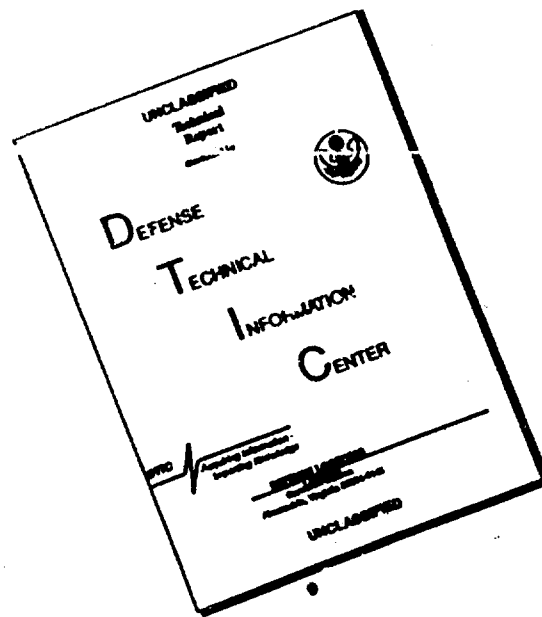


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ACCELERATING LP ALGORITHMS

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Winograd [3] has given a new method for computing inner products. Under certain circumstances, when a series of inner products must be calculated, using Winograd's scheme is more efficient than the standard (naive) method. Winograd points out that his method does matrix multiplication up to twice as fast as the usual scheme and notes similar acceleration for matrix inversion and the solution of linear equations.

Here we point out how Winograd's method can speed up linear programming (LP) algorithms, in particular the revised simplex method, (see, e.g., Simonnard [2]).

Winograd's algorithm:

Let $x = (x_1, \dots, x_n)$, $y = (y_1, \dots, y_n)$,

$$\xi = \sum_{j=1}^{[n/2]} x_{2j-1} x_{2j}$$

$$\eta = \sum_{j=1}^{[n/2]} y_{2j-1} y_{2j}$$

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$$\gamma = \sum_{j=1}^{\lfloor n/2 \rfloor} (x_{2j-1} + y_{2j})(x_{2j} + y_{2j-1}),$$

where $\lfloor t \rfloor$ denotes the integer part of t . The inner product (x, y) is then given by

$$(x, y) = \begin{cases} \gamma - \xi - \eta, & \text{if } n \text{ is even} \\ \gamma - \xi - \eta + x_n y_n, & \text{if } n \text{ is odd.} \end{cases}$$

In the sequel, we denote (x, y) simply by xy .

Pricing out in LPs:

At a given iteration, let π be the vector of simplex multipliers and let J be the set of nonbasic columns in the constraint matrix. A major task is to determine which column should enter the basis. Let a^j stand for a generic column. To price out, we need to compute πa^j , $j \in J$. Assuming that there are m constraints and k columns in J , the conventional procedure requires km multiplications and $k(m - 1)$ additions.

Now we apply Winograd's method. For simplicity, suppose that m is even. At the first iteration only, compute

$$\lambda_j = \sum_{i=1}^{m/2} a_{2i-1}^j a_{2i}^j$$

for all j , basic or not. Of course, if a^j is a unit vector, $\lambda_j = 0$. (The initial basis generally consists of unit vectors.) Since the λ_j 's need to be computed only once, we neglect the multiplications and

additions involved. Thus, pricing out with Winograd's scheme requires $(k + 1)m/2$ multiplications and $k(3m/2 + 1) + m/2 - 1$ additions per iteration. Typically, $k \gg m$. If the multiply and add times were identical, the two procedures would be roughly equivalent. If the multiply time is significantly slower than the add time, as is generally the case, the acceleration using Winograd's procedure can be dramatic. Winograd's procedure requires roughly half as many multiplications as the standard procedure and roughly 50 per cent more additions.

Improvement factor:

If p is the fraction of time spent pricing out with the standard method and r is the ratio of multiply time to add time, then using Winograd's algorithm is approximately $2(r + 1)/[p(r + 3) + 2(1 - p)(r + 1)]$ times as fast as using a standard LP code. For $r = 3$, a fairly representative number for current computers, the improvement factor is $8/(8 - 2p)$.

Now we estimate p . A pivot takes about m^2 multiplications and m^2 additions. By comparison, the number of operations to find the representation of the pivot column in terms of the current basis is of the same order and the number to determine the pivot row is negligible. We do not count input/output time. Thus p is about $k/(2m + k)$, which is typically near one. For $r = 3$, we can expect an improvement of almost 25 percent.

Other LP applications:

We do not see where Winograd's procedure would be helpful in general in pivoting. However, sometimes a good starting basis is known (often, in Markov renewal programming [1]) and Winograd's procedure can then be applied to efficiently compute its inverse. See [3] for details.

Sparse matrices:

Various programming tricks for handling sparse matrices are available. When using these tricks, the relative efficiency of Winograd's procedure should be reexamined. We believe that Winograd's procedure will generally turn out to be faster.

REFERENCES

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