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REPRESENTATIONS OF THE LORENTZ GROUP: RECENT DEVELOPMENTS

MOSHE CARMELI GENERAL PHYSICS RESEARCH LABORATORY

SHIMON MALIN COLGATE UNIVERSITY HAMILTON, NEW YORK

PROJECT NO. 7114

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REPRESENTATIONS OF THE LORENTZ GROUP: RECENT DEVELOPMENTS

MOSHE CARMELI GENERAL PHYSICS RESEARCH LABORATORY AEROSPACE RESEARCH LABORATORIES

AND

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FOREWORD

This Technical Report presents results of research carried out by Professor S. Malin, Colgate University, and Dr. M. Carmeli, General Physics Research Laboratory, Aerospace Research Laboratories. Dr. Carmeli's work was accomplished on Project No. 7114.

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ABSTRACT

Recent developments in the theory of representations of the Lorentz group, in which all infinite-dimensional representations of the group were expressed in spinor-like forms, are reviewed.

TABLE OF CONTENTS

SECTION		PAGE
1.	INTRODUCTION	1
2.	THE INFINISTESIMAL APPROACH	4
3.	SPINOR REPRESENTATION OF THE LORENTZ GROUP	10
4.	PRINCIPAL SERIES OF REPRESENTATIONS OF SL(2, C)	15
5.	COMPLEMENTARY SERIES OF REPRESENTATIONS OF SL (2, C)	26
6.	COMPLETE SERIES OF REPRESENTATIONS OF SL(2, C)	35
	ACKNOWLEDGEMENTS AND CONCLUDING REMARKS	50
	FOOTNOTES	51
	REFERENCES	59
	LIST OF SYMBOLS	66

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1. INTRODUCTION

Infinite-dimensional representations of noncompact Lie groups are currently of interest and are being studied in describing the physics of elementary particles.¹ Of particular importance in this class of groups is SL(2, C), the group of all 2x2 complex matrices with determinant unity. This is the covering group of the restricted Lorentz group describing homogeneous Lorentz transformations that are orthochroneous and proper.² This group plays an important role in relativistic quantum mechanics, quantum field theory, S-matrix theory and axiomatic field theory.

The theory of representations of the Lorentz group is of particular interest in connection with recent developments utilizing infinitecomponent wave equations to describe particle properties. This approach was originally attempted by Majorana (1932), who suggested an infinitedimensional wave equation whose form is analogous to Dirac's spinor equation. It turns out, however, that Majorana's equation generates an unphysical mass specturm. The theory of infinite-component wave equations, which are generalizations of Dirac's equation, was subsequently developed by Gel'fand and Iaglom (1948).

Recently, Nambu, Barut, Fronsdal, and others³ developed more complex types of equations based on the Lorentz group and showed how to describe particle properties within this framework. Barut and his co-workers, in particular Kleinert and Conigan, have also developed an approach

in which particle properties (mass spectrum, magnetic moments, form factors, etc.) are directly expressed in terms of operators in a given infinite-dimensional representation, without using wave equations.

Various aspects of the theory of infinite-component c-number wave-functions and wave equations were also investigated by Bohm (1967, 1968), Lam (1968), Miyazaki (1968a, b), Takabayashi (1967) and many others.⁴ The relationship between Regge's theory and Lorentz invariance was investigated, and equations which reproduce Regge mass spectra were proposed.² The problem of second quantization of such theories, which raised some deep difficulties, were extensively investigated (Grodsky and Streater 1958; Abers, Grodsky, and Norton 1967; Feldmann and Matthews 1967a, b; Fronsdal 1967c; Cksak and Todorov 1969, 1970; Miyazaki 1970b, c). The relationship between infinite-dimensional wave-functions and the foundations of quantum mechanics was investigated by Barut and Malin (1968a, b, 1971). Infinite-dimensional representations were used in relation to the problem of representing the algebra of current density (Dashen and Gell-Mann 1966; Bebie and Lentwyler 1967; Lentwyler 1968; Cell-Mann, Horn and Weyers 1967; Barut and Komen 1970; Hamprect and Kleinert 1969; Kleinert, Corrigan, and Hamprect 1970; Cocho, Fronsdal, and White 1969; Fronsdal and Harun-Ar Rashid 1969; Chang, Dashen, and O'Raifeartaigh 1969a, b; Katz and Noga 1970). The applications of infinite-dimensional representations of the Lorentz group to particle physics were recently reviewed by Hiyazaki (1970b).⁶ All these problems are very complex both physically and mathematically.

As far as the mathematical theory of representations of the Lorentz group is concerned, there are estentially two approaches: (1) the infinitesimal approach, in which one finds the matrices corresponding to infinitesimal generators in a given representation and expresses matrices corresponding to finite group elements as exponential functions of the generators (Bargaann 1947); and (2) the global approach, in which the representations are realized as operators defined over an abstract space of functions (Gel*fand and Naimark 1946, 1947).

Recently, the authors (Carmeli 1970; Carmeli and Malin 1971, 1972) introduced a generalized Fourier transformation which enabled them to use the global approach for expressing infinite-dimensional representations in terms of matrices, generalizing the spinor⁷ form of finite-dimensional representation to the infinite-dimensional case. While the usual spinor representations are non-unitary, this new form describes both unitary and non-unitary representations.

The purpose of the present review is to summarize these recent developments in the theory of representations of the Lorentz group.

Sections 2 and 3 include reviews of the infinitesimal approach and of the finite-dimensional representations of the group SL(2, C). The content of these sections is well known, but is given here for completeness and to establish the notation. The principal, complementary, and complete series of representations are then discussed in Sections 4, 5, and 6, respectively.

Throughout the paper we adopt the now standardized notation and terminology of Naimark (1954).

2. THE INFINITESIMAL APPROACH

A. Infinitesimal Lorentz Matrices

A linear transformation g of the variables x_1 , x_2 , x_3 and x_4 which leaves the form $x_1^2 + x_2^2 + x_3^2 - x_4^2$ invariant is called a <u>Lorentz trans</u>formation. The aggregate of all such linear transformations g provides a group which is called the <u>Lorentz group</u>. If $g_{ij4} \ge 1$, the transformation is called <u>orthochroneous</u>. The aggregate of all orthochroneous Lorentz transformations provides a subgroup of the Lorentz group. The determinant of every Lorentz transformation is equal to either +1, in which case the transformation is called proper, or to -1, in which case it is called <u>improper</u>. The aggregate of all proper, or to -1, in which case it is called <u>improper</u>. The aggregate of all proper, or the Lorentz group.⁸ <u>Throughout this paper we</u> will be concerned with the group of all proper orthochroneous Lorentz transformations. This group is denoted by L.

Rotations $a_1(\Psi)$, $a_2(\Psi)$, $a_3(\Psi)$ and Lorentz transformations $b_1(\Psi)$, $b_2(\Psi)$, $b_3(\Psi)$, around and along $0x_1$, $0x_2$, $0x_3$ can then be written explicitly.⁹ The infinitesimal matrices a_r and b_r of the group L are defined by¹⁰ $a_r = \left[\frac{da_r(\Psi)}{d\Psi}\right]_{\Psi} = 0$, $b_r = \left[\frac{db_r(\Psi)}{d\Psi}\right]_{\Psi} = 0$ (2.1)

and satisfy the commutation relations

$$\begin{bmatrix} a_{i}, a_{j} \end{bmatrix} = \epsilon_{ijk} a_{k}$$

$$\begin{bmatrix} b_{i}, b_{j} \end{bmatrix} = \epsilon_{ijk} a_{k}$$

$$\begin{bmatrix} a_{i}, b_{j} \end{bmatrix} = \epsilon_{ijk} b_{k}.$$
(2.2)

B. Infinitesimal Operators

We denote an arbitrary linear representation of the group L in a Banach space B by $g \rightarrow T_g$ and for convinience we put¹¹

$$A_{r}(\Psi) = T_{a_{r}}(\Psi), \quad B_{r}(\Psi) = T_{b_{r}}(\Psi).$$
 (2.3)

The basic infinitesimal operators of the one-parameter groups $A_r(\Psi)$ and $B_r(\Psi)$ are then defined by ¹²

$$A_{\mathbf{r}} = \begin{bmatrix} \frac{dA_{\mathbf{r}}(\Psi)}{d\Psi} \end{bmatrix}_{\Psi}, \qquad B_{\mathbf{r}} = \begin{bmatrix} \frac{dB_{\mathbf{r}}(\Psi)}{d\Psi} \end{bmatrix}_{\Psi}, \qquad (2.4)$$

if the representation is finite-dimensional. If the representation $g \to T_g$ is infinite-dimensional, however, the operator functions $A_r(\Psi)$ and $B_r(\Psi)$ might be non-differentiable, but there may still exist a vector x for which $A_r(\Psi)x$ and $B_r(\Psi)x$ are differentiable vector-functions.¹³

A representation $g \to T_g$ of the group L is completely determined by its infinitesimal operators A_i and B_i , i = 1, 2, 3. The determination of the irreducible representations of the group L is based on the fact that the basic infinitesimal operators of a representation satisfy the same commutation relations that exists among the infinitesimal matrices a_r and b_r :

(2.5)

(2.6)

$$\begin{bmatrix} A_{i}, A_{j} \end{bmatrix} = \epsilon_{ijk} A_{k},$$
$$\begin{bmatrix} B_{i}, B_{j} \end{bmatrix} = -\epsilon_{ijk} A_{k},$$
$$\begin{bmatrix} A_{i}, B_{j} \end{bmatrix} = \epsilon_{ijk} B_{k}.$$

Defining now the operators

$$H_{\mp} = iA \pm A_2, H_3 = iA_3$$

 $F_{\mp} = iB_1 \pm B_2, F_3 = iB_3,$

one finds

$$\begin{bmatrix} H_{\mp} , H_{3} \end{bmatrix} = \pm H_{\mp} , \begin{bmatrix} H_{+} , H_{-} \end{bmatrix} = 2H_{3}$$

$$\begin{bmatrix} F_{\mp} , F_{3} \end{bmatrix} = \mp H_{\mp} , \begin{bmatrix} F_{+} , F_{-} \end{bmatrix} = -2H_{3}$$

$$\begin{bmatrix} H_{\pm} , F_{\pm} \end{bmatrix} = 0, \begin{bmatrix} H_{3} , F_{3} \end{bmatrix} = 0, \begin{bmatrix} H_{\pm} , F_{\mp} \end{bmatrix} = \pm 2F_{3}$$

$$\begin{bmatrix} H_{\pm} , F_{3} \end{bmatrix} = \mp F_{\pm} , \begin{bmatrix} F_{\pm} , H_{3} \end{bmatrix} = \mp F_{\pm} .$$

$$(2.7)$$

The problem then reduces to the determination of H_{\pm} , H_3 , F_{\pm} , F_3 satisfying the conditions (2.7).

Now, since the three-dimensional pure rotation group 0_3 is a subgroup of the proper, orthochroneous Lorentz group L, obviously every representation of L is also a representation of 0_3 . Clearly, if a given representation of L is irreducible it need not be irreducible when considered as a representation of 0_3 . In fact, any infinite representation of L, when regarded as a representation of 0_3 , is highly reducible; it is equivalent to a direct sum of an infinite number of irreducible representations. The space R of any irreducible representation of the group L is, therefore, a closed direct sum of subspaces M^j , where M^j is the (2j+1)-dimensional space in which the irreducible representation of weight j of the group 0_3 is realized.

Following the standard convention, one chooses the 2j+1 normalized eigenvectors of the operator H₃ as the canonical basis for the subspace M^j. Let these base vectors be denoted as f_m^j , where m = -j, -j+1, ..., j, the superscript jindicates the subspace to which f_m^j belongs, 1^{j} and the subscript is the eigenvalue of the operator H₃. A detailed investigation of the commutation relations (2.7) in terms of the canonical basis f_m^j leads to the following conclusions:

(a) Each irroducible representation of the group L is characterized by a pair of numbers (j_0, c) , where j_0 is integral or half-integral, and c is a complex number.

(b) The space R (j_0, c) of any given irreducible infinite-dimensional representation of the group L is characterized by the integer or half-integer j_0 such that $R(j_0, c) = M^{j_0} \oplus M^{j_0} \oplus \cdots$. The whole space $R(j_0, c)$ is spanned, therefore, by the set of base-vectors f_m^j , where $j = j_0, j_0+1, j_0+2,$..., and $m = -j, j+1, \ldots, j$. If the given irreducible representation is finite-dimensional than the direct sum of the subspaces M's terminates after a finite number of terms.

(c) A given representation is finite-dimensional if and only if $c^2 = (j_0 + n)^2$, for some natural number n.

(d) The irreducible representation corresponding to a given pair (j_0, c) is, with a suitable choice of basis f_m^j in the space of representation, given by the formulas¹⁵

$$H_{\pm} f_{m}^{j} = \lfloor (j \pm m + 1) (j \pm m) \rfloor^{\frac{1}{2}} f_{m\pm 1}^{j}$$

$$H_{j} f_{m}^{j} = m f_{m}^{j}$$

$$F_{\pm} f_{m}^{j} = \pm \lfloor (j \pm m) (j \pm m - 1) \rfloor^{\frac{1}{2}} C_{j} f_{m\pm 1}^{j-1}$$

$$- \lfloor (j \pm m) (j \pm m + 1) \rfloor^{\frac{1}{2}} A_{j} f_{m\pm 1}^{j}$$

$$\pm \lfloor (j \pm m + 1) (j \pm m + 2) \rfloor^{\frac{1}{2}} C_{j+1} f_{m\pm 1}^{j+1}$$

$$F_{j} f_{m}^{j} \lfloor (j - m) (j + m) \rfloor^{\frac{1}{2}} C_{j} f_{m}^{j-1} - m A_{j} f_{m}^{j}$$

$$- \lfloor (j \pm m + 1) (j - m + 1) \rfloor^{\frac{1}{2}} C_{j+1} f_{m}^{j+1} \qquad (2.8)$$

Here
$$A_j = i c j_0 / j (j + 1)$$
, and $C_j = i (j^2 - j_0^2)^{\frac{1}{2}} (j^2 - c^2)^{\frac{1}{2}} / j (4j^2 - 1)^{\frac{1}{2}}$.

(e) To each pair of numbers (j_0,c) , where j_0 is integral or half-integral and c is complex, there corresponds a representation $g \rightarrow T_g$ of the group I, whose infinitesimal operators are given by Eqs. (2.8).

C. Unitarity Conditions

If the representation $g \rightarrow T_g$ of the group L is unitary,^{16,17} then Eqs. (2.8) satisfy certain conditions which are summarized below.

Let A be an infinitesimal operator of a unitary representation $g \to T_g$ of the group L. Then $A(t) = T_{a(t)}$ is a unitary operator and therefore its $adjoint^{18} [A(t)] = [A(t)] -1 = A(-t)$. Accordingly (A(t)f, g) = (f, A(-t)g). Differentiating both sides of this equation with respect to t we obtain for t = 0,

$$(Af, g) = -(f, Ag).$$
 (2.9)

Using this relation one then easily finds that

$$(H_{f}, g) = (f, H_{g}), (H_{3}f, g) = (f, H_{3}g),$$
 (2.10)

 $(F_{+}f, g) = (f, F_{-}g), (F_{3}f, g) = (f, F_{3}g).$

A systematic use of Eq. (2.10) in (2.8) then leads to the following: If the irreducible representation $g \rightarrow T_g$ of the group L is unitary then the pair (j_0,c) characterizing it satisfies either (a) c is purely imaginary and j_0 is an arbitrary non-negative integral or half-integral number; or (b) c is a real number in the intervals $0 \le c \le 1$ and $j_0 = 0$.

The representations corresponding to case (a) are called the <u>principal series of representations</u> and those corresponding to case (b) are called the <u>complementary series</u>.

3. SPINOR REPRESENTATION OF THE LORENTZ GROUP

A. The Group SL(2, C) and the Lorentz Group

In what follows we will use the fact that elements of the proper, orthochroneous, Lorentz group L can be described by means of elements of SL(2, C), the group of all 2x2 complex matrices with determinant unity. The relation between these two groups can be established as follows.

Let x_{α} and x_{β}^* , with α , $\beta = 1, 2, 3, 4$, describe the coordinates of two Lorentz frames, related by

$$\mathbf{x}_{\alpha}^{*} = \mathbf{g}_{\alpha\beta} \mathbf{x}_{\beta} , \qquad (3.1)$$

where $g_{\alpha\beta} \in J_{\alpha}$. One associates with each coordinate system $x_{\alpha} = 2x2$ Hermitian matrix Q defined by

$$Q = x_{\beta} \sigma^{\beta}, \qquad (3.2)$$

where σ^{k} , k = 1,2,3, are the Pauli spin matrices,

$$\sigma^{4} = \begin{pmatrix} 0 & 4 \\ 1 & 0 \end{pmatrix}, \quad \sigma^{2} = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}, \quad \sigma^{3} = \begin{pmatrix} 4 & 0 \\ 0 & -1 \end{pmatrix} \quad (3.3)$$

and σ^4 is the 2x2 unit matrix. In terms of the Q's one demands that the coordinate transformation (3.1) be expressed as

$$Q' = a Q a^{\dagger}, \tag{3.4}$$

where a is an element of SL(2, C), $Q^{*} = x_{\beta}^{*\sigma} \sigma^{\beta}$, and a^{\dagger} is the Hermitian conjugate of a. One then finds that the relation between as SL(2, C) and g ϵ L are given by ¹⁹

$$\mathbf{g}_{\alpha\beta} = \frac{1}{2} \operatorname{Tr}(\sigma^{\alpha}_{a}\sigma^{\beta}_{a}^{\dagger}), \qquad (3.5)$$

It thus follows that the group L is homomorphic to the group SL(2,C)such that to every element $g \in L$ there correspond two matrices $\mp a \in SL(2, C)$ and, conversely, to every $a \in SL(2, C)$ there corresponds some element $g \in L$. Accordingly, the description of the representations of the group L is equivalent to that of the group SL(2,C); a representation $g \rightarrow T_g$ of L is single- or double-valued according to whether or not T_g is equal to T_{-a} or not.

B. Spinor Representation of the Group SL(2, C)

We now construct the spinor representation which contains all the irreducible finite-dimensional representations of the group SL(2, C).

We denote by P_{mn} the aggregate of all polynomials $p(z,\bar{z})$ in the variable z and its complex conjugate \bar{z} of degree not exceeding m in z and n in \bar{z} , where m and n are fixed non-negative integers determining the representation. The space P_{mn} is a linear vector space where the operation of addition and multiplication by a number are defined in the usual way for polynomials.

An element of the group SL(2,C) will be denoted by

$$g = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
(3.6)

where a, b, c, and d are complex numbers satisfying the condition

ad
$$-bc = 1.$$

Define the operator ${\rm T}_{\rm g}$ in ${\rm P}_{\rm mn}$ by

$$T_{g} p(3,\overline{3}) = (b_{3}+d)^{m}(\overline{b}_{\overline{3}}+\overline{d})^{n} p\left(\frac{a_{3}+c}{b_{3}+d}, \frac{\overline{a}_{3}+c}{\overline{b}_{\overline{3}}+d}\right) (3.7)$$

The correspondence $g \rightarrow T_g$ is a linear representation of the group SL(2,C) as can be easily verified. This is the <u>spinor representation</u> of SL(2,C) of dimension $(m + 1) \cdot (n + 1)$.

In order to relate this representation to the 2-component spinors, one realizes it in a somewhat different way.

One considers all systems of numbers $\phi_{A_1 \dots A_m} X_1 \dots X_n$, symmetrical in both the indices $A_1, \dots A_m$ and in X_1, \dots, X_n taking the values 0 and 1. The set of all such systems of numbers provides a linear space, denoted by S_{mn} , of dimension (m + 1)(n + 1).

A one-to-one linear mapping between the spaces P_{mn} and S_{mn} can easily be established. To each system $\phi_{A_1 \cdots A_m} \hat{X}_1 \cdots \hat{X}_n \in S_{mn}$ there corresponds the phynomial

$$p(3,\overline{3}) = \sum_{\substack{A_{1},...,A_{m} \\ \dot{X}_{1},...,\dot{X}_{n}}} \phi_{A_{1}...A_{m}} \dot{x}_{1}...\dot{x}_{n} \ 3^{A_{1}+...+A_{m}} \ \overline{3}^{\dot{X}_{1}+...+\dot{X}_{n}}$$
(3.8)

of degree not exceeding m in z and n in \overline{z} , and therefore $p(z,\overline{z}) \in P_{mn}$. On the other hand every polynomial

$$P(3,\overline{3}) = \sum_{r,s} P_{rs} 3^{r} \overline{3}^{s}$$
 (3.9)

in P_{mn} can be written in the form (3.8) if one relate the ϕ 's and p's by means of

$$\phi_{A_1\cdots A_m} \dot{x}_1\cdots \dot{x}_n = \frac{1}{m!\,n!}\,\operatorname{Prs} \qquad (3.10)$$

with $A_1 + \dots + A_m = r$, and $X_1 + \dots + X_n = s$.

A second form of the spinor representation is then obtained if one applies the polynomials (3.8) in Eq. (3.7). One obtains

$$T_{g} p(3,\overline{3}) = \sum_{\substack{A_{1},...,A_{m} \\ X_{1},...,X_{m}}} \varphi_{A_{1}...A_{m}} \chi_{A_{1}...,X_{m}} \overline{3}^{A_{1}+..+A_{m}} \overline{3}^{X_{1}+..+X_{m}}$$
(3.11)

where we have used the notation

$$\phi'_{\mathbf{A}_{1}\cdots\mathbf{A}_{m}\dot{\mathbf{x}}_{1}\cdots\dot{\mathbf{x}}_{n}} = \sum_{\substack{\mathbf{B}_{1}\cdots\mathbf{B}_{m}\\\dot{\mathbf{y}}_{1}\cdots\dot{\mathbf{y}}_{n}}} a_{\mathbf{A}_{1}\mathbf{B}_{1}}\cdots a_{\mathbf{A}_{m}\mathbf{B}_{m}} \vec{a}_{\dot{\mathbf{x}}_{1}\dot{\mathbf{y}}_{1}}\cdots \vec{a}_{\dot{\mathbf{x}}_{n}\dot{\mathbf{y}}_{n}} \phi_{\mathbf{B}_{1}\cdots\mathbf{B}_{m}} \vec{\mathbf{y}}_{1}\cdots\dot{\mathbf{y}}_{n}$$
(3.12)

and where $a_{11} = a$, $a_{10} = b$, $a_{01} = c$, and $a_{00} = d$.

The quantity $\phi_{A_1 \dots A_m} \dot{X}_1 \dots \dot{X}_n$ is a spinor, symmetric in its m undotted indices and in its n dotted ones, whereas Eq. (3.12) expresses its transformation law under the matrix $a \in SL(2,C)$.

C. Infinitesimal Operators of the Spinor Representation

We now find the infinitesimal operators H_+ , H_- , H_3 , and F_+ , F_- , F_3 of the spinor representation discussed in the last subsection.

The one-parameter subgroups of SL(2,C), corresponding to the one-parameter subgroups $a_k(t)$ and $b_k(t)$ of the group L, can easily be obtained using the formula (3.5).²⁰ In terms of the infinitesimal matrices a_r and b_r of the group SL(2,C) they can be written as

$$a_k(t) = \exp(t a_k), b_k(t) = \exp(t b_k),$$
 (3.13)

where $a_k = i\sigma^k/2$ and $b_k = \sigma^k/2$, and where σ^k are the Pauli spin matrices given by Eq. (3.3). Using the matrices $a_k(t)$ and $b_k(t)$ in (3.7), differentiating both sides of the obtained equations with respect to the variable t, and putting t = 0, gives the expressions for the operators A_k and B_k , from which one then obtains the operators H's and F's:

$$H_{+} = -\frac{2}{33} - \frac{3}{32} + \frac{2}{33} + n\frac{3}{3}$$

$$H_{-} = 3^{2} \frac{2}{33} + \frac{2}{33} - m_{3}$$

$$H_{3} = -3 \frac{2}{33} + \frac{3}{33} + \frac{2}{33} + \frac{1}{2} (m-n)$$

$$F_{+} = i \left(\frac{2}{33} - \frac{3}{2} + \frac{2}{33} + n\frac{3}{3} \right)$$

$$F_{-} = i \left(-3^{2} \frac{2}{33} + \frac{2}{33} + \frac{2}{33} + m\frac{3}{3} \right)$$

$$F_{1} = i \left(3 \frac{2}{33} + \frac{2}{33} + \frac{2}{33} - \frac{1}{2} (m+n) \right).$$
(3.14)

4. PRINCIPAL SERIES OF REPRESENTATIONS OF SL(2,C)

A. The Hilbert Spaces $L_{a}^{2s}(SH_{2})$ and ℓ_{a}^{2s} .

In its global form the principal series of representations was introduced (Naimark 1964) as a set of operators over the Hilbert space of functions $L_{B}^{2,S}(SU_{g})$, a sub-space of $L_{0}(SU_{p})$, defined as follows.

The Hilbert space Le(SU2) is defined as the set of all functions ϕ (u), where uesu, which are measurable and satisfy the condition 21

$$\int |\phi(u)|^2 du < \infty \tag{4.1}$$

The scalar product is defined by

$$(\phi_1, \phi_2) = \int \phi_1(u) \, \overline{\phi_2(u)} \, du.$$
 (4.2)

Corresponding to any integer or half-integer ε we now define a Hilbert space $L_2^{2s}(SU_{\epsilon})$, which is a sub-space of $I_{\epsilon}(SU_{2})$, as follows:

$$\phi(u) \in L_2^{2^{S}}(SU_2) \text{ if } \phi(u) \in L_2(SU_2) \text{ and}$$

$$\phi(\gamma u) = e^{is\psi} \phi(u) \qquad (4.3)$$

where $\gamma \in SU_2$ is given by

$$\gamma = \begin{pmatrix} \epsilon^{-i\psi_2} & 0 \\ 0 & e^{i\psi_2} \end{pmatrix}.$$
 (4.4)

The scalar product is again given by Eq. (4.2).

 $L_2(SU_2)$ is the direct sum of all the spaces $L_2^{2s}(SU_2)$, for all integral values of 2s.

The generalized Fourier transformation, to be introduced at the end of the section, transforms each Hilbert space $L_2^{2s}(SU_2)$ into a Hilbert space ℓ_2^{2s} , which is defined as follows (Carmeli 1970):

Consider all possible cystems of numbers β_m^j , where m = -j, -j + 1, ..., j and j = |s|, |s| + 1, |s| + 2,... with the condition

$$\sum_{j=1}^{\infty} (2j+1) \sum_{m=j}^{j} |\phi_{m}^{j}|^{2} < \infty$$
(4.5)

The aggregate of all such systems p_m^j forms a Hilbert space, denoted by ℓ_2^{2s} , where the scalar product is defined by

$$\sum_{j=1s}^{\infty} (2j+1) \sum_{m=1}^{j} \psi_{m}^{j} \overline{\psi_{m}^{j}}$$

$$(4.6)$$

for any two vectors ϕ_m^j and ψ_m^j of ℓ_2^{2s} .

Let us show now that for any integral or half-integral value of s the two Hilbert spaces L_2^{2s} (SU₂) and $\frac{2s}{2}$ are isometric, and derive the trans-formation between them.

Let $T_{sm}^{j}(u)$ be the matrix element of the irreducible representation of the group SU_{2} corresponding to the eigenvalue j(j + 1) of the Cosimir operator J^{2} . The functions $T_{sm}^{j}(u)$ satisfy (Naimark 1964)

$$T_{sm}^{j}(\gamma u) = e^{is\psi} T_{sm}^{j}(u)$$
 (4.7)

and for a fixed value of s they provide a complete orthogonal set for the Hilbert space $L_2^{2s}(SU_2)$ as m = -j, -j + 1, ..., j and $j = \lfloor s \rfloor$, $\lfloor s \rfloor + 1$, $\lfloor s \rfloor + 2, ...$ (Carmeli 1969). The functions T_{sm}^j (u) satisfy the orthogonality relation

$$\int T_{sm}^{j}(u) T_{s'm}^{j'}(u) du = (2j+1)^{-1} \delta_{jj} \delta_{ss}, \delta_{mm}, (4.8)$$

Consequently, any function $\phi(u) \in L_2^{2,5}(SU_2)$ can be uniquely expanded in the form

$$\phi(u) = \sum_{j=1}^{\infty} (2j+1) \sum_{m=-j}^{j} \phi_{m}^{j} T_{m}^{j} (u) \qquad (4.9)$$

where

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$$\psi_{m}^{j} = \int \phi(u) T_{sm}^{j}(u) clu$$
. (4.10)

It can be easily shown that the system of numbers ϕ_m^j satisfies Eq. (4.5) if and only if the corresponding function $\phi(u)$ satisfies Eq. (4.1). The Hilbert spaces $L_2^{2^{S}}(SU_2)$ and $\ell_2^{2^{S}}$ are, therefore, isometric and the mapping between them is given by the "generalized Fourier transformation" (4.9) and (4.10).

 B. Realization of the Principal Series of Representations in the Spaces L^{2s}₂^{3U}₂) We are now in a position to introduce the realization of the principal series representations of the group SL(2, C) in the Hilbert space L^{2s}₂(SU₂).
 To this end we proceed as follows.²²

Let us denote by K to aggregate of all elements k of the group SL(2,C) where k has the form

$$k = \begin{pmatrix} \lambda^{-\prime} & \mu \\ 0 & \lambda \end{pmatrix}$$
(4.11)

with λ , μ complex numbers and $\lambda \neq 0$. One can easily verify that the set K forms a subgroup of the group SL(2, C).

We now construct the set of right cosets of the group SL(2, C) with respect to the subgroup K.

Each right coset consists of all the element kg', where g' is a fixed element of SL(2, C) and k varies over the subgroup K. Each coset will be

denoted either by Kg' or by $\tilde{Kg}' = \tilde{g}$ where g is an arbitrary element belonging to the coset Kg'.

It can be easily shown that every element $g \in SL(2, C)$ can be represented in the form

$$g = ku;$$
 keK; ue SU₂. (4.12)

It follows from Eq. (4.12) that if an element $g \in SL(2,C)$ belongs to a given coset \tilde{g} , then $k^{-1}g = u \in SU_2$ also belongs to the same coset. Therefore each coset \tilde{g} contains elements of the group SU_2 .

Furthermore, the decomposition (4.12) is not unique since $g = ku = k^{u}$; k, k' ϵ K; u, u' ϵ SU₂ (4.13)

where

$$\mathbf{k}^* = \mathbf{k}\mathbf{Y} \qquad \mathbf{u}^* = \mathbf{y}^{-1}\mathbf{u} \qquad (\mathbf{4}_*\mathbf{1}\mathbf{4})$$

with Y an arbitrary element of the subgroup Γ :

$$\Gamma: \gamma = \begin{pmatrix} e^{-i\omega} & 0 \\ 0 & e^{i\omega} \end{pmatrix}, \quad \omega \text{ real.} \quad (4.15)$$

Therefore each coset \widetilde{g} contains a one-parametric set of elements belonging to SU₂.

Let us denote by ug an arbitrary element (matrix) of the coset ug = Kug which belongs to SU_2 . It can be proved (Naimark, 1964) that any principal series representation corresponding to the pair of parameter (s, ρ), where s is an integer or half-integer, and ρ is real, can be formulated as follows: to every element g \in SL(2, C) there corresponds an operator V_g defined over the space $L_2^{\leq S}(SU_2)$ by

$$V_g \phi(u) = \frac{\alpha(u_g)}{\alpha(u_g)} \phi(u_g) \qquad (4.16)$$

for all
$$\phi(u) \in 4^{2s}_{2}(SU_1)$$
, and α is given by
 $\alpha(g) = 1g_{22} \int f^{2s-2}_{23} g_{32}^{2s}$
(4.17)

for an arbitrary $g' \in SL(2, C)$. ug is an element of the right coset ug defined above.

To facilitate practical applications of the representation formula (4.16) we derive now (a) an explicit expression for the matrix ug in terms of the matrices $\mu \in SU_2$ and $g \in SL(2,C)$. The expression will involve a phase factor which can be chosen arbitrarily; (b) the ratio $\frac{\alpha(ug)}{m}$ appearing in formula (4.16) $\alpha(u\vec{g})$ for two cases of particular interest: (i) g is unitary; (ii) g is of the form

$$g = \begin{pmatrix} \varepsilon_{21} & o \\ o & \varepsilon_{21} \end{pmatrix}, \qquad (4.18)$$

where ε_{22} is real.

(a) Let us denote the matrix ug by u'. Then u' can be written as

$$\mathcal{U}' = \begin{pmatrix} u'_{i1} & u'_{12} \\ u'_{21} & u'_{12} \end{pmatrix} = \begin{pmatrix} \alpha' & \beta' \\ -\overline{\beta'} & \overline{\alpha'} \end{pmatrix}$$
(4.19)

with the condition

$$|\alpha'|^2 + |\beta'|^2 = 1.$$
 (4.20)

According to Eq. (4.12) ug can be written in the form $ug = k \cdot ug = k \cdot u$

$$\begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} = \begin{pmatrix} \lambda^{-1} & \mu \\ 0 & \lambda \end{pmatrix} \begin{pmatrix} \alpha' & \beta' \\ -\overline{\beta}^{-1} & \overline{\alpha}^{-1} \end{pmatrix}. \quad (4.21)$$

This gives

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$$g_{21} = -\lambda \overline{\beta'}, \quad g_{22} = \lambda \overline{\alpha'} \quad (4.22)$$

from which one obtains

$$a' = \frac{g'_{11}}{\bar{a}}, \quad \beta' = -\frac{\bar{5}_{11}}{\bar{a}}.$$
 (4.23)

Furthermore, using the condition (4.20) one obtains

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$$|\lambda|^2 = |g_{21}|^2 + |g_{21}|^2. \qquad (4.24)$$

But g' = ug. Let us denote u by

$$u = \begin{pmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{pmatrix} = \begin{pmatrix} \alpha & \beta \\ -\overline{\beta} & \overline{\alpha} \end{pmatrix}, \qquad (4.25)$$

and g by

$$g = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}, \qquad (4.26)$$

then

$$\begin{pmatrix} g_{11}' & g_{12}' \\ g_{21}' & g_{22}' \end{pmatrix} = \begin{pmatrix} \chi g_{11} + \beta g_{21} & \chi g_{12} + \beta g_{22} \\ -\bar{\beta} g_{11} + \bar{\chi} g_{21} & -\bar{\beta} g_{12} + \bar{\chi} g_{22} \end{pmatrix}.$$
(4.27)

If we write now $\lambda = |\lambda| \exp(i \Lambda)$, where Λ is some real number (phase), then one finally obtains for (4.23) and (4.24)

$$\alpha' = (-\beta \, \overline{g_{12}} + \alpha \, \overline{g_{12}}) \, |\lambda|^{-1} \, c^{i\Lambda}$$

$$\beta' = (\beta \, \overline{g_{11}} - \alpha \, \overline{g_{11}}) \, |\lambda|^{-1} \, e^{i\Lambda} \qquad (4.28)$$

and

$$|\chi|^{2} = |\beta \overline{g_{11}} - \alpha \overline{g_{21}}|^{2} + |-\beta \overline{g_{12}} + \alpha \overline{g_{22}}|^{2}. \quad (4.29)$$

Hence, ug is determined by means of u and g up to an arbitrary phase factor.

(b) (i) let g be a unitary matrix u_o with determinant unity:

$$u_{o} = \begin{pmatrix} \alpha_{o} & \beta_{o} \\ -\overline{\beta_{o}} & \overline{\alpha_{o}} \end{pmatrix}; \quad |\alpha_{o}|^{2} + |\beta_{o}|^{2} = 1$$
(4.30)

Then one obtains from Eqs. (4.28), (4.29)

$$\alpha' = (-\beta \overline{\beta} + \alpha \alpha) e^{i\Lambda}$$

$$\beta' = (\beta \overline{\alpha} + \alpha \beta) e^{i\Lambda}$$

$$|\lambda| = 1$$

(4.31)

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and, accordingly

$$\frac{\alpha(uu_{\bullet})}{\alpha(u\bar{u}_{\bullet})} = e^{2is\Lambda}$$
(4.32)

(ii) g is the matrix given by Eq. (4.18). One then obtains

$$\alpha' = \alpha \, \mathcal{E}_{21} \, |\lambda|^{-1} \, e^{i\lambda}$$

$$\beta' = \beta \, \mathcal{E}_{21}^{-1} \, |\lambda|^{-1} \, e^{i\lambda}$$

$$|\lambda|^{2} = |\beta|^{2} \, \mathcal{E}_{22}^{-2} + |\alpha|^{2} \, \mathcal{E}_{22}^{1}$$

$$(4.34)$$

and

$$\frac{\chi(u\epsilon)}{\chi(u\bar{\epsilon})} = |\lambda|^{if^{-2}} e^{2is\Lambda}.$$
 (4.35)

C. Realization of the Principal Series of Representations in the Space l_2^{2s} .

Using the generalized Fourier transformation, introduced in Sec. 4A, we express now the representations belonging to the principal series as infinitedimensional matrices, the elements of which will be explicitly given as integral over the group SU_2 . One first notices that $T_{sm}^{j}(u)$ is an element of the Hilbert space $L_2^{2S}(SU_2)$. Therefore Eq. (4.16), which expresses a given principal series representation, can be applied to $T_{sm}^{j}(u)$ to yield

$$V_{g} T_{sm}^{j}(u) = \frac{\alpha(u_{g})}{\alpha(u_{g})} T_{sm}^{j}(u_{g}^{-}).$$
 (4.36)

From Eqs. (4.9), (4.16), and (4.36) we have

$$V_{y} \phi(u) = \sum_{j} (2j+i) \sum_{m} \phi_{m}^{j} \frac{\alpha(ug)}{\alpha(ug)} T_{sm}^{j} (ug). \quad (4.37)$$

Since $\frac{\alpha(ug)}{\alpha(ug)}$ T^j (ug) is a vector in the Hilbert space L^{2s}₂(SU₂) it $\alpha(ug)$ (of the space L^{2s}₂(SU₂) it can be expanded as a series (form (4.9). One obtains

$$\frac{\alpha(u_{\bar{g}})}{\alpha(u_{\bar{g}})}T_{sm}^{j}(u_{\bar{g}}) = \sum_{j'} (2j'+1) \sum_{m'} V_{mm'}^{jj'}(g;s,f) T_{m'}^{j'}(u)$$
(4.38)

where, because of Eq. (4.10)

$$V_{mm'}(g; s, f) = \int \frac{\alpha(ug)}{\alpha(ug)} T_{sm}^{j}(ug) T_{sm'}^{j}(u) du$$
 (4.39)

Combining Eqs. (4.37), (4.38) one finally obtains

$$V_{g}\phi(u) = \sum_{j} (2j+1) \sum_{m} \phi_{m}^{ij} T_{sm}^{j}(u)$$
 (4.40)

where

$$\phi_{m'}^{\prime j'} = \sum_{j=|s|}^{\infty} (2j+i) \sum_{m=-j}^{j} V_{mm'}^{jj'} (g; s, g) \psi_{m}^{j}. \qquad (4.41)$$

Thus the operator V_g of the principal series of representations of SL(2, C) in the space \mathcal{L}_2^{2s} is the linear transformation determined by Eq. (4.41) describing the law of transformation of the quantities ϕ_m^j where j = |s|, |s| + 1, |s| + 2,... and $m = -j, -j + 1, \ldots, j$. The coefficients $V_{mm}^{jj'}$ (g; s, ρ) are functions of g \in SL(2, C) and ρ and s, where ρ is real and 2s is an integer. These functions are the matrix elements of an infinite-dimensional matrix, whose rows are labeled by (j, m) and columns - by (j', m'). They are given by Eq. (4.39) as integrals over the group SU₂.

It will be noted that the quantities β_m^j , whose transformation law is given by Eq. (4.41), were obtained from the representation formula (4.16), in analogy with the way 2-component spinors, transforming according to Eq. (3.12), both being coefficients appearing in the spaces of representations.

D. Comparison with the Infinitesimal Approach

We have seen in the present section that all the irreducible representations of the group SL(2, C) belonging to the principal series are characterized by a pair of numbers (s, β) where s is an integer or half-integer and β is real. If the representation is given in a global form, the space of the representation depends on the value of s (see Sec. 4A) and the operators depend on both s and β (Eqs. (4.16), (4.17)). The principal series was already defined in terms of the infinitesimal operators in Sec. 2C. It was found to depend on a pair of papameters (j_0, c) where j_0 takes the values $0, \frac{1}{2}$ 1, 3/2,... and c is pure imaginary. The values of these parameters occurred in the formulae for the infinitesimal operators (Eq. (2.8)).

By applying the global form of a given representation to infinitesimal elements of the group SL(2, C) one can calculate the infinitesimal operators of the representation. By comparing the infinitesimal operators thus obtained with the results of Sec. 2 one establishes the relationship between the pairs of parameters (s, ip) and (j_0 , c). The result is as follows:

For $j_0 = 0$, one obtains

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$$s = 0$$
, $c = \pm i \frac{\rho}{2}$, (4.42)

and for $j_0 \neq 0$, one obtains

$$j_{0} = s \qquad c = -i\frac{\rho}{2} \text{ if } s > 0 \qquad (4.43)$$

$$j_{0} = s \qquad c = i\frac{\rho}{2} \text{ if } s < 0$$

5. COMPLEMENTARY SERIES OF REPRESENTATIONS OF SL(2 C)

A. Realization of the Complementary Series of Representations in the Space H.

In Sec. 4 the principal series of representations which is unitary and irreducible, was realized as sets of operators on the Hilbert spaces L_2^{25} (SU₂). The scalar product was given simply by Eq. (4.2) and the operators were defined by Eqs. (4.16), (4.17).

The principal series of representations, however, do not realize all irreducible unitary representations of the group SL(2, C). Rather, every irreducible unitary representation of the group SL(2, C) is unitarily equivalent to a representation of either the principal series or the complementary series of representations.

Formally, the complementary series of representations formulae can be obtained from that of the principal series formuale (4.16) if one takes $\rho = i^{\sigma}$ and s = 0 in the latter and assume that now σ is real and has the values $0 < \sigma < 2$ (Nairmark 195^h). Unfortunately, the operators thus defined are not unitary in the scalar product (4.2): Eq. (4.16) defines a unitary operator if and only if $\alpha(g)$ is defined by Eq. (4.17) with ρ real.

A realization of the complementary series representations in terms of unitary operators is, however, possible on the Hilbert space of H_{σ} to be defined as follows.

Let H denote the set of all bounded measurable functions $\phi(u)$, where u is an element of SU₂, satisfying the condition

$$\phi(\mathbf{Y}\mathbf{u}) = \phi(\mathbf{u}), \tag{5.1}$$

and where $\gamma \in SU_2$ is given by Eq. (4.4). [The condition (5.1) is in fact identical with (4.3) for the case s = 0.] Introduce in H the scalar product

$$\langle \phi_1, \phi_2 \rangle = \pi \iint K (u^* u^{*-1}) \phi_1 (u^*) \phi_2 (u^{**}) du^* du^*$$
 (5.2)

for $\phi_1, \phi_2 \in H$. Here K (u' u"⁻¹) is a kernel function defined by

$$K(u) = |u_{21}|^{\sigma-2},$$
 (5.3)

where $0 < \sigma < 2$ and the integral on the right hand side of Eq. (5.2) converges absolutely. The space H can be shown to be Euclidean, whose completion (which is a Hilbert space²³) we denote by h_{σ} .

In the Hilbert space H_{σ} , the operators V_{g} of a representation of the complementary series, defined in complete analogy with the principal series, are unitary. Explicitly, the definition of V_{g} is as follows:

$$V_{g} \phi(u) = \frac{\alpha(ug)}{\alpha(ug)} \phi(u\overline{g})$$
(5.4)

where $\oint \epsilon H$ and $\alpha(g)$ is given by

$$\alpha (g) = |g_{22}|^{\sigma-2}$$
 (5.5)

for any g ε SL(2, C) and 0 < σ < 2. The representations thus defined are irreducible and unitary.

B. Orthogonal Set in the Space H

We now define a set of functions which provides an orthogonal basis in the space H. It is given by

$$\mathbf{t}_{m}^{\mathbf{j}}(\mathbf{u}) = N_{\mathbf{j}} \mathbf{T}_{om}^{\mathbf{j}}(\mathbf{u})$$
 (5.6)

for j = 0, 1, 2, 3... and m = -j, -j + 1, ..., j, where the $T_{om}^{j}(u)$ were defined in Sec. 4C and N_j is a real normalization factor whose value is given by

$$N_{j} = \{ \pi_{j} K(u) T_{00}^{j}(u) du \}^{-\frac{1}{2}}.$$
 (5.7)

The integration involved in the definition of N_j can be carried out to yield an expression of the normalization constants as a finite sum of Euler B - functions. The result is (Carmeli and Malin 1971)

$$N_{j}^{-2} = \pi \sum_{m=0}^{j} (-)^{3j-m} (\frac{j}{m})^{2} B(m+1, j+\frac{\sigma}{2}-m)$$
(5.8)

where²⁴

$$B(x,y) = \frac{\Gamma(x) \Gamma(y)}{\Gamma(x+y)} .$$
 (5.9)

To show that \mathbf{t}_m^{j} indeed provide an orthogonal basis in H we calculate the scalar product
$$\langle t_{m_{1}}^{j_{1}}, t_{m_{2}}^{j_{2}} \rangle = \pi \iint K(u'u''') t_{m_{1}}^{j_{1}}(u') t_{m_{2}}^{j_{1}}(u'') du' du'''$$

$$= \pi N_{j_{1}}^{j_{1}} N_{j_{2}}^{j_{2}} \iint K(u'u''') T_{om_{1}}^{j_{1}}(u') du' T_{om_{2}}^{j_{2}}(u'') du''$$

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By making the transition $u' \rightarrow u' u''$ in the integral (5.10) one obtains

$$< t_{m_1}^{j_1}, t_{m_2}^{j_2} >$$

= $\pi N_{j_1} N_{j_2} \int_{1}^{j_1} K(u') T_{om_1}^{j_1} (u'u'') du' T_{om_2}^{j_2} (u'') du'' (5.11)$

Using the relation

$$T_{om}^{j_{i}}(u'u'') = \sum_{m=j_{i}}^{j_{i}} T_{om}^{j_{i}}(u') T_{mm}^{j_{i}}(u'')$$
(5.12)

in the last integral we obtain

$$\leq t_{m_{1}}^{j_{1}}, t_{m_{2}}^{j_{2}} >$$

$$= \pi N_{j_{1}} N_{j_{2}} \sum_{m=-j}^{j} \int K(u') T_{om}^{j_{1}}(u') du' \int T_{mm_{1}}^{j_{1}}(u'') \overline{T_{om_{2}}^{j_{2}}(u'')} du''$$

$$(5.13)$$

Using now the orthogonality relation (4.8) that the matrices T^{j} satisfy, we obtain

$$< t_{m_{1}}^{j_{1}}, t_{m_{2}}^{j_{2}} >$$

$$= \pi N_{j_{1}} N_{j_{1}} \left\{ \int K(u') T_{oo}^{j_{1}}(u') du' \right\} \frac{5^{j_{1}j_{1}} 5^{m_{1}m_{1}}}{2j_{1} + 1} (5.14)$$

which, by virtue of Eq. (5.7) gives

$$< t_{m_{1}}^{j_{1}}, t_{m_{2}}^{j_{2}} > - \frac{\delta^{j_{1}j_{2}} \delta^{m_{1}m_{2}}}{2j_{1} + 1}.$$
 (5.15)

C. Realization of the Complementary Series in the Space h

In analogy with the generalized Fourier transformation, introduced in Sec. 4A, between the space $L_2^{2s}(SU_2)$ and l_2^{2s} , there exists for the complementary series a transformation from the Euclideon space of functions H (and its completion, the Hilbert space H_0) to a Euclideon space of systems of numbers h (and its completion, the Hilbert space h_0) (Carmeli and Malin 1971).

The Euclidean space h is defined as the aggregate of all systems of numbers Ψ_m^j , where $m = -j, -j + 1, \ldots, j$ and $j = 0, 1, 2, \ldots$, satisfying

$$\sum_{j} (2j+1) N_{j}^{-2} \sum_{m=-j}^{j} |\psi_{m}^{j}|^{2} < \infty$$
(5.16)

The scalar product is defined by

$$\sum_{j} (2j+i) N_{j}^{-2} \sum_{m=1}^{j} \phi_{m}^{j} \psi_{m}^{j}$$
(5.17)

for any two vectors ϕ_m^j and Ψ_m^j in h. The coefficients N_j are defined by Eq. (5.7).

In analogy with Eqs. (4.9) and (4.10) relating the space $L_2^{2s}(SU_2)$ and ℓ_2^{2s} the correspondence between H and h is given by

$$\varphi(u) = \sum_{j} (2j+1) N_{j}^{-1} \sum_{m} \phi_{m}^{j} t_{m}^{j} (u) \qquad (5.18)$$

and

$$\phi_{m}^{j} = N_{j} \langle \phi, t_{m}^{j} \rangle, \qquad (5.19)$$

where t_m^j was defined by Eq. (5.6). Comparing

$$\langle \phi, \psi \rangle = \sum_{j} (2j+1) N_{j}^{-2} \sum_{m}^{2} \phi_{m}^{j} \overline{\psi_{j}^{j}}$$
 (5.20)

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with Eq. (5.18) we see that $\phi(u)$ eH if and only if the corresponding ϕ_m^j eh.

If we denote now by h_{σ} the completion²³ of the Euclidean space h, then the isometric mapping (5.18), (5.19) of H on h can be extended in a unique way by continuity to an isometric mapping of H_{σ} on h_{σ} . The operators V_{g} of a representation of the complementary series in the space H_{σ} pass over into operators in the space h_{σ} , which are also denoted by V_{g} and whose explicit expression we find below.

Applying Eq. (5.4) to the t_m^j gives

$$V_{g} t_{m}^{j}(u) = \frac{\alpha(u_{g})}{\alpha(u_{g})} t_{m}^{j}(u_{g}^{j})$$
 (5.21)

Using this result in Eq. (5.18) yields

$$V_{g}\phi(u) = \sum_{j} (2j+1) N_{j}^{-1} \sum_{m} \phi_{m}^{j} \frac{\alpha(u_{g})}{\alpha(u_{g})} t_{m}^{j} (u_{g}^{-1})$$
(5.22)

Expanding $\frac{\alpha(ug)}{\alpha(ug)} t_m^j (ug)$ in the series (5.18) we obtain

$$V_{j} \phi(u) = (5.23)$$

= $\sum_{j} (2j+1) \sum_{m} \phi_{m}^{j} \sum_{j'} (2j'+1) N_{j'}^{-j} \sum_{m} V_{mm}^{jj'} (g_{j}\sigma) \ell_{m'}^{j'}(u)$

where, because of Eqs. (5.19) and (5.2)

$$V_{mm}^{jj'}(g,\sigma) = \pi \frac{N_{j'}}{N_{j}} \iint K(u'u''-i) \frac{\alpha(u'j)}{\alpha(u'j)} t_{m}^{j}(u'j) t_{m'}^{j'}(u'') du' du'''} (5.24)$$

Accordingly, Eq. (5.23) has the form

$$V_{j} \psi(u) = \sum_{j} (u_{j} + 1) N_{j}^{-1} \sum_{m} \psi_{m}^{ij} t_{m}^{j} (u)$$
 (5.25)

where

$$\phi_{m'}^{\,\prime j} = \sum_{j=0}^{\infty} (2j * 1) \sum_{m=j}^{j} V_{mm}^{\,j j'} (g_{j} \sigma) \phi_{m}^{\,j} . \quad (5.26)$$

Eq. (5.26) defines a linear transformation in the space h_{σ} corresponding to the operator V_{g} of the complementary series. $V_{mn}^{jj'}(g, \sigma)$, which are given by Eq. (5.24) as double integrals over the group SU_{2} , are functions of $g \in SL(2,C)$ and σ where $0 < \sigma < 2$. These functions are the matrix elements of an infinitedimensional matrix, where rows are labeled by (j, m) and columns - by (j', m').

D. Comparison with the Infinitesimal Approach

The complementary series in its global form, as defined in this section, is characterized by a parameter σ , whose range of variation is $0 < \sigma < 2$. The value of σ determines the scalar product (Eqs. (5.2) and (5.3)) in the Hilbert space of representations and also the operators of the representations (eqs. (5.4) and (5.5)).

33

The complementary series was defined in Sec. 2 through the infinitesimal approach. All the irreducible representations of the group SL(2, C) were characterized in Sec. 2 by a pair of numbers (j_0, c) , where j_0 takes the values 0, $\frac{1}{2}$, 1 3/2,... and c is complex. The complementary series representations were characterized by $j_0 = 0, 0 < c < 1$.

To establish the relationship between the parameters σ and c one applies the global form of a given representation to infinitesimal elements of the group SL(2,C) and compares the infinitesimal elements thus obtained with the results of Sec. 2. The result is

$$j_0 = 0, c = \pm (c/2),$$
 (5.27)

6. COMPLETE SERIES OF REPRESENTATIONS OF SL(2, C)

A. Realizations of the Complete Series in the Spaces L_2^{2s} (SU₂) and l_2^{2s} .

As has already been pointed out in Sec. 5 all the unitary representations of the group SL(2, C) are included in either the principal or the complementary series.²⁵ Gel'faund and Naimark (1947) and Naimark (1954, 1964) have shown that all the completely irreducible²⁵ representations of SL(2, C)(i.e. not necessarily unitary) are included, up to equivalence, in a series of representations known as the complete series.²⁷

We define here the complete series and its realization in the spaces L_2^{2s} (SU₂) and ℓ_2^{2s} .

All the representations of the complete series can be characterized by a pair of numbers (s, ρ) where s is an integer or half-integer and ρ satisfies $\rho^2 \neq -4 (|s| + k)^2$, $k = 1, 2, 3, \cdots$ and is otherwise an arbitrary complex number. The pairs (s, ρ) and $(-s, -\rho)$ define the same representation.

All the representations of the complete series can be realized in the spaces L_2^{2s} (SU₂), defined in Sec. 4A. The space of realization depends therefore, on s alone and is independent of ρ . A given representation corresponding to a pair (s, ρ) is realized in $L_2^{2s}(SU_2)$ by a set of operators V_g , g ϵ SL(2, C) defined by

$$V_{j} \phi(u) = \frac{\alpha(u_{j})}{\alpha(u_{j})} \phi(u_{j}) \qquad (6.1)$$

for ϕ (u) $\in L_2^{2s}(SU_2)$, where

$$x(g) = g_{22}^{25} |g_{22}|^{i_{f}-25-2}$$
(6.2)

and ug was defined in Sec. 4B.

These formulas are the same as Eq. (4.16) and (4.17) for the principal series; the difference is that now ρ can take complex values, while in Eqs. (4.18) ρ is real. It can be shown that the operators V defined by Eqs. (6.1), (6.2) are unitary if and only if ρ is real.

In complete analogy with Sec. 4C the generalized Fourier transformation, introduced in Sec. 4A, can now be utilized to obtain a realization of the complete series in the spaces l_2^{2S} . The result is

$$\phi_{m'}^{\prime j'} = \sum_{j=l=1}^{\infty} (2j+l) \sum_{m=-j}^{j} V_{mm}^{jj'} (g; s, g) \phi_{m}^{j}$$
(6.3)

where

$$V_{mm}^{jj'}(g;s,g) = \int \frac{\alpha(ug)}{\alpha(u\bar{g})} T_{sm}^{-j}(u\bar{g}) T_{m'}^{j'}(u) du \quad (6.4)$$

which is again the same as Eqs. (4.39), (4.41) except insofar as the definition of α (g)(Eq. (6.2)) is extended to include complex values of ρ .

B. Relation to the Principal and Complementary Series

The complete series describes all the infinite-dimensional completely irreducible representations, to within equivalence, of the group SL(2, C). The meaning of equivalence here is such that the spaces of two equivalent representations need <u>not</u> be isometric, but it is the formulas which are essential for the representations and not the norm of the space. In the present subsection we define equivalence of representations and show that the representations belonging to the complementary series are, from this point of view, equivalent to representations contained in the complete series.

The definition of equivalence between representations realized in Banach spaces requires some preliminary mathematical definitions:

(i) the group ring X. Let X deonte the set of all infinitely differentiable functions x(g), $g \in SL(2, C)$, which vanish for all the matrices g satisfying

$$|g_{11}|^{2} + |g_{12}|^{2} + |g_{21}|^{2} + |g_{21}|^{2} > C \qquad (6.5)$$

for a big enough number C which may depend on the function x(g). This set forms a ring if addition and multiplication by complex numbers are defined in the usual way and multiplication of ring elements is defined as follows:²⁰

$$x_1 \cdot x_2(g) = \int x_1(g') \cdot x_1(g''g) \cdot dg'$$
 (6.6)

(ii) Conjugate representations. Given a Banach space B, whose elements are deonted by ξ , its conjugate space B is defined as the space of all bounded linear functionals f (ξ) in B. $_{37}$

Given an operator T in B its conjugate operator T* is defined in B* as

$$T^{*}f(\xi) = f(T\xi)$$
 (6.7)

Now, given a representation in terms of operators $\boldsymbol{V}_{\boldsymbol{g}}$ on a Banach space B we define

$$\tilde{v}_{g} = v_{g-1}^{\bullet}$$
(6.8)

as the conjugate representation in the Banach space B*.

(iii) The set Ω corresponding to a given representation in a Banach space B is defined as the aggregate of all finite linear combinations of the vector $V_x \xi$ (V_x is defined in footnote 2θ) where $\xi \in M^j$ (see Sec. 2) for any value of j, and x \in X. The set corresponding to the conjugate representation is denoted by Ω^* .

Following Naimark (1964) we now define two representations V_g^1 , V_g^2 on Banach spaces B^1 , B^2 as equivalent if there exists linear operators A^1 and A^2 from B^1 to B^2 and from B^2 to B^1 respectively, whose domains of definition are Ω^1 , Ω^2 and domains of variation Ω^2 , Ω^{*2} respectively, satisfying, for all 5 $\epsilon \Omega$, f $\epsilon \Omega^{*2}$,

$$f(A^{4}\xi) = A^{*}f(\xi);$$
 (6.9)

 $1f A^{1} \xi = 0, A^{2} f = 0 \text{ then } \xi = 0, f = 0,$

$$A^*V_{\mathbf{x}} \xi = V_{\mathbf{x}}^2 A\xi \quad ; \tag{6.10}$$

$$A^{2}\tilde{V}_{x}^{2} f = \tilde{V}_{x}^{4} A^{2} f .$$
 (6.11)

It is noteworthy that for the representations to be equivalent the Banach spaces need not be isometric.

In the previous subsection the complete series representations were characterized by a pair of paremeters (s, ρ) where s in an integer or halfinteger, and ρ is a complex number. We will now show that the complete series representations characterized by s = 0 and ρ satisfying $0 < -i\rho < 2$ are equivalent to the complementary series representations.

The space of representations of the complete series representations corresponding to s = 0 was defined in the previous subsection as the Hilbert space $L_2^o(SU_2)$. The space of representations of the complementary series was defined as the Hilbert space H_a. These spaces correspond to B¹, B² respectively in the definition of equivalence. Now, the crucial point is this: if V_g^1 is a complementary series representation corresponding to a value σ of the parameter, and V_g^2 is a complete series representation corresponding to the values s = 0, $\rho = i\sigma$, then the representation V_g^1 , V_g^2 are given in the two Banach spaces by the same formula (Eq. (6.1), (6.2) and Eqs. (5.4), (5.5) respectively). It follows now that the sets Ω^1 , Ω^2 corresponding to a given representation in the Banach spaces $L_2^o(SU_2) \stackrel{\text{(SU}}{+} H_{\sigma}$ are the same, because both consists of all the finite linear combinations of the vectors V_x^{ξ} where ξ is any of the functions $T_{om}^j(u)$. (V_x was defined in footnote 25). The operators A^1 , A^2 in the definition of equivalence are trivially defined now as the identity operators in $\Omega^1 = \Omega^2$ and $\Omega^{*1} = \Omega^{*2}$ respectively. One can easily check that they satisfy Eqs. (6.9) - (6.11). Therefore any complementary series representation, corresponding to a value σ is equivalent to the complete series representation characterized by the pair of parameters s = 0, $\rho = i\sigma$.

C. Relation to Spinors

In introducing the complete series we restricted the values of its parameter $(s_{1,0})$ by excluding the representations for which

$$\rho^2 = -4 (|s| + k)^2, k = 1, 2, 3, ...$$
 (6.12)

We now consider the representations corresponding to Eq. (6.12) and show that:

(i) the representations realized by the general formula for the complete series, Eqs. (6.1), (6.2), are not irreducible if Eq. (6.12) is satisfied;

(ii) when the general formulas (6.1), (6.2) of the complete series apply to a finite-dimensional linear space of polynomials over SU_2 , instead of an infinite-dimensional Hilbert space, they realize the spinor representations;

(iii) the generalized Fourier transform of these polynomials is related to the standard form of 2-component spinors by a linear transformation, which is explicitly derived.

(i) To see that indeed when $p^2 = -4 (|s| + k)^2$ the representation (6.1) is not irreducible we proceed as follows.

Suppose that $\rho = -2i(|s| + k)$ and denote by P_{MN} the set of all homogeneous polynomials in u_{21} , \bar{u}_{21} , u_{22} and \bar{u}_{22} :

$$p(u) = \sum_{\alpha_{1}, \beta_{1}, \gamma_{1}, \sigma} u_{21}^{\alpha} u_{21}^{\beta} u_{21}^{\gamma} u_{21}^{\gamma} u_{21}^{\gamma} u_{21}^{\gamma} u_{21}^{\gamma} (6.13)$$

with the conditions

$$\alpha - \beta + \gamma - 5 = 2s$$
 (6.14)

$$\alpha + \beta + \beta + \delta = 2|s| + 2k - 2$$
 (6.15)

where $k = 1, 2, 3, \ldots$ One can easily see, using Eq. (6.14) that

$$p(y'u) = e^{is \psi} p(u)$$
(6.16)

where Y is given by (4.4). Therefore P_{MN} is a subspace of the Hilbert space L_2^{2s} (SU₂). We show that P_{NN} is invariant with respect to the operator V_g of Eq. (6.1). To this end one writes

$$g = u_1 e u_2 , \qquad (6.17)$$

where u_1 , $u_2 \in SU_2$ and ϵ is given by

$$\boldsymbol{\xi} = \begin{pmatrix} \boldsymbol{\xi}_{21}^{-1} & \boldsymbol{\upsilon} \\ \boldsymbol{\upsilon} & \boldsymbol{\xi}_{21} \end{pmatrix}$$
(6.18)

with ϵ_{22} a real number. Since $V_g = V_u V_{\epsilon} V_{u_2}$, it is sufficient to show

that P_{MN} is invariant under each of the operators V_{u_1} , V_e and V_{u_2} . Now

$$V_{u,} p(u) = \frac{\alpha(uu,)}{\alpha(u\overline{u},)} p(u\overline{u},) \qquad (6.19)$$

It is shown in Sec. 4B that α (uu₁) / α ($i\bar{u}_1$) is equal to exp (2 is A), where Λ is an arbitrary real number. Also, a direct calculation, using Eq. (4.31) shows that

$$p(uu_{1}) = \sum_{\alpha, \beta, \gamma, s} e^{i\Lambda(-\alpha + \beta - \gamma + s)} \alpha_{\alpha\beta\gamma5}$$

$$\times (uu_{1})_{\alpha}^{\alpha} (uu_{1})_{\alpha}^{\beta} (uu_{1})$$

Hence, using the condition (6.14) one obtains

$$V_{u, p}(u) = p(uu,)$$
 (6.21)

which shows that P_{Mi} is invariant with respect to the operator V_{u_1} (and, of course, to V_{u_2}).

Similarly, $\mathbf{P}_{\mathbf{MN}}$ is invariant with respect to \mathbf{V}_{ε} , where

$$V_{\varepsilon} p(u) = \frac{\alpha(u\varepsilon)}{\alpha(u\varepsilon)} p(u\varepsilon). \qquad (6.22)$$

In Sec. 4B it is shown that $\alpha(u\varepsilon) / \alpha(u\overline{\varepsilon})$ is equal to exp. (2 is A) $|\lambda|^{i^{\rho}} - 2$, where $|\lambda|$ is given by Eq. (4.34). Furthermore, one easily verifies that

$$p(u\bar{z}) = \sum_{u,p,\gamma,s} e^{i\Lambda(-u+\beta-\gamma+s)} |\lambda|^{-(u+\rho+\gamma+s)} \bar{z}_{2\lambda}^{-u-\rho+\gamma+s}$$

$$\times a_{u,p\gamma r} u_{2\lambda}^{u} \bar{u}_{2\lambda}^{r} u_{2\lambda}^{s} \bar{u}_{2\lambda}^{s} . \qquad (6.23)$$

Using the conditions (6.14) and (6.15) and the fact that $\rho = -2i(|s| + k)$, one finds

$$V_{\epsilon} p(u) = \sum_{\substack{a,p,g,r}} \varepsilon_{2a}^{-a-p+r+s} \alpha_{aprs} u_{2i}^{a} \overline{u}_{2i}^{b} u_{2i}^{r} \overline{u}_{2i}^{r}. \quad (6.24)$$

This shows that $V_{e}p(u)$ is a polynomial in the space P_{MN} . Hence P_{MN} is invariant with respect to the operator V_{g} , and therefore the representation (6.1) is not irreducible when $\rho = -2i(|s| + k)$, $k = 1, 2, 3, \dots$ ²⁹

(ii) We now show that the operators defined by Eqs. (6.1), (6.2) which realize all the infinite-dimensional irreducible representations of SL(2, C), realize the spinor representations as well, if the space of the representations is properly defined as a space of polynomials over SU₂.

Starting from Eq. (3.9) let us denote $p(z, \overline{z})$ by f(z) and let

$$\alpha(g) = g_{33}^{m} - g_{33}^{m}$$
 (6.25)

where

$$g = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$$
(6.26)

is an element of SL(2, C). Equation (3.7) can then be written in the form

$$T_g f(z) = \alpha(zg) f(z\bar{g}).$$
 (6.27)

Here z denotes a complex variable and also the matrix

$$\mathcal{Z} = \begin{pmatrix} 1 & \upsilon \\ 2 & 1 \end{pmatrix}, \tag{6.28}$$

and the matrix $z^* = z\bar{g}$ amounts to a transformation in which the variable z goes over into the new variable

$$3' = g_{21} / g_{22} , \qquad (6.29)$$

where the matrix g' ε SL(2, C) is given by

$$g' = 3g = \begin{pmatrix} g_{11} & g_{12} \\ g_{11}3 + g_{21} & g_{12}3 + g_{12} \end{pmatrix}.$$
(6.30)

So that the new variable z^* , according to (6.29) and (6.30) is given by

$$3' = \frac{g_{11}3 + g_{11}}{g_{12}3 + g_{22}}$$
(6.31)

If now we write

$$\psi(u) = \pi \frac{\gamma_{2}}{\chi(u)} \frac{f(z)}{f(z)}$$
 (6.32)
45

where u, z, $\epsilon \tilde{z}$, ³⁰ and $z = u_{21}/u_{22}$, then

$$\phi(u) = \pi^{\gamma_2} \sum_{r=0}^{m} \sum_{s=0}^{n} p_{rs} u_{z_1}^r u_{z_2}^{m-r} \overline{u}_{z_1}^s \overline{u}_{z_2}^{n-s}. \quad (6.33)$$

Hence ϕ (u) runs through all polynomials which are homogeneous in u_{21} , u_{22} of degree m and in \bar{u}_{21} , \bar{u}_{22} of degree n, and p_{rs} are related to spinors by (3.10). Let \tilde{P}_{mn} denote the set of all such polynomials. Then \tilde{P}_{mn} is the set of all polynomials homogeneous of degree m + n in u_{21} , u_{22} , \bar{u}_{21} , \bar{u}_{22} , satisfying the condition

$$\phi(\gamma u) = e^{i(m-n)\psi/2} \phi(u), \qquad (6.34)$$

where γ is given by Eq. (6.14). The operators of the representation in the space \widetilde{P}_{min} are then given by the formula

$$T_{g} \phi(u) = \frac{\alpha(ug)}{\alpha(ug)} \phi(u\overline{g}) , \qquad (6.35)$$

where \oint (u) \in \widetilde{P}_{mn} and ug is a matrix of SU₂ whose explicit expression is given in Sec. 4B. Comparison of (6.25) with (6.2) gives

$$m = \frac{i}{2}f + p - l, \quad h = \frac{i}{2}f - p - l.$$
 (6.36)

We have, in fact, obtained already this space of polynomial in part (i) of the present section as that subspace of $I_2^{2s}(SU_2)$ which is invariant under the representation. Indeed, using Eqs. (6.14); (6.15) and (6.36) one obtains

$$y = m - \alpha, \quad 5 = n - \beta.$$
 (6.37)

Eq. (6.13) can now be written as

$$p(u) = \sum_{d=0}^{m} \sum_{p=0}^{n} \alpha_{dp} \ u_{11}^{d} \ \overline{u_{21}}^{p} \ u_{11}^{n-d} \ \overline{u_{22}}^{n-d}.$$
(6.38)

Comparing (6.38) with (6.33) we see that $a_{\alpha\beta}$ is just $\pi^{\frac{1}{2}} p_{rs}$. Hence $a_{\alpha\beta}$ is related to spinors, by (3.10), by

$$\alpha_{x/3} = \pi \frac{1}{2} m \ln \frac{1}{2} \phi_{A_1 \dots A_m \times 1} \times n \qquad (6.39)$$

with

$$A_1 + A_2 + ... + A_m = \alpha, \quad X_1 + X_2 + ... + X_n = \beta.$$

and the representations (6.35) is indeed a realization of the spinor representations.

(iii) We are now in a position to find the connection between spinors and the generalized Fourier transform p_m^j in the finite-dimensional case. Since $p(u) \in L_2^{2s}(SU_2)$, one can expand it into a finite series in $T_m^j(u)$

$$p(u) = \sum_{j=j+1}^{J} (2j+1) \sum_{m=-j}^{J} \phi_{m}^{j} T_{m}^{j}(u) \quad (6.40)$$

where ϕ_m^j is related to p(u) by

$$\dot{p}_{m} = \int p(u) T_{sm}^{J}(u) clu.$$
 (6.41)

Using the expression (6.38) for p(u) in (6.41) one obtains

$$\phi_{m}^{j} = \sum_{\alpha=0}^{M} \sum_{\beta=0}^{M} \widetilde{C}_{m\alpha\beta}^{j} \alpha_{\alpha\beta} \qquad (6.42)$$

where $\widetilde{C}_{m\alpha\beta}^{j^{\vee}N}$ are some numerical coefficients,

$$\tilde{C}_{map}^{jMN} = \int T_{sm}^{-j}(u) \ u_{2i}^{a} \ \overline{u_{2i}}^{a} \ u_{12}^{N-a} \ \overline{u_{2i}}^{N-a} \ du. \quad (6.43)$$

And in terms of 2-component spinors, by Eq. (6.39), one obtains .

48

$$\phi_{m}^{j} = \sum_{\alpha=0}^{M} \sum_{p=0}^{N} C_{m\alpha\beta}^{jMN} \phi_{\alpha,\dots,\alpha_{M}} \dot{x}_{1}\dots\dot{x}_{N} \qquad (6.44)$$

where

$$C_{map}^{\text{JMN}} = TT^{\frac{1}{2}} M! N! \widetilde{C}_{map}^{\text{JMN}}$$
(6.45)

Here $A_1 + \cdots + A_n = \alpha$, $\dot{X}_1 + \cdots + \dot{X}_N = \beta$.

The generalized Fourier transform p_m^j is, therefore, related to the spinors $p_{A_1 \cdots A_N X_1 \cdots X_N}$ via a linear transformation. Given explicitly by Eqs. (6.43), (6.45) as an integral over the group SU₂.

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It is a pleasure to thank Professor A. O. Barut for suggestions and critical comments. We also wish to thank Mr. J. Berning for his help in organizing the material. Finally, we would like to apologize to the authors, whose contributions were not referred to. The literature on the Lorentz group and its applications is so extensive that some selectivity, based on the authors' background and interests is unavoidable.

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FOOTNOTES

- 1. See, for example, the session on infinite-dimensional representations of particles in Magen, Guralnik, and Mathur (1967).
- 2. See, for example, the monograph of Streater and Wightman (1964).
- 3. See, Nambu (1966, 1967a); Barut and Kleinert (1967a, b); Burut, Corrigan, and Kleinert (1968a, b); Eronodal (1967a, b); Bohm (1967); Takabayashi (1967); Atarbanel and Frishnan (1968); Chodos (1970); Chodes and Haymaker (1970); Humi and Malin (1969); Noga (1970); Kursunoglu (1968); Aghassi, Roman, and Sanbilli (1970); Komar and Slad (1969); Bisiacchi, Colucci, and Fronsdal (1969).
- 4. One of the first systems which was described by infinite-dimensional wave equations was the non-relativistic H-atom (Fronsdal 1967b; Barut and Kleinert 1967c, d, e; Nambu 1967b; Kleinert 1968). More recently, an equation which describes the relativistic H-atom was obtained by Rarut and Raiquni (1969a, b). The relation of the Majorana equation to the two-dimensional Schrodinger equation was also investigated by Biedenharn and Giovannini (1967), Morita (1969), Barut and Duru (1971).
- 5. See, Domokos, Kovesi-Domokos, and Mansouri (1970a, b); Domokos, Kovesi-Domokos, and Schonberg (1970); Bacry and Nuyts (1967); Watanabe and Niyazaki (1969); Matsumoto (1970); Morita (1970); Fars and Gursey (1971).

51

- 6. See also Barut's review of hadron symmetries (Barut 1970). The relationship between current algebra and infinite dimensional equations were recently reviewed by O'Raifeartaigh (1969) and Niederer and O'Raifeartaigh (1970).
- 7. Spinors have also been of great importance in general relativity theory. For reviews of applications of spinors in general relativity see Penrose (1960), Firani (1965), and Carmell and Fickler (1972).
- 8. For details see Streater and Wightman (1964).
- 9. These matrices are given by

$$\mathbf{a_{l}}(\Psi) = \begin{pmatrix} \mathbf{l} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \cos \Psi & -\sin \Psi & \mathbf{0} \\ \mathbf{0} & \sin \Psi & \cos \Psi & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{l} \end{pmatrix}, \dots,$$

and

$$\mathbf{b}_{\underline{1}}(\Psi) = \begin{pmatrix} c, sh \Psi & 0 & 0 & sinh\Psi \\ 0 & & 0 \\ 0 & & 0 \\ cinh\Psi & 0 & 0 & cost\Psi \end{pmatrix}, \dots$$

1% The a_r and b_r are related to $a_r(\Psi)$ and $b_r(\Psi)$ by $a_r(\Psi) = \exp(\Psi a_r), b_r(\Psi) = \exp(\Psi b_r),$

and are given by

$$\mathbf{a}_{1} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}, \dots, \mathbf{b}_{1} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \dots$$

- 11. $A_r(\Psi)$ and $B_r(\Psi)$ are continuous functions of Ψ and are called basic oneparameter groups of operators for the given representation. They satisfy the relations $A_r(\Psi_1) A_r(\Psi_2) = A_r(\Psi_1 + \Psi_2)$, $B_r(\Psi) \perp_r(\Psi_2) = B_r(\Psi_1 + \Psi_2)$. $A_r(0) = 1$, $B_r(0) = 1$. If the representation is finite-dimensional then the operators $A_r(\Psi)$ and $B_r(\Psi)$ are differentiable functions of Ψ . If the representation is infinite-dimensional, however, these operators might be non-differentiable (see footnote 1)).
- 12. $A_r(\Psi)$ and $B_r(\Psi)$ might then be expanded in terms of A_r and B_r as $A_r(\Psi) = \exp(\Psi A_r)$, $B_r(\Psi) = \exp(\Psi B_r)$.
- 13. In general, let A(t) be a continuous one-parameter group of operators in a Banach space R, and denote by X(A) the set of all vectors $x \in R$ for which the limit of (A(t) x-x)/t, when $t \rightarrow ($ exists in the sense of

the norm in R. Obviously the set X(A) contains the vector x = 0. Define now the operator A for all x ϵ X(A) by Ax = lim $\{(A(t) | x - x)/t\}$ at the limit t \rightarrow 0. The domain of definition, X(A), of the operator A is a subspace of R, and A is linear, i.e., $A(\lambda_1 x_1 + \lambda_2 x_2) =$ $\lambda_1 A x_1 + \lambda_2 A x_2$ for $x_1, x_2 \in X(A)$. Such an operator A is called the infinitesimal operator of the one-parameter group A(t). If A(t) = $T_a(t)$ is the group of operators of the representation $g \rightarrow T_g$, corresponding to a one-parameter subgroup a(t) of the group L, the corresponding operator A is then called the <u>infinitesimal operator</u> of the representation $g \rightarrow T_g$.

- 14. The superscript in f_m^j specifies the subspace uniquely since each irreducible representation of 0_3 is contained at most once in any given irreducible representation of the group L.
- 15. Eqs. (2.8), for unitary representations case and under certain assumptions, were first obtained by Gel'fand (see Naimark (1964). p. 117); they later were rederived by Harish-Chatdra (1947a, 1947b), and by Gel'fand and Iaglom (1948).
- 16. For the physical significance of non-unitary representations see Barut and Malin (1968.).

- 17. A representation $g \to T_g$ of a group G in a space R is called unitary if R is a Hilbert space and T_g is a unitary operator for all $g \in G$. This implies that $(T_g x, T_g y) = (x, y)$ for all $g \in G$ and all $x, y \in R$, where (x, y) denotes the scalar product in R.
- 12. An operator B is called an adjoint to the operator A if (Ax, y) = (x, By) for all x, y $\in \mathbb{R}$.
- 19. Compare the analoguous formulas for the rotation group given by Eqs. (2.10) and (2.11) in Carmeli (1968). Eqs. (3.5) can easily be proved by finding the value of the expression $(\frac{1}{2})$ Tr $(\sigma^{\alpha}a\sigma^{\beta}a^{\dagger})_{\beta} =$ $(\frac{1}{2})$ Tr $(\sigma^{\alpha}a\sigma^{\beta}x_{\beta}a^{\dagger}) = (\frac{1}{2})$ Tr $(\sigma^{\alpha}aQa^{\dagger}) = (\frac{1}{2})$ Tr $(\sigma^{\alpha}Q^{\bullet}) = (\frac{1}{2})$ Tr $(\sigma^{\sigma}\sigma^{\beta}x_{\beta}) =$ $(\frac{1}{2})$ Tr $(\sigma^{\alpha}\sigma^{\beta})_{\alpha\beta} = \delta^{\alpha\beta}x_{\beta} = x_{\alpha}^{\dagger} = g_{\alpha\beta}x_{\beta}^{\bullet}$.
- 20. These matrices for the group SL(2, C) are given by

$$a_{1}(t) = \begin{pmatrix} \cos \frac{t}{2} & i \sin \frac{t}{2} \\ i \sin \frac{t}{2} & \cos \frac{t}{2} \end{pmatrix}, \qquad b_{1}(t) = \begin{pmatrix} \cosh \frac{t}{2} & \sinh \frac{t}{2} \\ \sinh \frac{t}{2} & \cosh \frac{t}{2} \end{pmatrix}$$

$$a_{2}(t) = \begin{pmatrix} \cos \frac{t}{2} & -\sin \frac{t}{2} \\ \sin \frac{t}{2} & \cos \frac{t}{2} \end{pmatrix}, \qquad b_{2}(t) = \begin{pmatrix} \cosh \frac{t}{2} & i \sin \frac{t}{2} \\ -i \sin \frac{t}{2} & \cos \frac{t}{2} \end{pmatrix},$$

$$a_{3}(t) = \begin{pmatrix} e^{\frac{it}{L}} \\ 0 \\ 0 \\ -\frac{it}{L} \end{pmatrix}, \qquad b_{3}(t) = \begin{pmatrix} e^{\frac{t}{L}} \\ 0 \\ 0 \\ -\frac{t}{L} \end{pmatrix}.$$

21. The integral in Eq. (4.1) and throughout this paper are invariant integrals over the group SU_2 which satisfy the conditions

$$\int f(uu_1) du = \int f(u_1u) du = \int f(u) du$$

for any $u_1 \in SU_2$, and
$$\int f(u^{-1}) du = \int f(u) du$$
$$\int du = 1.$$

- 22. For a different form of realization of the principal series see e.g. Gel'fand, Grae: and Vilenkin (1966).
- 23. Every Euclidean space can be completed to a Hilbert space. See e.g. Naimark (1959, 1964); Lyusternik and Sobolov (1951).
- 24. These functions were recently used by Veneziano (1968) for the construction of crossing-symmetric, Regge-behaved scattering amplitude for linearly rising trajectories.
- 25. It is interesting to note that the definition of the principal and complementary series of representations can be generalized from the group SL(2, C) to SL(N, C) for arbitrary N > 2. However, for N > 2 there exist, in general unitary representations not contained in either the principal or the complete series (Stein, 1967).

56

26. The definition of complete irreducibility is as follows (Naimark 1964): given a representation V_g of the group SL(2, C) on a Banach space B one first defines a bounded linear operator C as admissible if it has the form

$$C \xi = \sum_{i=1}^{n} f_{i} (\xi) e_{i}$$

where $f_1, \ldots, f_n \in \Omega'$ and $e_1, \ldots, e_n \in \Omega$. The definitions of the sets Ω , Ω' are given in Sec. 6B. One then defines the representations as completely irreducible if for every admissible operator C in B there exists a sequence $x_n \in X$ such that $(V_{x_n} \xi, \eta) \rightarrow (C \xi \eta)$ as $n \rightarrow \infty$ for all $\xi \in \Omega_1 \ \eta \in \Omega$. X is the group ring, defined in Sec. 6B, and the operators V_{x_n} are defined in footnote 28. It can be shown that every unitary irreducible representation in a separable Hilbert space is completely irreducible.

- 27. For a definition of equivalence of representations in the sense of the present section see Sec. 6B.
- 23. This definition comes about as follows: given a representation of SL(2,C) as a set of operators V one defines an operator V corresponding to every function $x(g) \in X$ as follows:

 $V_x = \int x(g) V_g dg$

By straightforward calculation one finds that

$$v_{x_1} v_{x_2} = v_{x_1} x_2$$

if $X_1 x_2$ is defined by Eq. (6.7). For further details see Naimark (1964).

- 29. The representation (6.1) is not irreducible also when $\rho = 2i(|s| + k)$, where $k = 1, 2, 3, \dots$, since the pairs (s, p) and (-s, -p) define the same completely irreducible representation.
- 30. \tilde{z} is the set of all matrices kg, where g is an element of SL(2, C), fixed, and k varies through the entire group of matrices of the form given by Eq.(4.11). For more details see Naimark (1964), p.140.

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LIGT OF SYMBOLS

Symbol	Description
Eijk	Levi-Civita skew-symmetric tensor with ϵ_{123} = 1
F+, F-, F3	Infinitesimal generators of the Lorentz group
S	Element of the Lorentz group L or the group $SL(2, C)$
^H +, ^H -, ^H ₃	Infinitesinal generators of the Lorentz group
H, h	Euclidean spaces
H _o , h _o	Hilbert spaces
L	Proper orthochroneous Lorentz group
$L_2^{2s}(SU_2)$	Hilbert space
$L_2(SU_2)$	Hilbert space
L ^{2s} 2	Hilbert space
^N j	Real normalization factor
°3	Three-dimensional pure rotation group
SL(2, C)	Group of all 2x2 complex matrices with determinent unity
SU2	Group of all 2x2 unitary matrices with determinent unity
T ^j mn(u)	Matrix elements of irreducible representations of the
	group SU2
$t_m^{\mathbf{j}}(u)$	Orthogonal set of functions
Tg	Operator
u	Element of the group SU ₂
V g	Operator
x ₁ , x ₂ , x ₃ , x ₄	Space-time coordinates