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A BASIC INVESTIGATION

OF

PERSPECTIVE MAP PROJECTIONS

A THESIS

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by

ALAN L. LAUBSCHER

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THE OHIO STATE UNIVERSITY

1965

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A BASIC INVESTIGATION OF PERSPECTIVE MAP PROJECTIONS

A Thesis

Presented in Partial Fulfillment of the Requirements for the Degree Master of Science

by

Capt. Alan Leland Laubscher, B.S.

The Ohio State University

1965

Approved by

Adviser Department of Geodetic Science

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1. INTRODUCTION

1. Map Projections

The subject of map projections has developed from its inception sometime early in the history of mankind, consisting of perhaps a rough sketch drawn in the sand, to a specialized branch of applied mathematics which it is today. Due both to this long development and to the extent of the subject, it is possible to encounter numerous definitions of a map projection. The very name of the subject, map projections, is deceiving, for most map projections are not projections in the true mathematical sense of the word. In the true mathematical sense, the term projection has the connotation perspective projection. Perspective projection may be simply described as the determining of the position on a plane of points in space as they would appear on the plane from some particular fixed view point. Applying the above definition to map projection would indicate that a map projection is the representation of the surface of the earth, or an accepted datum surface approximating the surface of the earth, on a plane as it would appear on the plane from some particular fixed view point. However, the above definition can certainly not be used to totally describe map projection in the sense in which the term is commonly used. The term projection, as applied to map projection, includes numerous geometrical, mathematical, and semi-geometrical transformations of a liatum surface onto a plane. Only a very few of these projections are truly perspective projections in a mathematical sense.

As was stated earlier, a map projection has been defined in many ways. One method of describing a map projection is to describe the transformation of the meridians and parallels from the surface of the earth, or a datum surface approximating the surface of the earth, to a mapping plane. The author will define a map projection as a systematic arrangement of intersecting lines on a plane that represent, and have a one-to-one correspondence to, the meridians and parallels of the datum surface. These lines, drawn to represent the meridians and parallels, are drawn according to some consistent principle in order to fulfill certain required conditions. Each set of new conditions produces a different map projection, and hence there potentially exists an unlimited number of map projections. Common conditions used in map projections are such that distances, areas, or angles measured on the datum surface will be equal to those measured on the mapping plane. In addition to the more common conditions stated above, a myriad of other conditions have been used to produce map projections. The conditions by which each particular map projection is designed are naturally based on the intended purpose of the map.

1.2 Perspective Map Projection

Based on the discussion in Section 1.1, it is apparent that the perspective map projection is only one of the many different types of map projections. It has characteristics, both desirable and undesirable, which dictate its use or non-use for particular purposes. A perspective map projection may be ideally vizualized as a

photograph taken of a portion of the datum surface. A photograph taken by an aircraft, a rocket, or a space vehicle of the earth, moon, or other heavenly body is actually a type of perspective projection. This certainly is one of the interesting aspects of the study of perspective projections.

Perspective projections are based on simple geometric principles. A straight line, which will be called the projection axis of the projection, extends from a point on the datum surface, through a point in space named the projection center, to the projection plane. This projection axis is perpendicular both to the datu surface and the projection plane. The intersection of the projection axis and the projection plane locates a point denoted as the image center. Likewise, all other points on the datum surface are located on the projection plane by extending straight lines from the particular point, through the projection center, onto the projection plane. In Figure 1, C represents the projection center and C', the image center. P is an arbitrary point on the datum surface and P' is the projection of this point on the projection plane. Principles of elementary geometry prove that a parallel displacement of the projection plane along the projection exis changes only the scale of the projection. However, a change in the location of the projection center will change the form of the projection. The location of the projection center is the factor which determines the characteristics of a particular perspective projection.



One means of classifying perspective projections is according to the orientation of the projection axis. If the projection axis is coincident with the axis of rotation of the datum surface, the projection is referred to as a normal or polar projection. If the projection axis lies in the equatorial plane of the datum surface, the projection is referred to as a transverse or equatorial projection. If the projection falls into neither of the above two special categories, then it is referred to as an oblique projection. It should be kept in mind that the normal and transverse projections are merely special cases of the oblique projection and equations derived for oblique projections are applicable to all special cases.

1.3 The Investigation Of Perspective Map Projections

The purpose of this thesis is to investigate the perspective projection in a very basic manner. The primary goal is to develop general mapping equations for the perspective projection suitable both for a spherical and an ellipsoidal datum surface. The term, mapping equations, refers to equations which transform the coordinates of a point from a latitude-longitude-elevation three dimensional type coordinate system of the datum surface to a X-Y plane coordinate system of the projection plane. A discussion of the distortions inherent in perspective projections is included to illustrate a method of using distortions to describe a projection. It will be seen that a combination coordinate-distortion type table or grid is an effective aid in vizualizing a projection.

The investigation is divided into five primary parts. In order to provide general background material and also provide equations on which to base the validity of equations derived later, Chapter 2 will briefly discuss and derive in a conventional manner the mapping equations for the three most common types of perspective projections. These three common projections are the Gnomonic Projection, the Stereographic Projection, and the Orthographic Projection. Chapter 3 discusses a descriptive geometry approach to perspective map projections as presented by Erwin Schmid [12]. It is from this publication that the author first became interested in the subject matter of this thesis. Chapter 4 is concerned with the actual development of general mapping equations for the

perspective projection. These equations are developed utilizing a photogrammetric approach, an approach which to the author's knowledge is novel to the study of map projections. Equations are first derived using the sphere as a datum surface in order both that the validity of the equations may be checked by comparison with those equations derived earlier and to facilitate for the reader the understanding of later derivations. In an analogous manner equations are then derived using the ellipsoid as a datum surface. It is shown that the mapping equations derived for an ellipsoidal datum surface are truly General Perspective Projection Mapping Equations, suitable for both spherical and ellipsoidal datum surfaces.

Chapter 5 briefly discusses an empirical method to determine the distortions inherent in the perspective projection of a latitudelongitude grid of a datum surface onto a projection plane. Chapter 6 illustrates examples of six types of perspective projections by means of tables or grids containing both X-Y plane coordinates and distortions. The coordinates and distortions are calculated for the intersection points of latitude and longitude lines spaced ten degrees apart. It is believed that the examples included in Chapter 6 both aid in the vizualization of perspective projections and at least partially validate the equations derived in Chapter 4. The computer program used to produce the examples of Chapter ℓ and a brief explanation of the computer program are included in the Appendix.

2. A CONVENTIONAL APPROACH TO PERSPECTIVE MAP PROJECTIONS

Three of the more common perspective map projections are the Gnomonic Projection, the Stereographic Projection, and the Orthographic Projection. The mapping equations for these three projections are briefly derived in this chapter for two main reasons. First, the derivations will illustrate what the author chooses to call a conventional approach to the derivation of perspective mapping equations, similar to the approach used in [4]. Second, the equations derived in this chapter will be a basis of comparison for those equations derived later.

2.1 The Gnomenic Projection

The Gnomonic Projection is developed by placing a projection center at the center of a sphere and projecting this sphere onto a projection plane tangent to it. Figure 2 represents a sphere with a radius R and a center at C, which in the Gnomonic Projection is also the projection center. The projection plane AB is made tangent to the sphere at O' and this point is the image center of the projection. O' is located at a latitude ϕ_c on the sphere. P is an arbitrary point located on the sphere at a latitude ϕ and at a longitude difference of λ from O'. P' is the projection of P on the projection plane.

Figure 2 illustrates the following:

 $CO^{\dagger} = CP = R$ Angle O'NP = λ



Figure 2



Fig.re 3



Figure 4

Angle NO'P = 90 - B No' = 90 - + Arc = 90 - 1 NP Arc

Figure 3 is drawn in the plane of the triangle CO'P and illustrates the projection of the arc O'P onto the projection plane AB. From Figure 3, it is evident that

(1)O'P'=R tan g

To reduce equation (1) to rectangular coordinates on the projection plane, the coordinate system illustrated in Figure 4 is developed. In this coordinate system, O'Y' represents the projection of the meridian through O' and O'X' represents the projection of the great circle through O' which is perpendicular to the meridian through O'.

From Figure 4, the following is derived:

 $X' = P' = O'P' \cos B = R \tan q \cos B = \frac{R \sin q \cos B}{\cos q}$ (2) $Y' = EP' = O'P' \sin B = R \tan q \sin B = \frac{R \sin q \sin B}{\cos q}$

Utilizing the properties of the spherical triangle in Figure 1, the following may be derived by the Law of Sines:

$$\frac{\sin \lambda}{\sin q} = \frac{\sin (90 - B)}{\sin (90 - \phi)} = \frac{\cos B}{\cos \phi}$$

and therefore

(3)

(4) sin q cos B= sin λ cos §

By the Law of Cosines, the following is derived:

(5)	$\sin q \sin B = \cos \phi \sin \phi - \sin \phi \cos \phi \cos \lambda$
(6)	$\cos q = \sin \phi$, $\sin \phi + \cos \phi$, $\cos \phi \cos \lambda$

By substituting equations (4), (5), and (6) into equations (2) and (3), the mapping equations for the Gnomonic Projection are obtained:

(7)
$$X^{*} = \frac{R \cos \phi \sin \lambda}{\sin \phi \sin \phi + \cos \phi \cos \phi \cos \lambda}$$

(8)
$$Y^{*} = \frac{R (\cos \phi \sin \phi - \sin \phi \cos \phi \cos \lambda)}{\sin \phi \sin \phi + \cos \phi \cos \phi \cos \lambda}$$

2.2 The Stereographic Projection

The Stereographic Projection is developed by placing a projection center at a point on the sphere which is diametrically epposite the point at which the projection plane is tangent to the sphere. The mapping equations for the Stereographic Projection are developed in an analogous manner to the development of the mapping equations for the Gnomonic Projection. Figure 5 represents a sphere with a radius R and a center at 0. The projection center is located at C and the projection plane AB is tangent to the sphere at 0'. 0' is also the image center of the projection. P is an arbitrary point located on the sphere at a latitude § and at a longitude difference of λ from 0'. P' is the projection of P on the projection plane.

Figure 5 illustrates the following:

OC = OO' = RAngle O'NP= λ Angle NO'P= 90 - B







Figure 6





Arc NO' = 90 - ϕ_c Arc NP = 90 - ϕ

Figure 6 is drawn in the plane of the triangle CO'P and illustrates the projection of the arc O'P onto the projection plane. It is evident from Figure 6 that

(9)
$$0'P' = 2 R \tan \frac{1}{2}$$

(10)

To reduce equation (9) to rectangular coordinates on the projection plane, the coordinate system illustrated in Figure 7 is developed. In this coordinate system, O'Y' represents the projection of the meridian through O' and O'X' represents the projection of the great circle through O' which is perpendicular to the meridian through O'.

From Figure 7, the following is derived:

X' = F'P' = O'P' cos B = 2 R tan $\frac{q}{2}$ cos B = $\frac{2 R \sin q \cos B}{1 + \cos q}$

(11) $Y' = \mathbf{E'P'} = \mathbf{O'P'} \sin \mathbf{B} = 2 \operatorname{R} \tan \frac{\mathbf{q}}{2} \sin \mathbf{B}$ $= \frac{2 \operatorname{R} \sin \mathbf{q} \sin \mathbf{B}}{1 + \cos \mathbf{q}}$

Utilizing the spherical triangle formed in Figure 5, equations (4), (5), and (6) can again be derived. By substituting equations (4), (5), and (6) into equations (10^h and (11), the mapping equations for the Stereographic Projection are obtained:

(12)
$$X' = \frac{2 R \cos \phi \sin \lambda}{1 + \sin \phi \sin \phi + \cos \phi \cos \phi \cos \lambda}$$

(13)
$$Y' = \frac{2 \operatorname{P} (\cos \phi_{c} \sin \phi - \sin \phi_{c} \cos \phi \cos \lambda)}{1 + \sin \phi_{c} \sin \phi + \cos \phi_{c} \cos \phi \cos \lambda}$$

2.3 The Orthographic Projection

The Orthographic Projection is developed by placing a projection center at infinity and by projecting the datum sphere onto a projection plane perpendicular to the projection rays. All projection rays are parallel to each other and perpendicular to the projection plane. The mapping equations for the Orthographic Projection can be developed in analogous manner to the development of the mapping equations in Section 2.1 and Section 2.2. Figure 8 represents a sphere with a radius R and a center at 0. The projection center is located at infinity in the direction indicated by the figure. The projection plane is perpendicular to the projecting rays and tangent to the sphere at 0', with 0' also being the image center of the projection. P is an arbitrary point located on the sphere at a latitude § and at a longitude difference of λ from 0'. P' is the projection of P on the projection plane.

Figure 8 illustrates the following:

OO' = OP = R Angle O'NP = λ Angle NO'P = 90 - B Arc NO' = 90 - ϕ_c Arc NP = 90 - ϕ

Figure 9 is drawn in the plane of triangle 00'P and illustrates the projection of the arc 0'P onto the projection plane.



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Figure 8









It is evident from Figure 9 that

(14) $0'P' = R \sin q$

To reduce equation (14) to rectangular coordinates on the projection plane, the coordinate system illustrated in Figure 10 is developed. In this coordinate system, 0'Y' represents the projection of the meridian through 0' and 0'X' represents the projection of the great circle through 0' which is perpendicular to the meridian through 0'.

From Figure 10, the following is derived:

- (15) $X' = FP' = O'P' \cos B = R \sin q \cos B$
- (16) $Y' = EP' = O'P' \sin P = R \sin'q \sin B$

Utilizing the spherical triangle formed in Figure 8, equations (4) and (5) can again be derived. By substituting equations (4) and (5) into equations (15) and (16), the mapping equations for the Orthographic Projection are obtained:

- (17) $X' = R \cos \phi \sin \lambda$
- (18) $Y' = R (\cos \phi \sin \phi \sin \phi \cos \phi \cos \lambda)$

3. A DESCRIPTIVE GEOMETRY APPROACH TO PERSPECTIVE MAP PROJECTIONS

The three perspective map projections just discussed, the Gnomonic, the Stereographic, and the Orthographic, were developed by placing the projection center at a particular location in reference to the datum sphere. In this chapter the projection center will be placed at an arbitrary distance above the surface of the datum sphere and perspective mapping equations will be developed for this spherical datum surface. Since the projection center will be located at an arbitrary distance above the datum surface. it is now pessible to better vizualize the physical significance of the perspective projection by comparing it to an aerial photograph. As was stated earlier, a photograph is actually a type of perspective projection. Thus, the perspective mapping equations derived in this chapter would enable the plotting of grid lines on an ideal vertical photograph taken at a particular distance above a datum sphere. Naturally, this can not be accomplished with an actual acrial photograph of the earth due to the fact that the earth is not a sphere nor a simple geometric figure of any type. Also, due to numerous distortions inherent to photography, aerial photographs are not ideal vertical projections. However, the comparison between perspective projections and vertical aerial photographs is still useful in visualizing the derivations included in this and the following chapter.



Figure 11 illustrates the descriptive geometry approach to perspective map projections presented in [12]. In this figure the lower circle represents a transverse or front view of the datum sphere, with the plane of the X axis defining the plane of the equator and the Y axis defining the polar axis. The upper circle in Figure 11 represents the polar or top view of the datum sphere, with N denoting the position of the pole. The small circle on the right side of the figure represents the perspective view of the datum sphere that would be obtained by placing a projection center at C_p . In this chapter mapping equations will be derived which allow the transformation of coordinates of an arbitrary point from a three dimensional latitude-longitude system, as illustrated in the top and front views of Figure 11, to a plane X'-Y' system, as illustrated on the projection plane in the perspective view of Figure 11.

In Figure 11, C represents a projection center located at a latitude ϕ_{C} , at a longitude λ_{c} , and at a distance h above a datum sphere of radius R. A cone of projection rays emanating from C_{F} is tangent to the sphere at A and B and creates right angles $0_{F}AC_{F}$ and $0_{F}BC_{F}$. The complete intersection of the projection cone and the sphere is a circle whose trace AB is shown in the front view. This circular intersection as seen from the projection center C_{F} is illustrated in the perspective view. This circular area can be vizualized as that portion of the datum sphere which could be seen if an observer were located at C_{F} . In this derivation the AB

plane will be used as the projection plane and all points on the visible portion of the sphere will be projected onto this plane.

In the front view of Figure 11, let P_{p} be an arbitrary point located at a latitude ϕ and at a longitude λ on the portion of the sphere visible from $\boldsymbol{C}_{_{\!\!\boldsymbol{\mathrm{F}}}}$. By definition, λ equals the difference in longitude between the arbitrary point P and the projection center C. P_m represents the position of the point P in the top view. P_{μ} is projected along the projection ray $C_{\mu}P_{\mu}$ until the ray intersects the projection plane d at P_{F} '. P_{F} ' is then the projected image of P_{μ} on the projection plane. P_{μ}' represents the position of this point in the top view. It is seen that the distance DP, ' is then the Y' coordinate of the point P' on the projection plane. In the top view, the distance $P'P'_{T}$ is the X' coordinate of the point P' on the projection plane and this distance, when transferred to the perspective view, locates the point P'. P', with an X' value of $P_T'P_T'$ and a Y' value of DP_F' , is thus the projection of point P on the projection plane in the perspective view.

The point P has now been transferred to the projection plane, and it only remains necessary to resolve the ordinate and abscissa values of the point into terms involving the original given parameters. This is accomplished in the following paragraphs.

The angle $C_{\mathbf{F}}^{AO}$ is designated θ and it is evident that

(19)
$$\cos \theta = \frac{AO}{O_{\rm F}C_{\rm F}} = \frac{R}{R+h}$$

and also that

(20) $O_{\rm m}D = R \cos \theta$

The equation of the line AB may now be written as

(21) $X \cos \phi + Y \sin \phi - R \cos \phi = 0$ and the equation of the line $O_{F} \cos \phi$ may be written as

(22) $X \sin \phi - Y \cos \phi = 0$

Next, the two perpendicular distances LP and P M from $_{F}$ point P_F to lines AB and O C respectively must be determined. This is done by using well known geometric formulas for finding the perpendicular distance from a point to a line. The resulting equations are

(23)	$LP_{F} = R (\cos \phi \cos \phi \cos \lambda + \sin \phi \sin \phi - \cos \phi)$
(24)	$MP_{F} = -R (\sin \phi \cos \phi \cos \lambda - \cos \phi \sin \phi)$

Considering the X'-Y' coordinate system of the projection plane in the perspective view, it was shown previously that the ordinate of P' in this coordinate system was equal to DP_F' . Utilizing similar triangles in the front view the following is obtained:

$$DP_{F}' = DC_{F} \frac{MP_{F}}{MC_{F}} = \frac{DC_{F} \cdot MP_{F}}{DC_{F} - LP_{F}}$$

and also from the front view the following is derived:

 $DC_{\mu} = AD \tan \theta = R \sin \theta \tan \theta$

A combination of the above equations yields the Y' cordinate of P' in the X'-Y' coordinate system of the projection plane.

$$Y' = DP_{F}'$$

$$\frac{(R \sin \theta \tan \theta) R (\cos \phi_{C} \sin \phi - \sin \phi_{C} \cos \phi \cos \lambda)}{C}$$

$$Y' = \frac{(R \sin \theta \tan \theta - R(\cos \phi \cos \phi \cos \lambda + \sin \phi \sin \phi - \cos \phi)}{C}$$

(25)
$$R \sin^{2} \theta \left(\cos \frac{1}{2} \sin \frac{1}{2} - \sin \frac{1}{2} \cos \frac{1}{2} \sin \frac{1}{2} \right)$$

A X' coordinate corresponding to the Y' coordinate calculated by equation (25) may now be derived. Considering Figure 11 again, the following proportions are obtained:

$$\frac{\mathbf{P}_{T}^{T}\mathbf{P}_{T}^{T}}{\mathbf{P}_{T}^{T}\mathbf{P}_{T}^{T}} = \frac{\mathbf{P}_{T}^{T}\mathbf{C}}{\mathbf{P}_{T}^{T}\mathbf{T}} = \frac{\mathbf{P}_{T}^{T}\mathbf{C}}{\mathbf{P}_{T}^{T}\mathbf{P}_{T}^{T}} = \frac{\mathbf{P}_{T}^{T}\mathbf{C}}{\mathbf{P}_{T}^{T}\mathbf{P}_{T}$$

It is also evident from Figure 11 that

$$P_{T}''P_{T} = R \cos \phi \sin \lambda$$
$$DP_{F}' = Y'$$

The abscissa X' of the point P' on the projection plane was previously shown to be equal to P_T ' P_T ' and thus

$$X' = P_T'P_T' = \frac{P_T'P_P}{T_T} \frac{DP'}{MP_F}$$

$$X^{*} = \frac{R}{-R} \left(\sin \phi \cos \phi \cos \lambda + \sin \phi \sin \phi \right)$$

(26)
$$X^{*} = \frac{R \sin \theta \cos \theta \sin \lambda}{1 - \cos \theta (\cos \theta \cos \theta \cos \lambda + \sin \theta \sin \theta)}$$

Summarizing, equations (25) and (26) are perspective

projection mapping equations which enable an arbitrary point to be transferred from a three dimensional latitude-longitude coordinate system of a datum sphere to a plane X'-Y' coordinate system of a projection plane.

4. A PHOTOGRAMMETRIC APPROACH TO PERSPECTIVE MAP PROJECTIONS

Equations (25) and (26), developed by a descriptive geometry method in Chapter 3, are mapping equations suitable for a spherical datum surface. It is not apparent to the author how these equations can be modified to make them applicable to an ellipsoidal datum surface. It is also not immediately apparent how these equations can be used for all possible locations of the projection center. In this chapter mapping equations will be derived that can be utilized regardless of the location of the projection center and that can be used both on spherical and ellipsoidal datum surfaces.

Since a perspective projection is directly comparable to a photograph, the author chose to derive the desired mapping equations through a photogrammetric approach. Section 4.1 deals with the derivation of equations based on a spherical datum surface, while Section 4.2 deals with similar equations based on an ellipsoidal datum surface. Since a sphere is only a special case of an ellipsoid, mapping equations derived for the sphere are only special cases of those derived for the ellipsoid. The author considers the spherical case worthy of separate discussion based on the belief that the sphere is a logical intermediate step before progressing to the more complicated ellipsoid. The mapping equations derived for the sphere may also be compared with previously derived equations as a check on the validity of the general method being utilized in this chapter.

4.1 A Spherical Datum Surface

4.11 The Mapping Equations

Figure 12 represents a spherical datum surface with a radius R and a conventional three dimensional X-Y-Z coordinate system. Point C depicts the projection center and is located at a latitude \bullet_c , at a longitude λ_c , and at a height above the datum sphere of h. Point P represents an arbitrary point on the datum surface and is located at a latitude \bullet and at a longitude λ . In the following derivation λ will equal the difference in longitude between the point P and the projection center C.

The space rectangular coordinates of point C are obtained from Figure 12.

- (27) $Y_{c} = (R + h) \cos \phi_{c}$
- (28) $X_{0} = 0$

Likewise, the coordinates of point P are obtained from Figure 12.

- (30) $Y_{p} = R \cos \phi \cos \lambda$
- (31) $X = R \cos \phi \sin \lambda$
- (32) Z = R sin +

As an aid in vizualizing the remainder of the derivation, point C may be compared to a camera lens and CO, the projection axis, is comparable to a camera axis. The projection plane AB, or mapping plane, may be vizualized as a photographic plate which is perpendicular to the camera axis and located at a distance f



Figure 12





behind the lens. It is seen that f is comparable to the focal length of a camera and, thus, the scale of the projection is dependent on f. Actually, the ratic of f to h determines the scale of the projection; and it is apparent that a full scale projection will result when f is equal to h. It will be necessary later in the derivation to have firm definitions of both h and f as regards to sign convention. The signs of h and f are defined as positive when they are above, or to the outside of, that portion of the sphere to be projected and negative if to the inside of the sphere.

Figure 12 illustrates the following:

$$CS = h$$

 $CC' = f$

OS = OP = R

The next step in the derivation is to rotate the original Z axis in the Z-Y plane until the Z axis coincides with the projection axis OC, as is illustrated in Figure 13. This rotation in the Z-Y plane creates a new X'-Y'-Z' coordinate system. It is evident that this type of rotation will not alter the X coordinate of points from their values as calculated in the original coordinate system.

Figure 13 illustrates the following:

PL Y_

PU- Z

 $PK = Y_{p}^{*}$ $PM = Z_{p}^{*}$ $NO = Y_{p} \sin \phi_{c}$ $UT = Z_{p} \cos \phi_{c}$ $UN = Y_{p} \cos \phi_{c}$ $PT = Z_{p} \sin \phi_{c}$

Considering Figure 13, the space rectangular coordinates of point C in the new X'-Y'-Z' coordinate system are obtained.

- (33) $X_{c}' = 0$
- (34) $Y_{c}' = 0$
- (35) $Z_{c} = R + h$

Likewise, the new coordinates of point P are obtained.

- (36) $Y_p' = Y_p \sin \phi Z_p \cos \phi$
- (37) $X_{p}' = X_{p}$
- (38) $Z_{p}' = Y_{p} \cos \phi_{c} + Z_{p} \sin \phi_{c}$

Substituting equations (30), (31), and (32) into equations (36), (37), and (38), the X'-Y'-Z' coordinates of point F in terms of the original parameters are obtained.

(39) $Y_p' = R \sin \phi_c \cos \phi \cos \lambda - R \cos \phi_c \sin \phi$

(40)
$$X_n = R \cos \phi \sin \lambda$$

(41)
$$Z_p = R \cos \phi \cos \phi \cos \lambda + R \sin \phi \sin \phi$$

The equation of the projection plane AB which is perpendicular to the projection axis and hence now perpendicular to the Z' axis is clearly

(42)
$$Z^* = R + h + f$$

The equation of the projection ray from P that passes through C and intersects the projection plane at P' can be written as

(43)
$$\frac{X' - X_{p'}}{X_{c'} - X_{p'}} = \frac{Y' - Y_{p'}}{Y_{c'} - Y_{p'}} = \frac{Z' - Z_{p'}}{Z_{c'} - Z_{p'}}$$

Equation (43) is the equation of the line in space along which P is projected onto the projection plane. The intersection of this line and the projection plane, as given by equation (42), is the location of P', the projection of P on the projection plane. Therefore, the simultaneous solution of equations (42) and (43) will yield the desired X'-Y' coordinates of the projected point.

The equation for X' is derived in the following manner:

From equation (43)

$$\frac{X' - X_{p'}}{X_{c'} - X_{p'}} = \frac{Z' - Z_{p'}}{Z_{c'} - Z_{p'}}$$

(44)
$$X_{i} = \frac{(Z_{i} - Z_{p}) (X_{c} - X_{p})}{(Z_{c} - Z_{p})} + X_{p}$$

Substituting equation (33) into equation (44)

(45)
$$X' = \frac{X_{p'} (Z_{c'} - Z')}{Z_{c'} - Z_{p'}}$$

Substituting equations (35), (40), (41) and (42) into equation (45)

$$X' = \frac{-f R \cos \phi \sin \lambda}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

Remembering that a photogrammetric approach was utilized in this derivation, it will be realized that the X' coordinate has suffered a reversal of sign during the process, presenting a reversed image of the original datum surface. In order to compensate for this situation the sign of the above equation must be reversed, and therefore

(46)
$$X' = \frac{\int R \cos \phi \sin \lambda}{R (1 - \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

The equation for Y' is derived in a manner analogous to the derivation of the equation for X' as follows:

From equation (43)

$$\frac{Y' - Y_{p'}}{Y_{c'} - Y_{p'}} = \frac{Z' - Z_{p'}}{Z_{c'} - Z_{p'}}$$

(47) $Y' = \frac{(Z' - Z_{p'}) (Y_{c'} - Y_{p'})}{(Z_{c'} - Z_{p'})} + Y_{p'}$

Substituting equation (34) into equation (47)

(48)
$$Y = \frac{Y_{p} \cdot (Z_{c} \cdot - Z_{r})}{Z_{c} \cdot - Z_{p}}$$

Substituting equations (35), (39), (41), and (42) into equation (48)

(49)
$$f = \frac{f R (\cos \phi_c \sin \phi - \sin \phi_c \cos \phi \cos \lambda)}{R (1 - \cos \phi_c \cos \phi \cos \lambda - \sin \phi_c \sin \phi) + h}$$

In summary, equations (46) and (49) are perspective projection mapping equations derived for a spherical datum surface. These equations allow the calculation of plane X'-Y' coordinates of a point P' on a projection plane located at a distance f from the projection center. Initially, point P had been located on the datum sphere by spherical $\frac{1}{2}-\lambda$ coordinates and C by both spherical $\frac{1}{2}-\lambda_c$ coordinates and a distance h above the datum surface.

4.12 A Comparison Of Mapping Equations

Two sets of mapping equations have now been developed for the case of a projection center being placed at an arbitrary distance above a spherical datum surface. If both sets of equations are valid, they must prove to be equal. A brief comparison of equations (25) and (26), derived by the descriptive geometry approach of Chapter 3, with equations (46) and (49), just derived, illustrates a great similarity in the equations. The differences in the equations are due to the fact that while equations (46) and (49) contain the parameters h and f, equations

(25) and (26) contain the comparable parameter **e**. In effect, the parameter **e** fixes a f for a particular h. As explained earlier, however, since f acts only as a scale factor, its value is not of real significance.

Considering Figure 11 and recalling that AB was the projection plane, it is evident that DC, being the distance between the projection center and the projection plane, is the parameter f introduced in Section 4.11. From Figure 11, the following expression for the parameter f may be derived:

(50)

$$f = DC_F = O_F C_F - O_F D$$

$$= R + h - R \cos \theta$$

$$R + h - \frac{R^2}{R + h}$$

Utilizing the definition of the parameter θ as given by equation (19) and the expression for f as given by equation (50), the perspective projection mapping equations derived by the descriptive geometry method of Chapter 3 will be proved equal to the mapping equations derived by the photogrammetric method of Section 4.11. Equation (26), derived in Chapter 3, may be transformed into equation (46), derived in Section 4.11, as follows:

Rewriting equation (26)

$$\frac{R \sin^2 \theta \cos \phi \sin \lambda}{X^* = \frac{1 - \cos \theta (\cos \phi \cos \lambda + \sin \phi \sin \theta)}{Substituting (1 - \cos^2 \theta) \text{ for } \sin^2 \theta \text{ and equation (19)}}$$
into the above equation
$$\begin{array}{c} \left[R + h - \frac{R}{R + h} \right] R \cos \phi \sin \lambda \\ X' = \frac{R}{R \left(1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi \right) + h} \\ \end{array}$$

Substituting equation (50) into the above equation

(51)
$$X' = \frac{f R \cos \phi \sin \lambda}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

In a like manner, equation (25), derived in Chapter 3, may be transformed into equation (49), derived in Section 4.11, as follows:

Rewriting equation (25)

$$R \sin^{2} \theta (\cos \phi \sin \phi - \sin \phi \cos \phi \cos \lambda)$$

$$Y' = \frac{1 - \cos \theta (\cos \phi \cos \phi \cos \lambda + \sin \phi \sin \phi)}{c}$$

Substituting $(1 - \cos^2 \theta)$ for $\sin^2 \theta$ and equation (19) into the above equation

$$(R + h - \frac{R^2}{R + h}) R (\cos \phi \sin \phi - \sin \phi \cos \phi \cos \lambda)$$

$$Y' = \frac{R + h}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

Substituting equation (50) into the above equation

(52)
$$f R (\cos \phi_c \sin \phi - \sin \phi_c \cos \phi \cos \lambda)$$
$$Y' = \frac{R (1 - \cos \phi_c \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}{R (1 - \cos \phi_c \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

Equations (51) and (52) are seen to be identical to equations (46) and (49). Thus, the perspective projection mapping equations derived by the descriptive geometry method are, in effect, equal to the equations derived by the photogrammetric method. This equality is a partial proof of the validity of the derivations and the derived equations of Section 4.11.

4.13 The Gnomonic Projection

Three special cases of the perspective projection were discussed in Chapter 2, and three sets of mapping equations were developed for these special cases. Since the perspective projection mapping equations, equations (46) and (49), are applicable to all perspective projections of a spherical datum surface, these equations must be applicable also to the above mentioned special cases. This fact will be proved in this and the two succeeding sections.

As was illustrated in Section 2.1, the Gnomonic Projection is a special case of the perspective projection in which the projection center is located at the center of the sphere. By reviewing Figure 2 and by recalling the definitions given earlier for h and f, the values for h and f in the Gnomonic Projection are seen to be -R and -R respectively. Substituting these values into the perspective projection mapping equations, equations (46) and (49), yields the following:

$$X^{*} = \frac{-R R \cos \phi \sin \lambda}{R (1 - \cos \phi_{c} \cos \phi \cos \lambda - \sin \phi_{c} \sin \phi) - R}$$

$$= \frac{R \cos \phi \sin \lambda}{\cos \phi_{c} \cos \phi \cos \lambda + \sin \phi_{c} \sin \phi}$$

$$Y^{*} = \frac{-R R (\cos \phi_{c} \sin \phi - \sin \phi_{c} \cos \phi \cos \lambda)}{R (1 - \cos \phi_{c} \cos \phi \cos \lambda - \sin \phi_{c} \sin \phi) - R}$$

$$(54) \qquad = \frac{R (\cos \phi_{c} \sin \phi - \sin \phi_{c} \cos \phi \cos \lambda)}{\cos \phi_{c} \cos \phi \cos \lambda + \sin \phi_{c} \sin \phi}$$

Equations (53) and (54) are identical to equations (7) and (8) developed for the Gnomonic Projection in Section 2.1. Thus, the mapping equations for the Gnomonic Projection have been proved to be special cases of the perspective projection mapping equations.

4.14 The Stereographic Projection

The Sterographic Projection was the second special case of the perspective projection discussed in Chapter 2. Considering Figure 5, the values for h and f in the Stereographic Projection are seen to be -2R and -2R respectively. Substituting these values into the perspective projection mapping equations, equations (46) and (49), yields the following:

$$X' = \frac{-2R R \cos \phi \sin \lambda}{R (1 - \cos \phi_c \cos \phi \cos \lambda - \sin \phi_c \sin \phi) - 2R}$$

$$= \frac{2R \cos \phi \sin \lambda}{1 + \cos \phi_c \cos \phi \cos \lambda + \sin \phi_c \sin \phi}$$

$$Y' = \frac{-2R R (\cos \phi_c \sin \phi - \sin \phi_c \cos \phi \cos \lambda)}{R (1 - \cos \phi_c \cos \phi \cos \lambda + \sin \phi_c \sin \phi) - 2R}$$

$$= \frac{2R (\cos \phi_c \sin \phi - \sin \phi_c \cos \phi \cos \lambda)}{1 + \cos \phi_c \cos \phi \cos \lambda + \sin \phi_c \sin \phi}$$
(56)
$$= \frac{2R (\cos \phi_c \sin \phi - \sin \phi_c \cos \phi \cos \lambda)}{1 + \cos \phi_c \cos \phi \cos \lambda + \sin \phi_c \sin \phi}$$

Equations (55) and (56) are identical to equations (12) and (13) developed for the Stereographic Projection in Section 2.2. Thus, the equations for the Stereographic Projection have been proved to be special cases of the perspective projection mapping equations.

4.15 The Orthographic Projection

The third special case of the perspective projection discussed in Chapter 2 was the Orthographic Projection. In order to convert the perspective projection mapping equations for use in an Orthographic Projection, a relationship must be established between f and h. It was discussed earlier that f has the effect of a scale factor, and from elementary projection principles it was seen that a full scale projection results if f equals h. Therefore, in developing an Orthographic Projection, f may be set equal to h. Making this substitution in the perspective projection mapping equations, equations (46) and (49), yields the following:

$$X' = \frac{h R \cos \phi \sin \lambda}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi) + h}$$

h R (cos
$$\phi_c$$
 sin ϕ_c - sin ϕ_c cos ϕ cos λ)
Y'= R (1 - cos ϕ_c cos ϕ_c cos λ - sin ϕ_c sin ϕ) + h

The numerators and denominators of the above equations are now divided by h, producing:

$$X' = \frac{\frac{R \cos \phi \sin \lambda}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi)}}{h} + 1$$

$$Y' = \frac{\frac{R (\cos \phi \sin \phi - \sin \phi \cos \lambda - \sin \phi \sin \phi)}{R (1 - \cos \phi \cos \phi \cos \lambda - \sin \phi \sin \phi)}}{h} + 1$$

The Orthographic Projection is based on the projection center being located at infinity. Substituting infinity for h in the above equations yields:

- (57) $X^{*} = R \cos \phi \sin \lambda$
- (58) $Y' = R (\cos \phi_c \sin \phi \sin \phi_c \cos \phi \cos \lambda)$

Equations (57) and (58) are identical to equations (17) and (18) developed for the Orthographic Projection in Section 2.3. Thus, the equations for the Orthographic Projection have also been proved to be special cases of the perspective projection mapping equations.

4.2 An Ellipsoidal Datum Surface 4.21 The General Mapping Equations

Section 4.1 dealt with perspective projection mapping equations for a spherical datum surface; however, the sphere is actually a rather poor approximation for the shape of the earth. A better approximation for the shape of the earth is an ellipsoid of revolution, and this section deals with the derivation of General Perspective Projection Mapping Equations for ellipsoidal datum surfaces. In the remainder of this paper, an ellipsoid of revolution will be implied by the term ellipsoid. The parameters used to define the ellipsoid will be a, the major semi-diameter, and e^2 , the square of the eccentricity. It will be seen that the derivation method to be used in this section is analogous to the method employed in Section 4.1L.

Figure 14 illustrates the datum surface which is an ellipsoid of revolution with the Z axis being the axis of rotation. Point C depicts the projection center and is located at a geodetic latitude





 φ_c , at a longitude λ_c , and at a height above the datum surface of h. Point P represents an arbitrary point on the datum surface and is locited at a geodetic latitude φ and at a longitude λ . As before, λ will equal the difference in longitude between the point P and the projection center. N_c and N_p are the radii of curvature in the prime vertical at C and P respectively.

Figure 14 illustrates the following:

CS = h CC' = f $KP = N_P$ $O'S = N_0$

The space rectangular coordinates of point C are obtained from Figure 14.

(59) $X_c = 0$

(60)
$$Y_c = (N_c + h) \cos \varphi_c$$

(61) $Z_c = [N_c (1 - e^2) + h] \sin \varphi_c$

Likewise, the coordinates of point P are obtained from Figure 14.

- (62) $X = N_p \cos \varphi \sin \lambda$
- (63) $Y_{\rm p} = N_{\rm p} \cos \varphi \cos \lambda$
- (64) $Z = N (1 e^2) \sin \varphi$

Similar to the derivation utilizing a spherical datum in Section 4.11, the Z axis is now rotated, and in this case transposed, in the Z-Y plane until the Z axis coincides with the projection axis CO'. The new X'-Y'-Z' coordinate system is illustrated in Figure 15. The values of X coordinates of points are not changed by the rotation due to the rotation being accomplished in the Z-Y plane.

Figure 15 illustrates the following:

PH = Y_p PU = Z_p PL = Y_p ' PM = Z_p ' JU'= $Y_p \sin \varphi_c$ TK = 00' cos φ_c UR = $Z_p \cos \varphi_c$ JT = $Y_p \cos \varphi_c$ UK = 00' sin φ_c RP = $Z_p \sin \varphi_c$

The distance OO' which the Z' axis has been transposed along the Z axis is computed as follows:

(65)

$$OO'= (N_c + h) \sin \varphi_c - Z_c$$

$$= (N_c + h) \sin \varphi_c - [N_c (1 - e^2) + h] \sin \varphi_c$$

$$= N_c e^2 \sin \varphi_c$$

The space rectangular coordinates of C in the new X'-Y'-Z' coordinate system are obtained from Figure 15.

- (65a) $X_{c}' = 0$
- (66) Y · = 0
- (67) Z' = N + h

Likewise, the new coordinates of point P are obtained.

- $(68) \qquad \qquad X_{p'} = X_{p}$
- (69) $Y' = Y \sin \varphi (Z + 00') \cos \varphi$
- (70) $Z' = Y \cos \varphi + (Z + 00') \sin \varphi$ p p c p c c

Substituting equations (62), (63), (64), and (65) into equations (68), (69), and (70), the coordinates of point P are obtained in terms of the original parameters.

(71) $X = N \cos \varphi \sin \lambda$ p p

Y'= N sin φ cos φ cos λ - N (1 - e²) cos φ sin φ

(72) $-N_c e^2 \sin \varphi \cos \varphi_c$

(73) $Z_{p}^{*} = N_{p} \cos \varphi_{c} \cos \varphi \cos \lambda + W_{p} (1 - e^{2}) \sin \varphi_{c} \sin \varphi$ $+ N_{c} e^{2} \sin^{2} \varphi_{c}$

The equation of the projection plane AB which is perpendicular to the projection axis and hence now perpendicular to the Z' axis is now formulated as

 $(74) \qquad Z'=N_c+h+f$

The equation of the projection ray from P that passes through C and intersects the projection plane at P' is now written as

(75)
$$\frac{X' - X_{p'}}{X_{c'} - X_{p'}} = \frac{Y' - Y_{p'}}{Y_{c'} - Y_{p'}} = \frac{Z' - Z_{p'}}{Z_{c'} - Z_{p'}}$$

Similar to the derivation in Section 4.11, the simultaneous solution of equations (75) and (74) will yield the desired X'-Y' coordinates of the projected point on the projection plane.

The equation for X' is derived in the following manner:

From equation (75)

(76)
$$X' = \frac{(Z' - Z')(X' - X')}{(Z' - Z')} + X'$$

Substituting equation (65a) into equation (76)

(77)
$$X' = \frac{X_{p'} (Z_{c'} - Z')}{Z_{c'} - Z_{p'}}$$

Substituting equations (67), (71), (73), and (74) into equation (77)

X'=
$$\frac{-f N_p \cos \varphi \sin \lambda}{N_c (1 - e^2 \sin^2 \varphi_c) - N_p [\cos \varphi_c \cos \varphi \cos \lambda]}$$

+ $(1 - e^2) \sin \varphi \sin \varphi + h$

As in Section 4.11, the sign of the above equation must be reversed to compensate for the inversion due to the photogrammetric derivation, and therefore

f N cos $\varphi \sin \lambda$

$$X' = \frac{p}{N_c (1 - e^2 \sin^2 \varphi_c) - N_p [\cos \varphi_c \cos \varphi \cos \lambda]}$$

(78) $+(1-e^2)\sin\varphi_c\sin\varphi]+h$

The equation for Y' is derived in a manner analogous to the derivation of the equation for X' as follows:

From equation (75)

(79)
$$Y_{b} = \frac{(Z' - Z') (Y' - Y')}{(Z' - Z')} + Y''$$

Substituting equation (66) into equation (79)

(80)
$$Y' = \frac{Y' (Z_c' - Z')}{Z_c' - Z_p'}$$

Substituting equations (67), (72), (73), and (74) into equation (80)

$$Y_{i} = \frac{f \left[N_{c} e^{2} \sin \varphi \cos \varphi + N_{p} \left[\left(1 - e^{2}\right) \cos \varphi \sin \varphi\right]}{N_{c} \left(1 - e^{2} \sin^{2} \varphi_{c}\right) - N_{p} \left[\cos \varphi_{c} \cos \varphi \cos \lambda\right]}$$

$$\left(01\right) \qquad \frac{-\sin \varphi_{c} \cos \varphi \cos \lambda]}{+\left(1 - e^{2}\right) \sin \varphi_{c} \sin \varphi] + h}$$

In summary,equations (75) and (81) are General Perspective Projection Mapping Equations derived for an ellipsoidal datum surface. These equations allow the calculation of plane X'-Y' coordinates of a point P' on a projection plane located at a distance f from the projection center. Initially, point P had been located on the datum ellipsoid by geodetic $\varphi - \lambda$ coordinates and C by both geodetic $\varphi_{-\lambda}$ coordinates and a distance h above the datum surface.

4.22 A Comparison of Mapping Equations For The Ellipsoid And For The Sphere

A sphere is actually a special case of an ellipsoid in which the ellipsoid flattening is equal to zero. Since equations (78) and (81) were derived as General Perspective Projection Mapping Equations for an ellipsoidal datum surface, these equations should prove to be suitable for a spherical datum surface. Therefore, equations (46) and (49), derived for a spherical datum surface, should prove to be special cases of equations (78) and (81). This is illustrated as follows:

Rewriting equations (78) and (81)

$$X = \frac{f N_p \cos \varphi \sin \lambda}{N_c (1 - e^2 \sin^2 \varphi_c) - N_p [\cos \varphi_c \cos \varphi \cos \lambda]}$$

$$\frac{f (1 - e^2) \sin \varphi_c \sin \varphi] + h}{F (1 - e^2) \sin \varphi_c \cos \varphi_c + N_p [(1 - e^2) \cos \varphi_c \sin \varphi]}$$

$$Y = \frac{f [N_c e^2 \sin \varphi_c \cos \varphi_c + N_p [(1 - e^2) \cos \varphi_c \sin \varphi]}{N_c (1 - e^2 \sin^2 \varphi_c) - N_p [\cos \varphi_c \cos \varphi \cos \lambda]}$$

$$\frac{-\sin \varphi_c \cos \varphi \cos \lambda]]}{+ (1 - e^2) \sin \varphi_c \sin \varphi] + h}$$

Considering the parameters in the above equations, it is apparent the following is true when the datum surface is spherical:

$$N_c = N_p = R$$

e = 0

The substitution of the above equalities into equations (78) and (81) transforms these equations into equations (46) and (49), the mapping equations for a spherical datum. Thus, equations (78) and (81) are valid both for spherical and ellipsoidal datum surfaces. Further, since it was shown that the mapping equations for the Gnomonic, Stereographic, and Orthographic Projections were only special cases of the mapping equations for a spherical datum, then they too are only special cases of equations (78) and (81). Therefore, equations (78) and (81) are truly General Perspective Projection Mapping Equations.

3. AN EMPIRICAL DETERMENTION OF PERUPECTIVE

AT PLUJECTION DISTORTIONS

Map distortions is an extensive subject and no attempt will be made in this paper to treat the subject in general. The author has derived an empirical method to calculate the linear distortions of the meridians and parallels on the projection plane and the angular distortions of the intersections of the meridians and parallels on the projection plane. The calculation of these distortions not only enables a vizualization of the projected latitude-longitude grid but also may be used as indicators as to the type of distortions that will be found in projecting any line from the datum surface onto the projection plane.

5.1 Meridian And Parallel Linear Distortions

The author defines a linear distortion to exist when the linear distance between two points measured on the datum surfac does not equal the linear distance between the same two points projected full scale onto the projection plane. The amount of distortion will be indicated by a ratio of the distance measured on the projection plane to the distance measured on the datum surface. In order to determine the linear distortions at a point, the two distances to be compared would of necessity have to be infinitely small. However, as will be shown by examples in Chapter 6, good approximations can be made by utilizing finite distances.

The distance between two points, P_1 and P_2 , located by plane X'-Y' coordinates on a projection plane is given by the following elementary equation:

(82)
$$d' = [(X_2' - X_1')^2 + (Y_2' - Y_1')^2]^{\frac{1}{2}}$$

The distance between two points on the same parallel on the projection plane, d_p ', would thus be obtained by using equations (78) and (81) to compute the X'-Y' coordinates of the two points and then by using equation (82) to calculate the distance between the points. Likewise, the distance between two points on the same meridian on the projection plane, d_m ', would also be obtained by using equations (78), (81), and (82).

The distance between two points on a Meridian on the datum surface is calculated by the following formula as presented in [6]:

 $d_{m} = a (1 - e^{2}) [A (\phi_{2} - \phi_{1}) - \frac{B}{2} (\sin 2\phi_{2} - \sin 2\phi_{1}) + \frac{C}{4} (\sin 4\phi_{2} - \sin 4\phi_{1}) - \frac{D}{6} (\sin 6\phi_{2} - \sin 6\phi_{1}) + \frac{B}{8} (\sin 8\phi_{2} - \sin 8\phi_{1}) - \frac{F}{10} (\sin 10\phi_{2} - \sin 10\phi_{1}) + \frac{B}{8} (\sin 8\phi_{2} - \sin 8\phi_{1}) - \frac{F}{10} (\sin 10\phi_{2} - \sin 10\phi_{1}) + \dots]$ (83)

The parameters in the above equation have the following definitions:

8 =	elli	psoid	major s	emi-diame	ter		
e =	ellij	psoid	eccentr	icity			
A =	1 + j	3 e ²	45 e ⁴	$+\frac{175}{256}e^{6}$	+ $\frac{11025}{16384}$ e ⁸	+ $\frac{43659}{65536}$ e ¹⁰	+
B =	i	<u>}</u> e ² +	15 c ⁴	+ <u>525</u> e ⁶ .	+ <u>2205</u> e ⁸	+ $\frac{72765}{65536} e^{10}$	+
C =			15 e ⁴	$+\frac{105}{256}e^{6}$	+ <u>2205</u> e ⁸	$+\frac{10395}{16384}e^{10}$	+
D =				<u>35</u> e ⁶	+ <u>35</u> e ⁸	+ <u>31185</u> 10 131072	+
E =					<u>315</u> 8 16384	$+\frac{3465}{65536}e^{10}$	+
F -						693 10 131072	+

The distance between two points on a parallel on the datum surface is calculated by the following formula:

(84)
$$d_p = N \cos \varphi (\lambda_2 - \lambda_1)$$

where N is the radius of curvature in the prime vertical.

Utilizing equations (82), (83), and (84), the linear distortions along meridians and parallels at a particular point are calculated by the following ratios:

(85) Meridian Distortion = $\frac{d_{m}!}{d_{m}}$ (86) Parallel Distortion = $\frac{d_{p}!}{d_{p}}$

Equations (85) and (86) represent ratios of projection plane distances to datum surface distances. By making the distances that are compared small, the above equations offer a good approximation of the distortions at a particular point.

5.2 Angular Distortions

The meridians and parallels of a sphere or an ellipsoid of revolution intersect at right angles on the datum surface. When these angles are projected onto the projection plane, they may not intersect at right angles and hence, distortions exist. The author chooses to indicate this distortion by the absolute value of the number of degrees that the projected angle differs from ninety degrees.

An angle on the projection plane can be calculated from a knowledge of the coordinates of three points.



Figure 16 48 Figure 16 depicts a projection plane on which a meridian, a segment of which is P_1P_0 , and r parallel, 'segment of which is P_2P_0 , intersect at P_0 . From Figure 16, it is evident that by knowing the coordinates of P_0, P_1 , and P_2 in a plane coordinate system, the angles θ_1 and θ_2 may be calculated by elementary geometry. In the example illustrated by Figure 16, the angular distortion, as previously defined, has the value $(\theta_1 + \theta_2)$. Naturally the points P_1 and P_2 could be located in other quadrants depending on the projection, but the basic principles in determining the angular distortion remains the same.

Usually the meridians and parallels are projected onto the projection plane as some type of curved lines. Thus, the segment of meridian P_1P_0 and segment of paralled P_2P_0 as illustrated in Figure 16 are actually curved lines. In order to obtain exact angular values, the points P_1 and P_2 would have to be taken infinitely close to P_0 . However, it will be illustrated in Chapter 6 that good approximations can be obtained for angular distortions by using finite distances for P_1P_0 and P_2P_0 .

5.3 Distortion Calculations

The methods discussed for distortion calculation in Sections 5.1 and 5.2 indicate that basically the same quantities are required to calculate both linear and angular distortions at a particular point. In the calculation of both types of distortions, the plane X'-Y' coordinates of three points are required. Since the calculation of plane coordinates is a rather lengthy procedure, the distortion

calculation methods discussed in this paper are especially suited for use when electronic computers are available.

6. EXAMPLES OF PERSPECTIVE MAP PROJECTION GRIDS

6.1 General Format Of The Projection Grids

This paper has dealt with the derivation of General Perspective Projection Mapping Equations and with the empirical derivation of the distortions inherent with the perspective projection. In this chapter six examples of the perspective projection are illustrated and briefly discussed. These examples are included both to illustrate various types of perspective projections and to partially verify the validity of the equations derived in prior chapters. The coordinates for all the examples were computed through the use of equations (78) and (81). All calculations were carried out on the IBM 7094 computer. The Appendix includes the computer program used to produce one of the examples and also includes a brief discussion of the program.

A similar format is used for all the included examples. The first page of each example lists all the projection parameters. The body of each example is a numerical grid which tabulates the coordinates and distortions of the intersections of meridians and parallels spaced ten degrees apart. The grid is read by selecting the longitude of a particular desired meridian from the top line and then by reading down the column under that longitude until the desired latitude, as indicated by the column on the left of the grid, is reached. For each intersection of a meridian and a parallel, five quantities, as listed on the left of the grid,

are tabulated. The first two quantities are the X' and Y' coordinates of the intersection as computed by equations (78) and (81). The next two quantities are the meridian distortion and the parallel distortion computed at the intersection point by equations (85) and (86) respectively. The fifth quantity is the angular distortion of the intersection of the meridian and the parallel, calculated as described in Section 5.2.

Depending on the type of projection, the grid illustrates either one half of the datum surface visible from the projection center or a grid 90 degrees in longitude and 170 degrees in latitude. In both of the above cases the first column of the body of the grid is the central meridian of the projection. The remaining columns describe meridians to the right of the central meridian. The grid to the left of the central meridian, if calculated, would be symmetrical to that calculated to the right of the central meridian. The central latitude is found in the center of the grid and may be located by the latitude indicators to the left of the grid. An inspection of these latitude indicators reveals that, as would be expected, the absolute values of the latitudes increase until a geographic pole is reached and then they proceed to decrease. It is evident that as a particular meridian passes through a pole, the meridian undergoes a 180 degree change in longitude and after passing through the pole the meridian is actually to the left of the central meridian. Being that only the grid to the right of the central meridian is being considered, as a meridian passes over a

pole the sympletric meridian to the right of the central meridian is considered rather than the original meridian. The above can be clarified by the following specific example of a meridian passing over a pole. In the examples illustrated in this chapter, the 90 Degrees West Longitude Meridian is the central meridian. Thus, as the 80 Degrees West Longitude Meridian passes through a pole, it assumes a longitude of 100 degrees East and is now located to the left of the central meridian. To complete the right side of the grid, the meridian symmetric to the 100 Degrees East Longitude Meridian is considered. This symmetric meridian is the 80 Degrees East Longitude Meridian. Therefore, the longitude indicators located at the top of the grids are numerically correct but may indicate East or West Longitude. It should be kept in mind when viewing the grid that the actual value of a meridian in no way enters into the computation of the plane X'-Y' coordinates of points on that meridian. It is the longitude difference between a particular point and the central meridian that determines the values of the coordinates of that point.

It will be noted that the distortions listed for 90 degrees of latitude are numbers consisting of a series of ones. These numbers are not the distortions at this latitude but merely indicators that the distortions at this latitude were not calculated. It is apparent from the distortion analysis in Chapter 5 that the equations used to compute distortions for the rest of the grid will not function properly at the pole. No effort is made in this paper to establish special distortion equations for the poles.

Earlier in this paper it was stated that to calculate exact distortions an infinitely small distance between two points on the datum surface and the corresponding distance on the projection plane would have to be compared. The distance actually selected would determine the accuracy of the calculations. Various small distances were selected and tested by calculating distortions at points where distortions were known quantities. It was determined that by using a distance of .00001 degrees of arc, or approximately 1 meter on the surface of the earth, errors were apparently eliminated in the values printed out in the examples. The manner in which the length of the distance affected the accuracy of the distortion computations varied according to the type of projection.

6.2 Sphere And Ellipsoid Parameters

The sphere that was selected to represent the datum surface in the examples is only one of many possible spherical approximations of the shape of the earth. A sphere radius of 6,371,224 meters was selected. This radius produces a sphere with approximately the same area and volume as the International Ellipsoid.

The International Ellipsoid was selected to represent the ellipsoidal datum surface approximating the shape of the earth. The International Ellipsoid is defined as an ellipsoid with a semi-major axis equal to 6,378,388 meters and a flattening equal to $\frac{1}{297}$.

6.3 Example 1 - The Gnomonic Projection

The first example illustrates a Gnomonic Projection. Since the projection center is located at the center of the sphere in a Gnomonic Projection, it is obvious that a complete hemisphere can not be projected onto a plane. The computer was programmed not to print out coordinates larger than the absolute value of 99,999,999, and this is the reason that a complete square grid was not printed. It can be seen that both the size of the coordinates and the size of the distortions increase rapidly as the location of points progress away from the central meridian and the central parallel. The property of a Gnomonic Projection that great circles on the datum surface are projected as straight lines is clearly illustrated by the projection of the equator. It is seen that the equator, the parallel with 0 degrees of latitude, has a constant Y' coordinate, readily identifying it as a straight line.

The following five pages illustrate a Gnomonic Projection.

PERSPECTIVE MAP PROJECTIONS. Example 1 - Gnomonic Prejection

PROJECTICN PARAMETERS -

CENTRAL LATITUCE = 40 CEGREES CENTRAL LONGITLDE = 9C CEGREES HEIGHT CF FRCJECTION CENTER = -6371224.000 METERS FOCAL LENGTH (SCALE FACTOR) = -6371224.00C METERS SPFERE RADIUS = 6371224.000 METERS LONGITUDE 90

_ 8C

60

50

	40					
LAI.eX	ou	-0.00	3082323.04	5537782.64	7080288.71	7778184.00
Y		36133006.84	34788105.78	31263162.51	26671423.45	22013989.15
MFR.		33.1034	30.7718	24.9310	18.2526	12.5585
PAR.	2 dat - wije ratur	5.7588	6.9358	8.4643	8.7772	8.0566
ANG.		9630.0	35.8472	51,5219	. 56.7526	57.2000
I AT.	70	No. of the Party o	and a second			
X		-0.00	1093623.91	2082862.58	2889102.03	3472925.00
Y		17504794.07	17241916.27	16495742.14	15377882.36	14031869.08
MER.		8.5486	8.2788	7.5375	6.4951	5.3507
PAR.	a-talleda min-ditalla	2,9238	3.0964	3.4638	3.7795	3.9129
ANG		0.0000	19.6499	33.2758	40.5782	43.2785
LAT.	80				1002106	
Y		-0.00	382685.08	7448 18.44	1068274.71	1338957.81
		11035283.47	10969339.75	10776604.00	10471494.34	10075409.70
MER.		4.0000	3,9326	3.7403	3.4450	3.0854
PAR.		2.0000	2.0607	2,2148	2.4021	2.5675
ANG		0 0000	12.7587	22.9347	29.5021	32.5893
LAT	00	0.0000	1201201	6207701	E TO DYEL	1697414
Y	0	-0.00	-6.60	-0.00	-0.00	-0.00
· · · · · · · · · · · · · · · · · · ·	Men occ. select and of	7502020 00	7502020 00	7502020 00	7502020 00	7592929.09
MED		1 1111	1 1111	1,1111	1,1111	1,1111
DAD	Pelland Debates same and			1 1111	1 1111	1 1111
ANC		1 1 1 1 1 1	1 1111	1 1111	1 1 1 1 1 1	1 1111
LAT	90					
LAIT	00	0.00	251452 87	400186 52	730310 47	967650 82
· · · · · · · · · · · · · · · · · · ·		5344001 71	6374373 41	5450249 11	5600766 23	5708866 28
MED		1 7.41	1 4070	1 6706	1 4600	1 6115
DAD		1 3054	1 2296	1 2058	1.5014	1 6370
ANC		0.000	4 2727	11 6647	15 4002	17 2407
LAT.	70	0.0000	0.2121	11.0041	13.4772	1763477
LAT	10	0.00	619040 00	974591 04	1211242 70	1746674 07
		2470427 40	130749.00	20/41/0 70	1011240.10	1740374.07
MCD		1 1113	1 227	1 2250	1 2270	1 3440
DAU		1 1647	1 1720	1.3350	1 2252	1.5440
ANC		1.1947	4 3150	0.000	1. 5202	11 4403
ANG.	40	0.0000	4.3138	8.0090	10.5580	11.4043
LAI	00		502245 25	1149407 40	1702020 61	2404702 14
·		2218025 80	2266606 40	2612102 10	2741400 04	212(122 10
MED		2310933.09	2 3000 90.09	1 1/07	2101040.00	1 20423
DAD		1.1325	1+1304	1 1 1 2 / 7	1.1705	1.3505
PAK.		1.0042	1.0810	1.1347	1.2238	1.3395
	50	0.0000	2.1011	4. 7340	0.2286	0.1799
LAI	20	0.00	727. / 01	1444510 05	2220644 75	3037165 03
K		1122410 10	127040.91	1400018.95	2220344.15	3027155.82
MCO		1123418.69	1112938.05	1324003.50	1387908.64	1980402.76
MEK.		1.0311	1.0376	1.0579	1.0941	1.1509
PAK.		1.0154	1.0326	× 1.0857	1.1/91	1.3215
ANG.		0.0000	1.2844	2.1720	2.2685	1.1794

LONGITUDE 90

CHL.	40				-	
X	4 0.0	0.00	855138.08	1730520.25	2648547.94	3636468.97
Y		0.00	48090.08	196138.55	456171.12	850772.12
MER.		1.0000	1.0090	1.0372	1.0881	1.1644
PAR.		1.0000	1.0180	1.0742	1.1754	1.3341
ANG.		0.0000	0.0575	C.4621	1.5709	3.7619
LAT.	30					
X	~ •	0.00	982969.06	1997403-32	3679291.61	4275167.26
Y		-1123418.69	-1079756.03	-944604.05	-704507.64	-333399.71
MER.		1.0311	1.0432	1.0811	1.1508	1.2646
PAR.		1.0154	1.0354	1.0984	1.2139	1.4017
ANG.		0.0000	1.4030	3.1230	5.4935	8.8810
LAT.	20			200/200 21	3610011 63	
X	strengt passes	0.00	1119378.70	2284632.71	3549944.57	4989577.74
Y		-2318935.89	-2283291.21	-21/2313.25	-19/2/25.6/	-105/944.92
MER.		1.1325	1.1490	1.2013	1.2991	1.403
PAR.		1.0642	1.0877	1.1024	1.3025	1.2382
ANG.	15	0.0000	2.8370	5.9/14	9.72(2	14.439
LAT.	10	0.00	1274969-60	2615363.25	4101181.25	5849113.47
Ý	a	-3678427.89	-3656061.74	- 1585960-12	-3458084.00	-3251558.01
MER.		1, 1333	1.3572	1.4334	1.5786	1,8306
PAH.		1.1547	1.1843	1,2793	1.4620	1.7821
ANG		0.0000	4.4683	9,2140	14.5356	20.7709
LAT.	0	0.000				Lettre
X	•	0.00	1466518.95	3027155-82	4801846.58	6978827.09
¥	-	-5346091.71	-5346091.71	-5346091.71	-5346091.71	-5346091.71
MER.		1.7041	1.7415	1.8624	2.0988	2.5275
PAR.	-	1.3054	1.3460	1.4783	1.7405	2.2245
ANG.		0.0000	6.4664	13.1678	20.3606	28.3408
LAT.	-10					
X		0.00	1725800.37	3592855.96	5791251.58	8649394.66
Y		-7592929.09	-7633718.28	-7764072.95	-8012135.21	-8443389.92
MER.		2.4203	2.4867	2.7051	3.1478	4.0030
PAR.	in these loss in the special	1.5557	1.6187	1.8282	2.2608	3.1190
ANG.		0.0000	9.1451	18.3924	27.8803	37.8144
LAT.	-20					
X		0.00	2125755.44	4484726.10	7417743.06	11605863.02
Y	-	11035283.67	-11162501.15	-11576207.83	-12394867.28	-13924798.91
MER.		4.0000	4.1437	4.6292	5.6720	7.9160
PAR.		2.0000	2.1190	2.5251	3.4164	5.3992
ANG.		0.0000	13.1958	26.0069	38.2607	50.0770
LAT.	-30					
X		0.00	2886438.59	6248587.75	10898420.12	18985371.82
Y		-17504794.07	-17873969.19	-19115510.04	-21773874.31	-27606699.42
MER.		8.5486	8.9950	10.5806	14.4155	24.9401
PAR.		2.9238	3.2455	4.3835	7.1647	15.0910
ANG.		C.0000	20.5179	38.4906	53.3529	65.9492
LAT.	-40				Ar / Boan /	AGE NERCE.
X		0.00	5144775.88	12073609.93	25679836.37	
Y	-	36133006.84	-3/199162.26	-44013496.05	-61603770.81	
MER.		33.1634	36.5226	50.4864	102.2915	
PAR.		5.7588	7.8025	15.4977	43.7005	a so all use allow the s
		O.COOU	38,2803	61.0794	74.8895	

LAT. 60 7555110.37 7932448.92 6400399.77 5722617.92 7860123.26 X 7592929.09 17853591.29 14378916.26 11574963.03 9348661.70 ۷ 5.0116 MER. 2.0743 3.8309 2.7321 8.4003 3.7446 3.0558 6.8875 4.6154 PAR. 5.6792 33.9839 16.2031 3,2201 23,8587 50.3708 ANG . 70 LAT. 3607623.82 3832039.33 3989554.00 3980602.22 3842220.09 - X 9846894.01 8646911.87 7592929.09 11176336,80 Y 12595301.16 MER. 1.7618 4.2671 3.3442 2.6231 2.1042 3.0090 2.6738 PAR. 3.6415 3.3435 3.8514 15.5794 42.5982 39.1155 25.9292 5.7041 ANG. 80 LAT. 1747729.23 1769505.32 1786361,88 1547922.86 1691279.19 X 9112031.95 8594888.77 8082956,89 7592929.09 9613598.88 Y 2.0109 1.7645 1.6041 MER. 2.7011 2.3315 2.4799 PAR. 2.7183 2.6918 2.6078 2.6173 ANG . 24.3653 13.9754 7.6926 29.7884 32.5936 90 LAT. -0.00 -0.00 -0.00 -0.00 -0.00 X 7592929.09 7592929.09 7592929.09 7592929.09 7592929.09 MER. 1.1111 1.1111 1.1111 1.1111 1.1111 1.1111 1.1111 1.1111 PAR. 1.1111 1.1111 1.1111 1.1111 1.1111 1.1111 ANG. 1.1111 80 LAT. 1747729.23 1660582.41 1537206.24 1179515.96 1369668.04 X 7137404.62 7592929.09 6053180.35 6362696.58 6725336.97 1.5077 1.5248 1.6041 MER. 1.5684 1.5291 1.7969 1.9702 2.1487 2.3225 2.4799 PAR. 1.2767 7.6926 14.1371 8.8287 16.9554 ANG. 70 LAT. 2161059.30 3303954.99 3607623.82 2567459.60 2952097.25 X 7592929.09 6686601.09 5921341.91 4771866.53 5286843.12 MER. 1.4427 1.3571 1.3850 1.5559 1.7618 PAR. 2.3597 2.6738 2.0717 1.8327 1.6258 10.4537 7.2057 1.5667 6.2665 ANG. 60 LAT.

10

LONGITUDE SJ

X

MER.

PAR.

ANG .

LAT.

MER.

PAR.

ANG.

X

Y

1.2374

1.5273

1.4949

ů

10

20

15.5794 5034192.04 4353088.87 5722617.92 3039487.42 3687368.48 5128048.38 7592929.09 3625160.06 4280943.68 6211969.24 1.3367 1.6902 2.0743 1.2561 1.4678 1.5428 1.7863 2.1052 2.5196 3.0558 5.6490 14.0153 23.8587 0.5239 4.3903 50 3878300.50 4801846.58 5823655.68 6978827.09 8317042.25 3279922.16 4295358.80 7592929.09 5678524.57 2530167.35

1.5896

2.2377

13.0316

1.9654

2.8455 22.1139

2.6511 3.7559

32.7324

0

1.3716

1.8199

6.1398

С

LAT.	40				
X	4730372.32	5981928.84	7470988.40	9331603.41	11812500.70
Y	1417866.59	2219975.14	3362577.79	5033120.18	7592929.09
MER.	1.2962	1.4987	1.8419	2.4742	3.765
PAR.	1.5758	1.9413	2.5104	3.4431	5.0984
ANG	7.4403	13.6158	20.8027	30.7934	42.3941
LAT.	30		a makatan san kanata managanak	and the second	
X	5652046.28	7316509.42	9456387.15	12445913.44	17167853.75
Y	214760.67	1021258.11	2238371.23	4178814.84	7592929.09
MER.	1.4479	1.7542	2.3090	3.4436	6.2229
PAR.	1.6998	2.1825	3.0100	4.5727	8.0424
ANG.	13.6920	20.3511	29.1988	46.2634	52.9955
LATA	20		and management of the state of the state		
X	6719319.00	8943015.50	12071566.38	17097576.91	27232625.23
Y	-1178518,91	-439665.70	757559.56	2902788.73	7592929.09
MER.	1.7380	2,2261	3,1958	5,5198	13.299
PAR.	1,9121	2.6211	3.9482	6.9752	16.489
ANG	20.5317	28.4251	38.4688	50.7024	64.5862
LAT.	10	20111.71			
X	8057257.36	11116142.05	15950704-66	25468232.98	56212979.66
Ŷ	-2925073.40	-2391562.69	-1438952.71	606583.12	7592929.00
MER.	2.2754	3,1315	5.0802	11,1511	51,5931
DAD	2 3515	1.4687	5.9224	13.4624	62,1357
ANC	28.3068	17.5549	48.8464	62,1979	77.037
LAT.	0	3112347	40.0404	0211777	
L TI	9911864.98	14405539.75	22850895.78	47168290.52	
	-5346091.71	-5346691.71	-5346091.71	-53666.91.71	
MER.	3.1196	5.1004	10,1119	37.0958	
DAL.	3,1594	5.2216	11,1595	43,2918	4
ANG.	37.4537	48.0699	60.4798	74.6602	
LAT	-10		0011170	1110002	
Y	12875517.14	20459851. 18	4.1272557.57		ann annan de la coine antaite differ ministres par k a
	-0214800 05	-10784059 71	-15210899 76		
MER	5.8104	10 6782	32, 3848		
DAD	8000 3	10.1311	36 2726		
ANC	AR 4401	60 2183	71 3141		-18
LAT	-20	00-2103	1313143		
Y	18886307.27	37014592.43			
Ŷ	-17058900.76	-25653447.80			
MER.	14,7292	18,1442			
PAR.	10.7.74	34.5561			
ANG	61,4192	73.9726			
LAT.	-30	13.7120			
Y	AC230340 30				
	-44015700 16				
MED	71 20-0				
DAD	64 0211				en en des las mer 1 de
ANC	77 4114				
an IM La	11.4310				

6.4 Example 2 - The Stereographic Projection

The primary property of a Stereographic Projection is that it is a conformal type projection. Conformal projections have. two properties which are immediately apparent in the following example. First, angles are projected from the datum surface to the projection plane with true size. Thus, it is seen in the example that all angular distortions are equal to zero, or, in other words, all the projected meridians and parallels intersect at right angles. The second property inherent in conformal projections is that at any particular point, scale distortion is the same in any direction. This point is illustrated in the example by the fact that the meridian and parallel distortions are equal to each other at all intersections.

The following five pages illustrate a Stereographic Projection.

PERSPECTIVE MAP PROJECTIONS

EXAMPLE 2 - STEREOGRAPHIC PROJECTION

PROJECTION PARAMETERS -

CENTRAL LATITUDE = 40 DEGREES

CENTRAL LONGITUDE = 90 DEGREES

HEIGHT OF PROJECTION CENTER = -12742448.000 METERS

FOCAL LENGTH (SCALE FACTOR) = -12742448.000 METERS

SPHERE RADIUS = 6371224.000 METERS

LONGITUDE 90

LAT.	50		1/11727 10	2120600 44	30/1005 50	4731000 34
X		-0.00	1411/3/.18	2120590.64	3041092.00	4721009.34
Υ		12742448.00	12568441.75	12066612.20	11292150.08	10321042.14
MER.		2.0000	1.9851	1.9423	1.8762	1.7934
PAR.		2.0000	1.9851	1.9423	1.8762	1.7934
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	60	and one age in an endered with the true with to 10 an ead		-		and the supervision of the state of the supervision of the state of the supervision of the state of the supervision of the supe
X		-0.00	938009.54	1820841.42	2600577.24	3241889.38
Y		10692183.42	10586682.43	10279432.18	9796365.59	9175267.35
MER.		1.7041	1.6957	1.6712	1.6327	1.5832
PAR.		1.7041	1.6957	1.6712	1.6327	1.5832
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	70					
X		-0.00	562250.11	1097776.10	1582348.69	1996255.98
Ŷ		8922358.14	8864353.79	8694107.61	8422399.70	8065593.86
MER.		1.4903	1.4859	1.4729	1.4523	1.4252
PAR.	ngi - Tradi siste is su	1.4903	1.4859	1.4729	1.4523	1.4252
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	80					
X		-0.00	255809.90	501842.04	728907.43	928925.75
Y		7356855.78	7332571.55	7260840.36	7144931.85	6989994.35
MER.		1.3333	1.3315	1.3262	1.3177	1.3062
PAR.		1.3333	1.3315	1.3262	1.3177	1.3062
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	90					
X		-0.00	-0.00	-0.00	-0.00	-0.00
Y		5941901.09	5941901.09	5941901-09	5941901.09	5941901.09
MER.	-	1.1111	1.1111	1.1111	1.1111	1.1111
PAR.		1.1111	1.1111	1.1111	1.1111	1.1111
ANG.		1.1111	1.1111	1.1111	1.1111	1.1111
LAT.	80	Ada mah				
X		0.00	217815.59	430477.47	632843.48	819804.60
Y		4637871.78	4655434.25	4707826.0.	4794148.25	4912864.40
MER.		1.1325	1.1338	1.1376	1.1440	1.1528
PAR.		1.1325	1.1338	1.1376	1.1440	1,1528
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	70					
X		0.00	406428.93	805622.82	1190157-15	155.2244.72
Y		3414328.65	3444483.50	3534796.53	3684772.75	3893451.41
MER.		1.0718	1.0741	1.0809	1.0923	1.1082
PAR.		1.0718	1.0741	1.0809	1.0923	1.1082
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	60					
X		0.00	572090-86	1136958.30	1686957.30	2213600-73
Y		2246837.38	2285770.51	2402780.36	2598445.63	2873548. AA
MER-		1.0311	1.0342	1.0435	1.0591	1.0810
PAR.		1-0311	1-0342	1-0435	1-0591	1.0810
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	50			5.0000	5.0000	0.0000
X		0.00	719303.37	1632848.83	2136283.11	2816031 60
Y		1114819.75	1159488.58	1294152.62	1520744.24	1842228 42
MER.		1.0077	1.0115	1.0230	1.0423	1 0407
PAR		1.0077	1.0115	1.0230	1 0232	1.0097
ANG		0 0000	0 0000	0 0000	0 0000	1.0097
		0.0000	0.0000	0.0000	0.000	

					and in success to	
LAT.	40					
X		0.00	851309.16	1699347.24	2540174.00	3368443.47
Υ		0.00	47874.76	192605.37	437505.40	788066.07
MER.		1.0000	1.0045	1.0180	1.0409	1.0737
PAR.		1.0000	1.0045	1.0180	1.0409	1.0737
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	30					
X		0.00	970389.81	1940709.20	2910260.49	3876994.93
Y		-1114819.75	-1065938.18	-917792.49	-665835.20	-302348.17
MER.		1.0077	1.0128	1.0284	1.0549	1.0931
PAR.		1.0077	1.0128	1.0284	1.0549	1.0931
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	20					
X		0.00	1078031.63	2159671.88	3248060.38	4345290.57
Y		-2246837.38	-2198952.12	-2053495.86	-1804966.80	-1443860.14
MER.		1.0311	1.0369	1.0547	1.0850	1.1291
PAR.		1.0311	1.0369	1.0547	1.0850	1.1291
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	10					
X		0.00	1174985.94	2357536.27	3555010.75	4774264.56
Y		-3414328.65	-3369351.81	-3232450.04	-2997557.31	-2654042.94
MER.		1.0718	1.0784	1.0986	1.1332	1.1838
PAR.		1.0718	1.0784	1.0986	1.1332	1.1838
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT	0					
X		0.00	1261225.87	2534048.46	3830209.56	5161686.00
Y		-4637871.78	-4597710.23	-4475242.20	-4264328.57	-3954080.88
MER.		1.1325	1.1400	1.1629	1.2023	1.2604
PAR.		1.1325	1.1400	1.1629	1.2023	1.2604
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT	-10					
X		0.00	1335776.11	2687026.06	4069770.02	5501130.51
Ŷ		-5941901.09	-5908527.26	-5806596.92	-5630483.71	-5370108.74
MER.		1.2174	1.2260	1.2521	1.2973	1.3640
PAR.		1.2174	1.2260	1.2521	1.2973	1.3640
ANG		0.0000	0.0000	0.0000	0.0000	0.0000
LAT	-20					
Y	20	0.00	1396354.14	2811600.79	4265579.63	5780112.95
Ŷ		-7356855.78	-7332360.25	-7257449.91	-7127679.27	-6935021.58
MER		1.3333	1.3431	1. 3731	1.4249	1,5020
DAR.	ander de la deser	1, 3333	1,3431	1.3731	1.4249	1.5020
ANG		0.0000	0.0000	0.0000	0.0000	0.0000
LAT	- 30	0.0000	010000	000000		
	- 30	0.00	1438694 61	2898814.36	4403054.66	5976810.99
:		-8022358 14	-8008945.95	-8867974.21	-8796830.89	-8690902.98
HED		1 4403	1.5014	1.6741	1.6940	1.6852
DAD	-	1 4703	1.5010	1 5241	1 6040	1 6862
PAR.		0.0000	0.0000	1. 301	0.0000	0 0002
ANG.	- 40	0.0000	0.0000	0.0000	0.0000	0.0000
LAI	-40	0.00	1455202 03	2022027 00	4457000 51	6054211 42
A U	-	10402102 (2	-10402103 43	-10602102 42	-10602102 43	-10402102 42
HER	1.2	10092103.42	-10072103.42	-10092103.42	1 0344	-10076103.42
MEK.		1.7041	1.7171	1.7571	1.0204	1. 0200
PAK.		1.1041	1.11/1	1.19/1	1.0204	1. 72 98
A A		n n n n n n n n n n	A	A AAAA	A 6666	<u>n nnnn</u>

2221227	LONG	TUDE	40	30	20	10	0
	LAT	50					
	X	10	5335886.89	5691969-65	5813275.12	5733356.59	5488251.42
	Y		9237041.51	8112659.28	7007798.45	5964757.89	5010423.49
	MER		1.7008	1.6049	1.5106	1.4216	1.3401
	PAR.		1.7008	1.6049	1.5106	1.4216	1.3401
	ANG .		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	60					
	X		3724348.11	4041756.83	4199426.25	4210577.24	4092853.57
	Y		8459535.16	7692281.59	6911988.16	6150125.56	5430512.29
	MER.		1.5262	1.4650	1-4029	1.3421	1.2848
-	PAR.		1.5262	1.4650	1.4029	1=3421	1.2848
	ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	70					
1-0	X	-	2325529.35	2562277.20	2704245.76	2753859.79	2717027.44
	Y		7643643.52	7177963.50	6689545.93	6197558.26	5718499.97
	MER.		1.3931	1.3578	1.3206	1.2833	1.2469
	PAR.		1.3931	1.3578	1.3206	1.2833	1.2469
	ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT .	80					
	X		1095321.43	1223264.16	1309749.03	1353534.76	1354974.14
	Y		6802652.21	6590527.58	6361748.16	6124494.27	5886622.70
	MER.		1.2924	1.2767	1.2598	1.2423	1.2247
	PAR.		1.2924	1.2767	1-2598	1.2423	1-2247
	ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	90				an in a summer and the second s	
	X		-0.00	-0.00	-0.00	-0.00	-0.00
	Y		5941901.09	5941901.09	5941901.09	5941901.09	5941901-09
	MER.		1.1111	1.1111	1-1111	1.1111	1.1111
	PAR.		1.1111	1.1111	1.1111	1-1111	1.1111
	ANG.		1.1111	1.1111	1.1111	1.1111	1.1111
	LAT.	80					
	X		986326.36	1127519-46	1238747.48	1315777.39	1354974.14
	Y		5061746.98	5237812.36	5437253-81	5655386.65	5886622.70
	MER.		1.1638	1.1768	1-1915	1.2076	1.2241
	PAR.		1.1638	1.1768	1.1915	1.2076	1.2247
	ANG.	-	0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	70	1000500 10	2126262 40	1/10000 00	2401040 20	2212022 //
	X		1883598.12	21/0302.00	2418082.29	2001948.39	571027.44
	ALC D		4139200-46	14/1421.20	4650210-15	2202008-UI	2/18499.9/
	MCK.		1.1204	1.1527	1.1000	1.2122	1.2409
	PAR.		1+1204	1+1027	1.1809	1+2125	1.2409
	ANG.	60	0.0000	0.0000	0.0000	0.0000	0.0000
	LAI.	00	2701147 17	1166217 06	3567696 36	1845512 04	4002851 57
	0		1229791 04	1666201 07	6170028 18	6760972 61	5430512 20
	MED		1 1003	1 1660	1 1851	1 2321	1 2949
	DAP		1 1003	1 1440	1 1851	1.2321	1. 2949
	ANG		0.0000	0.0000	0.0000	0 0000	0 0000
	I AT	50	0.0000	0.0000	0.0000	0.0000	0.0000
	Y	50	3668615.63	4079903.31	4634305-76	5111988.83	5488251.42
	Ŷ		2262892.14	2786795.67	3418128.94	4159517.61	5010423.49
	MER		1.1056	1.1503	1-2042	1.2675	1.3401
	PAR_		1.1056	1.1503	1.2042	1.2675	1.3401
	ANG		0.0000	0_0000	0.0000	0.0000	0,0000
			0.0000		0.0000	0.0000	0.0000

-

LONG	LTUDE 40	30	20	10	Q	
LAT.	40					
X	4176531.76	4953461-50	5683567.09	6344883.24	6907336.45	
Y	1251860.20	1838296.93	2558086.76	3422194.28	4439950.29	
MEQ.	1.1171	1.1710	1.2392	1.3201	1 4153	
DAD	1 1171	1 1710	1 2302	1.3201	1 4153	
ANG	0.0000	0.0000	0.0000	0.0000	0.0000	
ANU	20	0.0000	0.0000		0.0000	
h61g	20 (07/50/ 7/		1107515 13	7641050 05	0351345 30	
	4030304.20	5781157.52	0091343.02	7304030.03	0351245.20	
	103129.31	800949.33	1202340.49	2004901.01	3093322.04	
MEK.	1.1443	1.2098	1.2917	1.3922	1.5130	
PAR.	1.1443	1.2098	1.2917	1.3922	1.5136	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	
LAL.	20					
X	5451593.77	65 04106.26	7674962.10	8768342.18	9815977.84	
Y	-956169.27	-322711.33	481647.59	1488669.71	2736865.18	
MER.	1.1887	1.2660	1.3642	1.4872	1,6396	
PAR.	1.1887	1.2660	1.3642	1.4872	1-6396	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	
LAT.	10					
X	6021129.02	7299483.63	8609607.63	9945288.24	11288816.35	
·Y	-2185885.79	-1570434.47	-776694.10	236869.36	1524829.01	
MER.	1.2527	1.3433	1.4602	1.6095	1.7992	
PAR.	1.2527	1.3433	1.4602	1.6095	1.7992	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	
LATA	0					
X	6540643.34	7979108.00	9488081.93	11075565-28	12742448-00	
Y	-3527780.01	-2961155.49	-2219789.49	-1255313-41	0.00	
MER	1,3401	1.4461	1.5848	1.7652	2.0000	
PAR.	1,3401	1.4461	1.5848	1.7652	2,0000	
ANG	0.0000	0.0000	0.0000	0.0000	0.0000	
LAT.	-10	0.0000	0.0000	0.0000	0.0000	
	6999895.05	8587047.45	10286146 57	12123238 50	14125538 62	
÷	-5009753 69	-4524005 07	- 2995042 45	-2026857 10	-1007007 20	
MED	- ,00,77,53.00	1 5903	- 300,003.43	- 1 0420	2 2513	
	1 4643	1.5003	1 7440	1.9020	2.2213	
PAR.	1.4303	1.5005	1. /440	1.9020	2.2313	
ANG	0.0000	0.0000	0.0000	0.0000	0.0000	
LAIO	72002227 62	0005400 40	100/2020 0/	12027702 11	151/0117 01	
	1300221.52	9095080.42	10902929.84	1302/102-11	15348237.81	
T	-6666803.66	-0303890.23	-381/063.01	-2104924.72	-42/9355.38	
MER.	1.6092	1.7543	1.9486	2.2096	2.5636	
PAR.	1.6092	1.7543	1.9486	2.2096	2.5636	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	
LAT.	-30		ton armada	unte angletangle alempie andress gedar der der	/	
X	7649962.18	9459280.84	11451897.29	13690526.04	16261690.14	
V	-8542813.10	-8341287.44	-8069187.87	-7700093.77	-7192154.71	
MER.	1.8099	1.9796	2.2087	2.5195	2.9472	
PAR.	1,8099	1.9796	2.2087	2.5195	2.9472	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	
LAT.	-40					
X	7756600.99	9603693.17	11647311.36	13957654.17	16634084.50	
Y	-10692183.42	-10692183.42	-10692183.42	-10692183.42	-10692183.42	
MER.	2.0746	2.2721	2.5396	2.9039	3.4082	
PAR.	2.0746	2.2721	2.5396	2.9039	3.4382	
ANG.	0.0000	0.0000	0.0000	0.0000	0.0000	

6.5 Example 3 - The Orthographic Projection

Rather than illustrating an Orthographic Projection with the projection center located at an arbitrary latitude of 40 degrees as was done in Examples 1 and 2, a Polar Orthographic is illustrated in Example 3. A Polar Orthographic is a perspective projection in which the projection axis is coincident with the axis of rotation of the datum body, and the projection center is located at an infinite distance along this axis. In this type of projection the most prominent properties are that all parallels of latitude are projected in true size as concentric circles with centers at the pole and all meridians are projected as straight lines radiating from the pole. These properties are illustrated in the following example by the parallel distortions all being equal to unity, or, in other words, the distances along the parallels measured on the projection plane are equal to the distances along the parallels measured on the datum surface. Also, it is noted that all the angular distortions are equal to zero. This is due to the fact that the parallels are all concentric circles and the meridians are all straight lines radiating from the center of the concentric circles. Thus, all intersections of meridians and parallels form right angles.

The following five pages illustrate an Orthographic Projection.
PERSPECTIVE MAP PROJECTIONS

EXAMPLE 3 - ORTHOGRAPHIC PROJECTION

PROJECTION PARAMETERS -

CENTRAL LATITUDE = 90 DEGREES

CENTRAL LONGITUDE = 90 DEGREES

HEIGHT OF PROJECTION CENTER = INFINITY

and the second second

FOCAL LENGTH = INFINITY

SPHERE RADIUS = 6371224.000 METERS

6¢

LAT. X Y MER. PAR. ANG. LAT. X Y MER. PAR. ANG.	0	-0.00 6371224.00 0.0000 1.0000 0.0000	1106351.44 6274430.79 0.0000 1.0000	2179686.95 5986992.18 0.0000	3185612.00 5517641.84	4095343.85 4880640.74
X Y MER. PAR. ANG. LAT. X Y MER. PAR. ANG.	10	-0.03 6371224.00 0.0300 1.0000 0.0000	6274430.79 0.0000 1.0000	5986992 .1 8 0.0000	5517641.84	4880640.74
Y MER. PAR. ANG. LAT. X Y MER. PAR. ANG.	10	0.0000 0.0000 1.0000 0.0000	0274430.79 0.0000 1.0000	0.0000	0000	4000040.14
MER. PAR. ANG. LAT. X Y MER. PAR. ANG.	10	0.0000 1.0000 0.0000	0.0000	0.0000		a (10/0/0
PAR. ANG. LAT. X Y MER. PAR. ANG.	10	1.0000	1.0000		0.0000	0.0000
ANG. LAT. X Y MER. PAR.	10	0.0000		1.0006	1.0000	1.0000
LAT. X Y MER. PAR. ANG.	10		0.0000	0.0000_	C.0000	0.0000
X Y MER. PAR. ANG.					COLUMN TRANSFORM	and the second second
Y MER. PAR. ANG.		-0.00	1087543.47	2145981.72	3137215.40	4033126.37
MER. PAK. ANG.		6274430.79	6179108.09	5896036.31	5433816.46	4806492.84
PAR.		0.1736	0.1736	0.1736	0.1736	C.1736
ANG .		1.0000	1.0000	1.0000	1.0000	1.0000
		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	20		949 AT			
X		-0.00	1039630.28	2047671.92	2993496.09	3848364.39
Y		5986992.18	5896036.31	5625932.37	5184887.32	4586302.09
MER.		0.3420	0.3420	0.3420	C.3420	0.3420
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG		0.0000	0.0000	0.0000	0.0000	0.0000
FAT:	30					
¥	20	-0.00	958128.45	1887144.65	2758820.92	3546671.81
Ŷ		5517641.84	5433816.46	5184887.32	4778418.00	4226758.87
MER		0.5000	0.5000	0.5000	C.5000	0.5000
DAD		1 0000	1.0000	1.0000	1.0000	1.0000
ANC		1.0000	C .3300	0.0000	0.0000	00000
ANG.	40	0.0000	0.0000	0.0000	0.0000	0.0000
LAIN	40	-2.02	047614 37	1660277 / 5	2440320 37	1127216 40
÷		-0.00	041014.01	1009211:42	2440320.31	3131213.40
MED		4000040.74	4800492.84	4200302+04	4220100.01	3130101.12
MER.		0.0428	0.0420	0.0420	0.0420	0.0420
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.	5.0	0.0010	C.0000	0.0000	0.000	0.0000
LAT.	50			1.000.000.000		0/ 20/ 2/ 00
X		-0.00	711149.00	1400690.09	2047671.92	2632436.28
Y		4095343.85	4033126.37	3848364.39	3546671.81	3137215.40
MER.		0.1660	0.7660	C. 766C	0.7660	0.7660
PAR.		1.0000	1.0000	1.0.00	1.0000	1.0000
ANG.		0.0000	0.0000	0.0000	C.0000	C.0000
LAT.	60					
X		-0.00	553175.72	1089543.47	1592806.00	2047671.92
Y		3185612.00	3137215.40	2993496.09	2758820.92	2440320.37
MER.		0.8660	0.8660	0.8660	0.8660	0.8660
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	70	0.7 0 UNIX 0.00 UNIX	AND A STATE OF		and the second sec	and the second sec
X		~0.00	178394.48	745291.63	1089543.47	1400690.09
Y		2179086.95	2145981.72	2047671.92	1887144.65	1669277.45
MER.		0.9397	0.9397	0.9397	0.9397	C.9397
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG -		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	80					
X		-0.00	192115.91	378394.48	553175.72	711149.00
Ŷ		1106351.44	1089543.47	1039030.28	958128.45	847514 17
MER.		6 9R4R	C. 9848	D_9848	(QX48	0 0849
PAR		1,0000	1 6 30 2	1 0001	1 0000	1 6000
ANG		0.0000	0.0000	0 0000	1.0000	0.0000

LONGI	TUDE	•••• 90	. 80	70	. 60	50
LAT.	90					
×		-0.00	-0.00	-0.02	-0.00	-0.00
Y		-0.00	-0.00	-0.00	-0.00	-0.00
MER.		1.1111	1.1111	1.1111	1.1111	1.1111
PAR.		1.1111	1.1111	1.1111	1.1111	1,1111
ANG.		1.1111	1.1111	1.1111	1.1111	1,1111
LAT.	80			ale an a bala a substantia		
X		0.00	192115.91	378394.48	553175.72	711149.00
Y		-1106351.44	-1089543.47	-1039630.28	-958128.45	-847514.37
MER.		0.9848	0.9848	0.9848	C.9848	0.9848
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	6.0000	0.0000	0.000.0	0.0000
LAT.	70			the Man Man		
X		0.00	378394.48	745291.63	1089543.47	1400690-09
Y		-2179086.95	-2145981.72	-2047671.92	-1887144-65	-1669277.45
MER.		0.9397	0.9397	0.9397	0.9397	0.9397
PAR.		1.0000	1.0000	1.0000	1.0000	1,0000
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
LAT.	60		VILVVV	Mar have been		
Y		0.00	553175 72	1089563.67	1592806.00	2047671 92
Ŷ		-3185612.00	-3137215 40	-2003406 10	-2758820 92	-2440320 37
MER.		0.8660	6.8660	0.8666		0.38.0
PAR.		1.0000	1.0000	1.0000	1 6006	1.0000
ANG	•	0.0000	C 6000	0.0000	0.0000	0.0000
LAT	50	1 40000		······································		G. 9009
Y		0.00	711149 60	1400690 09	2.147671 92	2632636 28
Ŷ	-	-4095343.85	-4033126.37	-3868366.49	-3544671 81	-3137215 40
MER.		0.7660	L.7660	0.7660	6.7660	0.7666
PAR.		1.0000	1.0000	1.0000	1.0000	1.0002
ANC.		0.0000	6.6000	0.0000	1.0000	0.0000
LAT.	40		0.0100	y • 9770 3	and the second	
X		0.00	847514.37	1669277.45	2440320.37	3137215.46
Y	-	4880640.74	-4806492.84	-4586302.29	-4226758.87	-3738787 72
MER.		2.6428	0.6428	0.6428	C.6428	1.6428
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.	_	0.0000	0.0000	6.0003	0.0000	0.0000
LAT.	30			0.0000		
X		0.00	958128.45	1887144.65	2758820.92	3546671.81
Y	-	-5517641.84	-5433816.46	-5184887.32	-4778418.00	-4226758.87
MER.		0.5000	0.5000	0.5000	0.5000	0.5000
PAR.		1.0000	1.0000	1.0006	1.0000	1.00:0
ANG.		0.0000	0.0000	0.0000	C.0000	0.010
LAT.	20		e-Berdel -B	and an and a set of the set of th		
X		ũ.00	1039630.28	2047671.92	2993496.09	3848364.19
Y	-	5986992.18	-5896036.31	-5625932.37	-5184887.32	-4586302.04
MER.		0.3420	(.3420	5. 3420	1.1420	0.3420
PAR.		1.0000	1.9000	1.0000	1.0000	1.0.0
ANG.		0.01.00	C. 30CC	0.0000	0.0000	0.0000
LAT.	10					
X		0.00	1089543.47	2145981.72	3137215.40	4034126.47
Y	-	6274430.79	-6179108-09	-5896036.41	-5433816.46	-4806492.84
MER-		6.1736	C.1736	0.1746),1736	(-1736
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	6.0000	0.0000	6.0000	0.0000
			0.0000	0.0000	0.0000	0.0000

Ģ

							2
LAT.	0	wately relating the and second s					
X		4880640.14	5517641.84	5986992.18	6274430.79	63/1224.00	
Y		4095343.85	3185612.00	2179086.95	1106351.44	0.00	
MER.		0.0000	C.0000	0.0050	0.0000	0.0000	
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000	
ANG.		0.0000	0.6000	0.0000	0.0000	0.0000	
LAT.	10						
X		4806492.84	5433816.46	5896036.31	6179108.09	6274430.79	
Y		4033126.37	3137215.40	2145981.72	1089543.47	0.30	
MER.		0.1736	6.1736	0.1736	0.1736	0.1736	
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000	
ANG.		0.0000	0.0000	0.0000	0.000C	0.0000	_
LAT.	20	and the second design of the	- gaa.andy inva bit				
X		4586302.09	5182847.32	5625932.37	5896036.31	5986992.18	~
· Y		3848364.39	2973. 16.09	2047671.92	1039630.28	0.00	
MER.		0.3420	6.3420	0.3420	0.3420	9.3420	
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000	
ANG.		0.0000	0.0000	0.0000	0.0000	0.0000	
LAT.	30		and an an an advanced antipation of a constraint proper service of a service of the s	a taga a sama-managim antari a ta			
X		4226758.87	4778418.00	5184887.32	5433816.46	5517641.84	
Y		3546671.81	2758820.92	1887144.65	958128.45	0.00	
MER.		0.5000	0.5000	3.5000	0.5000	0.5000	-
PAR.		1.6000	1.0000	1.0000	1.0000	1.0000	-
ANG.		0.0000	6.0000	0.0000	0.0000	0.0000	
LAT.	40			· · · · · · · ·			-
X	10	3738787.72	4226758.67	4586302.09	4806492.84	4880640.74	
Y		31 37215.40	2440320.37	1669277.45	847514.37	C.00	
MER		0.6428	0.6428	0.6428	0.6428	0.6428	
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000	
ANG.		0.0000	0.0000	C.0000	0.0000	0.0000	
LATA	50						
X		3137215.40	3546671.81	3848364.39	4033126.37	4095343.85	
Y	··· ··	2632436.28	2047671.92	1400690.09	711149.00	-0.00	
MER.		0.7660	0.7660	0.7660	U.7060	0.7660	
PAR.	1000	1.0000	1.0000	1.0000	1.0000	1.0000	
ANG.		0.0000	0.0000	0.0000	0.0000	0.0001	
LAT	6.0			5			-
X	00	2440 120. 51	2758820.92	2993496.09	\$137215.40	3185612.00	
Ŷ		2047671.92	1592806.00	1089543.47	553175.72	-0.00	
MED		0.8660	0.8660	0.3660	0.8660	0.8660	
DAR.		1.0000	1.0000	1.0000	1.0000	1.0000	
ANG	-	0.0000	6.0000	0.0000	0.0000	0.0000	
LAT	70						
LATT	10	1669277.45	1887164.65	2047671.92	2145981.72	2179086.95	
÷		1400490 00	1007144.03	745201 63	178406 68	-0.00	
MED		0.0107	0 0 107	147271.03	0 0107	0.0107	. energe
DAU		1.0000	1.0000	1.0000	1 6000	1.0000	
PAR.		0.0000	0.0000	0.0000	0.0000	0.0000	
ANU.	0.0	0.0003	0.0000	JOULUC	0.0050	0.0000	-
LAT	80	467516 17	054120 /6	10 106 10 24	1089542 47	1106351 44	
X		711140.00	990120.49	274204 10	102115 01	-0.00	
Y		711149.00	222112.12	0 00/0	192112.91	0.000	-
MEK.		0.9848	0.9848	0.9648	1 6000	1.0000	
PAR.		1.0000	1.0000	1.0000	1.0000	0.0000	
ANG.		0.0000	0.0000	0.0000	5.0003	0.0000	

LON	IG I	T	UC	E						40	
-----	------	---	----	---	--	--	--	--	--	----	--

	T					
LAT.	90	alanan mandarana a	and approximation and a second			
X		-0.00	-0.00	-0.00	-0.00	-0.10
······································		-0.30	-0.00	=0.60	-0.00	-0.1
MER.		1.1111	1.1111	1.1111	1.1111	1.1111
PAR.	-	1.1111	1.1111	1.1111	1.1111	1.1111
ANG.		1.1111	1.1111	1.1111.	1.1111	1.1111
LAT .	80					
X		847514.37	958128.45	1039630.28	1089543.47	1106-51.44
Y.		-711149:20	-553175.72	-378394.48	-192115-91	-0.00
MER .		0.9848	C.9848	0.9848	0.9848	0.9848
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.	- 704	G.0000	0.0000	0.000	0002:0	0.0000
LAT.	70					
X		1669277.45	1887144.65	2047671.92	2145981.72	2179086.95
Y		-1402693.29	-1089543.47	-745291.63	-378394.48	-0.00
MER.		0.9397	0.9397	0.9397	0.9397	0.9397
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	0.0000	0,0000	0.0000	0.00.0
LAT.	60					
X		2440320.37	2758820.92	2993496.09	3137215.40	3185612.00
Y		-2047671.92	-1592806.00	-1389543.47	-553175.72	-0,00
MER.		0.8660	C.8660	0.8660	Ú.8660	C.8660
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		C.0000	0.0000	0.0000	0.0000	0.0000
LAT.	.50	and the second	and the second		ցուլ ու նաև Քի ԴերանԳահԳահԳահԳատարո	
X		31 37215.40	3546671.81	3848364.39	4033126.37	4095343.85
Y	-	-2632436.28	-2047671.92	-1400690.09	-711149.00	-0.00
MER.		C.7060	C.7660	0.7660	0.7660	C. 7660
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG .		0.0000	9329.9	0.0000	6.0000	6.0000
LAT.	40					
X		3738787.72	4226758.87	4586302.09	4806492.84	4880640.74
···· ¥		-3137215.49	-2440320.17	-1669271.45	-847514.37	6.00
MER.		0.6428	0.6428	0.6428	0.6428	6.6421
PAR.	-	1.0.00	1.0000	1.0000	1.0000	1.0000
ANG		6.0.00	0.0000	6,0000	6.6000	0.0000
AT.	30	010000	0.0000	0.00,00	020000	91900
Y	30	4226758.87	4778418.00	5184887 42	5433816.46	5517641 84
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		-3546671.81	-2756820.92	-1987144.65	-958128.45	0.00
MER.		0.5000	6.5000	0.5066	0.500C	0.5000
PAP.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG		0.0000	0.0000	0.0000	0.0000	0.0000
LAT	20		<b>C.OCO</b>			
LAIT	20	4546302 00	5146887 32	5675012 17	6804536 31	5046002 16
0		-1849344 10	-2993696 09	-2047671 02	-1030636 28	0,000,000,000
MED		0 2420	6 3/20	-2041011.92	-1039030.20	C 24.20
DAD		1 0000	1 0000	1.0000	1 0000	1.0000
ANC		0.000	1.0000	0.0000	1.0000	0.0000
ANU.	-10	9.0000	0.0000	0.0000	0.5000	0.000
LAT	10	1.001103 01	6/1901/ /.	600000 11	1170100 00	( ) 7 / / ) 0 7.
÷		-6073124 37	-411/216 //	-2145001 22	-1040543 47	0214430.1
MED			-3137213.40	-2145901.12	-1007943.47	0.11
DAD		1.0220	1.0000	1.0000	1.300/	1.00.10
PAR.		1.0000	1.0000	0.0000	1.0000	1.0000
ANU		0.0000	0.0000	0.0000	0.0000	0.0000

6.6 Example 4 - A General Projection Of A Spherical Datum

In Examples 1, 2, and 3, the parameter h, the height of the projection center above the datum shpere, was set equal to a particular value in relationship to the datum sphere in order that the resulting projection would exhibit certain desired properties. In Example 4, a completely arbitrary value of approximately 700 miles has been selected for the parameter h. Thus, ideally, Example 4 illustrates the type of projection that would be obtained by taking a vertical photograph of the datum sphere from a height of approximately 700 miles.

In the following example the computer was programmed to print out the coordinates of only those meridian-parallel intersections that are visible from the projection center. By visible, the author means that the intersection point is not beyond the horizon as viewed from the projection center. The relationship between latitude and longitude values on the horizon is calculated by setting  $LP_{p}$  equal to 0 in equation (23), which results in the following equation:

(87)  $\cos \theta = \cos \phi \cos \phi \cos \lambda + \sin \phi \sin \phi$ 

It is interesting to note that the shape of the projected grid in the following example actually resembles the shape of the grid that would be visible from the projection center.

The following two pages illustrate a general projection of a spherical datum.

# PERSPECTIVE MAP PROJECTIONS

EXAMPLE 4 - GENERAL PROJECTION

PROJECTION PARAMETERS -

CENTRAL LATITUDE = 40 DEGREES

CENTRAL LONGITUDE = 90 DEGREES

HEIGHT OF PROJECTION CENTER = 1126542.900 METERS

FOCAL LENGTH (SCALE FACTOR) = 1126542.900 METERS

SPHERE RADIUS = 6371224.000 METERS

LONG	ITUDE 90	80	70	60	50
	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				Barry service residence and the state and state of the second states
LAT.	70				
Х	0.00	212555.86	403501.10	tanan ay a sa sadanan in sadaya a did kilindan adjenih dala	
Y	1812374.71	1801410.01	1770424.38		
HER.	0.0351	0.1495	0.2695		
PAR.	0.5689	0.5421	0.4696		
ANG.	0.0000	79.6911	89.7728	A1 A 47 March	
LAT.	50				
X	0.00	402607.95	740325.02	976410.19	1108127.44
Y	1624884.83	1608607.03	1564559.07	1503979.25	1438497.17
MER.	0.3328	0.3861	0 4715	0.5142	0.5060
PAR.	0.7457	0.6845	0.5306	0.3475	0.1920
ANG.	0.0000	35.2465	55.0944	70.6413	89.7929
LAT.	50				
X	0.00	630323.72	1117097.50	1403461.63	1515120.17
Y	1018814.33	1016056.92	1008965.24	1000010.81	991240.37
MER.	0.7623	0.7612	0.7354	0.6673	0.5740
PAR.	0.9209	0.8069	0.5424	0.2668	0.0608
ANG.	0.0000	15.7277	26.8938	33.7398	43.8255
LAT.	40				
X	0.00	806833.61	1390891.78	1689227.46	1765997.41
Y	0.00	45373.60	157644.78	290943.11	413164.91
MER.	1.0000	0.9517	0.8301	0.6833	0.5482
PAR.	1.0000	0.8529	0.5357	0.2539	0.1310
ANG.	0.0000	0.7103	5.9601	24.3073	74.7379
LAT.	30				
X	0.00	838315.20	1438161.72	1736647.90	
Y	-1018814.33	-920859.00	-680129.73	-397325.71	
MER.	0.7623	0.7302	C.6481	0.5463	and not friday to t
PAR.	0.9209	0.7987	0.5438	0.3357	
ANG.	0.0000	17.1789	37.3981	65.2857	
AT.	20				
X	0.00	741045.79	1290611.26		
Y	-1624884.83	-1511575.70	-1227160.90		
HER.	0.3328	0.3572	0.3854		
PAR.	0.7457	0.6722	0.5137		
ANG.	0.0000	37.5277	66.9396		
LAT.	10				
*	0.00	597822.64			
Y	-1812374.71	-1714296.95		1 AND	and the second sec
HER.	0.0351	0.1408		1	
PAR.	0.5689	0.5304			
ANG.	0.0000	85,9367			

6.7 Example 5 - A general Projection Of An Ellipsoidal Datum

Example 5 illustrates a projection analogous to Example 4 with the exception that an ellipsoidal datum surface is utilized rather than a spherical datum surface. The same value of h, approximately 700 miles, is also used in Example 5. Therefore, Example 5 illustrates to a better approximation than Example 4 the projection of the actual meridians and parallels on the surface of the earth.

Equation (87) was again utilized in obtaining those intersections of meridians and parallels that are visible from the projection center. While equation (87) is an exact formula when dealing with a spherical datum surface, this equation is only an approximation when dealing with ar ellipsoidal datum surface. The author wishes to emphasize, however, that the calculated values are exact and the approximation only involves the determination as to which intersections are visible.

The following two pages illustrate a general projection of an ellipsoidal datum.

## PERSPECTIVE MAP PROJECTIONS

#### EXAMPLE 5 - GENERAL PROJECTION

## PROJECTION PARAMETERS -

CENTRAL LATITUDE = 40 DEGREES

**CENTRAL LONGITUDE = 90 DEGREES** 

HEIGHT OF PROJECTION CENTER = 1126542.900 METERS

FOCAL LENGTH (SCALE FACTOR) = 1125542.900 METERS

ELLIPSOID MAJOR SEMI DIAMETER = 6378388.000 METERS

ELLIPSOID FLATTENING = 1/297.0

 LONG	TUDE 90	80		60	
-2					
LAT.	70				
X	0.00	213247.66	404766.70		
Y	1812769.58	1801764.18	1770668.50		
MER.	0.0352	0.1507	0.2716		
PAR.	0.5685	0.5416	0.4690	walks (r) A the relativistic relativistic relation to a space and	
ANG.	0.0000	79.7439	89.8051		
LAT.	60				
X	0.00	403959.06	742643.99	979168.62	1110890.16
Y	1624973.58	1608639.02	1564450.96	1503710.60	1438096.83
MER.	0.3344	0.3881	0.4740	0.5167	0.5082
PAR.	0.7455	0.6842	0.5300	0.3466	0.1912
ANG.	0.0000	35.2851	56.1342	70.6878	89.9032
LAT.	50	A			
X	0.00	632220.67	1120121-61	1406725.49	1518077.95
Y	1018253.01	1015508.42	1008452.65	999549.64	990836.13
MER.	0.7637	0.7626	0.7366	0.6680	6.5744
PAR.	0.9209	0.8067	0.5416	0.2658	0.0600
ANG.	0.0000	15.7402	26.9041	33.7372	43.8693
LAT.	40				
X	. 0.00	808767.25	1393808.42	1692169.17	1768497.56
Y	-0.00	45482.34	157975.36	291449.78	413749.83
MER.	1.0000	0.9516	0.8297	C.6827	C.5475
PAR.	1.0000	0.8525	0.5349	0.2531	0.1307
ANG.	0.0000	0.7120	5.9752	24.3909	74.4825
LAT.	30				de 6 an o deservitiendeben a o samp cardono se
X	0.00	840043.44	1440743.42	1739222.20	
Y	-1016690.79	-918639.64	-677765.04	-394953.84	
 MER.	0.7627	0.7306	0.6483	6.5463	
PAR.	0.9211	0.7985	0.5431	6.3348	
ANG.	0.0000	17.1835	37.4138	65.3518	
LAT.	20				
X	0.00	742761.38	1293251.00		
Y	-1621426.01	-1508007.55	-1223424.93		
MER.	0.3339	0.3584	0.3865		
PAR.	0.7463	0.6725	0.5133		
ANG.	0.0000	37.5217	66.9340		
LAT.	10				
×	0.00	599603.54			
Y	-1809173.44	-1710917.70			
MEK.	0.0359	0.1418	444 - 46 - 16		
PAR.	0.5760	0.5311			
ANG.	0.0000	85.6795			

6.8 Example 6 - An Orthographic Projection Of An Ellipsoidal Datum

Example 6 is included as a final illustration of the utility of the mapping equations derived previously in this paper. The Orthographic Projection is a rather commonly used projection, but to the best of the author's knowledge a spherical datum surface is always used for this projection. Example 6 illustrates a Polar Orthographic Projection using an ellipsoidal datum surface. This type of projection more closely approximates the projection of the actual meridians and parallels of the earth than a projection using a spherical datum surface. Therefore, in this respect, it appears to be a superior type projection.

It can be seen that the properties noted in Example 3 are also evident in Example 6. As in Example 3, the linear distortions along the parallels and the angular distortions in the intersections of meridians and parallel are both equal to zero.

A disadvantage in using an ellipsoidal datum surface rather than a spherical datum surface is obviously the more complicated mapping equations required for the former. However, as the use of electronic computers increases, this disadvantage correspondingly decreases.

The following five pages illustrate an Orthographic Projection of an ellipsoidal datum.

## PERSPECTIVE MAP PROJECTIONS

## EXAMPLE 6 - ORTHOGRAPHIC PROJECTION

## PROJECTION PARAMETERS -

.

CENTRAL LATITUDE = 90 DEGREES

CENTRAL LONGITUDE = 90 DEGREES

HEIGHT OF PROJECTION CENTER = INFINITY

FOCAL LENGTH = INFINITY

ELLIPSOID MAJOR SEMI DIAMETER = 6378388.000 METERS

ELLIPSOID FLATTENING = 1/297.0

LONG	TUDE	E 90	80	70	36	50
	-					
LAT.	0	0.00	1107605 /6	2101517 10	214010/ 00	100019 70
A		-0.00	1107595.45	2101337.10	5109194.00	4099948.18
¥		6378388.09	6281485.95	5993724.14	5523840.04	4880128.08
MLR.		(.0.00	C.UGUC	0.0000	0.0000	0.0000
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	C.0000	0.0000	0.0000	0.0000
LAT.	10					
X		-0.00	1090879.16	2148612.51	3141061.36	4038070.65
Y		6282122.72	6186683.16	5903264.36	5440477.87	4812385.20
MER .		0.1736	C.1736	0.1736	C-1736	0.1736
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANC.		0.0000	0.0200	0.000	0.0000	C.000C
LAT.	20					
X		-0.00	1041208.76	2050780.92	2998041.13	3854207.39
Y		5996082.27	5904988.31	5634474.26	5192759.57	4593265.50
MER.		C.342J	6.3420	0.3420	C.342C	0.3420
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0400	0.0000	0.0000	0.0000	0.0000
I AT.	30					
X		-0.00	960012-87	1890856.23	2764246.89	3553667.30
Y		5528493.78	5444503.53	5195084.81	4787816.06	4235071.94
MER		0.5000	0.5000	6.5000	0.5000	0.5000
DAD		1.0(00	1.0000	1 0000	1 0000	1, 2020
FAR.		0.0000	0.0000	0.0000	1.0000	0.0000
ANG	10	0.0000	0.0000	0.0000	0.0000	0.0000
LAI.	40	c . 0.0	0.0.0.0	1/70/00 00	A	
×		-0.00	849648.17	10/3480.22	2440404.41	3145114.02
Y		4892928.82	4818594.24	4597849.11	4231400.66	3748200.93
MEK.		C.6428	0.6428	0.6428	0.6428	0.6428
PAK.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	3.6000	0.000	0.0000	0.0000
LAT.	50					
X		-0.00	713357.13	1405039.26	2054029.99	2640610.06
Y		4108059.98	4045049.32	3860313.65	3557684.31	3146956.52
MER.		0.7674	C.7674	0.7674	0.7674	0.7674
PAR.		1.0000	1.0000	1.0000	1.0000	1.0030
ANG .		0.0000	0.0000	0.0000	0.000.0	0.0000
LAT.	60			The state of the s	and the second se	
X		-0.00	555199.15	1093528.86	1598632.25	2055162.00
Y		3197264.49	3148690.86	3004445.85	2768912.27	2449246.70
MER.		3.8704	0.8704	0.8704	0.8704	C.8704
PAR.		1.0000	1.0300	1.0000	1.0000	1.00.00
ANG.		0.0000	0.0000	0.0000	0000.0	0.0000
LAT.	70		and the second			
X		-0.00	379949.37	748354.18	1094020.62	1406445.8
Y		2188341.24	2154799.98	2056086.21	1994899.30	1676136.84
MER-		0.9473	6-9470	0.9476	0.9476	6.9675
PAR		1.0.00	1.0000	1.0.00	1.0000	1.00.10
ANG		0.0.00	0.000	0.0000	6.0000	( 00.00
1 41	80	0.0000		300000		C. 0321
LATE	00	-0.00	102052 (1	190040 07	565611 07	314303 04
		1111221 0/	1004341 05	1044208 04	042242.14	114260.98
T NEG		0 10/ 2	1094341.99	1044208.94	702348.16	001240.93
MEK.		0.9942	0.9942	0.9942	0.9942	.9942
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
		1.01.00	1 6.616	0.0000	C. CO00	F. 00

81 -

LAT.	90					
X		-3.00	-0.00	-0.00	-0.00	-C.00
٧		0.00	-0.63	-0.00	-0.00	-0.00
MER.		1.1111	1.1111	1.1111	1.1111	1.1111
PAR.		1.1111	1.1111	1.1111	1.1111	1-1111
ANG.		1.1111	1.1111	1.1111	1.1111	1.1111
LAT.	80					
X		C.JU	192962.01	380060.97	555611.97	714280.28
Y		-1111223.94	-1094341.95	-1344208.94	-962348.16	-851246.93
MER.		6.9445	6.9942	0.9942	0.9942	2.3942
PAR.		1.0000	1.0000	1.0002	1.0000	1.0000
ANG.		2.0305	0.0000	2.0000	0.0000	0.0000
LAT.	70					
		J.59	379949.37	748 354.18	1094020.62	1406445.83
Y		-2188341.24	-2154799.98	-2056086.21	-1894899.30	-1676136.84
MEK.		6.9473	0.9470	3.9470	0.9470	0.9470
PAR.		1.0009	1.0000	1.0000	1.0000	1.0090
ANG.				C.0300	C.0055	C.000C
LAT	00			1001010 04	10000000000	
		0.00	222144.12	1073320.00	1340036.63	2033102.30
MEL		-319/209.97	-3144040.00	- 3099993.87	-2/08912.2/	-2999290.15
DAD.		2.3704	1.0000	1.0000		0.0114
ANC			1.0000	0.0000		1.0000
ANU		9.000V	0.0000	0. JULL	0.0010	0.0000
LAIN	30	0 00	711167 13	1405010 74	2*54:20 00	2440410 64
÷		-4108050.98	-4045449 17	- 1040313 45	-3567484 11	-1144464 52
MED		7.7676	0.7676	0.7674	C. 7676	- JL407 /00 /L
PAP.		1.0300	1.0000	1.0000	1.0000	1.0000
ANG		0.0360	0.0000	0.0000	0000	0.0010
LAT	40	3.0700				
X		3.00	844648-17	1673689.22	2446464.41	3145114.02
Ŷ		-4892928.82	-4818594.74	-4597849.11	-4237401.66	-3748202.93
HER.		0.6428	C.6428	C.6428	C.6428	6428
PAR.		1.0100	1.0000	1.0060	1.0000	1.0000
ANG.		0.0000	0.000.2	0.0000	5000.0	0.0000
LAT.	30					
X		0.00	960012.87	1890856.23	2764246.89	3553647.3.
Y		-5528493.78	-5444503.53	-5195084.81	-4787816.26	-4235371.94
MER.		0.5000	6.5000	C.5000	5.5000	0.5003
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0003	0.000.0	0.0000	0000.0	0.0000
LAT.	20					
X		0.00	1041208.76	2050740.92	2998641.13	3854207.34
Y		-5996082.27	-5904988.31	-5634474.26	-5192754.57	-4593265.53
MER.		3.3423	C.3420	C.342C	C.3420	ú. 3420
PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
ANG.		0.0000	6.0000	0.0000	C.COOC	0.000C
LAT.	10					
X		0.00	1093879.16	2148612.51	3141061.36	4038070.65
Y		-6282122.72	-0100003.16	-3903204.30	-3490477.87	-4012387.23
HER.		0.1736	0.1736	7.1736	1.0000	1. 1130
PAR.		1.0003	1.0000	1.0000	1.0000	
ANG.		7.0030	0.0003	0.0000	0.0000	0.0000

2)

	LAT.	0	¹² In description electrolization in advantary — the second or Million electrolization			ininger imperiesen en der eine Betreiten Betreiten Betreiten	
	×		4886128.68	5523846.04	5993724.14	6281485.95	6378388.30
	Y		4099948.78	3189194.00	2181537.18	1107595.45	0.00
	MER.		0.0000	0.0000	0.0000	0.0000	0.0000
	PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	C.0000	0.0000	0.0000	0.0000
1	LAT.	10			the second		
	x		4812385.20	5440477.87	5903264.36	6186683.16	6282122.72
	Y		4038070.65	3141061.36	2148612.51	1090879.16	0.00
	MER.		2.1736	6.1730	0.1736	0.1736	0.1736
	PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	20	and the second sec	and the distance of the second s			
	X		4593265.50	5192759.57	5634474.26	5904988.31	5996082.27
	Y		3854207.39	2998041.13	2050780.92	1041208.76	0.00
	MER.		0.3422	C.3420	0.3420	0.3420	0.3420
	PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	0.000.0	0.0000	0.0000	0.0000
_	LAT.	30	an analy way to a second a second of the second sec		uladig on sig i linger a say - sinte enter dabage which is a		
	X		4235071.94	4787816.06	5195084.81	5444503.53	5528493.78
	Y		3553647.30	2764246.89	1890856.23	960012.87	0.00
	MER.		0.5000	U.5000	0.5000	0.5000	0.5000
	PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	0.0000	0.0000	0.000	0.0000
	LAT.	40	and a second	gan gana akan da a a			
	X		3748200.93	4237400.66	4597849.11	4818594.24	4892928.82
	¥		3145114.02	2446464.41	1673480.22	849648.17	0.00
	MER.		0.6428	C.6428	0.6428	J.6428	C.6428
	PAR.	1.1	1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	0.0000	0.0000	0.0000	0.0000
	LAT.	50					
	X		3146956.52	3557684.31	3860313.65	4 34 50 49. 32	4108059.98
	Y		2640610.06	2054029.99	1405039.26	713357.13	-0.30
	MER.		0.7674	C.7674	0.7674	0.7674	0.7674
	PAR.		1.0000	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	6.0000	0.0000	0.0000	0.0000
	LAT.	60	and the second second		the second second second		the second s
	X		2449246.70	2768912.27	3004445.85	3148690.86	3197264.49
-	Y		2055162.00	1598632.25	1093528.86	555199.15	-0.00
	MER.		0.8704	0.8704	0.8704	0.8704	C.8704
	PAR.		1.0000	1.6000	1.0000	1.0000	1.0000
	ANG.		C.0000	C.0000	0.0000	0.0000	0.0000
	LAT.	10					
	X		1676136.84	1894899.30	2056086.21	2154799.98	2188041.24
	Y		1406445.80	1094020.62	748354.18	379949.37	-0.00
	MEK.		0.9470	6.9470	0.9470	0.9470	0.9470
	PAR.		1.0300	1.0000	1.0000	1.0000	1.0000
	ANG.		0.0000	0.0309	0.0000	0.0000	C.6030
	LAT.	80	0510// 03	0. 33 ( ) .	1011200 01	1304141 01	
	X		851246.93	902348.16	1044208.94	1094341.95	1111223.94
	Y		714280.98	555611.97	380060.97	192962.01	-0.00
	MER.		0.9942	0.9942	0.9942	0.9942	0.9942
	PAR.		1.0.00	1.0000	1.0000	1.0000	1.0000

LAT.	90			a		87 545 1170 517 1000 100011
X		-0.00	-0.00	-0.00	-0.00	-9.0
Y .		-0.90	-0.00	-9.90	-6.00	-C.
MER.		1.1111	1.1111	1.1111	1.1111	1.111
PAR.		1.1111	1.1111	1.1111	1.1111	1.111
ANG.		1.1111	1.1111	1.1111	1.1111	1.111
LAT.	80					
X		851246.93	962348.16	1044208.94	1094341.95	1111223.9
Y		-714280.98	-555611.97	-380060.97	-192962.01	-2.0
MER.		C.9942	C.9942	0.9942	0.9942	0.994
PAR.		1.0000	1.0000	1.0000	1.0000	1.000
ANG.		0.0(00	0.0000	0.0000	0.0000	0.000
LAT.	76		name and the Mark of Mark and the	anana anana ana an an an an an an an an		
Y	1.0	1676136.84	1894899. 10	2056086.21	2154700.08	2188041.2
		-1404445 83	-1004020 62	-769356 19	-170040 27	-0 (
MCD		-1406449.85	-1074070102	0 0470		
MEK+		0.9470	1.0000	0.9410	1.0000	1.000
PAR .		1.0000	1.0000	1.0000	1.0000	1.000
ANG.		0.0000	0,0007	0.0000	0.0000	0.000
LAT.	60					
X	-	2449246.70	2768912.27	3004445.85	3148690.86	
Y		-2055162.00	-1598632.25	-1093528,86	-555199.15	-0.0
MER.	shared systems of the	0.8704	0.8704	0.8704	C.8704	0,870
PAR.		1.0000	1.0000	1.9000	1.0000	1.000
ANG.		0.0000	0.0000	C.COOC	0.0000	0.000
LAT.	50					
X		3146956.52	3557684.31	3860313.65	4045649.32	4108059.9
Y		-2640610.06	-2054029.99	-1405039.26	-713357.13	-0.0
MER.		C.7674	0.7674	0.7674	C.7674	0.767
PAR.		1.0000	1.0000	1.0000	1.0000	1.000
ANG.	A Ar	0.0000	C.0200	0.0000	0.000.0	0.000
LAT.	40					
X		3748200.93	4237400.66	4597849.11	4818594.24	4892928.8
		-3145114.02	-2446464.41	-1673680.22	-849648.17	0.0
MED.		0.6428	0.6428	0 6428	1. 6628	6 663
DAD	*****	1 0.0120	1.0010	1 0000	1.0000	1 002
ANC		0.0000	0.0000	0.0000	0.0000	6.000
ANG	20	0.0000	0.0000	0.0000	0.0000	0.000
LAIS			1707014 04	5105001 01		6530/03 3
-		4233071.94	4/0/010.00	2192004.01	2444203+23	2220493.1
T		- 3333647.39	-2104246.89	-1890856.23	-900012.87	U.L
MER.		0.5000	0.5000	0.5000	0.5000	0.57
PAR.		1.0000	1.0000	1.0000	1.0000	1.000
ANG.		0.0000	0.0000	0.0000	0.0000	0.000
LAT.	20					
X		4593265.50	5192759.57	5634474.26	5904988.31	5996082.2
Y		-3854207.39	-2998041.13	-2050780.92	-1041208.76	0.0
MER.		0.3420	0.3420	0.3420	6.3420	0.342
PAR.		1.0000	1.0000	1.0000	1.0000	1.000
ANG.		0.0000	0.0000	C.000C	0.0000	0.000
LAT.	10	and the second se	an a			
X		4812385.20	5440477.87	5903264.34	6186683.16	6282122.7
Y		-4038070.65	-3141661.36	-2148612.51	-1090879.16	0-1
MER		0-1736	6.1736	0.1736	6.1736	0.174
PAR		1.0.100	1.0000	1.0000	1.0000	1.000
ANG	-	0.0000	0.0000	0.0000	0.0000	0.000
		0.0000	0.0000	0.0000	0.0000	0.010

### 7. SUMMARY AND CONCLUSIONS

The primary goal of this paper, as stated in the Introduction, was to develop general mapping equations for the perspective projection which would be suitable both for spherical and ellipsoidal datum surfaces. A careful method of proceeding from the known to the unknown was utilized in developing the desired equations. First, mapping equations for selected perspective projections of a spherical datum surface were derived utilizing already validated methods. Next, mapping equations for a spherical datum surface were derived by a novel photogrammetric method. These mapping equations were proved equal to those derived earlier. After having at least partially proved the photogrammetric method to be valid by its use on a spherical datum surface, this method was used to derive mapping equations for an ellipsoidal detum surface. Equations (78) and (81), the General Perspective Projection Mapping Equations, were the results of the derivation. Equations (78) and (81) were proved to be general equations encompassing all the special cases that had been discussed prior to their derivation. It is evident from the derivation of these equations that they could be made to be even more general by providing for the possibility that the arbitrary point P that is to be projected is not on the datum surface but at some distanc: above or below it. The alteration to equations (78) and (81) to take into consideration this distance would be accomplished by first changing the coordinates of point

P, as given by equations (62), (63), and (64), to account for the distance and then by using these new coordinates in the remainder of the derivation. Finally, as a means of vizualizing certain perspective projections, an empirical method was developed to compute various distortions in the projections and examples of several projected grids were illustrated.

The author believes that equations (78) and (81) derived in this thesis are useful equations in that they are truly General Perspective Projection Mapping Equations suitable for both spherical and ellipsoidal datum surfaces that can be used regardless of the location of the projection center.

## APPENDIX

The computer programs utilized to produce all examples included in this thesis were basically very similar. The actual equations used to calculate the desired data were identical in all the examples, and the primary differences in the programs concerned format. Thus, although this appendix is devoted to an explanation of the computer program used to produce Example 5, it essentially explains the computer programs used for all the included examples. The IBM 7094 computer of the Ohio State University was employed to produce the examples; and the programming language used was SCATRAN, a program language taught and used at Ohio State University.

A complete and detailed explanation of the program will not be given, but sufficient explanation will be given to allow the reader to understand the general principles of the program. A more thorough discussion of the computer program is not being presented due to the authors belief that the program is not an end product but only a tool that was used to illustrate and verify the concepts developed in this thesis.

In succeeding paragraphs, first the major terms used in the program will be identified, and then the functions of the Source Language Statements will be explained. The program itself is included at the end of this appendix.

The following is a list of the major terms that were

components of the program used to produce Example 5 of this thesis:

X - the abscissa or X coordinate of a particular point in meters
Y - the ordinate or Y coordinate of a particular point in meters
V - a longitude value used in printing out the grid format
W - a latitude value used in printing out the grid format
INP - an angular distortion in the intersection of a meridian and

a parallel

- RDM a ratio of a meridian distance on the projection plane to a meridian distance on a datum surface
- RDP a ratio of a parallel distance on the projection plane to a parallel distance on a datum surface

RAD - a conversion factor to convert degrees to radians

A - the sphere radius or ellipsoid semi-major axis in meters

FLAT - the ellipsoid flattening

- EC the height of the projection center above the datum surface in meters
- F the distance between the projection center and the projection
   plane in meters

BC - the central latitude in degrees

BP - the latitude of a particular point in degrees

LC - the central longitude in degrees

LP - the longitude of a particular point in degrees

DEGCH - a small number of degrees used to locate a point very close

to a primary point. In the following definitions the

primary point, which is the intersection of a particular meridian and a particular parallel, will be identified as  $P_0$ . Figure 16 illustrates  $P_0$  and its relationship to  $P_1$  and  $P_2$ .

BPRB - the latitude of P in radians

LPRL - the longitude of  $P_2$  in radians

U - a term used to indicate the computation of an Orthographic

Projection. When an Orthographic Projection is being calculated,

U is set equal to 0 and F is set equal to 1.

E2 - the square of the eccentricity of an ellipsoid

Al, Bl, Cl, Dl, El, Fl - terms used in equation (83)

- NP the radius of curvature in the prime vertical at a particular point
- NC the radius of curvature in the prime veritcal along the projection axis

.

NPB - the radius of curvature in the prime vertical at  $P_1$ 

DENOM - the denominator of equations (78) and (81)

XB - X coordinate of P

YB - Y coordinate of P

DENO - the denominator of equations (78) and (81) used to calculate XB and YB

XL - X coordinate of P2

YL - Y coordinate of P

DEN - the denominator of equations (78) and (81) used to calculate XL and YL **DXB** - the absolute difference in the X coordinates of  $P_0$  and  $P_1$ **DYB** - the absolute difference in the Y coordinates of  $P_0$  and  $P_1$ 

AB - the arctan of  $\frac{DYB}{DXB}$ 

DXL - the absolute difference in the X coordinates of  $P_0$  and  $P_2$ DYL - the absolute difference in the Y coordinates of  $P_0$  and  $P_2$ 

AL - the arctan of 
$$\frac{DYL}{DXL}$$

DMM - the distance on the projection plane between  $P_0$  and  $P_1$ DPM - the distance on the projection plane between  $P_0$  and  $P_2$ DME - distance on the datum surface between  $P_0$  and  $P_1$ DPE - the distance on the datum surface between  $P_0$  and  $P_2$ 

The following is a brief explanation of the Source Language Statements of the program included at the end of this appendix: 1 - 35 : set up the projection parameters and are self explanatory

when considered with the term (effinitions given above 36 - 45 : calculate the X and Y coordinates of  $P_0$ 46 - 71 : check the location of  $P_0$  to determine if it is visible

from the projection center

72 - 80 : calculate the X and Y coordinates of  $P_1$ 

81 - 87 : calculate the X and Y coordinates of  $P_{2}$ 

88 - 105 : calculate the angular distortion in the projected

intersection of a parallel and a meridian 106 - 116 : calculate the meridian and parallel linear distortions 117 - 153 : dictate the size and shape of grid to be computed

154 - 159 : calculate the longitude values that will be used for

column headings in the grid

160 - 167 : print out the projection parameters

168 - 197 : print out the numerical grid

The program contained on the next seven pages was used to produce Example 5 of this thesis.

INTÉGERS       IT. UV.V.40C)-         FLORTING       ILCALTER, MAR. J. M. J. L. YL, JEN, J. M. J. L. YL, JEN, J. M. J. L. YL, JEN, JEN, JEL, DEL, DEL, DEL, DEL, DEL, DEL, DEL, D		DIMENSION (X(190,11),Y(190,11),V(10),M(19),IMP(190,11),XDM(190,11),XDP(190	
FLOATING       LCALIMA.W.MG. (MP., MP.). (MP., JEL.).         PRECISION       C.C.L.MA.W.MG. (MP., ML., ML., ML., ML., ML., ML., ML., ML		INTEGERS (T.U.V.W.BC)-	
RECISTOR 12.1.1.7.4.4.4.0.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1	i	FLOATING (LCR.LPR.NP.NC., IMP.NPB.LPRL, IFL)-	
RAD-J.1419726535/L9C.0-         Le378386.200-         IFL=297.0-         FLAT-LL0/IFL-         HCT-LL0/IFL-         HCT-LL0/IFL-         HCT-LL0/IFL-         HCT-LL0/IFL-         HCT-LL0/IFL-         HCT-L20/IFL-         HCT-L20-         HCT-		PRECISION (2,x,Y,RAD,F,A,FLAT,E2,8CR,8PA,LCR,LPR,MC,NP8,DENDM,NP,NC,DSIN, ,x8,y8,dx8,dy8,a8,dx1,dy1,al,daīan,,x1,y1,den,imP,dmm,dpm,dpe,dme,al,e Pri,8Pr2,8CR1,f1,ds0x7,)-	COS.,CHECK,DENO,BPRD,LPAL .Cl,Dl,El,RDM,RDP,CHECK,B
<pre>4-6378366.500- ifile297.6-</pre>	-	RAD=3.1415926536/190.0-	
IFL=207.0-         FLAT-1.0/IFL-         HG-1126542.9-         F+HC-         HG-1126542.9-         F+HC-         BGCH00.00001-         DEGCH00.00001-         DEGCH00.00001-         District         E2-2*FLAT-FLAT.2.2-         I1+10-         A1-1.001.5/4.0)=622462-625-622-622-622-622-622-622-622-622-6		A=6378388.000-	(a) is common .
FLAT = 1.0/1FL- HC = 11.06x2:9- HC = 11205x2:9- F+HC - EC = 400- LC = 90- LC = 90- LC = 90- LC = 90- LC = 90- LC = 90- LC = 10- LC = 10-LC = 10- LC = 10-LC = 10- LC = 10-LC		Ift=297.0-	
HC=1126542.9- F#C- BC=40- LC=90- DEGG+e0.00001- U=1- E22*FLAT-FLAT.P.2- 11=10- A1=1.0*(+.0)=E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E11025.0/16394.0)=E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E		FLAT=1.0/1FL-	ananan undari inda inda inda inda inda inda inda ind
F=HC- BG=4G- LC=90- DEGCH=0.00001- U=1- E2=2FLAT-FLAT.P.2- I1=+10- 3536.0)+E2=E2=E2=E2=C2+(175.0/256.0)+E2=E2=E2+(11025.0/15394.0)+E2=E2=E2+E2+(43659 1==1.004.0)+E2=E2=E2=E2=C2+(175.0/256.0)+E2=E2=E2+(11025.0/16394.0)+E2=E2=E2=E2=C2+(43659 1==1.004.0)+E2=E2=E2=E2=(2105.0/555.0/512.0)+E2=E2=E2=(210395.0/16394.0)+E2=E2=E2=E2=E2=E2=E2=E2=E2=E2=E2=E2=E2=E		HC=1126542.9~	a mumania
66.46- LC+90- DEGCH-0.00001- U+1- E2=2*FLAT-FLAT.P.2- [1=10- ]= E2=2*FLAT.P.2- [1=10- ]= E2=2*E145.0/4.0) *E2*E2*175.0/256.0] *E2*E2*E2*(11025.9/16334.0) *E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*		FaHC-	
LC=90- DEGCH=0.00001- U=1- E2=2*FLAT-FLAT.P.2- I1=10- A1=1.0*13.J/4.0J+E2*145.D/64.0J+E2*E2*1175.0/256.0J+E2*E2*E2*111025.J/15334.DJ+E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E		BC=40-	
DEGG+=0.00001- U=1- U=1- E2=2*ELAT-FLAT.P.2- 11=10- A1=1.0+1.3.2/4.0)*E2*E2*E2*E2*E2*(175.0/250.0)*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*E2*		-06-07	
U+1- E2=2+FLAT-FLAT.P.2- 11=10- 3536.3)+E2+E5+E2+E2+E2+E2+1175.0/256.0)+E2+E2+E2+E2+11025.0/16334.0)+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+		DEGCH=0.00001-	
E2=2+FLAT-FLAT.P.2- 11=10- A1=1.0+13.:2/4.0)=E2+45.0/64.0)=E2+E2+1175.0/256.0)=E2=E2+E2+(11025.0/16334.0)=E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E		-1=D	
I1=10- A1=1.0+15.2/4.0)+E2+E2+E2+E2-E2+E2+1175.0/256.0)+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+		E2=20FLAT-FLAT.P.2-	
Al=1.0+(J.:2/4.0)+E2+(45.0/64.0)+E2+E2+(175.0/256.0)+E2=E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E		11=10-	
Bl=(3.0/4.0)+E2+(15.0/16.0)+E2+E2+(525.0/512.0)+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+		Al*1.0+(j.2/4.0)+E2+(45.0/66.0)+E2+E2+(175.0/256.0)+E2+E2+(11025.0/16334 5536.0)+E2+E2+E2+E2+E2-	01+E2+E2+E2+E43659+3 <u>/6</u>
Cl={15,J/64.0}=E2+E2+(135.0/256.0)=E2+E2+(205.0/4096.0)=E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E		B1={3.0/4.3}+E2+{15.0/16.0}+E2+E2+{525.0/512.0}+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+8.2}+E2 }+E2+E2+E2+E2+E2+E2-	€2•E2•E2•L72 <u>765</u> •Q1655 <u>3</u> 6•Q
01=(35.0/512.0)+E2+E2+E15.0/2048.0)+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+E2+		Cl={15.3/64.0}*E2*E2*{135.0/256.0}*E2*E2*E2*E2*{235.3/4096.0}*E2*E2*E2*E2*E2*E2*E2*E2*E2*5.10 *E2-	!95 <b>•</b> 2/15384 <b>•</b> 31•E2•E2•E2•E2
El≈f315.0/16384.0)•E2*E2*E2*E3*f3465.0/65536.0)•E2*E2*E2*E2*E2*E2 F1≈(693.0/131072.0)*E2*E2*E2*E2* RCK*BC*RAU- LCR*LC*RAD- f=9-		01=(3.0/512.0)+E2+E2+E2+(315.0/20+8.0)+E2+E2+E2+E3+13135.0/131072+0)+E2+E	-62-62-62-
F1=(693.0/131072.3)•E2•E2•E2•E2•E2- 8Ck=8C∘R≜U- LCR=LC•R≜O- 1=9-		El¤(315.0/16384.0}+E2*E2*E2*E2*(3465.0/65536.0)*E2*E2*E2*E2-E2-	
ጽርጽ∍ፅርቀጽÅ⊍- ሀርጽ∗ԼርቀጽÅD- 1s9-		fl=(693.0/131072.01•E2•E2•E2•E2•E2•E2•E2•E2•	ng tang tang tang tang tang tang tang ta
L CR=L C+R & D- I =9-		8Ck*8C *RAU-	
[s9-		LCR*LC+RAD-	
		-6=]	
H(1)=8C-		W11)=8C-	· · · · · · · · · · · · · · · · · · ·

THE THE REPORT OF A DECK OF A DECK OF A

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LAUBSI	CHER. A.	JOB BEA25ù 05/05/65 119018 PAGE 5
22		1aG-
28		L=C.O-
54		AP#8C-
30		
16		-1+1-
32		- 0 0
		dPk]=dq.4ek&D-
*		8PR2=-89.9eR4D-
35		6CR1 = 39.3 = R4C-
96	574871	-C1-1-1-1-1-C-1-1-1-1-1
37		LPK=10.00 JeR4D=13+180.0084D0-14-
36		*###4/1059%f.fl-52+051N.f8PR1.w.21)-
53		%C=3/{D5GKf.fl=E2.05IM.fBGkj.p.2]}-
34		PACVIDED [U.L.1]. TRAVSFEM TO TORTHOJ-
15		∪E*inM≠VC+f1-E2+051N.fRCq).P.2]-NP+{0C05.f8Cq}+0C05.f8Pq}+0C05.fLPq)+f1-E2]+051N.f8Cq1+051N.f8Pq})+++C-
42		FRANSFER TO ILALCI-
5	DATHO	-?*l=aut30
;	CALC	#(1,J)={Fe'Pe(COS.(8PH)eUSIN.(LPR))/DENDM-
54	1 1/10	Y([.J]=(F+{AC+2+US1+,[9CR]+UCD5,[8CR]+NP+1(]-E2]+DCO5,[8CR]+DS1N+(8PR]-D51N+(8CR]+DCD5,(8PR)+DCO5,(1 P41)])/UEVUM-
••		PAIVIDED (3PR.G.49.C+MAD). TRAVSFER TO (800901-
4 7		PHOVICEU (HPH.L39.C+MAD), MANSFER TO (NOM90)-
4.5		PPDVIUED 14C2.G.49.D.*RANSFER TO INCP9CI-
6.9		CHECk=(A/fä+HC)-USfN, (BCR1+DSfN, (BVR1)/(DCOS, (BCR1+DCOS, (BPR1)-
ŞC		TRAISFER TH ICHERI-
15	05dda	PROVIDED (3C4.6.39.9*RAD), FRANSFER TO (8CP)-
\$2		CHECK=[1/[1+HCJ-D5]N,[8CR]+C5]N,[3P2]]/[DCOS.[8CR]+DCOS.[8PA]]]-
53		TRANSFER TO ICHER
*5	BCP	CHECK=[A/[A+HC]-DS]N.[BCR]+DS]N.[BPR]]/[DCOS.[BCR]]+DCOS.[BPR]]]-
\$\$		TRANSFER TO (CHER)-

~		PRUVIDED (BLA.G.BV.YORAD), TRANSFEE TO (BCM)-	
		CHECK=(A/(4+HC)=DS IN_(ACB)=DSIM_(ABB)//(NCOC_(ACB)=DCOC_(ABB)//	and the second sec
-		TRANSFER TO (CHEK)-	
	904	CHECK=(A/(A+HC)-DSIN.(BCR)+DSIN.(BFR))/(DCOS.(BCR1)+DCOS.(BFR2))-	
0		TAANSFEA ID ICMENI-	
-	56-36	PROVIDED (8PR.6.89.9.4AD). TRAMSFER TO (8CP)-	and the second design of the s
N		PROVIDED (BPR.LB9.9-RAD), TRANSFER TO (BEM)-	de la de deuron de uno de la
•		CHECK+(4/14+HC)-DSIN.(BCR)+DSIN.(BPR))/(DCOS.(BCR))+DCOS.(BPR))-	a a
	CHER	PROVIDED (DCOS.ILPA).GE.CHECK). TRANSFER TO LANDIS)-	
•		-61616181*(f*1)x	
•		-61614161+16*114	
~		PROVIDEU (J.L.S), TRANSFER TO (PAGE2)-	
æ		TAANSFER TO TTGUT-	
•	P4652	k*5-	
0		<pre><!--!</td--><td></td></pre>	
		TRANSFER TO (TSC)-	
~	A1015	ePubespactueGCHetaDeDCOS.(BPA))-	
-		PROVIDED 14PR.5.89.9.RAD.OR.8PR.L89.9-RAD), TRANSFER TO (DUT)-	
		WPH=A/(050HT.(1-E2-051N.(8PRH).P.21)-	
\$		PROVIDED (U.L.1). TRANSFER TO (DATH)-	
٥		DE 40=4C+11-22+DS14+18CR1.P.23-4PB+10C05+18CR1+0C05+18PRB1+0C05+1LPR1+11-E21+0514+18CR1+051 C-	N. (8998)). I
~		TAANSFER TO (CAL)-	
æ	-110	0END=1.C-	
	CAL	x8=[f.up8+DCOS.[8##8]+DSIM.[LP3]]/DEND-	
o		Ya= (Fe1vC+E2+051v, (BCR)+6COS, (3CR)+NPB+({1-E2)+0COS, (BCR)+0SIN, (BPRB)-05IN, (BCR)+0COS, (BPR   a)))/0Ev0-	B)+DCOS.(LP
-		LPRL=LPR+UUEGCH+RAD1-	
N		PROVIDED (U.L.1), TAANSFER TO (DAT)-	

210
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LAUBSCHE	ER. A.	JOB BEA250 05/05/65 119018 PAGE 8	
112	1	TRANSFER TO (LOOP)-	
113 0	DUT	-1111-1-11.11H	
•11		RDM(1.J)+1.1111-	
115		ROP(1,.1)=1.1111-	
110 1	100	CONTINUE -	
117 1	160	PROVIDED (1.6.0). TRANSFER TO (TG1)-	
118		BPR=BPR+[10.0+RAD]-	
611		PROVIDED LIBPR/RADI.G.91.31. TRANSFER TO (TEL)-	
120		-I+I+I-	a de la constante de
121		PROVIDED (1.6.18), TRANSFER TO (TE2)-	- and p definition of a straight definition, and straight the straight of t
122 #	.1540	M(1)=8PR/MAD-	
123		TRANSFER TO (STARTI)-	
124 1	101	PROVIDED (1.G.1), TRANSFER TO (TG2)-	
125		TRANSFER TO LUPHICI-	
126 1	161	Tst-	
127		[ ]=-[-	
128		[4e]-	
129		₩₽K = B₽K - 13. C + K 40-	An a second provide the second se
13C 8	01-46	8PR=HPK-13.C+RAD-	
161		= + -	
132		PROVIDED (1.6.181, TRANSFER TO (162)-	
661		TRANSFER TO (MIEBP)-	
134 1	162	PROVIDED (1.6.2). TRANSFER TO (BPP12)-	
135		TRANSFEM TO IBPM1021-	
136 T	TC2	f = 2 -	
101		13=1- 13=1-	
1 36		14±C -	
139		-6s]	
140		8PR=8CR-	
			eter en la

41 BP#102	BPR=BPR-(10.0+RAD)-
*2	PROVIDED (BPR/RAD.L91.0), TRANSFER TO (TE3)-
++	PROVIDED [1.L.O], TRANSFER TO (WRITE)-
45	TRANSFER TO (MIEBP)-
46 TE3	[a]-
47	[]3•-[-
48	-[tel-
67	6P2=3PR+[13.0+RAD]-
01048 35	8PR=8PR+[1C.C+2A0}-
51	-[=]=.
52	PROVIDED (1.L.D), TRANSFER TO (WRITE)-
53	IAANSFER TO (MIEBP)-
54 WRITE	1 s C -
\$\$	V(I)*LC-
14131 95	• • •
57	PROVIDED (1.6.9), TRANSFER TO (FINAL)-
58	V([]*.485.[V(]-])-]0]-
59	TAANSFER TO ILEPPID-
AC FIVAL	WRITE NO HEADING , FORM90-
61 F FURM90	[[H]////////334,27HPERSPECTIVE MAP PROJECTIONS/] -
62	WAITE OUTPUT .FORMSI-
63 F FORMOL	(32x,3CHEXAMPLE 5 - GENERAL PROJECTION//////) -
64	waite Durput .FORM92,18C,LC,MC,F1-
65 F FURM92	(22x,23HPROJECTION PARAMETERS -//33x,19HCENTRAL LATITUDE = ,13,8M DEGREES//33x,22HCENTRAL LONGITUDE = ,13,8H DEGREES//33x,30HHEIGHT OF PROJECTION CENTER = ,0F13.3,7H METERS//33X,30HFDCAL LENGTH 1SCA LE FACTOR) = ,0F13.3,7H METERS/)
••	weite Output "Form94, (A, IFL)-
67_F FORM94	(33X,32HELLIPSOID MAJOR SEMI DIAMETER - ,DE13.3,7M METERS//33X,25HELLIPSOID FLATTENING - 1/,F5.13

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