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INVESTIGATION OF THE LOW SPEED

FIXED GEOMETRY SCRAMJET

"INLET DESIGN PRACTICE MANUAL"

Edited by

James Johnson

TECHNICAL REPORT AFAPL-TR-68-7

February 1968

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INVESTIGATION OF THE LOW SPEED

FIXED GEOMETRY SCRAMJET

"INLET DESIGN PRACTICE MANUAL"

Edited by James Johnson

FOREWORD

This report was prepared by the General Applied Science Laboratories, Inc., Westbury, New York, a wholly owned subsidiary of The Marquardt Corporation, on Contract F-33(615)-67-C-1084, Task 3012, "Investigation of the Low Speed Fixed Geometry Scramjet." The work was administered under the direction of the Air Force Aero Propulsion Laboratory, Air Force Systems Command. Mr. R. Canny, (APRP) was the project engineer for the laboratory.

The studies presented began in September 1966 and were concluded in August 1967. Mr. James Johnson was responsible for the technical direction of this program at GASL. The technical efforts were performed by the following scientists; Messrs. M. Abbett and G. Bleich for the two-dimensional flow analysis and programming, and Drs. S. Angelucci and C. Ruger for the three-dimensional flow analysis and programming.

This report, GASL TR-667, was submitted November 1967.

ABSTRACT

Computer programs have been written to aid the design and analysis of two-dimensional, axisymmetric, and three-dimensional supersonic inlets. This report presents the fundamental analytic techniques, the use and operation of the computer programs, and the application to the design of supersonic inlets. The programs are written in Fortran IV for use on the 7094 high speed digital computer.

The two-dimensional and axisymmetric programs presented herein are written for generalized inviscid supersonic internal flow problems with uniform or non-uniform inlet entry conditions for entropy, total enthalpy, pressure, Mach number and flow direction. The program capabilities include the intersections and reflections of both family waves, the formation of shocks or expansions at corners, the formation of shocks by coalescence of waves from smooth walls, and the formation of contact discontinuities.

The three-dimensional programs presented herein are written for the calculation of the inviscid supersonic flow fields associated with basic elements of three-dimensional supersonic inlets. The methods utilized exact and linearized supersonic flow theory with engineering approximations to yield solutions to the following unit problems; delta wing flow, conical shock interacting with a plane surface, plane shock interacting with a conical surface, and the interaction of two different conical flow fields.

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NOMENCLATURE FOR SECTION IV

- a speed of sound, $a^2 = \gamma P/\rho$
- b $\sqrt{M^2-1} / o u^2$
- c, c, coefficients of specific heat
- $G \qquad \frac{(\tau \lambda) \quad \tau}{y} \quad j$
- h specific static enthalpy, $h = \frac{\gamma}{\gamma 1} p/\rho$
- H specific total enthalpy, $H = h + q^2/2$
- M Mach number, M = q/a
- p pressure
- q magnitude of the velocity vector, $q^2 = u^2 + v^2$
- R gas constant
- S entropy

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- u velocity component in x direction
- v velocity component in y direction
- x abscissa (horizontal axis = z in cylindrical polar frame (z, r, θ) for axisymmetric flow)
- y ordinate (vertical axis = 4 in cylindrical polar frame for axisymmetric flow)
- δ angle flow turns when going through oblique shock
- c_{p}/c_{v} , the ratio of specific heats
- λ characteristic slope
- u viscosity (=0 in this report

υ	Prandtl-Meyer turning angle (see equation 15)
ρ	density
σ	angle oblique shock makes with incident flow
τ	streamline slope, $\tau = v/u$
A	angle velocity vector makes with x axis
Subscript	<u>s</u>
() _x	<u>9×</u>
1, 2	conditions in front of and behind shock, respectively
A,B,C,etc	. variable is to be evaluated at the indicated point
Superscri	pts_
j	<pre>0 for two-dimensional flow 1 for axisymmetric flow</pre>
	averaged quantity, also indicates a line between two points
I, II	down running and up running characteristic respectively
The follo	wing is standard notation on the figures
	down running characteristic
~	up running characteristic
	oblique shock
	contact discontinuity (interface, slip stream)

INTRODUCTION

The use of three-dimensional flow fields in the design of supersonic and hypersonic inlets has been under experimental and analytical investigation at GASL for several years under Air Force sponsorship as reported in References 1 through 6. Three-dimensional designs can be used for either fixed or variable geometry inlet configurations over a wide flight Mach number range to obtain, for example, high inlet contraction ratios and capture mass flows, to prevent boundary layer separation, and to reduce heating loads to the inlet structure. General use of three-dimensional designs however, has been limited by the development of practical analytic techniques. In most cases where three-dimensional analytic techniques are available, they are either so highly restricted, or complicated and time consuming, that they are impractical for use in a typical inlet design effort.

Practical methods for the design and analysis of three-dimensional supersonic inlets have been under development at GASL for the Air Force Aero Propulsion Laboratory as part of the overall investigations of the low speed range supersonic combustion ramjet (SCRAMJET). These methods combine exact and linearized three-dimensional theory with engineering approximations to yield solutions to unit problems which are basic elements of three-dimensional supersonic internal flow fields, i.e., delta wing flow, conical shock interacting with a plane surface, plane shock interacting with a conical surface, and the interaction of two different conical flow fields. A combination of these unit problems can be used to design and analyze a large variety of supersonic and hypersonic three-dimensional inlets.

These methods for two and three dimensional inlet design and analysis, have been programmed in Fortran IV for use on the IBM 7094 digital computer. This report presents the complete description of the fundamental analysis, the program use and operation, and the application to the design of three and two dimensional supersonic inlets. This work was performed for the Wright-Patterson Air Force Base Aero Propulsion Laboratory under contract F33(615)-67-C-1084.

PROGRAM OBJECTIVES AND APPROACH

The overall objective of this effort was to generate digital computer programs for aid in the design and analysis of two and three dimensional supersonic inlets. The analytic techniques which form the basis of this work have been developed at GASL during the past several years under Air Force sponsorship. The purpose of this report is to present these fundamental analytic techniques, the use and operation of the computer programs, and the application to the design of supersonic inlets. The aim is to provide a practical tool for two and three dimensional inlet design, in addition to a detailed description of the analysis. To this end, the following sections describe;

- Section III A discussion of the methodology used for threedimensional inlat design and the use of the computer programs in these efforts.
- Section IV A complete description of the two-dimensional and axisymmetric internal flow field analysis and computer programs.
- Section V A complete description of the three-dimensional analysis and computer program elements.

It is seen then, that this report can be used as a "Design Manual" to aid in three-dimensional inlet design, or as an initial step in developing a more sophisticated or modified analysis. In either case, it must be noted that the current work presented here has limitations which should be the object of continuing study. These limitations will be clear as they arise in the following sections in this report. A summary of the overall limitations however, is given here.

- (1) Viscous effects are neglected
- (2) Completely supersonic flow required
- (3) Completely supersonic leading edgss required
- (4) Three-dimensional computations only for unit problems.

METHODS FOR THREE-DIMENSIONAL INLET DESIGN

The detailed three-dimensional and two-dimensional analytic techniques and computer programs will be described in the following sections. It is necessary here, however, to describe the overall methodology for using these techniques before going into the analysis.

The overall inlet design process is schematically shown in Figure 1. It is seen that several steps are required in the design process:

- a) choice or definition of inlet design performance characteristics
- b) choice or definition of inlet design concept, e.g., two-dimensional, three-dimensional, with or without centerbody, etc.
- c) two-dimensional calculations to define essential performance properties
- d) three-dimensional corrections to define exact performance properties
- e) evaluation of performance with respect to initial required performance levels
- f) repeat steps (b) to (e) until required performance is obtained.

A summary of each of the above design process steps is given in the following discussion.

The initial steps (a) and (b) are closely interrelated since the required inlet design performance characteristics generally dictate the choice of the inlet design concept. The requirement of fixed geometry operation over a wide Mach number range, for example, might require a more highly three-dimensional inlet design (with possibly one or more inlet central bodies) than a fixed geometry inlet design for a more restricted Mach number

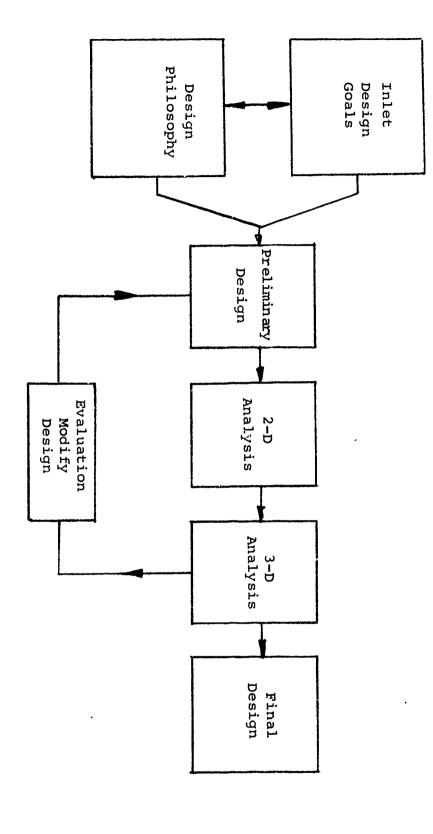


FIGURE 1 - INLET DESIGN PROCESS

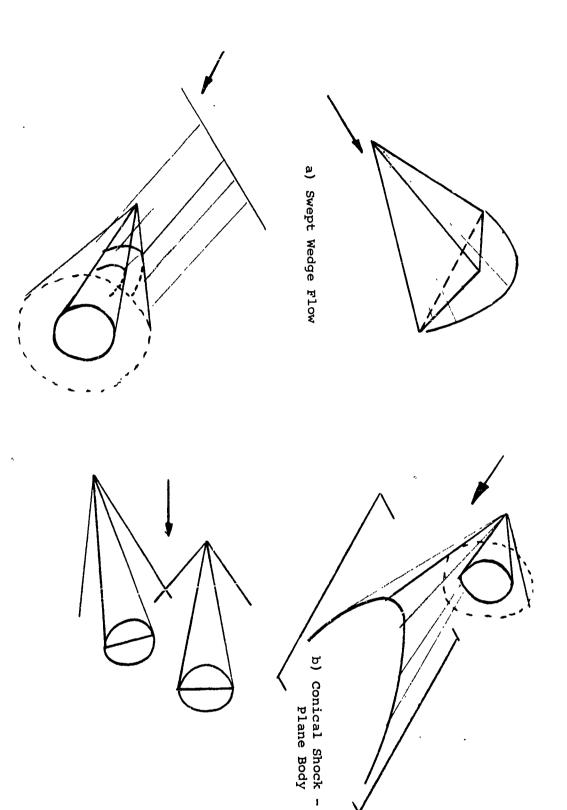
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range of flight operation. Other requirements might lead to a variable geometry inlet design to attain performance goals. In any case, these initial steps of the design process require decisions based upon inlet design experience.

The next step (c) utilizes the two-dimensional and/or axisymmetric computer programs described in Section IV. This step
would be the final step for a completely two-dimensional or
axisymmetric design. For the case of a three-dimensional design,
however, it forms the first step. Several overall inlet design
geometries are roughed out by the inlet designer and the computer
program provides a detailed analysis of each one. The overall
properties of the various inlet flow fields are then evaluated
with respect to the initial design goals and the most promising
designs are chosen for further consideration by including the
effects of three-dimensionality.

The next step (d) utilizes the three-dimensional computer program elements described in Section V. The basic elements of a large variety of supersonic three-dimensional inlet flow fields are programmed for machine calculation in this phase of the design process. These elements as shown in Figure 2 are the delta wing flow field, the interaction of a conical shock with a plane surface, the interaction of a plane shock with a conical surface, and the interaction of two different conical shocks. The techniques used for these machine computations however, can also be used manually to compute the flow field of almost any supersonic threedimensional configuration. The level of three dimensionality designed into the inlet geometry in this step of course depends again upon the initial design goals. The overall procedure here again is to investigate various geometries until the desired performance conditions are achieved. However, here the overall configuration is known from the two-dimensional and axisymmetric analysis of step (c). The procedures in this step are to incorporate, for example, various leading edge sweep angles, cone angles, etc.

An inlet configuration is now defined and analyzed. Step (e) calls for an evaluation of the resulting performance based upon the initial design performance goals. At this point, either these goals are satisfied or steps (c) and (d) are repeated. In this manner then the required inlet performance characteristics are achieved.



6

c) Plane Shock - Conical Body

d) Double Conical Shock

FIGURE 2 - THREE DIMENSIONAL SUPERSONIC INLET FLOW ELEMENTS

TWO-DIMENSIONAL AND AXISYMMETRIC SUPERSONIC INTERNAL FLOW COMPUTER PROGRAM

A. Summary and Introduction

A computer program has been written for the computation of two-dimensional and axisymmetric inviscid supersonic internal flows for configurations typical of supersonic and hypersonic inlets. The program is designed for use either for the design and analysis of completely two-dimensional or axisymmetric inlets, or as part of the design exfort of a three-dimensional inlet as described in Section III. The program is written in Fortran IV for use on the IBM 7094 and the CDC 6600 high speed digital computers.

The overall computer program can be summarized as follows:

General - Calculation of complete inviscid two-dimensional and axisymmetric supersonic internal flow fields.

THE STATE OF THE S

Input - Uniform or non-uniform entry conditions for entropy, total enthalpy, pressure, Mach number and flow direction.

Capabilities

- Intersection and reflections of waves of same and opposite families - no limit to number.
- · Formation of shocks at compression corners.
- For ation of shocks by coalesence of waves from smooth walls.
- · Formation of contact discontinuities.
- · Reflection of waves from walls.
- · Perfect gas.

Output - Fluid mechanic and thermodynamic parameters, wave locations and contact discontinuity location at each point of the characteristic mesh.

A complete detailed description of this computer program is given in this section. Part B describes the types of flows considered and summarizes the assumptions and simplifications in the analysis and computer program. In Part C the Euler equations of motion are presented and non-dimensionalized. In addition, the special forms of the governing equations are given here for characteristic, oblique shock, and Prandtl Meyer expansion computations. Part D describes the manner in which the computation is performed and gives outlines of the various types of computations. Appendix I gives most of the information required by the user of the program. In Appendix III some sample calculations are presented.

A person who wishes to use the program with a minimum amount of effort should skim Part B and Part D. He should carefully read, in order, Part C-a and Appendices I-III.

B. Outline of the Program

a) Type of Flows Considered

The program computes internal flows typical of supersonic and hypersonic inlets. Included in the flow field computation are weak shocks of both families, their formation at sharp corners and by the coalesence of characteristics (envelope shocks), the intersection of shocks of the same and opposite families, the reflection of shocks on the inlet walls, the intersection of weak shocks and slip streams, and centered corner expansions. The gas is considered to be an inviscid perfect gas of constant ratio of specific heats. Since the method of characteristics is used to perform the calculation, the flow must remain supersonic throughout. Strong shocks are not considered.

b) General Comments - Approximations and Simplifications

A schematic representation of a typical inlet is given in Figure 3. The flow impinges on the inlet at some specified angle of actack. There may be an expansion, a shock, or neither, at the leading edge of the lower wall and at the cowl. Due to smooth or abrupt compressions along the two walls, shocks may form. In addition, expansion waves may be generated by smooth or sharp expansions of the walls. The shocks and empansions will then interact in complicated ways.

Oblique Shock
Contact Discontinuity (Slip Stream)

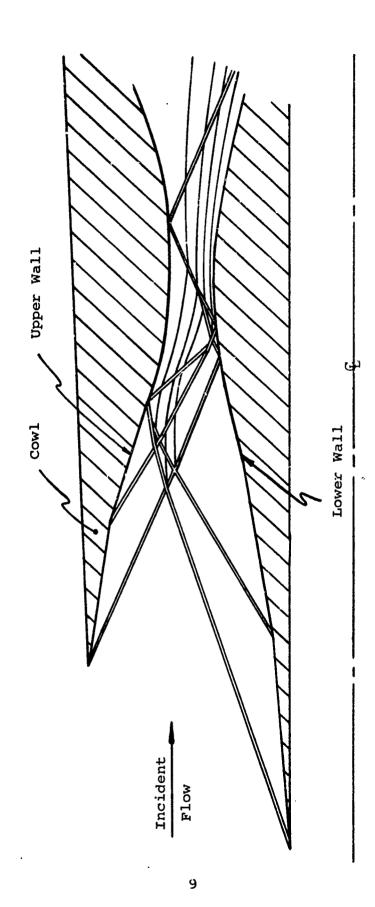


FIGURE 3 - TYPICAL INLET CONFIGURATION (AXISYMMETRIC)

Because of storage and time considerations and the desire to keep the program as simple as possible while retaining sufficient accuracy, various assumptions and simplifications have been made. These are outlined here with their justification.

1. Intersection of Two Weak Shocks of the Same Family

In general, such an intersection will result in the two shocks continuing as either two shocks and a contact discontinuity or as one shock, an expansion fan, and a contact discontinuity (Figure 4). However, in cases of interest here the second shock or expansion fan (\overline{OE}) of Figure 4) and the contact disconuity (\overline{OD}) usually have a much smaller effect on the flow field than does the primary shock (\overline{OC}) . Hence, in the program, two shocks of the same family intersecting are continued as only one shock of that family.

2. Intersection of Two Shocks of Opposite Families

When two weak shocks of opposite families intersect they will in general continue as two shocks of opposite families and a contact discontinuity (Figure 5). In the program such an intersection is treated with no simplifications.

3. Intersection of a Weak Shock and a Contact Discontinuity

Ordinarily such an intersection will continue as a shock, a centered expansion, and a contact discontinuity (Figure 6). Fresently, the contact discontinuity is dropped when it intersects an oblique shock.

4. Formation of Attached Oblique Shocks
By Discontinuous Compression

This is done in a straightforward fashion (Figure 7) with no simplifying assumptions.

5. Reflection of Oblique Shocks from Walls

This is done in a staightforward fashion, the shock being reflected with strength such that the reflected shock has a turning angle which is minus that of the incident shock. (Figure 8).

FIGURE 4 - INTERSECTION OF TWO SHOCKS OF THE SAME FAMILY

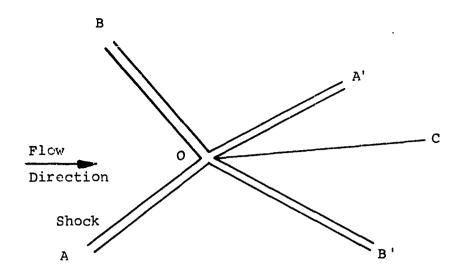


FIGURE 5 - INTERSECTION OF TWO SHOCKS OF OPPOSITE FAMILIES

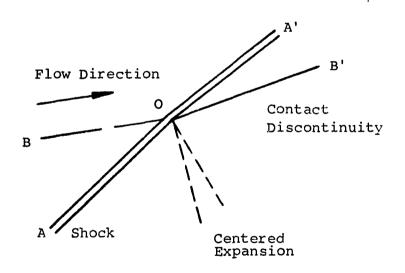


FIGURE 6 - INTERSECTION OF AN OBLIQUE SHOCK AND A CONTACT DISCONTINUITY

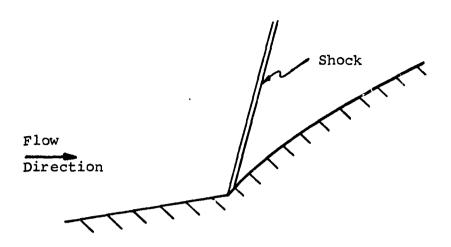


FIGURE 7 - FORMATION OF ATTACHED OBLIQUE SHOCKS
BY DISCONTINUOUS COMPRESSIONS

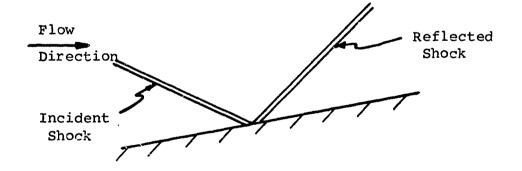


FIGURE 8 - REFLECTION OF AN OBLIQUE SHOCK FROM A WALL

6. Formation of Detached Oblique Shocks
By Coalescence of Characteristics

After each point of the characteristic mesh has been computed, tests are made to detect the crossing of characteristics of the same family, indicating the formation of an oblique shock. When such a crossing occurs, a shock is entered in the flow field at that point and its subsequent development is followed. (Figure 9)

7. Centered Expansions Due to Discontinuous Expansion Corners

These are performed by dividing the turning angle of the corner into a finite number of segments and then making regular characteristic computations. (Figure 10)

8. Reflection of an Oblique Shock from the Axis of Symmetry

In the case of axisymmetric flow, the possible flow configurations arising when an oblique shock reflects on the axis of symmetry, are several and complicated. There is no provision in the program to treat this problem. One can expect the program to usually blow up as an oblique shock approaches the symmetry axis. However, it may be that the shock will reflect, as from a wall, away from the symmetry axis.

9. Compression Corner on the Symmetry Axis in Axisymmetric Flow

The only compression corner allowed on the symmetry axis in axisymmetric flow is at the leading edge of the lower wall. In addition, the initial data line must go through the leading edge of the lowe. wall. (See Part D-a)

10. Viscous Effects

At present there is no consideration of viscous effects in the program.

C. Analysis

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a) Non-Dimensionalization and General Equations of Motion

The dimensional Euler equations of motion for the steady, inviscid, nonisentropic flow of a perfect gas of constant specific heat ratio, γ , are

continuity
$$(\bar{\rho} \ \bar{y}^{\dot{j}} \ \bar{u})_{x} + (\bar{\rho} \ \bar{y}^{\dot{j}} \ \bar{v})_{y} = 0$$
 (1) momentum
$$\bar{\rho} \bar{u} \bar{u}_{x} + \bar{\rho} \bar{v} \bar{u}_{y} + \bar{p}_{x} = 0$$
 (2a)
$$\bar{\rho} \bar{u} \bar{v}_{x} + \bar{\rho} \bar{v} \bar{v}_{y} + \bar{p}_{y} = 0$$
 (2b)

energy
$$\overline{v}_{\overline{x}} + \overline{v}_{\overline{y}} + \overline{p}_{\overline{y}} = 0$$
 (2b)

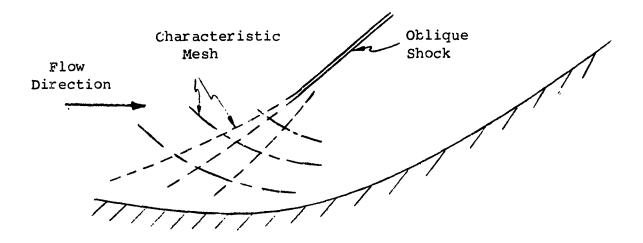


FIGURE 9 - FORMATION OF A DETACHED OBLIQUE SHOCK
BY COALESCENCE OF COMPRESSION WAVES

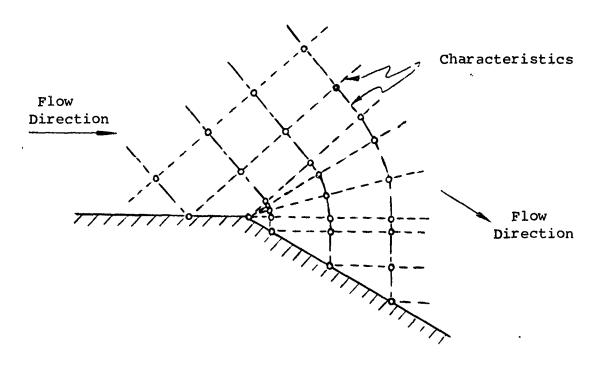


FIGURE 10 - CENTERED EXPANSIONS DUE TO DISCONTINUOUS EXPANSION CORNERS

where x and y are axes of a right handed cartesian frame (cylindrical frame) with velocity components u and v respectively. The x axis is positive in the general direction of the incident flow. j=0 for two dimensional flow and j=1 for arisymmetrical flow, ρ is the density, p the pressure, S the entropy, and the bars indicate dimensional quantities. Now we divide all pressures by reference pressure \bar{p} , densities by $\bar{\rho}_0$, temperatures by \bar{T}_0 , lengths by $\bar{1}_0$, velocities by $\sqrt{p_0/\rho_0} = \sqrt{R} |\bar{T}_0|$ where R is the gas constant and $\bar{p}_0 = \bar{\rho}_0 |\bar{R}\bar{T}_0$, and we subtract \bar{S}_0 from all entropies are divide the difference by c. Then, in nondimension with tities p, ρ , u, v, x, y, S, the equations are, (w , \bar{p}_0), $\bar{p}_0 = \bar{p}/\rho_0$, $\bar{S}_0 = (\bar{S}-\bar{S}_0/c_v)$, etc.

$$(\rho u y^{j})_{x} + (\rho v y^{j})_{y} = 0$$
 (4)

$$\rho u u_{x} + \rho v u_{y} + p_{x} = 0$$
 (5a)

$$\rho u v_{x} + \rho v v_{y} + p_{y} = 0$$
 (5b)

$$uS_{x} + vS_{y} = 0 (6)$$

where

$$S = \ln (p) - \gamma \ln (\rho)$$
 (7)

The user of this program is free to pick any reference length, \overline{l} , he chooses. If the incident flow is uniform and the simplified input is used (see Appendix I), the reference pressure and temperature are chosen to be the free stream (i.e. incident) static pressure and temperature. The non-dimensional specific static enthalpy is given by

$$h = \frac{\gamma}{\gamma - 1} \frac{p}{\rho} \tag{8}$$

and the specific total enthalpy by

$$H = h + \frac{u^2 + v^2}{2} = \frac{a^2}{v - 1} + \frac{q^2}{2}$$
 (9)

where q (= $\sqrt{u^2 + v^2}$) is the modulus of the velocity and a (= $\gamma p/\rho$) is the square of the speed of sound.

Since the flow is inviscid and steady, H and S are constant along a streamline. When there are shocks, the entropy, S, suffers a jump increase.

For completeness, the remaining parts of this section will present well known special forms of the governing equations to be used when we make certain computations, e.g., characteristic computations. All variables in the equations are non-dimensional. Those readers wishing more detailed explanations of the mathematical character of supersonic, inviscid, perfect gas flows should look in any standard text book on gas dynamics, e.g., References 7,8,9.

b) Characteristic Equations

Along characteristic, or Mach, lines, in the absence of shock waves, the Euler equations can be combined so that we have only total derivatives of certain quantities in the direction of the characteristic line. It is well known that for our cases the characteristic directions are given by

$$\lambda^{T} = \frac{dy}{dx} = \frac{uv - a\sqrt{u^{2} + v^{2} - a^{2}}}{u^{2} - a^{2}}$$
 (10a)

$$\lambda^{II} = \frac{dy}{dx} = \frac{uv + a\sqrt{u^2 + v^2 - a^2}}{u^2 - a^2}$$
 (10b)

$$\lambda^{\text{III}} = \frac{dy}{dx} = \frac{v}{v} = \tau \tag{10c}$$

Henceforth, $\lambda^{\rm I}$ will be referred to as a down-running characteristic and $\lambda^{\rm II}$ as an up-running characteristic. Along $\lambda^{\rm I,II}$ the Euler equations can be combined to give

$$\frac{d\tau}{dx} \pm b \frac{dp}{dx} = \left[\frac{(\tau - \lambda^{I,II}) \tau}{y} \right] .j$$
 (11)

where

b =
$$\sqrt{M^2 - 1} / \rho u^2$$
 and M (=q/A) is the Mach number.

Along λ^{III} , the streamline, we have

$$dS = dH = 0 \text{ (no snocks)} \tag{12}$$

We can write equations (lla) in differential form as:

$$\Delta \tau - b\Delta p = \left[\frac{(\tau - \lambda^{\mathrm{I}}) \tau}{y} \right] \cdot j \Delta x = G^{\mathrm{I}} \Delta x \cdot j$$
 (13a)

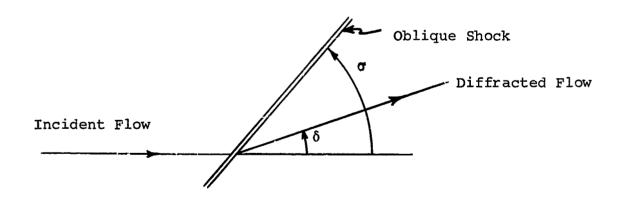
along a down running characteristic and

$$\Delta \tau + b\Delta p = \left[\frac{(\tau - \lambda^{II})}{Y} \right] \Delta x \cdot j = G^{II} \Delta x \cdot j \quad (13b)$$

along an up running characteristic.

c) Oblique Shocks - Rankine Hugoniot Equations

Let subscript l refer to the conditions in front of (upstream) the shock and subscript 2 refer to the conditions behind (downstream) the shock and let σ be the acute angle the incident flow makes with the shock wave.



 δ is the turning angle of the flow. The Rankine Hugoniot equations are

$$\frac{p_2}{p_1} = \frac{2\gamma M_1^2 \sin^2 \sigma - (\gamma - 1)}{\gamma + 1}$$
 (14a)

$$\frac{\rho_2}{\rho_1} = \frac{(\gamma+1) \ p_2 + (\gamma-1) \ p_1}{(\gamma+1) \ p_1 + (\gamma-1) \ p_2} \tag{14b}$$

$$\tan^2 \delta = \tan \left(\frac{(\rho_2/\rho_1 - 1)}{(\tan^2 \sigma + \rho_2/\rho_1)} \right)$$
 (14c)

$$M_{2}^{2} = \frac{(\gamma-1) M_{1}^{2} \sin^{2} \sigma + 2}{\sin^{2} (\sigma-\delta) [2\gamma M_{1}^{2} \sin^{2} \sigma - (\gamma-1)]}$$
(14d)

$$S_{2} = S_{1} + \ln \left[\frac{2\gamma M_{1}^{2} \sin^{2} \sigma - (\gamma - 1)}{\gamma + 1} \right] - \gamma \ln \left[\frac{(\gamma + 1) M_{1}^{2} \sin^{2} \sigma}{(\gamma - 1) M_{1}^{2} \sin^{2} \sigma + 2} \right] (14e)$$

$$H_2 = H_1 \tag{14f}$$

$$\tan^{-1} (\tau_2) = \tan^{-1} (\tau_1) + \delta$$
 (14g)

$$q_2 = \sqrt{2 \left(H_2 - \frac{\gamma}{\gamma - 1} - \frac{p_2}{\rho_2}\right)}$$
 (14h)

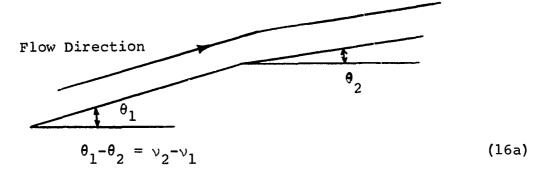
d) Prandtl-Meyer Expansion

The Prandtl-Meyer relation is

$$v = \sqrt{\frac{\gamma+1}{\gamma-1}} \tan^{-1} \sqrt{\frac{\gamma-1}{\gamma+1} (M^2-1)} - \tan^{-1} \sqrt{M^2-1}$$
 (15)

where v is the angle turned from Mach = 1 to reach the Mach number

M. If we have a corner with other than sonic velocity just prior to the corner, then denoting the conditions just prior to the expansion by subscript 1 and just after the expansion by subscript 2, we have



$$\frac{\mathbf{p}_{2}}{\mathbf{p}_{1}} = \frac{\left(1 + \frac{\gamma - 1}{2} \, \mathbf{M}_{1}^{2}\right)^{\frac{\gamma}{\gamma - 1}}}{\left(1 + \frac{\gamma - 1}{2} \, \mathbf{M}_{2}^{2}\right)^{\frac{\gamma}{\gamma - 1}}} \tag{16b}$$

$$\frac{\rho_2}{\rho_1} = \frac{\left(1 + \frac{\gamma - 1}{2} \,\mathrm{M}_1^2\right)^{\frac{1}{\gamma - 1}}}{\left(1 + \frac{\gamma - 1}{2} \,\mathrm{M}_2^2\right)^{\frac{1}{\gamma - 1}}} \tag{16c}$$

$$H_2 = H_1 \tag{16d}$$

$$s_2 = s_1 \tag{16e}$$

$$\tau_2 = \tan \theta_2 \tag{16f}$$

$$q_2 = \sqrt{\gamma \frac{p_2}{\rho_2}} M_2 \tag{16g}$$

- D. The Program General Outline
 - a) Initial Conditions Boundary Conditions Coordinate Systems

As indicated previously, the purpose of the program is to compute supersonic and hypersonic inviscid inlet flows. coordinate system and body geometry are represented schematically in Figure 11. The x axis is aligned in the general direction of the free stream flow (it is the axis of symmetry in the case of axisymmetric flow) but need not be exactly parallel to the incident It is positive in the general direction of the incident flow. The y axis is normal to the x axis and is positive in the direction determined by rotating the positive x axis 90° counterclockwise. corresponds to the radial axis in a cylindrical (x,r,θ) frame in the case of axisymmetric flow. It is assumed that the tips of both the cowl and the lower wall are pointed and of small enough included angle relative to the incident flow so that any tip shocks are attached and there are no regions of subsonic flow. Furthermore, for axisymmetric flow with a lower leading edge on the axis of symmetry, it is assumed that, in the coordinate system used, the x coordinate of the tip of the cowl is greater than or equal to the x coordinate of the tip of the lower wall.

The line 'parallel' to the y axis through the tip of the lower wall, \overline{AA} ', is considered to be the "data line" of the incident flow (see Appendix I).

The geometry of the upper and lower walls must be specified.

- b) Order of Progression of The Computation
 - 1. In The Absence of Shocks

The computation proceeds along down running characteristics issuing either from points on the initial data line, (AA', Figure 11) or from the upper wall. Referring to Figure 12, let us follow the outline of a typical computation, forgetting for the moment the possibility of shocks or centered expansions. Mesh points are indicated by circles and the flow is completely specified initially along the initial data line, AA'. The flow field at point C can be computed for the known conditions at points A and B (see Part D-c-1), where C is the point of intersection of the up running characteristic from A and the down running characteristic from B. The down running characteristic

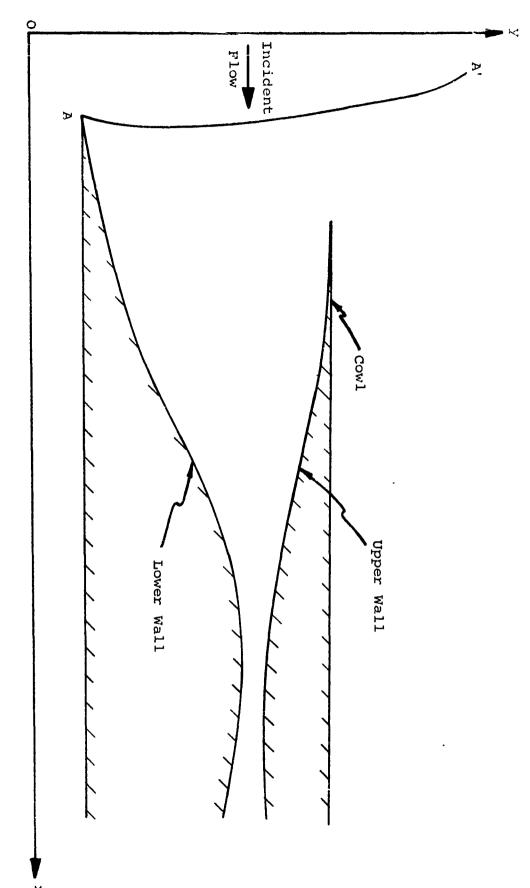


FIGURE 11 - SCHEMATIC OF COORDINATE SYSTEM AND BODY GEOMETRY

from C intersects the wall at D, and the flow conditions at D can then be obtained from the known conditions at C and the specified wall slope at D. (See D-c-2)

The computation proceeds in this manner working along down running characteristics from the initial data line to the bottom wall. Eventually, however, one of the down running characteristics will cross the cowl as illustrated in Figure 13a. C, the point formed by the intersection of the characteristics from D and B, is computed as an ordinary Then the conditions at E, the tip of the cowl, are obtained by interpolation between points A, B, C, and D. computation is continued by working along the down running characteristic issuing from E (forget for the moment the possibility of a shock at E), Figure 13b. When that characteristic is completed, the intersection, with the upper wall of the up running characteristic FG, from point F, can be determined. The flow conditions at G can then be computed using the known conditions at F and the specified wall slope at G. computation can be continued in a normal fashion working along the down running characteristic issuing from G.

In the absence of shocks and centered corner expansions, the entire inlet flow field could be computed in this fashion. In actual fact however, there will often be not only one, but several oblique shocks (of either or both families) which complicate matters somewhat.

2. In the Presence of Attached Shocks

Although up and down running characteristics have equal stature in the mathematical theory of supersonic inviscid flow, the situation is somewhat different in the program. That is to say, since the computation proceeds along down running characteristics, we have implicitly created a favoritism between the characteristics of opposite families. This difference is important when shocks and contact discontinuities are present.

This unequal treatment of characteristics of different families does not affect the basic order of the computation when up running shocks are present. (See Figure 14)

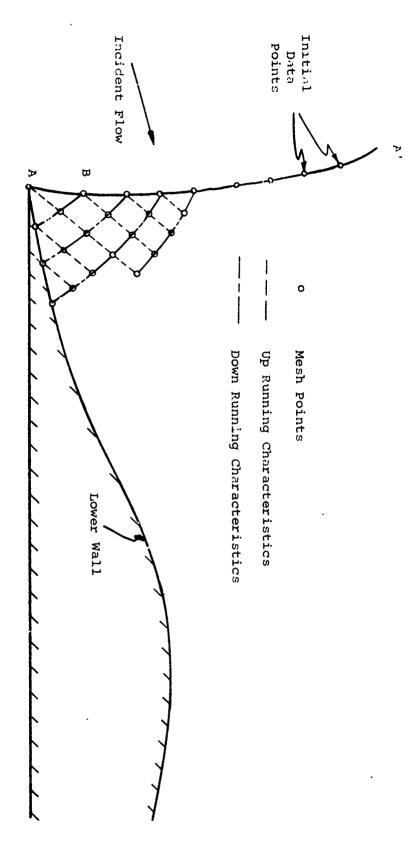


FIGURE 12 - SCHEMATIC OF COMPUTATION PROCEDURE

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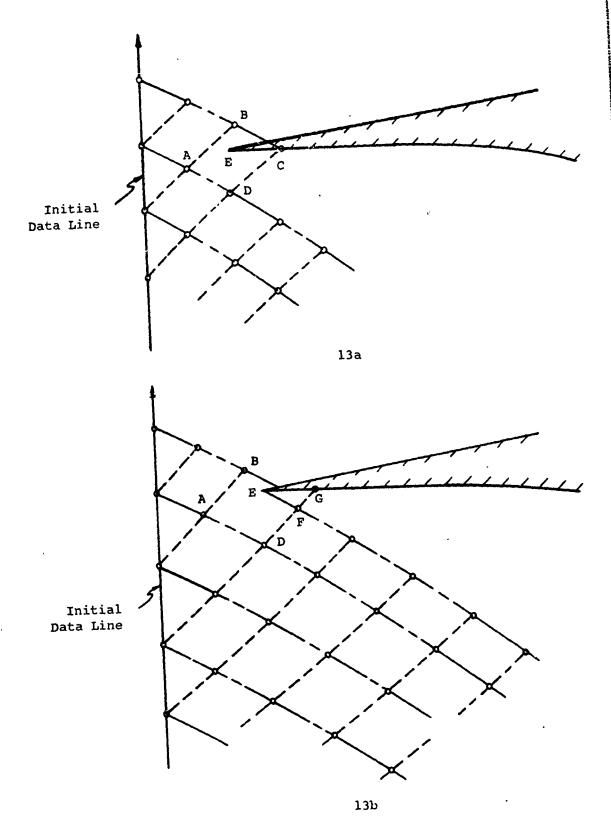


FIGURE 13 - MODIFICATION OF CHARACTERISTIC MESH AT THE COWL 25

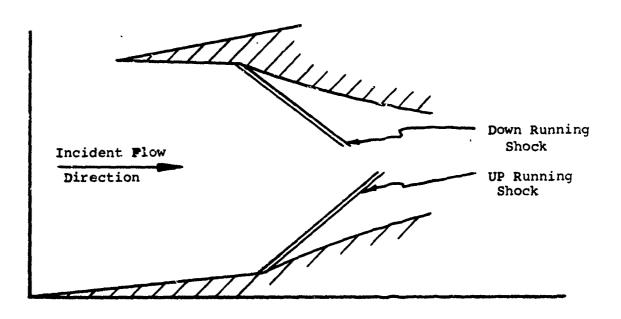


FIGURE 14 - SKETCH OF DOWN RUNNING AND UP RUNNING SHOCKS

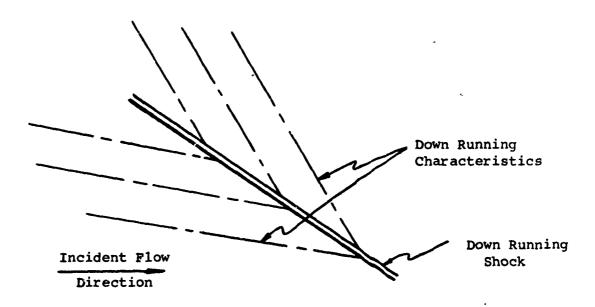


FIGURE 15 - PATTERN OF DOWN RUNNING CHARACTERISTICS NEAR DOWN RUNNING SHOCK

If there are such shocks, the intersection of each shock with each down running characteristic defines a mesh point (actually two, one in front of and one behind the shock, see Part D-e-1). The only complication in the program is that, as it proceeds along a down running characteristic, the program must be instructed to look for the intersection of the down running characteristic with any up running shocks from the previous down running characteristics. When such an intersection occurs, a special computation must be made.

However, the situation is not quite so simple when there are down running shocks. For, the down running characteristics down stream of the shock terminate at the shock (see Figure 15), i.e. characteristics terminate at a shock of the same family. Thus, as the program proceeds along a down running characteristic, it must make a special provision upon encountering a down running shock since the down running characteristic does not continue on the other side (up stream) of the shock.

The proceedure that is followed in such cases is illustrated in Figure 16 for the case of a compression corner on the upper wall. When such a corner is detected, the conditions upstream of the shock are obtained by a regular characteristic wall computation between the corner and A, the data at A being computed by interpolation on the previous down running characteristic. The program then computes the down running characteristic, BC, that would issue from B if no compressive corner were present. All the data computed on characteristics upstream of and including BC is referred to as region I and is stored for later use by the program.

With the specified turning angle and the conditions in front of the shock at B, the shock angle and the conditions behind the shock can be determined (see Part C-c). shock will always have a slope less than the local slope of the down running characteristics in region I, hence, the shock will always be in region I. The intersection, E, of the shock and the next up running characteristic of region I is determined and the conditions upstream of the shock are determined by interpolation between points, O and P. In region I+1, the region behind the shock, FE is the down running characteristic from the upper wall to the point E. It is assumed that the conditions at F are equal to the conditions behind the shock at B. Then, the flow behind the shock and the shock slope at E can be determined by simultaneously solving the compatibility equation (Eq. 13) along FE and the Rankine-Hugoniot equations across the shock.

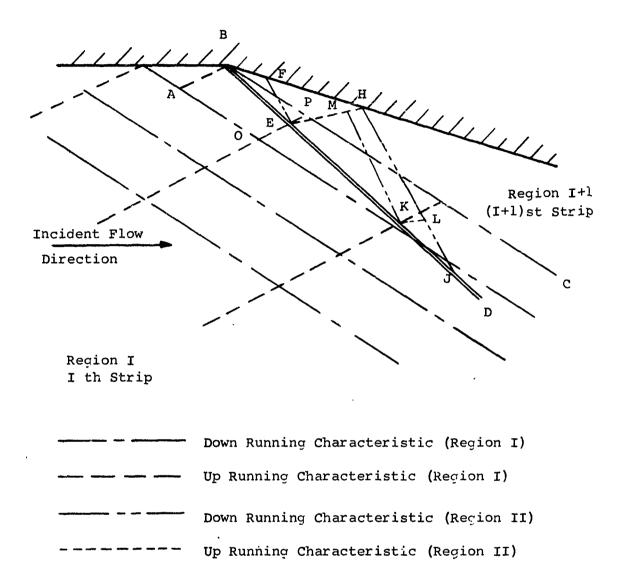


FIGURE 16 - CHARACTERISTIC MESH AT COMPRESSION CORNER
ON THE UPPER WALL

With the known conditions behind the shock at E, the intersection, H, of the up running characteristic from E with the upper wall can be determined. The flow field at H can be determined by solving the compatibility equation (13b) along EH using the known wall slope at H.

Now we work along the down running characteristic, HJ, in region I+1. If the shock, BD, crosses the next up running characteristic of region I at a point K before it intersects HJ, then the conditions in front of the shock at K are determined by interpolation in the characteristic mesh of region I. By interpolation, the point M, on EH, whose down running characteristic passes through K, and the data at M are determined. The flow behind the shock at K is determined by simultaneously solving the compatibility equation along MK with the Rankine Hugoniot jump conditions across the shock at K.

Then the location and conditions at L are determined by a regular characteristic computation between H and K. This process continues until the down running characteristic, HJ, intersects the shock, BD, at a point J. The conditions in front of the shock at J are determined by interpolation as above; the conditions behind by using the compatibility equation along LJ and the jump conditions at J.

The result is that the flow field is divided into a number of regions, or strips, the boundaries of which are down running shocks.

3. In the Prescace of Detached Shocks

It may happen that shocks are formed by the coalesence of compression waves due to a smooth turning of either of the walls (see Part D-f-2). The formation of up running shocks by such a process in no way affects the progression of the computation on the gross scale now under discussion.

However, if a down running shock is formed by the coalescence of compression waves, we again divide the flow field into two strips as illustrated in Figure 17.

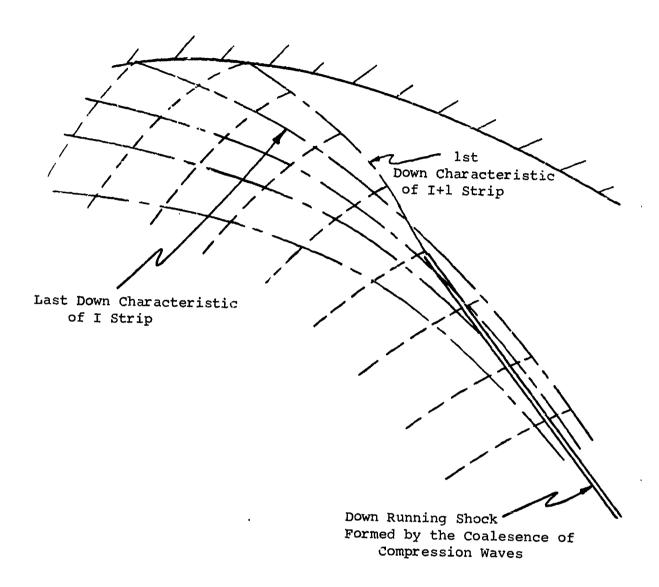


FIGURE 17 - DOWN SHOCK FORMED BY THE COALESENCE OF COMPRESSION WAVES

- 4. The Presence of Centered Expansions on the upper or lower walls causes no essential change in the progression of the computation (see Part D-d).
 - c) Computation of Regular Points

Now that we have indicated the gross order of progression of the computer program, we can look into the various specific computations in a little more detail.

1. Interior Flow Field Points

As mentioned in Part I of this section, regular interior points are determined by the intersection of a down running characteristic with the up running characteristic issuing from a mesh point on the previous down running characteristic. This is illustrated in Figure 18 where C is the point to be computed. All of the points, including B, on the (I-1) st down running characteristic have been computed, as have all the points through A on the i th characteristic. Point C is the next point to be computed.

First Equations 13a and 13b are written in finite difference form:

$$(\tau_C - \tau_A) - \bar{b}_{AC} (p_C - p_A) = \bar{G}_{AC}^{I} (x_C - x_A) j$$
 (17a)

$$(\tau_C - \tau_B) + \bar{b}_{BC} (p_C - p_B) = \bar{G}_{BC}^{IT} (x_C - x_B) j$$
 (17b)

where the barred quantities are averaged quantities on the appropriate characteristic. Equations 17a and 17b are solved simultaneously to give

$$p_{C} = \frac{\vec{b}_{AC} p_{A} + b_{BC} p_{B} - \tau_{A} + \tau_{B} - \left[\vec{G}_{AC}^{I} (x_{C} - x_{A}) - \vec{G}_{BC}^{II} (x_{C} - x_{B}) \right] j}{\vec{b}_{AC} + \vec{b}_{BC}}$$
(18a)

$$\tau_{C} = \tau_{A} + \bar{b}_{AC} (p_{C} - p_{A}) + \bar{G}_{AC}^{I} (x_{C} - x_{A})_{j}$$
 (18b)

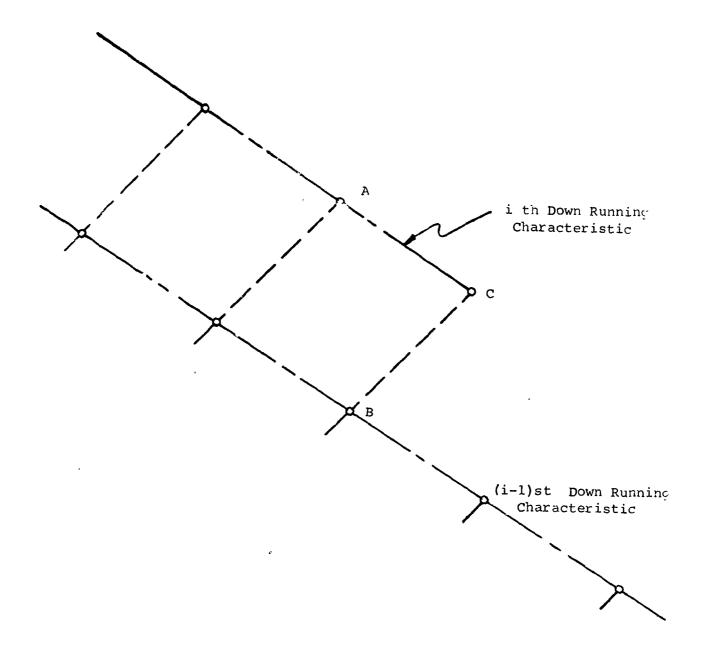


FIGURE 18 - REGULAR INTERIOR POINT COMPUTATION

In addition, we have the following definitions and equations available:

$$S_C = \ln p_C - \gamma \ln \rho_C$$
, or $\rho_C = e^{\frac{\ln (p_C) - S_C}{\gamma}}$ (19a)

$$H_{C} = \frac{\gamma}{\gamma - 1} p_{C}/\rho_{C} + \frac{q_{C}^{2}}{2}$$
; or $q_{C} = \sqrt{2(H_{C} - \frac{\gamma}{\gamma - 1} \frac{p_{C}}{\rho_{C}})}$ (19b)

$$q_C^2 = u_C^2 + v_C^2$$
; or $u_C^2 = \frac{q_C^2}{1+\tau_C^2}$ (19c)

$$\tau_{C} = \frac{v_{C}}{u_{C}}; \text{ or } v_{C} = u_{C}^{\mathsf{T}}_{C}$$
 (19d)

Now, it is fairly common to perform a regular computation in somewhat the following form.

- 1) Get the location of C by the intersection of characteristics from A and B.
- 2) Compute p_C and T_C using (18a) and (18b) where, in the first pass, the averaged quantities are taken as those at A or B, whichever is appropriate.
- 3) Project the streamline of slope τ_C back from C to intersect the line \overline{AB} c necting A and B (not shown in Figure 18).
- 4) Since S and H are constant along streamlines (in the absence of shocks) obtain H_C and S_C by linear interpolation along \overline{AB} .
- 5) Use equations 19 to determine u_C , v_C , ρ_C from the known p_C , τ_C , S_C , H_C .
- 6) Compute the coefficients b_C , G_C^I , G_C^{II} , etc., average the coefficients along each characteristic, and iterate until the characteristic slopes at C dc not change within some specified tolerance.

However, if one proceeds in this manner, and if the flow is nonisentropic, he will find that the linear interpolation in step 4 introduces errors that can become quite large (Reference 4). These errors are quite evident when, after computing a number of characteristics, one checks the mass flow, where the error can exceed 40%.

A much better way of proceeding is to set up a mass flow-entropy, enthalpy table. The fact that S and H are constant along streamlines (and that we can compute the change in S through a shock) means that we can set up functions defined pointwise for S and H with mass flow as independent variable. Then we replace steps 4-5 by another process.

- 4-5 a) guess S_C and H_C , compute ρ_C , u_C , v_C .
 - b) compute the mass flow through AC, subtract it from the known mass flow below A to get the mass flow at C.
 - c) go to the mass flow S, H table and obtain S_C , H_C
 - d) compare with the guessed values of S and $H_{\rm C}$ and iterate until convergence.

Then continue with 6) in the indicated manner.

The result is a very accurate computation with the error in the integrated mass flow often less than 1% in the computation of two-dimensional flows. Of course, the mass flow-entropy table must be modified when there are shocks.

The dependence of S and H on mass flow are determined initially from the known conditions on the initial data line.

This technique is used in the present program.

The increment of mass flow across AC is given by

$$\frac{1}{\rho q} \sin \left[\tan^{-1} \frac{1}{\tau} - \tan^{-1} \frac{1}{\lambda}\right] \Delta \text{ area}$$
 (20)

where the barred quantities are averaged between A and C and \triangle area is the area between A and C, given by,

$$\Delta \text{area} = \sqrt{(x_C - x_A)^2 + (y_C - y_A)^2}$$
 for 2-dim. flow (j=0) (21a)

$$\Delta \text{area} = \sqrt{1 + \tilde{\lambda}^{2}} (y_A^2 - y_C^2) \text{ for axi-sym. flow (j=1)}$$
 (21b)

2. Boundary Points

Boundary points are computed in the same manner as interior points, except for a few simplifications. First, since in an entirely inviscid flow the boundaries are streamlines, we know a priori what S and H are along the boundary (the case of shocks is explained in Part D-g), and we need not do the mass flow - S, H iteration required at interior points. In addition, $T_C = v_C/u = dy/dx$ on the boundaries is a specified function of x. To compute a point on the lower wall we use Equation 17a along the down running characteristic to get p_C . To compute a point on the upper wall we use 17b along an up running characteristic. Naturally, erations are made in averaging coefficients when the equations are solve.

3. Centerli : Points

When the flow is axisymmetric, it may happen that the lower wall ends at the axis of symmetry and then the lower wall computation must be replaced by a symmetry condition. The only effect this has, in the absence of shocks, is that G^{I} and G^{II} , which take the indeterminate form 0/0 at y=0, must be evaluated by L'Hospital's rule.

$$G^{I,II}\Big|_{Y=0} = (\tau - \lambda^{I,II}) \frac{\tau}{Y} \Big|_{Y=0} = -\lambda^{I,II} \frac{d\tau}{dy} \Big|_{Y=0}$$
 (22)

The program requires a cusp at the trailing edge

of the lower wall.

There is no provision to compute the reflection of shocks at the axis of symmetry.

d. Centered Expansion on the Boundaries

Everytime we compute the location of an upper or lower boundary point, a test is made to determine whether or not there is a corner between the current point and the last point on that boundary. If a corner has been detected, the next operation is to find out whether or not it is an expansion or a compression corner. The latter is treated in Part D-f.

If it is an expansion corner, the conditions just upstream of the corner are first determined (see Figure 19). Then the total turning angle , $\Delta\theta$, of the flow is determined. This turning angle is divided into a number of increments, n, of size $\delta(\Delta\theta) = \Delta\theta/n$, and the conditions corresponding to the flow which has turned from the state just prior to the corner, say θ , to $\theta=\theta+m$ δ ($\Delta\theta$), m=1,n, are determined. This is done by determining the change in Mach number to go from θ to $\theta+m$ δ ($\Delta\theta$) from Equation 15). Then the rest of the conditions can be determined by using Equation 16.

If the expansion is on the upper boundary, a new down running characteristic is put in the mesh for each value of m, and the regular upper boundary point computation is bypassed until all of the down running characteristics issuing from the corner have been computed (see Figure 19a).

If the expansion is on the lower wall, a number, n+1, of mesh points is put at the corner and the current down running characteristic is finished by making a series of regular interior point computations as indicated in Figure 19b.

e. Computation of Interior Shock Points

1. Up Running Shock Points

In Figure 20, AB is a down running characteristic along which we know everything, including the location and slope of any up running shocks crossing AB. Such a characteristic shock intersection is designated by two points (H,I of Figure 20) which have the same physical coordinates, one having the properties of the flow just in front of the shock and the other properties just behind the shock. We want to compute CD, the next down running characteristic.

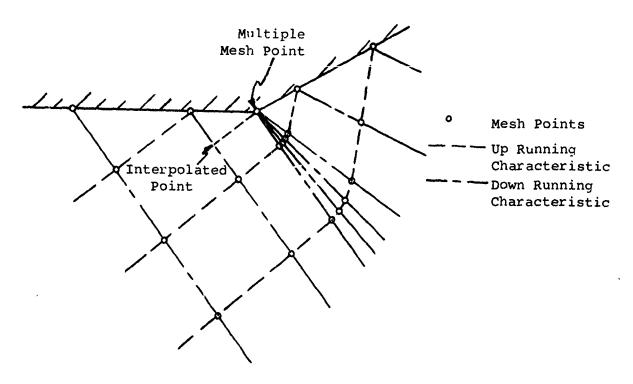


FIGURE 19a - EXPANSION ON UPPER BOUNDARY

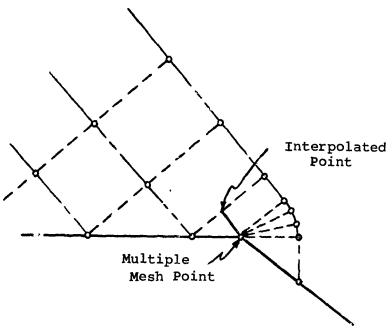


FIGURE 19b - EXPANSION ON LOWER BOUNDARY

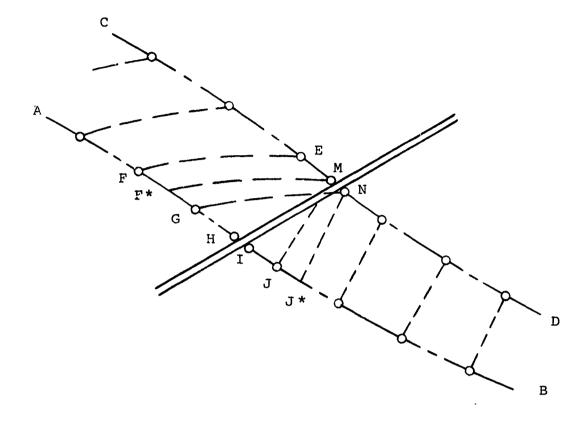


FIGURE 20 - PROGRESS OF THE COMPUTATION IN THE PRESENCE OF AN UP RUNNING SHOCK

Supposing the shock to be the first up running shock to cross CD, all points through E on CD can be computed as ordinary points. As each such point is computed, we test to see if the down characteristic and the shock intersect before we can compute any other regular points. When such an intersection occurs, we locate it (M in Figure 20) by intersecting the down characteristic EM from E, the last good regular point, with the up characteristic, FFM, from F*, an interpolated point on AB. The conditions at M are determined by a regular characteristic computation between F* and E.

Now we must determine the new shock slope at M and the conditions behind the shock at N. To do this, a point J^* on \overline{AB} is found by interpolation such that the up running characteristic, $\overline{J^*N}$, from J^* , intersects the shock at N. Then the compatibility equation (13b) along $\overline{J^*N}$ is solved simultaneously with the Rankine Hugniot conditions across the shock to determine everything including the shock slepe, at N. In outline, the process of solution is:

- guess σ, the shock slope at M;
- 2) compute, p, ρ , τ , M^2 at N from Rankine Hugniot equations (14) and the known conditions at M,
- 3) compute p', at N from the known conditions at J* using the compatibility equation (17b) along J*N and the T from 2, above,
- 4) compare p' and p; if they do not agree, guess another value of σ and repeat the process until convergence.

When the iteration has converged, an additional test is made on p_N/p_M . If an expansion has caused the shock to become so weak that, within the numerical accuracy of the computation, the shock no longer has finite strength, it is desirable to eliminate it from the flow field. Thus if $p_N/p_M \le 1$, we drop the shock.

2. Down Running Shock Points

The intersection of a down running characterist c and a down running chock were outlined in Part D-b-2, although the manner in which the iteration is carried out was not given. The iteration is performed exactly as in the case of a down characteristic up shock intersection detailed in Part D-e-1, except that the

compatibility equation is 17a written along a down running characteristic (see Figure 16 and Part D'-b-2). There is presently no provision to drop a down shock which has become very weak. This should not cause any trouble in the use of the program.

f. How Are Shocks Started?

Shocks may arise in two fashions, differing only in their smoothness. There may be sharp compressive corners in the flow field which will give rise to attached oblique shocks (Figure 7) (the case of strong shocks is not considered here). Or, a continuous smooth compression may coalesce into a shock as illustrated in Figure 9.

- 1. Formation of Attached Oblique Shocks by Sharp Corners
- Lower Boundary When a corner is encountered on the lower boundary, the conditions just in front of the shock are found by an ordinary lower boundary computation (Part D-c-2) along MA of Figure 21 where M is an interpolated point. The turning angle of the flow is specified and the conditions behind the shock at B and the shock slope at (A,B) are completely determined from Equations 14 where $\delta = \tan^{-1} \tau_{R} - \tan^{-1} \tau_{\Lambda}$. The intersection of the shock with the down running characteristic (E of Figure 21) is found and the conditions in front of the shock are determined by a regular characteristic computation between G and H where G is an interpolated point on the previous down characteristic and H is the last computed point in front of the shock on the current characteristic. C is the point on the wall behind the shock whose up running characteristic intersects the shock at (E,F). conditions at C are assumed to equal those at B. A regular shock computation between E, F, and C is then performed (see Part D-e) determining the conditions at F and the slope of the shock at (E,F). Then D is computed as a regular boundary point.
- b) Upper Boundary The computation of the formation of shocks on the upper boundary has been outlined in Part D-b-2 except that no indication was given of the equations used to determine the conditions behind the shock. However, the equations are those indicated in the preceding paragraph and there is no need to duplicate here a description of the computational procedure outlined in Parts D-b-2 and D-f-1.
 - 2. Shocks Formed by Coalescence of Smooth Compressions

The formation of oblique shocks by the coalescence of a smooth compression is manifested numerically by the crossing of characteristics of the same family as illustrated in Figure 9 for a

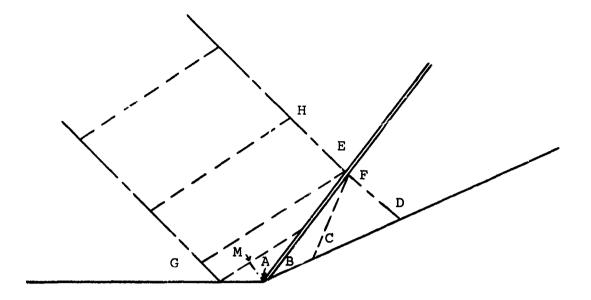


FIGURE 21 - FORMATION OF ATTACHED OBLIQUE SHOCK ON LOWER WALL

compression from the lower wall. In the program such shocks are detected by testing each regularly computed mesh point to see if there has been a crossing of either characteristic family. In such an instance a shock of that family is initiated.

- g. Reflection of Oblique Shocks at the Walls
 - 1. Up Running Shock Reflected at the Upper Wall

The reflection of an up running shock at the upper wall is illustrated in Figure 22. It is easy to detect such a reflection since the counter indicating the mesh point of the shock on the down running characteristic approaches one (1) as the shock approaches the boundary. When such a reflection occurs, we proceed in a manner similar to that used when we have a sharp compressive corner on the upper wall. Referring to Figure 22, \overline{AB} is assumed to have been completely computed. The location, (C,D,F) of the intersection is determined and the conditions at C in front of the incident shock are determined by a regular upper wall computation (H is an interplated point on \overline{AB}). Then the slope of the incident shock at the point of intersection and the conditions at D (behind the incident shock but in front of the reflected shock) are determined by a regular up shock-down characteristic computation (Part D-e-1). The characteristic \overline{DE} is then completed in the usual manner.

Now since the up shock reflects as a down shock, the latter will separate the flow field into two strips, say the I'th so p in front of the reflected shock and the (I+1) st strip behind it. The incident shock turns the flow toward the wall, and we can think of there being an effective compressive corner at the point of reflection which turns the flow from its direction at D, between the two shocks, to the direction parallel to the wall at F, behind the reflected shock. Thus, after DE is computed the reflection is treated exactly as a sharp compressive corner (see Part D-f- -b).

2. Down Running Shock Reflected at the Lower Wall

The configuration arising when a down running shock reflects at the lower wall is illustrated in Figure 23. While working along the down running characteristic, DEF, j. the I'th strip, tests are made to see if the characteristic intersects the lower wall before it intersects the down shock, GA, separating the I'th and (I-1)st strips. When this happens, the point of intersection (A,B,C) of the shock with the wall is determined. The conditions at A are determined by interpolating on the (I-1)st strip. The conditions at B are determined by making a regular down shock computation as previously

Last Down Characteristic in the I th Strip Reflected Shock I th Strip Incident Shock

FIGURE 22 - REFLECTION OF AN UP RUNNING SHOCK AT THE UPPER WALL

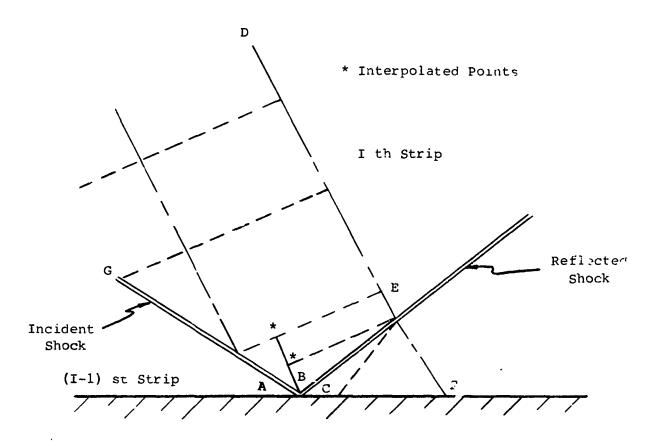


FIGURE 23 - REFLECTION OF A DOWN RUNNING SHOCK AT THE LOWER WALL

outlined. The incident shock turns the flow toward the wall at B, between the two shocks. The slope of the reflected shock and the flow at C is then determined by requiring the known flow at D to turn back parallel to the wall at C. By extrapolating the reflected shock we find E, the last good computed point on DEF. By a procedure identical with the case of a sharp compressive corner on the lower wall (Part D-f-1) the rest of DEF is recomputed as indicated in the figure.

h. Intersection of Shocks of the Same Family

In general, such an intersection will be continued as a shock, a contact discontinuity, and a reflected expansion or shock as is illustrated in Figure 4. We neglect the contact discontinuity and reflected expansion or shock because they should be weak compared to the shock $\overline{\text{OC}}$.

i. Intersection of Shocks of Opposite Family

This situation is illustrated in Figure 24. Such an intersection will result in the diffraction of the two incident shocks and the creation of a contact discontinuity along which the pressure and velocity direction are continuous. While working along the down characteristic \overline{AB} in the Ith strip, tests are made to determine whether or not the down shock \overline{COB} separating the two strips intersects an up shock of the (I-1)st strip. When this happens, the point of intersection, O, is determined. The conditions at O (in front of both intersecting shocks) are obtained by interpolation on the (I-1)st strip. The slopes at O of the two incident shocks and the conditions at E and F are then determined, the slopes being assumed equal to the slope at the nearest previous shock point and the conditions at E and F being then computed directly using the Rankine Hugoniot relations.

The slope of the diffracted up shock, \overline{OK} , is then guessed and the conditions at G are determined, including τ_G . Then the slope of the diffracted down shock, \overline{OB} , is determined which gives $\tau_{H^-}\tau_{G^-}$. Then p_G and p_H are compared and, if they disagree, the slope of \overline{OK} is changed an an iteration is performed. Then the intersection, K, of the down characteristic, \overline{AB} , with the diffracted up shock, \overline{OK} , is determined as are the other intersections indicated in the figure.

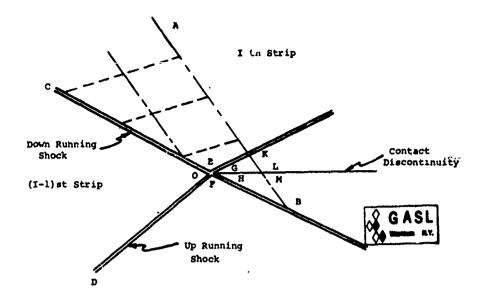


FIGURE 24 - INTERSECTION OF SHOCKS OF OPPOSITE FAMILY

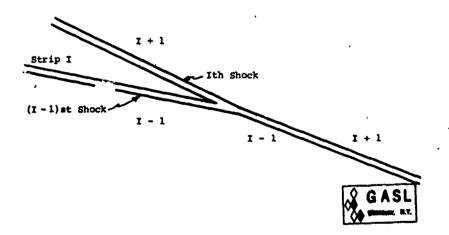


FIGURE 25 - COALESENCE OF DOWN RUNNING SHOCKS

The next down running characteristic in the Ith strip is then made in the normal fashion.

j. Intersection of Shocks with Contact Discontinuities

The situation which arises in this case is depicted in Figure 6 where it is seen that the intersecting shock and contact discontinuity are diffracted at the point of intersection with a weak centered expansion often arising at the point of intersection, O.

Currently, contact discontinuities are dropped from the computation upon intersecting a shock.

Up Running Characteristic

Down Running Characteristic

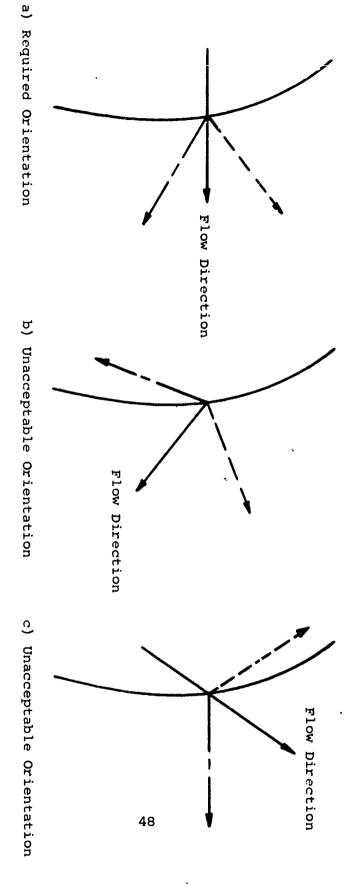


FIGURE 26 - RECUIRED ORIENTATION OF CHARACTERISTICS WITH RESPECT TO THE INITIAL DATA LINE

THREE-DIMENSIONAL SUPERSONIC FLOW COMPUTER PROGRAM ELEMFNTS

A. Summary and Introduction

Computer programs have been written for machine computation of the basic flow elements which compose a large variety of three-dimensional supersonic inlet flow fields. A combination of these unit problems can be used to design and analyze three-dimensional inlets as described in Section III. The programs are written in Fortran IV for use on the IBM 7094 high speed digital computer.

The overall program can be summarized as follows:

- General Computer calculation of the basic elements of three-dimensional supersonic inlet flow fields
 - · Plane shock conical body
 - Conical shock plane body
 - · Conical shock-conical shock
 - · Delta wing
- Input
- · Uniform free stream conditions
- Supersonic leading edges
- Any combination of Mach number, body surface angle and leading edge sweep angle
- · Perfect gas
- Output
- Aerodynamic flow properties along the axis of symmetry of the locus of the threedimensional wave intersections
- Aerodynamic properties, incident and reflected wave angles and locations, immediately behind the three-dimensional wave intersections
- Complete flow field behind intersections calculated for plane shock - conical body and conical shock - plane body

Complete descriptions of these program elements are given in this section. The problems are divided into two parts. Firstly, the swept wedge (Part B) which is considered to be infinite, i.e., no end expansions. This problem requires the analytic description of a shock envelope and flow field composed of a central conical region between two two-dimensional regions which extend from the central region boundaries to the leading edges. Secondly, for the remaining problems (Parts C, D and E) the initial shock envelopes and flow fields are either purely conical or two-dimensional and therefore are known a priori.

For each of the above problems, once the initial shock envelope and the associated flow field is determined, the various three-dimensional reflection and intersection curves are computed by using linearized and two-dimensional supersonic flow theory and working in planes normal to the tangent of the intersection curve. The flow relds behind the intersection curves are then constructed from two-dimensional characteristics with entropy variations.

It is suggested that the reader study the analysis given in Parts B through E before using these programs, in order to fully understand the approximations involved. The operating instructions, including the input formats, definition of symbols, and example problems, are given in the Appendices to this section.

B-1 Swept Wedge Flow (Delta Wing)

According to linear theory 11 the effect of the vertex of a supersonic swept wedge is limited to a region inside the free-stream Mach cone from the vertex. In the analysis presented herein the two dimensional leading edge shock and flow field (the region outside this central Mach cone) are obtained from exact oblique shock theory applied in a plane normal to the wedge leading edge. Since an exact solution for the region influenced by the vertex Mach cone is nonexistent, linear theory is used on the base plane of the wedge to obtain the flow properties inside the Mach cone corresponding to the two dimensional Mach number. This cone is assumed to divide the two- and threedimensional regions. Similar to the solution of Babaev 12 and Fowelll3 for a swept flat plate at an angle of attack, a second order curve is used as an approximation for the shock envelope in the 3-D central region. The flow conditions behind the reflection of the wedge shock from a plane surface are then determined from oblique shock theory in planes normal to the tangent of the intersection curve.

The supersonic flow over a swept wedge as shown schematically in Figure 28 is considered here. The sweep angle is designated by and the wedge angle in the plane of symmetry is denoted . The leading edges are assumed to be supersonic and the wedge is taken to be of infinite span.

As is well known 1, the influence of the wedge apex (0') is only felt inside of a Mach cone whose vertex is at 0'. Outside of this cone the flow field behind the leading edge shock is two-dimensional. This region may be analyzed in the usual way by breaking the free stream Mach number into two components, tangent and normal to the leading edge. Oblique shock theory can then be used in the plane normal to the leading edge to determine the flow behind the two-dimensional portion of the shock. The wedge angle in this normal plane is determined geometrically to be

$$\lambda_{n} = \tan^{-1} \left(\frac{\tan \lambda}{\cos x} \right) \tag{23}$$

ShockEnvelope

FIGURE 27 - SCHEMATIC OF SWEPT WEDGE FLOW

and the flow deviation on the wedge surface with respect to line O'C (Fig.28), is

$$\sigma_1 = \cos^{-1}(\cos \lambda \sin \chi) - \tan^{-1}\left(\frac{M_{n_1}}{M_{t_1}}\right)$$
 (30)

The general shape of the swept wedge shock consists of the two plane shocks attached to the leading edges, as described above, connected through the central region by a curved section which is determined by the threedimensional recure of the flow. In order to analyze this central region it is necessary to make some approximations concerning the shock shape and the distribution of the flow properties. The local Mach cone defined by μ_1 , with the vertex at 0' and an axis along O'C is assumed to separate the two-dimensional flow field from the central portion, which is conical under the assumption of linear theory 14. Due to the conical nature of the central flow, the element of the wedge shock in the vertical plane of symmetry (x = 0) is a straight line and, therefore, a linear function of z. In a plane normal to the z' axis the shock is assumed to be a parabola, which is tangent to the two-dimensional shocks at their points of intersection with the local Mach cone (Fig. 29). A parabola is chosen since this family of curves have asymptotes, which is desired since the curve must match with the straight two dimensional shock. The angles that the twodimensional shocks make with the base plane of the wedge in the y-z and x-y planes are respectively:

$$\beta^{\chi} = \tan^{-1} \left(\tan \theta_{10} \cos \chi \right)$$
 (31)

$$\theta_s = \tan^{-1} (\tan \theta_{1n} \sin \chi)$$
 (32)

Using these relations the two-dimensional shock angle in the plane normal to the z' axis can be found as

$$\theta_{c}' = \tan^{-1} \left\{ \left[\cos \lambda \tan (\beta * - \lambda) + \sin \lambda \right] \tan \chi \right\}$$
 (33)

The points of intersection of the two-dimensional shocks with the local Mach cone in the plane $z' = \cos \lambda$ are given by $x! = \pm \cos \theta \cos \lambda$ $\left\{ \tan (\beta * - \lambda) \sin \theta \right\} + \left[\tan^2 \mu_1 - \tan^2 (\beta^* - \lambda) \cos^2 \theta \right]^2$

$$y'_{j} = \begin{vmatrix} x'_{j} \\ tan \theta'_{c} - cos \lambda tan (\beta^{*} - \lambda) \end{vmatrix}$$

$$z'_{j} = cos \lambda$$
(34)

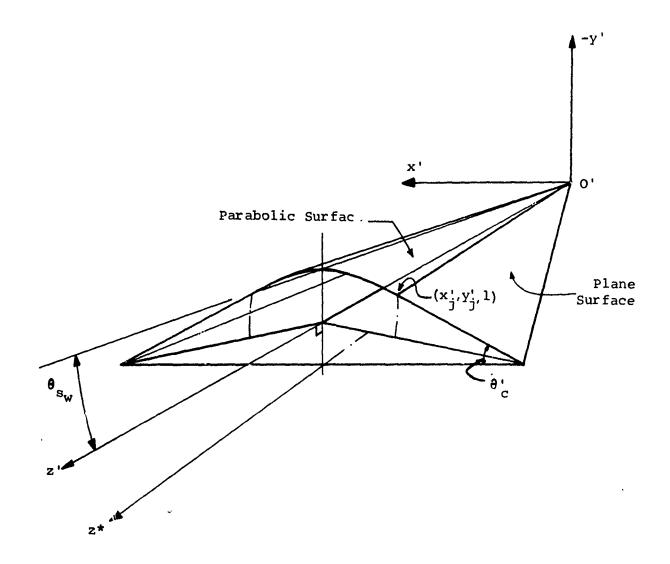


FIGURE 29 - SHOCK CONFIGURATION

Since the central portion of the wedge shock is represented by a parabola tangent to the two-dimensional shocks in a plane z' = const. and is linear in z', the three-dimensional shock envelope is represented by a parabolic sheet whose equation is

$$x^{\frac{1}{2}} = Az' (y' + hz')$$
 (35)

The constants A and h are determined by requiring, as stated previously, that the shocks pass through the point $(x_1^i, \dot{y}_1^i, \dot{z}_1^i)$ and have slope tan θ_C in the plane z' = const. at that point. The resulting values of these constants are

$$A = \frac{2 \left| \frac{x_{j}^{1}}{\tan \theta_{C}^{1}} \right|}{\tan \theta_{C}^{1}} \frac{1}{\cos \lambda}$$

$$h = \left(\frac{x_{j}^{1}}{A \cos \lambda} - \dot{y}_{j}^{1} \right) \frac{1}{\cos \lambda}$$
(36)

The constant h, as can be seen from (36), is the tangent of the angle $\theta_{\rm SW}$ that the three-dimensional shock makes with the z' axis in the plane of symmetry (y-z).

Linear theory has been used in the conical region to obtain the variation of the flow properties from their uniform values in the two-dimensional region to the plane of symmetry. For this present work the variations of the properties in the y direction has been neglected. Therefore the variations used are truly valid only on the baseplane (x-z*) of the wedge. However, for small wedge angles (<10 degrees approximately) which are generally used in supersonic and hypersonic inlet designs the approximation is good for the whole region. Since the local Mach cone has been used previously to construct the shock and linear theory uses the free stream Mach cone, the conical rays of linear theory must be adjusted to fit into the local Mach cone. Thus, given the ratio $(x/z)_i$, which represents the slope of a conical ray i, the adjusted parameter used in linear theory is

$$\zeta_{i} = \left(\frac{x}{z}\right)_{i} \left(\frac{\cos^{2} \lambda - |y_{j}^{i}| \sin \lambda}{|x_{j}^{i}|}\right) n \tag{37}$$

where n = tan $\chi \sqrt{M_{\infty}^2 - 1}$. The resulting variations of pressure and Mach number in the conical region are

$$\frac{P_{1_{i}}}{P_{\infty}} = \frac{P_{1}}{P_{\infty}} \frac{1 + \frac{1}{2} \gamma M_{\infty}^{2} C_{pi}}{1 + \frac{1}{2} \gamma M_{\infty}^{2} C_{po}}$$
(38)

and

$$M_{1_{i}} = M_{1} \left\{ \frac{\left(1 - \frac{C_{pi}}{2}\right)^{2} + u_{i}^{2}}{\left(1 - \frac{C_{po}}{2}\right)^{2} + \left(\frac{n}{\sqrt{1 - n^{2}}} \tan \lambda\right)^{2}} \right\}$$
(39)

where the pressure coefficients from linear theory 11 for the two-dimensional and conical regions are respectively,

$$c_{po} = \frac{2 \tan \lambda}{\sqrt{(M_m^2 - 1) (1 - n^2)}}$$
 (40)

and

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$$c_{pi} = c_{po} \left[1 - \frac{2}{\pi} \sin^{-1} \left(\frac{n^2 - \zeta_i^2}{1 - \zeta_i^2} \right)^{1/2} \right]$$
 (41)

and the lateral velocity u, (x-direction) is

$$u_{i} = \frac{n \tan \lambda}{\pi \sqrt{1-n^{2}}} \left\{ \cos^{-1} \left[\frac{n^{2} - \zeta_{i}}{n (1-\zeta_{i})} \right] - \cos^{-1} \left[\frac{n^{2} + \zeta_{i}}{n (1+\zeta_{i})} \right] \right\}$$
(42)

The flow deviation with respect to the z' axis in the conical region is

$$\sigma_{1i} = \sigma_{1} \left[\frac{\frac{1 - \frac{C_{po}}{2}}{1 - \frac{1}{2} + \tan \lambda}}{\frac{1 - \frac{C_{pi}}{2}}{1 - \frac{C_{pi}}{2}}} \right]$$
(43)

where σ_1 (Eq. 30), represents the flow deviation in the two-dimensional region.

B-2 Swept Wedge Shock Reflection

A swept wedge shock reflecting from a plane surface is considered next. The three-dimensional wedge shock intersects a plane body along a curve which ends in two straight lines (Fig.30), corresponding to the intersection of the two-dimensional portions of the shock with the plane. For the case under consideration, where the plane body is parallel to the base plane of the wedge, the two straight line sections are parallel to the leading edges of the wedge. The central curved portion of the intersection curve is represented by the second order equation

$$x_{i} = \pm \left[A \left(B z_{i}^{2} + 2C z_{i} + D \right) \right]^{1/2}$$
 (44)

where

B =
$$\cos \lambda$$
 ($\sin \lambda + h \cos \lambda$)
C = r ($h \sin \lambda \cos \lambda + \sin^2 \lambda - 1/2$)
D = $r^2 \sin \lambda$ ($h \sin \lambda - \cos \lambda$) (45)

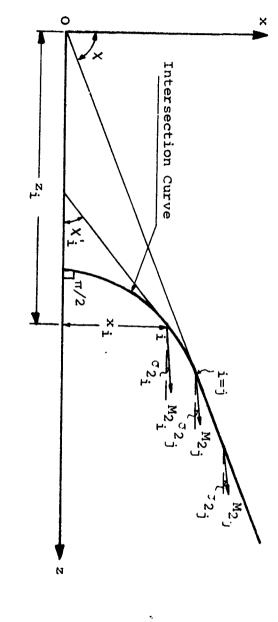
and where r is the distance between the plane and the base of the wedge. Values of z are obtained by incrementing from the value of z obtained from Eq (44) with $x_{i=0}^{=0}$, i.e., $z_{i}^{=z} + i \Delta z$.

For each point on the curve the angle between the tangent to the curve and the z axis is given by

$$\chi_{i}^{i} = \tan^{-1} \left[\frac{A(Bz_{i} + C)}{|x_{i}|} \right]$$
 (46)

When the value of χ_i^i reaches $(\pi/2) - \chi$, the intersection curve becomes a straight line and the incrementation of z_i can be stopped.

The intersection curve represents the line along which the shock reflects from the plane body. The flow field between the incident and reflected shocks has been assumed to be the same as the flow on the wedge surface, i.e., no variation in the y-direction (Fig.30). In order to obtain the flow conditions behind the reflected shock, it is necessary to use the oblique shock relations in planes normal to the tangents of the intersection



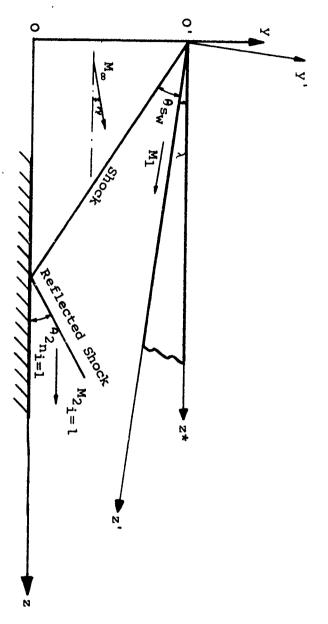


FIGURE 30 - WEDGE SHOCK REFLECTION

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curve for each point i. To simplify the procedure the components of the Mach number between the incident and reflected shocks in the x-y-z directions are found first.

$$M_{l_{xi}} = M_{li} \left[\cos x \cos (x^* - \sigma_{li}) - \cos \lambda_n \sin x \sin (x^* - \sigma_{li}) \right]$$

$$M_{1_{\text{Zi}}} = -M_{1i} \sin \lambda_{n} \sin(\chi^{*} - \sigma_{1i})$$

$$M_{1_{\text{Zi}}} = M_{1_{i}} \left[\sin \chi \cos(\chi^{*} - \sigma_{1i}) + \cos \lambda_{r} \cos \chi \sin(\chi^{*} - \sigma_{1i}) \right]$$

$$(47)$$

where the angle between the leading edge and the z' axis on the wedge surface is

$$\chi^* = \cos^{-1} (\cos \lambda \sin \chi) \tag{48}$$

Then the Mach number components normal and tangent to the intersection curve on the plane surface are easily found from

$$M_{1_{n_{i}}} = M_{1_{z_{i}}} \sin x_{i}' - M_{1_{x_{i}}} \cos x_{i}'$$

$$M_{1_{t_{i}}} = M_{1_{z_{i}}} \cos x_{i}' + M_{1_{x_{i}'}} \sin x_{i}'$$
(49)

The total Mach number in the plane normal to the intersection curve is

$$M_{N_{i}} = (M_{n_{i}}^{2} + M_{1}^{2})$$
(50)

and the corresponding flow deflection is

$$\delta_{1_{i}} = \tan^{-1} \left| \frac{M_{1_{Y_{i}}}}{M_{1_{n_{i}}}} \right|$$
 (51)

since the flow behind the reflected shock must be parallel to the plane body. The oblique shock relations are also used to find the change in flow properties across the reflected shock:

$$M_{2_{N_{i}}}$$
; $\left\langle \frac{P_{2}}{P_{1}} \right\rangle_{i}$; $\left\langle \frac{a_{2}}{a_{1}} \right\rangle_{i}$; $\theta_{2_{i}}$ and ΔS_{i}

These conditions together with the relation

$$\mathbf{M}_{2_{t_{i}}} = \mathbf{M}_{1_{t_{i}}} \left(\frac{\mathbf{a}_{1}}{\mathbf{a}_{2}} \right)_{i}$$
 (52)

give the flow properties behind the reflected shock

$$M_{2_{i}} = (M_{2_{N_{i}}}^{2} + M_{2_{t_{i}}}^{2})^{1/2}$$
(53)

$$\frac{\mathbf{p}_{2_{\hat{\mathbf{I}}}}}{\dot{\mathbf{p}}_{\infty}} = \left(\frac{\mathbf{p}_{2}}{\mathbf{p}_{1}}\right)_{i}^{\mathbf{p}_{1_{\hat{\mathbf{I}}}}} \frac{\mathbf{p}_{1_{\hat{\mathbf{I}}}}}{\mathbf{p}_{\infty}} \tag{54}$$

$$\theta_{2_{n_{i}}} = \theta_{2_{i}} - \delta_{1_{i}} \tag{55}$$

$$\sigma_{2_{i}} = \chi_{i}' - \tan^{-1} \left(\frac{M_{2_{N_{i}}}}{M_{2_{t_{i}}}} \right)$$
 (56)

$$\Delta S_{2_{i}} = \Delta S_{1} + \Delta S_{i} \qquad (57)$$

4

These relations give the flow conditions immediately behind the curved portion of the intersection curve for each point i. The point i for which the value of X_i reaches $(\pi/2 - \chi)$ gives the conditions behind the two-dimensional shock reflection.

The flow conditions in the whole region of the plane surface behind the shock intersection can be found by using two-dimensional characteristics which take the variations of entropy, due to the curvature of the shock, into account. This method has been applied to the conical flow problems of Sections C and E and has been presented in such a manner (separate subroutine in the computer program), that it can easily be used in this wedge program.

Other methods of solution for supersonic flow over the wedge, which are more complicated than the approximation of linear theory used here, include an exact solution similar to the indirect method for a swept flat plate at an angle of attack of Ref. 12. Also, the present solutions can be improved by using threedimensional linear theory to give an approximation which allows variation of the flow properties in the y-direction. A method for determining the y-variation of the flow, which should yield a better approximation than threedimensional linearized theory, is to use the conical flow variation between the body and shock of an equivalent cone, whose surface pressure is matched to the surface pressure of the wedge at the same free stream Mach number. In any case, the methods of the present work and the analytic techniques presented above can either be used directly in an inlet design and analysis effort or as a starting point for additional investigations.

The program operation and example problems are described completely in Appendices V and VI.

Impingement of a Conical Shock on a Plane Surface

The configuration examined here is the supersonic flow over a cone of half angle yh at zero angle of attack, in the presence of a plane surface inclined by an angle θ_1 with respect to the cone axis (Fig. 31).

The intersection curve of the conical shock, (v_c) produced by the cone, with the plane surface, (x', z' plane), is represented by the second order equation

$$x_{i}^{\prime} = \left\{ -(Az_{i}^{\prime 2} - 2Bz_{i}^{\prime} + C) \right\}^{\frac{1}{2}}$$
 (58)

where

$$A = \sin^{2}\theta_{1} - \tan^{2}\gamma_{c}\cos^{2}\theta_{1}$$

$$B = r \sin\theta_{1} + q \tan^{2}\gamma_{c}\cos\theta_{1}$$

$$C = r^{2} - q^{2}\tan^{2}\gamma_{c}$$
(59)

where θ_1 is the inclination of the plane surface to the free stream direction and where r and q are the coordinates of the origin 0', which is assumed to be in the y', z' plane (Fig. 31). Values of z; are obtained by incrementing from the value of $z_{i=0}^{!}$, obtained from Equation (58) with $x_{i}^{!} = 0$, i.e., $z_{i}^{!} = z_{0}^{!} + i \Delta z'$

For each point of the intersection curve, the angle between the tangent to the curve and the z' axis is given by

$$\Omega_{i} = \tan^{-1} \left| \frac{B-Az_{i}'}{x_{i}'} \right|$$
 (60)

The intersection curve is cut off when Ω_i becomes 5° or less in order to work on only one side of the cone. conical flow field of a cone at zero angle of attack is completely defined by the values of the critical Mach number M_1^* and the flow direction angle ψ_1 for each conical ray angle γ (15). The Mach number components along and normal to a conical ray of angle γ are, from Ref. 15.

$$M_{r} = u/a$$

$$M_{t} = M_{r} tan (\psi_{1} - \gamma)$$
(61)

where

$$u = \sqrt{\frac{\overline{\gamma} - 1}{\overline{\gamma} + 1}} \quad M^{\pm}_{1} \quad \frac{1}{[1 + \tan^{2}(\psi_{1} \ \gamma)]^{\frac{1}{2}}}$$

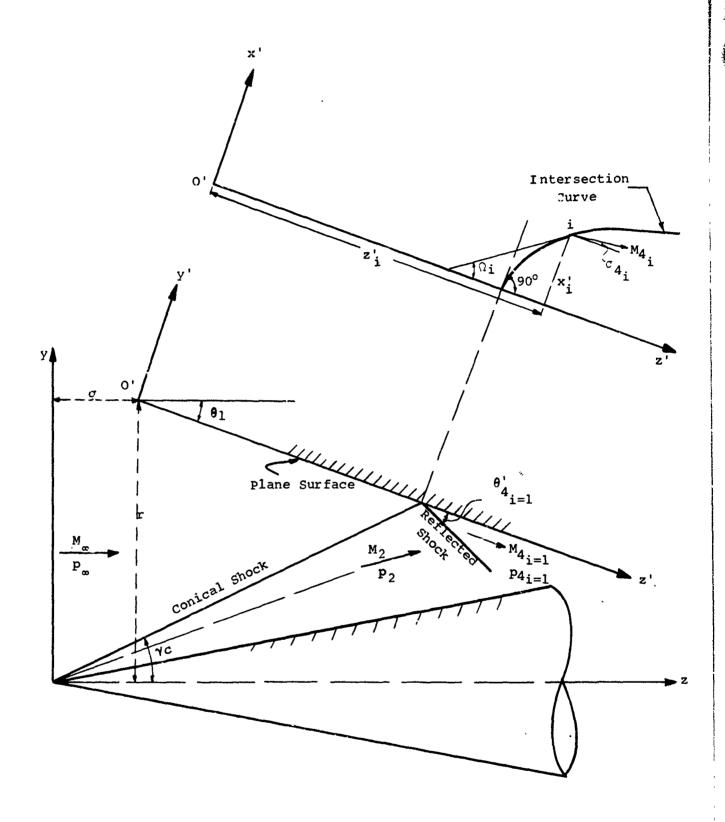


FIGURE 31 - CONICAL SHOCK-PLANE BODY GEOMETRY

and

$$a = \sqrt{\frac{\bar{y}-1}{2}} \left(1 + \frac{\bar{y}-1}{\bar{y}+1} M_1^{*2} \right)^{\frac{1}{2}}$$
 (62)

represent the velocity along the conical ray and the speed of sound non-dimensionalized with respect to the limiting velocity, respectively. The Mach number components immediately behind the conical shock, which is represented by the conical ray $\gamma = \gamma_{\rm C}$, are found from Eqs.(61) and (62) by setting $\gamma = \gamma_{\rm C}$. In order to calculate the flow field beind the reflected shock, the oblique shock relations are used in a plane normal to the tangent of the intersection curve for each point i. The components of the Mach number immediately behind the conical shock in the x', y', z' directions are found first;

$$M_{2}_{x_{i}^{'}} = M_{r} \sin \gamma_{c} \cos \varphi_{i} + M_{t} \cos \gamma_{c} \sin \varphi_{i}$$

$$M_{2}_{y_{i}^{'}} = M_{r} \left(\sin \gamma_{c} \cos \varphi_{i} \cos \theta_{1} + \cos \gamma_{c} \sin \theta_{1} \right)$$

$$+ M_{t} \left(\cos \gamma_{c} \cos \varphi_{i} \cos \theta_{1} - \sin \gamma_{c} \sin \theta_{1} \right)$$

$$M_{2}_{z_{i}^{'}} = M_{r} \left(\cos \gamma_{c} \cos \theta_{1} - \sin \gamma_{c} \cos \varphi_{i} \sin \theta_{1} \right)$$

$$- M_{t} \left(\cos \gamma_{c} \cos \varphi_{i} \sin \theta_{1} + \sin \gamma_{c} \cos \theta_{1} \right)$$

$$(63)$$

where

$$\varphi_i = \tan^{-1} (x_i'/y_i')$$
 with $y_i' = r-z_i' \sin\theta_1$

Then the upstream Mach number components normal and tangent to the intersection curve on the plane surface are found from

$$M_{2_{n_{i}}} = M_{2_{z_{i}^{'}}} \sin \Omega_{i} - M_{2_{x_{i}^{'}}} \cos \Omega_{i}$$

$$M_{2_{t_{i}}} = -M_{2_{z_{i}^{'}}} \cos \Omega_{i} - M_{2_{x_{i}^{'}}} \sin \Omega_{i}$$

$$(64)$$

The total Mach number and the flow deflection in the plane normal to the intersection curve are

$$M_{s_{N_{i}}} = (M_{s_{n_{i}}}^{2} + M_{s_{Y_{i}}}^{2})^{\frac{1}{2}}$$
 (65)

$$\delta_{2_{\dot{1}}} = \tan^{-1} \left(M_{2_{\dot{1}}} / M_{2_{\dot{n}}} \right)$$
 (66)

With the oblique shock relations giving the change in flow properties across the shock as

$$M_{4_{N_{i}}}$$
; $(p_{4}/p_{2})_{i}$; $a_{4}/a_{2})_{i}$; $\theta_{4_{i}}$

and the relation

$$M_{4_{t_{i}}} = M_{2_{t_{i}}} (a_{2}/a_{4})_{i}$$
 (67)

the flow properties behind the reflected shock can be found from

$$M_{4_{i}} = (M_{4_{N_{i}}}^{2} + M_{4_{t_{i}}}^{2})^{\frac{1}{2}}$$
(68)

$$p_{4_{i}}/p_{\infty} = (p_{4}/p_{2})_{i} p_{c}/p_{\infty}$$
 (69)

$$\sigma_{4_{i}} = \pi/2 - \Omega_{i} + \tan^{-1} \left(\frac{M_{4_{i}}}{M_{4_{N_{i}}}} \right)$$
 (70)

$$\theta_{4_{i}}' = \theta_{4_{i}} - \delta_{2_{i}} \tag{71}$$

$$S_{4_{i}} = \frac{\overline{y}-1}{2\overline{y}} S_{2}/R + \frac{1}{2\overline{y}} \left[\ln \left(\frac{2\overline{y}M_{2}^{2} \sin^{2}\theta_{4_{i}} - (\overline{y}-1)}{\overline{y}+1} \right) - \overline{y} \ln \left(\frac{(\overline{y}+1)M_{2}^{2} \sin^{2}\theta_{4_{i}}}{(\overline{y}-1)M_{2}^{2} \sin^{2}\theta_{4_{i}} + 2} \right) \right]$$
(72)

where p_C/p_{∞} and S_2/R represent the pressure ratio and the entropy increase across the conical shock. The shock angle, θ_4' is referred to the plane surface.

C-2 Characteristic Subroutine

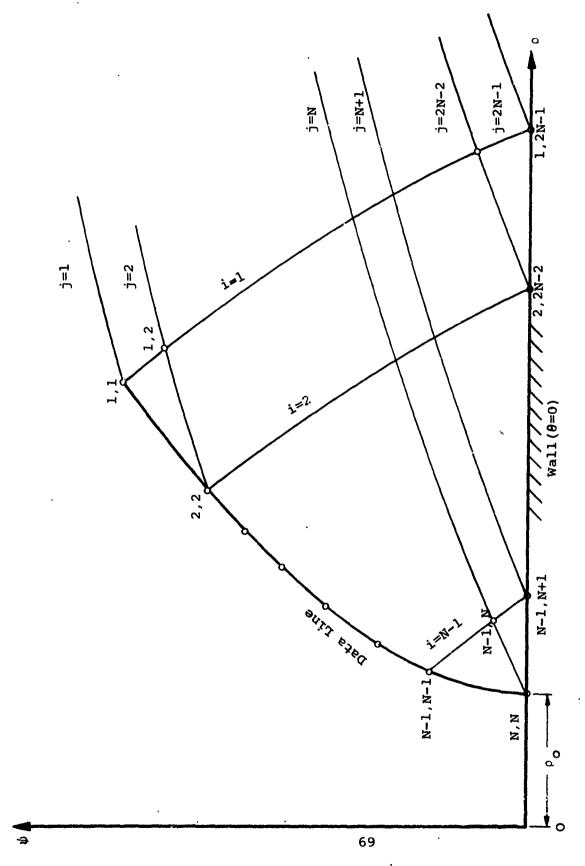
The flow properties on the plane surface behind the reflection curve are determined by using two-dimensional characteristics. The flow conditions immediately behind the reflected shock on the plane surface are calculated by the methods of the preceding section. Due to the conical flow in front of the reflected shock, the properties behind the shock vary in the y-direction. Therefore, the flow is truly three-dimensional. However, the y-variations are small for most cases of interest in inlet design (γ_b < 10 approximately) and thus a two-dimensional characteristic calculation on the plane surface has been assumed appropriate.

On the plane surface, whose coordinates are redefined as ρ,ψ the intersection curve is considered a data line, since the flow conditions immediately behind it are known (Fig.32). Due to the flow symmetry about the plane x=x'=0, the ρ axis must be a streamline and therefore can be considered as a wall with zero flow deviation ($\theta=0$). The data line terminates when either a five degree slope or a Mach reflection is reached. The program computes the characteristic mesh between the data line, the wall and the second family characteristic line from the last data point. The characteristic equations include the effect of entropy due to the varying strength of the reflected shock. This subroutine can also be applied to find the flow field behind the intersection curves of any of the problems considered in this report.

The data required for the characteristic equations at each point (ρ_i , ψ_i) on the data line are: the flow deviation, θ , with respect to the ρ axis, the local entropy $\bar{S}_i = (S_i - S_m)/2c$, the local velocity, w_i , nondimensionalized with respect to the local limiting velocity and the local Mach angle μ_i . The values of w_i and μ_i can be found from the known Mach number behind the intersection curve from the relations:

$$w_{i} = M_{i} \frac{\sqrt{\frac{\bar{y}-1}{2}}}{\sqrt{1 + \frac{\bar{y}-1}{2} M_{i}^{2}}}$$
(73)

$$\mu_{i} = \sin^{-1} (1/M_{i})$$



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FIGURE 32 - CHARACTERISTIC MESH

The equations which determine the location of a typical point Q_3 in Fig. 33 are

$$\psi_{3} - \psi_{1} = (\rho_{3} - \rho_{1}) \left[\tan (\theta + \mu) \right]_{1,3}$$

$$\psi_{3} - \psi_{2} + (\rho_{3} - \rho_{2}) \left[\tan (\theta - \mu) \right]_{2,3}$$
(74)

where the double subscript indicates the average value between the two points. The relations which hold along the first and second family characteristic lines are, respectively

$$(\frac{\cot \mu}{w})_{1,3} (w_3 - w_1) - (\theta_3 - \theta_1) = -\frac{2}{7-1} (\sin^2 \mu \cos \mu)_{1,3}$$

$$\cdot \frac{ds}{dn} \overline{Q_1 Q_3}$$

$$(\frac{\cot \mu}{w})_{2,3} (w_3 - w_2) - (\theta_3 - \theta_2) = \frac{2}{7-1} (\sin^2 \mu \cos \mu)_{2,3} \frac{ds}{dn} \overline{Q_2 Q_3}$$

where ds/dn represents the entropy variation between the points Q_1 and Q_2 normal to the streamlines.

The characteristic grid consists of first and second family characteristics designated by j=1,2....2N-1 and i=1,2....N-1 respectively, where N is the number of data points (Fig. 32.) If the Eqs. (74) are rearranged into a form suitable for computation there results

$$\rho_{i,j} = \frac{\psi_{i+i,j} - \psi_{i,j-1} - \rho_{i+i,j} \tan(\overline{\theta + \mu}) + \rho_{i,j-1} \tan(\overline{\theta - \mu})}{\tan(\overline{\theta - \mu}) - \tan(\overline{\theta + \mu})}$$
(76)

$$\psi_{i,j} = \psi_{i,j-1} + (\rho_{i,j} - \rho_{i,j-1}) \tan (\overline{\theta - \mu})$$
 where

$$\tan(\overline{\theta+\mu}) = \frac{1}{2} \left[\tan(\theta_{i+1,j} + \mu_{i+1,j}) + \tan(\theta_{i,j} + \mu_{i,j}) \right]$$
 and (77)

 $\tan(\theta-\mu)=\frac{1}{2}[\tan(\theta_{i,j-1}-\mu_{i,j-1}) + \tan(\theta_{i,j}-\mu_{i,j})]$ For the first approximation of these averages only the values at the known point are used. The order of computation is to start at the point i=N, j=N and to move

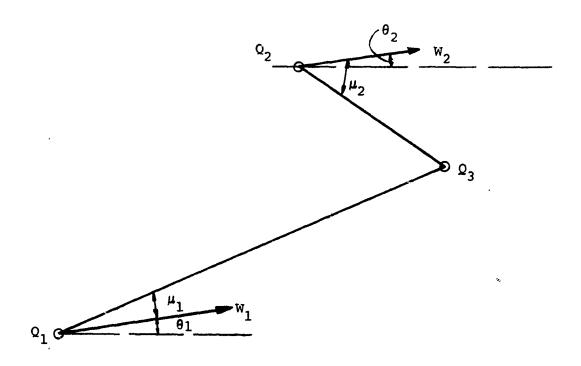


FIGURE 33 - CHARACTERISTIC UNIT PROBLEM

along second family characteristic lines, (i=const.), from the data line, toward the wall. This can be represented, in subscript form, by

$$i = N, N-1, N-2,...1$$

 $j = i, i+1, i+2,...2N-1$

A wall point is obtained whenever i=2N-j. At these points $\psi_{i,j} = \theta_{i,j} = 0$ and

$$\rho_{i,j} = \rho_{i,j-1} + \psi_{i,j-1} \left| \cot \left(\overline{\theta - \mu} \right) \right|$$
 (78)

where

$$\cot \alpha (\overline{\theta - \mu}) = \frac{1}{2} \left[\cot \alpha (\theta_{i,j-1}^{-\mu}, j-1) - \cot \alpha \mu_{i,j}^{-\mu} \right]$$
(79)

Eqs. (75) , solved for w and θ , give

$$w_{i,j} = \frac{1}{\Delta} (\Omega_{i+1,j} + \Omega_{i,j-1})$$
 (80)

$$\theta_{i,j} = \frac{1}{\Delta} \left[\Omega_{i,j-1} \left(\frac{\overline{\operatorname{ctan}}_{i+1,j}}{w_{i+1,j}} \right) - \Omega_{i+1,j} \left(\frac{\overline{\operatorname{ctan}}_{i,j-1}}{w_{i,j-1}} \right) \right] \quad (81)$$

where

$$\Omega_{i+1,j} = -\frac{2}{\overline{\gamma}-1} \left(\overline{\sin^2 \mu_{i+1,j}} \cos \mu_{i+1,j} \right) \left(\frac{\overline{ds}}{\overline{dn}} \right) \overline{L}_{i+1,j}
-\theta_{i+1,j} + w_{i+1,j} \left(\overline{\frac{\cot \mu_{i+1,j}}{w_{i+1,j}}} \right)
\Omega_{i,j-1} = \frac{2}{\overline{\gamma}-1} \left(\overline{\sin^2 \mu_{i,j-1}} \cos \mu_{i,j-1} \right) \left(\overline{\frac{ds}{dn}} \right) \overline{L}_{i,j-1}
+\theta_{i,j-1} + w_{i,j-1} \left(\overline{\frac{\cot \mu_{i,j-1}}{w_{i,j-1}}} \right)
\Delta = \left(\overline{\frac{\cot \mu_{i+1,j}}{w_{i+1,j}}} \right) + \left(\overline{\frac{\cot \mu_{i,j-1}}{w_{i,j-1}}} \right)$$
(82)

and where

$$\begin{split} & \overline{L}_{i+1,\frac{\pi}{2}} [(\psi_{i,j} - \psi_{i+1,j})^2 + (\rho_{i,j} - \rho_{i+1,j})^2]^{\frac{1}{2}} \\ & \overline{L}_{i,j-1} = [(\psi_{i,j} - \psi_{i,j-1})^2 + (\rho_{i,j} - \rho_{i,j-1})^2]^{\frac{1}{2}} \\ & \chi_{\frac{ds}{dn}} = \frac{\overline{S}_{i,j-1} - \overline{S}_{i+1,j}}{\overline{L}_{i+1,j}} + \overline{L}_{i,j-1} (sin\mu_{i,j-1}) \\ & \overline{sin\mu_{i+1,j}} = \frac{1}{2} (sin\mu_{i+1,j} + sin\mu_{i,j}) \\ & \overline{sin^2\mu_{i+1,j}} = \frac{1}{2} (sin\mu_{i,j-1} + sin\mu_{i,j}) \\ & \overline{sin^2\mu_{i+1,j}} \cos \mu_{i+1,j} = \frac{1}{2} (sin^2\mu_{i+1,j} \cos \mu_{i+1,j} + sin^2\mu_{i,j}) \\ & \overline{sin^2\mu_{i,j}} \cos \mu_{i,j}) \\ & \overline{sin^2\mu_{i,j-1}} \cos \mu_{i,j-1} = \frac{1}{2} (sin^2\mu_{i,j-1} \cos \mu_{i,j-1} + sin^2\mu_{i,j-1} \cos \mu_{i,j}) \\ & \overline{sin^2\mu_{i,j-1}} \cos \mu_{i,j}) \\ & \overline{\frac{ctan\mu_{i+1,j}}{w_{i+1,j}}} = \frac{1}{2} \left(\frac{ctan\mu_{i+1,j}}{w_{i+1,j}} + \frac{ctan\mu_{i,j}}{w_{i,j}} \right) \\ & \overline{\frac{ctan\mu_{i,j-1}}{w_{i,j-1}}} = \frac{1}{2} \left(\frac{ctan\mu_{i,j-1}}{w_{i,j-1}} + \frac{ctan\mu_{i,j}}{w_{i,j}} \right) \\ & \overline{\frac{ctan\mu_{i,j-1}}{w_{i,j-1}}} = \frac{1}{2} \left(\frac{ctan\mu_{i,j-1}}{w_{i,j-1}} + \frac{ctan\mu_{i,j}}{w_{i,j}} \right) \end{aligned}$$

The Mach angle and the non-dimensionalized entropy are

$$\mu_{i,j} = \sin^{-1} \left[\left(\frac{\overline{y}-1}{2} - \frac{1-w_{i,j}^2}{w_{i,j}^2} \right)^{\frac{1}{2}} \right]$$
 (84)

$$\overline{S}_{i,j} = \overline{S}_{i,j-1} - \frac{d\widetilde{S}}{dn} \overline{L}_{i,j-1} (\overline{\sin\mu}_{i,j-1})$$
(85)

At the wall, (i=2N-j), the flow properties are

$$\frac{w_{i,j}^{-w_{i,j-1}^{+}} \left(\frac{\frac{1}{\cot n\mu_{i,j-1}}}{\frac{w_{i,j-1}^{-}}{w_{i,j-1}^{-}}}\right) \left[\theta_{i,j-1}^{+} + \frac{2}{\frac{2}{\gamma-1}}\right] \\
\times \left(\sin^{2}\mu_{i,j-1}^{-\cos\mu_{i,j}}\right) \left(\frac{d\tilde{s}}{dn}\right) L_{i,j-1}^{-} \qquad (86)$$

$$\mathbf{x} \left(\sin^{2} \mu_{\mathbf{i}, \mathbf{j}-1} \cos \mu_{\mathbf{i}, \mathbf{j}} \right) \left(\frac{d\tilde{\mathbf{s}}}{dn} \right) \mathbf{L}_{\mathbf{i}, \mathbf{j}-1}$$
(87)

where
$$(\frac{d\tilde{s}}{dn})^{j=0} = \frac{\overline{s}_{i,j-1} - \overline{s}_{N,N}}{\overline{L}_{i,j-1} (\overline{sin}\mu_{i,j-1})}$$

Since the wall is a streamline, the entropy has the constant value $S_{N,N}$ and the pressure distribution and the pressure distribution can be found from

$$\frac{\mathbf{p}_{\underline{i},\underline{j}}}{\mathbf{p}_{\infty}} = \frac{\mathbf{p}_{\underline{N},\underline{N}}}{\mathbf{p}_{\infty}} \qquad \left(\frac{1 - w_{\underline{i},\underline{j}}^2}{1 - w_{\underline{N},\underline{N}}^2}\right)^{\frac{\overline{\gamma}}{\overline{\gamma} - 1}} \tag{88}$$

For this particular problem, $p_{N,N}/p_{\infty}$ is $p_{4,1}/p_{00}$.

The program operation and example problems are given in Appendices V and VI.

D Intersection of Two Conical Shocks of Different Strengths

D-1 Conical Flow Fields

The problem examined here is the flow field immediately behind the intersection of two conical shocks of different strength. The conical shocks are generated by two unequal cones, one of which is at a small angle of attack with respect to the free-stream velocity. The cone axes are assumed to be in a plane. These assumptions, which simplify the analytical solution of the problem, are consistent with common geometrical configurations of inlets.

The analysis includes the definition of the intersection curve between the two conical shocks, the definition of an orthogonal reference frame attached to the intersection curve, and the use of the two-dimensional oblique shock relations in the plane defined by the normal and binormal to the intersection curve.

In the analysis that follows, the cone with the axis parallel to the free-stream direction will be denoted as the "base cone" while the designation "second cone" will be used for the cone at a small angle of attack.

The flow fields of the two conical bodies are found first. For the base cone, the velocity along a conical ray line (γ = const.) in a spherical coordinate system, and the speed of sound nondimensionalized with respect to the limiting velocity are respectively 15

$$u = \sqrt{\frac{\overline{\gamma}-1}{\overline{\gamma}+2}} \qquad \frac{M_1^*}{\sqrt{1+\tan^2(\psi_1^*-\gamma)}}$$

 $a = \frac{\overline{y}-1}{2} \left(1 - \frac{\overline{y}-1}{\overline{y}+1} M_1^{*2}\right)^{\frac{1}{2}}$

(89)

where M_1^* and ψ_1^* , which represent the critical Mach number and the flow direction, are tabulated in Ref.15. The Mach number components along and normal to the conical ray line γ =const. become (Fig.34)

$$M_{r} = u/a$$

$$M_{t} = M_{r} \tan (\psi_{1}^{*} - \gamma)$$
(90)

The effect of a small angle of attack on the conical flow field can be considered as a perturbation of the flow conditions for no angle of attack. It has been shown in Ref. 11 that a circular come at a small angle of attack produces a circular conical shock having the same half angle as the shock which would be produced by the same concial body at no angle of attack, but inclined slightly with respect to the free stream direction in the plane containing the body axes (z*) and the free-stream velocity vector, Fig.35. Therefore, the total nondimensional velocity components in a cylindrical coordinate system u, v, and w, along the z axis, along the r axes and normal to the meridian plane respectively, may be defined by (16)

$$u_{i} = u_{1} \cos \gamma - v_{1} \sin \gamma + \alpha u_{2} \cos \varphi_{i}$$

$$\bar{v}_{i} = v_{1} \cos \gamma + u_{1} \sin \gamma + \alpha v_{2} \cos \varphi_{i}$$

$$w_{i} = \alpha w_{2} \sin \varphi_{i}$$
(91)

where φ_i is the meridian angle defined in Fig.35, which is incorrectly defined in Ref. 16. The velocity components u_1 and v_1 are the zero-angle of attack values along and normal to the conical ray $\gamma = \gamma_2$, where γ_2 is the shock angle, and are given by

$$u_{1} = \sqrt{\frac{\bar{\gamma}-1}{\bar{\gamma}+1}} M_{1,2}^{*} \frac{1}{\sqrt{1+\tan^{2}(\psi_{1,2}^{*}-\gamma_{2})}}$$
 (92)

$$v_1 = u_1 \tan (\psi_{1,2}^* - \gamma_2)$$

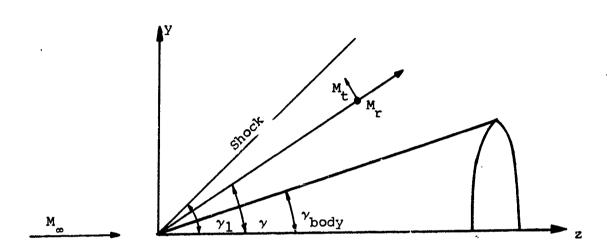


FIGURE 34 - BASE CONE FLOW

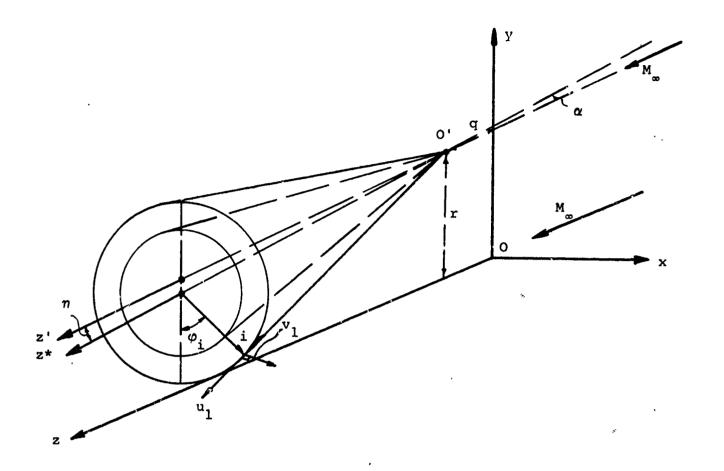


FIGURE 35 - SECOND CONE FLOW

where M_1^* and ψ_1^* are the critical Mach number and the flow direction of the second cone flow with no angle of attack. The perturbation velocities derived from Ref.16 are

$$u_{2} = \sqrt{\frac{\bar{\gamma}-1}{\bar{\gamma}+1}} \left[-\frac{M_{1}^{*}}{2}, 2 \psi_{2}^{*} \sin \psi_{1,2}^{*} + \frac{M_{2}^{*}}{2} \cos \psi_{1,2}^{*} \right]$$

$$v_{2} = \sqrt{\frac{\bar{\gamma}-1}{\bar{\gamma}+1}} \left[-\frac{M_{1}^{*}}{2}, 2 \psi_{2}^{*} \cos \psi_{1,2}^{*} + \frac{M_{2}^{*}}{2} \sin \psi_{1,2}^{*} \right]$$

$$w_{2} = \sqrt{\frac{\bar{\gamma}-1}{\bar{\gamma}+2}} - \frac{M_{2}^{*}}{2} \cos \psi_{1,2}^{*} + \frac{M_{2}^{*}}{2} \sin \psi_{1,2}^{*} \right]$$

$$(93)$$

where the flow direction ψ_2^* and the critical Mach numbers M^*_2 and $M^*_{w,2}$ are tabulated in Ref. 16.

To complete the definition of the flow field of the second cone, the local speed of sound and the second cone shock axis inclination must be defined. The speed of sound non-dimensionalized with respect to the limiting velocity, is

$$a_{2i} = \sqrt{\frac{\bar{y}-1}{2}} \left[1 - \frac{\bar{y}-1}{\bar{y}+1} \quad M_{i}^{*2} \right]^{\frac{1}{2}}$$
 (94)

where the total critical Mach number Mt, is

$$M_{i}^{*} = M_{1,2}^{*} + \alpha M_{2}^{*} \cos \varphi_{i}$$
 (95)

The inclination of the shock axis with respect to the free-stream direction is given by

$$\theta_1 = \alpha \ (1 - \eta/\alpha) \tag{96}$$

where η/α , tabulated in Ref.16, represents the ratio between the deviation of the shock axes from the cone axis and the angle of attack (Fig.36).

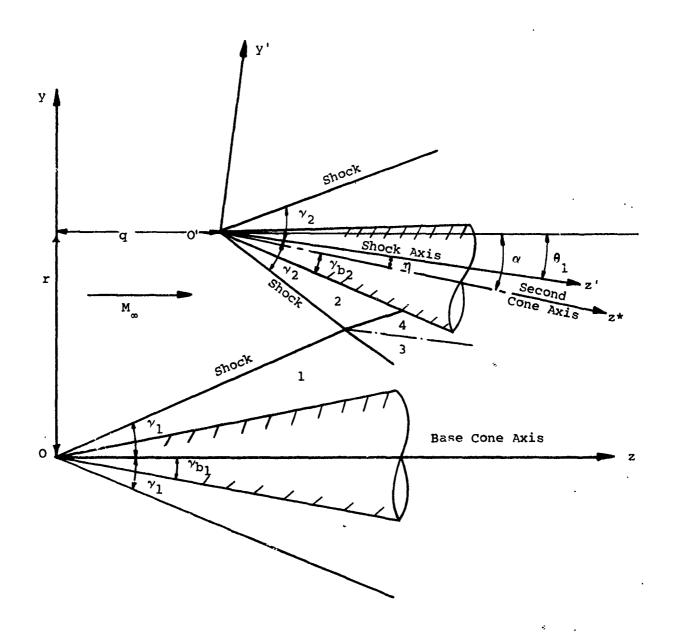


FIGURE 36 - CONICAL-CONICAL SHOCK INTERSECTION

D-2 Shock Intersection

In the preceding section, the conical flow fields have been defined. In order to calculate the flow field behind the intersection of the two conical shocks, it is first necessary to determine the intersection curve. On the base cone a conical coordinative system, ρ , ψ is defined as shown in Fig. 37. The intersection curve of the base cone shock, of angle ν_1 , and the second cone shock, of angle ν_2 , whose axis is inclined by an angle θ_1 to the free stream direction, is represented in this coordinate system by

$$\frac{1}{\rho_{i}} = -\left(D_{1} + C_{1} \cos \psi_{i}\right) + \left[\left(D_{1} + C_{1} \cos \psi_{i}\right)^{2} - \left(A_{1} \cos^{2} \psi_{i} + 2E_{1} \cos \psi_{i} + B_{1}\right)\right]^{\frac{1}{2}}$$

$$(97).$$

where

$$A_{1} = \left[(a_{2}-1) \sin^{2}\gamma_{1} \right] / F_{1}$$

$$B_{1} = \left[(c_{2}+b_{1}^{2}) \cos^{2}\gamma_{1} \right] / F_{1}$$

$$C_{1} = \left[(e_{2}b_{2}^{2} \sin\theta_{1} - d_{2} \cos\theta_{1}) \sin\gamma_{1} \right] / F_{1}$$

$$D_{1} = -\left[(e_{2}b_{2}^{2} \cos\theta_{1} + d_{2} \sin\theta_{1}) \cos\gamma_{1} \right] / F_{1}$$

$$E_{1} = (f_{2} \sin\gamma_{1} \cos\gamma_{1}) / F_{1}$$
(98)

and where

$$b_{1}^{2} = \tan^{2} \gamma_{1}$$

$$b_{2}^{2} = \tan^{2} \gamma_{2}$$

$$a_{2} = \cos^{2} \theta_{1} - b_{2}^{2} \sin^{2} \theta_{1}$$

$$c_{2} = \sin^{2} \theta_{1} - b_{2}^{2} \cos^{2} \theta_{1}$$

$$d_{2} = r \cos \theta_{1} + q \sin \theta_{1}$$

$$e_{2} = r \sin \theta_{1} - q \cos \theta_{1}$$

$$f_{2} = \cos \theta_{1} \sin \theta_{1} (1+b_{2}^{2})$$

$$F_{1} = d_{2}^{2} - b_{2}^{2} e_{2}^{2}$$
(99)

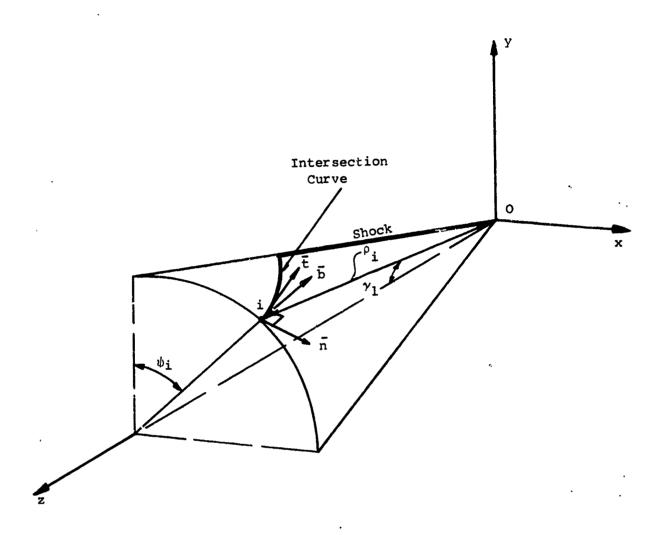


FIGURE 37 - BASE CONE COORDINATES

The curve is computed by inserting values of ψ_i given by, $\psi_i = i\Delta\psi$, $i=0,1,2\cdots\psi_{\text{max}}/\Delta\psi$ into Eq.(97) where ψ max. represents the furthest point out on the intersection curve, before the curve bends in again

 $\psi_{\text{max}} = \cos^{-1} \left[\frac{D_1 C_1 - E_1}{C_1^2 - A_1} + \sqrt{\left(\frac{D_1 C_1 - E_1}{C_1^2 - A_1}\right)^2 - \frac{D_1^2 - B_1}{C_1^2 - A_1}} \right]$

In order to determine the planes normal to the tangent to the intersection curve, the direction cosines of the tangent, bi-normal and normal with respect to the x-y-z directions must be found. Following the procedure of Ref.17, the direction cosines of the tangents to the intersection curve are found as

$$\cos(\hat{\mathbf{f}}_{\mathbf{x}})_{i} = \sin\gamma_{1} (\rho_{i}^{!} \sin^{2}\psi_{i} - \rho_{i} \cos\psi_{i})/\Delta_{i}^{*}$$

$$\cos(\hat{\mathbf{f}}_{\mathbf{y}})_{i} = \sin\gamma_{1} \sin\psi_{i} (\rho_{i}^{!} \cos\psi_{i} + \rho_{i}^{!})/\Delta_{i}^{*}$$

$$\cos(\hat{\mathbf{f}}_{\mathbf{z}})_{i} = \rho_{i}^{!} \cos\gamma_{1} \sin\psi_{i}/\Delta_{i}^{*}$$
(100)

where

$$\rho_{i}' = -\frac{1}{\sin \psi_{i}} \left(\frac{\partial \rho}{\partial \psi} \right)_{i} = \rho_{i}^{2} \left[c_{1} \frac{(c_{1}^{2} - A_{1}) \cos \psi_{i} + D_{1} C_{1} - E_{1}}{\sqrt{(c_{1}^{2} - A_{1}) \cos^{2} \psi_{i} + 2 (D_{1} C_{1} - E_{1}) \cos \psi_{i} + D_{1}^{2} - B_{1}}} \right]$$

(101)

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$$\Delta_{i}^{*} = \left[(\rho_{i}^{'})^{2} \sin^{2} \psi_{i} + \rho_{i}^{2} \sin^{2} \gamma_{1} \right]^{\frac{1}{2}}$$
 (102)

The bi-normal to the curve is the normal to the plane tangent to the cone at the generic point i, and the direction cosines are given by

$$\cos(\hat{bx})_{i} = \cos\gamma_{1} \sin\psi_{i}$$

$$\cos(\hat{by})_{i} = \cos\gamma_{1} \cos\psi_{i}$$

$$\cos(\hat{bz})_{anyi} = -\sin\gamma_{1}$$
(103)

Finally, the vector normal to the curve can be found from the vector product $\bar{n} = \bar{t} \times \bar{b}$ and lies on the plane

tangent to the cone at the generic point i. Its direction cosines are

$$\cos(\hat{n}x)_{i} = \cos(\hat{t}y)_{i} \cos(\hat{b}z)_{i} - \cos(\hat{t}z)_{i} \cos(\hat{b}y)_{i}$$

$$\cos(\hat{n}y)_{i} = \cos(\hat{t}z)_{i} \cos(\hat{b}x)_{i} - \cos(\hat{t}x)_{i} \cos(\hat{b}z)_{i}$$

$$\cos(\hat{n}z)_{i} = \cos(\hat{t}x)_{i} \cos(\hat{b}y)_{i} - \cos(\hat{t}y)_{i} \cos(\hat{b}x)_{i}$$

$$(104)$$

The Mach number components, immediately behind the base cone shock $(\gamma = \gamma_1)$, in the t, b and n directions are from Eq. (89) and (90).

$$M_{\overline{t}_{1_{i}}}^{=} = M_{x_{1_{i}}} \cos(\stackrel{\wedge}{tx})_{i} + M_{y_{1_{i}}} \cos(\stackrel{\wedge}{ty})_{i} + M_{z_{1_{i}}} \cos(\stackrel{\wedge}{tz})_{i}$$

$$M_{\overline{n}_{1_{i}}}^{=} = M_{x_{1_{i}}} \cos(\stackrel{\wedge}{nx})_{i} + M_{y_{1_{i}}} \cos(\stackrel{\wedge}{ny})_{i} + M_{z_{1_{i}}} \cos(\stackrel{\wedge}{nz})_{i}$$

$$M_{\overline{b}_{1_{i}}}^{=} = M_{x_{1_{i}}} \cos(\stackrel{\wedge}{bx})_{i} + M_{y_{1_{i}}} \cos(\stackrel{\wedge}{by})_{i} + M_{z_{1_{i}}} \cos(\stackrel{\wedge}{bz})_{i}$$

$$(105)$$

ere
$$M_{x_{1_{i}}} = (M_{r} \sin \gamma_{1} + M_{t} \cos \gamma_{1}) \sin \psi_{i}$$

$$M_{y_{1_{i}}} = (M_{r} \sin \gamma_{1} + M_{t} \cos \gamma_{1}) \cos \psi_{i}$$

$$M_{z_{1_{i}}} = M_{r} \cos \gamma_{1} - M_{t} \sin \gamma_{1}$$
(106)

The Mach number component and the flow deviation in the plane normal to the tangent to the intersection curve are

$$M_{N_{1}} = (M_{n_{1}}^{2} + M_{n_{1}}^{2})^{\frac{1}{2}}$$

$$\delta_{1_{i}} = \left| \Gamma_{i} - \tan^{-1} \left(\frac{M_{n_{1}}}{M_{n_{1}}} \right) \right|$$
(108)

where Γ_i , which represents the angle between the direction of the free-stream Mach number and the normal (\bar{n}) to the intersection curve at each point i in this plane, is given by

$$\Gamma_{i} = \tan^{-1} \left[\frac{\cos(\dot{p}z)_{i}}{\cos(\dot{p}z)_{i}} \right]$$
 (109)

For the second cone, a similar procedure is carried out to find the Mach number components along the Ξ , \bar{b} , and \bar{n} directions, when the value of ϕ_i , corresponding to the generic point i of the intersection curve, is known. The coordinates of the generic point ρ_i , ψ_i in the x',y', directions (Fig. 36) are

$$x'_{i} = \rho_{i} \sin \psi_{i} \sin \gamma_{1}$$

$$y'_{i} = (\rho_{i} \cos \psi_{i} \sin \gamma_{1} - r) \cos \alpha + (\rho_{i} \cos \gamma_{1} - q) \sin \alpha$$
(110)

from which

$$\varphi_{i} = \tan^{-1} \left| \frac{x'_{i}}{y'_{i}} \right| \tag{111}$$

For the second cone, the relations corresponding to equations (105) become from equations (91), (94), and (111) with $\gamma = \gamma_2$

$$M_{\overline{t}_{2_{i}}} = M_{x_{2_{i}}} \cos(\widehat{tx})_{i} + M_{y_{2_{i}}} \cos(\widehat{ty})_{i} + M_{z_{2_{i}}} \cos(\widehat{tz})_{i}$$

$$M_{\overline{n}_{2_{i}}} = M_{x_{2_{i}}} \cos(\widehat{nx})_{i} + M_{y_{2_{i}}} \cos(\widehat{ny})_{i} + M_{z_{2_{i}}} \cos(\widehat{nz})_{i}$$

$$M_{\overline{b}_{2_{i}}} = M_{x_{2_{i}}} \cos(\widehat{bx})_{i} + M_{y_{2_{i}}} \cos(\widehat{by})_{i} + M_{z_{2_{i}}} \cos(\widehat{bz})_{i}$$

$$M_{\overline{b}_{2_{i}}} = M_{x_{2_{i}}} \cos(\widehat{bx})_{i} + M_{y_{2_{i}}} \cos(\widehat{by})_{i} + M_{z_{2_{i}}} \cos(\widehat{bz})_{i}$$

$$(112)$$

where

Mreare
$$M_{x_{2_{i}}} = \frac{\overline{v_{i}}}{a_{2_{i}}} \sin \varphi_{i} + \frac{\overline{w_{i}}}{a_{2_{i}}} \cos \varphi_{i}$$

$$M_{y_{2_{i}}} = (-\frac{\overline{v_{i}}}{a_{2_{i}}} \cos \varphi_{i} + \frac{\overline{w_{i}}}{a_{2_{i}}} \sin \varphi_{i}) \cos \alpha - \frac{\overline{u_{i}}}{a_{2_{i}}} \sin \alpha$$

$$M_{z_{2_{i}}} = (-\frac{\overline{v_{i}}}{a_{2_{i}}} \cos \varphi_{i} + \frac{\overline{u_{i}}}{a_{2_{i}}} \sin \varphi_{i}) \sin \alpha + \frac{\overline{u_{i}}}{a_{2_{i}}} \cos \alpha$$
(113)

The Mach number component and the flow deviation in the plane normal to the tangent to the intersection curve are represented, similar to Eqs. (107) and (108) by

$$M_{N_{2_{i}}} = \left[(M_{\tilde{n}_{2_{i}}})^{2} + (M_{\tilde{b}_{2_{i}}})^{2} \right]^{\frac{1}{2}}$$

$$\delta_{2_{i}} = \left| r_{i} - \tan^{-1} \left(\frac{M_{\overline{b}_{2_{i}}}}{M_{\overline{n}_{2_{i}}}} \right) \right|$$
 (115)

The oblique shock relations in the plane normal to the tangent to the intersection curve are used to find the flow conditions at each point i, immediately behind the intersection of the two shocks, which due to the conical nature of the flow field, remain valid only in the immediate vicinity of the point. In this present work, the flows of the base cone and the second cone are considered to be deflected by the angles δ_2 and δ_1 ;

respectively. Using the oblique shock relations with M_{Nli}

and δ_{2_i} , the Mach number behind the shock M_B , the shock

angle θ and the pressure and speed of sound ratios P_2/P_1 , A_2/A_1 are found for the lower portion of the intersection. The total Mach number behind the shock intersection is

$$M_{3_{i}} = (M_{3_{t_{i}}}^{2} + M_{B_{1_{i}}}^{2})^{\frac{1}{2}}$$
(116)

where
$$M_{3t_{i}} = M_{\overline{t}_{1_{i}}}^{/(A_{2}/A_{1})}$$
 (117)

The total pressure ratio and the total entropy change are

$$(p_{3}/p_{\infty})_{i} = (\frac{p_{2}}{p_{1}})_{i} \frac{p_{1}}{p_{\infty}}$$

$$s_{3} = \frac{\bar{\gamma}-1}{2\bar{\gamma}} \frac{s_{1}}{R} + \frac{1}{2\bar{\gamma}} \left\{ \ln \left[\frac{2\bar{\gamma}M_{N_{1}i}^{2} \sin^{2}\theta_{3i} - (\bar{\gamma}-1)}{\bar{\gamma}+1} \right] - \bar{\gamma} \ln \left[\frac{(\bar{\gamma}+1)M_{N_{1}i}^{2} \sin^{2}\theta_{3i}}{(\bar{\gamma}-1)M_{N_{1}i}^{2} \sin^{2}\theta_{3i} + 2} \right] \right\}$$
(118)

where p_1/p_{∞} and S_1/R are the values immediately behind the base cone shock.

Using $M_{N_{2_i}}$ and δ_{1_i} , the upper portion of the

flow behind the shock intersection is calculated in a similar manner from the oblique shock relations. The flow properties immediately behind the shock are

$$M_{4_{t_{i}}} = M_{\bar{t}_{2_{i}}}/(A_{2}/A_{1})_{i}$$
 (120)

$$M_{4_{i}} = (M_{4_{i}}^{2} + M_{B_{2_{i}}}^{2})^{-}$$
 (121)

$$\frac{p_{4_{i}}}{p_{\infty}} = \left(\frac{p_{2}}{p_{1}}\right)_{i} \frac{p_{2}}{p_{\infty}} \left[\frac{(\bar{\gamma}+1) - (\bar{\gamma}-1) \left(M_{1,2}^{*} + \alpha M_{2}^{*} \cos p_{i}\right)^{2}}{(\bar{\gamma}+1) - (\bar{\gamma}-1) \left(M_{1,2}^{*}\right)^{2}} \right]^{\frac{\bar{\gamma}}{\bar{\gamma}-1}}$$

$$\cdot e - \frac{S_{2}}{R} \alpha \cos p_{i}$$
(122)

$$S_{4_{i}} = \frac{\bar{\gamma}-1}{2\bar{\gamma}} \left(\frac{S_{1,2}}{R} + \alpha \frac{S_{2}}{R} \cos \varphi_{i} \right)$$

$$+ \frac{1}{2\bar{\gamma}} \left\{ \ln \left[\frac{2\bar{\gamma} M_{N_{2_{i}}}^{2} \sin^{2} \theta_{4_{i}} - (\bar{\gamma}-1)}{\bar{\gamma}+1} \right] - \bar{\gamma} \ln \left[\frac{(\bar{\gamma}+1) M_{N_{2_{i}}}^{2} \sin^{2} \theta_{4_{i}}}{(\bar{\gamma}-1) M_{N_{2_{i}}}^{2} \sin^{2} \theta_{4_{i}} + 2} \right] \right\}$$
(123)

The last two expressions contain factors which represent the contribution of the angle of attack of the second cone. In the present analysis, the shock strengths have been assumed to be constant through the intersections. An iterative procedure can be used to improve the results. The iteration consists of varying the flow deviations δ_1 and δ_2 until the pressures in the lower and upper region behind the shock intersection are matched.

In order to define the flow field behind the shock intersection, the characteristic subroutine can be used in a plane which contains the projection of the intersection curve. This curve becomes the data line and the flow properties immediately behind it are obtained by averaging the values in the upper and lower regions and finding the flow deviation in this plane from the projections of the normal and tangent Mach number components.

The program operation and example problems are given in Appendix V and VI. 87

E. Impingement of a Plane Shock On a Conical Surface

The impingement of a plane shock from a twodimensional wedge of angle δ_1 on a conical body is treated here. In order to treat the most general case, the shock of the conical body is included (Fig. 38). The intersection of the conical and plane shocks is found first. the plane shock passes through the conical shock it is no long: Planar, due to the effects of the conical flow field. The Loc : : : lination of this shock can be found by using shock *** the cone surface as shown by dashed lines in In this analysis the computation is carried out only at the cone shock and at the cone surface. The properties obtained by crossing the "plane" shock at the cone surface are used in the manner discussed in the preceding sections to obtain the shock reflected from the cone surface. The flow field behind the reflected shock is found by using the Characteristic Subroutine after transforming the reflection curve, which lies on the cone body, into a curve on a plane.

The computation starts by using oblique shock theory for the given wedge angle, $\boldsymbol{\delta}_1,$ and free stream Mach number to obtain

$$M_1$$
, θ_1 , p_1/p_m and a_1/a_m

which represent the uniform flow properties behind the plane shock. As in the previous sections, the conical field of the cone at zero-angle of attack is defined by imputing the parameters, $\gamma_{\rm C}$, M*, $\psi_{\rm 1}$, p_/p_, T_c/T_w and S_/R behind the conical c

shock and γ_b , M_b^* , ψ_{lb} , p_b/p_b on the body (see Ref. 15). This data allows the conical flow properties to be computed. The Mach number components along and normal to the conical ray γ = const.are

$$M_{r} = u/a$$

$$M_{t} = M_{r} \tan (\psi_{1} - \gamma)$$
(124)

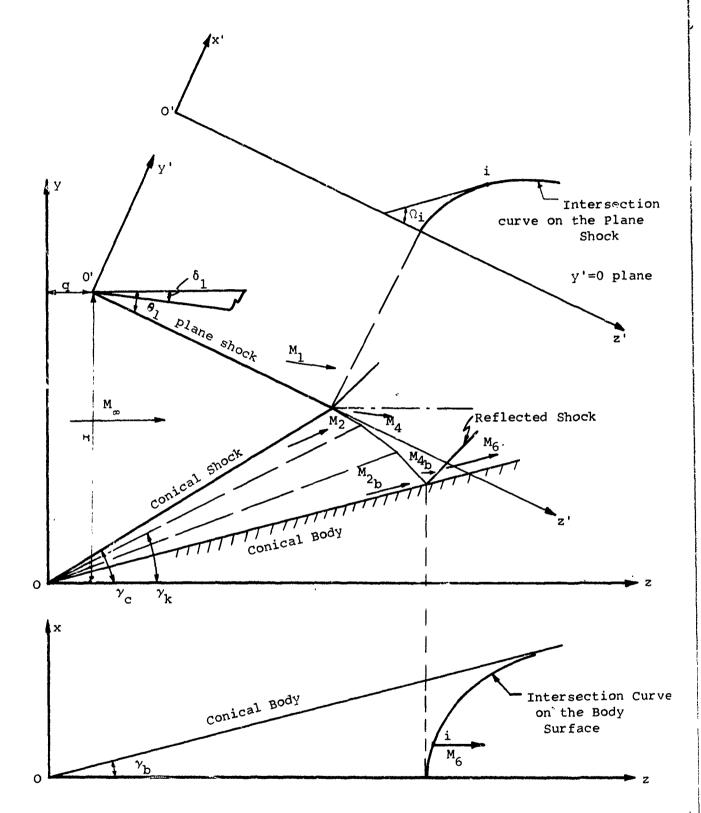


FIGURE 38 - CONICAL BODY-PLANE SHOCK CONFIGURATION

where

$$u = \sqrt{\frac{\bar{\gamma} - 1}{\bar{\gamma} + 1}} M_1^* \cos (\psi_1 - \gamma)$$

$$a = \sqrt{\frac{\bar{\gamma} - 1}{2}} \sqrt{1 - \frac{\bar{\gamma} - 1}{\bar{\gamma} + 1}} M_1^{*2}$$
(125)

The intersection of the conical shock and the plane shock on the z'-x' plane, (Fig. 38), is given by

$$x'_{i} = \left\{ - (Az'_{i}^{2} - 2Bz'_{i} + C) \right\}^{\frac{1}{2}}$$
 (126)

where

$$A = \sin^2 \theta_1 - b^2 \cos^2 \theta_1$$

$$B = r \sin \theta_1 + b^2 q \cos \theta_1$$

$$C = r^2 - b^2 q^2$$

$$b^2 = \tan^2 \gamma c$$
(127)

and where z'_{i} is obtained by incrementing from the value of z' corresponding to x' = 0 (z'_{0}) and is given by

$$z'_{i} = z'_{O} + i \Delta z' \tag{128}$$

The angle between the tangent to the intersection curve and the z'-axis is

$$\Omega_{i} = \tan^{-1} \left| \frac{B - Az^{i}}{x^{i}} \right| \tag{129}$$

The computation of the intersection is terminated when $\Omega_{i}^{<5^{\circ}}$ in order to work on one side of the cone. The conical flow Mach number components immediately behind the shock, $(\gamma=\gamma_{C})$, in the x'-y'-z' directions are

$$M_{2_{x_{i}}} = M_{r} \sin \gamma_{c} \sin \phi_{i} + M_{t} \cos \gamma_{c} \sin \phi_{i}$$

$$M_{2_{Y'i}} = M_{r} \left(\sin \gamma_{c} \cos \alpha_{i} \cos \theta_{1} + \cos \gamma_{c} \sin \theta_{1} \right)$$

$$+ M_{c} \left(\cos \gamma_{c} \cos \alpha_{i} \cos \theta_{1} - \sin \gamma_{c} \sin \theta_{1} \right)$$

$$(1)$$

(130)

$$M_{2_{z'_{i}}} = M_{r} (\cos \gamma_{c} \cos \theta_{1} - \sin \gamma_{c} \cos \phi_{i} \sin \theta_{1})$$

$$-M_t (\cos \gamma_c \cos \alpha_1 \sin \gamma_1 + \sin \gamma_c \cos \alpha_1)$$

where the meridian angle ϕ_i is

$$\varphi_{i} = \tan^{-1} \left(\frac{x_{i}}{y_{i}} \right) \tag{131}$$

with

$$x_{i} = x'_{i}$$

$$y_{i} = q + z'_{i} \sin \theta_{1}$$
(132)

Equations (130) projected along the normal and the tangent to the intersection curve with z', x' plane become

$$M_{2_{n_{i}}} = M_{2_{z_{i}}} \sin \Omega_{i} - M_{2_{x_{i}}} \cos \Omega_{i}$$

$$M_{2_{t_{i}}} = -M_{2_{z_{i}}} \cos \Omega_{i} - M_{2_{x_{i}}} \sin \Omega_{i}$$
(133)

With the total Mach number component in the generic plane normal to the intersection curve at point i given by

$$M_{2_{N_{i}}} = (M_{2_{Y_{i}}}^{2} + M_{2_{n_{i}}}^{2})^{\frac{1}{2}}$$
(134)

and the strength of the plane shock given by,

$$\delta_{1_{i}}^{*} = \tan^{-1} \left(\frac{\tan \theta_{1}}{\sin \Omega_{1}} \right) - \tan^{-1} \left[\frac{\tan \left(\theta_{1} - \delta_{1} \right)}{\sin \Omega_{i}} \right]$$
 (135)

the oblique shock relations can be used to find the flow properties behind the lower region of the shock intersection. The properties thus found are the Mach number component $M_{4...}$, the shock angle, $\theta_{4..}$, in the plane normal to the intersection curve and the pressure and speed of sound ratios $(P_4/P_2)_i$ and $(a_4/a_2)_i$, respectively. The tangent Mach number component M_4 , the total Mach number M_4 , the pressure ratio

 $(p_4/p_{\infty})_i$, the speed of sound ratio $(a_4/a_{\infty})_i$ and the change of entropy S₄ are respectively

$$M_{4_{i}} = M_{2_{i}} \left(\frac{a_{2}}{a_{4}}\right)_{i}$$

$$M_{4_{i}} = \left\{ \left(M_{4_{N_{i}}}\right)^{2} + \left(M_{4_{t_{i}}}\right)^{2}\right\}_{2}^{\frac{1}{2}}$$

$$\left(p_{4}/p_{\infty}\right)_{i} = \left(p_{4}/p_{2}\right)_{i} \left(p_{c}/p_{\infty}\right)$$

$$\left(a_{4}/a_{\infty}\right)_{i} = \left(a_{4}/a_{2}\right)_{i} \sqrt{T_{c}/T_{\infty}}$$

$$= \frac{1}{2} \left(\left(\sqrt{\gamma_{-1}}\right)^{\frac{S_{2}}{2}} + \left(\sqrt{\gamma_{-1}}\right)^{\frac{S_{2}}{2}} + \left(\sqrt{\gamma_{-1}}\right$$

$$S_{4_{i}} = \frac{1}{2\overline{\nu}} \left\{ (\overline{\nu}-1) \frac{S_{2}}{R} + \left[\ln \left(\frac{2\overline{\nu} \cdot M_{2} \sin^{2} \theta_{4_{i}} - (\overline{\nu}-1)}{\overline{\nu}+1} \right) - \overline{\nu} \ln \left(\frac{(\overline{\nu}+1) M_{2}^{2} \sin^{2} \theta_{4_{i}}}{(\overline{\nu}-1) M_{2}^{2} \sin^{2} \theta_{4_{i}} + 2} \right) \right] \right\}$$

The flow deviation with respect to the z' axis is

$$\sigma_{4_{i}} = \Omega_{i} - \tan^{-1} \left| \frac{M_{4_{N_{i}}}}{M_{4_{t_{i}}}} \right| \qquad 92$$
 (137)

For the eventual computation of the upper intersection region it will be useful to know the strength of the conical shock, which is

$$\delta_{2_{i}^{*}} = \tan^{-1} \left(\frac{M_{2_{i}^{'}}}{M_{2_{n_{i}^{'}}}} \right) - \tan^{-1} \left(\frac{\tan A_{1}}{\sin \Omega_{i}} \right)$$
 (138)

In each plane normal to the intersection curve a new orthogonal coordinate system, (ζ,η) , is defined, in which ζ is in the x'-z' plane and is coincident with the normal direction previously defined, (Fig. 39). The angle of the lower shock, referred to the ζ axis, is

$$\theta'_{4} = \theta_{4} - \tan^{-1} \left(\frac{y'_{1}}{M_{2n_{1}}} \right)$$
 (139)

For each normal plane the point η_{i1} , ζ_{i1} of intersection between the shock and the conical body is found from the following;

$$n_{i_1} = -\frac{Q}{P} + \sqrt{(\frac{Q}{P})^2 - \frac{N}{P}}$$
 (140)

$$\zeta_{i_1} = -\eta_{i_1} \cot \theta_{i_1}$$

where

$$P = L + e_1 (E e_1 + 2 G)$$
 $Q = e_1 F + H$ ('.41)

and where

$$E = \cos^{2} \Omega_{i} + \sin^{2} \Omega_{i} (\sin^{2} \theta_{1} - b^{2} \cos^{2} \theta_{1})$$

$$F = -x_{i}' \cos \Omega_{i} - (F_{1} \sin \theta_{1} + b^{2} F_{2} \cos \theta_{1}) \sin \Omega_{i}$$

$$G = -\sin \theta_{1} \cos \theta_{1} \sin \Omega_{i} (1+b^{2})$$

$$H = F_{1} \cos \theta_{1} - b^{2} F_{2} \sin \theta_{1}$$

$$L = \cos^{2} \theta_{1} - b^{2} \sin^{2} \theta_{1}$$
(142)

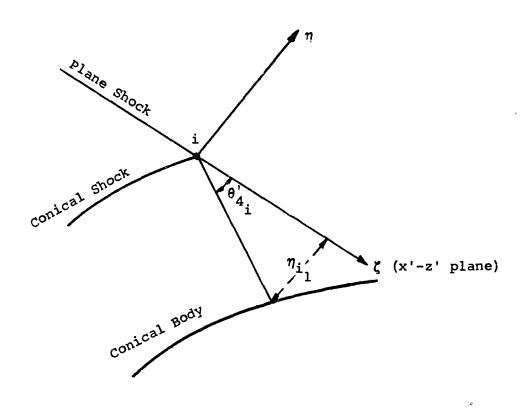


FIGURE 39 - GENERIC PLANE NORMAL TO THE INTERSECTION CURVE

$$N = (x_{i}')^{2} + F_{1}^{2} - b^{2} \cdot F_{2}^{2}$$

$$F_{1} = r - z_{i}' \sin \theta_{1}$$

$$F_{2} = q + z_{i}' \cos \theta_{1}$$

$$e_{1} = -\cot a \begin{vmatrix} a_{i}' \\ a_{i} \end{vmatrix}$$
(143)

The coordinates of these intersection points on the body are transformed into a conical coordinate system, ρ , ρ , which represents the polar distance from the conical body apex and the meridian angle in the z= constant plane, respectively, (see Fig. 40). This transformation is given by

$$\rho_{i} = + \left\{ x_{i_{1}}^{2} + y_{i_{1}}^{2} + z_{i_{1}}^{2} \right\}^{\frac{1}{2}}$$

$$\varphi_{i} = \tan^{-1} \left| x_{i_{1}} / y_{i_{1}} \right|$$
(144)

where

$$x_{i_{1}} = x_{i}' - \zeta_{i_{1}} \cos \Omega_{i}$$

$$y_{i_{1}} = r + n_{i_{1}} \cos \theta_{1} - \sin \theta_{1} (z_{i}' + \zeta_{i_{1}} \sin \Omega_{i})$$

$$z_{i_{1}} = q + n_{i_{1}} \sin \theta_{1} + \cos \theta_{1} (z_{i}' + \zeta_{i_{1}} \sin \Omega_{i})$$
(145)

In order to analytically represent the intersection of the shock on the conical body, a second order curve of the form

$$a_k \varphi^2 + b_k \rho^2 + d_k \rho + 1 = 0$$
 (146)

is fitted to three selected points

which are the center line point, a point in the region near the center line and one of the last points, respectively. The

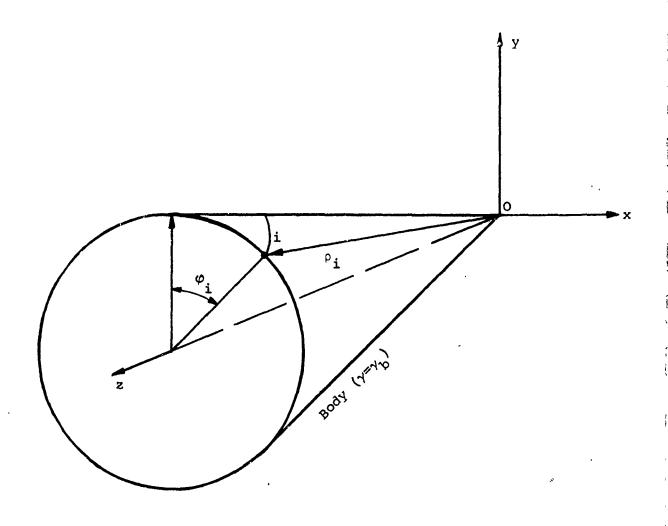


FIGURE 40 - CONICAL COORDINATE SYSTEM ON CONE SURFACE

coefficients of Eq. (146) are

$$a_{k} = (\rho_{2} - \rho_{1}) (\rho_{1} - \rho_{0}) (\rho_{2} - \rho_{0}) / \Delta_{k}$$

$$b_{k} = [\varphi_{1}^{2} (\rho_{2} - \rho_{0}) - \varphi_{2}^{2} (\rho_{1} - \rho_{0})] / \Delta_{k}$$

$$d_{k} = [\varphi_{2}^{2} (\rho_{1}^{2} - \rho_{0}^{2}) - \varphi_{1}^{2} (\rho_{2}^{2} - \rho_{0}^{2})] / \Delta_{k}$$
where
$$\Delta_{k} = \rho_{0} [\varphi_{1}^{2} \rho_{2} (\rho_{2} - \rho_{0}) - \varphi_{2}^{2} \rho_{1} (\rho_{1} - \rho_{0})]$$
(147)

Similar to Section D a set of coordinates tangent, binormal and normal to the curve represented by Eq. (146) are defined. Their direction cosines with respect to the x-y-z axes are

$$\cos(\hat{tx})_{i} = (\varphi_{i} \sin \varphi_{i} \sin \gamma_{b} - AA_{i} \cos \varphi_{i})/BB_{i}$$

$$\cos(\hat{ty})_{i} = (\varphi_{i} \cos \varphi_{i} \sin \gamma_{b} + AA_{i} \sin \varphi_{i})/BB_{i}$$

$$\cos(\hat{tz})_{i} = (\varphi_{i} \cos \gamma_{b})/BB_{i}$$
(148)

$$\cos(\hat{b}x)_{i} = \sin \varphi_{i} \cos \gamma_{b}$$

$$\cos(\hat{b}y)_{i} = \cos \varphi_{i} \cos \gamma_{b}$$

$$\cot_{i} \hat{b}z)_{i} = -\sin \gamma_{b}$$
(149)

and

$$\cos(\hat{n}x)_{i} = NA_{i}$$

$$\cos(\hat{n}y)_{i} = NB_{i}$$

$$\cos(\hat{n}z)_{i} = \Delta\Delta_{i}$$
(150)

where

$$AA_{i} = (b_{k} \rho_{i} + \frac{d_{k}}{2}) \frac{\rho_{i} \sin \gamma_{b}}{a_{k}}$$

$$BB_{i} = \left\{ \varphi_{i}^{2} + AA_{i}^{2} \right\}^{\frac{1}{2}}$$

$$\Delta\Delta_{i} = \cos(\hat{t}x)_{i} \cos(\hat{b}y)_{i} - \cos(\hat{t}y)_{i} \cos(\hat{b}x)_{i}$$

$$NA_{i} = \cos(\hat{t}y)_{i} \cos(\hat{b}x)_{i} - \cos(\hat{t}x)_{i} \cos(\hat{b}y)_{i}$$

$$NB_{i} = \cos(\hat{t}x)_{i} \cos(\hat{b}x)_{i} - \cos(\hat{t}x)_{i} \cos(\hat{b}x)_{i}$$

$$(151)$$

Next it is desired to find the flow field behind the "plane" shock near the conical surface. The Mach number components of the conical flow field in front of the "plane" shock on the conical body are

$$M_{2_{x'bi}} = M_{r} \sin \gamma_{b} \sin \omega_{i} + M_{t} \cos \gamma_{b} \sin \omega_{i}$$

$$M_{2_{y'bi}} = M_{r} (\sin \gamma_{b} \cos \omega_{i} \cos \theta_{1} + \cos \gamma_{b} \sin \theta_{1})$$

$$+ M_{t} (\cos \gamma_{b} \cos \omega_{i} \cos \theta_{1} - \sin \gamma_{b} \sin \theta_{1})$$

$$+ M_{t} (\cos \gamma_{b} \cos \theta_{1} - \sin \gamma_{b} \cos \omega_{i} \sin \theta_{1})$$

$$- M_{t} (\cos \gamma_{b} \cos \omega_{i} \sin \theta_{1} + \sin \gamma_{b} \cos \theta_{1})$$

where M_r is found from Eqs. (124) and (125) with $\gamma = \gamma_b$, $M_1^{\star} = M_{1b}^{\star}$ and $\psi_1 = \psi_1$. The components normal and tangent to the original intersection curve are

$$M_{2} = M_{2} \sin \Omega_{i} - M_{2} \cos \Omega_{i}$$

$$M_{2} = -M_{2} \cos \Omega_{i} - M_{2} \sin \Omega_{i}$$

$$M_{2} = M_{2} \cos \Omega_{i} - M_{2} \sin \Omega_{i}$$

$$98$$

$$(153)$$

The flow field behind the shock near the conical body can be found by using

$$M_{2_{\text{Nbi}}} = \left\{ M_{2_{\text{nbi}}}^{2} + M_{2_{\text{ybi}}}^{2} \right\}^{\frac{1}{2}}$$
 (154)

and δ_{1}^{*} (Eq. 135), in the oblique shock relations. The

shock strength has been assumed to be constant; however, the flow behind the shock near the body differs from that of the lower region of the shock intersection since the flow field in front of the shock is conical. In the usual manner the properties obtained are: the normal Mach number M4 , the shock angle θ_4 , the pressure and speed θ_5

of sound ratios $(P_4/P_2)_{bi}$ and $(a_4/a_2)_{bi}$. The tangent Mach number and the total change in entropy are

$$S_{4_{\text{bi}}} = M_{2_{\text{tbi}}} (a_{2}/a_{4})_{\text{bi}}$$

$$S_{4_{\text{bi}}} = \frac{1}{2\bar{\gamma}} \left\{ (\bar{\gamma}-1) \frac{S_{2}}{R} + \left[\ln \left(\frac{2\bar{\gamma}M_{2}N_{\text{bi}}^{2} \sin^{2}\theta_{4_{\text{bi}}} - (\bar{\gamma}-1)}{\bar{\gamma}+1} \right) - \bar{\gamma} \ln \left(\frac{\bar{\gamma}+1}{\bar{\gamma}-1} M_{2}N_{\text{bi}}^{2} \sin^{2}\theta_{4_{\text{bi}}} - \bar{\gamma} \right) \right\}$$

$$(155)$$

The Mach number components normal and binormal to the original intersection curve are

$$M_{4_{n_{bi}}} = M_{4_{N_{bi}}} \cos (\gamma_{b_{i}}^{*} + \theta_{1_{i}}^{*} - \delta_{1_{i}}^{*})$$

$$M_{4_{b_{bi}}} = M_{4_{N_{bi}}} \sin (\gamma_{b_{i}}^{*} + \theta_{1_{i}}^{*} - \delta_{1_{i}}^{*})$$
(156)

where after much gcomctry

$$\theta_{1_{i}}^{*} = \cos^{-1} \left[\frac{\cos \theta_{1}}{(1-\cos^{2} \Omega_{i} \sin^{2} \theta_{1})^{\frac{1}{2}}} \right]$$

and

$$\gamma_{b_{i}}^{*} = \cos^{-1} \left\{ \left[1 - \cot^{2} \Omega_{i} \cos \theta_{1} \left(\sin \theta_{1} \left(\frac{\partial y}{\partial t} \right)_{i_{1}} \right. \right. \right. \\ \left. - \cos \theta_{1} \right) \right] / \left(1 + \cos^{2} \theta_{1} \cot^{2} \Omega_{i} \right)^{\frac{1}{2}} \left[1 + \left(\frac{\partial y}{\partial t} \right)_{i_{1}}^{2} \right. \\ \left. + \left(\sin \theta_{1} \left(\frac{\partial y}{\partial t} \right)_{i_{1}} - \cos \theta_{1} \right)^{2} \cot^{2} \Omega_{i} \right]^{\frac{1}{2}} \right\}$$

where

$$\begin{aligned} &(\frac{\lambda y}{\delta t})_{i_{1}} = [\sin \theta_{1} \cos \theta_{1} \cot^{2} \Omega_{i} \ y_{i_{1}} \\ &+ \kappa_{i} \cos \theta_{1} \cot \Omega_{i} - (\cos^{2} \theta_{1} \cot^{2} \Omega_{i} \\ &- \tan^{2} \gamma_{b})^{z}_{i_{1}}] / [(\sin^{2} \theta_{1} \cot^{2} \Omega_{i} + 1) \ y_{i_{1}} \\ &+ \kappa_{i} \sin \theta_{1} \cot \Omega_{i} - z_{i_{1}} \sin \theta_{1} \cos \theta_{1} \cot^{2} \Omega_{i}] \\ \text{with} & \kappa_{i} = -\alpha_{i} + \sqrt{\alpha_{i}^{2} - \beta_{i}} \\ &c_{i} = \cot \Omega_{i} (\sin \theta_{1} \ y_{i_{1}} - \cos \theta_{1} \ z_{i_{1}}) \\ &\beta_{i} = (\sin^{2} \theta_{1} \cot^{2} \Omega_{i} + 1) \ y_{i_{1}}^{2} \\ &-2 \sin \theta_{1} \cos \theta_{1} \cot^{2} \Omega_{i} \ y_{i_{1}}^{2} z_{i_{1}} \\ &+ (\cos^{2} \theta_{1} \cot^{2} \Omega_{i} - \tan^{2} \gamma_{b}) \ z_{i_{1}}^{2} \end{aligned}$$

To obtain the flow field behind the reflected shock it is necessary to find the upstream Mach number components in the directions tangent, normal, and binormal to the reflection curve which are

$$M_{4\bar{t}_{i}} = M_{4} \times_{bi} \cos(\hat{t}x)_{i} + M_{4} \times_{bi} \cos(\hat{t}y)_{i} + M_{4} \times_{bi} \cos(\hat{t}z)_{i}$$

$$M_{4\bar{n}_{i}} = M_{4} \times_{bi} \cos(\hat{n}x)_{i} + M_{4} \times_{bi} \cos(\hat{n}y)_{i} + M_{4} \times_{bi} \cos(\hat{n}z)_{i}$$

$$M_{4\bar{b}_{i}} = M_{4} \times_{bi} \cos(\hat{b}x)_{i} + M_{4} \times_{bi} \cos(\hat{b}y)_{i} + M_{4} \times_{bi} \cos(\hat{b}z)_{i}$$

$$(157)$$

where

$$M_{4} = M_{4} \cos \Omega_{i} - M_{4} \sin \Omega_{i}$$

$$M_{4} = M_{4} \cos \theta_{1} - M_{4} \sin \Omega_{i} \sin \theta_{1}$$

$$+ M_{4} \cos \Omega_{i} \sin \theta_{1}$$

$$+ M_{4} t_{bi} \cos \Omega_{i} \sin \theta_{1}$$

$$M_{4} z_{bi} = M_{4} \sin \Omega_{i} \cos \theta_{1} - M_{4} \cos \Omega_{i} \cos \theta_{1}$$

$$+ M_{4} t_{bi} \sin \Omega_{i} \cos \theta_{1} - M_{4} t_{bi} \cos \theta_{1}$$

$$+ M_{4} t_{bi} \sin \theta_{1} \cos \theta_{1} - M_{4} t_{bi} \cos \theta_{1}$$

$$+ M_{4} t_{bi} \sin \theta_{1} \cos \theta_{1} - M_{4} t_{bi} \cos \theta_{1}$$

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$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

$$+ M_{4} t_{bi} \cos \theta_{1} \cos \theta_{1} - M_{4} t_{bi}$$

Then the total Mach number component in a plane normal to the reflection curve

$$M_{4\bar{n}i} = \left\{ M_{4\bar{n}i}^2 + M_{4\bar{b}i}^2 \right\}^{\frac{1}{2}}$$

(159)

and the flow deflection across the reflected shock in this plane

$$\delta_{4_{i}} = \tan^{-1} \left| M_{4_{\bar{b}i}} / M_{4_{\bar{n}i}} \right| \tag{160}$$

can be used in the oblique shock relations to give the flow properties behind the reflected shock on the cone surface. The results are finally given by the following relations:

$$M_{6_{i}} = \left\{ {}^{\bullet}M_{6_{i}}^{2} + M_{6_{N_{i}}}^{2} \right\}^{\frac{1}{2}}$$
(161)

where M_{6} is obtained from the oblique shock relations and N_{1}

$$M_{6\bar{t}_{i}} = M_{4\bar{t}_{i}} \left(\frac{a_{4}}{a_{6}}\right)_{i} \tag{162}$$

The shock angle with respect to the body is

$$\theta_{6_{\underline{i}}} = \theta_{6_{\underline{i}}} - \delta_{4_{\underline{i}}} \tag{163}$$

The pressure ratio is

$$(p_6/p_{\infty})_{i} = \left(\frac{p_6}{p_4}\right)_{i} \left(\frac{p_4}{p_2}\right)_{bi} \left(\frac{p_b}{p_{\infty}}\right) \tag{164}$$

The flow deviation in the ρ , ϕ plane with respect to the ρ axes is

$$\sigma_{6_{i}} = \cos^{-1} \left[\frac{2a_{k}\phi_{i}}{\sqrt{(2a_{k}\phi_{i})^{2} + (2b_{k}\rho_{i} + d_{k})^{2}}} \right] - \tan^{-1} \left(\frac{M_{6_{N_{i}}}/M_{6_{\bar{t}_{i}}}}{M_{6_{\bar{t}_{i}}}} \right)$$
(165)

and the total change in entropy is

$$S_{6_{i}} = S_{4_{bi}} + \frac{1}{2\bar{\nu}} \left[\ln \left(\frac{2\bar{\nu} M_{4_{N_{bi}}}^{2} \sin^{2} \theta_{6_{i}} - (\bar{\nu}-1)}{\bar{\nu}+1} \right) - \bar{\nu} \ln \left(\frac{(\bar{\nu}+1) M_{4_{N_{bi}}}^{2} \sin^{2} \theta_{6_{i}}}{(\bar{\nu}-1) M_{4_{N_{bi}}}^{2} \sin^{2} \theta_{6_{i}}} \right) \right]$$

$$(166)$$

To find the flow field on the body, the characteristic sub-routine can be used in the ρ , ω plane, with the above conditions which are valid immediately behind the reflected shock.

The program operation and example problems are given in Appendices $\,\,$ V and $\,$ VI.

APPENDIX I

HOW TO USE THE PROGRAM (Two-Dimensional and Axisymmetric Flow Computer Program)

1. General Comments

Very often instructions for operating a computer program are more complicated than even the program itself. Many quite useful programs have been rendered almost useless because the answers to prospective users questions are either not provided by the instruction manual or are hidden in a plethora of jargon. The important questions which are answered here are:

- a. What does the program do?
- b. What are its restrictions and limitations?
- c. What input data are required by physics?
- d. What additional input data are required to make the program work?
- e. What is the required form of the input data?
- f. What is given in return (i.e. what are the outputs)?
- q. How is the output to be interpreted?
- h. What might go wrong? What can be done about it?

Answers and parts of answers to some of these questions have already been given. In such instances, the appropriate sections will be designated and that information will not be repeated in this section. The questions and answers are:

a. What does the program do?

The program computes the inviscid supersonic internal flow of a perfect gas of constant specific heat ratio for configurations typical of supersonic and hypersonic inlets. (Also see Section IV-A,B).

b. What are its restrictions and limitations?

In standard notation:

y = constant (constant ratio of specific heats)

 $p = \rho RT$ (perfect gas equation of state)

 $\mu = 0$ (inviscid)

M > 1 (supersonic)

c. What input data are required by physics?

Referring to Figure 11, the physics of these flows requires one to specify the flow conditions completely on some initial data line (which is not characteristic) (\overline{AA}') of Figure 11) and the geometry (y(x), y'(x)) of both the walls. When this data has been specified (maximum ordinate of the initial data must be great enough so that a down characteristic from that point intersects the leading edge of the upper wall) the entire inviscid flow in the inlet can be determined, so long as it remains everywhere supersonic.

Needless to say, one must also specify γ , the ratio of specific heats.

d. What additional input data is required to make the program work?

In addition to the physically required data, the program needs the following information: abscissa of upper and lower leading edges, maximum abscissa of the upper wall to be computed, angle of attack of the free stream flow with respect to the horizontal axis, spacing of mesh points on the initial data line (uniform incident flow), a code indicating whether data along the initial line is supplied or the simplified input is used, a code indicating whether the flow is two-dimensional or axisymmetrical, and other codes related to the wall geometry. In addition, for the convenience of the user, provision is made for inputing and outputing the date and a run indentification number.

e. What is the required input data? Physical Data

As mentioned before all input data must be nondimensionalized in the manner specified in Part C-a, Non Dimensionalization and General Equations of Motion. Read Part C-a before continuing with this section.

If the incident flow is uniform, the user may specify the incident Mach number, M, the specific heat ratio, γ , and, in the case of two-dimensional flow, the angle of attack. In this case the reference pressure and temperature will be assumed to be the incident pressure and temperature.

In the case of uniform incident flow, the leading edge of the lower wall must be upstream of the leading edge of the upper wall. However, if it is not, this requirement can be overcome by extending the lower wall upstream of its leading edge parallel to the incident flow. This can not be done in the case of axisymmetric flow when the leading edge of the lower wall has a sharp corner on the axis of symmetry. If it is desired to have the output referred to another pressure and temperature, it is necessary to input data on the initial data line point by point, the data being referred to the desired reference pressure and temperature.

If the incident flow is non-uniform, it is necessary to specify the data point by point, starting at the leading edge of the lower wall. A reference pressure and temperature (and length, if desired) must be chosen. Then the coordinates of each data point must be specified along with the Mach number, the angle the streamline makes with the x axis, and either the static pressure and temperature or the total enthalpy and total pressure (all non-dimensionalized).

It is important to realize that the initial data line may not be arbitrarily specified. The first point must be at the leading edge of the lower wall and the subsequent points must be in order of increasing ordinate. Also, the initial data line must be oriented so that the characteristics emanating there-from point downstream from the data line (see Figure 26). In addition, the inital data line must be upstream of the leading edge of the upper wall (cowl).

The required data are:

- l) Free stream Mach number, M (simplified input, uniform incident flow) or x,y,M, θ , either p and T or p_t and H on the initial data.
 - 2) Specific heat ratio, γ .
- 3) Abscissae of the two leading edges and the maximum abscissa to be computed on the upper wall. All lengths must be dimensionally the same or non-dimensionalized consistently. If non-dimensionalized, the program does not need to know how this was done, nor is there any way of telling it.

- 4) Angle-of-attack in degrees measured positive counter-clockwise from the horizontal axis. (Two-dimensional, uniform incident flow, only.)
- 5) The code for two-dimensional/axisymmetrical flow is an integer which is zero (0) if the flow is two-dimensional and one (1) if it is axisymmetrical.
- 6) The run identification number and the date are read in as integers, the identification number having a maximum of 5 digits.
 - 7) Miscellaneous control integers.
- 8) y(x) on the lower and upper walls in the form of second order polynomials. There are a maximum of 9 second order polynomials on each wall. The polynomials are of the form

$$y(x) = a_i + b_i (x-x_i) + c_i (x-x_i)^2$$
, i=1, 9

for top and bottom. a_i , b_i , c_i , and x_i must be specified for each polynomial.

Note: - A more complicated, but extremely versatile way of specifying body geretries is given in Appendix A. It can be used to specify body a metries in virtually any manner.

- 9) The x coo. inate of every sharp corner on the upper and lower wall, but not a cluding the leading edges. In addition, the user must supply dy/dx before and after the corner. There are a maximum of six such corners on each wall.
 - f. What is given in return? (What are the output?)

Data at each mesh point, including the location of the point, are written on scratch tape in the following form:

- 1) abscissa and ordinate of the point (in the same units or non-dimensionalized in the same manner as the input lengths).
 - 2) pressure divided by the reference pressure
 - temperature divided by the reference temperature
 - 4) the streamline angle, θ
 - 5) Mach number

- 6) (S-S₀)¢ where S is dimensional entropy (S₀ is the entropy corresponding to the place where p₀ and T₀ are).
- 7) total enthalpy divided by the ratio of reference pressure to reference density.
- 8) the mass flow between the mesh point and the lower wall divided by [square root of (reference pressure x reference density) times the square of the length used to non-dimensionalize lengths (if they are non-dimensionalized)].

i.e.
$$\frac{\text{mass flow}}{\sqrt{\rho_O p_O \ell_O^2}}$$

$$p_O = \rho_O R T_O$$

In addition, in axisymmetric flow the mass flow is also divided by $\boldsymbol{\pi}_{\bullet}$

- 9) Pitot pressure divided by the reference pressure.
- g. How is the output to be interpreted?

The output is given as a function of mesh points on each down running characteristic. In each strip the down running characteristics are identified integrally beginning with 1 for the first point to be computed (see Part D-b on the order of progression of the computation) in that strip. Similarly, the strips are identified integrally beginning with 1 for the strip containing the initial data line.

These should be no problem so far as reference quantities are concerned.

There is a little problem arising from the way in which the computation proceeds. It will be recalled that (see Part D-b-2,3) when a down shock is initiated, the region between (see Figure 16) the last down characteristic BC, in the previous strip (Ith strip) and the down shock, BD, separating the two strips (i.e., the region between BC and BD) is computed first as a part of the Ith strip without considering the influence of the compression at B, and then is recomputed as a part of the (I+1)st strip taking into account the compression. This is necessary since we have no way of knowing a priori just where the shock, BD, will go. We only know that it will always be upstream of BC.

For this reason, in computing the Ith strip, we write out all of the data in that strip up to and including all of the data on BC. Then, in recomputing the region common to both strips, we output the new "good" data between BD and BC. Thus, one must be careful to pick the "good" data for the common region.

But this is made simple by the following device.

Recall that the various strips are separated by down running shocks. In general, the Ita down shock will separate the Ita and the (I+1)st strip. Neglecting, for the moment, the effect of any other down shocks, the data ambiguity is a result of the fact that some of the data computed in the Ita strip is not valid because it is downstream of the Ita shock. So the proper procedure is to plot first the down running shocks and to use their locations as a guide in determining which data has become invalid.

Note that, if two down running shocks coalesce, being continued as one shock, downstream of the coalescence the difference between the strip number on either side of the shock will be greater than one (Figure 25).

h. How long will a computation take?

The program is written in Fortran IV for use with IBSYS 13 on the IBM 7094. A typical case will take about 1-4 minutes execution time.

On the CDC 6600, the same computation would be complete! in less than 2 minutes including compilation time.

i. What might go wrong and what can be done about it?

Any computer program developed to compute phenomena as complicated as those under consideration here is bound to have trouble from time to time. Prospective users should be neither surprised nor frightened by this fact. A good program will have difficulties, but they should not occur too frequently under normal use nor should they occur when relatively "simple" cases are being computed. But, when troubles arise, the user should be given every opportunity to get around the difficulties in order to obtain the information (or at least some of it) desired.

The difficulties of this flow field program will ordinarily fit into two categories, those resulting from computational inaccuracies and those resulting from logical complications caused by extremely complicated flow field patterns.

The usual reason for problems to arise because of computation inaccuracies is that dependent variables have large variations on the scale of a mesh size or less. For instance, if one has an expansion corner, the pressure, density and streamline orientation are discontinuous at the corner. Hence, we make provisions to compute the flow near the corner in special ways in order to retain the desired accuracy. If we did not make such provision, we not only would lose accuracy, but we would usually find that the errors made would be so large that the computation would soon fail to converge in one of the many subsequent iterations.

Suppose that in some region one of the boundaries changes so rapidly, relative to the local mesh scale, that there are large changes in the pressure, density, and streamline orientation during one mesh interval on the body. Then, even though things are smooth, because of the rapid changes it is not unlikely that, in addition to inaccuracies, there will be difficulties and/or failures in attempting to converge in some iteration.

One obvious solution is to decrease the mesh size by decreasing the initial mesh size. This can be done within limits (the computer has limited storage capacity), though a price is paid in increased computer time. If it is impossible to refine the mesh enough, an alternative is to replace the rapid smooth turning with a sharp corner strategically placed and oriented. Then, locally, near the corner, the solution will not describe well the flow over the original body, but the engineer can usually correct the computed flow to give him the required information.

In certain cases the user is justified in relaxing certain tolerances in order to allow an iteration to converge. Such action must be done with an appreciation for the effect that this will have on the computation. Some tolerances can be relaxed by an order of magnitude under certain conditions without having a marked effect on the accuracy of the computation. Others should not be relaxed by even a factor of two. Such decisions require a quite intimate knowledge of the program and should not usually be attempted by infrequent users.

2) Logical problems resulting from extremely complicated flow field patterns - For such problems all of the prescriptions applicable to inaccuracy problems also apply, in addition to a few others. The problems we are now discussing result from very complicated flow field patterns. For example, if three down running shocks converge near the lower wall (perhaps they converge just before, or the reflected shocks converge just after, or some combination happens) near a sharp corner, it would not be too surprising to find that the program gets a little confused trying to keep track of what happened, what is happening, and what might happen. Sometimes the program will fail to work perfectly for such reasons. This does not mean that it is useless or that the user is lost. There are many alternatives available, including those already discussed under a), above.

Another "corrective" measure is best explained by an illustrative example. Suppose that for a given geometry and Mach number, such a complicated pattern develops in a particular region and the program gets confused and stops. Very often a change in Mach number (in both directions) will spread things out so that they are not quite so concentrated. One can use this to infer his desired results.

j. Special control cards; Tape Assignments

The program is written in FORTRAN IV for use on the IBM 7094 or CDC 6600 computer.

Approximately 72,000 octal locations are needed on the CDC 6600. No special control cards are needed other than specifications of the use of logical tape 5 for input, 6 for output, and 3 and 4 as scratch tapes.

On the IBM 7094, the same tape assignments are used. Because of storage requirements, it is necessary to use the alternate input-output option, the ALTIO routines. This is dome by specifying ALTIO as one of the options on the \$IBJOB control card.

2. Input

Input are read on logical tape 5 and the results written on logical tape 6. In addition, the results are stored on logical tape 4 for use during the computation. But that tape can be used later also. Logical tape 3 is also used as a scratch tape.

The data for several cases can be stacked.

INPUT DATA

All Integers Must Be Right Adjusted

Card No.	Columns	Datum- Fortran Symbols	Format	Must be Right Adjusted	Recom- mended Value	Description
1	1-5	NRUN	1 5	Yes		Run number
	6-10	MONTH				Number of the month
	11-15	MDAY				Number of the day
	16-20	MYEAR				Last two digits of the year
	21-25	IUNFLO			Must be ≥0	O-If initial data is uniform and to be computed from given Mach number and γ. In this case the initial data line is the line x=XBEG (see card #2). If the initial data is to be read for each mesh point, then IUNFLO equals the number of such points.
	26-30	JA			Must be 0 or 1	<pre>0 for two-dimen- sional flow, 1 for axisymmetric flow.</pre>
	31-35	ILWFTS			≤ 9	Number of quadratic fits on the lower wall [y(x)=a _i +b _i (x-x _i)+c _i (x-x _i)]
	36-40	IUPFTS	\		≤9	Number of quad- ratic fits on the upper wall [y(x)=a _i +b _i (x-x _i)+ c _i (x-x _i) ²]

Card No.	Columns	Datum- Fortran Symbols	Format	Must be Right Adjusted	Recom- mended Value	Description
ı	41-45	INPT	I5	Yes	+1	INPT=+1 if IUNFLO ≠ 0 and p and T are to be specified. INPT=-1 if IUNFLO ≠0 and p _T and H are to be specified.
	46-50	ICŌRNL			≤6	Number of corners on lower wall (not counting lower leading edge)
	51-55	ICŌRNU	*	*	6	Number of corners on upper wall (not counting upper leading edge
2	1-10	MACH	E10.8	Optional		$v=c_{\rm p}/c_{\rm v}$, the ratio of
	11-20 21-30	GAMMA ALPHA				spečific heats. Angle of attack of free stream with respect to x axis, positive counter-clockwise
	31-40	ĐΥ				∆y interval for
	41-50	XAU				initial line x co- ordinate of the lead- ing edge of the upper wall
	~1 - 60	XEND				Maximum abscissa of the upper wall. The computation will be stopped when this value is reached and the next case will be begun.
	61-70	XBEG	↓	↓		Abscissa of the lead- ing edge of the lower wall.

Card No.	Columns	Datum- Fortran Symbols	Format	Must be Right Adjusted	Recom- mended Value	Description
3	1-10 11-20 21-30	XFLAGL(1) (2) (3)	E10.8	Optional		x coordinate of the sharp corners on the lower wall.
	51-60	(6)				There are a maxi- mum of 6 such corners. They must be in order beginning at the first sharp corner after the leading edge. There are ICOKNL corners (See card #1) *
4	1-10	TFLAGL (1,1)				$\tau=dy/dx$ on the
	11-20	(1,2	:)			upstream edge of the sharp corners on the lower wall,
	51-60	(1,6	i)			in order. *
5	1-10	TFI.AGL (2,1) (2,2)				<pre>r=dy/dx on the downstream side of the sharp corners on the lower wall, in</pre>
	51-60	(2,6)				order, ,*
6	1-10	XFLAGU(1)				x coordinate of
	11-20	(2)				the sharp corners on the upper wall (maximum of 6). They must be in
	51~60	(6)		↓		order beginning with the lst corner after the leading upper edge. There are ICORNU corners (See card # 1) *

^{*} If there are no corners, insert blank data cards.

Card No.	Columns	Datum- Fortran Symbols	Format	Must be Right Adjusted	Recom- mended Value	Description
7	1-10 11-20	TFLAGU (1,1) (1,2) (1,6)		Optional		<pre>τ=dy/dx on the up- stream side of the sharp corners on the upper wall, in order. *</pre>
8	1-10 11-20 51-60	TFLAGU (2,1) (2,2)				<pre>τ=dy/dx on the downstream side of the sharp corners on the upper wall, in order. *</pre>
9	1-10 11-20 21-30 31-40	YLBC(1,1) (1,2) (1,3) (1,4)				Coefficients in the first of the second order polynomial fits for y(x) on the lower wall. y(x)=a1+b1(x-x1)+c1(x-x1)2x1≤x≤x2 where a1 is in columns 1-10, b1 is in columns 11-20, c1 is in columns 11-20, c1 is in columns 11-20, c1 is in columns 11-40. There are a maximum of 9 such fits. The actual number of such fits is ILWFTS which is a datum on the first card.

Card No.	Columns	Datum- Fortran Symbols	Format	Must be Right Adjusted	Recom- mended Value	Description .
10	1-10 11-20 21-30 31-40	YLBC (2,1) (2,2) (2,3) (2,4)		Optional		Coefficients of the second order polynomial fits for y(x) on the lower wall. y(x)=a ₂ +b ₂ (x-x ₂)+c ₂ (x-x ₂) ² , x ₂ < x < x ₃ where a ₂ is in columns 1-10, b ₂ is in columns 11-20,c ₂ is in columns 21-30,x ₂ is in columns
			ì	j		31-40 2
9+ILWFTS-1		YIBC ((ILW	FTS,1)			Coefficients of the last of the second order fits for y(x) on the lower wall.
		YLBC (ILW	rts,4)			
9+ilwfts	1-10 11-20 21-30 31-40	YUBC (1,1) (1,2) (1,3) (1,4)				Coefficients of the 1st of the 2nd order polynomial fits for y(x) on the upper wall. y(x)=a ₁ +b ₁ (x-x ₁)+ c ₁ (x-x ₁) ² x ₁ < x < x ₂ where a ₁ is in columns 1-10,
			Ì	l		b ₁ is in columns 11-20,
•						c ₁ is in columns 11-30,
. . 						x ₁ is in columns 31-40,
		YUBC (IUPF	TS,1) IUPFTS,4)			Coefficients of the last of the 2nd order polynomial fits for y(x) on the upper wall.

If the specified initial data is uniform with given Mach number, there are no more data cards. If the initial data is non-uniform, it is read on the following cards. The first point is the point corresponding to the minimum value of y and will usually correspond to the leading edge of the lower wall (the axis point, for axially symmetric flow). Recall that the coordinate system is right handed, with x, the abscissa, positive in the general direction of the flow. The characteristics issuing from the data line must point downstream of the initial line.

Card No.	Columns	Datum Fortran Symbols	Format	Must be Right Adjusted	Recom- mended value	Description
9+ILWFTS+ IUPFTS	1-10	x (1,1)	E10.8	Optional		x, abscissa of the lst data point (must equal XBEG,
	11-20	Y(1,1)				y, ordinate of the first data point.
	21-30	TAU(1,1)				Angle (in degrees) made by the stream- line through the
	31-40	SM(1,1)				first data point. Mach number of the
	41-50	P (1,1)				first data point. Static pressure (INPT=+1) or total pressure (INPT=-1 of the first data point (non-dimen- sionalized).
	51-60	H(1,1)				Static temperature (INPT=+1) or total enthalpy (INPT=-1) of the first data point (non-dimen-sionalized).
9+ILWFTS+ IUPFTS+1 .						Second data card for initial data line.
9+ILWFTS+ IUPFTS+IU -1						Last: data card for initial data line.

3. Qutput

The output is done by writing on logical tape 6 as the computation proceeds. After each down running characteristic has been computed, the data along that characteristic is output. The data is nondimensionalized as indicated in Part C-a.

Sample output sheets are given in Appendix II (pp. 126-129).

At the beginning of the computation, the pertinent input data are output and identified.

At the top of the data of each down characteristic, the strip number and the number of the characteristic in that strip are printed out. These are foll and by a block with important data concerning the location of contact discontinuities and up running (See page 127, Appendix II.) The contact discontinuities and the shocks are numbered from one (1) to ten (10) beginning with those nearest the upper wall as one proceeds along the characteristic. Thus, on Page 128, Appendix II, one sees that there is a contact discontinuity at the 20th mesh point on the 18th characteristic of the The data on the 'upper' side of the discontinuity is strip. , while the data at the 'lower' side of the disat mesh point 20 continuity is at mesh point 21 . Similarly, there are up-running 25 shocks at mesh points 16 , the data behind the shocks and being stored in points 17 and 26 respectively. The column under SIGMA givesthe local slope of the shock (dy/dx of the shock) while 1/SIGMA is the inverse of the slope.

Following is the data along the characteristic, beginning at the upper wall and continuing to either the lower wall or a down running shock, as the case may be. The column of integers on the extreme left and right identify the mesh point number on that characteristic. The various quantities output are the mesh point coordinates, the non-dimensional pressure and temperature, the angle (in degrees) the streamline makes with the x axis, the Mach number, and the non-dimensional entropy, enthalpy, mass flow (between the lower wall and that mesh point), and total pressure.

The only thing to be cleared up is how to be able to distinguish whether the down characteristic ends at a down running shock or bottom wall. But this is really very easy because the initiation of a down running shock is always indicated by one of the following three

messages:

- 1) SHOCK ON UPPER WALL AT X = y=
- 2) REFLECTION ON UPPER WALI, AT X= , Y=
- 3) DOWN SHOCK FORMED BY COALESENCE OF SMOOTH COMPRESSION WAVES

The first message is written when a down shock is formed by a sharp compression corner on the upper wall.

The second message is written when a down shock is formed by the reflection of an up running shock on the upper wall.

The third message is written when smooth compression waves coalesce to form an 'envelope shock'.

So, after any one of the three messages, the last point on the down running characteristics will be on the downstream side of the down running shock, until that shock reflects at the lower wall. This is indicated by the message

4) REFLECTION ON LOWER WALL AT X = , Y= indicating that a down running shock has reflected off the lower wall, the reflected shock being an up running shock. All the down characteristics printed after message 4), will terminate on the lower wall until one of the messages 1) - 3) is again printed.

Sample output are shown in Appendix II.

APPENDIX II

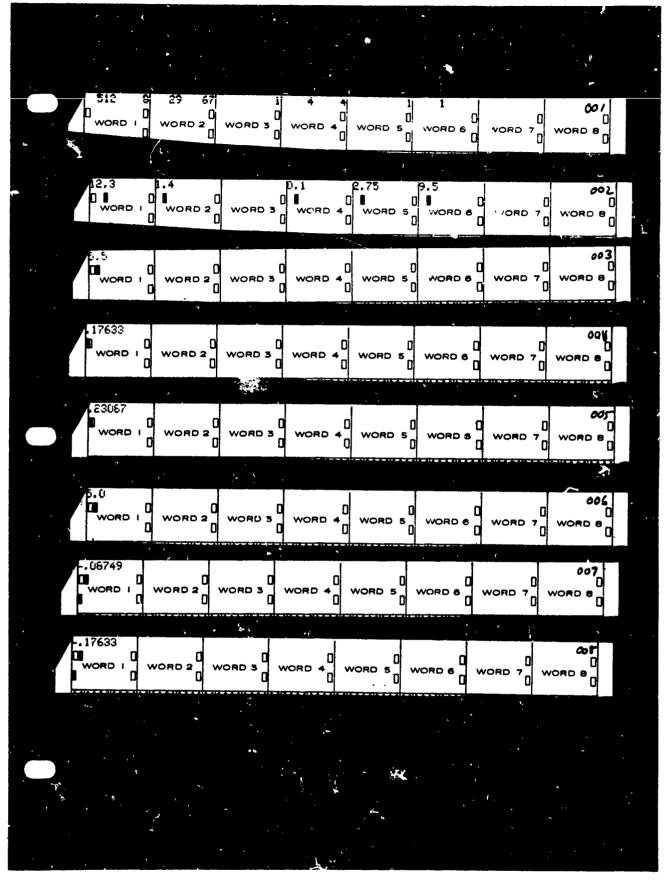
SAMPLE INPUT AND OUTPUT

1. Sample Input

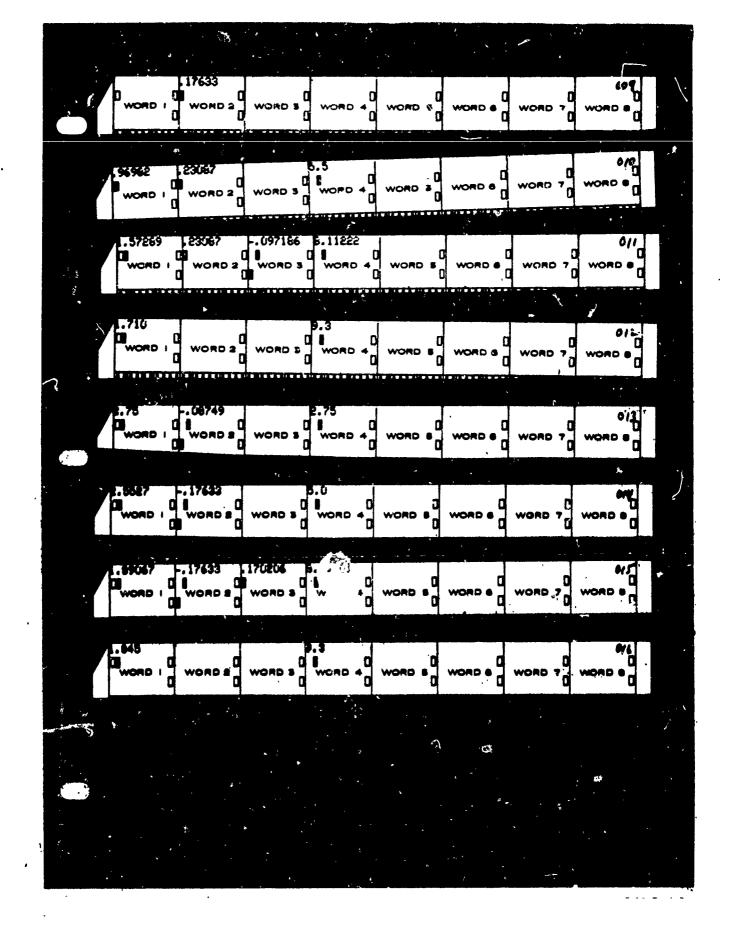
Two-dimensional

Sample input cards for a case with the simplified input (uniform incident flow) are given on the following pages. The data for this case are:

```
\gamma = 1.4
M_{\bullet} = 12.3
Uniform incident flow
Zero degrees angle of attack
\Delta y \sim 0.1 on the initial data line
lower wall leading edge at x = 0.0, y = 0.0
upper wall leading edge at x = 2.75, y = 2.75
maximum upper wall abscissa at x = 9.5
The geometry of the lower wall is:
y = 0.17633x
                       ; 0≤x≤5.5
y = 0.96962 + 0.23087 (x-5.5) 5.5 < x \le 8.1122
y = 1.5729 + 0.23087 (x-8.1122) - 0.097186 (x-3.1122)^2 8.1122 < x \le 9.3
y = 1.71
                               x>9.3
The geometry of the upper wall is:
y = 2.75 - 0.08749 (x-2.75) 2.75 \le x \le 5.0
y = 2.5527 - 0.17633 (x-5.0) 5.0 < x \le 8.782
y = 1.8907 - 0.17633 (x-8.782) + 0.17021 (x-8.782)^2 8.782 < x < 9.3
y = 1.845
                               9.3 < x
```



SAMPLE INPUT CARD



SAMPLE INPUT CARDS (cont'd)
123

2. Sample Output

Sample output sheets for the case of the preceding pages is given on the following pages (pp. 126-129).

The first page, Table I, gives the input data. If the simplified input is not used, just disregard those parameters which are used only for the simplified input. They are:

MACH

M

ANGLE OF ATTACK

DY

 Δy on initial lines

For completeness, a review of the meaning of Table I follows:

The first two lines of output are self-explanatory.

IUNFLO = 0 means the incident flow is uniform and the simplified input is being used

MACH = 12.3 $M_{m} = 12.3$

 $GAMMA = 1.4 \qquad Y = 1.4$

ANGLE OF ATTACK = 0 is self-explanatory

DY = 0.1 Δy = 0.1 on the initial data line which is computed internally

JA = 1 means the flow is axisymmetric

IIWFTS = 4 means there are four geometry fits on the lower wall

INPT = 0 means the flow is uniform and the simplified input is being used

ICORNL = 1 means there is one sharp corner on the lower wall after the leading edge

X UPPER = 2.75 is the abscissa of the leading edge of the upper wall (cowl)

X FINAL = 9.5 is the maximum abscissa to be computed on the upper wall

X IOWER = 0.0 is the abscissa of the leading edge of the lower wall

Following are the abscissae and slopes (dy/dx) of each of the corners on the upper and lower walls. TAU LEFT is dy/dx on the upstream side of the corner. TAU RIGHT is dy/dx on the downstream side. Remember, the leading edges are not counted as corners in this part of the input.

Following are the coefficients of the polynomial fits for the walls. This data is self-explanatory.

Table II shows the data on the eleventh down running characteristic of the first strip. Note that the leading edge of the upper cowl has not yet been intersected. Also note that since the data at x=0, y=0, is on the first characteristic, one would expect to have the eleventh characteristic having an ordinate of y=1.0 since $\Delta y=0.1$ was input. The fact that y=0.9 here indicates that twice a failure has occurred in an iteration and the initial Δy was temporarily halved. In this example this happened at the very beginning near the symmetry axis of the conical centerbody. The lower wall has a leading edge of 10° yielding a conical shock of 11.9° . For a more extensive discussion of how to read this table, see Appendix I, Part c.

Table III gives the data along a down running characteristic further downstream.

The shock wave pattern for this example is given in Appendix III along with some comments about the computation.

TABLE I - SAMPLE OUTPUT (2-D)

SUPERSUNIC INLET-PROGRAM 1A

	(2-D)
•	TABLE II - SAMPLE OUTPUT (2-D)
	SAMPLE
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	II
	TABLE

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TABLE III - SAMPLE OUTPUT (2-D)

STEP_NUMBER_18 ____STRIP NUMBER 3

APPENDIX III

RESULTS

The shock wave pattern for the example case given in Appendix II is shown in Figure 41. The strip numbers are shown in the Figure in order to illustrate once again that feature of the program.

Another sample case is shown in Figure 42. This is an internal flow problem with many sharp compressions and expansions and illustrates very well the interaction of the various wave patterns. The flow is two-dimensional and at an incident Mach number of 3, \bar{P} is the ratio of the local pressure to free stream pressure and M is the local Mach number. The values of \bar{P} and M are indicated for various points in the flow field. Thus, at point D we have $\bar{P} = 0.109$ and $\bar{M} = 4.63$. Point D is just in front of the intersection of the two shocks. Do not interpret the letters as indicating that an entire area has the specified properties. For instance, the properties of \bar{F} are at a point at the wall slightly in front of the expansion corner. The properties vary along the wall between \bar{E} and \bar{F} .

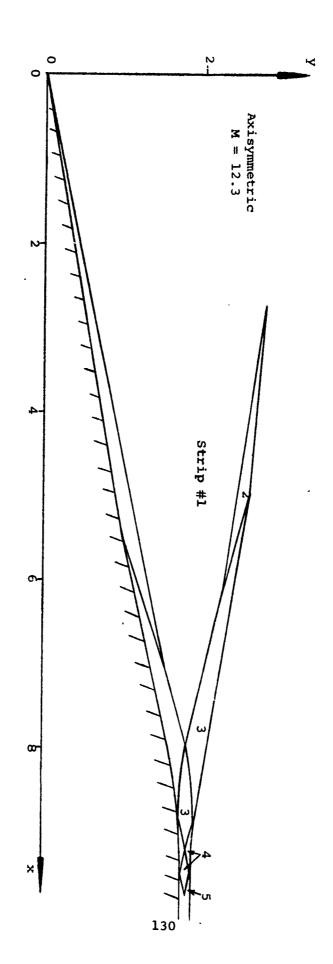


FIGURE 41 - SAMPLE COMPUTATION - SHOCK WAVE PATTERN

have assert

FIGTRE 42 - SAMPLE INTERNAL FLOW COMPUTATION

SHOCK WAVE
SLIP STREAM
CHARACTERISTICS

A CONTRACTOR OF THE CONTRACTOR

00.00 202 R 1670 202 20-7

131

APPENDIX IV

DISCUSSION ON THE GEOMETRY SPECIFICATION AND SUGGESTIONS ON HOW TO ACHIEVE GREATER FLEXIBILITY

It has already been stated that the geometry of the upper and lower walls is specified through a number of second order polynomial fits for y as a function of x. Presently, this number is nine, but it can be increased by simply increasing the dimension of the appropriate variables. In addition, there is provision for six corners on each wall. That number can also be increased. The dimension of the appropriate variables must be one more than the number of fits or corners, respectively.

It would not be difficult to increase the order of the polynomials. The limitations are primarily machine storage space and convenience in input. However, the polynomials could be increased to sixth order while still retaining the pattern of one data card per polynomial. It is only necessary to modify the dimension statements for YLBC and YUBC from (10, 4) to (10, 7), to change the corresponding input and output statements, and to modify the coding in functions YUB, YLB, TUB, TLB, which compute y(x) and dy/dx on the upper and lower boundaries.

These functions can be made as versatile as desired, the only penalty being that a certain amount of programming needs to be performed. Each of these functions has an argument, XIN, which is the value of the abscissa at which one would like either y or dy/dx. That is,

FUNCTION YLB (XIN) computes y(XIN) on the lower boundary,

FUNCTION TLB (XIN) computes T=dy/dx at x=XIN on the lower boundary.

FUNCTION YUB (XIN) computes y (XIN) on the upper boundary,

FUNCTION TUB (XIN) computes T=dy/dx at X=XIN on the upper boundary.

An example can best illustrate the method for changing the geometry routines. Suppose that the second order fits are satisfactory on the upper wall but not on the lower wall where it is desired to specify y(x) as:

 $y(x) = 0 0 \le x \le 1$

 $y(x) = tanh (x-1) 1 < x \le 2$

y(x) = 0.76159 x>2

then

$$y'(x)=0$$
 0 < x < 1

$$y'(x) = sech^{2}(x-1)$$
 1

$$y'(x) = 0$$
 $x > 2$

The procedure is to recompile FUNCTION YLB(XIN) and FUNCTION TLB(XIN) as follows:

\$IBFTC YL

FUNCTION YLB (XIN)

IF (XIN.LE.1.))YLB=0.0

IF (XIN.GT.1.).AND.XIN.LE.2.0) YLB=TANH(XIN-1.0)

IF (XIN.GT.2.0) YLB=0.76159

RETURN

END

SIBFTC TL

FUNCTION TLB (XIN)

IF (XIN.LE.1.0) TLB=0.0

IF (XIN.GT.1.0.AND.XIN.LE.2.0) TLB=1./COSH(XIN-1.0)) **2

ID (XIN.GT.2.0) TLB=0.0

RETURN

END

Do not forget that it is necessary to input the proper data indicating that there is a compressive corner at x=1.0 and an expansion corner at x=2.0.

APPENDIX V

PROGRAM OPERATION (THREE-DIMENSIONAL)

These programs are coded in the IBM Fortran IV language. It is designed for use with the IBSYS Monitor system for the IBM 7090/94 digital computer. The only tapes utilized are the system input tape mounted on unit B1 (logical tape 5), and the system BCD output tape mounted on unit B2 (logical tape 6).

No sense switch settings are interrogated, nor any program stops anticipated. This program may be "backed" with other runs and may be pre-processed via the IBM1401, say, in the usual manner.

Execution time for the longer programs is approximately 1 minute per case.

1. Wedge Program

The wedge program computes the shock and inviscid flow field about a swept wedge with supersonic leading edges including the effects of an angle of attack. The conditions behind the reflection of this shock from a plane surface parallel to the base of the wedge as well as the reflected shock geometry are also computed. In its present form the program uses a ratio of specific heats, γ , equal to 1.4.

Input

The card input to the program is on a single card and is read as follows:

 χ , M_{∞} , λ , α , Δz , r FORMAT (6E10.4)

The symbols in the input statement have the following meanings:

CHI (X): Wedge sweep angle (deg.)
M-INF(M_): Free stream Mach number
LAMBDA (\(^{\chi}\)):Wedge angle in y-z plane (deg.)

ALPHA (α): Angle of attack with respect to wedge base plane (deg.)

DELTA Z (Δz)Step size in z for determining intersection curve. A typical value is 0.05r.

R(r): Distance between reflection plane and the base plane of the wedge (normalized in any convenient manner).

Output

The output consists of the conditions in the two-dimensional region and the constants that define the shock shape, followed by tables of conditions in the conical region for each computed point on the shock reflection curve. It should be noted that the conditions corresponding to the last point in these tables represent the two-dimensional shock reflection.

The meanings of the symbols in the first part of the output are:

LAMBDA-N(λ n): Wedge angle in a plane normal to the leading edge (radians).

ALPHA-N (α_n) : Sum of wedge angle and angle of attack in plane normal to leading edge, i.e., flow deflection across two-dimensional shock (radians).

135

- MN-INF (M $_{n}$): Component of free stream Mach number in a plane normal to leading edge.
- MT-INF (Mt): Component of free stream Mach number tangent to leading edge.
- THETA (θ_1): Two-dimensional shock angle with respect to $M_{R_{1}}$ in a plane normal to leading edge (radians).
- Pl/P-INF(p/p_m):Pressure jump across two-dimensional shock.
- MTl(Mt]: Component of Mach number behind two-dimensional shock, tangent to leading edge.
- THETA-N(θ_{ln}): Shock angle with respect to base plane of wedge in a plane normal to leading edge (radians).
- M-1 (M_1) : Total Mach number on wedge surface.
- CHI-STAR (χ^*) : Angle between z'-axis and leading edge (radians).
- SIGMA-1(σ_1): Flow deviation on wedge surface with respect to z' axes (radians).
- THETA-S(0): Two-dimensional shock angle with recent to the base plane of wedge in a plane parallel to the x-y plane (radians).
- BETA-STAR (β *): Two-dimensional shock angle with respect to base plane of wedge in a plane parallel to the y-z plane (radians).
- THETA-CP(9'): Two-dimensional shock angle with respect to base plane of wedge in a plane normal to the z' axis (radians).
- A: Constant in equation of parabolic sheet (35)
- XJP (x'): The x coordinate of the point of intersection of the two-dimensional shock and the local Mach cone in the plane z' = cos λ
- H(h): Constant in equation of parabolic sheet (36)

THETA-SW (A): Angle between the three dimensional shock and the z' axes in the y-z plane (radians).

The meanings of the symbols in the tables of conditions on each conical ray i are:

I(i): Designates conical ray in central region.

Normalized z coordinate of the intersection point of conical ray i and the shock reflection curve on plane surface.

X(x_i): Normalized x coordinate of the intersection
point of conical ray i and the shock reflection curve on plane surface.

CHI (χ') : Angle between the tangent to the intersection curve and the z-axes (radians).

SIGMA-1 (σ_{l_i}): Flow deviation on conical ray i (radians).

 $M-1(M_{1})$: Total Mach number on conical ray i.

MT(M_l): Upstream Mach number component tangent to intersection curve.

MN(M₁): Upstream Mach number component normal to intersection curve, on plane surface.

MKN (M_N) : Total Mach number component in a plane normal to intersection curve.

DELTA-1(δ_1): Flow deflection across reflected shock (radians).

M2T (M₂): Component of Mach number behind reflected shock, tangent to intersection curve.

P2/P-INF Pressure ratio behind reflected shock.

(P_{2i}/P_i):
M2(M_{2i}): Total Mach number behind reflected shock.

SIGMA-2(σ_{2i}): Flow deviation with respect to z axes behind reflected shock (radians).

THETA-P Reflected shock angle with respect to the reflection plane in a plane normal to the intersection curve (radians).

The subroutine which contains the oblique shock relations is equipped with four stops printed out as follows:

- 1) $M_{\infty} = 1$: If the total Mach number becomes sonic.
- 2) Upstream normal Mach number < 1: If the Mach number component in a plane normal to the leading edge or to the intersection curve becomes sonic.
- 3) Mach Reflection: If the flow deflection used in the shock relations exceeds the maximum value given by

$$\delta_{\rm m} = \frac{4}{3\sqrt{3}(\gamma+1)} \frac{(M_{\rm N}^2 - 1)^{3/2}}{M_{\rm N}^2}$$

where M is the Mach number component in a plane normal to the leading edge or to the intersection curve. The computation of the intersection curve is terminated but the rest of the computation is continued for the points already obtained.

4) Imaginary roots: If a pair of roots of the cubic equation for the shock angle are imaginary.

2 Conical Shock-Plane Surface Program and Characteristic Subroutine

This program starts with the shock and flow field about a cone at zero angle of attack and computes the reflection of this shock from a plane inclined at an angle θ_1 to the cone axes. The characteristic subroutine computes the flow field behind the reflection curve on the plane surface by using two-dimensional characteristics and may be applied to any of the programs of the report. The ratio of specific heats, $\bar{\gamma}$, is an input quantity in the program, while the characteristic subroutine automatically uses the value which the main program has used.

Main Program

Input

The card input to the program is on two cards and is read as follows:

CARD 1: M_{∞} , A_{1} , γ_{c} , $\overline{\gamma}$, r, q, Δz^{*} CARD 2: P_{C}/P_{∞} , M^{*}_{1C} , ψ_{1C} , S_{2}/R FORMAT (4E 10.4)

The symbols in the input statement have the following meanings:

M-INF(M_): Free stream Mach number.

THETA-l(0): Angle between plane surface and free stream direction (deg.)

GAMMA-C (γ_{α}) : Conical shock angle from Reference 15 (rad.)

R (r): y distance between origins 0 and 0' (Fig.31), normalized in any convenient manner.

Q (q): Nondimensionalized z distance between 0 and 0', usually zero.

DELTA-Z(Δz'): Step size in z' for determining intersection curve. A typical value is 0.05 r. PC/P-INF Pressure ratio across conical shock, from (p_C/p_{∞}) : Reference 15.

M1-STAR (M*): Critical Mach number behind conical shock, from Reference 15.

PSI (ψ_{1c}) : Angle of flow behind conical shock with respect to the cone axes (rad.).

S2/R(S₂/R): Entropy change across conical shock normalized with respect to the gas constant.

Output

The output of the program consists of tables of conditions in front of and behind the reflected shock, near the plane surface, for each point i on the reflection curve.

The meanings of the symbols in the output are:

I(i): Designates point on reflection curve.

OMEGA (Ω_i): Angle between the tangent of the reflection curve at point i and the z' axes. The computation terminates when $\Omega_i < 5^{\circ}$ (rad.).

M2XP (M_{2x}): Mach number component behind conical shock in x' direction.

M2YP (M_{2y}): Mach number component behind conical shock in y' direction.

M2ZP (M2z',): Mach number component behind conical shock in z' direction.

M2N (M_{2ni}): Mach number component in front of the reflected shock, normal to the reflection curve, on the plane surface.

- M?T (M₂): Mach number component in front of reflected shock, tangent to the reflection curve.
- M2KN (M_{2N}) : Total Mach number component in front of the reflected shock, in a plane normal to the reflection curve.
- DELTA-2 (δ_{2i}): Flow deflection across the reflected shock in a plane normal to the reflection curve (radians).
- P4/P2 $(p_4/p_2)_{i}$:Pressure jump across reflected shock.
- A4/A2 (a₄/a₂)_i: Speed of sound ratio across reflected shock.
- M4N (M_{4N}): Mach number component behind reflected shock in a plane normal to the reflection curve.
- THETA 4 (4): Reflected shock angle, in a plane normal to the reflection curve, with respect to the direction of $\rm M_{2N_i}$, (radians).
- M4T (M4t): Mach number component behind reflected shock, tangent to reflection curve.
- P4/P-INF (p_4/p_{∞}) : Pressure ratio behind reflected shock.
- SIGMA-4(σ_{4i}): Flow deviation behind reflected shock, with respect to z' axes (radians).
- THETA-P-4(θ'_4): Reflected shock angle with respect to plane body (radians).
- S(S₄): Change in entropy from the free stream value, nondimensionalized by twice the specific heat at constant pressure (2 C_D).

Characteristic Subroutine

The Characteristic Subroutine is an integral part of the program of this section, Conical-Shock-Plane Body, and the program of Section V, Plane Shock-Conical Body. In these cases no additional input is needed. The subroutine also exists as a separate program for which the input is given below. The output of the subroutine is the same for all cases and is also given below.

Input

The second secon

When used as a separate program, the input is on N+1 cards and is read as follows:

CARD 1: γ , p_{NN}/p_{∞} , N

FORMAT (2E10.4, I10)

CARD 2: M_N , ρ_N , ψ_N , θ_N , S_N (Data at last point of main program)

(One card for each data point)

CARD N+1: M_1 , ρ_1 , ψ_1 , θ_1 , S_1 (Data at first point of main program)

The symbols in the input statement have the following meanings:

GAMMA (γ) : Ratio of specific heats

P/P $(p_{N,N}/p_{\infty})$:Pressure ratio at point N,N (Fig.32).

N: Number of data points.

M $(M_{i,j})$: Total Mach number at data point, i=j.

RHO (p_{i,j}): Nondimensionalized coordinate of datapoint (Fig. 32).

PSI $(\psi_{i,j})$: Nondimensionalized coordinate of data point (Fig. 32.)

THETA (*): Flow deviation with respect to p axes, at data point (radians).

S (Si, j): Entropy change from free stream at data point, normalized with respect to twice the specific heat at constant pressure.

Output

The output consists of the Mach angle and velocity at the data points, which is printed next to the data, and a page of output for each second family characteristic line, i=constant, which gives the flow conditions at each point along the line.

The output symbols, not defined under input, have the following meanings:

MU $(\mu_{i,j})$: Mach angle (radians).

W (W_{i,j}): Flow velocity, normalized with respect to the limiting velocity.

I (i): Second family characteristic line. The computation starts at I=N, Fig. 32.

P/P-INF(p_{i,j}/p_∞): Pressure ratio at the wall points, i.e., last point on each i line.

J (j): First family characteristic line, Fig. 32.

3. Double Conical Shock Program

The double conical shock program computes the flow field behind the intersection of two conical shocks of different strength when given the flow conditions behind the shocks. An option is included which allows one of the cones to be oriented by an angle attack, q, with respect to the free stream direction. The properties immediately behind the upper and lower shocks behind the intersection are found, along with the new shock angles. This data can be used in the characteristic subroutine, (Section C), to find the flow field on a plane passing through the shock intersection.

Input

A THE SECOND

The card input consists of three cards if both cones are at zero angle of attack and four cards if one cone is at an angle of attack, and is read as follows:

CARD 1: $M_1^*, \psi_1^*, \gamma_1, p_1/p_{\omega}, s_1/R$

FORMAT (5E10.4)

 $^{\rm M_{1,2}^{\star}}, \, \psi_{1,2}^{\star}, \, \gamma_{2}, \, {\rm p_{2}/p_{\infty}}, \, {\rm s_{1,2}/R}$ FORMAT (5E10.4) CARD 2:

 $r,q,\Delta\psi,\overline{\gamma}, S_{\gamma}/R,KALF$ CARD 3:

FORMAT (5E10.4, I10)

 α , η/α , M_2^* , $M_{w,2}^*$, ψ_2^* CARD 4:

FORMAT (5E10.4)

(Only required if the angle of attack $\alpha \neq 0$)

The symbols in the input have the following meanings:

 $M1* (M_1*):$ Critical Mach number behind the shock of the first cone, ("base cone"), which has zero angle of attack.

PSI 1* (ψ_1^*) Flow direction angle behind the shock of the base cone, (radians).

GAMMA 1 (γ_1) : Base cone shock angle, (radians).

P1/P-INF (p_1/p_{G_1}) : Pressure jump across base cone shock.

S1/R (S₁/R): Entropy increase across base come shock, normalized with respect to the universal gas constant, Reference 15.

M12*(M*_{1,2}): Critical Mach number behind the shock of the second cone, for zero angle of attack.

PS12 $(\psi_{1,2}^*)$: Flow direction angle behind the shock of the second cone, for zero angle of attack, (radians).

GAMMA 2 (γ_2): Shock angle of second cone at zero angle of attack, (radians).

P2/P-INF(p_2/p_{00}): Pressure ratic across the second cone shock, for zero angle of attack.

S12/R(S_{1,2}/R): Entropy increase across second cone shock, for zero angle of attack.

R(r): Vertical, (y), distance between cone verticies, normalized in any convenient manner.

Q (q): Normalized z distance between cone verticies.

DELTA-PSI $(\Delta \psi)$: Step size in ψ for determining the intersection curve. A typical value is 5 deg.(deg.).

GAMMA-BAR $(\bar{\gamma})$: Ratio of specific heats.

S2/R (S2/R): Entropy perturbation, due to angle of attack of second cone 16.

ALPHA (α): Angle of attack of second cone, (deg.).

ETA/ALPHA (η/α): Ratio of tilt angle of second cone shock to angle of attack 16.

M2* (M2*): Critical Mach number perturbation, due to angle of attack, behind second cone shock.

MW2*(M*w,2): Critical Mach number normal to meridian plane, behind second cone shock.

PSI2*(ψ_2 *): Flow direction angle perturbation, due to angle of attack, behind second cone shock, (radians).

Output

The output consists of the maximum value of ψ , three quantities which are invariant along the intersection curve and tables which describe the intersection curve, the base and second cone flows and the flows in the upper and lower intersection regions, for each point i on the intersection curve.

The meanings of the symbols in the output are:

PSI-MAX(ψ max.): Maximum value of intersection curve coordinate, ψ , before reaching double values of ρ , (degrees).

THETA-1 (θ_1) : Angle between second cone shock axis and free stream direction, (radians).

COS(BZ) (cos(bz)): Direction cosine of binormal to intersection curve and z axes.

MZ1(M_{Z1}): Mach number component in z direction, behind lower cone shock.

PSI (ψ_i) : Meridian coordinate of point on intersection curve, (radians).

COS(TX)(cos(tx)):Direction cosine of tangent to intersection curve and x axes.

COS(TY)(cos(ty)):Direction cosine of tangent to intersection curve and y axes.

COS(TZ)(cos(tz)):Direction cosine of tangent to intersection curve and z axes.

COS(BX)(cos(bx);):Direction cosine of binormal to intersection curve and x axes.

- COS(BY)(cos(by)):Direction cosine of binormal to intersection curve and y axes.
- COS(NX)(cos(nx)):Direction cosine of normal to intersection curve and x axes.
- COS(NY) (cos(ny)):Direction cosine of normal to intersection curve and y axes.
- COS(NZ)(cos(nz)):Direction cosine of normal to intersection curve and z axes.
- RHO (ρ_i): Nondimensionalized radial coordinate of point on intersection curve.
- GAMMA (Γ_i) : Angle between the normal to the intersection curve and the free stream direction, (radians).
- MY1 (My1; Mach number component in y direction behind base cone shock.
- MX1 (M_X): Mach number component in x direction behind base cone shock.
- MT-BAR 1 (Mt): Mach number component tangent to the intersection curve, behind the base cone shock.
- MN-BAR 1 (Mn₁): Mach number component along the normal to the intersection curve, behind the base cone shock.
- MB-BAR 1 (M₋): Mach number component along the binormal to the intersection curve, behind the base cone shock.
- MN1 (Mn1:

 Total Mach number component in a plane normal to intersection curve, behind the base cone shock upstream of the intersection.
- DELTA 1 (δ_{1}): Strength of the base cone shock in a plane normal to the intersection curve, and which is assumed to be constant through the intersection, (radians).

х (х	'):	Nondimer	nsional	lized	x'	coordinate	of	inter-
		section	curve	point	i	•		

- Y (y'): nondimensionalized y' coordinate of intersection curve point i.
- Z (z'): nondimensionalized z' coordinate of intersection curve point i.
- PHI (ϕ_i) : Meridian angle of intersection curve point, (second cone coordinates), (radians).
- U-BAR (\bar{u}_i) : Velocity component behind the second cone shock along the z axes, normalized with respect to limiting velocity.
- V-BAR (v
 i): Normalized velocity component behind the second cone shock along the r axes.
- W-BAR (\bar{w}_i) : Normalized velocity component behind the second cone shock, normal to the meridian plane.
- M*(M.*): Total critical Mach number behind the second cone shock.
- A2 (a₂): Speed of sound behind the second cone shock, normalized by the limiting velocity.
- MX2 (M): Mach number component in x direction, behind second cone shock
- MY2 (M): Mach number component in y direction, behind second cone shock.
- MZ2 (M $_{\rm z}$) Mach number component in z direction behind second cone shock.
- MT-BAR 2 (M₋): Mach number component tangent to the intersection curve, behind the second cone shock.
- MN-BAR 2 (M-): Mach number component normal to the intersection curve, behind the second cone shock.

MB-BAR 2 ($M_{\overline{b}}$): Mach number component along the binormal to the intersection curve, behind the second cone shock.

MN2 (M_N): Total Mach number component in a plane normal to the intersection curve, behind the second cone shock.

DELTA 2 (52): Strength of the second cone shock in a plane normal to the intersection curve, and which is assumed constant through the intersection, (radians).

MB1 (M): Mach number component behind lower portion of intersection, in a plane normal to the intersection curve.

THETA ($^{A}_{3}$): Second cone shock angle with respect to $^{\delta}_{1}$; in a plane normal to intersection curve, behind the intersection, (radians).

M3T (M₃): Mach number component behind lower portion of intersection, tangent to the intersection curve.

M3 (M₃): Total Mach number behind lower portion of intersection.

P3/P-INF(p3/p0): Pressure ratio immediately behind lower portion of intersection.

S3 (S₃): Entropy change from free stream, behind lower portion of intersection, normalized by twice the specific heat at constant pressure.

MB2 (M_B): Mach number component behind upper portion of intersection, in a plane normal to the intersection curve.

THETA (θ_4): Base cone shock angle, with respect to δ_2 , in a plane normal to the intersection curve, behind the intersection, (radians).

M4T (Mt): Mach number component behind upper portion of intersection, tangent to the intersection curve.

M4 (M₄): Total Mach number behind upper portion of intersection.

P4/P-INF (p_4/p_{∞}) :Pressure ratio behind upper portion of intersection.

S4 (S₄): Entropy change from free stream behind upper portion of intersection, normalized by twice the specific heat at constant pressure.

4. Plane Shock - Conical Body

When given a conical flow field and a free stream Mach number, this program computes the flow behind the shock from a two-dimensional wedge, both before and after its intersection with the conical shock. The reflection curve of the modified plane shock on the conical body is then determined, together with the flow field behind the reflected shock on the cone surface. The characteristic subroutine, described in Section C, is incorporated in the program to compute the rest of the flow field on the conical body.

Input

The card input to the program consists of four cards and it is read as follows:

CARD 1: M_{∞} , δ_1 , r, q, Δz , $\bar{\gamma}$ FORMAT (6E10.4)

CARD 2: p_c/p_{ω} , p_b/p_{ω} , T_c/T_{ω} , S_2/R FORMAT (4E10.4)

CARD 3: γ_{c} , M^{*}_{lc} , ψ_{lc} FORMAT (3E10.4)

CARD 4: γ_b , M*_{1b}, ψ_{1b} FORMAT (3E10.4)

The meanings of the symbols in the input statement are:

M-INF (M_): Free stream Mach number.

DELTA-1 (δ_1) : Two-dimensional wedge angle, (deg.)

R (r):
 y distance of the wedge vertex from the cone
 vertex, normalized in any convenient manner,
 (Figure 38).

Q (q): Normalized z distance of the wedge vertex from the cone vertex.

DELTA-Z ($\Delta z'$): Step size in z' for determining intersection curve.

GAMMA $(\bar{\gamma})$: Ratio of specific heats.

PC/P-INF (p_{c}/p_{m}) : Pressure ratio behind conical shock.

PB/P-INF (p_h/p_{ω}) :Pressure ratio at cone surface.

TC/T-INF (T/T $_{\infty}$):Temperature ratio behind conical shock.

S2/R (S_2/R): Entropy increase across conical shock, normalized with respect to the universal gas constant.

GAMMA (γ_c, γ_b) : Conical shock and cone angles, respectively, (radians).

M1-STAR (M* lc, M*): Critical Mach numbers behind conical shock and on cone, respectively.

PSI-1(ψ_{lc} , ψ_{lb}): Flow deviation behind conical shock and on cone, respectively, (radians).

Output

The output consists of many parts. The first includes some quantities in the two-dimensional and conical fields, which are independent of the shock intersection. Second, are tables describing the intersection curve of the plane and conical shocks, and the flow conditions ahead and behind the modified plane shock near the intersection. Next, the reflection curve of the modified plane shock on the cone surface is described, along with the flow conditions in front and behind this shock near the body. Finally, the conditions behind the reflected shock on the cone surface are given. The characteristic subroutine is included in the program and its output is described in Appendix V-2.

The meanings of the symbols in the output are:

GAMMA-C (γ_c) : Cone shock angle, (radians).

MR (M_r): Mach number component behind the conical shock, parallel to the shock.

MT (M_t): Mach number component behind the conical shock, normal to the shock.

M-1 (M_1): Mach number behind the two-dimensional shock.

THETA-1 (θ_1) : Two-dimensional shock angle, with respect to the free stream direction, (radians).

 $Pl/P-INF(p_1/p_m)$: Pressure jump across two-dimensional shock.

Al/A-INF(a_1/a_∞): Speed of sound increase across two-dimensional shock.

ZP (z'_i): Normalized z' coordinate of point on twodimensional and conical shock intersection, on plane of two-dimensional shock.

XP (x'_i): Normalized x' coordinate of point on shock intersection curve.

OMEGA (Ω_i): Angle between the tangent to the intersection curve and the z' axes. The computation of the curve terminates when $\Omega_i < 5^\circ$, (radians).

M2XP (M₂): Mach number component in x' direction, behind conical shock.

M2YP (M₂): Mach number component in y' direction, behind conical shock.

M2ZP(M₂): Mach number component in z' direction, behind conical shock.

M2NP (M₂): Mach number component normal to the intersection curve in the plane of the two-dimensional shock, behind the conical shock.

M2TP (M₂): Mach number component tangent to the intersection curve, behind the conical shock. M2KN (M₂): Total Mach number component in a plane normal to the intersection curve, behind the conical shock.

DELTA (2): Flow deviation behind conical shock with respect to plane of two-dimensional shock, in a plane normal to the intersection. (First term of Eq. 138), (radians).

OMEGA-STAR: $\pi/2-\Omega_i$, (radians).

GAMMA: Free stream flow deviation with respect to the plane of the two-dimensional shock, in a plane normal to the intersection curve. (Second term of equation 138), (radians).

DELTA(2)STAR(6*2i):Strength of the conical shock in a plane normal to the intersection curve, (radians).

DELTA (1): Flow deviation behind two-dimensional shock with respect to two-dimensional shock plane, in a plane normal to the intersection curve. (Second term of equation 135) (radians).

DELTA(1)STAR(δ_1^*):Strength of the plane shock in a plane normal i to the intersection curve, (radians).

 $P4/P2(p_4/p_2)_i$: Pressure jump across modified plane shock.

A4/A2(a₄/a₂)_i: Speed of sound increases across modified plane shock.

M4N (M₄): Mach number component in a plane normal to the intersection curve, in the lower intersection region.

THETA(4) (A_{4i}): Modified plane shock angle behind intersection, with respect to upstream conical flow direction, in a plane normal to the intersection curve, (radians).

M4T (M₄): Mach number component tanget to the intersection curve, in the lower intersection region. M4 (M₄): Total Mach number in the lower intersection region.

P4/P-INF(p_4/p_{∞})_i :Pressure ratio in the lower intersection region.

A4/A-INF(a₄/a_{∞}): Speed of sound ratio in the lower intersection region.

SIGMA(4)(σ_4): Flow deviation in the lower intersection region with respect to the z'-axes, (radians).

THETAP(4) (A'₄): Lower shock angle with respect to the ζ axes, i Figure 39, (radians).

S4 (S₄): Entropy increase from free stream, in the lower intersection region, normalized by twice the specific heat at constant pressure.

GAMMA(K) (γ_h) : Conical body half angle, (radians).

I (i): Shock - conical body intersection points.

ETA (η_i): Normalized coordinate, normal to plane of the two-dimensional shock, of intersection point of modified plane shock and conical body, (Figure 39).

X (x): Normalized x coordinate of intersection point.

Y (y i): Normalized y coordinate of intersection point.

Z (z): Normalized z coordinate of intersection
point.

RHO (ρ_i) : Normalized radial, conical coordinate of intersection point, (Figure 40).

PHI (φ_i) : Meridian, conical coordinate of intersection point, (radians).

CHECK: Checks if x_i , y_i , z_i , lie on the conical body $(x_{i_1}^2 + y_{i_1}^2) - (\tan v_b)^2 z_{i_1}^2 = 0$)

THREE POINT I=a, I=b, I=c: Intersection points

SELECTION:

chosen for determining reflection curve.

(The program presently uses I=1, I=4
I=10).

RHO-0,RHO-1,RHO-2, Normalized coordinates of the three sel-(ρ_0 , ρ_1 , ρ_2): ected points.

PHI-1, PHI-2, Cooordinates of last two selected points. (φ_1, φ_2) : The coordinate $\varphi_0 = 0$, (radians).

COS(TX) ($\cos(tx)_i$): Direction cosine of tangent to reflection curve and x axes.

COS(TY)(cos(ty)):Direction cosine of tangent to reflection curve and y axes.

COS(TZ) (cos(fz); Direction cosine of tangent to reflection curve and z axes.

COS(BX) $(\cos(bx)_i)$: Direction cosine of binormal to reflection curve and x axes.

COS(BY) ($\cos(by)_i$):Direction cosine of binormal to reflection curve and y axes.

COS(BZ)($\cos(\hat{bz})_i$):Direction cosine of binormal to reflection curve and z axes.

COS(NX) (cos($\stackrel{\wedge}{nx}$); Direction cosine of normal to reflection curve and x axes.

COS(NY)(cos(ny);):Direction cosine of normal to reflection curve and y axes.

COS(NZ)($\cos(nz)$): Direction cosine of normal to reflection curve and z axes.

M2XP(M₂): Mach number component, in x' direction, on conical surface.

M2YP(M₂): Mach number component, in y' direction, on onical surface.

M2ZP(M₂): Mach number component, in z' direction, on conical surface.

M2T(M₂): Mach number component tangent to intersection curve, on conical surface.

M2N(M₂): Mach number component normal to intersection curve, on conical surface.

M2KN(M $_2$ N $_{\rm bi}$ Total Mach number component in a plane normal to the intersection curve, on the conical body.

 $P4/P2(p_4/p_2)_{bi}$: Pressure jump across the modified plane shock near the cone.

A4/A2(a₄/a₂)_{bi}: Speed of sound increase across the modified plane shock near the cone.

M4CN(M₄): Total Mach number component in a plane normal to the intersection curve, in front of the reflected shock, near the cone.

THETA(4)(θ_4): Modified plane shock angle near the cone, with respect to the direction of M_2 , (radians).

S4(S₄): Total entropy change behind the modified plane shock near the cone, normalized by twice the specific heat at constant pressure.

M4T(M₄):
Mach number component tangent to the intersection curve, in front of the reflected
shock, near the cone.

M4N(M₄): Mach number component along normal to intersection curve, in front of reflected shock, near the cone.

M4B(M₄): Mach number component along binormal to intersection curve, in front of reflected shock, near the cone.

M4TB(M₄₋): Mach number component tangent to the reflection curve, in front of the reflected shock, near the cone.

M4MB(M₄₋): Mach number component along the normal to the reflection curve, in front of the reflected shock, near the cone.

Mach number component along the binormal to the reflection curve, in front of the reflected shock near the cone.

DELTA-4(δ_4): Flow deflection across the reflected shock in a plane normal to the reflection curve, (radians).

M4KN(M₄₋): Total Mach number component in a plane normal to the reflection curve, in front of the reflected shock.

THETAP-6(θ'_6): Reflected shock angle with respect to the cone surface, in a plane normal to the reflection curve (radians).

 $P6/P4(p_6/p_4)_i$: Pressure jump across reflected shock on cone surface.

A6/A4(a_6/a_4): Speed of sound increase across the reflected shock on cone surface.

M6N(M₆): Total surface Mach number component in a plane normal to the reflection curve behind the reflected shock.

M6T(M₆ $_{\dot{t}}$): Surface Mach number component tangent to the reflection curve, behind the reflected shock.

P6/P-INF(p_6/p_{∞}); Pressure ratio on cone surface behind reflected shock.

SIGMA-6(σ_6): Surface flow deviation behind the reflected shock, with respect to the β axes.

S6(S₆): Total surface entropy change behind the reflected shock, normalized by twice the specific heat at constant pressure.

APPENDIX VI

(SAMPLE PROBLEMS - THREE-DIMENSIONAL)

1. Wedge Program Example

To illustrate the use of the wedge program a particular example was carried out for the following input data:

 $\chi = 55 \text{ deg.}$

 $M_{-} = 4.23$

 $\lambda = 8 \text{ deg.}$

 $\alpha = 0$

 $\Delta z = 0.05$

All lengths have been normalized with respect to r by inputting r=1. The program output is included in this appendix and the symbols are defined in Appendix V-1.

Each set of non-dimensionalized coordinates x and z represent a point on the intersection curve of the shock on the plane surface. However, if the ratio x/z is considered the variation of flow conditions on the wedge surface is determined. Each set of conditions, i, corresponds to the flow on a ray on the base plane of the wedge passing through the wedge vertex and making a angle $tan^{-1}(x/z)$; with the z axes. Due to the assumption of linear theory the flow on the wedge surface is the same as that on the base plane of the wedge. The last set of conditions (i = 22) corresponds to those on the edge of the local Mach cone and therefore also to the constant conditions in the two-dimensional region. Note that the step size has been reduced by a factor of 5 for the last set of points in order to approach the two-dimensional values more closely. Figure 43 presence the variation of Mach number, pressure ratio and flow deviation across the wedge surface. Only half the wedge is shown due to its symmetry.

These conditions are also valid in front of the reflected shock. The strength of the reflected shock at any point i on the intersection curve depends on the upstream Mach number in a plane normal to the intersection curve at that point and on the

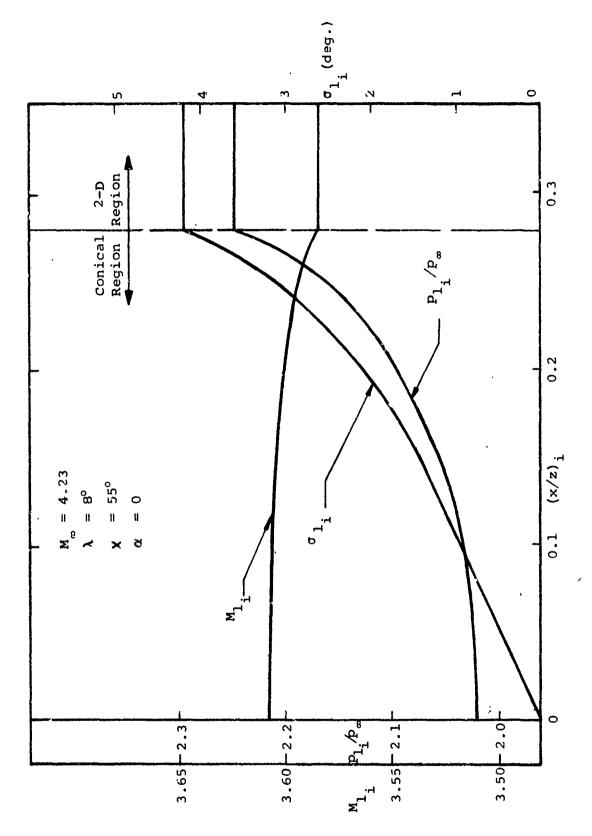
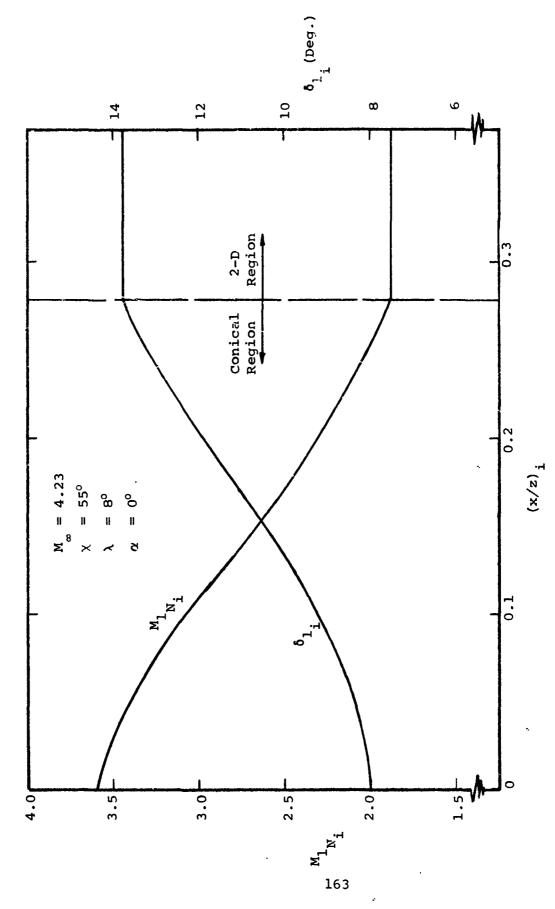


FIGURE 43 - WEDGE SURFACE CONDITIONS

deflection of the flow necessary to turn the flow parallel These quantities are plotted for each to the plane surface. point on the intersection curve i.. Figure 43. one would expect that the shock strength would decrease as points further and further from the z axes are considered since the normal Mach number decreases. However, it is also necessary to consider the fact that the flow deflection increases as the two-dimensional region is approached. fore, the shock strength may increase or decrease depending on the relative effects of these two quantities. It is also possible that as the two-dimensional region is approached the required deflection will become too large for the corresponding normal Mach number, resulting in a Mach reflection. This did not occur in this example but would result in a program stop as described in Appendix V.

The conditions immediately behind the intersection curve on the plane surface are plotted in Figure 45. Figures 44 and 45 do not represent a cross section, but points on the intersection curve (Figure 30 of the main text). It can be seen that the shock strength decreases a little and then increases as the intersection curve is traversed from the z axes to the two-dimensional region. It should be noted that the values of θ_{2n_1} can be used to construct the reflected shock. In particular θ_{2n_1} is the angle between the reflected shock and the z axes in the y-z plane.



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FIGURE 44 - CONDITIONS AFFECTING RFTLECTED SHOCK STRENGTH

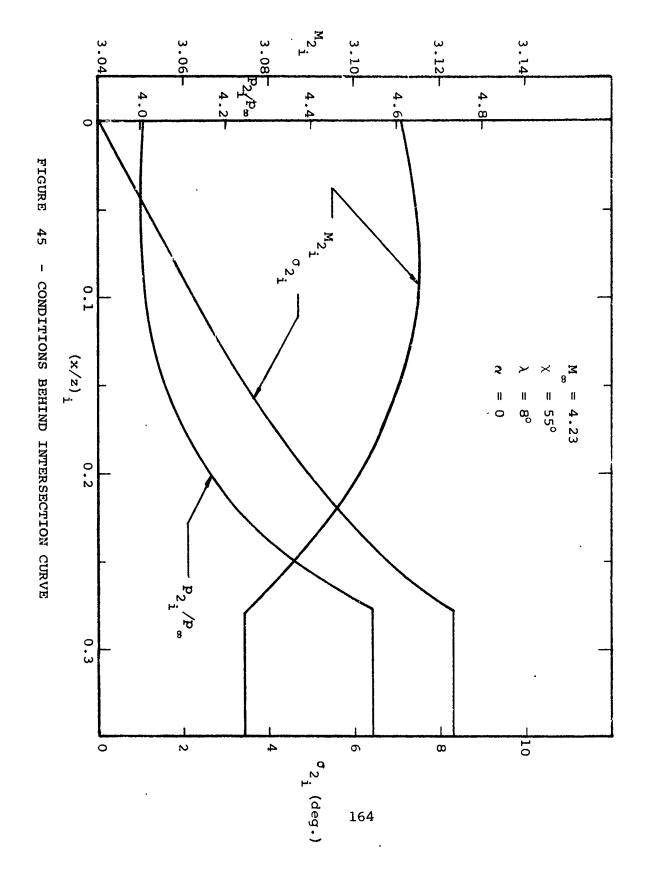


TABLE IV - SAMPL SOUTPUT - SWEPT WEDGE

2. Conical Shock-Plane surface Program Example

This program was run together with the characteristic subroutine program for the following input data.

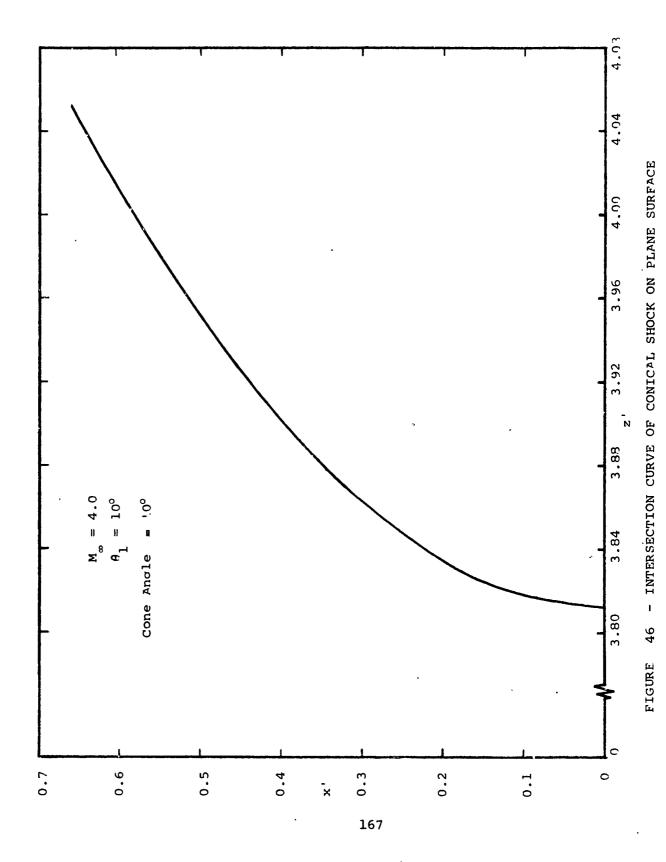
$$M_{\infty} = 4.0$$
 $\theta_{1} = 10 \text{ deg.}$
 $\gamma_{c} = 0.30918 \text{ rad.} (10 \text{ deg. cone})$
 $\overline{\gamma} \cdot = 1.4$
 $r = 2.5$
 $q = 2.0$
 $\Delta z = 0.01$
 $p_{c}/p_{\infty} = 1.562$
 $M_{1c}^{*} = 2.09123$
 $\psi_{1c} = 0.0803353 \text{ rad.}$
 $s_{2}/R = 0.089929$

This program output is included in the appendix and the symbols are defined in Appendix V.2.

Corresponding to each value of i, the set of coordinates x' and z' represent a point on the reflection curve of the conical shock from the plane surface. This curve also represents the data line for the characteristic subroutine and is shown in Figure 46. The curve is terminated after computing a maximum number of 25 points. If it is necessary to find the flow further out on the curve the step size, Δz , would have to be increased. If a large enough step size were used the reflection curve computation would terminate either at a Mach reflection or when the slope of the curve with respect to the z' axes becomes 5° or less.

The variation of the reflected shock strength can be determined from Figure 47 where the total upstream Mach number component in a plane normal to the reflection curve (M) and $^2{\rm N}$

and the flow deflection necessary to turn the flow parallel to the plane surface (δ_2) are plotted vs. the slope



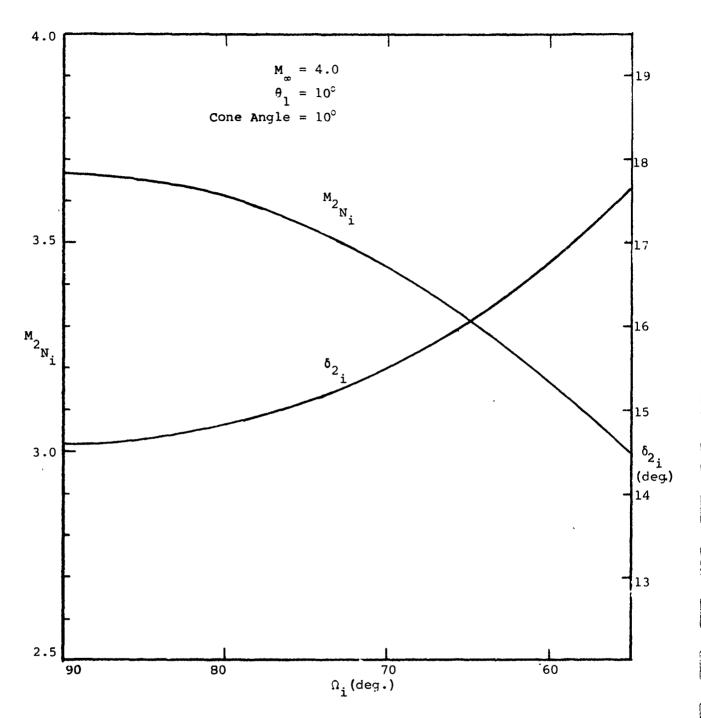


FIGURE 47 - CONDITIONS AFFECTING STRENGTH OF REFLECTED CONICAL SHOCK

of the reflection curve $\Omega_{\bf i}$. The effect of these parameters is described in Appendix VI.1 where it is also pointed out that this figure does not represent a cross-section but points along the reflection curve.

The conditions on the plane surface behind the reflection are given in Figure 48. The first part of the figure shows the pressure and Mach number variations immediately behind the reflection curve. It can be seen that a Mach relection must occur quite soon since the pressure is increasing so rapidly. The second part of the figure shows the variation of the pressure along the line of symmetry (ρ or z' axes) on the plane surface as obtained from the characteristic subroutine program.

Something should be said here about the output of the characteristic subroutine. The first page gives the value of the pressure behind the reflection curve on the centerline and the flow conditions along the reflection curve, which is now called the data line. The data is given in reverse order, i.e., the point furthest out on the curve is listed first and the centerline point is given last. The next page gives the conditions along the second family characteristic line closest to the centerline data point. This line is designated by the value of i, and the value of p/p given at the top is the pressure ratio at the intersection of this second family characteristic line and the centerline (wall). The procedure continues until the second family line from the data point furtherst out on the reflection curve has been considered.

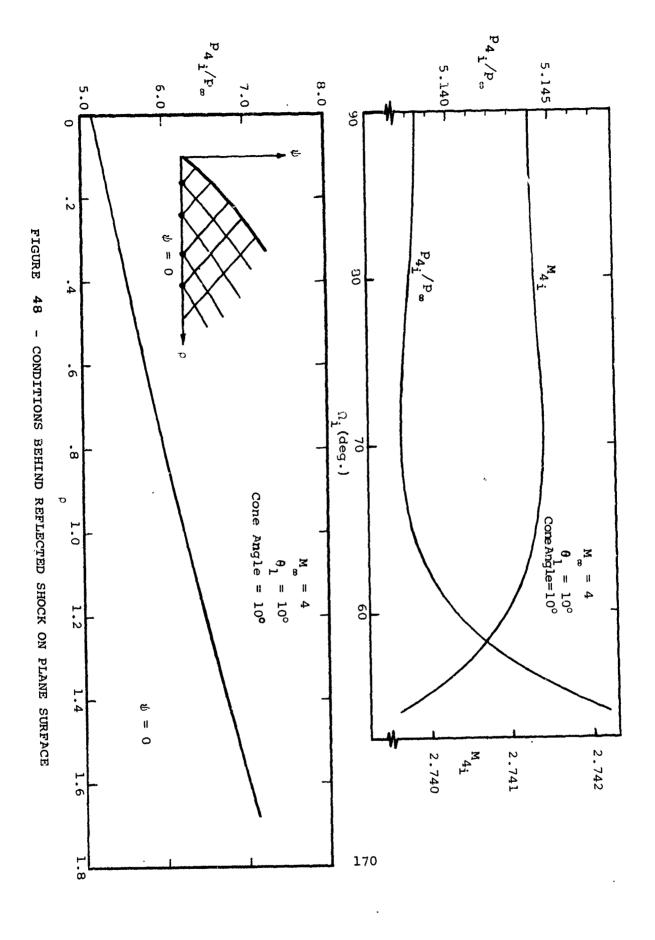


TABLE V - SAMPLE OUTFUT FOR CONICAL SHOCK - PLANE BODY PROGRAM CUNICAL SHULK - PLANE BOUY

33				•																																						
1.562000E CU 8.U3353ue-U2	M2N		3.547845E 00		3.465517E 00		-								3.095001E 00	3.0001000000			00 3696096°					2513E JU	-	À-4		** 946572F-01	5-00567et-01	5.064259E-01	5-1223436-01	5.1799496-01	5.2038036-01	5.350088E-01	5.405968t-01	5.46146UL-0}	5.516>79E-01	5.4257405-01	5-6798516-01	5.733627E-01	5.7871026-01	5.840287E-01 5.893197E-01
PC/P-INF= 1. PSI= 8.	•			•	•												•		. ~	. ~	~	•	2.865	2.8425135	2.820	THE TA-4	ò	000	5-005	5.064	5.122	5.179	5.002	5,350	5.405	5.461	5.516	7.6.6	5.679	5.733	5.787	5.840
	d 3				200,000			•						100 00										343E 00	373E 00	I		122F 00				48E 00	_	-	-	_	96E 00		_	_		93E 00
2.091230E 00 1.000000E-02	M24P		3.5478436	100674696	3.3461136	3.5483845	3.54851BE	3.548021E	3.5487835	3.5489165	3.549048£	. 3.549179E	3.549310E	3.04744CT	3.3493716	3.5491000	3.54005R	3.5500876	3.550214E	3-550342E	3.550469E	3.550596	3.5507226	3.5>08435	3.550973E	ž	,	2.704322F	2.668557E	2.633895E	2.600277E	2.567648E	7.5051536	2.475196E	2.446043E	2.417655E	2.389996E	2.3050335	2.311065E	2.286004E	2.261521E	2.237593E 2.214196E
M1-STAR* 2,091230E DELTA-2* 1,009000E	MZYR		7.54466404	10-318966764	94228004E-01	91212768F-01	9.205189E-01	9-197636E-01	9.1901081-01	9.182606E-C1	9,175129E-01	9-167677E-01	9,160250E-01	10-38#87C1 %	70-311464146	0-130110E-01	9-1234HZE-01	9-1:6207F-01	9+108952E-01	9-101721E-01	9-0945146-01	9-0873305-01	9.0801716-01	9.0730351-01	9.0659226-01	A4/A2	00 100000	1.213915E 00				1.213889E 00					1,213928E 00			-		1.214057E 00 1.214100E 00
2.500000E 00 2.000000E 00	M2KP	•	0.	20-3661747-2	3.023478E-02	4-2029#4F-02	4.758940E-02	5.205324E-02	5.613959E-02	5.9925666-02	6.346590E-02	6.679920E-02	20-3777777	7 5 2 3 5 2 5 5 5 7	7 3550415-12	4-120045C-02	3.374647F-02	8-619658E-07	8.4565156-02	9.045852E-02	9.308232E-02	9.5241535-02	9.1340536-02	9.9383836-02	1.0137316-01	P4/P2	3 1464776 00	3.289506E 00				3.2891585 00					3.259681E 00			_		3.291549E 00 3.291999E 00
1.0000 JOE 01 K= 3.091 800 E - 01 U=	UNEGA	00 5 00 00	1.3701962 00		1.4181785 00		_			1.172872E JO			1.113543E 00	00 3515000-1						٠	9.8736856-01	9.763617E-U1	9.057d75E-J1	*.550150E-J1	5.456185E-01	UELTA-2	0 1684436 11	2.575747E-01	2.602420E-01	2.0287156-01	2.6546435-01	2.70544.2E=01	2.730334E-01	2.75+90CE-01	2.779150c-ul	2.893693E-01	2.826/36E-UI	2.873156E-01	2-895947E-01	2.9184695-01	2.940726E-01	-964131E-UL -984483E-01
THL TA-)= 1. GAMMA-C= 3.	d	-	1 4444346-01	10-3377636-1	1.4217125-01	Z-081395F-01	2.998402£-01	3.235204E-01	3.2491926-01	3. 19497ut-01	4.325943E-01	10-3876447	10-355-55+4	10-357*166**	10-1426-136-1	3, 70,34,751-01	10-3560675-01	3.3415BLE-01	5.7333556-01	3.43U725t-u1	5.014121E-01	% . losal2t-01	0.310063E-01	0.4531cot-01	0.543150t-01	42KiN	00 322 500					3.4.3904E 00	_				3.284137E UU					3.122441E 00 3.097688E 00
m=144 = 4.6000c0E 30 vAdha= 1.40)c5CE 32 s2/K= 3.5?2500E-32	47		J. 1221216 00						30m 35 127E Ju		•		00 1/01/10								4.0121276 00	4. 1221212 JU			4. 136127E 30	17W	7 - 100 3 100 1	-5-4475696-01	-1.0172516-01	.220491t-	., 55 107E	-1.1028/51 03	3314240 .	304036	.532.410c	177-10c.	-1.029737E 00	1352281	. 105254E			-1.46/144 (00
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110 110 110 110 110 110 110 110 110 110		20 21 22 23 24 25
-1.041253c 03 -1.113275c 03 -1.173575 00 -1.237.736 00 -1.342531c 00 -1.43283246 00 -1.473859c 00 -1.546746 00 -1.546746 00 -1.546746 00 -1.546746 00 -1.5766156 00 -1.7766156 00 -1.776650c 00	#4T 1.277591E-C7 -4.487570E-01 -6.275371C-01 -7.007119E-01 -8.082050E-01	-1.936113E 00 -2.033595E 00 -2.067382E 00 -2.057382E 00 -2.130379E 00 -2.159312E 00
2.741401E 00 2.741391E 00 2.741334E 00 2.741304E 00 2.741254E 00 2.7411254E 00 2.7411254E 00 2.7411254E 00 2.741042E 00 2.740950F 00		3.00/3945E 00 3.000/545E 00 3.002/793E 00 3.005/538E 00 2.98340:E 00 2.98360:E 00
5.137602E JO 5.137714c OO 5.137984E OO 5.138205E JO 5.138462E JO 5.138213E OO 5.139213E OO 5.140183E OO 5.142102E OO 5.142102E OO 5.142102E OO 5.142102E OO 5.142102E OO 5.142506E OO 5.145568E OO 5.145601E OO 5.146604E OO 5.146604E OO		3.005991E-01 3.027259E-01 3.048296E-01 3.069102E-01 3.110051E-01
-4.013690E-02 -4.338397E-02 -4.641349E-02 -5.197095E-02 -5.455061E-02 -5.702225E-02 -5.939969E-02 -6.169409E-02 -6.816415E-02 -7.020520E-02 -7.219722E-02 -7.414439E-02 -7.414438E-02 -7.791880E-02 -7.975226E-02 -8.155356E-02	\$16#A-4 4.660606E-08 -1.633115E-02 -2.311048E-02 -2.932288E-02 -3.272630E-02 -3.661413E-02	3.29249/E UU 3.293023E QU 3.293599E QO 3.294218E QO 3.294881E QO 3.295588E QO
2.531654 t=01 2.5595188 t=01 2.658367 t=01 2.658367 t=01 2.658367 t=01 2.658367 t=01 2.7521634 t=01 2.7521634 t=01 2.7521634 t=01 2.7521634 t=01 2.752163 t=01	THETA-P-4 2,336244E-01 2,370826E-01 2,403256E-01 2,453700E-01 2,499734E-01	1.214137E 00 1.214176E 00 1.214219E 00 1.214265E 00 1.214314E 00 1.214366E 00
3.658620E-02 3.658801E-02 3.65987E-02 3.6599351E-02 3.6599351E-02 3.6599351E-02 3.6699591E-02 3.66997E-02 3.660897E-02 3.662862E-02 3.664532E-02 3.664532E-02 3.665477E-02 3.667999E-02 3.667999E-02 3.667999E-02 3.667999E-02	S 3.659544E-02 3.65924JE-02 3.658997E-02 3.658812E-02 3.658687E-02 3.658623E-02	2.191307E 00 2.168905E 00 2.146972E 00 2.125487E 00 2.104433E 00 2.083794E 00
		5.945844E-01 5.998237E-01 6.050390E-01 6.102314E-01 6.154019E-01 6.205517E-01

TABLE V (Cont'd)

CHARACTERISTICS PROGRAM

	3	7.74709E-01	7.747316-01	7.74752E-01	7.74772E-01	7.74790E-01	7.7*807E-01	7.74822E-01	7.74836E-01	7.748496-01	7.74861E-01	7.74871E-01	7.74880E-01	7.74888E-01	7.74895E-01	7.74901E-01	7.74905E-01	7.74909E-01	7.74911E-01.	7.749126-21	7.74912E-01	7.74911E-01	7.74908E-01	7.74985E-01	7.74901E-01	7.74895E-01
	, T	3.73650E-01	3.736224-61	3.73595E-01	3.73571E-01	3.73548E-01	3.73526E-01	3.73507E-01	3.73489E-01	3.734721-01	3.73458E-01	3.73445E-01	3.73433E-01	3.73423E-01	3.734146-01	3.73407E-01	3.73402E-01	3.733976-01	3.73395£-01	3.73393E-01	3.73393E-01	3.73395E-01	3.733981-01	3.73402E-01	3.73407E+01	3.734145-101
	z	2.73961E OC	_	٠.	2-74010£ 00			2-740612 00	2.74073" 46		2.74095- 00	2.74104E 00	-	2-741196 00	2.74125E 00		-	-	2.74139E 00	2.74140E 00		_	2474137E 00	2.74134E 00	2.74130E 00	2.74126E 00
.400 P/P= 5.138	s	3.57003E-02	3.668775-02	3.66760E-02	3.66650E-02	3.66548E-02	3.6045JE-02	3.6636E-02	3.66286E-02	3.60214E-02	3.661.8 72	3.66090E-02	3.66038E-02	3.65993E-02	3.65955E-02	3.65924E-02	3.658995-02	3.65480E-02	3.65868E-02	3.65862E-02	3.65862E-02	3.65869E-02	3.65881E-02	3.65900E-02	3.65924E-02	3.65954E-02
6AMMA= 1.400	THEIA	-8.15536E-02	-1.975235-02	-7.79188E-02	-7.00505E-02	-7.41444E-02	-7.21972E-02	-1.023525-02	-6.81641E-02	-6.00692E-02	-6.39147E-02	-6.16941E-02	-5.93997E-02	-5.7u223E-02	-5.455Uot-U2	-5-197C9E-02	-4.92663E-02	-4.04135E-02	-4.33840E-02	-4.013695-07	-3.661416-02	-3.27263E-02	-2.83229E-02	-2.31105E-02	-1.03312t-02	• 0
	Psi	0.5 4315E-01	0.453116-01	6.310066-01	6.10381E-01	0.01412E-01	3.30073E-U1	5,733336-01	5.J4158E-01	5.37510t-01	5.203+36-01	5.026035-01	4.84228t-J1	4.65142E-01	4.45255E-UI	4.2%45 3E-C1	4.02544-01	3.744972-01	3,54919E-01	3,28528E-01	2.95847E-01	2.631.06-01	2.321716-01	1.895316-01	1.339926-01	0.
	krdU	2.400032-31	2.37000E-01	2.230 00E-01	2.13000E-01	()'Juć-01	1 4 7-305-01	1.630006-01	1.730006-01	1.6330006-01	1.5000c-01	1.433006-01	1.336901-01	1.2) June-01	1.1 300 35-01	1.0320CE-01	3.C300CE-C2	3.00006-02	7.0 10000-02	6.(3003E-02	5.C)3000E-04	4.()0000E-02	3.0 J. COE-02	2.030c0E-02	1.03 JevE-32	;
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1.33992E-01 -1.63312E-02 6.73966E-02 -8.15930E-03 0. I= 24 P/P-INF= 5.49350E 00 THETA S 3.65924E-02 3.65939E-02 3.65954E-02 3.73407E-01 3.76562E-01 3.79740E-01 ₹ 7.74901E-01 7.72412E-01 7.69911E-01

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3	7.74905e-01 7.73873e-01 7.71377e-01 7.68870E-01 7.67826E-01
₹	3,73402E-01 3,74709E-01 3,71870E-01 3,81066E-01
5.64639E 00 S	3.65900E-02 3.65911E-02 3.65930E-02 3.65947E-02
I= 2? P/P-INF= 5.64639E 00 THETA S	-2.31105E-02 -1.97158E-02 -1.15439E-02 -3.38465E-03 0.
: 1	1.89531E-01 1.62125E-01 9.56047E-02 2.8238UE-02 0.
ини	2.00000E-02 8.50+65E-02 2.46594E-01 4.11920E-01
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5. y013¢E-01	5.36309E-01	4.67045E-01	3.03507E-01	1.443036-01	7.9466dE-02	3.00006-02	Ġ.
0•	, 2.18245E-02	5.00573E-02	1.17387E-01	1.83837E-01	2.112036-01	2.321716-01	15d
c.	-2.60242E-03	-5.987056-03	-1.41463e-02	-2.231816-02	-2.57128E-02	-2.832296-02	I= 22 P/F-INF= 5.76624E 00 THETA S
3.65954E-02	3.65949E-02	3.659416-02	J-65923E-02	3.65901E-02	3.65890E-02	3.65881E-02	= 5.76624E 00 S
3.84455E-01	3.83425c-01	3.82089E-01	3.788 + 9E-01	3.75714E-01	3.74402E-01	3.73398E-01	₹.
7,66215E-01	7.670225-01	7.680b8E-01	7.705806-01	7-73080E-01	7.74115E-01	7.749086-01	X.

7.74911E-61 7.74241E-01 7.73446E-01 7.73446E-01 7.67346E-01 7.67389E-01 7.65341E-01 7.65533E-01 3.73395E-01 3.75243E-01 3.75260E-01 3.75564E-01 3.7554E-01 3.8295E-01 3.84295E-01 3.85328E-01 ₹ 3.65869E-02 3.65874E-02 3.65893E-02 3.65893E-02 3.65936E-02 3.65936E-02 3.65936E-02 P/P-1NF= 5.86909E 00 THETA S TABLE 7 (Cont'd) -3.27254-02 -3.05220E-02 -2.79120E-02 -2.45173E-02 -1.63494E-02 -8.18620E-03 -2.19920E-03 71 <u>"</u> 2.68340E-01 2.50492E-01 2.29563C-01 2.02233E-01 1.35852E-01 6.85010E-02 4.03360E-02 1.85142E-02 154 4.0300E-02 8.10976E-02 1.53075E-01 1.94336E-01 5.13992E-01 5.1395E-01 7.35978E-01 6.35978E-01 111240013

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7.61933E-01 Q.			6.23822E-01 5.67347E-02							5.00000E-02 2.99847E-01	ISd OHY
0.	-1.94253E-03	_	-6.74410E-03							-3.06141E-02	I= 20
3-65954E-02	3.65950E-02	3.65944E-02	3-65938E-02	3.65930E-02	3.65909E-02	3.65886E-02	3.65876E-02	3165870E-02	3,65865E-02	3.65862E-02	5.96115E 00 S
3.87755E-01	3.86978E-01	3.86100E-01	3.85065E-01	3.83723E-01	3.80508E-01	3.77318E-01	3.76001E-01	3.74992E-01	3.74142E-01	3.733936-01	ŧ
7.63640E-01	7.64245E-01	7.64930E-01	7-657396-01	7.66788E-01	7.69308E-01	7.718164-01	7.72854E-01	7.73650E-01	7.74321E-01	7.74912E-01	π

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3	3.7393E-01 3.74071E-01 3.76672E-01 3.76683E-01 3.84602E-01 3.8462E-01 3.68765E-01 3.88765E-01 3.89167E-01	1 1 1 1 1
6.04562E 00	3.65862E-02 3.65864E-02 3.65864E-02 3.6587E-02 3.65812E-02 3.65904E-02 3.65936E-02 3.65946E-02 3.65946E-02	
I= 19 P/P-INF# 6.04562E 00 IHETA 5	-4.01309b-02 -3.83754E+02 -3.64302b-02 -3.42259E-02 -2.8211E-02 -2.00493E-02 -1.18901E-02 -5.90395E-03 -5.90395E-03 -5.90395E-03	
i) ISd	3.28528E UL 3.14517E-01 2.99024E-01 2.81437E-01 2.550558E-01 2.55058E-01 2.55058E-01 2.55058E-01 1.67047E-01 1.64916E-02 7.16353E-02 4.98235E-02 1.49103E-02 0.	,
AHD.	6.000006-02 9.197526-02 1.274426-01 1.678436-01 2.159996-01 2.791966-01 4.342726-01 6.937736-01 7.934926-01 7.944926-01 7.944926-01	

	RHO .	PS4 #4	I= 18 P/8-ENF=	P/P-ENF= 6.12433E 80	8	£
	7.00000E-02	3454919E-01	-4-33840E-02	3.65868E-02	3.73395E-01	10-3116+2FE
	9.91151E-02	3-42047E-01	-4-17617E-02	31658652-02	3134018E-01	7-74418E-01
	1.30846E-01	3-28-586-01	-4.00002E+02	3.66864E-02	10-3169421E	7473882E-01
	1.66043E-01	3-12598E-01	-3.80549E-02	3-65864E-02	3.75448E-01	7-73290E-01
	2.061415-01	2195025E-01	-3.56507E-02	3165865E-02	3-76301E-01	2.72617E-01
	2.53938E-01	2-74174E-01	-3-32407E-02	31 66 869 E-02	TO-3ETERLTE	7,71820E-01
•	3.16669E-01	2-46945E-01		3165836E-02	3+78635E-01	7.70780E-01
	4.70630E-01	1-80760E-01		3.65898E-02	3.81837E-01	7.68265E-01
	6.29025E-01	1-13596E-01		3+65920E-02	3.850046-01	7-65739E-01
	6.96164E-01	8.54028E-02		3.65929€-02	3186412E-01	7-64687E-01
	7.48355E-01	4-35974E-02	-7.52784E-03	3.659345-02	3+87451E-01	7-63876E-01
	7.92828E-01	4450915E-02	-5.32870E-03	3.65941E-02	3.88332E-01	7-63190E-01
	8.32382E-01	2-86901E-02	-3.38618E-03	3.65946E-02	31891125-01	7-62583E-01
	8.68451E-01	1.37807E-02	-I.62481E-03	3.65950E-02	3189820E-01	7-62031E-01
	9.01884E-01	0.	0.	3.65954E-02	3.90475E-01	7-61522E-01

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	3	14/4909E-01	7.74449E-01	3-73956E-01	F.73420E-01	2472827E-01	7-72154E-01	7-71355E-01	7470314E-01	7.67797E-01	3465268E-01	E464745E-01	\$163403E-01	7162716E-01	7.62108E-01	Z-61556E-01	7161046E-01	1-60570E-01
	3	34 73397E-02	3173979E-01	3.24603E-101	3.75283E+01	3.76035E-01	3.76889E-01	3.78903E-01	3.79227F-01	31824356-01	318%67E-01	3187017E-01	3.68058E-01	31859405-01	3189721E-01	31904315+01	319E088E+01	3.91701E-01
6119865E 00	vo	3.65880E-02	3465875E-02	3.45841E-02	3.65867E-02	3.65866E-02	3.65865E-02	3465867E-02	3.55873E-02	3.65894E-02	3465916E-02	3.65925E-02	3.65931E-02	3.66937E-02	3165942E-02	3.65946E-02	3.65951E-02	3.65954E-02
(= 17 0/8-1NF= 6.19865E 00	THETA	-4.64135E-02	-4.49012E+02	-4.32790E-02	-4.15176E-02	-3.95722E-02	-3. 73 680 E-02	-3.47580E-02	-3.13633E-02	-2.319146-02	-1.50322E-02	-1-16476E-02	-9.04517E+03	-6.84601E-03	-4.90351E-03	-3.14211E-03	-1.51734E-03	•0
	P51	3.79497E-01	3.67525E-01	3,546736-01	3.40704E-01	3.25257E-01	3.07718E-01	2.86894E-01	2.59697E-01	1.93576E-01	1.254556-01	9.82745ë- U2	7.64762E-U2	5.79748E-02	4.15761E-02	2-66683E-02	1.28884E-02	•0
	OHX OHX	8.00000E-02	1.06857E-01	1.35762E-01	1.67265E-01	2.022126-01	2.42026E-01	2.89489E-01	3.51786E-01	5.04709E-01	6.62073E-01	7.28786E-01	7.80649E-01	8.24846E-01	8.64157E-01	9.00006E-01	9.33237E-01	9.54400E-01

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1.00000E-01	4.24453E-01	-5.19709t-02	3.65924E-02	3. 73407E-01	7.74901E-01
1.234805-01	4.138276-01	-5.06236E-0Z	3.65913E-02	3173925E-01	7.744926-01
I.48331E-01	4.02607E-01	-4.92012E+62	3.65903E-02	31744725-01	7.74060E-U1
1.74828E-01	3.90672E-01	-4.76890E-02	3.65894E-02	3175054E-01	7.73600E-01
2.033495-01	3.77858E-01	-4.60667E-02	3.65887E-02	3475681E-01	7-73106E-01
2.34436E-01	3.639316-01	-4.43053E-02	3.65880E-02	3. 76362E-01	7-72569E-01
2.649246-01	3.48526E-01	-4.23600E-02	3.65874E-02	3.77126E-01	1-119756-01
3.08220E-01	3.31034E-01	-4.01557E-02	3.65870E02	31789735-01	7-71301E-01
3.55070E-01	3.10262E-01	-3.75457E-02	3.65868E-02	3.78990E-01	1-70501E-01
4.16573E-01	2.83127E-01	-3.41510E-02	3.65870E-02	34863175-01	3.69458E-01
5.67594L-01	2.17131E-01	-2.59792E-02	3.65887E-02	31835355-01	7-66935E-01
7.23069E-01	1.500996-01	-1.78200t-02	3+65907E-02	3.86777E-01	7.64402E-01
7.890026-01	1.21945E-01	-1.44354E-02	3.65916E-02	3.88131E-01	7-63346E-01
8.43266E-01	1.00162E-02	-1.18330E-02	3.65923E-02	3.89176E-01	1162533E-01
8.839585-01	8.16714E-02	-9.63383E-03	3.65929E-02	3.90061E-01	7461844E-01
9.22824E-01	6.52799E-02	-7.69134E-03	3.65934E-02	3490845E-101	1.64235E-01
9.582696-01	5.03769E-02	-5.92995E-03	3.65939E-02	3.91557E-01	7.60682E-01
9.91129E-01	3.659996-02	-4.30520E-03	3.65943E-02	3.92215E+01	7-60171E-01
1.02195E 00	2.371326-02	-2.78788E-03	3.65947k-02	3.92831E+01	7.59693E-01
1.05110E 00	1.15528E-02	-1.35781E-03	3.65951E-02	3.93412F+01	7.59243E-01
1.07880t 00	•0	•0	3.65954E-02	3+9365E-01	7.58814E-01

		14	P/P-INF= 6+40216E 00		
KH0	ISA	THETA	v	₹	x
1.100000E-01	4-45255E-01	-5.45506E-02	3.65955E-02	3.73414E-01	7
1.32172E-01	4.35151E-01	-5.32673E-02	3165942E-02	3473907E-01	.7450bE-01
1.55503E-01	4-24543E-01	-5.19200E-02	3.65929E-02	3.74425E-01	10-34097E-01
1.80197E-01	4.13340E-01	-5.04976E-02	3.659188-02	3.74973E-01	7-73665E-01
2.06526E-01	4.01422E-01	-4.89853E-02	3.65907E-02	3.75556E-01	7.73205E-01
2.34871E-01	3.88628E-01	-4.73831E-02	3.65897E-02	3.76183E-01	7.72710E-01
2.65765E-01	3.74720E-01	-4.56016E-02	3.65888E-02	3.76865E-01	7.72173E-01
3.00040E-01	3.59336E-01	-4-36563E-02	3.65881E-02	3.77620E-01	7.71578E-01
3.39096E-01	3441867E-01	-4.14521E-02	3.65875E-02	3.78478=-01	7.70903L-01
3.85662E-01	3.21120E-01	-3.88420E-02	3.65871E-02	3.79496E-01	7.70103E-01
4. 67986-01	2.94016E-01	-3.54473E-02	3465870E-02	3.80826E-01	7.69059E-01
5:96937E-01	2.28081E-01	-2.72755E-02	3.65884E-02	3.84048E-01	7466534E-01
7.51538E-01	1.610946-01	-1.91163E-02	3.65904E-02	3.87295E-91	1.6.19986-91
8.17109E-01	1.32953E-01	-1-57317E-02	3.65913E-02	3.88651E-01	7-62942E-01
8.08096E-01	1.11179E-01	-1.31293E-02	3-65920E-02	3.896975-01	7.62127E-01
9.11553E-01	9.26945E-02	-1.09301E-02	3.65926E-02	3.90583E-01	7-61438E-01
9.502126-01	7.63072E-02	-8.98767E-03	3.65931E-02	3.91368E-01	7-60828E-01
9.85471E-01	6-14071E-02	-7-22628E-03	3.65935E-02	3.92082E-01	7-60275E-01
1.01816E 00	4.76323E-02	-5.60152E-03	3.65940E-02	3192741E-01	7.597 3E-01
1.04881E 00	3.47470E-02	-4.08421E-03	3-65944E-02	3.93358E-01	7.592 55-01
1.07782E 00	2.25875E-02	-2.65414E-03	3.65947E-02	3.93940E-01	7.58834E-01
1.10543E 00	1.10351E-02	-1.29634E-03	3.65951E-02	3.94494E-01	7.58406E-01
1.13187E 00	0.	0.	3.65954E-02	3.95023E-01	7.57996E-01

TABLE V (Cont'd)

	3	7,74888E-01	1174516E-01	7-74127E-01	7,73718E-01	7.73285E-01	2172824E-	7.72330E-01	7171792E-01	7.71197E-01	7-70522E-01	7469720E-C1	7.68675E-01	2.66149E-01	7.6:010E-01	7.62553E-01	2-61738E-01	7-61048E-01	7.60438E-01	7.59884E-01	7-59372E-01	10-366885-01	7.584425-01	7-58043E-01	7.57603E-01	2-57209E-01
	7	3.734235-01	31738945-01	3.74387E-0.1	3.74906E-01	3. 354545-01	3+76038E+01.	3.7666E-01	3.78349E-01	3478105E-01	3.78963E+01	3.799835-01	3.813146-01	3.845405-01	3,81792E=01	3.89150E-01	34901976-01	3.91085E-01	3191871E-01	3.92586E=01	3.932465-01	3.93863E+01	3.94447E-01	3195001E-01	3+95532E+01	3+960416-01
P/P-INF= 6146518E 00	S	3.65993E-02	3.65977E-02	3-65962E-02	3.65948E-02	3.65934E-02	3.65921E-02	3.65909E-02	3.65899E-02	3.65889E-02	3165881E-02	3.65875E-02	3.65872E-02	3.65882E-02	3165901E-02	3165909E-02	3.65916E-02	3.65922E-02	3.65927E-02	3.65932E-02	3.65936E-02	3.65940E-02	3.65944E-02	3.65948E-02	3.65951E-02	3,65954E-02
1= 13 P/P-INF=	THET	-5.70223E-02	-5.57943E-02	-5.45111E-02	-5.31638E-02	-5.17414E-02	-5.02291E-02	-4.86069E-02	-4.68454E-02	-4.49001E-02	-4.26958E-02	-4.00858E-02	-3.66911E-02	-2.85192E-02	-2.03601E-02	-1.69755E-02	-1.43731E-02	-1.21739E-02	-1.02314E-02	-8.47008E-03	-6.84528E-03	-5.32796E-03	-3.89791E-03	-2.540115-03	-1.24380E-03	•
<u></u>	PSI	4.65142E-01	4.55490E-01	4-45402E-01	4.34310E-01	4.23624E-01	4.11725E-01	3.989486-01	3.85060E-01	3.69697E-01	3.522496-01	3.31527E-01	3.04453E-01	2.38580E-01	1.71638E-01	1.43511E-01	1.21746E-01	1.03267E-01	8.68845E-02	7.19878E-02	5.82155E-02	4.53319E-02	3.31/36E-02	2.162195-02	1.05872E-02	• 5
	AHO	1.200005-01	1.410436-01	1.636795-01	1.802678-01	2.10812E-01	2.36983E-01	2.651556-01	2.958654-01	3.299376-01	3.68753E-01	4.15058E-01	4.75841E-01	0.25137E-01	7. 78900E-01	8.44125E-01	8.948465-01	9.38U80E-01	9.705416-01	1.01162E 00	1.04414E 00	1.07465 00		1.130986 00	-	1.1425'8E 00

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-	æ I	Post H	12 THET	R/R-INF= 6.52634E 00	Ē	E.
•	1 300001-01	4.94.7385-01	-6 939975-03	3-660386-03	a. 746336-03	7-748+05-01
u :	1.50055E-01	4.74970E-01	-5.82203E-02	3-66020E-02	3. 738856-01	7.745236-01
14	1.70973E-01	4.653336-01	-5.59924E-02	3.66002E-02	3.74357t-01	7-74151E-01
15	1.92478E-01	4.55261E-01	-5.57091E-02	3.65985E-02	3+74850E-01	7.73761E-01
16	2.15930E-01	4.44685E-01	-5-43618E-02	3.65968E-02	3.75369E-01	7.73352E-01
17	2.40330E-01	4.33516E-01	-5.29393E-02	3.65952E-02	3+75918E+01	7472919E-01
18	2.66349E-01	.4-21634E-01	-5.14271E-02	3-65937E-02	3.76503E-01	7-72458E-01
19	2.94357E-01	4.08875E-01	-4.98048E-02	3.65923E-02	3.771316-01	7.719636-01
20	10-3688+7°F	3.95006E-01	-4.80434E-02	3.65910E-02	3.728156-01	7-71425E-0i
21	3.58766E-01	3.79663E-01	-4.60981E-02	3.65899E-02	3.73572E+01	7.70829E-01
22	3.97371E-01	3-62237E-U1	-4.38938E-02	3.658888-02	3.79432E-01	7.70153E-01
23	4.43405E-01	3.41540E-01	-4.12837E-02	3.65880E-02	3-80453E-01	7.69351E-01
24	5.03850E-01	3.14495E-01	-3.78890E-02	3.658746-02	3.81785E-01	7.68306E-01
25	6.52336E-01	2.48683E-01	-2.97172E-02	3.65881E-03	3+85016E-01	7165777E-01
26	8.05294E-01	1.817876-01	-2.15580E-02	3.65898E-02	3.882716-01	7.63237E-01
27	8.70186E-01	1.53674E-01	-1.81734E-02	3.65906E-02	3.89531E-01	7+62178E-01
85	9.206526-01	1.319186-01	-1.55710E-02	3.65913E-02	10-308906-01	7-61363E-01
29	9.63670E-01	1.13446E-01	-1.33719E-02	3.65918E-02	3.91569E-01	7.60672E-01
30	1.00194E 00	9.70676E-02	-1.142916-02	3.65924E-02	3.92356E+01	7.60061E-01
31	1.03685E 00	8-21746E-02	-9.66805E-03	3.65928E-02	3.93072E-01	7.59507E-01
32	1.06921E 00	6-84050E-02	-8.04327E-03	3.65933E-02	3.93733E-01	7.58995E-01
33	1.09957E 00	5.55234E-02	-6.52595E-03	3.65937E-02	3.94351E-01	7.58516E-01
34	1.12829E 00	4.33666E-02	-5.09589E-03	3.65941E-02	3494935E-01	7. 38064E-01
35	1.15563E 00	3.18159E-02	-3.73809E-03	3.65944E-02	3.95491E-01	7-57634E-01
36	1.18182E 00	2.07818E-02	-2.44176E-03	3.65948E-02	3.96022E-01	7-572246-01
37	1.20699E 00	1.01949E-02	-1-19797E-03	3.65951E-02	3.96532E-01	7.56830E-01
38	1.23124E 00	•	•	3.65954E-02	3.97024E-01	7.56450E-01

TABLE V (Cont'd)

			=	P/P-INF= 6.50589E 00		
د	ž	ISA	THETA	g*	ě	£
=	1.400006-01	5.026036-01	-6.169416-02	3.640906-02	3.73445E-01	7.74871E-01
7	1.591626-01	4.936946-01	-6.05576b-02	3.6#069E-02	3. 73880E-01	7.74527E-01
-	1.791216-01	4.844515-01	-5.93782k-02	3.64048E-02	3.74333E-01	7-74170E-01
-	1.999186-01	4.748291-01	-5.81503E-02	3-66028E-02	3.74805E-01	7.73797E-01
* *	2.216985-01	4.647736-01	-5.68670E-02	3.660096-02	3175299E-01	10-3407E-01
1 0	2.446176-01	4.542136-01	-5.55197E-02	3.65990€-02	3.75819E-01	7.72997E-01
17	2.60d78E-01	4.430606-01	-5.40972E-02	3.65973E-02	3.76368E-01	7-72564E-01
20	2-947508-01	4.31195E-01	-5.25850E-02	3.659556-02	3.76953E-01	7-721036-01
19	3-22600E-01	4.184546-01	-5.09627E-02	3.659396-02	3.77582E-01	7-716086-01
20	3-52962E-01	4.04603E-01	-4.92013E-02	3.65924E-02	3.78267E-01	71069E-01
12	3.86050E-01	3-89280E-01	-4.42559E-02	3.65910E-02	3.79024E-01	7-70473E-01
2	4.25042E-01	3.71876E-01	-4.50517E-02	3.65897E-02	3.798851-01	10-37676-01
4.4	4.70d25E-01	3.51203E-01	-4.24416E-02	3-05446E-02	3.809075-01	10-356689FL
4.	5.30944E-01	3.241886-01	-3.90469E-02	3.65878E-02	3.82241E-01	7.57948E-01
25	0.730492-01	2.584361-01	-3.08751E-02	3.65880E-02	3.854766-01	7-654186-01
20	d.33831E-01	1.915856-01	-2.27159E-02	3.65895E-02	3.88736E-01	7. J2875E-01
27	8-95402E-01	1.634866-01	-1.933136-02	3.65903E-02	3.90097E-01	10-39181912
28	95022E-01	1.417406-01	-1.67289E-02	3.659008-02	3191148E-01	1-610006-01
~	9-884326-01	1.232741-01	-1.45298e-02	3.659154-02	3.92038E-01	10-360E09#/
٢	1.020528 30	1.069015-01	-1.25873E-02	3.65920E-02	3.92826E-01	7-59697E-01
31	1-C0126E 30	3.20122E-02	-1.082596-02	3.65925E-02	10-3245E-01	7,59142E-01
32	1-09347E 30	7.82455E-02	-9.2011CE-03	3.65930E-02	10-3+024E-01	2,58629E-01
33		6.53663E-02	-7.0d376E-03	3.65934E-02	3.94824E-01	7-58150E-01
40	1.13227E 00	5.321126-02	-6.25373E-03	3.65938E-02	3.954096-01	7-57698E-01
3		4.166186-02	-4.845456-03	3.65941E-02	3.95965E-01	7-572086-01
jo		3.062866-02	-3.59900E-03	3.65945E-02	3.96496E-01	7-56857E-01
37	1.23U61E 00	2-034226-02	-2.35541E-03	3.65948E-02	3.970086-01	7.56463E-01
Į.		9.8+751E-03	-1.157836-03	3.65951E-02	3.97500E-01	7-56082E-01
٤	1.27819E 00	c·	c.	3.659545-02	3.97977E-01	7.55715E-01

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	3	7.74861E-01	7.745296-01	7-741846-01	7.73827E-01	7.73454E-01	7-730646-01	7.7265+6-01	7.72220E-01	7.717596-01	7.712035-01	7.70724E-01	7.701286-01	7.09451E-UI	7.680486-01	7.67601E-01	7.65069E-01	7.625245-01	7.61464E-01	7.60647t-01	7.599504-01	7.59344E-01	7.567886-01	7.58275E-01	7.57796E-01	7-573436-01	7.569136-01	7.56502E-01	7.56107E-01	7.557206-01	7.55358E-01	7.55001E-01
	₹	3.73458E-01	3.738785-01	3.743145-01	3.74768E-01	3.75240E-01	3,75735E-01	3.762555-01	3.76605E-01	317390E-01	3.78020E-01	3.78705E-01	3.794646-01	3.80325é-01	3.813486-01	3.82684E-01	3.85922E-01	3.89186c-01	3.905496-01	3.91601E-01	3,924936-01	3.93282E-C1	3.93999E-01	3.94662±-01	3.95282E-01	3.95868E-01	3.96425E-01	3.96957E-01	3.97469E-01	3.979625-01	3.98440E-01	31989046-01
P/P-ENF = 6.64403E 00	n	3.66148E-02	3.66124E-02	3.66101E-02	3.66079E-02	3.66057E-02	3-66035E-02	3.06015E-02	3.65995E-02	3.65975E-02	3.65957E-02	3.65939E-02	3.65923E-02	3.65907E-02	3.65894E-02	3.05883E-02	3.65881E-02	3.65893E-02	3.65900E-02	3.6590eE-02	3.65912E-02	3.65917E-02	3.65922E-02	3.65926E-02	3.65930E-02	3.659346-02	3.65938E-02	3.65942E-02	3.65945E-02	3.65948E-02	3.65951E-02	3.65954E-02
01	THETA	-6.39147E-02	-6.28165E-02	-6.16801E-02	-6.05007t-02	-6.92727E-02	-5.79895E-02	-5.66421E-02	-5.52197E-02	-5.37074E-02	-5.20851E-02	-5.03237E-02	-4.83784E-02	-4-61742E-02	-4.35641E-02	-4.01693E-02	-3.19975E-02	-2.383846-02	-2.04538E-02	-1.78514E-02	-1.56522ë-02	-1.37097E-02	-1.19484E-02	-1.03236t-02	-8.806246-03	-7.37620E-03	-6.018406-03	-4.72206E-03	-3.47830E-03	-2.28030E-03	-1.12250E-03	•0
= 7	PS1	5-20343E-01	5.11745E-01	5.02851t-01	4.93622E-01	4.84015E-01	4.73974E-01	4.63430E-01	4.52293E-01	4.40444E-01	4-27721E-01	-4.13888E-01	3,98585E-01	3.81203E-01	3-60553E-01	3.33567E-01	2.67875E-01	2.01070E-01	1-72986E-01	1.51249E-01	1.32790E-01	1.16423E-01	1.01538E-01	8.11742E-02	7.48974E-02	6-27443E-02	5.11963E-02	4-01642E-02	2.95786E-02	1.93844E-02	9-53708E-03	•0
	ZHY.	1.50000E-01	1.68403E-01	1.87477E-01	2.07304E-01	2.27984E+01	2.49642E-01	2.724346-01	2.95561E-01 ·	3.22290E-01	3.49988E-01	3.801846-01	4.13690E-01		4.97417E-01 %	5.57221E-01	7.04170E-01	8.55602E-01	9.198635-01	9.698452-01	1.01245E 00	1.02030E 00		-		1.17554E 00	-	-	1.25353E 00	1.27760E 00		1.32350£ 00
	7	01	11	12	13	7.7	15	16	1.7	18	19	07	21	55	23	24	25	56	27	28	53	30	31	32	33	34	35	36	37	38	39	0,

	;	#	9 P/P-INF= 6,76092E 00	6.76092€ 00	į	7
	KHC	rs.	PHEIA	a	2	
	1.00000E-01	5.37210E-01	-6.600326-02	3.66214E-02	3.734726-01	1-148496-01
•	1.777036-01	5.29193601	-6.50056t-02	3.66187E-02	3. 73880E-01	7.74528E-01
_	1.960056-01	5.20609E-01	-6.39074E-02	3.66161E-02	3474301E-01	7.74195E-01
	2.1+973E-01	5-11728E-01	-6.27710E-02	3.66136E-02	31747376-01	7.73851E-01
	2.34691c-01	5.025146-01	-6.15916E-02	3.66111E-02	3475191E-01	7.73493E-01
	2.552595-01	4.92922E-01	-6.036375-02	3.66087E-02	3.75664E-01	7-73120E-01
.:	2.757996-01	4.82896E-01	-5.90804E-02	3.66064E-02	31761596-01	7.72729E-01
	2.93467E-01	4.72367E-01	-5.77330E-02	3.66041E-02	3,766795-01	7.72319E-01
_:	3.23404E-01	4.61240E-01	-5.63105E-02	3.66018E-02	3.772306-01	7.71886E-01
	3.44055E-01	4.494146-01	-5.479836-02	3.65998E-02	34778165-01	7.71424E-01
:	3.766001-01	4.367086-01	-5.31760E-02	3.65976E-02	3178446E-01	7-70928E-01
:	4.06642E-01	4.228936-01	-5.14146E-02	3.05956E-02	3.79132E-01	7.70389E-01
:	4.39972E-01	4.07609E-01	-4.94892E-02	3.65937E-02	3.79891E-01	7.69792E-01
:	4.77959E-01	3.90248E-01	-4.72650E-02	3.65919E-02	3.807546701	7.69115E-01
:	5.23263E-J1	3.09022E-01	-4-46549E-02	3.05903E-02	3.817785-01	7.58312E-01
:	5.82762E-01	3.42065E-U1	-4.12602E-02	3.65889E-02	3.831156-01	7.67284E-01
	7.28979E-01	2.17032E-01	-3.30833E-02	3.65882E-02	3,863575-01	7-64730E-01
	8.790846-01	2-102734-01	-2.49292E-02	3.65892E-02	3.89625E-01	2.62183E-01
	9.430425-01	1.82204E-01	-2.15446E-02	3.55898E-02	3.90990E-01	7.61122E-01
	9.93395E-01	1.00476E-01	-1.894226-02	3.65904E-02	3.920436-01	7.60305E-01
_:	1.0353lc JU	1.423256-01	-1.67450E-02	3.65909£-02	3.92935E-01	7.59613E-01
_:	1.07355E 00	1.25663E-01	-1.48005E-02	3.65914E-02	3193725E-01	7-59000E-01
•	107976 00	1.10782E-01	-1.303926-02	3.65919E-02	3-94446-01	7.584445-01
_:	.13990E 00	9.70217E-02	-1.14144E-02	3.65923E-02	3.95107E-01	7.57931E-01
•	1.16984E OU	8-41476E-02	-9.8y710E-03	3.65927E-02	3.95728E-01	7.57451E-01
_:	1.19817E OC	7.19906E-02	-8.46707E-03	3.65931E-02	31963156-01	7.56998E-01
_:	1.22514E 00	6.04503E-02	-7.10926E-03	3.65935E-02	3.948725-01	1-56567E-01
_:	1.2>09d£ 00	4.94195E-02	-5.81292E-03	3.65938E-02	3197405E-01	7.56156E-01
_:	1.27581E 00	3.38348E-02	-4.56915E-03	3.65942E-02	3197918E-01	7.55761E-01
•	-	2.86413E-02	-3.371156-03	3.65946E-02	3.98412F-01	7.55380E-01
_:	1.32294E 00	1.879445-02	-2.213376-03	3.65948E-02	3.98890E-03	~55011E-01
•		9.25749E-03	-1.09087E-03	3.65951E-02	3.99355E+01	1.54654E-01
•	1.36737£ 00	• •	•0	3.65954E-02	3.998076-01	7-54306E-01

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a	1.700006-01	5-54158E-01	-0.81641E-02	3-66286E-02	3.734896-01	7-74836E-01
•	1.870706-01	5.46094E-01	-6.71317E-02	3+66257E-02	3.738846-01	7.74524E-01
10	2.04677E-01	5-377906-01	-6-60681E-02	3.662296-02	3.7.2916-01	7.74202E-01
1	2.22880E-01	5-29220E-01	-6.49700E-02	3.662018-02	3.74713E-01	7-73870E-01
12	2.41747E-01	5.203536-01	-6.38335E-02	3.661736-02	3.751506-01	7.73525E-01
14	2.61359E-01	5.111536-01	-6.26541E-02	3.68146E-02	3.75603E-01	7.73167E-01
14	2.810175-01	5.01575E-01	-6.14201E-02	3.66120E-02	3.76077E-01	7.72794E-01
7	3.03243E-01 .	4.915646-01	-6.01428E-02	3.66094E-02	3.76572E-01	7.72403E-01
16	3.257916-01	4-81050E-01	-5.87955E-02	3.66069E-02	3.770936-01	7.71993E-01
17	3.49002E-01	4.699456-01	-5.73730E-02	3.66044E-02	3.776446-01	7.71559E-01
18	3.751196-01	4.58129E-01	-5.58608E-02	3.66020E-02	3.78231E-01	7.71097E-01
19	4.025266-01	4.45440E-01	-5.42385E-02	3.65997E-02	3.78862E-01	7.70601E-01
20	4.324066-01	4.31643E-01	-5.24770E-02	3.65975E-02	3.79549E-01	7.70002E-01
21	4.65565E-01 ·	4.163786-01	-5.05317E-02	3.65953E-02	3.803086-01	7-69465E-01
22	5.033586-01	3.99038E-01	-4.83275E-02	3.65933E-02	3-81172E-01	7.68787E-01
~3	5-484346-01	3.78436E-01	-4.57174E-02	3.655136-02	3.821976-01	7.679836-01
24	6-07636E-01	3.51507E-01	-4.23227E-02	3.65896E-02	3.83535E-01	7-66935E-01
25	7.531436-01	4-45934E-01	-3-41508E-02	3.65884E-02	3.86781E-01	7.64399E-01
20	9.031426-01	2.19220E-01	-2.59917E-02	3-658918-02	3.90052E-01	7-618516-01
27	9.66810E-01	1.91166E-01	-2.26071E-02	3.65896E-02	3.91+19E-01	7.607896-01
P 23	1-01034£ 00	1.694486-01	-2.00047E-02	3.65901E-02	3-92473E-01	7.59971E-01
29		1.51004E-01	-1.78055E-02	3.65906E-02	3.93367E-01	7-59278E-01
30		1.346476-01	-1.58630E-02	3.659116-02	3.941585-01	7-58665E-01
31	1.13041E 00	1.19771E-01	-1.41017E-02	3.65914E-02	3+948776-01	7.581096-01
32		1.060146-01	-1.24769E-02	3.65920E-02	3-955426-01	7.575956-01
W		9.31429E-02	-1.09596E-02	3.65924E-02	3.96163E-01	7.57114E-01
46		8.09942E-02	-9.5295E-03	3.65928E-02	3+967515-01	7-56661E-01
Ų		6.94498E-02	-8.17178E-03	3-65932E-02	3.97309E-01	7-56230E-01
ò		5.842031-02	-6.875426-03	3-65936E-02	3.978436-01	7-55818E-01
37	1.29752E 00	4.78368E-02	-5.63166E-03	3.65939E-02	3+98356E-01	7.55423E-01
34	1.32139E 00	3-76441E-02	-4.43365E-03	3+65942E-02	3-98851E-01	7-55042E-01
39	1.34449E 00	2.77978E-02	-3.27586E-03	3.65945E-02	3.99329E-01	7.54673E-01
ć	1.36690E 00	1-82612E-02	-2-15335E-03	3.65948E-02	3.99794E-01	7.54315E-01
41	1.38870E 00	9.00391E-03	-1.06250E-03	3.65951E-02	4-00247E-01	7-53967E-01
42	1.40×94E 00	•	••	3.659546-02	4.09688E-01	7.53628E-01

7.74207E-01	7.73885E-01	7.73552F-0)	7.72849E-01	7.72475E-01	7.720456-01	\$-71674E-01	1-71240E-01	7.70778E-01	7,70282E-01	7.69742E-01	7-69145E-01	7-68467E-01	7.67662E-01	2166613E-0	7.64076E-01	7.61526E-01	10-369409-01	7.59645E-01	7.58951E-01	7.58338E-01	7-57781E-01	7.57267E-01	7.567BoE-01	7.56332E-01	3,55901E-01	7.55489E-01	7.55093E-01	7.54712E-01	2,54343E-01	7,53985E-01	7.53636E-01	7.53297E-01	7,52965E-01
3.73891E-01 3.74286E-01	3174694E-01	3.7513 SE-01	3.76007E-01	3.769816-01	31769776-01	3. 114.78E-01	3478050E-101	3.78637E-01	3.792686-01	3.749565-01	3.80716E-01	3.81580E-01	3.82607E-01	3.839465-01	3,871956-01	3.904705-01	3.918385-01	3 4 92894E-01	3.93789E-01	3.945815-01	3.95301E-01	3.95966E-01	3,965895-01	3.971765-01	31977355-01	3.98270E-01	3.987845-01	3.99279E-01	31997591-01	4,002246-01	4.006776~01	4.01119E-01	4.01551E-01
3.66303E-02	3.66272E-03	3.06242E-02	3-66183F-02	3-661556-02	3.66127E-02	3.66099E-02	3.66072E-02	3.66046E-02	3.66020E-02	3*65995E-02	3.66971E-02	3.05947E-02	3.65926E-02	3.65904E-02	3.05887E-02	3.65890E-02	3.65895E-02	3.65899E-02	3.65904E-02	*- 65909£-02	J. 65913E-02	3.65917E-02	3.65921E-02	3.65925E-02	3.65929£-02	3.65933E-02	3.65936E-02	3.65939E-02	3.65942E-02	3165946E-02	3.65949E-02	3.65952E-02	3.65954E-02
-6.92012E-02 -6.81688E-02	-+.71052E-02	-6.60071E-02	-5.48706E-02 -4.36911E-02	-6.24632E-02	-6.117996-02	-5.98326E-02	-5.84101E-02	-5.68978E-02	-5.52755E-02	-5.351416-02	-5.15688E-02	-4.93645E-02	-4.67544E-02	-4.33597E-02	-3.51879E-02	-2.70287E-02	-2.36441E-02	-2.10417E-02	-1.88426E-02	-1.69001E-02	-1.513d7E-02	-1.35139E-02	-1.19966E-02	-1.05666E-02	-9.20841E-03	-7.91245E-03	-0.66870E-03	-5.47073E-03	-4.31293E-03	-3.19043E-03	-2.09958E-03	-1.037116-03	•0
5.62499E-01 5.54448E-01	5.46157E-01	5.37600E-01	5-28747E-01 5-19561E-01	5.099976-01	5.00000E-01	4.89502E-01	4.78412E-01	4.66612E-01	4.539405-01	4.40161E-01	4.24915E-01	4.07595E-01	3.87016E-01	3.001106-01	2.94601E-01	2.279336-01	1.998946-01	1. 78186E-01	1.59749E-01	1.433986-01	1.285272-01	1.:47741-01	1.01905=-01	8-97591E-02	7.82167E-02	6.71888E-02	5-66060E-02	4.64148E-02	3.05693E-02	2.70332E-02	1.777626-02	8.77248E-03	•0
1.96494E-01 2.13473E-01	2.30987E-01	2.430946-11	2.67861E-01 2.87371E-01	3.07722E-01	3, 29036E-01	3.51468E-01	3.75210E-01	4.03542E-01	4.27810E-01	4.575.9E-01	4.90531c-J1	5.2d136E-01	5.72990E-01	6.31903E-01	7.1071dE-01	9.250336-01				-	-	-	-			-		-	-			-	1.451.0E 00
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1.47148E 00		1.429865 00			*			•••					1.1J246E 00		1.01150E 00	9.483966-01	7.99754E-01	6.55613E-01	5.96981E-01	5.523456-01	5.14923E-01	4.82093E-01	4.52511E-01	4.253806-01	4.00180E-01	3.76553E-01	3.54234E-01	3.330286-01	3.12782E-01	2.933726-01	2.74701E-01	2.566886-01	2.392656-01	2.223746-01	2.059666-01	1.900006-01	Ž	840
0. 0. 0. 0.	1-73325E-02	2.63360E-02	4.51279E-02	5.49726E-02	6.51633E-02	7.574418-02	8.677035 /.	9.8310oE /	1.10454E-0.	1.233196-01	1.37068E-01	1.519366-01	1.68281E-01	1.867106-01	2.08408E-01	2.36432E-01	3.03055E-01	3.58510E-01	3.953836-01	4.15938E-01	4.332386-01	4.48465E-01	4-62227E-01	4.748826-01	4.86666E-U1	4.97741E-01	5-08235E-01	5.18207E-01	5-27757E-01	5.36929E-01	5-45769E-01	5.54313E-01	5.62591E-01	5.706296-01	5-78450E-01	5-86073E-01		120
0.	-2.05104E-03	-3.11350E-03	5.32690E-03	-6.48470E-03	-7.68267E-03	-8.92643E-03	-1.02228E-02	-1.15806E-C2	-1.30106E-02	-1.45279E-02	-1.61527E-02	-1.79141E-02	-1.9856E-02	-2.20557E-02	-2.46581E-02	-2.80427E-02	-3.62018E-02	-4.437376-02	-4.77684E-02	-5.03785E-02	-5.25828E-02	-5.45281E-02	-5.~2896E-02	-5.79119E-02	-5-94242E-02	-6.08467E-02	-6.21940E-02	-6.34773E-02	-6.47052E-02	-6.58847E-02	-6.70211E-02	-6.81193E-02	-6.91829E-02	-7-02154E-02	-7.12193E-02	-7.21972E-02	-	6 1447
3.65954E-02	3.65949E-02	3.65946E-02	3.65940E-02	3.65936E-02	3.65933E-02	3.659306-02	3.65926E-02	3-65922E-02	3-65919E-02	3.65915E-02	3.65910E-02	3.65906k-02	3.65902E-02	3.65897E-02	3.65893E-02	3.65890E-02	3.658905-02	3.05914E-02	3.65938E-02	3.65964E-02	3.65990E-02	3-66017E-02	3.66044E-02	3+66073E-02	3.66102E-02	3-66131E-02	3.66161E-02	3.66192E-02	3.66223E-02	3.662546-02	3.66286E-02	3.663196-02	3.66352E-G2	3.663858-02	3.66419E-02	3.66453E-02	•	P/P-INF= 6.86544E 00
4.02396E-01	4.01541E-01	4-01098E-01	4-09179E-01	3.996-39E-01	3.99292E-01	3.986886-01	3.981536-01	3+975975-01	3.97005E-01	3.963826-01	3495715E-01	3.94995E-01	3,94202E-01	3.93306E-01	3.92249E-01	3.90880E-01	3.87601E-01	3.84349E-01	10-380088-01	10-308618 · E	3+81115E-01	3.80354E-01	3.79666E-01	3.79035E-01	3.78447E-01	3.778956-01	3.77373E-01	3.768765-01	3.76402E-01	3.759486-01	3.75510E-01	3.75088E-01	3474680E-01	J. 74284E-01	3.73900E-01	3.73526E-01	į	E
7-52316E-01	7-52973E-01	7,533136-01	7-54020E-01	7.543891-01	7.547716-01	7.55167E-01	7.555796-01	7.560116-01	7.56465E-01	7.56946E-01	7.57461E-01	7.58018E-01	7-586326-01	7.593256-01	7-601456-01	7-612086-01	7-637606-01	7-662996-01	7-073486-01	7-68153E-01	7.688316-01	7-694296-01	7.699696-01	7.704656-01	7.70928E-01	7-713626-01	7.71773E-01	7-72164E-01	7.72537E-01	7.728966-01	7.73240E-01	7.73573E-01	7.738966-01	7-74208E-01	7. 74511E-C1	7.748076-01	1	Ľ

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2.04494E-01 2.81829E-01	5.70539E-01 5.62273E-01	-7.01761E-02 -6.91125E-02	3.66402E-02	3.75067E-01 3.75475E-01	7.73590E-C1
2.997506-01	5.537436-01	-6.80144E-02 -6.68179E-02	3.06332E-02	3.75898E-01	7.72935E-01 7.72590E-01
3.37039£-01	5-357566-01	-6.56984E-02	3.66264E-02	3 . 757 90E-01	7.72232E-01
3.57784E-01	5.26222E-01	-6.44705E-02	3.66231E-02	3.772655-01	7.71858E-01
4.01091E-01	5.05784E-01	-6.18398E-02	3.66105E-02	3.782846-01	7.71056E-01
4.24002E-01	4.94725E-01	-0.04173E-02	3.66133E-02	3.788366-01	7.70622E-01
4.446786-01	4.82956E-01	-5.89050E-02	3.66102E-02	3.794246+01	7.70159E-01
4.70070E-01	4.70317E-01	-5.72827E-02	3.66071E-02	3.800575-01	7.69662E-01
5.387ppf-01	4.41365E-01	-5-35759E-02	3.06011E-02	3 4 8 15 0 7 E-01	7.68524E-01
5.73028E-01	4.24085E-01	-5.13717E-02	3.65981E-02	3.82373E+01	7.67846E-01
6.43453E-01	4.03552E-01	-4.87615E-02	3.65953E-02	3.83401E-01	7.67040E-01
6.78d11E-01	3.76707E-C1	-4.53668E-02	3.65924E-02	3.84743E-01	10-306659*2
8.222936-01	3.113106-01	-3.71950E-02	3.65895E-02	3.87998E-01	7.63450E-01
1.03312E 00	2. to 724E-01	-2.56512t-02	3.65893E~02	3-92652E-01	7.59832E-01
	1.950376-01	-2.30488E-02	₹896E-02	3.93710E-01	7.59012E-01
	1.700156-01	-2.08497t-02	20−300€ °	3.94607E-01	7.58318t-01
	10-392709-1	-1.890726-02	20-3+06 · ·	3.95401E-01	7457704E-01
-	1.454136-01	-1.71459E-02	~5908E-03	3.961.2E-01	7.57146E-01
_	1.31.66E-01	-1.55211E-02	3.65912E-02	3.967895-01	2.56631E-01
1.25546E 00	1.18806E-01	-1.40038E-02	3.65916E-02	3.9 (4136-01	7.554.0E-01
1 409454 00	1.086835-01 0.11270F-02	-1.121595-02	3.659231-02	31985636-01	7.55264F-01
_	8.41027E-02	-9.91960E-03	3.65927E-02	3-99098E-01	7.54851E-01
-	7.35234E-02	-8.67586E-03	3.65930E-02	3.99613E-01	7,544556-01
1,34327E 00	6.333394-02	-7.47788E-03	3.65934E-02	4.00110E-01	7.54072E-01
1. +JougE 00	5.34902E-02	-6.32009E-03	3.65937E-02	4.00591E-01	7.53703E-01
-	4.39550E-02	-5.19758E-03	3.65940E-02	4.01057E-01	7,53344E-01
	3.40990E-02	-4.10671E-03	3.65943E-02	4.01511E-01	7.52995E-01
_	2.56966-02	-3.04424E-03	3.65946E-02	4.01954E-01	7.52655E-01
-	1.69245E-02	-2.007185-03	3.05949E-02	4402387E-01	7.52323E-01
1.511246 00	8.36440E-03	-9.93212E-04	3.65952E-02	4.02811E-01	7.51998E-01
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TABLE V (Cont'd)

| 1-74752E-01 | 73744775-01 | 10-30614162 | 70-30000-01 | 2 - 222005-01 | 7.72996E-01 | 7.72674E-01 | 7-723406-01 | 7.71995E-01 | 7.716365-01 | 7471262E-01 | 2,70871E-01 | 7-70460E-01 | 7.70025E-01 | 1-6456ZE-04 | 7-69065E-01
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 | T.62846E-01 | 7.60289E-01 | 10-34226512 | 7.58403E-01
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 | 7452727E-01 | 1-52378E-01 | 7452038E-01 | 10-361402E-01 | 7.51379E-01
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 | 10-0056616 | 3.961916-01 | 10-347 ABA • 6 | 3.98208F-01 | 3.98799E-01
 | 3.99360E-01 | 3.998976-01 | 4,004136-01 | 4100911E-01 | 4.01393E-01
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 | 3.66093E-02 | 3.66057E-32 | 3.66022E-02 | 3.65986E-02 | 3.65950E-02
 | 3.65907E-02 | 3.65894E-02 | 65893E-02 | 3.65894E-02
 | 3465897E-02 | 3.65900E-02 | 31039046-04 | 3.65011F=02 | 3,659146-02
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 | 3-65949E-02 | 3465952E-02 | 3-684246-04 |
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 | -1.930936-03 | -9.56806E-04 | • |
| 6.31006E-C1 | 6.23922E-01 | 6.16684E-01 | 6.09279E-01 | 6.01693E-01 | 20-38086-01 | 5.77675-01 | 5.591525-01 | 5.60362E-01 | 5.51229E-01 | 5.41721E-01 | 5.31780E-01 | 5.213406-01 | 5.10310E-01 | 4.94573E-01 | 4.85966E-UI
 | 4.72256E-01 | 4.57084E-01 | 4.398446-01 | 4.19356E-01 | 3.92>67E-01
 | 3.27285t-01 | 2.607996-01 | 2.32320E-01 | 2.11153E-01
 | 1.92747E-01 | 1.76420E-01 | 1.61567E-01 | 10-4/6305-01 | 1.22840F-01
 | 1.113065-01 | 1.00286E-01 | 8.97U99E-02 | 7.95232E-02 | 6.96817E-02
 | 6.01489E-02 | 5.08944E-02 | 4.18925E-02 | 3. 312126-02 | 2.45617E-02
 | 1.61976E-02 | 8.01456E-03 | • • |
| 2.20000£-01 | 2.34019E-01 | 7.49578E-01 | 2.64904E-0. | 2.806.50E-01 | 2.96791E-01 | 30134545101 | 4.44448F=01 | 3-60732E-01 | 3.8585E-01 | +.05804E-01 | 4.20699E-01 | 4 44092E-01 | 4.71977E-01 | 4.96812E-01 | 5.23554E-01
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P/P-1MF= 7-13488E 00	•	3.67005E-02	3.68955E-02	3.44907E-02	3-6-060E-02	76-3679000	3.667915-02	3-66676E-02	3-66630E-02	3-46585E-02	3.64540E-02	3.66496E-02	3.64452E-02	30-984-05	20-100F 90°F	70-37759915	3.002806-02	50-316799°C	2 44 16 35 -02	3.44115-02	31.440695-92	3.44024F-02	3-65981E-02	3. 65922E-02	3.65890E-02	3-45895E-02	3.65694E-02	3.6389eE-02	3169595F-02	3-15963F-02	3.65906E-02	3,65910E-02	3-659136-02	3.65926E-02	3.659201-04	200362600	3-65929F-02	3.65932E-62	3.65936E-02	3.65934E-02	3.65941E-02	3.65946-02	3.65946.02	3.659496-62	3-1504F-02	
1 0/0-116	PHETA	-8.15536E-02	-8.06790E-Q2	-7.97666E-02	-7.68753E-02	-1.19434E-02	-7.69693E-02	-7.50075E-02	39751E-	-7.29114E-02	-7.18132E-02	-7.06767E-02	-4.04972E-02	-6-82693E-02	-6.69860E-02	-6.56380E+UZ	-0-92460E-02	20-31-01-0-	70-301907-07	i	-5.517036-02	-5-25401E-02	-4.91654E-02	-4.09935E-02	-3.283436-02	-2.94497E-02	-2.684736-02	-2.46981E-02	-2.27057E-02	: -	-	-1.63722E-02	-1.50144E-02	-1.37281E-02	1.247435-02	70-349171-1-	20-360766-8-	-7.90526E-03	-6.84277E-03	-5.80668E-03	-4.79170E+03	-3.79852E-03	-2.624396-08	-1.86761E=03	-9.408085-04	;
	754	6.59315E-01	• 52528E-01 ·	6.45409E-01	4.38548E-01	6. 51.532E-01	6.23951E-01	6-08627E-01	4.00650E-01	5.92435E-01	5.839556-01	5. 751406-01	5-660736-01	5.56591E-01	2.460785-01	5.36266E-01	5.25265E-01	3-13334E-01	10-360660	40012016-01	4.54970F-01	4.34526E-01	4.07791E-01	3.42624E-01	2.76228E-01	2.48280E-01	2.26634E-01	2.08243E-01	1.91926E-01	1.61457F=01	1.50509E-01	1.383796-01	1-26851E-01	1.158356-01	1.05262E-01	Y-50/68E-02	7-57094F-02	6.64566E-02	5.74561E-02	4.84840E-02	4.01274E-02	3.176394-02	2.35814E-02	1.55671E-02	7. /UYYZE-US	;
	QHY .	2.4J000E-01	2.538746-01	2.68039E-01	2.82516E-01	2.97329E-01	3.12507E-01	3.440A4F-01	3.605646-01	3.77563E-01	3.95138E-01	4.133576-01	4.322991-01	4.52059E-01	4.72758E-01	6.94545E=01	5.17613E-01	2.422.18E=01	5-64/13E-01	2. 310.23E-01	0.55240E=01	7.09862E-01	7.671796-01	9.08165E-01	1.053675 00				1.24111E 00			-		-	3094	1.460166 00	1.574456 00		54633E				-	7.442998 00	1.0001000	
	7	-	~	~	,	•	۰,	- a	• •	01	=	77	7	*	2	2	<u> </u>		5 6	5.	; ?	1 7	52	52	92	2.7	82	5 3	ĝ:	7 7	7 6	46	35	30	~ :	9 (, ,) red	42	43	;	45	9	4.	1 0 0	F

3. Double Conical Shock Program Example

This program was carried out for the case where one cone is at an angle of attack for the following input data:

$$M_1^* = 2.03183 \ (M_{\infty} = 4.0, 15 \text{ deg. cone}).$$

$$\psi_1^* = 0.165935 \text{ rad.}$$

$$\gamma_1 = 0.38032 \text{ rad.}$$

$$p_1/p_{\infty} = 2.4056$$

$$s_1/R = 0.067733$$

$$M^*_{1,2} = 2.06346$$

$$\psi^*_{1,2} = 0.12262 \text{ rad.}$$

$$\gamma_2 = 0.342957 \text{ rad. } (M_{\infty} = 4.0, 12.5 \text{ deg. cr})$$

$$p_2/p_{\infty} = 1.9441$$

$$s_{1,2}/R = 0.029667$$

$$r = 2.0$$

$$q = 1.0$$

$$\Delta \psi = 5.0 \text{ deg.}$$

$$\bar{\gamma} = 1.4$$

$$s_2/R = 0.52932$$

$$KALF = 1$$

$$\alpha$$
 = 2.0 deg.

$$\eta/\alpha = 0.654926$$

$$M_2^* = -0.408226$$

$$M_{w,2}^* = 1.86308$$

$$\psi_2^* = -0.505885 \text{ rad.}$$

The program output is included in this appendix and the symbols are defined in Appendix V.3.

The intersection curve of the two conical shocks is described in terms of conical coordinates ρ and ψ , which lie on the base cone surface. The computation of this curve is terminated when the value of $\psi_{\rm max}$, which represents the point where the intersection curve starts to bend back in, is reached.

The pressure, Mach number and entropy immediately behind the intersection curve in the lower and upper regions are given by Figures 49 and 50. These quantities are plotted versus the meridian angle ψ and therefore are at points along the intersection curve. As shown in the output these computations are terminated when a so-called Mach reflection is reached. This means that the normal Mach number components are too small for the necessary deflections and a cusped intersection with a normal shock region occurs. Comparison of Figures 49 and 50, shows that the pressure ratios in the lower and upper regions, at each point on the intersection curve, differ by less than 2% even though the assumption of constant shock strengths has been used instead of an iteration procedure.

FIGURE 49 - LOWER CONICAL-CONICAL INTERSECTION REGION PROPERTIES

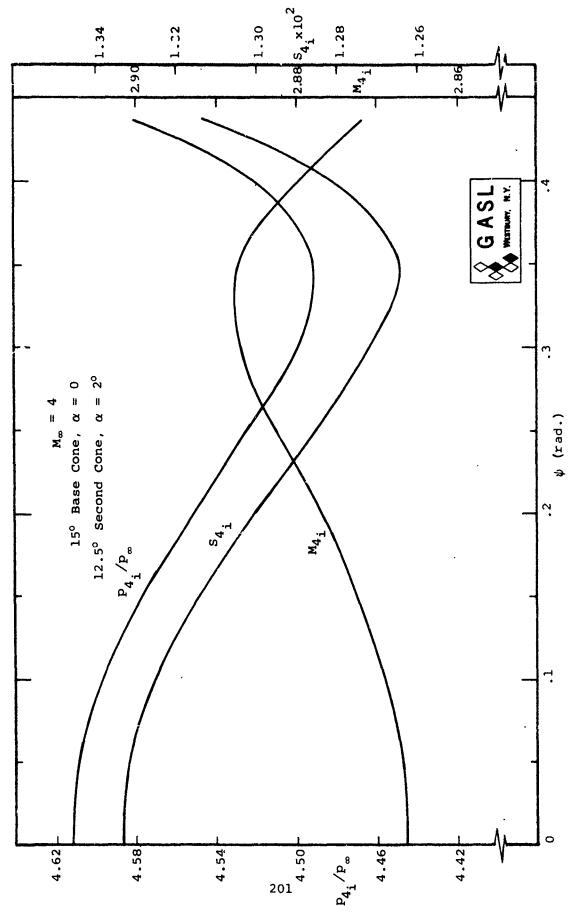


FIGURE 50 - UPPER CONICAL-CONICAL INTERSECTION REGION PROPERTIES

DUDBLE CONICAL SHOCK BROWNING CONICAL SHOCK PROBLEM DUDBLE CONICAL SHOCK PROBLEM

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FIRST GUME

Miss 2.03183E UD PS41ss 1.05935E-01 CAMMAIS 3.80320E-01 P1/P-1MF= 2.40500E 80 S1/R= 0.77330E-02

SECUMD CUME METM NU AMOLE L÷ AFFACE
M120= 2.70346E 00 95812= 1.22620E=01 GARMA2= 3.42957E=01 92/4=10F= 1.94410E 00 512/R= 2.96670E=02

UATA FOR SECOND COME WITH ANGLE OF ATTACK

ALPHA= 2-00000E 00 ETA/ALRHA= 6-54926E-01 M2==-6-08226E-01 MM2== 1-86304E 00 #382==-5-05885E-01

M* 2.000000E 00 4= 1.00000t 00 DLLIA PSI= 5.00000E 00 ALPHA AND DELTA PSE ARE IN DEGREES \$2/x= 5.29320E-01 CAMMA-BAK# 1.40000E OC

PSI-MAKEDEGMEESI = 5.23065E 01

TERMS INDEPENDENT OF PSELIE

THETA-1# 1.20454E-02 LDSINCIS-3.71218E-01 #21# 3.27538E 00

COSENZI	-9.28554G1 -8.8284E+01 -6.5024E-01 -6.5024E-01 -6.366E-01 -3.5560E+01 -3.6345E+01 -2.3467E+01 -2.3467E+01 -2.4345E+01 -2.5607E+01	MN1 3,3209E 00 3,1650E 00 2,7966E 00 2,3796E 00 2,3796E 00 1,6879E 00 1,4295E 00 1,0394E-01 2,0394E-01 7,6087E-01	
COSTAY	-3.7122E-01 -3.7861E-01 -4.0069E-01 -4.368E-01 -5.3142E-01 -5.3142E-01 -6.3902E-01 -6.9164E-01 -7.4095E-01	MB-BAR 1 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01 -1.0651E-01	
CD51 NX)	0- 247795E-01 448981E-01 649378E-01 742892E-01 742892E-01 742892E-01 748856E-01 64856E-01	4M-BAR 1 -34249E 00 -347058E 00 -247058E 00 -14873E 00 -14875E 00 -14875E 00 -14875E 00 -14876E 00	
CH81800	9.2855E-01 9.2501E-01 9.144E-01 8.265E-01 8.4255E-01 8.4155E-01 7.6131E-01 7.6131E-01 5.9686E-01	MI+BAR 1 +0. -1.00055E 00 -1.7910E 00 +2.31646 00 -2.46600E 00 -3.1641E 00 -3.1541E 00 -3.1541E 00	
COSTRE	0. 8.09286-02 1.1246-01 3.17686-01 3.92456-01 4.64276-01 6.32596-01 6.56866-01 7.11316-01	MX1 0. 4.7808E-02 9.5251E-02 1.4197E-01 2.3182E-01 2.7427E-01 3.5259E-01 3.5259E-01 4.2020E-01	
7717502	-0.6 -2.67746-01 -5.12516-01 -6.62866-01 -7.58016-01 -8.18416-01 -8.51766-01 -9.15576-01 -9.15576-01	MY1 5-4853E+01 5-46646E-01 5-46646E-01 5-2964E-01 6-215455+01 4-514E+01 4-64938E-01 4-2028E-01 3-5756E-01	
COSTA	-0. -3.1732E-02 -5.6976E-02 -7.4728E-02 -9.688E-02 -9.688E-01 -1.0550E-01 -1.458E-01 -1.2539E-01 -1.7104E-01	GAMMA 3.8032E-01 3.9804E-01 4.4705E-01 5.1874E-01 7.0538E-01 8.0586E-01 9.1866E-01	
COS(TK)	-1.0000E 00 -9.5718E-01 -2.5679E-01 -7.4500E-01 -6.4648E-01 -5.631E-01 -5.031E-01 -4.1191E-01 -4.1191E-01 -3.7561E-01	##U 3.3117E 00 3.3311E 00 3.3847E 00 3.4779E 00 3.4179E 00 4.0861E 00 4.6666E 00 5.0178E 00	00 366 1001
PSI	0. 8.7266E-02 1.7454E-01 2.6180E-01 3.4907E-01 4.3435E-01 5.2360E-01 6.1087E-01 7.8540E-01 8.7266E-01	PSI 0.7266E-U2 1.7454E-U1 2.6180E-01 3.4907E-01 4.3631E-01 6.1087E-01 6.9813E-01 7.8540E-01	8. (2005-01

			н	TABLE VI (Cont'd)	t'd)			
RSI	DELTA 1	×	*		110	U-BAR	V-BAR	H-BAX
0. 8.72665-02	1.6594E-01	0. 1.0778F-01	1,23016	00 3.0769E	00 01	-01 8-3212E-01	8-7561E-02	0. 6.0708F=03
1.7453E-01	119162E-01	2.18186-01		00 3.14296	8		8-8287E-02	8.0325E-03
2.6180E-01	2117306-01	3.34156-01	m		8		8-9169E-02	1-1784E-02
3.4907E-01	2144965-01	4.5926E-01	1+2618E	00 3.3588E	8		940363E-02	1.5236E-02
4.36338-01	2.7045E-01	5.9833E-01	ш		8		9-1835E-02	1-83186-02
5+2360E-01	218992E-01	7.5843E-01	1.31368		00		9.3550E-C	2.0977E-02
6-10876-01	2.9910E-01	9.5104k-01	1.35826	_	00 1+0011F	_	9.5487E-02	2.31 FoE-02
6.9813E-01	219209E-01	1-1973E 00	"		00 1+2149E		9.7645E-02	2.43866-02
7.8540E-01	2.5827E-01	1.5449E 00	1.5449E	00 5,4651E	8	TO-3EESEPR 00	100105-01	2.6066E-02
8.7266E-01	1*6291E-01	2.16516 00			90	_	1-02836-01	2.6548£-02
	1Se	Ę		A2	NX2	AY2	MZ2	
	0. 8.726646E-02	.02 2.049210E	88	2,449992E-01 2,449522E-01	0. 7.135457E-02	-417671756E-01	3.381897E 00	
	1.7453296-01		8	2448129E-01	1.403797E-01	7415224845701		
	3.4906596-01	01 2.0517906	88	214427846-01	2.6395736-01	+34859796E-01	3.3979906 00	
	4.363323E-01	•	00	2.4389866-01	3.141446E-01	+3.308320E-01		
	5.2359886-01	_	8	21434547E+01	3-564167E-01	-21848797E-01		
	61108652E-01	_	88	214395245-01	3.896173E-01	-212823716-01	3.427510€ 00	
	2,052025-01		88	10-34066-01	70-377/66146	-1369C832E-03		
	110-32865-01		88	70-140413412	10-3866687*	+9134093ZE-0Z	3-454175E 00	
	8.726646E-01	·01 2.063272E	00	2.410332E-01	4.2805026-01	→11462250E-02	3-470046E 00	

			TABLE VI (Cont.d)	(Cont.d)			
PSI	MT-BAR 2		MN-BAR 2	MB-BAR 2		MN 2	DELTA 2
	•0-		-219634545 00	-14697139E 08	90	344251905 00	1.3974896
3.726646E-02	-1.026803E	3			00	3125818 (E 00	1.453406
	-1,829891£ 00	8			0	21886102E 00	1.4015416
10-3464191	-243688B9E	8	-1,892714E 00		00	24471808E 00	1 - 792911
1.490659E-01	1.490659E-01 -2.112286E 00 -	ဒ	-1454078E 00	-1.514542E	80	21094567E 00	
1.363323E-01	-2.932875E	00	-1,085971E 00		00	14793422E 00	
235988E-01	-3.079447E	8	-7.872122E-01		90	14548458E 00	٠
. 108a52k-01	-34809855	00	-54470882E+01		9	11353904E 00	
.981317E-01	-3.254447E	00	-3.522045E+01		3	11199959E 00	
*853982E-01	-31310185E	8	-11860066E-01		00	14079373E 00	•
1.720646E-01	-3.352736F	o	-3.887907F-03 -9.935880F-03	-9-035ABOF-	6	010250545-01	

MACH REFLECTION

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TABLE VI (Cont'd)

1808= 7

CALL NO. . I

0. 8.726646E-U2 1.745329E-01 2.617994E-01 3.490659E-01 4.363323E-01	1 Sd	0. 8.726646E-02 1.746329E-01 2.61794E-01 3.49059E-01 4.363323E-01	158
2.866119E 00 2.710533E 00 2.366515E 00 1.959745E 00 1.675906E 00 1.213386E 00	2 6600	2.873366E 00 2.726020E 00 2.374730E 00 1.969264E 00 1.587814E 00 1.232307E 00	NB1
4.265092E-01 4.471016-01 5.084387E-01 6.036278E-01 7.32387601 9.162864E-01		4.110448E-01 4.32877ZE-01 4.925270E-01 5.860078E-01 7.139304E-01 8.987727E-01	THETA
-0. -9.146360E-01 -1.631134E 00 -2.113157E 00 -2.418992E 00 -2.603055E 00	H&J	-0. -9.148747E-01 -1.531541E 00 -2.113722E 00 -2.420010E 00 -2.406381E 00	151
21868119E 00 24868271E 00 24874195E 00 24882040E 00 24871968E 00	r Z	2,873366E 00 2,875446E 00 2,881193E 00 2,188914E 00 2,1894409E 00 2,1883020E 00	*3
4.598628E 00 4.598628E 00 4.564257E 00 4.519414E 00 4.491620E 00 4.581099E 00	P4/P-INF	4.554718E 00 4.504727E 00 4.504727E 00 4.459746E 00 4.424527E 00 4.495577E 00	P3/P-INF
1.334597E-02 10 1.327465E-02 10 1.307863E-02 10 1.261918E-02 10 1.264519E-02 10 1.312793E-02	∽	0 1.343131E-02 0 1.338228E-02 0 1.324864E-02 0 1.307379E-02 1 1.295257E-02 0 1.320679E-02	\$3

4. Plane Shock-Conical Body Program Example

The following input data has been used as an example of the operation of this program:

$$M_{\infty} = 4.0$$
 $\delta_1 = 10 \text{ deg.}$
 $r = 2.5$
 $q = 2.0$
 $\Delta z = 0.05$
 $\tilde{\gamma} = 1.4$
 $p_{c}/p_{\infty} = 2.405 \text{ (15 deg. cone)}$
 $p_{b}/p_{\infty} = 2.80$
 $T_{c}/T_{\infty} = 1.31$
 $s_{2}/R = 0.067733$
 $\gamma_{c} = 0.3803 \text{ rad.}$
 $M^*_{1c} = 2.03183$
 $\psi_{1c} = 0.165935 \text{ rad.}$
 $\gamma_{b} = 0.261799 \text{ (15 deg.)}$
 $M^*_{1b} = 2.01128$
 $\psi_{1b} = 0.261799 \text{ rad.}$

The program output with the characteristic subroutine is included in this appendix and the symbols are defined in Appendix V-4.

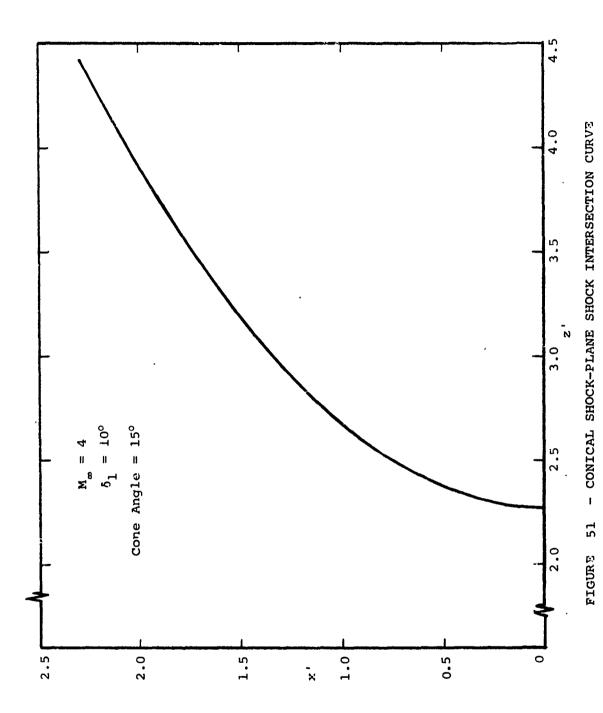
The intersection curve of the plane and conical shocks in coordinates on the plane surface is given in Figure 51. As noted on the first page of the output, this computation terminates when a so-called Mach reflection is reached, which means a cusped-normal shock intersection exists in the plane normal to the intersection curve. Figure 52 shows the variation of Mach number, pressure ratio and entropy in the lower intersection region, immediately behind the intersection curve (conditions 4) versus the slope of the curve with respect to the z' axes (Ω_i) .

The program next computes the intersection curve of the modified plane shock and the cone surface. To do this it is necessary to pick three points through which to construct the second order curve (Section E). The points chosen in this case are i = 1,4, and 10. This curve is terminated due to a Mach reflection. The flow properties M4 , p4 /p bi bi

and S_4 immediately behind the modified plane shock near bit the cone surface are shown in Figure 53 and differ somewhat from those in Figure 52 since the flow upstream of the modified plane shock is conical. The flow properties immediately behind the reflected shock on the cone surface are plotted versus the slope of the reflection curve on the conical surface, β , given by

$$\beta_{i} = \sigma_{6_{i}} + \tan^{-1} \left(\frac{M_{6_{N_{i}}}}{M_{6_{\overline{t}_{i}}}} \right)$$

in Figure 54. The pressure variation along the centerline on the cone surface obtained from the characteristic subroutine is given in Figure 55. The output of the characteristic subroutine is described in Appendix VI-2.



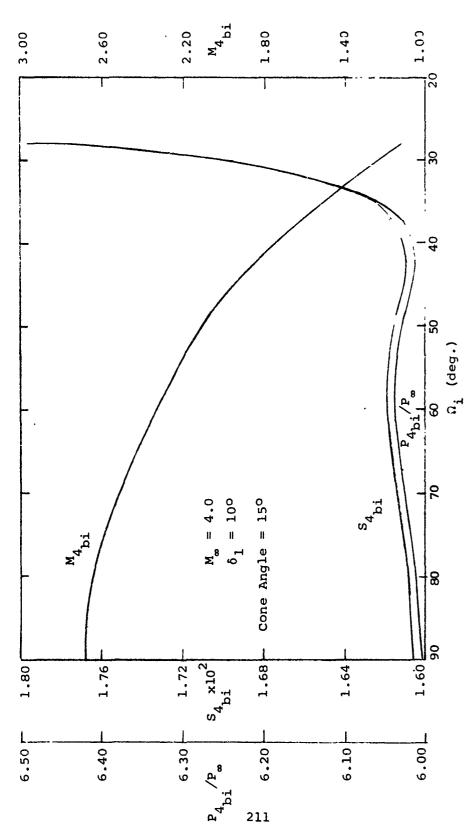
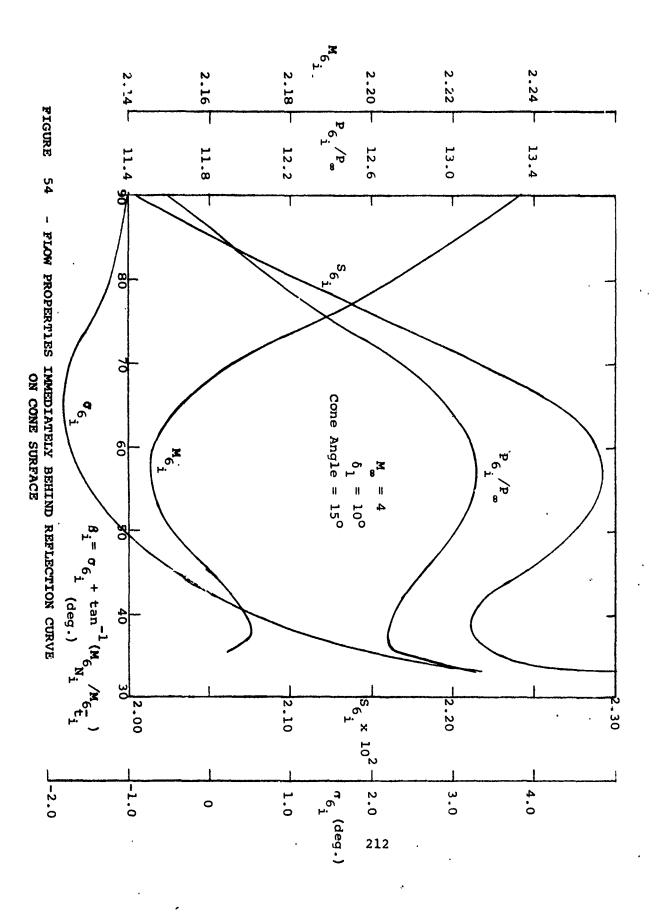


FIGURE 53. - FLOW PROPERTIES BEHIND THE MODIFIED PLANE SHOCK NEAR THE CONE SURFACE



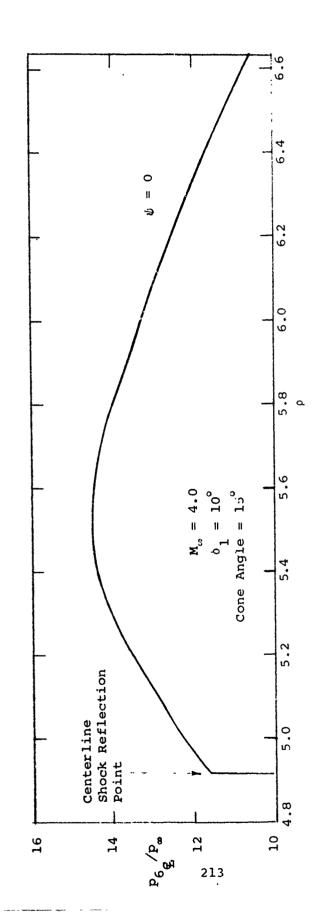


FIGURE 55 - CENTERLINE PRESSURE DISTRIBUTION ON CONE SURFACE BEHIND REFLECTED SHOCK

TABLE VII - SAMPLE OUTPUT FOR PLANE SHOCK

CONICAL BODY PROBLEM

PL. VIE SHOCK - CONICAL BODY MITH CHARACTERISTICS

阿尔姆斯

DELTA Z= 5.00~000E-02 TC/T-INF= 1.310000E 09 1= 2.5FFRANGE AD DELTA-1= 1.000000E 01 PC/P-INF= 2.405RNOE 00 G- 2.000000E 70 S2/N= 6.773300E=02 PB/P-INF= 2.800000E 00 DELTA-1 IN DEGREES ... MAINE 4. PRODUCE CO

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M1-STAR PSI-1 CAMMA

1.65935E-01 2.61799E-01 2.03183E 00 2.01128E 00 3.87300F-01 2.61799E-31

MT=-7.06449E-01 GAMMA-C= 3.8030CE-01 MR= 3.24491E 00

PI/P-INF 2.50604E 00 AI/A-INF 1.15294E 00 4-1= 3.28605E CO THETA-1= 3.88059F-01

MACH REFLECTION

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M2TP		7.76525E	.06C89E	2582£	987E	244E	63469E	72188E	3747F	38 SE	92277F	*97554E	02316F	30499	0590E	4217E	7561E	.20658E	.23537F	6221E	8731E	31C66E	33300E	5387E	7359E	.39225E	40995E	42677E	4278E	5804E	. 201E	48653E	.49986E	263E	489E	POPE	4798E	. 558872	.56937E	949E	926E	. 59869E	0781E	2E 00
Σ	°	7.76	1.05	1.25	-1.40987t	1,532	1.63	1.72	1.79	-1.86385E	1.92	1.97	2.02	2.06	-2.10	2.14	2.17	2.20	2.23	2.26	2.28	2.31	2.33	2.35	2.37	2.39	2.40	2.45	2.44	2.45	2.47	2.48	2.49	2,51263E	2.52489E	2.5366E	2.54	2.55	2.56	2,57949	2.58926	2.59	9.	7007
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1 -4.05110F-		5.956395-01			5.15547E 00	4.62733E-01	-7.45E-08
2 -7,453376-1		5.40147E-01	1.18108E 00		5.19052E 00	4.966836-01	•
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3 -7.85946E-02		7.24406E-01	1.15399E 00		5.26436E 00	5.60569E-01	-8.94E-08
4 -7.75225E-C.		7.643 TOE-01	1.13994E_00		5.39288E 00	5.90678E-01	2.98E-08
5 -7.03015r-07		3.03015E-01	1.12562E OO	5.16029E 00	5.34233E 00	6.19664E-01	1.495-08
5 -7.511111E-72	•	3.40422E-C1	1.11106E CO	5.19919E 00	5.38260E CO	6.47592E-01	-4.47E-08
7 -7.47650F-12		3.76666E-01	1.09632F no	5.23881E 00	5.42361E 00	6.74523E-01	-7.45E-08
9 7.232~7E-02	02 6496214E-01	9.11814E-01	1.08142E 00	5,27908E 90	5.46531E CT	. 7.00511E-01	-2.98E-08
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2 -4.54.456-0.5	1	1.04263E 00	1.020815.00	5.44564E 00	5.63774E 00	7.95972E-01	2.98E-18
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5 -5.480156-02	_	1.131835 00	9.74981E-01		5.77186E 00	8,597116-01	-5.96E-08
6 -5.627935-02	7.18091E-C1	1.160.095 00	9.59753E-01	5.61911E 00.	5.81733E 00	8.79623E-01	-8.94E-08
7 4.357635-02	7		9.44584E-01		5.86314E 00	8,98908E-01	-2.98E-08
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72 -1.57773E-C	7	- 1	8.70420E-01		6.09692E 00	9.86518E-01	-1-19E-07
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37 -1.2009AE-0	~	1.43119E 00	8.017896-01	6.12236E 00	6.33833E 00	1.06014E 00	-1.196-07
39 -2-66252E-03	7,75904E-01	1.45269E 00	7.892395-01	6.17000E 00	6.38765E 00	1.07312E 00	-2.98E-08
•	~	1.47454F CO	7.74784E-01		6.43580E 00	1.08701E OC	-2.98E-03
40 -44.3460AG-03	13 7.419605-01	1.499476 00	7.49798E-01			1.10712E 00	-5.96E-03
1 -1.923706-02	_	1.52404E 00	7.23850E-01	6.29674E 00			-2.98E-03
2 -2.843956-02	72 7.943476-01.	1,548315 00	6.96634E-01		6.55986E 00	1.14800E 00	2.986-04
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4 5,59694E-02	7.863325-01	1,59645F 00	6.35596E-01	6.41290E 00	6.63912E 00	1.19190E 00	-1.196-07

THREE POINT SELECTION I. 1 I* 4 I* 10

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		1.3057E-01	1.1382E-01	7.47675-02	6.2894E-02	4.6264E-02	2.74876-02	9.7647E-03	-9.2902E-03	-4.3433E-02	-5.95348-02	-7.4986E-02	-8.9792E-02	10-356501	-1.3028E-01	-1.42456-01	-1.53936-01	-1.6470E-01	-1.7475E-01	-1.84078-01	-1.9262E-01	10-32400-01	-2.07245-01	-2,1830E-01	-2.2235F-01	-2.2531E-C1	-2.2710E-01	-2.27626-01	-2.2436E-01	-2.2030E-01	-2.1439E-01	-2.06475-01	-1.8347E-01	-1.6743E-01	-1.49?78-01	-1.2707E-01	-1.0057E-01	0.	COS(TY))) •
1		9.6565E-01	9.6497E-01	10-35859-6	10-46200 -6	9.5787E-01	9.5456E-01	10-32905*6	9.4617E-01	10-36619	9.29898-01	9.2350E-D1	9-16648-01	9.09296-01	0.0143F-01	10-34148-8	8.7469E-01	H.5463E-71	8.5392E-01	8.4252E-01	8.30386-01	8-17426-01	1013470101	7.7281E-01	7.5566E-71	7.3715E-01	7.1711E-01	6.95346-01	6.4569E-01	6.1725E-01	5.8594E-01	5.51 39E-01	4. 700HE-01	4.2341E-01	3.7051E-01	3. L127E-01	2.4359E-01	0.	(213802)	
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		5.5961E-01	5.6022E-01	5.61256-01	# 6270E-01	5.66916-01	5.7014E-C1	5.74046-01	5.7852E-01	5.83566-01	10-3166-01	6-0201E-01	6.0926E-01	6.1703E-01	6.25346-01	4.36176-01	5.53376-01	6.6372F-01	6.7456E-01	6.8587E-01	6.9764E-01	7.0985E-01	7.2249E-01	1.36736-01	7.62686-01	7.7673E-01	7.9104E-01	8.0556E-01	10-316-01	8.4971E-01	8.6434E-01	8.7876E-01	10-348-01 10-348-01	9.1929E-01	9.3131E-01	9.4222E-01	9.51806-01	9.6593E-01 9.5978E-01	COSCOL	707704
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		-5.7419E-01	-5.7006E-01	-5.66016-01	10-36168-01	-5.5500E-01	-5.51356-01	-5.4797E-01	-5,4497E-01	-5.4236E-01	-5-40095-01	-5.36556-01	-5.3523E-01	-5.3416E-01	-5.3331E-01	10-32406-01	10-30016-01	-5.3174E-01	-5.3079E-01	-5.3022E-01	-5.2945E-01	-5.2840E-01	-5.2694E-01	-5.24955-01	-5.1X/8E-01	-5-1426E-01	-5.0849E-01	-5.0123E-01	-4-9220F-01	-4.6746E-01	-4.5097E-01	-4.3111E-01	-4.0737E-01	10-3//55*5-	-3-06526-01	-2.6040E-01	-2.0582E-01	-0.	COSTAX	700164
	1	8-1840E-01	8-2048E-01	8.2197E-01	8.22805-01	8.2248E-01	8.2109E-01	8.1878E-01	8-1561E-01	8.11636-71	8-0685F-01	7.94966-71	7.87876-01	7.80046-01	7.71465-01	7.62145-01	7-83065-01	1.7-32-05-71	7-17246-01	7.0406E-01	10-37C0P.0	6.75256-01	6.5959E-01	6.43066-01	6 25 55 - 1	5.8815E-01	5.68756-31	5.47046-01	5.2517E-01	4.79076-01	4.54916-01	4.3030E-01	4.0541E-01	10-36969	3.32248-01	3.0995E-01	2.8976E-01	2.5882E-01 2.7245E-01	000000	TOCIEV
		2.29126-02	4.2851E-02	6.3225E-02	8-3713F-02	1.04176-01	1.47761-01	1.71785-01	1.94368-01	2.17641-01	10-42165	10-11164*2	3.0461F-01	3.259nE-01	3.4703F-01	10 - 3 con co	10-35086-5	4.37621-01	4.5148E-01	4.7241F-01	4.93441-01	5.1452[-0]	5.35991-01	5.57598-01	5.70665-01	6.24198-01	6.4712F-01	6.7045F-71	10-11296	7.42981-01	7.57916-71	7. 930RE-01	8.18356-01	10-3046-01	8.920 9-01	9-14406-01	9.3471F-01	9.65938-01	00361621	COSINI
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- 34 44 4 4 4 A	1-3116-01	1.633696	ć		7.69715E-01			00
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1-435566-11	10-309041-9	1.623008	00	2.691186 00	7.354296-01	ш	-	60
0.46529E-01	4.75519E-11	1,62615	ပ္ပ	-	7.19481E-DI	-2.68052F.00	Ξ.	0
11-36E084.	6. 740 94F-1	1.624545	ç	-	7.041496-01		-	c :
16-3962050	1.2846-01	1,52348£	ç,	_	6.82410t-01	uÌ.	1.76389E	8
0.5268bE-A1	4.732135-01	1.62266E	ć	2,69336E 00	6.75242E-01	-2.69411E 00	1.75755E	9
9.52861E-01	6.745876-01	1,62218E	00	2.69356E QO	-6.61622E-01_	-2.69778E 00	1.75191E	8

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2.303106	2.29209E	2.28132E	2.270828	2.26062E	2.250765	2.24125F	2.23216E	2.22353E	2.21537E	2.2077CE	2.200528	318461.2	2 1 1 2 7 4 5	2 101645	2.172716	2.16776E	2.16377E		2.157766	2 155205	2.15163F	2.15039E	2.14950E	2-14897F	2.14884E	2.149 9E	2.149 7BE	2.15056F	7.157495	2.15354E	2.15453E	_ 2.15539E	2.15600E	2.15624E	2.155945	2.15291E	2.14966E	2.14480E
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9.80014E-01	9.71962E-01	9.63622E-01	9.55007E-01	9.46131E-01	9.37012E-01	9,273596-01	9.17370E-01	9.07136E-01	8.96681E-01	8.86023E-01	8.75177E-01	8.64157E-01	8.52976F-01	0-3017101 10-301701	D. 10230E-U1	8.06783E-01	7.94923E-01	7.82898E-01	L-70771E-01	7-585265-01	7.33681E-01	7.21082E-01	7.083646-01	6.95527E-01	6-694d 1E-01	6.56266E-01	6-42917E-01	6.29429E-01	6-157955-01	2.88026E-01	5.73934E-01	5.59628E-01	5.451256-01	5-30-116-01	5.15466E-01	\$-003716-01	4-69025E-01	4.52907E-01
1.79977E-02	1.78567E-02	1.17197E-02	1.75370E-02	1.74589E-02	1.73358E-02	1-72178E-02	1.71057E-02	1.699986-02	1.690036-02	1.58071E-02	1.672046-02	1-66400E-02	1.656596-02	1.649808-02	1.030025-02	1.633006-02	1.62854E-02	1.624646-02	1.62126E-02	1.618395-02	1.61411E-02	1.61265E-02	1.61163E-02	1.61101E-02	1.61986E-02	1.61127E-02	1.61195E-02	1.61285E-02	20-311619-1	1.616336-02	1.61749E-02	1.61849E-02	1.61921E-02	1.61948E-02	1.61913E-02	1.613606-02	1.611816-02	1.60617E-02
i						• • • • •	35586E	.35073E					-2.31414E 00		7 6			-2.24031E 00		-2.20617E 00	-2.16594E 00		m	-2.09148E 00	חה		1.95609E	m 1	-1.86625F 00		-1.688805 00		-1.52712E 00	1.42637E		-7 - 16024F 00	-7.069Z5E-01	9.97524E-08
5.56120E-01	5.79520E-0	6.02165E-0	6.2463AE-0	6.47219E-0	6.7C072E-01	6.88617E-01	7.070056-01	7.26410E-01	7.46824F-01	7.682486-01	7.906968-01	8-141856-01	8.387406-01	8-64397F-01	9-171716-0	9.4830[F-0]	9.78735F-CI			1.078176 00	1.151886 00		ų.	1.27505E 00	1.366597 00		•••		1.576035 00				1.89717E 00		2.04704E 09	2.12679F 00		T.

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DELTA-4	1.745336-01	1-92405E-01	2.05977E-01	2.16484E-01	2.24781E-01	2,31457E-01	2.369335-01	2.51510E-01	2.454176-01	2.48828E-01	2.51884E-01	2.54706E-01	2.573976-01	2.60053E-01	2.62766E-01	2.65625E-01	2.68722E-01	2.72156E-01	2.76030E-01	2.80464E-01	2.85592E-01	2.91570E-01	2.98589E-01	3.06877E-01	3.16719E-01	3,28476E-01	3.42613E-01	3-59742E-01	3.80686E-01	4.06577E-01	4.39005E-01	4-802 (4E=01	2.33789E=01	201010	0-344636-01	200000		ŀ		1.28832E 00	1.03008E 00	8-15840E-01	6.49240E-01	2441424E-VI
M488	-4.65439E-01	-5.04252E-01	-5.28189E-01	-5.41069E-01	-5.45755E-01	-5-44398E-01	-5.38615E-01	-5.29627E-01	-5.18357E-01	-5.05502E-01	-4.91592E-01	-4.77029E-01	-4.62120E-01	-4.47096E-01	-4.32136E-01	-4.17371E-01	-4.02936E-01	-3.88814E-01	-3.75153E-01	-3.61966E-01	-3.49233E-01	-3.37126E-01	-3.25510E-01	-3.14447E-01.	-3.03943E-01	-2.940034-01	-2.84629E-01	-2.75825E-01	-2.67591E-01	-2,59928E-01	-2.52841E-01	-2.46333E-CL	-2.404105-01	- C. 32031E-CL	-2.303385-01	Z-505555	-2.2280601	-2.200355-01	-2.16545E-01	-2.07425E-01	-1.98231E-01	-1-88950E-01		-1.67933E-01
#4NB	2.63964E 00	2.53836E 00.	2.52795E 00	2,46018E 00	2.38692F ON	2.3099 F. OD.	2.23058E 00	2.15017E 00				1.83219E 00	1.75554E NO	1.68032E 00	i	1.53415E CO		1.39320E CO		1.25658E CO	1.189586 00	1.12329E 00	1.057576 00	9.92298E-01		9.62626E-01	7.97998E-01	7.33366E-01	6.68628E-01	6.03588E-01	5.38457E-01	4. 72846E-01	4.06772E-01	3.4012/1-21	2.72920E-01	70-320 (5-0.7	1.462776-01	6.6705 RE-02	-1.430596-03	-6.01896E-02	-1.19018E-01	-1. 77686E-01	-2,357876-01	-2.92451E-01
4418	4.42776-09	4.73289F-01	7.055816-01	9.05471E-01	1.093706 00	1.237176 00.	1.37746F 10	1.52347E 00		1. 71882E 00	1.81084E On	1.89397E 00	_	2.04751E 00	-	_	_		2,23795E 90	_		2.43582E 30	_	2.45499E 00	•	2,51344£ no	2.53436F n0	2.55321E nn	2.5770ht Or	2.534c9E CC	w			_			<u>.</u> نند	J. 515050	2.63441E 00	2.63196E 00	2.42525E CC		2.01243E 30	2.67365F OD
T.	Jr 419.24	186125	15780E JC	_		Trastit.	JOSEP JO	10573F of	Ju albéal	טר אלףייוני	790136 10	.09766F 0.0	JC 36096C	06 345 200	002386 00	טר פווייטט	71 3C374C	טר אר יישר	14145	7777VF JC	77 37 87 70	Y JAPPAC	OK 165346	JC JC5090*	UL 14556.	JE1318 10	3, 36,36%	0 3675EU.	של של שצצני	. 12 Jr CC.	ος 311221.	or allale	יו אייוני.	JC 32040C*	.47763F-71	. 91592E-1	1.45418F-11	. 19253E-1	1.14n72E-0)	. 729106-01	11935F-11	1.71240E-71	. 70975E-11	.71428E-01

TABLE VII (Cont'd)

(CO)	TABLE VII
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	Řci z	A 55E #	-	I.I.A.I. cw	TA SER ICES
6.2117E-01 6.2789E-01 7.5941F-01		4.0862E-01 4.2837E-01 4.5081E-01	3.6475E-01 3.7680E-01	3.49176-01	THETADA
2.1118E 00 2.1267E 00 2.1861E 00	2.1509F 00 2.1361E 00 2.1226E 00 2.1131E 00	2.1772E 00 2.1742E 00 2.1644E 00	2.1044E 00 2.1473E 00 2.1697E 00	1.9295E 00	P6/P4
1.1194E 00 1.1207E 00 1.1258E 00	1.1228E 00 1.1215E 00 1.1204E 00	1.1251E 00 1.1249E 00 1.1240E 00	1.1187E 00 1.1225E 00	1.103CE 00 1.1125E 00	46/44
1.2728E 00 1.1781E 00 1.0627E 00	1.5247E 00 1.5247E 00 1.4433E 00	1.8435E 00 1.7643E 00 1.6848E 00	2.0793E 00 2.0009E 00 1.9223E 00	2.2396E 00 2.1584E 00	TABLE
1.8180E 00 1.8650E 00	1.4399E 00 1.6163E 00 1.691BE 00	1.2245E 00 1.3376E 00	6.3167E-01 8.0663E-01 9.6106E-01	4.0145E-09 4.2273E-01	TABLE VII (Cont'd)
2.1714E 00 2.1664E 00 2.1466E 00	2.1618E 00 2.1669E 00 2.1706E 00	2.1465E 00 2.1476E 00 2.1512E 00		in m	D
1.2716E 01 1.3144E 01	1.2793E 01 1.2793E 01 1.2730E 01	1.3145E.01 1.3125E.01 1.3063E.01	1.2685E 01 1.2956E 01 1.3098E 01	1.15880 01	P6/P-INF
2.2653E-02 3.7443E-02 6.0320E-02	1.7087E-03 1.1203E-02	-2.4350E-02 -1.9421E-02	-3.0544E-02 -3.0573E-02	0. -2.1795E-02	9-4-51S
2.2297E-02 2.2297E-02	2.2448F-02 2.2261F-02 2.2162E-02	2.2922F-02 2.2922F-02 2.2800F-02	2.2594E-02 2.2596E-02	2.0158t-02 2.1275E-02	ur T

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IN III

CHAFALTERISTICS PROGRAM

GAMMA= 1.430 P/P=11.588

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	2	184	THETA	S	3 .	e E	•	
				50-330305 5	2.14655F 00	4.84511E-01	6.92519E-01	
	1, 1 31 1 65 6 71	5.11219E-1	6.03204E-n2	20-36-962-7	0 1777011 C	4.79798E-C1	6.95824E-01	
	CC 331448	3 4 4 6 1 4 5 - 6 1	3.74431E-n2	2.22960E-12	00 190101	785(65-0)	7. 96649F-(1	
	7 T. U.S. T. S.	1-195894-4	2,205338-02	2,21364E-02	00 325 00 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	10303030	6.96520F-03	
_	0.00	7 7 7 8 6 5 7	1.120316-02	2.21618E-02	2.1705/E 00	1: - 00 1: 01	10-2000	
_	5.7.786F F	1 1 10 10 200	100176-03	2.22AN9F-12	2.16689E OO	4.796/55-01	10-3116-0	
	4.10152F O	1013455550**	I . (040) - I	3 3/6/3/3/2	2 14178F 00	4.909(AE-C1	6.950636-01	
	1 1000	10-35-22-01	-6.41440E-03	25-26/442*2	00 351 0T • 2	10-32243F-01	5.941436-01	
	, , , ,	17-47-81-37	-1,342875-02	2.263085-02	16 162061.7	- C-30+760 - 7	19-310826	
) • h · · · · · · · · · · · · · · · · · ·		-1 0420AF-02	2.27978E-02	2.15122F G	171360469*4		
-	2	1)11/26/50	20 0000	2 202236=02	2,1476CE CO	4.84353E-01	2.42040E-11	
_	() 10+050	3.524(1E-01	フローコノムもをち・スー	70 767767	000000000000000000000000000000000000000	4.84626F-01	6.925 <i>C</i> 9E+C1	
	10000	1,-35,001	20-31090x*2-	2.5461 35-12	764041.7	()-0770cc	13-400B	
			-3 12727E-(1)	2.28684F-C2	2.14919L 03	1	10 000000	
_		1 - 21 + C x 2 * F		2 250375-02	2.13737F OO	4.81972E-01	0.74724F - 1	
	1 4 1 2 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1	7,213916-01	-3.02447E-02	20-71166207	00 32122	4.781775-01	6.95949E-01	
	() 37 1 37 1 7	1.712338-01	-2.81739E-02	2.23/965-02	C 1010117	101111111111111111111111111111111111111	7.012336-01	
٠.			- 2 176566-02	2.12755E-02	2.19938E 00	10.00.00.00	10	
٠,	1 / 3. c. L. V. J	1 - LC - C - I - I	7	CA-310310 C	1,23960F CO	4.62860E-11	11	
•	CC 312427**	•	·.	3375/70*7				

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		į.		:		1				:	•			1.12836E-01 5.72039E-02	PSI		
	,		1										?	-2.17950E-02 -1.88131E-02	THETA	= 14 P/P-INE	TABLE VII (Cont'd)
		,	1		1								2.01581E-02	2.12755E-02 2.07406E-02	5	P/P-INF= 1.31958E 01	ont'd)
				•	٠	1	i i	i ! !		•	•		4.82170-01	4.72007E-01 4.72981E-01			-
												1		7.01233E-01	3	E	

6.96949E-01 6.97212E-01 6.97288E-01 6.90903E-01 6.88114E-01 4.78172E-01 4.7682E-01 4.86976E-01 4.91079E-01 ₹ 2.20796E-02 2.17274E-02 2.11111E-02 2.05920E-02 2.01581E-02 P/P-INF 1.39602E 01 THETA S TABLE VII (Cont'd) -2.81738E-02 -3.01225E-02 -2.71360E-02 -8.31418E-03 1.71233E-01 1.44115E-01 9.78293E-02 3.98672E-02 0. PSI 4.96414E 70 5.01350E 00 5.11461E 00 5.21887E 00 SH.X

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TABLE
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(Cont. o

4.43375E 00 2. 5.02328E 00 1. 5.17242E 00 1. 5.27330F 00 5. 5.33024E 00 5. 5.34295E 00 0.	<u>.</u>
	15d
-3.05443E-C2 -3.24435E-02 -3.43975E-02 -3.14983E-02 -1.25736E-02 -4.25226E-C3 0.	TABLE VII (COM: ") I= 12
2.25937F-02 2.23832E-02 2.20803E-02 2.14573E-02 2.08359E-02 2.04890E-02 2.01581E-02	= 1.43652E 31
4.80742E-01 4.80742E-01 4.79340E-01 4.80292E-01 4.80646E-01 4.93779E-01 4.95741F-01	š
6.943291-01 6.951771-01 6.96108E-01 6.95447E-01 6.89548E-01 6.862891-01 6.84964F-01	£

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1			TABLE VII (Cont'd)	nt'd)	•	
l I			I= 10 P/P-INF= 1.44486E 01	1.44486E 01		;
	SHO SHO	ISd	THETA	u	E	×
	5.03199E 0	n 3.12005E-01	2.87677E-02	2.29603E-02	4.84626E-01	6.92509E-01
	5 C6151E C	C 2.95374E-C1	-2.96936E-02	2.29275E-02	4.83721E-01	6.931286-01
-	5.0955oE)	0 2.76155E-01	-3.14267E-02	2.28636E-02	4.82732E-01	6.93807E-01
,	3 5.13549E ?	c _2.53632E-01	-3.33322E-02	2.27526E-02	4.81604E-01	6.94582E-01
·	4 5.13439E C	n 2.25436E-01	-3.528n6E-02	2.25635E-02	4.80374E-01	5.954296-01
··· (5 5,23409E 2	0 1.69536E-01.	-3.22838E-22	2.20502E-02	4.81395E-01	6.94720E-C1
· i	5.39166E 1	r 1.15059E-01	-1.34519E-02	2.14772E-02	4.90840E-01	6.882768-01
.	7 5.4362BE 0	9 8.51736E-02	-5.13028E-03	2.11433E-02	4.95006E-01	6.8545ZE-01
·	x 5.49806E 0	0 5.48405E-02	-8.65693E-04	2.08181E-02	4.96982E-01	6.84134E-71
	9 5,54016E 0	c 2.85613E-c2.	5.85683E-04	2.04997E-02	4.97404E-01	6.839516-01
2	5.50285F O	o	o.	2.01581E-02	4.96696E-01	6.84326E-CI

OH.≈	IS a	I= .9 P/P-INF THETA	P/P-INF= 1.42493E Q1 . TA	₽	*
	190015	-2.43497F-02	2.29223E-02	4.84353E-01	6.02596E-01
7	3. 32.9 JEC 1.	CO-344000 C	2.29349F-02	4.83496E-01.	6,93283E-01
5° 3815e of	3.2342/E-11	77 77 18 27 87	2 202225-02	4 . R2627F-01	6.93879E-01
5.11558E no	3.217~5E-C1	-2.762065-02	2.737C67.7	10 10 10 10 10 1	10-365-595 A
7C 3554F 3C	3.12544E-C1	-2.93538E-02	2,290516-02	TO-3700T0 * 4	10-10-10-10-1
10 DO 100 0	2 7093RF-01	-3-12545E-02	2.28393E-02	4.80606E-01	1:1-36026-0
30 1.71	10 2000000	23 32084F-02	2-27066E-02	4.79439E-01	6.969 (4E-UI
5.23351E 77	7-27-17-7	400 300 00	207056-02	4. A0551F-01	6.95307E-01
4.33932E nr	1.9616'E-01	-3.021(9E-02	30-36-35-3	101100000	A ARAZOF-OI
JC 317577 5	1-42907E-01	-1,13773E=02.	2.17640E-92	4.900295	1010000
40000	1 12555	-3.05427F-03	2.14517E-02	4.94220E-01	16-324669
ひ。4 29 4 4 7	1 7/////		3 113005-02	4-96206F-03	6.84655E-01
J. 3060+6.c	8.55325t-r2	1.410446=(3	7 7. 5. 5. 7. 7. 7.		A.84367E-01
Or 341565.8	5.74137E-02	2.65207E-03	2.081/4E=02	10-300301	0.000000
00 000	2 R9 15 3 F- 17	2.07572E-03	2.04890E-02	4.959.32E=01	0.0000000
20 20 20 20 0	4. 4. 4. 7. 7. 7. 7. 7. 7. 7. 7. 7. 7. 7. 7. 7.		2 015816-02	4.94410E-01	6.85865E-UI
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	,		TABLE VII (Cont'd)	Cont'd)		
	슈	15 I =	B P/P-INF	P/P-INF= 1.39492E 21	3	E
	UC Janker s	1.915276-01	-1.942)8E-02	2.279945-02	4.834696-01	6.93301
_	5.11260E 00	3.79257E-C1	-2.11801E-02	2.28372E-02	4.82577E-01	6.93913
	5.138798 00	3.64606E-01	-2.28180E-02	2,28700E-02	4.817476-01	6.94484
	5.16893E 00	3.47946E-01	-2.445JBE-02	2,28928E-02	4.80911E-01	6.95059
	5.21367E 00	3.287046-01	-2.618401-92	2.289776-02	4.80004E-01	6.95684
	5.24429E 20	3.06152E-C1	-2.80838E-02	2.287236-02	4.78978E-01	6.96392
	5-29418E 00	2.78423E-01	-3.00391E-02	2.27920E-02	4.77873E-01	6.97156
-	5.374316 00	2.22807E-C1	-2.70492E-02	2.24580E-02	4.79079E-01	6.96322
-	CC 7 [654.2	1.709336-61	-8.20652E-03	2.201486-02	4.88607E-01	6. 49793
Ī	5.542426 00	1.42271E-01	1.17329E-04	2.17335E-02	4.92805E-01	6.86945
•	5.59478E 70	1.144166-01	4.38256E-03	2.14412E-02	10-380846-01	6.85596
_	5.64539E 00	8.62E-C2	5.83347E-03	2.113326-02	4.95251E-01	6.85297
-	0. 3126e0.5	5.81206E-02	5.246208-03	2, 181296-02	4.94561E-01	6.85762
	5.723895 70	2.92492E-C2	3-159176-23	2.04859E-02	4.93050E-01	5:86781
-	5.87867F nc		·	2.01581E-02	4.90952E-01	F , 852000
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x	6.94143E-01 6.95439E-01 6.95439E-01 6.95996E-01 6.96595E-01 6.97159E-01 6.97655E-01 6.97665E-01 6.97665E-01 6.97665E-01 6.97665E-01 6.97695E-01 6.86941E-01 6.86941E-01 6.86941E-01
ſ₩	4.822.43E-01 4.81232E-01 4.79591E-01 4.778142E-01 4.7781E-01 4.7781E-01 4.7781E-01 4.7781E-01 4.9791E-01 4.97017E-01 4.9241E-01 4.92736E-01 4.92736E-01 4.92736E-01
P/P-INF= 1.35796E 01.	2.26308E-02 2.27274E-02 2.27274E-02 2.27760E-02 2.28516E-02 2.28516E-02 2.28516E-02 2.28516E-02 2.22316E-02 2.17159E-02 2.17159E-02 2.17159E-02 2.17159E-02 2.17159E-02 2.17159E-02 2.17159E-02 2.17159E-02
I= 7 P/P-INF: THETA	-1,34287E-02 -1,54414E-02 -1,72936E-02 -2,22938E-02 -2,41097E-02 -2,41097E-02 -2,60591E-02 -2,50591E-02 -4,22615E-03 4,098+2E-03 8,35358E-03 9,35358E-03 9,35358E-03 9,35358E-03 9,35358E-03 9,35358E-03 9,35358E-03
12 0 81	4, 2808 / E-01 4, 1742 3E-01 4, 04951 E-01 3, 9751 7E-01 3, 5443 7E-01 2, 0453 4E-01 2, 0453 4E-01 2, 0453 4E-01 1, 0453 4E-01 1, 0453 4E-01 1, 0453 4E-01 1, 0453 1E-01 1, 0453 1E-01 1, 0453 1E-01 1, 0453 1E-02 2, 054 13 E-02
Skin	5.12143# 00 5.1455# 00 5.10411# 00 5.2024# 00 5.2024# 00 5.2024# 00 5.44200 00 5.44200 00 6.44200 00 6.44200 00 6.44200 00 6.4234# 00 6.4334# 00 6.43

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6.03287E no	5.97581E 00		,	5.90721E 00		5.7007E 00	5.648446 00	5.59593E 00		5.402125 00	5.35102E 00	5.30936E 00	5.27370E 90	5.24275E 00	5.21582E09	5.19247E 00	5.17241£ 00	5.15547E no	кHO		
ი•	2.97699E-02	5.92974E-02	8.84639E-C2	1.17134E-01	1.45173E-01	1.72509E-01	1.99314E-01	2.26788E-01	2.76026E-01	3.375458-01	3. 58093E-01	3,805756-01	3.99640E-01	4.16216E-01	4.30613E-01	4.43069E-01	4.53743E-01	4.62734E-01	PSI		
0.	4.58150E-03	8.55976E-03	1.17325E-02	1.38126E-02	1.44020E-02	1.29525E-02	8.69729E-03	3.62310E-04	-1.84820E-02	-2.147)7E-02	-1.95212E-02	-1.76156E-02	-1.58828E-02	-1.42505E-02	-1.26132E-02	-1.08545E-02	-8.84235E-03	-6.41440E-03	THETA	= 6 P/P-IN	The second of th
2.01581E-02	2.04734E-02	2.07914E-02	2.11057E-02	2.14094E-02	2.16949E-02	2.19553E-02	2.21.851E-C2	2.23860E-02	2.26669E-02	2.28197E-02	2.28127E-02	2.27747E-02	2.2722CE-02	2.26632E-02	Z.26036E-02	2.25465E-02	2.24942E-02	2.24479E-02	· ·	P/P-INF= 1.31634E 01	40000
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ď	5.13052E no	4.95598E-01	1.70857t-03	2.228091-02	4.79675E-01	6.95911E-01	
•	5.23484E 00	4.88154E-01	-1.35263E-03	2.23184E-02	4.78112E-01	6.96990E-01	
. ~	5.22217E 90	4. 79142E-01	-3.77935E+03	2.23639E-02	4.76895E-01	6.97833E-01	
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۰,	2.25634E 00	4.55047E-01	-7.55023E-03	2.24769E-02	4.75058E-01	6.99108E-01	
_	5.23369E OU	4.41703E-01	-9.18738E-03	2.25423E-02.	4.74281E-01	6.9964BE-01	
· -	5.375C9E OC	4.25199F-01	-1.08190E-02	2.26108E-02	4.735 !1E-01.	7.00184E-01	
	5.35126E 00	4.05151E-01	-1.25514E-02	2.26786E-02	4.72651E-01	7.00756E-01	
ļ	5.4.751E OF	3.83845E-01	-1.44557E-02	2.273ABE-02	4.71776E-01	7.01394E-01	
i -\$	5.45529E nr	3.564416-01	-1.64060E-02	2.27791E-02	4.70820E-01	7.02062E-01	
عي ر	5.53719F OC	3.02553E-01	-1.34178E-02	2.27054F-02	4:722746-01	7.01047E-01	
1	5.648A1E 00	2.54728E-01	5.42672E-03	2.25040E-02	4.81870E-01	6.94399E-01	
7	5.70120F 30	2.27931E-01	1.37519E-02	2.23466E-02	4.86174E-01	6.91484E-01	
٠,٠	5.75268E OF	2.01592E-C1	1.80169E-02	2,21549E-02	4.89200E-01	6.90069E-01	
7	5.87589E 00	1.745836-01	1.94657E-02	2.19270E-02	4.88727E-01	6.89711E-01	
c	5.R5074E 00	1.46773E-01	1.88751E-02	2.16677E-02	4.88119E-01	6.90124E-01	
. =	5.41694E JO	1-18257E-01	1.67935E-02	2.13843E-02	4.86686E-01	6.91101E-01	
٠.	5. 97410E JC	8.91359E-02	1.36185E-02	2.10846E-02	4.84659E-01	6.92486E-01	
۳.	6.03187E 00	5.97087E-02	9.63856E-03	2.07759E-02	4.82210E-01	6.94166E-01	
. 4	00 3986E 00	2.99489E-02	5.054805-03	2-04650E-02	4.79460E-01.	6.96059E-01	
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TABLE

VII (Cont'd)

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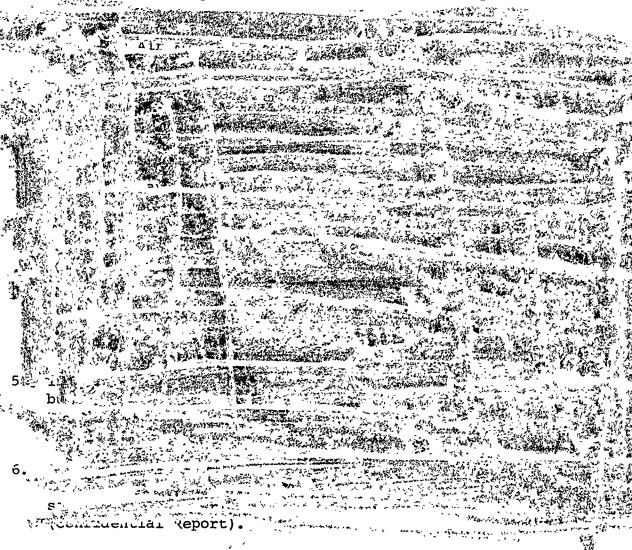
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Ę		PSI	THETA	Ŋ	₽	3
4 , A F	ž	56396F-1	2.26533E-02	2.21364E-02	4.786n6E-01	6.966
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5925	رد	5.45749E-01	1,305346-02	2-21497E-02	4.73637E-01	7.000
1116	ç	5-192216-01	2. 99262E-03	2.21655E-02	4.72089E-91	7.011
925E	ç	5.29153E-01	7.56600E-03	2-21899E-02	4.70863E-01	7.020
364c	ς,	5-19527E-01	5-55461E-03	2,22242E-62	4.69872E-01	7.027
5 76	٥	5.06275E-01	3.79702E-03	2.22694F-02	4.69024E-01	7.033
331E	c c	4.92013E-01	2.16036E-03	2.23259E-02	4.68252E-01	7.038
5,98	5	4.75704E-01	5.29875E-04	2.23931E-02	4.67494E-01	7.043
1906	5	4.56391E-31	-1.20192E-03	2.24695E-02	4.26697E=01	7.049
	ور	4.34964E-01	-3,106945-03	2.25518E-02	4.65821E-01	7.055
	ć.	4.07832E-21	-5.05456E-03	2.26341E-02	4.64924E-01	7.062
3316	5	3.553406-01	-2.06659E-03	2.26832E-12	4.66477E-01	7.051
310E	5	3-11147E-01	1.67775E-02	2.26183E-02	4.76050E-01	486.9
170E	٦c	2.84994F-C1	2.51026E-02	2.25429E-02	4.80318E-01	6.954
5716	٥	2.59538E-01	2.93671E-02	2.24296E-02	5.92445E-01	0.940
7.1E	<u>ر</u>	2.33363E-11	3.081465-02	2.22753E-02	4.83943E+01	6.935
535£	۲,	2.06100E-C1	3.02219E-02	2-20815E-02	.4.82513E-01	6.939
465F	ç	1.779905-01	2.81375E-02	2.185336-02	4.81170E-01	6.948
357E	۲	1.47213E-01	2.49533E-02	2.15977E-02	4.79225E-01	6.962
16.50	ç	1.19937E-01	2.09748E-02	2.13223E-02	4.76850E-01	6.978
374E	۶	4.71714E-02	1,63826E-02	2410345E-02	- 427170E-01	6-997
43.1F	٠ 0	20-39265-02	1.132706-02	2.07409E-02	4.712646-01	7.017
36 F. 4	ړ	3.13112E-02	5.96601E-03.	2404472E-02	4x68181E=01	7.039
55.7F	ć	c.	c c	2.01581E-02	4.64930E-01	7.062

•) 1	1	Park Total	:	=
ب	(H)	2	I HE I A	,	3	ε
J	5.31704F 10	10-441646	3.744116-02	2.229666-02	4.797946-01	6.95H2bF-01
عدا	5.33904E DE	5.913J2E-C1	2.927476-02	2.22764E-02	4.754135-01	0.98862[-0]
•		5.76557E-C1	2.35011E-02	2.22528E-02	4.725136-01	7.008406-01
Ţ	5,332375 ~	5.703925-01	1.94738E-02	2,22309E-02	4.704295-01	7.1.23366-01
3	5.3.7112 3.	5.62797F-01	1.64129F-02	2:22147E-02	4.689546-01	1-1344 18-01
7	5.30052E ??	5.5375cE-21	1.398536-02	2.220786-~2	4.67617E-C1	7.043036-11
ı		5.431746-61	1.197496-02	2.221290-02	4.666046-01	7.057278-71
٤	5,41321E ~@	5.3~927E-C1	1.021756-02	2+22321E-02	. 4.65747F-01	7.1553(E-01
,		5.16+38F-01		2.726676-02	4.64953[-7]	7.(+ 1 45.6 1
-	5.47446F 01	10-36560.5		2.231716-72	4.641858-01	7.0c726F-1
2	5.512756 70	4.81995E-J1	5.219996-03	2.23827F-02	4.633466-01	7.672926-01
٠,٠	5.555006 70	10-384109.4		2.24614F-72	4-62514E-01	7-(79296-0)
٠	5.611116 70	4. 133526-01		7.25499E-02	11116919.4	7. F534E-1
J	5.715676 00	3.815386-01		2,263456-02	4.5320 15-01	7.74175-01
	5.47457E 00	10-365188 *		2.262595-02	4.727416-11	7.007214-01
7	5.おしいつみだ つつ	3.13473E-C1	3.15249E-02	2.25851E-02	4.770046-01	0.977586-~1
ىد	2. 36 1k. b. s	2.04661F-C1		2.250856-02	4.791445-01	6.46.274F-CL
•	5.952798 30	2.529226-01	,	2.23915E-92	4.797825-01	1د-18834 • ٥
7	4. JESPIC. A	2.359676-01	3.66424E-02	2.22337F-02	4.793616-01	6.961596-61
_	6.07821E 00	2-096196-01	3.45557E-02	2.203838-02	4.780016-01	6.97067E-71
`	4.11324F OF	1.79451F-C1	3.137546-72	2.181126-72	4.761058-71	4.98181-11
w		1.50339E-31	2.739)5E-C2	2.155922-02	4.737776-01	1)-366066
4	4.25772E 70	1.209296-01	2.290)08-02	2.1289AF-02	4.71141E-01	7.018346-01
٠,	6.32250E no	9.1025CE-02	1.77331E-02	2-100965-02	4.68275E-01	7,038466-1
,	6. 38441E CO	\$-09858E-03	1.22745F-02	2.07746F-02	4.65229E-01	7.05990E-01
7	0. 344544E 00	3,069734-62	6.476906-03	2.043976-02	4.620105-01	7-182565-01
I	6.57895E 00	?	•	2.015R1E-02	4.585626-01	7.107176-01

3	6.92519E-01	6.98109E-01	7.01181E-01	7.032496-01	7.047596-01	7.05917E-01	7.068376-01	₹ 7.07594E-01	7.08245E-01	7.08833E-01	7.09401E-01	7.09986E-01	. 7.10614E-01	7.112426-01	7.10117E-01	7.03432E-01	7.00466E-01	6.98966E-01	6.98505E-01	6.98808E-01	6.99676E-01	7-009596-01	7.02548E-01	7.04361E-01	7.06345E-01	7.C8468E-01	7.10726E-01	7.13161E-01	7.15975E-01
₽	4.84611E-01	4.76497E-01	4.72381E-01	4.69126E-01	4.669765-01	4.65333E=01	4.64029E-01	4.62958E-01	4.62040E-01	4.61210E-01	4.604116-01	4.59588E-01	4.587065-01	4 57826E-01	4.594046-01	4.68864E-01	4.731076-01	4.75262E-01	4.75926E-01	4.75489E-01	4.74241E-01	4.72399E-01	4.70127E-01	4.67542E-01	4.64725E-01	4.61725E-01	4.58549E-01	4.551.40E-01	4.512216-01
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THETA	4.03204E-02	4.50038E-02	3.66364E-02	3.106335-02	2.70314E-72	2,396945-02	2.15421E-02	J. 95303E-02	1.77727E-02	1.613295-02	1.45054E-02	1.27756E-02	1.0H722E-02	8492475E-03	1.191336-02	3.07555E-02	3.99.814E-02	4.33453E-02	4.47918E-C2	4.41973E-02	4.21134E-02	3-892396-02	3.49426E-02	3.03430E-02	2.52835E-02	1.98173E-02	1.39459E-02	7.537136-03	ځ.
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DOCUMENT CONTROL DATA - R & D (Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified) 28. REPORT SECURITY CLASSIFICATION General Applied Science Laboratories, Inc. Unclassified A Subsidiary of The Marquardt Corporation 26 GROUP Investigation of the Low Speed Fixed Geometry Scramjet Inlet Design Practice Manual 4 DESCRIPTIVE NOTES (Type of report and inclusive dates) Technical Report - September 1966 to August 1967 5 AUTHOR(S) (First name, middle initial, last name) Edited by Johnson, James 6 REPORT DATE 78. TOTAL NO OF PAGES 75. NO OF REFS 17 February 1967 241 94. ORIGINATOR'S REPORT NUMBER(S) SA. CONTRACT OR GRANT NO F-33(615)-67-C-1084 TR-667 3012 9b. OTHER REPORT NO(5) (Any other numbers that may be assigned this report) AFAPL-TR-68-7 10 DISTRIBUTION STATEMENT This report is subject to special export controls and each transmittal to foreign governments or foreign nationals may be made only with the prior approval of the Air Force Aero Propulsion Laboratory wright-Patterson AFR. Ohio 45433. Air Force Aero Propulsion Laboraonly with specific prior approval of the Air Force Aero Propulsion Labora-tory Wright-Patterson AFB Ohio 45433 tory, Wright-Patterson AFB, Ohio 45433

Computer programs have been written to aid the design and analysis of 2-D, axisymmetric, and 3-D supersonic inlets. This report presents the fundamental analytic techniques, the use and operation of the computer programs, and the application to the design of supersonic inlets. The programs are written in FORTRAN IV for use on the 7094 high speed digital computer.

The 2-D and axisymmetric programs presented herein are written for generalized inviscid supersonic internal flow problems with uniform or non-uniform inlet entry conditions for entropy, total enthalpy, pressure, Mach number and flow direction. The program capabilities include the intersections and reflections of both family waves, the formation of shocks or expansions at corners, the formation of shocks by coalescence of waves from smooth walls, and the formation of contact discontinuities.

The 3-D programs presented herein are written for the calculation of the inviscid supersonic flow fields associated with basic elements of 3-D supersonic inlets. The methods utilized exact and linearized supersonic flow theory with engineering approximations to yield solutions to the following unit problems; delta wing flow, conical shock interacting with a plane surface, plane shock interacting with a conical surface, and the interaction of two different conical flow fields.

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