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PREDICTION OF SPACE VEHICLE THERMAL CHARACTERISTICS

 $Q_{f} = 33(615) - 1755$ J. T. Bevans, et al.

J. T. Bevans, et al. TRW Systems Group

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FOREWORD

The following report was/prepared by TRW Systems Group, under USAF Contract No. AF 33(615)-1725 as part of Project 6146, Task 614617. The program was administered by the Air Force Flight Dynamics Laboratory, Research and Technology Division, Wright-Patterson Air Force Base. The Technical Monitor was Mr. C. J. Feldmanis.

The program was performed by J. T. Bevans, T. Ishimoto, B. R. Loya, and E. E. Luedke. Dr. D. K. Edwards of the University of California, at Los Angeles, was consultant throughout the study.

The manuscript was released by the authors 31 August 1965, for publication as an RTD Technical Report.

This technical report has been reviewed and is approved.

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Environmental Control Branch Vehicle Equipment Division AF Flight Dynamics Laboratory

ABS TRACT

「東京村大学」をごときであたいであります。

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The work reported herein is the first phase of a program to improve the prediction of spacecraft thermal performance. The study has consisted of measuring actual joint thermal conductances, correlation of the measured joint conductances, programing an improved method of thermal radiation analysis, and performing an experimental comparison of predicted radiation exchange for a simple geor trical system.

Three types of structural and three sizes of component mounting joints were tested and the conductances measured. A successful method of correlation was developed for the unfilled component mounting joints. All joints were selected for their applicability to the next phase of the program, a thermal test of a spacecraft model.

A method of radiation analysis has been programed which uses directional thermal radiation properties and accounts for the specularity and/or diffuseness of these properties. The results of this program can be readily incorporated into most existing thermal analysis programs. The user has the choice of the specular, the diffuse, or the specular-diffuse assumption. The prediction of radiation exchange using these assumptions for simple geometrical avrangements has been compared to experiment. Although the results were within the overall experimental tolerances, further improvement in the predicted values is believed possible.

The study has developed several important technical areas which are worthy of further evaluation. The first is the extension of the correlation techniques to include filled component joints and filled or unfilled structural joints. Continuation of the general measurement of joints to develop 4 large knowledge of practical joint conductances is also indicated. The comparison of experimental and predicted radiation exchange has shown that a more extensive study is needed of thermal radiation properties to determine the division of these properties into specular and diffuse components. The non-gray error of radiation analysis has also been shown to be an important area for further study.

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SYMBOLS

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| Section 3 | |
|--------------|---|
| A | Area - ft^2 |
| h | Thermal conductance - Btu/hr ft ² F; $h_{eff} = effective h$ |
| q | Heat flow - Btu/hr |
| t | Temperature - ^O F |
| Section 4 | |
| A | Area of a surface $-ft^2$ |
| В | Quantity introduced by Gebnart - Btu/hr ft R4 (Section 4.1) |
| С | Heat capacity - Btu/hr |
| D | Diffuse irradiation - Btu/hr ft^2 ster. (Section 4.2) |
| F | Geometrical shape factor |
| 3 | "Script F" |
| J | Radiosity - Btu/hr ft ² |
| M | Number of surfaces within the enclosure |
| N | Number of time intervals |
| R | Thermal conduction resistance - hr $^{\circ}F/Btu$ (Equation $L-3$) |
| R | Hottel's radiant power leaving a surface - Btu/hr ft ^{2 0} R ⁴ (Section 4.1) |
| Т | Absolute temperature - ^O R |
| 3 | Coefficient (Section 4.2) |
| Ъ | Coefficient (Section 4.2) |
| С | Coefficient (Section 4.2) |
| đ | Coefficient (Section 4.2) |
| i,j,k | Indices representing surfaces within the enclosure |
| q | Heat flow Btu/hr |
| r,y,z | Indices |
| α | Absorptance |
| 3 | Emittance |
| η | Convergence factor (Equation 4-8) |
| fτ | 3.1415927 |
| ρ | Reflectanco |
| σ | Stefan-Boltzmann constant - Btu/hr ft ²⁰ R ⁴ |
| 0 | Time |

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SYMBOLS (Cont.)

[] Square matrix

[]⁻¹ Inverse square matrix

{ } Column matrix

Section 5

Symbols defined in the text.

Section 6

| Q | Source heat flow - Btu/hr | | | |
|------|---|--|--|--|
| p(θ) | Directional reflectance at angle θ | | | |
| 9 | Angle between the normal to the surface and the | | | |
| | incident or reflected radiation - degrees | | | |

Section 7

| A | Area, ft ² |
|----|--|
| Q | Heat flux, Btu/hr ft ² |
| R | Radius - in. |
| Т | Temperature, ^O F |
| 8 | Bolt diameter, in. |
| Ъ | Twice the plate thickness, in. |
| c | Effective contact radius, in. |
| đ | Bolt major thread dia. |
| h | Thermal conductance - Btu/hr ft ² °F |
| k | Thermal conductivity - Btu/hr ft ^O F |
| r | Radial position, in. |
| t | Plate thickness - it. |
| η | Nondimensional radius ratio - r/R |
| ηο | Nondimensional radius constant R _o /R |

Appendix IV

 $T_R = "Receiver" temperature {}^{O}R$

T_H = "Mirror" temperature ^OR

 $T_c = "Sink" (cold wall) tomperature <math>^{O_R}$

T_g = "Source" temperature ^OR

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1. INTRODUCTION AND SUMMARY

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The program, "Prediction of Space Vehicle Thermal Performance," was initiated on 1 July 1964, under Contract AF 33(615)-1725. The purpose of the study can be stated as: Given the necessary analytical methods and experimental data, how well can the thermal performance of a space vehicle be predicted? The subject program was the first step towards securing an answer to this question.

The problem provides two natural divisions. The first is the examination of the analytical procedures needed and the experimental information required for analysis. The second is the verification of the predictions of analysis by a thermal test of a model space vehicle. The present program was intended to satisfy the first need and to provide a transition to the second. Since a model is required to verify analysis, its design will dictate the nature and scope of the experimental studies performed to support analysis. In particular, the subsequent construction of a test model will require the selection of structural and component joints in anticipation of the design. Depending upon the type of joint selected and the degree of experimental measurements made, the thermal resistance of the joints can be critical to the experimental verification of any predictions made. Consequently, it was necessary at the start of the present program to select, in reasonable detail, the model configuration. The experimental measurements of joint thermal resistance were restricted to those joints to be used in the model. Only in this manner could the end purpose of the study, the test of prediction, be achieved within the allocated resources and time.

The specific tasks undertaken in the study were:

- (a) Selection of a model for determination of the experimental joint thermal conductance measurements
- (b) Experimental measurement of component and s'ructural joint thermal conductance
- (c) Examination of the results of the joint thermal conductance results to ascertain if a correlation were possible
- (d) Comparison of the analytical techniques of Hottel (1), Gebhart (2), and Oppenheim (3).
- (e) Development of a computer program for a specular-diffuse analysis (4)
- (f) Experimental measurement of radiation exchange with real surfaces

The following report will consider the above tasks in the order shown. It should be re-emphasized that the purpose of the program and hence, the goal of each task, is to provide the necessary data for a comparison of thermal analysis and thermal test of a spacecraft model.

2. SPACECRAFT MODEL SELECTION

An important initial task was the conceptual design of the model of the space vehicle to be tested in the subsequent phase of the program. The size, method of construction and shape of the mc'el greatly affects the type of fasteners, the physical dimensions and the shape of the joints.

The model which has been selected is shown in Figure 1. Alternative shapes, cylindrical and spherical, were considered but the rectangular parallelepiped was chosen for economy and ease of fabrication. Furthermore, the geometrical shape can not be a critical factor in a test of the prediction of thermal performance. The indicated dimensions, $24" \times 24" \times 36"$, are sufficiently large to demonstrate the effects of construction variations, thermal gradients, and internal dissipation. The model will conveniently fit into most environmental test chambers and available solar simulation facilities. Also, the size is representative of many present day space vehicles.

A welded framework is indicated. This method of construction was selected to reduce the number of structural joints that had to be tested. There are three structural joints with the frame: the side panels, the end panels, and the component mounting platform. The side and end panels are 1/16-inch aluminum; i.e., thin enough to sustain a thermal gradient. The mounting platform is 1/8-inch aluminum. In actual space vehicle construction, this mounting plate would probably be a honeycomb structure to reduce weight. Such materials are anisotropic and the thermal conductance in the x, y, and z directions are variable from sample to sample of the same material. The conductance also varies widely for different types of honeycomb. Thus, use of a honeycomb structure would introduce a major undetermined factor in the thermal analysis. This could easily obscure the validity of the comparison of prediction and experiment. The aluminum mounting plate avoids this without affecting the value of the test to be conducted. Thus, if the analysis can properly predict for the aluminum plate, it will be satisfactory for application to a honeycomb material (assuming the properties of the honeycomb are known).

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The external panels can be changed to provide different external thermal radiation properties. This may not be important in the initial testing to be performed with the model but will be useful should further testing be desired or required. These panels can be coated to simulate solar cell thermal radiation properties, low a/c properties or even be insulated without affecting the basic model physically. A louver system could be used in place of any panel to determine the effects of variable emission. Hence, the model will be of much more value than just for the program contemplated in Phase II.



Figure 1. Spacecraft Model - Size and Shape

3. THERMAL CONDUCTANCE OF JOINTS

Completely riveted joints were excluded from the study. In spacecraft practice, riveted systems are used in order to save weight. However, the thermal conductance of such joints is not considered reproducible and variations of 100 percent have been found in supposedly identical joints (5). Since the goal of the program is to test the ability to predict thermal performance with reliable input information, the introduction of such an uncontrolled thermal resistance is not desired. This would not test the prediction of thermal performance but only the uncertainty of knowledge. The effect of the variable thermal resistance can be demonstrated analytically, once the analysis has been verified.

Two general types of joints were studied: component and structural joints. The component joints are shown in Figure 2. The dimensions were chosen as representative of typical component base sizes. Simulation of the actual component box was not deemed necessary since this would only involve changes in the radiation shape factors used. The assumption was made that the base plates would have a uniform areal power dissipation. The experimental variables examined were bolt-torque, power dissipation level, filler material and reproducibility of the joints. A detailed description of the test method and the results will be given in Section 3.1.

The structural joints tested are presented in Figure 3 and all are bolted joints. The structural joints were selected to satisfy the requiremants of the proposed space vehicle model (see Section 2). The first configuration corresponds to the joint between the side panels and the frame. The end panels are bolted to the frame by means of nut plates which are riveted in place (second joint). This joint can be considered to be a combination of a rivet and bolt fastener. The third joint shown represents the joint between the component mounting platform and the frame. As with the component joints, the variables of power dissipation level, filler material and reproducibility were examined. The experimental test method and results are given in Section 3.2.

These joints are "practical" ones; i.e., representing actual fabricated joints. As a result, variations in the thermal conductance must be expected from "identical" joints. An attempt was made to apply idealised theories to these joints to obtain a correlation of the test data. The results of this affort are given in Section 7.

3.1 COMPONENT JOINT EXPERIMENTAL DESTS

The component joints were similated by bolting a plate 1/16 inch thick of the necessary dimensions to a base plate 1/8 inch thick. The component base plate dimensions used were 6 inches square, 6 inches by 12 inches, and 12 inches square. The plates upon which the base plates were mounted were 2 inches greater in each dimension than the component plate; e.g., 8 inches square for the 6-inch square component plate. The bolt size and placement for each joint are shown in Figure 2. A heater made of 40 gage constantan wire sandwiched between 1 mil Mylar was bonied to the upper surface of each component base plate. The mounting plate had 1/4 inch



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Figure 2. Component Jointe



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copper cooling coils attached to its underside. The whole assembly was wrapped in 20 layers of super insulation and suspended within a bell jar. This bell jar was evacuated to a pressure less than 10^{-5} torr. Figure 4 shows a component joint after testing; the final assembly and the vacuum system are illustrated in Figure 5. The thermocouples have been removed from this sample so that surface roughness measurements can be made.

The test procedure consisted of placing the insulated and instrumented joint within the bell jar, securing a vacuum on the system, and setting the initial heating rate. Equilibrium was determined by plotting the various temperatures as a function of time. Once these temperatures had stabilized to less than plus or minus 1°F.per hour, a set of data was taken. The observed temperature drift was caused by drift in the cooling water temperature.

The electrical circuit used to measure the power dissipated by the heater is shown in Figure 6. The power was determined by measuring the voltage across the heater terminals at the component joint and measuring the current flowing in the heater with a standard resistor. This procedure is componing referred to as the four terminal resistor technique. The potentiometer used for these two measurements was a Leeds and Northrup Type K-3 Potentiometer. This instrument has three ranges: 1.6 volts, 0.16 volts, and 16 millivolts. The least count on those three ranges is 50, 5, and 0.5 microvolts, respectively.

Initially, temperatures were to be measured with nickel resistance temperature sensors. These sensors were obtained from the RdF Corp., Hudson, New Hampshire, and were calibrated by the vendor to within plus or minus 0.5°F. The first tests did not yield consistent results. This was traced to the resistance sensors. Deviations as large as 2°F were found between initial and final calibrations for a run. Since the temperature differences across a joint were generally smaller than $2^{\circ}F_{F}$ this initial data had to be discarded and the sensors replaced with differential copper-constantan thermocouples. The subsequent data was reproducible and consistent for a given test configuration.

Resistance thermometry has the inherent advantage of measuring an area rather than a point; i.e., a local average. When properly calibrated, it is also a more accurate sensor since the impurities in the metals used ere less important in resistance than in thermoelectric effects. However, this accuracy can only be achieved at a significant increase in cost relativ, to thermocouples. The instrumentation method required for differential resistance thermometry is quite different than that used for resistance thermometry. The ratio of the resistances of two elements must be measured, the absolute value of one of these elements is needed, and two sets of lead resistance corrections are necessary. This involves two different bridge circuits (and/or instruments) and a means for electrical switching. The alternative use of thermocouples can provide a differential accuracy of approximately plus or minus 0.1°F if the thermocouples are cut from the same roll of wire and careful experimental procedures used. The cost is much less, both in construction and use. This is offset by the "point" measurement characteristics of a thermocouple. For this series of tests, the thermal conductivity of the aluminum joint material was sufficient to minimize this problem.

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Figure 4. Typical Component Joint

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Pigure 5. Component Joint Roady for Testing



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The emf of the test thermocouples was measured with a Leeds and Northrup Type K-3 Potentiometer. On the millivolt range, this instrument has a least count of 0.5 microvolts. Doutch No. 14657-37T vacuum feed throughs were used for the thermocouples to avoid a discontinuity in the thermocouple circuitry. When a filler material was used, it was applied by placing two 0.050 inch wires on the surface of the mounting plate, putting an ample quantity of the filler material between the wires and scraping the excess off with a straight edge resting on the wires. Before the material set, in the case of RTV-11 filler material, the component plate was placed on the mounting plate and bolted down. The bolt torques for all joints were set with a calibrated torque wrench. No special instructions were given to the person assembling the joint relative to the order of tightening the bolts. This was intentional since the randomness of a fabricated joint was desired.

5

The results are summarized in Tables 1, 2, and 3; the actual data and the techniques used in its reduction are given in Appendix I. Included in the Appendix are schematic diagrams showing the placement of the temperature sensors. Three specimens of each joint were run with the exception of the G 683 silicons grease filler.^{*} This material was found to be less suitable for use as filler than the silicone rubber. The primary difficulty with the grease was the contamination of the other areas around the joint; i.e., it was messy. Furthermore, it did not yield joint conductances as large as the RTV-11 material.

The results for the 6-inch square joint (Table 1) shows that the effect of heat flux level was small. This was a temperature gradient effect and for the small range involved in this test (from 2.5° F to 10° F for a typical case), it was not important. Similarly, the change in bolt torque from 12 to 30 inch-pounds was not significant. The effect of the RTV-11 was, however, quite significant. It increased the thermal conductance of the 6-inch square joints by a factor of 4 and the larger joints by a factor between 5 and 6.

The most obvicus result of the tests was the inconsistency of the results for "identical" joints. Joint No. 2 of the 6-inch square joints is a good example. An examination of the second joint showed the component base plate to be bowed by 0.007 inches (concave upwards); Joint No. 1 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave upwards). Thus a trend of increased conductance with upward concavity is indicated by these limited tests. In actual fabrication, a flatness tolerance can be imposed, e.g., plus or minus .003 inches, which would minimize this effect. Such a constraint is not unreasonable. The surface roughness of the test plates was measured using a diamond stylus profilometer. The results were consistent for all the plates and yielded 11 μ in. rms across the roll marks and 4 μ in. rms with the roll marks. The surfaces were randomly mated, that is the roll marks placed either parallel or perpendicular, but recorded. The results show no correlation hot striation alignment and conductance values.

Manufactured by General Electric Company, Silicone Products Department

| | TAL RESULTS | |
|---------|-------------|---------------------|
| | EXPERIMENT | арт ² ор |
| TABLE 1 | CONDUCTANCE | ANCE - BTU/HE |
| - | THERMAL | CONDUCT |
| | JOINT | ERMAL |
| | COMPONENT | Ę |

p

6 inch by 6 inch plate, 1/16 inch thick, bolted to 8 inch by 8 inch plate, 1/8 inch thick, using 12 bolts

Bolt Torque

Sample No.

| Sample No. | | | Bolt | Ingue | | | Filler |
|------------|----------|-----------|-----------|---------------------|------------|----------|--------|
| | dl-nt 21 | | れ | dl-nt | | di-ni 06 | |
| | | | Power 1 | Missipa tion | | | |
| | 10 Watte | 4.9 Watts | 8.6 Watts | 13.4 Watts | 18.4 Watts | 10 Watts | |
| 1 | | 22.8 | 23.2 | 22.9 | 23.1 | | None |
| 8 | 28.5 | 29.1 | 30.1 | 1.05 | 30.0 | - : 30.0 | None |
| ۳ ۲2 | 24.8 | 22.1 | 25.9 | 26.2 | 26.6 | | None |
| *r-1 | | 76.9 | 81.5 | 82.5 | 83.2 | | RTV-11 |
| 2 | 123.0 | 126.1 | 127.0 | 129.0 | 130.0 | 142.0 | RTV-11 |
| 9 | 84.1 | 0.16 | 93.5 | 94.8 | 95.4 | - | ETV-JT |
| *,- | | | | | ŗ | | G- 583 |
| 5 | 55.5 | 63.0 | 65.0 | 66.1 | 67.1 | 57.0 | G-683 |
| m | 47.0 | 47.3 | 48.2 | 48.8 | 49.5 | | G-683 |
| | • | | | | | | |

. Same samples as avo, with filler added.

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TABLE 2

COMPONENT JOINT THERMAL CONDUCTANCE EXPERIMENTAL RESULTS THERMAL CONDUCTANCE - BTU/HR FT² °F

6 inch by 12 inch plate, 1/16 inch thick, mounted to 8 inch by 14 inch plate, 1/8 inch thick using 18 bolts; bolt torque 24 in-1b

Power Dissipation

| Sample No. | 10 Watts | 20 Watts | 40 Watts | Filler Material |
|------------|----------|----------|------------|-----------------|
| 1 | 18.5 | 18.9 | 18.5 | None |
| 1 | 103 | 101.5 | 9 8 | RTV-11 |
| 2 | 103 | 101 | 97 | RTV-11 |
| 3 | 90 | 92 | 92 | RTV-11 |

TABLE 3

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COMPONENT JOINT THERMAL CONDUCTANCE EXPERIMENTAL RESULTS THERMAL CONDUCTANCE - BTU/HR FT² °F

12 inch by 12 inch plate, 1/16 inch thick, mounted to 14 inch by 14 inch plate, 1/8 inch thick using 24 bolts; boli torque 24 in-15

| | 1 | Power Dissipa | tion | |
|------------|----------|---------------|----------|-----------------|
| Sample No. | 20 Watts | 40 Watte | 80 Watts | Filler Material |
| 1 ·] | 8.4 | 8.3 | 8.3 | None |
| 1 | 56.6 | 55.8 | 56.1 | RTV-11 |
| 2 | 51.7 | 52.8 | 51 | R TV-11 |
| 3 | 51.4 | 51.9 | 52.4 | RTV-11 |
| 1 | | | | |

The value of the filler for component mounting boxes is apparent. For the proposed test of a spacecraft model, the component boxes will be simulated by resistances dissipating pre-determined values of power. This is very similar to an actual spacecraft system. The higher values of conductance will permit the same heat flow with 1/3 to 1/4 of the temperature difference or conversely, 3 to 4 times the heat flow for the same temperature difference. This should make this type of thermal resistance less critical in the thermal analysis and prediction.

The effect of using filled joints must be investigated for each specific application under consideration. While much higher conductance values were obtained, the scatter in the data was larger for filled than unfilled joints. Therefore, the selection of filled or unfilled joints depends upon whether joints of high conductance, not precisely defined or joints of low conductance, more accurately described, are desired.

The differences in conductance for different sized component mounting plates was also of interest. The filled conductance decreased by a factor of 2 when the dimensions of the square component base was increased from 6 to 12 inches. This decrease is expected since the number of bolts doubled while the total area increased four times. This effectively causes an increase in the conduction pathlength of the mounting plate. These factors will be considered in more detail in Section 7, "Correlation of Experimental Results."

The overall accuracy of the tests is difficult to assess properly. However, the experimental accuracy of the various tests quantities can be given:

Inaccuracy in temperature difference measurement: $\pm 0.1^{\circ}F$ Inaccuracy in temperature measurement: $\pm 0.5^{\circ}F$ Inaccuracy in power dissipation (including insulation loss): $\pm .5\%$ Inaccuracy in area measurement: $\pm .050 \text{ in}^2$ Inaccuracy in bolt torque: ± 0.5 inch-pounds

These values may be combined in a linear error analysis to approximate the total measurement inaccuracy. That is, the error in measured conductance (h) of a typical unfilled joint is:

 $\frac{\Delta h}{h} = \frac{\Delta(\Delta t)}{\Delta t} + \frac{\Delta q}{q} + \frac{\Delta A}{A} = \frac{1}{1} + \frac{.025}{5} + \frac{.05}{.36}$

or

 $\frac{\Delta h}{h} = 10.5\%$

The significance of this inaccuracy must be appraised in terms of the application of the data. The error in the measurement of a single joint is less than the lack of reproducibility between joints. Hence, the more

important factor is the variation of the conductance of "identical" joints. As shown in Tables 1, 2, and 3, this is approximately plus or minus 25 percent. However the influence of such a variation upon a thermal analysis can be either large or small, depending upon the system examined. For example, if a spacecraft thermal control system is conduction controlled, this variation might be critical; conversely, if it were radiation dominated, the differences might be negligible. To determine the importance of these variations requires an error analysis of the specific configuration.

3.2 STRUCTURAL JOINT EXPERIMENTAL TESTS

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The test procedures used for the structural joint measurements were identical to those used with the component joints. The structural joints tested are shown schematically in Figure 3; an actual test joint is shown in Figure 7. A 40 gage constantan and Mylar heater was bonded to one edge of the joint. On the opposite edge, a 1/4 inch copper cooling tube was bonded to provide the necessary heat sink. This whole assembly was wrapped in 20 layers of super insulation and suspended in a bell jar (similar to Figure 5). The remainder of the test procedure was identical to that used for the component joints, e.g., the electrical measurement circuit was that given in Figure 6. Based upon the experience with the component joints, only thermocouples were used as the temperature sensors. The leeds and Northrup Type K-3 Fotentiometer was again used for measuring the thermocouple voltages.

The test results are given in Tables 4, 5, and 6; the actual data from which these results were reduced are given in Appendix II. The first joint tested, Configuration 1 of Figure 3, is representative of the trends indicated for all three joints. Within the range of power dissipations used, no dependency upon power level is indicated for the unfilled joint; i.e., for small temperature differences, the conductance is a constant. A much higher value of joint conductance was obtained with the use of a filler material along with an apparent heat flow dependency. Configuration 2 used nut plates on one side instead of bolts. This had little effect upon conductance for the unfilled case. However, opposite results were obtained for two different RTV-11 filled joints with this configuration; i.e., in one case the rut plate side had a higher conductance and in the other, it had a lower one. No difference between a bolted joint and a nut plate joint could be concluded from the results for Configuration 1 and 2 because of this conflicting data. A strong dependency with heat flow is also noted for the filled joint.

The results of the filled structural joint tests show wide variations in calculated conductance. The most probable reason for these variations is the temperature measurement error. The temperature difference across the interface was of the same order of magnitude as the expected temperature error. In ideal joint conductance tests appearing in the literature (see Section 3.3), the temperature profile of the mating parts is accurately plotted and the data projected to the interface to obtain the temperature difference. The heat flows are normally much higher than 1 the present study and much higher temperature differences result. In the



Figure 7. Typical Structural Joint

| 6 inch joi | int, 2 bolts, 24 | inch-jounds torqu | e, Configuratio | on 1 |
|------------|------------------|-------------------|-----------------|--------|
| loint No.* | | Q - Heat Supplied | l | Filler |
| | 5 Watts | 15 Watts | 25 Watts | |
| la | 70.3 | 74.2 | 75.7 | None |
| Ъ | 80.5 | 80.6 | 85.3 | None |
| 28 | 103.5 | 100.1 | 100.9 | None |
| 2b | 88.5 | 90 | 96.5 | None |
| 34 | 78.5 | 79.4 | 77.0 | None |
| 3h | 77.5 | 79-8 | 81.8 | None |
| la | 1042 | , 906 | 715 | RTV-11 |
| 1b | 1042 | 995 | 895 | RTV-11 |
| la | 502 | 595 | 542 | G-683 |
| 1b | 681 | 652 | 645 | G-683 |

TABLE 4 STRUCTURAL JOINT CONDUCTANCE - BTU/HR FT² °F

9 inch joint, 3 bolts, 24 inch-pounds torque, Configuration 1 Joint No.* Filler

| | 7.5 Watts | 22.5 Watts | 37.5 White | |
|----|-----------|------------|------------|------|
| la | 116.0 | 98.5 | 100.8 | None |
| 1ь | 74.0 | 75.3 | 77.9 | None |

The notation a and b are used to distinguish the side of the joint next to the hester and the cooling soil, respectively.

TABLE 5 STRUCTURAL JOINT CONDUCTANCE, BTU HR FT² °F

6 inch joint, 2 bolts, 24 inch-pounds torque, Configuration 2

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| Joint No. | | | | Filler |
|-------------------|---------|----------|----------|----------------|
| | 5 Watts | 15 Watts | 25 Watts | |
| la (Bolt) | 84.2 | 81.5 | 85.0 | None |
| lb (Nut Plate) | 99.0 | 100.8 | 110.3 | None |
| 2a (Bolt) | 105.5 | 102 | 100.8 | None |
| 2b (Nut Plate) | 82.4 | 81.4 | 83.2 | None |
| 3a (Belt) | 89.5 | 88,5 | 92.6 | None |
| 3b (Nut Plate) | 93.5 | 99.3 | 105.2 | None |
| la (Bolt) | 1427 | 1227 | 1050 | RTV-11 |
| 1b (Nat Plate) | 520 | 514 | 490 | RTV-11 |
| 18 (B olt) | 438 | 425 | 420 | G-683 |
| 1b (Nut Plate) | 341 | 345 | 375 | G683 |
| 2a (Bolt) | 889 | 795 | 669 | R TV-11 |
| 2b (Nut Plate) | 1892 | 1466 | 800 | R TV-11 |

9 inch joint, 3 bolts, 24 inch-pounds worque, Configuration 2

| Joint No. | | | | Filler |
|----------------|-----------|------------|------------|--------|
| | 7.5 Watts | 22.5 Watts | 37.5 Watte | |
| la (Bolt) | 93.5 | 95.2 | 94.1 | None |
| lb (Nut Plate) | 34.1 | 67.8 | 97.6 | None |

TABLE 6 STRUCTURAL JOINT CONDUCTANCE, BTU HR FT² °F

| | 6 inch joint, 2 bo | olts, 24 inch-pounds | torque, Configurati | on 3 |
|-------|--------------------|----------------------|---------------------|----------------|
| Joint | No. | | | Filler |
| | 5 Watts | 15 Watts | 25 Watts | |
| 1 | 147.0 | 144.2 | 142.0 | None |
| 2 | 194.0 | 180.0 | 174.0 | None |
| 3 | 112.2 | 108.5 | 106.5 | None |
| 1 | 1110 | 1273 | 1242 | RTV-11 |
| 1 | 1328 | 1262 | 1231 | G~-6 83 |
| | | | | |

9 inch joint, 3 bolts, 24 inch-pounds torque, Configuration 3 Joint No. Filler

| | 7.5 Watts | 22.5 Watts | 27.5 Watts | |
|---|-----------|------------|------------|------|
| 1 | 142.2 | 139.0 | 135.5 | None |

present investigation, the real joints had two dimensional heat flows. It was not possible to project gradient measurements to the interface. Furthermore, the heat fluxes used were selected as representative of those to be encountered in an actual spacecraft, and the temperature gradients were correspondingly small.

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Two values of joint conductance are given in Table 4 and 5 (Configurations 1 and 2) for each test joint. The experimental system was instrumented to obtain the conductance from either plate to the angle. The effective conductance from plate to plate is determined (by analogy to an electrical circuit) as:

^heff =
$$\frac{1}{\frac{1}{h_1} + \frac{1}{h_2}}$$

If this effective conductance is computed for "identical" joints and conditions, the variations between the measurements are reduced significantly for the unfilled joints. In the case of Configuration 1, the variations in total conductance are less than plus or minus 15 percent; for Configuration 2, it is less than plus or minus 7.5 percent. The filled joints have a much wider variation as is indicated by the measurements.

Two lengths of joint were tested for all three configurations. No significant differences in the measured conductances were observed. Hence, the end losses from the test joint are considered to have been negligible.

The third configuration tested was the one to be used for connecting the internal mounting plate to the frame. The measured results were similar to those obtained for the other two configurations.

The test results obtained indicate a filled structural joint to be more variable than an unfilled one. The conductance is significantly higher, of course. This variability may be nullified by the higher value obtained. As discussed in Section 3.1, this can only be assessed by performing an analysis of an actual spacecraft system using these opposing conditions. The choice will depend upon the relative importance of the two modes of heat transfer, rediation and conduction, for the joint analysed and the particular system used. However, if filled joints are used, a formerly conduction dominated system may become rediation controlled. For example, the tot 1 effective conductance of an unfilled joint is of the order of 40 to 50 Btu/hr ft² oF where as an RTV-11 filled joint has a conductance of over 500 Btu/hr ft² oF.

4. DEVELOPMENT OF ANALYTICAL METHODS FOR THERMAL PERFORMANCE ANALYSIS

The transient energy equation which must be solved for each surface in space vehicle thermal analysis is:

$$C_{i} = \frac{dT_{i}}{d\theta} = (q_{r})_{i} + (q_{r})_{i} + (q_{c})_{i}$$
 4-2

where q = net heat transfer from an external source or by internal dissipation

- q_ = net heat transfer by radiation
- q = net heat transfer by conduction

The quantity q_{j} is generally a function of tire. This is a result of orbital conditions and/or of mission imposed duty cycles. Solutions of Equation 4-1 are required for each surface of the spacecraft (internal and external) as a function of time in orbit.

For computer solution, the technique of finite differences is used. Equation 4-1 is written

$$T_{i}(\theta + \Delta \theta) = T_{i}(\theta) = \begin{bmatrix} \Delta \theta \\ C_{i} \end{bmatrix} \left\{ \begin{bmatrix} q_{x}(\theta) \\ \end{bmatrix} + \begin{bmatrix} q_{c}(\theta) \end{bmatrix} + \begin{bmatrix} q_{r}(\theta) \end{bmatrix} \right\}$$

Thus, the temperature of surface i at time $0 + \Delta 0$ is expressed in terms of the temperature and net energy transfers at time 0. The variation of q_x with time is assumed to be known or imposed by external constraints upon the spacecraft. However, both conduction and radiation contain the temperature variable. The expression for q_x is

$$(q_c)_i = \sum_{k=1}^{M} \frac{T_k - T_i}{R_{ki}}$$
 4-3

The expression for q_r can be given by either the network method or by Hottel's "sc-ipt F." The equations which must be solved to obtain $(q_r)_4$ by the two methods is given in Section 4.1. They are

Hottel: $(q_{r})_{i} = \sum_{k=1}^{n} A_{i} S_{ik} \sigma(T_{k}^{4} - T_{i}^{4})$

4-4

The simple equivalence of Hottel (1) and Geblart (2) methods (see Section 4.1) is such that for all practical purposes, they may be assumed to be identical.

Network:

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$$\mathbf{i} = \mathbf{A}_{\mathbf{i}} \begin{pmatrix} \varepsilon_{\mathbf{i}} \\ \rho_{\mathbf{i}} \end{pmatrix} \begin{pmatrix} \sigma T_{\mathbf{i}}^{4} - J_{\mathbf{i}} \end{pmatrix} \qquad (4-5)$$

$$J_{i} = \epsilon_{i} \sigma T_{i}^{4} + \rho_{i} \sum_{k=1}^{K} F_{ik} J_{k}$$
 4-6

or

$$(\mathbf{q}_{r})_{i} = \mathbf{A}_{i} \varepsilon_{i} \sigma T_{i}^{4} - \mathbf{A}_{i} \varepsilon_{i} \sum_{k=1}^{r} \mathbf{F}_{ik} J_{k}$$
 4-7

The difference between the two methods for radiation calculations becomes apparent by examining the above equations. At each time interval, the natwork method requires a new solution of the radiation problem; the "script F" technique requires the radiation problem to be solved once to determine the values of \tilde{J}_{ik} . The determination of \tilde{U}_{ik} does not next to be repeated unless the properties are changed. It should be noted that if the problem is not transient and no conduction is involved, neither method has any computational advantage over the other.

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The procedure for obtaining the "script F" values for a given enclosure can be that described by Hottel (1) or from the network method (6). In both methods of securing π_{ij} , one matrix inversion is required; if the two matrices are compared (see References 1 and 6), they differ only by the use of the areas of the surfaces in the diagonal of Hottel's matrix; i.e., no computational or accuracy advantage.

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The inversion process and the time interval increments used in Equation 4-2 provides a quantitative means for determining the "cost" of solving Equation 4-2 by the radiosity method. A matrix of the coefficients of the various J's must be inverted once at the start of the entire problem and can be used again with the values of temperature obtained at substance times. Hottel's method for calculating "script F" requires a similar matrix inversion. In each case, after the matrix inversion, secondary calculations are required to determine the various J_{\perp} or the new radiosities. However, with "script F," this does not have to be repeated at each time interval. Hence, for N time intervals and M surface enclosure, the number of calculations using radiosities is:

NN² + the matrix inversion

The reciprocity relationship $A_{i} \overline{j}_{j} = A_{j} \overline{j}_{ji}$ can be used in conjunction with the method given by Reference 6 to obtain \overline{J}_{ji} in a time corresponding to that given for the network method of:

1/2 (M)(M+1) + the matrix inversion

Consequently, the "script F" mothod is significantly more economical than the network method.

The steady state case is also more readily solved by the "script F" method when radiation and conduction are both present. Equation 4-1 for the steady state case can be written with the aid of Equation 4-3 as:



4-8

where prepresents the convergence factor; i.e., $\eta \Rightarrow 0$ with convergence. Equation 4-8 must be solved for all surfaces i, e.g., by iteration. If, for each iteration, a new solution for the values of $(\gamma_{i})_{i}$ is required, the number of calculations required is identical to the time interval problem. If however, $(q_{r})_{i}$ is represented by Equation 4-4, the iteration process is independent of recalculation of the radiation problem.

This discussion of the relative merits of the network method and the "script F" method is not based upon the assumptions inherent in either procedure. Another technique based on less restrictive assumptions will be described in Section 4.2. It can be used in either a network or a "script F" form, and the same arguments will hold relative to the method of solution to be used.

The accuracy of any method can be separated into two parts. The first is that inherent in the assumptions; e.g., specular versus diffuse properties. The second part is the accuracy of computation. The assumptions of the analysis is the dominant factor in determining the degree to which a method approximates a real system.

4.1 <u>COMPARISON OF THE ANALYTICAL METHODS OF HOTTEL (1). GEBMART (2)</u>, AND OPPENHEIM (3) FOR CALCULATION OF FADIATION HEAT TRANSFER

The calculation of radiation heat transfer is generally based upon several simplifying assumptions:

- (1) The thermal radiation properties of all surfaces involved in the heat transfer are diffuse (independent of angle), grey (independent of wavelength), not dependent upon temperature, and surfaces are opaque.
- (2) An "enclosure" can be constructed which contains and/or bounds all of the surfaces involved in the radiation exchange such that all radiation emitted and/or reflected from any one surface is reflected and/or _bsorbed by the other surfaces.
- (3) Any single surface used in the calculations is isothermal and uniformly irradiated; this may necessitate the subdivision of a large natural surface into several parts in order to approach this condition.
- (4) No effects occur as a result of polarization, diffraction or fluorescence.
Three different methods of viewing the solution of this radiation exchange problem are available. These are generally known as the "script F" method (Hottel), Gebhart's method, and the network (Oppenheim). Intuitively, these methods must be identical since they are based upon the same physical assumptions and the conservation of energy. However, it is important that this equivalence be demonstrated. Sparrow (7) has recently shown this by developing the methods of Hottel and Gebhart from the network method. Since the "script F" method has been advocated as a more useful approach in complex transient radiation exchange, the "script F" method will be used here as the method of comparison.

Hottel's method is based upon the superposition of the radiant exchange within an enclosure. To do this, he assumed all of the surfaces except one within the enclosure to be at zero temperature; the remaining surface has an emission rate of unity, i.e., $\sigma T_i^4 = 1$. He then considers the quantity R_i , the power per unit area leaving surface j as a result of the power emitted by surface i; for surface i, the radiation leaving is $\epsilon_i + R_i$. The exchange between surfaces i and j are expressed as

$$Q_{ij} = A_i \overline{i}_{j\sigma} (T_i^4 - T_j^4)$$

where the reciprocity relation has been used, i.e., $A_{i}\overline{v}_{ij} = A_{i}\overline{v}_{ji}$. The quantity R_{ij} is related to \overline{v}_{ij} by:

$$A_{j} \tilde{v}_{jj} = i^{R_{j}} j^{A_{j}} \begin{pmatrix} \tilde{c}_{j} \\ \rho_{j} \end{pmatrix}$$

Thus, the incident power per unit area $({}_{i}R_{i}/\rho_{i})$ is absorbed in the fraction ε_{i} . This absorbed power is a result of an emission from surface i of unity and must be increased by the factor σT_{i} . Correspondingly, the absorbed power of surface i from emission by surface j must be increased by σT_{i}^{4} . The "script F" is, therefore, a quantity which collects the interreflections within the enclosure and provides a measure of the radiant interchange between two surfaces by direct and reflected (from all surfaces) exchange.

The irradiation of surface j by surface i $({}_{i}R_{j}/\rho_{j})$ can be expressed for an M surface enclosure $(\sigma T_{i}^{+} = 1)$ as:



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Multiplying through by $\varepsilon_j A_j / A_j$ gives

$$\frac{A_{j}\varepsilon_{j}i^{R}_{j}}{A_{i}\rho_{j}} = \frac{A_{j}F_{ji}\varepsilon_{i}\varepsilon_{j}}{A_{i}} + \sum_{k=1}^{M} \frac{\varepsilon_{j}A_{j}F_{jk}i^{R}_{jk}}{A_{i}} \left(\frac{\rho_{k}}{\rho_{k}}\right) \left(\frac{\varepsilon_{k}}{\varepsilon_{k}}\right)$$

$$4-12$$

With Equation 4-10 and noting $A_iF_{ij} = A_jF_{ji}$, this gives M

$$\mathbf{\tilde{s}}_{ij} = \varepsilon_{i}\varepsilon_{j}F_{ij} + \sum_{k=1}(\varepsilon_{j}F_{kj}) \frac{\rho_{k}}{\varepsilon_{k}} \frac{A_{k}}{A_{i}} \frac{\varepsilon_{k}}{\rho_{k}} i^{R}_{k}$$

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$$\mathbf{\tilde{s}}_{ij} = \varepsilon_i \varepsilon_j F_{ij} + \sum_{k=1}^{n} \varepsilon_j F_{kj} \frac{\rho_k}{\varepsilon_k} \mathbf{\tilde{s}}_{ik}$$
 4-13

Equation 4-13 will be developed by the network method in order to indicate the equivalence of the two techniques.

The Gebhart method is a variation of the "script F" phrased in different language. Gebhart utilized a quantity B_{ij} to represent the effects of interreflections within the enclosure. B_{ij} is the fraction of radiation emitted by surface i which is absorbed by surface j. The heat loss of a surface was expressed by Gebhart 4s:

$$q_{j} = \varepsilon_{j}A_{j}\sigma T_{j}^{4} - \sum_{i=1}^{n} B_{ij}\varepsilon_{i}A_{i}\sigma T_{i}^{4}$$
 4-14a

or

$$q_{j} = \varepsilon_{j} A_{j} \sigma^{T}_{j}^{4} - \sum_{i=1}^{M} q_{ij}$$
 4-14b

The corresponding expression for Hottel's method is:

$$q_{j} = \sum_{i \neq j}^{M} A_{j} \overline{v}_{ji} \sigma T_{j}^{4} - \sum_{i \neq j}^{M} A_{i} \overline{v}_{ij} \sigma T_{i}^{4}$$
 4-15

The first term of Equation 4-15 simplifies by noting the total radiation leaving surface j is $\varepsilon_j \sigma T_j^4$, i.e., $T_i = 0$

$$\sum_{i \neq j}^{M} \sigma T_{j}^{4} \tilde{\sigma}_{ji} = \varepsilon_{j} \sigma T_{j}^{4} - \tilde{\sigma}_{jj} \sigma T_{j}^{4}$$

$$\sum_{i=1}^{M} \bar{s}_{ji} = \epsilon_{j}$$
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Equations 4-14 and 4-15 must represent the same net heat loss by surface j. Equating these two relations gives:

$$\sum_{i=1}^{M} A_{i} \mathfrak{d}_{ij} \sigma T_{i}^{4} = \sum_{i=1}^{M} B_{ij} \varepsilon_{i} A_{i} \sigma T_{i}^{4}$$

This can only be true if:

or

 $v_{ij} = c_i B_{ij}$ 4-17

Consequently, Gebhart's B_{ij} is equal to Hottel's π_{ij} divided by ε_i .

The equations representing the network method of solution utilize the radiosity * of a surface. The radiosity of a surface can be expressed as:

$$J_{i} = \varepsilon_{i}\sigma T_{i}^{4} + \sum_{k=1}^{M} \rho_{i}F_{ik}J_{k}$$

$$4-18$$

The net heat flux leaving a surface is:

$$q_{i} = A_{i} \frac{\varepsilon_{i}}{\rho_{i}} \left(\sigma T_{i}^{4} - J_{i} \right)$$

$$4-19$$

This can also be written as (since $\varepsilon_i + \rho_i = 1$):

$$q_{i} = A_{i}J_{i} - A_{i}\sum_{k=1}^{M}F_{ik}J_{k}$$
 4-20

Now consider the case of an enclosure with all surfaces at zero temperature except surface i which has $\sigma T_i^4 = 1$.

$$J_{j} = \rho_{j} \sum_{k=1}^{n} F_{jk} J_{k}$$
4-21

$$q_{j} = q_{ij} = A_{j}J_{j} - A_{j} \sum_{k=1}^{M} F_{jk}J_{k}$$
 4-22

or

$$q_{ij} = A_{j}J_{j}(1 - \frac{1}{\rho_{j}}) = - \left(\frac{\varepsilon_{j}}{\rho_{j}}\right) A_{j}J_{j} \qquad 4-23$$

*Radiosity is the sum of the emitted and reflected radiant power from a surface. 26

But by Equation 4-9 for the assumed constraints on surface temperatures

$$q_{ij} = -A_i \overline{a}_{ij} = -A_j \overline{a}_{ji}$$

Hence

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$$\mathbf{v}_{ji} = \left(\frac{\varepsilon_j}{\rho_j}\right) J_j \qquad 4-24$$

Substitution of Equation 4-24 into Equation 4-20 yields

$$\mathbf{\tilde{v}}_{ij} = \varepsilon_i \varepsilon_j \mathbf{F}_{ij} + \sum_{k=1}^{N} \varepsilon_j \mathbf{F}_{kj} \left(\frac{\rho_k}{\varepsilon_k}\right) \mathbf{\tilde{v}}_{ik}$$
 4-25

This is identical to Equation 4-13.

SUMMARY

The method of Gebhart has been shown to be directly convertible to the "script F" of Hottel by the use of Equation 4-17. Similarly the network method has been shown to yield an expression for $\overline{v}_{i,j}$ identical to that obtained from Hottel's method (Equation 4-13 and 4-25). Therefore, there is no difference in the methods and by algebraic manipulation, one method can be expressed in the terms of either of the other two.

4.2 IMPROVED METHOD OF RADIATION ANALYSIS

The available methods for radiation heat transfer analysis have been restricted by the assumptions given in Section 4.1 Recently, a review of the problem has been made and a procedure is now available for eliminating the restriction to nondirectional diffuse properties (4). The use of nongrey thermal radiation properties can be used in the manner described by Bevans and Dunkle (8). Perfectly specular properties can be treated by the method of Eckert and Sparrow (9) but the properties must be considered to be nondirectional. The case of polarization can also be treated (10) but the practicality is limited to a few cases. The most practical new technique is believed to be that given by the second approximation described in Reference 4. The following discussion will describe the adaptation of this method to development of a "script F."

The second approximation of Reference 4 considers surfaces which have directionality and components of reflection which are diffuse and specular. The expression for the heat transfer to a surface within an enclosure under the assumptions of wavelength independent properties is:

This later restriction can be easily removed but is not pertinent to the ensuing discussion.

$$q_{k} = A_{k} \overline{e}_{k} \sigma T_{k}^{4} - \sum_{j=1}^{M} A_{k} \alpha_{kj} \overline{f}_{kj} \varepsilon_{jk} \sigma T_{j}^{4}$$

$$- \sum_{j=1}^{M} \sum_{i=1}^{M} A_{k} \alpha_{kj} \rho_{ijk} \varepsilon_{ij} \overline{f}_{kj} \overline{f}_{ji} \sigma T_{i}^{4}$$

$$- \pi \sum_{j=1}^{M} \sum_{i=1}^{M} A_{k} \alpha_{kj} \rho_{ijk} \rho_{ij} \overline{f}_{kj} \overline{f}_{ji} D_{i}$$

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This can be written as:

$$q_{k} = A_{k} \tilde{\epsilon}_{k} \sigma T_{k}^{4} - \sum_{i=1}^{M} \sum_{j=1}^{M} A_{k} a_{ki} (\epsilon_{ik} F_{ki} + \rho_{ijk} \epsilon_{ij} F_{kj} F_{ji}) \sigma T_{i}^{4}$$
 4-27
$$- \pi \sum_{i=1}^{M} \sum_{j=1}^{M} A_{k} a_{kj} \rho_{ijk} \rho_{ij} F_{kj}^{F}_{ji} D_{i}$$

In matrix notation this becomes:

where

$$a_{xy} = - (A_{x}^{\alpha} xy^{\varepsilon} yx^{F} xy + \sum_{g=1}^{M} A_{x}^{\alpha} xy^{\rho} yzx^{\varepsilon} yz^{F} xz^{F} zy^{\rho})$$

$$b_{xy} = - \sum_{g=1}^{M} A_{x}^{\alpha} xz^{\rho} yzx^{F} xz^{F} zy^{\rho} xz$$

The quantity D_k is given by:

$$D_{k} = \frac{1}{\pi} \sum_{j=1}^{M} \varepsilon_{jk} \sigma_{j}^{4} F_{kj} + \frac{1}{\pi} \sum_{j=1}^{M} \sum_{i=1}^{P} \rho_{ijk} \varepsilon_{ij} F_{kj}^{F}_{ji}^{T}_{i}^{4}$$
$$+ \sum_{j=1}^{M} \sum_{i=1}^{M} \rho_{ijk} \rho_{ij} F_{kj}^{F}_{ji}^{D}_{i}$$
4-31

In matrix notation, these equations can be written:

where

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$$d_{xy} = \frac{1}{\pi} e_{yx} e_{xy} e_{xz} e_{xz} e_{xz} (x \neq y)$$

$$d_{xy} = \frac{1}{\pi} e_{yx} e_{xy} e_{xz} e_{x$$

If Equation 4-32 is now solved for the quantities D, we have

[n] = [d] [c] {ot⁺} 4-35^{*}

The notation [] has been introduced to denote a square matrix, e.g., the d or c mailing of Equation 4-32; the [] denotes a column matrix such as the D or σT^{-} matrix of Equation 4-32; and []⁻¹ is the inverse of the indicated matrix

Solution of Equation 4-35 yields the various D_k 's required in Equation 4-28. Equation 4-28 can then be expressed as:

$$\{q\} = \{\varepsilon_{\sigma}T^{4}\} + [a] \{\sigma T^{4}\} + [b] \{D\}$$
 4-36

A directional diffuse-specular "script F" can be obtained with Equations 4-35 and 4-36. Using Hottel's concept of a "script F," i.e., set all temperatures except one within the enclosure equal to zero and the remaining one equal to unity (say surface k), the heat flows (q) are then $q_{k,i}$. With this condition:

$$\{q_{kj}\} = \{ \hat{e}_{k} \} + \{ a_{jk} \} + [b] \{ D_{jk} \}$$

$$4-37^{*}$$

and

$$\left\{ D_{kj} \right\} = \left[d \right]^{-1} \left\{ c_{jk} \right\}$$
 4-38⁴

The solution then proceeds as follows:

- An index k is selected and the pertinent coefficients c_{kj} selected.
- (2) D_{ik} is computed for all j by Equation 4-38.
- (3) The values of a_{jk} are selected and the values of q_{kj} for all j are computed with Equation 4-37.
- (b) $\mathbf{n}_{\mathbf{k},\mathbf{i}}$ is then computed with the definition:

$$\overline{\vartheta}_{jk} = \frac{\Theta_{k,j}}{\Lambda_j}$$
4-39

- (5) The next value of k is selected, and the calculation continues until all M surfaces have been computed. The reciprocity relationship $A_j \bar{u}_{jk} = A_k \bar{u}_{kj}$ is used to reduce the number of computations.
- (6) N is used in the same manner as with Hottel's method and the jk solution of Equation 4-2 or 4-8.



The equations presented in this section may appear to be more complicated and hence, more difficult than with the diffuse property assumption. Mathematically, this is not the case. The computations are more time consuming and require added computer time and storage space. This is only the penalty paid for more exact computations.

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5. COMPUTER PROGRAM FOR DIRECTIONAL SPECULAR-DIFFUSE METHOD

The procedural steps required to calculate a "script F" (8) from the equations for the directional specular-diffuse analysis have been described in Section 4.2 This method has been programmed for an IBM 7094 as a program separate from any general program for thermal analysis. The technical basis for selecting the 3 procedure rather than the network approach have been discussed in the first portion of Section 4. For the reasons given there, most computer programs for thermal analysis have been written in terms of 0. Thus, the existing analysis programs could incorporate a directional specular-diffuse 8 as an input quantity with a minimum of alteration. Furthermore, the direction specular-diffuse 3 requires a much larger working computer storage than a diffuse 0. If an attempt was made to assemble a single 3 and analysis program, the number of surfaces would have been seriously limited. It is for these technical and practical reasons that the 3 calculation was programmed as a separate entity. The flow chart of the program is shown in Figure 8 and a complete printout in Appendix III. The symbols used are those of Section 4.2.

5.1 REQUIRED INFUT DATA

The physical factors which are required for the directional speculardiffuse 8 are:

- (a) the areas of the surfaces involved $(A_i, i = 1, 2, 3...)$
- (b) the number of surfaces used to subdivide the enclosure $(N; N \leq 20)$
- (c) the directional reflectance of surface i in the direction of surface j (ρ_{ij} of Reference 4; designated RHØ in machine language)
- (d) the geometrical bidirectional reflectance of surface j for radiation from surface i which is reflected to surface k by surface j (ρ_{ijk} of Reference 4; designated R_{ijk} in machine language)
- (e) the geometrical diffuse shape factors between surfaces (r_{11})

The only quantities which are not used in conventional diffuse 5 analysis are ρ_{ij} (RH9) and ρ_{ijk} (R_{ijk}). The use of the usual diffuse shape factors (F_{ij}) is made possible by assigning the deviations from diffusences to the reflectances. This is described in greater detail in Reference 4 and leads to the concept of geometrical reflectances, i.e., a property which is weighted by the geometry and n mdiffusences of the surface. The directional emittance of a surface is incorporated in the progrem as: $1 - \rho_{ij}$. This introduces the gray radiation assumption, i.e., propertive independent of wavelength. If desired, either a band energy or monochromatic analysis could be performed (see Reference 4).



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Figure 8. Computer Program Flow Chart





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Figure 8. Computer Program Flow Chart (Cont.)

Values of ρ_{ij} and ρ_{ijk} (RH¢ and R_{ijk}) an be approximated with data obtained in many Thermophysics Laboratories (4). The methods suggested for this approximation will be illustrated in Section 5.3 and 6.2

5.2 INPUT PROCEDURE

The input format is shown in Figure 9. The quantities indicated are as follows:

- N = the number of surfaces within the enclosure to be examined. The present program is storage limited to a maximum of 20 surfaces.
- CLR = a flag directing the program to clear itself of input information (CLR = 1), prior to proceeding to the next case, or instructing the program to retain input information (CLR = 0) for the following case. When CLR is set to zero, only those quantities that vary from case to case need be entered, all other information will be retained.
- L = a flag used in the column labeled "PRE" of the load sheet. The quantity L is used in conjunction with CLR = 0. An input matrix is not cleared of information if the quantity L is inserted in the column labeled "PRE."
- M = a flag used in the column labeled "PRE" of the load sheet. It instructs the program to clear the input matrix of information prior to storing data.
- $\rho_{ij} = RH\emptyset = the directional reflectivity of surface i in the direction$ $of surface j. For program convenience, <math>\rho_{il}$ is set equal to the negative value of the hemispherical reflectance for a diffuse surface.
- $F_{ij} = F =$ the shape factor of surface j as viewed by surface i. Only the lower triangular half of the shape factor matrix need be entered; that is: F_{11} , F_{21} , F_{22} , F_{31} , F_{32} , F_{33} , \cdots F_{mn} .
- R_ijk = Geometrical bidirectional reflectance of surface j for incident energy from surface i and reflected to surface k. Bidirectional reflectivities are inputed in block form as indicated by the sample load sheet. The block number corresponds to the third subscript k, and the other two subscripts are contained within the k'th block. Only the upper triangular portion of the three dimensional R_{ijk} matrix need be entered. That is, R_{1j1} for j = 1 to n is entered for the first matrix, K = 1; R_{1j2} R_{2j2}, for j = 1 to n is entered for the second matrix, K = 2; R_{1j3}, R_{2j3}, R_{3j3} for j = 1 to n is entered for the third matrix, K = 3; and so on until the full matrix is entered for K = n. A_j = A = surface area of node i.

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An unlimited number of cases may be "stacked"; all that is required to run several cases together is an END card between cases. Output quantities 3 and 3-area products, are printed out in matrix form.

Ine following is a very simple problem which illustrates the input loading. Consider two infinite diffuse strips of unit width and separation, as shown below:



Input information:

(a) $\rho_{12} = \rho_{13} = \rho_{21} = \rho_{23} = 0.9$ $\rho_{31} = \rho_{32} = \rho_{33} = 0$ (b) $F_{12} = F_{21} = F_{33} = 0.414214$ $F_{13} = F_{23} = 0.585786$ (c) $R_{213} = R_{312} = R_{313} = R_{212} = \rho_1 = 0.9$ $R_{123} = R_{321} = R_{323} = R_{121} = \rho_2 = 0.9$ (d) $A_1 = A_2 = 1.0, A_3 = 2.0$

The load sheet for the above problem with diffuse surfaces can be found in Figure 10. The result of this computation is 0.0933965, which can be compared to the value given by Reference 9 of 0.09340.

It should be noted that in addition to comparing very favorably with the **S** matrix evaluated by hand, using Hottel's techniques, the following holds

$$\mathbf{\bar{e}}_{\mathbf{k}} = \sum_{j=1}^{M} \mathbf{\bar{u}}_{\mathbf{k}j} = \text{hemispherical emittance}$$

as it should.

"It should be noted that all quantities should be left justified within their respective fields.

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Figure 10. Load Sheet for Two Parallel Infinite Diffuse Strips of Unit Width and Separation

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5.3 EXAMPLES OF INPUT FOR DIFFUSE, SPECULAR, AND SPECULAR-DIFFUSE

The following problem has been selected to illustrate the input required for the three cases of diffuse, specular and directional specular-diffuse. The 3 computer program given here can treat these cases by manipulation of the quantity R_{jjk} (ρ_{ijk}). As discussed in Reference 4, this factor is approximated by:

 $\rho_{ijk} = (\rho_D)_j + (\rho_S)_j \qquad \left\{ \frac{F_{ik(j)}}{F_{kj} F_{ji}} \right\} \qquad 5-1$

If the perfectly diffuse assumption is to be made, the specular reflectance of surface j (ρ_s) is set equal to zero; if the perfectly specular assumption is made, the diffuse reflectance (ρ_D) is set equal to zero. The configuration to be used to illustrate the input is shown below:



Surface 1: $\rho_1 = 0.973$ (vacuum deposited aluminum) Surface 2: $\rho_2 = \rho_3 = 0.116$ (3M black paint) and 3: Surface 4: $\rho_4 = 0$ (surrounding space) $F_{12} = F_{21} = F_{31} = F_{32} = F_{41} = F_{43} = 0.2$ $F_{44} = 0.4$ $A_1 = A_2 = A_3 = 1$ $A_4 = 3$

The diffuse assumption input sheet is shown in Figure 11.

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The specular assumption utilizes the same data as above, but the reflection is assumed to be perfectly specular. For this condition,

$$R_{213} = \rho_{12} \left\{ \frac{F_{23(1)}}{F_{21}F_{13}} \right\}$$

= 2.0897

The quantity R_{L12} is obtained by noting for R_{ijk}

$$\rho_{jk} = \sum_{i=1}^{n} R_{ijk} F_{ji}$$

5-2

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i.e., conservation of energy. Thus,

$$R_{412} = \frac{\rho_{12} - R_{312}F_{13}}{F_{14}} = 0.9323$$

Use is made of reciprocity to find $R_{312} = R_{213}$, $R_{214} = R_{412}$, and $R_{412} = R_{413}$. The load sheet for this problem is shown in Figure 12.

The directional specular-diffuse procedure requires a knowledge of the directional properties of the surfaces. The greatest angle subtended by surface 3 as viewed from surface 2 is less than 55 degrees. For the black surface, the directional reflectance and hence directional emittance is very nearly equal to the near normal value. Therefore, the near normal value was used for ρ_{23} and ρ_{32} . To obtain ρ_{21} , a heat balance was used, i.e., for the general case of surface i

$$(\rho_{\rm H})_{i} = \frac{1}{A_{j}} \sum_{j=1}^{n} \rho_{ij} A_{i}^{F}_{ij}$$
 5-3

where

 $(\rho_{\mu})_{i}$ = hemispherical reflectance of surface i.

The value of ρ_{21} was obtained from:

$$P_{21} = \frac{(\rho_{\rm H})_2 - F_{23}\rho_{23}}{4 F_{21}}$$

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Figure 12. Load Sheet for Sample Problem; Specular Assumption

Reciprocity was utilized to obtain $\rho_{21} = \rho_{12}$, $\rho_{31} = \rho_{13}$, etc. Using the procedure described for ρ_{21} , the values of the other geometrical reflectances were:

$$\rho_{12} = \rho_{13} = 0.9716$$

$$\rho_{14} = 0.9744$$

$$\rho_{23} = \rho_{32} = 0.07$$

The load sheet for this problem is shown in Figure 13. The computer results for the above configuration will be found in Section 6.

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Figure 13. Load Sheet for Sample Problem; Directional Specular-Poffuse Assumption

6. EXPERIMENTAL COMPARISON OF SFECULAR, DIFFUSE AND DIRECTIONAL SPECULAR-DIFFUSE ANALYSES

The purpose of this task was to obtain an experimental evaluation of the different analytical methods. Such a comparison must utilize an experimental system that is simple conceptually and physically. Otherwise the effects of geometry, conduction, convections, extraneous heat losses, etc., will not be controlled. The experimental configurations chosen are shown in Figure 14. A test consisted of placing the experiment within a crid wall vacuum chamber (to eliminate convection), insulating the non-radiative surfaces, supplying a known quantity of power to one of the surfaces and measuring the equilibrium temperatures of the other surface(s). The experimental results were then compared to the predicted values using the directional specular-diffuse analysis (4), the specular property assumption and the diffuse property assumption.

The following discussion will be divided into three parts: (1) the experimental test method, (2) the analytical results, and (3) a discussion of the comparison of experiment and sualysis.

6.1 EXPERIMENTAL METHOD AND PROCEDURE

The configuration selected for test are shown in Figure 14. The test surfaces were six such squares of 1100 aluminum 0.0625 inc. thick. In each case the lower surface was selected as the heat source and the remaining surface(s) allowed to reach an equilibrium condition with the environment. The heated surface had a heater of approximately 200 ohms cemented to its underside (the non-radiative side). This heater consisted of 40 gage constantan wire sandwiched between two sheets of 1 mil Mylar. Voltage leads were attached at the heater boundary and the four terminal resistance method used (see Section 3.1) to calculate power dissipation. The electrical measuring circuit was the same as shown in Figure 6 of Section 3 with a Leeds and Northrup 8686 substituted for the Type K 3.

Originally, the back of each surface was insulated with 20 layers of super insulation. However, the edge heat leak was found to be too large relative to the heat absorbed by the unheated surfaces. A guard heat system was found to be necessary. This was obtained by placing a heated plate on the outside of the insulation and adjusting the dissipation until the temperature difference across the insulation was zero, i.e., no heat flow through the insulation. The edges of the insulation, guard heater, and test surface were covered with 1/4 mil thick aluminized Mylar, aluminum side out. These steps reduced the edge and back heat "leak," i.e., uncontrolled loss, to approximately 1 Btu/hr for a test surface temperature of 70°F. This was satisfactory for all test surfaces except the surface coated with vacuum deposited aluminum. The radiative heat loss or gain from such a surface was the same order of magnitude as the edge loss. Hence, this test surface had to be used as a passive surface, i.e., a reflector, and no heat balance could be performed for it.





Figure 15. Test Configuration in Test Fixture





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Each test surface was supported within a framework by dacron cords attached to phenolic stand-off attachments. In this manner the test surfaces were isolated from the framework but properly positioned and restrained (see Figure 15). This framework was mounted within a LN_2 cooled baffled and the assembly placed within a vacuum system. A pressure of 10⁻⁵ torr or lower was obtained during the testing. The system is illustrated in Figure 16.

Thermocouples were placed on at least two points of each test surface; one at the center of the surface and one within one-half inch of the edge. No significant gradient across the test surface was observed in any of the tests; i.e., the surfaces were essentially isothermal. The thermocouple material was copper-constantan. All thermocouples were taken from the same roll. The voltages generated by the thermocouples were measured with a Leeds and Northrup Type 8686 potentiometer using a conventional ice junction compensation system.

The test procedure consisted of the following steps:

- (1) setting the predicted power dissipation for the source surface
- (2) setting estimated guard heat dissipation(s) for the receiving surface(s)
- (3) observing the temperature of the receiver surface(s) and adjusting the guard power dissipation(s)
- (4) when the receiver surface(s) and guard heater(s) indicated a negligible temperature difference for thirty minutes, at least two sets of data were recorded within the next thirty minutes.

The latter step insured that the surfaces were in equilibrium for approximately one hour. The accuracy of the measurements are estimated to be:

| Temperature d | ifference | <u>+</u> | 0.1°F |
|------------------------------|------------|----------|-------------|
| Temperature Total power d | lissipated | bv | 1°F 1.5% |
| the heat sour | .09 | -, | |

A complete summary of the experimental data is given in Appendix III.

6.2 ANALYTTUAL PREDICTION

The radiative heat flow from the source surface and the temperature of the receiver surface were predicted by the analytical methods based upon the three different property assumptions: diffuse (1,2,3), specular (7), and the directional specular-diffuse (4). The prediction served to test the utility and practicality of the computer program developed for this study (Section 5) as well as provide a basis of comparison between theory and experiment.

The test configurations have been described in Section 6.1 and illustrated in Figure 14. These three configurations were combined with different surface coatings to give six different test systems. These systems are schematically represented in Figure 17. The directional

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Test

Surface Coatings

| | Source | Receiver | Reflector | Configuration |
|----|--------------------------|--|--|---------------|
| 1. | "3M" Flat Black Paint | "3M" Flat Black Paint | | (a) |
| 2. | "3M" Flat Black Paint | "3M" Flat Black Paint | | (b) |
| 3. | "3M" Flat Black Paint | "3M" Flat Black Paint | Vacuum Deposited Aluminum | (c) |
| 4. | "3M" Flat Black Paint | "3M" Flat Black Paint | Rinshed-Mason Leafing Aluminum Paint | (c) |
| 5. | "3M" Flat Biack Paint | Rinshed-Mason Leafing Aluminum Paint | Vacuum Deposited Aluminum | (c) |
| 6. | "3M" Flat Black Paint | Rinshed-Mason Leafing Aluminum Paint | Anodized Aluminum | n (c) |

NOTE: The coating material descriptions are described in detail in Figures 18 through 21.

Figure 17. Experimental Matrix for Test of Radiation Analysis

reflectances of these coatings for a black body source at 540°R are shown in Figures 18 through 22. Included in these figures is the specular reflectance for the same radiation source. The specular reflectances were measured with a goniometric reflectometer shown in Figure 22. The directional reflectances were measured with a heated cavity reflectometer similar to that described in Reference 11.

The method of determining the various quantities and establishing the input for the computer program has been described in Section 5.3. The results of the computer calculations are shown in Table 7.

6.3 COMPARISON OF EXPERIMENTAL AND ANALYTICAL RESULTS

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An examination of the results presented in Table 7 will quickly show one consistent fact: In every case, the experimentally measured temperature exceeded the value predicted by any of the analytical methods. A hasty conclusion would be that the experiments were in error in some manner. After re-examining the experimental technique for major errors, nothing sufficiently significant could be found. Conversely, many questions can be raised relative to the analytical predictions. The following discussion will be concerned with the errors of prediction. However, the possibility of an unrealized source of error in the experiments is not ruled out.

The difficulties with the predictions are believed to be centered about the thermal rediation properties used. The analyses are based upon the gray radiation assumption, i.e., wavelength independent properties. The source surface was operated at approximately 585°R whereas the receiver surfaces ranged between 340 and 425°R, i.e., a difference of 170 to 245°F. All properties used in the analysis assumed a meterial and source temperature of 585°R for emittance and reflectance. This "non-gray" error would be particularly noticeable with anodized aluminum and aluminum paint surfaces. To correct for this, the analyses would have to be performed on at least the band energy basis (4).

A second error was in the measurement of the properties. The heated cavity reflectometer is known to have an error due to sample heating (11). This error could le of the order of .02-.04 in directional reflectance (or emittance) and would affect the predicted temperatures slightly. It would have a more direct effect upon the predicted heat less by the source surface. In only one case (Test 5), was the measured heat less lower than predicted. In this instance, it was within experimental accuracy for the nearest prediction. The predicted temperatures and heat fluxes are too interrelated to separate them except as a first approximation. Thus, no firm conclusion can be drawn from this one case. However, the problem of sample emission is not considered to have been a major source of the discrepancies as ju'ged from the spectral data.

Folarisation of the energy with the menochromator of the heated cavity can also cause an error. For very highly reflective materials, e.g., vacuum deposited aluminum, or smooth dielectrics, polarization may cause an error as large as 10 to 20 percent in the reflectance at high angles.



Figure 18. Directional Reflectance of 3M Flat black Paint to a 540 K Black Body as a Function of Angle

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Figure 19. Directional Reflectance of Vacuum Deposited Aluminum to a 540°R Elack Body as a Function of Angle

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Figure 21. Directional Reflectance of Rinshed-Mason Leafing Aluminum Paint to a 540 R Black Body as a Function of Angle

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| | | Q _g Source Heat Quantity Bou/nr | T _R Receiver Temperature [°] R |
|----------------------------|---------------------------------------|---|---|
| Configuration [*] | | . · · · | |
| 1 | Experimental Directional Specular- | 29.83 | 345.2 |
| | Diffuse Analysis | 29.41 | 340.4 |
| • | Specular Assumption | 29.17 | 342.2 |
| | Diffuse Assumption | 29.17 | 342.2 |
| 2 | Experimental Directional Specular | 42.50 | 393 . ð |
| | Diffuse Analysis | 42.06 | 38 6 |
| | Specular-Assumption | 41.2 | 386.4 |
| | Diffuse Assumption | 41.2 | 386.4 |
| 3 | Experimental Directional Specular- | 41.29 | 428.2 |
| | Diffuse Analysis | 40.68 | 419.4 |
| | Specular-Assumption | 40.93 | ,12.0 |
| | Diffuse Assumption | 39.69 | 393.8 |
| 4 | Experimental Directional Specular- | 40.7 | 423.5 |
| | Diffuse Analysis | 40.33 | 415.5 |
| | Specular-Assumption | 40.25 | 408.8 |
| | Diffuse Assumption | 40.54 | 397.4 |
| 5 | Experimental Directional Specular- | 39.93 | 409.7 |
| | Diffuse Analysis | 40.0 | 391.6 |
| | Specular-Assumption | 40.3 | 402.5 |
| | Diffuse Assumption | 40.2 | 383.8 |
| 6 | Experimental Directional Specular- | 40.05 | 398.7 |
| | Diffuse Analysis | 39.21 | 382.3 |
| | Specular-Assumption | 39.56 | 391.1 |
| | Diffuse Assumption | 40.19 | 387.9 |

TABLE 7 SUMMARY OF RADIATION EXCHANGE ANALYSES AND EXFERIMENT

* See Figures 14 and 17.

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M1, M5 SPHERICAL MIRRORS 300 mm f.1. M2, M3, M4 FLAT MIRRORS

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This source of error has also been recently recognized and the information required to assess this error is not yet available for the monochromator used. In the case of the tests described, only the 3M flat black paint will be free of this error.

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A fourth source of error was the approximations used to obtain the geometrical reflectances; i.e., the interaction between spatial variation of reflectance and the shape factor integral. The methods used to approximate these properties have been described in Section 5.3. Until a spatial distribution of the reflectance property of a number of surfaces have been obtained and incorporated in the integration of a shape factor, the magnitude of this error will not be known. Simple analysis of an extreme case has shown this to be as large as 30 percent (4).

Considering all of these factors together, plus the probable experimental error, leads to the conclusion that the predicted temperatures should be re-examined. This would require the analyses to be performed on a band energy basis and with a more detailed evaluation of the properties.

The analytical results given in Table 7 also offer an opportunity to compare the different methods of analysis. The program described in Section 5 is based upon the method given in Reference 4. The technique is an admitted approximation to the integral squations describing the radiation exchange within an enclosure. The other two methods are also approximations in that an assumption is made relative to the radiation properties, i.e., nondirectional perfectly specular or perfectly diffuse. The approach programed to this study resulted in a set of equations which were very similar to those Otained in the diffuse approximation and could be solved with a slight increase in time. In contrast, an enclosure with perfectly specular surfaces can require extensive preliminary calculation to obtain the "specular interreflections."

The test configurations of Figure 17 are examples of very simple enclosures which are easily solved by any one of the three methods. They do not represent a complex enclosure and cannot adequately demonstrate the differences between the specular, diffuse and directional speculardiffuse methods. A trend can be inforred, however. For example, Test Configurations 1 and 2 should yield identical results for the specular and diffuse assumptions. The directional specular-diffuse analysis yields different results because the emission from source occurs at large angles from the normal. The predicted temperature of the receiver is higher for Test 1 and Lower for Test 2 because of the angular effects of absorption. For Test 3, the specular analysis is suitable but does not account for the directional properties. The diffuse analysis does not account for specular reflection and radiation is "diffusely" reflected back to the source. The directional specular-diffuse result is between these two. Similar arguments hold for Test Configurations 4, 5, and 6. These geometries are more complicated by the use of the aluminum paint and anodized aluminum which have directional and/or specular components of reflection. In more complicated enclosures, such a simple explanation of possible differences is not practical. The only comment that can be made is that the directional specular-diffuse analysis is a more realistic approximation to physical fact.
7. CORRELATION OF COMPONENT JOINT EXPERIMENTAL RESULTS

At the request of the Technical Monitor, C. J. Feldmanis, an effort was made to correlate the experimentally measured values of joint conduction. This work was a substitute for the completion of the preliminary design task originally scheduled for the last portion of the program. This correlation effort has resulted in a simplified approach based on the conduction flow pattern to a circular cavity (region of the bolts) in the mating parts. For the thin plates in the component mounting joints, the conduction at the bolts was very high and the apparent contact area small. This led to the conclusion that macroscopic effects were of the greatest significance.

A review of the technical literature revealed little information that would be useful in predicting interface conductance for the bolted joints of this study. A subsequent study of the pressure distribution indicated that the apparent contact area occupies only to a small region near the bolts. This suggested that the predominant thermal resistance lies in the mating plates themselves. This correlation effort has resulted in a simplified expression for the interface conductance based on the heat flow pattern in a large circular region to a circular sink at the center. These comments apply specifically to the mounting plate configuration investigated in this study.

7.1 REVIEW OF LITERATURE

A review of technical literature reveals that the study of vacuum thermal contact resistance is of recent vintage. Fast emphasis has been upon joints in a conducting fluid; e.g., air. This is not surprising since the need for information on the behavior of heat flow through connecting elements in a vacuum was not great until the advent of satellites. An excellent review of technical literature is contained in Reference 12 and a bibliography on contact conductance is contained in Reference 13; Appendix V list references that are not reported in Reference 13.

As background to the correlation to be presented, two well known methods that have been proposed will be cited. The applicability (or lack of it) to the type of joints considered in the present study will be indicated.

Fench and Rohsenow (14) developed an expression for the thermal conductance of a mathematical model with contacting surfaces idealized as cylindrical contacts equily spaced in a triangular array. The thermal conductance was expressed in terms of the thermal conductivity of the metals and of the fluids of filling the voids, the real area in contact, the number of contact points per unit area, and the volume average thickness of the void gaps. A method of obtaining these physical properties of a contact is contained in Reference 15. The need for the profiles of the contacting surfaces precluded the axamination of this method.

While most investigators were concerned with microscopic areas of contacts (those due to surface finish), Clausing and Chao (12) concluded that macroscopic resistances (that due to large scale waviness or nonflatness) was predominant over the microscopic resistance for a majority of engineering surfaces. The interface conductance was expressed in terms of the mean thermal conductivity of the two contacting materials, the radius of the macroscopic constriction ratio, the contact pressure, the macroscopic constriction ratio, the harmonic mean of the moduli of the two-contacting materials, and the total equivalent flatness deviation. This method requires the measurement of flatness deviation and surface finish; the latter is readily obtained, but the former is more difficult to measure. This method was not applied since subsequent studies showed that the apparent contact area (the region adjacent to the bolts) represents only a small percent of the total joint area. However, the concept of constrictive heat flow is employed in the present study, except that it is applied in a much larger, gross scale. The method is discussed below.

The two methods discussed above considered a physical system without a disruptive element such as a bolt. Intuitively, the influence of fasteners should be great. An attempt at correlating joint conductance data is reported in Reference 16, and the resultant expression is semiempirical. The method employed in the present study is semi-analytical and the close correlation with experimental results strongly suggests that the governing resistance is centered in the plate itself; at least for the type of joints considered here. The analytical method is discussed below.

7.2 ANALYTICAL DEVELOPMENT

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The correlation of joint conductance data was limited to the component joint configurations. An anlytical model was postulated based on the work done by previous workers, experimental data and engineering judgement. The basic concept of the proposed method is that the controlling thermal resistance is the plate. It is postulated that the points of contact which contribute to the conductance are in the small region under and around the bolts. The problem is then to describe the heat flow in the plate to the bolt area. Two mathematical models were employed for this purpose.

7.2.1 ANALYTICAL MODEL I

The first model is shown in Figure 23(a). It is a disc with uniform heat flux over its surface and conduction to a central area at a constant temperature. The outside surface (r = R) is assumed to be insulated. This model is used to describe heat flow in a joint with only a few bolts in relation to the total area.



For an incremental volume at radius r, a heat balance yields,



$$Q 2\pi r dr = -2\pi k tr \frac{dT}{dr} + 2\pi k tr \frac{dT}{dr} r$$

$$7-1$$

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$$Q = -\frac{kt}{r} \frac{d}{dr} \left(r \frac{dT}{dr} \right)$$
 7-2

with boundary conditions:

at
$$r = R$$
, $\frac{dT}{dr} = 0$ (insulated) and
at $r = R_0$, $T = T_0$
Hence, $T_0 - T = \frac{Q}{Rt} = \frac{1}{4} (r^2 - R_0^2) + \frac{1}{2} R^2 \ln \frac{R_0}{r}$
7-2

Now let
$$\frac{r}{R} = \eta$$
, $\frac{R_0}{R} = \eta_0$
 $\therefore T_0 - T = \frac{QR^2}{kt} \frac{1}{4} (\eta^2 - \eta_0^2) + \frac{1}{2} \ln \frac{\eta_0}{T_1} = \Lambda T$
7-4

The conductance of one plate is:

$$h = \frac{Q\pi R^2}{R} \qquad 7-5$$

$$\int_{R_o} (T-T_o) 2\pi r dr$$

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7-6

Substituting ΔT from Equation 7-4 and changing the limits of integration gives:

$$h = \frac{QnR^2}{1} \int_{\eta_o} \frac{QR^2}{kt} \left[\frac{1}{\hbar} (\eta_o^2 - \eta^2) + \frac{1}{2} \ln \frac{\eta}{\eta_o} \right]^{2\gamma \eta_d \eta}$$

Integrating and substituting the limits yields

$$h = \frac{2\kappa t}{R^2} \left[\frac{1}{\eta_0^2 - \eta_0^4 / 4 - \ln \eta_0 - 3/4} \right]$$
 7-7

The bracketed term of Equation 7-7 is plotted in Figure 24 and the conductance versus radius for several effective contact radius values is shown in Figure 25.

7.2.2 ANALYTICAL MODEL II

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The model which can be applied to a system having contact around the periphery is shown in Figure 23(b). The equation for this system is:

$$Q = -\frac{kt}{r} \frac{d}{dr} \left(r \frac{dt}{dr}\right)$$
 7-8

The boundary conditions are:

$$r = 0$$
, T is finite
 $r = R_0$, $T = T_0$

Solution of Equation 7-8 yields,

 $T - T_{o} = \frac{Q}{4kt} \begin{bmatrix} R_{o}^{2} - r^{2} \end{bmatrix}$ 7-9

The conductance of one plate is:

$$h = \frac{QmR^2_o}{R_o}$$
 7-10
$$\int (T-T_o) 2mrdr$$

Substituting &T from Equation 7-9 and integrating gives:

 $h = \frac{3kt}{R_0^2}$ 7-11

This equation is plotted in Figure 26.





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Figure 25. The Thermal Conductance of a Single Contact Junctio as a Function of Contact Radius (R₀) for an Aluminu Plate 1/16th Inch Thick



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7.2.3 CONTACT REGION AROUND A BOLT

The contact area and conductance of a bolt is based on the deformation of the plates under bolt head. The method used to determine this quantity is that presented in reference (17). The analysis given by this reference assumes a uniform loading over the bolt area. The resultant stress distribution is shown in Figure 27 and can be expressed as (Equation 56, Reference 17):

 $\frac{\sigma_2}{\sigma_p} = 1 - \left(\frac{r}{c}\right)$

7-12

The quantity c is dependent upon the bolt diameter, a, and the plate thickness, $\frac{b}{2}$. For a 1/16-inch plate in contact with a 1/8-inch plate, the effective contact radius, c, is given by Reference 17 as 1.35a.

The pressure under the bolt must be computed for use in the above expression. The tensile load in a bolt torqued to a preset value is determined from the approximate relation given in Reference 18.

$$T = 0.20 \text{ Fd}.$$

7--13

where

T = bolt torque, 24 in.-lb.
F = tensile load, lb.
d = major thread dia. = .190 in.

or

 $F = 630 \, lb$.

This value is conservative for the present application; that is, it yields a lower conductance than values given by other references. Aron and Colombo (16), for example, use a value of 800 lb. for 22 in.-lb. torgue in the same size bolt.

The bolt (NAS 563) has a measured bearing diameter of 0.344 inches and the mut (NAS 671) has a measured bearing diameter of 0.312 inches. The area under the nut was used to obtain the pressure, assuming uniform loading ($\sigma_{\rm p} = F$)

 $P = \frac{7}{A} = \frac{630 \text{ lb.}}{.0468 \text{ in}^2} = 13,450 \text{ lb/in}^2$ 7-14

This result was used with Equation 7-12 to obtain the pressure distribution and conductance at the bolt. The solution of Equation 7-12 for σ_z , using the results of Equation 7-12, are plotted in Figure 28. The pressure distribution was used by dividing the area into annular zones and evaluating each zone to estimate its conductance. The numerical values were obtained from the conductance versus pressure plot given in



Figure 27. Stress Distribution in a Bolted Plate for Uniform Bolt Pressure





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Figure 6-3 of Reference 19, labeled "Best line through most of the Aluminum (II) Data-Vacuum." The results of this calculation yield

a conductance through the bolt of 21,000 $\operatorname{Ptu/hr}$ ft² °F. This can be compared to the value of 10,000 Btu/hr ft² °F calculated in Reference 19 for a No. 10 bolt tightened to 22 in.-lb₂ torque. The area under the bolt in Reference 19 is given as 0.33 inches² (a washer was used in Reference 19). The contact area under the bolt in the present study was 0.12 in.². Thus, the thermal resistance of the two bolts can be compared:

Present Study:

$$R = \frac{1}{hA} = .0575 \frac{o_{F hr}}{BTU}$$

Reference (3)

$$R = \frac{1}{hA} = .044 \frac{OF hr}{BTU}$$

7.3 APPLICATION TO TEST CONFIGURATIONS

Three component test configurations were run with fewer than the normal 12 bolts to evaluate bolt spacing effectiveness. These tests were in addition to those reported in Section 3.1. These configurations are shown in Figure 29 (a, b, and c). The sample size was 6 inches by 6 inches, the upper plate thickness was 1/16 inch, and the mounting plate was 1/8 inch thick. The bolt torque was 24 in. 1b. for all cases.

Configuration 29-a was divided into four equal areas for purposes of analytical correlation. Each triangular section was assumed to be deformed into a sanicircular shape of the same area and having a contact region at the center. The radius of the segment is then 2.38 in., and the bolt contact area, now semicircular, has an effective radius of 0.311 in. These dimensions were substituted in the equations described in Section 7.2.1. Ine resulting conductance of the upper plate was found to be: $h_1 = 18.3$ Btu/h 10^{20} F.

The conductance of the lower plate will be computed using the same analytical procedure. Since the heat removal from the lower plate is not as uniform as heat supplied to the upper plate, the analytical model is now a poorer approximation of the real system. The results were used as an approximation since an analytical solution of the real heat flow in this plate would be a lengthy task. Applying this method to the lower plate, which has a thickness twice that of the upper plate, results in

 $h_2 = 36.6$ Btu/hr ft^{2 o}F. These two plate thermal conductances must be combined with the bolt thermal conductance. The thermal circuit for this system is:



Figure 30. Thormal Circuit for Calculating Overall II. srmal Conductance

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The overall conductance is given by:

$$\frac{1}{hA} = \frac{1}{h_1A_1} + \frac{1}{h_BB_B} + \frac{1}{h_2A_2}$$

Substituting the values gives:

 $\frac{1}{hA} = .874 + .057 + .437$

$$\frac{1}{hA} = \frac{1}{18.3} \frac{1}{\left(\frac{9}{144}\right)} + \frac{1}{21,000} \frac{1}{\left(\frac{12}{144}\right)} + \frac{1}{36.6} \frac{1}{\left(\frac{9}{144}\right)}$$

or

C

h =
$$\frac{1}{1.368(\frac{9}{1Lh})}$$
 = 11.7 Btu/hr ft² °F

Applying this technique to Configuration 29-b, the corner bolts were close together and were lumped together to form a quarter circular area having an effective radius of 0.622 inches. The analytical method of Section 7.2.1 and thermal circuit substitutions yield an overall conductance of h = 8.0 Btu/hr ft² ^oF.

Configuration 29-c was divided by allotting to each corner bolt a hemicircular area of 4 in.² and each center bolt a quarter circle of 5 in.². Using the same technique as above, the thermal circuit gave:

$$h = 22.0 Btu/hr ft2 °F.$$

The twelve-bolt configuration was analyzed in the same manner by dividing this area into eight equal area segments as shown in Figure 29-d. The result was:

$$h = 26.7 Btu/hr ft2 °F.$$

The 6 inch by 12 inch component configuration can be approached using the same technique by dividing the area into eight hemici. Jular sectors and four quarter circular sectors each with an effective area of 6 inch. Similarly the 12 by 12 configuration was divided into twelve hemicircles and four quarter circles of equal area, 9 inch². The results for these six configurations are shown in Table 8.

The 6 inch by 6 inch, 12 bolt and 12 inch by 12 inch, 24 bolt configurations can also be predicted using the method described in Section 7.2.2. An effective radius based on the plate area was used in Equation 7-11. The results are also given in Table 8. The results of these correlation attempts are compared to the measured values in Table 8. The agreement is adequate in all cases except 29-b where the predicted value is a little more than half of the measured conductance. In spite of this, the success of the technique is quite satisfactory. Further exploitation should be made of the approach described here. The results have been restricted to a bolted thim plate without a filler material. EXPERIMENTAL SYSTEMS AND ANALYTICAL APPROXIMATIONS







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| COMPARISON | OF FREDICIED AND M | CASURED COMPONENT SOLNT | CONDUCIANCES |
|-------------------------|--|---|--|
| Configuration | Experimental h, BTU/hr ft ² °F | Method I (Sec. 7.2.1) h, BTJ/hr ft ² ^o F | Method II (Sec. 7.2.2) h, BTU/hr ft ² oF |
| 29 -a | 13.4 | 11.7 | |
| 29-b | 13.7 | 8.0 | |
| 29-c | 22.0 | 22.0 | |
| 29-d 6 x 6, 12 bolts | 26.3 | 26.7 | 29 |
| 6 x 12, 18 bolts | 18.5 | 18.1 | |
| 12 x 12, 24 bolts | 8.3 | 10.5 | 7.8 |

TABLE 8 COMPARTSON OF FREDICITED AND MEASURED COMPONENT JOINT CONDUCTANCES

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An attempt should be made to extend this to thick plates with and without a filler and to thin plates with a filler.

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8. CONCLUSIONS AND RECOMMENDATIONS

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This report presents the results of the first phase of a program designed to improve the prediction of spacecraft thermal performance. The information necessary for the comparison of prediction and test of a spacecraft model has been gathered. The continuation of the program to this natural conclusion is the second phase of the study. There has been no decrease in the practical needs for this continuation and it is important to complete this program.

There have been several developments within this program which warrant further study. The first is the extension of the joint conductance testing to include a larger number of joint types. The techniques which have been developed in this program for experimentally measuring the conductance of practical joints have proven to be very simple and inexpensive. The accuracy which is obtained is adequate for such joints and is a satisfactory compromise with the cost of such experimentation. The joints for this additional work should not be chosen on the basis of a thermal test model but selected for the frequency with which they are used in actual practice, e.g., riveted joints, low conductance joints, etc.

The practical correlation of joint conductances should also be continued. The correlation for the thin plate unfilled component joints was obtained by assuming the primary resistance to heat flow was in the thin plates. This primary resistance was found to be adequately described by radial in the region surrounding each bolt fastener. The success with which the component joints were correlated by this procedure was very encouraging. The limitations of time and resources did not allow a similar attempt to be made to correlate filled joints or structural joints. However, such a correlation is believed to be feasible. This work could be included in the second phase of the program; correlation of other test joints would be performed as part of the experimental work described above or as a separate study. Regardless of the mechanism chosen for performing this correlation, this work should be continued and extended.

The application of the directional specular-diffuse method of analysis has indicated a major gap in our knowledge of thermal radiation properties. A critical part of this method is the separation of the thermal radiation proparties into the diffuse and specular components. Additional experimental and analytical work is required to develop a basis for this separation from measurements of the directional and specular reflectances. Such a study should include an examination of the geometrical reflectances (and emittances) relative to the distribution of reflected (and emitted) radiation.

Although the comparisons of predicted and experimental radiation exchange in the simple geometries were close, further refinement of the predictions are desired. This problem is related in part to the separation of the diffuse and specular components discussed above. The effect of non-gray radiation properties is probably of equal or greater importance. Further study is needed for the improvement of the predicted temperatures and heat fluxes, e.g., a prediction using the band energy method. In conclusion, the objectives of the first phase of the program have been satisfied; i.e., the data and methods required to compare the predicted and test thermal performance of a model spacecraft have been developed. Other areas for further study have also been found:

- (1) practical joint conductance measurements
- (2) correlation of measured joint conductances
- (3) the separation of radiation properties into diffuse and specular components for the directional specular-diffuse analysis
- (.) the importance of the non-gray property assumption

The development of additional problems is to be expected in a study of this nature. The second phase of the program should be expected to raise its own share of new problems.

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APPENDICES

I. Experimental Data—Component Joints II. Structural Joint Tests

- III. Structural Joint Tests
 III. Script F Computer Program Print Out
 IV. Experimental Data—Radiation Exchange Experiment
 V. Bibliography for Joint Thermal Conductance
 VI. Component Joint Test Data used for Correlation Task

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APPENDIX I

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EXPERIMENTAL DATA-COMPONENT JOINTS

The experimental data for the 6 x 6 component joint is listed in Table 9 of this appendix. The thermocouple locations are shown on the full size drawing of Figure 31. In addition to these thermocouples, thermocouples were placed in the cooling water inlet and outlet lines. These are absolute thermocouples No. 3 and 4 respectively. The approximate cooling water flow rate was also recorded, but varied as the water pressure fluctuated. The heater voltage and current are also recorded.

Figure 31 also illustrates the zones which were vsed in computing the area weighted temperature difference. A sample calculation for run 20. 1 is as follows:

$$\overline{\Delta T}_{(1)} = \frac{1.02 + 1.04 + 0.80 + 0.77}{4} = 0.91 \text{ F}$$

$$\overline{\Delta T}_{(2)} = 1.98 \text{ }^{\circ}\text{F}$$

$$\overline{\Delta T}_{(3)} = \frac{2.50 + 4.11 + 2.57}{3} = 3.06 \text{ }^{\circ}\text{F}$$

$$\overline{\Delta T}_{(4)} = \frac{6.29 + 6.53}{2} = 6.41 \text{ }^{\circ}\text{F}$$

These average ΔT 's are for each zone, obtained by averaging the differential thermoccuple readings in each zone. The overall ΔT is now computed by area weighting these values.

$$\Delta T_{M} = \Delta T_{0} \frac{A_{0}}{A_{T}} + \Delta T_{0} \frac{A_{0}}{A_{T}} + \Delta T_{0} \frac{A_{0}}{A_{T}} + \Delta T_{0} \frac{A_{0}}{A_{T}} + \Delta T_{0} \frac{A_{0}}{A_{T}}$$

$$\Delta T_{M} = \frac{9.05}{56} (0.91) + \frac{7.50}{36} (1.96) + \frac{13.2}{36} (3.06) + \frac{6.25}{36} (6.41)$$

$$\Delta T_{M} = 0.229 + 0.412 + 1.121 + 1.11$$

$$\Delta T_{M} = 2.872^{\circ} F$$

$$Q_{IN} = 3.702 (0.1314) = 4.864 \text{ watts}$$

$$= 16.6 \text{ Btu/hr}$$

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$$h = \frac{Q}{A\Delta T_{1,1}}$$
$$= \frac{16.6 \text{ Btu/hr}}{1/4 \text{ ft}^2 2.872^\circ \text{F}}$$
$$h = 23.1 \text{ Btu/hr} \text{ ft}^2 \text{ o}$$

The experimental data for the 6 inth x 12 inch and 12 inch x 12 inch component joints are given in Tables 10 and 11, respectively, of this appendix. The thermocouple locations and temperature weighting zones are shown in Figures 32 and 33 for these two experimental configurations.

Differential thermocouples are located at the same (x, y) coordinates on the back of the mounting plate and the component plate at the locations shown on Figures 31, 32 and 33.

The conductance is calculated using the following equation:

$$h = \frac{Q}{AAT}$$

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The area used in this calculation is the contact area of the mating parts. For the structural joints, this was the overlap area between the angle bracket and the panel. The ΔT is an area weighted average which is determined by the method explained in above.



6" x 6" COMPONENT THERMOCOUPLE LOCATION

Figure 31. 6" x 6" Component Joint Thermocouple Location

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12" x 12" COMPONENT THE MOCOUPLE LOCATION

Figure 33. 12" x 12" Component Joint Thermocouple Location

| Run No. | 1 | 2 | 3 | 4 | 5 |
|------------------------------|----------------------|--------------------|--------------------|--------------------|--------------------|
| Date | 10/26/64 | 10/26/64 | 10/26/64 | 10/26/64 | 10/27/64 |
| Pressure, Torr | 6 x 10 ⁻⁷ | 6×10^{-7} | 6×10^{-7} | 6×10^{-7} | 5×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 85.7 | 95 . 3 | 107.1 | 119.0 | 85.3 |
| 2 - ⁰ F | 80.2 | 85.6 | 91.6 | 97.8 | 79.8 |
| 3 - ⁰ F | 74.0 | 74.5 | 74. 5 | 74.3 | 73.8 |
| $4 - {}^{\circ}F$ | 74. 1 | 74.8 | 75.0 | 75.0 | 74.0 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 6.5 3 | 11.78 | 18.28 | 24.72 | 6.72 |
| 2 - ⁰ F | 6.29 | 11.38 | 17.60 | 23.78 | 6 . 48 |
| 3 - ⁰ F | 2.50 | 4.56 | 7.25 | 9.85 | 2.52 |
| 4 - ^o F | 4.11 | 7.06 | 10.95 | 14.90 | 4.05 |
| 5 - ⁰ F | 2.57 | 4.64 | 7.25 | 9.81 | 2.63 |
| 6 - ⁰ F | 1.02 | 1.81 | 2.81 | 3.81 | 1.02 |
| 7 - ⁰ F | 1.98 | 3, 52 | 5. 4 6 | 7.40 | 2.00 |
| 8 - ⁰ F | 1.04 | 1.88 | 2.92 | 3.96 | 1.07 |
| 9 - ⁰ F | 0.80 | 1.41 | 2.19 | 2.97 | 0.81 |
| 10 - ^o F | 0.77 | 1.31 | 2.04 | 2.77 | 0.74 |
| Voltage, volts | 37.02 | 49.31 | 61.54 | 72.04 | 36.99 |
| Current, amps | 0.1314 | 0.1750 | 0.2185 | 0.2560 | 0.1313 |
| Water Flow, ml/min | 725 | 650 | 650 | 630 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | 'one | None | None | None | None |
| Sample Number | 1 | 1 | 1 | 1 | 1 |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ² °F | 23.1 | 22.9 | 23.0 | 22.3 | 22.8 |

Table 9. Experimental Data-6 by 6 Inch Component Joints

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Table 9. Experimental Data -- 6 by 6 Inch Component Joints (Continued)

| Run Number | 6 | 7 | 8 | 9 | 10 |
|-------------------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| Date | 10/27/64 | 10/27/64 | 10/27/64 | 10/28/64 | 10/28/64 |
| Pressure, Torr | 5×10^{-7} | 5×10^{-7} | 5×10^{-7} | 6×10^{-7} | 7×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - F | 95.1 | 107.5 | 118.5 | 105.5 | 117.5 |
| 2 - [°] F | 85,2 | 92.3 | 97.3 | 89.9 | 102.3 |
| 3 - [°] F | 74.1 | 74.3 | 73.3 | 73.2 | 74.7 |
| 4 - ⁰ F | 74.5 | 75.0 | 74.1 | 73.6 | 89.1 |
| Differential T.C. | | | | | |
| $1 - {}^{o}F$ | 11.78 | 18.30 | 24.72 | 18.27 | 18.68 |
| 2 - ⁰ F | 11.31 | 17.65 | 23.89 | 17.68 | 17,82 |
| $3 - {}^{\circ}F$ | 4.48 | 7.25 | 9.85 | 7.22 | 7.95 |
| $4 - {}^{O}F$ | 7.03 | 10.95 | 14.88 | 10.90 | 11,32 |
| $5 - {}^{o}\mathbf{F}$ | 4.60 | 7.50 | 9.79 | 7.19 | 7.44 |
| 6 - [°] F | 1.78 | 2.77 | 3.77 | 2.78 | 2,53 |
| 7 - [°] F | 3,50 | 5,45 | 7.37 | 5.50 | 5.04 |
| 8 - ⁰ T | 1.86 | 2.9 2 | 3.96 | 2.94 | 2.87 |
| 9 - [°] F | 1,40 | 2.16 | 2.94 | 2.19 | 2.00 |
| 10 - ⁰ F | 1.30 | 2.00 | 2.71 | 2.02 | 1.82 |
| Voltage, volts | 49. 23 | 61.54 | 72.02 | 61.53 | 61.52 |
| Current, amps | 0.1751 | 0,2185 | 0.2559 | 0.2185 | 0.2185 |
| Water Flow, ml/min | 5 2 5 | 525 | 525 | 1175 | 21 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | None | None |
| Sample Number | 1 | 1 | 1 | 1 | 1 |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| h. Btu/hr ft ^{2 o} F | 23.2 | 22.9 | 23.1 | 23.0 | 22.8 |

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| Table 9. Experim | iental Date - | | | • • • | |
|------------------------------|---------------------|--------------------|----------------------|--------------------|--------------------|
| Run Number | 11 | 12 | 13 | 14 | 15 |
| Date | 10/29/64 | 10/29/64 | 10/29/64 | 10/29/64 | 10/30/64 |
| Pressure, Torr | "x 10 ⁻⁷ | 7×10^{-7} | 7 x 10 ⁻⁷ | 7×10^{-7} | 5×10^{-7} |
| Absolute T.C. | | | | | |
| l - ^o F | 85.0 | 94.2 | 105.7 | 117.8 | 84.8 |
| 2 - ⁰ F | 79.8 | 84.9 | 91.9 | 97.5 | 79. 5 |
| 3 - °F | 73.8 | 73.9 | 73.7 | 73.6 | 73.6 |
| 4 - ⁰ F | 74.0 | 74.3 | 74.3 | 74.4 | 73.6 |
| Differential T.C. | | | | | |
| | 6.22 | 10.90 | 17.20 | 23.37 | 6,27 |
| 2 - ⁰ F | 5.88 | 10.29 | 16.30 | 22.10 | 5.93 |
| 3 - ⁰ F | 2.23 | 4.02 | 6.62 | 9.10 | 2.90 |
| 4 - ⁰ F | 3.88 | 6.74 | 10.52 | 14.31 | 3.90 |
| 5 - ⁰ F | 2.45 | 4.30 | 6.80 | 9.30 | 2. 55 |
| 6 - ⁰ F | 0.62 | 1.10 | 1.73 | 2.32 | 0.68 |
| 7 - ⁰ F | 1.83 | 3.21 | 5.04 | 6.81 | 1.84 |
| 8 - ⁰ F | 0.91 | 1,61 | 2.57 | 3.50 | 0.95 |
| 9 - ^o F | 0.66 | 1.19 | 1.87 | 2.53 | 0.70 |
| 10 - ^o F | 0.74 | 1.31 | 2.04 | 2.73 | 0.79 |
| Voltage, volts | 37.00 | 49.32 | 61.54 | 72.02 | 37.0 |
| Current, amps | 0.1313 | 0.1751 | 0.2185 | 0.2559 | 0.1313 |
| Water Flow, ml/min | 525 | 550 | 550 | 550 | 500 |
| Bolt Torque, in-lb | 30 | 30 | 30 | 30 | 18 |
| Filler | None | None | Nore | None | None |
| Sample Number | 1 | 1 | 1 | 1 | 1 |
| Number of Bolts | 12 | 12 | 2 ! | 12 | 12 |
| h, Btu/hr ft ² °F | 25.0 | 25.2 | 24.8 | 25.0 | 23.9 |

Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

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Table 9. Experimental Data- -6 by 6 Inch Component Joints (Continued)

| Run Number | 16 | 17 | 18 | 1-9 | 20 |
|-------------------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| Date | 10/30/64 | 11/2/64 | 11/2/64 | 11/2/64 | 11/2/64 |
| Fressure, Torr | 5×10^{-7} | 6×10^{-7} | 6×10^{-7} | 6×10^{-7} | 6×10^{-7} |
| Absolute T.C. | | | | | |
| $1 - {}^{o}F$ | 94.1 | 81.5 | 88.4 | 96.1 | 104.5 |
| 2 - ⁰ F | 84.8 | 78.9 | 84.0 | 88.9 | 94.7 |
| 3 - ⁰ F | 73.7 | 73.2 | 73.6 | 73.4 | `D.891 |
| 4 - [°] F | 74.1 | 73.4 | 73.9 | 73.9 | |
| Differential T.C. | | | | | |
| $1 - c_{\mathbf{F}}$ | 10.99 | 2.20 | 3.76 | 5.76 | 7.83 |
| 2 - ⁰ F | 10.34 | 2.25 | 3.87 | 5.94 | 8.05 |
| 3 - ⁰ F | 4.10 | 0.50 | 0.83 | 1.27 | 1.73 |
| 4 - ⁰ F | 6.76 | 1.49 | 2.50 | 3.90 | 5.27 |
| 5 - ⁰ F | 4.46 | 0.43 | 0.72 | 1.11 | 1.52 |
| 6 - ⁰ F | 1.19 | 0.27 | 0.47 | 0.71 | 0.98 |
| 7 - ⁰ F | 3.21 | 0.52 | 0.93 | 1.26 | 1.71 |
| 8 - ⁰ F | 1.67 | 0.15 | 0.25 | 0.38 | 0.53 |
| 9 - ⁰ F | 1.24 | 0.28 | 0.44 | 0.67 | 0.91 |
| 10 - ⁰ F | 1.38 | 0.45 | 0.73 | 1,11 | 1.49 |
| Voltage, volts | 49.30 | 37.00 | 49.34 | 61.50 | 72.04 |
| Current, amps | 0.1750 | 0.1313 | 0.1751 | 0.2183 | 0.2558 |
| Water Flow, ml/min | 525 | 600 | 600 | 600 | 600 |
| Bolt Torque, in-lb | 18 | 24 | 24 | 24 | 24 |
| Filler | None | RTV 11 | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 1 | 1 | 1 | 1 | L |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| b. Btu/hr ft ^{2 c} F | 24.8 | 76.9 | 81.5 | 82.5 | 83.2 |

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| Table 9. Experimental Data—6 by 6 Inch Component Joints (Continued) | | | | | | |
|---|--------------------|--------------------|--------------------|--------------------|--------------------|--|
| Run Number | 21 | 22 | 23 | 24 | 25 | |
| Date | 11/6/64 | 11/6/64 | 11/9/64 | 11/9/64 | 11/9/64 | |
| Pressure, Torr. | 8×10^{-7} | 8×10^{-7} | 9×10^{-7} | 9×10^{-7} | 9×10^{-7} | |
| Absolute T.C. | | | | | | |
| 1 - ⁰ F | 81.4 | 91.0 | 83.7 | 86.8 | 95.5 | |
| 2 - ⁰ F | 76.0 | 80.2 | 74.2 | 77.5 | 80.9 | |
| 3 - ⁰ F | 73.3 | 73.8 | 70.9 | 71.7 | 72.1 | |
| 4 - ^o F | 73.4 | 74.1 | 71.1 | 72.1 | 72.5 | |
| Differential T.C. | | | | | | |
| 1 - ⁰ F | 5.76 | 11.60 | 5.69 | 9.82 | 15.25 | |
| 2 - ⁰ F | 5.11 | 10.29 | 5.06 | 8.71 | 13.56 | |
| 3 - ⁰ F | 2.88 | 5.85 | 2.87 | 4.92 | 7.65 | |
| 4 - ⁰ F | 2.29 | 4.62 | 2.23 | 3.82 | 5.96 | |
| 5 - ⁰ F | 0.65 | 1.32 | 0.45 | 0.76 | 1.18 | |
| 6 - ⁰ F | 1.36 | 2.76 | 1.26 | 2.17 | 3.38 | |
| 7 - ⁶ F | 0.95 | 1.97 | 0.91 | 1,55 | 2.44 | |
| 8 - ⁰ F | 0.48 | 1.02 | 0.44 | 0.74 | 1.17 | |
| 9 - ⁰ F | | | | | | |
| 10 - ⁰ F | | | | | | |
| Voltage, volts | 37.03 | 53.01 | 37.01 | 49.33 | 61.53 | |
| Current, amps | 0.1315 | 0.1883 | 0.1314 | 0.1752 | 0.2186 | |
| Water Flow, ml/min | 1300 | 675 | 575 | 575 | 575 | |
| Bolt Torque, in-lb | 12 | 12 | 24 | 24 | 24 | |
| Filler | None | None | None | None | None | |
| Sample Number | 2 | 2 | 2 | 2 | 2 | |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 | |
| h, Btu/hr ft ² °F | 24.7 | 28.5 | 29.1 | 30.1 | 30, 1 | |

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Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

| Run Number | 26 | 27 | 28 | 29 | 30 |
|-------------------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| Date | 11/9/64 | 11/10/64 | 11/13/64 | 11/17/64 | 11/17/64 |
| Pressure, Torr. | 9×10^{-7} | 1×10^{-6} | 1×10^{-6} | 1×10^{-6} | 1×10^{-6} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 104.7 | 88.2 | 81.2 | 71.6 | 75.7 |
| 2 - [°] F | 84.5 | 77.4 | 75.4 | 69.0 | 70.9 |
| 3 - ⁰ F | 72.1 | 70.8 | 69.9 | 66.0 | 70.9 |
| 4 - ⁰ F | 73.0 | 71.3 | 70.4 | 66.4 | 66.5 |
| Differential T.C. | | | | | |
| $1 - {}^{O}F$ | 20.93 | 11.30 | 3.78 | 1.80 | 3.08 |
| 2 - ⁰ F | 18.57 | 10.09 | 3.38 | 1.61 | 2.76 |
| 3 - [°] F | 10.51 | 5.74 | 1.38 | 0.63 | 1,11 |
| $4 - {}^{\circ}F$ | 8.19 | 4.50 | 0.72 | 0.31 | 0,58 |
| 5 - °F | 1.63 | 0.84 | 0.29 | 0.21 | 0.36 |
| 6 - ⁰ F | 4.62 | 2.54 | 0.20 | 0.091 | 0.20 |
| 7 - ⁰ F | 3.34 | 1.78 | 0.26 | 0.095 | 0.20 |
| 8 - ⁰ F | 1.63 | 0.89 | 0.26 | 0.091 | 0.27 |
| 9 - ⁰ F | | | | | |
| 10 - F | | | | | • |
| Voltage, volts | 72.03 | 53.01 | 53.03 | 37.02 | 49.31 |
| Current, amps | 0.2560 | 0.1883 | 0.1883 | 0.1314 | 0.1751 |
| Water Flow, ml/min | 575 | 575 | 575 | 625 | 600 |
| Bolt Torque, in-lb | 24 | 30 | 12 | 24 | 2: |
| Filler | None | None | RTV II | RTV 11 | RTV 11 |
| Sample Number | 2 | 2 | 2 | 2 | 2 |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 30.1 | 30.0 | 123.0 | 128.1 | 127.0 |

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| Run Number | 31 | 32 | 33 | 34 | 35 |
|------------------------------|--------------------|--------------------|----------------------|--------------------|--------------------|
| Date | 11/17/64 | 11/17/64 | 11/19/64 | 11/20/64 | 11/23/64 |
| Pressure, Torr | 1×10^{-6} | 1×10^{-6} | 7 x 10 ⁻⁷ | 1×10^{-6} | 1×10^{-6} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 81.7 | 87.0 | 78.8 | 80.6 | 72.1 |
| 2 - ⁰ F | 74.2 | 76.5 | 73.4 | 72.5 | 68.2 |
| 3 - [°] F | 66.2 | 66.1 | 67.7 | 66.7 | 65.2 |
| 4 - ⁰ F | 67.0 | 67.0 | 68. ? | 67.1 | 65.4 |
| Differential T.C. | | | | | |
| $1 - {}^{o}\mathbf{F}$ | 4.72 | 6.39 | 3.39 | 7.25 | 3.62 |
| $2 - {}^{o}\mathbf{F}$ | 4.25 | 5.77 | 3.04 | 6.20 | 1.29 |
| 3 - [°] F | 1.73 | 2.35 | 1.12 | 3.12 | 1.57 |
| 4 - ⁰ F | 0.89 | 1,24 | 0.54 | 2.22 | 1.07 |
| 5 - °F | 0.51 | 0.67 | 0.31 | 0.37 | 0.19 |
| 6 - °F | 0 . 30 | 0,41 | 0.17 | 0.93 | 0.45 |
| 7 - [°] F | 0,29 | 0.37 | 0.17 | 0,53 | 0.23 |
| 8 - ⁰ F | 0.44 | 0.65 | 0.30 | 0.42 | 0,15 |
| 9 - °F | | | | | |
| 10 - ⁰ F | | | | | |
| Voltage, volts | 61.51 | 72.05 | 53.01 | 52.99 | 37.09 |
| Current Amps | 0.2185 | 0,2560 | 0.1883 | 0.1879 | 0.1312 |
| Water Flow, inl/min | 600 | 600 | 600 | 690 | 460 |
| Bolt Torque, in-lb | 24 | 24 | 30 | 12 | 24 |
| Filler | KTV 11 | RTV 11 | RTV 11 | G 683 | G 683 |
| Sample Number | , | 2 | 2 | 2 | 2 |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ² °F | 129.0 | 130.0 | 142.0 | 55.5 | 63.0 |

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| Run Number | 36 | 37 | 38 | 30 | 40 |
|------------------------------|--------------------|--------------------|--------------------|--------------------|----------|
| Date | 1/23/64 | 11/23/64 | 11/23/64 | 11/23/64 | 4U |
| Pressure, Torr | 1×10^{-6} | 1×10^{-6} | 1×10^{-6} | 1×10^{-6} | 11/24/64 |
| Absolute T.C. | | | | | 3 X 10 |
| 1 - ⁰ F | 78.3 | 85.7 | 97 4 | 79 0 | |
| 2 - ⁰ F | 71.4 | 74.7 | 77 4 | 7.7.7 71.7 | 88,1 |
| 3 - ^o F | 66.0 | 66.7 | 66 5 | 11.1 65.0 | 73.9 |
| $4 - {}^{\circ}F$ | 66.5 | 67.4 | 67 5 | 65.9 | 66.7 |
| Differential T.C. | | | 0119 | 00,4 | 67.1 |
| 1 - ⁰ F | 6.20 | 9.46 | 12.83 | 7 15 | 12 . 0 |
| 2 - ⁰ F | 2.07 | 3.11 | 4.15 | 6 15 | 13.58 |
| 3 - °F | 2.72 | 4,17 | 5 63 | 2 00 | 13.37 |
| 4 - ⁰ F | 1.86 | Z.88 | 3 89 | 2.77 | 0.59 |
| 5 - °F | 0.33 | 0.52 | 0.67 | 0.22 | 4.72 |
| 6 - [°] F | 0.77 | 1.17 | 1.56 | 0.31 | 1.07 |
| $7 - {}^{\circ}F$ | 0. 42 | 0,66 | 0.87 | 0.72 | 3.35 |
| 8 - °F | 0.34 | 0.56 | 0.07 | 0.34 | 2.22 |
| 9 - °F | | | 0,77 | V. 3 2 | 1.18 |
| 10 - F | | | | | |
| Voltage, volts | 49.31 | 61,53 | 72.04 | 52.96 | 52.96 |
| Current, ampr | 0,1749 | 0.2183 | 0.2556 | 0.1878 | 0 1990 |
| Water Flow, ml/min | 460 | 460 | 460 | 475 | 560 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 30 | 12 |
| Filler | G 683 | G 683 | G 683 | G 683 | None |
| Sample Number | 2 | 2 | 2 | 2 | 3 |
| Number of Bolts | 12 | 12 | 12 | 12 | - 12 |
| h, Btu/hr ft ² °y | 65.0 | 66.1 | 67.1 | 57.0 | 24.8 |

Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

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| Run Number | 41 | 42 | 43 | 44 | 4 5 |
|-------------------------------|--------------------|--------------------|----------------------|--------------------|--------------------|
| Date | 11/24/64 | 11/25/64 | 11/25/64 | 11/25/64 | 11/25/64 |
| Pressure, Torr | 5×10^{-7} | 5×10^{-6} | 5 x 10 ⁻⁶ | 5×10^{-7} | 5×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 92.6 | 88.4 | 92.7 | 77.5 | 85.0 |
| 2 - ⁰ F | 81.8 | 74.9 | 75.0 | 70.7 | 72.9 |
| 3 - ⁰ F | 66.6 | 65.9 | 66.4 | 66.8 | 66.2 |
| 4 - ⁰ F | 67.0 | 66.4 | 66.9 | 67.0 | 66.7 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 17.64 | 14.32 | 18.42 | 6.70 | 11.50 |
| $2 - {}^{\circ}F$ | 17.70 | 13.93 | 18.45 | 6.65 | 11.44 |
| 3 - ⁰ F | 11.94 | 7.36 | 10,19 | 3.17 | 5.45 |
| 4 - ⁰ F | 7.46 | 4.97 | 10.59 | 2.26 | 3.92 |
| 5 - ⁰ F | 1.80 | 1.11 | 9.44 | 4.78 | 0.80 |
| 6 - ⁰ F | 7.80 | 4.26 | 7.95 | 1.57 | 2.67 |
| 7 - ⁰ F | 10.18 | 3.26 | 3.64 | 0.93 | 1.65 |
| 8 - ⁰ F | 10.40 | 2.53 | 1.61 | 0.49 | 0.92 |
| 9 - ⁰ F | | i | | | |
| $10 - {}^{0}F$ | | | | | |
| Voltage, volts | 52.96 | 52.95 | 52.95 | 37.01 | 49.32 |
| Current, amps | 6.1880 | 0.1880 | 0.1880 | 0.1313 | 0.1751 |
| Water Flow, ml/min | 700 | 575 | 550 | 625 | 625 |
| Boli Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | Ncne | None | None | None | None |
| Sample Number | 3 | 3 | 3 | 3 | 3 |
| Number of Bolts | 4 [*] | 8 [*] | 8 [*] | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 13.4 | 22.0 | 13.7 | 22.1 | 25.9 |

Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

*See Appendix VI.

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Table 9. Experimental Data-6 by 5 Inch Component Joints (Continued)

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| Run Number | 46 | 47 | 48 | 49 | 50 |
|-------------------------------|--------------------|----------------------|--------------------|--------------------|--------------------|
| Date | 11/27/6- | 11/27/64 | 11/30/64 | 12/3/64 | 12/3/64 |
| Pressure, Torr | 5×10^{-7} | 5 x 10 ⁻⁷ | 6×10^{-7} | 4×10^{-7} | 4×10^{-7} |
| Absolute T.C. | | | | | |
| $1 - {}^{O}F$ | 94.6 | 105.5 | 81.8 | 73.0 | 79.1 |
| 2 - ⁰ F | 75,7 | 79.6 | 72.7 | 68.8 | 71.5 |
| 3 - ⁰ F | ό5.4 | 65.5 | 66.0 | 65.3 | 65.8 |
| 4 - ⁰ F | 66.0 | 66.4 | 66.5 | 65.6 | 66.3 |
| Differential T.C. | | | | | |
| 1 ~ ⁰ F | 17.67 | 23.95 | 5.63 | 2.63 | 4.54 |
| 2 - ⁰ F | 17.59 | 23.80 | 6.21 | 3.00 | 5.14 |
| $3 - {}^{\circ}F$ | 8.36 | 11,31 | -1.81 | 0.76 | 1.32 |
| 4 - ⁰ F | 6.02 | 8.20 | 0.75 | 0.27 | 0.45 |
| 5 - °F | 1.26 | 1.69 | 0.24 | 0.14 | 0.21 |
| 6 - ⁰ F | 4.14 | 5.60 | 0,24 | 0.13 | 0.20 |
| 7 - ⁰ F | 2.59 | 3. 5 4 | 0,24 | 0.12 | 0.23 |
| 8 - ⁰ F | 1.49 | 2.02 | 0.37 | 0.05 | 0.23 |
| 9 - ⁶ F | | | | | |
| 10 - ⁰ F | | | | | |
| Voltage, volts | 61,52 | 72.06 | 53.01 | 37.00 | 49.34 |
| Current, amps | 0.2134 | 0.2560 | 0.1883 | 0.1313 | 0.1751 |
| Water Flow, ml/min | 600 | 600 | 600 | 550 | 550 |
| Bolt Torque, in-lb | 24 | 24 | 12 | 24 | 24 |
| Filler | None | None | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 3 | 3 | 3 | 3 | 3 |
| Number of Bolts | 12 | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 26.2 | 26.6 | 84.1 | 91.0 | 03.5 |



| Run Number | 51 | 52 | 53 | 54 |
|---------------------------------|--------------------|--------------------|--------------------|----------------------|
| Date | 12/3/64 | 12/3/64 | 12/4/64 | 12/4/64 |
| Pressure, Torr | 4×10^{-7} | 4×10^{-7} | 5×10^{-7} | 2 x 10 ⁻⁶ |
| Absolute T.C. | | | | |
| $1 - {}^{O}F$ | 86.8 | 94.9 | 83.5 | 75.6 |
| 2 - ⁰ F | 74.8 | 78.5 | 72.2 | 70.0 |
| 3 - ⁰ F | 66.2 | 66.2 | 65.6 | 66.7 |
| $4 - {}^{\mathrm{o}}\mathrm{F}$ | 66.9 | 67.1 | 66.0 | ٥7.0 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 6.95 | 9. 14 | 8.95 | 4.52 |
| 2 - ⁰ F | 7.86 | 10.62 | 9.19 | 4.48 |
| 3 - ⁰ F | 2.03 | 2.77 | 3.22 | 1.59 |
| $4 - {}^{o}F$ | 0.70 | 0.96 | 2.25 | 1.09 |
| 5 - ⁰ F | 0.30 | 0.40 | 0.26 | 0.12 |
| 6 - ⁰ F | 0.29 | 0.40 | 0.92 | 0.42 |
| 7 - ⁰ F | 0.37 | 0.52 | 0.70 | 0.28 |
| 8 - ⁰ F | 0.44 | 0.67 | 0.42 | 0.11 |
| 9 - ⁰ F | | | | |
| $10 - {}^{0}F$ | | | | |
| Voltage, volts | 61.54 | 72.05 | 53.01 | 37.05 |
| Current, amps | 0,2184 | 0.2558 | 0.1878 | 0.1312 |
| Wate: Flow, ml/min | 550 | 550 | 650 | 600 |
| Bolt Torque, in-lb | 24 | 24 | 12 | 24 |
| Filler | RTV 11 | RTV 11 | G 683 | G 683 |
| Sample Number | 3 | 3 | 3 | 3 |
| Number of Bolts | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 94.8 | 95 .4 | 47.0 | 47.3 |

Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

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| Pun Number | 55 | 56 | 57 | 59 |
|-------------------------------|----------------------|----------------------|--------------------|--------------------|
| Kun Humber | | 50 | 51 | 20 |
| Date | 12/4/64 | 12/7/64 | 12/7/64 | 12/8/64 |
| Pressure, Torr | 5 x 10 ⁻⁸ | 1 x 10 ^{-ό} | 1×10^{-6} | 5×10^{-7} |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 81.9 | 88.0 | 97.1 | 71.0 |
| 2 - ⁰ F | 72.9 | 72.9 | 76 .4 | 66.3 |
| 3 - ⁰ F | 63.5 | 63. 5 | 63.8 | 63.1 |
| 4 - ⁰ F | 64.3 | 63.4 | 64.7 | 6 3. 5 |
| Differential 1.C. | | | | |
| 1 - ⁰ F | 7.70 | 11.80 | 15.93 | 3.12 |
| 2 - [°] F | 7.74 | 11.88 | 16.05 | 3.25 |
| 3 - ⁰ F | 2.76 | 4.25 | 5.74 | 0.85 |
| $4 - {}^{O}F$ | 1.91 | 2.98 | 4.02 | 0.48 |
| 5 - ⁰ F | 0.22 | 0.36 | 0.48 | 0.15 |
| 6 - [°] F' | 0.74 | 1.09 | 1.48 | 0.18 |
| 7 - ⁰ F | 0.54 | 0.81 | 1.10 | 0.73 |
| 8 - ⁰ F | 0.33 | 0.51 | 0.76 | 0. |
| 9 - ⁰ F | | | | |
| 10 - ⁰ F | | | | |
| Voltage, volts | 49.36 | 61.52 | 72.04 | 37.02 |
| Current, amps | 0.1748 | 0.2180 | 0.2554 | 0.1311 |
| Water Flow, ml/min | 600 | 500 | 500 | 525 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | G 683 | G 683 | G 683 | G 641 |
| Sample Number | 3 | 3 | 3 | 3 |
| Number of Bolts | 12 | 12 | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 48.2 | 48.8 | 49.5 | 77.5 |

Table 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

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| Table 9. Experimer | ntal Data — 6 | by 6 Inch C | component Joi |
|-------------------------------|--------------------|----------------------|--------------------|
| Run Number | 59 | 60 | 61 |
| Date | 12/8/54 | 12/8/64 | 12/8/64 |
| Pressure, Torr | 5×10^{-7} | 5 x 10 ⁻⁷ | 5×10^{-7} |
| Absolute T.C. | | | |
| 1 - ⁰ F | 77.8 | 85.8 | 93.8 |
| 2 - ⁰ F | 69.7 | 73.2 | 76.8 |
| 3 - ⁰ F | 63.9 | 64.5 | 64.8 |
| $4 - {}^{o}F$ | 64.4 | 65.2 | 65.8 |
| Differential T.C. | | | |
| 1 - ⁰ F | 5.36 | 8.20 | 11.10 |
| 2 - ⁰ F | 5,58 | 8.56 | 11.56 |
| 3 - ⁰ F | 1.47 | 2.27 | 3.07 |
| 4 - ⁰ F | 0.85 | 1.34 | 1.81 |
| 5 - °F | 0,22 | 0,32 | 0.40 |
| 6 - ⁰ F | 0.33 | 0.51 | 0.70 |
| 7 - ⁰ F | 0.20 | 0.37 | 0.54 |
| 8 - ⁰ F | 0.10 | 0,45 | 0.69 |
| 9 - ⁰ F | | | |
| 10 - ⁰ F | | | |
| Voltage, volts | 49.35 | 61.52 | 72.02 |
| Current, amps | 0.1748 | 0,2180 | 0.2553 |
| Water Flow, ml/min | 525 | 525 | 5 2 5 |
| Bolt Torque, in-lb | 24 | 24 | 24 |
| Fi er | C 641 | G 641 | G641 |
| Sample Number | 3 | 3 | 3 |
| Number of Bolts | 12 | 12 | 12 |
| h, Btu/hr ft ^{2 o} F | 79.0 | 79.0 | 79.5 |

Cable 9. Experimental Data-6 by 6 Inch Component Joints (Continued)

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| Table 10. | Experimental | Data — 6 | by 1 | 2 Inch | Component | Joints |
|-----------|--------------|----------|------|--------|-----------|---------|
| 14010 10. | | 2414 0 | ~, - | | oomponent | 0011100 |

| Run Number | 62 | 63 | 64 | 65 | 66 |
|-------------------------------|--------------------|--------------------|--------------------|----------------------|--------------------|
| Date | 12/9/64 | 12/9/64 | 12/9/64 | 12/10/64 | 12/10/64 |
| Pressure, Torr | 3×10^{-7} | 3×10^{-7} | 3×10^{-7} | 5 x 10 ⁻⁷ | 5×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 74.4 | 84.9 | 106.0 | 74.9 | 70.0 |
| 2 - ⁰ F | 67.7 | 71.6 | 79.0 | 68.1 | 66.7 |
| 3 - ⁰ F | 63,3 | 63.9 | 63.5 | 64. U | 64.5 |
| $4 - {}^{o}F$ | 64. 3 | 64.8 | 65,2 | 64.6 | 64.9 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 2. 43 | 5.93 | 8.94 | 3.07 | 1.35 |
| 2 - ⁰ F | 1.94 | 3.87 | 7.90 | 1.9 | 0. 98 |
| 3 - [°] F | 5.83 | 11.57 | 23,50 | 5.87 | 2.94 |
| $4 - {}^{\circ}F$ | 5.22 | 10.40 | 22.02 | 5,17 | 2.59 |
| 5 - ⁰ F | 3, 15 | 171 | 29.30 | 7.22 | 3.64 |
| 6 - ⁰ F | 2. 49 | 4.95 | 10,20 | 2. 47 | 1.24 |
| 7 - [°] F' | 0.73 | 1, 43 | 2.85 | J. 75 | 0.39 |
| 8 - ⁰ F | 1.33 | 2.61 | 5.37 | 1.31 | 0.66 |
| 9 - [°] F | 0.50 | 1.00 | 2.09 | 0.51 | 0.25 |
| Voltage, volts | 35.48 | 50.00 | 70, 70 | 35, 47 | 25 00 |
| Currents, amps | 0.2837 | 0. 4000 | 0.5667 | 0.2840 | 0. 2001 |
| Water Flow, ml/min | 575 | 600 | 600 | 550 | 550 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | None | None |
| Sample Number | 1 | 1 | 1 | 1 | 1 |
| Number of Bolts | 18 | 18 | 18 | 18 | 18 |
| h, Btu/hr ft ^{2 o} F | 22.7 | 19.5 | 18.5 | 18, 5 | 18.5 |

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|------------------------------|----------------------|--------------------|--------------------|--------------------|--------------------|
| Run Number | 67 | 6 8 | 69 | 70 | 71 |
| Date | 12/10/64 | 12/14/64 | 12/14/64 | 12/14/64 | 12/17/64 |
| Pressure, Torr. | 5 x 10 ⁻⁷ | 4×10^{-7} | 4×10^{-7} | 4×10^{-7} | 6×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 86.5 | 70.4 | 76.0 | 88.3 | 68.6 |
| 2 - ⁰ F | 73.3 | 67.9 | 70.8 | 77.6 | 65.2 |
| 3 - ⁰ F | 65.2 | 64.6 | 65.0 | 66.5 | 62.0 |
| 4 - ⁰ F | 66.Z | 65,1 | 65.9 | 67.7 | 62.6 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 4.72 | 0.32 | 0.66 | 1.68 | 0.64 |
| 2 - ⁰ F | 3.86 | 0.22 | 0.44 | 0.95 | 0.28 |
| 3 - ⁰ F | 11.60 | 1,25 | 2.52 | 5.26 | 1.27 |
| $4 - {}^{O}F$ | 10.37 | 1.06 | 2.09 | 4.24 | 1.05 |
| 5 - °F | 14.36 | 1,55 | 3.06 | 6.15 | 1.42 |
| 6 - [°] F | 4.95 | 0,22 | 0.48 | 1.02 | 0.15 |
| 7 - [°] F | 1.46 | 0.19 | 0.37 | 0.80 | 0.08 |
| 8 - ⁰ F | 2.60 | 0.13 | 0.41 | 0.91 | 0.04 |
| 9 - ⁰ F | 1.02 | 0.12 | 0.29 | 0.61 | - |
| Voltage, volts | 50.00 | 35.47 | 50.00 | 70.73 | 35.49 |
| Current, amps | 0.4005 | 0.2839 | 0.4004 | 0.5669 | 0.2822 |
| Water Flow, ml/min | 550 | 625 | 625 | 625 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | RTV 11 | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 1 | 1 | 1 | 1 | 2 |
| Number of Bolts | 18 | 18 | 18 | 18 | 18 |
| h, Btr/hr ft ² °F | 18.9 | 103.0 | 101.5 | 98.0 | 103.0 |

Table 10. Experimental Data-6 by 12 Inch Component Joints

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Table 10. Experimental Data-6 by 12 Inch Component Joints (Continued)

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| Run Number | 72 | 73 | 74 | 7 5 | 76 |
|---------------------------------|--------------------|--------------------|----------------------|--------------------|--------------------|
| Date | 12/17/64 | 12/17/64 | 12/21/64 | 12/21/64 | 12/21/64 |
| Pressure, Torr. | 6×10^{-7} | 6×10^{-7} | 6 x 10 ⁻⁷ | 6×10^{-7} | 6×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 75.5 | 88.5 | 67.5 | 73.5 | 86.2 |
| 2 - [°] F | 68 .8 | 75.0 | 64.2 | 67.0 | 73.4 |
| $3 - {}^{\circ}F$ | (2.6 | 62.8 | 61.1 | 61.1 | 61.6 |
| $4 - {}^{\mathrm{O}}\mathbf{F}$ | 63.6 | 6 4.8 | 61.6 | 61.9 | 63.3 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 1.37 | 2.85 | 0.71 | 1.41 | 2.88 |
| 2 - [°] F | 0.59 | 1.21 | 0.27 | 0.52 | 1.05 |
| 3 - ⁰ F | 2.52 | 5.50 | 1.26 | 2.48 | 5.02 |
| $4 - \mathbf{^{O}F}$ | 2.13 | 4.30 | 1.21 | 2.37 | 4.74 |
| 5 - [°] F | 2.86 | 5.76 | 1.79 | 3, 51 | 7.05 |
| 6 - ⁰ F | 0.33 | 0.71 | 0.17 | 0.30 | 0.57 |
| 7 - ⁰ F | 0.12 | 0.23 | 0.11 | 0.20 | 0.36 |
| 8 - ^C F | 0.11 | 0.26 | 0.16 | 0.30 | 0.61 |
| 9 - °F | | 0 | 0 .08 | 07 | 0.38 |
| Voltage, volts | 50.02 | 70.64 | 35 . 48 | 50,01 | 70.71 |
| Current, amps | 0.3980 | 6.5628 | 0.2834 | 0.3995 | 0,5651 |
| Water Flow, ml/min | 575 | 575 | 650 | 650 | 650 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filer | RTV 11 | RTV 11 | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 2 | 2 | 3 | 3 | 3 |
| Number of Bolts | 18 | 18 | 18 | 19 | 18 |
| h, Btu/hr ft ^{2 o} F | 101.0 | 97.0 | 90.0 | 92.0 | 92.0 |

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| Pure | ' 77 | 70 | 70 | 80 |
|------------------------------|--------------------|--------------------|--------------------|--------------------|
| Run | | (0 | 19 | 00 |
| Date | 12/22/64 | 12/22/64 | 12/22/64 | 12/28/64 |
| Pressure, Torr | 4×10^{-7} | 4×10^{-7} | 4×10^{-7} | 6×10^{-7} |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 80.5 | 100.2 | 138.6 | 69.9 |
| 2 - ⁰ F | 66. 3 | 71.6 | 82. 3 | 65.6 |
| 3 - ⁰ F | 61.1 | 60.9 | 61.4 | 61.8 |
| 4 - ⁰ F | 62. 0 | 62.8 | 65. 2 | 62.8 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 0,58 | 0.92 | 1.64 | 0.51 |
| 2 - ⁰ F | 1.89 | 3.85 | 7.73 | 0.28 |
| 3 - [°] F | 1.35 | 2. 75 | 5.19 | 0.18 |
| 4 - ⁰ F | 3, 29 | 6.75 | 13, 40 | 0.10 |
| 5 - ⁰ F | 12, 10 | 24.50 | 49.60 | 1. 49 |
| 6 - ⁰ F | 16. 42 | 33.20 | 6 5.80 | 3.14 |
| 7 - ⁰ F | 1.30 | 2.69 | 5.36 | 0.12 |
| 8 - ⁰ F | 5.78 | 11.59 | 22.90 | 0.70 |
| Voltage, volts | 29.60 | 41.90 | 59.20 | 29.61 |
| Current, amps | 0.6753 | 0.9543 | 1, 3437 | 0.6748 |
| Water Flow, ml/min | 550 | 550 | 550 | 600 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | None | None | None | RTV ii |
| Sample Number | 1 | 1 | 1 | i |
| Number of Bolts | 24 | 24 | 24 | 24 |
| h, Btu/hr ft ² °F | 8.36 | 8.32 | 8, 34 | 56.6 |

Table 11. Experimental Data-12 by 12 Inch Component Joint

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Table 11. Experimental Data - 12 by 12 Inch Component Joint (Continued)

| Run | 81 | 82 | 83 | 84 |
|------------------------------|--------------------|--------------------|--------------------|----------------------|
| Date | 12/28/64 | 12/28/64 | 1/5/65 | 1/5/65 |
| Pressure, Torr | 6×10^{-7} | 6×10^{-7} | 8×10^{-8} | 8 x 10 ⁻⁷ |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 77.7 | 93.3 | 68,7 | 77.3 |
| 2 - ⁰ F | 69.0 | 76.0 | 64 . 5 | 69.5 |
| 3 - ⁰ F | 61.5 | 61.7 | 60.5 | 61.4 |
| 4 - ⁰ F | 63. 4 | 65.3 | 61.7 | 63. 5 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 0,72 | 0.98 | 0.31 | 0, 53 |
| 2 - ⁰ F | 0.53 | 1.04 | 0.20 | 0.37 |
| 3 - ⁰ F | 0.37 | 0.62 | 0.20 | 0.35 |
| 4 - ⁰ F | 0.22 | 0, 48 | 0.12 | 0.20 |
| 5 - ⁰ F | 2.95 | 5.91 | 1.74 | 3.39 |
| 6 - ⁰ F | 6.25 | 12.41 | 2.76 | 5, 42 |
| 7 - ⁰ F | 0.27 | 0, 55 | 0.14 | 0, 25 |
| 8 - ⁰ F | 1,48 | 2.94 | 1.06 | 2.10 |
| Voltage, volts | 41.83 | 59.22 | 29.59 | 41.84 |
| Current, amps | 0.9527 | 1.3460 | 0.6747 | 0. 9521 |
| Water Flow, ml/min | 600 | 600 | 550 | 550 |
| Bolt Torque, in-lh | 24 | 24 | 24 | 24 |
| Filler | RTV 11 | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 1 | 1 | 2 | 2 |
| Number of Bolts | 24 | 24 | 24 | 24 |
| h. Btu/hr ft ² °F | 55.8 | 56. i | 51.7 | 52, 8 |

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| Run | 85 | 86 | 87 | 88 |
|-------------------------------|--------------------|--------------------|----------------------|----------------------|
| Date | 1/5/65 | 1/7/65 | 1/7/65 | 1/8/65 |
| Pressure, Torr | 8×10^{-7} | 8×10^{-7} | 8 x 10 ⁻⁷ | 5 x 10 ⁻⁷ |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 95. E | 69.0 | 76.9 | 92. 7 |
| 2 - ⁰ F | 79. 2 | 64.8 | 68.3 | 75.7 |
| 3 - [°] F | 63.4 | 60.6 | 60.4 | 59.1 |
| $4 - {}^{\circ}F$ | 67. i | 61.6 | 62. 3 | 63, 3 |
| Differential T.C. | | | | |
| 1 - ⁰ F | . 1.06 | 0. 42 | 0.57 | 0, 87 |
| 2 - ⁰ F | 9. 77 | 0.17 | 0.32 | 0.66 |
| 3 - ⁰ F | 0.65 | 0, 13 | 0.28 | 0.60 |
| 4 - ⁰ F | 0.37 | - | - | - |
| 5 - ⁰ F | 6.80 | 1.89 | 3.76 | 7.54 |
| 6 - [°] F | 10, 80 | 2.91 | 5.72 | 11,40 |
| 7 - ⁰ F | 0.63 | 0.14 | U. 30 | 0.64 |
| 8 - °F | 4.64 | 0. 93 | 1,85 | 3, 58 |
| Voltage, volts | 59. 26 | 29, (* | 41, 85 | 59,25 |
| Current, amps | 1, 3435 | 0. 6750 | 0.9518 | i.344 0 |
| Water Flow, ml/min | 550 | 550 | 550 | 500 |
| Bolt Torque, in-1b | 24 | 24 | 24 | 24 |
| Filler | RTV 11 | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 2 | 3 | 3 | 3 |
| Number of Bolts | 24 | 24 | 24 | 24 |
| h, Btu/hr ft ^{2 o} F | 51.0 | 51.4 | 51.9 | 52.4 |

APPENDIX II

STRUCTURAL JOINT TESTS

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The experimental data for structural joint configuration No. 1 (Figure 3 of main report) is given in Table 12 of this appendix. The location of thermocouples is shown in Figures 34 and 35. The average ΔT for each joint, called "a" and "b," was obtained by dividing the joint area into zones. Two zones were used, a one inch square zone at each bolt, with the bolt in the center, and the remaining area as the other zone. The water flow rate and temperatures were monitored as in the component joints, and absolute thermocouples 2 and 3 measure inlet and outlet tem-

- peratures respectively. For run number 1, the conductance calculation for join: "a" is as follows: $\overline{\Delta T}_{(1)} = 3.56^{\circ}F$ $\overline{\Delta T}_{(2)} = \frac{6.10 + 8.17}{2} = 7.13^{\circ}F$ $\overline{\Delta T}_{M} = \frac{A_{1}}{A_{T}}\overline{\Delta T}_{1} + \frac{A_{2}}{A_{T}}\overline{\Delta T}_{2}$
 - $\overline{\Delta T}_{M} = \frac{2}{6} (3.56) + \frac{4}{6} (7.13)$ $\overline{\Delta T}_{M} = 5.95^{\circ} F$

 $Q_{IN} = 22.05(0.2312) = 5.039$ watts = 17.4 Btu/hr $h_a = \frac{Q}{A\overline{\Delta T}}$

$$h_a = \frac{17.4}{\frac{6}{144} \times 5.95} = 70.3 \text{ Btu/hr ft}^2 \,^{\circ}\text{F}$$

Thermocouples 1, 2, and 3 are used to calculate the conductance of joint "a," h_a , and thermocouples 6, 7, and 8 to calculate the conductance of joint "b," h_b .

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Table 13 lists the experimental data for structural joint configuration 2. The thermocouple locations are shown in Figures 34 and 35. This configuration utilizes nut plates on one joint, called joint "h" in Table 13.

The results for configuration 3 are shown in Table 14, and the thermocouple locations in Figures 36 and 37. Differential thermocouples are located at the same (x, y) coordinates on the back of the angle brackets and panels at the locations shown on Figures 34, 35, 36, and 37.

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Figure 35. 9 Inch Structural Joint, Configurations 1 and 2, Thermocouple Locations



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| Run Number | 1 | 2 | 3 | 4 | 5 |
|---|--------------------|----------------------|----------------------|--------------------|----------------------|
| Date | 2/16/65 | 2/16/65 | 2/16/65 | 2/17/65 | 3/1/65 |
| Pressure, Torr | 2×10^{-6} | 2 x 10 ⁻⁶ | 2 x 10 ⁻⁶ | 1×10^{-6} | 1 x 10 ⁻⁶ |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 93.0 | 126.2 | 158, 4 | 196. 7 | 88,0 |
| $2 - {}^{\circ}F$ | 63.5 | 63.8 | 63.0 | 60.2 | 63.1 |
| 3 - ⁰ F | 63.9 | 64. 4 | 63. 9 | 61.4 | 63.3 |
| Differential T C. | | | | | |
| i - ^o F | 3.56 | 7. 4 6 | 11.32 | 16.00 | 0.22 |
| 2 - ⁰ F | 6.10 | 12.48 | 18, 32 | 25.55 | 0.54 |
| 3 - ⁰ F | 8.17 | 17, 05 | 26, 55 | 37,70 | 0.45 |
| 4 - [°] F | 7.89 | 16.82 | 26.30 | 36.95 | 7.95 |
| 5 - [°] F | 0.50 | 0.97 | 1, 51 | 2.13 | 0.06 |
| 6 - [°] F | 3.30 | 7.00 | 10, 72 | 14.90 | 0.20 |
| 7 - ⁰ F | 5.11 | 11.47 | 17.60 | 23.93 | 0.33 |
| 8 - [°] F | 7.24 | 14.72 | 23.28 | 31.60 | 0.65 |
| 9 - ⁶ F | 6.72 | 13,88 | 21.44 | 30.10 | 7.3Ŭ |
| 10 - ⁰ F | | | | | |
| Voltage, volts | 22.05 | 32.21 | 40.17 | 48.17 | 22.00 |
| Current, amps | 0.2310 | 0.3376 | 0. 4216 | 0. 5061 | 0. 2306 |
| Water Flow, ml/min | 750 | 750 | 750 | 550 S | 700 |
| Bolt Torque, in-1b | 24 | 24 | 24 | 24 | 24 |
| Filler | None | Nor.e | None | None | RTV 11 |
| Sample Number | 1 | 1 | 1 | 1 | 1 |
| Joint Length, in. | 6 | 6 | o | 6 | 6 |
| Number of Bolts | 2. | 2 | 2 | 2 | 2 |
| h _a , Btu/hr ft ^{2 o} F | 70.3 | 72.0 | 74. 2 | 75.7 | 1042 |
| h _b , Stu/hr ft ^{2 o} F | 80.5 | 80.6 | 80.6 | 85.3 | 1042 |

Table 12. Experimental Data - Structural Joint Configuration 1

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| Run Number | 6 | 7 | 8 | 9 | 10 |
|---|--------------------|----------------------|----------------------|--------------------|--------------------|
| Date | 3/1/65 | 3/1/65 | 2/19/65 | 2/19/65 | 2/19/65 |
| Pressure, Torr | 1×10^{-6} | 1 x 10 ⁻⁶ | 1 x 10 ⁻⁶ | 1×10^{-6} | 1×10^{-6} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 141.0 | 176.6 | 88, 4 | 149.8 | 184. 9 |
| 2 - [°] F | 62.8 | 62.6 | 61.1 | 62.3 | 61.3 |
| 3 - [°] F | 63.6 | 63.7 | 61.6 | 63.1 | 62,5 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 0, 8 8 | 2, 30 | 2, 58 | 8.25 | 11, 31 |
| 2 - ⁰ F | 1.95 | 3.36 | 4.08 | 14.20 | 20, 52 |
| 3 - ⁰ F | 1,64 | 2.77 | 5.44 | 18.88 | 27. 42 |
| $4 - {}^{\circ}F$ | 25.10 | 38.60 | 8.06 | 76.22 | 37.95 |
| 5 - ⁰ F | 0.33 | 2.75 | 0 | 0.04 | 0.13 |
| б - ⁰ F | 0.68 | 0, 82 | 3.50 | 11.24 | 15.88 |
| 7 - ⁰ F | 1.08 | 2.05 | 4.50 | 14.80 | 19.80 |
| 8 - ⁰ F | 2.28 | 3.89 | 6.17 | 19.93 | 26.08 |
| 9 - ^o F | 22, 58 | 33.75 | 7.82 | 24.17 | 34, 85 |
| 10 - [°] F | | | | | |
| Voltage, volts | 39.52 | 48.40 | 22.01 | 39,99 | 47.92 |
| Current, amps | 0. 41 4 9 | 0.5085 | 0. 2319 | 0. 4223 | 0.5067 |
| Water Flow, ml/min | 700 | 700 | 650 | 650 | 650 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | RTV ii | RTV 11 | None | None | None |
| Sample Number | 1 | 1 | 2 | 2 | 2 |
| Joint Length, in. | 6 | 6 | 6 | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 | 2 |
| h _a . Btu/hr ft ^{2 o} F | 906 | 715 | 103.5 | 100. 1 | 100.9 |
| h _b , Btu/hr ft ^{2 o} F | 995 | 895 | 88,5 | 90 | 96.5 |

Table 12. Experimental Data-Structural Joint Configuration 1 (Continued)

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| Run Number | 11 | 12 | 13 | 14 | 15 |
|---|----------------------|--------------------|----------------------|----------------------|--------------------|
| Date | 3/5/65 | 3/5/65 | 3/8/65 | 3/9/65 | 3/9/65 |
| Pressure, Torr | 2 x 10 ⁻⁶ | 2×10^{-6} | 1 x 10 ⁻⁶ | 8 x 10 ⁻⁷ | 8×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - [°] F | 90.5 | 142.5 | 192. 1 | 87.7 | 134. 7 |
| 2 - ⁰ F | 63.5 | 63. 4 | 62.9 | 62.8 | 62.5 |
| 3 - [°] F | 63.9 | 6 4 , 1 | 64.0 | 63,1 | 63,1 |
| Differential T.C. | | | | | |
| 1 - F | 7.12 | 21,30 | 35.8 | 0.50 | 1.50 |
| 2 - ^o f | 5.98 | 18.07 | 30.82 | 0.75 | 2.44 |
| 3 - ⁰ F | 2.61 | 7.99 | 13.70 | 0.77 | 2,27 |
| 4 - ⁰ F | 7.21 | 21, 42 | 36.0 | 7.92 | 23,70 |
| 5 - [°] F | 1.74 | 4.96 | 7.85 | 0.35 | 1 02 |
| $6 - \tilde{\mathbf{F}}$ | 7.21 | 21,05 | 32,65 | 0 | 0.07 |
| 7 - ⁰ F | 5, 87 | 17, 37 | 28, 5 | 0.65 | 2,08 |
| 8 - [°] F | 2, 84 | 8.36 | 14, 4 | 1,16 | 3, 53 |
| 9 - [°] F | 6.98 | 20.05 | 33, 15 | 6, 98 | 20, 47 |
| $10 - {}^{o}F$ | 1.37 | 3, 84 | 5, 49 | | |
| Voltage, volts | 21,58 | 37.50 | 48, 22 | 21.83 | 37.83 |
| Current, amps | 0, 2327 | 0, 4050 | 0.5217 | 0. 2289 | 0.3972 |
| Water Flow, mi/min | 675 | 675 | 700 | 750 | 750 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | G 683 | G 683 |
| Sample Number | Ĵ | 3 | 3 | 1 | 1 |
| Joint Length, in. | 6 | 6 | Ç. | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 | 2 |
| h _a , Btu/hr ft ^{2 o} F | 78,5 | 79. 4 | 77.0 | 602 | 595 |
| h _b , Blu/hr ft ²⁰ F | 77.5 | 79.8 | 81.9 | 681 | 652 |

Table 12. Experimental Data - Structural Joint Configuration 1 (Continued)

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| Run Number | 16 | 17 | 18 | 19 |
|--|--------------------|--------------------|--------------------|--------------------|
| Date | 3/9/65 | 3/15/65 | 3/15/65 | 3/16/65 |
| Pressure, Torr | 8×10^{-7} | 8×10^{-7} | 6×10^{-7} | 6×10^{-7} |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 176.5 | 88.5 | 138.9 | 189.1 |
| 2 - ^o F | 62.7 | 62.5 | 62.2 | 62.6 |
| 3 - [°] F | 63.8 | 63,0 | 63, 3 | 64.2 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 2.48 | 1.96 | 7.85 | 12.53 |
| $2 - {}^{o}F$ | 4.59 | 4. 05 | 13.85 | 22.80 |
| 3 - [°] F | 3.82 | 4. 59 | 15.75 | 25.65 |
| $4 - {}^{o}F$ | 37,45 | 8,62 | 26.40 | 43.30 |
| 5 - ^o F | 1.66 | 1.21 | 4.55 | 7, 48 |
| 6 - ⁰ F | 0, 21 | 3.64 | 11.28 | 18.70 |
| 7 - ⁰ F | 3.26 | 6.02 | 18.05 | 28.85 |
| 8 - ⁰ F | 5.71 | 6.57 | 19.58 | 31.45 |
| 9 - ⁰ F | 31,90 | 7.70 | 23, 25 | 37.20 |
| 10 - ⁰ F | | 3, 86 | 13.80 | 21.77 |
| Voltage, voltm | 47.80 | 19.4 4 | 33.73 | 43.55 |
| Current, amp# | 0.5024 | 0, 3841 | 0.6672 | 0.8623 |
| Water Flow. ml/min | 750 | 700 | 625 | 625 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | G 683 | None | None | None |
| Sample Number | i | i | 1 | 1 |
| Joint Length, in. | 6 | 9 | 9 | 9 |
| Number of Bolts | 2 | 3 | 3 | 3 |
| h _a , Btu/hr ft ^{2 o} F | 542 | 116 | 98, 5 | ±00, 8 |
| h _b , Btu/hr ft ² ^o F | 645 | *4 | 75.3 | 77.4 |

Table 12. Experimental Data - Structural Joint Configuration 1 (Continued)

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Table 13. Experimental Data-Structural Joint Configuration 2

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| Run Number | 20 | 21 | 22 | 23 | 24 |
|---|--------------------|--------------------|--------------------|--------------------|--|
| Date | 3/23/65 | 3/23/65 | 3/23/65 | 3/25/65 | 3/25/65 |
| Pressure, Torr | 5×10^{-7} | 5×10^{-7} | 5×10^{-7} | 7×10^{-7} | 7×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 87.8 | 134 | 178.8 | 89.3 | 140.4 |
| 2 - ⁰ F | 63.7 | 64.4 | 64.0 | 63.5 | 64, 2 |
| 3 - [°] F | 54.0 | 65.0 | 65.0 | 63.9 | 64.9 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 2.61 | 8.02 | 12, 75 | 2. 14 | 6.53 |
| 2 - ⁰ F | 5,20 | 16, 10 | 25,80 | 3. 93 | 12, 42 |
| 3 - ⁰ F | 6.79 | 20, 95 | 33, 75 | 5.55 | 17, 25 |
| 4 - ³ F | 8.03 | 24, 35 | 38, 65 | 7.37 | 21.60 |
| 5 - [°] F | -0.11 | -0. 23 | 0.05 | 0.35 | 0.94 |
| t - °F | 3.32 | 9.70 | 15.35 | 3.53 | 10, 44 |
| 7 - [°] F | 3.75 | 10, 81 | 16.33 | 5,25 | 15,20 |
| $8 - {}^{o}F$ | 5.35 | 15, 91 | 24.62 | 6, 72 | 19.88 |
| 9 - °F | 7.24 | 21, 40 | 34.10 | 7.07 | 20,22 |
| 10 - F | | | | | |
| Voltage, velts | 21.89 | 37, 85 | 48.97 | 21.88 | 37, 99 |
| Current, amps | 0. 2284 | 0.3956 | 0.5126 | 0. 2279 | 0.3964 |
| Water Flow, ml/min | 775 | 775 | 775 | 625 | 625 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | None | None |
| Sample Number | 1 | \$ | 1 | 3 | an a |
| Joint Length, in, | 6 | 6 | 6 | 6 | b |
| Number of Bolts | 2 | 2 | 2 | 2 | 2 |
| b _a , Blu/hr It ^{2 o} F | 34.2 | 81.5 | 85.0 | 105, 5 | i02.0 |
| h, Btu/hr ft ² oF | 63' Q | 100, 8 | 1: , 3 | 82, 4 | 91, 4 |

Table 13. Experimental Data-Structural Joint Condiguration Continued)

Run Number 25 26 27 28 3/25/65 3/26/65 3/26/65 3/29/65 Date 7×10^{-7} 3×10^{-6} 3×10^{-6} 2×10^{-6} Pressure, Torr Absolute T.C. 1 - F188.6 94.0 149.7 206.2 $2 - {}^{\circ}F$ 63.8 64.7 64.5 64.8 3 - °F 65.1 65.0 65.2 65.8 Differential T.C. $1 - {}^{O}F$ 11.05 2.54 8,00 12.35 2 - ⁰F 20.80 4.89 14.73 23.78 $3 - {}^{O}F$ 29.35 6.41 19.12 31.00 $4 - {}^{O}F$ 34.70 7.35 21,92 37.80 5 - ^oF 1,53 1.02 2.50 3.65 6 - °F 17.48 3.69 10.81 17.25 $7 - ^{\circ}F$ 24.20 4, 31 11.94 18.55 8 - ⁰F 32.45 5.24 14.55 23.10 9 - ⁰F 32.80 6.91 19.87 32.10 $10 - {}^{0}F$ Voltage, volts 49.00 21.86 37.75 48.88 Current, amps 0.5121 0.2368 0.3993 0.5179 Water Flow. ml/min 550 759 700 650 Bolt Torque, in-1b 24 24 24 24 Filler None None None None Sample Number 2 3 3 3 Joint Length, in, 6 6 6 6 Number of Bolts 2 2 2 r, h, Btu/hr ft² °F 100.8 89.5 88.5 92.6 h_{h} . Btu/hr ft² °F 83.2 93.5 19.3 105.2

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| Table 13. Experimental Data-Structural | Joint Configuration 2 (Continued) |
|--|-----------------------------------|
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| Run Number | 29 | 30 | 31 | 32 |
|--|--------------------|----------------------|--------------------|----------------------|
| Date | 3/31/65 | 5/31/65 | 3/31/65 | 4/1/65 |
| Pressure, Torr | 7×10^{-7} | 7 x 10 ⁻⁷ | 7×10^{-7} | 1 x 10 ⁻⁶ |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 84.2 | 124. 7 | 165.0 | 84.0 |
| 2 - ⁰ F | 63.3 | 63.5 | 63.5 | 62.7 |
| 3 - [°] F | 63.6 | 64. 1 | 64.7 | 63.0 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 0.70 | 2.51 | 4.46 | 0.95 |
| 2 - ⁰ F | 0.07 | 0.08 | 0 34 | 0.67 . |
| 3 - ⁰ F | 0.09 | 0.40 | 1.05 | 1.17 |
| $4 - {}^{O}F$ | 7, 73 | 22, 85 | 37,85 | 7.53 |
| 5 - ⁰ F | 0.33 | 0.91 | 1.37 | 0.20 |
| 6 - ⁰ F | C. 48 | 1,50 | 2.19 | 0,54 |
| 7 - [°] F | 0.64 | 1.96 | 3.70 | 0.80 |
| 8 - ⁰ F | 1,24 | 3.72 | 6.65 | 2.24 |
| 9 - ⁰ F | 7.42 | 21.50 | 34.75 | 7.49 |
| 10 - ⁰ F | | | | |
| Voltage, volts | 21.93 | 37.87 | 48,93 | 21,83 |
| Current, amps | 0.2289 | 0.3958 | 0.5120 | 0.2279 |
| Water Flow, ml/min | 650 | 650 | 650 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | RTV 11 | RTV 11 | RTV 11 | G 683 |
| Sample Number | 1 | 1 | 1 | 1 |
| Joint Length, in. | 6 | 6 | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 |
| h _a , Btu/hr ft ^{2 o} F | 1427 | 1227 | 1050 | 438 |
| h _h , Btu/hr ft ² ^o F | 520 | 514 | 490 | 341 |

| Run Number | 33 | 34 | 35 | 36 |
|---|----------------------|--------------------|--------------------|--------------------|
| Date | 4/i/65 | 4/2/65 | 4/5/65 | 4/5/65 |
| Pressure. Torr | 1 x 10 ⁻⁶ | 7×10^{-7} | 1×10^{-6} | 1×10^{-6} |
| Absolute T.C. | | | | |
| 1 - ⁰ F 2 - ⁰ F | 126.0 62.9 | 167, 2 63, 1 | 88.8 64.2 | 137.0 65.1 |
| 3 - ^o F | 63.8 | 64.5 | 64 <i>.</i> 6 | 66.0 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 3.54 | 6.13 | 2.78 | 8,04 |
| $2 - {}^{\circ}F$ | 1,89 | 3.10 | 4,03 | 11.92 |
| 3 - ⁰ F | 3.33 | 5.44 | 6, 31 | 18,92 |
| 4 - ⁰ F | 22.40 | 36.95 | 8, 51 | 26,80 |
| 5 - ° F | 0, 50 | 0,91 | 0.25 | 0.74 |
| 6 - ⁰ F | 1. 73 | 2.66 | 2.7ó | 8,35 |
| 7 - ⁰ F | 2, 44 | 3.74 | 5,23 | 15.50 |
| 8 - ⁰ F | 6.53 | 10,03 | 6.21 | 18.28 |
| 9 - °F | 21.75 | 35.15 | 7.97 | 23.00 |
| 10 - ⁰ F | | | 5.13 | 14.95 |
| Voltage, volts | 37,96 | 48.96 | 19.43 | 33.66 |
| Current, amps | 0, 3967 | 0.5124 | 0.3865 | 0.6710 |
| Water Flow, ml/min | 575 | 550 | 600 | 600 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | G 683 | G 683 | None | None |
| Sample Number | 1 | 1 | 1 | 1 |
| Joint Length, in. | 6 | 6 | 9 | 9 |
| Number of Bolts | 2 | 2 | 3 | 3 |
| h _a , Btu/hr ft ^{2 o} F | 425 | 420 | 93. 5 | 95.2 |
| h _b , Btu/hr ft ² °F | 345 | 375 | 84, 1 | 87.8 |

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Table 13. Experimental Data-Structural Joint Configuration 2 (Continued)

| Run | 37 | 38 | 39 | 40 |
|---|----------------------|----------------------|--------------------|--------------------|
| Date | 4/5/65 | 4/6/65 | 4/6/65 | 4/6/65 |
| Pressure, Tor- | 1 x 10 ⁻⁶ | 8 x 10 ⁻⁷ | 8×10^{-7} | 8×10^{-7} |
| Absolute T.C. | | | | |
| í - ^O F | 182. 2 | 85.1 | 126.0 | 162. 2 |
| 2 - [°] F | 64.6 | 6 4 , 0 | 64. 4 | 64 . 0 |
| 3 - ^ο F | 66.2 | 64.4 | 65.1 | 65.0 |
| Differential T.C. | | | | |
| 1 - ⁰ F | 12.58 | 0.16 | 0.60 | 1.26 |
| 2 - ⁰ F | 20.59 | 0.39 | 1.44 | 2,99 |
| $3 - {}^{O}F$ | 32.44 | 0,83 | 2.61 | 4.95 |
| $4 - {}^{\circ}F$ | 45.32 | 7,33 | 22,00 | 36.10 |
| 5 - ⁰ F | 1, 28 | 0,35 | 1.05 | 1.87 |
| 6 - [°] F | 12.05 | 0.17 | 0,65 | 3.43 |
| 7 - [°] F | 23,56 | 0.13 | 0.51 | 1,44 |
| 8 - ⁰ F | 27, 59 | 0,35 | 1.36 | 2.86 |
| 9 - ⁰ F | 36,90 | 7.41 | 21,60 | 35.02 |
| $10 - {}^{O}F$ | 25, 22 | | | |
| Voltage, volts | 43.44 | 21.89 | 37.99 | 48.99 |
| Current, amps | 0.8674 | 0. 2281 | 0.3960 | 0.5119 |
| Water Flow, ml/min | 600 | 625 | 625 | 625 |
| Bolt Torque, in-1b | 24 | 24 | 24 | 24 |
| Filler | None | RTV 11 | RTV 11 | RTV 11 |
| Sample Number | 1 | 2 | 2 | 2 |
| Joint Length, in. | 9 | 6 | 6 | 6 |
| Number of Bolts | 3 | 2 | 2 | 2 |
| h _a , Btu/hr ft ^{2 o} F | 94. 1 | 889 | 795 | 669 |
| h _b , Bîu/hr ft ^{2 o} F | 97.6 | 1892 | 1466 | 800 |

Table 13. Experimental Data—Structural Joint Configuration 2 (Continued)

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| Table 14. Experimental Data — Structural Joint Configuration 3 | Table 14. | Experimental | Data — Structural | Joint | Configuration 3 |
|--|-----------|--------------|-------------------|-------|-----------------|
|--|-----------|--------------|-------------------|-------|-----------------|

| Run Number | 41 | 42 | 43 | 44 | 45 |
|-------------------------------|--------------------|----------------------|----------------------|----------------------|--------------------|
| Date | 5/8/65 | 5/8/65 | 5/8/65 | 5/9/65 | 5/9/65 |
| Pressure, Torr | 1×10^{-6} | 1 x 10 ⁻⁶ | 1 x 10 ⁻⁶ | 1 x 10 ⁻⁶ | 1×10^{-6} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 70.3 | 84, 5 | 98.1 | 69.6 | 80.0 |
| 2 - ⁰ F | 62.7 | 62.6 | 62.2 | 63.5 | 63, 1 |
| 3 - [°] F | 63.0 | 63.3 | 63.4 | 63.9 | 64.0 |
| Differential T.C. | | | | | |
| 1 - ⁰ F | 1.42 | 4.55 | 7.80 | 1, 11 | 4.06 |
| 2 - ⁰ F | 3.12 | 9.3 4 | 15.78 | 2.35 | 7.48 |
| 3 - ^o F | 3,83 | 11.61 | 19.67 | 2, 84 | 8.90 |
| $4 - {}^{O}F$ | 3.62 | 10.91 | 18.90 | 3. 84 | 11,20 |
| 5 - [°] F | -0.22 | 0.36 | 1.15 | 0. 43 | 1,55 |
| 6 - ⁰ F | 2.66 | 8.30 | 14.35 | 1.92 | 6.15 |
| 7 - ^o F | 3.11 | 9.55 | 16.40 | 1.98 | 6. 41 |
| 8 - ⁰ F | | | | | |
| Voltage, volts | 21.93 | 37.94 | 49.01 | 21.89 | 38,0 1 |
| Current, amps | 0. 2281 | 0.3949 | 0.5106 | 0.2268 | 0. 3943 |
| Water Flow, ml/min | 600 | 600 | 600 | 575 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | None | None |
| Sample Number | 1 | 1 | 1 | 2 | 2 |
| Joint Length, in. | 6 | 6 | 6 | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 | 2 |
| h, Btu/hr ft ^{2 o} F | 147 | 144.2 | 142 | 194 | 180 |

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|-------------------------------|----------------------|--------------------|--------------------|--------------------|--------------------|
| Run Number | 46 | 47 | 48 | 49 | 50 |
| Date | 5/9/65 | 5/13/65 | 5/13/65 | 5/13/65 | 5/15/65 |
| Pressure, Torr | 1 x 10 ⁻⁶ | 6×10^{-7} | 6×10^{-7} | 6×10^{-7} | 5×10^{-7} |
| Absolute T.C. | | | | | |
| 1 - ⁰ F | 89.7 | 72.2 | 86.8 | 98.3 | 7 0, 7 |
| 2 - ⁰ F | 62.5 | 65.0 | 66.0 | 64.1 | 62.4 |
| 3 - ⁰ F | 63.7 | 65.3 | 66.9 | 65.4 | 62.8 |
| Differential T.C. | | | | | |
| i - ^o F | 7.11 | 2.69 | 7.94 | 13, 30 | 0,107 |
| 2 - ⁰ F | 12.79 | 3, 82 | 11.62 | 19.90 | 0,583 |
| $3 - {}^{O}F$ | 15,31 | 4. 91 | 14.60 | 24.80 | 0.414 |
| $4 - {}^{\circ}F$ | 19,00 | 4.01 | 11.79 | 20.30 | 3,84 |
| 5 - [°] F | 1.94 | 0.07 | 0,43 | 0.76 | -0.458 |
| 6 - [°] F | 10.50 | 3.71 | 11.08 | 18,82 | 0,307 |
| 7 - ⁰ F | 10.81 | 3.66 | 10.52 | 17.78 | 0.222 |
| 8 - [°] F | | | | | |
| Voltage, volts | 49.01 | 21.88 | 37.20 | 48.00 | 21,91 |
| Current, amps | 0, 5084 | 0. 2385 | 0. 4 059 | 0.5244 | 0.2279 |
| Water Flow, ml/min | 575 | 575 | 575 | 575 | 425 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 | 24 |
| Filler | None | None | None | None | RTV 11 |
| Sample Number | 2 | 3 | 3 | 3 | í |
| Joint Length, in. | 6 | 6 | 6 | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 | 2 |
| h, Btu/hr ft ^{2 o} F | 174.0 | 112, 2 | 108.5 | 106.5 | 1110 |

Table 14. Experimental Data -- Structural Joint Configuration 3 (Continued)

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| Run Number | 51 | 52 | 53 | 54 |
|--|--------------------|--------------------|--------------------|--------------------|
| Date | 5/15/65 | 5/15/65 | 5/16/65 | 5/16/65 |
| Pressure, Torr | 5×10^{-7} | 5×10^{-7} | 4×10^{-7} | 4×10^{-7} |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 87.7 | 102,5 | 74.3 | 91. 3 |
| 2 - ⁰ F | 63.7 | 63.4 | 66.0 | نّ və, 0 |
| 3 - ⁰ F | 64.8 | 65.0 | 66.3 | 68.9 |
| Differential T.C. | | | | |
| 1 - [°] F | 0.461 | 0.827 | 0.222 | 0, 723 |
| 2 - ⁰ F | 1,560 | 2.441 | 0.284 | 0, 991 |
| 3 - ⁹ F | 0.979 | 1.672 | 0.418 | 1.208 |
| 4 - ⁰ F | 11,52 | 19.50 | 3,89 | 11.71 |
| 5 - ⁰ F | -0,282 | -0.218 | -0,515 | 0. 491 |
| 6 - ⁰ F | 0,735 | 1.260 | 0.391 | 1.104 |
| 7 - ⁰ F | 0.630 | 1.088 | 0.311 | 0,835 |
| 8 - ⁰ F | | | | |
| Voltage, volts | 38.00 | 48.99 | 21.90 | 38,00 |
| Current, amps | 0.3956 | 0, 5104 | 0.2278 | 0.3955 |
| Water Flow, ml/min | 375 | 45 0 | 450 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | RTV 11 | RTV 11 | G 683 | G 683 |
| Sample Number | 1 | 1 | 1 | 1 |
| Joint Length, in. | 6 | 6 | 6 | 6 |
| Number of Bolts | 2 | 2 | 2 | 2 |
| h, Btu/hr ft ² ^o F | 1273 | 1242 | 1328 | 1262 |

Table 14. Experimental Data — Structural Joint Configuration 3 (Continued)

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| Run Number | 55 | 56 | 57 | 58 |
|-------------------------------|--------------------|--------------------|--------------------|--------------------|
| Date | 5/16/65 | 5/19/65 | 5/19/65 | 5/20/65 |
| Pressure, Torr | 4×10^{-7} | 7×10^{-7} | 7×10^{-7} | 4×10^{-7} |
| Absolute T.C. | | | | |
| 1 - ⁰ F | 103. 2 | 75.0 | 87.0 | 96.8 |
| 2 - ⁰ F | 63.9 | 68. o | 69.2 | 67.2 |
| 3 - ⁰ F | 65.1 | 69. 2 | 70,2 | 68.9 |
| Differential T.C. | | | | |
| i - ^o F | 1.273 | 1.44 | 4.41 | 7.60 |
| $2 - {}^{o}F$ | 1.678 | 3.10 | 9.46 | 16.21 |
| 3 - [°] F | 2.043 | 4.10 | 12.64 | 21.63 |
| 4 - ⁰ F | 19.85 | 4.10 | 12, 39 | 21,08 |
| 5 - °F | 0.80 | 0.40 | 1.50 | 2.78 |
| 6 - °F | 1.905 | 4.64 | 14.00 | 23.78 |
| 7 - ⁰ F | i. 440 | 3,84 | 11.61 | 19.60 |
| 8 - ⁰ F | | 3.00 | 9.18 | 15.47 |
| Voltage, volts | 49.01 | 18.98 | 32, 84 | 42.45 |
| Current, amps | 0.5105 | 0.3958 | 0.6852 | 0.8860 |
| Water Flow, ml/min | 625 | 575 | 575 | 575 |
| Bolt Torque, in-lb | 24 | 24 | 24 | 24 |
| Filler | G 683 | None | None | None |
| Sample Number | 1 | 1 | i | 1 |
| Joint Length, in. | 6 | 9 | 9 | 9 |
| Number of Bolts | 2 | 3 | 3 | 3 |
| h, Btu/hr ft ^{2 o} F | 1231 | 142.2 | 139 | 135.5 |

Experimental Data-Structural Joint Configuration 3 (Continued) Table 14

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APPENDIX III

SCRIPT F COMPUTER FROGRAM PRINT OUT

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CIO FORMAT LIMI.26X.56HSPECULAR-DIRECTIONAL SCRIPT F PROGRAM LAHO52A). 1 10/28/44 /(140.21X.1146) 1 CALA SCRF (M.MN. MNO.F.AREA.R.D.DI.SF.SFA.IFRN) FORMAT (1H1.5X.11HAREA VECTUR//(5E20.8)) DO 2100 J-1.N 1F(J.LT.11F(J.1)+AREA(1)+F(1.J)/AREA(J) FORMAT (1H1+5K+16HSCRIFT FA MATRIX FORMAT (1H1.5X.15HRHO(I.J) MA.RIX) Call Mprt (RH0.N) Write (5.1005) FORMAT (1H0/1H0.5X,9HBLOCK NO. 14) FOUNDAT []H].5X.15HSCRIPT F MATRIX) WALTE (3.1005) FORMAT (1M1.5%-14HR(1.J+K) ARAY) FORMAT (1H1,5X,13HF(1,J) MATRIX) 1001 FORMAT (1HC.5X. CHEND OF IMPUT) WRITE (3.1004) (AREA([).I=1.N) F (RHO(1 , 1)) 2020 - 2070 - 2070 CALL MPRT (RI1.1.K).NI IF (CLR) 300+100+300 Free 1 . 1) = - # + O (1 . 1) WRITE (3.1010) ID R(K+1+J)=R00(1+1) CALA MPRT (SFA.R) MRITE (3.1009) K CALL MPRT (SF.N) CALL HERT (FIR) WEITE (3.1002) WRITE (1,1001) METE AS. 1007) KITE (3,1008) DO 2040 K=1.J DO 2100 K=1.J DO 2100 1-1-N M+1+1 0402 00 DO 150 K-1.F JUNI LINOU 2+2 2000 2070 2020 2060 2100 1005 1009 1002 1033 1004 1007 1001 130 U

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| S I BMAP | ERRS | | | | | | | | | | | | - | | | ER23 | ER24 | | , | | | | | | | | | | | | | | | BEG1 | | | | | |
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|---|---|--|--|---|
| | MAT9 LIST,REF,DECK SUBROUTINE MAT9(A,X,KR,KC,LC,LA) DIMEMSION A(KR,KC),X(KR,LC) MMCK MMCKC DO 15 1=2,M 11=1-1 | F(A(I.J))9.15.9 F(A(I.J))9.15.9 F(A(I.J)/A(J.J))-ABS(A(I.J)) 11.10.10 F(A(J.J)/A(I.J) F(A(J.J)/A(I.J) F(A(J.J)/A(I.J) F(A(J.K)-A(I.J) F(J.K)-A(I.K) F(J.K)-A(I.K) F(J.K)-A(I.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-ReA(J.K) F(J.K)-A(I.K)-REA(J.K) F(J.K)-F(J.K)-F(J.K) F(J.K)-F(J.K)-F(J.K)-F(J.K) F(J.K)-F(| ETURN 228J=1.M 2281=2.N J=M-1+1 =0. 1=M-1+2 1=0. | F (JJ.K)*K(*.J) F (ABS(A(JJ.J.))-3.0E-10)26.26.2A ALL ERRS(2.4HMATS) A=-1 ETURN [JJ.J)*(A(JJ.KK)-B)/A(JJ.J.J) (JJ.J)*(A(JJ.KK)-B)/A(JJ.J.J) |
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| | TC MPRT LIST.REF.DECK MPRT PRINTS THE FIRST N ROWS AND COLUMNS OF A 20X2G ARRAY SUBROUTIT'E MPRT (A.M) SUBROUTIT'E MPRT (A.M) DO JOO 1=1.M DO JOO 1=1.M MRITE (3:1001) 1:(A(16J).J=1.M) MRITE (3:10.M) MRITE (3:1001) 1:(A(16J).J=1.M) MRITE (3:10.M) MRITE | | | |
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SCRF I.IST.REF.DECK SCRF COMPUTES AN NXM SCRIFT F MATRIX (1 SCRIPT F(1,J))} +ALPHA(20+20)+A(20+20)+B(20+20)+C(20+20)+DD(20+20) SUBROUTINE SCRF (N.N. RHO, F. AREA, R.D. DI, SF. SFA, IERR) DIMENSION RH0(20+20)+F(20+20)+AREA(20)+R(20+20+20) COMPUTE ABSORBITIVITIES AND EMISSITIVITIES. Do 210 I=1.N Do 210 J±1.N ALPMA(I.J)= 1.-RHO(I.J) \bigcirc CUMPUTE MATRICES A, 8, C, AND D. R(JoKol)#F(loK)#F(K.J) •SF(20.20)•SFA(20.20) ALPHA(I .J) #WK(3) CLEAR_STORAGE PEGIONS DO 120 1=1.400 東大「6」= MK(5) #RHO(7*K) (N*N) IQ* (NN*N)Q* DO. 150 I=1 .NN2 Nº 1=1 066 00 X=1.N SF(1+1)= 0. DD([,1])* 0. SFA([+])= 0 D(1.1)= 0. • 4N2= 2+N2 HX(4)= 0. WK (10) CONTINUE CONTINUE CONTINUE DO 320 H ERR= 0 N2M N4W MK(1)= CO 390 IK (2)= IK (3) = SIBFTC SCRF 200 210 150 100 120 300 υυ \bigcirc 152

1 FORMAT (64H] ERROR. MATRIX D CAN NOT BE INVERIED. CHECK DIAGONAL E Ì De/IHOSSES BIMATRIX DI (1, K) * WK (7) PHALLOK) THE (6) 0 (D.D. W.W. W. W.LA) COMPUTE CAPITAL D MATRIX + DI(J+K)+C(K+I) UK(7)= WK(5)=ALPHA(J+K) =J. DIAGONAL ELENENTS UNIN - TINS F (1-J) 390.330.390 [] 410,410,300 CALL VHPRT (D.M) GO TO 900 3-23. D(1.J)= 1.-WK(4) 3,10001 W(3) -HK (] K=l=X KIJJ= WKIJJ CONTINUE DD(1.J)= W K(2)= W(2) K(4)= K(4 B41+183= 1+ K(3)- K(3 CONTINUE CONTINUE THE CONTINUE -(1-1)) No. 00 520 -(L+1)A a().[]0 X. X **JRITE** Q=X 88 2 0001 ŝ 410 520 005 320 330 υ U U 15

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C COMPUTE SCRIPT F MATRIX 600 DQ 690 I=1.N WE A(1.J) WE A(1.J) ME A(1.J) 00 620 K=1.M WE WE HE + B(1.K)=DD(J.K) 620 CONTINUE 5F(1.J)= -WE=AREA(1) 690 CONTINUE 900 RETURN 5FAII.J)= -WE=AREA(1) 600 RETURN 600 CONTINUE i

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APPENDIX IV

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EXPERIMENTAL DATA ----

RADIATION EXCHANGE EXPERIMENT

The experimental data used in the verification of the analytical techniques described in Section 6 are shown in Table 15. The predicted receiver temperature was calculated from a heat balance between the surfaces of the experimental enclosure. The heat balance equation for the receiver is

$$A_{S} \mathfrak{I}_{S-R} \left(\sigma T_{S}^{4} - \sigma T_{R}^{4} \right) + A_{M} \mathfrak{I}_{M-R} \left(\sigma T_{M}^{4} - \sigma T_{R}^{4} \right) = A_{R} \mathfrak{I}_{R-O} \left(\sigma T_{R}^{4} - \sigma T_{O}^{4} \right) + Q_{LOSS}$$
$$\sigma T_{R}^{4} = \frac{A_{S} \mathfrak{I}_{S-R}^{\sigma} T_{S}^{4} + A_{M} \mathfrak{I}_{M-R}^{\sigma} T_{M}^{4} + A_{R} \mathfrak{I}_{R-O}^{\sigma} T_{O}^{4} - Q_{LOSS}}{A_{S} \mathfrak{I}_{S-R}^{\sigma} + A_{M} \mathfrak{I}_{M-R}^{\sigma} + A_{R} \mathfrak{I}_{R-O}^{\sigma}}$$

For Configuration 3, run number 7, using the directional analysis to obtain the \exists 's

$$\sigma T_{R}^{4} = \frac{0.0593(201.84) + 0.0013(62.85) + 0.159(1.0) - 0.57}{0.2196}$$
$$\sigma T_{R}^{4} = 53.0$$
$$T_{R} = 419.4^{\circ}R$$

This temperature can be compared to the experimentally measured value of 428. 2° R.

The net heat lost by the source, Q_S , is computed by summing the heat leaving the source and received by each surrounding surface

$$Q_{S} = Q_{S-M} + Q_{S-R} + Q_{S-O} + Q_{LOES}$$

$$Q_{S-M} = A_{S} \cdot S_{S-M} \left(\sigma T_{S}^{4} - \sigma T_{M}^{4} \right)$$

$$Q_{S-R} = A_{S} \cdot S_{R-S} \left(\sigma T_{S}^{4} - \sigma T_{R}^{4} \right)$$

$$Q_{S-O} = A_{S} \cdot S_{R-O} \left(\sigma T_{S}^{4} - \sigma T_{O}^{4} \right)$$

Using the data from Run 7, directional analysis

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$$Q_{s} = 0.0013(201.84 - 62.85) + 0.0593(201.84 - 57.62) + 0.159(201.84 - 1.0)$$

$$Q_{S} = 40,68 \text{ Btu/nr}$$

This value compares to the experimental quantity of 41, 29 Btu/hr.

As described in Section 6, a guard heater method was used to minimize the extraneous heat losses from each test surface. Figure 38 shows the measured heat losses from a vacuum deposited aluminum coated surface and a 3M black paint coated surface. These results were used to correct the experimentally measured source radiation and in the prediction of the temperature of the receiver temperature.


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|---------------------------|--------------------|--------------------|----------------------|--------------------|----------------------|
| Run Number | 1 | 2 | 3 | 4 | 5 |
| Date | 3/18/65 | 3/19/65 | 3/19/65 | 3/23/65 | 3/4/65 |
| Pressure | 4×10^{-6} | 4×10^{-6} | 3 x 10 ⁻⁶ | 4×10^{-6} | 5 x 10 ⁻⁶ |
| Configuration | * | * | * | 油 (加) | 1 |
| Source | | | | | |
| Center T.C ^O F | 129.9 | -1.0 | -150.9 | +4.4 | 73.8 |
| Corner T.C ^O F | 129.1 | -L.5 | -151.7 | +4.1 | 72.2 |
| Guard T.C ^O F | 129.9 | -0.3 | -147.4 | +1.0 | 73.1 |
| Mirror | | | | | |
| Center I.C ^O F | | | | | |
| Corner T.C ^O F | | | | | |
| Guard T.C ^O F | | | | | |
| Receiver | | | | | |
| Center T.C ^O F | | | | | -114.5 |
| Corner T.C ^O F | | | | | -115.0 |
| Guard T.C ^O F | | | | | -114.8 |
| Source Voltage, volts | 50.5 | 30.4 | 13.5 | 6.86 | 41.11 |
| Source Current, amps | 0.276 | 0.167 | 0.0776 | 0.0373 | 0.2266 |

Table 15.Summary of the Data Obtained in the Experimental
Testing of the Analytical Prediction

*Single black plate

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Table 15.Summary of the Data Obtained in the Experimental
Testing of the Analytical Prediction (Continued)

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| Run Number | 6 | 7 | 8 | 9 | 10 |
|---------------------------|--------------------|--------------------|--------------------|----------------------|----------------------|
| Date | 3/28/65 | 4/1/65 | 4/5/65 | 4/6/65 | 4/8/65 |
| Pressure | 2×10^{-6} | 3×10^{-6} | 4×10^{-6} | 5 x 10 ⁻⁶ | 7 x 10 ⁻⁶ |
| Configuration | 2 | 3 | 4 | 5 | 6 |
| Source | | | | | |
| Center T.C ^O F | 124.6 | 125.8 | 124. 7 | 125.0 | 124. 5 |
| Corner T.C ^O F | 124, 5 | 125.8 | 124.3 | 124.6 | 124.1 |
| Guard T.C ^O F | 125. 1 | 125. 3 | 123.7 | 126.7 | 125.5 |
| Mirror | | | | | |
| Center T.C ^O F | | -22. 4 | -51.8 | -74.7 | -63.5 |
| Corner T.C ^O F | | -22. 4 | -51.7 | -74.7 | -62.6 |
| Guard T.C ^O F | | -23.7 | -51,7 | -73.5 | -60, 3 |
| Receiver | | | | | |
| Center T.C ^O F | -66.1 | -31,0 | - 36. 5 | -50, 3 | -61,3 |
| Corner T.C ^O F | -66.4 | -31.7 | -37.0 | -50.3 | -61.3 |
| Guard T.C ^O F | -65.4 | -24. 4 | -35.2 | -52.4 | -61. i |
| Source Voltage, volts | 48.7 | 4 8. 0 | 47.7 | 47.3 | 47.4 |
| Source Current, amps | 0.267 | 0. 2635 | 0. 2615 | 0. 259 | 0. 2592 |

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APPENDIX V

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APPENDIX VI COMPONENT JOINT TEST DATA USED FOR CORRELATION TASK

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Three experimental tests were conducted to verify the results of the correlation task. The experimental mersurements are given in Table 16. The thermocouple locations and data reduction technique are described in Appendix I. The bolt locations for these three tests are shown in Figure 39.



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| Run Number | 41 | 42 | 43 |
|-------------------------------|--------------------|--------------------|--------------------|
| Date | 11/24/64 | 11/25/64 | 11/25/64 |
| Pressure | 5×10^{-7} | 5×10^{-6} | 5×10^{-6} |
| Absolute T.C. | | | |
| 1 - ⁰ F | 92.6 | 88.4 | 92.7 |
| 2 - ^o f | 81.8 | 74.9 | 75.0 |
| 3 - [°] F | 66.6 | 65.9 | 66. 4 |
| 4 - ⁰ F | 67.0 | 66. 4 | 66.9 |
| Differential T.C. | | | |
| 1 - ⁰ F | 17.64 | 14. 32 | 18, 42 |
| 2 - ⁰ F | 17.70 | 13.93 | 18.45 |
| $3 - {}^{o}F$ | 11.94 | 7.36 | 10.19 |
| $4 - {}^{\circ}F$ | 7.46 | 4.97 | 10.59 |
| 5 - ⁰ F | 1,80 | 1.11 | 9, 44 |
| 6 - ⁰ F | 7,80 | 4.26 | 7, 95 |
| 7 - ⁰ F | 10.18 | 3, 26 | 3.64 |
| 8 - ⁰ F | 10.40 | 2.53 | 1.61 |
| Voltage, volts | 52.96 | 52.95 | 52, 95 |
| Current, amps | 0. 1880 | 0. 1880 | 0. 1880 |
| Water Flow, ml/min | 700 | 575 | 550 |
| Bolt Torque, in-lb | 24 | 24 | 24 |
| Filler | None | None | None |
| Sample Number | 3 | 3 | 3 |
| Number of Bolts | 4 | c , | 8 |
| h, Btu/hr ft ^{2 o} F | 13, 4 | 22.0 | 13.7 |

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Table 16. Additional Component Joint Correlation Data

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