

Approved for MTS rel. ...



-7he RH Corporation

9)

## SUMMARY

The purpose of this paper is to illustrate how the techniques of the theory of dynamic programming may be used to convert a number of eigenvalue problems, where one is interested only in maximum or minimum values, into problems involving recurrence relations.

#### EIGENVALUES AND FUNCTIONAL EQUATIONS

#### Richard Bellman

61. INTRODUCTION

The purpose of this paper is to illustrate how the techniques of the theory of dynamic programming, image may be used to convert a number of eigenvalue problems, where one is interested only in maximum or minimum values, into problems involving recurrence relations.

In turn we shall treat Jacobi matrices, some special types of quadratic forms possessing certain features of regularity, and finally Sturm-Liouville problems. The connection between Sturm-Liouville problems and dynamic programming has already been discussed in [2], using an approach different from that we shall present here.

Solution The method discussed **below** is not only useful for computational purposes, but provides a method for studying the analytic dependence of the maximum and minimum eigenvalues upon the analytic structure of the matrix.

## 62. JACOBI MATRICES.

Let us consider the Jacobi matrix

(1) 
$$J = \begin{pmatrix} b_1 & a_1 & 0 \\ a_1 & b_2 & a_2 \\ \vdots \\ 0 & a_{N-1} & b_{N-1} & a_{N-1} \end{pmatrix} = \begin{pmatrix} a_{N-1} & b_{N-1} & a_{N-1} \\ & a_{N-1} & b_{N} \end{pmatrix}$$

Other computational techniques are treated in papers of W. Karush, [4] and C. Lanzcos, [5].

and the associated quadratic form

(2) 
$$Q(x) = \sum_{k=1}^{N} b_k x_k^2 + 2 \sum_{k=1}^{N-1} a_k x_k x_{k+1}$$
.  
Define the sequence of functions  
 $f_n(y) = \max_{x_{n=1}^{N-1}} \left[ b_N x_N^2 + 2y x_N \right]$ ,

(3) N  

$$f_{R}(y) = \max_{\{x\}} \left[ \sum_{k=R}^{N} b_{k} x_{k}^{R} + 2y x_{R} + 2 \sum_{k=R}^{N-1} a_{k} x_{k} x_{k+1} \right]$$

where the maximization is over the region

(4) 
$$\sum_{k=R}^{N} x_{k}^{2} = 1$$
.

The maximum characteristic root of J is clearly  $f_1(0)$ .

Let us now show that we can obtain a recurrence relation connecting the members of the sequence  $\{f_R(y)\}$  . Write

(5) 
$$f_{R}(y) = \max_{\{x\}} \left[ b_{R} x_{R}^{2} + 2yx_{R} + \sum_{k=R+1}^{N} b_{k} x_{k}^{2} + 2a_{R} x_{R} x_{R+1} \right]$$

+ 
$$2\sum_{k=R+1}^{N-1} a_k x_{k+1}$$

Once  $x_R$  has been chosen, the problem of choosing the remaining  $x_k$  is quite similar to the original, with R transformed into R+1 and the constraint on the remaining  $x_k$  taking the form

$$(c) \sum_{k=R+1}^{N} x_k^2 = 1 - x_R^2$$

Let us then set

(7) 
$$x_{k} = \sqrt{1-x_{R}^{2}} z_{k}, k = R+1, ..., N$$
,

so that the constraint of 
$$z_k$$
 is  $\sum_{k=R+1}^{N} z_k^2 = 1$ .

We then have

(8) 
$$f_{R}(y) = \max_{\{x\}} \left[ b_{R} x_{R}^{2} + 2yx_{R} + (1-x_{R}^{2}) \left[ \frac{\zeta}{k=R+1} b_{k} z_{k}^{2} + \frac{2a_{R} x_{R} z_{R+1}}{\sqrt{1-x_{R}^{2}}} + 2 \sum_{k=R+1}^{N-1} a_{k} z_{k} z_{k+1} \right] \right].$$

Employing the "principle of optimality," [1], we obtain the recurrence relation

(9) 
$$f_{R}(y) = \max_{\substack{x_{R}^{2} \leq 1}} \left[ b_{R} x_{R}^{2} + 2y x_{R} + (1 - x_{R}^{2}) f_{R+1} (a_{R} x_{R} / 1 - x_{R}^{2}) \right]$$

for R = 1, 2, ..., N-1.

A similar recurrence relation may be obtained for the minimum eigenvalue with Min replacing Max.

## 53. EXTENSIONS

Similar recurrence relations, of more complicated form, may be obtained from the consideration of matrices of the form



The basic sequence is

(2) 
$$f_{R}(u,v) = Max \left[ \sum_{k=R}^{N} b_{k} x_{k}^{*} + 2 \sum_{k=R}^{N-1} a_{k} x_{k} x_{k+1} + 2 \sum_{k=R}^{N-2} c_{k} x_{k} x_{k+2} + 2 u x_{R} + 2 v x_{R+1} \right].$$

### 54. SOME SPECIAL CLASSES OF QUADRATIC FORMS

Consider the following three special classes of quadratic forms

(a) 
$$Q_1 = (ax_1)^2 + (x_1 + ax_2)^2 + \dots + (x_1 + x_2 + \dots + x_{N-1} + ax_N)^2$$
,  
(1) (b)  $Q_2 = x_1^2 + (x_1 + ax_2)^2 + \dots + (x_1 + ax_2 + \dots + a^{N-1}x_N)^2$ ,  
(c)  $Q_3 = x_1^2 + (x_1 + ax_2)^2 + (x_1 + ax_2 + (a+b)x_3)^2 + \dots + (x_1 + ax_2 + (a+b)x_3 + \dots + (a+(N-2)b)x_N)^2$ .

For the first quadratic form, define the sequence

(2) 
$$f_{R}(y) = \max_{\{x\}} [(y+ax_{R})^{2}+(y+x_{R}+ax_{R+1})^{2}+\ldots+(y+x_{R}+x_{R+1}+\ldots+x_{N-1}+ax_{N})^{2}],$$
  
over the region  $\sum_{k=R}^{N} x_{R}^{2} = 1.$ 

As above, we obtain the recurrence relation

(5) 
$$f_{R}(y) = \max_{\substack{x_{R} \leq 1 \\ x_{R} \leq 1}} \left[ (y + ax_{R})^{2} + (1 - x_{R}^{2}) f_{R+1}((y + x_{R})/\sqrt{1 - x_{R}^{2}}) \right].$$

Recurrence relations of similar form may be obtained for the other quadratic forms and for the minimum characteristic roots.

Many other special classes of quadratic forms can be constructed to yield simple recurrence relations. The form

(4) 
$$\frac{\underline{N}}{\underline{\lambda}} \left[ (x_{k} - a_{k})^{2} + b_{k} (x_{k} - x_{k-1})^{2} \right]$$

is discussed in [3].

# 65. EIGENVALUE PROBLEMS

If  $\phi(x)$  is a continuous function over [0,1], uniformly positive so that  $\dot{\phi}(x) \ge a^2 > 0$ , the problem of determining the values of  $\lambda$  which yield non-trivial solutions of

(1)  
$$u'' + \gamma \phi(x)u = 0,$$
  
 $u(0) = u(1) = 0,$ 

is equivalent to the problem of determining the relative minima of

(2) 
$$J(u) = \int_{0}^{1} u^{12} dx$$
,

subject to the constraints

(a) 
$$\int_{0}^{1} \phi(x)u^{2}dx = 1$$
,  
(5)  
(b)  $u(0) = u(1) = 0$ .

We shall consider here only the absolute minimum. Using a different approach, a functional equation connected with this quantity was derived in [2]. Here we use the following approximate technique. Consider the problem of minimizing

(4) 
$$J = \sum_{k=1}^{N} (u_k - u_{k-1})^* \Delta$$
,

1

subject to the restrictions

(a) 
$$\sum_{k=1}^{N-1} \phi_k u_k^2 \Delta = 1$$
,  
(5) (b)  $u_0 = x$ ,  $u_N = 0$ .

Set  $\phi_k = g_k^2$ ,  $x_k = g_k u_k$ , and absorb the  $\triangle$  factor, obtaining the problem of minimizing

,

.

(6) 
$$J(x) = \sum_{k=1}^{N} \left( \frac{x_{k}}{g_{k}} - \frac{x_{k-1}}{g_{k-1}} \right)^{2}$$

subject to

.

(a) 
$$\sum_{k=1}^{N-1} x_k^2 = 1$$
,  
(7) (b)  $x_0 = zg_0, x_N = 0$ 

Define the sequence

(8) 
$$f_{R}(z) = Min \sum_{k=R}^{N} \left( \frac{x_{k}}{g_{k}} - \frac{x_{k-1}}{g_{k-1}} \right)^{2}$$
,

with 
$$x_{R-1} = zg_{R-1}$$
, over  $\sum_{k=R}^{N} x_k^2 = 1$ ,  $x_N = 0$ .

We have

(9) 
$$f_N(z) = \min_{\substack{x_N^2 = 1 \\ N}} \left( \frac{x_N}{g_N} - z \right)^2$$
  
=  $Min \left[ \left( \frac{1}{g_N} - z \right)^2, \left( \frac{1}{g_N} + z \right)^2 \right],$   
and  
(10)  $f_P(z) = Min \left[ \left( \frac{x_R}{g_N} - z \right)^2 + \left( 1 - x_P^2 \right) f_{P+1} \left( x_P / g_P \sqrt{1 - x_P^2} \right) \right]$ 

(10) 
$$f_{R}(z) = M_{1R} \left[ \left( \frac{x_{R}}{g_{R}} - z \right)^{2} + \left( 1 - x_{R}^{2} \right) f_{R+1} \left( x_{R} / g_{R} \int 1 - x_{R}^{2} \right) \right]$$

#### REFERENCES

- [1] Bellman, Richard, "The Theory of Dynamic Programming," Bull. Amer. Math. Soc., vol. 60(1954), pp. 503-516.
- [2] \_\_\_\_\_, "Dynamic Programming and a New Formalism in the Calculus of Variations," Proc. Nat. Acad. Sci., vol. 40(1954), pp. 231-235.
- [3] \_\_\_\_\_, "On a Class of Variational Problems," Quart. Applied Math., (to appear).
- [4] Karush, W., "An Iterative Method for Finding Characteristic Vectors of a Symmetric Matrix," <u>Pacific Journal of Math.</u>, vol. 1(1951), pp. 233-248.
- [5] Lanzcos, C., "An Iteration Method for the Solution of the Eigenvalue Problem of Linear Differential and Integral Operators," J. Research Nat. Bur. Standards, vol. 45(1950), pp. 255-282.