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COUNTERMEASURE THREAT EMULATOR AND METHOD

STATEMENT OF THE GOVERNMENT INTEREST

The invention described herein may be manufactured and used by or for the Government of the United States of America for Governmental purposes without the payment of any royalties thereon or therefore.

BACKGROUND OF THE INVENTION

(1) Field of the Invention

The present invention relates generally to torpedo countermeasure devices and, more specifically, to programmable apparatus and methods for emulating torpedo countermeasure devices.

(2) Description of the Prior Art

Torpedo countermeasure (CM) devices are used on ships and submarines to confuse incoming torpedos. Therefore, a need exists for testing U.S. torpedoes with respect to foreign countermeasures to determine the efficacy of U.S. torpedoes when confronted by countermeasures. The current methodology of testing U.S. torpedoes is to use a U.S. countermeasure device
that is thought to be representative of a possible foreign CM
device, and use this U.S. countermeasure in field tests.
However, because prior art U.S. countermeasures may not be the
same as various foreign countermeasures, are highly limited in
the type of response which may be produced especially with
respect to the requirements of emulating foreign countermeasures,
and do not have related desirable features for this purpose as
discussed below, the testing may not be as complete as may be
desired.

The prior art discloses various types of training required
by submarines and the development of various types of acoustic
devices, but does not provide a solution to the above disclosed
problem and does not even appear to recognize this long felt
need. Representative patents in this area include the following:
U. S. Patent No. 2,887,671, issued May 19, 1959, to Burton
Frankel et al., discloses an invention pertaining to a sonar
device used in the training of sonar operators to acquaint them
with the characteristic sounds of a sonar ping returning from a
submarine. Claim 1 states: In a sonar device, an elongated hull
to be placed underwater and having a forward and an aft
transducer for receiving a sonar ping, comparing means mounted in
the hull for comparing the time relationship of arrival of a
given ping as received by the forward and aft transducers, means
connecting the forward and aft transducers to the comparing means, signal generating means connected to the comparing means for generating a signal having a characteristic which is a function of the relationship, and transmitting transducer means mounted on the elongated hull and connected to the signal generating means for transmitting the generated signal.

U. S. Patent No. 5,394,376, issued Feb. 28, 1995, to Laurence R. Riddle et al, discloses an apparatus for reducing acoustic radiation from an enclosure containing a fluid including one or more vibration sensors in communication with surfaces of the enclosure. The vibration sensors feed signals corresponding to detected vibrations in the surface to a radiation filter. The radiation filter assigns weights to the signals and generates a summation signal which is then input to a control unit, with the summation signal ideally representing only those vibrations that will actually radiate from the enclosure. The control unit uses a reference signal and the summation signal to calculate a cancellation waveform to offset the cause of the detected vibrations. The cancellation signal is input to a fluid displacement unit which applies pressure oscillations to the fluid corresponding to the cancellation waveform.

U. S. Patent No. 4,184,209, issued Jan. 15, 1980, to Ralph P. Crist, discloses a towed decoy system adapted to be towed from
a towing vessel, an electrically powered noisemaker, an
electrical tow cable attached to the noisemaker, a depressor
vane, a depressor cable connected to the depressor vane and to
the towing vessel, and means interconnecting the depressor cable
and the electrical tow cable at a point near the depressor vane,
the interconnecting means comprising a pair of cable grips
respectively attached at one end to adjacent sections of the
electrical tow cable and at their other ends to a snatch block
movably mounted on the depressor cable thereby providing slack in
the electrical tow cable, whereby the noisemaker is towed at a
depth not less than that of the point of attachment of the snatch
block to the depressor cable.

U. S. Patent No. 4,025,724, issued May 24, 1977, to Allen R.
Davidson, Jr. et al., discloses an array of independent sound
cancellation units arranged over a vibrating noise generating
surface. Each unit includes an arrangement of acoustic
transducers (sensors) positioned adjacent the surface to obtain
an electrical average of the local acoustic noise generated by a
predetermined zone of the surface. The summed average is changed
in phase and gain by an active filter whose output drives an
acoustic projector also positioned adjacent the surface and the
acoustic output of which sums with the original noise signal in
the acoustic far field, thus tending to cancel the noise. In
essence, each vibrating surface zone and its associated sound
cancellation unit tends to form an acoustic doublet. A signal
indicative of the projector output is used as a feedback signal,
with appropriate time delays, to cancel the effect of the
projected output signal being picked up by the unit's
transducers, and to cancel the effect of the output of other
projectors of the array.

R. Browning, discloses and describes an apparatus and method for
overcoming stroke limitations of moving coil reaction-mass
vibration dampers, by recovering armature stroke displacement.
The coil housing is selectively coupled or de-coupled to the
vibrating structure. If, when the armature reaches its travel
limit, sufficient damping energy has not been applied to the
structure, the coil-housing assembly is decoupled from the
structure while the armature is pulsed back to its zero
displacement position. The housing then is re-coupled to the
surface, having displaced some determinable distance from its
previous location relative to the surface. Additional armature
movement in the same direction as the previous armature stroke is
applied, thereby generating the needed additional damping force.
The resetting of the housing to its normal position vis-a-vis the
vibrating structure can occur at a selected time in the damping
force-generating cycle when reset does not impart an undesired reaction to the vibrating structure. In one implementation, a pair of moving-coil actuators counter-drive the vibrating structure; in another, a multiplicity of additional reaction-mass actuators are used.

U.S. Patent No. 5,341,343, issued Aug. 23, 1994, to Robert L. Aske, discloses an explosive actuated acoustic device which emits sound to be used in torpedo countermeasures. Numbered devices are delivered over an extended area and sink through the water. The devices are actuated at different times as they sink, to provide sound masking over an extended period of time. The devices also include safety devices which prevent premature actuation from jarring or jolting and from impact with the water.

U.S. Patent No. 5,117,401, issued May 26, 1992, to Paul L. Feintuch, discloses an active adaptive noise canceller that inserts delays in the weight update logic of an adaptive filter employed by the canceller to make the filter stable. It has been found that there is a great deal of flexibility regarding the selection of the delay values. This insensitivity permits designing the delays in advance and not having to adjust them to different situations as they change, thus no longer requiring a training mode. The canceller dramatically reduces the amount of hardware needed to perform active adaptive noise cancelling, and
eliminates the need for the training mode, which in some applications, including automobiles, for example, can be objectionable as the noise sources that are to be suppressed.

The above patents do not address or provide solutions to the problem of testing torpedoes with respect to various types of countermeasures. Consequently, it would be desirable to provide an in-water device that can emulate known characteristics of CM devices, both U.S. and foreign. It would be desirable for such a device to be reusable, either stationary or mobile, and suitable for both in-laboratory and in-water use. Moreover, it would be desirable to provide a system that is totally programmable and can be programmed to intercept and identify a threat waveform, and then respond in a totally programmable manner, including pre-programmed structured signals, broad band noise, narrow band noise, echo repeater mode, swept LFM mode, or any one of several possible randomly generated false alarm modes where the transmission is a modified replica of the intercepted threat waveform. Those skilled in the art will appreciate the present invention that addresses the above and other needs and problems.

SUMMARY OF THE INVENTION

Accordingly, it is an object of the present invention to provide a countermeasure threat emulator.
It is yet another object of the present invention to provide a means for testing domestic torpedoes against foreign countermeasures.

These and other objects, features, and advantages of the present invention will become apparent from the drawings, the descriptions given herein, and the appended claims.

In accordance with the present invention, a method is provided for testing a torpedo utilizing a countermeasure threat emulation system which comprises steps such as selectively programming the countermeasure threat emulation system for producing at least one of a plurality of foreign countermeasures chosen from a database of foreign countermeasures. The countermeasure threat emulation system is controlled to operate at a selected depth or range of depths in the water. The countermeasure threat emulation system may be stationary or mobile. A torpedo is launched for testing with the countermeasure threat emulation system.

The sounds produced by the torpedo may be analyzed with a neural network within the countermeasure threat emulation system. The analysis by the neural network results in an identification of the torpedo. A CPU within the countermeasure threat emulation system may be programmed to respond to the torpedo based on the identification so derived.
The countermeasure threat emulation system may preferably operate in duplex mode by simultaneously sending and receiving acoustic signals. A digital signal processing unit within the countermeasure threat emulation system may be used for selectively producing a large number of different types of signals including a wideband acoustic signal or a band limited acoustic signal.

The programmable countermeasure threat emulation system comprises a tubular housing suitable for launching from a submarine and a power supply within the tubular housing. The power supply includes controls for selectively operating remotely or operating connected to an external power source. A hovering system for the tubular housing is provided for controlling a water depth of the tubular housing. A transmitter which may be comprised of a transducer stack may be used for transmitting acoustic signals. A digital signal processing unit produces waveforms to be transmitted by the transmitter. A central processing unit is used for storing digital information related to one or more countermeasure threats and supplying the digital information to the digital signal processing unit. The system also comprises a database stored in a computer external to the housing which contains a plurality of foreign countermeasure threats. A plurality of field programmable gate arrays is
preferably provided for the digital signal processing unit so as to make this unit programmable. A signal conditioner is operable for converting a stream of digital signals into an analog signal for broadcast by the transmitter.

In operation, the method comprises maintaining a database having a plurality of foreign countermeasure threats. Data for at least one of the plurality of foreign countermeasure threats is downloaded into a computer within the countermeasure threat emulator. The countermeasure threat emulator is launched for underwater operation. An emulation of the respective foreign countermeasure threat is transmitted into water through an acoustic transducer. A receiver hydrophone is utilized in the countermeasure threat emulator for receiving acoustic signals produced by an incoming torpedo. The incoming torpedo is identified from the received acoustic signals by utilizing a neural network within the countermeasure threat emulator and responding to the incoming threat based on the identification and a preprogrammed response for the identification.

BRIEF DESCRIPTION OF THE DRAWINGS

A more complete understanding of the invention and many of the attendant advantages thereto will be readily appreciated as the same becomes better understood by reference to the following
detailed description when considered in conjunction with the accompanying drawings wherein corresponding reference characters indicate corresponding parts throughout the several views of the drawings and wherein:

FIG. 1 is a schematic representation of a countermeasure unit in accord with the present invention; and

FIG. 2 is a schematic block diagram of countermeasure electronics for the countermeasure unit of FIG. 1.

BRIEF DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring now to the drawings and, more particularly, to FIG. 1 there is shown a countermeasure threat emulator 10 in accord with the present invention. CM threat emulator 10 may be provided within a six inch CM housing or other size housing 12 so as to preferably be launchable/retrievable from a torpedo tube. CM threat emulator 10 includes countermeasure electronics unit 14 discussed hereinafter and shown in block diagram form in FIG. 2. CM threat emulator 10 is provided with hovering system 16 for controlling water depth, which may also be used in making CM threat emulator 10 mobile. While CM threat emulator 10 is preferably reuseable, one embodiment of CM threat emulator 10 may be made low enough in cost so as to be expendable by using, for instance, mostly salvaged components of existing countermeasure
devices. For remote operation, power source 18 may be used although when tethered to surface controls, CM threat emulator 10 can be operated using external power from external control 20. Power control electronics 19 can be provided to perform such functions as switching between power supply sources, recharging, and the like. Power supply 18 and/or power from external control 20 may be used to provide power to DC/DC converter 21 (see FIG. 2) for powering CM electronic unit 14.

Preferably, CM electronic unit 14 utilizes commercial off the shelf technology wherever possible. CM emulator electronics 14 may include up to four digital signal processors (DSP) 22, such as the Texas Instruments TMS320C40. In a preferred embodiment, the main software runs on four DSP processors. DSP processing unit 22 is interconnected with transducer interface 26 by high speed bus 24. Interface 26 preferably includes at least four analog channels in and four analog channels out. As well, interface 26 preferably includes at least sixteen channels of high speed digital input/output (TTL) for cooperation with high speed bus 24 and for use by signal conditioner and power amplifier 27. The analog channels may also be used in conjunction with signal conditioner and power amplifier 27. Signal conditioner/power amplifier 27 may be used to convert digital streams of TTL signals to analog sinusoidal waves for use
by a transducer stack such as transducer stack 30. Signal conditioner 27 therefore connects to one of several possible transducer stacks, or transmitters 30, such as an ADC MK2 array, an ADC MK3 array, or a BQR-7 spherical array.

Signal conditioner 27 also preferably connects to a receive hydrophone 28. Receive hydrophone 28 will serve to collect in-water data of incoming torpedo threats from the viewpoint of the countermeasure hydrophones. The data so collected and stored by CPU 34 will be used to enhance simulation and modeling efforts, and then verify the mathematics used in development of the other countermeasure techniques. Thus, the memory of CPU 34 may be downloaded into computer 32 for such analysis.

Electronics unit 14 including CPU 34 are totally programmable and can be programmed by external computer 32, such as a weapons control panel or laptop computer, to intercept and identify a threat waveform by means discussed hereinafter, and then respond in a totally programmable manner, including pre-programmed structured signals, broad band noise, narrow band noise, echo repeater mode, swept LFM mode, or any one of several possible randomly generated false alarm modes (where the transmission is a modified replica of the intercepted threat waveform).
In order for CM threat emulator 10 to be programmable, CM electronics unit 14 is therefore designed to be programmable. CM electronics unit 14 may be programmed to respond in any arbitrary fashion or with specific characteristics. CM electronics unit 14 can be programmed via an alterable and updateable database 35 to emulate a plurality of foreign CM waveforms and signal types as indicated by 36, 38, and 40. CM threat emulator 10 may also be used to imitate other countermeasure devices 41 such as various existing domestic countermeasure devices. The device requirements for the CM database 35 come from the MK2, MK3, and MK4 system specification documents, from available foreign documents, and from efforts to develop operating characteristics of rest of the world CM devices, and the like. Thus, the information for CM database 35 has been obtained, will be updated in the future, and is preferably maintained in one form as downloadable CM database 35 for use by CPU 34.

As indicated above, CM threat emulator 10 can be made to emulate mobile threat countermeasures as well as stationary ones. Preferably, CM threat emulator 10 can operate in full duplex mode, receiving transmissions from receive hydrophone 28 while broadcasting from transmitters 30. Depending on the selection of type of countermeasure to be emulated, CM threat emulator 10 can
be programmed to operate in either a wideband or band limited manner.

The processors provided in DSP processing unit 22 are preferably in a format that can be used to permit a wide array of different types of signals to be processed. Preferably, neural network 42, such as a Ni-1000 Recognition Accelerator Chip from Nestor and Intel is provided for pattern recognition of incoming threats so as to identify the particular threat. Neural network based processor 42 will be used for incorporation of research into classification of incoming torpedoes based on pattern recognition of acoustic signatures processed with advanced time frequency distribution and wavelet algorithms.

DSP processing unit 22 preferably includes field programmable gate arrays (FPGA) and flash memories for at least two purposes. One use will be in digital "glue logic" functions for consolidation of space and functional enhancement. Secondly, the FPGA's and flash memories may be used to provide reconfigurable DSP logic. FPGA technology can be used for construction of high speed digital signal processing logic. Additionally, the FPGA's are dynamically programmable, so the DSP processing elements can be re configured based on changing tactical information (for example, the FPGA's could be designed as a tunable digital filter, or as an iterative bank of filters),
or can possibly be reprogrammed by an advanced CM shipboard
launcher designed to use such flexibility.

The programmability of CM threat emulator 10 makes the
system virtual, giving the CM threat emulator 10 the ability to
emulate any CM device under software control. The bulk of the
processing and control software preferably running under the
Texas Instrument’s TMS320C40 digital signal processing chips may
be developed using the Pegasus Parallel Processing Design
Environment developed by Jovian Systems, Inc. The parallel C40
digital signal processor software development system may be used
to auto-generate C code suitable for use on a network of multiple
interconnect C40 modules using a graphical icon based
environment. The final product is multi-threaded and multi-
tasking executable code that can be easily distributed over the
multiple modules via the C40’s high speed communication ports.

In summary, a relatively low cost CM threat emulator 10 may
serve as a test platform for in-water testing of new concepts and
technology for next generation CM device development and as a low
cost test vehicle for U.S. Torpedo Programs requiring foreign CM
device acoustic signatures. The present invention takes
advantage of presently available information about foreign and
domestic torpedo countermeasure devices to provide the technology
for providing a virtual countermeasure concept. CM threat
emulator 10 is suitable for in-water use, where it will be designed to be deployed from both submarine and ship platforms, serving a dual role as a developmental platform for testing new concepts and technology. CM threat emulator 10 also acts as a low cost test vehicle for U.S. Torpedo Programs requiring foreign CM device acoustical signatures for high fidelity testing of U.S. Torpedoes.

Numerous variations of the above method are possible, some of which have already been described. Therefore, it will be understood that many additional changes in the details, materials, steps and arrangement of parts, which have been herein described and illustrated in order to explain the nature of the invention, may be made by those skilled in the art within the principle and scope of the invention.
COUNTERMEASURE THREAT EMULATOR AND METHOD

ABSTRACT OF THE DISCLOSURE

A system and method is disclosed for a countermeasure threat emulator. The countermeasure threat emulator is provided in a tubular housing that may be launched from a submarine or ship. The electronics of the countermeasure threat emulator include a CPU board for running software, communicating with a computer external to the tubular housing, and data recording. The computer external to the tubular housing preferably incorporates a database that includes data representative of a plurality of foreign countermeasures as well as domestic countermeasures. The data may be downloaded to the CPU board as well as updated for reprogramming of the CPU board. A digital signal processing board preferably utilizes a plurality of DSP processors for running the main software that is capable of producing a wide range of acoustic signal outputs. A neural network may be used for analyzing acoustic sounds from incoming threats for identification thereof and for subsequent notification to the CPU board for selection of a preprogrammed response. Power
amplifiers and filters are provided for converting digital
streams of digital signals to analog signals for transmission by
a transducer stack.