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# EXPERIMENTS ON THE THERMAL PERFORMANCE OF RIBBON PARACHUTES

C. J. SCOTT E. R. G. ECKERT

UNIVERSITY OF MINNESOTA

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#### FOREWORD

This report summarizes the work done by the Heat Transfer Laboratory, Department of Mechanical Engineering, University of Minnesota, during a research program sponsored by the Recovery and Crew Station Branch of the Air Force Flight Dynamics Laboratory under Contract AF33(657)11688, Project No. 6065, Task No. 606503. The manuscript was released by the authors September 1964 for publication as an RTD Technical Report. The contract's technical project monitor was C. A. Babish 111 of the Air Force Flight Dynamics Laboratory. E. R G. Eckert served as principal investigator of the contract at the University of Minnesota.

The report covers work conducted from July 1963 through September 1964.

The authors wish to thank other persons on the staff of the University of Minnesota who have contributed to various phases of the work. In particular, special acknowledgements are due to Dr. R. Olson for his design work and Mr. V. Jonsson, who programmed the data reduction procedures. Appreciation is also extended to Messrs. K. Krall, J. Lloyd, and B. Williams for their precise work during the operation of the pressurized subsonic wind tunnel and assistance in the data reduction and analysis.

This technical report has been reviewed and is approved.

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Vehicle Equipment Division AF Flight Dynamic Laboratory

#### ABSTRACT

Experimental heat transfer studies were conducted on full scale ribbons of flat circular type parachutes having a geometric porosity of 20.5 percent. A pressurized subsonic wind tunnel served as the flow facility. The average approach flow velocity was 134 feet per second. The measurements were made in the Reynolds number range of one million to ten million, where the Reynolds number is based on the ribbon width of 2.1 inches and on the velocity and temperature of the flow in the slots between the ribbons. The pressure ratio applied to the ribbon was varied from 1.4 to 26.3. Using a transient energy balance, local and average heat transfer data were obtained and compared with available analyses.

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# NOMENCLATURE

٨	convective heat transfer area, ft <sup>2</sup>
а	speed of sound, ft/see
cp	specific heat, Btu/1b <sub>m</sub> - <sup>o</sup> R
D	width of parachute ribbon, "slat" , ft
h	convective heat transfer coefficient, $Btu/hr-ft^2 - {}^{O}R$
k	thermal conductivity, Btu/hr-ft- <sup>0</sup> H
М	Mach number
Nu	${\rm h}{ m D}$ Nusselt number based on stagnation conditions ko
Nu <sub>w</sub>	hx Nusselt number based on wall conditions
р	absolute static pressure, lb <sub>f</sub> /in <sup>2</sup>
q	rate of heat transfer per unit area, Btu/hr-ft <sup>2</sup>
x	distance along ribbon from stagnation point, it.
Re <mark>*</mark> =	$\frac{\rho^* a^* D}{\mu^*}$ = Reynolds number based on slat width and conic condition $\mu^*$ in the slot
Re <sub>w</sub> -	$\frac{\rho_{w} U_{8} x}{\mu_{w}}$
R	slat half width, ft
Т	temperatures, <sup>o</sup> F or <sup>o</sup> R
T <sub>aw</sub>	recovery temperature, <sup>o</sup> F or <sup>o</sup> R
t	thickness, ft
U <sub>S</sub>	external flow velocity outside boundary layer, ft/see
Uao	undisturbed velocity approaching model, ft/see
р	density, 1bm/ft <sup>3</sup>
ť	time, hr
Super	cripts

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denotes sonic conditions calculated from the measured stagnation conditions, assuming an isentropic expansion to sonic velocity

Several symbols defined in the lext and used but tark fill special included in this list.

## NOMENCLATURE (cont'd)

# Subscripts

лW	denotes adiabatic wall conditions, q <sub>w</sub> - O
avg	average value
D	conditions based on slat width D
exit	denotes conditions downstream of ribbon
1	denotes undisturbed conditions upstream of model
2	denotes conditions at the downstream stagnation point of the ribbon
m	refers to ribbon material
0	denotes stagnation conditions, also condition in settling chamber before wind tunnel contraction
stag	denotes conditions at the stagnation point
W	denotes local conditions at the surface of the test ribbon
8	denotes conditions at edge of boundary layer

## I. INTRODUCTION

A growing interest in the use of parachutes for aerospace-vehicle recovery operations has directed attention to the aerodynamic heat transfer problems involved when high speed aerodynamic decelerators are employed. A variety of retardation devices have been proposed which satisfy such dynamic design requirements as filling time, opening shock, drag establishment and control and stability. However, as the flight Mach number is increased, a common problem, aerodynamic heating, is encountered. At the present time, there exists neither a fully predictive theory nor sufficient experimental data to permit reliable calculations of the heat rates involved in the several deceleration schemes (1)<sup>\*</sup>

In general, aerodynamic decelerators must possess a large drag-toweight ratio and must be capable of being stored in a small volume. Therefore, most proposed drag producing devices are relatively thin and flexible. In addition, dynamic stability requires venting or porosity. As a result, most retardation techniques employ porous surfaces involving high temperature plastic, glass, or wire mesh cloth in conjunction with other venting techniques. The heat transfer to these elements of mesh is a common problem in parachute performance calculations. Alternately, experimental heat transfer data must be applied to a variety of situations.

The flow field associated with a parachute results from the interaction of the large-scale phenomena enveloping the complete body and the small-scale processes associated with the local flow about a single element in the mesh material itself. The large scale phenomena, (parachute shape and size, velocity, altitude) which vary with the particular design, are

Numbers enclosed by brackets refer to references.

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generally involved with the aerodynamics of the problem and contribute end or boundary conditions (pressure ratio, Reynolds number) to the small-scale phenomena. a and the second reasing manual little of the second second second second second second second second second s

A. Large Scale Phenomena

The range of interests in the present study consists of altitudes from sea level up to 200,000 feet and flight Mach numbers ranging from 2 to 5. A concave hemisphere canopy is a typical shape considered for supersonic operations although specification of the exact geometry is not necessary. In previous work (2), it was felt that a good starting point for study of the large-scale phenomena was the simple concave hemisphere. This provides a flow amenable to analysis and experiment. The experimental results of Reference (3) indicate that at angular locations up to 75 degrees from the stagnation point, the static pressure on the upstream surface of the concave hemisphere is equal to the total pressure. This means that there is practically no flow near and parallel to the surface of the hemisphere except near the edge. Of course, in supersonic flow, a normal shock would stand ahead of the hemisphere and this would produce a completely subsonic flow regime inside of the concave hemisphere. In the absence of any chute porosity, the pressure on the upstream side of the chute is closely approximated by the total pressure behind the normal shock. In determining the pressure on the rearward (downstream) face of the chute, we are led to a base prossure phenomena described by H. H. Korst (4).

The discussion in the previous paragraph illustrates a technique for computing the pressures and hence the pressure ratio across a chute with no porosity. The analysis for the base pressure problem has been extended to the case of flow through the chute with small momentum only.

Since this last condition is rarely met in the case of practical parachute configurations, the pressure ratio across the chute openings must be found from experiment.

#### B. Small Scale Phenomena

A high temperature, high density flow is produced inside the canopy. This flow passes through the individual openings of the mesh. Heat is transferred from the hot gases to the mesh elements. Therefore, it is the distribution of heat flux to the surfaces of a mesh element which is of primary importance. The element is bounded on each side by an opening (slot) through which the oncoming flow passes. The typical ribbon (slat) may be considered as a flat plate aligned normal to the flow. The approaching flow may or may not separate upstream of the ribbon. This process has not been clearly defined. The flow passing through the slots exhibits properties which depend upon the overall applied pressure ratio. In most flight applications, the applied pressure ratio will be such that the flow in the slot may be considered as a sonic flow. Additional energy is available for further expansion of the stream as it emerges from the slot such that localized regions of supersonic flow will occur downstream of the slot. Between the supersonic jets emerging from the slot and the rearward facing wall of the ribbon, two regions are found. The first is a conventional free-shear layer in which the streamwise component of velocity diminishes from the value found in the jet to a nearzero condition. Adjacent to the shear layer there exists a small region of reverse flow. There is a circulating vortex in this region. The local pressure in the separation bubble is determined by the local base pressure phenomena (the flow issuing from the slot). The mean near-wake pressure which exists further downstream is determined by the gross geometry and the freestream Mach number. These two pressures are probably not equal.

Therefore, further recompression exists downstream of the jets issuing from the individual slots. The local base pressure behind an individual ribbon is therefore determined by the slot pressure ratio and the recompression process in the shear layers. a de son una se su an san ta menundan menunda serviciona. Esta de una destructura de son a su a su a su a su a

The distribution of heat flux over the surface of a single ribbon is of primary importance. A model which applies to the general heat exchange process between the shear layers and the rearward facing wall of the ribbon has been proposed by Korst (4) and Chapman (5). Related experiments are discussed in References (6) and (7).

Considering a single ribbon in the absence of adjacent ribbons, the heat flux increases from the "apparent" stagnation point value (at the center of the ribbon) to higher values toward the outer edge of the ribbon, according to laminar analysis. Experimental evidence (8) covering the forward face of such a ribbon confirms this distribution of heat flux and in addition, the variation of heat flux with pressure level (for a fixed velocity gradient). When several ribbons are grouped together in a manner simulating a ribbon parachute, the heat flux distribution on the frontfacing surface of a typical ribbon is influenced by the presence of the adjacent ribbons (2). The heat flux also increases at locations away from the stagnation point but at a rate somewhat faster than a single ribbon. The increased heat flux near the edge of the ribbon appears to be due to a diminution in the thickness of the viscous layer adjacent to the ribbon slot. This diminution is produced by the interaction of the slot flow with the ribbon boundary layer.

Recent experiments (6,7) suggest that adjacent to the separation bubble, a laminar, boundary-layer-like flow exists along the rear surface and this serves as the major barrier to the exchange of energy between

the freestream and the surface. In the case of a flat plate aligned normal to the flow, this thin film exhibits the properties of a stagnation-point boundary layer of the laminar type. The heat transfer processes along the forward and rearward faces of the ribbon appear to be governed by a similar mechanism.

Experimentally (7), the magnitude of the heat fluxes to the forward face are found to be considerably larger than those of the rearward face. This is primarily due to the significant difference in pressure level which occurs between the front and rear surfaces. The specific value of the ratio of heat fluxes on the forward and rearward surfaces varies with the freestream unit Reynolds number since base pressure phenomena depend on the character of the shear layer (laminar, transitional or turbulent).

The greatest source of uncertainty in engineering calculations of the energy exchange process to the mesh elements lies in the determination of the convective heat flux as characterized by a heat transfer parameter Nu. In the present instance the heat transfer parameter is a function of Reynolds number,  $\text{Re}^{*}$ , and the pressure ratio across the ribbon,  $P_1/P_2$ . The inter-relationships between Nu,  $\text{Re}^{*}$ , and  $P_1/P_2$  are sufficiently complex that they must be determined experimentally. It is convenient to define a Reynolds number based on the velocity and flow properties in the sonic orifice and the slat width

$$\operatorname{Re}_{D}^{*} = \frac{\rho^{*} a^{*} b}{\mu^{*}}$$
(1)

In the flight case the static temperature  $T_{\infty}$  and pressure  $p_{\infty}$  are determined by the flight altitude. A total pressure  $p_{\alpha}$  and temperature  $T_{\alpha}$  are determined once the flight Mach number is prescribed. Since the bow

shock is assumed to be normal, the total pressure behind the normal shock  $p_0^{\dagger}$  (inside of the canopy) is determined from  $p_0$  and  $M_{00}$ .<sup>4</sup> The total density, behind the bow shock, is computed from  $p_0^{\dagger}$ ,  $T_0$  and the proper equation of state. Finally, the sonic density and speed are determined from an isentropic expanison from  $p_0^{\dagger}$ ,  $T_0$ , to  $p^*$  and  $T^*$ . The superscript \* refers to the slot condition where a sonic speed exists for supercritical pressure ratios. The viscosity  $\mu^*$  is a known function of the temperature  $T^*$ .

The heat transfer parameter Nu is based on the stagnation conditions of the approaching flow and relates the wall heat flux to the difference between the wall temperature  $T_w$  and the adiabatic wall temperature  $T_{aw}$ .

$$Nu = \frac{hD}{k_o} = \frac{q}{T_{aw} - T_w} \cdot \frac{D}{k_o}$$
(2)

Notice that  $k_{\substack{O}}$  is the thermal conductivity of the air at the stagnation temperature.

## 11. EXPERIMENTAL EQUIPMENT AND PROCEDURES

A. Facility

The experimental facility used in the present experiments appears in the photograph of the experimental setup, Figure 2, and is also sketched in Figure 3. This facility is located at the University of Minnesota's Resemburnt Research Center. Prior to modification, the wind tunnel was a conventional blowdown supersonic windtunnel (9). The 6 x 12-inch supersonic windtunnel was modified by removing the supersonic nozzle blocks and fabricating a new 6 x 8-inch subsonic test section. A quick-acting DeZurik valve

The present experimental procedure is to simulate the subsonic flow conditions behind the bow shock. The total pressure behind the normal shock is preperly simulated by the windtunnel stagnation pressure (see Section IIA).

was installed in the 6-inch inlet pipe. The opening time of this valve is slightly less than one second, which is of importance when transient heat transfer measurements are made. A series of five perforated plates were placed at ll-inch intervals inside the 18-inch diameter stilling chamber and a 16-mesh screen was inserted between the flanges at the downstream end of this chamber to even out the flow. The plates and screen had a porosity of about 54 percent. Tests reported by Baines and Peterson (10) indicated that this is an optimum porosity for flattening out non-uniform velocity profiles.

A short round-to-rectangular contraction with an area ratio of 3.2 followed the stilling chamber, and the supersonic nozzle blocks normally were installed immediately downstream. These blocks were replaced by a pair of two-dimensional subsonic contraction blocks with a contraction ratio of 1.5. The contraction contours (cubical arcs) were determined from the data given by Rouse and Hasson (11) on a cavitation prevention basis. The second contraction provided an additional acceleration of the flow to 134 feet per second. It also served the purpose of reducing the nozzle boundary layer thickness.

The compressed air system consists of two high-pressure compressors, air storage tanks, a dryer, and associated valving and piping. One compressor is a two-stage unit, rated at 250 cfm at 600 psig and powered by a 100 h.p. electric motor. The other is a three-stage compressor, rated at 195 cfm at 1500 psig, and driven by a 50 h.p. electric motor. The compressors pressurize a storage volume of 1460 cubic feet to 250 psia (18 atmospheres). The air is dried to a dew point of -40°F prior to storage.

Downstream of the test section the air may be exhausted either to the atmosphere or to multiple vacuum tanks whose total capacity is 22,750 cubic feet. The vacuum system was not used for these studies. Only atmospheric exhaust was employed.

## B. The Experimental Model

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The test model was mounted two nozzle heights downstream of the nozzle tangency point (see Figure 3). The model consisted of three slats - each 2.1-inches high, 6-inches wide and 0.312-inch thick (see Figures 4 and 5). The slats were mounted in such a way that they resemble the array of ribbons in a ribbon parachute. A single ribbon spacing of 0.537-inch was used. This applies to the two center slots. The outer two slots were 0.337-inch. This value was obtained by selecting a half-slot height plus a nozzle displacement thickness correction. A single geometric porosity (open-to-total area) of 20.5 percent was examined<sup>\*</sup>. This porosity was selected since it closely matched the design throat size of the tunnel when operated supersonically; i.e., design subsonic and supersonic mass flows were identical.

At the maximum upstream pressure, the aerodynamic loading was approximately 200 pounds per square inch - or a total loading per slat of approximately one ton. The test slats had to be quite husky to withstand this loading. The three slats were cantilevered from aluminum "windows" on each end as may be observed in Figure 4. Optical windows were embedded in the aluminum windows for shadowgraph/schlieren observations of the slot and shear layer flows. Structural and packaging problems limited the field

Geometric porosity was systematically varied in Reference (2) from 20 percent to 84 percent. Porosity was demonstrated to be an unimportant parameter in determining the heat transfer processes in a subsonic ribbon parachute. This conclusion is undoubtedly still true in supersonic flow as long as the shock remains ahead of the entire parachute entrance.

of view to a 4-inch diameter circle located slightly downstream of the center slat. Two views of the ribbon parachute model, as installed in the wind tunnel, are shown as Figures 4a and 4b. Certain instrumentation details are also visible in these Figures although the reader is referred to Figure 5 for additional construction and instrumentation details.

For structural reasons, only one side of the ribbon was instrumented. The ribbon orientation was fully reversible. The basic structure of the ribbon was a solid bar of type 304 stainless steel. Chambers or compartments were milled in the bar to accept the instrumentation leads and to provide an air gap element of insulation between the forward and rearwardfacing surfaces of the ribbons. A removable constant-thickness, stainlesssteel, instrumentation-plate was screwed and potted to the main load bearing structure.

Eleven, 36-gauge, calibrated iron-constantan thermocouples were cemented at regular intervals in small holes drilled in the internal face of the instrumentation plate (see Figure 5). A minimum quantity of copper oxide cement was used in the installation. Small rectangular grooves, 0.025-inch deep and 0.040-inch wide, were milled in the stainless steel instrumentation plate. These grooves were filled with Resiweld epoxy cement and the epoxy was shaved flush. Two additional grooves, visible in Figure 4, were provided on the exposed face of the instrumentation plate. These grooves blocked the conductive heat flux by reducing the effective thermal conductivity of the surface material.

Two small tab elements, which covered a portion of the slot region, were brazed to the edge of the main instrumentation plate. The tabs and the main plate were of identical material and of equal thickness. A single

thermocouple was installed in the center of the rear face of each tab. Hollow pressure chambers were soldered to the sheltered face of the instrumentation plate. The pressure taps were drilled (d = 0.020-inch) through the plate into the chambers. A typical pressure tap installation is shown in Figure 5.

### III. EXPERIMENTAL STUDIES

## A. Uniformity of Approach Flow

As the airflow enters the wind tunnel stagnation chamber, it undergoes a sharp 90 degree turn (see Figures 2 and 3). The perforated plates and the screen were installed to remove any resulting nonuniformities. A 15-tube velocity survey rake, Figure 7, was fabricated to sense the uniformity of the approaching flow velocity. The test ribbon assembly was moved downstream to the last window location." The velocity survey rake was installed in the abandoned test plane. Runs were carried out at upstream pressures of 104 and 74 psia. These pressures exceeded the limits of available manometric instrumentation. A special manometer, visible in Figure 2, was constructed using high pressure, translucent plastic tubing. Water colored with food dye was used as manometer fluid. The specific gravity of this combination, as measured by a hydrometer, was C.999 at 77°F. A great deal of difficulty was encountered in accurately measuring the differences in impact pressure. For example, at a stagnation pressure of 74 psia, a typical difference in impact pressures was 1/4-inch of water (0.01 psia). The combined effects of high pressure level (74 psia), low pressure difference (0.01 psia), short

<sup>\*</sup> 

This was necessary since the test ribbons provide the choking mechanism required to establish a fixed value of the approach velocity.

wind tunnel running time (30 to 50 seconds), and the various response rates of the individual tubes of the rake, were such that, initially, the manometer board was emptied of fluid on nearly every run. The response problem was examined in bench tests in which the rake-manometer combination was connected to a pressure manifold to which a 100 psia test pressure could be suddenly applied. Satisfactory pressure readings were obtained by measuring the pressure differences between tubes of nearly equal response rates.

The approach flow velocity distribution data are summarized in Figure 8. All velocities are within one percent of the centerline velocity with the exception of the four points taken near the nozzle walls. These latter points all yield low indicated velocities which are undoubtedly due to the nozzle boundary layers. The average approach velocity was found to be 134 feet per second. The uniformity of the approach flow seemed to be within tolerable limits.

## B. Ribbon Pressure Ratios

The pressure ratios applied across the ribbon elements are presented in Figures 9 and 10 as a function of the slot sonic Reynolds number  $\operatorname{Re}_{n}^{\pi}$ . This quantity is defined as (12)

$$Re_{D}^{*} = \frac{\rho^{*}a^{*}D}{\mu^{*}} = \frac{\rho^{*}}{\rho_{0}} \frac{\rho_{0}\sqrt{\sqrt{8}RT^{*}}}{\frac{3/2}{2.270T^{*}} \times 10^{-8}}$$
(3)
$$Re_{D}^{*} = 5.49 \times 10^{4} P_{1} \text{ (psia)}$$
(4)

(4)

or

for a staggation temperature of 70°F and a ribbon width of 2.1-inches. The operating range of the wind tunnel, as determined by a useful running time of 30 seconds, is  $P_1 = 20 - 140$  psia. Two downstream pressures were measured for reference. The first,  $P_2$ , is the pressure measured at the downstream stagnation point of the ribbon. The second,  $P_{exit}$ , was measured using a wall static pressure tap installed in the centerline of the last window location (see Figure 3).  $P_{exit}$  should correspond to the pressure p measured properly on an actual parachute. This occurs several ribbon widths downstream of a ribbon element. Since the wind tunnel discharges into the atmosphere, at low flow rates P<sub>exit</sub> is nearly atmospheric. A sonic or critical pressure ratio is approximately 2. Only the first two points on the left side of Figure 9 are subcritical. All others are supercritical. This point is clear in Figure 10. A comparison of Figures 6, 9, and 10 is quite informative. The critical condition occurs between photo b and photo c of Figure 6. The jets from the two slots diverge as the upstream pressure (and the pressure ratio) is increased. The two diverging jets most at an  $extsf{Re}_D^{ imes}$  of approvimately 3.5 million. No further jet expansion is possible since the jet flow completely fills the champel downstream of the ribbons. Therefore the pattern becomes stable; i.e., insensitive to further increases in the upstream pressure  $P_1$ . The pressure ratio  $P_1/P_{exit}$ remains constant. The ribbon porosity, open-to-total area, is 20.5 percent. This produces a geometric area ratio of 4.88. Expanding onedimensionally, this generates a downstream Mach number of 3.15, and a stagnation-to-static pressure ratio of 46. Actually, the shear layers occupy a portion of the flow area downstream of the ribbons. The measured pressure ratio,  $P_1/P_{exit}$ , is 26, which yields an average downstream Bach number of 2.78.

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At low Re<sup>\*</sup><sub>D</sub>, the discrepancy between P<sub>2</sub> and P<sub>exit</sub> is a base flow phenomenon. Consider the vertical dashed lines in Figures 9 and 10 at Re<sup>\*</sup><sub>D</sub> = 3.3 x 10<sup>6</sup> (photo c of Figure 6). The jet flow expands to a Mach number of approximately 2.5 and then undergoes a shock recompression<sup>\*</sup> to P<sub>exit</sub>. According to Figure 9, P<sub>2</sub>/P<sub>exit</sub> = 2.8/12 = 0.23. The predicted value, according to the base pressure theory of Korst (4), is 0.24.

At large values of  $\operatorname{Re}_{D}^{*}$ , the jets completely fill the duct, the flows are parallel and exhibit the conventional shock diamond pattern. Apparently this pattern continues for some distance down the duct. Beyond  $\operatorname{Re}_{D}^{*} = l_{+} \times 10^{6}$ ,  $P_{exit}$  is less than  $P_{2}$ .

One important conclusion to be drawn from Figure 10 is that the \*ribbon pressure ratio is constant at a value of approximately 26 (depending on the definition) for slot sonic Reynolds numbers greater than 4 x 10<sup>6</sup>. This result applies to the case of atmospheric discharge. In another series of tests,  $P_{exit}$  was increased from subatmospheric values to progressively larger values by covering the exhaust flange with stacked layers of perforated plates. In this manner,  $P_1/P_{exit}$  was varied from 5 to 26 at a single  $Re_D^*$  of 6.3 x 10<sup>6</sup>. These latter studies will be discussed in Section D.2 (b).

Referring again to Figures 9 and 10, it is necessary to point out that the pressure ratio remains fixed for  $\operatorname{Re}_{D}^{*} > 4 \ge 10^{6}$ . Any heat transfer trends which occur at  $\operatorname{Re}_{D}^{*} > 4 \ge 10^{6}$  are truly due to Reynolds number and not due to pressure ratio.

The phenomena observed in Figures 6, 9, and 10 will occur on actual ribbon parachutes. The Reynolds numbers at which the several events would occur are not necessarily related to the present values of  $\operatorname{Re}_{D}^{*}$ .

The shock is a normal shock in photo c of Figure 6. This quickly reverts to the weak shock system shown in photo f.

## C. Ribbon Surface Pressure Distribution

The front surface and rearward surface wall static pressure distributions were obtained using the static pressure taps visible in Figure 5. The results, plotted in Figure 11, present a local pressure at location x divided by the stagnation pressure, at location x = 0. R is one-half of the slat height. Notice that the pressures were measured along two vertical lines - alternate points belong to different spanwise stations. The data was taken at small values of x/R in view of the anticipated correlation of results with stagnation flows. The point x = 0 represents the geometric centerline of the ribbon. For supercritical pressure ratios, the pressures along both the front and back surfaces reach maximum values near the geometric centerline<sup>\*</sup>. Pressures along the front surface are considerably more uniform than those along the rear surface<sup>\*\*</sup>.

The actual location of the stagnation point was obtained from large scale plots of the pressure distributions. This data is summarized in Figure 12. The apparent stagnation point nearly always fell below the geometric centerline for both the upstream and downstream surfaces. The average displacement (0.06-inch) is not large when one considers the internal diameter of a pressure tap is approximately 0.03-inch. It was not possible to move the apparent stagnation point closer to the geometric

The single exception occurs along the rear face at a subcritical pressure ratio. The application of a stagnation point model to the rear surface does not apply at subcritical pressure ratios.

The ribbons were of finite thickness. The static pressure taps installed in the center of the slot width indicated local Mach numbers well in excess of one. This implies that the sonic line lies near the upstream face of the ribbon. A typical value is  $p_{slot}/p_1 \approx 0.22$  when  $P_1 \approx 165$ psia,  $\text{Re}_n^2 \approx 8.5 \times 10^6$ .

centerline by a simple rotation of the ribbon. Apparently this slight flow abnormality is a property of the facility. By assuming that the measured pressures are constant across the thickness of the boundary layer, and that the flow outside of the boundary layer expands isentropically from  $p_{stag}$  to  $p_x$ , the local velocities just outside of the boundary layer may be determined. This data is presented in Figure 13. Of primary importance in this figure is the fact that both the upstream and downstream velocities grow linearly with distance from the stagnation point. This phenomena is characteristic of stagnation flows and is a familiar result for the upstream surface. Figure 13 presents the strongest evidence for considering the flow adjacent to the downstream surface as a stagnation flow - recalling that this occurs only when super-critical pressure ratios are involved.

Since the velocities outside of the boundary layer grow linearly with distance, the velocity gradient may be computed. These results are presented in Figure 14<sup> $\times$ </sup>. Two values are given at each Re<sup>\*</sup><sub>D</sub> for both the forward and rearward surfaces. The asymmetry between the upper and lower values is undoubtedly due to the stagnation point shifts summarized in Figure 12.

The upstream surface velocity gradient is independent of Reynolds number for supercritical pressure ratios. For the fully developed jet flows ( $\operatorname{Re}_{D}^{*} \approx 4 \ge 10^{6}$ ) the downstream surface velocity gradient decreases with keynolds number. Over the narrow range 3.5  $\ge 10^{6} \leqslant \operatorname{Re}_{D}^{*} \leqslant 8.5 \ge 10^{6}$ ,

$$\sqrt{C} = \sqrt{\frac{dU_{\delta}}{dx}} = \text{constant } \operatorname{Re}_{D}^{2} = \text{constant } (P_{2})$$
 (5)

Actually the square root of the velocity gradient is plotted since this quantity is of importance in stagnation point heat transfer calculations.

The measured upstream surface stagnation point velocity gradients may be compared with analytical predictions. For flow over blunt bodies, the first term of the Taylor series expansion for the surface velocity is the linear relation

$$U_{\mathbf{g}} = C\mathbf{x}, \tag{6}$$

where C is the local velocity gradient-external to the boundary layer. For reference, the stagnation point velocity gradient is expressed by

$$C = \frac{\beta U_{\infty}}{R}$$
(7)

where  $U_{co}$  is the subsonic velocity approaching the body and R is the body radius.  $\beta$  is a constant depending on body geometry. The following table illustrates a few numerical values of  $\beta$ .

Using an approach velocity of 134 feet per second, a body radius of  $\frac{1.05}{12}$  feet, and a  $\beta$  of 2 yields

$$\sqrt{C = \sqrt{\frac{\beta U_{co}}{R}} = \sqrt{\frac{(2)(134)}{\frac{1.05}{12}}} = 55 \text{ sec}^{-1/2},$$

a value which is 24 percent larger than the measured value.

Methods for predicting the maximum recirculation zone velocity  $(U_b \text{ for the rear face})$  are being developed. For the present experimental conditions, reference (7) gives

$$2\left(\frac{u_{\rm b}}{u_{\rm j}}\right)\left(\frac{\rho_{\rm b}}{\rho_{\rm j}}\right)\sigma\tan\alpha = \frac{1}{2} \tag{8}$$

where

σ

- U<sub>b</sub> is the mean recirculation velocity
- is the mean jet velocity downstream of the slot at the maximum jet width = 2000 ft/sec υj
- Pb
- is the mean recirculation zone convergence  $U_j, \frac{\rho_j}{\rho_b} = \frac{T_b}{T_j} = \frac{T_b}{T_j}, \frac{T_{oj}}{\frac{T_j}{f(M_j)}}$  $\rho_{\rm d}$

α is the jet expansion half-angle,  $\tan \alpha = 0.2$ 

ing the jot mixing layer spreading factor, 20

Substituting these values into Equation 3.6 yields

$$U_{b} = 280$$
 for per second

$$\sqrt{C} = \sqrt{\frac{(2)(280)}{\frac{1.05}{12}}} = 81 \text{ sec}^{-1/2}.$$

- D. Heat Transfer Measurements
- 1. Forward -Facing Surface
  - (a) Recovery Temperature Distribution

The 30-50 second wind tunnel running time did not permit a standard "run-to-recovery" which normally requires 30 to h5 minutes. Extrapolation techniques had to be adopted. Two tunnel runs were made to find the one thermoeouple of the seven installed in the stagnation temporature rake which responded closest to the average of the seven. Four runs were then made to determine the distribution of recovery temperatures. For those runs the model was allowed to respond thermally and to approach the adjubatic condition. The indicated model temperatures  $\mathrm{T_i}$  and tunnel total temperatures  $\mathrm{T_o}$  were measured as a function of time. The extrapolations to zero heat transfer were made by plotting  $T_i/T_o$  versus  $1/\tau$  and examining the curve for the limit as  $\tau$  increases. The extrapolations never involved a temperature change of more than 2°F from the last measured value. The upstream surface recovery temperature ratios are given in Figure 15. At the stagnation point, x/R = 0, the recovery temperature should equal the freestream total temperature at these low temperature levels. This is not always the case (see Figure 15, x/R = 0), a phenomena undoubtedly due to thermal conduction in the surface of the model. A one percent change in  $T_i/T_o$  corresponds to a 5.4 degree Fahrenheit change in the indicated recovery temperature. The relatively low recovery temperatures in the slot reflect the large velocities that exist there. It is important to note that the equilibrium temperatures in the slot are lower than at the stagnation point. The steady state operational temperature of a parachute is determined by the conditions at the stagnation point and not at the slot".

(b) <u>Heat Transfer Runs</u>

The general heat transfor experimental technique is described in detail in Appendix A. The technique consisted of precooling the model by packing dry ice around the ribbons and waiting for 10 to 15 minutes until the surface temperature was  $-108 \stackrel{1}{=} 1^{\circ}F$ . The tunnel was started rapidly

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In Section 2, the discussion of Figure 28 points out that the heat transfer coefficients in the slot are 6 or 7 times those at the stagnation point. Therefore, <u>transfert operational temperatures</u> are determined by <u>conditions</u> in the slot.

(in less than 1 second after the initiation of the valve actuator<sup>\*</sup>). The dry ice was blasted off by the air stream. The model heated up under the direct action of both forced convection and the heat capacity of the instrumented skin of the model. Heat transfer coefficients were calculated for several times using Equation A-14 of Appendix A. The heat transfer coefficients were extrapolated to zero time (a uniform wall temperature condition) ignoring data taken in the first 1-1/2 seconds. Model thermal symmetry was verified such that only one<sup>4</sup> half of the central ribbon was extensively studied. The stagnation point shifts, observed by means of the surface pressure distributions, were also clear in temperature distribution plots made at several time conditions. The reader is again referred to Appendix A where a sample run is illustrated and the various steps in the data reduction process are illustrated. The dimensional upstream stagnation point heat transfer coefficients are presented in Figure 16. The data was taken for Reynolds numbers as high as ten times those previously obtained  $(10^7)$ . The heat transfer coefficients increase with nearly the one-half power of the Reynolds number, a situation typical of laminar stagnation point boundary layers. The scatter in the data is approximately  $\frac{1}{2}$  10 percent. The heat transfer and

During the period after the upstream plug valve begins to open, there is a rapid compression of the air in the stagnation chamber which lasts about 1 second. The indicated stagnation temperature, as indicated by seven shielded 36-gauge iron-constantan thermocouples, rises sharply. After an indicated temperature rise of nearly 50°F, the temperature dropped to within a few degrees of room temperature and then decreased at a rate depending on the rate that mass was removed from the storage tanks. The initial transients (valve opening time, compression in the stagnation chamber, downstream pressure decrease to the desired subatmospheric level) were clearly visible in the data transes and were completed in 1-12 seconds (with the exception of the aforementioned stagnation temperature drop).

and pressure data at the upstream stagnation point are combined in a dimensionless group in Figure 17. The parameter

$$\frac{Nu_{w}}{\sqrt{Re_{w}}} = \frac{\frac{hx}{k_{w}}}{\sqrt{\frac{\rho_{w}U - x}{\mu_{w}}}} = \frac{\frac{h}{k_{w}}}{\sqrt{\frac{\rho_{w}}{\mu_{w}}}c}$$
(9)

is equal to 0.49 (13) for a laminar two-dimensional, stagnation point for a wall-to-stream temperature ratio of 0.7. Since the data was extrapolated to time  $\tau = 0$ , the dry ice temperature was used in evaluating the gas properties  $k_w$ ,  $\delta_w$ , and  $\mu_w$ . The density and velocity gradients were obtained from the pressure measurements, Figures 9 and 14, respectively.

The data agrees with stagnation point predictions for low Reynolds numbers  $(1 \ge 10^6 \le \text{Re}_D^* \le \text{r} \ge 10^6)$ . At higher Reynolds numbers the data falls 20-30 percent above the two-dimensional laminar stagnation point boundary layer analysis of Reshotko and Cohen (13). The applied pressure ratio increases with  $\text{Re}_D^*$  in Figure 17. The flagged points in Figure 17 represent data taken at  $\text{Re}_D^* = 6.3 \ge 10^6$  at several applied pressure ratios (also see Figure 27). As mentioned in Figure 3, for these tests with increased downstream pressure, a stacked set of perforated plates covered the exhaust opening. The downstream pressure,  $p_{\text{exit}}$ , was varied by changing the overlay of the perforated plates. The flagged points represent forward surface heat transfer measurements taken over a range of  $p_1/p_{\text{exit}}$  of 5 to 25.

The local distribution of heat transfer coefficients on the upstream side is presented in Figure 18. For easy reference, the local values were non-dimensionalized using the stagnation point values given in Figure 16. This was done in view of the overall aim of correlating all results with the stagnation point heat transfer which may be predicted with precision.

The data of Figure 18 has been corrected for stagnation point shift such that x represents the actual distance from the stagnation point and R, the distance from the true stagnation point to the slot. Some typical faired curves demonstrate that the local distributions are not universal but are strongly dependent on Reynolds number. Local heat transfer increases rapidly away from the stagnation point. Local heat transfer coefficients were observed which were eight times the stagnation point value. Further attempts to correlate local heat transfer coefficients with stagnation point values were abandoned at this point because of the uncertainties involved in the distributions. The curve labeled Re<sup>\*</sup><sub>D</sub> = 0.99 x 10<sup>6</sup> in Figure 18 represents a subcritical measurements reported in reference (2). Higher Reynolds number distributions generally yield higher local values relative to the stagnation point level.

The average upstream surface heat transfér coefficients are presented in Figure 19. This data was obtained by numerical integration of the local distributions illustrated in Figure 18. Notice that the average heat transfer coefficients increase linearly with Reynolds number. This is to be compared with the normal laminar square root dependence.

In Figure 20, the average Nussell numbers, defined as

$$Nu_{avg} = \frac{h_{avg}D}{k_{o}}$$
(10)

are plotted for the upstream side. The characteristic length in both Nussell and Reynolds numbers is the width of the ribbon. The characteristic velocity in the Reynolds number is the velocity in the slot. This enables a comparison of present heat transfer data with previous ribbon

parachute data (2) and data obtained on tube banks where it is customary to base the Reynolds number on the tube diameter and on the velocity in the narrowest cross section  $(1_{\rm h})$ . AND DE DESEMINE REALES DE LE COMPANY DE L

The subcritical data of Reference (2) is presented in Figure 20 to illustrate the overall Reynolds number dependence<sup>\*</sup>. The increase of the slope of the curve with higher Reynolds numbers, first observed here in Figure 17, has been observed by other investigators on circular cylinders and tube bundles (14, 15).

### 2. Rearward Facing Surface

### (a) <u>Recovery Temperature Distribution</u>

The recovery temperature data is summarized in Figure 21. The sharp rise in recovery temperature at  $\operatorname{Re}_D^* \approx 2.5 \ge 10^6$  may be correlated with the establishment of a completely supersonic jet flow downstream of the slots (see Figure 6).<sup>\*St</sup> The primary variation of the recovery temperature ratio,  $T_{aw}/T_0$  is with pressure ratio and not Reynolds number. For  $\operatorname{Re}_D^* \approx 4 \ge 10^6$  the constancy of  $T_{aw}/T_0$  reflects the constancy of pressure ratio (see Figure 10).

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The solid symbols in Figure 20 represent data taken in two different test facilities and using different experimental techniques. The agreement between the three experiments is reassuring.

At lew subsonic Reynolds numbers a vortex system is formed in the wakes behind obstacles. The phenomena is characterized by periodic vortex shedding. A suppression of the vortex sheet has been accomplished by a splitter plate which increases the temperature recovery factor  $r = (T_{aw} - T_{\delta})/(T_{o} - T_{\delta})$  from 0.1 to 0.8-0.9 (16). At transonic and

supersonic speeds where the vortex sheet disappears, the recovery factors are again 0.2-0.9. Shadowgraph observations of the supersonic case reveal a stable vortex pattern with no shedding. The expansion-shock pattern stabilizes the flow pattern according to the laws of forbidden signals.

#### (b) <u>Heat Transfer Runs</u>

The heat transfer coefficients measured at the downstream stagnation point are presented in Figure 22. A comparison of Figures 16 and 22 reveals that the downstream stagnation point heat transfer rates exceed the upstream stagnation point values for  $\operatorname{Re}_{D}^{\mathbb{Z}} < 6 \ge 10^{6}$ . This is rather surprising when one considers the downstream density is considerably smaller. The initial decrease in  $h_{\rm star}$  with  $Re_{\rm D}^{\star}$  is probably due to the density decrease (Figure 9). The sharp rise in the range 2 x  $10^6 \leq \mathrm{Re}_{\mathrm{p}}^* \leq 6 \times 10^6$  might possibly result from the increased regirculation velocitics (7). The fraction of the shear layer flow which is reversed decreases slightly as the pressure ratio (and the jet Mach number) is increased. Since the density in the recirculation zone decreases, increased recirculation zone velocities are required. Equation 3.5 relates a stagnation point velocity gradient to an approach velocity. On the other hand, the velocity gradient measurements on the rearward facing surface (see Figure 14) exhibit a decrease in magnitude as  $\operatorname{Re}_D^*$  is increased. Therefore, both the density and the velocity gradient are decreasing with increasing  $\operatorname{Re}_D^*$  while the heat transfer coefficient is increasing. These behavior patterns are not typical of ordinary stagnation flows.

The apparently sharp discontinuity in the results at  $\operatorname{Re}_{D}^{*} \approx 6 \times 10^{6}$  is not understood at the present time. No discontinuous process is observable in any of the photographs or graphs at this point. The downstream stagnation point heat transfer data are compared with two-dimensional laminar stagnation point analyses in Figure 23. The velocity gradient and density were obtained from Figures 9 and 14. Additional experimental results are precented for the condition of elevated exhaust

pressures. The results are not in complete agreement; either with each other or with laminar stagnation point analysis. A few of the points compare well with analysis while the rest do not. Two possible explanations are the increased turbulence level of the recirculating flow at high  $\operatorname{Re}_{D}^{*}$  and/or that the recirculating flow pulsates between several patterns.

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The distributions of heat transfer coefficients on the downstream side are given in Figure 24. The average or integrated values are presented in Figure 25. The combination of effects produce an average heat transfer coefficient which is independent of Reynolds number. The abnormalities in the stagnation point heat transfer variations with  ${\rm Re}_D^{\#}$  are masked. This fact, coupled with the complex distributions given in Figure  $2I_{+}$ , make it difficult to compare the behavior of the average and stagnation point heat transfer coefficients. A comparison of Figures 19 and 25 reveals that the downstream average heat transfer coefficients fall well below the corresponding upstream average values. This point is pursued in Figu. 26. Faired curves through the upstream and downstream average heat transfer coefficients are given over a wide Reynolds number range. At low Reynolds numbers the head transfor on the front side is greater than that on the back side. With increasing Reynolds number the heat flux to the back side increases more rapidly and for  $\operatorname{Re}_D^*$  - 50,000 it is as high as on the front side - and even higher as  $\operatorname{Re}^{\times}_D$  is increased further. This is a behavior pattern which agrees quantitatively with tubes and tube bundles in cross flow (16).

The present data continue the trends described above for subscritical pressure ratios<sup>\*</sup>. However, for critical pressure ratios, the downstream heat transfer becomes progressively less than the upstream. If the stagnation point analogy is valid, the ratio of upstream to downstream

The pressure ratios for the two lowest Reynolds number points of the present experiment are subcritical.

average heat transfer flux should vary directly with the square root of the density ratio or approximately with  $(p_1/p_2)^{1/2}$ . As an example choose  $\operatorname{Re}_{D}^{\times} = 8 \times 10^6$ . From Figure 10,  $(p_1/p_2)^{1/2} \approx 5$ . From Figures 19 and 25,  $h_{uv}/h_{down} = 375/120 \approx 3$ . Thus the proper pressure ratio trend is observed.

The problems are not completely understood, however. A summary of data taken at  $\text{Re}_{D}^{\#} = 6.3 \ \text{y} \ 10^{6}$ , with several exit pressures, is given in Figure 27. The upstream pressure is held constant in this figure while the downstream pressure is varied. The pressure ratios are all supercritical. The upstream heat transfer is sensibly independent of the downstream exit pressure. However, the downstream stagnation point heat transfer coefficient decreases as the exit pressure is increased. From Figure 10 it can be concluded that the variations in  $P_{\text{exit}}$  did not affect  $P_2$ .

The final figure, Figure 28, presents measurements of the slot heat transfer coefficient taken with the instrumented surface facing forward (bottom slot) and rearward (after rotation on the top slot).

The data displays the slight asymmetry found in all measurements and points out that the extreme heat flux rates occur in the slot. Undoubtedly the slot heating rates depend on the ribbon thickness or thickness ratio. Figures 15 and 28 summarize the slot heat transfer behavior as follows: (1) the heat transfer coefficients in the slot are the largest observed on the ribbon; and, (2) the equilibrium temperatures in the slot are the lowest observed on the ribbon. Slot heat transfer is of major importance in transient problems.

#### IV. CONCLUSIONS

Experiments have been performed on models representing the individual ribbons of a ribbon parachute. The recovery factor and heat transfer coefficient results obtained are valid in the continuum flow regime at transfer results extend the region of available experimental heat transfer data on ribbon parachutes to include  $\operatorname{Re}_{\mathrm{D}}^{*}$  of 3,000 to 10,000,000. The average measured Nusselt numbers are presented in Figure 26. It was found that the maximum local heat transfer coefficient exists at the edges of the ribbon. Also the maximum local values on both the upstream and downstream sides also occurred at the edges. The central regions of the upstream and downstream sides exhibited behavior similar to luminar stagnation point boundary layers. The relative minimum heat flux rates occurred at the stagnation point for each surface-flow orientation. Attempts to correlate the gross ribbon heat transfer characteristics with the upstream stagnation point heat transfer predictions were only partially successful.

Large differences in local heat transfer behavior were attributable to the onset of sonie flow in the slots between the ribbons. The applied pressure ratio was demonstrated to affect the ratio of average upstream to average downstream heat transfer coefficients.
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PHOTOGRAPH OF THE EXPERIMENTAL APPARATUS SHOWING THE PRESSURIZED SUBSONIC WIND TUNNEL FIGURE 2.

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(a) SIDE VIEW THROUGH WINDOW



(b) REAR VIEW LOOKING UPSTREAM

# FIGURE 4, RIBBON PARACHUTE MODEL INSTALLED IN THE WIND TUNNEL









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FIGURE 6. SHADOWGRAPH PHOTOGRAPHS OF THE FLOW DOWNSTREAM OF THE SLOTS



FIGURE 7. APPROACH FLOW VELOCITY DISTRIBUTION RAKE



FIGURE 8. UNIFORMITY OF APPROACH FLOW VELOCITIES



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FIGURE 9. VARIATION OF DOWNSTREAM PRESSURES WITH RIBBON REYNOLDS NUMBER



FIGURE 10. PRESSURE RATIOS ACROSS THE RIBBON VERSUS RIBBON REYNOLDS NUMBER



FIGURE 11. TYPICAL SURFACE PRESSURE DISTRIBUTIONS ON THE CENTER RIBBON

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FIGURE 13. RIBBON SURFACE VELOCITY DISTRIBUTIONS



FIGURE 14. STAGNATION POINT VELOCITY GRADIENTS CALCULATED FROM SURFACE STATIC PRESSURE MEASUREMENTS

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FIGURE 16. UPSTREAM STAGMATION POINT HEAT TRANSFER COEFFICIENTS



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FIGURE 18. DISTRIBUTION OF HEAT TRANSFER COEFFICIENTS ON THE UPSTREAM SIDE



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DOWNSTREAM SURFACE HEAT TRANSFER DISTRIBUTIONS



FIGURE 24. Continued







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FIGURE 27. VARIATION OF BOTH UPSTREAM AND DOWNSTREAM STAGNATION POINT HEAT TRANSFER RATES WITH THE PRESSURE RATIO ACROSS THE RIBBON



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## APPENDIX A

## 1. Transient Energy Balance

The transient technique relies on the heat capacity of the model skin for the experimental determination of convective heat flux. The general heat balance on a small element of surface must include

9 <sub>bl</sub> - the heat flux to/from the boundary layer	I
q <sub>st</sub> - the heat stored	II
q <sub>cond</sub> - the heat transferred within the skin by conduction	III
q <sub>rad</sub> - the heat exchange due to radiation to the wind tunnel (n) and to the model interior (m)	IV

 $q_{bl}$  is the term we wish to determine for comparison with analytical predictions. To generate a "good" experiment,  $q_{bl}$  should be the dominant



Figure 29 Energy Balance Notation

The general heat balance is written

term.

$$q_{bl}dA_{w} + (q_{cond}_{in} A_{din} - q_{cond}_{out} A_{din}) - q_{rad}dA_{w} = q_{st}dA_{w}$$
(11)

The temperature is assumed to be constant across the thickness of the surface - a condition referred to as the "thin-wall" assumption, i.e.,

$$T = \overline{T} = T_w$$
(12)

The heat conducted into an element of surface per unit time is

$$k_m \dot{A}_{din} \frac{dT_W}{dx}$$
, and that out is  $+k_m (A_d + \frac{dA_d}{dx} dx) (\frac{dT_W}{dx} + \frac{d^2 T_W}{dx^2} dx).$ 

Thus, the net rate of heat conducted into the element is

$$q_{\text{cond}_{\text{in}}} A_{\text{d}_{\text{in}}} - q_{\text{cond}_{\text{out}}} A_{\text{d}_{\text{out}}} - k_{\text{m}} A_{\text{d}} - \frac{d^2 T_{\text{w}}}{dx^2} - dx - k_{\text{m}} \frac{dA_{\text{d}}}{dx} - \frac{dT_{\text{w}}}{dx} dx$$
(13)

Also

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$$dA_{w} = 1 dx, A_{d} = t1; (t = 0.072-inch)$$
 (14)

The heat storage term may be written

$$q_{rx} dt_{w} = c_{p_{m}} dW \frac{dT_{w}}{dx}$$
(15)

where dW is the element of mass lying boneath the surface area  $\mathrm{d}\Lambda_W^*$  For a tabiform wall thickness

$$dW + \rho_{in} l dx t$$
 (16)

It is possible to obtain reasonable, but not precise, estimates of the radiation heat fluxes. Radiation losses to the test section walls and nozzle blocks must be considered. Radiant energy impinging on the rear face of the test surface which originates inside of the model (i.e., the support plate) is also of importance. The radiation heat exchange between the test surface and the wind tunnel nozzle - nozzle box combination is given by

$$Q_{w-n} = F_{w-n} \Lambda_w \in W_{w-n} \quad (T_w^{4} - T_n^{4})$$
(17)

The surface  $\Lambda_w$  is completely surrounded by the nozzle and is flat. It can be stated immediately that  $F_{w-n} = 1$ . The model surface area is small compared to the mean test surface - nozzle separation distance. The fraction of reflected radiation which returns to the model is small enough to be neglected. The interchange factor,  $\epsilon_{w-n}$ , is then

 $\epsilon_{w-n} = \epsilon_w \epsilon_n; \ \epsilon_w \approx 0.2\hbar, \ \epsilon_n \approx 0.5, \ \epsilon_{w-n} \approx 0.1$ 

The massiveness of the nozzle blocks and the inch thick test section walls allowed the assumption that the nozzle temperature  $T_n$  was equal to the room temperature during the brief 20 second runs.

The emissivity of the model surface was estimated to be  $0.2l_{\rm f}$  which is the value for iron at  $100^{\rm O}$ F freshly rubbed with emery paper. As the test surface is aerodynamically heated by the external flow, it receives varying amounts of radiant energy from the support structure. In this case, the radiation geometry consists of two parallel, closely-spaced flat plates. As before

$$Q_{w-m} = F_{w-m}A_{w} \in W_{w-m}(T_{w}^{L_{1}} - T_{m}^{L_{1}})$$
(18)

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Again the geometric factor  ${\rm F}_{\rm W-m}$  is unity. The interchange factor for two parallel walls is

$$\epsilon_{w-m} = \frac{1}{\frac{1}{\epsilon_w} + \frac{1}{\epsilon_m} - 1} , \quad \epsilon_w = \epsilon_m \approx 0.24$$
(19)

Combining all elements of the heat balance results in

In view of Equation 20, the following is a discussion of the experimental technique:

The model temperature was preset by surrounding the model with solid  $CO_2(T = -109.8^{\circ}F)$ , prior to starting the tunnel. These runs were made during a typical Minnesota summer day such that the tunnel temperature averaged  $80^{\circ}F$ . Therefore, the initial temperature potential (190°F) was the same for all tests. When the model temperatures were stable and uniform, the wind tunnel was started. The dry ice was removed by the

tunnel starting blast. Model temperatures increased with time as a result of the convective heating process. Each term in Equation 20 is time dependent. Initially only the heat storage term and the model-nozzle radiation terms contribute. As time proceeds, the other terms increase in importance. The equilibrium situation occurs when term II reduces to zero, and the model is at the adiabatic wall  $(T_{aw})$  condition.

The accuracy of the methods depends to a large extent on the frequency with which reliable thermocouple readings are recorded near the beginning of a run. Modification M24 of the Dymee DY-2010A Data Acquisition System provided 25 channel input continuously monitored at a precise rate of 5 channels per second. Taking data early in a run implies that no surface heat conduction corrections are necessary; a fact which greatly simplifies data reduction. The acrodynamic heat flux is then obtained for the isothermal surface temperature case, which is the most basic and easily specified case and the only case for which most heat transfer analyses apply.

Neglecting terms IT and  $\mathrm{IV}^{\times}$ , Equation 20 is written

$$q_{bl} = h(T_{aw} - T_w) = \rho_m c_{p_m} t_{dv} \frac{dT_w}{dv}$$
(21)

with h and  $T_{aw}$  held constant, and at  $\tau = 0$ ,  $T_w = T(0)$ , Equation 21 yields the particular integral

$$\frac{T_{aw} - T_w}{T_{aw} - T(0)} = e \frac{-hv}{\rho_m e_{p_m} t}$$
(22)

The maximum radiant heat flux was found to be 10  $Btu/ft^2$ -hr. Since the initial temperature was 190°F, the radiation heat transfer coefficient of 10/190 = 0.05, was at most, 1/4 percent of the convective heat transfer coefficient and could be safely neglected.

The left side of Equation 22 represents the ratio of the temperature potential remaining after  $\tau$  seconds to the initial temperature potential. For small values of time ( $\tau \approx 0$ ), Equation 23 may be written

$$\frac{T_{w} - T(0)}{T_{aw} - T(0)} = \frac{h\tau}{\rho_{m}c_{p_{m}}t}$$
(23)

which applies quite closely to the case of constant applied heat flux  $(q_{bl} = constant)$  and generates a constant rate of change of wall temperature with time.

Writing Equation 22 for two times,  $\tau_1$  and  $\tau_2$  yields

$$h = \frac{\rho_{m} c_{p_{m}}^{t}}{(\tau_{2} - \tau_{1})} \cdot \ln_{e} \frac{T_{aw} - T_{w_{1}}}{T_{aw} - T_{w_{2}}}$$
(24)

Equation 24 was used in the actual data reduction procedure since the quantities  $T_{w_1}$ ,  $T_{w_2}$ , and the time difference  $(\tau_2 - \tau_1)$ , are known somewhat more accurately than  $T_w$ , T(0) and the absolute time  $\tau_1$  - as required by Equation 22. The indicated heat transfer coefficients obtained using Equation 24 were extrapolated to the condition of constant surface temperature, ( $\tau = 0$ ), by plotting h versus the consumed temperature potential ratio ( $T_{ave}$ - T(0))/ ( $T_{aw}$  - T(0)). This ratio is equal to zero when  $\tau = 0$ .

The analysis of a sample run is presented in Figures 30 through 33. The temperature traces, the basic raw data, are given in Figure 30. The initial time,  $\tau = 0$ , is found by inspection. The variation of heat flux,  $q_{bl}$ , with surface location is directly proportional to the trace slopes since the product,  $\rho_m c_{p_m} t$ , is the same for all positions<sup>\*</sup>.

<sup>\*</sup>The specific heat does vary strongly with temperature. In Figure 31 heat capacity data for pure iron is presented which should apply closely to the present material, type 304 stainless steel.

The stagnation point heat transfer rates are seen to be the smallest of the group while the slot rates are the largest. Heat transfer coefficients obtained by repeated application of Equation 24 are given in Figure 32 together with a visual representation of the effects of extrapolating to a uniform wall temperature condition. Experimentally, there seems to be a time-temperature region in which conduction effects are small enough to be ignored. This region does not include the slot where large gradients in temperature are rapidly established.

Finally, Figure 33 illustrates the integration of the local heat transfer values - a process which yields the one average heat transfer coefficient for the run.


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FIGURE 30. TYPICAL TEMPERATURE TRACES

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FIGURE 31. CORRELATION OF HEAT CAPACITY DATA FOR IRON



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EIGURE 32. EXTRAPOLATION OF HEAT TRANSFER COEFFICIENTS TO A UNIFORM WALL TEMPERATURE CONDITION

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 $\operatorname{FIGURE}(33)$  . Integration of the local heat transfer values

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