REFERENCE MANUAL FOR THE
Ada
PROGRAMMING LANGUAGE

PROPOSED STANDARD DOCUMENT

United States Department of Defense

JULY 1980

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Reference Manual for the Ada Programming Language

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Ada is the result of a collective effort to design a common language for programming large scale and real-time systems. This report is the proposed standard document for Ada.
Since the early 70's, DoD has been committed to the use of High Order Languages and has developed an extensive set of requirements for a single language which could be adopted for use throughout DoD. In April 1978, the language designed by Jean Ichbiah and his team at Honeywell/Cii-Honeywell Bull, Paris, France, was chosen to be the new DoD language. For the ensuing fourteen months, Ada was subjected to an intense period of test and evaluation by the international computer science community and the design was modified in response to language issues raised during that test and evaluation. It will be added to the list of approved languages for use in DoD systems and promises to have a significant impact on DoD software development.

Ada will be reviewed under American National Standards Institute (ANSI) canvass procedures for designation as an American National Standard and is on the agenda for the International Standards Organization (ISO). The DoD is concentrating on the development of compilers and an integrated programming support environment for Ada software. Although developed for use in DoD systems, Ada has generated considerable interest in the international computing community, particularly NATO, as well as in the U.S. commercial computing community.
REFERENCE MANUAL FOR THE
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PROGRAMMING LANGUAGE,

PROPOSED STANDARD DOCUMENT,

Technical report

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United States Department of Defense

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Ada is the result of a collective effort to design a common language for programming large scale and real-time defense systems.

The common high order language program began in 1974. The DoD requirements were formalized in a series of documents which were extensively reviewed by the Services, industrial organizations, universities, and foreign military departments. The culmination of that process was the Steelman Report to which the Ada language has been designed.

The Ada design team was led by Jean D. Ichbiah and has included Bernd Krieg-Brueckner, Brian A. Wichmann, Henry F. Ledgard, Jean-Claude Heliard, Jean-Raymond Abrial, John G.P. Barnes, Mike Woodger, Olivier Roubine, Paul N. Hillinger and Robert Firth.

At various stages of the project, several people closely associated with the design team made major contributions. They include J.B. Goodenough, M.W. Davis, G. Ferran, L. MacLaren, E. Morel, I.R. Nassi, I.C. Pyle, S.A. Schuman, and S.C. Vestal.

Two parallel efforts that were started in the second phase of this design had a deep influence on the language. One is the development of a formal definition using denotational semantics, with the participation of V. Donzeau-Gouge, G. Kahn, B. Lang, and P. Cadiou. The other is the design of a test translator with the participation of K. Ripken, P. Boullier, J. Holden, J. F. Huertas, R.G. Lange, and D.T. Cornhill. The entire effort benefited from the dedicated assistance of Lyn Churchill and Marion Myers, and the effective technical support of B. Gravem and W.L. Heimerdinger. H.G. Schmitz served as program manager.

Over the three years spent on this project, nine one-week design reviews were conducted with the participation of H. Harte, A.L. Hisgen, P.M. Knueven, M. Kronental, G. Seegmueller, V. Stenning, F. Belz, P. Cohen, R. Converse, K. Correll, R. Dewar, A. Evans, N. Habermann, J. Sammet, S. Squires, J. Teller, P. Wegner, and P.R. Wetherall.


These reviews and comments, the numerous evaluation reports received at the end of the first and second phases, the more than nine hundred language issue report comments, and test and evaluation reports received from fifteen different countries during the third phase of the project, and the ongoing work of the IFIP Working Group 2.4 on system implementation languages and that of LTPL-E of Purdue Europe all had a substantial influence on the final definition of Ada.

The Military Departments and Agencies have provided a broad base of support including funding, extensive reviews, and countless individual contributions by the members of the High Order Language Working Group and other interested personnel. In particular, William A. Whitaker provided leadership for the program during the formative stages. David A. Fisher was responsible for the successful development and iteration of language requirements documents, leading to the Steelman specification.

This language definition was developed by Cii Honeywell Bull and Honeywell Systems and Research Center under contract to the United States Department of Defense. William E. Carlson served as the technical representative of the Government and effectively coordinated the efforts of all participants in the Ada program.
This reference manual was prepared with a formatter specialized for Ada texts. It was developed by Jon F. Hueras for Multics and adapted by Paul Knueven for the CMU Scribe photocomposition system.
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1. Introduction

This report describes the programming language Ada, designed in accordance with the Steelman requirements of the United States Department of Defense. Overall, the Steelman requirements call for a language with considerable expressive power covering a wide application domain. As a result the language includes facilities offered by classical languages such as Pascal as well as facilities often found only in specialized languages. Thus the language is a modern algorithmic language with the usual control structures, and the ability to define types and subprograms. It also serves the need for modularity, whereby data, types, and subprograms can be packaged. It treats modularity in the physical sense as well, with a facility to support separate compilation.

In addition to these aspects, the language covers real time programming, with facilities to model parallel tasks and to handle exceptions. It also covers systems program applications. This requires access to system dependent parameters and precise control over the representation of data. Finally, both application level and machine level input-output are defined.

1.1 Design Goals

Ada was designed with three overriding concerns: a recognition of the importance of program reliability and maintenance, a concern for programming as a human activity, and efficiency.

The need for languages that promote reliability and simplify maintenance is well established. Hence emphasis was placed on program readability over ease of writing. For example, the rules of the language require that program variables be explicitly declared and that their type be specified. Since the type of a variable is invariant, compilers can ensure that operations on variables are compatible with the properties intended for objects of the type. Furthermore, error prone notations have been avoided, and the syntax of the language avoids the use of encoded forms in favor of more English-like constructs. Finally, the language offers support for separate compilation of program units in a way that facilitates program development and maintenance, and which provides the same degree of checking as within a unit.

Concern for the human programmer was also stressed during the design. Above all, an attempt was made to keep the language as small as possible, given the ambitious nature of the application domain. We have attempted to cover this domain with a small number of underlying concepts integrated in a consistent and systematic way. Nevertheless we have tried to avoid the pitfalls of excessive involution, and in the constant search for simpler designs we have tried to provide language constructs with an intuitive mapping on what the user will normally expect.

Like many other human activities, the development of programs is becoming more and more decentralized and distributed. Consequently the ability to assemble a program from independently produced software components has been a central idea in this design. The concepts of packages, of private types, and of generic program units are directly related to this idea, which has ramifications in many other aspects of the language.
No language can avoid the problem of efficiency. Languages that require overly elaborate compilers or that lead to the inefficient use of storage or execution time force these inefficiencies on all machines and on all programs. Every construct of the language was examined in the light of present implementation techniques. Any proposed construct whose implementation was unclear or required excessive machine resources was rejected.

Perhaps most importantly, none of the above goals was considered something that could be achieved after the fact. The design goals drove the entire design process from the beginning.

1.2 Language Summary

An Ada program is composed of one or more program units, which can be compiled separately. Program units may be subprograms (which define executable algorithms), packages (which define collections of entities), or tasks (which define concurrent computations). Each unit normally consists of two parts: a specification, containing the information that must be visible to other units, and a body, containing the implementation details, which need not be visible to other units.

This distinction of the specification and body, and the ability to compile units separately allow a program to be designed, written, and tested as a set of largely independent software components.

An Ada program will normally make use of a library of program units of general utility. The language provides means whereby individual organizations can construct their own libraries. To allow accurate control of program maintenance, the text of a separately compiled program unit must name the library units it requires.

Program units.

A subprogram is the basic unit for expressing an algorithm. There are two kinds of subprograms: procedures and functions. A procedure is the logical counterpart to a series of actions. For example, it may read in data, update variables, or produce some output. It may have parameters, to provide a controlled means of passing information between the procedure and the point of call. A function is the logical counterpart to the computation of a value. It is similar to a procedure, but in addition will return a result.

A package is the basic unit for defining a collection of logically related entities. For example, a package can be used to define a common pool of data and types, a collection of related subprograms, or a set of type declarations and associated operations. Portions of a package can be hidden from the user, thus allowing access only to the logical properties expressed by the package specification.

A task is the basic unit for defining a sequence of actions that may be executed in parallel with other similar units. Parallel tasks may be implemented on multicomputers, multiprocessors, or with interleaved execution on a single processor. A task unit may define either a single executing task object or a task type defining similar task objects.

Declarations and Statements

The body of a program unit generally contains two parts: a declarative part, which defines the logical entities to be used in the program unit, and a sequence of statements, which defines the execution of the program unit.
The declarative part associates names with declared entities. For example, a name may denote a type, a constant, a variable, or an exception. A declarative part also introduces the names and parameters of other nested subprograms, packages, and tasks to be used in the program unit.

The sequence of statements describes a sequence of actions that are to be performed. The statements are executed in succession (unless an exit, return, or goto statement, or the raising of an exception causes execution to continue from another place).

An assignment statement changes the value of a variable. A procedure call invokes execution of a procedure after associating any arguments provided at the call with the corresponding formal parameters of the subprogram.

Case statements and if statements allow the selection of an enclosed sequence of statements based on the value of an expression or on the value of a condition.

The basic iterative mechanism in the language is the loop statement. A loop statement specifies that a sequence of statements is to be executed repeatedly until an iteration clause is completed or an exit statement is encountered.

A block comprises a sequence of statements preceded by the declaration of local entities used by the statements.

Certain statements are only applicable to tasks. A delay statement delays the execution of a task for a specified duration. An entry call is written as a procedure call; it specifies that the task issuing the call is ready for a rendezvous with another task that has this entry. The called task is ready to accept the entry call when its execution reaches a corresponding accept statement, which specifies the actions then to be performed. After completion of the rendezvous, both the calling task and the task having the entry may continue their execution in parallel. A select statement allows a selective wait for one of several alternative rendezvous. Other forms of the select statement allow conditional or timed entry calls.

Execution of a program unit may lead to exceptional situations in which normal program execution cannot continue. For example, an arithmetic computation may exceed the maximum allowed value of a number, or an attempt may be made to access an array component by using an incorrect index value. To deal with these situations, the statements of a program unit can be textually followed by exception handlers describing the actions to be taken when the exceptional situation arises. Exceptions can be raised explicitly by a raise statement.

Data Types

Every object in the language has a type which characterizes a set of values and a set of applicable operations. There are four classes of types: scalar types (comprising enumeration and numeric types), composite types, access types, and private types.

An enumeration type defines an ordered set of distinct enumeration literals. For example a list of states or an alphabet of characters. The enumeration types BOOLEAN and CHARACTER are predefined.

Numeric types provide a means of performing exact or approximate computations. Exact computations use integer types, which denote sets of consecutive integers. Approximate computations use either fixed point types, with absolute bound on the error, or floating point types, with relative bound on the error. The numeric types INTEGER and DURATION are predefined.
Composite types allow definitions of structured objects with related components. The composite types in the language provide for arrays and records. An array is an object with indexed components of the same type. A record is an object with named components of possibly different types.

A record may have distinguished components called discriminants. Alternative record structures that depend on the values of discriminants can be defined within a record type.

Access types allow the construction of linked data structures created by the execution of allocators. They allow several variables of an access type to designate the same object, and components of one object to designate the same or other objects. Both the elements in such a linked data structure and their relation to other elements can be altered during program execution.

Private types can be defined in a package that conceals irrelevant structural details. Only the logically necessary properties (including any discriminants) are made visible to the users of such types.

The concept of a type is refined by the concept of a subtype, whereby a user can constrain the set of allowed values in a type. Subtypes can be used to define subranges of scalar types, arrays with a limited set of index values, and records and private types with particular discriminant values.

Other Facilities

Representation specifications can be used to specify the mapping between data types and features of an underlying machine. For example, the user can specify that objects of a given type must be represented with a specified number of bits, or that the components of a record are to be represented in a specified storage layout. Other features allow the controlled use of low level, non portable, or implementation dependent aspects, including the direct insertion of machine code.

Input–output is defined in the language by means of predefined library packages. Facilities are provided for input–output of values of user–defined as well as of predefined types. Standard means of representing values in display form are also provided.

Finally the language provides a powerful means of parameterization of program units, called generic program units. The generic parameters can be types and subprograms (as well as objects) and so allow general algorithms to be applied to all types of a given class.

1.3 Sources

A continual difficulty in language design is that one must both identify the capabilities required by the application domain and design language features that provide these capabilities.

The difficulty existed in this design, although to a much lesser degree than usual because of the Steelman requirements. These requirements often simplified the design process by permitting us to concentrate on the design of a given system satisfying a well defined set of capabilities, rather than on the definition of the capabilities themselves.
Another significant simplification of our design work resulted from earlier experience acquired by several successful Pascal derivatives developed with similar goals. These are the languages Euclid, Lis, Mesa, Modula, and Sue. Many of the key ideas and syntactic forms developed in these languages have a counterpart in Ada. We may say that whereas these previous designs could be considered as genuine research efforts, the language Ada is the result of a project in language design engineering, in an attempt to develop a product that represents the current state of the art.

Several existing languages such as Algol 68 and Simula and also recent research languages such as Alphard and Clu, influenced this language in several respects, although to a lesser degree than the Pascal family.

Finally, the evaluation reports received on the initial formulation of the Green language, the Red, Blue and Yellow language proposals, the language reviews that took place at different stages of this project, and the more than nine hundred reports received from fifteen different countries on the preliminary definition of Ada, all had a significant impact on the final definition of the language.

1.4 Syntax Notation

The context-free syntax of the language is described using a simple variant of Backus-Naur Form. In particular,

(a) Lower case words, some containing embedded underscores, denote syntactic categories, for example
   adding_operator

(b) Boldface words denote reserved words, for example
   array

(c) Square brackets enclose optional items, for example
   end [identifier];

(d) Braces enclose a repeated item. The item may appear zero or more times. Thus an identifier list is defined by
   identifier_list ::= identifier { identifier }

(e) A vertical bar separates alternative items, unless it occurs immediately after an opening brace, in which case it stands for itself:
   letter_or_digit ::= letter | digit
   component_association ::= [ choice { choice } => ] expression

(f) Any syntactic category prefixed by an italicized word and an underscore is equivalent to the unprefixed corresponding category name. The prefix is intended to convey some semantic information. For example type_name and task_name are both equivalent to the category name.
In addition, the syntax rules describing structured constructs are presented in a form that corresponds to the recommended paragraphing. For example, an if statement is defined as

```
if_statement ::=  
  if condition then  
  sequence_of_statements  
{ elsif condition then  
  sequence_of_statements)  
[ else  
  sequence_of_statements]  
end if;
```

1.5 Structure of the Reference Manual

This reference manual contains fourteen chapters, six appendices and an index. Each chapter is divided into sections that have a common structure. Each section introduces its subject, gives any necessary syntax equations, and describes the semantics of the corresponding language constructs. Examples, notes, and references, when present, follow in this order.

Examples are meant to illustrate the possible forms of the constructs described. Notes are to emphasize consequences of the rules described in the section or elsewhere. References refer to related sections. Neither examples, nor notes, nor references are part of the standard definition of the Ada language. In addition the appendices D (glossary), F (implementation dependent characteristics), and any section whose title starts by "example" do not form part of the standard definition.

1.6 Classification of Errors

The language recognize three categories of errors.

(1) Errors that must be detected at compilation time by every Ada compiler. These errors correspond to any violation of a rule of the language, other than those corresponding to (2) or (3) below. Any rule that uses the terms legal, allowed, must, or may only belongs to this category.

(2) Errors that must be detected at run time. These are called exceptions. In certain situations compilers may give warning during compilation that an exception is certain to occur in every execution of the program.

(3) Finally the language specifies certain rules that must be obeyed by Ada programs, although Ada compilers are not required to check that such rules are not violated. For any error belonging to this category, the reference manual uses the word erroneous to qualify the corresponding programs. If an erroneous program is executed, its effect is unpredictable.
2. Lexical Elements

This chapter defines the lexical elements of the language.

2.1 Character Set

All language constructs may be represented with a basic graphic character set, which is subdivided as follows:

(a) upper case letters
    \[A\] \[B\] \[C\] \[D\] \[E\] \[F\] \[G\] \[H\] \[I\] \[J\] \[K\] \[L\] \[M\] \[N\] \[O\] \[P\] \[Q\] \[R\] \[S\] \[T\] \[U\] \[V\] \[W\] \[X\] \[Y\] \[Z\]

(b) digits
    \[0\] \[1\] \[2\] \[3\] \[4\] \[5\] \[6\] \[7\] \[8\] \[9\]

(c) special characters
    \[\"\] \[#\] \[%\] \& \([\) \(\) \(+\) \(-\) \(+\) \(-\) \(/\) \(:\) \(;\) \(<\) \(>\) \[\[\) \[\]\) \[\{\) \[\}\)

(d) the space character

The character set may be extended to include further characters from the 95 character ASCII graphics set. These are:

(e) lower case letters
    \[a\] \[b\] \[c\] \[d\] \[e\] \[f\] \[g\] \[h\] \[i\] \[j\] \[k\] \[l\] \[m\] \[n\] \[o\] \[p\] \[q\] \[r\] \[s\] \[t\] \[u\] \[v\] \[w\] \[x\] \[y\] \[z\]

(f) other special characters
    \[!\] \[$\] \[@\] \[\[\] \[\]\] \[\{}\] \[\}\] ~

Every program may be converted into an equivalent program which uses only the basic character set. Any lower case letter is equivalent to the corresponding upper case letter, except within character strings and character literals. Rules for the transliteration of strings into the basic character set appear in section 2.10.

References:

ascii package C, character literal 2.5, character string 2.6, transliteration 2.10.
2.2 Lexical Units and Spacing Conventions

A program is a sequence of lexical units: the partitioning of the sequence into lines and the spacing between lexical units do not affect the meaning of the program. The lexical units are identifiers (including reserved words), numeric literals, character literals, strings, delimiters and comments. A delimiter is either one of the following special characters in the basic character set

```
& ' ( ) * + - / ; < > |
```

or one of the following compound symbols

```
=) .. *= /= >= <= << >> <>
```

Adjacent lexical units may be separated by spaces or by passage to a new line. An identifier or numeric literal must be separated in this way from an adjacent identifier or numeric literal. Spaces must not occur within lexical units, excepting strings, comments, and the space character literal. Each lexical unit must fit on one line.

Control characters of the ASCII set are used to effect this layout.

Any of carriage return, line feed, vertical tabulate, form feed, and only these, causes passage to a new line. Horizontal tabulate is allowed in comments. Otherwise no control character may occur within a lexical unit. Between lexical units horizontal tabulate is equivalent to a space, backspace is not allowed, and delete and null characters are ignored.

Note:

The number of lines produced by combinations of control characters is not prescribed. Thus carriage return terminates a lexical unit, whether or not a line feed follows it. Note that the double quote, double hyphen, and sharp sign are not delimiters; they are part of other lexical units.

References:

ASCII package C, character literal 2.5, comment 2.7, identifier 2.3, numeric literal 2.4, reserved word 2.9, string 2.6.

2.3 Identifiers

Identifiers are used as names (also as reserved words). Isolated underscore characters may be included. All characters, including underscores, are significant.

```
identifier ::= letter ( [ underscore ] letter_or_digit )  
letter_or_digit ::= letter | digit 
letter ::= upper_case_letter | lower_case_letter
```

Note that identifiers differing only in the use of corresponding upper and lower case letters are considered as the same.
Lexical Elements

Examples:

COUNT X get_symbol Ethelyn Marion
SNOBOL_4 X1 PageCount STORE_NEXT_ITEM

References:

lower case letter 2.1, name 4.1, upper case letter 2.1.

2.4 Numeric Literals

There are two classes of numeric literals: integer literals and real literals. Integer literals are the literals of the type universal_integer. Real literals are the literals of the type universal_real.

\[
\text{numeric_literal} \quad ::= \quad \text{decimal_number} \mid \text{based_number}
\]
\[
\text{decimal_number} \quad ::= \quad \text{integer} \mid [\text{integer}] \mid [\text{exponent}]
\]
\[
\text{integer} \quad ::= \quad \text{digit} \mid ([\text{underscore}] \text{digit})
\]
\[
\text{exponent} \quad ::= \quad E \mid (+) \text{integer} \mid E \mid (-) \text{integer}
\]

Isolated underscore characters may be inserted between adjacent digits of a decimal number, but are not significant.

The conventional decimal notation is used. Real literals are distinguished by the presence of a decimal point. An exponent indicates the power of ten by which the preceding number is to be multiplied to obtain the value represented. An integer literal can have an exponent; the exponent must be positive or zero.

Examples:

\[
\begin{align*}
12 & \quad 0 & \quad 123,456 & \quad 1E6 & \quad \text{-- integer literals} \\
12.0 & \quad 0.0 & \quad 0.456 & \quad 3.14159_26 & \quad \text{-- real literals} \\
1.34E-12 & \quad 1.0E+6 & \quad \text{-- real literals with exponent}
\end{align*}
\]

Note:

The exponent may be indicated by either an upper case E or a lower case e (see 2.1).

References:

universal_integer type 3.5.4, universal_real type 3.5.6
2.4.1 Based Numbers

Numbers may be represented with a base other than ten. Based numbers can have any base from 2 to 16.

\[
\text{based-number ::= base \# based-integer [based-integer] \# [exponent]}
\]

\[
\text{base ::= integer}
\]

\[
\text{based-integer ::= extended-digit ([underscore] extended-digit)}
\]

\[
\text{extended-digit ::= digit | letter}
\]

Isolated underscore characters may be inserted between adjacent extended digits of a based number, but are not significant. An exponent indicates the power of the base by which the preceding number is to be multiplied to obtain the value represented. The base and the exponent are in decimal notation. For bases above ten, the extended digits include the letters A through F, with the conventional significance 10 through 15.

Examples:

\[
\begin{align*}
2\#1111_1111\# & \quad 16\#FF\# & \text{--- integer literals of value 255} \\
16\#E\#E1 & \quad 2\#1110_0000\# & \text{--- integer literals of value 224} \\
16\#F.FF\#E+2 & \quad 2\#1.1111_1111_111\#E11 & \text{--- real literals of value 4095.0}
\end{align*}
\]

Note:

An extended digit that is a letter can be written either in lower case or in upper case.

2.5 Character Literals

A character literal is formed by enclosing one of the 95 ASCII graphic characters (including the space) between single quote characters.

Examples:

\[
'\text{A}' \quad '\text{v}' \quad ' ' \quad ' '
\]

References:

ascii package C, character 2.1
2.6 Character Strings

A character string is a sequence of zero or more characters prefixed and terminated by the string bracket character.

character_string :: = "[character]"

In order that arbitrary strings of characters may be represented, any included string bracket character must be written twice. The length of a string is the length of the sequence represented. Catenation must be used to represent strings longer than one line, and strings containing control characters.

Examples:

"" -- an empty string
" " "A" " " " " -- three strings of length 1

"characters such as $, % and ) may appear in strings"

"FIRST PART OF A STRING THAT " &
"CONTINUES ON THE NEXT LINE"

"String containing" & ASCII.CR & ASCII.LF & "Control characters"

References:
catenation 3.6.3 4.5.3, character 2.1

2.7 Comments

A comment starts with two hyphens and is terminated by the end of the line. It may only appear following a lexical unit or at the beginning or end of a program unit. Comments have no effect on the meaning of a program; their sole purpose is the enlightenment of the human reader.

Examples:

-- the last sentence above echoes the Algol 68 report
end; -- processing of LINE is complete

-- a long comment may be split onto
-- two or more consecutive lines

---------- the first two hyphens start the comment

References:

lexical unit 2.2, program unit 6 7 9.
2.8 Pragmas

Pragmas are used to convey information to the compiler. A pragma begins with the reserved word \texttt{pragma} followed by the name of the pragma, which distinguishes it from other pragmas. A pragma not recognized by the compiler has no effect.

\begin{verbatim}
pragma ::=
  pragma identifier ([argument , argument]);

argument ::= [identifier =\>] name
  | [identifier =\>] static_expression
\end{verbatim}

Pragmas may appear before a program unit, or wherever a declaration or a statement may appear, depending on the pragma. Some pragmas have arguments, which may involve identifiers visible at the place of the pragma. The extent of the effect of a pragma depends on the pragma.

A pragma may be language defined or implementation defined. All language defined pragmas are described in Appendix B. All implementation defined pragmas must be described in Appendix F. A pragma whose identifier is not recognized by the compiler has no effect.

Examples:

\begin{verbatim}
pragma LIST(OFF);
pragma OPTIMIZE(TIME);
pragma INCLUDE("COMMONTEXT");
pragma INLINE(SETMASK);
pragma SUPPRESS(RANGE_CHECK, ON => INDEX);
\end{verbatim}

References:

declaration 3.1, implementation defined pragma F, language defined pragma B, program unit 6 7 9, reserved word 2.9, statement 5, static expression 4.9, visibility rules 8

2.9 Reserved Words

The identifiers listed below are called \textit{reserved words} and are reserved for special significance in the language. Declared identifiers may not be reserved words. For readability of this manual, the reserved words appear in lower case boldface.

2.7 Reserved Words
Lexical Elements

<table>
<thead>
<tr>
<th>abort</th>
<th>declare</th>
<th>generic</th>
<th>of</th>
<th>select</th>
</tr>
</thead>
<tbody>
<tr>
<td>accept</td>
<td>delay</td>
<td>goto</td>
<td>or</td>
<td>separate</td>
</tr>
<tr>
<td>access</td>
<td>delta</td>
<td>others</td>
<td>subtype</td>
<td></td>
</tr>
<tr>
<td>all</td>
<td>digits</td>
<td>if</td>
<td>out</td>
<td></td>
</tr>
<tr>
<td>and</td>
<td>do</td>
<td>in</td>
<td></td>
<td></td>
</tr>
<tr>
<td>array</td>
<td>is</td>
<td>package</td>
<td>terminate</td>
<td></td>
</tr>
<tr>
<td>at</td>
<td>else</td>
<td>limited</td>
<td>procedure</td>
<td></td>
</tr>
<tr>
<td></td>
<td>elsif</td>
<td>private</td>
<td>type</td>
<td></td>
</tr>
<tr>
<td>begin</td>
<td>entry</td>
<td>raise</td>
<td>use</td>
<td></td>
</tr>
<tr>
<td>body</td>
<td>exception</td>
<td>range</td>
<td>when</td>
<td></td>
</tr>
<tr>
<td>exit</td>
<td>mod</td>
<td>record</td>
<td>rem</td>
<td></td>
</tr>
<tr>
<td>new</td>
<td>return</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>case</td>
<td>for</td>
<td>not</td>
<td>rename</td>
<td></td>
</tr>
<tr>
<td>constant</td>
<td>function</td>
<td>null</td>
<td>reverse</td>
<td>xor</td>
</tr>
</tbody>
</table>

2.10 Transliteration

A character string may contain characters not in the basic character set. A string containing such characters can be converted to a string written with the basic character set by using identifiers denoting these characters in concatenated strings. Such identifiers are defined in the predefined package ASCII. Thus the string "AB$CD" could be written as "AB" & ASCII.DOLLAR & "CD". Similarly, the string "ABcd" with lower case letters could be written as "AB" & ASCII.LC_C & ASCII.LCD.

The following replacements are allowed for characters that may not be available:

- The vertical bar character |, which appears on some terminals as a broken bar, may be replaced by the exclamation mark ! as a delimiter.

- The sharp character # may be replaced by the colon : throughout any based number.

- The double quote character " used as string bracket may be replaced by a percent character % at both ends of a string, provided that the string contains no double quote character. Any percent character within the string must then be written twice. A string which contains a double quote character can be represented using concatenation and a name for that character.

Note:

The preferred character set is the one employed in the rest of this manual. It is recommended that use of these replacements be restricted to cases where the characters replaced are not available.

References:

ascii package C, based number 2.4.1, basic character set 2.1, character string 2.6 choice 3.7.3, identifier 2.2.
3. Declarations and Types

This chapter describes the types in the language and the rules for declaring constants, variables, and named numbers.

3.1 Declarations

The language defines several forms of named entities. A named entity can be either a number, an enumeration literal, an object, a discriminant, a record component, a loop parameter, a type, a subtype, an attribute, a subprogram, a package, a task, an entry, a named block, a named loop, a labeled statement, an exception, or finally, a parameter of a subprogram, of an entry, or of a generic subprogram or package.

A declaration associates an identifier with a declared entity. Each identifier must be explicitly declared before it is used, excepting only labels, block identifiers, and loop identifiers; these are declared implicitly. There are several forms of declarations.

```
declaration ::= 
  object_declaration | number_declaration 
  | type_declaration | subtype_declaration 
  | subprogram_declaration | package_declaration 
  | task_declaration | exception_declaration 
  | renaming_declaration
```

A declaration may declare one or more entities. Discriminant declarations, component declarations, entry declarations, and parameter declarations occur as part of one of the above forms of declarations. Enumeration literals are declared by an enumeration type definition. A loop parameter is declared by an iteration clause. Attributes are predefined and cannot be declared.

The process by which a declaration achieves its effect is called the elaboration of the declaration. This process generally involves several successive actions:

- First, the identifier of a declared entity is introduced at the point of its first occurrence; it may hide other previously declared identifiers from then on (the rules defining visibility and hiding of identifiers are given in section 8.3).

- The second action is the elaboration of the declared entity. For all forms of declarations, except those of subprograms, packages, and tasks, an identifier can only be used as a name of a declared entity once the elaboration of the entity is completed. A subprogram, package, or task identifier can be used as a name of the corresponding entity as soon as the identifier is introduced, hence even within the declaration of the entity.

- The last action performed by the elaboration of an object declaration may be the initialization of the declared object (or objects).
The region of text over which the declaration has an effect is called the **scope** of the declaration; this region always starts at the point where the declared identifier is introduced (scope rules are defined in section 8.2).

Object, number, type, and subtype declarations are described here. The remaining declarations are described in later chapters.

**Notes:**

The rules defining the elaboration of the different forms of declarations are such that an expression appearing in a declaration is evaluated when the declaration is elaborated, except for certain expressions given in generic parts and which depend on generic parameters. This rule applies to any expression contained in a subprogram declaration but not to an expression contained in a subprogram body (since a body is not a declaration).

The term elaboration also applies to use clauses, with clauses, representation specifications, and to bodies (see section 3.9).

**References:**

block identifier 5.6, component declaration 3.7, discriminant declaration 3.7.1, elaboration 3.9, enumeration literal 3.5.1, exception declaration 11.1, expression 4.4, generic package declaration 12.1, generic subprogram declaration 12.1, hide 8.3, identifier 2.3, label 5.1, loop identifier 5.5, loop parameter 5.5, name 4.1, number declaration 3.2, object declaration 3.2, package declaration 7.1, parameter declaration 6.1, renaming declaration 8.5, scope 8.2, subprogram body 6.3, subprogram declaration 6.1, subtype declaration 3.3, task declaration 9.1, type declaration 3.3, visibility rules 6.3.

### 3.2 Object and Number Declarations

An object is an entity that contains (has) a value of a given type. Objects can be introduced by object declarations. Objects can also be components of other objects, or formal parameters of subprograms and generic program units. Finally, an object can be designated by a value of an access type.

**object_declaration ::=**

- `identifier_list [constant] subtype_indication [::= expression];`
- `identifier_list [constant] array_type_definition [::= expression];`

**number_declaration ::=**

- `identifier_list [constant] := literal_expression;
- `identifier_list := identifier { , identifier} ;`

An object declaration introduces one or more named objects of a type given either by a subtype indication, or by a constrained array type definition. An object declaration may include an expression specifying the initial value for the declared objects, provided that assignment is available for the type of the declared objects.
Declarations and Types

The elaboration of an object declaration consists of the elaboration of the declared objects, followed by their explicit initialization, if any:

(a) For the elaboration of the declared objects, the identifiers of the list are first introduced; the type is then established by elaborating the corresponding array type definition or by evaluating any constraint in the subtype indication; objects of this type and named by the identifiers are then created; these objects are subject to any constraint resulting from either the subtype indication or the constrained array type definition. Finally, in the absence of an explicit initialization, if a default initial value exists for objects of the type or for some of their components, the corresponding default initializations are performed. In particular, for objects of types with discriminants, the default discriminant values are assigned to the corresponding discriminants unless the objects are constrained, in which case the discriminant values specified by the constraints are assigned.

(b) If an explicit initialization is specified in an object declaration, the corresponding expression is then evaluated and its value is assigned to each of the declared objects. This value must satisfy any constraint on the objects as for assignment statements. An explicit initialization overrides a default initialization (but of course an explicit initialization cannot modify a discriminant value of an object with a discriminant constraint).

An object is a constant if the reserved word constant appears in the object declaration or if it is a component of a constant array or of a constant record. The initial value of a constant cannot be modified; this value must be given in the constant declaration except in the case of a deferred constant (that is, a constant declared in the visible part of a package and whose type is a private type declared in the same visible part, as explained in section 7.4).

Objects that are not constant are called variables. The value of a variable is undefined after elaboration of the corresponding object declaration unless either the latter contains an explicit initialization, or a default initial value exists for objects of the type. A program whose result depends upon an undefined value is erroneous.

A number declaration introduces one or more identifiers naming a number defined by a literal expression, which involves only numeric literals, names of numeric literals, calls of the predefined function ABS, parenthesized literal expressions, and the predefined arithmetic operators (see section 4.10 for literal expression). A named number is of the type universal_integer if every numeric literal (or name of a numeric literal) contained in the literal expression is of this type; otherwise it is of the type universal_real.

Elaboration of an object declaration with either an explicit or a default initialization raises the exception CONSTRAINT_ERROR if the initial value fails to satisfy some constraint on the object.

Examples of variable declarations:

```pascal
COUNT, SUM : INTEGER;
SORTED : BOOLEAN := FALSE;
COLOR_TABLE : array (1 .. N) of COLOR;
OPTION : BIT_VECTOR(1 .. 10) := (OPTION_RANGE => TRUE);
```

Examples of constant declarations:

```pascal
LIMIT : constant INTEGER := 10_000;
LOW_LIMIT : constant INTEGER := LIMIT / 10;
TOLERANCE : constant COEFFICIENT := DISPERSION(1.15);
NULL_KEY : constant KEY; -- deferred initialization
```
Examples of number declarations:

<table>
<thead>
<tr>
<th>Variable</th>
<th>Declaration</th>
</tr>
</thead>
<tbody>
<tr>
<td>PI</td>
<td>constant := 3.14159_26536; -- a real number</td>
</tr>
<tr>
<td>TWO_PI</td>
<td>constant := 2.0 * PI; -- a real number</td>
</tr>
<tr>
<td>POWER_16</td>
<td>constant := 2**16; -- the integer 65_536</td>
</tr>
<tr>
<td>ONE, UN, EINS</td>
<td>constant := 1; -- three different names for 1</td>
</tr>
</tbody>
</table>

Notes:

Once an object is elaborated, its name can be used. In particular it can serve to form the names of attributes of the object. Such attributes can even appear in the expression defining the initial value of the object. In the above examples, the attribute OPTION'RANGE, denoting the range 1 .. 10, is used as a choice in the aggregate initializing the array OPTION.

The expression initializing a constant object may (but need not) be a static expression (see 4.9). In the above examples, LIMIT and LOW_LIMIT are initialized with static expressions, but TOLERANCE is not since it is initialized with the result of the call of a user defined function.

References:

arithmetic operator 4.5, assignment statement 5.2, component 3.6 3.7, constraint 3.3, default initial value 3.7 3.8, deferred constant 7.1, discriminant 3.7.1 7.1, discriminant constraint 3.7.2, elaboration 3.1 3.9, expression 4.4, formal parameter 6.2, generic program unit 12, literal expression 4.10, name 4.1, numeric literal 2.4, package visible part 7.2, private type definition 7.4 static expression 4.9, type definition definition 3.3, type definition mark 3.3, universal integer type 2.4 3.5.4, universal real type 2.4 3.5.6.

3.3 Type and Subtype Declarations

A type characterizes a set of values and a set of operations applicable to those values. The values are denoted either by literals or by aggregates of the type, and can be obtained as the result of operations.

There exist several classes of types. Scalar types are types whose values have no components; they comprise types defined by enumeration of their values, integer types, and real types. Array and record types are composite: their values consist of several component values. An access type is a type whose values provide access to other objects. Finally, there are private types where the set of possible values is well defined, but not known to the users of such types.

Record and private types may have special components called discriminants whose values distinguish alternative forms of values of one of these types. Discriminants are defined by a discriminant part. The possible discriminants of a private type are known to its users. Hence a private type is only known by its name, its discriminants if any, and the set of operations applicable to its values.

The set of possible values for an object of a given type can be restricted without changing the set of applicable operations. Such a restriction is called a constraint (the case of no restriction is also included). A value is said to belong to a subtype of a given type if it obeys such a constraint; the given type is called the base type of the subtype. A type is a subtype of itself; the base type of a type is the type itself.

Certain types may have default initial values defined for objects of the type or for some of their components.

3.3 Type and Subtype Declarations
Certain characteristics of types and subtypes, such as certain specific values and operations, are called attributes of the types and subtypes. Attributes are denoted by the form of names described in section 3.1.4.

```
type_declaration ::= 
  type_identifier [discriminant_part] is typedefinition; 
  incomplete_type_declaration

type_definition ::= 
  enumeration_type_definition | integer_type_definition 
  | real_type_definition | array_type_definition 
  | record_type_definition | access_type_definition 
  | derived_type_definition | private_type_definition

subtype_declaration ::= 
  subtype_identifier is subtype_indication;

subtype_indication ::= type_mark [constraint]

type_mark ::= type_name | subtype_name

constraint ::= 
  range_constraint | accuracy_constraint 
  | index_constraint | discriminant_constraint
```

The elaboration of a type definition always produces a distinct type. For the elaboration of a type declaration, the type identifier is first introduced; elaboration of any discriminant part and of the type definition follow in this order. The type identifier can then serve as a name of the type resulting from the elaboration of the type definition and of the optional discriminant part.

The elaboration of certain forms of the type definitions for derived types, numeric types, and array types has the effect of specifying a constaint for a type defined by an underlying unconstrained type definition. The identifier introduced by a type declaration containing such a type definition is the name of a subtype of the (anonymous) unconstrained type.

For the elaboration of a subtype declaration the subtype identifier is first introduced; if there is a constraint in the subtype indication it is then evaluated, that is, any contained expression is evaluated. The subtype identifier can then serve as a name of the declared subtype. In the absence of a constraint in the subtype declaration, the subtype name is an alternative name to the type mark. If the subtype declaration includes a constraint, the subtype name is an abbreviation for the name of the base type of the type mark together with the constraint, with the meanings that they both have at the subtype declaration.

Whenever a constraint appears after a type mark in a subtype indication, the constraint imposed on the type mark must be compatible with any constraint already imposed by the type mark, the exception CONSTRAINT_ERROR is raise if this condition is not satisfied. Compatibility is defined for each form of constraint in the corresponding section (see 3.5, 3.5.7, 3.5.9, 3.6.1, 3.7.2, 3.8). An index constraint (or a discriminant constraint) may only be imposed on a type mark that does not already impose an index constraint (or a discriminant constraint).

Incomplete type declarations are used for the definition of recursive and mutually dependent access types. Recursion in type definitions is not allowed unless an intermediate access type is used (see 3.11).
Attribute:

For any type or subtype T, the following attribute is defined:

T'BASE

The base type of T. This attribute can only be used to form the names of other attributes, for example T'BASE'FIRST.

Examples of type declarations:

```ada
type COLOR is (WHITE, RED, YELLOW, GREEN, BLUE, BROWN, BLACK);
type COL_NUM is range 1 .. 72;
type TABLE is array (1 .. 10) of INTEGER;
```

Examples of subtype declarations:

```ada
subtype RAINBOW is COLOR range RED .. BLUE;
subtype RED_BLUE is RAINBOW;
subtype SMALL_INT is INTEGER range 10 .. 10;
subtype ZONE is COL_NUM range 1 .. 8;
subtype SQUARE is MATRIX(1 .. 10, 1 .. 10);
subtype MALE is PERSON(SEX = M);
```

Notes:

Two type definitions always introduce two distinct types, even if they are textually identical. For example, the array type definitions given in the declarations of A and B below define distinct types.

```ada
A : array(1 .. 10) of BOOLEAN;
B : array(1 .. 10) of BOOLEAN;
```

On the other hand, C and D in the following declaration are of the same type, since only one type definition is given.

```ada
C, D : array(1 .. 10) of BOOLEAN;
```

A subtype declaration does not introduce a new type.

References:

access type 3.8, array type definition 3.6, constraint_error exception 11.1, derived type 3.4, discriminant 3.7.1, elaboration 3.1 3.9, enumeration type 3.5.1, identifier 2.3, incomplete type declaration 3.8, name 41, numeric type 3.5, private type definition 7.4, record type 3.7, scalar type 3.4

3.4 Derived Type Definitions

The elaboration of a derived type definition defines an unconstrained type deriving its characteristics from those of a parent type. It may further define a subtype obtained by imposing a constraint upon the unconstrained derived type. A derived type definition is only allowed in a type declaration. The identifier introduced by such a type declaration can be either the name of the derived type if unconstrained, or it can be the name of a subtype of the (anonymous) derived type.

```ada
derived_type_definition ::= new subtype_indication
```

3.4 Derived Type Definitions
The parent type is the base type of the subtype indicated after the reserved word new. If the subtype indication includes an explicit constraint, it is evaluated as part of the elaboration of the derived type definition. Such explicit constraint, or in its absence any constraint already imposed by the type mark of the parent subtype, becomes associated with the type mark introduced by the derived type declaration (subject to the same rules of compatibility as described in section 3.3).

The characteristics of a derived type are as follows:

- The derived type belongs to the same class of types as the parent type (for example, the derived type is a record type if the parent type is).
- The set of possible values for the derived type is a copy of the set of possible values for the parent type. Explicit conversion of a value of the parent type into the corresponding value of the derived type is possible and vice versa (see 4.6). If a default initial value exists for the parent type, a corresponding initial value exists for the derived type.
- The notation for any literals or aggregates of the derived type is the same as for the parent type. Such literals and aggregates are said to be overloaded. The notation used to denote any component of objects of the derived type is the same as for the parent type.
- The same attributes are defined for the derived type as for the parent type. If the parent type is an access type, the parent and the derived type share the same collection. Any representation specification already elaborated for the parent type (consequently, not in the same declarative part) also applies to the derived type (see 13.1).
- Certain subprograms applicable to the parent type, that is, subprograms that have a parameter or result of the parent type (or of one of its subtypes) are derived by the derived type. These derived subprograms are implicitly declared at the place of the derived type definition but may be redefined in the same declaration list.

For a predefined type, the subprograms that are derived are the corresponding predefined operations. The subprograms derived by a derived type can be further derived if this type is used as parent type in another derived type definition. If a type is declared in a package specification, the subprograms applicable to the type and declared in the package specification are derived by any derived type definition given after the end of the package specification.

The specification of a derived subprogram is obtained by systematic replacement of the parent type by the unconstrained derived type in the specification of the subprogram applicable to the parent type; a type conversion to the derived type is applied to the bounds of any range constraint for a parameter of the parent type and to any default value of the parent type. Prior to this transformation any subtype of the parent type is first expanded into the corresponding base type (that is, the parent type) and any associated constraint.

The effect of a call of a derived subprogram is achieved by a call of the parent subprogram preceded by (implicit) conversion of any in and in out parameters to the parent type, and followed by (implicit) conversion of any in out parameters, out parameters, or function result to the derived type.

Example:

```pascal
type MIDWEEK is new DAY range TUE .. THU;
```
Notes:

The above rules mean that a type declaration of the form

```ada
type NEW_TYPE is new OLD_TYPE constraint;
```

where the constraint is compatible with those of OLD_TYPE, is equivalent to the succession of declarations:

```ada
type new_type is new base_type_of_OLD_TYPE;
subtype NEW_TYPE is new_type constraint;
```

where new_type is an identifier distinct from those of the program. Hence, the values and operations of the old type are derived by the new type, but objects of the new type must satisfy the added constraint. For example, the name MIDWEEK is the name of a subtype of an anonymous type derived from the type DAY.

The rule given in section 3.3, concerning the compatibility of a constraint imposed on a type mark with any constraint already imposed by the type mark, applies to the subtype indication given in a derived type definition. Note however that the constraint imposed on a parameter of a subprogram applicable to the parent type may be incompatible with the constraint of the derived type. In such a case all calls of the derived subprogram will raise the exception CONSTRAINT_ERROR.

References:

access type 3.8, aggregate 4.3, attribute 4.1.4, base type 3.3, constraint 3.3, declaration 3.1, elaboration 3.1
3.9, in parameter 6.2, in out parameter 6.2, literal 4.2, package specification 7.2, predefined operation C,
predefined type C, representation specification 13.1, subprogram specification 6.1, subtype 3.3, subtype
indication 3.3, type conversion 4.6, type mark 3.3

3.5 Scalar Types

Scalar types comprise discrete types and real types. All scalar types are ordered. A range constraint specifies a subset of values of a scalar type or subtype. Discrete types are the enumeration types and integer types; they may be used for indexing and iteration over loops. Each discrete value has a position number which is an integer number. Integer and real types are called numeric types.

```
range_constraint ::= range range
range ::= simple_expression .. simple_expression
```

The range L .. R describes the values from L to R inclusive. The values L and R are called, respectively, the lower bound and upper bound of the range. A value is said to satisfy a range constraint if it is a value of the range. A null range is a range for which the upper bound is less than the lower bound. For a range constraint appearing after a type mark in a subtype indication, the type of the simple expressions is given by the type mark. A range constraint is said to be compatible with an earlier range constraint when both bounds of the later constraint lie within the range of the earlier constraint, or when the range of the later constraint is null.

3.: Scalar Types
Attributes:

For any scalar type or subtype T the attributes FIRST and LAST are defined (see also Appendix A for the definition of the attributes IMAGE and VALUE).

T’FIRST The minimum value of the type T or the lower bound of the subtype T
T’LAST The maximum value of the type T or the upper bound of the subtype T

References:

constraint 3.3, discrete range 3.6.1, loop statement 5.6, simple expression 4.4, subtype 3.3

3.5.1 Enumeration Types

An enumeration type definition defines an ordered set of distinct values that are denoted by enumeration literals.

enumeration_type_definition ::= 
  (enumeration_literal (, enumeration_literal))
enumeration_literal ::= identifier | character_literal

An enumeration value is denoted by an identifier or a character literal. Order relations between enumeration values follow the order of listing, the first being less than the last (when more than one). The position number of the first listed literal is zero; the position number of each other literal is one more than that of its predecessor in the list.

For the elaboration of an enumeration type definition, each enumeration literal is introduced at the point of its occurrence in the enumeration type definition; this elaboration declares the enumeration literals.

The same identifier or character literal can appear in different enumeration types whose scopes overlap. Such enumeration literals are said to be overloaded. An overloaded enumeration literal may only appear at points of the program text where its type can be determined from the context (see 6.6). A qualified expression can be used to resolve the type ambiguity where the context does not otherwise suffice (see 4.7).

Examples:

type DAY is (MON, TUE, WED, THU, FRI, SAT, SUN);
type SUIT is (CLUBS, DIAMONDS, HEARTS, SPADES);
type LEVEL is (LOW, MEDIUM, URGENT);
type COLOR is (WHITE, RED, YELLOW, GREEN, BLUE, BROWN, BLACK);
type LIGHT is (RED, AMBER, GREEN);  -- RED and GREEN are overloaded

type HEXA is ('A', 'B', 'C', 'D', 'E', 'F');
type MIXED is ('A', 'B', 'D', B, NONE);

subtype WEEKDAY is DAY range MON..FRI;
subtype MAJOR is SUIT range HEARTS..SPADES;
subtype RAINBOW is COLOR range RED..BLUE;  -- the color RED, not the light
3.5.2 Character Types

A character type is an enumeration type that contains character literals and possibly identifiers. The values of the predefined type CHARACTER are the 128 characters of the ASCII character set. Each of the 95 graphic characters of the ASCII character set can be denoted by a character literal. The predefined package ASCII includes the declaration of constants denoting control characters and of constants denoting graphic characters that are not in the basic character set.

Example:

    type ROMAN_DIGIT is ('I', 'V', 'X', 'L', 'C', 'D', 'M');

Note:

Character literals of character types can be used in character strings.

References:

ascii package C, character literal 2.5, character string 2.6 3.6.3, identifier 2.3

3.5.3 Boolean Type

There is a predefined enumeration type named BOOLEAN. It contains the two literals FALSE and TRUE ordered with the relation FALSE < TRUE. The evaluation of a condition must deliver a result of this predefined type.

References:

condition 5.3 5.5 5.7,

3.5.4 Integer Types

The elaboration of an integer type definition introduces a set of consecutive integers as values of the type.

    integer_type_definition ::= range_constant

Each bound of a range used for an integer type definition must be an integer value defined by a static expression of some integer type. The range must not be a null range; it may include negative values.
A type declaration of the form

```pascal
type T is range L .. R;
```

is equivalent to the declaration of a type derived from one of the predefined integer types

```pascal
type T is new integer_type range L .. R;
```

where the predefined `integer_type` is implicitly chosen so as to contain the values L through R inclusive.

The predefined integer types include the type `INTEGER`. An implementation may also have predefined types such as `SHORT_INTEGER` and `LONG_INTEGER`, which have respectively significantly shorter and longer ranges than `INTEGER`. The range of each of these types must be symmetric about zero (excepting an extra negative value for two's complement machines). The base type of each of these types is the type itself.

The same arithmetic operators are defined for all predefined integer types and consequently for all integer types (see 4.5 and appendix C). The position number of an integer number is the number itself.

Integer literals are the literals of the type `universal_integer`; there are no bounds on values of this type. Implicit conversions exist from this type to any predefined or user defined integer type, so that integer literals can appear in expressions of these types. The exception `CONSTRAINT_ERROR` is raised by such an implicit conversion if the value is not within the range of the required type.

Examples:

```pascal
type PAGE_NUM is range 1 .. 2_000;
type LINE_SIZE is new INTEGER range 1 .. MAX_LINE_SIZE;
subtype SMALL_INT is INTEGER range -10 .. 10;
subtype COLUMN_PTR is LINE_SIZE range 1 .. 10;
```

Notes:

The name introduced by an integer type declaration is the name of a subtype of an anonymous type derived from one of the predefined integer types (see 3.4). The value contained by an object of an integer type must satisfy the constraint given in the corresponding integer type definition (an attempt to violate this constraint will raise the exception `CONSTRAINT_ERROR`). On the other hand, the operations of an integer type deliver results whose range is defined by the parent predefined type; such a result need not therefore lie within the range defined by the constraint (the exception `NUMERIC_ERROR` may be raised by an operation whose result is not within the predefined range).

The smallest (most negative) integer value supported by the predefined integer types of an implementation is the integer number `SYSTEM.MIN_INT` and the largest (most positive) value `SYSTEM.MAX_INT` (see 13.7).

References:

arithmetic operator 4.5 C. constraint_error exception 11.1. derived type 3.4. elaboration 3.1 3.9. integer literal 2.4. name 4.1. numeric_error exception 11.1. parent type 3.3. position number 3.5 static expression 4.9. subtype 3.3. universal integer type 2.4 3.2
3.5.5 Attributes of Discrete Types and Subtypes

For every discrete type T the attributes T'POS, T'SUCC, T'PRED, and T'VAL are functions defined as follows:

T'POS(X)  The parameter X must be a value of type T; the result of the function is the position number of X; the type of the result of this overloaded function is of an integer type determined by the context (see 6.6).

T'SUCC(X)  The parameter X must be a value of type T; the result of the function is the value of type T whose position number is one greater than that of X. The exception CONSTRAINT_ERROR is raised if X = T'LAST.

T'PRED(X)  The parameter X must be a value of type T; the result of the function is the value of type T whose position number is one less than that of X. The exception CONSTRAINT_ERROR is raised if X = T'FIRST.

T'VAL(N)  The parameter N must be a value of an integer type; the result of the function is the value of type T whose position number is N. The exception CONSTRAINT_ERROR is raised if N is not in the range T'POS(T'FIRST) .. T'POS(T'LAST).

For a subtype S of a discrete type, each of these four attributes denotes the corresponding attribute of the base type. Consequently, the results delivered by S'SUCC, S'PRED, and S'VAL need not be in the range of S; similarly, the actual parameters of S'POS, S'SUCC, S'PRED need not be in the range of S.

Examples:

-- For the types and subtypes declared in section 3.5.1 we have

-- COLOR'FIRST = WHITE, COLOR'LAST = BLACK
-- RAINBOW'FIRST = RED, RAINBOW'LAST = BLUE
-- COLOR'SUCC(BLUE) = RAINBOW'SUCC(BLUE) = BROWN
-- COLOR'POS(BLUE) = RAINBOW'POS(BLUE) = 4
-- COLOR'VAL(0) = RAINBOW'VAL(0) = WHITE

Note:

The following relations are satisfied (in the absence of an exception) by these four attributes of discrete types

\[
\begin{align*}
\text{T'POS(T'SUCC(X))} &= \text{T'POS(X)} + 1 \\
\text{T'POS(T'PRED(X))} &= \text{T'POS(X)} - 1 \\
\text{T'VAL(T'POS(X))} &= \text{X} \\
\text{T'POS(T'VAL(N))} &= \text{N}
\end{align*}
\]

References:

attribute 4.1.4, base type 3.3, constraint_error exception 11.1, discrete type 3.5, first attribute 3.5, function 6.5, last attribute 3.5, position number 3.5, subtype 3.3, type 3.3
3.5.6 Real Types

Real types provide approximations to the real numbers, with relative bounds on errors for floating point types, and with absolute bounds for fixed point types.

\[
\text{real_type_definition ::= accuracy_constraint}
\]

\[
\text{accuracy_constraint ::= floating_point_constraint | fixed_point_constraint}
\]

The elaboration of a real type definition defines a set of numbers called model numbers. Error bounds on the predefined operations are defined in terms of the model numbers. An implementation of the type must include at least these model numbers and represent them exactly.

Real literals are the literals of the type \textit{universal_real}; there are no bounds on values of this type. Implicit conversions exist from this type to any predefined or user defined real type, so that real literals can appear in expressions of these types. If the universal real value is a model number, the conversion delivers the corresponding value. Otherwise, the converted value can be any value within the range defined by the model numbers next above and below the universal real value. The exception \texttt{CONSTRAINT_ERROR} is raised by such an implicit conversion if the value is not within the range of the required type.

\textit{Note:}

An algorithm written to rely only upon the minimum numerical properties guaranteed by the type definition will be portable without further precautions.

\textit{References:}

accuracy of operations 4.5.8, elaboration 3.1 3.9, fixed point constraint 3.5.9, fixed point type 3.5.9, floating point constraint 3.5.7, floating point type 3.5.7, model fixed point number 3.5.9, model floating point number 3.5.7, universal real type 2.4 3.2

3.5.7 Floating Point Types

For floating point types, the error bound is specified as a relative precision by giving the minimum required number of decimal digits for the decimal mantissa (that is, for the decimal value when the power of ten and leading zeros are ignored).

\[
\text{floating_point_constraint ::= digits static_simple_expression [range_constraint]}
\]

The required number \(D\) of decimal digits is specified by the value of the static expression following the reserved word \textit{digits}; it must be positive and of some integer type. This value determines a corresponding minimum number \(B\) of binary digits for the binary mantissa such that the relative precision of the binary form is no less than that specified for the decimal form. \((B\) is the integer next above \(D\ln(10)/\ln(2)\)).
The model numbers of the type comprise zero and all numbers of the form

\[ \text{sign} \times \text{binary\_mantissa} \times (2.0 \times \text{exponent}) \]

such that

- sign is +1 or -1
- \(0.5 \leq \text{binary\_mantissa} < 1.0\)
- binary\_mantissa has exactly B digits after the point when expressed in base two
- exponent is an integer in the range \(-4B \ldots 4B\)

A floating point type declaration of one of the two forms (that is, with or without a range):

```ada
type NEW_TYPE is digits D [range L .. R];
```

where L and R if present must be static expressions of some real types, is equivalent to the declaration of a type derived from one of the predefined floating point types

```ada
type NEW_TYPE is new floating\_point\_type digits D [range L .. R];
```

where the predefined floating\_point\_type is chosen appropriately such that its model numbers include the model numbers defined by D. The predefined floating point types include the type FLOAT. An implementation may also have predefined types such as SHORT\_FLOAT and LONG\_FLOAT, which have respectively substantially less and more precision than FLOAT.

Where the range constraint is present the same model numbers are used, but objects of type NEW\_TYPE must satisfy the range constraint. Thus the value of D in the type definition guarantees specific minimal properties for the type.

For a subtype or object declaration, the constraint can either be a range constraint or a floating point constraint. In either case, the expressions giving the upper and lower bounds must be of the type or subtype specified and within the range of the type or subtype. The expression following digits in the floating point constraint must be a static expression of an integer type and its value must not be greater than the corresponding number D for the floating point type or subtype.

A subtype declaration defines a set of model numbers which is a subset of the model numbers of the base type. If the subtype indication includes a floating point constraint specifying fewer decimal digits than the base type, then the mantissa length B of the model numbers is correspondingly reduced; otherwise the model numbers for the subtype are the same as for the base type.

The compatibility of a floating point constraint with an earlier one is defined as follows. The number of digits of the later one must not exceed that of the earlier one; if both floating point constraints have range constraints, the later range constraint must be compatible with the earlier range constraint (within the accuracy of the corresponding real operations, see 4.5.8). A value of a floating point type satisfies a floating point constraint if it satisfies any included range constraint.
Examples:

```haskell```

```plaintext```
type COEFFICIENT is digits 10 range -1.0 .. 1.0;
type REAL is digits 8;
type MASS is new REAL digits 7 range 0.0 .. 1.0E10;
subtype SHORT_COEFF is COEFFICIENT digits 5;
```
```haskell```

Notes on the examples:

The implemented range for REAL is derived from a predefined type having at least 8 digits of precision. The definition for MASS is valid because REAL has more than 7 digits precision and because

\[ MASS'LAST < REAL'LARGE <= REAL'LAST \]

References:

accuracy constraint 3.5.6, base type 3.3, bounds 3.5, integer type 3.5.4, model number 3.5.6, range constraint 3.3, static expression 4.9, subtype 3.3, subtype indication 3.3,

3.5.8 Attributes of Floating Point Types

For every floating point type or subtype F the following attributes are defined:

- \( F'DIGITS \) For a predefined type F, the equivalent number of decimal digits precision for model numbers of the type. For other types or subtypes, the number of decimal digits specified by the accuracy constraint. Of type universal_integer.

- \( F'MANTISSA \) The length of the binary mantissa of model numbers of F. Of type universal_integer. (The number B of section 3.5.7).

- \( F'EMAX \) The number such that the binary exponent range of model numbers of F is \(-F'EMAX .. F'EMAX\). Of type universal_integer.

- \( F'SMALL \) The smallest positive model number of F. Of type universal_real.

- \( F'LARGE \) The largest positive model number of F. Of type universal_real.

- \( F'EPSILON \) The absolute value of the difference between 1.0 and the next model number above 1.0. Of type universal_real.

In addition, the usual attributes of scalar types FIRST and LAST are defined. (They need not be model numbers).
Notes:

The attributes EMAX, SMALL, LARGE and EPSILON are provided for convenience. They are all related to MANTISSA, the parameter which defines the model numbers and is in turn related to DIGITS, by the following formulas:

\[
\begin{align*}
F'EMAX & = 4 \times F'MANTISSA \\
F'SMALL & = 2.0 \times (-F'EMAX - 1) \\
F'LARGE & = 2.0 \times 2^{F'EMAX} \times (1.0 - 2.0 \times (-F'MANTISSA)) \\
F'EPSILON & = 2.0 \times (-F'MANTISSA + 1)
\end{align*}
\]

Since F'FIRST and F'LAST need not be model numbers, they may have machine dependent properties.

Certain attributes of floating point types are machine dependent. They are described in section 13.7.1.

References:

accuracy constraint 3.5.6, binary mantissa 3.5.7, boolean type 3.5.3, digits 3.5.7, exponent 3.5.7, first attribute 3.5, floating point type 3.5.7, integer type 3.5.4, last attribute 3.5, model number 3.5.6, numeric_error exception 11.1, universal_integer type 2.4 3.2, universal_real type 2.4 3.2

3.5.9 Fixed Point Types

For fixed point types, the error bound is specified as an absolute value, called the delta of the fixed point type.

fixed_point_constraint ::=
delta static_simple_expression [range_constraint]

The delta is specified by the value of the static expression following the reserved word delta, it must be positive and of some real type. The range constraint is required in a fixed point type definition; it is optional in a subtype indication.

The model numbers of a fixed point type comprise consecutive integer multiples of a certain number called actual_delta. The multipliers comprise all integers in the range

\[-(2^{N} + 1) \ldots (2^{N}) - 1\]

for some positive integer N. This implemented error bound actual_delta must be positive and not greater than the specified delta. For a fixed point type definition with a range constraint of the form

range L .. R
L and R must be static expressions of some real types; the integer N must be chosen so that model numbers of the type lie at most delta distant from each of L and R, although neither L nor R need be model numbers. Thus the values of L and R and the delta in the type definition guarantee specific minimal properties for the type.

For a subtype or object declaration, the constraint can be either a range constraint or a fixed point constraint. In either case, the expressions giving the lower and upper bounds must be of the type specified and within the range of the type or subtype. The expression in the fixed point constraint must be a static expression of a real type and its value must not be less than the corresponding value delta for the type or subtype.

A subtype declaration defines a set of model numbers which is a subset of the model numbers of the base type. The actual delta of the subtype is a non-negative power of two, times the actual delta of the base type, and must not be greater than the specified delta.

Multiplication and division of fixed point values deliver results of a fixed point type with an arbitrarily fine accuracy, whose name cannot be used in programs and which is referred to in this text for explanatory purposes as universal_fixed. The values of this type must be converted explicitly to some numeric type.

The compatibility of a fixed point constraint with an earlier one is defined as follows. The delta of the later one must not be less than that of the earlier one; if both fixed point constraints have range constraints, the later constraint must be compatible with the earlier range constraint (within the accuracy of the corresponding real operations; see 4.5.8). A value of a fixed point type satisfies a fixed point constraint if it satisfies any included range constraint.

Examples:

```plaintext
-- A pure fraction which requires all the available space in a word
-- on a two's complement machine can be declared as type FRAC:

DEL : constant := 1.0/2**(WORD_LENGTH - 1);
type FRAC is delta DEL range -1.0 .. 1.0 - DEL;
type LONG_FRAC is delta DEL/1000 range -1.0 .. 1.0 - DEL;
-- a pure fraction requiring more bits

type VOLT is delta 0.125 range 0.0 .. 255.0;

subtype S_VOLT is VOLT delta 0.5 "-- same range as VOLT"
```

Note:
The actual delta is ordinarily a power of two, in order to make conversions fast. The actual delta may be specified explicitly by a representation specification (see 13.2).

References:

accuracy constraint 3.5.6, bounds 3.5, integer type 3.5.4, model number 3.5.6, range constraint 3.3, real type 3.5.6, simple expression 4.4, static expression 4.9, subtype indication 3.3.
3.5.10 Attributes of Fixed Point Types

For every fixed point type or subtype F the following attributes are defined:

F'DELTA If F is a type, or a subtype without a fixed point constraint, this is the delta of the base type. Otherwise it is the delta specified by the fixed point constraint. Of type universal_real.

F'ACTUAL_DELTA The actual delta of F. Of type universal_real.

F'BITS When positive values of model numbers of F are expressed as K*F'ACTUAL_DELTA, the attribute F'BITS is the number of binary digits used to represent the unsigned integer K. Of type universal_integer. The attribute F'BITS is the number N of section 3.5.9.

F'LARGE The largest model number of F.

Notes:

Machine dependent attributes of real types are described in section 13.7. The following relation is satisfied by the attributes LARGE, BITS, and ACTUAL_DELTA:

F'LARGE = (2**F'BITS - 1) * F'ACTUAL_DELTA

References:

accuracy constraint 3.5.6, base type 3.3, boolean type 3.5.3, delta 3.5.9, model number 3.5.6

3.6 Array Types

An array object is a composite object consisting of components of the same component type. A component of an array is designated using one or more index values belonging to specified discrete types. The value of an array object is a composite value consisting of the values of its components.

array_type_definition ::= array (index {, index}) of component_subtype_indication | array index_constraint of component_subtype_indication

index ::= type_mark range <>

index_constraint ::= (discrete_range {, discrete_range})

discrete_range ::= type_mark [range_constraint] | range

An array object is characterized by the number of indices (the dimensionality of the array), the type and position of each index, the lower and upper bounds for each index, and the type and possible constraints of the components. The order of the indices is significant.
A one-dimensional array has a distinct component for each possible index value. A multi-dimensional array has a distinct component for each possible sequence of index values that can be formed by selecting one value for each index position. The possible values for an index are all values between the lower and upper bounds, inclusive.

There are unconstrained and constrained forms of array type definitions:

(1) *Unconstrained array type definitions*

These are array type definitions of the form

\[
\text{array} (\text{index} \{, \text{index}\}) \text{ of component subtype indication}
\]

The elaboration of such a type definition includes the evaluation of any constraint in the component subtype indication; it defines an array type. For all objects of this array type, the number of indices, the type and position of each index, and the subtype of the components are as in the type definition. (The compound symbol \(\langle\rangle\) is called a box; it stands here for an undefined range).

For each index, the actual values of the lower and upper bounds can be different for different objects of the array type but they must satisfy any range constraint imposed by the type mark.

(2) *Constrained array type definitions*

These are array type definitions of the form

\[
\text{array} \text{ index constraint of component subtype indication}
\]

The elaboration of such a type definition includes the evaluation of the index constraint and of any constraint in the component subtype indication. It defines an unconstrained array type in which each index has the base type of the corresponding discrete range, and with the same component subtype; it further defines the subtype obtained by imposing the index constraint upon the unconstrained array type. Consequently all arrays of a type declared with a constrained array type definition have the same bounds.

Unconstrained array type definitions are only allowed for type definitions used in type declarations.

**Examples of unconstrained array type declarations:**

- `type MATRIX is array(INTEGER range \(\langle\rangle\), INTEGER range \(\langle\rangle\)) of REAL;
- `type BIT_VECTOR is array(INTEGER range \(\langle\rangle\)) of BOOLEAN;
- `type ROMAN is array(NATURAL range \(\langle\rangle\)) of ROMAN_DIGIT;

**Examples of constrained array type declarations:**

- `type TABLE is array(1..10) of INTEGER;
- `type SCHEDULE is array(DAY) of BOOLEAN;
- `type LINE is array(1..MAX_LINE_SIZE) of CHARACTER;
Examples of array declarations including a constrained type definition:

``` ada
GRID : array(1 .. 80, 1 .. 100) of BOOLEAN;
MIX  : array(COLOR range RED .. GREEN) of BOOLEAN;
PAGE : array(1 .. 50) of LINE; -- an array of arrays
```

Note:

For a one-dimensional array, the rule given means that a type declaration with a constrained array type definition such as

``` ada
type T is array (INDEX) of COMPONENT;
```

is equivalent to the succession of declarations

``` ada
type unconstrained is array (INDEX range <> ) of COMPONENT;
subtype T is unconstrained (INDEX);
```

where unconstrained is an identifier distinct from those of the program. Similar transformations apply to multi-dimensional arrays.

References:

Boolean type 3.5.3, character 3.5.2, discrete type 3.5, elaboration 3.1 3.9, index value 3.6.1, integer type 3.5.4, real type 3.5.6, subtype indication 3.3, type mark 3.3

3.6.1 Index Constraints and Discrete Ranges

An index constraint specifies the possible range of each index of an array type, and thereby the corresponding array bounds.

An index constraint can be imposed on an array type mark in a subtype indication, if and only if the type mark designates an unconstrained array type. To be compatible with the type mark, the index constraint must provide a discrete range for each index; the type of each discrete range must be the same as that of the corresponding index, the range defined by each discrete range. if not a null index range (see below), must be compatible with any range constraint already imposed by the type mark given in the corresponding index.

If the bounds of a discrete range given by a range without a type mark are integer numbers or integer literal expressions, the bounds are assumed to be of the predefined type INTEGER. This rule also applies to discrete ranges used in for loops (see 5.5) and entry declarations (see 9.5).

The discrete range supplied for a given index defines a null index range if its upper bound is the predecessor of its lower bound. If an index constraint contains a null index range, any array thus constrained is a null array having no component. The lower bound of a null index range must satisfy any range constraint imposed by the type mark of the index. The upper bound of a null index range must also be a value of the base type of the index but this value need not satisfy the range constraint (if any). The exception CONSTRAINT_ERROR is raised for any incompatible discrete range or if the upper bound of a discrete range is less than the predecessor of the lower bound.
The bounds of an array object defined by an object declaration, or as component of another object, must be known when the corresponding declaration is elaborated. These bounds are necessarily known if the array subtype is given in this declaration by the type mark of a constrained array type; the corresponding index constraint defines the bounds. If the array subtype contains the type mark of an unconstrained array type, index bounds must be specified by an explicit index constraint in variable declarations and in the subtype of components; the index constraint can be omitted from the declaration of a constant, in which case the bounds are those of the initial value. The bounds of an array value satisfy an index constraint if they are equal to the bounds of the index constraint.

For an array formal parameter whose parameter declaration specifies an unconstrained array type, the bounds are obtained from the actual parameter. Within the body of the corresponding subprogram, or generic unit, the formal parameter is constrained by the values of these bounds.

The bounds of any array object created by an allocator must be known upon allocation.

The expressions defining the discrete range allowed for an index need not be static, but can depend on computed results. Arrays, one or more of whose bounds are not static, are called dynamic arrays. In records, dynamic arrays may only appear when the dynamic bounds are discriminants of the record type.

Examples of array declarations including an index constraint:

```
BOARD       : MATRIX(1..8, 1..8);
RECTANGLE   : MATRIX(1..20, 1..30);
INVERSE     : MATRIX(1..N, 1..N); -- N need not be static
FILTER      : BIT_VECTOR(0..31);
```

Example of array declaration with a constrained array type:

```
MY_TABLE    : TABLE: -- all arrays of type TABLE have the same bounds
```

Example of record type with a dynamic array as component:

```
type VAR_LINE(LENGTH: INTEGER) is record
  IMAGE: STRING(1..LENGTH);
end record;

NULL_LINE   : VAR_LINE(0); -- NULL_LINE.IMAGE is a null array
```

References:

actual parameter 6.4, allocator 4.8, base type 3.3, compatible range constraint 3.5, constant declaration 3.2, bounds 3.5, discriminant 3.7.1, elaboration 3.1 3.9, entry declaration 9.5, for loop 5.1, formal parameter 6.2 6.4, 12.1, generic program unit 12, integer type 3.5, initial value 3.2, parameter declaration 6.1, range constraint 3.5, record type 3.7, subprogram body 6.3, subtype 3.3, type mark 3.3, unconstrained array type 3.3, variable declaration 3.2
3.6.2 Array Attributes

For an array object A (or for the type mark A of a constrained array type), the following attributes are defined (N is an integer value given by a static expression):

- **A'FIRST** The lower bound of the first index.
- **A'LAST** The upper bound of the first index.
- **A'LENGTH** The number of values of the first index (zero for a null range). This attribute is overloaded and produces a result of an integer type determined by the context (see 6.6).
- **A'RANGE** The subtype defined by the range A'FIRST .. A'LAST.
- **A'FIRST(N)** The lower bound of the N-th index.
- **A'LAST(N)** The upper bound of the N-th index.
- **A'LENGTH(N)** The number of values of the N-th index (zero for a null range). This attribute is overloaded and produces a result of any integer type determined by the context (see 6.6).
- **A'RANGE(N)** The subtype defined by the range A'FIRST(N) .. A'LAST(N).

Examples (using arrays declared in the examples of section 3.6.1):

```
-- FILTER'FIRST   = 0
-- FILTER'LAST    = 31
-- FILTER'LENGTH  = 32
-- BOARD'LAST(1)   = 8
-- RECTANGLE'LAST(2) = 30
```

Note:
The above attributes are not defined for unconstrained array types. The following relations are satisfied by the above attributes if the index type is an integer type:

```
A'LENGTH   = A'LAST - A'FIRST + 1
A'LENGTH(N) = A'LAST(N) - A'FIRST(N) + 19
```

References:
attribute A. bounds 3.6. constrained array type 3.6. index 3.6. integer type 3.5.4. range 3.5. static expression 4.3.10.6. subtype 3.3. type mark 3.3.
3.6.3 Strings

The predefined type STRING denotes one-dimensional arrays of the predefined type CHARACTER, indexed by values of the predefined subtype NATURAL:

```
subtype NATURAL is INTEGER range 1 .. INTEGER'LAST;
type STRING is array (NATURAL range <>) of CHARACTER;
```

Character strings (see 2.6) are a special form of positional aggregate applicable to the type STRING and other one-dimensional arrays of characters. Catenation is a predefined operator for the type STRING and for one-dimensional array types, it is represented as &. The relational operators <, <=, >, and => are defined for strings, and correspond to lexicographic order (see 4.5.2).

Examples:

```
STARS : STRING(1 .. 120) := (1 .. 120 => 'a');
QUESTION : constant STRING := "HOW MANY CHARACTERS?";
-- QUESTION'FIRST = 1, QUESTION'LAST = 20 (the number of characters)

ASK_TWICE : constant STRING := QUESTION & QUESTION;
NINETY_SIX : constant ROMAN := "XCVI";
```

References:
aggregate 4.3, character type 3.5.2, character string 2.6, catenation 3.6.3 4.5.3, subtype 3.3

3.7 Record Types

A record object is a composite object consisting of named components, which may be of different types. The value of a record object is a composite value consisting of the values of its components.

```
record_type_definition ::= record
component_list end record

component_list ::= { component_declaration } [variant_part] | null;

component_declaration ::= identifier_list . subtype_indication := expression];
| identifier_list : array_type_definition [: = expression];
```

The elaboration of a record type definition defines a record type: it consists of the elaboration of any included component declarations, in the order in which they appear (including any component declaration in a variant part).
A component declaration defines one or more components of a type given either by a subtype indication or by a constrained array type definition.

For the elaboration of a component declaration, the identifiers of the list are first introduced; the component type is then established by elaborating the corresponding array type definition or by evaluating any constraint in the subtype indication; the identifiers can then be used to name the corresponding components. Finally, if a component declaration indicates an explicit initialization, the corresponding expression is evaluated; this initial value must satisfy any constraint imposed by the subtype indication (or by the array type definition), otherwise the exception CONSTRAINT_ERROR is raised.

If a component declaration indicates an explicit initialization, the value thus specified is the default initial value for the corresponding components. In the absence of an explicit initialization in a component declaration, a default initial value exists for the corresponding components if and only if there is one for their type. An explicit initialization may only be given if assignment is available for the component type (see 7.4).

All objects of a record type that has neither a discriminant nor a variant part have the same components. If the component list is defined by the reserved word null, the record type has no component; all records of the type are null records.

Examples:

```ada
type DATE is record
  DAY : INTEGER range 1 .. 31;
  MONTH : MONTH_NAME;
  YEAR : INTEGER range 0 .. 4000;
end record;

type COMPLEX is record
  RE : REAL := 0.0;
  IM : REAL := 0.0;
end record;
```

-- both components of every complex record are initialized to zero (if no explicit initialization).

Note:

If a default initial value exists for a component of a record type without a discriminant, it is the same for all objects of the type since it is the value obtained during the elaboration of the record type definition.

References:

array type definition 3.6, constraint 3.3, constraint_error exception 11.1, discriminant 3.7.1, elaboration 3.1, enumeration type 3.5.1, expression 4.4, identifier 2.3, object 3.2, subtype indication 3.3, variant part 3.7.3
3.7.1 Discriminants

A discriminant part can be given in the type declaration for a record type; it defines the discriminants of the type. A discriminant is a named component of any object of such a record type (appearing before any of the components in the type definition).

\[
\text{discriminant\_part ::= (discriminant\_declaration ; discriminant\_declaration)}
\]

\[
\text{discriminant\_declaration ::= identifier\_list : subtype\_indication [: = expression]}
\]

Each discriminant must belong to a discrete type. The elaboration of a discriminant declaration proceeds in the same way as that of a component declaration. Default initial values must be provided either for all or for none of the discriminants of a discriminant part.

Within a record type definition the name of a discriminant may be used either as a bound in an index constraint, or as the discriminant name of a variant part, or to specify a discriminant value in a discriminant specification. In each of these three cases, the discriminant name must appear by itself, that is, not as part of a larger expression. No other dependence between record components is allowed.

Each record value includes a value for each discriminant declared for the record type; it also includes a value for each record component that does not depend on a discriminant. The values of the discriminants determine which other component values must appear in the record value.

The discriminants of a record object can only be changed by assigning a complete record value to the object.

Record types and private types implemented as record types are the only types that may have discriminants.

Examples:

```plaintext
type BUFFER(SIZE : INTEGER range 0 .. MAX := 100) is record
    POS : INTEGER range 0 .. MAX := 0;
    VALUE : STRING(1 .. SIZE);
end record;

type SQUARE(SIDE : INTEGER) is record
    MAT : array(1 .. SIDE, 1 .. SIDE) of REAL;
end record;
```

Discriminants 3.7.1
type DOUBLE(NUMBER : INTEGER) is
record
  LEFT  : BUFFER (NUMBER);
  RIGHT : SQUARE (NUMBER);
end record;

type CUBE(SIDE : INTEGER) is
record
  VALUE  : array(1 .. SIDE) of SQUARE(SIDE);  -- double dependency
end record;

Notes:
A discriminant need not be referred to by any record component, as shown in the example below

type ITEM(NUMBER : NATURAL) is
record
  CONTENT : INTEGER;
end record;

References:
array type definition 3.6, bound 3.6, component 3.7, component declaration 3.7, constraint 3.3, discrete type 3.5, dynamic array 3.6.1, elaboration 3.1, private types 7.4.1, object 3.2, record component 3.7, record type 3.7

3.7.2 Discriminant Constraints

The allowable discriminant values for a record object can be fixed by a discriminant constraint. A record value satisfies a discriminant constraint if each discriminant of the record value has the value imposed by the corresponding discriminant specification.

discriminant_constraint ::=  
  (discriminant_specification {, discriminant_specification})

discriminant_specification ::=  
  [discriminant_name {, discriminant_name} = ] expression

Each expression specifies the value of a discriminant. The expressions can be given by position (in the order of discriminant declarations) or by naming the chosen discriminant. Named discriminant specifications can be given in any order, but if both notations are used in one discriminant constraint, the positional discriminant specifications must be given first. A discriminant constraint must provide a value for every discriminant of the type.
A discriminant constraint can be imposed on a type mark in a subtype indication if and only if the type mark does not already impose a discriminant constraint. The discriminant constraint is compatible with the type mark if and only if each specified discriminant value satisfies any range constraint imposed on the corresponding discriminant.

In the absence of default initial values for the discriminants of a type, a discriminant constraint must be supplied for every object declaration declaring an object of the type. Similarly a discriminant constraint must be imposed on such a type if this type is used in a record component declaration or as the component type in an array type definition. The constraint can be imposed either explicitly or by supplying the name of a subtype that incorporates such a constraint.

If a discriminant constraint is imposed on an object declaration, a record component, or an array component, each discriminant is initialized with the value specified in the constraint. This value overrides any discriminant default initialization and cannot later be changed.

For a formal parameter whose parameter declaration indicates a type with discriminants, these are initialized with the discriminants of the actual parameter (subject to any discriminant constraint on the formal parameter). Within the body of the corresponding subprogram, or generic unit, the value of a discriminant of the formal parameter cannot be changed if the corresponding actual parameter is constrained.

Attribute:

For any object A of a type with discriminants, the following boolean attribute is defined.

A'CONSTRAINED True if and only if a discriminant constraint applies to the object A; if A is a formal parameter, the value of this attribute is obtained from that of the actual parameter. Of type BOOLEAN.

Examples:

LARGE : BUFFER(200); -- always 200 characters: LARGE'CONSTRAINED = TRUE
MESSAGE : BUFFER; -- initially 100 characters: MESSAGE'CONSTRAINED = FALSE
BASIS : SQUARE(5); -- constrained, always 5 by 5
ILLEGAL : SQUARE; -- illegal, a SQUARE must be constrained

Notes:

The above rules ensure that discriminants always have a value, either because they must be constrained, or because of the existence of a default initial value.

If a subtype declaration includes a discriminant constraint, all objects of this subtype are constrained and their discriminants are initialized accordingly.

References:

actual parameter 6.4, array type definition 3.6, component subtype 3.6, constraint_error exception 11.1, default initial value 3.7, discriminant 3.7.1, expression 4.4, formal parameter 6.2 6.4, generic program unit 12, record component 3.7, record object 3.7, subtype declaration 3.3, type mark 3.3
3.7.3 Variant Parts

A record type with a variant part specifies alternative lists of components. Each variant defines the components for the corresponding value (or values) of the discriminant. A variant can have an empty component list, which must be specified by null.

```
variant_part ::= case discriminant_name is
    {when choice {! choice} => component_list}
end case;
choice ::= simple_expression | discrete_range | others
```

A record value must contain the component values of a given variant if the discriminant value is equal to one of the values specified by the choices prefixing the corresponding component list. This rule applies in turn to any further variants which may be included in the component list of the given variant.

A choice given as a discrete range stands for all values in the corresponding range. The choice others stands for all values of the discriminant type (possibly none) that are not specified in previous choices; it can only appear alone and for the last component list. Each value of the discriminant subtype if this subtype is static, otherwise each value of the discriminant type, must be represented once and only once in the set of choices of a variant part. The value of a choice given in a variant part must be determinable statically (see 4.9).

**Example of record type with a variant part:**

```
type DEVICE is (PRINTER, DISK, DRUM);
type STATE is (OPEN, CLOSED);
type PERIPHERAL(UNIT : DEVICE := DISK) is record
    STATUS : STATE;
    case UNIT is
        when PRINTER =>
            LINE_COUNT : INTEGER range 1 .. PAGE_SIZE;
        when others =>
            CYLINDER : CYLINDER_INDEX;
            TRACK : TRACK_NUMBER;
    end case;
end record;
```

**Examples of record subtypes:**

```
subtype DRUM_UNIT is PERIPHERAL(DRUM);
subtype DISK_UNIT is PERIPHERAL(DISK);
```

**Examples of constrained record variables:**

```
WRITER : PERIPHERAL(UNIT => PRINTER);
ARCHIVE : DISK_UNIT;
```
Note:
Choices with discrete values are also used in case statements and in aggregates.

References:
aggregate 4.3, case statement 5.1, discrete range 3.6.1, discriminant 3.7.1, discrete type 3.5, simple expression 4.4, subtype 3.3

3.8 Access Types

Objects declared in a program are accessible by their name. They exist during the lifetime of the declarative part to which they are local. In contrast, objects may also be created by the execution of allocators (see 4.8). Since they do not occur in an explicit object declaration, they cannot be denoted by their name. Instead, access to such an object is achieved by an access value returned by an allocator; the access value is said to designate the object.

access_type_definition ::= access subtype_indication

incomplete_type_declaration ::= type identifier [discriminant_part];

The elaboration of an access type definition causes the evaluation of any constraint given in the subtype indication. The access type resulting from this elaboration is the type of a set of access values. This set includes the value null designating no object at all. Other access values of the type can be obtained by execution of an allocator associated with the type. Each such access value designates an object of the subtype indicated after the reserved word access. The objects created by an allocator and designated by the values of an access type form a collection implicitly associated with the type.

The null value of an access type is the default initial value of the type. An access value obtained by an allocator can be assigned to several access variables. Hence an object created by an allocator may be designated by more than one variable or constant of the access type. If an access object is constant, the contained access value always designates the same object but the value of the designated object can be modified.

If the subtype indication in the access type definition denotes either an unconstrained array type or a type with discriminants but without a discriminant constraint, the corresponding index bounds or discriminant values must be supplied for each allocator. The allocated object is constrained by these values.

Components of an object designated by a value of an access type may have values of the same or of another access type. This permits recursive and mutually dependent access types. Their declaration requires a prior incomplete type declaration for one or more types. Whenever an incomplete type declaration appears in a list of declarative items, the full type declaration must appear later in the same list of declarative items. Both the incomplete type declaration and the corresponding full type declaration must have the same discriminant part (if any) which is elaborated on y once, at the earlier occurrence. The correspondence between the incomplete and the full type declaration follows the same rules as for private types (see 7.4.1). The name of a yet incompletely defined type can be used only as the type mark of the subtype indication of an access type definition.
The only constraint that can appear after the name of an access type in a subtype indication (for example one used in the declaration of an access variable) is either a discriminant constraint or an index constraint. Such a constraint is imposed on any object designated by a value of the access type (hence by any value other than null); the type of the designated objects must be a type with the corresponding discriminants or indexes.

Examples:

```ada
type FRAME is access MATRIX;

type BUFFER_NAME is access BUFFER;

type CELL; -- incomplete type declaration

type LINK is access CELL;

type CELL is
    record
        VALUE : INTEGER;
        SUCC : LINK;
        PRED : LINK;
    end record;

HEAD : LINK := new CELL(0, null, null);
```

Examples of mutually dependent access types:

```ada
type PERSON(SEX : GENDER); -- incomplete type declaration
type CAR; -- incomplete type declaration

type PERSON_NAME is access PERSON;
type CAR_NAME is access CAR;

type PERSON(SEX : GENDER) is
    record
        NAME : STRING(1 .. 20);
        AGE : INTEGER range 0 .. 130;
        VEHICLE : CAR_NAME;
        case SEX is
            when M => WIFE : PERSON_NAME(SEX => F);
            when F => HUSBAND : PERSON_NAME(SEX => M);
        end case;
    end record;

type CAR is
    record
        NUMBER : INTEGER;
        OWNER : PERSON_NAME;
    end record;

MY_CAR, YOUR_CAR, NEXT_CAR : CAR_NAME; -- initialized with null
```

5.9 Access Types
3.9 Declarative Parts

A declarative part contains declarations and related information that apply over a region of program text. Declarative parts may appear in blocks, subprograms and packages.

\[
declarative\_part ::= \\
\quad \{declarative\_item\} \{representation\_specification\} \{program\_component\}
\]

\[
declarative\_item ::= declaration \mid use\_clause
\]

\[
program\_component ::= body \\
\quad \mid package\_declaration \mid task\_declaration \mid body\_stub
\]

\[
body ::= subprogram\_body \mid package\_body \mid task\_body
\]

For the elaboration of a declarative part, its constituents (possibly none) are successively elaborated in the order in which they appear in the program text.

The body of a subprogram, package, or task declared in a declarative part must be provided in the same declarative part, but if the body of one of these program units is a separately compiled subunit (see 10.2), it must be represented by a body stub at the place where it would otherwise appear.

Access to any entity before its elaboration is not allowed. In particular, a subprogram must not be called during the elaboration of a declarative part if its subprogram body appears later than the place of the call.

The exception STORAGE_ERROR may be raised by the elaboration of a declarative part if storage does not suffice for the declared entities.

References:

Elaboration of declarations 3.1. discriminant d. 3.7.1, entry d. 9.5, generic d. 12.1, loop parameter d. 5.5, number d. 3.2, object d. 3.2, package d. 7.2, parameter d. 6.1, renaming d. 8.5, subprogram d. 6.1, subtype d. 3.3, type d. 3.3

Elaboration of type definitions 3.3. access t.d. 3.8, array t.d. 3.6, derived t.d. 3.4, enumeration t.d. 3.5.1, integer t.d. 3.5.4, private t.d. 7.4, real t.d. 3.5.6, record t.d. 3.7


exception during elaboration 11.4.2, order of elaboration 10.5
4. Names and Expressions

4.1 Names

Names can denote declared entities. These are objects, numbers, types, and subtypes, subprograms, packages, tasks, and their entries, and exceptions. Names can also be labels, block names, or loop names. Particular forms of names denote attributes, operators, and components of objects. Finally, a name can denote the result returned by a function call.

name ::= identifier
| indexed_component | slice
| selected_component | attribute
| function_call | operator_symbol

The simplest form for the name of an entity is the identifier given in its declaration. Function calls and operator symbols are described in Chapter 6.4. The remaining forms of names are described here.

Examples of simple names:

P1 -- the name of a number
LIMIT -- the name of a constant
COUNT -- the name of a scalar variable
BOARD -- the name of an array variable
MATRIX -- the name of a type
SORT -- the name of a function
ERROR -- the name of an exception

References:

array type definition 3.6, boolean type 3.5.3, bound 3.6, component 3.2, identifier 2.3, index value 3.8.1, function call 6.4, numeric type 3.5, numeric_error exception 4.5.8 11.1, operator symbol 6.1, range 3.5, type declaration 3.3

4.1.1 Indexed Components

An indexed component denotes either a component of an array or an entry in a family of entries.

indexed_component ::= name(expression [, expression])
In the case of a component of an array, the name denotes an array object (or an access object whose value designates an array object). Alternatively, the name can be a function call delivering an array (or delivering an access value that designates an array). The expressions specify the index values for the component; there must be one such expression for each index position of the array type.

In the case of an entry in a family of entries, the name denotes an entry family and the expression (only one can be given) specifies the index value for the individual entry.

Each expression must be of the type of the corresponding index. If evaluation of an expression gives an index value that is outside the range specified for the index, the exception CONSTRAINT_ERROR is raised. This exception is also raised if the name denotes an access object whose value is null.

Examples of indexed components:

- MY_TABLE(5) -- a component of a one dimensional array
- PAGE(10) -- a component of a one dimensional array
- BOARD(M, J + 1) -- a component of a two dimensional array
- PAGE(10)(20) -- a component of a component
- REQUEST(MEDIUM) -- an entry of the family REQUEST
- NEXT_FRAME(F)(M, N) -- an indexed component of the function call NEXT_FRAME(F)

Notes on the examples:

Distinct notations are used for components of multidimensional arrays (such as BOARD) and arrays of arrays (such as PAGE). The components of an array of arrays are arrays and can therefore be indexed. Thus PAGE(10)(20) denotes the 20th component of PAGE(10).

Note:

The language does not define the order of evaluation of the different expressions of an indexed component of a multi-dimensional array. Hence programs that rely on a particular order are erroneous.

References:

access value 3.8, array type definition 3.6, array component 3.6, constraint_error exception 11.1, entry 9.5, entry family 9.5, expression 4.4, function 6.5, function call 6.4, index value 3.6.1, name 4.1 range 3.5

4.1.2 Slices

A slice is a one dimensional array denoting a sequence of consecutive components of a one dimensional array.

slice := name (discrete_range)

The name given in a slice denotes an array object (or an access object whose value designates an array object). The name can be a function call delivering an array (or delivering an access value that designates an array).
The type of a slice is the base type of the named array. The bounds of the slice are given by the discrete range; the slice is a null slice denoting a null array if the discrete range is a null range (see 3.6.1).

If a slice is not null, the index values of its discrete range must be possible index values for the named array; otherwise the exception CONSTRAINT_ERROR is raised. This exception is also raised if the name denotes an access object whose value is null.

Examples of slices:

```
STARS(1 .. 15) -- a slice of 15 characters
PAGE(10 .. 10 + SIZE) -- a slice of 1 + SIZE components
PAGE(L)(A .. B) -- a slice of the array PAGE(L)
STARS(1 .. 0) -- a null slice
MY_SCHEDULE(WEEKDAY) -- bounds given by subtype
STARS(5 .. 15)(9) -- same as STARS(9)
```

Note:

For a one dimensional array A, the name A(N .. N) is a slice of one component; its type is the base type of A. On the other hand A(N) is a component of the array A and has the corresponding component type.

References:

access object 3.8, access value 3.8, array type definition 3.6, base type 3.3, bound 3.6, 3.6.1, constraint_error exception 11.1, discrete range 3.6.1, function 6.5, function call 6.4, index 3.6, name 4.1, null array 3.6.1, null range 3.6.1, type definition 3.3

4.1.3 Selected Components

Selected components are used to denote record components. They are also used for objects designated by access values. Finally, selected components are used to form names of declared entities.

```
selected_component ::= =
     name_identifier | name.all | name.operator_symbol
```

A selected component can denote either

(a) A component of a record:

The name denotes a record (or an access object whose value designates a record) and the identifier specifies the record component. The name can be a function call delivering a record (or delivering an access value that designates a record).

(b) An object designated by an access value:

The name denotes an access object and is followed by a dot and the reserved word all. The name can be a function call delivering an access value.
(c) An entity declared in the visible part of a package:

The name denotes a package and the identifier specifies the declared entity. For an operator, the corresponding operator symbol (that is, the operator enclosed by double quotes) follows the name of the package and the dot.

(d) An entry (or entry family) of a task:

The name denotes a task object (or if the selected component occurs in a task body, this program unit) and the identifier specifies one of its entries (one of its entry families).

(e) An entity declared in an enclosing subprogram body, package body, task body, block, or loop:

The name denotes this (immediately) enclosing unit and the identifier (or the operator symbol) specifies the declared entity. This notation is only allowed within the named enclosing unit. If there is more than one visible enclosing overloaded subprogram of the given name, the selected component is ambiguous, independently of the identifier (see section 8.2 on visibility rules).

For variant records, a component identifier can denote a component in a variant part. In such a case, the component must be one of those that must be present for the existing discriminant value (or values), otherwise the exception CONSTRAINTERROR is raised. This exception is also raised if the name has the access value null in the above cases (a) and (b).

Examples of selected components:

- APPOINTMENT.DAY -- a record component
- NEXT_CAR.OWNER -- a record component
- NEXT_CAR.OWNER.AGE -- a record component
- WRITER.UNIT -- a record component (a discriminant)
- MIN_CELL(H).VALUE -- a selected component of the function call MIN_CELL(H)
- NEXT_CAR.all -- the object designated by the access variable NEXT_CAR
- TABLE_MANAGER.INSERT -- a procedure in the package TABLE_MANAGER
- APPLICATION."*" -- an operator in the package APPLICATION
- CONTROL.SEIZE -- an entry of the task CONTROL
- POOL(K).WRITE -- an entry of the task POOL(K)
- MAIN.ITEM_COUNT -- a variable declared in the procedure MAIN

Notes:

Every parameterless function call must use empty parentheses (see 6.4). Hence F().C can only be a selected component of the function result and, within the body of F, F.L can only be used to denote a locally declared entity L. For a record with components that are other records, the identifier of each level must be given to name a nested component.
Names and Expressions

References:
access object 3.8, access value 3.8, constraint_error exception 11.1, discriminant value 3.7.1, entity 3.1, function call 6.4, identifier 2.3, name 4.1, operator 4.5, operator symbol 6.1, overloading a subprogram 6.6, package 7, package body 7.3, record type 3.7, record component 3.7, subprogram body 6.3, task 9, task body 9.1, variant part 3.7.3, visible part 7.2

4.1.4 Attributes

Attributes denote certain predefined characteristics of named entities.

attribute ::= name'identifier

An attribute identifier is always prefixed by an apostrophe; such an identifier is not reserved (unless it is already reserved for another reason). An attribute can be a value, a function, or a type or subtype. Specific attributes are described with the language constructs associated with their use.

Appendix A gives a list of all the language defined attributes. Additional attributes may exist for an implementation.

Examples of attributes:

COLOR'FIRST -- minimum value of the enumeration type COLOR
RAINBOW'BASE'FIRST -- same as COLOR'FIRST
REAL'DIGITS -- precision of the type REAL
BOARD'LAST(2) -- upper bound of the second dimension of BOARD
BOARD'RANGE(1) -- subtype of index range of the first dimension of BOARD
POOL(K)'TERMINATED -- TRUE if task POOL(K) is terminated
DATE'SIZE -- number of bits for records of type DATE
CARD'ADDRESS -- address of the record variable CARD

References
enumeration type 3.5.1, function 6.5, identifier 2.3, real type 3.5.6, record variable 3.7, subtype declaration 3.5, task 9, type declaration 3.3, upper bound 3.6 3.6.1, value 3.2 3.3

4.2 Literals

A literal denotes an explicit value of a given type.
literal ::= numeric_literal | enumeration_literal | character_string | null

Numeric literals are the literals of the types universal_integer and universal_real. Enumeration literals include character literals and denote values of the corresponding enumeration types. A character string denotes a one dimensional array of characters. The literal null stands for the null access value which designates no object at all.

Literals 4.2
Examples:

- 3.14159_26536  -- a real literal
- 1_345  -- an integer literal
- CLUBS  -- an enumeration literal
- 'A'  -- an enumeration literal that is a character literal
- "SOME TEXT"  -- a character string

References:

array type definition 3.6, character literal 2.5, character string 2.6, enumeration literal 3.5.1, null access value 3.8, numeric literal 2.4 3.2 4.10, universal_integer type 2.4 3.2 3.5.4 4.10, universal_real type 2.4 3.2 3.5.6

4.3 Aggregates

An aggregate denotes a record or an array value constructed from component values.

aggregate ::= (component_association {, component_association})

component_association ::= [choice {choice} => ] expression

The expressions define the values to be associated with components. An aggregate must be complete, that is, a value must be provided for each component of the composite value. Component associations can be given by position (in textual order for record components) or by naming the chosen components. Choices have the same syntax as in variant parts (see 3.7.3); they are component identifiers in the case of record aggregates, index values or ranges of index values in the case of array aggregates. Each value, or each component identifier must be represented once and only once in the set of choices of an aggregate. The choice others can only appear alone and in the last component association; it stands for all remaining components, if any.

For named components, the component associations can be given in any order (except for the choice others), but if both notations are used in one aggregate, all positional component associations must be given first. Aggregates containing a single component association must always be given in named notation. Specific rules concerning component associations exist for record aggregates and array aggregates.

An expression given in a component association must satisfy any constraint associated with a corresponding component, otherwise the exception CONSTRAINT_ERROR is raised.

Note:

The language does not define the order of evaluation of the expressions of the different component associations. Hence programs relying on a particular order are erroneous.

Aggregates may be overloaded, that is, a given aggregate may be an aggregate for more than one array or record type, its interpretation depending on the context.
4.3.1 Record Aggregates

A record aggregate denotes a record value and must specify an explicit value for each component (including discriminants) of the record value, whether or not a default initial value exists for the component. A component association with more than one choice is only allowed if the denoted components are of the same type. The same rule applies for the choice others representing all other components.

The value specified for a discriminant governing a variant part must be given by a static expression.

Examples of positional record aggregate:

(4, JULY, 1776)

Examples of record aggregates with named components:

(DAY => 4, MONTH => JULY, YEAR => 1776)
(MONTH => JULY, DAY => 4, YEAR => 1776)
(UNIT => DISK, STATUS => CLOSED, CYLINDER => 9, TRACK => 1)
(DISK, CLOSED, TRACK => 5, CYLINDER => 12)

Note:

For positional aggregates, discriminant values appear first since the discriminant part is given first; they must be in the same order as in the discriminant part.

References:

component association 4.3, default initial value 3.3 3.7, discriminant 3.7.1, discriminant part 3.7.1, discriminant value 3.7.1, record value 3.3 3.7, static expression 4.9, variant part 3.7.3

4.3.2 Array Aggregates

An array aggregate denotes an array value.

For aggregates in named notation, a choice given by a simple expression stands for the corresponding index value; a choice given by a discrete range stands for all possible index values in the range. The value of each choice (excepting others) must be determinable statically unless the aggregate consists of a single component association, including a single choice.

The bounds of a named aggregate that does not contain the choice others are determined by the smallest and largest choices given.
The bounds of any aggregate containing the choice others are defined by the context. The only allowable contexts for such an aggregate are as follows:

(a) The aggregate is an actual parameter corresponding to a formal parameter of a constrained array subtype.

(b) The aggregate appears in a return statement as the expression specifying the value returned by a function whose result is of a constrained array subtype.

(c) The aggregate is either qualified by a constrained array subtype, or used in an allocator for a constrained array subtype.

(d) The aggregate is used to specify the value of a component of an enclosing aggregate, and the enclosing aggregate is itself in one of these four contexts.

In each of these four cases the bounds are defined by the applicable index constraint.

The bounds of a positional aggregate not containing the choice others are similarly defined by the applicable index constraint, if the aggregate appears in one of the above four contexts. Otherwise, the lower bound is given by S'FIRST, where S is the index subtype; the upper bound is determined by the number of components.

An aggregate for an n-dimensional array is written as a one-dimensional aggregate of components that are (n-1)-dimensional array values. If an array aggregate contains positional component associations, the only named association it may contain is a component association with the choice others.

The exception CONSTRAINT_ERROR is raised if the number of components of the aggregate is incompatible with the context.

Examples of positional array aggregates:

(7, 9, 5, 1, 3, 2, 4, 8, 6, 0)
TABLE'(5, 8, 4, 1, others => 0)

Examples of array aggregates in named notation:

(1 .. 5 => (1 .. 8 => 0.0))
TABLE'(2 | 4 | 10 => 1, others => 0) -- qualified by TABLE, see 4.7
SCHEDULE'(MON .. FRI => TRUE, others => FALSE)
SCHEDULE'(WED .. SUN => FALSE, others => TRUE)

Examples of aggregates as initial values:

A : TABLE := (7, 9, 5, 1, 3, 2, 4, 8, 6, 0); -- A(1) = 7, A(10) = 0
B : TABLE := TABLE'(2 | 4 | 10 => 1, others => 0); -- B(1) = 0, B(10) = 1
C : constant MATRIX := (1 .. 5 => (1 .. 8 => 0.0)); -- C'FIRST(1) = 1, C'LAST(2) = 8
D : BIT_VECTOR(M .. N) := (M .. N => TRUE);
E : BIT_VECTOR(M .. N) := (E'_RANGE => TRUE);
F : STRING(1 .. 1) := (1 => 'F'); -- a one component aggregate: same as "F"

4.2 Array Aggregates
4.4 Expressions

An expression is a formula that defines the computation of a value.

expression ::= relation (and relation)
| relation (or relation)
| relation (xor relation)
| relation (and then relation)
| relation (or else relation)

relation ::= simple_expression [relational_operator simple_expression]
| simple_expression [not] in range
| simple_expression [not] in subtype_indication

simple_expression ::= [unary_operator] term [adding_operator term]

term ::= factor [multiplying_operator factor]

factor ::= primary [** primary]

primary ::= literal | aggregate | name | allocator | function_call
| type_conversion | qualified_expression | (expression)

Each primary has a value and a type. The only names allowed as primaries are attributes (those which have a value) and names denoting objects (the value of such a primary is the value of the object). The type of an expression depends only on the type of its constituents and on the operators applied; for an overloaded constituent or operator, the determination of the constituent type or the identification of the appropriate operator, may depend on the context. The rules defining the allowed operand types and the corresponding result types for all predefined operators are given in section 4.5 below.

Examples of primaries:

4.0 -- real literal
(1 .. 10 => 0) -- aggregate array value
VOLUME -- value of a variable
DATE'SIZE -- attribute
SINE(X) -- function call
COLOR'(BLUE) -- qualified expression
REAL(M+N) -- conversion
(LINE_COUNT + 10) -- parenthesized expression
Examples of expressions:

- VOLUME
- B**2
- LINE_COUNT mod PAGE_SIZE
- -4.0
- not DESTROYED
- B**2 - 4.0*A*C
- PASSWORD(1 .. 5) = "JAMES"
- N not in 1 .. 10
- INDEX = 0 or ITEM_HIT
- (COLD and SUNNY) or WARM
- A**(B**C)

References:

adding operator 4.5.3, aggregate 4.3, allocator 4.8, array aggregate 4.3.2, attribute 4.1.4, function call 6.4, literal 2.5 4.2, multiplying operator 4.5.5, name 4.1, object 3.2, overloading 3.5.1, 6.6 6.7, qualified expression 4.7, range 3.5, subtype indication 3.3, type 3, type conversion 4.6, unary operator 4.5.4, value 5.3, variable 3.2 4.1

4.5 Operators and Expression Evaluation

The following operators, divided into six classes, have a predefined meaning in the language. These operators, and only these, may be overloaded for user defined types and, excepting equality and inequality, may be redefined (see 6.7). They are given in the order of increasing precedence.

- logical operator ::= and | or | xor
- relational operator ::= = | /= | < | <= | > | >=
- adding operator ::= + | - | &
- unary operator ::= + | - | not
- multiplying operator ::= * | / | mod | rem
- exponentiating operator ::= **

The short circuit control forms and then and or else have the same precedence as logical operators. The membership tests in and not in have the same precedence as relational operators.

All operands of a factor, term, simple expression, or relation, and the operands of an expression that does not contain a short circuit control form, are evaluated (in an undefined order) before application of the corresponding operator. The right operand of a short circuit control form is evaluated if and only if the left operand has a certain value (see 4.5.1).
Names and Expressions

For a term, simple expression, relation, or expression, operators of higher precedence are applied first. In this case, for a sequence of operators of the same precedence level, the operators are applied in textual order from left to right (or in any order giving the same result); parentheses can be used to impose a specific order.

The execution of some operations may raise an exception for certain values of the operands. Real expressions are not necessarily evaluated with exactly the specified accuracy (precision or delta), but the accuracy will be at least as good as that specified.

Examples of precedence:

```
not SUNNY or WARM       -- same as (not SUNNY) or WARM
X > 4.0 and Y > 0.0      -- same as (X > 4.0) and (Y > 0.0)
-4.0*A**2               -- same as -(4.0 * (A**2))
Y**(-3)                 -- parentheses are necessary
A / B * C               -- same as (A/B)*C
A + (B + C)             -- evaluate B + C before adding it to A
```

Note:
The language does not define the order of evaluation of the two operands of an operator (excepting short circuit control forms). A program that relies on a specific order (for example because of mutual side effects) is therefore erroneous.

References:
accuracy of operations with real operands 4.5.8, adding operator 4.5.3, delta 3.5.9, exception 11, expression 4.4, factor 4.4, logical operator 4.5.1, membership operator 4.5.2, name 4.1, overloading an operator 6.7, precision 3.5.6, real type definition 3.5.6, relation 4.4, relational operator 4.5.2, short circuit control form 4.5.1, simple expression 4.4, term 4.4, type 3

4.5.1 Logical Operators and Short Circuit Control Forms

The predefined logical operators are applicable to BOOLEAN values and to one dimensional arrays of BOOLEAN values having the same number of components. The operations on (non null) arrays are performed on a component by component basis on matching components (as for equality, see 4.5.2). The lower bound of the index of the resulting array is the lower bound of the index subtype of the array type.

```
Operator   Operation     Operand Type          Result Type
and        conjunction   BOOLEAN array of BOOLEAN components   BOOLEAN same array type
or         inclusive disjunction  BOOLEAN array of BOOLEAN components  BOOLEAN same array type
xor        exclusive disjunction  BOOLEAN array of BOOLEAN components  BOOLEAN same array type
```

Logical Operators and Short Circuit Control Forms 4.5.1
The operands need not have the same bounds, but must have the same number of components, otherwise the exception CONSTRAINT_ERROR is raised.

The short circuit control forms and then and or else are applied to operands of the predefined type BOOLEAN and deliver a value of this type. If the left operand of an expression with the control form and then evaluates to FALSE, the right operand is not evaluated and the value of the expression is FALSE. If the left operand of an expression with the control form or else evaluates to TRUE, the right operand is not evaluated and the value of the expression is TRUE. If both operands are evaluated, and then delivers the same result as and, and or else delivers the same result as or.

Examples of logical operators:

- SUNNY or WARM
- FILTER(1 .. 10) and FILTER(15 .. 24)

Examples of short circuit control forms:

- NEXT_CAR.OWNER /= null and then NEXT_CAR.OWNER.AGE > 25
- N = 0 or else A(N) = HIT_VALUE

References:

- array type definition 3.6, boolean type 3.5.3, boolean value 3.5.3, bound 3.6.1, component 3.6, constraint_error exception 11.1, equality 4.5.2, expression 4.4, false 3.5.3, index 3.6, true 3.5.3

4.5.2 Relational and Membership Operators

The predefined relational operators have operands of the same type and return values of the predefined type BOOLEAN. Equality and inequality are predefined for any two objects of the same type, excepting limited private types and composite types having components of limited private types.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>= /=</td>
<td>equality and inequality</td>
<td>any type</td>
<td>BOOLEAN</td>
</tr>
<tr>
<td>&lt; &lt;= &gt; &gt;=</td>
<td>test for ordering</td>
<td>any scalar type, discrete array type</td>
<td>BOOLEAN</td>
</tr>
</tbody>
</table>

Equality for the discrete types is equality of the values. For real operands whose values are nearly equal, the results of the predefined relational operators are given in section 4.5.8. Two access values are equal if they designate the same object; or if both are equal to null.

The values of two non null arrays or two non null records, of the same type, are equal if and only if their matching components are equal, as given by the predefined equality operator for the component type. Two null arrays of the same type are always equal; two null records of the same type are always equal. If equality is explicitly defined for a limited private type, it does not extend to composite types having components of the limited private type. Equality can be defined explicitly for such composite types.
For comparing two non null records of the same type, matching components are those which have the same component identifier.

For comparing two non null one dimensional arrays of the same type, matching components are those whose index values match in the following sense: the lower bounds of the index ranges are defined to match, and the successors of matching indices are defined to match. For multidimensional arrays, matching components are those whose index values match in successive index positions. If any component of an array has no matching component in the other array, the two arrays are not equal.

The inequality operator gives the complementary result to the equality operator.

The ordering operators <, <=, >, and >= are defined for one dimensional arrays of an array type whose components are of a discrete type. These operators correspond to lexicographic order using the order relation of the component type for corresponding components. A null array is less than any array having at least one component.

The membership tests in and not in test whether a value is within a corresponding range, or whether it satisfies any constraint imposed by a subtype indication. The value must be of the same type as the bounds of the range or as the base type of the subtype. These operators return a value of the predefined type BOOLEAN. A test for an accuracy constraint always yields the result TRUE.

**Examples:**

\[
X \neq Y \quad \text{-- with real } X \text{ and } Y, \text{ is implementation dependant}
\]

\[
"A" \lt "A" \text{ and } "A" \lt "AA" \quad \text{-- TRUE}
\]

\[
"AA" \lt "B" \quad \text{-- TRUE}
\]

\[
\text{MY\_CAR = null} \quad \text{-- true if MY\_CAR has been set to null}
\]

\[
\text{MY\_CAR = YOUR\_CAR} \quad \text{-- true if we both share the same car}
\]

\[
\text{MY\_CAR.all = YOUR\_CAR.all} \quad \text{-- true if the two cars are identical}
\]

\[
\text{N not in 1 .. 10} \quad \text{-- range check}
\]

\[
\text{TODAY in WEEKDAY} \quad \text{-- subtype check}
\]

\[
\text{TODAY in \text{DAY range } MON .. FRI} \quad \text{-- same subtype check}
\]

\[
\text{ARCHIVE in DISK\_UNIT} \quad \text{-- subtype check}
\]

**References:**

access value 3.8, accuracy constraint 3.5.6, accuracy of operations with real operands 4.5.8, array type definition 3.6, boolean type 3.5.3, bounds 3.6, component 3.3, composite type 3.6 3.7, constraint 3.3, delta attribute 3.5.10, discrete type 3.5, fixed point type 3.5.9, floating point type 3.5.7, index range 3.6, index value 3.6, limited private type 7.4.2, range 3.5, real type 3.5.6, record value 3.7, scalar type 3.5, subtype declaration 3.3, small attribute 3.5.8, type declaration 3
4.5.3 Adding Operators

The predefined adding operators + and - return a result of the same type as the operands.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>+</td>
<td>addition</td>
<td>numeric type</td>
<td>same numeric type</td>
</tr>
<tr>
<td>-</td>
<td>subtraction</td>
<td>numeric type</td>
<td>same numeric type</td>
</tr>
<tr>
<td>&amp;</td>
<td>catenation</td>
<td>one dimensional array type</td>
<td>same array type</td>
</tr>
</tbody>
</table>

For real types, the accuracy of the result is determined by the operand type. For all numeric types the exception NUMERIC_ERROR is raised if the result of addition or subtraction does not lie within the implemented range of the type (for real operands see 4.5.8).

The adding operator & (catenation) is applied to two operands of a one dimensional array type. Catenation is also defined for a left operand of a one dimensional array type and a right operand of the corresponding component type and vice versa. The result is an array of the same type. For any one-dimensional array type T whose component type is C and whose index is specified as

\[ \text{INDEX range} \]

the effect of catenation is defined by the three following functions

\[
\text{LOW} : \text{constant INDEX} := \text{INDEX'FIRST};
\]

\[
\text{function "&" (X,Y:T) return T is}
\]

\[
\begin{align*}
\text{RESULT} & : T(\text{LOW}..\text{INDEX'VAL(\text{INDEX'POS(LINDEX}) + (X'LENGTH + Y'LENGTH - 1})}); \\
\text{begin} & \\
\text{RESULT(LOW..INDEX'VAL(INDEX'POS(LINDEX) + (X'LENGTH - 1)})} & := X; \\
\text{RESULT(INDEX'VAL(INDEX'POS(LINDEX) + X'LENGTH))..RESULT'LAST} & := Y; \\
\text{return RESULT;}
\end{align*}
\]

\[
\text{function "&" (X:C;Y:T) return T is}
\]

\[
\begin{align*}
\text{begin} & \\
\text{return (LOW \Rightarrow X) \& Y};
\end{align*}
\]

\[
\text{function "&" (X:T;Y:C) return T is}
\]

\[
\begin{align*}
\text{begin} & \\
\text{return X \& (LOW \Rightarrow Y)};
\end{align*}
\]

The exception CONSTRAINT_ERROR is raised if the upper bound of the result exceeds the range of the index subtype.

Examples:

\[
Z \times 0.1 \quad \text{-- Z must be of a real type}
\]

\[
"A" \& "BCD" \quad \text{-- catenation of two strings}
\]
Names and Expressions

References:

accuracy of operations 4.5.8, array type 3.6, catenation 3.6.3, numeric type 3.5, numeric_error exception 11.1, real type 3.5.6, string 2.6 3.6.3, type declaration 3

4.5.4 Unary Operators

The predefined unary operators are applied to a single operand and return a result of the same type.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>+</td>
<td>identity</td>
<td>numeric type</td>
<td>same numeric type</td>
</tr>
<tr>
<td>-</td>
<td>negation</td>
<td>numeric type</td>
<td>same numeric type</td>
</tr>
<tr>
<td>not</td>
<td>logical negation</td>
<td>BOOLEAN</td>
<td>BOOLEAN</td>
</tr>
<tr>
<td></td>
<td></td>
<td>array of BOOLEAN components</td>
<td>same array type</td>
</tr>
</tbody>
</table>

The operator not may be applied to a one dimensional array of BOOLEAN components. The result is a one dimensional boolean array with the same bounds; each component of the result is obtained by logical negation of the corresponding component of the operand (that is, the component which has the same index value).

For a numeric operand, the exception NUMERIC_ERROR is raised if the result does not lie within the implemented range of the type (for real operands see 4.5.8).

References:

accuracy of operations with real operands 4.5.8, array type 3.6, numeric type 3.5, numeric_error exception 11.1

4.5.5 Multiplying Operators

The predefined operators * and / for integer and floating point values and the predefined operators mod and rem for integer values return a result of the same type as the operands.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>*</td>
<td>multiplication</td>
<td>integer</td>
<td>same integer type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>floating</td>
<td>same floating point type</td>
</tr>
<tr>
<td>/</td>
<td>integer division</td>
<td>integer</td>
<td>same integer type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>floating</td>
<td>same floating point type</td>
</tr>
<tr>
<td>mod</td>
<td>modulus</td>
<td>integer</td>
<td>same integer type</td>
</tr>
<tr>
<td>rem</td>
<td>remainder</td>
<td>integer</td>
<td>same integer type</td>
</tr>
</tbody>
</table>
Integer division and remainder are defined by the relation

\[ A = (A/B) \times B + (A \text{ rem } B) \]

where \((A \text{ rem } B)\) has the sign of \(A\) and an absolute value less than the absolute value of \(B\). Integer division satisfies the identity

\[ (-A)/B = -(A/B) = A/(-B) \]

The result of the modulus operation is such that \((A \mod B)\) has the sign of \(B\) and an absolute value less than the absolute value of \(B\); in addition this result must satisfy the relation

\[ A = B \times N + (A \mod B) \]

for some integer value of \(N\).

For fixed point values, the following multiplication and division operations are provided. The types of the left and right operands are denoted by \(L\) and \(R\).

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>multiplication</td>
<td>fixed integer integer</td>
<td>same as (L)</td>
</tr>
<tr>
<td></td>
<td>fixed integer</td>
<td>integer fixed</td>
<td>same as (R)</td>
</tr>
<tr>
<td></td>
<td>fixed fixed</td>
<td>fixed fixed</td>
<td>universal fixed</td>
</tr>
<tr>
<td></td>
<td>division</td>
<td>fixed integer integer</td>
<td>same as (L)</td>
</tr>
<tr>
<td></td>
<td>fixed fixed</td>
<td>fixed fixed</td>
<td>universal fixed</td>
</tr>
</tbody>
</table>

Integer multiplication of fixed point values is equivalent to repeated addition and hence is an accurate operation. Division of a fixed point value by an integer does not involve a change in type but is approximate.

Multiplication of operands of the same or of different fixed point types is exact and delivers a result of the type \(\text{universal\_fixed}\) whose delta is arbitrarily small. The result of any such multiplication must always be explicitly converted to some numeric type. This ensures explicit control of the accuracy of the computation. The same considerations apply to division of a fixed point value by another fixed point value.

The exception \(\text{NUMERIC\_ERROR}\) is raised by any multiplying operator if the result does not lie within the implemented range of the type (for real operands see 4.5.8). In particular it is raised by integer division, \(\text{rem}\), and \(\text{mod}\) if the second operand is zero.

Examples:

```
I : INTEGER := 1;
J : INTEGER := 2;
K : INTEGER := 3;
X : MY\_FLOAT digits 6 := 1.0;
Y : MY\_FLOAT digits 6 := 2.0;
F : FRAC delta 0.0001 := 0.1;
G : FRAC delta 0.0001 := 0.1;
```

4.5.5 Multiplying Operators
### Names and Expressions

#### Expression Value Result Type

<table>
<thead>
<tr>
<th>Expression</th>
<th>Value</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>I*J</td>
<td>2</td>
<td>same as I and J, that is, INTEGER</td>
</tr>
<tr>
<td>K/J</td>
<td>1</td>
<td>same as K and J, that is, INTEGER</td>
</tr>
<tr>
<td>K mod J</td>
<td>1</td>
<td>same as K and J, that is, INTEGER</td>
</tr>
<tr>
<td>X/Y</td>
<td>0.5</td>
<td>same as X and Y, that is, MY_FLOAT</td>
</tr>
<tr>
<td>F/2</td>
<td>0.05</td>
<td>same as F, that is, FRAC</td>
</tr>
<tr>
<td>3*F</td>
<td>0.3</td>
<td>same as F, that is, FRAC</td>
</tr>
<tr>
<td>F+G</td>
<td>0.01</td>
<td>universal_fixed, conversion needed</td>
</tr>
<tr>
<td>FRAC(F+G)</td>
<td>0.01</td>
<td>FRAC, as stated by the conversion</td>
</tr>
<tr>
<td>MY_FLOAT(J)*Y</td>
<td>4.0</td>
<td>MY_FLOAT, the type of both operands after conversion of J</td>
</tr>
</tbody>
</table>

### Notes:

For positive A and B, A/B is the quotient and A rem B is the remainder when A is divided by B. The following relations are satisfied by the rem operator:

\[
A \mod (-B) = A \mod B \\
(-A) \mod B = -(A \mod B)
\]

For any integer K the following identity holds:

\[
A \mod B = (A + K*\text{mod } B) \mod B
\]

The relations between integer division, remainder and modulus are illustrated by the following table:

<table>
<thead>
<tr>
<th>A</th>
<th>B</th>
<th>A/B</th>
<th>A rem B</th>
<th>A mod B</th>
<th>A</th>
<th>B</th>
<th>A/E</th>
<th>A rem B</th>
<th>A mod B</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>5</td>
<td>2</td>
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<td>0</td>
<td>-10</td>
<td>5</td>
<td>-2</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>11</td>
<td>5</td>
<td>2</td>
<td>1</td>
<td>-11</td>
<td>5</td>
<td>-2</td>
<td>-1</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>5</td>
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<td>2</td>
<td>-12</td>
<td>5</td>
<td>-2</td>
<td>-2</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>5</td>
<td>2</td>
<td>3</td>
<td>-13</td>
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<td>-2</td>
<td>-3</td>
<td>2</td>
<td></td>
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<td>-2</td>
<td>-4</td>
<td>1</td>
<td></td>
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<tr>
<td>10</td>
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<td>-2</td>
<td>0</td>
<td>0</td>
<td>-10</td>
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<td>-11</td>
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<td>-1</td>
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</tr>
<tr>
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<td>-14</td>
<td>-5</td>
<td>2</td>
<td>-4</td>
<td>-4</td>
<td></td>
</tr>
</tbody>
</table>

### References:

- accuracy of operations 4.5.8, addition 4.5.1, fixed point type 3.5.9, floating point type 3.5.7, integer type 3.5.4, numeric type 3.5, numeric_error exception 4.5.8 11.1, relation 4.4, type definition 3.3

Multiplying Operators 4.5.5
4.5.6 Exponentiating Operator

The predefined exponentiating operator ** is used for exponentiation.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Operation</th>
<th>Operand Type</th>
<th>Result Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>**</td>
<td>exponentiation</td>
<td>integer</td>
<td>same as L</td>
</tr>
<tr>
<td></td>
<td></td>
<td>non-negative integer</td>
<td>same as L</td>
</tr>
<tr>
<td></td>
<td></td>
<td>floating</td>
<td>same as L</td>
</tr>
</tbody>
</table>

Exponentiation of an operand by a positive exponent is equivalent to repeated multiplication (as indicated by the exponent) of the operand by itself. For a floating operand, the exponent can be negative, in which case the value is the reciprocal of the value with the positive exponent. Exponentiation by a zero exponent delivers the value one.

Exponentiation of an integer raises the exception CONSTRAINT_ERROR for a negative exponent. Exponentiation raises the exception NUMERIC_ERROR if the result does not lie within the implemented range of the type (for real operands see 4.5.8).

References:

constraint_error exception 11.1, floating point type 3.5.7, multiplication 4.5.5, numeric type 3.5, numeric_error exception 11.1

4.5.7 The Function Abs

The predefined function ABS returns the absolute value of its operand.

<table>
<thead>
<tr>
<th>Function</th>
<th>Operation</th>
<th>Operand type</th>
<th>Result type</th>
</tr>
</thead>
<tbody>
<tr>
<td>ABS</td>
<td>absolute value</td>
<td>numeric type</td>
<td>same numeric type</td>
</tr>
</tbody>
</table>

The exception NUMERIC_ERROR is raised if the result does not lie within the implemented range of the type (for a real argument see 4.5.8).

Examples:

ABS(J - K)

References:

accuracy of operations with real operands 4.5.8, numeric_error exception 11.1
4.5.8 Accuracy of Operations with Real Operands

A real type or subtype specifies a set of model numbers. Both the accuracy to be expected from any operation giving a real result, and the result of any relation between real operands are defined in terms of these model numbers.

Given a real value of a type or subtype T, there (normally) exists a smallest interval whose bounds are model numbers and which encloses the given real value. This interval is called the model interval associated with the real value. This model interval is not defined where the absolute value of the given value exceeds the largest model number, that is, T'LARGE; the model interval is then said to overflow.

The model interval associated with a model number is an interval consisting of the number alone. The model interval associated with a real interval (that is, a range of real values) is the smallest interval whose bounds are model numbers and which encloses the values of the real interval.

The bounds on a real value resulting from a predefined operation are defined by the three following steps:

1. A model interval of the appropriate type or subtype is associated with the value of each operand.

2. A new interval is formed by applying the (exact) mathematical operation to operands from the model intervals produced in step (1); for one operand the new interval consists of the range of results produced for all operands in the model interval; for two operands the new interval consists of the range of results produced for all pairs of operands selected from the corresponding model intervals.

3. A model interval of the type of the result of the operation is associated with the interval produced in step (2).

Step (3) gives the required bounds on the result of the machine operation, except when one of the model intervals in step (1) or (3) overflows. The exception NUMERIC_ERROR can only (but need not) be raised in the case of interval overflow.

The result of a relation between two real operands (which need not be of the same subtype) is defined by associating a model interval of the appropriate type or subtype with each operand, and then according to the cases which follow:

(a) The intervals are disjoint (no real value is in both): the result is the (exact) mathematical result.

(b) Each interval is a single model number, and they are equal: the result is the (exact) mathematical result.

(c) The intervals have only a single number in common (this number can only be a model number): the result is the (exact) mathematical result either of comparing the given operands or of comparing the first operand with itself.

(d) Either the intervals have more than one value in common, or one of the intervals (at least) overflows: the result is implementation defined.

The exception NUMERIC_ERROR can only (but need not) be raised in the case of interval overflow.
Notes:

Given \( X/Y \) where \( X = 15.0 \) and \( Y = 3.0 \) which are both model numbers, then the result is exactly 5.0 provided this is a model number of the resulting type. In the general case, division does not yield model numbers and in consequence one cannot assume that \((1.0/3.0)\times 3.0 = 1.0\)

References:

bound 3.5, large attribute 3.5.8, model number 3.5.6, numeric error exception 11.1, predefined operator 4.5, range 3.5, real type 3.5.6, relational operator 4.5.2, subtype declaration 3.3

4.6 Type Conversions

Explicit type conversions are allowed between closely related types as defined below:

\[
\text{type_conversion ::= type_mark (expression)}
\]

The only allowed type conversions correspond to the following three cases:

(a) Numeric types

The expression can be of any numeric type; the value of the expression is converted to the base type of the type mark; this base type must also be a numeric type. For conversions involving real types, the result is within the accuracy of the specified type. Conversion of a real value into an integer type involves rounding.

(b) Array types

The conversion is allowed when for both array types (the operand type, and the base type of the type mark) the index types for each dimension are the same or one is derived from the other, and the component types are the same or one is derived from the other. If the type mark denotes an unconstrained array type, the bounds of the result are the same as those of the operand. If the type mark denotes a constrained array (sub)type, for each component of either array there must be a matching component of the other array; the bounds of the result are then those imposed by the type mark. In either case the value of each component of the result is the same as that of the matching component of the operand (see 4.5.2 for the definition of matching components).

(c) Derived types

The conversion is allowed when the type of the operand is (directly) derived from the type denoted by the type mark, or vice versa. The conversion may result in a change of representation (see 13.6).

The exception CONSTRAINT ERROR is raised by a type conversion if the value of the operand fails to satisfy a constraint imposed by the type mark. For array type conversions this includes any index constraint.
If a conversion is allowed from one type to another, the reverse conversion is also allowed. This reverse conversion is used where an actual parameter of mode in out or out is a type conversion of a (variable) name. For a parameter of mode in out the value of the named object is converted before the call and the converted value is passed as actual parameter; for parameters of modes in out or out, the value of the formal parameter is converted back to the operand type upon return from the subprogram.

Examples of numeric type conversion:

- REAL(2*J) -- value is converted to floating point
- INTEGER(1.6) -- value is 2
- INTEGER(-0.4) -- value is 0

Examples of conversions between array types:

- type SEQUENCE is array (INTEGER range <>) of INTEGER;
- subtype DOZEN is SEQUENCE(1 .. 12);
- LEDGER : array(1 .. 100) of INTEGER;
- SEQUENCE(LEDGER) -- bounds are those of LEDGER
- SEQUENCE(LEDGER(31 .. 42)) -- bounds are 31 and 42
- DOZEN(LEDGER(31 .. 42)) -- bounds are those of DOZEN

Example of conversion between derived types:

- type A_FORM is new B_FORM;
- X : A_FORM;
- Y : B_FORM;
- X := A_FORM(Y);
- Y := B_FORM(X); -- the reverse conversion

References:

actual parameter 6.4, array type definition 3.6, base type 3.3, bounds 3.6.1, component 3.2, constrained array 3.6, constraint 3.3, constraint_error exception 11.1, derived type 3.4, expression 4.4, floating point type 3.5.7, formal parameter 6.2, in out parameter 6.2, index constraint 3.6.1, integer type 3.5.4, name 3.1 4.1, numeric type 3.5, out parameter 6.2, real type 3.5.6, type definition 3.3, type mark 3.3, unconstrained array type 3.6, variable 3.2 4.1

4.7 Qualified Expressions

A qualified expression is used to state explicitly the type, and possibly the subtype, of an expression or aggregate.

qualified_expression ::= 
  type_mark(expression) | type_markaggregate

The expression (or the aggregate) must have the same type as the base type of the type mark. In addition it must satisfy any constraint imposed by the type mark, otherwise the exception CONSTRAINT_ERROR is raised.
Examples:

```ada
    type MASK is (FIX, DEC, EXP, SIGNIF);
    type CODE is (FIX, CLA, DEC, TNZ, SUB);

    PRINT (MASK'(DEC)); -- DEC is of type MASK
    PRINT (CODE'(DEC)); -- DEC is of type CODE

    for I in CODE'(FIX) .. CODE'(DEC) loop ...
        -- qualification needed for either FIX or DEC
    end loop;

    for I in CODE range FIX .. DEC loop ...
        -- qualification unnecessary
    end loop;

    for I in CODE'(FIX) .. DEC loop ...
        -- qualification unnecessary for DEC
    end loop;

    DOZEN'(1 | 3 | 5 | 7 => 2, others => 0)
```

Notes:

The same enumeration literal may appear in several types; it is then said to be overloaded. In these cases and whenever the type of a enumeration literal or aggregate is not known from the context, a qualified expression may be used to state the type explicitly. In particular, an overloaded enumeration literal must be qualified in a subprogram call to an overloaded subprogram that cannot be identified when given as a parameter on the basis of remaining parameter or result types, in a relational expression where both operands are overloaded enumeration literals, or in an array or loop parameter range where both bounds are overloaded enumeration literals. Explicit qualification is also used to specify which one of a set of overloaded parameterless functions is meant, or to constrain a value to a given subtype.

References:

aggregate 4.3, base type 3.3, constraint 3.3, constraint_error exception 11.1, enumeration literal 3.5.1, expression 4.4, literal 4.2, loop parameter 5.5, overloaded literal 3.4 3.5.1, overloaded subprogram 6.6, parameter 6.2, relational expression 4.4, subprogram call 6.4, subtype declaration 3.3, type declaration 3.3, type mark 3.3

4.3 Allocators

The execution of an allocator creates an object and delivers as result an access value that designates the object.

```ada
alphactor ::=  
    new type_mark ([expression])  
    | new type_mark aggregate  
    | new type_mark discriminant_constraint  
    | new type_mark index_constraint  
```

The type mark given in an allocator denotes the type of the object created, the type of the access value returned by the allocator is defined by the context.

4.4 Allocators
Names and Expressions

For the execution of an allocator, any expression, aggregate, discriminant constraint or index constraint is first evaluated; a new object of the type given by the type mark is then created. If the type mark denotes an unconstrained array type or an unconstrained type with discriminants, the allocator must contain either an explicit initial value (an expression or an aggregate), or an index or discriminant constraint; this is the only case in which an index or discriminant constraint is permitted. The created object is constrained by such an explicit constraint, or by the bounds or discriminants of the initial value.

If a default initial value exists for objects of the type or for some of their components, excepting discriminants, then the corresponding default initializations are performed. Finally any explicitly given initial value is assigned to the object, subject to the constraint of the type mark, and an access value designating the created object is returned.

The exception CONSTRAINT_ERROR is raised if either the initial value, or the discriminant or bound values imposed by the constraint, fail to satisfy any constraint imposed by the type mark.

An object created by the execution of an allocator remains allocated for as long as this object is accessible directly or indirectly, that is, as long as it can be designated by some name. When such an object becomes inaccessible, the storage it occupies can be reclaimed (but need not be), depending on the implementation.

When an application needs closer control over storage allocation for objects of an access type, such control may be achieved by one or more of the following means.

(a) The total amount of storage available for the collection of objects of an access type can be set by means of a length specification (see 13.2).

(b) The pragma CONTROLLED informs the implementation that automatic storage reclamation should not be performed except upon leaving the scope of the access type definition. The form of this pragma is as follows

    pragma CONTROLLED (access_type_name);

    The position of a CONTROLLED pragma is governed by the same rules as for a representation specification (see 13.1). This pragma cannot be used for a derived type.

(c) Explicit deallocation of individual access objects may be done by calling a procedure obtained by instantiation of the predefined generic library procedure UNCHECKED_DEALLOCATION (see 13.10.1).

The exception STORAGE_ERROR is raised by an allocator if there is not enough storage.

Examples:

    new CELL(0, null, null)
    new CELL(VALUE => 0, SUCC => nil, PRED => null)
    new MATRIX(1 .. 10 1 .. 20) -- not initialized
    new MATRIX(1 .. 10 => (1 .. 20 => 0)) -- initialized
    new BUFFER(IOu)
    new BUFFER(SIZE => 100, POS => (1, VALUE => (1 .. 100 => 'A')))
4.9 Static Expressions

Static expressions are defined in terms of their possible constituents. Every constituent of a static expression must be one of the following:

(a) a literal or a literal expression
(b) an aggregate whose components and choices are static expressions; if the choice \texttt{others} occurs it must correspond to a static range
(c) a constant initialized by a static expression
(d) a predefined operator, a membership test, the predefined function \texttt{ABS}, or a short circuit control form
(e) an attribute whose value is static; for attributes that are function names, the arguments must also be static expressions
(f) a qualified static expression or the result of a type conversion applied to a static expression, provided that any constraint imposed by the type mark is static
(g) a selected component of a record constant initialized by a static expression
(h) an indexed component of an array constant initialized by a static expression, where the indices are static expressions

Static expressions must be evaluated at compilation time when they appear in a construct in which a static expression is required by the rules of the language. If compile time analysis of such a static expression shows that its evaluation will raise an exception then the static expression must be replaced by code that raises the exception.

References:

aggregate 4.3, attribute 3.3, component 3.2, constant 3.2, constraint 3.3, exception 11, function 6.1 6.4 6.5, indexed component 4.1.1, literal 2.4 3.2 4.2, operator 4.5, qualified expression 4.7, type conversion 4.6
4.10 Literal Expressions

Literal expressions are defined in terms of their possible primary constituents and operators. A primary in a literal expression must be either a numeric literal, a name of a numeric literal, a call of the predefined function ABS, or a literal expression enclosed in parentheses. The value of a literal expression is of the type `universal_integer` if all its primaries are of this type, otherwise it is of the type `universal_real`.

The only operators allowed in a universal integer literal expression are the predefined operators which take operands of integer type.

The only operators allowed in a universal real literal expression are as follows:

- The unary operators +, and -, the function ABS, and the binary operators +, -, *, and /, for universal real operands
- Multiplication of a universal real value by a universal integer value and vice versa.
- Division and exponentation with a universal real first operand and universal integer second operand

The relational operators are also available with universal real operands and deliver a BOOLEAN result.

The evaluation of a literal expression must deliver a result that is at least as accurate as the most accurate numeric type supported by the implementation.

Examples:

```
1 + 1  -- 2
ABS(-10)*3  -- 30
KILO : constant := 1000;
MEGA : constant := KILO*KILO;
LONG : constant := FLOAT_DIGITS*2;
HALF_PI : constant := PI/2;
DEG_TO_RAD : constant := HALF_PI/180;
RAD_TO_DEG : constant := 1.0/DEG_TO_RAD;  -- equivalent to (1.0/((3.14159_26536)/2)/180))
```

References:

- abs function 4.5.7, expression 4.4, integer type 3.5.4, name of numeric literal 3.2, numeric literal 2.4, operator 4.5, primary 4.4, relational operator 4.5.2, universal integer type 2.4 3.2 3.5.4, universal real type 2.4 3.2 3.5.6
5. Statements

The execution of statements causes actions to be performed.

This section describes the general rules applicable to all statements. Some specific statements are discussed in later chapters: Procedure calls are described in Chapter 6 on subprograms. Entry calls, delay, accept, select, and abort statements are described in Chapter 9 on tasks. Raise statements are described in Chapter 11 on exceptions and code statements in Chapter 13. The remaining forms of statements are presented here.

References:


5.1 Simple and Compound Statements - Sequences of Statements

A statement may be simple or compound. A simple statement contains no other statement. A compound statement may contain simple statements and other compound statements.

sequence_of_statements ::= statement {statement}

statement ::= 
  {label} simple_statement | {label} compound_statement

simple_statement ::= null_statement
  | assignment_statement | exit_statement
  | return_statement | goto_statement
  | procedure_call | entry_call
  | delay_statement | abort_statement
  | raise_statement | code_statement

compound_statement ::= 
  if_statement | case_statement
  | loop_statement | block
  | accept_statement | select_statement

label ::= <<identifier>>

null_statement ::= null;

A statement may be labeled with an identifier enclosed by double angle brackets. Labels are implicitly declared at the end of the declarative part of the innermost enclosing subprogram body, package body, or task body. Consequently, within the sequence of statements of a subprogram, package, or task body, any two labels given for the same statement or for different statements must have different identifiers.
The implicit declarations for different labels, loop identifiers and block identifiers are assumed to occur in the same order as the beginnings of the labeled statements, loop statements and blocks themselves.

Execution of a null statement has no other effect than to pass to the next action.

The statements in a sequence of statements are executed in succession unless an exception is raised or an exit, return, or goto statement is executed.

Examples of labeled statements:

```ada
<<AFTER>> null;
<<THERE>> <<LA>> <<DORT>> null;
```

References:
abort statement 9.10, accept statement 9.5, assignment statement 5.2, block 5.6, case statement 5.4, code statement 13.8, delay statement 9.6, exception 11, exit statement 5.7, goto statement 5.9, if statement 5.3, loop statement 5.5, package body 7.1 7.3, procedure 6, raise statement 11.3, return statement 5.8, select statement 9.7, subprogram body 6.3, task body 9.1

5.2 Assignment Statement

An assignment statement replaces the current value of a variable with a new value specified by an expression. The named variable and the right hand side expression must be of the same type.

```
assignment_statement ::= variable_name := expression;
```

For the execution of an assignment statement, the expression of the right hand side, and any expression used in the specification of the variable name are first evaluated. The value of the expression must satisfy any range, index, or discriminant constraint applicable to the variable; then the value of the expression is assigned to the variable. Otherwise the exception CONSTRAINT_ERROR is raised.

Examples:

```ada
VALUE := MAX_VALUE - 1;
SHADE := BLUE;
NEXT_FRAME(F)(M, N) := 2.5;
U := DOT_PRODUCT(V, W);
WRITER := (STATUS => OPEN, UNIT => PRINTER, LINE_COUNT => 60);
NEXT_CAR_all := (72074, null);
```
Examples of constraint checks:

\[
I, J : \text{INTEGER range } 1 \ldots 10; \\
K : \text{INTEGER range } 1 \ldots 20; \\
I := J; \quad \text{-- identical ranges} \\
K := J; \quad \text{-- compatible ranges} \\
J := K; \quad \text{-- will raise the exception CCNSTRAINT_ERROR if } K > 10
\]

Notes:

The language does not define whether evaluation of the expression on the right hand side precedes, follows, or is concurrent with that of any expression used in the specification of the variable name. A program that relies on a specific order is therefore erroneous.

The discriminants of an object designated by an access value cannot be altered (even by a complete object assignment) since such objects, created by allocators, are always constrained (see 4.8).

References:

access value 3.8, allocator 4.8, constraint_error exception 11.1, discriminant 3.7.1, discriminant constraint 3.7.2, expression 4.4, index constraint 3.6, name 4.1, range constraint 3.5, variable 3.2

5.2.1 Array Assignments

For an assignment to an array variable (including assignment to a slice), each component of the array value is assigned to the matching component of the array variable. For each component of either the array value or the array variable, there must be a matching component in the other array. Otherwise, no assignment is performed and the exception CONSTRAINT_ERROR is raised.

Examples:

\[
A : \text{STRING}(1 \ldots 31); \\
B : \text{STRING}(3 \ldots 33); \\
A := B; \quad \text{-- same number of components} \\
A(1 \ldots 9) := \text{"tar sauce"}; \\
A(4 \ldots 12) := A(1 \ldots 9); \quad \text{-- } A(1 \ldots 12) = \text{"tartar sauce"}
\]

Notes:

Array assignment is defined even in the case of overlapping slices, because the expression on the right hand side is evaluated before performing any component assignment. In the above example, an implementation yielding \(A(1 \ldots 12) = \text{"tartartartar"}\) would be incorrect.

References:

array component 3.6, array value 3.6, array variable 3.2 3.6, assignment statement 5.2, constraint_error exception 11.1, expression 4.4, matching components 4.5.2, slice 4.1.2
5.3 If Statements

An if statement selects for execution one or none of a number of sequences of statements, depending on the truth value of one or more corresponding conditions. The expressions specifying conditions must be of the predefined type BOOLEAN.

```
if_statement ::=  
    if condition then  
        sequence_of_statements  
        { elsif condition then  
           sequence_of_statements  
        [ else  
           sequence_of_statements  
        end if;

condition ::= boolean_expression
```

For the execution of an if statement the condition specified after if and any conditions specified after elsif are evaluated in succession (treating a final else as elsif TRUE then), until one evaluates to TRUE; then the corresponding sequence of statements is executed. If none of the conditions evaluates to TRUE, none of the sequences of statements is executed.

Examples:

```
if MONTH = DECEMBER and DAY = 31 then
    MONTH := JANUARY;
    DAY := 1;
    YEAR := YEAR + 1;
end if;

if INDENT then
    CHECK_LEFT_MARGIN;
    LEFT_SHIFT;
elsif OUTDENT then
    RIGHT_SHIFT;
else
    CARRIAGE_RETURN;
    CONTINUE_SCAN;
end if;

if MY_CAR.OWNER_VEHICLE /= MY_CAR then
    FAIL ("INCORRECT RECORD");
end if;
```

References:

boolean type 3.5.3, boolean expression 3.5.3 4.4, sequence of statements 5.1, true 3.5.3, truth value 3.5.3
5.4 Case Statements

A case statement selects for execution one of a number of alternative sequences of statements, depending on the value of an expression. The expression must be of a discrete type.

\[
\text{case statement} ::= \\
\quad \text{case expression is} \\
\quad \quad \{ \text{when choice} \ [| \text{choice}] \Rightarrow \text{sequence of statements} \} \\
\quad \text{end case;}
\]

Each alternative sequence of statements is preceded by a list of choices (see 3.7.3) specifying the values for which the alternative is selected. The type of the expression must be known independently of the context (for example, it cannot be an overloaded literal). Each value of the subtype of the expression, if this subtype is static, otherwise each value of the type of the expression, must be represented once and only once in the set of choices of a case statement. The choice others may only be given as the choice for the last alternative, to cover all values (possibly none) not given in previous choices. The values specified by choices given in a case statement must be determinable statically.

**Examples:**

```plaintext
case SENSOR is 
  when ELEVATION => RECORD_ELEVATION (SENSOR_VALUE);
  when AZIMUTH => RECORD_AZIMUTH (SENSOR_VALUE);
  when DISTANCE => RECORD_DISTANCE (SENSOR_VALUE);
  when others => null;
end case;

case TODAY is 
  when MON => COMPUTE_INITIAL_BALANCE;
  when FRI => COMPUTE_CLOSING_BALANCE;
  when TUE .. THU => GENERATE_REPORT(TODAY);
  when SAT .. SUN => null;
end case;

case BIN_NUMBER(COUNT) is 
  when 1 => UPDATE_BIN(1);
  when 2 => UPDATE_BIN(2);
  when 3 | 4 => 
    EMPTY_BIN(1);
    EMPTY_BIN(2);
  when others => raise ERROR;
end case;
```

**Notes:**

The execution of a case statement will choose one and only one alternative, since the choices are exhaustive and mutually exclusive. It is always possible to use a qualified expression for the expression of the case statement to limit the number of choices that need be given explicitly.

**References:**

discrete type 3.5, expression 4.4, literal 2.5 3.2.5 2, overloading a subprogram 6.6, sequence of statements 5.1, static determination 4.9
5.5 Loop Statements

A loop statement specifies that a sequence of statements in a basic loop is to be executed repeatedly zero or more times.

```
loop_statement ::= [loop_identifier:] [iteration_clause] basic_loop [loop_identifier];

basic_loop ::= loop
    sequence_of_statements
    end loop

iteration_clause ::= for loop_parameter in [reverse] discrete_range
    | while condition

loop_parameter ::= identifier
```

If a loop identifier appears in a loop statement, the identifier must be given both at the beginning and at the end. A loop identifier is implicitly declared at the end of the declarative part of the innermost enclosing block, subprogram body, package body, or task body; where this block has no declarative part, an implicit declarative part (and preceding declare) is assumed.

A loop statement without an iteration clause specifies repeated execution of the basic loop. The basic loop may be left as the result of an exit or return statement; as the result of selecting a terminate alternative of a select statement; or also as the result of a goto statement, or as the result of an exception.

In a loop statement with a while iteration clause, the condition is evaluated and tested before each execution of the basic loop. If the while condition is TRUE the sequence of statements of the basic loop is executed, if FALSE the execution of the loop statement is terminated.

The execution of a loop statement with a for iteration clause starts with the elaboration of this clause, which acts as the declaration of the loop parameter. The identifier of the loop parameter is first introduced and the discrete range is then evaluated: the loop parameter is declared as a variable, local to the loop statement, whose type is that of the elements in the discrete range and whose range constraint is given by the discrete range. If the discrete range is a range whose bounds are integer literals or integer literal expressions, the type is assumed to be the predefined type INTEGER.

If the discrete range of a for loop is null, the basic loop is not executed. Otherwise, the sequence of statements of the basic loop is executed once for each value of the discrete range (subject to the basic loop not being left as described above). Prior to each such iteration, the corresponding value of the discrete range is assigned to the loop parameter. These values are assigned in increasing order unless the reserved word reverse is present, in which case the values are assigned in decreasing order.

Within the basic loop, the loop parameter acts as a constant. Hence the loop parameter may not be changed by an assignment statement, nor may the loop parameter be given as an out or in out parameter of a procedure or entry call.
Statements

Examples:

```
while BID(N).PRICE < CUT_OFF.PRICE loop
    RECORD_BID(BID(N).PRICE);
    N := N + 1;
end loop;

SUMMATION:
while NEXT /= HEAD loop
    SUM := SUM + NEXT.VALUE;
    NEXT := NEXT.SUCC;
end loop;

for J in BUFFER'range loop  -- valid even with empty range
    if BUFFER(J) /= SPACE then
        PUT(BUFFER(J));
    end if;
end loop;
```

Notes:

The discrete range of a for loop is evaluated just once. Loop names can be referred to by exit statements.

References:

assignment statement 5.2, block 5.6, bounds 3.6, condition 5.3, discrete range 3.6, elaboration 3.1 3.9, entry call 9.5, exception 11, exit statement 5.7, false 3.5.3, goto statement 5.9, identifier 2.3, in out parameter 6.2, integer literal 2.4, integer type 3.5.4, name 4.1, null range 3.6.1, out parameter 6.2, package body 7.1 7.3, procedure 6.1, range attribute 3.6.2, return statement 5.8, sequence of statements 5.1, subprogram body 6.3, task body 9.1, terminate alternative 9.7.1, true 3.5.3, variable 4.1

5.6 Blocks

A block introduces a sequence of statements optionally preceded by a governing declarative part.

```
block ::= [block_identifier]
    [declare declarative_part]
    begin
    sequence_of_statements
    [exception [exception_handler]]
    end [block_identifier];
```

If a block identifier is given for a block, it must be given both at the beginning and at the end. A block identifier is implicitly declared at the end of the declarative part of the innermost enclosing block, subprogram body, package body, or task body, where this enclosing block has no declarative part, an implicit declarative part (and preceding declare) is assumed.

The execution of a block results in the elaboration of its declarative part followed by the execution of the sequence of statements. A block may also contain exception handlers to service exceptions occurring during the execution of the sequence of statements (see 11.2).
Example:

```ada
SWAP:
    declare
        TEMP : INTEGER;
    begin
        TEMP := V; V := U; U := TEMP;
    end SWAP;
```

Notes:

Within a block, the block name can be used in selected components denoting local entities such as SWAP. TEMP in the above example (see 4.1.3 (e)).

References:

declarative part 3.9, elaboration 3.1 3.9, exception 11, exception handler 11.2, name 4.1, package body 7.1 7.3, sequence of statements 5.1, subprogram body 6.3, task body 9.1

5.7 Exit Statements

An exit statement may cause the termination of an enclosing loop, depending on the truth value of a condition.

```
exit_statement ::= exit [loop_name] [when condition];
```

The loop exited is the innermost loop unless the exit statement specifies the name of an enclosing loop, in which case the named loop is exited (together with any enclosing loop inner to the named loop). If an exit statement contains a condition, this condition is evaluated and loop termination occurs if and only if its value is TRUE.

An exit statement may only appear within a loop (a named exit statement only within the named loop). An exit statement must not transfer control out of a subprogram body, package body, task body, or accept statement.

Examples:

```ada
for I in 1 .. MAX_NUM_ITEMS loop
    GET_NEWITEM(NEW_ITEM);
    MERGE_ITEM(NEW_ITEM, STORAGE_FILE);
    exit when NEW_ITEM = TERMINAL_ITEM;
end loop;

MAIN_CYCLE:
    loop
        -- initial statements
        exit MAIN_CYCLE when FOUND;
        -- final statements
    end loop MAIN_CYCLE;
```
5.8 Return Statements

A return statement terminates the execution of a function, procedure, or accept statement.

\[
\text{return} \text{statement} ::= \text{return} \{\text{expression}\};
\]

A return statement may only appear within a function body, procedure body, or accept statement. A return statement for a procedure body or for an accept statement must not include an expression.

A return statement for a function must include an expression whose value is the result returned by the function. The expression must be of the type specified in the return clause of the function specification, and must satisfy any constraint imposed by the return clause. Otherwise, the execution of the function is not terminated and the exception CONSTRAINT_ERROR is raised at the place of the return statement.

A return statement must not transfer control out of a package body or task body.

Examples:

\[
\text{return;}
\]

\[
\text{return} \text{KEY\_VALUE(LAST\_INDEX);}
\]

References:

accept statement 9.5. constraint 3.3. constraint\_error exception 11.1. expression 4.4. function 6.1. function body 6.3. function specification 6.1. package body 7.1 7.3. procedure 6.1. procedure body 6.3. sequence of statements 5.1. task body 9.1

5.9 Goto Statements

The execution of a goto statement results in an explicit transfer of control to another statement specified by a label.

\[
\text{goto} \text{statement} ::= \text{goto label\_name;}
\]

A goto statement must not transfer control from outside into a compound statement or exception handler, nor from one of the sequences of statements of an if statement, case statement, or select statement to another. A goto statement must not transfer control from one exception handler to another, nor from an exception handler back to the statements of the corresponding block, subprogram body, package body, or task body.

A goto statement must not transfer control out of a subprogram body, package body, task body, or accept statement.
Example:

```
<<COMPARE>>
   if A(i) < ELEMENT then
     if LEFT(i) /= 0 then
       i := LEFT(i);
       goto COMPARE;
     end if;
     -- some statements
   end if;
```

Notes:

It follows from the scope rules that a goto statement cannot transfer control from outside into the body of a subprogram, package, or task (see 5.1 and 8.1).

References:

accept statement 9.5, block 5.6, case statement 5.4, compound statement 5.1, exception handler 11.2, if statement 5.3, label 5.1, package body 7.1 7.3, scope rules 8, select statement 9.7, sequence of statements 5.1, subprogram body 6.3, task body 9.1
6. Subprograms

A subprogram is an executable program unit that is invoked by a subprogram call. Its definition can be given in two parts: a subprogram declaration defining its calling convention, and a subprogram body defining its execution. There are two forms of subprograms: procedures and functions. A procedure call is a statement; a function call returns a value.

Subprograms are one of the three forms of program units of which programs can be composed. The other forms are packages and tasks.

References:

function 6.1 6.5, function call 6.4, procedure 6.1, procedure call 6.4, subprogram body 6.3, subprogram call 6.4, subprogram declaration 6.1

6.1 Subprogram Declarations

A subprogram declaration declares a procedure or a function.

\[
\text{subprogram_declaration} ::= \text{subprogram_specification;}
\]

| generic_subprogram_declaration |
| generic_subprogram_instantiation |

\[
\text{subprogram_specification} ::= \\
\text{procedure identifier [formal_part]}
\]

| function_designator [formal_part] return subtype_indication |

designator ::= identifier | operator_symbol

operator_symbol ::= character_string

formal_part ::= (parameter_declaration [: parameter_declaration])

parameter_declaration ::= identifier_list : mode subtype_indication [: expression]

mode ::= [in] | out | in out

The specification of a procedure specifies its identifier and its formal parameters (if any). The specification of a function specifies its designator, its formal parameters (if any) and the subtype of the returned value. A designator that is an operator symbol is used for overloading operators of the language. The sequence of characters represented by an operator symbol must be an operator belonging to one of the six classes of overloadable operators defined in section 4.5.
For the elaboration of a subprogram declaration (other than a generic subprogram declaration or a
generic subprogram instantiation), the subprogram identifier (or operator symbol) is first introduced
and can from them on be used as a name of the corresponding subprogram. Elaboration of
parameter declarations and result subtype follow in the order in which they are written.

For the elaboration of a parameter declaration, the identifiers of the list are first introduced; then the
mode and parameter subtype are established; the identifiers then name the corresponding
parameters. If the parameter declaration has the mode in, and only then, it may include an
initialization. In that case, the corresponding expression is next evaluated. Its value is the default
initial value of the parameter; it must satisfy any constraint imposed by the subtype indication,
otherwise the exception CONSTRAINT_ERROR is raised.

Neither the name of a variable, nor a call to a user-defined operator, function, or allocator, may
appear in any expression occurring in a formal part. A parameter declaration, or a constraint on the
result of a function, may not mention the name of a parameter declared in another parameter
declaration of the same formal part.

A generic subprogram declaration defines a template for several subprograms obtained by generic
subprogram instantiation (see 12.1 and 12.3).

Examples of subprogram declarations:

```
procedure TRAVERSE_TREE;
procedure RIGHT_INDENT(MARGIN : out LINE_POSITION);
procedure INCREMENT(X : in out INTEGER);

function RANDOM return REAL range -1.0 .. 1.0;
function COMMON_PRIME (M,N : INTEGER) return INTEGER;
function DOT_PRODUCT (X,Y : VECTOR) return REAL;
function "*" (X,Y : MATRIX) return MATRIX;
```

Examples of in parameters with default values:

```
procedure PRINT_HEADER( PAGES : in INTEGER;
              HEADER : in LINE := BLANK_LINE;
              CENTER : in BOOLEAN := TRUE);
```

Note:

All subprograms can be called recursively and are reentrant.

References:

constraint 3.3, constraint_error exception 11.1, expression 4.4, formal parameter 6.2, function 6.5, function
call 6.4, generic part 12.1, operator 4.5, overloading an operator 6.7, procedure call 1.4, subtype declaration
3.1, variable name 3.2 4.1

6. Subprogram Declarations
6.2 Formal Parameters

The formal parameters of a subprogram are considered local to the subprogram. A parameter has one of three modes:

- **in** The parameter acts as a local constant whose value is provided by the corresponding actual parameter.

- **out** The parameter acts as a local variable whose value is assigned to the corresponding actual parameter as a result of the execution of the subprogram.

- **in out** The parameter acts as a local variable and permits access and assignment to the corresponding actual parameter.

If no mode is explicitly given, the mode in is assumed. If a parameter of mode in is an array or a record, none of its components may be changed by the subprogram. For parameters of a scalar or access type, at the start of each call, the value of each actual parameter which corresponds to a formal parameter of mode in or in out is copied into the corresponding formal parameter; upon return from the subprogram, the value of each formal parameter of mode in or out or out is copied back into the corresponding actual parameter.

For parameters of an array, record, or private type, the values may be copied as in the above case; alternatively, the formal parameter may provide access to the corresponding actual throughout the execution of the subprogram. The language does not define which of these two mechanisms is used for parameter passing. A program that relies on one particular mechanism is therefore erroneous.

Within the body of a subprogram, a formal parameter is subject to any constraint given in its parameter declaration. For a formal parameter of an unconstrained array type, the bounds are obtained from the actual parameter. For a formal parameter whose declaration specifies an unconstrained (private or record) type with discriminants, the discriminants of the formal parameter are initialized with the values of the corresponding discriminants of the actual parameter; if the actual parameter is constrained by these discriminant values then so also is the formal.

Notes:

For parameters of array, record, or private types, the parameter passing rules have these consequences:

- If the execution of a subprogram is abnormally terminated by an exception, the final value of an actual parameter of such a type can be either its value before the call or a value assigned to the formal parameter during the execution of the subprogram.

- If no actual parameter of such a type is accessible by more than one path, then the effect of a (normally terminating) subprogram call is the same whether or not the implementation uses copying for parameter passing. If however there are multiple access paths to such a parameter (for example, if a global variable or another formal parameter, refers to the same actual parameter), then after an assignment to the actual other than via the formal, the value of the formal is undefined. A program using such an undefined value is erroneous.
Subprogram Bodies

A subprogram body specifies the execution of a subprogram.

\[
\text{subprogram_body ::= } \text{subprogram_specification is}
\]
\[
\text{declarative_part}
\]
\[
\text{begin}
\]
\[
\text{sequence_of_statements}
\]
\[
\text{[exception}
\]
\[
\text{[exception_handler]]}
\]
\[
\text{end [designator]};
\]

If both a subprogram declaration and a subprogram body are given, the subprogram specification provided in the body must be the same as that given in the corresponding subprogram declaration: the parameter names, the subtype indications, and the expressions specifying any default values must be the same and in the same order. The only variation allowed is that names can be written differently, provided that they denote the same entity.

A subprogram declaration must be given if the subprogram is declared in the visible part of a package, or if it is called by other subprogram, package, or task bodies that appear before its own body. Otherwise, the declaration can be omitted and the specification appearing in the subprogram body acts as the declaration. The elaboration of a subprogram body consists of the elaboration of its specification if that has not already been done; the effect is to establish the subprogram body as defining the execution of the corresponding subprogram.

The execution of a subprogram body is invoked by a subprogram call (see 6.4). For this execution, (after establishing the association between formal parameters and actual parameters) the declarative part of the body is elaborated, and the sequence of statements of the body is then executed. Upon completion of the body, return is made to the caller (and any necessary copying back of formal to actual parameters occurs (see 6.2)). A subprogram body may contain exception handlers to service any exceptions that occur during the execution of its sequence of statements (see 11).

The optional designator at the end of a subprogram body must repeat the designator of the subprogram specification.

A subprogram body may be expanded in line at each call if this is requested by the pragma INLINE:

\[
\text{pragma INLINE(subprogram_name, sub program name, ...)}
\]

This pragma (if given) must appear in the same declarative part as the named subprograms (a single subprogram name may stand for several overloaded subprograms); for subprograms declared in a package specification the pragma must also be in this package specification. The meaning of a subprogram is not changed by the pragma INLINE.
Example of subprogram body:

```pascal
procedure PUSH(E : in ELEMENT_TYPE; S : in out STACK) is
begin
  if S.INDEX = S.SIZE then
    raise STACK_OVERFLOW;
  else
    S.INDEX := S.INDEX + 1;
    S.SPACE(S.INDEX) := E;
  end if;
end PUSH;
```

Note:

As stated above, where a subprogram specification is repeated, the second occurrence is never elaborated. Therefore there is no question of expressions in the second occurrence delivering a different value.

References:


6.4 Subprogram Calls

A subprogram call is either a procedure call or a function call. It invokes the execution of the corresponding subprogram body. The call specifies the association of any actual parameters with formal parameters of the subprogram. An actual parameter is either a variable or the value of an expression.

```pascal
procedure_call ::= procedure_name [actual_parameter_part];

function_call ::= function_name actual_parameter_part | function_name ()

actual_parameter_part ::= (parameter_association {, parameter_association})

parameter_association ::= [formal_parameter =>] actual_parameter

formal_parameter ::= identifier

actual_parameter ::= expression
```
Actual parameters may be passed in positional order (positional parameters) or by explicitly naming the corresponding formal parameters (named parameters). For positional parameters, the actual parameter corresponds to the formal parameter with the same position in the formal parameter list. For named parameters, the corresponding formal parameter is explicitly given in the call. Named parameters may be given in any order.

Positional parameters and named parameters may be used in the same call provided that positional parameters occur first at their normal position, that is, once a named parameter is used, the rest of the call must use only named parameters.

The call of a parameterless function is written as the function name followed by empty parentheses. This is also done for a function call in which default initial values are used for all parameters. The call of a parameterless procedure is written as the procedure name followed by a semicolon.

Examples of procedure calls:

```
RIGHTSHIFT;
TABLE_MANAGER.INSERT(E);
SEARCH_STRING(STRING, CURRENT_POSITION, NEW_POSITION);
PRINT_HEADER(PAGES => 128, HEADER => TITLE, CENTER => TRUE);
SWITCH(FROM => X, TO => NEXT);
REORDER_KEYS(NUMBER_OF_ITEMS, KEY_ARRAY => RESULT_TABLE);
```

Examples of function calls:

```
DOT_PRODUCT(U, V)
CLOCK()
```

References:
default parameter value 6.1, expression 4.4, function 6.1 6.5, identifier 2.3, name 4.1, procedure 6.1, subprogram body 8.3, variable 3.2 4.1

6.4.1 Actual Parameter Associations

An expression used as an actual parameter of mode in out or out must be a variable name or a type conversion of a variable name (see 4.6). An expression used as an actual parameter of mode in is evaluated before the call. If a variable given as an actual parameter of mode in out or out is a selected component or an indexed component, its identity is established before the call.

For a parameter of a scalar type, if the mode is in or in out, any range constraint on the formal parameter must be satisfied by the value of the actual parameter before each call. If the mode is in out or out, any range constraint on the actual parameter must be satisfied by the value of the formal parameter upon return from the subprogram.

For a parameter of an access type the only possible constraints are index and discriminant constraints applying to the objects designated by the access values. These constraints must be satisfied (that is, are checked) before the call (for the modes in and in out) and upon return (for the modes in out and out).
For a parameter of an array type, or of a record or private type with discriminants, any constraint specified for the formal parameter must be satisfied by the corresponding actual parameter before the call for all parameter modes.

The exception CONSTRAINT_ERROR is raised at the place of the subprogram call if any of the above-mentioned constraints is not satisfied.

Notes:

For array types, and for record and private types with discriminants, the language rules guarantee that if the actual parameter satisfies the constraint of the formal parameter before the call, then the formal parameter satisfies the constraint of the actual parameter upon return. Hence no constraint check is needed upon return.

The language does not define in which order different parameter associations are evaluated. A program relying on some specific order is therefore erroneous.

References:

access type 3.8, access value 3.8, array type definition 3.6, constraint_error exception 11.1, discriminant 3.7.1, discriminant constraint 3.7.2, expression 4.4, indexed component 4.1.1, mode 6.2, object 3.2, private type definition 7.4, range constraint 3.5, record type 3.7, scalar type 3.5, selected component 4.1.3, variable name 3.2

6.4.2 Default Actual Parameters

If a subprogram declaration specifies a default value for an in parameter, then the corresponding parameter may be omitted from a call. In such a case the rest of the call, following any initial positional parameters, must use only named parameters.

Example of procedure with default values:

```
procedure ACTIVATE(PROCESS in PROCESS_NAME;
                   AFTER in PROCESS_NAME := NO_PROCESS;
                   WAIT in DURATION := 0.0;
                   PRIOR in BOOLEAN := FALSE);
```

Examples of its call:

```
ACTIVATE(X);
ACTIVATE(X, AFTER => Y);
ACTIVATE(X, WAIT => 60.0, PRIOR => TRUE);
ACTIVATE(X, Y, 10.0, FALSE);
```

Note:

The default value for an in parameter is evaluated when the subprogram specification is elaborated and is thus not reevaluated at each call. Hence the same default value is used for all calls.
References:

default parameter value 6.1, named parameter 6.4, subprogram specification 6.1,

6.5 Function Subprograms

A function is a subprogram that returns a value. The specification of a function starts with the reserved word function. A function may only have parameters of the mode in. The sequence of statements in the function body (excluding statements in nested bodies) must include one or more return statements specifying the returned value. If the body of a function is left by reaching the end, the value returned by the function call is undefined. A program that relies upon such an undefined value is erroneous.

Example:

```ada
function DOT_PRODUCT(X, Y : VECTOR) return REAL is
    SUM : REAL := 0.0;
    begin
        CHECK(X'FIRST = Y'FIRST and X'LAST = Y'LAST);
        for J in X'RANGE loop
            SUM := SUM + X(J)*Y(J);
        end loop;
        return SUM;
    end DOT_PRODUCT;
```

References:

exception 11, function body 6.3, function call 6.4, function specification 6.1, mode 6.2, parameter 6.2, return statement 5.8

6.3 Overloading of Subprograms

The same subprogram identifier can be used in several otherwise different subprogram specifications: it is then said to be overloaded. The declaration of an overloaded subprogram identifier does not hide another subprogram declaration made in an outer declarative part unless, in the two declarations, the order, the names, and the types of the parameters are the same, the same parameters have default values, and (for functions) the result type is the same. When this condition for hiding is satisfied, the two subprogram specifications are said to be equivalent. On the other hand the default values themselves, the constraints, and the parameter modes are not taken into account to determine if one subprogram hides another.

Overloaded subprogram declarations may occur in the same declarative part, but they must then differ by more than just the parameter names.

A call to an overloaded subprogram is ambiguous (and therefore illegal) if the types and the order of the actual parameters, the names of the formal parameters (if named associations are used), and the result type (for functions) are not sufficient to identify exactly one (overloaded) subprogram specification.
Examples of overloaded subprograms:

- procedure PUT(X : INTEGER);
- procedure PUT(X : STRING);
- procedure SET(TINT : COLOR);
- procedure SET(SIGNAL : LIGHT);

Example of calls:

PUT(28);
PUT("no possible ambiguity here");

SET(TINT => RED);
SET(SIGNAL => RED);
SET(COLOR'(RED));

-- SET(RED) would be ambiguous since RED may
denote a value of type either COLOR or LIGHT

Notes:

Ambiguities may (but need not) arise when actual parameters of the call of an overloaded subprogram
are themselves overloaded function calls, literals or aggregates. Ambiguities may also arise when
several overloaded subprograms belonging to different packages are applicable. These ambiguities
can usually be resolved in several ways: qualified expressions can be used for some or all actual
parameters and for any result; the name of the subprogram can be expressed more explicitly as a
selected component (prefixing the subprogram identifier by the package name); finally the
subprogram can be renamed.

References:

actual parameter 6.4, constraints on parameters 6.4.1, declarative part 3.9, default parameter value 6.1,
function 6.5, hide 8.3, named parameter association 6.4, overloaded aggregate 4.3, overloaded literal 3.5.1
4.7, package 7, parameter type 6.1, qualified expression 4.7, renaming declaration 8.5, result type 6.1,
selected component 4.1.3, subprogram call 6.4, subprogram declaration 6.1, subprogram identifier 6.1,
subprogram specification 6.1

6.7 Overloading of Operators

A function declaration whose designator is an operator symbol is used to define an additional
overloading for an operator. The sequence of characters of the operator symbol must be either a
logical, a relational, an adding, a unary, a multiplying, or an exponentiating operator (see 4.5). Neither
membership operators nor the short circuit control forms are allowed.

The declaration of an overloaded operator hides the declaration of another operator, with the same
designator, made in an outer declarative part, if for both declarations the types of the parameters are
the same, and the result type is the same; the names of the parameters are not taken into account.
The declaration of a unary operator must be a function declaration with a single parameter. The declaration of any other operator must be a function declaration with two parameters; for each use of this operator, the first parameter takes the left operand as actual parameter, the second parameter takes the right operand. Default values for parameters are not allowed in operator declarations. The operators "+" and "-" may be overloaded both as unary and as binary operators.

The equality operator "=" can only be overloaded for two parameters of the same limited private type or of a composite type that has one or more components (or components of components, and so on) of a limited private type. An overloading of equality must deliver a result of the predefined type BOOLEAN; it also implicitly overloads the inequality operator "/=" so that this still gives the complementary result to the equality operator. Explicit overloading of the inequality operator is not allowed.

Examples:

```ada
function "*" (X, Y : MATRIX) return MATRIX;
function "*" (X, Y : VECTOR) return VECTOR;
```

Note:

Overloading of relational operators does not affect basic comparisons in the language such as testing for membership in a range or the choices in a case statement.

References:

actual parameter 6.4, adding operator 4.5.3, boolean type 3.5.3, case statement 5.4, composite type 3.3, declarative part 3.9, default parameter value 6.1, designator 6.1, equality operator 4.5.2, function declaration 6.1, hide 8.3, limited private type 7.4.2, mode 6.2, operator symbol 6.1, parameter type 6.1, range 3.5, relational operator 4.5.2, result type 6.1, unary operator 4.5.4

6.7 Overloading of Operators
7. Packages

Packages allow the specification of groups of logically related entities. In their simplest form, packages can represent pools of common data and type declarations. More generally, packages can be used to describe groups of related entities such as types, objects, and subprograms, whose inner workings are concealed and protected from their users.

Packages are one of the three forms of program units, of which programs can be composed. The other forms are subprograms and tasks.

References:

object 3.2, subprogram 6, task 9, type declaration 3.3

7.1 Package Structure

A package is generally provided in two parts: a package specification and a package body. The simplest form of package, that representing a pool of data and types, does not require a package body.

```
package_declaration ::=
   package_specification;
   | generic_package_declaration
   | generic_package_instantiation

package_specification ::= package identifier is
   (declarative_item)
   [private
    (declarative_item)
    (representation_specification)]
   end [identifier]

package_body ::= package body identifier is
   declarative_part
   [begin
    sequence_of_statements
    [exception
     (exception_handler)]]
   end [identifier];
```

A package specification and the corresponding package body have the same identifier; only this identifier may appear as the optional identifier at the end of the package specification or body (or both).
With respect to visibility and redeclaration rules (see 8.1), the declarative items and representation specifications in a package specification and the declarative part of the corresponding package body (if any) are considered as forming a single declarative part. A package declaration may be separately compiled (see 10.1) or it may appear within a declarative part. In the latter case the corresponding body (if any) must appear later in the same declarative part.

Package specifications and package bodies may contain further package declarations. The body of any program unit (that is, any subprogram, package, or task) declared in a package specification must appear in the corresponding package body (unless the unit declared is obtained by generic instantiation or is a subprogram for which an INTERFACE pragma is given, see 13.9).

A generic package declaration defines a template for several packages obtained by generic package instantiation (see 12.1 and 12.3).

References:
declarative item 3.9, declarative part 3.9, generic instantiation 12.3, generic part 12.1, identifier 2.3, program unit 6 7 9, redeclaration rules 8.2, representation specification 13.1, subprogram 6, task 9, visibility 8.1

7.2 Package Specifications and Declarations

The first list of declarative items of a package specification is called the visible part of the package. The entities declared in the visible part can be referred to from other program units by means of selected components: they can be made directly visible to other program units by means of use clauses (see 4.1.3 and 8.4). The visible part contains all the information that another program unit is able to know about the package. The optional lists of declarative items and representation specifications after the reserved word private form the private part of the package.

For the elaboration of a package declaration (other than a generic package declaration or a generic package instantiation), the package identifier is first introduced and can from then on be used as a name of the corresponding package; elaboration of the visible part, and of any declarative items and representation specifications appearing after the reserved word private follow in this order.

A package consisting of only a package specification (that is, without a package body) can be used to represent a group of common constants or variables, or a common pool of data and types.

Example of a group of common variables.

```ada
package PLOTTING_DATA is
   PEN_UP : BOOLEAN;
   CONVERSION_FACTOR,
   X_OFFSET, Y_OFFSET,
   X_MIN, X_MAX,
   Y_MIN, Y_MAX : REAL;
   X_VALUE, Y_VALUE : array (1 .. 500) of REAL;
end PLOTTING_DATA;
```

7.2 Package Specifications and Declarations
Example of a common pool of data and types:

```pascal
package WORK_DATA is
    type DAY is (MON, TUE, WED, THU, FRI, SAT, SUN);
    type HOURS_SPENT is delta 0.01 range 0.0 .. 24.0;
    type TIME_TABLE is array (DAY) of HOURS_SPENT;
    WORK_HOURS : TIME_TABLE;
    NORMAL_HOURS : constant TIME_TABLE :=
        (MON .. THU => 8.25, FRI => 7.0, SAT | SUN => 0.0);

end WORK_DATA;
```

References:

constant 3.2 declarative item 3.9, elaboration 3.1, generic package instantiation 12.3, generic part 12.1, package specification 7.1, program unit 6 7 9, representation specification 13.1, selected component 4.1.3, separate compilation 10.1, type declaration 3.3, use clause 8.4, variable 3.2

7.3 Package Bodies

The specification of a package, in particular the visible part, may contain the specifications of subprograms, tasks and other packages. In such cases, the bodies of the specified program units must appear within the declarative part of the package body (unless a pragma INTERFACE is given, see 13.9). This declarative part may also include local declarations and local program units needed to implement the visible items.

In contrast to the entities declared in the visible part, the entities declared in the package body are not accessible outside the package. As a consequence, a package with a package body can be used for the construction of a group of related subprograms (a package in the usual sense), where the logical operations accessible to the users are clearly isolated from the internal entities.

For the elaboration of a package body, its declarative part is elaborated first, and its sequence of statements (if any) is then executed. Any entity declared in this declarative part remains in existence for as long as the package itself.

The optional exception handlers at the end of a package body handle exceptions raised during the execution of its sequence of statements.

Example of a package:

```pascal
package RATIONAL_NUMBERS is
    type RATIONAL is
        record
            NUMERATOR : INTEGER;
            DENOMINATOR : INTEGER range 1 .. INTEGER'LAST;
        end record;
    function EQUAL(X,Y : RATIONAL) return BOOLEAN;
    function "+" (X,Y : RATIONAL) return RATIONAL;
    function "+" (X,Y : RATIONAL) return RATIONAL;
end;
```

Package Bodies 7.3
package body RATIONAL_NUMBERS is

procedure SAME_DENOMINATOR (X, Y : in out RATIONAL) is
begin
  -- reduces X and Y to the same denominator
end;

function EQUAL(X, Y : RATIONAL) return BOOLEAN is
  U, V : RATIONAL;
begin
  U := X;
  V := Y;
  SAME_DENOMINATOR (U, V);
  return U.NUMERATOR = V.NUMERATOR;
end EQUAL;

function "+" (X, Y : RATIONAL) return RATIONAL is ...
end "+";
function "+" (X, Y : RATIONAL) return RATIONAL is ...
end "+";

end RATIONAL_NUMBERS;

Notes:

A variable declared in a package specification or body retains its value between calls to subprograms declared in the visible part. Such a variable is said to be an own variable of the package.

If a package body contains the declarations of subprograms specified in the visible part then it is only after the elaboration of the package body that these subprograms can be called from outside the package (see 3.9 and 10.5).

References:

declarative part 3.9, elaboration 3.1, exception handler 11.2, exception 11, package specification 7.1, sequence of statements 5.1, subprogram 6, task 9, variable 3.2, visible part 7.2

7.4 Private Type Definitions

The structural details of some declared type may be irrelevant to the use of its logical properties outside a package, and one may wish to protect them from external influence. This can be accomplished by declaring such a type with a private type definition in the visible part of a package specification.

    private_type_definition ::= [limited] private

A private type definition may only occur in a type declaration given in the visible part of a package or in a generic part (see 12.1.2). The corresponding types are called (limited) private types. The only effect of the elaboration of a private type declaration is to introduce the name of a (limited) private type and to elaborate its discriminant part, if any.

If a package specification includes a private type declaration it must also include a full declaration of the type in the private part of the package (that is, in the list of declarative items following the reserved word private).

7.1 Private Type Definitions
A constant of a private type can be declared in the visible part as a *deferred* constant, that is, as a constant whose initial value is not specified in its declaration. The initial value must be specified in the private part by redeclaring the constant in full.

**References:**

constant 3.2, declarative item 3.9, discriminant part 3.3 3.7.1, elaboration 3.1, generic part 12.1, limited private type 7.4.2, name 4.1, package specification 7.1, private part 7.2, type declaration 3.3, visible part 7.2

**7.4.1 Private Types**

For a private type not designated as limited, the only information available to other external program units is that given in the visible part of the defining package. Thus the name of the type is available. In addition, any subprogram specified within the visible part with a parameter or result of the private type defines an available operation for objects of the private type. Finally, assignment and the predefined comparison for equality or inequality are available.

These are the only externally available operations on objects of a private type. External units can declare objects of the private type and apply available operations to the objects; in contrast, they cannot directly access the structural details of objects of private types.

For each private type declaration given in the visible part of a package specification, a corresponding type declaration (with the same name) must be given in full in the private part, that is, with a type definition other than a private type definition. Assignment and equality must be available for this type.

If the private type declaration has **discriminants**, the full declaration must have the same discriminants: the discriminant names, the subtype indications, and any default values must be the same and in the same order. The only variation allowed is that names may be written differently, provided that they denote the same entity. The elaboration of the full type declaration consists only of the elaboration of the corresponding type definition (since the type name has already been introduced and any discriminant part has already been elaborated). The full type declaration cannot include a discriminant part if the private type declaration does not have one; it cannot declare an unconstrained array type.

Within the private part and the body of a package, the operations available on objects of the private type are those defined in both the visible part and the private part. If the full declaration is in terms of a derived type definition, an inherited operation may be redefined (and thereby hidden) by an operation declared in the visible part.

**Example:**

```pascal
package KEY_MANAGER is
    type KEY is private;
    NULL_KEY : constant KEY;
    procedure GET_KEY(K : out KEY);
    function "<" (X, Y : KEY) return BOOLEAN;
private
    type KEY is new INTEGER range 0 .. INTEGER'LAST;
    NULL_KEY : constant KEY := 0;
end;
```

Private Types 7.4.1
-- the only externally available operations of the private type KEY are assignment,
-- equality, inequality, "<", and the procedure GET_KEY returning a KEY value

package body KEY_MANAGER is
LAST_KEY : KEY := 0;
procedure GET_KEY(K : out KEY) is
begin
LAST_KEY := LAST_KEY + 1;
K := LAST_KEY;
end GET_KEY;

function "<" (X, Y : KEY) return BOOLEAN is
begin
return INTEGER(X) < INTEGER(Y);
end "<";
-- this definition of "<" hides the definition inherited from INTEGER; hence X<Y would
-- be a recursive call and conversion is necessary to invoke the "<" of INTEGER
end KEY_MANAGER;

Note:
Outside its defining package a private type is just a private type. The fact that it may be implemented
as a particular type class (for example, as an array type) is irrelevant. Consequently any language rule
which applies specifically to that class does not apply to that private type outside its defining package.

References:
array type definition 3.6, assignment statement 5.2, derived type definition 3.4, discriminant 3.7.1, elaboration
3.1, equality 4.5.2, inherited 3.4, limited private type 7.4.2, name 4.1, parameter 6.2, private part 7.2,
subprogram 6, subtype indicator 3.4, type class 3.3, type declaration 3.3, unconstrained array type 3.6,
visible part 7.2

7.4.2 Limited Private Types

Outside the package defining a limited private type, assignment and the comparisons for equality or
inequality are not available for objects of the type. Moreover if a composite type has components of a
limited private type, assignment, equality and inequality are not available for objects of the composite
type, outside the package defining the limited private type. The only externally available operations
on objects of a limited private type are those defined by the subprograms declared in the visible part
of the defining package.

The following are consequences of the non-availability of assignment:

- A declaration of a variable of a limited private type cannot include an initialization.
- Parameters of a limited private type may not have default values.
- No constant of a limited private type can be declared outside the defining package.
- An allocator for an access type designating objects of a limited private type is not allowed to
specify an initial value for the allocated object.

7.4.2 Limited Private Types
Outside the defining package, subprograms having parameters of any mode can be defined for objects of a limited private type, provided that the above rules are satisfied.

The type definition given in the full declaration of a limited private type need not (but may) define a type for which assignment and equality are available; the full type declaration may be the declaration of a task type.

Example:

In the example below, an external subprogram making use of I_O_PACKAGE may obtain a file name by calling OPEN and later use it in calls to READ and WRITE. Thus, outside the package, a file name obtained from OPEN acts as a kind of password; its internal properties (such as containing a numeric value) are not known and no other operations (such as addition or comparison of internal names) can be performed on a file name.

```pascal
package I_O_PACKAGE is
    type FILE_NAME is limited private;
    procedure OPEN (F : in out FILE_NAME);
    procedure CLOSE (F : in out FILE_NAME);
    procedure READ (F : in FILE_NAME; ITEM : out INTEGER);
    procedure WRITE (F : in FILE_NAME; ITEM : in INTEGER);
private
    type FILE_NAME is
        record
            INTERNAL_NAME : INTEGER := 0;
        end record;
end I_O_PACKAGE;

package body I_O_PACKAGE is
    LIMIT : constant := 200;
    type FILE_DESCRIPTOR is record ...
    end record;
    DIRECTORY : array (1 .. LIMIT) of FILE_DESCRIPTOR;
    ...
    procedure OPEN (F : in out FILE_NAME) is ...
    end;
    procedure CLOSE (F : in out FILE_NAME) is ...
    end;
    procedure READ (F : in FILE_NAME; ITEM : out INTEGER) is ...
    end;
    procedure WRITE (F : in FILE_NAME; ITEM : in INTEGER) is ...
    end;

begin...
end I_O_PACKAGE;
```

This example is characteristic of any case where complete control over the operations of a type is desired. Such packages serve a dual purpose. They prevent a user from making use of the internal structure of the type. They also implement the notion of an encapsulated data type where the only operations on the type are those given in the package specification.

References:

access type 3.8, allocator 4.8, assignment statement 5.2, composite type 3.6 3.7, constant 3.2, equality 4.5.2, initialization 3.2, inequality 4.5.2, mode 6.2, name 4.1, package specification 7.1, subprogram 6, task type 9, type definition 3.3, variable 3.2, visible part 7.2
7.5 Example of a Table Management Package

The following example illustrates the use of packages in providing high level procedures with a simple interface to the user.

The problem is to define a table management package for inserting and retrieving items. The items are inserted into the table as they are supplied. Each inserted item has an order number. The items are retrieved according to their order number, where the item with the lowest order number is retrieved first.

From the user's point of view, the package is quite simple. There is a type called ITEM designating table items, a procedure INSERT for inserting items, and a procedure RETRIEVE for obtaining the item with the lowest order number. There is a special item NULL_ITEM that is returned when the table is empty, and an exception TABLE_FULL that may be raised by INSERT.

A sketch of such a package is given below. Only the specification of the package is exposed to the user.

```ada
package TABLF_MANAGER is

    type ITEM is
        record
            ORDER_NUM : INTEGER;
            ITEM_CODE : INTEGER;
            QUANTITY : INTEGER;
            ITEM_TYPE : CHARACTER;
        end record;

    NULL_ITEM : constant ITEM :=
        (ORDER_NUM => 0, ITEM_CODE => 0, QUANTITY => 0, ITEM_TYPE => ' ');

    procedure INSERT (NEW_ITEM in ITEM);
    procedure RETRIEVE (FIRST_ITEM : out ITEM);

    TABLE_FULL : exception; -- may be raised by INSERT

end;
```

The details of implementing such packages can be quite complex; in this case they involve a two way linked table of internal items. A local housekeeping procedure EXCHANGE is used to move an internal item between the busy and the free lists. The initial table linkages are established by the initialization part. The package body need not be shown to the users of the package.
package body TABLE_MANAGER is
  SIZE : constant := 2000;
  subtype INDEX is INTEGER range 0 .. SIZE;

  type INTERNAL_ITEM is
    record
      CONTENT : ITEM;
      SUCC   : INDEX;
      PRED   : INDEX;
    end record;

  TABLE : array (INDEX) of INTERNAL_ITEM;
  FIRST_BUSY_ITEM : INDEX := 0;
  FIRST_FREE_ITEM : INDEX := 1;

  function FREE_LIST_EMPTY return BOOLEAN is ... end;
  function BUSY_LIST_EMPTY return BOOLEAN is ... end;
  procedure EXCHANGE (FROM in INDEX; TO in INDEX) is ... end;

  procedure INSERT (NEW_ITEM : in ITEM) is
  begin
    if FREE_LIST_EMPTY then
      raise TABLE_FULL;
    end if;
    -- remaining code for INSERT
  end INSERT;

  procedure RETRIEVE (FIRST_ITEM : out ITEM) is ... end;

begin
  -- initialization of the table linkages
end TABLE_MANAGER;

References:

exception 11, procedure 6, package body 7.3 visible part 7.2.

7.3 Example of a Text Handling Package

This example illustrates a simple text-handling package. The user only has access to the visible part; the implementation is hidden from him in the private part and the package body (not shown).

From the user’s point of view, a TEXT is a variable length string. Each text object has a maximum length, which must be given when the object is declared, and a current value, which is a string of some length between zero and the maximum. The maximum possible length of a text object is an implementation-defined constant.
The package defines first the necessary types, then functions that return some characteristics of objects of the type, then the conversion functions between texts and the predefined CHARACTER and STRING types, and finally some of the standard operations on varying strings. Most operations are overloaded on strings and characters as well as on texts, in order to minimize the number of explicit conversions the user has to write.

```ada
package TEXT_HANDLER is
  MAXIMUM : constant INTEGER := SOME_VALUE; -- implementation defined
  subtype INDEX is INTEGER range 0 .. MAXIMUM;
  type TEXT(MAXIMUM_LENGTH : INDEX) is limited private;

  function LENGTH(T : TEXT) return INDEX;
  function VALUE (T : TEXT) return STRING;
  function EMPTY (T : TEXT) return BOOLEAN;

  function TO_TEXT (S : STRING; MAX : INDEX) return TEXT; -- maximum length MAX
  function TO_TEXT (C : CHARACTER; MAX : INDEX) return TEXT;
  function TO_TEXT (S : STRING) return TEXT; -- maximum length S'LENGTH
  function TO_TEXT (C : CHARACTER) return TEXT;

  function "&" (LEFT TEXT, RIGHT TEXT) return TEXT;
  function "&" (LEFT TEXT, RIGHT STRING) return TEXT;
  function "&" (LEFT STRING, RIGHT TEXT) return TEXT;
  function "&" (LEFT TEXT, RIGHT CHARACTER) return TEXT;

  procedure SET(OBJECT in out TEXT, VALUE in TEXT);
  procedure SET(OBJECT in out TEXT, VALUE in STRING);
  procedure SET(OBJECT in out TEXT, VALUE in CHARACTER);

  procedure APPEND(TAIL in TEXT, TO in out TEXT);
  procedure APPEND(TAIL in STRING, TO in out TEXT);
  procedure APPEND(TAIL in CHARACTER, TO in out TEXT);

  procedure AMEND(OBJECT in out TEXT, BY in TEXT; POSITION in INDEX);
  procedure AMEND(OBJECT in out TEXT, BY in STRING; POSITION in INDEX);
  procedure AMEND(OBJECT in out TEXT, BY in CHARACTER; POSITION in INDEX);

  -- amend replaces part of the object by the given text, string, or character
  -- starting at the given position in the object

  function LOCATE (FRAGMENT : TEXT, WITHIN TEXT) return INDEX;
  function LOCATE (FRAGMENT : STRING, WITHIN TEXT) return INDEX;
  function LOCATE (FRAGMENT : CHARACTER, WITHIN TEXT) return INDEX;

  -- all return 0 if the fragment is not located

private
  type TEXT(MAXIMUM_LENGTH : INDEX) is
    record
      POS INDEX := 0;
      VALUE STRING(1 .. MAXIMUM_LENGTH);
    end record;
end TEXT_HANDLER;
```

7. Example of a Text Handling Package
Example of use of the text handling package:

A program opens an output file, whose name is supplied by the string NAME. This string has the form

[DEVICE :] [FILENAME [ EXTENSION]]

There are standard defaults for device, filename, and extension. The user-supplied name is passed to EXPAND_FILE_NAME as a parameter, and the result in the expanded version, with any necessary defaults added.

function EXPAND_FILE_NAME(NAME : STRING) return STRING is
use TEXT_HANDLER;

DEFAULT_DEVICE : constant STRING := "SY:"
DEFAULT_FILENAME : constant STRING := "RESULTS"
DEFAULT_EXTENSION : constant STRING := ".DAT"

MAXIMUM_FILE_NAME_LENGTH : constant INDEX := SOME APPROPRIATE VALUE;
FILENAME : TEXT(MAXIMUM_FILE_NAME_LENGTH);

begin
SET(FILE_NAME, NAME);
if EMPTY(FILE_NAME) then
SET(FILE_NAME, DEFAULT_FILENAME);
end if;
if LOCATE(':', FILE_NAME) = 0 then
SET(FILE_NAME, DEFAULT_DEVICE & FILE_NAME);
end if;
if LOCATE('.', FILE_NAME) = 0 then
APPEND(DEFAULT_EXTENSION, TO => FILE_NAME);
end if;
return VALUE(FILE_NAME);
end EXPAND_FILE_NAME;
8. Visibility Rules

The rules defining the scope of declarations and the rules defining which identifiers are visible at various points in the text of the program are described in this chapter. These rules are stated here as applying to identifiers. They apply equally to character strings used as function designators and to character literals used as enumeration literals.

References:

character literal 2.5, character string 2.6, enumeration literal 3.5.1, function designator 6.1, identifier 2.3

8.1 Definitions of Terms

Scope of a declaration:

A declaration associates an identifier with a program entity (see 3.1) such as a variable, a type, a subprogram, a formal parameter, a record component. The region of text over which a declaration has an effect is called the scope of the declaration. This region starts at the point where the declared identifier is introduced (within a compilation unit).

The same identifier may be introduced by different declarations in the text of a program and may thus be associated with different entities. The scopes of several declarations with the same identifier may even overlap.

Overlapping scopes of declarations with the same identifier can result from overloading of subprograms and of enumeration literals (see 6.6 and 3.5.1). They can also occur for record components, entities declared in package visible parts, and for formal parameters, where there is overlap of the scopes of the enclosing record type definitions, packages, subprograms, entries, or generic program units. Finally, overlapping scopes can result from nesting. In particular, subprograms, packages, tasks, and blocks can be nested within each other, a id can contain record type definitions or (possibly nested) loop statements.

Visibility of a declaration - visibility of an identifier:

The declaration of an entity with a certain identifier is said to be visible at (or from) a given point in the text when an occurrence of the identifier at this point can refer to the entity, that is, when the entity is an acceptable meaning for this occurrence. Some suitable context may be required to realize this visibility, as explained in section 8.3.

For overloaded identifiers, there may be several meanings acceptable at a given point, and the ambiguity must be resolved by the rules of overloading (see 4.6 and 6.6). For identifiers that are not overloaded (the usual case) there can be at most one acceptable meaning.
Whenever the declaration of an entity with a certain identifier is visible from a given point, the identifier and the entity are also said to be visible from that point. The visibility rules are the rules defining which identifiers are visible from various points of the text.

References:
block 5.6, compilation unit 10.1, declaration 3.1, enumeration literal 3.5.1, formal parameter 6.2, identifier 2.3, loop statement 5.5, overloaded literal 3.4 3.5.1 4.7, overloading a subprogram 6.6, package 7, record component 3.7, record type 3.7, subprogram 6, task 9, type 3.3, variable 3.2

8.2 Scope of Declarations

Entities can be declared in various ways. An entity can be declared in the declarative part of a block or in the declarative part of the body of a subprogram, package, or task; alternatively, an entity can be declared in the specification of a package or task. A separately compiled subprogram or package, other than a subunit, is effectively declared by its presence in a compilation.

An entity can be declared, alternatively, as a record component, as a discriminant, or as a formal parameter of a subprogram, entry or generic program unit. A loop parameter is declared by its occurrence in an iteration clause, an enumeration literal by its occurrence in an enumeration type definition. Finally, the declaration of a label, block identifier, or loop identifier is implicit.

The scope of each form of declaration (that is, the region of text over which the declaration has an effect) is defined below. Whenever the scope of an entity is said to extend from its declaration, this means that the scope extends from the point where the declared identifier is introduced.

(a) The scope of a declaration given in the declarative part of a block or in the declarative part of the body of a subprogram, package, or task extends from the declaration to the end of the block, subprogram, package, or task.

(b) The scope of a declaration given in the visible part of a package extends from the declaration to the end of the scope of the package declaration itself. It therefore includes the corresponding package body.

(c) The scope of a declaration given in the private part of a package extends from the declaration to the end of the package specification; it also extends over the corresponding package body.

(d) The scope of an entry declaration given in a task specification extends from the declaration to the end of the scope of the task declaration. It therefore includes the corresponding task body.

(e) The scope of a separately compiled subprogram or package, other than a subunit, comprises that compilation unit, its subunits (if any), any other compilation unit that mentions the name of the subprogram or package in a with clause, and the body of this subprogram or package. (See Chapter 10 for compilation units, subunits and with clauses).
The scope of record components, discriminants, formal parameters, loop parameters, and enumeration literals is defined by the following rules:

(f) The scope of a record component extends from the component declaration to the end of the scope of the record type declaration itself.

(g) The scope of a discriminant extends from the discriminant declaration to the end of the scope of the corresponding type declaration.

(h) The scope of a formal parameter of a subprogram, entry, or generic program unit extends from the parameter declaration to the end of the scope of the declaration of the subprogram, entry, or generic program unit itself. It therefore includes the body of the corresponding subprogram or generic program unit, and, for an entry, the corresponding accept statements.

(i) The scope of a loop parameter extends from its occurrence in an iteration clause to the end of the corresponding loop.

(j) The scope of an enumeration literal extends from its occurrence in the corresponding enumeration type declaration to the end of the scope of the enumeration type declaration itself.

Note:

The usual rules (a), (b), and (c) apply to subunits since they are declared in the declarative part of another compilation unit (see 10.2). Rule (a) also applies to the implicit declaration of a label, block identifier, or loop identifier, inserted at the end of a declarative part (see 5.1, 5.5, 5.6). For rule (e), note that the subprogram specification given only in the subprogram body acts as the subprogram declaration (see 6.3).

References:

accept statement 9.5, block 5.6, block identifier 5.6, compilation unit 10.1, component declaration 3.7, declarative part 3.9, discriminant 3.7.1, entry 9.5, entry declaration 9.5, enumeration literal 3.5.1, enumeration type definition 3.5.1, enumeration type declaration 3.5.1, formal parameter 6.2, generic program unit 12, iteration clause 5.5, label declaration 5.1, loop 5.5, loop identifier 5.5, loop parameter 5.5, package 7, package body 7.1, package specification 7.1, parameter declaration 6.1, private part 7.6, record component 3.7, scope 8.1, separate compilation 10, subprogram 6, subprogram body 6, subunit 10.2, task 9, task body 9.1, task specification 9.1, type declaration 3, with clause 10.1.1

8.3 Visibility of Identifiers and Declarations

The scope of the declaration of an identifier, as defined in the previous section, is the region of text over which the declaration has an effect. For each declaration, there exists a subset of this region where the declared entity can be named simply by its identifier; the entity, its declaration, and its identifier are then said to be directly visible from this subset. Where it is not directly visible (but within its scope), some suitable context may be required to make the entity visible. This context can be the prefix of a selected component, the place of a choice in a named record aggregate, the place of a discriminant name in a named discriminant constraint, or the place of a formal parameter name in a named parameter association.
An entity for which overloading is not possible and that is declared within a given construct is said to be hidden within an inner construct when the inner construct contains another declaration with the same identifier. Within the inner construct the hidden outer entity is not directly visible.

A subprogram declaration hides another subprogram declaration only if their specifications are equivalent with respect to the rules of subprogram overloading (see 6.6). Otherwise a subprogram identifier (also an enumeration literal) overloads, but does not hide, another subprogram (or enumeration literal) with the same identifier. A character literal may overload but cannot hide another character literal. The inner declaration of a subprogram or enumeration literal hides the declaration of any other non over-loadable outer entity with the same identifier.

The name of an entity declared immediately within a subprogram, package, or task, or immediately within a named block or loop can always be written as a selected component within this unit, whether the entity is directly visible or hidden (a declaration is said to be immediately within a construct if it is within that construct but not within an inner one). The name of the unit is used as a prefix (possibly also using component selection); the unit must be visible and the name unambiguous (even for an overloaded subprogram). Component selection thus provides the necessary context for realizing visibility of the selected entity from the point where the identifier occurs (after the dot).

This form of selected component is available for an identifier denoting an enumeration literal but is not available for record components or discriminants (since they are not declared immediately within one of the above units). For formal parameters of subprograms and generic program units, this notation is only available within the unit of which they are parameters (since the parameters are declared for that unit and not immediately within the unit in which the subprogram or generic program unit is itself declared). For formal parameters of an entry this notation is only available within an accept statement for the entry.

An entity declared immediately within a unit is said to be local to the unit, an entity visible within but declared outside the unit is said to be global to the unit.

For each form of declaration (within its scope), the region of text in which a declared identifier is visible (and directly visible unless hidden by an inner declaration) is defined as follows:

(a) An identifier declared in the declarative part of a block or in that of the body of a subprogram, package, or task is directly visible within this block or body.

(b) An identifier declared in the visible part of a package is directly visible within the package specification and body.

(c) An identifier declared in the private part of a package is directly visible within the package private part and body.

(d) An (entry) identifier declared in a task specification is directly visible within the task specification and body.

Outside the task, but within its scope, the identifier is made visible by a selected component whose prefix names the task or a task object of the task type.

8. Visibility of Identifiers and Declarations
(e) The identifier of a separately compiled subprogram or package is directly visible within the
compilation unit itself and its subunits, and within any other compilation unit that has a with
clause which mentions the identifier.

(f) The identifier of a record component is directly visible within the record type definition that
declares the component, and within a record type representation specification for the record
type.

Outside the record type definition, but within the scope of that definition, a record component is
made visible by a selected component whose prefix names a record of the type of which it is a
component. It is also visible as a choice in a component association of an aggregate of the
record type.

(g) The identifier of a discriminant is directly visible within the discriminant part that declares the
discriminant and within the associated record type definition.

Where it is not directly visible, but within the scope of the type, a discriminant is made visible by
being in a selected component or in an aggregate, as for any other record component. It is also
visible at the place of a discriminant name in a named discriminant specification of a
discriminant constraint.

(h) The identifier of a formal parameter of a subprogram is directly visible within the formal part
where the parameter is declared and within the subprogram body. The identifier of a formal
parameter of an entry is directly visible within the formal part where the parameter is declared
and within any accept statement for the entry. The identifier of a generic formal parameter is
directly visible within the generic part where the parameter is declared and within the
specification and body of the generic subprogram or package.

Where it is not directly visible, but within its scope, a formal parameter of a subprogram, entry,
or generic program unit is visible at the place of a formal parameter name in a named parameter
association of a corresponding subprogram call, entry call, or generic instantiation.

(i) The identifier of a loop parameter is directly visible within the loop where it is declared.

(j) An enumeration literal is directly visible within the scope of the enumeration type that declares
the literal.

A declaration must not hide another declaration in the same declarative part (that is, at the same level,
not in a nested declarative part). For this rule a generic part, a formal part of a subprogram, and the
declarative part of the subprogram body are considered as comprising one declarative part. Similarly,
a generic part, a package specification, and the declarative part of a package body are considered as
comprising a single declarative part.
Example:

```ada
procedure P is
  A : BOOLEAN;
  B : BOOLEAN;

procedure Q is
  C : BOOLEAN;
  B : BOOLEAN; -- an inner redeclaration of B
begin
  B := A; -- means Q.B := P.A;
  C := P.B; -- means Q.C := P.B;
end;

begin
  A := B; -- means P.A := P.B;
end;
```

**Note:**

An enumeration literal may overload but cannot hide another enumeration literal since enumeration literals are declared by their occurrence in an enumeration type declaration, and since two type declarations introduce distinct types.

**References:**

accept statement 9.5, aggregate 4.3, block 5.6, character literal 2.5, compilation unit 10.1, declaration 3.1, declarative part 3.9, discriminant 3.7.1, discriminant constraint 3.7.2, entry 9.5, entry call 9.5, enumeration literal 3.5.1, enumeration type 3.5.1, formal parameter 6.2, formal part 6.1, generic formal parameter 12.1, generic instantiation 12.3, generic package 12.1, generic part 12.1, generic program unit 12, generic subprogram 12.1, identifier 2.3, loop 5.5, loop parameter 5.5, name 4.1, overloading 3.4 3.5.1 4.6 6.6, package 7, package body 7.1, package specification 7.1, private part 7.4, record component 3.7, record type 7.1, record type representation 13.4, scope 8.1, selected component 4.1.3, subprogram 6, subprogram body 6, subprogram call 6.4, subprogram declaration 6, subprogram overloading 6.6, subprogram specification 6.1, subunit 10.2, task 9, task body 9.1, task object 9.2, task specification 9.1, task type 9.2, use clause 9.4, visible 8.1, visible part 7.2, with clause 10.1.1

### 8.4 Use Clauses

If the name of a package is visible at a given point of the text, the entities declared within the visible part of the package can be denoted by selected components. In addition, direct visibility of such entities can be achieved by means of use clauses.

```ada
use_clause ::= use package_name {. package_name};
```

A use clause is a declarative item. The effect of the elaboration of a use clause is to cause certain identifiers of the visible parts of the named packages to become directly visible from the text subject to the use clause. This effect takes place only on completion of this elaboration.
In order to define the set of identifiers (and entities) that are made directly visible by use clauses at a given point of the text, consider the set of package names appearing in the use clauses of all (nested) units enclosing this point, up to the compilation unit itself.

- An identifier is made directly visible by a use clause if it is declared in the visible part of one and only one package of the set and if the same identifier declared elsewhere is not already directly visible otherwise (that is in the absence of any use clause).

- An enumeration literal declared in the visible part of a package of the set is made directly visible if and only if the corresponding identifier is not otherwise directly visible, and in any case if it is a character literal.

- A subprogram declared in the visible part of a package of the set is made directly visible if and only if the two following conditions are satisfied. First, the specification of the subprogram must not be equivalent (see 6.6) to that of another subprogram in the set or to that of a subprogram that is otherwise directly visible. Second, an entity other than a subprogram or an enumeration literal and with the same identifier must not be declared in the visible part of any of the packages of the set, nor may such an entity be otherwise directly visible.

Thus an identifier made directly visible by a use clause can never hide another identifier although it may overload it. If an entity declared in the visible part of a package cannot be made visible by a use clause (because of one of the above conflicts), the name of the entity must take the form of a selected component.

For overloading resolution within an expression, identifiers made visible by a use clause are only considered if an interpretation of the complete expression cannot otherwise be found (that is, if the expression would be undefined without the use clause). Similarly, for overloading resolution of a procedure or entry call, identifiers made visible by a use clause are only considered if an interpretation of the complete procedure or entry call cannot otherwise be found. An ambiguity exists if there is more than one interpretation without the use clauses or if there is no interpretation without the use clauses but more than one can be given in their presence.

Example of conflicting names in two packages:

```plaintext
procedure R is
  use TRAFFIC, WATER_COLORS;
  -- subtypes used to resolve the conflicting type name COLOR
  subtype T_COLOR is TRAFFIC.COLOR;
  subtype W_COLOR is WATER_COLORS.COLOR;
  SIGNAL : T_COLOR;
  PAINT   : W_COLOR;
begin
  SIGNAL  := GREEN;  -- that of TRAFFIC
  PAINT   := GREEN;  -- that of WATER_COLORS
end R;
```

Use Clauses 8.4
Example of name identification with a use clause:

```ada
package D is
  T, U, V : BOOLEAN;
end D;

procedure P is
  package E is
    B, W, V : INTEGER;
  end E;

procedure Q is
  T, X : REAL;
begin
  declare
  use D, E;
  begin
      -- the name T means Q.T, not D.T
      -- the name U means D.U
      -- the name B means E.B
      -- the name W means E.W
      -- the name X means Q.X
      -- the name V is illegal: either D.V or E.V must be used
  end Q;
begin
end P;
```

Example of overloading resolution with a use clause:

```ada
procedure MAIN is
    ... package P is
    function F (X : REAL) return TARGET;  -- P.F
    function G(X : SOURCE) return REAL;  -- P.G
    function K (X : SOURCE) return BOOLEAN;  -- P.K
    end P;
    function F (X : BOOLEAN) return TARGET;  -- MAIN.F
    function G(X : SOURCE) return BOOLEAN;  -- MAIN.G
    function H(X : SOURCE) return REAL;  -- MAIN.H
    function K (X : SOURCE) return REAL;  -- MAIN.K
    S : SOURCE;
    T : TARGET;
    use P;
begin
    begin
    T := F(G(S));  -- MAIN.F(MAIN.G(S)), interpreted without considering use clause
    T := F(H(S));  -- P.F(MAIN.H(S))
    -- T := F(K(S)) would be ambiguous
    -- it could mean either MAIN.F(P.(S)) or P.F(MAIN.K(S))
    end;
```

8.4 Use Clauses
Note:
Renaming declarations and subtype declarations may help to avoid excessive use of selected components.

References:
character literal 2.5, compilation unit 10.1, declarative item 3.9, direct visibility 8.3, elaboration 3.1, entry call 9.5, enumeration literal 3.5.1, expression 4.4, identifier 2.3, hidden 8.3, name 4.1, overloading 3.4 3.5.1 4.6 6.6, package 7, procedure call 6.4, renaming declaration 8.5, selected component 4.1.3, subprogram 6, subprogram specification 6.1, subtype declaration 3.3, type 3.3, visible 8.1, visible part 7.2

8.5 Renaming Declarations

A renaming declaration declares another name for an entity.

\[
\text{renaming_declaration ::=}
\]

- identifier : type_mark renames name;
- identifier : exception renames name;
- package identifier renames name;
- task identifier renames name;
- subprogram_specification renames name;

For the elaboration of a renaming declaration, the identifier is first introduced, or the subprogram specification is elaborated, and then the identity of the entity following the reserved word renames is established. The identifier can be used as the name of this entity from then on.

The first form is used for renaming objects. The newly declared identifier is constant if the renamed entity is.

The type mark given in the renaming declaration must express the same constraints as those of the renamed entity. A component of an unconstrained object of a type with discriminants cannot be renamed if the existence of the component depends on the value of a discriminant.

The last form is used for renaming a subprogram (or entry) whose specification matches the one given in the renaming declaration in the following sense. The renamed subprogram and this specification must have parameters in the same order, of the same mode and with the same types and constraints. For functions the result type and constraints must be the same. Parameter names, the presence or absence of defaults, and the values of any defaults, are ignored for this matching; hence a renaming declaration can introduce different default parameters.

A function can be renamed as an operator and vice versa (renaming cannot, of course, declare an operator with default parameters, see 6.7). An entry can only be renamed as a procedure.

A renaming declaration is ambiguous, and therefore illegal, if more than one visible subprogram (or entry) matches the subprogram specification. The exception CONSTRAINT_ERROR is raised if the constraints of the parameters or results of the two subprograms (or entries) are not the same.
Examples:

```ada
procedure TMR (ELEM : out ITEM) renames TABLE_MANAGER.RETRIEVE;
procedure SORT (X : in out LIST) renames QUICKSORT2;
task T renames POOL(6);
FULL : exception renames TABLE_MANAGER.TABLE_FULL;
```

declare
  L : PERSON renames LEFTMOST_PERSON;
begin
  L.AGE := L.AGE + 1;
end;

```ada
function REAL_PLUS (X, Y : REAL) return REAL renames "+";
function INT_PLUS (X, Y : INTEGER) return INTEGER renames "+";
function "*" (X, Y : VECTOR) return REAL renames DOT_PRODUCT;
```

Notes:
Renaming may be used to resolve name conflicts, to achieve partial evaluation and to act as a shorthand. Renaming does not hide the old name. Neither a label, nor a block or loop identifier may be renamed. A subtype can effectively be used to rename a type as in

```ada
subtype INPUT is TEXT_IO.IN_FILE;
```

References:

- block identifier 5.6
- constant 3.2
- constraint 3.3
- constraint on parameters 6.4.1
- constraint_error exception 11.1
- declaration 3
- elaboration 3.1
- entry 9.5
- function 6.1 6.5
- identifier 2.3
- label 5.1
- loop identifier 5.5
- mode 6.2
- name 4.1
- operator 4.5
- parameter 6.1
- parameter name 6.2
- parameter type 6.1
- subprogram specification 6.1
- subtype 3.3
- type 3.3
- type mark 3.3
- unconstrained record type 3.7
- variant record 3.7.1

8.6 Predefined Environment

All predefined identifiers, for example those of built-in types such as INTEGER, BOOLEAN, and CHARACTER, operators and the predefined function ABS, are assumed to be declared in the predefined package STANDARD given in Appendix C. All identifiers declared in the visible part of the package STANDARD are assumed to be declared at the outermost level of every program. In addition, the separately compiled subprograms and packages named in a with clause are assumed to be implicitly declared in STANDARD.

Note:
If all blocks of a program are named, the name of any program unit can always be written as a selected component starting with STANDARD (unless this name is itself hidden by a redeclaration). Apart from the local package SYSTEM and the definitions of predefined numeric types and subtypes, the package STANDARD must be the same for all implementations of the language.

References:

- abs function 5.6
- boolean type 3.5.3
- character type 3.5.2
- identifier 2.3
- integer type 3.5.4
- name 4.1
- operator 4.5
- package 7
- program unit 7
- selected component 4.1.3
- standard package 5
- type 3.3
- visible part 7.2
- with clause 10.1.1

K.4 Predefined Environment
9. Tasks

Tasks are entities that may operate in parallel. Parallel tasks may be implemented on multicomputers, multiprocessors, or with interleaved execution on a single processor. Tasks may have entries which may be called by other tasks. Synchronization is achieved by rendezvous between a task issuing an entry call and a task accepting the call. Entries are also the principal means of communication between tasks.

Tasks are one of the three forms of program units, of which programs can be composed. The other forms are subprograms and packages. The properties of tasks and entries, and the statements specific to tasking (that is, accept statements and selective waits) are described in this chapter.

9.1 Task Specifications and Task Bodies

A task specification which starts with the reserved words task type defines a task type. An object of a task type denotes a task having the entries, if any, that are declared in the task specification. The task specification therefore specifies the interface between tasks of the type and other tasks of the same or of different types.

The execution of a task is defined by a task body. A task specification and the corresponding task body have the same identifier and must occur in the same declarative part, the specification first.

```
task_declaration ::= task_specification

task_specification ::= 
  task [type] identifier [is ]
  {entry_declaration}
  {representation_specification}
  end [identifier];

task_body ::= 
  task body identifier is 
  [declarative_part]
  begin
  sequence_of_statements
  [exception
  {exception_handler}]
  end [identifier];
```

A task specification without the reserved word type defines a single task. A task declaration of this form introduces a task name (rather than the name of a task type) and is equivalent to the declaration of an anonymous task type immediately followed by the declaration of an object of the type. In the remainder of this chapter, explanations are given in terms of task type specifications; the corresponding explanations for single task declarations follow from the stated equivalence.
For the elaboration of a task specification the task type (or task) identifier is first introduced and can from then on be used as the name of the corresponding task type (or task). Entry declarations and representation specifications, if any, are then elaborated in the given order. Such representation specifications only apply to the entries declared in the task specification, or to the task type (or task) itself (see 13.2 and 13.5).

The elaboration of a task body has no other effect than to establish the body as defining the execution of tasks of the corresponding type.

Examples of specifications of task types:

```ada
task type RESOURCE is
  entry SEIZE;
  entry RELEASE;
end RESOURCE;

task type KEYBOARD_DRIVER is
  entry READ (C : out CHARACTER);
  entry WRITE (C : in CHARACTER);
end KEYBOARD_DRIVER;
```

Examples of specifications of single tasks:

```ada
task PRODUCER_CONSUMER is
  entry READ (V : out ELEM);
  entry WRITE (E : in ELEM);
end;

task CONTROLLER is
  entry REQUEST (LEVEL) (D : DATA); -- a family of entries
end CONTROLLER;

task USER; -- has no entry
```

Example of task specification and corresponding body:

```ada
task PROTECTED_ARRAY is
  -- INDEX and ELEM are global types
  entry READ (N : in INDEX; V : out ELEM);
  entry WRITE (N : in INDEX; E : in ELEM);
end;

task body PROTECTED_ARRAY is
  TABLE : array(INDEX) of ELEM := (INDEX => 0);
begin
  loop
    select
      accept READ (N : in INDEX; V : out ELEM) do
        V := TABLE(N);
      end READ;
    or
      accept WRITE (N : in INDEX; E : in ELEM) do
        TABLE(N) := E;
      end WRITE;
    end select;
  end loop;
end PROTECTED_ARRAY;
```

9.1 Task Specifications and Task Bodies
Task Objects and Task Types

Objects of a task type are defined by object declarations where the type indicated is the task type. Task objects can also be components of records and arrays. Finally, objects of a task type can be the objects (or components of the objects) designated by the values of an access type.

The value of an object of a task type denotes a task of the type (this task has the corresponding entries). This value is defined either by the elaboration of the corresponding object or by its creation by an allocator. Entries of the corresponding task can be called once this value is defined.

Neither assignment nor comparison for equality or inequality are defined for objects of task types. In this respect, a task type has the properties of a limited private type: it can appear as the definition of a limited private type given in a private part, and as a generic actual parameter associated with a formal parameter that is a limited private type.

In subprogram calls and generic instantiations, a task object can be passed as an actual parameter associated with a formal parameter of the same task type. Since the value of a task object denotes a task, both the formal parameter and the actual parameter denote the same task. The in, out, and out parameter modes are not allowed for parameters of a task type.

Examples:

CONTROL : RESOURCE;
TELETYPE : KEYBOARD_DRIVER;
POOL : array(1 .. 10) of KEYBOARD_DRIVER;

Example of access type designating task objects:

type KEYBOARD is access KEYBOARD_DRIVER;

TERMINAL : KEYBOARD := new KEYBOARD_DRIVER;

Notes:

Task objects behave as constants since their values are implicitly defined and no assignment is available. If an application needs to store and exchange task identities, it can do so by defining an access type designating the corresponding task objects and by using access values for identification purposes (see above example). Assignment is available for such an access type as for any access type.

There are no constraints applicable to task types.

References:

access type 3.8, allocator 4.8, entry 9.5, generic parameter 12.1, limited private type 7.4.2, object declaration 3.2
9.3 Task Execution

A task body defines the execution of the tasks of the corresponding type. The activation of a task object consists of the elaboration of the declarative part, if any, of the corresponding task body. After activation the statements of the task body are executed.

Task objects declared immediately within a declarative part (that is, not within a nested declarative part), and task objects that are components of other objects declared immediately within a declarative part, are all activated before execution of the first statement following the declarative part. Each task can continue its execution as a parallel entity once its activation is completed.

Should an exception occur during the activation of one of these tasks, that task and any other of these tasks that are not yet activated become terminated tasks (see 9.4); already activated tasks are unaffected. Such an exception is treated as if raised within the statements following the declarative part in question. Should an exception occur within the declarative part itself, all of the declared tasks so far elaborated become terminated tasks.

For the above rules, in a package body without statements, a null statement is assumed; in the absence of a package body, one containing a single null statement is assumed to occur not earlier than the task body.

The creation of a task object by an allocator is followed by its activation and execution. Execution of the allocator is complete when all created task objects have been activated. Each task can continue its execution as a parallel entity as soon as its activation is completed. Should an exception occur during the activation of one of these tasks, that task and any other of these tasks that are not yet activated become terminated tasks.

A task must not be activated before the elaboration of the corresponding task body is complete. An entry of a task can be called before the task has been activated. If the called task terminates before accepting an entry call, the exception TASKING_ERROR is raised in the calling task (see 11.4).

Example:

```ada
procedure P is
   A, B : RESOURCE;  -- elaborate A, B
   ...
   C : RESOURCE;     -- elaborate C
begin
   -- A, B, C are activated in any order
   ...
end;
```

Notes:
The language does not specify the order in which tasks declared within a declarative part are activated.
9.4 Normal Termination of Tasks

Each task depends either on a block, a subprogram body, a task body, or on a library package (no task depends on a package declared within another unit). For each of these units a dependent task is one of:

(a) A task object that is an object (or a component of an object) declared within the unit considered, including within an inner package, but excluding within any inner block, subprogram body, or task body.

(b) A task object that is the object (or a component of the object) designated by the value of an access type, if this access type is declared within the unit considered, including within an inner package, but excluding within any inner block, subprogram body, or package body.

A block, subprogram body, or task body is not left until all dependent tasks have terminated their execution (including the case where the end of this block or body is reached as the result of an unhandled exception).

Normal termination of a task occurs when its execution reaches the end of its task body and all dependent tasks, if any, have terminated. Normal termination also occurs on selection of a terminate alternative in a selective wait statement (see 9.7.1). After its termination, a task is said to be terminated.

Example:

```pascal
declare
type GLOBAL is access RESOURCE;
A, B : RESOURCE;
G : GLOBAL;
begin
-- activation of A and B
declare
type LOCAL is access RESOURCE;
X : GLOBAL := new RESOURCE;  -- activation of X.all
L : LOCAL := new RESOURCE;  -- activation of L.all
C : RESOURCE;
begin
-- activation of C
...
end;  -- await termination of C and L.all but not X.all
...
end;  -- await termination of A, B, G.all and X.all
```

Normal Termination of Tasks 9.4
Notes:

The usual rules apply to the main program. Consequently, termination of the main program awaits termination of any dependent task even if the corresponding task type is declared in a library package. On the other hand, termination of the main program does not await termination of tasks denoted by task objects declared in library packages; the language does not define whether such tasks are required to terminate.

References:

access type 3.8, block 5.6, component 3.2 3.6 3.7 4.1, library package 10.1, main program 10.1, object 3.2, selective wait 9.7.1, task type 9.2, terminate alternative 9.7

9.5 Entries and Accept Statements

An entry declaration is similar to a subprogram declaration and can be given only in a task specification. An entry of a task can be called by another task. The actions to be performed when an entry is called are specified by corresponding accept statements. Entry call and accept statements are the primary means of communication between tasks and of synchronization of tasks.

```
entry_declaration ::= entry_identifier [(discrete_range)] [formal_part];

entry_call ::= entryname [(actual_parameter_part)];

accept_statement ::= accept entry_name [formal_part] [do
sequence_of_statements
end [identifier]];)
```

For the elaboration of an entry declaration the entry identifier is first introduced; any discrete range is then evaluated; finally, any formal part is elaborated as for a subprogram declaration. From then on, the entry identifier can be used as a name of the corresponding entry (or entry family). An entry declaration including a discrete range declares a family of distinct entries having the same formal part (if any); that is, one such entry for each value of the discrete range.

Each task of a task type has the entries declared in the specification of the task type. Within the body of a task, each of its entries (or entry families) can be named by the corresponding identifier; the name of an entry of a family takes the form of an indexed component, the family name being followed by the index in parentheses. Outside the body of a task an entry name has the form of a selected component, with the name of the task object prefixing the identifier of one of its entries. Selected component notation may also be used within a task body, with the name of the task or task type as the prefix.

The syntax of an entry call is similar to that of a procedure call. The semantics is as follows.

An accept statement specifies the actions to be performed at a call of a named entry (it can be an entry of a family). The formal part given in the accept statement must match that given in the corresponding entity declaration; the matching rules are the same as for the match between the formal part of a subprogram body and the formal part of the corresponding subprogram declaration.
Tasks

An accept statement for an entry of a given task may only appear within the sequence of statements of the corresponding task body. The consequence of this rule is that a task can execute accept statements only for its own entries. A task body may contain more than one accept statement for the same entry.

Execution of an accept statement starts with the evaluation of any entry index (in the case of an entry of a family). Execution of an entry call also starts with the evaluation of any entry index, followed by the evaluation of any expression in the actual parameter list. Further execution of the accept statement and of a corresponding entry call are synchronized. There are two possibilities:

- If a calling task issues an entry call before a corresponding accept statement is reached by the task owning the entry, the execution of the calling task is suspended.

- If a task reaches an accept statement prior to any call of that entry, the execution of the task is suspended until such a call occurs.

When an entry has been called and a corresponding accept statement is reached, the sequence of statements, if any, of the accept statement is executed by the called task (while the calling task remains suspended). This interaction is called a rendezvous. Thereafter, the calling task and the task owning the entry can continue their execution in parallel.

If several tasks call the same entry before a corresponding accept statement is reached, the calls are queued: there is one queue associated with each entry. Each execution of an accept statement removes one call from the queue. The calls are processed in order of arrival.

Entries may be overloaded both with each other and with procedures with the same identifier. An entry may be renamed as a procedure.

An attempt to call an entry of a terminated task raises the exception TASKING_ERROR. The exception CONSTRAINT_ERROR is raised by the evaluation of the name of an entry of a family if the index is not within the specified discrete range.

Examples of entry declarations:

```plaintext
entry READ(V : out ELEM);
entry SEIZE;
entry REQUEST(RANK)(D : DATA);  -- a family of entries
```

Examples of entry calls:

```plaintext
CONTROL.RELEASE;
PRODUCER_CONSUMER.WRITE(E);
POOL(5).READ(NEXT_CHAR);
CONTROLLER.REQUEST(LOW)(SOME_DATA);
```

Examples of accept statements:

```plaintext
accept SEIZE;

accept READ(V : out ELEM) do
    V := LOCAL_ELEM;
end READ;

accept REQUEST(LOW)(D : DATA) do ... end REQUEST;
```
Notes:

An accept statement may contain other accept statements (possibly for the same entry) and may call subprograms issuing entry calls. An accept statement need not have a sequence of statements even if the corresponding entry has parameters. Equally, it may have a sequence of statements even if the corresponding entry has no parameters. A task may call its own entries but it will, of course, deadlock. The language permits conditional and timed entry calls (see 9.7.2 and 9.7.3). The language rules ensure that a task can only be in one queue at a given time.

If the bounds of the discrete range of an entry family are integer numbers, the indexes must be of the predefined type INTEGER (see 3.6.1).

References:

actual parameter 6.4, conditional entry call 9.7.2, constraint_error exception 11.1, discrete range 3.6.1, elaboration 3.1 3.9, formal part 6.2, indexed component 4.1.1, name 4.1, overloading a subprogram 6.6, procedure call 6.4, renaming 8.5, selected component 4.1.3, sequence of statements 5.1, subprogram call 6.4, subprogram declaration 6.1, subprogram body 6.3, task body 9.1, task specification 9.1, task type 9.2, tasking_error exception 11.5, timed entry call 9.7.3

9.6 Delay Statements, Duration and Time

A delay statement suspends further execution of the task that executes it for at least the given time interval.

delay_statement :: = delay simple_expression;

The argument of the delay statement is of the predefined fixed point type DURATION and is given in seconds. A delay statement with a non-positive argument has no effect.

The type DURATION allows representation of durations (both positive and negative) up to at least 86400 seconds (one day). The definition of the type TIME is provided in the predefined library package CALENDAR. The function CLOCK returns the current value of TIME at the time it is called. The operators "+" and "-" for addition and subtraction of times and durations have a conventional meaning.

package CALENDAR is
  type TIME is
    record
      YEAR : INTEGER range 1901 .. 2099;
      MONTH : INTEGER range 1 .. 12;
      DAY : INTEGER range 1 .. 31;
      SECOND : DURATION;
    end record;
  function CLOCK return TIME;
  function "+" (A : TIME; B : DURATION) return TIME;
  function "+" (A : DURATION; B : TIME) return TIME;
  function "-" (A : TIME; B : DURATION) return TIME;
  function "-" (A : TIME; B : TIME) return DURATION;
end CALENDAR;
Examples:

delay 3.0; -- delay 3.0 seconds

declare
  INTERVAL : constant DURATION := 60.0;
  NEXT_TIME : CALENDAR.TIME := CALENDAR.CLOCK() + INTERVAL;
begin
  loop
    delay NEXT_TIME - CALENDAR.CLOCK();
    -- some actions
    NEXT_TIME := NEXT_TIME + INTERVAL;
  end loop;
end;

Notes:
The second example causes the loop to be repeated every 60 seconds on the average. This interval between two successive iterations is only approximate. However there will be no cumulative drift as long as the duration of each iteration is (sufficiently) less than INTERVAL.

References:
fixed point type 3.5.9, library package 10.1

9.7 Select Statements

There are three forms of select statements. One form provides a selective wait for one or more alternatives. The other two provide conditional and timed entry calls

select_statement ::= selective_wait
| conditional_entry_call | timed_entry_call

9.7.1 Selective Wait Statements

This form of the select statement allows a combination of waiting for, and selection of, one or more alternatives. The selection may depend on conditions associated with each alternative of the selective wait statement.

selective_wait ::= 
  select
    [when condition =>]
      select_alternative
    (or [when condition =>]
      select_alternative)
  [else
      sequence_of_statements]
  end select;

A select alternative is said to be open if there is no preceding when clause or if the corresponding condition is true. It is said to be closed otherwise.

A selective wait can contain at most one terminate alternative; it cannot contain both a terminate alternative and an alternative starting with a delay statement. Each of these possibilities excludes the presence of an else part. A selective wait must contain at least one alternative commencing with an accept statement.

Execution of a selective wait statement proceeds as follows:

(a) All conditions are evaluated to determine which alternatives are open. For an open alternative starting with a delay statement, the delay expression is evaluated immediately after the evaluation of the corresponding condition. Similarly, if an open alternative starts with an accept statement for an entry of a family, the entry index is evaluated immediately after the evaluation of the condition.

(b) An open alternative starting with an accept statement may be selected if a corresponding rendezvous is possible (that is, when a corresponding entry call has been issued by another task). When such an alternative is selected, the corresponding accept statement and possible subsequent statements are executed.

(c) An open alternative starting with a delay statement will be selected if no other alternative has been selected before the specified duration has elapsed. Any subsequent statements of the alternative are then executed.

(d) An open alternative with the reserved word terminate may be selected only if the task containing the selective wait belongs to the set of dependent tasks of a block, subprogram, or task, and either the end of this block, subprogram body or task body has been reached (see 9.4), or in the case of a task body, a terminate alternative has been reached. This (first mentioned) alternative will be selected if and only if all other tasks of the set, also any task depending on a task of the set, and so on, are either terminated or waiting at a selective wait with a terminate alternative. Election of a terminate alternative causes normal termination of the task. A terminate alternative may not appear in an inner block that declares task objects.

(e) If no alternative can be immediately selected, and there is an else part, the else part is executed. If there is no else part, the task waits until an open alternative can be selected.

(f) If all alternatives are closed and there is an else part, the else part is executed. If all alternatives are closed and there is no else part the exception SELECT_ERROR is raised.

In general, several entries of a task may have been called before a selective wait is encountered. As a result, several alternative rendezvous are possible. Similarly, several open alternatives may start with an accept statement for the same entry. In such cases one of these alternatives is selected arbitrarily.
Tasks

Example:

```
task body RESOURCE is
    BUSY : BOOLEAN := FALSE;
begin
    loop
        select
            when not BUSY =>
                accept SEIZE do
                    BUSY := TRUE;
                end;
            or
                accept RELEASE do
                    BUSY := FALSE;
                end;
            or
                when not BUSY => terminate;
        end select;
    end loop;
end RESOURCE;
```

Notes:

Selection among open alternatives starting with accept statements is performed arbitrarily. This means that the selection algorithm is not defined by the language and that any program relying on a particular selection algorithm is therefore erroneous. Several open alternatives may start with a delay statement. A consequence of the above rules is that only the alternative with the shortest duration can be selected (a negative duration being shorter than a positive one).

The language does not define in which order to evaluate the conditions of a select statement. A program that relies on a specific order is therefore erroneous.

References:

- accept statement 9.5, condition 5.3, delay statement 9.6, dependent task 9.4, duration 9.6, entry call 9.5, entry family 9.5, rendezvous 9.5, sequence of statements 5.1, task 9.2 task termination 9.4

9.7.2 Conditional Entry Calls

A conditional entry call issues an entry call if and only if a rendezvous is immediately possible.

```
  conditional_entry_call ::= 
    select 
        entry_call [sequence_of_statements] 
    else: 
        sequence_of_statements 
    end select;
```
For the execution of a conditional entry call an entry index (in the case of an entry of a family) is first evaluated. This is followed by the evaluation of any expression occurring in the actual parameters. If a rendezvous with the called task is immediately possible, it is performed and the optional sequence of statements after the entry call is then executed. Otherwise the else part is executed.

Example

```
procedure SPIN(R : RESOURCE) is
   begin
      loop
          select
             R.SEIZE;
             return;
          else
              null; -- busy waiting
          end select;
      end loop;
   end;
```

References:

accept 9.5, actual parameter 6.4, entry call 9.5, entry family 9.5, rendezvous 9.5, sequence of statements 5.1

9.7.3 Timed Entry Calls

A timed entry call issues an entry call if and only if this entry call can be accepted within a given delay.

```
timed_entry_call ::=
   select
      entry_call [sequence_of_statements]
   or
      delay_statement [sequence_of_statements]
   end select;
```

For the execution of a timed entry call an entry index (in the case of an entry of a family) is first evaluated. This is followed by the evaluation of any expression occurring in the actual parameters and by the evaluation of the expression stating the delay.

If a rendezvous can be started within the specified duration, it is performed and the optional sequence of statements after the entry call is then executed. Otherwise the optional sequence of statements of the delay alternative is executed.
Example:

```plaintext
select
  CONTROLLER.REQUEST(URGENT)(SOMEDATA);
or
delay 45.0;
  -- controller too busy, try something else
end select;
```

References:


9.8 Priorities

Each task may (but need not) have a priority, which is an integer value of the predefined subtype PRIORITY. A lower value indicates a lower degree of urgency; the range of priorities is implementation defined. A priority is associated with a task if a pragma

```plaintext
pragma PRIORITY (static_expression);
```

appears in the corresponding task specification; the priority is given by the value of the expression. A priority is associated with the main program if such a pragma appears in its outermost declarative part. At most one such pragma can appear within a given task specification (or for the main program).

The specification of a priority is an indication given to the compiler, to assist in the allocation of processing resources to parallel tasks when there are more tasks eligible for execution than can be supported simultaneously by the available processing resources. The effect of priorities on scheduling is defined by the following rule:

If two tasks with different priorities are both eligible for execution and could sensibly be executed using the same processing resources then it cannot be the case that the task with the lower priority is executing while the task with the higher priority is not.

For tasks of the same priority, the scheduling order is not defined by the language. For tasks without explicit priority, the scheduling rules are not defined, except when such tasks are engaged in rendezvous. If the priorities of both tasks engaged in a rendezvous are defined, the rendezvous is executed with the higher of the two priorities. If only one of the two priorities is defined, the rendezvous is executed with at least that priority. If neither is defined, the priority of the rendezvous is undefined.

Notes:

The priority of a task is static and therefore fixed. Priorities should be used only to indicate relative degrees of urgency; they should not be used for task synchronization.

References:

declarative part 3.9, main program 10.1, pragma 2.8, rendezvous 9.5, static expression 4.9, synchronization 9.5, task 9.2, task specification 9.1
9.9 Task and Entry Attributes

For a task object or for a task type T the following attributes are defined:

\[ \text{T.TERMINATED} \]
Of type BOOLEAN. This attribute is initially equal to FALSE when the task T is declared (or allocated) and becomes TRUE when the task is terminated.

\[ \text{T.PRIORITY} \]
Of the subtype PRIORITY. The value of this attribute is the priority of the task T if one is defined; use of this attribute is otherwise not allowed.

\[ \text{T.STORAGE_SIZE} \]
This attribute indicates the number of storage units allocated for the task T. Of type universal_integer.

For an entry E of a task T the following attribute may be used within the body of the task T:

\[ \text{E.COUNT} \]
The number of entry calls presently on the queue associated with the entry E. Of type INTEGER.

Note:

Algorithms interrogating the attribute E.COUNT should take precautions to allow for the increase of the value of this attribute for incoming entry calls, and its decrease, for example with timed entry calls. Within an accept statement for an entry, the count does not include the calling task.

References:

attribute 4.1.4, entry call 9.5, entry queue 9.6, integer number 2.4, integer type 3.5.4, priority 9.8, storage unit 13.2, task body 9.1, task termination 9.4

9.10 Abort Statements

Abnormal termination of one or several tasks is achieved by an abort statement.

\[ \text{abort_statement : = abort task_name [, task_name]}; \]

An abort statement causes the unconditional asynchronous termination of the named tasks. If a task is already terminated there is no effect; if a task has not yet been activated it is terminated and there is no other effect.

At normal termination of a task causes the abnormal termination of any task dependent on it. It further causes the abnormal termination of any task dependent on any subprogram (or block) being called directly or indirectly by the task. On completion of the abort statement each of these tasks is terminated.

9.0 Abort Statements
If a task calling an entry is abnormally terminated it is removed from the entry queue; if the rendezvous is already in progress the calling task is terminated but the task executing the accept statement is allowed to complete the rendezvous normally. If there are pending entry calls (possibly timed) for the entries of a task that is abnormally terminated, an exception TASKING_ERROR is raised for each calling task at the point where it calls the entry (including for the task presently engaged in a rendezvous, if any); for a timed entry call, such an exception cancels the delay.

Example:

    abort USER, TERMINAL.all, POOL(3);

Notes:

An abort statement should be used only in extremely severe situations requiring unconditional termination. In less extreme cases (where the task to be terminated can be given the possibility of executing some cleanup actions before termination), the exception FAILURE could be raised for the task (see 11.5). A task may abort any task, including itself.

References:

accept statement 9.5, block 5.6, dependent task 9.4, entry call 9.5, entry queue 9.5, name 4.1, rendezvous 9.5, subprogram 6, task 9.2, task activation 9.3, task elaboration 9.1, task termination 9.4, tasking_error exception 11.4, timed entry call 9.7.3

9.11 Shared Variables

The normal means of communication between tasks is via entry calls.

If two tasks operate on common global variables, then neither of them may assume anything about the order in which the other performs its operations except at the points where they synchronize. Two tasks are synchronized at the start and at the end of their rendezvous. At the time of its activation a task is synchronized with the task that causes this activation.

If shared variables are used, it is the programmer's responsibility to ensure that two tasks do not simultaneously modify the same shared variable.

Compilers will normally assume all variables not to be shared and may consequently maintain some of them in local registers. Whenever one must ensure that a shared variable has been updated with its latest value, this can be achieved by calling a procedure obtained by instantiating on of the predefined generic library procedure SHARED_VARIABLE_UPDATE, for the type of the shared variable.

    generic
    type SHARED is limited private;
    procedure SHARED_VARIABLE_UPDATE(X : in out SHARED);

A call to such a procedure will generate no code, other than any code needed to update the shared variable with its latest value (for example, if this value is in a register).

References:

entry call 9.5, generic procedure 12.1, rendezvous 9.5, task 9.2, task activation 9.3
9.12 Example of Tasking

The following example defines a buffering task to smooth variations between the speed of output of a producing task and the speed of input of some consuming task. For instance, the producing task may contain the statements

```
loop
  -- produce the next character CHAR
  BUFFER.WRITE(CHAR);
  exit when CHAR = END_OF_TRANSMISSION;
end loop;
```

and the consuming task may contain the statements

```
loop
  BUFFER.READ(CHAR);
  -- consume the character CHAR
  exit when CHAR = END_OF_TRANSMISSION;
end loop;
```

The buffering task contains an internal pool of characters processed in a round-robin fashion. The pool has two indices, an `IN_INDEX` denoting the space for the next input character and an `OUT_INDEX` denoting the space for the next output character.

```
task BUFFER is
  entry READ (C : out CHARACTER);
  entry WRITE(C : in CHARACTER);
end;

task body BUFFER is
  POOL_SIZE constant INTEGER := 100;
  POOL : array(1 .. POOL_SIZE) of CHARACTER;
  COUNT : INTEGER range 0 .. POOL_SIZE := 0;
  IN_INDEX, OUT_INDEX : INTEGER range 1 .. POOL_SIZE := 1;
begin
  loop
    select
      when COUNT < POOL_SIZE =>
        accept WRITE(C : in CHARACTER) do
          POOL(IN_INDEX) := C;
        end;
        IN_INDEX := IN_INDEX mod POOL_SIZE + 1;
        COUNT := COUNT + 1;
      or when COUNT > 0 =>
        accept READ(C : out CHARACTER) do
          C := POOL(OUT_INDEX);
        end;
        OUT_INDEX := OUT_INDEX mod POOL_SIZE + 1;
        COUNT := COUNT - 1;
      or
        terminate
    end select;
  end loop;
end BUFFER;
```
10. Program Structure and Compilation Issues

The overall structure of programs and the facilities for separate compilation are described in this chapter. A program is a collection of one or more compilation units submitted to a compiler in one or more compilations. A compilation unit can be a subprogram declaration or body, a package declaration or body, a generic declaration, or a subunit, that is, the body of a subprogram, package, or task declared within another compilation unit.

References:
package body 7.1, package declaration 7.1, subprogram body 6.3, subprogram declaration 6.1, subunit 10.2, task body 9.1

10.1 Compilation Units - Library Units

The text of a program can be submitted to the compiler in one or more compilations. Each compilation is a succession of one or more compilation unit. A simple program may consist of a single compilation unit.

\[
\text{compilation ::= \{compilation_unit\}}
\]

\[
\text{compilation_unit ::=}
\]
\[
\text{context_specification subprogram\_declaration}
\]
\[
\text{l context_specification subprogram\_body}
\]
\[
\text{l context_specification package\_declaration}
\]
\[
\text{l context_specification package\_body}
\]
\[
\text{l context_specification subunit}
\]

\[
\text{context_specification ::= \{with\_clause \{use\_clause\}\}}
\]

\[
\text{with\_clause ::= with unit\_name \{, unit\_name\};}
\]

The compilation units of a program are said to belong to a program library. A compilation unit that is not a subunit of another unit is called a library unit. Within a program library the names of all library units must be distinct (except, of course, that a body has the same name as the corresponding declaration).

The compilation units of a compilation are compiled in the given order. The effect of compiling a subprogram or package declaration is to define (or redefine) the corresponding unit as one of the library units. The effect of compiling a subunit, or the body of a subprogram or package, is to define that body. The declaration of a subprogram that is not generic need not be supplied in a compilation, in which case compilation of the body serves as both the declaration and the body.
A compilation unit is effectively declared by its presence in a compilation. For the elaboration of a compilation unit, its context is first elaborated; the following subprogram declaration or body, package declaration or body, or subunit is then elaborated. The order of elaboration of compilation units need not be the order in which they appear in a compilation; this order of elaboration is defined in section 10.5.

The elaboration of a context specification consists of the elaboration of its constituent with clauses and use clauses. The only identifiers that are visible within a with clause are names of library units. The only package names that can be listed in the use clause of a context are those declared in the package STANDARD and those made visible by previous with clauses and previous use clauses. Any with clause and any use clause given in the context specification of a subprogram, package, or generic declaration applies also to the corresponding subprogram or package body (whether repeated or not). Any with clause and any use clause given for a compilation unit also applies to its subunits (if any).

The designator of a separately compiled subprogram must be an identifier (not an operator symbol). However, a separately compiled function may be renamed as an operator.

A library unit that is a subprogram can be a main program in the usual sense. The means by which the execution of a main program is initiated are not prescribed within the language definition.

Example 1: A main program:

The following is an example of a program consisting of a single compilation unit, a procedure printing the real roots of a quadratic equation. The predefined package TEXT_IO and the package REAL_OPERATIONS (containing the definition of the type REAL and of the packages REAL_IO and REAL_FUNCTIONS) are assumed to be already present in the program library. Such packages may be used by different main programs.

```ada
with TEXT_IO, REAL_OPERATIONS; use REAL_OPERATIONS;
procedure QUADRATIC_EQUATION is
  A, B, C, D : REAL;
  use REAL_IO, -- defines GET and PUT for REAL
     TEXT_IO, -- defines PUT for strings and NEW_LINE
     REAL_FUNCTIONS; -- defines SQRT
begin
  GET(A); GET(B); GET(C);
  D := B**2 - 4.0*A*C;
  if D < 0.0 then
    PUT("Imaginary Roots.");
  else
    PUT("Real Roots : X1 = ");
    PUT((-B - SQRT(D))/(2.0*A)); PUT(" X2 = ");
    PUT((-B + SQRT(D))/(2.0*A));
  end if;
  NEW_LINE;
end QUADRATIC_EQUATION;
```

Notes:

A compilation unit may be a generic package or a generic subprogram; alternatively, it may be an instantiation of a generic subprogram or package.
10.1.1 With Clauses

The names that appear in a with clause must be the names of library units. The effect of the elaboration of a with clause is to create an implicit declaration of the named library units at the end of the package STANDARD; the order of these implicit declarations does not necessarily correspond to the order in which the units are named in a with clause (see 10.3 and 10.5). If the name of a library unit occurs in more than one with clause of a given context, only the first occurrence is considered.

The names of library units mentioned in with clauses are directly visible (except where hidden) within the corresponding compilation unit. In particular, the names of these library units can be used as follows:

- If the name of a generic subprogram or package is mentioned in a with clause of a compilation unit, instances of this generic program unit can be declared within the compilation unit.
- If the name of a (non generic) subprogram is mentioned in a with clause of a compilation unit, this subprogram can be called within the compilation unit.
- If the name of a (non generic) package is mentioned in a with clause of a compilation unit, this name can be used to form the names of selected components and may appear in use clauses.

With clauses define dependences among compilation units; that is, a compilation unit that mentions other library units in its with clauses depends on those library units. These dependences between units have an influence on the order of compilation (and recompilation) of compilation units, as explained in section 10.3.

Notes:
The with clauses of a compilation unit need only mention the names of those library subprograms and packages whose visibility is actually necessary within the unit. They need not (and should not) mention other library units that are used in turn by some of the units named in the with clause unless those other library units are also used directly by the compilation unit prefixed by the with clauses. For example, the implementation of the package REAL_OPERATIONS may need the operations provided by other more basic packages. The latter should not appear in the with clause of QUADRATIC_EQUATION since these basic operations are not directly called within its body.

The name of a library unit C can be written as the selected component STANDARD.C (unless the name STANDARD is hidden) since library units are implicitly declared in the package STANDARD.

References:
declaration 3, directly visible 8.3, elaboration 3.1, generic package 12.1, generic subprogram 12.1, hidden 8.3, name 3.1 4.1, package 7, package standard, program unit 7, selected component 4.1.3, subprogram 8, use clause 8.4, visibility 8
10.1.2 Examples of Compilation Units.

A compilation unit can be split into a number of compilation units. For example consider the following program:

```ada
procedure PROCESSOR is
    package D is
        LIMIT : constant := 1000;
        TABLE : array (1..LIMIT) of INTEGER;
        procedure RESTART;
    end D;

    package body D is
        procedure RESTART is
            begin
                for N in 1..LIMIT loop
                    TABLE(N) := N;
                end loop;
            end;
        begin
            RESTART;
        end D;

        procedure Q(X : INTEGER) is
            use D;
        begin
            TABLE(X) := TABLE(X) + 1;
        end Q;

        begin
            D.RESTART; -- reinitializes TABLE;
        end PROCESSOR;
    end;

    begin
        D.RESTART; -- reinitializes TABLE;
    end PROCESSOR;
end;
```

The following three compilation units define a program with an equivalent effect (the broken lines between compilation units serve to remind the reader that these units need not be contiguous texts).

Example 2: Several compilation units:

```ada
package D is
    LIMIT : constant := 1000;
    TABLE : array (1..LIMIT) of INTEGER;
    procedure RESTART;
end D;
```
package body D is
  procedure RESTART is
    begin
      for N in 1 .. LIMIT loop
        TABLE(N) := N;
      end loop;
    end;
    begin
      RESTART;
    end D;

with D;
procedure PROCESSOR is
  procedure Q(X: INTEGER) is
    use D;
    begin
      TABLE(X) := TABLE(X) + 1;
    end Q;
    begin
      D.RESTART;  -- reinitializes TABLE
    end PROCESSOR;

Note that in the latter version, the package D has no visibility of outer identifiers other than the predefined identifiers (of the package STANDARD). In particular, D does not depend on any identifier declared in PROCESSOR; otherwise D could not have been extracted from PROCESSOR in the above manner. The procedure PROCESSOR, on the other hand, depends on D and mentions this package in a with clause. This permits the inner occurrences of D in a use clause and in a selected component.

These three compilation units can be submitted in one or more compilations. For example, it is possible to submit the package specification and the package body together in a single compilation.

References:

identifier 2.3, package 7, package body 7.1, package specification 7.1, procedure 1, selected component 4.1.3, standard package C, use clause 8.4, visibility 8, with clause 10.1.1
10.2 Subunits of Compilation Units

The body of a subprogram, package, or task declared in the outermost declarative part of another compilation unit (either a library unit or a subunit) can be separately compiled and is then said to be a subunit of that compilation unit. Within the subprogram, package, or task where a subunit is declared, its body is represented by a body stub at the place where the body would otherwise appear. This method of splitting a program permits hierarchical program development.

```
subunit ::=
  separate (unit_name) body

body_stub ::=
  subprogram_specification is separate;
  | package_body_identifier is separate;
  | task_body_identifier is separate;
```

Each subunit mentions the name of its parent unit, that is, the compilation unit where the corresponding stub is given. If the parent unit is itself a subunit, this name must be given in full as a selected component, starting with the ancestor library unit. The names of all subunits of a given library unit and the names of all subunits of these subunits, and so on, must all be distinct. A generic subprogram or package can be a subunit.

Visibility within a subunit is as at the corresponding body stub; hence the name of a library unit that is named in a with clause of a parent unit is also directly visible within a subunit (except if it is hidden). The context of the subunit may mention additional library units; these names are directly visible within the subunit (except where they are hidden). For the elaboration of a subunit, this visibility is first established, then the subprogram body is elaborated.

Elaboration of a body stub has no other effect than to establish that the corresponding body is separately compiled as a subunit and to elaborate the body of the subunit.

**Note:**

The name of a library unit mentioned in the with clause of a subunit may be hidden if the same identifier is declared within the subunit, or even within one of its parents (since library units are implicitly declared in STANDARD). In such cases this does not affect the interpretation of the with clauses, themselves, since only names of library units can appear in with clauses.

Two subunits of different library units in the same program library need not have distinct identifiers. Their full names are distinct, in any case, since the names of library units are distinct and since the names of all subunits of a given library unit are also distinct. By means of renaming declarations, overloaded subprogram names that rename (distinct) subunits can be introduced.

**References:**

compilation unit 10.1, declarative part 3.9, elaboration 3.1, generic package 12.1, generic subprogram 12.1, identifier 2.3, library unit 10.1, overloading a subprogram 6.6, package body 7.1, program library 10.1 10.4, renaming declaration 8.5, selected component 4.1.3, standard package C, subprogram body 6.3, task body 9.1, visibility 8, with clause 10.1.1
10.2.1 Examples of Subunits

The procedure TOP is first written as a compilation unit without subunits.

```plaintext
with INPUT_OUTPUT;
procedure TOP is
  type REAL is digits 10;
  R, S : REAL := 1.0;

  package D is
    PI : constant := 3.14159_265358;
    function F(X : REAL) return REAL;
    procedure G(Y, Z : REAL);
  end D;

  package body D is
    -- some local declarations followed by
    function F(X : REAL) return REAL is
      begin
        -- sequence of statements of F
      end F;

    procedure G(Y, Z : REAL) is
      -- use of INPUT_OUTPUT
      begin
        -- sequence of statements of G
      end G;
  end D;

  procedure Q(U : in out REAL) is
    use D;
    begin
      U := F(U);
      --
      end Q;
  begin -- TOP
    Q(R);
    --
    D.G(R, S);
  end TOP;
```

The body of the package D and that of the procedure Q can be made into separate subunits of TOP. Similarly the body of the procedure G can be made into a subunit of D as follows.
Example 3:

```ada
procedure TOP is
    type REAL is digits 10;
    R, S : REAL := 1.0;

    package D is
        PI : constant := 3.14159_26536;
        function F (X : REAL) return REAL;
        procedure G (Y, Z : REAL);
    end D;

    package body D is separate; -- stub of D
    procedure Q (U : in out REAL) is separate; -- stub of Q
    begin -- TOP
        Q (R);
        ...
        D.G (R, S);
    end TOP;
```

```ada
separate (TOP)
procedure Q (U : in out REAL) is
    use D;
    begin
        U := F (U);
        ...
    end Q;
```

```ada
separate (TOP)
package body D is
    -- some local declarations followed by
    function F (X : REAL) return REAL is
        begin -- sequence of statements of F
            end F;

        procedure G (Y, Z : REAL) is separate; -- stub of G
    end D;
```

```ada
with INPUT_OUTPUT;
separate (TOP.D) -- full name of D
procedure G (Y, Z : REAL) is
    -- use of INPUT_OUTPUT:
    begin
        -- sequence of statements of G
    end;
```

10.2.1 Examples of Subunits
In the above example Q and D are subunits of TOP, and G is a subunit of D. The visibility in the split version is the same as in the initial version except for one change: since INPUT_OUTPUT is only used in G, the corresponding with clause appears for G instead of for TOP. Apart from this change, the same identifiers are visible at corresponding program points in the two versions. For example, the procedure TOP, the type REAL, the variables R and S, the package D and the contained constant PI and subprograms F and G are visible within the subunit body of G.

References:

constant 3.2, identifier 2.3, package 7, procedure 6, real type 3.5.6, subprogram 6, visibility 8, with clause 10.1.1

10.3 Order of Compilation

The rules defining the order in which units can be compiled are direct consequences of the visibility rules and, in particular, of the need for a given unit to see the identifiers listed in its with clauses. A unit must be compiled after all units whose names appear in one of its with clauses. A subprogram or package body must be compiled after the corresponding subprogram or package declaration. The subunits of a unit must be compiled after the unit.

The compilation units of a program can be compiled in any order that is consistent with the partial ordering defined by the above rules.

Similar rules apply for recompliations. Any change in a compilation unit may affect its subunits. In addition, any change in a library unit that is a subprogram declaration or package declaration may affect other compilation units that mention its name in their with clauses. The potentially affected units must be recompiled. An implementation may be able to reduce the compilation costs if it can deduce that some of the potentially affected units are not actually affected by the change.

The subunits of a unit can be recompiled without affecting the unit itself. Similarly, changes in a subprogram or package body do not affect other compilation units (apart from the subunits of the body) since these compilation units only have access to the subprogram or package specification. Deviations from this rule are only permitted for inline inclusions, for certain compiler optimizations, and for certain implementations of generic program units, as described below.

If a pragma INLINE is applied to the declaration of a subprogram declared in a package specification, inline inclusion will only be achieved if the package body is compiled before units calling the subprogram. In such a case, inline inclusion creates a dependence of the calling unit on the package body and the compiler must recognize this dependence when deciding on the need for recompilation. If a calling unit is compiled before the package body, the pragma may be ignored by the compiler for such calls (a warning that inline inclusion was not achieved may be issued). Similar considerations apply to a separately compiled subprogram for which an INLINE pragma is specified.

For optimization purposes, an implementation may compile several units of a given compilation in a way that creates further dependencies among these compilation units. The compiler must then take these dependencies into account when deciding on the need for recompliations. Finally an implementation may also introduce a dependence on the body of a separately compiled generic program unit.
Examples of Compilation Order:

(a) In example 2, the package body D must be compiled after the corresponding package specification.

(b) The specification of the package D must be compiled before the procedure PROCESSOR; on the other hand, the procedure PROCESSOR can be compiled either before or after the package body D.

(c) In example 1, the procedure QUADRATIC_EQUATION must be compiled after the library packages TEXT_IO and REAL_OPERATIONS since they appear in its with clause. Similarly, in example 3, the procedure G must be compiled after the package INPUT_OUTPUT, which appears in its with clause. On the other hand INPUT_OUTPUT can be compiled either before or after TOP.

(d) In example 3, the subunits Q and D must be compiled after the main program TOP. Similarly the subunit G must be compiled after its parent unit D.

References:

compilation unit 10.1, generic program unit 12, inline pragma B, library unit 10.1, name 4.1, package body 7.1, package declaration 7.1, package specification 7.1, pragma 2.8, procedure 6, subprogram body 6.3, subprogram declaration 6.1, subprogram specification 6.1, subunit 10.2, visibility rules 8, with clause 10.1.1

10.4 Program Library

Compilers must preserve the same degree of type safety, for a program consisting of several compilation units and subunits, as for a program submitted as a single compilation unit. Consequently a library file containing information on the compilation units of the program library must be maintained by the compiler. This information may include symbol tables and other information pertaining to the order of previous compilations.

A normal submission to the compiler consists of the compilation unit(s) and the library file. The latter is used for checks and is updated as a consequence of the current compilation.

There should be compiler commands for creating the program library of a given program or of a given family of programs. These commands may permit the reuse of units of other program libraries. Finally, there should be commands for interrogating the status of the units of a program library. The form of these commands is not specified by the language definition.

References:

compilation unit 10.1, library unit 10.1, subunit 10.2
10.5 Elaboration of Library Units

Before the execution of a main program, all library units used by the main program are elaborated. These library units are those which are mentioned in the with clauses of the main program and its subunits, and in the with clauses of these library units themselves, and so on, in a transitive manner.

The elaboration of these units is performed consistently with the partial ordering defined by the dependence relations imposed by with clauses (see 10.3).

The order of elaboration of library units that are package bodies must also be consistent with any dependence relations resulting from the actions performed during the elaboration of these bodies. Thus if a subprogram defined in a given package is called during the elaboration of the body of another package (that is, either during the elaboration of its declarative part or during the execution of its sequence of statements), the body of the given package must be elaborated first.

The program is illegal if no consistent order can be found (that is, if a circularity exists in the dependence relations). If there are several possible orders, the program is erroneous if it relies on a specific order (among the possible orders).

References:

- compilation unit 10.1, declarative part 3.9, dependence relation 10.1.1, elaboration 3.1, library unit 10.1, main program 10.1, package 7, package body 7.1, statement 5, subprogram 6, subunit 10.2, with clause 10.1

10.6 Program Optimization

Optimization of the elaboration of declarations and the execution of statements may be performed by compilers. In particular, a compiler may be able to optimize a program by evaluating certain expressions, in addition to those that are static expressions. Should one of these expressions (whether static or not) be such that an exception would be raised by its evaluation, then the code in that path of the program can be replaced by code to raise the exception.

A compiler may find that some statements or subprograms will never be executed, for example, if their execution depends on a condition known to be false. The corresponding code can then be omitted. This rule permits the effect of conditional compilation within the language.

Note:

An expression whose evaluation is known to raise an exception need not represent an error if it occurs in a statement or subprogram that is never executed. The compiler may warn the programmer of a potential error.

References:

- condition 5.3, declaration 3, elaboration 3.1, exception 11, expression 4.4, raise an exception 11.3, statement 5, static expression 4.9, subprogram 6
11. Exceptions

This chapter defines the facilities for dealing with errors or other exceptional situations that arise during program execution. An exception is an event that causes suspension of normal program execution. Drawing attention to the event is called raising the exception. Executing some actions, in response to the occurrence of an exception, is called handling the exception.

Exception names are introduced by exception declarations. Exceptions can be raised by raise statements, or they can be raised by subprograms, blocks, or language defined operations that propagate the exceptions. When an exception occurs, control can be passed to a user-provided exception handler at the end of a block or at the end of the body of a subprogram, package, or task.

References:
block 5.6, propagation of exception 11.4, raise statement 11.3, subprogram 6

11.1 Exception Declarations

An exception declaration defines one or more exceptions whose names can appear in raise statements and in exception handlers within the scope of the declaration.

```
exception_declaration ::= identifier_list : exception;
```

The identity of the exception introduced by an exception declaration is established at compilation time (an exception can be viewed as a constant of some predefined enumeration type, the constant being initialized with a static expression). Hence the declaration of an exception introduces only one exception, even if the declaration occurs in a recursive subprogram.

The following exceptions are predefined in the language and are raised in the following situations:

**CONTRAINT_ERROR** When a range constraint, an index constraint, or a discriminant constraint is violated. This can occur in object, type, subtype, component, subprogram, and renaming declarations; in initializations; in assignment and return statements; in component associations of aggregates; in qualified expressions, type conversions, subprogram and entry calls, and generic instantiations. This exception is also raised when an attempt is made to designate a component that cannot exist under the applicable constraint, in an indexed component, a selected component, a slice, or an aggregate. Finally, this exception is raised on an attempt to select from or index an object designated by an access value, if the access value is equal to null.
NUMERIC_ERROR When the result of a predefined numeric operation does not lie within the implemented range of the numeric type; division by zero is one such situation. This exception need not be raised by an implementation.

SELECT_ERROR When all alternatives of a select statement that has no else part are closed.

STORAGE_ERROR When the dynamic storage allocated to a task is exceeded, or during the execution of an allocator, if the available space for the collection of allocated objects is exhausted.

TASKING_ERROR When exceptions arise during intertask communication.

Examples of user-defined exception declarations:

SINGULAR : exception;
ERROR : exception;
OVERFLOW, UNDERFLOW : exception;

References:

access value 3.8, aggregate 4.3, allocator 4.8, assignment statement 5.2, component declaration 3.7, constraint 3.3, constraint_error exception 3.3 3.5.4 3.5.5 3.5.6 3.6.1 3.7 3.7.2 4.1.1 4.1.2 4.1.3 4.3 4.5.1 4.5.6 4.6 4.7 5.2 5.2.1 5.8 6.1 6.4.1 8.5 9.5 12.3.1 12.3.2 12.3.4 12.3.5 12.3.6 14.3.5, declaration 3.1, discriminant constraint 3.7.2, entry call 9.5, enumeration type 3.5.3, generic instantiation 12.3, index constraint 3.6.1, indexed component 4.1.1, initialization 3.2 3.7 6.1, name 4.1, numeric_error exception 3.5.8 4.5.3 4.5.4 4.5.5 4.5.6 4.5.7 4.5.8, numeric operation 4.5, numeric type 3.5, object declaration 3.2, qualified expression 4.7, raise statement 11.3, range constraint 3.5, recursive procedure 6.1, renaming declaration 8.5, return statement 5.8, scope of a declaration 8.2, select_error exception 9.7.1, select statement 9.7, selected component 4.1.3, slice 4.1.2, static expression 4.9, storage_error exception 3.9 4.8 13.2, subprogram call 6.4, subprogram declaration 6.1, subtype declaration 3.3, tasking_error exception 9.3 9.5 9.10 11.4, task 9.1, type conversion 4.6, type declaration 3.3

11.2 Exception Handlers

The response to one or more exceptions is specified by an exception handler. A handler may appear at the end of a unit, which must be a block or the body of a subprogram, package, or task. The word unit will have this meaning in this section.

```
exception_handler ::= 
  when exception_choice | exception_choice | others =>
  sequence_of_statements

exception_choice ::= exception_name | others
```

An exception handler of a unit handles the named exceptions when they are raised within the sequence of statements of this unit; an exception name may only occur once in the exception choices of the unit. A handler containing the choice others can only appear last and can only contain this exception choice; it handles all exceptions not listed in previous handlers, including exceptions whose names are not visible within the unit.
Exceptions

When an exception is raised during the execution of the sequence of statements of a unit, the execution of the corresponding handler (if any) replaces the execution of the remainder of the unit: the actions following the point where the exception is raised are skipped and the execution of the handler terminates the execution of the unit. If no handler is provided for the exception (either explicitly or by others), the execution of the unit is abandoned and the exception is propagated according to the rules stated in 11.4.1.

Since a handler acts as a substitute for (the remainder of) the corresponding unit, the handler has the same capabilities as the unit it replaces. For example, a handler within a function body has access to the parameters of the function and may execute a return statement on its behalf.

Example:

```
begin
  -- sequence of statements
exception
  when SINGULAR | NUMERIC_ERROR =>
    PUT(" MATRIX IS SINGULAR ");
  when others =>
    PUT(" FATAL ERROR ");
raise ERROR;
end;
```

References:

block 5.6, function 6.1, package body 7.1, parameter declaration 6.1, program unit 7, return statement 5.8, statement 5.1, subprogram body 6.3, task body 9.1, visible 8.1

11.3 Raise Statements

An exception can be raised explicitly by a raise statement.

```
raise_statement ::= raise [exception_name];
```

For the execution of a raise statement with an exception name, the identity of the exception is established, and then the exception is raised. A raise statement without an exception name can only appear in an exception handler (but not in a nested subprogram, package or task). It raises again the exception that caused transfer to the handler.

Examples:

```
raise SINGULAR;
raise NUMERIC_ERROR; -- explicitly raising a predefined exception
raise;
raise POOL(K)'FAILURE; -- see section 11.5
```

References:

name 4.1
11.4 Dynamic Association of Handlers with Exceptions

When an exception is raised, normal program execution is suspended and control is transferred to an
exception handler. The selection of this handler depends on whether the exception is raised during
the execution of statements or during the elaboration of declarations.

11.4.1 Exceptions Raised During the Execution of Statements

The handling of an exception raised during the execution of a sequence of statements depends on
the innermost block or body that encloses the statement.

(a) If an exception is raised in the sequence of statements of a subprogram body that does not
contain a handler for the exception, execution of the subprogram is abandoned and the same
exception is raised again at the point of call of the subprogram. In such a case the exception is
said to be propagated. The predefined exceptions are exceptions that can be propagated by
the language defined constructs. If the subprogram is itself the main program, the execution of
the main program is abandoned.

(b) If an exception is raised in the sequence of statements of a block that does not contain a
handler for the exception, execution of the block is abandoned and the same exception is
raised again in the unit whose sequence of statements includes the block. In such a case, also,
the exception is said to be propagated.

(c) If an exception is raised in the sequence of statements of a package body that does not contain
a handler for the exception, the elaboration of the package body is abandoned. If the package
appears in a declarative part (or is a subunit) the exception is raised again in the unit enclosing
the package body (or enclosing the body stub that corresponds to the subunit). If the package
is a library unit, the execution of the main program is abandoned.

(d) If an exception is raised in the sequence of statements of a task body that does not contain a
handler for the exception, the execution of the task is abandoned; the task is terminated. The
exception is not further propagated.

(e) If a local handler has been provided, execution of the handler replaces the execution of the
remainder of the unit (see 11.2).

(f) A further exception raised in the sequence of statements of a handler (but not in a nested block)
causes execution of the current unit to be abandoned; this further exception is propagated if
the current unit is a subprogram body, a block, or a package body as in cases (a), (b), and (c).
Example:

```pascal
procedure P is
    ERROR : exception;
    procedure R;

    procedure Q is
        begin
            R;
            exception
                ... when ERROR => handler E2
            end Q;

    procedure R is
        begin
            ... exception situation (3)
            end R;

    begin
        ... exception situation (1)
        Q;
        exception
            ... when ERROR => handler E1
        end P;
```

The following situations can arise:

1. If the exception ERROR is raised in the sequence of statements of the outer procedure P, the handler E1 provided within P is used to complete the execution of P.
2. If the exception ERROR is raised in the sequence of statements of Q, the handler E2 provided within Q is used to complete the execution of Q. Control will be returned to the point of call of Q upon completion of the handler.
3. If the exception ERROR is raised in the body of R, called by Q, the execution of R is abandoned and the same exception is raised in the body of Q. The handler E2 is then used to complete the execution of Q, as in situation (2).

Note that in the third situation, the exception raised in R results in (indirectly) passing control to a handler that is local to Q and hence not enclosed by R. Note also that if a handler were provided within R for the choice others, situation (3) would cause execution of this alternative, rather than direct termination of R.

Lastly, if ERROR had been declared in R, rather than in P, the handlers E1 and E2 could not provide an explicit handler for ERROR since this identifier would not be visible within the bodies of P and Q. In situation (3), the exception could however be handled in Q by providing a handler for the choice others.
Example:

```ada
function FACTORIAL (N : NATURAL) return FLOAT is
begin
  if N = 1 then
    return 1.0;
  else
    return FLOAT(N) * FACTORIAL(N - 1);
  end if;
exception
  when NUMERIC_ERROR => return FLOAT'LARGE;
end FACTORIAL;
```

If the multiplication raises NUMERIC_ERROR then FLOAT'LARGE is returned by the handler. This value will cause further NUMERIC_ERROR exceptions to be raised in the remaining activations of the function, so that for large values of N, the function will ultimately return the value FLOAT'LARGE.

References:

block 5.6, body 6.3 7.1, body stub 10.2, declarative part 3.9, elaboration 3.1, identifier 2.3, library unit 10.1 10.1.1, local 8.3, main program 10.1, multiplication operation 4.5.5, overflow 4.5.8, package body 7.1, procedure 8, statement 5.1, subprogram body 6.3, subprogram call 6.4, subunit 10.2, task body 9.1, visible 8.1

11.4.2 Exceptions Raised During the Elaboration of Declarations

If an exception occurs during the elaboration of the declarative part of a block or body, or during the elaboration of a subprogram, package, or task declaration, this elaboration is abandoned. The exception is propagated to the unit causing the elaboration, if there is one:

(a) An exception raised in the declarative part of a subprogram is propagated to the unit calling the subprogram, unless the subprogram is the main program itself, in which case execution of the program is abandoned.

(b) An exception raised in the declarative part of a block is propagated to the unit whose statements include the block.

(c) An exception raised in the declarative part of a package body is propagated to the unit enclosing the body (or body stub, for a subunit) unless the package is a library unit, in which case execution of the program is abandoned.

(d) An exception raised in the declarative part of a task body is propagated to the unit that caused the task activation.

(e) An exception raised during the elaboration of a subprogram, package, or task declaration is propagated to the unit enclosing this declaration, unless the subprogram or package declaration is the declaration of a library unit, in which case execution of the program is abandoned.
Example:

```declare
                 ...
begin
declare
    N : INTEGER := F();  -- F may raise ERROR
begin
    ...
    exception
        when ERROR =>  -- handler E1
    end;
    ...
    exception
        when ERROR =>  -- handler E2
    end;

    -- if the exception ERROR is raised in the declaration of N, it is handled by E2
```

References:

body 6.3 7.1, body stub 10.2, declaration 3.1, declarative part of block 5.6, elaboration of declaration 3.1 3.9, library unit 10.1.1, main program 10.1, package body 7.1, package declaration 7.1, program unit 7, statement 5, subprogram declaration 6.1, subunit 10.2, task activation 9.3, task declaration 9.1 11.5

11.5 Exceptions Raised During Task Communication

An exception can be propagated to a task communicating, or attempting to communicate, with another task.

When a task calls an entry of another task, the exception TASKING_ERROR is raised in the calling task, at the place of the call, if the called task terminates before accepting the entry call or is already terminated at the time of the call.

A rendezvous can be terminated abnormally in two cases:

(a) When an exception is raised inside an accept statement and not handled locally. In this case, the exception is propagated both to the unit containing the accept statement, and to the calling task at the point of the entry call.

A different treatment is used for the special exception attribute FAILURE as explained in section 11.6 below.

(b) When the task containing the accept statement is terminated abnormally (for example, as the result of an abort statement). In this case, the exception TASKING_ERROR is raised in the calling task at the point of the entry call.

On the other hand, abnormal termination of a task issuing an entry call does not raise an exception in the called task. If the rendezvous has not yet started, the entry call is cancelled. If the rendezvous is in progress, it is allowed to complete, and the called task is unaffected.
11.6 Raising the Exception Failure in Another Task

Each task has an attribute named FAILURE which is an exception. Any task can raise the FAILURE exception of another task (say T) by the statement

```
raise T'FAILURE;
```

The execution of this statement has no direct effect on the task issuing the statement (unless, of course, it raises FAILURE for itself). This exception is the only exception that can be raised explicitly by one task in another task.

For the task receiving the FAILURE exception, this exception is raised at the current point of execution, whether the task is actually executing or suspended. If the task is suspended on a delay statement, the corresponding wait is cancelled. If the task has issued an entry call (or a timed entry call) the call is cancelled if the rendezvous has not yet started; alternatively the rendezvous is allowed to complete if it has already started; in both cases the called task is unaffected. If the task is suspended by an accept or select statement, execution of the task is scheduled (according to the usual priority rules, see 9.8) in order to allow the exception to be handled. Finally, if the exception FAILURE is received within an accept statement and not handled locally, the rendezvous is terminated and the exception TASKING_ERROR is raised in the calling task at the place of the entry call.

Within the body of a task or task type T (and only there) there may be handlers for the exception name T'FAILURE.

Note:

The name FAILURE is not reserved. Hence it could be declared as any entity, including an exception. No conflict can arise with the attribute FAILURE because of the distinct notation for attributes.

References:

accept statement 9.5, entry 9.5, entry call 9.5, rendezvous 9.5, task 9.1, task termination 9.3 9.4

11.7 Suppressing Exceptions

The detection of the conditions under which some predefined exceptions are raised (as a preliminary to raising them) may be suppressed within a block or within the body of a subprogram, package, or task. This suppression may be achieved by the insertion of a SUPPRESS pragma in the declarative part of such a unit. The form of this pragma is as follows:

```
pragma SUPPRESS (check_name [, [C|N => ] name]);
```
The first name designates the check to be suppressed; the second name is optional and may be either an object name or a type name. In the absence of the optional name, the pragma applies to all operations within the unit considered. Otherwise its effect is restricted to operations on the named object or to operations on objects of the named type.

The following checks correspond to situations in which the exception CONSTRAINT_ERROR may be raised:

**ACCESS_CHECK**
Check that an access value is not null when attempting to select from or index the object designated by the access value.

**DISCRIMINANT_CHECK**
When accessing a record component, check that it exists for the current discriminant value. Check that a value specified for a discriminant satisfies or is compatible with a discriminant constraint.

**INDEX_CHECK**
Check that a specified index value or range of index values satisfies an index constraint or is compatible with an index type.

**LENGTH_CHECK**
Check that the number of components for an index is equal to a required number.

**RANGE_CHECK**
Check that a value satisfies a range constraint or that an index constraint, discriminant constraint, or range constraint is compatible with a type mark.

The following checks correspond to situations under which the exception NUMERIC_ERROR is raised:

**DIVISION_CHECK**
Check that the second operand is not zero for the operations /, rem and mod.

**OVERFLOW_CHECK**
Check that the result of a numeric operation does not overflow.

The following checks correspond to situations under which the system STORAGE_ERROR is raised:

**STORAGE_CHECK**
Check that execution of an allocator does not require more space than is available for a collection. Check that the space available for a task or program unit has not been exceeded.

The SUPPRESS pragma indicates that the corresponding run time check need not be provided. The occurrence of such a pragma within a given unit does not guarantee that the corresponding exceptions will not arise, since the pragma is merely a recommendation to the compiler, and since the exceptions may be propagated by called units. Should an exception situation occur when the corresponding run time checks are suppressed, the program would be erroneous (the results would be unpredictable).

**Examples:**

```
pragma SUPPRESS(RANGE_CHECK);
pragma SUPPRESS(INDEX_CHECK, OK => TABLE);
```
Note:

For certain implementations, it may be impossible, or too costly to suppress certain checks. The corresponding SUPPRESS pragmas can be ignored.

References:

access value 3.8, array component 3.6, assignment statement 5.2, block 5.6, declarative part 3.9, division operation 4.5.5, index range 3.6, mod operator 4.5.5, name 4.1, object name 3.2, overflow 3.5.8 4.5.8, package body 7.1, pragma 2.8, record component 3.7, record discriminant 3.7.1, rem operator 4.5.6, subprogram body 6.3, task body 9.1, type declaration 3, type name 3.3

11.8 Exceptions and Optimization

The purpose of this section is to specify the conditions under which certain operations can be invoked either earlier or later than indicated by the exact place in which their invocation occurs in the program text. The operations concerned comprise any function (including operators) whose value depends only on the values of its arguments (the actual parameters) but which raises an exception for certain argument values (this exception depending only on the value of the arguments). Other operations also included are the basic operations involved in array indexing, slicing, and component selection, including the case of objects designated by access values.

If it were not for the fact that these operations may propagate exceptions, they could be invoked as soon as the values of their arguments were known, since the value returned depends only on the argument values. However the possible occurrence of exceptions imposes stricter limits upon the allowable displacements of the points where such operations are invoked as explained below:

- Consider the statements and expressions contained in the sequence of statements of a block, body, or accept statement (but excluding any nested inner block, body, or accept statement). For a given operation, choose a subset of these statements and expressions such that if any statement (or expression) in the subset is executed (or evaluated), one or more invocations of the given operation is required (according to rules stated elsewhere than in this section). Then, within the chosen subset the operation can be invoked as soon as the values of its arguments are known, even if this invocation may cause an exception to be propagated. The operation need not be invoked at all if its value is not needed, even if the invocation would raise an exception. If the operation may raise an exception and if the value is needed, the invocation must occur no later than the end of the sequence of statements of the enclosing block, body or accept statement.

- The rules given in section 4.5 for operators and expression evaluation leave the order of evaluation of the arguments of such operations undefined except for short circuit control forms. Also, in the case of a sequence of operators of the same precedence level (and in the absence of parentheses imposing a specific order), these rules allow any order of evaluation that yields the same result as the textual (left to right) order. Any reordering of evaluation allowed by these rules is permitted even if some of the operations may propagate exceptions, as long as no further exception can be introduced.
Notes:

The above rules guarantee that an operation is not moved across a return, an exit, a goto, a raise, or an abort statement. Moreover, an optimization cannot move an operation in such a way that an exception would be handled by a different handler.

Whenever the evaluation of an expression may raise an exception for an allowed order of evaluation, it is the programmer's responsibility to impose a specific order by explicit parentheses. In their absence, a compiler is allowed to choose any order satisfying the above rules, even if this order removes the risk of an exception being raised. In addition, the code produced by different compilers may raise different exceptions for a given expression since the order of evaluation of arguments is not defined.

References:

accept statement 9.5, access value 3.8, actual parameter 6.4, array indexing 4.1.1, block 5.6, body 6.3 7.1, expression 4.4, expression evaluation 4.5, function 6.1, operator 4.5, propagation of exception 11.4.1, selected component 4.1.3, slice 4.1.2, statement 5
12. Generic Program Units

Subprograms and packages can be generic. Generic program units are templates of program units and are often parameterized. Being templates, they cannot be used directly as ordinary subprograms or packages; for example, a generic subprogram cannot be called. Instances (that is, copies) of the template are obtained by generic instantiation. The resulting subprograms and packages are ordinary program units, which can be used directly.

A generic subprogram or package is defined by a generic declaration. This form of declaration has a generic part, which may include the definition of generic formal parameters. An instance of a generic unit, with appropriate actual parameters for the generic formal parameters, is obtained as the result of a generic subprogram instantiation or a generic package instantiation.

References:

declaration 3.1, generic actual parameter 12.3, generic declaration 12.1, generic formal parameter 12.1, generic part 12.1, package 7, program unit 6 7 9, subprogram 6,

12.1 Generic Declarations

A generic declaration includes a generic part and declares a generic subprogram or a generic package. The generic part may include the definition of generic parameters.

For the elaboration of a generic declaration, the subprogram designator or package identifier is first introduced and can from then on be used as the name of the corresponding generic program unit. The generic part is next elaborated. Finally, the subprogram or package specification is established as the template for the specification of the corresponding generic program unit.

```plaintext
generic_subprogram_declaration ::= 
generic_part subprogram_specification;

generic_package_declaration ::= 
generic_part package_specification;

generic_part ::= generic (generic_formal_parameter)

generic_formal_parameter ::= 
parameter_declaration;
| type identifier [discriminant_part] is generic_type_definition;
| with subprogram_specification [is name];
| with subprogram_specification is <>;

generic_type_definition ::= 
(<> | range <> | delta <> | digits <>
| array_type_definition | access_type_definition
| private_type_definition

Generic Declarations 12.1
```
For the elaboration of a generic part, the generic formal parameters (if any) are elaborated one by one in the given order. A generic parameter may only be referred to by another generic parameter of the same generic part if it (the former parameter) is a type and appears first.

Expressions appearing in a generic part are evaluated during the elaboration of the generic part, excepting any primary referring to a type that is a generic parameter (for example, an attribute of such a type); such primaries are evaluated during the elaboration of generic instantiations.

References to generic parameters of any form (not only types) may occur in the specification and body of a generic subprogram or package. However neither a choice, nor an integer type definition, nor an accuracy constraint, may depend on a generic formal parameter.

Examples of generic parts:

```
generic -- parameterless

generic
  SIZE : NATURAL;

generic
  LENGTH : INTEGER = 200; -- default value

generic
  type ENUM is (<>);
  with function IMAGE (E : ENUM) return STRING is ENUM'IMAGE;
  with function VALUE (S : STRING) return ENUM is ENUM'VALUE;
```

Examples of generic subprogram declarations:

```
generic
type ELEM is private;
procedure EXCHANGE (U, V : in out ELEM);

generic
type ITEM is private;
  with function "*" (U, V : ITEM) return ITEM is <>;
  function SQUARING (X : ITEM) return ITEM;
```

Example of generic package declaration.

```
generic
  type ITEM is private;
  type VECTOR is array (INTEGER range <>) of ITEM;
  with function SUM (X, Y : ITEM) return ITEM;
package ON_VECTORS is
  function SUM (A, B : VECTOR) return VECTOR;
  function SIGMA (A : VECTOR) return ITEM;
end;
```

Note:

A subprogram or package specification given in a generic declaration is the template for the specifications of the corresponding subprograms or packages obtained by generic instantiation. Hence the template specification is not elaborated during elaboration of the generic declaration (this specification is merely established as being the template specification). The subprogram or package specification obtained by instantiation of the generic program unit is elaborated as part of this instantiation.

12.1 Generic Declarations
When a template is established all names occurring within it must be identified in the context of the
generic declaration.

References:
accuracy constraint 3.5.6, attribute 4.1.4, designator 6.1, elaboration 3.1, expression 4.4, identifier 2.3,
integer type definition 3.5.4, name 4.1, object 3.2, package 7, package identifier 7.1, package specification
7.1, primary 4.4, program unit 7, subprogram 6.1, subprogram specification 6.1, type 3.3

12.1.1 Parameter Declarations in Generic Parts

The usual forms of parameter declarations available for subprogram specifications can also appear in
generic parts. Only the modes in and in out are allowed (the mode out is not allowed for generic
parameters). If no mode is explicitly given, the mode in is assumed.

A generic parameter of mode in acts as a constant; its value is a copy of the value provided by the
corresponding generic actual parameter in a generic instantiation.

A generic parameter of mode in out acts as an object name renaming the corresponding generic
actual parameter supplied in a generic instantiation. This actual parameter must be a variable of a
type for which assignment is available (in particular, it cannot be a limited private type). The actual
parameter cannot be a component of an unconstrained object with discriminants, if the existence of
the component depends on the value of a discriminant.

References:
assignment 5.2, constant 3.2, generic actual parameter 12.3, in mode 6.1, in out mode 6.1, object name 3.2,
out mode 6.1, parameter declaration 6.1, subprogram specification 6, type 3.3

12.1.2 Generic Type Definitions

The elaboration of a generic formal parameter containing a generic type definition proceeds
according to the same rules as that of a type declaration (see 3.3). Generic type definitions may be
array, access, or private type definitions, or one of the forms including a box (that is, the compound
symbol <>).

Within the specification and body of a generic program unit, the operations available on values of a
generic formal type are those associated with the corresponding generic type definition, together with
array given by generic formal subprograms.

For an array type definition, the usual operations on arrays (such as indexing, slicing, assignment,
equality, and so on), and the notation for aggregates, are available. For an access type definition, the
usual operations on access types are available; for example allocators can be used.

Generic Type Definitions 12.1.2
For a limited private type no operation is available; for a private type, assignment, equality and inequality are available. Additional operations can be supplied as generic formal subprograms. The only form of constraint applicable to a generic formal type that is a (limited) private type is a discriminant constraint in the case where the generic formal parameter includes a discriminant part.

The generic type definitions including a box correspond to the major forms of scalar types:

<table>
<thead>
<tr>
<th>Syntactic Form</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>(&lt;&gt;)</td>
<td>any discrete type</td>
</tr>
<tr>
<td>range &lt;&gt;</td>
<td>any integer type</td>
</tr>
<tr>
<td>digits &lt;&gt;</td>
<td>any floating point type</td>
</tr>
<tr>
<td>delta &lt;&gt;</td>
<td>any fixed point type</td>
</tr>
</tbody>
</table>

For each generic formal type declared with one of these forms, the predefined operators and the function ABS of the corresponding scalar type are available (see 4.5). The attributes defined for the corresponding scalar types (see 3.5) are also available, excepting the attributes IMAGE and VALUE (see appendix A).

Examples of generic formal types

```ada
type ITEM is private;
type BUFFER(LENGTH : NATURAL) is limited private;
type ENUM is (<>);
type INT is range <>;
type ANGLE is delta <>;
type MASS is digits <>;
type TABLE is array (ENUM) of ITEM;
```

Notes:

Since the attributes IMAGE and VALUE are not already available for the generic type definitions including a box, extra generic formal suborograms must be supplied for these attributes where they are needed.

References:

abs function 4.5.7, access type definition 3.8, aggregate notation 4.3, allocator 4.8, array type definition 3.6, array operations 4.5, assignment 5.2, attribute 4.1.4, constraint 3.3, discriminant constraint 3.7.2, discriminant part 3.7.1, elaboration 3.1, equality 4.5.2, formal parameter 6.4, image attribute A, incomplete access type predeclaration 3.8, indexing 3.6.1, inequality 4.5.2, limited private type 7.4.2, predefined operators C, private type definition 7.4, scalar type 3.5, slicing 4.1.2, subprogram 6.1, type declaration 3.3, value attribute A

12.1.3 Generic Formal Subprograms

A generic formal parameter that includes a subprogram specification defines a generic formal subprogram. Such subprograms may have (non generic) parameters and results of any visible type, including types that are previously declared generic formal types.
If the subprogram specification is followed by the reserved word is and by either a name or a box, an actual parameter is optional for this generic formal subprogram. If a name is used, the named subprogram is used by default in any generic instantiation that does not contain an explicit actual parameter for this generic formal subprogram. If a box is used, a default actual subprogram that matches the specification of the generic formal subprogram may be selected at the point of generic instantiation (see 12.3.6).

For the elaboration of a generic formal parameter that includes a subprogram specification, the subprogram specification is first elaborated: this elaboration introduces the names of any parameters and identifies the corresponding types (which may be generic types). The identity of any name that follows the reserved word is is then established (it may be an attribute of a generic type). This subprogram name must match the subprogram specification according to the rules given in section 12.3.6.

Examples of generic formal subprograms:

- with function INCREASE(X : INTEGER) return INTEGER;
- with function SUM(X, Y : ITEM) return ITEM;
- with function "+"(X, Y : ITEM) return ITEM is <>;
- with function IMAGE(X : ENUM) return STRING is ENUM'IMAGE;
- with procedure UPDATE is DEFAULT_UPDATE;

References:

- generic actual parameter 12.3, name 4.1, parameter 6.1, subprogram declaration 6.1, subprogram specification 6.1, type 3.3, visible 8.1

12.2 Generic Bodies

The body of a generic subprogram or package is a template for the bodies of the corresponding program units obtained by generic instantiation. The only effect of the elaboration of a generic body is to establish this body as the template to be used for the corresponding instantiations.

Examples of generic subprogram bodies:

- procedure EXCHANGE(U, V : in out ELEM) is
  
  T : ELEM; -- the generic formal type

  begin
  T := U; U := V; V := T;
  end EXCHANGE;

- function SQUARING(X : ITEM) return ITEM is
  
  begin
  return X*X; -- the formal operator "*"
  end;
Example of a generic package body:

```ada
package body ON_VECTORS is
  function SUM(A, B : VECTOR) return VECTOR is
    RESULT : VECTOR(A'RANGE); -- the formal type VECTOR
    begin
      for N in A'RANGE loop
        RESULT(N) := SUM(A(N), B(N)); -- the formal function SUM
      end loop;
      return RESULT;
    end;
  function SIGMA(A : VECTOR) return ITEM is
    TOTAL : ITEM := A(A'FIRST); -- the formal type ITEM
    begin
      for N in A'FIRST + 1 .. A'LAST loop
        TOTAL := SUM(TOTAL, A(N)); -- the formal function SUM
      end loop;
      return TOTAL;
    end;
end;
```

References:

elaboration 3.1 3.9, package 7, program unit 7, subprogram 6

12.3 Generic Instantiation

An instance of a generic program unit is obtained as the result of the elaboration of a generic subprogram instantiation or package instantiation.

```
generic_subprogram_instantiation ::= 
  procedure identifier is generic_instantiation;
  | function designator is generic_instantiation;

generic_package_instantiation ::= 
  package identifier is generic_instantiation;

generic_instantiation ::= 
  new name [(generic_association ( generic_association )]]

generic_association ::= 
  [formal_parameter =>] generic_actual_parameter

generic_actual_parameter ::= 
  expression | subprogram_name | subtype_indication
```

A generic actual parameter must be supplied for each generic formal parameter unless the corresponding generic part allows a default to be used. Generic associations can be given in positional form or in named form as for subprogram calls (see 6.4). Each generic actual parameter must match the corresponding generic formal parameter. An object matches an object; a subprogram or an entry matches a subprogram; a type matches a type. The detailed matching rules are given in subsections below.

12.3 Generic Instantiation
For the elaboration of a generic subprogram instantiation or package instantiation, the designator of the procedure or function, or the identifier of the package is first introduced, and the generic instantiation is then elaborated. The designator or identifier can be used as the name of the instantiated unit from then on.

The elaboration of a generic instantiation first creates an instance of the template defined by the generic program unit, by replacing every occurrence of a generic formal parameter in both the specification and body of the unit by the corresponding generic actual parameter. This instance is a subprogram or package whose specification and body are then elaborated in this order according to the usual elaboration rules applicable to such entities (see 6.1 and 6.3 for subprograms, 7.2 and 7.3 for packages). Note however, that any identifier other than a generic parameter and which occurs within the generic declaration or body names an entity which is visible at the point where it occurs with the generic declaration or body (not at the point of instantiation).

Examples of generic instantiations:

```
procedure SWAP is new EXCHANGE(ELEM => INTEGER);
procedure SWAP is new EXCHANGE(CHARACTER);   -- SWAP is overloaded

function SQUARE is new SQUARING(INTEGER);   -- "*" of INTEGER used by default
function SQUARE is new SQUARING(MATRIX, MATRIX_PRODUCT);

package INT_VECTORS is new ON_VECTORS(INTEGER, TABLE, "+");
```

Examples of uses of instantiated units:

```
SWAP(A, B);
A := SQUARE(A);

T : TABLE(1..5) := (10, 20, 30, 40, 50);
N : INTEGER := INT_VECTORS.SIGMA(T);   -- 150

use INT_VECTORS;
```

References:


12.3.1 Matching Rules for Formal Objects

An expression of a given type matches a generic formal parameter of the same type; it must satisfy any constraint imposed on the generic formal parameter otherwise the exception CONSTRAINT_ERROR is raised by the generic instantiation.
An expression used as a generic actual parameter of mode in out must be a variable name (an
expression that is a type conversion is not allowed as a generic actual parameter if the mode is in
out).

References:

constraint 3.3, constraint_error exception 11.1, expression 4.4, in out mode 6.1, type 3.3, type conversion
4.6, variable name 4

12.3.2 Matching Rules for Formal Private Types

A generic formal private type is matched by any type other than an unconstrained array type, in the
following conditions:

- If the formal type is limited, the actual type can be any type (including a task type); if the formal
type is not limited, assignment and the comparison for equality or inequality must be available
for the actual type.

- If the formal type has a discriminant part, the actual type must have the same discriminants: the
discriminant names, subtypes, and any default values must be the same and in the same order.
The exception CONSTRAINT_ERROR is raised at the place of the generic instantiation if the
constraint or default values differ.

References:

assignment 5.2, constraint 3.3, constraint_error exception 11.1, discriminant part 3.7.1, equality 4.5.2,
inequality 4.5.2, limited generic formal type 12.1.2, subtype 3.3, task type 9.1, type 3.3, unconstrained array
type 3.6

12.3.3 Matching Rules for Formal Scalar Types

A generic formal type defined by (<> in) is matched by any discrete type (that is, any enumeration or
integer type. A generic formal type defined by range <> is matched by any integer type. A generic
formal type defined by digits <> is matched by any floating point type. A generic formal type defined
by delta <> is matched by any fixed point type. No other matches are possible for these generic
formal types.

References:

delta 3.5.9, digits 3.5.7, discrete type 3.5 3.5.5, enumeration type 3.5.1, fixed point type 3.5.9, floating point
type 3.5.7, integer type 3.5.4

12.3.3 Matching Rules for Formal Scalar Types
12.3.4 Matching Rules for Formal Array Types

A formal array type is matched by an actual array type with the same number of indices.

If any of the index and component types of the formal array type is itself a formal type, its name is replaced by the name of the corresponding actual type. All such substitutions having been achieved, a formal array type is matched by an actual array type if the following conditions are satisfied:

- The component type and constraint must be the same for the formal array type as for the actual array type.
- For each index position, the index subtype must be the same for the formal array type as for the actual array type.
- Either both array types must be unconstrained or, for each index position, the index constraint must be the same for the formal array type as for the actual array type.

The exception CONSTRAINT_ERROR is raised during the elaboration of a generic instantiation if the constraints on the component type are not the same, or if the index subtype, or the index constraint for any given index position are not the same for the formal array type as for the actual array type.

Example

```pascal
-- given the generic package

generic
  type ELEM is private;
  type INDEX is (< >);
  type VECTOR is array (INDEX range < >) of ELEM;
  type TABLE is array (INDEX) of ELEM;
package P is
...
end;
-- and the types

type MIX is array (COLOR range < >) of BOOLEAN;
type OPTION is array (COLOR) of BOOLEAN;
-- then MIX can match VECTOR and OPTION can match TABLE
-- but not the other way round:

package Q is new P(ELEM => BOOLEAN, INDEX => COLOR,
  VECTOR => MIX, TABLE => OPTION);
```

References:

array 3.6, array index 3.6, component type 3.6, constraint 3.3, constraint_error exception 11.1, unconstrained array type 3.6
12.3.5 Matching Rules for Formal Access Types

If the type of the objects designated by values of the formal access type is itself a formal type, its name is replaced by the name of the corresponding actual type. Any such substitution having been achieved, a formal access type is matched by an actual access type if the type of the designated objects is the same in both the formal and the actual access types.

If a constraint is specified in the generic type definition for the type of the objects designated by the access type, the same constraint must exist for the actual access type, otherwise the exception CONSTRAINT_ERROR is raised at the place of the generic instantiation.

Example:

```ada
-- the formal types

generic
  type NODE is private;
  type LINK is access NODE;
package P is
...
end;
-- can be matched by the actual types

type CAR;
type CAR_NAME is access CAR;

type CAR is
  record
    PRED, SUCC : CAR_NAME;
    NUMBER : LICENSE_NUMBER;
    OWNER : PERSON;
  end record;

-- in the generic instantiation

package R is new P(NODE => CAR, LINK => CAR_NAME);
```

References:

access type 3.8, constraint 3.3, constraint_error exception 11.1, object 3.2, type 3.3

12.3.6 Matching Rules for Formal Subprograms

Any occurrence of the name of a formal type in the formal subprogram specification is replaced by the name of the corresponding actual type or subtype. Any such substitution having been achieved, a formal subprogram is matched by an actual subprogram that has parameters in the same order, of the same mode and type, and with the same constraints. For functions, the result type and constraints must be the same. Parameter names and the presence or absence of default values are ignored for this matching. Should any constraint not match, the exception CONSTRAINT_ERROR is raised at the place of the generic instantiation.
If a box appears after the reserved word is in the definition of the generic formal subprogram, the corresponding actual subprogram can be omitted if a subprogram with the same designator and with a matching specification is visible at the place of the generic instantiation; this subprogram (there must only be one) is then used by default.

Example:

```
-- given the generic function specification

generic
    type ITEM is private;
    with function "x" (U, V : ITEM) return ITEM is <>;
    function SQUARING(X : ITEM) return ITEM;

-- and the function

function MATRIX_PRODUCT(A, B : MATRIX) return MATRIX;

-- the following instantiations are possible

function SQUARE is new SQUARING(MATRIX, MATRIX_PRODUCT);
function SQUARE is new SQUARING(INTEGER, "x");
function SQUARE is new SQUARING(INTEGER);

-- the last two instantiations are equivalent

Note:
The matching rule for formal subprograms is the same as the matching rule given for subprogram renaming declarations (see 8.5).

References:

12.3.7 Matching Rules for Actual Derived Types

A formal generic type cannot be a derived type. On the other hand, an actual type may be a derived type, in which case the matching rules are the same as if its type were the actual type, subject to any constraints imposed on the derived type.

References:
constraint 3.3, derived type 3.4, parent type 3.4
12.4 Example of a Generic Package

The following example provides a possible formulation of stacks by means of a generic package. The size of each stack and the type of the stack elements are provided as generic parameters.

```ada
generic
  SIZE: NATURAL;
  type ELEM is private;
package STACK is
  procedure PUSH(E: in ELEM);
  procedure POP(E: out ELEM);
  OVERFLOW, UNDERFLOW: exception;
end STACK;

package body STACK is
  SPACE: array (1..SIZE) of ELEM;
  INDEX: INTEGER range 0..SIZE := 0;

procedure PUSH(E: in ELEM) is
  begin
    if INDEX = SIZE then
      raise OVERFLOW;
    end if;
    INDEX := INDEX + 1;
    SPACE(INDEX) := E;
  end PUSH;

procedure POP(E: out ELEM) is
  begin
    if INDEX = 0 then
      raise UNDERFLOW;
    end if;
    E := SPACE(INDEX);
    INDEX := INDEX - 1;
  end POP;
end STACK;
```

Instances of this generic package can be obtained as follows:

```ada
package STACK_INT is new STACK(SIZE => 200, ELEM => INTEGER);
package STACK_BOOL is new STACK(100, BOOLEAN);
```

Thereafter, the procedures of the instantiated packages can be called as follows:

```ada
STACK_INT.PUSH(N);
STACK_BOOL.PUSH(TRUE);
```
Alternatively, a generic formulation of the type STACK can be given as follows (package body omitted):

```
generic
type ELEM is private;
package ON_STACKS is
type STACK(SIZE : NATURAL) is limited private;
procedure PUSH(S : in out STACK; E : in ELEM);
procedure POP (S : in out STACK; E : out ELEM);
OVERFLOW, UNDERFLOW : exception
private
type STACK(SIZE : NATURAL) is
  record
    SPACE : array(1 .. SIZE) of ELEM;
    INDEX : INTEGER range 0 .. INTEGER'LAST := 0;
  end record;
end;
```

In order to use such a package an instantiation must be created and thereafter stacks of the corresponding type can be declared:

```
declare
  package STACK_INT is new ON_STACKS(INTEGER); use STACK_INT;
  S : STACK(100);
begin
  PUSH(S, 20);
  ...
end;
```
13. Representation Specifications and Implementation Dependent Features

13.1 Representation Specifications

Representation specifications specify how the types of the language are to be mapped onto the underlying machine. Mappings acceptable to an implementation do not alter the net effect of a program. They can be provided to give more efficient representation, or to interface with features that are outside the domain of the language (for example, peripheral hardware).

\[
\text{representation specification ::= length specification I enumeration type representation}
\]

\[
| \text{record type representation I address specification}
\]

Representation specifications may appear in a declarative part, after the list of declarative items, and can only apply to items declared in the same declarative part. A representation specification given for a type applies to all objects of the type. For a given type, more than one representation specification can be given if and only if they specify different aspects of the representation. Thus for an enumeration type, both a length specification and an enumeration type representation can be given (but of course, at most one of each kind).

Representation specifications may also appear in package specifications and task specifications. A representation specification given in the private part of a package specification may only apply to an item declared in either the visible part or the private part of the package. A representation specification given in a task specification may only apply to an entry of the task (type) or to the task (type) itself.

In the absence of explicit representation specifications for a particular item, its representation is determined by the compiler.

The representation specifications in a declarative part, package specification, or task specification are elaborated in the order in which they appear. The effect of the elaboration of a representation specification is to define the corresponding representation and any consequent representation attribute (see 13.7). Any reference to such an attribute assumes that the choice of a representation has already been made, either explicitly by a specification, or by default by the compiler. Consequently a representation specification for a given entity must not appear after an occurrence of a representation attribute of this entity, nor may the specification mention such an attribute.

No representation specification may be given for a type derived from an access type. The only allowable representation specification for a type (other than an access type) that has derived user defined subprograms from its parent type is a length specification.
The interpretation of some of the expressions appearing in representation specifications may be implementation dependent, for example, expressions specifying addresses. An implementation may limit representation specifications to those that can be handled simply by the underlying hardware. For each implementation, the corresponding implementation dependences must be documented in Appendix F of the reference manual.

Whereas representation specifications are used to specify a mapping completely, pragmas can be used to provide criteria for choosing a mapping. The pragma PACK specifies that storage minimization should be the main criterion when selecting the representation of a record or array type. Its form is as follows:

    pragma PACK(type_name);

Packing means that gaps between the storage areas allocated to consecutive components should be minimized. It does not, however, affect the mapping of each component onto storage. This mapping can only be influenced (or controlled) by a pragma (or representation specification) for the component or component type. The position of a PACK pragma is governed by the same rules as for a representation specification; in particular, it must appear before any use of a representation attribute of the packed entity.

Additional representation pragmas may be provided by an implementation; these must be documented in Appendix F.

References:

- access type 3.8, array type 3.8, declarative item 3.9, declarative part 3.9, derived type 3.4, elaboration 3.1, entry 9.5, enumeration type 3.5.1, expression 4.4, object 3.2, package 7, package specification 7.1, parent type 3.4, pragma 2.8, private part 7.2, record type 3.7, subprogram 6, task specification 9.1, type 3, visible part 7.2

### 13.2 Length Specifications

A length specification controls the amount of storage associated with an entity.

    length_specification ::= for attribute use expression;

The expression must be of some integer type; it is evaluated during the elaboration of the length specification, unless it is a static expression. The effect of the length specification depends on the attribute given. This must be an attribute of a type (task types included), or of a task, denoted here by T:

(a) Size specification: T\(^\ast\)SIZE

The type T can be any type, other than a task type. The expression must be a static expression of some integer type; its value specifies the maximum number of bits to be allocated to objects of the type T. This number must be at least equal to the minimum number needed for the representation of objects of this type.
A size specification for a composite type may affect the size of the gaps between the storage areas allocated to consecutive components. On the other hand, it does not affect the size of the storage area allocated to each component.

Size specifications are not allowed for types whose constraints are not static.

(b) **Specification of collection size: T'\text{STORAGE\_SIZE}**

The type T must be an access type. The expression must be of some integer type (but need not be static); its value specifies the number of storage units to be reserved for the collection, that is, the storage space needed to contain all objects designated by values of the access type.

(c) **Specification of task storage: T'\text{STORAGE\_SIZE}**

The name T must be the name of a task type or task, introduced by a task specification. The expression must be of some integer type (but need not be static); its value specifies the number of storage units to be reserved for an activation of a task of the type (or for the single task). This length specification has, of course, no effect on the size of the storage occupied by the code of the task type.

(d) **Specification of an actual delta: T'\text{ACTUAL\_DELTA}**

The type T must be a fixed point type. The expression must be a literal expression expressing a real value. This value specified as actual delta must not be greater than the delta of the type. The effect of the length specification is to use this value of actual delta for the representation of values of the fixed point type.

The exception \text{STORAGE\_ERROR} may be raised by an allocator, or by the execution of a task, if the space reserved is exceeded.

**Examples:**

```
-- assumed declarations

type MEDIUM is range 0 .. 65000;
type SHORT is delta 0.01 range -100.0 .. 100.0;
type DEGREE is delta 0.1 range -360.0 .. 360.0;

BYTE : constant := 8;
PAGE : constant := 2000;

-- length specifications

for COLOR'SIZE use 1*BYTE;
for MEDIUM'SIZE use 2*BYTE;
for SHORT'SIZE use 15;

for CAR\_NAME\_STORAGE\_SIZE use -- approximately 2000 cars
2000+((\text{CAR\_SIZE}/\text{SYSTEM\_STORAGE\_UNIT}) + 1);

for KEYBOARD\_DRIVER\_STORAGE\_SIZE use 1*PAGE;

for DEGREE\_ACTUAL\_DELTA use 360.0/2**\text{SYSTEM\_STORAGE\_UNIT} - 2);
```
Notes:

In the length specification for SHORT, fifteen bits is the minimum necessary, since the type definition requires at least 20100 model numbers ((2*100) + 1)*100).

Objects allocated in a collection need not occupy the same amount of storage if they are records with variants or dynamic arrays. Note also that the allocator itself may require some space for internal tables and links. Hence a length specification for the collection of an access type does not always give precise control over the maximum number of allocated objects.

The method of allocation for objects denoted by an access type or for tasks is not defined by a length specification. For example, the space allocated could be on a stack; alternatively, a general allocator or fixed storage could be used.

References:

access type 3.8, actual delta 3.5.9, allocator 4.8, collection 3.8, delta 3.5.9, composite type 3.7, dynamic array 3.6.1, elaboration 3.1, expression 4.4, fixed point type 3.5.9, integer type 3.5.4, literal expression 4.10, object 3.2, real value 3.5.6, record 3.7, static expression 4.9, storage_error exception 11.1, task 9, task type 9, type 3, variant 3.7.1

13.3 Enumeration Type Representations

An enumeration type representation specifies the internal codes for the literals of an enumeration type.

```
enumeration_type_representation :: = for type_name use aggregate;
```

The aggregate used to specify this mapping is an array aggregate of type

```
array (type_name) of universal_integer
```

All enumeration literals must be provided with distinct integer codes, and the aggregate must be a static expression. The integer codes specified for the enumeration type must satisfy the ordering relation of the type.

Example:

```
type MIX_CODE is (ADD, SUB, MUL, LDA, STA, STZ);
for MIX_CODE use
  (ADD => 1, SUB => 2, MUL => 3, LDA => 8, STA => 24, STZ => 33);
```

Notes:

The attributes SUCC, PRED, and POS are defined even for enumeration types with a non-contiguous representation; their definition corresponds to the (logical) type declaration and is not affected by the enumeration type representation. In the example, because of the need to avoid the omitted values, the functions are less efficiently implemented than they could be in the absence of representation specification. Similar considerations apply when such types are used for indexing.
13.4 Record Type Representations

A record type representation specifies the storage representation of records, that is, the order, position, and size of record components (including discriminants, if any). Any expression contained in a record type representation must be a static expression of some integer type.

\[
\text{record \_type \_representation} ::= \\
\text{for type} \_name \text{ use} \\
\quad \text{record} [\text{alignment} \_clause:] \\
\quad \quad \{\text{component} \_name \text{ location;}\} \\
\quad \text{end record;} \\
\text{location} ::= \text{at static} \_simple \_expression \text{ range range} \\
\text{alignment} \_clause ::= \text{at mod static} \_simple \_expression
\]

The position of a component is specified as a location relative to the start of the record. The integer defined by the static expression of the at clause of a location is a relative address expressed in storage units. The range defines the bit positions of the component, relative to the storage unit. The first storage unit of a record is numbered 0. The first bit of a storage unit is numbered 0. The ordering of bits in a storage unit is machine dependent and may extend to adjacent storage units. For a specific machine, the size of bits of a storage unit is given by the configuration dependent constant \(\text{SYSTEM.STORAGE\_UNIT}\).

Locations may be specified for some or for all components of a record, including discriminants. If no location is specified for a component, freedom is left to the compiler to define the location of the component. If locations are specified for all components, the record type representation completely specifies the representation of the record type and must be obeyed exactly. Locations within a record variant must not overlap, but the storage for distinct variants may overlap. Each location must allow for enough storage space to accommodate every allowable value of the component. Locations can only be specified for components whose constraints are static.

An alignment clause forces each record of the given type to be allocated at a starting address which is a multiple of the value of the given expression (that is, the address modulo the expression must be zero). An implementation may place restrictions on the allowable alignments. Components may overlap storage boundaries, but an implementation may place restrictions on how components may overlap storage boundaries.

An implementation may generate names that denote certain system dependent components (for example, one containing the offset of another component that is a dynamic array). Such names can be used in record type representations. The conventions to be followed for such names must be documented in Appendix F.
Example:

```ada
WORD : constant := 4; -- storage unit is byte, 4 bytes per word

type STATE is (A, M, W, P);
type MODE is (FIX, DEC, EXP, SIGNIF);

type PROGRAM_STATUS_WORD is
  record
    SYSTEM_MASK : array(0 .. 7) of BOOLEAN;
    PROTECTION_KEY : INTEGER range 0 .. 3;
    MACHINE_STATE : array(STATE) of BOOLEAN;
    INTERRUPT_CAUSE : INTERUPTION_CODE;
    ILC : INTEGER range 0 .. 3;
    CC : INTEGER range 0 .. 3;
    PROGRAM_MASK : array(MODE) of BOOLEAN;
    INST_ADDRESS : ADDRESS;
  end record;

for PROGRAM_STATUS_WORD use
  record at mod b;
    SYSTEM_MASK at 0*WORD range 0 .. 7;
    PROTECTION_KEY at 0*WORD range 10 .. 11; -- bits 8, 9 unused
    MACHINE_STATE at 0*WORD range 12 .. 15;
    INTERRUPT_CAUSE at 0*WORD range 18 .. 31;
    ILC at 1*WORD range 0 .. 1; -- second word
    CC at 1*WORD range 2 .. 3;
    PROGRAM_MASK at 1*WORD range 4 .. 7;
    INST_ADDRESS at 1*WORD range 8 .. 31;
  end record;

for PROGRAM_STATUS_WORD'SIZE use 2*SYSTEM.STORAGE_UNIT;
```

Note on the example

The record type representation defines the record layout; the length specification guarantees that exactly two storage units are used.

References:

component 3.7, constraint 3.3, discriminant 3.7.1, expression 4.4, integer type 3.5.4, name 4.1, range 3.5, record component 3.7, record type 3.7, static expression 4.9, type 3, value 3.7.1, variant 3.7.1 3.7.3

13.5 Address Specifications

An address specification defines the location of an object in storage or the starting address of a program unit. An address specification given for an entry links the entry to a hardware interrupt.

```ada
address_specification ::= for name use at static_simple_expression;
```

The static expression given after the reserved word at must be of some integer type. The conventions that define the interpretation of this integer value as an address, as an interrupt level, or whatever it may be, are implementation dependent. They must be documented in Appendix F.

13.5 Address Specifications
The name must be one of the following:

(a) Name of an object: the address is the address assigned to the object (variable or constant).

(b) Name of a subprogram, package, or task: the address is that of the machine code associated with the body of the program unit.

(c) Name of an entry: the address specifies a hardware interrupt to which the entry is linked. This form of address specification cannot be used for an entry of a family.

Address specifications should not be used to achieve overlays of objects or overlays of program units. Nor should a given interrupt be linked to more than one entry. Any program using address specifications to that effect is erroneous.

Example:

for CONTROL use at 16#0020#;

Notes:

For address specifications an implementation may allow static expressions containing terms that are only known when linking the program. Such terms may be written as representation attributes. An implementation may provide pragmas for the specification of program overlays.

References:

constant 3.2, entry 9.5, family of entries 9.5, integer type 3.5.4, name 4.1, object 3.2, package 7, pragma 2.8, program unit 7, static expression 4.9, subprogram 6, task 9, value 3.3, variable 3.2 4.1

13.5.1 Interrupts

An address specification given for an entry associates the entry with an interrupt; such an entry is referred to in this section as an interrupt entry. If control information is supplied by an interrupt, it is passed to an associated interrupt entry as one or more in parameters.

The occurrence of an interrupt acts as an entry call issued by a task whose prior ty is higher than that of any user-defined task. The entry call may be an ordinary entry call, a timed entry call, or a conditional entry call, depending on the type of interrupt and on the implementation.

Example:

    task INTERRUPT_HANDLER is
        entry DONE;
        for DONE use at 16#40#;
    end;

Interru1ts 13.5.1
Notes:

Interrupt entry calls need only have the semantics described above; they may be implemented by having the hardware directly execute the appropriate accept statements.

Queued interrupts correspond to ordinary entry calls. Interrupts that are lost if not immediately processed correspond to conditional entry calls. It is a consequence of the priority rules that an accept statement executed in response to an interrupt takes precedence over ordinary, user-defined tasks, and can be executed without first invoking a scheduling action.

One of the possible effects of an address specification for an interrupt entry is to specify the priority of the interrupt (directly or indirectly). Direct calls to an interrupt entry are allowed.

References:


13.6 Change of Representation

Only one representation can be defined for a given type. If therefore an alternative representation is desired, it is necessary to declare a second type derived from the first and to specify a different representation for the second type.

Example:

```ada
-- PACKED_DESCRIPTOR and DESCRIPTOR are two different types
-- with identical characteristics, apart from their representation

type DESCRIPTOR is
  record
    -- components of a descriptor
  end;

type PACKED_DESCRIPTOR is new DESCRIPTOR;

for PACKED_DESCRIPTOR use
  record
    -- locations of all components
  end record;
```

Change of representation can now be accomplished by assignment with explicit type conversions:

```ada
D : DESCRIPTOR;
P : PACKED_DESCRIPTOR;

P := PACKED_DESCRIPTOR(D); -- pack D
D := DESCRIPTOR(P); -- unpack P
```

References:

assignment 5.2, derived type 3.4, type 3, type conversion 4.8

13.6 Change of Representation
13.7 Configuration and Machine Dependent Constants

For a given implementation the package SYSTEM (declared in STANDARD) will contain the definitions of certain constants designating configuration dependent characteristics. The exact definition of the package SYSTEM is implementation dependent and must be given in Appendix F. The specification of this package must contain at least the following declarations.

```plaintext
package SYSTEM is
    type SYSTEM_NAME is -- implementation defined enumeration type
        NAME : constant SYSTEM_NAME := -- the name of the system
        STORAGE_UNIT : constant := -- the number of bits per storage unit
        MEMORY_SIZE : constant := -- the number of available storage units in memory
        MIN_INT : constant := -- the smallest integer value supported by a predefined type
        MAX_INT : constant := -- the largest integer value supported by a predefined type
    end SYSTEM;
```

The corresponding characteristics of the configuration can be specified in the program by supplying appropriate pragmas:

```plaintext
pragma SYSTEM(name); -- to establish the name of the object machine
pragma STORAGE_UNIT(number); -- to establish the number of bits per storage unit
pragma MEMORY_SIZE(number); -- to establish the required number of storage units
```

The values corresponding to other implementation dependent characteristics of specific program constructs, including the characteristics established by representation specifications, can be obtained by the use of appropriate representation attributes. These include the attributes ADDRESS, SIZE, POSITION, FIRST_BIT, LAST_BIT, and so on. The list of language defined attributes is given in Appendix A.

An implementation may provide additional pragmas that influence representation, and it may also provide corresponding representation attributes. These implementation specific pragmas and attributes must be documented in Appendix F.

Examples:

```plaintext
INTEGER'SIZE -- number of bits actually used for implementing INTEGER
TABLE'ADDRESS -- address of TABLE
X.COMPONENT'POSITION -- position of COMPONENT in storage units
X.COMPONENT'FIRST_BIT -- first bit of bit range
X.COMPONENT'LAST_BIT -- last bit of bit range
```

References:

attribute A, constant 3.2, declaration 3.1, package 7, package specification 7.2, pragma 2.8
13.7.1 Representation Attributes of Real Types

For every floating point type or subtype F, the following machine dependent attributes are defined which are not related to the model numbers. Programs using these attributes may thereby exploit properties that go beyond the minimal properties associated with the numeric type. Precautions must consequently be taken when using these machine dependent attributes if portability is to be ensured.

- **F'MACHINE_ROUNDS**
  True if and only if all machine operations using type F perform rounding. Of type BOOLEAN.

- **F'MACHINE_RADIX**
  The machine radix of numerical representation. Of type universal_integer.

- **F'MACHINE_MANTISSA**
  The number of machine radix places in the mantissa. Of type universal_integer.

- **F'MACHINE_EMAX**
  The maximum exponent of numerical representation (to the base of the radix). Of type universal_integer.

- **F'MACHINE_EMIN**
  The smallest exponent of numerical representation. Of type universal_integer.

- **F'MACHINE_OVERFLOWS**
  True if and only if the exception NUMERIC_ERROR is raised for computations which exceed the range of real arithmetic. Of type BOOLEAN.

For every fixed point type or subtype F, the following machine dependent attribute is defined.

- **F'MACHINE_ROUNDS**
  True if and only if each operation on values of the type F performs rounding. Of type BOOLEAN.

*Note:*

The largest machine representable number is almost

\[(F'MACHINE_RADIX)**(F'MACHINE_EMAX),\]

and the smallest is

\[F'MACHINE_RADIX ** (F'MACHINE_EMIN - 1)\]

*References:*

accuracy of operations with real operands 3.5.8, boolean type 3.5.3, exponent 3.5.7, fixed point type 3.5.9, floating point type 3.5.7, mantissa 3.5.7, model number 3.5.7, numeric_error exception 11.1, universal integer type 2.4 3.2
13.8 Machine Code Insertions

A machine code insertion can be achieved by a call to an inline procedure whose sequence of statements contains only code statements. Only use clauses and pragmas may appear in the declarative part of such a procedure. No exception handler may appear in such a procedure.

\[
\text{code\_statement} ::= \text{qualified\_expression};
\]

Each machine instruction appears as a record aggregate of a record type that defines the corresponding instruction. Declarations of such record types will generally be available in a predefined package for each machine. A procedure that contains a code statement must contain only code statements.

An implementation may provide machine dependent pragmas specifying register conventions and calling conventions. Such pragmas must be documented in Appendix F.

Example:

\[
\begin{align*}
\text{M : MASK}; \\
\text{procedure SET\_MASK : pragma INLINE(SET\_MASK);}
\end{align*}
\]

\[
\begin{align*}
\text{procedure SET\_MASK is} \\
\text{use INSTRUCTION\_360;}
\begin{align*}
\text{begin} \\
\text{SL\_FORMAT'(CODE \Rightarrow SSM, B \Rightarrow M'BASE, D \Rightarrow M'DISP);} \\
\quad \text{-- M'BASE and M'DISP are implementation specific predefined attributes}
\end{align*}
\end{align*}
\]

References:
declarative part 3.9, exception handler 11.2, inline pragma 6.3, inline procedure 6.3, package 7, pragma 2.8, procedure 6, qualified expression 4.7, record aggregate 4.3.1, record type definition 3.7, statement 5.1, use clause 8.4

13.9 Interface to Other Languages

A subprogram written in another language can be called from an Ada program provided that all communication is achieved via parameters and function results. A pragma of the form

\[
\text{pragma INTERFACE (language\_name, subprogram\_name);} \\
\]

must be given for each such subprogram(a subprogram name may stand for several overloaded subprograms). This pragma must appear after the subprogram specification, either in the same declarative part or in the same package specification. The pragma specifies the calling conventions and informs the compiler that an object module will be supplied for the corresponding subprogram. Neither a body nor a body stub may be given for such a subprogram.

This capability need not be provided by all compilers. An implementation may place restrictions on the allowable forms and places of parameters and calls.
Example:

```ada
package FORT_LIB is
    function SQRT (X : FLOAT) return FLOAT;
    function EXP  (X : FLOAT) return FLOAT;
    private
        pragma INTERFACE (FORTRAN, SQRT);
        pragma INTERFACE (FORTRAN, EXP);
    end FORT_LIB;

Note:

The conventions used by other language processors that call Ada programs are not part of the Ada language definition. Other language processors.

References:

body 6.3 7.3, body stub 10.2, declarative part 3.9, package specification 7.2, parameter 6.1, pragma 2.8, subprogram 6, subprogram specification 6.1

13.10 Unchecked Programming

The predefined generic library subprograms UNCHECKED_DEALLOCATION and UNCHECKED_CONVERSION are used for unchecked storage deallocation and for unchecked type conversions.

generic
    type OBJECT is limited private;
    type NAME is access OBJECT;
    procedure UNCHECKED_DEALLOCATION (X : in out NAME);

generic
    type SOURCE is limited private;
    type TARGET is limited private;
    function UNCHECKED_CONVERSION (S : SOURCE) return TARGET;

13.10.1 Unchecked Storage Deallocatior

Unchecked storage deallocation of an object designated by a value of an access type is achieved by a call of a procedure obtained by instantiation of the generic procedure UNCHECKED_DEALLOCATION. For example.

```
procedure FREE is new UNCHECKED_DEALLOCATION (.);
```
Such a FREE procedure has the following effect:

(a) after executing FREE(X), the value of X is null

(b) FREE(X), when X is already equal to null, has no effect

(c) FREE(X), when X is not equal to null, is an indication that the object denoted by X is no longer required, and that the storage it occupies is to be reclaimed.

If two access variables X and Y designate the same object, then any reference to this object using Y is erroneous after the call FREE(X); the effect of a program containing such a reference is unpredictable.

It is a consequence of the visibility rules of the language that any compilation unit using unchecked storage deallocations must include UNCHECKED_DEALLOCATION in one of its with clauses.

References:
access type 3.8, generic function 12.1, generic instantiation 12.3, library unit 10.1, type 3.3, visibility rules 8, with clause 10.1.1

13.10.2 Unchecked Type Conversions

Unchecked type conversions can be achieved by instantiating the generic function UNCHECKED_CONVERSION.

The effect of an unchecked conversion is to return the (uninterpreted) parameter value as a value of the target type, that is, the bit pattern defining the source value is returned unchanged as the bit pattern defining a value of the target type. An implementation may place restrictions on unchecked conversions, for example restrictions depending on the respective sizes of objects of the source and target type.

Whenever unchecked conversions are used, it is the programmer's responsibility to ensure that these conversions maintain the properties to be expected from objects of the target type. Programs that violate these properties by means of unchecked conversions are erroneous.

It is a consequence of the visibility rules of the language that any compilation unit using unchecked conversions must include UNCHECKED_CONVERSION in one of its with clauses.

References:
constraint 3.3, constraint_error exception 11.1, generic procedure 12.1, generic instantiation 12.3, library unit 10.1, type 3.3, type conversion 4.6, visibility rules 8, with clause 10.1.1
14. Input-Output

Input-output facilities are predefined in the language by means of two packages. The generic package INPUT_OUTPUT defines a set of input-output primitives applicable to files containing elements of a single type. Additional primitives for text input-output are supplied in the package TEXT_IO. These facilities are described here, together with the conventions to be used for dealing with low level input-output operations.

References:


14.1 General User Level Input-Output

The high level input-output facilities are defined in the language. A suitable package is described here and is given explicitly in section 14.2; it defines file types and the procedures and functions that operate on files.

Files are declared, and subsequently associated with appropriate sources and destinations (called external files) such as peripheral devices or data sets. Distinct file types are defined to provide either read-only access, write-only access or read-and-write access to external files. The corresponding file types are called INFILE, OUTFILE, and INOUTFILE.

External files are named by a character string, which is interpreted by individual implementations to distinguish peripherals, access rights, physical organization, and so on.

The package defining these facilities is generic and is called INPUT_OUTPUT. Any program which requires these facilities must instantiate the package for the appropriate element type.

A file can be read or written, and it can be set to a required position; the current position for access and the number of elements in the file may be obtained.

When the term file is used in this chapter, it refers to a declared object of a file type; the term external file is used otherwise. Whenever there is a possible ambiguity, the term internal file is used to denote a declared file object.

References:

character string 2.6, declaration 3.1, function 6.1, generic instantiation 12.3, generic package 12.1, package 7, procedure 6, type 3
14.1.1 Files

A file is associated with an unbounded sequence of elements, all of the same type. With each element of the file is associated a positive integer number that is its (ordinal) position number in this sequence. Some of the elements may be undefined, in which case they cannot be read.

The file types for a given element type, and the appropriate subprograms for dealing with it, are produced by instantiating a generic package. For example:

    package INT_IO is new INPUT_OUTPUT(ELEMENT_TYPE => INTEGER);

establishes types and procedures for files of integers, so that

    RESULTS_FILE : INT_IO.OUT_FILE;

declares RESULTS_FILE as a write-only file of integers.

Before any file processing can be carried out, the internal file must first be associated with an external file. When such an association is in effect, the file is said to be open. This operation is performed by one of the CREATE or OPEN procedures which operate on a file and a character string used to name an external file:

    procedure CREATE(FILE : in out OUTFILE; NAME : in STRING);
    procedure CREATE(FILE : in out INOUTFILE; NAME : in STRING);

Establishes a new external file with the given name and associates with it the given file. A new external file established by a CREATE operation corresponds to a sequence of elements all of which are initially undefined. If the given internal file is already open, the exception STATUS_ERROR is raised. If creation is prohibited for the external file (for example, because an external file with that name already exists), the exception NAME_ERROR is raised.

    procedure OPEN(FILE : in out IN_FILE; NAME : in STRING);
    procedure OPEN(FILE : in out OUT_FILE; NAME : in STRING);
    procedure OPEN(FILE : in out INOUT_FILE; NAME : in STRING);

Associates the given internal file with an existing external file having the given name. If the given internal file is already open, the exception STATUS_ERROR is raised. If no such external file exists, or if this access is prohibited, the exception NAME_ERROR is raised.

After processing has been completed on a file, the association may be severed by the CLOSE procedure:

    procedure CLOSE(FILE : in out IN_FILE);
    procedure CLOSE(FILE : in out OUT_FILE);
    procedure CLOSE(FILE : in out INOUT_FILE);

Severs the association between the internal file and its associated external file. The exception STATUS_ERROR is raised if the internal file is not open.
The functions IS_OPEN and NAME take a file as argument:

function IS_OPEN(FILE : in IN_FILE) return BOOLEAN;
function IS_OPEN(FILE : in OUT_FILE) return BOOLEAN;
function IS_OPEN(FILE : in INOUT_FILE) return BOOLEAN;

Returns TRUE if the internal file is associated with an external file, FALSE otherwise.

function NAME(FILE : in IN_FILE) return STRING;
function NAME(FILE : in OUT_FILE) return STRING;
function NAME(FILE : in INOUT_FILE) return STRING;

Returns a string representing the name of the external file currently associated with the given internal file. If there is no external file currently associated, the exception STATUS_ERROR is raised. The string returned is implementation dependent, but must be sufficient to identify uniquely the corresponding external file if used subsequently, for example, in an OPEN operation.

The following procedure operates on external files:

procedure DELETE(NAME : in STRING);

Deletes the named external file; no OPEN operation can thereafter be performed on the external file, and the external file can cease to exist as soon as it is no longer associated with any internal file. Raises the NAME_ERROR exception if no such external file exists, or if this operation is otherwise prohibited.

Example: create a new external file on backing store:

CREATE(FILE => RESULTS_FILE, NAME => "<ADA> COUNTS.1:P77000");
-- write the file
CLOSE(RESULTS_FILE);

Example: read a paper tape:

declare
  package CHAR_IO is new INPUT_OUTPUT(CHARACTER);
  PT : CHAR_IO.IN_FILE;
begin
  CHAR_IO.OPEN(PT, "ttyg");
  -- input the data from device ttyg
  CHAR_IO.CLOSE(PT);
end;

References:

exception 11, false 3.5.3, function 6, generic parameter 12.1, name 4.1, package declaration 7.1, procedure 6, raise an exception 11.3, string 3.6.3, true 5.5.3, type 3
14.1.2 File Processing

An open IN_FILE or INOUT_FILE can be read; an open OUT_FILE or INOUT_FILE can be written. A file that can be read has a current read position, which is the position number of the element available to the next read operation. A file that can be written has a current write position, which is the position number of the element available to be modified by the next write operation. The current read or write positions can be changed. Positions in a file are expressed in the implementation defined integer type FILE_INDEX.

A file has a current size, which is the number of defined elements in the file, and an end position, which is the position number of the last defined element if any, and is otherwise zero.

When a file is opened or created, the current write position is set to 1, and the current read position is set to the position number of the first defined element, or to 1 if no element is defined.

The operations available for file processing are described below; they apply only to open files. The exception STATUS_ERROR is raised if one of these operations is applied to a file that is not open. The exception DEVICE_ERROR is raised if an input-output operation cannot be completed because of a malfunction of the underlying system. The exception USE_ERROR is raised if an operation is incompatible with the properties of the external file.

```ada
procedure READ(FILE in IN_FILE; ITEM out ELEMENT_TYPE);
procedure READ(FILE in INOUT_FILE; ITEM out ELEMENT_TYPE);
```

Returns, in the ITEM parameter, the value of the element at the current read position of the given file. Advances the current read position to the next defined element in the sequence, if any, and otherwise increments it by one. The exception DATA_ERROR is raised if the value is not defined and may (but need not) be raised if it is not of the required element type. The exception END_ERROR is raised if the current read position is higher than the end position. Any previous WRITE on the same external file must have been completed before this READ. Note that READ is not defined for an OUT_FILE.

```ada
procedure WRITE(FILE in OUT_FILE; ITEM in ELEMENT_TYPE);
procedure WRITE(FILE in INOUT_FILE; ITEM in ELEMENT_TYPE);
```

Gives the specified value to the element in the current write position of the given file, and adds 1 to the current write position. Adds 1 to the current size if the element in the current write position was not defined, and sets the end position to the written position if the written position exceeds the end position. Note that WRITE is not defined for an IN_FILE.

```ada
function NEXT_READ(FILE : in IN_FILE) return FILE_INDEX;
function NEXT_READ(FILE : in INOUT_FILE) return FILE_INDEX;
```

Returns the current read position of the given file.

```ada
procedure SET_READ(FILE : in IN_FILE; TO : in FILE_INDEX);
procedure SET_READ(FILE : in INOUT_FILE; TO : in FILE_INDEX);
```

Sets the current read position of the given file to the specified index value. (The specified value may exceed the end position).
procedure RESET_READ(FILE : in INFILE);
procedure RESET_READ(FILE : in INOUT_FILE);

Sets the current read position of the given file to the position number of the first defined element, or to 1 if no element is defined.

function NEXT_WRITE(FILE : in OUT_FILE) return FILE_INDEX;
function NEXT_WRITE(FILE : in INOUT_FILE) return FILE_INDEX;

Returns the current write position of the given file.

procedure SET_WRITE(FILE : in OUT_FILE; TO in FILE_INDEX);
procedure SET_WRITE(FILE : in INOUT_FILE; TO : in FILE_INDEX);

Sets the current write position of the given file to the value specified by TO. (The specified value may exceed the end position).

procedure RESET_WRITE(FILE : in OUT_FILE);
procedure RESET_WRITE(FILE : in INOUT_FILE);

Sets the current write position of the given file to 1.

function SIZE(FILE : in INFILE) return FILE_INDEX;
function SIZE(FILE : in OUT_FILE) return FILE_INDEX;
function SIZE(FILE : in INOUT_FILE) return FILE_INDEX;

Returns the current size of the file.

function LAST(FILE : in INFILE) return FILE_INDEX;
function LAST(FILE : in OUT_FILE) return FILE_INDEX;
function LAST(FILE : in INOUT_FILE) return FILE_INDEX;

Returns the end position of the file.

function END_OF_FILE(FILE : in INFILE) return BOOLEAN;
function END_OF_FILE(FILE : in INOUT_FILE) return BOOLEAN;

Returns TRUE if the current read position of the given file exceeds the end position, otherwise FALSE.

procedure TRUNCATE(FILE : inout FILE; TO : in FILE_INDEX);
procedure TRUNCATE(FILE : in INOUT_FILE; TO : in FILE_INDEX);

Sets the end position of the given file to the specified index value, if it is not larger than the current end position, and changes the current size accordingly. Any element after the given position becomes undefined. Raises the USE_ERROR exception if the specified index value exceeds the current end position.
The predefined package does not restrict the physical representation of an external file, providing only that this representation implements a sequence of elements, indexed by position. An external file can thus be a collection of records stored on disks, tapes or other media, or a keyboard, a terminal, a line-printer, a communication link or other device. The interpretation of the character string used to name an external file depends on the implementation: this external file name can be used to specify devices, system addresses, file organization, access rights and so on.

A file may be implemented using various access methods. In a sequential organization, all the elements up to the size of the file are always defined (although their value may be arbitrary), and a successful READ operation will always increment the current read position by 1. In an indexed organization however, the only defined elements are those whose position numbers are given by existing key values.

Certain accesses to particular external files may be prohibited; attempts at such accesses will raise the exception USE_ERROR. Examples are the attempt to backspace on a paper tape, to write a protected file, to extend a file whose size is fixed, or manipulate the current read or write position on a communication link, or to ask for the SIZE or the LAST of an interactive device.

Example of file processing:

```
-- Accumulate the values of a sequential external and append the total

declare
  use INT_IO;
  COUNTS : INOUT_FILE;
  VALUE : INTEGER;
  TOTAL : INTEGER := 0;
begin
  OPEN(COUNTS, "> udd > ada > counts");
  while not END_OF_FILE(COUNTS) loop
    READ(COUNTS, VALUE);
    TOTAL := TOTAL + VALUE;
  end loop;
  SET_WRITE(COUNTS, LAST(COUNTS) + 1);
  WRITE(COUNTS, TOTAL);
  CLOSE(COUNTS);
end;
```

Example of file positioning:

```
RESET_READ(COUNTS);   -- could mean rewind
SET_WRITE(RESULTS_FILE, NEXT_WRITE(RESULTS_FILE) - 1);  -- backspace
SET_WRITE(RESULTS_FILE, LAST(RESULTS_FILE) + 1);        -- advance to end of file
```

References:

character string 2.6, false 3.5.3, name 4.1, output parameter 6.2, package 7, record 3.7, true 3.5.3, type 3

14.1.2 File Processing
14.2 Specification of the Package Input_Output

The specification of the generic package INPUT_OUTPUT is given below. It provides the calling conventions for the operations described in section 14.1.

generic
  type ELEMENT_TYPE is limited private;
package INPUT_OUTPUT is
  type IN_FILE is limited private;
  type OUT_FILE is limited private;
  type INOUT_FILE is limited private;
  type FILE_INDEX is range 0 .. implementation_defined;

-- general operations for file manipulation

procedure CREATE (FILE : in out OUT_FILE; NAME : in STRING);
procedure CREATE (FILE : in out INOUT_FILE; NAME : in STRING);
procedure OPEN (FILE : in out IN_FILE; NAME : in STRING);
procedure OPEN (FILE : in out OUT_FILE; NAME : in STRING);
procedure OPEN (FILE : in out INOUT_FILE; NAME : in STRING);

procedure CLOSE (FILE : in out IN_FILE);
procedure CLOSE (FILE : in out OUT_FILE);
procedure CLOSE (FILE : in out INOUT_FILE);

function IS_OPEN (FILE : in IN_FILE) return BOOLEAN;
function IS_OPEN (FILE : in OUT_FILE) return BOOLEAN;
function IS_OPEN (FILE : in INOUT_FILE) return BOOLEAN;

function NAME (FILE : in IN_FILE) return STRING;
function NAME (FILE : in OUT_FILE) return STRING;
function NAME (FILE : in INOUT_FILE) return STRING;

procedure DELETE (NAME : in STRING);

function SIZE (FILE : in IN_FILE) return FILE_INDEX;
function SIZE (FILE : in OUT_FILE) return FILE_INDEX;
function SIZE (FILE : in INOUT_FILE) return FILE_INDEX;

function LAST (FILE : in IN_FILE) return FILE_INDEX;
function LAST (FILE : in OUT_FILE) return FILE_INDEX;
function LAST (FILE : in INOUT_FILE) return FILE_INDEX;

procedure TRUNCATE(FILE: in OUT_FILE; TO: in FILE_INDEX);
procedure TRUNCATE(FILE: in INOUT_FILE; TO: in FILE_INDEX);
-- input and output operations

procedure READ (FILE in INFILE: ITEM out ELEMENTTYPE);
procedure READ (FILE in INOUTFILE: ITEM out ELEMENTTYPE);

function NEXT_READ (FILE in INFILE) return FILE_INDEX;
function NEXT_READ (FILE in INOUTFILE) return FILE_INDEX;

procedure SET_READ (FILE in INFILE: TO in FILE_INDEX);
procedure SET_READ (FILE in INOUTFILE: TO in FILE_INDEX);

procedure RESET_READ (FILE in INFILE);
procedure RESET_READ (FILE in INOUTFILE);

procedure WRITE (FILE in OUTFILE: ITEM in ELEMENTTYPE);
procedure WRITE (FILE in INOUTFILE: ITEM in ELEMENTTYPE);

function NEXT_WRITE (FILE in OUTFILE) return FILE_INDEX;
function NEXT_WRITE (FILE in INOUTFILE) return FILE_INDEX;

procedure SET_WRITE (FILE in OUTFILE: TO in FILE_INDEX);
procedure SET_WRITE (FILE in INOUTFILE: TO in FILE_INDEX);

procedure RESET_WRITE (FILE in OUTFILE);
procedure RESET_WRITE (FILE in INOUTFILE);

function END_OF_FILE (FILE in INFILE) return BOOLEAN;
function END_OF_FILE (FILE in INOUTFILE) return BOOLEAN;

-- exceptions that can be raised

NAME_ERROR : exception;
USE_ERROR : exception;
STATUS_ERROR : exception;
DATA_ERROR : exception;
DEVICE_ERROR : exception;
END_ERROR : exception;

private
    -- declarations of the file private types
end INPUT_OUTPUT;

14.3 Text Input-Output

Facilities are available for input and output in human readable form, with the external file consisting of characters. The package defining these facilities is called TEXT_IO; it is described here and is given explicitly in section 14.4. It uses the general INPUT_OUTPUT package for files of type CHARACTER, so all the facilities described in section 14.1 are available. In addition to these general facilities, procedures are provided to GET values of suitable types from external files of characters, and PUT values to them, carrying out conversions between the internal values and appropriate character strings.
All the GET and PUT procedures have an ITEM parameter, whose type determines the details of the action and determines the appropriate character string in the external file. Note that the ITEM parameter is an out parameter for GET and an in parameter for PUT. The general principle is that the characters in the external file are composed and analyzed as lexical elements, as described in Chapter 2. The conversions are based on the IMAGE and VALUE attributes described in Appendix A.

For all GET and PUT procedures, there are forms with and without a file specified. If a file is specified, it must be of the correct type (IN_FILE for GET, OUT_FILE for PUT). If no file is specified, a default input file or a default output file is used. At the beginning of program execution, the default input and output files are the so-called standard input file and standard output file, which are open and associated with two implementation defined external files.

Although the package TEXT_IO is defined in terms of the package INPUT_OUTPUT, the execution of an operation of one of these packages need not have a well defined effect on the execution of subsequent operations of the other package. For example, if the function LAST (of the package INPUT_OUTPUT) is called immediately before and after a call of the function NEWLINE (of the package TEXT_IO) for a given file and with spacing one, the difference between the two values of LAST is undefined; it could be any non negative value. The effect of the package TEXT_IO is defined only if the characters written by a PUT operation or read by a GET operation belong to the 95 graphic ASCII characters. The effect of a program that reads or writes any other character is implementation dependent.

Note:

Text input output is not defined for files of type INOUT_FILE.

References:

character 2.6, character string 2.6, character type 3.5.2, external file 14.1, image attribute A, in parameter 3.1, out parameter 6.1, package 7, procedure 6, type 3, value attribute A.

14.3.1 Default Input and Output Files

Control of the particular default files used with the short forms of GET and PUT can be achieved by means of the following functions and procedures:

function STANDARD_INPUT return IN_FILE: -- returns INITIAL default input file
function STANDARD_OUTPUT return OUT_FILE: -- returns INITIAL default output file
function CURRENT_INPUT return IN_FILE: -- returns CURRENT default input file
function CURRENT_OUTPUT return OUT_FILE: -- returns CURRENT default output file
procedure SET_INPUT (FILE : in IN_FILE): -- sets the default input file to FILE
procedure SET_OUTPUT (FILE : in OUT_FILE): -- sets the default output file to FILE

The exception STATUS_ERROR is raised by the functions CURRENT_INPUT and CURRENT_OUTPUT if there is no corresponding default file, and by the procedure SET_INPUT and SET_OUTPUT if the parameter is not an open file.
14.3.2 Layout

A text file consists of a sequence of lines, numbered from 1. The characters in each line are considered to occupy consecutive character positions called columns, counting from 1. Each character occupies exactly one column. A file may have a particular line length that is explicitly set by the user. If no line length has been specified, lines can be of any length up to the size of the file. The line length can be set or reset during execution of a program, so that the same file can be written using both fixed line length (for instance for the production of tables), and variable line length (for instance during interactive dialogues). A file which is open (or simply created) has a current line number and a current column number. These determine the starting position available for the next GET or PUT operation.

The following subprograms provide for control of the line structure of the file given as first parameter, or of the corresponding default file if no file parameter is supplied. Unless otherwise stated, this default file is the current output file. As in the general case, these subprograms may raise the USE_ERROR exception if the request is incompatible with the associated external file.

function COL(FILE in INFILE) return NATURAL;
function COL(FILE in OUTFILE) return NATURAL;
function COL return NATURAL;

Returns the current column number.

procedure SET_COL(FILE in INFILE; TO in NATURAL);
procedure SET_COL(FILE in OUTFILE; TO in NATURAL);
procedure SET_COL(TO: in NATURAL);

Sets the current column number to the value specified by TO. The current line number is unaffected. The exception LAYOUT_ERROR is raised if the line length has been specified and is less than the specified column number.

function LINE(FILE in INFILE) return NATURAL;
function LINE(FILE in OUT_FILE) return NATURAL;
function LINE return NATURAL;

Returns the current line number.

procedure NEW_LINE(FILE : in OUT_FILE; SPACING : in NATURAL := 1);
procedure NEW_LINE(SPACING : in NATURAL := 1);

Resets the current column number to 1 and increments the current line number by SPACING. Thus a SPACING of 1 corresponds to single spacing, a SPACING of 2 to double spacing. This terminates the current line and adds SPACING - 1 empty lines. If the line length is fixed, extra space characters are inserted when needed to fill the current line and add empty lines.
procedure SKIP_LINE(FILE: in INFILE; SPACING : in NATURAL := 1);
procedure SKIP_LINE(SPACING : in NATURAL := 1);

Resets the current column number to 1 and increments the current line number by SPACING (A value of SPACING greater than 1 causes SPACING - 1 lines to be skipped as well as the remainder of the current line). The default file is the current input file.

function END_OF_LINE(FILE : in INFILE) return BOOLEAN;
function END_OF_LINE RETURN BOOLEAN;

Returns TRUE if the line length of the specified input file is not set, and the current column number exceeds the length of the current line (that is, if there are no more characters to be read on the current line), otherwise FALSE. The default file is the current input file. (END_OF_LINE is meant to be used primarily for files containing lines of different lengths).

procedure SET_LINE_LENGTH(FILE: in INFILE; N : in INTEGER);
procedure SET_LINE_LENGTH(FILE: in OUTFILE; N : in INTEGER);
procedure SET_LINE_LENGTH(N : in INTEGER);

Sets the line length of the specified file to the value specified by N. The value zero indicates that line length is not set; it is the initial value for any file. The exception LAYOUT_ERROR is raised by a get operation if a line mark does not correspond to the specified line length.

function LINE_LENGTH(FILE: in INFILE) return INTEGER;
function LINE_LENGTH(FILE: in OUTFILE) return INTEGER;
function LINE_LENGTH RETURN INTEGER;

Returns the current line length of the specified file if it is set, otherwise zero.

Examples:

SET_COL(((COL() - 1)/10 + 1)*10 + 1);  -- advance to next multiple of 10
       -- plus 1 on current output - file

if END_OF_LINE(F) then
       -- advance to next line at end of current line
       SKIP_LINE(F);  -- (the line length of F is not set)
end if;

SET_LINE_LENGTH(F, 132);

References:

character 2.1, exception 11, false 3.5.3, number 2.4, parameter 6, subprogram 6, true 3.5.3
14.3.3 Input-Output of Characters and Strings

The GET and PUT procedures for these types work with individual characters. The current line and column number are affected as explained below. Special line marks are used to implement the line structure, in addition to the individual characters.

For an ITEM of type CHARACTER

```
procedure GET(FILE : in IN_FILE; ITEM : out CHARACTER);
procedure GET(ITEM : out CHARACTER);
```

Returns, in the out parameter ITEM, the value of the character from the specified input file at the position given by the current line number and the current column number. Adds 1 to the current column number, unless the line length is fixed and the current column number equals the line length, in which case the current column number is set to 1 and the current line number is increased by 1. (This case corresponds to a line mark following the character that was read; thus line marks are always skipped when the line length is fixed). The default file is the current input file.

```
procedure PUT(FILE : in OUT_FILE; ITEM : in CHARACTER);
procedure PUT(ITEM : in CHARACTER);
```

Outputs the specified character to the specified output file on the current column of the current line. Adds 1 to the current column number, unless the line length is fixed and the current column number equals the line length, in which case a line mark is output and the current column number is set to 1 and the current line number is increased by 1. The default file is the current output file.

When the ITEM type is a string, the length of the string is determined and that exact number of GET or PUT operations for individual characters is carried out.

```
procedure GET(FILE : in IN_FILE; ITEM : out STRING);
procedure GET(ITEM : out STRING);
procedure PUT(FILE : in OUT_FILE; ITEM : in STRING);
procedure PUT(ITEM : in STRING);
```

In addition, the following functions and procedures are provided

```
function GET_STRING(FILE : in IN_FILE) return STRING;
function GET_STRING return STRING;
```

Performs GET operations on the specified IN file, skipping any leading blanks (that is, spaces, tabulation characters or line marks) and returns as result the next sequence of characters up to (and not including) a blank. The default file is the current input file.

```
function GET_LINE(FILE : in IN_FILE) return STRING;
function GET_LINE ... return STRING;
```

Returns the next sequence of characters up to, but not including, a line mark. If the input line is already at the end of a line, a null string is returned. The input file is advanced just past the line mark, so successive calls of GET_LINE return successive lines. The default file is the current input file.
procedure PUT_LINE(FILE : in OUT_FILE; ITEM : in STRING);
procedure PUT_LINE(ITEM : in STRING);

Calls PUT to write the given STRING to the specified file, and appends a line mark. The default file is the current output file.

Example: variable line length

PUT(F, "01234567");
NEW_LINE(F);
PUT(F, "89012345");

will output

01234567
89012345

The string can subsequently be input by

GET_STRING(G) & GET_STRING(G)

Alternatively, it can be obtained by

X : STRING(1 .. 16);
...
GET(G, X(1 .. 8));
SKIP_LINE(G);
GET(G, X(9 .. 16));

Example: fixed line length

SET_LINE_LENGTH(F, 8);
...
PUT(F, "0123456789012345");

will output

01234567
89012345

The string can subsequently be input by

X : STRING(1 .. 16);
SET_LINE_LENGTH(G, 8);
GET(G, X);

Note that the double-quote marks enclosing an actual parameter of PUT are not output, but the string inside is output with any doubled double-quote marks written once, thus matching the rule for character strings (see 2.6).

References:

actual parameter 6.4, character 2.1, character string 2.6, character type 3.5.2, double-quote marks 2.6, function 6, out parameter 6.2, space character 2.1, string 3.6.3, type 3
14.3.4 Input-Output for Other Types

All ITEM types other than CHARACTER or STRING are treated in a uniform way, in terms of lexical units (see 2.2, 2.3, 2.4). The output is a character string having the syntax described for the appropriate unit and the input is taken as the longest possible character string having the required syntax. For input, any leading spaces, leading tabulation characters, and leading line marks are ignored. A consequence is that no such units can cross a line boundary.

If the character string read is not consistent with the syntax of the required lexical unit, the exception DATA_ERROR is raised.

The PUT procedures for numeric and enumeration types include an optional WIDTH parameter, which specifies a minimum number of characters to be generated. If the width given is larger than the string representation of the value, the value will be preceded (for numeric types) or followed (for enumeration types) by the appropriate number of spaces. If the field width is smaller than the string representation of the value, the field width is ignored. A default width of 0 is provided, thus giving the minimum number of characters.

In each PUT operation, if the line can accommodate all the characters generated, then the characters are placed on that line from the current column. If the line cannot accommodate all the characters, then a new line is started and the characters are placed on the new line starting from column 1. If however the line length is fixed and smaller than the length of the string to be output, then the exception LAYOUT_ERROR is raised instead, and a new line is not started.

For each GET operation an IN file may be specified, and the default file is the current input file. For each PUT operation an OUT file may be specified, and the default file is the current output file.

References:

character string 2.6, character type 3.5.2, enumeration type 3.5.1, exception 11, in_file 14.1, lexical unit 2.2, numeric type 3.5, out_file 14.1, space character 2.1, string type 3.6.3, tabulation character 2.2

14.3.5 Input-Output for Numeric Types

Input for numeric types is defined by means of three generic packages; these packages must be instantiated for the corresponding numeric types (indicated by NUM in the specifications given here).
**Integer types:**

The following procedures are defined in the generic package INTEGER_IO

```plaintext
procedure GET(FILE : in IN_FILE; ITEM : out NUM);
procedure GET(ITEM : out NUM);
```

Reads an optional plus or minus sign, then according to the syntax of an integer literal (which may be a based number). The value obtained is implicitly converted to the type of the out parameter ITEM (see 3.5.4), and returned in ITEM if the converted value is within the range of this type; otherwise the exception CONSTRAINT_ERROR is raised and ITEM is unaffected.

```plaintext
procedure PUT(FILE : in OUT_FILE;
   ITEM : in NUM;
   WIDTH : in INTEGER := 0;
   BASE : in INTEGER range 2 .. 16 := 10);
procedure PUT(ITEM : in NUM;
   WIDTH : in INTEGER := 0;
   BASE : in INTEGER range 2 .. 16 := 10);
```

Expresses the value of the parameter ITEM as an integer literal, with no underscores and no leading zeros (but a single 0 for the value zero), and a preceding minus sign for a negative value. Uses the syntax of based number if the parameter BASE is given with a value different from 10 (the default value), otherwise the syntax of decimal number.

**Examples:**

In the examples for numeric types the string quotes are shown only to reveal the layout; they are not output. Similarly leading spaces are indicated by the lower letter b.

```plaintext
PUT(126);
PUT(-126, 7);
PUT(126, WIDTH => 13, BASE => 2);
```

**Floating point numbers:**

The following procedures are defined in the generic package FLOAT_IO

```plaintext
procedure GET(FILE : in IN_FILE; ITEM: out NUM);
procedure GET(ITEM: out NUM);
```

Reads an optional plus or minus sign, then according to the syntax of a real literal (which may be a based number). The value obtained is implicitly converted to the type of the out parameter ITEM (see 3.5.7), and returned in ITEM if the converted value is within the range of this type; otherwise the exception CONSTRAINT_ERROR is raised and ITEM is unaffected.

---

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procedure PUT(FILE : in OUT_FILE;
ITEM : in NUM;
WIDTH : in INTEGER := 0;
MANTISSA : in INTEGER := NUM'DIGITS;
EXPONENT : in INTEGER := 2);
procedure PUT(ITEM : in NUM;
WIDTH : in INTEGER := 0;
MANTISSA : in INTEGER := NUM'DIGITS;
EXPONENT : in INTEGER := 2);

Expresses the value of the parameter ITEM as a decimal number, with no underscores, a preceding minus sign for a negative value, a mantissa with the decimal point immediately following the first non-zero digit and no leading zeros (but 0.0 for the value zero), and a signed exponent part. A minimum number of digits in the mantissa (excluding sign and point characters) can be specified (leading zeros being supplied as necessary); the default value is given by the type of ITEM: rounding is performed if fewer digits are specified than the implemented precision. A minimum number of digits in the exponent part (excluding sign and \(E\)) can be specified (leading zeros being supplied as necessary); the default value is 2; if the value of ITEM needs more digits than specified for the exponent part, the exact number of significant digits is used.

Examples:

package REAL_IO is new FLOAT_IO(REAL); use REAL_IO;
X : REAL := 0.001266; -- digits 8

PUT(X); -- "1.2660000E-03"
PUT(X, WIDTH => 14, MANTISSA => 4, EXPONENT => 1); -- "bbbbbb1.266E-3"

Fixed point numbers:
The following procedures are defined in the generic package FIXED_IO

procedure GET(FILE : in IN_FILE; ITEM : out NUM);
procedure GET(ITEM : out NUM);

Reads an optional plus or minus sign, then according to the syntax of a real literal (which may be a based number). The value obtained is implicitly converted to the type of the out parameter ITEM (see 3.5.9), rounded to the implemented delta for the type, and returned in ITEM if the resulting value is within the range of the type; otherwise the exception CONSTRAINT_ERROR is raised and ITEM is unaffected.

procedure PUT(FILE : in OUT_FILE;
ITEM : in NUM;
WIDTH : in INTEGER := 0;
FRACT : in INTEGER := DEFAULT_DECIMALS);
procedure PUT(ITEM : in NUM;
WIDTH : in INTEGER := 0;
FRACT : in INTEGER := DEFAULT_DECIMALS);

Expresses the value of the parameter ITEM as a decimal number, with no underscores, a preceding minus sign for a negative value, and a mantissa but no exponent part. At least one digit precedes the decimal point; if this requires leading zeros, just the number needed are inserted. The number of digits after the point can be specified; the default value is given by the type of ITEM; rounding is performed if fewer digits are specified than are needed to represent the delta of the type.
Example:

```haskell
type FIX is delta 0.05 range -10 .. 10;
package FIX_IO is new FIXED_IO(FIX);
use FIX_IO;
X : FIX := 1.25;

PUT(X); -- "1.25"
PUT(X, WIDTH => 8, FRACT => 3); -- "bbb1.250"
PUT(X - 1.3); -- "-0.05"
```

References:

based number 2.4.1, constraint_error exception 11.1, decimal number 2.4, digit 2.1, exception 11, exponent part 2.4, fixed point number 3.5.9, floating point number 3.5.7, generic package 12.1, generic package instantiation 12.3, integer literal 2.4, integer type 3.5.4, layout_error exception 14.3.2, mantissa 3.5.7, minus sign 2.4 4.5.4, numeric type 3.5, out parameter 6.2, plus sign 2.4 4.5.9, point character 2.4, precision 3.5.8, range 3.5, real literal 2.4, sign character 4.5.4, underscore 2.3

14.3.6 Input-Output for Boolean Type

procedure GET(FILE : in IN_FILE; ITEM : out BOOLEAN);
procedure GET(ITEM : out BOOLEAN);

Reads an identifier according to the syntax given in 2.3, with no distinction between corresponding upper and lowercase letters. If the identifier is TRUE or FALSE, then the boolean value is given; otherwise the exception DATA_ERROR is raised.

```haskell
procedure PUT(FILE : in CUT_FILE;
ITEM : in BOOLEAN;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);
procedure PUT(ITEM : in BOOLEAN;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);
```

Expresses the value of the parameter ITEM as the words TRUE or FALSE. An optional parameter is used to specify upper or lower case (default is upper case). If a value of WIDTH is given, exceeding the number of letters produced, then spaces follow to fill a field of this width.

Note:

The procedures defined in this section are directly available (that is, not by generic instantiation).

References:

boolean type 3.5.3, boolean value 3.5.3, data_error exception 14.3.4, exception 11, false 3.5.3, identifier 2.3, space character 2.1, true 3.5.3
14.3.7 Input-Output for Enumeration Types

Because each enumeration type has its own set of literals, these procedures are contained in the generic package ENUMERATION_IO. An instantiation must specify the type, indicated here by ENUM.

```ada
procedure GET(FILE : in IN_FILE; ITEM : out ENUM);
procedure GET(ITEM : out ENUM);
```

Reads an identifier (according to the syntax given in 2.3, with no distinction between corresponding upper and lower case letters) or a character literal (according to the syntax of 2.5, a character enclosed by single quotes). If this is one of the enumeration literals of the type, then the enumeration value is given; otherwise the exception DATA_ERROR is raised.

```ada
procedure PUT(FILE : in OUT_FILE;
ITEM : in ENUM;
WIDTH : in INTEGER := 0;
LOWERCASE : in BOOLEAN := FALSE);
procedure PUT(ITEM : in ENUM;
WIDTH : in INTEGER := 0;
LOWERCASE : in BOOLEAN := FALSE);
```

Outputs the value of the parameter ITEM as an identifier or as a character literal. An optional parameter indicates upper or lower case for identifiers (default is upper case); it has no effect for character literals. If a field width is given, exceeding the number of characters produced, then spaces follow to fill a field of this width.

**Note:**
There is a difference between PUT defined for characters, and for enumeration values. Thus

```ada
TEXT_IO.PUT('A'); -- the character A
package CHAR_IO is new TEXT_IO.ENUMERATION_IO(CHARACTER);
CHAR_IO.PUT('A'); -- the character A' between single quotes
```

**References:**
character literal 2.5, data_error exception 14.3.4, enumeration literal 3.5.1, enumeration type 3.5.1, generic package 12.1, generic instantiation 12.3, literal 2.4 3.2 4.2, procedure 6, type 3
14.4 Specification of the Package TEXT_IO

The package TEXT_IO contains the definition of all the text input-output primitives.

package TEXT_IO is
   package CHARACTER_IO is new INPUT_OUTPUT(CHARACTER);

   type IN_FILE is new CHARACTER_IO.IN_FILE;
   type OUT_FILE is new CHARACTER_IO.OUT_FILE;

   -- Character Input - Output
   procedure GET(FILE : in IN_FILE; ITEM : out CHARACTER);
   procedure GET(ITEM : out CHARACTER);
   procedure PUT(FILE : in OUT_FILE; ITEM : in CHARACTER);
   procedure PUT(ITEM : in CHARACTER);

   -- String Input - Output
   procedure GET(FILE : in IN_FILE; ITEM : out STRING);
   procedure GET(ITEM : out STRING);
   procedure PUT(FILE : in OUT_FILE; ITEM : in STRING);
   procedure PUT(ITEM : in STRING);

   function GET_STRING(FILE : in INFILE) return STRING;
   function GET_STRING return STRING;

   function GET_LINE(FILE : in IN_FILE) return STRING;
   function GET_LINE return STRING;
   procedure PUT_LINE(FILE : in OUT_FILE, ITEM : in STRING);
   procedure PUT_LINE(ITEM : in STRING);

   -- Generic package for Integer Input - Output
   generic
      type NUM is range 0;
      with function IMAGE(X : NUM) return STRING is NUM'IMAGE;
      with function VALUE(X : STRING) return NUM is NUM'VALUE;
   package INTEGER_IO is
      procedure GET(FILE : in IN_FILE; ITEM : out NUM);
      procedure GET(ITEM : out NUM);
      procedure PUT(FILE : in OUT_FILE;
                     ITEM : in NUM;
                     WIDTH : in INTEGER := 0;
                     BASE : in INTEGER range 2 .. 16 := 10);
      procedure PUT(ITEM : in NUM;
                     WIDTH : in INTEGER := 0;
                     BASE : in INTEGER range 2 .. 16 := 10);
   end INTEGER_IO;

   end TEXT_IO;
-- Generic package for Floating Point Input - Output

generic
type NUM is digits <>;
with function IMAGE (X : NUM) return STRING is NUM'IMAGE;
with function VALUE (X : STRING) return NUM is NUM'VALUE;
package FLOAT_IO is
   procedure GET(FILE : in IN_FILE; ITEM: out NUM);
   procedure GET(ITEM : out NUM);
   procedure PUT(FILE : in OUT_FILE;
      ITEM : in NUM;
      WIDTH : in INTEGER := 0;
      MANTISSA : in INTEGER := NUM'DIGITS;
      EXPONENT : in INTEGER := 2);
   procedure PUT(ITEM : in NUM;
      WIDTH : in INTEGER := 0;
      MANTISSA : in INTEGER := NUM'DIGITS;
      EXPONENT : in INTEGER := 2);
end FLOAT_IO;

-- Generic package for Fixed Point Input - Output

generic
   type NUM is delta <>;
   with function IMAGE (X : NUM) return STRING is NUM'IMAGE;
   with function VALUE (X : STRING) return NUM is NUM'VALUE;
package FIXED_IO is
   DELTA_IMAGE : constant STRING := IMAGE(NUM'DELTA - INTEGER(NUM'DELTA));
   DEFAULT_DECIMALS : constant INTEGER := DELTA_IMAGE'LENGTH - 2;
   procedure GET(FILE : in IN_FILE; ITEM : out NUM);
   procedure GET(ITEM : out NUM);
   procedure PUT(FILE : in OUT_FILE;
      ITEM : in NUM;
      WIDTH : in INTEGER := 0;
      FRACT : in INTEGER := DEFAULT_DECIMALS);
   procedure PUT(ITEM : in NUM;
      WIDTH : in INTEGER := 0;
      FRACT : in INTEGER := DEFAULT_DECIMALS);
end FIXED_IO;

14.4 Specification of the Package Text_IO
-- Input-output for Boolean

procedure GET(FILE : in IN_FILE; ITEM : out BOOLEAN);
procedure GET(ITEM : out BOOLEAN);

procedure PUT(FILE : in OUT_FILE;
ITEM : in BOOLEAN;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);

procedure PUT(ITEM : in BOOLEAN;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);

-- Generic package for Enumeration Types

generic
    type ENUM is (<>);
    with function IMAGE (X : ENUM) return STRING is ENUM'IMAGE;
    with function VALUE (X : STRING) return ENUM is ENUM'VALUE;

package ENUMERATION_IO is
    procedure GET(FILE : in IN_FILE; ITEM : out ENUM);
    procedure GET(ITEM : out ENUM);

    procedure PUT(FILE : in OUT_FILE;
ITEM : in ENUM;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);

    procedure PUT(ITEM : in ENUM;
WIDTH : in INTEGER := 0;
LOWER_CASE : in BOOLEAN := FALSE);
end ENUMERATION_IO;

-- Layout control

function LINE(FILE : in IN_FILE) return NATURAL;
function LINE(FILE : in OUT_FILE) return NATURAL;
function LINE return NATURAL; -- for default output file

function COL(FILE : in IN_FILE) return NATURAL;
function COL(FILE : in OUT_FILE) return NATURAL;
function COL return NATURAL; -- for default output file

procedure SET_COL(FILE : in IN_FILE; TO : in NATURAL);
procedure SET_COL(FILE : in OUT_FILE; TO : in NATURAL);
procedure SET_COL(TO : in NATURAL) -- for default output file
procedure NEW_LINE(FILE : in OUT_FILE; N : in NATURAL := 1);
procedure NEW_LINE(N : in NATURAL := 1);

procedure SKIP_LINE(FILE : in IN_FILE; N : in NATURAL := 1);
procedure SKIP_LINE(N : in NATURAL := 1);

function END_OF_LINE(FILE : in IN_FILE) return BOOLEAN;
function END_OF_LINE return BOOLEAN;

procedure SET_LINE_LENGTH(FILE : in IN_FILE; N : in INTEGER);
procedure SET_LINE_LENGTH(FILE : in OUT_FILE; N : in INTEGER);
procedure SET_LINE_LENGTH(N : in INTEGER); -- for default output file

function LINE_LENGTH(FILE : in IN_FILE) return INTEGER;
function LINE_LENGTH(FILE : in OUT_FILE) return INTEGER;
function LINE_LENGTH return INTEGER; -- for default output file

-- Default input and output manipulation

function STANDARD_INPUT return IN_FILE;
function STANDARD_OUTPUT return OUT_FILE;

function CURRENT_INPUT return IN_FILE;
function CURRENT_OUTPUT return OUT_FILE;

procedure SET_INPUT (FILE : in IN_FILE);
procedure SET_OUTPUT (FILE : in OUT_FILE);

-- Exceptions

NAME_ERROR : exception renames CHARACTER_IO.NAME_ERROR;
USE_ERROR : exception renames CHARACTER_IO.USE_ERROR;
STATUS_ERROR : exception renames CHARACTER_IO.STATUS_ERROR;
DATA_ERROR : exception renames CHARACTER_IO.DATA_ERROR;
DEVICE_ERROR : exception renames CHARACTER_IO.DEVICE_ERROR;
END_ERROR : exception renames CHARACTER_IO.END_ERROR;
LAYOUT_ERROR : exception;
end TEXT_IO;

References:

boolean type input-output 14.3.6, character input-output 14.3.3, default input-output 14.3.1, enumeration type
input-output 14.3.7, exceptions for input-output 14.1.1 14.1.2 14.3.2 14.3.4, fixed point input-output 14.3.5,
floating point input-output 14.3.5, generic package 12.1, integer input-output 14.3.3, item parameter 14.3,
layout for input-output 14.3.2, package 7, string input-output 14.3.3

14.4 Specification of the Package Text_IO
14.5 Example of Text Input-Output

The following example shows the use of the text input-output primitives in a dialogue with a user at a terminal. The user is asked to select a color, and the program output in response is the number of items of the color available in stock. The default input and output files are used.

```
procedure DIALOGUE is
    use TEXT_IO;
    type COLOR is (WHITE, RED, ORANGE, YELLOW, GREEN, BLUE, BROWN);
    INVENTORY : array (COLOR) of INTEGER = (20, 17, 43, 10, 28, 173, 87);
    CHOICE : COLOR;
    package COLOR_IO is new ENUMERATION_IO(COLOR); use COLOR_IO;

    function ENTER_COLOR return COLOR is
        SELECTION: COLOR;
    begin
        loop
            begin
                PUT("Color selected: ");
                GET(SELECTION);
                return SELECTION;
            exception
                when DATA_ERROR =>
                    PUT("Invalid color, try again.");
            end;
        end loop;
    end;
begin
    CHOICE := ENTER_COLOR;
    NEW_LINE;
    PUT(CHOICE, LOWER_CASE => TRUE);
    PUT(" items available: ");
    SET_COL(25);
    PUT(INVENTORY(CHOICE), WIDTH => 5);
    PUT(",");
    NEW_LINE;
end DIALOGUE;
```

Example of an interaction (characters typed by the user are italicized):

Color selected: black
Invalid color, try again. Color selected: blue
blue items available: 173;

References:

default input file 14.3, default output file 14.3, text input-output primitives 14.4
14.6 Low Level Input-Output

A low level input-output operation is an operation acting on a physical device. Such an operation is handled by using one of the (overloaded) predefined procedures SEND_CONTROL and RECEIVE_CONTROL.

A procedure SEND_CONTROL may be used to send control information to a physical device. A procedure RECEIVE_CONTROL may be used to monitor the execution of an input-output operation by requesting information from the physical device.

Such procedures are declared in the standard package LOW_LEVEL_IO and have two parameters identifying the device and the data. However, the kinds and formats of the control information will depend on the physical characteristics of the machine and the device. Hence the types of the parameters are implementation defined. Overloaded definitions of these procedures should be provided for the supported devices.

The visible part of the package defining these procedures is outlined as follows:

```ada
package LOW_LEVEL_IO is
    -- declarations of the possible types for DEVICE and DATA;
    -- declarations of overloaded procedures for these types:
    procedure SEND_CONTROL (DEVICE : device_type; DATA : in out data_type);
    procedure RECEIVE_CONTROL (DEVICE : device_type; DATA : in out data_type);
end;
```

The bodies of the procedures SEND_CONTROL and RECEIVE_CONTROL for various devices can be supplied in the body of the package LOW_LEVEL_IO. These procedure bodies may be written with code statements.

References:

actual parameter 6.4, code statement 13.8, overloaded definition 3.4, overloaded predefined procedure 6.6, package 7, package body 7.1 7.3, procedure 6.1, procedure body 6.1, type 3, visible part 7.2
A. Predefined Language Attributes

The following attributes are predefined in the language. They are denoted in the manner described in 4.1.4: the name of an entity is followed by a prime, and then by the identifier of an attribute appropriate to the entity.

Attribute of any object or subprogram X
ADDRESS  A number corresponding to the first storage unit occupied by X (see 13.7). Overloaded on all predefined integer types.

Attribute of any type or subtype T (except a task type)
BASE  Applied to a subtype, yields the base type; applied to a type, yields the type itself. This attribute may be used only to obtain further attributes of a type, e.g. T'BASE'FIRST (see 3.3).

Attribute of any type or subtype (except a task type), or any object thereof
SIZE  The maximum number of bits required to hold an object of that type (see 13.3). Of type INTEGER.

Attributes of any scalar type or subtype T
FIRST  The minimum value of T (see 3.3).
LAST  The maximum value of T (see 3.3).
IMAGE  If X is a value of type T, T'IMAGE(X) is a string representing the value in a standard display form.

For an enumeration type, the values are represented, in minimum width, as either the corresponding enumeration literal, in upper case, or as the corresponding character literal, within quotes.

For an integer type, the values are represented as decimal numbers of minimum width. For a fixed point type, the values are represented as decimal fractions of minimum width, with sufficient decimal places just to accommodate the declared accuracy. For a floating point type, the values are represented in exponential notation with one significant characteristic digit, sufficient mantissa digits just to accommodate the declared accuracy, and a signed three-digit exponent. The exponent letter is in upper case. For all numeric types, negative values are prefixed with a minus sign and positive values have no prefix.
VALUE

If S is a string, T'VALUE(S) is the value in T that can be represented in display form by the string S. If the string does not denote any possible value, the exception DATA_ERROR is raised; if the value lies outside the range of T, the exception CONSTRAINT_ERROR is raised. All legal lexical forms are legal display forms (see 2.3, 2.4).

Attributes of any discrete type or subtype T

POS

If X is a value of type T, T'POS(X) is the integer position of X in the ordered sequence of values T'FIRST .. T'LAST, the position of T'FIRST being itself for integer types and zero for enumeration types, (see 3.5.5).

VAL

If J is an integer, T'VAL(J) is the value of enumeration type T whose POS is J. If no such value exists, the exception CONSTRAINT_ERROR is raised, (see 3.5.5).

PRED

If X is a value of type T, T'PRED(X) is the preceding value. The exception CONSTRAINT_ERROR is raised if X = T'FIRST, (see 3.5.5).

SUCC

If X is a value of type T, T'SUCC(X) is the succeeding value. The exception CONSTRAINT_ERROR is raised if X = T'LAST, (see 3.5.5).

Attributes of any fixed point type or subtype T

DELTA

The delta specified in the declaration of T (see 3.5.10). Of type universal real.

ACTUAL_DELTA

The delta of the model numbers used to represent T (see 3.5.10). Of type universal real.

BITS

The number of bits required to represent the model numbers of T (see 3.5.10). Of type universal integer.

LARGE

The largest model number of T (see 3.5.10). Of type universal real.

MACHINE_ROUNDS

True if the machine performs true rounding (to nearest even) when computing values of type T (see 13.7.1). Of type BOOLEAN.

Attributes of any floating point type or subtype T

DIGITS

The number of digits specified in the declaration of T (see 3.5.8). Of type universal integer.

MANTISSA

The number of bits in the mantissa of the representation of model numbers of T (see 3.5.8). Of type universal integer.

EMAX

The largest exponent value of the representation of model numbers of T (see 3.5.8). The smallest exponent value is -EMAX. Of type universal integer.

SMALL

The smallest positive model number of T (see 3.5.8). Of type universal real.
Predefined Language Attributes

LARGE The largest model number of T (see 3.5.8). Of type universal real.

EPSILON The difference between unity and the smallest model number of T greater than unity (see 3.5.8). Both unity and T'EPSILON are model numbers of T. Of type universal real.

MACHINE_RADIX The radix of the exponent of the underlying machine representation of T (see 13.7.1). Of type universal integer.

MACHINE_MANTISSA The number of bits in the mantissa of the underlying machine representation of T (see 13.7.1). Of type universal integer.

MACHINE_EMAX The largest exponent value of the underlying machine representation of T (see 13.7.1). Of type universal integer.

MACHINE_EMIN The smallest exponent value of the underlying machine representation of T (see 13.7.1). Of type universal integer.

MACHINE_ROUNDS True if the machine performs true rounding (to nearest even) when computing values of type T (see 13.7.1). Of type BOOLEAN.

MACHINE_OVERFLOWES True if, when a computed value is too large to be represented correctly by the underlying machine representation of T, the exception NUMERIC_ERROR is raised (see 13.7.1). Of type BOOLEAN.

Attributes of any array type or subtype, or object thereof

FIRST If A is a constrained array type or subtype, or an array object, A'FIRST is the lower bound of the first index (see 3.6.2).

FIRST(J) Similarly, the lower bound of the J'th index, where J must be a static integer expression (see 3.6.2).

LAST If A is a constrained array type or subtype, or an array object, A'LAST is the upper bound of the first index (see 3.6.2).

LAST(J) Similarly, the upper bound of the J'th index, where J must be a static integer expression (see 3.6.2).

LENGTH If A is a constrained array type or subtype, or an array object, A'LENGTH is the number of elements in the first dimension of A (see 3.6.2).

LENGTH(J) Similarly, the number of elements in the J'th dimension, where J must be a static expression (see 3.6.2).

RANGE If A is a constrained array type or subtype, or an array object, A'RANGE is the subtype A'FIRST .. A'LAST, whose base type is the first index type of A (see 3.6.2).
RANGE(J)  Similarly, the subtype A'FIRST(J) .. A'LAST(J), whose base type is the J'th index type of A, and where J must be a static integer expression (see 3.6.2).

Attribute of any record type with discriminants

CONSTRAINED  If R is an object of any record type with discriminants, or of any subtype thereof, R'CONSTRAINED is true if and only if the discriminant values of R cannot be modified (see 3.7.2). Of type BOOLEAN.

Attributes of any record component C

POSITION  The offset within the record, in storage units, of the first unit of storage occupied by C (see 13.7). Of type INTEGER.

FIRST_BIT  The offset, from the start of C'POSITION, of the first bit used to hold the value of C (see 13.7). Of type INTEGER.

LAST_BIT  The offset, from the start of C'POSITION, of the last bit used to hold the value of C. C'LAST_BIT need not lie within the same storage unit as C'FIRST_BIT (see 13.7). Of type INTEGER.

Attribute of any access type P

STORAGE_SIZE  The total number of storage units reserved for allocation for all objects of type P (see 13.2). Overloaded on all predefined integer types.

Attributes of any task, or object of a task type, T

TERMINATED  True when T is terminated (see 9.9). Of type BOOLEAN.

PRIORITY  The (static) priority of T (see 9.9). Of type universal integer.

FAILURE  The exception that, if raised, causes FAILURE within T (see 9.9).

STORAGE_SIZE  The number of storage units allocated for the execution of T (see 9.9). Overloaded on all predefined integer types.

Attribute of any entry E

COUNT  Momentarily, the number of calling tasks waiting on E (see 9.9). Of type INTEGER.
## B. Predefined Language Pragmas

<table>
<thead>
<tr>
<th>Pragma</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTROLLED</td>
<td>Takes an access type name as argument. It must appear in the same declarative part as the access type definition (see 4.8). It specifies that automatic storage reclamation should not be performed for objects of the access type except upon leaving the scope of the access type definition (see 4.8).</td>
</tr>
<tr>
<td>INCLUDE</td>
<td>Takes a string as argument, which is the name of a text file. This pragma can appear anywhere a pragma is allowed. It specifies that the text file is to be included where the pragma is given.</td>
</tr>
<tr>
<td>INLINE</td>
<td>Takes a list of subprogram names as arguments. It must appear in the same declarative part as the named subprograms. It specifies that the subprogram bodies should be expanded inline at each call (see 6.3).</td>
</tr>
<tr>
<td>INTERFACE</td>
<td>Takes a language name and subprogram name as arguments. It must appear after the subprogram specification in the same declarative part or in the same package specification. It specifies that the body of the subprogram is written in the given other language, whose calling conventions are to be observed (see 13.9).</td>
</tr>
<tr>
<td>LIST</td>
<td>Takes ON or OFF as argument. This pragma can appear anywhere. It specifies that listing of the program unit is to be continued or suspended until a LIST pragma is given with the opposite argument.</td>
</tr>
<tr>
<td>MEMORY_SIZE</td>
<td>Takes an integer number as argument. This pragma can only appear before a library unit. It establishes the available number of storage units in memory (see 13.7).</td>
</tr>
<tr>
<td>OPTIMIZE</td>
<td>Takes TIME or SPACE as argument. This pragma can only appear in a declarative part and it applies to the block or body enclosing the declarative part. It specifies whether time or space is the primary optimization criterion.</td>
</tr>
<tr>
<td>PACK</td>
<td>Takes a record or array type name as argument. The position of the pragma is governed by the same rules as for a representation specification. It specifies that storage minimization should be the main criterion when selecting the representation of the given type (see 13.1).</td>
</tr>
<tr>
<td>PRIORITY</td>
<td>Takes a static expression as argument. It must appear in a task (type) specification or the outermost declarative part of a main program. It specifies the priority of the task (or tasks of the task type) or the main program (see 9.8).</td>
</tr>
<tr>
<td>STORAGE_UNIT</td>
<td>Takes an integer number as argument. This pragma can only appear before a library unit. It establishes the number of bits per storage unit (see 13.7).</td>
</tr>
</tbody>
</table>
SUPPRESS Takes a check name and optionally also either an object name or a type name as arguments. It must appear in the declarative part of a unit (block or body). It specifies that the designated check is to be suppressed in the unit. In the absence of the optional name, the pragma applies to all operations within the unit. Otherwise its effect is restricted to operations on the named object or to operations on objects of the named type (see 11.7).

SYSTEM Takes a name as argument. This pragma can only appear before a library unit. It establishes the name of the object machine (see 13.7).
C. Predefined Language Environment

This appendix outlines the specification of the package STANDARD containing all predefined identifiers in the language. The corresponding package body is implementation defined and is not shown.

package STANDARD is

type BOOLEAN is (FALSE, TRUE);

function "not" (X : BOOLEAN) return BOOLEAN;

function "and" (X.Y : BOOLEAN) return BOOLEAN;
function "or" (X.Y : BOOLEAN) return BOOLEAN;
function "xor" (X.Y : BOOLEAN) return BOOLEAN;

type SHORT_INTEGER is range implementation_defined;
type INTEGER is range implementation_defined;
type LONG_INTEGER is range implementation_defined;

function "+" (X INTEGER) return INTEGER;
function "-" (X INTEGER) return INTEGER;
function ABS (X : INTEGER) return INTEGER;

function "+" (X.Y INTEGER) return INTEGER;
function "-" (X.Y INTEGER) return INTEGER;
function "*" (X.Y : INTEGER) return INTEGER;
function "/" (X.Y : INTEGER) return INTEGER;
function "rem" (X.Y : INTEGER) return INTEGER;
function "mod" (X.Y : INTEGER) return INTEGER;
function "**" (X INTEGER; Y : INTEGER range 0..INTEGER'LAST) return INTEGER;

-- Similarly for SHORT_INTEGER and LONG_INTEGER

type SHORT_FLOAT is digits implementation_defined range implementation_defined;
type FLOAT is digits implementation_defined range implementation_defined;
type LONG_FLOAT is digits implementation_defined range implementation_defined;

function "+" (X : FLOAT) return FLOAT;
function "-" (X : FLOAT) return FLOAT;
function ABS (X : FLOAT) return FLOAT;

function "+" (X.Y : FLOAT) return FLOAT;
function "-" (X.Y : FLOAT) return FLOAT;
function "/" (X.Y : FLOAT) return FLOAT;
function "+" (X : FLOAT; Y : INTEGER) return FLOAT;

-- Similarly for SHORT_FLOAT and LONG_FLOAT
The following characters comprise the standard ASCII character set.
Character literals corresponding to control characters are not identifiers;
They are indicated in italics in this definition:

```ada
package ASCII is

  -- Control characters:

  NUL : constant CHARACTER := nul;
  SOH : constant CHARACTER := soh;
  STX : constant CHARACTER := stx;
  ETX : constant CHARACTER := etx;
  EOT : constant CHARACTER := eot;
  ENQ : constant CHARACTER := enq;
  ACK : constant CHARACTER := ack;
  BEL : constant CHARACTER := bel;
  BS  : constant CHARACTER := bs;
  HT  : constant CHARACTER := ht;
  LF  : constant CHARACTER := lf;
  VT  : constant CHARACTER := vt;
  FF  : constant CHARACTER := ff;
  CR  : constant CHARACTER := cr;
  SO  : constant CHARACTER := so;
  SI  : constant CHARACTER := si;
  DLE : constant CHARACTER := dle;
  DC1 : constant CHARACTER := dc1;
  DC2 : constant CHARACTER := dc2;
  DC3 : constant CHARACTER := dc3;
  DC4 : constant CHARACTER := dc4;
```
NAK : constant CHARACTER := nak;
SYN : constant CHARACTER := syn;
ETB : constant CHARACTER := eth;
CAN : constant CHARACTER := can;
EM : constant CHARACTER := em;
SUB : constant CHARACTER := sub;
ESC : constant CHARACTER := esc;
FS : constant CHARACTER := is;
GS : constant CHARACTER := gs;
RS : constant CHARACTER := rs;
US : constant CHARACTER := us;
DEL : constant CHARACTER := del;

-- Other characters
EXCLAM : constant CHARACTER := '!' ;
SHARP : constant CHARACTER := '#';
DOLLAR : constant CHARACTER := '$';
QUERY : constant CHARACTER := '?';
AT_SIGN : constant CHARACTER := '@';
L_BRACKET : constant CHARACTER := '[';
BACK_SLASH : constant CHARACTER :: '\';
R_BRACKET : constant CHARACTER := ']';
CIRCUMFLEX : constant CHARACTER := '^';
GRAVE : constant CHARACTER := '¨';
L_BRACE : constant CHARACTER := '{';
BAR : constant CHARACTER := '|';
R_BRACE : constant CHARACTER := '}';
TILDE : constant CHARACTER := '~';

-- Lower case letters
LC_A : constant CHARACTER := 'a';
...
LC_Z : constant CHARACTER := 'z';
end ASCII;

-- Predefined types and subtypes
subtype NATURAL is INTEGER range 1 .. INTEGER'LAST;
subtype PRIORITY is INTEGER range implementation_defined;

type STRING is array(NATURAL range <>) of CHARACTER;
type DURATION is delta implementation_defined range implementation_defined;

-- The predefined exceptions
CONSTRAINT_ERROR : exception;
NUMERIC_ERROR : exception;
SELECT_ERROR : exception;
STORAGE_ERROR : exception;
TASKING_ERROR : exception;
-- The machine dependent package SYSTEM

package SYSTEM is
    type SYSTEM_NAME is implementation_defined Enumeration_type;

    NAME: constant SYSTEM_NAME := implementation_defined;
    STORAGE : constant := implementation_defined;
    MEMORY_SIZE : constant := implementation_defined;
    MIN_INT : constant := implementation_defined;
    MAX_INT : constant := implementation_defined;

end SYSTEM;

for CHARACTER use -- 128 ASCII character set without holes
(0, 1, 2, 3, 4, 5, ..., 125, 126, 127);

pragma PACK(STRING);

end STANDARD;

Certain aspects of the predefined entities cannot be completely described in the language itself. For example, although the enumeration type BOOLEAN can be written showing the two enumeration literals FALSE and TRUE, the relationship of BOOLEAN to conditions cannot be expressed in the language.

The language definition predefines certain library units (other than the package STANDARD). These library units are:

- The package CALENDAR (see 9.8)
- The generic procedure SHARED_VARIABLE_UPDATE (see 9.11)
- The generic procedure UNCHECKED_DEALLOCATION (see 13.10.1)
- The generic function UNCHECKED_CONVERSION (see 13.10.2)
- The generic package INPUT_OUTPUT (see 14.2)
- The package TEXT_IO (see 14.4)
- The package LOW_LEVEL_IO (see 14.8)
D. Glossary

Access type An access type is a type whose objects are created by execution of an allocator. An access value designates such an object.

Aggregate An aggregate is a written form denoting a composite value. An array aggregate denotes a value of an array type; a record aggregate denotes a value of a record type. The components of an aggregate may be specified using either positional or named association.

Allocator An allocator creates a new object of an access type, and returns an access value designating the created object.

Attribute An attribute is a predefined characteristic of a named entity.

Body A body is a program unit defining the execution of a subprogram, package, or task. A body stub is a replacement for a body that is compiled separately.

Collection A collection is the entire set of allocated objects of an access type.

Compilation Unit A compilation unit is a program unit presented for compilation as an independent text. It is preceded by a context specification, naming the other compilation units on which it depends. A compilation unit may be the specification or body of a subprogram or package.

Component A component denotes a part of a composite object. An indexed component is a name containing expressions denoting indices, and names a component in an array or an entry in an entry family. A selected component is the identifier of the component, prefixed by the name of the entity of which it is a component.

Composite type An object of a composite type comprises several components. An array type is a composite type, all of whose components are of the same type and subtype; the individual components are selected by their indices. A record type is a composite type whose components may be of different types; the individual components are selected by their identifiers.

Constraint A constraint is a restriction on the set of possible values of a type. A range constraint specifies lower and upper bounds of the values of a scalar type. An accuracy constraint specifies the relative or absolute error bound of values of a real type. An index constraint specifies lower and upper bounds of an array index. A discriminant constraint specifies particular values of the discriminants of a record or private type.

Context specification A context specification, prefixed to a compilation unit, defines the other compilation units upon which it depends.

Declarative Part A declarative part is a sequence of declarations and related information such as subprogram bodies and representation specifications that apply over a region of a program text.

Derived Type A derived type is a type whose operations and values are taken from those of an existing type.

Discrete Type A discrete type has an ordered set of distinct values. The discrete types are the enumeration and integer types. Discrete types may be used for indexing and iteration, and for choices in case statements and record variants.

Discriminant A discriminant is a syntactically distinguished component of a record. The presence of some record components (other than discriminants) may depend on the value of a discriminant.

Elaboration Elaboration is the process by which a declaration achieves its effect. For example it can associate a name with a program entity or initialize a newly declared variable.
Entity  An entity is anything that can be named or denoted in a program. Objects, types, values, program units, are all entities.

Entry  An entry is used for communication between tasks. Externally an entry is called just as a subprogram is called; its internal behavior is specified by one or more accept statements specifying the actions to be performed when the entry is called.

Enumeration type  An enumeration type is a discrete type whose values are given explicitly in the type declaration. These values may be either identifiers or character literals.

Exception  An exception is an event that causes suspension of normal program execution. Bringing an exception to attention is called raising the exception. An exception handler is a piece of program text specifying a response to the exception. Execution of such a program text is called handling the exception.

Expression  An expression is a part of a program that computes a value.

Generic program unit  A generic program unit is a subprogram or package specified with a generic clause. A generic clause contains the declaration of generic parameters. A generic program unit may be thought of as a possibly parameterized model of program units. Instances (that is, filled-in copies) of the model can be obtained by generic instantiation. Such instantiated program units define subprograms and packages that can be used directly in a program.

Introduce  An identifier is introduced by its declaration at the point of its first occurrence.

Lexical unit  A lexical unit is one of the basic syntactic elements making up a program. A lexical unit is an identifier, a number, a character literal, a string, a delimiter, or a comment.

Literal  A literal denotes an explicit value of a given type, for example a number, an enumeration value, a character, or a string.

Model number  A model number is an exactly representable value of a real numeric type. Operations of a real type are defined in terms of operations on the model numbers of the type. The properties of the model numbers and of the operations are the minimal properties preserved by all implementations of the real type.

Object  An object is a variable or a constant. An object can denote any kind of data element, whether a scalar value, a composite value, or a value in an access type.

Overloading  Overloading is the property of literals, identifiers, and operators that can have several alternative meanings within the same scope. For example, an overloaded enumeration literal is a literal appearing in two or more enumeration types; an overloaded subprogram is a subprogram whose designator can denote one of several subprograms, depending upon the kind of its parameters and returned value.

Package  A package is a program unit specifying a collection of related entities such as constants, variables, types and subprograms. The visible part of a package contains the entities that may be used from outside the package. The private part of a package contains structural details that are irrelevant to the user of the package but that complete the specification of the visible entities. The body of a package contains implementations of subprograms or tasks (possibly other packages) specified in the visible part.

Parameter  A parameter is one of the named entities associated with a subprogram, entry, or generic program unit. A formal parameter is an identifier used to denote the named entity in the unit body. An actual parameter is the particular entity associated with the corresponding formal parameter in a subprogram call, entry call, or generic instantiation. A parameter mode specifies whether the parameter is used for input, output or input-output of data. A positional parameter is an actual parameter passed in positional order. A named parameter is an actual parameter passed by naming the corresponding formal parameter.
Pragma A pragma is an instruction to the compiler, and may be language defined or implementation defined.

Private type A private type is a type whose structure and set of values are clearly defined, but not known to the user of the type. A private type is known only by its discriminants and by the set of operations defined for it. A private type and its applicable operations are defined in the visible part of a package. Assignment and comparison for equality or inequality are also defined for private types, unless the private type is marked as limited.

Qualified expression A qualified expression is an expression qualified by the name of a type or subtype. It can be used to state the type or subtype of an expression, for example for an overloaded literal.

Range A range is a contiguous set of values of a scalar type. A range is specified by giving the lower and upper bounds for the values.

Rendezvous A rendezvous is the interaction that occurs between two parallel tasks when one task has called an entry of the other task, and a corresponding accept statement is being executed by the other task on behalf of the calling task.

Representation specification Representation specifications specify the mapping between data types and features of the underlying machine that execute a program. In some cases, they completely specify the mapping, in other cases they provide criteria for choosing a mapping.

Scalar types A scalar type is a type whose values have no components. Scalar types comprise discrete types (that is, enumeration and integer types) and real types.

Scope The scope of a declaration is the region of text over which the declaration has an effect.

Static expression A static expression is one whose value does not depend on any dynamically computed values of variables.

Subprograms A subprogram is an executable program unit, possibly with parameters for communication between the subprogram and its point of call. A subprogram declaration specifies the name of the subprogram and its parameters; a subprogram body specifies its execution. A subprogram may be a procedure, which performs an action, or a function, which returns a result.

Subtype A subtype of a type is obtained from the type by constraining the set of possible values of the type. The operations over a subtype are the same as those of the type from which the subtype is obtained.

Task A task is a program unit that may operate in parallel with other program units. A task specification establishes the name of the task and the names and parameters of its entries; a task body defines its execution. A task type is a specification that permits the subsequent declaration of any number of similar tasks.

Type A type characterizes a set of values and a set of operations applicable to those values and a set of operations applicable to those values. A type definition is a language construct introducing a type. A type declaration associates a name with a type introduced by a type definition.

Use clause A use clause opens the visibility to declarations given in the visible part of a package.

Variant A variant part of a record specifies alternative record components, depending on a discriminant of the record. Each value of the discriminant establishes a particular alternative of the variant part.

Visibility At a given point in a program text, the declaration of an entity with a certain identifier is said to be visible if the entity is an acceptable meaning for an occurrence at that point of the identifier.
E. Syntax Summary

2.3 identifier ::= letter ([underscore] letter_or_digit)
letter_or_digit ::= letter | digit
letter ::= upper_case_letter | lower_case_letter

2.4 numeric_literal ::= decimal_number | based_number
decimal_number ::= integer [integer] [exponent]
integer ::= digit ([underscore] digit)
exponent ::= E [+] integer | E - integer

2.4.1 based_number ::= base # based_integer [based_integer] # [exponent]
base ::= integer
based_integer ::= extended_digit ([underscore] extended_digit)
extended_digit ::= digit | letter

2.6 character_string ::= "[character]"

2.8 pragma ::= pragma_identifier [(argument [argument])]::
argument ::= [identifier] name

3.1 declaration ::= object_declaration | number_declaration
| type_declaration | subtype_declaration
| subprogram_declaration | package_declaration
| task_declaration | exception_declaration
| renaming_declaration

3.2 object_declaration ::= identifier_list [constant] subtype_indication [expression];
| identifier_list [constant] array_type_definition [expression];
number_declaration ::= identifier_list constant :: literal_expression;
identifier_list ::= identifier [identifier]

3.3 type_declaration ::= type_identifier [discriminant_part] is type_definition;
| incomplete_type_declaration
| type_definition ::= type_identifier [discriminant_part] is type_definition
| array_type_definition | record_type_definition | derived_type_definition
| enumeration_type_definition | integer_type_definition
| real_type_definition | access_type_definition
| type_mark ::= type_name | subtype_name

constraint ::= range_constraint | accuracy_constraint
| index_constraint | discriminant_constraint

3.4 derived_type_definition ::= new subtype_indication

3.5 range_constraint ::= range_range
range ::= simple_expression..simple_expression

3.5.1 enumeration_type_definition ::= (enumeration_literal [enumeration_literal])
enumeration_literal ::= identifier | character_literal

3.5.2 integer_type_definition ::= range_constraint

3.5.8 real_type_definition ::= accuracy_constraint
accuracy_constraint ::= floating_point_constraint | fixed_point_constraint

3.5.7 floating_point_constraint ::=
digits simple_expression..simple_expression..range_constraint

3.5.9 fixed_point_constraint ::=
digits simple_expression..range_constraint

3.6 array_type_definition ::= array [index [index]] of component_subtype_indication
| array index_constraint of component_subtype_indication
index ::=[type_mark range <>]
index_constraint ::= [discrete_range [discrete_range]]
| discrete_range ::= type_mark [range_constraint..range]

3.7 record_type_definition ::= record
| component_list
end record
| component_list ::= [component_declaration [variant_part]] [variant]
component_declaration ::= identifier_list subtype_indication [expression];
| identifier_list array_type_definition [expression];
37.1
discriminant_part :=
  (discriminant_declaration [: discriminant_declararion))

discriminant_declaration :=
  identifier_list : subtype_indicator [: = expression]

37.2
discriminant_constraint :=
  (discriminant_specification [: discriminant_specification))

discriminant_specification :=
  [discriminant_name [: discriminant_name] >> expression]

37.3
variant_part :=
  case discriminant_name is
    (when choice [: choice] =>
      component_list)
  end case;

choice := simple_expression | discrete_range | others

3.8
access_type_definition := access subtype_indicator

incomplete_type_declaration := type_identifier [discriminant_part]

3.9
declarative_part :=
  (declarative_item) (representation_specification) (program_component)

declarative_item := declaration | use_clause

program_component := body
  | package_declaration | task_declaration | body_stub

body := subprogram_body | package_body | task_body

4.1
name := identifier
  | indexed_component | slice
  | selected_component | attribute
  | function_call | operator_symbol

4.1.1
indexed_component := name(expression [: expression])

4.1.2
slice := name (discrete_range)

4.1.3
selected_component :=
  name_identifier | name.all | name_operator_symbol

4.1.4
attribute := name_identifier

4.2
literal :=
  numeric_literal | enumeration_literal | character_string | null

4.3
aggregate :=
  (component_association [: component_association])

component_association :=
  [choice [: choice] >> expression]

4.4
expression :=
  relation (and relation)
  | relation (or relation)
  | relation (xor relation)
  | relation (then relation)
  | relation (else relation)
  
relation :=
  simple_expression (relational_operator simple_expression)
  | simple_expression (not) in range
  | simple_expression (not) in subtype_indication

simple_expression := [binary_operation] term (addition_operator term)

term := factor (multiplying_operator factor)

factor := primary (primary)

primary :=
  literal | aggregate | name allocator function_call
  | type_conversion | qualified_expression | expression

4.5
logical_operator := and | or | xor

relational_operator := = | /= | < | <= | > | >=

adding_operator := + | - | &

unary_operator := + | - | not

multiplying_operator := * | / | mod | rem

exponentiating_operator := **

4.6
type_conversion := type_mark (expression)

4.7
qualified_expression :=
  type_mark (expression) | type_mark aggregate

4.8
allocator :=
  new type_mark (expression)
  | new type_mark aggregate
  | new type_mark discriminant_constraint
  | new type_mark index_constraint

5.1
sequence_of_statements := statement (statement)

statement :=
  (label) simple_statement | (label) compound_statement

simple_statement := null_statement
  | assignment_statement | exit_statement
  | return_statement | goto_statement
  | procedure_call | entry_call
  | delay_statement | abort_statement
  | raise_statement | code_statement
Syntax Summary

compound_statement ::= i f_statement | loop_statement | accept_statement | case_statement

if_statement ::= [ { label ::= << identifier >> } ] { null_statement ::= null; |
  block ::= block |
  accept_statement ::= accept_statement |
  case_statement ::= case_statement |
  loop_statement ::= loop_statement |
  select_statement ::= select_statement

5.1

subprogram_declarations ::= subprogram_specification |
  generic_subprogram_declaration |
  generic_subprogram_instantiation

subprogram_specification ::= |
  procedure_identifier [ formal_part ] |
  function_identifier [ formal_part ] return subtype

designator ::= identifier | operator_symbol |

operator_symbol ::= character_string |

formal_part ::= |
  (parameter_declaration [ parameter_declaration ] )

parameter_declaration ::= |
  identifier_list : mode subtype indication = expression |

mode ::= [ in ] | out | in out

6.3

subprogram_body ::= |
  subprogram_specification is |
  declarative_part |
  begin |
  sequence_of_statements |
  [ exception |
    [ exception_handler ] ] |
  end [ designator ];

6.4

procedure_call ::= |
  procedure_name [ actual_parameter_part ]; |

function_call ::= |
  function_name actual_parameter_part | function_name () |

actual_parameter_part ::= |
  (parameter_association [ parameter_association ] )

parameter_association ::= |
  [ formal_parameter => ] actual_parameter |

formal_parameter ::= identifier |

actual_parameter ::= expression

7.1

package_declaration ::= package_specification |
  | generic_package_declaration |
  | generic_package_instantiation

package_specification ::= |
  package_identifier is |
  declarative_item |
  [ private |
    declarative_item |
    representation_specification ] |
  end [ identifier ];

7.4

private_type_definition ::= [ limited ] private
8.4
use_clause :: = use package_name (, package_name);

8.5
renaming_declaration :: =
  identifier : type_mark renames name;
  | identifier : exception renames name;
  | package_identifier renames name;
  | task_identifier renames name;
  | subprogram_specification renames name;

9.1
task_declaration :: = task_specification

9.5
task_specification :: =
  task [type] [typedef] [is]
  (entry_declaration)
  (representation_specification)
  end [identifier];

task_body :: =
  task_body_identifier [declarative_part]
  begin
  sequence_of_statements
  exception [exception_handler]
  end [identifier];

9.3
delay_statement :: = delay simple_expression;

9.7
select_statement :: = selective_wait
  | conditional_entry_call | timed_entry_call

9.7.1
selective_wait :: =
  select [when condition ]
  | select_alternative
  | [or_when condition ]
  | select_alternative
  | else
  sequence_of_statements
  end select;

select_alternative :: =
  accept_statement [sequence_of_statements]
  | delay_statement [sequence_of_statements]
  | terminate

9.7.2
conditional_entry_call :: =
  select
  entry_call [sequence_of_statements]
  else
  sequence_of_statements
  end select;

9.7.3
timed_entry_call :: =
  select
  entry_call [sequence_of_statements]
  | delay_statement [sequence_of_statements]
  end select;

10.1
compilation :: = (compilation_unit)

compilation_unit :: =
  task_specification subprogram_declaration
  | task_specification subprogram_body
  | task_specification package_declaration
  | task_specification package_body
  | task_specification subunit

content_specification :: = (with_clause [use_clause])
  | with_clause [with unit_name , unit_name];

10.2
subunit :: = separate (unit_name) subunit_body

subunit_body :: =
  subprogram_body | package_body | task_body

body_stub :: =
  subprogram_specification is separate;
  | package_body_identifier is separate;
  | task_body_identifier is separate;

11.1
exception_declaration :: = identifier_list : exception;

11.2
exception_handler :: =
  when exception_choice [ exception_choice ] =>
  sequence_of_statements

exception_choice :: = exception_name | others

11.3
raise_statement :: = raise [exception_name];

12.1
generic_subprogram_declaration :: =
  generic_part subprogram_specification;

generic_package_declaration :: =
  generic_part package_specification;

generic_part :: = generic [generic_parameter]

parametric_format_parameter :: =
  parameter_specification
  | type_identifier [discriminant_part] is generic_type_definition;
  | with subprogram_specification [is name];
  | with subprogram_specification in (1);

generic_type_definition :: =
  ( ) | range ( ) | delta ( ) | digits ( )
  | array_type_definition | access_type_definition
  | private_type_definition

12.2
12.3

generic_subprogram_instantiation ::= 
  procedure identifier is generic instantiation;
  | function designator is generic instantiation;

generic_package_instantiation ::= 
  package identifier is generic instantiation;

generic_instantiation ::= 
  new name [generic_association [ generic_association ]]

generic_association ::= 
  [formal_parameter => ] generic_actual_parameter

generic_actual_parameter ::= 
  expression | subprogram_name | subtype indication

13.1

representation_specification ::= 
  length_specification [ enumeration_type_representation ]
  | record_type_representation [ address_specification ]

13.2

length_specification ::= for attribute use expression;

13.3

enumeration_type_representation ::= for type_name use aggregates;

13.4

record_type_representation ::= 
  for type_name use
    record [ alignment_clause ]
    [ component_name location ]
  end record;

global_clause ::= at static_simple_expression range range

13.5

address_specification ::= for name use at static_simple_expression;

13.6

code_statement ::= qualified_expression;
F. Implementation Dependent Characteristics

This appendix is to be supplied in the reference manual of each Ada implementation. The Ada language definition allows for certain machine dependences in a controlled manner. No machine dependent syntax or semantic extensions or restrictions are allowed. The only allowed implementation dependences correspond to implementation dependent pragmas and attributes, certain machine dependent values and conventions as mentioned in chapter 13, and certain allowed restrictions on representation specifications.

The appendix F for a given implementation must list in particular:

(1) The form, allowed places, and effect of every implementation dependent pragma.
(2) The name and the type of every implementation dependent attribute.
(3) The specification of the package SYSTEM.
(4) the list of all restrictions on representation specifications (see 13.1)
(5) The conventions used for any system generated name denoting system dependent components (see 13.4).
(6) The interpretation of expressions that appear in address specifications, including those for interrupts, (see 13.5).
(7) Any restriction on unchecked conversions (see 13.10.2).
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