AN IMPROVED COHERENT PROCESSOR FOR AMBIGUITY FUNCTION DISPLAY, (U)

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A coherent optical processor for displaying a signal's ambiguity function is described. The required time delay is simulated by 45 degree rotations of two identical input transparencies, and the doppler shift by a subsequent one-dimensional Fourier transform. The entire ambiguity function is displayed in the output (doppler-shift-time delay) plane. Examples of the optically computed ambiguity function for single and double pulse signals are shown to be in excellent agreement with theory. Advantages of this approach over other schemes, and possible extension to real time processing, are also discussed.

Introduction

The ambiguity function, first introduced by Woodward, has been applied in radar in predicting the capability of a given signal to simultaneously determine the range and velocity of a target. The range is determined by the time delay, \( t \), and the velocity by the doppler shift, \( \nu \). The ambiguity function for a given signal, \( f(t) \), is

\[
x(v,\nu) = \int f(t) f(t-\nu) e^{-j2\pi \nu t} dt
\]  

(1)

In optics, Papoulis has employed the ambiguity function in analyzing diffraction phenomena.

In this paper, we describe a rather easily implemented coherent processor capable of generating the ambiguity function in magnitude. A similar, yet somewhat more elaborate, scheme for generating \( x(v,\nu) \) in both magnitude and phase is also presented. Such a scheme, for example, would need to be utilized when further coherent processing of the ambiguity function is required.

Cutrona et al. and Preston have proposed a coherent ambiguity function processor which utilizes multiple channels to display the ambiguity function for discrete values of \( \nu \). The scheme of Casasent et al. generates one-dimensional "slices" of the ambiguity function in the \( (v,\nu) \) plane. Similar one-dimensional displays have also been electronically produced. Our method, as described in the following sections, (1) displays \( |x(v,\nu)|^2 \) in a continuous (rather than quantized) form over the entire \( (v,\nu) \) plane, (2) has the capacity for extension to real time processing, and (3) is easily implemented.

Implementation Scheme

The coherent processor capable of displaying the ambiguity function (in magnitude) is pictured in Fig. 1. The field amplitude, \( U(v,\nu) \), in plane \( P_2 \) is related to the coherently illuminated transparency, \( S(v,\nu) \), in plane \( P_1 \) by a one-dimensional Fourier transform:

\[
U(v,\nu) = \int S(v,\nu) e^{-j2\pi \nu t} dt
\]  

(2)

where \( \lambda \) is the wavelength of the spatially coherent illumination, \( f \) is the focal length of both lenses \( L_1 \) and \( L_2 \), and the spatial frequency \( \nu \) is related to the horizontal displacement, \( x_2 \), on plane \( P_2 \) by

\[
\nu = \frac{x_2}{\lambda f}
\]  

(3)

By an appropriate choice of an input, this coherent processor will be shown to have the capability of ambiguity function display.

Consider, then, the one-dimensional temporal signal \( f(t) \) in Fig. 2a and its representation on the \((t,\nu)\) plane [Fig. 2b]. By rotating this function counterclockwise about the origin an angle of \( \theta \) [Fig. 2c], we generate the function

\[
f(t\cos\theta - \nu\sin\theta)
\]

Thus, for a rotation of 45 degrees, we obtain \( f((t + \nu)/\sqrt{2}) \), and for a rotation of -45 degrees, we obtain \( f((t - \nu)/\sqrt{2}) \). If we cascade transparencies of these two functions, in the input plane of the processor of Fig. 1 so as to form the product \( f((t + \nu)/\sqrt{2}) f((t - \nu)/\sqrt{2}) \), then, from Eq. 2, the resulting output is

\[
U(v,\nu) = \exp(-j2\pi \nu v^2) \int \frac{f(t - \nu)}{\sqrt{2}} \frac{f(t + \nu)}{\sqrt{2}} e^{-j2\pi \nu t} dt
\]  

(4)

where we have made the change of variable

\[
t' = \frac{t + \nu}{\sqrt{2}}
\]

The intensity distribution associated with Eq. 4 is immediately recognized as a scaled version of the squared modulus of the ambiguity function:

\[
I(v,\nu) = |U(v,\nu)|^2
\]  

(5)

Experimental Results

To evaluate the performance of the proposed processor, the ambiguity functions for a single and double pulse signal are evaluated analytically and compared to the corresponding optical system outputs. In practice, the processor output is magnified by conventional means for observation and photographic purposes.

For a Single Pulse

For a single pulse, (Fig. 3a), we may write

\[
f(t) = \text{rect}(t/2T)
\]  

(6)
where $2T$ is the pulse duration and

$$\text{rect}(t) = \begin{cases} 1 & \text{if } |t| \leq 1/2 \\ 0 & \text{if } t > 1/2 \end{cases}$$

The geometric interpretation of $f(t)$, $f(t - \tau)$, and $f(t - \tau_1)f(t - \tau_2)$ are shown in Figs. 3a, 3b and 3c respectively.

Substituting Eq. 6 into Eq. 1 followed by evaluation yields the ambiguity function

$$x(v, \tau) = \{2(2T - |\tau|)|\text{sinc}(2T - |\tau|)\exp(-j\pi v v)|\tau| \leq 2T \\ 0 \quad \text{if } |\tau| > 2T$$

(7)

where $\text{sinc} v = \sin(v)/v$. The corresponding output intensity is

$$|x(v, \tau)|^2 = \{4(2T - |\tau|)^2|\text{sinc}^2(2T - |\tau|)\cos^2(4\piTv) ; |\tau| \leq 2T \\ (2T - |\tau|)^2|\text{sinc}^2(2T - |\tau|)\ ; 2T \leq |\tau| \leq 4T \\ (6T - |\tau|)^2|\text{sinc}^2(6T - |\tau|)\ ; 4T \leq |\tau| \leq 6T \\ 0 \quad \text{if } |\tau| > 6T$$

(8)

For a Double Pulse

For a double pulse, (Fig. 6a), we write

$$f(t) = \text{rect}(t + 2T/2T) + \text{rect}(t - 2T/2T)$$

(10)

where, for convenience, the pulse separation, $2T$, has been chosen to be equal to each of the pulse widths. The geometric interpretation of $f(t - \tau_1)f(t - \tau_2)$ is shown in Fig. 6b. The ambiguity function associated with the double pulse is

$$x(v, \tau) = \{2(2T - |\tau|)|\text{sinc}(2T - |\tau|)\cos(4\piTv)\exp(-j\pi v v) ; |\tau| \leq 2T \\ -2(2T - |\tau|)|\text{sinc}(2T - |\tau|)\exp(-j\pi v v) ; 2T \leq |\tau| \leq 4T \\ (6T - |\tau|)|\text{sinc}(6T - |\tau|)\exp(-j\pi v v) ; 4T \leq |\tau| \leq 6T \\ 0 \quad \text{if } |\tau| > 6T$$

(11)

The corresponding output intensity is

$$|x(v, \tau)|^2 = \{4(2T - |\tau|)^2|\text{sinc}^2(2T - |\tau|)\cos^2(4\piTv) ; |\tau| \leq 2T \\ (2T - |\tau|)^2|\text{sinc}^2(2T - |\tau|)\ ; 2T \leq |\tau| \leq 4T \\ (6T - |\tau|)^2|\text{sinc}^2(6T - |\tau|)\ ; 4T \leq |\tau| \leq 6T \\ 0 \quad \text{if } |\tau| > 6T$$

(12)

The equations describing the zero-value loci are easily shown to be

$$v = (2n + 1)/8T \quad |\tau| \leq 2T$$

$$v = n/(|\tau| - 2T) \quad |\tau| \leq 4T$$

$$v = n/(6T - |\tau|) \quad 4T \leq |\tau| \leq 6T$$

(13)

where $m$ is any integer and, as before, $n$ is any non-zero integer. An illustration of these zero-value loci is presented in Fig. 7.

By appropriately placing two identical double slits in planes $P_1$ and $P_2$ of the coherent processor, the ambiguity function for the double pulse is generated. The result, shown in Fig. 8, again compares quite favorably with the theory.

An Alternate Scheme

The coherent processor just discussed, is capable of displaying the ambiguity function only in magnitude. That is, quadratic and linear phase factors are present on the output plane [see Eq. 4].

A processor capable of generating the ambiguity function both in magnitude and phase is presented in Fig. 9. The scaling lenses $L_1$ and $L_2$ have respective focal lengths related by

$$f_1 = \sqrt{2} f_2$$

(14)

The field amplitude incident on the left of plane $P_2$ is the desired $f(t - \tau)$. This will multiply the transmittance $f(t)$ plane $P_2$ to give immediately to the right of $P_2$ the field amplitude $f(t)f(t - \tau)$. The geometrical interpretation of this product in the $(t, \tau)$ plane, for the case of a single pulse, is shown in Fig. 10.

With reference to Eq. 1, it remains to perform a Fourier transformation with respect to $\tau$. This is accomplished with cylindrical lenses $L_a$, $L_b$, and $L_c$ which have respective focal lengths of

$$2f_a = 2f_b = 2f_c$$

(15)

One sees that, from plane $P_2$ to $P_3$, imaging is performed in the vertical direction by $L_b$ and $L_c$ while Fourier
transformation is independently performed in the horizontal direction by \( L \). Thus, the field amplitude, \( U(v,i) \), in plane \( P_3 \) is a scaled version of the ambiguity function:

\[
U(v,i) = \int f(t)f(t - \tau)\exp(-j2\pi vt) \, dt
\]

where \( v \) is related to the horizontal displacement, \( x_3 \), in \( P_3 \) by

\[
v = x_3/\lambda f
\]

This ambiguity function processor, which is more elaborate than that shown in Fig. 2, need be used only when the ambiguity function's magnitude and phase are required.

As a final note, we observe that the scheme we propose assumes that \( f(t) \) is real valued. If, in fact, \( f(t) \) is complex, then we need to generate \( f^*(t - \tau) \) in the integrand of Eq. 1 in order to properly generate \( x(v,i) \). Some additional work appears needed for the case of a general complex-valued \( f(t) \).

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References
6. The "ambiguity function processors" in Refs. (4-5, 7-8) should rigorously be called uncertainty function processors in that they are only capable of displaying the uncertainty function \( |x(v,i)| \). Following this precedent, we herein refer to both \( x(v,i) \) and \( |x(v,i)| \) as the ambiguity function. The actual function to which reference is made is clear in the context of the paper.
10. The squared modulus of the ambiguity function is sometimes also referred to as the ambiguity function.
Fig. 4. Zero locus plot of the ambiguity function of a single pulse.

Fig. 5. The ambiguity function (modulus squared) display for a single pulse, as generated by the coherent processor of Fig. 2.

Fig. 6. (a) A double pulse. (b) The corresponding function \( f(t + t_0)f(t - t_0) \) on the \((t,\tau)\) plane.

Fig. 7. Zero locus plot of the ambiguity function of a double pulse.

Fig. 8. The ambiguity function (modulus squared) display for a double pulse as generated by the coherent processor of Fig. 2.

Fig. 9. Coherent processor for generating the ambiguity function in phase and amplitude. Scaling lenses \( L_1 \) and \( L_2 \) have a focal length relation \( f_1 = \sqrt{2}f_2 \).

Fig. 10. The product \( f(t)f(t - \tau) \) on the \((t,\tau)\) plane for the single pulse of Fig. 3a.
A coherent optical processor for displaying a signal's ambiguity function is described. The required time delay is realized by 45 rotations of two identical input transparencies, and the Doppler shift by a 1-D Fourier transformation. The modulus squared of the entire ambiguity function is displayed in the output plane. Examples of the optically computed ambiguity functions for single and double pulse signals are shown to be in excellent agreement with the theory. Advantages of this approach over various alternative schemes are discussed.