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DUAL DIAMETER ROLLER BEARING - 3.5 MILLION DN-600F

John Rumberger, et al

Franklin Institute Research Laboratories

Prepared for:

Air Force Aero Propulsion Laboratory

May 1973

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DUAL DIAMETER ROLLER BEARING - 3.5 MILLION DN-600°F

> John Rumbarger Edmund Filetti James Dunfee David Gubernick

Franklin Institute Research Laboratory

TECHNICAL REPORT AFAPL-TR-73-23

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John Rumbarger Edmund Filetti James Dunfee David Gubernick

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FOREWORD

This report was prepared by the Franklin Institute Research Laboratories, 20th and Benjamin Franklin Parkway, Philadelphia, Pa. 19103 under USAF Contract F-33615-71-C-1883. The work was administered under the direction of the Air Force Aero Propulsion Laboratory, with Mr. John Jenkins and Mr. M. R. Chasman (AFAPL/SFL) acting as project engineers.

This report covers work conducted from 23 June 1971 - 31 December 1972.

The Franklin Institute Research Laboratories was prime contractor and performed all of the analysis and design. The prototype test bearings were manufactured by the Bower Bearing Div., Federal-Mogul Corp., Detroit, Mich. The prototype testing was accomplished by subcontractor Midwest Aero Industries Div., Pure Carbon Company, Saint Mary's, Pa. The testing was under the direction of Mr. Donald Moyer of MAIC.

Publication of this report does not constitute Air Force Approval of the report's findings or conclusions. It is published only for the exchange and stimulation of ideas.

> HOWARD F. JONES, CHIEF Lubrication Branch Fuels and Lubrication Division

-ii-

ABSTRACT

Five gas turbine engine mainshaft roller bearing configurations were investigated for capability of sustained performance at DN values (Bore in mm x Speed in RPM) f om 2 million to 3.5 million and normal operating temperatures to 600°F. A unique Dual Diameter Roller was selected for the final analysis of stress and lubrication parameters, design and fabrication. A 140 mm Bore Dual Diameter Roller Bearing operated successfully for 30 min. continuous operation at 25,000 RPM (3.5 million DN) with stabilized outer race temperatures above 525°F. Lubrication was with Polyphenyl Ether 5P4E in an air environment.

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SECTION I

INTRODUCTION

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The objective of this research program was to develop a long life, high speed roller bearing design for future high performance turbine engines. The bearing must be capable of sustained performance at DN values from 2.0 x 10^6 to above 3.5 x 10^6 and normal operating temperatures to 600 F while maintaining the rotating shafts within the necessary tolerance for optimum compressor and turbine performance.

The trends in turbine engine technology are toward increased rotational speed, larger bearing diameters and increased bearing temperature. It is anticipated that bearing DN requirements (bearing bore mm x rpm) will grow from the current 2×10^6 or less to greater than 3.5×10^6 in the 1980's. Efforts to increase bearing DN capability are currently aimed at ball bearings. Approaches being investigated for ball bearings include hollow balls and compliant races. The roller bearing has received very little attention. Efforts which have focused on roller bearings indicate that variations in roller bearing geometry such as the dual diameter roller and hollow rollers, show promise for significant increases in bearing performance. Improved ball and roller bearing capability is required for future systems.

Known current roller bearing types were investigated in order to select a preliminary configuration for further development. The selection was based on the potential of each type to meet the capabilities shown in Table I. A bearing bore of 140 mm was selected for this preliminary configuration study.

The results of the preliminary configuration study resulted in the selection of the dual diameter roller bearing concept for further consideration. This selection was based upon lower cage speeds obtained in

the dual diameter bearing which result in significan ly lower that ' mechanic losses (viscous loss due to shearing of the oil). These lower drags or losses in turn result in a lower cage slip threshold.

Table I

BEARING OPERATING REQUIREMENTS

Normal Operating Temperature	600°F
Operating Temperature Range	-65 to +800°F
Normal Operating DN (mm x rpm)	4.0 × 10 ⁶
Operating Radial Load Range (lb.)	0 to 2000
L ₁₀ Life, Hr. (greater than)	1000
Radial Deflection at Max. Load, (in.)	0.010
Minimum Heat Generation	

The dual diameter roller bearing configuration was subjected to a thorough analysis from which a final design was developed. A complete systems analysis incorporating the latest available elastohydrodynamic lubrication technology and including fluid drag forces and thermal etfects was accomplished by means of a digital computer program (Reference 1). This analysis was used to finalize the bearing design and determine operating clearances and oil flow or lubrication requirements of the bearing. Complete detailed working drawings of the prototype test bearings are contained in the body of this report.

Six prototype dual diameter roller bearings were manufactured by the Federal-Mogul Corporation, Bower Bearings Div., Detroit, Michigan, to the drawings and specifications contained in this report. A summary of inspection data relating to dimensional quality of the test bearings is also included.

Two dual diameter prototype roller bearings were tested by the Midwest Aero Industries Div., Pure Carbon Co., St. Mary's, Pa. on a special high speed mainshaft test rig. The test bearings were operated

initially with MIL-L-7808 lubricant at 250°F oil inlet and then later with Folyphenyl Ether 5P4E lubricant at 600°F.

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SECTION II

SELECTION OF PRELIMINARY CONFIGURATION

1. CANDIDATE BEARING CONFIGURATIONS

Five basic concepts or candidate bearing configurations, as shown on Figure 1(a-d), were investigated. The reasons for considering the various configurations are listed below:

- a. Solid rollers inner land riding cage: The inner land riding cage solid roller concept, Figure la, is one of the most commonly used mainshaft roller bearing designs. This design consists of an inner race with two integral shoulders to guide the roller complement. The one piece fully machined cage has close clearance and rides on an oil film in contact with the lands on the inner race. The outer race is a sleeve construction which allows complete axial freedom of the inner race and roller complement. It is common in some designs to provide coolant flow through slots under the inner race since the inner race operating temperature. An advantage of this type of cage construction is the fact that friction in the cage to land areas will help to drive the cage at synchronous or epicyclic speed.
- b. Solid roller outer land riding cage: This outer land riding concept, Figure 1b, is very similar to the concept above; the main difference being that the integral guiding flanges and the cage to race land guidance are on the outer race. This bearing configuration is also common in modern jet engines. The advantage of this type of construction is better retention of oil at the outer race contact (due to centrifugal forces) under momentary oil starvation. Also some engine applications are more easily assembled with this type of roller guidance. It should be noted that in this configuration the friction in the cage to land surfaces is a dissipative effect which will tend to place a drag on the cage and add to the cage slipping tendency.
- c. Hollow roller concept: The roller bearing concept is shown in Figure 1c. This concept can be applied to either an inner land riding cage or an outer land riding cage configuration. Basically the use of a hollow roller reduces the outer race to roller loading. The centrifugal force on the outer race due to



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Figure 1(a). Solid Rollers - Inner Land Riding Cage



Figure 1(b). Solid Rollers - Outer Land Riding Cage

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Figure 1(c). Hollow Roller Concept

the cage and roller complement rotative speed results in significant contact loading. Hollow rollers of less mass than solid rollers are found to be beneficial. A note of caution is indicated in that prior experience shows that too thin a wall section in the hollow rollers will lead to roller breakage due to reverse bending of the rings. Thus mass reduction must be compromised with ring bending fatigue properties. Attempts have been made in the past to use three or more oversized hollow rollers equally spaced in a solid roller complement to provide rollers which are always inder load and essentially drives the cages up to cyclic speed. The effect which was analyzed in the preliminary selection of configurations was the mass reduction effect only.

- Series hybrid bearing: The series hybrid bearing is a relatively d. new concept, Figure 1d, for reducing the effective speed of rotation at the inner race of a mainshaft roller bearing. This concept consists c' a rolling element bearing and an bil film journal bearing in series. The inner race of the roller bearing is separated from the outer surface of the rotating shaft by means of the hydrodynamic oil film bearing. Both bearings carry the full radial load, however, the inner race of the rolling bearing will rotate at some intermediate speed to the shaft speed resulting in a lower effective DN operating regime for the roller bearing. The speed reduction is the main advantage of this configuration. Additional under race cooling of the inner race can also be accomplished if locating oil film thrust bearing surfaces are built as pumps to supply additional coolant flow under the inner race. These locating thrust bearings to maintain the location of the inner race are not shown on Figure 1d. The main disadvantage is the obvious one of mechanical complexity.
- e. Dual diameter roller concept: The dual diameter roller concept is shown in Figure 2. This is basically a wagon wheel shaped roller with a large central diameter and two smaller diameters which look very much like an axle through the main wheel. The purpose of this configuration is to reduce cage operating speed. A reduction in cage orbital speed results in a significant reduction of the outer race to roller contact load due to centrifugal effects.

The relative kinematics of a conventional roller bearing and a dual diameter roller bearing are shown in Figure 3. The large outer diameter of the two-diameter roller contacts the inner race surface. The small coller diameters of the two-diameter roller contact the outer race surface. The effects of the relative kinematics are shown graphically in Figure 4. With a small roller (50% of the major roller diameter) it can



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SERIES HYBRID BEARING (Reduce Roller Bearing Inner Race Speed)

Figure 1(d). Series Hybrid Bearing



Figure 2. Dual Diameter Roller Bearing Configuration



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Figure 3. Kinematics of Dual Diam. Roller



Figure 4. Relative Kinematics of Dual Diameter Roller

be seen that for the same inner race speed, a cage rotative speed 1/3less than that of the conventional bearing can be achieved. At the same time the roller rotative speed about its own axis is about 1/3 greater in the dual diameter roller than in the conventional roller design. This increased roller rotative speed enhances the entrainment velocity which is important in the development of a full elastohydrodynamic oil film in the contacts. Higher entrainment velocities of the two-diameter roller will essentially result in thicker EHD oil films in the contact. Thus a 4.0 x 10^6 DN bearing of the two-diameter roller configuration will result in cage rotative speeds and resulting centrifugal effects at the roller to outer race contact comparable to those found in a 2.67 x 10^6 DN bearing of conventional design.

2. LOAD-LIFE PARAMETRIC STUDY

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Initial calculations indicated that the requirements for greater than 1,000 hours L-10 operating life at 4.0 x 10^6 DN could not be achieved with 2,000 lbs. radial load. The 2,000 lb. load is representative of momentary maneuvering loads and not intended as a long time operating load condition for design of mainshaft bearings. The duty cycle given in Table II was used for the parametric study.

A special short length computer program was used for the parametric study and consisted of a full load deflection analysis of the bearing with elastohydrodynamic films in the race roller contacts. The EHD film thicknesses were computed per the classical isothermal Dowson-Higginson formulas (Reference 2). This is a simplification in that no cage slip was considered. However, for the purposes of load life studies this is a valid assumption especially for preliminary configuration selection. The three radial loads identified in Table II were used to analyze the operating L-10 life and the results were prorated over the percentages of operating times (Reference 3). The figures presented are in terms of the prorated life over the duty cycle.

Table II DUTY CYCLE AT 4.0 x 10⁶ DN

<u>% Time</u>	Radial Load
10	2000 pounds
20	1000 pounds
70	500 pounds

The parametric studies were run with the following assumptions:

- Constant pitch diameter = 6.50 inches = E
- Number of rollers = π times E divided by 1.5 times D
- Effective length of contact = roller diameter (D)
- 4 x 10⁶ DN (28,740 shaft rpm at 140 mm bore)
- Dual diameter roller .8D outer length, .5D inner length

The L-10 prorated bearing life over the entire duty cycle in hours for the hollow roller concept is shown in Figure 5 where bearing life is plotted as a function of roller diameter. The bottom curve on Figure 5 represents a solid roller of the configurations described in Figure 1a and 15. A similar plot of the L-10 prorated bearing life over the duty cycle for the dual diameter roller bearing is shown in Figure 6. An obvious knee in the curves is apparent for all of the roller concepts at a roller diameter of 0.5 inches. This can be explained in terms of the exponential reduction in life with increasing load. The larger diameter rollers have a higher outer race contact load because of increased centrifugal force and over 0.5 inch roller diameter this increase in centrifugal effects is greater than the corresponding increase in dynamic capacity of the roller race contact.

The results of the parametric study in terms of the design goal of more than 1,000 hours L-10 life are (a) roller diameter must be 0.5 inches or less for all configurations, (b) solid rollers are not acceptable in any diameter size, (c) hollow rollers should be 0.5 to 0.7 hollow, (d) dual diameter rollers with 0.5 to 0.6 small to large diameter roller ratio



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Figure 5. Bearing Life vs. Roller Diam. (Hollow Rollers)





are of interest, (e) the requirement for 0.01 inches maximum radial deformation under 2,000 lbs. load indicates that hollow rollers over 0.7 hollowness are not recommended. The parametric life study also shows that L-10 fatigue life can be a limiting factor at 4.0 $\times 10^{6}$ DN operation.

3. CAGE-SLIP AND HORSEPOWER LOSS STUDY

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The most promising configurations resulting from the parametric study were used in a full EHD computer analysis (Reference 1) containing the latest available elastohydrodynamic (EHD) technology (Reference 4). The majority of the computer runs were made with MIL-L-7808 oil at 250°F oil inlet temperature. One check run each for a single diameto and a dual diameter roller configuration were made with Polyphenyl Ether SP4E lubricant at 500°F oil inlet temperature. The actual run data is summarized in Table III, which also contains a summary of results including percentage cage slip and horsepower dissipation. More detailed information is summarized in Table IV. L-10 life, roller load, film thickness, and specific film thickness data as well as sliding speeds at both the outer and inner races are given for the maximum loaded roller.

The primary problem encountered in high speed mainshaft roller bearings is cage slip. This is the phenomena which results in high sliding velocities between the rollers and the inner race contacts. Severe glazing and micro-pitting results in bearing failure. The full EHD computer analysis gives detailed information regarding slip conditions. Figure 7 shows the percentage cage slip as a function of radial load for various operating conditions. An inner race land riding cage with hollow rollers has corsiderable slip and is used as a reference point in Figure 7. Seven hundred pounds radial load are required for non-slip or synchronous running of the cage. The outer race land riding hollow roller design has considerably higher slip than any of the other configurations and only one check run is plotted on Figure 7. The beneficial effects of having the frictional torque and the cage land contact acting as a driving torque indicates that an inner land riding cage

Table III

SCHEDULE OF COMPUTER RUNS

		F			Lube			Result	s		
		l. Hollow-Inner		Speed	/ 000 0 250°F	% 0i1			L-10 Life		
Run	Svmhol	2. Hollow-Outer	Load	, DII x 10-6	5P4E 0 500°F	in Brg Cavity	% Cage	d H	Hours (Fatique)	Cage RPM	
	- <u>2011</u> / 2			2	-	141.222	2		1226.22		-
-	V		666	4.0	7808	•	11.53	52.8	6,108		
~	Q	,	666	4.0	7808	.15	NYS	28.4	3,030	13,224	_
ŝ	\$		333	4.0	7808	.15	21.66	22.5	25,562	10,364	_
4	۵	2	333	4.0	7808	.15	64.97	9.6	953,167		
S	7	,	333	3.0	7808	.15	19.85	13.9	131,307		
9	V	ç	333	2.0	7808	.15	9.02	6.6	487,022		
~	-4		333	1.0	7808	.15	SYN	1.82	2.29×10 ⁶		
ω	4		333	4.0	5P4E	.15	17.14	17.5	17,751	10,961	
6		m	333	4.0	7808	.15	4.58	21.4	9,630	8,390	
10		m	333	4.0	5P4E	.15	SYN	17.2	7,505	8,792	
=		m	100	4.0	7808	.15	25.96	16.0	142,522	6,510	
12		e	333	(ل	7808	.15	SYN	5.2	44,301		

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Table IV

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SUMMARY OF COMPUTER RESULTS

	5 T S												
	No. 01 Loaved Roller	6	6	6	6	2	2	ۍ	6	ى م	e	æ	m
	Slide n./sec	1079.	2.9	2028.	6086.	1393.	420	3.2	1606.	412.	0.05	2335.	2.0
	V	1.55	1.59	1.68	1.60	1.52	1.36	0.97	0.33	1.40	0.25	1.63	1.23
Inner	EHD Film hxl0 ⁶	13.91	14.20	15.05	14.29	13.63	12.19	8.63	2.94	12.87	2.23	14.57	11.02
	Roll LD Lbs	138	190	72	11	66	110	117	74	139	141	59	213
	Slide in./sec	0.7	0.5	C	0	1.73	2.5	2.4	0	1.0	0	0	0 . 5
	V	1.46	1.46	1.53	1.27	1.46	1.36	1.01	0.31	0.98	0.23	66.0	0.75
OUTER	EHD Film hxl0 ⁶	13.08	13.05	13.66	11.35	13.02	12.12	9.04	2.79	8.74	2.09	8,85	6.68
	Roll LD Lbs	336	378	219	101	185	159	132	238	266	280	131	248
	% Cage Sliρ	11.53	Nis	21.66	64.97	19.85	9.02	SYII	17.14	4.58	SYN	25.96	NAS
	Load Lbs	666	666	333	333	333	333	333	333	333	333	100	333
_	Speed6 DNx10 ⁻⁶	4.0	4.0	4.0	4.0	3.0	2.0	1.0	4°C	4.0	4.0	4.0	2.0
	Symbol	~	V	4	۵	Q	V	4	4				
	Run No.	-	2	n	4	Ŝ	9	2	8	6	10	=	12
	OUTER Inner	Run Symbol DNx10 ⁻⁶ Lbs S1ip Lb hx10 ⁶ A in./sec Lbs hx10 ⁶ A in./sec Roll LD Film S1ide Loave	Run No.Speed Speed boxLoad $\&$ Cage $S1ip$ Cage RunRun S1ipInnerNo. 0 S1ide $hx10^6$ No. 0 ANo. 0 S1ide $hx10^6$ No. 0 	Run Speed Load % Cage Roll LD EHD Film Slide No. o No. o No.<	Run Nuo.Speed Speed No.Load % CageRoll LD LbsDUTERInnerInner1 Λ Speed Nx10 ⁻⁶ LbsS1ip LbsLbHD Film hx10 ⁶ S1ide LbsNo. q1 Λ 4.066611.5333613.081.460.713813.911.551079.92 Λ 4.0666SYII37813.051.460.519014.201.592.993 Δ 4.033321.6621913.661.5307215.051.682028.9	Run No.Speed Speed boll DNX10 ⁻⁶ Load % Cage Load S S1ipOUTERInnerInner1 Λ Speed SymbolLoad % Cage LNX10 ⁻⁶ Koll LD LbsEHD FilmS1ide hx10 ⁶ No. of ANo. of in./secNo. of S1ide hx10 ⁶ No. of hx10 ⁶ No. of ANo. of in./secNo. of Rolle Rolle ANo. of in./secNo. of Rolle Rolle ANo. of in./secNo. of Rolle ANo. of in./secNo. of Rolle ANo. of in./secNo. of Rolle ANo. of in./secNo. of Rolle ANo. of in./secNo. of Rolle ANo. of in./secNo. of Rolle ANo. of 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SYII 378 13.05 1.46 0.7 138 13.51 1.55 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 1.66 6086. 9 9 1.66 6086. 9 1.6 6086. 9 1.6 6 8 1.6 1.6 6086. <t< td=""><td>Run Speeds Load $^{\circ}$ Cage Roll LU FHD Film Inner Inner 1 Λ Speeds Lbs Slip Lbs Roll LD HU Film Slip Roll No. of the second in t</td></t<></ld<></ld<></td>	Run No.Speed Speed No.Load % Cage% Cage LbsRun FHD FilmInnerInnerNo. o1 Λ SymbolDNX10 ⁻⁶ LbsS1ipEHD FilmS1ideLoace No. oNo. o1 Λ 4.066611.5333613.081.460.713813.911.551079.92 Λ 4.0666SYH37813.051.460.519014.201.592.993 Δ 4.033321.6621913.661.5307215.051.682028.94 ∇ 4.033321.6621911.351.2707114.291.606086.95 Δ 33019.8518513.021.461.739913.631393.5	Run Nu.Speed Speed No.Load % Cage $$ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $	Run Speede Load % Cage Rol1 <ld< th=""> EHD Film S1ide Kon, Gage Rol1<ld< th=""> Run S1ide Load % Cage Rol1<ld< th=""> FHD Film S1ide Load No. Gage Rol1<ld< th=""> Hun Film S1ide Load % Cage Rol1<ld< th=""> FHD Film S1ide Load No. Gage Rol1<ld< th=""> 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⁻⁴ 6 Load % Cage Rol1 <ld< td=""> EHD Film S1ide Rol1<ld< td=""> EHD Film S1ide No. o 1 Λ 4.0 666 11.53 336 13.08 1.46 0.7 138 13.91 1.55 1079. 9 2 Δ 4.0 666 SYII 378 13.05 1.46 0.7 138 13.91 1.55 1079. 9 3 Δ 4.0 666 SYII 378 13.05 1.46 0.7 138 13.51 1.55 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 2.9 9 9 1.66 6086. 9 9 1.66 6086. 9 1.6 6086. 9 1.6 6 8 1.6 1.6 6086. <t< td=""><td>Run Speeds Load $^{\circ}$ Cage Roll LU FHD Film Inner Inner 1 Λ Speeds Lbs Slip Lbs Roll LD HU Film Slip Roll No. of the second in t</td></t<></ld<></ld<>	Run Speeds Load $^{\circ}$ Cage Roll LU FHD Film Inner Inner 1 Λ Speeds Lbs Slip Lbs Roll LD HU Film Slip Roll No. of the second in t





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configuration should be considered. For this reason all dual diameter roller computer runs were made with an inner land riding cage configuration. The dual diameter roller bearing has significantly less cage slip as shown on Figure 7. Another way to represent sliding or cage slip is to show the reduction in cage rpm as a function of radial load. This is given in Figure 8. It is immediately apparent that the hollow roller inner-land-riding cage speed or a single diameter roller bearing concept cage speed is considerably higher than the corresponding cage speed for the dual diameter roller concept. As evident in Figure 8, a much lower load is required to prevent sliding or tage slip in the dual diameter roller concept.

An object of the present study is to minimize heat generation in the bearing. An indication of heat generation is the computed horsepower loss of the bearing. As shown on Figure 9, the horsepower losses for both the inner land riding cage configurations (single diameter roller and dual diameter roller) are essentially the same. Horsepower losses are expected to be somewhat lower with the use of Polyphenyl Ether 5P4E lubricant as compared to MIL-L-7808 oil. The oil viscosity of the 5P4E at 500°F is less than that of the 7808 at 250°F. Viscous drag losses predominate in the bearing at 4.9 x 10⁶ DN. Therefore, lower cil viscosity (at synchronous cage speed) will result in less power loss.

4. SERIES HYBRID BEARING

The series hybrid bearing concept, Figure 1d, consists of an oil film bearing between the inner race of the roller bearing and the shaft. The concept is one of speed sharing or speed reduction. The rotative speed of the roller bearing inner race is determined by the frictional torque of the oil film journal bearing matching the frictional torque of the roller bearing. The advantage of speed sharing is the fact that reduction speed on the inner race of the roller bearing results in a lower operating DN speed regime.

A three lobe oil film hydrodynamic bearing was considered for this application. Satisfactory bearing stability (absence of half-frequency





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Figure 9. Horsepower Loss vs. Speed

whirl) can be obtained with this type of bearing. Good inherent stability was shown to exist under a shaft weight of 35 lbs. (representing an anticipated test rig shaft). This stability decreases as shaft weight increases, however, satisfactory stability for the bearing under study could be obtained up to 200 lbs. shaft weight. Minimum oil films on the order 0.001 inch can be anticipated under light 200 lb. loadings. The oil films would reduce to 0.0004 inches under the maximum 2,000 lbs. applied external load. The frictional torque of a three-lobe journal bearing was computed. The roller bearing inner race, Figure 1d, when supported on an oil film journal bearing only, would be completely free to move axially with respect to the shaft. Thus locating oil film bearings would be required to maintain the position of the roller bearing inner race. Locating thrust loads would be small. One approach is to use a conical type bearing (Reference 5). A pair of thrust bearings operating against the face of the roller bearing inner race were envisioned as a series of step pad thrust surfaces. The frictional torque of such surfaces amounted to approximately 15 or 20% of the overall journal bearing friction. This amount was added to the oil film bearing system torques.

The operation of the journal bearing would be in the turbulent regime and factors for the computation of turbulent friction are usually applied to laminar friction estimates. This approach was used in arriving at the total journal bearing friction curve. The friction loss vs. speed ratio for MIL-L-78C8 oil at 250° is shown in Figure 10. The solid lines indicate the friction torque expressed in inch pounds of the oil film journal and thrust bearing surfaces is a function of the ratio of the roller bearing inner race speed to shaft speed. The dashed curve represents the frictional torque of the inner land riding cage hollow roller bearing configuration. The point of intersection of these two frictional torque curves defines the operating speed of the roller bearing inner race. It is seen in Figure 10 that the present bearing system would result in a speed ratio of 0.84. Recent work by NASA (Reference 5) with a series hybrid concept using a ball thrust bearing and an oil



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film thrust bearing surface resulted in a speed sharing ratio of approximately 0.66 at best. The analysis is highly dependent upon accurate calculation of frictional torques. The frictional torques even in the turbulent regime of the fluid bearing has been fairly well established and correlated with experimental results and can be considered rea'istic. High speed roller bearing torque needs to be carefully verified to determine the anticipated speed sharing ratio. It is possible to add frictional torque to the roller bearing concepts by increasing the amount of oil forced through the bearing. Thus, it is possible by raising the frictional torque of the roller bearing to obtain a more favorable speed sharing ratio as could be seen by raising the curve on Figure 10. However, any reductions in roller bearing torque would result in reduction in the anticipated speed sharing ratio.

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5. SELECTION OF DUAL DIAMETER ROLLER BEARING

The dual diameter roller bearing concept, Figure 2, with an inner land riding cage was recommended for the thorough design analysis, fabrication and prototype testing. Selection of the dual diameter roller bearing concept was based upon the lower cage speeds obtained which result in significantly less cage slip.

The series hybrid bearing concept is interesting but was not recommended for further study under the present program. Operation of the series hybrid bearing design is highly dependent upon accurate determination of roller bearing friction torque. The horsepower losses of both conventional and dual diameter roller bearing concepts, Figure 9, ere shown to be essentially the same. Therefore the selection of a roller bearing configuration for further development at this time does not affect future consideration of development of the series hybrid bearing concept.

SECTION III

LUBRICANT SELECTION

A summary of full scale bearing test results of 8 candidate high temperature (600°F) lubricants is given in Table V, which was taken from Reference 6. All of the lubricants in this study were operated with an inerting blanket of nitrogen gas. Another recent study (References 7 and 8) considered five candidate high temperature lubricants. In this case Table VI, all of the lubricants were again protected by an inert nitrogen blanketing gas with the exception of Polyphenyl Ether 5P4E. The Polyphenyl Ether was operated in an oxygen atmosphere. The only advanced lubricant showing reasonable success without special inert oxidation protection is the 5P4E Polyphenyl Ether. Figure 11 is a reproduction of a report of bearing fatigue life experiments with Polyphenyl Ether (Reference 8). Indications are that Polyphenyl Ether is an acceptable high temperature lubricant up to 600°F but that the failure mode may be one of moderate glazing and micropitting of the races and rolling elements. This is attributed to thinner EH) lubricant films in the operating race and roller contacts. The various bearing configurations were analyzed with 5P4E Polyphenyl Ether at 500°F to determine the operating specific film thicknesses in the roller race contacts.

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The properties of MIL-L-7808 and Polyphenyl Ether lubricants are discussed in the elastohydrodynamic lubrication preliminary design manual (Reference 4). Additional data (Reference 9) regarding high pressure viscometer experiments with Polyphenyl Ether 5P4E were also used for estimating properties of this lubricant at 500°F. Lubricant data as a function of operating tempera ure is given in Table VII for the MIL-L-7808 and 5P4E lubricants. This lata as a function of temperature is consistent with the extrapolation routines of Reference 4.

Table V

SUMMARY OF TEST RESULTS

Performance	1	Fluid (5)	Measured h/a @ 600°F	Typical Bearing Condition
Excellent	*	Super Refined Mineral Cil Plus 10% High Molecular Weight Resin.	3.6-4.0	Good.
Good	2.	Perflorinated Polyether.	3-4(lnitial!y) <l.8 (long-term)<="" td=""><td>Minor Glazing And Micropitting.</td></l.8>	Minor Glazing And Micropitting.
	ų.	Modified Fluorsilicone.	<1.8	
Acceptable	ц.	Synthetic Hydrocarbon Plus 10% High Molecular Weight Resin.	<1.8	Moderate Glazing
	ŗ.	Modified Polyphenyl Ether.	<1.8	And Micropitting
Unacceptable.	6.	Super Refined Mineral Oil W:thout High Molecular Weight Resin.	2.6-3.6 (Initially) <1.8 (Long-Term)	
	7.	Synthetic Hydrocarbon Without High Molecular Weight Resin.	3.5-4.0	Heavy Glazing And Pitting.
	ω.	Highly Hindered Ester.	<1.8 <	•

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Table VI

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PROPERTIES OF TEST LUBRICANTS

					Kine	natic		Specific	Density
Lubricant		•	Flash point.	Fire point.	vi scos at	ity, cs -	-	heat at 500°F,	at 500°F
designation	Base Stock	Additive content	ш. •	۶. ۲	100°F	210°F	500 F	Btu/(1b.)(°F)	1b./ft.
NA-XL-10	Super-refined naphthenic mineral oil	(a)	445	495	62	8.4	1.1	0.660	45.7
NA-XL-13	Synthetic paraffinic oil	None	530	580	314	32	62.9	I	1
NA-XL-16	Polyester- hindered type	(c)	480	540	27.6	5.2	۰،۱ ^۵	ı	ı
NA-XL-20	Fluorocarbon	None	1	ı	335	29	2.1	.317	94
NA-XL-22	5P4E polyphenyl ether	None	550	660	363	13.1	1.2	. 496	63.1
:IA-XL-23	5P4E polyphenyl ether	(P)	550	660	363	13.1	1.2	. 496	63.1
NA-XL-24	Synthetic paraffinic oil	(e)	530	580	314	32	^b 2.9	ŧ	ı
^a 0xidation	innibitor, extrem	e pressure	e additiv	e, and ar	ıtifoam	agen t.			

^bExtrapolated.

^COxidation inhibiton and dispersant.

^dOxidation inhibitor.

^eAntiwear additive.



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Rolling-element fatigue life of 120-mm bore angularcontact ball bearings run with polyphenyl ether lubricant. Material, AISI M-50 steel; thrust load, 4365 lb; speed, 12,000 rpm; temperature, 600°F air environment; [failure index, 2 out of 26.]

Table VII

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LUBRICANT PROPERTIES USED IN THE ANALYSIS

MIL-L-7808 LUBRICANT PROPERTIES

Wt. Dens. (<u>ll./in³)</u>	.33100-61 .32300-01 .31600-01 .30800-01 .30100-01
Spec. Heat (BTU/lb°F)	.48400+00 .51200+00 .53100+00 .55000+00 .56800+00 .58803+00
Therm.Cond. (BTU/°F-HRFT)	.09050+00 .08700-01 .83000-01 .79400-01 .75600-01
Gana (in ² -°F/1b.)	.63000-01 .63000-01 .63000-01 .63000-01 .63000-01
Beta (°F)	.49130+04 .49130+04 .49130+04 .49130+04 .49130+04 .49130+04
Alpha (in ² /1b)	.88400-04 .81000-05 .76200-04 .72800-04 .70600-04 .69000-04
Viscosity (<u>lb-sec/in²)</u>	.11006~05 .45000-06 .30500-06 .21500-06 .16000-06 .12000-06
Temperature (°F)	.15000+03 .20000+03 .25000+03 .30000+03 .35000+03 .40000+03

Polyphenyl Ether LUBRICANT PROPERTIES (5P4E)

Wt. Dens. (1b./in ³)	.40700-01 .40700-01 .40100-01 .39800-01 .39500-01
Spec. Heat (<u>BTU/lb-°F)</u>	.46200+00 .47800+00 .49200+00 .51100+00 .52700+00 .5400+00
Therm.Cond. (BTU/°F-HR-FT)	.77300-01 .77100-01 .76700-01 .76600-01 .76400-01
Gama (in ² -°F/lb.)	.18300+00 .18300+00 .18300+00 .18300+00 .18300+00
Beta (°F)	.65040+04 .65040+04 .65040+04 .65040+04 .65040+04 .65040+04
АІрня (in ² /1b)	.66000-04 .54000-04 .43000-04 .33000-04 .26000-04 .19000-04
Viscosity (<u>lb/sec/in²)</u>	.80000-06 .44000-06 .26000-06 .16000-06 .10000-06
Temperature (°F)	.30000+03 .35000+03 .40000+03 .45000+03 .50000+03 .55000+3

SECTION IV

DUAL DIAMETER BEARING ANALYSIS AND DESIGN

1. DESIGN CONSIDERATIONS

The dual diameter roller bearing concept was selected as a result of the preliminary configuration study. Selection was based upon the lower cage speeds obtained which will result in significantly less cage slip. The orbital cage speed of the dual diameter roller bearing with a diameter ratio of 0.5 will result in a 1/3 reduction of cage speed as seen by Figure 4. A major roll diameter of 0.5 inches was selected as an optimum based on Figure 6. The resulting estimated bearing life (under the duty cycle of Table II) would be 5,000 hours L-10 life shown on Figure 6. This is well in excess of the design goal of 1,000 hours.

The primary problem encountered in high speed mainshaft roller bearings is cage slip. This is a phenomena which results in high sliding velocities between rollers and inner race contacts. Severe glazing and micropitting results in bearing failure. The minimum radial load to prevent skid or cage slip in the dual diameter roller bearing is 333 lbs. as shown on Figures 7 and 8. This minimum radial load was used in the design and performance evaluation calculations. Neavier radial loads will result in reduced bearing fatigue life, but do not endanger the bearing from a skid or cage slip standpoint and are of relatively minor interest. It is essential to assure that cage slip will not occur under operating conditions. A complete systems analysis (Reference 1) incorporating the latest available elastohydrodynamic lubrication technology (Reference 4) and including fluid drag forces and thermal effects were selected as the best approach to achieve a practical design.

2. INNER RACE STRESSES

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A study of the effect of inner race thickness and total interference fit between the inner race and shaft (with the hollow test shaft) to determine race circumferential, hoop or tangential tension stresses was conducted using standard ring formulas. Race radial thickness over 0.25 inches has little effect upon reducing circumferential tangential stresses. Race thicknesses less than 0.250 inches radial thickness can result in unacceptably high stresses. Therefore the inner race thickness should meet or exceed 0.25 inches.

High shaft speeds (up to 28,600 rpm) will create significant circumferential, hoop or tangential stresses in the inner race. Figure 12 shows a magnitude of this maximum tangential stress as a function of shaft speed expressed both in rpm and DN values for the 140 mm bore bearing. Approximately 50,000 psi tangential stress can be anticipated at 4.0 x 10^6 DN with the 0.25 inch thick race of the prototype bearing design.

Approximate physical properties of M-50 fully hardened steel are given in Table VIII. The material is brittle at room temperature and care must be exercised to prevent over-stressing. The material does become more ductile as temperature increases. The effect of stresses due to speed, Figure 12, and stresses due to interference fit are essentially additive. Approximately 0.012 inches diametral interference fit would be required at room temperature to assure a working interference fit of 0.001 at 4.0 x 10⁶ DN operation. This heavy interference fit would result in almost 60,000 psi tangential ring stresses initially. It was decided to compromise with a lesser interference fit at room temperature (0.0063 inches) and allow the inner race to become loose with respect to the shaft at approximately 3.0 x 10⁶ DN. Key slots in the inner race allow the race to be axially clamped and prevent relative rotation of the race and shaft. The loose fit between "nner race and shaft at speeds over 3.0 x 10⁶ DN will keep the inner race tangential stresses to less than 60,000 psi.

High tensile ring stresses may have a detrimental effect on inner race rolling contact fatigue. Thermal gradients may also cause the interference



Figure 12. Inner Race Maximum Tangential Stress vs. Shaft Speed

TABLE VIII

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PROPERTIES OF M-50 HARDENED TO RC-60 Per VASCO Technical Bulletin

Property	Room lemp.	800°F
Tensile ULT. (psi)	411,500	345,000
Tensile Yield (psi)	388,000	262,500
Elongation (1.5" gauge) (%)	2	6
Red. of Area (%)	2	17

An existing FIRL finite element computer program was used to evaluate the tangential ring stresses in the actual inner race design at 4.0 x 10° and 3.5 x 10⁶ DN. Figure 13 illustrates the inner race model and the location of various tangential stresses. The stress values of Figure J3 are in good agreement with the approximate solutions used to obtain the values in Figure 12. It is readily apparent that stresses on the order of 57,000 psi will occur in the inner race at 4.0 x 10⁶ DN. Stress level will drop to approximately 44,000 psi maximum at 3.5 x 10° DN (25,000 rpm). A third case was analyzed where circumferential line loads were applied in the vicinity of the roller inner race contacts to simulate stress conditions under 500 lb. external radial load. It can be seen from Table IX that the stress values range between a high of 43,000 psi and a low of 29,000 psi. The only available data to date for M-50 steel at 500°F in reverse bending f :: igue (Reference 10) indicates a life which is asymptotic at 60,000 psi banding stresses beyond 10⁸ cycles. The fluctuation of inner race bending stresses are all unidirectional and remain tensile as shown in Table IX and do not exceed a maximum value of 43,000 psi. The inner race compliant section calculates to have adequate reverse bending fatigue properties.

3. LUBRICATION

The method of lubrication for the dual diameter roller bearing is illustrated in Figure 14. Jet oil is introduced to an undercut in the test shaft as shown. Oil then passes through the shaft to the undercut portion of the inner race which octs as an oil reservoir. Centrifugal force resulting from shaft rotation then provides pressure to force a flow of oil through orifice holes in the inner race. This oil is then

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Finite Element Analysis of Inner Race Tangential Strusses at 4.0 x 10⁶ DN Figure 13.

TABLE IX

INNER RACE TANGENTIAL STRESS (KSI)

Loading/Element No.	1	10	81	90	171	208	215	270	370	492	392	
4.0 × 10 ⁶ DN	55	55	55	53	55	57	52	57	51	55	51	
3.5 × 10 ⁶ DN	42	4]	42	41	41	43	40	44	39	43	39	
3.5 × 10 ⁶ DN												
500 lbs.	37	23	36	33	37	40	36	41	38	43	39	
Radial Load												

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introduced to the underside of the cage and is further circulated throughout the bearing by the pumping action of the rollers. Auxiliary jet oil lubrication into the sides or faces of the bearing can also be provided as necessary to obtain satisfactory cooling.

Three computer analysis runs were executed using three different flow rates (6.1, 12.0 and 18.0 lbs./min.) of 5P4E at 500°F oil inlet temperature. The minimum load to prevent skid of 333 lbs. and the top design shaft speed of 28,560 rpm (4.0 x 10^6 DN) were used. A complete thermal analysis was included in the solutions. A summary of the effects of oil flow upon bearing performance is given in Table X and shown graphically in Figure 15. Examination of Figure 15 shows no clear maxima or minima characteristics. It is evident that increased oil flow rate results in reduced outlet temperature and increased bearing horsepower loss. The outlet oil temperature shows some indication of leveling out below 6 lbs. per minute, but at unacceptably high values in excess of 700°F. Increasing the oil flow from 6 to 12 lbs. per minute drops the outlet oil temperature by 51.8°F. Increasing the oil flow from 12-18 lbs. per minute drops the outlet oil temperature by only 22.3°F.

An cil flow rate of 12 lbs./min. was selected as the design point. This flow can be obtained with 6 orifices of 0.028 inches diameter. The calculated oil outlet temperature of 4.0×10^6 DN is 598.5°F which is consistent with the program goal of 600°F operation. Table XI gives the resulting oil flow rates for 5P4E at 500°F oil inlet and MIL-L-7808 at 250°F oil inlet as a function of shaft speed.

4. PERFORMANCE ANALYSIS

Eight computer solutions were executed at various shaft speeds with 5P4E and MIL-L-7808 oil lubricant under a constant bearing radial load of 333 pounds. A summary of these computer runs and performance results are contained in Table XII. Initial fit-up conditions are 0.0063 inches shrink fit between bearing inner race and the shaft and 0.011 inches initial (machined or ground) diametral clearance. All of the solutions summarized in Table XII included a full thermal analysis consisting of 21 thermal modes described in Figure 14. Description of the node locations and the temperature

TABLE X

EFFECT OF OIL FLOW RATE ON BEARING PERFORMANCE

	Run 2P	<u>3P</u>	<u>4</u> P
Flow (lbs/min)	6.1	12.0	18.0
HP (loss)	21.7	23.53	25.4
Temp. Out of Brg. (°F)	650.3	598.5	576.2
Sump. Temp. (°F)	608.1	561.8	544.4

Shaft Speed 28,560 RPM (4.0 x 10⁶ DN) Lubricant: 5P4E @500°F oil inlet Radial Load: 333 lbs

TABLE XI

OIL FLOW RATE VS. SPEED (DN)

		-	011 Flow 1	<u>Rate Ibs/min</u>	
Lubricant_	Inlet Temp. °F	4.0x10 ⁶ DN	3.0x10 ⁶ DN	2.0x10 ⁶ DN	1.0x10 ⁶ DN
Polyphenyl Ether 5P4E	500	12.0	9.03	6.05	3.0
MIL-L-7808	250	8.98	6.82	4.60	2.33

Six 0.028" Diam. Orificies in Inner Race





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TABLE XII

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SUMMARY OF PERFORMANCE ANALYSIS COMPUTER RUNS

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Run No.	λ	0 P	d/	ЯР	96	401	d	122
Speed DN	4 × 10 ⁶	3 × 10 ⁶	2 × 10 ⁶	1 × 10 ⁶	4 × 10 ⁶	3 × 10 ⁶	2 × 10 ⁶	1 × 10 ⁶
Lube Type	5P4E	SP4E	5P4E	5P4E	7808	7808	7808	7808
Lube Flow Rate (lb/min.)	12.0	9.03	6.05	3.0	8.984	6.819	4.6	2.327
L ₁₀ Life (Hrs.)	7,236	22,496	63,329	1.7 × 10 ⁶	8,036	23,962	71,756	2.1 × 10 ⁶
Total Hp.	22.6	10.8	4.0	0.9	26.6	14.4	5.9	1.2
Operating Clear (Mils)	3.3(1)	6.6	7.0	7.3	1.6 ⁽¹⁾	6.2	6.3	6.3
Cage Operating Clear (Mils) (Diametral)	32.	32.	32.0	32.0	32.0	34.0	33.0	32.0
No. Loaded Rollers	ŝ	m	ŝ	e	ſ	Ś	Ś	m
Radial Deflect (Mils)	2.0	3.7	3.9	3.9	-	3.4	3.5	3.5

(1) Inner Race loose on Shaft

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profiles for the 8 performance runs are summarized in Table XIII.

The temperatures when using the Polyphenyl Ether 5P4E lubricant are acceptable at all speeds. The average oil temperature within the bearing (node 11) at 4.0 x 10^6 DN operation of 631.9°F is acceptable for short duration test runs. Operating temperatures with MIL-L-7808 oil are not acceptable and auxiliary side jet lubrication was required during the initial checkout test runs with this lubricant.

The predicted frictional horsepower losses are shown in Figure 16 as a function of the speed parameter DN. Horsepower losses are also summarized in Table XII. A total loss of 22.6 horsepower was predicted at 4.0×10^6 DN using Polyphenyl Ether 5P4E at 500°F oil inlet temperatures.

Radial displacements are summarized in Table XII and include one half of the operating internal clearance in the bearing. The specifications require that the total radial displacement not exceed 0.010 inches under 2000 lbs. radial load. An additional elastic deflection between rollers and raceways of 0.0006 inches should be added to the values in Table XII to adjust for the difference between the 333 1b. analysis load and the 2000 lb. specific tion load. All total displacement values are well below (less than half) maximum allowable values. The largest radial displacements occur at the lowest shaft speeds. The effects of shaft speed and thermal effects in the bearing tend to decrease diametual clearance. A summary of the fluid film forces and roller contact forces acting on the cage are given in Table XIV. It is evident from the table that the draving torque resulting from the loaded rollers contacting the cage pockets is not sufficient to prevent serious cage slip at 4.0 \times 10⁶ DN operation. The fluid film drag on the inner surface and inner race to cage land is necessary to drive the cage at speed and prevent cage slip. An outer riding cage with resultant fluid drag torques at the outer race land contacts would result in significant cage slip at 4.0 x 10^b DN. Roller to cage web contact forces of 10.3 pounds are predicted at the maximum DN operation.

TABLE XIII

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SUMMARY OF TEMPERATURE PROFILES FOR DUAL DIAMETER ROLLER BEARING

		NO	4×10 ⁶	3×10 ⁶	2×10 ⁶	1×10 ⁶	4×10 ⁶	3×10 ⁶	2×10 ⁶	1×10 ⁶
		Lube	SΡϤΕ	5P4E	5P4E	5P4E	7808	7808	7808	7808
No.	Location	Run	5P	6P	٦P	8	96	10P	dII	12P
	Inner Shaft Coulant		660.8	601.4	545.5	476.5	514.2	470.5	379.5	280.9
2.	lnner Shaft Surface		556.6	540.7	514.4	488.4	346.6	347.1	307.5	263.7
ы.	Outer Shaft Surface at E	Bearing	535.6	535.2	512.3	488.9	314.4	337.9	303.4	263.1
4.	Inner Race at Shaft	1	613.3	558.4	521.8	9.164	453.8	374.0	320.6	267.1
	Under-cut Surface of Inn	ner Race	615.8	564.0	524.1	492.2	456.3	382.4	324.5	268.0
6.	Under Race Coolant		529.5	517.4	503.1	485.5	297.8	289.0	274.6	253.9
7.	Inner Race Beyond Roller	r Contact	628.1	571.3	526.8	492.8	469.3	391.5	328.6	268.8
	Cage at the Land		665.6	600.8	542.4	498.9	549.7	462.2	369.1	282.0
و.	Cage Inner Surface		674.2	604.0	543.5	4.99.4	554.6	465.3	370.4	282.4
10.	Cage Duter Surface		672.6	603.0	543.1	4.99.4	552.0	464.1	369.9	282.4
11.	Internal Lubricant to Be	saring	631.9	576.6	529.3	494.5	465.9	404.8	338.9	272.7
12.	Rollers)	673.4	601.8	543.3	498.5	557.9	464.6	370.8	282.3
13.	Inner Race at Rollers		627.1	570.1	526.1	492.6	465.5	388.8	327.2	268.5
.41	Inner Surface of Outer F	Aace	623.5	570.7	525.7	492.3	446.4	389.7	329.3	269.1
15.	Inner Cooled Surface Out	ter Race	621.6	569.7	525.3	492.1	444.2	388.3	328.6	268.9
16.	Outer Race Lubricant		620.0	568.9	525.0	6.164	442.3	387.1	328.0	268.8
17.	Outer Cooled Surface Out	ter Race	618.5	568.0	524.6	8.164	440.4	386.0	327.5	268.6
18.	Bearing Outer Diameter		603.8	560.2	521.3	490.3	422.8	374.8	322.0	267.3
.61	Chamber Wall (Inner Side	(a)	548.5	515.0	484.7	459.2	359.4	325.6	287.5	246.8
20.	Loading Bolt (Strut) Roc	ot	491.3	458.6	429.2	405.7	354.1	317.1	276.0	233.0
21.	Shaft (External to Bearl	ing)	574.7	545.4	515.6	490.1	371.5	345.9	306.1	263.4
	Sump Oil Temperature		581.8	547.4	516.2	0.064	385.0	348.5	307.3	263.3
	EHD Contact Temperature		584.9	548.6	519.8	500.7	377.7	347.0	303.8	267.4
	∆t Rise (Input - No. 11)	•	131.9	76.6	29.3	- 5.5	215.9	154.8	88.9	22.7

500°F 250°F

5P4E input Temperature 7808 input Temperature



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TABLE XIV

SUMMARY OF CAGE ANALYSIS

	Speed(DN) Lube Run No.	4×.0 ⁶ 5P4E 5P	3×10 ⁶ 5P4E 6P	2×10 ⁶ 5P4E 7P	1×10 ⁶ 5P4E 8P	4×10 ⁶ 7808 9P	3×10 ⁶ 7808 10P	2×10 ⁶ 7808 11P	1×10 ⁶ 7808 12P
Cage Clearance (Operating)(Mils)		32.	32.	32.	32.	32.	34.	33.	32.
% Cage Slip from Synchronous Cage Torque {in∼lb)		.0006	.0005	4000.	100.	0.31	.05	6 0 .	.12
From Driving Rollers At the Land Contact On Inner Cage Surface On Outer Cage Surface On Outer Cage Surface On Cage Sides Cage Driving Force (lbs) or Max Loaded Roller Dage Drag Force (lbs)		48.7 14.5 38.6 4.5 4.5 .51 10.3	29.7 10.5 23.8 2.8 33 9.6	16.3 6.3 11.6 1.36 .10 .10 4.1	6.3 2.4 3.3 .14 4.1	49.9 19.8 35.4 4.1 .32 7.4(2)	32.2 13.7 21.6 2.5 2.5 9.7	18.2 8.4 10.8 .59 .14 7.1	6.8 3.3 3.1 .4 .06 3.9
on ¹ Inloaded Roller (1) + Indicates Driving Torque		-	-	ço.	٥ <u>۲</u>	1.97	1.45	.93	.39

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(2) Has 5 rollers in contact All others have three.

- Indicates Drag Torque

5. EHD APAMETERS

The order race to roller contact EHD conditions for unloaded rollers are summanised in Table XV. The outer race to roller conditions for the maximum loaded roller in each case are summarized in Table XVI. The inner race contact EHD conditions for the maximum loaded roller are summarized in Table XVII.

Thin elastohydrodynamic (EHD) oil films (less than 3.0×10^{-6} inches) are predicted with Polyphenyl Ether 5P4E lubricant at 500°F oil inlet temperature for the bearing. The calculated oil inlet temperature at the entrance to the EHD contacts are given in the appropriate tables. The thin EHD films result in low (approximately 0.25) specific film values. Specific film thickness is the ratio of the actual oil film thickness to the root mean square of the contacting surface finishes. Operation at 600°F or higher temperatures with 5P4E lubricant can be expected to result in surface oriented damage or distress prior to any evidence of classical sub-surface oriented fatigue damage.

Somewhat thicker EHD films are predicted with MIL-L-7808 cil applied to the bearing at 250°F. The specific films are approximately 1.0 which is still in the surface related distress region of operation.

The sliding contribution to the total traction values between roller and race contacts is predominant for both contacts of the maximum loaded rollers (Tables XVI and XVII). The rolling contribution to the total traction is significant at the outer race contact of the unloaded rollers, Table XV. All of the rolling contacts are in the low slip (sliding velocities less than 1.0 inches per second) region, with the exception of 1.0×10^6 DN operation with 5P4E lubricant.

6. DESIGN DRAWINGS

The five drawings (Figures 17-21) completely describe the final design of the dual diameter roller bearing.

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TABLE XV

TRACTION VALUES - OUTER RACE CONTACT - UNLOADED ROLLERS

Specific Film	249	.306	.337	.299	1.09	1.13	61.1	1.09
Traction Ratio Roll/		1.54	1.62	.156	870.	.082	.167	.313
EHD Contact Temp.	585°F	549°F	520°F	501°F	378°F	347°F	304°F	267°F
0il Film Thick.	1.41×10 ⁻⁶	1.7×10 ⁻⁶	1.9×10 ⁻⁶	1.7×10 ⁻⁶	6.2×10 ⁻⁶	6.4×10 ⁻⁶	6.7×10 ⁻⁶	6.2×10 ⁻⁶
Total Tract.	1.513	.920	.495	.256	1.724	1.226	.72	.236
Rolling Tract.	-1.512	-1.42	-0.80	-0.04	-0.083	-0.10	-0.12	4£0.0-
Si iding Tract.	10000	2.34	1.295	.296	1.807	1.326	0.84	0,31
Coeffic- ient of Trac- tion	.7×10 ⁻⁵	0.03	0.037	0.034	0.013	0.017	0.024	0.036
loj Ibs	139	78	35	8.7	139	78	35	8.7
Sliding Velocity (in/sec)	0.0112	0.187	0.622	15.56	566°	2.70	9.32	15.5
Rolling Entrain- ment: Velocity (in/sec)	3112	2332	1555	762	3109	2329	1545	762
t Cage Silp	.00065	.0005	.00038	.0005	.035	.055	60.	.116
æ	4×10 ⁶	3×10 ⁻	2×10 ⁻	1×10	4×10 ⁶	3×10 ⁶	2×10°	1×10
110	5P4E	574E	574E	5P4E	MIL-L	7808	7808	808/

TABLE XVI

TRACTION VALUES - OUTER RACE CONTACT - MAXIMUM LOADED ROLLERS

Spec. Film .226 .260 .264	0.1 .97 49. 1.09
Ratio Roll/ Joj .036 .022 .022	.031 .012 .037 .038
EHD Contact <u>Temp.</u> 585°F 549°F 520°F 501°F	378°F 347°F 304°F 267°F
011 Film Thick. 1.28×10 ⁻⁶ 1.47×10 ⁻⁶ 1.49×10 ⁻⁶ 1.13×10 ⁻⁶	5.7×10 ⁻⁶ 5.5×10 ⁻⁶ 5.3×10 ⁻⁶ 4.2×10 ⁻⁶
Total Tract. -6.099 -5.82 -3.62 -2.55	-4.17 -5.79 -4.30 -2.38
Rolling <u>Tract.</u> 219 08 14	-0.13 -0.07 -0.16 -0.09
511ding <u>Tract.</u> -5.88 -5.32 -3.54	-4.04 -5.72 -4.14 -2.29
Trac- tion <u>Coeff</u> . 0.02 0.016 0.012	0.015 0.022 0.019 0.012
Poj 294 201 201 201	269 260 218 191
Sliding Velocity (in/sec) -0.007 -0.0037 -0.0032	261 90 -1.21 78
Rolling Entrain- ment Velocity (in/scc) 3112 2334 1576 778	3110 2333 1556 778
\$ 511p .00065 .0005 .00038	.035 .055 .116
DN 4×106 3×106 1×106 1×106	4×10 3×10 2×10 1×10 1×10
011 5945 5945 5945 5945 5945	7808 7808 7808 7808

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TABLE XVII

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TRACTION VALUES - INNER RACE CONTACT - MAXIMUM LOADED ROLLERS

Spec. Film	.355	644.	532	.396	02 1	1.64	1.67	1.38
Ratio Roll/ oj	0.033	0.052	0.046	0.036	o uho	0.022	0.041	0.0 6
EHD Contact Temp.	585°F	549°F	520°F	3-105	378°F	347°F	304°F	267°F
Oil Film Thick.	2×10 ⁻⁶	2.5×10 ⁻⁶	3.0×10 ⁻⁶	2.2×10 ⁻⁶	9.6×10 ⁻⁶	9.3×10 ⁻⁶	9.4×10 ⁻⁶	7.8x10 ⁻⁶
Total Tract.	4.195	3.754	2.37	1.60	3.219	3.917	2.812	1.49
Rolling Tract.	-0.145	+61.0-	-0.110	-0.059	-0.160	-0.087	-0.116	-0.09
Sliding Tract.	4.340	3948	2.480	1.659	3.379	4.004	2.928	1.58
Trac- tion <u>Coeff</u> .	0.028	0.021	0.013	0.0085	0.0258	0.022	0.016	0.0087
1. [] []	155	188	161	193	131	182	183	182
Sliding Velocity (in/sec)	-05	.013	.0065	C400.	2.60	16.1	1.65	1.06
Rolling Entrain- ment Velocity (in/sec)	6224	4668	3112	1556	6220	4666	3112	1556
t Cage Silp	.00065	.0005	.00038	.0005	.035	.055	60.	.116
ß	4×10°	3×10°	2×10	1×10	4×106	3×10 ⁶	2×10°	1×10
110	5P4E	5P4E	5P4E	5P4E	M1L-L 7808	7808	7808	809/





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Figure 18. Inner Ring, Two Diameter Roller Bearing

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Figure 21. Cage, Two Diameter Roller Bearing

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SECTION V

DUAL DIAMETER BEARING FABRICATION

Six prototype test bearings Figure 22 were fabricated to the design drawings (Figures 17-21) by the Bower Bearing Div., Federal-Mogul Corporation, Detroit, Mich. A summary of the six prototype bearing dimensional sizes and variations are given in Table XVIII.

The inner race roller path circularity and contour for test bearing No. 3 are shown in Figures 23 and 24 and are representative of all of the bearings. The circularity and raceway contour of the outer race roller path are shown in Figures 25 and 26 for test bearing No. 3.

The roller design for the dual diameter roller, Figure 20, is not an easy shape to produce. However, the test bearing rollers were centerless ground and crowns were maintained within drawing limits on all three roller portions, as shown by the typical roller traces, Figure 27.

All material specifications, silver plating, balance, etc., are given in the design drawings, Figures 17-21. All prototype bearings met or exceeded the design drawing requirements.

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Table XVIII

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Serial Number	A1	82	C 3	04	65	r6
Inner Reces - C3132-2						
0.0. Size	6.00384	6.00385	6.00395	6,00396	6.00385	6.00390
Taper	0.000020	0.00040	0.000070	0,000070	0.000020	0.000038
Dut-of-Round	0.000050	0.000050	0.000050	0,000050	0.000050	0.000050
Bore Land	5.51160	5.51160	5.51165	5.51170	5,51165	5.51165
Bore Land	5.57160	5.51165	5.57165	5.51170	5.51165	5.51165
Out-of-Round	0.000050	0.00015	0.00015	0.00015	0.00015	0.00015
Concentric	0.00010	0.00025	0.00015	0.00013	0.00012	0.00010
Width	1.4955	1.4951	1.4955	1.4955	1.4954	1.4954
0.0. Surface Finish	244	2-1/2/388	2/2-1/2AA	1-1/2/2AA	1+1/2/2AA	244
Outer Races - C3132-2						
0.0. Size	7.8739	7.8736	7.8738	7.8736	7.8739	7.8738
Tager	6.001	0.0001	0.0001	0.0001	0.0001	0.0001
Out-of-Round	0.0001	0.001	0.0001	0.0001	0.0001	0.0001
I.D. Track	6.76416	6.76414	6.76416	6.76420	6.76416	6.76412
Out-of-Round	0,00015	0.00015	0.00015	0.00015	0.00015	0.0001
Taner	0.000050	0.000050	0.000050	0.000050	0.000050	0.000050
Concentric	0,00010	0.000050	0.00015	0.00015	0.00010	0.0010
Flaces Onesian	0.2508	0.2508	0.2512	0.2508	0.2508	0.2511
Parallal Face to Wall	0.00016	0001	0.00015	0.00015	0.00015	0.00015
Perallel Well to Well	0.0001	0.0001	0.0001	0.00015	0.00015	0.0001
1.B. Surface Flatab	CAA	haa	EAA	KAA	3-1/2/644	
Flance Surface Ion	244	2-1/2/344	2/2-1/244	1-1/2/288	1-1/2/288	244
	200					
Cage - C3132-5						
0.0. \$1ze (A)	6.6436/6.6442	6.6428/6.6434	6.6423/6.6438	6.6426/6.6430	6.6427/6.6433	6.64221/6.6428
0.9. Size (8)	6.6434/6.6444	6.6427/6.6432	6.6424/6.6436	6.6427/6.6432	6.6424/6.6433	6,6423/6.6424
0.s. Out-of-Round	.0006/.001	.0006/.0005	.0013/.0012	.0004/.0005	.0006/.0005	.0003/.0001
1.0. \$120 (A)	6.0404/6.0415	6.0408/6.0412	6.0408/6.0414	6.0410/6.0417	6.0408/6.0412	6.0412/6.0422
1.D. Size (8)	6.0408/6.0412	6.0408/6.0412	6:0404/6.0412	6.0409/6.0413	6.040576.0412	6.0412/6.042
Concentric 10/00	,001 TIR	.001 TIR	.001 TIR	.0012 TIR	.0012 TIR	.0008 TIR
Syue rones s	.001 TIR	.001 TIR	.0011 TIR	.001 TIR	.00105 TIR	.0008 TIR
Vidth	1.057	1.0572	1.0565	1.055	1.055	1.055
Cage Balanca GM/cm # 500 rpm	0.2-0.3	0.3-0.2	0.4-0.3	0.2-0.2	0.5-0.3	0.5-0.1
Pkt. Fig. from Side	0004	0004	0004	•	•	
hollers - C3132-4						
Large 0.0.	.5000/.49995					
Out-of-Round	.000050 max.					
Vidth	.2500/.2501					
Width Se, w 5 00	.00010 mex.					
W/1 to .2500	.00010 max.					
See11 00	.249975/.24992					
Out-of-Bound	.000050 mex.					
Length	3500/ 34001					
Tenne 1 2 M 15 00						
Overall Length	.7500/.7490					
1 Dia's Concentric	0.000050 TIR					
Finish Dials	1 MS					
Finish End	5 NHS					
ASSEMULED DIAM CLEARANCE	0.0103	0.0103	0.0102	0.0102	0.0103	0.0102

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Figure 23. Bearing No. C3 Inner Race Circularity

and the second s 1 ! i • ; TJTAL N.AVINES PRUMLE. . ROUGHAES i ; ţ į : i ; -; Ļ 108.1 ディンシン 2 i : ふら . ki . 3 į ł ļ . . . CENTER ; t ARITH, AVE. SCALE HING CONDER ; *:** NO048 1.00 CUNTOUL : ì 3 ; • PART NO KA - AL -OATE 7.24-72 1 いいと言いい んればアン 1 1 11 0001 11 0001 11 0005 11 0005 **5** 1 S 2 ŧ CHAST NO. 337 W K K K K 1 • Į 1 the three way CUIOFF. # 010 1 2 į İ m. C.I. : 9 27 ł 3745 211125 1. USH 1155 į ! : į -1 1 1 . . i ! 1

igure 24. Bearing No. C3 Inner Raceway Contour

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Figure 26. Bearing No. C3 Outer Raceway Contour



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SECTION VI DUAL DIAMETER BEARING TESTS

1. TEST RIG

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The dual diameter bearing testing was performed at Midwest Aero Industries, Div. Pure Carbon Co., St. Mary's, Pa., on an existing 250 hp drive test stand with an eddy current clutch and speed increaser gear box. The test rig is shown in Figures 28 and 29. A cross-sectional drawing of the rig is given in Figure 30. The numbered locations correspond to the thermocouple temperature readings of the actual test data. All of the original test log sheets are contained in the Appendix.

The test rig consists of a short hollow shaft supported by two 75 mm bore slave roller bearings. The dual diameter roller bearing, 140 mm bore, is supported midway between the two slave bearings. Radial load is applied by pulling upward on the test bearing housing through a large ring as shown on Figure 30. Oil to the dual diameter bearing is introduced through three orifices, location No. 1, and jeted to a scoop on the test shaft. The oil then travels to the recess under the dual diameter bearing, up through the bearing, out into the rig cavity, and exits the drain through points 2 and 4. The test shaft is driven by a splined quill shaft between the rig and the speed increaser gear box. The area for the quill shaft drive is shown with the cover removed in Figure 28. The entire test head shown in Figure 30 and a transition cone covering the quill drive shaft are cantilevered from the speed increaser gear box, as can be scen in Figures 28 and 29.

Two prototype dual diameter roller bearings were tested under the current contract. The first bearing was operated with MIL-L-7808 oil at approximately 250°F inlet temperature to gain a feel for the power losses and general operation of the bearing with a known lubricant. The first test bearing was then operated with Polyphenyl Ether 5P4E lubricant at approximately





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500°F oil inlet temperatures up to and including 3.25×10^{6} DN operation. The second test bearing was operated with Polyphenyl Ether 5P4E lubricant at approximately 500°F oil inlet temperature and successfully completed 30 minutes of continuous operation at 3.5×10^{6} DN (25,000 rpm) with stabilized temperatures. The second test bearing . as then subjected to a series c rapid acceleration/deceleration tests and removed for visual inspection.

2. MIL-L-7808, TEST BEARING A1

A data statery sheet for the operation of the first test bearing s/n No. Al is shown in Table XIX. The bearing outer race and front and rear drain oil temperature increases as a function of bearing speed for the testing shown in Figure 31.

Twenty-five minutes of successful operation at 3.50×10^{6} DN was obtained (see runs 49 and 50). The bearing was removed from the test cell and visually inspected. The inner race, rollers and outer race showed some discoloration due to operating at 300°F average outer race temperatures. The rolling surfaces looked to be in exellent condition with only the normal amount of burnishing to be expected after completion of 13 hours and 40 minutes accumulated runcing time.

The cage was found to be badly worn on the inner land riding diameters over approximately a 35 degree arc on both lands. The worn areas had penetrated the silver plating and significantly deformed the steel. The worn areas were directly under one of the cage pins used for cage speed instrumentation. It appeared that the cage had excessive mass unbalance in operation which led to the localized wearing on the inner land surfaces. The s/n No. Al cage was not reused. The inper race, outer race and roller complement however were in excellent condition and were reused for the second set of tests.

3. 5P4E, TEST BEARING A1

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s/n No. Al bearing with the s/n No. B2 cage was assembled in the test rig for the high temperature Polyphenyl Ether test. A data summary sheet Table XIX

DATA SUMMARY SHEET FIRST TEST BEARING - MIL-L-7808 OIL

					۲ .	3				,		 -	_		×		11			۰. ۲.	.
- 72	OLT 72	1/1/10	Nils.	0.R	0.75	C 15	0.15	0.08	0.07	0 05	0.09	90.0	003	0.40		0.05	02.0	C. SE	0.25	1.00	
- 12-12	DATE-	1.16		0.0	0.5	0.25	0.25	6.14	0.21	0.50	0.60	0.40	0.50	0.3		0.70	1.00	0.95	0.70	0.50	
DATE	TEST	2 7	23	- 4/	- 3á	- 35	- /3	- 7	2-	- 2	2	12	16	32	27	157	23	ők	64	55	64
SH : -		00/1 L	40	207	210	5/2	232	239	242	542	248	252	261	295	275	250	273	294	319	215	5.7
MARY NARY	10019	47	9F	-21	- 16	-15	- 5	- ~	1	/ -	8	11	15	22	22	26	21	39	45	18	50
	. – . NO	110	20	227	230	235	240	240	242	299	247	251	360	270	270	275	271	285	300	310	315
DATA CUSTC	PROJ.	AT CONT	10	- 22	- 25	- 18	8) 1	- 9	1	01	22	1E	38	£5	45	53	31	55	65	74	75
CO -		0.R TENE	20	219	125	23.7	23,	242	249	260	263	271	283	297	293	302	281	301	320	336	042
RBON	11. 2	Oil Teny.	ы	248	246	250	245	246	248	250	241	240	245	248	248	249	250	246	255	262	265
KE C.A.	, S	Oil Ru	16/min	53	5:3	5;3	8.5	<i>8</i> .5	R.5	8.S	5:5	8,7	86	8:5	5.0	8.9	9.4	9.9	9.6	9.6	8.6
PUF	100 808	prog	145	471	954	428	477	477	777	477	453	462	452	482	959	947	500	958	474	164	462
0F 7C	2-7-1%	NQ		0.5	0.5	0.75	0.75	1.00	1.25	1.50	1.75	2.00	2:25	2.50	2.50	2.75	2.50	300	3.25	3.50	3.50
i i <u>ë ST (</u>	ï	Realing	140	9	//	15	19	17	23	25	1E	55	35	38	39	41	46	47	48	49	Sí.

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vs. Speed, MIL-L-7808 G

is given in Table XX. The temperature differentials in the bearing for the outer race and drain temperatures are shown on Figure 32. The bearing was initially operated up to and including 3.0×10^6 DN operation. At this point the Polyphenyl Ether lubricant was being pumped back through the quill shaft Figure 30, to the gear box and tixing with NIL-L-7808 oil in the gear box system. The rig was shut down and lube system changed so that the gear box as well as the test head would operate on 5P4E lubricant and would avoid the loss of excessive amounts of the test cil. Testing was then resumed and resulted in the second set of curves as shown on Figure 32.

Successful operation of the test bearing was accomplished up to and including 3.25 x 10⁶ DN operatica. After approximately 10 minutes operation at 3.50 x 10^6 DN operation (run No. 86), the bearing failed abruptly as evidenced by a seizure and a dead stop of the test shaft. The failed test bearing was then removed for visual examination. The inner race had separated and formed into two circumferential halves approximately in the center of the race. The rings had also snapped open at a location corresponding to one of the key slots as shown in Figure 33. A considerable amount of debris was trapped between the inner race cavity and the shaft. Figure 34 is a photograph of the rollers, cage and otter race assembly still in the cuter race loading ring. The rollers all had a flat surface on the major diameter which presumably was caused when the rollers locked up and braked the inner race to a complete halt. Several of the rollers are shown on Figure 35. All of the rollers had at least one of the small diameters separated from the body of the roller as shown in Figure 35 and in several cases both minor diameters had been separated. Subsequent metallurgical examination of the fractured surfaces supports the fact that the small diameters were twisted or torqued cut of the major diameter. They were not reversed bending fatigue failures. Complete seizure of the inner race creating sufficient friction to grind flat from the rollers (as shown in Figure 35) would create tremendous torques on the minor roller diameters. The outer race is shown in Figure 36 and the cage is shown in Figure 37. The cage suffered serious distortion as would be anticipated.

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Table XX

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DATA SUMMARY SHEET FIRST TEST BEARING - POLYPHENYL ETHER 5P4E

	:	2			-	1	-	:			- ;		· • • •	;		~ .		•		 •
	- 72	11-6-7	120	1-12/14	. 55	,06	01	. 25	· / ·		./3			20.	35	01.1				
	(1-21-	DATE -	112. 11. 11. 11. 11. 12. 12. 12. 12. 12.	5/10/ 5/10/		^۲ در.	41	0	. 40 .		92.			:24	1.90	2.10				
1	DATE	TEST	44		30	40	s,	° C	75	40	50	R -	715	25	+ 65 :	+80		-	-	G
U U U U U U			0014	40	SUG	190	231	555	555	2.40	535	170	クット	5.8.4	530	530				250
VA AN	111.1	10018	1- V	35	145	55	5.2	04	50	75'	ŞÜ	- 10	+ 30	26+	+83	+100				30
N SUM	MER-	10. 10.	11.2	70	440	505	575	555	560	555	565	380	930	525	550	570				273
ATAC.	cusic	PROJ.	2 C K	50	-38	- 28	- 22	- 9	+ 8	+ 12	+ 18	- 82	- 76	+ 29	+ 51	+ 50				- 37
C0-	1-1	11/5 =	1	2/3	407	422	458	476	958	492	503	305	424	47.7	503	520				112
RBON	Mr. Ree	P 500 5	011 Temp	30	345	9:20	480	455	980	980	-485	190	470	178	7.62	470		·		ع ج ک
RCA	actes R	59956	0.1 F/or	14/2000	9.9	10.6	10.7	10.4	. 9.9	8.5	9.3	9.2	9.5	9.8	10.0	10.2		-		
PUF	Vel Di	ETher	pro 7	(11.5	441	453	166	454	459	164	438	471	965	959	114	159				
	0F	1 Persol of	NO	•	0,5	1.0	1.5	0.2	2.5	3. 75	3.00	1.0	3.0	3.0	1 3 25	3.50				0.5
	TEST (2.1	Reading	04	61	61	67	70	73	75	66	So	52	84	55	36				100
		•						-									-		 	







Figure 33. Test Bearing No. 1, Inner Race Failure



Figure 34. Test Bearing No. 1 Outer Race Cage Roller Assembly Failure



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Figure 35. Failed Rollers



Figure 36. Test Bearing No. 1 Outer Ring Failure



Figure 37. Test Bearing No. 1 Cage Failure

The test bearing Al accumulated a total of 24 hours operation at various speeds of which 10 hours and 20 minutes were with the Polyphenyl Ether lubricant at high temperature. The failure of the inner race, Figure 33, can be explained by two possible failure modes, the first being thermal lockup of the bearing where the growth of the inner race both thermally and due to centrifugal forces exceeds the growth rate of the outer race resulting in internal diametral preload. Roller bearings are exceptionally stiff and small amounts of diametral preload (on the order of 0.0002 inches or more) can result in very high roiler loadings. Greatly increased roller loadings at the inner race contact (see Figure 17) would then undoubtedly fail in reverse bending fatigue. The second possible failure mode is that sufficient clearance did remain in the bearing and that failure of the inner race was due entirely to reverse bending fatigue. The finite element analysis of the inner ring as shown on Figure 13 and summarized in Table IX did not indicate that excessive stress variation would be anticipated at 3.5×10^6 DN operation. Therefore, thermal lockup was suspected. The fact that the bearing did operate for approximately 10 minutes at the higher speed level, however, is not indicative of thermal lockup. Thermal lockup occurs very rapidly after an increase of speed.

The concern over thermal lockup was resolved by additional thermal analysis of the test bearing operating conditions. The initial thermal gradients in the bearing for design purposes did not include any effects of external energy being introduced into the system because of dissipation in the slave bearing. Table XXI shows the results of the thermal analysis with external energy introduced at node 21 on the shaft surface external to the test bearing. Also the effect of insulation around the outer diameter or outer surface of the test head was introduced into this analysis. The results of the improved thermal analysis for the actual load, speed and lubricant supply conditions of the test agree closely with the observed temperatures of Table XX. The outer race temperature per analysis (node 18), was 527.86°F as compared to average observed outer race temperatures of 520°F. The total AT to the oil by analysis in Table XXI was (node 11)

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TABLE XXI

Thermal Analysis of First Test Bearing Conditions with 5P4E

THE CONVERGED TEMPERATURE DISTRIBUTION (DEG F.) IS AS FOLLOWS:

- 695.016692 - 545.986656	522•194206	: 540.523114	544.477898	: 500.870ng3	550.633530	: 576.609593	: 532.211386	= 541.600281	: 555.119461	: 586.775314	= 550.U68855	= F47.625595	- J46.366028	= 545.315437	= 544.274139	= 527.360451	: 513.45°312	: 474.929032	575.953255	96447 2 •14	528.370239
1 INNER SHAFT COULANT 2 INNER SHAFT SURFAC	5 OUTER SHAFT SURFACE AT LEANING	4 INWER RACE AT SHAFT	5 UNDER-CUT SURFACE OF 11. ER RACE :	6 UNDER RACE COOLANT	7 INNER NACE NEYOND ROLLEN CURTACT	B CAUE AT THE LAND	9 CAGE INNER SURFACE :	10 CAGE OUTER SURFACE :	11 INTERNAL LURKICANT TO BEANING	12 ROLLERS	13 INHER HACE AT ROLLERS	14 INMER SURFACE OF OUTER MAC	15 INVER COOLED SURFACE UNTEN RACE :	16 OUTER RACE LUBRICALT	17 OUTER COOLED SURFACE UNTER PALE :	18 BEARING OUTER DIARLTER	19 CHAMBER "ALL (IINEN SIL.)	20 LUKUING BOLT (STRUI) RULT	21 SHAFT (LXTERNAL TO BEANING)	BULK TEFTERATIONE ALSE OF LUERLONT	AVERAGE JULK OIL TEPPER. TURE

555° less oil inlet temperature of 470° resulting in an 85° AT to the oil. This compares very favorably to the 90° average of the oil out front and oil out rear of Table XX. The calculated internal diametral clearance in the bearing under the thermal gradients shown in Table XXI is 0.0051 inches. This number includes all thermal and centrifugal growths. A number of variations in the assumptions of the thermal analysis such as percentage air oil mixture, etc. were tried and found to have little effect on the thermal gradients in the bearing. Therefore the conclusion was reached that the bearing did not fail due to thermal lockup but rather failed due to reverse bending fatigue of the undercut inner race. The finite element analysis summarized in Table IX would indicate that the stress variations with roller loading should not have exceeded the long term life value in reverse bending fatigue. nowever, the test bearing at the point of failure had experienced 39.7 x 10° cycles of stress or coller load variations between rollers and inner races with both MIL-L-7808 and the 5P4E lubricant. The values were essentially equal with each type of oil. The decision was made to proceed with testing of the second bearing on the assumption that thermal lockup was not the failure mode and to limit the bearing load to no more than 500 pounds so as not to significantly increase the danger of failure due to reverse bending fatigue.

4. 5P4E, TEST BEARING C3

The second test bearing, Serial No. C3, was assembled in the rig for high temperature testing with 5P4E lubricanc. A summary data sheet of the test is given in Table XXII and the ΔT 's as a function of speed are plotted in Figure 38. This bearing achieved 30 minutes of temperature stabilized operation at 3.5 x 10⁶ DN (25,000 rpm) under a 471 lb. radial load. The only variation in test conditions over the first test bearing was the addition of an auxiliary jet towards the rear of the bearing at the inner race and cage land contact. This auxiliary jet supplied approximately 2 lbs. per minute oil flow of the total reported in the test log.

The test bearing was then subjected to four rapid acceleration and deceleration tests between 1.5 x 10^6 DN and 3.5 x 10^6 DN in 15 seconds each.

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TABLE XXIY

DATA SUMMARY SHEET, SECOND TEST BEARING POLYPHENYL ETHER 5P4E

-12-21-23-72 TEST + 30 5.4+ - 55 + 30 125 -50 ~ 40 135 +10 745 150 +50 +10 535 + 30 イン SHEET 300 105 450 570 280 2.S.S. 470 490 いご 535 280 540 Yor yo 250 595 04 10018 SUMMARY + 35 ÷20 10/-+-+55 155 + 55 +40 +20 +40 155 いにさ 755 +55 レン + #5 d CUSIOMER- / PROJ. NO.- // 575 540 530 565 570 550 SSU 990 420 -23,960 345 515 Sou 0212 - 17 366 PURE CARPON CO-DATA over el - 28 68-+30 + 10 +18 +25 + 27 5 + + 22 1-29 50 い 11 1 + 5.18 \$ 5000 High 545 125% 439 503 Sis 5.84 542 308 372 397 655-500 501 9.2 221 130 0 1/20 325 330 500 ういち 54% 260 100 いいい 500 Trenp 155 195 Sit てい 0 i Õ - D. V.A. Diamerer Roller (3.0 23.3 13.4 9.3 HOM 13.0 15.6 661 16.5 1.12 11.3 21.4 21.9 13.1 01 1 5:3 159 5188 626 476 153 453 471 171 471 124-がい 124 11.4 471 1001 145 3,53 3.25 3.43 3.43 3,73 1.50 . 63 Phany . Ś 0 19 0 6 2.5 30 0 17 s' S کر о . Redug 3 132 133 125 129 3 2.1 104 12 500 5 かい 126 10

MY 2001 4111 V (1)







The second test bearing is shown in Figure 39. All of the race and roller operating surfaces were in excellent condition. The cage was in good condition and showed even burnished wear areas in the cage roller to pocket contacting surfaces. With the exception of the riding land, the cage was in excellent condition. The silver plate was not worn through at any position and very little discoloration was noticed. The cage inner land riding surfaces however were discolored over a 90° arc indicating insufficient lubricant to the cage lands. The inner race shows a uniformly burnished area in the center of the race where the rollers contacted. Distress is noted in the cage land riding areas on the inner race. The outer race was in excellent condition. There was some indication in the discoloration due to temperature that the rear of the bearing was cooler than the front face of the bearing. This can be attributed to the auxiliary oil jet directed at the rear face of the bearing.

The Polyphenyl Ether 5P4E lubricant used in the test was supplied by the Aero Propulsion Laboratory, Wright-Patterson Air Force Base. Some of the fluid was new fluid and some of the fluid furnished was reconstituted fluid. It was noted that when new 5P4E fluid was added to the oil sump, that foaming of the oil occurred for a period of 10 to 20 minutes and then subsided. This foaming did not occur when reconstituted 5P4E fluid was added to the sump. The foaming action did not seem to have any effect upon bearing operation.



SECTION VII

CONCLUSIONS

The second dual diameter roller bearing successfully operated for 30 minutes of stabilized temperature operation at a shaft speed of 25,000 rpm. This is 3.5×10^6 DN operation of a 140 mm bore bearing. External redial load was 471 lbs. and the lubricant was 5P4E Polyphenyl Ether at approximately 500°F oil inlet temperature.

The failure of the first test bearing was attributed to reverse bending fatigue of the M-50 steel inner race at high speed and 600°F operating temperatures. The calculated stress levels were below known allowable stress levels for long term operation. This suggests that additional carefully controlled reverse bending fatigue data is required for M-50 bearing steels for elevated temperature operation. Any future tests of the dual diameter should use a solid inner race, eliminating the undercut,

The lubrication method of introducing the oil to a cavity in the inner race and through orifices directly into the bearing intering was benerally successful, however distress and wear was observed at the cage inner land riding surface.

The suc.essful operation of the second test bearing establishes the validity of the design approach. A complete systems analysis using existing state-of-the-art elastohydrodynamic technology, fluid mechanics, theory and thermal analysis techniques, can be used to design a completely new bearing concept and enable initial prototype testing to be successful at speeds and temperatures beyond the realm of current experience.

APPENDIX I

TEST LOGS

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APPENDIX II

GAS TURBINE ENGINE MAINSHAFT ROLLER BEARING - SYSTEM ANALYSIS

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ABSTRACT

An interdiciplinary systems analysis is presented for highspeed gas turbine engine mainshaft roller bearings which will enable the designer to meet the demands for ever higher rotative speeds and operating temperatures. The latest elastohydrodynamic experimental traction data is included. Analytical results cite a need for better definition of the rolling friction portion of the total traction. A fluid mechanics model for the detailed analysis of fluid drags is developed based upon a turbulent vortex-dominated flow and includes the effect of lubricant flow through the bearing. Typical cage equilibrium solutions show evidence of possible unstable operation. A complete thermal analysis including dynamic and thermal effects upon bearing dimensions and resulting clearances is also included. Heat transfor coefficients are given in detail. Shaft power loss and cage slip predictions as a function of load, speed, and lubricant supply correlate well with available experimental data.

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The use of elastohydrodynamic lubrication theory for rolling bearing a alysis was first suggested by Dowson and Higginson^[1]. The first use of digital computers for the analysis of high speed roller bearing performance was by Harris^[2]. The Harris paper presented an analytical method to predict skidding in high-speed roller bearings. The influence of the amount of lubricant supply on cage and roller motion in high speed roller bearings was experimentally described and analytically discussed by Boness^[3]. A refinement was introduced by Poplawski^[4] with the solution of all of the loaded rollers under the varying load pattern resulting from external radial load. He also introduced a fluid "churning" loss and cage pilot surface friction formulations.

All of the previous analytical work used the Dowson-Higginson^[1] isothermal elastohydrodynamic (EHD), formulation. A recent comprehensive review of EHD theory and experimental data by McGrew, et al^[5] resulted in selection and recommendation of the latest and most applicable EHD formulations. This preliminary EHD design manual^[5] also presents computer subroucines for the calculation of oil film thickness including thermal effects developed by Cheng^[6] and EHD traction subroutines fitted to available disk machine experimental data.

The present paper presents a system analysis of a high-speed roller bearing under radial loading as commonly used on gas turbine engine mainshafts. Oil film thickness, traction, and hydrodynamic pressure forces acting in an elastohydrodynamic roller-race contact are computed according to the latest available techniques^[5]. A complete fluid mechanics model is developed in order to more accurately predict the fluid drag losses acting upon roller, race, and cage moving surfaces. Turbulent vortexdominated flow theory is used to calculate boundary layer stresses. Finally, a complete thermal analysis is described.

> -1-115

Combining the resulting thermal deformations with deformations of the bearing components due to centrifugal growth completely defines changes in critical bearing operating parameters at each step of the iterative solution process. The thickness of an EHD oil film is determined by the temperature and viscosity at the inlet to the contact. This inlet oil temperature is very sensitive to the temperature gradients which exist within the bearing. Oil viscosity changes and dimensional changes throughout the bearing as a function of temperatures are included. The thermal solution as expected is dependent upon lubricant flow rate, method of application (under inner race, thorough bearing, etc.) and external heat paths.

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LOAD AND SPEED EQUILIBRIUM

Elastohydrodynamic Pressure Forces and Tractions

The surface velocities and relative rotational speeds of rollers and raceways are shown in Fig. 1 and follow the nomenclature of Harris^[2]. Sliding velocities, V_{ij} and V_{oj} are defined as positive when the surface velocity of the race is greater than the surface velocity of the roller and is equal to their difference. The rolling or entrainment velocities U_{ij} and U_{oj} are always positive and defined as the average of raceway and roller solace velocities. The sliding velocities and entrainment velocities are made dimensionless by introduction of the fluid entrance viscosity, n_e , reduced modulus of elasticity, E', and equivalent cylinder radius, R, for each contact as suggested by Dowson^[1].

Forces and moments acting on a loaded roller are shown in Fig. 2 and those acting on an unloaded roller are shown in Fig. 3. The effect of cage orbital speed, ω_c , is to create a dynamic body force on the roller acting radially outwards. Figs. 2 and 3 use D'Alembert's principle^[7] to represent the summation of this roller body forces as an inertia force CF* acting through the center mass of the rollers.

 $CF^{\star} = \frac{1}{2} M_r E \omega_c^2$

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Thus Figs. 2 and 3 are free body diagrams of the roller in static and dynamic steady state equilibrium with all static and dynamic forces shown.

Fluid pressure forces Q_{ij} and Q_{oj} tending to translate the roller relative to the raceways are described by Dowson, etal^[1] and approximated by Harris^[2] for synthetic lubricants as:

$$\overline{Q}_{ij} = 18.4 (1-\gamma) G^{-0.3} \overline{\overline{U}}_{ij}^{0.7}$$

$$\overline{Q}_{oj} = 18.4 (1+\gamma) G^{-0.3} \overline{\overline{U}}_{oj}^{0.7}$$
(2)

Traction forces T_{ij} and T_{cj} consist of fluid frictional drag forces as described by elastohydrodynamic lubrication theory. They consist of rolling and sliding friction forces. Using the Harris^[2] approximation for Q_{ij} and Q_{oj} they are expressed as:

$$T_{ij} = -9.2G^{-0.3}\overline{v}_{ij}^{0.7} \ell_{ij}^{E'R_{i}} + \frac{|V_{ij}|}{V_{ij}} f(T_{e})_{i}^{P_{ij}}$$

$$T_{oj} = -9.2G^{-0.3} \overline{v}_{oj}^{0.7} \ell_{oj}^{E'R_{o}} + \frac{|V_{oj}|}{V_{oj}} f(T_{e})_{o}^{P_{oj}}$$

The coefficient of traction, f, for the sliding portion has been obtained by experiment from disk machines. This coefficient has been curve fitted to existing data by McGrew, etal^[5] as a function of three dimensionless parameters G_1 , G_2 , G_3 and is represented symbolically as:

$$f(Te) = F(G_1, G_2, G_3, 30^{\circ}C) - 0.001 (Te-86^{\circ}F)$$

where Te is the temperature, °F, at the entrance to the EHD contact. The three dimensionless parameters (given in the nomenclature) express shear rate effects, thermal heating effects, and pressure viscosity effects, respectively. Graphs and computer subroutines for the traction coefficient, f, are given in reference, [5] and are not repeated in this paper.

> -3-117

(3)

(4)

It should be noted that this representation of experimentally obtained traction data is extrapolated for both high and low sliding velocities to \cdot make the data useful over a wide range for the analysis of bearing systems. At small values of G₁ all curves of, f, have a 45° slope. This corresponds to the fact that at small sliding speeds the frictional coefficient varies linearly with sliding speed.

 P_{oj} and P_{ij} are raceway normal forces transmitted to the roller by the external bearing load. F_{add} is a force resulting from contact between the roller and the guiding shoulders of the raceway. M_{rj} is a symbolic representation of all of the fluid resisting moments acting on the roller. F_{cj} is loading due to the cage. A loaded roller, Fig. 2, which drives the cage results in a positive value of F_{cj} as shown. An unloaded roller is driven by the cage as shown in Fig. 3. A retarding torque is always present as a result of rubbing coulomb friction between the roller and cage pocket.

Load Roller Equilibrium

Summation of forces in the horizontal and vertical directions, Fig. 2, for the loaded roller must equal zero for steady state translating equilibrium.

$$Q_{ij} + T_{ij} - Q_{oj} - T_{oj} - F_{cj} + F_{add} = 0$$
 (5)

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$$P_{ij} + CF^{*} - \mu F_{cj} - P_{oj} = 0$$
 (6)

Summation of moments about the roller axis of rotation, Fig. 2, must equal zero for steady state rotary motion equilibrium: (The term F_{add} resulting from roller end contact with the guiding shoulder is described later by Eq. (36).

$$T_{ij} \frac{d}{2} + T_{oj} \frac{d}{2} - \mu F_{cj} \frac{d}{2} - M_{rj} \neq 0 \stackrel{\sim}{=} I_{rj} \frac{\partial \omega r_{j}}{\partial t}$$
(7)

The equations of equilibrium for the unloaded roller are similar and can easily be derived-from Fig. 3. (Also Ref. [2]).

> -4-118

EHD Oil Film Thickness

The average oil film thickness in the Hertzian zone is computed according to the Dowson, etal^[1] isothermal theory for line contact and modified with the Cheng^[6] thermal correction factor, $\phi_{\rm T}$.^[5] The film thickness is determined by the lubricant velocity, $\eta_{\rm e}$, at the inlet.

$$h = \frac{1.6 \ G^{0.6} \ \overline{U}^{0.7} R \ \phi_{T}}{\overline{U}^{0.13}}$$
(8)

Roller Load Distribution

The summation of all inner race loadings, P_{ij} , equals the applied external radial load, F_x . For simplicity, the solution will be given in a single degree of freedom, along X. Then:

$$F_{x} - \sum_{ij}^{2} P_{ij} \cos \phi_{j} \neq 0 = \epsilon LD$$
(9)

$$j = 1$$

$$\cos \phi_{i} = \frac{2 j \pi}{Z}$$
(10)

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Cage Equilibrium

Steady state rotation of the cage requires that the summation of all fluid film forces and roller to cage forces acting on the cage be in equil/brium. The sum of the moments of all of the fluid film forces acting on the cage surfaces and taken about the center of bearing rotation will be represented symbolically by H_c and will be considered to be a drag or retarding moment when expressed in the positive sense. An inner land riding cage will develop a driving torque in the land, which helps to drive the cage. An outer land riding cage develops a drag torque in the lands. An unloaded roller by definition has a negative cage force F_c , Fig. 3. A loaded roller has either a psotive driving cage force, F_c , or a negative drag force, per Eq. (5) and Fig. 2.

$$\frac{E}{2}\sum_{i=1}^{2} (F_{cj}) - N_{c} \neq 0 = I_{c} - \frac{\partial \omega_{c}}{\partial t}$$
(11)

-5-119

Method of Solution

A flow chart of the method of solution is given in Fig. 4. The solution consists of six nested single degree of freedom iterative loops. Two convergence schemes are used. Load distribution solutions are solved using classical Newton-Raphson matrix inversion techniques^[8] Roller speed and cage speed solutions use a modified time step solution because of the multiple valued traction function.

Equations (7) and (11) are written as inequalities where the right hand side is the product of the polar moment of inertia and the first time derivative of the rotational speed. The desired steady state solution will occur when the right hand side vanishes. The magnitude and sign of the right hand side is used to compute the increment of cage or roller speed. Roller inertias are small, and extremely small time steps would be required for solution. A modified time step in the form of cage or roller speed steps proportional to the right hand side (or moment unbalance) are used for the solution. Initial step size is determined by experience to minimize computer execution time. Changes in speed regiems (DN values) and change of lubricant usually requ' es an adjustment in step size.

Determination of Loaded Rollers

The radial displacement, $\delta \phi_i$, at any location angle, ϕ_i , is:

$$\delta\phi_{j} = X\cos\phi_{j} - \frac{Pd}{2} + x'_{\psi}$$
(12)

where x_{ϕ}^{\dagger} is a constant deviation from a true circular profile. A plus value of x_{ϕ}^{\dagger} means a radially outward deviation of the inner race or a radial inward deviation of the outer race at location ϕ , or the algebraic sum of deviations of both races from a true circular profile. An elliptical out-of-round race or any race shape in general^[9] can be described by specifying values of x^{\dagger} for every location angle, ϕ_{4} .

> -6-120

A quantity, δ_{TOTAL} , is defined as the total deflection requirement for an unloaded roller assuming that it is initially in dry line contact (no EHL film, no roller load, no bearing clearance) with both inner and outer races.

$$\delta_{\text{TOTAL}} = \delta_0 - h_0 - h_1 - \delta_{\text{ROT}} + \delta_{\text{CF}}$$
(13)

where:

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$$\delta_{u} = \left(\frac{CF^{*}}{K_{o}}\right)^{9/10}$$
(14)

$$K_{o} = 11.4 \times 10^{6} \ell_{o}^{8/9}$$
 (15)

δ₀ is the elastic compression or approach of the roll centeru line towards a distant point in the outer race using the Palmgren^[8] approximation.

h is the EHD film thickness at the outer race contact per u Eq. (8).

h₁ is the EHD film thickness at the inner race contact per u Eq. (8) with a load of $P_{ij}/\ell_{ij} = 1.0$ lbs./inch.

 δ_{ROT} is the increase in diameter of the unloaded roller caused u by rotation, ω_{ri} , about its own axis. (See Table 1).

 $\int_{u}^{0} CF$ is the compression of a hollow roller as a ring due to the inertia force $CF^{*[10]}$.

$$\int_{u}^{\delta} CF = \frac{CF^{*}r^{3}}{EI} \left(\frac{U.46}{2R} 74 \right)$$
(16)

r = the mean radius of the hollow roller (in.)

I = area moment of Inertia of the ring section (in, 4)

-7-121 Determination of a loaded roller is then made by:

$$\begin{cases} \delta_{\phi_{j}} \leq \delta_{\text{TOTAL}} & P_{ij} = 0 \text{ UNLOADED} \\ \delta_{\phi_{j}} > \delta_{\text{TOTAL}} & P_{ij} > 0 \text{ LOADED} \end{cases}$$

$$(17)$$

Eq. (17) states that if the total radial displacement, $\delta \phi_j$, is greater than the radial displacement value, δ_{TOTAL} of an unloaded roller; then the roller is loaded. If $\delta \phi_j > \delta_{\text{TOTAL}}$ then P_{ij}/ℓ_{ij} must equal or exceed 1.0 lb/inch. This test is made at each roller location as shown by iteration loop 4, Fig. 4, for the radial load solution.

Solution of a Loaded Roller

The solution of a loaded roller according to Eq. (5), (6), and (7) is accomplished by means of two nested iterations #5-Inver Race Roll Load, P_{ij} and #6-Roll Speed, ω_{rj} , as shown in Fig. 4.

The inner loop #6 to determine roll speed ω_{rj} (by means of Eq. (7)) is solved using the modified time step technique described above. This solution requires a known value of the inner race load, P_{ii} .

The inner race loading, P_{ij} , of a loaded roller is determined by using Newton-Raphson iteration (loop 5 of Fig. 4) and assuming an initial value of P_{ij} an then calculating corrections to it. An initial value can be closely determined from the external radial load and using Stribeck's constant for the maximum roller load.

The cage to roller contact force F is solved directly from Eq. (5) for a given value of ω_{rj} . Roller speed is determined by iteratively solving Eq. (7) with a modified time step or incremental values of ω_{rj} . The solution of Eq. (7) is very sensitive to small changes to torques about the roll axis.

The μ Fcj term of Eq. (6) is neglected in the solution. The coulomb coefficient of friction μ is usually less than 0.1. The traction coefficient in the EHD contact, $f(T_e)$, is always less than 0.1 and usually

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less than .01. Thus the F_{cj} term is always less than 1% and usually less than 0.1% of P_{oj} .

The relationship of radial displacement, x, of the inner ring upon a loaded roller is:

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$$\delta_{\text{oj}} + \delta_{\text{ij}} - h_{\text{oj}} - h_{\text{ij}} + \delta_{\text{CF}_{j}} + \delta_{r_{j}} - \delta_{\text{rot}_{j}} - X_{\text{cos}\phi_{j}} + \frac{Pd}{2} - X_{\phi}^{*} \neq 0 = \varepsilon_{j} \quad (18)$$

Where δ_{CF_j} and δ_{r_j} refer to a hollow roller and are omitted from Eq. (18) when solving solid rollers. δ_{r_j} is the ring compression of a hollow roller per Timoshenko^[11] as:

$$\delta_{\mathbf{r}_{j}} = \frac{C_{\mathbf{r}j}}{\ell_{\mathbf{i}j}} \cdot P_{\mathbf{i}j}$$
(19)

$$C_{rj} = \frac{r^2}{tEe} \left\{ \frac{\Pi}{4} - \frac{2}{\Pi} \left(\frac{1-\frac{e^2}{r^2}}{r^2} \right) + 2\frac{e}{R} \left[\frac{2}{\Pi} \left(1-\frac{e}{r} \right) - \frac{\Pi}{8} \right] + \frac{\Pi}{4} \frac{\alpha Ee}{C} \right\}$$
(20)

Subsequent values of P are then:

$$\left(\mathbf{P}_{ij} \right)_{p+1} = \left(\mathbf{P}_{ij} \right)_{p} - \left(\frac{\delta \varepsilon_{j}}{\delta \mathbf{P}_{ij}} \right)_{p}$$
 (21)

Solution of Eq. (18) using corrected values of P_{ij} from Eq. (21) is rapid and no convergence difficulties have been encountered.

The load carried by each loaded roller is determined by the Radial load solution loop No. 4 of Fig. 4. . .q. (9) is solved by Newton-Raphson iteration using the radial displacement, x of Eq. (18) as the variable. An initial value of x is computed using an assumption for the value of P_{ij} , Eqs. (6, 15, and 16), assuming pure rolling (no slip) for

-9-123 the maximum loaded roller speed, and cage speeed. Subsequent values of x are:

$$(X)_{p+1} = (X)_p - \left\{ \frac{\partial \varepsilon LD}{\partial X} \right\}_p$$
(22)

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Solution of Eq. (9) using the corrected values of x is rapid and no convergence difficulties have been encountered.



FLUID MECHANICS MODEL

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Flow models for the (usually) turbulent flow field are briefly discussed, and then applied to calculation of fluid drags acting on roller and cage surfaces. The influence of the mixed component lubricant-air fluid field is treated with respect to definition of wall shear stresses explicit in the calculation of fluid drags. Lastly, the consequences of the fluid drags acting on roller and cage surfaces are described in relation to their influence on bearing behavior.

At least one previous investigator, Poplawski^[4], has included the effects of fluid drags in an analytical model of voller bearing performance. This model lumped the effects of fluid drags into a "churning loss" and suggested the use of an effective air-oil density to improve the analytical description. The Poplawski^[4] model demonstrated significantly better correlation with existing experimental data than did the original Harris^[2] model. The present work examines in more detail the influence of fluid drag torques acting on individual surfaces, and accounts for the driving influence of such torques on certain cage and roller surfaces as well as the retarding influences of such torques. Both the energy dissipation and the convective heat transfer within the bearings are closely associated with the viscous fluid behavior of the lubricant. The techniques employed in this analysis use a combination of empiricial and theoretical treatments to define these effects.

From the standpoint of the dynamic solution of the interacting rollers, races, and cage, the most important factor is calculation of the friction drags on the element surfaces. In general, this effect is described by an equation of the form:

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 $T = \tau_{u}Ar$

(23)

where T is the drag torque acting over the element surface,

A is the surface area,

r is the reference radius from the center of rotation,

 τ_{ω} is the wall shear stress

The description of the wall shear stress is a function of the fluid properties, the motion of the surface with respect to the fluid body, and the proximity of other surfaces influenced by the same fluid. Regarding the last mentioned, close clearances between rotating members of the bearing have especially strong influences.

Fritz^[12]has investigated the wall shear stress phenomenon in journal bearings with vortex turbulent flow. Examination of typical roller-cage clearance to roller radius ratios, and Reynolds and Taylor numbers representative of 1 x 10^6 DN and higher bearing operation clearly place such fluid flows in the turbulent-vortex regime as defined by Fritz^[12] and illustrated for a typical case in his Fig. 3. For surface finishes and bearing dimensions typical of 1 x 10^6 DN and higher roller bearings, the flows representative of cage surfaces appears to be in the couette turbulence regime.

Wall shear stress for a surface rotating in a viscous fluid is defined by the relation [13]:

$$\tau_{\rm w} = f(1/2 \ \rho \ U^2)$$
 (24)

where U = mass average velocity of fluid

 ρ = fluid density

f = friction factor

For this correlation, $U = \frac{r\omega}{2}$

The applicable friction factors from Fritz^[12], and curve fitted for computer analysis' are:

$$f/f_{L} = 1.3 \left(\frac{N_{Ta}}{41}\right)^{0.539474}$$
 (25)

-12-126 for the vortex-turbulent correlation and

$$f_{f_{L}} = 3.0 \left(\frac{N_{Re}}{2500}\right)^{0.85396}$$
 (26)

for the couette turbulent correlation.

Here,

$$N_{Re} = \frac{r\omega C}{v}$$
 is the Reynolds number (27)

$$N_{Ta} = \frac{r\omega C}{v} \sqrt{\frac{C}{r}}$$
 is the Taylor number (28)

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$$f_L = \frac{16}{N_{Re}}$$
 is the laminar friction factor (29)

Should calculation yield a Reynolds number less than 2500, or a Taylor number less than 41, a circumstance virtually impossible in high speed roller bearings, the appropriate friction factor then can be taken as the laminar friction factor f_T .

In addition to the fluid drag acting on the cylindrical surfaces, the roller ends or cage sides provide an additional source of drag. Per Refs. [13] and [14] for a rotating disk wetted on both sides, the total moment resulting from fluid drag about the disk centerline is given by:

$$M_{\rm T} = \frac{1}{2} \rho \,\omega^2 \,r^5 \,C_{\rm n}$$
(30)

where C_n

$$= \begin{cases} 3.87/(N_{Re})^{1/2} \text{ for laminar flow, } N_{Re} < 300,000 \\ 0.196/(N_{Re})^{1/5} \text{ for turbulent flow, } N_{Re} > 300,000 \end{cases} (31)$$

where here

$$P_{Re} = \begin{bmatrix} \frac{r^2 \omega}{v} \end{bmatrix}$$
(32)

For hollow rollers and for the cage, account must be taken of the areas pertinent to the calculations by modifying the radius factor of the disk equation to the form:

$$r^{5} = r_{out}^{3} (r_{out}^{2} - r_{in}^{2})$$
 (33)

where

r is the outer radius

r, is the inside radius

This is at least true to a good approximation in the case of the roller, since examination of the integral from which a closed form solution of (30) is derived shows that approximately 75% of the total moment contribution comes from the area defined by the outer 50% of the roller radius. In the case of the cage, the "disk" torque acting on the cage side surfaces is less justifiable on theoretical grounds, but the calculated effect has been shown to be small with respect to the cylindrical surface contribution in this instance.

Basic to the above calculations is the realization that highspeed roller bearings never are completely flooded with lubricant, and seldom are more than 15 to 20% full of oil within the bearing for very high speed operation. Indeed, an excess of oil within the bearing has been conclusively shown by Boness to produce adverse effects on bearing operation^[3]. Notion of the many moving parts within the bearing, in particular the pumping action of the rollers, will tend to induce an air oil mixture within the bearing. Nueristically, it can be argued that for pure viscosity effects in a turbulent regime, this phenomenon will have little tendency to change the fluid behavior from that of a flooded bearing, since in general such effects are confined to relatively thin boundary layers adjacent to the surfaces. Further, the turbulent mechanisms of momentum and energy transfer depends on physical displacement of fluid particles. However, the density or inertia effects of the air oil

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mixture can be drastically influenced by comparison to that of a flooded bearing. Hence, it becomes necessary to modify the density of the fluid mixture, choosing a volumetric basis for the calculation:

$$\rho_{av} = (\rho_{oil} \times oil volume + \rho_{air} \times air volume)/Total Volume$$

$$= \rho_{\text{oil}} \times \frac{\text{oil volume}}{\text{Total volume}}, \text{ defined as } \rho_{\text{oil}} \times \text{DECFUL} = \text{DENS}$$
(34)

The apparent density of the fluid is taken as this in roller drag calculations. Recognizing that the land regions and the cage surface on the close clearance land side will be somewhat restrictive to free flow of oil out such regions, the oil density in this region is taken as:

$$\rho_{\text{HIGH}} = \frac{\rho_{\text{oll}} \times \text{DECFUL}}{0.4 + 0.6 \text{ DECFUL}}$$
(35)

The fluid density in other regions is taken as:

$$\rho_{\text{LOW}} = \frac{\rho_{\text{oil}} \times \text{DECFUL}^2}{0.4 + 0.6 \text{ DECFUL}}$$
(36)

These relations derive from flow continuity considerations, assuming 40% of the total flow will be on average confined within the higher density region. While admittedly arbitrary, these assumptions have led to excellent correlation with existing empirical data.

Roller Fluid Drag Torque

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Consider the drag torque acting on the cylindrical roller surface, as computed from equations (23) through (29), T_{rcyl}. In this case, careful consideration must be given to the calculation of the characteristic radial clearance required in the calculation. From the close clearance region between the rollers and the cage, and the interrace cage geometry, it is possible to define a characteristic clearance between

> -15-129

the rollers and the surrounding elements. Figure 5 illustrates the geometry. This clearance is defined by:

$$C \simeq C_{CH} = \frac{1}{2\pi} \int C(\theta) d\theta$$
 (37)
Circumference

Five distinct zones must be considered in the calculation on each semicylindrical half of the roller. Rollers are assumed to be in contact with either the leading cage pocket surface (driving roller) or the lagging cage pocket surface (driven roller). Generally, rollers carrying load are driving rollers and unloaded rollers are always cage-driven. Comparing the two roller surfaces, therefore, the only zone not symmetric with respect to the radial ray through the roller center is Zone III, where the entire diametral pock c clearance is taken as 10% of the roller radius. Calculation of the clearance is then straightforward, given dimensions of the cage, rollers, and races.

Similarly, the drag torque acting on the roller ends, Trend' is computed directed from Equations (30) through (33). For all roller calculations, the appropriate density is computed from Equation (34).

While not totally fluid mechanical in origin, the sensitive nature of the roller equilibrium solution requires consideration of the influence of the contact between the roller and the guiding shoulders of the cage in the torque equilibrium solution. Computer results show this effect to contribute generally 5 to 10% of total roller drag moment. Further, for a roller guided on the outer race shoulder, this moment can either drive or retard the roller, depending on the distribution of relative local velocities between roller and shoulder. The calculation requires the assumption of a coulomb coefficient of friction between the roller and shoulders, generally taken as 0.05 to 0.08 for a well lubricated contact. While strictly an integral over the contact area, the moment can be closely approximated by dividing the contact area into a number of horizontal and vertical strips or lamina as shown in Figure 6 for a

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roller guided on the outer race. A similar situation exists for a roller guided on the inner race, but the appropriate relative kinematics must be used. Further, for the inner race guided roller, the local race speed always exceeds the local roller speed, and hence always produces a net driving $\frac{1}{2}$ (we on the roller. The moment contribution, T_{add} , of the contact to $\frac{1}{2}$ roller moment is then given by

$$T_{add} = \mu_{c} \frac{F_{jG}}{A_{G}} \left\{ \sum_{N=1}^{N} \frac{|V_{Ri} - V_{Hji}|}{(V_{Ri} - V_{Hji})} A_{i'ji} r_{Hji} - 2 \sum_{i=1}^{S/2} A_{Vjk} r_{Vjk} \right\}$$
(38)

The second term always produces a retarding moment, while the sign of the first term, at least for an outer race guided roller, is dependent on the velocity distribution over the contact region.

The resultant vertical force is self-equilibrating, since the velocity distribution is asymmetric with respect to the radial ray through the roller center. However, the horizontal resultant can be either positive or negative, and contributes to the contact force between the roller and the cage, as evidenced in Equation (5). This resultant force is given by

$$F_{add} = \frac{\frac{\mu_{c} F_{jG}}{A_{G}} \sum_{i=1}^{N} \frac{|v_{Ri} - v_{Hji}|}{(v_{Ri} - v_{Hji})} A_{Hji}$$
(39)

Note that these quantities are functions of velocity, and must be determined at each roller iteration. Since F_{jG} is constant in any given problem, the derivatives of F_{acd} and T_{add} are not involved in any of the Newton-Raphson iterations.

The contact force between the roller ends and the guiding race shoulder, F_{jC} acts in the direction of the roller axis. Such a force can arise from a variety of sources. Among these are differential pressure acting across the bearing, cage angular misalignments, roller skewing due to gyroscopic moments, and unbalances in the various rotating members which give rise to dynamic forces between the roller and the guiding shoulder.

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In this formulation of the problem, the contact force was assumed to arise from "rential pressure resulting from crossflow of lubricant through and out the bearing. This axial crossflow was assumed to be superimposed on the swirling turbulent flow pattern existing in the annular spaces between the rollers, cage, and races. In traversing the distance actors the bearing, the resistance to flow in the roller axis direction, and hence the differential pressure across the bearing, will depend not only on the axial flow, but also on the flow in the tangential direction. We assume the same turbulent flow mechanism to be operating in both the axial and tangential directions. This leads, after some manipulation, to a differential pressure relation

$$\delta_{p} = \frac{f\rho \, \ell_{p} \, E\omega_{c} \, L\overline{\nu}}{16 \, A_{x}} \tag{40}$$

where

 $\boldsymbol{\ell}_{\rm D}$ is the peripheral length of a typical crossflow passage

E is the bearing pitch diameter \overline{V} is a "length of peripheral surface averaged" circumferential velocity ω_{r} is the cage angular speed

L is the bearing length

Ax is the area of a typical crossflow passage

[13] Calculation of the friction factor uses the Blasius relation

$$f = 0.3164/(4/N_{Re})$$
 (41)

where here

$$N_{Re} = \frac{4\overline{V} A_{x}}{2} \qquad (42)$$

- -18-

It is assumed that this differential pressure acts uniformly on the cage side and the roller disk area exposed to the crossflow. Defining this area as Ap, finally,

$$F_{jG} = \delta p \Lambda_{p}$$
(43)

which is the force appropriate to Equations (38) and (39).

The total fluid drag moment, M_{rj} acting on the roller in Equation (7) is ther calculated as:

$$M_{rj} = T_{rcyl} + T_{rend} + T_{add}$$
(44)

Note, while the first two terms are always positive in this formulation, the algebraic sigh of T_{add} in determined by the relative velocity distribution, as discussed above.

Cage Fluid Drag Torque

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The fluid drag torque acting on the cage is composed of the fluid torques acting on the inner and outer cage surfaces, the cage sides, and the cage land surface. Its influence in the equilibrium solution for the cage is indicated in Equation (11) by the quantity \mathbb{N}_{c} .

Calculation of the four component drag torques proceeds directly from Equations (23) through (29) for the inner and outer cage surfaces and for lands, and from Equations (30) through (33) for the cage sides. The appropriate radii and clearances for these calculations are the local cage surface radii and clearances between adjacent surfaces. Fluid densities in the various regions are computed from Equation (35) and (36). Dimensional changes with speed and thermal effects resulting from dissipation are insignificant in these calculations, except in the case of close land clearances.

The total drag moment acting on the cage is then computed from

$$M_{c} = T_{cout} - T_{cin} + T_{cside} + T_{cland}$$
(45)

-19-133 Note that since the total drag moment positive sense is in the direction of retarding cage motion, the outer surface and side torque terms are always positive. The inner surface drag torque always acts to increase cage speed and is hence always negative. The sign of the land surface torque is positive for an outer land riding cage and negative for an inner land riding cage.

Influence of Fluid Drag Torques on Solution

Figure 7 compares the predictions of three analytical models with samples of previously published test data of rolle. bearing cage slip as a function of applied radial load. The present model demonstrates almost exact correlation with this data across the load range for which data is available. Close correlation is shown by the Poplawski^[4]model, which uses a simplified fluid drag correlation. The Harris^[2] model matches closely the trend of the test data, but differs significantly in the magnitude of slip predicted across the load range. In addition to the correlation shown for an outer land riding cage, the present model has also accurately predicted the experimentally measured ^{*} cage slip of an inner land riding cage bearing.

Power dissipations predicted by the model closely match available ** rig data. Shaft horsepower dissipation is computed by summing all torques acting on the inner race. The prediction and distribution of these dissipative losses is essential for accurate determination of thermal gradients and operating temperatures. Predictions for two conventional roller bearings analyzed for comparison are summarized below. Uperation was approximately 2.0 x 10^6 DN.

Bearing	Experimental Power Dissipation, Hp	Computer Power Dissipation, Hp
130 MM Bore	5.80	6.94
115 MM Bore	4.25	3.89

Data courtesy of Boeing Co., Vertol Division, Philadelphia, Pa. **
Data courtesy of Midwest Aero Industries, Div. Pure Carbon Co., St. Maxys, Pa. -20-

Both bearings were operated at near synchronous condition. This calculation is extremely sensitive to the amount of lubricant within the bearing, estimated at between 10 to 15% by volume by the test agency. The 100 MM bearing was analyzed for 15% oil-to-air ratio within the bearing, and the 115 MM bearing was analyzed for a 10% oil-to-air ratio. It will be noted that the results bracket the experimental data, being high for the higher oil/air ratio and low for the lower oil/air ratio. A repeat of this analysis taking both bearings at about a 13% oil/air ratio would yield results matching the experimental data.

The foregoing illustrates generally the sensitivity of the solution to fluid drag influences. As further illustration, consider Figure 8 which compares two cage error curves as functions of cage speed for all other conditions the same. For this relatively low speed application, a difference of 10% in oil/air ratio produced a 2% difference in cage slip.

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The shape of the cage error curve, of Figure 8, provides a possible further insight into the bi-stable operation of bearings noted by some investigators. Dr. Ehrich ^[15] noted this phenomenon, and hypothesized its origin as systematic changes in bearing clearances coupled with dynamic phenomenon of shaft rotation. The cage error vs speed curve always has the same characteristic shape, for which three solutions are possible when slip occurs. One root is always close to synchronous, where the steep slope of the error-speed curve requires successive predictions at small slip valves to obtain a solutions. Other solutions are possible if the error curve changes sign at less than synchronous speed (two possible additional solutions), or if the error curve is tangent to the abscissa of one point. Since the magnitudes of the errors are strong functions of speed and load, and to a lesser extent of oil/sir ratio, it is possible that for some combination of these variables the bearing operation may oscillate between two closely spaced roots. This might occur as thermally induced dimensional changes in internal diametral and close land clearances change the operating

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conditions of the bearing. Juch operation has been demonstrated using the present model with thermal and dynamic effects considered. One computer run found about 3% slip on the first iteration (without thermal gradients), but sought the synchronous solution when the results of thermal gradients resulting from the first iteration were reflected in the second. While not conclusive at this time, this subject bears extensive further investigation, with comparison to actual test data as it becomes available.



DIMENSIONAL MODEL

The model accounts for changes which occur during bearing operation as a result of dynamic (centrifugal effects) and thermal deformations. The effects considered to be most significant are:

- Changes in bearing internal diametral clearance (IDC) with dynamic and thermal deformations and with shrink fit between the inner race and the shaft.
- Changes in bearing internal diametral clearance (IDC) due to changes in roller (especially hollow rollers) diameter with dynamic and thermal growth.
- Changes in close clearance guiding cage/race lands with thermal and dynamic deformations, and for an inner land riding cage, changes in the clearance with shrink fit between shaft and inner race.

The use of simple closed form expressions to predict the dynamic and thermal dimensional changes occurring in bearing members is desirable, since this greatly simplifies the system analysis. Predictions of such deformations, on the other hand, must be more than order of magnitude accurate to realistically describe the influence of such operation dependent variables on bearing performance. In the process of model selection, estimates of deformations from available closed form solutions were compared to the results ... more sophisticated analyses, using finite element computer solutions of typical bearing element geometries.

Dynamic Deformations

The dynamic deformation models selected for the races, rollers, and cage are given in Table 1 and are obtained from standard theory of elasticity sources. [16 and 17] Comparison of finite element solutions for a 0.50 "diameter hollow roller with a 0.25" diameter hole showed closest agreement with the generalized plane strain solution. At roller speeds of 150,000 RPM and higher, a $\pm 4\%$ bulging and contraction of the outer surface near the roller edges was calculated in the finite element solution. This cannot be predicted by any of the closed form solutions, however, since it is common practice to crown rollers, this variation is

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not considered significant. For a solid roller, little comparative difference was noted for any of the closed form deformation relations, and hence a plane stress relation was used for simplicity.

Both the inner and outer surface deformations of the inner race, are significant. The deformation of the inner surface contributes to change in the shrink fit between the race and the snaft, and deformation of the outer surface influences both the bearing IDC and the land clearance of an inner land riding cage. The closed form dynamic deformation relation best describing the behavior of both race surfaces was found to be the plane strain relation. These relations generally predict deformation within 5% of the finite element results even at extreme speed, providing race undercuts or other irregularities such as guiding shoulders are small.

The shaft outer surface deformation is also significant in that it contributes to change in shrink fit. While not checked against a finite element model, the shaft conforms to the basic assumptions of the plane strain relation.

The deformations of the cage land surfaces are significant in the determination of clearances required in the calculation of cage land fluid viscous drag. Agreement of closed form predictions with the results of finite element modeling were within 15 to 20% for this deformation for all closed form solutions. However, the calculation of the fluid viscous drag has been determined to be insensitive to this variation, changing only about 2% at maximum speed. This larger deviation is the result of the inability of the closed form solutions to account for the difference in cage surface and land diameters or to account for bending deformations resulting from the additional mass of the land protrusions. Over the relatively narrow land width, the land surface deformation is fortunately quite uniform, as predicted by finite element analysis. The closed form solution best matching the finite element results, within the limitations discussed, was the plane stress formation.

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Shrink fit (Δ) between the inner race and shaft acts to decrease the bearing internal diametral clearance (IDC), as compared to

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the IDC of an unmounted assembled bearing. Also, for an inner land riding cage bearing, the shrink fit decreases the close land clearance. An extensive treatment of this subject is contained in references [18].

Thermal Deformations

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The model used for calculations [16] of thermal deformations assumes an axisymmetric temperature distribution, uniform end deformations and cylindrical geometry. The radial deformation of the ith bearing surface, having inner radius, r_{t} , and outer radius, r_{o} , is given by:

$$\delta T_{i} = \frac{2\alpha r_{i}}{\left[r_{o}^{2} - r_{I}^{2}\right]} \int_{r_{I}}^{r_{o}} T_{r} dr = \frac{2\alpha r_{i}}{\left[r_{o}^{2} - r_{I}^{2}\right]} \left\{ (T_{out} - T_{ref}) \left[\frac{r_{o}^{2}}{2} - \left(\frac{r_{o}^{2} - r_{I}^{2}}{4\ln\left(\frac{r_{o}}{r_{I}}\right)}\right] + (T_{in} - T_{ref}) \left[\frac{(r_{o}^{2} - r_{I}^{2})}{4\ln\left(\frac{r_{o}}{r_{I}}\right)} - \frac{r_{I}^{2}}{2}\right] \right\}$$
(46)

The above relations are known to be quite accurate within the governing assumptions. No attempt has been made to date to confirm in detail their accuracy for this application. Comparison of thermal growth predictions to the limited empirical data available to the authors shows reasonable agreement of the magnitude of these deformations.

When applying the above to prediction of the thermal growth of the outer race, it must be noted that no radial constraint is included in the formulation. This is typical of the test environment of roller bearings where loading is accomplished through an external yoke, but growth of the outer race is otherwise unconstrained. Other application

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of this type of analysis must consider any radial constraint appropriate to the application, particularly because of the possibility of bearing thermal lock-up.

From the above, it follows that when the surface temperatures of all bearing elements are known, the thermal deformations of the bearing members are completely defined. Company of the

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THERMAL ANALYSIS

Problem Formulation

The temperature field within the bearing must be known in order to compute thermal deformations. With the basic assumption of axisymmetric temperature distribution, the techniques of performing such an analysis are well known. Harris ^[19] has applied heat transfer techniques to the determination of bearing temperature distributions. The technique presented here will basical y follow this presentation, with additional emphasis on the calculation and distribution of power dissipation within the bearing and on calculation of convective conductances or heat transfer coefficients appropriate to the calculation.

All three modes of heat transfer, conduction, convection, and radiation can operate between bearing members and between the bearing and its environment. Conduction is a linear phenomenon. Convection is basically non-linear in that the convective conductance is strongly velocity and temperature dependent. However, in the iterative solution technique used, Fig. 4, velocity is fixed at each step of the iteration. Temperature dependence is mainly reflected in fluid property changes. Since the iterative scheme employs the updated temperatures from the previous temperature iteration solution in the convective conductance calculations for the current temperature solution, the convective mode formulation is linear at each temperature iteration. Radiation heat transfer depends on differences of forth powers of surface temperatures, and is hence always non-linear. The forms of the conductive, convective,

> -26-140

and radiation heat transfer equations respectively are:

$$H_{cond}_{ij} = \begin{cases} \frac{2\pi k_{1}}{\ln \left(\frac{r}{r_{1}}\right)} & \Delta T_{ij}; \text{ hollow cylindrical body of length} \\ \ln \left(\frac{r}{r_{1}}\right) & l_{g}, \text{ in radial direction} \end{cases}$$

$$(47)$$

$$kA_{T} \frac{\Delta T_{ij}}{\Delta L}; \text{ axial direction, through area } A_{T} \text{ over distance } \Delta L$$

$$H_{conv_{ij}} = h_k A_{s_k} \Delta T_{ij}$$
(48)

$$H_{rad_{ij}} = \frac{\sigma \left[(T_{1} + 460)^{4} - (T_{1} + 460)^{4} \right]}{\frac{(1 - \xi_{n})}{\xi_{m} s_{m}} + \frac{1}{\overline{F}_{m,n} s_{m}} + \frac{(1 - \xi_{n})}{\frac{\xi_{n} A_{s_{m}}}{\xi_{n} s_{n}}}$$
(49)

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= Boltzmann radiation constant $\boldsymbol{\xi}_m$ and $\boldsymbol{\xi}_n$ are the emissivities associated with the m^{th} and nth surfaces, respectively. = view factor of nth surface seen from mth surface **F**_{m, n}

These equations are basic, and are derived in any standard heat transfer text, such as reference [20].

The radiation mode of heat transfer becomes significant only for temperature differ γ_{-s} of the order of 100°F and higher. For normal bearing operation, such conditions do not exist within the bearing. However, heat transfer by this mode can be significant between the bearing and its environment, and must be included.

Formulation of the heat transfer problem requires discretizing the bearing elements into a set of nodes, and writing a Kirchkoff energy balance at each node. The power dissipation occurring within the bearing

acts as the driving potential, and must be computed and distributed among the nodes. Fig. 9 defines the nodal pattern used in this analysis. In this model, provisions are made for coolant flow through the outer race and through the shaft, and for lubricant to be flowing both through the bearing and under the inner race. Any of these flows except the flow through the bearing may be set to zero. The coolant through the outer race, and the lubricant flows under the race and through the bearing are assumed to mix external to the bearing, and to wash the inner surface of the chamber, the shaft, and the exterior of the bearing. The environment external to the bearing assumes the assembly to be enclosed in a test chamber, and to be loaded through an external yoke extending through the chamber. The governing equations are then of the form, for nodes i = 1 to 21,

$$\sum_{j=1}^{21} H_{ij} + \sum_{k=1}^{N_i} Q_k = \varepsilon_i$$
(50)

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Here H_{ij} is the energy transfer between nodes i and j, and the Q_k are the dissipations, external energy inputs, energy transfer to coolant or lubricant flows, or losses from a typical node i. N_i is the total number of Q_k at node i. Table 2 illustrates the flow of energy between all nodes, and defines the Q_k quantities at each node. The explicit forms of the equations defined generally by (50) are derivable directly from Table 2. Note that all energy fluxes other than losses are assumed to enter each node. The temperature differences of equations (47), (48) and (49) may thus be uniformly taken at $(T_i - T_i)$ at each node i.

The energy balances of equations (50) are equated to the error functions ε_i , where ε_i approaches zero for the steady state equilibrium set of temperatures. At each temperature iteration, Fig. 4, in the bearing solution, whis non-linear set of equations is solved by Newton-Raphson iteration techniques. As an initial guess of the temperature field to start the iterative process, setting all temperatures equal to the previous

> -28-142

value of bearing oil temperature, T_{11} , has been found to produce rapid convergence. To implement the Newton-Raphson solution scheme, the set of equations (50), with the H_{ij} quantities expressed in terms of equations (47), (48), and (49) must be rewritten in the form

$$\sum_{j=1}^{21} \left(\mathbf{A}_{ij} \mathbf{T}_{j} + \mathbf{A}_{ij}^{*} \mathbf{T}_{j}^{4} \right) + \sum_{k=1}^{N_{i}^{*}} \mathbf{Q}_{k} + \sum_{k=1}^{(N_{i} - N_{i}^{*})} \mathbf{B}_{k} = \varepsilon_{i}$$
(51)

Here the A_{ij} are thermal admittances for terms originating from convection and conduction, and A^*_{ij} are thermal admittances for terms originating from radiation. N_i^* is the total number of quantities, Q_k at node i not explicitly containing temperature, and B_k are constants originating from such sources as products of lubricant mass flow rates, specific heats, and inlet temperatures. The non-linear set of equations (51) for i = 1to 21 is then directly solvable for the temperature field using the Newton-Raphson solution technique.

Power Dissipation

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As previously stated, the driving potentials which result in thermal deformations are the power dissipations occurring within the bearing. These arise from fluid boundary layer and coulomb friction phenomenon. The distribution of the component dissipations is shown in Table 2. The total power expended within the bearing must appear at the shaft surface, since this is the driven member, and is easily calculated as the sum of all roller to inner race tractions and the sum of the fluid drags acting on the inner race and shaft surfaces (including land torques for an inner land riding cage). Shaft power loss is an important design factor and one that until new could only be estimated emperically based upon test experience.

Power dissipations at specific nodes, shown in Table 2, are also easily calculated. Roller to race contact dissipation is the product of the EHD traction and the sliding velocity in the contact. Fluid drag

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moments are a ribed by the fluid mechanics model.

Ext al energy input such as energy dissipations by slave bearings supporting the shaft in test apparatus, other supporting bearings in an engine, energy input from turbine gasses, etc., must be calculated separately and introduced as heat sources or sinks at the appropriate nodes of Table 2.

(53)

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Heat Transfer Coefficients

Correct values of the heat transfer coefficients, or more properly the convective conductances, used in the thermal analysis are essential to obtaining a representative solution. While standard techniques of determining these quantities can be used for non-rotating surfaces, the shaft, cage, and roller surfaces pose a special problem. Bjorklund^[21] has investigated the problem for the case of concentriz rotating cylinders. The techniques and correlations of this source will be used here.

For two concentric rotating cylinders, with the annular space between them containing a viscous fluid, the critical Taylor number for both is given by

$$N_{\text{Ta}_{cr}_{\eta}} = \left[\frac{48.7 \left(2 + \frac{C}{r_{5}}\right)}{\left(1 - \eta\right) \left[1 - \eta\left(1 + \frac{C}{r_{5}}\right)\right] \left[0.6571 \left(\frac{1 + \eta}{1 - \eta} - 0.625 \frac{C}{r_{5}}\right) + \frac{.00056}{\frac{1 + \eta}{1 - \eta} - 0.625 \frac{C}{r_{5}}\right]} \right] (52)$$

where

$$n = \frac{\omega_c}{\Omega}$$
 Speed ratio

C = radial clearance between inner race and inner cage surfaces or between inner race surface and cage land surface for an inner land riding cage.

-30-144

The Taylor number for this condition is given by

$$N_{Ta} = \sqrt{\frac{c}{R}} (R\omega c/\beta)$$
 (54)

where

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 $\beta = \text{kinematic viscosity of fluid}$ R = radius of inner rotating member $\omega = \begin{cases} \Omega \text{ for inner race to cage condition,} \\ \omega_{c} \text{ for outer race to cage condition} \end{cases}$

The Nusselt number for pure conductance through the fluid is given by

$$N_{Nu_{cond}} = \left(\frac{C}{R}\right) / \ln \left(1 + \frac{C}{R}\right)$$
(55)

and the ratio of the local Nusselt number to the conduction Nusselt number is given by

$$\frac{N_{N_{t}}}{N_{N_{u}}_{cond}} = 1.1 \left[\frac{N_{Ta} - (N_{Ta} - N_{Ta}_{cr_{n}} - N_{Ta}_{cr_{n=0}}) (1 - 3.5 \frac{C}{r_{5}})}{41.1 + (N_{Ta}_{cr_{n}} - N_{Ta}_{cr_{n=0}}) (3.5 \frac{C}{r_{5}})} \right]^{1/2}$$
(56)

Finally, the convective conductance is given by

$$h = \frac{k_f}{C} N_{Nu}$$
 (57)

where k_f = thermal conductivity of the fluid. For the inner cylinder rotating only,

 $\frac{N_{Nu}}{N_{Nu}_{cond}} = 0.175 N_{Ta}$ (58)

applies as an alternate to equation (53).

-31-145 Here the appropriate C is the radial clearance between the outer race and cage outer surface or cage lands for an outer land riding cage. Equations (52) through (58) can be used directly to obtain the appropriate coefficients for the race and cage cylindrical surfaces. Over the vertical cage surfaces, an average of the coefficients of the bounding cylindrical surfaces is recommended. These relations also define the coefficient values on the roller surfaces, using equation (58) and the average roller clearance defined by equation (37). In all of the above calculations, the tluid density used for the calculation of the kinematic viscosity should be computed as discussed in equations (34-36). The variation of fluid properties with temperature must also be considered, updating the fluid properties at each step of the iterative solution.

Coefficients for the outer bearing surfaces and the chamber inner and outer surfaces are computed from a correlation suggested by Jakob^[2?] for natural convection of fluids in contact with horizontal cylinders

$$h = 0.525 \frac{k_f}{D_r} \left(\frac{D_r^3 \gamma g \Delta t}{\beta^2} \cdot \frac{\beta}{\alpha_d} \right)^{0.25}$$
(59)

where

 D_{\perp} = diameter of cylinder

 γ = coefficient of volumetric expansion

g = gravitational acceleration

- α_d = thermal diffusivity
- At = absolute value of temperature difference between
 surface and bulk fluid temperature

For condition inside the chamber, the fluid properties appropriate to the calculation are those of the lubricant, since the bearing outer surface, the shaft, and the inner chamber wall are assumed to be washed with the mixed oil. The temperature difference should be taken between

> -32-146[.]

the surface temperature in question and the mixed lubricant temperature, which is computed from

$$r_{ave} = \frac{\ddot{m}_{6} c_{p_{6}} T_{6} + \dot{m}_{11} c_{p_{11}} T_{11} + \dot{m}_{16} c_{p_{16}} T_{16}}{(\dot{m}_{6} c_{p_{6}} + \dot{m}_{11} c_{p_{11}} + \dot{m}_{16} c_{p_{16}})}$$
(60)

where

 $\hat{\mathbf{m}}_{i}$ is the mass flow rate of the ith lubricant

 c_{p_1} is the specific heat of the ith lubricant at Temperature T_i For the outer chamber surface, the appropriate fluid properties are those of air, and the temperature difference is taken between the chamber wall and the external ambient. For external circulation of air over the chamber, forced convection relations must be used, for which standard formulations can be obtained from Kays^[23].

The shaft surface coefficients can be obtained from equations (52) through (58), using equation (58) rather than equation (56), if care is taken to use mass averaged fluid properties. The resulting prediction will be higher than the actual coefficient value. The clearance required here is the difference between shaft and chamber radii. This result should be checked against the prediction of equation (59), which provides a lower bound on the coefficient value, and engineering judgement used to choose the proper value of the coefficient.

The heat transfer coefficient for the external surface of the loading yoke depends on the geometry of the member. Generally, this can be treated as a fin heated at the root, and standard correlations applied, such as those of reference [20].

Sample Thermal Analysis Results

The results of the thermal analysis of a conventional inner land riding roller bearing operating at 2 x 10^6 DN are summarized in Table 3. The guiding shoulders for the rollers were on the outer race. Two cases

> -33-147

are compared, for conditions with and without under race cooling. This analysis was accomplished using specified operating values of IDC and land clearances, and hence the results are quite comparable for cage slips and power dissipations. The original conditions necessary to achieve the specified operating conditions were computed from the results of the thermal analysis and considering dynamic influences, and are summarized in Table 3 along with results pertinent to the thermal analysis.

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The results shown in Table 3 are consistent, showing generally lower temperatures for the case with additional cooling, and a higher oil temperature rise for the reduced cooling case. Also, with under race cooling the temperature difference from the inner to the outer race is 13.7°F, as compared to a temperature difference of 34.7°F for the case of no under race cooling. These results are in general agreement with measured values for comparable bearing operating conditions.

DISCUSSION OF APPLICATION OF EXPERIMENTAL TRACTION DATA AND ROLLER KINEMATICS

Typical traction values for several roller bearings from 65mm bore to 140mm bore and for shaft speeds from 1.0 \times 10⁶ DN through 4.0 \times 10⁶ DN with MIL-L-7808 oil are presented in Table 4, for unloaded and the maximum loaded roller contacts. All tabulated values were computed with the full EHD, fluid mechanics, dimensional, and thermal models described in this paper.

A roller always rotates near a pure rolling condition (low sliding velocity) at the outer race contact of a roller bearing with inner race or shaft rotation. Sliding velocities from near zero to 3 in/sec are typical as shown in Tables 4a and 4b for outer-race contact.

An unloaded roller, Table 4a, rotates about its own axis at an angular speed slightly less than the angular speed required for pure rolling at the outer race contact. Positive sliding (outer race relative surface velocity is greater than the roller surface velocity) always occurs and is in the range of near zero to 3 in/sec. The rolling portion.

> -34-148

of the total traction value is significant and cannot be ignored. Indeed the rolling portion can even predominate as shown by the ratio of rolling traction to total traction in Table 4a.

A loaded roller which produces a cage driving force rotates about its own axis at an angular speed slightly greater than the angular speed required for pure rolling at the outer race contact. Negative sliding occurs and is in the range of near zero to -3 in/sec as shown in Table 4b. The maximum loaded roller and most of the loaded rollers in the bearing have negative sliding at the outer race. Occasionally a lightly loaded roller or rollers near the entry and exit from the radial load zone will have positive sliding at the outer race contact. Such rollers result in a net drag on the cage similar to completely unloaded rollers. In all cases the rolling portion of the total traction is significant and cannot be ignored.

A loaded roller always has positive sliding at the inner race contact. Typical values are shown in Table 4c. A bearing operating at essentially epicyclic cage speed (no cage slip) has very low values of sliding velocity (< 3 in/sec) at the inner race contact and the rolling portion of the total traction is significant. A bearing operating with measureable cage slip can develop high values of positive sliding velocity at the inner race contact as shown in Table 4c. In these cases the sliding portion of the traction reaches a ceiling value and again the rolling portion of the total tractior value is significant and cannot be ignored.

A high speed roller bearing with elastohydrodynamic oil films cannot operate under a pure rolling condition. An examination of the traction formulation of Eq. (3) shows that for zero sliding vehocities the traction at both inner and outer races would be negative and no equilibrium solution can occur as shown in Fig. 2. Some cage slip (however small) must occur.

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RECOMMENDATIONS

1. Experimental data defining the rolling portion of the total traction force in an EHD contact is needed. The accuracy and usefulness of a complete systems analysis of a high speed roller bearing is very dependent upon good rolling friction data.

Archard and Crook^[1] have stated that for loads which develop essentially resallel surfaces in the Hertzian contact and at speeds of sliding above a few centimeters per second, the sliding component of traction predominates and the rolling component can be ignored. This assumption has been generally accepted and has led to an emphasis upon obtaining twin disk traction data only for sliding conditions by current researchers.

Typical twin disk machines (with equal size disks) measure only the sliding contribution to the total traction in an EHD contact. Because of disk symmetry the data is also symmetric about zero sliding speeds, i.e., the traction value vanishes at zero sliding and reversal of the relative sliding direction reverses the direction of the traction. The rolling portion of the total traction is very small compared to maximum traction values. The instrumentation of existing traction machines is not designed to measure small magnitudes of rolling traction, indeed the contribution of rolling traction is calibrated-out along with disk support bearing friction. Symmetry of test machine geometry leads to symmetry of results. Special attention to non-symmetrical bench rig design and instrumentation is required.

 Cage dynamics need to be explored and better defined both experimentally and analytically. Bi-stable ^[15] operation is shown to be possible by the present analysis.

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The authors express their thanks to The Franklin Institute Research Laboratories for sponsoring development of the computer program and preparation of this paper.

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Figure 1. Surface Velocities and Relative Rotational Speeds of Raceways and Rollers Including Slip at Each Contact as a Result of Cage Slip

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Figure 6. Mathematical Model of Horizontal and Vertical Relative Velocity Distributions in Roller-Shoulder Contact

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Figure 8. Influence of Oil/Air hatio on Each Solution

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Table 1 DIMENSIONAL MOLELS DIAMETER GROWTH DUE TO CENTDIELS

Locasion	Mode]	Formula
Hollow Roller Outer Surface	Generalized Plain Strain	$\int_{3}^{3} \operatorname{rot} = \frac{p_{rw}}{2} \frac{r_{o}(1+\sigma_{r})(3-2\sigma_{r})}{2} \left[(1-\sigma_{r})(1-\sigma_{r}) r_{i}^{2} + \frac{(1-2\sigma_{r})}{(3-2\sigma_{r})} r_{o}^{2} \right] + \frac{p_{rw}}{\varepsilon} \frac{2\sigma_{o}^{2}}{(r_{i}^{2}+r_{o}^{2})}$
Solid Roller Outer Surface	Plane Stress	$\delta_{rot} = \frac{\rho_r \sigma_{wr}^3 r^2}{2E_r} (1 - \sigma_r)$
Inner Race 6 Hollow Shaft Outer Surface	P:ane Strain	$\delta_{1R_{0}} = \frac{\rho_{3R}a^{2}r_{0}(1+\sigma_{1R})(3-2\sigma_{1R})}{2E_{r}(1-\sigma_{1R})} \left[(1-\sigma_{1R})r_{1}^{2} + \frac{(1-2\sigma_{1R})}{(3-2\sigma_{1R})}r_{0}^{2} \right]$
lnner Race Inner Surface	Plane Strain	$\delta_{IR_{i}} = \frac{\rho_{IR} \alpha^{2} r_{i} (1+\sigma_{IR}) (3-2\sigma_{IR})}{2E_{r} (1-\phi_{IR})} \left[\frac{(1-2\sigma_{IR})}{(3-2\sigma_{IR})} r_{i}^{2} + (1-\sigma_{IR}) r_{o}^{2} \right]$
Inner Land Riding Cage - Land Diameter	Plane Stress	$\delta_{c_{L}} = \frac{\rho_{c}\omega_{c}^{2}r_{L}(3+\sigma_{c})(1-\sigma_{c})}{2E_{c}} \left[\frac{r_{L}^{2}}{(3+\sigma_{c})} + \frac{\sigma_{o}^{2}}{(1-\sigma_{c})} \right]^{2}$
Outer Land Riding Cage - Land Diameter	Plane Stress	$\delta_{L} = \frac{\rho_{C}\omega_{C}^{2}r_{L}(3+\sigma_{C})(1-\sigma_{C})}{2E_{C}} \left[\frac{r_{1}^{2}}{(1-\sigma_{C})} + \frac{r_{L}^{2}}{(3+\sigma_{C})} \right]$
 p. mass density (lb-sei n, shaft angular veloci w_c, cage angular velocit o, Poisson's ratio 	c ² /in. ⁴) ity (rad/sec) ty (rad/sec)	E. Youngs Acdulus, (1b/in. ²) r _j , innermost radius (in.) r _o , outermost radius (in.) r _L , cage land radius (in.)

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		Heat Transfer Pr	194	1	
Neda	Location and Description	lifth Nodes	Type	Ulasipative and Externel Energy Assignments	Nonerts
:	Inner Skaft Coolant	2,21	cv	$\mathbf{Q}_{1} = \mathbf{A}_{1}\mathbf{C}_{\mathbf{A}1}\left(\mathbf{T}_{1\mathbf{N}_{1}} - \mathbf{T}_{1}\right)$	Coolant flow through holiow shaft,
1	Inner Shaft Surface	1 3,4(a),21(b)	ev		a) for $\lambda < 0$ inserterance fit
,	Outer Sheft Surface	$\frac{1}{4}$ (a) , (b)	CV CV		c) for $a \ge 0$ loose fix on shaft
٨	Suter Edges of Undurside of Innar Ress (in Contest with Shaft))(e),6(d) 2(a),3(a),3,21(a)	C CV		d) we everege of $T_{ij} \in T_{jj}$
5	Hiddia Section of Underside of Inner Ress	6(a) (d) ,6 4,7,13	ev		a) sides of undercut
6	Under Rese Content	3.465(d,0),5,18,19, 21	l av	$Q_{d} = A_{d}C_{ad}(T_{14}, -T_{d})$	Oll flow cooling under inner rese.
7	Outer Liges of Tep Side of Inner Rese	11 5,13 a(f)	ev ev	1/6 Cals-Cage-Inner Surface	f) for inner land riding aspe
•	Lands of Cage	11,11(h),11(1) 9 7(f),14(a)	CV C R	1/3 9 ₂₁₅ -Lones (/ er s)	 g) f⁻, outer land riding case n) as average of Tg & Tg Inder a) surface 1) use average of Tg & Tj & outer a) surface
9	Inner Surface at Cage	11,11(h) 4,10 42,12	CY.	1/3 Gais-Case-Innar Surface 1/2 G _{COUL} (V _C 1/2 G _{COUL} (V _C +1 _R)	j) dissipation due to Coulomb fristion bismoon roller and cope peckdt. V _C = Cope Volume V _a = Relier Volume (Tatal)
10	Octor Surface of Lago	11(1),11 9 12,15	CV C K	1/2 QCOUL (VC) 1/2 QCOUL (VC) 1/2 Qg1g=Cage-Duter Surface	
11	dii Wishin Bearing	7,8,9,10,12,13,14 869(h),8610(1) 18,19,21	CY CY	$\begin{array}{l} q_{11} = \hat{a}_{11} C_{p11} (T_{11_{i_1}} - T_{11}) \\ \text{I/3} \ q_{015} \text{-Coge-Immar Surface} \\ \text{I/3} \ q_{015} \text{-Coge-Outer Surface} \\ \text{I/3} \ q_{015} \text{-Londe} \\ \text{I/3} \ q_{015} \text{-Londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} \text{-londe} \\ \text{I/3} \ q_{015} (h) \end{array}$	011 fime through bearing b) Q ₁₁₂ is internet fluid emergy distipation not attributeble to perdistlar surfaces and ~ Gnet Paux - Sum of Surface Dissipctions. Galtag ~ D'm Traction # Sliding Velocity
12	Rollers	11 3,10,13,14	CV A	$\begin{array}{c} 1/2 \ Bein^{-Rellers} \\ G_{CSUL} \left(\frac{V_R}{U_C^{-V_R}} \right) (J) \\ 1/4 \ G_{SLigg} - Inner \ Race \\ 1/4 \ G_{SLigg} - Dutor \ Race \end{array}$	
13	Alddia Seation of Top Side of Innor Rase (Soller Path)	11 5,7 9,12	CV C R	1/4 Gelige-Inner Race 3/6 Beig-Cope-Inner Surface	
14	Inner Surface of Outer Reas (Relier Peth)	11 15 a(e),10,12	CV C R	1/4 Q <u>SLIBE</u> -Outor Roc- 1/3 Qols-Londe(0)	
18	Inner (Canlar) Surface of Outer	16 18,17	ęv		
16	Outor New Caping Fluid	15,17,18,19,21	64	Q16 = A16 ^C 016 ^{(T} 1216 ^{-T} 16)	011 flew throw in outar reveas
"	Outor (Caulad) Surfame of Outor Rado	16 15,18	ĘV		
•	Auser Austaan of Auser Sace	6,11,16,21 17,19,20	ev e		
"	Chamber Wets	•,11,16 18 18	CY CA	GETTING(1) GEDES-CVSR-Ambient Alr	1) esterns: energy input from other bearings, seeis, etc.
* [Lond Yoke Rent		.	Gues-CY-Aubient Air.	
"	Outer Sheft Surface Aunute from Bearing	1,6,11,16(m),18 [45 ⁽⁶⁾ ,4(2)	CV C	4(XT2) ⁽¹⁾	n) assumes all amoting all firms win at node 21 on way to admini some.

Table 2 DESCRIPTION OF THERMAL ANALYSIS BY NODES -----

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CV - Convection

C - Conduction B - Rediction

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Table 3 TYPICAL THERMAL ANSLYSIS

Bearing & Lubricant Data

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Pitch diameter = 6.512 in. Roller diameter = 0.5 in. Operating IDC = .002 in. Operating radial land clearance = 0.015 in. Lubricant = MIL-L=7808D Lubricant flow rates = 6 lb/min through hearing (both runs) 6 lb/min under race (2nd run only) Aubricant inlet temperature = 250°F Radial load = 333 lb Shaft speed = 14,280 rpm Oil/air ratio in bearing = 15%

Temperature Distribution (Ref. Fig. 9)

		lempera	Lure, r
Node	Location	No Under-Race Cooling	Under Race Cooling
1	Inner shaft coolant		
2	Inner shaft surface	361.5	295.8
3	Outer shaft surface at bearing	217.7	293.6
4	Inner race at shaft	`. 8	310.7
5	Under-cut surface of inner race	362.5	314.6
6	Under race coolant	~	265.9
7	Inner race beyond roller contact	361.7	317.1
8	Cage at the land	380.8	370.3
9	Cape inner Burface	393.1	383.1
10	Caga outer surface	392.9	383.0
11	Internal lubricant to bearing	330.7	318.3
12	Rollers	351.3	339.2
13	Inner race at rollers	357.5	324.8
14	Inner surface of outer race	329.9	30 ê , 2
15	Inner cooled surface cuter race	329.9	307.:
16	Outer race lubricant		· •
37	Outer cooled surface outer race	329.8	306.2
18	Bearin* cuter diameter	329.4	362.6
19	Chamber wall (inner side)	309.0	273.7
20	Loading bolt (strut) root	281.8	<i>2</i> 60.1
2]	Shaft (external to bearing)	335.3	293.1

	No Under-Race Cooling	With Under-Race <u>Ccoling</u>
Percent cage alip	32.5	33.7
Fow r dissipation, H	7.09	7.15
Initial shrink fit, in.	0.0082	8300 0
Machined XDC, 1m.	0.0097	0.0089
Nounted IDC, in.	0.0024	0.0011
Michined diametral land clearance, in.	0.0037	C.0035
Mounted dismetor land cleat rise, in.	0.0029	0.0027
Mired lubricant temperature at sump, "F	330.7	292 - 3

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						Bliding Pertim	Bolling Portion -9.70-9.75.4.	Tractim	413 711a	ten Consort			• 848	wike		
111. 20 24	1 Cago Alla	ter ter	Y _{aj} Ja/aat	aj Jan	/(te)_	ej line		T _{ed}		тар Та 27	<u>#11.7mm</u> -	3000	Sali Sim.		Lond Lond	LALIS Solly
1.6	10.0	1363	3.31	172.97	9.0098	3.108	- 0.401	8.507	23.2	230	HIL-L-7800	63		Besar	823	ə. M
1.36	0.02 7	3453	1.875	49.4	0.030	8.697	- 0.363	0.338	19.9	230	ML-1-7898	115	9.300	laser	3075	1.13
3.0	8.866	1332	3.125	34.71	0.936	8.347	- 0.132	8.435	,	230	HEL-1-7888	340	8.250	Inner -	111	2.8
3.8	19.43	3823	2.425	86.6'	0.9006	0.758	- 0.323	8.438		i.e	ML-L-7808	140	0.1.8	laner	333	8.73
4.8	8.0003	3113	1.900	138.87	3.6813	1.332	- 0.212	3.130	٢,	122		210	4.134	10.41	313	8.18
• 2	26	2302	2.375	76.23	9.912	8.547	- 0.172	8.236	\$ 44	230	Hile1-7882	140	0.236	laner	3.86	4.11
4.8	8.996	3119	9.610	139.07	8.8870	8.541	- 4.153	0.8L4	1.5	566	3948	310	0.220	later	333	0.19

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OUTER RACE CONTACT OF MAXIMUM LOADED ROLLER

						tliding Pertijn	Selling Pertim									
541. 30 - 4	S Coga Silan	telast.	e) Jalans,	**: ###	1(7 ₀)	1 est erras Pas	-9.20 ^{0.7} 8.2 ⁸ 1 8 ^{0.3}	fotal Truction T _{oj}	Hil File Totak Janja ⁶		\$11_D0a_) 20.	842) 641.	Cape Militan Militan	Sedial Loss	Rotis [Bolling] T _{al}
1.8	18.8	1362	~3.19	3?4.0	6.0063	- 5.839	- 8.012	• 3.331	10.7	190	1011-L-2000	41	0.8368	Bule r	885	8.13
1.36	4.427	2433	-4.81	\$52.9	6-10	004	- 8,364	- 8.364	11.8	230	101-1-7800	11	0.300	Inner	3975	3.99
2.8	8.866	1356	-0.46	247.0	9.930	- 3.343	- 0,138	- 8.471	4.7	234	HEL-L-7888	240	0.239	20007	333	0.05
3.G	18.86	1011	-1.725	185.1	8.8952	- 8.781	0.323	- 1.103	13.9	350	MIL-L-7888	140	0.300	10007	233	8.25
4.0	0.096 3	1113	-0.0003	119.1	3.6039	- 2.276	- 0.212	- 2.566	7.7	236	101-1-7838	140	0.236	Inter	111	8.87
4.0	*	2385	-0.6616*4	138.5	3×10 ⁻⁴	001	- 0.171	- #.172	8.9	334	#11-1-7884	140	0.230	Laber	544	0.90
4,8	0.005	3113	-8.6e18 ⁻⁶	217.5	8.0830	- 1.017	- 0.233	- 1.4.3	2.1	308	394£	3.90	8.157	Jagor	333	9.12

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INNER RACE CONTACT OF MAXIMUM LOADED ROLLER

						titelja Portim	Pauling Pertim									
200. 20 20	t Cape	T _{L]}	*.:	*s;	f(fe) ₁₃	(*11) *13 	-9.28 1 415 415 415 415 415 415 415 415 415 4	total Troction T _{ij} Sha.).	eit File Ditth All		811.7mm	iers Mar	8+35 8138-	Cage Badding Jacob	kaftal Lood - Mili	Setio Seli _{/1} 1
1.0	18.8	1943	454.5	387.7	8 4398	7,866	- 9,687	7.179		139	101-1-"108	*5	1.6268	Bull(3	815	¥.14
1.3	8.87	344.3	7.738	443.7	0.0013	1.030	- 0.345	3.493	11.3	238	ML-1-7888	313	0.555	Same v	3875	v 34
1.4	8.64	1411	43	213.2	0.815	3.848	- 8,343	3.673	11,0	299	NTL-1+7004	146	8.35	Zama v	333	0 C4
1.4	39.86	3043	3		0.4313	2.136	- 0.396	1,72	23.6	258	#16-1- 18 7	390	8.98	Later	u)	9.20
4.8	8.0004	6236	8.884	\$70.0	9.0047	3,889	- 2,368	4.712	\$.3	254	#11-1-76.1	- 144	9,30	Loost 7	.11	v 64
4.4	*	44.10	2328	34.4	4.510	1.443	- 0,416	3,100	4.8	250	1825,-5×788.8	148	\$.58	Lane t	tar	6 33
4.8	9.0006	4365	9.95	140.9	8.659	2.733	- 8 184	3.3 m	23	344-	Polyphon1/ Eshar 1948	148	8.36	lant	313	3 2,
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Ь	×	semi-width of Hertzian contact - in.
c _r	*	hollow roller ring deflection constant - in/lb.
CF [*]	=	centrifugal force acting on roller - 1b.
d	=	roller diameter - in.
E	=	pitch diameter of bearing - in.
^Е ум	=	Modulus of elasticity - 1b./in ²
E'	=	reduced Modulus = $E_{ym}/(1-\sigma^2)$
f(Te)	*	coefficient of traction at temperature T
Fddd	E.	contact force on roller from guiding race shoulder (15.)
Fc	-	cage to roller force - 1b.
F _x	*	radial external load - 1b.
G	=	material parameter = $\alpha E'$
G1,G2,G3	=	parameters to determine f(Te)
$G_1 = \frac{n_e V}{\frac{P_h h}{hz^h}}$		(Shear Rate Effects) .
$G_2 = \frac{\beta_1 \eta_e}{8K_f}$	v ²	(Thermal heating effects)
$G_3 = \alpha P_{hz}$		(Pressure viscosity effect)

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n		Iubricant average film thickness - in.
^I r	*	roller polar moment of inertia lb-in-sec ²
I c	*	cage polar moment of inertia lb-in-sec ²
I	-	bending moment of inertia for hollow roller - in ⁴
К	=	roller to race deflection constant
^K f	×	thermal conductivity of lubricant, BTU/o _F -hrft.
£	8	effective length of roller contact - in.
^m r	*	roller mass - 1b-sec ² /in.
M _c	Ξ	cage fluid drag moment - lb-in.
Mr	=	roller fluid drag moment - lb-in.
Р	2	roller load - 1b
p	=	order of iteration
P _{HZ}	¥	maximum Hertz contact stress - 1b./in ²
Pd	82	diametral clearance - in.
Q	*	hydrodynamic pressure force - 1b.
Q	*	dimensionless form of $Q = Q/(lE^*R)$
Q _m	87	dimensionless heating parameter = $2n_e U^2 / (K_f T_e)$
r	12	mean radius of hollow roller - in.
R	=	radius of an equivalent cylinder and plane - in.
t	-	thickness of hollow roller - in,
T	7	traction in an EHD contact - 1b.
T e	-	temperature of lubricant at entrance to EHD contact - °F
Ũ	-	fluid entrainment velocity - in./sec.
Ũ	-	dimensionless form of $U = \eta_e V/(E'R)$

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v	-	sliding velocity - in./sec.
$\overline{\mathbf{v}}$	*	dimensionless form of V ≖ η _e V/(E'R)
ធ	=	dimensionless load = P/(2E'R)
x	=	radial displacement of inner race - in.
Χ _φ	*	deviation of races from true circular form - in.
Z	-	total number of rollers
α	-	pressure viscosity exponent - in ² /lb.
β	=	temperature viscomity coefficient - °F
Ŷ	-	ratio of roller diameter to bearing pitch diameter
[⁺] j	=	ongular location of roller, deg.
φ _T	#	thermal reduction factor for EHD film thickness
Ω	*	angular velocity of inner race, rad/sec.
ω _c	-	angular velocity of cage, rad/sec
ω _r	8	angular velocity of roller, rad/sec.
η		lubricant absolute viscosity - lbsec/in. ²
μ		coulomb coeff of sliding friction
δ _ο	=	roller - outer race deflection - in.
δ ₁	28	roller - inner race deflection - in.
^δ cf	*	hollow roller deflection from CF [*] - in.
⁶ rot	×	roller diametral expansion from ω_r - in.
⁶ TOTAL	85	total deflection of an unloaded roller - in.
δ _{φj}	æ	relative movement of races at ϕ_j - in.
σ	-	poison's ratio

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 $\frac{1}{2}$ (where $|\mathbf{x}| = \mathbf{x}^{-1}$ are prime by \mathbf{w}_{1}^{-1} is a time \mathbf{x} of spectruling $\mathbf{p}_{2}^{-1} = \mathbf{x}^{-1}$ (where \mathbf{x}^{-1} is the spectruling $\mathbf{x}_{2}^{-1} = \mathbf{x}^{-1}$

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PIN HARDING

i =	inner race contact
0 =	outer race contact
ب ذ	roller number or location
u =	an unloaded roller
e =	entrance region of EHD contact
Fluid Mechani	ics
A	Surface Area in. ²
A _G	Total contact area between roller and guiding shoulders in. ²
A _{Hji}	Area of i th horizontal lamina in. ²
A p	Roller and cage surface area within typical crossflow passage exposed to crossflow in. ²
A _{Vjk}	Area of k th vertical lamina in. ²
A _x	Cross sectional area of a typical crossflow passage in. ²
C	Radial clearance, in.
C'	Clearance of cage pocket and roller, in.
с _N	Laminar or turbulent correlation lactor for disk rotating in a viscous fluid
^F jG	Contact force between roller and race guiding shoulder 1b
f	Friction factor
f _L	Laminar friction factor
L	2°aring length
2p	Peripherel length of a typical crossflow passage in.
H _T	Noment about center line of a disk rotating in a viscous fluid in-lb.

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N	Number of horizontal lanina
N _{Re}	Reynold's number (Defined in Text)
N _{Ta}	Taylor number (Deffred in Text)
r	Reference radius in.
r _{Hji}	Distance from roller center to i th horizontal lamina in.
ri	Inner radius
ro	Outer radius
r _{Vjk}	Distance from radial ray through roller center to k th lamina in.
S	Number of vertical lamina
δp	Crossflow differential pressure lb/in. ²
T	Drag torque in1b
^T add	Moment contribution of contact force to roller drag moment inlb
T cland	Fluid drag moment on cage lands in1b
T cside	Fluid drag moment on cage sides in1b
^T rend	Moment contribution of roller ends to roller drag moment in1b
^T rcyl	Moment contribution of roller surface to roller drag moment in1b
U	Mass average velocity of fluid in./sec
v	Peripheral crossflow surface average velocity in./sec
V _{Hji}	Velocity of roller at i th horizontal lamina in./sec
V _{Ri}	Velocity of race at i th horizontal lamina in./sec
V _{⊻jk}	Velocity of roller at k th vertical lamina in./sec
^μ c	Coulomb coefficient of friction between roller and race guid- ing shoulder
ν	Fluid Kinemetic visosity in. ² /sec
ρ	Fluid mass density 1b sec ² /in. ⁴
τ _w	Wall shear stress, 1b/in. ²
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Thermal Analysis and Dimensional Model

а	roller inner radius, in.
^B k	energy rate constants in formulation of thermal problem, ref. equation (48), Btu/sec.
ь	roller outer radius, in.
с	radial clearance between cylindrical surface - in.
° _{p1}	specific heat of lubricant or coolent associated with i th thermal node - Bru/lb°F.
F m,n	Radiation view factor between m th and n th surface
g	gravitational acceleration, 386.4 in./aec ²
H _{ij}	energy transfer between nodes i and j Btu/sec
h _k	convective conductance associated with k^{th} surface Btu/sec - in. ² °F
IDC	bearing internal diametral clearance - in.
k	thermal conductivity - Btu/sec in. °F
^k f	thermal conductivit, of fluid - Btu/sec in. °F
د s	generic length of cylindrical surface - in.
^m i	lubricant or coolent flow rate of i th thermal node - 1b/sec.
Ni	total number of component dissipations, external energy inputs energy transfer to coolent or lubricant flows, and losses at ith thermal node.
N'i	total subset of N, not explicity containing temperature.
N _{Ta} cond	Taylor Number for pure conduction through a fluid.
N _{Ta} cr _n	critical Taylor number at speed ratio n.
r _L	radius of inner race at land for an inner land riding cage or radius of outer race at land for an outer land riding cage - in.
T _{ave}	mixed lubricant temperature - °F

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T _i	temperature of i th thermal node - °F.
^T ref	initial uniform reference temperature of all bearing elements - °F
α	coefficient of thermal expansion - in./in. °F.
ď	zhermal diffusivity - in. ² /sec.
\$	kinematic viscosity of fluid - in. ² /sec.
Y	coefficient of volumetric expansion - 1/°F.
∆T _{ij}	Temperature difference between i^{th} and j^{th} thermal nodes, $T_j - T_i$, - °F.
Δt	absolute temperature difference between surface and fluid.
δ _T	thermal deformation of the i th surface of a bearing member, (see Figure 1) - in.
ε _i	energy error function at i th temperature node for Newton- Raphson solution of temperature field in bearing - Btu/sec.
Ę m	emissivity of m th surface.
. µ	coulomb coefficient of friction between rollers and cage.
η	ratio of cage to shaft angular relocities.
ν	Poisson's ratio
υ	Boltzmann radiation constant - Btu/sey in. 2 °R"

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