

AFFDL-TR-69-123
VOLUME IV

AD706919

**A STABILITY AND CONTROL PREDICTION
METHOD FOR HELICOPTERS AND
STOPPABLE ROTOR AIRCRAFT**

**VOLUME IV
APPENDICES**

BILLY J. BIRD
Bell Helicopter Company
A Textron Company

TECHNICAL REPORT AFFDL-TR-69-123, VOLUME IV

MARCH 1970

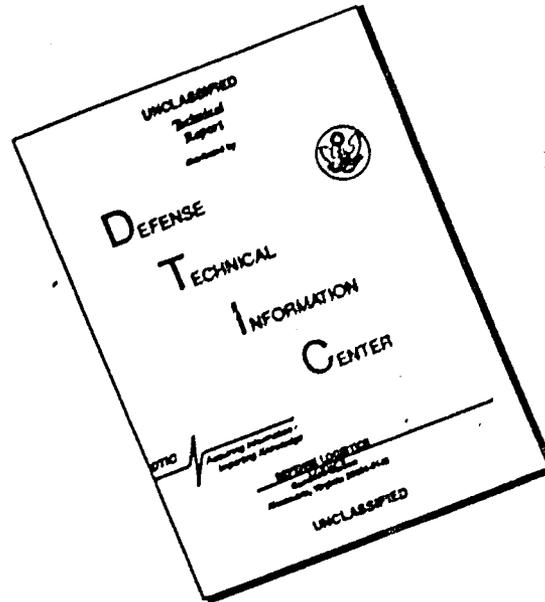
This document has been approved for public release and sale;
its distribution is unlimited.

Reproduced by the
CLEARINGHOUSE
for National Scientific & Technical
Information, Springfield, Va. 22151

AIR FORCE FLIGHT DYNAMICS LABORATORY
AIR FORCE SYSTEMS COMMAND
WRIGHT-PATTERSON AIR FORCE BASE, OHIO

312

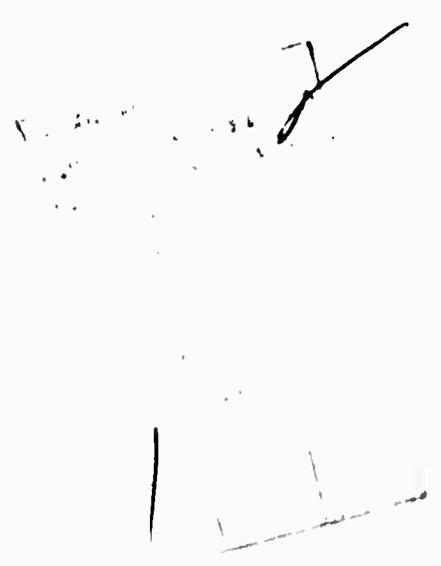
DISCLAIMER NOTICE



THIS DOCUMENT IS BEST QUALITY AVAILABLE. THE COPY FURNISHED TO DTIC CONTAINED A SIGNIFICANT NUMBER OF PAGES WHICH DO NOT REPRODUCE LEGIBLY.

NOTICE

When Government drawings, specifications, or other data are used for any purpose other than in connection with a definitely related Government procurement operation, the United States Government thereby incurs no responsibility nor any obligation whatsoever; and the fact that the government may have formulated, furnished, or in any way supplied the said drawings, specifications, or other data, is not to be regarded by implication or otherwise as in any manner licensing the holder or any other person or corporation, or conveying any rights or permission to manufacture, use, or sell any patented invention that may in any way be related thereto.



Copies of this report should not be returned unless return is required by security considerations, contractual obligations, or notice on a specific document.

**A STABILITY AND CONTROL PREDICTION
METHOD FOR HELICOPTERS AND
STOPPABLE ROTOR AIRCRAFT**

**VOLUME IV
APPENDICES**

BILLY J. BIRD

This document has been approved for public release and sale;
its distribution is unlimited.

FOREWORD

This report represents the results of the efforts expended in performance of Contract F33615-69-C-1121, "Development of Stability and Control Prediction Methods for Stoppable Rotor Aircraft." The work was performed by Bell Helicopter Company under Project No. 8219. It was sponsored by the Air Force Flight Dynamics Laboratory, Air Force Systems Command, from December 1968 through February 1970. Mr. Charles L. Livingston was the Bell Helicopter Company Project Engineer. Mr. Robert Nicholson was the Air Force Project Engineer.

This final report is presented in four volumes. The first describes the mathematical model and the methods used to calculate stability characteristics. They are of sufficient complexity that a digital computer is necessary for the solution of the equations. The second volume presents the results of sample computations and discusses input and output formats and good user techniques. The third volume describes the computer program while the fourth volume contains Appendices which are computer generated documentation of the program.

The author gratefully acknowledges the assistance of Messrs. B. L. Blankenship and Tyce McLarty of the Bell Helicopter Company Aeromechanics Group and Mr. C. L. Livingston of the Stability and Control Group in the development of the mathematical model.

This technical report has been reviewed and is approved.



C. B. Westbrook
Chief, Control Criteria Branch
Flight Control Division
Air Force Flight Dynamics
Laboratory

ABSTRACT

This report describes a mathematical model of rotorcraft that may be used to determine characteristics of performance, stability, response, and rotor blade loads. The complexity of the equations used requires the use of a digital computer for efficient solution. This four volume report describes the computer program in detail and illustrates the method of computing rotorcraft characteristics by specific example.

This volume contains the Appendices. Volume III describes the contents and use of these appendices in detail. The first and second volumes contain a discussion of the mathematical model and detailed instructions for the users of the program.

These appendices, which originate from card images for easy updating, are necessary tools for any programmer working on this program.

TABLE OF CONTENTS

<u>Appendix</u>		<u>Page</u>
A	Variable Definitions	1
B	Subroutines and Commons Containing Each Common and Variable	13
C	Commons and Variables in Each Subroutine and Common	28
D	Subroutines Containing Each Variable, by Common	80
E	Program Sections Containing Each Variable, by Common	102
F	FORTRAN Listing	125

APPENDIX A
VARIABLE DEFINITIONS

A	ARRAY NAME FOR FORCES AND MOMENTS
B	(2) BM AND BTR
C	(21) MAIN ROTOR BLADE WEIGHT DISTRIBUTION
F	(79) TRIM VALUES OF A AND OTHER FORCES
Q	1/2 RHO
R	(2) RM AND RTR
T	MANEUVER TIME
V	VELOCITY - AIR SPEED
W	GROSS WEIGHT
X	(1,7) COMPUTED CORRECTIONS IN TRIM
AH	(3) UPPER SCALE LIMITS FOR PLOT
AL	(3) LOWER SCALE LIMITS FOR PLOT
AP	PITCH ANGLE OF ATTACK OF FUSELAGE
AY	SIDESLIP (NEW VALUE)
BH	(2) .5 * B
BM	MAIN ROTOR NUMBER OF BLADES
C3	CD BEFORE RESOLUTION THROUGH INDUCED ANGLE OF ATTACK
C4	CL BEFORE RESOLUTION THROUGH INDUCED ANGLE OF ATTACK
DT	(21) TAIL ROTOR BLADE WEIGHT DISTRIBUTION
ER	(2) ERM AND ERTR
HL	(2) MAST LENGTHS
IX	FUSELAGE MOMENT OF INERTIA ABOUT X-AXIS (ROLL)
IY	FUSELAGE MOMENT OF INERTIA ABOUT Y-AXIS (PITCH)
IZ	FUSELAGE MOMENT OF INERTIA ABOUT Z-AXIS (YAW)
OR	(2) ORM AND ORTR
PI	3.141593
QL	TOTAL ROLL MOMENT (X-COMPONENT - BODY REFERENCE)
QM	TOTAL PITCHING MOMENT (Y-COMPONENT - BODY REFERENCE)
QN	TOTAL YAW MOMENT (Z-COMPONENT - BODY REFERENCE)
RM	MAIN ROTOR RADIUS
RW	1. / W
T1	(2) T1MT AND T1TT
T2	(2) T2MT AND T2TT
VH	GROUND SPEED
XB	(2) 1. / NXR
XE	TOTAL X-FORCE (BODY REFERENCE)
XK	INTERMEDIATE VARIABLE
XX	GROUND REFERENCE X-COMPONENT OF DISTANCE FLOWN
YF	TOTAL Y-FORCE (BODY REFERENCE)
YY	GROUND REFERENCE Y-COMPONENT OF DISTANCE FLOWN
ZF	TOTAL Z-FORCE (BODY REFERENCE)
ZZ	GROUND REFERENCE Z-COMPONENT OF DISTANCE FLOWN
AGW	GEOMETRIC ANGLE OF ATTACK OF WING RELATIVE TO FUSELAGE CENTERLINE
AIB	(2) ROTOR BLADE INERTIAS
ALT	ALTITUDE
AOR	(2) (EXH / R) **2
APD	FUSELAGE PITCH RATE
APE	PITCH (FIXED - FUSELAGE)
ARD	FUSELAGE ROLL RATE
ARE	ROLL (FIXED - FUSELAGE)
AYD	FUSELAGE YAW RATE
AYE	YAW (FIXED - FUSELAGE)
AY1	SIDESLIP (PREVIOUS VALUE)
AIM	A1 MAIN ROTOR (FORE/AFT FLAPPING)

PTP
 314
 CLP
 CLP
 DCD
 DCL
 DON
 DT2
 DT1
 DT2
 FPD
 FRM
 ERR
 ERX
 EXH
 GOV
 HMR
 HTR
 IND
 IT4
 ITX
 KMI
 LMR
 LTR
 MFR
 MTR
 NMR
 NTR
 OPM
 PFD
 PSD
 OMR
 QMX
 QPC
 QDD
 QTR
 QWS
 RHO
 RHY
 RTP
 R12
 SPD
 SMC
 TMR
 TTR
 T74
 T7D
 T7T
 T14
 T1T
 T24
 T2T
 VIR
 V14

TAIL ROTOR - NUMBER OF BLADES
 B1 MAIN ROTOR (LATERAL FLAPPING)
 SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 DERIVATIVE OF CD WITH RESPECT TO ALPHA
 SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 DEGREES TO RADIAN CONVERSION FACTOR
 (2) F/A SMASHPLATE INPUT FROM FLAT TRACKER
 (2) LAT SMASHPLATE INPUT FROM FLAT TRACKER
 PARTIAL DERIVATIVE INCREMENT FOR TRIM
 MAIN ROTOR ALLOWABLE FLAPPING MOMENT ERROR FOR TRIM
 (10) INPUT ALLOWABLE ERRORS ON TRIM FORCES AND MOMENTS
 (2) ERXM AND ERXTR
 (2) HUB EXTENTS
 FLAG ON ENGINE TORSIONAL SYSTEM - NORMALLY=0
 MAIN ROTOR H-FORCE
 TAIL ROTOR H -FORCE
 FLAG OR SWITCH TYPE VARIABLE
 ITERATION LIMIT TO BALANCE ROTOR FLAPPING MOMENTS IN ITROT
 FUSELAGE PRODUCT OF INERTIA
 NUMBER OF EQUATIONS IN SYSTEM
 X-COMPONENT OF MOMENT DUE TO MAIN ROTOR FORCES
 Y-COMPONENT OF MOMENT DUE TO TAIL ROTOR FORCES
 Y-COMPONENT OF MOMENT DUE TO MAIN ROTOR FORCES
 Y-COMPONENT OF MOMENT DUE TO TAIL ROTOR FORCES
 Z-COMPONENT OF MOMENT DUE TO MAIN ROTOR FORCE
 Z-COMPONENT OF MOMENT DUE TO TAIL ROTOR FORCE
 MAIN ROTOR TIP SPEED
 INTERMEDIATE VARIABLE IN PEDAL CALCULATION
 MAIN ROTOR PSI DOT =OMEGA
 TORQUE REQUIRED TO MAINTAIN CONSTANT RPM ON MAIN ROTOR
 MAIN ROTOR TORQUE
 PROP-ROTOR COLLECTIVE GOVERNOR FLAG - 0 OR 10
 COEFFICIENT FOR CALCULATING ENGINE TORQUE AVAILABLE
 TAIL ROTOR TORQUE
 O* 1/2 AREA OF WING
 AIR DENSITY AT ALTITUDE
 I. / IY
 TAIL ROTOR RADIUS
 I. / IZ.
 (6,6,3) RATE DERIVATIVES IN STAB
 (2) SIDEMASH COEFFICIENTS
 MAIN ROTOR THRUST
 TAIL ROTOR THRUST
 MAIN ROTOR ROOT COLLECTIVE PITCH FROM CONTROLS
 (2) TZMT AND TZTT
 TAIL ROTOR ROOT COLLECTIVE PITCH FROM CONTROLS
 MAIN ROTOR F/A CYCLIC PITCH FROM CONTROLS
 TAIL ROTOR F/A CYCLIC PITCH FROM CONTROLS
 MAIN ROTOR LATERAL CYCLIC PITCH FROM CONTROLS
 TAIL ROTOR LATERAL CYCLIC PITCH FROM CONTROLS
 (2) VIMP AND VITR
 DOWNWARD VELOCITY ON WING FROM M.R. INDUCED VELOCITY

VI2
VI4
VXB
VXS
VYB
VYS
VZB
VZS
XAR
XAR
EFL
EFR
EFC
EFN
EFS
EFW
EGN
EIT
EMA
EMN
EMR
ETR
EMC
XKD
VAR
VFL
VFN
VFS
VFW
VWR
VTR
VWG
VYD
ZAR
ZFW
ZLN
AIBP
AIBP
ALE1
ALGF
AP3G
APDR
APFP
APTD
ARAG
ARDP
APTD
ASEP
AVRC
AVFP
AATA
BLCG

.5 0 VROT 002
VI2 002
FUSELAGE X VELOCITY
X-COMPONENT OF VROT IN SWASHPLATE REFERENCE
FUSELAGE Y VELOCITY
Y-COMPONENT OF VROT IN SWASHPLATE REFERENCE
FUSELAGE Z VELOCITY
Z-COMPONENT OF VROT IN SWASHPLATE REFERENCE
(2) X MOMENT ARM OF ROTOR HUB
(2) Y MOMENT ARM OF ROTOR HUB
(14) ELEVATOR GROUP INPUTS
(7) ALLOWABLE ERROR GROUP INPUTS
(28) FLIGHT CONSTANTS GROUP INPUTS
(7) FIN / RUDDER GROUP INPUTS
(35) FUSELAGE GROUP INPUTS
X-FORCE DUE TO WEIGHT
(7) WEAPONS GROUP INPUTS
(21) ITERATION LIMITS GROUP INPUTS
(2) XMAI AND XMAIT
(7) XMBI AND XMBIT
(49) MAIN ROTOR GROUP INPUTS
(49) TAIL ROTOR GROUP INPUTS
(21) WING GROUP INPUTS
X COMPONENT OF VELOCITY - FIXED AXES
(2) Y MOMENT ARM OF ROTOR HUB
(21) INPUT CLCD CONSTANTS FOR ELEVATOR
(21) INPUT CLCD CONSTANTS FOR FIN
(14) COEFFICIENTS FOR CALCULATING FUSELAGE FORCES AND MOMENTS
Y-FORCE DUE TO WEIGHT
(21) INPUT CLCD CONSTANTS FOR MAIN ROTOR
(21) INPUT CLCD CONSTANTS FOR TAIL ROTOR
(21) INPUT CLCD CONSTANTS FOR WING
Y COMPONENT OF VELOCITY - FIXED AXES
VELOCITY OF SHIP CG DUE EAST IN FIXED REFERENCE
(2) Z MOMENT ARM OF ROTOR HUB
Z-FORCE DUE TO WEIGHT
RATE OF DESCENT
(2) AIBPM AND AIBPT
(2) AIBRM AND AIBRT
TOTAL ANGLE OF ATTACK OF ELEVATOR
FIN GEOMETRIC ANGLE
E-4. PITCH FUSELAGE - GUN
(7) APTD AND APTTD
E-4. PITCH FIXED - FLIGHT PATH
MAIN ROTOR INSTANTANEOUS PITCH VELOCITY OF TIP PATH PLANE
CONSTANT, $\dot{\theta}$
(2) ARTD AND ARTTD
MAIN ROTOR INSTANTANEOUS ROLL VELOCITY OF TIP PATH PLANE
YAW PILOT VARIABLE
E-4. YAW FUSELAGE - GUN
E-4. YAW FIXED - FLIGHT PATH
AT TAIL ROTOR
(2) R 0 AIB
OUTLINE LOCATION OF C.G.

BMTC	COEFFICIENT OF X DOT IN BOBWEIGHT EQUATION
BWTK	COEFFICIENT OF X IN BOBWEIGHT EQUATION
BWTH	CONSTANT MULTIPLIER OF (G - G PRELOAD) IN BOBWEIGHT EQUATION
B1TR	B1 TAIL ROTOR
CDMB	(2) CD FOR MJB SEGMENTS
CGWL	CURRENT WATERLINE LOCATION OF CENTER OF GRAVITY
CLBO	SEE USERS GUIDE TO INPUT FORMAT. WING GROUP
CNBO	SEE USERS GUIDE TO INPUT FORMAT. WING GROUP
COLL	(6) INTERMEDIATE VARIABLES IN COLLECTIVE LINKAGES
CYCF	(3) INTERMEDIATE VARIABLES IN F/A CYCLIC LINKAGES
CYCL	(3) INTERMEDIATE VARIABLES IN LAT CYCLIC LINKAGES
CZET	COSINE OF ZETA
DAMP	MAXIMUM ERROR FOR XLIMIT HALVING IN TRIM
DEPD	(10) INCREMENTS USED FOR CALCULATING PD IN TRIM
DIST	DISTANCE FLOWN
DPIX	$IX / (IX^2 + IZ^2 - IXZ \cos 2\epsilon)$
DPIZ	$IZ / (IX^2 + IZ^2 - IXZ \cos 2\epsilon)$
DPSI	(2) CHANGE IN PSI BETWEEN AZIMUTH POSITIONS
DTRR	RADIANS TO DEGREES CONVERSION FACTOR
EPDS	PARTIAL DERIVATIVE INCREMENT FOR STAB
EPDX	(10) UNIT CONVERSION FACTOR IN APPLYING CORRECTIONS IN RATE
FRTR	TAIL ROTOR ALLOWABLE FLAPPING MOMENT ERROR FOR TRIM
ERYM	MAXIMUM ERROR FOR HALVING XLMAX
ERTX	MAXIMUM ERROR FOR HALVING LMAX
FTAQ	CORRECTION TO DYNAMIC PRESSURE AT ELEVATOR DUE TO WING WAKE
FXIT	ERROR INDICATOR -NOT ZERO INDICATES ERROR AND TERMINATES JOB
FHPT	(2) FLAPPING HINGE POINTS
GFWD	G-LEVEL IN FUSELAGE X-DIRECTION
GLAY	G-LEVEL IN FUSELAGE Y-DIRECTION
ICOM	(49) COMMENTS
IPSN	PROBLEM SERIAL NUMBER
KCIT	(20) VALUES OF J ON MANEUVER
LELE	X-COMPONENT OF MOMENT DUE TO ELEVATOR
LFIN	X-COMPONENT OF MOMENT DUE TO FIN
LFUS	X-COMPONENT OF MOMENT DUE TO FUSELAGE
LGUN	X-COMPONENT OF MOMENT DUE TO GUN
LINK	SEGMENT INDICATOR TRIM=2 STAB=3 MANEUVER=4
LLWG	X-COMPONENT OF MOMENT DUE TO LEFT WING
LQMR	MAIN ROTOR TORQUE - X COMPONENT
LQTR	TAIL ROTOR TORQUE - X COMPONENT
LROT	(2) COUNTERS FOR ROTORS, USED IN WAG
LRWG	X-COMPONENT OF MOMENT DUE TO RIGHT WING
MASS	TOTAL MASS
MELE	Y-COMPONENT OF MOMENT DUE TO ELEVATOR
MEIN	Y-COMPONENT OF MOMENT DUE TO FIN
MFUS	Y-COMPONENT OF MOMENT DUE TO FUSELAGE
MGUN	Y-COMPONENT OF MOMENT DUE TO GUN
MLWG	Y-COMPONENT OF MOMENT DUE TO LEFT WING
MQMR	Y-COMPONENT OF MOMENT DUE TO MAIN ROTOR TORQUE
MQTR	Y-COMPONENT OF MOMENT DUE TO TAIL ROTOR TORQUE
MRWG	Y-COMPONENT OF MOMENT DUE TO RIGHT WING
NELE	Z-COMPONENT OF MOMENT DUE TO ELEVATOR
NEIN	Z-COMPONENT OF MOMENT DUE TO FIN
NEFUS	Z-COMPONENT OF MOMENT DUE TO FUSELAGE

NGUM	Z-COMPONENT OF MOMENT DUE TO GUN
NJET	NUMBER OF JETS
NLWG	Z-COMPONENT OF MOMENT DUE TO LEFT WING
NPSI	(2) NUMBER OF AZIMUTH STATIONS
NO4R	Z-COMPONENT OF MOMENT DUE TO MAIN ROTOR TORQUE
NOTR	Z-COMPONENT OF MOMENT DUE TO TAIL ROTOR TORQUE
NRWG	Z-COMPONENT OF MOMENT DUE TO RIGHT WING
NWAG	INDICATOR- 1=USE WAGNER-BUETTNER FUNCTIONS 0=DON'T
ORTR	TAIL ROTOR TIP SPEED
PEDA	(3) INTERMEDIATE VARIABLES IN PEDAL LINKAGE
PHOM	(2) PHOMM AND PHOMT
PSDD	PSI DOUBLE DOT
PSDT	TAIL ROTOR ANGULAR SPEED -PSI DOT
PSID	(2) PSD AND PSOT
QELE	Q* AREA OF ELEVATOR
QFIN	Q* AREA OF FIN
QMAX	MAXIMUM ENGINE TORQUE AVAILABLE
QMRS	ENGINE TORQUE SUPPLIED - TOTAL
OSVI	TORQUE AT TRIM POINT
RAIB	(2) 1. / AIB
RMOM	(2) RMOMM AND RMOHT
ROTJ	SIGN CHANGER, +1. = MAIN ROTOR, -1. = TAIL ROTOR
RTRP	(2) 1. / (TMOPI * RHO * R **2)
R550	1. / 550
SZET	SINE OF ZETA
TAXL	AUXILIARY THRUST LEFT
TAXR	AUXILIARY THRUST RIGHT OR CENTER
TIME	T - .05 * TDELTA USED IN COMPARISONS INSTEAD OF T
TMAX	STOP TIME FOR TDELTA CURRENTLY IN USE
TZMS	MAIN ROTOR COLLECTIVE IF LOCKED
TZMT	MAIN ROTOR TOTAL ROOT COLLECTIVE
TZTT	TAIL ROTOR TOTAL ROOT COLLECTIVE
TIMS	MAIN ROTOR F/A CYCLIC IF LOCKED
TIMT	MAIN ROTOR TOTAL F/A CYCLIC
TITS	TAIL ROTOR F/A CYCLIC IF LOCKED
TITT	TAIL ROTOR TOTAL F/A CYCLIC
T2MS	MAIN ROTOR LAT CYCLIC IF LOCKED
T2MT	MAIN ROTOR TOTAL LAT CYCLIC
T2TS	TAIL ROTOR LAT CYCLIC IF LOCKED
T2TT	TAIL ROTOR TOTAL LAT CYCLIC
VIER	DOWNWARD VELOCITY ON ELEVATOR FROM ON M.R. INDUCED VELOCITY
VIMR	MAIN ROTOR INDUCED VELOCITY
VITR	TAIL ROTOR INDUCED VELOCITY
VROT	VELOCITY OF THE ROTOR HUB
VSND	RECIPROCAL OF THE SPEED OF SOUND
WLCG	WATERLINE LOCATION OF CENTER OF GRAVITY
XAWG	X ARM OF THE WING
XCON	(63) CONTROLS GROUP INPUTS
XFMR	X-FORCE DUE TO MAIN ROTOR
XFTR	X-FORCE DUE TO TAIL ROTOR
XJET	(14) JET GROUP INPUTS
XK43	INTERMEDIATE VARIABLE
XLNK	(14) CONTROL LINKAGE RATIOS
XMAI	MAIN ROTOR LATERAL FLAPPING MOMENT

XMB1 MAIN ROTOR F/A FLAPPING MOMENT
 XMIN LOWER LIMIT ON VALUES OF XLIMIT
 YFIN (2) SAVED VALUES OF FIN LIFT -FOR DAMPING ON UNSTEADY AERODYNAMICS
 YFHR Y-FORCE DUE TO MAIN ROTOR
 YFTR Y-FORCE DUE TO TAIL ROTOR
 YHRF MAIN ROTOR Y-FORCE
 YTRF TAIL ROTOR Y -FORCE
 ZAWG Z ARM OF THE WING
 ZETA MAIN ROTOR MAST TILT ANGLE
 ZFEL (2) SAVED VALUES OF FLEVATOR LIFT - FOR UNSTEADY AERODYNAMICS
 ZFMR Z-FORCE DUE TO MAIN ROTOR
 ZFTR Z-FORCE DUE TO TAIL ROTOR
 ZZTR TAIL ROTOR ALTITUDE
 AIRPM MAIN ROTOR LAT FLAPPING MOMENT DESIRED
 AIRPT TAIL ROTOR LAT FLAPPING MOMENT DESIRED
 AIRRM MAIN ROTOR F/A FLAPPING MOMENT DESIRED
 AIRRT TAIL ROTOR F/A FLAPPING MOMENT DESIRED
 ALCYP ANGLE FOR AILERON EFFECT
 ALERT OFF/ON INDICATOR ON YAW PILOT
 ALFIN TOTAL ANGLE OF ATTACK OF THE FIN
 ALGEZ COEFFICIENT USED IN COMPUTING ELEVATOR ANGLE OF ATTACK
 ALGE1 COEFFICIENT USED IN COMPUTING ELEVATOR ANGLE OF ATTACK
 ALGE2 COEFFICIENT USED IN COMPUTING ELEVATOR ANGLE OF ATTACK
 ALLWG TOTAL ANGLE OF ATTACK ON THE LEFT WING
 ALRWG TOTAL ANGLE OF ATTACK ON THE RIGHT WING
 APTTD TAIL ROTOR INSTANTANEOUS PITCH VELOCITY OF TIP PATH PLANE
 ARTTD TAIL ROTOR INSTANTANEOUS ROLL VELOCITY OF TIP PATH PLANE
 AYOMX MAXIMUM YAW RATE
 AYEFP SIDESLIP INDICATOR
 AIBAL A1 AFTER MOMENT BALANCE IN STAB
 RFTA7 (2) PRECONES
 RNPST = NUMBER OF BLADES / NUMBER OF AZIMUTH STA.
 RIBAL R1 AFTER MOMENT BALANCE IN STAB
 CDOLF CD ON ELEVATOR
 COFIN CD ON FIN
 CDLWG CD ON LEFT WING
 CDRWG CD ON RIGHT WING
 CGSTA CURRENT STATION LINE LOCATION OF CENTER OF GRAVITY
 CLACL SEF USERS GUIDE TO INPUT FORMAT, WING GROUP
 CLELE CL ON ELEVATOR
 CLFIN CL ON FIN
 CLLWG CL ON LEFT WING
 CLRWG CL ON RIGHT WING
 CLRWG COLLECTIVE LOCK INDICATOR 0=OFF / 1=ON
 CNACL SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 CNPCD SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 CNPCL SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 CNRCD SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 CNRCL SEE USERS GUIDE TO INPUT FORMAT, WING GROUP
 COLKS SAVED VALUE OF COLSTK
 CONDI CONDITIONAL OUTPUT INDICATOR
 COND2 CONDITIONAL OUTPUT INDICATOR
 CPWIC COLLECTIVE PITCH WING INCIDENCE COUPLING FACTOR
 CWWG WING CHORD -MEAN AERODYNAMIC CHORD = SORT(AREA/AR)

CYCR1	INTERMEDIATE VARIABLE BETWEEN F/A CYCLIC STICK AND ROTOR
CYCR2	INTERMEDIATE VARIABLE BETWEEN LATERAL CYCLIC STICK AND ROTOR
CZET4	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
CZET6	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
CZET9	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
DCAFR	(2) TIP VORTEX EFFECT COEFFICIENTS
DELTA	DELTA TIME FOR RUNGE-KUTTA
DIXZ	IX - IZ
DIYIX	IY - IX
DIZIY	IZ - IY
DPIXZ	IXZ / (IX * IZ - IXZ **2)
DIBWT	CHANGE IN COLLECTIVE PITCH DUE TO BOBWEIGHT
DTZMT	COLLECTIVE PITCH INPUT BY PROP ROTOR COLLECTIVE GOVERNOR
DTZM1	CHANGE IN COLLECTIVE PITCH DUE TO PITCH COME COUPLING MAIN ROTOR
DTZT1	CHANGE IN COLLECTIVE PITCH DUE TO PITCH COME COUPLING TAIL ROTOR
D3ELE	COLLECTIVE STICK -ELEVATOR INCIDENCE COUPLING FACTOR
FLOCK	F/A CYCLIC LOCK INDICATOR
FNSHC	FIN SIDE-WASH COEFFICIENT
FKTS	FT/SEC TO KNOTS CONVERSION FACTOR
FVIND	INDUCED VELOCITY CHANGE LIMITER
GMAXV	TOTAL GUST VELOCITY = GMAXV1 +GMAXV2
GUFSS	INPUT CONTRGL FOR FLIGHT CONSTANTS GUESSES
GVERT	G-LEVEL IN FUSELAGE Z-DIRECTION
HDELT	.5 * TDELTA
HGUST	FUSELAGE X-COMPONENT OF GUST VELOCITY
HLTRI	TAIL ROTOR MAST LENGTH IF SIDE-BY-SIDE, = 0. OTHERWISE
HLTR2	OPPOSITE OF HLTRI
HURKP	MAIN ROTOR F/A HUB SPRING RATE PER BLADE
HURKR	LATERAL HUB SPRING RATE PER BLADE
ITORS	INERTIA OF TORSIONAL SYSTEM
KREAD	NUMBER OF MANEUVER CARDS FOR THIS RUN
KTCR	POINTER TO WHICH TIME INCREMENT IS BEING USED IN MANEUVER
LLJET	X-COMPONENT OF MOMENT DUE TO LEFT OR CENTER JET THRUST
LRJET	X-COMPONENT OF MOMENT DUE TO RIGHT JET THRUST
LWING	COUNTER ON UNSTEADY AERODYNAMIC EFFECTS -WAGNER FUNCTION
MLJET	Y-COMPONENT OF MOMENT DUE TO LEFT OR CENTER JET THRUST
MRJET	Y-COMPONENT OF MOMENT DUE TO RIGHT JET THRUST
NLJET	Z-COMPONENT OF MOMENT DUE TO LEFT OR CENTER JET THRUST
NPSI	NUMBER OF AZIMUTH STATIONS
NPART	PRIMARY PATH CONTROL VARIABLE
NPASS	TRIM ITERATION COUNTER
NRJET	Z-COMPONENT OF MOMENT DUE TO RIGHT JET THRUST
NVARA	SECONDARY PATH CONTROL VARIABLE OR PLOT CODE NUMBER
NVARB	SECONDARY PATH CONTROL VARIABLE OR PLOT CODE NUMBER
NVARC	SECONDARY PATH CONTROL VARIABLE OR PLOT CODE NUMBER
JMEGM	MAIN ROTOR SPEED IN RAD/SEC TARGET OR TRIM VALUE
PCDEL	CHANGE IN COLLECTIVE TO ADD TO M.R. AT THIS TIME INCREMENT PCG
PEDAL	PEDAL POSITION IN PERCENT
PIU30	RADIANS/SEC TO RPM CONVERSION FACTOR, 30. / PI
PMDHM	MAIN ROTOR F/A HUBSPRING MOMENT, PER BLADE
PMDMT	TAIL ROTOR F/A HUBSPRING MOMENT, PER BLADE
PMREL	INPUT COEFFICIENT OF M.R. INDUCED VELOCITY ON ELEVATOR
PMRWG	INPUT COEFFICIENT OF M.R. INDUCED VELOCITY ON WING
PTRFN	INPUT COEFFICIENT OF T.R. INDUCED VELOCITY ON FIN

QMRA	MAXIMUM ENGINE TORQUE SUPPLIED -LIMITED BY THROTTLE
RANGE	COLLECTIVE PITCH RANGE
RATE1	RAMP GUST -GMAXV1 / LMGTH1
RATE2	RAMP GUST -GMAXV2 / LMGTH2
RMASS	I. / MASS
RMOMM	MAIN ROTOR LAT HUBSPRING MOMENT, PER BLADE
RMOT	TAIL ROTOR LAT HUBSPRING MOMENT, PER BLADE
RPIST	INTERMEDIATE VARIABLE IN WING MAKE CALCULATIONS
STAGG	STATION LOCATIN OF CENTER OF GRAVITY
STOP2	END DISTANCE FOR 2ND RAMP OR HUMP -START2 +LNGTH2
SWING	WING SPAN
SWKR1	(2) F/A SPRING RATES FOR FOCUSED PYLON EFFECT
SWKR2	(2) LAT SPRING RATES FOR FOCUSED PYLON EFFECT
SZET5	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
SZET7	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
SZET8	INTERMEDIATE VARIABLE IN CONTROL LINKAGES
TDELT	TIME INCREMENT FOR MANEUVER SECTION
IMROT	(2) PREVIOUS VALUE OF ROTOR THRUST
TIP38	(2) TIP LOSS FACTORS
TRALT	TAIL ROTOR ALTITUDE
TWOPI	6.283185
TZERO	START TIME FOR MANEUVER
VGUST	FUSELAGE Z-COMPONENT OF GUST VELOCITY
VYAXE	VELOCITY AT WHICH ELEVATOR IS COMPLETELY SUBMERGED IN AIR WAKE
WGCOL	WING ANGLE OF ATTACK DUE TO COLLECTIVE COUPLING
XAELE	X ARM OF THE ELEVATOR
XAFIN	X ARM OF THE FIN
XAFUS	X ARM OF THE FUSELAGE
XAGUN	X ARM OF THE GUN
XAJET	X ARM OF THE JETS
XAPYL	X ARM OF THE PYLON
XARSP	(2) X ARM OF THE ROTOR SHAFT PIVOT POINT
XFELE	X-FORCE DUE TO ELEVATOR
XFFIN	X-FORCE DUE TO FIN
XFFUS	X-FORCE DUE TO FUSELAGE
XFGUN	X-FORCE DUE TO GUN
XFLWG	X-FORCE DUE TO LEFT WING
XFRWG	X-FORCE DUE TO RIGHT WING
XGUST	DISTANCE TO BEGINNING OF GUST AT ZERO
XLOCK	LATERAL CYCLIC LOCK INDICATOR
XMAIT	TAIL ROTOR LATERAL FLAPPING MOMENT
XMBIT	TAIL ROTOR F/A FLAPPING MOMENT
XSTAH	(2) XSTAHM AND XSTAHT
YAELE	Y ARM OF THE ELEVATOR
YAFIN	Y ARM OF THE FIN
YAFUS	Y ARM OF THE FUSELAGE
YAGUN	Y ARM OF THE GUN
YALWG	Y ARM OF THE LEFT WING
YARWG	Y ARM OF THE RIGHT WING
YFFIN	Y-FORCE DUE TO FIN
YFFUS	Y-FORCE DUE TO FUSELAGE
YFGUN	Y-FORCE DUE TO GUN
YGUST	FUSELAGE Y-COMPONENT OF GUST VELOCITY
YSTAH	(2) YSTAHM AND YSTAHT

ZAELE Z ARM OF THE ELEVATOR
 ZAFIN : ARM OF THE FIN
 ZAFUS Z ARM OF THE FUSELAGE
 ZAGUN Z ARM OF THE GUN
 ZAJET Z ARM OF THE JETS
 ZAPYL Z ARM OF THE PYLON - INTERMEDIATE VARIABLE
 ZARSP (2) Z ARM OF THE ROTOR SHAFT PIVOT POINT
 ZFTAR (2) ZETA AND ZETATR
 ZFELE Z-FORCE DUE TO ELEVATOR
 ZFFUS Z-FORCE DUE TO FUSELAGE
 ZFGUN Z-FORCE DUE TO GUN
 ZFLWG Z-FORCE DUE TO LEFT WING
 ZFRWG Z-FORCE DUE TO RIGHT WING
 ZMAX2 STOP TIME FOR SECOND TIME INCREMENT
 ZMAX3 STOP TIME FOR THIRD TIME INCREMENT
 ALECR1 WING ANGLE OF ATTACK FOR AILERON EFFECT
 ALGFPO RUDDER ANGLE OF ATTACK FROM PEDAL
 APBJET E.A. PITCH, FUSELAGE TO JET
 ARBJET CONSTANT, = 0.
 ASECOL YAW PILOT VARIABLE
 AYBJET E.A. YAW, FUSELAGE TO JET
 BOTTON LOWER LIMIT OF COLLECTIVE PITCH
 CNPCD1 INTERMEDIATE VARIABLE, FUNCTION OF CNPCD
 CNPCD2 INTERMEDIATE VARIABLE, FUNCTION OF CNPCD
 COLJET COLLECTIVE STICK - JET THRUST COUPLING FACTOR
 COLSTK COLLECTIVE STICK POSITION IN PERCENT
 CYPMIC LATERAL CYCLIC STICK WING INCIDENCE COUPLING FACTOR (AILERON EFF)
 CYSTK1 FORE/AFT CYCLIC STICK POSITION IN PERCENT
 CYSTK2 LATERAL CYCLIC STICK POSITION IN PERCENT
 CZET11 INTERMEDIATE VARIABLE IN CONTROL LINKAGES
 CZET12 INTERMEDIATE VARIABLE IN CONTROL LINKAGES
 CZET13 INTERMEDIATE VARIABLE IN CONTROL LINKAGES
 DCAFXX DCAFR * XK
 DELT2R L. / DELT2
 DQDCOL O TORQUE / D COLLECTIVE FROM TRIM SECTION
 DTRRSO RADIAN *2 TO DEGREE *2 CONVERSION FACTOR, DTRR *2
 EIMAST COUPLING COEFFICIENT MAST TILT TO ELEVATOR INCIDENCE
 FIZETA ELEVATOR ANGLE OF ATTACK FROM MAST TILT
 ENGRPH ENGINE RPM
 ETAOMX REFERENCE VALUE OF ETAO -AT CENTERLINE OF WING WAKE
 GEARAT GEAR RATIO TAIL ROTOR /MAIN ROTOR
 GMAXV1 FIRST MAXIMUM GUST VELOCITY
 GMAXV2 SECOND MAXIMUM CHANGE IN GUST VELOCITY
 GMAXV3 INTERMEDIATE VARIABLE = GMAXV1 -START2 *RATE2
 GPRELD G PRELOAD FOR BOBWEIGHT
 GUSTYP TYPE OF GUST -9,10,11,OR 12 AS J VALUE FOR GIVEN CASE
 HALFPI 1.570796, .5 * PI
 HFORCE HMR AND HTR
 HGUSTE HORIZONTAL GUST VELOCITY AT ELEVATOR
 HGUSTF HORIZONTAL GUST VELOCITY AT FIN
 HGUSTW HORIZONTAL GUST VELOCITY AT WING
 HLPYLD DISTANCE FROM M.A.R. PIVOT POINT TO FLAT PLATE DRAG C.P. ON MAST
 HNP5IR 2. /NOP5I
 HUBKPR HUBKP AND HUBKTP

HUBKPS SPRING RATE PER BLADE - MAIN ROTOR PITCH (F/A)
 HUBKRP HUBKR AND HUBKTR
 HUBKRS SPRING RATE PER BLADE - MAIN ROTOR ROLL
 HUBKTP TAIL ROTOR F/A HUB SPRING RATE PER BLADE
 HUBKTR TAIL ROTOR LATERAL HUB SPRING RATE PER BLADE
 HUBTPS SPRING RATE PER BLADE -TAIL ROTOR PITCH
 HUBTRS SPRING RATE PER BLADE -TAIL ROTOR ROLL
 IPRINT BLADE ELEMENT DATA PRINT INDICATOR
 KCONFIG CONFIGURATION NUMBER, = 1. + TRIND + TRIND1
 LAMBDA VELOCITY *SIN(ALFA) --INDUCED VELOCITY (NOT DIVIDED BY OMEGA *R)
 LNGTH1 LENGTH OF FIRST RAMP OR BASE OF HUMP FOR SIN**2 GUST
 WXPASS MAXIMUM NUMBER OF ITERATION ALLOWED IN TRIM (INPUT)
 VORAM NUMBER OF RADIAL STATIONS
 VSCALE SCALE FACTOR FOR PLOTS
 OMEGMD RATE OF CHANGE OF MAIN ROTOR SPEED (TARGET) RAD/SEC**2
 PCGDED PCG DEAD BAND
 PCGMAX MAXIMUM VALUE OF PCRATE
 PCRATE RATE OF CHANGE OF PCDEL
 PILGHI INTERMEDIATE GUST VARIABLE = PI / LNGTH1
 PILGHT INTERMEDIATE GUST VARIABLE = PI / LNGTH2
 PSDROP MAIN ROTOR TO ENGINE GEAR RATIO
 PSD550 PSD / 550.
 PWGKI COEFFICIENT FOR DEFLECTION OF WING MAKE CENTERLINE
 P1DTR -.0001745329, .01 * DTR
 RCHING 1. / CHING
 ROELT1 1. / TOELT
 ROELT2 1. / HOELT
 ROTORS 1. / ITORS
 RUJDIND RUDDER INDICATOR 1=WITH 0= WITHOUT
 START2 START DISTANCE FOR 2ND RAMP OR HUMP FROM END OF 1ST GUST
 SWINGH .5 * SWING
 SZFT1 INTERMEDIATE VARIABLE IN CONTROL LINKAGES
 TCLOCK TAIL ROTOR COLLECTIVE LOCK
 VENTER VELOCITY AT WHICH ELEVATOR ENTERS M.R. MAKE
 VGUSTE VERTICAL GUST VELOCITY ON ELEVATOR
 VGUSTW VERTICAL GUST VELOCITY ON WING
 VXMVER INTERMEDIATE VARIABLE = 1. / (VMAXE--VENTER)
 WPOTOR WEIGHT OF HUB ASSFMRLY AND BLADES
 XAPYLD X ARM OF THE PYLON DRAG
 XFLJET X FORCE DUE TO LEFT OR CENTER JET
 XFRJET X FORCE DUE TO RIGHT JET
 XLIMIT MAXIMUM AMOUNT TRIM VARIABLES CAN CHANGE
 XLMAXH MAXIMUM VALUE OF XLIM FOR MAIN ROTOR
 XLMAXT MAXIMUM VALUE OF XLIM FOR TAIL ROTOR
 XLMINH MINIMUM VALUE OF XLIM FOR MAIN ROTOR
 XLMINT MINIMUM VALUE OF XLIM FOR TAIL ROTOR
 XSTAHT TAIL ROTOR NORTH-SOUTH DISTANCE FROM START OF GUST TO HUB
 YALJET Y ARM OF LEFT OR CENTER JET
 YARJET Y ARM OF RIGHT JET
 YFLJET Y FORCE DUE TO LEFT OR CENTER JET
 YFRJET Y FORCE DUE TO RIGHT JET
 YGUSTF LATERAL GUST VELOCITY ON THE FIN
 YGUSTW LATERAL GUST VELOCITY AT THE WING STATION LINF
 YSTAHP MAIN ROTOR EAST-WEST DISTANCE FROM START OF GUST TO HUB

YSTATM TAIL ROTOR EAST-WEST DISTANCE FROM START OF GUST TO HUB
ZAPYLD Z ARM OF THE PYLON DRAG
ZDELTI1 FIRST AND THIRD TIME INCREMENT FOR RUNGE-KUTTA INTEGRATION
ZDELTI2 SECOND TIME INCREMENT FOR RUNGE-KUTTA INTEGRATION
ZETATR TAIL ROTOR MAST TILT ANGLE
ZFLJET Z FORCE DUE TO LEFT JET
ZFLWGI SAVED VALUES OF LEFT WING LIFT- FOR UNSTEADY AERODYNAMICS
ZFRJET Z FORCE DUE TO RIGHT OR CENTER JET
ZFRWGI SAVED VALUES OF RIGHT WING LIFT FOR UNSTEADY AERODYNAMICS

APPENDIX B

SUBROUTINES AND COMMONS CONTAINING EACH COMMON AND VARIABLE

VARIABLE	CS	RC	MT	IN	IR	IO	AC	SW	MI	IV	PG	TS	LS	JA	OW	TP	SD	II	IP	CC	
SHEAR					X	X	X														
START2					X	X	X				X										
SMINGH																					
SZET1																					
TLOCK																					
*THRUST																					
*TORQUE																					
TRIND1																					
TRIND2																					
UPGUST																					
URGUST																					
UTGUST																					
VENTER																					
VGUSTE																					
VGUSTW																					
VKVER																					
*VZETAR																					
VZETAT																					
WROTOR																					
XAPYLD																					
XFLJET																					
XFRJET																					
*XLIMAX																					
*XLIMIN																					
XLIMIT																					
XLMAX																					
XLMAXT																					
XLMAXW																					
XLMIN																					
XLMINW																					
XLMINT																					
XSTAHM																					
XSTAHT																					
YALJET																					
YARJET																					
YFLJET																					
*YFORCF																					
YFRJET																					
YGUSTF																					
YGUSTW																					
YSTAHM																					
YSTAHT																					
ZAPYLD																					
ZDELT1																					
ZDELT2																					
ZETATR																					
ZFLJET																					
ZFLWGI																					
ZFRJET																					
ZFRWGI																					

ANDOIT
 ROMAN
 STARAN
 MANAL
 MANAL
 MANARU
 MANARO
 STRIAB
 STANAN
 ROSTAR
 ROSTAR
 ROSTAR
 ROSTAR
 STARAN
 MANARO
 MANARO
 STARAN
 ROMAN
 ROMAN
 ROSTAR
 MANAL
 FORCE
 FORCE
 ROSTAR
 ROSTAR
 STRIAB
 ROSTAR
 ROSTAR
 ROSTAR
 ROSTAR
 ROMAN
 ROMAN
 STARAN
 STARAN
 FORCE
 FORCE
 MANARO
 MANARO
 ROMAN
 ROMAN
 MANAL
 STRIMA
 STRIMA
 MANARO
 FORCE
 MANAL
 FORCE
 MANAL

6310
 6320
 6330
 6340
 6350
 6360
 6370
 6380
 6390
 6400
 6410
 6420
 6430
 6440
 6450
 6460
 6470
 6480
 6490
 6500
 6510
 6520
 6530
 6540
 6550
 6560
 6570
 6580
 6590
 6600
 6610
 6620
 6630
 6640
 6650
 6660
 6670
 6680
 6690
 6700
 6710
 6720
 6730
 6740
 6750
 6760
 6770
 6780

APPENDIX C

COMMONS AND VARIABLES IN EACH SUBROUTINE AND COMMON

C81

C81

TOPLOT
AH
AL
EXIT
IPSN
NPART
NTIME
NVARA
NVARB
NVARC
NVAR5
NPRINT
NSCALE

START

*ZETAR
APBJET
AYBJET
COLJET
COLSTK
CYSTK1
CYSTK2
DTRRSO
EIMAST
ENGRPH
ETAQMX
GEARAT
PRELD
ALFPI
HLPLYD
MKPASS
PCGDED
PCGMAX
PSD30P
PWGEL1
PWGK1
P01DTR
*THRUST
TRIND1
VENTER
XLIMIT
XLMINH
XLMINT
YARJET
ZETATR

XCOM
XJET
XMIN
ZANG
ZETA
ALGEZ
CGSTA
CLBCL
CNBCL
CNPCD
CNPCL
CNRCD
CNRCL
COND1
COND2
D3ELE
FNSWC
FVIND
GUESS
OMEGH
PEDAL
PIU30
PMREL
PMRWG
PTRFN
STACC
TRIND
TSTAB
TMOPI
VMAXE
XAELE
XAFIN
XAFUS
XAGUN
XAJET
XAPYL
YAELE
YAERO
YAFIN
YAFUS
YAGUN
YARWG
ZAELE
ZAFIN
ZAFUS
ZAGUN
ZAJET
ZAPYL

XFS
XGN
XIT
XMR
XRG
XXP
YEL
YFN
YFS
YMR
YTR
YMG
YYD
ZZD
ALGF
APBG
AYBG
A1TR
BAIB
BLGG
BWTG
BWTG
BWTG
BLTR
CGBL
CGWL
CLB0
CNB0
DAMP
DTRR
EPDS
ERTR
ERXM
ERXT
IXZ
KVAR
NJET
NSDT
QELE
OFIN
OMAX
RAIB
TATR
TAXL
TAXR
VSND
WLCG
XANG

START

STRIAB
STRIMA
STAMAN
MANAL
ROMAN
MANARO
STANRO
ROSTAR
STARAN
*B
D
Q
T
W
BH
BM
DT
IX
IY
IZ
PI
ZZ
AGW
APE
ARE
AYE
ALM
BTR
BIM
CLP
CLR
DTR
ERM
ERR
ITM
IXZ
PSD
OMG
RHO
R12
SWC
TMR
TTR
XBW
XEL
XER
XFC
XFN

READIN

READIN

STRIAB
STRIMA
TOPLOT
D
DT
XBW
XEL
XER
XFC
XFN
XFS
XGN
XIT
XMR
XTR
XWG
YEL
YFN
YMR
YTR
YWG
ICOM
IPSN
KCIT
TMAX
XCIT
XCON
XJET
GUFSS
KRFAD
NPART
TSTAB
TZERO
ZMAX2
ZMAX3
ZDELT1
ZDELT2

COM1

COM1

STRIMA
MANAL
CULL
CYCF
CYCL
PEOA
TZMS
TZYS
TIMS
TITS
T2MS
T2TS
ALGE1
ALGE2
CLOCK
CPMIC
FLOCK
XLOCK
CYPMIC
HALFPI
RUDIND
TCLOCK

MNEM

FORCE
 STRIAB
 STRIMA
 STAHAN
 MANAL
 ROMAN
 MANARO
 STANRO
 POSTAR
 TOPLJT
 STARAN
 Q
 V
 W
 Y
 AM
 AP
 BM
 CT
 HL
 IX
 IY
 IZ
 RC
 RM
 PW
 XF
 ZZ
 AGW
 ALT
 APD
 APE
 ARD
 ARE
 AYD
 AYE
 AIM
 RTP
 RIM
 DOL
 DON
 DTR
 ERR
 HMR
 HTR
 IND
 ITM
 IXZ

NXR
 ORM
 PED
 PSD
 STAHAN
 OMX
 QTR
 OMG
 RIY
 SMC
 TMR
 TTR
 TZM
 TZT
 T1M
 T1T
 T2M
 T2T
 UHS
 VIW
 VXB
 VXS
 VYB
 VYS
 VZB
 VZS
 XAR
 XFC
 XFM
 XMR
 XMG
 XXD
 YAR
 YFS
 YFS
 YFW
 YWG
 YYD
 ZAR
 ZFM
 ZFD
 ALEL
 APDD
 APFF
 ARDD
 AYDD
 AYFF
 AITR
 BAIB
 BETA

BIR
 CGML
 COLLE
 COSE
 CYCF
 CYCL
 CZET
 DAMP
 DPIX
 DPIS
 EPOS
 ERXM
 ERXT
 ETAO
 EXIT
 LINK
 MASS
 NJET
 NPSI
 NMAG
 ORTR
 PEDA
 PSDD
 PSDT
 RTRP
 R550
 SZET
 TATR
 TAXL
 TAXR
 TMAX
 VIER
 VIMR
 VITR
 VROT
 VSND
 XAMG
 XCON
 XMAI
 XMBI
 XMIN
 YMRF
 YTRF
 ZAMG
 ZFTA
 ZZTR

ALFIN
 ALLWG
 ALRWG
 APBMT
 ARBMT
 AYBMT
 BETAE
 BETAN
 BETAX
 BETAZ
 BMBIT
 BNPST
 COELE
 CDFIN
 COLWG
 CORWG
 CGSTA
 CLELE
 CLFIN
 CLLWG
 CLRWG
 CMPCD
 COLKS
 CWING
 CYCR1
 CYCR2
 DIXIZ
 DIYIX
 DIZIY
 DPIXZ
 GUFSS
 HLTR1
 HLTR2
 ITORS
 LLJET
 LRJET
 LWING
 MLJET
 MRJET
 NLJET
 NPART
 NPJET
 NVARR
 NVARC
 NVARD
 PEDAL
 PMREL
 RMASS

RPIS
 SWING
 TRALT
 TRIND
 TMI ST
 TZERO
 VMAXE
 XAELE
 XAJET
 XARSP
 XMBIT
 XMAIT
 YAERO
 YALWG
 YARSP
 YARWG
 ZAELE
 ZAJET
 ZARSP
 ZMAX2
 ZMAX3
 APBJET
 ARBJET
 AYBJET
 CNPCD1
 CNPCD2
 COLJET
 COLSTK
 CYSTK1
 CYSTK2
 DXWGL
 DZWGL
 GEARAT
 GUSTYP
 HALFPI
 HGUSTE
 HGUSTF
 HGUSTW
 HNPSTR
 ITRAKE
 KONFIG
 PILGH2
 PSD550
 PSTREF
 PSISTP
 RCWING
 RITORS
 RUDIND

SWINGH
 TRINDI
 TRIND2
 UPGUST
 URGUST
 UTGUST
 VENTER
 VGUSTE
 VGUSTW
 VXMVER
 WROTOR
 XFLJET
 XFRJET
 XLIMIT
 XLMAXM
 XLMAXT
 XLMINM
 XLMINT
 YALJET
 YARJET
 YFLJET
 YFRJET
 YGUSTF
 YGUSTW
 ZDELT1
 ZDELT2
 ZETATR
 ZFLJET
 ZFRJET

MNEM

TINII

TINII

STRIMA
STAMAN
HL
VH
DT1
DT2
KPD
QOO
XXO
YYO
ZZO
APFP
ARBG
ASEP
AYFP
QMAX
R55O
TAIR
ALERT
AYDMX
DTBMT
DTZMT
DTZMI
DTZTI
FTKTS
HGUST
HLTR2
ISTOP
KTCTR
PCDEL
QMRSA
TRALT
TSTAB
VGUST
YGUST
ASECOL
IBRAKE
OMEGMO
PCRATE
RITORS
TRINDZ

INRO

INRO

STPIAB
 SYAMAN
 ROMAN
 ROSTAR
 D
 *R
 AM
 OT
 HL
 *DP
 PH
 XB
 AIP
 AIP
 AIP
 ADR
 DTP
 FXH
 NXR
 GRM
 PCC
 PSN
 PBH
 RMD
 RTR
 R12
 VXS
 VYS
 V75
 *AIRP
 *AIR
 *APER
 APTD
 *AFDR
 APTD
 WLG
 CHH
 CHSE
 STEP
 CHAT
 LBUT
 NPST
 DRTZ
 PSOT
 *PSID
 *AIR
 DTPD
 WLG
 AIRPM
 AIBPT
 AIBRM
 AIBRT
 APTTD
 ARTTD
 AZETA
 BETAN
 BETAX
 BETAZ
 CONEK
 DCAFR
 HUBKP
 HUBKR
 STAGC
 SMKRI
 SMKRZ
 TIPIB
 TIPBB
 TRIND
 TWIST
 TWOPT
 VZETA
 XARSP
 YARSP
 ZARSP
 *AZETAR
 AZETAT
 AZETAZ
 BETAZS
 CLPADK
 DELTA3
 *HUBKPR
 HUBKPS
 *HUBKRR
 HUBKRS
 HUBKTP
 HURKTR
 HURTPS
 HUBTPS
 PSIRFF
 *VZETAR
 VZETAT

VIND

VIND

20MAN
MANARD
STARRD
R1STAR
*R
*R
44
CT
*R
RM
ALT
ADR
MTR
DRM
RTR
IHS
*VIP
VZS
*PTC
VIMP
VITP
VONT
LAFDA

ROTAN

ROTAN

ANDJIT
 P0MBN
 MANARO
 STANRO
 ROSTAR
 TOPL0T
 T
 J
 *P
 T
 Y
 A1
 R1
 *Q5
 P1
 *T1
 *T2
 XK
 Z2
 ALY
 APD
 APF
 APD
 APF
 APE
 AYD
 AYE
 AIM
 RIM
 HMP
 HTR
 TMD
 HXR
 GOM
 PSC
 WTC
 SMC
 TMP
 TTC
 UHS
 VHS
 VI2
 VI4
 VX9
 VXS
 VVR
 VYS
 VZR
 VZS

XAR
 VAR
 ZAR
 APDD
 APDM
 *APDP
 APDS
 APFM
 APTD
 ARDD
 APOM
 *ARDR
 APDS
 ARFM
 APTD
 AYDD
 AYFM
 ALTR
 ALTP
 FXIT
 GFWD
 GLAT
 LINK
 LROT
 NPSI
 NWAG
 ORTR
 PSOT
 *PSIN
 *PMJM
 P0YJ
 TAIP
 TINT
 TITT
 T2MT
 T2TT
 V2OT
 XK43
 XLTM
 YBRF
 YTRF
 ZETA
 ZZTR
 APBMT
 APDBS
 APTTD
 APBMT
 ARDRS

ARTTD
 AYBMT
 AZETA
 AIRAL
 BIRAL
 CBFAC
 COMD2
 DCAFR
 GOISK
 GVERT
 NPSI
 NVARC
 NWARD
 RMOMM
 RMOMT
 S*KR1
 S*KR2
 TANTI
 TANT2
 TDELY
 THROT
 TRIND
 VZETA
 XMOMD
 XMOML
 *ZFTAR
 *AZETAH
 AZETAT
 DCAFAX
 GUSTYP
 *HFORCE
 HGUJTE
 HGUSTF
 HGUSTM
 IPRINT
 KONFIG
 NBRADI
 SHEARD
 SHEARL
 SHFARR
 *THRUST
 VGUSTE
 VGUSTW
 *VZETAR
 VZETAT
 WRNOR
 *XLIMAX
 XLMAXW

XLMAXT
 *YFORCE
 VGUSTF
 ZETATR

ITROT

ITROT

ANDJIT	*RMOM
ROMAN	RTRP
MANARO	TZMT
STANRO	TZTT
ROSTAR	VIMR
TOPLOT	VITR
I	XLIM
J	XMAI
AI	XMBI
BI	YMRF
CT	YTRF
*ER	AIBPH
*OP	AIBPT
PI	AIBRM
XY	AIBRT
ERM	APDBS
*ERX	ARDBS
HMR	BETAE
HTR	BETAN
ITM	BFTAX
ORM	BETAZ
PCC	BETAO
PSD	BNPSI
OMX	CONOI
QTR	CONDZ
TMR	FVIND
TTR	PMOMM
*TZP	PMOMT
*VIR	RMOMM
VI2	RMOMT
VI4	TANAI
VZS	TANBI
*XMA	XMAIT
*XMB	XMBIT
*AIBP	XMOMO
*AIBR	XMOML
DYRR	DCAFXK
ERTR	*HFORCE
ERXM	LAMBDA
ERXT	SHEARD
EXIT	SHEARL
LINK	SHEARR
ORTR	*THRUST
PFAC	*TORQUE
*PHJM	*XLIMIN
PSDT	XLMINM
*PSID	XLMINT
RFAC	*YFORCE

ANDOIT
 ROMAN
 MANARO
 STAVRO
 ROSTAR
 TOPLOT
 *P
 Y
 AM
 *OP
 RM
 XB
 XK
 XY
 ATR
 FXH
 HMR
 HTR
 ORM
 PSD
 OMX
 OTR
 PBH
 RTP
 TMR
 TTP
 *TZR
 *VTR
 VXS
 VYS
 VZS
 *XMA
 *XM3
 APM
 APOS
 APFM
 ARDM
 ARDS
 APF4
 AYFM
 AFTA
 COMB
 COSF
 DPSI
 DIRR
 EXIT
 LINK
 ORTR

PFAC
 *PMOM
 PSDT
 *PSID
 RAIB
 RFAC
 *RMOM
 ROTJ
 TZNT
 TZTT
 VIMR
 VITR
 VSND
 XK43
 XHAI
 XHBI
 YHRF
 YTRF
 BETAD
 BETAE
 BETAN
 BETAX
 BETAZ
 BETAQ
 CBFAC
 CONEK
 GDISK
 GMAXV
 HUBKP
 HUBKR
 NBPST
 PHOMM
 PHOMT
 RATE1
 RATE2
 RHOMM
 RHOMT
 STOP2
 TANAI
 TANI
 TANTI
 TANT2
 TIP18
 TIP30
 TWIST
 XGUST
 XMAIT
 XMBIT

XMDMD
 XMOHL
 *XSTAH
 *YSTAH
 BETAZD
 CLRADK
 DELTA3
 GMAXV1
 GMAXV2
 GMAXV3
 GUSTYP
 *MFORCE
 *MPSIR
 *HUBKPR
 HUBKPS
 *HUBKRR
 HUBKRS
 HUBKTP
 HUBKTR
 HURTPS
 HURTPS
 HURTPS
 IPRINT
 LAMBDA
 LNGTH1
 NORADL
 PILGHI
 PILGH2
 PSIREF
 SHEARD
 SHEARL
 SHEAR
 START2
 *THRUST
 *TORQUE
 UPGUST
 URGUST
 UTGJUST
 XSTAHM
 XSTAHM
 *YFORCE
 YSTAHM
 YSTAHT

KGJFE
KJAL
KALAB
KABOD
KAPLOT
KAPAM

VTM
VVA
VVR
VZB
XAB
XFM
YAR
YFS
YFM
ZAR
ZEM
ALEL
SAB
CLRO
CMAO
CZET
ETAO
FKTY
GFWD
GLAT
LFLF
LFTN
LFUS
LGIN
LLMG
LJMR
LQTR
LRMG
WELE
WFEN
WFUS
WGUM
MLWG
MOMR
MOTR
MPMG
NFLE
NFTN
NFUS
NGUN
NJET
NLWG
NMR
NOTR
NRMG
MWAG
PSDD
OFLE

OFIN
SZFY
TAXL
TAXR
VIFR
VIMP
VITR
VONT
VSND
XAWG
XEMR
XFTA
XFTN
XFMR
YVFR
YTFR
YTRF
ZAWG
ZETA
ZFEL
ZFMR
ZFTR
ALCYP
ALFIN
ALLWG
ALRWG
APRMT
ARMT
AVRMT
COELE
COFIN
COLMG
CORMG
CLACL
CLFLE
CLFIN
CLLWG
CLRWG
CMBCL
CMPCL
CMRCD
CMRCL
COLKS
CWING
DYELE
FMSWC
GVFRT
LLJET

LPJFT
LWING
MLJET
MRJET
NLJET
NRJET
PQMM
PMMT
PAREL
PMPWG
PYBFN
PQMM
PMMT
RPIST
SMING
TDELT
VMAXF
WCCOL
XAFLE
XAFIN
XAFUS
XAJET
XFLE
XFEN
XFFUS
XFGUN
XFLWG
XFRWG
YAELE
YAEAD
YAFIN
YAFUS
YALWG
YARWG
YFFIN
YFFUS
YFGUN
ZAFLE
ZAFIN
ZAFUS
ZAJET
ZEELE
ZFFUS
ZFGUN
ZFLWG
ZFRWG
ALECRI
ALGFPD

APRJFT
ARRJFT
AYBJET
CMPCOI
CMLJET
COLSTR
DXMGFL
DZMGFL
FIZETA
FTAOMX
HALFPI
HGUSTE
HGUSTF
HGUSTW
PMGFLI
PMGKLI
RCWING
SWINGH
VENTER
VGUSTE
VGUSTW
VRAVER
XAPYLD
XFLJET
XFRJET
YALJET
YALJET
YFLJET
YFRJET
YGUSTE
YGUSTW
ZAPYLD
ZFLJET
ZFLWGI
ZFRJET

CLCO

CLCO

STANAN
C3
C4
DCH
YAERO

SMAS

SMAS

MANAL
PED
TZM
TZY
TLM
TIT
TZM
TZT
CZET
TZMS
TZTS
TIMS
TITS
TZMS
TZTS
XLNK
CLOCK
CYCR1
CYCR2
CZET4
CZET6
CZET9
FLOCK
RANGE
SZET5
SZET7
SZET8
KLOCK
BOTTOM
CZET11
CZET12
CZET13
SZET10
TCLOCK

WROT

WROT

WROT
WROT
WROT
WROT

FORCE
 STEIMA
 STAMAN
 MANAL
 ROMAN
 MAPARO
 STANRO
 TOPLDT
 I
 T
 V
 Y
 AY
 OL
 OM
 ON
 OY
 VH
 YF
 YF
 YF
 YY
 ZF
 ZZ
 ATR
 ATR
 APO
 APE
 APD
 ARE
 AYD
 AYE
 AYI
 AIM
 AIM
 DTI
 DTI
 GOV
 IND
 IXI
 IXI
 PCC
 PCC
 QME
 QME
 QPC
 QPC
 QTO

RIV
 RTR
 TMR
 TTR
 TZM
 TZT
 TLM
 TLT
 T?M
 T2T
 VXR
 VYB
 VZB
 XXD
 YYD
 ZZD
 APDD
 APFP
 APTD
 ARDD
 ARDD
 AYDD
 AYFP
 ZZ
 ALTR
 BETA
 RWTC
 BMTK
 BMTM
 RLTR
 DIST
 DPIX
 DPIZ
 DPST
 EXIT
 FHPT
 IPSM
 LINK
 NPST
 NWAG
 NPTR
 PSDD
 PSDT
 QMAX
 QMS
 QSSO
 TIME
 TMAX
 T?MT

TZTT
 TIMT
 T1TT
 T2MT
 TZTT
 ZETA
 ZZTR
 APBMT
 APTTD
 ARBMT
 ARTTD
 AYBMT
 AZETA
 BETAD
 BETAE
 BETAZ
 BETAO
 DELT2
 DIXIZ
 DIVIX
 DIZIY
 DPIXZ
 DTBMT
 DTZMT
 DTZMI
 DTZTI
 GVERT
 MOELT
 HUBKP
 HUBKR
 ISTOP
 ITORS
 KTCTR
 NVARB
 NVARS
 OMEGM
 OMPSA
 RMASS
 TDELT
 THROT
 TRALT
 TRIND
 TSTAB
 TMOPI
 VZETA
 ZFLMG
 ZFRWG
 ZMAX2

ZMAX3
 ASECOL
 AZETAT
 BETAZD
 COLSTK
 DELT2R
 GEARAT
 GPREDL
 HALFPI
 HUBKPS
 HUBKRS
 HUBKTP
 HUBKTR
 HUBTPS
 HUBTRS
 IBRAKE
 PSD550
 PSIREF
 PSTSTP
 QXRRAK
 QBRAKE
 RDELT1
 RDELT2
 RITORS
 VZETAT
 ZDELT1
 ZDELT2
 ZFLWG1

INIT

INIT

FIGURE
 STPMA
 STAMAN
 MANAL
 ROMAN
 MANARO
 TOPLOT
 A
 T
 V
 Y
 AP
 AV
 VH
 A1M
 B1M
 AMP
 HTE
 PSC
 QMR
 QM
 QTE
 TMR
 TTP
 T7M
 T7T
 T1M
 T1T
 T2M
 T2T
 VXS
 VYS
 V7S
 ALFL
 APFP
 APTD
 APTD
 AVFB
 ALTR
 RLTR
 CGRL
 CGWL
 G1ST
 GDSI
 DTRR
 GEMD
 GLAY
 IPSN

NPST
 OMRS
 TAXL
 TAXR
 TZMT
 TZTY
 T1MT
 T1TT
 T2MT
 T2TT
 VIMR
 VITR
 XMAI
 XMBI
 Y4RF
 YTRF
 ZETA
 ALFIN
 ALLWG
 ALRWG
 APTD
 ARTD
 RETAN
 RETAX
 RETAD
 CDELE
 CDFIN
 CDLWG
 CDRWG
 CGSTA
 CLELE
 CLFIN
 CLLWG
 CLRWG
 FTKTS
 GVERT
 HGUST
 HUBKP
 HUBKP
 NTIME
 PEDAL
 PIU30
 VGUST
 XMAIT
 XMBIT
 YGUST
 COLSTK
 CYSTKI

CVSTK2
 GEARAT
 HUBKTR
 HUBKTR
 KONFIG
 NPRINT
 PSD550
 OSPAKE
 ZETATR

VARI

VARI

FURCE
STRAB
STRIMA
STAMAN
MANAL
ROMAN
MANARD
TOPLOT
I
T
X
Y
AY
HL
ZF
AGH
APD
APE
AYL
ALM
RIM
DTI
DT2
GOV
KMI
KPD
PED
PSD
OPC
QQU
T2M
T7T
T1M
T1T
T2M
T2T
XAR
YAP
ZAP
ALGF
APRG
ARPG
ASEP
AYRG
AITR
BETA
BITR
CGHL

COLL
COSE
CYCF
CYCL
OPSI
EXIT
KCIT
LGUN
MGUN
NGUN
NPSI
PEDA
PSDT
QMAX
QMS
TAXL
TAXR
TIME
TZMS
TZTS
TIMS
TITS
T2MS
T2TS
XCIT
XMAI
XMBI
XZETA
ALCYP
ALERT
ALGEZ
ALGEI
ALGE2
APBMT
AYBMT
AYDMX
AZEYA
BETAD
BETAN
BETAX
BETAZ
CGSTA
CLOCK
CPNIC
CYCR1
CYCR2
FLOCK
HDELT

MLTRI
MLTR2
HUBKI
HUBKA
HUBKP
HUBKR
ISTOP
KREAD
OMEGH
PDPHI
PEDAL
QMSA
TDELT
TRIND
VZETA
WGCOL
XAGUN
XARSP
XFGUN
KLOCK
YAGUN
YARSP
YFGUN
ZAGUN
ZARSP
ZFGUN
ALECR1
ALGFPO
AZETAT
BETAZD
BETAZS
COLSTK
CYPNIC
CYSTK1
CYSTK2
DELT2R
HALFPI
HUBKPS
HUBKTP
HUBKTR
IBRAKE
KONFIG
NPRINT
OMEGMD
PCGMAX
PCRATE
PSD550
PSIREF

RDELT2
RUDIND
TCLOCK
TRIND2
VZETAT
ZETATR

PCG

PCG

OPC
HDEL T
OMEGM
PCDEL
OMEGMO
PCGDFD
PCGMAX
PCRATE

GUST

GUST

STAMAN
MANAL
ROMAN
MANARD
O
XX
YY
APE
ARE
AVE
QMG
KAP
YAR
ZAR
XAWG
ZAMG
CMTNG
GMAXV
HGUST
RATE1
RATE2
STOP2
VGUST
XAFLE
XAFIN
XGUST
YAFIN
YGUST
ZAFLE
ZAFIN
GMAXV1
GMAXV2
GMAXV3
GUSTYP
HGUSTE
HGUSTF
HGUSTW
LNGTHI
PLGHI
STAPT2
VGJSTE
VGJSTW
YSTAMH
KSTAMT
YJSTF
YGUSTW
YSTAMW
YSTAMT

TILT

YALJET
YARJET
ZAPYLD

TILT

STAMAN
MANAL
HL
RC
CGBL
CZET
SZET
XAMG
XLNK
ZAMG
CZET4
CZET6
CZET9
RANGE
SZET5
SZET7
SZET8
XAELE
XAFIN
XAFUS
XAGUN
XAJFT
XAPYL
XARSP
YAELE
YAFIN
YAFUS
YAGUN
YALWG
YARSP
YARMG
ZAELE
ZAFIN
ZAFUS
ZAGUN
ZAJET
ZAPYL
ZARSP
BOTTOM
CZET11
CZET12
CZET13
EIMAST
EIZETA
HLPYLD
P71DTR
SZET10
XAPYLD

WRFM

WRFM

FORCE
ROMAN
A
XMAI
XMBI
XMAIT
XMBIT

STAB

AIBRM
AIBRT
APBMT
APTDD
ARBMT
ARTTD
AYBMT
AIBAL
BETAE
BNPSI
BIBAL
CLOCK
CWING
DTZMT
DTZMI
DTZTI
PEDAL
RANGE
SWING
TRIND
TSTAB
XAELE
XMAIT
XMBIT
ASECOL
BETAES
COLSTK
CYSTK1
CYSTK2
DODCOL
HMPSIR

T2M
T2T
VX8
VY8
VZ8
XFM
XXD
YFM
YYD
ZFM
ZZD
APTD
ARTD
ALTR
BLTR
COLL
CYCF
CYCL
CZET
DPSI
DTRR
EPDS
EXIT
LINK
NPSI
PEDA
QSVI
SZET
TAXL
TAXR
THRS
TTRS
TZMT
TZTT
TLMT
TLTT
T2MT
T2TT
VIMR
VITR
XAMG
XMAI
XMBI
VMRF
YTRF
ZETA
AIBPM
AIGPT

STAB

FORCE
STRIAB
STRIMA
MANAL
ROMAN
MANARO
STANRO
TOPLOT
E
J
O
V
W
BM
PD
OL
QM
ON
XF
YF
ZF
APD
APE
ARD
ARE
AYD
AYE
AIM
BTR
BIM
DT1
DT2
HMR
HTR
ITM
KMI
PCC
PSD
OMX
QTR
QMG
SPD
TMR
TTR
TZM
TZT
TIM
TIT

L MODE

L MODE

STRIAB
STANRO
IV
PD
DTR
SPD
YEL
YMG
MASS
OELF
VSND
DTRRSQ
PMGLI

LAMODE

STRIAB
IX
IZ
PD
SPD
XFS
MASS

SETE

SETE

FORCE
STRIAB
MANARO
A
E
PD
HMR
HTR
KMI
OHX
QTR
TMR
TTR
OSVI
TMRS
TTRS
YMRF
YTRF
BETAE
BETAES

JACOBI

JACOBI

STRIAB
MANARO
TOPLOT
F PD
APE
ARE
AVE
AIM
BIM
EPD
KMI
OMX
QTR
TMR
TTR
AATR
BITR
DEPD
EXIT
KVAR
QSVI
TMRS
TTRS
BETAE
PEDAL
RETAES
COLSTK
CYSTK1
CYSTK2
DODCOL

AJAC08

CYCF
CYCL
EXIT
LINK
PEDA
TAXL
TZMT
TZTT
TIIMT
TIITT
T2MT
T2TT
XMAI
XMBI
ALCYP
ALGEZ
ALGE1
ALGE2
CONDI
CPWIC
CYCRI
CYCR2
DTZMT
DTZMI
DTZTI
PEDAL
TRIND
WGCOL
XMAIT
XMBIT
ALECRI
ALGFPPD
ASECOL
COLSTK
CYPWIC
CYSTKI
CYSTK2
RUDIND

AJAC08

FORCF
STRIB
STRIMA
MANAL
ROMAN
MANARO
STAVRO
TOPLOT
F
J
DL
DM
DN
DX
DY
DZ
PD
QL
QM
QN
XF
YF
ZF
AGW
APF
ARF
AYE
AIM
RIM
DTI
DT2
X4I
PED
TZM
TZT
TIM
TIIT
T2M
T2T
VXB
VYR
VZB
XXD
YYD
ZZD
ALGF
AITR
BITR

OFFTRM

OFFTRM

STRIAB
STRIMA
ROMAN
MANARO
V
Y
DL
DM
DN
DX
DY
DZ
APD
APE
ARD
ARE
AYD
AYE
IXZ
VXB
VYB
VZB
APEP
APTD
ARTD
AYFP
MASS
ZETA
APBMT
APTTD
ARBMT
ARTTD
AYBMT
DIXIZ
DIYIX
DIZIY

MRVP

MRVP

MANARO
HMR
HTR
OMX
QTR
TMS
TTR
KVAR
VIMR
VITR
YMRF
YIRF
SETAO

TRIM

DIST
DPSI
EPDX
EXIT
LINK
NPSI
PFDA
PSDT
QMRS
TAXL
TAXR
TIME
THRS
TTRS
YFIN
ZFEL
APTTD
ARTTD
AYEFP
BETAE
BNPSI
NPART
PDPHI
PEDAL
RANGE
TDELT
TZERO
YFFIN
ZFELE
BETAES
COLSTK
CYSTK1
CYSTK2
GEARAT
HMPSIR
KONFIG
PILGH2
ZDELT1

TRI4

FORCE
STRIAB
STRIMA
MANAL
ROMAN
MANARO
STANRO
TOPLOT
V
X
Y
AY
RM
DL
DM
DN
DX
DY
DZ
PD
APD
APF
ARD
ARE
AYD
AYF
AIM
RTR
BIM
IND
ITM
PSD
QMP
OMX
OTP
TMP
TTR
VXR
VVR
VZR
XIT
APTD
ARTD
AYFP
AISR
RISR
CYCF
CYCL

PARA

XFELE
XFFIN
XFLMG
XFRMG
YFFIN
ZFELE
ZFLMG
ZFRMG
COLSTK
CYSTK1
CYSTK2
ENGRPH
GEARAT
KONFIG
PSD30P
PSD550
RUDIND
ZETATR

PARA

FORCE
STRIAB
STRIMA
MANAL
ROMAN
MANARO
TOPLOT
PD
VH
AIR
APF
ARE
AYE
AIM
BIM
HMR
HTR
KMI
OMX
QTR
TMR
TTR
ZZD
ALFL
ALTR
BLTR
CGHL
DTRR
EXIT
OMAX
TAXL
TAXR
TZMT
TZTT
TlMT
TlTT
T2MT
T2TT
VMRF
VTRF
ZETA
ALFIN
ALLWG
ALRWG
CGSTA
FKTS
NPASS
PEDAL

SOLVE

SOLVE

STRIAB
TOPLOT
X
KMI
EXIT
POPHI

DAMPER

DAMPER

STR1AB
EPD
DEPD
EPDX
XMIN
XLIM:1

ITRIM

ITRIM

XLIMIT

STPIAB
MANAL
MANARO
STANRO
TOPLOY
F
J
W
K
Y
PH
PD
APE
APF
AYF
AIM
RTD
BIM
ERR
ITM
KMI
TMR
TTR
VXB
VYR
VZR
XFC
AITR
BITR
DAMP
EPDX
EXIT
TAXL
TAXP
TMR5
TTPS
AYEFP
RETAE
CONDI
NPASS
POPHI
PEDAL
RETAES
CPLSTK
CYSTK1
CYSTK2
HALFPI
MXPASS

IVAR

IVAR

STRIMA
ROMAN
PSD
OMR
COLL
CYCF
CYCL
DTRR
KCIT
PEDA
PSDT
XCIT
RETAN
GMAXV
HURKI
HUBKM
HURKP
HUBKR
KREAD
PIU30
RATE1
RATE2
STOP2
XGUST
GMAXV1
GMAXV2
GMAXV3
HUBKTP
HUBKTR
LNGTH1
PTLGH1
PSISTP
OXRRAK
START2

P PLOT

P PLOT

TOPLOT
AH
AL
TPSN
NPART
N TIME
NVARA
NVARB
NVARC
NPRINT
NSCALE

CALL

CALL

TOPLOT
ICOM
IPSN
NSCALE

CURVET

CURVET

TRIPULT
AL
RVARA
RVARB
RVARC

FORCE

FORCE

A
AL
AM
AN
AO
AP
AQ
AR
AS
AT
AU
AV
AW
AX
AY
AZ
BA
BB
BC
BD
BE
BF
BG
BH
BI
BJ
BK
BL
BM
BN
BO
BP
BQ
BR
BS
BT
BU
BV
BW
BX
BY
BZ
CA
CB
CC
CD
CE
CF
CG
CH
CI
CJ
CK
CL
CM
CN
CO
CP
CQ
CR
CS
CT
CU
CV
CW
CX
CY
CZ
DA
DB
DC
DD
DE
DF
DG
DH
DI
DJ
DK
DL
DM
DN
DO
DP
DQ
DR
DS
DT
DU
DV
DW
DX
DY
DZ
EA
EB
EC
ED
EE
EF
EG
EH
EI
EJ
EK
EL
EM
EN
EO
EP
EQ
ER
ES
ET
EU
EV
EW
EX
EY
EZ
FA
FB
FC
FD
FE
FF
FG
FH
FI
FJ
FK
FL
FM
FN
FO
FP
FQ
FR
FS
FT
FU
FV
FW
FX
FY
FZ
GA
GB
GC
GD
GE
GF
GG
GH
GI
GJ
GK
GL
GM
GN
GO
GP
GQ
GR
GS
GT
GU
GV
GW
GX
GY
GZ
HA
HB
HC
HD
HE
HF
HG
HH
HI
HJ
HK
HL
HM
HN
HO
HP
HQ
HR
HS
HT
HU
HV
HW
HX
HY
HZ
IA
IB
IC
ID
IE
IF
IG
IH
II
IJ
IK
IL
IM
IN
IO
IP
IQ
IR
IS
IT
IU
IV
IW
IX
IY
IZ
JA
JB
JC
JD
JE
JF
JG
JH
JI
JJ
JK
JL
JM
JN
JO
JP
JQ
JR
JS
JT
JU
JV
JW
JX
JY
JZ
KA
KB
KC
KD
KE
KF
KG
KH
KI
KJ
KK
KL
KM
KN
KO
KP
KQ
KR
KS
KT
KU
KV
KW
KX
KY
KZ
LA
LB
LC
LD
LE
LF
LG
LH
LI
LJ
LK
LL
LM
LN
LO
LP
LQ
LR
LS
LT
LU
LV
LW
LX
LY
LZ
MA
MB
MC
MD
ME
MF
MG
MH
MI
MJ
MK
ML
MM
MN
MO
MP
MQ
MR
MS
MT
MU
MV
MW
MX
MY
MZ
NA
NB
NC
ND
NE
NF
NG
NH
NI
NJ
NK
NL
NM
NN
NO
NP
NQ
NR
NS
NT
NU
NV
NW
NX
NY
NZ
OA
OB
OC
OD
OE
OF
OG
OH
OI
OJ
OK
OL
OM
ON
OO
OP
OQ
OR
OS
OT
OU
OV
OW
OX
OY
OZ
PA
PB
PC
PD
PE
PF
PG
PH
PI
PJ
PK
PL
PM
PN
PO
PP
PQ
PR
PS
PT
PU
PV
PW
PX
PY
PZ
QA
QB
QC
QD
QE
QF
QG
QH
QI
QJ
QK
QL
QM
QN
QO
QP
QQ
QR
QS
QT
QU
QV
QW
QX
QY
QZ
RA
RB
RC
RD
RE
RF
RG
RH
RI
RJ
RK
RL
RM
RN
RO
RP
RQ
RR
RS
RT
RU
RV
RW
RX
RY
RZ
SA
SB
SC
SD
SE
SF
SG
SH
SI
SJ
SK
SL
SM
SN
SO
SP
SQ
SR
SS
ST
SU
SV
SW
SX
SY
SZ
TA
TB
TC
TD
TE
TF
TG
TH
TI
TJ
TK
TL
TM
TN
TO
TP
TQ
TR
TS
TT
TU
TV
TW
TX
TY
TZ
UA
UB
UC
UD
UE
UF
UG
UH
UI
UJ
UK
UL
UM
UN
UO
UP
UQ
UR
US
UT
UU
UV
UW
UX
UY
UZ
VA
VB
VC
VD
VE
VF
VG
VH
VI
VJ
VK
VL
VM
VN
VO
VP
VQ
VR
VS
VT
VU
VV
VW
VX
VY
VZ
WA
WB
WC
WD
WE
WF
WG
WH
WI
WJ
WK
WL
WM
WN
WO
WP
WQ
WR
WS
WT
WU
WV
WW
WX
WY
WZ
XA
XB
XC
XD
XE
XF
XG
XH
XI
XJ
XK
XL
XM
XN
XO
XP
XQ
XR
XS
XT
XU
XV
XW
XX
XY
XZ
YA
YB
YC
YD
YE
YF
YG
YH
YI
YJ
YK
YL
YM
YN
YO
YP
YQ
YR
YS
YT
YU
YV
YW
YX
YZ
ZA
ZB
ZC
ZD
ZE
ZF
ZG
ZH
ZI
ZJ
ZK
ZL
ZM
ZN
ZO
ZP
ZQ
ZR
ZS
ZT
ZU
ZV
ZW
ZX
ZY
ZZ

STRIAB

MLCG
XCOM
XJET
XMIN
AYEFP
CNPCD
GUFSS
NPASS
POPHI
SIACG
TZERO
BETAES
DODCOL
DIRRSO
ENGRPM
MKPASS
PSD30P
TRIND1
XLIMIT

STRIAB

STRIAB
D
F
F
X
OL
DM
DN
DT
DX
DY
DZ
IX
IY
IZ
PJ
DTR
EPD
ERR
KMI
RHO
PIZ
SPP
XBW
XEL
XEP
XFC
XFN
XFS
XGN
XIT
XMR
XTR
XWG
YEL
YFN
YMR
YTR
YWG
BLGG
DAMP
DEPD
EPDS
EPDX
MASS
OSVI
TMRS
TTRS

STRIMA

PSD550
PSISTP
OXBRK
RUDIND
ZDELT1
ZDELT2

STRIMA

STRIMA
AY
VH
AGW
DT1
DT2
TXZ
QMR
XXD
YYD
ZZD
ALGF
APFP
AYFP
CGWL
COLL
CYCF
CYCL
DIST
KCIT
PEDA
QMAX
OMRS
TIME
TMAX
XCIT
ALGEZ
ALGF1
ALGE2
CGSTA
CPWIC
DIXIZ
DIYIX
DIZIY
DTZMT
DTZM1
DTZT1
FTKTS
HURKI
HURKM
KREAD
PIU30
TSTA9
ZMAX2
ZMAX3
ASECOL
CYPWIC
GEARAT

ANDJIT

ANDJIT

ANDJIT
A1
HJ
KK
YY
VI2
VI4
APDM
APDS
APFM
ARDM
ARDS
APFM
AYFM
PFAC
PFAC
POTJ
XK43
XLIM
APDBS
ARDBS
CBFAC
GDISK
NOPSI
TANA1
TANB1
TANTI
TANT2
X40MD
X40ML
DCAFEXK
IPRINT
NOPADL
SHFARD
SHEARL
SHFARR

STAMAN

STAMAN

YGUST
ZAGUN
ZAPYL
ZARSP
BETAZS
DELT2R
ETMAST
GPRED
HLPYLD
IRRAKE
OMEGMD
PCGDED
PCGMAX
PCRATE
POIDTR
QBRAKE
RDELT1
RDELT2
RITORS
TRIND2

STAMAN
HL
RC
XX
YY
AY1
GOV
KPN
QPC
QOO
RIY
APBG
ARRG
ASFP
AYBG
BUTC
BMTK
RWTM
CGRL
COSE
DPIX
DPIZ
FMPT
R550
ALFRT
AYDMX
DELT2
DPIXZ
DTRWT
HOELT
HGUST
HLTR1
HLTR2
ISTTP
ITORS
KTCTR
OMEGM
PCDEL
QMRSA
RMASS
TRALT
TWPII
VGUST
XAGUN
XAPYL
XARSP
YAGUN
YARSP

MANAL

XAJET
XLOCK
YAFIN
ZAELE
ZAFIN
ZAFUS
ZAJET
ALECRI
ALGFPD
BOTTOM
CZET11
CZET12
CZET13
EIZETA
HALFPI
SZET10
TCLOCK
XAPYLD
YGUSTW
ZAPYLD
ZFLNG1

MANAL

MANAL
O
AP
PED
OMG
T2M
T2Y
T1M
T1Y
T2M
T2Y
ALEL
CZET
PSDD
SZET
TAXL
TAXR
XAMG
XLNK
ZAMG
ALCYP
ALFIN
ALLWG
ALRWG
GDELE
CDFIN
CDLWG
CDRWG
CLELE
CLFIN
CLLWG
CLOCK
CLRWG
CWMG
CYCR1
CYCR2
CZET4
CZET6
CZET9
FLOCK
RANGE
SZET5
SZET7
SZET8
WGCOL
XAELE
XAFIN
XAFUS

ROMAN

XSTAMT
YSTAMH
YSTAMT

ALBRT
APTTD
ARTTD
AZETA
BETAD
BETAN
BETAX
BETAZ
BNPSI
COMDZ
GMAXV
HUBKP
HUBKR
RATE1
RATE2
STOP2
THROT
TRIND
VZETA
XGUST
XMAIT
XMRIT
*XSTAH
*YSTAH
*AZETAR
AZETAT
BETAZD
GMAXV1
GMAXV2
GMAXV3
GUSTYP
HMPSIR
*HUBKPR
HUBKPS
*HUBKRR
HUBKRS
HUBKTP
HUBKTR
HURTPS
HUBTRS
KONFIG
LNGTH1
PILGH1
PSTREF
START2
*VZETAR
VZETAT
XSTAMH

ROMAN

ROMAN
*R
T
*OR
RM
*T1
*T2
ZZ
AIB
ATR
ORM
PCC
PSD
RTR
*TZR
VXS
VYS
VZS
*XMA
*XMB
*AIBP
*AIBR
APDD
*APDR
APTD
ARDD
*ARDR
ARTD
AYDD
BETA
DPSI
OTRR
NPST
ORTR
PSDT
*PSID
TZMT
TZTT
T1MT
T1TT
T2MT
T2TT
XMA1
XMB1
ZZTR
AIRPM
AIRPT
AIRRM

MAMARD

MAMARD

HGUSTE
HGUSTF
HGUSTM
*THRUST
*TORQUE
VGUSTE
VGUSTM
*YFORCF
YGUSTF
ZETATD

MAMARD
I
V
ADN
APE
APD
APE
AYD
AYE
AIM
RIM
HMR
HTR
IND
QMX
QTP
TMR
TTR
*VIR
VXB
VYB
VZB
XAR
YAR
ZAP
ALTR
HITR
GFWJ
GLAT
NWAG
VIMR
VITR
YMPF
YTRF
ZETA
APBMT
ARBMT
AYBMT
BETA
BETAJ
GVERT
PEDAL
TDELT
*ZFTAR
COLSTK
CYSTK1
CYSTK2
*MFJRC

STANRO

STANRO

*B
J
W
RM
BTR
ITM
VHS
LINK
*PMOM
DELE
*RMOM
VROT
VSND
VFIN
ZFEL
AIRAL
BIBAL
CONDI
PMOMM
PMOHT
RMOMM
RMOMT
SWING
PILGH2
PMGEL1

ROSTAR

ROSTAR

AM
CT
*EP
PI
XB
ALT
ADR
ERM
*ERX
EXH
NXR
RBM
SMC
UHS
COHB
ERTR
ERXM
ERXT
LROT
RAIB
RTRP
TAIR
CONEK
OCAFR
FVIND
NWARD
SMR1
SMR2
TIPIB
TIP38
TWIST
CLRADK
DELTA3
LAMBDA
UPGUST
URGUST
UTGUST
WROTOR
*XLIMAX
*XLIMIN
XLMAXM
XLMAXT
XLMINH
XLMINT

TOPLOT

TOPLOT

TOPLOT
AH
AL
EXIT
ICDH
IPSN
NPART
NTIME
NVARA
NVARB
NVARC
NVAR5
NPRINT
NSCALE

STARAN

CNPCDZ
COLJET
DXNGEL
DZNGEL
EYAOHX
PWGKI
RCWING
SWINGH
VENTER
VXNVER
YALJET
YARJET

STARAN

STARAN
BH
C2
C4
RH
CLP
CLP
DGD
DQL
DON
VIV
VFS
RATR
CLRD
CNRO
FTAO
NJET
QFIN
T7MS
T7TS
T1MS
T1TC
T2MS
T2TS
VIFR
CLBCL
CNBCL
CNPCL
CNPCD
CNRCL
COLKS
D3ELF
FNSWC
LWING
PMREL
PMRWG
PTRFN
RP1ST
VMAXE
YAFLE
YAERO
YAFUS
YALWG
YARWG
APBJET
ARBJET
AYSJET
CNPCDI

APPENDIX D

SUBROUTINES CONTAINING EACH VARIABLE, BY COMMON

VARIABLE	CS	SR	ST	EA	AD	IR	TI	MT	VI	IR	DA	CS	SW	MI	VP	PG	WT	MS	LL	LS	JA	OW	TR	PA	SO	DI	IP	CC
FORCE																												
A		X									X			X														
QL				X							X			X														
Q4				X							X			X														
Q8				X							X			X														
XF		X		X							X			X														
YF				X							X			X														
ZF				X							X			X														
LNR				X							X			X														
LTR				X							X			X														
MNR				X							X			X														
MTR				X							X			X														
NMR				X							X			X														
NTR				X							X			X														
XFM				X							X			X														
YFM				X							X			X														
ZFM				X							X			X														
LELE				X							X			X														
LEFI				X							X			X														
LFUS				X							X			X														
LGUN				X							X			X														
LLWG				X							X			X														
LQMR				X							X			X														
LOTR				X							X			X														
LRWG				X							X			X														
MELE				X							X			X														
MFIN				X							X			X														
MFUS				X							X			X														
MGUN				X							X			X														
MLWG				X							X			X														
MOHR				X							X			X														
MOTR				X							X			X														
MRWG				X							X			X														
NELE				X							X			X														
NFIN				X							X			X														
NFUS				X							X			X														
NGUN				X							X			X														
NLWG				X							X			X														
NQMR				X							X			X														
NQTR				X							X			X														
NRWG				X							X			X														
XFMR				X							X			X														
XFTR				X							X			X														
YFMR				X							X			X														
YFTR				X							X			X														
ZFMR				X							X			X														
ZFTR				X							X			X														
LLJET				X							X			X														

FORCE

```

C S R C M T I V R I D A C S W M I V P G T M S L L S J A O W T P S D I T P C C
R T E O N E M R N D N T R O O L D S T U T I R A M A C U I R T M A E A J F R R A O A T V P 8 U
I A D I M I O O M T T X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X
T I N X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X
A C S W M I V P G T M S L L S J A O W T P S D I T P C C
R T E O N E M R N D N T R O O L D S T U T I R A M A C U I R T M A E A J F R R A O A T V P 8 U
I A D I M I O O M T T X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X
T I N X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X

```

```

VARIABLE
FORCE
LRJET
MRJET
NRJET
XFFELE
XFFIN
XFFUS
XFGUN
XFLMG
XFRMG
YFFIN
YFFUS
YFGUN
ZFFELE
ZFFUS
ZFGUN
ZFLMG
ZFRMG
XFLJET
XFRJET
YFLJET
YFRJET
ZFLJET
ZFRJET

```

FORCE

VARIABLE	C	S	R	C	M	T	I	V	R	I	D	A	C	S	W	R	A	N	A	G	I	V	P	G	T	M	S	L	L	S	J	A	D	M	T	P	S	O	I	I	P	C	C						
STRIAB	X	X	X																																														
D	X	X																																															
F																																																	
F																																																	
DL																																																	
DM																																																	
DN																																																	
DX																																																	
DY																																																	
DZ																																																	
IX	X	X	X																																														
IY	X	X	X																																														
IZ	X	X	X																																														
PD																																																	
DTR	X																																																
EPD	X																																																
ERR	X																																																
KM1	X																																																
RHM	X																																																
PI2	X																																																
SPD	X																																																
XBW	X	X	X																																														
XEL	X	X	X																																														
XER	X	X	X																																														
XFC	X	X	X																																														
XFN	X	X	X																																														
XFS	X	X	X																																														
XGN	X	X	X																																														
XIT	X	X	X																																														
XMR	X	X	X																																														
XTR	X	X	X																																														
XMG	X	X	X																																														
YFL	X	X	X																																														
YFN	X	X	X																																														
YMR	X	X	X																																														
YTR	X	X	X																																														
YMG	X	X	X																																														
BLCG																																																	
DAMP																																																	
DEPO																																																	
EPDS																																																	
FPDX																																																	
MASS																																																	
OSVI																																																	
TMRS																																																	
TTRS																																																	

C	S	R	C	M	T	I	V	R	I	D	A	C	S	M	I	V	P	G	T	W	S	L	S	J	A	D	W	T	P	S	D	I	I	P	C	C		
R	T	E	O	N	I	N	I	O	T	O	N	L	M	R	A	N	A	C	U	I	R	T	M	A	E	A	J	F	R	R	A	O	A	T	V	P	8	U
I	A	A	D	I	M	I	O	A	D	T	R	A	C	A	D	M	I	R	G	S	L	F	A	D	O	E	C	A	F	V	I	R	M	A	L	I	R	
T	I	M	I	O	A	D	T	R	A	C	A	D	O	L	D	S	T	U	T	I	F	M	B	E	D	B	O	R	M	A	E	M	A	E	M	A	E	
VARIABLE																																						
STRIAB	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X		
MLCG	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X		
XCON	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X		
XJET	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
XMIN	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
AYEFP	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
CNPCD	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
GUESS	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
NPASS	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
PDPHI	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
STACG	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
TZERO	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
RETAFS	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
DQDCOL	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
DTRRSQ	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
ENGRPH	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
MPASS	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
PSD30P	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
TRINDI	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
XLIMIT	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X

STRIAB


```

CSRCM T I V R I D A C S W M I V P G T W S L S J A O W T P S D I I P C C
8TEO N I M I O T R R A C A O T U T I R T M A E A J F R R A A O A T V P B U
1 A A M N M Y R R A C A O T U T I R T M A E A J F R R A A O A T V P B U
T I M I O D A G Y L D S T U T I R T M A E A J F R R A A O A T V P B U
T I M I O D A G Y L D S T U T I R T M A E A J F R R A A O A T V P B U
T I M I O D A G Y L D S T U T I R T M A E A J F R R A A O A T V P B U

```

-VARIABLE
 STRIMA
 PSD550
 PSJSTP
 OXBRAK
 RUOIND
 ZDELT1
 ZDELT2

STRIMA

ANDDIT

C S R C M T I V R I O A C S W R A N A G U I R T M A E A J F R R A O A T V P 8 U
 B T E O N I N I O T T R R A C C A O N I R G S L F A O M T C C A F V I R L M A L O L V
 I A A R D I M I O D M T T X
 T I R I O A C S W R A N A G U I R T M A E A J F R R A O A T V P 8 U
 T I M

VARIABLE

ANDDIT	
A1	
B1	X
XK	X
XY	X
VI2	X
VI4	X
APDM	X
APDS	X
APEM	X
ARDM	X
ARDS	X
ARFM	X
AYEM	X
PFAC	X
RFAC	X
ROTJ	X
XK*3	X
XLIM	X
APDBS	X
ARDBS	X
CBFAC	X
GDISK	X
NOPSI	X
TANAI	X
TANBI	X
TANT1	X
TANT2	X
XMOMD	X
XMOML	X
DCAFEX	X
IPPINT	X
NORADL	X
SHEARJ	X
SHEARL	X
SHEARR	X

C S R C M T I V R I O T R A C A O L D S T U T I V P G T W S L S J A O W T P S D I I P C G
 I T A A N E M R N T R A C A O L D S T U T I R G T T M B E E B O R I B M A E A J F R R A O M R A L I R
 R D I M I O D A O T T N T T A O O L D S T U T I G T T M B E E B O R I B M A E A J F R R A O M R A L I R
 T I N T T N T T A O O L D S T U T I G T T M B E E B O R I B M A E A J F R R A O M R A L I R

STAMAN

VARIABLE
 STAMAN
 HL
 PC
 XX
 YY
 AYI
 GOV
 KPD
 OPC
 OOO
 PIY
 APBG
 ARBG
 ASFP
 AYBG
 BWTC
 BWTK
 BWTM
 CGBL
 COSE
 DPIX
 DPIZ
 FHPT
 R550
 ALERT
 AYDMX
 DELTZ
 DPIXZ
 DYBWT
 HDEL
 HGUST
 HLTR1
 HLTR2
 ISTOP
 ITORS
 KTCTR
 OMEGH
 PCDEL
 QMRSA
 RMASS
 TRALT
 TWOPT
 VGUST
 XAGUN
 XAPYL
 XARSP
 YAGUN
 YARSP

C S R C M T I V R I D A C S W M I V P G T M S L L S J A D W T P S D I I P C C
8 T E O N I N I O T O R A C A O N I R G S L F A D M T C A C T P M A E E M R X
I A A D I M I O D A N T T X
T I N X
C S R C M T I V R I D A C S W M I V P G T M S L L S J A D W T P S D I I P C C
8 T E O N I N I O T O R A C A O N I R G S L F A D M T C A C T P M A E E M R X
I A A D I M I O D A N T T X
T I N X

MANAL

VARIABLE

MANAL
O
AP
PED
OMG
IZM
T2T
T1T
T1T
T2M
T2T
ALEL
CZET
PSDD
SZET
TAXL
TAXR
XAWG
XLNK
ZANG
ALCYP
ALFIN
ALLWG
ALRNG
COELE
CDFIN
COLWG
CORWG
CLELE
CLFIN
CLLWG
CLOCK
CLRNG
CWING
CYCR1
CYCR2
CZET4
CZET6
CZET9
FLOCK
RANGE
SZET5
SZET7
SZET8
WGCOL
XAELE
XAFIN
XAFUS

VARIABLE	C	S	R	E	O	N	E	M	I	D	A	C	S	W	M	I	V	P	G	T	W	S	L	L	S	J	A	O	W	T	P	S	D	I	I	P	C	C	
MANAL	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
XAJET	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
XLOCK	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
YAFIN	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZAFLE	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZAFIN	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZAFUS	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZAJET	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ALECR1	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ALGFPD	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
BOTTOM	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
CZET11	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
CZET12	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
CZET13	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
EIZETA	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
HALFPI	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
SZET10	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
TCLOCK	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
XAPYLD	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
YGUSTW	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZAPYLD	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
ZFLMG1	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	

VARIABLE	ROMAN	AI	BI	CI	DI	EI	FI	GI	HI	II	LI	MI	NI	OI	PI	RI	SI	TI	UI	VI	WI	XI	YI	ZI
ROMAN	X																							
AI		X																						
BI			X																					
CI				X																				
DI					X																			
EI						X																		
FI							X																	
GI								X																
HI									X															
II										X														
LI											X													
MI												X												
NI													X											
OI														X										
PI															X									
RI																X								
SI																	X							
TI																		X						
UI																			X					
VI																				X				
WI																					X			
XI																						X		
YI																							X	
ZI																								X

C	S	R	C	M	I	V	R	I	D	A	C	S	W	M	I	V	P	G	T	W	S	L	L	A	E	A	J	F	R	A	D	A	J	A	D	W	T	P	S	D	I	I	P	C	G												
8	T	E	O	M	I	N	I	O	T	O	N	L	W	R	A	N	A	C	G	U	I	R	T	M	S	L	L	A	E	A	J	F	R	A	D	A	J	A	D	W	T	P	S	D	I	I	P	C	G								
L	A	A	N	E	R	N	T	R	R	A	C	A	D	N	I	R	G	T	T	F	A	D	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E									
R	O	I	M	I	O	O	N	T	T						X	X	X																																								
T	I														X	X	X																																								
VARIABLE	X																																																								
ROMAN																																																									
XSTAHM																																																									
XSTIAHI																																																									
YSTAHM																																																									
YSTAHT																																																									

ROMAN

VARIABLE	C	S	R	C	M	T	I	V	R	I	D	A	C	S	M	I	V	P	G	T	W	S	L	L	S	J	A	O	M	T	P	S	D	I	I	P	C	C		
MANARO																																								
HGUSTE																																								
HGUSTW																																								
*THRUST																																								
*TORQUE																																								
VGUSTE																																								
VGUSTW																																								
*YFORCE																																								
YGUSTF																																								
ZETATr																																								

MANARO

STANRO

```

C  S R C M T I V R I D A C S W R A N A C S I R S T T M R F E I B M X X
B  T F O M I N R N A O O L D S T U T I   X
I  A A D I M I T X X X X X X X X X X X X X X X X X X X X X X X X X X X X
T  P I T I N X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X X
VARIABLE
STANRO   X
#9      X
J        X
W        X
B4       X
BTP      X
ITM      X
VHS      X
LINK     X
*PMOM    X
OELE     X
*RMOM    X
VRGT     X
VSND     X
YFIN     X
ZFEL     X
AIBAL    X
BIBAL    X
CONDI    X
PMOMH    X
PMOMT    X
RMOMH    X
RMOMT    X
SWING    X
PILGH2   X
PWGEL1   X

```

STANRO

```

C  S L S J A O W T P S D I I P C C
B  L S J A O W T P S D I I P C C
I  L S J A O W T P S D I I P C C
T  L S J A O W T P S D I I P C C
VARIABLE
STANRO   X
#9      X
J        X
W        X
B4       X
BTP      X
ITM      X
VHS      X
LINK     X
*PMOM    X
OELE     X
*RMOM    X
VRGT     X
VSND     X
YFIN     X
ZFEL     X
AIBAL    X
BIBAL    X
CONDI    X
PMOMH    X
PMOMT    X
RMOMH    X
RMOMT    X
SWING    X
PILGH2   X
PWGEL1   X

```

ROSTAR

```

C S R C M T I V R I D A C S M H I V P G T M S L L S J A O M T P S D I I P C C
O T E O M I N I O T O N L M R A M A C U I R T M A E A J F R K R A D A T V P B U
I A A M E M N R M T R A C A O N I R G S L F A O M T C C A F V I R L V P I R
T I M I T R I D I M I T R I D I M I T R I D I M I T R I D I M I T R I D I M I T
VARIABLE
ROSTAR X X X X X X
AM X X X
CT X X X
ER X X X
PI X X X
XB X X X
ALT X X X
ADR X X X
ERM X X X
ERX X X X
EXH X X X
NXR X X X
RBH X X X
SWC X X X
UHS X X X
CDMB X X X
ERTR X X X
ERXM X X X
ERTX X X X
LROT X X X
RAIB X X X
RTRP X X X
TAIR X X X
CONEK X X X
DCAFR X X X
FVIND X X X
NWARD X X X
SWKR1 X X X
SWKR2 X X X
TIP18 X X X
TIP38 X X X
TWIST X X X
CLRADK X X X
DELTA3 X X X
LAMBDA X X X
JPGUST X X X
URGUST X X X
UTGUST X X X
WROTOR X X X
XLIMAX X X X
XLIMIN X X X
XLMAXM X X X
XLMAXT X X X
XLMINH X X X
XLMINT X X X

```

TOPLOT

VARIABLE	TOPLOT	TCOM	NPRINT	NSCALE
8				
1				
S	X	X	X	X
R				
I				
M		X	X	X
H	X	X	X	X
I				
N				
T				
C	X		X	X
M				
I	X	X	X	X
V				
R	X	X	X	X
I				
O		X	X	X
T	X	X	X	X
R		X	X	X
A	X	X	X	X
O				
L				
C				
A				
S	X	X	X	X
W				
M	X	X	X	X
I				
V	X	X	X	X
P				
G				
T	X	X	X	X
W				
S				
L				
L				
M	X	X	X	X
A				
E				
J	X	X	X	X
A				
O	X	X	X	X
M				
F				
R				
R				
A				
O	X	X	X	X
A				
T	X	X	X	X
V				
I				
R	X	X	X	X
P				
I				
I	X	X	X	X
P				
C	X	X	X	X

STARAN

VARIABLE	C	S	R	I	D	A	C	S	H	M	I	V	P	G	T	W	S	L	L	S	J	A	O	W	T	P	S	O	I	I	P	C	C		
STARAN	X																																		
RH	X																																		
C3		X																																	
C4		X																																	
PH			X																																
CLP				X																															
CLD					X																														
OCN						X																													
NOL							X																												
DON								X																											
VIW									X																										
YES										X																									
BATH											X																								
CLRD												X																							
CNRD													X																						
FTAQ														X																					
NJFT															X																				
OFIN																X																			
TZMS																	X																		
TZTS																		X																	
TIWS																			X																
TITS																				X															
TZMS																					X														
TZTS																						X													
VIFR																							X												
CLACL																								X											
CNPCI																								X											
CNPCI																								X											
C.NPCN																								X											
CNPCI																								X											
CJLKS																								X											
DELF																								X											
FNSWC																								X											
LWING																								X											
P4RFL																								X											
P4RWG																								X											
PTPEM																								X											
P1ST																								X											
VMAXE																								X											
YAFLE																								X											
YAFRO																								X											
YAFUS																								X											
YALWG																								X											
Y4RWG																								X											
APRJFT																								X											
ARBJFT																								X											
AVGJFT																								X											
C.VPCNI																								X											

VARIABLE	STARAN
STARAN	X
CUPC02	X
COLJFY	X
DXMCEL	X
DWGEI	X
ETAQXX	X
PMGKI	X
RCAWIS	X
SWINGH	X
VENTFR	X
VXWVEI	X
YALJFI	X
YAPJFI	X

S P C M T I V R I D A C S W M I V P G T M R T M A E A J A U W R R A O A T V P B U
 Y P G N I N I O T R R A C A F N I R S L F A O O E O C C Y P M A E E M R
 T A A N E N R N T R R A C A F N I R S L F A O O E O C C Y P M A E E M R
 P D I M I O O N T T
 V I N I O O N T T
 V R I O O N T T
 I D A C S W M I V P G T M R T M A E A J A U W R R A O A T V P B U
 T R R A C A F N I R S L F A O O E O C C Y P M A E E M R
 R A C A F N I R S L F A O O E O C C Y P M A E E M R
 A C A F N I R S L F A O O E O C C Y P M A E E M R
 C A F N I R S L F A O O E O C C Y P M A E E M R
 A F N I R S L F A O O E O C C Y P M A E E M R
 F N I R S L F A O O E O C C Y P M A E E M R
 N I R S L F A O O E O C C Y P M A E E M R
 I R S L F A O O E O C C Y P M A E E M R
 R S L F A O O E O C C Y P M A E E M R
 S L F A O O E O C C Y P M A E E M R
 L F A O O E O C C Y P M A E E M R
 F A O O E O C C Y P M A E E M R
 A O O E O C C Y P M A E E M R
 O O E O C C Y P M A E E M R
 O E O C C Y P M A E E M R
 E O C C Y P M A E E M R
 C C Y P M A E E M R
 Y P M A E E M R
 P M A E E M R
 M A E E M R
 A E E M R
 E E M R
 E M R
 M R
 R
 B U

APPENDIX E
PROGRAM SECTIONS CONTAINING EACH VARIABLE, BY COMMON

VARIABLE	C	S	R	A	M	S	T	P
FORCE	X	X	X	X	X	X	X	X
STRIAB	X	X	X	X	X	X	X	X
STKIMA	X	X	X	X	X	X	X	X
ANDUIT	X	X	X	X	X	X	X	X
STAMAN	X	X	X	X	X	X	X	X
MANAL	X	X	X	X	X	X	X	X
POMARJ	X	X	X	X	X	X	X	X
MANARJ	X	X	X	X	X	X	X	X
STAMPJ	X	X	X	X	X	X	X	X
POSTAR	X	X	X	X	X	X	X	X
TOPLOT	X	X	X	X	X	X	X	X
STARAN	X	X	X	X	X	X	X	X

C S R A M S T P
 9 T O N A T R P
 I A T A N A I L
 T R A L U B M T

VARIABLE
 F TRCF X X X X X X
 A X X X X X
 OL X X X X X
 OM X X X X X
 ON X X X X X
 OF X X X X X
 LMR X X X X X
 LTP X X X X X
 MPM X X X X X
 MTR X X X X X
 NMR X X X X X
 NTR X X X X X
 XFW X X X X X
 YFW X X X X X
 ZFW X X X X X
 LELE X X X X X
 LETN X X X X X
 LFUS X X X X X
 LGUN X X X X X
 LLWG X X X X X
 LQMR X X X X X
 LQTR X X X X X
 LRWG X X X X X
 MELE X X X X X
 METN X X X X X
 MEUS X X X X X
 MGIN X X X X X
 MLWG X X X X X
 MMR X X X X X
 MOTO X X X X X
 MPMG X X X X X
 NELE X X X X X
 NEIN X X X X X
 NEUS X X X X X
 NGUN X X X X X
 NLWG X X X X X
 NQMR X X X X X
 NQTR X X X X X
 NRNG X X X X X
 XFMP X X X X X
 XFTO X X X X X
 YEMR X X X X X
 YETR X X X X X
 ZEMP X X X X X
 ZFTO X X X X X
 IJST X

FORCE

STRIAB

VARIABLE	STR	IA	B	ST	TR	P
STRIAB	X	X	X	X	X	X
D	X					
E						
F						
X						
DL						
DM						
DN						
DT						
DX						
DY						
DZ						
IX						
IY						
IZ						
PD						
OYR						
EDD						
ERR						
KM1						
RHO						
R12						
SPD						
XBH						
XEL						
XER						
XEC						
XFN						
XFS						
XGN						
XIT						
XMR						
XTR						
XWG						
YEL						
YFN						
YMR						
YTR						
YMG						
BLCG						
DAMP						
DEPD						
EPDS						
EPDX						
MASS						
OSV1						
TMRS						
TTRS						

C S R A M S T P
 R T O N A T R P
 I A T A N A I L
 P A L U B M O
 T N

VARIABLE
 STRIAB X X X
 WLCG X X
 XCON X X
 XJET X X
 XMIN X X
 AYEFP X X
 CVPCD X X
 GUESS X X
 NPASS X X
 POPHI X X
 STAGG X X
 TZERO X X
 BETAES X X
 DQDCOL X X
 DTRRSQ X X
 ENGRPM X X
 MXPASS X X
 PSD30P X X
 TRINDI X X
 XLIMIT X X

STRIB

C S R A M S T P
 8 T O N A T R P
 I A T A N A I L
 R A L U B M O
 T N

VARIABLE	C	S	R	A	M	S	T	P
STRIMA	X							
AY				X	X	X		
VH	X			X	X	X		
AGW	X			X	X	X		
DIF1	X			X	X	X		
OT2	X			X	X	X		
IXZ	X			X	X	X		
QMR	X			X	X	X		
XXD	X			X	X	X		
YYD	X			X	X	X		
ZZD	X			X	X	X		
ALGF	X			X	X	X		
APFP	X			X	X	X		
AYFP	X			X	X	X		
CGWL	X			X	X	X		
COLL	X			X	X	X		
CYCF	X			X	X	X		
CYCL	X			X	X	X		
DIST	X			X	X	X		
KCIT	X			X	X	X		
PEDA	X			X	X	X		
QMAX	X			X	X	X		
QMS	X			X	X	X		
TIME				X	X	X		
TMAX	X			X	X	X		
XCIT	X			X	X	X		
ALGEZ	X			X	X	X		
ALGF1	X			X	X	X		
ALGE2	X			X	X	X		
CGSTA	X			X	X	X		
CPWIC	X			X	X	X		
DIXIZ	X			X	X	X		
DIXIX	X			X	X	X		
DIZIY	X			X	X	X		
DTZMT	X			X	X	X		
DTZM1	X			X	X	X		
DTZT1	X			X	X	X		
FKTS	X			X	X	X		
HJJKI	X			X	X	X		
HURK4	X			X	X	X		
KRFAD	X			X	X	X		
PIU3C	X			X	X	X		
TSTAB	X			X	X	X		
ZMAX2	X			X	X	X		
ZMAX3	X			X	X	X		
ASFCOL	X			X	X	X		
CYPMIC	X			X	X	X		
GEARAT	X			X	X	X		

STRIMA

C S R A M S T P
8 T O N A T R P
1 A T A N A I L
T R A L U R M O
T N

VARIABLE
STRIMA
PSD55
PSISTP
OXBRK
RJJND
ZDELT1
ZDELT2

STRIMA

X X X
X X X
X X X
X X X
X X X
X X X
X X X

C S R A M S T P
B T O M A T R P
I A T A N A I L
R A L U B M O
T N

VARIABLE	ANDOTT
ANDOTT	X
A1	X
B1	X
XK	X
XY	X
VI2	X
VI4	X
APDH	X
APDS	X
APFM	X
ARDM	X
ARDS	X
ARFM	X
AYFM	X
PFAC	X
RFAC	X
ROTJ	X
XK43	X
XLIM	X
APDBS	X
ARDBS	X
CBFAC	X
GDISK	X
NDPSI	X
TANAI	X
TANBI	X
TANT1	X
TANT2	X
XMOMD	X
XMOML	X
OCAFXX	X
IPRINT	X
NORAOL	X
SHEARD	X
SHEARL	X
SHEARR	X

STAMAN

C S R A M S T P
9 T 0 N A T R P
1 A T A N A I L
T R A L L U B M O Y
T M

VARIABLE
STAMAN X
HL X
PC X
XX
YY X
AYI X
GVV X
KPD X
QPC X
QJO X
RTV X
APBG X
ARBG X
ASEP X
AYBG X
BUTC X
BWK X
BWTM X
CGBL X
CUSE X
DPIX
DPIZ X
FHPT X
R550 X
ALERT X
AYDMX
DELT2 X
DPIX2 X
DTAWT X
HDELT X
HGUST X
HLTR1 X
HLTR2 X
ISTOP X
ITORS X
KTCTR X
UMEGM X
PCDEL X
OMRSA X
RMASS X
TRALT X
TMOPI X
VGUST X
YAGUN X
XAPYL X
XARSP X
YAGUN X
YARSP X

C S P A M S T P
 R T O : A T R P
 I A T A N A I L
 R A L U B M O
 Y N

VARIABLE

STAMAN X
 YGUST X
 ZAGIN X
 ZAPYL X
 ZASP X
 RETA7S X
 DELT28 X
 ETMAST X
 GPPELD X
 HLPYLD X
 LBRAKE X
 LMEGND X
 PCGDED X
 PCGMAX
 PCRATF X
 POLDTR X
 URBAKE X
 SBELTI X
 BDELTP X
 RTOPS X
 T-IND2 X

STAMAN

MANAL

VARIABLE	C	S	P	A	M	S	T	P
MANAL	X	X	X	X	X	X	X	X
O	X	X	X	X	X	X	X	X
AP	X	X	X	X	X	X	X	X
PED	X	X	X	X	X	X	X	X
OMG	X	X	X	X	X	X	X	X
TZM	X	X	X	X	X	X	X	X
TZT	X	X	X	X	X	X	X	X
T1M	X	X	X	X	X	X	X	X
T1T	X	X	X	X	X	X	X	X
T2M	X	X	X	X	X	X	X	X
T2T	X	X	X	X	X	X	X	X
ALEL	X	X	X	X	X	X	X	X
CZFT	X	X	X	X	X	X	X	X
PSDD	X	X	X	X	X	X	X	X
SZET	X	X	X	X	X	X	X	X
TAXL	X	X	X	X	X	X	X	X
TAXR	X	X	X	X	X	X	X	X
XAWG	X	X	X	X	X	X	X	X
XLNK	X	X	X	X	X	X	X	X
ZAWG	X	X	X	X	X	X	X	X
ALCYP	X	X	X	X	X	X	X	X
ALFIN	X	X	X	X	X	X	X	X
ALLWG	X	X	X	X	X	X	X	X
ALRMG	X	X	X	X	X	X	X	X
CDELE	X	X	X	X	X	X	X	X
CDFIN	X	X	X	X	X	X	X	X
COLWG	X	X	X	X	X	X	X	X
CDRMG	X	X	X	X	X	X	X	X
CLFLE	X	X	X	X	X	X	X	X
CLFIN	X	X	X	X	X	X	X	X
CLLWG	X	X	X	X	X	X	X	X
CLOCK	X	X	X	X	X	X	X	X
CLRMG	X	X	X	X	X	X	X	X
CWING	X	X	X	X	X	X	X	X
CYCR1	X	X	X	X	X	X	X	X
CYCR2	X	X	X	X	X	X	X	X
CZET4	X	X	X	X	X	X	X	X
CZET6	X	X	X	X	X	X	X	X
CZET9	X	X	X	X	X	X	X	X
FLOCK	X	X	X	X	X	X	X	X
RANGE	X	X	X	X	X	X	X	X
SZET5	X	X	X	X	X	X	X	X
SZFT7	X	X	X	X	X	X	X	X
SZET8	X	X	X	X	X	X	X	X
WGCOL	X	X	X	X	X	X	X	X
XAELE	X	X	X	X	X	X	X	X
XAFIN	X	X	X	X	X	X	X	X
XAFUS	X	X	X	X	X	X	X	X

VARIABLE	CS	RAM	ST	P
MANAL	X	X	X	X
XAJET	X	X	X	X
XLOCK	X	X	X	X
YAFI:	X	X	X	X
ZAELE	X	X	X	X
ZAEIN	X	X	X	X
ZAFUS	X	X	X	X
ZAJET	X	X	X	X
ALECR1	X	X	X	X
ALGFPD	X	X	X	X
BOTTOM	X	X	X	X
CZET11	X	X	X	X
CZET12	X	X	X	X
CZET13	X	X	X	X
EIZETA	X	X	X	X
HALFPI	X	X	X	X
SZET10	X	X	X	X
TCLOCK	X	X	X	X
XAPYLD	X	X	X	X
YGUSTW	X	X	X	X
ZAPYLD	X	X	X	X
ZFLWGI	X	X	X	X

MANAL

ROMAN

CSRA MSTRP
 8TONA TRLP
 IATANAILL
 TRALUBMOT

VARIABLE

ROMAN X X X X
 *R X X X X
 *OR X X X X
 RM X X X X
 *T1 X X X X
 *T2 X X X X
 ZZ X X X X
 AIB X X X X
 AIR X X X X
 ORM X X X X
 PCC X X X X
 PSD X X X X
 RTT X X X X
 *TZR X X X X
 VXS X X X X
 VYS X X X X
 VZS X X X X
 *XMA X X X X
 *XMB X X X X
 *AIBP X X X X
 *AIBR X X X X
 APDD X X X X
 *APDR X X X X
 APTD X X X X
 APOD X X X X
 *AROK X X X X
 ARTO X X X X
 AYDD X X X X
 BETA X X X X
 DPSI X X X X
 DYRR X X X X
 NPSI X X X X
 ORTK X X X X
 *SOT X X X X
 *PSID X X X X
 TZMT X X X X
 TZTT X X X X
 TIMT X X X X
 TITT X X X X
 T2MT X X X X
 T2TT X X X X
 XMA1 X X X X
 XMB1 X X X X
 ZZTR X X X X
 AIBPM X X X X
 ATRPT X X X X
 AIBRM X X X X

ROMAN

VARIABLE	C	S	R	A	M	S	T	P
ROMAN	X	X	X	X	X	X	X	X
AIART	X	X	X	X	X	X	X	X
APTTD	X	X	X	X	X	X	X	X
ARTTD	X	X	X	X	X	X	X	X
AZETA	X	X	X	X	X	X	X	X
BETAD	X	X	X	X	X	X	X	X
BETAN	X	X	X	X	X	X	X	X
BETAX	X	X	X	X	X	X	X	X
BETAZ	X	X	X	X	X	X	X	X
BNPSI	X	X	X	X	X	X	X	X
COND?	X	X	X	X	X	X	X	X
GMAXV	X	X	X	X	X	X	X	X
HUBKP	X	X	X	X	X	X	X	X
HUBKR	X	X	X	X	X	X	X	X
RATE1	X	X	X	X	X	X	X	X
RATE2	X	X	X	X	X	X	X	X
STOP?	X	X	X	X	X	X	X	X
THROT	X	X	X	X	X	X	X	X
TRIND	X	X	X	X	X	X	X	X
VZETA	X	X	X	X	X	X	X	X
XGUST	X	X	X	X	X	X	X	X
XMAIT	X	X	X	X	X	X	X	X
XMBIT	X	X	X	X	X	X	X	X
*XSTAH	X	X	X	X	X	X	X	X
*YSTAH	X	X	X	X	X	X	X	X
*AZETAR	X	X	X	X	X	X	X	X
AZETAT	X	X	X	X	X	X	X	X
RETAZD	X	X	X	X	X	X	X	X
GMAXV1	X	X	X	X	X	X	X	X
GMAXV2	X	X	X	X	X	X	X	X
GMAXV3	X	X	X	X	X	X	X	X
GUSTY?	X	X	X	X	X	X	X	X
HNPSTR	X	X	X	X	X	X	X	X
*HUBKPR	X	X	X	X	X	X	X	X
HUBKPS	X	X	X	X	X	X	X	X
*HUBKRQ	X	X	X	X	X	X	X	X
HUBKRS	X	X	X	X	X	X	X	X
HUBKTD	X	X	X	X	X	X	X	X
HUBKTR	X	X	X	X	X	X	X	X
HUBTPS	X	X	X	X	X	X	X	X
HU3TPS	X	X	X	X	X	X	X	X
KONFIG	X	X	X	X	X	X	X	X
LNGLHI	X	X	X	X	X	X	X	X
PTLGH1	X	X	X	X	X	X	X	X
PSIREF	X	X	X	X	X	X	X	X
START?	X	X	X	X	X	X	X	X
*VZFTAR	X	X	X	X	X	X	X	X
VZFTAT	X	X	X	X	X	X	X	X

C S R A M S T P
R T I N A T R P
I A T A N A I L
T P A L U B M O
T N

VARIABLE
ROMAN X X X X X
XSTAHX X X X
YSTAHX X X X
YSTAHX X X X

ROMAN

MAMARO

C S R A H S T P
B T O N A T R P
L A T A N A I L L
T R A L U B M O
T N

VARIABLE	MANARO	I	V	APD	APE	ARD	ARE	AYD	AYE	AJM	BIM	HNR	HTR	IND	QHX	QYR	TMR	IIR	VIR	VXB	VYB	VZB	XAR	YAR	ZAR	AITR	BITR	GFWD	GLAT	NMAG	VIMR	VITR	YMRF	YTRF	ZETA	APBHI	ARBHT	AYBHT	BETAE	RETAO	GVERT	PEDAL	TDELT	*ZETAR	COLSTK	CYSTK1	CYSTK2	*HFORCE	
	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X

MANARD

C S R A M S T P
 8 T O N A T R P
 I A T A N A I L
 Y N R A L U B M O T

VARIABLE
 MANARD X X X X X X
 HGUSTE X X X X X
 HGUSTF X X X X X
 HGUSTW X X X X X
 *THRUST X X X X X
 *TORQUE X X X X X
 VGUSTE X X X X X
 VGUSTW X X X X X
 *YFORCE X X X X X
 YGUSTF X X X X X
 ZETATR X X X X X

STANRO

VARIABLE	C	S	R	A	M	S	T	P
STANPT	X	X	X	X	X	X	X	X
*R	X	X	X					
J	X			X	X	X	X	
W	X	X	X	X	X	X	X	
RM	X	X	X	X	X	X	X	
BTP	X	X	X	X	X	X	X	
ITM	X	X	X	X	X	X	X	
VHS	X	X	X	X				
LINK	X	X	X	X	X	X	X	
*PMOM	X							X
QELF	X							
*RMDM	X	X	X	X	X	X	X	
VRUT	X	X	X	X	X	X	X	
VSUD	X	X	X	X	X	X	X	
YFIN	X	X	X	X	X	X	X	
ZFFI	X							X
ATRAL	X							X
BIRAL	X	X	X	X	X	X	X	
CNDI	X	X	X	X	X	X	X	
PMOMM	X	X	X	X	X	X	X	
PMOMT	X	X	X	X	X	X	X	
PMOMM	X	X	X	X	X	X	X	
PMOMT	X	X	X	X	X	X	X	
SWING	X	X	X	X	X	X	X	
PILGH?	X	X	X	X	X	X	X	
PHCELT	X	X	X	X	X	X	X	

C S R A M S T P
 R T O N A T R P
 L A T A N A I L
 T R A L U B M O
 T N

VARIABLE

ROSTAR X X X
 AM X X X
 CT X X X
 *FER X X X
 PI X X X
 XB X X X
 ALT X X X
 ADR X X X
 ERM X X X
 *ERX X X X
 EXH X X X
 NXR X X X
 RBH X X X
 SMC X X X
 UHS X X X
 CDHR X X X
 ERTR X X X
 ERXH X X X
 ERXT X X X
 LROT X X X
 RAIB X X X
 RTRP X X X
 TATR X X X
 CONEK X X X
 DCAFR X X X
 FVIND X X X
 NWARD X X X
 SWKR1 X X X
 SWKR2 X X X
 TIP18 X X X
 TIP38 X X X
 THIST X X X
 CLRADK X X X
 DELTA3 X X X
 LAMBDA X X X
 UPGUST X X X
 URGUST X X X
 UTGUST X X X
 WROTOR X X X
 *XLMAX X X X
 *XLMIN X X X
 XLMAX X X X
 XLMAXT X X X
 XLMIN X X X
 XLMINT X X X

ROSTAR

C S R A M S T P
 S T O N A T R P
 I A T A M A I L
 R A L U B M O
 T N

VARIABLE
 TOPLOT X X X X X X X X
 AH X X X X X X X X
 AL X X X X X X X X
 EXIT X X X X X X X X
 ICOM X X X X X X X X
 IPSM X X X X X X X X
 NPART X X X X X X X X
 NTIME X X X X X X X X
 NVARA X X X X X X X X
 NVARB X X X X X X X X
 NVARC X X X X X X X X
 NVAPS X X X X X X X X
 NPR:NT X X X X X X X X
 NSCALE X X X X X X X X

TOPLOT

STARAN

C S R A M S T P
B T O N A T R P
I A T A M A I L
T R A L U B M O
T N

VARIABLE
STARAN X X X X X X X X X X X X X X X X
CNPCD? X X X X X X X X X X X X X X X X
COLJET X X X X X X X X X X X X X X X X
DXWGL X X X X X X X X X X X X X X X X
DZHGFL X X X X X X X X X X X X X X X X
ETAOMX X X X X X X X X X X X X X X X X
PMGKI X X X X X X X X X X X X X X X X
RCWING X X X X X X X X X X X X X X X X
SWINGH X X X X X X X X X X X X X X X X
VENTER X X X X X X X X X X X X X X X X
VXNVER X X X X X X X X X X X X X X X X
YALJET X X X X X X X X X X X X X X X X
YARJET X X X X X X X X X X X X X X X X

APPENDIX F
FORTRAN LISTING

```

C      ASAJ01  C81 STABILITY AND CONTROL ANALYSIS
C
C      PROGRAM CONTROL SECTION
C
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICDM(49),IPSM,
1 NPART,NVARA,NVARB,NVARC,NSCALE
2 NVAR5,NPRINT,NTIME
3
DIMENSION AA(17),IDUM(266)
READ (5,2000) AA
WRITE (6,1002)
DD 2002 I=1,6
WRITE (6,2003) AA
2002 CONTINUE
CALL WROTI
CALL SETIME (600.)
CALL ERRSET (207,2,2,0,0,0)
CALL ERRSET (208,256,-1,0,0,0)
CALL ERRSET (209,2,2,0,0,0)
NVAR5=0
EXIT=2.
AM(2)=0.
13 CONTINUE
IF(AH(2).EQ.88..AND.EXIT.EQ.1.) CALL A3JUMP

THIS PROGRAM DEPENDS UPON THE VALUE OF NPART FIRST TO DETERMINE
ITS EXECUTION PROCESS.
WHEN TWO VALUES OF NPART USE THE SAME SUBROUTINES THE PATHS TAKEN
IN THE SUBROUTINES ARE DIFFERENT DEPENDING UPON THE VALUES OF
THE OTHER VARIABLES IN THE PROBLEM.

READ (5,1001,END=70) NPART,NPRINT,NSCALE,NVARA,AL(1),AH(1),
1 NPART,AL(2),AM(2),NVARC,AL(3),AH(3)

CHECK NPART TO SEE IF IT IS AN ALLOWABLE VALUE.
IF IT IS NOT THE PROGRAM IS TERMINATED AFTER ITS VALUE IS WRITTEN.
14 IF(NPART.GT.11.OR.NPART.LT.1) GO TO 50

IF NPART IS EQUAL TO 10 AFTER AN ERROR OR INITIALLY, THE PROGRAM
IS TERMINATED IMMEDIATELY.

IF(EXIT.NE.0..AND.NPART.EQ.10) GO TO 70
NTIME=-1
IF(NPRINT.LE.0) NPRINT=1
EXIT=0.
GO TO (1,2,3,60,60,60,7,3,60,10,11),NPART
1 CONTINUE
CALL START

CHECK EXIT FOR AN ERROR VALUE WHEN CONTROL HAS RETURNED FROM START
IF(EXIT.NE.0.) GO TO 13
CALL TRIM

```

```

C8100010
C8100020
C8100030
C8100040
C8100050
C8100060
C8100070
C8100080
C8100090
C8100100
C8100110
C8100120
C8100130
C8100140
C8100150
C8100160
C8100170
C8100180
C8100190
C8100200
C8100210
C8100220
C8100230
C8100240
C8100250
C8100260
C8100270
C8100280
C8100290
C8100300
C8100310
C8100320
C8100330
C8100340
C8100350
C8100360
C8100370
C8100380
C8100390
C8100400
C8100410
C8100420
C8100430
C8100440
C8100450
C8100460
C8100470
C8100480
C8100490
C8100500
C8100510
C8100520
C8100530
C8100540

```

```

C810055C
C8100560
C8100570
C8100580
C8100590
C8100600
C8100610
C8100620
C8100630
C8100640
C8100650
C8100660
C8100670
C8100680
C8100690
C8100700
C8100710
C8100720
C8100730
C8100740
C8100750
C8100760
C8100770
C8100780
C8100790
C8100800
C8100810
C8100820
C8100830
C8100840
C8100850
C8100860
C8100870
C8100880
C8100890
C8100900
C8100910
C8100920
C8100930
C8100940
C8100950
C8100960
C8100970
C8100980
C8100990
C8101000
C8101010
C8101020
C8101030
C8101040
C8101050
C8101060
C8101070
C8101080

START A NEW PROBLEM AFTER RETURNING FROM TRIM.
GO TO 13
A VALUE OF 2 FOR NPART CONSTITUTES A MANEUVER PROBLEM.
? CONTINUE
CALL START
IF AN ERROR APPEARS IN EITHER START OR TRIM FLUSH THE MANEUVER
DATA.
IF(EXIT.NF.0.) GO TO 19
CALL TRIM
IF(EXIT.NF.0.) GO TO 18
12 CONTINUE
CALL MANU
IF(EXIT.NE.0.-OR.NVARS.EQ.0) GO TO 13
CALL STAB
IF(EXIT.EQ.0.) GO TO 12
A4=99999999.
WRITE (3) IPSN,A4,IDUM
GO TO 13
19 CONTINUE
READ (5,1001,END=70) NPART,NPPINT,NSCALE,NVARA,AL(1),AM(1),
NVARB,AL(2),AM(2),NVARC,AL(3),AM(3)
IF NPART = 1,2,7, START A NEW PROBLEM
IF(NPART.EQ.3.-OR.NPART.EQ.8) GO TO 18
IF(NPART.EQ.10) GO TO 70
IF(NPART.EQ.11) GO TO 21
GO TO 14
FLUSH CURVE FIT DATA (NVARB AND ND DATA CARDS)
21 READ (5,900) (IDUM(II),II=1,NVARA)
IF(NVARB.EQ.0) GO TO 23
DO 22 IJ=1,NVARB
READ (5,900) NNUM,ND,(IDUM(II),II=1,NUM)
22 CONTINUE
23 CONTINUE
ND=AL(2)+.1
IF(ND.EQ.0) GO TO 18
DO 24 IJ=1,ND
READ (5,900) (IDUM(II),II=1,3)
24 CONTINUE
GO TO 18
3 CONTINUE
REWIND 3
CALL PPLOT
GO TO 13

```

```

C      A VALUE OF 7 FOR NPART RESULTS IN THE CALCULATION OF STABILITY
C      DERIVATIVES.
C
C      7 CONTINUE
C      CALL START
C      IF(EXIT.NE.0.) GO TO 13
C      CALL TRIM
C      IF(EXIT.NE.0.) GO TO 13
C      CALL STAB
C      GO TO 13
C
C      AN NPART VALUE OF 10 RESULTS IN A PARAMETER SWEEP USING TRIM OR
C      STABILITY DERIVATIVES ONLY.
C
C      10 CONTINUE
C      CALL START
C      IF(EXIT.NE.0.) GO TO 70
C      CALL TRIM
C      IF(EXIT.NE.0.) GO TO 70
C      IF(NVARA.NE.0) CALL STAB
C      IF(EXIT.NE.0.) GO TO 70
C      GO TO 13
C
C      A VALUE OF 11 FOR NPART RESULTS IN A LEAST SQUARES CURVE FIT OF
C      TIME HISTORY DATA.
C
C      11 CONTINUE
C      REWIND 3
C      CALL CURVET
C      GO TO 13
C      60 WRITE (6,1000)NPART
C      70 STOP
C      900 FORMAT (14I5)
C      1000 FORMAT (1H1,I8X,'BELL HELICOPTER 1RM 05/350 PROGRAM ASAJ01',
C      1       1H 17X39HHELICOPTER RIGID BODY DYNAMICS ANALYSIS////////
C      2       23H DATA ERROR .. NPART = ,I5)
C      1001 FORMAT (12,X,I3,X,I1,3(I5,X,2F5.0))
C      1002 FORMAT (1M1)
C      2000 FORMAT (17A4)
C      2003 FORMAT (1H0,17X,17A4////////)
C      FND

```

```

C0101090
C0101100
C0101110
C0101120
C0101130
C0101140
C0101150
C0101160
C0101170
C0101180
C0101190
C0101200
C0101210
C0101220
C0101230
C0101240
C0101250
C0101260
C0101270
C0101280
C0101290
C0101300
C0101310
C0101320
C0101330
C0101340
C0101350
C0101360
C0101370
C0101380
C0101390
C0101400
C0101410
C0101420
C0101430
C0101440
C0101450
C0101460
C0101470
C0101480
C0101490

```

SUBROUTINE AJACOB COMMON /FORCE/ 1 XF, XFRWG, XFLWG, XFELE, XFEUS, XFRJET, 2 XF3JET, XFMR, XFTR, XFGUN, XFFIN, XFM, 3 YF, YFFUS, YFRJET, YFLJET, YFMR, YFTR, 4 YFGUN, YFFIN, YFW, 5 ZF, ZFRWG, ZFLWG, ZFELE, ZFEUS, ZFRJET, 6 ZFLJET, ZFMR, ZFTR, ZFGUN, ZFM, 7 OL, LRWG, LLWG, LFELE, LFUS, LRJET, LLJET, 8 LMR, LTR, LGUN, LFIN, LOMR, LQTR, 9 OM, MRWG, MLWG, MELE, MFUS, MRJET, MLJET, A NMR, NTR, NGUN, NFIN, NOMR, NQTR, B ON, NRWG, NLRWG, NELE, NFUS, NRJET, NLJET, NMR, NTR, NGUN, NFIN, NOMR, NOTR COMMON /STRIAB/ 1 D(21), DT(21), E(79), F(13), X(10), 2 DL, DM, DN, DX, DY, DZ, IX, IY, IZ, PD(10,11), 3 DTR, EPD, ERR(10), KMI, RMD, 4 R12, SPD(6,6,3), XBM(21), XEL(14), 5 XER(7), XFC(21), XFN(7), XFS(35), 6 XGN(7), XIT(21), XMR(49), XTR(49), 7 XMG(21), YMR(21), YTR(21), YWG(21), 8 YEL(21), YFN(21), BLCG, DAMP, DEPD(10), 9 EPDS, EPDX(10), MASS, QSV1, TMR5, TTRS, A WLG, XCON(6,3), XJET(14), XMIN, AYEFP, B BETAES(2), CNPCD, DMADQ, DYBDR, GUESS, C NPASS, PDPH(11,1), STACC, TZERO, D XMAST, DMADAQ, DDDCOL, DTRRSQ, DYBDR, ENRPM, NXPASS, PSD30P, TRINDI, XLIMIT AY, VH, AGM, DT(2), DT2(2), IXZ, QMR, XXD, YYD, ZD, ALGF, APFP, AYFP, CGNL, COLL(6), CYCF(3), CYCL(3), DIST, KCIT(20), PEDA(3), OMAX, OMRS, TIME, TMAX, KCIT(20,6), ALGEZ, ALGE1, ALGE2, CGSTA, CPWIC, DIXIZ, DIYIX, DIZIY, DTZMT, DTZMI, DTZT1, FTRTS, HUBKM(2,2), HUBKI(2,2), KREAD, PIU30, TSTAB(14), ZMAX2, ZMAX3, ASECOL, CYPWIC, GEARAT, PSD550, PSISTP, OXBRAK, RUDIND, ZDELT1, ZDELT2 Q, AP, PED, QMG, TZM, TIM, TZM, TZT, T1T, T2T, ALEL, CZET, PSD0, SZET, TAXL, TAXR, XAMG, XLNK(16), ZANG, ALCYP, ALFIN, ALLMG, ALRWG, CDELE, CDFIN, CDLWG, CDRWG, CLELE, CLFIN, CLLMG, CLRWG, CMING, CYCRI, CYCR2, CZET4, CZET6, CZET9, RANGE, SZET5, SZET7, SZET8, WGCOL, XAELE, XAFIN, XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS, YAELE, YAFUS, YALMG, YARWG, YALJET, YARJET, ZAJET, ALECR1, ALGFPD, BOTTOM, CZET11, CZET12, CZET13, ETZETA, HALFPI, SZET10, XAPYLD, YGUSTM, ZAPYLD, ZFLWG1, ZFRWGI , TZMS, T1MS, T2MS, T1TS, T2TS, CLOCK, FLOCK, XLOCK, TCLOCK ZZ, VXS(2), VYS(2), VZS(2), BETA(12,2), T, PCC(2), COSE(7,7,2), BETAM(2), BETAZ(2),	AJAC0010 AJAC0020 AJAC0030 AJAC0040 AJAC0050 AJAC0060 AJAC0070 AJAC0080 AJAC0090 AJAC0100 AJAC0110 AJAC0120 AJAC0130 AJAC0140 AJAC0150 AJAC0160 AJAC0170 AJAC0180 AJAC0190 AJAC0200 AJAC0210 AJAC0220 AJAC0230 AJAC0240 AJAC0250 AJAC0260 AJAC0270 AJAC0280 AJAC0290 AJAC0300 AJAC0310 AJAC0320 AJAC0330 AJAC0340 AJAC0350 AJAC0360 AJAC0370 AJAC0380 AJAC0390 AJAC0400 AJAC0410 AJAC0420 AJAC0430 AJAC0440 AJAC0450 AJAC0460 AJAC0470 AJAC0480 AJAC0490 AJAC0500 AJAC0510 AJAC0520 AJAC0530 AJAC0540
--	--

```

*
1 1 AIB(2),APDD,ARDD,AYDD,AIR(2),
2 DPSI(12,2),DTRR,MPSI(2),ZZTR,
3 BETAD(12,2),BNPSI(2),
4 COMD2,GMAXY,RATE1,RATE2,STOP2,
5 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
6 GMAXV2,GMAXV3,GUSTYP,HMPSTR(2),
7 HUBKPS,HUBKRS,HUBTPS,HUBTRS,
8 KONFIG,LNGTH1,PILGH1,PSIREF(2),
9 STARTZ,XMOMLI(12,2),
0 RM,RYR,ORM,ORTR,TIMT,TIIT,
1 T2MT,T2TT,TZMT,TZTT,XMAl,XMAIT,
2 XMB1,XMB1T,AIBPH,AIBPT,AIBRM,AIBRT,
3 APTD,APTD,ARTD,ARTD,PSD,PSDT,
4 XSTAHM,XSTAHM,YSTAHM,YSTAHM,
5 HUBKP,HUBKTP,HUBXR,HUBKTR,
6 AZETA,AZETAT,VZETA,VZETAT
7 COMMON /MANARO/ I,V,IND,NMAG,APBMT,ARBMT,AYBMT,BETA0(2),TDELT,
8 BETAE(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
9 VGUSTM,VGUSTF,GFMD,GLAT,GVERT,
0 VXB,VZB,APD,VYB,ARD,AYD,
1 COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
2 APE,ARE,AIM,BIM,AIR,BITR,
3 XAR(2),YAR(2),ZAR(2),
4 VIMR,VITR,ZETA,ZETATR,HMR,HTR,
5 TMR,TTR,OMX,OTR,YMRF,YTRF
6 COMMON /STANRO/ J,M,ITM,VAS(2),LINK,OELE,VROT(2),
7 VSND,YFIN(2),ZFEI(2),AIBAL(2),
8 BIBAL(2),COND1,SWING,PILGH2,PMGEL1,
9 BM,BYR,PHOMM,PHOMT,PHOMM,RHOMT
0 COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
1 NPART,NVARA,NVARB,NVARC,NSCALE
2 -NVAR5,NPRINT,NTIME
3 DIMENSION VAR(11)
4 EQUIVALENCE (VAR(1),COLSTK)
5 CYCR1=CYSTKI*CYCF(3)+CYCF(2)
6 CYCR2=CYSTK2*CYCL(3)+CYCL(2)
7 PED= PEDAL*PEDA(3)+PEDA(2)
8 WCOL=CPMIC*COLSTK+AGW
9 ALECR1=ALGEZ+CYCR1*(ALGET+ALGE2*CYCR1)
0 ALCYP=CYPMIC*CYCR2
1 ALGFPD=ALGF+RUDIND*PED
2 CALL SWAS(COLSTK)
3 TZMT=TZM+DTZM1+DTZMT+ASECOL
4 TZTT=TZT+DTZT1+TRIND*(DTZMT+ASECOL)
5 TIMT=TIM+DTI(1)
6 T1TT=T1T+DTI(2)
7 T2MT=T2M+DT2(1)
8 T2TT=T2T+DT2(2)
9 CALL RATS (XXD,YYD,ZZD,AYE,APE,ARE,VXB,VYB,VZB,-1)
0 IF(LINK.EQ.2) CALL OFFTRM
1 CALL ANAL
2 IF(EXIT.NE.0.) RETURN
3

```

```
F(1) = XF - DX  
F(2) = YF - DY  
F(3) = ZF - DZ  
F(4) = ON - DN  
F(5) = OM - DM  
F(6) = OL - DL  
F(7)=XMB1  
F(8)=XMA1  
F(9)= XMB1T  
F(10)=XMA1T  
IF(CONDI.LE.1.5.AND.J.NE.1) RETURN  
(F(CONDI.LE.1.5.AND.LINK.EQ.3) RETURN  
IF(CONDI.EQ.0.) RETURN  
CALL WRVP (1,VAR,KM1,PD,TAXL,TAXR)  
CALL WRFM  
PFT JPN  
END
```

```
AJAC1090  
AJAC1100  
AJAC1110  
AJAC1120  
AJAC1130  
AJAC1140  
AJAC1150  
AJAC1160  
AJAC1170  
AJAC1180  
AJAC1190  
AJAC1200  
AJAC1210  
AJAC1220  
AJAC1230  
AJAC1240  
AJAC1250
```

SUBROUTINE ANAL
COMMON /FORCE/ XF, XFRWG, XFLWG, XFELE, XFFUS, XFRJET,
1 FFLJET, XFMR, XFTR, XFGUN, XFFIN, XFM,
2 YF, YFFUS, YFRJET, YFLJET, YFMR, YFTR,
3 YFGUN, YFFIN, YFM,
4 ZF, ZFRWG, ZFLWG, ZFELE, ZFFUS, ZFRJET,
5 ZFLJET, ZFMR, ZFTR, ZFGUN, ZFM,
6 OL, LRWG, LLWG, LELE, LFUS, LRJET, LLJET,
7 LMR, LTR, LLGUN, LFIN, LQMR, LOTR,
8 OM, MRWG, MLWG, MELE, MFUS, MRJET, MLJET,
9 MMR, MTR, MGUN, MFIN, MQMR, MQTR,
A ON, MRWG, NLWG, NELE, NFUS, NRJET, NLJET,
B NMR, NTR, NGUN, NFIN, NOMR, NQTR
COMMON /MANAL/
1 O, AP, PED, OMG, TZM, TIM, TZM,
2 TZT, TIT, TZT, ALEL, CZET, PSSD,
3 SZET, TAXL, TAXR, XAWG, XLNK(116), ZAWG,
4 ALCYP, ALFIN, ALLWG, ALRWG, CODEL, CDFIN,
5 COLWG, CORWG, CLELE, CLFIN, CLLWG, CLRWG, CMING,
6 CYCR1, CYCR2, CZET4, CZET6, CZET9, RANGE,
7 SZET5, SZET7, SZET8, WGCOL, XAELE, XAFIN,
8 XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,
9 YAELE, YAFUS, YALWG, YARWG, YALJET, YARJET,
A ZAJET, ALECR1, ALGFPD, BOTTOM, CZET11,
B CZET12, CZET13, EZETA, HALFPI, SZET10,
C XAPYLD, YGUSTM, ZAPYLD, ZFLWG1, ZFRWG1
D * TZMS, TIMS, TZMS, TZTS, TITS, TZTS,
E CLOCK, FLOCK, XLOCK, TCLOCK
F I, V, IND, MAG, APART, ARBMT, AYBMT, BETA0(2), TDELT,
G BETAE(2), HGUSTE, HGUSTF, HGUSTM, VGUSTE,
H VGUSTM, YGUSTF, GFMD, GLAT, GVERT,
I VXB, VZB, APD, VYB, ARD, AYD,
J COLSTK, CYSTK1, CYSTK2, PEDAL, AYE,
K APE, ARE, A1M, B1M, A1TR, B1TR,
L XAR(2), YAR(2), ZAR(2),
M VIMR, VITR, ZETA, ZETATR, HMR, HTR,
N TMR, TTR, OMX, OTR, YMR, YTRF
COMMON /STANDR/
1 J, M, ITM, VHS(2), LIMK, OELE, VADT(2),
2 VSND, YFIN(2), ZFEL(2), AIBAL(2),
3 BIBAL(2), CDND1, SWING, PILGH2, PMGEL1,
4 RM, BTR, PHDMM, PMOMT, R, MOMM, PMOMT
COMMON /TOPLOT/
1 AH(3), AL(3), EXIT, ICOM(49), IPSN,
2 NPART, NVARA, NVARR, NVARC, NSCALE
3 NVARS, NPRI, NTIME
COMMON /STARAN/
1 RH(2), C3, C4, RM, CLP, CLR, DCD, DOL, DQM, VIM,
2 SAI8(2), CL8D, CNERD, ETAO, NJET,
3 OFIN,
4 VIER, CLBCL, YFS(114),
5 CNBCL, CNPCL, CNRCD, CNRCL, COLKS, O3ELE,
6 FNSWC, LWING, PMREL, PMRWG,
7 PTRFN, RPIST, VMAXF, YAERDI(31, 5),
8 APBJET, ARBJET, AYBJET,
9 CNPCDI, CNPCD2, COLJET, DXHREL, DZMGEL,
A ETAOMX, PMGWK1, RCWING, SWINGH,
VENTER, VXXVFR

ANAL0010
ANAL0020
ANAL0030
ANAL0040
ANAL0050
ANAL0060
ANAL0070
ANAL0080
ANAL0090
ANAL0100
ANAL0110
ANAL0120
ANAL0130
ANAL0140
ANAL0150
ANAL0160
ANAL0170
ANAL0180
ANAL0190
ANAL0200
ANAL0210
ANAL0220
ANAL0230
ANAL0240
ANAL0250
ANAL0260
ANAL0270
ANAL0280
ANAL0290
ANAL0300
ANAL0310
ANAL0320
ANAL0330
ANAL0340
ANAL0350
ANAL0360
ANAL0370
ANAL0380
ANAL0390
ANAL0400
ANAL0410
ANAL0420
ANAL0430
ANAL0440
ANAL0450
ANAL0460
ANAL0470
ANAL0480
ANAL0490
ANAL0500
ANAL0510
ANAL0520
ANAL0530
ANAL0540

```

COMMON /FOR/ Y(4,150)
REAL LELE, LFIN, LGUN, LHURK, LHURKT, LLJET, LLWG, LMR,
1 LOMR, LOTR, LRJET, LRWG, LTR, MELE, MFIN, MFUS,
2 MGUN, MHURKT, MLJET, MMR, MPYL, MQMR,
3 MOTR, MRJET, MRWG, MTR, NELE, NFIN, NFUS, NGUN, MLWG,
4 NHURK, NHURKT, NLJET, NLWG, NMR, NOMR, NOTR, NRJET,
5 NRWG, NTR, LFUS, NFEUS, MFUS
V3=0.
MP=MCOS(APE)
XFM=-MSIN(APE)
YFM=MP*SIN(ARE)
ZFM=MP*COS(ARE)
GFMD=(XFM-XF)*RW
SLAT=(YFM-YF)*RW
GVERT=(ZFM-ZF)*RW
IF(BM.EQ.0.) GO TO 300
CALL ROTAN (1)
IF(EXIT.NE.0.) RETURN
CALL RATS (-HMR,YMRF,-TMR,0.,-ZETA,0.,XFMR,YFMR,ZFMR,1)
CALL DOGS (XAR(1),YAR(1),ZAR(1),XFMR,YFMR,ZFMR,LMR,MMR,NMR)
OREACT=OMX+BAIB(1)*PSDD
CALL MICE (0.,0.,-ZETA,LOMR,NOMR,-1)
PHMM=PMOMM*BH(1)
PMOMH=PMOMM*BH(1)
CALL RATS (PMOMH,PMOMH,0.,0.,-ZETA,0.,LHURK,MMR,NHURK,1)
LOMR=LOMR+LHURK
NOMR=NOMR+NHURK
IF(VROT(1).NE.0.) V3=(VHS(1)/VROT(1))*3
300 IF(BTR.EQ.0.) GO TO 299
CALL ROTAN (2)
IF(EXIT.NE.0.) RETURN
CALL RATS (-HTR,YTRF,-TTR,AYBMT,APBMT,ARBMT,XFTR,YFTR,ZFTR,1)
CALL DOGS (XAR(2),YAR(2),ZAR(2),XFTR,YFTR,ZFTR,LTR,MTR,NTR)
OREATT=OTR+BAIB(2)*PSDD
CALL RATS (0.,0.,-OREATT,AYBMT,APBMT,ARBMT,LOTR,MOTR,NOTR,1)
PHMM=PMOMT*BH(2)
PMOMH=PMOMT*BH(2)
CALL RATS (PMOMH,PMOMH,0.,0.,AYRMT,APBMT,ARBMT,LHURKT,MHURKT,
1)
LOTR=LOTR+LHURKT
MOTR=MOTR+MHURKT
NOTR=NOTR+MHURKT
299 XMAC=V*VSND
AP=0.
APOOT=0.
VXBSO=VXB**2+VZB**2
IF(VXBSO.EQ.0.) GO TO 303
AP=ATAN2(VZB,VXB)
APOOT=(VXB*(1.78)-VZB*(1.76))/VXBSO
C
C
C
303 CONTINUE
ANGE=0.

```

```

ANAL0550
ANAL0560
ANAL0570
ANAL0580
ANAL0590
ANAL0600
ANAL0610
ANAL0620
ANAL0630
ANAL0640
ANAL0650
ANAL0660
ANAL0670
ANAL0680
ANAL0690
ANAL0700
ANAL0710
ANAL0720
ANAL0730
ANAL0740
ANAL0750
ANAL0760
ANAL0770
ANAL0780
ANAL0790
ANAL0800
ANAL0810
ANAL0820
ANAL0830
ANAL0840
ANAL0850
ANAL0860
ANAL0870
ANAL0880
ANAL0890
ANAL0900
ANAL0910
ANAL0920
ANAL0930
ANAL0940
ANAL0950
ANAL0960
ANAL0970
ANAL0980
ANAL0990
ANAL1000
ANAL1010
ANAL1020
ANAL1030
ANAL1040
ANAL1050
ANAL1060
ANAL1070
ANAL1080

```

```

IF(OMG.LT.0) GO TO 304
VIM=VIMR*PHRWG
XXW=VXB-HGUSTW+VIM*SZET
ST1=VZB-VGUSTW-VIM*SZET
ANGRW=ATAN2(ST1,XXW)
ALGEO=ANGRW*WCOL
ALRWG=ALGEO-ALCYP
CALL CLCD (ALRWG,CLRWG,CDRWG,XMAC,EXIT,3)
IF(EXIT.NE.0.) GO TO 1
CD=C3
CL=C4
DCDR=DCD
VELSO=XXW**2+ST1**2
ORW=OMG*VELSO
CALL MICE (-CDRWG,-CLRWG,ANGRW,C1,C2,1)
XFRWG=C1*ORW
ZFRWG=C2*ORW
CALL DOGS (XAWG,YARWG,ZAWG,XFRWG,0. ,ZFRWG,LRWG,MRWG,NRWG)
ALLWG=ALGEO*ALCYP
CALL CLCD (ALLWG,CLLWG,CDLWG,XMAC,EXIT,3)
IF(EXIT.NE.0.) GO TO 1
CD=C5*(C3+CD)
ALWG=-5*(C4+CL)
DCD=.5*(DCDR+DCD)
CALL MICE (-CDLWG,-CLLWG,ANGRW,C1,C2,1)
XFLWG=C1*ORW
ZFLWG=C2*ORW
CALL DOGS (XAWG,YALWG,ZAWG,XFLWG,0. ,ZFLWG,LLWG,MLWG,NLWG)
YS=SWINGH/SORT(VELSO)
FF=ORW*SWING
YAW=0.
IF(VYB-YGUSTW.NE.0.-OR.XXW.NE.0.) YAW=ATAN2(VYB-YGUSTW,XXW)
DOL AND DON ARE CONTRIBUTION OF EACH WING. NOT TOTAL
DOL=FF*(YAW*(CLBD+CLBCL*CLWG)+TS*(AYD*CLR*CLWG+ARD*CLP))
DON=FF*(YAW*(CNBD+CNBCL*CLWG**2)+TS*(AYD*(CNRCL*CLWG**2+CNRCDD*DCD)
1 +ARD*(CNPCL*CLWG+CNPCD1+CNPCD2*ALWG)))
LRWG=LRWG+DOL
LLWG=LLWG+DOL
NRWG=NRWG+DON
NLWG=NLWG+DON
ANGE=-PWGEL1*CLWG
ANG1=0.
IF(VXB.NE.0.) ANG1=APDOT*XAELE*PWGEL1/VXB
IF(ALWG.EQ.0.) GO TO 305
ANGE=ANGE-ANG1*CLWG/ALWG
GO TO 306
305 CONTINUE
ANGE=ANGE-ANG1*YAERO(17,3)
306 CONTINUE
AWAKE=PWGKI*CLWG
DSTALL=RPISY*AMAX1(0.,(ALWG-YAERO(19,3)))
ANAL1090
ANAL1100
ANAL1110
ANAL1120
ANAL1130
ANAL1140
ANAL1150
ANAL1160
ANAL1170
ANAL1180
ANAL1190
ANAL1200
ANAL1210
ANAL1220
ANAL1230
ANAL1240
ANAL1250
ANAL1260
ANAL1270
ANAL1280
ANAL1290
ANAL1300
ANAL1310
ANAL1320
ANAL1330
ANAL1340
ANAL1350
ANAL1360
ANAL1370
ANAL1380
ANAL1390
ANAL1400
ANAL1410
ANAL1420
ANAL1430
ANAL1440
ANAL1450
ANAL1460
ANAL1470
ANAL1480
ANAL1490
ANAL1500
ANAL1510
ANAL1520
ANAL1530
ANAL1540
ANAL1550
ANAL1560
ANAL1570
ANAL1580
ANAL1590
ANAL1600
ANAL1610
ANAL1620

```

```

ANAL1630
ANAL1640
ANAL1650
ANAL1660
ANAL1670
ANAL1680
ANAL1690
ANAL1700
ANAL1710
ANAL1720
ANAL1730
ANAL1740
ANAL1750
ANAL1760
ANAL1770
ANAL1780
ANAL1790
ANAL1800
ANAL1810
ANAL1820
ANAL1830
ANAL1840
ANAL1850
ANAL1860
ANAL1870
ANAL1880
ANAL1890
ANAL1900
ANAL1910
ANAL1920
ANAL1930
ANAL1940
ANAL1950
ANAL1960
ANAL1970
ANAL1980
ANAL1990
ANAL2000
ANAL2010
ANAL2020
ANAL2030
ANAL2040
ANAL2050
ANAL2060
ANAL2070
ANAL2080
ANAL2090
ANAL2100
ANAL2110
ANAL2120
ANAL2130
ANAL2140
ANAL2150
ANAL2160

XA=DXWGEL-DSTALL
ANGEL=ATAN2(DZWGEL,XA)
DMGEL=SQRT(XA**2+DZWGEL**2)*RCWING
ANGLE=AWAKE-AP-ANGEL
DIS=DMGEL*ABS(SIN(ANGLE))
XT=DMGEL*ABS(COS(ANGLE))
HWAKE=.68*SQRT(CD*(XT+.15))
ETAQ=0.
IF(DIS .LT. HWAKE .AND. ABS(ANGLE).LT.HALFPI)
1  ETAQ=ETAQX*SQRT(CD)/(XT+.3)*(COS(DIS *HALFPI/HWAKE))**2
  (F(NMAG.EQ.0) GO TO 304
  LWING=LWING+1
  LWING1=LWING
  DLIFT=ZFRWG-ZFRWG1
  CALL WAG (CWING,LWING,3,V,TDELT,RED,DLIFT)
  ZFRWG=ZFRWG-RED
  DLIFT=ZFLWG-ZFLWG1
  CALL WAG (CWING,LWING1,4,V,TDELT,RED,DLIFT)
  ZFLWG=ZFLWG-RED

ELEVATOR EQUATIONS
304 IF(COLE.LT.0) GO TO 302
  VIER=0.
  IF(V.GT.VENTER) VIER=VIMR*(V-VENTER)*VXMMVER
  IF(V.GT.VMAXE) VIFR=PMREL*VIMR
  ST1=VZBARD*YAELE-APD*XAELE-VIER*CIJET-VGJSTE
  XE=VXB*APD*ZAELE-AYD*YAELE-HGUSTE
  VELSO=XE**2+ST1**2
  IF(VFLO.NE.0.) ANGE=ATAN2(ST1,XXE)+ANGE
  ALEL=ALECR1+D3ELE*COLSTK+EIZETA+ANGE
  CALL CLCD (ALEL,CLFLE,CDELE,XMAC,EXIT,4)
  IF(EXIT.NE.0.) GO TO 1
  DE=DELE*VELSO*(1.-ETAQ)
  IF(ALFL.NE.0.) CLELF=CLELE*ALEL/(ALEL+CLELE*QE*YAERD(11,4))
  CALL MICE (-CDELE,-CLELE,ANGE,C1,C2,1)
  XFELE=C1*QE
  ZFELE=C2*QE
  CALL DDGS (XAELE,YAELE,ZAELE,XFELE,0. ,ZFELE,LELE,MELE,NELE)
  IF(NMAG.EQ.0) GO TO 302
  ZFEL(1)=ZFELE
  ZFEL(2)=.5*(ZFEL(1)+ZFEL(2))
  IF(1.NE.3) ZFEL(1)=ZFEL(2)

FIN EQUATIONS
302 IF(OFIN.LT.0) GO TO 301
  ST1=ARD*ZAFIN-AYD*XAFIN-VYB*FN*SWC-VITR*PTRFN+YGUSTF
  XFEN=YXB*APD*ZAFIN-AYD*YAFIN-HGUSTF
  QF=OFIN*(XFEN*XFEN+ST1*ST1)
  ANGF=0.
  IF(QF.NE.0.) ANGF=ATAN2(ST1,XFEN)
  ALFIN=ANGF+ALGFPD
  CALL CLCD (ALFIN,CLFIN,CDFIN,XMAC,EXIT,5)

```

```

IF(EXIT.NE.0.) GO TO 1
IF(ALFIN.NE.0.) CLFIN=CLFIN*ALFIN/(ALFIN+CLFIN*OF*VAERO(11,5))
CALL MICE (-CDFIN,CLFIN,ANGF,C1,C2,-1)
XFFIN=C1*OF
YFFIN=C2*OF
CALL DOGS (XAFIN,YAFIN,ZAFIN,XFFIN,YFFIN,0., .LFIN,MFIN,NFIN)
IF(NMAG.EQ.0) GO TO 301
YFIN(2)=YFFIN
YFFIN=.5*(YFIN(1)+YFIN(2))
IF(1.NE.3) YFIN(1)=YFIN(2)
FUSFLAGE EQUATIONS
301 XXF=VXB-HGUSTM
ST1=VZB-VGUSTM
ANG1=0.
QVXZB=Q*(XXF*XXF+ST1*ST1)
IF(QVXZB.NE.0.) ANG1=ATAN2(ST1,XXF)
FSLIFT=OVXZB*(YFS(1)+ANG1*YFS(2))
DF=OVXZB*(YFS(7)+ANG1*(YFS(8)+ANG1*YFS(9)))
ST2=YGUSTM-VYB
QVXYB=Q*(XXF*XXF+ST2*ST2)
ANG2=0.
IF(QVXYB.NE.0.) ANG2=ATAN2(ST2,XXF)
YFFS=QVXYB*(YFS(10)+ANG2*(YFS(11)+ANG2*YFS(12)))
DFAY=QVXYB*YFS(13)+ANG2**2
CALL MICE (-DF,-FSLIFT,ANG1,XFFUS,ZFFUS,1)
CALL MICE (-OFAY,YFFS,ANG2,XFFUS,YFFUS,-1)
DPYLON=OVXZB*YFS(14)*V3
CALL MICE (-OPYLON,0.,ANG1,XFPYL,ZFPYL,1)
XFFUS=XFFUS+XFPYL+XFFUSY
ZFFUS=ZFFUS+ZFPYL
CALL DOGS(XAPYLD,0.,ZAPYLD,XFPYL,0.,ZFPYL,TV,MPYL,TV1)
CALL DOGS (XAFUS,YAFUS,ZAFUS,XFFUS,YFFUS,ZFFUS,LFUS,MFFUS,MFFUS)
MFUS=OVXZB*(YFS(3)+ANG1*YFS(4))+MPYL+MFFUS
YFUS=OVXYB*(YFS(5)+ANG2*YFS(6))+MFFUS
JET THRUST EQUATIONS
IF(COLJET.EQ.0.) GO TO 79
DCOL=COLJET*(COLSTK-COLKS)
COLKS=COLSTK
TAXR=TAXR+OCOL
IF(INJET.EQ.1) GO TO 79
TAXL=TAXL+OCOL
79 CONTINUE
CALL RATS (TAXR,0.,0.,AYBJET,APBJET,XRBJET,YRBJET,ZRJET,1)
CALL DOGS (XAJET,YAJET,ZAJET,XRJET,YRJET,ZRJET,LRJET,MRJET,
1 NRJET)
CALL RATS(TAXL,0.,0.,-AYBJET,APBJET,XFLJET,YFLJET,ZFLJET,1)
CALL DOGS (XAJET,YAJET,ZAJET,XFLJET,YFLJET,ZFLJET,LLJET,MLJET,
1 NLJET)
FORCE EQUATIONS

```

```

ANAL2170
ANAL2180
ANAL2190
ANAL2200
ANAL2210
ANAL2220
ANAL2230
ANAL2240
ANAL2250
ANAL2260
ANAL2270
ANAL2280
ANAL2290
ANAL2300
ANAL2310
ANAL2320
ANAL2330
ANAL2340
ANAL2350
ANAL2360
ANAL2370
ANAL2380
ANAL2390
ANAL2400
ANAL2410
ANAL2420
ANAL2430
ANAL2440
ANAL2450
ANAL2460
ANAL2470
ANAL2480
ANAL2490
ANAL2500
ANAL2510
ANAL2520
ANAL2530
ANAL2540
ANAL2550
ANAL2560
ANAL2570
ANAL2580
ANAL2590
ANAL2600
ANAL2610
ANAL2620
ANAL2630
ANAL2640
ANAL2650
ANAL2660
ANAL2670
ANAL2680
ANAL2690
ANAL2700

```

```

C
XF=XFRWG+XFLWG+XFELE+XFFUS+XFRJET+XFLJET+XFMR+XFTR+XFGUN+XFFIN+XFWANAL2720
YF=YFRJET+YFLJET+YFMR+YFTR+YFGUN+YFFIN+YFWANAL2730
ZF=ZFRWG+ZFLWG+ZFELE+ZFFUS+ZFRJET+ZFLJET+ZFMR+ZFTR+ZFGUN
ANAL2710
ANAL2750
ANAL2760
ANAL2770
ANAL2780
ANAL2790
ANAL2800
ANAL2810
ANAL2820
ANAL2830
ANAL2840

MOMENT EQUATIONS
QL=LRWG+LLWG+LELE+LFUS+LRJET+LLJET+LMR+LTR+LGUN+LFIN+LQMR+LQTR
OM=NRWG+MLWG+MELE+MFUS+MRJET+MLJET+MMR+MTR+MGUN+MFIN+MQMR+MQTR
ON=NRWG+NLWG+NELE+NFUS+NRJET+NLJET+NNR+NNTR+NGUN+NFIN+NQMR+NQTR

1 RETURN
END
C

```

```

SUBROUTINE CATS (A1,A2,A3,B1,B2,B3,C1,C2,C3,N1,N2)
A IS THE MATRIX OF THE A SET OF EULER ANGLES
B IS THE MATRIX OF THE B SET OF EULER ANGLES
C IS THE MATRIX OF THE C SET OF EULER ANGLES
N1= 1, N2= 1 IS FOR B*A
N1=-1, N2= 1 IS FOR B*(TRANSPOSE)
N1= 1, N2=-1 IS FOR B*(TRANSPOSE)*A
N1=-1, N2=-1 IS FOR B*(TRANSPOSE)*A*(TRANSPOSE)
DIMENSION A(3,3),B(3,3),C(3,3)
      COMPUTE A AND B MATRICES
CALL MATRIX (A1,A2,A3,A,N1)
CALL MATRIX (B1,B2,B3,B,N2)
      COMPUTE C MATRIX
DO 101 I=1,3
DO 101 J=1,3
C(I,J)=0.
DO 101 L=1,3
C(I,J)=C(I,J)+B(L,J)*A(I,L)
101 CONTINUE
      CHECK TO SEE IF PITCH ANGLE IS 90 DEGREES
IF(C(1,1)-EQ.0.-AND.C(1,2)-EQ.0.) GO TO 104
C1=ATAN2(C(1,2),C(1,1))
C3=ATAN2(C(2,3),C(3,3))
CC3=CC3(C3)
IF(ABS(CC3)-LE.0.001) GO TO 102
C2=ATAN2((-C(1,3)*CC3),C(3,3))
GO TO 103
102 CONTINUE
C2=ATAN2(-C(1,3),C(2,3)*SIN(C3)))
103 CONTINUE
      CHECK TO SEE IF C1,C2,C3 ARE IN WRONG QUADRANT
IF(COS(C2).GE.0.) RETURN
      RECOMPUTE C1,C2,C3 IN CORRECT QUADRANT
C1=ATAN2(-C(1,2),-C(1,1))
C3=ATAN2(-C(2,3),-C(3,3))
IF(ABS(CC3)-LE.0.001) RETURN
C2=ATAN2((-C(1,3)*COS(C3)),C(3,3))
RETURN
      RESOLVE INDETERMINACY CAUSED BY PITCH ANGLE BY USING OLD
      YAW ANGLE
104 CONTINUE
C2 = -SIGN(1.570796,C(1,3))
C3=(ATAN2(-C(2,1),(-C(1,3)*C(3,1)))-C1)*C(1,3)
RETURN
END

```

CATS0010
CATS0020
CATS0030
CATS0040
CATS0050
CATS0060
CATS0070
CATS0080
CATS0090
CATS0100
CATS0110
CATS0120
CATS0130
CATS0140
CATS0150
CATS0160
CATS0170
CATS0180
CATS0190
CATS0200
CATS0210
CATS0220
CATS0230
CATS0240
CATS0250
CATS0260
CATS0270
CATS0280
CATS0290
CATS0300
CATS0310
CATS0320
CATS0330
CATS0340
CATS0350
CATS0360
CATS0370
CATS0380
CATS0390
CATS0400
CATS0410
CATS0420
CATS0430
CATS0440
CATS0450
CATS0460
CATS0470
CATS0480

```

SUBROUTINE CLCJ (ALP,CL,CO,XMAC,EXIT,N)
COMMON /STARAN/ RH(2),C3,C4,RM,CLP,CLR,DCD,DOL,DON,VIM,
1 BAIB(2),CLB0,CNR0,ETAQ ,NJET,
2 OFIN,
3 VIER,CLBCL,YFS(14),
4 CNBCL,CNPCL,CNRCJ,CNRCL,COLKS,03ELE,
5 FNSWC,LWING,PMREL,PMRWG,
6 PTRFN,RPIST,VMAXE,YAERO(31,5),
7 APBJET,ARBJET,AYBJET,
8 CNPCD1,CNPCD2,COLJET,DXWGEL,OZMGEL,
9 ETAOMX,PMGMK1,RCWING,SMINGH,
A VENTER,VXWVER
DIMENSION HEAD(3,3)
DATA DTRR,PI,TWPI/ 57.29578,3.141593,6.283185/
DATA HALFPI/1.570796/
DATA HEAD/
LOGICAL STALL
STALL=.FALSE.
ALF=ALP
AL=YAERO(17,N)
6010 SG=1.
IF(ALF.LT.0.) SG=-1.
AMG=SG*ALF
IF(20.LE.AMG) GO TO 6015
IF(PI.GE.AMG) GO TO 6020
AMG=AMG-TWOPI
ALF=AMG*SG
GO TO 6010
6015 WRITE (6,6101) N
EXIT=1.
RETURN
IF(AL.NE.0.) GO TO 50
ALD=AMG*DTRR
CALL TABINT (CL,CO,XMAC,ALD,SG)
CL=CL*SG
RETURN
50 SMAC=1./SORT(ABS(1.-XMAC**2))
AL(=0.
CRM=YAERO(1,N)
SSMM=YAERO(2,N)
CDZ=YAERO(12,N)
CD1 = YAERO(13,N)
CD2 = YAERO(14,N)
CDMX=YAERO(16,N)
SMAL4 = AMINI(XMAC,SSMM)
AR = YAERO(18,N)
ALD=ALP*DTRR
ZK3=1+.25*XMAC**4
IF((HALFPI).GE.AMG) GO TO 6032
AMG=PI-AMG
SG=-SG
CLZ=YAERO(7,N)
CLMX=CLZ+SMALM*(YAERO(8,N)+SMALM*(YAERO(9,N)+SMALM*YAERO(10,N)))
ALB=YAERO(23,N)

```

```

CLCD0010
CLCD0020
CLCD0030
CLCD0040
CLCD0050
CLCD0060
CLCD0070
CLCD0080
CLCD0090
CLCD0100
CLCD0110
CLCD0120
CLCD0130
CLCD0140
CLCD0150
CLCD0160
CLCD0170
CLCD0180
CLCD0190
CLCD0200
CLCD0210
CLCD0220
CLCD0230
CLCD0240
CLCD0250
CLCD0260
CLCD0270
CLCD0280
CLCD0290
CLCD0300
CLCD0310
CLCD0320
CLCD0330
CLCD0340
CLCD0350
CLCD0360
CLCD0370
CLCD0380
CLCD0390
CLCD0400
CLCD0410
CLCD0420
CLCD0430
CLCD0440
CLCD0450
CLCD0460
CLCD0470
CLCD0480
CLCD0490
CLCD0500
CLCD0510
CLCD0520
CLCD0530
CLCD0540

```

```

SALB=YAERD(21,N)
SZALB=YAERD(25,N)
CALB=YAERD(27,N)
GO TO 6031
6032 CLZ=YAERD(3,N)
CLMX=CLZ+SMALM*(YAERD(4,N)+SMALM*(YAERD(5,N)+SMALM*YAERD(6,N)))
ALB=YAERD(22,N)
SALB=YAERD(20,N)
SZALB=YAERD(24,N)
CALB=YAERD(26,N)
6033 IF(XMAC.LY.CRM) GO TO 6041
IF(SSMM.LE.XMAC) GO TO 6042
AL=YAERD(29,N)+XMAC*(YAERD(30,N)+XMAC*YAERD(31,N))
GO TO 5000
6041 AL=AL*SMAC
GO TO 5000
6042 AL=4.*SMAC
5000 ANG=AMG
ALPH14=CLMX/AL
SANG=SIN(ANG)
CANG=COS(ANG)
IF(N.LT.3) GO TO 11
F1=CLZ
F2=.81
GO TO 10
11 F1=.938
F2=.581
10 CONTINUE
IF(ALB.GT.AMG) GO TO 6044
STALL=.TRUE.
IF(XMAC.GT.1.0)ZK3=-.84+.082/(XMAC-.8)
IF(ABS(AMG).GE.1.565) GO TO 35
Q0=F1*ZK3
Q1=Q0+Q0
A=Q0*SIN(ANG+AMG)
Z2=.81+Q1*SANG-F2*ZK3
S02A=(AR-SANG*Q2+Q1*CANG**2)/(A+A)
COA=CANG*Q2/A
DISC=SQRT(RO2A**2+COA)
IF(RO2A.GT.0) GO TO 31
ALI=DISC-RO2A
GO TO 36
31 CONTINUE
ALI=COA/(RO2A+DISC)
GO TO 36
35 ALI = 0.
36 CL = AR * ALI
GO TO 20
6044 ALI = AL/(AL+AR)*AMG
ANG=AMG-ALI
CL=AL*ANG
IF(CLMX.GE.CL) GO TO 20
J0=F1*ZK3
Q1=Q0+Q0

```

```

CLCD0550
CLCD0560
CLCD0570
CLCD0580
CLCD0590
CLCD0600
CLCD0610
CLCD0620
CLCD0630
CLCD0640
CLCD0650
CLCD0660
CLCD0670
CLCD0680
CLCD0690
CLCD0700
CLCD0710
CLCD0720
CLCD0730
CLCD0740
CLCD0750
CLCD0760
CLCD0770
CLCD0780
CLCD0790
CLCD0800
CLCD0810
CLCD0820
CLCD0830
CLCD0840
CLCD0850
CLCD0860
CLCD0870
CLCD0880
CLCD0890
CLCD0900
CLCD0910
CLCD0920
CLCD0930
CLCD0940
CLCD0950
CLCD0960
CLCD0970
CLCD0980
CLCD0990
CLCD1000
CLCD1010
CLCD1020
CLCD1030
CLCD1040
CLCD1050
CLCD1060
CLCD1070
CLCD1080

```

CLCD1090
 CLCD1100
 CLCD1110
 CLCD1120
 CLCD1130
 CLCD1140
 CLCD1150
 CLCD1160
 CLCD1170
 CLCD1180
 CLCD1190
 CLCD1200
 CLCD1210
 CLCD1220
 CLCD1230
 CLCD1240
 CLCD1250
 CLCD1260
 CLCD1270
 CLCD1280
 CLCD1290
 CLCD1300
 CLCD1310
 CLCD1320
 CLCD1330
 CLCD1340
 CLCD1350
 CLCD1360
 CLCD1370
 CLCD1380
 CLCD1390
 CLCD1400
 CLCD1410
 CLCD1420
 CLCD1430
 CLCD1440
 CLCD1450
 CLCD1460
 CLCD1470
 CLCD1480
 CLCD1490
 CLCD1500
 CLCD1510
 CLCD1520
 CLCD1530
 CLCD1540
 CLCD1550
 CLCD1560
 CLCD1570
 CLCD1580
 CLCD1590
 CLCD1600
 CLCD1610
 CLCD1620

```

A=00*S2ALB
Q2=-.81+01*SALB-F2*ZK3
BO2A=(AR-SALB*02+01*CALB**2)/(A+A)
COA=CALB*02/A
DISC=SQRT(BO2A**2+COA)
IF(BO2A.GT.0.) GO TO 32
ALIB=DISC-BO2A
GO TO 33
32 CONTINUE
ALIB=COA/(BO2A+DISC)
33 CONTINUE
CLB = AR * ALIB
ALIMX = CLMX/(AR + AL)
ADVER = (AMG-ALPH14)/(ALPH14-ALB)
ALI = ALIMX*(ALIMX-ALIB)*ADVER
CL = CLMX+(CLMX-CLB)*ADVER
ANG=AMG-ALI
STALL=.TRUE.
20 CL=CL*SG
IF(1.0-LE.XMAC) GO TO 6050
CDZ = CDZ*SHAC
XMACM = AMAX1(XMAC,.35) - CRM
IF(ALPH14.LT.AMG) GO TO 60
DD = XMACM + 1.9*AMG
C5=1.9
IF(DD.GE.0.) GO TO 30
DD=0.
30 CONTINUE
C6=AMG*CD2
C7=C01 + C6
CD=CDZ+AMG*C7+DD
IF(CD.GT.CDMX) GO TO 70
DCD=C5+C6+C7
GO TO 253
70 CONTINUE
CDSX=CDMX
AS1 = CD1 + 1.9
AS2 = CDZ - CDSX + XMACM
IF(CD2
  ALFSX = (SQRT(.25*AS1*AS1 - AS2*CD2
GO TO 6040
80 CONTINUE
ALFSX = -AS2/AS1
GO TO 6040
60 CONTINUE
CDSX=CDZ+ALPH14*(CD1
  AMAX1(0.,XMACM + 1.9*ALPH14)
  IF(CDSX.GT.CDMX) GO TO 70
ALFSX=ALPH14
6040 CONTINUE
IF(IN.LT.3) GO TO 40
C5=AMG-HALFPI
C6=C5*(CDSX-2.0)/(ALFSX-HALFPI)**2
  
```

```

CD=C5*C6+2.0
DCD=C5+C6
GO TO 254
40 CONTINUE
ZK4=2.1*ZK3
CALF=1./COS(ALFSX)
SALF=CALF*SIN(ALFSX)**2
CALF=CDS*CALF
CD=ZK4*SAMG**2+(CALF-SALF*ZK4)*CANG
RETURN
6050 CD=COMX
DCD=0.
IF(SSMM.GT.XMAC) GO TO 253
CD=4.*(AMG**2+YAERO(15,N))*SMAC*CDZ
DCD=8.*AMG*SMAC
6060 IF(CD.LE.COMX) GO TO 253
CD=COMX
DCD=0.
253 IF(N.LT.3) RETURN
254 CONTINUE
IF(STALL) WRITE (6,22) (HEAD(J,N-2),J=1,3),ALD,CL,CD
C3=CD
C4=CL
MSGG = -SG
CALL MICE (C3,C4,ALI,CD,CL,MSGG)
RETURN
22 FORMAT (1H0,3A4,'STALLED AT ',F7.3,' DEGREES CL = ',F6.3,' CD = ',
1 F6.3)
6101 FORMAT ('0 EXCESSIVE ANGLE OF ATTACK FOR N = ',I2)
END

```

```

CLC01630
CLC01640
CLC01650
CLC01660
CLC01670
CLC01680
CLC01690
CLC01700
CLC01710
CLC01720
CLC01730
CLC01740
CLC01750
CLC01760
CLC01770
CLC01780
CLC01790
CLC01800
CLC01810
CLC01820
CLC01830
CLC01840
CLC01850
CLC01860
CLC01870
CLC01880
CLC01890
CLC01900
CLC01910
CLC01920

```

SUBROUTINE CCMOVL(COEF,REPRT1,ZPRT1,REPRT2,ZPRT2)

SOLUTION OF SIMULTANEOUS EQUATIONS
WITH COMPLEX COEFFICIENTS
N = ORDER OF MATRIX

DIMENSION COEF(2,3),A(2,5)
COMPLEX A,TEMP,DET,COEF

N=2
NP1 = 3
DO 3J = 1,NP1
DO 3I = 1,N
A(I,J) = COEF(I,J)
3 CONTINUE
DET = (1.0,0.0)

COLUMNAR REARRANGEMENT OF MATRIX

AMI=N-1
DO 60 I=1,NMI
JJ=I+1
IMAX=I
AMAXT = REAL(A(JJ,I))**2 + AIMAG(A(JJ,I))**2
DO 29J=JJ,N
ATEST1 = REAL(A(J,I))**2 + AIMAG(A(J,I))**2
ATEST2 = REAL(A(IMAX,I))**2 + AIMAG(A(IMAX,I))**2
IF(ATEST1-ATEST2) 29,29,28
28 IF(ATEST1.LE.AMAXT) GO TO 29
AMAXT = ATEST1
IMAX = J

29 CONTINUE
IF(IMAX-I) 60,60,33
33 DET=-DET
DO 50K=1,NP1
TEMP=A(I,K)
A(I,K)=A(IMAX,K)
A(IMAX,K)=TEMP
50 CONTINUE
60 CONTINUE

AUGMENT INPUT MATRIX WITH THE IDENTITY MATRIX

NP2 = 4
NP1 = 5
DO 10 I=1,N
DO 11 J =NP2,NP1
A(I,J) = 0.0
11 CONTINUE
10 CONTINUE
DO 13 I = 1,N
J = I + NP1
A(I,J) = 1.0
13 CONTINUE

COMSO010
COMSO020
COMSO030
COMSO040
COMSO050
COMSO060
COMSO070
COMSO080
COMSO090
COMSO100
COMSO110
COMSO120
COMSO130
COMSO140
COMSO150
COMSO160
COMSO170
COMSO180
COMSO190
COMSO200
COMSO210
COMSO220
COMSO230
COMSO240
COMSO250
COMSO260
COMSO270
COMSO280
COMSO290
COMSO300
COMSO310
COMSO320
COMSO330
COMSO340
COMSO350
COMSO360
COMSO370
COMSO380
COMSO390
COMSO400
COMSO410
COMSO420
COMSO430
COMSO440
COMSO450
COMSO460
COMSO470
COMSO480
COMSO490
COMSO500
COMSO510
COMSO520
COMSO530
COMSO540

COMS0550
 COMS0560
 COMS0570
 COMS0580
 COMS0590
 COMS0600
 COMS0610
 COMS0620
 COMS0630
 COMS0640
 COMS0650
 COMS0660
 COMS0670
 COMS0680
 COMS0690
 COMS0700
 COMS0710
 COMS0720
 COMS0730
 COMS0740
 COMS0750
 COMS0760
 COMS0770
 COMS0780
 COMS0790
 COMS0800
 COMS0810
 COMS0820
 COMS0830
 COMS0840
 COMS0850
 COMS0860
 COMS0870
 COMS0880
 COMS0890

```

SOLUTION
DO 19 I=1,N
  IPI = I+1
  TTEST = REAL(A(I,I))**2 + AIMAG(A(I,I))**2
  IF(TTEST.LE.0.000001) GO TO 99
  DO 15 J = IPI,NZPI
    A(I,J) = A(I,J)/A(I,I)
  15 CONTINUE
  DO 18 K = 1,N
    IF(K-I) 16,18,16
  16 DO 17 J = IPI,NZPI
    A(K,J) = A(K,J) - A(K,I)*A(I,J)
  17 CONTINUE
  18 CONTINUE
  19 CONTINUE
DETERMINANT EVALUATION
DO 20 I = 1,N
  DET = DET * A(I,I)
  20 CONTINUE
  ZPRT1 = REAL(A(1,3))
  ZPRT1 = AIMAG(A(1,3))
  ZPRT2 = REAL(A(2,3))
  ZPRT2 = AIMAG(A(2,3))
  RETURN
SINGULAR MATRIX
99 PRINT 999,I,I,A(I,I)
999 FORMAT (/3H A(,I2,1H,,I2,4H) = ,2F10.8 )
94 FORMAT(7E12.4)
RETURN
END

```

```

SUBROUTINE CON1 (XCON, O3ELE, TRIND, COLJET, EIMAST, PCGOEO, PCGMAX)
COMMON /STRIMA/ AY, VH, AGM, OT1(2), OT2(2), IXZ,
1 OMR, XXO, YVO, ZZD, ALGF, APFP, AYFP,
2 CGML, COLL(6), CYCF(3), CYCL(3),
3 OIST, KCIT(20), PEDAI(3), OMAX,
4 QMRS, TIME, TMAX, XCIT(20,6), ALGEZ,
5 ALGEL, ALGE2, CGSTA, CPWIC, OIXIZ,
6 OIYIX, OIZIV, OTZMT, OTZML, OTZTI, FTKTS,
* HUBKM(2,2), HUBKI(2,2),
7 KREAD, PIU30, TSTAB(14), ZMAX2, ZMAX3,
8 ASECOL, CYPWIC, GFARAT, PS0550,
9 PSISTP, OXBRK, RUDIND, ZOELT1, ZOELT2
COMMON /MANAL/
1 TZT, TIT, T2I, ALFL, CZET, PSDD,
2 SZET, TAXL, TAXR, XAMS, KLNK(16), ZAMG,
3 ALCYP, ALFIN, ALLWG, ALRMG, ALRMG, CDELE, COFIN,
4 COLMG, CORMG, CLELE, CLFIN, CLLWG, CLRMG, CMING,
5 CYCR1, CYCR2, CZET4, CZET6, CZET9, RANGE,
6 SZET5, SZET7, SZET8, NGCOL, XAELE, XAFIN,
7 XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,
8 YAELE, YAFUS, YALWG, YARMG, YALJET, YARJET,
9 ZAJET, ZALECR1, ALGFPD, BOTTOM, CZET11,
A CZET12, CZET13, FIZETA, HALFPI, SZET10,
B XAPYLO, YGUSTM, ZAPYLO, ZFLWGL, ZFRMG1
, TZMS, TMS, T2MS, TZTS, TITS, T2TS,
C CLOCK, FLOCK, XLOCK, TCLOCK
DIMENSION XCON(63)
DATA OTR, OTRR, PO10TR / .1745329E-01, .57.29578, .1745329E-03/
SET UP VALUES FOR COLLECTIVE
COLL(1)=XCON(1)
IF(COLL(1).EQ.0.) COLL(1)=100.
COLL(2)=XCON(2)*OTR
COLL(3)=XCON(3)
COLL(4)=XCON(4)*OTRR
COLL(5) = XCON(5)
IF(COLL(5).EQ.0.) COLL(5) = 100.
XXX = XCON(6)
IF(XXX.EQ.0.) XXX=COLL(5)
SLOPE OF RANGE
COLL(6)=(XXX-COLL(5))/HALFPI
CLOCK=XCON(7)
TZMS=XCON(8)*OTR
CPWIC=XCON(10)*COLL(1)*PO10TR
O3ELE=XCON(11)*COLL(1)*PO10TR
COLJET=XCON(12)*COLL(1)/100.
SET UP VALUES FOR F/A CYCLIC
CYCF(1)=XCON(15)
IF(CYCF(1).EQ.0.) CYCF(1)=100.

```

```

CON10010
CON10020
CON10030
CON10040
CON10050
CON10060
CON10070
CON10080
CON10090
CON10100
CON10110
CON10120
CON10130
CON10140
CON10150
CON10160
CON10170
CON10180
CON10190
CON10200
CON10210
CON10220
CON10230
CON10240
CON10250
CON10260
CON10270
CON10280
CON10290
CON10300
CON10310
CON10320
CON10330
CON10340
CON10350
CON10360
CON10370
CON10380
CON10390
CON10400
CON10410
CON10420
CON10430
CON10440
CON10450
CON10460
CON10470
CON10480
CON10490
CON10500
CON10510
CON10520
CON10530
CON10540

```

CON10550
 CON10560
 CON10570
 CON10580
 CON10590
 CON10600
 CON10610
 CON10620
 CON10630
 CON10640
 CON10650
 CON10660
 CON10670
 CON10680
 CON10690
 CON10700
 CON10710
 CON10720
 CON10730
 CON10740
 CON10750
 CON10760
 CON10770
 CON10780
 CON10790
 CON10800
 CON10810
 CON10820
 CON10830
 CON10840
 CON10850
 CON10860
 CON10870
 CON10880
 CON10890
 CON10900
 CON10910
 CON10920
 CON10930
 CON10940
 CON10950
 CON10960
 CON10970

```

CYCF(2)=XCON(16)*DTR
IF(CYCF(2).EQ.0.) CYCF(2)=-.8726646
CYCF(3)=XCON(17)*P01DTR
IF(CYCF(3).EQ.0.) CYCF(3)=DTR
FLOCK=XCON(18)
TIMS=XCON(19)*DTR
TITS=TIMS*TRIND
RDPIN=CYCF(1)/(100.*CYCF(3))
ALGE1=XCON(27)*RDPIN*DTR
ALGE2=XCON(28)*RDPIN**2*DTR

SET UP VALUES FOR LATERAL CYCLIC
CYCL(1)=XCON(29)
IF(CYCL(1).EQ.0.) CYCL(1)=100.
CYCL(2)=XCON(30)*DTR
IF(CYCL(2).EQ.0.) CYCL(2)=-.8726646
CYCL(3)=XCON(31)*P01DTR
IF(CYCL(3).EQ.0.) CYCL(3)=DTR
XLOCK=XCON(32)
T2MS=XCON(33)*DTR
T2TS=T2MS*TRIND
CYPWIC=XCON(41)*CYCL(1)/(100.*CYCL(3))*DTR

SET UP VALUES FOR PEDAL
PEOA(1)=XCON(43)
IF(PEOA(1).EQ.0.) PEOA(1)=100.
PEOA(2)=XCON(44)*DTR
IF(PEOA(2).EQ.0.) PEOA(2)=-.8726646
PEOA(3)=XCON(45)*P01DTR
IF(PEOA(3).EQ.0.) PEOA(3)=DTR
TCLOCK=XCON(46)
TZTS=XCON(47)*DTR

MISC. VALUES
PCGMAX=XCON(13)*DTR
PCGDEO=XCON(14)
RUOIND=XCON(48)
FIMAST=XCON(63)
RETURN
END
  
```

C
C
C

C
C
C

C
C
C

```

SUBROUTINE CON2 (XCON,XLNK,KONFIG,PUDIND)
DATA DTR/ .1745329E-01/
DIMENSION XCON(63),XLNK(16)
XLNK(12)=XCON(25)
XLNK(13)=XCON(26)
IF(KONFIG.NE.1) GO TO 10
XLNK(2)=1.
IF(RUDIND.EQ.0.) GO TO 11
RUDIND=1.
XLNK(2)=XCON(58)
11 DD=0TR*RUDIND
XLNK(1)=XCON(57)*00
XLNK(3)=XCON(59)*00*DTR
RETURN
10 XLNK(1)=XCON(24)
XLNK(2)=XCON(40)
XLNK(3)=XCON(9)
DO 13 I=1,3
IF(XLNK(I).EQ.0.) XLNK(I)=1.
13 CONTINUE
IF(KONFIG.EQ.3) GO TO 12
XLNK(4)=XCON(23)
XLNK(5)=XCON(22)
XLNK(6)=XCON(55)
XLNK(7)=XCON(54)
RETURN
12 XLNK(4)=XCON(37)
XLNK(5)=XCON(51)
XLNK(6)=XCON(36)
XLNK(7)=XCON(50)
XLNK(8)=XCON(39)
XLNK(9)=XCON(53)
XLNK(10)=XCON(38)
XLNK(11)=XCON(52)
XLNK(14)=XCON(60)
XLNK(15)=XCON(61)
XLNK(16)=XCON(52)*DTR
RETURN
END

```

```

CON20010
CON20020
CON20030
CON20040
CON20050
CON20060
CON20070
CON20080
CON20090
CON20100
CON20110
CON20120
CON20130
CON20140
CON20150
CON20160
CON20170
CON20180
CON20190
CON20200
CON20210
CON20220
CON20230
CON20240
CON20250
CON20260
CON20270
CON20280
CON20290
CON20300
CON20310
CON20320
CON20330
CON20340
CON20350
CON20360
CON20370
CON20380
CON20390

```

```

SUBROUTINE CURVET
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
I NPART,NVARA,NVARB,NVARC,NSCALE
I ,NVARC,NPRINT,NTIME
COMMON /PLOTTD/ HEAD(9,267)
DIMENSION A(266),NC(266),AMP(266),PHI(266),C(266),SUM1(266),
I S1(266),SUM3(266),SUM4(266),CDEF(266),NUMC(266)
I REAL*8 X,Y,R,S1,S2,S3,S4,S5,SUM1,SUM2,SUM3,SUM4,
I DIFF1,DIFF2,DIFF3,DIFF5,DIFF6,DENOM,CON1,CON2,CON3,DIFF7
CALL TIMEEX (TUSED,TDELT,TLEFT)
DTR=.174532925E-01
DTRR=57.2957795
TWOP=6.283185307
INITIALIZE VARIABLE SUMS
DO 10 I=1,254
NC(I)=0
SUM1(I)=0.
SUM2(I)=0.
SUM3(I)=0.
SUM4(I)=0.
10 CONTINUE
C READ CODES FOR VARIABLES TO BE FIT
READ (5,900) (NC(I),I=1,NVARA)
C SKIP TRANSIENT POINTS
DO 11 I=1,NVARC
READ (3) JPSN,T,A
11 CONTINUE
TSTART=T
C CHANGE INPUT CPS TO RAD/SEC AND INITIALIZE TIME SUMS
OMEGA=AL(1)*TWOP
S1=0.
S2=0.
S3=0.
S4=0.
S5=0.
KOUNT=C
998 READ (3,END=999) JPSN,T,A
IF(T.GT.9.E+07) GO TO 999
X=SIN(OT)
Y=COS(OT)
C COMPUTE SUMS WHICH ARE CONSTANT WRT VARIABLES AND COUNT POINTS
S1=S1+X
S2=S2+Y
S3=S3+X*X
S4=S4+Y*Y
S5=S5+X*Y
KOUNT=KOUNT+1
C COMPUTE SUMS DEPENDENT UPON EACH VARIABLE
DO 12 J=1,NVARA
I=NC(J)
R=A(I)
SUM1(I)=SUM1(I)+R
SUM2(I)=SUM2(I)+R*X

```

```

CURV0010
CURV0020
CURV0030
CURV0040
CURV0050
CURV0060
CURV0070
CURV0080
CURV0090
CURV0100
CURV0110
CURV0120
CURV0130
CURV0140
CURV0150
CURV0160
CURV0170
CURV0180
CURV0190
CURV0200
CURV0210
CURV0220
CURV0230
CURV0240
CURV0250
CURV0260
CURV0270
CURV0280
CURV0290
CURV0300
CURV0310
CURV0320
CURV0330
CURV0340
CURV0350
CURV0360
CURV0370
CURV0380
CURV0390
CURV0400
CURV0410
CURV0420
CURV0430
CURV0440
CURV0450
CURV0460
CURV0470
CURV0480
CURV0490
CURV0500
CURV0510
CURV0520
CURV0530
CURV0540

```

```

SUM3(I)=SUM3(I)+B*Y
SUM4(I)=SUM4(I)+B*B
12 CONTINUE
GO TO 998
C COMPUTE INTERMEDIATE VARIABLES
999 DIFF1=KDUNT*S3-S1**2
DIFF2=KDUNT*S4-S2**2
DIFF3=KDUNT*S5-S1*S2
DENOM=DIFF1*DIFF2-DIFF3**2
CALL WROT
WRITE (6,901) TSTART,AL(I)
C COMPUTE AMPLITUDE, PHASE ANGLE, CONSTANT, AND RESIDUE
DO 13 J=1,NVAR
I=NC(J)
DIFF5=KDUNT*SUM2(I)-S1*SUM1(I)
DIFF6=KDUNT*SUM3(I)-S2*SUM1(I)
CON1=(DIFF5*DIFF2-DIFF6*DIFF3)/DENOM
CON2=(DIFF1*DIFF6-DIFF5*DIFF3)/DENOM
AMP(I)=DSORT(CON1**2+CON2**2)
PHI(I)=ATAN2(CON2,CON1)*DTRR
CON3=(SUM1(I)-CON1*S1-CON2*S2)/KOUNT
DIFF7 =CON1*(CON1*S3-2.*SUM2(I)+2.*CON2*S5+2.*CON3*S1)
1 +CON2*(CON2*S4-2.*SUM3(I)+2.*CON3*S2)
2 +CON3*(KDUNT*CON3-2.*SUM1(I))+SJM4(I)
C(I)=CON3
CDEF(I)=DSORT(1.-DIFF7/(SUM4(I)-SUM1(I)**2/KOUNT))
WRITE (6,902) (HEAD(K,I),K=1,9),AMP(I),PHI(I),C(I),CDEF(I)
13 CONTINUE
IF(NVAR.EQ.0) GO TO 18
CALL WROT
WRITE (6,903)
C AMPLITUDE AND PHASE ANGLE COMPARISONS
DO 100 I=1,NVAR
READ (5,900) NNUM,ND, (NUMC(J),J=1,NUM)
Q1=1./AMP(ND)
Q2=PHI(ND)
DO 15 K=1,NUM
J=NUMC(K)
RATIO=AMP(J)*Q1
DIFF=PHI(J)-Q2
WRITE (6,904) (HEAD(L,J),L=1,9), (HEAD(L,ND),L=1,9),RATIO,DIFF
15 CONTINUE
100 CONTINUE
16 KLIN=AL(2)+.1
IF(KLIN.EQ.0) GO TO 101
CALL WROT
WRITE (6,908)
DO 16 J=1,KLIN
READ (5,900) NDEP,NIN1,NIN2
SIN2=SIN(PHI(NIN1)-PHI(NIN2))*DTR
IF(ABS(SIN2).LT..0001) GO TO 17
SIN1=SIN(PHI(NIN1)-PHI(NDEP))*DTR
SIN3=SIN(PHI(NDEP)-PHI(NIN2))*DTR
XK1=AMP(NDEP)/SIN2
CURV0550
CURV0560
CURV0570
CURV0580
CURV0590
CURV0600
CURV0610
CURV0620
CURV0630
CURV0640
CURV0650
CURV0660
CURV0670
CURV0680
CURV0690
CURV0700
CURV0710
CURV0720
CURV0730
CURV0740
CURV0750
CURV0760
CURV0770
CURV0780
CURV0790
CURV0800
CURV0810
CURV0820
CURV0830
CURV0840
CURV0850
CURV0860
CURV0870
CURV0880
CURV0890
CURV0900
CURV0910
CURV0920
CURV0930
CURV0940
CURV0950
CURV0960
CURV0970
CURV0980
CURV0990
CURV1000
CURV1010
CURV1020
CURV1030
CURV1040
CURV1050
CURV1060
CURV1070
CURV1080

```

```

CURV1090
CURV1100
CURV1110
CURV1120
CURV1130
CURV1140
CURV1150
CURV1160
CURV1170
CURV1180
CURV1190
CURV1200
CURV1210
CURV1220
CURV1230
CURV1240
CURV1250
CURV1260
CURV1270
CURV1280
CURV1290
CURV1300
CURV1310
CURV1320
CURV1330
CURV1340
CURV1350
CURV1360
CURV1370
CURV1380
CURV1390
CURV1400
CURV1410
CURV1420
CURV1430
CURV1440
CURV1450
CURV1460

XK2=XK1*SIN3
XK3=XK1*SIN1
BK=XK2/AMP(NIN1)
CK=XK3/AMP(NIN2)
DK=C(NDEP)-BK*C(NIN1)-CK*C(NIN2)
WRITE (6,906) (HEAD(K,NIN1),K=1,9),(HEAD(K,NIN1),K=1,9),BK,
1 (HEAD(K,NIN2),K=1,9),CK,DK
GO TO 16
17 WRITE (6,907) (HEAD(K,NIN1),K=1,9),(HEAD(K,NIN2),K=1,9)
16 CONTINUE
101 CALL TIMEX (TUSED,TDELT,TLEFT)
WRITE (6,905) TDELT,TUSED
RETURN
900 FORMAT (14I5)
901 FORMAT (1H0//1H ,32X,'LEAST SQUARES CURVE FIT STARTING AFTER',
1 F7.3,' SECONDS MANUEVER TIME'//1H ,23X,
'FIT) = AMPLITUDE*SIN(OMEGA*T + PHASE ANGLE) + CONSTANT'
1 10X,' WITH OMEGA =',F7.3,' CPS'//
2 1H ,20X,' VARIABLE',23X,'AMPLITUDE',6X,
3 'PHASE ANGLE (DEGREES)',7X,'CONSTANT',11X,'COEF OF CORR')
4
902 FORMAT (1H0,6X,9A4,4I6X,G15.5)
903 FORMAT (1H0//1H ,48X,'AMPLITUDE AND PHASE ANGLE COMPARISONS'//
1 1H ,39X,' VARIABLES',39X,'AMPLITUDE RATIO',3X,
2 'PHASE ANGLE DIFFERENCE')
904 FORMAT (1H0,7X,9A4,7',9A4,2I7X,G15.5)
905 FORMAT (1H0,10X,F10.3,' MINUTES USED IN CURVE FITTING',
1 F10.3,' MINUTES TOTAL COMPUTING TIME')
906 FORMAT (1H0,30X,'A',10X,9A4/
1 1H ,30X,'B',10X,9A4,10X,G15.5/
2 1H ,30X,'C',10X,9A4,10X,G15.5/
3 1H ,69X,'CONSTANT',10X,G15.5)
907 FORMAT (1H0,10X,'THE PHASE ANGLE DIFFERENCE BETWEEN ,9A4,' AND ',CURV1400
1 9A4//1H ,10X,' IS A MULTIPLE OF 180 DEGREES. THEREFORE, NO VCURV1410
2 VARIABLE CAN BE EXPRESSED AS A LINEAR FUNCTION OF THEM.')
908 FORMAT (1H0//1H ,35X,'VARIABLE ,A', AS A LINEAR COMBINATION OF VACURV1430
1 VARIABLES ,B', AND ,C',,//1H ,56X,'A = KA*B + KC*C + KD'//1H ,
2 27X,' VARIABLE',22X,'NAME',28X,'COEFFICIENT')
END

```

```

C81L0010
C81L0020
C81L0030
C81L0040
C81L0050
C81L0060
C81L0070
C81L0080
C81L0090
C81L0100
C81L0110
C81L0120
C81L0130
C81L0140
C81L0150
C81L0160
C81L0170
C81L0180
C81L0190
C81L0200
C81L0210
C81L0220
C81L0230
C81L0240
C81L0250
C81L0260
C81L0270
C81L0280
C81L0290
C81L0300
C81L0310
C81L0320
C81L0330
C81L0340
C81L0350
C81L0360
C81L0370
C81L0380
C81L0390
C81L0400
C81L0410
C81L0420
C81L0430
C81L0440
C81L0450
C81L0460
C81L0470
C81L0480
C81L0490
C81L0500
C81L0510
C81L0520
C81L0530
C81L0540

SURROUTINE CALL
LIBRARY UPDATING
*****
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
  NPART,NVARA,NVARB,NVARC,NSCALE
  ,NVAR5,NPRINT,NTIME
1 DIMENSION A(266)

READ DATA CARD IN C81-11 DRIVER...
NPART = 8 (TO GET IN HERE)
NSCALE = (TO SPECIFY WHICH LIBRARY PATH)

NPATH = 0 TO DUMP TIME HISTORY DATA ON TAPE 9
READ SINGLE TIME-HISTORY FROM (3),
WRITE TIME HISTORY ON 9
NPATH = 1 IS FOR LAST JOB THIS TERMINATES TAPE 9

NPATH = 2 IS FOR PULLING DATA FROM 9 AND WRITING IT ON 3

TO PULL A SPECIFIC IPSN FOR RE-PLOTTING (NPATH=2),
USE COMMENT CARDS WHICH WERE ON DECK WHEN T-H WAS MADE
***** DO NOT CHANGE IPSN ON FIRST COMMENT CARD *****
*****

CALL TIMEX (TUSED,TOELT,TLFT)
NPATH = NSCALE
NPSN=0
WRITE(6,202)
IF(NPATH.LT.0.OR.NPATH.GT.2) GO TO 130
IF(NPATH.EQ.2) GO TO 100
TRANSFER T-H FROM 3 TO 9
203 READ (3) JPSN,T,A
25 WRITE(9,21) JPSN,T,A
IF(T.LT.9999.E+04) GO TO 203
WRITE(6,204) JPSN
IF(NPATH.EQ.0) GO TO 207
T=888888.E+01
WRITE (9,21) IPSN,T,A
ENDFILE 9
207 REMIND 9
GO TO 600
C 100 READ (5,1011) IPSN,ICOM
SEARCH OLD MASTER FOR T-H TO PLOT
C 110 READ (8,21) JPSN,T,A
IF(8888.E+04.LT.T.AND.T.LT.9999.E+04) GO TO 140
IF(NPSN.EQ.JPSN) GO TO 115
NPSN=JPSN
WRITE (6,205) NPSN
C 115 IF(IPSN.NE.JPSN) GO TO 110
WRITE T-H ON TAPE 3
C 120 WRITE (3) JPSN,T,A

```

```

IF(T.LT.9999.E+04) GO TO 110
WRITE (6,206) MPSN
ENDFILE 3
REWIND 8
GO TO 600
140 WRITE(6,14)
GO TO 600
130 WRITE(6,13)
500 CALL TIMEX (TUSED,TDELT,TLEFT)
WRITE(6,601) TDELT
RETURN
13 FORMAT (' NSCALE HAS ILLEGAL VALUE')
14 FORMAT(30H IPSN INDICATED NOT ON LIBRARY )
21 FORMAT (19,2E12.5/(10E12.5))
202 FORMAT (1H,18X,12HPROGRAM C01L/14X,20HTIME HISTORY LIBRARY //
1 ON PULLED FROM PUT ON
2 48H LIBRARY TAPE LIBRARY TAPE SCRATCH TAPE )
204 FORMAT(34X,112)
205 FORMAT(114)
206 FORMAT (18X,112)
601 FORMAT(1H /24H TIME USED WITHIN C01L =, F5.2.5H MIN.)
1011 FORMAT (2X,18,13A4/17A4/17A4)
END
C01L0550
C01L0560
C01L0570
C01L0580
C01L0590
C01L0600
C01L0610
C01L0620
C01L0630
C01L0640
C01L0650
C01L0660
C01L0670
C01L0680
C01L0690
C01L0700
C01L0710
C01L0720
C01L0730
C01L0740
C01L0750
C01L0760
C01L0770

```

DAMP0010
DAMP0020
DAMP0030
DAMP0040
DAMP0050
DAMP0060
DAMP0070
DAMP0080
DAMP0090
DAMP0100
DAMP0110
DAMP0120
DAMP0130
DAMP0140
DAMP0150
DAMP0160
DAMP0170
DAMP0180
DAMP0190
DAMP0200
DAMP0210
DAMP0220
DAMP0230
DAMP0240
DAMP0250

```

SUBROUTINE DAMPER
COMMON /STRIAB/ D(21),DT(21),E(79),F(10),X(10),
DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
DTR,EPD,ERR(10),KMI,RHD,
R12,SPD(6,6,3),XBM(21),XEL(14),
XER(7),XFC(28),XFN(7),XFS(35),
XGN(7),XIT(21),XMR(49),XTR(49),
XWG(21),YMR(21),YTR(21),YWG(21),
YEL(21),YFN(21),BLCG,DAMP,DEPD(10),
EPDS,EPDX(10),MASS,OSV1,TMRS,TTRS,
WLCG,XCOM(63),XJET(14),XMIN,AYEFP,
BETAES(2),CMPCD,DMADQ,DYBDR,GUESS,
NPASS,POPHI(10,11),STACG,TZERO,
XMAST,DMADAQ,DOOCOL,DTRRSQ,DYBDBR,
EMGRPH,MXPASS,PSD30P,TRIND1,XLIMIT
D XLIMIT=.5*XLIMIT
IF(XLIMIT.LT.XMIN) XLIMIT=XMIN
EPD=.5*XLIMIT
IF(EPD.LT..1745329E-03) EPD=.1745329E-03
DO 2 I=1,9
DEPD(I)=EPD*EPDX(I)
2 CONTINUE
DEPD(10)=-EPD
RETURN
END

```

BLOCK DATA			
COMMON /METER/	PARM1(10.6), PARM2(10.6), PARM3(10.6),		DAT00010
1	PARM4(10.6), PARM5(10.6), PARM6(10.6), PARM7(10.2)		DAT00020
COMMON /PLOT0/			DAT00030
1	PLOT10(9.7), PLOT29(9.7), PLOT11(9.7), PLOT28(9.7)		OATDD0040
2	PLOT12(9.7), PLOT29(9.7), PLOT13(9.7), PLOT3D(9.7)		OATDD0050
1	PLOT14(9.7), PLOT31(9.7), PLOT15(9.7), PLOT32(9.7)		OATDD0060
2	PLOT16(9.7), PLOT33(9.7), PLOT17(9.7), PLOT34(9.7)		OATDD0070
1	PLOT18(9.6), PLOT3C(9.5)		OATDD0080
3	OPLOT(9.6), PLOTE(9.6), PLOTF(9.6), PLOTG(9.5)		DAT00090
4	PLOTH(9.6), PLOTI(9.6), PLOTJ(9.6), PLOTK(9.5)		DAT00100
5	PLOTL(9.7), PLOTM(9.7)		OAT00110
6	PLOT19(9.7), PLOT20(9.7), PLOT21(9.7)		DAT00120
7	PLOT22(9.7), PLOT23(9.7), PLOT24(9.7)		DAT00130
7	PLOT25(9.7), PLOT26(9.7)		OAT00140
5	PLOTM(9.6), PLOTN(9.6), PLOT0(9.5)		DAT00150
6	PLOTT(9.6), PLOTU(9.6), PLOTV(9.6), PLOTS(9.5)		DAT00160
7	PLOTX(9.6), PLOTY(9.6), PLOTZ(9.6), PLOT0(9.5)		DAT00170
8	DATA PARM /		DAT00180
1	IF ATTACK (DEGREES)		DAT00190
2	BODY Z-FORCE (+DOWN) (LBS)	WING ANGLE (DEGREES)	DAT00200
3	BODY X-FORCE (+FWD) (LBS)	F/A CYCLIC PITCH (DEGREES)	DAT00210
DATA PARM1 /		LAT CYCLIC PITC (DEGREES)	DAT00220
4/A FLAPPING	(DEGREES)	ELEVATOR ANGLE OF ATTACK (DEGREES)	FOAT00230
5)	LAT FLAPPING (DEGREES)	THRUST (LBS)	DAT00240
6(+DOWN) (LBS)		BODY Z-FORCE (LBS)	DAT00250
7	DATA PARM2 /		DAT00260
1	FIN ANGLE OF ATTACK (DEGREES)	H-FORCE (LBS)	DAT00270
2	Y-FORCE (LBS)	RUDDER ANGLE OF ATTACK (DEGREES)	DAT00280
9	Y-FORCE (+RIGHT) (LBS)	BODY Y-FORCE (+RIGHT) (LBS)	DAT00290
8	DATA PARM3 /		DAT00300
1	HORSEPOWER	BODY X-FORCE (+FWD) (LBS)	DAT00310
2	(LBS)	BODY X-FORCE (LBS)	DAT00320
C+ FWD)		HELICOPTER EULER ANGLE YAW (DEGREES) %	DAT00330
D	RPM		DAT00340
E	DEGREES)	MAST TILT ANGLE (DEGREES) %	DAT00350
DATA PARM4 /			DAT00360
1	PITCH (DEGREES)	BLADE INERTIA (SLUG-FT-SQ)	DAT00370
2	ROLL (DEGREES)	JET THRUST, LEFT SIDE (FT/SEC)	DAT00380
G	(LBS)		DAT00390
H	RATE OF CLIMB (FT/SEC)	FORWARD SPEED (KNOTS)	DAT00400
I	RIGHT SIDE (LBS)	COLLECTIVE F/A CYCLIC	DAT00410
J	DATA PARM5 /		DAT00420
1	PCT CONTROL USED (LBS)		DAT00430
2	ENGINE RPM	C.G. STATION LINE (IN)	DAT00440
3	DATA PARM6 /		DAT00450
1	PEDAL	WATER LINE (IN)	DAT00460
2			DAT00470
3			DAT00480
4			DAT00490
5			DAT00500
DATA PLOT10 /	Q VELOCITY, TPPI, DEG/SEC	P VELOCITY, TPPI, DEG/SEC	DAT00510
1	U VELOCITY, MAST1 AXES, FT/SEC	DMEGA-ODD	DAT00520
2	BETA-2DOT, BLADE1, ROT/R1, DEG/SEC	F/A FLAPPING, MAST1/TPPI, DEG	DAT00530
3	THRUST, LB		DAT00540

```

4 // DATA PLOT27 OAT00550
4 // LATERAL FLAPPING, MAST1/TPP1, DEG // DAT00560
DATA PLOT11 // V VELOCITY, MAST1 AXES, FT/SEC OMEGA, ROTOR1, DAT00570
1 DEG/SEC BETA-DOT, BLADE1, ROTOR1, DEG/SEC ROTOR1 HDAT00580
2-FORCE, LB M VELOCITY, MAST1 AXES, FT/SEC ROTOR1 AZOAT00600
3-AZIMUTH LOC., BLADE1, ROTOR1, DEG BETA, BLADE1, ROTOR1, DEG OAT00610
4 // OAT00620
DATA PLOT28 DAT00630
4 // ROTOR1 Y-FORCE, LB OAT00640
DATA PLOT12 // ROTOR1 COLLEC. FROM CONTROLS, DEG ROTOR1 F/A CYC DAT00650
1. FROM CONTROLS, DEG ROTOR1 LAT CYC. FROM CONTROLS, DEG ROTOR1 COAT00660
2-ONING, DEG MAST1 TILT, DEG ROTOR1 COAT00670
3-TOR1 TORQUE, FT-LB ROTOR1 OTHER COLLEC., DEG DAT00680
4 // DAT00690
DATA PLOT29 DAT00700
4 // ROTOR1 OTHER F/A CYC., DEG ROTOR1 INDUCED DAT00710
DATA PLOT13 // ROTOR1 OTHER LAT CYC., DEG ROTOR1 HOAT00730
1 VELOCITY, FT/SEC ROTOR1 RPM ROTOR1 UPPER FLAPPING LIMIT, DEG ROTOR1 HOAT00740
2-RORSEPOWER ROTOR1 F/A HUBSPRING, FT-LB/DEG ROTOR1 TOTAL COLLECTIVE, DEG OAT00750
3-TOR1 F/A HUBSPRING, FT-LB/DEG ROTOR1 TOTAL COLLECTIVE, DEG OAT00760
4 // DAT00770
DATA PLOT30 DAT00780
4 // ROTOR1 TOTAL F/A CYCLIC, DEG ROTOR1 LOWER FOAT00790
DATA PLOT14 // ROTOR1 TOTAL LAT CYCLIC, DEG ROTOR1 LOWER FOAT00790
1 FLAPPING LIMIT, DEG ROTOR1 LAT HUBSPRING, FT-LB/DEG O VELOCIDAT00800
2-TY, TPP2, DEG/SEC P VELOCITY, TPP2, DEG/SEC U DAT00810
3-VFLOCITY, MAST2 AXES, FT/SEC OMEGA-DOT, ROTOR2, DEG/SEC/SEC DAT00820
4 // DAT00830
DATA PLOT31 DAT00840
4 // BETA-DOT, BLADE1, ROTOR2, DEG/SEC/SEC // DAT00850
DATA PLOT15 // ROTOR2 THRUST, LB F/A FLAPPING, DAT00860
1 MAST2/TPP2, DEG LATERAL FLAPPING, MAST2/TPP2, DEG V VELOCIDAT00870
2-TY, MAST2 AXES, FT/SEC OMEGA, ROTOR2, DEG/SEC BEDAT00880
3-TA-DOT, BLADE1, ROTOR2, DEG/SEC ROTOR2 H-FORCE, LB DAT00890
4 // OAT00900
DATA PLOT32 DAT00910
4 // M VELOCITY, MAST2 AXES, FT/SEC // DAT00920
DATA PLOT 3 // AZIMUTH LOC., BLADE1, ROTOR2, DEG BETA, BLADE1, ROTOR2, DEG DAT00930
1 ROTOR2, DEG ROTOR2 Y-FORCE, LB ROTOR2 COATD00940
2 COLLEC. FROM CONTROLS, DEG ROTOR2 F/A CYC. FROM CONTROLS, DEG ROTOR2 COATD00950
3 ROTOR2 LAT CYC. FROM CONTROLS, DEG ROTOR2 CONING, DEG DAT00960
4 // DAT00970
DATA PLOT33 DAT00980
4 // MAST2 TILT, DEG // DAT00990
DATA PLOT17 // ROTOR2 TORQUE, FT-LB ROTOR2 OTHER COATD1000
1 COLLEC., DEG ROTOR2 OTHER F/A CYC., DEG ROTOR2 COATD1010
2 OTHER LAT CYC., DEG ROTOR2 INDUCED VELOCITY, FT/SEC ROTOR2 COATD1020
3 TOR2 RPM ROTOR2 HORSEPOWER DAT01030
4 // DAT01040
DATA PLOT34 OAT01050
4 // ROTOR2 UPPER FLAPPING LIMIT, DEG // OAT01060
DATA PLOT18 // ROTOR2 F/A HUBSPRING, FT-LB/DEG DAT01070
1 COLLECTIVE, DEG ROTOR2 TOTAL F/A CYCLIC, DEG ROTOR2 TOTAL COATD1080
ROTOR2 TOTAL DAT01080

```

2J2AL LAT CYCLIC, DEG ROTR2 LOWER FLAPPING LIMIT, DEG ROAT01090
 3TOR2 LAT HUBSPRING, FT-LB/DEG // DATO1100
 DATA PLOTG / DATO1110
 A X-COMP VELOCITY, FIXED AXES, FT/SEC Y-COMP VELOCITY, FIXED AXES, FT/SEC
 B FT/SEC Z-COMP VELOCITY, FIXED AXES, FT/SEC TOTAL DISTANCE FLOWN, DATO1120
 C FT AIR SPEED, KTS // DATO1130
 DATA DPLOT / HEADING ANGLE, DEG X-COMP DISP., FT/SEC DATO1140
 1IXEO AXES, FT Y-COMP DISP., FT/SEC X-COMP DISP., FT/SEC DATO1150
 2SP., FIXED AXES, FT ALTITUDE, FT Z-COMP DISPLACEMENT, FT/SEC DATO1160
 3UND SPEED, KTS // GRODATO1170
 DATA PLOTG / CLIMB ANGLE, DEG DATO1180
 4 U-DDOT ACCEL., BODY AXES, FT/SEC V-DDOT ACCEL., BODY AXES, FT/SEC DATO1190
 5/SEC/SEC W-DDOT ACCEL., BODY AXES, FT/SEC P-DDOT ACCEL., BODY AXES, FT/SEC DATO1200
 6S, DEG/SEC/SEC Q-DDOT ACCEL., BODY AXES, DEG/SEC/SEC // DATO1210
 DATA PLOTG / R-DDOT ACCEL., BODY AXES, DEG/SEC/SEC // DATO1220
 7DY AXES, DEG/SEC/SEC COLLEC. BOMWT. ACCEL., DEG/SEC/SEC U VELOCIT DATO1230
 8Y, BODY AXES, FT/SEC V VELOCITY, BODY AXES, FT/SEC W VELOCIT DATO1240
 9ELOCITY, BODY AXES, FT/SEC P VELOCITY, BODY AXES, DEG/SEC // DATO1250
 A // DATO1260
 DATA PLOTG / DATO1270
 A O VELOCITY, BODY AXES, DEG/SEC R VELOCITY, BODY AXES, DEG/SEC DATO1280
 BSEC COLLEC. BOMWT. VELOCITY, DEG/SEC YAM VELOCITY, FIXED/8 DATO1290
 CODY, DEG/SEC PITCH VELOCITY, FIXED/BODY, DEG/SEC // DATO1300
 OATA PLOTG / ROLL VELOCITY, FIXED/BODY, DEG/SEC YAM ANGLE, FIXED DATO1310
 1D/BODY, DEG PITCH ANGLE, FIXED/BODY, DEG ROLL ANGLE DATO1320
 2E, FIXED/BODY, DEG COLLECTIVE STICK POSITION, PCT F/ADATO1330
 3 CYCLIC STICK POSITION, PCT // DATO1340
 DATA PLOTG / DATO1350
 4 RIGHT WING ANGLE OF ATTACK, DEG LEFT WING ANGLE OF ATTACK, DEG DATO1360
 5EG FIN ANGLE OF ATTACK, DEG ELEVATOR ANGLE OF ATTACK, DDATO1370
 6ATH, DEG C.G. STATION LINE LOCATION, IN. // BODY YAM WRT. FLIGHT DATO1380
 DATA PLOTJ / DATO1390
 7. BODY AXES, FT/SEC X-COMP G-S, BODY AXES X-COMP GUST VELOCIT DATO1400
 8YCLIC STICK POSITION, PCT LEFT WING COEFFICIENT OF LIFT LATERAL CDATO1410
 9HT WING COEFFICIENT OF LIFT ELEVATOR COEFFICIENT OF LIFT RIGDATO1420
 A // DATO1430
 DATA PLOTG / DATO1440
 A FIN COEFFICIENT OF LIFT BODY PITCH WRT. FLIGHT PATHOATO1450
 B, DEG C.G. BUTT LINE LOCATION, IN. Y-COMP GUST VEL., BODDATO1460
 CY AXES, FT/SEC Y-COMP G-S, BODY AXES // DATO1470
 DATA PLOTG / PEDAL POSITION, PCT LEFT WING COEFFOATO1480
 1ICIENT OF DRAG RIGHT WING COEFFICIENT OF DRAG ELEVATOR DATO1490
 2COEFFICIENT OF DRAG FIN COEFFICIENT OF DRAG C-GOATO1510
 3. WATER LINE LOCATION, IN. Z-COMP GUST VEL., BODY AXES, FT/SOATO1520
 4EC // DATO1530
 DATA PLOTM / DATO1540
 4 RIGHT/CENTER JET THRUST, LB Z-COMP G-S, BODY AXES DATO1540
 5LB TOTAL HORSEPOWER REQUIRED ENGINE TORQUE SUPPLIED, FT-DATO1550
 6 SHAFT HORSEPOWER LEFT JET THRUST, LB DATO1560
 TORQUE APPLIED, FT-LB // ROTOR BRAKE TOR DATO1570
 DATA PLOT19 / AZIMUTH LOC., BLADE1, ROTOR1, DEG AZIMUTH LOC., DATO1580
 1BLADE2, ROTDR1, DEG AZIMUTH LOC., BLADE3, ROTDR1, DEG AZIMUTH DATO1590
 2L3C., BLADE4, ROTDR1, DEG AZIMUTH LOC., BLADE5, ROTDR1, DEG AZ DATO1610
 3IMUTH LOC., BLADE6, ROTDR1, DEG AZIMUTH LOC., BLADE7, ROTDR1, DEDATO1620

4G ' / OATO1630
 DATA PLOT20 / ' BETA-2DOT, BLADE1, ROTOR1, DEG/SEC BETA-2DOT, BLADDDATO1640
 1E2, ROTOR1, DEG/SEC BETA-2DOT, BLADE3, ROTOR1, DEG/SEC BETA-2DODATO1650
 2T, BLADE4, ROTOR1, DEG/SEC BETA-2DOT, BLADE5, ROTOR1, DEG/SEC BEDATO1660
 3TA-2DOT, BLADE6, ROTOR1, DEG/SEC BETA-2DOT, BLADE7, ROTOR1, DEG/SEC/DATD1670
 4SEC' / OATO1680
 OATA PLOT21 / ' BETA-DOT, BLADE1, ROTOR1, DEG/SEC BETA-DOT, BLADDDATO1690
 1E2, ROTOR1, DEG/SEC BETA-DOT, BLADE3, ROTOR1, DEG/SEC BETA-DOTDOTO1700
 2, BLADE4, ROTOR1, DEG/SEC BETA-DOT, BLADE5, ROTOR1, DEG/SEC BEDATO1710
 3TA-DOT, BLADE6, ROTOR1, DEG/SEC BETA-DOT, BLADE7, ROTOR1, DEG/SEC/DATD1720
 4C ' / OATO1730
 DATA PLOT22 / ' BETA, BLADE1, ROTOR1, DEG BETA, BLADE2, OATO1740
 1ROTOR1, DEG BETA, BLADE3, ROTOR1, DEG BETA, BLADATO1750
 2AOE4, ROTOR1, OEG BETA, BLADE5, ROTOR1, OEG BEDATO1760
 3TA, BLADE6, ROTOR1, OEG BETA, BLADE7, ROTOR1, DEG DATO1770
 4 ' / DATO1780
 DATA PLOT23 / ' AZIMUTH LOC., BLADE1, ROTOR2, DEG AZIMUTH LOC., DATO1790
 1BLADE2, ROTOR2, OEG AZIMUTH LOC., BLADE3, ROTOR2, DEG AZIMUTH DATO1800
 2LOC., BLADE4, ROTOR2, DEG AZIMUTH LOC., BLADE5, ROTOR2, DEG AZDATO1810
 3IMUTH LOC., BLADE6, ROTOR2, DEG AZIMUTH LOC., BLADE7, ROTOR2, DEOATO1820
 4G ' / DATO1830
 DATA PLOT24 / ' BETA-2DOT, BLADE1, ROTOR2, DEG/SEC BETA-2DOT, BLADDDATO1840
 1E2, ROTOR2, OEG/SEC BETA-2DOT, BLADE3, ROTOR2, DEG/SEC BETA-2DODATO1850
 2T, BLADE4, ROTOR2, OEG/SEC BETA-2DOT, BLADE5, ROTOR2, DEG/SEC BEDATO1860
 3TA-2DOT, BLADE6, ROTOR2, DEG/SEC BETA-2DOT, BLADE7, ROTOR2, DEG/SEC/DATO1870
 4SEC' / DATO1880
 DATA PLOT25 / ' BETA-DOT, BLADE1, ROTOR2, OEG/SEC BETA-DOT, BLADDDATO1890
 1E2, ROTOR2, DEG/SEC BETA-DOT, BLADE3, ROTOR2, DEG/SEC BETA-DOTDOTO1900
 2, BLADE4, ROTOR2, DEG/SEC BETA-DOT, BLADE5, ROTOR2, DEG/SEC BEDATO1910
 3TA-DOT, BLADE6, ROTOR2, DEG/SEC BETA-DOT, BLADE7, ROTOR2, DEG/SEC/DATO1920
 4C ' / DATO1930
 DATA PLOT26 / ' BETA, BLADE1, ROTOR2, DEG BETA, BLADE2, OATO1940
 1ROTOR2, DEG BETA, BLADE3, ROTOR2, DEG BETA, BLADATO1950
 2AOE4, ROTOR2, DEG BETA, BLADE5, ROTOR2, DEG BEDATO1960
 3TA, BLADE6, ROTOR2, DEG BETA, BLADE7, ROTOR2, OEG DATO1970
 4 ' / OATO1980
 OATA PLOTN / ' TOTAL X-FORCE OATO1990
 7N C.G., LB X-FORCE FROM RIGHT WING, LB X-FORCE FOATO2000
 8FROM LEFT WING, LB X-FORCE FROM ELEVATOR, LB X-FDATO2010
 9JRCE FROM FUSELAGE, LB X-FORCE FROM RIGHT JET, LB
 A ' / DATO2030
 DATA PLOT0 / DATO2040
 A ' X-FORCE FROM LEFT/CENTER JET, LB X-FORCE FROM ROTOR1, LB OATO2050
 B X-FORCE FROM ROTOR2, LB X-FORCE FROM WEAPDN FDATE2060
 CIRE, LB X-FORCE FROM FIN, LB ' / DATO2070
 DATA PLOT0 / ' X-FORCE FROM WEIGHT, LB TOTAL Y-FORCE OATO2080
 IN C.G., LB Y-FORCE FROM FUSELAGE, LB Y-FORCE FDATE2090
 2FROM RIGHT JET, LB Y-FORCE FROM LEFT/CENTER JET, L' Y-FDATE2100
 3ORCE FROM ROTOR1, LB ' / DATO2110
 DATA PLOT0 / ' Y-FORCE FROM ROTOR2, LB DATO2120
 4 Y-FORCE FROM WEAPON FIRE, LB Y-FORCE FROM FIN, LB DATD2130
 5 Y-FORCE FROM WEIGHT, LB TOTAL Z-FORCE ON C.G.-OATO2140
 6, LB Z-FORCE FROM RIGHT WING, LB ' / DATO2150
 OATA PLOT0 / ' Z-FORCE FROM LEDATO2160

7FT WING, LB Z-FORCE FROM ELEVATOR, LB Z-FORCE FDATE02170
 8ROM FUSELAGE, LB Z-FORCE FROM RIGHT JET, LB Z-FDATE02180
 9ORCE FROM LEFT/CENTR JET, LB Z-FORCE FROM ROTORI, LB
 A // DATO2190
 DATA PLOTS / DATO2200
 A Z-FORCE FROM ROTOR2, LB Z-FORCE FROM WEAPON FIRE, LDATO2210
 BB Z-FORCE FROM WEIGHT, LB TOTAL ROLL MOM ON C.GDATE02220
 C. FT-LB ROLL MOM FROM RIGHT WING, LB DATO2220
 DATA PLOTX / ROLL MOM FROM LEFT WING, FT-LB ROLL MOM FROM EDATO22250
 1ELEVATOR, FT-LB ROLL MOM FROM FUSELAGE, FT-LB ROLL MOM DATO22260
 2FROM RIGHT JET, FT-LB ROLL MOM FROM LEFT/CENTR JET, FT-LB ROLLDATO22270
 3L MOM FROM ROTORI FORCES, FT-LB // DATO22280
 DATA PLOTU / ROLL MOM FROM ROTOR2 FORCES, FT-LDATO22290
 4R ROLL MOM FROM WEAPON FIRE, FT-LB ROLL MOM FROM FIN, FT-LB DATO22300
 5 ROLL MOM FROM ROTORI TOPOQUE, FT-LB ROLL MOM FROM ROTOR2 DATO22310
 6TORQUE, FT-LB TOTAL PITCH MOM ON C.G., FT-LB // DATO22320
 DATA PLOTV / PITCH MOM FROM ROTOR2, FT-LB // DATO22330
 7RIGHT WING, FT-LB PITCH MOM FROM LEFT WING, FT-LB PITCH MOMDATE022340
 8 FROM ELEVATOR, FT-LB PITCH MOM FROM FUSELAGE, FT-LB PITCH MOMDATE022350
 9CH MOM FROM RIGHT JET, FT-LB PITCH MOM FROM LEFT/CENTR JET, FT-DATO22360
 ALB // DATO22370
 DATA PLOTW / DATO22380
 A PITCH MOM FROM ROTORI FORCES, FT-LB PITCH MOM FROM ROTOR2 FORCEDATO22390
 BS FT-LB PITCH MOM FROM WEAPON FIRE, FT-LB PITCH MOM FROM FIN, FDATE022400
 CT-LB PITCH MOM FROM ROTORI TORQUE, FT-LB // DATO22410
 DATA PLOTX / PITCH MOM FROM ROTOR2 TORQUE, FT-LB TOTAL YAW MOM ODATO22420
 IN C.G., FT-LB YAW MOM FROM RIGHT WING, FT-LB YAW MOM FDATE022430
 2ROM LEFT WING, FT-LB YAW MOM FROM ELEVATOR, FT-LB YAWDATO22440
 3 MOM FROM FUSELAGE, FT-LB // DATO22450
 DATA PLOTY / YAW MOM FROM RIGHT JET, FT-LB DATO22460
 4 YAW MOM FROM LEFT/CENTR JET, FT-LB YAW MOM FROM ROTORI FORCES,DATE022470
 5 FT-LB YAW MOM FROM ROTOR2 FORCES, FT-LB YAW MOM FROM WEAPON FDATE022480
 6IRE, FT-LB YAW MOM FROM FIN, FT-LB // DATO22490
 DATA PLOTZ / YAW MOM FROM ROTOR2 TORQUE, FT-LB ROTORI FRODDATO22500
 7TORI TORQUE, FT-LB YAW MOM FROM ROTOR2 TORQUE, FT-LB ROTORI F/DATE022510
 8A FLAPPING MOMENT, FT-LB ROTORI LAT FLAPPING MOMENT, FT-LB ROTORIDATO22520
 9OR2 F/A FLAPPING MOMENT, FT-LB ROTOR2 LAT FLAPPING MOMENT, FT-LBDATO22530
 A // DATO22540
 DATA PLOTQ / DATO22550
 A NOT USED DATO22560
 FND DATO22570

```

BLOCK DATA
COMMON/LDISK/LOCATE(120)
COMMON/KVARTR/ KVAR(10)
COMMON /TAB/ CY41(110),CY42(99),CX41(149),CX42(120),CX43(120),
CX44(120),CX45(120),CX46(120),CX47(108)
*K(11),L(17)
DATA LOCATE/119,116,113,110,107,103,96,89,82,75,120,117,114,111,
108,104,97,90,83,75,105,100,98,93,91,86,84,79,77,72,
70,69,68,67,66,65,64,63,62,61,20,22,27,29,34,36,41,
43,48,50,3,6,9,12,15,19,26,33,40,47,2,5,8,11,14,18,
25,37,39,46,1,4,7,10,13,17,24,31,38,45,16,21,23,28,
30,35,37,42,44,49,51,52,53,54,55,56,57,58,59,60,
101,94,94,92,97,95,80,78,73,71,118,115,112,109,106,
102,95,88,81,74/
DATA KVAR/1,2,3,4,5,7,9,9,10,11/
LIFT TABLE (COMPOSITE) AIRFOIL = 64A210 JUNE 9,1967
DATA CY41/
1 0.2,0.4,0.6,0.8,1.0,1.1,1.2,1.3,1.4,1.5,1.6,
2 21.39,49.129,147.161,172.5,180.,
3 90.,
4 .228, .25, .27, .285, .308,
5 .325, 2*.395,
6 .390, .477, .518, .555, .575,
7 .585, 2*.575,
8 .560, .653, .58, .742, .75, .765,
9 .720, 2*.650,
A .750, .872, 2*.9, .833, .805,
B .760, 2*.695,
C .949, 1.095, 1.082, 1.015, .885, .835,
D .792, 2*.722,
E 1.05, 1.195, 1.17, 1.062, .912, .845,
F .810, 2*.738,
G 1.155, 1.245, 1.253, 1.1, .935, .850,
H .920, 2*.740,
I 1.28, 1.24, 1.285, 1.112, .945, .840,
J .918, 2*.738
DATA CY42/ 1.295,1.186,1.222,1.08,955,.832,
1 .809, 2*.725,
2 1.19, 1.087, 1.14, 1.038, .955, .82,
3 .79, 2*.713,
4 1.012, .977, 1.06, .991, .955, .80,
5 .77, 2*.698,
6 .8, .83, 3*.85, .71,
7 .68, 2*.64,
8 18*1.18,
9 18*-1.,
A 9*-62,
B 9*-78,
C 9*0.
DATA CY43/ 0.,2.,3.,4.,5.,5.,7.,75.,8.,85.,9.1.,
1 -180.,-175.,-170.,-165.,-160.,-140.,-120.,-110.,-100.,
2 -90.,-80.,-70.,-60.,-50.,-30.,-21.,-16.,-15.,
3 -14.,-13.,-12.,-11.,-10.,-9.,-8.,-7.,-6.,-5.,

```


I	.01113	.01126	.01132	.01138	.02525	.0595	DATA CX44/	0AT11090
J	.162	.146	.149	.173	.18	.206	4*.0105	0AT11100
1	.151	.133	.136	.161	.169	.196		0AT11110
2	4*.01025				.01475	.0252		0AT11120
3	.13	.108	.123	.143	.157	.187		0AT11130
4	4*.01				.012	.0175		0AT11140
5	.109	.079	.09	.124	.146	.177		0AT11150
6	4*.01				.0102	.013		0AT11160
7	.081	.0495	.05625	.08	.135	.1675		0AT11170
8	4*.01	.022	.025	.04	.009	.0105		0AT11180
9	.053				.123	.158		0AT11190
A	4*.01				.00825	.009		0AT11200
B	.031	.011	.01425	.024	.055	.148		0AT11210
C	4*.01	.00825	.01325	.02325	.008	.00825		0AT11220
D	.01				.0435	.1375		0AT11230
E	4*.01				2*.008			0AT11240
F	2*.009	.02175	2*.046			.107		0AT11250
G	4*.01				2*.008			0AT11260
H	.0085	.009	.062	.085	.086	.1		0AT11270
I	4*.01				2*.008			0AT11280
J	.01	.012	.0955	2*.117		.11		0AT11290
1	DATA CX45/	4*.01			.008	.0082		0AT11300
2	.016	.028	.1235	2*.146	.00825	.127		0AT11310
3	.033	.05	.139	2*.162		.009		0AT11320
4	4*.0105				.009	.144		0AT11330
5	.055	.088	.153	2*.177		.0105		0AT11340
6	.01113	.01126	.01132	.01138	.01025	.1615		0AT11350
7	.085	.11	.168	.191	.193	.179		0AT11360
8	.01175	.01200	.01213	.01225	.012	.0174		0AT11370
9	.111	.128	.183	.205	.012	.0174		0AT11380
A	.01338	.01413	.0145	.01488	.208	.195		0AT11390
B	.131	.149	.198	.22	.01475	.025		0AT11400
C	.015	.0163	.0169	.0175	.224	.213		0AT11410
D	.15	.162	.212	.234	.0185	.039		0AT11420
E	.018	.0212	.023	.0245	.239	.231		0AT11430
F	.169	.178	.227	.249	.025	.0595		0AT11440
G	.027	.032	.0345	.037	.255	.248		0AT11450
H	.191	.2	.2415	.263	.036	.0885		0AT11460
I	.072	.0855	.0938	.101	.27	.264		0AT11470
J	.213	.22	.257	.277	.0705	.131		0AT11480
1	DATA CX46/	.130	.145	.160	.286	.282		0AT11490
2	.232	.238	.271	.291	.117	.166		0AT11500
3	.166	.177	.1825	.188	.301	.299		0AT11510
4	.251	.258	.286	.306	.162	.201		0AT11520
5	.202	.209	.213	.216	2*.3165			0AT11530
6	.272	.282	.301	.32	.209	.237		0AT11540
7	4*.332				2*.332			0AT11550
8	.33	.32	2*.324		.29	.295		0AT11560
9	4*.562				2*.34			0AT11570
A	.57	.56	2*.566		.51	.52		0AT11580
B	4*1.296				2*.56			0AT11590
1	1.39	1.38	2*1.386		1.34	1.345		0AT11600
2					2*1.38			0AT11610
3								0AT11620


```

SUBROUTINE DET
COMMON /ST80/ UX,UY,UO,VO,T,A(9,2),N,NS
DOUBLE PRECISION C,UO,VO,UX,UY,T,A,XM,B,XR,YO,XO
N1=N-1
K=0
UD=1.
VO=0.
DO 57 L=1,M1
J=K+L
JN=J+N
J1=J+1
K=K+N
IF(UY.NE.0.) GO TO 1
IF(A(J,1))43,42,43
DO 44 I=J1,K
IF(A(I,1))45,44,45
CONTINUE
GO TO 113
40 JO=-UO
IM=I-J
DO 46 I=J,NS,N
IMM=I+IM
B=A(I,1)
A(I,1)=A(IMM,1)
A(IMM,1)=B
UD=UO*A(J,1)
XO=-1./A(J,1)
DO 47 I=J1,K
IF(A(I,1).NE.0.) A(I,1) = A(I,1)*XD
CONTINUE
DO 48 M=JN,NS,N
IF(A(M,1))60,80,60
MJ=M-J
DO 41 I=J1,K
IF(A(I,1))49,41,49
IC=MJ+I
A(IC,1)=A(IC,1)+A(I,1)*A(M,1)
CONTINUE
80 CONTINUE
GO TO 57
IF(A(J,1).NE.0.)OR. A(J,2).NE.0.) GO TO 16
DO 7 I=J1,K
IF(A(I,1).NE.0.)OR. A(I,2).NE.0.) GO TO 15
CONTINUE
50 TO 113
UD=-UD
VD=-VO
IM=I-J
DO 19 I=J,NS,N
IMM=I+IM
DO 19 M=1,2
B=A(I,M)
A(I,M)=A(IMM,M)
A(IMM,M)=B

```

```

DET00010
DET00020
DET00030
DET00040
DET00050
DET00060
DET00070
DET00080
DET00090
DET00100
DET00110
DET00120
DET00130
DET00140
DET00150
DET00160
DET00170
DET00180
DET00190
DET00200
DET00210
DET00220
DET00230
DET00240
DET00250
DET00260
DET00270
DET00280
DET00290
DET00300
DET00310
DET00320
DET00330
DET00340
DET00350
DET00360
DET00370
DET00380
DET00390
DET00400
DET00410
DET00420
DET00430
DET00440
DET00450
DET00460
DET00470
DET00480
DET00490
DET00500
DET00510
DET00520
DET00530
DET00540

```

DET00550
 DET00560
 DET00570
 DET00580
 DET00590
 DET00600
 DET00610
 DET00620
 DET00630
 DET00640
 DET00650
 DET00660
 DET00670
 DET00680
 DET00690
 DET00700
 DET00710
 DET00720
 DET00730
 DET00740
 DET00750
 DET00760
 DET00770
 DET00780
 DET00790
 DET00800
 DET00810
 DET00820
 DET00830
 DET00840
 DET00850
 DET00860
 DET00870
 DET00880
 DET00890
 DET00900

16 C=UD*A(J,1)-VD*A(J,2)
 VD=UD*A(J,2)+VD*A(J,1)
 UD=C
 IF(A(J,1))21,22,21
 22 XD=0.
 YD=1./A(J,2)
 GD TO 23
 21 XR=A(J,2)/ A(J,1)
 XM=(1.+XR*XR)*A(J,1)
 XD=-1./XM
 YD=XR/XM
 23 DO 25 I=J1,K
 37 B=XD*A(I,1) -YD* A(I,2)
 A(I,2)= XD*A(I,2)+YD*A(I,1)
 2 A(I,1)= B
 25 CONTINUE
 DO 81 M=JM,NS,M
 IF(A(M,1).EQ.0..AND.A(M,2) .EQ. 0.) GD TO 81
 MJ=M-J
 DO 27 I=J1,K
 IF(A(I,1).EQ.0..AND. A(I,2) .EQ. 0.) GD TO 27
 IC=MJ+I
 A(IC,1)=A(IC,1)+A(I,1)*A(M,1)-A(I,2)*A(M,2)
 A(IC,2)=A(IC,2)+A(I,1)*A(M,2)+A(I,2)*A(M,1)
 CONTINUE
 27 CONTINUE
 81 CONTINUE
 57 CONTINUE
 IF(UY)56,55,56
 113 UD=0.
 55 JO=UD*A(NS,1)
 14 VD=0.
 RETURN
 56 UD=UD*A(NS,1)-VD*A(NS,2)
 VD=UD*A(NS,2)+VD*A(NS,1)
 RETURN
 END

DISK0010
 DISK0020
 DISK0030
 DISK0040
 DISK0050
 DISK0060
 DISK0070
 DISK0080
 DISK0090
 DISK0100
 DISK0110
 DISK0120
 DISK0130
 DISK0140
 DISK0150
 DISK0160
 DISK0170
 DISK0180
 DISK0190
 DISK0200
 DISK0210
 DISK0220
 DISK0230
 DISK0240
 DISK0250
 DISK0260
 DISK0270
 DISK0280
 DISK0290
 DISK0300

```

SUBROUTINE DISK (GDISK)
  DIMENSION GDISK(120)
  DISPLAY GUST VELOCITY DISTRIBUTION ON ROTOR (IF ANY VELOCITY
  IS NON-ZERO AND IF WHOLE ROTOR IS NOT SUBJECT TO THE
  SAME VELOCITY)
  DISK1=GDISK(119)
  DD 227 J=1,120
  IF(ABS(GDISK(J)).GT.0.5.AND.GDISK(J).NE.DISK1) GO TO 228
  227 CONTINUE
  RETURN
  228 WRITE(6,229) GDISK
  RETURN
  229 FORMAT( 1H1,10X,30H GUST VELOCITIES ON ROTOR DISK, 10X,4H FWD//
  1 30X,F4.0,16X,F4.0,16X,F4.0/32X,F4.0,16X,F4.0,16X,F4.0,16X,F4.0//
  2 34X,F4.0,12X,F4.0,12X,F4.0/36X,F4.0,10X,F4.0,10X,F4.0,10X,F4.0//
  3 38X,F4.0, 8X,F4.0, 8X,F4.0/10X,F4.0,26X,F4.0, 6X,F4.0,
  4 6X,F4.0,76X,F4.0/14X,F4.0,68X,F4.0/18X,F4.0,20X,F4.0,
  5 4X,F4.0,4X,F4.0,20X,F4.0/22X,F4.0,52X,F4.0/26X,F4.0,
  6 14X,F4.0, 2X,F4.0, 2X,F4.0,14X,F4.0/30X,F4.0,36X,F4.0/
  7 34X,F4.0, 8X,3F4.0,8X,F4.0/38X,F4.0,22X,F4.0,42X,5F4.0/
  8 42X,2F8.0/10X,10F4.0,4X,10F4.0/42X,2F8.0/
  A 30X,F4.0,36X,F4.0/28X,F4.0,14X,F4.0, 2X,F4.0, 2X,F4.0,
  B 14X,F4.0/22X,F4.0,52X,F4.0/18X,F4.0,20X,F4.0, 4X,F4.0,
  C 4X,F4.0,20X,F4.0/14X,F4.0,68X,F4.0/12X,F4.0,26X,F4.0,
  D 6X,F4.0, 6X,F4.0,26X,F4.0/38X,F4.0, 8X,F4.0, 8X,F4.0//
  E 36X,F4.0,10X,F4.0,10X,F4.0/34X,F4.0,12X,F4.0,12X,F4.0//
  F 32X,F4.0,14X,F4.0,14X,F4.0/30X,F4.0,16X,F4.0,16X,F4.0//
  G 50X,4H AFT)
  END
  
```

00GS0010
00GS0020
00GS0030
00GS0040
00GS0050
00GS0060
00GS0070

SUBROUTINE DOGS (RX,RY,RZ,FX,FY,FZ,ROLL,PITCH,YAW)
 COMPUTE VECTOR CROSS PRODUCT L = R X F
 ROLL=RY*FZ-RZ*FY
 PITCH=RZ*FX-RX*FZ
 YAW=RX*FY-RY*FX
 RETURN
 END

C

```

SURROUTINE DOROT (N)
COMMON /ANDOIT/ A1,B1,XK,XY,VI2,VI4,APDM,APFM,ARDM,ARFM,
1 AYFM,ROTJ,XK43,XLIM,CBFAC,
2 GOISK(12),NPSI,TAMA1,TANB1,
3 TANT1,TANT2,DCAF,XK,IPRINT,NORAOI,
4 SHEAR(12),SHEARD(12),SHEARR(12),
5 XMOML(12),XMOMO(12)
6
COMMON /ROMAN/
1 ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
2 T,PCC(2),CDSE(7,7,2),BETAM(2),BETAX(2),BETAZ(2),
3 AIB(2),APDD,ARDD,AYOD,AIR(2),
4 DPSI(12,2),DTRR,NPSI(2),ZZTR,
5 BETAD(12,2),BNPSI(2),
6 COND?,CHAXV,RATE1,RATE2,STOP?,
7 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
8 GMAXV?,CHAXV?,GUSTYP,HMPSIR(2),
9 HUBKPS,HUBKRS,HUBTPS,HUBTRS,
0 KONFIG,LANGTH1,PILGHI,PSIREF(2),
1 START2,XMOMLI(12,2),
2 R(2),OR(2),T1(2),
3 T2(2),TZR(2),XMA(2),
4 XMB(2),AIBP(2),AIBR(2),
5 APDR(2),ARDR(2),PSID(2),
6 XSTAH(2),YSTAH(2),
7 HUBKPR(2),HUBKRR(2)
8
COMMON /MANARO/
1 ,AZETAR(2),YZETAR(2)
2 I,V,IND,MWAG,APRMT,ARBMT,AVBMT,BETAD(2),TDELT,
3 BETAE(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
4 VGUSTM,VGUSTF,GFMD,GLAT,GVERT,
5 VXB,VZB,APD,VYB,ARD,AYD,
6 COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
7 APE,ARE,AIM,BIM,ALTR,BITR,
8 XAR(2),YAR(2),ZAR(2),
9 VIR(2),ZETAR(2),MFORCE(2),
0 THRUST(2),TORQUE(2),YFORCE(2)
1 J,W,ITM,VHS(2),LINK,OELE,VROT(2),
2 VSNO,YFIN(2),ZFEL(2),AIBAL(2),
3 B1BAL(2),COND1,SWING,PILGH2,PWGELL,
4 B(2),PHOM(2),RMOM(2)
5
COMMON /ROSTAR/
1 AM(2),CT,PI,XB(2),ALT,ADR(2),EXM(2),
2 NXR(2),RBH(2),SWC(2),UHS,CDHB(2),LROT(2),
3 RAI(2),RTRP(2),TATR(14),CDNEK(2),OCAFR(2),FVIND,
4 NWARD,
5
6
7 SWKR1(2),SWKR2(2),TIPIB(2),TIPIB(2),
8 TWISTI(2,2),CLRADK(2),DELTA3(2),
9 LAMBDA(2),UPGUST,URGUST,UTGUST,MROTOR,
0 ER(2),ERX(2),
1 XLIMAX(2),XLIMIN(2)
2
COMMON /TOPLOT/
1 AH(3),AL(3),EXIT,ICOM(49),IPSN,
2 NPART,NVARA,NVARB,NVARC,NSCALE,
3 ,NVAR5,NPRINT,NTIME
4
COMMON /FORY/
1 Y(4,15D)
2
COMMON /LOISK/LOCATE(12D)
3
DATA TMOPI,045,0105,0255,0315 /6,2831853,78539816,1.8325957,

```

```

1 4.4505896,5.4977871/
DIMENSION HUBKS(2,2),JFLAP(7)
EQUIVALENCE (HUBKS(1,1),HUBKPS)
REAL LAM,MRCP,MRCPSB,MRCPCB,LENGTH1,LAMBDA
REAL NOPSIZ
LOGICAL NRIGID
NRIGID=.TRUE.
IF(BETAX(N).EQ.BETAN(N)) NRIGID=.FALSE.
IJ = 1
ADXMOM = 0.0
PSIDSQ = PSID(N)**2
NPSIZ=2./NOPSI
IF(LINK.LT.4) GO TO 9
DO 10 L=1,NOPSI
JFLAP(L)=0
IF(NRIGID) GO TO 5
BETAL(N)=BETAZ(N)
BETAD(L,N)=BETAZD(N)
GO TO 10
5 CONTINUE
IF(BETA(L,N).LT.BETAN(N)) GO TO 2
IF(BETA(L,N).LT.BETAX(N)) GO TO 10
JFLAP(L)=1
DBETA=BETA(N)-BETA(L,N)
DBETAD=0.
IF(BETAD(L,N).GT.0.) DBETAD=-BETAD(L,N)
GO TO 3
2 CONTINUE
JFLAP(L)=-1
DBETA=BETAN(N)-BETA(L,N)
DBETAD=0.
IF(BETAD(L,N).LT.0.) DBETAD=-BETAD(L,N)
GO 4 K=1,NOPSI
BETAK(N)=CDBE(K,L,N)*DBETA+BETA(K,N)
BETAD(K,N)=CDBE(K,L,N)*DBETAD+BETAD(K,N)
4 CONTINUE
10 CONTINUE
9 CONTINUE
DO 40 L=1,NOPSI
PSIR=PSIREF(N)+DPSI(L,N)
IF(PSIR.GE.TWOPI) PSIR=PSIR-TWOPI
VXOR=VIR(N)
IF((PSIR.GT.D45.AND.PSIR.LT.D105).OR.
1 (PSIR.GT.D255.AND.PSIR.LT.D315))
2 VXOR=VXOR+VX*PSIN(6.*(PSIR-D45))
SPSI=SIN(PSIR)
CPSI=COS(PSIR)
IF(LINK.EQ.4) GO TO 27
IF(NRIGID) GO TO 26
BETAL(N)=BETAZ(N)
BETAD(L,N)=BETAZD(N)
GO TO 27
26 CONTINUE

```

```

DOR00550
DOR00560
DOR00570
DOR00580
DOR00590
DOR00600
DOR00610
DOR00620
DOR00630
DOR00640
DOR00650
DOR00660
DOR00670
DOR00680
DOR00690
DOR00700
DOR00710
DOR00720
DOR00730
DOR00740
DOR00750
DOR00760
DOR00770
DOR00780
DOR00790
DOR00800
DOR00810
DOR00820
DOR00830
DOR00840
DOR00850
DOR00860
DOR00870
DOR00880
DOR00890
DOR00900
DOR00910
DOR00920
DOR00930
DOR00940
DOR00950
DOR00960
DOR00970
DOR00980
DOR00990
DOR01000
DOR01010
DOR01020
DOR01030
DOR01040
DOR01050
DOR01060
DOR01070
DOR01080

```

```

BETA(L,N)=BETAZ(N)-ATAN(TANAI*CPST1+TANB1*SPST1)
BETAD(L,N)=-COS(BETAZ(N)-BETA(L,N))*2*(PFAC*CPST1+RFAC*SPST1)
27 CONTINUE
SBFAC=SPST1*COS(APFM)*SIN(ARFM)+CPST1*SIN(APFM)
SBETA=SIN(BETA(L,N)+BETAZ(N))
CBETA=COS(BETA(L,N)+BETAZ(N))
CBOR=OR(N)*CBETA
%DDTR=R(N)*BETAD(L,N)-ARDS*SPST1-APDS*CPST1
BETA1=BETA(L,N)-BETAZ(N)
TZPDT=TZ(N)-ATAN(TANAI*SPST1+TANTZ*CPST1)-BETA1*DELTA3(N)
SHEAR(L1)=0.
SHEAR(L2)=0.
SHEAR(L3)=0.
XMOML(L1)=0.
XMOML(L2)=0.
XMOML(L3)=0.
XKLAM= 1.333333+XK43*CPST1
%RCP=VXS(N)*CPST1-VYS(N)*SPST1
%RSP=VXS(N)*SPST1+VYS(N)*CPST1
%RCPB=MRCP*SBETA
%RCPB=MRCP*CBETA
STORE=1.
JLOCL=(PSIR+D45)/.52359878
IF(JLOCL.GT.12) JLOCL=1
JLOC=10*JLOCL-9
IF(IPRINT.EQ.0) GO TO 55
PSI=PSIR*OTRP
IF(IJ.EQ.2) GO TO 53
IJ = 2
WRITE (6,50)
50 FORMAT('1')
GO TO 52
53 WRITE (6,51)
51 FORMAT (1H ,//)
IJ = 1
52 WRITE (6,424) PSI,VXS(N),VYS(N),VZS(N),XK,SBETA,CBETA,CBOR
IF(CLRADK(N).LT.0.) GO TO 55
IJ=1
WRITE (6,425)
55 XR=1.+XB(N)
%O 30 K=1,NDRADL
XR=XR-XB(N)
IF(XR.LT..7) VXDR=VIR(N)
LAM=LAMBDA(N)+VXDR*(1.-XKLAM*XR)
RR=XR*(N)
IF(GUSTYP.LT.1.) GO TO 13
AGUSTR=0.
HGUSTR=0.
VGUSTR=0.
VVGUSTR=0.
XRR=-RR*CPST1
YRR=RR*SPST1*ROTJ
CALL RATS (XRR,YRR,0.,AYFM,APFM,ARFM,STA,8L,TV,1)
XSTARE=SQRT((XSTAH(N)+STA)**2+(YSTAH(N)+8L)**2)-XGUST
IF(XSTARE.LE.0.) GO TO 600

```

```

DDR01090
DDR01100
DDR01110
DDR01120
DDR01130
DDR01140
DDR01150
DDR01160
DDR01170
DDR01180
DDR01190
DDR01200
DDR01210
DDR01220
DDR01230
DDR01240
DDR01250
DDR01260
DDR01270
DDR01280
DDR01290
DDR01300
DDR01310
DDR01320
DDR01330
DDR01340
DDR01350
DDR01360
DDR01370
DDR01380
DDR01390
DDR01400
DDR01410
DDR01420
DDR01430
DDR01440
DDR01450
DDR01460
DDR01470
DDR01480
DDR01490
DDR01500
DDR01510
DDR01520
DDR01530
DDR01540
DDR01550
DDR01560
DDR01570
DDR01580
DDR01590
DDR01600
DDR01610
DDR01620

```

```

IF(GUSTYP.EQ.1).O.DR.GUSTYP.EQ.12.) GO TO 11
IF(XSTARE.LE.START2) GO TO 601
IF(XSTARE.GE.STOP2) GO TO 602
AGUSTR=GMAXV3+XSTARE*RATEZ
GO TO 605
601 IF(XSTARE.GE.LMGTH1) GO TO 604
AGUSTR=XSTARE*RATE1
GO TO 605
604 AGUSTR=GMAXV1
GO TO 605
605 AGUSTR=GMAXV
605 IF(GUSTYP.EQ.11.) GO TO 606
GO TO 607
11 IF(XSTARE.LE.START2) GO TO 608
IF(XSTARE.GE.STOP2) GO TO 600
AGUSTR=GMAXV2*(SIN(XSTARE-START2)*PILGH2)**2
GO TO 612
608 IF(XSTARE.GE.LMGTH1) GO TO 600
AGUSTR=GMAXV1*(SIN(XSTARE*PILGH1)**2
612 IF(GUSTYP.EQ.12.) GO TO 606
607 CONTINUE
CALL RATS (O.O.O.O,AGUSTR,AYFM,APFM,ARFM,HGUSTR,YGUSTR,VGUSTR,-1)
GO TO 609
606 CONTINUE
CALL RATS (AGUSTR,O.O.O.O,AYFM,APFM,ARFM,HGUSTR,YGUSTR,VGUSTR,-1)
609 YGUSTR=YGUSTR*ROTJ
600 IF(STORE.LE.O.) GO TO 16
GOISK(LOCATE(JLOC),-AGUSTR
JLOC=JLOC+1
16 STORE=-STORE
UGUSTR=HGUST*CP*SI-YGUSTR*SP*SI
UPGUST=UGUST*SBETA-VGUSTR*CBETA
UTGUST=HGUST*SP*SI+YGUSTR*CP*SI
URGUST=UGUST*CBETA+VGUSTR*SBETA
13 CONTINUE
UP=LAM*CBETA-XR*DDOTR-MRC*PSB+UPGUST
UT=XR*CBOR+MR*SP-UTGUST
UR=URGUST-LAM*SBETA-MRC*PCB
TZTM=TZPOT-TWIST*(K,N)
UIPSO=UR**2+UT**2
UIP=SQRT(UIPSO)
U=SQRT(U**2+UIPSO)
GAMMA=ABS(ATAN(UT/UR))
SGAM=SIN(GAMMA)**2
CGAM=1.-SGAM
IF(CLRAD(KIN).GE.O.) GO TO 17
SGAM=1.
CGAM=C.
U=SQRT(U**2+UT**2)
17 CONTINUE
CGAMCT=CGAM*U*ABS(COS(TZTM))
UPT=UP*SGAM
UPR=UP*CGAM
PHI=0.

```

```

DDRO1630
DDRO1640
DDRO1650
DDRO1660
DDRO1670
DDRO1680
DDRO1690
DDRO1700
DDRO1710
DDRO1720
DDRO1730
DDRO1740
DDRO1750
DDRO1760
DDRO1770
DDRO1780
DDRO1790
DDRO1800
DDRO1810
DDRO1820
DDRO1830
DDRO1840
DDRO1850
DDRO1860
DDRO1870
DDRO1880
DDRO1890
DDRO1900
DDRO1910
DDRO1920
DDRO1930
DDRO1940
DDRO1950
DDRO1960
DDRO1970
DDRO1980
DDRO1990
DDRO2000
DDRO2010
DDRO2020
DDRO2030
DDRO2040
DDRO2050
DDRO2060
DDRO2070
DDRO2080
DDRO2090
DDRO2100
DDRO2110
DDRO2120
DDRO2130
DDRO2140
DDRO2150
DDRO2160

```

```

IF(UT.NE.O..OR.UPT.NE.O.) PHI=ATAN2(UPT,UT)
USGAM=USGAM
XMACN=USGAM*VSN0
XMACR=USGAM*VSN0
PHIR=0.
I(ELUR.NE.O..OR.UPT.NE.O.) PHIR=ATAN2(UPT,UR)
I(FRR.GT.EXH(N)) GO TO 14
ALF=0.
CL=0.
CD=C*MB(N)
CLR=0.
CDR=CD
GO TO 15
14 CONTINUE
ALF=TZTM*PHI
CALL CLCD (ALF,CL,CD,XMACN,EXIT,N)
I(EXIT.NE.O.) RETURN
I(CLRAK(N).GE.O.) CALL CLCD (PHIR,CLR,CDR,XMACR,EXIT,N)
I(EXIT.NE.O.) RETURN
CLR=CLR*CLRAK(N)
15 CONTINUE
ALDADL=USGAM*(CL*UT+CD*UPT)+CGAMCT*(CLR*UR+CDR*UPR)
ALDADO=USGAM*(CD*UT-CL*UPT)
ALOADR=CGAMCT*(CDR*UR-CLR*UPR)
ALDLR=ALOADL*RR
ALDDR=ALOADD*RR
I(K.NE.2) GO TO 20
SHEAR(L)=TIP38(N)*SHEAR(L)+TIP18(N)*ALOADL
SHEAR(DL)=.375*SHEAR(DL)+.125*ALOADD
SHEAR(LI)=.375*SHEAR(LI)+.125*ALDADR
XMOM(L)=TIP38(N)*XMOM(L)+TIP18(N)*ALDLR
XMOM(DL)=.375*XMOM(DL)+.125*ALDDR
20 SHEAR(LI)=SHEAR(LI)+ALOADL
SHEAR(DLI)=SHEAR(DLI)+ALOADD
SHEAR(LI)=SHEAR(LI)+ALOADR
XMOM(LI)=XMOM(LI)+ALDLR
XMOM(DL)=XMOM(DL)+ALDDR
I(IPRINT.EQ.O) GO TO 30
PHI=PHI*DTTR
ALF=ALF*DTTR
WRITE (6,407) XR,PHI,ALF,CL,CD,XMACN,VXOR,LAM,UT,UP
I(CLRAK(N).LT.O.) GO TO 30
GAMMA=GAMMA*DTTR
PHIR=PHIR*DTTR
WRITE (6,408) GAMMA,PHIR,CLR,CDR,XMACR,UR,UPR,UPT
30 CONTINUE
XMOM(L)=XMOM(L)+HMPSIR(N)
BMOM=(HUBKPR(N)*CPSI**2+HUBKRR(N)*SPSI**2)*BETA1*NOPSI2
PMOM(N)=PMOM(N)-BMOM*CPSI
RMOM(N)=RMOM(N)-BMOM*SPSI
AMFAC=(CBFAC*CBETA+SRFAC*BETA)*NOPSI2
XMOM=XMOM(L)-BMOM*AM(N)*AMFAC
CBETA2=(CBETA+HUBKS(1,N))*NOPSI2
XMOM1=CBETA2*(ARDM*CPSI-APDM*SPSI)*CBETA

```

```

DOR02170
DOR02180
DOR02190
DOR02200
DOR02210
DOR02220
DOR02230
DOR02240
DOR02250
DOR02260
DOR02270
DOR02280
DOR02290
DOR02300
DOR02310
DOR02320
DOR02330
DOR02340
DOR02350
DOR02360
DOR02370
DOR02380
DOR02390
DOR02400
DOR02410
DOR02420
DOR02430
DOR02440
DOR02450
DOR02460
DOR02470
DOR02480
DOR02490
DOR02500
DOR02510
DOR02520
DOR02530
DOR02540
DOR02550
DOR02560
DOR02570
DOR02580
DOR02590
DOR02600
DOR02610
DOR02620
DOR02630
DOR02640
DOR02650
DOR02660
DOR02670
DOR02680
DOR02690
DOR02700

```

```

XMOMLI(L,N)=XMOH*RAI(B(N))+XMOH1-CBETA2*S8BETA*PSIDSQ
XMOH2=XMOH*XMOH1+AIB(N)
XMA(N)=XMA(N)+XMOH2*SPSI
XMB(N)=XMB(N)+XMOH2*CPST
TORQUE(N)=TORQUE(N)+XMOH(L)
THRUST(N)=THRUST(N)+SHEAR(L)*CBETA-SHEAR(L)*S8BETA
SHL SRC=SHEAR(L)*S8BETA+SHEAR(L)*CBETA
YFORCE(N)=YFORCE(N)-SHEAR(L)*CPST-SHL SRC*SPSI
HFORCE(N)=HFORCE(N)+SHEAR(L)*SPST-SHL SRC*CPST
ADXMOM = ADXMOM +XMOH(L)
IF(NRIGID) GO TO 40
XMOBH=XMOMLI(L,N)*RBH(N)
PHO4(N)=PHO(N)+XMOBH*CPST
PMOM(N)=PMOM(N)+XMOBH*SPST
XMOMLI(L,N)=0.
40 CONTINUE
OSQI=PSIDSQ*AIB(N)
ADXMOM=ADXMOM/NOPSI
DO 41 K=1,3
CR0=COS(BETA0(N))
SR0=SIN(BETA0(N))
CB0H=CB0+HUBKS(1,N)
FBE=CONEK(N)*BETA(N)-ADXMOM*CR0H*S80*OSQI
FPBF=CONEK(N)+OSQI*(CB0H*CB0-S80**2)
RETAE(N)=BETA(N)-FBE/SPRE
BETA0(N)=BETA(N)+BETA(N)
41 CONTINUE
IF(LINK.LT.4) RETURN
DO 61 L=1,NOPSI
Y(L,7*N+L+99)=DOTX(COSE(1,L,N),1,XMOMLI(1,N),1,NOPSI)
61 CONTINUE
IF(.NOT.NRIGID) RETURN
DO 62 L=1,NOPSI
PSIR=PSIREF(N)+OPSI(L,N)
XMOBH=Y(I,7*N+L+99)*RBH(N)
PHO4(N)=PHO(N)+XMOBH*COS(PSIR)
PMOM(N)=PMOM(N)+XMOBH*SIN(PSIR)
XMOMLI(L,N)=0.
JFLAP(L)=10
62 CONTINUE
DO 63 L=1,NOPSI
Y(I,7*N+L+99)=DOTX(COSE(1,L,N),1,XMOMLI(1,N),1,NOPSI)
IF(JFLAP(L).NE.10) GO TO 63
PSIR=PSIREF(N)+DPSI(L,N)
XMOBH=Y(I,7*N+L+99)*RBH(N)
PHO(N)=PHO(N)+XMOBH*COS(PSIR)
PMOM(N)=PMOM(N)+XMOBH*SIN(PSIR)
Y(I,7*N+L+99)=0.
63 CONTINUE
RETURN
407 FORMAT (6X,10F12.5)
408 FORMAT (24X,8F12.5)
424 FORMAT (12X, , AZIMUTH , U-SHAFT , V-SHAFT , W-SHAFT

```

```

DOOR2710
DOOR2720
DOOR2730
DOOR2740
DOOR2750
DOOR2760
DOOR2770
DOOR2780
DOOR2790
DOOR2800
DOOR2810
DOOR2820
DOOR2830
DOOR2840
DOOR2850
DOOR2860
DOOR2870
DOOR2880
DOOR2890
DOOR2900
DOOR2910
DOOR2920
DOOR2930
DOOR2940
DOOR2950
DOOR2960
DOOR2970
DOOR2980
DOOR2990
DOOR3000
DOOR3010
DOOR3020
DOOR3030
DOOR3040
DOOR3050
DOOR3060
DOOR3070
DOOR3080
DOOR3090
DOOR3100
DOOR3110
DOOR3120
DOOR3130
DOOR3140
DOOR3150
DOOR3160
DOOR3170
DOOR3180
DOOR3190
DOOR3200
DOOR3210
DOOR3220
DOOR3230
DOOR3240

```

DDRD3250
DDRD3260
CDDRD3270
DDRD3280
DDRD3290
DDRD3300
DDRD3310

UP'///
CL
CL
UPT'///

BETA DOT'///
ALPHA
UT
PHI
UPR
UPT'///

COS(BETA)
PHI
LOCAL VI LOC.
GAMMA
UR

SIN(BETA)
PHI
LOCAL VI LOC.
GAMMA
UR

XK
12X,8F12.5/1M0,
9X, 'RAD,STA.
MACH
MACH
MACH

1
2
3
4D
625
1CD
END

FORMAT (13X,'RADIAL FLOW
UR
MACH

```

SUBROUTINE ELEC (GAIN)
COMMON /TRONIC/ UU(6),VV(6),TAU(22),DAMP(22),NUMRTS,GAINB,
INDEX,STGAIN(6),TSTAR,COELTD,SLOT(3,9)
1 GAIN=1
IX=INC
DO 20 IX=IX,TS
U=UU(I)
V=VV(I)
IF(V.EQ.0.) GO TO 15
IF(V.NE.-VV(I+1)) GO TO 18
Z=1./(U**2+V**2)
TAU(I)=Z
DAMP(I)=-2.*Z*U
GAIN=GAIN/Z
GO TO 20
15 CONTINUE
DAMP(I)=-1./U
GAIN=-GAIN*U
GO TO 19
18 CONTINUE
DAMP(I)=0.
19 CONTINUE
TAU(I)=0.
20 CONTINUE
IF(NUMRTS.GE.3) RETURN
IX=IX+1
TAU(I)=0.
DAMP(I)=0.
UU(3)=0.
VV(3)=0.
RETURN
END

```

```

ELEC0010
ELEC0020
ELEC0030
ELEC0040
ELEC0050
ELEC0060
ELEC0070
ELEC0080
ELEC0090
ELEC0100
ELEC0110
ELEC0120
ELEC0130
ELEC0140
ELEC0150
ELEC0160
ELEC0170
ELEC0180
ELEC0190
ELEC0200
ELEC0210
ELEC0220
ELEC0230
ELEC0240
ELEC0250
ELEC0260
ELEC0270
ELEC0280
ELEC0290
ELEC0300
ELEC0310
ELEC0320
ELEC0330

```

SUBROUTINE GUST (J)
COMMON /STAMAN/
1 HL(2),XX,YY,AY1,GOV,KPD,OPC,000,
2 RIY,APBG,ARBG,ASEP,AYBG,BMTC,
3 RC,BWTK,RMTM,CGBL,DPIX,DPIZ,
4 FMPT(2),R550,ALERT,AYDMX,DELT2,
5 DPIX,DTBWT,DMLCG,MDLST,MGUST,
6 HLTR1,HLTR2,ITORS,KTCR,OMEGM,
7 PCDEL,OMRSA,RMASS,TRALT,TWOPI,VGUST,
8 ISTOP,XAGUN,XAPYL,XARSP(2),YAGUN,
9 YARSP(2),YGUST,ZAGUN,ZAPYL,ZARSP(2),
10 DELTZR,DSTAG,ETMAST,GPRELD,HLPLYD,
11 IBRAKE,OMEGMD,ORRAKE,BETAZS(2),
12 PCGOEN,PCGMX,PCRATE,PJ1DTR,RDELT1,
13 RDELT2,RIITORS,TRIIND2
COMMON /MANAL/
1 O,AP,PEL,OMG,TZM,TIM,T2M,
2 TZT,T1T,T2T,ALEL,CZET,PSDD,
3 SZET,TAXL,TAXR,XAWG,XLNK(16),ZAMG,
4 ALCYP,ALFIN,ALLWG,ALRWG,CDELE,CDFIN,
5 CDLWG,CDRWG,CLELE,CLFIN,CLLWG,CLRWG,CHING,
6 CYCRI,CYCR2,CZET4,CZET6,CZET9,RANGE,
7 SZET5,SZET7,SZET8,WCOL,XAELE,XAFIN,
8 XAFUS,XAJET,YAFIN,ZAELE,ZAFIN,ZAFUS,
9 YAELE,YAFUS,YALWG,YARWG,YALJET,YARJET,
10 ZAJET,ALECR1,ALGFPD,BOTTOM,CZET11,
11 CZET12,CZET13,EIZETA,HALFPI,SZET10,
12 XAPYLD,YGUSTW,ZAPYLD,ZFLWGI,ZFRWGI
13 TZMS,TIMS,T2MS,TZTS,T1TS,T2TS,
14 CLOCK,FLOCK,XLOCK,XCLOCK
COMMON /ROMAN/
1 ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
2 T,PCC(2),COSE(7,7,2),BETAM(2),BETAX(2),BETAZ(2),
3 AIB(2),APDD,AROD,AYDD,AIR(2),
4 OPSI(12,2),OTRR,NPSI(2),ZZTR,
5 BETAD(12,2),BNPSI(2),
6 COND2,GMAXV,RATE1,RATE2,STOP2,
7 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
8 GMAXV2,GMAXV3,GUSTYP,HNPSIR(2),
9 HUBKPS,HUBKRS,HUBTPS,HUBTRS,
10 KDNFIG,LNGTHI,PILGHI,PSIREF(2),
11 START2,XMOMLI(12,2),
12 RM,RTR,ORM,ORTR,TIMT,T1TT,
13 T2MT,T2TT,TZMT,TZTT,XMAL,XMAIT,
14 XMB1,XMB17,AIBPM,AIBPT,AIBRM,AIBRT,
15 APTD,APTD,ARTD,ARTD,PSD,PSDT,
16 XSTAHM,XSTAHM,YSTAHM,YSTAHM,
17 HUBKP,HUBKTP,HUBKR,HUBKTR
18 ,AZETA,AZETAT,VZETA,VZETAT
19 I,V,IND,MNAG,APRMT,ARBMT,AYBMT,BETAO(2),TDELT,
20 RETAE(2),HGUSTE,NGUSTF,NGUSTW,VGUSTE,
21 VGUSTW,YGUSTF,GFWD,GLAT,GVERT,
22 VXB,VZB,APD,VYB,ARD,AYD,
23 COLSTK,CYSTKI,CYSTK2,PEDAL,AYE,
24 APE,ARE,AIM,B1M,A1TR,B1TR,
25 XAR(2),YAR(2),ZAR(2),
26 VIMR,VITR,ZETA,ZETATR,HMR,HTR,
27

GUST0010
GUST0020
GUST0030
GUST0040
GUST0050
GUST0060
GUST0070
GUST0080
GUST0090
GUST0100
GUST0110
GUST0120
GUST0130
GUST0140
GUST0150
GUST0160
GUST0170
GUST0180
GUST0190
GUST0200
GUST0210
GUST0220
GUST0230
GUST0240
GUST0250
GUST0260
GUST0270
GUST0280
GUST0290
GUST0300
GUST0310
GUST0320
GUST0330
GUST0340
GUST0350
GUST0360
GUST0370
GUST0380
GUST0390
GUST0400
GUST0410
GUST0420
GUST0430
GUST0440
GUST0450
GUST0460
GUST0470
GUST0480
GUST0490
GUST0500
GUST0510
GUST0520
GUST0530
GUST0540

```

      THR, TTR, QMX, OTR, YMR, YTRF
      REAL LNGTHI
      DIMENSION XSTA(7), AGUST(7)
      XSTA(1)=SORT(XX**2+YY**2)-XGUST
      CALL RATS (XAR(1), YAR(1), ZAR(1), AYE, APE, ARE, STA, BL, TV, 1)
      XSTAHM=XX+STA
      YSTAHM=YY+BL
      CALL RATS (XAR(2), YAR(2), ZAR(2), AYE, APE, ARE, STA, BL, TV, 1)
      XSTAHT=XX+STA
      YSTAHT=YY+BL
      CALL RATS (XAFIN, YAFIN, ZAFIN, AYE, APE, ARE, STA, BL, TV, 1)
      XSTA(2)=SORT(XX+STA)**2+(YY+BL)**2)-XGUST
      CALL RATS (XAELE, O, ZAELE, AYE, APF, ARE, STA, BL, TV, 1)
      XSTA(3)=SORT(XX+STA)**2+(YY+BL)**2)-XGUST
      CALL RATS (XANG, O, ZANG, AYE, APE, ARE, STA, BL, TV, 1)
      XSTAHM= SORT(XX+STA)**2+(YY+BL)**2)-XGUST
      K=7
      IF(OMG.LT.Q) K=4
      DO 208 M=1,4
      AGUST(M)=0.
      AGUST(M+3)=0.
      BILL=M
      IF(OMG.LT.Q) BILL=2.
      XSTA(M+3)=XSTAHM+(.5-.25*BILL)*CWING
      GUSTVP=J
      IF(J.EO.10.DR.J.EO.12) GO TO 224
      DO 207 M=1,K
      IF(XSTA(M).GE.LNGTHI) GO TO 100
      IF(XSTA(M).LE.O.) GO TO 207
      AGUST(M)=XSTA(M)*RATE1
      GO TO 207
100 IF(XSTA(M).GE.STOP2) GO TO 101
      IF(XSTA(M).LE.START2) GO TO 102
      AGUST(M)=GMAXV3+XSTA(M)*RATE2
      GO TO 207
101 AGUST(M)=GMAXV
      GO TO 207
102 AGUST(M)=GMAXV1
      207 CONTINUE
      GO TO 232
224 DO 206 M=1,K
      IF(XSTA(M).GT.O.O.AND.XSTA(M).LT.LNGTHI)
      1 AGUST(M)=GMAXV1*(SIN(XSTA(M)*PI/LGHI))**2
      IF(XSTA(M).GT.START2.AND.XSTA(M).LT.STOP2)
      1 AGUST(M)=GMAXV2*(SIN(XSTA(M)-START2)*PI/LGHI))**2
      206 CONTINUE
      232 RGUSTM=AGUST(4)
      IF(K.EO.7) RGUSTM=.25*(AGUST(4)+AGUST(5)+AGUST(6)+AGUST(7))
      IF(J.GT.10) GO TO 233
      CALL PATS (O.O.O.,BGUSTM,AYE, APE, ARE, HGUSTM, YGUSTM, VGUSTM, -1)
      CALL PATS (O.O.O.,AGUST(3), AYE, APE, ARE, HGUSTE, TV, VGUSTE, -1)
      CALL RATS (O.O.O.,AGUST(2), AYE, APE, ARE, HGUSTF, YGUSTF, TV, -1)
      CALL PATS (O.O.O.,AGUST(1), AYE, APE, ARE, HGUST, YGUST, VGUST, -1)
      RETURN
GUST0550
GUST0560
GUST0570
GUST0580
GUST0590
GUST0600
GUST0610
GUST0620
GUST0630
GUST0640
GUST0650
GUST0660
GUST0670
GUST0680
GUST0690
GUST0700
GUST0710
GUST0720
GUST0730
GUST0740
GUST0750
GUST0760
GUST0770
GUST0780
GUST0790
GUST0800
GUST0810
GUST0820
GUST0830
GUST0840
GUST0850
GUST0860
GUST0870
GUST0880
GUST0890
GUST0900
GUST0910
GUST0920
GUST0930
GUST0940
GUST0950
GUST0960
GUST0970
GUST0980
GUST0990
GUST1000
GUST1010
GUST1020
GUST1030
GUST1040
GUST1050
GUST1060
GUST1070
GUST1080

```

GUSTI090
GUSTI100
GUSTI110
GUSTI120
GUSTI130
GUSTI140

233 CALL RATS (BGUSTM,O.,O.,,AYE,APF,ARE,HGUSTM,YGUSTM,YGUSTM,-1)
CALL RATS (AGUST(3),O.,O.,,AYE,APF,ARE,HGUSTE,TV,VGUSTE,-1)
CALL RATS (AGUST(2),O.,O.,,AYE,APF,ARE,HGUSTF,YGUSTF,TV,-1)
CALL RATS (AGUST(1),O.,O.,,AYF,APF,ARE,HGUST,YGUST,YGUST,-1)
RETURN
END

```

SUBROUTINE IMIT
COMMON /FORCE/ A(71)
COMMON /STRIMA/ AY,VM,AGM,DT1(2),DT2(2),IXZ,
1 OMR,XXD,YYD,ZZD,ALGF,APFP,AYFP,
2 CGML,COLL(6),CYCF(3),CYCL(3),
3 DIST,KCIT(20),PEDA(3),QMAX,
4 QMRS,TIM,TMAX,KCIT(20,6),ALGEZ,
5 ALGE1,ALGE2,CGSTA,CPMIC,DIXIZ,
6 DIYIX,DIZIY,DTZMT,DTZM1,DTZT1,FKTS,
7 HUBKM(2,2),HUBKI(2,2),
8 KREAD,PIU30,TSTAR(14),ZMAX2,ZMAX3,
9 ASECDL,CYPMIC,GFARAT,PSD550,
COMMON /STAMAN/ HL(2),XX,YY,AY1,GOV,KPD,OPC,OOO,
1 RIY,APBG,ARBG,ASEP,AYBG,BWTC,
2 RC,BWTK,BWTM,CGAL,DPIX,DPIZ,
3 FHPT(2),R950,ALERT,AYDNX,DELT2,
4 DPIXZ,DTBMT,DMLCG,MDELT,HGUST,
5 HLTR1,HLTR2,ITORS,KTCR,DMEGM,
6 PCDEL,OMRSA,RMASS,TRALT,TWDPI,VGUST,
7 ISTOP,XAGUN,XAPYL,XARSP(2),YAGUN,
8 YARSP(2),YGUST,ZAGUN,ZAPYL,ZARSP(2),
9 DELT2R,OSTACG,EIMAST,GPRELD,MLPYLD,
A I BRAKE,OMEGMD,OBRAKE,BETAZS(2),
B PCGDED,PCGMAX,PCRATE,POIDTR,RDELT1,
C RDELT2,RTORS,TRINDZ
COMMON /MANAL/
1 O,AP,PED,OMG,TZM,TIM,T2M,
2 TZT,T1T,T2T,ALEL,CZET,PSDD,
3 SZET,TAXL,TAXR,XANG,XLNK(16),ZANG,
4 ALCP,ALFIN,ALLWG,ALRWG,CDELE,CDFIN,
5 CDLWG,CORWG,CLELE,CLFIN,CLLWG,CLRWG,CWING,
6 CYCRI,CYCR2,CZET4,CZET6,CZET9,RANGE,
7 SZETS,SZET7,SZET8,WGCOL,XAELE,XAFIN,
8 XAFUS,XAJET,YAFIM,ZAELE,ZAFIN,ZAFUS,
9 YAELE,YAFUS,YALWG,YARWG,YALJET,YARJET,
A ZAJET,ALECR1,ALGFPD,BOTTOM,CZET11,
B CZET12,CZET13,EIZETA,HALFPI,SZET10,
C XAPYLD,YGUSTW,ZAPYLD,ZFLWGL,ZFRWG1
* TZMS,TIMS,T2MS,TZTS,T1TS,T2TS,
* CLOCK,FLOCK,XLOCK,TCLOCK
COMMON /ROMAN/
* ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
* T,PCC(2),COSE(7,7,2),BETAN(2),BETAX(2),BETAZ(2),
* AIB(2),APDD,ARDD,AYDD,AIR(2),
* DPSI(12,7),DTRR,MPSI(2),ZZTR,
* BETAG(12,2),BNPSI(2),
* CONOZ,GMAXV,RATEI,RATE2,STOP2,
* THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
* GMAXV2,GMAXV3,GUSTYP,HMPSIR(2),
* HUBKPS,HUBKRS,HUBTPS,HUBTRS,
* KONFIG,LNGTH1,PILGH1,PSIREF(2),
* START2,XMOMLI(12,2),
* RM,RTR,ORM,ORTR,TIMT,T1TT,
* T2MT,TZTT,TZMT,TZTT,XMAL,XMAIT,
* XMB1,XMB1T,AIBPM,AIBPT,AIBRM,AIART,

```

```

INIT0010
INIT0020
INIT0030
INIT0040
INIT0050
INIT0060
INIT0070
INIT0080
INIT0090
INIT0100
INIT0110
INIT0120
INIT0130
INIT0140
INIT0150
INIT0160
INIT0170
INIT0180
INIT0190
INIT0200
INIT0210
INIT0220
INIT0230
INIT0240
INIT0250
INIT0260
INIT0270
INIT0280
INIT0290
INIT0300
INIT0310
INIT0320
INIT0330
INIT0340
INIT0350
INIT0360
INIT0370
INIT0380
INIT0390
INIT0400
INIT0410
INIT0420
INIT0430
INIT0440
INIT0450
INIT0460
INIT0470
INIT0480
INIT0490
INIT0500
INIT0510
INIT0520
INIT0530
INIT0540

```

```

C      APTD,APTD,ARTD,ARTD,PSD,PSDT,
D      XSTAHM,XSTAHT,YSTAHM,YSTAHT,
F      HURKP,HURKTP,HUBKR,HUBKTR
F      AZETA,AZETAT,VZETA,VZETAT
COMMON /MANARD/ I,V,IND,NVAG,APRMT,ARBMT,AYBMT,RETAO(2),TOELT,
1      BETAE(2),HGUSTE,HGUSTF,AR8MT,AR8MT,AR8MT,RETAO(2),TOELT,
2      VGUSTM,YGUSTF,GFMD,GLAT,GVERT,
3      VXB,VXB,APD,VVB,ARO,AYD,
4      COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
5      APE,ARE,AIM,BIM,AITR,BITR,
6      XAR(2),YAR(2),ZAR(2),
7      VIMR,VITR,ZETA,ZETATR,HMR,HTR,
8      TMR,TTR,OMX,QTR,YMRF,YTRF
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
1      NPART,NVARA,NVARB,NVARC,NSCALE
1      NVARS,NPRINT,NTIME
COMMON /FORV/ Y(4,150)
DATA HEAD1/ , MAIN FWD RIGHT TAIL AFT LEFT */
DATA DTRR1/57.2957795/
DATA DTR / .1745329E-01/
DIMENSION HEAD1(2,6),PAR(191)
DD 78 J=1,7
PAR(J+135)=0.
PAR(J+142)=Y(1,J+106)*DTRR1
PAR(J+149)=Y(1,J+11)*DTRR1
PAR(J+156)=Y(1,J+17)*DTRR1
PAR(J+163)=0.
PAR(J+170)=Y(1,J+113)*DTRR1
PAR(J+177)=Y(1,J+38)*DTRR1
PAR(J+184)=Y(1,J+24)*DTRR1
78 CONTINUE
DD 91 N=1,2
NPSIN=NPSI(N)
IF(NPSIN.EQ.0.) GO TO 91
K=28*N+107
K=K+1
K=K+1
PAR(K)=(Y(1,N+6)+DPSI(J,N))*DTRR1
IF(PAR(K).GE.360.) PAR(K)=PAR(K)-360.
IF(PAR(K).LT.0.) PAR(K)=PAR(K)+360.
90 CONTINUE
91 CONTINUE
DD 79 J=1,3
JJ=4-J
PAR(J+70)=Y(1,J+89)
PAR(J+76)=Y(1,J+14)
PAR(J+82)=Y(1,J+75)
PAR(J+85)=Y(1,J+78)*DTRR1
PAR(J+89)=Y(1,J)
PAR(J+92)=Y(1,J+3)*DTRR1
PAR(J+96)=Y(1,J+84)*DTRR1
PAR(J+99)=Y(1,J+ 9)*DTRR1
79 CONTINUE
PAR(1)=APTD*DTRR
INIT0550
INIT0560
INIT0570
INIT0580
INIT0590
INIT0600
INIT0610
INIT0620
INIT0630
INIT0640
INIT0650
INIT0660
INIT0670
INIT0680
INIT0690
INIT0700
INIT0710
INIT0720
INIT0730
INIT0740
INIT0750
INIT0760
INIT0770
INIT0780
INIT0790
INIT0800
INIT0810
INIT0820
INIT0830
INIT0840
INIT0850
INIT0860
INIT0870
INIT0880
INIT0890
INIT0900
INIT0910
INIT0920
INIT0930
INIT0940
INIT0950
INIT0960
INIT0970
INIT0980
INIT0990
INIT1000
INIT1010
INIT1020
INIT1030
INIT1040
INIT1050
INIT1060
INIT1070
INIT1080

```

PAR(2)=ARTD*DTRR
 PAR(3)=VXS(1)
 PAR(4)=Y(1.84)*DTRR
 PAR(5)=Y(1.107)*DTRR
 PAR(6)=YMR
 PAR(7)=AIM*DTRR
 PAR(8)=BIM*DTRR
 PAR(9)=VVS(1)
 PAR(10)=Y(1.9)*DTRR
 PAR(11)=Y(1.32)*DTRR
 PAR(12)=HMR
 PAR(13)=VZS(1)
 PAR(14)=Y(1.7)*DTRR
 PAR(15)=Y(1.18)*DTRR
 PAR(16)=YHRF
 PAR(17)=TZM*DTRR
 PAR(18)=TIM*DTRR
 PAR(19)=TZM*DTRR
 PAR(20)=BETA0(1)*DTRR
 PAR(21)=ZETA*DTRR
 PAR(22)=OMX
 PAR(31)=TZMT*DTRR
 PAR(32)=TIMT*DTRR
 PAR(33)=TZMT*DTRR
 PAR(23)=PAR(31)-PAR(17)
 PAR(24)=PAR(32)-PAR(18)
 PAR(25)=PAR(33)-PAR(19)
 PAR(26)=VIMR
 PAR(27)=PSD*PIU30
 PAR(28)=OMX*PSD550
 PAR(29)=BETAX(1)*DTRP
 PAR(30)=HUBKP*DTR
 PAR(34)=BETAN(1)*DTRR
 PAR(35)=HUBKR*DTR
 PAR(36)=APTTD*DTRR
 PAR(37)=ARTTD*DTRR
 PAR(38)=VXS(2)
 PAR(39)=PAR(4)*GEARAT
 PAR(40)=Y(1.114)*DTRR
 PAR(41)=YTR
 PAR(42)=AITR*DTRR
 PAR(43)=BITR*DTRR
 PAR(44)=VVS(2)
 PAR(45)=PAR(10)*GEARAT
 PAR(46)=Y(1.39)*DTRR
 PAR(47)=HTR
 PAR(48)=VZS(2)
 PAR(49)=Y(1.6)*DTRR
 PAR(50)=Y(1.25)*DTRR
 PAR(51)=YTRF
 PAR(52)=YTT*DTRR
 PAR(53)=ITT*DTRR
 PAR(54)=TZT*DTRR
 PAR(55)=RETAC(2)*DTRP

INIT1090
 INIT1100
 INIT1110
 INIT1120
 INIT1130
 INIT1140
 INIT1150
 INIT1160
 INIT1170
 INIT1180
 INIT1190
 INIT1200
 INIT1210
 INIT1220
 INIT1230
 INIT1240
 INIT1250
 INIT1260
 INIT1270
 INIT1280
 INIT1290
 INIT1300
 INIT1310
 INIT1320
 INIT1330
 INIT1340
 INIT1350
 INIT1360
 INIT1370
 INIT1380
 INIT1390
 INIT1400
 INIT1410
 INIT1420
 INIT1430
 INIT1440
 INIT1450
 INIT1460
 INIT1470
 INIT1480
 INIT1490
 INIT1500
 INIT1510
 INIT1520
 INIT1530
 INIT1540
 INIT1550
 INIT1560
 INIT1570
 INIT1580
 INIT1590
 INIT1600
 INIT1610
 INIT1620

PAR(56)=ZETATR*OTRR
PAR(57)=QTR
PAR(66)=TZTT*OTRR
PAR(67)=YITT*OTRR
PAR(68)=Y2TT*OTRR
PAR(58)=PAR(66)-PAR(52)
PAR(59)=PAR(67)-PAR(53)
PAR(60)=PAR(68)-PAR(54)
PAR(61)=VITR
PAR(62)=PAR(27)*GEARAT
PAR(63)=OTR*PSD550*GEARAT
PAR(64)=BETAX(2)*OTRF
PAR(65)=HUBKTP*OTR
PAR(69)=BETAN(2)*OTRR
PAR(70)=HUBKTR*DTR
PAR(74)=DIET
PAR(75)=V*FTKTS
PAR(76)=AYFP*OTRR
PAR(80)=--PAR(79)
PAR(81)=VH*FTKTS
PAR(82)=APFP*OTRR
PAR(89)=Y(1.89)*DTRR1
PAR(96)=Y(1.14)*DTRR1
PAR(103)=COLSTK
PAR(104)=CYSTK1
PAR(105)=ALLMG*OTRR
PAR(106)=ALRMG*OTRR
PAR(107)=ALEL*OTRR
PAR(108)=ALFIN*OTRR
PAR(109)=AY*OTRR
PAR(110)=CGSTA
PAR(111)=HGUST
PAR(112)=--GFWD
PAR(113)=CYSTK2
PAR(114)=CLLMG
PAR(115)=CLRMG
PAR(116)=CLELE
PAR(117)=CLFIN
PAR(118)=AP*OTRR
PAR(119)=CGBL
PAR(120)=YGUST
PAR(121)=GLAT
PAR(122)=PEDAL
PAR(123)=COLMG
PAR(124)=CDRMG
PAR(125)=CDELE
PAR(126)=CDFIN
PAR(127)=CGWL
PAR(128)=VGUST
PAR(129)=GVERT
PAR(130)=TAXR
PAR(131)=OMRS
PAR(132)=OMR*PSD550
PAR(133)=TAXL

INIT1630
INIT1640
INIT1650
INIT1660
INIT1670
INIT1680
INIT1690
INIT1700
INIT1710
INIT1720
INIT1730
INIT1740
INIT1750
INIT1760
INIT1770
INIT1780
INIT1790
INIT1800
INIT1810
INIT1820
INIT1830
INIT1840
INIT1850
INIT1860
INIT1870
INIT1880
INIT1890
INIT1900
INIT1910
INIT1920
INIT1930
INIT1940
INIT1950
INIT1960
INIT1970
INIT1980
INIT1990
INIT2000
INIT2010
INIT2020
INIT2030
INIT2040
INIT2050
INIT2060
INIT2070
INIT2080
INIT2090
INIT2100
INIT2110
INIT2120
INIT2130
INIT2140
INIT2150
INIT2160

```

PAR(134)=OMRS*PSD550
PAR(135)=OBRAKE
WRITE (3) IPSM,T,PAR,A,XMB1,XMA1,XMBIT,XMAIT
TIME, I91 PAR-S, 75 A-S = 267 TOTAL
NTIME=NTIME+1
IF(NTIME-GE.NPRINT) NTIME=0
IF(NTIME-NE.0) RETURN
CALL TIMEX(TUSED,DTIME,TLEFT)
WRITE(6,80) T,TUSED
WRITE (6,81) (HEAD1(J,KONFIG),J=1,2),(PAR(J),J=1,35)
WRITE(6,82) (PAR(J),J=71,82)
WRITE(6,83) (PAR(J),J=83,102)
WRITE(6,84) (PAR(J),J=103,129)
WRITE(6,85) (PAR(J),J=130,135)
CALL WRFM
WRITE (6,86)
WRITE (6,87) (HEAD1(J,KONFIG),J=1,2),(PAR(J),J=136,163)
WRITE (6,87) (HEAD1(J,KONFIG),J=1,2),(PAR(J),J=164,191)
RETURN
80 FORMAT (I1,10X,F8.3,3X,'SECONDS MANEUVER TIME',10X,
F8.3,3X,'MINUTES ELAPSED COMPUTING TIME',10X,
'L8,FT,DEG,SEC UNITS')
81 FORMAT (I10,49X,2A4,'ROTOR SHAFT REFERENCE'/
28X,'O/AL',6X,'P/BI',37X,'PSI',7X,'BETA',7X,'FORCES'/
14X,'VELOCITY ',2F10.3,6X,'U ',F8.3,
6X,'ACCEL ',2F10.3,6X,'THRUST ',F10.3/
14X,'LOCATION ',2F10.3,6X,'V ',F8.3,
6X,'VELOCITY ',2F10.3,6X,'M-FORCE ',F10.3/
49X,'M ',F8.3,
6X,'LOCATION ',2F10.3,6X,'Y-FORCE ',F10.3/
7X,'FROM',7X,'COLLEC F/A CYC LAT CYC'/
7X,'CONTROLS ',3F8.3,3X,'CONING ',F8.3,
3X,'M,TILT ',F9.3,3X,'TOPO ',F9.2,
3X,'FLAP, LIM',6X,'HUB SPRINGS'/
7X,'OTHER ',3F8.3,3X,'IND, V ',F8.3,
3X,'RPM ',F9.3,3X,'HP ',F9.2,
3X,'UPPER ',F7.3,3X,'F/A ',F8.1/
7X,'TOTAL ',3F8.3,57X,'LOWER ',F7.3,
3X,'LAT ',F8.1)
82 FORMAT (I10,58X,'GROUND REFERENCE'/
38X,'X',9X,'Y',9X,'Z',24X,'SPEED (KTS) FLT PATH ANGLES'/
22X,'VELOCITY ',3F10.3,' DISTANCE ',F8.1,
1 AIR ',F7.2,' HEADING ',F8.3/
22X,'LOCATION ',3F10.3,' ALTITUDE ',F8.1,
1 GND ',F7.2,' CLIMB ',F8.3)
83 FORMAT (I10,57X,'FUSELAGE REFERENCE'/
20X,'U',9X,'V',9X,'W',9X,'P',9X,'Q',9X,'R',
7X,'BOBMT',5X,'EULER ANGLES FROM GROUND'/
5X,'ACCEL ',5X,7F10.3,18X,'PSI',6X,'THETA',6X,'PHI'/
5X,'VELOCITY ',7F10.3,3X,'VELOCITY ',3F10.3/
88X,'LOCATION ',3F10.3)
84 FORMAT (I10,6X,'CONTROLS (PCT)'/
7X,'COLSTK',5X,F7.2,8X,'L. WING R. WING',

```

```

2 4X,'ELF',4X,'FIN/RUD FUSELAGE',7X,'C.G. LOC (IN)',
3 6X,'GUST (CG) G-S',
4 7X,'F/A CYCSTK ',F7.2,' ATK ',4F9.3,
5 1 ATKY ',EB.3,' STA. LINE ',F7.2,
6 1 FWD ',F5.1,' FWD ',F5.2/
7 7X,'LAT CYCSTK ',F7.2,' CL ',4F9.3,
8 1 ATKP ',FB.3,' B. LINE ',F7.2,
9 1 LAT ',F5.1,' LAT ',F5.2/
0 7X,'PEDAL',6X,F7.2,' CD ',4F9.3,'17X,'W. LINE ',F7.2,
1 1 VERT ',F5.1,' VERT ',F5.2)
R 05 FORMAT (IHO,34X,'JET THRUST',13X,'ENGINE',/
1 35X,'RIGHT/CENTER ',F8.1,' TORQUE ',
2 F9.1,' TOTAL HP RQD ',6X,F8.1/
3 35X,'LEFT',9X,F8.1,' SHAFT HP ',F9.1,
4 1 ROTOR BRAKE TORQUE ',F8.1)
R6 FORMAT (IMI)
R7 FORMAT (IHO,59X,2A4,'ROTOR',/
1 48X,'BLADE 1 BLADE 2 BLADE 3 BLADE 4 BLADE 5',
2 3X,'BLADE 6 BLADE 7',/
3 18X,'AZIMUTH LOCATION ',7F10.3/
4 18X,'FLAPPING ACCEL WRT MAST ',7F10.3/
5 18X,'FLAPPING VELOCITY WRT MAST ',7F10.3/
6 18X,'FLAPPING LOCATION WRT MAST ',7F10.3)
INIT2710
INIT2720
INIT2730
INIT2740
INIT2750
INIT2760
INIT2770
INIT2780
INIT2790
INIT2800
INIT2810
INIT2820
INIT2830
INIT2840
INIT2850
INIT2860
INIT2870
INIT2880
INIT2890
INIT2900
INIT2910
INIT2920
INIT2930
INIT2940

```

```

SUBROUTINE INRO (ZETAR,BH,BAIB,XMR,Q,B,N)
COMMON /STRIAB/ D(21),DT(21),E(79),F(10),X(10),
1 DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPD,ERR(10),KMI,RHO,
3 R12,SPD(6,3),XBW(21),XEL(14),
4 XER(7),XFC(28),XFN(7),XFS(35),
5 XGN(7),XIT(21),XRM(49),XTR(49),
XMR MUST HAVE ITS NAME CHANGED HERE TO AVOID CONFLICT
WITH ARGUMENT
6 XWG(21),YMR(21),YTR(21),YWG(21),
7 YEL(21),YFN(21),BLCG,DAMP,DEPD(10),
8 EPDS,EPDX(10),MASS,OSV1,TMRS,TTRS,
9 WLCG,XCON(63),XJET(14),XMIN,AYEFP,
A BETAES(2),CNPCD,DHADO,DYBDR,GUESS,
B NPASS,PDPHI(10,11),STACG,TZERD,
C XMAST,DHADA0,DODCOL,DTRRSO,DYBDR,
D ENGRPM,4XPASS,PSO30P,TRIND1,XLIMIT
COMMON /STAMAN/ HL(2),XX,YY,AY1,GOV,KPD,QPC,000,
1 RIY,APBG,ARBG,ASEP,AYBG,BWTC,
2 RC,BWTK,BWTK,CG8L,DP1X,DP1Z,
3 FHPT(2),R550,ALERT,AYDMX,DELTZ,
4 OPIX,DTBWT,DWLCG,MOELT,HGUST,
5 HLTR1,HLTR2,ITORS,KTCR,DMEGM,
6 PCDEL,QMRS,RMASS,TRALT,TMOPI,VGUST,
7 ISTOP,XAGUN,XAPYL,XARSP(2),YAGUN,
8 VARS(2),YGUST,ZAGUN,ZAPYL,ZARSP(2),
9 DELTZR,DSTACG,E'MAST,GPRELD,HLPYLD,
A IBRAKE,DMEGMO,OBRAKE,BETAZS(2),
B PCGOED,PCGMAX,PCRATE,PO1DTR,ROELT1,
C RDELTZ,RITORS,TRINDZ
COMMON /ROMAN/ ZZ,VXS(2),VVS(2),VZS(2),BETA(12,2),
1 T,PCC(2),COSE(7,7,2),BETAN(2),BETAX(2),BETAZ(2),
2 A18(2),APDD,ARDO,AYDD,AIR(2),
3 DPST(12,2),DTRR,NPSI(2),ZZTR,
4 BETA0(12,2),8NPSI(2),
5 COND2,GMAXV,RATE1,RATE2,STDP2,
6 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
7 GMAXV2,GMAXV3,GUSTYP,HMPSIR(2),
8 HUBKPS,HUBKRS,HUBTPS,HUBTRS,
9 KONFIG,LNGTHI,PILGHI,PSIREF(2),
A START2,XNOMLI(12,2),
B R(2),OR(2),TI(2),
C T2(2),TZR(2),XMA(2),
D XMB(2),A18P(2),A1BR(2),
E APDR(2),ARDR(2),PSI0(2),
F XSTAH(2),YSTAH(2),
G HUBKPR(2),HUBKRP(2)
COMMON /ROSTAR/ AZETAR(2),VZETAR(2)
1 AM(2),CT,P1,XB(2),ALT,ADR(2),EXH(2),
2 NXR(2),RBH(2),SWC(2),UHS,CDHB(2),LROT(2),
3 RATB(2),RTRP(2),TAIR(14),CONEK(2),OCAFR(2),FVIND,
4 NVARD,
5 SWKR1(2),SWKR2(2),TIP18(2),TIP38(2),
6 TWIST(20,2),CLRADK(2),DELTA3(2),

```

```

INR00010
INR00020
INR00030
INR00040
INR00050
INR00060
INR00070
INR00080
INR00090
INR00100
INR00110
INR00120
INR00130
INR00140
INR00150
INR00160
INR00170
INR00180
INR00190
INR00200
INR00210
INR00220
INR00230
INR00240
INR00250
INR00260
INR00270
INR00280
INR00290
INR00300
INR00310
INR00320
INR00330
INR00340
INR00350
INR00360
INR00370
INR00380
INR00390
INR00400
INR00410
INR00420
INR00430
INR00440
INR00450
INR00460
INR00470
INR00480
INR00490
INR00500
INR00510
INR00520
INR00530
INR00540

```

```

5      LAMBDA(2),UPGUST,URGUST,UTGUST,WRDTRD,
6      ER(2),ERX(2),
7      XLIMAX(2),XLIMIN(2)
1  DIMENSION XMR(49),HUBKS(2,2),ZETAR(2),BM(2),BATB(2),B(2)
      ,DROT(2,2)
1  EQUIVALENCE (HUBKS(1,1),HUBKPS),(DROT(1,1),O(1))
VXS(N)=0.
VYS(N)=0.
VZS(N)=0.
LROT(N)=0.
ARDR(N)=0.
APDR(N)=0.
AIBP(N)=0.
AIBR(N)=0.
      BETAZ = INPUT PRE-CONE ANGLE
      BETAE = DEFLECTION FROM BETAZ DUE TO BLADE BENDING
      BETAO = CONING ANGLE = BETAZ + BETAE
AZEIAR(N)=0.
BETAZD(N)=0.
VZETAR(N)=0.
PSIREF(N)=0.
B(N)=XMR(1)
NXR(N)=XMR(2)
NPSI(N)=12
R(N)=XMR(4)
IF(R(N).NE.0.) GO TO 12
R(N)=1.
S(N)=0.
12 CONTINUE
C=XMR(5)*R12
COMEK(N) = XMR(6)*DTRR
BETAN(N)=XMR(7)*DTR
XARSP(N)=STACG-XMR(8)*R12
YARSP(N)=XMR(9)*R12-BLCG
ZARSP(N)=WLCG-XMR(10)*R12
ZETAR(N)=XMR(11)*DTR
HL(N)=XMR(12)
FHPT(N)=XMR(16)
HUBKPR(N)=XMR(17)*DTRR
HUBKRR(N)=XMR(18)*DTRR
SWKRI(N)=XMR(19)*DTR
EXH(N)=XMR(21)
BETAZ(N)=XMR(22)*DTR
PCC(N)=XMR(23)
IF(N.EQ.2) PCC(N)=XMR(23)*TRIND
DELTA3(N)=TAN(XMR(24)*DTR)
CJHB(N)=XMR(25)
CLRADK(N)=XMR(26)*TWOPIC/(57.3*(C+4.*R(N)))
DCAFR(N)=XMR(27)
NRAD = NXR(N)
OO 11 I=1,NRAD
TWIST(I,N)=-XMR(11+20)*DTR
11 CONTINUE
      SWKR2(N)=SWKRI(N)

```

```

INR00550
INR00560
INR00570
INR00580
INR00590
INR00600
INR00610
INR00620
INR00630
INR00640
INR00650
INR00660
INR00670
INR00680
INR00690
INR00700
INR00710
INR00720
INR00730
INR00740
INR00750
INR00760
INR00770
INR00780
INR00790
INR00800
INR00810
INR00820
INR00830
INR00840
INR00850
INR00860
INR00870
INR00880
INR00890
INR00900
INR00910
INR00920
INR00930
INR00940
INR00950
INR00960
INR00970
INR00980
INR00990
INR01000
INR01010
INR01020
INR01030
INR01040
INR01050
INR01060
INR01070
INR01080

```

INR0109C
 INR01100
 INR01110
 INR01120
 INR01130
 INR01140
 INR01150
 INR01160
 INR01170
 INR01180
 INR01190
 INR01200
 INR01210
 INR01220
 INR01230
 INR01240
 INR01250
 INR01260
 INR01270
 INR01280
 INR01290
 INR01300
 INR01310
 INR01320
 INR01330
 INR01340
 INR01350
 INR01360
 INR01370
 INR01380
 INR01390
 INR01400
 INR01410
 INR01420
 INR01430
 INR01440
 INR01450
 INR01460
 INR01470
 INR01480
 INR01490
 INR01500
 INR01510
 INR01520
 INR01530
 INR01540
 INR01550
 INR01560
 INR01570
 INR01580
 INR01590
 INR01600
 INR01610
 INR01620

```

CR(N)=PSID(N)*R(N)
BETAZ(N)=BETAZ(N)
BETAX(N)=2.*BETAZ(N)-BETAN(N)
RTRP(N)=1./(TWOPI*RMOR(N)**2)
XB(N)=-.05
IF(NRAD.NE.0) XB(N)=1./NRAD
TIPIR(N)=.125-.00625*NRAD
TIP3B(N)=3.*TIPIR(N)
AOR(N)=(FXH(N)/R(N))**2
BH(N)=-.5*B(N)
IF(XMR(16).NE.0.) XMR(15)=XMR(16)
IH=20.*XMR(15)/R(N)
RSO=R(N)**2
HNPSI=2.*QCOR(N)*XB(N)
R10=.015*RSO
R10 = IN * FT
R09=-.2330821E-04*RSO*R(N)
R09 = IN * FT * SEC**2
DO=DROT(21.N)/R(N)
AIB(N)=1307.511*DD
CFX=2.052239*DD
RI=0.
RIMK=0.
K=21
RO=20.75
DO 57 I=1,20
K=K-1
RO=RO-1.
POMK=RO*DROT(K,N)
CFX=CFX+RIMK+ROMK
AIB(N)=AIB(N)+RO*ROMK+RI+RIMK
RI=RO-.5
RIMK=RI*DROT(K,N)
IF(K.EQ.10) GO TO 56
57 CONTINUE
58 CONTINUE
AM(N)=CFX*R10
AIB(N)=AIB(N)*R09
BAIB(N)=B(N)*AIB(N)
AIR(N) =BH(N)*AIB(N)
IF(B(N).LE.2.) A(R(N) =2.*AIB(N)
RBH(N)=0.
(F(BH(N).NE.0.) RBH(N)=AIR(N)/BH(N)
RAIB(N)=0.
IF(AIR(N).NE.0.) RAIB(N)=1./A(R(N)
ECE=FHPT(N)*AM(N)/32.16
CALL NOPSIO (HNPSI,BH,N)
ECEI=ECE*RAIB(N)
HUBKS(1,N)=ECEI
HUBKS(2,N)=ECEI
IF(FHPT(N).EQ.0.) GO TO 48
BETAZ(N)=0.
HUBKPS(N)=ECE*PSID(N)**2
HUBKRR(N)=HUBKPR(N)

```

```

48 CONTINUE
IF(B(N).EQ.0.) RETURN
NPSIN=B(N)
DO 10 I=1,NPSIN
COSE(I,I,N)=1.
IF(I.EQ.NPSIN) GO TO 10
I1=I+1
DO 9 K=I1,NPSIN
IF(ECE.NF.0.) GO TO 8
COSE(I,K,N)=DCOS(6.283185307D00/NPSIN*(I-K))
COSE(K,I,N)=COSE(I,K,N)
GO TO 9
8 CONTINUE
COSE(I,K,N)=0.
COSE(K,I,N)=0.
9 CONTINUE
10 CONTINUE
RETURN
END

```

```

INR01630
INR01640
INR01650
INR01660
INR01670
INR01680
INR01690
INR01700
INR01710
INR01720
INR01730
INR01740
INR01750
INR01760
INR01770
INR01780
INR01790
INR01800
INR01810

```

```

SUBROUTINE ITRI4(LPASS)
COMMON /STRIAB/ D(21),DT(21),EI79,F(10),X(10),
1 DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPD,ERR(10),KMI,RHO,
3 R12,SPDI6,6,3),XBMI21),XEL(14),
4 XER(7),XFIC28),XFN(7),XFS(35),
5 XGN(7),XITI21),XMR(49),XTRI49),
6 XWG(21),YMR(21),YTR(21),YMG121),
7 YFL(21),YFNI21),BLCG,DAMP,DEPD(10),
8 EPDS,EPDX(10),MASS,OSV1,TMRS,TTRS,
9 WLCG,XCONI63),XJET(14),XMIN,AYEFP,
A 9ETAES(2),CNPCD,DHADQ,DYBDR,GUESS,
B VPASS,PPPHI(10,11),STACG,YZERO,
C XMAST,DHADAQ,DODCOL,OTRRSQ,DYBDBR,
D ENGRPM,MXPASS,PSD30P,TRINDI,XLIMIT
COMMON /MANAL/
1 TZT,T1T,T2T,ALEL,CZFT,PSDD,
2 SZFT,TAXL,TAXR,XAWG,XLNKI16),ZAWG,
3 ALCYP,ALFIN,ALLWG,ALRWG,CDELE,CDFIN,
4 COLWG,CORWG,CLELF,CLFIN,CLLWG,CLRWG,CWING,
5 CYCR1,CYCR2,CZEI4,CZEI6,CZET9,RANGE,
6 SZETS,SZFT7,SZFT8,WGCOL,XAFLE,XAFIN,
7 XAFUS,XAJET,YAFIN,ZAELE,ZAFIN,ZAFUS,
* YAEF,YAFUS,YALWG,YARWG,YALJET,YARJET,
9 ZAJET,ALECR1,ALCFPD,BOTTOM,CZET11,
9 CZFT12,CZET13,EIZFTA,HALFPI,SZET10,
A XAPYLO,YGUSTW,ZAPYLD,ZFLWGI,ZFRWGI
B ,TZMS,TIMS,T2MS,TZTS,TITS,T2TS,
C CLOCK,FLOCK,XLOCK,TLOCK
COMMON /MANARO/ (V,IND,NWAG,APBMT,ARBMT,AYBMT,BETA0(2),TDELT,
1 3ETAE(2),HGUSTE,HGUSTF,HGUSTW,VGUSTE,
2 VGUSTW,YGUSTF,GFWD,GLAT,GVERT,
3 VXB,VZB,APD,VYR,ARD,AYD,
4 COLSTK,CYSTKI,CYSTX2,PEDAL,AYE,
5 APE,ARE,ALM,BIM,ALTR,BITR,
6 XAR(2),YAR(2),ZAR(2),
7 VIMP,VITR,ZETA,ZETATR,HMR,HTR,
8 TMR,ITR,OMX,OTR,YMRF,YTRF
COMMON /STANRO/ J,W,ITM,VHS(2),LINK,QUELE,VROT(2),
1 VSND,YFIN(2),ZFEL(2),AIBAL(2),
2 BIBAL(2),CONDI,SWING,PILGRZ,PMGEL1,
3 BM,BTR,PMOMM,PMOMT,RMOMM,RMOMT
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOMI49),IPSN,
1 NPART,NVARA,NVARR,NVARC,NSCALE
2 NVARS,NPRINT,NTIME
COMMON /FORY/ Y(4,150)
DIMENSION VAR(11)
EQUIVALENCE (VAR11),COLSTK)
KOUNT=11
IF(BTR.FQ.0.) KOUNT=9
IF(BM.FQ.0.) KOUNT=7
IF(XFC(23).NE.0.) KOUNT=7
IF(ITM.NE.0) KOUNT=7
KMI=KOUNT-1

```

```

ITRI0010
ITRI0020
ITRI0030
ITRI0040
ITRI0050
ITRI0060
ITRI0070
ITRI0080
ITRI0090
ITRI0100
ITRI0110
ITRI0120
ITRI0130
ITRI0140
ITRI0150
ITRI0160
ITRI0170
ITRI0180
ITRI0190
ITRI0200
ITRI0210
ITRI0220
ITRI0230
ITRI0240
ITRI0250
ITRI0260
ITRI0270
ITRI0280
ITRI0290
ITRI0300
ITRI0310
ITRI0320
ITRI0330
ITRI0340
ITRI0350
ITRI0360
ITRI0370
ITRI0380
ITRI0390
ITRI0400
ITRI0410
ITRI0420
ITRI0430
ITRI0440
ITRI0450
ITRI0460
ITRI0470
ITRI0480
ITRI0490
ITRI0500
ITRI0510
ITRI0520
ITRI0530
ITRI0540

```

```

NPASS=C
KPASS=-1
CALL TIMEX (TUSED,DTIMEF,LEFT)
5 NPASS=NPASS+1
KPASS=KPASS+1
IF(KPASS.EQ.LPASS) KPASS=0
IF(COND1.NE.0.) WRITE (6,210) NPASS
J=1
BETA(1)=BETAES(1)
BETA(2)=BETAES(2)
TMR=TMRS
TTR=TTRS
CALL AJACOB
IF(EXIT.NE.0.) GO TO 61
BETA(1)=BETA(1)
BETA(2)=BETA(2)
TMR=TMRS
TTR=TTRS
DO 40 K=1,KM1
PD(K,KOUNT)=-F(K)
DO 71 K=1,KM1
IF(ABS(F(K)).GT.DAMP) GO TO 72
71 CONTINUE
CALL DAMPER
72 CONTINUE
DO 73 K=1,KM1
IF(ABS(F(K)).GT.ERR(K)) GO TO 75
GO TO 170
75 CONTINUE
IF(KPASS.GT.0) GO TO 56
J=2
CALL JACOBI
IF(EXIT.NE.0.) GO TO 61
IF(KOUNT.EQ.7)
1 CALL RATS (Y(1,91),Y(1,92),AYE,APE,ARE,VXB,VYB,VZB,-1)
IF(KOUNT.EQ.11) CALL PDZ(PD,AYEFP)
IF(COND1.NE.0.) CALL WRVP (Z,VAR,KM1,PD,TAXL,TXRR)
DO 47 I=1,KM1
PD(I,10)=-PD(I,10)
47 CONTINUE
56 CONTINUE
DO 48 J=1,KOUNT
DO 48 I=1,KM1
48 POPHI(I,J)=PD(I,J)
CALL SOLVE
IF(EXIT.NE.0.) GO TO 10
CALL RATIO(X,EPDX,XLIMIT,VAR)
DO 86 I=6,11
IF(ABS(VAR(I)).GT.HALFPI) GO TO 61
86 CONTINUE
IF(NPASS.LT.MXPASS)GO TO 5
61 EXIT=1.
170 CONTINUE

```

```

ITRI0550
ITRI0560
ITRI0570
ITRI0580
ITRI0590
ITRI0600
ITRI0610
ITRI0620
ITRI0630
ITRI0640
ITRI0650
ITRI0660
ITRI0670
ITRI0680
ITRI0690
ITRI0700
ITRI0710
ITRI0720
ITRI0730
ITRI0740
ITRI0750
ITRI0760
ITRI0770
ITRI0780
ITRI0790
ITRI0800
ITRI0810
ITRI0820
ITRI0830
ITRI0840
ITRI0850
ITRI0860
ITRI0870
ITRI0880
ITRI0890
ITRI0900
ITRI0910
ITRI0920
ITRI0930
ITRI0940
ITRI0950
ITRI0960
ITRI0970
ITRI0980
ITRI0990
ITRI1000
ITRI1010
ITRI1020
ITRI1030
ITRI1040
ITRI1050
ITRI1060
ITRI1070
ITRI1080

```

```
CALL PAPA (M,COND1)
RETURN
10 CONTINUE
WRITE (6,11)
RETURN
11 FORMAT (1H0,'THE PARTIAL DERIVATIVE MATRIX IS SINGULAR.'/
1      , THIS IS PROBABLY CAUSED BY ONE OF THE CONTROLS BEING
2 UNCONNECTED.')
210 FORMAT (1H1/1H ,50X,'***** START OF ITERATION '13,' *****')
END
```

```
ITR11090
ITR11100
ITR11110
ITR11120
ITR11130
ITR11140
ITR11150
ITR11160
ITR11170
ITR11180
```

```

SURROUTINE ITRDT (N)
COMMON /ANDJIT/ A1,B1,XK,XY,VI?,VI4,APDM,APFM,ARDM,ARFM,
1 AYFM,RDTJ, XK43,XLIM,CBFAC,
2 GOISK(120),NOPSI,TANAI,TANB1,
3 TANTI,TNT2,DCAF,XK,IPRINT,NORADL,
4 SHEARL(12),SHEARO(12),SHEARR(12),
5 XMOML(12),XMOMO(12)
6
COMMON /ROMAN/
* ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
* T,PCC(2),COSE(7,7,2),BETAN(2),BETAX(2),RETAX(2),
1 AIB(2),APDD,ARDD,AYDO,AIR(2),
2 DPSI(12,2),DIRR,NPSI(2),ZZTR,
3 BETAD(12,2),BNPSI(2),
4 COND?,GMAXV,RATE1,RATE2,STOP?,
5 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
6 GMAXV2,GMAXV3,GUSTYP,HNPSI(2),
7 HUBKPS,HUBKRS,HUBTPS,HUBTRS,
8 KONFIG,LNGTH1,PILGH1,PSIREF(2),
9 START2,XMOMLI(12,2),
10 R(2),GR(2),TI(2),
11 T(2),TZR(2),XMA(2),
12 XMB(2),AIBP(2),AIBR(2),
13 APDR(2),ARDR(2),PSID(2),
14 XSTAH(2),YSTAH(2),
15 HUBKPR(2),HUBKRR(2),
16 AZETAR(?),VZETAR(2)
COMMON /MANAR/ I,V,IND,NWAG,APRMT,ARBMT,AYBMT,BETA0(2),TOELT,
1 BETA1(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
2 VGUSTW,YGUSTF,GFWD,GLAT,GVERT,
3 VXB,VZB,APD,VYR,ARD,AYO,
4 COLSYK,CYSTKI,CYSTK?,PEDAL,AYE,
5 APE,ARE,AIM,BIM,AIR,BIYR,
6 XAR(2),YAR(2),ZAR(2),
7 VIR(2),ZETAR(2),WFORCE(2),
8 THRUST(2),TORQUE(2),YFORCE(2)
COMMON /STANR/ J,W,ITM,VHS(2),LINK,QUELE,VPOT(2),
1 VSND,YFIN(2),ZFEL(2),AIBAL(2),
2 RIBAL(2),COND1,SWING,PILGH2,PMGELL,
3 B(2),PMOM(2),RMOM(2)
COMMON /RSTAP/ AM(2),CT,PI,XR(2),ALT,ADR(2),EXH(2),
1 NXR(2),RBH(2),SWC(2),UHS,CDHB(2),LROT(2),
2 RAIB(2),RTRP(2),TAIR(14),CONEK(2),DCAFR(2),FVIND,
3 NWARD,
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19
20
21
22
23
24
25
26
27
28
29
30
31
32
33
34
35
36
37
38
39
40
41
42
43
44
45
46
47
48
49
50
51
52
53
54
55
56
57
58
59
60
61
62
63
64
65
66
67
68
69
70
71
72
73
74
75
76
77
78
79
80
81
82
83
84
85
86
87
88
89
90
91
92
93
94
95
96
97
98
99
100
101
102
103
104
105
106
107
108
109
110
111
112
113
114
115
116
117
118
119
120
121
122
123
124
125
126
127
128
129
130
131
132
133
134
135
136
137
138
139
140
141
142
143
144
145
146
147
148
149
150
151
152
153
154
155
156
157
158
159
160
161
162
163
164
165
166
167
168
169
170
171
172
173
174
175
176
177
178
179
180
181
182
183
184
185
186
187
188
189
190
191
192
193
194
195
196
197
198
199
200
201
202
203
204
205
206
207
208
209
210
211
212
213
214
215
216
217
218
219
220
221
222
223
224
225
226
227
228
229
230
231
232
233
234
235
236
237
238
239
240
241
242
243
244
245
246
247
248
249
250
251
252
253
254
255
256
257
258
259
260
261
262
263
264
265
266
267
268
269
270
271
272
273
274
275
276
277
278
279
280
281
282
283
284
285
286
287
288
289
290
291
292
293
294
295
296
297
298
299
300
301
302
303
304
305
306
307
308
309
310
311
312
313
314
315
316
317
318
319
320
321
322
323
324
325
326
327
328
329
330
331
332
333
334
335
336
337
338
339
340
341
342
343
344
345
346
347
348
349
350
351
352
353
354
355
356
357
358
359
360
361
362
363
364
365
366
367
368
369
370
371
372
373
374
375
376
377
378
379
380
381
382
383
384
385
386
387
388
389
390
391
392
393
394
395
396
397
398
399
400
401
402
403
404
405
406
407
408
409
410
411
412
413
414
415
416
417
418
419
420
421
422
423
424
425
426
427
428
429
430
431
432
433
434
435
436
437
438
439
440
441
442
443
444
445
446
447
448
449
450
451
452
453
454
455
456
457
458
459
460
461
462
463
464
465
466
467
468
469
470
471
472
473
474
475
476
477
478
479
480
481
482
483
484
485
486
487
488
489
490
491
492
493
494
495
496
497
498
499
500
501
502
503
504
505
506
507
508
509
510
511
512
513
514
515
516
517
518
519
520
521
522
523
524
525
526
527
528
529
530
531
532
533
534
535
536
537
538
539
540
541
542
543
544
545
546
547
548
549
550
551
552
553
554
555
556
557
558
559
560
561
562
563
564
565
566
567
568
569
570
571
572
573
574
575
576
577
578
579
580
581
582
583
584
585
586
587
588
589
590
591
592
593
594
595
596
597
598
599
600
601
602
603
604
605
606
607
608
609
610
611
612
613
614
615
616
617
618
619
620
621
622
623
624
625
626
627
628
629
630
631
632
633
634
635
636
637
638
639
640
641
642
643
644
645
646
647
648
649
650
651
652
653
654
655
656
657
658
659
660
661
662
663
664
665
666
667
668
669
670
671
672
673
674
675
676
677
678
679
680
681
682
683
684
685
686
687
688
689
690
691
692
693
694
695
696
697
698
699
700
701
702
703
704
705
706
707
708
709
710
711
712
713
714
715
716
717
718
719
720
721
722
723
724
725
726
727
728
729
730
731
732
733
734
735
736
737
738
739
740
741
742
743
744
745
746
747
748
749
750
751
752
753
754
755
756
757
758
759
760
761
762
763
764
765
766
767
768
769
770
771
772
773
774
775
776
777
778
779
780
781
782
783
784
785
786
787
788
789
790
791
792
793
794
795
796
797
798
799
800
801
802
803
804
805
806
807
808
809
810
811
812
813
814
815
816
817
818
819
820
821
822
823
824
825
826
827
828
829
830
831
832
833
834
835
836
837
838
839
840
841
842
843
844
845
846
847
848
849
850
851
852
853
854
855
856
857
858
859
860
861
862
863
864
865
866
867
868
869
870
871
872
873
874
875
876
877
878
879
880
881
882
883
884
885
886
887
888
889
890
891
892
893
894
895
896
897
898
899
900
901
902
903
904
905
906
907
908
909
910
911
912
913
914
915
916
917
918
919
920
921
922
923
924
925
926
927
928
929
930
931
932
933
934
935
936
937
938
939
940
941
942
943
944
945
946
947
948
949
950
951
952
953
954
955
956
957
958
959
960
961
962
963
964
965
966
967
968
969
970
971
972
973
974
975
976
977
978
979
980
981
982
983
984
985
986
987
988
989
990
991
992
993
994
995
996
997
998
999
1000

```

```

DATA HEAD/ 4HMAIN,4HTAIL/
DATA HEAD1/ ROTOR FLAP CORRECTION EXCEEDS 90 DEGREES ROTOR BAL
LANCE EXCEEDS ALLOWABLE ERROR %/
DATA HEAD2/ AIRLOAD LIFT AIRLOAD DRAG RADIAL DRAG FLAPP
TING MOMENT INPLANE MOMENT*/
IF(BETAX(N).EQ.BETAN(N)) ITM=C
KBAL=C
TZRN=TZR(N)
VITER=0
287 KK=2
(F(ITM.NF.0) GO TO 21
(F(L.EQ.2.AND.LINK.EQ.4) GO TO 21
(F(J.EQ.1.AND.LINK.EQ.2) GO TO 21
KK=C
GO TO 288
22 KK=KK-1
21 CONTINUE
VIRS=VIR(N)
VIR(N)=C.
LAMBDA(N)=VZS(N)
(F(THRUST(N).EQ.0.-OR.OR(N).EQ.0.) GO TO 289
CT=THRUST(N)*TRP(N)
CALL VIND (N,EXIT)
(F(EXIT.NE.0.) RETURN
289 CONTINUE
DVIR=VIR(N)-VIRS
(F(ABS(DVIR)-GT.FVIND) VIR(N)=VIR(N)+SIGN(FVIND,DVIR)
VIR(N) = .5*(VIR(N) + VIRS)
288 CONTINUE
XY=SQRT(V(4+VIR(N)**2))-VIZ
(ITER=-1
15 VITER=NITER+1
ITER=ITER+1
(F(ITER.FQ.4) ITR=0
(F(ITM.EQ.0) GO TO 204
NDA1=0
(F(XL(M.LT.XLIM(N)) XLIM=XLIM(N)
EPDD=.5*XLIM
FPDDR=1./EPDD
GO TO 25
204 NDA1=3
25 NDA1=NDA1+1
(F(LINK.EQ.4) GO TO 26
TANAL=TAN(A1)
TANB1=TAN(B1)
COSB1=COS(B1)
PFAC=APDBS/(COS(A1)**2+COSB1)**2*PSID(N)*TANB1
RFAC=ARDBS/COSB1**2-PSID(N)*TANAL
(F(LINK.EQ.3) GO TO 26
BETAO(N)=BETAZ(N)+BETAE(N)
TZR(N)=TZR+BETAE(N)*PCC(N)
26 CONTINUE
XMA(N)=C.
ITR00550
ITR00560
ITR00570
ITR00580
ITR00590
ITR00600
ITR00610
ITR00620
ITR00630
ITR00640
ITR00650
ITR00660
ITR00670
ITR00680
ITR00690
ITR00700
ITR00710
ITR00720
ITR00730
ITR00740
ITR00750
ITR00760
ITR00770
ITR00780
ITR00790
ITR00800
ITR00810
ITR00820
ITR00830
ITR00840
ITR00850
ITR00860
ITR00870
ITR00880
ITR00890
ITR00900
ITR00910
ITR00920
ITR00930
ITR00940
ITR00950
ITR00960
ITR00970
ITR00980
ITR00990
ITR01000
ITR01010
ITR01020
ITR01030
ITR01040
ITR01050
ITR01060
ITR01070
ITR01080

```

```

XMB(N)=0.
PMOM(N)=0.
RMO(N)=0.
THRUST(N)=0.
TORQUE(N)=0.
HFORCE(N)=0.
YFORCE(N)=0.
CALL DDROT(N)
IF(EXIT.NE.0) RETURN
THRUST(N)=THRUST(N)*BNPSI(N)
TORQUE(N)=TORQUE(N)*BNPSI(N)
HFORCE(N)=HFORCE(N)*BNPSI(N)
YFORCE(N)=YFORCE(N)*BNPSI(N)
XMA(N)=XMA(N)-ATBP(N)
XMB(N)=XMB(N)+ATBR(N)
IF(COND2.EQ.C.) GO TO 67
DO 59 K=1,12
DO 58 L=1,5
IF(L.EQ.4) GO TO 58
AA(K,L)=AA(K,L)*BNPSI(N)
58 CONTINUE
59 CONTINUE
WRITE (6,106) ((HEAD2)M,K),M=1,4),(AA)M,K),M=1,12),K=1,5)
60 CONTINUE
IF(COND1.LT.1.5) GO TO 67
ALDEG=AL*DTRR
SIDEG=B1*DTRR
WRITE (6,104) N,NDAL,ALDEG,BIDEF,XMA(N),XMB(N)
1 ,PMOM(N),RMO(N),ATOP(N),ATBR(N)
67 GO TO (64,61,62,1),NDAL
64 BASEA=XMA(N)
BASEB=XMB(N)
IF(ABS(XMA(N))-LE.ERX(N)-AND.ARS)XMB(N))-LE.ERX(N)) X(LM=EPDD
IF(ABS(XMA(N))-GT.ER(N)) GO TO 66
IF(ABS(XMB(N))-GT.ER(N)) GO TO 66
KBAL=1
GO TO 1
66 CONTINUE
IF(ITER.GT.0) GO TO 68
AI=AI+EPDD
GO TO 25
61 AI=AI-EPDD
BI=BI+EPDD
PDAA=(XMA(N)-BASEA)*EPDDR
PDBA=(XMB(N)-BASEB)*EPDDR
GO TO 25
62 BI=BI-EPDD
PDAB=(XMA(N)-BASEA)*EPDDR
PDBB=(XMB(N)-BASEB)*EPDDR
DENDM=PDAA*PDAB-PDAB*PDAA
68 CONTINUE
XNA=BASEB*PDAB-BASEA*PDBB
XNB=BASEA*PDBA-BASEB*PDAA
A=999.

```

```

ITR01000
ITR01100
ITR01110
ITR01120
ITR01130
ITR01140
ITR01150
ITR01160
ITR01170
ITR01180
ITR01190
ITR01200
ITR01210
ITR01220
ITR01230
ITR01240
ITR01250
ITR01260
ITR01270
ITR01280
ITR01290
ITR01300
ITR01310
ITR01320
ITR01330
ITR01340
ITR01350
ITR01360
ITR01370
ITR01380
ITR01390
ITR01400
ITR01410
ITR01420
ITR01430
ITR01440
ITR01450
ITR01460
ITR01470
ITR01480
ITR01490
ITR01500
ITR01510
ITR01520
ITR01530
ITR01540
ITR01550
ITR01560
ITR01570
ITR01580
ITR01590
ITR01600
ITR01610
ITR01620

```

```

IF(DENOM.EQ.0.) GO TO 70
DA1=XNA/DENOM
DB1=XNB/DENOM
IF(ICONDI.GE.1.51 WRITE 16,1751 PDAA,PDBA,PDA8,PD6B,DEMOM,XNA,XNB,
1 DA1,DB1,EPDD,XLIM
63 A=ARS(DA1)
88=ABS(DB1)
IF(A.LT.XLIM.AND.88.LT.XLIM) GO TO 65
IF(A.GT.PI.OR.88.GT.PI) GO TO 70
CA1=DA1*.5
DB1=DB1*.5
GO TO 63
65 A1=A1+DA1
B1=B1+DB1
KK=2
IF(NITER.LT.10) GO TO 15
IF(KRAL.EQ.0) GO TO 70
KBAL=2
NDA1=3
GO TO 25
70 JJ=1
IF(A.LT.XLIM.AND.88.LT.XLIM) JJ=2
WRITE(16,101) FEAD(N),(HFAD1:J,JI,J=1,11)
EXIT=1.
RETURN
1 IF(KBAL.NE.2) GO TO 4
K=J-1
WRITE (6,102) K
GO TO 3
4 CONTINUE
IF(KK.EQ.0) GO TO 2
IF(LINK.LT.4) GO TO 22
2 IF(1TM.EQ.0) GO TO 3
IF(ABS(XNA(N)).GT.ER(N).OR.ABS(XNB(N)).GT.ER(N)) GO TO 297
3 CONTINUE
YZRN)=YZRN
RETURN
101 FORMAT (1H0,12A4)
102 FORMAT ('WARNING. THE PARTIAL DERIVATIVE MATRIX MAY BE IN ERROR')
104 FORMAT (1H0,215,6G15.7/(11X,6G15.7))
105 FORMAT (1H0,8G15.7)
106 FORMAT (1H0,57X,4A4//6E20.5/6E20.5)
END
ITR01610
ITR01640
ITR01650
ITR01660
ITR01670
ITR01680
ITR01690
ITR01700
ITR01710
ITR01720
ITR01730
ITR01740
ITR01750
ITR01760
ITR01770
ITR01780
ITR01790
ITR01800
ITR01810
ITR01820
ITR01830
ITR01840
ITR01850
ITR01860
ITR01870
ITR01880
ITR01890
ITR01900
ITR01910
ITR01920
ITR01930
ITR01940
ITR01950
ITR01960
ITR01970
ITR01980
ITR01990
ITR02000
ITR02010
ITR02020
ITR02030
ITR02040
ITR02050

```

```

SUBROUTINE IVAP (EXIT, LINK, TAXL, TAXP, PILLGM?, AIM, AIM, AIR, AIRTR, AIRTR)
COMMON /STRIMA/
1  AY, VH, AGM, DT1(2), DT2(2), IXZ,
2  QMR, XXD, VYD, ZZD, ALGF, APFP, AYFP,
3  CGWL, COLL(6), CYCF(4), CYCL(3),
4  DIST, KCIT(20), PFDA(3), QMAX,
5  QMPS, TIME, TMAX, XCIT(20,6), ALGEZ,
6  ALGEL, ALGF2, CGSTA, CPMIC, DEXI2,
7  DIVIX, DTZY, DTZMT, DTZMI, DTZTL, FKTS,
8  HUBKM(2,2), HURKI(2,2),
9  KPFAD, PIU30, TSTAR(14), ZMAX2, ZMAX3,
10 AFECL, CYPMIC, GEARAT, PSD55,
11 P5STP, QX9PAK, PUOTND, ZDEL1, ZDEL2,
12 ZZ, VXS(2), VYS(2), VZS(2), BETA(12,2),
13 T, PCC(2), COSF(7,7,2), RETAN(2), RETAX(2), BETAZ(2),
14 AIR(2), APDD, APD0, AYD0, AIR(2),
15 DPSI(12,2), DTPR, PPSI(2), ZZTR,
16 RETAD(12,2), BNPST(2),
17 CONQ2, GMAXV, RATE), RATE?, STOP?,
18 THROT(2), TRIND, XGUST, RETAZD(2), GMAXV1,
19 SMAXV2, GMAXV3, GUSTYP, HNP5IP(2),
20 HURKPS, HURKRS, HURTPS, HURTRS,
21 KONEF5, LENGTH1, PILLGHI, PSTREF(2),
22 STAPT?, XMOHLI(12,2),
23 GM, PTR, ORM, ORTR, TIMI, TILT,
24 T2MT, T2TT, T2MT, T2TT, XMA), XMAIT,
25 XMA1, XMAIT, AIRPM, AIRPT, AIRRM, AIRRT,
26 APTD, APTD, APTD, APTD, PSD, PSDT,
27 XSTAHM, XSTAHM, YSTAMM, YSTAMT,
28 HURKP, HURKTP, HURKR, HURKTR
29 HAZETA, AZETA, VZETA, VZETAT
30 DATA PTR, MALFPI, PI, TWOP / .174679E-01, 1.570796, 3., 41593.6, 2.01195/
31 REAL LENGTH), LENGTH?
32 DIMENSION HURK(2,2), TAX(2), PSD(2)
33 EQUIVALENCE (HURK(1,1), HURKPI), (PSD(1), PSD)
34 XDELIMX1, X2, X3)=AMAX(X1, AMINI(X2, X3))
35 TAX(1)=TAXL
36 TAX(2)=TAXP
37 GO TO (1=1, K=READ
38 J=KCIT(1)
39 IF(J, L, 1, OR, J, GT, 31) GO TO 2013
40 IF((LNK, EQ, 1) GO TO 21
41 (F(J, EQ, 13) GO TO 209
42 IF(J, EQ, 14) GO TO 210
43 IF(J, EQ, 21) GO TO 219
44 IF(J, EQ, 22) GO TO 219
45 GO TO 220
46 CONTINUE
47 WRITE (6, 10P) J, (XCIT(L, K), K=1, 6)
48 IF(J, GT, 8) GO TO 221
49 GO TO (21, 232, 233, 234, 220, 236, 237, 236), J
50 DA=100./COLL(11)
51 GO TO 239
52 DA=100./CYCF(11)
53 GO TO 239

```

IVAR010C
IVAR0120
IVAR0130
IVAR0140
IVAR0150
IVAR0160
IVAR0170
IVAR0180
IVAR0190
IVAR0200
IVAR0210
IVAR0220
IVAR0230
IVAR0240
IVAR0250
IVAR0260
IVAR0270
IVAR0280
IVAR0290
IVAR0300
IVAR0310
IVAR0320
IVAR0330
IVAR0340
IVAR0350
IVAR0360
IVAR0370
IVAR0380
IVAR0390
IVAR0400
IVAR0410
IVAR0420
IVAR0430
IVAR0440
IVAR0450
IVAR0460
IVAR0470
IVAR0480
IVAR0490
IVAR0500
IVAR0510
IVAR0520
IVAR0530
IVAR0540

```

233 DA=100./CYCL(1)
GO TO 239
234 DA=100./PEDA(1)
GO TO 239
236 EA=0TR
GO TO 239
237 DA=1./PIU30
239 XCIT(L,2)=XCIT(L,2)*DA
XCIT(L,5)=XCIT(L,5)*DA
IF(XCIT(L,3).EQ.0.) GO TO 220
IF(XCIT(L,4).GE.XCIT(L,3).AND.XCIT(L,6).GE.XCIT(L,4)) GO TO 220
XCIT(L,4)=9999.
XCIT(L,6)=9999.
GO TO 220
221 IF(J.GT.12) GO TO 222
XGUST=XCIT(L,1)
GMAXV1=XCIT(L,2)
LNGTH1=XCIT(L,3)
START2=XCIT(L,4)+LNGTH1
LNGTH2=XCIT(L,5)
GMAXV2=XCIT(L,6)
STOP2=START2+LNGTH2
IF(J.EQ.10.OR.J.EQ.12) GO TO 223
RATE1=0.
IF(LNGTH1.NE.0.) RATE1=GMAXV1/LNGTH1
RATE2=0.
IF(LNGTH2.NE.0.) RATE2=GMAXV2/LNGTH2
GMAXV=GMAXV1+GMAXV2
GMAXV3=GMAXV1-START2*RATE2
GO TO 220
223 PILGH1=0.
IF(LNGTH1.NE.0.) PILGH1=P1/LNGTH1
PILGH2=0.
IF(LNGTH2.NE.0.) PILGH2=P1/LNGTH2
GO TO 220
222 K=J-12
GO TO (220,220,211,212,213,214,215,216,220,220,220,220,220,220,
1 211,282,283,284,286),K
209 XCIT(L,6)=XCIT(L,2)*OMR
GO TO 220
210 INDIC=XCIT(L,2)+.01
IF(INDIC.NE.2) GO TO 220
INDIC=XCIT(L,6)+.01
IF(INDIC.LT.1.OR.INDIC.GT.2) GO TO 2013
XCIT(L,5)=TAX(INDIC)
XCIT(L,2)=1.
GO TO 220
211 XCIT(L,2)=XCIT(L,2)*DTR
XCIT(L,3)=XCIT(L,3)/PEDA(3)
XCIT(L,4)=XCIT(L,4)/PEDA(3)
GO TO 220
212 IF(XCIT(L,2).EQ.0.) XCIT(L,2)=9999.
XCIT(L,5)=0.
IF(XCIT(L,4).NE.0.) XCIT(L,5)=XCIT(L,3)/XCIT(L,4)

```

```

IVAR0550
IVAR0560
IVAR0570
IVAR0580
IVAR0590
IVAR0600
IVAR0610
IVAR0620
IVAR0630
IVAR0640
IVAR0650
IVAR0660
IVAR0670
IVAR0680
IVAR0690
IVAR0700
IVAR0710
IVAR0720
IVAR0730
IVAR0740
IVAR0750
IVAR0760
IVAR0770
IVAR0780
IVAR0790
IVAR0800
IVAR0810
IVAR0820
IVAR0830
IVAR0840
IVAR0850
IVAR0860
IVAR0870
IVAR0880
IVAR0890
IVAR0900
IVAR0910
IVAR0920
IVAR0930
IVAR0940
IVAR0950
IVAR0960
IVAR0970
IVAR0980
IVAR0990
IVAR1000
IVAR1010
IVAR1020
IVAR1030
IVAR1040
IVAR1050
IVAR1060
IVAR1070
IVAR1080

```

```

GO TO 220
213 XCIT(L,2)=XCIT(L,2)*DTR
XCIT(L,5)=XCIT(L,5)*DTR
XCIT(L,4)=HALFPI/(HALFPI-XCIT(L,5))
XCIT(L,6)=-XCIT(L,6)*XCIT(L,4)/PIU3
GO TO 220
214 CONTINUE
XCIT(L,2)=XCIT(L,2)/PIU30
PSISTP=XCIT(L,3)*DTR
OMRRAK=XCIT(L,1)
GO TO 220
215 CONTINUE
XCIT(L,2)=XCIT(L,2)/CYCF(3)
XCIT(L,3)=XCIT(L,3)/CYCF(3)
XCIT(L,4)=XCIT(L,4)/CYCF(3)
XCIT(L,5)=XCIT(L,5)*DTR
GO TO 270
217 CONTINUE
XCIT(L,4)=XCIT(L,4)*DTR
XCIT(L,5)=XCIT(L,5)*DTR
GO TO 211
218 CONTINUE
IF(XCIT(L,6)-F0.0.) GO TO 217
XCIT(L,4)=A1M
XCIT(L,5)=R1M
GO TO 211
219 CONTINUE
IF(XCIT(L,6)-EQ.0.) GO TO 217
XCIT(L,4)=A1TR
XCIT(L,5)=B1TR
GO TO 211
216 XCIT(L,2)=XCIT(L,2)*TWOPI
XCIT(L,3)=XCIT(L,3)*XCIT(L,2)
K=XCIT(L,5)+.1
IF(K.LT.1.OR.K.GT.5) GO TO 2013
GO TO (271,272,273,274,275),K
280 CONTINUE
N=XCIT(L,1)+.1
HUBKM(1,N)=1.E+20
HUBKM(2,N)=1.E+20
XCIT(L,3)=XCIT(L,3)/PIU30
DRPM=XCIT(L,4)/PIU30-XCIT(L,3)
XCIT(L,2)=XCIT(L,2)*DTR
IF(DRPM.EQ.0.) GO TO 281
-HUBKM(1,N)=(HUBK(N,1)-XCIT(L,2))/DRPM
HUBKM(2,N)=(HUBK(N,2)-XCIT(L,2))/DRPM
281 CONTINUE
HUBKI(1,N)=XCIT(L,2)-HUBKM(1,N)*XCIT(L,3)
HUBKI(2,N)=XCIT(L,2)-HUBKM(2,N)*XCIT(L,3)
XCIT(L,3)=HUBK(N,1)
XCIT(L,4)=HUBK(N,2)
HUBK(N,1)=XDELIM(XCIT(L,3),XCIT(L,2),
1 HUBKM(1,N)*PS10(N)+HUBK(1,N))
HUBK(N,2)=XDELIM(XCIT(L,3),XCIT(L,2),

```

```

IVAR109A
IVAR110A
IVAR111A
IVAR112C
IVAR113C
IVAR1140
IVAR1150
IVAR1160
IVAR117A
IVAR1180
IVAR119A
IVAR119A
IVAR1200
IVAR1210
IVAR1220
IVAR1230
IVAR1240
IVAR1250
IVAR1260
IVAR127A
IVAR1280
IVAR1290
IVAR1300
IVAR1310
IVAR1320
IVAR133A
IVAR134C
IVAR135A
IVAR1360
IVAR1370
IVAR1380
IVAR1390
IVAR1400
IVAR1410
IVAR1420
IVAR1430
IVAR144A
IVAR145A
IVAR1460
IVAR1470
IVAR1480
IVAR1490
IVAR1500
IVAR151A
IVAR1520
IVAR1530
IVAR1540
IVAR154A
IVAR1560
IVAR1570
IVAR1580
IVAR1590
IVAR1600
IVAR1610
IVAR1620

```

```

1      GO TO 220
282 CONTINUE
   N=XCIT(L,1)+.1
   XCIT(L,5)=1.E+20
   XCI TL(3)=XCIT(L,3)/PIUJO
   DRPM=XCIT(L,4)/PIUJO-XCIT(L,3)
   XCIT(L,2)=XCIT(L,2)+DTR
   IF(DRPM.NE.C.) XCIT(L,5)=(BETAN(N)-XCIT(L,2))/DRPM
   XCIT(L,4)=XCIT(L,2)-XCIT(L,5)*XCIT(L,3)
   XCIT(L,3)=BETAN(N)
   XCIT(L,6)=0.
   GO TO 220
283 CONTINUE
   IF(XCIT(L,5).LE.0..OR.XCIT(L,5).GT.15.) XCIT(L,5)=15.
   XCIT(L,6)=0.
   GO TO 220
284 CONTINUE
   DO 285 K=3,5
   XCIT(L,K)=XCIT(L,K)+DTR
285 CONTINUE
   IF(XCIT(L,6).LT..5) XCIT(L,6)=.5
   XCIT(L,6)=XCIT(L,6)+DTR
   GO TO 220
286 CONTINUE
   IF(XCIT(L,3).LE.XCIT(L,1)) XCIT(L,3)=0000.
   IF(XCIT(L,5).LE.XCIT(L,3)) XCIT(L,5)=00000.
   GO TO 220
287 CONTINUE
   XCIT(L,3)=XCIT(L,3)+100./COLL(1)
   GO TO 220
288 XCIT(L,3)=XCIT(L,3)+100./CYCF(1)
   GO TO 220
289 XCIT(L,3)=XCIT(L,3)+100./CYCL(1)
   GO TO 220
290 XCIT(L,3)=XCIT(L,3)+100./PEDA(1)
   GO TO 220
291 CONTINUE
   XCIT(L,3)=XCIT(L,3)+DTR
292 CONTINUE
293 WRITE (6,2014) L,J
   EXIT=1.
   RETURN
2014 FORMAT (1H,25X,110,6F10.3)
END

```

```

IVAR1630
IVAR1640
IVAR1650
IVAR1660
IVAR1670
IVAR1680
IVAR1690
IVAR1700
IVAR1710
IVAR1720
IVAR1730
IVAR1740
IVAR1750
IVAR1760
IVAR1770
IVAR1780
IVAR1790
IVAR1800
IVAR1810
IVAR1820
IVAR1830
IVAR1840
IVAR1850
IVAR1860
IVAR1870
IVAR1880
IVAR1890
IVAR1900
IVAR1910
IVAR1920
IVAR1930
IVAR1940
IVAR1950
IVAR1960
IVAR1970
IVAR1980
IVAR1990
IVAR2000
IVAR2010
IVAR2020
IVAR2030
IVAR2040
IVAR2050
IVAR2060
IVAR2070
IVAR2080
IVAR2090

```

```

SUBROUTINE JACOBI
COMMON /STRIAB/ D(21),DY(21),F(79),F(19),X(10),
1 DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,FPD,ERR(10),KMI,KMO,
3 R12,SPD(6,6,3),XMI(21),XEL(14),
4 XFR(7),XFC(28),XFM(7),XFS(75),
5 XGM(7),XIT(21),XMR(49),XTR(49),
6 XMG(21),YMR(21),YTR(21),YMG(21),
7 YEL(21),YFM(21),BLCG,DAMP,DEPD(19),
8 CPDS,EPDX(10),MASS,OSV1,TRRS,TRRS,
9 WLCG,XCON(63),XJET(16),XMIN,AYEFP,
A RETAES(2),CMPCD,DHADO,DYDRD,GUESS,
B NPASS,PPHI(19,11),STAGG,YZERO,
C XMAST,OHADAO,DODCOL,DTRRSO,NY000R,
D ENGR,IM,XPASS,PSD30P,TRINDI,XLIMT
COMMON /MANAR/ I,V,IND,MMAG,APMT,ARMT,AYBMT,RETAO(2),TDELT,
1 PETAE(2),MGUSTF,MGUSTF,GFMD,GLAT,GVERT,
2 VGUSTM,YGUSTF,GFMD,ARD,AYD,
3 VXB,VZB,APD,VYR,ARD,AYD,
4 COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
5 APE,ARE,AIM,BIM,AITP,AITR,
6 YAR(2),YAR(2),ZAR(2),
7 VIMR,VITR,ZETA,ZETATR,HMR,MTR,
8 THR,TRR,OMX,OTR,YMRF,YTRF
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),EPSM,
1 NPART,NVARA,NVARR,NVARC,NSCALE
COMMON /KVARTR/ KVAR(10)
DIMENSION VAR(11)
EQUIVALENCE
20 55 L=1,KMI
HETA(1)=RETAES(1)
RETA(2)=RETAES(2)
THR=THPS
TTR=TTPS
VAR(KVAR(L))=VAR(KVAR(L))+DEPD(L)
IF(L.GT.1) VAR(KVAR(L-1))=VAR(KVAR(L-1))-DEPD(L-1)
CALL AJACOB
IF(EXIT.NE.0.) RETURN
IF(L.FO.1) DODCOL=(.5*(OMX+OTR)-OSV1)/DEPD(1)
20 41 K=1,KMI
41 PD(K,L)=(F(K)+PD(K,KMI+1))/EPD
55 CONTINUE
VAR(KVAR(KMI))=VAR(KVAR(KMI))-DEPD(KMI)
RETURN
END

```

JACO0010
JACO0020
JACO0030
JACO0040
JACO0050
JACO0060
JACO0070
JACO0080
JACO0090
JACO0100
JACO0110
JACO0120
JACO0130
JACO0140
JACO0150
JACO0160
JACO0170
JACO0180
JACO0190
JACO0200
JACO0210
JACO0220
JACO0230
JACO0240
JACO0250
JACO0260
JACO0270
JACO0280
JACO0290
JACO0300
JACO0310
JACO0320
JACO0330
JACO0340
JACO0350
JACO0360
JACO0370
JACO0380
JACO0390
JACO0400
JACO0410
JACO0420
JACO0430
JACO0440
JACO0450

LAM00010
 LAM00020
 LAM00030
 LAM00040
 LAM00050
 LAM00060
 LAM00070
 LAM00080
 LAM00090
 LAM00100
 LAM00110
 LAM00120
 LAM00130
 LAM00140
 LAM00150
 LAM00160
 LAM00170
 LAM00180
 LAM00190
 LAM00200
 LAM00210
 LAM00220
 LAM00230
 LAM00240
 LAM00250
 LAM00260
 LAM00270
 LAM00280
 LAM00290
 LAM00300
 LAM00310
 LAM00320
 LAM00330
 LAM00340
 LAM00350
 LAM00360
 LAM00370
 LAM00380
 LAM00390
 LAM00400
 LAM00410
 LAM00420
 LAM00430
 LAM00440
 LAM00450
 LAM00460
 LAM00470
 LAM00480
 LAM00490
 LAM00500
 LAM00510
 LAM00520
 LAM00530
 LAM00540

```

SUBROUTINE LAMODE (V,QMG,ZFM,SWING)
COMMON /STRIB/ D(21),DT(21),E(19),F(10),X(10),
1 DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPD,EPR(10),KML,RMO,
3 R12,SPD(6,6,3),XDM(21),XEL(14),
4 XER(7),XFC(28),XFM(7),XFS(35),
5 XGN(7),XIT(21),XMP(49),XTR(49),
6 XWG(21),YMR(21),YTR(21),YWG(21),
7 YEL(21),YFN(21),BLCG,XDAMP,DEPO(10),

      DAMP MUST HAVE ITS NAME CHANGED HERE TO AVOID
      CONFLICT WITH COMMON /TRONIC/

      EPDS,EPDX(10),MASS,OSVI,TM,S,ITRS,
      WLCG,XCOM(63),XJET(14),XIRM,AYEFP,
      BETAES(2),CMPCD,DMADO,DYDOR,GUESS,
      NPASS,PDPHI(10,11),STACG,TZERO,
      XMAST,DMADAO,DOCDL,DTRRSO,DYDOR,
      ENGRPH,MXPASS,PSD3OP,TRIMDI,XLIMIT

COMMON /TRONIC/ UU(6),VV(6),TAU(22),DAMP(22),MUMRTS,GAINB,
1 INDEX,STGAIN(6),TSTAR,COELTD,SLOT(3,9)
2 DIMENSION PLMODE(6),FLMODE(6),THLFDB(6),TZEROM(6),
3 FANG2(6),ROOT(2,3), ZLNT1(6),FANG1(6),ZLNT2(6)
4 DIMENSION UDSLOT(11,3),HEAD(2),KS(3),LS(2)
5 DATA HEAD/ 0, 0, 0, KS/2,6,4/,LS/3,4/
6 REAL IX, IZ,MASS
7 COMPLEX ROOT
8 WRITE (6,556)
9 DO 333 J=1,3
10 DO 333 I=1,9
11 DO 333 J=1,4
12 PLMODE(I)=0
13 FLMODE(I)=0
14 THLFDB(I)=0
15 TZEROM(I)=0
16 CONTINUE
17 TSTAR=SWING/(2.*V)
18 SLOT(1,2)=MASS
19 SLOT(1,3)=-SPD(4,4,1)
20 SLOT(1,5)=-SPD(5,4,1)/V
21 SLOT(1,6)=-ZFM/V
22 SLOT(1,9)=MASS-SPD(6,4,1)/V
23 SLOT(2,3)=-SPD(4,5,1)
24 SLOT(2,4)=IX/V
25 SLOT(2,5)=-SPD(5,5,1)/V
26 SLOT(2,8)=-XFS(11)/V
27 SLOT(2,9)=-SPD(6,5,1)/V
28 SLOT(3,3)=-SPD(4,6,1)
29 SLOT(3,4)=SLOT(2,9)
30 SLOT(3,5)=-SPD(5,6,1)/V
31 SLOT(3,8)=IZ/V
32 SLOT(3,9)=-SPD(6,6,1)/V
33 WRITE (4,557) HEAD(1)
  
```

```

WRITE (6,555) ISLOT(I,J),J=(I,9),PD(2,3),PD(2,4),ISLOT(2,J),J=(1,9),LAMO550
1      PD(6,3),PD(6,4),ISLOT(3,J),J=(1,9),PD(4,3),PD(4,4) LAMO560
WRITE (6,557) HEAD(2) LAMO570
JIV)=2.90MG0V LAMO580
DIV2=DIVI*SMING LAMO590
CALL MODSLOT (DIVI, DIV2, TSTAR, PD, SLOT, J), KS, LS, UOSLOT, TSTAR) LAMO600
WRITE (6,555) UOSLOT LAMO610
WRITE(6,777) LAMO620
CALL SRT LAMO630
INDEX=6 LAMO640
CALL ELEC (GAINB) LAMO650
DO 807 (I=1, NUMRTS) LAMO660
IF(UU(I).EQ..0.AND.VV(I).EQ..0) GO TO 899 LAMO670
IF(VV(I).EQ..0)GO TO 85) LAMO680
PLMODE(I)=6.2832/ABSIVV(I) LAMO690
FLMODE(I)=1./PLMODE(I) LAMO700
45) IF(UU(I).EQ..0) GO TO 899 LAMO710
THLFD8(I)=.69315/ABS(UU(I)) LAMO720
GO TO 807 LAMO730
899 (ZERON(I)=1 LAMO740
907 CONTINUE LAMO750
DO 465 (I=1, NUMRTS) LAMO760
IF(I2FROM(I).NE.0) GO TO 465 LAMO770
REL=UU(I)*SLOT(I,2) *SLOT(I,3) LAMO780
ZPRT=VV(I)*SLOT(I,2) LAMO790
ROO(I,1)=CPLX(RELP,ZPRT) LAMO800
ROO(I,2)=CPLX(SLOT(I,9),.7) LAMO810
ZELP=-(UU(I)*SLOT(I,5) *SLOT(I,6) ) LAMO820
ZPRT= -VV(I)*SLOT(I,5) LAMO830
ROO(I,3)=CPLX(RELP,ZPRT) LAMO840
ROO(I,4)= CMLX(SLOT(2,3),.0) LAMO850
REL = UU(I)*SLOT(2,8) *SLOT(2,9) LAMO860
ZPRT = VV(I)*SLOT(2,8) LAMO870
ROO(I,2,2)=CPLX(RELP,ZPRT) LAMO880
REL =-(UU(I)*SLOT(2,6) *SLOT(2,4) *UU(I)*SLOT(2,5) ) LAMO890
ZPRT =-( 2.*UU(I)*VV(I)*SLOT(2,6) *VV(I)*SLOT(2,5) ) LAMO900
ROO(I,2,3)=CPLX(RELP,ZPRT) LAMO910
CALL COMSOL (ROO(I,1,ZPT),RPT(I,ZPT),RPT2,ZPT2) LAMO920
ZLNT(I)=SORT( RPT1,RPT1,ZPT)*ZPT) LAMO930
IF(RPT).EQ..0) GO TO 463 LAMO940
FANG(I)=57.30ATAN2(ZPT1,RPT1) LAMO950
GO TO 464 LAMO960
463 FANG(I)=90. LAMO970
464 ZLNT2(I)= SORT((RPT2*UU(I)*ZPT2*VV(I))**2 *ZPT2*UU(I)-RPT2*
(VV(I)**2)/(UU(I)**2*VV(I)**2) LAMO980
IF(RPT2.EQ..0) GO TO 464 LAMO990
FANG2(I)=57.30ATAN2(ZPT2*UU(I)-RPT2*VV(I)),(RPT2*UU(I)*ZPT2*VV(I)
1) LAMO1000
GO TO 466 LAMO1010
464 FANG2(I)=90. LAMO1020
466 CONTINUE LAMO1030
465 CONTINUE LAMO1040
DO 828 (I=1, NUMRTS) LAMO1050
IF(VV(I).LT..0) GO TO 828 LAMO1060
LAMO1070
LAMO1080

```

```

IF(IZEROM(I),ME,0) GO TO 926
WRITE(6,729)U(I),VV(I),PLMODE(I),FLMODE(I),TMLF08(I),ZLMT1(I),FANL,AM01100
151(I),ZLMT2(I),FANG2(I),COELTD
A28 CONTINUE
I=1
CALL MODE (PD,V,I)
RETURN
727 FORMAT (1M0,5X,'CONTROLS FIXED',7X,'R D O T S',46X, 'SIDE SLAM01160
1L',7X,'ROLL ANG.',8X,'YAW ANG./ROLL ANG.',7X,'REAL',8X,'IMAG.',8X,'PELAM01170
2X',8X,'FREQ. T HALF-DRL',6X,'MAGN.',9X,'PHASE',7X,'MAGN.',LAM01180
3,8X,'PHASF',5X,'LEAD COEF.',)
729 FORMAT(1H ,10G13.5)
556 FORMAT (1M1,60X,'LATERAL MODE')
557 FORMAT (1M0,38X,A4,
1 'DIMENSIONAL COEFFICIENTS OF CHARACTERISTIC EQUATIONS'
2 /, 8X,'BETA-S',6X,'BETA',9X,'PHI-S',6X,'PHI-S',
3 9X,'PHI',8X,'R-S',6X,'R-S',11X,'R',7X,
4 'LAT CYCLIC PEDAL')
555 FORMAT (1M ,G10.2,10G12.5)
END
LAM01099
LAM01100
LAM01110
LAM01120
LAM01130
LAM01140
LAM01150
LAM01160
LAM01170
LAM01180
LAM01190
LAM01200
LAM01210
LAM01220
LAM01230
LAM01240
LAM01250
LAM01260
LAM01270
LAM01280

```

```

SUBROUTINE LMODE (V,OMG,XFM,ZFM,CWING,XAELE)
COMMON /STR(AB/ D(21),DT(21),E(79),F(10),X(10),
1 DL,DM,ON,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 XTR,FPD,ERR(10),KML,RMD,
3 R12,SPD(6,6,3),XRM(21),XEL(14),
4 XER(7),XFC(28),XFN(7),XFS(35),
5 XGN(7),XIT(21),XMR(49),XTR(49),
6 XMG(21),YMR(21),YTP(21),YMG(21),
7 YEL(21),YFN(21),ALCG,XDAMP,DEPD(10),
8
9 FPOS,EPDX(10),MASS,QSV1,THRS,TTAS,
A WLCG,XCON(63),XJET(14),XMIN,AYEFP,
B XTAFS(7),CMPCO,DMADO,DYADR,GUESS,
C NPASS,PPHI(10,11),STACG,TZERO,
D XMAST,DMADAO,DDCOL,DYRSQ,DYBDB9,
E ENGRPH,XPASS,PSO3OP,TRIND1,XLIMIT
COMMON /STANRO/ J,W,ITM,VMS(2),LINK,OELE,VROT(2),
1 VSND,YFIN(2),ZFEL(2),AIBAL(2),
2 RIBAL(2),CONDI,SWING,PILGM2,PMGELL,
3 RM,ATR,PHOMM,PHONT,RHOMM,RHOMT
COMMON /TRONIC/ UUI(4),VV(6),TAU(22),DAMP(22),MURTS,GAINR,
1 IMDEX,STGAIN(6),TSTAR,DELTD,SLOT(3,9)
REAL IV,MASS
DIMENSION PLMODE(6),FLMODE(6),THL FDB(6),TZEROM(6),
1 FANG2(6),ROOT(2,3), ZLNT(6),FANGI(6),ZLNT2(6)
DIMENSION JDSLOT(11,3),HEADI(1),KS(3),LS(2)
DATA HEAD/ NON-1/ KS/1,3,5/,LS/2,1/
COMPLEX ROOIT
WRITE (6,556)
DO 70A I=1,4
PLMODE(I)=0
FLMODE(I)=0
THL FDB(I)=0
TZEROM(I)=0
70A CONTINUE
DO 703 I=1,3
DO 703 J=1,9
SLNT(I,J)=0
703 CONTINUE
TSTAR=CWING/(2*V)
SLNT(1,2)=MASS
SLNT(1,3)=-SPD(1,1,1)
SLNT(1,6)=-SPD(2,1,1)
SLNT(1,9)=-SPD(3,1,1)/V
SLNT(1,9)=ZFM/V
SLNT(2,3)=-SPD(1,2,1)
SLNT(2,9)=VFL(17)*OELE*XAELE*YMG(17)*PMGELL*YMG(18)*YEL(18)*OTRARSO/
1 ((3.+YMG(19))*(3.+YEL(18))*(1.-((V*VSNDR)*2)))
SLNT(2,5)=MASS-CZADE
SLNT(2,9)=-SPD(2,2,1)
SLNT(2,9)=-((MASS*SPD(3,2,1))/V)

```

```

LM000010
LM000020
LM000030
LM000040
LM000050
LM000060
LM000070
LM000080
LM000090
LM000100
LM000110
LM000120
LM000130
LM000140
LM000150
LM000160
LM000170
LM000180
LM000190
LM000200
LM000210
LM000220
LM000230
LM000240
LM000250
LM000260
LM000270
LM000280
LM000290
LM000300
LM000310
LM000320
LM000330
LM000340
LM000350
LM000360
LM000370
LM000380
LM000390
LM000400
LM000410
LM000420
LM000430
LM000440
LM000450
LM000460
LM000470
LM000480
LM000490
LM000500
LM000510
LM000520
LM000530
LM000540

```

OAMP MUST HAVE ITS NAME CHANGED HERE TO AVOID
CONFLICT WITH COMMON /TRONIC/

```

SLOT(2,9)=XFW/V
SLOT(3,3)=SPO(1,3,1)
SLOT(3,5)=CZADEXAELE
SLOT(3,6)=SPO(2,3,1)
SLOT(3,7)=IV/V
SLOT(3,8)=SPO(3,3,1)/V
WRITE (6,557) HEAD(1)
WRITE (6,558) (SLOT(1,J),J=1,9),PD(1,2),PD(1,1),(SLOT(2,J),J=1,9),
LM000630 PD(3,2),PD(3,1)-(SLOT(3,J),J=1,9),PD(5,2),PD(5,1)
WRITE (6,557) HEAD(2)
)IV2=2.00MG/V
)IV1=DIV2*CMING
CALL MDSLOT (OTV1,OTV2,TSTAR,PO,SLOT,3,KS,LS,UDSLOT,1,1)
WRITE (6,555) UDSLOT
WRITE (6,727)
CALL SRT
INDEX=6
CALL ELEC (GAINB)
NO 707 I=1,NUMPTS
IF (UJ(1),EQ.,C.AMO.VV(1),EQ.,0) GO TO 799
IF (VV(1),EQ.,0) GO TO 751
PLMODE(1)=6.2832/ABS(VV(1))
CLMDF(1)=1./PLMODE(1)
751 IF (UU(1),EQ.,0) GO TO 799
TMLFDA(1)=.69315/ABS(UU(1))
GO TO 707
799 (ZEROM(1)=1
707 CONTINUE
DO 365 I=1,NUMPTS
IF (ZEROM(I),NE.,0) GO TO 365
R00NT(1,1)=CMLX(SLOT(2,3),0)
RELPL=UU(1)*SLOT(2,5)+SLOT(2,6)
ZPRT=VV(1)*SLOT(2,5)
P00NT(1,2)=CMLX(RELP,ZPRT)
RELPL=SLOT(2,7)*VV(1)+UU(1)*VV(1)-SLOT(2,8)*UU(1)
-SLOT(2,9)
ZPRT=-(2.*UU(1)*VV(1)+SLOT(2,7)+VV(1)*SLOT(2,8))
R00NT(1,3)=CMLX(RELP,ZPRT)
R00NT(2,1)=CMLX(SLOT(3,1),0)
RELPL=SLOT(3,5)*UU(1)+SLOT(3,6)
ZPRT=VV(1)*SLOT(3,5)
R00NT(2,2)=CMLX(RELP,ZPRT)
RELPL=-(SLOT(3,7)*2.*UU(1)*UU(1)-VV(1)*VV(1)+SLOT(3,8)*UU(1))
ZPRT=-(SLOT(3,7)*2.*UU(1)*VV(1)+SLOT(3,8)*VV(1))
R00NT(2,3)=CMLX(RELP,ZPRT)
CALL CONSOL (R00NT,RPRT1,ZPT1,RPRT2,ZPT2)
ZLNT(1)=SORT( RPRT1 ,02 + ZPT1 ,02)
IF (RPRT1 ,EQ.,0) GO TO 363
FANG1(1)=ATAN2(ZPT1,RPRT1)/OTR
)N TO 364
363 FANG1(1)=.90
364 ZLNT(1)= SORT(RPRT2,02 + ZPT2,02)
IF (RPRT2 ,EQ.,0) GO TO 3645
FANG2(1)=ATAN2(ZPT2,RPRT2)/OTR

```

```

50 TO 366
365 F2 Z(1)=FANG1(1)*90.
366 CONTINUE
365 CONTINUE
70 72# I=1,NUMRTS
IF(VV(1).LT..C) GO TO 72A
IF(IZERFRM(1).NE.C)GO TO 72A
WRITE(6,729) UU(1),VV(1),PLMODE(1),FLMODE(1),TMLFDR(1),ZLMT(1),
1 FANG1(1),ZLNT2(1),FANG2(1),COELTD
72A CONTINUE
1=7
CALL MODE (PD,V,1)
RETURN
727 FORMAT (1M0,5BX,CONTROLS FIXED,7X,R 0 0 T S,6AX, *FMD,VELMOD1220
1L/TMETHA,15X,ALPHA/TMETHA,75X,REAL,8X,IMAG,8X,PERIOD,5X,FLMOD1230
2FREQUENCY T,HALF-OBL,6X,MAGN,9X,PHASE,7X,MAGN,8X,PHAS,FLMOD1240
3,5X,LEAD COEF,1)
729 FORMAT(1M,10G13.5)
556 FORMAT (1M1,57X,(LONGITUDINAL MODE))
557 FORMAT (1M0,7AX,44,
1 *DIMENSIONAL COEFFICIENTS OF CHARACTERISTIC EQUATIONS*
2 /3X,U-See? U-S,11X,U,6X,ALPHA-See? ALPHA-S,
3 6X,ALPHA THETA-See? THETA-S,7X,THETA,5X
4 *FA CYCLIC COLLEC.**)
555 FORMAT (1M,610,?,10G12.5)
FMD
LMO01090
LMO01100
LMO01110
LMO01120
LMO01130
LMO01140
LMO01150
LMO01160
LMO01170
LMO01180
LMO01190
LMO01200
LMO01210
LMO01220
LMO01230
LMO01240
LMO01250
LMO01260
LMO01270
LMO01280
LMO01290
LMO01300
LMO01310
LMO01320
LMO01330
LMO01340

```

SUBROUTINE MAMU

COMMON /FORCE/ XF, XFRMG, XFLWG, XFELE, XFFUS, XFRJET,
 XFLJET, XFRM, XFR, XFGUM, XFFIN, XFM,
 YF, YFFUS, YFRJET, YFLJET, YFRM, YFR,
 YFGUM, YFFIN, YFM,
 ZF, ZFRMG, ZFLWG, ZFELE, ZFFUS, ZFRJET,
 ZFLJET, ZFRM, ZFR, ZFGUM, ZFFIN,
 OL, LRMG, LLWG, LELF, LFUS, LRJET, LLJET,
 LMR, LTR, LGUM, LFIN, LQMR, LQTR,
 OM, MRMG, MLWG, MELE, MFUS, MRJET, MLJET,
 MMR, MTR, MGUM, MFIN, MQMR, MQTR,
 OM, MRMG, MLWG, MELE, MFUS, MRJET, MLJET,
 MMR, MTR, MGUM, MFIN, MQMR, MQTR,
 COMMON /STRIMA/ AV, VM, AGM, DT1(2), DT2(2), IXZ,
 OMR, XIX, YYD, ZZD, ALGF, APPP, AYFP,
 CGWL, COLL(6), CYCF(3), CYCL(3),
 JIST, KCIT(20), PEDA(3), OMAX,
 OMS, TIME, TMAX, XCIT(20, 6), ALGEZ,
 ALGEL, ALGEZ, CGSTA, CPWIC, DIXIZ,
 DIVIX, DIZIV, DTZMY, DTZMI, DTZTI, FTKTS,
 HUBKM(2, 2), MURKI(2, 2),
 KREAD, PIUTO, TSTAB(14), ZMAX2, ZMAX3,
 ASECOL, CYPWIC, GEARAT, PS050,
 PSTSTP, QDBAK, RUDIM, ZDELTI, ZDELTI,
 HL(2), KX, YV, AV1, GOV, KPO, OPC, OOO,
 COMMON /STAMAN/
 1 RIV, APRG, ARBG, ASEP, AVBG, BMTG,
 2 RC, BMTK, BMTM, CGBL, DPIK, DPIZ,
 3 FMPT(2), R550, ALEPT, AYDMK, DELT2,
 4 DPIKZ, DTMT, DMCG, MDLT, MGUST,
 5 MLTR1, MLTR2, ITORS, KTCTR, OMEGM,
 6 PCDEL, OMSA, RMAS, TRALT, TMOPI, VGUST,
 7 ISTOP, XAGUM, XAPYL, XARSP(2), YAGUM,
 8 YARSP(2), YGUST, YAGUM, ZAPYL, ZARSP(2),
 9 DELT2R, NSTAGC, EIMAST, GPRED, HLPYLD,
 4 IBRAKE, OMEGM, ORRAKE, BETAZS(2),
 PCGDED, PCGNAX, PCRATE, P0IDTR, RDELTI,
 *DELT2, RITORS, TRINDZ
 COMMON /MANAL /
 1 O, AP, PED, OMG, TZM, YIM, TZM,
 2 TZT, YIT, YZT, ALEL, CZET, PSDD,
 3 SZFT, TAXL, TAXR, XAWG, XLMK(16), ZAWG,
 4 ALCYP, ALFIN, ALLWG, ALRWG, CDELE, CDFIN,
 5 COLWG, CDRMS, CLELE, CLFIN, CLLWG, CLRWG, CMING,
 6 CYCRL, CYCR2, CZET4, CZET6, CZET9, RANGE,
 7 SZETS, SZETT, SZETR, WCOL, XAELE, XAFIN,
 8 XAFUS, XAJFT, YAFIN, ZAELE, ZAFIN, ZAFUS,
 9 YAFLE, YAFUS, YALWG, YARWG, YALJFT, YARJET,
 4 ZAJET, ALECR1, ALGFPO, BOTTOM, CZET11,
 5 CZET12, CZET13, FIZETA, HALFPI, SZET10,
 6 XAPYLD, YGUSTM, ZAPYLD, ZFLWG1, ZFRWG1,
 7 TZMS, T1MS, T2MS, TZTS, T1TS, T2TS,
 8 CLOCK, FLOCK, XLOCK, TLOCK
 COMMON /ROMAN/
 1 ZZ, VXS(2), VYS(2), VZS(2), BETA(12, 2),
 2 T, PCC(2), CODE(7, 7, 2), BETAM(2), BETAK(2), BETAZ(2),
 3 AI(9(2), APDD, ARDD, AYDD, AIR(2),

MAMU0010
 MAMU0020
 MAMU0030
 MAMU0040
 MAMU0050
 MAMU0060
 MAMU0070
 MAMU0080
 MAMU0090
 MAMU0100
 MAMU0110
 MAMU0120
 MAMU0130
 MAMU0140
 MAMU0150
 MAMU0160
 MAMU0170
 MAMU0180
 MAMU0190
 MAMU0200
 MAMU0210
 MAMU0220
 MAMU0230
 MAMU0240
 MAMU0250
 MAMU0260
 MAMU0270
 MAMU0280
 MAMU0290
 MAMU0300
 MAMU0310
 MAMU0320
 MAMU0330
 MAMU0340
 MAMU0350
 MAMU0360
 MAMU0370
 MAMU0380
 MAMU0390
 MAMU0400
 MAMU0410
 MAMU0420
 MAMU0430
 MAMU0440
 MAMU0450
 MAMU0460
 MAMU0470
 MAMU0480
 MAMU0490
 MAMU0500
 MAMU0510
 MAMU0520
 MAMU0530
 MAMU0540

```

MANU0550
MANU0560
MANU0570
MANU0580
MANU0590
MANU0600
MANU0610
MANU0620
MANU0630
MANU0640
MANU0650
MANU0660
MANU0670
MANU0680
MANU0690
MANU0700
MANU0710
MANU0720
MANU0730
MANU0740
MANU0750
MANU0760
MANU0770
MANU0780
MANU0790
MANU0800
MANU0810
MANU0820
MANU0830
MANU0840
MANU0850
MANU0860
MANU0870
MANU0880
MANU0890
MANU0900
MANU0910
MANU0920
MANU0930
MANU0940
MANU0950
MANU0960
MANU0970
MANU0980
MANU0990
MANU1000
MANU1010
MANU1020
MANU1030
MANU1040
MANU1050
MANU1060
MANU1070
MANU1080

NPSI(12,7),NTRR,NPSI(2),ZZTR,
9ETAD(12,2),ANPSI(2),
COMD2,GMAXV,RATE1,RATE2,STOP2,
THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
GMAXV2,GMAXV3,GUSTYP,MNPSIR(2),
HUBKPS,HUBKRS,HUBTPS,HUBTRS,
KONFIG,LNGTHI,PILGH1,PSIREF(2),
START2,XMOML1(12,2),
RM,RTR,ORM,ORTR,TIMT,TILT,
T2MT,T2TT,TZMT,TZTT,XM1,XM1T,
XM01,XM01T,AT0PM,AT0PT,ATARM,AT0RT,
APT0,APT0D,ART0,ART0D,PSD,PS0T,
XSTAMH,XSTAMT,YSTAMH,YSTAMT,
HUBKP,HUBKTP,HUBKR,HUBKTR
, AZETA,AZETAT,VZETA,VZETAT
COMMON /MANAPO/ I,V,IND,NMAG,APRMT,ARBMT,AYBMT,BETA0(2),TDELT,
MEYAE(2),HGUSTE,HGUSTF,HGUSTM,HGUSTE,
VGUSTM,VGUSTF,GFWD,GLAT,GVERT,
VXB,VZB,APD,VVB,ARD,AYD,
COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
APE,ARE,AIM,BIM,AITR,BITR,
YAR(2),YAR(2),ZAR(2),
VIMR,VITR,ZETA,ZETATR,NMR,MTR,
TMR,TTR,OMX,OTR,YMRF,YTRF
COMMON /TOPLOT/ AM(3),AL(3),EXIT,ICM(49),IPSN,
MPART,NVARA,NVARB,NVARC,NSCALE
,NVAR,NPRINT,NTIME
COMMON /FORY/ Y(4,150),OLD(4,2)
COMMON /STANRD/ J,W,(TM,VMS(2),LINK
DATA FOURPI/12.56637/
REAL LP, NP,IXZ,ITORS
DIMENSION A(266),PSID(2),FLAP(2,2),HUBKS(2,2),HUBK(2,2),
; FOUVALENCE (A(1),Y(1,1)),(PSID(1),PSD),(FLAP(1,1),A1M),
1 (AP0R(1),ART0D),(AP0R(1),APT0)
2 (HUBKS(1,1),HUBKPS),(HUBK(1,1),HUBKP)
XDELIM(X1,X2,X3)-AMAX1(X1,AMIM)(X2,X3)

PART 3. ELEVEN DEGREE OF FREEDOM MANEUVER SECTION

SYMBOL IDENTIFICATION

V(1, 1) VXB VELOCITY X-COMPONENT BODY REFERENCE
V(1, 2) VVB VELOCITY Y-COMPONENT BODY REFERENCE
V(1, 3) VZB VELOCITY Z-COMPONENT BODY REFERENCE
V(1, 4) AVD VELOCITY YAW-COMPONENT BODY REFERENCE
V(1, 5) APD VELOCITY PITCH-COMPONENT BODY REFERENCE
V(1, 6) ARD VELOCITY ROLL-COMPONENT BODY REFERENCE
V(1, 9) PSD VELOCITY RPM-COMPONENT YPP REFERENCE
V(1,10) AVE EULER ANGLE YAW-COMPONENT FIXED TO BODY
V(1,11) APE EULER ANGLE PITCH-COMPONENT FIXED TO BODY
V(1,12) ARE EULER ANGLE ROLL-COMPONENT FIXED TO BODY
V(1,13) DT0MT DISP DELTA T2M FROM 00BMT ROTOR REFERENCE
V(1,14) DT0MTD VFL DELTA T2M FROM 00BMT ROTOR REFERENCE

```

Y(1.15)	XX	DISPLACEMENT	X-COMPONENT	FIXED REFERENCE	MANU1090
Y(1.16)	YY	DISPLACEMENT	Y-COMPONENT	FIXED REFERENCE	MANU1100
Y(1.17)	ZZ	DISPLACEMENT	Z-COMPONENT	FIXED REFERENCE	MANU1110
Y(1.76)	VX80	ACCELERATION	X-COMPONENT	BODY REFERENCE	MANU1120
Y(1.77)	VY80	ACCELERATION	Y-COMPONENT	BODY REFERENCE	MANU1130
Y(1.78)	VZ80	ACCELERATION	Z-COMPONENT	BODY REFERENCE	MANU1140
Y(1.79)	A7DD	ACCELERATION	YAW-COMPONENT	BODY REFERENCE	MANU1150
Y(1.80)	APOD	ACCELERATION	PITCH-COMPONENT	BODY REFERENCE	MANU1160
Y(1.81)	ARDD	ACCELERATION	ROLL-COMPONENT	BODY REFERENCE	MANU1170
Y(1.84)	PSDD	ACCELERATION	RPM-COMPONENT	TPP REFERENCE	MANU1180
Y(1.85)	AYED	FUL.ANG.VEL.	YAW-COMPONENT	FIXED TO BODY	MANU1190
Y(1.86)	APFD	FUL.ANG.VEL.	PITCH-COMPONENT	FIXED TO BODY	MANU1200
Y(1.87)	AREO	FUL.ANG.VEL.	ROLL-COMPONENT	FIXED TO BODY	MANU1210
Y(1.98)	OTAMTD	VEL	DELTA TZM	ROTOR REFERENCE	MANU1220
Y(1.89)	OTAMTD	ACCEL	DELTA TZM FROM BOBWT	ROTOR REFERENCE	MANU1230
Y(1.91)	XXD	VELOCITY	X-COMPONENT	FIXED REFERENCE	MANU1240
Y(1.91)	YYD	VELOCITY	Y-COMPONENT	FIXED REFERENCE	MANU1250
Y(1.92)	ZZD	VELOCITY	Z-COMPONENT	FIXED REFERENCE	MANU1260


```

IF (VARS.NE.0) GO TO 299
QBRAF=C.
ICAM=C
I=1
LINK=1
LINK=5
SG=1.
DO 297 N=1,2
NPSIN=NPSI(N)
IF (NPSIN.EQ.0) GO TO 297
CALL ROTAN (N)
DLD(1,N)=FLAP12,N)*SG
DLD(2,N)=FLAP1
DLD(3,N)=TAN(OLD(1,N))
DLD(4,N)=(COS(BETAZ(N))-OLD(1,N))*0.02+(SG*ORDR(N)-ARD)/
(COS(OLD(1,N))*0.02-PSID(N)+TAN(FLAP11,N))
SG=SG
L=70N
DO 296 K=1,NPSIN
L=L*2
Y(1,L*1)=BETA1K,N)
Y(1,L*2)=BETA2K,N)
Y(1,L*3)=BETA3K,N)
296 CONTINUE
297 CONTINUE
END=C
LINK=4
294 ADELTA=SDDELTA
295 DELT1=1./DELTA
296 DELT2=2.*DELTA
IF (ICTP.FO.C) GO TO 210
295 CONTINUE
VARS=C
IF (TIME.LT.TMAX) GO TO 350
VT=VART(T)

```

```

9250 GO TO (9060,9061,11), KICR
      TDELT=ZDELT?
      TMAX=ZMAX?
      MMAG=C
      IF (WAB.FO.2) MMAG=1
      GO TO 299
9061 TDELT=ZDELT
      TMAX=ZMAX
      MMAG=C
      GO TO 299
C      ***** TIME LOOP *****
C      *****
210 CONTINUE
      IF (Y(1,7).GE.TWOP) Y(1,7)=Y(1,7)-TWOP
      IF (Y(1,8).GE.TWOP) Y(1,8)=Y(1,8)-TWOP
      OTZM=RETAE(1)*DCC(1)
      OTZ1=RETAE(2)*DCC(2)
      TO 212 N=1,2
      RETAZD(1)=0.
      BETA(1)=BETAZ(N)+RETAE(N)
      IF (MPSI(N).EQ.0) GO TO 212
      IF (M.EQ.1) GO TO 208
      AYRM=AYBMT
      APBM=APBMT
      ARBM=ARBMT
      GO TO 207
208 CONTINUE
      AYBM=C.
      APBM=ZETA
      ARBM=C.
209 CONTINUE
      CALL RATS (ARD,ARD,AYD,AYRM,APRM,ARSM,ARDM,APDM,AYDM,-1)
      RET1=Y(1,7)*M+11-BETAZ(N)
      BETA2=Y(1,7)*M+12-BETAZ(N)
      TAMB1=TAN(BETA1)
      TAMB2=TAN(BETA2)
      DPS12=DPSI(2,N)
      SIM2=SIN(DPS12)
      SIM1=SIN(V(1,M+6))
      COS1=COS(V(1,M+6))
      RET1D=Y(1,7)*M+25
      RET2D=Y(1,7)*M+26
      IF (ABS(SIM2).GT..0001) GO TO 209
      RET42=OLD(1,N)
      DPS12=PSIREF(N)-OLD(2,N)
      TAMB2=OLD(3,N)
      BETA2D=OLD(4,N)
      SIM2=SIN(DPS12)
      IF (PSID(N).NE.C.) GO TO 209
      TAMB1=O.
      TAMB1=O.
      IF (COS1.GE..707) TAMB1=-TAMB1/COS1
      IF (COS1.LT..707) TAMB1=-TAMB1/SIM1
      APDR(N)=BETA1D+COS1*APDM

```

```

MANU1630
MANU1640
MANU1650
MANU1660
MANU1670
MANU1680
MANU1690
MANU1700
MANU1710
MANU1720
MANU1730
MANU1740
MANU1750
MANU1760
MANU1770
MANU1780
MANU1790
MANU1800
MANU1810
MANU1820
MANU1830
MANU1840
MANU1850
MANU1860
MANU1870
MANU1880
MANU1890
MANU1900
MANU1910
MANU1920
MANU1930
MANU1940
MANU1950
MANU1960
MANU1970
MANU1980
MANU1990
MANU2000
MANU2010
MANU2020
MANU2030
MANU2040
MANU2050
MANU2060
MANU2070
MANU2080
MANU2090
MANU2100
MANU2110
MANU2120
MANU2130
MANU2140
MANU2150
MANU2160

```

MANU2170
MANU2180
MANU2190
MANU2200
MANU2210
MANU2220
MANU2230
MANU2240
MANU2250
MANU2260
MANU2270
MANU2280
MANU2290
MANU2300
MANU2310
MANU2320
MANU2330
MANU2340
MANU2350
MANU2360
MANU2370
MANU2380
MANU2390
MANU2400
MANU2410
MANU2420
MANU2430
MANU2440
MANU2450
MANU2460
MANU2470
MANU2480
MANU2490
MANU2500
MANU2510
MANU2520
MANU2530
MANU2540
MANU2550
MANU2560
MANU2570
MANU2580
MANU2590
MANU2600
MANU2610
MANU2620
MANU2630
MANU2640
MANU2650
MANU2660
MANU2670
MANU2680
MANU2690
MANU2700

```
ARDB(N)=BETA10*SIN(M)*ARDM  
GO TO 211  
209 CONTINUE  
SIN2=SIN(Y1)*M+61+DPSI2N  
COS2=COS(Y1)*M+61+DPSI2N  
TANAI=(SIN1*TANB12-SIN2*TANB11)/SIN02  
TANR1=(COS2*TANB11-COS1*TANB12)/SIN02  
FLAP1(M)=ATAN(TANAI)  
FLAP2(M)=ATAN(TANB11)  
C1=9BETA10/ICOS(BETA11)*02  
C2=9ETA20/ICOS(BETA21)*02  
PFAC=C1*SIN2-C2*SIN1/SIN02  
RFAC=C2*COS1-C1*COS2/SIN02  
COS91=COS(FLAP12,M)  
APD(M)=APDM*(COS1*FLAP11,M)+02*(COS8)*0(PFAC-PS10(M)*TANB11)  
APD(M)=APDM*(COS1*02+PFAC*PS10(M)*TANAI)  
211 CONTINUE  
DLO1(M)=BETA1  
DLO2(M)=PSIAFF(M)  
DLO3(M)=TANB1  
DLO4(M)=BETA10  
212 CONTINUE  
BITR=-BITR  
ARTD=-ARTD  
AVI=AV  
TMR011)=TMP  
TMR012)=TTR  
ZFLW1)=ZFLWG  
ZFRWG)=ZFRWG  
AZETA=C  
AZETA=C  
VZETA=C  
VZETA=C  
VZETA=C  
IF(ISTOP=NE-1) ISTOP=0  
CALL INIT  
DBRAKE=C  
TIME=TIME+DELT  
DIST=DIST+VOTDELT  
DO 66 N=1,2  
IF(LFPT(M).EQ=C.1) GO TO 64  
PSDS01=PSID(M)*02+AIR(M)  
MURK(N,1)=MURK(1,M)*PSDS01  
MURK(N,2)=MURK(2,M)*PSDS01  
66 CONTINUE  
IF(TSTAR11).GT.TIME) GO TO 208  
VVAOS=1  
I=1  
GO TO 450  
000RUNGF-KUTTA000  
35 I=2  
355 GO TO (1,2)90,420,400).1  
360 DELT=MDLT
```

MANU2710
 MANU2720
 MANU2730
 MANU2740
 MANU2750
 MANU2760
 MANU2770
 MANU2780
 MANU2790
 MANU2800
 MANU2810
 MANU2820
 MANU2830
 MANU2840
 MANU2850
 MANU2860
 MANU2870
 MANU2880
 MANU2890
 MANU2900
 MANU2910
 MANU2920
 MANU2930
 MANU2940
 MANU2950
 MANU2960
 MANU2970
 MANU2980
 MANU2990
 MANU3000
 MANU3010
 MANU3020
 MANU3030
 MANU3040
 MANU3050
 MANU3060
 MANU3070
 MANU3080
 MANU3090
 MANU3100
 MANU3110
 MANU3120
 MANU3130
 MANU3140
 MANU3150
 MANU3160
 MANU3170
 MANU3180
 MANU3190
 MANU3200
 MANU3210
 MANU3220
 MANU3230
 MANU3240

```

DELTA=DELT2
JUAN1=DELT1
30 TO 420
400 DELT2=DELT
DELTA=DELT1
QUAD1=DELT2
420 TO 440 K=1.75
Y(I,K)=Y(I,K)+Y(I-(K+75))*DELT2
440 CONTINUE
450 VX9=Y(I,1)
VX8=Y(I,2)
VZ8=Y(I,3)
AYD=Y(I,4)
APD=Y(I,5)
PSIRFF(I)=Y(I,7)
PSIREF(I)=Y(I,8)
PSD=Y(I,9)
PSD=PSD*GFARAT
AYE=Y(I,10)
APE=Y(I,11)
ARE=Y(I,12)
IF(Y(I,12)-LT.C.) Y(I,13)=C.
DTBWT=Y(I,13)
XX=Y(I,15)
YY=Y(I,16)
ZZ=Y(I,17)
DO 214 N=1,2
NPSIN=NPST(N)
IF(NPSIN.FO.C.) GO TO 214
DO 213 K=1,NPSIN
RETA(K,N)=Y(I,7+N*K+10)
RETAD(K,N)=Y(I,7+N*K+24)
213 CONTINUE
214 CONTINUE
PSD450=PSD*550
CALL PAYS(VXB,VYR,VZ8,AYE,APE,ARE,XXD,VYD,ZZD,1)
VHSO=XXD**2+YYD**2
VM=SQRT(VHSO)
V=SQRT(VHSO+ZZD**2)
AY=C.
AYFP=C.
APP=C.
IF(VX9.NE.0.OR.VY8.NE.0) AY=ATAN2(-VY8,VX8)
IF(VH.NE.C.) AYFP=ATAN2(VYD,XXD)
IF(V.NE.0) APP=ATAN2(-ZZD,VH)
IF(VARS.NE.C) RETURN
IF(1.EQ.3.OR.IND.EQ.1) GO TO 275
*** VARIATIONS DUE TO INPUTS ***
CALL VAPI
IF(FXIT.NE.C.) GO TO 1
CALL SWAS (COLSTK)
  
```

MANU3250
 MANU3260
 MANU3270
 MANU3280
 MANU3290
 MANU3300
 MANU3310
 MANU3320
 MANU3330
 MANU3340
 MANU3350
 MANU3360
 MANU3370
 MANU3380
 MANU3390
 MANU3400
 MANU3410
 MANU3420
 MANU3430
 MANU3440
 MANU3450
 MANU3460
 MANU3470
 MANU3480
 MANU3490
 MANU3500
 MANU3510
 MANU3520
 MANU3530
 MANU3540
 MANU3550
 MANU3560
 MANU3570
 MANU3580
 MANU3590
 MANU3600
 MANU3610
 MANU3620
 MANU3630
 MANU3640
 MANU3650
 MANU3660
 MANU3670
 MANU3680
 MANU3690
 MANU3700
 MANU3710
 MANU3720
 MANU3730
 MANU3740
 MANU3750
 MANU3760
 MANU3770
 MANU3780

```

TIMT=TIM+DT1(1)
TZMT=TZM+DT2(1)
TITT=ITT+DT1(2)
TZTT=TZT+DT2(2)
CALL PCG (PSD,OTZMT,1)
DTZ=DTZMT+ASECON
TZM=TZM+DTZM1+DTZ
TZT=TZT+DTZT1+DTZ*TRIND
275 ORM=PSD*PM
    OTR=PSD*OTR
TZMT=TZM+DTBWY
TZTT=TZT+DTBWT*TRIND
ZZTR=TRALT-ZZ*TRIND
CALL ANAL
IF(EXIT.NE.C.) GO TO 1
QMR=QMR+QTR*GEARAT
QMR = TORQUE FROM AIRLOAD DRAG
QMAX = MAXIMUM TORQUE AVAILABLE
QMS = TORQUE SUPPLIED
QMSA = TORQUE AVAILABLE, LIMITED BY ENG. ACCEL. SCHED.
IF (OPC.EQ.10.) GO TO 315
IF (QOQ.EQ.1.) GO TO 308
IF (QOQ.NE.2.) GO TO 303
QMS=QMR
GO TO 315
304 IF (QMSA.GE.QMAX) GO TO 308
    IF (GOV.LT.0.) GO TO 315
    IF (GOV.NE.0.) GO TO 305
QMSA=QMAX
GO TO 308
305 IF (I.EQ.3.OR.IND.EQ.1) GO TO 308
    TGOV=TDILT/GOV
QMSA=QMSA+(SORT(QMSA*QMAX)+.25*TGOV*QMAX)*TGOV
IF (QMSA.GT.QMAX) QMSA=QMAX
308 QUAD=V1-1, 9)
    IF (I.EQ.3) QUAD=V11, 9)
QMS=QMR+ITORS*(NMEGM-QUAD)*QIAO1
315 QMS=XDELIM(Q.,QMSA,QMS)
303 CONTINUE
    IF (IBRAKE.NE.0) GO TO 322
    IF (PSD.FO.0) GO TO 323
    DPSTOP=PSISTP-PSIREF(1)
    IF (PSD.LF.(-PSD*TDILT)) GO TO 325
    IF (DPSTOP.GE.(PSD*TDILT)) GO TO 321
300 CONTINUE
    DPSTOP=DPSTOP+DPSI(2,1)
    IF (ICAN.EQ.1.AND.DPSTOP.GT.DSTOP1) GO TO 325
    IF (DPSTOP.LT.0.) GO TO 320
321 CONTINUE
    DBRAKF=ITORS*PSD**2/(DPSTOP+DPSTOP1)-QMR
    IF (ICAN.NE.0) DPSTOP.GE.FOURPT) DBRAKE=AMINI(OBRAKE, QDBRAK)
    IF (QDBRAKF.GT.QDBRAK) GO TO 320
  
```

MANU3790
 MANU3800
 MANU3810
 MANU3820
 MANU3830
 MANU3840
 MANU3850
 MANU3860
 MANU3870
 MANU3880
 MANU3890
 MANU3900
 MANU3910
 MANU3920
 MANU3930
 MANU3940
 MANU3950
 MANU3960
 MANU3970
 MANU3980
 MANU3990
 MANU4000
 MANU4010
 MANU4020
 MANU4030
 MANU4040
 MANU4050
 MANU4060
 MANU4070
 MANU4080
 MANU4090
 MANU4100
 MANU4110
 MANU4120
 MANU4130
 MANU4140
 MANU4150
 MANU4160
 MANU4170
 MANU4180
 MANU4190
 MANU4200
 MANU4210
 MANU4220
 MANU4230
 MANU4240
 MANU4250
 MANU4260
 MANU4270
 MANU4280
 MANU4290
 MANU4300
 MANU4310
 MANU4320

```

OHR=OHR*ORAKE
IF(DPSTOP.LT.DPSI(2,1).AND.ORRAKE.LT.OXBRAK) ICAN=1
IF(ICAN.EQ.1) DSTOPI=DPSTOP+.1
IF(DPSTOP.GT.PSDDELTA) GO TO 322
325 CONTINUE
DPSTP=PSISTP*PSIREF(1)
PSIREF(1)=PSISTP
PSIREF(2)=PSIREF(2)+DPSTP*GEARAT
DO 324 K=1,4
  Y(K,7)=PSISTP
  Y(K,8)=PSIREF(2)
  Y(K,9)=0.
  Y(K,82)=0.
  Y(K,83)=0.
  Y(K,84)=0.
  ISTOP=1
324 CONTINUE
GO TO 323
322 CONTINUE
Y(1,84)=(OHR5-OHR)*ORITORS
323 CONTINUE
LP=QL-APD*(AYD*DIZIY-ARD*IXZ)
MP=ON-APD*(ARD*(YK*AYD*IXZ)
Y(1,76)=XFORMASS-APD*VZB+AYD*VYB
Y(1,77)=YFORMASS-AYD*VXB+ARD*VZB
Y(1,78)=ZFORMASS-ARD*VYB+APD*VXB
AYDD=L*POPIZ+MP*OPIX
APDD=(OM-AYD*ARD*DIXZ+(AYD*ARD)*(AYD-ARD)*IXZ)*RIY
ARDD=L*POPIZ+MP*OPIX
Y(1,79)=AYDD
Y(1,80)=APDD
Y(1,81)=ARDD
Y(1,82)=Y(1,9)
Y(1,83)=Y(1,9)*GEARAT
CAPZ=COS(APE)
SARE=SN(APE)
CARE=COS(APE)
IF(ABS(CAPE).LT.0.001) GO TO 1
Y(1,85)=(APD*SARE+AYD*CARE)/CAPE
Y(1,86)=APD*CARE-AYD*SARE
Y(1,87)=ARD*(Y(1,85)*SN(APE)
Y(1,88)=Y(1,14)
BMTDO=BMTD*(GVERT-GPREL)-BMTD*(Y(1,14)-BMTK*DTBMT
IF(DTBM.T.GT.0..OR.BMTDD.GE.0.) GO TO 668
Y(1,13)=0.
Y(1,14)=0.
Y(1,88)=0.
Y(1,89)=0.
BMTDD=0.
668 Y(1,89)=BMTDD
Y(1,90)=XXD
Y(1,91)=YYD
Y(1,92)=ZZD
PSDD=Y(1,84)

```

MANU4330
 MANU4340
 MANU4350
 MANU4360
 MANU4370
 MANU4380
 MANU4390
 MANU4400
 MANU4410
 MANU4420
 MANU4430
 MANU4440
 MANU4450
 MANU4460
 MANU4470
 MANU4480
 MANU4490
 MANU4500
 MANU4510
 MANU4520
 MANU4530
 MANU4540
 MANU4550
 MANU4560
 MANU4570
 MANU4580
 MANU4590
 MANU4600
 MANU4610

```

DO 671 N=1,2
NPSIN=NPSI(N)
IF(NPSIN-EO.0) GO TO 671
DO 670 K=1,NPSIN
Y(I,7*N+K+10)=BETA(K,N)
Y(I,7*N+K+24)=BETAD(K,N)
Y(I,7*N+K+85)=BETAD(K,N)
670 CONTINUE
671 CONTINUE
IF(IND.NE.0) GO TO 500
I=I+1
IF(I.LE.4) GO TO 355
DO 490 I=1,75
K=I+75
Y(4,K)=(Y(1,K)+2.*(Y(2,K)+Y(3,K))+Y(4,K)).166667.
490 Y(4,I)=Y(1,I)+TDELTY(4,K)
IND=1
I=4
50 TO 450
500 DO 495 I=1,150
495 Y(1,I)=Y(4,I)
Y=T+TDELTY
IND=0
I=1
GO TO 210
1 A4=99999999.
WRITE (3) IPSN,A4,A
RETURN
END
  
```

MATR0010
 MATR0020
 MATR0030
 MATR0040
 MATR0050
 MATR0060
 MATR0070
 MATR0080
 MATR0090
 MATR0100
 MATR0110
 MATR0120
 MATR0130
 MATR0140
 MATR0150
 MATR0160
 MATR0170
 MATR0180
 MATR0190
 MATR0200
 MATR0210
 MATR0220
 MATR0230
 MATR0240
 MATR0250
 MATR0260

```

SUBROUTINE MATRIX (A1,A2,A3,A,N1)
  DIMENSION A(9)
  COMPUTE EULER ANGLE MATRIX A FROM EULER ANGLFS A1,A2,A3
  N1=1 IS FOR USUAL MATRIX
  N1=-1 IS FOR INVERSE OF USUAL MATRIX
  SAI=SIN(A1)
  SA2=SIN(A2)
  SA3=SIN(A3)
  CA1=COS(A1)
  CA2=COS(A2)
  CA3=COS(A3)
  SIC3=SA1*CA3
  SIS3=SA1*SA3
  CIC3=CA1*CA3
  CIS3=CA1*SA3
  A(1)=CA1*CA2
  A(3-N1)=CIS3*SA2-SIC3
  A(5-2*N1)=CIC3*SA2+SIS3
  A(3+N1)=SA1*CA2
  A(5)=SIS3*SA2+CIC3
  A(7+N1)=CA2*SA3
  A(5+2*N1)=-SA2
  A(7-N1)=SIC3*SA2-CIS3
  A(9)=CA2*CA3
  RETURN
  FND
  
```

C
C
C

```
C C C  
TWO DIMENSIONAL VECTOR TRANSFORMATION  
N1=1 IS FOR USUAL  
N1=-1 IS FOR INVERSE  
SUBROUTINE MICE (X1,Y1,A,X2,Y2,N1)  
S=SIN(A)*N1  
C=COS(A)  
X2=X1+C*Y1*S  
Y2=X1*S+Y1*C  
RETURN  
END
```

```
MICE0010  
MICE0020  
MICE0030  
MICE0040  
MICE0050  
MICE0060  
MICE0070  
MICE0080  
MICE0090  
MICE0100
```

SUBROUTINE MNEM			
COMMON /FORCE/	XF, XFRMG, XFLWG, XFELE, XFFUS, XFRJET,		
1	XFLJET, XFMR, XFTR, XFGUN, XFFIN, XFM,		
2	YF, YFFUS, YFRJET, YFLJET, YFMR, YFTR,		
3	YFGUN, YFFIN, YFM,		
4	ZF, ZFRMG, ZFLWG, ZFELE, ZFFUS, ZFRJET,		
5	ZFLJET, ZFMR, ZFTR, ZFGUN, ZFM,		
6	QL, LRMG, LLWG, LFLE, LFUS, LRJET, LLJET,		
7	LMR, LTR, LGUN, LF1N, LOMR, LQTR,		
8	OM, MRMG, MLWG, MELE, MFUS, MRJET, MLJET,		
9	MNR, MTR, MGUN, MF1N, MOMR, MQTR,		
A	ON, NRMG, NLWG, NELE, NFUS, NRJET, NLJET,		
B	NMR, NTR, NGUN, NF1N, NOMR, NQTR,		
C	COMMON /STRIAB/	DI(21), DI(21), E(179), F(13), X(10),	
1	DL, DM, DN, DX, DY, DZ, IX, IY, IZ, PO(10, 11),		
2	DTR, FPD, FR(10), KMI, RMQ,		
3	Q12, SPD(6, 6, 3), XAW(21), XFL(14),		
4	XEP(7), XFC(2R), XFM(7), XES(35),		
5	XGM(7), XIT(21), XMR(49), XTR(49),		
6	XMG(21), YMR(21), YTR(21), YMG(21),		
7	YEL(21), YFN(21), YLCG, YAMP, YDPD(10),		
8	YPOS, YPDX(10), MASS, OSV), YMRS, YTRAS,		
9	WLCG, XCON(63), XJET(14), XMIN, AYEP,		
A	RETRES(2), CNPCD, DHADO, DYADR, GUESS,		
B	NPASS, PDPH(10, 11), STACG, TZEPO,		
C	XMAST, DHADAQ, DODCOL, TRRSQ, DYRDBR,		
D	ENGRPM, WXPASS, PSD30P, TR(N01, XLIM(T		
COMMON /STRIMA/	AV, VH, AGM, DT(21), DT(22), IXZ,		
1	QMR, XKD, YVD, ZZO, ALGF, APFP, AYFP,		
2	CGML, COLL(6), CYCF(3), CYCL(3),		
3	DIST, KCIT(20), PFDA(3), QMAX,		
4	QMR5, TIME, TMAX, XCIT(20, 6), ALGF7,		
5	ALGF1, ALGE2, CGSTA, CPMIC, DIX17,		
6	DIYX, DIZZY, DTZMT, DTZM), DTZT1, FTKTS,		
7	MURK(2, 2), MURK1(2, 2),		
8	KREAD, PIUAC, TSTAR(14), ZMAX2, ZMAX3,		
9	ASECOL, CYPWIC, GFARAT, PSD450,		
A	PSISTP, OXBRK, RUDIND, ZDELT1, ZDELT2		
COMMON /STAMAN/	HL(2), XX, YY, AY, GNV, KPD, JPC, QOO,		
1	RC, RHTK, BMT, CGAL, DIX, DP1Z,		
2	FHPT(2), P550, ALEP1, AYDMX, DELT2,		
3	DP1X7, DTBWT, DMLCG, MDEL, KOST,		
4	HLTR1, HLTR2, ITORS, KTCTR, DMEGM,		
5	PCDEL, OMRSA, RMAS, TRALT, TMOP1, VGUST,		
6	ISTOP, XAGUN, XAPYL, XARSP(2), YAGUN,		
7	YARSP(2), YGUST, ZAGUN, ZAPYL, ZARSP(2),		
8	DELT2R, NSTACG, ETMAST, GPRED, HLPYLD,		
9	IBRAKE, OMEGM, ORAKE, PFTAZS(2),		
A	PCGDED, PCGMX, PCRATE, PJDTR, RDELT1,		
B	ZDELT2, PITORS, YPINDZ		
C	COMMON /MANAL/	O, AP, PED, OMG, TZM, TIM, T2M,	
1	Y7T, Y1T, Y2T, ALEL, CZFT, PSDD,		
2	SZFT, TAXL, TAXR, XAWG, XLNK(16), ZAWG,		

MNEM0010
MNEM0020
MNEM0030
MNEM0040
MNEM0050
MNEM0060
MNEM0070
MNEM0080
MNEM0090
MNEM0100
MNEM0110
MNEM0120
MNEM0130
MNEM0140
MNEM0150
MNEM0160
MNEM0170
MNEM0180
MNEM0190
MNEM0200
MNEM0210
MNEM0220
MNEM0230
MNEM0240
MNEM0250
MNEM0260
MNEM0270
MNEM0280
MNEM0290
MNEM0300
MNEM0310
MNEM0320
MNEM0330
MNEM0340
MNEM0350
MNEM0360
MNEM0370
MNEM0380
MNEM0390
MNEM0400
MNEM0410
MNEM0420
MNEM0430
MNEM0440
MNEM0450
MNEM0460
MNEM0470
MNEM0480
MNEM0490
MNEM0500
MNEM0510
MNEM0520
MNEM0530
MNEM0540

3	ALCP, ALFIN, ALLWG, ALRWG, CDELE, CDFIN,	MMEND550
4	COLWG, CORRNG, CLELF, CLFIM, CLLMG, CLRWG, CMING,	MMEND560
5	CYCR1, CYCR2, CZETA, CZET6, CZET9, RANGE,	MMEND570
5	CZET5, SZET7, SZETA, MGCOL, XAELE, XAFIN,	MMEND580
7	XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,	MMEND590
8	YAELE, YAFUS, YALWG, YARWG, YALJET, YARJET,	MMEND600
8	ZAJET, ALECR1, ALGFPD, BOTTOM, CZET11,	MMEND610
9	CZET12, CZET13, EIZETA, HALFPI, SZET1D,	MMEND620
A	KAPYLD, YGUSTW, ZAPYLD, ZFLWG1, ZFRWGI	MMEND630
R	YZMS, TMS, TMS, TZTS, TYS, TZTS,	MMEND640
C	CLOCK, FLOCK, XLOCK, TCLOCK	MMEND650
	ZZ, VXS(2), VYS(2), VS(2), BETA(12,2),	MMEND660
*	T, PCC(2), COSEL(7,2), BETAM(2), BETAK(2), BETAZ(2),	MMEND670
*	AIB(2), APDD, ARDD, AYDD, AIA(2),	MMEND680
1	DPS(112,2), DTPR, MPS(12), ZZTR,	MMEND690
2	BETAD(12,2), BNPSI(2),	MMEND700
3	COND2, GMXV, RATE1, RATE2, STOP2,	MMEND710
4	THROT(7), TRIND, XGUST, BETAZD(2), GMXV1,	MMEND720
5	GMXV2, GMXV3, GUSTYP, MNPSIR(2),	MMEND730
6	MURKS, MURKS, MUBTSP, MUBTAS,	MMEND740
7	KONFIG, LNGTH1, PILGH1, PSIREF(2),	MMEND750
8	STAPT2, XMOPL(112,2),	MMEND760
9	RM, RTR, ORM, ORTR, T1MT, T1TT,	MMEND770
A	T2MT, T2TT, T2MT, T2TT, XMA1, XMA1T,	MMEND780
R	XMB1, XMB1T, AIRPM, AIBPT, AIBPM, AIBRT,	MMEND790
C	APT, APTD, ARTD, ARTD, PSD, PSDT,	MMEND800
D	XSTAM, XSTAMT, YSTAM, YSTAMT,	MMEND810
E	MURKP, MURKTP, MURKR, MURKTR	MMEND820
E	ZZETA, AZETAT, VZETA, VZETAT	MMEND830
	(V, IND, MAG, APRMT, ARMT, AYBMT, BETA0(2), TDELT,	MMEND840
1	BETA(2), MGUSTE, MGUSTF, MGUSTM, VGUSTE,	MMEND850
2	VGUSTM, VGUSTF, GFWD, GLAT, GVERT,	MMEND860
3	VXB, VZB, APD, VYR, APD, AYD,	MMEND870
4	COLSTR, CYSTK1, CYSTK2, PEDAL, AYE,	MMEND880
5	APE, ARE, AIM, RIM, AITP, BITA,	MMEND890
6	XAR(2), YAR(2), ZAR(2),	MMEND900
7	VIMR, VITP, ZFTA, ZFTATR, MMR, MTR,	MMEND910
8	TMR, TTR, QMX, QTR, YMR, YTR	MMEND920
	J, M, ITR, VMS(2), L (MK, OFLE, VROT(2),	MMEND930
1	VSND, VFN(2), ZFEL(2), AIBAL(2),	MMEND940
2	PI9AL(2), CONDI, SWING, PILGH2, PMGELL,	MMEND950
3	BM, BTR, PMOM, PMOMT, RMOM, RMOMT	MMEND960
	AM(2), CT, PI, XB(2), ALT, AOR(2), FXM(2),	MMEND970
1	XIR(2), RBM(2), SMC(2), UMS, CDM(2), LRROT(2),	MMEND980
2	ZAIR(2), RTRP(2), TAIR(14), CONER(2), DCAFR(2), FVIND,	MMEND990
*	NVARO,	MMEND1000
3	SMR1(2), SMR2(2), TPIB(2), TPIB(2),	MMEND1010
4	TWIST(2,2), CLRADK(2), DELTA1(2),	MMEND1020
5	LAMDA(2), UPGUST, URGUST, JTGUST, WROTOR,	MMEND1030
6	ERM, ERTR, ERX4, ERXT,	MMEND1040
7	KLMAW, KLMAKT, XLMINM, XLMINT	MMEND1050
	AM(3), AL(3), EXIT, ICM(49), IPSM,	MMEND1060
1	NPAR, NVAR, NVARA, NVARC, NSCALE	MMEND1070
1	NVAPS, NPR(NT, NTIME)	MMEND1090

```

COMMON /STARAN/ RH(2),C1,C4,PM,CIP,CLR,DCD,DOL,DOM,VIM,
  PAIR(2),CLRN,CNBN,ETAO,NJET,
  OFIN,
  VIER,CLACL,YES(14),
  CNBCL,CNPCL,CNPCR,CN2CL,COLKS,D3FLF,
  FNSMC,LWJMG,PMREL,PMRWG,
  PTRFN,APIST,VMAXE,VAERO(31,5),
  APBJET,APBJET,AVRJET,
  CNPCOI,CNPCO2,COLJET,DIRGEL,DZMGEL,
  ETAOMX,PMGSKI,RCWJMG,SWJMG,
  VENTER,VMVFR
COMMON /FORV/ V(4,150)
PEAL IX,IY,IZ,IXZ,MASS,ITORS,ILJET,LRJET,MLJET,MRJET,NLJET,NRJET
DIMENSION FOR(71)
EQUIVALENCE (XF,FOR(1))
NVAR0=C
TFINVARC,NE=2) GO TO 102
NVARC=1
GO TO 100
102 CONTINUE
TFINVARC,NE=0) NVARC=1
100 CONTINUE
TRIND?=-1--TRIND
CALL YINIT (YAIR)
ALEL=C.
ALFIN=C.
ALLWG=C.
AIRMG=C.
APD=C.
APDD=C.
APBJET=C.
ARD=C.
ARDD=C.
AYD=C.
AYDD=C.
BETA(1)=0.
BETA(2)=0.
BETA(1)=0.
BETA(2)=0.
COLMG = 0.
CRMG = 0.
CDELE = 0.
CDFIN = 0.
CLLWG = 0.
CLWMS = 0.
CLELE = 0.
CLFIN = 0.
DOL=C.
DOM=C.
ETAO=C.
EXIT=C.
GUSTYP=C.
HGUSTE=C.
NNEM1090
NNEM1100
NNEM1110
NNEM1120
NNEM1130
NNEM1140
NNEM1150
NNEM1160
NNEM1170
NNEM1180
NNEM1190
NNEM1200
NNEM1210
NNEM1220
NNEM1230
NNEM1240
NNEM1250
NNEM1260
NNEM1270
NNEM1280
NNEM1290
NNEM1300
NNEM1310
NNEM1320
NNEM1330
NNEM1340
NNEM1350
NNEM1360
NNEM1370
NNEM1380
NNEM1390
NNEM1400
NNEM1410
NNEM1420
NNEM1430
NNEM1440
NNEM1450
NNEM1460
NNEM1470
NNEM1480
NNEM1490
NNEM1500
NNEM1510
NNEM1520
NNEM1530
NNEM1540
NNEM1550
NNEM1560
NNEM1570
NNEM1580
NNEM1590
NNEM1600
NNEM1610
NNEM1620

```

```

MNE1630
MNE1640
MNE1650
MNE1660
MNE1670
MNE1680
MNE1690
MNE1700
MNE1710
MNE1720
MNE1730
MNE1740
MNE1750
MNE1760
MNE1770
MNE1780
MNE1790
MNE1800
MNE1810
MNE1820
MNE1830
MNE1840
MNE1850
MNE1860
MNE1870
MNE1880
MNE1890
MNE1900
MNE1910
MNE1920
MNE1930
MNE1940
MNE1950
MNE1960
MNE1970
MNE1980
MNE1990
MNE2000
MNE2010
MNE2020
MNE2030
MNE2040
MNE2050
MNE2060
MNE2070
MNE2080
MNE2090
MNE2100
MNE2110
MNE2120
MNE2130
MNE2140
MNE2150
MNE2160

```

```

VGUSTF=0.
VGUSTW=C.
HMR=C.
HTR=C.
IND=1
VMAG=C
PSDD=0.
OMX=0.
QTR=0.
SMC(1)=1.
UPGUST=0.
UTGUST=0.
URGUST=0.
VGUSTF=C.
VGUSTW=C.
VIER=0.
VIN=C.
XMA1=C.
XMB1=C.
XMAIT=C.
XMBIT=C.
YGUSTF=C.
YGUSTW=C.
YMR=C.
YTRF=C.
PSD550=PSD*550
DO 307 I=1.71
FOR(I)=0.
DO 308 J=1.150
DO 308 I=1.4
Y(I,J)=0.
307 CONTINUE
308 CONTINUE
CALL MOPSI1 (NPSI,MNPSIR,BNPSI,DPSI)
DIZIV=IZ-IV
DIXIZ=IX-IZ
DIYIX=IV-IX

```

```

SET UP CURVE FOR EFFECT OF MAIN ROTOR WAKE ON THE ELEVATOR.
THIS CURVE CAN BE REPRESENTED BY THREE STRAIGHT LINES - ZERO
AFFORE THE VELOCITY IS GREAT ENOUGH TO CAUSE AN EFFECT ON
THE ELEVATOR,VENTER: A LINE WITH CONSTANT SLOPE FROM VENTER
TO A VELOCITY WHICH PRODUCES A MAXIMUM EFFECT,VMAXE: AND A
CONSTANT AT VMAKE AND GREATER.

```

```

VXMR=PMREL
IF(VMAXF,NE,VENTER) VXMR=PMREL/(VMAXE-VENTER)
IF(XLMINM,LE,0.,OR,XLMINM,GT,DTR) XLMINM=.3490659E-02
IF(XLMINT,LE,0.,OR,XLMINT,GT,DTR) XLMINT=.3490659E-02
IF(ERXP,LT,750.) ERXP=750.
IF(ERT,LT,750.) ERT=750.
XLMAXM=8.*XLMINM
XLMAXT=8.*XLMINT
IF(XMIN,LT,.8726645E-03) XMIN=DTR

```

```

MNF2170
MNF2180
MNF2190
MNF2200
MNF2210
MNF2220
MNF2230
MNF2240
MNF2250
MNF2260
MNF2270
MNF2280
MNF2290
MNF2300
MNF2310
MNF2320
MNF2330
MNF2340
MNF2350
MNF2360
MNF2370
MNF2380
MNF2390
MNF2400
MNF2410
MNF2420
MNF2430
MNF2440
MNF2450
MNF2460
MNF2470
MNF2480
MNF2490
MNF2500
MNF2510
MNF2520
MNF2530
MNF2540
MNF2550
MNF2560
MNF2570
MNF2580
MNF2590
MNF2600
MNF2610
MNF2620
MNF2630
MNF2640
MNF2650
MNF2660
MNF2670
MNF2680
MNF2690
MNF2700

IF(XMIN.GT.DTR) XMIN=DTR
IF(XLIM(T.LT.1.5*DTR).OR.XL(M(T.GT..1745320) XLIM(T=DTR
(F(DAMP.LT.(40.*ERR(1))) DAMP=40.*ERR(1)
VAR(1)=VARS(1)
VALMG=-YAPMG
VALJET=-YARJET
IF(TRIND.NE.C..AND.ABS(XARS(1)-XARS(2)).LE.5.) TRIND=1.
KONFIG=1.*TRIND*TRIND
CALL COM2 (XCON,XLINK,KONFIG,RUD(ND)
RC=0.
IF(XMR(14).NE.0.) RC=AM(1)/M
IF(KONFIG.EQ.3) RC=PC*2.*DB
CALL TILT (KONFIG)
CALL TILT (XAR,ZAR,CGL,COLL,ZETA,CZSTA)
CALL TFA (XAR,BETAZ,CZSTA)
CALL HSAF (XAR,YAR,DPSI,MPSI,CGSTA,PSIREF)
XAR(2)=XARS(2)*HL(2)*SIN(ZETA)
CZTR=COS(ZETA)
HLTR1=HL(2)*TRIND
VAR(2)=VARS(2)-HLTR1*CZTR
ZAR(2)=ZARS(2)-HLTR1*CZTR
CALL RATS (XXD,YYD,ZZD,AVE,AFE,ARE,VXB,VYB,VZB,-1)
V=SQRT(XXD**2+YYD**2+ZZD**2)
CALL TURN (XFC,V,ARE)
WROTDR=1350.*TRIND
RM=1./M
MASS= W/32.17
IF(EPS.EQ.0.) EPDS=.3
ARWING=YM(1)
IF(ARWING.EQ.0.) ARWING=1.
SWING=SQRT(XMG(1)*ARWING)
CMWING=SWING/ARWING
RCWING = 0.
IF(CWING.NE.0.) *CMWING = 1./CMWING
CAGM=COS(AGM)
CMG6=.6*CMWING
YAER(19,3)=YAER(13,3)/YAER(17,3)
*PIST=.35*CAGM/|HALFPI-YAER(10,3)|
DXMGEL=XANG-XAELE+CMG6*CAGM
DZMGEL=ZANG-ZAELE+SIN(AGM)*CMG6
SWINGM=.5*SWING
CNPCD1=CNPCD*YAER(13,3)
CNPCD2=CNPCD*2.*YAER(14,3)*ARWING/13.*ARWING)

IF THERE ARE NO JETS CALCULATE FORCES AND MOMENTS AND USE THE
VALUE OF COLJET TO PREVENT FURTHER CALCULATIONS LATER IN THE
PROGRAM

IF(INJET.EQ.0) COLJET=C.
CALL PATS(TAXL,0,0,-AYRJET,APBJET,APBJET,XFLJET,VFLJET,ZFLJET,1)
CALL DOGS (XAJET,YAJET,ZAJET,XFLJET,YFLJET,ZFLJET,LLJET,MLJET,
I MLJET)
CALL RATS (TAXR,0,0,AYBJET,APRJET,ARBJET,XFRJET,YFRJET,ZFRJET,1)
CALL DOGS (XAJET,YAJET,ZAJET,XFRJET,YFRJET,ZFRJET,LRJET,MRJET,

```

C
C
C
C
C

MNUM2710
 MNUM2720
 MNUM2730
 MNUM2740
 MNUM2750
 MNUM2760
 MNUM2770
 MNUM2780
 MNUM2790
 MNUM2800
 MNUM2810
 MNUM2820
 MNUM2830
 MNUM2840
 MNUM2850
 MNUM2860
 MNUM2870
 MNUM2880
 MNUM2890
 MNUM2900
 MNUM2910
 MNUM2920
 MNUM2930
 MNUM2940
 MNUM2950
 MNUM2960
 MNUM2970
 MNUM2980
 MNUM2990
 MNUM3000
 MNUM3010
 MNUM3020
 MNUM3030
 MNUM3040
 MNUM3050
 MNUM3060
 MNUM3070
 MNUM3080
 MNUM3090
 MNUM3100
 MNUM3110
 MNUM3120
 MNUM3130
 MNUM3140
 MNUM3150
 MNUM3160
 MNUM3170
 MNUM3180
 MNUM3190
 MNUM3200
 MNUM3210
 MNUM3220
 MNUM3230
 MNUM3240

```

1 MRJET)
  AYBMT=ZETATR*TRIND2
  APBMT=-ZETATR*TRIND
  ARBMT=HALFPI*TRIND2
  ZZTR=TRALT-ZZ*TRIND
  CYCR1=CYSK1*CYCF(3)+CYCF(2)
  CYCR2=CYSK2*CYCL(3)+CYCL(2)
  PED=PEDAL*PEDA(3)+PEDA(2)
  COLKS=COLSTK
  CALL SMAS1 (KOMF1G)
  CALL SMAS (COLSTK)
  IF(GUESS.EQ.2) GO TO 58

ORIGINATE GUESS FOR THRUST AND FLAPPING.

XFWG = 0.
ZFWG = 0.
IF(LONG.LT.0) GO TO 51
AP=0.
IF(VXB.NE.0.0.OR .VZB.NE.0.0) AP=ATAN2(VZB.VXB)
ALWG=AGW*AP
XMAC=V*V*V*V
CALL CLCD (ALWG,CL,CD,XMAC,EXIT,3)
IF(EXIT.NE.0.) RETURN
CALL MICE (1-CD,-CL,AP,C1,C2,1)
VONG = 2.*V*V*V*V*V
ZFWG = VONG*2
XFWG = VONG*C1

51 CALL RATS (0.,0.,0.,W,AVE,APE,ARE,XFM,YFM,ZFM,-1)
DF=Q*V*V*(VFS(7)+1.)*XFWG
TMR=((ZFM*ZFM)*CZET*DF*SZET)*(1.-.5*TRIND)
YTR=125.*TR*TRIND2*TR*TRIND
IF(GUESS.NE.0.) GO TO 58
IF(ORH.GT.RH) GO TO 52
WRITE(6,53)
EXIT = 1.
RETURN

52 CONTINUE
ALF=APE-APFP
THTM=ZTM-TWIST(30NIR(1)/4,1)
ALF=ZETA+THTM-ALF1
XMU=V/ORM*COS(ALF)
XLM=V/ORM*SIN(ALF)
ATM=XMU*(2.666667*THTM+2.*XLM)/(1.-.5*XMU**2)-THTM
BTM=T2M
THT=T2T-TWIST(30NIR(2)/4,2)
ALF=ZETATR+THT-ALF1*TRIND-(AVE-APFP)*TRIND2
XMU=V/ORM*COS(ALF)
XLM=V/ORM*SIN(ALF)
ATR=XMU*(2.666667*THT+2.*XLM)/(1.-.5*XMU**2)-THT
BTR=T2T

58 CONTINUE
VIMR = 0.
VITR = 0.
  
```

C
C
C

```

IF(RM.FO.O.) TMR=C.
IF(ATP.FO.O.) YTR=C.
IF(TMR.FO.O..OR.ORM.LE.RM) GO TO 59
ALT=-ZZ
CALL RATS (VXB,VVR,VZB,C...ZETA,C...VXS(1),VYS(1),VZS(1),-1)
VROT(1)=V
VMS=VXS(1)*2+VYS(1)*2
CT=TMPORTRP(1)
CALL VIND (1,EXIT)
CALL RATS (VXB,VYB,VZB,AYBMT,ARBMT,VXS(2),VYS(2),VZS(2),-1)
ALT=ZZTR
VROT(2)=V
VMS=VXS(2)*2+VYS(2)*2
CT=TRORTRP(2)
CALL VIND (2,EXIT)
<9 CONTINUE
Y(1,9)=XXD
Y(1,91)=YYD
Y(1,92)=ZZD
RATB(2)=RATB(2)*GEARAT
IF(PSO.NE.C.) GO TO 73
DO 72 N=1,2
  BETAN(N)=BETAZ(N)
  METAX(N)=BETAZ(N)
72 CONTINUE
XFC(23)=Z.
AIM=C.
AIM=C.
AITR=C.
BITR=C.
GO TO 67
73 CONTINUE
IF(XFC(23).NE.1.) GO TO 66
IPAKF=C
PSD=C.
PSDT=C.
67 CONTINUE
NPSI(1)=BM
NPSI(2)=BTR
ITM=C
64 CONTINUE
LINK=1
PSTIP=C.
IF(PART.NE.2) GO TO 109
WRITE (6,108)
IF(NVAR.NE.C) GO TO 103
WRITE (6,104)
GO TO 105
103 WRITE (6,104) NVAR
105 WRITE (6,107) ZERO,ZDEL1,THAX,ZDEL2,ZMAX2,ZMAX3
  CALL IVAR (EXIT,LINK,TARL,TARR,PILGH2,AIM,BIM,A1TR,B1TR)
109 CONTINUE
IF(XFC(23).NE.1.) GO TO 65
CALL NPSI1 (NPSI,NMPSIR,9NPSI,DPSI)

```

```

NNEM3250
NNEM3260
NNEM3270
NNEM3280
NNEM3290
NNEM3300
NNEM3310
NNEM3320
NNEM3330
NNEM3340
NNEM3350
NNEM3360
NNEM3370
NNEM3380
NNEM3390
NNEM3400
NNEM3410
NNEM3420
NNEM3430
NNEM3440
NNEM3450
NNEM3460
NNEM3470
NNEM3480
NNEM3490
NNEM3500
NNEM3510
NNEM3520
NNEM3530
NNEM3540
NNEM3550
NNEM3560
NNEM3570
NNEM3580
NNEM3590
NNEM3600
NNEM3610
NNEM3620
NNEM3630
NNEM3640
NNEM3650
NNEM3660
NNEM3670
NNEM3680
NNEM3690
NNEM3700
NNEM3710
NNEM3720
NNEM3730
NNEM3740
NNEM3750
NNEM3760
NNEM3770
NNEM3780

```

MNEM3790
 MNEM3800
 MNEM3810
 MNEM3820
 MNEM3830
 MNEM3840
 MNEM3850
 MNEM3860
 MNEM3870
 MNEM3880
 MNEM3890
 MNEM3900
 MNEM3910
 MNEM3920
 MNEM3930
 MNEM3940
 MNEM3950
 MNEM3960
 MNEM3970
 MNEM3980
 MNEM3990
 MNEM4000
 MNEM4010
 MNEM4020
 MNEM4030
 MNEM4040
 MNEM4050
 MNEM4060
 MNEM4070
 MNEM4080
 MNEM4090
 MNEM4100
 MNEM4110
 MNEM4120
 MNEM4130
 MNEM4140
 MNEM4150
 MNEM4160
 MNEM4170
 MNEM4180
 MNEM4190
 MNEM4200
 MNEM4210
 MNEM4220
 MNEM4230
 MNEM4240
 MNEM4250
 MNEM4260
 MNEM4270
 MNEM4280
 MNEM4290
 MNEM4300
 MNEM4310
 MNEM4320

```

60 64 N=1.2
61 SIFF(N)=PSISTP
IF(KONFIG.EQ.3) GO TO 62
62 TAN(N)=C.
63 ETAX(N)=C.
64 ETAX(N)=C.
IF(N.EQ.2) GO TO 64
65 61 K=1.12
66 PSIIK(N)=C.
IF(K.GT.7) GO TO 61
67 60 L=1.7
68 COSEIK(.5*N)=1.
69 CONTINUE
61 CONTINUE
62 GO TO 64
63 CONTINUE
64 ETAX(N)=--HALFPI
65 ETAN(N)=--HALFPI
66 ETAX(N)=--HALFPI
67 PSIN=NPSIIN
68 62 K=1.MPSIN
69 ETALK(N)=--HALFPI
70 CONTINUE
64 CONTINUE
65 CONTINUE
IF(PART.NE.2) RETURN

INITIALIZE VARIABLES ONLY IF A MANEUVER IS CALLED FOR.
ITOPS=DATB(1)+MATB(2)
IF(ITOPS.NE.C.) RTORS=1./ITOPS
LWING=C
CALL MAGI
RMASS=1./MASS
RTY=1./TY
OP = IX*IZ - IYZ*IXZ
IF(OP.EQ.0.) GO TO 70
DPIZ=IXZ/OP
DPIX=IX/OP
DPIZ=IZ/OP
Y(1,9)=PSO
Y(1,17)=ZZ
Y(1,82)=PSO
Y(1,83)=PSOT
RETURN
70 CONTINUE
EXIT=1.
WRITE (6,71)
72 STOP
73 FORMAT('0 FLAPPING ANGLES CANNOT BE ESTIMATED FOR A STOPPED',
'0 ROTOC. ')
71 FORMAT ('0 CHECK INPUT FUSELAGE INERTIAS. THE NUMBERS INPUT ARE
PHYSICALLY IMPOSSIBLE AND CANNOT BE HANDLED BY THIS PROGRAM. ')
72 FORMAT (1H)
  
```

```

104 EQPMAT (1H0,46X,'WAGNER AND BUETTNER FUNCTIONS (INACTIVE)') MNEM4330
106 EQPMAT (1H0,40X,'WAGNER AND RUETTNER FUNCTIONS ACTIVE ON TIME STEMNEM4340
      IP,12) MNEM4350
107 EQPMAT (1H0,54X,23HINPUT DATA FOR MANUEVER/1H0,34X, 'START' DEL MNEM4360
      MAX1 DFLT2 MAX2 MAX3'/35X, '(SEC) MNEM4370
      2 (SEC) (SEC) (SEC) (SEC)'/1H,29X,6F10.3 MNEM4380
      3 //35X, 61HJ XCIT(J,1) (J,2) (J,3) (J,4) (MNEM4390
      4J,5) (J,6)) MNEM4400
      FND MNEM4410

```

```

SUBROUTINE MODE (PD,V,IMODE)
COMMON /TRONIC/ UU(6),VV(6),TAU(22),DAMP(22),NUMRTS,GAINB,
1 INDEX,STGAIN(6),TSTAR,COELTD,SLOT(3,9)
DIMENSION PD(10,11),SLT(3,9),ISLOT(2,2)
DIMENSION HEAD(3,2,2),HEAD1(3,3,2)
DATA HEAD /'LAT CYCLIC PEDAL F/A CYCLIC COLLECTIVE '/
DATA HEAD1 /'SDE.SLP.ANG.ROLL ANGLE YAW RATE FWD. VEL. ANG.
IF ATK.PITCH ANGLE '/'
DATA ISLOT /3,4,2,1/
COLD=COELTD
WRITE (6,299)
ISLTF=0
INDEX=0
KSLTF=-2
DO 10 I=1,3
KSLTF=KSLTF+3
CALL SLTF (SLT,SLOT,KSLTF)
ISLTF=ISLTF+3
DO 9 J=1,2
JSLTF=ISLTF(J,IMODE)
CALL SLTF (PD,ISLTF,JSLTF,IMODE)
COELTD=COELTD/COLD
IF(I.EQ.1.AND.IMODE.EQ.2) COELTD=COELTD*V
CALL /'LEC (GAINB)
INDEX=INDEX+1
STGAIN(INDEX)=GAINB*COELTD/GAINB
WRITE (6,301) (HEAD1(L,I,IMODE),L=1,3),(HEAD(L,J,IMODE),L=1,3),
1 (UU(L),VV(L),L=1,3),COELTD
9 CONTINUE
CALL SLTF (SLT,SLOT,KSLTF)
10 CONTINUE
DO 669 I=19,21
IF(TAU(I).NE.0..OR.DAMP(I).NE.0.) GO TO 669
N=I
GO TO 673
669 CONTINUE
GO TO 674
673 CONTINUE
DO 668 I=N,21
DAMP(I)=DAMP(I+1)
TAU(I)=TAU(I+1)
668 CONTINUE
674 CONTINUE
WRITE (6,300) (((HEAD1(I,J,IMODE),I=1,3),(HEAD(I,K,IMODE),I=1,3),
1 (TAU(I+3*(K+2*J-3)),DAMP(I+3*(K+2*J-3)),I=1,3),
2 STGAIN(K+2*J-2),K=1,2),J=1,3),
3 (TAU(I),DAMP(I),I=19,21),GAINB,TSTAR
RETURN
299 FORMAT('H',57X,'FREQUENCY RESPONSE',/1X,'DEPEND.VAR. INDEP.
1 VAR. REAL1 IMAG1 REAL2 IMAG2
2 REAL3 IMAG3 GAIN')
300 FORMAT ('ODEP. VAR. INDEP. VAR.,.6X,'TAU',
1 12X,'DAMP',.9X,'TAU',.9X,'DAMP',.12X,'TAU',
2 11X,'DAMP',.5X,'STATIC GAIN'/'

```

```

3      6(1H ,3A4,5X,3A4,7G14.6/)
4      '0D E N O M I N A T O P ,8X,7G14.6/
5      ' ALL ROOTS, FREQUENCIES, PERIODS, AND TIME TO HALF OR
6 DOUBLF AMPLITUDE ARE IN REAL SECONDS./
7      ' ALL MAGNITUDES AND PHASE ANGLES HAVE BEEN DETERMINED FROM
8 M ROOTS IN AIR SECONDS./
9      ' GAINS ARE DETERMINED FROM ROOTS IN REAL SECONDS./
A      ' ALL STATIC GAINS ARE IN NATURAL UNITS PER INCH OF STICK
R./
C      ' T* = ,G13.5)
301 FORMAT(1H ,3A4,5X,3A4,7G14.6)
END
MODE0550
MODE0560
MODE0570
MODE0580
MODE0590
MODE0600
MODE0610
MODE0620
MODE0630
MODE0640
MODE0650
MODE0660

```

```

SUBROUTINE NDSLOT (DIV1,DIV2,TSTAR,PD,SLOT,I1,KS,LS,JD,SLOT,X)
DIMENSION UDSLOT(11,3),PD(10,11),SLNT(3,9),KS(3),LS(2)
DO 10 I=1,3
  DIV=DIV1
  (F(I,FO,(I) DIV=DIV)
  LK=I
  DO 8 K=1,11
    UDSLOT(K,I)=PD(KS(I),LS(LK))/DIV
    LK=LK+1
  8 CONTINUE
  J=4
  DO 9 K=1,3
    J=J-1
    UDSLOT(J,I)=SLOT(I,J)/DIV
    UDSLOT(J+3,I)=SLOT(I,J+3)/DIV
    JD,SLOT(J+6,I)=SLOT(I,J+6)/(X*DIV)
  9 CONTINUE
  10 CONTINUE
  %RETURN
END
NDSLC01C
NDSLC02D
NDSLC030
NDSLC040
NDSLC050
NDSLC060
NDSLC070
NDSLC080
NDSLC090
NDSLC10A
NDSLC11A
NDSLC120
NDSLC130
NDSLC140
NDSLC150
NDSLC160
NDSLC170
NDSLC180
NDSLC190
NDSLC200
NDSLC210

```

MPS010
MPS020
MPS030
MPS040
MPS050
MPS060
MPS070
MPS080
MPS090
MPS100
MPS110
MPS120
MPS130
MPS140
MPS150
MPS160
MPS170
MPS180
MPS190
MPS200

NPST(1) = NPST(1) + NPST(2) + NPST(3) + NPST(4) + NPST(5) + NPST(6) + NPST(7) + NPST(8) + NPST(9) + NPST(10) + NPST(11) + NPST(12) + NPST(13) + NPST(14) + NPST(15) + NPST(16) + NPST(17) + NPST(18) + NPST(19) + NPST(20)

NPST(1) = NPST(1) + NPST(2) + NPST(3) + NPST(4) + NPST(5) + NPST(6) + NPST(7) + NPST(8) + NPST(9) + NPST(10) + NPST(11) + NPST(12) + NPST(13) + NPST(14) + NPST(15) + NPST(16) + NPST(17) + NPST(18) + NPST(19) + NPST(20)

NPST(1) = NPST(1) + NPST(2) + NPST(3) + NPST(4) + NPST(5) + NPST(6) + NPST(7) + NPST(8) + NPST(9) + NPST(10) + NPST(11) + NPST(12) + NPST(13) + NPST(14) + NPST(15) + NPST(16) + NPST(17) + NPST(18) + NPST(19) + NPST(20)

1	COMMON /STRIAB/	D(21),DT(21),E(79),F(10),X(10),	OFFT0010
2		DL,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),	OFFT0020
3		ETR,EPD,ERR(1C),KMI,RHO,	OFFT0030
4		P12,SPO(6,6,3),XBW(21),XEL(14),	OFFT0040
5		XER(7),XFC(20),XFM(7),XFS(35),	OFFT0050
6		XGN(7),XIT(21),XMR(49),XTR(49),	OFFT0060
7		XWG(21),YMR(21),YTR(21),YWG(21),	OFFT0070
8		YEL(21),YFM(21),BLCG,OAMP,OEPI(10),	OFFT0080
9		EPOS,EPOX(10),MASS,OSV1,THRS,TTAS,	OFFT0090
A		WCG,XCON(63),XJET(14),XMIN,AYEFP,	OFFT0100
B		BETAES(2),CMPCO,OHADO,OYBOR,GUESS,	OFFT0110
C		NPASS,POPHI(1C,11),STACG,TZERO,	OFFT0120
D	COMMON /STRIHA/	XMAST,DMA'AO,OODCOL,DTRRSO,OYBDBR,	OFFT0130
1		AY,VH,AGW,DT1(2),DT2(2),IXZ,	OFFT0140
2		QMR,XXD,YYD,ZZD,ALGF,APFP,AYFP,	OFFT0150
3		CGML,COLL(6),CYCF(3),CYCL(3),	OFFT0160
4		DIST,KCIT(20),PEDA(3),OMAX,	OFFT0170
5		QMR,TIME,TMAX,XCIT(20,6),ALGEZ,	OFFT0180
6		ALGE1,ALGE2,CGSTA,CPMIC,DIXIZ,	OFFT0190
7		DIVIX,DIZIY,DTZMT,DTZMI,DTZTI,FTKTS,	OFFT0200
8		HUBKM(2,2),HUBKI(2,2),	OFFT0210
9		KREAO,PIU30,TSTAR(14),ZMAX2,ZMAX3,	OFFT0220
A		ASECOL,CYPMIC,GFARAT,PSD550,	OFFT0230
B		PSISTP,OXPRAK,RUIND,ZDELT1,ZDELT2	OFFT0240
C	COMMON /ROMAN/	ZZ,VXS(2),VVS(2),VZS(2),BETA(12,2),	OFFT0250
D		T,PCC(2),COSF(7,7,2),BETAN(2),BETAX(2),BETAZ(2),	OFFT0260
E		AT(2),APOD,AROD,AYOD,ATR(2),	OFFT0270
F		OPSI(12,2),OTRP,NPSI(2),ZZTR,	OFFT0280
1		BETAD(12,2),RNPSSI(2),	OFFT0290
2		COMD2,GMAXV,RATE1,RATE2,STOP2,	OFFT0300
3		THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,	OFFT0310
4		GMAXV2,GMAXV3,GUSTP,HNPSIR(2),	OFFT0320
5		HUBKPS,HUBKRS,HUBTPS,HUBTRS,	OFFT0330
6		KONFIG,LNGTH1,PILGHI,PSIREF(2),	OFFT0340
7		START2,XMOMLI(12,2),	OFFT0350
8		RM,RTR,ORM,ORT,TIME,TITT,	OFFT0360
9		TZMT,TZTT,TZMT,TZTT,XMA1,XMAIT,	OFFT0370
A		XMB1,XMR11,AIBPM,AIBPT,AIBRM,AIBRT,	OFFT0380
B		APT,APTTO,ARTO,ARTTO,PSD,PSOT,	OFFT0390
C		XSTAMM,XSTANT,YSTAMM,YSTANT,	OFFT0400
D		HUBKP,HUBKTP,HUBKR,HUBKTR	OFFT0410
E		AZETA,AZETAT,VZETA,VZETAT	OFFT0420
F	COMMON /MANARD/	I,V,INO,MWAG,APBMT,ARMT,AYRMT,BETA0(2),TOELT,	OFFT0430
1		BETAE(2),MGUSTE,MGUSTF,MGUSTW,MGUSTE,	OFFT0440
2		VGUSTW,VGUSTF,GFWO,GLAT,GVERT,	OFFT0450
3		VXB,VZB,APD,VYB,ARO,AYD,	OFFT0460
4		COLSTK,CYSTKI,CYSTK2,PEDAL,AYE,	OFFT0470
5		APE,ARE,AIM,AIM,AITP,BITR,	OFFT0480
6		XAR(2),YAR(2),ZAR(2),	OFFT0490
7		VIMR,VITR,ZETA,ZETATR,MMR,HJR,	OFFT0500
8	COMMON /FORY/	THR,TTR,OMX,QTR,YMRF,YTRF	OFFT0510
		Y(4,150)	OFFT0520
			OFFT0530
			OFFT0540

OFFT0550
 OFFT0560
 OFFT0570
 OFFT0580
 OFFT0590
 OFFT0600
 OFFT0610
 OFFT0620
 OFFT0630
 OFFT0640
 OFFT0650
 OFFT0660
 OFFT0670
 OFFT0680
 OFFT0690
 OFFT0700
 OFFT0710
 OFFT0720
 OFFT0730
 OFFT0740
 OFFT0750
 OFFT0760
 OFFT0770
 OFFT0780

```

9FAL MASS,IXZ
IF(Y(1,R5),EO,0.) GO TO 225
ARD=-Y(1,R5)*SIN(APE)
CAPE=Y(1,R5)*COS(APE)
APD=CAPE*SIN(ARE)
AYD=CAPE*COS(ARE)
GO TO 226
225 CONTINUE
      IF(Y(2,R6),FQ,1.) GO TO 224
      APED=32.17*(Y(2,R6)-COS(APE)*COS(ARE))/V
      CALL CATS (AYE,APE,ARE,AYFP,APFP,O.,AYPB,APPB,ARPB,1,-1)
      CALL RATS (O.,APED,O.,AYPB,APPB,ARPB,ARD,APD,AYD,-1)
226 CONTINUE
      OX = MASS*(APD*VZB-AYD*VYB)
      OY = MASS*(AYD*VXB-ARD*VZB)
      OZ = MASS*(ARD*VYB-APD*VXB)
      OL = APD*(AYD*D(7,1Y)-ARD*IXZ)
      OM = ARD*AYD*D(1,1Z)-(ARD*AYD)*(ARD-AYD)*IXZ
      ON = APD*(ARD*D(1,1X)+AYD*IXZ)
      CALL RATS (ARD,APD,AYD,O.,-ZFTA,C.,ARTD,APTD,TV,-1)
      CALL RATS (ARD,APD,AYD,AYRMT,APRMT,ARMT,ARTD,APTD,TV,-1)
224 CONTINUE
      RETURN
      END
  
```

SUBROUTINE PARA (M,COND1)
COMMON /FORCE/

1 XE,XFMG,XFLWG,XFELE,XFFUS,XFRJET,
2 XFLJET,XFMR,XFTR,XFGUN,XFFIN,XFM,
3 YF,YFFUS,YFRJET,YELJET,YFMR,YFTR,
4 YFGUN,YFFIN,YFM,
5 ZF,ZFRMG,ZFLWG,ZFELE,ZFFUS,ZFRJET,
6 ZFLJET,ZFMR,ZFTR,ZFGUN,ZFM,
7 OL,LRMG,LLWG,LELE,LFUS,LRJET,LLJFT,
8 LMR,LTR,LGUN,LFIN,LQMR,LQTR,
9 OM,MRMG,MLWG,MELF,MFUS,MPJET,MLJET,
0 MMR,NTR,NGUN,MFIN,MQMR,MQTR,
1 ON,NPMG,NLWG,NFELE,NFUS,NRJET,NLJET,
2 NMR,NTR,NGUN,NFIN,NQMR,NQTR

COMMON /STRTAB/ D(21),E(79),F(10),X(14),
1 OL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPD,FRR(10),KMI,RHM,
3 R12,SPD(6,6,3),XBM(21),XFL(14),
4 XFR(7),XFC(28),XFN(7),XFS(35),
5 XGM(7),XIT(21),XMR(49),XTR(49),
6 XWG(21),XMR(21),YTR(21),YWG(21),
7 YFL(21),YFN(21),BLCG,DAMP,DEPD(10),
8 EPDS,FPOX(10),MASS,OSVI,THRS,YTRS,
9 WLCG,XCON(63),XJET(14),XMIN,AYEFP,
0 PETAES(2),CNPCD,DHADO,DYBDR,GUESS,
1 NPASS,POPHI(10,11),STAGG,TZERO,
2 XMAST,DHADAQ,DQCCOL,DTRRSQ,DYBDBR,
3 ENGRPM,XPASS,PSD30P,TRIND1,XLIMIT

COMMON /STRIMA/

1 AY,VH,AGW,DTI(2),DTZ(2),IXZ,
2 QMR,XXD,YYD,ZZD,ALGF,APFP,AYFP,
3 CGWL,COLL(6),CYCF(3),CYCL(3),
4 D(1),KCIT(20),PEDA(3),OMAX,
5 QMRS,TIME,TMAX,XCIT(20,6),ALGEZ,
6 ALGFI,ALGE2,CGSTA,CPMIC,DIXIZ,
7 DIYIX,DIY(1),DT7MT,DTZM,DTZTI,FTKTS,
8 HURKMI(2),HURKI(2,2),
9 KREAD,PIJ30,TSTAR(14),ZMAX2,ZMAX3,
0 ASECOL,CYPMIC,GEARAT,PSD550,
1 PSTSTP,OXRRAK,RUDIND,ZDELT1,ZDELT2
2 Q,AP,PED,OMG,TZM,TIM,T2M,
3 TZI,TIT,T2T,ALEL,CZFT,PSDD,
4 S7ET,TAXL,TAYR,XAMG,XLNK(16),Z4WG,
5 ALCYP,ALFIN,ALLWG,ALPMG,CDELE,COFIN,
6 COLWG,CORWG,CLEFL,CCLFN,CLLWG,CLRMG,CMING,
7 CYCPI,CYCR2,CZET4,CZET6,CZET9,RANGE,
8 S7ET5,SZET7,SZET8,NGCOL,XAELE,XAFIN,
9 XAFUS,XAJET,YAFIN,ZAELE,ZAFIN,ZAFUS,
0 YAFLE,YAFUS,YALWG,YARMG,YALJET,YARJET,
1 ZAJET,ALECR1,ALGEPD,BOTTOM,CZET11,
2 CZET12,CZET13,ETZETA,HALFPI,SZET10,
3 XAPYLD,YGUSTM,ZAPYLD,ZFLWGL,ZFRWG)
4 T2MS,T1MS,T2MS,TZTS,T1TS,TZTS,
5 CLOCK,FLOCK,XLOCK,TCLOCK
6 ZZ,VXSI(2),VYSI(2),VZSI(2),RETAI(2,2),
7 Y,PCO(2),COSE(7,7,2),BETANI(2),BETAX(2),BETAZ(2),

PARA0010
PARA0020
PARA0030
PARA0040
PARA0050
PARA0060
PARA0070
PARA0080
PARA0090
PARA0100
PARA0110
PARA0120
PARA0130
PARA0140
PARA0150
PARA0160
PARA0170
PARA0180
PARA0190
PARA0200
PARA0210
PARA0220
PARA0230
PARA0240
PARA0250
PARA0260
PARA0270
PARA0280
PARA0290
PARA0300
PARA0310
PARA0320
PARA0330
PARA0340
PARA0350
PARA0360
PARA0370
PARA0380
PARA0390
PARA0400
PARA0410
PARA0420
PARA0430
PARA0440
PARA0450
PARA0460
PARA0470
PARA0480
PARA0490
PARA0500
PARA0510
PARA0520
PARA0530
PARA0540

```

1  *
2  1 A(BI2),APDO,ARON,AYDD,AIR(2),
3  2 DPSI(12,2),OTRR,NPSI(2),ZZTR,
4  3 9ETAO(12,2),BMPSI(2),
5  4 CMD2,GMAXV,RATE1,RATE2,STOP2,
6  5 THROT(2),TRIND,XGUST,BETAZO(2),GMAXV1,
7  6 GMAXV2,GMAXV3,GUSTYP,HMPSIR(2),
8  7 HUBKRS,HUBKRS,HUBTPS,HUBTRS,
9  8 KONE(L,NGTH1,P(LGH1,PSIREF(2),
10 9 START2,XMOMLI(12,2),
11 0 RM,RTF,ORF,ORTF,TIMT,TITT,
12 A T2MT,T2TT,TZMT,TZTT,XMAL,XMAIT,
13 B XMB1,XMBIT,AIBPM,AIBPT,AIBRM,AIBRT,
14 C APTD,APTD,ARTD,ARTD,PSO,PSOT,
15 D XSTAHM,XSTAHT,YSTAHM,YSTAHT,
16 E HUBKP,HUBKTD,HUBKR,HUBKTR
17  *
18  * AZETA,AZETAT,VZETA,VZETAT
19  * V,IND,NWAG,APRMT,ARMT,AVBMT,BETAO(2),TDELT,
20  * 9ETAE(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
21  * VGUSTW,VGUSTF,SFWD,GLAT,GVERT,
22  * VXB,VZB,APD,VYB,ARD,AYD,
23  * COLSTK,CYSTK1,CYSTK2,PEOAL,AYE,
24  * ADE,ARE,AIM,RIM,AITP,BITR,
25  * XAR(2),VAR(2),ZAR(2),
26  * VIMR,VITR,ZETA,ZETATR,HMR,HTR,
27  * TMR,TTR,OMX,QTR,YMRF,YTRF
28  * AM(3),AL(3),EXIT,ICOM(49),IPSN,
29  * NPART,NVARA,NVARB,NVARC,NSCALE
30  * NVAR5,NPRINT,NTIME
31  *
32  * COMMON /MANAPO/
33  *
34  * 1 DIMENSION P(48),HEAD(12,6),VAR(11)
35  * 2 QU(VALENCE (VAR(11),COLSTK(
36  * 3 DATA HEAD1 / * MAIN FWD RIGHT TAIL AFT LEFT * /
37  * 4 COMMON /METER/ HEAD(10,39(
38  * 5 (FICOM1,NF,C,( GO TO 173
39  * 6 CALL MRFM
40  * 7 CALL WRVP (3,VAR,KMI,PD,TAXL,TAXR)
41  * 8 CALL WRRT (3,GO TO 160
42  * 9 WRITE(6,171(
43  * 10 GO TO 175
44  * 11 WRITE(6,171( NPASS
45  * 12 WRITE(7,1-RUDINQ
46  * 13 WRITE(6,80( (HEAD(11,K)NFIC,(=1,2,(HEAD(11,(KONFIG+3(,I=1,2(
47  * 14 P(1)=TZMT*OTRR
48  * 15 P(2)=TZTT*OTRR
49  * 16 P(3)=5*(ALRMG+ALLWG(*OTRR
50  * 17 P(4)=T(MT*OTRR
51  * 18 P(5)=T(IT*OTRR
52  * 19 P(6)=ZFRMG+ZFLMG
53  * 20 P(7)=T2MT*OTRR
54  * 21 P(8)=T2TT*OTRR
55  * 22 P(9)=XFPMG+XFLMG
56  * 23 P(10)=A1*OTRR
57  * 24 P(11)=A1P*OTRR
58  * 25 P(12)=ALFL*OTRR
59  *
60  *
61  *
62  *
63  *
64  *
65  *
66  *
67  *
68  *
69  *
70  *
71  *
72  *
73  *
74  *
75  *
76  *
77  *
78  *
79  *
80  *
81  *
82  *
83  *
84  *
85  *
86  *
87  *
88  *
89  *
90  *
91  *
92  *
93  *
94  *
95  *
96  *
97  *
98  *
99  *
100  *
101  *
102  *
103  *
104  *
105  *
106  *
107  *
108  *
109  *
110  *
111  *
112  *
113  *
114  *
115  *
116  *
117  *
118  *
119  *
120  *
121  *
122  *
123  *
124  *
125  *
126  *
127  *
128  *
129  *
130  *
131  *
132  *
133  *
134  *
135  *
136  *
137  *
138  *
139  *
140  *
141  *
142  *
143  *
144  *
145  *
146  *
147  *
148  *
149  *
150  *
151  *
152  *
153  *
154  *
155  *
156  *
157  *
158  *
159  *
160  *
161  *
162  *
163  *
164  *
165  *
166  *
167  *
168  *
169  *
170  *
171  *
172  *
173  *
174  *
175  *
176  *
177  *
178  *
179  *
180  *
181  *
182  *
183  *
184  *
185  *
186  *
187  *
188  *
189  *
190  *
191  *
192  *
193  *
194  *
195  *
196  *
197  *
198  *
199  *
200  *
201  *
202  *
203  *
204  *
205  *
206  *
207  *
208  *
209  *
210  *
211  *
212  *
213  *
214  *
215  *
216  *
217  *
218  *
219  *
220  *
221  *
222  *
223  *
224  *
225  *
226  *
227  *
228  *
229  *
230  *
231  *
232  *
233  *
234  *
235  *
236  *
237  *
238  *
239  *
240  *
241  *
242  *
243  *
244  *
245  *
246  *
247  *
248  *
249  *
250  *
251  *
252  *
253  *
254  *
255  *
256  *
257  *
258  *
259  *
260  *
261  *
262  *
263  *
264  *
265  *
266  *
267  *
268  *
269  *
270  *
271  *
272  *
273  *
274  *
275  *
276  *
277  *
278  *
279  *
280  *
281  *
282  *
283  *
284  *
285  *
286  *
287  *
288  *
289  *
290  *
291  *
292  *
293  *
294  *
295  *
296  *
297  *
298  *
299  *
300  *
301  *
302  *
303  *
304  *
305  *
306  *
307  *
308  *
309  *
310  *
311  *
312  *
313  *
314  *
315  *
316  *
317  *
318  *
319  *
320  *
321  *
322  *
323  *
324  *
325  *
326  *
327  *
328  *
329  *
330  *
331  *
332  *
333  *
334  *
335  *
336  *
337  *
338  *
339  *
340  *
341  *
342  *
343  *
344  *
345  *
346  *
347  *
348  *
349  *
350  *
351  *
352  *
353  *
354  *
355  *
356  *
357  *
358  *
359  *
360  *
361  *
362  *
363  *
364  *
365  *
366  *
367  *
368  *
369  *
370  *
371  *
372  *
373  *
374  *
375  *
376  *
377  *
378  *
379  *
380  *
381  *
382  *
383  *
384  *
385  *
386  *
387  *
388  *
389  *
390  *
391  *
392  *
393  *
394  *
395  *
396  *
397  *
398  *
399  *
400  *
401  *
402  *
403  *
404  *
405  *
406  *
407  *
408  *
409  *
410  *
411  *
412  *
413  *
414  *
415  *
416  *
417  *
418  *
419  *
420  *
421  *
422  *
423  *
424  *
425  *
426  *
427  *
428  *
429  *
430  *
431  *
432  *
433  *
434  *
435  *
436  *
437  *
438  *
439  *
440  *
441  *
442  *
443  *
444  *
445  *
446  *
447  *
448  *
449  *
450  *
451  *
452  *
453  *
454  *
455  *
456  *
457  *
458  *
459  *
460  *
461  *
462  *
463  *
464  *
465  *
466  *
467  *
468  *
469  *
470  *
471  *
472  *
473  *
474  *
475  *
476  *
477  *
478  *
479  *
480  *
481  *
482  *
483  *
484  *
485  *
486  *
487  *
488  *
489  *
490  *
491  *
492  *
493  *
494  *
495  *
496  *
497  *
498  *
499  *
500  *
501  *
502  *
503  *
504  *
505  *
506  *
507  *
508  *
509  *
510  *
511  *
512  *
513  *
514  *
515  *
516  *
517  *
518  *
519  *
520  *
521  *
522  *
523  *
524  *
525  *
526  *
527  *
528  *
529  *
530  *
531  *
532  *
533  *
534  *
535  *
536  *
537  *
538  *
539  *
540  *
541  *
542  *
543  *
544  *
545  *
546  *
547  *
548  *
549  *
550  *
551  *
552  *
553  *
554  *
555  *
556  *
557  *
558  *
559  *
560  *
561  *
562  *
563  *
564  *
565  *
566  *
567  *
568  *
569  *
570  *
571  *
572  *
573  *
574  *
575  *
576  *
577  *
578  *
579  *
580  *
581  *
582  *
583  *
584  *
585  *
586  *
587  *
588  *
589  *
590  *
591  *
592  *
593  *
594  *
595  *
596  *
597  *
598  *
599  *
600  *
601  *
602  *
603  *
604  *
605  *
606  *
607  *
608  *
609  *
610  *
611  *
612  *
613  *
614  *
615  *
616  *
617  *
618  *
619  *
620  *
621  *
622  *
623  *
624  *
625  *
626  *
627  *
628  *
629  *
630  *
631  *
632  *
633  *
634  *
635  *
636  *
637  *
638  *
639  *
640  *
641  *
642  *
643  *
644  *
645  *
646  *
647  *
648  *
649  *
650  *
651  *
652  *
653  *
654  *
655  *
656  *
657  *
658  *
659  *
660  *
661  *
662  *
663  *
664  *
665  *
666  *
667  *
668  *
669  *
670  *
671  *
672  *
673  *
674  *
675  *
676  *
677  *
678  *
679  *
680  *
681  *
682  *
683  *
684  *
685  *
686  *
687  *
688  *
689  *
690  *
691  *
692  *
693  *
694  *
695  *
696  *
697  *
698  *
699  *
700  *
701  *
702  *
703  *
704  *
705  *
706  *
707  *
708  *
709  *
710  *
711  *
712  *
713  *
714  *
715  *
716  *
717  *
718  *
719  *
720  *
721  *
722  *
723  *
724  *
725  *
726  *
727  *
728  *
729  *
730  *
731  *
732  *
733  *
734  *
735  *
736  *
737  *
738  *
739  *
740  *
741  *
742  *
743  *
744  *
745  *
746  *
747  *
748  *
749  *
750  *
751  *
752  *
753  *
754  *
755  *
756  *
757  *
758  *
759  *
760  *
761  *
762  *
763  *
764  *
765  *
766  *
767  *
768  *
769  *
770  *
771  *
772  *
773  *
774  *
775  *
776  *
777  *
778  *
779  *
780  *
781  *
782  *
783  *
784  *
785  *
786  *
787  *
788  *
789  *
790  *
791  *
792  *
793  *
794  *
795  *
796  *
797  *
798  *
799  *
800  *
801  *
802  *
803  *
804  *
805  *
806  *
807  *
808  *
809  *
810  *
811  *
812  *
813  *
814  *
815  *
816  *
817  *
818  *
819  *
820  *
821  *
822  *
823  *
824  *
825  *
826  *
827  *
828  *
829  *
830  *
831  *
832  *
833  *
834  *
835  *
836  *
837  *
838  *
839  *
840  *
841  *
842  *
843  *
844  *
845  *
846  *
847  *
848  *
849  *
850  *
851  *
852  *
853  *
854  *
855  *
856  *
857  *
858  *
859  *
860  *
861  *
862  *
863  *
864  *
865  *
866  *
867  *
868  *
869  *
870  *
871  *
872  *
873  *
874  *
875  *
876  *
877  *
878  *
879  *
880  *
881  *
882  *
883  *
884  *
885  *
886  *
887  *
888  *
889  *
890  *
891  *
892  *
893  *
894  *
895  *
896  *
897  *
898  *
899  *
900  *
901  *
902  *
903  *
904  *
905  *
906  *
907  *
908  *
909  *
910  *
911  *
912  *
913  *
914  *
915  *
916  *
917  *
918  *
919  *
920  *
921  *
922  *
923  *
924  *
925  *
926  *
927  *
928  *
929  *
930  *
931  *
932  *
933  *
934  *
935  *
936  *
937  *
938  *
939  *
940  *
941  *
942  *
943  *
944  *
945  *
946  *
947  *
948  *
949  *
950  *
951  *
952  *
953  *
954  *
955  *
956  *
957  *
958  *
959  *
960  *
961  *
962  *
963  *
964  *
965  *
966  *
967  *
968  *
969  *
970  *
971  *
972  *
973  *
974  *
975  *
976  *
977  *
978  *
979  *
980  *
981  *
982  *
983  *
984  *
985  *
986  *
987  *
988  *
989  *
990  *
991  *
992  *
993  *
994  *
995  *
996  *
997  *
998  *
999  *
1000  *

```

```

P(13)=BIM*OTRR
P(14)=B1TR*OTRR
P(15)=ZFLE
P(16)=YMR
P(17)=YTR
P(18)=XFELE
WRITE (6,81) ((HEAD(I,2*J-1),I=1,10),P(3*J-2),P(3*J-1),
1 (HEAD(I,2*J),I=1,10),P(3*J),J=1,6)
P(19)=MWR
P(20)=MTR
P(21)=ALFIN*OTRR
P(22)=YMR
P(23)=YTR
P(24)=YFFIN
P(25)=OMX*PSD550
P(26)=OTR*PSD550*GEARAT
P(27)=XFFIN
WRITE (6,81) ((HEAD(I,3*J-8),I=1,10),P(3*J-2),P(3*J-1),
1 (HEAD(I,3*J-NRUD),I=1,10),P(3*J),J=7,9)
P(28)=PSD30P
P(29)=P(28)*GEARAT
P(30)=AYE*OTRR
P(31)=ZETA*OTRR
P(32)=ZETA*P*OTRR
P(33)=APE*OTRR
P(34)=A19(1)
P(35)=A19(2)
P(36)=ARE*OTRR
WRITE (6,81) ((HEAD(I,2*J+2),I=1,10),P(3*J-2),P(3*J-1),
1 (HEAD(I,2*J+3),I=1,10),P(3*J),J=10,12)
P(37)=AXL
P(38)=Z2D
P(39)=TAXR
P(40)=VM*FTXTS
P(41)=COLSTK
P(42)=W
P(43)=CVSTK1
P(44)=ENGRPH
P(45)=CVSTK2
P(46)=CGSTA
P(47)=PEDAL
P(48)=CGWL
WRITE (6,82) ((HEAD(I,J-9),I=1,10),P(J),J=37,48)
CALL TIMEX (TUSED,OTIME,TLLEFT)
WRITE (6,2011) NPASS,TUSED
HPSUP=OMX*PSD550
HPTOT=P(25)*P(26)
IF(HPTOT.LE.HPSUP) GO TO 300
WRITE (6,1028)
EXIT=)
300 RETURN
90 FORMAT (1H0,49X,2A4,3X,2A4)
91 FORMAT (9X,10A4,2F10.3,5X,10A4,F10.3/)
92 FORMAT (9X,10A4,5X,F10.3,10X,10A4,F10.3/)

```

```

PARA1090
PARA1100
PARA1110
PARA1120
PARA1130
PARA1140
PARA1150
PARA1160
PARA1170
PARA1180
PARA1190
PARA1200
PARA1210
PARA1220
PARA1230
PARA1240
PARA1250
PARA1260
PARA1270
PARA1280
PARA1290
PARA1300
PARA1310
PARA1320
PARA1330
PARA1340
PARA1350
PARA1360
PARA1370
PARA1380
PARA1390
PARA1400
PARA1410
PARA1420
PARA1430
PARA1440
PARA1450
PARA1460
PARA1470
PARA1480
PARA1490
PARA1500
PARA1510
PARA1520
PARA1530
PARA1540
PARA1550
PARA1560
PARA1570
PARA1580
PARA1590
PARA1600
PARA1610
PARA1620

```

161 FORMAT(1M1.50M HELICOPTER IS ****NOT*** IN STABLE CONDITION AFTER. PARA1630
1 15.12M ITERATIONS./16X.9M***** PARA1640
171 FORMAT(35M HELICOPTER IS IN STABLE CONDITION./1 PARA1650
1728 FORMAT(1M0.56M***** POWER REED. FOR TRIM COND. EXCEEDS POWER AVAIL.PARA1660
TABLE) PARA1670
2011 FORMAT (5X6HPART 1.16X13.12M ITERATIONS.20X10.3. PARA1680
1 35H MINUTES FLAPSD COMPUTING TIME /1M1) PARA1690
END PARA1700

```

SUBROUTINE PCG (PSD,DTZMT,I)
COMMON /STAMAN/ HL(2),XX,YY,AVI,GOV,KPD,OPC,000,
1 RY,APRG,ARBG,ASEP,AYRG,BMTC,
2 RC,BWK,9MTM,CGRL,DPIX,DPIZ,
3 FHPT(2),R550,ALFPT,AYDMX,OELT2,
4 OPIX,OTBWT,OMLCG,HOELT,MGUST,
5 HLTR1,HLTR2,ITOPS,KICTR,JMEGN,
6 PCDEL,OMRSA,RNASS,TRALT,TWOPI,VGUST,
7 ISTOP,KAGUN,XAPYL,XARSP(2),YAGUN,
8 YARSP(2),YGUST,ZAGUN,ZAPYL,ZARSP(2),
9 DELTR,DSTAGG,ETMAST,GPRELD,HLPLYD,
A IBRAKE,OMFGMD,OBRAKE,BEYAZS(2),
B PCGFD,PCGMAX,PCRATE,POINTR,RDELT1,
C ROELT2,RITORS,TPINDZ
COMMON /FORV/ Y(4,150)
PSOMM=PSD*OMEGM
O1=ARSI*PCOEL
O2=O1-.01*PCRATE
(IF(OPC.EQ.10.) GO TO 224
IF(O2.GT.0.) PCDEL=PCDEL-SIGN(PCRATE,PCDEL)
GO TO 232
224 CONTINUE
IF(O2.GT.0.) GO TO 236
IF(ABS(PSOMM).LE.(PCGOEO*OMEGM)) GO TO 226
236 CONTINUE
O2=SIGN(PCRATE,PSOMM)
YOM=Y(1-1,84)-OMEGMD
IF(PSOMM/(YOM+.2*PSOMM).GT.0.) PCDEL=PCDEL+O2
IF(O1.GT.PCGMAX*HOELT) PCDEL=PCDEL-O2
IF((PSOMM/YOM).GT.0.) GO TO 237
IF(O2.GT.HOELT*Q1/PCRATE) PCDEL=PCDEL-SIGN(PCRATE,PCDEL)
237 CONTINUE
DTZMT=DTZMT+PCOEL
226 CONTINUE
RETURN
END

```

```

PCG00019
PCG00020
PCG00030
PCG00040
PCG00050
PCG00060
PCG00070
PCG00080
PCG00090
PCG00100
PCG00110
PCG00120
PCG00130
PCG00140
PCG00150
PCG00160
PCG00170
PCG00180
PCG00190
PCG00200
PCG00210
PCG00220
PCG00230
PCG00240
PCG00250
PCG00260
PCG00270
PCG00280
PCG00290
PCG00300
PCG00310
PCG00320
PCG00330
PCG00340
PCG00350
PCG00360

```

```

SUBROUTINE PDZ1 (KL)
DIMENSION PD(10,11)
LOGICAL AVEEP
KONFIG=KL
RETURN
C NTPY PDZ (PD,AVEEP)
C ZERO THE PARTIALS OF THE FLAP MOM OF ONE ROTOR WRT TO
C THE FLAP ANGLES OF THE OTHER ROTOR
DO 303 I=7,8
DO 303 J=7,8
PD(I,J+2)=0.
PD(I+2,J)=0.
IF TANDEM RETURN
C 307 (287,300,301),KONFIG
C IF SIDE-BY-SIDE WITH SIDESLIP RETURN
C 301 IF(AVEEP) RETURN
C SET LEFT ROTOR DERIVATIVES TO MAGNITUDE OF CORRESPONDING
C RIGHT ROTOR DERIVATIVES
DO 277 J=9,10
PD(9,J)=SIGN(PD(7,J-2),PD(9,J))
PD(10,J)=SIGN(PD(9,J-2),PD(10,J))
DO 292 I=1,6
PD(J,I)=SIGN(PD(J-2,I),PD(J,I))
PD(11,J)=SIGN(PD(1,J-2),PD(11,J))
C ZERO PARTIALS OF Y-FORCE, YAW, AND ROLL MOMENTS WRT
C F/A CYCLIC AND COLLECTIVE STICKS AND PITCH ANGLE
DO 289 I=2,6,2
PD(I,5)=0.
DO 289 J=1,2
PD(I,J)=0.
RETURN
C SINGLE ROTOR CASES
C 287 03 288 I=9,10
C ZERO THE PARTIALS OF THE MR FLAP MOM WRT TO PEDAL
PD((-2,4))=0.
DO 288 J=1,2
C ZERO THE PARTIALS OF THE TR FLAP MOM WRT STICKS
PD(I,J)=0.
300 RETURN
END

```

```

PDZ00010
PDZ00020
PDZ00030
PDZ00040
PDZ00050
PDZ00060
PDZ00070
PDZ00080
PDZ00090
PDZ00100
PDZ00110
PDZ00120
PDZ00130
PDZ00140
PDZ00150
PDZ00160
PDZ00170
PDZ00180
PDZ00190
PDZ00200
PDZ00210
PDZ00220
PDZ00230
PDZ00240
PDZ00250
PDZ00260
PDZ00270
PDZ00280
PDZ00290
PDZ00300
PDZ00310
PDZ00320
PDZ00330
PDZ00340
PDZ00350
PDZ00360
PDZ00370
PDZ00380
PDZ00390
PDZ00400

```



```

PPL00559
PPL00560
PPL00570
PPL00580
PPL00590
PPL00600
PPL00610
PPL00620
PPL00630
PPL00640
PPL00650
PPL00660
PPL00670
PPL00680
PPL00690
PPL00700
PPL00710
PPL00720
PPL00730
PPL00740
PPL00750
PPL00760
PPL00770
PPL00780
PPL00790
PPL00800
PPL00810
PPL00820
PPL00830
PPL00840
PPL00850
PPL00860
PPL00870
PPL00880
PPL00890
PPL00900
PPL00910
PPL00920
PPL00930
PPL00940
PPL00950
PPL00960
PPL00970
PPL00980
PPL00990
PPL01000
PPL01010
PPL01020
PPL01030
PPL01040
PPL01050
PPL01060
PPL01070
PPL01080

WRITE (6,5) I4, A(3),AH(3),RATE(3),I6,(2,14
WRITE (6,7) I7,I1,I2,I4
      (INITIAL(ZF LINE TO BLANKS
3100 I=1,I10
      LINE(I)=IR
      CALL TIMEX (TUSED,TDELT,TLEFT)
3110 READ (3) IPSN,T,A
      IF(T.GT.9999.E+04) GO TO 9999
      NTIME=NTIME+1
      IF(NTIME.EQ.NPRINT) NTIME=C
      IF(NTIME.NE.C) GO TO 6019
      SCALE DATA TO FIXED POINT POSITION ON SCALE
      X=A(NVARA)*AC(1)+AD(1)
      KY=A(NVARB)*AC(2)+AD(2)
      KY=A(NVARC)*AC(3)+AD(3)
      CHECK FOR EQUALITY OF VARIABLES
      IF(KB.EQ.KX) GO TO 3101
      IF(KB.EQ.KY) GO TO 3102
      IF(KX.EQ.KY) GO TO 3103
      CHECK TO SEE IF VARIABLES FALL ON SCALE
      IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=I1
      IF(KX.GE.1.AND.KX.LE.101) LINE(KX)=I2
      IF(KY.GE.1.AND.KY.LE.101) LINE(KY)=I4
      GO TO 5000
3101 IF(KB.EQ.KY) GO TO 3104
      FIRST AND SECOND VARIABLES ARE IN SAME POSITION
      IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=I3
      IF(KY.GE.1.AND.KY.LE.101) LINE(KY)=I4
      GO TO 5000
3102 FIRST AND THIRD VARIABLES ARE IN SAME POSITION
      IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=I5
      IF(KX.GE.1.AND.KX.LE.101) LINE(KX)=I2
      GO TO 5000
3103 SECOND AND THIRD VARIABLES ARE IN SAME POSITION
      IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=I1
      IF(KX.GE.1.AND.KX.LE.101) LINE(KX)=I6
      GO TO 5000
      ALL THREE VARIABLES ARE IN SAME POSITION
3104 IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=I7
3000 WRITE (6,5001) T,L,LINE
      RESET LINE TO BLANKS
      IF(KB.GE.1.AND.KB.LE.101) LINE(KB)=IB
      IF(KX.GE.1.AND.KX.LE.101) LINE(KX)=IB
      IF(KY.GE.1.AND.KY.LE.101) LINE(KY)=IR
      GO TO 6019
6999 CONTINUE
      CALL TIMEX (TUSED,TDELT,TLEFT)
      WRITE (6,7000) TDELT
      RETURN
6 FORMAT (1H,10X,'SCALE ',A1,' FROM',F11.3,' TO',F11.3,
1 ' ',1 INCH =',F9.3,11X,A1,' FOR ',A1,' + ',A1,'X,
2 ' ON SAME PRINT POS. ')
7 FORMAT (1H,15X,A1,' FOR ',A1,' + ',A1,' + ',A1,' ON SAME PRINT POPPL01070
15.//67X,'INCHES'/T2,'0',T3,'1',T4,'2',T5,'3',T6,'4',T7,'5',PPL01080

```

PPL01090
PPL01100
PPL01110
PPL01120
PPL01130
PPL01140
PPL01150

```
2190,*,*,T00,*,7,*,T100,*,9,*,T110,*,6,*,T119,*,10,*/ Y20,*,*,Y30,*,*,  
3 Y40,*,*,Y50,*,*,T60,*,*,T70,*,*,T80,*,*,T90,*,*,T00,*,*,Y100,*,*,  
4 T110,*,*,T120,*,*,  
215 FORMAT (7X,*, SYMBO1 ',A1,*, =',9A4)  
211 FORMAT (1H,*,5X,F9.2,4X,101A1)  
2000 FORMAT (1H0,F15.5)  
END
```

RATIO010
 RATIO020
 RATIO030
 RATIO040
 RATIO050
 RATIO060
 RATIO070
 RATIO080
 RATIO090
 RATIO100
 RATIO110
 RATIO120
 RATIO130
 RATIO140
 RATIO150
 RATIO160
 RATIO170
 RATIO180
 RATIO190
 RATIO200
 RATIO210
 RATIO220

```

SUBROUTINE RATT (X,EPDX,XLIMIT,VAR)
COMMON /KVARTR/ KVAR(10)
DIMENSION VAR(11),X(11),EPOX(11)
RATIO=1.
RATIOI=1.
DO 10 I=1,10
  CHECK TO SEE IF ANY CORRECTION EXCEEDS LIMITS
  IF (ABS(X(I))-GT.XLIMIT) RATIOI=ABS(XLIMIT/X(I))
  CHOOSE RATIO SO THAT LARGEST CORRECTION = LIMIT
  IF (RATIO.LE.RATIOI) GO TO 10
  RATIO=RATIOI
  II=I
10 CONTINUE
  MAKE CORRECTIONS
  DO 20 I=1,10
 20 VARIKVAR(I)=VAR(KVAR(II))+X(I)*RATIO*EPOX(II)
  IF (RATIO.NE.1.) WRITE (6,40) X,RATIO,II
30 RETURN
40 FORMAT (1H0//1H , 'CORRECTIONS',2X,10F11.7.
1 /1H0,'RATIO APPLIED TO CORRECTION VECTOR IS ',F10.7.
2 2X,'FROM COMPONENT ',I3)
END

```

```
SUBROUTINE RATS (X1,Y1,Z1,A1,A2,A3,X2,Y2,Z2,N1)
DIMENSION A(9)
THREE DIMENSIONAL VECTOR TRANSFORMATION
N1=1 FOR USUAL
N1=-1 FOR INVERSE
CALL MATRIX (A1,A2,A3,A,N1)
X2=X1*A(1)+Y1*A(2)+Z1*A(3)
Y2=X1*A(4)+Y1*A(5)+Z1*A(6)
Z2=X1*A(7)+Y1*A(8)+Z1*A(9)
RETURN
END
```

```
C
C
C
```

```
RATS0010
RATS0020
RATS0030
RATS0040
RATS0050
RATS0060
RATS0070
RATS0080
RATS0090
RATS0100
RATS0110
```



```

READ (5,1003) XIT
READ (5,1004) TSTAB
READ (5,1005) R
IF (NPAR.EQ.3) MPART.EQ.7) RETURN
READ (5,1006) ZZERO ZDELTA1 ZMAX1 ZDELTA2 ZMAX2
* /MAX3
T = TZERO
IF (ZDELTA1.EQ.0.) ZDELTA1 = 0.1
IF (ZDELTA2.EQ.0.) ZDELTA2=ZDELTA1
TMAX = ZMAX1
DO 201 I=1,20
READ (5,2001) NEXT, J ,(XCIT(I,K),K=1,6)
KCIT(I) = J
KREAD = I
IF (NEXT.EQ.0) RETURN
201 CONTINUE
RETURN
KRETURN
1003 FORMAT(7F10.0)
1011 FORMAT(2X,18,15A4/17A4/1/4)
2001 FORMAT(11,14,5X,6F10.0)
END

```

```

READ0550
READ0560
READ0570
READ0580
READ0590
READ0600
READ0610
READ0620
READ0630
READ0640
READ0650
READ0660
READ0670
READ0680
READ0690
READ0700
READ0710
READ0720
READ0730
READ0740
READ0750

```



```

60      G(IR+1,2)=Y
      X= G(IR+1,1)*.999
      Y=DMAX1(DABS(G(IR+1,2)*.99900),DABS(1.0-3*G(IR+1,1)))
174     DO 40 I=1,11
40      UMP(I)=0.
      GO TO 15
17      DXNI=DX
      DYNI=DY
      DXSP=DXS
      DX=DS*X
      DY=DS*Y
      DXS=DX*DX+DY*DY
      X=X+DX
      Y=Y+DY
15      RETURN
69      ICT=ICT+1
      IF(U. EQ. 0..AND. V. EQ. 0. ) GO TO 160
      IF( IR)62,62,19
      CALL OVERFL(IOV)
19      DO 23 J=1,15
      XI=X-CS(J)
      YI=Y
      TS4=V/U
      IF(BS(J))90,90,91
      YI=(Y+Y)*XI
      XI=(XI-Y)*(XI+Y)+8S(J)
      TS2=U/(XI*XI+YI*YI)
      U=(XI+YI*TS4)*TS2
      V=(TS4*XI-YI)*TS2
      CALL OVERFL(IOV)
      GO TO (160,62,160).IOV
62      US=DABS(U)+DABS(V)
      U7=U7+US-US3
      U6=U4
      U5=U3
      U4=V-U2
      U3=U-U1
      U2=V
      U1=U
      US3=US2
      US2=US1
      US1=US
      IF(ICT-2)13,17,84
84      AVG=3./U7
      DO 126 I=1,6
126     DF(I)=UMP(I)*AVG
      IF(DY)55,56,55
56      DRN=DX/DXNI
      TS3=(DUN-DRN*DUNI)*DRN
      TS=1.+DRN
      TS1=TS*DUN+TS3
      TS5=-2.*UN*TS
      TS7=TS1*TS1+2.*TS3*TS5
137     DXNI=DX

```

```

RODA0550
RODA0560
RODA0570
RODA0580
RODA0590
RODA0600
RODA0610
RODA0620
RODA0630
RODA0640
RODA0650
RODA0660
RODA0670
RODA0680
RODA0690
RODA0700
RODA0710
RODA0720
RODA0730
RODA0740
RODA0750
RODA0760
RODA0770
RODA0780
RODA0790
RODA0800
RODA0810
RODA0820
RODA0830
RODA0840
RODA0850
RODA0860
RODA0870
RODA0880
RODA0890
RODA0900
RODA0910
RODA0920
RODA0930
RODA0940
RODA0950
RODA0960
RODA0970
RODA0980
RODA0990
RODA1000
RODA1010
RODA1020
RODA1030
RODA1040
RODA1050
RODA1060
RODA1070
RODA1080

```

```

DX=TS5*DX/(TS1+DSIGN(DSORT(DABS(TS7)),TS1))
GO TO 138
JPN=(DX*DXNI+DY*DYNI)/DXSP
DIN=(DY*DXNI-DX*DYNI)/DXSP
TS1=DUN-DRN*DUNI+DIN*DVNI
TS2=DVN-DIN*DUNI-DRN*DVNI
TS3=DRN*TS1-DIN*TS2
TS4=DRN*TS2+DIN*TS1
TS=1+DRN
TS1=TS*DUN-DVN*DIN+TS3
TS2=TS*DVN+DUN*DIN+TS4
TS5=2*(VN*DIN-UN*TS)
TS6=-2*(VN*TS+UN*DIN)
TS7=(TS1-TS2)*(TS1+TS2)+2*(TS5*TS3-TS4*TS6)
TS8=2*(TS1*TS2+TS4*TS5+TS3*TS6)
TS9=DABS(TS7)*DSORT(1+(TS8/TS7)**2)
TS3=DSORT(.5*DABS(TS9+TS7))
TS4=DSIGN(DSORT(.5*DABS(TS9-TS7)),TS8)
134 IF(TS1*TS3+TS2*TS4)132,131,131
132 TS4=-TS4
TS3=-TS3
131 TS7=TS1+TS3
TS8=TS2+TS4
TS3=TS7**2+TS8**2
TS1=(TS5*TS7+TS6*TS8)/TS3
TS7=(TS6*TS7-TS5*TS8)/TS3
DXNI=DX
DYNI=DY
DX=TS1*DXNI-TS2*DYNI
DY=TS2*DXNI+TS1*DYNI
DXSP=DXS
Y=Y+DY
IF (DABS(Y) .GT. 1.0-5 .AND. DABS(Y/X) .GT. '5.D-4 ) GO TO 128
V=0.
DY=0.
128 YS=Y*Y
138 X=X+DX
TST=X*X+Y*Y
IF(TST-1.0-15)41,41,74
41 FM=FR
38 IM=C
73 X=0.
Y=0.
YS=0.
GO TO 160
74 DXS=DX*DX+DY*DY
AT=DXS/TST
IF (AT .LF. 1.0-15 ) GO TO 20
IF (ICT -21 ) 305,87,88
** IF(AT-ATX) 87,70,70
05 AT=ATX
X=XX
Y=YX
YS=YX

```

```

RDDA1090
RDDA1100
RDDA1110
RDDA1120
RDDA1130
RDDA1140
RDDA1150
RDDA1160
RDDA1170
RDDA1180
RDDA1190
RDDA1200
RDDA1210
RDDA1220
RDDA1230
RDDA1240
RDDA1250
RDDA1260
RDDA1270
RDDA1280
RDDA1290
RDDA1300
RDDA1310
RDDA1320
RDDA1330
RDDA1340
RDDA1350
RDDA1360
RDDA1370
RDDA1380
RDDA1390
RDDA1400
RDDA1410
RDDA1420
RDDA1430
RDDA1440
RDDA1450
RDDA1460
RDDA1470
RDDA1480
RDDA1490
RDDA1500
RDDA1510
RDDA1520
RDDA1530
RDDA1540
RDDA1550
RDDA1560
RDDA1570
RDDA1580
RDDA1590
RDDA1600
RDDA1610
RDDA1620

```

```

75  FM=FB
    GO TO 20
87  ATX=AT
    XX=X
    YX=Y
    YSX=YS
70  IF (ICT.LT. 25 ) GO TO 305
    IF (AT.NE. ATX ) GO TO 95
    IF (ICT.GE. 40) GO TO 75
305  (F(TST-SLIM2)15,15,50
31  V=-Y
    SS(IS)=YS
    IS=IS-1
85  ICT=0
167  AT=0.
    20 CONTINUE
    IF (IR.EQ.6) GO TO 51
    IR=IR+1
    IS=IS+1
    CS(IS)=X
    G(IR,1)=X
    G(IR,2)=Y
    (FY.NE.0..AND..ICT.GT.0) GO TO 31
    DO 61 I=1,2
    TS2=EVL(1,I)-X
    IF (YS.GT.0.) TS2=TS2+YS
61  EVL(2,I)=FVL(2,I )/TS2
    D1=(EVL(2,1)+EVL(2,2))*5
    UNPT=01*Y
    IF (DABS(EVL(2,1)-EVL(2,2)) . LE. 1.0-4* DABS(D1)) GO TO 92
    IF (IP.LT. (0 ) GO TO 10
51  CONTINUE
    WRITE (6,54)
54  FORMAT ( ' SOLUTION EXCEEDS MAXIMUM NUMBER OF ROOTS.' )
    GO TO 36
50  WRITE (6,52) SLIM
52  FORMAT ( ' NEXT ROOT GREATER THAN' F10.1, ' RADIANS.' )
36  WRITE (6,655)
655  FORMAT ( ' INCOMPLETE FUNCTION, RESIDUE F(S) REMAINING.' )
92  (D=0
    IO=IR
    X=UMPT
    RETURN
    END

```

```

RODA1630
RODA1640
RODA1650
RODA1660
RODA1670
RODA1680
RODA1690
RODA1700
RODA1710
RODA1720
RODA1730
RODA1740
RODA1750
RODA1760
RODA1770
RODA1780
RODA1790
RODA1800
RODA1810
RODA1820
RODA1830
RODA1840
RODA1850
RODA1860
RODA1870
RODA1880
RODA1890
RODA1900
RODA1910
RODA1920
RODA1930
RODA1940
RODA1950
RODA1960
RODA1970
RODA1980
RODA1990
RODA2000
RODA2010
RODA2020
RODA2030
RODA2040
RODA2050
RODA2060

```

```

SUBROUTINE ROTAN (N)
COMMON /ANDDIT/ A1,R1,XK,XY,VI2,VI4,APDM,APFM,AROM,ARFM,
1 AYFM,ROTJ,XK43,XLIM,CBFAC,
2 GDISK(12),NOPST,YANAI,TANB1,
3 TANTI,TANT2,DCAFXX,IPRINT,NORADL,
4 SHEARL(12),SHEAPD(12),SHEARR(12),
5 XMOML(12),XMOMD(12)
6 APDS,ARDS,PFAC,RFAC,APOBS,ARBS
COMMON /ROMAN/
* ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
* T,PCC(2),COSE(7,2),BETAN(2),BETAX(2),BETAZ(2),
* AIB(2),APDD,ARDD,AYDD,AIR(2),
1 UPSI(12,2),DTRP,NPSI(2),ZZTR,
2 BETAD(12,2),BNPSI(2),
3 CONO2,GMAXV,RATF1,RATE2,STOP2,
4 THROT(2),TRIND,XGUST,BETAZO(2),GMAXV1,
5 GMAXV2,GMAXV3,GUSTYP,MNPSIR(2),
6 HUBKPS,HUBKPS,HUBTPS,HUBTRS,
7 KONFIG,LNGTH1,PILGH1,PSIREF(2),
8 START2,XMOML(12,2),
9 R(2),OR(2),T1(2),
A T2(2),TZR(2),XMA(2),
B XMB(2),AIBP(2),AIBR(2),
C APDR(2),ARDR(2),PSIO(2),
D XSTAH(2),YSTAH(2),
E HUBKPR(2),HUBKRR(2)
* AZETAR(2),VZETAR(2)
COMMON /MANARD/
1 V,IND,NMAG,APRMT,ARBMT,AYBMT,BETAO(2),TDELT,
2 BETAF(2),HGUSTE,HGUSTF,HGUSTW,HGUSTE,
3 VGUSTW,YGUSTE,GFWD,GLAT,GVERT,
4 VX6,VZ6,APD,VYB,ARD,AYD,
5 COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
6 APE,ARE,AIM,B1M,A1TR,B1TR,
7 XAR(2),YAR(2),ZAR(2),
8 VIR(2),ZETAR(2),HFORCE(2),
9 THRUST(2),TORQUE(2),YFORCE(2),
COMMON /STANRO/
1 J,W,ITM,VHS(2),LINK,DELE,VROT(2),
2 VSNO,YFIN(2),ZFEL(2),AIBAL(2),
3 B1BAL(2),COND1,SMING,PILGH2,PMGELL,
4 B(2),PMOM(2),RMDM(2)
COMMON /ROSTAR/
1 AM(2),CT,PI,XB(2),ALT,ADR(2),EXH(2),
2 NXR(2),RBH(2),SMC(2),UHS,COMB(2),LR0T(2),
3 R AIB(2),RTRP(2),TATR(14),CONEK(2),DCAFR(2),FVIND,
4 NVARO,
5 SWKR(2),SWKR2(2),TIPR(2),TIP3B(2),
6 TWIST(20,2),CLRAOK(2),DELTA3(2),
7 LAMBDAL(2),UPGUST,URGUST,UTGUST,WR0TOR,
8 ER(2),ERX(2),
9 XLIMAX(2),XLIMIN(2)
COMMON /TOPILOT/
1 AH(3),AL(3),EXIT,ICOM(49),IPSM,
2 NPART,NVARA,NVARB,NVARC,NSCALE
3 *NVAR,NPRINT,NTIME
4 DIMENSION FLAP(1,2),HEADRO(6),AA(60)
5 EQUIVALENCE (FLAP(1,1),AIM),(AA(1),SHEARL(1))
6 DATA HEADRO/'MAIN FWD RTAIL AFTLEFT'/

```

```

ROTA0010
ROTA0020
ROTA0030
ROTA0040
ROTA0050
ROTA0060
ROTA0070
ROTA0080
ROTA0090
ROTA0100
ROTA0110
ROTA0120
ROTA0130
ROTA0140
ROTA0150
ROTA0160
ROTA0170
ROTA0180
ROTA0190
ROTA0200
ROTA0210
ROTA0220
ROTA0230
ROTA0240
ROTA0250
ROTA0260
ROTA0270
ROTA0280
ROTA0290
ROTA0300
ROTA0310
ROTA0320
ROTA0330
ROTA0340
ROTA0350
ROTA0360
ROTA0370
ROTA0380
ROTA0390
ROTA0400
ROTA0410
ROTA0420
ROTA0430
ROTA0440
ROTA0450
ROTA0460
ROTA0470
ROTA0480
ROTA0490
ROTA0500
ROTA0510
ROTA0520
ROTA0530
ROTA0540

```

```

200  A1=FLAP(1,N)
      R1=FLAP(2,N)
      DO 200 K=1,60
      AAK(K)=C.
      CONTINUE
      NJPSI=NPSI(N)
      NDRADL = NXR(N)
      IPRINT = 0
      IF(ICOND2.GT.2.5) IPRINT = 1
      IF(LINK.LT.4.OR.IND.NE.1.OR.TAIR(1).GT.(T+TDELTA)) GO TO 199
      IF(N.EQ.1.AND.NVARC.EQ.0.AND.NVARD.NE.0) GO TO 199
      IF(N.EQ.2.AND.NVARC.EQ.0.AND.NVARD.EQ.0) GO TO 199
      IPRINT=1
      CONTINUE
190  CALL RATS (GFWD,GLAT,GVERT,0.,-ZETAR(N),0.,GMFWD,GMLAT,GMVERT,-1)
      NRDT=KONFIG+3*(N-1)
      RDTJ=3-2*N
      AISV=A1
      B1SV=R1
      T1S=T1(N)
      T2S=T2(N)
      KOUNT=0
      CALL DOGS (ARD,APD,AYD,XAR(N),YAR(N),ZAR(N),VXR,VYR,VZR)
      AYFM=AYE
      CALL CATS (0.,-ZETAR(N),0.,AYE,APE,ARE,AYFM,APFM,ARFM,1,1)
      CBFAC=COS(APFM)*COS(ARFM)
      CALL RATS (0.,0.,WROTRD,AYFM,APFM,ARFM,XWRDT,YMROT,ZHROT,-1)
      FFWD=XWRDT*GMFWD
      FSIDE=YMROT*GMLAT
      VXR=VXR+VXB
      VYR=VYR+VYB*SWC(N)
      VZR=VZR+VZB
      VROT(N)=SORT(VXR**2+VYR**2+VZR**2)
      ALT=-ZZ
      VI2=.5*VROT(N)**2
      VI4=VI2**2
601  CONTINUE
      FWD5=HFORCE(N)
      FLATS=YFORCE(N)
      DT1=SMKR1(N)*(HFORCE(N)-FFWD)
      DT2=-SMKR2(N)*(YFORCE(N)+FSIDE)
      T1(N)=T1S+DT1
      T2(N)=T2S+DT2
      KOUNT=KOUNT+1
      AYBM=C.
      APBM=-ZETAR(1)
      ARBM=C.
      IF(N.EQ.1) GO TO 207
      T2(N)=-T2(N)
      AROR(N)=-AROR(N)
      YFORCF(N)=-YFORCE(N)
      A1=-B1
      AYBM=AYBMT

```

```

ROTA0550
ROTA0560
ROTA0570
ROTA0580
ROTA0590
ROTA0600
ROTA0610
ROTA0620
ROTA0630
ROTA0640
ROTA0650
ROTA0660
ROTA0670
ROTA0680
ROTA0690
ROTA0700
ROTA0710
ROTA0720
ROTA0730
ROTA0740
ROTA0750
ROTA0760
ROTA0770
ROTA0780
ROTA0790
ROTA0800
ROTA0810
ROTA0820
ROTA0830
ROTA0840
ROTA0850
ROTA0860
ROTA0870
ROTA0880
ROTA0890
ROTA0900
ROTA0910
ROTA0920
ROTA0930
ROTA0940
ROTA0950
ROTA0960
ROTA0970
ROTA0980
ROTA0990
ROTA1000
ROTA1010
ROTA1020
ROTA1030
ROTA1040
ROTA1050
ROTA1060
ROTA1070
ROTA1080

```

```

APRM=APRMT
ARBM=ARRMT
ALT=ZTR
287 CONTINUE
XLIM=XLIMAX(N)
CALL RATS (VXR,VYR,VZP,AYBM,APRM,ARBM,VXS(N),VYS(N),VZS(N),-1)
IHS=VYS(N)*2+VYS(N)*2
VHS(N)=SORT(IHS)
VYS(2)=-VYS(2)
TANT1=TANT1(N)
TANT2=TANT2(N)
CALL RATS (APD,APD,AYD,AYBM,APBM,ARBM,ARDS,APDS,AYS,-1)
CALL RATS (ARDD,APDD,AYD,AYBM,APRM,ARRM,ARDD,APDS,AYDS,-1)
PSD2=PSD(N)*2.
APDS=APDS-VZETAR(N)
ARDM=PSD2*ARDS+APDS-1*LTAR(N)
APDM=PSD2*APDS-APDS
IF(LINK.NE.2) GO TO 289
APDR(N)=APDS
IF(N.FO.2) ARDR(N)=-ARDS
APDR(N)=APDS
289 CONTINUE
IF(LINK.FO.4) GO TO 288
APDBS=APDR(N)-APDS
APDBS=ARDR(N)-APDS
288 CONTINUE
XK=11.25*VHS(N)
IF(VHS(N).GT.(.1067*OR(N))) XK=1.36*OR(N)-1.5*VHS(N)
IF(VHS(N).GT.(.5733*OR(N))) XK=.5*OR(N)
IF(ARS(OR(N)).LT.R(N)) GO TO 286
XK=XK/OR(N)
GO TO 1001
286 XK=.5
1001 CONTINUE
XK43=XK*1.33333
OCAFXK=OCAXR(N)*XK
IF(GUSTYP.LT.1.) GO TO 17
AYFM=AYF
CALL GATS (AYBM,APBM,ARBM,AYE,APF,AYE,APFM,ARFM,1,1)
GO TO 19 K=1,120
GO(SK(K))=0.
19 CONTINUE
17 CONTINUE
CALL ITROT (N)
IF(EXIT.NF.0.) RETURN
IF(N.FO.1) GO TO 304
VYS(2)=-VYS(2)
T2(N)=-T2(N)
ARDR(N)=-ARDR(N)
YFORCE(N)=-YFORCE(N)
A1=-A1
PHOM(N) = -RHOM(N)
104 IF(LINK.FO.4.OR.SMKRI(N).EQ.0.) GO TO 606
195MF=ABS(HFORCE(N)-FWD5)

```

```

ROTA1090
ROTA1100
ROTA1110
ROTA1120
ROTA1130
ROTA1140
ROTA1150
ROTA1160
ROTA1170
ROTA1180
ROTA1190
ROTA1200
ROTA1210
ROTA1220
ROTA1230
ROTA1240
ROTA1250
ROTA1260
ROTA1270
ROTA1280
ROTA1290
ROTA1300
ROTA1310
ROTA1320
ROTA1330
ROTA1340
ROTA1350
ROTA1360
ROTA1370
ROTA1380
ROTA1390
ROTA1400
ROTA1410
ROTA1420
ROTA1430
ROTA1440
ROTA1450
ROTA1460
ROTA1470
ROTA1480
ROTA1490
ROTA1500
ROTA1510
ROTA1520
ROTA1530
ROTA1540
ROTA1550
ROTA1560
ROTA1570
ROTA1580
ROTA1590
ROTA1600
ROTA1610
ROTA1620

```

```

A3SYF=ABS(YFORCE(N)-FLATS)
IF(KOUNT.EQ.1) GO TO 606
IF(KOUNT.EQ.10) GO TO 602
  ABOVE CARD USED IF DIAGNOSTICS WANTED
  IF(ABSHE.GT.1..OR.ABSYF.GT.1.) GO TO 601
  GO TO 606
602 WRITE (6,603) HEADRO(NROT),ABSHE,ABSYF
606 CONTINUE
IF(TPIND.EQ.0..AND.N.EQ.2) GO TO 305
IF(GUSTYP.LT.1..OR.I.NE.2) GO TO 305
IF(N.EQ.1) WRITE(6,9070) VGUSTM,HGUSTE,HGUSTM,HGUSTE,HGUSTF,YGUSTF
CALL DISK (GDISK)
305 IF(NWAG.FO.0) GO TO 503
  LROT(N)=LROT(N)+1
  DLIFT=THRUST(N)-THROT(N)
  CALL WAG (R,N),LROT(N),N,V,TDELT,RED,DLIFT)
  THRUST(N)=THRUST(N)-RFD
503 IF(LINK.EQ.2..AND.J.EQ.1) RETURN
  AIBAL(N)=A1
  IIBAL(N)=B1
  FLAP(1,N)=A1SV
  FLAP(2,N)=B1SV
  IF(TPRINT.EQ.0) RETURN
  IF(N.FO.1..AND.NVARD.NE.0) RETURN
  DO 702 L=1,13
  TATR(L)=TAIR(L+1)
702 CONTINUE
  TAIR(14)=9999.
  RETJPN
503 FORMAT (1H0//10X,A4,' ROTOR H-FORCE AND Y-FORCE NOT BALANCED. DELTROTAL920
1AS APF,2GLS,7,5X,'LRS. ')
9770 FORMAT(61H VGUSTM VGUSTE HGUSTM HGUSTE HGUSTF
15USTF/1H ,6F10.3)
  FND

```

```

ROTA1630
ROTA1640
ROTA1650
ROTA1660
ROTA1670
ROTA1680
ROTA1690
ROTA1700
ROTA1710
ROTA1720
ROTA1730
ROTA1740
ROTA1750
ROTA1760
ROTA1770
ROTA1780
ROTA1790
ROTA1800
ROTA1810
ROTA1820
ROTA1830
ROTA1840
ROTA1850
ROTA1860
ROTA1870
ROTA1880
ROTA1890
ROTA1900
ROTA1910
ROTA1920
ROTA1930
ROTA1940
ROTA1950
ROTA1960

```

SETE0010
 SETE0020
 SETE0030
 SETE0040
 SETE0050
 SETE0060
 SETE0070
 SETE0080
 SETE0090
 SETE0100
 SETE0110
 SETE0120
 SETE0130
 SETE0140
 SETE0150
 SETE0160
 SETE0170
 SETE0180
 SETE0190
 SETE0200
 SETE0210
 SETE0220
 SETE0230
 SETE0240
 SETE0250
 SETE0260
 SETE0270
 SETE0280
 SETE0290
 SETE0300
 SETE0310
 SETE0320
 SETE0330
 SETE0340
 SETE0350
 SETE0360
 SETE0370
 SETE0380
 SETE0390
 SETE0400
 SETE0410
 SETE0420
 SETE0430
 SETE0440
 SETE0450
 SETE0460
 SETE0470
 SETE0480
 SETE0490

```

SUBROUTINE SETE A(71)
COMMON /FORCE/
COMMON /STRIAB/
1 DL,DM,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPD,ERR(10),KMI,PHD,
3 R12,SPD(6,6,3),XBM(21),XEL(14),
4 XER(7),XFC(28),XFN(7),XFS(35),
5 XGN(7),XIT(21),XMR(49),XTR(49),
6 XWG(21),YMR(21),YTR(21),YWG(21),
7 YEL(21),YFN(21),BLCG,DAMP,DEPD(10),
8 EPDS,EPDX(10),MASS,OSV1,TMRS,TTRS,
9 WLCG,XCON(63),XJFT(14),XMIN,AYEFP,
A BETAES(?),CNPCD,DHADDQ,OYBDR,GUESS,
P NPASS,PPH1(10,11),STACG,TZERO,
C XMAST,DHADAQ,DODCOL,OTRRCO,DYBDR,
D ENGRPM,MXPASS,PSD3OP,TRIINDI,XLIMIT
1 I,V,IND,NWAG,APRMT,ARBMT,AYBMT,BETA0(2),TDELT,
2 BETAE(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
3 VGUSTM,YGUSTF,GFND,GLAT,GVFRT,
4 VXB,VZB,APD,VYB,ARD,AYD,
5 COLSTK,CYSTKI,CYSTK2,PEDAL,AYE,
6 APE,ARE,AIM,RIM,A1TR,B1TR,
7 XAR(2),YAR(2),ZAR(2),
8 VIMR,V1TR,ZETA,ZETATR,HMR,HTR,
9 TMR,TTR,OMX,QTR,YMRF,YTRF

DIMENSION KS(6)
DATA KS/1,13,22,59,46,33/
DO 301 L=1,6
90(L,7)=-A(KS(L))
301 CONTINUE
DO 74 K=1,71
E(K)=A(K)
74 CONTINUE
F(72) = TMR
F(73) = HMR
F(74) = YMRF
F(75) = OMX
F(76) = TTR
F(77)=HTR
F(78) = YTRF
F(79) = QTR
OSV1 = 5*(OMX+QTR)
BETAES(1)=BETA0(1)
BETAES(2)=BETA0(2)
TMRS= TMR
TTRS=TTR
KMI=6
RETURN
END
  
```

SLTE0010
SLTE0020
SLTE0030
SLTE0040
SLTE0050
SLTE0060
SLTE0070
SLTE0080
SLTE0090
SLTE0100
SLTE0110

SUBROUTINE SLTE (PD ,J,L,M)
COMMON /TRONIC/ UU(6),VV(6),TAU(22),DAMP(22),NUMRTS,GAINB,
INDEX,STGAIN(6),TSTAP,COELTD,SLOT(3,9)
DIMENSION PD(10,11),K(3,2)
DATA K /2,5,4,1,3,5/
DO 10 I=1,3
 10 CONTINUE
 CALL SRY
 RETURN
 END

```
SUBROUTINE SLTT (A,B,K)
DIMENSION A(3,9),B(3,9)
L=K+2
DO 10 I=1,3
DO 10 J=K,L
A(I,J)=B(I,J)
9(I,J)=0.
10 CONTINUE
RETURN
END
```

```
SLTT0010
SLTT0020
SLTT0030
SLTT0040
SLTT0050
SLTT0060
SLTT0070
SLTT0080
SLTT0090
SLTT0100
```

```

SUBROUTINE SOLVE
COMMON /STRIAB/ DT(21),DT(21),E(79),F(10),X(10),
1 DL,DM,DX,DY,DZ,IX,IY,IZ,PD(10,11),
2 DTR,EPO,ERR(10),KMI,RHO,
3 R12,SPD(6,6,3),XBM(21),XEL(14),
4 XEP(7),XFC(29),XFN(7),XFS(35),
5 XGN(7),XIT(21),XMR(49),XTR(49),
6 XWG(21),YMR(21),YTR(21),YWG(21),
7 YEL(21),YFN(21),BLCG,DAMP,DEPD(10),
8 FPD,EPDX(10),MASS,OSV1,TMRS,TTRS,
9 WLCG,XCON(6,3),XJET(14),XMIN,AYEFP,
A BETAES(2),CMPCD,OHADQ,DYBDR,GUESS,
B NPASS,PDPHI(10,11),STACG,TZERO,
C XMAST,DHADAQ,DONCOL,OTRRSQ,DYBDR,
D FNGRPM,MXPASS,PSD3OP,TRIN01,XLIMT
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
1 NPART,NVARA,NVARB,NVARC,NSCALE
2 *NVARA,NPRINT,NTIME
C SOLUTION OF KMI LINEAR EQUATIONS IN KMI VARIABLES
VI = 1 + KMI
NM1=KMI-1
DO 150M = 1, KMI
K = M + 1
C CHECK FOR ZERO ON DIAGONAL
IF(ABS(PDPHI(M,M)).GE.1.E-05)GO TO 100
DO 81 I=K,KMI
81 CONTINUE
IF(ABS(PDPHI(I,M)).GE.1.E-05)GO TO 82
C SINGULAR MATRIX NO SOLUTION
EXIT=1.
RETURN
82 DO 85 III=1,N1
3=PDPHI(I,III)
PDPHI(I,III)=POPFI(M,III)
85 POPFI(M,III)=B
100 DO 110J = K, N1
110 PDPHI(M,J)=POPFI(M,J)/POPFI(M,M)
IF(KMI-LT,K)GO TO 160
DO 150MP = K, KMI
DO 150 J = K, N1
150 POPFI(MP,J)=POPFI(MP,J)-PDPHI(MP,M)*PDPFI(M,J)
160 DO 180M = 1, KMI
180 X(M)=PDPFI(M,N1)
DO 250KI = 1, NM1
J = N1 - KI
K = J - 1
DO 250M = 1, K
250 X(M)=X(M)-PDPFI(M,J)*X(J)
RETURN
END

```

SOLV0010
SOLV0020
SOLV0030
SOLV0040
SOLV0050
SOLV0060
SOLV0070
SOLV0080
SOLV0090
SOLV0100
SOLV0110
SOLV0120
SOLV0130
SOLV0140
SOLV0150
SOLV0160
SOLV0170
SOLV0180
SOLV0190
SOLV0200
SOLV0210
SOLV0220
SOLV0230
SOLV0240
SOLV0250
SOLV0260
SOLV0270
SOLV0280
SOLV0290
SOLV0300
SOLV0310
SOLV0320
SOLV0330
SOLV0340
SOLV0350
SOLV0360
SOLV0370
SOLV0380
SOLV0390
SOLV0400
SOLV0410
SOLV0420
SOLV0430
SOLV0440
SOLV0450
SOLV0460
SOLV0470
SOLV0480
SOLV0490
SOLV0500

SRT00010
 SRT00020
 SRT00030
 SRT00040
 SRT00050
 SRT00060
 SRT00070
 SRT00080
 SRT00090
 SRT00100
 SRT00110
 SRT00120
 SRT00130
 SRT00140
 SRT00150
 SRT00160
 SRT00170
 SRT00180
 SRT00190
 SRT00200
 SRT00210
 SRT00220
 SRT00230
 SRT00240
 SRT00250
 SRT00260
 SRT00270
 SRT00280
 SRT00290
 SRT00300
 SRT00310
 SRT00320
 SRT00330
 SRT00340
 SRT00350

```

SURROUTINE SRT
COMMON /STBD/ UX,UY,U,V,T,A(9,2),IO,IO2,G(6,2),SLIM,IO,IL
COMMON /TRONIC/ UU(6),VV(6),TAU(22),DAMP(22),NR,GAINR,
INDEX,STGAIN(6),TSTAR,COL,SLOT(3,9)
1 DOUBLE PRECISION UX,UY,U,V,T,A,UR,G,UI
DO 1 I=1,6
DO 1 J=1,2
G(I,J) = 0.
ID=6
IO=3
IO2=9
IL=1
SLIM=10000.
T=1.
CALL R00A
UR=(UX-UY)*(UX+UY)
UI= ? *UX*UY
DO 2 L=1,3
M= 3*L-3
DO 2 I=1,3
N=M+I
K=3*I-2
A(N,1) = SLOT(L,K+2)+SLOT(L,K+1)*UX + SLOT (L, K ) *UR
A(N,2) = SLOT(L,K+1) *UY +SLOT IL,K )*UI
CALL DET
CALL R00B
IF (IL)161,24,161
NR=ID
IF(NR.GT.4) NR=4
COL=UX
DO 3 J=1,IO
UU(J)=GI(J,1)
VV(J)=G(J,2)
RETURN
END
  
```

1	COMMON /FORCF/	XF, XFRWG, XFLWG, XFELE, XFFUS, XFRJET, XFLJET, XFR, XFR, XFFIN, XFM, YFFUS, YFRJET, YFLJET, YFMR, YFTR, YFGUN, YFFIN, YFW,	STAB0010
2		ZF, ZFRWG, ZFLWG, ZFFLE, ZFFUS, ZFRJET, ZFLJET, ZFR, ZFR, ZFGUN, ZFW,	STAB0020
3		QL, LRWG, LLWG, LEUF, LFUS, LRJET, LLJET, LMR, LTR, LLGUN, LFIN, LOMR, LOTR,	STAB0030
4		OM, MRWG, MLWG, MELE, MFUS, MRJET, MLJET, MMR, MTR, MGJN, MFIN, MOMR, MOYR,	STAB0040
5		ON, NRWG, NLWG, NELE, NEFUS, NRJET, NLJET, NMR, NTR, NGUN, NFIN, NOMR, NOTR	STAB0050
6	COMMON /STRIB/	D(21), DT(21), E(79), F(12), X(10), DL, DM, DN, DX, DY, DZ, IX, IY, IZ, PD(10, 11), DTR, EPD, ERP(10), KMI, RMC,	STAB0060
7		R12, SPD(6, 6, 3), XRM(21), XEL(14), XEP(7), XFC(28), XFN(7), XFS(35), XGN(7), XIT(21), XMR(49), XTR(49),	STAB0070
8		XWG(21), YMR(21), YTR(21), YMG(21), YEL(21), YFN(21), BLCG, DAMP, DEPD(10),	STAB0080
9		EPDS, EPDX(10), MASS, OSV1, THPS, TTRS, WCG, XCON(63), XJET(15), XMIN, AVEFP, BETA(2), CNPCD, DMAJQ, DYBR, GUESS,	STAB0090
0		NPASS, PDPH(10, 11), STAGG, ZERO, XMAST, DHADAO, ODDCOL, DTRRSO, DYBDBR, FNGRPM, XYPASS, PS03OP, TRINDI, XLIMIT	STAB0100
1	COMMON /STRIMA/	AY, VHM, OM, DT(2), DT2(2), IXZ, OMR, XXD, YYD, ZZO, ALGF, APEP, AYFP, CGML, COLL(6), CYCF(3), CYCL(3),	STAB0110
2		DIST, KCIT(20), PEDA(3), OMAX, OMR, TIME, TMAX, XCIT(20, 6), ALGEZ, ALGF1, ALGE2, CGSTA, CPMIC, DIXIZ,	STAB0120
3		DIYIX, DIZIY, DTZMT, DTZMI, DIZTI, FTKTS, HUBKI(2, 2), HUBKI(2, 2),	STAB0130
4		KREAD, PIJ30, TSTAB(14), ZMAX2, ZMAX3, ASECOL, CYPMIC, GFARAT, PSD590, PS1STP, QXBRK, RUDIND, ZDELTI, ZDELTZ	STAB0140
5	COMMON /MANAL/	O, AP, PED, OMG, T2M, TIM, T2M, ZET, T1T, T2T, ALEL, CZFT, PSDD,	STAB0150
6		ALCYP, ALFIN, ALLWG, ALRNG, COELE, COFIN, COLMG, CORWG, CLELE, CLFIN, CLLMG, CLRMG, CWMG, CYCR1, CYCR2, CZET4, CZET6, CZET9, RANGE, SZETS, SZET7, SZET8, MGCOL, XAELE, XAFIN, XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,	STAB0160
7		YAELE, YAFUS, YALWG, YARWG, YALJET, YARJET, ZAJET, ALECR1, ALGFPD, BOTTOM, CZET11, CZET12, CZET13, EI'ETA, HALFPI, SZET10, XAPYLD, YGUSTM, ZAPYLD, ZFLWGI, ZFRWGI	STAB0170
8		TZMS, TMS, T2MS, TZTS, T1TS, T2TS, CLOCK, FLOCK, XLOCK, TLOCK	STAB0180
9	COMMON /ROMAN/	ZZ, VXS(2), VYS(2), VZS(2), BETA(12, 2), T, PCC(2), COSE(7, 7, 2), BETAN(2), BETAZ(2),	STAB0190
0			STAB0200
			STAB0210
			STAB0220
			STAB0230
			STAB0240
			STAB0250
			STAB0260
			STAB0270
			STAB0280
			STAB0290
			STAB0300
			STAB0310
			STAB0320
			STAB0330
			STAB0340
			STAB0350
			STAB0360
			STAB0370
			STAB0380
			STAB0390
			STAB0400
			STAB0410
			STAB0420
			STAB0430
			STAB0440
			STAB0450
			STAB0460
			STAB0470
			STAB0480
			STAB0490
			STAB0500
			STAB0510
			STAB0520
			STAB0530
			STAB0540

```

*
1 A1R(2), APDD, ARDD, AYDD, A1R(2),
2 DPSI(12,2), OTRR, NPST(2), ZZTR,
3 RETAD(12,2), RNPS(2),
4 COND2, GMAXV, RATE1, RATE2, STOP2,
5 THROT(2), TRIND, XGUST, BETAZD(2), GMAXV1,
6 GMAXV2, GMAXV3, GUSTYP, MNPSIR(2),
7 HURKPS, HURKPS, HURTPS, HUBTRS,
8 KONFIG, LNSTH1, PILGH1, PSIRFF(2),
9 START2, XMDML1(12,2),
10 RM, RTR, OPM, OPTR, T1MT, T1TT,
11 T2MT, T2TT, T2MT, T2TT, XMA1, XMAIT,
12 XMB1, XMBIT, AIRPM, AIRPT, AIRM, AIRBT,
13 APTD, APTTD, ARTQ, ARTTD, PSD, PSD1,
14 XSTAHM, XSTAHT, YSTAHM, YSTAHT,
15 HUBKP, HURKTP, HUBKR, HUBKTR
16 , AZETA, AZETAT, VZETA, VZETAT
COMMON /MANAPO/ J, V, JND, NWAG, APRMT, ARBMT, AYBMT, BETAO(2), TDELT,
1 RETAE(2), HGUSTE, HGUSTF, GUSTM, VGUSTE,
2 VGUSTW, VGUSTF, GFMD, GLAT, GVFT,
3 VXB, V7B, APD, VY9, ARD, AYD,
4 COLSTK, CYSTK1, CYSTK2, PEDAL, AYE,
5 APE, ARE, AIM, B1M, A1TR, B1TR,
6 XAR(2), VAR(2), ZAR(2),
7 VIMR, V1TR, ZETA, ZETATR, HMR, HTR,
8 TMR, T1TR, OMX, OTR, YMR, YTRF
COMMON /STANDP/ J, M, LTM, VHS(2), LINK, OELE, VKOT(2),
1 VSND, VFIN(2), ZFEEL(2), AIBAL(2),
2 PIRAL(2), CONDI, SWING, PILCH2, PWCELL,
3 RM, RTR, PHOMM, PHOMT, RMDMM, RMDMT
COMMON /TOPLOT/ AH(3), AL(3), EXIT, ICOM(49), JPSN,
1 NPART, NVARA, NVARR, NVARC, NSCALF
2 , NVARS, NPRTINT, NTIME
COMMON /KVARTP/ KVAR(10)
3 DIME, VSION VAR(6), FPDD(6), A(7), WS(6), FEAD1(2)
4 , VAP1(6), UNIT(4), DAPTD(6), DARTD(6), DAPTTD(6),
5 DARTTD(6), VARSV(4), DPSISV(7,2)
EQUIVALENCE (VAR(1), VXB), (A(1), XF), (VARI(1), COLSTK)
DATA KS/12,2), 32, 45, 58, 71/
LTK=3
KVAR(5)=5
KVAR(6)=6
DZ741=RETAE(1)*PCC(1)
DZ771=RETAE(2)*PCC(2)
VIMPS=V)MR
VITKS=V)TP
DO 313 N=1,4
VAPSV(N)=VAP1(N)
313 CONTINUE
IF (PSD.EQ.0.) GO TO 309
DO 315 I=1,7
DPSISV(I,1)=DPSI(I,1)
DPSISV(I,2)=DPSI(I,2)
315 CONTINUE

```

```

STAR0550
STAR0560
STAR0570
STAR0580
STAR0590
STAR0600
STAR0610
STAR0620
STAR0630
STAR0640
STAR0650
STAR0660
STAR0670
STAR0680
STAR0690
STAR0700
STAR0710
STAR0720
STAR0730
STAR0740
STAR0750
STAR0760
STAR0770
STAR0780
STAR0790
STAR0800
STAR0810
STAR0820
STAR0830
STAR0840
STAR0850
STAR0860
STAR0870
STAR0880
STAR0890
STAR0900
STAR0910
STAR0920
STAR0930
STAR0940
STAR0950
STAR0960
STAR0970
STAR0980
STAR0990
STAR1000
STAR1010
STAR1020
STAR1030
STAR1040
STAR1050
STAR1060
STAR1070
STAR1080

```

```

J=1
VPS(1)=12
VPS(2)=12
CALL NOPS11 (NPS1,MNPS1R,ANPS1,DPS1)
CALL AJAC08
  (TM=40
A(RPM)=XMA1
A(RPM)=XMR1
A(RPT)=XMA1T
A(RPT)=XMB1T
309 CONTINUE
J=2
CALL SETE
CALL JACOBI
DO 312 J=1,6
  DAPTD(J)=0.
  DARTD(J)=0.
  DAPTTD(J)=0.
  DARTTD(J)=0.
312 CONTINUE
  KOUNTS=0
  COL=0.
  COLS=COL*STK
  JNIT(1)=100.*RANGE/COLL(1)
  JN(1)=100.*CYCF(3)/CYCF(1)
  JN(2)=100.*CYCF(3)/CYCF(1)
  JN(3)=100.*CYCL(3)/CYCL(1)
  JN(4)=100.*PEDA(3)/PEDA(1)
  CALL RATS (XXD,YYD,ZZD,AYE,APE,ARE,VX0,VY0,VZ0,-1)
DO 306 J=1,4
  DO 306 I=1,6
    PD(I,J)=PD(.,J)*UNIT(J)
306 CONTINUE
  WRITE (6,404)
  CALL WRVP (2,VARI,KMI,PD,TAXL,TAXR)
  CALL RATS (0.,0.,0.,M,AYE,APF,ARF,XFM,YFM,ZFM,-1)
  EPDD(1)=EPDS*100.
  EPDD(2)=EPDS*100.
  EPDD(3)=EPDS
  EPDD(4)=EPDS*100.
  EPDD(5)=EPDS
  EPDD(6)=EPDS
  DAPTD(3)=EPDD(3)
  CALL RATS (0.,EPDD(3),0.,AYBMT,APBMT,ARBMT,DARTTD(3),DAPTTD(3),
1 TV,-1)
  DARTD(5)=EPDD(5)*CZET
  CALL RATS (EPDD(5),0.,0.,AYBMT,APBMT,ARBMT,DARTTD(5),DAPTTD(5),
1 TV,-1)
  DARTD(6)=EPDD(6)*SZET
  CALL RATS (0.,0.,EPDD(6),AYBMT,APBMT,ARBMT,DARTTD(6),DAPTTD(6),
1 TV,-1)
DO 55 J=1,6
  VAR(J)=VAR(J)+EPDD(J)
  APTD=APTD+DAPTD(J)
  ARTD=ARTD+DARTD(J)

```

```

STAB1090
STAB1100
STAB1110
STAB1120
STAB1130
STAB1140
STAB1150
STAB1160
STAB1170
STAB1180
STAB1190
STAB1200
STAB1210
STAB1220
STAB1230
STAB1240
STAB1250
STAB1260
STAB1270
STAB1280
STAB1290
STAB1300
STAB1310
STAB1320
STAB1330
STAB1340
STAB1350
STAB1360
STAB1370
STAB1380
STAB1390
STAB1400
STAB1410
STAB1420
STAB1430
STAB1440
STAB1450
STAB1460
STAB1470
STAB1480
STAB1490
STAB1500
STAB1510
STAB1520
STAB1530
STAB1540
STAB1550
STAB1560
STAB1570
STAB1580
STAB1590
STAB1600
STAB1610
STAB1620

```

```

APITD=APITD+DAPITD(J)
APITD=APITD+DAPITD(J)
IF(J.EQ.1) GO TO 307
VAR(J-1)=VAR(J-1)-EPDD(J-1)
APTD=APTD-DAPTD(J-1)
ARTD=ARTD-DAPTD(J-1)
APITD=APITD-DAPITD(J-1)
ARTD=ARTD-DAPITD(J-1)
307 CONTINUE
RETA(1)=BETAES(1)
RETA(2)=BETAES(2)
TMR=TMRS
TTP=TTPS
308 CONTINUE
CALL ANAL
IF(X(T.NE.O.) RETURN
IF(KOUNTS.NE.O) GO TO 305
WRITE(6,401)
TV=VAR(1)
VAP(3)=VAP(3)+OTPR
CALL WVP (1,VAR,KMI,PD,TAXL,TAXR)
VAP(3)=TV
CALL WRF *
309 CONTINUE
IF(J.NE.1.OR.ZETA.LT.1.396263.OR.PSD.EQ.O..OR.CLOCK.NE.O.) GOTO304
1.396263 PADIANS = 80. DEGREES
OSV2=.5*(OMX+OTR)
PO=OSV2-OSV1
IF(ABS(OO).LT.1001*APS(OSV1)) GO TO 302
KOUNTS=KOUNTS+1
IF(KOUNTS.GT.20) GO TO 302
IF(KOUNTS.NE.1) DDCCOL=(OSV2-OSV3)/DCOL
IF(KOUNTS.EQ.1) OSV3=OSV2
DCOL=DCOL-DO/DDCCOL
COLSTR=COLS+DCOL
CALL SWAS (COLSTR)
T2MT=T2M+DTZM1+DTZMT+ASECOL
T2TT=T2T+DTZT1+TRIND*(DTZMT+ASECOL)
T1MT=T1M+DT1(1)
T1TT=T1T+DT1(2)
T2MT=T2M+DT2(1)
T2TT=T2T+DT2(2)
GO TO 303
302 CONTINUE
COLSTR=COLS
CALL SWAS (COLSTR)
T2MT=T2M+DTZM1+DTZMT+ASECOL
T2TT=T2T+DTZT1+TRIND*(DTZMT+ASECOL)
T1MT=T1M+DT1(1)
T1TT=T1T+DT1(2)
T2MT=T2M+DT2(1)
T2TT=T2T+DT2(2)
KOUNTS=N
DDDU=(OSV3-OSV1)/EPDD(1)

```

```

STAB1630
STAB1640
STAB1650
STAB1660
STAB1670
STAB1680
STAB1690
STAB1700
STAB1710
STAB1720
STAB1730
STAB1740
STAB1750
STAB1760
STAB1770
STAB1780
STAB1790
STAB1800
STAB1810
STAB1820
STAB1830
STAB1840
STAB1850
STAB1860
STAB1870
STAB1880
STAB1890
STAB1900
STAB1910
STAB1920
STAB1930
STAB1940
STAB1950
STAB1960
STAB1970
STAB1980
STAB1990
STAB2000
STAB2010
STAB2020
STAB2030
STAB2040
STAB2050
STAB2060
STAB2070
STAB2080
STAB2090
STAB2100
STAB2110
STAB2120
STAB2130
STAB2140
STAB2150
STAB2160

```

```

374 WRITE (6,400) DDDCOL,DDDU,DCOL
CONTINUE
SPG(J,1,1)=XF-E(11)
SPD(J,2,1)=ZF-E(22)
SPD(J,3,1)=OM-E(46)
SPD(J,4,1)=YF-E(13)
SPD(J,5,1)=OL-E(33)
SPD(J,6,1)=ON-E(59)
SPD(J,1,2)=TMR-E(72)
SPD(J,2,2)=HMR-E(73)
SPD(J,3,2)=AIBAL(1)-AIM
SPD(J,4,2)=YMR-E(74)
SPD(J,5,2)=QMX-E(75)
SPD(J,6,2)=BIBAL(1)-91M
SPD(J,1,3)=TTR-E(76)
SPD(J,2,3)=HTR-E(77)
SPD(J,3,3)=AIBAL(2)-A1TR
SPD(J,4,3)=VTRF-E(78)
SPD(J,5,3)=QTR-E(79)
SPD(J,6,3)=BIBAL(2)-B1TR
DO 55 LL=1,3
DO 56 K=1,6
SPD(J,K,LL)=SPD(J,K,LL)/EPDD(J)
56 CONTINUE
DO 57 K=1,71
A(K)=A(K)-E(K)
57 CONTINUE
WRITE (6,402)
CALL WPFM
L=1
DO 59 K=1,6
M=KS(K)
RAL=1.
IF(ALL).NE.C.) RAL=100./A(L)
DO 58 KK=L,M
A(KK)=A(KK)*RAL
58 CONTINUE
L=M+1
59 CONTINUE
WRITE (6,403)
CALL WPFM
55 CONTINUE
VAR(6)=VAR(6)-EPDD(6)
APT0=APT0-DAPT0(6)
ART0=ART0-DART0(6)
APTT0=APTT0-DAPTT0(6)
ARTTD=ARTTD-DARTTD(6)
WRITE (6,152) ((SPO(I,J),I=1,6),J=1,6)
WRITE (6,153) HEAD1(1),((SPO(I,J,2),I=1,6),J=1,6)
WRITE (6,153) HEAD1(2),((SPO(I,J,3),I=1,6),J=1,6)
XAELE=XAELE-XAWS
(FOMG,GE..5*Q) GO TO 300
OMG=.5*Q
CM(NG)=1.

```

```

STAB2170
STAB2180
STAB2190
STA92200
STAB2210
STAB2220
STAB2230
STAB2240
STAB2250
STAB2260
STAR2270
STA92280
STAB2290
STAB2300
STAB2310
STAB2320
STAB2330
STAB2340
STAB2350
STAB2360
STAB2370
STAB2380
STAB2390
STAB2400
STA92410
STAB2420
STAB2430
STAB2440
STAB2450
STAB2460
STA92470
STAB2480
STAB2490
STAB2500
STA92510
STAB2520
STAB2530
STAB2540
STAB2550
STAB2560
STAB2570
STAB2580
STA92590
STAB2600
STA92610
STAB2620
STAB2630
STAB2640
STAB2650
STA92660
STAB2670
STAB2680
STAB2690
STAB2700

```

```

300 CONTINUE
SWING=1.
DO 299 J=1,4
DO 298 I=1,6
PD(I,J)=PD(I,J)/V
298 CONTINUE
299 CONTINUE
CALL LMODE (V,OMG,E(12),E(32),CWING,XAE(LM))
CALL LMODE (V,OMG,E(32),SWING)
LINK=4
BETA(1)=BETAES(1)
BETA(2)=BETAES(2)
TMR=TMRS
YTR=YTRS
VIMR=VIMRS
VITR=VITRS
AIBPM=0.
AIBRM=0.
AIBPT=0.
AIBRT=0.
DO 311 J=1,13
TSTAR(J)=TSTAR(J+1)
311 CONTINUE
TSTAR(14)=9999.
DO 314 J=1,4
VAR1(J)=VARSV(J)
314 CONTINUE
IF(PSD.EQ.0.) GO TO 308
NPSI(1)=BN
NPSI(2)=BTR
CALL NPSI1 (NPSI,MNPSIR,BNPSI,DPSI)
DO 316 I=1,7
DPSI(I,1)=DPSISV(I,1)
DPSI(I,2)=DPSISV(I,2)
316 CONTINUE
ITM=7
308 CONTINUE
CALL TIMEX (TUSFO,DTIME,TLFFT)
WRITE (6,27) DTIME,TUSED
RETURN
27 FORMAT (1H7,10X,F7.3,' MINUTES USED IN STAB ',5X,F8.3,
' MINUTES TOTAL RUN TIME')
157 FORMAT (1H1,47X,'STABILITY PARTIAL DERIVATIVE MATRICES'
//1H0,30X,'U',17X,'Q',17X,'W',17X,'V',17X,'P',17X,'R',
/1H0,4X,'X-FORCE',6G18.7/
5X,'Z-FORCE',6G18.7/
5X,'PITCH MOMENT',6G18.7/
/5X,'Y-FORCE',6G18.7/
5X,'ROLL MOMENT',6G18.7/
5X,'YAW MOMENT',6G18.7/)
158 FORMAT ( /62X,A4,' ROTOR' /
/5X,' THRUST',6G18.7/
5X,' M-FORCE',6G18.7/
5X,' F/A FLAPPING',6G18.7/

```

```

STA92710
STA82720
STA52730
STA92740
STA82750
STA92760
STA92770
STA82780
STA82790
STA82800
STA82810
STA82820
STA82830
STA92840
STA82850
STA82860
STA82870
STA82880
STA82890
STA82900
STA82910
STA82920
STA82930
STA82940
STA82950
STA92960
STA82970
STA82980
STA92990
STA83000
STA93010
STA83020
STA83030
STA83040
STA83050
STA93060
STA83070
STA93080
STA83090
STA83100
STA83110
STA83120
STA83130
STA83140
STA83150
STA83160
STA83170
STA83180
STA83190
STA83200
STA83210
STA83220
STA83230
STA83240

```

```

4      /SX,'Y-FORCE          ',6G18.7/
5      5X,'TORQUE          ',6G18.7/
6      5X,'LAT FLAPPING   ',6G18.7/
400  FORMAT (I10,'DO/DCOL = ',G15.7,2X,'FT-LBS/PERCENT',/
1      I10,'DQ/DU = ',G15.7,2X,'FT-LBS/FT/SEC',/
2      I10,'DCOL = ',G15.7,2X,'PERCENT')
401  FORMAT (I10)
402  FORMAT (I10,63X,'DELTA')
403  FORMAT (I10,58X,'NORMALIZED DELTA')
404  FORMAT (I10,30X,'THE FIRST FOUR ROWS OF THIS MATRIX ARE LBS OR FT-
1LBS PER INCH OF CONTROL MOVEMENT')
      END

```

```

STAB3250
STAB3260
STAB3270
STAB3280
STAB3290
STAB3300
STAB3310
STAB3320
STAB3330
STAB3340
STAB3350
STAB3360

```


* 1	T, PCC(2), COSE(7, 7, 2), BFTAN(2), BETAX(2), BETAZ(2),	STAR0550
* 2	AIB(2), APDD, ARDC, AYDD, AIR(2),	STAR0560
1	NPSI(12, 2), DTR9, NPSI(2), ZZTR,	STAR0570
2	BETAD(12, 2), BNPSI(2),	STAR0580
3	COND2, GMAXV, RATE1, PATE2, STOP2,	STAR0590
4	THROT(2), TRIND, XGUST, BETAZD(2), GMAXV1,	STAR0600
5	GMAXV2, GMAXV3, GUSTYP, HNPISIR(2),	STAR0610
6	HURKPS, HURKRS, HURTPS, HUBTRS,	STAR0620
7	KONFIG, LNGTH1, PILGHI, PSIREF(2),	STAR0630
8	START2, XMDLI(12, 2),	STAR0640
9	RM, RTR, OPM, ORTR, TIMT, TITT,	STAR0650
A	T2MT, T2YT, T2MT, T2YT, XMAL, XMAIT,	STAR0660
B	XMB1, XMBIT, AIRPM, AIRPT, AIRRM, AIRBT,	STAR0670
C	APTD, AFTTD, ARTD, ARTTD, PSD, PSDT,	STAR0680
D	XSTAHM, XSTAHM, YSTAHM, YSTAHM,	STAR0690
E	HURKP, HURKTP, HURKR, HURKTR	STAR0700
F	AZETA, AZETAT, VZETA, VZETAT	STAR0710
1	I, V, IND, NMAG, APRMT, ARBT, AYBMT, BETA0(2), TDELT,	STAR0720
2	BETAF(2), HGUSTE, HGUSTF, HGUSTM, VGUSTE,	STAR0730
3	VGUSTW, VGUSTF, GFWD, GLAT, GVFRY,	STAR0740
4	VXB, VZB, APD, VVB, ARD, AYD,	STAR0750
5	COLSTK, CYSTKI, CYSTK2, PEDAL, AYE,	STAR0760
6	APE, ARE, AIM, RIM, ATR, B1TR,	STAR0770
7	XAR(2), YAR(2), ZAR(2),	STAR0780
8	VIMR, VITR, ZEVAR(2), HAR, MTR,	STAR0790
9	THRUST(2), OMX, OTR, YMR, YTRF	STAR0800
1	J, M, ITM, VMS(2), LINK, QELE, VROT(2),	STAR0810
2	VSND, YFIN(2), ZFEL(2), AIRAL(2),	STAR0820
3	BIBAL(2), CONDI, SWING, PILGH2, PMGELI,	STAR0830
4	R(2), PMOM(2), RMOM(2)	STAR0840
5	AM(2), CT, PI, XR(2), AI, T, ADR(2), EXH(2),	STAR0850
6	NXR(2), RBH(2), SWC(2), UHS, CDMB(2), LRROT(2),	STAR0860
7	RAIB(2), RTRPI(2), TAIR(14), CDNEK(2), DCAFR(2), FVIND,	STAR0870
8	NVARO,	STAR0880
9	SWR1(2), SWR2(2), TIPIB(2), TIP38(2),	STAR0890
1	TMIST(20, 2), CLRADK(2), DELTA3(2),	STAR0900
2	LAMBDA(2), UPGUST, URGUST, UTGUST, WROTOR,	STAR0910
3	ERM, FRTR, ERXM, FRXT,	STAR0920
4	XLMAXM, XLMAXT, XLMINM, XLMINI	STAR0930
5	BH(2), C3, C4, RW, CLP, CLR, DCD, DOL, DOM, VIM,	STAR0940
6	RAIB(2), CL80, CM90, ETAO, NJET,	STAR0950
7	QFIN,	STAR0960
8	VIER, CLBL, YES(14),	STAR0970
9	CNBL, CNPCL, CNRCD, CNRCL, COLKS, D3ELE,	STAR0980
1	FNSWC, LWMG, PMREL, PMRWG,	STAR0990
2	PTREN, RPIST, VMAXE, YAERO(31, 5),	STAR1000
3	APBJET, AR9JET, AYBJET,	STAR1010
4	CNPCD1, CNPCD2, COLJET, DXWDEL, DZWDEL,	STAR1020
5	ETAOMX, PMGKI, RCWING, SWINGH,	STAR1030
6	VENTER, VXMVER	STAR1040
7	COMMON /KVARTR/ KVAR(10)	STAR1050
8	DIMENSION HEAD(4, 14), HEAD1(2, 2)	STAR1060
9	DATA HEAD /	STAR1070
1	WING	STAR1080
	ELEVATOR	B
	FIN/RUDDER	
	MAIN ROTOR	
	TAIL ROTOR	
	JET	

```

20RWEIGHT          CONTROLFLIGHT CONSTANTS ALLOWABLE ERROR
3RAT10N           STAB TIMES AIRLOAD TIMES*/
DATA HEAD1 /' ROLL   YAW   ' /
REAL IX,IY,IZ,IXZ
GUESS=0.

READ IN DATA THRU SUBROUTINE READIN.
CALL READIN (T,TAIR)
CALCULATE PHYSICAL CONSTANTS.
DTR=.174532925E-01
RHO=.002378*XF(12A)
Q=.5*RAH0
PIU30=9.54929658
DTRRS0=3282.80635
DTRR=57.2957795
R12=1./12.
PI=3.1415926536
POL0TR=.174532925E-03
HALFPI=1.570796327
TWOPI=6.283185307
TRIND=0.
TRIND1=0.
RA1R(1)=0.
RA1B(2)=0.
RA1B(1)=0.
RA1B(2)=0.
SEARAT=0.

WRITE OUT HEADINGS.
CALL WR0T
WRITE (6,100)
WRITE (6,101) (HEAD(1,1),I=1,4),XFS

CALCULATE CONSTANTS FOR FUSELAGE - SEE INPUT FORMAT GUIDE FOR
DESCRIPTION OF CONSTANTS.
W=XFS(1)
STACG=XFS(5)*R12
WLCG=XFS(6)*R12
WLCG=XFS(7)*R12
CGSTA=XFS(5)
CGAL=XFS(6)
CGWL=XFS(7)
XAFUS=STACG-XFS(12)*R12
YAFUS=XFS(3)*R12-WLCG
7AFUS=WLCG-XFS(4)*R12
IX=XFS(8)
IY=XFS(9)
IZ=XFS(10)
IXZ=XFS(11)

```

```

ITFSTAR1090
STAR1100
STAR1110
STAR1120
STAR1130
STAR1140
STAR1150
STAR1160
STAR1170
STAR1180
STAR1190
STAR1200
STAR1210
STAR1220
STAR1230
STAR1240
STAR1250
STAR1260
STAR1270
STAR1280
STAR1290
STAR1300
STAR1310
STAR1320
STAR1330
STAR1340
STAR1350
STAR1360
STAR1370
STAR1380
STAR1390
STAR1400
STAR1410
STAR1420
STAR1430
STAR1440
STAR1450
STAR1460
STAR1470
STAR1480
STAR1490
STAR1500
STAR1510
STAR1520
STAR1530
STAR1540
STAR1550
STAR1560
STAR1570
STAR1580
STAR1590
STAR1600
STAR1610
STAR1620

```

STAR1630
 STAR1640
 STAR1650
 STAR1660
 STAR1670
 STAR1680
 STAR1690
 STAR1700
 STAR1710
 STAR1720
 STAR1730
 STAR1740
 STAR1750
 STAR1760
 STAR1770
 STAR1780
 STAR1790
 STAR1800
 STAR1810
 STAR1820
 STAR1830
 STAR1840
 STAR1850
 STAR1860
 STAR1870
 STAR1880
 STAR1890
 STAR1900
 STAR1910
 STAR1920
 STAR1930
 STAR1940
 STAR1950
 STAR1960
 STAR1970
 STAR1980
 STAR1990
 STAR2000
 STAR2010
 STAR2020
 STAR2030
 STAR2040
 STAR2050
 STAR2060
 STAR2070
 STAR2080
 STAR2090
 STAR2100
 STAR2110
 STAR2120
 STAR2130
 STAR2140
 STAR2150
 STAR2160

```

YFS(1)=XFS(20)
YFS(2)=XFS(21)*OTRR
YFS(3)=XFS(15)
YFS(4)=XFS(16)*OTRR
YFS(5)=XFS(17)
YFS(6)=XFS(18)*OTRR
YFS(7)=XFS(22)
YFS(8)=XFS(23)*OTRR
YFS(9)=XFS(24)*OTRRSO
YFS(10)=XFS(26)
YFS(11)=XFS(27)*OTRR
YFS(12)=XFS(28)*OTRRSO
YFS(13)=XFS(25)*OTRRSO
YFS(14)=XFS(32)
WR=XFS(29)/WR12
XAPYL=(XMR(8)-XFS(30))*WR
ZAPYL=(XMR(10)-XFS(31))*WR
HLPYLD=XFS(33)
WRITE (6,101) (HEAD(1,2),I=1,4),XMR,0,YMR

CALCULATE CONSTANTS FOR MAIN ROTOR - SEE INPUT FORMAT GUIDE FOR
DESCRIPTION OF CONSTANTS.

PSD30P = XMR(13)*XFC(25)
OMEGM = PSD30P/PIU30
PSD=OMEGM (ZETAR,BH,BAIB,XMR,Q,0,1)
CALL INRD (ZETAR,BH,BAIB,XMR,Q,0,1)
WRITE (6,101) (HEAD(1,3),I=1,4),XTR,DT,YTR

CALCULATE CONSTANTS FOR TAIL ROTOR - SEE INPUT FORMAT GUIDE FOR
DESCRIPTION OF CONSTANTS.

IF(XMR(13).NE.0.) GEARAT=XTR(13)/XMR(13)
PSDT=PSD*GEARAT
IF(XTR(14).NE.0.) TRIND=1.
SWC(2)=1.-XTR(28)
CALL INRD (ZETAR,BH,BAIB,XTR,0,0,8,2)
WRITE (6,101) (HEAD(1,4),I=1,4),XMG,YMG

CALCULATE CONSTANTS FOR WING - SEE INPUT FORMAT GUIDE FOR
DESCRIPTION OF CONSTANTS.

OMG=-.50*XWG(11)
XAWG=STAG-XWG(2)*R12
YAWG=XWG(3)*R12-BLCG
ZAWG=WLCG-XWG(4)*R12
AGW=XWG(5)*DTR
PRWG=XWG(8)
PWGK1 =XWG(9)*DTR
ETAOMX=XWG(10)
CLB0=XWG(12)
CLRCL=XWG(13)
CLR=XWG(14)

```

C
 C
 C
 C
 C

C
 C
 C
 C

C
 C
 C
 C

STAR2170
 STAR2180
 STAR2190
 STAR2200
 STAR2210
 STAR2220
 STAR2230
 STAR2240
 STAR2250
 STAR2260
 STAR2270
 STAR2280
 STAR2290
 STAR2300
 STAR2310
 STAR2320
 STAR2330
 STAR2340
 STAR2350
 STAR2360
 STAR2370
 STAR2380
 STAR2390
 STAR2400
 STAR2410
 STAR2420
 STAR2430
 STAR2440
 STAR2450
 STAR2460
 STAR2470
 STAR2480
 STAR2490
 STAR2500
 STAR2510
 STAR2520
 STAR2530
 STAR2540
 STAR2550
 STAR2560
 STAR2570
 STAR2580
 STAR2590
 STAR2600
 STAR2610
 STAR2620
 STAR2630
 STAR2640
 STAR2650
 STAR2660
 STAR2670
 STAR2680
 STAR2690
 STAR2700

CLP=XWG(15)
 CNB0=XWG(16)
 CNBCL=XWG(17)
 CNPCL=XWG(18)
 CNRCJ=XWG(19)*DTR
 CNPCL=XWG(20)
 CNPCD=XWG(21)
 WRITE (6,101) (HEAD(1,5),I=1,4),XEL,YEL
 CALCULATE CONSTANTS FOR ELEVATOR - SEE INPUT FORMAT GUIDE FOR
 DESCRIPTION OF CONSTANTS.

OELE=0*XEL(11)
 XAELE=STACG-XEL(2)*R12
 YAELE=XEL(3)*R12-BLCG
 ZAELE=WLCG-XEL(4)*R12
 ALGEZ=XEL(5)*DTR
 PMREL=XEL(8)
 VENTER=XEL(9)*1.6878
 VMAXE=XEL(10)*1.6878
 PMGEL1=XEL(11)*DTR
 WRITE (6,101) (HFAD(1,6),I=1,4),XFN,YFN
 CALCULATE CONSTANTS FOR FIN/RUDDER - SEE INPUT FORMAT GUIDE FOR
 DESCRIPTION OF CONSTANTS.

QFTN=0*XFN(1)
 XAFIN=STACG-XFN(2)*R12
 YAFIN=XFN(3)*R12-BLCG
 ZAFIN=WLCG-XFN(4)*R12
 ALGF=XFN(5)*DTR
 PTRFN=XFN(6)
 FNSWC=1.-XFN(7)
 WRITE (6,101) (HEAD(1,7),I=1,4),XJET
 CALCULATE CONSTANTS FOR JET - SEE INPUT FORMAT GUIDE FOR
 DESCRIPTION OF CONSTANTS.

XJET=XJET(1)
 TAXR=XJET(2)
 TAXL=XJET(3)
 XAJET=STACG-XJET(4)*R12
 YAJET=XJET(5)*R12-BLCG
 ZAJET=WLCG-XJET(6)*R12
 AYBJET=XJET(8)*DTR
 APBJET=XJET(9)*DTR
 WRITE (6,101) (HFAD(1,8),I=1,4),XBW
 CALCULATE CONSTANTS FOR BOBWEIGHT - SEE INPUT FORMAT GUIDE FOR
 DESCRIPTION OF CONSTANTS.

IF(XBW(1),EQ,0.) GO TO 12
 R1=XBW(16)/XBW(18)
 R2=R1*XBW(19)/XBW(20)

```

R3=R2*XBW(21)
TM1=XAW(9)*XBW(17)
TM=(TM1+R3*XBW(11))*R12
TI=XAW(4)+R1+2*XBW(5)+R2+2*XBW(6)+TM1*XBW(17)+
1 XBW(16)+2*XAW(8)+(R1*XBW(19))+2*XBW(10)+R3+2*XBW(11)
GPRFLD=XBW(7)
CF=386.04*XBW(15)+2/TI
BWC=XBW(3)*CF
BWK=XBW(2)*CF
BWM=R3*XBW(11)+DTR*TM/TI+12.
BWF= SORT(BWK)/TMOPI
WRITE (6,13) BWF
13 FORMAT (1H0,10X,'BOB WEIGHT FREQUENCY = ',G12.5,' CPS')
GO TO 14
12 BWC=0.
BWK=0.
BWM=0.
GPRFLD=0.
14 CONTINUE
WRITE (6,101) (HEAD(I,9),I=1,4),XCON
CALL COM1 (XCOM,DSELE,TRIND,COLJET,EIMAST,PCGOED,PCGMAX)
WRITE (6,101) (HEAD(I,10),I=1,4),XFC,XGM
XCD=XFC(1)*1.6878
YYD=XFC(2)*1.6878
ZZD=XFC(3)
ZZ=-XFC(4)
IALFS=IALF
IALF=XIT(15)
KVAR(5)=6
KVAR(6)=7
IF(IALF.LT.1.OR.IALF.GT.2) IALF=1
IF(IALF.EQ.2) KVAR(6)=5
IF(GUESS.EQ.2.AND.IALF.EQ.2.AND.IALFS.EQ.1) GO TO 18
AYE=XFC(5)+DTR
ARE=XFC(7)+DTR
18 CONTINUE
IF(GUESS.EQ.2) GO TO 15
APE=XFC(6)+DTR
COLSTK=XFC(8)
CYSTK1=XFC(9)
CYSTK2=XFC(10)
PEDAL=XFC(11)
A1=XFC(15)+DTR
R1M=XFC(16)+DTR
A1R=XFC(17)+DTR
R1TR=XFC(18)+DTR
THRUST(1)=XFC(19)
THRUST(2)=XFC(20)
GUESS=XFC(22)
15 CONTINUE
CALL WRVPI (HEAD1,IALF)
ENGRPM=XFC(25)
OMAX=1.0/OMEG.
IF(OMEGM.NE.0.AND.XFC(26).NE.0.) OMAX=XFC(26)+500./OMEGM

```

```

STAR2710
STAR2720
STAR2730
STAR2740
STAR2750
STAR2760
STAR2770
STAR2780
STAR2790
STAR2800
STAR2810
STAR2820
STAR2830
STAR2840
STAR2850
STAR2860
STAR2870
STAR2880
STAR2890
STAR2900
STAR2910
STAR2920
STAR2930
STAR2940
STAR2950
STAR2960
STAR2970
STAR2980
STAR2990
STAR3000
STAR3010
STAR3020
STAR3030
STAR3040
STAR3050
STAR3060
STAR3070
STAR3080
STAR3090
STAR3100
STAR3110
STAR3120
STAR3130
STAR3140
STAR3150
STAR3160
STAR3170
STAR3180
STAR3190
STAR3200
STAR3210
STAR3220
STAR3230
STAR3240

```


SWAS0010
 SWAS0020
 SWAS0030
 SWAS0040
 SWAS0050
 SWAS0060
 SWAS0070
 SWAS0080
 SWAS0090
 SWAS0100
 SWAS0110
 SWAS0120
 SWAS0130
 SWAS0140
 SWAS0150
 SWAS0160
 SWAS0170
 SWAS0180
 SWAS0190
 SWAS0200
 SWAS0210
 SWAS0220
 SWAS0230
 SWAS0240
 SWAS0250
 SWAS0260
 SWAS0270
 SWAS0280
 SWAS0290
 SWAS0300
 SWAS0310
 SWAS0320
 SWAS0330
 SWAS0340
 SWAS0350
 SWAS0360
 SWAS0370
 SWAS0380
 SWAS0390
 SWAS0400
 SWAS0410
 SWAS0420
 SWAS0430
 SWAS0440
 SWAS0450
 SWAS0460
 SWAS0470
 SWAS0480
 SWAS0490
 SWAS0500
 SWAS0510
 SWAS0520
 SWAS0530
 SWAS0540

```

SUBROUTINE SWAS1 (KL)
COMMON /MANAL/ Q,AP,PED,QMG,TZM,TIM,T2M,
  TZT,T1T,T2T,ALEL,CZET,PSDD,
  SZET,TAXL,TAXR,XAMG,XLNM(16),ZAMG,
  ALCYP,ALFIN,ALLMG,ALRMG,CDELE,COFIN,
  COLMG,CDRMG,CLELE,CLFIN,CLLMG,CLMG,CWING,
  CYCR1,CYCR2,CZET4,CZET6,CZET9,RANGE,
  SZET5,SZET7,SZET8,WGCOL,XAELE,XAFIN,
  XAFUS,XAJET,YAFIN,ZAELE,ZAFIN,ZAFUS,
  YAELE,YAFUS,YALMG,YARMG,YALJET,YARJET,
  ZAJET,ALECR1,ALGFPD,BOTTOM,CZET11,
  CZET12,CZET13,EIZETA,MALFPI,SZET10,
  XAPYLD,YGUSTM,ZAPYLD,ZFLMG1,ZFRMG1,
  TZMS,TIMS,TZMS,TCTS,TITS,TZTS,
  CLOCK,FLOCK,XLOCK,TCLOCK
  KONFIG=KL
RETURN
ENTRY SWAS (COLSTK)
  BOTTOM = RAD
  RANGE = RAD/PERCENT
  SINGLE ROTOR CONTROLS
  TZMR=COLSTK+RANGE+BOTTOM
  T1MR=CYCR1+CZET
  TZMR=CYCR2+CZET
  IF(KONFIG.NE.1) GO TO 105
  TZTR=XLNM(1)+XLNM(2)+PED+XLNM(3)+PED**3
  T1TR=0.
  TZTR=0.
  GO TO 102
  TAIL ROTOR CONTROLS FOR EITHER TANDEM OR SIDE-BY-SIDE
  105 T1TR=T1MR+XLNM(1)
  TZTR=T2MR+XLNM(2)
  TZTR=T2MR+XLNM(3)
  IF(KONFIG.EQ.3) GO TO 104
  TANDEM CONTROLS
  TZTR=TZTR+XLNM(4)+T1MR
  TZMR=TZMR+XLNM(5)+T1MR
  TZTR=TZTR+XLNM(6)+PED
  TZMR=T2MR+XLNM(7)+PED
  GO TO 102
  SIDE-BY-SIDE CONTROLS
  EXAMPLE- SZET9=XLNM(9)+SIN(IF(ZETA))
  104 TZTR=TZTR+CYCR2+CZET4+PED+SZET5
  TZMR=TZMR+CYCR2+CZET6+PED+SZET7
  T1TR=T1TR+CYCR2+SZET8+PED+CZET9
  T1MR=T1MR+CYCR2+SZET10+PED+CZET11
  CHECK CONTROL LOCKS
  102 IF(CLOCK.EQ.0.) GO TO 99
  TZM=TZMS
  GO TO 98
  99 TZM=TZMR
  98 IF(FLOCK.EQ.0.) GO TO 97
  
```

C
 C
 C
 C
 C

272

C

C

C

C

99

98

SWAS0550
SWAS0560
SWAS0570
SWAS0580
SWAS0590
SWAS0600
SWAS0610
SWAS0620
SWAS0630
SWAS0640
SWAS0650
SWAS0660
SWAS0670
SWAS0680
SWAS0690
SWAS0700
SWAS0710
SWAS0720
SWAS0730
SWAS0740
SWAS0750

T1M=T1MS
T1T=T1TS
GO TO 100
97 T1M=T1MR
T1T=T1TR
100 IF(XLOCK.NE.0.) GO TO 101
T2M=T2MR
T2T=T2TR
GO TO 107
101 IF(XLOCK.LT.1.5) GO TO 96
T2M=T2MS+CYCRI*CZET12
T2T=T2TS+CYCRI*CZET13
GO TO 107
96 T2M=T2MS
T2T=T2TS
107 IF(TCLOCK.EQ.0.) GO TO 95
T2T=T2TR
RETURN
95 T2T=T2TR
RETURN
END

```

SUBROUTINE TABINT (CL,CD,X,Z,SG)
      X = XMAC
      Z = ALD

COMMON /TAB/ CURVEL(209),CURVED(857),K(11),L(17)
DIMENSION CLO(2)
NX=9
NZ=20
N=10.*X+1.
IF(N.GT.11) N=11
KM=K(N)
DO 30 I=KM,NX
IF(X.GE.CURVEL(I)) GO TO 30
KX=I
IF(I.EQ.1) KX=2
GO TO 32
30 CONTINUE
KX=NX
3? XL=CURVEL(KX-1)
XM=(X-XL)/(CURVEL(KX)-XL)
XMI=1.-XM
M=NZ+NX
N=Z+1.
IF(N.GT.17) N=17
KA=L(N)
J=NX+KA
DO 70 I=J,M
IF(Z.GE.CURVEL(I)) GO TO 70
KZ=I
IF(I.EQ.(NX+1)) KZ=NX+2
GO TO 72
70 CONTINUE
KZ=M
7? ZL=CURVEL(KZ-1)
J=(KZ-NX-2)*NX+KX+NZ
DO 75 I=1,2
J=J+NX
CLO(I)=CURVEL(J-1)+XMI*CURVEL(J)*XM
75 CONTINUE
CL=CLO(1)+(Z-ZL)/(CURVEL(KZ)-ZL)*(CLO(2)-CLO(1))
NX=12
N=65
Z=Z*SG
DO 40 I=KM,NX
IF(X.GE.CURVED(I)) GO TO 40
KX=I
IF(I.EQ.1) KX=2
GO TO 42
40 CONTINUE
KX=NX
4? XL=CURVED(KX-1)
XM=(X-XL)/(CURVED(KX)-XL)
XMI=1.-XM

```

C
C
C

TAB10010
TAB10020
TAB10030
TAB10040
TAB10050
TAB10060
TAB10070
TAB10080
TAB10090
TAB10100
TAB10110
TAB10120
TAB10130
TAB10140
TAB10150
TAB10160
TAB10170
TAB10180
TAB10190
TAB10200
TAB10210
TAB10220
TAB10230
TAB10240
TAB10250
TAB10260
TAB10270
TAB10280
TAB10290
TAB10300
TAB10310
TAB10320
TAB10330
TAB10340
TAB10350
TAB10360
TAB10370
TAB10380
TAB10390
TAB10400
TAB10410
TAB10420
TAB10430
TAB10440
TAB10450
TAB10460
TAB10470
TAB10480
TAB10490
TAB10500
TAB10510
TAB10520
TAB10530
TAB10540

TAB10550
TAB10560
TAB10570
TAB10580
TAB10590
TAB10600
TAB10610
TAB10620
TAB10630
TAB10640
TAB10650
TAB10660
TAB10670
TAB10680
TAB10690
TAB10700
TAB10710
TAB10720
TAB10730
TAB10740
TAB10750

```
M=NZ+NX
KA=33.+Z
IF(KA-LT.17) NA=1
IF(KA-GT.49) KA=49
J=NX+KA
DO 60 I=J,M
IF(Z.GE.CURVED(I)) GO TO 60
KZ=I
IF(I.EQ.(NX+1)) KZ=NX+2
GO TO 62
60 CONTINUE
KZ=M
62 ZL=CURVED(KZ-1)
J=(KZ-NX-2)*NX+XX+NZ
DO 65 I=1,2
J=J+NX
CLO(I)=CURVED(J-1)*XM1+CURVED(J)*XM
65 CONTINUE
CD=CLO(1)+(Z-ZL)/(CURVED(KZ)-ZL)*(CLO(2)-CLO(1))
RETURN
END
```

SUBROUTINE TILTI (KL)

```

COMMON /STAMAN/ HL(2), XX, YY, AY1, GOV, KPD, OPC, 000,
RIY, APBG, ARBG, ASEP, AYBG, BWTG,
RC, BMTK, BMTM, CGBL, OPIX, OPIZ,
FHPT(2), R550, ALERT, AYDMX, DELT2,
DPIXZ, DTBWT, DMLCG, HDELT, HGUST,
HLTR1, HLTR2, ITORS, KTCTR, OMEGH,
PCOEL, QMRSA, RMAS, TRALT, TWOP1, VGST,
I STOP, XAGUN, XAPYL, XARSP(2), YAGUN,
YARSP(2), YGUST, ZAGUN, ZAPYL, ZARSP(2),
OELT2R, OSTAGG, EIMAST, GPRELD, HLPYLO,
IBRAKE, OMEGH0, QBRAKE, BETAZS(2),
PCGDED, PCGMAX, PCRATE, POIDTR, RDELT1,
RDELT2, RITORS, TRIND2
COMMON /MANAL/
Q, AP, PED, QMG, TZM, TIM, T2M,
TZT, T1T, T2T, ALEL, CZET, PSOD,
SZET, TAXL, TAXR, XAWG, XLNK(16), ZAWG,
ALCYP, ALFIN, ALLWG, ALRNG, CDELE, CDFIN,
CDLWG, CDRWG, CLELE, CLFIN, CLLWG, CLRWG, CMING,
CYCR1, CYCR2, CZET4, CZET6, CZET9, RANGE,
SZET5, SZET7, SZET8, WGCOL, XAELE, XAFIN,
XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,
YAELE, YAFUS, YALWG, YARWG, YALJET, YARJET,
ZAJET, ALECR1, ALGPO, BOTTOM, CZET11,
CZET12, CZET13, ETZETA, HALFPI, SZET10,
XAPYLD, YGUSTM, ZAPYLD, ZFLWG1, ZFRWG1
, TZMS, T1MS, T2MS, T2TS, T1TS, T2TS,
CLOCK, FLOCK, XLOCK, TCLOCK
DIMENSION XAR(2), YAR(2), ZAR(2), COLL(6), DPSI(12,2), NPSI(2),
BETAZ(2), PSIREF(2)
KONFIG=KL
DSTCGT=0.
DSTCGH=0.
DBLCG=0.
DSTACG=0.
DMLCG=0.
RETURN
ENTRY TILT (XAR, ZAR, CGVL, COLL, ZETA, CGSTA)
SZET=SIM(ZETA)
CZET=COS(ZETA)
CZETM1=1.-CZET
XA=ZAPYL*SZET+XAPYL*SZETM1-DSTACG
ZA=ZAPYL*SZETM1-XAPYL*SZET-DMLCG
DSTACG=XA+DSTACG
DMLCG=ZA+DMLCG
ZAFUS=ZAFUS+ZA
ZARSP(1)=ZARSP(1)+ZA
ZARSP(2)=ZARSP(2)+ZA
ZAR(1)=ZARSP(1)-HL(1)*CZET
ZAGUN=ZAGUN+ZA
ZAFIN=ZAFIN+ZA
ZAELE=ZAELE+ZA
ZAWG=ZAWG+ZA
ZAJET=ZAJET+ZA

```

TILT0D10
TILT0D20
TILT0030
TILT0040
TILT0050
TILT0D60
TILT0070
TILT0080
TILT0D90
TILT0100
TILT0110
TILT0120
TILT0130
TILT0140
TILT0150
TILT0160
TILT0170
TILT0180
TILT0190
TILT0200
TILT0210
TILT0220
TILT0230
TILT0240
TILT0250
TILT0260
TILT0270
TILT0280
TILT0290
TILT0300
TILT0310
TILT0320
TILT0330
TILT0340
TILT0350
TILT0360
TILT0370
TILT0380
TILT0390
TILT0400
TILT0410
TILT0420
TILT0430
TILT0440
TILT0450
TILT0460
TILT0470
TILT0480
TILT0490
TILT0500
TILT0510
TILT0520
TILT0530
TILT0540

```

ZAPYLD=ZARSP(1)-HLPYLD*CZET
CGWL=CGML+ZA*12.
RANGE=(COLL(6)*ZETA*COLL(5))*POIDTR
BOTTOM=COLL(2)+ZETA*(COLL(3)+ZETA*COLL(4))
CZET12=XLNK(12)*CZET
CZET13=XLNK(13)*CZET
EZETA=EIMAST*ZETA
IF(KONFIG.NE.3) GO TO 100
CX26=COS(XLXNK(14)*ZETA)
SPED2=SIN(XLXNK(15)*ZETA+XLXNK(16))
CZET4=XLNK(4)*CX26
SZET5=XLNK(5)*SPED2
CZET6=XLNK(6)*CX26
SZET7=XLNK(7)*SPED2
SZET8=XLNK(8)*SZET
CZET9=XLNK(9)*CZET
SZET10=XLNK(10)*SZET
CZET11=XLNK(11)*CZET
GO TO 100
ENTRY HSAF (XAR,YAR,DPSI,NPSI,CGSTA,PSIREF)
NPSI1 = NPSI(1)
SUMCOS = 0.
SUMSIN = 0.
DO 10 I=1,NPSI1
ARG = PSIREF(1) + DPSI(I,1)
SUMCOS = SUMCOS + COS(ARG)
SUMSIN = SUMSIN + SIN(ARG)
10 CONTINUE
XA=RC*SUMCOS-DSTCGH
YA=-RC*SUMSIN-DRLCG
NSTCGH = XA + DSTCGH
DBLCG = YA + DBLCG
YAFUS = YAFUS + YA
YARSP(1) = YARSP(1) + YA
YARSP(2) = YARSP(2) + YA
YAR(1) = YARSP(1)
YAR(2) = YARSP(2)
XAR(2)=YAR(2)+XA
YAGUN = YAGUN + YA
YAFIN = YAFIN + YA
YAFLE = YAELE + YA
YALWG = YALWG + YA
YARWG = YARWG + YA
YALJET = YALJET + YA
YARJET = YARJET + YA
CGBL=CGBL+YA*12.
GO TO 100
ENTRY TFFA (XAR,BETAZ,CGSTA)
XA=-RC*SZET*SIN(BETAZ(1))-DSTCGT
DSTCGT = XA + DSTCGT
100 CONTINUE
XAFUS=XAFUS+XA
XARSP(1)=XARSP(1)+XA
XARSP(2)=XARSP(2)+XA

```

```

TILT0550
TILT0560
TILT0570
TILT0580
TILT0590
TILT0600
TILT0610
TILT0620
TILT0630
TILT0640
TILT0650
TILT0660
TILT0670
TILT0680
TILT0690
TILT0700
TILT0710
TILT0720
TILT0730
TILT0740
TILT0750
TILT0760
TILT0770
TILT0780
TILT0790
TILT0800
TILT0810
TILT0820
TILT0830
TILT0840
TILT0850
TILT0860
TILT0870
TILT0880
TILT0890
TILT0900
TILT0910
TILT0920
TILT0930
TILT0940
TILT0950
TILT0960
TILT0970
TILT0980
TILT0990
TILT1000
TILT1010
TILT1020
TILT1030
TILT1040
TILT1050
TILT1060
TILT1070
TILT1080

```

TILTI090
TILTI100
TILTI110
TILTI120
TILTI130
TILTI140
TILTI150
TILTI160
TILTI170
TILTI180

XAR(1)=XARSP(1)+HL(1)*SZET
XAGUN=XAGUN+XA
XAFIN=XAFIN+XA
XAELE=XAELE+XA
XAMG=XAMG+XA
XAJET=XAJET+XA
XAPYLD=XARSP(1)+HLPYLD+SZET
CGSTA=CGSTA+XA*12.
RETURN
END

```

SUBROUTINE TINIT (TAIR)
COMMON /STRIMA/ AY,VH,AGM,DT1(2),DT2(2),IXZ,
1 QMR,XXD,YYD,ZZD,ALGF,APFP,AYFP,
2 CGML,COLL(6),CYCF(3),CYCL(3),
3 DIST,KCIT(20),PEDAC3,QMAX,
4 QMRS,TIME,THAX,XCIT(20,6),ALGEZ,
5 ALGE1,ALGE2,CGSTA,CPMIC,DIXIZ,
6 DIYIX,DIZIY,DTZMT,DTZM1,DTZT1,FTKTS,
7 HUBKM(2,2),HUBKI(2,2),
8 KREAD,PIU30,TSTAB(14),ZMAX2,ZMAX3,
9 ASECOL,CYPMIC,GEARAT,PSD550,
10 PSISTP,OXBRAK,RUDIND,ZDELT1,ZDELT2
COMMON /STAMAN/ HL(2),XX,YY,AY1,GOV,KPD,QPC,QOO,
1 RIY,APBG,ARBG,ASEP,AYBG,BWTC,
2 RC,BWTK,BWTH,CGBL,DPIX,DPIZ,
3 FHPT(2),R55D,ALERT,AYDMX,DELT2,
4 DPIXZ,DTBWT,DWLCG,MDELT,HGUST,
5 HLTR1,HLTR2,ITORS,KTCR,OMEGM,
6 PCDEL,QMRS,RMASS,TRALT,TMOPI,VGUST,
7 ISTOP,XAGUN,XAPYL,XARSP(2),YAGUN,
8 YARSP(2),YGUST,ZAGUN,ZAPYL,ZARSP(2),
9 DELT2R,DSTACG,EIMAST,GPRELD,HLPLYD,
A IBRAKE,OMEGMD,QBRAKE,BETAZS(2),
B PCGDED,PCGMAX,PCRATE,POIDTR,RDELT1,
C RDELT2,RITORS,TRINDZ
DIMENSION TAIR(14)
ARBG=0.
ASECL=0.
AYDMX=0.
DTZMT=0.
DTZM1=0.
DTZT1=0.
DT1(1)=0.
DT1(2)=0.
DT2(1)=0.
DT2(2)=0.
DTBMT=D.
HGUST=0.
ISTOP=0
IBRAKE=1
KPD=0
VGUST=C.
ALERT=0.
ASEP=0.
KTCR = 0
OMEGMD=D.
PCDEL=0.
PCRATE=0.
QOO=2.
RITORS=0.
FTKTS=,5925
R55D=.101R101RE-02
YGUST=0.
QMRS=QMAX

```

```

TINI0010
TINI0020
TINI0030
TINI0040
TINI0050
TINI0060
TINI0070
TINI0080
TINI0090
TINI0100
TINI0110
TINI0120
TINI0130
TINI0140
TINI0150
TINI0160
TINI0170
TINI0180
TINI0190
TINI0200
TINI0210
TINI0220
TINI0230
TINI0240
TINI0250
TINI0260
TINI0270
TINI0280
TINI0290
TINI0300
TINI0310
TINI0320
TINI0330
TINI0340
TINI0350
TINI0360
TINI0370
TINI0380
TINI0390
TINI0400
TINI0410
TINI0420
TINI0430
TINI0440
TINI0450
TINI0460
TINI0470
TINI0480
TINI0490
TINI0500
TINI0510
TINI0520
TINI0530
TINI0540

```

TINI0550
TINI0560
TINI0570
TINI0580
TINI0590
TINI0600
TINI0610
TINI0620
TINI0630
TINI0640
TINI0650
TINI0660
TINI0670

```
HLTR2=HL(2)*TRIND2
VH=SQRT(XD**2+YYD**2)
AYFP=0.
APEP=0.
IF(VH.NE.0.) AYFP=ATAN2(YYD,XXD)
IF(VH.NE.0..OR.ZZD.NE.0.) APFP=ATAN2(-ZZD,VH)
TRALT=100*TRIND2
DO 45 I=2,14
  IF(TSTAB(I).EQ.0.) TSTAB(I)=9999.
  IF(TAIR(I).EQ.0.) TAIR(I)=9999.
45 CONTINUE
RETURN
END
```

SUBROUTINE TRIM		
COMMON /FORCE/	XF, XFRWG, XFLWG, XFELE, XFFUS, XFRJET,	TRIM0010
1	XFLJET, XPMR, XFTR, XFGUN, XFFIN, XFM,	TRIM0020
2	YF, YFFUS, YFRJET, YFLJET, YFMR, YFTR,	TRIM0030
3	YFGUN, YFFIN, YFW,	TRIM0040
4	ZF, ZFRWG, ZFLWG, ZFELE, ZFFUS, ZFRJET,	TRIM0050
5	ZFLJET, ZPMR, ZFTR, ZFGUN, ZFM,	TRIM0060
6	QL, LRMG, LLMG, LELE, LFUS, LRJET, LLJET,	TRIM0070
7	LMR, LTR, LGUN, LFIN, LQMR, LQTR,	TRIM0080
8	QM, MRWG, MLWG, MELF, MFUS, MRJET, MLJET,	TRIM0090
9	MMR, MTR, MGUN, MFIN, MQMR, MQTR,	TRIM0100
A	QN, NRWG, NLWG, NELE, NFUS, NRJET, NLJET,	TRIM0110
B	NMR, NTR, NGUN, NFIN, NQMR, NQTR	TRIM0120
COMMON /STRIAB/	D(21), DT(21), E(79), F(10), X(10),	TRIM0130
1	DL, DM, DN, DX, DY, DZ, IX, IY, IZ, PD(10, 11),	TRIM0140
2	OTR, EPD, ERR(10), KMI, RHO,	TRIM0150
3	R12, SPD(6, 6, 3), XBW(21), XEL(14),	TRIM0160
4	XER(7), XFC(28), XFN(7), XFS(35),	TRIM0170
5	XGN(7), XIT(21), XMR(49), XTR(49),	TRIM0180
6	XMG(21), YMR(21), YTR(21), YMG(21),	TRIM0190
7	VEL(21), YFN(21), BLCG, DAMP, DEPD(10),	TRIM0200
8	EPDS, EPDX(10), MASS, QSV1, TMR5, TTRS,	TRIM0210
9	WLCG, XCON(63), XJET(14), XMIN, AYEF, P,	TRIM0220
A	BETAES(2), CNPCD, DMADO, DYBDR, GUESS,	TRIM0230
B	NPASS, PDPHI(10, 11), STACG, TZERD,	TRIM0240
C	XMAST, DHADAQ, OQDCOL, DTRRSO, DY80BR,	TRIM0250
D	ENGRPH, MXPASS, PSD30P, TRIND1, XLIMIT	TRIM0260
COMMON /STRIMA/	AY, VH, AGM, DT1(2), DT2(2), IXZ,	TRIM0270
1	QMR, XXD, YYD, ZZD, ALGF, APFP, AYFP,	TRIM0280
2	CGML, COLL(6), CYCF(3), CYCL(3),	TRIM0290
3	DIST, KCIT(20), PEOA(3), OMAX,	TRIM0300
4	OMRS, TIME, TMAX, XCIT(20, 6), ALGEZ,	TRIM0310
5	ALGE1, ALGE2, CGSTA, CPMIC, OIXIZ,	TRIM0320
6	DIYIX, DIZIY, DTZMT, DTZML, OTZT1, FTKTS,	TRIM0330
*	HUBKM(2, 2), HUBKI(2, 2),	TRIM0340
7	KREAD, PIU30, TSTAB(14), ZMAX2, ZMAX3,	TRIM0350
8	ASECOL, CYPMIC, GEARAT, PS0550,	TRIM0360
9	PS1STP, QXBRK, RUDIND, ZDELT1, ZDELT2	TRIM0370
COMMON /MANAL/	Q, AP, PED, QMG, TZM, TIM, T2M,	TRIM0380
1	TZT, T1T, T2T, ALEL, CZET, PSDD,	TRIM0390
2	SZET, TAXL, TAXR, XAWG, XLNK(16), ZANG,	TRIM0400
3	ALCYP, ALFIN, ALLWG, ALRMG, CDELE, CDFIN,	TRIM0410
4	COLMG, CORMG, CLELE, CLFIN, CLLWG, CLRWG, CWMG,	TRIM0420
5	CYCR1, CYCR2, CZET4, CZET6, CZET9, RANGE,	TRIM0430
6	SZET5, SZET7, SZETA, WGCOL, XAELE, XAFIN,	TRIM0440
7	XAFUS, XAJET, YAFIN, ZAELE, ZAFIN, ZAFUS,	TRIM0450
*	YAELE, YAFUS, YALWG, YARMG, YALJET, YARJET,	TRIM0460
8	ZAJET, ALECR1, ALGFPD, BDTTOM, CZET11,	TRIM0470
9	CZET12, CZET13, EIZETA, HALFPI, SZET10,	TRIM0480
A	XAPYLD, YGUSTW, ZAPYLD, ZFI, ZSI, ZFRMG1	TRIM0490
B	TZMS, T1MS, T2MS, TZTS, T1TS, T2TS,	TRIM0500
C	CLOCK, FLOCK, XLOCK, TLOCK	TRIM0510
*	ZZ, VXS(2), VYS(2), VZS(2), BETA(12, 2),	TRIM0520
	T, PCC(2), CDSE(7, 7, 2), BETAN(2), BETAX(2), BETAZ(2),	TRIM0530
		TRIM0540

```

*
1 AIB(2),APDD,ARDD,AYDD,AIR(2),
2 DPSI(12,2),OTRR,MPSI(2),ZZTR,
3 BETAD(12,2),BMPSI(2),
4 CDND2,GMAXV,RATEL,RATE2,STOP2,
5 THROT(2),TRIND,XGUST,BETAZD(2),GMAXV1,
6 GMAXV2,GMAXV3,GUSTYP,HMPSIR(2),
7 HUBKS,HMKRS,HUBTPS,HUBTRS,
8 KONFIG,LANGTH1,PILGH1,PSIREF(2),
9 START2,XMDMLI(12,2),
A RM,RTR,ORM,ORTR,TIMT,TITT,
B T2MT,T2TT,T2MT,T2TT,XMAL,XMALT,
C XM01,XM01T,AIBPH,AIBPT,AIBRM,AIBRT,
D APTD,APTD,ARTD,ARTD,PSD,PSDT,
E XSTAHM,XSTAHM,YSTAHM,YSTAHM,
F HUBKP,HUBKTP,HUBKR,HUBKTR
COMMON /MANARO/ I,V,IND,MNAG,APBMT,ARBMT,AYBMT,BETAD(2),TOELT,
1 BETAE(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
2 VGUSTW,VGUSTF,GFWD,GLAT,CVERT,
3 VXB,VZB,APD,VYB,ARD,AYD,
4 COLSTK,CYSTKI,CYSTK2,PEDAL,AYE,
5 APE,ARE,AIM,0IM,AITR,0ITR,
6 XAR(2),YAR(2),ZAR(2),
7 VMR,VITR,ZETA,ZETATR,HMR,HTR,
8 TMR,TTR,OMX,OTR,YMRF,YTRF
COMMON /STANRO/ J,M,ITM,VHS(2),LINK,OELE,VROT(2),
1 VSND,YEIN(2),ZEEL(2),AIBAL(2),
2 B1BAL(2),CDND1,SWING,PILGH2,PMGEL1,
3 0M,0TR,PHOMM,PHOMT,RMOMM,RMOMT
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
1 NPART,NVARA,NVAR0,NVARC,NSCALE
2 NVAR5,NPRINT,NTIME
COMMON /FORY/ Y(4,150)
1 DIMENSION VAR(11),HEAD2(6,7),PSID(2),APDR(2),ARDR(2),
2 EQUIVALENCE (VAR(1),COLSTK),(PSID(1),PSD),(APDR(1),APTD),
3 (ARDR(1),ARTD)
1 DATA HEAD2/'*****COLLECTIVE STICK *****PEDAL POSITION EXCEEDS STOPS (TRIMD92D
2 *LAT CYCLIC STICK *****'
LOGICAL AYEFP
REAL MASS,IXZ
AYEFP=.TRUE.
IF(ABS(AYE-AYEFP).LE..01.AND.Y(1,85).EQ.0.) AYEFP=.FALSE.
LPASS=5
IF(IXIT(3).EQ.0.) LPASS=1
EPDX(1)=1./RANGE
EPDX(2)=1./CYCF(3)
EPDX(3)=1./CYCL(3)
EPDX(4)=1./PEDA(3)
DX=0.
DY=0.
DZ=0.
DL=0.

```

```

TRIM0550
TRIM0560
TRIM0570
TRIM0580
TRIM0590
TRIM0600
TRIM0610
TRIM0620
TRIM0630
TRIM0640
TRIM0650
TRIM0660
TRIM0670
TRIM0680
TRIM0690
TRIM0700
TRIM0710
TRIM0720
TRIM0730
TRIM0740
TRIM0750
TRIM0760
TRIM0770
TRIM0780
TRIM0790
TRIM0800
TRIM0810
TRIM0820
TRIM0830
TRIM0840
TRIM0850
TRIM0860
TRIM0870
TRIM0880
TRIM0890
TRIM0900
TRIM0910
TRIM0920
TRIM0930
TRIM0940
TRIM0950
TRIM0960
TRIM0970
TRIM0980
TRIM0990
TRIM1000
TRIM1010
TRIM1020
TRIM1030
TRIM1040
TRIM1050
TRIM1060
TRIM1070
TRIM1080

```

```

DM=0.
DM=0.
BETAES(1)=BETA(1)
BETAES(2)=BETA(2)
TMR5=TMR
TTR5=TTR
DO 4 I=5,10
  EPDX(I)=1.
4 CONTINUE
CALL DAMPER
CALL PDZ1 (KONFIG)
DO 6 K=1,10
  X(K)=0.
DO 6 L=1,11
  PD(K,L)=0.
  POPH(K,L)=0.
6 CONTINUE
LINK=2
CALL ITRIM(LPASS)
DO 175 I=1,4
  IF(IVAR(I).GE.0.0.AND.VAR(I).LE.100.) GO TO 175
  WRITE (6,176) ((HEAD2(J,I),J=1,6), (HEAD2(J,5),J=1,6),VAR(I),
    1 EXIT=1.
175 CONTINUE
DL=0.
DM=0.
OM=0.
OX=0.
OY=0.
OZ=0.
IF(IMPART.NE.2.OR.EXIT.NE.0.) RETURN
IND=0
Y(1, 1)=VXB
Y(1, 2)=VYB
Y(1, 3)=VZB
Y(1,4)=AYD
Y(1,5)=APD
Y(1,6)=ARD
Y(1,10)=AVE
Y(1,11)=APE
Y(1,12)=ARE
NPSI(1)=BM
NPSI(2)=BTR
CALL MOPSI1 (MPSI,MMPSIR,BNPSI,DPSI)
TDLT = ZDELTI
TIME=TZERD-.95*TDLT
DIST= TZERO*V
AY=0.
IF(VXB.NE.0.0.OR .VYR.NE.0.) AY=ATAN2(-VYB,VXB)
OMR=OMX+OTR*GEARAT
OMRS=OMR
CALL IV... (EXIT,LINK,TAXL,PILGH2,A1M,B1M,A1TR,B1TR)
ZFEL(1)=ZFELE

```

```

TRIM1090
TRIM1100
TRIM1110
TRIM1120
TRIM1130
TRIM1140
TRIM1150
TRIM1160
TRIM1170
TRIM1180
TRIM1190
TRIM1200
TRIM1210
TRIM1220
TRIM1230
TRIM1240
TRIM1250
TRIM1260
TRIM1270
TRIM1280
TRIM1290
TRIM1300
TRIM1310
TRIM1320
TRIM1330
TRIM1340
TRIM1350
TRIM1360
TRIM1370
TRIM1380
TRIM1390
TRIM1400
TRIM1410
TRIM1420
TRIM1430
TRIM1440
TRIM1450
TRIM1460
TRIM1470
TRIM1480
TRIM1490
TRIM1500
TRIM1510
TRIM1520
TRIM1530
TRIM1540
TRIM1550
TRIM1560
TRIM1570
TRIM1580
TRIM1590
TRIM1600
TRIM1610
TRIM1620

```

YFIN(1)=YFFIN
REWIND 3
ITM=0
RETURN
176 FORMAT (1H0,12A4,F7.1,12A4)
END

TRIM1630
TRIM1640
TRIM1650
TRIM1660
TRIM1670
TRIM1680

```

SUBROUTINE TURN (XFC,V,ARE)
COMMON /FORV/ Y(4,150)
DIMENSION XFC(28)
DATA G/32.17/,DTR/.1745329E-01/,
Y(2,86)=1.
IF(XFC(21).NE.0.) GO TO 5
DO 100 I=12,14
IF(XFC(I).EQ.0.) GO TO 100
J=I-11
GO TO (1,2,3),J
100 CONTINUE
RETURN
1 CONTINUE
GLEVEL=XFC(12)
IF(GLEVEL.LE.1.) GO TO 5
ARE=ARCOS(1./GLEVEL)
ARED=ARE/DTR
TRAD=V**2/(G*TAN(ARE))
GO TO 4
2 CONTINUE
ARED=XFC(13)
ARE=AKED*DTR
GLEVEL=1./COS(ARE)
TRAD=V**2/(G*TAN(ARE))
GO TO 4
3 CONTINUE
TRAD=XFC(14)
ARE=ATAN2(V**2,G*TRAD)
ARED=ARE/DTR
GLEVEL=1./COS(ARE)
4 CONTINUE
Y(1,85)=V/TRAD
PSID=Y(1,85)/DTR
TURNT=360./ABS(PSID)
TRAD=ABS(TRAD)
WRITE (6,170) GLEVEL,ARED,TRAD,PSID,TURNT
RETURN
5 CONTINUE
Y(2,86)=XFC(12)
IF(XFC(12)-1.) 6,7,8
6 CONTINUE
WRITE (6,180) XFC(12)
7 CONTINUE
RETURN
8 WRITE (6,190) XFC(12)
RETURN
170 FORMAT(' ',G-LEVEL = ,G12.5,10X,' BANK ANGLE = ,G12.5//,
1 ' TURN RADIUS = ,G12.5,10X,' YAW RATE = ,G12.5//,
2 ' TIME USED TO COMPLETE 360 DEGREE TURN = ,G12.5)
180 FORMAT(' ',PUSH-OVER WITH G-LEVEL = ,G12.5)
190 FORMAT(' ',PULL-UP WITH G-LEVEL = ,G12.5)
END
TURN0010
TURN0020
TURN0030
TURN0040
TURN0050
TURN0060
TURN0070
TURN0080
TURN0090
TURN0100
TURN0110
TURN0120
TURN0130
TURN0140
TURN0150
TURN0160
TURN0170
TURN0180
TURN0190
TURN0200
TURN0210
TURN0220
TURN0230
TURN0240
TURN0250
TURN0260
TURN0270
TURN0280
TURN0290
TURN0300
TURN0310
TURN0320
TURN0330
TURN0340
TURN0350
TURN0360
TURN0370
TURN0380
TURN0390
TURN0400
TURN0410
TURN0420
TURN0430
TURN0440
TURN0450
TURN0460
TURN0470
TURN0480
TURN0490
TURN0500
TURN0510
TURN0520

```

SUBROUTINE VARI		
COMMON /FIRCF/	XF, XFRWG, XFLWG, XFFLE, XFFUS, XFRJET,	VARI0010
1	XFLJET, XFR, XFR, XFFUN, XFFIN, XFFW,	VARI0020
2	YF, YFFUS, YFRJET, YFLJET, YFMR, YFTR,	VARI0030
3	YFGUN, YFFIN, YFV,	VARI0040
4	ZF, ZFRWG, ZFLWG, ZFFLE, ZFFUS, ZFRJET,	VARI0050
5	ZFLJET, ZFMR, ZFTR, ZFGUN, ZF4,	VARI0060
6	OL, LRWG, LLWG, LELF, LFUS, LRJET, LIJET,	VARI0070
7	LMR, LTR, LGUN, LFIN, LMR, LOTR,	VARI0080
8	OM, MRWG, MLWG, MELF, MFUS, MRJET, MLJET,	VARI0090
9	MTR, MTR, MGUN, MFIN, MOMR, MOTR,	VARI0100
A	ON, NRWG, NLWG, NELE, NFUS, NRJET, NLJET,	VARI0110
B	NMR, NTR, NGUN, NFIN, NOMR, NOTR	VARI0120
COMMON /STRIAB/	D(21), OT(21), E(79), F(10), X(10),	VARI0130
1	DL, DM, ON, DX, OY, OZ, IX, IY, IZ, PD(10, 11),	VARI0140
2	DTR, EPD, ERR(10), KML, RHO,	VARI0150
3	R12, SPO(6, 6, 3), XFM(21), XEL(14),	VARI0160
4	XER(7), XFC(28), XFM(7), XFS(35),	VARI0170
5	XGN(7), XIT(21), XMR(49), XTR(49),	VARI0180
6	XMG(21), YMR(21), YTR(21), YMG(21),	VARI0190
7	YEL(21), YFN(21), BLCG, OAMP, DEPO(10),	VARI0200
8	EPOS, EPOX(10), MASS, OSVI, TMRS, TTRS,	VARI0210
9	MLCG, XCON(63), XJET(14), XMIN, AYEFP,	VARI0220
A	BETAES(2), CNPCO, OHADO, DYDBR, GUESS,	VARI0230
B	NPASS, POPHI(10, 11), STAG, T7ERO,	VARI0240
C	XMAST, DHAOAO, DQCOL, DTRRSQ, DYBDBR,	VARI0250
D	ENGRPM, HXPASS, PSD30P, TAINOI, XLIMIT	VARI0260
COMMON /STRIMA/	AY, VH, AGM, OTI(2), OT2(2), IXZ,	VARI0270
1	QMR, XXD, YYO, ZZO, ALGF, APFP, AYFP,	VARI0280
2	CGML, COLL(6), CYCF(3), CYCL(3),	VARI0290
3	OIST, KCIT(20), PEDA(3), OMAX,	VARI0300
4	QMR, TIYE, TMAX, XCIT(20, 6), ALGEZ,	VARI0310
5	ALGE1, ALGE2, CGSTA, CPMIC, OIXZ,	VARI0320
6	DIYX, OIZIY, OTZMT, DTZMI, OTZTI, FTKTS,	VARI0330
*	HUBKM(2, 2), HURKI(2, 2),	VARI0340
7	KREAD, PIU30, TSTAB(14), ZMAX2, ZMAX3,	VARI0350
8	ASECOL, CYPWIC, GEARAT, PSD550,	VARI0360
9	PSISTP, OXBRK, RUOIND, ZOELT1, ZDELT2	VARI0370
COMMON /STAMAN/	HL(2), XX, YY, AV1, GOV, KPD, QPC, QOQ,	VARI0380
1	RIY, APBG, ARBG, ASEP, AYBG, BWTG,	VARI0390
2	RC, BMTK, BWTM, CGBL, DPIX, OPIZ,	VARI0400
3	FHPT(2), R550, ALERT, AYDMX, DELT2,	VARI0410
4	DPIX, DTBWT, DMLCG, HDELT, HGUST,	VARI0420
5	HLTRI, HLTR2, ITOPS, KTCR, DMEGM,	VARI0430
6	PCOEL, OMRSA, RMAS, TRALT, TMOPI, VGUST,	VARI0440
7	ISTOP, XAGUN, XAPYL, XARSP(2), YAGUN,	VARI0450
8	YARSP(2), YGUST, ZAGUN, ZAPYL, ZARSP(2),	VARI0460
9	DEL2R, OSTAG, EIMAST, GPRED, HLPYLD,	VARI0470
A	IBRAKE, OMEGMD, OBRAKE, BETAZS(2),	VARI0480
B	PCGDEO, PCGMAX, PCRATE, POIOTR, ROELT1,	VARI0490
C	RDEL2, RITORS, TRINOZ	VARI0500
COMMON /MANAL/	Q, AP, PEO, OMG, TZM, TIM, T2M,	VARI0510
1	TZT, TIT, T2T, ALEL, CZET, PSDD,	VARI0520
2	SZET, TAXL, TARR, XAWG, XLNK(16), ZAWG,	VARI0530
		VARI0540

```

3 4 5 6 7 8 9 A B C
ALCYP,ALFIN,ALLWG,ALRMG,CDELE,CDFIN,
COLWG,CDRMG,CLELE,CLFIN,CLLWG,CLRMG,CWING,
CYCR1,CYCR2,CZET4,CZET6,CZET9,RANGE,
SZET5,SZET7,SZET8,MGCOL,XAELE,XAFIN,
XAFUS,XAJET,YAFIN,ZAELE,ZAFIN,ZAFUS,
YAELE,YAFUS,YALWG,YARMG,YALJET,YARJET,
ZAJET,ALECR1,ALGPO,BOTTOM,CZET11,
CZET12,CZET13,EIZETA,HALFPI,SZET10,
XAPYLO,YGUSTM,ZAPYLD,ZFLWGI,ZFRWGI
.TZMS,TIMS,T2MS,TZTS,T1TS,T2TS,
CLOCK,FLOCK,XLOCK,TCLOCK
ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
T,PCC(2),CDSE(7,2),BETAN(2),BETAX(2),BETAZ(2),
AIB(2),APDO,AROD,AYDO,AIR(2),
DPSI(12,2),OTRR,NPSI(2),ZZTR,
BETA0(12,2),BNPSI(2),
COND2,GMAXV,RATEI,RATE2,STOP2,
THROT(2),TRINO,XGUST,BETAZO(2),GMAXV1,
GMAXV2,GMAXV3,GUSTYP,MNPSIR(2),
HUBKPS,HUBKRS,HUBTPS,HUBTRS,
KONFIG,LNGTH1,PILGH1,PSIREF(2),
START2,XMOMLI(12,2),
RM,RTR,ORM,ORTR,TIMT,TITT,
TZMT,TZTT,TZMT,TZTT,XMAI,XMAIT,
XMB1,XMB1T,AIBPM,AIBPT,AIBRM,AIBRT,
APTO,APTO,ARTO,ARTO,PSO,PSDT,
XSTAHM,XSTAHT,YSTAHM,YSTAHT,
HUBKP,HUBKTP,HUBKR,HUBKTR
.AZETA,AZETAT,VZETA,VZETAT
I,V,INO,NMAG,APBT,ARBMT,AYBMT,BETA0(2),TDELT,
BETA(2),HGUSTE,HGUSTF,HGUSTM,VGUSTE,
VGUSTW,VGUSTF,GFMO,GLAT,GVERT,
VXB,VZB,APO,VYB,ARD,AYD,
COLSTK,CYSTKI,CYSTK2,PEDAL,AYE,
APE,ARE,AIM,RIM,AITP,BITR,
XAR(2),YAR(2),ZAP(2),
VIMR,VITR,ZETA,ZETATR,HMR,HTR,
TMR,TTR,OMX,OTR,YMRF,YTRF
COMMON /TDPLNT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
NPART,NVARA,NVARR,NVARC,NSCALE
,NVARS,NPRINT,NTIME
COMMON /FORV/ Y(4,150)
REAL LGUN,NGUN
DIMENSION TAX(2),PSID(2),HUBK(2,2)
DIMENSION COMLOK(4),THEIS(6),THEI(6),XMOI(3),PDM(3,4),DTHEI(3)
EQUIVALENCE (TAX(1),TAXL),(PSID(1),PSO),(HUBK(1,1),HUBKP)
EQUIVALENCE (COMLOK(1),CLOCK),(THEIS(1),TZMS),(THEI(1),TZM)
XDELIM(X1,X2,X3)=AMAX1(X1,AMIN1(X2,X3))
NMEGMD=0.
IF(I.GT.2) GO TO 221
OPC=0.
GRV=0.
QOQ=1.
TCIATS(Y(1,9)-OMEGM).LT..9) QOQ=2

```

```

VARI0550
VARI0560
VARI0570
VARI0580
VARI0590
VARI0600
VARI0610
VARI0620
VARI0630
VARI0640
VARI0650
VARI0660
VARI0670
VARI0680
VARI0690
VARI0700
VARI0710
VARI0720
VARI0730
VARI0740
VARI0750
VARI0760
VARI0770
VARI0780
VARI0790
VARI0800
VARI0810
VARI0820
VARI0830
VARI0840
VARI0850
VARI0860
VARI0870
VARI0880
VARI0890
VARI0900
VARI0910
VARI0920
VARI0930
VARI0940
VARI0950
VARI0960
VARI0970
VARI0980
VARI0990
VARI1000
VARI1010
VARI1020
VARI1030
VARI1040
VARI1050
VARI1060
VARI1070
VARI1080

```

```

221 DO 220 L=I,KREAD
      J=XCIT(L)
      IF(J.EQ.26) GO TO 262
      IF(J.EQ.31) GO TO 295
      IF(J.EQ.6.OR.J.GT.26) GO TO 273
      IF(J.GT.23) GO TO 220
      IF(J.EQ.23) GO TO 219
      IF(J.EQ.13) GOV=-I
      IF(J.LT.9.OR.J.GT.12) GO TO 223
      CALL GUST (J)
      GO TO 220
223 CONTINUE
      IF(J.EQ.18) GO TO 214
      IF(TIME.LT.XCIT(L,I)) GO TO 220
      IF(J.GT.12) GO TO 413
      RATE=XCIT(L,2)
      J.EQ.1 IS FOR MR. COLLECTIVE INPUT
      J.EQ.2 IS FOR MR. F/A CYCLIC INPUT
      J.EQ.3 IS FOR MR. LATERAL CYCLIC INPUT
      IF(TIME.GT.XCIT(L,3)) RATE=0.
      IF(TIME.GE.XCIT(L,4)) RATE=0.
      IF(TIME.GT.XCIT(L,6)) RATE=0.
      DA=RATE*HDELT
      IF(J.EQ.5) GO TO 264
      IF(RATE.EQ.0.) GO TO 220
      GO TO (260,261,262,263,264,265,266,267).J
260 CONTINUE
      COLSTK=XDELIM(0.,100.,COLSTK+DA)
      MGCOL=CPMIC*COLSTK+AGM
      GO TO 220
261 CONTINUE
      CYSTK1=XDELIM(0.,100.,CYSTK1+DA)
      CYCR1=CYSTK1*CYCF(3)+CYCF(2)
      ALECR1=ALGEZ+CYCR1*(ALGE1+ALGE2*CYCR1)
      GO TO 220
262 CONTINUE
      CYSTK2=XDELIM(0.,100.,CYSTK2+DA)
      CYCR2=CYSTK2*CYCL(3)+CYCL(2)
      ALCYP=CYPMIC*CYCR2
      GO TO 220
263 CONTINUE
      PEDAL=XDELIM(0.,100.,PEDAL+DA)
      PED=PEDAL*PEDA(3)+PEDA(2)
      ALGFPD=ALGF+RUDIND*PED
      GO TO 220
264 PCRATE=PCGMX *HDELT**2
      IF(XCIT(L,3).LT.TIME.AND.TIME.LT.XCIT(L,4)) GO TO 220
      IF(XCIT(L,6).LT.TIME) GO TO 220
      OPC=10.
      IF((DA*PSD550).EQ.0.) GO TO 220
      QMRS=XDELIM(0.,QMRS,QMRS+DA/PSD550)
      GO TO 220
273 CONTINUE
      IF(LISTOP.NE.0.AND.I.EQ.4) GO TO 274

```

VARI1090
VARI1100
VARI1110
VARI1120
VARI1130
VARI1140
VARI1150
VARI1160
VARI1170
VARI1180
VARI1190
VA911200
VAR 1210
VA 1220
VARI1230
VARI1240
VARI1250
VARI1260
VARI1270
VARI1280
VARI1290
VARI1300
VARI1310
VARI1320
VARI1330
VARI1340
VARI1350
VARI1360
VARI1370
VARI1380
VARI1390
VARI1400
VARI1410
VARI1420
VARI1430
VARI1440
VARI1450
VARI1460
VARI1470
VARI1480
VARI1490
VARI1500
VARI1510
VARI1520
VARI1530
VARI1540
VARI1550
VARI1560
VARI1570
VARI1580
VARI1590
VARI1600
VARI1610
VARI1620

VARI1630
 VARI1640
 VARI1650
 VARI1660
 VARI1670
 VARI1680
 VARI1690
 VARI1700
 VARI1710
 VARI1720
 VARI1730
 VARI1740
 VARI1750
 VARI1760
 VARI1770
 VARI1780
 VARI1790
 VARI1800
 VARI1810
 VARI1820
 VARI1830
 VARI1840
 VARI1850
 VARI1860
 VARI1870
 VARI1880
 VARI1890
 VARI1900
 VARI1910
 VARI1920
 VARI1930
 VARI1940
 VARI1950
 VARI1960
 VARI1970
 VARI1980
 VARI1990
 VARI2000
 VARI2010
 VARI2020
 VARI2030
 VARI2040
 VARI2050
 VARI2060
 VARI2070
 VARI2080
 VARI2090
 VARI2100
 VARI2110
 VARI2120
 VARI2130
 VARI2140
 VARI2150
 VARI2160

```

IF(PSD.EQ.0.) GO TO 223
IF(J.EQ.29) GO TO 276
GO TO 220
274 CONTINUE
  ISTOP=2
  IF(J.EQ.29) GO TO 275
  XCIT(L,1)=XCIT(L,1)+T
  IF(J.EQ.30) GO TO 279
  XCIT(L,3)=XCIT(L,3)+T
  IF(J.EQ.27) GO TO 220
  XCIT(L,4)=XCIT(L,4)+T
  XCIT(L,6)=XCIT(L,6)+T
  GO TO 220
275 CONTINUE
  IF(XCIT(L,3).NE.0.) XCIT(L,1)=XCIT(L,1)+T
  IF(XCIT(L,4).NE.0.) XCIT(L,2)=XCIT(L,2)+T
276 CONTINUE
  IF(XCIT(L,3).EQ.0.) GO TO 223
  GO TO 220
279 CONTINUE
  XCIT(L,2)=XCIT(L,2)+T
  GO TO 220
265 CONTINUE
  DO 269 N=1,2
  RFTAZD(N)=-RATE
  IF(NPSI(N).EQ.0) GO TO 269
  BETAZ(N)=BETAZ(N)-DA
  BETAN(N)=BETAN(N)
  BETAX(N)=BETAN(N)
259 CONTINUE
  CALL TFFA (XAR,BETAZ,CGSTA)
  GO TO 220
266 OMEGM=OMEGM+DA
  OMEGMD=RATE+OMEGM
  DOO=1.
  GO TO 220
267 ZETATR=ZETATR+DA
265 XAR(2)=XARSP(2)+HL(2)*SIN(ZETATR)
  CZTR=COS(ZETATR)
  VAR(2)=YARSP(2)-HLTR1+CZTR
  AY9MT=ZETATR*TRIND2
  AP8MT=-ZETATR*TRIND
  VZETAT=RATE
  IF(J.EQ.20) AZETAT=AZ
  GO TO 220
413 CONTINUE
  IF(J.EQ.27) GO TO 226
  IF(J.EQ.29) GO TO 283
  IF(J.EQ.30) GO TO 284
  K=J-12
  GO TO (209,210,211,212,213,214,215,216,217,218,219).K
209 IF(TIME-GE.XCIT(L,3)) GO TO 270
  DOO=XCIT(L,2)

```

```

VARI2170
VARI2180
VARI2190
VARI2200
VARI2210
VARI2220
VARI2230
VARI2240
VARI2250
VARI2260
VARI2270
VARI2280
VARI2290
VARI2300
VARI2310
VARI2320
VARI2330
VARI2340
VARI2350
VARI2360
VARI2370
VARI2380
VARI2390
VARI2400
VARI2410
VARI2420
VARI2430
VARI2440
VARI2450
VARI2460
VARI2470
VARI2480
VARI2490
VARI2500
VARI2510
VARI2520
VARI2530
VARI2540
VARI2550
VARI2560
VARI2570
VARI2580
VARI2590
VARI2600
VARI2610
VARI2620
VARI2630
VARI2640
VARI2650
VARI2660
VARI2670
VARI2680
VARI2690
VARI2700

OMRSA=XDELIM(0.0MAX,XCIT(L,6))
OMRS=OMRSA
GO TO 220
270 GOV=XCIT(L,5)
GO TO 220
210 IF(TIME-LT,XCIT(L,1)) GO TO 220
DA=XCIT(L,3)*HDELT
N=XCIT(L,6)*.01
IF(XCIT(L,2).EQ.0.) GO TO 225
TAX(N)=TAX(N)+DA
IF(SIGN(1.0DA).EQ.SIGN(1.0(XCIT(L,5)-TAX(N)))) GO TO 220
TAX(N)=XCIT(L,5)
222 XCIT(L,1)=9999.
GO TO 220
225 IF(TIME-GE,XCIT(L,4)) GO TO 222
TAX(N)=TAX(N)+DA
GO TO 220
211 IF(ALERT.EQ.0.0.AND.ABS(AY).LT.XCIT(L,2)) GO TO 220
IF(TIME-GE,XCIT(L,6)) GO TO 220
ALERT=1.
AYID=(AY-AY1)*DELT2R
AYDABS=ABS(AYID)
AYDMX=AMAX1(AYDMX,AYDABS)
..... SAVES LARGEST YAW RATE (ABS.)
UNTIL PILOT GOES OFF ALERT.
C
C
IF(ABS(AY).GE.XCIT(L,2)) GO TO 710
IF(AYDABS .GE.(XCIT(L,5)*AYDMX))GO TO 710
ALERT=0.
AYDMX=0.
GO TO 220
710 DA=(AY*XCIT(L,3)+AY10*XCIT(L,4))*HDELT
GO TO 263
C
WEAPONS GROUP
212 FGUN=0.
IF(XCIT(L,2)-LT,TIME) GO TO 250
RMLTH=XCIT(L,4)
TIMEIN=T-XCIT(L,1)
IF(TIMEIN.LT.RMLTH) FGUN=TIMEIN*XCIT(L,5)
IF(TIMEIN.GE.RMLTH) FGUN=XCIT(L,3)
250 CALL RATS (FGUN,0.0.,AYDG,APBG,ARBG,XFGUN,YFGUN,ZFGUN,1)
CALL ODS (XAGUN,YAGUN,ZAGUN,XFGUN,YFGUN,ZFGUN,LGUN,MLGUN,NGUN)
GO TO 220
213 IF(XCIT(L,3)-LT,TIME) GO TO 220
RATE=XCIT(L,2)
DA=RATE*HDELT
VZETA=RATE
IF(J.EQ.20) AZETA=AZ
ZETATR=ZETA
CALL TILT (XAR,ZAR,CGML,COLL,ZETA,CGSTA)
ALF=XCIT(L,5)
IF(ZETA.LE.ALF) GO TO 205
BET=XCIT(L,4)
DOMEG=XCIT(L,6)*SIN(ZETA-ALF)*BET)*DA

```

```

VARI2710
VARI2720
VARI2730
VARI2740
VARI2750
VARI2760
VARI2770
VARI2780
VARI2790
VARI2800
VARI2810
VARI2820
VARI2830
VARI2840
VARI2850
VARI2860
VARI2870
VARI2880
VARI2890
VARI2900
VARI2910
VARI2920
VARI2930
VARI2940
VARI2950
VARI2960
VARI2970
VARI2980
VARI2990
VARI3000
VARI3010
VARI3020
VARI3030
VARI3040
VARI3050
VARI3060
VARI3070
VARI3080
VARI3090
VARI3100
VARI3110
VARI3120
VARI3130
VARI3140
VARI3150
VARI3160
VARI3170
VARI3180
VARI3190
VARI3200
VARI3210
VARI3220
VARI3230
VARI3240

OMEGA=OMEGH+OMEG
OMEGND=OMEG*ROELT2+OMEGND
QQ=1.
GO TO 205
214 CONTINUE
IBRAKE=0
IF( TIME.GT.XCIT(L,4).OR.PSIO(1).GT.XCIT(L,2) ) IBRAKE=1
GO TO 220
215 OLOASE=ASEP
FLAG=XCIT(L,6)*ROELT2
ASEP=(XCIT(L,2)*(XCIT(L,5)-APE)+XCIT(L,3)*APD+XCIT(L,4)*Y(I-1,60)
1 +OLOASE*FLAG)/(1.+FLAG)
DA=ASEP
GO TO 261
216 IF( TIME.GT.XCIT(L,4) ) GO TO 220
OT=XCIT(L,2)*(1-XCIT(L,1))
RATE=XCIT(L,3)*COS(OT)
OA=RATE*MOELT
K=XCIT(L,5)+.1
IF(K.EQ.5) AZ=-XCIT(L,2)*XCIT(L,3)*SIN(OT)
GO TO (260,261,262,263,271),K
217 IF(ABS(HALFPI -ZETA).GT.0.001) GO TO 220
OAL=XCIT(L,3)*MOELT
O1=ALM-XCIT(L,4)
IF(ABS(O1).GT.XCIT(L,2) ) OT1(1)=OT1(1)+OAL*O1
O1=BM-XCIT(L,5)
IF(ABS(O1).GT.XCIT(L,2) ) OT2(1)=OT2(1)-OAL*O1
GO TO 220
218 IF(ABS(HALFPI -ZETATR).GT.0.001) GO TO 220
OAL=XCIT(L,3)*MOELT
O1=ALM-XCIT(L,4)
IF(ABS(O1).GT.XCIT(L,2) ) OT1(2)=OT1(2)+OAL*O1
O1=BM-XCIT(L,5)
IF(ABS(O1).GT.XCIT(L,2) ) OT2(2)=OT2(2)-OAL*O1
GO TO 220
219 CONTINUE
M=XCIT(L,1)+.1
HUBK(M)=XOELIM(XCIT(L,3),XCIT(L,2),
1 HUBK(M,1,N)*PSIO(N)+HUBKI(1,N))
HUBK(M,2)=XOELIM(XCIT(L,3),XCIT(L,2),
1 HUBK(M,2,N)*PSIO(N)+HUBKI(2,N))
GO TO 220
282 CONTINUE
N=XCIT(L,1)+.1
BETANN=XOELIM(XCIT(L,3),XCIT(L,2),XCIT(L,4)+XCIT(L,5)*PSIO(N))
IF(BETANN.EQ.XCIT(L,2).AND.XCIT(L,6).GT..5) GO TO 220
IF(BETANN.EQ.XCIT(L,3).AND.XCIT(L,6).LT.-.5) GO TO 220
BETANN(B)=BETANN
VPSIN=MPST(N)
IF(BETANN.EQ.XCIT(L,2) ) XCIT(L,6)=1.
IF(BETANN.EQ.XCIT(L,3) ) XCIT(L,6)=-1.
DA=0.
IF(BETAZ(N).GT.(-BETANN) ) OA=BETAZ(N)+BETANN
IF(BETAZ(N).LT.(-BETANN).AND.BETAZ(N).LT.BETAZ(N) )

```

```

10A=BETAZ(N)-AMIN1(BETAZ(N),(-BETAMN))
BETAZ(N)=BETAZ(N)-DA
BETAX(N)=BETAZ(N)*2.-BETAMN
DO 301 K=1,NP5IN
  BETA(K,N)=BETA(K,N)-DA
  Y(1,7*N+K+10)=Y(1,7*N+K+10)-DA
301 CONTINUE
IF(KONFIG.EQ.3) CALL TFFA (XAR,BETAZ,CGSTA)
GO TO 220
283 CONTINUE
  XLOK=1.
  IF(XCIT(L,6).EQ.0.) GO TO 277
  XLOK=0.
  XCIT(L,2)=9999.
277 CONTINUE
  N=XCIT(L,5)
  DO 278 M=1,4
    N1=5-M
    N2=2*(N1-1)
    IF(N.LT.N2) GO TO 278
    CONLOK(N1)=XLOK
    THETS(N1)=THET(N1)
    IF(N1.GT.2) THETS(N1+2)=THET(N1+2)
    N=N-N2
278 CONTINUE
  XCIT(L,1)=XCIT(L,2)
  XCIT(L,3)=XCIT(L,4)
  XCIT(L,6)=1.
  GO TO 220
284 CONTINUE
  IF(IME.LE.XCIT(L,2)) GO TO 285
  KPD=0
  XCIT(L,1)=9999.
  GO TO 220
285 CONTINUE
  IF(1.NE.2) GO TO 292
  XMOM(1)=ZF
  XMOM(2)=XMB1
  XMOM(3)=XMA1
  IF(KPO.NE.0) GO TO 288
  DO 287 K=1,3
    DO 286 M=1,3
      POM(K,M)=0.
286 CONTINUE
  POM(K,K)=XCIT(L,K+2)
  POM(K,4)=-XMOM(K)
287 CONTINUE
  GO TO 290
288 CONTINUE
  DO 289 K=1,3
    POM(K,KPO)=(XMOM(K)+POM(K,4))/OTHET
    POM(K,4)=-XMOM(K)
289 CONTINUE
  OTHETO(KPO)=OTHET

```

```

VARI3250
VARI3260
VARI3270
VARI3280
VARI3290
VARI3300
VARI3310
VARI3320
VARI3330
VARI3340
VARI3350
VARI3360
VARI3370
VARI3380
VARI3390
VARI3400
VARI3410
VARI3420
VARI3430
VARI3440
VARI3450
VARI3460
VARI3470
VARI3480
VARI3490
VARI3500
VARI3510
VARI3520
VARI3530
VARI3540
VARI3550
VARI3560
VARI3570
VARI3580
VARI3590
VARI3600
VARI3610
VARI3620
VARI3630
VARI3640
VARI3650
VARI3660
VARI3670
VARI3680
VARI3690
VARI3700
VARI3710
VARI3720
VARI3730
VARI3740
VARI3750
VARI3760
VARI3770
VARI3780

```

```

290 CONTINUE
KPD=KPD+1
IF(KPD.EQ.4) KPD=1
DO 291 K=1,4
DO 291 M=1,3
  PPSI(M,K)=PDM(M,K)
291 CONTINUE
  KMI=3
  CALL SOLVE
  IF(EXIT.EQ.0.) GO TO 293
  DTHT=C.
  EXIT=0.
  SO TO 294
293 CONTINUE
  DTHT=XIKPD)
  XLIM=XCITIL(6)*TDELT
  DTHT=XDELIM(-XLIM,XLIM,DTHT)
294 CONTINUE
  DXMIN=.8726646E-02*TDELT
  IF(ABS(DTHT).LT.DXMIN) DTHT=SIGN(DXMIN,DTHT)(KPD)
292 CONTINUE
  THETS(KPD)=THETS(KPD)+.5*DTHT
  GO TO 220
295 CONTINUE
  DO 296 K=1,5,2
  IF(TIME.GF.XCITIL(K)) NPRINT=XCITIL(K+1)
296 CONTINUE
  IF(NPRINT.LE.0) NPRINT=1
  GO TO 220
226 CONTINUE
  IF(XCITIL(3).LT.TIME) GO TO 220
  DA=XCITIL(2)*WDELT
  K=XCITIL(4)+.1
  K1=K
  NPSI1=NPSI(1)
  IF(K.NE.1) GO TO 228
  PSIREF11=PSIREF11+DA
  Y11(7)=Y11(7)+DA
  DO 227 M=2,NPSI1
  DPSI1(M,1)=DPSI(M,1)-DA
227 CONTINUE
  K1=NPSI1
  SO TO 231
228 CONTINUE
  DPSI1(1)=DPSI1(1)+DA
231 CONTINUE
  IF(HUBKPS.NE.0.) GO TO 220
  DO 230 N=K,K1
  DO 229 M=1,NPSI1
  COSE1(M,N,1)=COS(DPSI(M,1)-DPSI1(M,1))
229 CONTINUE
  COSF(N,N,1)=1.
230 CONTINUE
  CALL HSAF (XAR,YAR,DPSI,NPSI,CGSTA,PSIREF)

```

```

VARI3790
VARI3800
VARI3810
VARI3820
VARI3830
VARI3840
VARI3850
VARI3860
VARI3870
VARI3880
VARI3890
VARI3900
VARI3910
VARI3920
VARI3930
VARI3940
VARI3950
VARI3960
VARI3970
VARI3980
VARI3990
VARI4000
VARI4010
VARI4020
VARI4030
VARI4040
VARI4050
VARI4060
VARI4070
VARI4080
VARI4090
VARI4100
VARI4110
VARI4120
VARI4130
VARI4140
VARI4150
VARI4160
VARI4170
VARI4180
VARI4190
VARI4200
VARI4210
VARI4220
VARI4230
VARI4240
VARI4250
VARI4260
VARI4270
VARI4280
VARI4290
VARI4300
VARI4310
VARI4320

```

220 CONTINUE
RETURN
FWD

VARI4330
VARI4340
VARI4350

```

SUBROUTINE VIND (N,EXIT)
COMMON /ROMAN/
*   ZZ,VXS(2),VYS(2),VZS(2),BETA(12,2),
*   T,PCC(2),COSE(7,7,2),BETAN(2),BETAX(2),BETAZ(2),
1   AIB(2),APDD,APDD,AYDD,AIR(2),
2   DPSI(12,2),DTRR,NPSI(2),ZZTR,
3   BETAD(12,2),BNPSI(2),
4   COMD2,GMAXV,RATEI,RATE2,STOP2,
5   THROT(2),TRIND,XGUST,BETAZO(2),GMAXV1,
6   GMAXV2,GMAXV3,GUSTYP,HMPSIR(2),
7   HUBKPS,HUBKRS,HUBTPS,HUBTRS,
8   KONFIG,LNGTH1,PILGH1,PSIREF(2),
9   START2,XMOMLI(12,2),
A   R(2),OR(2),TI(2),
B   T2(2),TZR(2),XMA(2),
C   XMB(2),AIB(2),AIBR(2),
D   APR(2),ARDR(2),PSIO(2),
E   XSTAH(2),YSTAH(2),
F   HUBKPR(2),HUBKRR(2)
COMMON /MANARD/
*   AZETAR(2),VZETAR(2)
1   I,V,IND,MWAG,APBMT,ARBMT,AYBMT,BETAD(2),TDELT,
2   BETAE(2),HGUSTE,HGUSTF,HGUSTW,VGUSTE,
3   VGUSTM,YGUSTF,GFWD,GLAT,GVERT,
4   VXB,VZB,APD,VYB,ARD,AYD,
5   COLSTK,CYSTK1,CYSTK2,PEDAL,AYE,
6   APE,ARE,AIM,BIM,AITR,BITR,
7   XAR(2),YAR(2),ZAR(2),
8   VIR(2),ZETAR(2),MFORCE(2),
9   THRUST(2),TORQUE(2),YFORCE(2)
COMMON /STANRO/
1   J,M,ITM,VHS(2),LINK,OELE,VROT(2),
2   VSMD,YFINI(2),ZFEL(2),AIBAL(2),
3   BIBAL(2),COND1,SWING,PILGH2,PHGELL,
4   R(2),PHOM(2),RMON(2)
COMMON /ROSTAR/
1   AM(2),CT,PI,XR(2),ALT,ADR(2),EXH(2),
2   NXR(2),RBH(2),SVC(2),UHS,CDH8(2),LROT(2),
3   RAB(2),RTRP(2),TAIR14),CONEK(2),DCAFR(2),FVINO,
4   NWARD,
5   SWKR1(2),SMKR2(2),TIP18(2),TIP38(2),
6   TWIST(20,2),CLRAOK(2),OELTA3(2),
7   LAMBDA(2),UPGUST,URGUST,UTGUST,WROTOR,
8   ER(2),FRX(2),
9   XLIMAX(2),XLIMIN(2)
PEAL LAMBOA,LAMZ
BB=1.-2.*SORT(ABS(CT))/(ABS(OR(N))*B(N))
CB=CT/(180*BB-ADR(N))
DI=ABS(CB)
O2=-6*O1*SORT(O1)
O3=O1*8.*UHS
O4=O2/O3
O5=O1*O4
O6=2.6666667*O4
LAMBDA(N)=VZS(N)
L=100
17 CONTINUE
L=L-1

```

```

VIND0010
VIND0020
VIND0030
VIND0040
VIND0050
VIND0060
VIND0070
VIND0080
VIND0090
VIND0100
VIND0110
VIND0120
VIND0130
VIND0140
VIND0150
VIND0160
VIND0170
VIND0180
VIND0190
VIND0200
VIND0210
VIND0220
VIND0230
VIND0240
VIND0250
VIND0260
VIND0270
VIND0280
VIND0290
VIND0300
VIND0310
VIND0320
VIND0330
VIND0340
VIND0350
VIND0360
VIND0370
VIND0380
VIND0390
VIND0400
VIND0410
VIND0420
VIND0430
VIND0440
VIND0450
VIND0460
VIND0470
VIND0480
VIND0490
VIND0500
VIND0510
VIND0520
VIND0530
VIND0540

```

```

VIND0550
VIND0560
VIND0570
VIND0580
VIND0590
VIND0600
VIND0610
VIND0620
VIND0630
VIND0640
VIND0650
VIND0660
VIND0670
VIND0680
VIND0690
VIND0700
VIND0710
VIND0720
VIND0730
VIND0740
VIND0750
VIND0760
VIND0770
VIND0780
VIND0790
VIND0800

IF(L.LE.0) GO TO 30
VIRS=VIR(N)
LAM2=LAMBDA(N)**2
VIR(N)=CB/(SQRT(.866*LAM2+UHS)+(Q5-Q6*LAMBDA(N)*ABS(LAMBDA(N)))/
1 (Q1+8.*LAM2))
LAMBDA(N)=VZS(N)-VIR(N)
IF(ABS(VIR(N)-VIRS).GT..0001) GO TO 10
GROUND EFFECT - FOR V.LT.30 AND IF H IS FROM .25 TO 1. ROTOR DIAME
VIND0550
VIND0560
VIND0570
VIND0580
VIND0590
VIND0600
VIND0610
VIND0620
VIND0630
VIND0640
VIND0650
VIND0660
VIND0670
VIND0680
VIND0690
VIND0700
VIND0710
VIND0720
VIND0730
VIND0740
VIND0750
VIND0760
VIND0770
VIND0780
VIND0790
VIND0800

GRE=.25+.5*ALT/R(N)
IF(GRE.GT.1.) RETURN
IF(VROT(N).LE.30.) VIR(N)=VIR(N)*(1.+(GRE-1.)*((VROT(N)-30.)
1 /30.))**2)
IF(GRE.GE..25) RETURN
EXIT=1.
WRITE(6,9000)
RETURN
30 WRITE(6,9001)
VIR(N)=0.
LAMBDA(N)=VZS(N)
RETURN
9000 FORMAT(28H0.....SHIP CONTACTS GROUND)
9001 FORMAT(27HINDUCED VELOCITY SET TO 0.728H CALCULATIONS NON-CONVERG
1ENT)
ENO

```

```

SUBROUTINE WAG1
DIMENSION HEAD(2),FX(61,4),XD(4),DETH(31,4),KFLAG(4)
DATA HEAD /'MAINTAIL'/
DO 100 I=1,4
KFLAG(I)=C
100 CONTINUE
RETURN
ENTRY WAG (CHR,K,I,V,TDELT,RED,DLIFT)
RED=0.
IF(KFLAG(I).EQ.1) GO TO (40,40,30,30),I
1 K2=(K-1)/2+1
K4=(K-1)/4+1
DETH(K,I)=DLIFT
IF(I.GT.2) GO TO 8
DD=TDELT*.5*V/(2.*CHR)
IF(K2.GT.2) GO TO 2
IF(DO.GT..5) GO TO 41
GO TO 9
8 DD=TDELT*V/CHR
IF(K2.GT.2) GO TO 2
IF(DD.GT.7.5) GO TO 31
9 IF(K2.NE.1) GO TO 2
XC(I)=DD
50 TO 3
2 IF(MOD(K,2).EQ.1) XD(I)=DD+XD(I)
3 A=XD(I)
IF(I.GT.2) GO TO 4
IF(A.GT.1.) GO TO 5
FX(K2,I)=1-((.5+A*(6.011997+A*(-28.92326+A*(72.13591
1+A*(-97.5837+A*(67.39273+A*(-18.53368))))))
IF(K.LE.10) GO TO 10
GO TO 5
4 IF(A.GT.15.) GO TO 5
FX(K2,I)=.2838*EXP(-.49*A)
IF(K.LE.120) GO TO 10
5 DO 6 J=2,K4
6 DETH(J-1,I)=DETH(J,I)
K=K-1
K7=K2-1
K4=K4-1
10 DO 20 J=1,K4
M=K2-2*(J-1)
20 RED=RED+DETH(J,I)*FX(M,I)
50 RETURN
31 KFLAG(I)=1
30 WRITE (6,60)
60 FORMAT (1H0,13X,'ALLEVIATION DEVICE FOR WINGS BYPASSED BECAUSE WINWAG00470
15 CHORD IS TOO SMALL FOR THIS TIME INCREMENT AND VELOCITY.')
```

```

WAG00010
WAG00020
WAG00030
WAG00040
WAG00050
WAG00060
WAG00070
WAG00080
WAG00090
WAG00100
WAG00110
WAG00120
WAG00130
WAG00140
WAG00150
WAG00160
WAG00170
WAG00180
WAG00190
WAG00200
WAG00210
WAG00220
WAG00230
WAG00240
WAG00250
WAG00260
WAG00270
WAG00280
WAG00290
WAG00300
WAG00310
WAG00320
WAG00330
WAG00340
WAG00350
WAG00360
WAG00370
WAG00380
WAG00390
WAG00400
WAG00410
WAG00420
WAG00430
WAG00440
WAG00450
WAG00460
WAG00470
WAG00480
WAG00490
WAG00500
WAG00510
WAG00520
WAG00530
WAG00540
```

RETURN
END

MAG00550
MAG00560


```

SUBROUTINE WROT1
COMMON /TOPLOT/ AH(3),AL(3),EXIT,ICOM(49),IPSN,
1 NPART,NVARA,NVARB,NVARC,NSCALE
1 NVAR,NPRINT,NTIME
DIMENSION NDATE(2)
CALL DATE (NDATE)
RETURN
ENTRY WROT
WRITE (6,1000) NDATE,NPART,IPSN,ICOM
RETURN
1000 FORMAT (1H1,46X,'BELL HELICOPTER IBM 360/ PROGRAM ASAJ0: '//
1 H ,46X,'HELICOPTER RIGID BODY DYNAMICS ANALYSIS'//
2 H ,57X,'COMPILED 10/30/69'//
3 H ,57X,'COMPUTED ',2A4//
4 1H0,18X,14,4X,19,5X,15A4/1H ,32X,17A4,/1H ,32X,17A4)
END

```

```

WROT0010
WROT0020
WROT0030
WROT0040
WROT0050
WROT0060
WROT0070
WROT0080
WROT0090
WROT0100
WROT0110
WROT0120
WROT0130
WROT0140
WROT0150
WROT0160

```



```

WRITE (6,60) (HEAD(I,21),I=1,3),(PD(I,KM1+1),I=1,KM1)
RETURN
20 FORMAT (1H0,11X,'VAR(I) ',10F10.5)
10 FORMAT (/1H .30X,'THRUST M-FORCE Y-FORCE TORQUE ',
1 'IND. V. CONING JET THRUST'/16X,
2 'MAIN ROTOR',4F10.0,2F10.3,5X,'RIGHT/CENTER',F10.0/16X,
3 'TAIL ROTOR',4F10.0,2F10.3,5X,'LEFT ',F10.0)
30 FORMAT (1H0,53X,'PARTIAL DERIVATIVE MATRIX'/1H0,11X,30A4/)
60 FORMAT (1H .3A4,10F12.0)
END

```

```

MRVP0550
:MRVP0560
MRVP0570
MRVP0580
MRVP0590
MRVP0600
MRVP0610
MRVP0620
MRVP0630
MRVP0640

```

```

SUBROUTINE YFIX (VIN, YAERO)
DIMENSION HEAD(9), YIN(21,5), YAERO(31,5)
DATA HEAD / 'M.R.T.R.WING ELE FINNORMAL REVERSED' /
DATA DTRR,PI23,DTRRSO /57.29578,2.0943951,3282.806/
DO 15 I=1,18
DD=1.
IF(I.EQ.13.OR.I.EQ.17) DD=DTRR
IF(I.EQ.14) DD=DTRRSO
DO 18 J=1,5
YAERO(I,J)=YIN(I,J)*DD
18 CONTINUE
15 CONTINUE
DO 20 J=1,5
IF(YAERO(17,J).EQ.0.) GO TO 20
YAERO(18,J) = YAERO(18,J)*PI23
ALB1MR=YAERO(17,J)*YIN(18,J)/(2.+YIN(18,J))
IW1=-1
IW2=2
DO 25 IW=22,23
IW1=IW1+4
IW2=IW2+2
YAERO(IW,J)=YAERO(IW1,J)/ALB1MR+.08727
IF(YAERO(IW,J).LE..69813) GO TO 25
YAERO(IW1,J)=-.61087*ALB1MR
YAERO(IW,J) = .69813
WRITE (6,26) HEAD(J),(HEAD(IW2+K),K=2,3),YAERO(IW1,J)
25 CONTINUE
27 CONTINUE
YAERO(20,J)=SIN(YAERO(22,J))
YAERO(24,J)=SIN(2.*YAERO(22,J))
YAERO(26,J)=COS(YAERO(22,J))
YAERO(21,J)=SIN(YAERO(23,J))
YAERO(25,J)=SIN(2.*YAERO(23,J))
YAERO(27,J)=COS(YAERO(23,J))
IF(YAERO(1,J).LT.1.) GO TO 12
YAERO(1,J)=.99
WRITE(6,101) HEAD(J),YAERO(1,J)
12 SM = SORT(1.+(1.-YAERO(1,J)**2)**16./YAERO(17,J)**2)
IF(YAERO(2,J).GT.SM) GO TO 29
YAERO(2,J)=SM
WRITE (6,102) HEAD(J),YAERO(2,J)
29 YV1 = YAERO(17,J)/SORT(1.-YAERO(1,J)**2)
YV2 = 4./SORT(YAERO(2,J)**2-1.)
YV3 = -YV2*YAERO(2,J)/(YAERO(2,J)**2-1.)
DEN = 1./YAERO(2,J)-YAERO(1,J)**2
YAERO(31,J) = ( YV1-YV2-YV3*(YAERO(1,J)-YAERO(2,J)))*DEN
YAERO(30,J) = YV3 - 2.*YAERO(31,J)*YAERO(2,J)
YAERO(29,J) = YV1-YAERO(30,J)*YAERO(1,J)-YAERO(31,J)*YAERO(1,J)**2
20 CONTINUE
RETURN
26 FORMAT (1H0,10X,A4,' CLZ FOR ',2A4,' FLOW HAS BEEN RESET TO
1 F6.3,' ALB = 40 DEGREES.')
101 FORMAT (1H0,10X,A4,' DRAG DIVERGENCE MACH NUMBER HAS BEEN RESET TOYFIX0530
1 ',F6.3)

```

```

YFIX0010
YFIX0020
YFIX0030
YFIX0040
YFIX0050
YFIX0060
YFIX0070
YFIX0080
YFIX0090
YFIX0100
YFIX0110
YFIX0120
YFIX0130
YFIX0140
YFIX0150
YFIX0160
YFIX0170
YFIX0180
YFIX0190
YFIX0200
YFIX0210
YFIX0220
YFIX0230
YFIX0240
YFIX0250
YFIX0260
YFIX0270
YFIX0280
YFIX0290
YFIX0300
YFIX0310
YFIX0320
YFIX0330
YFIX0340
YFIX0350
YFIX0360
YFIX0370
YFIX0380
YFIX0390
YFIX0400
YFIX0410
YFIX0420
YFIX0430
YFIX0440
YFIX0450
YFIX0460
YFIX0470
YFIX0480
YFIX0490
YFIX0500
YFIX0510
YFIX0520
YFIX0530
YFIX0540

```

1.7? FORMAT (1H0,10X,A4,1 MACH NUMBER FOR LOWER BOUND OF SUPERSONIC REGYFIX0550
110M HAS BEEN RESET TO 1,P6.3) YFIX0560
END YFIX0570

UNCLASSIFIED

Security Classification

DOCUMENT CONTROL DATA - R & D		
<i>(Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified)</i>		
1. ORIGINATING ACTIVITY (Corporate author) Bell Helicopter Company Fort Worth, Texas 76101		2a. REPORT SECURITY CLASSIFICATION Unclassified
		2b. GROUP
3. REPORT TITLE A STABILITY AND CONTROL PREDICTION METHOD FOR HELICOPTERS AND STOPPABLE ROTOR AIRCRAFT -- VOLUME IV		
4. DESCRIPTIVE NOTES (Type of report and inclusive dates) Final Report		
5. AUTHOR(S) (First name, middle initial, last name) Billy J. Bird		
6. REPORT DATE February 1970	7a. TOTAL NO. OF PAGES 304	7b. NO. OF REFS
8a. CONTRACT OR GRANT NO. F33615-69-C-1121	8b. ORIGINATOR'S REPORT NUMBER(S)	
b. PROJECT NO. 8219		
c. Task No. 821907	9b. OTHER REPORT NO(S) (Any other numbers that may be assigned this report) AFFDL-TR-69-123, Volume IV	
d.		
10. DISTRIBUTION STATEMENT This document has been approved for public release and sale; its distribution is unlimited.		
11. SUPPLEMENTARY NOTES		12. SPONSORING MILITARY ACTIVITY Air Force Flight Dynamics Laboratory Wright-Patterson AFB, Ohio 45433
13. ABSTRACT This report describes a mathematical model of rotorcraft that may be used to determine characteristics of performance, stability, response, and rotor blade loads. The complexity of the equations used requires the use of a digital computer for efficient solution. This four volume report describes the computer program in detail and illustrates the method of computing rotorcraft characteristics by specific example. This volume contains the Appendices. Volume III describes the contents and use of these appendices in detail. The first and second volumes contain a discussion of the mathematical model and detailed instructions for the users of the program. These appendices, which originate from card images for easy updating, are necessary tools for any programmer working on this program.		

DD FORM 1473
1 NOV 66

UNCLASSIFIED

Security Classification

14. KEY WORDS	LINK A		LINK B		LINK C	
	ROLE	WT	ROLE	WT	ROLE	WT
Helicopter Stability and Control Stoppable Rotor Aircraft Stability and Control V/STOL Aircraft Rotorcraft Simulation						