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ESTIMATORS IN TWO SAMPLE PROBLEMS

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EMPIRICAL AND HIERARCHICAL BAYES COMPETITORS OF PRELIMINARY TEST ESTIMATORS IN TWO SAMPLE PROBLEMS

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1. Introduction

Suppose in a laboratory, say Laboratory I, a certain instrument is designed to measure several characteristics, and a number of vector-valued measurements is recorded. Our objective is to estimate the unknown population mean. It is known, however, that a similar instrument is used in another laboratory, say Laboratory II for the same purpose, and a number of observations is recorded from the second instrument. It is also suspected that the two population means are equal, in which case, observations recorded in Laboratory II can possibly be used effectively together with those in Laboratory I for estimating the population mean of the first instrument. Thus, the question that naturally arises is whether one should use the sample mean from Laboratory I or the pooled mean from the two laboratories.

In problems of this type what is normally sought is a compromise estimator which leans more towards the pooled sample mean when the null hypothesis of the equality of the two population means is accepted, and towards the sample mean from Laboratory I when such a hypothesis is rejected.

A very popular way to achieve this compromise is to use a preliminary test estimator (PTE) which uses the pooled mean when the null hypothesis is accepted at a desired level of significance, and uses the sample mean from Laboratory I when opposite is the case. For an excellent review of PTE's, see Bancroft and Han (1981). It is known, though, in other situations that a PTE is typically not a minimax estimator, and estimators with uniformly smaller mean squared error (MSE) than the PTE can often be produced (see for example Sclove et al (1972)). Moreover, the degree of evidence for or against the null hypothesis is not reflected in the PTE.

In this paper, we propose instead an empirical Bayes (EB) estimator which achieves the intended compromise. Such an EB estimator is quite often a weighted average of the pooled mean and the first sample mean. The weights are adaptively determined from the data in such a way that larger the value of the usual $F$ statistic used for testing the equality of the two population means, the smaller is the weight attached towards the pooled sample mean. Thus, unlike the PTE, the EB estimator incorporates the degree of evidence for or against the null hypothesis in a very natural way. Also, unlike a subjective Bayes estimator, the EB estimator is quite robust (with respect to its frequentist or Bayesian risk) against a wide class of priors.

Section 2 motivates the EB estimator, and its Bayesian properties are discussed in this Section. Among other things, it is shown that the EB estimator has uniformly smaller Bayes risk than the first sample mean. In Section 3, the estimators are compared in terms of their frequentist risks, and sufficient conditions under which an EB estimator dominates the first sample mean are given. Also, in this section, a modified EB estimator is proposed, and sufficient conditions under which it dominates the PTE are given. Finally, in Section 5, a hierarchical Bayes approach is proposed as an alternative to EB estimators. It has recently
come to our attention that Saleh and Ahmed (1987) have considered estimation of $\mu_1$ under the loss $L(\delta, \mu_1) = (\delta - \mu_1)'V^{-1}(\delta - \mu_1)$, assuming $V_1 = V_2 = V$ unknown, and proposed the shrinkage estimator $\tilde{X}_1 + \frac{n_2}{n_1 + n_2}(X_2 - \tilde{X}_1) \cdot \frac{n_2}{n_1 + n_2}$ where $\gamma_1^2 = \frac{n_1 n_2}{n_1 + n_2}(X_2 - \tilde{X}_1)'S^{-1}(X_2 - \tilde{X}_1)$, $nS$ = pooled sum of squares and products matrix, $n = n_1 + n_2 - 2$, and $0 < c < \frac{2(p-2)}{n_1 + n_2 - p + 1}$. A comparison of the risk of the above estimator with those of the PTE as well as $\tilde{X}_1$ and $\frac{n_2}{n_1 + n_2}X_2$ is also undertaken by the above authors.
2. The EB Estimator and its Bayesian Properties

Let $X_1(i = 1, \ldots, n_1)$ and $X_2(i = 1, \ldots, n_2)$ be independent $p(\geq 3)$-dimensional random vectors, where $X_1$'s are i.i.d $N_p(\mu_1, \sigma^2V_1)$, while $X_2$'s are i.i.d $N_p(\mu_2, \sigma^2V_2)$. In the above $\mu_1, \mu_2 \in \mathbb{R}^p$, $\sigma^2(>0)$ are unknown, but $V_1$ and $V_2$ are known $p \times p$ p.d. matrices. Our goal is to estimate $\mu_1$.

In order to motivate the EB estimator, we need find first a Bayes procedure. It is immediate that the minimal sufficient statistic for $(\mu_1, \mu_2, \sigma^2)$ is $(\bar{X}_1, \bar{X}_2, \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2))$, where $\bar{X}_j = n_j^{-1} \sum_{i=1}^{n_j} X_{j,i}$ ($j = 1, 2$) and $S_j = \sum_{i=1}^{n_j} (X_{j,i} - \bar{X}_j)(X_{j,i} - \bar{X}_j)^T$, $j = 1, 2$. Note also that $\bar{X}_j \sim N_p(\mu_j, \sigma^2n_j^{-1}V_j)$ ($j = 1, 2$), while $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \sim \sigma^2 \chi^2_{(n_1 + n_2 - 2)p}$.

In a Bayesian framework, the above is treated as a conditional distribution given $\mu_1$ and $\mu_2$. We use the independent $N_p(\nu, \tau^2n_j^{-1}V_j)$ and $N_p(\nu, \tau^2n_j^{-1}V_j)$ priors for $\mu_1$ and $\mu_2$, that is the prior variance covariance matrix is proportional to the variance-covariance matrix of the corresponding sample mean. The suspicion that $\mu_1$ and $\mu_2$ may be equal is reflected in the choice of a priori common mean $\nu$. For a related prior in the general regression model, see Ghosh et al (1987).

In order to find the posterior distribution of $\mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}$, first note that conditional on $\mu_1$ and $\mu_2$, $\bar{X}_1, \bar{X}_2, S_1$ and $S_2$ are mutually independent, and the distributions of $S_1, S_2$ do not depend on $\mu_1$ and $\mu_2$. Hence, we can restrict ourselves to the conditional distributions of $\bar{X}_j$'s given $\mu_j$'s. Also, since $\mu_1$ and $\mu_2$ have independent normal priors, standard calculations yield that $\mu_1$ and $\mu_2$ given $\bar{X}_1$ and $\bar{X}_2$ have independent posterior distributions with

$$
\mu_j | \bar{X}_j \sim N_p((1 - B)x_j + B\nu, \sigma^2(1 - B)n_j^{-1}V_j)
$$

$j = 1, 2$ where $B = \sigma^2/(\sigma^2 + \tau^2)$. Now, using the loss

$$
L(\mu_1, a) = \sigma^{-2}(a - \mu_1)^TQ(a - \mu_1)
$$

for estimating $\mu_1$ by $a$ ($Q$ being a known p.d. weight matrix), the Bayes estimator of $\mu_1$ is

$$
e_{B}(\bar{X}_1) = (1 - B)\bar{X}_1 + B\nu.
$$

Note that the Bayes estimator does not depend on the choice of $Q$. The multiplier $\sigma^2$ is used in the loss because that makes $\bar{X}_1$ a minimax estimator of $\mu_1$ with constant risk not depending on any unknown parameter.

In order to find an EB estimator of $\mu_1$, we estimate the unknown parameters $B$ and $\nu$ in (2.3) from the marginal distributions of $\bar{X}_1$, $\bar{X}_2$ and $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)$. Note that marginally $\bar{X}_1$, $\bar{X}_2$ and $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)$ are mutually independent with $\bar{X}_j \sim N_p(\nu, n_j^{-1}(\sigma^2 + \tau^2)V_j)$, ($j = 1, 2$) and $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \sim \sigma^2 \chi^2_{(n_1 + n_2 - 2)p}$. Hence the
complete sufficient statistic for \((v, \tau^2, \sigma^2)\) based on this marginal distribution is \((W, Z, \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2))\) where \(W = (n_1V_1^{-1} + n_2V_2^{-1})^{-1}(n_1V_1^{-1}X_1 + n_2V_2^{-1}X_2)\) is the pooled sample mean, \(Z = YT(n_1V_1^{-1} + n_2V_2^{-1})^{-1}Y\) and \(Y = \bar{X}_1 - \bar{X}_2\). Also, marginally, \(W \sim \mathcal{N}_p(\nu, \sigma^2 + r^2)(n_1V_1^{-1} + n_2V_2^{-1})^{-1}Y \sim \mathcal{N}_p(0, (n_1V_1^{-1} + n_2V_2^{-1})\sigma^2 + \tau^2)\) and \(\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \sim \sigma^2 \chi^2_{n_1 + n_2 - 2}\). Hence, the UMVUE of \(\nu\) is \(W\), while the UMVUE of \((\sigma^2 + \tau^2)^{-1}\) is \((p - 2)/(YT(n_1V_1^{-1} + n_2V_2^{-1})^{-1}Y)\). The last assertion follows since \(YT(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y \sim (\sigma^2 + \tau^2)^2\). Moreover since \(\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \sim \sigma^2 \chi^2_{n_1 + n_2 - 2}\), the best scale invariant estimator of \(\sigma^2\) is \(((n_1 + n_2 - 2)p + 2)^{-1}\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)\). Substituting these estimators for \(\nu, (\sigma^2 + \tau^2)^{-1}\) and \(\sigma^2\) in (2.3), one gets the EB estimator of \(\mu_1\) as

\[
e_{EB}(X_1, X_2, S_1, S_2) = (1 - \hat{B})\bar{X}_1 + \hat{B}W = W + (1 - \hat{B})(\bar{X}_1 - W) \tag{2.4}\]

where \(\hat{B} = \frac{(p - 2)\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{((n_1 + n_2 - 2)p + 2)YT(n_1V_1^{-1} + n_2V_2^{-1})^{-1}Y} \tag{2.5}\)

**Remark 2.1** Note that \(0 < B < 1\), while the estimator \(\hat{B}\) though positive can values exceeding one. Accordingly, for practical purposes, one proposes the positive part EB estimator

\[
e_{EB}^+(X_1, X_2, S_1, S_2) = W + (1 - \hat{B})^+(X_1 - W). \tag{2.6}\]

of \(\mu_1\), where \(\alpha^+ = \max(\alpha, 0)\). For simplicity of exposition, in the remainder of this section, we shall, however, work with \(e_{EB}\) rather than \(e_{EB}^+\).

A question that naturally arises is why this particular method of estimation is used for estimating the prior parameters. We shall answer the question by proving the “optimality” of \(e_{EB}\) within the class of estimators

\[
d_c(X_1, X_2, S_1, S_2) = W + (1 - \frac{c\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{((n_1 + n_2 - 2)p - 2)YT(n_1V_1^{-1} + n_2V_2^{-1})^{-1}Y})(\bar{X}_1 - W), \tag{2.7}\]

where \(c > 0\) is a constant. Note that \(e_{EB} = \delta_{p-2}\).

**Theorem 2.1** The Bayes risk of \(d_c\) under the assumed prior (say \(\xi\)) and the loss (2.2) is given by

\[
r(\xi, d_c) = (1 - \theta)(n_1^{-1}\text{tr}(QV_1^{-1} + B\text{tr}(Q(n_1V_1^{-1} + n_2V_2^{-1}))^{-1}) + B\text{tr}(QA(n_1V_1^{-1} + n_2V_2^{-1})^{-1}A^T) \cdot \left[\frac{2c(n_1 + n_2 - 2)}{(n_1 + n_2 - 2)p + 2}(p - 2) - \frac{2c(n_1 + n_2 - 2)}{(n_1 + n_2 - 2)p + 2} + 1 \right]. \tag{2.8}\]

where $\Lambda$ is defined following (2.11) below.

Proof:

The second part of the theorem follows immediately from (2.8). To prove the first part, write

$$r(\xi, \delta) = r(\xi, e_B) + \sigma^2 E[(e_B - \delta)^T Q (e_B - \delta)]$$  \hspace{1cm} (2.9)

Note from (2.1) to (2.3) that

$$r(\xi, e_B) = (1 - B)n_1^{-1} \text{tr}(Q V_1)$$  \hspace{1cm} (2.10)

Also, writing $\hat{B}_c = \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)/(n_1 + n_2 - 2)p + 2)Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y$, one gets

$$r(\xi, e_B) = (1 - B)\hat{X}_1 + B\nu - W - (1 - \hat{B}_c)(\hat{X}_1 - W)$$

$$= -B(W - \nu) + (\hat{B}_c - B)(\hat{X}_1 - W)$$

$$= -B(W - \nu) + (\hat{B}_c - B)\Lambda Y,$$  \hspace{1cm} (2.11)

$$\Lambda = (n_1V_1^{-1} + n_2V_2^{-1})^{-1}n_2V_2^{-1}.$$  

Next using the independence of $W$ and $(Y, \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2))$ and the facts that $E(W) = \nu$, $\text{Var}(W) = (\sigma^2 + r^2)(n_1V_1^{-1} + n_2V_2^{-1})^{-1} = \sigma^2 B^{-1}(n_1V_1^{-1} + n_2V_2^{-1})^{-1}$, one gets

$$E[(e_B - \delta)^T Q (e_B - \delta)]$$

$$= B^2 E[(W - \nu)^T Q (W - \nu)] + E[(\hat{B}_c - B)^2 Y^T \Lambda^T Q \Lambda Y]$$

$$= \sigma^2 B \text{tr} \{Q(n_1V_1^{-1} + n_2V_2^{-1})^{-1}\} + E[(\hat{B}_c - B)^2 Y^T \Lambda^T Q \Lambda Y]$$ \hspace{1cm} (2.12)

Now we find

$$E[(\hat{B}_c - B)^2 Y^T \Lambda^T Q \Lambda Y]$$

$$= E\left[\frac{\sigma^2 \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{(n_1 + n_2 - 2)p + 2} \left\{Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y\right\} \right]$$

$$+ B^2(Y^T \Lambda^T Q \Lambda Y)$$  \hspace{1cm} (2.13)

Using the independence of $Y$ and $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)$ along with the fact that $\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \sim \sigma^2 X^2_{(n_1 + n_2, 2)p}$, it follows that the right hand side of (2.13)
Next observe that $Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y$ is a function of the complete sufficient statistic while $(Y^T A^T Q A Y)/(Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y)$ is ancillary. Now using Basu's theorem (or Lemma 1 of Ghosh et al (1987)) along with $E(Y^T A^T Q A Y) = (\sigma^2 + \tau^2)$,

$$
(\sigma^2 + \tau^2)\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T),
$$

$$
E(Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y) = p(\sigma^2 + \tau^2),
$$

and $E(Y^T(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y)^{-1} = (\sigma^2 + \tau^2)^{-1}(p - 2)^{-1}$, it follows that the right hand side of (2.14) is

$$
= \frac{c^2\sigma^2 B(n_1 + n_2 - 2)p\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T)}{(n_1 + n_2 - 2)p + 2}p(p - 2)
$$

$$
+ \frac{2c\sigma^2 B(n_1 + n_2 - 2)p\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T)}{(n_1 + n_2 - 2)p + 2}p
$$

$$
+ \frac{\sigma^2 B\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T)}{(n_1 + n_2 - 2)p + 2}p + 1
$$

(2.15)

It follows from (2.12) - (2.15) that

$$
E[(c_n - \delta)^T Q(c_n - \delta)]
$$

$$
\begin{align*}
\sigma^2 B\text{tr}(Q(n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}) + \sigma^2 B\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T) \\
\frac{c^2(n_1 + n_2 - 2)}{(n_1 + n_2 - 2)p + 2}p(p - 2) \quad \frac{2c(n_1 + n_2 - 2)}{(n_1 + n_2 - 2)p + 2}p + 1
\end{align*}
$$

(2.16)

The proof of the theorem is complete from (2.9), (2.10) and (2.16).

Next we compare the Bayes risks of $c_{EB}$ and $\bar{X}_1$. Note that $\bar{X}_1$ has constant risk, and hence constant Bayes risk (under any prior) $\sigma^2 n_1^{-1}\text{tr}(QV_1)$. Rather than comparing the Bayes risks of $c_{EB}$ and $\bar{X}_1$ directly, we find it convenient to introduce the notion of Relative Savings Loss (RSL) as in Efron and Morris (1973).

For any estimator $\hat{c}$ of $\mu_1$, the RSL of $c_{EB}$ with respect to $\hat{c}$ (under the prior $\xi$) is defined as

$$
RSL(\xi; c_{EB}, \hat{c}) = \left| r(\xi, c_{EB}) - r(\xi, \hat{c}) \right|/\left| r(\xi, c_{EB}) - r(\xi, \hat{c}) \right|
$$

$$
= 1 - \left| r(\xi, c_{EB}) - r(\xi, \hat{c}) \right| / \left| r(\xi, c_{EB}) - r(\xi, \hat{c}) \right|
$$

(2.17)

This is the proportion of the possible Bayes risk improvement over $\hat{c}$ that is sacrificed by the use of $c_{EB}$ rather than the ideal $c_{EB}$ under the prior $\xi$. From (2.8) with $c = p - 2$ and (2.10), it follows that...
\[ RSL(\xi; \mathbf{e}_F, \bar{X}_1) \]
\[ = |\text{tr}(Q(n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1})| \]
\[ + \text{tr}(Q \Lambda (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1}) \mathbf{A}^T) \left( \frac{2(n_1 + n_2 - 1)}{(n_1 + n_2 - 2)p + 2} \right) [n_1 \text{tr}(Q \mathbf{V}_1)]^{-1} \]  
(2.18)

Note that the above RSL expression does not depend on any unknown parameter. Also, from (2.18), since \(2(n_1 + n_2 - 1) < (n_1 + n_2 - 2)p + 2\), and

\[ (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1} + \Lambda (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1}) \mathbf{A}^T = n_1 \mathbf{V}_1, \]  
(2.19)

it follows that \( RSL(\xi; \mathbf{e}_F, \bar{X}_1) < 1 \) which is equivalent to \( r(\xi, \mathbf{e}_F) < r(\xi, \bar{X}_1) \). Thus \( \mathbf{e}_F \) has smaller Bayes risk than \( \bar{X}_1 \). A proof of (2.19), follows easily from simultaneous diagonalization of \( \mathbf{V}_1 \) and \( \mathbf{V}_2 \). Alternatively, writing

\[ \Lambda = (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1} n_2 \mathbf{V}_2^{-1} = [V_2^{-1}(n_1 \mathbf{V}_1 + n_2 \mathbf{V}_1)^{-1}]^{-1} n_2 \mathbf{V}_2^{-1} \]
\[ = n_1 \mathbf{V}_1(n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1}, \]

it follows that

\[ (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1} + \Lambda (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1}) \mathbf{A}^T = n_2 \mathbf{V}_2^{-1} \Lambda \mathbf{V}_2 + n_1 \mathbf{V}_1^{-1} \Lambda \mathbf{V}_1 \]
\[ = \Lambda (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1}) = n_1 \mathbf{V}_1, \]

which is (2.19).

Finally, in this section, we compare the Bayes risk of \( \mathbf{e}_F \) with that of \( \mathbf{W} \). Note that \( \mathbf{W} \) has Bayes risk

\[ r(\xi, \mathbf{W}) = r(\xi, \mathbf{e}_n) + \sigma^{-2} \mathbb{E}[|\mathbf{e}_n - \mathbf{W}|^T Q(\mathbf{e}_n - \mathbf{W})] \]  
(2.20)

Since \( \mathbf{e}_n = \mathbf{W} - (1 - B)\bar{X}_1 + B \nu = \mathbf{W} - B(\mathbf{W} - \nu) + (1 - B)(\bar{X}_1 - \mathbf{W}) = B(\mathbf{W} - \nu) + (1 - B)\Lambda \mathbf{Y} \) where \( \Lambda \) is defined following (2.11), using once again the independence of \( \mathbf{W} \) and \( \mathbf{Y} \), it follows that

\[ \mathbb{E}[|\mathbf{e}_n - \mathbf{W}|^T Q(\mathbf{e}_n - \mathbf{W})] \]
\[ = \sigma^{-2} \mathbb{E}[\text{tr}(Q(n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1}) (1 - B)^2 \mathbb{E}(\mathbf{Y}^T \Lambda T \mathbf{Q} \mathbf{A} \mathbf{Y})] \]
\[ = \sigma^{-2} \mathbb{E}[\text{tr}(Q(n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1})^{-1}) + \sigma^2 (1 - B)^2 B \text{tr}(Q \Lambda (n_1 \mathbf{V}_1^{-1} + n_2 \mathbf{V}_2^{-1}) \mathbf{A}^T] \]  
(2.21)

Thus from (2.10), (2.20) and (2.21).
\[
\begin{align*}
\tau(\xi, W) &= n_1^{-1}(1 - B)\text{tr}(QV_1) + R\text{tr}(Q(n_1V_1^{-1} + n_2V_2^{-1})^{-1}) \\
&\quad + (1 - B)^2B^{-1}\text{tr}(QA(n_1^{-1}V_1 + n_2^{-1}V_2)A^T) \\
&= (2.22)
\end{align*}
\]

Finally, from (2.8) with \( c = p - 2 \), (2.10) and (2.22), it follows that \( RSL(\xi; e_F \theta, W) = |r(\xi, e_F \theta) - r(\xi, e_R)|/|r(\xi, W) - r(\xi, e_R)| \)

\[
\begin{align*}
\frac{\text{tr}(Q(n_1V_1^{-1} + n_2V_2^{-1})^{-1})}{\text{tr}(Q(n_1V_1^{-1} + n_2V_2^{-1})^{-1})} + \frac{2(n_1 + n_2 - 1)}{(n_1 + n_2 - 2)p + 2}
\end{align*}
\]

which is less than one if and only if

\[
\{(1 - B)/B\}^2 > 2(n_1 + n_2 - 1)/\{(n_1 + n_2 - 2)p + 2\}
\]

(2.24)

**Remark 2.2** The fact that \( e_F \theta \) does not dominate \( W \) uniformly is not at all surprising. If, for example, \( r^2 \) is very small and \( \mu_1 \) is nearly degenerate at \( \nu \), then \( W \) is much closer to \( \nu \) than \( e_F \theta \). Indeed, in this case \( B = \sigma^2/(\sigma^2 + r^2) \) is very close to 1 so that (2.24) cannot hold. However, when \( \sigma^2 \leq r^2 \), then \( B \leq \frac{1}{2} \leftrightarrow (1 - B)/B \geq 1 \) so that (2.24) holds.
3. Minimax Estimation

It is well known that under the loss given in (2.2), \( \hat{X}_1 \) is a minimax estimator of \( \mu \) with constant risk \( n_1^{-1} \text{tr}(QV_1) \). In this section, first we find a class of estimators including \( e_{EB} \) as a member which dominates \( \hat{X}_1 \) under certain conditions, and then investigate whether \( e_{EB} \) satisfies these conditions.

With this end, first write

\[
F = \left( Y^T (n_1^{-1}V_1 + n_2^{-1}V_2)^{-1}Y \right) / \left\{ \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) / ((n_1 + n_2 - 2)p + 2) \right\} \tag{3.1}
\]

and consider the class of estimators

\[
\mu_1^\phi = \hat{X}_1 - (\phi(F)/F)(X_1 - W) \tag{3.2}
\]

for estimating \( \mu \). Note that \( e_{EB} \) belongs to this class with \( \phi(F) = p - 2 \). We now compute the frequentist risk of the estimator \( \mu_1^\phi \) (i.e. without any reference to the prior \( \xi \)). Throughout this section, \( E \) denotes expectation conditional on \( \mu_1 \) and \( \mu_2 \).

**Theorem 3.1**

\[
E[(\mu_1^\phi - \mu_1)^T Q(\mu_1^\phi - \mu_1)]/\sigma^2 = n_1^{-1} \text{tr}(QV_1) - 2E \left[ \frac{\phi(F)}{F} \text{tr}(\Lambda^T Q \Lambda V) + 2(\phi'(F) - \frac{\phi(F)}{F}) \frac{Y^T \Lambda^T Q \Lambda Y}{Y^T V^{-1}Y} \right] \\
+ \sigma^2 E[I \left( \frac{\phi^2(F)}{F^2} \right) Y^T \Lambda^T Q \Lambda Y] \tag{3.3}
\]

where \( V = n_1^{-1}V_1 + n_2^{-1}V_2 \).

**Proof:** First write

\[
E[(\mu_1^\phi - \mu_1)^T Q(\mu_1^\phi - \mu_1)] \\
= E[(\hat{X}_1 - \mu_1)^T Q(\hat{X}_1 - \mu_1)] \\
- 2(\phi(F)/F) Y^T \Lambda^T Q(\hat{X}_1 - \mu_1) \\
+ (\phi^2(F)/F^2) Y^T \Lambda^T Q \Lambda Y \tag{3.4}
\]

where we have used the fact that \( \hat{X}_1 - W = \Lambda Y \). Next writing \( \tilde{X}_1 = W + \Lambda Y \) and correspondingly \( \mu_1 = \mu + \Lambda \mu_0 \) where \( \mu = (n_1 V_1^{-1} + n_2 V_2^{-1})^{-1}(n_1 V_1^{-1} \mu_1 + n_2 V_2^{-1} \mu_2) \) and \( \mu_0 = \mu_1 - \mu_2 \), one gets

\[
E[(\phi(F)/F) Y^T \Lambda^T Q(\tilde{X}_1 - \mu_1)] \\
= E[(\phi(F)/F) Y^T \Lambda^T Q((W - \mu + \Lambda(Y - \mu_0))] \\
= E[(\phi(F)/F) Y^T \Lambda^T Q\Lambda(Y - \mu_0)] \tag{3.5}
\]
where in the final step of (3.5), one uses the independence of \((Y, \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2))\) with \(W\) as well as \(E(W) = \mu_i\). Now since \(V\) is p.d., there exists a nonsingular \(D\) such that \(D^{-1}V(D^{-1})^T = I_p\). Write \(Z = D^{-1}Y\) and \(\eta_0 = D^{-1}\mu_0\). Then \(Z \sim N_p(\eta_0, \sigma^2 I_p)\).

We rewrite

\[
Y^T \Lambda^T Q A (Y - \mu_0) = Z^T U (Z - \eta_0),
\]

where \(U = ((u_{ij})) = D^T \Lambda^T Q A D\). Also, in terms of \(Z, F = Z^T Z / \{\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) / ((n_1 + n_2 - 2)p + 2)\}\). Now using Stein’s identity (cf. Stein (1981)), the independence of \(Z\) and \(\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)\), and (3.6),

\[
E[(\phi(F)/F) Z^T U (Z - \eta_0)]
\]

\[
= \sigma^2 \sum_{i=1}^p E \left[ \frac{\partial}{\partial Z_i} \left\{ \frac{\phi(F)}{F} \sum_{j=1}^p u_{ij} Z_j \right\} \right]
\]

\[
= \sigma^2 \sum_{i=1}^p E \left[ \frac{\phi(F)}{F} \frac{\text{tr}(U)}{2} + 2 \left\{ \frac{\phi'(F)}{F} - \frac{\phi(F)}{F^2} \right\} \frac{Z^T U Z}{\{\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) / ((n_1 + n_2 - 2)p + 2)\}} \right]
\]

\[
= \sigma^2 E \left[ \frac{\phi(F)}{F} \frac{\text{tr}(\Lambda^T Q A V)}{2} + 2 \left\{ \frac{\phi'(F)}{F} - \frac{\phi(F)}{F^2} \right\} \frac{Y^T \Lambda^T Q A Y}{Y^T V^{-1} Y} \right]
\]

\[
= \sigma^2 E \left[ \frac{\phi(F)}{F} \frac{\text{tr}(\Lambda^T Q A V)}{2} + 2 \left\{ \frac{\phi'(F)}{F} - \frac{\phi(F)}{F^2} \right\} \frac{Y^T \Lambda^T Q A Y}{Y^T V^{-1} Y} \right] \tag{3.7}
\]

The theorem follows now from (3.3), (3.4) and (3.7).

Next in this section we find an upper bound for \(E[(\phi(F)/F^2) Y^T \Lambda^T Q A Y]\). We first get the inequality

\[
E[(\phi(F)/F^2) Y^T \Lambda^T Q A Y]
\]

\[
= E \left[ \frac{\phi(F)}{F^2} \cdot \frac{Y^T \Lambda^T Q A Y}{Y^T V^{-1} Y} \cdot \frac{\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{((n_1 + n_2 - 2)p + 2)} \right]
\]

\[
\leq \chi_1(\Lambda^T Q A V) E[h^2(F) F \cdot \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) / ((n_1 + n_2 - 2)p + 2)] \tag{3.8}
\]

where \(\chi_1(\Lambda^T Q A V)\) denotes the largest eigen value of \(\Lambda^T Q A V\) and \(h(F) = \phi(F) / F\).

Next applying (2.18) of Efron and Morris (1976), one gets

\[
E[h^2(F) F \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) / ((n_1 + n_2 - 2)p + 2)]
\]
\[
E = E\left[\frac{(n_1 + n_2 - 2)p}{(n_1 + n_2 - 2)p + 2} \cdot h^2(F) F + \frac{2}{(n_1 + n_2 - 2)p + 2} \cdot \frac{\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{F} \right] \\
\cdot (2h(F)h'(F)F + h^2(F)) \left( - \frac{\text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2)}{((n_1 + n_2 - 2)p + 2)} \right)
\]
\[
= \sigma^2 E \left[ \frac{(n_1 + n_2 - 2)p}{(n_1 + n_2 - 2)p + 2} \cdot \frac{\phi^2(F)}{F} \\
- 2 \frac{F}{(n_1 + n_2 - 2)p + 2} \cdot \left\{ 2 \frac{\phi'(F)}{F} - \frac{\phi(F)}{F^2} \right\} \phi(F) + \frac{\phi^2(F)}{F^2} \right] \\
= \sigma^2 E \left[ \frac{\phi^2(F)}{F} - \frac{4}{(n_1 + n_2 - 2)p + 2} \phi(F) \phi'(F) \right] (3.9)
\]

From (3.8) and (3.9), one gets

\[
E \left[ \frac{\phi^2(F)}{F^2} \cdot (Y^T \Lambda Y) \right] \\
\leq \sigma^2 c_1(\Lambda Y) E \left[ \frac{\phi^2(F)}{F} - \frac{4}{(n_1 + n_2 - 2)p + 2} \phi(F) \phi'(F) \right] (3.10)
\]

Combining (3.3) and (3.10), one gets

\[
\sigma^{-2} E[(\mu_1^* - \mu_1)^T Q(\mu_1^* - \mu_1) - (X_1 - \mu_1)^T Q(X_1 - \mu_1)] \\
\leq -2E \left[ \frac{\phi(F)}{F} \cdot \text{tr}(\Lambda Y) + 2(\phi'(F) - \frac{\phi(F)}{F^2}) \frac{Y^T \Lambda Y}{Y^T V^{-1} Y} \right] \\
+ ch_1(\Lambda Y) E \left[ \frac{\phi^2(F)}{F} - \frac{4}{(n_1 + n_2 - 2)p + 2} \phi(F) \phi'(F) \right] (3.11)
\]

The following theorem is now easy to prove from (3.11). Recall that \( \Lambda = (n_1V_1^{-1} + n_2V_2^{-1})^{-1}n_1V_1^{-1}V_1 + n_2^{-1}V_2 \).

**Theorem 3.2** Suppose that

(i) \( \text{tr}(\Lambda Y) > 2c_1(\Lambda Y) \)

(ii) \( 0 < \phi(F) < 2\left| \frac{\text{tr}(\Lambda Y)}{c_1(\Lambda Y)} - 2 \right| \) and

(iii) \( \phi(F) \uparrow \) in \( F \)

hold. Then \( \sigma^{-2} E[(\mu_1^* - \mu_1)^T Q(\mu_1^* - \mu_1) - (X_1 - \mu_1)^T Q(X_1 - \mu_1)] < 0 \) for all \( \mu_1 \) and \( \mu_2 \).
\textbf{Proof:} Using (iii), it follows from (3.11) that

\[
\sigma^2 E[(\mu^* - \mu_1)^T Q(\mu^* - \mu_1) - (\bar{X}_1 - \mu_1)^T Q(\bar{X}_1 - \mu_1)] \\
\leq 2E \left[ -\frac{\phi(F)}{F} \text{tr}(\Lambda^T QAV) + \frac{2\phi(F)}{F} \frac{Y^T A^T QAY}{Y^T V^{-1} Y} + \frac{1}{2} \frac{\phi^2(F)}{F} \chi_1(\Lambda^T QAV) \right] \\
\leq 2E \left[ -\frac{\phi(F)}{F} \text{tr}(\Lambda^T QAV) + 2\frac{\phi(F)}{F} \chi_1(\Lambda^T QAV) + \frac{1}{2} \frac{\phi^2(F)}{F} \chi_1(I^T QAV) \right] \\
= 2E \left[ -\frac{\phi(F)}{2F} \chi_1(\Lambda^T QAV) \left\{ 2 \left( \frac{\text{tr}(\Lambda^T QAV)}{\chi_1(\Lambda^T QAV)} - 2 \right) - \phi(F) \right\} \right] \\
< 0 \tag{3.12}
\]

using conditions (i) and (ii) of the theorem.

\textbf{Remark 3.1} It is an immediate consequence of the above theorem that if condition (i) of Theorem 3 holds, and \(0 < p - 2 < 2/\{\text{tr}(\Lambda^T QAV) / \chi_1(\Lambda^T QAV) - 2\}\), then the EB estimators \(e_{EB}\) dominates \(\bar{X}_1\). In particular, if \(Q = V_1 = V_2 = I_p\), then \(\text{tr}(\Lambda^T QAV) = p \chi_1(\Lambda^T QAV)\), and hence \(e_{EB}\) dominates \(\bar{X}_1\) for \(p \geq 3\).

In the remainder of this section we show how a modified EB estimator can dominate the PTE. Once again, an appeal to Theorem 3.1 is made.

A PTE \(\delta_{PTE}\) of \(\mu_1\) is of the form \(\delta_{PTE} = g(F)\bar{X}_1 + (1 - g(F))W = \bar{X}_1 - (1 - g(F))(\bar{X}_1 - W)\) where \(g(F) = I[F > d]\) for some positive constant \(d\), and \(I\) denotes the usual indicator function. The choice of \(d\) is governed by the level of significance that is used for testing \(H_0 : \mu_1 = \mu_2\). We propose the rival estimator

\[
\delta_{MEN} = \bar{X}_1 - (1 - (1 - \frac{c}{F})g(F))(\bar{X}_1 - W) \\
= W + (1 - \frac{c}{F})g(F)(\bar{X}_1 - W) \tag{3.13}
\]

which is a modified version of \(e_{EB}\) with \(p - 2\) replaced by a general \(c\). Note that \(\delta_{MEN} = W\) when \(g(F) = 0\), but \(\delta_{MEN} = \delta_{EB}\) when \(g(F) = 1\). The following theorem is then proved.

\textbf{Theorem 3.3} Suppose condition (i) of Theorem 3.2 holds and \(0 < c < 2\left\{\frac{\text{tr}(\Lambda^T QAV)}{\chi_1(\Lambda^T QAV)} - 2\right\}\). Then

\[
\sigma^2 E[|\delta_{MEN} - \mu_1|^2 Q(\delta_{MEN} - \mu_1) - (\delta_{PTE} - \mu_1)^T Q(\delta_{PTE} - \mu_1)|] < 0 \tag{3.14}
\]

for all \(\mu_1\) and \(\mu_2\).
Proof:

Write $\phi_1(F) = F(1 - g(F))$ and $\phi_2(F) = F(1 - (1 - \frac{c}{F})g(F)) = \phi_1(F) + cg(F)$. Then $\delta_{TF} = \tilde{X}_1 - (\phi_1(F)/F)(\tilde{X}_1 - W)$ while $\delta_{MF} = \tilde{X}_1 - (\phi_2(F)/F)(\tilde{X}_1 - W)$. Note that both $\phi_1(F)$ and $\phi_2(F)$ are differentiable everywhere except at $F = d$. Thus $\phi'_1(F)$ and $\phi'_2(F)$ are defined a.e. (Lebesgue). Moreover, $\phi_1(F) - \phi_2(F) = -cg(F)$, $\phi'_1(F) - \phi'_2(F) = -c^2g^2(F) = -c^2g(F)$ and $\phi'_1(F) = \phi'_2(F) = 1 - g(F)$ a.e. Lebesgue.

Then, applying Theorem 3.1 twice once with $\phi(F) = \phi_1(F)$, and next with $\phi(F) = \phi_2(F)$, one gets

Left hand side of (3.14)

$$
= -2E \left[ \frac{cg(F)}{F} \text{tr}(A^TQAV) - \frac{2}{F}cg(F)Y^TA^TQAY \right] \\
+ \sigma^{-2}E \left[ \frac{c^2g^2(F)}{F^2} \cdot (Y^TA^TQAY) \right]
$$

$$
\leq -2E \left[ \frac{cg(F)}{F} \text{tr}(A^TQAV) - \frac{2}{F}cg(F)\text{ch}_1(A^TQAV) \right] \\
+ \sigma^{-2}E \left[ \frac{c^2g^2(F)}{F^2} \cdot F \cdot \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \frac{\text{ch}_1(A^TQAV)}{(n_1 + n_2 - 2)p + 2} \right]
$$

$$
\leq -2E \left[ \frac{cg(F)}{F} \text{tr}(A^TQAV) - \frac{2}{F}cg(F) \cdot \text{ch}_1(A^TQAV) \right] \\
+ \sigma^{-2}\text{ch}_1(A^TQAV)E \left[ \frac{c^2g^2(F)}{F^2} \cdot F \cdot \frac{\text{tr}(A^TQAV)}{(n_1 + n_2 - 2)p + 2} \right]
$$

Applying (2.18) of Efron and Morris (1976) again with $\phi(F) = g(F)$ so that $\phi'(F) = 0$ a.e. Lebesgue, one gets

$$
E \left[ \left( \frac{g^2(F)}{F^2} \right) F \text{tr}(V_1^{-1}S_1 + V_1^{-1}S_2)/((n_1 + n_2 - 2)p + 2) \right] = \sigma^2 E|g^2(F)/F| = \sigma^2 E|g(F)/F|.
$$

Now from (3.15) and (3.16), left hand side of (3.14)

$$
\leq -E \left[ \frac{cg(F)}{F} \text{ch}_1(A^TQAV) \left\{ 2 \left( \frac{\text{tr}(A^TQAV)}{\text{ch}_1(A^TQAV)} - 2 \right) - c \right\} \right]
$$

by using the upper bound of $c$ given in this theorem. The proof of the theorem is complete.
Remark 3.2  Note that when $Q = V_1 = V_2 = I_p$, the conditions of the theorem hold when $0 < c < 2(p - 2)$, and in particular when $c = p - 2$, $p \geq 3$. 
4. Hierarchical Bayes Estimation

Section 2 is devoted to classical empirical Bayes estimation, i.e. when the unknown prior parameters are estimated by classical methods of estimation such as uniformly minimum variance unbiased estimation, maximum likelihood estimation, best invariant estimation etc. Instead, one can assign prior distributions (proper or improper) to the hyperparameters, and come up with hierarchical Bayes (HB) estimators of \( \mu_1 \).

Note that in a classical EB approach, the lower stage Bayesian analysis is performed as if the hyperparameters were known a priori. This approach ignores the error associated with the estimation of the hyperparameters. On the other hand, the HB approach models the uncertainty of the hyperparameters by the second stage prior. Accordingly, unlike positive part EB estimators, the HB estimators are smooth, and bear the potentiality of being admissible.

To introduce the HB model, first note that as in Section 2, one may start with the minimal sufficient statistic \((X_1, X_2, \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2))\). Write \( r = \sigma^2 \) and \((pr)^{-1} = \tau^2\) i.e. \( \rho = \sigma^2 / \tau^2 \). Now conditional on \( \mu_1, \mu_2 \) and \( r \), \( X_1, X_2 \) and \( U - \text{tr}(V_1^{-1}S_1 + V_2^{-1}S_2) \) are mutually independent with \( X_1 \sim N_p(\mu_1, (n_1 pr)^{-1}V_1) \), \( X_2 \sim N_p(\mu_2, (n_2 pr)^{-1}V_2) \) and \( U \sim r^{-1} \chi^2_{n_1+n_2-2p} \). Next we assume that conditional on \( \nu, \rho \) and \( r \), \( \mu_1 \) and \( \mu_2 \) are mutually independent with \( \mu_1 \sim N(\nu, (pr)^{-1}n_1^{-1}V_1) \) and \( \mu_2 \sim N(\nu, (pr)^{-1}n_2^{-1}V_1) \). Also, it is assumed that \( \nu, \rho \) and \( r \) are mutually independent with \( \nu \) uniform on \( R^p \), \( \rho \) has the type II Beta distribution with pdf \( h_1(\rho) \propto \rho^{m-1}(1 + \rho)^{-(m+1)} \) where \( m(>0) \) is known, while \( r \) has a gamma distribution with pdf \( h_2(r) \propto \exp(-\frac{1}{2}r) r^{\delta-1}, \alpha(>0) \) and \( \delta(>0) \) being known. We shall aim at finding the posterior distribution of \( \mu = (\mu_1^T, \mu_2^T)' \) given \( X_1, X_2 \) and \( u \).

First note that the joint prior distribution of \( \mu_1, \mu_2, \nu, r \) and \( \rho \) is given by

\[
\begin{align*}
f(\mu_1, \mu_2, \nu, r, \rho) & \propto (pr)^\rho \\
& \cdot \exp\left(-\frac{pr}{2} \left\{ n_1(\mu_1 - \nu)^TV_1^{-1}(\mu_1 - \nu) + n_2(\mu_2 - \nu)^TV_2^{-1}(\mu_2 - \nu) \right\} \right) \\
& \cdot h_1(\rho) h_2(r)
\end{align*}
\]

(4.1)

Next observe that

\[
\begin{align*}
n_1(\mu_1 - \nu)^TV_1^{-1}(\mu_1 - \nu) &= (\mu_2 - \nu)^TV_2^{-1}(\mu_2 - \nu) \\
&= \left((\nu - \mu_2)^TV_2^{-1}(\nu - \mu_2)\right)^T \\
&+ n_1\mu_1^TV_1^{-1}\mu_1 + n_2\mu_2^TV_2^{-1}\mu_2 - \mu_1^TV_1^{-1}\mu_1 \\
&+ n_2\mu_2^TV_2^{-1}\mu_2 \quad \text{with } V_1^{-1} = n_1V_1^{-1} + n_2V_2^{-1} \quad \text{and } V_2^{-1} = n_1V_1^{-1} + n_2V_2^{-1} \quad \text{by the formula (4.2)}
\end{align*}
\]

(4.2)

where one may recall that \( \mu_1 = (n_1V_1^{-1} + n_2V_2^{-1})^{-1}(n_1V_1^{-1}\mu_1 + n_2V_2^{-1}\mu_2) = (V_1^{-1})^{-1}(n_1V_1^{-1}\mu_1 + n_2V_2^{-1}\mu_2) \) with \( V_1^{-1} - n_1V_1^{-1} + n_2V_2^{-1} \). Now integrating with respect to \( \nu \), one gets the joint pdf of \( \mu_1, \mu_2, r \) and \( \rho \) in the form

\[
\begin{align*}
&\propto (pr)^{p/2} \exp\left(-\frac{pr}{2} \left\{ n_1\mu_1^TV_1^{-1}\mu_1 + n_2\mu_2^TV_2^{-1}\mu_2 - \mu_1^TV_1^{-1}\mu_1 \right\} \right) h_1(\rho) h_2(r)
\end{align*}
\]

(4.3)
The exponent in (4.3) is easily simplified as

\[ n_1 \mu_1^TV_1^{-1}\mu_1 + n_2 \mu_2^TV_2^{-1}\mu_2 - \mu^TV^{-1}\mu. \]

\[ = \mu_1^T\{n_1V_1^{-1} - n_1V_1^{-1}V_1n_1V_1^{-1}\}\mu_1 + \mu_2^T\{n_2V_2^{-1} - n_2V_2^{-1}V_2n_2V_2^{-1}\} \]

\[ - \mu_1n_1V_1^{-1}V_2n_2V_2^{-1}\mu_2 - \mu_2n_2V_2^{-1}V_1n_1V_1^{-1}\mu_1 \]  

(4.4)

where \( V_r = (n_1V_1^{-1} + n_2V_2^{-1})^{-1} \). Also, the joint pdf of \( \bar{X}_1, \bar{X}_2 \) and \( U \) conditional on \( \mu_1, \mu_2 \) and \( r \) is given by

\[
f(\bar{x}_1, \bar{x}_2, u|\mu_1, \mu_2, r) \propto r^n \exp\left[-\frac{r}{2}\{n_1(\bar{x}_1 - \mu_1)^TV_1^{-1}(\bar{x}_1 - \mu_1) + n_2(\bar{x}_1 - \mu_2)^TV_2^{-1}(\bar{x}_1 - \mu_2)\}\right] \]

\[ \times \exp\left(-\frac{ru}{2}\right)u^{(n_1 + n_2 - 2)n/2 - 1}(n_1 + n_2 - 2)n/2 \]  

(4.5)

Next we calculate

\[ G = n_1(\mu_1 - \bar{x}_1)^TV_1^{-1}(\mu_1 - \bar{x}_1) + n_2(\mu_2 - \bar{x}_2)^TV_2^{-1}(\mu_2 - \bar{x}_2) \]

\[ + \rho\{n_1\mu_1^TV_1^{-1}\mu_1 + n_2\mu_2^TV_2^{-1}\mu_2 - \mu^TV^{-1}\mu\} \]  

(4.6)

which is needed to derive the posterior distribution of \( \mu \) given \( \bar{x}_1, \bar{x}_2 \) and \( u \). Using (4.4) and straightforward algebra, one gets

\[ G = \mu_1^TD_{11}\mu_1 + \mu_2^TD_{22}\mu_2 - 2\mu_1^TD_{12}\mu_2 - 2n_1\bar{x}_1^TV_1^{-1}\mu_1 - 2n_2\bar{x}_2^TV_2^{-1}\mu_2 \]

\[ + n_1\bar{x}_1^TV_1^{-1}\bar{x}_1 + n_2\bar{x}_2^TV_2^{-1}\bar{x}_2 \]  

(4.7)

where

\[ D_{11} = n_1V_1^{-1} + \rho\{n_1V_1^{-1} - n_1V_1^{-1}V_1n_1V_1^{-1}\}, \]

\[ D_{22} = n_2V_2^{-1} + \rho\{n_2V_2^{-1} - n_2V_2^{-1}V_2n_2V_2^{-1}\}, \]

\[ D_{12} = \rho n_1V_1^{-1}V_2n_2V_2^{-1} \]  

(4.8)

We now write \( G \) as \( G_1 + G_2 \) where

\[
G_1 = [(\mu_1 - A_{11}\bar{x}_1 - A_{12}\bar{x}_2)^TD_{11}(\mu_1 - A_{11}\bar{x}_1 - A_{12}\bar{x}_2) + (\mu_2 - A_{21}\bar{x}_1 - A_{22}\bar{x}_2)^TD_{22}(\mu_2 - A_{21}\bar{x}_1 - A_{22}\bar{x}_2) - 2(\mu_1 - A_{11}\bar{x}_1 - A_{12}\bar{x}_2)^TD_{12}(\mu_2 - A_{21}\bar{x}_1 - A_{22}\bar{x}_2)] \]

(4.9)

and
\[ G_2 = [n_1x_1^TV_1^{-1}x_1 + n_2x_2^TV_2^{-1}x_2 - (A_{11}x_1 + A_{12}x_2)^TD_{11}(A_{11}x_1 + A_{12}x_2) \\
- (A_{21}x_1 + A_{22}x_2)^TD_{22}(A_{21}x_1 + A_{22}x_2) \\
+ 2(A_{11}x_1 + A_{12}x_2)^TD_{12}(A_{21}x_1 + A_{22}x_2)] \] (4.10)

From (4.7), (4.9) and (4.10), it follows that \( A_{11}, A_{12}, A_{21} \) and \( A_{22} \) satisfy

\[
\begin{align*}
D_{11}A_{11} &= D_{12}A_{21} - n_1V_1^{-1} \\
D_{22}A_{22} &= D_{12}^TA_{12} - n_2V_2^{-1} \\
D_{11}A_{12} &= D_{12}A_{22} \\
D_{22}A_{21} &= D_{12}^TA_{11}
\end{align*}
\] (4.11)

which can be rewritten as

\[
\begin{align*}
A_{12} - D_{12}^TD_{12}A_{22}A_{21} &= D_{22}^TD_{12}^TA_{11}, \\
(D_{11} - D_{12}^TD_{12}D_{12}^TD_{11})A_{11} &= n_1V_1^{-1}, \\
(D_{22} - D_{12}^TD_{11}D_{12})A_{22} &= n_2V_2^{-1}
\end{align*}
\] (4.12)

The following lemma whose proof is given in the Appendix is crucial to further simplify \( G_2 \). Recall that \( B = \sigma^2/((\sigma^2 + \tau^2) - \rho/(1 + \rho)) \) and \( W = (n_1V_1^{-1} + n_2V_2^{-1})(n_1x_1^{-1}x_1 + n_2x_2^{-1}x_2) - V_i(n_1V_1^{-1}x_1 + n_2V_2^{-1}x_2) \).

**Lemma 4.1**

\[
\begin{align*}
A_{11}x_1 + A_{12}x_2 &= (1 - B)x_1 + BW - b_1 \text{(say)} \quad (4.13) \\
A_{21}x_1 + A_{22}x_2 &= (1 - B)x_2 + BW - b_2 \text{(say)} \quad (4.14)
\end{align*}
\]

From (4.10), (4.13) and (4.14), \( G_2 \) can be simplified as

\[
\begin{align*}
G_2 &= n_1x_1^TV_1^{-1}x_1 + n_2x_2^TV_2^{-1}x_2 \\
&\quad + \{[(1 - B)x_1 - BW]D_{11}\{[(1 - B)x_1 - BW] \\
&\quad + [(1 - B)x_2 - BW]D_{12}\{[(1 - B)x_2 - BW] \\
&\quad + 2\{(1 - B)x_1 - BW\}D_{12}\{[(1 - B)x_2 - BW] \\
&\quad + \hat{x}_1^T[n_1V_1^{-1} - [(1 - B)] \\
&\quad + Bn_1V_1^{-1}V_1]D_{11}\{[(1 - B)]I + Bn_1V_1^{-1}V_1\} \\
&\quad + Bn_1V_1^{-1}V_1]D_{22}(Bn_1V_1^{-1}V_1^{-1})
\end{align*}
\]
\[ D_{11} + D_{22} - 2D_{12} = (1 + \rho)(n_1V_1^{-1} + n_2V_2^{-1}) - \rho(n_1V_1^{-1} + n_2V_2^{-1})V_1(n_1V_1^{-1} + n_2V_2^{-1}) = n_1V_1^{-1} + n_2V_2^{-1} \ (\text{since } V_1 = n_1V_1^{-1} + n_2V_2^{-1}) \]

\[ D_{11}^* = n_1V_1^{-1} - n_1V_1^{-1}V_1n_1V_1^{-1} \]

\[ D_{22}^* = n_2V_2^{-1} - n_2V_2^{-1}V_2n_2V_2^{-1} \]

\[ D_{12}^* = n_1V_1^{-1}V_1n_2V_2^{-1} \]

Using (4.8) and (4.16), it is possible to simplify \( G \) considerably. This is done in the following Lemma whose proof appears in the Appendix.

**Lemma 4.2** \( G_2 = B|x_1^T(n_1V_1^{-1} - n_1V_1^{-1}V_1n_1V_1^{-1})x_1 + x_2^T(n_2V_2^{-1} - n_2V_2^{-1}V_2n_2V_2^{-1})x_2 - 2x_1^T(n_1V_1^{-1}V_1n_2V_2^{-1})x_2| \)

Therefore, from (4.9), Lemma 4.1 and Lemma 4.2, \( G \) can be written as

\[ G = (\mu_1 - b_1)^T D_{11}(\mu_1 - b_1) + (\mu_2 - b_2)^T D_{22}(\mu_2 - b_2) - 2(\mu_1 - b_1)^T D_{12}(\mu_2 - b_2) + B|x_1^T D_{11} + x_2^T D_{22} + x_2 - 2x_1^T D_{12} + x_2| \]

where

\[ D_{11}^* = n_1V_1^{-1} - n_1V_1^{-1}V_1n_1V_1^{-1} \]

\[ D_{22}^* = n_2V_2^{-1} - n_2V_2^{-1}V_2n_2V_2^{-1} \]

\[ D_{12}^* = n_1V_1^{-1}V_1n_2V_2^{-1} \]

Returning to (4.3) and (4.5), the joint pdf of \( \bar{\mu}, \bar{\mu}, u, \mu_1, \mu_2, r \) and \( \rho \) is given by
\[ f(\bar{x}_1, \bar{x}_2, u, \mu_1, \mu_2, r, \rho) \]
\[ \propto r^n (pr)^{n/2} \cdot \exp \left[ -\frac{r}{2} \frac{C}{\rho} \right] \cdot \exp \left[ -ru/2 \right] \]
\[ u{(n_1 + n_2 - 2)p/2 - 1}, r{(n_1 + n_2 - 2)p/2}h_1(\rho)h_2(r) \]

It follows from (4.17) and (4.19) that conditional on \( \bar{x}_1, \bar{x}_2, u, r \) and \( \rho \),
\[ \left( \begin{array}{c} \mu_1 \\ \mu_2 \end{array} \right) \sim N_{2p} \left[ \left( \begin{array}{c} b_1 \\ b_2 \end{array} \right), r^{-1} \left( \begin{array}{cc} D_{11} & -D_{12} \\ -D_{12}^T & D_{22} \end{array} \right)^{-1} \right] \]  
(4.20)

Also, integrating out with respect to \( \mu_1 \) and \( \mu_2 \), it follows from (4.19) that the joint pdf of \( X_1, \bar{X}_2, U, r \) and \( \rho \) is given by
\[ f(\bar{x}_1, \bar{x}_2, u, r, \rho) \propto (pr)^{n/2} \left| D_{11} - D_{12} \right|^{-\frac{1}{2}} \exp \left[ -\frac{r}{2} (u + R SS_H) \right] \]
\[ \cdot r{(n_1 + n_2 - 2)p/2} \cdot u{(n_1 + n_2 - 2)p/2} \cdot \rho^{-1} (1 + \rho)^{-(m+1)} \cdot \exp(-\alpha r/2) r^{k-1} \]

where
\[ SS_H = \bar{x}_1^T D_{11} + \bar{x}_1 + \bar{x}_2^T D_{22} + \bar{x}_2 - 2\bar{x}_1^T D_{12} + \bar{x}_2 \]

(4.22)

Now, from (4.8), one gets
\[
\begin{vmatrix}
D_{11} & D_{12} \\
D_{12}^T & D_{22}
\end{vmatrix}
\]
\[
\begin{vmatrix}
(1 + \rho) \left( \begin{array}{cc} n_1 V_1 & 0 \\ 0 & n_2 V_2 \end{array} \right) & \rho \left( \begin{array}{cc} n_1 V_1 & n_1 V_1 \\ n_2 V_2 & n_2 V_2 \end{array} \right) \\
(1 + \rho) r^2 \left( \begin{array}{cc} n_1 V_1 & 0 \\ 0 & n_2 V_2 \end{array} \right) & \rho^2 \left( \begin{array}{cc} n_1 V_1 & n_1 V_1 \\ n_2 V_2 & n_2 V_2 \end{array} \right)
\end{vmatrix}
\]
\[
\begin{vmatrix}
I_{2p} & B \left( \begin{array}{cc} \frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \left( \begin{array}{cc} n_1 V_1 & 1 \\ n_2 V_2 & 1 \end{array} \right) \left( \begin{array}{cc} \frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \end{vmatrix}
\]
\[
\begin{vmatrix}
(1 + \rho) r^2 \left| n_1 V_1 \right| \left| n_1 V_1 \right| & \left| n_2 V_2 \right| \\
(1 + \rho) r^2 \left| n_1 V_1 \right| \left| n_2 V_2 \right| & I_p \end{vmatrix}
\]
\[
\left( \begin{array}{cc}
\frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \left( \begin{array}{cc} n_1 V_1 & 1 \\ n_2 V_2 & 1 \end{array} \right) \left( \begin{array}{cc} \frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \end{vmatrix}
\]
\[
\begin{vmatrix}
(1 + \rho) r \left| n_1 V_1 \right| \left| n_2 V_2 \right| & I_p \end{vmatrix}
\]
\[
\left( \begin{array}{cc}
\frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \left( \begin{array}{cc} n_1 V_1 & 1 \\ n_2 V_2 & 1 \end{array} \right) \left( \begin{array}{cc} \frac{1}{\sqrt{n_1}} & 0 \\ 0 & \frac{1}{\sqrt{n_2}} \end{array} \right) \end{vmatrix}
\]  
(4.23)
Hence, from (4.21) and (4.23), one gets

\[
f(\bar{x}_1, \bar{x}_2, u, r, \rho) \propto \rho^{r/2} (n_1 + n_2 - 1) \rho \exp \left[ -\frac{r}{2} (u + BSS_H + \alpha) \right] \\
\times u^{(n_1 + n_2 - 2) \rho / 2 - 1} \rho^{m-1} (1 + \rho)^{-m-1} \tag{4.24}
\]

Integrating out with respect to \( r \), one gets the joint pdf of \( \bar{X}_1, \bar{X}_2, U \) and \( \rho \) as

\[
f(\bar{x}_1, \bar{x}_2, u, \rho) \propto \left( \frac{\rho}{1 + \rho} \right)^{r/2} \rho^{m \rho - 1} u^{(n_1 + n_2 - 2) \rho / 2 - 1} (u + BSS_H + \alpha)^{(n_1 + n_2 - 1) \rho / 2 - \lambda} \\
\times \rho^{m-1} (1 + \rho)^{-m-1} \tag{4.25}
\]

Using the transformation \( \rho/(1 + \rho) = B \) provides the joint pdf of \( \bar{X}_1, \bar{X}_2, U \) and \( B \) as

\[
f(\bar{x}_1, \bar{x}_2, u, B) \propto B^{r/2 + m - 1} u^{(n_1 + n_2 - 2) \rho / 2 - 1} (u + BSS_H + \alpha)^{(n_1 + n_2 - 1) \rho / 2 - \lambda} \tag{4.26}
\]

Next observe from (4.20) and (4.13) that

\[
E(\mu_1 | B, \bar{x}_1, \bar{x}_2, u, r) = b_1 = (1 - B) \bar{x}_1 + BW.
\]

Hence the IH estimator of \( \mu_1 \) is

\[
E(\mu_1 | \bar{x}_1, \bar{x}_2, u) = \bar{x}_1 - E(B | \bar{x}_1, \bar{x}_2, u)(\bar{x}_1 - W) \tag{4.27}
\]

But, from (4.26), one gets

\[
E(B | \bar{x}_1, \bar{x}_2, u) = \frac{\int_0^1 B^r/2 \rho \rho^{m - 1} (u + BSS_H + \alpha)^{(n_1 + n_2 - 1) \rho / 2 - \lambda} dB}{\int_0^1 B^r/2 \rho^{m - 1} (u + BSS_H + \alpha)^{(n_1 + n_2 - 1) \rho / 2 - \lambda} dB} \tag{4.28}
\]

**Remark 4.1** From simultaneous diagonalization of \( n_1 V_1^{-1} \) and \( n_2 V_2^{-1} \), it is easy to show from (4.18) that

\[
D_{11} = D_{22} = D_{12} = (n_1 V_1^{-1} + n_2 V_2^{-1})^{-1},
\]

so that from (4.22) one gets

\[
SS_H = (\bar{x}_1 \bar{x}_2)^T (n_1 V_1^{-1} + n_2 V_2^{-1})^{-1} (\bar{x}_1 \bar{x}_2) \tag{4.30}
\]

which is precisely the numerator of \( F \) defined in (3.1).
Remark 4.2 It is sometimes possible to reduce the above HB estimator to an EB estimator of the form $\hat{x}_1 - (\phi(F)/E)(x_1 - W)$. Consider for example the situation when $\alpha = 0$ i.e., $R$ has the improper prior $h_2(r) = r^{k-1}$. Now writing $v = SSW/u$, we note from (4.30) that $F = ((n_1 + n_2 - 2)p + 2)v$. Also, for $\alpha = 0$, it follows from (4.28) that

$$E(B|x_1, x_2, u) = \int_0^1 B^{p/2 + 1}(1 + B)v^{(n_1 + n_2 - 2)p + 2} dB \int_0^1 B^{\xi + 1}(1 + B)v^{(n_1 + n_2 - 2)p + 2} dB$$

$$- v^{-1} \int_0^1 \left( \frac{1}{1 + Bv} \right)^{(n_1 + n_2 - 2)p + \xi - m + 1} B^v dB$$

$$+ \int_0^1 \left( \frac{1}{1 + Bv} \right)^{(n_1 + n_2 - 2)p + \xi - m + 1} Bv dB$$

$$- v^{-1} \int_0^u (1 + u)^{(n_1 + n_2 - 2)p + \xi - m + 1} du$$

$$+ \int_0^u (1 + u)^{(n_1 + n_2 - 2)p + \xi - m + 1} du (4.31)$$

From (4.31) it follows that $E(B | x_1, x_2, u)$ can be expressed as $\phi(v)/v = \phi(F)/F$.

Next note that integration by parts gives numerator of (4.31)

$$- v^{-1} \left\{ \left( \frac{1}{1 + v} \right)^{(n_1 + n_2 - 2)p + \xi - m + 1} \right\}$$

$$+ \int_0^u (1 + u)^{(n_1 + n_2 - 2)p + \xi - m + 1} du$$

$$- v \left\{ (n_1 + n_2 - 2)p + 2\delta - 2m - 2 \right\}$$

$$\int_0^u (1 + u)^{(n_1 + n_2 - 2)p + \xi - m + 1} du (4.32)$$

Hence from (4.31) and (4.32),

$$E(B|x_1, x_2, u) = \frac{p + 2m}{(p + 2m)((n_1 + n_2 - 2)p + 2)}$$

$$F((n_1 + n_2 - 2)p + 2\delta - 2m - 2) (4.33)$$

so that

$$\phi(F) = \frac{(p + 2m)((n_1 + n_2 - 2)p + 2)\delta - 2m - 2}{2(p - 2)}$$
if \((p + 2m)((n_1 + n_2 - 2)p + 2)b \leq 2(p - 2)(n_1 + n_2 - 2)p - 2m - 2)(\cdot \delta > c) \leftarrow p(2m(n_1 + n_2) + 6) \leq p(p - 4)(n_1 + n_2 - 2) + 4m + 8\) which holds whenever \(p \geq 5\) and \(m \geq \{(p - 4)(n_1 + n_2 - 2) - 6\}/2(n_1 + n_2)\), assuming \(n_1 + n_2 > 8\). Hence, for this choice of \(m\), \(\phi(F)\) satisfies condition (ii) of Theorem 3.2 for \(Q = V_1 - V_2 = I_p\). Also, for \(Q = V_1 - V_2 - I_p\), condition (i) of Theorem 3.2 automatically holds when \(p > 3\).

Finally, noting that \(v\) is strictly increasing in \(F\), and using the inequality

\[
\int_0^v \frac{v^{\alpha + 1}}{\nu} \frac{\nu^{\xi + m}(1 - u)^{n_1 + n_2 - 2m + \delta}}{m - 1} du
\]

one gets after direct differentiation \(\phi'(v) \geq 0\). Hence \(\phi'(v)\) is \(<\) in \(v\). Hence, condition (iii) of Theorem 3.2 also holds. Therefore, when \(\alpha = 0, Q = V_1 = V_2 = I_p, p \geq 5\) and \(0 < m < \{(p - 4)(n_1 + n_2 - 2) - 6\}/2(n_1 + n_2)\), the HB estimator obtained in (4.27) is minimax.

Remark 4.3 The conclusion given in Remark 4.2 bears strong resemblance to Strawderman (1971) in the one sample problem. However, the formulation here is much more general than the one given in Strawderman (1971) or Strawderman (1973). First, the estimator is not shrunk towards zero or a prespecified point, but is shrunk towards the pooled mean. In Strawderman (1971), \(r\) is assumed to be known, whereas in Strawderman (1973), \(r\) is assumed to belong to \((\gamma, \infty)\) for some \(\gamma > 0\). Our formulation is also more general than the one given in Morris (1983) because there \(r\) is assumed known and \((pr)^{-1}\) is given a uniform prior on \((0, \infty)\).
A. Proofs

Proof of Lemma 4.1: To prove (4.13), note from (4.8) that

\[
(D_{22} - D_{12}^T D_{11}^{-1} D_{12}) D_{12}^{-1} D_{11} = D_{22} D_{12}^{-1} D_{11} - D_{12}^T
\]

\[\sim n_2 V_2^{-1} (1 + \rho) \{ I - BV, n_2 V_2^{-1} \} \cdot \frac{1}{\rho} n_2, V_1, V_2, \left( n_1 V_1^{-1} \right) \cdot (1 + \rho) \{ I - BV, n_1 V_1^{-1} \} - \rho n_2 V_2^{-1} V, n_1 V_1^{-1}
\]

\[\sim ((1 + \rho)^2/\rho) \{ I - Bn_2 V_2^{-1} V \} V_1^{-1} (I - BV, n_1 V_1^{-1}) - \rho n_2 V_2^{-1} V, n_1 V_1^{-1}
\]

\[\sim ((1 + \rho)^2/\rho) \{ I - Bn_2 V_2^{-1} V \} \{(I - B)n_1 V_1^{-1} + n_2 V_2^{-1} \} (I - B) n_1 V_1^{-1} + n_2 V_2^{-1} V, n_1 V_1^{-1}
\]

\[\sim ((1 + \rho)^2/\rho) \{ I - Bn_2 V_2^{-1} V \} \{ I - B \} n_1 V_1^{-1} + n_2 V_2^{-1} V, n_1 V_1^{-1}
\]

\[\sim (n_1 V_1^{-1} + n_2 V_2^{-1} V) / B
\]

so that

\[D_{11}^{-1} D_{12} (D_{22} - D_{12}^T D_{11}^{-1} D_{12})^{-1} = BV.
\]

(A.1)

and

\[D_{22} - D_{12}^T D_{11}^{-1} D_{12} = (n_1 V_1^{-1} + n_2 V_2^{-1}) D_{11}^{-1} D_{12} / B
\]

which yields by symmetry

\[D_{11} - D_{12}^T D_{22}^{-1} D_{12} = (n_1 V_1^{-1} + n_2 V_2^{-1}) D_{12}^T D_{12} / B
\]

(A.2)

Hence from (4.8) one gets

\[(D_{11} - D_{12} D_{22}^{-1} D_{12}^T)^{-1} = B (D_{12}^T)^{-1} D_{22} (n_1 V_1^{-1} + n_2 V_2^{-1})^{-1}
\]

\[= B (V_1 V_2^{-1}) \cdot (I + \rho) n_2 V_2^{-1} (I - BV, n_2 V_2^{-1}) V
\]

\[= V_1 V_2^{-1} (I - BV, n_2 V_2^{-1}) V
\]

\[= V_1, V_2^{-1} (I - BV, n_2 V_2^{-1}) V
\]

(A.3)

so that

\[(D_{11} - D_{12} D_{22}^{-1} D_{12}^T)^{-1} n_1 V_1^{-1} - I \sim B V_1 n_2 V_2^{-1} V, n_1 V_1^{-1}
\]

(A.4)
which yields from (A.2)

\[
\begin{align*}
(D_{11} - D_{12}D_{22}^{-1}D_{12}^T)^{-1}n_1V_1^{-1} & = D_{11}^{-1}D_{12}(D_{22} - D_{12}^TD_{12}^{-1}D_{12})^{-1}n_1V_1^{-1} \\
& = I - B_{n_1}^{V_1^{-1}}n_2V_2^{-1}V_1^{-1}n_1V_1^{-1} \\
& = I - B_{n_1}^{V_1^{-1}}(n_2V_2^{-1} + n_1V_1^{-1})V_1^{-1}n_1V_1^{-1} \\
& = (1 - B)I
\end{align*}
\]

(4.13) now follows upon writing from (4.12)

\[
A_{11}\tilde{x}_1 + A_{12}\tilde{x}_2 = (D_{11} - D_{12}D_{22}^{-1}D_{12}^T)^{-1}n_1V_1^{-1}\tilde{x}_1 + D_{11}^{-1}D_{12}(D_{22} - D_{12}^TD_{12}^{-1}D_{12})^{-1}n_2V_2^{-1}\tilde{x}_2 \\
= ([D_{11} - D_{12}D_{22}^{-1}D_{12}^T]^{-1}n_1V_1^{-1} - D_{11}^{-1}D_{12}(D_{22} - D_{12}^TD_{12}^{-1}D_{12})^{-1}n_1V_1^{-1})\tilde{x}_1 \\
+ D_{11}^{-1}D_{12}(D_{22} - D_{12}^TD_{12}^{-1}D_{12})^{-1}(n_2V_2^{-1}\tilde{x}_2 + n_1V_1^{-1}\tilde{x}_1)
\]

and invoking (A.2) and (A.6). The proof of (4.14) is similar and hence omitted.

Proof of Lemma 4.2: The matrix appearing in $\tilde{x}_1^T|\tilde{x}_1$ in (4.15) is simplified as

\[
\begin{align*}
n_1V_1^{-1} & \{ (1 - B)I + Bn_1V_1^{-1}V_1 \} D_{11} \{ (1 - B)I + Bn_1V_1^{-1} \} \\
& + (Bn_1V_1^{-1}V_1)D_{22}(Bn_1V_1^{-1}V_1) + 2((1 - B)I + Bn_1V_1^{-1}V_1)D_{12}(Bn_1V_1^{-1}V_1) \\
& = n_1V_1^{-1} - (1 - B)^2D_{11} - (1 - B)(n_1V_1^{-1}V_1D_{11} + D_{11}n_1V_1^{-1}V_1) \\
& + 2B(1 - B)n_1V_1^{-1}V_1 \\
& + 2Bn_1V_1^{-1}V_1n_1V_1^{-1} \\
& + n_1V_1^{-1}(1 - B)^2\{ n_1V_1^{-1}(1 + \rho) \} \\
& + (1 - B)n_1V_1^{-1}V_1 \{ n_1V_1^{-1}(1 + \rho) \} \\
& + (1 - B)n_1V_1^{-1}V_1 \{ n_1V_1^{-1}(1 + \rho) \} \\
& + 2B(1 - B)n_1V_1^{-1}V_1n_2V_2^{-1}V_1n_1V_1^{-1} \\
& + 2Bn_1V_1^{-1}V_1n_1V_1^{-1} \\
& + n_1V_1^{-1}(1 + \rho)(1 - B)^2 \\
& + n_1V_1^{-1}V_1n_1V_1^{-1}(1 - B)^2 \\
& + 2B(1 - B)(1 + \rho - B^2) \\
& + 2\rho B(1 - B)n_1V_1^{-1}V_1n_1V_1^{-1}V_1n_1V_1^{-1}
\end{align*}
\]
\[ 2\rho B(1 - B)n_1 V_1^{-1}V.n_2 V_2^{-1}V.n_1 V_1^{-1} \]
\[ = Bn_1 V_1^{-1} + n_1 V_1^{-1}V.n_1 V_1^{-1}(\rho/(1 + \rho)^2) \]
\[ - 2\rho/(1 + \rho)^2 - \rho^2/(1 + \rho)^2 \]
\[ = B[n_1 V_1^{-1} - n_1 V_1^{-1}V.n_1 V_1^{-1}] \quad (A.7) \]

Analogously, the matrix appearing in \( \mathbf{A}_2^{T}\mathbf{A}_2 \) in (4.15) comes out as

\[ n_2 V_2^{-1} \]
\[ = \{(1 - B)I + Bn_2 V_2^{-1}V.\}D_{22}\{(1 - B)I + Bn_2 V_2^{-1}V.\} \]
\[ (Bn_2 V_2^{-1}V.)D_{11}(Bn_2 V_2^{-1}V.) + 2\{(1 - B)I + Bn_2 V_2^{-1}V.\}D_{12}(Bn_2 V_2^{-1}V.) \]
\[ - B[n_2 V_2^{-1} - n_2 V_2^{-1}V.n_2 V_2^{-1}] \quad (A.8) \]

We show that the matrix appearing in \( \mathbf{A}_2^{T}\mathbf{A}_2 \) in (4.15) is null i.e.,

\[ \{(1 - B)I + Bn_1 V_1^{-1}V.\}D_{11}(Bn_2 V_2^{-1}V.) \]
\[ - B\{(1 - B)I + Bn_1 V_1^{-1}V.\}D_{12}\{(1 - B)I + Bn_2 V_2^{-1}V.\} = 0 \quad (A.9) \]

Left hand side of (A.9)

\[ B(1 - B)D_{11}V.n_2 V_2^{-1} - B(1 - B)n_1 V_1^{-1}V.D_{22} + 2(1 - B)^2D_{12} \]
\[ + 2B(1 - B)(D_{12}V.n_2 V_2^{-1} + n_1 V_1^{-1}V.D_{12}) \]
\[ - B^2n_1 V_1^{-1}V.(D_{11} + D_{22} - 2D_{12})V.n_2 V_2^{-1} \]

(\text{using (4.8) and (4.16)})

\[ B(1 - B)\{(1 + \rho)n_1 V_1^{-1} - \rho n_1 V_1^{-1}V.n_1 V_1^{-1}\}V.n_2 V_2^{-1} \]
\[ = B(1 - B)n_1 V_1^{-1}V.\{(1 + \rho)n_2 V_2^{-1} - \rho n_2 V_2^{-1}V.n_2 V_2^{-1}\} \]
\[ + 2(1 - B)^2\rho n_1 V_1^{-1}V.n_2 V_2^{-1} + 2B(1 - B)\rho n_1 V_1^{-1}V.n_2 V_2^{-1} \]
\[ + 2B(1 - B)\rho n_1 V_1^{-1}V.n_1 V_1^{-1}V.n_2 V_2^{-1} \]

(\text{using } V.n_1 V_1^{-1} - n_1 V_1^{-1} + n_2 V_2^{-1})

\[ n_1 V_1^{-1}V.n_2 V_2^{-1} \]
\[ = 2B(1 - B)(1 + \rho) + 2\rho(1 - B)^2 + B^2 + \rho B(1 - B) + 2\rho B(1 - B)\]
\[ 0, \text{ since } B - \rho/(1 + \rho). \]
Finally, we evaluate the matrix appearing in $X_i^T | X_i$ in (4.15), namely

$$-(Bn_2V_2^{-1}V, D_{11} \{(1 - B)I + BV, n_1V_1^{-1}\} - \{(1 - B)I$$

$$+ Bn_2V_2^{-1}V, D_{22}(BV, n_1V_1^{-1}) + 2(Bn_2V_2^{-1}V, D_{12}(BV, n_1V_1^{-1})$$

$$= -B(1 - B)n_2V_2^{-1}V, D_{11} - B(1 - B)D_{22}V, n_1V_1^{-1}$$

$$- B^2n_2V_2^{-1}V, (D_{11} + D_{22} - 2D_{11})V, n_1V_1^{-1}$$

(using (4.8) and (4.16))

$$= -B(1 - B)n_2V_2^{-1}V, \{(1 + \rho)n_1V_1^{-1} - \rho n_1V_1^{-1}V, n_1V_1^{-1}\}$$

$$- B(1 - B)\{(1 + \rho)n_2V_2^{-1}V, n_2V_2^{-1}V, n_2V_2^{-1}\}V, n_1V_1^{-1}$$

$$- B^2n_2V_2^{-1}V, n_1V_1^{-1}$$

(using $V_1^{-1} = n_1V_1^{-1} + n_2V_2^{-1}$)

$$= -2Bn_2V_2^{-1}V, n_1V_1^{-1}$$

(A.10)

Combining (A.7)-(A.10), the proof of the lemma is complete.
B. References


