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## SOLUTION TO THE BINARY DIFFUSION LAMINAR BOUNDARY LAYER EQUATIONS INCLUDING THE EFFECT OF SECOND-ORDER TRANSVERSE CURVATURE

N. A. Jaffe, R. C. Lind, and A. M. O. Smith Douglas Aircraft Division a Division of Douglas Aircraft Company, Inc. Long Beach, California

February 1967

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#### FOREWORD

The research reported herein was sponsored by the Arnold Engineering Development Center, Air Force Systems Command, under Program Element 62405334, Project 8953, Task 895303 and 895306. The work was performed by Douglas Aircraft Division, a division of Douglas Aircraft Company, Inc., Long Beach, California, under Purchase Order 5A-9405 that was made under the provisions of Prime Contract AF40(600)-1000 between the U. S. Air Force and ARO, Inc. (a subsidiary of Sverdrup & Parcel and Associates, Inc.), operating contractor of AEDC, AFSC, Arnold Air Force Station, Tennessee.

The reproducibles supplied by the authors were used in the reproduction of this report. The Douglas Aircraft Division report number is LB 32613.

The authors express their gratitude to Mr. Donald Baron for his painstaking efforts in programming the equations. In addition, Mr. David Callin is acknowledged for checking many of the numerical results.

This technical report has been reviewed and is approved.

Carl E. Simmons	Edward R. Feicht
Captain, USAF	Colonel, USAF
Directorate of Plans and Technology	Director of Plans and Technology

#### 1.0 SUMMARY

This report presents a numerical method for solving the binary diffusion laminar boundary-layer equations. The differential equations of continuity, momentum, energy, and species diffusion are solved simultaneously for two-dimensional or axisymmetric flow. For the case of axisymmetric flow the second-order transverse curvature terms appearing in the equations are retained.

Relations for mixture fluid properties as functions of local conditions in the boundary layer are developed and used in obtaining solutions to the equations. The mixtures considered in this investigation are He - air, Ar - air, and  $CO_2$  - air.

Solutions to the equations are given for flow of a pure air free stream over a  $9^{\circ}$  half angle cone at a free stream Mach number of 10 and free stream Reynolds number, based on cone slant length of 940. The initial section of the cone is solid and mass injection is initiated at a location downstream of the tip. Results are presented and compared for calculations both including and neglecting the second-order transverse curvature effect.

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С	ρμ/ρ <sub>e</sub> μ <sub>e</sub>
C <sub>p</sub>	constant pressure specific heat of mixture
°°р <sub>f</sub>	constant pressure specific heat of species f
cv	constant volume specific heat of mixture
cvf	constant volume specific heat of species f
° <sub>f</sub>	mass fraction of free stream species, $\rho_{\rm f}/\rho$
°i	mass fraction of injected species, $\rho_i / \rho$
$D_{f}^{T}$	thermal coefficient of diffusion
D <sub>fi</sub>	binary diffusion coefficient
f	stream function (equation 16)
g	dimensionless enthalpy ratio H/He
н	total specific enthalpy of mixture
h	static specific enthalpy of mixture
<sup>h</sup> f	static specific enthalpy of species f
к <sub>1</sub>	bound on trial solutions of momentum equation
к <sub>2</sub>	bound on trial solutions of energy equation
k	Boltzmann constant
L	reference body length
Le	Lewis number $\rho D_{fi} C_p / \lambda$
M <sub>f</sub>	molecular weight of species f
м <sub>fi</sub>	reduced molecular weight of species f and i
n	count of successive steps in transformed x direction

Р	pressure
Pr	Prandtl number $\mu C_p / \lambda$
R'	universal gas constant
r	distance from axis of symmetry to location in the boundary layer
S т	dimensionless concentration parameter (see equation 27)
t	transverse curvature parameter (see equation 25)
u	velocity component in x direction
v	velocity component in y direction
$\overline{\mathbf{v}}$	transformed velocity (equation 8)
$\mathbf{x}_{\mathbf{f}}$	mole fraction of species f
x	direction along surface measured from leading edge or stagnation point
у	direction measured normal to surface
2	mass fraction ratio $c_{f}/c_{f}$
β	dimensionless velocity gradient (see equation 26)
٤ ٤	convergence criterion for momentum equation
٤Z	convergence criterion for energy equation
<b>•</b> 3	perturbation of initial condition on energy equation
<b>η</b> ,η	transformed y coordinate
$\eta_{\infty}$	maximum value of $\eta$ used in numerical solution
λ	thermal conductivity of mixture
$\lambda_{f}$	thermal conductivity of species f
μ	viscosity of mixture
۴f	viscosity of species f

-

ρ	mass density of mixture
<u>ξ</u> ,ξ	transformed x coordinate

#### SUBSCRIPTS

e evaluated at edge of boundary layer
f evaluated for species f
i evaluated for species i
n evaluated at station n
w evaluated at surface

 $\infty$  evaluated at free stream conditions or see  $\eta_{co}$ 

Primed quantities denote differentation with respect to  $\eta$  or  $\overline{\eta}$ ; barred quantities refer to variables based upon transformation given by equations (6), (7), and (14), (15).

#### 5.0 INTRODUCTION

This report describes a general method for solving the laminar diffusion boundary-layer equations for a binary gas mixture. The primary object of this investigation has been the development of an exact method of solution to the governing flow equations applicable to arbitrary twodimensional or axisymmetric shapes and a wide range of flow conditions, such as might be incurred during wind tunnel tests or actual flight conditions.

Significant contributions, which are briefly reviewed here, to the field of analysis of the binary diffusion laminar boundary-layer equations have been made by Baron, Covert, Culick, and co-workers at MIT. Baron (reference 1) developed the basic equations describing the binary mixture laminar boundary layer and solved them for the case of similar flows with zero pressure gradient, solutions were given for Schmidt number and Prandtl number of unity. An integral method was used to obtain the effect of mass transfer downstream of the injection point. Cases were computed for injection of helium and carbon dioxide into air. Covert (reference 2) developed an approximate integral method, valid for small injection rates, which could be employed without the use of large scale computers. Baron and Scott (reference 3) extended the analysis to flows with pressure gradients; this study was restricted to similar flows. Cases were computed for injection of helium over a temperature range for which the vibrational relaxation contribution to the heat capacity was neglected. A more general analysis of the . problem (viz, not restricted to similar flows) was made by Moran and Scott

(reference 4). The equations were solved in terms of Crocco variables using a finite-difference technique developed by Flügge-Lotz and Baxter (reference 5). The method requires starting profiles and is apparently not capable of handling large changes taking place in the streamwise direction. Again a helium - air mixture was considered over a temperature range for which vibrational relaxation of the air molecules could be ignored. Covert's method was extended by Moran (reference 6) to flows over a porous cone with solid tip. In reference (7) Culick developed an integral method to solve the diffusion equation for zero pressure gradient flows. Velocity and enthalpy profiles are required for this method which was applied to flows with helium injection into air. Subsequently, Culick (reference 8) developed a method for zero pressure gradient flows. This is also an integral method. It utilizes integral relations between heat and surface mass transfer and does not require a previously obtained solution to the energy equation. Results are presented for both helium and air injection.

The previous studies were primarily concerned with the application of mass injection for cooling; moreover, the second-order transverse curvature terms for axisymmetric flow were not included in the equations. Recent experimental measurements with mass injection of helium and air into air (references 9 and 10) in hypersonic flow over slender cones indicates that mass injection has a marked effect on drag coefficients as well as heat transfer. The results reported in references (9) and (10) were for low Reynolds number flows and the total drag was predominantly skin friction drag. Hence, it is to be expected that solutions to the boundarylayer equations for flows with mass transfer will prove valuable for the

prediction of the effects of mass injection on drag coefficients in certain flight regimes. In addition, results reported in references (9), (10), and (11), which were based upon measurements for hypersonic flow over slender cones, indicate that the transverse curvature effect may be significant. The theoretical methods used to treat this effect in the above references were not exact; hence, to gain more insight into the problem, the second-order transverse curvature terms appearing in the boundary layer equations have been retained in the present investigation.

A numerical method based on ideas originated by Hartree and Womersley (reference 12) is used to solve the flow equations. The method has been developed for solution of the incompressible laminar boundarylayer equations (reference 13), the compressible laminar boundary-layer equations (reference 14), and the laminar boundary-layer equations of a binary nonequilibrium dissociating gas (reference 15). The primary differences between the work described in this report and that described in reference (15) are the mathematical transformations used and the mixture fluid properties incorporated in the computer program. The computer program developed makes it possible to include or neglect the second-order transverse curvature terms appearing in the equations.

Numerical results for injection of helium, argon, and air into air for flow over a 9<sup>°</sup> half-angle cone at a Mach number of 10 and free-stream Reynolds number based on slant length are given. The free stream conditions are within the range of test conditions of the AEDC-VKF Low Density Tunnel L.

#### 6.0 ANALYSIS

#### 6.1 Basic Equations

The laminar boundary-layer of a binary gas mixture with no chemical reactions is considered for two-dimensional or axisymmetric flow. The actual mixtures studied are: He - air, Ar - air, and  $CO_2$  - air. Although thermal diffusion is neglected in the numerical calculations it is retained in the development of the equations. The second-order transverse curvature terms are retained and handled through use of a transformation introduced by Probstein and Elliott (reference 16.) The equations are further transformed to the form in which they are finally solved through use of the Levy - Lees transformation (reference 17). The final equations resulting from the combined Probstein-Elliott and Levy-Lees transformations contain a common term and it is shown that neglect of this term reduces the equations to the standard two-dimensional or axisymmetric form.

The equations containing transverse curvature in a curvilinear coordinate system are as follows:

**Overall** Continuity

$$\frac{\partial}{\partial x} (r\rho u) + \frac{\partial}{\partial y} (r\rho v) = 0 \qquad (1)$$

Momentum

$$\rho \left( u \quad \frac{\partial u}{\partial x} + v \quad \frac{\partial u}{\partial y} \right) = -\frac{dp}{dx} + \frac{1}{r} \quad \frac{\partial}{\partial y} \left( r\mu \quad \frac{\partial u}{\partial y} \right)$$
(2)

Energy

$$\rho\left(u \frac{\partial H}{\partial x} + v \frac{\partial H}{\partial y}\right) = \frac{1}{r} \frac{\partial}{\partial y} \left[r \left[\frac{\mu}{Pr} \frac{\partial H}{\partial y} + \mu \left(1 - \frac{1}{Pr}\right)u \frac{\partial u}{\partial y}\right]\right]$$
$$+ \frac{1}{r} \frac{\partial}{\partial y} \left[r \left[\frac{\mu}{Pr} (Le - 1) (h_{f} - h_{i}) \frac{\partial c_{f}}{\partial y} + D_{f}^{T} (h_{f} - h_{i}) \frac{1}{T} \frac{\partial T}{\partial y}\right]\right] (3)$$

Species

e

$$\rho\left(\mathbf{u} \quad \frac{\partial \mathbf{c}_{\mathbf{f}}}{\partial \mathbf{x}} + \mathbf{v} \quad \frac{\partial \mathbf{c}_{\mathbf{f}}}{\partial \mathbf{y}}\right) = \frac{1}{\mathbf{r}} \frac{\partial}{\partial \mathbf{y}} \left[\mathbf{r} \left(\rho \mathbf{D}_{\mathbf{f}\mathbf{i}} \quad \frac{\partial \mathbf{c}_{\mathbf{f}}}{\partial \mathbf{y}} + \frac{\mathbf{D}_{\mathbf{f}}^{\mathrm{T}}}{\mathrm{T}} \frac{\partial \mathrm{T}}{\partial \mathbf{y}}\right)\right] (4)$$

6.2 Transformed Equations

For axisymmetric flow a position in the boundary layer is determined by specifying the coordinates x, y, and r (see Figure 1) where r is given by

$$r(\mathbf{x}, \mathbf{y}) = r_{\alpha}(\mathbf{x}) + \mathbf{y} \cos\alpha \qquad (5)$$



Figure 1. Coordinates for Axially Symmetric Body

The body shape is specified by the function  $r_0(x)$ . Equations (1) thru (4) can be placed in an almost two-dimensional form through use of the following transformation originated by Probstein and Elliott (reference 16).

$$\overline{ly} = (r(x, y)/L) dy$$
(6)

$$a\overline{\mathbf{x}} = (\mathbf{r}_0 (\mathbf{x})/\mathbf{L})^2 \, \mathrm{d}\mathbf{x} \tag{7}$$

This differs from the Mangler transformation in that r(x, y) appears in equation (6) rather than  $r_0(x)$ . Moreover, the Mangler transformation is normally applied only to the boundary layer equations containing the first order transverse curvature term. The y velocity component v is eliminated through the following relation

$$\overline{\mathbf{v}} = \left(\frac{\mathbf{r}\mathbf{L}}{\mathbf{r}_{o}^{2}}\right)\mathbf{v} + \left[\left(\frac{\mathbf{L}}{\mathbf{r}_{o}}\right)^{2}\left(\frac{\partial\overline{\mathbf{y}}}{\partial\mathbf{x}}\right)\right]\mathbf{u}$$
(8)

Equations (1) thru (4) in the new coordinate system and in terms of  $\overline{\mathbf{v}}$  become

Continuity

$$\frac{\partial}{\partial \overline{x}} (\rho u) + \frac{\partial}{\partial \overline{y}} (\rho \overline{v}) = 0$$
 (9)

Momentum

$$\rho \left( \mathbf{u} \quad \frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \mathbf{\overline{v}} \quad \frac{\partial \mathbf{u}}{\partial \mathbf{\overline{y}}} \right) = -\frac{\mathrm{d}\mathbf{p}}{\mathrm{d}\mathbf{\overline{x}}} + \frac{\partial}{\partial \mathbf{\overline{y}}} \left( \mu \frac{\mathbf{r}^2}{\mathbf{r}_{\mathrm{O}}^2} \frac{\partial \mathbf{u}}{\partial \mathbf{\overline{y}}} \right)$$
(10)

Energy

$$\rho \left( \mathbf{u} \quad \frac{\partial \mathbf{H}}{\partial \mathbf{x}} + \mathbf{\bar{v}} \quad \frac{\partial \mathbf{H}}{\partial \mathbf{\bar{y}}} \right) = \frac{\partial}{\partial \mathbf{\bar{y}}} \left\{ \frac{\mathbf{r}^2}{\mathbf{r}_o^2} \left[ \frac{\mu}{\mathbf{Pr}} \quad \frac{\partial \mathbf{H}}{\partial \mathbf{\bar{y}}} + \mu \left( \mathbf{l} - \frac{1}{\mathbf{Pr}} \right) \mathbf{u} \quad \frac{\partial \mathbf{u}}{\partial \mathbf{\bar{y}}} \right. \\ \left. + \frac{\mu}{\mathbf{Pr}} \left( \mathbf{Le} - \mathbf{l} \right) \left( \mathbf{h_f} - \mathbf{h_i} \right) \quad \frac{\partial \mathbf{c_f}}{\partial \mathbf{\bar{y}}} + \mathbf{D_f}^{\mathrm{T}} \left( \mathbf{h_f} - \mathbf{h_i} \right) \frac{1}{\mathrm{T}} \quad \frac{\partial \mathrm{T}}{\partial \mathbf{\bar{y}}} \right] \right\}$$
(11)

Species

$$\rho\left(u\frac{\partial c_{f}}{\partial \overline{x}} + \overline{v}\frac{\partial c_{f}}{\partial \overline{y}}\right) = \frac{\partial}{\partial \overline{y}}\left[\frac{r^{2}}{r_{o}^{2}}\left[\left(\rho D_{fi}\frac{\partial c_{f}}{\partial \overline{y}} + \frac{D_{f}}{T}\frac{\partial T}{\partial \overline{y}}\right)\right]\right]$$
(12)

The quantity  $(r/r_0)^2$  is given by

$$\frac{r^2}{r_0^2} = 1 + \frac{2L}{r_0^2} \quad \overline{y} \cos \alpha \tag{13}$$

It can be seen that neglecting the second term on the right-hand side of equation (13) reduces equations (9) thru (12) to the two-dimensional form.

The following transformation (reference 17) is now introduced in order to place the equations in a form more suitable for solution

$$\bar{\xi} = \int_{0}^{\bar{\mathbf{x}}} \rho_{\mathbf{e}} \, \mathbf{u}_{\mathbf{e}} \, \boldsymbol{\mu}_{\mathbf{e}} \, d\bar{\mathbf{x}}$$
(14)

$$\overline{\eta} = \frac{\rho_e}{(2\overline{\xi})^{\prime 2}} \int_{0}^{\overline{y}} \frac{\rho}{\rho_e} d\overline{y}$$
(15)

and equations (9) and (10) are combined through use of a stream function given by

$$\overline{\psi} = (2\overline{\xi})^{'^{\circ}} \mathbf{f} (\overline{\mathbf{x}}, \overline{\eta})$$
(16)

where

$$\rho u = \frac{\partial \overline{\psi}}{\partial \overline{y}} , \quad \rho \overline{v} = -\frac{\partial \overline{\psi}}{\partial \overline{x}}$$
(17)

The following relations are used to express the partial derivative operators in the new coordinate system

$$\left(\frac{\partial}{\partial \,\overline{y}}\right)_{\overline{x}} = \frac{u_{e} \rho}{(2 \,\overline{\xi})^{\mu}} \left(\frac{\partial}{\partial \,\overline{\eta}}\right)_{\overline{\xi}}$$
(18)

$$\left(\frac{\partial}{\partial \,\overline{\mathbf{x}}}\right)_{\overline{\mathbf{y}}} = \rho \mathbf{u}_{\mathbf{e}} \,\,^{\mu} \,\mathbf{e} \left[ \left(\frac{\partial}{\partial \,\overline{\xi}}\right)_{\overline{\eta}} \,\,^{+} \left(\frac{\partial \,\overline{\eta}}{\partial \,\overline{\xi}}\right)_{\overline{\mathbf{y}}} \,\,\left(\frac{\partial}{\partial \,\overline{\eta}}\right)_{\overline{\xi}} \,\,\right] \tag{19}$$

and

$$\left(\frac{\partial \bar{\eta}}{\partial \bar{\xi}}\right)_{\bar{y}} = \frac{u_{e}}{(2\bar{\xi})^{\varkappa}} \int_{0}^{\bar{y}} \left(\frac{\partial \rho}{\partial \bar{\xi}}\right)_{\bar{y}} d\bar{y} - \frac{1}{2\bar{\xi}} \frac{u_{e}}{(2\bar{\xi})^{\varkappa}} \int_{0}^{\bar{y}} \rho d\bar{y}$$
(20)

1

From equations (16), (17), and (18) it can be shown that

$$f' = \left(\frac{\partial f}{\partial \overline{\eta}}\right)_{\overline{X}} = \frac{u}{u_e}$$
(21)

Introducing the stream function f, applying the above operators and nondimensionalizing by the factor ( $\bar{\xi} / \rho u_e^2$ ) yields

Momentum

$$\left[C(1+t) f''\right]' + \beta \left(\frac{\rho_{e}}{\rho} - f'^{2}\right) + ff'' = 2 \tilde{\xi} \left(f' \frac{\partial f}{\partial \tilde{\xi}} - f'' \frac{\partial f}{\partial \tilde{\xi}}\right)$$
(22)

•

Energy

$$\begin{bmatrix} C (1+t) \left\{ \frac{g'}{Pr} + \frac{u_e^2}{H_e} \left( 1 - \frac{1}{Pr} \right) f' f'' + \frac{h_f - h_i}{H_e} \left( \frac{Le - 1}{Pr} c_{f_e} z' + \frac{D_f^T}{\mu} \frac{T'}{T} \right) \right\} \end{bmatrix}^{'} + fg' = 2 \overline{\xi} \left( f' \frac{\partial g}{\partial \overline{\xi}} - g' \frac{\partial f}{\partial \overline{\xi}} \right)$$
(23)

Species  

$$\left[C(1+t)\left(\frac{Le}{Pr} \ z' + \frac{D_{f}T'}{c_{f}\mu T}\right) - Szf' + fz' = 2\overline{\xi}\left(f' \ \frac{\partial z}{\partial \overline{\xi}} - z' \ \frac{\partial f}{\partial \overline{\xi}}\right)$$
(24)

where

$$t = 2\sqrt{2} L\bar{\xi}^{\frac{V_2}{2}} \frac{\cos \alpha}{r_0^2 \rho_e^{u} e} \int_0^{\overline{y}} \frac{\rho_e}{\rho} d\overline{y}$$
(25)

$$\beta = \frac{2\bar{\xi}}{u_e} \quad \frac{du_e}{d\bar{\xi}}$$
(26)

$$S = 2 \frac{\overline{\xi}}{c_{f_{e}}} \frac{dc_{f_{e}}}{d\overline{\xi}}$$
(27)

$$g = H/He$$
(28)

$$z = c_f / c_f_e$$
(29)

The boundary conditions on equations (22) - (24) are:

$$\overline{\eta} = 0:$$
  
 $\mathbf{f} = \frac{-1}{\left(2\overline{\xi}\right)^{\frac{1}{2}}} \int_{\mathbf{O}}^{\overline{\mathbf{x}}} \rho_{\mathbf{w}} \mathbf{v}_{\mathbf{w}} \left(\frac{\mathbf{L}}{\mathbf{r}_{\mathbf{O}}}\right) d\overline{\mathbf{x}}$  (30a)

$$\mathbf{f}^{\dagger} = \mathbf{0} \tag{30b}$$

$$\begin{cases} g = g_{w} \\ or \\ g' = g'_{w} \end{cases}$$
(30c)  
$$\begin{cases} z = z_{w} \\ or \\ z' = z'_{w} \end{cases}$$
(30d)

$$\bar{\eta} \rightarrow \infty$$
: f'  $\rightarrow 1$  (30e)

$$g \rightarrow 1$$
 (30f)

$$z \rightarrow 1$$
 (30g)

It can be seen that neglect of the quantity t in equations (22) - (24) leads to the standard two-dimensional form of the laminar boundary-layer equations in the Levy - Lees coordinate system. Hence with t set equal to zero the appropriate transformation is

$$\xi = \int_{0}^{x} \rho_{e} u_{e} \mu_{e} r_{o}^{2k} dx \qquad (31)$$

$$\eta = \frac{\rho_e u_e}{(2\xi)^{\frac{1}{2}}} \int_0^y r_o^k \frac{\rho}{\rho_e} dy \qquad (32)$$

where k = 0 for two-dimensional flow and k = 1 for axisymmetric flow. The quantity  $r_0$  does not appear in equations (14) and (15) since it is already contained in the quantities  $\overline{x}$  and  $\overline{y}$ . The second-order transverse curvature effects can now either be accounted for or neglected; with t given by equation (25) and application of the transformation given by equations (14) and (15) it is accounted for and with t equal to zero and application of the transformations

given by equations (31) and (32) second-order transverse curvature is not accounted for. In addition, it should be kept in mind that when t is zero and equations (31) and (32) are applied the quantity r(x, y) in the original equations (1) - (4) is replaced by  $r_{a}(x)$ .

The equations were programmed so that transverse curvature (TVC) effects could be included or neglected in any given calculation. If TVC is neglected it is understood that the unbarred variables apply. The expressions for certain quantities such as displacement thickness and the inverse transformation back to the physical plane depend on whether the barred (including TVC) or unbarred system (neglecting TVC) is used. These expressions for both systems are developed in Section 6.5.

In order to make the solution of equations (22) - (24) possible, expressions for the fluid properties appearing in these equations are necessary.

#### 6.3 Fluid Properties

The fluid properties developed in this section are those dealing with a binary mixture of non-reacting gases. The basic binary mixture is obtained by the injection of a foreign gas, either helium, argon, or carbon dioxide into a free stream consisting of air. The mixture properties employed in this development are functions of the mass fractions of the individual species and properties of the pure species comprising the mixture. In a binary mixture, one of the mass fractions can be eliminated by the relationship

$$c_{i} + c_{f} = 1 \tag{33}$$

The mass fraction  $c_i$  has been eliminated in the present formulation. The species equation variable z then becomes (as shown in equation (29))

$$z = \frac{c_f}{c_f}$$
(34)

If the free stream is uncontaminated,  $c_{f_e}$  will be one at the edge of the boundary layer, and if a foreign gas alone is injected into the boundary layer, z will be zero at the wall.

The fluid properties needed to solve the laminar boundary-layer equations of a binary mixture are:  $C_p$ ,  $C_V$ ,  $C_{p_i}$ ,  $C_{p_f}$ ,  $C_V$ ,  $C_V$ , h,  $h_i$ ,  $h_f$ ,  $\lambda$ ,  $\lambda_i$ ,  $\lambda_f$ ,  $\mu$ ,  $\mu_i$ ,  $\mu_f$ ,  $D_{fi}$ ,  $D_f^T$  and certain combinations of these that give the dimensionless parameters Pr and Le. Storage for the coefficient

of thermal diffusion  $D_f^T$  is allocated although a numerical statement of it is not included. The fluid properties are valid in the temperature range from 50°K to 3500°K (except for  $C_p$ , which is valid to 0°K).

## 6.3.1 Thermodynamic Properties

The individual species comprising the gas mixture are assumed perfect but not necessarily calorically perfect. That is, the specific enthalpies of the pure species are not constant but are taken as functions only of temperature. Also the total pressure is the sum of the partial pressures of the individual species. The expression for the density  $\rho$  of a mixture of perfect gases is given by

$$\rho = \frac{p}{R'T} \left[ \frac{M_i M_f}{c_f (M_i - M_f) + M_f} \right] \frac{s \log s}{ft^3}$$
(35)

Where

$$M_{f} = M_{air} = 28.966$$
  
 $M_{i} = M_{Ar} = 39.948$   
 $M_{He} = 4.0083$   
 $M_{CO_{2}} = 44.011$ 

The constant volume and constant pressure heat capacities of the mixture are given by

$$C_{V} = (1 - c_{f}) C_{V_{i}} + c_{f} C_{V_{f}}$$
(36)

and

$$C_{p} = (1 - c_{f}) C_{p_{i}} + c_{f} C_{p_{f}}$$
 (37)

The constant volume heat capacities of the pure species are obtained from statistical mechanical considerations (reference 18). The modes of energy distribution considered are translation, rotation, and vibration.

For the monatomic gases, He and Ar, the translational mode is fully excited at room temperature to give the value

$$C_{V_j} = \frac{3}{2} \frac{R'}{M_j}$$
(38)

and there are no contributions due to rotation and vibration. For air the rotational and vibrational modes must also be used. The contribution of electronic excitations to the heat capacities are negligible in the temperature range of interest and have been neglected. The constant pressure heat capacities of He, Ar, and air are obtained by means of

$$C_{p_j} = C_{v_j} + \frac{R'}{M_j}$$
(39)

The constant pressure heat capacity for  $CO_2$  was obtained from the Janaf Thermochemical Data Tables (reference 19). The  $C_p_j$  data for air and  $CO_2$  have been fit to polynomials of the form

$$C_{p_j} = A + BT + CT^2 + DT^3 + ET^4 + FT^5 \left(\frac{ft^2}{sec^{2} \circ R}\right)$$
 (40)

The coefficients in equation (40) are given in Table I. The values of  $C_{p_j}$ 

for He and Ar are:

$$C_{p_{He}} = 3.1025 \times 10^4 \frac{ft^2}{sec^2 \circ_R}$$
 (41)

$$C_{p_{Ar}} = 3.11151 \times 10^3 \frac{ft^2}{sec^{2} \circ R}$$
 (42)

The static enthalpy of the mixture is given by

$$h = (1 - c_f) h_i + c_f h_f$$
 (43)

Where

$$h_{i} = \int_{0}^{T} C_{p_{i}} dT \qquad (44)$$

and

$$h_{f} = \int_{0}^{T} C_{p_{f}} dT$$
(45)

Substituting equations (40), (41) and (42) into (44) and (45) results in a polynomial of the form

$$h_j = AT + BT^2 + CT^3 + DT^4 + ET^5 + FT^6 \left(\frac{ft^2}{sec^2}\right)$$
 (46)

for air and  $CO_2$  (the coefficients for equation (46) are given in Table II) and for He and Ar gives

$$h_{He} = 3.1025 \times 10^4 T \frac{ft^2}{sec^2}$$
 (47)

$$h_{Ar} = 3.1115 \times 10^3 T \frac{ft^2}{sec^2}$$
 (48)

#### 6.3.2 Transport Properties

The transport properties calculated in this section are viscosity, thermal conductivity and the binary diffusion coefficient. The development of the thermal diffusion coefficient can be found in reference (20).

The viscosity of the mixture is obtained from Wilke's formula (reference 21) applied to a binary gas mixture.

$$\mu = \frac{\mu_{i}}{1 + G_{if}} \frac{X_{f}}{X_{i}} + \frac{\mu_{f}}{1 + G_{fi}} \frac{X_{i}}{X_{f}}$$
(49)

Where

$$X_{i} = \frac{(1 - c_{f})/M_{i}}{c_{f}/M_{f} + (1 - c_{f})/M_{i}}$$
(50)

$$X_{f} = \frac{c_{f}/M_{f}}{c_{f}/M_{f} + (1 - c_{f})/M_{i}}$$
(51)

$$G_{if} = \frac{1}{\sqrt{8}} \left( 1 + \frac{M_i}{M_f} \right)^{-\frac{N}{2}} \left[ 1 + \left( \frac{\mu_i}{\mu_f} \right)^{\frac{N}{2}} \left( \frac{M_f}{M_i} \right)^{\frac{N}{2}} \right]^2$$
(52)

and  $\boldsymbol{\mu}_i, \; \boldsymbol{\mu}_f$  are viscosities of the individual species

The viscosities of the individual species are given by the Chapman-Enskog relation (reference 22).

$$\mu_j = 0.625 \frac{kT}{\Omega_j^{(2,2)}}$$
 (53)

For temperatures less than  $1000^{\circ}$ K, the collision integral  $\Omega_{j}^{(2, 2)}$  is obtained from the Lennard-Jones (6-12) potential as tabulated in reference (22); Sutherland's law, reference (23), is used for air up to a temperature of  $1500^{\circ}$ K. For temperatures greater than  $1000^{\circ}$ K, the viscosities of He and Ar are obtained from Amdur and Mason (reference 24); where the collision integral was evaluated based upon an exponential repulsive potential of the form

$$\phi = Ae^{-r/\rho}$$
(54)

The viscosity of  $CO_2$  for temperatures greater than  $1000^{\circ}$ K is taken from reference (25), where a Morse potential of the form

$$\phi = A \left[ 1 - e^{-B(r-c)} \right]^2$$
(55)

is used to evaluate the collision integral. The viscosity of air for temperatures greater than  $1500^{\circ}$ K is calculated by using the mixture formula (equation (49)), and taking the composition of air to be essentially N<sub>2</sub> and O<sub>2</sub>. The viscosity of N<sub>2</sub> is taken from Amdur and Mason, and the viscosity of O<sub>2</sub> is taken from reference (26). The viscosity data for all the gases have been fit to polynomials of the form

$$\mu_{j} = \mathbf{A} + \mathbf{BT} + \mathbf{CT}^{2} + \mathbf{DT}^{3} + \mathbf{ET}^{4} + \mathbf{FT}^{5} \left( \frac{\mathbf{lb \ sec}}{\mathbf{ft}^{2}} \right)$$
(56)

The coefficients in equation (56) are given in Table III.

The thermal conductivities of the individual species are given by the Eucken relation (reference 27)

$$\lambda_{j} = \frac{1}{4} \left( 9 \frac{C_{p_{j}}}{C_{V_{j}}} - 5 \right) C_{V_{j}} \mu_{j}$$
(57)

The above relation takes molecular vibration and rotation into account in addition to the translation contribution to the internal energy. The thermal conductivity of the mixture is obtained by using equation (49) and replacing the individual species viscosities with the conductivities. The binary diffusion coefficients are calculated from the first Chapman Enskog approximation (reference 22)

$$D_{fi} = 3k^2 T^2 / 16 p M_{fi} \Omega_{fi}^{(1, 1)}$$
(58)

where  $M_{fi}$  is the reduced mass of particles f, i.

The calculation of  $D_{air i}$  is made by applying a reduced mass correction factor to calculated values of  $D_{N_2}$  i (reference 28)

$$D_{air i} = D_{N_2 i} \left( \frac{M_{N_2 i}}{M_{air i}} \right)^{1/2}$$
(59)

For He, Ar and N<sub>2</sub>, the collision integral  $\Omega_{fi}^{(1, 1)}$  in equation (58) has been evaluated by Monchick (reference 29) on the basis of an exponential repulsive potential (equation (54)), where A and  $\rho$  are (reference 24).

A (ev) $\rho$  (A°)He - He0.0386 x 1040.220Ar - Ar3.23 x 1040.224N<sub>2</sub> - N<sub>2</sub>1.35 x 1040.263

To obtain the necessary combinations of these, a simple geometric mean combination rule (reference 24) is used

$$A_{fi} = \left(A_{ff} A_{ii}\right)^{6}$$
(60)

$$\frac{1}{\rho_{\rm fi}} = \frac{1}{2} \left( \frac{1}{\rho_{\rm ff}} + \frac{1}{\rho_{\rm ii}} \right) \tag{61}$$

Using Monchick's results and equation (58) values of  $pD_{fi}$  were calculated and fitted to a fifth degree polynomial whose coefficients are given in Table IV.

For  $CO_2$  the collision integral was calculated based upon the Lennard-Jones (6-12) potential (reference 22) up to a temperature of  $1000^{\circ}$ K. For temperatures greater than  $1000^{\circ}$ K,  $D_{fi}$  was calculated based upon the Sutherland model (reference 22)

$$D_{fi} = \frac{D(T)_{fi} - rigid sphere}{1 + \frac{\theta}{T}}$$
(62)

where  $D(T)_{fi}$  - rigid sphere and  $\theta$  are calculated from two known temperatures.  $pD_{fi}$  was calculated and fit to equation (62). The coefficients are given in Table IV.

It is stressed that the basic method of solution is the same for all three mixtures considered; the only differences appearing in the computer program are the numerical constants, appearing in the previous equations, used to describe properties of the individual species.

#### TABLE I

## SPECIFIC HEAT AT CONSTANT PRESSURE

$$C_{P_{j}} = A + BT + CT^{2} + DT^{3} + ET^{4} + FT^{5} \left(\frac{ft^{2}}{\sec^{2} o_{R}}\right)$$

Gas	Temperature Range <sup>O</sup> R	A	в	С	D	E	F
Аіт	0 ≤ T ≤ 2000	6.035179 <u>7</u> ×10 <sup>3</sup>	-9.4509125 ×10 <sup>-4</sup>	-7.3022675 x10 <sup>-4</sup>	1.7322782 x10 <sup>-6</sup>	-9.7657438 x10 <sup>-10</sup>	1.7465179 ×10 <sup>-13</sup>
	2000 ≤ T ≤ 6300	6.4371993 ×10 <sup>3</sup>	-4.4825613 x10 <sup>-1</sup>	7.1435785 x10 <sup>-4</sup>	-2.4394435 x10 <sup>-7</sup>	3.4477526 x10 <sup>-11</sup>	-1.7810174 ×10 <sup>-15</sup>
co <sub>2</sub>	0 ≤ T ≤ 2000	2.3317627 ×10 <sup>2</sup>	7.3287082 ×10 <sup>1</sup>	-1.342833 x10 <sup>-1</sup>	1.3090637 x10 <sup>-4</sup>	-6.0572879 x10 <sup>-8</sup>	1.0531063 x10 <sup>-11</sup>
	2000 ≤ T ≤ 6300	1.328997 x10 <sup>4</sup>	1.0499195 ×10 <sup>1</sup>	-3.4760828 x10 <sup>-3</sup>	6.1489558 x10 <sup>-7</sup>	-5,568993 x10 <sup>-11</sup>	2.033227 x10 <sup>-15</sup>

## TABLE II

## STATIC ENTHALPY

$$h_j = AT + BT^2 + CT^3 + DT^4 + ET^5 + FT^6 \left(\frac{ft^2}{sec^2}\right)$$

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Gas	Temperature Range <sup>O</sup> R	А	В	с	D	E	F
Air	$0 \leq T \leq 2000$	6.0351797 x10 <sup>3</sup>	-4.7254562 x10 <sup>-4</sup>	-2.4340867 x10 <sup>-4</sup>	4. 3306955 x10 <sup>-7</sup>	-1.9531487 x10 <sup>-10</sup>	2.9108631 ×10 <sup>-14</sup>
	2000 ≤ T ≤ 6300	6.4371993 x10 <sup>3</sup>	-2.2412806 x10 <sup>-1</sup>	2. 3811928 x10 <sup>-4</sup>	-6.098608 x10 <sup>-8</sup>	6.895505 x10 <sup>-12</sup>	-2.968362 x10 <sup>-16</sup>
coz	0 ≤ T ≤ 2000	2.3317627 x10 <sup>2</sup>	3.6643541 ×10 <sup>+1</sup>	-4.476109 ×10 <sup>-2</sup>	3.272659 x10 <sup>-5</sup>	-1,2114575 x10 <sup>-8</sup>	1.755177 x10 <sup>-12</sup>
	2000 ≤ T ≤ 6300	1.328997 x10 <sup>4</sup>	5.249597	-1.158694 x10 <sup>-3</sup>	1.5372389 ×10 <sup>-7</sup>	-1.1137986 x10 <sup>-11</sup>	3. 388711 x10 <sup>-16</sup>

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## TABLE III

## VISCOSITIES

$$\mu_{j} \times 10^{7} = A + BT + CT^{2} + DT^{3} + ET^{4} + FT^{5} \left(\frac{1b \text{ sec}}{ft^{2}}\right)$$

 $90^{\circ}R \le T \le 6300^{\circ}R$ 

Gas	А	В	С	D	E	F
H <sub>e</sub>	5.5026909	7.9471713	-2.2178108	4.0447782	-1.806356	-1.0112767
	x10 <sup>-1</sup>	x10 <sup>-3</sup>	x10 <sup>-6</sup>	x10 <sup>-10</sup>	x10 <sup>-14</sup>	x10 <sup>-18</sup>
A <sub>r</sub>	-5.5369992	1.0747731	-4.4382035	1.395966	-2.066 <b>7</b> 733	1.1450887
	x10 <sup>-2</sup>	x10 <sup>-2</sup>	x10 <sup>-6</sup>	×10 <sup>-9</sup>	x10 <sup>-13</sup>	x10 <sup>-17</sup>
co <sub>2</sub>	-7.8193191	6.7732592	-17286911	3.8700139	-5.1304856	2.7591624
	×10 <sup>-2</sup>	x10 <sup>-3</sup>	x10 <sup>-6</sup>	×10 <sup>-10</sup>	x10 <sup>-14</sup>	x10 <sup>-18</sup>
Air	-1.9336805	8.9325935	- 3. 918504	1,1728501	-1.649344	8.751547
	x10 <sup>-2</sup>	x10 <sup>-3</sup>	x10 <sup>-6</sup>	x10 <sup>-9</sup>	x10 <sup>-13</sup>	x10 <sup>-18</sup>

## TABLE IV

## BINARY DIFFUSION COEFFICIENT

$$pD_{fi} = A + BT + CT^{2} + DT^{3} + ET^{4} + FT^{5} \left(\frac{lb}{sec}\right)$$
  
 $90^{\circ}R \le T \le 6300^{\circ}R$ 

Gas	А	В	С	D	Е	F
Н <sub>е</sub>	-9.7598318	1.4399797	3.9911825	-4.0516911	4.7053885	-2.3594221
	×10 <sup>-2</sup>	x10 <sup>-3</sup>	×10 <sup>-6</sup>	×10 <sup>-10</sup>	x10 <sup>-14</sup>	x10 <sup>-18</sup>
Ar	-3.2467965	4.8860752	1.1704382	-1.3105574	1.4735018	~7.0980313
	×10 <sup>-2</sup>	×10 <sup>-4</sup>	×10 <sup>-6</sup>	×10 <sup>-10</sup>	x10 <sup>-14</sup>	×10 <sup>-19</sup>
co <sub>2</sub>	1.3094896	-5.6215733	1.4178492	-3.8555763	6.84051 <b>7</b> 7	-4.7403394
	x10 <sup>-2</sup>	x10 <sup>-5</sup>	x10 <sup>-6</sup>	×10 <sup>-10</sup>	x10 <sup>-14</sup>	x10 <sup>-18</sup>

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#### 6.4 Overall Method of Solution

The method used to solve equations (22) - (24) is based upon ideas originated by Hartree and Womersley (reference 12). This method has been applied to the incompressible laminar boundary-layer equations (reference 13), the compressible laminar boundary-layer equations (reference 14), and the laminar boundary-layer equations of a binary dissociating gas (reference 15). Many of the details of the method can be found in the aforementioned references. The essential differences between the work reported here and that reported in reference (15) is in the mathematical transformations and the fluid properties used. In addition a modification of the integration techniques used on the momentum and energy equations is introduced. The derivatives in the transformed streamwise direction appearing on the righthand side of equations (22) - (24) are replaced by forward finite difference expressions. Thus at any given location along the surface the partial differential equations are approximated by ordinary differential equations provided solutions are known at upstream locations. Equations (22) - (24) are rewritten at station n along the body to give the following (it is to be understood that unless otherwise specified quantities are evaluated at station n, values at previous stations are denoted by subscripts):

Momentum

$$\left[C(1+t)\phi^{\prime\prime}\right]^{\prime} = \beta\left(\phi_{s}^{\prime 2} + 2\phi^{\prime} + 1 - \frac{\rho_{e}}{\rho}\right) - (\phi+\eta)\phi^{\prime\prime} + R_{1}$$
(63)

Energy

$$\pi' = -(\phi + \eta) \psi' + R_{2}$$
 (64)

Species

$$\Omega' = S(\phi'+1) z - (\phi+\eta) z' + R_{2}$$
(65)

where

$$\phi' = f' - 1$$
 (66)

$$\psi = g - 1 \tag{67}$$

and

$$\pi = C(1+t) \left\{ \frac{\psi'}{\Pr r} + \frac{u_e^2}{H_e} \left( 1 - \frac{1}{\Pr r} \right) (\phi'+1) \phi'' + \frac{h_f - h_i}{H_e} \left[ \frac{L_e - 1}{\Pr r} c_f z' + \frac{D_f^T}{\mu} \frac{T'}{T} \right] \right\}$$
(68)

$$\Omega = C(1+t) \left( \frac{Le}{Pr} \mathbf{z}' + \frac{D_f^T}{c_f \mu} \frac{T'}{T} \right)$$
(69)

The quantities  $\phi'$  and  $\psi$  are introduced to reduce round off errors in the numerical integration of equations (63) and (64). These values go to zero at the edge of the boundary layer whereas the original dependent variables f' and g go to unity. The terms on the left-hand side of equations (63) - (65) contain the molecular transport quantities and are composed of the highest order derivatives in the direction normal to the surface. The quantities  $R_1$ ,  $R_2$ , and  $R_3$  contain the streamwise derivatives which are first order and are expressed in finite difference form, for example

$$R_{1} = 2\overline{\xi} \left\{ (\phi^{\dagger} + 1) \left[ a(\phi^{\dagger} + 1) + b(\phi^{\dagger}_{n-1} + 1) + c(\phi^{\dagger}_{n-2} + 1) \right] - \phi^{\dagger} \left[ a(\phi + \eta) + b(\phi_{n-1} + \eta) + c(\phi_{n-2} + \eta) \right] \right\}$$
(70)
  
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Similar finite difference expressions are employed for  $R_2$  and  $R_3$ . The quantities a, b, and c depend on the choice of step size for the independent variable  $\overline{\xi}$ ; for the special case of equally spaced steps of length  $\Delta \overline{\xi}$ 

$$a = 1.5/\Delta \xi$$
  $b = -2.0/\Delta \xi$   $c = 0.5/\Delta \xi$ 

if solutions are known at stations n-1 and n-2 equations (63), (64), and (65) are ordinary in  $\phi$ ,  $\psi$ , and z respectively. At station one, the three point finite difference expressions are replaced by two point finite difference expressions. No difficulty is encountered in starting at station zero since  $R_1$ ,  $R_2$ , and  $R_3$  are all zero at  $\overline{\xi} = 0$ .

Equations (63) - (65) are coupled and must be solved simultaneously. An iteration process is used (reference 15). At any given station n the initial fluid properties used are those obtained from the final solution at station n-1. The initial fluid properties are then used to obtain a solution to the momentum equation; the same fluid properties and stream function obtained from the solution of the momentum equation are used to solve the species and energy equations. Since the fluid properties and stream function are specified for any given solution of the species and energy equations, these equations are linear in z and  $\psi$ , respectively. The solutions to the species and energy equations are used to generate new fluid properties which are in turn used to obtain new solutions of the species and energy equations. This process is continued until the values of fluid properties converge. The same stream function is used for all cycles of this iteration loop. Upon convergence of fluid properties a new stream function is calculated using the latest fluid properties. This double iteration is continued until convergence of solutions to the momentum equation is obtained. The initial fluid properties used at
station zero are obtained by assuming a linear variation between the surface and edge conditions which are known boundary conditions.

6,4,1 Solution of the Momentum Equation

Equation (63) is a two point boundary value problem with two conditions at  $\eta = 0$  and one condition at  $\eta_m$ . That is

 $\varphi (0) = \varphi_{w} \text{ (specified)}$   $\varphi^{\dagger} (0) = -1$   $\varphi^{\dagger} (\eta_{m}) = 0$ 

The boundary value problem is transformed to an initial value problem by hunting for the third condition at  $\eta = 0$ , namely  $\phi''(0)$  which will give a solution satisfying the condition  $\phi'(\eta_{\infty}) = 0$ . With three conditions specified, $\phi(0)$ ,  $\phi'(0)$ , and  $\phi''(0)$ , equation (63) can be integrated. The right-hand side, RHS, of equation (63) is first integrated and  $\phi''$  is obtained from

$$\phi^{11} = \frac{1}{C(1+t)} \int_{0}^{\eta} RHS \, d\eta + \phi^{11}(0)$$
 (71)

Successive integrations of  $\phi''$  then yield  $\phi'$  and  $\phi$ . It should be kept in mind that C (1+t) is known from fluid properties which were obtained previously. Trial values of  $\phi''(0)$  are used until three solutions have been bracketed within the bound  $\pm K_1$  at  $\eta_{\infty}$ . Once three solutions have been obtained and at least one solution is either high or low satisfying the condition

$$-K_1 \leq \phi'(\eta_{\omega}) \leq K_1$$

three point Lagrangian interpolation is used to obtain the final solution satisfying  $\phi'(\eta_{\omega}) = 0$ . A high solution is one in which  $\phi'(\eta_{\omega}) > 0$  and a low solution is one in which  $\phi'(\eta_{\omega}) < 0$ . A predictor - corrector technique (pp 116-131, reference 30) is used to perform the integration indicated in equation (71). Solutions are started at the wall by means of a Taylor Series expansion and a shorter step size to maintain accuracy. See references (14) and (20) for details of the integration and the Lagrangian interpolation processes.

Under certain conditions it has been found that values of  $\phi'(\eta_{\infty})$  are extremely sensitive to trial values of  $\phi''(0)$  and difficulty is encountered in bracketing three solutions at  $\eta_{\infty}$ . In previous work (references 14 and 15) the original value input for  $\eta_{\infty}$  has been reduced when three solutions could not be bracketed. However in addition to the explicit boundary condition

$$\phi'(\eta_m) = 0$$

there exists the implicit condition that  $\phi$  "---- 0 as  $\eta$  -----  $\eta_m$ .

Although the solution is forced to satisfy the explicit condition the implicit condition is satisfied only if  $\eta_{\infty}$  is sufficiently large. Hence,  $\eta_{\infty}$  can not be indiscriminately reduced in order to bracket three solutions. A method has been devised to overcome this difficulty. The essential feature of this method is that once  $\phi''(0)$  has been determined to within a specified accuracy, the searching process for  $\phi''$  no longer continues at  $\eta = 0$  but rather at some new value of  $\eta$ . Solutions are generated by incrementing or decrementing  $\phi''(0)$ , depending upon whether  $\phi'(\eta_{\infty})$  is low or high, a fixed amount until at least one high and one low solution is obtained. From then on trial values of  $\phi''(0)$  are obtained by bisection.

If three solutions have not been bracketed within bound  ${}^{\pm}K_1$  and for two successive trial values  $\phi_i^{\mu}(0)$  and  $\phi_{i+1}^{\mu}(0)$  the following condition exists

$$\frac{\left|\phi_{i+1}^{\prime\prime}(0) - \phi_{i}^{\prime\prime}(0)\right|}{\phi_{i+1}^{\prime\prime}(0) + \phi_{i+1}^{\prime\prime}(0)} < \epsilon_{1}$$

then integration is begun at  $\eta$  where  $\eta_{s1}$  is the maximum value of  $\eta$  at which the last high and low  $\diamond$ ' profiles differ by a small amount,  $\epsilon_2$ . The trial velocity profiles  $\phi'$  agree at  $\eta = 0$  and the difference between them grows with  $\eta$ ; hence, it can be said that the velocity profile has been determined to within  $\epsilon_2$  up to  $\eta_{s1}$ . The last three profiles, of which at least one is either high or low, are now used as the basis for beginning the search at  $\eta_{s1}$ . Let the subscripts 1, 2, 3 refer to these last three profiles where 1 refers to the low profile, 2 to the middle profile, and 3 the high profile. The quantities  $\phi_2(\eta_{s1})$  and  $\phi'_2(\eta_{s1})$  are used as initial values for succeeding integrations from  $\eta_{s1}$ . Trial values of  $\phi''(\eta_{s1})$  are now used to obtain new solutions. The first new solution is obtained by subtracting from or adding to  $\phi_2''(\eta_{s1})$ , depending upon whether  $\phi_2'(\eta_m)$  is high (>0) or low (<0), one fourth the difference between  $\phi_1''(\eta_{s1})$  and  $\phi_3''(\eta_{s1})$ . The process of adding or subtracting one fourth the difference between the last high and low solutions to the last trial value of  $\varphi''(\eta_{s1})$  is continued until a high and low solution are obtained; then bisection between the high and low is continued until three values of  $\varphi'(\eta_{\underline{w}})$  have been bracketed or

$$\frac{|\phi_{i+1}^{''}(\eta_{s1}) - \phi_{i}^{''}(\eta_{s1})|}{\phi_{i+1}^{''}(\eta_{s1}) + \phi_{i}^{''}(\eta_{s1})} < \epsilon_{1}$$

If the latter condition is met and three solutions are still not bracketed, integration begins at  $\eta_{s2}$  with trial values of  $\phi''(\eta_{s2})$  where  $\eta_{s2}$  is now the maximum value at which the last high and low solutions differ by  $\epsilon_2$ . This procedure is continued J times; that is until trial solutions have been attempted from  $\eta_{sJ}$ . The quantities  $\epsilon_1$ ,  $\epsilon_2$  and J are inputs to the program; typical values are  $10^{-8}$ ,  $10^{-6}$ , and 4 respectively.

The process of extending the trajectory of integration (ETI) by beginning from a new location has also been applied to the species and energy equations and a schematic diagram of the process applicable to the energy equation is shown in Figure 2.

### 6.4.2 Solution of the Species Equation

With values of the stream function and fluid properties known, it can be seen that equation (65) is linear in z. The usual specified boundary condition at the wall will be z(0). The equation is second order and a value of z'(0) in addition to z(0) will provide the necessary information to be able to treat the solution as an initial value problem. Two trial values  $z'_1(0)$  and  $z'_2(0)$  are used to obtain  $z_1$  and  $z_2$ . These solutions are combined linearly to give a general solution

$$\mathbf{z} = \mathbf{A}\mathbf{z}_1 + \mathbf{B}\mathbf{z}_2 \tag{72}$$

and then the coefficients A and B are obtained from the two boundary conditions

$$z(0) = z_w$$
 (specified) and  $z(\eta_{-}) = 1$ 

to give a particular solution.



Figure 2. - Diagram of Solution to Energy Equation

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The quantity z'(0) may be specified as a boundary condition instead of z(0). In this case, two trial values of z(0) are used to obtain two solutions which are combined to give a general solution. The particular solution is then obtained by satisfying the boundary conditions

$$z'(0) = z'_w$$
 (specified) and  $z(\eta_w) = 1$ 

The coefficients A and B in equation (72) obtained from the boundary conditions are

$$A = \frac{1 - z_2(\eta_{\infty})}{z_1(\eta_{\infty}) - z_2(\eta_{\infty})}$$
(73)

$$B = 1 - A$$
 (74)

As with the momentum equation, the quantity  $R_3$  is replaced by a finite difference expression and equation (65) becomes ordinary and is integrated in the  $\eta$  direction at successive values of  $\overline{\xi}$ . The solution at any value of  $\overline{\xi}$  utilizes solutions at the two previous values of  $\overline{\xi}$ .

Once z(0) and z'(0) are specified a solution z is obtained by using the specified initial conditions and integrating the right-hand side of equation (65) to give  $\Omega$ . Once  $\Omega$  is determined, z' is obtained from equation (69) and z is obtained by integration of z'. The same integration formulas (pp. 116 - 131, reference 30) used on the momentum equation are used to perform the necessary integrations to obtain a solution to the species equation.

# 6.4.3 Solution to the Energy Equation

Equation (64) is linear in  $\psi$  since fluid properties and the stream function are known from a previous solution. The same general procedure

used to solve the species equation is used on the energy equation. The quantity  $R_2$  is expressed in finite difference form to make the equation ordinary. The specified surface boundary condition may be either  $\psi(0)$  or  $\psi'(0)$ . If  $\psi(0)$  is specified two trial values  $\psi'_1(0)$  and  $\psi'_2(0)$  are used to produce solutions  $\psi_1$  and  $\psi_2$ ; these solutions are linearly combined to give a general solution and then the boundary conditions

 $\psi(0) = \psi_{w}$  (specified)

and

 $\psi(\eta_{\infty}) = 0$ 

are satisfied to obtain the particular solution.

The general solution is given by

$$\psi = \mathbf{A} \dot{\psi}_{1} + \mathbf{B} \dot{\psi}_{2} \tag{75}$$

where the coefficients obtained from satisfying boundary conditions are given by

$$\mathbf{A} = \frac{-\psi_2(\eta_{\omega})}{\psi_1(\eta_{\omega}) - \psi_2(\eta_{\omega})}$$
(76)

$$B = 1 - A$$
 (77)

With given initial conditions  $\psi(0)$  and  $\psi'_1(0)$ , the right-hand side of equation (64) is integrated to give  $\pi$ . Equation (68) is solved for  $\psi'_1$  which is then integrated to give  $\psi_1$  and a similar procedure is used to obtain  $\psi_2$ .

If the two trial solutions  $\psi_1$  and  $\psi_2$  are highly divergent, the linearization technique over the complete range from zero to  $\eta_{\infty}$  can break down. In this case, a modified procedure is used to obtain a solution. A set of coefficients  $A_0$  and  $B_0$  are computed as before using equations (76) and (77); however, it is assumed that the final solution is valid only out to  $\eta_{\text{Pl}}$  where  $\eta_{\text{Pl}}$  is the minimum value at which either  $\psi_1$  or  $\psi_2$  exceeds the bound  $K_2$ . (See Figure 2.)

That is

$$\Psi = A_0 \Psi_1 + B_0 \Psi_2 \quad \text{for } 0 \le \eta \le \eta_{P1}$$
(78)

a new solution  $\psi_3$  is now generated from  $\eta$  using  $\psi(\eta$  ) and  $\psi_t'(\eta)$  as initial conditions where

$$\psi(\eta_{\rm Pl}) = A_{\rm o} \psi_{\rm l}(\eta_{\rm Pl}) + B_{\rm o} \psi_{\rm 2}(\eta_{\rm Pl})$$
(79)

and  $\psi'_t(\eta_{Pl})$  represents a small perturbation of  $\psi'(\eta_{Pl})$ . The new solution  $\psi_3$  is now linearly combined with  $\psi$  to give a continuation  $\psi_c$  of the original solution

$$\psi_{c} = A_{1}\psi + B_{1}\psi_{3} \text{ for } \eta_{P1} \leq \eta \leq \eta_{P2}$$
(80)

The process is continued until a complete solution out to  $\eta_{\infty}$  has been obtained. The quantities  $K_2$  and  $\epsilon_3$  are inputs to the program and are typically 100 and  $10^{-3}$  respectively.

### 6.5 Boundary Layer Parameters

Once the profiles of  $\phi$ , z,  $\psi$  and their derivatives have been determined at an x-station, the program determines the conventional boundary-layer parameters of displacement thickness, momentum thickness, local skin friction, and local heat transfer. The program calculates a set of these parameters for the Levy-Lees transformation designated as t equal to zero, and for the Levy-Lees Probstein-Elliott transformation including second-order transverse curvature, designated as t not equal to zero (for this case t is given by equation (25)).

If TVC is neglected the following expressions are used:

The displacement thickness is calculated from the formula

$$\delta^* = \int_0^\infty \left( 1 - \frac{\rho u}{\rho_e u_e} \right) dy$$
 (81)

when transformed to the  $\xi$  ,  $\eta$  - coordinates equation (81) becomes

$$\delta^* = \frac{(2\xi)^{l_2}}{\rho_e u_e r_o^k} \int_0^\infty \left(\frac{\rho_e}{\rho} - f'\right) d\eta$$
(82)

The program calculates normalized displacement thickness  $\Delta$ \*, which is defined by

$$\Delta^{*} = (\operatorname{Re}_{\mathbf{x}})^{\frac{1}{2}} \frac{\delta^{*}}{r_{o}^{k}} = \frac{\mathbf{x}}{r_{o}^{2k} \mu_{e}} \left(\frac{2\xi}{\operatorname{Re}_{\mathbf{x}}}\right)^{\frac{1}{2}} \left[\int_{0}^{\infty} \left(\frac{\rho_{e}}{\rho} - f^{\dagger}\right) d\eta\right]$$
(83)

where

$$Re_{x} = \frac{\rho_{e} u_{e}^{x}}{\mu_{e}}$$

/

The program calculates y from  $\eta$  using the following relationship

$$\eta = \frac{\rho_e u_e}{(2\xi)^{\frac{1}{2}}} \int_0^y \frac{\rho}{\rho_e} r_o^k dy \qquad (84)$$

or

$$\mathbf{y} = \frac{(2\xi)^{\frac{1}{2}}}{\mathbf{r}_{o}^{k} \rho_{e} \mathbf{u}_{e}} \int_{o}^{\eta} \frac{\rho_{e}}{\rho} d\eta \qquad (85)$$

A normalized y is defined

$$Y = (Re_x)^{\frac{1}{2}} \frac{y}{r_o^k}$$
(86)

and calculated from

$$Y = \frac{\mathbf{x}}{r_o^{2k}\mu_e} \left(\frac{2\xi}{Re_x}\right)^{\frac{1}{2}} \int_0^{\eta} \frac{\rho_e}{\rho} d\eta \qquad (87)$$

The momentum thickness is given by

$$\theta = \int_{0}^{\infty} \frac{\rho u}{\rho_{e} u_{e}} \left(1 - \frac{u}{u_{e}}\right) dy \qquad (88)$$

or in  $\xi$  ,  $\eta$  - coordinates by

$$\theta = \frac{(2\xi)^{\frac{1}{2}}}{\rho_{e} u_{e} r_{o}^{k}} \int_{o}^{\infty} f' (1-f') d\eta$$
 (89)

A normalized momentum thickness is calculated from

$$\boldsymbol{\theta} = (\operatorname{Re}_{\mathbf{x}})^{\frac{1}{2}} \frac{\theta}{r_{o}^{k}} = \frac{\mathbf{x}}{r_{o}^{2k} \mu} \left( \frac{2\xi}{\operatorname{Re}_{\mathbf{x}}} \right)^{\frac{1}{2}} \left[ \int_{o}^{\infty} f'(1-f') \, d\eta \right]$$
(90)

The shear stress at the wall is

$$r_{w} = \mu_{w} \left(\frac{\partial u}{\partial y}\right)_{w}$$
(91)

and in ξ, η coordinates

.

$$\tau_{w} = \frac{\rho_{w} \mu_{w} u_{e}^{2} r_{o}^{k} f_{w}^{*}}{(2\xi)^{\frac{1}{2}}}$$
(92)

Introducing the local skin friction coefficient defined as

$$c_{f} = \frac{\tau_{W}}{\frac{1}{2}\rho_{e} u_{e}^{2}}$$
(93)

gives

$$\mathbf{c}_{\mathbf{f}} = \left(\frac{2}{\xi}\right)^{\frac{1}{2}} \frac{\rho_{\mathbf{w}}}{\rho_{\mathbf{e}}} + \mathbf{w} \mathbf{r}_{\mathbf{o}}^{\mathbf{k}} \mathbf{f}_{\mathbf{w}}^{\mathbf{u}}$$
(94)

The heat transfer at the wall is

$$-q_{w} = \left\{ \lambda \frac{\partial T}{\partial y} + (h_{f} - h_{i}) \left[ \rho D_{fi} \frac{\partial c_{f}}{\partial y} + D_{f}^{T} \frac{1}{T} \frac{\partial T}{\partial y} \right] \right\}_{w}$$
(95)

$$-q_{w} = \left\{ \frac{\lambda}{\overline{C}_{p}} \frac{\partial h}{\partial y} + (h_{f} - h_{i}) \frac{\lambda}{\overline{C}_{p}} \left[ (L_{e} - 1) \frac{\partial c_{f}}{\partial y} + \frac{\overline{C}_{p}}{\lambda} D_{f}^{T} \frac{1}{T} \frac{\partial T}{\partial y} \right] \right\}_{w} (96)$$

In terms of  $\xi$  ,  $\eta\text{-coordinates}$ 

$$-q_{w} = \frac{\mu_{w} \rho_{w} u_{e} H_{e} r_{o}^{k}}{\Pr_{w} (2\xi)^{\frac{1}{2}}} \begin{cases} g_{w}^{\prime} + \left(\frac{h_{f} - h_{i}}{H_{e}}\right)_{w} \end{cases}$$

$$\left[ (Le - 1) c_{f} z^{\prime} + \frac{\Pr D_{f}^{T}}{T\mu} T^{\prime} \right]_{w} \end{cases}$$

$$(97)$$

The Stanton number is defined as

$$St = \frac{-q_w}{\rho_e u_e H_e (1-g_w)}$$
 (98)

`

$$St = \frac{\mu_{w} \rho_{w} r_{o}^{k}}{\Pr_{w} \rho_{e} (1-g_{w}) (2\xi)} \sqrt{2} \left\{ g_{w} \right\}$$

$$+ \left(\frac{h_{f} - h_{i}}{H_{e}}\right)_{w} \left[ (Le-1) c_{f} z' + \frac{\Pr D_{f}^{T}}{\mu T} T' \right]_{w} \right\}$$
(99)

If TVC is included the following expressions are used:

The displacement thickness is given by

$$\delta^{\#} \left( 1 + \frac{\delta^{\#}}{2r_{o}} \cos \alpha \right) = \int_{0}^{\infty} \left( (1 - \frac{\rho_{u}}{\rho_{e} u_{e}}) \left( 1 + \frac{y}{r_{o}} \cos \alpha \right) dy$$
(100)

To express  $\delta^*$  in  $\overline{\xi}$ ,  $\overline{\eta}$  coordinates

$$d\overline{y} = \left(\frac{r_{o}}{L} + \frac{y}{L} \cos \alpha\right) dy$$
(101)

and

$$\delta^{\ast} = \frac{\mathbf{r}_{o}}{\cos\alpha} \left[ -1 + \left( 1 + \frac{2 \operatorname{L} \cos\alpha}{\operatorname{r}_{o}^{2} \rho_{e} u_{e}} \left( 2\overline{\xi} \right)^{2} \int_{O}^{\infty} \left( \frac{\rho_{e}}{\rho} - f^{\dagger} \right) d\overline{\eta} \right)^{\frac{1}{2}} \right]$$
(102)

A normalized displacement thickness is defined by

$$\Delta^{*} = \left\langle \operatorname{Re}_{\mathbf{x}} \right\rangle^{\frac{1}{2}} \frac{\delta^{*}}{\mathbf{r}_{o}}$$
(103)

and calculated from

$$\Delta^{\alpha} = \frac{\left(\operatorname{Re}_{\mathbf{x}}\right)^{\frac{1}{2}}}{\cos \alpha} \left[ -1 + \left(1 + A \int_{O}^{\infty} \left(\frac{\rho_{\mathbf{e}}}{\rho} - \mathbf{f}\right) d\overline{\eta}\right)^{\frac{1}{2}} \right]$$
(104)

where

$$A = \frac{2L\cos\alpha}{r_o^2 \rho_e^2 u_e^2} (2\vec{\xi})^{\frac{1}{2}}$$
(105)

The transformation to  $\overline{\eta}$  and its inverse are:

$$\overline{\eta} = \frac{\rho_e \, u_e}{(2\overline{\xi})^{\frac{1}{2}}} \int_{0}^{\overline{y}} \frac{\rho}{\rho_e} \, d\overline{y}$$
(106)

$$\overline{y} = \frac{(2\overline{\xi})^{\frac{1}{2}}}{\rho_e^{u}e} \int_{0}^{\frac{1}{2}} \frac{\rho_e}{\rho} d\overline{\eta}$$
(107)

using equation (101)

$$y = \frac{r_{o}}{\cos\alpha} \left[ -1 + \left( 1 + \frac{2L\cos\alpha}{r_{o}^{2}\rho_{e}u_{e}} \left( 2\overline{\xi} \right)^{\frac{1}{2}} \int_{0}^{\overline{\eta}} \frac{\rho_{e}}{\rho} d\overline{\eta} \right)^{\frac{1}{2}} \right]$$
(108)

a normalized y is defined below

$$Y = (Re_x)^{\frac{1}{2}} \frac{y}{r_o}$$

and calculated from

$$Y = \frac{(Re_x)^{\frac{1}{2}}}{\cos\alpha} \left[ -1 + \left( 1 + A \int_{O}^{\overline{\eta}} \frac{\rho_e}{\rho} d\overline{\eta} \right)^{\frac{1}{2}} \right]$$
(109)

where A is defined by equation (105)

The momentum thickness is given by

$$\theta \left(1 + \frac{\theta}{2r_o} \cos \alpha\right) = \int_{0}^{\infty} \frac{\rho u}{\rho_e u_e} \left(1 - \frac{u}{u_e}\right) \left(1 + \frac{y}{r_o} \cos \alpha\right) dy \quad (110)$$

and in  $\overline{\xi},\ \overline{\eta}$  coordinates becomes

1

$$\Theta = \frac{r_o}{\cos \phi} \left[ -1 + \left( 1 + A \int_0^{\omega} f' (1 - f') d\eta \right)^{l_2} \right]$$
(111)

A normalized momentum thickness is defined by

$$\boldsymbol{\theta} = (\operatorname{Re}_{\mathbf{x}})^{\frac{1}{2}} \frac{\boldsymbol{\theta}}{\mathbf{r}_{o}}$$
(112)

and obtained from

$$\boldsymbol{\theta} = \frac{\left(\operatorname{Re}_{\mathbf{x}}\right)^{\frac{1}{2}}}{\cos\alpha} \left[ -1 + \left(1 + \operatorname{A} \int_{0}^{\infty} \mathbf{f}^{\dagger} \left(1 - \mathbf{f}^{\dagger}\right) d_{\overline{\eta}}\right]^{\frac{1}{2}} \right]$$
(113)

The shear stress obtained from equation (91)

in  $\overline{\xi},\ \overline{\eta}$  coordinates is given by

$$\tau_{w} = \frac{\rho_{w} \mu_{w} u_{e}^{2} r_{o} f_{w}^{n}}{L (2\bar{\xi})^{\frac{1}{2}}}$$
(114)

Introducing  $c_{f}$  defined by equation (93) gives

$$c_{f} = \left(\frac{2}{\xi}\right)^{\frac{1}{2}} \frac{r_{o}}{L} = \frac{\rho_{w}}{\rho_{e}} + \mu_{w} = f_{w}^{*}$$
(115)

The surface heat transfer obtained from equation (95) in  $\overline{\xi}, \ \overline{\eta}$  coordinates is given by

$$-q_{w} = \frac{\mu_{w} \rho_{w} u_{e} H_{e} r_{o}}{L Pr_{w} (2\bar{\xi})^{\frac{1}{2}}} \left| g_{w}' + \left( \frac{h_{f} - h_{i}}{H_{e}} \right) \right|_{w} + \left[ (Le-1) c_{f} z' + \frac{Pr D_{f}}{\mu T} T' \right]_{w} \right|$$
(116)

Stanton number is given by equation (98) and becomes

$$St = \frac{\mu_{W} \rho_{W} r_{o}}{\Pr_{W} L \rho_{e} (1-g_{W}) (2\overline{\xi})^{\frac{1}{2}}} \left| g_{W}^{\dagger} + \left(\frac{h_{f} - h_{i}}{H_{e}}\right)_{W} \left[ (Le-1) c_{f} z' + \frac{\Pr_{D} D_{f}^{T}}{\mu_{T}} T' \right]_{W} \right|$$
(117)

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### 7.0 RESULTS AND DISCUSSION

The laminar boundary-layer flow field was calculated for a 9° halfangle cone at a free stream Mach number of 10 and free stream Reynolds number, based on cone slant length, of 940. Cases were computed with and without mass injection. The following edge conditions were used for all cases computed:\*

$$u_{e} = 7897.0 \text{ ft/sec} \qquad \rho_{e} = 3.485 \times 10^{-7} \text{ lb sec}^{2}/\text{ft}^{4}$$

$$H_{e} = 3.395 \times 10^{7} \text{ ft}^{2}/\text{sec}^{2} \qquad T_{e} = 460.09^{\circ}\text{R}$$

$$\rho_{e} = 0.2749 \text{ lb/ft}^{2} \qquad \mu_{e} = 3.368 \times 10^{-7} \text{ lb sec/ft}^{2}$$

$$c_{f_{e}} = 1.0$$

The conditions at the wall are specified by  $f_w$ ,  $g_w$ , and  $z_w$ . At locations where the wall is solid  $f_w$  is zero; at locations where mass injection takes place  $f_w$  is given by equation (30a). If TVC (transverse curvature) is neglected  $f_w$  is given by a slightly modified form of equation (30a), shown below

$$f_{w} = -\frac{1}{(2\xi)^{1_{2}}} \int_{0}^{x} \rho_{w} v_{w} r_{o} dx$$

J

<sup>\*</sup> These values are within the range of test conditions of the AEDC-VKF Low Density Tunnel L.

It should be kept in mind that without TVC the Probstein-Elliott transformation is not used and the independent variables are unbarred. The value of  $g_w$  used is based on a surface temperature of 1116.6°R; for pure air this corresponds to a value for  $g_w$  of 0.2. The value of  $z_w$  is unity at surface locations with no mass transfer and is zero at locations where there is injection of a foreign gas.

The body used for computational purposes is based on a test model employed at AEDC-VKF. It is a 9° half-angle cone with solid front section followed by a porous section used for mass injection. Taking the slant length of the cone as l the porous section begins at an x/l of 0.4218. The actual length of the test model is 2.397 in. and the free stream Reynolds number used is based on this length. In all cases calculated with blowing the mass injection rate is assumed uniform from 0.4218l to the base of the cone (see Figure 3).



Figure 3. - Diagram of Cone Model

The results presented in this section are for calculations both with and without the TVC term included in the equations. Both sets of results are exhibited in order to provide a basis for comparison of predicted values obtained from a standard Mangler treatment with values obtained from an exact treatment of TVC.

The TVC term t as can be seen from equation (25) is of the form

$$t = F(\overline{\xi}) \int_{0}^{\overline{\eta}} \frac{\rho_{e}}{\rho} d\overline{\eta}$$

where the function  $F(\overline{\xi})$  is well behaved if the radius of the body is finite. However, if the radius is zero, which is the case at the tip of a cone,  $F(\xi)$ becomes singular. Trial solutions indicated that downstream solutions are insensitive to the value of F(0). Numerical solutions were obtained first by neglecting F(0) and using various distributions of  $\overline{\xi}$  near the tip of the cone. The different solutions converged to the same values downstream of the tip and it was shown that the region of convergence moved upstream as locations closer to the tip were used. Neglecting F(0), however, did cause the results in a region near the tip to be of questionable accuracy; for example, the skin friction coefficient rather than decreasing monotonically exhibited a slight dip and rise near the tip prior to decreasing. This phenomenon was eliminated by employing a value of F(0) which is higher than F( $\overline{\xi}_1$ ) where  $\overline{\xi}_1$ is the first location past the tip at which a solution is obtained. In all calculations involving TVC, the first station past the tip was taken at a value of  $\overline{\xi}$  of 0.236231 x 10<sup>-22</sup>; this corresponds to an x/ $\ell$  of 2.5 x 10<sup>-4</sup>. As the solution proceeded downstream, larger increments of  $\overline{\xi}$  could be handled and a total of 27 stations were used for the complete cone. The value of

F(0.236231 x  $10^{-22}$ ) for the particular flow studied here is 16.1496 and F(0) was arbitrarily chosen as 32. An examination of equations (22), (23) and (24) indicates that as larger values of F(0) are used the values of f''(0), g'(0), and z'(0) increase and in the limit as F(0)  $\longrightarrow \infty$  f', g, and z are unity for all  $\eta$  greater than zero. The use of a large value for F(0) will provide steep gradients at the wall and hence provide reasonable starting profiles.

The Hartree Womersley method was originally developed to handle a one component gas (references 14 and 31). A different transformation than is employed in the present investigation was used and the method was programmed for pure air. In the present investigation, if z is unity and z' is zero for the whole boundary layer, then the binary mixture equations reduce to those describing pure air. Although the solution of the species equation would yield a z of unity throughout the boundary layer for a single component, an option was incorporated in the computer program which can be used to bypass the solution of the species equation and automatically yield a value of unity for z and zero for z'. The fluid properties computed are then those of pure air. Using this option, the boundary layer with mass injection of air on the body, shown in Figure 3, was computed neglecting TVC and compared to results using the method described in references 14 and 31. The fluid property relations used in the two methods and the mathematical transformations differ; values of displacement thickness and Stanton number divided by skin friction coefficient shown in Table V are in fair agreement. This comparison was made primarily for the purpose of checking the system of reducing the binary mixture equations to those for a single component.

Figures 4 through 11 and Tables VI and VII exhibit results from calculations both neglecting and including TVC and employing helium, air, argon and carbon dioxide as the injected gas.

Since viscous interaction is neglected in the present calculations, the quantity  $\beta$  appearing in equation (22) is zero and since the free stream is pure air for all locations along the cone, the quantity S appearing in equation (24) is zero. The circled points in Figures 5(b) and 10(b) indicate locations on the cone at which solutions to equations (22) through (24) were obtained. Intervals of 0.05 of the transformed y coordinate were used with smaller step sizes (see references 20 and 31) near the wall to maintain accuracy.

Probstein and Elliott (reference 16) point out that the additional term in the differential equations arising from the inclusion of the transverse curvature effect causes behavior similar to that of a favorable pressure gradient. Examination of the figures and tables indicate that inclusion of the TVC term causes predictions of skin friction coefficient and Stanton number to be higher and predictions of displacement thickness lower than predictions based upon calculations which neglect TVC; hence, the present results agree with the aforementioned observation of Probstein and Elliott.

The computed results show that, in general, the effect of TVC increases with decreasing molecular weight; hence, its effect is greater for helium injection than injection of any of the other gases. This result is explained by the fact that the TVC term t appearing in the equations contains the quantity  $\int \rho_e /\rho \, d\bar{\eta}$  which increases with decreasing molecular weight. Moreover, the results indicate that inclusion of TVC predicts values of the various boundary layer parameters which differ significantly from values obtained

from calculations which neglect the TVC effect. For example (see Figures 5(a) and 9(a)) with no mass injection, the skin friction coefficient at x/f = 1.0 is about 50% greater when TVC is included. It is also shown (see Tables VI and VII), that the relative effect of helium injection in comparison to air injection is far less pronounced when TVC is taken into account.

Of interest in connection with the results obtained here are experimental results reported by King and Talbot (reference 9) which show that for a given injection rate air has a greater effect on the drag coefficient than does helium. The present results in this respect do not agree with experiment; however, it can be said that the inclusion of TVC in the calculations greatly improves matters regarding agreement between theory and experiment.

It is felt that inclusion of the boundary layer displacement effect on the external flow would be one further refinement which might clear up the discrepancy between theory and experiment. This effect would introduce a favorable gradient and as with TVC the effect would increase with decreasing molecular weight since the pressure gradient term appearing in the momentum equation (i.e., see equation (22)) contains the quantity  $\rho_e/\rho$ .

The present results indicate the importance of solutions utilizing accurate fluid properties to ascertain the relative effects of various injection gases on the boundary layer. For example, a simplified treatment based solely on the molecular weight effect would predict a decreasing effect on  $c_f$  of mass injection with increasing molecular weight of the injected gas. This is due to the effect of the molecular weight on the quantity C. However, as can be seen from the results in Tables VI and VII, the present investigation indicates the opposite effect with regard to injection of argon, and carbon

dioxide. This result is due to the fact that the quantity C is temperature dependent and the heat capacity effect of the injected gas must be taken into account. The present investigation indicates that carbon dioxide injection has a greater effect on reduction of  $c_f$  than argon injection. Although the molecular weight of carbon dioxide is greater, the temperature distribution produced by its injection is considerably lower than that for argon injection (see Figures 8(b) and 11(b)) due to its high heat capacity; hence, the net effect on  $c_f$  is greater than that for argon injection. It is expected, however, that the heat capacity effect would decrease with decreasing surface temperatures and at low Mach numbers the effect of injection would be directly related to molecular weight.

In addition to the effect of including TVC on the skin friction predictions, interesting effects are produced regarding predictions of heat transfer. The results in Table VI based on calculations without TVC indicate that the Stanton number for helium injection is lower than that for any of the other gases. For a binary mixture, the surface heat transfer rate (see equation (95)) is composed of a temperature gradient term and concentration gradient term. Since the heat capacity of helium is much greater than that of air, the concentration gradient will contribute to a heat flux away from the wall and the temperature gradient term which contributes to a heat flux towards the surface will be lowered by the heat capacity effect. The net result indicates heat transfer away from the wall for the set of conditions investigated here. However, with TVC (see Table VII), the conduction term is increased to the point where the net result is heat transfer to the wall. Thus, without TVC, helium appears to be the best coolant of the gases studied here, and with TVC, carbon dioxide appears to be the best coolant. Again, this is due to the fact that the effects of

including transverse curvature are felt the most with helium injection and the least with carbon dioxide injection.

### TABLE V

# COMPARISON OF COMPUTED BOUNDARY LAYER PARAMETERS FOR AIR INJECTION NEGLECTING TVC - Pr = 0.71

x/ <b>[</b>		St /c <sub>f</sub>	0*/ <b>L</b>		
	Present Method	Reference 31	Present Method	Reference 31	
0.20	0.5071	0.5088	0.0570	0. 0581	
0.45	0.5383	0.5327	0.0956	0.0962	
0.60	0,5410	0.5490	0.1200	0.1308	
0.72	0.5509	0.5573	0.1397	0.1508	
0.86	0.5627	0.5675	0.1628	0.1737	
0.90	0.5758	0,5705	0.1694	0.1801	
0.96	0.5708	0,5752	0.1785	0.1897	
1,00	0.5740	0.5783	0.1846	0.1962	

 $\frac{\Pr_w v_w}{\Pr_e u_e} = 0.01434$ 

### TABLE VI

# COMPUTED BOUNDARY LAYER PARAMETERS, NEGLECTING TVC - VARIABLE FLUID PROPERTIES

<u>w</u> w	 0 01147
<sup>p</sup> e <sup>u</sup> e	 0.01141

INJECTED GAS	x/l = 0.75			$\mathbf{x}/\mathbf{l} = 0.90$		
	δ*/ <b>[</b>	° <sub>f</sub>	St x 10	δ*/ <b>l</b>	° <sub>f</sub>	St x 10
He	0.3183	0.0036	-0.1536	0.3695	0.0022	-0.2355
Air	0.1398	0.0140	0.0747	0.1595	0.0114	0.0616
ρ						

$$\frac{r_w w}{\rho_e u_e} = 0.01434$$

Air	0.1459	0.0117	0.0636	0.1699	0.0089	0.0493
Ar	0.1452	0.0162	0.0972	0.1700	0.0126	0.0768
co2	0.1070	0.0159	0.0381	0.1240	0.0124	0.0308

# TABLE VII

# COMPUTED BOUNDARY LAYER PARAMETERS, INCLUDING TVC - VARIABLE FLUID PROPERTIES

Pwvw	_	0 01434
<sup>p</sup> e <sup>u</sup> e	-	0,01101

	x/l = 0.75			$x/\ell = 0.90$		
GAS	δ≭/ <b>L</b>	° <sub>f</sub>	St x 10	δ*/ <b>L</b>	° <sub>f</sub>	St x 10
Не	0.1937	0.0147	0.6603	0.2475	0.0099	0.1656
Air	0.1266	0.0232	0.1205	0.1434	0.0191	0.1001
Ar	0.1280	0.0298	0.1723	0.1451	0.0249	0.1439
co <sub>2</sub>	0.1060	0.0245	0.0529	0.1185	0.0203	0.0491

### 8.0 CONCLUDING STATEMENTS

The method described in this report has proven capable of solving the binary diffusion laminar boundary layer equations. It is applicable to axisymmetric flows with or without transverse curvature effects included and to two-dimensional flows. The mathematical transformations used make it possible to easily include or neglect the transverse curvature terms within the framework of one computer program. A combination of the Probstein-Elliott and Levy-Lees transformations introduces a common term t to the system of equations being solved. If this term is retained, the higher order transverse curvature effects are accounted for in the numerical solution to the equations; if this term is neglected, the equations assume the standard Levy-Lees form and the second-order transverse curvature effects are not accounted for. The general method of solution is identical for both cases; however, the proper inverse transformations used to go back to the physical plane depend on whether or not the quantity t is included or neglected in the solution of the partial differential equations.

The method of solution has been programmed for the IBM 7094 computer for the following mixtures: helium-air, argon-air, and carbon dioxide-air. The program also contains an option which bypasses the solution of the species equation when a calculation with pure air is desired. Variable fluid properties given as functions of local temperature and mass fraction throughout the boundary layer are used. Although the equations appear to be more complex when second-order transverse curvature is accounted for, the actual computing times are less. This is due to the fact that convergence of trial solutions of the momentum equation is more rapid

when the transverse curvature term appears in the equation. Approximately 21 stations along the cone were used to obtain solutions neglecting the TVC term and 27 stations were used when it was included. The total computing times for the complete body were about 47 minutes and 36 minutes respectively.

The results indicate that the TVC effect is significant and increases with decreasing molecular weight. As a corollary of this, the effect of helium injection on the reduction of skin friction relative to the effect of air injection is far less pronounced when TVC is taken into account. Solutions to the equations containing the TVC term yield values of skin friction coefficient and Stanton number higher and values of displacement thickness lower than solutions which neglect this term.

The results obtained indicate the necessity of using exact fluid properties to ascertain the relative effects of injection of various gases.

The investigation of viscous interaction for hypersonic flow over slender cones with mass injection is recommended for future study. This investigation could be conducted by using the present method together with an iteration between external pressure distribution and computed displacement thickness. It is felt that the viscous interaction effect will increase with decreasing molecular weight of the injected gas and, in general, will cause behavior similar to that caused by inclusion of the transverse curvature effect.

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Figure 4. - Comparison of Boundary Layer Parameters for He and Air Injection, Neglecting TVC. (a) Coefficient of Skin Friction



Figure 4. - Concluded. (b) Displacement Thickness

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Figure 5. - Boundary Layer Parameters for Air Injection, Neglecting TVC. (a) Coefficient of Skin Friction



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Figure 5. - Concluded. (b) Displacement Thickness


Figure 6. - Boundary Layer Parameters for Ar Injection, Neglecting TVC. (a) Coefficient of Skin Friction



Figure 6. - Concluded. (b) Displacement Thickness



Figure 7. - Boundary Layer Parameters for CO<sub>2</sub> Injection, Neglecting TVC. (a) Coefficient of Skin Friction

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Figure 7. - Concluded. (b) Displacement Thickness

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Figure 8. - Concluded. (c) Mass Fraction Profiles







Figure 9. - Concluded. (b) Displacement Thickness





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Figure 11. - Comparison of Boundary Layer Profiles at x/l = 0.75, Including TVC. (a) Dimensionless Velocity Profiles

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Figure 11. - Continued. (b) Temperature Profiles

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Figure 11. - Concluded. (c) Mass Fraction Profiles

Security Classification									
DOCUMENT CONTROL DATA · R&D									
1 ORIGINAT NG ACTIVITY (Corporate suthor) Douglas Aircraft Div., a Div. of Aircraft Co., Inc., Long Beach, C	Douglas alifornia	28 REPOR UNCL 25 group N/A	ASSIFIED						
3 REPORT TITLE SOLUTION TO THE BINARY DIFFUSION LAMINAR BOUNDARY LAYER EQUATIONS INCLUDING THE EFFECT OF SECOND-ORDER TRANSVERSE CURVATURE									
DESCRIPTIVE NOTES (Type of report and inclusive dates) N/A									
5 AUTHOR(S) (Lest name. first name, initial) Jaffe, N. A., Lind, R. C., and Smith, A. M. O., Douglas Aircraft Div.									
6. REPORT DATE February 1967	74 TOTAL NO OF P	AGES	75 NO OF REFS 31						
BA CONTRACT OF GRANT NO AF40(600)-1000 5 project no 8953	SA ORIGINATOR'S REPORT NUMBER(S) AEDC-TR-66-183								
• Program Element 62405334	9b -OTHER REPORT NO(S) (Any other numbers that may be assigned this report)								
<sup>d</sup> Task 895303 and 895306	306 LB-32613								
Available in DDC.									
11 SUPPLEMENTARY NOTES Work was con- ducted under Purchase Order 5A- 9405 from ARO, Inc., Contract Operator, AEDC	12 SPONSORING MILITARY ACTIVITY Arnold Engineering Development Center, Air Force Systems Command, Arnold Air Force Station, Tenn.								
This report presents a numerical method for solving the binary diffusion laminar boundary-layer equations. The differential equa- tions of continuity, momentum, energy, and species diffusion are solved simultaneously for two-dimensional or axisymmetric flow. For the case of axisymmetric flow the second-order transverse curvature terms appearing in the equations are retained. Relations for mixture fluid properties as functions of local conditions in the boundary layer are developed and used in obtaining solutions to the equations. The mixtures considered in this investigation are He - air, Ar - air, and CO <sub>2</sub> - air. Solutions to the equations are given for flow of a pure air free stream over a 9° half angle cone at a free stream Mach number of 10 and free stream Reynolds number, based on cone slant length of 940. The initial section of the cone is solid and mass injection is initiated at a location downstream of the tip. Results are presented and compared for calculations both including and neglect ing the second-order transverse curvature effect.									

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14	KEY WORDS	LINK A		LINK B		LINK C	
		ROLE	ΨT	ROLE	WT	ROLE	WΤ
	binary diffusion						
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