INTERFACING OF THE SILICON GRAPHICS NETWORKABLE FLIGHT SIMULATOR WITH SIMNET

Technical Report

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### Title

Interfacing of the Silicon Graphics Networkable Flight Simulator with SIMNET

### Abstract

One of the efforts of the Network & Communications Technology Research Lab is to interface dissimilar simulators in the "SIMNET World". As part of this effort we have networked (via ETHERNET) a flight simulation program running on a Silicon Graphics 4D70GT Workstation with the SIMNET M1 modules that are located in the IST Research Laboratory. Various steps were taken to achieve this task, and the keypoints are documented herein.

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Introduction

One of the efforts of the Network & Communications Technology Research Lab is to interface dissimilar simulators in the "SIMNET World". As part of this effort we have networked (via ETHERNET) a flight simulation program running on a Silicon Graphics 4D7CGT Workstation with the SIMNET M1 modules that are located in the IST Research Laboratory. Various steps were taken to achieve this task, and the keypoints are documented herein.

SIMNET Vehicle Appearance Protocol Data Unit (PDU)

Our first task was to gain a thorough understanding of the SIMNET Vehicle Appearance PDU. PDU's are data units which are exchanged between simulators. The Vehicle Appearance PDU's describe the visual appearance of a vehicle at the moment of broadcast. Each PDU is composed of a discrete number of fields. The fields for the SIMNET PDU's are shown below (byte length in brackets):

- SIMNET Package Header
  - ethernet destination [6]
  - ethernet source [6]
  - ethernet packet type [2]
  - user data length [2]

- Vehicle Appearance data fields [1512 - header size] (see appendix for description of Vehicle Appearance PDU fields)


Silicon Graphics (SG) "Dogfight" Flight Data

In this section we discuss certain characteristics of interest of the SG Networkable "Dogfight" Flight Simulation. These characteristics are the coordinate system, initialization, and vehicle orientation (attitude).

- Coordinate System: The origin of the SG Terrain Data Base is in the center of the runway. The X-axis points North, the Z-axis point West, and the Y-axis points opposite the direction of gravity (see Figure 1).
- **Initialization**: The SG airplane initializes on the taxi-way at $X = 850$, $Y = 0$, and $Z = -2050$ (feet). Air speed is zero.

- **SG Attitude Data**: In the SG simulation, the pitch, roll, and yaw of the vehicle are expressed as elevation, twist, and azimuth respectively. The conventions for these attitude angles are given in Figure 2 below.
SIMNET Characteristic Data:
The values of the SIMNET data base range from zero to 75,000 in the X and Y directions. All SIMNET distance values are in meters. The conventions for vehicle pitch, roll, and yaw are illustrated in Figure 3.

Silicon Graphics to SIMNET Conversion
The SG "Dogfight" PDU contains similar types of information as the SIMNET PDU. However, some calculations and transformations are required to convert the SG PDU information into SIMNET PDU format. Unlike SIMNET, the SG uses the angles of azimuth, elevation, and twist (yaw, pitch, roll) to describe the orientation of the airplane in free space. In order to interface the SG with the SIMNET, we needed a program which calculates the SIMNET required nine element (3 x 3) rotation matrix given these angles. The program which performs this calculation is provided as an attachment to this document.

The SG simulation uses feet as its distance unit of measure, whereas, SIMNET uses meters. Therefore, the conversion of feet to meters was another necessary transformation.

Translation of Silicon Graphics "Dogfight" PDU
We were able to translate the SG "Dogfight" PDU's by "stealing" packets from the ETHERNET via a PC/AT with an Excelan 205E ETHERNET board installed. The software written to perform this operation uses UDP/IP to capture the SG broadcast packets and saves them to a disk file. Information contained in the SG PDU was reformatted or translated into SIMNET type packets, and then retransmitted over the ETHERNET to the SIMNET M1 tank modules.

CONCLUSION
As a result from this task we were able to prove our capabilities of building a protocol translator using the resources that exist in the IST laboratory. These projects use a PC/AT-based platform that will translate or manipulate the ETHERNET packets allowing us to experiment with new implementations of SIMNET technology.
## APPENDIX A

**SIMNET Vehicle Appearance PDU**

<table>
<thead>
<tr>
<th>PDU Header</th>
<th>Simulation Protocol Header</th>
</tr>
</thead>
<tbody>
<tr>
<td>version</td>
<td>length</td>
</tr>
<tr>
<td>bits 1 thru 4</td>
<td>bits 5 thru 16</td>
</tr>
<tr>
<td>protocol</td>
<td>octet 2</td>
</tr>
<tr>
<td>kind</td>
<td>octet 3</td>
</tr>
<tr>
<td>exercise ID</td>
<td>octet 4</td>
</tr>
<tr>
<td>padding</td>
<td>octet 5</td>
</tr>
<tr>
<td>vehicle ID</td>
<td>octet 6</td>
</tr>
<tr>
<td></td>
<td>octet 7</td>
</tr>
</tbody>
</table>

| role         | battalion                 |
| octet 8      | octet 9                   |
| company      | octet 10                  |
| bumper       | octet 11                  |
| class        | octet 12                  |
| appearance   | octet 13                  |
|             | octet 14                  |

| rotation     | location                  |
| octet 15     | octet 16                  |
| octet 17     | octet 18                  |
| octet 19     | octet 20                  |
| octet 21     | octet 22                  |

| grid         | engine speed              |
| octet 23     | octet 24                  |
| octet 25     | octet 26                  |
| padding      | octet 27                  |

### STATIC CLASS VEHICLES

- padding
- octet 28

### SIMPLE CLASS VEHICLES

- padding
- velocity
- octet 28 | octet 29 | octet 30 | octet 31 | octet 32

### TANK CLASS VEHICLES

- padding
- velocity
- turret azimuth
- gun elevation
- octet 28 | octet 29 | octet 30 | octet 31 | octet 32 | octet 33 | octet 34 | octet 35
- gun elevation
- octet 36
APPENDIX B

Silicon Graphics "Dogfight" to SIMNET Interfacing Software
This file is the header file for the airplane running on the Silicon Graphics.

#define NAME_LENGTH 15
/*
#define MYPLANEID 16 */
#define ADJUSTX -850
#define ADJUSTZ 2050
#define AIRPORTX 40000.0
#define AIRPORTY 220.0
#define AIRPORTZ 30000.0 /*
#define F2M 3.281 */
#define F2M 5.0

struct plane {
    long planeid;
    char version; /* flight version */
    char cmd; /* type of packet */
    short type; /* plane type */
    short alive; /* alive */
    char myname[NAME_LENGTH+1];

    unsigned short status; /* for msgs these 2 shorts */
    unsigned short won; /* hold the plane id */
    unsigned short lost;

    float x; /* plane position */
    float y;
    float z;
    short azimuth;
    short elevation;
    short twist;

    short mstatus; /* missile data */
    float mx;
    float my;
    float mz;
    float last_mx;
    float last_my;
    float last_mz;
    long kill;
    float tps;
    int airspeed;
    int thrust;
    short wheels; /* wheel position */
    short elevator; /* elevator position */
    char mtype;
};

struct plane plane;
short port=0x140a; /* port address for udp/ip connection */
This file contains the C code to handle the airplane flying on the SG.

* Initialize a synchronous/blocking udp/ip connection for input */

sginitin()

    /* Check that the driver is loaded, and get our own ethernet MAC address from the EXOS board */
    if (!loaded()) errexit("driver NOT loaded");
    if (ipinfo(&opt) < 0) errexit("could not get own ethernet MAC address");
    memcpy(my_addr, opt.xo_eaddr, sizeof(my_addr));

    /* Display my address */
    fprintf(stderr, "my addr = %02x-%02x-%02x-%02x-%02x-%02x\n",
              my_addr[0], my_addr[1], my_addr[2],
              my_addr[3], my_addr[4], my_addr[5]);

    /* Open input disk file */
    diskfd = open(inputfile, FILEOFLAG, FILEPMODE);
    if (diskfd < 0) errexit("cannot open diskfile");
    fprintf(stderr, "disk file fd = %d\n", diskfd);

    /* UDP/IP specification */
    send_socket_sg.sin_port = htons(port);
    send_socket_sg.sin_addr.s_addr = 0x00000000;
    recv_socket_sg.sin_port = htons(port);
    recv_socket_sg.sin_addr.s_addr = 0xffffffff;

    /* Make a udp socket call */
    if ((netfdsg = socket(SOCK_DGRAM, (struct sockproto *) 0,
              &send_socket_sg, 0)) < 0) {
        fprintf(stderr, "ERRNO %d\n", errno);
        errexit("socket");
    }
    fprintf(stderr, "sg socket fd = %d\n", netfdsg);
    return(0);

    /* Read synchronous/blocking udp/ip packet */

sgreadin()

    int cnt;

    /* if ((cnt = soretceive(netfdsg, &recv_socket_sg, buf, sizeof(buf))) < 0)
        errexit("soretceive");
    fprintf(stderr, "read %d bytes from sg\n", cnt); */
    if ((cnt = read(diskfd, buf, 100)) < 0)
        errexit("read");
    /* fprintf(stderr, "read %d bytes from disk\n", cnt); */
    return(cnt);

* Close connection */

gfiniin()

    soclose(netfdsg);
int i, j;
union {
    char *tmpc;
    float *tmpf;
} tmp;
union {
    char *tmpc;
    short *tmps;
} tmps;

tmp.tmpf = &plane.x;  
swap4(tmp.tmpc);  
tmp.tmpf = &plane.y;  
swap4(tmp.tmpc);  
tmp.tmpf = &plane.z;  
swap4(tmp.tmpc);  
tmps.tmps = &plane.azimuth;  
swap2(tmps.tmpc);  
tmps.tmps = &plane.elevation;  
swap2(tmps.tmpc);  
tmps.tmps = &plane.twist;  
swap2(tmps.tmpc);  
}

/*@ Host order to network order transform */
hton_flight ()
{
int i, j;
union {
    char *tmpc;
    float *tmpf;
} tmp;
union {
    char *tmpc;
    short *tmps;
} tmps;

tmp.tmpf = &plane.x;  
swap4(tmp.tmpc);  
tmp.tmpf = &plane.y;  
swap4(tmp.tmpc);  
tmp.tmpf = &plane.z;  
swap4(tmp.tmpc);  
tmps.tmps = &plane.azimuth;  
swap2(tmps.tmpc);  
tmps.tmps = &plane.elevation;  
swap2(tmps.tmpc);  
tmps.tmps = &plane.twist;  
swap2(tmps.tmpc);  
}

/*@ This subroutine is here for documentation, it is on simnet.ccd */

swap4(char *ptr)
This subroutine is here for documentation, it is on simnet.ccd

swap2(char *ptr)
{
    char tmp;
    tmp = *ptr;
    *ptr = *(ptr+1);
    *(ptr+1) = tmp;
}

display_plane()
{
    fprintf(stderr, "plane id %ld\n", plane.planeid);
    fprintf(stderr, "version %c\t cmd %c\t type %d\t alive %d\t myname %s\n",
            plane.version, plane.cmd, plane.type, plane.alive,
            plane.myname);
    fprintf(stderr, "status %ud\t won %ud\t lost %ud\n", plane.x, plane.y,
            plane.z);
    fprintf(stderr, "x %f\t y %f\t z %f\n", plane.x, plane.y, plane.z);
    fprintf(stderr, "azimuth %d\t elevation %d\t twist %d\n", plane.azimuth,
            plane.elevation, plane.twist);
    fprintf(stderr, "mstatus %d\t mx %f\t my %f\t mz %f\n", plane.mstatus,
            plane.mx, plane.my, plane.mz);
    fprintf(stderr, "last_mx %f\t last_my %f\t last_mz %f\n", plane.last_mx,
            plane.last_my, plane.last_mz);
    fprintf(stderr, "kill %d\t tps %f\n", plane.kill, plane.tps);
    fprintf(stderr, "air speed %d\t thrust %d\n", plane.airspeed,
            plane.thrust);
    fprintf(stderr, "wheels %d\t elevator %d\t mtype %c\n", plane.wheels,
            plane.elevator, plane.mtype);
/* Initialize the synchronous/non-blocking link-level socket connection */
netinit()
{
    int rc, on=1;

    /* Check that the driver is loaded, and get our own ethernet MAC
       address from the EXOS board */
    if (!loaded) errexit("driver NOT loaded");
    if (ipinfo(&opt) < 0) errexit("could not get own ethernet MAC address");
    mempy(my_addr, opt.xo_eaddr, sizeof(my_addr));

    /* Display my address */
    fprintf(stderr, "my addr = %02x-%02x-%02x-%02x-%02x-%02x\n",
            my_addr[0], my_addr[1], my_addr[2],
            my_addr[3], my_addr[4], my_addr[5]);

    /* Initialize the simnet receiver/sender socket type */
    recv_socket.sl_types[0] = ETYPE;

    /* Make a link level socket call */
    if ((netfd=socket(SOCK_ETH, (struct sockproto *)0, &recv_socket, 0)) < 0) {
        if (errno == EACCES)
            errexit("link-level access must be enabled with -l option on netload");
        else errexit("cannot create socket");
    }
    fprintf(stderr, "socket fd = %d\n", netfd);

    /* Synchronous/non blocking mode */
    soioctl(netfd, SIOCSLINGER, &timelimit);
    rc = soioctl(netfd, FIONBIO, &on);
    if (rc < 0) {
        experror("soioctl(...FIONBIO, &on)\n")
        return(-1);
    }
    return(0);
}

/* Read synchronous/non blocking mode packet */
/* netread (struct ether buf) */
netread()
{
    int cnt;

    cnt = soreceive(netfd, (struct sockaddr *)0, &ether_buf, MAXPKTSIZE);
    if ((cnt < 0) && (errno == EWOULDBLOCK))
        /* No network data */
    else
        if (cnt < 0) experror("soreceive read error"); /* Error condition */
        return (cnt);
}

/* Write synchronous/non blocking mode packet */
/* netwrite (struct ether *buf) */
datalength = ntohs(datalength);  
cnt = datalength * header_length;  
netcnt = sosend(netfd, (struct sockaddr *)0, &ether_buf, cnt + HEADER_SIZE);  
if ((netcnt < 0) && (errno == EWOULDBLOCK)) netcnt = 0;  
if (netcnt < 0)  
    errexit("sosend write error");  
else  
    if ((netcnt >= 0) && (netcnt < cnt))  
        fprintf(stderr, "sosend: some data has been lost
");

/* Close synchronous/non blocking socket connection */
netfini()  
{
    int off = 0;

    if (netfd >= 0) {  
        fprintf(stderr, "Please wait up to %d seconds for completion\n", timelimit);
        soioctl(netfd, FIONBIO, &off);
        soclose(netfd);
        netfd = -1;
    }
}

/* Network order to host order transform, not all of the data field are included yet. Add more statements if needed and modify the hton_simnet() too */
/* ntoh_simnet (PDU buf) */
ntoh_simnet()  
{
    int i, j;
    union {
        char *tmpc;
        unsigned short *tmpui;
    } tmpui;
    union {
        char *tmpc;
        float *tmpf;
    } tmp;

    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[0];  
        swap4(tmp.tmpc);
    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[1];  
        swap4(tmp.tmpc);
    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[2];  
        swap4(tmp.tmpc);
    tmpui.tmpui = &pdu_buf.VAPDU.VADATA.hdr.vehicleID;  
        swap2(tmpui.tmpc);
    for (i=0; i<=2; i++)  
        for (j=0; j<=2; j++) {  
            tmp.tmpf = &pdu_buf.VAPDU.VADATA.rotation[i][j];  
            swap4(tmp.tmpc);
        }
    return(pdu_buf.ANYPDU.ANYHDR.kind);
}
/* Byte order to network order transform, not all of the data field are included yet. All write statements it needed and modify the htonl substitute */
/* htonl substitute (struct IPv4 buf) */

htonl substitute()
{
    int i, j;
    union{
        char *tmpc;
        unsigned short *tmpui;
    } tmpui;
    union{
        char *tmpc;
        float *tmpf;
    } tmp;

    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[0];
    swap4(tmp.tmpc);
    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[1];
    swap4(tmp.tmpc);
    tmp.tmpf = &pdu_buf.VAPDU.VADATA.location[2];
    swap4(tmp.tmpc);
    tmpui.tmpui = &pdu_buf.VAPDU.VADATA.hdr.vehicleID;
    swap2(tmpui.tmpui);
    for (i=0; i<=2; i++)
        for (j=0; j<=2; j++)
            tmp.tmpf = &pdu_buf.VAPDU.VADATA.rotation[i][j];
    return(0);
}

/* This subroutine does the same work as ntohl(), htonl(). */
swap4(char *ptr)
{
    char tmp;

    tmp = *ptr;
    *ptr = *(ptr+3);
    *(ptr+3) = tmp;
    tmp = *(ptr+1);
    *(ptr+1) = *(ptr+2);
    *(ptr+2) = tmp;
}

/* This subroutine does the same work as ntohs(), htons(). */
swap2(char *ptr)
{
    char tmp;

    tmp = *ptr;
    *ptr = *(ptr+1);
    *(ptr+1) = tmp;
}

/* This subroutine is for debugging purpose only, it will DUMP the content of a link level packet in hexadecimal*/
/* dump_ether (struct ether ether_buf) */
dump_ether()
{
    int i, j, netcnt;

    B-7
fprintf(stderr,"Pource addr:
ether_buf.e_shost[0], ether_buf.e_shost[1], ether_buf.e_shost[2], ether_buf.e_shost[3], ether_buf.e_shost[4], ether_buf.e_shost[5]);
}

fprintf(stderr,"Destination addr:
ether_buf.e_dhost[0], ether_buf.e_dhost[1], ether_buf.e_dhost[2], ether_buf.e_dhost[3], ether_buf.e_dhost[4], ether_buf.e_dhost[5]);

netcnt = datalenth.i_datalenth.length;
for (i=0; j=3; i<(netcnt-HEADER_SIZE-2); i++, j++) {
    fprintf(stderr,"%2x ", ether_buf.simnet_data.e_data[i]);
    if (j >= 17) {
        j=0;
        fprintf(stderr, "\n");
    }
    fprintf(stderr, "\n");
}

/* This subroutine is for debugging purpose only, it will DUMP the content of a pdu packet in hexadecimal*/
dump_pdu()
{
    int i, j, netcnt;

    datalenth.p_datalenth = ntohss (ether_buf.simnet_data.e_datalenth);
    netcnt = datalenth.i_datalenth.length;
    for (i=0; j=1; i<(netcnt-HEADER_SIZE-2); i++, j++) {
        fprintf(stderr,"%2x ", pdu_buf.DATANYLPU.DATANY[1][j]);
        if (j >= 17) {
            j=0;
            fprintf(stderr, "\n");
        }
    }
    fprintf(stderr, "\n");
}

/* This subroutine is for debugging purpose only, it will DISPLAY the content of a pdu packet */
display_pdu()
{
    int i, j;
    union {
        char *tmpc;
        float *tmpf;
    } tmp;

    fprintf(stderr, "Rotation\n");
    for (i=0; i<=2; i++)
        for (j=0; j<=2; j++)
            fprintf(stderr,"%d %d %lf\n", i, j, pdu_buf.VAPDU.VADATA.rotation[i][j])
    fprintf(stderr, "Location\n");
    fprintf(stderr, "%lf\n", pdu_buf.VAPDU.VADATA.location[0]);
    fprintf(stderr, "%lf\n", pdu_buf.VAPDU.VADATA.location[1]);
    fprintf(stderr, "%lf\n", pdu_buf.VAPDU.VADATA.location[2]);
    fprintf(stderr, "%u\n", pdu_buf.VAPDU.VADATA.hdr.vehicleID);
This program displays the airplane controlled by the SiliconGraphics on the simnet.

simnet: Link Level Raw Ethernet Packets / Synchronous Non-blocking

SiliconGraphics: Synchronous-blocking UDP/IP or (disk file)

```c
#include <sys/extypes.h>
#include <stdio.h>
#include <ctype.h>
#include <math.h>
#include <sys/exerrno.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <fcntl.h>
#include <signal.h>
#include <errno.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <sys/exosopt.h>
#include <sys/exos.h>
#include <ex_ioctl.h>
#include <sys/ioctl.h>
#include <sys/socket.h>
#include "..\simnet.h\simnet2.h"
#include "..\flight.h\flight.h"

struct sockaddr_link recv_socket = ( AF_ETYPEFILTER );
struct sockaddr_link send_socket = ( AF_ETYPEFILTER );
struct sockaddr_in recv_socket_sg = ( AF_INET );
struct sockaddr_in send_socket_sg = ( AF_INET );

#define FILEOFLAG (0_RDONLY | O_BINARY)
#define FILEPMODE (0)
#define PI 3.14159

extern int errno;
extern int break_enabled;
extern int abort_op;

int diskfd = -1; /* disk file */
int netfd = 1; /* simnet file */
int netfdsg = -1; /* udp/ip file */
int timelimit = 30;
char *inputfile;

char SENDIT;
char buf[1024];

int break_handler();

main (argc, argv)
char **argv;
```
signal(SIGINT, break_handler);
break_enabled = 1;
inputfile = argv[1];

go ;

sginitin();
netinit();

/* Capture a simnet packet first, so we don't have to fill all of the data field */
fprintf(stderr, "wait for simnet\n");
while(1) {
  /* netcnt=netread(inbuf): */
  netcnt=netread();
  datalenlen.p_datalenlen= ntohs (ether_buf.simnet_data.e_datalenlen);
  netcnt=datalenlen.i_datalenlen.length + HEADER_SIZE;
  memcpy (&pdu_buf, &ether_buf.simnet_data, netcnt - HEADER_SIZE);
  pdukind = ntohs_pdukind();
  if (pdukind == vehicleAppearancePDUKind) {
    SENDIT = 'A';
    if (ether_buf.e_shost[5] == TANKA)
      SENDIT = 'A';
    if (ether_buf.e_shost[5] == TANKB)
      SENDIT = 'B';
  }
  if (SENDIT == 'A' || (SENDIT == 'B')) break;
}

fprintf(stderr, "Got a vehicle appearance packet from tank %c\n", SENDIT);
pdu_buf.VAPDU.VADATA.hdr.vehicleID = MYTANKID;
pdu_buf.VAPDU.VADATA.appearance.vehKindMask = A10;
memcpy (ether_buf.e_shost, my_addr, sizeof(my_addr));

while (1) {
  netcnt = sgreadin();
  if (netcnt <= 0) break;
  memcpy(&plane, buf, netcnt);
  ntoh_flight();

  pdu_buf.VAPDU.VADATA.location[0] =
    AIRPORTX + ((plane.x + ADJUSTX)/F2M);
  pdu_buf.VAPDU.VADATA.location[1] =
    AIRPORTZ - ((plane.z + ADJUSTZ)/F2M);
  pdu_buf.VAPDU.VADATA.location[2] = AIRPORTY + (plane.y/F2M);
  calrotation();
  hton_simnet();
  memcpy (&ether_buf.simnet_data, &pdu_buf, netcnt - HEADER_SIZE);
  netwrite();
}

fprintf (stderr, "End of input sg packet\n");
close(diskfd);
sgfinin();
netfini();

errexit(errstring)
char *errstring;

B-10
break_handler() /* break handler ... control-break or control-c */
{
    static int break_count = 0;

    if (++break_count == 1) {
        /* first time, just try to stop current network operation */
        abort_op = 1;
        signal(SIGINT, break_handler); /* reset trap */
        return;
    } else {
        /* second time, try to clean up, then quit */
        errexit("user abort");
    }
}

pinfo(optp)
struct exosopt *optp;
{
    /* note that this routine will not return valid results
     * if used with a pre-3.3 driver, which interpreted the
     * board memory address as absolute, rather than relative
     * to the beginning of the data segment
     */
    long optaddress = 0; /* location of options */
    int id;

    if ((id = brdopen(0, 1)) < 0) {
        experror("brdopen");
        return(-1);
    }
    if (brdioctl(id, BRDADDR, &optaddress) < 0) {
        experror("brdioctl(BRDADDR,...)");
        return(-1);
    }
    if (brdread(id, optp, sizeof(struct exosopt)) < 0) {
        experror("brdread");
        return(-1);
    }
    brdclose(id);
    return 0;
}

/* This subroutine computes the rotation matrix (3x3) for the SIMNET PDU's */
* given the pitch, roll and yaw of the vehicle. */
alrotation()
/* In Silicon Graphics DogFight: Roll=Twist; Pitch=Elevation; Yaw=Azimuth */

R=(plane.twist/10*PI)/180;
P=-(plane.elevation/10*PI)/180;
Y=-(plane.azimuth/10*PI)/180;

RC=cos(R);
RS=sin(R);

PC=cos(P);
PS=sin(P);
YC=cos(Y);
YS=sin(Y);

z[0][0]=YC;
z[0][1]=-YS;
z[0][2]=0;
z[1][0]=YS;
z[1][1]=YC;
z[1][2]=0;
z[2][0]=0;
z[2][1]=0;
z[2][2]=1;

x[0][0]=1;
x[0][1]=0;
x[0][2]=0;
x[1][0]=0;
x[1][1]=PC;
x[1][2]=-PS;
x[2][0]=0;
x[2][1]=PS;
x[2][2]=PC;

y[0][0]=RC;
y[0][1]=0;
y[0][2]=RS;
y[1][0]=0;
y[1][1]=1;
y[1][2]=0;
y[2][0]=-RS;
y[2][1]=0;
y[2][2]=RC;

for (i=0; i<=2; i++) {
    for (j=0; j<=2; j++) {
        A[i][j]=0;
        for (k=0; k<=2; k++)
            A[i][j] += x[i][k] * y[k][j];
    }
}
for (i = 0; i < J; i++)
for (j = 0; j < J; j++)
    pdu_buf.VAPDU.VADATA.rotation[i][j] = 0;
for (k = 0; k < 2; k++)
    pdu_buf.VAPDU.VADATA.rotation[i][j] += A[i][k] * z[k][j];
SIMNET DATA STRUCTURE DECLARATIONS

#define TANKA 0x68 /* 02-cf-1f-30-27-68 */
#define TANKB 0xff95 /* 02-cf-1f-30-27-95 */
#define MCC 0x09 /* 02-cf-1f-30-28-09 */
#define ANZR 0x14 /* 08-00-09-00-ba-14 */

typedef struct {
  unsigned version :4; /* version of protocol */
  unsigned length :12; /* length of PDU in octets */
  unsigned protocol :8; /* protocol PDU belongs to */
  unsigned kind :8; /* type of PDU within protocol */
} PDUHeader;

/* version field */
#define protocolVersionFeb87 0 /* the Feb. 1987 version of the protocols */
#define protocolVersionNov87 1 /* the Nov. 1987 version of the protocols */

/* protocol field */
#define protocolMgmt 1 /* the Network Management Protocol */
#define protocolSim 2 /* the Simulation Protocol */
#define protocolData 3 /* the Data Collection Protocol */
#define protocolXfer 4 /* the File Transfer Protocol */
#define protocolDiag 5 /* the Diagnosis Protocol */

/* kind field */
#define activatePDUKind 1 /* Activate PDU */
#define activatePDUKind 2 /* Activating PDU */
#define deactivatePDUKind 3 /* Deactivate PDU */
#define vehicleAppearancePDUKind 4 /* Vehicle Appearance PDU */
#define unusedPDU Kind 5 /* Unused PDU */
#define vehicleImpactPDUKind 6 /* Vehicle Impact PDU */
#define groundImpactPDUKind 7 /* Ground Impact PDU */
#define indirectFirePDUKind 8 /* Indirect Fire PDU */
#define serviceRequestPDUKind 9 /* Service Request PDU */
#define resupplyOfferPDUKind 10 /* Resupply Offer PDU */
#define resupplyReceivedPDUKind 11 /* Resupply Received PDU */
#define repairPDUKind 12 /* Repair PDU */
#define repairedPDUKind 13 /* Repaired PDU */
#define collisionPDUKind 14 /* Collision PDU */
#define firePDUKind 15 /* Fire PDU */
#define radiatePDUKind 16 /* Radiate PDU */
#define resupplyCancelPDUKind 17 /* ResupplyCancel PDU */

/* Vehicle Type Identifier Field */
#define vehMainBattleTank 1 /* M1 or T72 main battle tank */
#define vehPersonnelCarrier 2 /* M2, M3 or BMP */
#define vehCommandPost 3 /* M577 Command Post */
#define vehAmmunitionTruck 4 /* M977 Ammo Truck */
#define vehFuelTruck 5 /* M978 Fuel Truck */
#define vehSupplyTruck 6 /* M35-A2 Truck */
#define vehMortarCarrier 7 /* M106 Carrier */
#define vehSPHowitzer 8 /* M109 Howitzer */
#define vehRecoveryVehicle 9 /* M88 Recovery */
#define vehFISTVehicle 10 /* Fire Support */

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typedef struct {
    PDUHeader pduHdr; /* version, length, protocol, PDUKind */
    unsigned char exerciseID; /* exercise identifier */
    unsigned char padding;
    unsigned short vehicleID; /* vehicle identifier */
} SimPDUHeader;

typedef struct {
    unsigned char role; /* role of vehicle: ammo truck,
                           fuel truck, etc */
    unsigned char batallion; /* batallion (task force) vehicle belongs to */
    unsigned char company; /* company (team) vehicle belongs to */
    unsigned char bumper; /* bumper number within company */
} VehicleRole;

/* role field */
define roleSimulator 0 /* a vehicle operated by a full crew,
                           simulated by a crewed vehicle simulator */
define roleOPFOR 1 /* a vehicle simulated by a Semi-automated Forces system */
define roleGunneryTarget 2 /* a gunnery target, such as that simulated by an MCC system */
define roleAmmoTruck 3 /* an ammunition truck, such as that simulated by an MCC system */
define roleFuelTruck 4 /* a fuel truck, such as that simulated by an MCC system */
define roleMaintTeam 5 /* a maintenance team, such as that simulated by an MCC system */
define roleS2 6 /* a batallion S2's vehicle, such as that simulated by an MCC system as part of a tactical operations center (TOC) */
define roleS3 7 /* a batallion S3's vehicle, such as that simulated by an MCC system as part of a TOC */
define roleFSE 8 /* a batallion fire support officer's vehicle, such as those simulated by an MCC system as part of a TOC */
define roleTACP 9 /* a batallion tactical air control party vehicle, such as those simulated by an MCC system as part of a TOC */
define roleAdminLogCenter 10 /* a batallion admin/log center vehicle, such as that simulated by an MCC system */
define roleOther 99 /* any other vehicle not in one of the above categories */

/* company field */
define assignedBattalion 1 /* the vehicle is assigned to no unit in particular within the batallion */
define assignedScoutPlt 2 /* the vehicle belongs to the batallion's scout platoon */
define assignedTACP 3 /* the vehicle belongs to the batallion's tactical air control party */
/* Common to all vehicles */
VehicleRole role; /* include ID of described number */
unsigned char alignment; /* offense, defense, friend, or foe */
unsigned char vehicleClass; /* class of vehicle */
/* unsigned short appearance; /* type of vehicle and appearance */
/* struct */
unsigned vehKindMask : 6;
unsigned un1 : 1;
unsigned vehDestroyed : 1;
unsigned vehSmokePlume : 1;
unsigned vehFlaming : 1;
unsigned vehDustCloudMask : 2;
unsigned un2 : 1;
unsigned vehTOWLauncherUp : 1;
unsigned vehEngineSmoke : 1;
unsigned un3 : 1;
} appearance; /*
struct {
unsigned vehSmokePlume : 1;
unsigned vehFlaming : 1;
unsigned vehDustCloudMask : 2;
unsigned un2 : 1;
unsigned vehTOWLauncherUp : 1;
unsigned vehEngineSmoke : 1;
unsigned un3 : 1;
unsigned vehKindMask : 6;
unsigned un1 : 1;
unsigned vehDestroyed : 1;
} appearance;
float rotation [3][3]; /* vehicle rotation */
float location [3]; /* exact vehicle location */
short grid [2]; /* approximate vehicle location */
unsigned short engineSpeed; /* engine speed, in RPM */
/* unsigned short padding; */
unsigned short sequence; /* sequence # for vehicleAppearancePDU */

/* Depending on vehicle class */
union {
/* If a simple moving vehicle, without turret ... */
struct {
float velocity [3]; /* velocity (m/sec/15) */
} simple;
/* If a tank */
struct {
float velocity [3]; /* velocity (m/sec/15) */
unsigned short turretAzimuth;
/* turret/hull orientation */
unsigned short gunElevation; /* gun/turret elevation */
} tank;
} u;
} VehicleAppearancePDU;

/* alignment field */
#define alignedFoe 0 /* the vehicle appears unfriendly to all participants */
/* vehicle class field */
define vehicleClassStatic 1 /* the vehicle is always stationary when visible, and it has no independently movable parts */
define vehicleClassSimple 2 /* the vehicle can move, but is has no independently movable parts */
define vehicleClassTank 3 /* the vehicle can move, and it has a turret and a gun barrel */

typedef struct {
    unsigned char ammunition; /* type of ammunition fired */
    unsigned char fuze; /* type of fuze used */
    unsigned char quantity; /* number of rounds in burst */
    unsigned char rate; /* rate of fire, rounds per second */
} BurstDescriptor;

/* ammunition field */
define ammoHEi25 1 /* 25 mm high explosive incendiary shell */
define ammoHEAT105 2 /* 105 mm high explosive anti-tank shell */
define ammoAPDS25 3 /* 25 mm armor piercing discarding sabot shell */
define ammoAPDS105 4 /* 105 mm armor piercing discarding sabot shell */
define ammoTP25 5 /* 25 mm target practice shell */
define ammoBomb500 6 /* 500 lb. bomb */
define ammoHE107 7 /* 107 mm (4.2in.) high explosive mortar shell */
define ammoHE155 8 /* 155 mm high explosive howitzer shell */
define ammoMissileTOW 9 /* TOW anti-tank missile */

/* fuze field */
define fuzePointDetonating 1 /* point detonating fuze */
define fuzeProximity 2 /* proximity fuze */

typedef struct {
    unsigned char targetType:2; /* what is known about the target */
    unsigned : 14;
    unsigned short vehicleID; /* ID of target vehicle, if known */
} TargetDescriptor;

/* targetType field */
define targetUnknown 0 /* the target vehicle is not known */
define targetNotVehicle 1 /* the target is known, but it is not a vehicle */
define targetVehicle 2 /* the target is known and it is not a vehicle */

/* */
define MYTANKID 16
#define MAXBUF 8192
#define HEADER_SIZE 14 /* ethernet header size including our header */

struct ether { /* first three fields required for any link level packet */
    char e_dhost[6]; /* 00-05 ethernet destination */
    char e_shost[6]; /* 06-11 ethernet source */
    short e_type; /* 12-13 ethernet packet type */
}
union {
    struct {
        unsigned length :12;
        unsigned version :4;
    } i_datalength;
    short p_datalength;
} datalength;

typedef union {
    struct {
        char DATAONLY [1512 - HEADER_SIZE];
    } DATAONLYPDU;
    struct {
        PDUHeader ANYHDR;
        char data [1512 - HEADER_SIZE - 4];
    } ANYPDU;
    struct {
        VehicleAppearancePDU VADATA;
    } VAPDU;
} PDU;

#define MAXPKTSIZE 1514     /* total size of largest possible packet */
/* char send_addr[6];   /* our ethernet MAC address */
/* char recv_addr[6];   /* his ethernet MAC address */
char my_addr[6];       /* my ethernet MAC address */
struct exosopt opt;    /* EXOS board options include own address */
#define ETYPE htons(0x5208)     /* arbitrary unused ethernet type */
#define HELICOPTER1 11
#define HELICOPTER12 12
#define A10 13
PDU pdu_buf;
struct ether ether_buf;