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SECOND TECHNICAL ANNUAL SUMMARY REPORT

ON THE PROPAGATION OF VLF WAVES IN SOLIDS

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Zusammenfassung.


Im experimentellen Teil werden die Messungen der Feldstärke eigener und kommerzieller Sender, so wie die dazu notwendigen Meßgeräte beschrieben.

Die Ergebnisse des Experiments und der Theorie werden eingehend erläutert und mit einander verglichen.

Summary.

A thorough theoretical study of the propagation of VLF-waves in homogeneous conducting media has been performed. The formulas and diagrams deduced for the electromagnetic fields of a magnetic dipole and quadrupole are given in terms of distance, conductivity, and the positions of the transmitting and receiving aerials. From these, a technique of determining the conductivity of geological conductors could be worked out.

The experimental section gives a description of the measurements of the intensities of our own and of commercial transmitters as well as of the required measuring equipment.

The results of experiment and theory are explained in detail and compared with one another in a special section.
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Measurement of the electrical conductivity of rock by means of low-frequency magnetic fields and their propagation

(1) Introduction

The mechanism of the propagation of VLF electromagnetic waves (ν < 10 kcps) in the Earth's interior and on the surface has found little explanation so far. The long range of such waves, in particular when emitted from an underground transmitter, is striking. The mechanism of long-distance propagation presumably is that the transmission aerial emits electromagnetic waves to the Earth's surface. These waves propagate along the surface or in the space between the surface and the ionosphere, penetrate into the ground and are received by the receiving aerial (Fig. 1). Besides by the transmission power and the distance between receiver and transmitter, the field strength at the point of reception is largely dependent on the electrical properties of the soil between the surface and the receiver or transmitter station, which exerts a strong attenuation because of its electrical conductivity. The absorption of electromagnetic energy in this soil is dependent on frequency. Waves of low frequency are damped less than waves of higher frequency. For this reason, the frequency band below 20 kcps (vacuum wavelength greater than 15 km) is particularly suitable for subterranean communication. The positions of the transmitter and the receiver must be
chosen in view of the conductivity of the area in question. But the conductivity of a large region cannot be deduced with the required accuracy from the conductivities of laboratory samples since the grounds are not uniform. Sounding tests in general involve troubles in reproducing uniquely the conditions of contact with the rock. A perfectly integrating method, i.e. one averaging over long distances, is the measurement of conductivity using a variable magnetic field. Its basic idea is as follows: a magnetic coil is fed with an alternating current \( I \cdot \exp(i\omega t) \). The magnetic field \( \mathbf{H} \) along its axis is measured at a distance \( r \). The greater the conductivity \( \sigma \) of the medium the greater the eddy losses and the weaker the received field.

(II) Theory. (Prof. Cap, Dr. Hommel)

§1. The field of a magnetic dipole

The calculation of the magnetic intensity of a coil in dissipative media is based on the theory of the Hertzian dipole and on Maxwell's equations. After isolating the time-dependent term \( \exp(+i\omega t) \) and introducing the complex dielectric constant \( \varepsilon'' = \varepsilon - i \frac{\sigma}{\omega \varepsilon_0} \), where \( \sigma \) is the conductivity as measured in ohms\(^{-1}\) m\(^{-1}\), and when no electrical charge is present, Maxwell's equations in the absolute system of units are
\[ \text{curl } \vec{H} = \epsilon_0 \omega \vec{E} \]
\[ \text{curl } \vec{E} = -\mu_0 \omega \vec{H} \]
\[ \text{div } \vec{H} = 0 \]
\[ \text{div } \vec{E} = 0 \]

Through known transformations one arrives at the Helmholtz equation for \( \vec{H} \)

\[ \Delta \vec{H} + k^2 \vec{H} = 0 \quad \text{with} \quad k^2 = \omega^2 \epsilon_0 \mu_0 \left( \epsilon - i \frac{\sigma}{\omega \epsilon_0} \right) = \omega_0^2 \mu_0 \epsilon_0 \]

When referring Eq. (2) particularly to an elementary magnetic dipole at the coordinate origin it is convenient to introduce spherical coordinates. In this case, however, Eq. (2) assumes a form which is very awkward for solving. We therefore introduce the Fitzgerald radiation vector as is usual in the case of magnetic aerials. We write

\[ \vec{E} = -\mu_0 \omega \text{curl } \vec{F} \]
\[ \vec{H} = \epsilon_0 \epsilon_0 \omega^2 \vec{F} + \text{grad } U \]

The term grad \( U \) is to conserve the general validity of the solution through the specialization of \( \vec{F} \). Inserting (3) in (1) we fulfill two equations identically. Furthermore, we have

\[ \text{grad } U = \text{curl } \text{curl } \vec{F} - k^2 \vec{F} \]

and

\[ k^2 \text{ div } \vec{F} + \text{div } \text{grad } U = 0 \]

after having applied the operator \( \text{div} \) to Eq. (4). Hence, Eq. (4) does not lead to any new results. With the specialization \( \vec{F} = \{ F_r, 0, 0 \} \), which does not restrict the general validity of the solution, we get from (4)
The last two equations can be fulfilled by the substitution

\[ u = \frac{\partial F_r}{\partial r} \]

Inserting (6) and the substitution

\[ F_r = rw \quad w = w(r, \phi, \varphi) \]

into (4-r), and since

\[ \Delta w = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial w}{\partial r} \right) + \frac{1}{r^2 \sin \phi} \frac{\partial}{\partial \phi} \left( \sin \phi \frac{\partial w}{\partial \phi} \right) + \frac{1}{r^2 \sin^2 \phi} \frac{\partial^2 w}{\partial \varphi^2} \]

we get from (4) the Helmholtz equation

\[ \Delta w + k^2 w = 0 \]

Then, inserting (7) in (3), we obtain the field strengths

\[ E_r = 0; \quad E_\phi = -\mu_0 \omega \frac{1}{r} \frac{\partial w}{\partial \phi}; \quad E_\varphi = \mu_0 \omega \frac{\partial w}{\partial \phi} \]

\[ H_r = k^2 rw + \frac{\partial^2 (rw)}{\partial r^2}; \quad H_\phi = \frac{1}{r} \frac{\partial^2 (rw)}{\partial \phi \partial r}; \quad H_\varphi = \frac{1}{r \sin \phi} \frac{\partial^2 (rw)}{\partial \varphi \partial r} \]

This is the most general solution of the electromagnetic field of a magnetic antenna embedded in a conducting medium.

In order to solve (9) we use the known substitution

\[ w(r, \phi, \varphi) = F_\phi (\cos \phi) (a_m \cos m\varphi + b_m \sin m\varphi) \cdot R_1(r) \]

to obtain
As is well known, the solution of this Bessel type differential equation is

\[ R_1(r) = \frac{1}{\sqrt{2}} Z_{1+\frac{1}{2}}(k^*r) \]

where \( Z \) is a general cylindrical function. As we are concerned not with standing but with propagating waves we choose Hankel functions for \( Z \) to obtain

\[ R_1(r) = r^{1}(\frac{d}{dr})^{1}\frac{e^{ik^*r}}{r} \]

since Bessel functions with half-integer subscripts can be reduced to \( \sin k^*r \) or to \( e^{ik^*r} \). Thus we get

\[ 1 = 0 \]

\[ w = \frac{e^{ik^*r}}{r} \]

This solution produces fields that are independent of the angle \( \phi \). As it corresponds to a magnetic pole it is not interesting from the physical viewpoint.

\[ l = 1 \] (magnetic dipole)

If we use only the asymptotic solution we have

\[ rw(r, \phi, \varphi) = \cos \phi (a_1 \cos \varphi + b_1 \sin \varphi)(-\frac{\theta}{r} - i k^* e^{-ik^*r}) \]

and obtain

\[ H_r = A \cos \phi (\cos \varphi + B \sin \varphi) \left( \frac{2}{r^3} e^{-ik^*r} + \frac{2ik^*}{r^2} e^{-ik^*r} \right) \]

\[ H_\theta = -A \sin \phi (\cos \varphi + B \sin \varphi) \left( \frac{e^{-ik^*r}}{r^3} + \frac{ik^*}{r^2} e^{-ik^*r} - \frac{k^2 e^{-ik^*r}}{r} \right) \]
H_\varphi = \cot \varphi (\sin \varphi + B \cos \varphi) \left( \frac{e^{-ikr}}{r^3} + \frac{ik}{r^2} e^{-ikr} - \frac{k^2}{r} e^{-ikr} \right)

H_\varphi = 0 \text{ for } \frac{\partial}{\partial \varphi} = 0. \text{ In (17) and (18) we have then } B = 0, \cos \varphi = 1. \text{ We do not calculate the electrical field strength as only } H \text{ is measured. The constant } A \text{ can be determined by passing to the static limit } k^2 \to 0. \text{ With } \varphi = 0 \text{ (xz-plane, cf. Fig. 2) we get}

H_r = A \cos \varphi \frac{2}{r^3}, \quad H_\varphi = -A \sin \varphi \frac{1}{r^3}

From this, \quad A = \left| \frac{2}{r^3} \right| = a

and with \frac{\partial}{\partial \varphi} we find the field of a magnetic dipole

(19) \quad H_r = m \cos \varphi \left( \frac{2}{r^3} e^{-ikr} + \frac{2ik}{r^2} e^{-ikr} \right)

(20) \quad H_\varphi = -m \sin \varphi \left( \frac{e^{-ikr}}{r^3} + \frac{ik}{r^2} e^{-ikr} - \frac{k^2}{r} e^{-ikr} \right).

We will now assume that the magnetic dipole be materialized as an infinitesimal frame antenna inside a hollow sphere of radius R. Let H^i be the field in the hollow sphere and H^a the field in the conducting medium. We have then

(21) \quad H_\varphi^a (R) = H_\varphi^a (R).

For the hollow (air) \sigma = 0, and therefore, according to (2),

k_o^2 = \omega^2 \epsilon_o \mu_o \epsilon_o.

From (21) follows

(22) \quad m_i \left( \frac{1 + \frac{k_o}{R^2}}{R^2 - \frac{k_o}{R}} \right) e^{-ik_o R} + ik_o R = m_o.
Fig.: 1

Fig.: 2

Fig.: 3
The amplitude $m_a$ of the electromagnetic field in the medium thus depends not only on the magnetic moment of the frame antenna but also on the radius $R$ of the hollow sphere (and on $k_o$ and $k^*$). Therefore, in practice the amplitude $m_a$ will not be calculated from the antenna current etc. but will be determined from one or several absolute measurements of field strength. For $m_i$ we have for an alternating current in vacuo

$$m_i = \omega \mu_0 I F n.$$  

$F$ is the frame area, $I$ is the current, $n$ is the number of turns. Through the relations

$$F = r^2, R = \frac{q}{2} 2 \pi n \text{ (resistance of coil)}$$

$I = \sqrt{\frac{N}{R}}$, where $N$ denotes the power, Eq. (23) for a given length of wire (given weight of antenna) assumes the form

$$m_i = \frac{i \omega \mu_0}{\sqrt{\pi}} \frac{q}{\sqrt{q}} 1\frac{3/2}{4} 1. \frac{1}{4\pi n}.$$

With power given it is therefore desirable to take few as possible turns (great $F$) of a thick low-resistivity wire. (Even if $I$ is variable it is desirable to make $r$ as great as possible.)

§2. Theory of the measurement of low-frequency magnetic fields

The magnetic fields in a conducting medium produced by a frame antenna in a hollow space have, according to §§ 1 and 3, the form

$$H_r = H_r(r, \phi); \ H_\phi = H_\phi(r, \phi).$$
when we measure the magnetic field at a point \(P(r, \theta)\) by means of the voltage induced in a little loop (cf. Fig. 2), then we will find that this voltage depends on the angle \(\psi\) formed by the normal \(\vec{n}\) to the loop (ferrite antenna, etc.) and the \(z\)-axis. As measurement of the fields within the conducting medium is not possible, the measuring loop is placed at a distance \(r\) from the transmitter in a hollow space. Let \(d\) be the distance between the measuring loop and the wall of the hollow space. The field strength \(H\) at the place of the loop is then

\[
H_r(r, \theta) = m_s \cos \theta \left( \frac{2}{r^3} e^{-ik_0r} + \frac{2ik_0}{r^2} e^{-ik_0r} \right)
\]

\[
H_\phi(r, \theta) = -m_s \sin \theta \left( \frac{-ik_0r}{r^2} + \frac{ik_0}{r} e^{-ik_0r} - \frac{k_0^2}{r} e^{-ik_0r} \right)
\]

where \(k_0\) denotes the values for air. \(m_s\) can be found from the boundary condition

\[
\frac{H_\phi(r-d, \theta)}{\sin \theta} = -m_s \left( \frac{e^{-ik_0(r-d)}}{(r-d)^3} + \frac{ik_0}{(r-d)^2} e^{-ik_0(r-d)} - \frac{k_0^2}{(r-d)^2} e^{-ik_0(r-d)} \right)
\]

\[
\frac{H_\phi(r-d, \theta)}{\sin \theta} = -m_s \left( \frac{e^{-ik_0(r-d)}}{(r-d)^3} + \frac{ik_0}{(r-d)^2} e^{-ik_0(r-d)} - \frac{k_0^2}{(r-d)^2} e^{-ik_0(r-d)} \right)
\]

If measurement is made quite close to the wall \((d \approx 0)\) one can use \((19) (20)\) for the formulas. Experiments with \(1\) kcps showed no difference even when the antenna was \(15\) m off the wall. For \(d \approx 0\) we have thus

\[
H_r(r, \theta) = \cos \theta \cdot f_r(r),
\]

\[
f_r(r) = m_s \left( \frac{2}{r^3} e^{-ik_0r} + \frac{2ik_0}{r^2} e^{-ik_0r} \right)
\]

\[
H_\phi(r, \theta) = -\sin \theta \cdot f_\phi(r)
\]
fig.: 4

f = 3 kHz; r = 316 m
The voltage induced in a measuring loop of area \( f \) (very small) is given by \( \frac{\partial}{\partial t} = i \omega \).

(31) \[ |U| = -\mu_0 \omega |H| \cos \psi \]

With the distance \( r \) from the transmitter fixed we have for the measured value \( |H| \)

(32) \[ |H| = \frac{-U(r, \psi)}{\mu_0 f \cos \psi} \text{ or } U(r, \theta, \psi) = A(\omega) \sqrt{\frac{f^2 \cos^2 \theta + \sin^2 \theta \cos \psi}{r^2}} \]

The function \( U(r, \theta, \psi) \) according to (31) was measured for

1. \( \psi = 3 \text{kops}, r = 316 \text{ m}, \theta = 90^\circ, 350^\circ, U = B \cos \psi, \text{Fig. 4} \), wherefrom \( B = 7.55 \) (90^\circ); \( B = 12.46 \) (350^\circ). (The angle \( \theta \) is plotted in the center of the polar graph, the angle \( \psi \) at the periphery.) The individual points of the curve correspond to different values of \( \psi \).

Measurements were made at \( \psi = 0^\circ, 30^\circ, 60^\circ, \text{etc. up to } 360^\circ \)

(12 readings).

2. \( \psi = 5 \text{kops}, r = 1000 \text{ m}, \text{Fig. 5} \)

\[ \theta = 0^\circ, 180^\circ \]
\[ B = 13.59 \]
\[ \theta = 30^\circ, 210^\circ \]
\[ B = 8.09 \]
\[ \theta = 90^\circ, 270^\circ \]
\[ B = 7.55 \]
\[ \theta = 150^\circ, 330^\circ \]
\[ B = 13.30 \]

3. \( \psi = 3 \text{kops}, r = 100 \text{ m}, \text{Fig. 6} \)

\[ \theta = 0^\circ, 180^\circ \]
\[ B = 14.244 \]
\[ \theta = 10^\circ, 190^\circ \]
\[ B = 13.688 \]
\[ \theta = 40^\circ, 220^\circ \]
\[ B = 10.699 \]
\[ \theta = 70^\circ, 250^\circ \]
\[ B = 7.646 \]
\[ \theta = 130^\circ, 310^\circ \]
\[ B = 8.944 \]
\[ \theta = 160^\circ, 340^\circ \]
\[ B = 12.436 \]


\[ f_1(r) = \mu_0 \left( e^{-ik \frac{r}{r^2}} + \frac{ik}{r} e^{-ik \frac{r}{r^2}} - \frac{k^2}{r^2} e^{-ik \frac{r}{r^2}} \right) \]

and consequently

(30) \[ H_2 = H_r + H_\theta = f_r \cos \theta + f_\theta \sin \theta \]
These measurements show that at such distances one is still far from the far field. For the latter, the terms with higher negative powers of $r$ can be omitted. Thus,

\[ H_0 = m \sin \phi k^2 \frac{e^{-ikr}}{r}, \quad H_r \approx 0. \]

Therefore, $H_0 > H_r$ and $|H| \approx 0$ should hold for $\phi = 0^\circ$. But this is not the case, or even $B(0^\circ) > B(90^\circ)$, cf. Fig. 5. However, the measurements were not further evaluated as they were made in different kinds of rock and served only as a first rough check of the theory.

§3. Numerical data

In §2 we defined

\[ k^2 = \omega^2 \varepsilon_0 \mu_0 \left( \varepsilon - \frac{i\sigma}{\omega \varepsilon_0} \right) \]

where

\[ \varepsilon_0 = 8.859 \times 10^{-12} \text{ amp sec/volts m} \]

\[ \mu_0 = 1.256 \times 10^{-6} \text{ volts sec/amp m}, \mu = 1. \]

Splitting $k^2 = \omega \sqrt{\varepsilon_0 \mu_0} \sqrt{\varepsilon - \frac{i\sigma}{\omega \varepsilon_0}}$ into its real and imaginary parts yields

\[ k^2 = k_1 - ik_2 \]

\[ k_1 = \sqrt{\frac{\omega^2 \varepsilon_0 \mu_0}{2} \left[ 1 + \sqrt{1 + \left( \frac{\sigma}{\omega \varepsilon_0 \mu_0} \right)^2} \right]} \]

\[ k_2 = \sqrt{\frac{\omega^2 \varepsilon_0 \mu_0}{2} \left[ 1 - \sqrt{1 + \left( \frac{\sigma}{\omega \varepsilon_0 \mu_0} \right)^2} \right]} \]
$f \cdot 34 \text{kHz} \quad r = 1000 \text{m}$

Fig.: 5
We now distinguish two cases.

(1) **Displacement current neglected.**

For \( \left( \frac{\sigma}{\omega \varepsilon_0} \right)^2 >> 1 \) we can simplify (38) (39); then we get

\[
\begin{align*}
(40) & \quad k_1 \approx + \sqrt{\frac{\omega \mu \sigma}{2}} \\
(41) & \quad k_2 \approx + \sqrt{\frac{\omega \mu \sigma}{2}} \approx k_1 \\
(42) & \quad k_k \approx \sqrt{\frac{\omega \mu \sigma}{2}} (1 - i) = k_k(1 - i).
\end{align*}
\]

The same expressions can be got when the displacement current is neglected. For \( \varepsilon \approx 10 \), this leads to the postulate \( \frac{\sigma}{\varepsilon} >> 8 \cdot 10^{-11} \). From this it follows that when every value

\[
\frac{\sigma}{\varepsilon} > 10^{-8}
\]

is regarded as relatively great, the range

- \( \sigma = 10^{-5} \) permits neglection from \( \nu < 1 \) kcps on
- \( \sigma = 10^{-4} \) permits neglection from \( \nu < 10 \) kcps on
- \( \sigma = 10^{-3} \) permits neglection from \( \nu < 100 \) kcps on.

As the conductivity is probably around \( 10^{-4} \), and since we always employed frequencies of \( \nu < 10 \) kcps, this neglection seems to be justified in most of the cases.

(2) **Displacement current not neglected.**

\( k_1 \) and \( k_2 \) in this case have to be calculated from (38) (39). Inserting (37) in (26) and (28), and after squaring we get

\[
(43) \quad |H_x|^2 = 4m^2 \cos^2 \theta e^{-2k_2 r} \left( \frac{1}{r^2} + \frac{k_2}{r^2} \right)^2 \left( \frac{k^2}{r^4} \right).
\]
\[ |H_\theta|^2 = m^2 \sin^2 \phi e^{-2k_2 r} \left( \frac{1}{r^3} + \frac{k_2}{r^2} + \frac{k_2^2 - k_1^2}{r} \right)^2 + \left( \frac{k_1}{r^2} + \frac{2k_1 k_2}{r} \right)^2. \]

Thus,
\[ |\vec{H}| = me^{-k_2 r} \left\{ 4 \cos^2 \phi \left[ \frac{1}{r^6} + \frac{2k_2}{r^5} + \frac{k_1^2 + k_2^2}{r^4} \right] + \sin^2 \phi \left[ \frac{1}{r^6} + \frac{2k_2}{r^5} + \frac{3k_2^2 - k_1^2}{r^4} + \frac{2k_1^3 + 2k_1 k_2^2}{r^3} + \frac{k_2^4 + k_1^4 + 2k_1^2 k_2^2}{r^2} \right] \right. \]
\[ + \left. \frac{1}{r^2} \right\} \].

For the measurements with \( \phi = 0^\circ \) and \( 90^\circ \) (cf. Figs. 4-6) we have
\[ \phi = 0^\circ; \]
\[ H_\theta = 0; |\vec{H}| = 2m e^{-k_2 r} \left\{ \frac{1}{r^6} + \frac{2k_2}{r^5} + \frac{k_1^2 + k_2^2}{r^4} \right\}^{1/2}. \]

\[ \phi = 90^\circ; \]
\[ H_r = 0; |\vec{H}| = me^{-k_2 r} \left\{ \frac{1}{r^6} + \frac{2k_2}{r^5} + \frac{3k_2^2 - k_1^2}{r^4} + \frac{2k_1^3 + 2k_1 k_2^2}{r^3} + \frac{k_2^4 + k_1^4 + 2k_1^2 k_2^2}{r^2} \right\}^{1/2}. \]

Neglecting the displacement current \( (k_1 = k_2 \approx \frac{\omega \mu_0}{2}) \),
we obtain with \( \alpha = \omega \sigma \)
\[ \phi = 0^\circ; |\vec{H}| = |H_r| = 2m e^{-k_2 r} \left\{ \frac{1}{r^6} + \frac{\omega \mu_0}{r^5} + \frac{\omega \mu_0}{r^4} \right\}^{1/2}. \]
We now define

$$f(r, \alpha) = e^{-\frac{\mu_0 \alpha}{2} r} \left\{ \frac{1}{r^6} + \frac{2}{r^5} + \frac{\mu_0 \alpha}{r^4} + \frac{2 \mu_0 \alpha^2}{r^3} \right\}^{1/2}$$

and calculate $f(r, \alpha)$ as a function of the one variable with the other variable fixed. Fig. 7 shows $f(r; \alpha)$ and Fig. 8 shows $f(\alpha; r)$. Fig. 7a is the same as Fig. 7, but on a larger scale.

We define

$$g(r, \alpha) = e^{-\frac{\mu_0 \alpha}{2} r} \left\{ \frac{1}{r^6} + \frac{2}{r^5} + \frac{\mu_0 \alpha}{r^4} + \frac{2 \mu_0 \alpha^2}{r^3} \right\}^{1/2}$$

and calculate $g(r, \alpha)$ as a function of one variable with the other variable fixed. Fig. 9 shows $g(r; \alpha)$, Fig. 10 shows $g(\alpha; r)$.

Neglecting the displacement current we find from (45) the amount of $|F|$ which is

$$|F| = m e^{-\frac{\mu_0 \alpha}{2} r} \left\{ \frac{4 \cos^2 \delta}{r^6} + \frac{2 \mu_0^2}{r^5} + \frac{\mu_0 \alpha}{r^4} + \frac{\mu_0 \alpha^2}{r^3} \right\}^{1/2}$$

Let $h(r, \alpha, \delta)$ be the quantity $\frac{|F|}{m}$. This function was computed:
Fig. 11 $h(r;\theta)$ for $\sigma = 10^{-3}$ and $\sigma = 10^{-4}$ (Tables 1 and 2)

Fig. 12 $h(r;\alpha)$ for $\theta = 45^\circ$ (Table 3)

Fig. 13 $h(\theta;r)$ for $\sigma = 10^{-4}$ (Table 1) and $\sigma = 10^{-3}$ (Table 2)

Fig. 14 $h(\theta;\alpha)$ for $r = 3160$ m (Table 5) and $r = 1000$ m (Table 4)

Fig. 15 $h(\alpha;r)$ for $\theta = 45^\circ$ (Table 3)

Fig. 16 $h(\alpha;\theta)$ for $r = 3160$ m (Table 5) and $r = 1000$ m (Table 4)

for $1 < \alpha < 1000$, i.e. for $5 \cdot 10^{-5} < \sigma < 5 \cdot 10^{-2}$

The results of the calculations are compiled in the following tables:

Table 1 Figs. 11, 13 $h(r;\theta)$ and $h(\theta;r)$, $\sigma = 10^{-4}$

Table 2 Figs. 11, 13 $h(r;\theta)$ and $h(\theta;r)$, $\sigma = 10^{-3}$

Table 3 Figs. 12, 15 $h(\alpha;r)$ $\theta = 45^\circ$

Table 4 Figs. 14, 16 $h(\alpha;\theta)$ $r = 1000$ m

Table 5 Figs. 14, 16 $h(\alpha;\theta)$ $r = 3160$ m

Evaluating the formulas

\begin{equation}
(38) \quad k_1 = + \sqrt{\frac{\omega \mu \epsilon \epsilon_0}{2}} \frac{1}{1 + \sqrt{1 + \frac{\sigma}{\omega \epsilon_0}}} \sqrt{1 + \sqrt{1 + \frac{\sigma}{\omega \epsilon_0}}^2}
\end{equation}

\begin{equation}
(39) \quad k_2 = + \sqrt{\frac{\omega \mu \epsilon \epsilon_0}{2}} \frac{1}{-1 + \sqrt{1 + \frac{\sigma}{\omega \epsilon_0}}^2}
\end{equation}

\begin{equation}
(42) \quad k_3 = \sqrt{\frac{\omega \mu \sigma}{2}} \quad \text{(displacement current neglected)}
\end{equation}

and using the values $\epsilon_0 = 8.859 \cdot 10^{-12}$, $\mu_0 = 1.256 \cdot 10^{-6}$ for

3000 cps, $\epsilon = 12.5$ we find
$g(\alpha; r)$

- $\alpha = 0.6$
- $u = 37.3000 \, s^1$

Fig.: 10
$h(r) \propto 10^{-4}$
$
\theta = 0.6$

Fig. 13
<table>
<thead>
<tr>
<th>r (r)</th>
<th>0°</th>
<th>45°</th>
<th>90°</th>
</tr>
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<td>1.58·10⁻³</td>
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</tr>
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<tr>
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<td>1.42·10⁻⁹</td>
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<table>
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<td>1.61·10⁻⁹</td>
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<td></td>
</tr>
<tr>
<td>10⁻⁴</td>
<td>1.58·10⁻⁹</td>
<td>1.57·10⁻⁹</td>
<td>1.53·10⁻⁹</td>
<td>1.48·10⁻⁹</td>
<td>1.42·10⁻⁹</td>
<td>1.38·10⁻⁹</td>
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<td>7.58·10⁻¹⁰</td>
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<td>2.66·10⁻¹¹</td>
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<td>1.71·10⁻¹¹</td>
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</table>
It is easy to see (cf. p. 11) that the displacement current at a frequency of 3000 cps can be neglected only for conductivities greater than $10^{-4}$.

Further calculation gives

<table>
<thead>
<tr>
<th>$\sigma$ (in $10^{-6}$)</th>
<th>$k_1$</th>
<th>$k_2$</th>
<th>$k_3$</th>
<th>$\alpha = \omega \sigma$</th>
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<td>1.075 $\cdot 10^{-3}$</td>
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<td>3.434 $\cdot 10^{-3}$</td>
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<td>2.43 $\cdot 10^{-2}$</td>
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</tbody>
</table>

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Further calculation gives

<table>
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<tr>
<th>$\sigma$ (in $10^{-5}$)</th>
<th>$k_1$</th>
<th>$k_2$</th>
<th>$k_3$</th>
</tr>
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<tbody>
<tr>
<td>$10^5$ cps, $\varepsilon = 11.5$</td>
<td>$k_1 = 7.1263 \cdot 10^{-3}$</td>
<td>$k_2 = 5.5455 \cdot 10^{-4}$</td>
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</tr>
<tr>
<td>$10^4$ cps, $\varepsilon = 12.5$</td>
<td>$k_1 = 8.4934 \cdot 10^{-3}$</td>
<td>$k_2 = 4.6482 \cdot 10^{-3}$</td>
<td></td>
</tr>
<tr>
<td>$10^3$ cps, $\varepsilon = 14.5$</td>
<td>$k_1 = 6.3037 \cdot 10^{-3}$</td>
<td>$k_2 = 6.2607 \cdot 10^{-3}$</td>
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Table 6

Table 7

<table>
<thead>
<tr>
<th>$\sigma$ (in $10^{-5}$)</th>
<th>$k_1$</th>
<th>$k_2$</th>
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<td>$10^5$ cps, $\varepsilon = 11.5$</td>
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<td>$k_1 = 6.3037 \cdot 10^{-3}$</td>
<td>$k_2 = 6.2607 \cdot 10^{-3}$</td>
</tr>
<tr>
<td>$x [m]$</td>
<td>$5 \cdot 10^{-5}$</td>
<td>$8 \cdot 10^{-5}$</td>
</tr>
<tr>
<td>--------</td>
<td>------------------</td>
<td>------------------</td>
</tr>
<tr>
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This shows that the quantities determinant for the propagation are highly dependent on the frequency.

Neglecting the displacement current we now calculate the ratio $|H_r|/|H_\phi|$ as this is independent of the constant $\lambda$ involved in the measurement. Considering the angular dependence we find from (48) and (49) with (42) the expression

$$\frac{|H_r|}{|H_\phi|} = 2 \cot \theta \left( \frac{1}{r^3} + \frac{2k_3}{r^5} + \frac{2k_3^2}{r^7} \right)^{1/2}$$

$$\left( \frac{1}{r^6} + \frac{2k_3}{r^8} + \frac{2k_3^2}{r^{10}} + \frac{4k_3^3}{r^{12}} + \frac{4k_3^4}{r^{14}} \right)^{1/2} = \nu(r)$$

Fig. 17 was plotted with $\theta = 45^\circ$, $k_3 = 7.695 \times 10^{-4}$, i.e. $\nu = 5 \times 10^{-5}$, $\nu = 3$ kcps. We can see that at distances of about 1 km we are by far not in the wave field. The inequality $|H_\phi| > |H_r|$ does not yet indicate the wave field; only $|H_\phi| > |H_r|$ does. The distance $r_f$ from which on $|H_\phi|$ is greater than $|H_r|$ can be computed from the condition $f(r_f, \sigma) = g(r_f, \sigma)$.

A preliminary estimate of the equation for $r_f$ gives

$$r_f = \frac{1670}{\nu \sigma} \text{[m]}$$

which, however, we do not claim to be correct.

On the other hand we can, keeping $r$ fixed, search for an optimum $\omega \sigma$-product at which $|H_\phi|$ has a maximum. From $\partial H_\phi/\partial(\omega \sigma) = 0$ we find the rough estimate

$$\omega \sigma = \frac{(2140)^2}{r^2}$$

Also these considerations are intended to be continued on a larger scale next year.
§ 4. The magnetic quadrupole

The field of a magnetic dipole was dealt with in §2. The intensity of this field tends to infinity with \( r \to 0 \), which corresponds to the ideal representation of a circular coil by a dipole. The formulas given are therefore not valid for small values of \( r \). To estimate up to what distances the dipole formulas are applicable one can calculate either the magnetic field of an a.c. circular coil or the quadrupole term \( l = 2 \).

For the vector potential of a suitably arranged circular coil there is only a \( \varphi \)-component

\[
A_\varphi = \frac{1}{4\pi} \int_0^{2\pi} i a \cos \varphi \, e^{-ikR} \, d\varphi
\]

\( \Delta \varphi = \varphi \), where

\[
R^2 = r^2 + a^2 - 2ar \cos \varphi \sin \beta
\]

This corresponds to the Biot-Savart formula extended to non-static processes.

\( H_r \) can be calculated from \( H_r = \text{curl}_r A_\varphi = \)

\[
H_r = - \frac{1}{r \sin \beta} \frac{\partial}{\partial \beta} (A_\varphi \sin \beta) = - \frac{1}{r} \frac{\partial A_\varphi}{\partial \beta} - \frac{1}{r} \frac{A_\varphi}{\tan \beta}
\]

The field on the axis is obtained by taking \( \beta \) equal to zero. In this case, \( A_\varphi \) and \( \tan \beta \) vanish simultaneously. Passing to the limit one gets

\[
H_r = - \frac{2}{\varphi} \frac{\partial A_\varphi}{\partial \beta} = \frac{2}{\varphi} \left( \frac{ia}{R} \int_0^{2\pi} \frac{e^{-ikR}}{R} \cos \varphi \, d\varphi \right)
\]

\[
= - \frac{ia}{2\varphi} \int_0^{2\pi} \left( \frac{e^{ikR}}{R} + \frac{ikR}{R^2} \right) e^{-ikR} \cos^2 \varphi \, d\varphi
\]
In unfavorable cases of large \( k^* \) values, the deviation of the dipole formula from the above exact formula for a radius of \( a = 1 \text{ m} \) is less than 10\% for \( r = 3 \text{ m} \) and less than 2\% for \( r = 10 \text{ m} \). It can therefore be neglected.

Eqs. (11), (12), (15) (with \( m = 0, l = 2 \)) lead to the quadrupole term

\[
H_r(x, y) = 6a_0 \left( \frac{3}{2} \cos^2 \varphi - \frac{1}{2} \right) e^{-ik^*r} \left\{ -\frac{k^*}{r^2} + \frac{3ik^*}{r^3} + \frac{3}{r^4} \right\}
\]

The absolute value, considering \( k^* = k_1 - ik_2 \), is

\[
|H_r|^2 = 36a_0^2 \left( \frac{3}{2} \cos^2 \varphi - \frac{1}{2} \right)^2 e^{-2k_2r} \left\{ \frac{k_1^4 + k_2^4 + 2k_1^2k_2^2}{r^4} + \frac{6k_2(k_1^2 + k_2^2)}{r^5} + \frac{3k_1^2 + 14k_2^2}{r^6} + \frac{18k_2}{r^7} + \frac{9}{r^8} \right\}
\]

\[
|H_\phi|^2 = a_0^2 \cdot \frac{9}{4} \sin^2 \varphi \cdot e^{-2k_2r} \left\{ \frac{k_1^6 + 3k_1^4k_2^2 + 3k_1^2k_2^4 + k_2^6}{r^2} + \frac{6k_1k_2 + 12k_1^2k_2^3 + 6k_2^5}{r^3} + \frac{-3k_1^4 + 16k_2^2k_2^4 + 21k_2^4}{r^4} + \frac{72k_1k_2 + 24k_2^3}{r^5} + \frac{72k_2}{r^6} + \frac{-72k_1}{r^7} + \frac{36}{r^8} \right\}
\]

The effect of these terms on the magnitude of the total field \( |\mathbf{H}| \) will be thoroughly investigated in the near future.
§5. The effect of the cavity

This section is devoted to a short examination of the effect of the cavity, in which the magnetic coil is usually placed for measurements in the conducting medium, on the accuracy of measurement. The electrical and magnetic variable fields produced by the magnetic coil in the cavity which is assumed to be spherical with the radius \( r = r_0 \) give rise to displacement and conduction currents in the outer medium according to the conductivity of the latter. These currents induce secondary fields in the cavity and influence the effective dipole moment.

The primary vector potential \( \mathbf{A}_p \) is therefore superimposed by a secondary potential \( \mathbf{A}_s \) which must not have any singularities in the cavity as is required by the physical circumstances.

Therefore, to describe the fields in the cavity, one has to consult the complete solution of the equation \( k^2 \alpha_1 + \Delta \alpha_1 = 0 \).

\[
\mathbf{A}_1 = \text{const.} \frac{x}{2 k r} B_2^1 (k r) + \text{const.} \frac{x}{2 k r} I_{1/2} (k r)
\]

where \( k^* \) is the wave number of the medium in the cavity (\( \infty \text{ vacuum} \)).

The secondary fields are represented by the half-integer Bessel functions which are regular at zero. If the magnetic dipole is aligned in the direction of the z-axis then we have symmetry with regard to the spherical coordinate \( \varphi \). In this case, the two components of \( \mathbf{A}_1 \) which are necessary for a complete description of the fields are, after the sines and cosines have been inserted, as follows:
\[
\alpha_{1r} = \left( A_1 \frac{e^{-ik_{II}r}}{r} + B \frac{\sin k_{II}r}{k_{II}r} \right) \cos \phi,
\]
\[
\alpha_{1\phi} = - \left( A_1 \frac{e^{-ik_{II}r}}{r} + B \frac{\sin k_{II}r}{k_{II}r} \right) \sin \phi.
\]

As before, the vector potential \( \alpha_{1II} \) follows the Hankel function
\[
\alpha_{1II} = C \cdot \frac{e^{-ik_{II}r}}{r} \cos \phi,
\]
\[
\alpha_{1II} = C \cdot \frac{e^{-ik_{II}r}}{r} \sin \phi.
\]

where \( k_{II} \) is the wave number of the conducting medium. The two constants \( B \) and \( C \) are determined by the condition that \( E \) and \( H \) be continuous:
\[
E : \quad \text{curl} \, \alpha_{1II} |_{r=r_0} = \text{curl} \, \alpha_{1II} |_{r=r_0}
\]
\[
H : \quad (r \frac{\partial}{\partial r} + 1) \text{curl} \, \alpha_{1II} |_{r=r_0} = (r \frac{\partial}{\partial r} + 1) \text{curl} \, \alpha_{1II} |_{r=r_0}
\]

The last equation follows from the Maxwell equation
\[
\text{curl} \mathbf{E} = -\mu_0 \omega \mathbf{H}. \quad \text{Substitution leads to}
\]
\[
B = \frac{1}{E} (C(1/r_o + ik_{II}^*)^e^{-ik_{II}r_o} - A_1(1/r_o + ik_I^*)^e^{-ik_{II}r_o})
\]
with \( E = \frac{\sin k_{II}r_0}{k_{II}r_0} - \cos k_{II}r_0 \)

Thus
\[
A_1 e^{-ik_{II}r_o} (k_{II}^2 + 1 - ik_{II}r_o) - 1 - (1 + ik_{II}r_o) \frac{\partial E}{\partial r |_{r=r_0}} =
\]
\[
= C e^{-ik_{II}r_o} (k_{II}^2 + 1 - ik_{II}r_o) - 1 - (1 + ik_{II}r_o) \frac{\partial E}{\partial r |_{r=r_0}}
\]
In the range of frequencies considered ($\nu < 15 \text{ kops}$),

$$k_1^* = \omega \sqrt{\mu_0} \nu < 10^{-4}.$$ Consequently, $k_1^* r_o$ for $r_o < 3 \text{ m}$ is less than $3 \times 10^{-4} < 1$.

For $\frac{E}{\delta r} |_{r=r_o}$, the limit

$$\lim_{r_o \to 0} \frac{E}{\delta r} |_{r=r_o} = -1 + \frac{k_1^* r_o \sin k_1^* r_o / (\sin k_1^* r_o / k_1^* r_o)}{\cos k_1^* r_o}$$

is therefore a good approximation. Thus ($k_1^* < 1$)

$$C = \frac{3}{3 + 3i k_1^* r_o - k_1^* r_o^2} e^{i k_1^* r_o}$$

For $r_o = 3 \text{ meters}$, and for medium conductivities and frequencies, $C$ is by less than 1\% greater than $A$. This means that the virtual increment in antenna current caused by the cavity can be neglected in regard of the formula (8) for a homogeneous conductive medium.

§6. The transformer and other plans for further theoretical work

As the displacement current can be neglected already in the present measurements, the transmitter and receiver aerials can be regarded as an open transformer. This is even more justified at still lower frequencies ($< 3 \text{ kops}$). However, the lack of time made it impossible to perform more exact calculations in this respect and to compare them with the results obtained so far. The calculations made until now were based only on the Hertzian dipole. The electrical dipole has not been considered
at all. The following considerations were decisive:

(a) As was shown in the first final report, a greater emissive power at a given power and VLF-waves can be reached with a magnetic antenna.

(b) The losses in a conducting medium are lower when magnetic fields (instead of electric fields) occur in the \( r \) and \( \theta \) directions.

The following plans are made for further theoretical work:

(1) transformer concept

(2) evaluation of the formulas with \( k_1, k_2 \) (displacement current not neglected)

(3) study of the Ohmian losses as depending on the kind of excitation of electromagnetic fields in a conducting medium (b)

(4) further studies on magnetic antennas (a)

(5) consideration of terms of higher order in the expansion (cf. §8)

(6) problems of wave propagation in inhomogeneous media

(7) surface waves (modes)

(8) continuation of the considerations of the end of §3.
§ 7 Plane Boundary Layer Waves

We study the well known problem of the propagation of plane waves along the interface between two media with different electric properties. We shall take the interface to divide the earth and the air space and place the x-y plane of a Cartesian coordinate system in this interface, the positive z-axis pointing upwards. The waves are considered to propagate along the x-axis. Maxwell's equations read as follows:

\[(60) \quad \nabla \times \mathbf{H} = \varepsilon_0 \frac{\partial \mathbf{E}}{\partial t} + \mathbf{J} \]

\[(61) \quad \nabla \times \mathbf{E} = -\mu_0 \frac{\partial \mathbf{H}}{\partial t} \]

From the foregoing, we assume \(\mathbf{H}\) to have the form

\[(62) \quad \mathbf{H} = \mathbf{H}_y = f(z)e^{j\omega(t - \frac{x}{v})} \]

Substitution in Maxwell's equations leads us to put

\[(63) \quad E_x = g(z)e^{j\omega(t - \frac{x}{v})} \]

\[(63) \quad E_z = h(z)e^{j\omega(t - \frac{x}{v})} \]

Inserting this into Maxwell's equations, we obtain

\[- \frac{dt}{dz} e^{j\omega(t - \frac{x}{v})} = \varepsilon_0 g(z) i\omega + \sigma g(z)e \]

\[- \frac{i\omega}{v} f(z)e^{j\omega(t - \frac{x}{v})} = \varepsilon_0 h(z) i\omega + \sigma h(z)e \]

After cancelling \(e^{j\omega(t - \frac{x}{v})}\), there remains

\[(64) \quad g = \frac{\varepsilon_0 i\omega}{\varepsilon_0 i\omega + \sigma} \]

Using (60, 61), we arrive at an equation containing \( g, f, \) and \( h. \) Substituting (64) and (65) into this equation, we obtain

\[
(66) \quad \left[ (\varepsilon \varepsilon_0 \omega + \sigma) \mu_\mu_0 \omega + \frac{\omega^2}{v^2} \right] f = \frac{d^2 f}{dz^2}
\]

We now make use of the relation

\[
(67) \quad \varepsilon_0 \mu_0 = \frac{1}{c_0^2}
\]

which specifies the velocity of light in empty space.

So we have

\[
(68) \quad \left[ \omega^2 \left( \frac{1}{v^2} - \frac{\varepsilon_0}{c_0^2} \right) + \frac{i\omega\sigma}{\varepsilon_0 c_0^2} \right] f = \frac{d^2 f}{dz^2}
\]

This has the solution

\[
(69) \quad \mathbf{F} = A \mathbf{e}^{+\mathbf{Qz}}
\]

where

\[
(70) \quad \mathbf{Q}^2 = \frac{\omega}{v^2} - \frac{\varepsilon_0}{c_0^2} \omega^2 + \frac{i\omega\sigma}{\varepsilon_0 c_0^2}
\]

This solution holds for both the air and the earth space. We are bound to choose the sign of \( \mathbf{Q} \) in such a manner that the amplitude decreases both with growing \( z \) (air space) and with negative \( z \) (\( z < 1, \) earth space). Hence \( \mathbf{Q} \) will be negative for the air space and positive for the earth space.

We now distinguish between \( \mathbf{Q} \) for the air and the earth space.
by the index \( L \) for the air and the index \( E \) for the earth space, respectively. We shall, however, for the moment ignore the fact that for practical purposes the conductivity of the air is zero. Hence, by a rearrangement of terms, we obtain

\[
\frac{\omega^2}{\epsilon_0} - \frac{\omega^2}{\epsilon_L} = -\frac{\epsilon_L \mu_L}{c_0^2} \omega^2 + \frac{i \omega \mu_L \sigma_L}{\epsilon_0 c_0^2}
\]

\[
\frac{\omega^2}{\epsilon_0} - \frac{\omega^2}{\epsilon_E} = -\frac{\epsilon_E \mu_E}{c_0^2} \omega^2 + \frac{i \omega \mu_E \sigma_E}{\epsilon_0 c_0^2}
\]

\[
\frac{\omega^2}{\epsilon_0} - \frac{\omega^2}{\epsilon_L} = \frac{\epsilon_L \mu_L}{c_0^2} \omega^2 - \frac{i \omega \mu_L \sigma_L}{\epsilon_0 c_0^2}
\]

\[
\frac{\omega^2}{\epsilon_0} - \frac{\omega^2}{\epsilon_E} = \frac{\epsilon_E \mu_E}{c_0^2} \omega^2 - \frac{i \omega \mu_E \sigma_E}{\epsilon_0 c_0^2}
\]

In these two relationships we have made use of the condition that the tangential components of the \( E \)- and \( H \)-vector (with respect to the \( X-Y \) plane) must be continuous on both sides of the interface. As this condition holds independently of time, the phase velocities of both the terrestrial and the air wave must be the same. Hence

\[
y_L = y_E
\]

Likewise, this boundary condition, when applied to the amplitudes, gives for \( z = 0 \)

\[
H_{yL} = H_{yE}
\]

\[
A_L = A_E
\]

The longitudinal component \( E_x \) (with respect to the direction of propagation) is then
Calculating $\frac{dt}{dz}$, we find, considering that the sign of the exponent is positive for the earth space

$$\frac{dt}{dz} = +Q_E \frac{Q_E^2}{\varepsilon_0 \varepsilon_i \omega + \sigma_E}$$

and this for $E_x E$

$$\varepsilon \frac{Q_E^2}{\varepsilon_0 \varepsilon_i \omega + \sigma_E} = \frac{Q_E}{\varepsilon \varepsilon_0 \varepsilon_i \omega + \sigma_E}$$

As for $H$, the boundary condition for the tangential components gives for $z = 0$

$$\frac{Q_L A e}{\varepsilon \varepsilon_0 \varepsilon_i \omega + \sigma_L} = -\frac{Q_E}{\varepsilon \varepsilon_0 \varepsilon_i \omega + \sigma_E}$$

So we obtain

$$Q_E = Q_L \frac{\varepsilon \varepsilon_0 \varepsilon_i \omega + \sigma_E}{\varepsilon \varepsilon_0 \varepsilon_i \omega + \sigma_L}$$

We are now capable of eliminating $Q_L$ and we obtain

$$Q_E = + \sqrt{\frac{b_E - b_L}{q^2 - 1}}$$

The plus sign of the root holds because $Q$ must be positive for $z < 0$. Inserting the formula for $Q_E^2$ we obtain

$$v = + \omega \sqrt{\frac{q^2 - 1}{b_E^2 - b_L}}$$
Now we are in a position to calculate the numerical values of the different constants involved. We use the formulas accounting for the fact that \( \sigma_L = 0 \):

\[
\begin{align*}
\beta_L &= \frac{\varepsilon_L \mu_L}{\varepsilon_0} \omega^2 \\
\beta_E &= \frac{\varepsilon_E \mu_E}{\varepsilon_0} \omega^2 - \frac{\varepsilon_0 \varepsilon E}{\varepsilon_0} \omega^2 \\
\omega^2 &= \left( \frac{\varepsilon_0 \varepsilon E}{\varepsilon_0 \varepsilon E + \sigma E} \right)^2
\end{align*}
\]

We shall use the following numerical values for the parameters:

\[
\begin{align*}
\varepsilon_0 &= 8.86 \cdot 10^{-12} \\
\varepsilon_L &= 1 \\
\varepsilon_E &= 10 \\
\sigma_E &= 5 \cdot 10^{-3}
\end{align*}
\]

and the three angular frequencies

\[
\omega_1 = 2 \pi \cdot 1, \quad \omega_2 = 2 \pi \cdot 10^4, \quad \omega_3 = 2 \pi \cdot 10^6
\]

corresponding to 1, 10, and 100 kc. We shall calculate every parameter for the three frequencies, using one column for each value:

<table>
<thead>
<tr>
<th>( \omega_1 )</th>
<th>( \omega_2 )</th>
<th>( \omega_3 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \beta_L )</td>
<td>( \beta_E )</td>
<td>( \beta_E )</td>
</tr>
<tr>
<td>( \omega^2 )</td>
<td>( \omega^2 )</td>
<td>( \omega^2 )</td>
</tr>
</tbody>
</table>

In calculating the root for \( \omega \) we are forced to neglect the second term under the root sign, because it is smaller by ten orders of magnitude compared to the first one. Hence it is far below the accuracy of a slide rule. Moreover, considering the representation of complex numbers in the complex plane,
it is at once evident that the complex numbers in question deviate from the real axis so little that for practical purposes they can be regarded as real numbers. We must not forget, however, that this approximation is valid only if it is not to be expected that in further mathematical operations the imaginary part will be multiplied by a factor which is large enough to restore approximate equality between the two parts of a complex number. Hence we were not allowed to apply this reasoning to the earlier steps of our development.

Accordingly, we shall calculate \( v \) from the approximative formula

\[
v = \omega \left( A + iB \right), \quad B \neq 0
\]

we obtained

\[
\begin{array}{ccc}
\omega_1 & \omega_2 & \omega_3 \\
2.99 \cdot 10^8 & 2.99 \cdot 10^8 & 2.99 \cdot 10^8 \\
\end{array}
\]

This result, e.g. that the phase velocity within the accuracy of slide rule computations, is equal for all three frequencies, and moreover equal to the velocity of light in empty space, permits to simplify the formula for \( q_E \).

We obtain

\[
q_E(\omega_1) = 4.45 \cdot 10^{-3} + i 4.44 \cdot 10^{-3}
\]
\[
q_E(\omega_2) = 1.4 \cdot 10^{-2} + i 1.405 \cdot 10^{-2}
\]
\[
q_E(\omega_3) = 4.45 \cdot 10^{-2} + i 4.45 \cdot 10^{-2}
\]

From these values of \( q_E \) we take only the real part which represents the exponent of the amplitude damping term, and
calculate the depth of penetration, e.g. the distance through which the original amplitude drops to \(1/e\). For this it is required that the exponent in the expression

\[ A = A_0 e^{+qz}; \quad z < 0 \]

is equal to unity, hence

\[ qz = 1 \]
\[ z = \frac{1}{q} \]

So we obtain the penetration depth of boundary layer waves

\[ Z(\omega_1) = 218 \text{ m} \quad \text{for} \quad \omega_1 = 2\pi \cdot 10^3, \quad E_\theta = 10, \quad a_\theta = 5 \cdot 10^{-3} \]
\[ Z(\omega_2) = 71.5 \text{ m} \quad \text{for} \quad \omega_2 = 2\pi \cdot 10^4 \]
\[ Z(\omega_3) = 22.6 \text{ m} \quad \text{for} \quad \omega_3 = 2\pi \cdot 10^5 \]

This calculation was made only to check our ideas and experimental results. We know very well that considerable work has been done in the US concerning the propagation of such waves along a curved interface. We will attach this problem in the next future. Furthermore the penetration of vertically incising plane waves will be considered.
§ 8. Comparison between experiment and theory

Before comparing the measured results with our calculations we shall calculate the wavelength. Neglecting the displacement current we have according to (42)

\[ k_J = \frac{2\pi}{\lambda} = \sqrt{\frac{\mu_0 \omega \sigma}{2}}. \]

Therefrom with \( \nu = 3 \) kcps we get

(76)

\[ \lambda = 8180 \text{ m} \]

in rock, whereas the wavelength in vacuo is 100,000 m.

All the measurements were made at distances of less than 1500 m because more powerful transmitter was not yet available. Thus, the measurements were made in the near field \((r < \lambda)\).

Let \( r \) be given, \( \delta \) and \( \zeta \) be known. If the field strength is measured then from Figs. 11 - 16 one can read that conductivity which had to be substituted into the theoretical formulas to yield a correct description of the measured values.

when this conductivity approximately agrees with the measured one, we can assume that our theory describes the experiments correctly. We shall now determine the effect of the frequency and of the distance on the accuracy of the measurement of conductivity. From the expansion of the radical and of the exponential function for small values of \( \omega, \sigma, \) and \( r \) in Eq. (50)

\[ f(r, \sigma) = \frac{1}{r^3} \left( 1 + r \sqrt{\frac{\omega \mu_0 \sigma}{2}} - \ldots \right) \left( 1 - r \sqrt{\frac{\omega \mu_0 \sigma}{2}} + \ldots \right) \]

one can see the opposed variations of radical and exponential.
f(r,σ) is therefore practically independent of σ at short distances and low frequencies (horizontal course of the curves in Fig. 8). As conductivity is dependent on frequency which usually is predetermined by the aim of the measurement, we can choose freely only the quantity r. The following minimum distances should be observed for a sufficiently accurate measurement:

For \( \omega \mu_0 \sigma > 2.5 \cdot 10^{-4} \) \( r > 500 \text{ m} \)
\( \omega \mu_0 \sigma > 8 \cdot 10^{-5} \) \( r > 800 \text{ m} \)
\( \omega \mu_0 \sigma > 8 \cdot 10^{-6} \) \( r > 1200 \text{ m} \)
\( \omega \mu_0 \sigma > 2.5 \cdot 10^{-7} \) \( r > 3000 \text{ m} \)

If the measuring frequency for instance is 3 kc/s, measurements in the region of conductivities around \( 10^{-3} \) are sensible only from about 800 m on. Greater distances must be chosen for lower conductivities.

The practical measuring arrangement consists of a magnetic coil and an a.c. power supply on the transmitter side, and a magnetometer whose sensitivity has to meet high requirements because of the rapid decrease of the field strength at longer distances. The magnetic field probe (a highly inductive coil on high-permeability ferrite cores) is connected to an amplifier which transforms the weak signals to a value convenient for reading. In contrast to the usual measuring and amplifying arrangements, the sensitivity of the magnetometer is determined not by the natural noise of the probe or of the amplifier but by the atmospherics which come from discharges in the air, thunderstorms, and similar static processes and which produce
considerably strong magnetic fields in the VLF range (Ref. 2). However, they have a broad frequency spectrum so that their effect can be reduced by selective amplifiers. The sensitivity is therefore determined by the selectivity of the amplifier whose 40-db band width should not be above 100 cps.

Until now, the measurements have been made with a 30-cps band width amplifier on a frequency of 3 kcps in the area of the mines at Schwaz, St. Gertraudi, and Lafatsch. The results are as follows:

Measurement 20-11-62, Schwaz (details, e.g. \( \psi \) in the experimental part) (\( \varsigma \) presumably 12.5). The voltage \( U \) measured was represented as \( U = B \cos \psi \), according to (32), and B was calculated.

\[
\begin{align*}
\text{r} & = 580 \text{ m} & \varsigma & = 0^\circ & B & = 16.9 \pm 1.5 \text{ [mv]} \\
\text{r} & = 760 \text{ m} & \varsigma & = 0^\circ & B & = 12.3 \pm 1.7 \text{ [mv]} \\
\text{r} & = 870 \text{ m} & \varsigma & = 8^\circ & B & = 12.3 \pm 3.7 \text{ [mv]} \\
\text{r} & = 1040 \text{ m} & \varsigma & = 10^\circ & B & = 6 \pm 4 \text{ [mv]}
\end{align*}
\]

Measurements 27-11-62, St. Gertraudi

\[
\begin{array}{ccc}
\text{r [m]} & \varsigma [^\circ] & B \text{ [mv]} \\
110 & 30 & 42.64 \pm 0.40 \\
150 & 18 & 17.88 \pm 0.80 \\
200 & 11 & 8.28 \pm 0.30 \\
240 & 7.5 & 4.93 \pm 0.70 \\
290 & 5.5 & 2.83 \pm 0.70 \\
340 & 4 & 1.66 \pm 0.20 \\
390 & 3 & 1.33 \pm 0.70 \\
440 & 2 & 0.679 \pm 0.14 \\
490 & 1 & 0.611 \pm 0.05 \\
540 & 0.5 & 0.564 \pm 0.09 \\
590 & 0 & 0.395 \pm 0.03 \\
\end{array}
\]

(corresponds to \( |H| = 79.6 \cdot 10^{-6} \) or \( |B| = 100 \cdot 10^{-12} \text{ [Wb m}^{-2}] \))
A second measurement at St. Gertraudi (transmitting antenna turned through 45°) gave

<table>
<thead>
<tr>
<th>r [m]</th>
<th>8 [°]</th>
<th>B [mv]</th>
</tr>
</thead>
<tbody>
<tr>
<td>640</td>
<td>-0.5</td>
<td>0.307 ± 0.02</td>
</tr>
<tr>
<td>690</td>
<td>-0.5</td>
<td>0.2503 ± 0.02</td>
</tr>
<tr>
<td>710</td>
<td>-0.5</td>
<td>0.2148 ± 0.01</td>
</tr>
<tr>
<td>820</td>
<td>-0.5</td>
<td>0.1306 ± 0.01</td>
</tr>
</tbody>
</table>

Both series of measurements are plotted in Fig. 19. Let us first consider the Schwaz measurements. First, the mean value of B was determined from the measured voltage U, according to (32).

For $\theta = 0°$ where $E_0 = 0$, using (32), i.e. $B = A(\omega) \cdot |H|$, we obtain according to (52) (50) (46)

\[ B = A(2m f(\theta, \alpha)) = C \cdot f(\theta, \alpha) \]

f can be taken from Fig. 7a (calculation see later)

580 m $\theta = 0°$ B = 16.9 f = $2 \cdot 10^{-9}$ for $c = 5 \cdot 10^{-5}$, thus $C_1 = 8.45 \cdot 10^9$

f = $6 \cdot 10^{-9}$ for $c = 10^{-5}$, thus $C_1 = 2.83 \cdot 10^9$

760 m $\theta = 0°$ B = 12.3 f = $6 \cdot 10^{-10}$ for $c = 5 \cdot 10^{-5}$, thus $C_2 = 2.05 \cdot 10^{10}$

f = $3 \cdot 10^{-9}$ for $c = 10^{-5}$, thus $C_2 = 4.10 \cdot 10^9$

For $c = 5 \cdot 10^{-5}$ the error in C is $C_1 - C_2 = -12 \cdot 10^9$ and
for $\sigma = 10^{-5}$ the error in $C$ is $C_1 - C_2 = -1.3 \cdot 10^9$

This first rough estimate shows that $\sigma$ is of the order of $10^{-5}$. But for such conductivities at 3 kops distances of at least 3 km are required.

To perform reliable measurements of the conductivity and to be able to verify the theoretical opinions about the propagation of VLF waves, a more powerful transmitter on a lower frequency is necessary.

A similar picture is put forward by the measurements at St. Gertraudi.

<table>
<thead>
<tr>
<th>$B$</th>
<th>$f(r,\alpha)$ for $\sigma=5 \cdot 10^{-5}$</th>
<th>relevant $C$</th>
<th>$f(r,\alpha)$ for $\sigma=10^{-5}$</th>
<th>from Fig. 7a</th>
<th>from Fig. 7a</th>
</tr>
</thead>
<tbody>
<tr>
<td>490 m</td>
<td>0.611</td>
<td>$4 \cdot 10^{-9}$</td>
<td>$0.153 \cdot 10^9$</td>
<td>8 $\cdot 10^{-9}$</td>
<td></td>
</tr>
<tr>
<td>590 m</td>
<td>0.395</td>
<td>$2 \cdot 10^{-9}$</td>
<td>$0.197 \cdot 10^9$</td>
<td>6 $\cdot 10^{-9}$</td>
<td></td>
</tr>
<tr>
<td>690 m</td>
<td>0.250</td>
<td>$9 \cdot 10^{-10}$</td>
<td>$0.250 \cdot 10^9$</td>
<td>$4 \cdot 10^{-9}$</td>
<td></td>
</tr>
<tr>
<td>820 m</td>
<td>0.131</td>
<td>$3 \cdot 10^{-10}$</td>
<td>$0.435 \cdot 10^9$</td>
<td>$2 \cdot 10^{-9}$</td>
<td></td>
</tr>
</tbody>
</table>

$\Delta C = 0.282 \cdot 10^9$  
$\Delta C = 0.0109 \cdot 10^9$

As $C$ increases with the distance at $\sigma = 5 \cdot 10^{-5}$, the value $5 \cdot 10^{-5}$ is obviously too great. At $\sigma = 10^{-5}$, $C$ first decreases, and then increases somewhat. But this increase might be due to inaccurate reading. This behavior of $C$ leads to the conclusion that $5 \cdot 10^{-5} > \sigma > 10^{-5}$ in the Schwaz measurements.

A more systematic investigation of the results of the measurements gave the same picture. We define

$$C(r,\alpha) = \frac{B(r,\theta)}{h(r,\theta,\alpha)}$$
$B(r, \theta)$ is the quantity

\begin{equation}
B = \frac{U(r, \theta, \psi)}{\cos \psi}
\end{equation}

calculated from Eq. (32) and from the measured $U(r, \theta, \psi)$.

$\bar{C}(\alpha)$ is the average over the $C(r, \alpha)$ with $\alpha$ fixed.

**Measurement Schwaz** (we have $1 \omega = 2.32 \cdot 10^{-12}$ [Weber $m^{-2}$], cf. experimental part)

<table>
<thead>
<tr>
<th>$r$ [m]</th>
<th>$B$ [mV] $B$ [Weber $m^{-2}] \cdot 10^{12}$</th>
<th>$h$ according to (52) $C(r, \alpha)$ $\bar{C} h$ [Weber $m^{-2}] \cdot 10^{12}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>580</td>
<td>85 $0.2$</td>
<td>$1.024 \cdot 10^{-8}$ $83.0 \cdot 10^{8}$ $0.1464$</td>
</tr>
<tr>
<td>760</td>
<td>36 $0.083$</td>
<td>$4.776 \cdot 10^{-9}$ $75.4 \cdot 10^{8}$ $0.0684$</td>
</tr>
<tr>
<td>870</td>
<td>16 $0.035$</td>
<td>$3.01377 \cdot 10^{-9}$ $53.1 \cdot 10^{8}$ $0.0430$</td>
</tr>
<tr>
<td>1040</td>
<td>6 $0.014$</td>
<td>$1.7477 \cdot 10^{-9}$ $34.35 \cdot 10^{8}$ $0.0250$</td>
</tr>
</tbody>
</table>

Mean value $\bar{C}(\alpha) = 61.67 \cdot 10^8$, deviation $C_{max} - C_{min} = 48 \cdot 10^8$.

The calculations performed with $\alpha = 0.0169$ ($\sigma = 10^{-6}$) showed, as was expected, that $\bar{C}$ was quite insensitive. It is therefore not possible to draw an unambiguous conclusion about $\omega \sigma = \alpha$.

According to Fig. 18 it can be assumed that the conductivity $\sigma = 10^{-6}$ is too small. The values of $\bar{C}(\alpha)h(r, \alpha)$ [Weber $m^{-2}$] are plotted in Fig. 18 together with the results for $B$ [Weber $m^{-2}$] for $\alpha = 0.0189$ ($\sigma = 10^{-6} \Omega^{-1} m^{-1}$). The quadrupole terms are being studied in detail.

**Measurement St. Gertraudi**

<table>
<thead>
<tr>
<th>$r$ [m]</th>
<th>$B$ [V] $B$ [Weber $m^{-2}] \cdot 10^{12}$</th>
<th>$h$ according to (52) $C(r, \alpha)$ $\bar{C} h$ [Weber $m^{-2}] \cdot 10^{12}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>110</td>
<td>$42.64 \pm 0.40$ $98.9$ $1.355 \cdot 10^{-6}$ $3.14 \cdot 10^7$ $115$</td>
<td></td>
</tr>
<tr>
<td>150</td>
<td>$17.88 \pm 0.80$ $41.5$ $5.71 \cdot 10^{-7}$ $3.13 \cdot 10^7$ $48.25$</td>
<td></td>
</tr>
<tr>
<td>Temperature (°C)</td>
<td>C (a) (±Δa)</td>
<td>C (b) (±Δb)</td>
</tr>
<tr>
<td>-----------------</td>
<td>-------------</td>
<td>-------------</td>
</tr>
<tr>
<td>200</td>
<td>8.28 ± 0.30</td>
<td>19.2</td>
</tr>
<tr>
<td>240</td>
<td>4.93 ± 0.70</td>
<td>11.44</td>
</tr>
<tr>
<td>290</td>
<td>2.83 ± 0.70</td>
<td>6.57</td>
</tr>
<tr>
<td>340</td>
<td>1.66 ± 0.20</td>
<td>3.85</td>
</tr>
<tr>
<td>390</td>
<td>1.33 ± 0.70</td>
<td>3.09</td>
</tr>
<tr>
<td>440</td>
<td>0.679 ± 0.14</td>
<td>1.574</td>
</tr>
<tr>
<td>490</td>
<td>0.611 ± 0.05</td>
<td>1.416</td>
</tr>
<tr>
<td>540</td>
<td>0.564 ± 0.09</td>
<td>1.307</td>
</tr>
<tr>
<td>590</td>
<td>0.395 ± 0.03</td>
<td>0.916</td>
</tr>
<tr>
<td>640</td>
<td>0.307 ± 0.02</td>
<td>0.711</td>
</tr>
<tr>
<td>690</td>
<td>0.250 ± 0.02</td>
<td>0.581</td>
</tr>
<tr>
<td>710</td>
<td>0.214 ± 0.01</td>
<td>0.496</td>
</tr>
<tr>
<td>820</td>
<td>0.130 ± 0.01</td>
<td>0.306</td>
</tr>
</tbody>
</table>

Mean value $\bar{C}(a) = 3.65·10^7$. Deviation $C_{\text{max}} - C_{\text{min}} = 1.56·10^7$

The calculations made with $a = 0.0942$ ($c = 5·10^{-6}$) gave the above table. The deviation was greater for other $a$:

<table>
<thead>
<tr>
<th>$a$</th>
<th>$\bar{C}(a)$</th>
<th>$C_{\text{max}} - C_{\text{min}}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.89</td>
<td>3.93·10⁷</td>
<td>1.71·10⁷</td>
</tr>
<tr>
<td>0.942</td>
<td>3.74·10⁷</td>
<td>1.63·10⁷</td>
</tr>
<tr>
<td>0.189</td>
<td>3.66·10⁷</td>
<td>1.57·10⁷</td>
</tr>
<tr>
<td>0.0189</td>
<td>3.61·10⁷</td>
<td>1.56·10⁷</td>
</tr>
</tbody>
</table>

Agreement of experiment and theory for $c < 5·10^{-6}$ is quite good as shows Fig. 19.
Fig. 19
$\theta = 27.5000 \, \text{s}^{-1}$
Measurement St. Gertraudi (antenna turned)

<table>
<thead>
<tr>
<th>r [m]</th>
<th>B [μT]</th>
<th>h according to (52) for $\sigma = 10^{-5}$</th>
<th>C(r, α)</th>
</tr>
</thead>
<tbody>
<tr>
<td>70</td>
<td>95</td>
<td>$5.885 \cdot 10^{-6}$</td>
<td>$1.615 \cdot 10^{7}$</td>
</tr>
<tr>
<td>150</td>
<td>32.65</td>
<td>$5.443 \cdot 10^{-7}$</td>
<td>$5.999 \cdot 10^{7}$</td>
</tr>
<tr>
<td>240</td>
<td>15.2</td>
<td>$1.233 \cdot 10^{-7}$</td>
<td>$12.320 \cdot 10^{7}$</td>
</tr>
<tr>
<td>340</td>
<td>11.87</td>
<td>$4.290 \cdot 10^{-8}$</td>
<td>$2.699 \cdot 10^{8}$</td>
</tr>
<tr>
<td>490</td>
<td>?</td>
<td>$1.404 \cdot 10^{-8}$</td>
<td>-</td>
</tr>
<tr>
<td>640</td>
<td>1.785</td>
<td>$6.022 \cdot 10^{-9}$</td>
<td>$2.965 \cdot 10^{8}$</td>
</tr>
<tr>
<td>820</td>
<td>0.745</td>
<td>$2.859 \cdot 10^{-9}$</td>
<td>$2.625 \cdot 10^{8}$</td>
</tr>
</tbody>
</table>

The calculations performed with $\sigma = 10^{-5}$ yielded $\overline{C}(\sigma = 10^{-5}) = 7.77 \cdot 10^{7}$. The $\overline{C}$ values obtained with the turned antenna are about twice as large as those obtained with the antenna not turned. This and the wide deviations of the $C(r, \alpha)$ in the case of the turned antenna are indicative of a systematic error or of considerable inhomogeneities of the conductivity. For this reason these measurements were not further evaluated.

Measurement Lafatsch

According to the geological conditions (ore layer) a higher conductivity should occur. The measurements at $\psi = 0^\circ$, $\varphi = 0^\circ$ gave

<table>
<thead>
<tr>
<th>series I</th>
<th>r [m]</th>
<th>B [wb m$^{-2}$]$^{10^{12}}$</th>
<th>B [Weber m$^{-2}$] calculated</th>
</tr>
</thead>
<tbody>
<tr>
<td>82</td>
<td>77</td>
<td>83.3</td>
<td></td>
</tr>
<tr>
<td>116</td>
<td>28</td>
<td>29.3</td>
<td></td>
</tr>
<tr>
<td>125</td>
<td>20</td>
<td>24.0</td>
<td></td>
</tr>
<tr>
<td>170</td>
<td>7.7</td>
<td>9.28</td>
<td></td>
</tr>
<tr>
<td>186</td>
<td>7</td>
<td>7.45</td>
<td></td>
</tr>
<tr>
<td>210</td>
<td>4.6</td>
<td>4.90</td>
<td></td>
</tr>
<tr>
<td>230</td>
<td>4.1</td>
<td>3.82</td>
<td></td>
</tr>
<tr>
<td>304</td>
<td>1.9</td>
<td>1.64</td>
<td></td>
</tr>
<tr>
<td>332</td>
<td>1.4</td>
<td>1.25</td>
<td></td>
</tr>
<tr>
<td>374</td>
<td>1.0</td>
<td>0.895</td>
<td></td>
</tr>
<tr>
<td>410</td>
<td>0.7</td>
<td>0.67</td>
<td></td>
</tr>
<tr>
<td>445</td>
<td>0.55</td>
<td>0.53</td>
<td></td>
</tr>
</tbody>
</table>
The results are compiled in Fig. 20 (\( C = 4.63 \times 10^7, \alpha = 0.0942,\) \( \sigma = 5 \times 10^{-6} \) in series I and \( C = 4.577 \times 10^7, \alpha = 0.189, \sigma = 10^{-5} \) in series II). On the whole they show a good agreement between theory and experiment. In the future it will be studied if the present deviations go back to the neglection of the displacement current, to an improper choice of \( \sigma \), to the neglection of the quadrupole terms, or to other causes.
III. Experimental part

§ 1. Summary

The measurements on the propagation of low-frequency electromagnetic waves through rock were continued on a larger scale in 1962. On the basis of the results given in the 1961 annual report an attempt was made to improve these results by improving the measuring equipment. The experiments were made in the following mines: Schwaz tetrahedrite mine, St. Gertraudi baryta mining, Lafatsch lead and zinc mining (all in the Tyrol). The measurements in the Hall salt mine are still incomplete at present. New conditions arise in this area as compared to the others since the conductivity of the salt-bearing bed is very high. The content in water is some 4%. The large inhomogeneities observed have not yet been studied theoretically. Besides measurements with the test transmitter, the signals from known long-wave transmitters were recorded underground. In particular the transmitters NAA and GBR were observed and measured over a longer period. The results of the first probing work in this area brought a special working team into operation which is to register the field strength above and under the surface, the signal-to-noise ratio, rapid and slow seasonal fluctuations, etc. Particularly suitable measuring locations with a mountain cover of some 1000 m were found in the Schwaz mining range.
§ 2. Design and construction of the transmitter station

For the measurements of underground propagation, a portable all-transistor transmitter was designed which in spite of its light weight and small volume has a power output of about 50 watts. Larger accumulators of 66 Ah guarantee a 10-hrs operation at full power. The transmitter itself consists of a stabilized RC generator which produces the required frequency, the electronic code automatic switch (Fig. 23), and the power amplifier (circuit diagram see Fig. 22). The power stage is in essential a strong low-frequency amplifier. The antenna matching is different from the usual LF wiring. The best matching of antenna and amplifier in each individual case can be adjusted with the aid of several tappings at the secondary winding of the output transformer. Each transmitting antenna is tuned to series resonance by means of mica switch capacitors. In this case only their ohmic resistance appears which usually can be kept low. To determine the power output the antenna current for a known impedance of the aerial is measured by means of a current transformer. As is clear from the theoretical formulas for the field strength of a magnetic dipole, the value of this current alone is enough for the exact calculation. In the case of resonance a voltage boost of up to 800 volts may occur although the impedance of the transmitter aerial is of the order of 10 ohms. On the one hand this furnishes a good insulation of the antenna and on
the other very powerful capacitor decades. The cooling plates necessary for the thermal stabilization of the output stage transistors were reduced to a minimum to provide small geometrical dimensions. The required cooling was performed by a controllable blower. Fig. I shows the complete transmitter station.

As for the transmitter antennas, the way taken last year is being continued. The aerials are all large air-core coils. For the purpose of installing the transmitter station at the different places of the mine, aerials of small dimensions and light weight were designed, as e.g. SA IV, SA V, SA VI. For the long-distance measurements, however, the frame dimensions were larger so that their easy portability had to be abandoned. Such aerials were mounted in exhausted mines or in suited galleries. In the Schwaz mine, for instance, a rotary frame of 17 m² was installed for long-term measurements. Technical data of the transmitter aerials:

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>SA IV</td>
<td>100 turns Cu 1 mm</td>
<td>R = 1 ohm, L = 23 mH</td>
<td>rigid frame, diameter 1 m</td>
</tr>
<tr>
<td>SA V</td>
<td>60 turns Cu 1 mm</td>
<td>R = 5 ohms, L = 11 mH</td>
<td>rigid frame, diameter 1.5 m</td>
</tr>
<tr>
<td>SA VI</td>
<td>60 turns of stranded wire = 2.5 mm²</td>
<td>R = 2.1 ohms, L = 15 mH</td>
<td>area 1.4 m², diameter about 1.5 m</td>
</tr>
</tbody>
</table>

To be able to forward these aerials with their relatively large diameters also through narrow tunnels, the wire turns
were fused into flexible plastic tube which is set up on a special frame only at the required place. This is shown in Fig. II.

SA VII 36 turns of stranded wire 0.75 mm², area of aerial 17 m²,
\[ R = 13.5 \text{ ohms}, \quad L = 12 \text{ mH}. \]
Rectangular shape.

The field produced by this antenna is sufficient to make measurements at distances of up to 1.2 km possible. A detection at even longer distances is also possible. Fig. IV shows the aerial SA VII as installed in the Schwaz mine.

§ 3. The receiver station

The portable all-transistor receiver (Fig. III) consists of four units:
removable receiving aerial
selective receiver
millivoltmeter
audio amplifier.

Also the receiving aerials are built as magnetic antennas only. Three different designs were employed.

The receiving aerial IV consists of five ferrite rods, 20 mm in diameter and 65 cm long, which are arranged along the edges of a prism with a regular pentagon as the base plane. An approximately 15 cm long cross-coil winding of 1600 turns is in the middle of each rod. The optimum edge length of the pentagon was calculated to be 15 cm. It depends on the
material and on the geometrical dimensions of the ferrite rods. Five windings can interchangeably be connected in parallel or in series. Fig. 24 shows the connection employed.

Similarly to the transmitter antenna circuit, also the receiving antenna is adjusted to resonance by series connection with switch capacitors. This type has an advantage over parallel circuits since the entire input circuit of the amplifier can be kept low-resistance. The sensitivity to atmospherics and noise can be reduced in this way. The receiving aerial V is simpler. It consists of only one 65 cm long ferrite rod. The cross-coil winding of 3000 turns is also placed in the middle of the rod. The antenna is tuned as described above, owing to its small size, the aerial can be shielded electrostatically and can therefore be calibrated with particular accuracy.

Receiving aerial VI: The low-permeability ferrite core is replaced by a high-permeability iron core with $\mu_{\text{tor}} = 80,000$. The laminated core is 100 cm long. At the measuring frequencies used so far (10 and 3 kcps) this design is not superior to the types IV and V. At low frequencies, however, it is supposed to be paramount.

Technical data:

EA IV  
maximum inductance = 8 H, $R = 5$ ohms  
number of turns $5 \times 1600$ (Fig. III)

EA V  
inductance = 2 H, 3000 turns, $R = 135$ ohms (Fig. V)
EA VI  inductance L = 2.2 H, 2 x 1000 turns, R = 56 ohms
μ, = 80,000, length = 100 cm, cross section = 8 cm²

Besides these types, also large stationary aerials of various designs were installed. They shall be discussed elsewhere.

The selective amplifier (circuit diagram Fig. 24):
The signal voltage supplied by the aerial rods at long-distance measurements is of the order of μV and even less. To be able to measure precisely these low voltages a special input amplifier with a signal-to-noise ratio as high as possible had to be designed. After thorough investigations into low-background transistor amplifiers a specially chosen transistor of the type BCY 20 supplied by the Siemens company was employed in emitter connection in the input stage. The signal is then amplified again by another low-background input stage transistor AC 107. The input signal can be weakened in steps of 10 db each by means of a calibrated divider. It is then fed into a multistage selective amplifier. The individual stages were d.c.-coupled to avoid undesired phase shifts. The temperature dependence is low as silicon transistors have been used. The temperature of the place of measurement and its environment is constant. The selective network which is a further development of the shunted T member was designed in our laboratory and has proved useful so far. The selective stage is followed by a buffer stage to eliminate feedback. A low-resistance output is reached by a transistor operated in collector connection. From here the signal comes
into the transistor voltmeter for measuring problems on the one hand, and on the other for audio tests into a mixer stage which adds a multivibrator signal. The resultant beat frequency can be led into an amplifier for a loudspeaker. This arrangement is to make audible those signals of known very-long-wave transmitters as GBR and NAA that are above the threshold of audibility. Because of the high requirements concerning constant amplification it was necessary to stabilize the operating voltage, which was supplied by two 9-v batteries, by means of Zener diodes. In this way amplification is independent of the decrease in battery voltage (18 - 15 v). The instrument which is built into the apparatus serves to control the battery but can also be used to indicate the measuring signal.

Technical data of the receiver:

- amplification 80,000 ± 3 db at 15°C
- background voltage at the input 0.1 µv
- band width about 5%
- frequency range 20 cps to 20 kcps
- frequency variation 1 : 2
- input resistance 5000 ohms
- output resistance (measuring output) 1000 ohms
- dimensions 15 by 11 by 27 cm.
Specification for receiver (Fig. 24)

<table>
<thead>
<tr>
<th>no.</th>
<th>R</th>
<th>C</th>
<th>transistors</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>680 kΩ</td>
<td>3 x 500 pF</td>
<td>Tr 1. BCY20</td>
</tr>
<tr>
<td>2</td>
<td>10 &quot;</td>
<td>400 pF</td>
<td>Tr 2. AC107</td>
</tr>
<tr>
<td>3</td>
<td>1.2 &quot;</td>
<td>1 nF</td>
<td>Tr 3. BCY20</td>
</tr>
<tr>
<td>4</td>
<td>5.6 &quot;</td>
<td>10 µF</td>
<td>Tr 4. &quot;</td>
</tr>
<tr>
<td>5</td>
<td>68 &quot;</td>
<td>100 &quot;</td>
<td>Tr 5. &quot;</td>
</tr>
<tr>
<td>6</td>
<td>47 &quot;</td>
<td>5 &quot;</td>
<td>Tr 6. OC71</td>
</tr>
<tr>
<td>7</td>
<td>470 &quot;</td>
<td>10 &quot;</td>
<td>Tr 7. &quot;</td>
</tr>
<tr>
<td>8</td>
<td>33 &quot;</td>
<td>10 &quot;</td>
<td>Tr 8. AC107</td>
</tr>
<tr>
<td>9</td>
<td>5.6 &quot;</td>
<td>100 &quot;</td>
<td>Tr 9. &quot;</td>
</tr>
<tr>
<td>10</td>
<td>15 &quot;</td>
<td>100 &quot;</td>
<td>Tr 10. OC71</td>
</tr>
<tr>
<td>11</td>
<td>1.5 &quot;</td>
<td>variable</td>
<td>Tr 11. &quot;</td>
</tr>
<tr>
<td>12</td>
<td>8.2 &quot;</td>
<td>GL 1. BA102</td>
<td>GL 2. OA70</td>
</tr>
<tr>
<td>13</td>
<td>15 &quot;</td>
<td>variable</td>
<td>SZ 1. OA203</td>
</tr>
<tr>
<td>14</td>
<td>10 &quot;</td>
<td>GL 2. BA102</td>
<td>SZ 2. OA202</td>
</tr>
<tr>
<td>15</td>
<td>680 &quot;</td>
<td>100 µF</td>
<td>potentiometers</td>
</tr>
<tr>
<td>16</td>
<td>15 &quot;</td>
<td>100 &quot;</td>
<td>P 1. 1 MΩ</td>
</tr>
<tr>
<td>17</td>
<td>220 Ω</td>
<td>25 &quot;</td>
<td>P 2. 10 kΩ</td>
</tr>
<tr>
<td>18</td>
<td>1.2 kΩ</td>
<td>20 nF</td>
<td>P 3. 100 kΩ</td>
</tr>
<tr>
<td>19</td>
<td>4.7 &quot;</td>
<td>100 µF</td>
<td>P 4. 250 Ω</td>
</tr>
<tr>
<td>20</td>
<td>22 &quot;</td>
<td>25 &quot;</td>
<td>P 5. 5 kΩ</td>
</tr>
<tr>
<td>21</td>
<td>3.3 &quot;</td>
<td>2 nF</td>
<td>P 6. 10 kΩ</td>
</tr>
<tr>
<td>22</td>
<td>47 &quot;</td>
<td>2 &quot;</td>
<td>P 7. 25 kΩ</td>
</tr>
<tr>
<td>23</td>
<td>2.7 &quot;</td>
<td>5 µF</td>
<td></td>
</tr>
<tr>
<td>24</td>
<td>680 Ω</td>
<td>0.47 &quot;</td>
<td></td>
</tr>
<tr>
<td>25</td>
<td>6.8 kΩ</td>
<td>40 nF</td>
<td></td>
</tr>
<tr>
<td>26</td>
<td>47 &quot;</td>
<td>20 &quot;</td>
<td></td>
</tr>
<tr>
<td>27</td>
<td>22 &quot;</td>
<td>40 &quot;</td>
<td></td>
</tr>
<tr>
<td>28</td>
<td>470 &quot;</td>
<td>20 &quot;</td>
<td></td>
</tr>
<tr>
<td>29</td>
<td>12 &quot;</td>
<td>10 µF</td>
<td></td>
</tr>
<tr>
<td>30</td>
<td>10 &quot;</td>
<td>5 &quot;</td>
<td></td>
</tr>
<tr>
<td>31</td>
<td>680 Ω</td>
<td>100 &quot;</td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>500 &quot;</td>
<td>100 &quot;</td>
<td></td>
</tr>
<tr>
<td>33</td>
<td>15 kΩ</td>
<td>100 &quot;</td>
<td></td>
</tr>
<tr>
<td>34</td>
<td>6.8 &quot;</td>
<td>1 &quot;</td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>150 Ω</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
The antenna EA IV, the selective amplifier, the transistor millivoltmeter, and the audio amplifier were arranged into one common transport casing for the measurements in the mines. This complete receiving station which in a mine can easily be handled by two persons is shown in Fig. III. For measurements on difficult terrain, very narrow tunnels or shafts the receiver unit was decomposed into two easily portable units. Fig. V shows this measuring arrangement: Antenna EA V, selective receiver, and millivoltmeter.

Calibration of the receiving antenna:

The antenna was calibrated in the same way as described in the last year's annual report. The aerial was placed into a uniform field of known intensity. The voltage induced was measured, i.e., the voltage measured at the output of the selective amplifier was extrapolated to the input. In this way one obtains the relationship between measured voltage and magnetic field strength in $\text{Wb/m}^2$. This determination must be repeated for all the frequencies in question because several parameters vary with frequency in a way very difficult to determine.

When approaching the problem mathematically we find the following:

The voltage induced in a coil is

$$U_{\text{ind}} = -L \frac{d\Phi}{dt} \quad (1)$$

Applying this equation to the antennas used by us we have
(2) \[ U_{\text{ind}} = -L \cdot i \omega \cdot F \cdot B \cdot e^{i \omega t} \]

and the required amount is

(3) \[ |U_{\text{ind}}| = L \cdot \omega F \cdot |B| ; \quad F = f \cos \psi \] (cf. formula (31), §2).

The receiving unit does not indicate \( |U_{\text{ind}}| \) but the output voltage \( U_a \) of the selective receiver. The relation between these two quantities is

(4) \[ U_a = \alpha \cdot V \cdot |U_{\text{ind}}| = \alpha V \omega F \cdot |B| \]

\( \alpha \) is the factor by which the input voltage of the receiver is greater than the voltage induced in the coil of the antenna. The quantity \( \alpha \) and the amplification \( V \) of the receiver depend on the frequency \( \omega \) and are conveniently ascertained by a calibrating measurement.

Fig. 25 shows Eq. (4) logarithmically: Calibration diagrams for the antennas LA IV, V, VI for both 3 and 10 kcps.

The spacing between two parallel straight lines is determined by the quantity \( \alpha \omega LF \) (\( L = \text{self induction of the serial coil}, \ F = \text{area} \)). The angle between each line and the abscissa is 45°.

\( |B| \) is a definite value for each place of reception. If the indicated voltage \( U_a \) is to increase either the amplification \( V \) or the sensitivity of the antenna have to be raised. The increment in \( V \) is limited by the rising background noise and by the instabilities. The sensitivity of the antenna is essentially determined by its area and by its inductance. The product \( F \cdot L \), however, cannot be
increased arbitrarily for the increasing ohmic resistance, the winding capacitances and other losses reduce the Q-factor of the coil. Therefore we have to look for a compromise when designing the antenna.

The dependence of the quality $Q$ on the frequency $\omega (Q = \omega L/R)$ entails the fact that the antenna delivers an optimum signal voltage to the receiver only in a relatively narrow frequency band. For the frequency bands studied the aerial had to be exchanged or switched over each time.

Eq. (4) shows the linear relationship between the magnetic field strength and the voltage measured. As shown in Fig. 25, the calibration curves are shifted parallel according to the frequency, aerial used (or amplification factor $V$). It is therefore enough in evaluating the measurements to give a number of conversion factors that are independent of frequency for each antenna.

To an output voltage $U_a$ of 1 volt correspond

<table>
<thead>
<tr>
<th>3 kcps</th>
<th>10 kcps</th>
</tr>
</thead>
<tbody>
<tr>
<td>EA IV: 2.32</td>
<td>$0.73 \cdot 10^{-12} \text{[Wb/m}^2\text{]}$</td>
</tr>
<tr>
<td>EA V: 6.8</td>
<td>$2.42 \cdot 10^{-12} \text{[Wb/m}^2\text{]}$</td>
</tr>
<tr>
<td>EA VI: 3.25</td>
<td>$2.63 \cdot 10^{-12} \text{[Wb/m}^2\text{]}$</td>
</tr>
</tbody>
</table>

To control and/or correct the described calibration of the receiver the following measurements were made: A certain definite magnetic field could be produced by means of a large single-layer cylindric coil in the direction of its axis. The magnetic induction is
The calibration coil was 390 turns wound on an 18.5-cm long ferrite rod, with an inductance of 145 μH. Its size as compared to that of the cylindric coil is so small that the field in the range of the coil can be regarded uniform. Tuning to resonance was avoided to eliminate the effect of the Q-factor whose dependence on frequency cannot be neglected. The voltage measured on the calibration coil must follow the law of induction and be strictly proportional to the frequency. In our above considerations this was not the case because of the dependences Q(ω) and V(ω).

Block diagram of the measuring arrangement

The calibration values measured are

\[ f = 10 \text{ kcps} \quad U_e = 1 \mu \text{V} \leftrightarrow 5.6 \times 10^{-12} \text{ [Wb/m}^2]\]

\[ f = 3 \text{ kcps} \quad U_e = 1 \mu \text{V} \leftrightarrow 18 \times 10^{-12} \text{ [Wb/m}^2]\]

All the other antennas can also be calibrated by comparing them with this calibration coil. The calibration factors found in this way depart only little from those that have been known before.
§ 4. Experimental work in the mine

Unlike the laboratory measurements, the underground measurements involve considerable difficulties. Even the transport to and from the sites of measurement is rendered difficult by narrow and partly very wet galleries. The measuring equipment must be carefully packed to protect it from moisture and also from hard shocks. In the lower bench (main gallery) it is sometimes possible to travel longer distances on the mine railway. The measuring location, however, usually is in abandoned mine regions for the individual measuring sites should be as far as possible from rails, electrical lines and pneumatic pipelines. Therefore, the whole equipment has to be carried in each reconnaissance. The measuring sites often can be reached only creeping because of narrow tunnels. Such a place is shown in Fig. IX.

But not only electrical lines and iron parts have to be avoided when choosing the measuring site. Dislocations, fissures, and larger cavities as e.g. pits produce unclear conditions. As all the theoretical calculations are based on the assumption of a homogeneous medium only such sections can be used for measurements in which the geological structure is known as thoroughly as possible. An ore-lined mountain range was purposely examined only in a few cases, as for instance in Lafatsch. Despite of all care differences in the measurements occur now and then. Their cause is assumed to be a variable electric conductivity. The
departures of the individual curves from the results of the measurements in the figures that shall be discussed later can be explained by this. The communication between receiver and transmitter, orders to turn the aerials, that are necessary for easy and quick measurements were given through a field telephone. As was proven the cable laid for this purpose has no measurable effect on the receiver. Yet a longer distance which was bridged by light signals was left between the telephone and the receiver.

For every measurement of reception one has to know not only the distance and the magnetic field strength but also the exact orientation of the transmitting and receiving aerials. The departures from the North-South direction were ascertained with compass and map. We could, however, not avoid an angular deflection caused by various effects as e.g. inaccurate maps, magnetic influence on the high-sensitivity geological compass, and insufficient possibilities of adjusting the transmitting and receiving aerials in the terrain. The angle $\beta$ could be set with an accuracy of $\pm 5^\circ$, the angle $\psi$ to $\pm 10^\circ$. The resultant errors have been corrected by least squares calculus.

The improved transmitting and receiving stations entail one difficulty, namely that of finding two sites of measurement in one mine that are at a sufficiently long distance from one another. The longest distances used so far in measurements are about 1200 meters in the Schwaz mine. In the St. Gertraudi and Lafatsch mines it was not possible
to find two sites at a distance greater than 1 km, not even if the geological structure of the rock between them may be completely inhomogeneous. Measurements between the individual mines are planned for the future with the large transmitter that is being constructed.

§ 5. Results of the measurements

The majority of the measurements in the Lafatsch, Schwaz, and St. Gertraudi mines was made to study the dependence of the magnetic field strength on the distance for fixed angles $\phi$ and $\psi$, and also to study the magnetic field strength at a constant distance $r$ as a function of $\phi$ and $\psi$.

Lafatsch mine

The first surveying measurements in this mine have already been described in our last year's report. In 1962, particular attention was paid to the inhomogeneities caused by ore deposits (Pb and Zn). Figs. 26 and 27 show the horizontal and vertical projections of the mine area. The transmitter locations are indicated by $S_1$ and $S_2$. The locations of the receiver for field strength measurements are indicated by the succession of small letters. The first measurement was made on the sixth bed (Fig. 26). The transmitter location $S_1$ lies in dolomite rock. At a distance of 85 m from the transmitter a 20 m thick ore vein lies between the points $m$ and $p$. The ore then abuts on dead limestone.
Measuring table:

**LAFATSCH**

<table>
<thead>
<tr>
<th>transmitter location ( S_2 )</th>
<th>( f = 10 \text{ kcps} )</th>
<th>( f = 3 \text{ kcps} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \text{points/m} )</td>
<td>(</td>
<td>B</td>
</tr>
<tr>
<td>( r )</td>
<td>50</td>
<td>125</td>
</tr>
<tr>
<td>( s )</td>
<td>73</td>
<td>53</td>
</tr>
<tr>
<td>( l )</td>
<td>148</td>
<td>5</td>
</tr>
<tr>
<td>( t )</td>
<td>204</td>
<td>2.35</td>
</tr>
<tr>
<td>( m )</td>
<td>212</td>
<td>2.2</td>
</tr>
<tr>
<td>( q,v )</td>
<td>238</td>
<td>1.6</td>
</tr>
<tr>
<td>( n )</td>
<td>266</td>
<td>1.3</td>
</tr>
<tr>
<td>( p )</td>
<td>285</td>
<td>1.05</td>
</tr>
<tr>
<td>( w )</td>
<td>310</td>
<td>0.89</td>
</tr>
<tr>
<td>( o )</td>
<td>321</td>
<td>0.85</td>
</tr>
<tr>
<td>( x )</td>
<td>373</td>
<td>0.62</td>
</tr>
</tbody>
</table>

The conductivity and the further theoretical conclusions deduced from these values have been discussed in § 8. The experimental curve is shown in Fig. 20. The second measurement which was made in the direction of an ore deposit has an entirely different course. The transmitter location in this case was \( S_1 \). The receiver was then placed in the floors below. In the map on Fig. 26, the individual bottoms are indicated by broken lines. In this measurement, particular attention was paid to the precise orientation of both the transmitting and receiving aerials. These had
to be turned not only horizontally but also vertically. The ore-bearing rock extends at a steep angle from the point $S_1$ in the second course to the region of the points $n - q$ in the sixth course.

Measuring table:

LAFATSCH

$f = 3$ kcps  SA VI  $I = 2a$

transmitter location $S_1$

| points/m | $|B| \left( \frac{\text{Wb}}{m^2} \right) \cdot 10^{-12}$ | points/m | $|B| \left( \frac{\text{Wb}}{m^2} \right) \cdot 10^{-12}$ |
|----------|--------------------------------|----------|--------------------------------|
| a 82     | 77                             | j 332    | 1.4                             |
| b 116    | 28                             | k 374    | 1.0                             |
| c 125    | 20                             | l 398    | 0.8                             |
| d 170    | 7.7                            | m,n 410  | 0.7                             |
| e 186    | 7.7                            | o 412    | 0.7                             |
| f,g 210  | 4.6                            | p 414    | 0.8                             |
| h 230    | 4.1                            | q 445    | 0.55                            |
| i 304    | 3.1                            |          |                                  |

For small values of $r$ these two curves of the first and second measurements depart only slightly from each other. As was discussed already in the theoretical part, conductivity has an effect only at longer distances which in this case is from some 200 m on. The short distances in these measurements in the Lafatsch mine proved to be unfavorable. It was not possible to find more appropriate ranges for measurement.
Schwaz mine

Very suitable galleries were found in particular for the long-distance measurements. As can be seen from the mine chart in Fig. 28, the distance between the points $S_1$ and 4 is approximately 1300 m. To bridge this distance it was necessary to design a new and larger transmitting aerial (SA VII). A frame coil, 3.80 by 4.5 m, was hoisted on a pole and mounted so that it was possible to rotate it through $180^\circ$ (Fig. IV). The area of the aerial is several times as large as that of the frames used so far. The electric resistance could be kept within the limits of a few ohms by using thicker wire. The number of turns is 36 and can always be increased.

The experimental curve in Fig. 18 was obtained with this arrangement.

Measuring table:

<table>
<thead>
<tr>
<th>SCHWAZ</th>
<th>SCHWAZ</th>
</tr>
</thead>
<tbody>
<tr>
<td>$f = 10$ kcps, $I = 2.1$ a &amp; transmitter frame SA VII at $S_1$, $\theta = 0^\circ$, $\psi = 0$</td>
<td>$f = 3$ kcps, $I = 1$ a &amp; $\theta = 0^\circ$, $\psi = 0$</td>
</tr>
<tr>
<td>$m$</td>
<td>$</td>
</tr>
<tr>
<td>30</td>
<td>280</td>
</tr>
<tr>
<td>49</td>
<td>140</td>
</tr>
<tr>
<td>79</td>
<td>31</td>
</tr>
<tr>
<td>110</td>
<td>15</td>
</tr>
<tr>
<td>116</td>
<td>10.5</td>
</tr>
<tr>
<td>146</td>
<td>4.8</td>
</tr>
<tr>
<td>194</td>
<td>2.3</td>
</tr>
<tr>
<td>243</td>
<td>1.15</td>
</tr>
<tr>
<td>293</td>
<td>0.76</td>
</tr>
<tr>
<td>342</td>
<td>0.36</td>
</tr>
<tr>
<td>389</td>
<td>0.25</td>
</tr>
<tr>
<td>435</td>
<td>0.18</td>
</tr>
<tr>
<td>478</td>
<td>0.12</td>
</tr>
</tbody>
</table>
Another section for measurement was between the points $S_2$ and $S$. On the one hand the large cavities at 5 could be avoided, but on the other there is different rock (a slate wedge) in between. Yet the course of the curve as shown in Fig. 18 is approximately the same.

**Measuring table**

<table>
<thead>
<tr>
<th>SCHWAZ transmitter frame at $S_2$</th>
<th>SCHWAZ</th>
</tr>
</thead>
<tbody>
<tr>
<td>$f = 3$ kcps, $I = 1.75 , a$</td>
<td>$f = 3$ kcps, $I = 3 , a$</td>
</tr>
<tr>
<td>$\theta = 0$, $\psi = 0$</td>
<td>$\theta = 0$, $\psi = 0$</td>
</tr>
</tbody>
</table>

| points/m | $|B| \left(\frac{Wb}{m^2}\right) \times 10^{-12}$ | m   | $|B| \left(\frac{Wb}{m^2}\right) \times 10^{-12}$ |
|----------|-----------------------------------------------|-----|-----------------------------------------------|
| 5        | 580                                           | 30  | 300                                           |
| 6        | 760                                           | 49  | 180                                           |
| 7        | 870                                           | 79  | 40                                            |
| 8        | 1040                                          | 110 | 20                                            |
|          |                                               | 116 | 17                                            |
|          |                                               | 146 | 7.8                                           |
|          |                                               | 194 | 3.2                                           |
|          |                                               | 243 | 2.4                                           |
|          |                                               | 293 | 1.3                                           |
|          |                                               | 342 | 0.8                                           |
|          |                                               | 389 | 0.6                                           |
|          |                                               | 435 | 0.45                                          |
|          |                                               | 478 | 0.3                                           |

Besides these measurements also the dependence $H(\theta, \psi)$ was studied as mentioned before. These programs were performed
as follows:

The transmitting aerial (point $S_1$) was directed so that $\theta = 0$. At a distance $r$ the receiving aerial was slowly rotated and the voltages pertaining to $\psi$: $0^\circ$, $30^\circ$, $60^\circ$, ... were read. After one full revolution of the receiving aerial through $360^\circ$, the same measurement was repeated for $\theta = 30^\circ$. The resultant graphs are given in Figs. 4, 5, 6. The $\theta$ values are at the periphery, the point with the greatest radius vector on each curve pertains to $\psi = 0^\circ$. By measuring the field strength at $\theta = 0^\circ$ and $\theta = 90^\circ$ we could also ascertain the ratio $\frac{|H_r|}{H_\theta}$ from which we could draw conclusions on the conductivity. Such measurements were made in a large number of galleries. The considerable stray indicates that large differences in conductivity may occur also in highly uniform rock.

St. Gertraudi mine (mine chart Fig. 29):

The Schwaz measurements were repeated. The transmitting aerial was a frame of the same kind as that used in Schwaz. Its location is indicated by $S$. The section of measurement goes to the points $a$, $b$, $c$. Two series of measurements are evaluated in Fig. 19. The one was made with the transmitting aerial directed to the most distant, the other with the transmitting aerial directed to the nearest site of measurement. In this way the angle $\theta$ varies from one site of measurement to the other whereas $\psi = 0^\circ$ is conserved.
### Measuring table:

**ST. GERTRAUDI**

\( f = 10 \text{ kcps}, \overline{2} \text{ III}, I = 2.2 \text{ a} \quad \phi = 0^\circ \quad \psi = 0^\circ \)

| \( \mathbf{m} \) | \( |\mathbf{B}| \left( \frac{\mu \text{B}}{\text{m}^2} \right) \cdot 10^{-12} \) |
|-----------------|----------------------------------|
| 28              | 380                              |
| 48              | 71                               |
| 71              | 22                               |
| 94              | 11.8                             |
| 119             | 6                                |
| 142             | 4.1                              |
| 167             | 2.65                             |
| 191             | 2                                |
| 216             | 1.5                              |
| 240             | 1.3                              |
| 264             | 0.9                              |
| 288             | 0.74                             |
| 313             | 0.58                             |
| 337             | 0.45                             |
| 362             | 0.33                             |

**series I \( f = 3 \text{ kcps} \)**

**St. Gertraudi**

large transmitter frame at \( S \)

\( f = 3 \text{ kcps}, I = 1.75 \text{ a} \)

| \( \mathbf{m} \) | \( \phi \) | \( |\mathbf{B}| \left( \frac{\mu \text{B}}{\text{m}^2} \right) \cdot 10^{-12} \) |
|-----------------|----------|----------------------------------|
| 110             | 30º      | 100                              |
| 150             | 18º      | 41                               |
| 200             | 11º      | 20                               |
| 240             | 7.5º     | 11.5                             |
| 290             | 5.5º     | 6.3                              |
| 340             | 4º       | 4                                |
| 390             | 3º       | 3                                |
| 440             | 2º       | 1.6                              |
| 490             | 1º       | 1.5                              |
| 540             | 0.5º     | 1.3                              |
| 590             | 0º       | 1                                |
| 640             | -0.5º    | 0.75                             |
| 690             | -0.5º    | 0.6                              |
| 740             | -0.5º    | 0.5                              |
| 820             | -0.5º    | 0.3                              |
| 70              | 0º       | 220                              |
| 150             | 27º      | 49                               |
| 240             | 37º      | 10                               |
| 340             | 41º      | 3.8                              |
| 490             | 44º      | 1.2                              |
| 640             | 45º      | 0.75                             |
| 820             | 45º      | 0.3                              |
The curves for the field strengths shown so far have been plotted for a frequency of 3 kcps. Fig. 21 shows one curve each taken in the three mines at a frequency of 10 kcps. The distances in these measurements were not greater than 400 m as smaller aerials were employed. Moreover, it was found that at frequencies of around 10 kcps particularly strong interferences occur with the measurements which at low frequencies make it impossible to perform precise measurements.

§ 6. Reception tests with commercial very-long-wave transmitters in the mine

As stated in several intermediate reports quite a number of very-long-wave stations in the range of frequencies around 15 kcps could be received very clearly in the mine. During the first time the arrangement described in § 3 was used as a receiver. However, it was suited only for preliminary probing measurements. First, we tried out which stations could be heard at all. Reception was very good from the GBR station, followed by FUB and others that were somewhat weaker (NAA, EB, UMS, NIT). The stations NAA and GBR could be heard both night and day whereas a number of other stations could be received only in the evening or during the night.

To get this result we had to listen to the frequency band between 10 and 20 kcps for 24 hours.
Fig. 24
According to the measuring site in the mine, the receiving aerials were either the ferrite aerials described before or large frame aerials constructed for particularly this purpose. One of these is in Schwaz (Fig. 28) at the point 10, the height of rock above this place is some 1000 m. The frame has the size 5 by 20 m and has two turns. It is either connected aperiodically to the receiver or tuned to the receiving frequency.

A second, larger frame is in the Kleinkogel range in St. Gertraudi. A vertical loop of 100 by 40 m was set up there. Using the two shafts a and b (Fig. 29) and the tunnels f which connect them on top and below it was possible to set up such a large antenna. The latter is a two-turn loop also in this case. A second 40 m long aerial was set up vertically in St. Gertraudi and used for receiving purposes. A low-background nuvistor amplifier was designed to reduce the damping of the ferrite aerial and of the large loop aerial. Its wiring diagram is shown in Fig. 32. It is a two-stage battery apparatus. Its smoothly adaptable feedback is adjustable with the potentiometer P.

First of all we had to check what relationship there is between reception in the mine and surface reception. Comparative measurements showed that the signals on the surface were somewhat stronger but that the noise level was a multiple of the useful signal level. This can be explained largely by the fact that these measurements were made in summer when owing to the atmospheric electricity the noise
level is much higher than in winter. Moreover, the bandwidth of the amplifier used by us is relatively great. It amounts to some 5%, so that also disturbing pulses of more distant frequencies had an effect. Repeating the measurements under the surface we found that the signals from the transmitter were attenuated but slightly. More than 1 km of rock reduced the signal intensity by about 60%. The attenuation of the atmospherics was considerably greater.

The next step was to prepare the long-term registration of the GBR or NAA stations. It was intended to follow the variation of the field strength above and under the surface over a long period. For this purpose we first had to find a suitable receiver station. A receiver, an integrating circuit, and a recording unit were necessary. Fig. VIII shows the mains-fed device during a test run in the St. Gertraudi mine. The EA IV receiving aerial was used. The receiver can be seen in the middle of the picture. This apparatus is a very-long-wave receiver for the frequency range of 4 - 150 kcps manufactured by the Siemens company and completely modified in our laboratory. Its sensitivity is about 10 μV, its bandwidth is very low so that also transmitters that are close to one another can be separated.

The circuit diagram of the receiver is shown in Fig. 33: On the left side is the two-stage voltage amplifier (ECC 83), adjoining the ring modulator (Q1) with the oscillator (ECC 82), followed by the two-stage selective output amplifier (ECP 80). The 1-kcps output signal can either be heard
MEASURING AMPLIFIER AND INTEGRATOR

AMPLIFIER DRIVING CODE RECORDER

ANTENNA PREAMPLIFIER
R₁ = R₂ = NUVISTORS 7560
through earphones or be fed into an integrating stage (Gl 3, Gl 4) whose rise and integration times are adjustable. The symmetric output stage (ECC 82) controls a slow graphical recorder via the terminals of output II. Another output over TR 5 and the rectifier bridge GI 2 serves for the control of a rapid recorder (output I). As the stations in question usually transmit morse signals, the problem of recording their field strength is much more difficult than it may seem at first. It has not yet been solved to satisfaction. Work in this respect is being carried on. Besides the slow recorder we used also a rapid recorder whose registrations were very valuable. Short noise peaks could be recorded accurately by means of it. The recorder can be seen in the top right-hand corner of Fig. VII; below is the required amplification unit. Another means for the identification of unknown transmitters was a Morse printer which made it possible to record the received code signals on a paper tape. In this way one can evaluate the signals later without having to listen all the time. The electronic control of this recorder can be seen in Fig. 31. A battery-supplied recording station was set up parallel to the apparatus described. This was necessary to be sure no electromagnetic waves are led through the power mains into the inner mine. Long-term measurements could be made at the deepest spots of the mine by means of this apparatus. It was found then that the supposition made before was wrong. Fig. VII shows this apparatus during an informative measurement in the St. Gertraudi mine. The receiver (left in the picture) was
not yet finished at that time. The recorder is provided with a clockwork. The integrator and the measuring amplifier for the recorder are installed separately. Fig. 30 shows its wiring diagram. A d.c.-amplifier was necessary for the sensitivity of the recorder available was too low to connect it directly to the integrating unit. The picture shows also several auxiliary equipment, as the battery-supplied oscilloscope, a millivoltmeter, and the required power sources. The receiving aerial on its stand is not very clear to see. This aerial is the EA I which has been described before. As mentioned before these measurements are still in their state of beginning. A new highly selective amplifier will soon be put into operation. The results obtained so far must be regarded preliminary. Up to now we cannot draw any definite conclusions as to the mechanism of propagation of electromagnetic waves from the transmitter to the receiver. Such measurements are being prepared.

§ 7. On the determination of \( \varepsilon \) and \( \sigma \)

In the year under review we have worked to design a suitable apparatus for measuring \( \varepsilon \) and \( \sigma \). Results on preliminary probing measurements of \( \varepsilon \) have been given in our last report. When it is possible to prepare the rock samples in a proper way, i.e. to saw them in pieces, to grind them, and to bring them into contact, these measurements should not be too difficult. The thin (2 - 5 mm) plan
parallel section consumes much time and still gives a large percentage of reject. Things are much more difficult in determining the loss factor, i.e. in measuring the conductivity of the rock in the entire VLF region. The kind of measuring electrodes abutting the rock sample plays such an important part that sufficiently accurate and reproducible measurements have not been possible up to now. The measuring arrangement used is shown in Fig. X. It consists of an RC generator which produced the measuring voltage of the desired frequency, of the measuring bridge, and of the selective thermionic voltmeter which is used as a zero indicator. The rock sample is let in the picture. 4 cm deep holes were drilled into the rock (here it is a dolomite sample from St. Gertraudi) at certain spacings. Contact tests were made with mercury, slightly acid cotton or aluminum foil pressed into the hole. Subsequently, the resistance is determined as a function of the spacing between the individual measuring electrodes. The accuracy of the measuring bridge in this measurement is several times greater than the errors caused by insufficient contacts. Good results were obtained when metal powder was used as a contact in the borehole.

Further work in this field shall enable us above all to determine the conductivity of an arbitrary section of rock in the mine and thus to gain insight into the natural conditions. However, the relevant theoretical problems have not yet been solved. They would make it possible to
find the conductivity of an extensive spatial conductor by measuring its electrical resistance. This work is regarded particularly important since it would offer a control for the determination of conductivity by measuring the attenuation of an electromagnetic wave.
Figures:

Fig. I  Transmitter station, RC generator, power amplifier, electronic switch, accumulator

Fig. II  flexible transmitting aerial SA VI with transmitter (Hall salt mine)

Fig. III  receiving unit: ferrite aerial EA IV, receiver, millivoltmeter, audio amplifier

Fig. IV  large rotary frame aerial SA VII and transmitter (Schwaz mine)

Fig. V  small receiver station with aerial EA V

Fig. VI  measuring team with receiver (Hall salt mine)

Fig. VII  battery-operated apparatus for recording field strength (St. Gertraudi mine)

Fig. VIII  mains-fed apparatus for recording field strength and noise level

Fig. IX  transport of receiver unit in an abandoned mine region

Fig. X  laboratory for geoelectrical measurements on rock samples

List of coworkers

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