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DYNA: DYNAMIC STORAGE ALLOCATION
IN FORTRAN FOR THE IBM/360 OPERATING SYSTEM

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This report describes an I.B.M./360 Assembly Language routine to allow for dynamic allocation of core storage in Fortran programs. The report describes in detail the implementation and use of the dynamic allocation subroutine DYNA.

A fairly detailed knowledge of FORTRAN is assumed in the report. The dynamic routine may be implemented by the FORTRAN programmer without a detailed understanding Assembly Language routine DYNA. A complete description of DYNA is included for those programmers who the discussion is technical and assumes a knowledge of I.B.M./360 Operating System Macros and Assembly Language.
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DYNAMIC STORAGE ALLOCATION
ABSTRACT

This report describes an I.B.M./360 Assembly Language routine to allow for dynamic allocation of core storage in Fortran programs. The report describes in detail the implementation and use of the dynamic allocation subroutine DYNA.

A fairly detailed knowledge of FORTRAN is assumed in the report. The dynamic routine may be implemented by the FORTRAN programmer without a detailed understanding of the Assembly Language routine DYNA. A complete description of DYNA is included. The discussion is technical and assumes a knowledge of I.B.M./360 Operating System 'macros and Assembly Language.
1. INTRODUCTION

A major limitation of Fortran is that storage for data is allocated at compile-time by the programmer. Essentially, some optimum dimensions are selected, the program is compiled and fixed amount of storage is made available. If a particular problem requires less space than is allocated, storage is wasted. If more space is required than has been allocated, the program must be redimensioned and recompiled. In today's multiprogrammed systems, either situation is an inefficient use of system resources.

A solution to the problem is to allocate storage for data at execution time, dynamically. The general rationale is that allocation of storage for data is a dynamic function that varies with each use of a particular program.

2. DYNA: Dynamic Storage Allocation in Fortran for the IBM/360

DYNA is an assembly language subroutine that provides an interface between a Fortran program or subroutine and the operating system's (O.S.) main storage manager. Each time DYNA is called, storage is allocated and made available to the Fortran subroutine.
The next four sections discuss the OS Getmain/Freemain facility, the interface for these functions, and the Error Conditions encountered. 1

2.1 Fortran Convention

The standard Fortran call is used to call DYNA and to allocate storage. The order of the parameters is as follows:

CALL DYNA (SUB, ARRAY1, NSIZE1, ..., ARRAYN, NSIZEN)

where

SUB is the name of the Fortran subroutine the storage is allocated to

ARRAYN is the Nth array to be allocated

NSIZEN is the amount of storage in words of ARRAYN.

DYNA is called by the calling Fortran routine which in turn calls the Fortran subroutine SUB. SUB must be declared EXTERNAL in the calling routine and the parameters must not appear in COMMON.

The parameter list is a list of the addresses of each parameter in the subroutine call. The first parameter is the address of the subroutine to be called by DYNA. The last parameter has its high order byte equal to 128. The call to DYNA consists of loading the address of the parameter list in general register 1, loading the address of DYNA in register 15 and then branching to register 15 and linking register 14. Register 13 points to a save area within the calling routine (standard OS linkage convention).

1See References.
2.2 O.S. Getmain/Freemain

Getmain is an SVC which requests the control program to assign ownership of an area of main storage to a routine. This SVC has many options and is conveniently coded as a macro in assembly language. However, it has been hand coded in DYNA using the R and VU forms. The R-form requests a specific amount of main storage in register 0. The SVC returns the address of this area in general register 1. The VU-form requests an amount of main storage between two ranges. If the request cannot be satisfied, the control program will terminate the calling routine (see Error Conditions). For this form, register 1 points to a parameter list with the appropriate flag specifying the VU-request.

The Freemain SVC frees the storage assigned by the Getmain. Both the R and V forms are used and are hand coded.

2.3 The Interface

Upon entry to DYNA, the general registers are saved in an area provided by the calling routine. Then the Getmain SVC issued to obtain a work area is appropriately initialized.

The next phase is to process the parameter list and save the address of the calling routine. The parameter requests are rounded up in preparation for the double-word alignment. Once the total size of the arrays has been calculated, the second Getmain is issued. The main storage block allocated is used by DYNA to reallocate array addresses. The original array addresses are replaced with the new double-word aligned addresses. Thus, the initial parameters corresponding to the
addresses passed to DYNA of the arrays are replaced by the addresses of the main storage area to be used.

DYNA then calls the subroutine whose address is given by the first parameter in the list passed to DYNA. On return from the called subroutine DYNA frees the main storage allocated for the arrays and re-establishes the linkage to the calling program. DYNA then frees the work area allocated and returns to the calling routine.

Since DYNA obtains a work area (activation list) upon entry and frees this work at exit, DYNA is a re-entrant routine and may be called by more than one program in any order.\(^2\)

### 2.4 Error Conditions

If there is no main storage available the system will abnormally end (ABEND) with a code of S80A or S804. Other codes are possible but have yet to be encountered.

If there is some storage available but not enough to satisfy the request, DYNA calls $\&\text{ERR}1$, an error routine written in Fortran which has as an argument a vector with the following values: the address of the core that was allocated, the amount the system could allocate, the minimum requested size (usually zero) and the maximum size requested.

$\&\text{ERR}2$ is called if the parameter list has the improper number of arguments. There should always be an odd number of arguments since the first argument is the name of the Fortran subroutine called by DYNA and all other arguments are the paired names and sizes. This

\(^2\)See references.
error exit occurs in the debugging stage and does not return control. A message is printed and control is returned to the system.

3. PROGRAMMING DYNAMIC ROUTINES

The use of DYNA is relatively straightforward. The subroutine (DYNA) is reentrant and may be nested to any level. The tradeoff is in the time required to call DYNA in comparison to its efficient use of space.

3.1 Some Rules

As mentioned in 2.1 standard Fortran is used to call DYNA. The name of the subroutine to which DYNA will pass control must be declared EXTERNAL in the routine calling DYNA. The parameters in the call statement must not appear in COMMON. If an array is to be DOUBLE PRECISION, the size parameter must reflect this (e.g. ten words DOUBLE PRECISION must be passed as twenty words). DYNA always allocates on double-word boundaries. If a particular array is doubly subscripted the following form is not allowed in the called subroutine:

\[ \text{DIMENSION X(1,1)} \]

Instead, the appropriate dimensions should be passed in COMMON and used in the called program in the following manner:

\[ \text{DIMENSION X(N,M)} \]

\[ \text{COMMON N,M} \]

For vectors, either form is acceptable.
3.2 An Added Advantage

If your program follows the normal Fortran convention of storing arrays columnwise, the arrays may be doubly-subscripted and calls to subroutines, as in the Scientific Subroutine Package, may be called without conversion. Since we always allocate the exact amount of storage needed by each array, the array may also be treated (in separate routines) as a vector. Since it is useful to use doubly-subscripted arrays for input/output and certain computations and singly-subscripted arrays (vectors) for other computations it is useful to be able to eliminate conversion problems. (For a more complete discussion see IBM/Scientific Subroutine Package-Programmers Guide).

3.3 A Sample Program

Consider a program which calculate means, standard deviations and correlations. A simple call to the IBM/SC? subroutine CORRE will suffice. All I/O will not be shown as the purpose is to demonstrate the use of DYNA. We shall consider that we are calling the DOUBLE PRECISION version of CORRE.

C -- THIS IS THE MAIN ROUTINE --

COMMON N, M

EXTERNAL SUBC

C -- READ CONTROL CARD AND ALLOCATE CORE

READ (5, 10) NROWX, NCOLX

10 FORMAT (2I3)

N = NROWX

M = NCOLX
N1 = NROWX * 2
N2 = NCOLX * 2
N3 = N1 * N2
N4 = (N2 * (N2 + 1))/2

C -- CALL SUBC VIA DYNA
CALL DYNA(SUBC,X,N3,XBAR,N2,STD,N2,RX,N3,R,N4,B,N2,D,N2,T,N2)
STOP
END

C -- THIS IS SUBROUTINE SUBC
SUBROUTINE SUBC(X,NA,XBAR,NB,STD,NC,RX,RD,RE,NE,B,NF,D,NG,T,NH)

C -- NOTICE THAT IN THE SUBROUTINE WE
C -- CANNOT HAVE DUPLICATE DUMMY NAMES
DIMENSION X(N,M),XBAR(1),STD(1),RX(1),RD(1),RE(1),B(1),D(1),T(1)
COMMON N,M

C -- READ IN DATA
DO 20 I = 1, N
20 READ (5,10) (X(I,J), J = 1, M)
10 FORMAT (10F8.0)

C -- CALL CORRE
CALL CORRE(N,NA,XBAR,STD,RX,R,B,D,T)

C -- PRINT RESULTS

RETURN
END
3.4 User Documentation

Primarily, the user must know:

a) The formula to calculate the dynamic area; and

b) the amount of static storage used by the program and buffers.

A simple test run with size = 1 for all dynamic data arrays will give the base (e.g. amount of static storage). To be safe this should be rounded up to the next even K bytes. The formula is determined by the particular program. For example, the formula for our sample program would be given as follows:

\[
\text{SIZE (in bytes)} = (2 \times N3 + 5 \times N2 + N4) \times 4
\]

where

\[
N1 = \text{Number of rows in X times 2}
\]

\[
N2 = \text{Number of columns in X times 2}
\]

\[
N3 = N1 \times N2
\]

\[
N4 = (N2 \times (N2 + 1))/2
\]

the region is = BASE + SIZE rounded up to next even K bytes.

This is the estimate the user should supply on the EXEC card.

C — TO SUPPLY LESS.

C -- RESULTS IN AN 80A;

C -- TO SUPPLY MORE:

C -- IS A WASTE FOR SURE:
2. DOUBLE-WORD BOUNDARIES

CORE GUESTIMATION ALGORITHM

LINKAGE EDITOR MAP
TOTAL LENGTH
SYSIN/SYSPRINT 4K BYTES
FOR N DD CARDS N*2K BYTES
SUM (BLKSIZE*BUFN0)  M
TOTAL REQUIREMENTS (TOTAL LENGTH)+4K+N*2K+M

DYNAC

CSECT

STM 14,12,12(13) SAVE THE GENERAL REGISTERS
LR 12,15 USE GR 12 AS THE BASE REGISTER
USING DYNAC,12 TELL THE ASSEMBLER THE BASE IS
LR 2,1 SAVE REGISTER 1 FOR LATER.
LA 0,SAVESIZE GR 0 HAS THE SIZE OF SAVE AREA
BAL 1,**4 IBM CONVENTION FOR GETMAIN (R)
SVC 10 GET MAIN SVC
USING DYNASAVE,11 USE GR 11 AS SAVE BASE REGISTER
LR 11,1 RESTORE GR 1 TO ORIGINAL VALUE
LR 2,1 RESTORE GR 1 TO ORIGINAL VALUE
ST 13,SAVEAREA+4 SAVE GR 13 FOR LINKAGE
LA 13,SAVEAREA RESET THE LINKAGE
ST 1,SAVEDR1

INITIALIZATION OF THE PARAMETER LISTS, AND CONSTANTS

LA 3,MINSIZE
ST 3,GETSIZE
LA 3,FREEAREA
ST 3,GETAREA
ST 3,ERRLIST
MVI GETMO0E,X'EO'
MVI GETSP,X'00'
XC FREEAREA(16),FREEAREA
EJECT

NOW START ALLOCATING THE CORRECT ADDRESSES.

GET ADDRESS OF REAL MAIN PROGRAM
GR 4 HAS THE ADDRESS OF REAL ONE
GR 5 POINTS TO THE ARRAY ADDRESS
SAVE THE NEW PARMLIST PTR.

WANDER THRU THE PARAMETER LIST TO DETERMINE THE MAX CORE REQ'D

ZERO THE WORK REGISTER.
ZERO THE WORK REGISTER.

LOCATES EQU
10.

CLI 0(5),X'80'
BE  ERROR1
L  4,4(0,5)
L  4,0(0,4)
SRL 4,1
LA  4,1(0,4)
SLL 4,3
AR  0,4
CLI 4(5),X'80'
LA  5,8(0,5)
BNE LOCATES

* FORCING DOUBLE WORD ALIGNMENT FOR DOUBLE PRECISION ARRAYS.

ST 0,MAXSIZE
LA 1,GETLIST
SVC 4
L 2,FREEAREA
L 3,FREESIZE
C 3,MAXSIZE
BL ERROR
L 5,SAVEGR1

LOOP EQU *
ST 2,0(0,5)
L 6,4(0,5)
L 6,0(0,6)
SRL 6,1
LA 6,1(0,6)
SLL 6,3
AR 2,6
CLI 4(5),X'80'
LA 5,8(0,5)
SNE LOOP
EJECT

* NOW CALL THE REAL MAIN PROGRAM WITH THE NEW PARAMETER LIST

L 1,SAVEGR1
L 15,SAVEMAIN
BALR 16,15
GO TO IT.

* FIRST FREE THE ALLOCATED CORE.
* RETURN TO THE MAIN CALLER NORMALLY.

RETRUNS EQU *
L 0,FREESIZE
L 1,FREEAREA
SVC 10
FREE THE ALLOCATED CORE.

RETURNQ EQU *
L 13,SAVEAREA+4
LA 0,SAVESIZE
FREE UP THE SAVE AREA
LR 1,11
RETURN THE ALLOCATED ADDRESS
SVC 10
FREE MAIN
LM 14,12,12(13)
LA 15,0
BR 14

* NOT ENOUGH CORE IS ALLOCATED FOR THIS JOB
## Incorrect Setup of the Parameter List, Missing Number of Bytes

```
ERROR EQU *  
   LA 1, ERRLIST  
   L 15, =V(SERR1)  
   LA 14, RETRUNS  

* INCORRECT SETUP OF THE PARAMETER LIST, MISSING NUMBER OF BYTES  
* ERROR1 EQU *  
   LA 14, RETURNQ  
   L 15, =V(SERR2)  
   BR 15  

***************  DYNAMIC SAVE AREA AND CONSTANTS FOR PROGRAM  
* THE ADDRESSES AND CONSTANTS ARE FILLED IN AT EXECUTION TIME  
***************  
LTORG  
DYNASAVE DSECT  
SAVEBEG EQU *  
   DS 0F  
GETLIST EQU *  
   GETSIZE DS AL4(MINSIZE)  
   GETAREA DS AL4(FREEAREA)  
   GETMODE DS XL1'EO'  
   GETSP DS XL1'OO'  

* DS 0F  
   FREEAREA DS AL4(0)  
   FREE_SIZE DS 1F'0'  
   MIN_SIZE DS 1F'0'  
   MAX_SIZE DS 1F'0'  
   ERRLIST DS AL4(FREEAREA)  
   SAVEAREA DS 18F'0'  
   SAVEMR1 DS 01F'0'  
   SAVEEND EQU  
   SAVESIZE EQU SAVEEND-SAVEBEG  
END  
```
SUBROUTINE $ERR1(ICORE)
DIMENSION ICORE(4)
PRINT 10,ICORE(1),ICORE(2),ICORE(4)
FORMAT(•ODYN ERROR: INSUFFICIENT CORE FOR PROGRAM '//' $ERR10)
1 'ALLOCATED CORE AT '28,' OF '16,' BYTES, BUT REQUIRED'
2 '16,' BYTES.'//' $ERR1050
RETURN $ERR1070
END $ERR1080

SUBROUTINE $ERR2
PRINT 10 $ERR200
FORMAT(•ODYN ERROR: INCORRECT PARAMETER LIST SETUP') $ERR2030
STOP $ERR2040
END $ERR2050
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