the base flow and shear layer regions and assuming that no external work is done on the wake fluid in these regions, then the constant in Equation 3 may be evaluated by equating the momentum defect of the boundary layer at the base of the forebody to the momentum defect of the wake. This may be stated mathematically as

$$\rho_{\rm B} u_{\rm B}^2 (\pi \, \theta_{\rm B} {\rm D}) = \rho_1 u_1^2 (\pi \, \theta_1^2) \quad , \qquad (4)$$

where the subscript 1 refers to the properties associated with the outer edge of the wake and the subscript B, to properties at the base of the vehicle where the boundary layer separates. The symbols  $\rho_B$  and  $u_B$ represent inviscid properties, and D is the forebody base diameter. Next, the Dorodnitzyn transformation is introduced in order to obtain a solution to the axial direction momentum equation. In the integral method of solution, it is assumed that the velocity profile in the viscous wake may be expressed as a fourth-order polynomial of the form

$$\frac{v}{u_1} = \sum_{0}^{4} a_i \eta^i .$$
 (5)

Applying the appropriate boundary conditions to the above equation, a solution for the viscous wake velocity profile in the transformed coordinate system may be obtained. Considering the energy equation for the assumption of Pr = 1 and applying the appropriate boundary conditions to the energy equation, the enthalpy profile in the transformed coordinate system is obtained as a funct on of  $\xi$  the form parameter as derived in Appendix IV.

The details of the above development are given in Appendix IV and apply to both laminar and turbulent viscous wake flows. The necessary equations for determining the properties of a high-speed compressible wake were derived using an integral technique and the Dorodnitzyn transformation. In order to describe the entire wake flow field, the inviscid flow field must be determined (see Item <u>e.</u>, below) and that an estimate be made of the vehicle boundary layer momentum thickness (Section II above).

#### b. Laminar Axisymmetric Wake

Appendix IV describes the case of both the conventional laminar wake and the cylindrical laminar wake. In the appendix, the relationship between  $\xi$  and  $\chi$  is determined. For each case, it is necessary to specify a relation for the viscosity coefficient and, for both laminar flow cases, the viscosity is assumed to be linearly dependent with respect to fluid temperature; i.e.,  $\mu/RT = \text{constant}$ . For the cylindrical wake case,  $u_0/u_1 = 0$ , which is equivalent to  $\xi = 24$  (Appendix IV). Thus, the properties of the cylindrical wake are solved by setting  $\xi = 24$ , and  $\xi$  will not depend on X for this case since there will be complete similarity between radial profile at each X direction station.

Having solved for  $\xi$  as a function of X (Appendix IV) together with the equations derived in that appendix for the velocity and enthalpy profiles and the relationship between the transformed and physical radial coordinates, the properties of the laminar viscous wake are completely known.

Using this theory, as shown in Figure 6, reason, ble agreement is attainable even in the near wake region where the present theory should give the least reliable results. A further check on the laminar wake theory is presented in Figure 7 where the wake growth behind a conical body is presented as a function of distance downstream of the body. Figure 7 also shows both ballistic range experimental data from Reference 11 and the result of a theoretical calculation using the laminar wake method developed in Appendix IV. As may be seen, excellent agreement exists.

Unfortunately, good data does not exist at the present time for the laminar wake in the presence of a decelerator with which the laminar cylindrical wake results may be compared. Note that during the wind tunnel tests


Figure 6 - Experimental Measurements of Neck Diameter for Laminar High-Speed Wake

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Figure 7 - Comparison of the Momentum Integral Method Solution with Experimental Laminar Far Wake Data

performed as a part of this program only turbulent wakes were obtained. It is felt, however, that since the conventional laminar wake results in Figure 6 are for conditions similar to these of the cylindrical wake (for example, the centerline velocity is low in the near wake region and the velocity profile is similar to that of a cylindrical wake); and since reasonably good agreement exists, then the laminar cylindrical wake results should lead to equally good agreement.

#### c. Turbulent Axisymmetric Wake

For the turbulent wake case, a form for the viscosity relationship must be chosen different from that used for the laminar case. In turbulent flow, the viscosity coefficient is only an effective one (artificially introduced due to the manner in which the governing equations are expressed) and is related to the momentum transfer caused by the fluctuating, mixing type motion. Many different mathematical forms for the turbulent viscosity coefficient have been suggested in the literature; and four of these, as applied to the wake centerline, are summarized below (these four models are virtually identical to those discussed in Reference 13):

$$\mu_0 = k \rho_0 u_0$$
,

$$\mu_0 = \mathbf{K} \Delta \left( \rho_1 \mathbf{u}_1 - \rho_0 \mathbf{u}_0 \right)$$

$$\mu_{0} = K \Delta \rho_{1} (u_{1} - u_{0}) ,$$

and

$$\mu_0 = \mathbf{K} \Delta \rho_0 (\mathbf{u}_1 - \mathbf{u}_0).$$

While only the above models were considered in this investigation, the solution is not restricted to these viscosity models. In all of the above models, the value of the constant K is required. The first model relates the turbulent viscosity coefficient to the centerline momentum flux, the second model form involves a momentum difference, and the third and fourth models involve only a velocity difference. These latter models correspond to the accepted "classical" form for incompressible flow. However, the second model also reduces to a velocity difference for the incompressible case. The first model obviously does not reduce to the classical form for incompressible flow. In fact, the first model did not originate from classical viscous flow work, but from studies of jetmixing phenomena. All of the above modes may be expressed using the general form written below:

$$\mu_{0} = K\Delta \rho_{1} u_{1} \left(\frac{\rho_{0}}{\rho_{1}}\right)^{m} \left[1 - n - (-1)^{n} \left(\frac{\rho_{0}}{\rho_{1}}\right)^{p} \frac{u_{0}}{u_{1}}\right].$$
(6)

In Table II, the values for the constants m, n, and p are presented. In the computer program for the viscous turbulent wake, the specification of the model number directs the program to use the proper values of m, n, and p.

The value of K must be determined from experiments. In low-speed flows, it is conventional to define  $\mu_0$ , and thus K, through introduction of the Townsend Reynolds number,  $R_T$ , where

$$R_{T} = \frac{(u_{1} - u_{o})r^{T}}{\mu_{0}/\rho_{0}}$$
 (7)

M del	۳0	m	n	Р	Remarks
First	KΔ <sup>ρ</sup> 0u0	1	1	0	Momentum flux
Se. ond	$K \Delta (\rho_1 u_1 - \rho_0 u_0)$	0	0	1	Momentum difference
Ihird	$K \Delta \rho_1 (u_1 - u_0)$	0	0	0	Velocity difference
Fourth	$\mathbf{K} \Delta \boldsymbol{\rho}_0 (\boldsymbol{u}_1 - \boldsymbol{u}_0)$	1	,	0	Velocity difference

TABLE II - CONSTANTS FOR TURBULENT VISCOSITY RELATIONSHIP

Here,  $r^*$  is the so-called half-width at half-depth, <u>i.e.</u>, the radius at which the velocity is exactly intermediate to the axial and edge values, and  $R_T$  is the constant to be determined from experiment. For the second, third, and fourth models and in the limit of either incompressible flow or an "incompressible like" flow, <u>i.e.</u> the far wake where  $\rho_0 = \rho_i$ , then K and  $R_T$  are related by

$$K = \frac{r^{*}/\Delta}{R_{T}} .$$
 (8)

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For the polynomial velocity prefile of Equation 65 of Appendix D, it follows that

$$\frac{r}{\Delta} \cong \eta^* \cong 0.4 ,$$

and thus

$$K \cong \frac{0.4}{R_{T}} \quad . \tag{9}$$

Typical experimental values for  $R_T$  are tabulated in Table III together with the value of K calculated from Equation 9. These values of K may be compared with those of Zakkay and Fox in Reference 13 where the first model is similar to their Model 1, the second model to their Model 2, the third model to their Model 2A, and the fourth model to their Model 4. Based on the analysis of wind-tunnel data, Zakkay and Fox concluded that a value of K = 0.01 for the second model and K = 0.04 -0.06 for third and fourth models represented a best fit to their data. Zakkay a.d Fox also suggested a value of 0.02 for use with the first model. In project EUREKA, the best correlation with wind-tunnel wake test data has been obtained for values of K on the order of 0.005 to 0.01. Details of the comparison of the theory with experimental data will be given later in this section.

By substituting Equation 6 for the viscous wake into Equation 63, Appendix IV, for  $\xi$ , the form parameter, the relation between  $\xi$  and X can be determined.

Wake type	R <sub>T</sub>	к
Axisymmetric, incompressible	14 1	6 0ci
Two-dimensional, incompressible	12.0	0.033
Two-dimensional, compressible	10.0	0.040
Axisymmetric, compressible	13.7	0.029

TABLE III - TOWNSEND REYNOLDS NUMBER IN WAKE

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If the present method of solution and the turbulent viscosity coefficient models included in the analysis are accepted, then the resulting equations for  $\zeta$  as a function X, together with the equations derived in Appendix IV for the velocity and enthalpy profiles and the relationship between the transformed and physical radial coordinates, are sufficient to completely determine the properties of the turbulent viscous wake. Again, the properties of the forebody boundary layer and at the edge of the viscous wake are assumed to be known from the forebody computer program.

Using the above method of analysis, the turbulent viscous wake characteristics were determined and comparisons were made with the velocity profiles obtained from wind-tunnel test data obtained in the wake of the Arapaho C vehicle with nose cone (Appendix V). These comparisons were based on the iterated wake solution described in Item 5 of this section. In Figures 8 through 23, the wake velocity profiles are shown plotted versus the nondimensional distance (Y/D or Z/D) measured from the centerline of the viscous wake. Comparisons are shown for a range of Mach numbers from 2 to 5 for two Reynolds number conditions and for stations behind the base of the forebody from 3 to 11 calibers, which is the region of interest for decelerator application.

The theory is shown as a solid line and represents the total wake description, <u>i.e.</u>, both viscous and inviscid portions. The inviscid wake comparisons are further discussed in Item 4 of this section. The experimental velocity data points shown were calculated from the wake wind tunnel pressure measurements obtained as a part of this program. The disparity between the Y/D-plane data and the Z/D-plane data is at least partially due to the presence of the prebody mounting strut in the Z/D plane. However, this strut also may influence the Y/D data, and thus data for both planes is shown. Note also that at X/D = 3, there may be added inaccuracies in the data due to the influence of the rake used to obtain pressure readings.

The best correlation with the experimental EUREKA wake data has been obtained using the third viscosity model,  $\mu_0 = K \Delta \rho_1 (u_1 - u_0)$  with a viscosity coefficient K = 0.005. This K value, while below these normally used, was justified by considering that the solution had been iterated as explained in Item 5 of this section nonthus had changed the boundary layer approach that originally defined the range of acceptable viscosity coefficient values. Using K = 0.005 for the third model (shown in Figures 8 through 15), agreement with experiment to well within 10 percent has been obtained in almost all cases over the range of Mach numbers and wake location considered in this program and for both Reynolds number conditions considered. For X/D > 3, the correlation of the centerline velocities is to within 5 percent in all but one case.

Correlation with the experimental data has been obtained using other viscosity models; the results using the fourth model are shown in Figures 16 through 19 for K = 0.010 and in Figures 20 through 23 for K = 0.005 in order to show the effect of changing viscosity model and/or viscosity coefficient. Using the fourth model, the results show that the trend of the predicted centerline velocity is affected by Mach number. At Mach 2 the predicted centerline velocity is significantly higher than

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Figure 3 - Constantion of Experimental and Colo Cated Woke Proto en INter of Figure 5 3 psi, Moder 5 - K 7 300051

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Figure 13 - Comparison of Experimental and Calculated Wake Profiles  $(M_{\infty} = 3, P_{t_{\infty}} = 43.2 \text{ psi}, \text{ Model 3}, K = 0.005)$ 

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Figure 14 - Comparison of Experimental and Calculated Wake Profiles  $(M_{\infty} = 4, P_{t_{\infty}} = 73.3 \text{ psi}, \text{ Model 3}, K = 0.005)$ 

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Figure 17 - Comparison of Experimental and Calculated Wake Profiles  $(M_{\infty} = 3, P_{t_{\infty}} = 5.9 \text{ psi}, \text{ Model 4}, K = 0.01)$ 

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Figure 21 - Comparison of Externmental and Colouated Wike Provides (Max 3) Provides Model 4, Robot 5.5.

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> the experimental value. As the Mach number is increased, the degree of correlation changes until at  $M_{00} = 5$  the theory significantly underpredicts the velocity. This effect is not seen with the choice of the third model. For the same K value, the use of the fourth model will yield a lower centerline velocity than will the third model. The second model for which no data are shown, will result in even higher predicted centerline velocities than the third model. The first model was excluded due to the fact that it deviated from the proper variation of velocity with X/D as exhibited by the other models (see Appendix IV). With each model the choice of the viscosity coefficient K will influence the resultant velocity profile. As K is increased, the velocity predicted by a given model will increase and, as K is decreased, the predicted velocity will decrease.

> Prior to the use of the iterated solution, reasonable correlations between experiment and theory were obtained for a value of K = 0.025 with the third and fourth models.

#### d. Wake Transition

In Items 3, b and 3, c, an integral method for calculating the properties of both laminar and turbulent wakes was presented. However, up to this point no mention has been made of the conditions under which the viscous wake would be laminar or turbulent. Obviously, if the forebody boundary layer is turbulent, then the wake also will be turbulent, and a calculation of the wake profiles as a function of x/D proceeds as described in Item 3, c. However, if the borebody boundary layer is laminar, then the viscous wake may be either laminar or turbulent, depending on whether or not the flow conditions are suitable for transition to occur.

The phenomena of transition in hypersonic wakes has been studied extensively in the laboratory. As pointed out in Reference 14, the correlation of wake transition data that appears to indicate the most physical insight and thus be the most general is that of Pallone, Erdes, and Eckerman. In their work they used a transition Reynolds number based on local properties at the edge of the wake, a velocity equal to that at the edge relative to the centerline velocity,  $u_1 - u_0$ , and on the wake diameter at transition,  $\delta_{DTR}$ . The correlation of experimental data that they present is thus in terms of the transition Reynolds number,

$$\operatorname{Re\delta}_{\mathrm{D}_{\mathrm{TR}}} = \frac{\rho_{1}u_{1}}{\mu_{1}} \delta_{\mathrm{D}_{\mathrm{TR}}} \left(1 - \frac{u_{c}}{u_{1}}\right)$$
(10)

and the effective Mach number,

$$\tilde{M}_{1} = \frac{u_{1}}{a_{1}} \left(1 - \frac{u_{0}}{u_{1}}\right) . \tag{11}$$

Figure 24 shows a summarization of experimental measurements of wake transition Reynolds number. There is a reasonable correlation of the different experiments and the wake transition may be predicted to within a factor of two in Reynolds number.

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Figure 24 - Experimental Measurements of Wake Transition Reynolds Number

> In order to facilitate calculations using the correlation of Pallone, Erdos, and Eckerman, an approximate curve has been fitted to the data in Figure 24. This approximation is

$$\operatorname{Re}_{\delta} \sum_{\mathrm{D}_{\mathrm{TR}}} = 1700 \, \overline{\mathrm{M}}_{1}^{2.2} \, . \tag{12}$$

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This curve also is shown in Figure 24, and reasonable agreement may be see to exist.

In applying Equation 12 to a laminar cylindrical wake,  $u_0$  will be zero due to no-slip condition on the tow cable or riser line. Thus, Re DTR and  $\overline{M}_1$  become a somewhat more conventional "looking" Reynolds numbber and Mach number based on local edge conditions. Furthermore, for a constant pressure wake region, Re  $\int_{DTR}$  and  $\overline{M}_1$  will not vary with X/D. The viscous wake in the presence of a riser line or tow cable, attaching an aerodynamic decelerator, will be either wholly laminar or wholly turbulent.

### e. Near Wake Characteristics

The general characteristics of the near wake were illustrated earlier in Figure 1. This region is made up of the free shear layer, the base region recirculating flow, and the beginnings of the viscous inner wake at the rear stagnation point and on down through the neck; when considered in total, it is a rather complex fluid mechanic phenomena.

As Reeves and Lees have pointed out, and also provided in Reference 15, a relatively clear picture of the structure of the near wake now exists as a result of the many experimental studies that have been reported in the literature (see, for example, Reference 16 through 19). However, theoretically, the state of the art has not progressed as far. As has been pointed out by Webb, et al. in Reference 20, the near wake is characterized by two length scales corresponding to the existence of separate regions of high shear and of low velocity. Because of this aspect of the problem, the resulting governing equations are nonsimilar in form and do not reduce to ordinary differential equations when properly transformed. This may be contrasted with the far wake problem in which similar solutions are obtainable.

In order to circumvent this complexity, Lees and Reeves, and later Lees working with Webb and others at TRW Systems (References 20 through 22), have been developing multimoment integral methods of solution for the near wake problem. Weiss in Reference 23, on the other hand, has taken an approach that though inherently more complex offers the hope of a more exact solution of the near wake problem. He obtains a solution by dividing the near wake flow into three regions: (1) a rotational outer flow resulting from the inviscid expansion of the forebody boundary layer at the base, (2) a thin viscous "boundary" layer above the dividing streamline, and (3) the recirculation region itself. The first of these regions is solved for by using the method of characteristics; the second, using a modified Oseen solutiod of the boundary layer equations; and finally, the third region, by a finite difference

solution to the full Navier-Stokes equations. By coupling these regions together through the matching of boundary conditions at their interfaces and using an iterative method, complete solutions up to the rear stagnation point have been carried out. Although this method has not yet been extended to axisymmetric bodies, it would appear to be the type of approach that could lead to a satisfactory solution of the near wake problem.

For the present investigation, neglecting the near wake details by equating the momentum defect at the base of the forebody to that of the viscous wake downstream of the near wake region appears to be a satistic factory approximation in the development of an engineering solution for the viscous wake characteristics since the free shear layer energy transfer to the recirculation region has been found to be on the order of 10 percent of the total energy transfer from the borebody to the viscous wake. However, even this loss can be accounted for in the solution by use of an empirical constant as will be shown later in this section.

As part of the integral wake solution, it is necessary to specify the location of the rear stagnation point in order to properly relate the wake development to the forebody.

Although the rear stagnation point has been chosen in this instance as the starting point for the viscous wake solution, any other suitable reference location  $(\underline{a}, \underline{g}, \underline{c})$  wake neck or sonic point may be used if sufficient data exist to specify its location. Use of the wake neck as the starting point of the solution could yield an improvement in the wake prediction method due to the fact that by starting at the rear stagnation point, the strong gradients in the wake flow are ignored. Further examination of the starting point reference should be considered as future program improvements.

In Figure 25 most of the available data in the literature on the location of the rear stagnation point,  $x_0$ , behind bodies at supersonic speeds are shown. Included are data from both two-dimensional and axisymmetric bodies, Mach numbers from 4 through 16, and for a wide range of Reynolds numbers. Also shown is an approximate fit to the data for both the laminar and turbulent flow regimes. As indicated for laminar flow, the rear stagnation point moves closes to the base as the Reynolds number increases. This movement is based obviously on certain allowance for the wide data scatter and even wider discrepancy for a few individual points; the same trend also is noted in Reference 11.

However, this movement is not in agreement with information extracted from available theoretical results. For example, Reeves and Lees predict that the rear stagnation point moves away from the body with increasing Reynolds number for the adiabatic wall case  $(h_w = H_1)$  and the cold wall case  $(h_w = 0.2 H_1)$ . They further predict that the rear stagnation point will be closer to the body for the cold wall case than for the adiabatic wall case and that this former case will have a very weak Reynolds number dependence. This picture of the near wake perhaps can be reconciled to the data of Figure 25 by noting that the higher data points are in general wind tunnel data (e.g., Reference 17 and 22) and thus correspond more closely to the adiabatic wall case, while (-) hower data points are in general from ballistic range and shock-tunnel



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experiments and closely approximate the cold wall case. This, however, does not completely explain the discrepancy since the data point from Reference 18 also was obtained in a wind tunnel.

Obviously, the "exact" prediction of the location of the rear stagnation point is more complicated for laminar flow than presented in Figure 25. Still, the approximate fit in Figure 25 should prove useful for engineering calculations. Furthermore, for cylindrical wake calculations, the rear stagnation point location,  $x_0$ , is not needed. This is due to the complete similarity in profiles for different X/D stations. Also shown in Figure 25 are measurements of the location of the rear stagnation point at conditions where the boundary layer at the base of the forebody was turbulent. Although there are only a limited number of measurements for this case of turbulent flow, an approximate fit,

$$\frac{\mathbf{x}_{0}}{\mathbf{D}}\approx0.94,\qquad(13)$$

does appear to correlate well with the data. As can be seen, in this case there is no apparent dependence on Reynolds number.

As indicated earlier, it is also of interest to compare the prediction of the rear stagnation point enthalpy with available experimental data. By combining Equations 77 and 80 of Appendix IV, the expression for the rear sugnation point enthalpy is

$$\frac{H_o}{H_1} \left(\xi = 24\right) = 1 - \left(1 - \frac{h_w}{H_1}\right) \frac{u_B}{u_1} .$$
 (14)

Equation 14 is based on the equating of the momentum and total enthalpy defects of the wake to the respective quantities of the forebody boundary layer. If it is furthermore assumed that  $u_B = u_1$ ; the simple result then is

$$\frac{H_{o}(\xi = 24)}{H_{1}} = \frac{h_{w}}{H_{1}}$$
(15)

at the rear stagnation point. Equation 15 is compared with available experimental data for laminar flow in Figure 26. The measured values lie slightly higher than that predicted by Equation 15.

In order to correct the present theory such that the predicted rear stagnation point enthalpy will be in agreement with experiment, Equation 4 and Equation 80; Appendix IV, are rewritten as

$$\kappa_1 u^2 (\mathbf{x} \theta_1^2) = K_1 B u^2_B (\mathbf{x} \theta_B^2)$$

and

 $\gamma_1 v_1 H_1 (\pi \theta_{T_1}^2) = K_2 B_B H_B (\pi \theta_{T_B})$ 



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(16)



Here,  $K_1$  and  $K_2$  are constants that would be expected to be greater than or equal to one since they are representative of the fractional increase in the momentum and energy defects due to the transport of these quantities across the dividing streamline. Combining the above two equations with Equation 79, it follows that

$$\frac{9\frac{2}{T_1}}{\theta^2} = \frac{K_2}{K_1} \left\{1 - \frac{h_w}{H_1}\right\} + \frac{u_1}{u_B}$$

This may be substituted into Equation 77 with the result that

$$\frac{H_0(\xi = 24)}{H_1} = 1 - K_3 \left(1 - \frac{h_1}{H_1}\right)$$
(17)

where  $K_3 = K_2 u_1 / K_1 u_B$ .

Equation 17 has been approximately fitted to the laminar experimental data using a value of  $K_3 = 0.9$  and is shown in Figure 26. Although this value of  $K_3$  is strictly based on experiment and has no real theoretical basis, its use in Equation 17 for laminar wake calculations should prove useful.

For turbulent near wake now, there is only a smattering of data that may be found in the literature. These limited number of data points, however, are compared with Equations 15 and 17 for both  $K_3 = 0.9$  and  $K_3 = 0.65$ , in Figure 27. The latter value of  $K_3$  does give agreement with the data. The limited amount of data prevents any real recommendation for the use of  $K_3 = 0.65$  for turbulent wake calculations, and it is obvious that more data and more comparisons of data with theory are necessary before any degree of confidence can be placed in Equation 17 and on the use of an effective  $K_3$  for either laminar or turbulent flow. In Appendix IV where a method for viscous wake calculations is outlined, the constant  $K_3$  is left as an input.

As was noted in Item 3, the present integral theory would not be expected to give accurate results in the near wake region. Thus, the lack of





> agreement in Figures 26 and 27 is not surprising, and the introduction of an empirical constant,  $K_3$ , into Equation 17 only represents an attempt to improve the accuracy of the present solution in a region where it otherwise would not be expected to hold. However, in spite of the failings of the present method in predicting the rear stagnation point enthalpy, comparisons with experimental data have shown that in the prediction of neck diameter for a laminar wake the method in Item 3, <u>b</u> of this section is quite satisfactory.

Before leaving this discussion of the near wake, one last comment should be made with regard to the nature of the flow. It has been found experimentally that the near wake is very sensitive to the base geometry of the vehicle and also to the injection of any fluid at the base into the near wake. This latter effect is obviously of concern in wind tunnel experiments where instrumentation may be supported from the base of the forebody. However, it also opens up the possibility of somewhat controlling the wake characteristics of a vehicle through fluid injection. It is also of interest in the decelerator problem where due to the manner of decelerator deployment the problem of interest may in fact be one in which there is fluid injection.

In Reference 24 Noticer presents measurements that show a 50-percent change in the location of the rear stagnation point due to a nitrogen injection mass flow rate that is only 2 percent of that of the free stream based on base area of the forebody. Furthermore, in Reference 25 Bauer shows that a 3-percent injection rate using helium causes the wake recompression shock to completely disappear.

This sensitivity of the near wake to almost any external influence casts doubt on the applicability of any wake data obtained under conditions where components of the model support system, <u>e.g.</u>, struts, wires, or a sting, interfere with the flow. Thus, future efforts should include wind tunnel studies where such interference effects are not present.

4. INVISCID WAKE ANALYSIS

#### a. Inviscid Wake Characteristics

In order to fully describe the trailing wake behind a supersonic body, both the viscous inner wake and invisit outer wake characteristics, e.g., velocity, density, and temperature profiles, must be known. The calculation of the viscous inner, wake depends on the forebody boundary layer, and methods for handling both of these types of fluid mechanic phenomena have been previously described for both laminar and turbulent flow and including transition. The inviscid outer wake characteristics, on the other hand, depend on forebody bow shock wave strength and shape and the subsequent expansion over the aft portion of the body.

b Analysis

For the purpose of analysis, the wake of a supersonic vehicle is conridered where it is assumed that the vehicle bow shock wave shape and the pressure distribution along the wake axis is known from either experiment or theory. For blunt bodies at hypersonic speeds, blast wave

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theory may be used to approximate both the bow shock shape and the pressure distribution on the wake axis. For supersonic speeds, however, the pressure in the wake may be approximated as being equal to  $P_{o}$ , the free stream pressure.

From conservation of mass, a mass balance may be written that relates the mass flow in the free stream at the shock through a disk of radius  $R_s$  with the mass flow in the inviscid wake through a disk region of radius r. This relation is

$$\rho_{\infty} V_{\infty} \pi R_{\beta}^{2} = 2\pi \int_{\delta^{*}}^{r} \rho urdr . \qquad (18)$$

The integration on the right-hand side of Equation 18 starts at  $\delta$ , the wake displacement thickness instead of zero in order to account for the displacing of streamlines by the viscous wake phenomena. The wake displacement thickness is defined by the relation

$$\rho_1 u_1 \delta^{*2} \pi = 2\pi \int_0^0 (\rho_1 u_1 - \rho_0) r dr$$
 (19)

and may be determined using the viscous wake results.

Equation 18 may be considered to be a relation between properties on a streamline passing through a point on the bow shock at a shock radius  $R_s$  and properties on the same streamline dowrstream of the body at a point A, a distance r from the axis of the wake. With the bow shock shape known, then a specific value of  $R_s$  corresponds to specific properties immediately behind the bow shock for the streamline passing through that point. If it is assumed that the flow is isentropic in expanding from the shock wave on downstream to point A, then Equation 18 is a relation between two points with the same entropy, or, in other words, the same total pressure. The assumption of isentropic flow behind the bow shock and forebody flare shock) produce negligible changes in entropy. Although this assumption is possibly open to question, it simplifies the calculation of the inviscid wake properties and is in line with the other assumptions employed.

Equation 18 thus provides a means for calculating the total pressure or entropy at point A, a distance r from the wake axis. Furthermore, the total enthalpy is known since the inviscid flow may be considered adiabatic. Finally, with the pressure distribution along the axis of the wake known, an estimate of the static pressure in the inviscid wake can be made by assuming that there are no pressure gradients radially in the wake region i.e., dp/dr = 0. The complete state of the gas at a point A in the inviscid wake thus is completely specified in terms of the total pressure, the total enthalpy, and the static pressure In order to facilitate calculations using the above analysis, the following transformation is introduced:

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 $urdr = \rho V_{op} ndn$ ,

and

 $\mathbf{x}_1 = \mathbf{x}$ .

Equation 18 then may be rewritten as

$$\rho_{\infty} V_{\infty} \pi R_s^2 = 2\pi \int_{\delta_n}^n V n dn ,$$

or

$$R_s^2 = n^2 - (\delta_n^*)^2$$
, (21)

where  $\delta_n^{*}$  is the transformed splacement thickness, and

$$\rho_1 u_1 \left(\delta^*\right)^2 = \rho_0 V_0 \left(\delta_n^*\right)^2 .$$
 (22)

Thus, from Equations 21 and 27 and assuming  $\delta$  known from an analysis of the viscous wake, the entropy and total pressure at a point A, lying a distance n from the axis in the transformed plane, may be determined as being equal to the immediately behind the bow shock wave at a radius R. With the total pressure or entropy known for the streamline, and with an estimate of the static pressure, the local Mach number at point A may be determined. This, together with the total enthalpy, gives the static estimalty or temperature. The complete state of the gas, including the velocity and density, at such a point is thus specified, and the variation in fluid properties in the transformed  $(n, x_1)$  plane may thus be determined. In order to transform the results back into the (X, r)plane, Equation 20 may be used with the result that r and n are related by the equation,

$$\int_{\delta^*}^{\mathbf{r}} \mathbf{r} d\mathbf{r} = \int_{\delta^*}^{\mathbf{n}} \frac{\rho_{\infty} \mathbf{V}}{\rho_{\lambda}} \mathbf{n} d\mathbf{n} \quad . \tag{23}$$

Since  $\rho_{00}V_{00}/\rho_{01}$  is known as a function of n, this calculation may be readily carried out using numerical techniques for the integration. The variation of such fluid properties as velocity, Mach number, and temperature thus may be calculated as a function of r, the radial distance from the axis of symmetry.

Using this inviscid wake prediction method with the shock shape as determined from wind tunnel tests of an Arapahe C with nose cone forebody as an input, a good correlation between theory and experimental results has been obtained. Figures 8 through 23 show both the experimental

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> velocity data points obtained by reducing the measured pressure data and the inviscid wake theoretical predictions for Mach numbers of 2, 3, 4, and 5 for two Reynolds number conditions and for X/D values between 3 and 11. The starting point for the inviscid wake prediction is noted in the figures, and in all instances the theor, is within 10 percent of the experimental values. Thus, the degree of correlation is certainly acceptable for engineering calculations.

The accuracy of the inviscid wake theory will be limited to some extent by the accuracy of the inputted shock shape. In performing the mass flow balance, theory does not consider the embedded shock produced by the forebody flare or the recompression shock wave formed in the wake neck region due to the added complexity required to include those considerations.

Although there is some data scatter and also some difference between Y/D plane experimental values and the Z/D plane experimental values due in part to the fact that the Z/D values were measured in the plane of the strut, the extent of the correlation between theory and experiment is sufficient for engineering calculations in the wake. The accuracy of the correlation improves for larger values of X/D. In the region of X/D = 3 that is quite near the wake neck and the recompression wake shock, the wake prediction method, while still adequate, is less accurate.

### 5. ITERATIVE WAKE SOLUTION

In order to completely describe the characteristics of the viscous and inviscid wake, an iterative solution was performed to compute the viscous wake profiles. This was done in order to obtain continuous profiles of the wake properties across the total wake (viscous + inviscid) since the viscous wake edge conditions were originally calculated based on the flow through the normal portion of the bow shock wave (as per boundary layer analysis) and did not match the edge value obtained from the mass flow balance performed in the inviscid wake.

The iteration procedure, which has been programmed, computes the viscous wake properties based on a revised value of Mach number,  $M_1$ , at the edge of the viscous wake. The revised value of  $M_1$  is obtained from the mass flow balance performed in the inviscid wake analysis and is that value of  $M_1$  predicted by the mass flow balance corresponding to the edge location predicted by the initial viscous wake run. This new  $M_1$  value is used as an input for a second pass (first iteration) through the viscous wake program and the inviscid wake program. Although the above procedure could be repeated an indefinite number of times, initial results have shown that no more than three iterations are necessary to obtain complete matching of the viscous wake-inviscid wake, edge.

The results based on this iterative solution are shown in Figures 8 through 23. The best correlation for these turbulent viscous welle cases were obtained using Model 3 with a viscosity coefficient equal to 0.005. A correlation for laminar viscous wake has not been made using the iterative solution. This value of K = 0.005 is below the range of values (0.02 to 0.06) indicated in the literature as shown in Item 3, <u>c</u>. However, those values were obtained from standard boundary layer type solutions.

By performing the iteration solution that changes the consideration of the flow through the normal shock as in standard boundary layer theory to flow through a locally oblique shock as used on this program, the value of K yielding a satisfactory correlation has been changed. Prior to the use of the iterative solution with the viscous wake, reasonable correlations between experiment and theory were obtained for values of K = 0.025 with Models 3 and/or 4. Until more experimental data become available on the effects of other parameters (such as the wake neck as a starting point rather than rear stagnation point mentioned in Item 3, e of this section, on the results of the predictive method, an acceptable range of K values cannot be exactly determined. Thus, it is believed that the current use of K = 0.005 with the iterated solution is acceptable as an engineering solution insofar as achieving and maintaining a general theoretical approach to the wake description.

### 6. FLOW FIELD COMPUTER PROGRAM

An integrated computer program has been developed and programmed in FORTRAN IV for use on the IBM 360-40 and IBM 7094 computers. The program is based on the forebody program of Section II and the wake analyses of Section III.

The computer program can determine the properties of the inviscid and viscous wake preceding a decelerator and consists of the following sub-programs:

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- 1. Forebody flow field  $(M_L, \Gamma_L, and PT_L)$
- 2. Boundary layer, laminar and turbulent  $(\theta, M)$
- 3. Viscous wake, laminar and turbulent  $(M_L, P_L)$  and  $T_L$
- 4. Inviscid wake  $(M_L, P_L, and T_L)$
- 5. Iteration (on Items 3 and 4 above)

The following inputs must be specified to utilize the integrated program:

- 1. Free stream conditions
- 2. Forebody geometry and wall temperature
- 3. Bow shock shape
- 4. Boundary layer constant, K (0 or 1)
- 5. Wake constants, K and K<sub>3</sub>
- 6. Number of iterations to be performed

Optional inputs (which will be calculated in the program if not specified) include:

1. Boundary layer transition Reynolds number or transition point location

2. Forebody flow field  $(M_L, P_L, and P_{T_L})$ 

Copies of this computer program may be obtained from AFFDL(FDFR), WPAFB, Ohio 45433 by request.

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#### SECTION IV

#### PARASONIC PARACHUTE PERFORMANCE

### 1. PERFORMANCE FACTORS

The performance of PARASONIC parachutes is described according to two basic criteria: drag and stability. The primary facurs that influence the performance are listed below. ころのない 東京の東京の

- 1. Canopy shape
- 2. Canopy porosity
- 3. Free stream Mach number
- 4. Free stream Reynolds number
- 5. Forebody shape
- 6. Downstream location of the canopy inlet (X/D)
- 7. Ratio of canopy area to forebody base area  $(A_c/A_b)$

The first two parameters, canopy shape and orosity, were held constant in this performance evaluation. All parachute testing was conducted with PARASONIC parachutes, thereby constraining the canopy shape. The selection of PARASONIC parachutes was made based on the high degree of inflation stability and structural integrity exhibited by these parachutes. The FARASONIC parachutes are members of the Hyperflo family of supersonic parachutes and are distinguished from standard Hyperflo parachutes by comparison of canopy profiles. The PARASONIC parachutes are constructed with an uninflated shape which approximates the fully inflated shape of a standard Hyperflo parachute (see Figure 28). When inflated, the PARASONIC canopy is free from excess material, thereby reducing "flagging" loads which have been found to lead to premature canopy failure. The porosity was held constant for all parachutes to further limit the number of variables.

An experimental iest program was conducted to determine the effects of the remaining parameters on the PARASONIC parachute performance. The analysis of the effects of these parameters is presented herein. The experimental test program is discussed in detail in Appendix V.

# 2. WIND-TUNNEL TEST SUMMARY

The PARASONIC parachutes described above were deployed behind the three forebody configurations shown in Figure 29. The basic  $Ara_{1}$  to C forebody is a 0.182-scale model of the Arapaho C free-flight test vehicle and consists of a probe nose; a cylindrical centerbody; and a symmetrical, flared afterbody. The Arapaho C with nose cone forebody has a centerbody and afterbody identical to the basic Arapaho C; however, the probe nose was replaced with a conical nose with a spherical tip. The third


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Figure 29 - Forebody Model Details

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forebody consisted of a blunted elliptical cone with a nose shape identical to the nose used on the second forebody.

Two types of PARASONIC canopies were tested. One type was constructed with a prewoven Nomex fine-mesh cloth as the roof inaterial, and the second type was constructed with a hand-woven coarse-mesh roof. Two canopy sizes were tested so that a canopy area to forebody base area ratio of 3.425 could be obtained for all forebodies. As stated earlier, all canopies were constructed with the same total aerodynamic porosity. The construction details for the parachute models are shown in Appendix V.

Two series of parachute performance tests were conducted under this program. The first series of tests (WT-IIB) was of sufficient scope to produce enough data to determine the effects of the aforementioned parameters on the parachute performance. The second series of performance tests (WT-VI) was conducted using a redesigned drag measurement system to obtain data having a higher degree of accuracy as the comparative basis for the drag predictive method discussed in Section V. The results of this series of tests were also used to validate the results of the first series of tests. A summary of the test conditions for both series of tests is shown in Table IV.

Results obtained from the parachute performance tests are presented in Appendix V. Both drag and stability parameters were determined. The base pressure to free stream static pressure  $(P_b/P_{co})$  values were recorded to indicate the degree of modification of the forebody wake due to the proximity of the attached decelerator. Table V lists the  $P_b/P_{co}$ ratios for the three forebodies without a decelerator immersed in the inner wake.

Comparison of the values in Tables V with the results presented in Appendix V gives an indication of the degree of wake modification. The remaining parameters listed in Appendix V describe the stability and drag characteristics of the parachute. General stability comments are discussed in Light 8, below.

# 3. MACH NUMBER EFFECTS

Figures 30 and 31 illustrate the effects of the free stream Mach number on the drag coefficient of PARASONIC models behind the Arapaho C with nose cone and the blunted elliptical cone forebodies. The trend of decreasing drag coefficient with increasing Mach number shown in these figures is typical of supersonic parachute performance. The Mach number effect, however, is interrelated with forebody shapes, parachute axial location (X/D), and canopy to forebody base area ratio ( $A_c/A_b$ ). The major interrelationship of interest is the combination of Mach number, X/D, and A /A, values at which severe modification of the forebody wake is encountered. It has been found that for a given forebody-parachute combination, the axial location at which severe modification is encountered increases as the free stream Mach number increases. Further discussion found atter station of the free stream Mach number and other influencing of the severe is presented in applicable sections.

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				9 (p	oo si)	X/D	
Forebody	oody Mesh A <sub>c</sub> /A <sub>b</sub> M <sub>∞</sub>		M <sub>co</sub>	Min	Max	Min	Max
WT-IIB							
Basic	Small	3. 425	2, 3, 4, 5	0.5	1.5	45	8
Arapaho C	Large	3. 425	2, 3, 4, 5	0.5	1.5	4.5	8
	Small	5.9	3, 4	0.5	1.5	6.0	9
	Large	5.9	3, 4	0.5	1.5	6.0	8
Blunted elliptical	Small	1.99	2, 3, 4, 5	0.5	1.5	4.0	8
cone	Large	1.99	3, 4	0.5	1	4.0	8
	Small	3. 425	2, 3, 4, 5	0.5	1.5	4.5	8
	Large	3. 425	2, 3, 4, 5	0.5	1.5	4.5	8
Arapaho C with	Small	3. 425	2, 3, 4, 5	0.5	1.0	4.5	8
nose cone	Large	3. 425	2, 3, 4, 5	0.5	1.0	4.5	8
	Small	5.9	3, *4	0.5	1.0	6.0	10
	Large	5.9	3, 4	0.5	1.0	6.0	10
WT~VI		ĺ					
Arapaho C with	Small	3. 425	2, 3, 4, 5	1.0	1.0	5.0	7
nose cone	Large	3. 425	2, 3, 4, 5	1.0	1.0	5.0	7
Blunted elliptical	Small	3. 425	2, 3, 4, 5	0.5	0.5	5.0	7
cone	Large	3. 425	2, 3, 4, 5	١.5	0.5	5.0	7

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# TABLE IV - PARACHUTE FERFORMANCE TEST CONDITIONS SUMMARY

# TABLE V - FOREBODY $P_b/P_{\infty}$ RATIOS

	P <sub>b</sub> /P <sub>∞</sub>						
Forebody	$M_{\infty} = 2$	$M_{\infty} = 3$	$M_{\infty} = 4$	M <sub>00</sub> = 5			
Basic Arapaho C	0.56	0.25	0.23	0.24			
Arapaho C with nose cone	0.50	0.24	0.19	0.17			
Blunted elliptical cone	0.49	0.29	0.17	0.15			

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#### 4. **REYNOLDS NUMBER EFFECTS**

In all cases during the parachute performance tests, the Reynolds numbers were such that the boundary layer at the base of the forebody was turbulent; the viscous portion of the wake was, therefore, also turbulent. Any variations in parachute drag due to operation in a laminar viscous wake could not, therefore, be determined. Ser. No.

The variation of parachute drag behind a given forebody depends on the profile of the flow field entering the parachute. A slight variation of velocity profiles with a variation in total pressure can be seen in Figures 8 through 15. For the wake survey tests, the temperatures were held constart at each Mach number; the variation of Reynolds number can be directly related with the variation of total pressure. Considering that the Reynolds number variation for the parachute tests was approximately half the variation for the wake survey tests, and that the wake profiles shown in Figures 8 through 15 do not indicate significant variations with Reynolds number, it can be safely assumed that the changes in parachute drag over the range of Reynolds numbers tested will be very slight.

From the wind-tunnel test results of WT-IIB, a slight correlation between variations of Reynolds number and variations of drag coefficient magnitude was observed. However, inaccuracies of the drag measurement system may have affected the repeatability of these slight trends. Figures 32 through 35 illustrate the effect of the free stream Reynolds



Figure 32 - Drag Coefficient versus Unit Reynolds Number, Basic Arapaho C Forebody (M = 2 and 3)



Figure 33 - Drig Coefficient versus Unit Reynolds Number, Basic Arapaho C Forebody ( $M_{\infty} = 4$  and 5)



Figure 34 - Drag Coefficient versus Unit Reynolds Number, Blunted Elliptical Cone Forebody ( $M_{\infty} = 2$  and 3)

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Figure 35 - Drag Coefficient versus Unit Reynolds Number, Blunted Elliptical Cone Forebody ( $M_{co} = 4$  and 5)

number on various for ebody-parachute combinations. The canopy location of X/D = 6 was chosen because of the near optimum performance exhibited by the parachutes at this location.

The figures indicate that, behind the blunted elliptical cone model, there is a slight increase in drag coefficient with an increase of Reynolds number. However the Reynolds number trends appear to be reversed for the axisymmetric forebody. An explanation of this trend reversal has not been determined.

# 5. FOREBODY EFFECTS

Of the three forebody models used in the parachute performance testing, two (the busic Arapaho C and the Arapaho C with nose cone forebodies) were axisymmetric; the third (blunted elliptical cone) had an elliptical cross section at the base. The third model was tested to simulate the wake of a lifting re-entry body.

The forebody effects on drag coefficient magnitudes are shown in Figure 36. The data shown on this figure were obtained from the second series of tests (WT-VI) and reflect a high degree of accuracy. The data indicate the effects of forebody asymmetry on parachute performance. The PARASONIC performance appears to have a higher degree of Mach number sensitivity in the wake of the asymmetric forebody as opposed to the axisymmetric forebody. The forebody effect is most

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Figure 36 - Drag Coefficient versus Mach Number, Blunted Elliptical Cone and Arapaho C with Nose Cone Forebodies

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apparent at  $M_{00} = 3$ . At  $M_{00} = 2$ , the effect is not quite as apparent; however, the  $M_{00} = 2$  data for the axisymmetric forebody may be in error due to slight damage of the canopy suspension lines. This damage is discussed further in Item 6, below. At  $M_{00} = 5$ , the low drag coefficient values for the blunted elliptical cone data are attributed to severe wake modification. This also is discussed further in Item 6. Same Brits & Brits

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#### 6. CANOPY AXIAL LOCATION EFFECTS

The axial location of the canopy aft of the forebody was found to become critical at the extreme ends of the X/D range tested. At the near X/D locations (X/D = 4 to 4.5), the proximity of the canopy to the forebody base resulted in severe wake deformations. In some cases, the modification was of such severity that the wake was considered to be "blown;" <u>i.e.</u>, flow leaving the forebody base separates and passes around, rather than through, the canopy. In the blown wake conditions the flow field entering the canopy is subsonic and an extremely low drag coefficient results. At canopy inlet locations greater than X/D = 7, the oscillation stability was found to be very time dependent and, at times, the oscillations became divergent in nature. The breathing action of the parachute also appeared to be X/D dependent, with the magnitude of the breathing increasing with decreasing distance between canopy and forebody base. From a stability standpoint, therefore, the optimum location of the canopy inlet was found to be at approximately X/D = 6.

Figure 30 indicates that at the X/D = 6 canopy inlet position, the drag coefficient is also optimized. When the Mach number 2 data (which do not follow this trend) are examined in more detail, and specifically the oscillation angles associated with these data points, it can be shown that the upper two data points exhibited oscillation angles varying from 10 deg to 13 deg; the middle two data points, angles from 6 deg to 8 deg; and the lower two data points, no oscillations. The three data points for the small-mesh parachutes at the Mach 2 conditions were affected by a near failure of the parachute. Immediately after completion of the Mach 2 points, inspection of the small-mesh parachute indicated some slippage of the suspension lines at the point of attachment to the swivel. The slippage of the suspension lines was such that the parachute inletwas no longer normal to the flow.

The drag coefficient data presented in Figure 35 for the blunted elliptical cone model also indicates a near opti. um canopy location at X/D = 6 except for the Mach number 5 conditions. For X/D's = 5 and 6 at  $M_{\infty} = 5$ , and X/D = 5 at  $M_{\infty} = 4$ , the modification of the wake was such that the parachute inflated with an elliptical shape normal to the flow with the major axis of the elliptical canopy in the same plane as the major axis of the elliptical forebody base. The degree of ellipticity was most severe at the  $M_{\infty} = 5$ , X/D = 5 test point. At these test points, the canopy was virtually motionless.

# 7. PARACHUTE TO FOREBODY BASE AREA RATIO EFFECTS

The parachute to forebody base area ratios  $(A_c/A_b)$  varied only during the first series of parachute performance tests (WT-IIB), and the data accuracy may have influenced any slight trends. The  $A_c/A_b$  effects can

> be seen on Figures 32 to 35. It does appear that the smaller A /A ratios exhibit slightly smaller drag coefficient values for the blunted elliptical cone data. For the smaller area ratio (1.99), the viscous portion of the wake is considered to have a noticeable effect on the drag coefficient value. The trend of smaller drag coefficient values with the smaller area ratio is not apparent in the Basic Arapaho C data. In this case, the smaller area ratio (3.425) is great enough that the viscous portion of the wake has little effect on the drag coefficient.

> The primary effect of  $A_c/A_b$ , as discussed previously, is associated with the canopy location at which wake modification is encountered. Reference 32 indicates that the X/D position of the parachute behind the forebody at which wake modification occurs is directly proportional to the ratio of the parachute size to the forebody size. The results of the wind-tunnel tests conducted under this program tend to substantiate this statement. At the  $M_{00} = 5$ , X/D = 6 conditions (WT-IIB) for the blunted elliptical cone tests, severe canopy breathing and wake modification were encountered for the  $A_c/A_b = 3.425$  test points. However, for  $A_c/A_b = 1.99$  at the same Mach number, no adverse effects were encountered at X/D = 6, and only slight wake modification observed at X/D = 5. Similar effects were observed with the axisymmetric forebodies; however, the effects were not nearly so severe.

#### 8. GENERAL STABILITY

It was observed that with the decelerator positioned at a large X/D location, the oscillations induced in the parachute became divergent in nature, and axial repositioning was required.

The observations led to the conclusion that a near optimum X/D position should exist where the minimum inflation-oscillation instability is present. This near optimum X/D position was observed to be at X/D = 6.

The drag oscillation frequency  $(f_i)$  does not appear to be Mach-number dependent within the range tested. The canopy oscillation angles (Q) and oscillation frequencies  $(f_Q)$  show a decrease in magnitude with increasing Mach number. The breathing frequencies  $(f_b)$  did not appear to be Machnumber dependent. However, behind the blunted elliptical cone, the breathing pulsations were time dependent and usually of small magnitude so that breathing frequencies could not be determined. This indicates that although the drag coefficient experiences degradation with increasing Mach number, the stability is enhanced.

The canopy oscillations were of different form behind the two forebodies. Behind the basic Arapaho C, the oscillations were predominately of the coning type in which any point on the riser line follows a circular path in a plane normal to the direction of flow. Behind the blunted elliptical cone, few coning oscillations were observed. Oscillations behind the blunted elliptical cone were predominantly in the vertical plane. However, in some cases at far X/D positions, the oscillations in the vertical plane were combined with higher frequency oscillations in the horizontal plane. A point on the riser line, then, traces a zig-zag path. Unfortunately, frequencies and amplitudes could not be determined for oscillations in the horizontal plane.

Inflation stability for parachutes overating behind the blunted elliptical cone was highly X/D sensitive. In the ot all cases with the largediameter parachute positioned at X/ 4.5, severe canopy breathing pulsations and wake deformations were inconcurred. Behind the basic Arapaho C, at the same X/D,  $A_c/A_b$  right and with the same roof mesh, canopy breathing pulsations and wake deformities were less severe. 19.16、14.14 19.16(19.14)

Throughout the tunnel tests, on-line observations indicated that the canopy was assuming an elliptical shape normal to the direction of flow while operating behind the blunted elliptical cone. The direction of ellipticity increased with increasing Mach number and decreating canopy X/D location. This ellipticity could not, however, be determined from the photographic coverage.

The type of roof mesh was found to have little effect on oscillation amplitudes or frequency, but to have an effect on inflation stability (breathing pulsations). The large-mesh canopies, being much more rigid than the small-mesh canopies, did not exhibit the high-frequency, low-amplitude canopy flutter observed with the small-mesh canopies. The largemagnitude canopy pulsations, referred to as breathing, were encountered with both canopies.

# SECTION V

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# DRAG PREDICTION

#### 1. GENERAL

This section presents a method for calculating the pressure drag of PARASONIC parachutes operating in supersonic axisymmetric wakes. The method uses the local wake profiles as the flow environment and the flow through a curved shock wave to determine pressure distribution on the parachute canopy. This is a great improvement over previous methods (Reference 33), which assume flow conditions at the parachute inlet equal to the free stream conditions ahead of the forebody and a normal shock standing at the parachute inlet. The canopy flow field in this analysis is determined using the following basic assumptions:

- 1. A detached, curved, shock is present ahead of the canopy inlet.
- 2. The presence of the canopy in the wake produces negligible distortions of the wake flow field.
- 3. The flow is sonic through the roof grid.
- 4. The flow stagnates at solid portions of the canopy roof.
- 5. Secondary effects due to separated flow and skin friction can be largely ignored.

#### 2. FLOW FIELD ANALYSIS

The flow analysis begins with the determination of the local flow parameter profiles in the wake. The most important parameters required for this analysis are the local Mach number  $(M_L)$ , static pressure  $(P_L)$ , pitot pressure  $(P_{t_1})$ , and dynamic pressure  $(q_L)$ . These profiles, obtained either from experimental tests or suitable analytical prediction as described in Section III of this report, represent wake profiles that are free from any adverse effects caused by the presence of a trailing body in the wake flow field. The "free" wake profiles, therefore, cannot be considered valid for the cases in which the trailing parachutes have been known to modify the wake structure radically. Figures 37 and 38, traced directly from schlieren photographs obtained during wind-tunnel tests (Section IV), illustrate the effect of the parachute axial positioning on the wake flow structure. The flow-field modification is quite evident with the parachute inlet positioned at X/D = 4.5. With the parachute inlet positioned at X/D = 8, however, the wake trailing shock does not appear to be deformed. The position of the trailing shock indicates, however, that the presence of the parachute causes a slight widening of the wake neck. This slight modification of the wake is not considered. in the drag prediction analysis.

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Figure 37 - Wake and Parachute Shock Structure ( $M_{\infty} = 3$ )



Figure 38 - Wake and Parachute Shock Structure ( $M_{oo} = 5$ )

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> On the assumption that the wake profiles have been determined, the next step in the flow analysis is to select profiles at an axial station immediately ahead of the canopy oblique shock. When this procedure is used, the influence of the parachute confluence point and suspensionlines on the flow field is neglected. This simplifies the analysis but may influence the accuracy of the predictive method.

Analyses of schlieren photos show that two general types of shocks appear around the supersonic parachute: detached inline shocks and attached shocks at the canopy inlet. The shape and stand-off distance of the inline shock is determined by the local Mach number profile and the aerodynamic porosity of the canopy (Reference 34). The shape of the attached shock is determined by the shape of the canopy and by the Mach number provide behind the parachute inline shock and is present only when the flow at the inlet edge is supersonic. The shap of the attached inlet shock need not be known for the drag prediction analysis. The shape of the inline shock must, however, be known in order to determine the pressure distribution inside the canopy. The shape of the inline shock, unfortunately, is not easily predicted. The shock wave oscillations encountered with relatively low-porosity canopies (Reference 34) along with the interaction of the shock wave and the flexible suspension lines result in a very unstable inline shock and, therefore, a nonsteady flow field entering the canopy inlet. Inflation and oscillation stability also affect the stability of the inline shock. The flow analysis, then, assumes the canopy to be motionless and the inline shock to be quasisteady.

Analysis of the schlieren photos indicate one other interesting phenomenon associated with the catopy inline shock. In some cases a seemingly intense and steady inline shock would lose its identity at the very center. This "hole" in the center of the shock indicates subsonic flow conditions at the wake centerline. The subsonic core at the wake centerline is most probably caused by the formation of a wake by the parachute attachment swivel and confluence ring. In cases where the forebody wake centerline velocity is at low supersonic velocities, further deceleration of the flow by the swivel and confluence ring then results in a subsonic core of air entering the parachute inlet.

#### 3. CANOPY PRESSURE DISTRIBUTION

The pressure distribution on the supersonic parachute canopy is determined by two flow paths: internal, through the canopy, and external, around the canopy. The flow field in which the canopy is engulfed as influenced by the detached oblique shock ahead of the canopy. With free stream profiles obtained from experiment or from the method described in Section III and a detached shock wave shape determined from either experiment or some applicable predictive method, flow parameters aft of the detached shock wave may be determined by the use of oblique shock relations. Both the total and static pressures are required to determine the pressure distribution on the canopy. In the absence of fu, ther perturbations aft of the shock waves, the parameters are combined within stream layers. If the shock is discontinuous at the wake centerline region, the flow is still considered isentropic and is treated as one-dimensional and compressible.

The axial velocities in the stream layers are assumed to stagnate on the solid portions of the canopy mesh and on the canopy roof cap (see Figure 37). The surfaces of the canopy skirt, however, are assumed to be acted upon by the static pressure of the stream layer entering the parachute at the inlet edge. The parachute canopy acts as a supersonic diffuser in that the flow inside is decelerated, and the kinetic energy of the flow is converted to a pressure rise. At each mesh opening the flow is assumed to be sonic; the static pressure in the opening is then

$$P_e = 0.528 P_{t_e}$$

The external flow influence on the canopy is divided into two regions. The first region is skirt surface, beginning at the inlet edge and ending at the juncture of the skirt material and the roof mesh. From the leading edge of the skirt to the point of maximum camber, the skirt is assumed to have a constant slope, and the pressures on this surface are assumed to follow conical flow theory. Along the skirt surface aft of the point of maximum camber, the flow expands and is assumed to be analogous to the flow over a ring-type airfoil, whereon the pressure coefficient along the upper surface may determined from Reference 35 as

$$C_{\mathbf{p}} = \frac{2}{\beta} \left( \frac{\mathbf{a}}{\mathbf{b}} - \boldsymbol{a}_{\mathbf{o}} \right)$$

#### 4. PRESSURE DRAG COEFFICIENT EVALUATION

The pressure drag associated with a superscnic parachute is the major drag component, and its analytically determined magnitude is an accurate estimation of the total drag of the parachute. Determination of secondary drag components is beyond the scope of this analysis. The pressure drag is evaluated using the method described below.

The pressure drag is evaluated by a summation of the axial components of the pressure differential acting on the parachute canopy (see Figure 40).

Examining a ring of radius r. and width ds, the tangent at point A intersects the parachute conterline at an angle  $\phi$ . The surface area of the ring is then

$$dA_{auxef} = 2\pi r ds$$
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therefore,

The pressure differential acting on the ring is

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# Figure 39 - Parachute Flow Environment

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Figure 40 - Canopy Cross Section

and the force perpendicular to the surface is the pressure differential multiplied by the surface area. The component of the force parallel to the parachute centerline is the axial drag force and can be expressed as

$$dD = \Delta P dA_{suri} \sin \phi$$
  
= -\_a \D P csc \overline sin \overline rdr  
= 2\pi \D P rdr .

The pressure drag of the canopy is equal to

$$D_{\mathbf{p}} = q_{\infty} C_{\mathbf{D}_{\mathbf{p}}} A = 2\pi \int_{\mathbf{r}_{0}}^{\mathbf{r}_{i}} \Delta \mathbf{P}_{i} d\mathbf{r}$$

and the drag coefficient is then

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$$C_{\rm DP} = \frac{2\pi}{q_{\infty} (\pi R^2)} \int_{r_0}^{r_i} \Delta Pr dr .$$

Simplified and put in nondimentional form, the radii are

$$C_{DP} = \int_{\frac{r_{o}}{R}}^{\frac{r_{i}}{R}} \frac{\Delta P}{q_{o}} d(\frac{r_{o}}{R})^{2}$$

For regions of constant pressure differential, the incremental pressure drag coefficient can be expressed as

$$\Delta C_{DP} = \frac{\Delta P}{q_{\infty}} \left[ \left( \frac{r_i}{R} \right)^2 - \left( \frac{r_o}{R} \right)^2 \right]$$

To simplify the calculation procedure, this equation may be rewritten as

$$\Delta C_{\rm DP} = (C_{\rm P internal} - C_{\rm P external}) \left[ \left( \frac{r_{\rm i}}{R} \right)^2 - \left( \frac{r_{\rm o}}{R} \right)^2 \right]$$
$$\Delta C_{\rm DP} = \Delta C_{\rm P} \left[ \left( \frac{r_{\rm i}}{R} \right)^2 - \left( \frac{r_{\rm o}}{R} \right)^2 \right] .$$

The total pressure-drag coefficient is then

$$C_{DP} = \sum_{i=1}^{n} \Delta C_{DP_i}$$

# 5. RESULTS

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Using the methods described in Item 4 above, several sample calculations were made and compared to drag coefficient values obtained in experimental tests (Appendix V). For the sample calculations, the para chute canopy was broken up into 11 annular rings, each assumed to have a uniform pressure differential across its surface. The location and size of these integration strips was based on the construction of the parachute models tested and on the pressure distribution on the canopy. Figure 39 shows the canopy construction and the coordinates of the integration strips.

Strips 1 through 3 make up the total skirt surface. Strips 4 through 9 comprise the mesh portion of the canopy roof. These strips are divided into open and closed areas. Strips 4 and 6 are the open strips and equal the total open area of the canopy. Strips 10 and 11 correspond to the non-porous cap on the canopy roof. The choice of 11 integration strips was deemed sufficient for obtaining reasonable results from the initial calculations.

The was profiles used for the initial calculations were obtained from

> wind-tunnel tests (Appendix V). The wake profiles were obtained in both horizontal and vertical planes during the wind-tunnel tests. However, the forebody mounting strut was in the horizontal plane, and the wake n.casurements in that plane were considered to be influenced by the wake of the strut. The wake profiles in the vertical plane were then used and were assumed to be axisymmetric. The shock shapes were obtained directly from schlieren photographs of the test items. From the shock shape and wake profiles, the conditions aft of the shock were determined. A first assumption was that the streamlines aft of the shock remain parallel to the wake axis. The results of computations made using this assumption indicated that accounting for any radial transposition of the streamlines would not substantially increase the accuracy of the calculation method.

Table VI lists the conditions and calculated values for one of the test cases. In Figure 41, results obtained using the drag predictive method are compared with experimental wind-tunnel data (Section IV). Table VII presents the same data in tabular form. The selection of canopy axial positioning at each Mach number was based on parachute stability and the availability of a well defined shock shape from schlieren photographs. As can be seen, there is good correlation between the calculated and experimental values. In most of the test cases the calculated values have smaller magnitudes than the corresponding experimental data. The accuracy of the method does not appear to be highly Mach-number dependent; however, as the Mach number increases, the possibility of wake modification due to proximity of decelerator and forebody becomes greater.

Wake profile parameters											
Y/D	P <sub>l</sub> (psf)	м <sub>1</sub>	θ	M <sub>1</sub> sin 0	P <sub>2</sub> (psf)	P <sub>t2</sub> (psf)	с <sub>р2</sub>	C <sub>pt2</sub>	C <sub>pe</sub>	C pconical <sup>†</sup>	C <sub>pext</sub> ‡
0	28.40	0. 70		0 5 5	• • •	30.4 <sup>.</sup>	• • •	. 0756			
0.2	28.40	1.70	44 <sup>0</sup>	1.18	41.4	66.9	. 0904	. 267	. 048		• • •
0.3	27.60	1. 92	40 <sup>0</sup>	1.23	44. J	68.8	. 114	. 286	. 055		
0.5	28. <b>8</b> 0	2.70	38 <sup>0</sup>	1.66	87.8	116.8	. 410	. 610	. 228		• • •
0.6	28.20	2.76	38 <sup>0</sup>	1.70	90.4	119.0	. 431	. 630	. 241	. 360	. 017

# TABLE VI - SAMPLE CALCULATION DATA

\*These data were calculated at the following free stream conditions: (1) parachute -  $M_{00}$  = 3.00,  $q_{00}$  = 0.98 psi, Re/in = .069 × 10<sup>6</sup>, X/D = 6.0,  $P_{t00}$  = 5.7 psi; and (2) wake measurements -  $M_{00}$  = 3.00,  $q_{00}$  = 1.01 psi, Re/in. = .069 × 10<sup>6</sup>, X/D = 3.  $P_{t00}$  = 5.9 psi.

<sup>+</sup>Conical flow theory

<sup>‡</sup>Ring airfoil theory





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M <sub>∞</sub>	x/d	с <sub>DP</sub>	(C <sub>D</sub> ) exp	$C_{DP}/(C_{D}) \times 100$
2	5	0.734	0.850	86.4
	7	0.873	0.950	92.0
3	5	0.585	0.494	118.3
	6	0.482	0.563	85.7
4	5	0.369	0.423	87.3
	7	0.361	0.340	106.0
5	6	0.260	0.376	69.2
	7	0.320	0.342	93. 5

# TABLE VII - EXPERIMENTAL AND CALCULATED DRAG COEFFICIENT VALUES

The pressure drag is the major drag component, and the theoretically determined drag magnitude is an excellent indication of the supersonic parachute performance. Evaluation of other drag-influencing parameters listed below could possibly enhance the accuracy of the predictive method.

- 1. Skin friction
- 2. Separated flow effects
- 3. Confluence point and suspension line effects
- 4. Effective porosity variation due to flow compressibility

Calculation of drag components attributed to these phenomena does not appear practical from an engineering standpoint; therefore, only trends are discussed.

The skin-friction drag can be neglected without sacrificing appreciable accuracy. The drag component attributed to separated flow effects may have a slight effect on the accuracy; however, evaluation of this component does not appear practical. The influence of the confluence point and suspension lines has been studied (Reference 34), and results indicate that the number of suspension lines does affect the internal pressure distribution on the canopy. The effect of the confluence point and suspension lines has been taken into account somewhat in that the shock shapes used for the initial calculations were obtained in the presence of the confluence point and suspension lines. The variation of effective porosity with Mach number does not appear to be an appreciable factor when dealing with the low porosities associated with supersonic parachutes.

Recommendations for future work are included in Section VII.

# SECTION VI

# CONCLUSIONS

- 1. A method of solution was developed to predict the flow field properties as well as the boundary layer momentum thickness and momentum defect over axisymmetric, asymmetric, and two-dimensional forebodies.
- 2. A method of solution was developed to predict the properties of the wake flow field behind an axisymmetric forebody in a supersonic free stream.
- 3. These methods have been programmed in FORTRAN IV. Results using this program have shown good agreement with experimental wake results over a large range of free-stream Mach numbers and axial locations aft of the forebody base.
- 4. A method for calculating supersonic parachute drag using wake profiles as free-stream conditions was developed.
- 5. Results using the parachute drag predictive method have been compared with experimental data and good agreement has been shown.
- 6. The results of the PARASONIC parachute performance tests indicate that, although the drag coefficient decreases with increasing Mach number, stability generally is enhanced. The effects of wake asymmetry on parachute performance became more pronounced as the Mach number increased. The drag coefficient values did not show any repeatable trends associated with Reynolds number or type of roof mesh.

## SECTION VII

# RECOMMENDATIONS

# The following tasks are recommended as desirable improvements to the forebody, wake, and decelerator analyses:

- 1. Forebody analysis Improve the turbulent boundary layer momentum defect calculation by using advanced methods for determining body friction coefficients
- 2. Viscous wake analysis
  - a. Better determine the starting point for the wake calculation and consider modification of the starting point from the rear stagnation point to the viscous wake neck
  - b. Extend the analysis to flows with Prandti number not equal to 1
  - c. Include the effect of axial pressure gradient (this would increase the complexity of the analysis)
  - d. Develop a solution for the near wake region (this would require a major effort).
- 3. Inviscid wake analysis
  - a. Include the effect of radial pressure gradients
  - b. Account for the effect of embedded oblique shock wakes (wake recompression shock and flare shock) on the inviscid wake profiles
- 4. Wake solution
  - a. Investigate methods for matching the viscous wake and inviscid wake edge conditions
  - b. Apply the wake solution to additional experimental data to determine the choice of viscosity model and viscosity coefficient that best correlates theory and experiment
  - c. Ferform a sensitivity analysis to determine which modifications to the analysis method will improve the solution the most
- 5. Drag prediction
  - a. Extend the drag predictive analyses to apply to nonporous decelerators
  - b. Conduct experimental tests on rigid decelerator models of simple geometry (for example, cores and spheres) and correlate with analytical results

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# APPENDIX I

# BOUNDARY LAYER THEORY

# 1. LAMINAR BOUNDARY LAYER THEORY

For the methods developed by Kemp, Rose, and Detra (Reference 1) for calculating boundary layer properties and, in particular, calculating momentum thickness ( $\theta$ ), Stetson (Reference 6) has presented an empirical correlation of the results of the numerical solutions for  $\theta$ , which is given by

$$\theta = \frac{\sqrt{2\xi}}{\rho_e u_e r^k} (0.491)(1 - 0.090\beta^{0.4}) (\rho_e \mu_e / \rho_w \mu_w)^{0.386}.$$
 (24)

Here,

$$\xi = \int_0^s \rho_w \mu_w u_e r^{2k} ds$$

and s is the distance from the stagnation point as measured along the surface of the body: k = 0 for two-dimensional flow, and k = 1 for axisymmetric flow. For nonaxisymmetric flow, one of these two cases must be used as a suitable approximation. For example, a flat delta of small thickness ratio is best approximated as a two-dimensional body, while an elliptical body with its major and minor axes on the same order of magnitude is more suitably approximated as a quasiaxisymmetric body (k = 1).

In the above equations, the subscript e denotes local conditions at the edge of the boundary layer, while w denotes local gas conditions at the wall. The effect of  $\beta$ , the pressure gradient parameter, is small in Equation 24. This can be seen since  $\beta$  ranges from one at a two-dimensional stagnation point to zero in a zero pressure gradient region; thus, a typical value for  $\beta$  represents no more than a 10 percent correction.

In Equation 24,  $\xi$  represents an effective surface distance that considers the prior boundary layer history. For purposes of calculation, can be rewritten as

$$\xi(s) = P_{s} V_{\infty} \frac{\mu w}{R_{1} T_{w}} R^{2k+1} \xi^{*},$$
 (26)

where

$$\xi^{*} = \int_{0}^{s/R} \frac{P_{e}}{P_{s}} \frac{u_{e}}{V_{\infty}} \left(\frac{r}{R}\right)^{2k} d\left(\frac{s}{R}\right) . \qquad (27)$$

 $P_s$  is the forebody nose stagnation pressure,  $V_{CD}$  the free-stream velocity, and R the base radius for an axisymmetric body or an effective base radius for a nonaxisymmetric body; assuming  $\mu/RT = constant$ .

The boundary layer momentum thickness,  $\theta$ , can be rewritten in terms of  $\xi^{\pm}$ . The result is

$$\frac{\theta}{R} = \frac{\sqrt{2} (0.491) (1 - 0.090\beta^{0.4}) \xi^{\frac{1}{2}}}{\left(\frac{\rho_{e} u_{e} R}{\mu_{e}}\right)^{1/2} \left(\frac{u_{e}}{V_{\infty}}\right)^{1/2} \left(\frac{P}{P_{s}}\right)^{1/2} \left(\frac{r}{R}\right)^{\frac{1}{2}} \left(\frac{\rho_{e} \mu_{e}}{\rho_{w} \mu_{w}}\right)^{0.114}} .$$
 (28)

Here,  $\beta$  can be evaluated from

$$\beta = 2 \frac{\xi^*}{u_e} \left( \frac{\partial^u e}{\partial \xi^*} \right) \phi = \text{const} .$$
 (29)

When the local boundary layer momentum is known, M can be evaluated from

$$\mathbf{M} = \int_{\text{circumference}} \rho u \frac{u^2}{e} ds \qquad (30)$$

where ds is a circumferential increment of length. From Equation 28,  $\mu_{\mu}^{2}\theta$  can be written as

$$\rho_{e} u_{e}^{2} \theta = \frac{\rho_{\infty} V_{\infty}^{2} R \sqrt{2} (0.491)(1 - 0.090\beta^{0.4}) \xi^{*1/2}}{\left(\frac{\rho_{\infty} V_{\infty} R}{\mu_{\infty}}\right)^{1/2} \left(\frac{\mu_{\infty}}{\mu_{w}}\right)^{1/2} \left(\frac{r}{R}\right)^{k} \left(\frac{\rho_{w} \mu_{w}}{\rho_{e} \mu_{e}}\right)^{0.386}} \frac{u_{e}}{V_{co}} \left(\frac{\rho_{e}}{\rho_{\infty}}\right)^{1/2} \left(\frac{T_{e}}{T_{w}}\right)^{1/2}.$$
(31)

Thus, the integral in Equation 30 can be evaluated readily once the local flow properties have been used to evaluate  $\xi^{\pm}$ ,  $\theta/R_{\gamma}$  and  $\rho_{e}u_{e}^{2}\theta$ . For a circular body and by evaluating the integral at the base,

$$M = \pi D \left( \dot{\rho}_{e} u_{e}^{2} \theta \right)_{base},$$

For a body with an elliptical cross section. M can be expressed as

$$M = 4 \int_{0}^{\pi/2} \rho_{e} u_{e}^{2} \frac{\theta}{R} G_{1} R^{2} d\theta , \qquad (33)$$

(32)

> where, because of the symmetry, it is only necessary to integrate over one quadrant, and where

$$G_{1} = \frac{1}{R} \frac{ds}{d\phi} \frac{\left[1 + \frac{\sin^{2}\phi \cos^{2}\phi}{\left(\frac{\sin^{2}\phi}{b^{2}} + \frac{\cos^{2}\phi}{a^{2}}\right)^{2}} \left(\frac{1}{b^{2}} - \frac{1}{a^{2}}\right)^{2}\right]^{1/2}}{\left[ab\left(\frac{\sin^{2}\phi}{b^{2}} + \frac{\cos^{2}\phi}{a^{2}}\right)^{1/2}\right]^{1/2}}.$$
 (34)

Here, b and a are the semiaxes of the ellipse.  $G_1$  is unity for a cylindrical body.

Once the inviscid flow properties along the edge of the body boundary layer are known, and assuming the wall temperature is known or can be estimated, then the boundary layer momentum thickness and integrated momentum defect can be evaluated using Equations 28 and 30.

# 2. TURBULENT BOUNDARY LAYER THEORY

Unfortunately, the state of knowledge regarding turbulent boundary layers is not so well developed as in the laminar case. Thus, although there have been many approximate treatments of turbulent flow, most of which can be supported to some extent by using existing experimental data, there are no "exact" theoretical solutions (such as those of Kemp, Rose, and Detra) for laminar flow.

One approximate solution, the results of which lead themselves to the present problem, is that of Reshotko and Tucker (Reference 7). This solution uses the momentum integral and moment-of-momentum equations as simplified using Stewartson's transformation. To solve these two equations, a skin friction relation must be used; Reshotko and Tucker choile the Ludwieg-Tillman relation in a form suitable for compressible flow with heat transfer through applying the reference enthalpy concept. The above equations were simplified further by using an approximate shear stress distribution and the power law velocity profile.

The moment-of-momentum equation is needed to account for pressure gradient effects on the boundary layer velocity profile. The method of Reshotko and Tucker, as applied to insulated surfaces, is quite well founded. However, for noninsulated or nonadiabatic wall cases the method, though qualitatively correct, is based on some speculative assumptions. It is still anticipated, however, that for such cases the method will-yield reasonable quantitative results. The method certainly is representative of the best that can be done within the present status of surbuient flow theory.

Resholks and Tucker in Reference 7 present their results for incomentum thickness in terms of a transformed momentum thickness,  $\theta_{tr}$ . The transformed momentum thickness,  $\theta_{tr}$ , can be related to the actual momentum thickness,  $\theta$ , by

$$\theta = \theta_{tr} \left( 1 + \frac{\gamma - 1}{2} M_e^2 \right)^3$$
 (35)

The solution for 9 is

$$\mathbf{\hat{r}} = \left[ \theta_{tr} \left( \frac{M_{e} \bullet_{o} \theta_{tr}}{\nu_{o}} \right)^{0.2155} M_{e}^{B} R^{1.2155k} \right]_{s} - \left[ \theta_{tr} \left( \frac{M_{e} \bullet_{o} \theta_{tr}}{\nu_{o}} \right)^{0.2155} M_{e}^{B} R^{1.2155k} \right]_{s}$$

$$* 0.01173 \int \frac{M_{e}^{B}\left(\frac{1}{T_{ref}}\right)}{\left(\frac{T_{o}}{T_{e}}\right)^{3.268}}$$
(36)

Here,  $a_0$  and  $v_0$  are the velocity of sound and the kinematic viscosity evaluated at the stagnation conditions of the local external stream, respectively. The exponent B can be exposed approximately as

$$B = 4.2 + 1.58 \left(\frac{1}{T_{5}}\right) - 1$$
 (37)

where T is the inviscid stagnation to numerature. The reference temperature,  $\Gamma_{ref}^{o}$  is given as

$$T_{rel} = 0.50 (T_w \in T_e) + 0.22 (T_{aw} - T_e)$$
. (38)

where T is the adiabatic wall or recovery temperature

$$T_{aw} = T_e \left( 1 + \frac{Y - 1}{2} M_e^d P_T \right)$$
 (39)

The distance,  $\varepsilon_{1}$ , in Equation 36 is the starting point of the calculation. If the boundary layer is turbulent over the entire body, then  $s_{1} = 0$ , and the calculation starts at the forward stagnation point. However, if the boundary layer is in fally laminar, then the calculation starts at  $s_{1} = s_{1}$ , the transition point. At that point,

$$\theta(tarbulent) = \theta(taminar) + (49)$$

The previously noted equation for a compressible turbulent boundary layer (Equation 36), can be recast in terms of a turbulent distance parameter,  $\xi_T$ , where

$$\xi_{T}^{*} = \frac{1}{M_{e}^{B}(\frac{r}{R})^{1.2155k}} \int_{\frac{s_{1}}{R}}^{s/R} \frac{M_{e}^{B}(\frac{r}{R})^{1.2155k}}{\left(\frac{T_{ref}}{T_{e}}\right)^{0.732} \left(\frac{T_{o}}{T_{e}}\right)^{3.268} d\frac{s}{R} \cdot (41)$$

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The transformed momentum thickness,  $\theta_{tr}$ , then can be expressed as

$$\left(\frac{9}{\text{tr}}\right)^{1.2155} = \left[\frac{\gamma_{\text{tr}}(\text{TR})}{\text{R}}\right]^{1.2155} \left[\frac{P_{0}(\text{TR})}{P_{0}}\right]^{0.2155} \left[\frac{M_{e}(\text{TR})}{M_{e}}\right]^{0.2155 + B} \times \frac{\left[\frac{r(\text{TR})}{R}\right]^{1.2155k}}{\left(\frac{r}{R}\right)^{1.2155k}} - \frac{0.01173\xi_{\text{T}}^{*}}{\left(\frac{M_{e}\text{Ra}}{\mu_{0}/\mu_{0}}\right)^{0.2155}} \right]$$
(42)

TR indicates that the property is to be evaluated at the transition point.

When  $\theta_{tr}$  is known, the actual momentum thickness,  $\theta$ , can be evaluated as can  $\operatorname{Re}_{\theta}$ ,  $\rho_e u_e^2 \theta$ , and M. For this latter quantity, Equations 32 through 34 are applicable. Thus, calculations can be carried out for the important boundary layer properties once the properties at the edge of the boundary layer are known.

#### APPENDIX II

# FOREBODY FLOW FIELD PROGRAM

The forebody geometry is stored as a table to allow all necessary geometric properties to be determined by simple calculation from the geometric coordinates. The storage system defines the body profile as a series of points that are the values of the distance r from the forebody axis to its surface and as a function of the axial distance x from the nose of the body. Thirteen profiles are stored on 13 planes formed by rotating the vertical plane containing the forebody axis about this axis 90 deg in 7.5-deg increments. Mirror symmetry is assumed about the vertical and horizontal planes.

The one geometric input required by the boundary layer program is the value of r/R, where R is average base radius. The value, r, is found as a function of x along any one  $\phi$  by linear interpolation between the points stored in the table.

For the pressure distribution subroutine, the angle of the forebody surface in  $e: ch \not o$  rlane with the body axis must be known. To calculate this,

$$\theta_{i} \neq \arctan \frac{r_{i} + l, \not e^{-r_{i}}, \phi}{x_{i} + l, \phi^{-x_{i}}, \phi}, \qquad (43)$$

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The application of the Newtonian or tangent-cone method for estimating the static pressure distribution is governed by the following logic. The free-system Mach number and the static pressure  $(M_{\infty} \text{ and } p_{\infty})$  are inputs to the pressure distribution subroutine. For each  $\phi$  profile, the following checks and decisions are made.

The nose angle is calculated from the stored geometry,

$$\theta_{0, \phi} = \arctan \frac{r_{1, \phi} - r_{0, \phi}}{x_{1, \phi} - x_{0, \phi}}.$$
 (44)

This value then is compared with a stored curve of  $\theta_c$  versus  $M_{\infty}$ , where  $\theta_c$  is the critical cone angle between conical flow with an attached conical shock and flow with a detached shock.

Case A

If  $\theta_{0, \not 0}$  is equal to or larger than  $\theta_{c}$ , then the shock wave is detached from the nose, and static pressure is estimated by the Newtonian flow

$$p_e = p_s \sin^2 \theta_{0, \phi}$$

where  $p_s$  is the nose total pressure. Since there is a detached shock,  $p_s$  is the free-stream impact pressure.

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 $\theta_{0, \ \phi} < \theta_{c}$ .

If  $\theta_0$ ,  $\phi$  is less than  $\theta_c$ , then an attached conical shock exists, and both the static and nose total pressure are evaluated from the conical flow subroutine. For both cases, the local Mach number is given by

$$M_{e} = \sqrt{\frac{2}{\frac{2}{r-1} \left( \frac{p_{o}}{p_{e}} \right)^{\frac{r-1}{r}} - 1}.$$

where  $p_0$  is the local total pressure. In this region,  $p_0 = p_s$ .

This solution is carried out at each point on the body profile. As long as  $\theta_i, \neq \theta_{i+1}, \neq$ , the local total pressure is equal to the nose total pressure for both cases. If the shock wave is detached, the static pressure is obtained by the Newtonian method until  $\theta_i, \neq \theta_c$ , after which the conical flow solution is used.

If, however,  $\theta_i$ ,  $\delta < \theta_{i+1}$ ,  $\delta$  a corner shock forms, and the local total pressure changes. To evaluate this condition, the flow properties in the region  $x_i = 1$  to  $x_i$  are used, and the angle  $\overline{\theta} = \theta_i + 1$ ,  $\delta = \theta_i$ ,  $\delta$  is the conical semiangle of interest. As before, there are two possible cases. For Case A where  $\overline{\theta} \ge \theta_c$  for  $M_{e_i}$ ,

$$p_{e_{i} \rightarrow j} = p_{o_{i} \neq j} sin^{2} \overline{\theta}$$

where  $p_{0i_{i_1}+1} = local total pressure behind a detached (normal) shock. This pressure is given by$ 

 $P_{o_{i}+1} = P_{s} \frac{(r+1)M_{e_{i}}^{2}}{(r-1)M_{e_{i}}^{2}+2} \frac{1}{r-1} \frac{1}{2rM_{e_{i}}^{2}-(r-1)} \frac{1}{r-1}$ 

For Case B where  $\overline{\theta}$  is less than  $\theta_c$  for  $M_{e_i}$ , the static and total pressures are taken from the conical flow routine using the local properties at point j as inputs. Again, the Mach number is given in either case by



# APPENDIX III

#### BOUNDARY LAYER TRANSITION PREDICTION

#### 1. GENERAL

A criteria for boundary layer transition was established that could be incorporated into a general laminar-turbulent boundary layer calculation program. Any such criteria must, because of what is known regarding transition and turbulent flow, be considered as leading to only an approximate estimate. In developing transition prediction criteria, recognition must first be rnade of the factors that influence transition, the parameters in terms of which transition correlations usually are made, and which of these factors are important and can be considered realistically. In general, boundary layer transition depends on the Reynolds number of the flow, surface roughness, free-stream turbulence, noise, compressibility effects and/or pressure gradient effects, and whether the boundary layer is being heated or cooled. Except for effects due to surface roughness and free-stream turbulence, one might think that the other effects are of such a nature that methods of predicting their associated influence on transition could be developed. However, the effects of roughness and turbulence each may couple with the other factors, thus making any attempt to separate one effect from another extremely difficult.

As an example, the effect of surface roughness depends on the thickness of the boundary layer, but the thickness of the boundary layer depends on the compressibility of the fluid (as manifested through the local Mach number) and whether the boundary layer is being heated or cooled, as well as many other factors. The free-stream turbulence also may vary with tunnel conditions. Thus, the individual factors do couple with one another.

In evaluating factors affecting transition (see Figure 42), Low, in Reference 36, presents a curve showing the effect of free-stream turbulence on transition.

Gazley (Reference 37) found that laminar boundary layer oscillations and their damping or amplification could be detected only when the freestream turbulence was less than 0.001. For greater turbulence values, the boundary layer oscillations became difficult to identify because of the near coincidence of their appearance with the point of transition to turbulence. Gazley also reported that the effects of free-stream turbulence tend to mask out the effects of other variables. This may explain the disagreement between Stainback (Reference 38) and Gazley. Stainback's results tended to confirm the invariance of transition Reynolds number with Mach number up to Mach 8; Gazley's results indicated an increase of transition Reynolds number with increasing Mach number.

Both Deem (Reference 39) and Stewart (Reference 40) indicate an increase of transition Reynolds number with an increase of unit Reynolds number. Deem also observed a transition reversal phenomenon due to changes in wall to adiabatic wall temperature ratios.

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Figure 42 - Free Stream Turbulence, U'/U

Correlations of boundary layer transition usually are presented in the form of a transition Reynolds number as a function of other flow similarity parameters. Although experimental data frequently are presented using the free-stream Reynolds number based on X (Re<sub>X</sub>), Reynolds numbers based on momentum thickness and displacement thickness also are used. If the transition process itself is viewed as originating through local boundary layer separation occurring because of a local momentum deficiency, then the local Reynolds number based on momentum thickness, Re<sub>0</sub>, would seem to be the appropriate dependent variable. For an incompressible, flat-plate boundary layer, the critical value of Re<sub>0</sub> corresponding to the boundary layer becoming unstable to small disturbances (<u>e.g.</u>, Tollmien-Schlicting waves) is 163 (Reference 41). On the other hand, the transition value may range as high as 1300, depending on the exact surface roughness and free-stream turbulence, both of which tend to decrease the value of the transition Reynolds number. For compressible flows, the Mach number and the ratio of the wall enthalpy to the adiabatic wall enthalpy also become important.

Pressure gradient effects (a favorable gradient stabilizes the boundary layer while an unfavorable gradient destabilizes it), although important, are much more difficult to consider. The unit Reynolds number also is included in many correlations of transition data. Originally, this parameter may have been related to wind-tunnel produced disturbances. However, there is now some evidence that it also is an important effect in correlating ballistic range and flight data. Its role, however, is not understood from a physical viewpoint.

# 2. ANALYSIS

In developing a rather simple correlation for the transition Reynolds number based on momentum thickness, only the effects of Mach number and  $h_w/h_{aw}$  are considered directly. Since the present boundary layer computer program calculated  $Re_{\theta}$ , it is convenient to treat the transition problem in terms of this parameter. Furthermore, the free-stream Mach number range of interest in this study is from 2 to 5. For a blunt nose body, this means local Mach numbers of less than 3.5.

For wind-tunnel tests on Project EUREKA, the wall conditions were such that  $h_W \approx h_{aW}$ . For free-flight calculations,  $h_W/h_{aW}$  could range as low as 0.12, based on an upper limit of 6 for  $M_{\infty}$ . Effects due to surface roughness and free-stream turbulence will not be included.

In general, the effect of the local Mach number on the transition Reynolds number in terms of X can be represented as shown in the following sketch (Reference 42 and 43).



A curve of this type can be represented by a power series of the form

$$\operatorname{Re}_{X_{tr}} = \left( \operatorname{Re}_{X_{TR}} \right)_{inc} \sum_{n=0}^{m} a_{n} M^{n}$$
(47)

If only the first four terms in the power series are used, the following boundary conditions can be applied:

1. M = 0,  $\operatorname{Re}_{X_{tr}} = \left(\operatorname{Re}_{X_{tr}}\right)_{inc}$  (a value of 2.5 × 10<sup>6</sup> was

2. 
$$M = 0$$
,  $dRe_X$ ,  $/dM = 0$ 

3.  $M = M_1$ ,  $dRe_{X_{tr}}/dM = 0$  ( $M_1$  based on experimental data)

4. 
$$M = M_{j}$$
,  $Re_{X_{ir}} / (Re_{X_{tr}})_{inc}$  (matched with experimental data)

If boundary conditions 3 and 4 are selected based on References 43 and 44, Equation 47 then becomes:

$$\mathbf{Re}_{\mathbf{X}_{tr}} = 2.5 \times 10^{6} (1 - 0.12 \text{ M}^{2} + 0.023 \text{ M}^{3}) . \tag{48}$$

Since  $\operatorname{Re}_{\Theta} \approx 0.664 \operatorname{Re}_{X}^{1/2}$ , (Reference 41), then

$$R_{\theta_{tr}} \approx 1000 (1 - 0.12 \text{ M}^2 + 0.023 \text{ M}^3)^{1/2} . \tag{49}$$

The effect of  $h_w/h_{aw}$  is illustrated in the following sketch:



This curve can be represented by a power series of the form

$$\operatorname{Re}_{X_{\mathrm{tr}}} = \left(\operatorname{Re}_{X_{\mathrm{tr}}}\right)_{T_{\mathrm{w}}} = T_{\mathrm{aw}} \qquad \sum_{n=0}^{m} b_{n} \left(\frac{h_{\mathrm{w}}}{h_{\mathrm{aw}}}\right)^{n} \quad . \tag{50}$$

which can be fitted to available experimental data. When the range,  $0.2 \le h_w/h_{aw} \le 1.0$ , is considered, the boundary conditions become

- 1.  $h_w/h_{aw} = 1$ ,  $Re_{X_{tr}} = (Re_{X_{tr}})T_w = T_{aw}$ 2.  $h_w/h_{aw} = \overline{h}_1$ ,  $Re_{X_{tr}}$  (matched with experimental data)
- 3.  $h_w/h_{aw} = \bar{h}_l$ ,  $dRe_{X_{tr}}/dh_w = 0$

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4.  $h_w/h_{aw} = 0.2$ ,  $Re_{X_{tr}}$  (matched with experimental data)

and where  $\operatorname{Re}_{\theta} \propto \operatorname{Re}_{X}^{1/2}$ , the correlation of Equation 49 becomes
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$$\operatorname{Re}_{\theta_{\mathrm{tr}}} \approx 1000 (1 - 0.12 \,\mathrm{M}^2 + 0.023 \,\mathrm{M}^3)^{1/2} \times (2.20 + 17.28 \,\mathrm{F} + 18 \,\mathrm{F}^2 + 3.01 \,\mathrm{F}^{1/2}$$
(51)

where  $\overline{h} = h_w/h_{aw}$ . Here, the effects due to  $h_w/h_{aw}$  are based on the experimental data of References 45 through 47.

The nature of this correlation is that transition reversal is included. However, the second transition reversal frequently found at values of  $h_w/h_{aw}$  of approximately 0.2 is not included. The correlation (Equation 51) thus is limited to  $h_w/h_{aw} > 0.2$ . Reshotko (Reference 48) has qualitatively explained both transition reversal phenomena. However, a general agreement among the available experimental data does not exist; the correlation, though qualitatively correct, is quantitatively only an approximation.

In representing the effects of Mach number and  $h_{aw}$  using power series, the coefficients in these series should be treated as functions of surface roughness and free-stream turbulence.

Pressure gradient effects, as noted before, also may be important. On this project, the primary bodies of interest are such that, excluding the nose region, the body is divided into regions of zero pressure gradient. This should be a reasonable approximation, even in the prediction of transition, with the one exception being at the junction of the cylindrical afterbody and the flare at the base of the body. The adverse pressure gradient there may produce transition if the Reynolds number is greater than the critical value. Thus, it was suggested that, in programming the boundary layer calculations,  $Re_{\theta}$  at the initiation of the flare be checked against ( $Re_{\theta}$ )<sub>CRIT</sub> as given below:

$$(\text{Re}_{\theta}) \approx 163 (1 - 0.12 \text{ M}^2 + 0.023 \text{ M}^3)^{1/2} \times (-2.29 + 17.38 \text{ F} - 18 \text{ F}^2 + 3.91 \text{ F}^3)^{1/2}$$
 (52)

This equation is merely Equation 51 with the incompressible transition value of a 1000 replaced by critical value 163). If at the flare,  $\text{Re}_{\theta} \geq \text{Re}_{CRIT}$ , then transition is assumed to encur. If  $\text{Re}_{\theta} < \text{Re}_{0}$  and the boundary layer remains laminar. With the inclusion of this criterion in the program boundary layer transition should at least be accounted for in a quantitatively correct manner.

The present correlation, Equation 52, has been compared with experimental results from Reference 40 on the effect of  $T_{W}/T_{aW}$  obtained at  $M_{CO} = 3$ . 1. Approximate agreement has been found to exist. The results of Stetson and Rushton (Reference 49) also have been compared; these results were obtained on blunt cones at a free-stream Mach number of

 $M_{\infty} = 5.5$  (see Figure 43). Here,  $X_T$  is the transition distance,  $X_{sw}$  is the distance for the high entropy layer to be swallowed, and  $Re_{\theta T}$  is the transition Reynolds number based on momentum thickness. The prediction based on the present method is shown only for one condition; however, reasonable agreement exists.

Equations 51 and 52 have been programmed as a part of the boundary layer program and are used to determine the approximate location of transition if the exact location of transition is not specified as an input.





## APPENDIX IV

## VISCOUS WAKE ANALYSIS

## 1. GENERAL

An integral method of solution was applied to the problem of determining the properties of both laminar and turbulent viscous wakes, particularly to the problem of the wake flow preceding a trailing aerodynamic decelerator. The important assumptions contained in the theory are as follows: the state of the s

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- 1. The fluid is thermally and calorically perfect, and there are no chemical reactions or other real gas phenomena.
- 2. Prandtl number is unity (Pr = 1).
- 3. Prandtl's concept of viscous flow phenomena is valid for the high-speed compressible wake in such a way that gradients in the streamwise or axial direction are much smaller than those normal to the wake axis, and boundary layer type equations can be used.
- 4. The details of the base flow and free shear layer regions can be largely ignored. Thus, the region of alidity for the present analysis must be considered to extend from somewhere in the vicinity of the wake neck or further downstream and on down into the far wake.
- 5. Effects due to the existence of an external pressure gradient are negligible.

By using these five assumptions, the momentum integral equation can be written as

$$\rho_1 u_1^2 (\pi \theta_1^2) = 2\pi \int_0^0 \rho u(u_1 - u) r dr = \text{ constant with respect to } X , \quad (53)$$

Here, 0 is the momentum thickness: Equation 53 simply states that the wake momentum defect is constant in the axial direction.

By ignoring the details of the base flow and shear layer regions and assuming that no external work is done on the wake fluid in these regions, then the constant in Equation 53 can be evaluated by equating the momentum defect of the boundary layer at the base of the forebody to the momentum defect of the wake. This can be stated mathematically as

$$\mathcal{F}_{\mathbf{B}} \mathbf{u}_{\mathbf{B}}^{2} (\mathbf{\pi}_{\mathbf{B}}^{\mathbf{B}} \mathbf{D}) = \mathcal{F}_{1} \mathbf{u}_{1}^{2} (\mathbf{\pi}_{1}^{2}), \qquad (54)$$

where the subscript i refers to properties associated with the outer edge of the wake, and the subscript B refers to properties at the base of the vehicle, where the boundary layer separates. B and u B are inviscid properties, while D is the forebody base diameter.

The continuity and momentum equations governing this laminar axisymmetric high-speed wake problem are

$$\frac{1}{r}\frac{\partial}{\partial r}(\rho r v) + \frac{\partial}{\partial X}(\rho u) = 0$$

$$\rho u \frac{\partial u}{\partial X} + \rho v \frac{\partial u}{\partial r} = \frac{1}{r}\frac{\partial}{\partial r}(r \mu \frac{\partial u}{\partial r})$$

$$\frac{\partial P}{\partial r} = 0. \qquad (55)$$

Here, v is the velocity in the radial direction, r; u is the velocity in the axial direction, X. For laminar flow, the properties in Equation 35 are the conventional local properties. For turbulent flow u, v, p, and  $\rho$  must be interpreted as time-averaged quantities (as opposed to the fluctuating component of each of these properties). The viscosity,  $\mu$ , takes a different form for laminar flow than for turbulent flow. The axial direction momentum equation can be expanded and expressed as

$$\rho u \frac{\partial u}{\partial X} + \rho v \frac{\partial u}{\partial r} = \frac{\partial}{\partial r} \left( \mu \frac{\partial u}{\partial r} \right) + \frac{1}{r} \mu \frac{\partial u}{\partial r} .$$
 (56)

To solve this equation, the Dorodnitzyn transformation is introduced where

$$ndn = \frac{\rho}{\rho_1} rdr .$$
 (57)

In this new X, n coordinate system, the transformed wake thickness  $\Delta$  is found through integration so that

$$\Delta^2 = 2 \int_0^0 \frac{\rho}{\rho_1} r dr . \qquad (58)$$

 $\Delta$  is termed the wake thickness but is really the wake radius. A nondimensional variable,  $\eta = n/\Delta$ , then can be introduced so that  $\eta = 0$  at the centur of the wake and  $\eta = 1$  at the outer edge where  $Y = \delta$ . In the X,  $\eta$  coordinate system, it is assumed that the velocity profile can be expressed as

$$\frac{u}{u_1} = \sum_{i=0}^4 a_i \tau^i \cdot$$

(50)

The boundary conditions to be used then are as follows.

- 1. At the centerline of the wake,  $Y = \eta = 0$  and  $u = u_0$ .
- 2. At the centerline of the wake,  $Y = \eta = 0$  and  $\frac{\partial u}{\partial Y} = \frac{\partial u}{\partial \eta} = 0$ .
- 3. At the outer edge of the waxe,  $\hat{X} = \delta \text{ or } \eta = 1$ ,  $u = u_1$ .
- 4. At the outer edge of the wake,  $Y = \delta$  or  $\eta = 1$ ,  $\frac{\partial u}{\partial Y} = \frac{\partial u}{\partial \eta} = 0$ .
- 5. At the centerline, the axial direction momentum equation applies.
- 6. At the outer edge of the wake,  $Y = \delta$  or  $\eta = 1$ ,  $\frac{\partial^2 u}{\partial Y^2} = \frac{\partial^2 u}{\partial \eta^2} = 0$ .

The first boundary condition yields

$$a_0 = \frac{u_0}{u_1}$$
.

Boundary conditions 2 through 4 yield

$$a_{1} = 0$$

$$a_{0} + a_{1} + a_{2} + a_{3} + a_{4} = 1$$

$$2a_{3} + 3a_{3} + 4a_{4} = 0$$
(60)

Boundary condition 5 can be evaluated only after the axial direction momentum equation is transformed. This leads to

$$e u \frac{\partial u}{\partial X} + e v \left( \frac{p}{r_1} + \frac{1}{n} \right) \frac{\partial u}{\partial n} = \frac{e^{\mu} 1}{r_1} + \frac{1}{n} \frac{\partial}{\partial n} \left( \frac{p \mu}{r_1 - r_1} + \frac{1}{n} \frac{\partial u}{\partial n} \right) + \frac{1}{n} \frac{p \mu}{r_1} \frac{\partial u}{\partial n} = \frac{1}{n} \frac{\partial u}{\partial n} + \frac{1}{n} \frac{p \mu}{r_1} \frac{\partial u}{\partial n} = \frac{1}{n} \frac{\partial u}{\partial n} + \frac{1}{n} \frac{\partial u}{r_1} \frac{\partial u}{\partial n} = \frac{1}{n} \frac{\partial u}{\partial n} + \frac{1}{n} \frac{\partial u}{r_1} \frac{\partial u}{\partial n} = \frac{1}{n} \frac{\partial u}{\partial n} + \frac{$$

Because of the symmetry of the problem, all gradients in the radial direction are zero on the wave centerline; thus, on the centerline the relation

leads to

$$n^2 = \frac{\rho_0}{\rho_1} r^2$$
.

Evaluating the above momentum equation at the wake centerline results in

$$\rho_1 u_0 \frac{\mathrm{d}u_0}{\mathrm{d}\mathbf{X}} = \mu_1 \frac{\rho_1}{\rho_0} \frac{\partial}{\partial n} \left( \frac{\rho_\mu}{\rho_1 \mu_1} \frac{\partial}{\partial n} \right) + \mu_1 \frac{\rho_1}{\rho_0} \left( \frac{\rho_\mu}{\rho_1 \mu_1} \right) \frac{1}{n} \frac{\partial u}{\partial n}$$

or

$$\rho_1 u_0 \frac{\mathrm{d}u_0}{\mathrm{d}X} = u_1 \frac{\rho_1}{\rho_0} \left( \frac{\rho_\mu}{\rho_1 u_1} \right)_0 \left[ \frac{\partial^2 u}{\partial_n^2} + \left( \frac{1}{n} \frac{\partial u}{\partial_n} \right) \right]_0$$

Substituting from Equation 59 results in

$$\rho_1 u_0 \frac{du_0}{dX} = \frac{\mu_0 u_1}{\Delta^2} 4a_2 .$$
 (61)

Thus,

$$4a_2 = \frac{a_0}{a_1} \Delta^2 \left( \frac{\rho_1}{\mu_0} \right) \frac{da_0}{dX} ,$$

and  $\varepsilon_2$  can be expressed as

$$c_2 = \frac{\zeta}{4} , \qquad (62)$$

where

$$\xi = \frac{u_0}{u_1} (\Delta^2) \left( \frac{\rho_1}{\mu_0} \right) \frac{du_0}{d\mathbf{X}} .$$
 (53)

The first five boundary conditions thus yield the following values for the coefficients  $a_0, a_1, \ldots$ 

 $a_0 = \frac{u_0}{u_1}$  $a_1 = 0$  $a_2 = \frac{\xi}{\xi}$ 

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$$a_{3} = 4\left(1 - \frac{u_{0}}{u_{1}}\right) - \frac{\xi}{2} = -\frac{\xi}{3}$$

$$a_{4} = -2\left(1 - \frac{u_{0}}{u_{1}}\right) + \frac{\xi}{4} = \frac{\xi}{8} . \qquad (64)$$

The velocity profile in the transformed plane then becomes

$$\frac{u-u_{0}}{u_{1}} = \frac{\xi}{4}(\eta^{2} - 2\eta^{3} + \eta^{4}) \div (1 - \frac{u_{0}}{u_{1}}) (4\eta^{3} - 3\eta^{4}) .$$

When boundary condition 6 is used, it can be shown that

$$\frac{\xi}{24} = \left(1 - \frac{u_0}{u_1}\right) ,$$

The velocity profile then becomes

$$\frac{u}{u_1} = (6\eta^2 - 8\eta^3 + 3\eta^4 - 1)\frac{\xi}{24} + 1.$$
 (65)

For  $\xi = 24$ , then  $u_0 = 0$  and X = 0; for  $\dot{\xi} = 0$ , then  $u_0 = 1$  and  $X = \infty$ .

With the velocity profile now known as a function of  $\xi$ , the next step is to relate  $\xi$  and X. This can be done by using Equation 63. However, to do this a form for the viscosity coefficient,  $\mu_0$ , must be specified. Its form will depend on whether the flow is laminar or turbulent; the evaluation of the relationship between  $\xi$  and K will be discussed in the next section, where the various special cases are treated.

It is of interest though, before turning to the solution of the energy equation, to consider the relationship between  $\theta$  and  $\Delta$ . This can be done by transforming Equation 53 so that

$$\frac{\theta^2}{\Delta^2} = 2 \int_0^1 \frac{u}{u_1} \left(1 - \frac{u}{u_1}\right) \eta d\eta .$$
 (66)

Substituting for  $\frac{u}{u_1}$  in terms of  $\eta$  and  $\xi$ , there results upon integration

$$\frac{\theta^2}{\Lambda^2} = \frac{\xi}{120} - \frac{11\xi^2}{60,480} \approx \frac{\xi}{120} - \frac{\xi^2}{5500} \,. \tag{67}$$

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Where there is no pressure gradient in the wake,  $\theta$  is constant and can be evaluated from Equation 64; then Equation 67 is a relationship between  $\Delta$  and  $\xi$ . The location of the wake neck can be sought by differentiating Equation 67 with respect to X. This results in

$$-2 \frac{\theta^2}{\Delta^3} \frac{d\Delta}{dX} = \left(\frac{1}{120} - \frac{2\xi}{5500}\right) \frac{d\xi}{dX} .$$

At the wake neck,

 $\frac{\mathrm{d}\Delta}{\mathrm{d}\mathbf{X}} = 0.$ 

However,  $d\xi/dX \neq 0$ ; thus, the location of wake neck is determined from the condition

$$\frac{2\xi}{5500} = \frac{1}{120} \text{ or } \xi = 22.9. \tag{68}$$

At this location, the centerline velocity then will be

$$\frac{u_0}{u_1} = 0.045,$$
 (69)

and the wake thickness or radius is

$$\left(\frac{\Delta}{\theta}\right)_{\text{neck}} = 3.24. \tag{70}$$

Although the above results are of interest, they are only approximate since in the neck region the effects of pressure gradient, in both the normal and axial directions, may be important.

In  $t_i$  e energy equation, the high-speed compressible wake can be written as

$$\rho \mathbf{u} \frac{\partial \mathbf{h}}{\partial \mathbf{X}} + \rho \mathbf{v} \frac{\partial \mathbf{h}}{\partial \mathbf{r}} = \frac{1}{\mathbf{r}} \frac{\partial}{\partial \mathbf{r}} \left( \frac{\mathbf{k}}{\mathbf{c}_{\mathbf{p}}} \mathbf{r} \frac{\partial \mathbf{h}}{\partial \mathbf{r}} \right) + \mu \left( \frac{\partial \mathbf{u}}{\partial \mathbf{r}} \right)^{2}. \tag{71}$$

Multiplying the axial direction momentum equation by u and adding  $\partial t$  to the above results in

$$\rho u \frac{\partial H}{\partial X} + \rho v \frac{\partial H}{\partial r} = \frac{1}{r} \frac{\partial}{\partial r} \left( \frac{\mu}{Pr} r \frac{\partial H}{\partial r} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left[ \left( 1 - \frac{1}{Pr} \right) \mu u r \frac{\partial u}{\partial r} \right]. \quad (72)$$

In either one of these equations, the properties must be considered as local fluid properties for laminar flow and as time-averaged properties for turbulent flow.

> For Pr = 1, a solution to the above energy equation in terms of total enthalpy is

$$H = c_1 u + c_2,$$

where the constants  $c_1$  and  $c_2$  are determined from the boundary conditions

$$u = u_1, H = H_1$$
  
 $u = u_0, H = H_0$  (73)

The total enthalpy profile thus can be expressed as

$$H_1 - H = (H_1 - H_0) \frac{u_1 - u}{u_1 - u_0}$$

or

$$\frac{H_1 - H}{H_1 - H_0} = \frac{1 - \frac{u}{u_1}}{1 - \frac{u_0}{u_1}}.$$
 (74)

 $H_0$  can be determined from the condition that the total enchalpy defect is constant in the wake and is equal to that of the vehicle boundary layer at its base. For the wake, the total enthalpy defect is

$$\rho_1 u_1 H_1 \left( \pi \theta_{T_1}^2 \right) = 2\pi \int_0^0 \rho u (H_1 - H) r dr$$
 (75)

or transforming

$$\frac{\theta_{T_1}^2}{\Delta^2} = 2 \int_0^1 \frac{u}{u_1} \left(1 - \frac{H}{H_1}\right) \eta d\eta.$$
 (76)

Substituting from Equation 74 and integrating leads to

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$$\theta_{T_1}^2 = \frac{1 - \frac{H_0}{H_1}}{1 - \frac{u_0}{u_1}} \theta_1^2$$

or

$$\frac{H_0}{H_1} = 1 - \frac{\theta_{T_1}^2}{\theta_1^2} \left(1 - \frac{u_0}{u_1}\right).$$
(77)

For the vehicle boundary layer, the total enthalpy defect is

$$\rho_{s} u_{s} H_{s} \left( \pi D \theta_{T_{s}} \right) = \pi D \int_{0}^{\delta_{s}} \rho u(H_{s} - H) dY, \qquad (78)$$

and for Pr = 1, this can be reduced to

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$$\theta_{T_s} = \left( 1 - \frac{h_w}{H_1} \right) \theta_s, \qquad (79)$$

where  $h_w$  is based on the forebody skin temperature at the base. If the total enthalpy defect of the wake is equated to that of the vehicle boundary layer at the base,

$$\rho_1 u_1 H_1 \left( \pi \Theta_{T_1}^2 \right) = \rho_s u_s H_s \left( \pi D \Theta_{T_s} \right) .$$

If Equations 54, 77, and 79 are substituted, then it follows that

$$\frac{\theta_{T_1}^2}{\theta_1^2} = \left(1 - \frac{h_w}{H_1}\right) \left(\frac{u_1}{u_B}\right).$$
(80)

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Thus, knowing the velocity profile (Equation 65), the total enthalpy profile can be determined using Equations 74, 77, and 80. The static enthalpy profile readily follows.

To transform the results back into the physical X, Y coordinate system, use must be made of the expression

$$\frac{r^2}{h^2} = 2 \int_0^{\eta} \frac{\rho_1}{\rho} \eta \, \mathrm{d}\eta = 2 \int_0^{\eta} \frac{h}{h_1} \eta \, \mathrm{d}\eta \,. \tag{81}$$

Substituting for the enthalpy profile and integrating results in

$$\frac{r^{2}}{\Delta^{2}} = 2\left\{\frac{H_{1} - H_{0}}{h_{1} \left(1 - \frac{u_{0}}{u_{1}}\right)} \left[\left(\frac{3}{2}\eta^{4} - \frac{8}{5}\eta^{5} + \frac{1}{2}\eta^{6} - \frac{\eta^{2}}{2}\right)\frac{\xi}{24} + \frac{\eta^{2}}{2}\right] + \frac{1}{2}\eta^{2} - \frac{u_{1}^{2}}{2}\left[\frac{\eta^{2}}{24} + \frac{\xi}{24}\left(\frac{3}{2}\eta^{4} - \frac{8}{5}\eta^{5} + \frac{\eta^{6}}{2} - \frac{\eta^{2}}{2}\right)\right] - \frac{u_{1}^{2}}{h_{1} \left(1 - \frac{u_{0}}{u_{1}}\right)} - \frac{u_{1}^{2}}{2}\left[\frac{\xi^{2}}{2}\left(\frac{\eta^{2}}{2} - 3\eta^{4} + \frac{16}{5}\eta^{5} + 5\eta^{6} - \frac{96}{7}\eta^{7} + \frac{100}{8}\eta^{8} - \frac{48}{9}\eta^{9} + \frac{9}{10}\eta^{10}\right)\right]\right\}$$

Thus, except for the relationship between  $\xi$  and X, the necessary equations for determining the properties of a high-speed compressible wake have been derived using an integral technique and the Dorodnitzyn transformation. For a given X/D, the velocity and total enthalpy profiles in the transformed coordinate system are given by Equations 65 and 74 in terms of H0, the centerline total enthalpy, and  $\xi$ , a form parameter. H<sub>0</sub> can be determined from Equations 77 and 80 and  $\xi$  as will be discussed in the next section. The transformed wake thickness or radius can be determined from Equation 67 and the physical coordinate r from Equation 82. To obtain numerical results, it is only necessary that the inviscid flow field be specified, and that an estimate be made of the vehicle boundary layer momentum thickness. Although some of the derived equations may seem rather cumbersome in terms of carrying out numerical calculations, the results are of an algebraic nature and in principle can be readily applied.

It should be re-emphasized, however, that the preceding analysis has ignored the details of the free shear layer and base flow regions. The results obtained thus must be considered as approximate; their range of applicability is certainly limited to the region downstream of the wake neck.

#### 2. CONVENTIONAL LAMINAR WAKE

To evaluate Equation 63 and to obtain  $\xi$  as a function of X, it is necessary to specify a relation for the viscosity coefficient. For lammar flow, the viscosity can be assumed to have a linear dependence on the fluid temperature, i.e.,  $\mu/RT = \text{constant}$ . Since in this analysis the radial pressure gradient is assumed to be zero; then from the equation of state it can be

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shown that  $\rho_{\mu}$  is constant with respect to r and that  $\rho_{\mu} = \rho_{1} \mu_{1}$ . Equation 63 then can be written as

$$\xi = \frac{u_0}{u_1} \left( \Delta^2 \right) \left( \frac{\rho_0}{\mu_1} \right) \frac{du_0}{dX}$$
(83)

Since

$$\frac{u_0}{u_1} = 1 - \frac{\xi}{24}$$

then

$$\frac{\mathrm{du}_0}{\mathrm{dX}} = -\frac{\mathrm{u}_1}{24} \frac{\mathrm{d}\xi}{\mathrm{dX}} \, .$$

Furthermore, the relationship between  $\Delta^2$  and  $\xi$  is known from Equation 67. Substituting these results into Equation 83 results in

$$\frac{\xi^2}{120} - \frac{\xi^3}{5500} = -\left(1 - \frac{\xi}{24}\right) \frac{\rho_0}{\mu_1} \frac{u_1}{24} \theta^2 \frac{d\xi}{dX} . \tag{84}$$

Since  $\rho_0$  has not been specified in terms of  $\xi$  or X, these two variables are not yet uniquely related to each other. To do this, attention must be given to solving the energy equation.

Now the centerline density,  $\rho_0$ , can be expressed as

$$\rho_0 = \frac{P_1}{RT_0} = \frac{\gamma}{\gamma_{-1}} \frac{P_1}{h_0}$$

The static enthalpy can be related to the total enthalpy as

$$h_0 = H_0 - \frac{u_0^2}{2}$$
.

When Equation 77 is used,  $\rho_0$  can be expressed as

$$P_{0} = \frac{Y}{Y - 1} \frac{P_{1}}{\frac{\theta_{T_{1}}^{2}}{\theta_{1}^{2}} H_{1} \left(1 - \frac{u_{0}}{u_{1}}\right) - \frac{u_{0}^{2}}{2}}.$$
(85)

Since the relationship between  $u_0/u_1$  and  $\xi$  is known, then Equation 84 takes the form

$$\frac{\xi^{2}}{120} - \frac{\xi^{3}}{5500} = -\left(1 - \frac{\xi}{24}\right)\frac{u_{1}}{24}\frac{\theta_{1}^{2}p_{1}}{\mu_{1}}\frac{\gamma}{\gamma - 1} - \frac{\frac{d\xi}{dX}}{H_{1} - \frac{\theta_{1}^{2}}{24}\frac{\xi}{24}H_{1} - \frac{u_{1}^{2}}{2}\left(1 - \frac{\xi}{24}\right)^{2}}$$

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After rearrangement, this takes the form

$$\mathbf{x} = -\int_{24}^{\xi} \frac{\left[\left(1 - \frac{\xi}{24}\right)^{\mathbf{u}_{1}}_{\mu_{1}}\right] \left(\frac{\mathbf{p}_{1}\theta_{1}^{2}}{24}\right) \left(\frac{\gamma}{\gamma - 1}\right)}{\left(\frac{\xi^{2}}{120} - \frac{\xi^{3}}{5500}\right) \left[\mathbf{H}_{1} - \frac{\theta_{T_{1}}^{2}}{\theta_{1}^{2}} \mathbf{H}_{1} \frac{\xi}{24} - \frac{\mathbf{u}_{1}^{2}}{2} \left(1 - \frac{\xi}{24}\right)^{2}\right]} d\xi \cdot (86)$$

Here, X is measured from where physically the wake centerline velocity is zero, <u>i.e.</u>, the rear stagnation point. For known flow conditions, Equation 86 gives the variation of  $\xi$  with X. When the results of Item 1 are used, a complete solution for the wake flow can be obtained.

Equation 36 can be recast in form by noting that the bracketed term in the denominator can be written as

$$H_{1}\left[1-\frac{\theta_{T_{1}}^{2}}{\theta_{1}^{2}}\frac{\xi}{24}-\left(1+\frac{\gamma-1}{2}M_{1}^{2}\right)^{-1}\left(\frac{\gamma-1}{2}M_{1}^{2}\right)\left(1-\frac{\xi}{24}\right)^{2}\right],$$

and that

$$\frac{u_1 P_1}{\mu_1} \frac{1}{H_1} \frac{\gamma}{\gamma - 1} = \frac{\rho_1 u_1}{\mu_1} \left(\frac{h_1}{H_1}\right).$$

The following then results:

$$\frac{\frac{\chi}{\theta}\left(\frac{1}{R_{\theta}}\right)}{\frac{1}{24}\left(1-\frac{\xi}{24}\right)} = \frac{\frac{1}{24}\left(1-\frac{\xi}{24}\right)}{\frac{\xi^{2}}{120}-\frac{\xi^{3}}{5500}\left[\left(1+\frac{Y-1}{2}M_{1}^{2}\right)\left(1-\frac{\theta_{T_{1}}^{2}}{\theta_{1}^{2}}\frac{\xi}{24}\right)-\frac{Y-1}{2}M_{1}^{2}\left(1-\frac{\xi}{24}\right)^{2}\right]^{\alpha\xi}}$$
(87)

where

$$\operatorname{Re}_{\theta} = \frac{\rho_1 u_1 \theta}{\mu_1}$$

and is based on wake edge conditions.

Two special cases are of interest. One is that of an adiabatic forebody wall such that  $\theta_{T_1}^2/\theta_1^2 = 0$ . In that case, Equation 87 becomes

$$\frac{\operatorname{Re}_{\mathbf{X}}}{\operatorname{Re}_{\theta}^{2}} = -\int_{24}^{\xi} \frac{\frac{1}{24}\left(1 - \frac{\xi}{24}\right)}{\left(\frac{\xi^{2}}{120} - \frac{\xi^{3}}{5500}\right) \left(1 + \frac{\gamma - 1}{2} \operatorname{M}_{1}^{2} \frac{\xi}{12} - \frac{\gamma - 1}{2} \operatorname{M}_{1}^{2} \frac{\xi^{2}}{576}\right)} d\xi. \quad (88)$$

The second case is that for a cold wall where

$$\frac{\theta_{T_1}^2}{\theta_T^2} = 1.$$

Here, Equation 87 becomes

$$\frac{\operatorname{Re}_{\mathbf{X}}}{\operatorname{Re}_{\theta}^{2}} = -\int_{24}^{\xi} \frac{1}{\left(\frac{\xi^{2}}{120} - \frac{\xi^{3}}{5500}\right) \left(1 + \frac{\gamma - 1}{2} \operatorname{M}_{1}^{2} \frac{\xi}{24}\right)}^{\frac{d\xi}{24}} .$$
 (89)

Equations 88 and 89 indicate that for  $\hat{\xi}$  small, then

$$\mathbf{x} \propto \xi^{-1}$$
.

Since  $\delta = \Delta$  for  $\xi$  small and similarly

 $\Delta^2 \propto \xi^{-1}$ .

Then,

$$\delta = \mathbf{X}^{\frac{1}{2}}$$
 (90)

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 $\xi$  small corresponds to the far wake region, and this square root dependence on X is in agreement with experimental data (Reference 13). It similarly can be shown that

$$1 = \frac{u_0}{u_1} \propto X^{-1}, \tag{91}$$

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and

$$1 - \frac{H_0}{H_1} \propto X^{-1}.$$
 (92)

This also is in agreement with experimental data.

## 3. CYLINDRICAL LAMINAR WAKE

The nature of the laminar axisymmetric wake in the presence of a small diameter wire or cable at its centerline is such that the wake will be approximately cylindrical (or at least will grow very slowly) and will have a zero centerline velocity caused by the no-slip condition at the cable.

An approximate solution corresponding to this case can be obtained from the results of Item 1 by noting that  $u_0/u_1$  equal to zero is equivalent to  $\xi$  equal to 24. Thus, the properties of a cylindrical wake can be obtained by setting  $\xi$  equal to 24 in the previously derived equations.  $\xi$  will not depend on X for this simplified case since there will be complete similarity between the radial profiles at all X direction stations. For this case, the wake velocity profile is given by

$$\frac{u}{u_1} = 6\eta^2 - 8\eta^3 + 3\eta^4, \qquad (93)$$

and the transformed wake thickness, by

$$\frac{\Delta}{\Theta} = 3.24, \qquad (94)$$

where  $\theta$  is deterrined from equating  $\rho_1 u_1 \theta_1$  to the momentum defect of the forebody boundary layer. For a slender body with a zero axial pressure gradient in the wake region,  $\theta_1$  is constant, and thus  $\Delta$  also is a constant. The wake thus has a constant diameter and is cylindrically shaped. If there is a favorable pressure gradient, then the wake diameter will increase in the downstream direction due to the decreasing gas density. Here, the momentum defect,  $\rho_1 u_1^2 \theta_1$ , is constant with axial position, and  $\Delta$  increases as  $\rho_1 u_1^2$  decreases.

For such a cylindrical wake, the solution to the energy equation (Pr = 1) is similar to that given in Item 1 and can be written as

$$\frac{H}{H_1} = \left(1 - \frac{h_w}{H_1}\right) \frac{u}{u_1} + \frac{h_w}{H_1}, \qquad (95)$$

where  $h_w$  is the enthalpy of the gas at a temperature equal to that of the tow cable or riser line. With the velocity and enthalpy profiles known, the wake characteristics can be completely determined. The transformed and physical coordinates then can be related using Equation 82 for  $\xi = 24$  with the result that

$$\frac{r^{2}}{\Delta^{2}} = 2 \left[ \frac{(H_{1} - h_{w})}{h_{1}} \left( \frac{3}{2} \eta^{4} - \frac{8}{5} \eta^{5} + \frac{1}{2} \eta^{6} \right) + \frac{1}{2} \frac{h_{w}}{h_{1}} \eta^{2} - \frac{u_{1}^{2}}{2h_{1}} \left( 6\eta^{6} - \frac{96}{7} \eta^{7} + \frac{100}{8} \eta^{8} - \frac{48}{9} \eta^{9} + \frac{9}{10} \eta^{10} \right) \right].$$
(96)

When the above equation is applied at  $\eta = 1$ , the actual wake radius or thickness can be related to the transformed thickness such that

$$\frac{\delta^2}{\Delta^2} = 0.72 + 0.08 \frac{H_1}{h_1} + 0.26 \frac{h_w}{h_1}.$$
 (97)

With the use of Equation 54, it can be further shown that

$$\left(\frac{\delta}{D}\right)^2 = 7.56 \left(1+0.111 \frac{H_1}{h_1}+0.278 \frac{h_w}{h_1}\right) \frac{\theta_s}{D} \frac{\rho_s u_s^2}{\rho_1 u_1^2}.$$
 (98)

With Equations 93 through 98, the solution is complete with the properties being clearly specified in terms of the forebody boundary layer characteristics and the inviscid properties at the edge of the viscous wake. In this approximate solution, the variation in properties with X is controlled by the change in the inviscid flow field with X since the solution is effectively a constant  $\xi$  solution, and there is no meaningful rektionship between  $\xi$  and X (except that  $\xi$  is constant).

#### 4. TURBULENT WAKE

In Item 1, the solution for the viscous wake profiles was obtained except for relating  $\xi$ , the form parameter, to X. Starting with the equation for the turbulent viscosity coefficient

$$\mu_0 = K \Delta \rho_1 u_1 \left(\frac{\rho_0}{\rho_1}\right)^m \left[1 - n - (-1)n \left(\frac{\rho_0}{\rho_1}\right)^p \left(\frac{u_0}{u_1}\right)\right], \quad (99)$$

as given in Section III, Item 3c, and where m, n, and p are defined for the various viscosity models (see Table VIII).

## TABLE VIII - RELATIONSHIP OF

Viscosity model	μο	m	n	р
1	KAP0 <sup>u</sup> 0	1	1	0
2	$K \Delta (\rho_1 u_1 - \rho_0 u_0)$	0	0	1
3	$K \Delta_1 (u_1 - u_0)$	0	0	0
4	$\mathrm{K}\Delta P_0(\mathbf{u}_1 - \mathbf{u}_0)$	1	0	0

## VARIOUS VISCOSITY MODELS

Substituting Equation 99 into Equation 63 results in

$$\xi = \frac{u_0}{u_1} \Delta \frac{1}{K\left(\frac{\rho_0}{\rho_1}\right)^m \left[1 - n - (-1)^n \left(\frac{\rho_0}{\rho_1}\right)^p \left(\frac{u_0}{u_1}\right)^d \frac{u_0}{u_1}\right]}$$

Introducing the relationship between  $u_0/u_1$  and  $\xi$  leads to

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$$\xi = \left(1 - \frac{\xi}{24}\right) \Delta \frac{1}{K\left(\frac{\rho_0}{\rho_1}\right)^m \left[1 - n - (-1)^n \left(\frac{\rho_0}{\rho_1}\right)^p \left(1 - \frac{\xi}{24}\right)\right]} - \frac{1}{24} \frac{d}{dX}.$$

When  $\Delta$  is replaced through the relationship between  $\Delta$  and  $\theta$ , it follows that

$$\xi = -\frac{\theta}{K} \frac{1}{24} \frac{\left(1 - \frac{\xi}{24}\right)}{\sqrt{\frac{\xi}{120} - \frac{\xi^2}{5500}} \left(\frac{\rho_0}{\rho_1}\right)^m} \left[1 - n - (-1)^n \left(\frac{\rho_0}{\rho_1}\right)^p \left(1 - \frac{\xi}{24}\right)} \frac{d\xi}{dx}.$$

After rearrangement, the integrable form is finally obtained:

$$\frac{K}{\theta} dX = -\frac{1}{24} \frac{\left(1 - \frac{\xi}{24}\right)}{\sqrt{\frac{\xi}{120} - \frac{\xi^2}{5500}}} \left[ \left(1 - n\right) \left(\frac{\rho_1}{\rho_0}\right)^P - \left(-1\right)^n \left(1 - \frac{\xi}{24}\right) \right]^{\frac{d}{\xi}}.$$
 (100)

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> Integration is particularly simple for turbulent viscosity coefficient Model 1 where m = n = p = 0. The above then becomes

$$\frac{K}{6} \int_{X_0}^{X} dX = - \int_{\xi_0}^{\xi} \frac{\left(1 - \frac{\xi}{24}\right)}{\xi^2 \sqrt{\frac{\xi}{120} - \frac{\xi^2}{5500}}} d\xi.$$
 (101)

Here,  $X_0$  is the point where the turbulent wake begins, and  $\xi_0$  is the value of  $\xi$  at that point. If the wake is initially laminar, then  $X_0$  is the physical location of the transition point, and  $\xi_0$  equals  $\xi_{\text{laminar}}$  at transition. Integrating Equation 101 results in

$$\frac{K}{\theta} (x - x_0) = \left(\frac{80}{\xi^2} - \frac{6.5}{\xi}\right) \sqrt{\frac{\xi}{120} - \frac{\xi^2}{5500}} \bigg|_{\xi_0}^{\xi}.$$
 (102)

Since 6 was considered constant in Equations 101 and 102, then these equations are limited to regions of zero-pressure gradient. Equation 101 is not so limited.

Another case of interest is when Model 4 is used for the turbulent viscosity coefficient. This is the same model used by Less and Hromas (Reference 50). In this case, n = p = 0 but m = 1, and it is necessary to evaluate  $\rho_1/\rho_0$  before  $\xi$  and X can be related. The value of  $\rho_0$  is given by Equation 85. This equation can be rewritten as

$$\frac{\frac{\rho_0}{\rho_1}}{\frac{\gamma}{\gamma-1}} = \frac{\frac{\gamma}{\gamma-1}}{\frac{\gamma}{\gamma-1} \frac{T_{0_1}}{T_1} - \frac{\theta_{T_1}^2}{\theta_1^2} \frac{\gamma}{\gamma-1} \frac{T_{0_1}}{T_1} \frac{\xi}{\xi^2} - \frac{\gamma}{2} M_1^2 \left(1 - \frac{\xi}{24}\right)^2}.$$
 (103)

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Thus,

$$\frac{\rho_1}{\rho_0} = 1 + \frac{\gamma - 1}{2} M_1^2 - \left(1 + \frac{\gamma - 1}{2} M_1^2\right) \frac{\theta_T^2}{\theta_1^2} \frac{\xi}{24} - \frac{(\gamma - 1)}{2} M_1^2 \left(1 - \frac{\xi}{24}\right)^2.(104)$$

When this value is substituted in Equation 100, there results for this case, i.e., using Model 4

$$\frac{K}{A} dX =$$

$$-\frac{\left(1-\frac{\xi}{24}\right)}{\sqrt{\frac{\xi}{120}-\frac{\xi^2}{5500}}}\left[1+\frac{\gamma-1}{2}M_1^2-\left(1+\frac{\gamma-1}{2}M_1^2\right)\frac{\theta_{T_1}^2}{\theta_1^2}\frac{\xi}{24}-\frac{(\gamma-1)}{2}M_1^2\left(1-\frac{\xi}{24}\right)^2\left|\frac{d\xi}{\xi^2}\right|.$$
(105)

For an adiabatic forebody wall,  $\theta_{T_1}^2$  equals zero; upon integration, the abave equation becomes

$$\frac{\kappa}{\theta} (\mathbf{x} - \mathbf{x}_0) = -\int_{\xi_0}^{\xi} \frac{\left(1 - \frac{\xi}{24}\right)}{\sqrt{\frac{\xi}{120} - \frac{\xi^2}{5500}}} \left[1 + \frac{\gamma - 1}{2} M_1^2 \left(\frac{\xi}{12} - \frac{\gamma - 1}{2} M_1^2 \frac{\xi^2}{576}\right) \frac{d\xi}{\xi^2}, \quad (106)$$

where again  $\theta$  has been assumed constant, and  $X_0$  and  $\xi_0$  are as previously defined for turbulent flow.

Another limiting condition is that of a cold wall where  $\theta_{T_1}^2 = \theta_1^2$ . Using this assumption, Equation 100 takes a final form upon integration of

$$\frac{K}{0} (\mathbf{X} - \mathbf{X}_{0}) = -\int_{\xi_{0}}^{\xi} \frac{\left(1 - \frac{\xi}{24}\right)}{\sqrt{\frac{\xi}{120} - \frac{\xi^{2}}{5500}}} \left[1 - \frac{\xi}{24} + \frac{\gamma - 1}{2} M_{1}^{2} \left(\frac{\xi}{24} - \frac{\xi^{2}}{576}\right)\right] \frac{d\xi}{\xi^{2}},$$
(107)

where  $\theta$  also has been considered a constant.

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For Model 3 and  $\xi$  small, the relationship between X and  $\xi$  (Equation 75) takes the limiting form

$$\mathbf{X} \circ \boldsymbol{\xi}^{\frac{3}{2}}.$$

Since for  $\xi$  small

$$\Delta^2 \propto \xi^{-1}$$

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and

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then it can be shown that

$$\delta \propto \chi^{\frac{1}{3}}.$$
 (108)

This is in the limit of small  $\xi$  or large X, i.e., the far wake.

With Models 2 and 4, it can be shown that for  $\xi$  small and  $\rho_0 \approx \rho_1$ 

$$d\mathbf{X} \propto \frac{d\xi}{5}$$
.

Then,

$$x \propto \xi^{\frac{3}{2}}$$
.

In a similar manner, the limiting form of

$$\delta \propto x^{\frac{1}{3}}$$
(109)

is arrived at for the far wake region. Furthermore, for Models 2 through 4, it also can be shown that for  $\xi$  small

$$1 - \frac{u_0}{v_1} \propto X^{-\frac{2}{3}}$$
(110)

and

$$1 - \frac{H_0}{H_1} \propto X^{-\frac{2}{3}}.$$
 (111)

These also are in agreement with other investigations of the far wake.

Only in the case of Model 1 is a deviation noted from the proper asymptotic behavior as indicated by experimental data. With Model 1,

 $X \propto \xi^2$ .

and thus

for  $\xi$  small. It then follows that

 $\delta \propto x^{\frac{1}{2}}$ ,

that

$$1 - \frac{u_0}{u_1} \propto x^{-\frac{1}{2}}$$

and that

$$1 - \frac{H_0}{H_1} \propto x^{-\frac{1}{2}}.$$
 (113)

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(112)

This lack of a proper behavior in the limit of large X casts some doubt on the suitability of Model 1.

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#### APPENDIX V

#### WIND-TUNNEL TESTING AND DATA REDUCTION

#### 1. GENERAL

All wind-tunnel tests in support of the EUREKA program were conducted in the 40-in. supersonic tunnel Gas Dynamics Wind Tunnel, Supersonic (A) of the von Karman Gas Dynamics Facility (VKF) at the Arnold Engineering Development Center (AEDC). The complete series is as follows:

- 1. WT-I static stability tests in support of design feasibility study described in Volume I
- 2. WT-IIA wake survey and forebody surface pressure test (axisymmetric and asymmetric forebodies)
- 3. WT-IJB parachute performance tests (axisymmetric and asymmetric forebodies)
- 4. WT-III shock shape determination (axisymmetric and asymmetric forebodies); surface pressure distribution (asymmetric forebody)
- 5. WT-IV wake centerline survey (axisymmetric forebody)
- 6. WT-V wake survey (axisymmetric forebody)
- 7. WT-VI parachute performance tests (axisymmetric and asymmetric forebodies)

The tabulated wake survey and forebody surface pressure data are given in Volume III. The static stability tests are described in Volume I; the remaining tests are described in this appendix.

#### 2. WIND-TUNNEL DESCRIPTION

Tunnel A is a continuous, closed-circuit, variable density wind tunnel with an automatically driven, flexible plate-type nozzle and a 40- by 40-in, test section. The tunnel operates from Mach 1.5 to 6 at maximum stagnation pressures from 29 to 200 psia, respectively, and stagnation temperatures up to 300 F ( $M_{00} \leq 6$ ). Minimum operating pressures are about one-tenth the maximum at each Mach number.

#### 3. MODELS AND SUPPORT SYSTEM

Figure 29 shows the forebody models in detail. The basic Arapaho C and the Arapaho C with nose cone forebodies are axisymmetric. The blunted elliptical cone forebody has an elliptical base.

For the wake survey and parachute performance tests, the forebodies were supported with a horizontal wall-to-wall strut having a constant chord and a constant thickness. For the parachute tests, the riser line passed through the forebody and mounting strut and into a plenum tank where it was attached to the tensiometer and winch assembly. Figure 44 shows this setup.

The models were sting-mounted from the rear for the shock shape determination (WT-III).

#### 4. INSTRUMENTATION

From calibration results, the maximum variation of tunnel centerline Mach number is about ±0.5 percent.

The tunnel stilling chamber temperature is accurate to  $\pm 3$  R. The tunnel stilling pressure,  $p_0$ , was measured with transducers of 5, 15, 30, 60, 150, and 300 psid capacity that are considered accurate to within 0.3 percent of full-scale capacity.

The model base pressures were measured with 1, 5, and 15 psid capacity transducers, referenced to a near vacuum, which also are considered accurate to within 0.3 percent of the transducer capacity. The lowest base pressures were encountered at the  $M_{00} = 5$  low Reynolds number test conditions. At these test conditions, base pressures were about 0.008 psia. The 0.3 percent accuracy of a 1 psid transducer then could introduce errors of approximately ±37.5 percent of the measured values.

The local wake pitot and static pressures were measured with transducers of the same capacity us those used for base pressure measurement. The lo est pressures and, therefore, the greatest inaccuracies were encountered at the  $M_{00} = 5$  minimum pressure test conditions. Combined errors in the local static and pitot pressures may introduce inaccuracies of 0.2 M at  $M_{1} = 1.0$ . The inaccuracy, in this case, was determined using maximum errors in pressure measurements assuming (1) the local static pressure was equal to free-stream static pressure and was measured with a 1 psid transducer and (2) the pitot pressure was mensured with a 5 prid transfucer. Making these same assumptions at free-stream Mach number of 4, 3, and 2 and at the minimum pressure condition, inaccuracies in measuring a local Mach number of 1.0 are 0.11, 0.06, and 0.03 M<sub>1</sub>, respectively. At the high-pressure conditions for these tests, the accuracy of measurement at  $M_{00} = 5$ ,  $M_{L} = 1.0$  is increased by approximately four. The lower Mach number test cases reflect a similar accuracy increase at the high-pressure test conditions.

Table DX lists the test conditions for the wake survey tests. Based on this table, the error in the measurement of the local static pressures, which are approximately equal to the free-stream static pressure and therefore are the most critical for measurement, due to the inaccuracy of a 1 psid transducer appears in the third significant digit except for the  $M_{100} \approx 5$  case. The total pressures, being higher than the static pressures, then should reflect a higher degree of accuracy.



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Figure 44 - Forebody Support Installation

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Forebodies	M <sub>cc</sub>	$\frac{\frac{\text{Re}_{\infty}}{\text{in.}}}{10^6} \times$	P <sub>o</sub> pria	P co (psia)	T <sub>o</sub> (deg R)	Probe stations X D
Basic Arapaho	3.	0.05	2,8	0.360	581	1, 2, 3, 5, 7,
C. Arapaho C with nose cone.	Z	0.365	19.0	2.430	582	9, and 11 for all test points
and blunted	3	0.06	5.9	0.176	583	
emptical cone	3	0. 50	43.0	1.170	582	
	4	0.09	13.5	0.090	583	
	4	0.50	73.0	0.460	583	
	5	0.13	30.5	0.058	585	
	5	0.50	133.0	0.251	631	
Arapaho C with	2	0.06	2.8	0.360	560	0.5, 1, 2, 3,
nose cone only	3	0.075	5.9	0.170	560	5, 6, 7, 9,
	: <b>,4</b>	0.10	13.5	0.090	560	test points
	5	0.135	30.5	0.058	560	
Arapaho C with	5	0.06	2.8	0.360	560	0.5, 1, 2, 3,
nose cone only*	3	0.075	5.9	0.170	560	5, 6, 7, $3$ , and 11 for all
	4	0.10	13.5	0.090	560	test points
	5	0.135	30.5	6.058	56C	

## TABLE DX - WAKE SURVEY TEST CONDITIONS SUMMARY

WT-IIA, pitot and static rakes.

\*WT-IV, pitot, static, and total temperature centerline probes.

\*WT-V, pitot rake.

The wake survey rakes used in WT-IIA and WT-V were of a cruciform design with multiple probes, thereby making it possible to obtain complete wake profiles at each X/D station without lateral or vertical movement of the sake. Table X lists locations of the probes; Figure 45 shows the probe geometry.

The centerline probes used in WT-IV have the same geometry as those used on the multiprobe takes.

The WT-IIB parachule drag measurements were made with a 200-lb tensiometer located in the winch plenum tank. A time nistory of the dynamic drag output from the tensiometer was recorded on an oscillograph, and the average drag values were determined from the recorded traces. The accuracy of the 200-lb tensiometer determined from static loads is as follows. AFF (L=1)/-67-192 Volume

ารกับสีมีและสุขารและสามารถเร็จ (มีแก่ได้มีเสียง) 		WI	WT-VI				
	Pitot	rake	Static	rake	Pitot rake		
Probe number	Y (in.)	Z (in.)	Y (in.)	2 (in.)	Y (in.)	Z (in.)	
	-1.610	0	-0.966	0	-4.57	C	
2	υ	0	-0.483	0	-4.17	0	
3	0.322	0	0.322	0	-3.7?	0	
4	0.644	0	0.805	0	-3.37	0	
5	0.966	0	0	-1.449	-2.97	0	
6	1.288	O	0	-0.966	-2.57	0	
7	1.610	0	C	-0.483	-2.17	C	
8	1.932	0	0	0.322	-1.77	0	
9	2.576	0	0	0.805	-1.37	0	
10	0	-2.576	0	1.289	-0.97	0	
11	0	-1.610	0	1.932	-0.64	0	
12	0	0.322	0	2.576	-0.32	0	
13	0	0.644			2.17	0	
14	0	0.966			3.37	0	
15	0	1.288			0	-4.57	
16	0	1.610	۰. ۱		-0	-4.17	
17	0	1.932			0	-3.77	
18	0	2.254		•	0	-3.37	
19	0	2.576			0	-2.97	
20	0	2.898			0	-2.57	
21	0	3.220			0	-2.17	
22	0	3.864			0	-1.77	
23	0	4,508	n .		0	-1.37	
24	0	5.152			0 -	j o	
25				ी कहा। अन्तर इन्द्रिय कर	0	0.32	
26			1		0	0.64	
21			-		ິດ	0.96	
28					0	1.28	
29					C	1,60	
30					0	1.92	
31					0	2.57	
<b>T1</b>	-0.966	0			0.966	с	
T2	0	-0.966			0	-0.966	

TABLE X - WAKE SURVEY PROBE LOCATIONS

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Figure 45 - Probe Geometry

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Error (pounds)			
±0.536			
±0.493			
±1.290			
±1.820			

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These accuracy values were for the tensiometer alone and, therefore, do not reflect any further inaccuracies caused by friction in the change-ofdirection pulleys in the system.

The WT-VI drag measurements were made with a 60-lb tensionieter. The tensiometer was calibrated for both 30- and 60-lb load ranges. The change-of-direction pulleys in the system were equipped with needle bearings in place of bronze bushings as used in previous tests. Average drag values were monitored with a low response servopotentiometer, and a time history of the dynamic output from the tensiometer was recorded on an oscillograph. The accuracy of the complete drag measuring system, determined from repeated static loads applied before the test, is shown below.

Load range (pourds)	Error (pounds)
0 to 5	±0,15
6 to 15	±0.25
16 10 30	±0.33
51 to 60	±0,84

Parachute performance for both tests was monitored on two high-speed, 16-mm motion picture cameras - one for conventional motion pictures and one for schleren photography. Still photographs, both conventional and schlieren, also were obtained.

## 5. PARACHUTE MODELS

PARASONIC parachutes, which have a constructed shape resembling the inflated shaped of a Hyperfle parachute (Reference Figure 28), were tested. The Hyperfle parachutes are constructed with a flat, porous roof and a truncated, conical nonporous skirt. The construction details of the PARASONIC models are given in Table XI.

## 6. DATA REDUCTION

## a. PARASONIC Performance Data

The data obtained from the PARASONIC performance tests are given in

> Tables XII and XIII. In addition to the average drag values, it was also desired to have average maximum and minimum drag values. These values were obtained from the recorded oscillographs as shown below.



Due to improper oscillograph calibration, average maximum and minimum drag values could not be determined for the WT-VI tests. It was possible, however, to obtain the drag oscillation frequency.

The diametric and angular measurements given in Tables XII and XIII were obtained from the high-speed motion pictures.

## b. Wake Survey Tests

During the reduction of the wake survey data acquired under WT-LA, a significant amount of data scatter was observed in formularing velocity profiles required for computation of experimental wake momentum defects (see Section III, Item 3a). The scatter was sufficient to cause considerable difficulty in evaluating experimentally achieved wake momentum defects obtained by integration of the velocity profiles. To combat this difficulty, the wake data for each test condition were smoothed by means of a multiple regression technique to permit more meaningful integration of the velocity profiles. This was achieved by expressing the family of curves formed by the velocity profile data points as a two-dimensional power series (i.e., a prover series in Y/D - or Z/D - and their cross products) to produce a best ratisficil fit for the family of curves. The best fit uses an equation of the form

# TABLE XI - MODEL DECELERATOR FABR

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	Measured parameters											
Model number (580A)	λT (%)	λG (%)	D <sub>c</sub> (in.)	D open (in.)	D <sub>i</sub> (in.)	1 s (in.)	NS	NG	<b>WR</b> (in.)	DR (in. )	Roof mes	
014-												
-001	4.60	10.7	6.0	3.06	5.83	12.4	12	12	0.25	1.625	HT-83-44 Nome	
-002	5.50	10.5	6.0	3.04	5.64	12,5	12	12	0.25	1.698	12.0i  oz/sq yd pl	
- 603	4,95	10.5	6.0	3.04	5.85	12.5	12	12	0.25	i.625	coated with D15	
-004	5.05	10.5	6.0	3.05	5.78	12.7	12	12	0.25	1.625	porosity control	
-005	5,00	10.3	6.0	3.02	5.81	12.4	12	12	0.25	1.625	coating with D-6 ible thermal coa	
615												
-001	4.85	7.87	6.0	2.64	5.79	12.69	12	12	0.25	1.625	MIL-T-713A, C	
-002	4.75	6.70	6.0	2.43	5.70	12.50	12	12	0.25	1.750	Type S nylon lac   (50-lb tensile) p	
- 003	5. IZ	9.28	6.0	2.86	5.75	12.38	12	12	0.25	1.750	coated on form D1569-F839 pol	
											thane, porosity trolled by coatin D-65 flexible th coating	
<b>016-</b>	-				ĺ							
-001	5.19	10.9	7.86	4.06	8.04	17.0	12	12	0.25	2.000	HT-83-44 Nome	
-002	5.25	10.6	7.86	4.0	7.64	16.5	12	12	0.25	1.937	warp) 3.01 oz/	
-003	5.45	10.7	7.86	4.01	7.50	17.0	12	12	0.25	2.000	precorted with F839 polyureth porosity contro coating with D- ible thermal co	
017-												
-001	5.44	8.90	7.86	3.70	7.55	17.0	12	12	0.25	2.300	MIL-C-5040 Ty	
~ 002	5.13	9.60	7.86	3.82	7.50	17.0	12	12	0.25	2.300	with libers rem precoated on fo	
- 003	5.44	8,27	7.86	3.54	7.55	17.0	12	12	0.25	2.300	with D1569-F83 polyu. sthane, f controlled by co with D-65 flexil thermai coating	

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# DECELERATOR FABRICATION DATA

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	Materials, coatings, specifications										
)R n. )	Roof mest	Suspension lines	Roof cap, skirt panels	Skirt reinforcement web, apex reinforcement web, roof/skirt seam, radials							
625 688 625 625 625	HT-83-44 Nomex cloth (172-Ib tensile, warp) 3.01 og/sq yd pre- coated with D1569- F839 polyurethane, porosity controlled by coating with D-65 flex- ible thermal coating	MIL-C-5040 Type I cord, 100-lb tensile strength	0.84 oz/sq yd 4787 rylon coated with D1569-F839 polyurethane	Double fold, cotton bias tape, 88 × 80 count, 20 lb/in.							
.625 .750 .750	MIL-T-713A, Class II, Type S nylon lacing (50-lb tensile) pre- coated on form with D1569-F839 polyure- thane, porosity con- trolled by coating with D-65 flexible thermal coating	MIL-C-5040 Type I cord, 100-1b tensile strength	0.84 oz/sq yd 4787 nylon coated with D1569-F839 polyurethane	Double fold, cotton bias rape, 88 × 80 count, 20 lb/in.							
, 000 , 937 , 000	HT-83-44 Nomex mesh cloth (172-lb tensile, warp) 3.01 oz/sq yd, precoated with D1569- F839 polyurethane, porosity controlled by coating with D-65 flex- ible thermal coating	M1L-C-5040 Type III cord with fibers re- moved	0.84 oz/sq yd 4787 nylon coated with D1569-F839 polyurethane	Double fold, cotton bias tape, 88 × 80 count, 20 lb/in.							
. 300 . 300 . 300	MIL-C-5040 Type I with fibers removed precoated on form with D1569-F839 polyurethane, porosity controlled by coating with D-65 flexible thermal coating	MIL-C-5040 Type III cord with fibers re- moved	0.84 oz/sq yd 4787 nylon coated with D1569-F839 polyurethane	Double fold, cotton bias tape, 88 × 80 count, 20 lb/in.							

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Y/D Cases

$$V = a_0 + a_1 \left(\frac{X}{D}\right) + a_2 \left(\frac{X}{D}\right)^2 + a_3 \left(\frac{X}{D}\right)^3 + a_4 \left(\frac{Y}{D}\right)^2 + a_5 \left(\frac{Y}{D}\right)^2 \left(\frac{X}{D}\right) + a_6 \left(\frac{Y}{D}\right)^2 \left(\frac{X}{D}\right)^2 + a_7 \left(\frac{Y}{D}\right)^2 \left(\frac{X}{D}\right)^3 + a_8 \left(\frac{Y}{D}\right)^4 + a_9 \left(\frac{Y}{D}\right)^4 \left(\frac{X}{D}\right) + a_{10} \left(\frac{Y}{D}\right)^4 \left(\frac{X}{D}\right)^2 + a_{11} \left(\frac{Y}{D}\right)^4 \left(\frac{X}{D}\right)^3 + a_{12} \left(\frac{Y}{D}\right)^6 + a_{13} \left(\frac{Y}{D}\right)^6 \left(\frac{X}{D}\right) + a_{14} \left(\frac{Y}{D}\right)^6 \left(\frac{X}{D}\right)^2 + a_{15} \left(\frac{Y}{D}\right)^6 \left(\frac{X}{D}\right)^3 + a_{16} \left(\frac{Y}{D}\right)^8 + a_{17} \left(\frac{Y}{D}\right)^8 \left(\frac{X}{D}\right) + a_{18} \left(\frac{Y}{D}\right)^8 \left(\frac{X}{D}\right)^2 + a_{19} \left(\frac{Y}{D}\right)^8 \left(\frac{X}{D}\right)^3$$

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Z/D Cases

$$\begin{aligned} \mathbf{V} &= \mathbf{b}_{0} + \mathbf{b}_{1} \left( \frac{\mathbf{X}}{\mathbf{D}} \right) + \mathbf{b}_{2} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{3} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{3} + \mathbf{b}_{4} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{5} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{2} \left( \frac{\mathbf{X}}{\mathbf{D}} \right) + \\ & \mathbf{b}_{6} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{2} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{7} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{2} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{3} + \mathbf{b}_{8} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{4} + \mathbf{b}_{9} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{4} \left( \frac{\mathbf{X}}{\mathbf{D}} \right) + \\ & \mathbf{b}_{10} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{4} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{11} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{4} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{3} + \mathbf{b}_{12} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{6} + \mathbf{b}_{13} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{6} \left( \frac{\mathbf{X}}{\mathbf{D}} \right) + \\ & \mathbf{b}_{14} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{6} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{15} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{6} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{3} + \mathbf{b}_{16} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{8} + \mathbf{b}_{17} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{8} \left( \frac{\mathbf{X}}{\mathbf{D}} \right) + \\ & \mathbf{b}_{18} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{8} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{2} + \mathbf{b}_{19} \left( \frac{\mathbf{Z}}{\mathbf{D}} \right)^{8} \left( \frac{\mathbf{X}}{\mathbf{D}} \right)^{3}. \end{aligned}$$

The curve fits used only even powers of Y/D or Z/D because of symmetry that exists in the wak of the forebody.

The curve fits are made to the experimentally derived velocities and are the best statistical fits to all the data presented. Thus, the curve is matched to the data points with scatter as well as to the more accurate date points. The multiple regression solution then gives the least squares value of the coefficients for a particular sample of observations.

Samples of the curve fits are shown in Figures 46 through 50. The sinusoidal type variation of the polynomials above Y/D values of 0.4 are smoothed out by the integration since the area under the curve is approximately the same as would exist without the sinusoidal type variation of velocity predicted by the polynomial. The sinusoidal trace is caused by the polynomial curve fit as the polynomial tries to pass through the



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existing data points. Where the velocity is constant or approximately constant with the change in Y/D or Z/D, the polynomial is unsuccessful in matching the experimental data. The one polynomial for each case is the best fit to all the data points at each X/D station; therefore, the polynomial is attempting to fit or match a surface of points in two dimensions.

## c. Test Data

Tables XII and XIII give the parachute performance test data (Table XII has data for the WT-IIB series and Table XIII, for the WT-VI series). Each drag and stability parameters were determined.

> (Reverse is blank) 133

TABLE XII " PARACHUIN PERFORMANCE TEST DATA, WT-HB SERIES

A V 10 0 1 17.30 23, 90 \$5.62 24.50 15.20 14.25 11 11 31.50 20.40 10.15 12.48 22.50 21,00 11.88 d. 25 9.23 5. 5 13.21 Ş 2 0.0 о. Э о о 0.0 ວ ວ 37.60 0.0 0 ... د: ت 000 0.0 e ñ 9.9 0.0 ා ර 0.0 0 о S 5. 2 9 0 ŭ. 0 0 3 ,0° õ 2.0 3 0°0 0 ٤.5 ¢.0 0. 0 0.0 0 0.0 5.1 3.0 ¢. 5 0.0 0.0 0 ت 0 с, о 0 ÷., ¢,0 2.5 0.0 0.0 0. O 0.C 0 Ģ 5 1.0 0.¢ un ri 0.7 3. C ¢.3 2.3 2.5 ¢.5 ۍ چ ۰.4 د. د Э.С 0.0 с. О ی 0 জ ক 0 с Т 1.0 : (Bap) 0 0.0 0.0 0.0 o ú 0,0 0.0 2,2 o d 0.0 0.0 0.0 0 5.0 0.1 0.0 ъ. с 0.0 0.7 °, 2.5 0 0 2 • • 0.0 \* 9. ¢ 0. 0.0 0 9 ÷.0 0 0 .M 0.1 0.2 0.0 1.1 0.0 . 1.0 0.01 <u>ار</u> - ۱ 6. D 8.0 s.5 \$ 79 **4**. 73 ¢. 64 4.5.4 4.60 5,09 5. 14 4.70 4.99 6.39 4.84 4.93 ¢. 50 4.40 \$: <del>1</del>3 4. 24 6. ng 3 4 4.55 5.01 4.37 4.46 ÷;; + 4. 33 | 4 72 4.65 5.35 5.14 5.26 5.30 4.57 4.75 : 4.62 • ÷. 49 4.4 4.84 5.07 4.61 5 37 5. JB : ŝ 93.4 +.35 0. 50 4.97 4.37 1.71 4.80 4.63 **4**. 23 5. 30 4. 55 A, 80 **6**. 37 4.73 4.30 3.64 6. 25 5. **4** 5 0 2.6 4.75 3.08 1.4.4 4.05 4.10 4.87 4.23 5.23 8.80 3.60 5.19 • 70 5.00 4.57 4.30 4.30 : \*.17 4.73 4.51 5. 23 : 135 Min • ő 4.77 4.40 6.90 4.73 4. b7 5.10 4.50 **6. 00** 4. 90 5.17 4, 63 4.80 MAX 5, 20 5, 53 22.8 6. 13 5.55 5.10 5.23 05 ¥ 5.30 5.00 5.10 4.95 4.75 \*, 00 5.15 **\*.8**7 **€**,93 5.05 5.87 4.70 • 33 4. 30 4. 23 5.45 5.65 5,40 5.55 5.7 с, Ç 0.890 0.930 0.932 1. 916 0.967 3. 780 0. 932 0.920 0.884 0.924 0. 908 919.0 0.879 0.934 0.912 0.897 J. 915 3, 490 0.867 0.911 0.864 0.835 0.873 0.942 0. 900 0.978 1.009 1.005 0.955 0.897 0.875 0.864 358 0.928 0.897 0.984 0.923 0.925 • : : -10 26.85 6.44 41.7 33.5 0 0 0 0 62.5 22 7 26.3 0.0 42.9 41.9 50.0 55.5 38.5 38.5 40. A 0.0 38.5 5.24 45.4 27.8 20.0 37.6 0 (\* ¢.0 43.4 29.4 5.51 52.7 5.34 41.6 5.01 34.9 0.0 5.54 36.6 ; 5.98 37.6 5.55 41.7 5.38 45.5 5.52 47.1 5. 58 37.7 5, 25 60.0 isd ... 5.90 55.E : 5.59 5,60 5.25 5.34 5.421 5.24 10 10 10 10 10 10 5. 05 5.65 5.27 5.48 5.38 5.49 5.30 1 1 5. . 5 0 5.10 5.89 6.03 5.59 5. 73 5.56 5.30 5.54 5 4 5 Ave 5. . : : . 5.60 3.70 4.30 5.50 MAR 5.30 ×. 10 4.60 3. 83 5.27 5.10 4.73 5.37 5.20 4.60 5.27 5.40 5.55 4.97 4.83 5.40 4.77 5.15 5.30 5,18 4.50 4.20 5, 30 4.65 4.67 2.20 5.30 5.60 5.03 5.73 5.40 5.50 3.63 5.47 5.37 1. 23 5.83 5.20 5.47 4.99 (in. . -: : : . Mark 20 9 9 69. 5.43 5. 63 5.70 5.73 5.67 5.50 9.90 5.63 5.40 5.37 6. ...) 5.55 5.60 5, 65 5.77 5.70 5.70 5.55 5.40 6 10 10 5 6.30 6.27 6. 25 3.30 5.83 6.00 6.00 5.70 6.00 5, 63 5. 75 6. 35 5.75 : • . . . 36.5 0, 29 0, 32 d/ Z | Q/ Å 0.52 0.37 0.30 0. 29 C. AB 0. 76 0. 36 0.76 3.68 0.76 5.66 0.60 3.55 0.55 0.56 0.34 0.59 0.56 0.53 0.36 0.33 0.36 6.33 0.32 0.31 0.30 0.48 6.37 0.31 0.31 0.29 0.31 0.29 0.34 0.32 0.36 0.34 0.31 0. 22 0. 30 0.40 0.42 0.38 0.38 9.36 0.37 0.27 0.29 0. 25 C. 35 9.39 0.34 A. 26 0. 29 9. 25 0. 26 0.21 0.29 0.17 0.27 0.99 E 56 0 81 10.74 0. 77 0. 67 0.81 0.78 0.58 0.54 0.33 0.35 6.21 3.29 0.28 0.31 J. 31 6. 33 Ż 0.17 0.51 0.24 0. 29 0.59 0.56 C. 30 0.35 2.35 1. 25 0.33 0.32 0,31 0.35 0.53 0.38 0.33 0. 29 0, 30 0, 25 C. 25 с.<sup>с</sup> l(ada) 29 103 1.03 135 146 102 573 66 113 • 88 29 126 101 135 105 172 108 126 128 100 118 104 93 5 51 3 127 233 505 104 : 0.115 0.150 C. 152 0.135 0. 125 CD Max 1 Min 1.170 0.115 0. 233 0.103 0.155 1.102 1.151 1.022 1.027 0.808 0.825 0.610 C. 110 U. 333 0.282 0. 238 0 295 0.235 0.214 a. 200 0. 252 0.233 0.150 0.191 G. 139 0. 137 0. 157 0. 123 0.171 0.197 0.199 0.199 0. 1 29 0. 144 0.152 0.159 0.148 0.177 0.184 0.170 261 . r 1 2 2 0 1 95 R. 156 0. 163 0. 153 0.163 6.167 0.156 2.417 0.846 0.958 0.815 3 938 1.663 1. 334 0.504 C. 255 0.212 0.308 0.185 0.189 0.181 0.584 0.358 0.274 C. 157 0. 249 0.155 0.350 0.159 0.417 0.417 10.213 2. 141 30. 177 1.005 1. 434 0.698 0. 773 6.640 6.539 0, 350 9.302 105.0 0.359 0.376 0, 364 0.170 0, 226 0.273 0.341 0, 212 0. 253 0. 245 0. 274 9.178 0.165 1.581 1. 279 0.252 0, 352 0.451 0.627 0.299 0.398 0.293 0.346 1.600 0.955 C, 184 0. 129 ú. 150 0. :40 0.689 0.312 0, 195 0. 145 0.142 1.350 1.204 1.029 0.234 U. 146 0.658 2.42.0 0.275 0. 267 0.260 0.315 0.327 0.287 0.305 0.157 C. 205 0.123 0.155 0.115 9-13 548 0.744 0.972 0.295 AVE 5 032 0.103 đ . . . 1, 1941 0.50 0.50 c 1.00 | 63 3 20 Σ Ň < 3 425 `` ۲ р Х \$. \* \$.5 S. O 0.0 ¢. 9 8.0 9.0 5.0 6.5 0 °. e. J ¢.5 5.3 ÷.5 5.0 6.0 7.0 9. C 6.0 5.0 5.0 **9**.0 6.0 7.0 8.0 5.0 5. Ĉ ê. 5 ÷.5 £.5 5.0 6.0 7.0 8.0 њ С G . I 8.0 • 6.0 C ~ 1 8.0 0 ? 4.5 4.5 ÷.5 014-003 Forebody P/C No 100-410 Baelc Arapaño 1C.º

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	5	e, 55	<b>4</b> . 60	•.37	4.40	•	· :	3.68	6.29	· ·			•.70	4.05	4.37	• • •	4. 25	4.33	:	4.33	2.83	4.47	5.25		1.83	06 · +	4.33	1 2.03		1.52	<b>Q</b>	•. 07	50.c		3.05		9.00	4. BC	67 · 1	3.00		10.4		5.05	;	6. 27		4.97	5		• •	A RA L
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	с. в.,	0.934	0.912	0.473	163 0		0.925	0.867	0.854	•	0. 311	0.864	0, 663	0.635	0. 873	•	0.881	C. 845	•	0, 395	0.829	0. 885	0. 905	•	0.912	0, 891	0.864	0.410	•	0, 905	0.878	5 % % · · ·		0.878	0.915	:	0, 945	0.925	0.835	C. 71.9		0.674	0, 858	0.917		C. 884	0.870	0.936	0.669		0. 656	0 882 1
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0.12	0.21		6.0	0.10	0.17	0.1%	61.5	+	c. 16(	0.181	0	0.161								0.1.0				0.410		0.463	0. 472	0.61	6, 699	0.779	0.539	0.536	0.805	0.427	0.431	845 n	0.621	0.247	0.297	0.367	0.591	0.588	0.315	0.303	0.327	0.449	0.418	0.947	0.313	0.288	0 100	
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0. 422       0. 119       0. 205       10. 119       0. 205       10. 119       0. 0.0       0. 0.0         0. 129       0. 205       119       0. 205       111       0. 0.0       0. 0.0       0. 0.0       0. 0.0         0. 119       0. 205       111       0. 205       111       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0       0. 0.0<					; ; ;	-	0 277	6 12 0	249	107	0 69 0			5	\$0.6	0.440	9.38	4.84	•. ••	0.0	0.0	0.0
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) 7   e	0.0	14.1	•		0.0	0.0	6.1	Ð. O	0	0 0 0 1	0.0	200	0.0	0.0	11.4	<b>*</b> . <b>•</b>		11.9	0.0	0.0	7.1	14.7	0.0	11.6		0.0	11.1	9.8	0	5 C				0.0	12.0	<b>₽</b> ` <b>6</b>	10.5	0	۵ ÷	•		i c	2.0	30.6	17.2		0,0	12.0	•	
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: <u>-</u>							<u> </u>						0	-	<u> </u>		-		=					<u>-</u>	~																		~				7 50	07 <b>-</b> 7	- <b>-</b>	<b>.</b> .
	12 0	9 · 4		0.2	0.1	0.24	0.2	0.17			0	0	6 13	0.0	0.10	0.22	0.18	0.11	C. 03	0	2	•		`.	• ·	~	• •	- -	5 c	5	4	<b>0</b> .1	с. <b>з</b>	0.32	0. <b>2</b> 4	0.14	0.1				4	-	0.52	0.76	0. ÷0	0.94	0	0.45	6. 70	8 9 9 U
0.37	0.33	6. 3			0.355	. 322	0.319	0.220			0	0.219	0. 13.7	0.095	0.810	0.401	0.431	<b>С. ]С</b> В	C. 369	0. 309	0. 147	C. 295	0.284	C 044	4. L. 4	0.75	0. 280	<b>1</b>			02 0	112.	6. <b>41</b> 3	6.413	0. 145	C. 101						299 0	e. J 7.	1 458	1 423	101-1	0.460	996 J	1.257	114 1.35
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TABLE XIII - PARACHUTE PERFORMANCE TEST DATA, WT-VI SERIES

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Matrix         Matrix<	•	- ~~		2-044	<b>, , , , , , , , , , , , , , , , , , , </b>			с С	· ''	$P_{b'}/P_{\infty}$		("us) d		 	 1	D <sub>1</sub> (.e.	-	o (de	2	-1
Maximum         Control         Control <t< th=""><th>Veriboa, P/C N.</th><th>۵ ۲</th><th>۹ ۲ ۲</th><th><u>ي</u> ب</th><th>2 (S. 1 )</th><th>8+<sub>ле</sub>∕лв. × 10<sup>1°</sup></th><th>AVE</th><th>N ix Min</th><th>- (a) - (a)</th><th>0/2 0/A</th><th>Mai</th><th>Min</th><th>VVR (cp.</th><th>, <sup>DP</sup> (</th><th>D<sub>c</sub> Max</th><th>Lin</th><th>AVR</th><th></th><th>Γ.</th><th>5 Å</th></t<>	Veriboa, P/C N.	۵ ۲	۹ ۲ ۲	<u>ي</u> ب	2 (S. 1 )	8+ <sub>ле</sub> ∕лв. × 10 <sup>1°</sup>	AVE	N ix Min	- (a) - (a)	0/2 0/A	Mai	Min	VVR (cp.	, <sup>DP</sup> (	D <sub>c</sub> Max	Lin	AVR		Γ.	5 Å
	Ar puse 234.90		52.5	2	1.0	0.127	0.336		102	0.17 0.16	0.23	5.60	5. 91 75.	°. Э	92 SR	20.7 <b>4</b> 91	5.37	ი ა	0.0	сî.
Number         Numbr         Numbr         Numbr <td>C WITE 2 LORE CODE</td> <td></td> <td></td> <td>• • • • • • • • • • • • • • • • • • •</td> <td><b>1</b>77</td> <td></td> <td>- 375</td> <td></td> <td> </td> <td>0.16</td> <td></td> <td>•</td> <td></td> <td></td> <td></td> <td>ic [ +. 23</td> <td>°. ⊷ ₹</td> <td>0.0</td> <td>0.0</td> <td>0</td>	C WITE 2 LORE CODE			• • • • • • • • • • • • • • • • • • •	<b>1</b> 77		- 375		 	0.16		•				ic [ +. 23	°. ⊷ ₹	0.0	0.0	0
No.         No. <td></td> <td>с. ~</td> <td></td> <td></td> <td></td> <td></td> <td>0.342</td> <td></td> <td><b>4</b>6</td> <td>0.10 0.15</td> <td>6.07</td> <td>5.75</td> <td>55.</td> <td>s</td> <td>58</td> <td>2.60</td> <td>5.09</td> <td>0 0</td> <td>0.0</td> <td>ń,</td>		с. ~					0.342		<b>4</b> 6	0.10 0.15	6.07	5.75	55.	s	58	2.60	5.09	0 0	0.0	ń,
Number         Constrained         Constrained <t< td=""><td></td><td>0.'y</td><td></td><td></td><td></td><td></td><td>0.361</td><td>•</td><td>52</td><td>0.12 9.10</td><td>0 6.17</td><td>5.67</td><td>5.92 0.</td><td>0.0</td><td>87 5.</td><td>(3   *.87</td><td>5.30</td><td>0 0</td><td>0.0</td><td>ċ</td></t<>		0.'y					0.361	•	52	0.12 9.10	0 6.17	5.67	5.92 0.	0.0	87 5.	(3   *.87	5.30	0 0	0.0	ċ
Number         Nume         Nume         Nume		5.0		• 00		5.098 1	0.424		136	0, 22 0, 15	9 5.27	5.80	6.04 0.		<u>، د</u>	3 5.03	5.38	0	2. 2.	*
Number         Num         Num         Num		ç.					9.421	•	3	0.2115.0				; 		4.51	2.00	0.0	0.2	0
Number         Numbr         Numbr         Numbr <td></td> <td>0 1.</td> <td></td> <td></td> <td></td> <td></td> <td>0.341</td> <td></td> <td></td> <td>0.20 0.11</td> <td>1</td> <td>5.87</td> <td>6.02 0.</td> <td>0 </td> <td>00</td> <td><u>5</u>.13</td> <td>2</td> <td>0.0</td> <td></td> <td>ं</td>		0 1.					0.341			0.20 0.11	1	5.87	6.02 0.	0 	00	<u>5</u> .13	2	0.0		ं
		5. C	·	3, 06		0.073	0.496	• • •	1 128	0.32 0.36	5 . S	9.20	6.27 0.	ہ۔ 	20   2 	3 5.66	. 70	0 3	0.0	୍
Number         Condition         C		د د		~			0.565		67	0.29 0.2	· · · · · · · · · · · · · · · · · · ·				۰ •	5 4.43	رد: .¢	10.0	0.7	.7
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Number         5.0         5.0         1.13         2.171         0.100         0.11         2.171         0.100         0.11         2.171         0.100         0.11         2.171         0.100         0.11         2.171         0.100         0.11         2.171         0.11         2.171         0.100         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11         0.11 <td></td> <td>5 q 0 f</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>•</td> <td></td> <td>0 24 0 21</td> <td></td> <td>а </td> <td>, 2 </td> <td> </td> <td> </td> <td></td> <td>v</td> <td></td> <td>2 2 2 2</td> <td>3</td>		5 q 0 f						•		0 24 0 21		а 	, 2 	 	 		v		2 2 2 2	3
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5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5.0       5		2.0				• 4:-	0.335		8	0.25.0	1 1 7.35		5.96 32	سر . و	é		3	ມ ວ່	<b></b>	0
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	<b></b> .	0.5		÷ 60		0.043	18/ 0	•	4	0.34	•	•				-				-
2.20       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       1.025       0.19       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10       0.10 <td< td=""><td></td><td>6. J</td><td></td><td></td><td></td><td></td><td>1. 026</td><td></td><td>* 1 1</td><td>0. 63 8. 2</td><td>· · ·</td><td></td><td></td><td>, </td><td></td><td></td><td>-</td><td>- - -</td><td>- -</td><td>5</td></td<>		6. J					1. 026		* 1 1	0. 63 8. 2	· · ·			, 			-	- - -	- -	5
C16-002       5,2       1,4       5,5       0,4       5,5       0,5       7,5       7,5       5,7       5,4       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       5,7       <		0.1	11			•	. 025		106	0. 23 0. 1	;		: 		•					<u>ب</u>
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$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		0			~		0.827		140	0.49 0.45	5 7. HO	7. 70	7.75 0		÷	77 6.71	• ] 5. 74	6 0	÷.	
5.0       1.005       1.005       0.57       1.70       7.55       7.65       7.76       1.75       7.65       7.76       1.75       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76       1.76		0.7					0.712].	• • •	161	0.48 0.4	5 7.80	7.57	7.50 0	ح	<i>.</i>	80 ( 6. <del>1</del> )	1 8.01	ن 	ž	
<b>6.</b> (a) <b>6.</b> (b) <b>6.</b> (c) <b></b>		5.0		2,00		0.035	1.005		162	0.56 0.51			دی 	د	÷.	90 6.67	1 5.74	0		
7.0       7.0       7.5       7.6       7.6       7.6       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       7.7       6.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0		و ر ا					10 × 35 1.	, , , , ,	130	1 C. 54 C. 54	5 7.73	7.65	7.085 0	. u .	178 E.	13 4 6.05	6 3.69	6.9	0.0	0
6.3       5.3       7.70       7.70       7.70       7.75       6.97       6.77       9.955       7.70       7.75       6.0       0.735       7.70       7.75       6.0       0.735       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.75       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76       7.76		2.5				-,	5.866	· · ·	1 145	0.53 0.56	1 7.70	7.55	7.62 0	.0 0.	Na   5.	33 ( ¢. 5)	0.45	0.0	0.0	c.
5.0       3.73       2.743       2.743       2.743       2.743       2.743       2.743       2.743       2.743       2.744       2.0       2.745       7.457       7.457       7.457       7.457       7.457       7.453       7.464       2.0       2.72       2.72       2.77       6.65       2.73       2.73       2.73       2.73       2.73       2.73       2.73       2.73       2.73       2.74       2.0       2.74       2.0       2.74       2.0       2.74       2.0       2.74       2.0       2.74       2.0       2.74       2.74       2.74       2.75       2.0       2.74       2.74       2.0       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.75       2.74       2.74       2.74       2.75       2.74       2.74       2.74       2.75       2.74       2.74       2.75       2.74       2.74       2.75       2.74       2.74       2.75       2.74       2.74       2.75       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74       2.74		6.0	<b></b>			-	0. 955 .		176	0.54 0.54	5 7.80	7.70	7.75 6	.0 0.	13 - 0.	87   <.76	1 4.70	( )	0.0	Ċ,
5.0       0.736       0.745       7.57       7.57       7.57       7.61       5.77       6.64       0.2       0.0         5.0       0.700       0.700       0.45       7.67       7.57       0.0       7.45       5.77       6.64       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0		5.0		57. 5		9. 673	S. 743   .	•		0.44 0.44			~ 	ج	يد 	20 4.5.	1 1.49	0 0 0	0	-
7.2       7.4       7.4       7.4       7.4       7.4       7.4       7.5       9.0       6.9         5.7       4.00       5.0       0.304       1.0       107       0.53       1.60       7.53       1.60       6.13       6.42       7.0       6.7         6.0       0.451       1.07       0.57       0.60       7.45       7.45       7.0       6.7       0.0       0.6         7.0       6.0       1.17       0.44       0.45       1.00       7.46       7.45       0.0       6.42       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       <		6.0					0.786		:	0.46 0.44	1 7.57	7.57	7.47 0	ें 	16.1 5.	77   é.éc	0 6.64	0 0 0	0.0	Ċ,
5.0       (1.304)       7.05       (1.304)       7.10       7.13       7.13       7.13       7.13       7.14       7.70       6.27       6.0       6.13       6.45       6.42       6.42       6.43       6.45       6.42       6.43       6.45       6.42       6.43       6.45       6.43       6.45       6.43       6.45       6.42       0.2       7.40       7.74       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2       0.2		ر. ۲ و. و.					0.700			0.45 0.4	1 7.60	1. 23	7.42 O	о с з с з с	<b>6</b> .	83   o. 13	5:53	0.0	¢.	Ų
6. c       6. c       7. (5)       7. (5)       7. (5)       7. (5)       7. (5)       7. (5)       7. (5)       7. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (5)       6. (7)       6. (7)       6. (7)       7. (6)       7. (6)       7. (6)       7. (6)       7. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)       0. (7)		C. 2		<b>4</b> , 00		050	0.304		4	0.78 U.54					¢ 	31 1 7. 70	6 23	0.0	0.0	Ċ.
7.0       0.453       117       0.4 0.45       7.40       7.50       0.0       0.0       0.73       6.01       0.756       0.740       7.50       0.0       0.755       0.12       0.70       0.795         6.0       5.00       5.00       0.453       117       0.45       0.47       1.60       7.35       7.40       7.50       7.43       5.63       5.73       5.73       5.743       5.75       0.7       0.70       0.73         5.0       5.00       5.00       1.03       1.02       1.03       1.02       1.03       1.02       1.13       5.74       5.67       5.75       6.7       0.0         6.0       5.00       5.00       0.45       7.40       7.40       7.40       0.95       6.73       5.73       5.75       6.7       7.73         6.0       5.00       5.01       1.02       1.03       1.02       1.03       1.02       1.01       0.74       0.0       0.01       0.01       0.01       0.01       0.01       0.01       0.01       0.01       0.02       0.01       0.01       0.01       0.01       0.02       0.01       0.01       0.01       0.01       0.01       0.01       0.0		9					0.47		107	0.57 0.60	7.60	7.45	7, 43 0.	0 0 0	.9 60	33   6.60	6.42	0.0	0. A	0
6.0       6.0       5.00       0.42       0.41       1.60       7.33       7.4 <sup>-</sup> 0.9       0.43       5.58       0.2       7.0         5.0       5.00       0.567       0.132       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       0.0       1.04       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0		-					0.453		117	0.4+ 0.45	1 7.60	7.40	7.50 0	6.9 G	155   6	A3   A. 50	1 6.72	0.0 .0	0 5	
5.0       5.00       5.00       5.00       5.00       0.05       1.03       1.03       1.02       1.03       1.02       1.03       1.02       1.03       1.02       1.03       1.02       1.03       1.02       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       1.03       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0       0.0		9					5 469		125	0.42 0.4	7 1.60	1.35	7.4-1	.0 i 0.5	50 6.	73 6 6, 43	1 4.58	; 0	ر. ا	~
6.0       6.169       6.169       6.169       6.169       6.169       6.169       6.171       6.184       0.071       0.1971       0.151       5.07       6.06       0.0       0       0.0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0       0 </td <td></td> <td></td> <td></td> <td><b>C</b>0</td> <td></td> <td>0.067</td> <td>0.132</td> <td>· · ·</td> <td>108</td> <td>1.03 1.0</td> <td></td> <td></td> <td>0</td> <td></td> <td>4</td> <td>71 5.67</td> <td>5 75</td> <td>2</td> <td>0.0</td> <td>3</td>				<b>C</b> 0		0.067	0.132	· · ·	108	1.03 1.0			0		4	71 5.67	5 75	2	0.0	3
7.5     7.50     7.50     7.50     7.50     7.50     7.50     6.38     6.41     0.5     0.5       7.5     5.6     5.6     5.75     5.6     5.75     5.6     5.6     5.81     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.7     5.6     5.7     5.6     5.7     5.6     5.7     5.7     5.7     5.6     5.7     5.6     5.7     5.6     5.7     5.6     5.7     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     5.6     <		4				-	0.169		*3	0.060.46		6.73	6.83) 0.	0.0	121 0.	15,97	7 6.04	0.0	0.0	3
017-762     5.00     0.247     0.247     0.247     1.12     1.06     1.06     1.12     1.06     1.01     6.01     6.03     5.28     5.21     5.21     5.01     6.0       6.0     6.0     1.05     1.05     1.05     1.05     1.05     1.05     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01     1.01		0.7					0.271	· · ·	166	3.65 0.65	0 . 7 6	7.08	2	0.0	114 6.	•3 6.38	5 6.41	0.0	0.0	Ŷ
6.6 0.274 0.274 0.274 0.274 0.27 0.27 0.90 6.50 6.27 1.5 0.30 6.27 1.5 0.30 6.27 1.5 0.30 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 6.27 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 0.01 1.5 1.5 1.5 1.5 1.5 1.5 1.5 1.	017-00	0	3.425	5 100		r 0.067	0.247		83	1.12 1.00		· · · · ·				13 و E	5.85	2.0	6.0	
		2					0.274	· · · ·		1. 09 1. 04	0 *	9.8.¢	7.14 23	5 0 	1 9 1 90	50   6.03	1 6.27	ن +	5.0	
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0	0.0	5,9	0°.0	0.0	ę. >	P1	9, 6	4.0	0.0	0.0	C. 13	6.7	1.0	0.3	0.0	6.0	0°0	0, 0	6. Ú	0.0	0.0	9.0	a. c	c. o	G. O	<b>9</b> , 0	0. C	5.0	A V	F ol	FI Lui C	DJ m	ي ج و ا	T	8	- <b>(</b>	57 57	5 U	]
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