DEEP SUBMERSION SYSTEMS TERMINOLOGY AND USAGE

Northrop Corporation

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DEEP SUBMERGENCE SYSTEMS TERMINOLOGY AND USAGE

1. This document presents terminology and usage peculiar to the Deep Submergence Systems Project (PM11). The document is intended to serve as a reference and guide for government and contractor organizations engaged in the preparation of manuals, technical documents, drawings, and other material for DSSP (PM11).

2. Revised line statements and new entries or additions are denoted by a vertical black line drawn at the right hand edge of the page to indicate the changed contents.

3. Existing documentation and drawings should not be revised solely to conform with this document. However, such material revised after publication of TD-19 should, where practical, conform to this approved terminology and usage.

4. This publication supersedes and cancels DSSP TD-19, Revision A, dated 24 July 1969.

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PMI1-10
PMI1-11
PMI1-12
PMI1-13
PMI1-14
PMI1-15
PMI1-20
PMI1-201
PMI1-202
PMI1-203
PMI1-204
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<table>
<thead>
<tr>
<th>Change No.</th>
<th>Date</th>
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<th>Change Inserted By</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
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</tr>
</tbody>
</table>

vi
CONTENTS

1.0 INTRODUCTION .................................. Page 1
2.0 REFERENCES ..................................... 1
3.0 CHANGES ....................................... 1
4.0 TERMINOLOGY AND USAGE ...................... 2
1.0 INTRODUCTION

The purpose of this document is to provide a basic reference of the terminology and usage peculiar to the U.S. Navy's Deep Submergence Systems Project (PM11).

Military activities, contractor organizations, equipment lists of specific systems, general oceanographic terms, basic ship designations, and other information that is readily available in other publications is not normally included.

2.0 REFERENCES

For terminology of specific items of equipment not listed in this document the reader is directed to nomenclature and equipment lists for the various systems and subsystems. In addition, the following documents are recommended for terminology and usage in fields related to deep submergence systems development and operations.

Assistant Secretary of the Navy (Research and Development).


3.0 CHANGES

Proposed additions and corrections to this document should be addressed to the Systems Engineering Support Contractor:

Northrop Corporation
Electro-Mechanical Division
8728 Colesville Road
Suite 900
Silver Spring, Maryland 20910

Where appropriate, full data such as formal name, informal name, abbreviation, AN/number, definition, and preferred usage should be included with the proposed change.

If a change to an existing entry is proposed, the justification for the change should be presented, citing published sources when possible. Additions and corrections will be made on a yearly basis in July.
4.0 TERMINOLOGY AND USAGE

Words, terms, acronyms, and abbreviations are listed in the index (far left) position in all capital letters except that informal names are in capital and lower-case letters.

The word "defined" in parenthesis after a word or term indicates a definition is provided under the formal name listing.

In general, lists of equipment or systems should use the formal name. The first time equipment or a system is mentioned in a narrative the formal name should be used, possibly with the informal name being given immediately after in parenthesis. Subsequent mention of the equipment could then use the informal name.

Definitions are given under the formal name entry. The formal name entry also contains the informal name and usage notes, if any.

Terminology applicable to a specific system or subsystem or having more than one meaning has each PMll application numbered. This sequential arrangement does not indicate preference.
ABSOLUTE VELOCITY LOG, SONAR, DOPPLER

Informal Doppler Sonar

Term Deleted. See DOPPLER SONAR SET

ADS

Altitude/Depth Sonar

See SOUNDER SET, SONAR, ALTITUDE/DEPTH

ADS

ADVANCED DIVING SYSTEM

Term used for commercial deep diving systems (e.g., ADS-IV).

AFT SPHERE

Aftermost sphere of a multisphere deep submergence vehicle.

The AFT SPHERE of the DSRV carries survivors from disabled submarines.

(Rear sphere is incorrect usage.)

Also see PRESSURE CAPSULE.

ALARM PHASE

Phase of deep submergence operations that begins with the attempt of a disabled submarine to signal the need for rescue and ends when the proper naval authorities know the Deep Submergence Rescue System is to be used.

Alerting BUOY

See BUOY, ALERTING
Alternate Applied Training Facility

Classrooms and maintenance laboratories for instruction of deep submergence vehicle operational and maintenance personnel, selected Mother Submarine crew members, and Rescue Control Center personnel until the DSAT facility is constructed.

Altitude/Depth Sonar

See SOUNDBING SET, SONAR, ALTITUDE/DEPTH

AMF

ASHORE MAINTENANCE FACILITY

AMTS

AQUANAUT AND MATERIAL TRANSPORT SYSTEM (defined)

AP/DDA

Auto Pilot/Digital Differential Analyzer

See COMPUTER GROUP, STABILIZATION DATA

AQUANAUT

A saturated diver taking part in a seafloor operation.

AQUANAUT AND MATERIAL TRANSPORT SYSTEM (AMTS)

Diver transport vehicles and material transport vehicles to support Aquanauts.

AQUANAUT EQUIPMENT

See CAVE, INTERIM

ARAWAK

See BREATHING APPARATUS

ARC

Designation for radio sets.

ASR

Navy ship designation for SUBMARINE RESCUE SHIP.
ASR CAPTURE ARMS  Armlike devices extending from the DSRV to engage cables suspended from the surface support ship during underwater retrieval of the DSRV.

ASR Diving System  See DEEP DIVING SYSTEM
BALLAST SYSTEMS

Means of maintaining desired buoyancy or stability in a deep submergence vehicle or seafloor habitat.

1. The DSRV has a MERCURY TRIM AND LIST system that uses liquid mercury pumped between compensated tanks to maintain trim angle, set list angle, vary center of gravity, and damp roll.

2. The DSRV has a RESCUE BALLAST system that transfers water ballast carried in the mid and aft spheres to compensate for the weight of survivors taken on board from a disabled submarine.

3. The DSRV has MAIN BALLAST and VARIABLE BALLAST systems that use soft and hard tanks, respectively, open to the sea to help maintain the required vehicle buoyancy. The MAIN BALLAST tanks provide positive buoyancy and are completely flooded when the DSRV is submerged.

4. The DSRV has a TRANSFER BALLAST system that provides a means to dewater the mating skirt during mating operations.

5. The 3EALAB habitat uses water ballast to aid in lowering operations and to help maintain position on the seafloor.

BEACON SET, SONAR

Informal Submarine Distress Finger

AN/BQN-13

BIBS

BUILT-IN BREATHING SYSTEM (Defined)

BINNACLE

See STABLE PLATFORM ASSEMBLY, INERTIAL NAVIGATOR

BIRDCAGE

See STRUCTURE, INTERNAL SUPPORT
BOUNCE DIVE
A short-duration dive that requires no additional decompression beyond the depth to which the diver is saturated.

BQC
Designation for sound communications equipment mounted in submarines, underwater vehicles, and seafloor habitats. Also see UQC and WQC.

Formal COMMUNICATION SET, SONAR
Informal Underwater Telephone

1. DSRV has AN/BQC-3 (COMMUNICATION SET, SONAR)
2. ASR-21 Class has AN/BQC-1 (for use in Submarine Rescue Chamber)
3. SEALAB III habitat has AN/BQC-1

BQN
Designation for underwater sound navigation equipment.

DSRV equipment in this category includes:

AN/BQN-7 TRANSPONDER SET, SONAR, TRACKING (Tracking Transponder)
AN/BQN-8 TRANSPONDER SET, SONAR, HOMING (Homing Transponder)
AN/BQN-9 INTERROGATOR SET, SONAR (Transponder Interrogator Sonar)
AN/BQN-10 SOUNDING SET, SONAR, ALTITUDE/DEPTH (Altitude/Depth Sonar)
AN/BQN-11 DOPPLER SONAR SET (Doppler Sonar)
AN/BQN-13 Beacon Set, Sonar (Submarine Distress Pinger)
BQR Designation for underwater listening equipment.

DSRV equipment includes AN/BQR-18 RECEIVING SET, SONAR, DIRECTIONAL LISTENING (Directional Listening Hydrophone Set)

BQS Designation for underwater sound equipment for detecting and/or determining range and bearing.

DSRV equipment in this category includes:

AN/BQS-16 DETECTING-RANGING SET, SONAR, VERTICAL OBSTACLE (Vertical Obstacle Sonar)

AN/BQS-17 DETECTING-RANGING SET, SONAR, SHORT RANGE (Short Range Sonar)

AN/BQS-18 DETECTING-RANGING SET, SONAR, HORIZONTAL OBSTACLE (Horizontal Obstacle Sonar)

BRC Designation for submarine radio set.

The DSRV has AN/BRC-3 radio set.

BREATHING APPARATUS Equipment to provide breathing gas directly to a diver rather than through his environment.

See: BUILT-IN BREATHING SYSTEM

HOOKAH

SCUBA

BSH Designation for submarine electronic recording equipment.

The DSRV has AN/BSH-3 RECORDER-REPRODUCER SET, SIGNAL DATA (Speech and Data Recorder).
BUBBLE LINE

The specified air/water interface level that has to be established in the Submarine Escape Trunk prior to opening escape hatch during submarine escape.

BUILT-IN BREATHING SYSTEM (BIBS)

Emergency individual breathing apparatus in submarines, deep submergence vehicles, and seafloor habitats.

BUOY, ALERTING

Informal Alerting Buoy

BUOY, MESSENGER

Informal Messenger Buoy

Tethered buoy released by a submarine in distress. The buoy carries a 7/16" CRES cable to the surface to be used as a downhaul wire for the Submarine Rescue Chamber.

BUOYANCY RINGS

Large flotation devices attached to a SEALAB habitat to increase positive buoyancy during surface handling operations.

BUOYANCY TRANSPORT DEVICE

Mobile device for moving material and equipment along the ocean floor with the lift provided by the device's buoyancy; for use in underwater construction and salvage.

BYQ

Designation for submarine data processing computer.

The DSRV has CP-1022/BYQ COMPUTER, SIGNAL DATA GENERATOR (Central Processing Computer Set)
CA COORDINATING ACTIVITY

CABLE-CONTROLLED UNDERWATER RESEARCH VEHICLE (CURV)

Unmanned, tethered underwater vehicle developed by the Naval Undersea Research and Development Center to locate and recover torpedoes and other objects from the ocean bottom.

1. CURV I has a 2,000-foot design depth capability.
2. CURV II has a 2,500-foot design depth capability.
3. CURV III has a 7,000-foot design depth capability.

CAMERA, TELEVISION, RIGHT ANGLE

Informal Right Angle Television Camera

Television camera with right-angle lens.

CART COMPLETE ASSEMBLY AND READY FOR TEST

Point at which Deep Submergence Rescue Vehicle is transferred from fabrication to test phase.

(Lockheed Missiles and Space Company term)

CAVE CONSOLIDATED AQUANAUT VITAL EQUIPMENT

Integrated equipment suit to provide saturated diver (Aquanaut) with (1) breathing gases, (2) thermal protection, (3) biological protection, (4) mechanical protection, (5) navigation data, (6) depth measurement, (7) visual observation aids, (8) stability aids, (9) electric power.
CDDR COORDINATED DESIGN DATA REQUIRED

Note on coordination drawings indicating the absence of specific data required to complete the interface definition process.

CENTRAL PROCESSING COMPUTER (CPC)

See COMPUTER, SIGNAL DATA GENERATOR

CENTRAL PROCESSING COMPUTER CONTROL AND DISPLAY PANEL

Formal Control-Indicator, Computer

See COMPUTER, SIGNAL DATA GENERATOR

CLAMSHELL HELMET

A free flooding helmet with a hinged faceplate containing an oral-nasal cavity. The helmet usually contains a built-in microphone, earphones, and a second stage regulator. Also called Diver's Helmet.

Clock and Transponder Release Panel

See PANEL, CLOCK AND TRANSPONDER RELEASE

CLUMP

Anchoring element placed on the sea floor.

COLLAPSE DEPTH

The depth at which the hull of a submarine or a submersible will collapse due to pressure. Generally designed to be 1 1/2 times the operating depth.

COMBINED TEST GROUP (CTG)

A group of representatives of cognizant military and contractor activities involved in test plans and procedures who have been chartered specific responsibility thereto.
COMMUNICATION SET, SONAR

Informal Underwater Telephone

See BQC

CONVERTER GROUP, SIGNAL DATA, HORIZONTAL OBSTACLE OU-52/BQS-18

Informal Horizontal Obstacle Sonar Analyzer

See DETECTING-RANGING SET, SONAR, HORIZONTAL OBSTACLE

COMPUTER GROUP, STABILIZATION DATA

Informal Ship Control Computer Group

DSRV ship control computer; this group includes:
(1) Computer, Stabilization Data, Digital (AP/DDA),
(2) Computer, Stabilization Data, Analog

COMPUTER RECORDER-REPRODUCER

See RECORDER-REPRODUCER, SIGNAL DATA

COMPUTER SET, SIGNAL DATA GENERATOR

Informal Central Processing Computer Set

DSRV general-purpose digital computer and its related equipment. This set includes: (1) Computer, Signal Data Generator, (2) Recorder-Reproducer, Signal Data, (3) Tape Electronic Data Processing, Programmed, (4) Control-Indicator, Computer.
COMPUTER, SIGNAL DATA GENERATOR CP-1022

Informal Central Processing Computer (CPC)

See COMPUTER SET, SIGNAL DATA GENERATOR

COMPUTER, STABILIZATION DATA, ANALOG

Informal Ship Control Electronics

See COMPUTER GROUP, STABILIZATION DATA

COMPUTER, STABILIZATION DATA, DIGITAL

Informal Auto Pilot/Digital Differential Analyzer (AP/DDA)

See COMPUTER GROUP, STABILIZATION DATA

CONCURRENT EVALUATION

An evaluation combining OPEVAL and TECHEVAL into one operation.

CONTINENTAL SHELF

Zone adjacent to a continent or island from the low water line to the depth at which there is usually a marked increase of slope to greater depth; the continental shelf area is generally considered to extend out to a depth of 600 feet (100 fathoms).

U.S. Navy operational requirements for the continental shelf generally have been extended to a depth of 850 feet.

CONTROL, COMMUNICATION SET AN/BQC-3

Informal Underwater Telephone Remote

Remote controls for a deep submergence vehicle underwater telephone.
CONTROL-INDICATOR  Control and display component for equipment; refer to specific equipment.

Control Shroud  See SHROUD, CONTROL

CONTROL SPHERE  Pressure sphere of a deep submergence vehicle, which houses the pilot(s) and primary controls. Also see PRESSURE CAPSULE.

CONTROL STICK ASSEMBLY  Operator's two control sticks for sail planes, rudder, and thrusters of NR-1.

CONTROLLER, HAND, ROTATIONAL

Informal  Rotational Hand Controller

Operator's control stick for rotational motion of deep submergence vehicle.

("Joystick" is incorrect usage)

CONTROLLER, HAND, TRANSLATIONAL

Informal  Translational Hand Controller

Operator's control stick for translational motion of deep submergence vehicle.

("Joystick" is incorrect usage)

CO₂ SCRUBBER  System or device to remove carbon dioxide from atmosphere or breathing gas.

CP-1022/BYQ CPC  Central Processing Computer

See COMPUTER, SIGNAL DATA GENERATOR
<table>
<thead>
<tr>
<th><strong>CREW</strong></th>
<th>All personnel-operational and maintenance-assigned to a deep submergence vehicle.</th>
</tr>
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<tbody>
<tr>
<td><strong>CRUISE MODE</strong></td>
<td>Deep submergence vehicle operating at cruising forward speed.</td>
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<td>DSRV mode of operation with full control by its shroud, thus, not requiring operation of the vehicle's ducted thrusters.</td>
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<td><strong>CTFM</strong></td>
<td>CONTINUOUS-TRANSMISSION, FREQUENCY MODULATED</td>
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<td>Generic term for specific type of echo-ranging sonar equipment.</td>
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<td><strong>CTG</strong></td>
<td>COMBINED TEST GROUP (defined)</td>
</tr>
<tr>
<td><strong>CURV</strong></td>
<td>CABLE-CONTROLLED UNDERWATER RESEARCH VEHICLE (defined)</td>
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<tr>
<td>Acronym</td>
<td>Description</td>
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<tr>
<td>DDA</td>
<td>DIGITAL DIFFERENTIAL ANALYZER</td>
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<td>See COMPUTER, STABILIZATION DATA, DIGITAL</td>
</tr>
<tr>
<td>DDC</td>
<td>DECK DECOMPRESSION CHAMBER (defined)</td>
</tr>
<tr>
<td>DDS</td>
<td>DEEP DIVING SYSTEM (defined)</td>
</tr>
<tr>
<td>DDTV</td>
<td>DRY DIVER TRANSPORTATION VEHICLE (defined)</td>
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<tr>
<td>DECK DECOMPRESSION CHAMBER (DDC)</td>
<td>Chamber in surface support ships to maintain divers at working depth pressure between work periods and for general and saturation diving decompression.</td>
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<td>1. The Deep Diving System MK I has two interconnected DDCs, which can be maintained at different pressures.</td>
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<td>2. The Deep Diving Systems MK2 MOD 0 and MOD 1 each have two separate DDCs.</td>
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<tr>
<td>DECK OPERATIONS CONTROL STATION (DOCS)</td>
<td>Location on surface support ship that monitors and controls deck operations associated with diving or rescue missions.</td>
</tr>
<tr>
<td>DECOMPRESSION CHAMBER ROOM</td>
<td>Compartment in surface support ship that houses Deck Decompression Chamber (DDC) and Main Control Console (MCC) of Deep Diving System (DDS).</td>
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</tbody>
</table>
DEEP SUBMERSION SYSTEMS PROJECT ALTERATION (defined)

DEEP DIVING SYSTEM (DDS)

Integrated system to support general and saturation diving; includes (1) Deck Decompression Chamber (DDC), (2) Personnel Transfer Capsule (PTC), (3) Main Control Console (MCC), (4) Strength-Power-Communications Cable (SPC CABLE), (5) related gas stowage, piping, etc.

1. The DDS MK I is an air-transportable system intended primarily for use on board Salvage Tugs (ATS).

2. The DDS MK 2 MOD 0 is installed in the range support ship ELK RIVER (IX-501).

3. The DDS MK 2 MOD 1 is intended for installation in ships of the ASR-21 class.

DEEP OCEAN TECHNOLOGY (DOT) PROGRAM

Program designed to advance the technology leading to occupation and exploitation of the deep ocean; includes power sources, structural materials, propulsion systems, hydraulic systems, etc.

DEEP OCEAN TRANSPONDER (DOT)

Expendable devices dropped onto the ocean floor to mark locations and serve as navigation beacons.

DEEP SUBMERSION APPLIED TRAINING (DSAT) FACILITY

Classrooms and maintenance laboratories for instruction of deep submersion vehicle operational and maintenance personnel, Rescue Control Center personnel, selected Mother Submarine crew members, and Rescue Control Center personnel.

D-2
DEEP DIVING SYSTEM (DDS)

Integrated system to support general and saturation diving; includes (1) Deck Decompression Chamber (DDC), (2) Personnel Transfer Capsule (PTC), (3) Main Control Console (MCC), (4) Strength-Power-Communications Cable (SPC CABLE), (5) related gas stowage, piping, etc.

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DEEP SUBMERGENCE APPLIED TRAINING (DSAT) FACILITY

Classrooms and maintenance laboratories for instruction of deep submergence vehicle operations and maintenance personnel, Rescue Control Center personnel, selected Mother Submarine crew members, and Rescue Control Center personnel.
DEEP SUBMERSION SYSTEMS PROJECT ALTERATION

Change to PM11 equipment or manuals intended for Fleet use after acceptance by the government.

DEI

DESIGN ENGINEERING INSPECTION

DEPLOYMENT

Movement of a support ship or submarine transporting a deep submergence system from the loading port to the operating area, support of the system operations in the area, and return to port. Also see MISSION, SORTIE

Depth Pressure Transducer

See TRANSDUCER, PRESSURE, DEPTH

DETECTING-RANGING SET, SONAR, HORIZONTAL OBSTACLE (HOS) AN/BQS-18

Informal Horizontal Obstacle Sonar

Sonar that sweeps in the deck plane to detect objects forward of a deep submergence vehicle; the sonar's display indicates range and bearing from the vehicle.

DETECTING-RANGING SET, SONAR, SHORT RANGE (SRS) AN/BQN-17

Informal Short Range Sonar

Sonar that indicates precise definition of underwater objects at relatively close range; designed to locate the escape hatches of submarines.

DETECTING-RANGING SET, SONAR, VERTICAL OBSTACLE (VOS) AN/BQS-16

Informal Vertical Obstacle Sonar

Sonar that sweeps in a plane perpendicular to the deck to detect objects forward of a deep submergence vehicle; the sonar's display indicates range and elevation from the vehicle.
DETECTOR, WATER LEVEL *Informal* Water Level Detector
A sonic device for determining the level of water within a submerged object; indication is external to the object.

DEWATERING SYSTEM See BALLAST SYSTEMS

Directional Gyro See GYROSCOPE, DIRECTIONAL

Directional Listening Hydrophone
See RECEIVING SET, SONAR, DIRECTIONAL LISTENING

DISSUB DISTRESSED SUBMARINE (defined)

Distress Pinger See BEACON SET, SONAR AN/BQN-13

DISTRESSED SUB (DISSUB)
A submarine disabled on the ocean floor at less than collapse depth and unable to surface under its own power.

Diurene Suit See THERMAL PROTECTIVE SUIT

Diver's Helmet See CLAMSHELL HELMET

DIVING STATION Main staging room for diving operations in a seafloor habitat.

DIVER'S UNDERWATER OMNI-SYSTEM (DUOS)
An underwater navigation system to enable a diver to determine his location and heading in a given work area.

D-4
DLH Directional Listening Hydrophone
See RECEIVING SET, SONAR AN/BQR-18

Docking Transponder
See TRANSPONDER, DOCKING

DOCS DECK OPERATIONS CONTROL STATION (defined)

DONUT FAIRLEAD A fitting located on submarine hatch through which messenger buoy cable is routed.

DOPPLER SONAR SET AN/BQN-11

Informal Doppler Sonar
Sonic device that provides indication of vehicle fore-aft and port-starboard ground speeds when near ocean floor; calculated from doppler frequency shifts in bottom-reflected sonic beams.

DOT
1. DEEP OCEAN TECHNOLOGY (defined)
2. DEEP OCEAN TRANSPONDER (defined)

DRY DIVER TRANSPORTATION VEHICLE (DDTV)
Submersible vehicle capable of underwater transport of divers in a dry environment.

DSAT FACILITY DEEP SUBMERGENCE APPLIED TRAINING FACILITY (defined)

DSKV DEEP SUBMERGENCE RESCUE VEHICLE
DSSV

DEEP SUBMERGENCE SEARCH VEHICLE

Ducted Thruster

See THRUSTER, DUCTED

DUOS

DIVER'S UNDERWATER OMNI-SYSTEM (defined)
**EASE**

ESCAPE AND SURVIVAL EQUIPMENT (defined)

**ELECTRIC WIRE SUIT**

See THERMAL PROTECTIVE SUIT

**ENTRY LOCK**

Separately pressurized extension of diver's pressurized habitat that provides access between the pressurized and unpressurized environments.

**ENTRY SKIRTS**

Access trunks located beneath the hatches of SEALAB habitat to facilitate entry and allow nominal changes in adjacent water level without water entering the habitat proper.

**ESCAPE AND SURVIVAL EQUIPMENT (EASE)**

Equipment for individual escape from a disabled submarine on the ocean floor and subsequent survival on the ocean surface.

**ESCAPE HATCH**

A second smaller hatch located on the Submarine Escape Trunk used for unassisted personnel escape and ascent; also see RESCUE HATCH.

**ESCAPE SYSTEM**

See SUBMARINE ESCAPE AND SURVIVAL SYSTEM

**ESCAPE TRUNK**

See SUBMARINE ESCAPE TRUNK

**EXCURSION DIVE**

Movement by a saturated diver below his saturation depth requiring no additional decompression.
FAILURE OR INADEQUACY REPORT (FIR)

Document that reports troubles, failures or inadequacies experienced with equipment or documentation subsequent to its being offered for government acceptance.

FUEL CELL POWER SYSTEM (FCPS)

Power supply system composed of gaseous hydrogen and oxygen which produces electrical power for the DSSV.

FIELD JOINTS

Two-part circular ring in a deep submergence vehicle's outer hull that opens, "breaking" the vehicle to allow access to internal components.

FIR

FAILURE OR INADEQUACY REPORT (defined)

FORWARD SPHERE

Foremost sphere of a multisphere deep submergence vehicle. Control Sphere is preferred usage if the foremost sphere houses the vehicle's primary controls. Also see PRESSURE CAPSULE.
GYRO SHELF
Plate on which rate gyro assembly, directional gyro, and vertical gyro are mounted.

GYROSCOPE ASSEMBLY, RATE
Informal Rate Gyro Assembly
An assembly containing three rate gyros, one fixed to each of three orthogonal vehicle axes, which continuously monitor the vehicle's angular rates. Component of the Gyroscope Assembly Group.

GYROSCOPE, DIRECTIONAL
Informal Directional Gyro
A single degree of freedom gyro measuring a vehicle's angular change around its input axis. Component of the Gyroscope Assembly Group.

GYROSCOPE, VERTICAL
Informal Vertical Gyro
Gyro that provides roll and pitch data. Component of the Gyroscope Assembly Group.
**HABITAT**

Dry-atmosphere chamber on or near the ocean floor to support saturated divers (Aquanauts) during bottom operations. The internal pressure is maintained at the ambient water pressure to provide free movement to and from the open water.

**Handling Equipment**

Equipment to facilitate moving, loading, transporting, and unloading deep submergence vehicle. HANDLING AND TRANSPORTATION EQUIPMENT is maintained at the vehicle's home port and SHIPBOARD HANDLING EQUIPMENT is maintained aboard the surface support ship.

**HANDLING TRAINING VEHICLE (HTV)**

Device that approximates the dimensions and weight of a specific deep submergence vehicle for use in movement, loading, and unloading training.

**Hatch Marker**

See TARGET, SONAR

**Hauldown Winch**

Winch mounted on a positively buoyant underwater vehicle or device for pulling the vehicle or device down against its positive buoyancy.

The DSRV has a HAULDOWN WINCH mounted in its mating skirt to provide downhaul force during final mating with a bottomed submarine.

The PTC has a HAULDOWN WINCH for hauling the capsule to the ocean floor against its positive buoyancy; the winch is slung from a trapeze at the bottom of the PTC. Can also be used for paying out to allow capsule to rise.

**HATCH, REPLACABLE LIFTING**

Device attached to the hatch structure of a disabled submarine to provide an attachment point for lifting during salvage operation.

H-1
HIS Hood Inflation System (British)

HISR Hooded Immersion Suit Raft

Hold-down Staples See Submarine Rescue Chamber Staples

HOME PORT Base at which a system or vehicle is normally maintained. Also see RESCUE UNIT HOME PORT.

Homing Transponder See TRANSPONDER SET SONAR, HOMING AN/BQN-8

HOOKAH Underwater breathing apparatus with breathing gas supplied to diver from an external source and exhaled gas returned through umbilical hose. Named for resemblance to Turkish water pipe. ARAWAK is trade name for HOOKAH device manufactured by Westinghouse Electric Corporation. Also used for certain supply hoses without a return hose feature.

HORIZONTAL OBSTACLE SONAR See DETECTING-RANGING SET, SONAR, HORIZONTAL OBSTACLE

HOS Horizontal Obstacle Sonar See DETECTING-RANGING SET, SONAR, HORIZONTAL OBSTACLE

HOT WATER SUIT See THERMAL PROTECTIVE SUIT

HOVER MODE Submarine or deep submergence vehicle operating with little or no forward motion.
HTV

HANDLING TRAINING VEHICLE (defined)

HYDROSTAT

Mode of operation with a Personnel Transfer Capsule (PTC) with the internal environment maintained at one atmosphere to enable its use as an observation chamber by unpressurized personnel.
ICAD INTEGRATED CONTROL AND DISPLAY EQUIPMENT (defined)

IMC VANS INTEGRATED MEDICAL AND COMMAND VANS (defined)

INERTIAL NAVIGATOR GROUP

Informal Inertial Navigator

Assembly of binnacle and associated electronics, exclusive of computer, that generates navigation data for a deep submergence vehicle.

Consists of (1) Stable Platform Assembly, Inertial Navigator, and (2) Control Electronics, Inertial Navigator.

INITIAL OPERATIONAL CAPABILITY (IOC)

Date at which a system can first perform its assigned task.

The IOC for the Rescue Program is the date on which two Deep Submergence Rescue Vehicles (DSRV), the required support facilities, and a support ship are available.

INITIAL RENDEZVOUS AND MATING

Phase of deep submergence rescue operation that begins when the distressed submarine has been located by the Deep Submergence Rescue Vehicle and ends when the first mating of the DSRV with the distressed submarine has been completed. Also see RESCUE MISSION SEQUENCE.

IN-SITU EXPERIMENTS Experiments conducted in the environment; i.e., underwater or in the open sea.
INTEGRATED CONTROL AND DISPLAY EQUIPMENT (ICAD)

Integrated computing, control, and display equipment for deep submergence vehicles. A man-machine interface and signal processing capability is provided for the vehicle's propulsion, maneuvering control, ballast, and jettison systems.

INTEGRATED MEDICAL AND COMMAND VANS (IMC VANS)

Mobile vans that can be installed onboard a surface support ship to form an integrated monitoring and command center for Man-in-the-Sea experiments. The Command Van has communication links to the surface support ship, seafloor habitat, and shipboard Deep Diving System, plus engineering, environmental, and oceanographic data recording facilities. The Medical Van has extensive medical laboratory facilities and can perform limited atmospheric and psychological monitoring of seafloor activities.

INTERIM AQUANAUT EQUIPMENT

See SCUBA MK 11 MOD 0

INTERIM RESCUE UNIT HOME PORT (IRUHP)

Location where the first Deep Submergence Rescue Vehicle is housed and supported until such time as the first Rescue Unit Home Port (RUHP) is activated. The Interim Rescue Unit Home Port will be capable of supporting the DSRV-1 and DSRV-2 for use on rescue and alternate missions.

INTEGRATED TEST PLAN

Plan for the Phase B Test Program including subsystem operability tests, system interface tests, and system operability tests necessary to obtain certification and acceptance.
INTERROGATOR-RECEIVER SET, SONAR, THREE DIMENSIONAL AN/SQQ-25

Informal Three-Dimensional Sonar

Sonar equipment in a surface support ship that provides range, depression angle, and bearing to an acoustic source by measuring the difference in arrival time of acoustic returns to each hydrophone of a hydrophone array.

INTERROGATOR SET, SONAR AN/BQN-9

Informal Transponder Interrogation Sonar

Sonar fitted in a deep submergence vehicle to interrogate underwater transponders.

INVESTIGATION PHASE

Phase of deep submergence vehicle operation during which objects previously located and are approached and observed with sensors that can determine detailed characteristics of the object. This phase includes (1) launch of vehicle from support ship or submarine, (2) descent of vehicle to investigation area, (3) navigation/homing on object, (4) observation of object, (5) marking of object (if necessary), (6) ascent of vehicle, (7) retrieval of vehicle by support ship or submarine.

IOC

INITIAL OPERATIONAL CAPABILITY (defined)

IRUHP

INTERIM RESCUE UNIT HOME PORT (defined)

ITP

INTEGRATED TEST PLAN

IX

Navy ship designation for MISCELLANEOUS UNCLASSIFIED.

The ELK RIVER (IX-501) is the range support ship for the San Clemente Island Range.
LAND TRANSPORT VEHICLE (LTV)

Flat-bed semitrailer for transporting deep submergence vehicles over improved surface roads; air transportable.

LARGE OBJECT SALVAGE SYSTEM (LOSS)

Integrated system for salvaging large objects from depths to 850 feet.

LEVELING LINES

Lines used to maintain the position of a seafloor habitat during lowering operations.

LIFE SUPPORT SYSTEM

Equipment in a deep submergence vehicle, seafloor habitat, or deep diving system to support human life in an alien environment; provides breathing gases, contaminant removal, temperature and humidity control, etc.

LOCAL TEST GROUP (LTG)

Subcommittee of the Combined Test Group (CTG) formed to carry out day-to-day operations during the conduct of tests.

LOCALIZATION PHASE

Phase of deep submergence rescue operations that begins when one Deep Submergence Rescue Vehicle and one DSRV support ship or Mother Submarine are in the area of the distressed submarine and that ends when the distressed submarine has been located by the DSRV. Also see RESCUE MISSION SEQUENCE.

Location Pinger

See BEACON SET, SONAR
LOCATION SYSTEM
System to provide submarines with radio and acoustic communication and location capability by means of a Location Pinger and a tethered radio buoy. The buoy is released at the option of the submarine commanding officer when the submarine is bottomed at less than its collapse depth and released automatically if the submarine's collapse depth is exceeded.

LOSS
LARGE OBJECT SALVAGE SYSTEM (defined)

LTC
LOCAL TEST GROUP (defined)

LTV
LAND TRANSPORT VEHICLE (defined)
MAIN CONTROL CONSOLE (MCC)

Component of a Deep Diving System that monitors and controls operation of the Deck Decompression Chamber(s) and Personnel Transfer Capsule(s), and coordinates communications.

MAN-IN-THE-SEA (MITS)

Program to develop improved capabilities for manned operations on the ocean floor with the concept of saturation diving. Also see SATURATION DIVING.

MAN-IN-THE-SEA IN-SITU TEST PROGRAM

A phase development and operational program to develop and evaluate a mounted diving system with support equipment.

MARK I
See Deep Diving System

MARK 2
See Deep Diving System

MARK VI
See SCUBA

MARK VIII
See SCUBA

MARK IX
See SCUBA

MARK 10
See SCUBA

MARK 11
See SCUBA

MATING

Operation wherein tow watertight/gastight devices are joined together mechanically or by differential pressure to form a watertight/gastight seal, thus enabling personnel transfer between the devices. The following is a list of mating combinations:

M-1
MATING (Cont)

1. DSRV to Submarine
2. SRC to Submarine
3. PTC to DDC
4. DSRV to DDC

MATING SKIRT
Hemispheric protrusion beneath a deep submergence vehicle's bottom hatch, which seals over a submarine's rescue hatch. The skirt is pumped dry of water to allow the submarine's hatch to swing up into skirt cavity and personnel to pass to or from the vehicle.

MCC
MAIN CONTROL CONSOLE (defined)

McCann Chamber
See SUBMARINE RESCUE CHAMBER

Mesenger Buoy
See BUOY, MESSENGER

MID-BODY
Cylindrical section of a deep submergence vehicle's outer hull between the major forward and aft field joints.

MID-SPHERE
Center sphere of a 3-sphere deep submergence vehicle.

The MID-SPHERE of the DSRV carries survivors from disabled submarines. (Center sphere is incorrect usage.) Also see PRESSURE CAPSULE.

MISSION
Those activities undertaken by a deep submergence vehicle or system during a sortie of a surface support ship or submarine. Also see SORTIE, DEPLOYMENT.

MITS
MAN-IN-THE-SEA (defined)
<table>
<thead>
<tr>
<th>Term</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MOTHER SUBMARINE (MS)</td>
<td>Nuclear-powered submarine modified to transport and support a deep submergence vehicle. A component of the Operational Ships System.</td>
</tr>
<tr>
<td>MOTHER SUBMARINE CHECKOUT EQUIPMENT</td>
<td>Equipment loaded aboard a Mother Submarine to test components of a deep submergence vehicle during support operations.</td>
</tr>
<tr>
<td>MPU</td>
<td>MAIN PROPULSION UNIT</td>
</tr>
<tr>
<td>MS</td>
<td>MOTHER SUBMARINE (defined)</td>
</tr>
</tbody>
</table>

M-3
Navigational Data Plotter

See TRACER, DEAD RECKONING

NOC

NOTICE OF CHANGE (defined)

NOTICE OF CHANGE (NOC) Approved change to a coordination drawing; also see PNOC.

NR-1

NUCLEAR-POWERED, DEEP SUBMERGENCE RESEARCH AND OCEAN ENGINEERING VEHICLE
OBJECT LOCATION AND SMALL OBJECT RECOVERY (SEARCH) PROGRAM

Program to provide for the location and recovery of small objects on the ocean floor.

OPERATING TEAM

Personnel who operate a deep submergence vehicle on a specific mission cycle; the operator is included in the vehicle's crew. Also see CREW.

OPERATIONAL EVALUATION (OPEVAL)

Test Evaluation to determine the ability of a system, component, or equipment to meet operational performance requirements specified in SORs, TDPs, Design Specifications, and other development guidelines to establish suitability for service use.

OPERATIONAL SHIPS SYSTEM

Informal Support Ships

Operational surface support ships and submarines that support a specific deep submergence system.

OPEVAL

OPERATIONAL EVALUATION (defined)

OPTICS EQUIPMENT

Equipment in a deep submergence vehicle that provides direct optical viewing outside of the vehicle; includes the vehicle's viewports, lights, and camera equipment.
PALLET CRADLE
Structure that supports a deep submergence vehicle while in transit or storage.

PAN AND TILT UNITS
Structures extending from a deep submergence vehicle or seafloor habitat on which are mounted lighting and camera equipment and that can be trained and elevated within given arcs.

PANEL, CLOCK AND TRANSPONDER RELEASE
Panel display in the DSRV of GMT and elapsed mission time. Panel also houses two switches for release of port and starboard homing transponders.

PDR
Designation for portable radiation detection equipment.

The AN/PDR-27Q RADIACMETER is carried in the Deep Submergence Rescue Vehicle; see RADIACMETER.

PERSONNEL TRANSFER CAPSULE (PTC)
Pressurized capsule that transfers divers between a Deck Decompression Chamber (DDC) in a surface support ship and their underwater work area. The PTC can also serve as a rest and refuge chamber while on the seafloor. The PTC can also be used in the Hydrostat Mode (interior pressure at 1 atmosphere) for bottom/salvage site observations. A component of a Deep Diving System (DDS).

PHASE A TESTS
Test phase that includes development, procurement qualification, and manufacturing tests on sub-assemblies, assemblies, units, and combinations thereof and that is generally conducted at the vendor's plant.
| **PHASE B TESTS** | Test phase that demonstrates that two or more subsystems meet their performance requirements; may involve testing in an operating environment. |
| **PHASE C TESTS** | Test phase that consists of a series of planned operations by a system to determine capabilities and task times and to verify and develop optimum mission sequences. |
| **PIGGYBACK** | Transportation mode in which deep submergence vehicle is secured to the deck of a Mother Submarine. |
| **PINGER, SUBMARINE DISTRESS** | Transponder near escape hatch in a submarine activated internally by submarine personnel. See BEACON SET, SONAR. |
| **PMS** | PLANNED MAINTENANCE SYSTEM |
| **PNOC** | PROPOSED NOTICE OF CHANGE (defined) |
| **PQC** | Designation for portable underwater sound communications equipment.  
The AN/PQC-3 is a diver-carried sonic communications device compatible with communications equipment in the SEALAB habitat. |
| **PRESSURE CAPSULE** | Structure to protect men and equipment from the ambient underwater environment; generally has an internal environment at one atmosphere.  
Pressure capsule is preferred usage for deep submergence vehicles. Pressure sphere indicates a spherical shape (e.g., three pressure spheres form the Deep Submergence Rescue Vehicle's pressure capsule). |
PRESSURE HULL
Pressure resistant structure, other than hard structure, including reinforced openings, penetrations and hatches, that experiences high differential pressure from submergence and that provides space for personnel.

PRESSURE SPHERE
See PRESSURE CAPSULE

PROPOSED NOTICE OF CHANGE (PNOC)
Proposed notice of change to a coordination drawing.

PTC
PERSONNEL TRANSFER CAPSULE (defined)

PTC/AQUANAUT HEAT SYSTEM
A system designed to provide hot water for a PTC space heater or an Aquanaut thermal protection suit of the hot water type.

PTC SPACE HEATER
A device or system for heating the inside of a PTC.
RADIACMETER AN/PDR-27Q

Portable radiation detection device carried in DSRV to monitor radiation levels in the rescue area and on disabled submarine survivors.

Rate Gyro Assembly

See GYROSCOPE ASSEMBLY, RATE

RCC

RESCUE CONTROL CENTER (defined)

RCC COMPUTER

Computer that performs general computations and tracking computations for INTERROGATOR-RECEIVER SET, SONAR, THREE DIMENSIONAL (Three-Dimensional Sonar) to determine ranges, bearings, and depression angles of multiple acoustic targets; installed in the Rescue Control Center (RCC) of the ASR-21 class ships.

RD

REQUIREMENTS DOCUMENT

Document prepared by the Plans and Program Division, Deep Submergence Systems Project.

RECEIVING SET, SONAR, DIRECTIONAL LISTENING AN/BQR-18

Informal Directional Listening Hydrophone

Sonar to provide deep submergence vehicle with binaural detection of acoustic signals from a distressed submarine.

RECORDER-REPRODUCER, SIGNAL DATA AN/BSH-3

Informal Speech and Data Recorder

Magnetic tape recorder for recording speech and data signals in a deep submergence vehicle.
RECOVERY PHASE
Phase of deep submergence vehicle operation for
recovery of an object from the ocean floor.
Includes (1) launch of vehicle from support ship or
submarine, (2) descent of vehicle to recovery area,
(3) attachment of recovery device to object, (4)
lifting of object (including breakout from bottom),
(5) ascent of vehicle, (6) loading object for trans-
port (including removal from water if surface
support ship is used), (7) retrieval of vehicle by
support ship or submarine. The recovery device may
provide for direct lift by the vehicle or from the
surface.

REMOTE AIRFIELD
Airfield nearest to the Remote Port that can accom-
modate aircraft transporting the Deep Submergence
Rescue Vehicle System.

REMOTE ATTACHMENT DEVICE
Clamp that automatically attaches to a fitting on
the top of the Personnel Transfer Capsule (PTC) to
enable a crane to lift PTC from water to ship or
converse.

REMOTE PORT
Port nearest to the location of a disabled submarine
having the necessary facilities for loading a DSRV
on a Submarine Rescue Ship or Mother Submarine.

REMOVABLE EQUIPMENT
External equipment removed from a deep submergence
vehicle to facilitate handling and transportation.

RESCUE CHAMBER LANDING PLATE
The reinforced circular steel plate around the escape
hatch of a submarine; during a DSRV rescue operation
the vehicle's mating skirt rests on the RESCUE CHAMBER
LANDING PLATE.
<table>
<thead>
<tr>
<th><strong>RESCUE CONTROL CENTER</strong> (RCC)</th>
<th>Compartment in ASR-21 class ships that serves as a command and control center for rescue operations; includes facilities to monitor submersible operations.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>RESCUE MISSION</strong></td>
<td>All operations related to the rescue of personnel in a disabled submarine.</td>
</tr>
<tr>
<td><strong>RESCUE MISSION SEQUENCE</strong></td>
<td>A 5-phase sequence of operations for completing a rescue mission. The five rescue mission phases are (1) Alarm, (2) Response, (3) Localization, (4) Initial Re... (5) Rescue.</td>
</tr>
<tr>
<td><strong>RESCUE PHASE</strong></td>
<td>Phase of deep submergence rescue operations beginning with the end of the first mating of the Deep Submergence Rescue Vehicle with the distressed submarine and ending when the rescue operation is completed. Also see RESCUE MISSION SEQUENCE.</td>
</tr>
<tr>
<td><strong>RESCUE</strong></td>
<td>Short title for SUBMARINE LOCATION, ESCAPE, AND RESCUE PROGRAM that consists of (1) Rescue System, (2) Location System, (3) Submarine Escape and Survival System.</td>
</tr>
<tr>
<td><strong>RESCUE HATCH</strong></td>
<td>A quick-acting-type access hatch located in the top of the Escape Trunk of a submarine. The hatch is used for assisted (SRC &amp; DSRV) personnel rescue; also see ESCAPE HATCH.</td>
</tr>
<tr>
<td><strong>Rescue Seat</strong></td>
<td>See ESCAPE TRUNK LANDING PLATE</td>
</tr>
<tr>
<td><strong>RESCUE SYSTEM</strong></td>
<td>System to provide rapid-response rescue of personnel from a submarine disabled on the ocean floor above its collapse depth.</td>
</tr>
</tbody>
</table>
RESCUE UNIT
Two Deep Submergence Rescue Vehicles (DSRV) and their personnel and support equipment and one surface support ship or two Mother Submarines.

RESCUE UNIT HOME PORT (RUHP)
Base for RESCUE UNIT where vehicles are maintained and kept in alert status.

RESPONSE PHASE
Phase of deep submergence rescue operation beginning when the Submarine Operating Authority (SUBOPAUTH) initiates a submarine disaster search and rescue program and ending when at least one Deep Submergence Rescue Vehicle and one DSRV support ship or Mother Submarine are in the area of the distressed submarine.

Right Angle Television Camera
See CAMERA, TELEVISION, RIGHT ANGLE

Rotational Hand Controller
See CONTROLLER, HAND, ROTATIONAL

RSTF
Rescue System Test Facility

RUHP
RESCUE UNIT HOME PORT (defined)

RUHP AIRFIELD
Airfield closest to a RESCUE UNIT HOME PORT that can accommodate aircraft transporting the Deep Submergence Rescue Vehicle System.
SAL

SUBMARINE ALERTING AND LOCATION

System to alert search and rescue forces as to the location of a disabled submarine. System consists of releasable free-floating transmitter buoys, acoustic pinger, attached UHG transceiver, automatic signal alarms, and airborne DF equipment.

SAKI

SUPPORT ACTIVITY - MARE ISLAND

SATURATION DIVING

An underwater operation in which the diver remains at a specific depth until the decompression requirement is independent of time at depth.

S&C

SENSORS AND CONTROLS (defined)

SCRUBBER

See CO₂ SCRUBBER

SCUBA

1. SELF-CONTAINED UNDERWATER BREATHING APPARATUS

Diving rig in which the diver carries his breathing gas in cylinders on his back. Also see BREATHING APPARATUS.

2. SELF-CLOSED CIRCUIT UNDERWATER BREATHING APPARATUS

Diving rig in which the diver rebreaths a major portion of his breathing gas that has been passed through a carbon dioxide (CO₂) absorbant. A small amount of his exhaled gas is exhausted from the system to enable addition of new gas and to avoid building up contaminants. This arrangement provides greater diving time for a given amount of gas than do open-circuit rigs. May be self-contained or with breathing gas supplied to the diver through a hose.
SCUBA (Cont.) 3. The following is a list of SCUBA designations and their descriptions.

a. SCUBA MK VI, semi-closed circuit underwater breathing apparatus.

b. SCUBA MK VIII MODs 0 and 1, semi-closed circuit underwater breathing apparatus.

c. SCUBA MK IX semi-closed circuit tethered underwater breathing apparatus.

d. SCUBA MK 10 MODs 0, 1, and 2, experimental closed circuit underwater breathing apparatus.

e. SCUBA MK 11 MOD 0, semi-closed circuit tethered underwater breathing apparatus.

SDS

SIMULATED DISTRESSED SUBMARINE (defined)

SDV

SWIMMER DELIVERY VEHICLE

(Formerly Swimmer Propulsion Unit)

SEALAB

Name for U.S. Navy open-sea experiments in saturation diving; derived from "sea laboratory." (The term SEALAB should not be used for the seafloor habitat.) SEALAB III is the fourth phase of MITS In-Situ Test Program.

SEALAB TEST GROUP (SLTG)

A group of representatives of cognizant military and contractor activities involved in test plans and procedures for a SEALAB experiment and who have been chartered specific responsibilities thereto.
<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>SEARCH PHASE</td>
<td>Phase of deep submergence vehicle operation including (1) deployment of area markers, (2) launch of vehicle, (3) descent to search area, (4) execution of search, (5) classification of sensor returns, (6) ascent of vehicle, (7) retrieval of vehicle by support ship or submarine.</td>
</tr>
<tr>
<td>SEARCH PROGRAM</td>
<td>Short title for OBJECT LOCATION AND SMALL OBJECT RECOVERY PROGRAM.</td>
</tr>
<tr>
<td>SECONDARY MISSION</td>
<td>Use of a deep submergence vehicle for activities other than its primary mission (other than RESCUE for the DSRV and SEARCH for the DSSV). Training is considered a secondary mission.</td>
</tr>
<tr>
<td>SECT</td>
<td>SUBMARINE EMERGENCY COMMUNICATION TRANSMITTER</td>
</tr>
<tr>
<td></td>
<td>Untethered radio buoy carried by Fleet Ballistic Missile Submarines.</td>
</tr>
<tr>
<td>SEIS</td>
<td>SUBMARINE ESCAPE/IMMERSION SYSTEM. Also, SUBMARINE EMERGENCY IDENTIFICATION SIGNAL</td>
</tr>
<tr>
<td>SENSORS AND CONTROLS (S&amp;C) SUBSYSTEM</td>
<td>Subsystem composed of a deep submergence vehicle's communications, sonar, optical, navigation, special devices, control and display, and computing equipment.</td>
</tr>
<tr>
<td>SESC</td>
<td>SYSTEMS ENGINEERING SUPPORT CONTRACTOR</td>
</tr>
<tr>
<td>3LT</td>
<td>SUBMARINE ESCAPE TRUNK (defined)</td>
</tr>
<tr>
<td>Term</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>SHALLOW</td>
<td>Generally considered underwater operations on the continental shelf.</td>
</tr>
<tr>
<td>SHIP CONTROL GROUP</td>
<td>Section of the Integrated Control and Display (ICAD) equipment containing the Autopilot/Digital Data Analyzer (AP/DDA) and the Ship Control Electronics.</td>
</tr>
<tr>
<td>SHIPBOARD HANDLING EQUIPMENT</td>
<td>See HANDLING EQUIPMENT</td>
</tr>
<tr>
<td>SHOCK MITIGATION RING</td>
<td>Shock absorbing ring around a deep submergence vehicle's mating skirt; minimizes impact and protects the skirt during mating operations.</td>
</tr>
<tr>
<td>SHORE POWER CONNECTOR</td>
<td>Connector used to supply battery charging power to deep submergence vehicle while mated to Mother Submarine.</td>
</tr>
<tr>
<td>SHORT RANGE SONAR</td>
<td>See DETECTING-RANGING SET, SONAR, SHORT RANGE</td>
</tr>
<tr>
<td>SHROUD, CONTROL</td>
<td>Wing around deep submergence vehicle's propeller providing steering and diving control in the cruise mode; also provides some protection to the propeller from mechanical hazards.</td>
</tr>
<tr>
<td>SIMULATED DISTRESSED SUBMARINE</td>
<td>A steel structure, the top of which resembles the Rescue Hatch area of the hull of an SSN type submarine. This structure to be lowered to the sea floor for use during DSRV testing.</td>
</tr>
<tr>
<td>SLS</td>
<td>Side Looking Sonar (See SONAR, SIDE LOOKING)</td>
</tr>
</tbody>
</table>
SLTG  SEALAB TEST GROUP (defined)

SMASH  SEMI-MOBILE ADVANCED SEA HABITAT

SOCC  SALVAGE OPERATIONAL CONTROL CENTER (defined)

SONAR, SIDE LOOKING (SLS) AN/BQS

Informal  Side Looking Sonar

Search sonar that provides continuous presentation of objects and topographic features of the ocean floor on both sides of a vehicle or sensor platform. The sonar's transmission and echo reception are in fan-shaped beams directed laterally and downward in a plane perpendicular to the fore-aft axis of the vehicle or platform.

SORTIE  One trip by surface support ship or Mother Submarine to a specific operating area; one support ship can undertake several SORTIES during a single deployment; more than one mission can be accomplished during one SORTIE. Also see MISSION, DEPLOYMENT.

SOUNDING SET, SONAR, ALTITUDE/DEPTH (ADS) AN/BQN-10

Informal  Altitude/Depth Sonar

Sonar that indicates a deep submergence vehicle's altitude above ocean floor and depth below the surface.

SPC CABLE  STRENGTH-POWER-COMMUNICATIONS CABLE (defined)

Speech and Data Recorder

See RECORDER-REPRODUCER, SIGNAL DATA

S-5
SPS  Designation for ship-mounted detecting and ranging radar. The ASR-21 will have an SPS-53A surface search radar.

SPU  SWIMMER PROPULSION UNIT. Now SWIMMER DELIVERY VEHICLE.

SQQ  Designation for ship-mounted sonar of a specialized type; see INTERROGATOR-RECEIVER SET, SONAR, THREE DIMENSIONAL. The ASR-21 will have AN/SQQ-25 Interrogator-Receiver Set, Sonar, Three Dimensional.

SQS  Designation for ship-mounted search sonar equipment. The ASR-21 will have AN/SQS-4 detecting and ranging sonar.

SRC  SUBMARINE RESCUE CHAMBER (defined) Designation for ship-mounted radio communications set. The ASR-21 will have an SRC-27 UHF Transceiver.

SSE  SUPPORT SUBSYSTEM EQUIPMENT

STABLE PLATFORM ASSEMBLY, INERTIAL NAVIGATOR

Informal  Inertial Navigator Binnacle

Three-axis gimbal system employing gyros and accelerometers for inertial sensing. Part of the Inertial Navigator Group.

STEERING TASK GROUP (STG)  Senior representatives of Navy organizations and activities, engaged in deep submergence, that advises the Project Manager, Deep Submergence Systems Project.
Steinke Hood  
See SUBMARINE ESCAPE APPLIANCE

STEP  
SUBMERGED TEST AND EVALUATION PLATFORM (defined)

STG  
STEERING TASK GROUP (defined)

STRENGTH-POWER-COMMUNICATIONS CABLE (SPC CABLE)
Cable that carries lines for electrical power and communications and is the main lifting connection between the PTC and support ship during normal underwater operations. It can lift the PTC onto the deck of the surface support ship in an emergency.

STRUCTURE, INTERNAL SUPPORT

Informal  
Birdcage
Spherical framing structure installed within deep submergence vehicle pressure capsule to mount equipment and equipment racks.

STUB SKIRT
Transition piece on a deep submergence vehicle's pressure capsule to which the mating skirt is attached; this feature allows removal of the mating skirt for transport by aircraft.

Submarine Distress Pinger

See BEACON SET, SONAR (defined)

SUBMARINE ESCAPE AND SURVIVAL SYSTEM

Informal  
Escape System
System to provide for individual exit from a submarine, including (1) improved escape trunk or chamber in the submarine, (2) Built-in Breathing System (BIBS), (3) Escape and Survival Equipment.
SUBMARINE ESCAPE APPLIANCE

Informal Steinke Hood

Device to enable personnel to exit from a submarine; consists of life jacket and removable hood; compressed air is used as the breathing gas. Named for its inventor Harris Steinke.

SUBMARINE ESCAPE TRUNK (SET)

Access lock between a submarine's pressure hull and outer hull, the upper hatch of which is an escape hatch.

SUBMARINE OPERATING AUTHORITY (SUBOPAUTH)

The commander responsible for the execution of SUBMISS/SUBSUNK search and rescue procedures.

SUBMARINE RESCUE CHAMBER (SRC)

Informal McCann Chamber

Tethered, submersible chamber carried by Submarine Rescue Ship (ASR) to rescue personnel from a disabled submarine. Carried by existing ASRs and to be carried by ASR-21 class ships.

SUBMARINE RESCUE CHAMBER STAPLES

Padeye-like devices on a submarine's rescue seat to which a Submarine Rescue Chamber (McCann Chamber) can attach turnbuckles as a safety precaution during certain mating operations; can also be used by a Deep Submergence Rescue Vehicle during certain mating operations.
SUBMARINE RESCUE SHIP (ASR)

Ship intended primarily for rescue of personnel from disabled sunken submarines; fitted with capability to support extensive diving operations.

1. Existing U.S. Navy ASRs carry the Submarine Rescue Chamber (McCann Chamber).

2. ASR-21 class ships now under construction have catamaran hull design and can transport, launch, recover, and support two Deep Submergence Rescue Vehicles; fitted with Deep Diving System MK 2 MOD 1; provision to carry DSRV Support Van.

SUBMERGED TEST AND EVALUATION PLATFORM (STEP)

SEALAB I habitat modified to support shallow water experiments in support of the Man-in-the-Sea Program.

SUBOPAUTH

SUBMARINE OPERATING AUTHORITY (defined)

Support Ships

See OPERATIONAL SHIPS SYSTEM

SUPPORT SUBSYSTEM

Fly-away support equipment for the DSRV.

SUPPORT VAN

Mobile van containing test, maintenance, and replenishment equipment and spare parts for a deep submergence vehicle. The support van is deployed with the vehicle to a Remote Port and is placed on the surface support ship. When the vehicle is supported by a submarine, specific items of equipment are removed from the van and installed or carried in the submarine.

SURFACE SUPPORT DIVER

A diver based on the surface support ship for short-duration dives in support of a deep submergence system; he may return to the surface in a PTV or by direct ascent.
SYNTATIC FOAM

Floatation material consisting of hollow glass or plastic microspheres dispersed in a polyester or epoxy resin matrix.
TARGET, SONAR

Informal Hatch Marker

Passive acoustic reflector mounted on or near a submarine escape hatch to aid hatch location by the Deep Submergence Rescue Vehicle.

TD

TECHNICAL DATA DOCUMENT (defined)

TECHEVAL

TECHNICAL EVALUATION (defined)

TECHNICAL DATA DOCUMENT (TD)

Technical data prepared by the Technical Division, Deep Submergence Systems Project.

TECHNICAL EVALUATION (TECHEVAL)

Test and analysis to determine whether a system, support system, component, equipment, or material meets design specifications, is functioning in a technically acceptable manner in its operational environment, and is technically suitable for an OPEVAL.

TEST EVALUATION AND CORRECTIVE ACTION REPORT (TICAR)

Document that diagnoses test failures and reports on corrective action taken.

TEST & EVALUATION (T&E) RESCUE CONTROL CENTER (RCC) VAN

Complex installed in a mobile van to provide tracking facilities for rescue vehicle operation during test and evaluation; the van is installed on the surface support ship.
TEST & EVALUATION (T&E) SUBMARINE

Submarine modified to support test and evaluation of a deep submergence vehicle or system.

TEST & EVALUATION (T&E) SYSTEM

Surface support ships, submarines, facilities, and equipment assigned to test and evaluate deep submergence hardware and techniques.

TEST PROCEDURE (TP)

Document explaining the scope of a test and how it is performed; includes method of operation of major equipment and use of test equipment involved in the test.

TEST REQUIREMENT OUTLINE (TRO)

Document providing a brief description of test to be performed; includes purpose, duration, systems involved, special equipment required, methodology, and responsibilities.

TEST SPECIFICATION (TS)

Document providing detailed instructions to field support groups; lists requirements such as instrumentation, operating areas, support craft, transportation, communications, security, and safety.

THERMAL PROTECTIVE SUIT

Suit providing a diver with protection from the extremely cold water.

The Wiswell Diver and Diurene Suits are of the open-circuit hot water type, which flushes hot water through the inside of a polymerized wet suit.

Three-Dimensional Sonar

See INTERROGATOR-RECEIVER SET, SONAR, THREE DIMENSIONAL

THRUSTER, DUCTED

Informal Ducted Thruster

Propulsion unit in a cylindrical housing, which provides vertical or athwartships thrust.
TICAR: TEST INVESTIGATION AND CORRECTIVE ACTION REPORT (defined)

TM: TECHNICAL MEMORANDUM

TP: TEST PROCEDURE (defined)

TRACER, DEAD RECKONING: Informal Navigation Data Plotter (preferred)
X-Y Plotter

Automatic plotter in deep submergence vehicle that operates in conjunction with the Central Processor Computer to graphically display position information.

Tracking Transponder: See TRANSPONDER SET, SONAR, TRACKING

TRANSCEIVER (XCVR): An electronic or electrical device functioning as both a transmitter and receiver.

TRANSUDER (XDCR): Device that converts electrical energy to sound energy or the converse.

TRANSUDER, DEPTH PRESSURE: Electro-mechanical device that converts physical pressure to signal voltages.

TRANSFER BALLAST SYSTEM: See BALLAST SYSTEMS.

TRANSPONDER (XPDR): Automated sonic receiver/transmitter for transmitting signals when triggered by an interrogating signal.
TRANSPONDER SET, SONAR, DOCKING (AN/BQN-12)

**Informal** Docking Transponder

Transponder mounted on the after end of the Mother Submarine's sail structure to aid underwater retrieval and mating of a deep submergence vehicle.

Transponder Interrogation Sonar

See INTERROGATOR SET, SONAR

TRANSPONDER SET, SONAR, TRACKING AN/BQN-7

**Informal** Tracking Transponder

Transponder in deep submergence vehicle that generates signal to enable surface support ship or submarine to track the vehicle.

TRANSPONDER SET, SONAR, HOMING AN/BQN-8

**Informal** Homing Transponder

Small, expendable transponder carried by deep submergence vehicle or unmanned system for planting on the ocean floor to mark an object or aid in navigation.

TRAPEZE

Arresting bar and attached supporting bars fitted to Mother Submarine to assist deep submergence vehicle alignment for mating and coming to rest directly on pylons installed on the submarine's deck. The TRAPEZE engages a hook on the vehicle.

TRIP

Activities of one deep submergence vehicle or system during one trip from the support ship or submarine.
TRUNNION FLANGE

Pressure capsule pivot/support flange located at the extremes of the common axis of the DSRV spheres. Holds the spheres to the outer null.
UMBILICAL

Connection between diver and support ship, habitat, or PTC that can carry breathing gas mixture, communications, life function monitoring, and hot water.

UIP

UNMANNED INSTRUMENT PLATFORM (defined)

Underwater Telephone

See BQC

UNDERWATER UPSIDE DOWN DAVIDT (UUDD)

Davit and winch mechanism mounted on SEALAB habitat to operate cargo canister system from surface support ship.

UNMANNED INSTRUMENT PLATFORM (UIP)

Unmanned platform, generally tethered and towed by surface ship, carrying sensors for underwater search.

UNMANNED RECOVERY VEHICLE (URV)

Unmanned device, generally tethered and controlled by surface ship, for recovering objects on the ocean floor.

Also see CABLE-CONTROLLED UNDERWATER RESEARCH VEHICLE

UQC

Designation for general utility underwater communications equipment.

1. The Test Range Support Ship ELK RIVER (IX-501) has AN/UQC-1 underwater telephone.
UQC (Cont) 2. Submarine Rescue Ships have AN/UQC-1
3. Combatant Submarines have AN/UQC-1.

Also see BQC.

UQN Designation for general utility, ship-mounted underwater sounding device. The ASR-21 will have a UQN-4 echo sounding system.

URD Designation for general utility, ship-mounted radio direction finder. The ASR-21 will have a URD-4 radio direction finder.

URV UNMANNED RECOVERY VEHICLE (defined)

UUDD UNDERWATER UPSIDE DOWN DAVIT (defined)
VAN See INTEGRATED MEDICAL AND COMMAND (IMC) VANS
See SUPPORT VAN
See TEST & EVALUATION RESCUE CONTROL CENTER (RCC) VAN

VARIABLE BALLAST See BALLAST SYSTEMS

Vertical Gyro See GYROSCOPE, VERTICAL

Vertical Obstacle Sonar See DETECTING-RANGING SET, SONAR, VERTICAL OBSTACLE

VIEWPORT OPTICS See OPTICS EQUIPMENT

VOS Vertical Obstacle Sonar
See DETECTING-RANGING SET, SONAR, VERTICAL OBSTACLE
Water Level Detector  See DETECTOR, WATER LEVEL

WBS  WORK BREAKDOWN STRUCTURE (defined)

Winch  See DOWNHAUL WINCH

WISWELL SUIT  See DIVER'S SUIT, HEATED

WORK BREAKDOWN STRUCTURE

"Family tree" division of hardware and software services and other work tasks that organizes, defines, and graphically displays the product to be produced as well as the work to be accomplished in achieving the specified product.

WQC  Designation for surface ship or submersible acoustic communications device.

    Formal  COMMUNICATION SET, SONAR

    Informal  Underwater Telephone

    ASR-21 Class will have AN/WQC-2 Underwater Telephone.
XCVR  TRANSCIEVER (defined)
XDCR  TRANSDUCER (defined)
XMTR  TRANSMITTER
XPDR  TRANSPONDER (defined)
X-Y Plotter  See TRACER, DEAD RECKONING

X-1