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SOME APPLICATIONS OF COMPETITIVE PRICES TO DYNAMIC PROGRAMMING PROBLEMS UNDER UNCERTAINTY

Jack Schechtman

California University

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68

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SOME APPLICATIONS OF COMPETITIVE PRICES TO DYNAMIC PROGRAMMING PROBLEMS UNDER UNCERTAINTY

by

Jack Schechtman Operations Research Center University of California, Berkeley

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DEDICATION

To Sandra, Deborah and Lilian.

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To Professor David Gale, my thesis adviser who introduced me to the subject and for the many hours of advising. To the other members of my thesis committee, Professor Roy Radner and Professor Stuart Dreyfus, for their reading and suggestions. To Professor David Blackwell for his help always available. To COPPE-UFRJ and CNPq^{*}, both from Brazil, and to the Operations Research Center of the University of California at Berkeley for their encouragement and support. To Barbara Brewer for the excellent typing, and to Luiz F. L. Legey for his reading.

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ABSTRACT

We will be concerned with one-good economy. The good can be used at any period of time for production or consumption. If \underline{x} units are put into production in period \underline{t} then $f^{t}(x;\omega^{t})$ units become available as outputs in period $\underline{t+1}$; where ω^{t} is a random variable with known distribution. If \underline{c} units are consumed in period \underline{t} this produces $u^{t}(c)$ units of satisfaction or utility to the society in that period. Our main interest is the study of qualitative properties of optimal solutions for a problem in which we maximize the total expected utility accumulated in \underline{t} periods.

In deterministic cases, i.e., the output is known with certainty, the basic tools are prices and competitive policies. D. Gale has suggested the introduction of similar concepts for the stochastic cases, and it turns out that after this is done, we get a better understanding of the problem and a powerful tool in the proof of theorems. Our main purpose here is to introduce the appropriate price concept and then exploit it in several directions to obtain new information on various stochastic problems.

The concepts of price and competitive policy are introduced, and it is shown that a competitive policy is optimal. For $f(x;\omega)$ and u(c) increasing, differentiable and strictly concave, optimality conditions are obtained and it is shown that every optimal policy is competitive. For the case in which $f(x;\omega) = g(x) + \omega$, $f'(x;\omega)$ and u'(c) are convex functions we obtain a result that permits us to compare optimal consumption policies with the corresponding policies of a deterministic

VI

case in which $f(x;\omega) = g(x) + \overline{\omega}$, where $\overline{\omega} = E\omega$. Finally the case $f(x;\omega) = x + \omega$ is studied in more details and it is shown that the limiting policy satisfies the following inequalities $0 < c(y) < \overline{\omega}$ for $0 < y < +\infty$, and that lim $c(y) = \overline{\omega}$. $y \rightarrow +\infty$

0. INTRODUCTION

We will be concerned with one-good economy. The good can be used at any period of time for production or consumption. If \underline{x} units are put into production in period \underline{t} then $f^{t}(x;\omega^{t})$ units become available as outputs in period $\underline{t+1}$; where ω^{t} is a random variable with known distribution. If \underline{c} units are consumed in period \underline{t} this produces $u^{t}(c)$ units of satisfaction or utility to the society in that period. Our main interest is the study of qualitative properties of optimal solutions for a problem in which we maximize the total expected utility accumulated in \underline{t} periods.

In deterministic cases, i.e., the output is known with certainty, the basic tools are prices and competitive policies. D. Gale has suggested the introduction of similar concepts for the stochastic cases, and it turns out that after this is done, we get a better understanding of the problem and a powerful tool in the proof of theorems. Our main purpose here is to introduce the appropriate price concept and then exploit it in several directions to obtain new information on various stochastic problems.

This thesis is divided into 5 sections and 1 appendix. In Section 1 we introduce the concepts of price and competitive policy, and it is shown using the fundamental equation of Dynamic Programming that competitive policy is optimal. In Section 2 for $f(x;\omega)$ and u(c) increasing, differentiable and strictly concave, optimality conditions are obtained and it is shown that any optimal policy is competitive. Section 3 is devoted to the study of the basic properties of prices and optimal policies. In Section 4 we study the case $f(x;\omega) = g(x) + \omega$ which has applications to the income fluctuation problem considered by K. E. Yaari [16] and B. Miller [9]. In this section we generalize one result obtained by L. J. Mirman [10] which permits us to compare optimal consumption policies with the corresponding policies of a deterministic case in which $f(x;\omega) = g(x) + \overline{\omega}$, where $\overline{\omega} = E\omega$. Bounds for limiting policies and

sufficient conditions for capital growing as it is defined in E. S. Phelps [11] are also obtained. Finally in Section 5 we consider the "income fluctuation problem" in which $f(x;\omega) = x + \omega$. This problem was introduced by M. E. Yaari [16], and we obtain the surprising fact that the limiting policy satisfies the following inequality $0 < c(y) < \overline{\omega}$, for $0 < y < +\infty$ and it is also shown that $\lim_{y \to \infty} c(y) = \overline{\omega}$.

Lemmas, theorems and corollaries are numbered by section in the order that they appear and the end of a proof is represented by \blacksquare .

1. COMPETITIVE POLICIES

In this section we consider a very general one-good economy. The good can be used at any period of time either for production or consumption. If <u>x</u> units are put into production in period <u>t</u> then $f^{t}(x;\omega^{t})$ units of the same good are available as outputs in period t + 1, where ω^{t} is a random variable with known distribution.^{*} If c units are consumed in period <u>t</u> this produces $u^{t}(c)$ units of satisfaction, or utility, to the society in that period. The functions $f^{t}(x;\omega^{t})$ and $u^{t}(c)$ are called the production and utility function. In general it will be assumed that the random variables ω^{t} are independent and $f^{t}(x;\omega^{t}) \ge 0$, with strict inequality if x > 0. Furthermore we will also assume that $f^{t}(x;\omega^{t})$ and $u^{t}(c)$ are continuous function.

Our problem is: given that we have y_0 units of the good at t = 1, how should we consume, invest, in each period in order that we maximize the total expected utility accumulated in T periods. We should mention that the definitions and theorems are very natural extensions to the stochastic case, of the definitions and theorems given in D. Gale [5] for the corresponding deterministic case.

In order to simplify the exposition, we will assume that ω^t are i.i.d., $u^t(c) \equiv \delta^t u(c)$ and $f^t(x; \omega^t) \equiv f(x; \omega)$ for all t where δ is a discount factor which can be any nonnegative number.

Let $V_t(y)$ be the maximum expected utility that we get when y is the stock available and we have t periods to go. Then, the usual Dynamic Programming formulation leads us to the following functional equations:

$$V_{t}(y) = \max_{\substack{c+x=y\\c\geq 0,x\geq 0}} \{u(c) + \delta EV_{\omega}(f(x;\omega))\} \qquad \text{for } t > 1$$

* For a given x, $f^{t}(x;\omega^{t})$ is a random variable.

4

and

$$V_1(y) = \max_{\substack{c+x=y\\c \ge 0, x \ge 0}} \{u(c)\}$$

Where E_{ω} stands for the expectation operator, and will be simply denoted by E when the random variable is easily understood from the text.

The amounts that we decide to save and consume when y is the stock available when t periods are left, will be denoted by the pair

$$(x_{t}(y), c_{t}(y))$$

Definition:

A T period policy is a sequence of pair of functions $\{(x_t(y),c_t(y))\}_{t=1,\ldots,T}$ such that

> $x_t(y) + c_t(y) = y$ $x_t(y) \ge 0$, $c_t(y) \ge 0$ for t = 1, ..., T.

Definition:

A T period policy $\{(x_t(y), c_t(y))\}_{t=1,...,T}$ is optimal if $(x_t(y), c_t(y))$ is a solution of

$$V_{t}(y) = \max \{u(c) + \delta EV_{t-1}(f(x;\omega))\}$$

c+x=y
c_{2}0,x_{2}0

for all t and y.

Definition:

A T period policy {(x_t(y),c_t(y))}_{t=1,...,T} is competitive if there exists a sequence of nonnegative functions $\{p_t(y)\}_{t=1,...,T}$ such that:

* It is also assumed that x (y) and c (y) are Borel measurable functions.

(1.1)
$$c_t(y)$$
 maximizes $u(c) - p_t(y)c$

subject to $c \ge 0$

(1.2) $x_t(y)$ maximizes $\delta E(p_{t-1}(f(x_t(y);\omega))f(x;\omega)) - p_t(y)x$ subject to $x \ge 0$

(1.3)
$$P_0(y) \equiv 0$$
.*

Conditions (1.1) and (1.2) have natural economic interpretations. If the numbers $p_t(y)$ are taken as the prices of one unit of goods when y is the stock available and t periods are left then (1.2) obviously states that $x_t(y)$ is chosen to maximize the expected profit, while condition (1.1) is the classical condition of consumption theory which, at least when u(c) is differentiable, says that price is equal to marginal utility and (1.3) is an ending condition.

Theorem 1.1

If a policy $\{(x_t(y), c_t(y))\}_{t=1,...,T}$ is competitive then it is optimal, and furthermore y maximizes

> $V_t(z) - p_t(y)z$ subject to $z \ge 0$.

Proof:

The proof will be done by induction.

I. For T = 1 we have,

$$V_1(y) = \max_{\substack{c+x=y\\c\geq 0,x\geq 0}} \{u(c)\}$$

Let (x,c) be any pair such that x + c = y, $x \ge 0$, $c \ge 0$. Now, from (1.1) we get

* It is also assumed that $p_t(y)$ is a Borel measurable function.

 $u(c) - p_1(y)c \leq u(c_1(y)) - p_1(y)c_1(y)$ for all $c \geq 0$.

Thus,

(1.4)
$$u(c_1(y)) - u(c) \ge p_1(y)(c_1(y) - c)$$

= $p_1(y)(x - x_1(y))$

From (1.2), we have

$$\delta E_{p_0}(f(x_1(y);\omega))f(x_1(y);\omega) - p_1(y)x_1(y) \ge$$

$$\delta E p_0(f(x_1(y); \omega)) f(x; \omega) - p_1(y) x \quad \text{for all } x \ge 0 .$$

Hence, using (1.3)

(1.5)
$$p_1(y)(x - x_1(y)) \ge 0$$
.

Finally, from (1.4) and (1.5), it follows that

 $u(c_1(y)) \ge u(c)$ for all $0 \le c \le y$. So, $(x_1(y), c_1(y))$

is optimal.

To show that y maximizes

$$V_1(z) - p_1(y)z$$

ubject to $z \ge 0$,

let $(x_1(z),c_1(z))$ be an optimal solution to

8

$$V_1(z) = \max_{\substack{c+x=z \\ c \ge 0, x \ge 0}} \{u(c)\}$$

Now, from (1.4) and (1.5) replacing c by $c_1(z)$ and x by $x_1(z)$ we get

(1.6)
$$u(c_1(y)) - u(c_1(z)) \ge p_1(y)(c_1(y) - c_1(z))$$

and

(1.7)
$$p_1(y)(x_1(z) - x_1(y)) > 0$$
.

Adding (1.6) and (1.7) we have

 $u(c_1(y)) - p_1(y)y \ge u(c_1(z)) - p_1(y)z$ for all $z \ge 0$.

So,

$$V_1(y) - p_1(y)y \ge V_1(z) - p_1(y)z$$
 for all $z \ge 0$.

II. Assume it is true for T = t - 1, i.e., any competitive policy for a t - 1 period is optimal, and y maximizes

 $V_{t-1}(z) - p_{t-1}(y)z$

subject to $z \ge 0$.

Now,

$$V_t(y) = \max_{\substack{c+x=y\\c\geq 0,x\geq 0}} \{u(c) + \delta EV_{t-1}(f(x;\omega))\}$$

Let (x,c) be any pair such that c + x = y, $x \ge 0$, $c \ge 0$. Thus, from (1.1) we get

$$u(c) - p_t(y)c \leq u(c_t(y)) - p_t(y)c_t(y)$$
 for all $c > 0$.

Or,

(1.8)
$$u(c_t(y)) - u(c) \ge p_t(y)(c_t(y) - c)$$

= $p_t(y)(x - x_t(y))$.

From (1.2) we get

$$\delta E p_{t-1}(f(x_t(y);\omega)f(x_t(y);\omega) - p_t(y)x_t(y)) \ge \delta E p_{t-1}(f(x_t(y);\omega)f(x;\omega) - p_t(y)x \quad \text{for all } x \ge 0$$

So,

(1.9)
$$p_{t}(y)(x - x_{t}(y)) \geq \delta E p_{t-1}(f(x_{t}(y); \omega) f(x; \omega) - \delta E p_{t-1}(f(x_{t}(y); \omega) f(x_{t}(y); \omega)) .$$

Now, from the induction hypothesis, y maximizes

 $V_{t-1}(z) - p_{t-1}(y)z$

subject to $z \ge 0$.

Thus,

$$V_{t-1}^{(f(x_t(y);\omega)) - p_{t-1}^{(f(x_t(y);\omega))f(x_t(y);\omega)} \ge V_{t-1}^{(f(x;\omega)) - p_{t-1}^{(f(x_t(y);\omega))f(x;\omega)}.$$

Or, taking the expected value, rearranging and multiplying by δ we get

(1.10)
$$\delta E_{t-1}(f(x_t(y)\omega))f(x;\omega) - \delta E_{t-1}(f(x_t(y);\omega)f(x_t(y);\omega)) \ge 0$$

$$\delta EV_{t-1}(f(x;\omega)) - \delta EV_{t-1}(f(x_t(y);\omega))$$

From (1.8), (1.9) and (1.10) we get

$$u(c_t(y)) - u(c) \geq \delta EV_{t-1}(f(x;\omega)) - \delta EV_{t-1}(f(x_t(y);\omega)).$$

Or,

$$u(c_{t}(y)) + \delta EV_{t-1}(f(x_{t}(y);\omega)) \geq u(c) + \delta EV_{t-1}(f(x;\omega)) .$$

So, $(x_t(y), c_t(y))$ is optimal.

To show that y maximizes

$$V_t(z) - p_t(y)z$$

subject to $z \ge 0$,

let $(x_t(z), c_t(z))$ be an optimal solution to

$$V_t(z) = \max \{u(c) + \delta E V_{t-1}(f(x;\omega))\}$$

 $c+x=z$
 $c\geq 0, x>0$.

From (1.1) and (1.2) we have

(1.11)
$$u(c_t(y)) - u(c_t(z)) \ge p_t(y)(c_t(y) - c_t(z))$$

and

$$(1.12) \qquad \delta E P_{t-1}(f(x_t(y); \omega)) f(x_t(y); \omega) - \delta E P_{t-1}(f(x_t(y); \omega)) f(x_t(z); \omega) \\ \geq P_t(y)(x_t(y) - x_t(z)) .$$

But from (1.10) replacing x by $x_t(z)$ and rearranging we get

(1.13)
$$\delta EV_{t-1}(f(x_t(y);\omega)) - \delta EV_{t-1}(f(x_t(z);\omega)) \geq$$

$$\delta E_{t-1}(f(x_t(y);\omega))f(x_t(y);\omega) - \delta E_{t-1}(f(x_t(y);\omega))f(x_t(z);\omega) .$$

Thus, from (1.13) and (1.12) it follows that

(1.14)
$$\delta EV_{t-1}(f(x_t(y); \omega)) - \delta EV_{t-1}(f(x_t(z); \omega) \ge p_t(y)(x_t(y) - x_t(z)))$$

Now, adding (1.11) and (1.14) we get

$$u(c_{t}(y)) + \delta EV_{t-1}(f(x_{t}(y); \omega)) - u(c_{t}(z)) - \delta EV_{t-1}(f(x_{t}(z); \omega))$$

$$\geq p_{t}(y)(y - z)$$

or,

$$V_t(y) - p_t(y)y \ge V_t(z) - p_t(y)z$$
 for all $z \ge 0$

2. CASE OF CONCAVE UTILITY AND PRODUCTION FUNCTION

From now on we will assume that the functions $f(x;\omega)$ and u(c) are strictly concave, increasing and differentiable. The reason for making this assumption, is to obtain the converse of Theorem 1.1.

First we will show that $V_t(y)$ inherit the basic properties of the function u(c).

Theorem 2.1

The function $V_t(y)$ is increasing and strictly concave for all t.

Proof:

The first part is immediate, the second, will be done by induction.

I. For t = 1

 $V_1(y) = u(y)$

since u(c) is increasing. So, $V_1(y)$ is strictly concave, since by assumption u(c) is strictly concave.

II. Assume that $V_{t-1}(y)$ is strictly concave. Now,

(2.1)
$$V_t(y) = \max_{\substack{t=y\\c \ge 0, x \ge 0}} \{u(c) + \delta EV_{t-1}(f(x; \omega))\}$$

Pick y_1 , $y_2 \in [0, +\infty)$, and let $(x_t(y_1), c_t(y_1))$ and $(x_t(y_2), c_t(y_2))$ be the corresponding solutions to (2.1). Let, \overline{y} be a convex combination of y_1 and y_2 , i.e., $\overline{y} = \lambda_1 y_1 + \lambda_2 y_2$, $\lambda_1 + \lambda_2 = 1$, $\lambda_1 \ge 0$, $\lambda_2 \ge 0$. Then,

$$V_t(y) = \max_{\substack{c+x=y\\c \ge 0, x \ge 0}} \{u(c) + \delta\phi_{t-1}(x)\}$$

Where,

 $\phi_{t-1}(x) \equiv EV_{t-1}(f(x; \omega))$,

which is strictly concave from the induction hypothesis. Since,

$$(\lambda_1 x_t(y_1) + \lambda_2 x_t(y_2), \lambda_1 c_t(y_1) + \lambda_2 c_t(y_2))$$

is a feasible solution to (2.1), it follows that,

$$v_{t}(y) \ge u(\lambda_{1}c_{t}(y_{1}) + \lambda_{2}c_{t}(y_{2})) + \delta\phi_{t-1}(\lambda_{1}x_{t}(y_{1}) + \lambda_{2}x_{t}(y_{2}))$$

$$> \lambda_{1}u(c_{t}(y_{1})) + \lambda_{2}u(c_{t}(y_{2})) + \delta\lambda_{1}\phi_{t-1}(x_{t}(y_{1})) + \delta\lambda_{2}\phi_{t-1}(x_{t}(y_{2}))$$

$$= \lambda_{1}v_{t}(y_{1}) + \lambda_{2}v_{t}(y_{2}) =$$

It is an immediate consequence of the previous theorem that the solution of (2.1) is unique. Hence, $x_t(y)$ and $c_t(y)$ are well defined functions.

Theorem 2.2

The function $V_t(y)$ is differentiable for y > 0, and for all t.

Proof:

I. for t = 1 we have,

$$V_{1}(y) = u(y)$$
.

So, $V_t(y)$ is differentiable for y > 0, since by assumption u(c) is differentiable for c > 0.

II. Assume that $V_{t-1}(y)$ is differentiable for y > 0. To prove that $V_t(y)$ is differentiable for y > 0, we must show that $V_t(y)$ has a unique support for all y > 0.

Let p be a support of V (y) at y. Then,

 $V_{t}(y') - V_{t}(y) \leq p(y' - y), \text{ for all } y' \geq 0.$

Or,

(2.2)
$$V_{t}(y') - py' \leq V_{t}(y) - py$$

Now, choose any c', $x' \ge 0$ and let y' = c' + x'. Then,

(2.3)
$$u(c') + \delta \phi_{t-1}(x') \leq V_t(y')$$

from the definition of $V_t(y)$. So, from (2.2) and (2.3) we get

(2.4)
$$u(c') + \delta\phi_{t-1}(x') - p(c' + x') \leq V_{t}(y') - py'$$
$$\leq V_{t}(y) - py$$
$$= u(c_{t}(y)) + \delta\phi_{t-1}(x_{t}(y)) - p(x_{t}(y) + c_{t}(y)) .$$

Thus,

(2.5)
$$u(c') - pc' + \delta\phi_{t-1}(x') - px' \leq u(c_t(y)) - pc_t(y) + \delta\phi_{t-1}(x_t(y)) - px_t(y)$$

Now, either $x_t(y) > 0$ or $c_t(y) > 0$ since $y = c_t(y) + x_t(y) > 0$. Suppose $c_t(y) > 0$, then for $x' = x_t(y)$ in (2.5), we get

(2.6)
$$u(c') - pc' \leq u(c_t(y)) - pc_t(y)$$
 for all $c' \geq 0$.

Or, u(c) - pc has a maximum at $c_t(y) > 0$. Then,

(2.7)
$$u'(c_y) = p$$
.

In an analagous way for $x_t(y) > 0$ we get

(2.8)
$$\delta \phi_{t-1}(x') - px' \leq \delta \phi_{t-1}(x_t(y)) - px_t(y)$$
, for all $x' \geq 0$.

Or, $\phi_{t-1}(x) - px$ has a maximum at $x_t(y) > 0$. So,

(2.9)
$$p = \delta \phi'_{t-1}(x_t(y)) =$$

In spite of the fact that $V_t(y)$ is differentiable for y > 0, the

function $c_t(y)$ need not be. Consider the following case:

$$f(x;\omega) = x + \omega ,$$
$$u(c) = \log c$$

and, ω assumes the values $a_1 = 1$, $a_2 = 2$ with corresponding probabilities $\pi_1 = 1/2$ and $\pi_2 = 1/2$. Now,

$$V_2(y) = \max \{ \log c + E \log (x + \omega) \}$$

 $c+x=y$
 $c\geq 0, x\geq 0$.

Which is equivalent to maximize

(2.10)
$$\log c + \sum_{i=1}^{2} \pi_i \log (y - c + a_i) \quad \text{for } c \ge 0$$
.

Taking the derivatives in (2.10), we get

(2.11)
$$\frac{1}{c} = \sum_{i=1}^{2} \frac{\pi_{i}}{y - c + a_{i}}$$

Making c = y in (2.11) we get a critical value

$$\bar{y} = \frac{1}{\sum_{i=1,2}^{\pi_i} \bar{a}_i} = \frac{4}{3}$$
,

below which, we consume all the stock of goods available, i.e.,

$$c_2(y) = y$$
 for $0 \le y < \overline{y}$.

For $y \ge \overline{y}$ the solution of (2.10) is given by

$$c_2(y) = \frac{6y + 9 - \sqrt{4y^2 + 12y + 17}}{8}$$

Now, taking the right and left hand side derivatives of $c_2(y)$, at the point \overline{y} we get:

$$\frac{dc_2(y)}{dy} \bigg|_{\overline{y}}^+ = \frac{1280}{2432}$$

and

$$\frac{\mathrm{dc}_2(\mathbf{y})}{\mathrm{dy}} \Big|_{\overline{\mathbf{y}}}^+ = 1 \ .$$

Which shows that $c_2(y)$ is nondifferentiable at the point \overline{y} . This example could be generalized for the case in which ω is any discrete random variable with a finite range.

To prove the converse of Theorem 1.1, we need to define the prices $p_t(y)$. The natural candidates are of course, $V'_t(y)$.

For some problems, when we follow the optimal policy, the level of stock is always positive. Hence, for those cases we do not need to define the prices $p_t(0)$. On the other hand, when this is not the case, in order to define the prices $p_t(0)$, we must show that the functions $V_t(y)$ have a derivative from the right at the point y = 0.

If $f'(o;\omega) = +\infty$, or $u'(o) = \infty$ and $f(o;\omega) = 0$ with positive probability, it can be shown from (2.7) and (2.9), that for the optimal policy $x_t(y) > 0$ whenever y > 0. In the Appendix it is shown that the functions $V_t(y)$ are differentiable from the right for y = 0, whenever $u'(0) < +\infty$ and $f'(0;\omega) < +\infty$.

Definition:

A problem is admissible whenever either the level of stock is always positive for the optimal policy, or the functions $V_t(y)$ are differentiable for y = 0.

Theorem 2.3

If a problem is admissible then the optimal policy is competitive. Furthermore $(x_t(y), c_t(y))$ satisfies the following relations

(2.12)
$$P_t(y) \ge u'(c_t(y))$$
 with equality if $c_t(y) > 0$.

and

(2.13)
$$P_{t}(y) \ge \delta E_{t-1}(f(x_{t}(y);\omega))f'(x_{t}(y);\omega))$$

with equality if $x_t(y) > 0$. Where $p_t(y) = V'_t(y)$.

Proof:

In (2.5) replacing p by
$$p_t(y)$$
, $\phi_{t-1}(x')$ by $EV_{t-1}(f(x';\omega))$ we get
(2.14) $u(c') - p_t(y)c' + \delta EV_{t-1}(f(x';\omega)) - p_t(y)x'$

$$\leq u(c_{t}(y)) - p_{t}(y)c_{t}(y) + \delta EV_{t-1}(f(x_{t}(y);\omega) - p_{t}(y)x_{t}(y) .$$

Now, setting $x' = x_t(y)$ we get

(2.15)
$$u(c') - p_t(y)c' \leq u(c_t(y)) - p_t(y)c_t(y)$$
 for all $c' > 0$.

So, the competitive condition (1.1) holds. To obtain (2.12) we observe that $c_t(y)$ maximizes

u(c) - p_t(y)c

subject to $c \ge 0$.

Hence,

$$p_{+}(y) \ge u^{+}(c_{+}(y))$$

with equality if $c_t(y) > 0$. In a similar way, setting in (2.14) $c' = c_t(y)$ we get

$$\delta EV_{t-1}(f(x';\omega)) - p_t(y)x'$$

 $\leq \delta EV_{t-1}(f(x_t(y);\omega) - p_t(y)x_t(y)).$

That is, x_t(y) maximizes

$$\delta EV_{t-1}(f(x;\omega)) - p_t(y)x$$

subject to $x \ge 0$.

So,

(2.16)
$$p_t(y) \ge \delta E p_{t-1}(f(x_t(y); \omega)) f'(x_t(y); \omega)$$
,

with equality if $x_{+}(y) > 0$, which is (2.13).

Now, multiplying (2.16) by $x - x_t(y)^*$, and using the concavity of $f(x;\omega)$ we have

$$(x - x_{t}(y))p_{t}(y) \geq \delta E p_{t-1}(f(x_{t}(y); \omega))f'(x_{t}(y); \omega)(x - x_{t}(y))$$

$$\geq \delta E p_{t-1}(f(x_{t}(y); \omega))(f(x; \omega) - f(x_{t}(y); \omega)) .$$

Or,

$$Ep_{t-1}(f(x;\omega))f(x;\omega)) - p_t(y)x \leq Ep_{t-1}(f(x_t(y);\omega)) - p_t(y)x_t(y)$$

for all $x \ge 0$, that is, competitive condition (1.2) holds \blacksquare

From now on the derivatives of $V_t(y)$ will be denoted by $p_t(y)$, and will be called prices.

The prices $p_t(y)$ are continuous decreasing functions since they are the derivatives of concave functions. The continuity is defined on $(0, +\infty)$, and on $[0, +\infty)$ if $V_t(y)$ are differentiable at y = 0.^{**}

*If $x_t(y) > 0$, (2.16) is an equality; and for $x_t(y) = 0$, $x - x_t(y) \ge 0$ and hence the direction of the inequality does not change.

** For a proof see W. Fenchel (4).

3. PROPERTIES OF $x_t(y)$, $c_t(y)$ AND $p_t(y)$.

From now on we will assume that all problems are admissible. In all proofs we will not make any distinction between the cases in which the level of stock is always positive and those for which $p_t(0)$ is well defined.

Theorem 3.1

The functions $x_t(y)$, $c_t(y)$ are nondecreasing functions. Furthermore, $x_t(y)(c_t(y))$ is increasing whenever $x_t(y) > 0(c_t(y) > 0)$.

Proof:

Let $y' > y \ge 0$. First we will show that $c_t(y') \ge c_t(y)$. Consider the following cases:

Case 1.

 $c_t(y') > 0$ and $c_t(y) > 0$. Then from the optimality conditions (2.12), it follows that

 $p_{t}(y') = u'(c_{t}(y'))$

and

 $p_t(y) = u'(c_t(y))$.

Thus,

by monotonicity of $p_t(y)$.

So,

 $c_{t}(y') > c_{t}(y)$

by monotonicity of u'(c) .

Case ii.

 $c_t(y') \ge 0$ and $c_t(y) = 0$. It immediately follows that

 $c_t(y') \ge c_t(y)$.

Now, we will show that $c_t(y') = 0$ and $c_t(y) > 0$ is not possible. From (2.12) we have

 $p_+(y') \ge u'(0)$

and

 $p_t(y) = u'(c_t(y))$.

But

 $p_{t}(y') < p_{t}(y)$.

Hence,

 $u'(0) < u'(c_+(y))$.

Which is a contradiction. An analagous proof holds for $x_t(y)$, except that we use the optimality condition (2.13).

Theorem 3.2*

The functions $x_t(y)$ and $c_t(y)$ are continuous.

Proof:

From Theorem 3.1, $x_t(y)$ and $c_t(y)$ are nondecreasing functions. Thus for $\overline{y} \ge 0$

$$\lim_{y \neq y} c_t(y) = c_t(\overline{y}) \leq c_t(\overline{y}) = \lim_{y \neq \overline{y}} c_t(y)$$

*The same proof given by W. A. Brock and L. J. Mirman [2].

and

$$\lim_{y \uparrow y} x_t(y) = x_y(\overline{y}) \leq x_t(\overline{y}) = \lim_{y \downarrow \overline{y}} x_t(y) .$$

However

 $x_{t}(y) + c_{t}(y) = y$.

Hence,

 $x_t(\overline{y}) + c_t(\overline{y}) = y$

and

$$x_{t}(\bar{y}^{+}) + c_{t}(\bar{y}^{+}) = y$$

From which we get

$$[x_{y}(\bar{y}) - x_{t}(\bar{y})] + [c_{t}(\bar{y}) - c_{t}(\bar{y})] = 0.$$

Since, both $x_t(y)$ and $c_t(y)$ are nondecreasing in y, both terms of the sum must be equal to zero. Hence

 $c_t(\bar{y}) = c_t(\bar{y})$

and

$$x_{t}(\bar{y}) = x_{t}(\bar{y})$$
.

Which implies the continuity of $c_t(y)$ and $x_t(y)$.

Theorem 3.3.

$$P_t(y) \ge P_{t-1}(y)$$
 for all $t \ge 2$.

^{*} In general we need to prove this only for y > 0. By continuity of $p_t(y)$ it will follow for y = 0.

Proof:

The proof will be done by induction.

I. For t = 2, we have from the optimality conditions (2.12) that

 $p_2(y) \ge u'(c_2(y))$

and

 $p_1(y) = u'(y)$.

Hence,

 $P_2(y) \ge P_1(y)$

since, $c_2(y) \leq y$ and u'(c) is a decreasing function.

II. Assume that it is true for t - 1, i.e., $p_{t-1}(y) \ge p_{t-2}(y)$. We need to consider two cases depending on the values that $x_t(y)$ and $x_{t-1}(y)$ assume.

Case 1.

 $0 \leq x_t(y) \leq y$, $0 < x_{t-1}(y) \leq y$. Then, from the optimality condition (2.13) we get

(3.1)
$$p_t(y) \ge \delta E p_{t-1}(f(x_t(y); \omega)) f'(x_t(y); \omega)$$

and

(3.2)
$$p_{t-1}(y) = \delta E p_{t-2}(f(x_{t-1}(y); \omega)) f'(x_{t-1}(y); \omega)) .$$

Now, suppose that $p_t(y) < p_{t-1}(y)$. Hence,

(3.3) $c_t(y) \ge c_{t-1}(y)$

and consequently

 $x_t(y) \leq x_{t-1}(y)$.

From (3.1) and the induction hypothesis we get

$$(3.5) \qquad p_{t}(y) \geq \delta E p_{t-1}(f(x_{t}(y);\omega))f'(x_{t}(y);\omega)) \\ \geq \delta E p_{t-2}(f(x_{t}(y);\omega))f'(x_{t}(y);\omega))$$

So, from (3.5), (3.4) and the monotonicity of $p_t(y)$ and $f'(x;\omega)$, we have

$$p_{t}(y) \ge \delta E p_{t-2}(f(x_{t-1}(y); \omega)) f'(x_{t-1}(y); \omega)$$

= $p_{t-1}(y)$ by (3.2).

Which is a contradiction.

Case ii.

(3.4)

 $0 \leq x_t(y) \leq y$, $x_{t-1}(y) = 0$. From (2.12) we have,

 $p_t(y) \ge u'(c_t(y))$

and

$$P_{t-1}(y) = u'(y)$$

Hence,

 $p_t(y) \ge p_{t-1}(y)$

since, $c_t(y) \leq y$ and u'(c) is a decreasing function \blacksquare

It is an immediate consequence the following corollary

Corollary 3.4.

 $c_t(y) \leq c_{t-1}(y)$ and $x_t(y) \geq x_{t-1}(y)$ for all $t \geq 2$.

We can now prove a result which will be needed later when we consider infinite horizon problems.

Theorem 3.5.

The limiting policy $x(y) = \lim_{t \to \infty} x_t(y)$ and $c(y) = \lim_{t \to \infty} c_t(y)$ exist and are nondecreasing continuous functions. Furthermore the sequence of functions $x_t(y)$ and $c_t(y)$ converge uniformly in any finite closed interval.

Proof:

From Corollary 3.4 we have

$$x_{t+1}(y) \ge x_t(y)$$
 for all t, $y \ge 0$

and

 $c_{t+1}(y) \leq c_t(y)$ for all $t, y \geq 0$.

But $c_t(y) \ge 0$ and $x_t(y) \le y$ for all t. Hence,

$$x(y) = \lim_{t \to \infty} x_t(y)$$

and

$$c(y) = \lim_{t \to \infty} c_t(y)$$

are well defined functions. Now, since $x_t(y)$, $c_t(y)$ are nondecreasing continuous functions, it follows that x(y) and c(y) are also nondecreasing functions. The continuity of x(y) and c(y) will follow by the same arguments used in Theorem 3.2. From the fact that a sequence of monotonic functions converging pointwise to a continuous function on a closed interval converges uniformly the theorem is finally proved =

The derivatives of the utility functions $u(c) = \log c$, $u(c) = c^{\gamma}0 < \gamma < 1$, $u(c) = ke^{-c}$ and the production function $f(x;\omega) = \omega x^{\gamma}0 < \gamma < 1$ usually found in the literature are convex functions. For those cases we can state the following theorem.

Theorem 3.6.

If u'(c) and f'(x; ω) are convex functions then $p_t(y)$ is also convex for all t.

Proof:

For t = 1 it is immediate, since

$$p_1(y) = u'(c)$$
.

Now, assume that $p_{t-1}(y)$ is convex; and suppose that $p_t(y)$ is not convex, i.e., there exist y_1 and $y_2 \in (0, +\infty)$, and λ_1 , $\lambda_2 \ge 0$, $\lambda_1 + \lambda_2 = 1$ such that for $\overline{y} = \lambda_1 y_1 + \lambda_2 y_2$ we have

(3.6)
$$P_t(\bar{y}) > \lambda_1 P_t(y_1) + \lambda_2 P_t(y_2)$$
.

We need to consider three cases depending on the values that $x_t(y)$ assumes at y_1 , y_2 and \overline{y} .

Case 1.

 $0 \leq x_t(y_1) \leq y_1$, $0 \leq x_t(y_2) \leq y_2$, $0 < x_t(\overline{y}) < \overline{y}$, and whenever the three inequalities holds. Then, from (2.12) and (2.13) it follows that

(3.7) $p_{t}(y_{1}) \ge u'(c_{t}(y_{1}))$ $p_{t}(y_{2}) \ge u'(c_{t}(y_{2}))$ $p_{t}(\bar{y}) = u'(c_{t}(\bar{y}))$

(3.8)
$$\lambda_{1} P_{t}(y_{1}) \geq \delta \lambda_{1} E_{p_{t-1}}(f(x_{t}(y_{1});\omega))f'(x_{t}(y_{1});\omega))$$
$$\lambda_{2} P_{t}(y_{2}) \geq \delta \lambda_{2} E_{p_{t-1}}(f(x_{t}(y_{2});\omega))f'(x_{t}(y_{2});\omega))$$
$$P_{t}(\overline{y}) = \delta E_{p_{t-1}}(f(x_{t}(\overline{y});\omega))f'(x_{t}(\overline{y});\omega))$$

Now, from (3.6) and (3.7) we have

$$u'(c_{t}(\bar{y})) > \lambda_{1}u'(c_{t}(y_{1})) + \lambda_{2}u'(c_{t}(y_{2}))$$

$$\geq u'(\lambda_{1}c_{t}(y_{1}) + \lambda_{2}c_{t}(y_{2}))$$

 $\mathbf{c}_{t}(\bar{\mathbf{y}}) \leq \lambda_{1}\mathbf{c}_{t}(\mathbf{y}_{1}) + \lambda_{2}\mathbf{c}_{t}(\mathbf{y}_{2})$

by monotonicity of u'(c) . And consequently

(3.9)
$$x_t(\bar{y}) \ge \lambda_1 x_t(y_1) + \lambda_2 x_t(y_2)$$
.

Now, from (3.6) and (3.8) we get

(3.10)

$$p_{t}(\bar{y}) > \delta \lambda_{1} E p_{t-1}(f(x_{t}(y_{1}); \omega)) f'(x_{t}(y_{1}); \omega)) + \delta \lambda_{2} E p_{t-1}(f(x_{t}(y_{2}); \omega)) f'(x_{t}(y_{2}); \omega))$$

$$\geq \delta E p_{t-1} (f(\lambda_1 x_t(y_1) + \lambda_2 x_t(y_2)); \omega)) f'(\lambda_1 x_t(y_1) + \lambda_2 x_t(y_2); \omega))$$

Where in the last inequality we used the fact that

$$\phi'_{t-1}(x) = E_{p_{t-1}}(f(x;\omega))f'(x;\omega)$$

is convex. * Finally from (3.10) and (3.9) we have

24

and

^{*} $\psi(x) \equiv p_{t-1}(f(x;\omega))f'(x;\omega)$ as a product of nonnegative, decreasing and convex functions is also convex. So, $Ep_{t-1}(f(x;\omega))f'(x;\omega)$ is convex.

$$P_{t}(\bar{y}) > \delta E_{t-1}(f(x_{t}(\bar{y}); \omega))f'(x_{t}(\bar{y}); \omega))$$

= $P_t(\bar{y})$

by (3.7). Which is a contradiction.

Case ii.

 $x_{t}(y_{1}) = 0 , 0 \leq x_{t}(y_{2}) < y_{2} , x_{t}(\bar{y}) = 0 . \text{ Then from (2.12) we have}$ $P_{t}(y_{1}) = u'(y_{1})$ (3.11) $P_{t}(y_{2}) = u'(c_{t}(y_{2}))$ $P_{t}(\bar{y}) = u'(\bar{y}) .$

So, from (3.6) and (3.11) we get

$$u'(y) > \lambda_{1}u'(y_{1}) + \lambda_{2}u'(c_{t}(y_{2}))$$

$$\geq u'(\bar{y}) .$$

Case iii.

 $x_t(y_1) = y_1$, $C < x_t(y_2) \le y_2$ and $x_t(\overline{y}) = \overline{y}$. The proof is the same as in Case i except that (3.9) is obtained in the following way:

$$\overline{y} = \lambda_1 y_1 + \lambda_2 y_2 .$$
But, $x_t(y_1) = y_1$, $x_t(\overline{y}) = \overline{y}$ and $x_t(y_2) \leq y_2 .$ So,
 $x_t(\overline{y}) \geq \lambda_1 x_t(y_1) + \lambda_2 x_t(y_2) =$

4. THE CASE OF $f(x;\omega) = g(x) + \omega$

One reason for studying this case is its application to the "income fluctuation problem" in which a consumer is faced with the following situation: He has a t period planning horizon and at each period he must decide how much to consume and save, in order to maximize his total expected utility. If \underline{x} is the amount saved at period \underline{t} , then the available income in the next period is $rx + \omega^{t}$, i.e., $f(x;\omega^{t}) = rx + \omega^{t}$, where ω^{t} is a nonnegative bounded random variable and $r \ge 1$ is the interest factor of a riskless investment. B. Miller [9] considers the case in which $u(c) = \log c$, borrowing is allowed with some constraints, w^t are independent and special constraints are imposed on the consumption. M. E. Yaari [16] considers the case r = 1, ω^{t} are i.i.d., borrowing is allowed at zero interest rate and no constraints are imposed on the consumption, (this case will be considered in more detail in Section 5). The "income fluctuation problem" differs from those considered by E. S. Phelps [10] and N. H. Hakansson [8] in that they consider r as a random variable and ω^t is known with certainty. From now on when we talk about an "income fluctuation problem," it is understood that no borrowing is allowed, $0 \leq c_{t}(y) \leq y$ and ω^{t} are i.i.d. random variables with range [a, A], $a \ge 0$ and $A < +\infty$.

Our main interest in this section is to obtain bounds for the limiting policy $\underline{c(y)}$ (by comparing it with various cases of perfect certainty), which we know from Theorem 3.5, is a continuous nondecreasing function. First we introduce some notation:

Notation

i) If $f(x;\omega) = g(x) + a$, then the corresponding prices and policies will be denoted by $p_t^a(y)$ and $(x_t^a(y), c_t^a(y))$.

^{*} The method used here could be applied to the stationary case of B. Miller [9] with borrowing.

ii) If $f(x;\omega) = g(x) + \overline{\omega}$, then the corresponding prices and policies will be denoted by $p_t^{\overline{\omega}}(y)$ and $(x_t^{\overline{\omega}}(y), c_t^{\overline{\omega}}(y))$.

iii) If $f(x;\omega) = g(x) + A$, then the corresponding prices and policies will be denoted by $p_t^A(y)$ and $\left(x_t^A(y), c_t^A(y)\right)$,

iv) and as the usual $p_t(y)$ and $(x_t(y), c_t(y))$ stands for the case $f(x;\omega) = g(x) + \omega$.

The optimality condition (2.12) and (2.13) are for i, ii, iii

(4.1)
$$p_{t}^{\mathbf{v}}(y) \geq \delta g' \left(x_{t}^{\mathbf{v}}(y) \right) p_{t-1}^{\mathbf{v}} \left(g \left(x_{t}^{\mathbf{v}}(y) \right) + v \right)$$
$$p_{t}^{\mathbf{v}}(y) \geq u' \left(c_{t}^{\mathbf{v}}(y) \right)$$

with v = a, $\overline{\omega}$ and A respectively, and for iv,

(4.2)
$$p_{t}(y) \geq \delta g'(x_{t}(y)) E p_{t-1}(g(x_{t}(y)) + \omega)$$
$$p_{t}(y) \geq u'(c_{t}(y)) .$$

Now we will prove a theorem that will give a lower bound for $c_t(y)$, i.e., we will compare $c_t(y)$ with the optimal consumption policy $c_t^a(y)$ of a "pessimistic consumer" who assumes $\omega \equiv a$.

Theorem 4.1

 $p_t(y) \leq p_t^a(y)$ for all t, and consequently $c_t(y) \geq c_t^a(y)$ for all t.

Proof:

The proof will be done by induction.

I. For t = 1 it is true since $p_1(y) = p_1^a(y) = u'(y)$.

II. Assume it is true for t-1, i.e., $p_{t-1}(y) \leq p_{t-1}^{a}(y)$. We need to consider two cases depending on the values that $x_{t}(y)$ assumes.

28

 $x_t(y) = 0$. Then $c_t(y) = y$ and $p_t(y) = u'(y)$. So, $p_t(y) \leq p_t^a(y)$ since $c_t^a(y) \leq y$ and u'(c) is decreasing function.

Case ii.

 $x_t(y) > 0$. By contradiction suppose that $p_t(y) > p_t^a(y)$. Then,

$$(4.3) c_t(y) \leq c_t^a(y)$$

and

(4.4)
$$x_{t}(y) \ge x_{t}^{a}(y)$$
.

Now, from the optimality condition (4.2) we get

(4.5)
$$p_t(y) = \delta g'(x_t(y)) E p_{t-1}(g(x_t(y)) + \omega)$$
.

Thus,

(4.6)
$$P_t(y) \leq \delta g'(x_t^a(y)) E_{t-1}(g(x_t^a(y)) + \omega),$$

since from (4.4) $x_t(y) \ge x_t^a(y)$ and g'(x) and $p_{t-1}(y)$ are decreasing functions. Now, from (4.6) using the fact that $p_{t-1}(y)$ is decreasing, and the induction hypothesis we get

$$p_{t}(y) \leq \delta g'(x_{t}^{a}, y) p_{t-1}(g(x_{t}^{a}(y)) + a)$$

$$\leq \delta g'(x_{t}^{a}(y)) p_{t-1}'(g(x_{t}^{a}(y)) + a)$$

$$\leq p_{t}^{a}(y) \quad by \quad (4.1) ,$$

which is a contradiction.

An immediate consequence is the following corollary.

Corollary 4.2.

If
$$c(y) = \lim_{t \to \infty} c_t(y)$$
 and $c^a(y) = \lim_{t \to \infty} c_t^a(y)$ then $c^a(y) \leq c(y)$.

In a similar way we can prove the following theorem and corollary that compare $c_t(y)$ with the consumption $c_t^A(y)$ of an "optimistic consumer" who assumes $\omega \equiv A$.

Theorem 4.3.

 $p_t(y) \ge p_t^A(y)$ for all <u>t</u> and consequently $c_t(y) \le c_t^A(y)$ for all t. <u>Corollary 4.4</u>.

If
$$c(y) = \lim_{t \to \infty} c_t(y)$$
 and $c^A(y) = \lim_{t \to \infty} c^A(y)$ then $c(y) \leq c^A(y)$.

If we consider the cases in which g'(x) and u'(c) are convex functions, we will be able to compare, the optimal policy $c_t(y)$ with the corresponding solution $c_t^{\widetilde{\omega}}(y)$ of the deterministic problem in which ω is replaced by $\widetilde{\omega} = E\omega$, i.e., we will show that $c_t(y) \leq c_t^{\widetilde{\omega}}(y)$. This result generalizes the one obtained by L. J. Mirman [10] page 184.

Theorem 4.5.

If g'(x) and u'(c) are convex functions then $p_t(y) \ge p_t^{\widetilde{\omega}}(y)$, and consequently $c_t(y) \le c_t^{\widetilde{\omega}}(y)$.

I. It is true for t = 1, since $p_1(y) = p_1^{\overline{\omega}}(y) = u'(y)$.

II. Assume that it is true for t-1. We need to consider two cases depending on the values that $x_t^{\widetilde{\omega}}(y)$ assumes.

Case 1.

 $x_t^{\widetilde{w}}(y) > 0$. By contradiction suppose that $p_t(y) < p_t^{\widetilde{w}}(y)$. Thus, (4.7)

$$c_t(y) \ge c_t^{\omega}(y)$$

30

and consequently

(4.8)
$$x_t(y) \leq x_t^{\widetilde{\omega}}(y)$$
.

Now, from (4.2), (4.8) and the fact that g(x) is increasing, g'(x) and $p_{t-1}(y)$ are decreasing functions we get

(4.9)
$$p_{t}(y) \geq \delta g'(x_{t}(y)) E p_{t-1}(g(x_{t}(y)) + \omega)$$
$$\geq \delta g'(x_{t}^{\widetilde{\omega}}(y)) E p_{t-1}(g(x_{t}^{\widetilde{\omega}}(y)) + \omega) .$$

But, from Theorem 3.6 we have that $p_t(y)$ is a convex function. Hence from (4.9) using the convexity and the induction hypothesis we get

$$p_{t}(y) \geq \delta g'(x_{t}^{\widetilde{\omega}}(y)) E p_{t-1}(g(x_{t}^{\widetilde{\omega}}(y)) + \omega)$$

$$\geq \delta g'(x_{t}^{\widetilde{\omega}}(y)) p_{t-1}(g(x_{t}^{\widetilde{\omega}}(y)) + \overline{\omega})$$

$$\geq \delta g'(x_{t}^{\widetilde{\omega}}(y)) p_{t-1}^{\widetilde{\omega}}(g(x_{t}^{\widetilde{\omega}}(y)) + \overline{\omega})$$

$$= p_{t}^{\widetilde{\omega}}(y)$$

by (4.2), which is a contradiction.

Case ii.

$$x_t^{\overline{\omega}}(y) = 0$$
. Then,

$$c_t^{\overline{\omega}}(y) = y$$

and

$$p_t^{\overline{\omega}}(y) = u'(y)$$
.

Now,

 $p_t(y) \ge u'(c_t(y))$.

$$p_t(y) \ge p_t^{\widetilde{\omega}}(y)$$

since
$$c_t(y) \leq y$$
 and $u'(c)$ is a decreasing function

And it is an immediate consequence the following corollary.

Corollary 4.6.

If
$$c^{\omega}(y) = \lim_{t \to \infty} c_t(y)$$
 then $c(y) \leq c^{\widetilde{\omega}}(y)$.

Theorem 4.7.

The limiting policy satisfies the following inequalities

(4.10)
$$c^{a}(y) \leq c(y) \leq c^{A}(y)$$

Moreover if u'(c) and g'(x) are convex functions then

(4.11)
$$c^{a}(y) \leq c(y) \leq c^{\overline{\omega}}(y)$$
.

Proof:

It is an immediate consequence of Corollary 4.2, Corollary 4.4 and Corollary 4.6

Example:

As an example of application of the last theorem consider the following "income fluctuation problem"

$$f(x;\omega) = rx + \omega$$
, $r \ge 1$

$$u(c) = \lambda c', \lambda > 0 \quad 0 < \gamma < 1$$

and we assume that $\delta r^{\gamma} < 1$, $\delta r > 1$ and $\omega \in [0, A]$.

32

The limiting policies $c^{a}(y)$ and $c^{\omega}(y)$ can be computed and they are

$$c^{a}(y) = \left(1 - (\delta r^{\gamma})^{\frac{1}{1-\gamma}}\right)_{y}$$

and

$$\begin{cases} c^{\overline{\omega}}(y) \leq y & \text{for } 0 \leq y \leq \overline{\omega} \\ c_{\overline{\omega}}(y) = \left(1 - (\delta r^{\gamma})^{\frac{1}{1-\gamma}}\right) \left(y + \frac{\overline{\omega}}{\gamma - 1}\right) & \text{for } y \geq \overline{\omega} \end{cases}$$

$$\begin{pmatrix} \left(1 - (\delta r^{\gamma})^{\frac{1}{1-\gamma}}\right)_{y \leq c(y) \leq y} & \text{for } 0 \leq y \leq \overline{\omega} \\ \left(1 - (\delta r^{\gamma})^{\frac{1}{1-\gamma}}\right)_{y \leq c(y) \leq (1 - (\delta r^{\gamma})^{\frac{1}{1-\gamma}}) \begin{pmatrix} y + \overline{\omega} \\ y = 1 \end{pmatrix}$$

for $y \ge \overline{\omega}$.

Lemma 4.8.

If the sequence of numbers $\{p_t(y)\}\$ is bounded above then $x(y) = \lim_{t\to\infty} x_t(y)$ satisfies the following relation

(4.12)
$$p_{+}(y) \ge \delta g'(x(y)) E_{p}(g(x(y)) + \omega)$$

where $p(y) = \lim_{t\to\infty} p_t(y)$.

Proof:

From (4.2) we have,

$$P_t(y) \geq \delta g'(x_t(y)) E_{t-1}(g(x_t(y)) + \omega) .$$

But, from Corollary 3.4 $x_t(y) \leq x(y)$, so

(4.13)
$$p_t(y) \ge \delta g'(x(y)) E p_{t-1}(g(x(y)) + \omega)$$

* E. S. Phelps [11] page 741. Now, the left hand side of (4.13) converges, since $\{p_t(y)\}$ is a nondecreasing sequence (Theorem 3.3) bounded above. Hence, taking the limit as $t \rightarrow \infty$ and using the Theorem of monotonic convergence we get (4.12)

Another way to study the limiting policy c(y) is using the relation (4.12). But in order to apply it, we first need to find a bound for $p_t(y)$. In some cases such a bound can be obtained from those of $p_t^a(y)$ since $p_t(y) \leq p_t^a(y)$ for all t. If g'(x) > 1, u(c) is bounded above and below then the following theorem will give us a bound for $p_t(y)$ that does not depend on the computation of $p_t^a(y)$.

Theorem 4.9**

If u(c) is bounded above and below, $g'(x) \ge r > 1$, $\delta = 1$ then

 $p_t^a(y) \leq \frac{M}{y}$

where $M = \frac{r}{r-1} (n - u(0))$, and n is such that $u(c) \leq n$ for all c.

For the remainder of this section we will assume that $p_t(y)$ is bounded in a convenient interval.

Now we are able to obtain an upper bound for c(y) of an "income fluctuation problem." This bound does not depend on the computation of $c^{A}(y)$ and it is also independent of the utility function.

Theorem 4.10.

If g(x) = rx, $\delta r \ge 1$, then the limiting policy satisfies the following inequality

$$c(y) \leq \frac{r-1}{r} y + \frac{A}{r}.$$

** For ~ proof see D. Gale and W. R. Sutherland [6].

^{*} E. C. Titchmarsh [15].

34

Proof:

From (4.12) we have

 $p(y) \geq \delta r E p(r x(y) + \omega)$ $\geq Ep(rx(y) + \omega)$

since $\delta r \ge 1$. Hence,

 $p(y) \ge p(rx(y) + A)$

and

by monotonicity of p(y) .*

 $c(y) \leq \frac{r-1}{r}y + \frac{A}{r}$

A sharper bound can be o in which u'(c) is convex. Theorem 4.11.

If g(x) = rx, $\delta r \ge 1$, and u'(c) is convex then

Proof:

From (4.2) we get

$$(4.14) \qquad p_{t}(y) \geq \delta r E p_{t-1}(r x_{t}(y) + \omega)$$
$$\geq E p_{t-1}(r x_{t}(y) + \omega)$$
$$\geq p_{t-1}(r x_{t}(y) + \overline{\omega})$$

p(y) is the limit of a sequence $\{p_t(y)\}$ of decreasing continuous function and hence nonincreasing.

$$c(y) \leq \frac{r-1}{r} y + \frac{\overline{\omega}}{r}.$$

 $y \leq r(y - c(y)) + A$

by convexity of $p_{t-1}(y)$. Now taking the limit as $t \neq \infty$ we get

 $p(y) \ge p(rx(y) + \overline{\omega})$.

Hence,

$$y \leq r(y - c(y)) + \overline{\omega}$$

by monotonicity of p(y). So,

$$c(y) \leq \frac{r-1}{r} y + \frac{\overline{\omega}}{r} =$$

Now, we will introduce the concept of capital growing as it is defined by S. E. Phelps [11] .

Definition.

If y^t (observe the superscript) is the stock of capital at the beginning of period \underline{t} , when we follow a policy (x(y), c(y)), we will say that capital grows for this policy if $E[y^{t+1}] \ge y^t$.

Theorem 4.12.

If $\delta g'(x) \ge 1$, g'(x) and u'(c) are convex functions then for the limiting policy (x(y), c(y)) the capital grows.

Proof:

From (4.2) we have

(4.15)
$$P_t(y) \ge \delta g'(x_t(y)) E_{t-1}(g(x_t(y)) + \omega)$$

$$\geq Ep_{+-1}(g(x_+(y)) + \omega)$$

since $\delta g'(x) \ge 1$. From (4.15) using the fact that $x_t(y) \le x(y)$, g(x) is increasing and $p_{t-1}(y)$ is decreasing we get

* Theorem 3.6.

36

(4.16)
$$p_t(y) \ge Ep_{t-1}(g(x_t(y)) + \omega)$$

 $\stackrel{\text{\tiny{leg}}}{=} Ep_{t-1}(g(x(y)) + \omega)$

$$\geq P_{t-1}(E(g(x(y)) + \omega))$$

by convexity of $p_{t-1}(y)$. Now, taking the limit as $t \rightarrow \infty$ we get

$$p(y) \ge p(E(g(x(y)) + \omega))$$

and finally from the monotonicity of p(y) it follows that

 $y \leq E(g(x(y)) + \omega) \equiv$

We finish this section with the following example,

Example:

Consider the following "income fluctuation problem"

 $f(x;\omega) = rx + \omega ,$ $u(c) = \log c ,$

and $0 < \delta < 1$. For u(c) = log c , $p_t^a(y)$ can be computed and it is equal to

$$p_t^a(y) = \frac{1 + \delta + ... + \delta^{n-1}}{y}$$
.

Then,

$$p_{t}(y) \leq p_{t}^{a}(y)$$
$$\leq \frac{1}{(1-\delta)y} .$$

So, $p_t(y)$ converges. Now using the convexity of u'(c) and Theorem 4.12 we will get that for the limiting policy (x(y),c(y)) the capital grows whenever $\delta r \ge 1$.^{*} Now, from Corollary 4.2 and Theorem 4.11, it follows that for $\delta r \ge 1$

$$(1 - \delta)y \leq c(y) \leq \frac{r-1}{r}y + \frac{\omega}{r}$$

We should also mention that we could prove using the concept of "competitive policy" that the limiting policy (x(y),c(y)) is also optimal. But this would take us too far from the purpose of this paper.

* This is the result obtained by B. Miller [9] page 19.

5. CASE OF $f(x; \omega) = x + \omega$.

In this section we will consider the "income fluctuation problem" with x = 1 and $\delta = 1$. Now, when the consumer saves an amount x at period <u>t</u>, the available income in the next period is $x + \omega^{t}$, i.e., $f(x;\omega^{t}) = x + \omega^{t}$.

When <u>y</u> is the initial income, the earning ω^1 , ..., ω^t are known with certainty and u(c) is strictly concave, it is known that it is optimal to set the consumption level c₁(y) at

$$c_t(y) = \min\left(y, \frac{\omega^1 + \ldots + \omega^t}{t}\right).$$

If $\frac{\omega^1 + \ldots + \omega^t}{t}$ converges to an average $\overline{\omega}^t$ as $t + \infty$, then the optimal consumption level will converge to min $(y,\overline{\omega})$. In the stochastic case, in which ω^t are i.i.d. random variables, it is natural to expect that $c_t(y)$ will converge to $c(y) = \min(y,\overline{\omega})$, since the expected average income $\frac{\omega^1 + \ldots + \omega^t}{t}$ will converge to $\overline{\omega} = E\omega^t$ by the law of large numbers. In this section we will show that this is not true whenever $u'(0) < \infty$ and $\omega^t \equiv \omega$ are nondegenerate random variable. In fact, we will obtain the surprising result that $0 < c(y) < \overline{\omega}$ for $0 < y < \infty$. M. E. Yaari [16] considers the case r = 1, $\delta = 1$, borrowing is allowed at zero interest rate, no constraints are imposed on $c_t(y) = \overline{\omega}$ for all y.

The range of the random variable $\omega \equiv \omega^{t}$ is an interval [0,A], $0 < A < +\infty$, and if $v(0,\varepsilon) \equiv \operatorname{Prob}[\omega \leq \varepsilon], \varepsilon \geq 0$, it will be assumed that $1 > v(0,\varepsilon) > 0$ for $A > \varepsilon > 0$. We also assume that $u'(0) < +\infty$ and without loss of generality that u(0) = 0.

The functional equations of the Dynamic Programming formulation are now,

(5.1)
$$\begin{cases} V_{t}(y) = \max \{u(c) + EV_{t-1}(x + \omega)\} \\ c+x=y \\ c\geq 0, x\geq 0 \quad \text{for } t > 1 \\ V_{1}(y) = \max \{u(c)\} \\ c+x=y \\ c\geq 0, x\geq 0 \\ , \end{cases}$$

and the optimality conditions are

(5.2)
$$p_t(y) \ge Ep_{t-1}(x_t(y) + \omega)$$

with equality if $x_t(y) > 0$, and

(5.3)
$$p_{*}(y) \ge u'(c_{*}(y))$$

with equality if $c_t(y) > 0$.

Theorem 5.1

The function $V_t(y)$ is differentiable for $y \ge 0$, and for all t. Furthermore $V_t'(0) = u'(0)$.

Proof:

For y > 0 it has been proved in Theorem 2.2. For y = 0 Theorem A2 holds, since $u'(0) < +\infty$, u(0) = 0 and $f'(x;\omega) = 1 = *$

Theorem 5.2.

The policy $c_t(y)$ satisfies the following inequalities

(5.4)
$$\frac{y}{t} \leq c_t(y) \leq \frac{y}{t} + \frac{t-1}{t} \wedge \text{ for all } t.$$

Moreover if u'(c) is convex then

(5.5)
$$\frac{y}{t} \leq c_t(y) \leq \frac{y}{t} + \frac{t-1}{t} \quad \text{for all } t.$$

* Hence the problem is admissible.

From Theorem 4.1 and Theorem 4.3 we have without any assumption about u'(c) that

$$c_t^{A}(y) \leq c_t(y) \leq c_t^{A}(y)$$
 for all t.

But, it is known that $c_t^{a}(y) = \frac{y}{t}$ and $c_t^{A}(y) = \min\left(y, \frac{y}{t} + \frac{t-1}{t}A\right)$. So, (5.4) holds. Now, for u'(c) convex, using Theorem 4.5 we get

$$c_t(y) \leq c_t^{\overline{w}}(y)$$
 for all t.

Hence,

$$c_t(y) \leq \frac{y}{t} + \frac{t-1}{t} \overline{\omega}$$

since it is known that $c_t(y) = \min\left(y, \frac{y}{t} + \frac{t-1}{t}\overline{\omega}\right)$. So, (5.5) holds =

Now we will obtain the surprising fact that c(y) is uniformly bounded.

Corollary 5.3.

The limiting policy c(y) satisfies the following inequalities

 $0 \leq c(y) \leq A$.

Moreover if u'(c) is convex then

$$0 \leq c(y) \leq \omega$$
.

Proof:

It follows immediately from Theorem 5.2 by taking limits as $t \neq \infty$ in (5.4) and (5.5)

Lemma 5.4.

The sequence of functions $\{p_t(y)\}$ converges uniformly in any finite and

Proof:

It converges pointwise, since

$$p_t(y) \ge p_{t-1}(y)$$

and

 $p_{t}(y) = V_{t}'(y)$ $\leq V_{t}'(0)$ = u'(0)

by concavity and Theorem 5.1. Now, from the fact that $c_t(y) \ge \frac{y}{t} > 0$ for y > 0 (Theorem 5.2), and the optimality condition (5.3) we have that

$$p_t(y) = u'(c_t(y))$$
 for all y.

Taking the limit and using the fact that u'(c) is a continuous function and $c_t(y)$ converges by Theorem 3.5, we will have that

$$p(y) = u'(c(y))$$
.

So, p(y) is continuous, since c(y) is continuous from Theorem 3.5. Now, the theorem follows from the fact that $\{p_t(y)\}$ is a sequence of monotonic functions converging pointwise to a continuous function, consequently it converges uniformly in any finite closed interval **B**

Lemma 5.5.

The limiting policy (x(y),c(y)) satisfies the following relations (5.6) p(y) = u'(c(y)) 42

$$(5.7) p(y) \ge Ep(x(y) + \omega)$$

with equality if x(y) > 0.

Proof:

From the Optimality conditions (5.3) and (5.2) we get

 $p_t(y) = u'(c_t(y))$

since $c_t(y) > 0$ for y > 0 and $p_t(0) = u'(0)$, and

$$p_{+}(y) \geq Ep_{+-1}(x_{+}(y) + \omega)$$

with equality if $x_t(y) > 0$. Now, taking the limit and using the fact that $\{p_t(y)\}$ converges uniformly in any finite closed interval we get (5.6) and (5.7) =

Lemma 5.6.

If c(y) = 0 for some y > 0 then $c(y) \equiv 0$.

Proof:

Let $\overline{y} = \sup \{y \mid c(y) = 0\}^{\ddagger}$. If $\overline{y} = +\infty$ we have done. Now suppose that $\overline{y} < +\infty$. Then,

$$p(y) = Ep(y + \omega)$$

and

$$p(\overline{y}) = u'(c(\overline{y}))$$

= u'(0) .

The supremum is actually achieved from the continuity of c(y) .

Now, for $\omega > 0$, $c(\bar{y} + \omega) > 0$ and $p(\bar{y} + \omega) < u'(0)$. Let ε be any number such that $0 < \varepsilon < \Lambda$. Then

$$p(\bar{y}) = Ep(\bar{y} + \omega)$$

$$= \int_{0}^{\varepsilon} p(\bar{y} + \omega)v(d\omega) + \int_{\varepsilon}^{A} p(\bar{y} + \omega)v(d\omega)$$

$$\leq u'(0)v(0,\varepsilon) + p(\bar{y} + \varepsilon)(1 - v(0,\varepsilon))$$

$$< u'(0)v(0,\varepsilon) + u'(0)(1 - v(0,\varepsilon))$$

$$< u'(0)$$

which is a contradiction D

Theorem 5.7.

If c(y) > 0 for y > 0 then p(y) is strictly decreasing.

Proof:

By contradiction suppose not, i.e., there exits $y' > y \ge 0$ such that

(5.8) $p(y') = p(y) = \overline{p}$.

Let,

 $\overline{y} = \min \{y \mid p(y) = \overline{p}, 0 \leq y \leq y'\}.$

Now, $\overline{y} > 0$ since c(y') > 0 and

$$p(\bar{y}) = p(y')$$
.
= u'(c(y'))
< u'(0)

44

Hence

(5.9)
$$p(y) > p(\bar{y})$$
 for $y < \bar{y}$.

From (5.2) we have that

(5.10)
$$p(\bar{y}) \ge Ep(x(\bar{y}) + \omega)$$

and

(5.11)
$$p(y') = Ep(x(y') + \omega)$$
.

Hence, from (5.8), (5.10) and (5.11) we have that

 $Ep(x(y') + \omega) \ge Ep(x(\overline{y}) + \omega)$.

So,

(5.12)
$$E[p(x(y') + \omega) - p(x(\overline{y}) + \omega)] \ge 0$$
.

But

(5.13)
$$E[p(x(y') + \omega) - p(x(\bar{y}) + \omega)] \leq 0$$

since $x(y') > x(\overline{y})$ and p(y) is nondecreasing. From (5.12) and (5.13) we have

$$E[p(\mathbf{x}(\mathbf{y}') + \boldsymbol{\omega}) - p(\mathbf{x}(\overline{\mathbf{y}}) + \boldsymbol{\omega})] = 0 .$$

Hence,

(5.14)
$$p(x(y') + \omega) = p(x(y) + \omega)$$
 for $\omega = 0$.

since $\psi(\omega) \equiv p(x(y') + \omega) - p(x(\overline{y}) + \omega)$ is nonpositive, continuous and $v(0,\omega) > 0$ for $\omega > 0$. From the fact that $p(\overline{y}) = p(y')$ it follows that

(5.15)
$$x(y') = x(\bar{y}) + y' - \bar{y}$$

Thus from (5.15) and (5.14) we have

$$p(x(\overline{y})) = p(x(\overline{y}) + y' - \overline{y}),$$

and consequently for $y \in [x(\overline{y}), x(\overline{y}) + y' - \overline{y}]$ we have

 $p(y) = p(x(\overline{y}))$.

If $x(\overline{y}) = 0$, then c(y) = 0 for $y \in [x(\overline{y}), x(\overline{y}) + y' - \overline{y}]$ which contradicts the fact that c(y) > 0 for y > 0. For $x(\overline{y}) > 0$ consider the following cases:

Case 1.

 $x(\bar{y}) + y' - \bar{y} \ge \bar{y}$. Then it follows that $p(x(\bar{y})) = p(\bar{y})^*$ which contradicts (5.9) since $x(\bar{y}) < \bar{y}$.

Case ii.

 $x(y) + y' - \overline{y} < \overline{y}$. Now repeat the proof starting with the new interval $[x(\overline{y}), x(\overline{y}) + y' - \overline{y}]$ and computing the new

$$y = \min \{y \mid p(y) = p(x(\bar{y})), y \ge 0, y \le x(\bar{y})\}$$

The repetition of Case ii will generate a sequence of intervals which are nonoverlapping, have nondecreasing lengths and are all contained in the interval [0,y']. So, Case ii can be repeated only a finite number of times **•**

Now we will show that
$$\lim_{T\to\infty} \frac{V_T(y)}{T} = u(\bar{\omega})$$
.

Lemma 5.8.

$$\lim_{\substack{T \to \infty}} \frac{V_T(y)}{T} \ge u(\bar{\omega}) , \text{ where } \bar{\omega} = E\omega . **$$

* $\overline{y} \in [x(\overline{y}), x(\overline{y}) + y' - \overline{y}]$ and hence $p(x(\overline{y})) = p(\overline{y})$. **This proof is similar to the one given in M. E. Yaari [16]. Proof:

It suffices to show that $\lim_{T\to\infty} \frac{V_T(0)}{T} \ge u(\bar{\omega})$, since $V_T(y) \ge V_T(0)$. For

 $V_{T}(0)$, consider the policy $c_{t}(y) = \min(y, \overline{w})$ for all $1 \le t \le T$. If y^{t} (observe the superscript) is the stock level at the beginning of period t when we follow the policy $c_{t}(y) = \min(y, \overline{w})$, then

$$y^{t} = \max(y^{t-1} + z^{t}, 0)$$
 $t \ge 2$
 $y^{1} = 0$.

Where $z^{t} = \omega - \overline{\omega}$, and hence $Ez^{t} = 0$.

When $y^k = 0$, we have at the k^{th} period (trial)^{*} a renewal point, since at this point the process will start all over again. If N(T) is the number of renewals in T periods, then the expected return from the policy $c_t(y) =$ min $(y,\bar{\omega})$ for a T period problem is greater or equal to $u(\bar{\omega})(T - E(N(T)) - 1)$. Hence

$$V_{T}(0) \geq u(\overline{\omega})(T - E(N(U)) - 1)$$

Thus to show that

$$\lim_{T\to\infty}\frac{V_{T}(0)}{T} \ge u(\bar{\omega})$$

it suffices to show that

$$\lim_{T\to\infty}\frac{EN(U)}{T}=0.$$

Let τ_i be the number of Trials between the ith and $(i-1)^{th}$ renewals. From the Renewal Theory we have

$$\lim_{T\to\infty}\frac{EN(T)}{T} = \frac{1}{E\tau_1} \quad \text{if } E\tau_1 < \infty$$

* Trial is the usual terminology in Renewal Theory.

and

$$\lim_{T\to\infty}\frac{EN(T)}{T}=0 \quad \text{if } E\tau_1=\infty.$$

But, from the Random Walk Theory it can be shown that $E\tau_1 = \infty$ if $Ez^t = 0$.** So, the lemma holds

Lemna 5.9.

$$\lim_{T\to\infty}\frac{V_T(y)}{T} \leq u(\tilde{\omega}) .$$

Proof:

It suffices to show that

$$V_{T}(y) \leq Tu\left(\frac{y}{T} + \frac{(T-1)}{T}\tilde{\omega}\right).$$

It is true for T = 1, since $V_1(y) \leq u(y)$. Assume it is true for t, i.e.,

(5.16)
$$V_{T}(y) \leq tu\left(\frac{y}{t} + \frac{t-1}{t}\overline{\omega}\right)$$
 for all y.

Now,

(5.17)
$$V_{t+1}(y) = u(c_t(y)) + EV_t(x_t(y) + \omega)$$
$$\leq u(c_t(y)) + V_t(x_t(y) + \widetilde{\omega})$$

by concavity of $V_t(y)$. Thus, from (5.16) and (5.17) we get

$$(5.18) \quad V_{t+1}(y) \leq u(c_t(y)) + tu\left(\frac{1}{t}(x_t(y) + \overline{\omega}) + \frac{t-1}{t}\overline{\omega}\right)$$
$$= (t+1)\left(\frac{1}{t+1}u(c_t(y)) + \frac{t}{t+1}u\left(\frac{1}{t}(x_t(y) + t\overline{\omega})\right)$$
$$(t+1)u\left(\frac{1}{t+1}(y + t\overline{\omega})\right)$$

* For a proof see S. Ross [13].

** See W. Feller [3] page 397.

by concavity of u(c)

From the previous two lemmas we can state the following Theorem.

Theorem 5.10.

 $\lim_{T\to\infty} \frac{V_T(y)}{T} = u(\bar{\omega}) \quad \text{for all } y .$

The sequence $V_t(y)$ diverges as $t \to \infty$. In order to study the behavior of the limiting policy c(y) we will define a special function, $h_t(y)$, that has the same properties of $V_t(y)$, but which sequence converges.

Definition.

Let $h_t(y) \equiv V_t(y) - V_t(0)$. Using the fact that

> $V_t(0) = u(0) + EV_{t-1}(\omega)$. = $EV_{t-1}(\omega)$,

since by assumption u(0) = 0, it can be shown that the function $h_t(y)$ satisfies the following relations

$$h_t(y) + V_t(0) - V_{t-1}(0) = \max_{\substack{c+x=y \\ c \ge 0, x \ge 0}} \{u(c) + Eh_{t-1}(x + \omega)\}$$

(5.19)

 $h_1(y) = V_1(y) = \max_{\substack{c+x=y\\c=0,x\geq0}} \{u(c)\}$

and

(5.20)
$$V_t(y) = h_t(y) + E \sum_{k=1}^{t-1} h_k(\omega)$$
.

Theorem 5.11.

The function h_t(y) is strictly concave, increasing and differentiable

for all t . Furthermore

$$h_{t}'(y) = p_{t}(y)$$

and if $(x_t(y),c_t(y))$ is the solution of (5.1), it is also the solution of (5.19).

Proof:

It is an immediate consequence of the fact that $h_t(y)$ and $V_t(y)$ differ by a constant.

Now, we will state without proof the following lemma (for a proof see W. Rudin [14]).

Lemma 5.12.

Suppose $\{f_n\}$ is a sequence of functions, differentiable on [a,b] and such that $\{f_n(x_0)\}$ converges for some x_0 on [a,b]. If the sequence of derivatives $\{f_n'\}$ converges uniformly on [a,b], then $\{f_n\}$ converges uniformly on [a,b] to a function f and

 $f'(x) = \lim_{n \to \infty} f'(x) \qquad a \leq x \leq b$.

Theorem 5.13.

The sequence of functions $h_t(y)$ converges uniformly in any finite interval [0,b]. Furthermore if $h(y) = \lim_{t \to \infty} h_t(y)$, then

$$h'(y) = \lim_{t\to\infty} h_t(y) = p(y)$$

Proof:

I. $h_t(0) = 0$ for all t. Hence

 $\lim_{t\to\infty} h_t(0) = 0$

II. $h_t(y)$ is differentiable for all t, $y \ge 0$.

III. $h'_t(y) = p_t(y)$ converges uniformly on any finite interval [0,b] by Lemma 5.4.

Hence, the theorem follows from the previous lemma

It is an immediate consequence the following corollary.

Corollary 5.14.

 $\lim_{t\to\infty} \operatorname{Eh}_t(\omega) = \operatorname{Eh}(\omega) .$

Lemma 5.15.

$$Eh(\omega) = u(\overline{\omega})$$
.

Proof:

From (5.20) we have

$$V_t(y) = h_t(y) + \sum_{k=1}^{t-1} Eh_k(\omega)$$
.

Now, dividing by t, and taking the limit we get

 $u(\bar{\omega}) = Eh(\omega)$.

Where we have used the following facts:

I.
$$\lim_{t \to \infty} \frac{V_{t}(y)}{t} = u(\bar{\omega}) \text{ from Theorem 5.10.}$$

$$\lim_{t \to \infty} \frac{t-1}{\sum_{k=1}^{\infty} Eh_{k}(\omega)}{t} = Eh(\omega) \text{ from corollary 5.14.}$$

III.
$$\lim_{t\to\infty} \frac{h_t(y)}{t} = 0$$
, since $h_t(y)$ is uniformly bounded in any finite

51

interval

Lemma 5.16.

$$\lim_{t\to\infty} V_t(0) - V_{t-1}(0) = u(\bar{\omega})$$

Proof:

From the definitions of $V_t(0)$, $V_{t-1}(0)$ and $h_{t-1}(y)$ we have,

$$V_t(0) - V_{t-1}(0) = u(0) + EV_{t-1}(\omega) - V_{t-1}(0)$$

= $Eh_{t-1}(\omega)$.

Now, taking the limit and using Corollary 5.14, Lemma 5.16, we get that

 $\lim_{t\to\infty} V_t(0) - V_{t-1}(0) = u(\bar{\omega}) =$

Lemma 5.17

 $h(y) + u(\overline{\omega}) = u(c(y)) + Eh(x(y) + \omega)$.

Proof:

From (5.19) we have

 $h_t(y) + V_t(0) - V_{t-1}(0) = u(c_t(y)) + Eh_{t-1}(x_t(y) + \omega)$.

Now, taking the limit, using Lemma 5.16 and the uniform convergence of $h_t(y)$ in any finite interval we get

$$h(y) + u(\omega) = u(c(y)) + Eh(x(y) + \omega) =$$

Theorem 5.18.

The limiting policy c(y) is always positive for y > 0.

Proof:

By contradiction suppose not, i.e., c(y) = 0 for some y > 0. Hence, from Lemma 5.6 $c(y) \equiv 0$. Now, from Lemma 5.15 we have

(5.21)
$$u(\tilde{\omega}) = Eh(\omega)$$

But

$$p(y) = u'(0)$$
 for all y,

since $c(y) \equiv 0$. Hence,

(5.22) h(y) = u'(0)y.

Finally, from (5.21) and (5.22) we get

 $u(\bar{\omega}) = u'(o)\bar{\omega}$.

Which is a contradiction, since u(c) is strictly concave

Lemma 5.19.

The function h(y) is strictly concave.

Proof:

From Theorem 5.18 c(y) > 0 for y > 0, hence from Theorem 5.7 p(y) = h'(y)is strictly decreasing and consequently h(y) is strictly concave B

Now, we are able to show the surprising fact that $c(y) < \overline{\omega}$ for $0 < y < +\infty$.

Theorem 5.20.

The limiting policy satisfies the following inequalities

 $0 < c(y) < \overline{\omega}$ for 0 < y < +-.

From Lemma 5.17 we have

$$h(y) + u(\omega) = u(c(y)) + Eh(x(y) + \omega)$$

Now, suppose by contradiction that for some $y < +\infty$, $c(y) = \overline{\omega}$. Hence

 $h(y) + u(\overline{\omega}) = u(\overline{\omega}) + Eh(y - \overline{\omega} + \omega)$.

Thus,

$$h(y) = Eh(y - \omega + \omega)$$

< h(y)

by strictly concavity of h(y). Which is a contradiction \blacksquare

Theorem 5.21.

 $\lim_{y \to \infty} c(y) = \overline{\omega}$

Proof:

Suppose not, i.e., $\lim_{y \to \infty} c(y) = \delta < \overline{\omega}$. Hence $\lim_{y \to \infty} h'(y) = \lim_{y \to \infty} u'(c(y)) = u'(\delta)$.

From Lemma 5.17 we have

(5.23)
$$u(\omega) - u(c(y)) = Eh(y - c(y) + \omega) - h(y)$$

Now, from the mean value theorem we get

(5.24)
$$h(y - c(y) + \omega) - h(y) = h'(y(y))(\omega - c(y))$$

where $y_{\omega}(y) \in [y - c(y) + \omega, y]$ if $c(y) \ge \omega$ and $y_{\omega}(y) \in [y, y - c(y) + \omega]$

if $c(y) \ge \omega$. Replacing (5.24) in (5.23) we get

$$u(\overline{\omega}) - u(c(y)) = Eh'(y_{\omega}(y))(\omega - c(y)) .$$

Now, taking the limit a: $y + \infty$ and using the fact that $y_{ij}(y) + \infty$ when $y + \infty^{*}$ we get

$$u(\omega) - u(\delta) = Eu'(\delta)(\omega - \delta)$$

$$= u'(\delta)(\omega - \delta)$$

which is a contradiction since u(c) is strictly concave and $\overline{\omega} < \delta$.

Now we will obtain some properties of the capital y^t accumulated in t periods.

Theorem.

Proof:

It suffices to show that y^{t} converges almost surely, since either $\{y^{t}\}$ does not converge or it converges almost surely to $+\infty$. From the optimality condition (5.7) we have that

(5.25)
$$p(y^{t}) \ge E[p(y^{t+1}) | y^{t}]$$

Now if we define $p^{t} \equiv p(y^{t})$ we will have from (5.25) that

(5.26)
$$p^{t} \ge E[p^{t+1} | p^{t}]$$

where we have used the fact that p(y) is a strictly decreasing function and hence, for a given p^t , y^t is uniquely defined. From (5.26) we have that $\{p^t\}$ is a positive Supermartingale and hence it converges almost surely to a random variable \overline{p} . Since p(y) is a continuous strictly decreasing function it is possible to define a continuous function g(p) such that

 $-\omega < -c(y) + \omega < A$ since $0 < c(y) < \omega$ and $\omega < A$. ** I am in debt to Professor R. Radner for insisting on this point.

 $y^t = g(p^t)$.

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Without loss of generality we will assume that u(0) = 0 whenever $u'(0) < +\infty$.

Lemma A.1.

If $u'(0) < +\infty$ and $1 \leq \rho \leq +\infty$ then

(A.1) $V_t(y) - V_t(0) \leq tu\left(\frac{\rho t}{t}\right)$.

Where ρ is the sup {f'(o; ω)}.

Proof:

The proof will be done by induction.

I. For t = 1 we have

 $V_1(y) = u(y)$.

Hence,

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V_1(y) \leq u(\rho y),
```

since u(c) is increasing, and $\rho \ge 1$.

II. Assume that it is true for t - 1, i.e.,

$$v_{t-1}(y) - v_{t-1}(0) \leq (t-1)u\left(\frac{p^{t-1}y}{t-1}\right)$$

Now,

(A.2)
$$V_t(y) - V_t(0) - u(c_t(y)) + \delta EV_{t-1}(f(x_t(y);\omega)) - \delta EV_{t-1}(f(o;\omega))$$

Also,

(A.3)
$$f(x_t(y);\omega) \leq f(0;\omega) + \rho x_t(y)$$
 for all ω .

From (A.2) and (A.3), and using the fact that $V_t(y)$ is nondecreasing we get

(A.4)
$$V_t(y) - V_t(0) \leq u(c_t(y)) + \delta E V_{t-1}(f(0;\omega) + \rho x_t(y)) - \delta E V_{t-1}(f(0;\omega))$$

$$\leq u(c_t(y)) + \delta (V_{t-1}(\rho x_t(y)) - V_{t-1}(0)) .$$

Hence,

$$V_{t}(y) - V_{t}(0) \leq u(c_{t}(y)) + (t - 1)u\left(\frac{\rho^{t-1}x_{t}(y)}{t-1}\right)$$

by the induction hypothesis. So,

$$\begin{array}{l} \mathbb{V}_{t}(\mathbf{y}) - \mathbb{V}_{t}(\mathbf{0}) \leq t \left[\left(\frac{1}{t} u(\mathbf{c}_{t}(\mathbf{y}) \right) + \frac{t-1}{t} u\left(\frac{\rho^{t-1} \mathbf{x}_{t}(\mathbf{y})}{t-1} \right) \right] \\ \\ \leq t u \left(\frac{1}{t} \mathbf{c}_{t}(\mathbf{y}) + \frac{\rho^{t}}{t} \mathbf{x}_{t}(\mathbf{y}) \right) \end{array}$$

by concavity. Hence,

$$V_{t}(y) - V_{t}(0) \leq tu\left(\frac{\rho^{t}}{t} (c_{t}(y) + x_{t}(y))\right)$$
$$= tu\left(\frac{\rho^{t}}{t} y\right). \blacksquare$$

Theorem A.1.

If $u^{\dagger}(0) < +\infty$ and $1 \leq \rho \leq +\infty$ then

$$V_t'(0) \leq \rho^t u'(0) .$$

Proof:

Dividing (A.1) by y > 0 we have

$$\frac{v_t(y) - v_t(0)}{y} \leq \frac{t}{y} u\left(\frac{\rho t}{t} y\right).$$

Now, taking the limit as $y \rightarrow 0+$ we get

Lemma A.2.

If $u'(0) < +\infty$ and $\rho \leq 1$ then

(A.5)
$$V_{t}(y) - V_{t}(0) \leq tu\left(\frac{y}{t}\right).$$

Proof:

For t = 1 we have

 $V_1(y) = u(y)$.

Hence,

 $V_1(y) \leq u(y)$.

Assume that it is true for t - 1, i.e.,

$$V_{t-1}(y) = V_{t-1}(0) \leq (t-1)u(\frac{y}{t-1})$$
.

Now, (A.4) still holds, hence

(A.6)

$$V_{t}(y) - V_{t}(0) \leq u(c_{t}(y)) + \delta(V_{t-1}(\rho x_{t}(y)) - V_{t-1}(0))$$
$$\leq u(c_{t}(y) + (V_{t-1}(x_{t}(y)) - V_{t-1}(0)) .$$

Where the last inequality follows from the fact that $V_{t-1}(y)$ is increasing and $\rho \leq 1$.

From (A.6) using the induction hypothesis we get

Theorem A.2.

If $u'(0) < \infty$ and $\rho \leq 1$ then

 $V_t^*(0) = u^*(0)$.

Proof:

First we have immediately that

(A.7)
$$V_{+}(y) - V_{+}(0) \ge u(y)$$
.

Then, from (A.5) and (A.7) we get

$$u(y) \leq V_t(y) - V_t(0) \leq tu\left(\frac{1}{t}y\right)$$
.

Dividing by y > 0 we have

$$\frac{u(y)}{y} \leq \frac{v_t(y) - v_t(0)}{y} \leq \frac{t}{y} u\left(\frac{1}{y} y\right).$$

Now, taking the limit as $y \neq 0^+$ we finally get

$$V'_t(0) = u'(0) =$$