Minimax Subset Selection with Applications to Unequal Variance Problems*

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1. INTRODUCTION

Let \( X_1, \ldots, X_k \) be observations from populations whose distributions are determined by unknown real parameters \( \theta_1, \ldots, \theta_k \). In a subset selection problem, the goal is to select a subset of the populations which includes the population associated with the largest parameter with "high" probability and includes the other populations with "low" probability. In this paper, rules are found which are minimax in the class of non-randomized, just, and translation invariant rules when risk is measured by the maximum probability of including a non-best population. These rules are of the form proposed and studied by Gupta (1965) in location and scale parameter problems. In many cases, these rules are the unique minimax rule in the class and, hence are also admissible in this class. These results are applied to the normal means problem with known unequal variances (or unequal sample sizes). Comparison of several proposed rules is made. A rule proposed by Gupta and Huang (1976) is found to be minimax. A generalization of the rule, proposed by Gupta and Wong (1976), is likewise minimax. Other rules, proposed by Chen and Dudewicz (1973) and Gupta and Huang (1974), are shown to be not minimax.

2. NOTATION AND FORMULATION

Let \( \mathbf{X} = (X_1, \ldots, X_k) \) be a random vector with cumulative distribution function (c.d.f.) \( F(\mathbf{x} - \theta) \) and density \( f(\mathbf{x} - \theta) \) with respect to Lebesgue measure on \( \mathbb{R}^k \). \( \theta \in \Theta = \mathbb{R}^k \) is the unknown location parameter. Let \( \theta[1] \leq \ldots \leq \theta[k] \) denote the ordered coordinates of \( \theta = (\theta_1, \ldots, \theta_k) \). This
induces the partition $\theta = \Theta_1 \cup \ldots \cup \Theta_k$ of the parameter space where $\theta_i = \{ \theta : \theta_i = \theta[k] \}$. Let $\pi_1, \ldots, \pi_k$ denote the $k$ populations which give rise to observations $X_1, \ldots, X_k$, respectively, and let $\pi(i)$ denote the (unknown) population associated with $\theta[i]$. The goal in a subset selection problem is to find rules which select a subset of the populations which includes the "best" population $\pi(k)$ with "high" probability and includes the "non-best" populations $\pi(1), \ldots, \pi(k-1)$ with "low" probability, regardless of the true parameter value. In general, a selection rule will be denoted by $\varphi(x) = (\varphi_1(x), \ldots, \varphi_k(x))$ where $\varphi_i(x) : x \rightarrow [0,1]$ is the probability that $\pi_i$ is included in the selected subset when $X = x$ is observed.

Selecting a subset which contains the best population is called a correct selection, CS. To insure a "high" probability of making a CS, we will consider only those rules which satisfy the $P^*$-condition, viz.,

\begin{equation}
\inf_{\theta} P_\theta (\text{CS} | \varphi) \geq P^*,
\end{equation}

where $\frac{1}{k} < P^* < 1$ is a pre-assigned fixed number. The risk function we will use, to reflect the fact that we want the non-best populations to be included with "low" probability, is

\begin{equation}
M(\theta, \varphi) = \max_{1 \leq i < j-1} P_\theta (\text{select } \pi(i) | \varphi).
\end{equation}

3. JUST AND INVARIANT RULES AND AN ORDERING OF DISTRIBUTIONS

In this section, two classes of selection rules are defined. An ordering of distributions is also introduced. Some preliminary lemmas are presented.
Definition 3.1. A selection rule is **just** if for every \( i = 1, \ldots, k \), 
\( q_i(x_1, \ldots, x_k) \) is a non-decreasing function of \( x_i \) and a non-increasing function of \( x_j, j \neq i \).

The concept of justness is appealing if the best population is the one associated with the largest parameter value and an increase of a parameter value causes the corresponding observation to be stochastically larger. Location parameters are common examples of this monotonic behavior. Just rules were defined and investigated in more generality by Nagel (1970) and Gupta and Nagel (1971).

Definition 3.2. A selection rule is translation invariant if for every \( x \in \mathbb{R}^k \), for every \( c \in \mathbb{R} \) and for every \( i = 1, \ldots, k \), 
\( q_i(x_1+c, \ldots, x_k+c) = q_i(x_1, \ldots, x_k) \).

Since the sets \( \Theta_1, \ldots, \Theta_k \) are translation invariant, restriction to translation invariant rules is reasonable. Lemma 3.1 provides a useful characterization of selection rules which are both just and translation invariant.

**Lemma 3.1.** A selection rule, \( q(x) = (q_1(x), \ldots, q_k(x)) \), is just and translation invariant if and only if the following two conditions hold:

(i) for every \( i = 1, \ldots, k \), \( q_i \) is a function only of the set of differences 
\( \{x_j - x_i : j = 1, \ldots, k, j \neq i\} \),
(ii) if \( x \) and \( y \) satisfy \( x_j - x_i \leq y_j - y_i \) for every \( j \neq i \), then \( q_i(x) \geq q_i(y) \).

**Proof.** \( q \) is translation invariant if and only if (i) holds because the differences are a maximal invariant for the translation group (see Lehmann (1959) p. 216). Suppose \( q \) is just and translation invariant. Let \( x \) and \( y \) be as in (ii). Using first invariance and then justness yields
\[ \varphi_1(x) = \varphi_1(x_1 - x_i + y_i, \ldots, x_k - x_i + y_i) \]
\[ = \varphi_1(x_1 - x_i + y_i, \ldots, y_i, \ldots, x_k - x_i + y_i) \]
\[ \geq \varphi_1(y_1, \ldots, y_i, \ldots, y_k) = \varphi_1(y) \]

so (ii) is true.

Now suppose (ii) is true. Fix \( x \in \mathbb{R}^k \), \( \varepsilon \geq 0 \) and \( i \neq j \). Then
\( x_j + \varepsilon - x_i \geq x_j - x_i \) and all other differences are equal so by (ii),
\[ \varphi_1(x_1, \ldots, x_k) \geq \varphi_1(x_1, \ldots, x_j + \varepsilon, \ldots, x_k), \]
\[ \text{i.e., } \varphi \text{ is non-increasing in } x_j, j \neq 1. \]
Also, \( x_j - (x_i + \varepsilon) \leq x_j - x_i \) for every \( j \neq i \) so by (ii),
\[ \varphi_1(x_1, \ldots, x_j + \varepsilon, \ldots, x_k) \geq \varphi_1(x_1, \ldots, x_i, \ldots, x_k), \]
\[ \text{i.e., } \varphi \text{ is non-decreasing in } x_i. \]
Hence \( \varphi \) is just

The following ordering of distributions was introduced by Lehmann (1952) and further investigated by Lehmann (1955). See also Alam (1973).

**Definition 3.3.** A subset \( A \subset \mathbb{R}^k \) is **monotone** if \( x \in A \) and \( y \) satisfies
\[ y_i \leq x_i \text{ for all } i = 1, \ldots, k \imply \text{} y \in A. \]

**Definition 3.4.** A family of probability distributions on \( \mathbb{R}^k \),
\( \{F_\theta : \theta \in \Theta \subset \mathbb{R}^k\} \), has the **stochastic increasing property (SIP)** if
\( \theta \in \Theta, \theta' \in \Theta, \text{ and } \theta_i \leq \theta'_i \text{ for all } i = 1, \ldots, k \imply \)
\[ P_\theta(A) = \int_A dF_\theta \geq \int_A dF_{\theta'}, = P_{\theta'}(A) \]

for all monotone sets \( A \).

In Lemma 3.1 it was shown that if a selection rule is translation
invariant, then the rule is a function only of the differences of the
observations. Thus the distribution of this random vector of differences
is of interest. Lemma 3.2 shows that this vector has the SIP. Lehmann
(1955) showed that if $\theta$ is a location parameter, then the family
$\{F_{\theta} : \theta \in \Theta\}$ has the SIP. This fact is used in the proof of Lemma 3.2.

**Lemma 3.2.** Suppose $\theta \in \mathbb{R}^k$ is a location parameter in the distribution
of $X = (X_1, \ldots, X_k)$. Then the distribution of $X^* = (X_1 - X_i, \ldots, X_{i-1} - X_i,$
$X_{i+1} - X_i, \ldots, X_k - X_i)$ depends on $\theta$ only through the parameter
$\theta^* = (\theta_1 - \theta_i, \ldots, \theta_{i-1} - \theta_i, \theta_{i+1} - \theta_i, \ldots, \theta_k - \theta_i)$ and the family of distributions
of $X^*$ has the SIP in terms of $\theta^*$.

**Proof.** Let $Y$ be a random vector with the same distribution as $X$ has
if $\theta = (0, \ldots, 0)$. Let $G$ be the c.d.f. of $(Y_1 - Y_i, \ldots, Y_{i-1} - Y_i, Y_{i+1} - Y_i, \ldots,$
$Y_k - Y_i)$ and $G_{\theta}$ be the c.d.f. of $X^*$. Then $(Y_1 + \theta_1, \ldots, Y_k + \theta_k)$ has the same
distribution as $X$ so, for any constants $c_1, \ldots, c_k$,

$$G_{\theta}(c_1, \ldots, c_k) = P_{\theta}(X_1 - X_i \leq c_1, \ldots, X_k - X_i \leq c_k)$$

$$= P(Y_1 + \theta_1 - Y_i - \theta_i \leq c_1, \ldots, Y_k + \theta_k - Y_i - \theta_i \leq c_k)$$

$$= G(c_1 - (\theta_1 - \theta_i), \ldots, c_k - (\theta_k - \theta_i)).$$

So the distribution of $X^*$ depends only on $\theta^*$ and in fact $\theta^*$ is a location
parameter. By Lehmann's result, the family of distributions has the SIP.

**4. MINIMAXITY AND ADMISSIBILITY OF SELECTION RULES**

A non-randomized selection rule is one for which $\pi_i(x) \in \{0, 1\}$ for
all $x \in \mathbb{R}^k$ and all $i$. Thus a non-randomized rule is completely determined
by $k$ sets $A_1, \ldots, A_k$ where $A_i = \{x : \pi_i(x) = 1\}$ is the set of observations
for which $i$ is included in the selected subset. By Lemma 3.1, a non-
randomized rule is just and translation invariant if and only if $x \in A_i$.
or \( x \in A^C \) (\( A^C \) denotes the complement of \( A \)) can be determined from only the differences \( \{x_j - x_i: j \neq i\} \) and \( A_i \) is monotone in these differences. In determining a rule which is minimax with respect to \( M \), the quantity to be minimized is

\[
\sup M(\theta, \phi) = \sup_{\Theta} \max_{1 \leq i < k-1} P_\theta(\text{select } \pi(i) | \phi)
\]

\[
= \max_{1 \leq i < k} \sup_{\Theta} P_\theta(\text{select } \pi_i | \phi)
\]

\[
= \max_{1 \leq i < k} \sup_{\Theta} P_\theta(A_i).
\]

This can be minimized by choosing sets \( A_i \) to minimize each of the terms \( \sup_{\Theta} P_\theta(A_i) \) separately with the restriction

\[
\inf_{\Theta} P_\theta(A_i) \geq P^* \quad \text{so the } P^*-\text{condition is satisfied. The form of the set which does this minimizing is given by Theorem 4.1 which is an extension of Lehmann's (1952) Theorem 4.1.}
\]

**Theorem 4.1.** Let the joint distribution of \( (Y_1, \ldots, Y_k) \) be \( F_Y(y_1, \ldots, y_k) \) where the parameter space is the finite or infinite open rectangle \( \gamma_i < y_i < \bar{\gamma}_i \) and the sample space is the finite or infinite open rectangle \( \gamma_i < y_i < \bar{\gamma}_i \), independent of the \( y \). Suppose \( P_\gamma(S) \) is a continuous function of \( y \) for any set of the form (4.5). Suppose the family \( \{F_Y\} \) has the SIP, that the marginal distribution of \( Y_1 \) depends only on \( \gamma_i \) and that \( Y_1 \) converges in probability to \( \gamma_i \) as \( \gamma_i \rightarrow \gamma_i \). Let \( \gamma^* = (\gamma_1^*, \ldots, \gamma_k^*) \) be a fixed parameter point and define

\[
\Gamma = \{\gamma: \gamma_i \leq \gamma_i^*, i = 1, \ldots, k\}.
\]

Let \( \Phi \) be the collection of all monotone sets which satisfy
Then a region $S^* \in \mathcal{S}$ which satisfies

$$
(4.4) \quad \sup_{\gamma^*} P_{\gamma^*}(S^*) = \inf_{\gamma} \sup_{S} P_{\gamma}(S)
$$

is given by

$$
(4.5) \quad S^* = \{y: y_i \leq a_i, i = 1, \ldots, k\},
$$

where the constants $a_i$ are determined by

$$
(4.6) \quad P_{\gamma^*}(S^*) = p^*
$$

and

$$
(4.7) \quad P_{\gamma^*}(y_1 \leq a_1) = P_{\gamma^*}(y_2 \leq a_2) = \ldots = P_{\gamma^*}(y_k \leq a_k).
$$

Furthermore, if for every $i$, the distribution of $Y_i$ given $\gamma_i$ has the entire interval $(\underline{y}_i, \bar{y}_i)$ as its support, the region $S^*$ is the essentially unique element of $\mathcal{S}$ which is minimax, i.e., satisfies (4.4).

**Proof.** For any set of constants $y_j > \underline{y}_j$ and any $i = 1, 2, \ldots, k$

$$
(4.8) \quad \lim_{\gamma_j \to \underline{y}_j, j \neq i} \frac{P_{\gamma}(y_1 \leq y_1, \ldots, y_k \leq y_k)}{P_{\gamma_i}(y_i \leq y_i)} = p_{\gamma_i}(y_i \leq y_i)
$$

because
\[
P(Y_1 \leq Y_1, \ldots, Y_k \leq Y_k) = P(Y_1 \leq Y_1) - P(Y_1 \leq Y_1, Y_j > y_j) \text{ for at least one } j \neq i
\]
\[
\geq P(Y_1 \leq y_1) - \sum_{j \neq i} P(Y_j > y_j)
\]
and every term \( P(Y_j > y_j) \) converges to zero in the limit of (4.8) because of the convergence in probability. The \( \leq \) inequality is immediate.

For an \( S \in S \), the SIP implies that \( \lim_{Y_j \to y_j} P(S) \) exists and the limit
\[
\lim_{Y_j \to y_j} P(S|Y_1)
\]
will be denoted by \( B_i(S|Y_1) \). The SIP also implies that
\[
(4.9) \quad \sup_{\gamma} P(S) \geq \max_{1 \leq i \leq k} B_i(S|Y_1^*)
\]
and because of the continuity, for sets of the form (4.5)
\[
\sup_{\gamma} P(S^*) = \max_{1 \leq i \leq k} B_i(S^*|Y_1^*).
\]
Since for the region \( S^* \) given by (4.5), (4.7) and (4.8) imply that
\[
B_1(S^*|Y_1^*) = B_2(S^*|Y_2^*) = \ldots = B_k(S^*|Y_k^*),
\]
if the theorem were false, an \( S \in S \) could be found which simultaneously decreases all \( k \) quantities. But this can not happen. For let \( S \in S \). Let \( \gamma \in S \cap S^C \). (Such a \( \gamma \) exists unless \( S \) is essentially the same as \( S^* \) because of (4.3) and (4.6).) For some \( i = 1, 2, \ldots, k \), \( y_i > a_i \) since \( \gamma \in S^C \)
\[
(4.10) \quad P(S^* \cap S^C) \leq P( \cup_{j \neq i} (Y_i \leq a_i, Y_j > y_j))
\]
\[
\begin{align*}
&\leq \sum_{j \neq i} P(Y_i \leq a_i, Y_j > y_j) \\
&\leq \sum_{j \neq i} P(Y_j > y_j).
\end{align*}
\]

As \(\gamma_j + \lambda_j\), all the terms \(P_{\gamma_j}(Y_j > y_j) \to 0\).

\[
B_i(S | \gamma_i) = \lim_{\gamma_j \to \lambda_j} P(S | \gamma_1, \ldots, \gamma_i, \ldots, \gamma_k)
\]

(4.11)

\[
= \lim_{\gamma_j \to \lambda_j} P(S^*) + \lim_{\gamma_j \to \lambda_j} P(S \cap S^*) - \lim_{\gamma_j \to \lambda_j} P(S^* \cap S^C)
\]

\[
= B_i(S^* | \gamma_i) + \lim_{\gamma_j \to \lambda_j} P(S \cap S^*) - \lim_{\gamma_j \to \lambda_j} P(S^* \cap S^C).
\]

From (4.10) the last limit is zero, so \(B_i(S | \gamma_i) \geq B_i(S^* | \gamma_i)\) and the first part of the theorem is proven.

Furthermore,

\[
P(S \cap S^C) \geq P(Y_1 \leq y_1, \ldots, Y_i \leq y_i, \ldots, Y_k \leq y_k)
\]

\[
- P(Y_1 \leq y_1, \ldots, Y_i \leq a_i, \ldots, Y_k \leq y_k).
\]

As \(\gamma_j \to \lambda_j, j \neq i\), by (4.8) the right hand side converges to

(4.12)

\[
P_{\gamma_i}(Y_i \leq y_i) - P_{\gamma_i}(Y_i \leq a_i).
\]

So if the support of the distribution of \(Y_i\) given \(\gamma_i^*\) is the entire interval
(\gamma_i, \bar{\gamma}_i), (4.12) is greater than zero and by (4.11), \beta_i(S|\gamma_i^*) > \beta_i(S^*|\gamma_i^*).

Hence by (4.9)

\begin{equation}
\sup_{\tau \subset \gamma_i} \mathbb{P}(S) > \sup_{\tau \subset \gamma_i} \mathbb{P}(S^*)
\end{equation}

and \( S^* \) is the essentially unique element of \& which is minimax. ||

The form of the region \( S^* \) in Theorem 4.1 becomes particularly simple
if the joint distribution of \( (Y_1, ..., Y_k) \) is symmetric (i.e., the random
variables are exchangeable) given \( \gamma^* \). Then (4.7) implies \( a_1 = ... = a_k = a \)
where \( a \) is determined by (4.6) and the minimax region is

\begin{equation}
S^* = \{ y : \max_{1 \leq i \leq k} y_i \leq a \}.
\end{equation}

The following selection rule has been proposed and studied by Gupta (1965).

**Definition 4.1.** Define the selection rule \( R_1 \) by

\[ R_1: \text{select } \pi_i \text{ if } x_i \geq \max_{1 \leq j \leq k} x_j - d \]

where \( d \) is chosen to be the smallest positive constant such that the \( P^* \)-condition (2.1) is satisfied.

Theorem 4.1 can be used to show that \( R_1 \) is minimax and admissible with
respect to \( M \) in a restricted class of rules.

**Theorem 4.2.** Let \( X = (X_1, ..., X_k) \) have a density \( f(x - \theta), \theta \in \mathbb{R}^k \) with
respect to Lebesque measure \( \mu \) on \( \mathbb{R}^k \). Suppose the support of \( f \) is \( \mathbb{R}^k \) and
f is symmetric (i.e., the random variables are exchangeable if \( \theta_1 = \ldots = \theta_k \)). Then \( R_1 \) is minimax with respect to \( M \) in the class of non-randomized, just, and translation invariant rules which satisfy the \( P^* \)-condition. Furthermore \( R_1 \) is the unique minimax rules in this class so \( R_1 \) is admissible in this class.

**Proof.** Fix \( i = 1, \ldots, k \). Let \( Y_i = X_i - X_i, \ldots, Y_{k-1} = X_k - X_i \) (omitting \( X_i - X_i \)) and \( \gamma_1 = \theta_1 - \theta_i, \ldots, \gamma_{k-1} = \theta_k - \theta_i \) (omitting \( \theta_i - \theta_i \)). As explained at the beginning of this section, by Lemma 3.1 a rule is non-randomized, just, and translation invariant if and only if it is of the form

\[
q_i(x) = \begin{cases} 
1 & \text{if } x \in S_i \\
0 & \text{if } x \in S_i^c
\end{cases}
\]

where \( S_i \) is a monotone subset of \( \mathbb{R}^{k-1} \). By Lemma 3.2, the distribution of \( Y \) depends only on \( \gamma \) and since \( X \) has a density with respect to Lebesgue measure on \( \mathbb{R}^k \), \( Y \) has a density with respect to Lebesgue measure on \( \mathbb{R}^{k-1} \). This implies \( P_\gamma (S^*) \) is a continuous function of \( \gamma \) for sets \( S^* \) of the form \( (4.5) \) since for such sets, \( \overline{S^*}/S^o \) (closure minus interior) has Lebesgue measure zero. Lemma 3.2 establishes the SIP of \( \{F_\gamma (y) : \gamma \in \mathbb{R}^{k-1}\} \).

Also \( \gamma_j \) is a location parameter in the marginal distribution of \( Y_j \) so the convergence in probability assumption of Theorem 4.1 is true.

Let \( \gamma = (0, \ldots, 0) \) so the set \( r \) of Theorem 4.1 is equivalent to

\[
\overline{\theta_i} = \{\theta : \theta_j \geq \theta_i, j = 1, \ldots, k\}
\]
(A denotes the closure of A). Because of the continuity of \( P_\theta (S) \) in terms of \( y \), the fact that \( r \) is \( \bar{\Theta}_i \) rather than \( \Theta_i \) is unimportant since the sup's and inf's are all the same taken over a set or its closure. (4.3) simply insure the \( P^*_\text{-condition} \).

Because \( f \) is symmetric, the distribution of \( Y \) given \( Y^* \) is also symmetric so the remark following Theorem 4.1 is relevant and the monotone set \( S^*_i \) which minimizes

\[
(4.15) \quad \sup_{C \subseteq \Theta_i} P_{\Theta_i} (\text{select } \pi_i) = \sup_{C \subseteq \Theta_i} P_{\Theta_i} (S) \quad \text{in terms of } \ Y \quad \text{is given by Theorem 4.1 as }
\]

\[
S^*_i = \{ y: y_j \leq d, \ j = 1, \ldots, k-1 \}
\]

\[
(4.16) = \{ x: x_j - x_i \leq d, \ j \neq i \}
\]

which is the acceptance region for \( \pi_i \) of \( R_1 \).

Since the support of \( f \) is \( \mathbb{R}^k \), the support of the distribution of \( Y_j \) given \( Y_j^* \) is \( \mathbb{R} \). So \( S^*_i \) is the unique acceptance region for \( \pi_i \) which minimizes (4.15). Because of the exchangeability, \( d_1 = \ldots = d_k = d \) and

\[
\sup_{C \subseteq \Theta_i} P_{\Theta_i} (S^*_i) = \ldots = \sup_{C \subseteq \Theta_k} P_{\Theta_k} (S^*_k) = P_{\Theta_1=\Theta_2} (x_2 - x_1 \leq d).
\]

So none of the \( S^*_i \) can be changed without increasing (4.1). Thus \( \{ S^*_1, \ldots, S^*_k \} \) is the unique set of acceptance regions which minimizes (4.1) (i.e., \( R_1 \) is the unique minimax selection rule). Any unique minimax rule is admissible.
5. SELECTION OF NORMAL MEANS WHEN THE VARIANCES ARE UNEQUAL

In this section we assume that $X_1, \ldots, X_k$ are independent random variables and $X_i$ is normally distributed with unknown mean $\theta_i$ and known variances $\sigma_i^2$. If the $\sigma_i^2$'s were assumed to be equal, we would have exchangeable random variables and by Theorem 4.2 $R_1$ would be a "good" selection rule. But here, no assumptions about the equality of the variances are made. The variances may be of the form

$$\sigma_i^2 = \frac{\gamma_i}{n_i},$$
e.g., $X_i$ is the mean of a random sample of size $n_i$ from $\pi_i$.

So this formulation includes unequal sample size problems.

The following five rules have been proposed. In each case $d$ is chosen to be the smallest positive constant such that the $P^*$-condition is satisfied. If $\gamma$ rather than $\gamma_i$ appears, it is assumed that $\gamma_1 = \ldots = \gamma_k = \gamma$.

Chen and Dudewicz (1973) proposed rules $R_2$ and $R_3$.

$$R_2: \text{select } \pi_i \text{ iff } x_i \geq \max_{1 \leq j \leq k} x_j - d\gamma \sqrt{\frac{1}{n_i} + \frac{1}{n[k]}}$$

where $n[k] = \max_{1 \leq j \leq k} n_j$.

$$R_3: \text{select } \pi_i \text{ iff } x_i \geq \max_{1 \leq j \leq k} x_j - d\gamma \sqrt{\frac{1}{n_i} + \frac{1}{n[1]}}$$

where $n[1] = \min_{1 \leq j \leq k} n_j$.


$$R_4: \text{select } \pi_i \text{ iff } x_i \geq \max_{1 \leq j \leq k} x_j - \frac{d\gamma}{\sqrt{n_i}}.$$
Gupta and Huang (1976) proposed $R_5$.

$$R_5: \text{select } \pi_i \text{ iff } x_i > \max_{1 \leq j \leq k} \left( x_j - d \sqrt{\frac{1}{n_i}} + \frac{1}{n_j} \right)$$


$$R_6: \text{select } \pi_i \text{ iff } x_i > \max_{1 \leq j \leq k} \left( x_j - d \sqrt{\frac{\gamma_i}{n_i}} + \frac{\gamma_j}{n_j} \right)$$

In Chen and Dudewicz (1973), $\gamma$ was not assumed known so an estimate was used in place of $\gamma$ in the definitions of $R_2$ and $R_3$. $R_5$ is easily seen to be a specialization of $R_6$ for the case $\gamma_1 = \ldots = \gamma_k$. It is easy to see that all the rules are just and translation invariant. All reduce to $R_1$ when the variances and sample sizes are all equal. The following theorem provides a minimax result for $R_6$.

**Theorem 5.1.** For the normal means problem, $R_6$ is minimax with respect to $M$ in the class of non-randomized, just, and translation invariant rules which satisfy the $P^*$-condition.

**Proof.** By Theorem 4.1, applied as in Theorem 4.2, the just and translation invariant acceptance region $S_i$ for $\pi_i$ which minimizes $\sup_{\theta_i} \mathbb{P}_\theta(\text{select } \pi_i)$ is given by

$$S_i = \{ \bar{x}: x_j - x_i \leq d_{ij} \mid j = 1, \ldots, k, j \neq i \}$$

where (4.7) implies that the $d_{ij}$ satisfy

$$P_{\theta_1=\theta_i} (X_1 - X_i \leq d_{i1}) = \ldots = P_{\theta_k=\theta_i} (X_k - X_i \leq d_{ik}).$$
This implies

\[(5.3) \quad \Phi(d_{11}/\sqrt{\sigma_1^2 + \sigma_i^2}) = \ldots = \Phi(d_{kk}/\sqrt{\sigma_k^2 + \sigma_i^2})\]

where \(\Phi\) is the standard normal c.d.f. Thus, the \(d_{ij}\) must satisfy

\[(5.4) \quad \frac{d_{11}}{\sqrt{\sigma_1^2 + \sigma_i^2}} = \ldots = \frac{d_{kk}}{\sqrt{\sigma_k^2 + \sigma_i^2}}.\]

Letting \(d^*_i = \frac{d_{11}}{\sqrt{\sigma_1^2 + \sigma_i^2}}\), we obtain

\[(5.5) \quad d_{ij} = \frac{d^*_i}{\sqrt{\sigma_j^2 + \sigma_i^2}} \quad j = 1, \ldots, k, \ j \neq i\]

for the minimax region and from the proof of Theorem 4.1 it can be seen that for this minimax region

\[(5.6) \quad \sup_{\delta C} P_\theta (select \pi_i) = \Phi(d_{11}/\sqrt{\sigma_1^2 + \sigma_i^2}) = \Phi(d^*_i).\]

Recall that, from (4.6), \(d^*_i\) is determined by

\[(5.7) \quad P_{\theta 1} = \ldots = \theta_k (X_j - X_i \leq \frac{d^*_i}{\sqrt{\sigma_j^2 + \sigma_i^2}}, \ j = 1, \ldots, k, \ j \neq i) = p^*\]

Comparing (5.1) (inserting (5.5)) and the definition of \(R_6\), we see that they are the same except that in (5.1), \(d^*_i\) depends on \(i\), whereas \(d\) in \(R_6\) does not.

To minimize (4.1), we must minimize the maximum of the \(k\) quantities in (5.6) which, of course, is \(\Phi(d^*_i)\) where \(d^*_i = \max_{1 \leq j \leq k} d_{ij}\). If \(d^*_i\) is used in place of \(d_i^*\) for all \(i\), then

\[\sup_{\delta C} P_\theta (select \pi_i) = \Phi(d^*_i) \quad \text{for all } i = 1, \ldots, k\]
so (4.1) is unchanged. The rule using the \( d_i^* \)'s obviously is minimax since it minimizes each of the terms in the max of (4.1). The rule using \( d^* \)
in place of all \( d_i^* \)'s has the same value of (4.1) so it too is minimax. But this rule is \( R_6 \) (set \( d = d^* \)). It should be noted that in going from the rule with the \( d_i^* \)'s to \( R_6 \), the \( P^* \)-condition has not been violated. Those acceptance regions which have changed have been increased in size so \( P(\text{CS}) \) has, if anything, increased. ||

The rules \( R_2 \), \( R_3 \) and \( R_4 \) are not minimax. The uniqueness part of Theorem 4.1 is applicable since \( X_i - X_j, j \neq i \), has support \( R \). They all have regions of the shape (4.5) but do not satisfy (4.7). For example, for \( R_4 \), (4.7) implies

\[
\phi(d_i, \frac{1}{n_i}) \sqrt{\frac{1}{n_i} + \frac{1}{n_j}} = \phi(d_i, \frac{1}{n_i}) \sqrt{\frac{1}{n_i} + \frac{1}{n_k}}.
\]

Unless \( n_i = \ldots = n_k \), this is not true. Similar reasoning holds for \( R_2 \) and \( R_3 \). Of course \( R_5 \) is minimax in the \( n_i = \ldots = n_k \) case since it is the same as \( R_6 \).

6. SCALE PARAMETERS

Results analogous to those of Section 4 may be obtained when \( \theta \) is a scale parameter. We assume \( X \) has c.d.f. \( F(x_1/\theta_1, \ldots, x_k/\theta_k) \) and density

\[
f(x_1/\theta_1, \ldots, x_k/\theta_k) = \prod_{i=1}^k \theta_i \text{ with respect to Lebesgue measure on } (0, \infty)^k,
\]

\( \theta \in \theta = (0, \infty)^k \). In scale problems, it is natural to restrict attention to scale invariant rules, i.e., rules satisfying \( \varphi(x_1, \ldots, x_k) = \varphi(cx_1, \ldots, cx_k) \). Replacing translation by scale invariance, lemmas like Lemmas 3.1 and 3.2 can be obtained with the differences (of both observations and parameters) replaced by quotients, e.g., \( X_1 - X_i \) becomes \( X_1/X_i \).
Theorem 4.1 is applicable exactly as stated to obtain the following. Define the rule

\[ R_7: \text{select } x_i \text{ iff } x_i \geq c \cdot \max_{1 \leq j \leq k} x_j \]

where \(0 < c < 1\) is the largest constant such that the P*-condition is satisfied.

Theorem 6.1. Let \(X\) have density \(f(x_1/\theta_1, \ldots, x_k/\theta_k) / \prod_{i=1}^{k} \theta_i\) with respect to Lebesgue measure on \((0, \infty)^k\). Suppose that the support of \(f\) is \((0, \infty)^k\) and \(f\) is symmetric. Then \(R_7\) is minimax with respect to \(M\) in the class of non-randomized, just, and scale invariant rules which satisfy the P*-condition. Furthermore \(R_7\) is the unique minimax rule in this class so \(R_7\) is admissible in this class.

Analogous results can also be obtained if the best population is the one associated with the smallest parameter value. In this case the rules

\[ R_8: \text{select } x_i \text{ iff } x_i \leq \min_{1 \leq j \leq k} x_j + d \]

and

\[ R_9: \text{select } x_i \text{ iff } x_i \leq c \cdot \min_{1 \leq j \leq k} x_j \]

are the minimax, admissible rules in the location and scale problems, respectively.
REFERENCES


Subset selection rules, minimaxity, admissibility, probability of selecting non-best populations, just, translation invariant, unequal variances.

Let $X_1, \ldots, X_k$ be observations from populations whose distributions are determined by unknown real parameters $\theta_1, \ldots, \theta_k$. In a subset selection problem, the goal is to select a subset of the populations which includes the population associated with the largest parameter with 'high' probability and includes the other populations with 'low' probability. In this paper, rules are found which are minimax in the class of non-randomized, just, and translation invariant.
rules when risk is measured by the maximum probability of including a non-best population. These rules are of the form proposed and studied by Gupta (1956) in location and scale parameter problems. In many cases, these rules are the unique minimax rule in the class and, hence are also admissible in this class. These results are applied to the normal mean problem with known unequal variances (or unequal sample sizes). Comparison of several proposed rules is made. A rule proposed by Gupta and Huang (1976) is found to be minimax. A generalization of the rule, proposed by Gupta and Wong (1976), is likewise minimax. Other rules, proposed by Chen and Dudewicz (1973) and Gupta and Huang (1974), are shown to be not minimax.